

This gives us the final ultimate formula:

$$\begin{aligned}
 \frac{\partial}{\partial t} \rho \left( \hat{U} + \frac{1}{2} v^2 \right) = & - \frac{\partial}{\partial x} \rho v_x \left( \hat{U} + \frac{1}{2} v^2 \right) - \frac{\partial}{\partial y} \rho v_y \left( \hat{U} + \frac{1}{2} v^2 \right) \\
 & - \frac{\partial}{\partial z} \rho v_z \left( \hat{U} + \frac{1}{2} v^2 \right) \\
 & - \left( \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} + \frac{\partial q_z}{\partial z} \right) \\
 & + \rho (v_x g_x + v_y g_y + v_z g_z) \\
 & - \left( \frac{\partial}{\partial x} \rho v_x + \frac{\partial}{\partial y} \rho v_y + \frac{\partial}{\partial z} \rho v_z \right) \\
 & - \left[ \frac{\partial}{\partial x} (\tau_{xx} v_x + \tau_{xy} v_y + \tau_{xz} v_z) \right. \\
 & \quad + \frac{\partial}{\partial y} (\tau_{yx} v_x + \tau_{yy} v_y + \tau_{yz} v_z) \\
 & \quad \left. + \frac{\partial}{\partial z} (\tau_{zx} v_x + \tau_{zy} v_y + \tau_{zz} v_z) \right] \\
 & + S_c
 \end{aligned}$$

In vector-tensor form this simplifies to:

$$\boxed{
 \begin{aligned}
 \frac{\partial}{\partial t} \rho \left( \hat{U} + \frac{1}{2} v^2 \right) = & - \underline{\nabla} \cdot \rho \underline{v} \left( \hat{U} + \frac{1}{2} v^2 \right) \\
 & - \underline{\nabla} \cdot \underline{q} + \rho \underline{v} \cdot \underline{g} - \underline{\nabla} \cdot \rho \underline{v} \\
 & - \underline{\nabla} \cdot (\underline{\tau} \cdot \underline{v}) + S_c
 \end{aligned}
 }$$

EQUATION OF ENERGY

## LECTURE-20

81) Applying the identity:  $\underline{\nabla} \cdot s \underline{w} = s \underline{\nabla} \cdot \underline{w} + \underline{w} \cdot \underline{\nabla} s$

we can transform:

$$\underline{\nabla} \cdot \underbrace{\rho \underline{v}}_{\underline{w}} \underbrace{\left( \hat{U} + \frac{1}{2} v^2 \right)}_s$$

$$\Rightarrow \underbrace{\frac{\partial}{\partial t} \rho (\hat{U} + \frac{1}{2} v^2)}_{\substack{\downarrow \\ (\hat{U} + \frac{1}{2} v^2) \frac{\partial \rho}{\partial t} + \rho \frac{\partial (\hat{U} + \frac{1}{2} v^2)}{\partial t}}} + (\hat{U} + \frac{1}{2} v^2) \underline{\nabla} \cdot \rho \underline{v} + \rho \underline{v} \cdot \underline{\nabla} (\hat{U} + \frac{1}{2} v^2) = -\underline{\nabla} \cdot \underline{q} + \dots$$

$$\Rightarrow (\hat{U} + \frac{1}{2} v^2) \left[ \underbrace{\frac{\partial \rho}{\partial t} + \underline{\nabla} \cdot \rho \underline{v}}_{\substack{\text{eq. of continuity} \\ \downarrow \\ \therefore \text{this is zero}}} \right] + \rho \left( \frac{\partial (\hat{U} + \frac{1}{2} v^2)}{\partial t} + \underline{v} \cdot \underline{\nabla} (\hat{U} + \frac{1}{2} v^2) \right) = -\underline{\nabla} \cdot \underline{q} + \dots$$

$$\Rightarrow \boxed{\rho \frac{D(\hat{U} + \frac{1}{2} v^2)}{Dt} = -\underline{\nabla} \cdot \underline{q} - \underline{\nabla} \cdot (\underline{\tau} \cdot \underline{v}) + \rho \underline{v} \cdot \underline{g} - \underline{\nabla} \cdot (\rho \underline{v}) + S_c}$$

