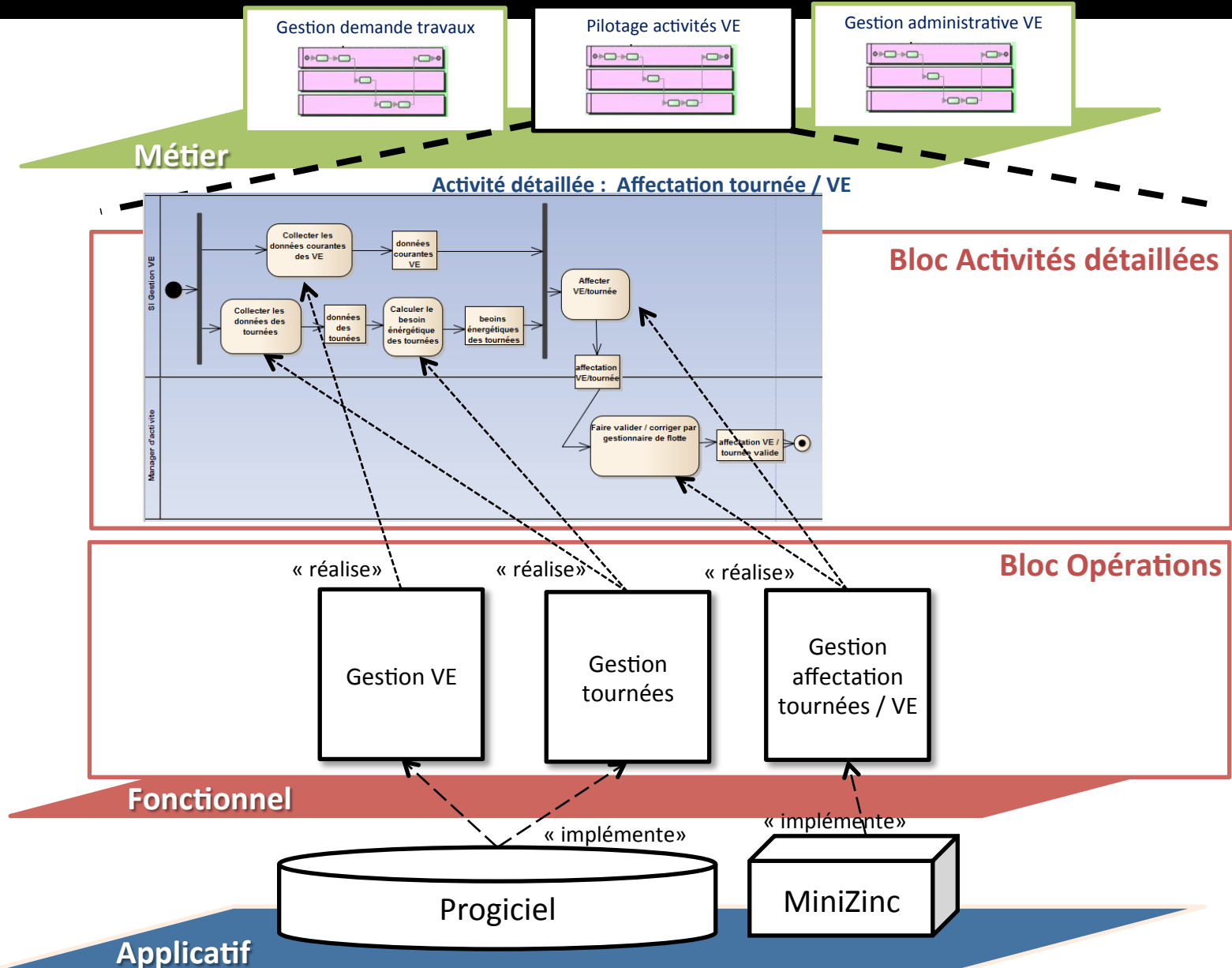
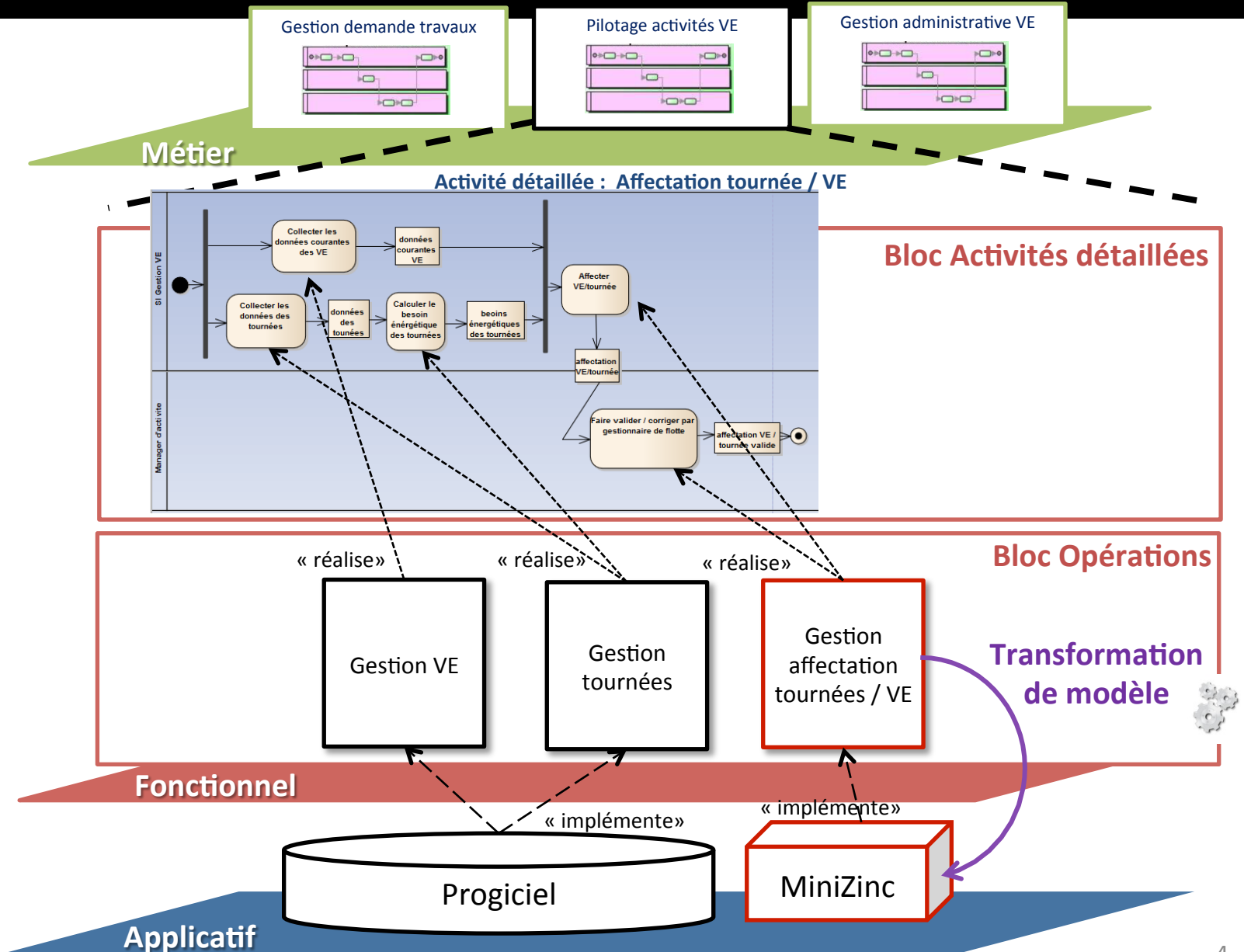


