

AXIOM-1

LECTURE-5 [continued]

32] Transport Phenomena is based on following five axioms:

1. Mass is conserved \rightarrow leads to Equation of continuity
 2. Momentum is conserved (essentially, Newton's 2nd Law) \rightarrow motion
 3. Moment of Momentum is conserved \rightarrow gives us τ is symmetric
 4. Energy is conserved \rightarrow Eq. of Energy \leftarrow Eq. of mechanical energy
 5. Mass of each component in a multi-component mixture is also conserved.
- Eq. of thermal energy
- Bernoulli Eq.^m

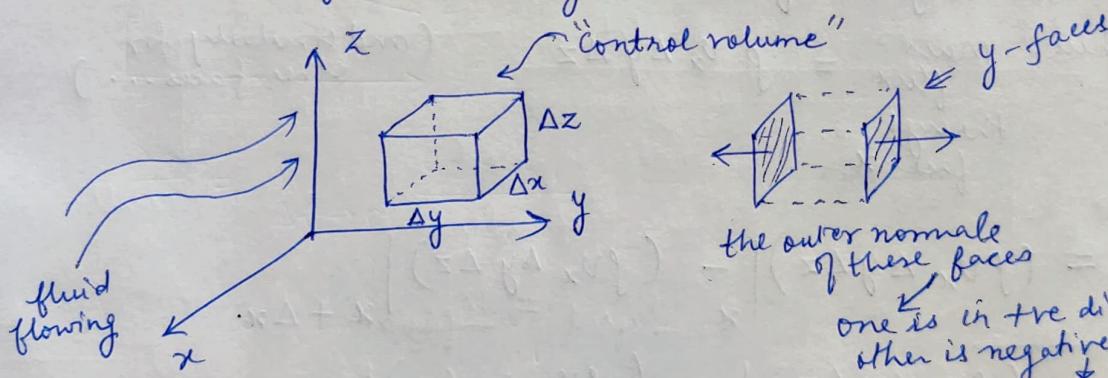
[the aim, in other words, is to get:

Velocity profile Temperature profile Concentration profile

Convective diffusion eq.^m

33) Axiom-1 : Mass is conserved

Taking cartesian coord. system:



Writing fluid velocity as:

$$\underline{v}(x, y, z, t)$$

↓ 3 components

$v_x(x, y, z, t)$

$v_y(x, y, z, t)$

$v_z(x, y, z, t)$

Density : $\rho(x, y, z, t)$

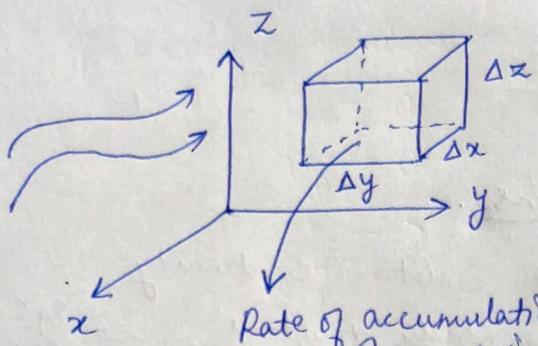
(mass/volume)

[If it were mass of a component/volume \rightarrow this would be called "mass concentration"]

* Here, if we take

$\Delta x \rightarrow 0$
 $\Delta y \rightarrow 0$
 and, $\Delta z \rightarrow 0$

} → then the control volume collapses to a single point.