This equation by itself  
however has  
almost no use  
for us

## 8.2] Derivation of equation of Mechanical Energy

We know:

$$\underline{F} = m \underline{a} = m \frac{d\underline{v}}{dt}$$

$$\Rightarrow \underline{v} \cdot \underline{F} = m \underline{v} \cdot \frac{d\underline{v}}{dt}$$

NOTE: This is NOT  
obtained from  
conservation  
of energy  
↓  
it is obtained  
from Newton's II<sup>nd</sup>  
Law

We also know that:  $\frac{d}{dt} (\underline{v} \cdot \underline{v}) = \underline{v} \cdot \frac{d\underline{v}}{dt} + \frac{d\underline{v}}{dt} \cdot \underline{v}$

$$= 2 \underline{v} \cdot \frac{d\underline{v}}{dt}$$

$$= \frac{1}{2} \frac{d}{dt} (v^2)$$

$$= \frac{d}{dt} \left( \frac{1}{2} v^2 \right)$$



Considering the situation:



$\downarrow g_z$ , i.e.  $F_x$  and  $F_y$  are zero

$$(i.e. \underline{g} = -g_z \hat{z}) \Rightarrow \underline{F} = -mg_z \hat{z}$$

Thus, we have:

$$-mv_z g_z = m \frac{d}{dt} \left( \frac{1}{2} v^2 \right)$$

We know that the eq<sup>n</sup> of motion for fluid is:

$$\rho \frac{D\underline{v}}{Dt} = -\underline{\nabla} P + \rho \underline{g} - \underline{\nabla} \cdot \underline{\tau}$$

$$\text{Taking } \underline{v} \cdot \Rightarrow \rho \underline{v} \cdot \frac{D\underline{v}}{Dt} = -\underline{v} \cdot (\underline{\nabla} P) + \underline{v} \cdot \rho \underline{g} - \underline{v} \cdot \underline{\nabla} \cdot \underline{\tau}$$

$$\Rightarrow \rho \frac{D(\frac{1}{2} v^2)}{Dt} = -\underline{v} \cdot \underline{\nabla} P + \underline{v} \cdot \rho \underline{g} - \underline{v} \cdot \underline{\nabla} \cdot \underline{\tau}$$

For the case of  $\rho = \text{const}$ , No shear forces:

$$\rho \frac{D(\frac{1}{2} v^2)}{Dt} = -\underline{v} \cdot \underline{\nabla} P + \underline{v} \cdot \rho \underline{g}$$

We can define gravity using a potential:  $\underline{g} = -\underline{\nabla} \phi$

$$\begin{aligned} \Rightarrow \rho \frac{D(\frac{1}{2} v^2)}{Dt} &= -\underline{v} \cdot \underline{\nabla} P + \underline{v} \cdot \rho (-\underline{\nabla} \phi) \\ &= -\underline{v} \cdot \underline{\nabla} P - \rho \underline{v} \cdot \underline{\nabla} \phi \end{aligned}$$

Since both  $P$  and  $\phi$  are not functions of time, so we can add those terms to create a substantial derivative:

$$\begin{aligned} \rho \frac{D(\frac{1}{2} v^2)}{Dt} &= -\underline{v} \cdot \underline{\nabla} P - \rho \underline{v} \cdot \underline{\nabla} \phi \\ &\quad - \frac{\partial P}{\partial t} - \rho \frac{\partial \phi}{\partial t} \end{aligned}$$

$$\Rightarrow \rho \frac{D(\frac{1}{2} v^2)}{Dt} = -\frac{DP}{Dt} - \rho \frac{D\phi}{Dt}$$

$$\Rightarrow \frac{D}{Dt} \left( \frac{1}{2} \rho v^2 + P + \phi \right) = 0$$

$$\Rightarrow \boxed{\frac{1}{2} \rho v^2 + P + \phi = \text{const.}}$$

which is  
BERNOULLI'S  
EQUATION

(applicable only for const.  $\rho$  and  
no shear forces  
and no temp. change)