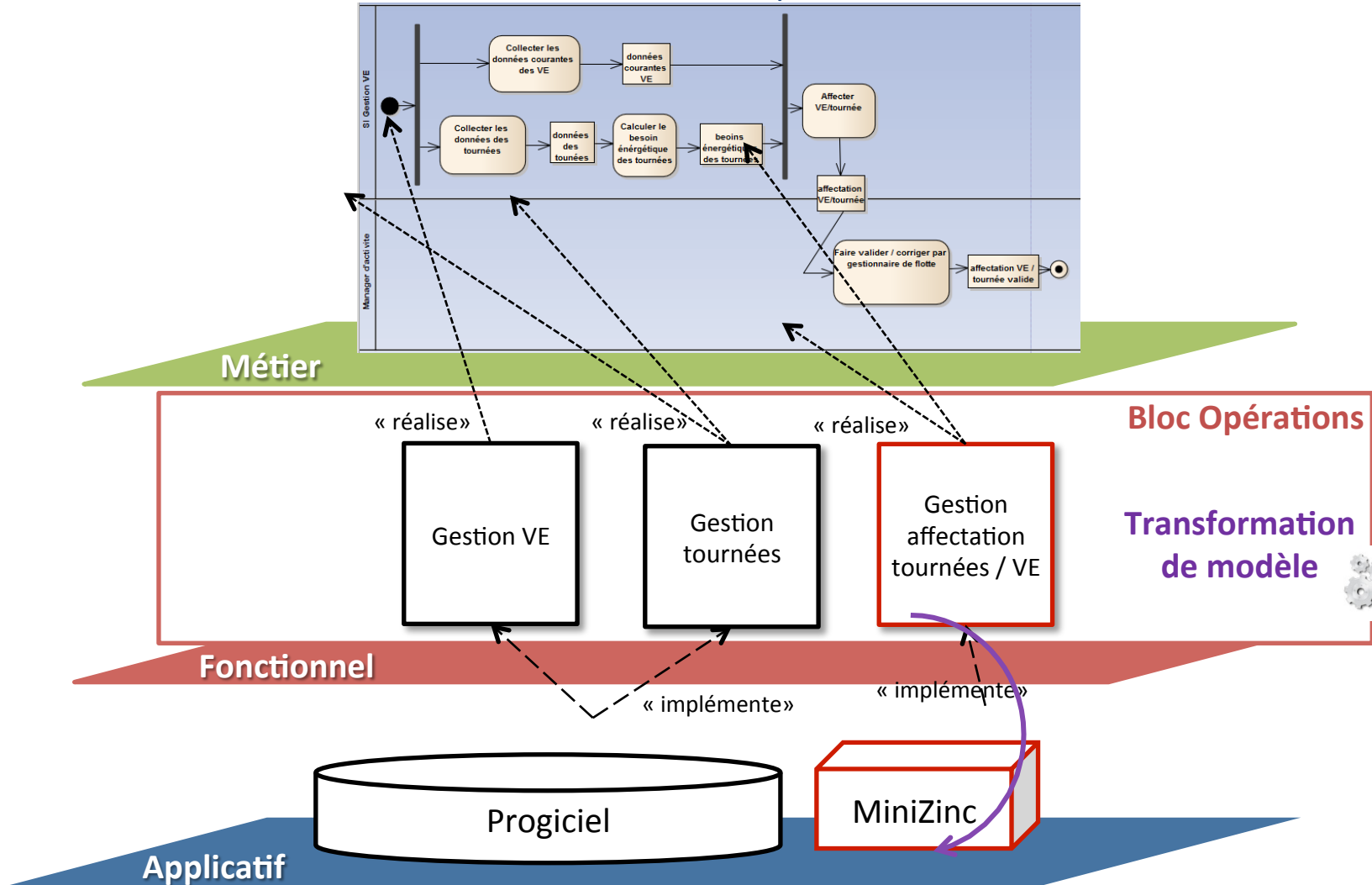
Mise en œuvre pour le cas métier



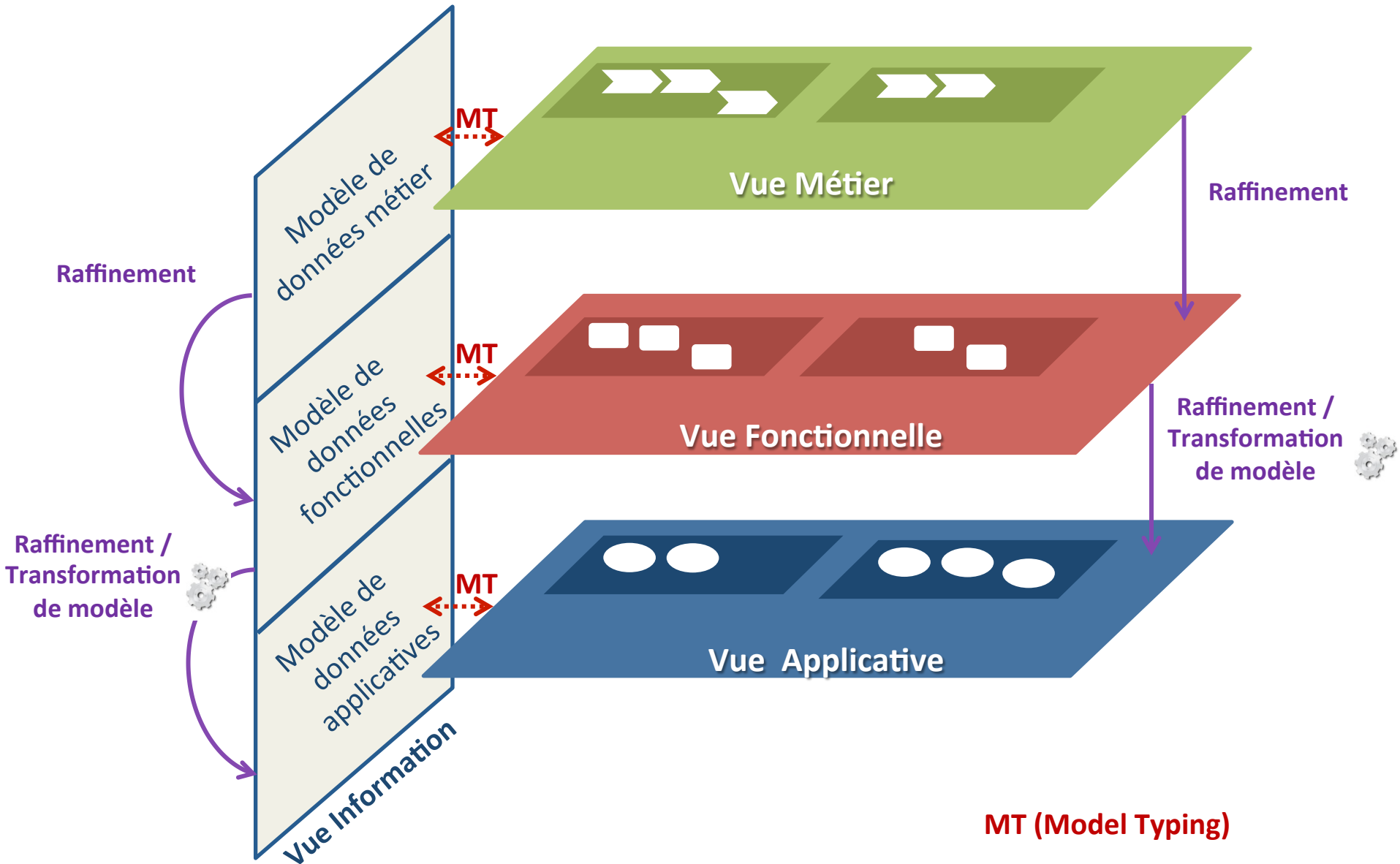