* for conservation of mass :

$$\text{Rate of accumulation of mass in C.V. (control voln)} = \text{Rate of inflow of mass in C.V.} - \text{Rate of outflow of mass in C.V.}$$

$$\begin{aligned}\text{Rate of accumulation of mass in C.V.} &= \lim_{\Delta t \rightarrow 0} \frac{m|_{t+\Delta t} - m|_t}{\Delta t} \\ &= \frac{\partial m}{\partial t} \\ &= \frac{\partial (\rho \Delta x \Delta y \Delta z)}{\partial t} \quad \xrightarrow{\text{i.e. the first term}}\end{aligned}$$

$$\text{We know, } m = \rho \Delta x \Delta y \Delta z$$

$$\text{Thus, Mass flux} = \rho v_x \Delta y \Delta z \quad (\text{and similarly for other faces...})$$

through
face-x

$$\begin{aligned}\text{Thus, Rate - Rate Inflow outflow} &= (\rho v_x \Delta y \Delta z)|_x - (\rho v_x \Delta y \Delta z)|_{x+\Delta x} \\ &\quad + (\rho v_y \Delta x \Delta z)|_y - (\rho v_y \Delta x \Delta z)|_{y+\Delta y} \\ &\quad + (\rho v_z \Delta x \Delta y)|_z - (\rho v_z \Delta x \Delta y)|_{z+\Delta z}\end{aligned}$$

In the resulting eqn., we can divide both sides by $\Delta x \Delta y \Delta z$:

$$\begin{aligned}\therefore \frac{\partial \rho}{\partial t} &= \frac{(\rho v_x)|_x - (\rho v_x)|_{x+\Delta x}}{\Delta x} + \frac{(\rho v_y)|_y - (\rho v_y)|_{y+\Delta y}}{\Delta y} \\ &\quad + \frac{(\rho v_z)|_z + (\rho v_z)|_{z+\Delta z}}{\Delta z}\end{aligned}$$

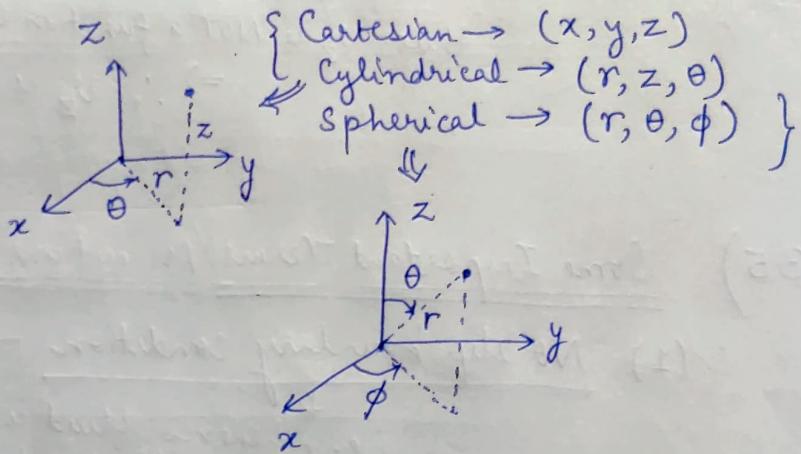
Finally, allowing $\Delta x \rightarrow 0, \Delta y \rightarrow 0, \Delta z \rightarrow 0$
we obtain:

$$\frac{\partial p}{\partial t} = - \frac{\partial (\rho v_x)}{\partial x} - \frac{\partial (\rho v_y)}{\partial y} - \frac{\partial (\rho v_z)}{\partial z}$$

$$\Rightarrow \frac{\partial p}{\partial t} + \frac{\partial (\rho v_x)}{\partial x} + \frac{\partial (\rho v_y)}{\partial y} + \frac{\partial (\rho v_z)}{\partial z} = 0$$

$$\Rightarrow \boxed{\frac{\partial p}{\partial t} + \nabla \cdot (\rho \underline{v}) = 0} \quad \text{THE CONTINUITY EQUATION}$$

* (Valid in all
Coordinate systems)



(for eg: In cylindrical: $\frac{\partial p}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} (\rho r v_r) + \frac{1}{r} \frac{\partial}{\partial \theta} (\rho v_\theta) + \frac{\partial}{\partial z} (\rho v_z) = 0$)