In general, the eq<sup>n</sup> of mechanical energy (is for No shear and const.  $\rho$ ):

$$\boxed{\rho \frac{D}{Dt} \left( \frac{1}{2} v^2 \right) = - \underline{v} \cdot \underline{\nabla} P - \rho \underline{v} \cdot \underline{\nabla} \phi}$$

\* this is actually  
in general!  
 $+ \rho \underline{v} \cdot \underline{g}$

EQUATION OF MECHANICAL  
ENERGY

Now, the general eq<sup>n</sup> of <sup>mechanical</sup> energy (that we got by taking  $\underline{v} \cdot$ )  
will also have the shear term.

Here, we know,  $\underline{v} \cdot (\underline{\nabla} \cdot \underline{\tau}) = \underline{\nabla} \cdot (\underline{\tau} \cdot \underline{v}) - \underline{\tau} : \underline{\nabla} \underline{v}$

Thus:  $\rho \frac{D}{Dt} \left( \frac{1}{2} v^2 \right) = - \underline{v} \cdot \underline{\nabla} P - \underbrace{\rho \underline{v} \cdot \underline{\nabla} \phi}_{\text{or just } + \rho \underline{v} \cdot \underline{g}} - \underline{\nabla} \cdot (\underline{\tau} \cdot \underline{v}) + \underline{\tau} : \underline{\nabla} \underline{v}$

Again we know:

$$\underline{\nabla} \cdot (\rho \underline{v}) = \rho \underline{\nabla} \cdot \underline{v} + \underline{v} \cdot \underline{\nabla} \rho$$

$$\Rightarrow \rho \frac{D}{Dt} \left( \frac{1}{2} v^2 \right) = \rho \underline{\nabla} \cdot \underline{v} - \underline{\nabla} \cdot (\rho \underline{v}) + \rho \underline{v} \cdot \underline{g} - \underline{\nabla} \cdot (\underline{\tau} \cdot \underline{v}) + \underline{\tau} : \underline{\nabla} \underline{v}$$

Subtracting eq<sup>n</sup> of mechanical energy from eq<sup>n</sup> of total energy:

$$\Rightarrow \boxed{\rho \frac{D \hat{U}}{Dt} = - \underline{\nabla} \cdot \underline{q} - \rho \underline{\nabla} \cdot \underline{v} - \underline{\tau} : \underline{\nabla} \underline{v} + S_c}$$

EQUATION OF THERMAL  
ENERGY



Now, the eq<sup>n</sup> of mechanical energy is:

$$\rho \frac{D(\frac{1}{2} \underline{v}^2)}{Dt} = \rho \underline{\nabla} \cdot \underline{v} - \underline{\nabla} \cdot (P \underline{v}) + \rho \underline{v} \cdot \underline{g} - \underline{\nabla} \cdot (\underline{\tau} \cdot \underline{v}) + \underbrace{\underline{\tau} : \underline{\nabla} \underline{v}}_{\text{this can be written as}}$$

The term is called

\* Viscous dissipation term

$$\Rightarrow \text{i.e. } -\underline{\tau} : \underline{\nabla} \underline{v}$$

↓  
this quantity is ALWAYS \*  
positive

↓  
for Newtonian fluid it takes the form:

$$\boxed{-\underline{\tau} : \underline{\nabla} \underline{v} = \rho \phi_v} \rightarrow \text{called the dissipation function for Newtonian fluids}$$

Hence this means

that some part of the

mechanical energy is always going down

↓  
and gets converting  
to thermal  
energy

$$(-\underline{\tau} : \underline{\nabla} \underline{v})$$

### 83) Temperature explicit form of eq<sup>n</sup> of thermal energy

The eq<sup>n</sup> of thermal energy is:

$$\rho \frac{D\hat{U}}{Dt} = -\underline{\nabla} \cdot \underline{q} - P \underline{\nabla} \cdot \underline{v} + (-\underline{\tau} : \underline{\nabla} \underline{v}) + S_c$$