Mise en œuvre pour le cas métier



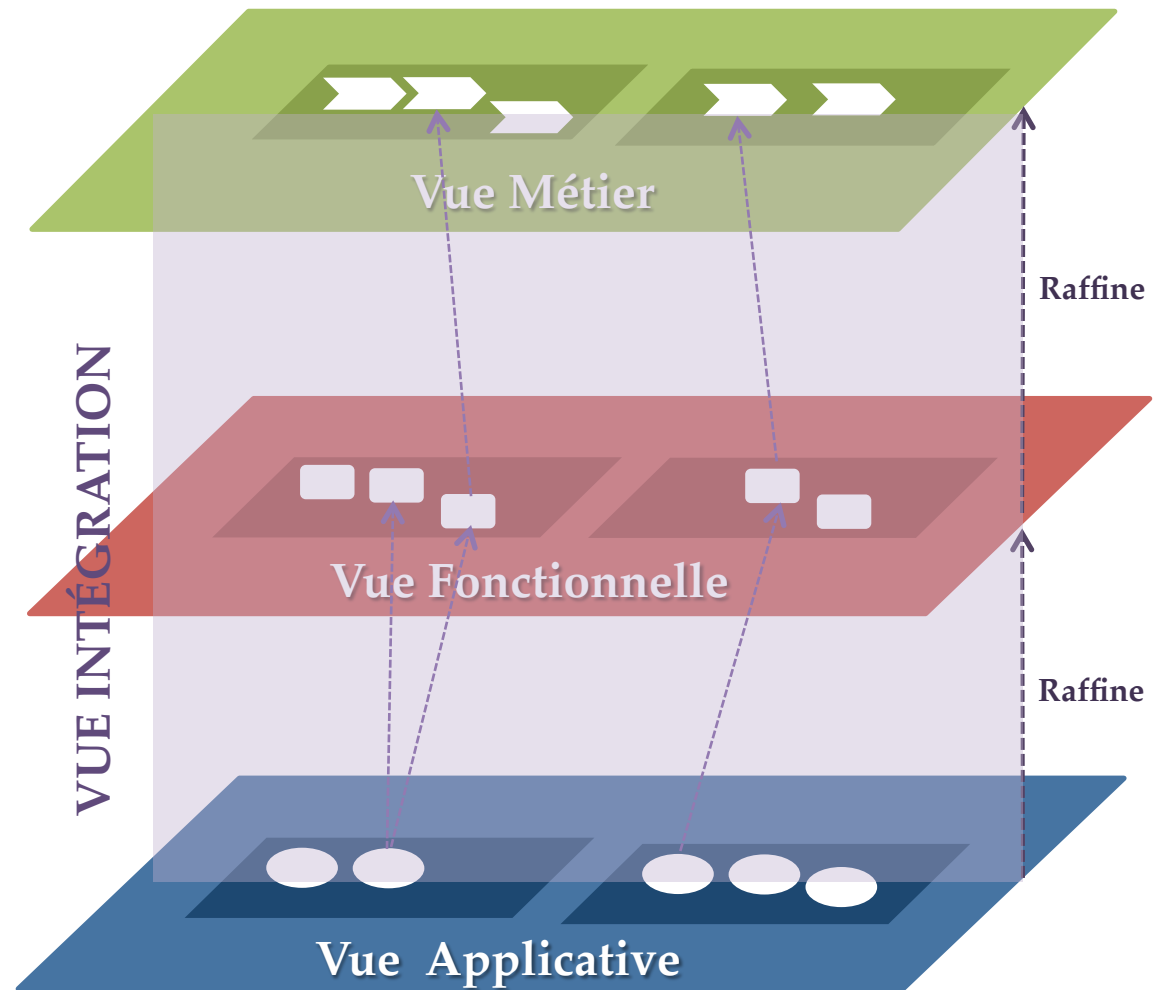
Activité détaillée : Affectation tournée / VE