In spherical: $\frac{\partial p}{\partial t} + \frac{1}{r^2} \frac{\partial}{\partial r} (\rho r^2 v_r) + \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} (\rho v_\theta \sin \theta) \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (\rho v_\phi) = 0$

* {But no need
to memorize
these}

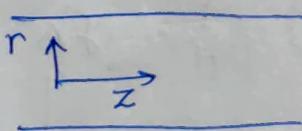
LECTURE-6

34] Steady Flow in a Tube

- 1) f constant
- 2) Steady flow

pressure
 $p = p_0$
 $z=0$

$p = p_L$
 $z=L$



Let's say: $\underline{v} \Rightarrow \begin{cases} v_r(r, \theta, z, t) \\ v_\theta(r, \theta, z, t) \\ v_z(r, \theta, z, t) \end{cases}$

(technically force)

If pressure is along z-dirⁿ only:

$$v_r = 0$$

$$v_\theta = 0$$

$v_z \rightarrow$ function of r, z only (NOT θ, t)

by symmetry, v_z should not depend on θ

↓
bcz steady

state reached

(i.e. fully developed flow)

Thus, from continuity eqⁿ:

$$\frac{\partial (fv_z)}{\partial z} = 0$$

$$\Rightarrow f \frac{\partial v_z}{\partial z} = 0$$

thus v_z is NOT a function of z

$\Rightarrow \therefore v_z$ is only a function of r
($v_z(r)$)

35) Some Important Terms/Assumptions

(1) No slip boundary condition

i.e. whenever fluid is in contact with a solid

then at interface

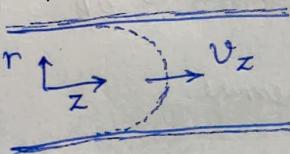
$$v_{\text{solid}} = v_{\text{fluid}}$$

e.g.: $r=R \therefore v_z|_{r=R} = 0$

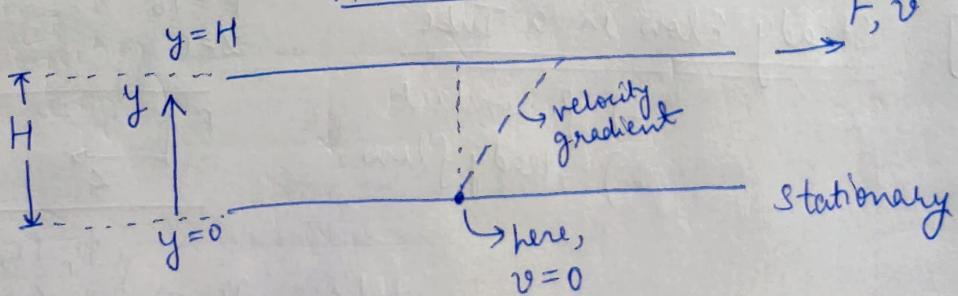
$\Downarrow \therefore v_z$ must be varying with r

