The **fixed-point** iterative process and associated error are (where $\rho(\mathbf{P})$ is the spectral radius of \mathbf{P} .):

$$\begin{split} \vec{x}^{(0)} = \text{ arbitrary }; & \quad \vec{x}^{(k+1)} = \mathbf{P} \vec{x}^{(k)} + \tilde{\vec{b}} \end{split}$$

$$\vec{e}^{(k+1)} = \mathbf{P} \vec{e}^{(k)} \; ; & \quad ||\vec{e}^{(k+1)}|| \leq ||\mathbf{P}^{k+1}|| \, ||\vec{e}^{(0)}|| \; ; & \quad ||\mathbf{P}^{k}|| \approx \rho^k(\mathbf{P}) \end{split}$$

To reduce error by a factor of ϵ , it takes $k \approx \frac{\log(\epsilon)}{\log(\rho(\mathbf{P}))}$ iterations.

Richardson	Jacobi
$(\mathbf{I} - \omega^{(k)} \mathbf{A}) \vec{x}^{(k)} + \omega^{(k)} \vec{b}$	$\mathbf{D}^{-1}(\mathbf{D} - \mathbf{A})\vec{x}^{(k)} + \mathbf{D}^{-1}\vec{b}$
GS	SOR
$\mathbf{(D+L)^{-1}} \left[-\mathbf{U}\vec{x}^{(k)} + \vec{b} \right]$	$(\mathbf{D} + \omega \mathbf{L})^{-1} \Big([(1 - \omega)\mathbf{D} - \omega \mathbf{U}] \vec{x}^{(k)} + \omega \vec{b} \Big)$

Table 1: $\vec{x}^{(k+1)}$ for several iterative methods

condition number of a matrix \mathbf{A} is defined as $\kappa(\mathbf{A}) = ||\mathbf{A}|| \, ||\mathbf{A}^{-1}||$. If the 2-norm is used, then $||\mathbf{A}||_2 = \sigma_1$, $||\mathbf{A}^{-1}||_2 = 1/\sigma_m$, and $\kappa_2(\mathbf{A}) = \sigma_1/\sigma_m$; σ_m is the mth singular value of \mathbf{A} .

Let G be a non-singular **preconditioner**, then $A\vec{x} = \vec{b}$ can be transformed as $G^{-1}Ax = G^{-1}b$.

Finite Difference for the DE in <u>1D</u> we use central difference for the derivative:

$$-\phi_{i-1} + \left(2 + \frac{h^2}{L^2}\right)\phi_i - \phi_{i+1} = h^2 \frac{S_{0,i}}{D} \qquad i = 1, 2, \dots, n-1 \qquad L \equiv \sqrt{\frac{D}{\Sigma_a}}$$

In 2D we use a 5-point stencil and use central in each dimension for the derivative, giving

$$\nabla^2 \phi_{i,j} = \frac{\phi_{i+1,j} + \phi_{i-1,j} + \phi_{i,j+1} + \phi_{i,j-1} - 4\phi_{i,j}}{h^2}$$

Finite Volume for the DE in 1D uses this grid

The physics values are defined in each cell (cell-centered) and the flux and source are defined at the mesh points (edge-centered.

We integrate the DE in each cell from $x_{i-1/2}$ to $x_{i+1/2}$. At the boundaries we apply the BCs as appropriate to get the i=0 and i=n equations.

The <u>2D</u> version uses a 2D stencil (not needed for exam). The physics values are again defined in each cell (cell-centered) and the flux and source are defined at the mesh points (edge-centered.

We again integrate over the partial cell, which is now in two dimensions: $x_{i-1/2}$ to $x_{i+1/2}$ and $y_{j-1/2}$ to $y_{j+1/2}$.

We use Gauss Theorem for the streaming term: $-\int_V d\vec{r} \left[\nabla \cdot \left(D(\vec{r}) \nabla \phi(\vec{r}) \right) \right] = \int_S d\vec{S} \, D(\vec{r}) \frac{\partial}{\partial \hat{n}} \phi(\vec{r}).$

Critical/eigenvalue equations have the addition of k, allowing us to adjust the equation such that the rhs of the DE becomes $\frac{1}{k}\nu\Sigma_f(x)\phi(x)$.