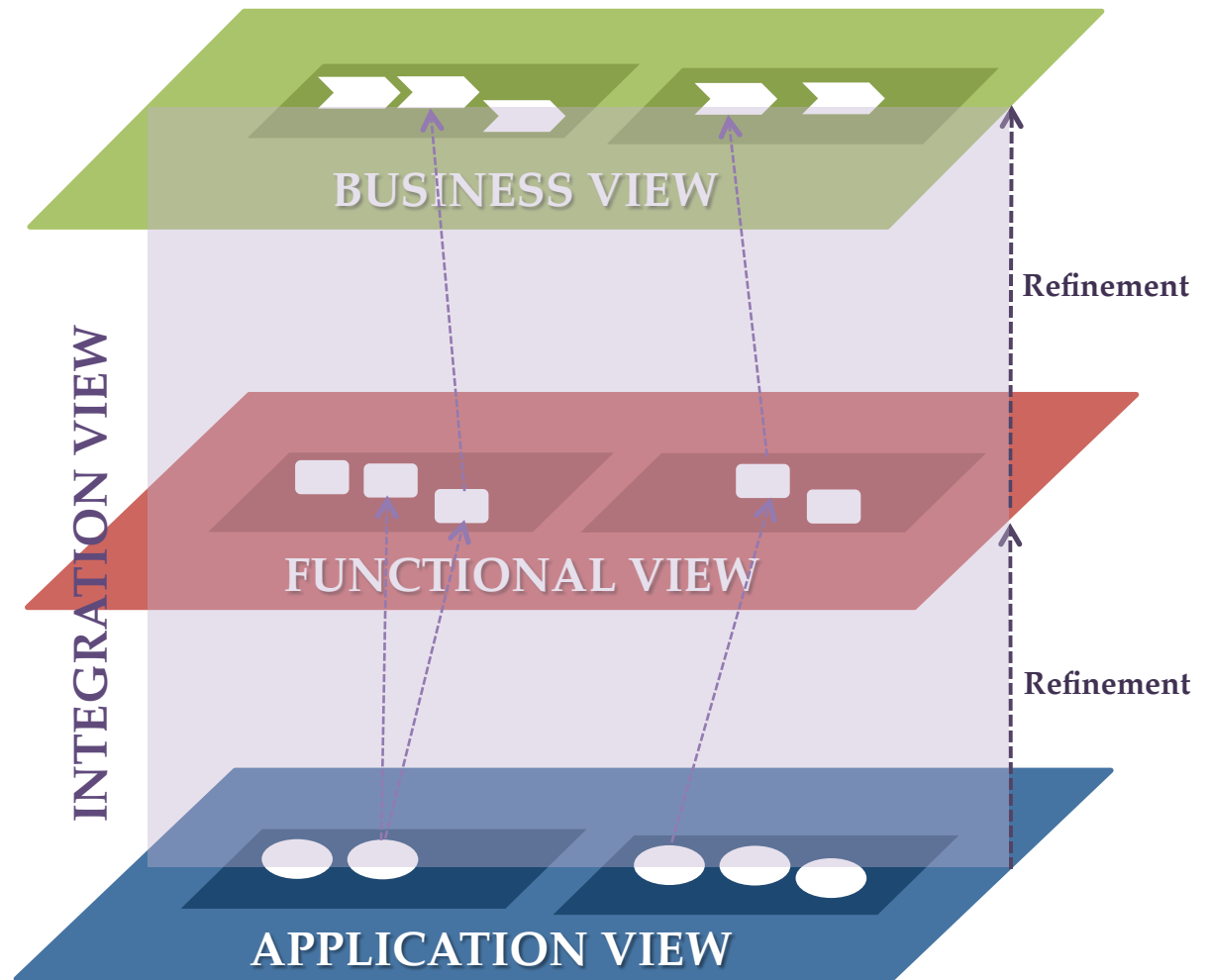
Démarche



Démarche



Démarche



Vue fonctionnelle

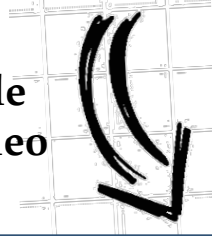
Gestion affectation

```
context Tournee
inv:    self.VE.autonomie * self.VE.niveauBatterie > self.distanceParcourue

context Tournee
inv:    self.VE <> undefined xor self.VT <> undefined

context Tournee::kmElec(): int
body:   (Tournee::allInstances()->collect(t.VE <> undefined |t.distanceParcourue))->sum()
```

Transformation de
modèle avec Acceleo



Vue applicative

MiniZinc

```
constraint forall (i in Tournees) (
%affectation de vehicule electrique si l autonomie l autorise
constraint forall(i in Tournees, j in VehiculesElec)
(tourneeVehicule[i]= identifiantVE[j] -> (autonomie[j]*niveauBatterie[j] > distanceTournee[i] /\
kmElec[i]=distanceTournee[i]));

% affectation d un vehicule thermique et dans ce cas kmElec est nul
constraint forall(i in Tournees, k in VehiculesTherm)
(tourneeVehicule[i]= identifiantVT[k] -> kmElec[i]=0);

%maximiser le nombre de km de tounrnee fait par les vehicules electriques
solve maximize sum(i in Tournees) (kmElec[i]);
```

Functional view

Allocation function

```
context Tour
inv : self.EV.autonomy * self.EV.batteryLevel > self.neededEnergy

context Tour
inv : self.EV <> undefined xor self.CV <> undefined

context Tour :: elecKm() : int
body : (Tours::allInstances() -> collect(t.EV <> undefined | t.distance)) ->
sum()
```