Results
in
Velocity
gradients

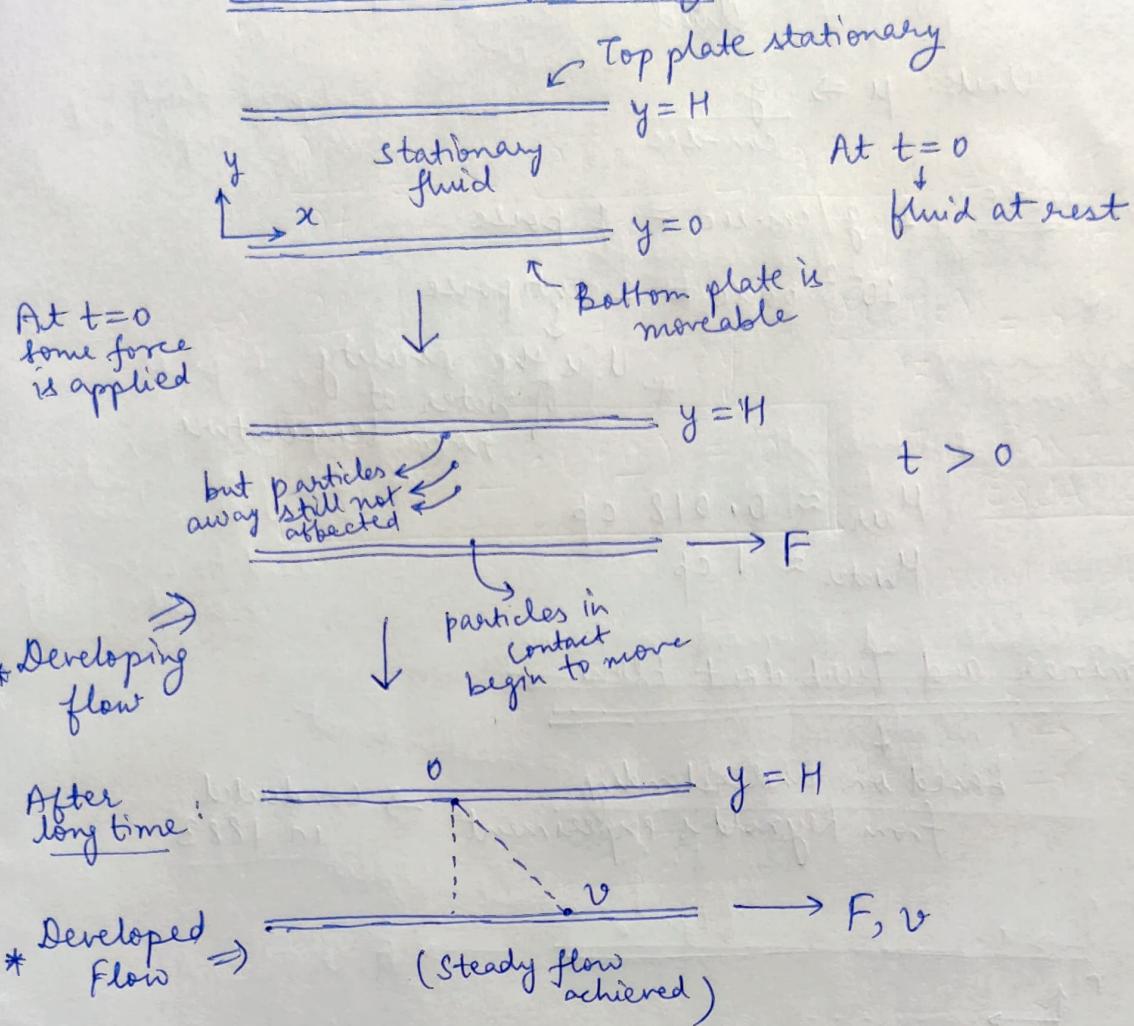
which leads to
shear forces



Another example:



(2) Newton's Law of Viscosity



F	v	$\tau_{yx} = \frac{F}{A}$	$\frac{dv_x}{dy} \approx \frac{v}{H}$
F_1	v_1	:	:
F_2	v_2	:	:
:	:	:	:

calculated experimentally

We observe the following relation:

$$\tau_{yx} \propto \frac{dv_x}{dy}$$

$$\Rightarrow \boxed{\tau_{yx} = \pm \mu \frac{dv_x}{dy}}$$

(* in Fluid mechanics we take -ve sign)

$$(e.g.: q_y = -k \frac{dT}{dy})$$

Heat flows in direction opposite to temp. gradient

(similarly, for concentration gradient)