Temp. explicit form of eq<sup>n</sup> can be obtained as follows:

We can write from thermodynamics:

$$\hat{U} = \hat{U}(T, \hat{V})_{\text{volume}}$$

$$d\hat{U} = \left( \frac{\partial \hat{U}}{\partial T} \right)_{\hat{V}} dT + \left( \frac{\partial \hat{U}}{\partial \hat{V}} \right)_T d\hat{V}$$

$$= C_v dT + \left[ -P + T \left( \frac{\partial P}{\partial T} \right)_{\hat{V}} \right] d\hat{V}$$

\* this term is zero ONLY  
for Ideal gases

This is because:

$$P \hat{V} = RT$$

$$\Rightarrow \left( \frac{\partial P}{\partial T} \right)_{\hat{V}} = \frac{R}{\hat{V}}$$

$$\text{Thus } \Rightarrow \left[ -P + \frac{RT}{\hat{V}} \right] = -P + P = 0 \}$$

Hence, we can write:

$$\frac{D\hat{U}}{Dt} = C_v \frac{DT}{Dt} + \left[ -P + T \left( \frac{\partial P}{\partial T} \right)_{\hat{V}} \right] \frac{D\hat{V}}{\hat{V} Dt}$$

We know that also:  $\hat{V} = \frac{1}{\rho}$  and  $\frac{D\rho}{Dt} + \rho \nabla \cdot \underline{v} = 0$

$$\Downarrow$$

$$\text{thus, } \frac{D\hat{V}}{Dt} = -\frac{1}{\rho^2} \frac{D\rho}{Dt} = -\frac{1}{\rho^2} (-\rho \nabla \cdot \underline{v})$$

$$= \frac{\nabla \cdot \underline{v}}{\rho}$$

So finally the eq<sup>n</sup> of thermal energy in explicit form is obtained using:

$$\underbrace{\rho \left( C_v \frac{DT}{Dt} + \left( -P + T \left( \frac{\partial P}{\partial T} \right)_{\hat{V}} \right) \frac{\nabla \cdot \underline{v}}{\rho} \right)}_{\rho C_v \frac{DT}{Dt} - P \nabla \cdot \underline{v} + T \left( \frac{\partial P}{\partial T} \right)_{\hat{V}} \nabla \cdot \underline{v}} = -\nabla \cdot \underline{q} - P \nabla \cdot \underline{v} + (-\underline{\tau} : \nabla \underline{v}) + S_e$$

Hence, we get:

$$\boxed{\rho C_v \frac{DT}{Dt} = -\nabla \cdot \underline{q} - T \left( \frac{\partial P}{\partial T} \right)_{\hat{V}} \nabla \cdot \underline{v} + (-\underline{\tau} : \nabla \underline{v}) + S_e}$$

EQUATION OF  
THERMAL ENERGY  
IN EXPLICIT  
FORM

\* { can be seen  
from Appendix }



84] Special cases:

(i) For  $\rho$  constant:

$$\rho C_p \frac{DT}{Dt} = -\nabla \cdot \underline{q} + \underbrace{(-\underline{\tau} : \nabla \underline{v})}_{\substack{\text{in general} \\ \text{can be} \\ \text{written as} \\ \mu \phi v}} + S_c$$

but if nothing mentioned in question  
it can be taken as zero

( $\because$  it is practically very small)

{ and similarly as we did in fluid mechanics, here also we can take

$$-\nabla \cdot \underline{q} \text{ as } k \nabla^2 T \}$$

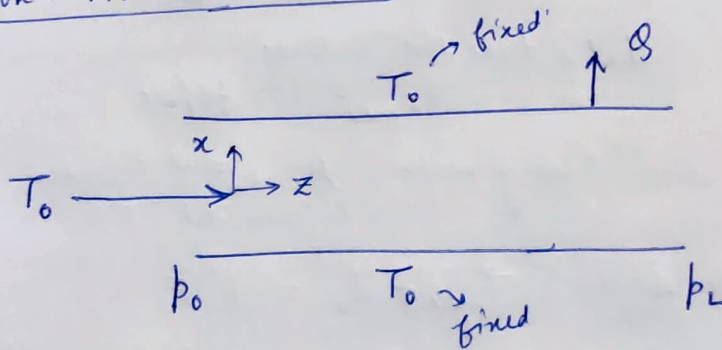
if  $k$  is also a constant

LECTURE-21

(ii) Thus, if both  $\rho$  and  $k$  are constant:

$$\rho C_p \frac{DT}{Dt} = k \nabla^2 T + (-\underline{\tau} : \nabla \underline{v}) + S_c$$

85] Book: Problem 10H-2



(it appears Temp. is same everywhere so it can't change  
but it will still change, due to heating up by viscous dissipation)

Assumptions:

Steady state

$\rho, \mu, k$  are constant

$$v_x = v_y = 0, v_z = v_z(x)$$

From fluid solution:

$$v_z = \frac{p_0 - p_L}{4\mu L} \left( 1 - \left( \frac{x}{\beta} \right)^2 \right) = v_{max} \left( 1 - \left( \frac{x}{\beta} \right)^2 \right)$$

Also,  $T(x, z) \Rightarrow T(x)$  only

Now,  $(-\underline{\tau} : \underline{\nabla} \underline{v}) = \mu \phi_v$   
 $\downarrow$   
 for Newtonian case

Hence, we can write:

$$\rho C_p \frac{DT}{Dt} = k \nabla^2 T + \mu \phi_v + \cancel{S_c}^0 \text{ (in this problem)}$$

Thus, we have:

$$\rho C_p \left( \frac{\partial T}{\partial t} + \underbrace{\underline{v} \cdot \underline{\nabla} T}_0 \right) = k \nabla^2 T + \mu \underbrace{\left( \frac{\partial v_z}{\partial x} \right)^2}_{\phi_v \text{ obtained from Appendix}}$$

Using boundary conditions:

$$x = B, T = T_0$$

$$\text{and } x = -B, T = T_0$$

We get the solution:  $T = T_0 + \frac{\mu}{k} \frac{v_{z_{\max}}^2}{3} \left( 1 - \left( \frac{x}{B} \right)^4 \right)$

Thus,  $T_{\max} - T_0 = \frac{\mu}{k} \frac{v_{z_{\max}}^2}{3}$

Let's take the values:

$$v_{z_{\max}} = 100 \text{ ft/sec}$$

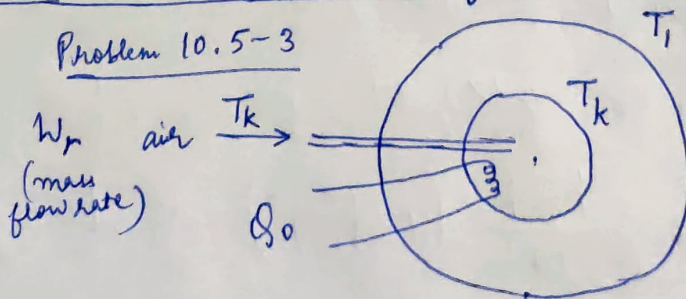
using water,  $\mu_{\text{water}}$  and  $k_{\text{water}}$   
 taken at  $25^\circ\text{C}$

We obtain,  $T_{\max} - T_0 \approx 1^\circ\text{F}$

$\hookrightarrow$  very small

## 86] Transpiration cooling/heating

Problem 10.5-3





## Assumptions

Steady state

$k, \rho, c_p$  constant

$$v_\theta = v_\phi = 0$$

$$v_r = v_r(r)$$

From eq<sup>n</sup> of continuity:  $\frac{1}{r^2} \frac{d}{dr} (r^2 v_r) = 0$

$$\Rightarrow r^2 v_r = \text{const.}$$

$$\Rightarrow \underbrace{4\pi r^2 \rho v_r}_{W_r} = \text{const}$$

$$\Rightarrow v_r = \frac{W_r}{4\pi \rho r^2}$$

Now, viscous dissipation is negligible

$$\text{and, } T(r, \theta, \phi) \Rightarrow T(r)$$

Thus,  $\rho c_p \left( \frac{\partial T}{\partial t} + \underline{v} \cdot \underline{\nabla} T \right) = k \nabla^2 T + \mu \phi_v$

$$\rho c_p \left( v_r \frac{dT}{dr} \right) = k \left[ \frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{dT}{dr} \right) \right]$$