Model transformation with Acceleo



Application view

MiniZinc Module

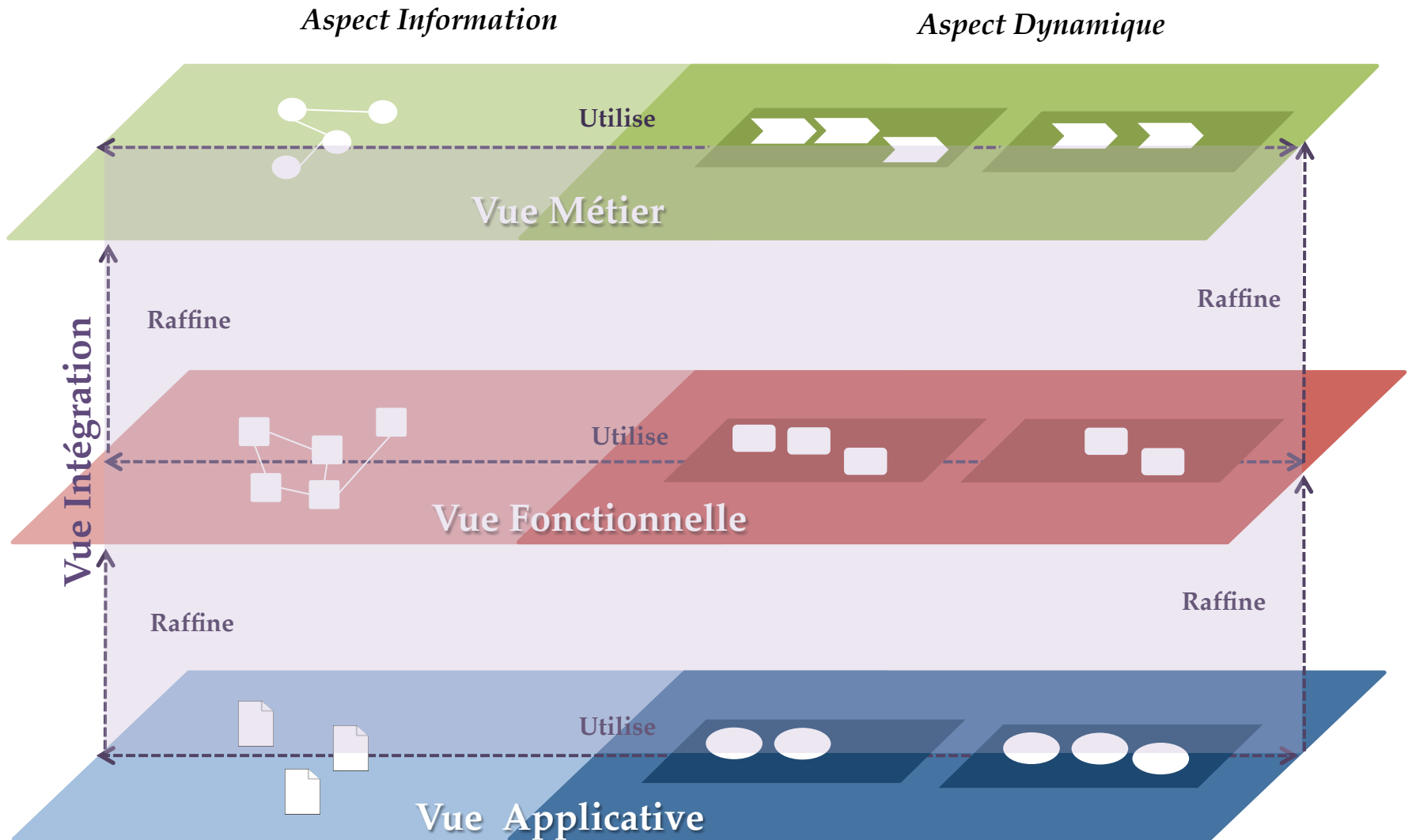
```
%a vehicle is affected to only one tour
constraint alldifferent(allocation);

%allocate an electric vehicle if the autonomy permits it
constraint forall(i in Tours, j in ElectricVehicles)
(allocation[i]= id_EV[j] -> (autonomy[j] > neededEnergy_Tours[i]
/\ kmElec[i]= distance_Tours[i]));

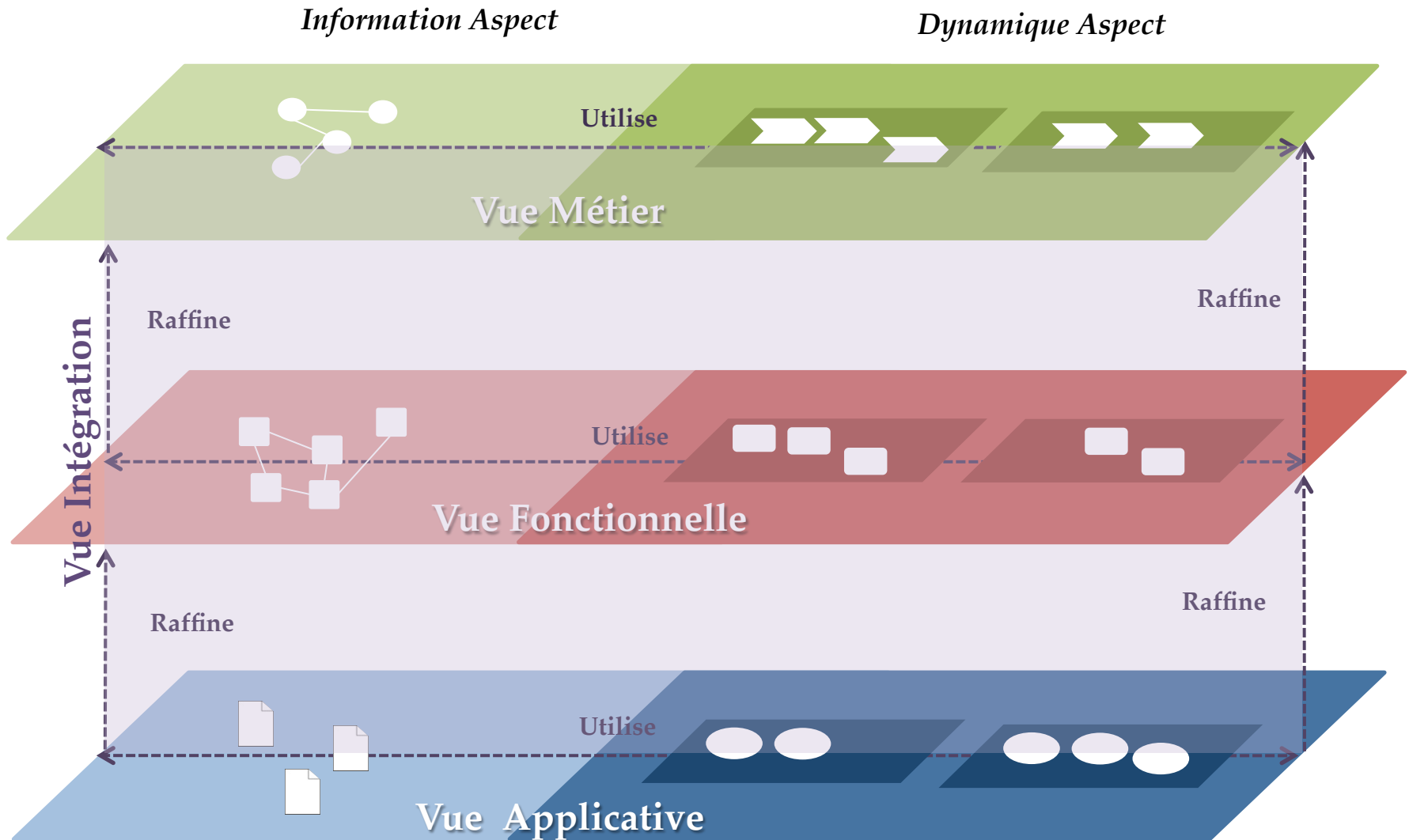
% allocate a combustion vehicle
constraint forall(i in Tours, k in CombustionVehicles)
(allocation[i]= id_CV[k] -> kmElec[i]=0);

%maximize km done by electric vehicles
solve maximize sum(i in Tours)(kmElec[i]);'
```