This means the rhs of our FD or FVM matrix formulation contains flux instead of only a fixed source.

$$A = -\frac{d}{dx}D(x)\frac{d}{dx} + \Sigma_a(x) \qquad F = \nu\Sigma_f(x) \qquad k = \frac{\text{total production rate}}{\text{total loss rate}}$$

$$\mathbf{A}\vec{\phi}^{(m+1)} = \frac{1}{k^{(m)}}\mathbf{F}\vec{\phi}^{(m)} \qquad k^{(m+1)} = \frac{\int_0^{\tilde{a}}F\vec{\phi}^{(m+1)}(x)dx}{\frac{1}{k^{(m)}}\int_0^{\tilde{a}}F\vec{\phi}^{(m)}(x)dx}$$

We also add an eigenvalue solver method, like Power Iteration. This uses the idea that $\vec{v}_0 = \gamma_1 \vec{x}_1 + \gamma_2 \vec{x}_2 + \dots + \gamma_n \vec{x}_n$, where \vec{x}_j is the jth eigenvector and γ_j is some constant.

Delayed neutrons let us deal with time variation. β fraction of the total neutrons released from fission are delayed. We use $\rho = \text{reactivity} = \frac{k-1}{k}$, and l is mean neutron lifetime.

$$\begin{split} n(t) &= n_0 e^{\frac{(k-1)t}{l}} \; ; \qquad T = \text{reactor period} = \frac{l}{k-1} \\ \phi(r,t) &= vn(t)\psi_1(r) \; ; \qquad \hat{C}_i(r,t) = C_i(t)\psi_1(r) \\ \text{where } \psi_1 \text{ is the fundamental mode solution of } \nabla^2 \psi_n + B_g^2 \psi_n = 0 \end{split}$$

PRKE

$$\frac{dn(t)}{dt} = \frac{\rho(t) - \beta}{\Lambda} n(t) + \sum_{i=1}^{6} \lambda_i C_i(t) ; \qquad \frac{dC_i(t)}{dt} = \frac{\beta_i}{\Lambda} n(t) - \lambda_i C_i(t)$$

 $C_i(t)$ = delayed neutron concentration from ith precursor; Λ = effective n lifetime = $(v\nu\Sigma_F)^{-1}$.

Runge Kutta methods use stages to avoid higher order derivates to get better accuracy. Two stage:

$$U^{n+1/2} = U^n + \frac{1}{2}kf(U^n) \qquad U^{n+1} = U^n + kf(U^{n+1/2}) \qquad U^{n+1} = U^n + kf(U^n + \frac{1}{2}kf(U^n))$$

Monte Carlo uses random numbers, sampling rules, tallies, and statistics

$$\mu = E(x) = \int x f(x) dx \; ; \qquad \bar{x} = \frac{1}{N} \sum_{i=1}^{N} x_i \quad \lim_{N \to \infty} \bar{x} \to \mu$$
$$\sigma^2 = E(x^2) - \mu^2 \; ; \qquad S_x^2 \approx \bar{x^2} - \bar{x}^2 \; ; \qquad S_{\bar{x}}^2 = \frac{S_x^2}{N}$$

$$p\{a \le x \le b\} = \int_{a}^{b} p(x)dx; \qquad p(x) \ge 0; \qquad \int_{-\infty}^{\infty} p(x)dx = 1$$

$$p(x = x_{k}) = p_{k} \equiv p(x_{k}), k = 1, \dots, N; \qquad p_{k} \ge 0; \qquad \sum_{k=1}^{N} p_{k} = 1$$

$$P\{x' \le x\} = P(x) = \int_{-\infty}^{x} p(x')dx'; \qquad P(-\infty) = 0, \quad P(\infty) = 1$$

$$P\{x' \le x\} = P_{k} \equiv P(x_{k}) = \sum_{j=1}^{k} p_{j}, k = 1, \dots, N; \qquad P_{0} = 0, \quad P_{N} = 1$$

Deal with <u>normalization</u> using $p(x) = \frac{g(x)}{G(\infty)}$, where p(x) is the numerical PDF, g(x) is the physical PDF, and G(x) is the physical CDF.

With rejection sampling, create $g(x) \ge p(x)$ for all x; Generate pair of random variables, (ξ, η) ; $x' = G^{-1}(\xi)$; If $\eta < p(x')/g(x')$, accept x'; Else, reject x'.

Probability of distance to collision

$$p_c(s) = \Sigma_t(s)e^{-\Sigma_t(s)s}ds$$

$$P_c(n) = \int_0^s \Sigma_t(s)e^{-\Sigma_t(s)s'}ds' = -e^{-\Sigma_t(s)s'}|_0^s = 1 - e^{-\Sigma_t(s)s}$$

After a collision, which nuclide from $p_i = \frac{\Sigma_{t,j}}{\Sigma_t}$ and which reaction from $p_x = \frac{\Sigma_{x,j}}{\Sigma_{t,i}}$.

In scattering, the new direction is $\left(\sin(\phi)\cos(\theta),\sin(\phi)\sin(\theta),\cos(\theta)\right) = \left(\sqrt{1-\mu^2}\cos(\theta),\sqrt{1-\mu^2}\sin(\theta),\mu\right)$.