From boundary conditions:

$$\left. \begin{array}{l} r = \lambda R, T = T_k \\ r = R, T = T_i \end{array} \right\} \text{will be used later}$$

$$\Rightarrow r^2 \frac{\rho c_p}{k} \underbrace{v_r}_{\substack{\text{replace with:} \\ \frac{W_r}{4\pi \rho r^2}}} \frac{dT}{dr} = \frac{d}{dr} \left( r^2 \frac{dT}{dr} \right)$$

$$\Rightarrow \underbrace{\frac{W_r c_p}{4\pi k}}_{\text{let's call this } R_0} \frac{dT}{dr} = \frac{d}{dr} \left( r^2 \frac{dT}{dr} \right)$$

let's call this  $R_0$

$$\Rightarrow R_0 \frac{dT}{dr} = r^2 \frac{d^2 T}{dr^2} + 2r \frac{dT}{dr}$$

Taking  $\frac{dT}{dr} = Y$

$$\Rightarrow R_0 Y = r^2 \frac{dY}{dr} + 2rY$$

$$\Rightarrow r^2 \frac{dY}{dr} = (R_0 - 2r) Y$$

$$\Rightarrow \frac{dY}{Y} = \frac{(R_0 - 2r)}{r^2} dr$$

$$\Rightarrow \log Y = -\frac{R_0}{r} - 2 \log r + C_2$$

$$\Rightarrow \log(r^2 Y) = -\frac{R_0}{r} + C_2$$

$$\Rightarrow r^2 Y = C_3 e^{-R_0/r}$$

$$\Rightarrow r^2 \frac{dT}{dr} = C_3 e^{-R_0/r}$$

$$\Rightarrow \frac{dT}{dr} = C_3 \frac{e^{-R_0/r}}{r^2}$$

We can integrate this to find  $T$ :

$$T = (C_3 \int \frac{e^{-R_0/r}}{r^2} dr) + C_4$$

From boundary cond<sup>n</sup>s:

$$\frac{T - T_i}{T_k - T_i} = \frac{e^{-R_0/r} - e^{-R_0/R}}{e^{-R_0/\lambda R} - e^{-R_0/R}} \quad \left. \vphantom{\frac{T - T_i}{T_k - T_i}} \right\} \rightarrow \text{from here } \frac{dT}{dr} \text{ can be computed}$$

So we get,  $Q = 4\pi \lambda^2 R^2 \left( -k \frac{dT}{dr} \right) \Big|_{r=\lambda R}$

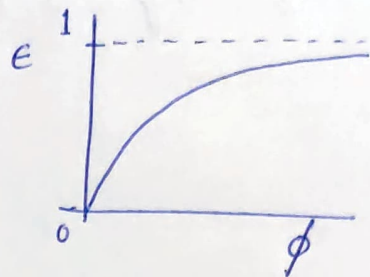
$$= \frac{4\pi k R_0 (T_i - T_k)}{e^{-R_0/\lambda R (1-\lambda)} - 1}$$

Now,  $R_0 = \frac{\omega_p C_p}{4\pi k}$ , so for the case  $\omega_p = 0 \Rightarrow Q_0 = \frac{4\pi k \lambda R (T_i - T_k)}{1 - \lambda}$



∴ The efficiency can be obtained as:

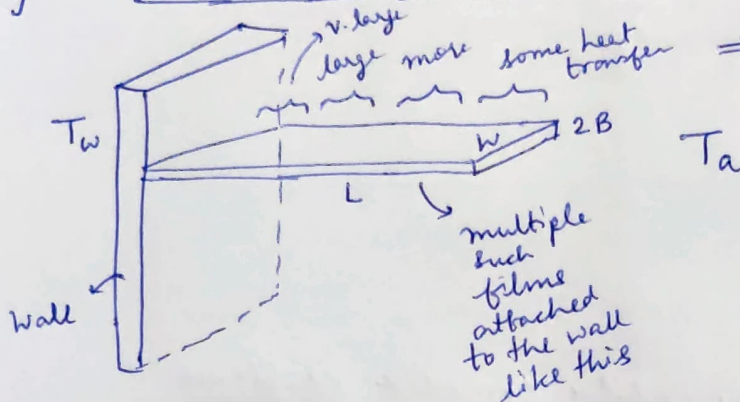
$$\epsilon = \frac{Q_0 - Q}{Q_0}$$



(where,  $\phi = \frac{R_0(1-\lambda)}{\lambda R}$ )

87)

### Heat conduction in a thin film



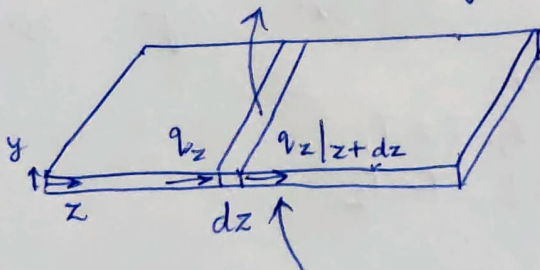
∴ heat transfer  $\propto T - T_a$   
 ↓  
 thus, longer length is preferable  
 (but length must be limited by practicality)

( $L \& W \gg 2B$ )

Due to large area  
 ↓  
 there will be large heat transfer

Efficiency,  $\eta = \frac{\text{heat which actually dissipated by addition of film}}{\text{Heat dissipated if the whole film was at temp. } T_w}$   
 (effectiveness of film)  
 ↓  
 ( $\eta > 1$ )

$T = T(z)$ ,  $k$  const.  
 $C_p$  const, etc...  
 steady state



$$0 = W(2B) q_z|_z - W(2B) q_z|_{z+dz} + h(T - T_a) dz W - (-h(T - T_a)) dz W$$

$$\Rightarrow \frac{d}{dz} \left( -k \frac{dT}{dz} \right) = \frac{dq_z}{dz} = \frac{-h(T - T_a)}{B}$$

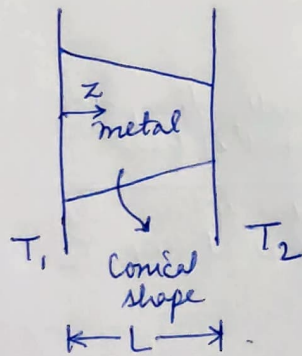
Boundary cond<sup>n</sup>s:  $z=0, T=T_w$

$$z=L, \frac{dT}{dz}=0, q_z|_{z=L} = h(T-T_a)|_{z=L}$$

## LECTURE-22

### 88] Reducing dimensions to solve complex problems in Transport Phenomena

eg:



$$T(x, y, z, t) \Rightarrow T(x, y, z)$$

Steady state  
k is constant

∴ Here:

$$0 = -\nabla \cdot \underline{q}$$

$$= -\left( \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} + \frac{\partial q_z}{\partial z} \right)$$

$$= k \left( \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right)$$

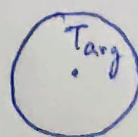
Boundary cond<sup>n</sup>s:

$$z=0, T=T_1$$

$$z=L, T=T_2$$

\* But for approximation:

We look at cross-section and assign an avg. temp. for it



$\Rightarrow T_{avg}(z)$   
thus T reduces to



So we have:

$$(A q_z)|_z - (A q_z)|_{z=z+dz} = 0 \quad (A \text{ is also changing})$$
$$\Rightarrow \frac{d(A q_z)}{dz} = 0$$

Now,  $A = \pi r^2$ , and  $r = r(z)$

{ From this method you get the answer for approximate/avg. temperature  
↓  
the real answer is extremely complex to solve, & will take a very long time }

---