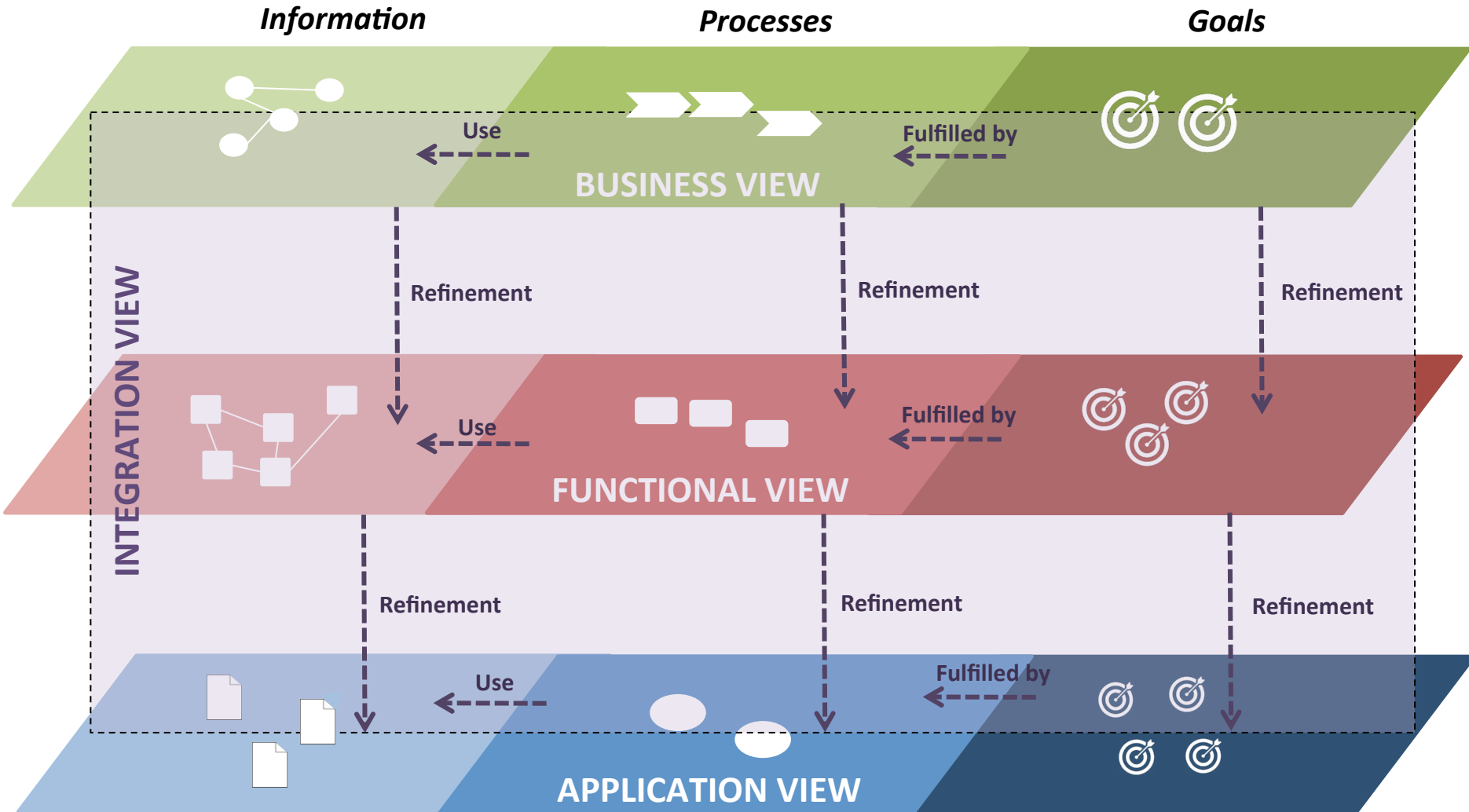
Démarche



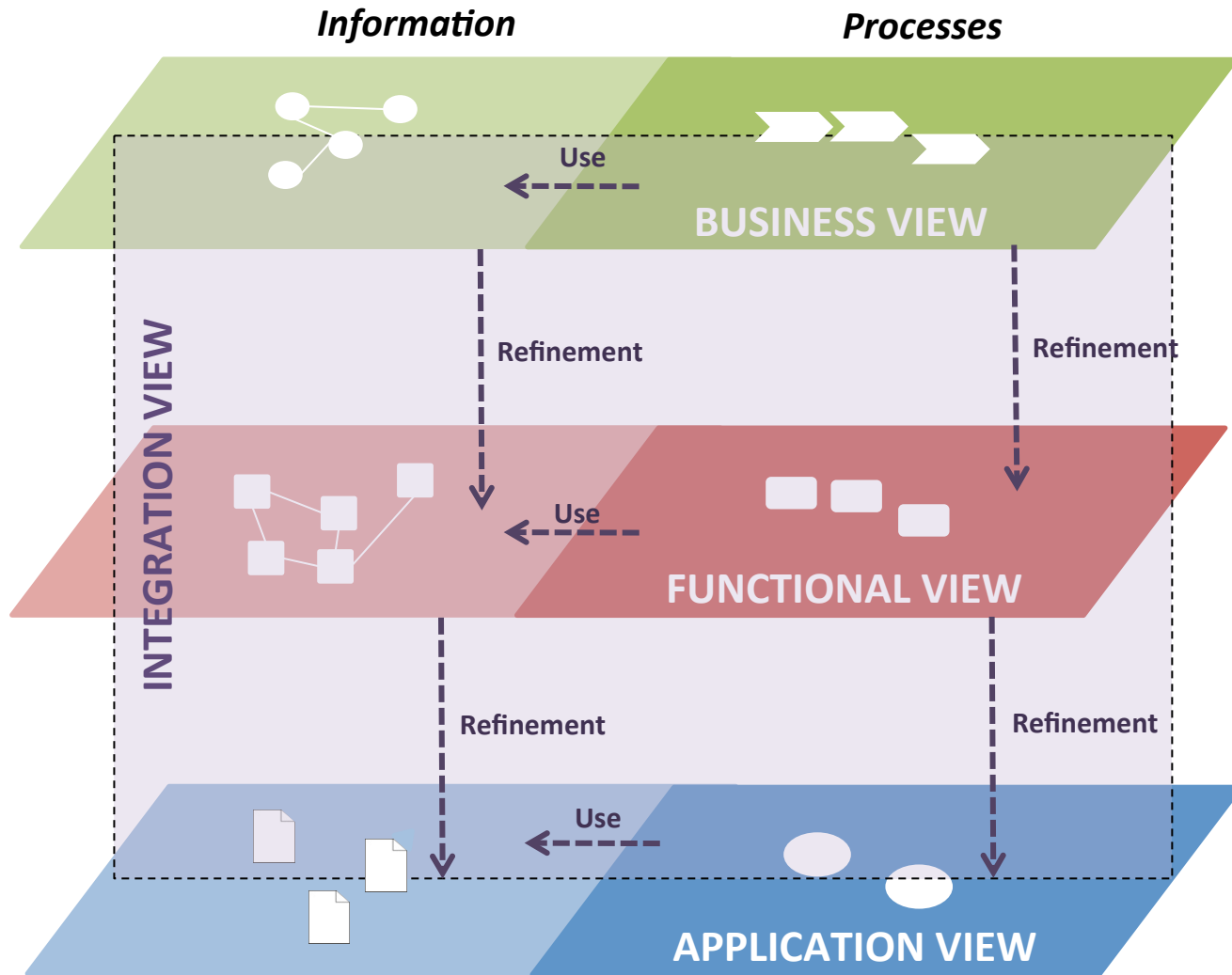
Approach

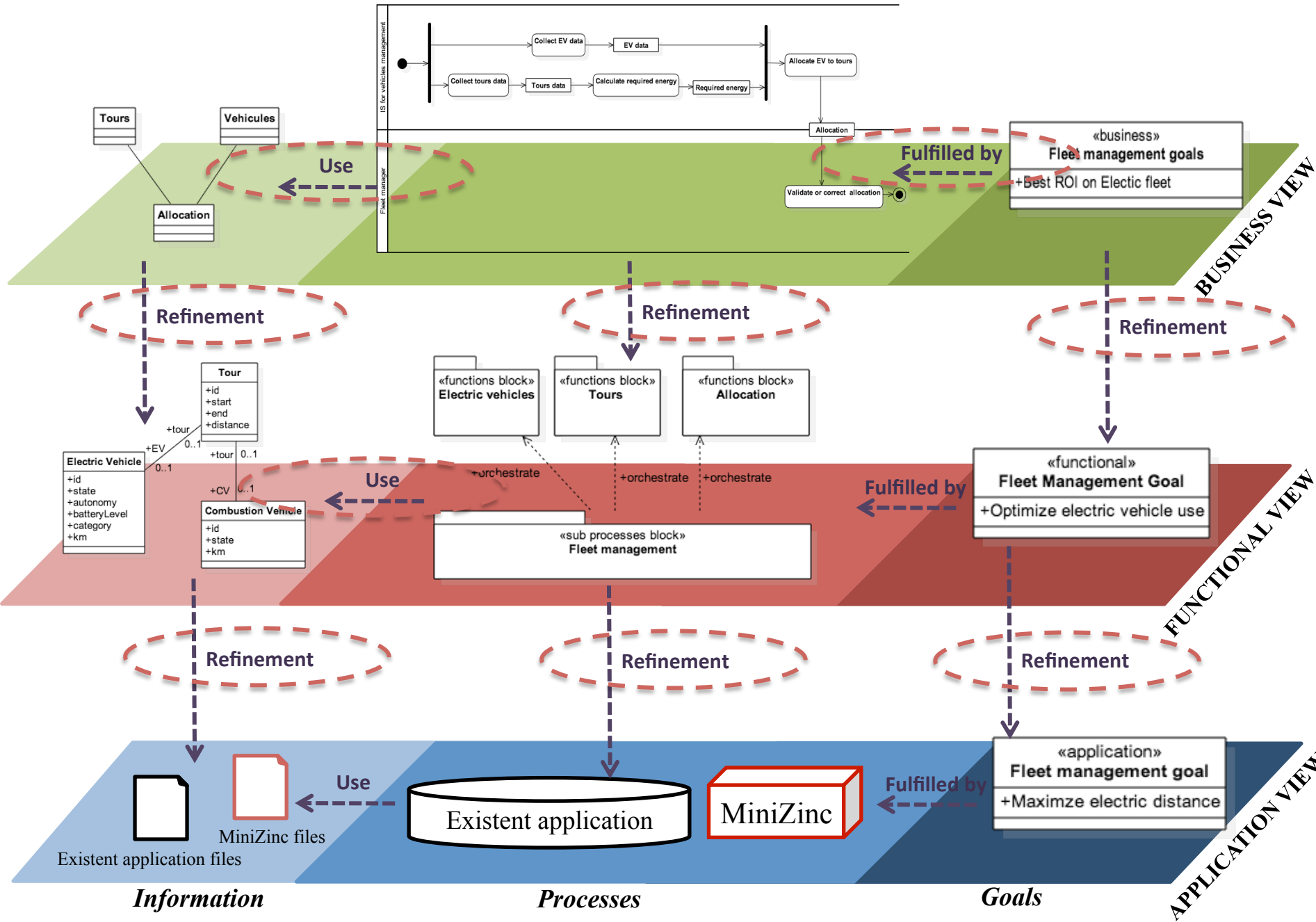


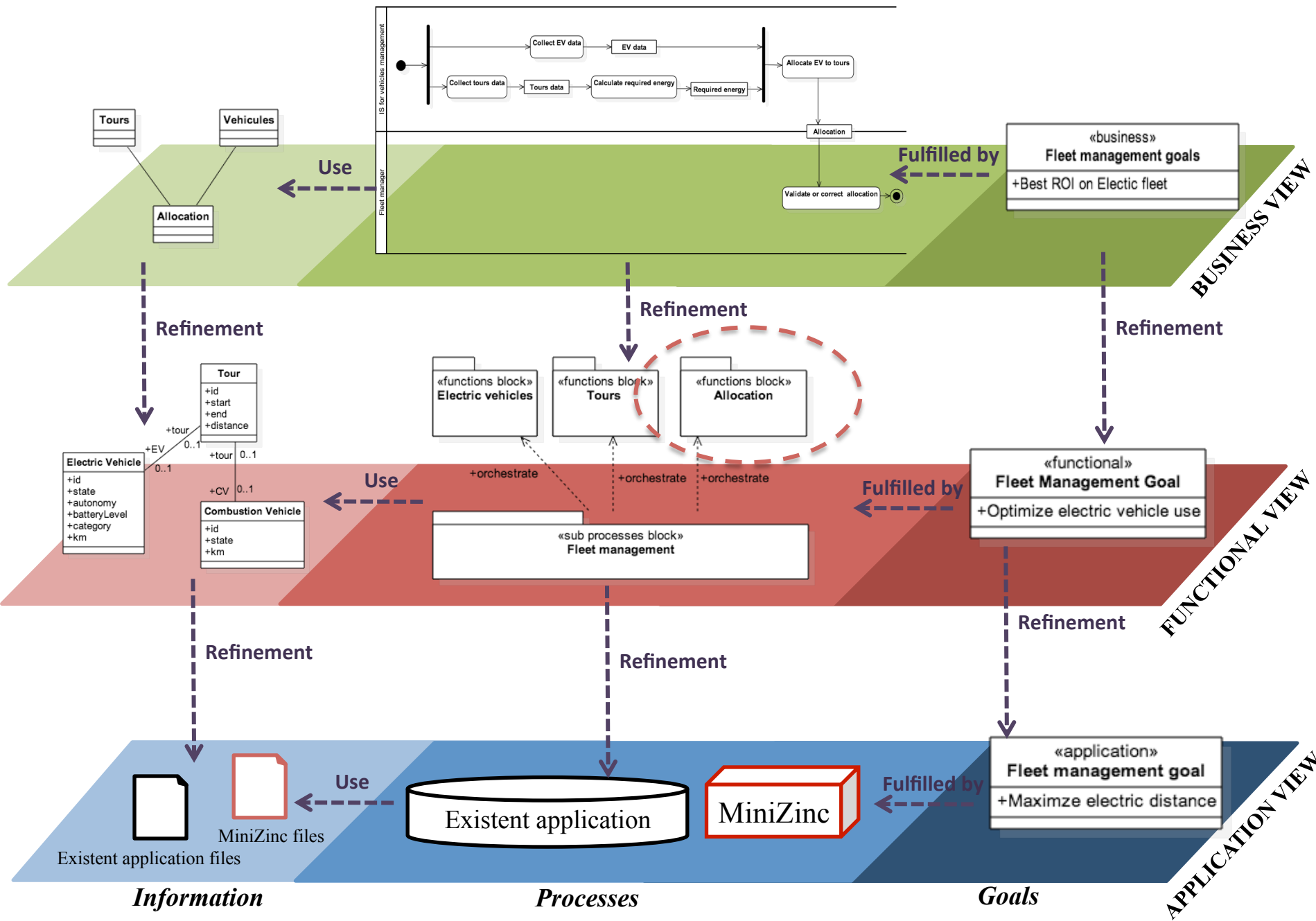
Démarche

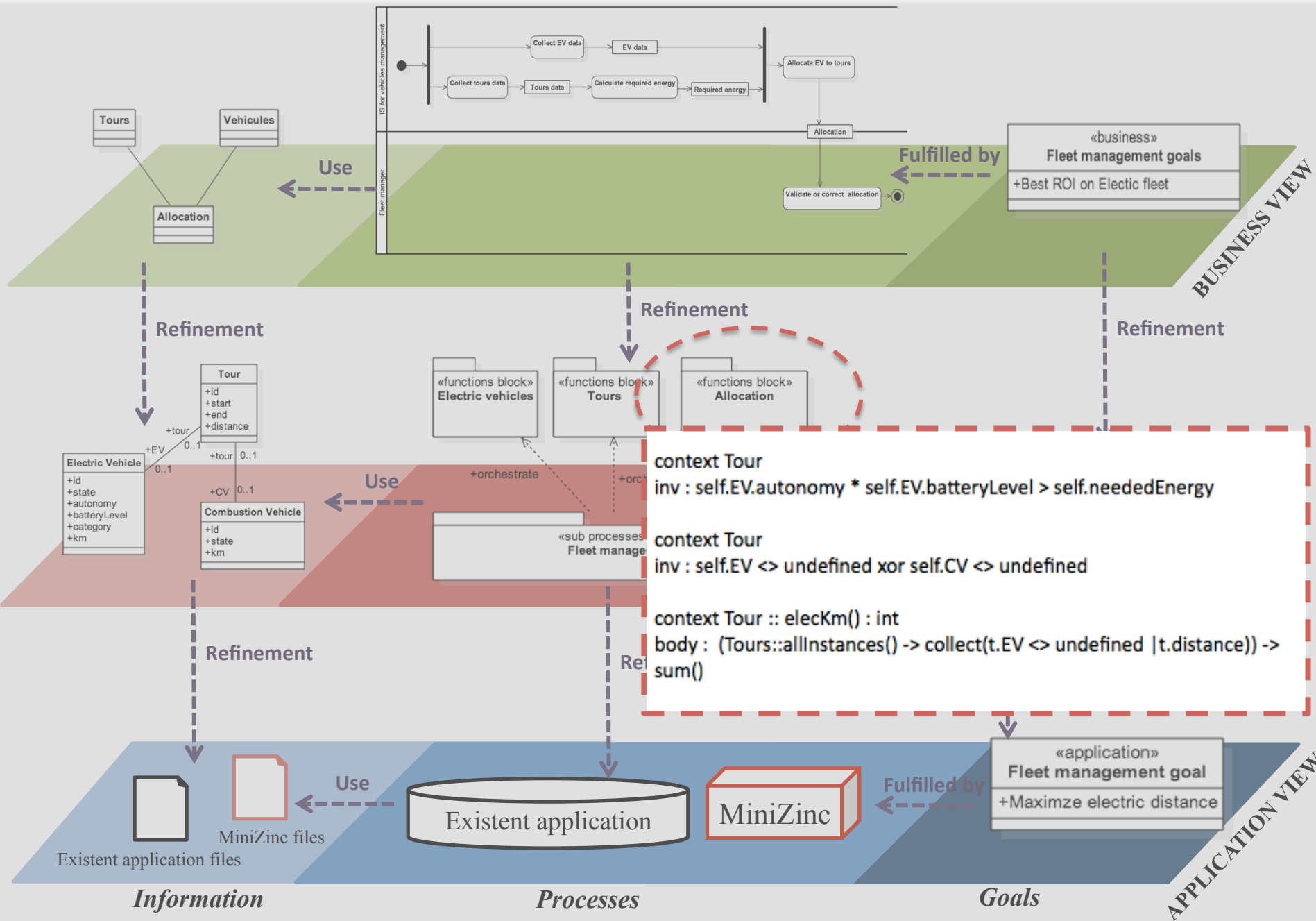


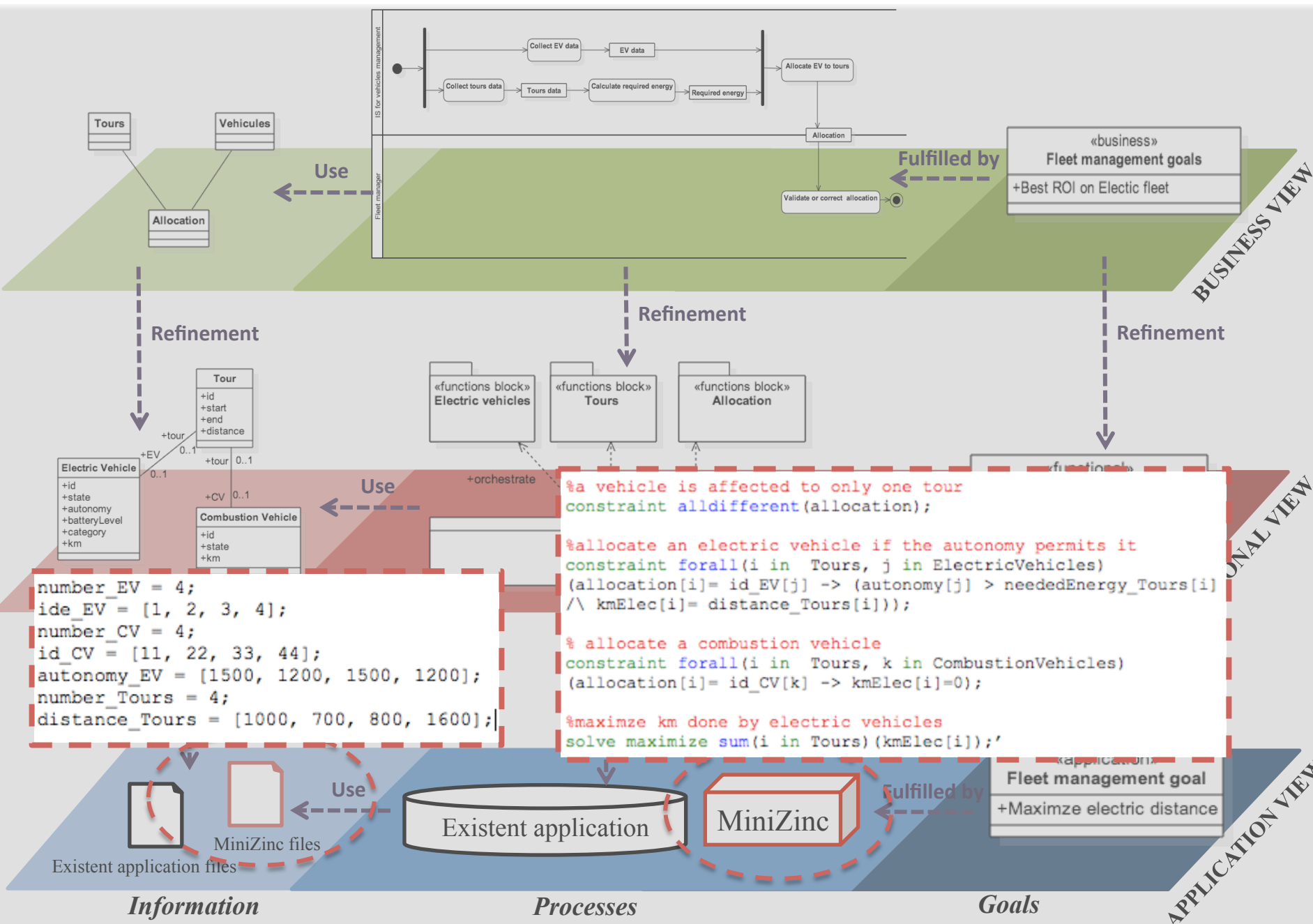
Démarche











```
number_EV = 4;  
ide_EV = [1, 2, 3, 4];  
number_CV = 4;  
id_CV = [11, 22, 33, 44];  
autonomy_EV = [1500, 1200, 1500, 1200];  
number_Tours = 4;  
distance_Tours = [1000, 700, 800, 1600];
```

```
% a vehicle is affected to only one tour  
constraint alldifferent(allocation);  
  
% allocate an electric vehicle if the autonomy permits it  
constraint forall(i in Tours, j in ElectricVehicles)  
(allocation[i]= id_EV[j] -> (autonomy[j] > neededEnergy_Tours[i]  
/\ kmElec[i]= distance_Tours[i]));  
  
% allocate a combustion vehicle  
constraint forall(i in Tours, k in CombustionVehicles)  
(allocation[i]= id_CV[k] -> kmElec[i]=0);  
  
%maximize km done by electric vehicles  
solve maximize sum(i in Tours) (kmElec[i]);
```