We call: $\mu \rightarrow$ viscosity of the fluid

Units: $\mu \Rightarrow \frac{g}{\text{cm} \cdot \text{sec}}$

NOTE: $1 \text{ g/cm} \cdot \text{sec} = 1 \text{ poise}$

$10^{-2} \text{ poise} = 1 \text{ centipoise}$

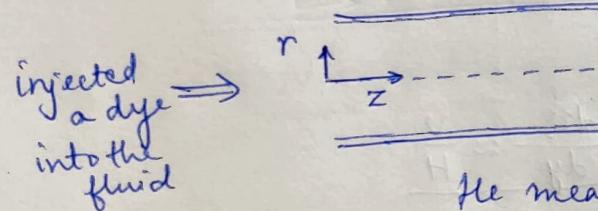
* it is the viscosity of water at room temperature

$$\mu_{\text{air}} \approx 0.018 \text{ cp}$$

$$\mu_{\text{water}} \approx 1 \text{ cp}$$

(3) Laminar and Turbulent Flow

based on understanding from Reynold's experiment \Rightarrow conducted in 1883



He measured & compared v_z

by taking different R , different f and different fluids (i.e. different μ)

But for larger velocities

as soon as dye injected

it spreads out & dissipates, and is not visible

\therefore The layers retain their individual properties (No mixing)



mixing b/w layers takes place

i.e. our assumption that

$$v_r = 0 \text{ and } v_\theta = 0$$

only applies for laminar flow (not turbulent flow)

He defined :

$$Re = \frac{\rho D v_{\text{avg}}}{\mu}$$

(Reynold's number)

this is dimensionless

When, $Re \leq 2100 \Rightarrow$ Laminar flow

(beyond 2100, Turbulent flow MAY occur)

(but beyond ~ 5000 , it will surely be turbulent flow)

Critical Reynold's Number = 2100

valid for any flow

{ Reason:
The mathematical form of the non-linear eqn's is such that + they become unstable beyond ~ 2100 }

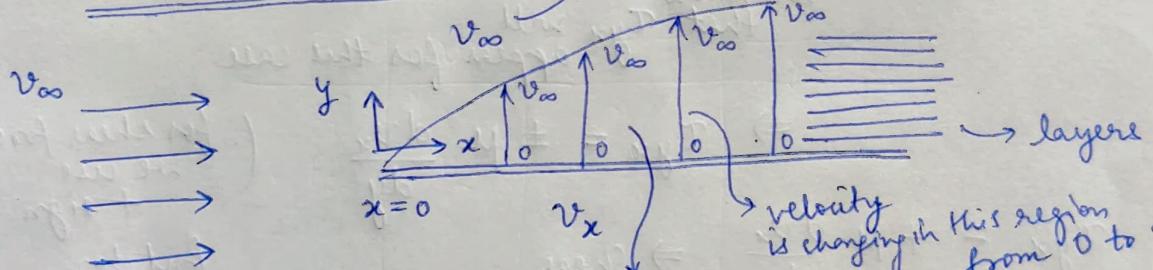
LECTURE-7

36] { * NOTE: Most problems that we'll solve in this course are fully-developed flow.

* Some imp. terms: types of flows

External flow Internal flow Boundary layer Potential flows
... etc.

Boundary Layer and Potential Flows:



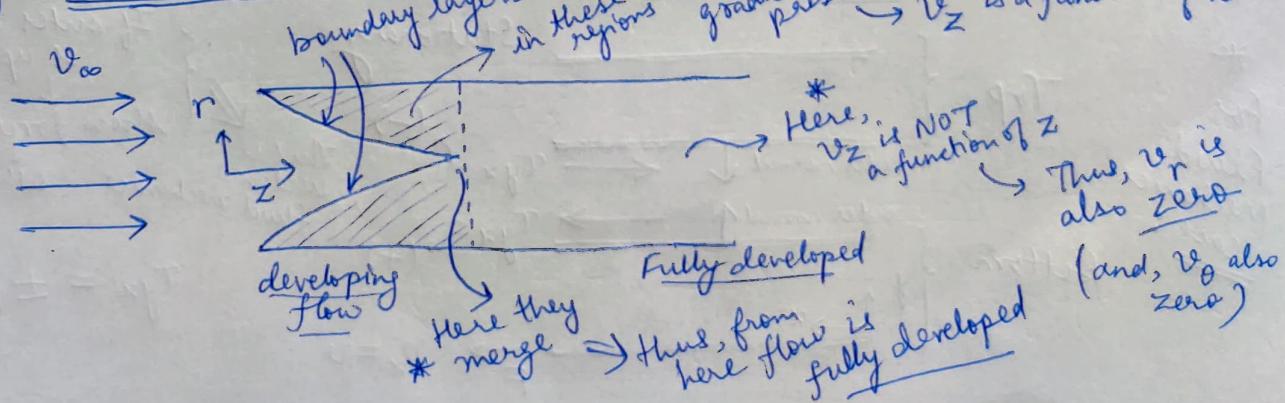
This is Boundary layer & potential flow

Here v_x is a function of x

velocity is changing in this region from 0 to v_{∞}

velocity gradients present in this region (shear forces also present here)

37] Internal Flow



* NOTE: From eq. of continuity, we can see that if $v_r \neq 0$, then it becomes extremely difficult ↓ thus developing flow is very complicated.

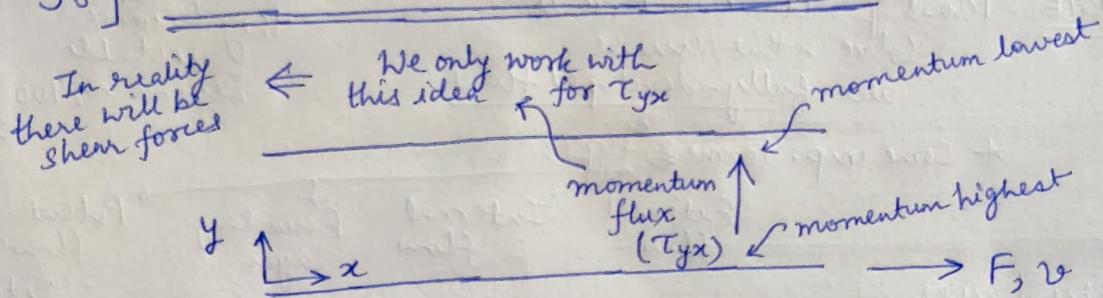
"Entry length" ↓
length of region where developing flow is present

This is usually
 v_r small

↑ relative to length of entire pipe

{ * But for short pipes ↓ using the case for fully developed flow may lead to wrong results }

38] Shear Forces and Momentum Flux



We know that τ_{yx} will appear for this case

$$\Rightarrow \tau_{yx} = \pm \mu \frac{dv_x}{dy} \quad (\text{for shear forces we use + sign})$$

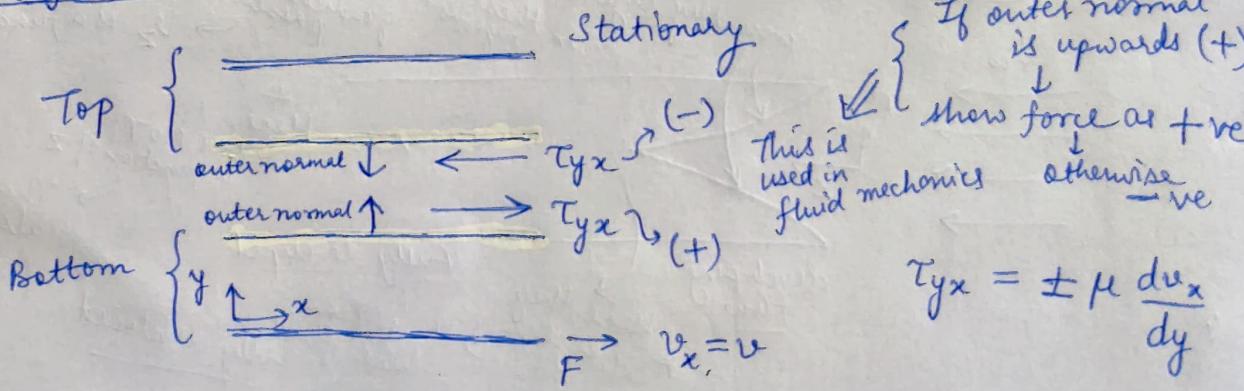
$$\tau_{yx} = +\mu \frac{dv_x}{dy} \Rightarrow \text{Shear forces}$$

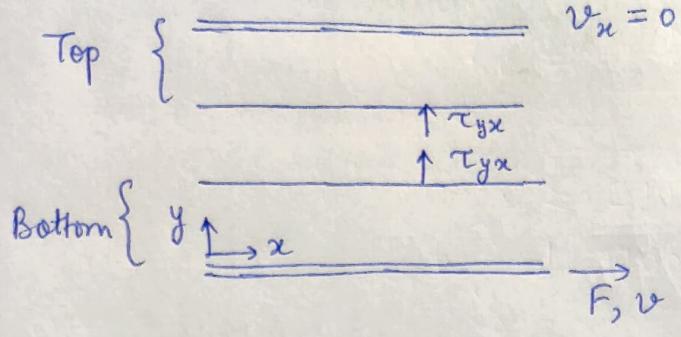
$$\tau_{yx} = -\mu \frac{dv_x}{dy} \Rightarrow \text{Momentum Flux}$$

But for our flows from high to low we use -ve sign

Sign Convention for Momentum Flux and Fluid Mechanics

* for fluid mechanics case:





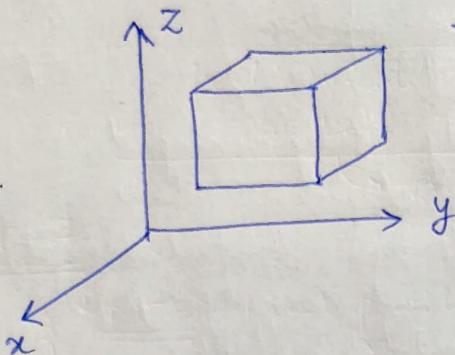
* In our case (using momentum flux)

So here,
the sign for momentum flux
will be -ve!

$$\tau_{yx} = -\mu \frac{dv_x}{dy}$$

(always
-ve)

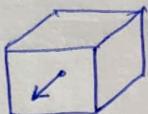
39]



There seem to be
 $6 \times 3 = 18$ components
but actually only 9
(\because faces on opposite sides
have normals along
some axis)

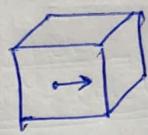
$$\begin{pmatrix} \tau_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & \tau_{yy} & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \tau_{zz} \end{pmatrix}$$

e.g.: τ_{xx} :



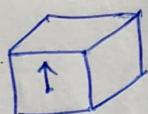
Similarly for z-face:

τ_{xy} :



(and similarly
for y-face...)

τ_{xz} :



40] Using equation of continuity:

$$\frac{\partial p}{\partial t} + \nabla \cdot (p \underline{v}) = 0$$

But we know that: $\nabla \cdot (s \underline{v}) = s \nabla \cdot \underline{v} + \underline{v} \cdot \nabla s$

$$\Rightarrow \boxed{\frac{\partial p}{\partial t} + p \nabla \cdot \underline{v} + \underline{v} \cdot \nabla p} = 0$$

Using
definition
of substantial
derivative

$$\boxed{\frac{Dp}{Dt} + p \nabla \cdot \underline{v} = 0}$$

* Alternate
form of Equation
of Continuity

LECTURE-8

* NOTE: Momentum flux (τ_{yx} for instance) \Rightarrow Momentum is along x
but the transfer of momentum is along y.
(i.e. flux) implies