

11.01.2019

Statistical Methods in AI (CSE/ECE 471)



Lecture-5: K-nearest neighbors classifier

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Announcements

- A1 is due **20/1, 11.59 PM**
- **No tutorial this Saturday**



Felicity
2019

SUPERHERO FACTS



Wally West (The Flash) stated he usually stays awake all night and takes micro sleeps during the day when people are blinking. Wish we could do that here at IIIT during lectures. :")

third

Supervised Learning

```
graph TD; A[Supervised Learning] --> B[Classification]; A --> C[Regression]; A --> D[Reinforcement Learning];
```

Classification

Regression

Reinforcement
Learning

So far

- Decision Tree classifier

Motivation

**Show me your
friends and I
will tell you
who you are**

*labeled
examples*

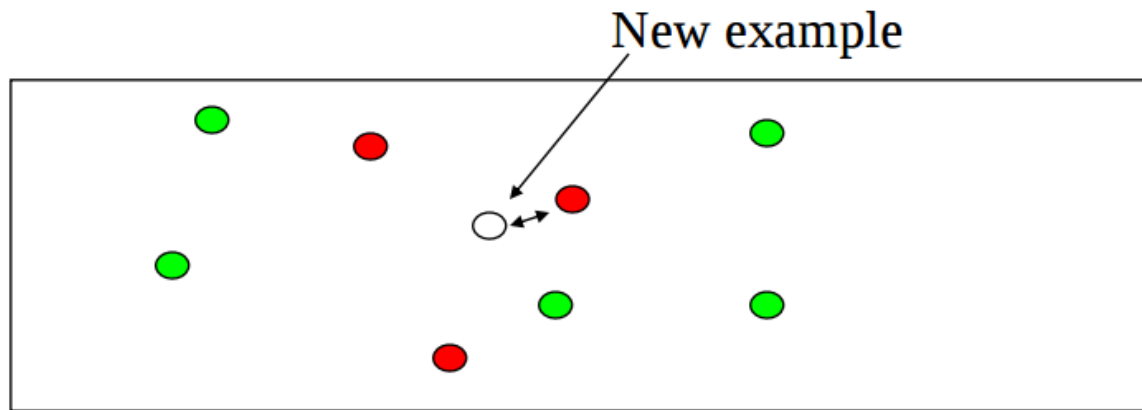
~~friends~~

~~you~~

→ label

Nearest neighbor classifier

- Given a new example \mathbf{x} , find the its closest training example $\langle \mathbf{x}^i, y^i \rangle$ and predict y^i



- How to measure distance – Euclidean (squared):

$$\|\mathbf{x} - \mathbf{x}^i\|^2 = \sum_j (x_j - x_j^i)^2$$

1-NN

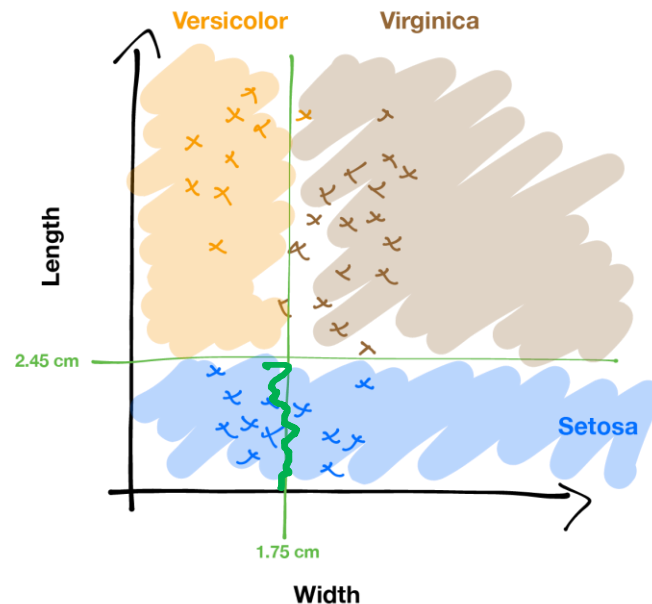
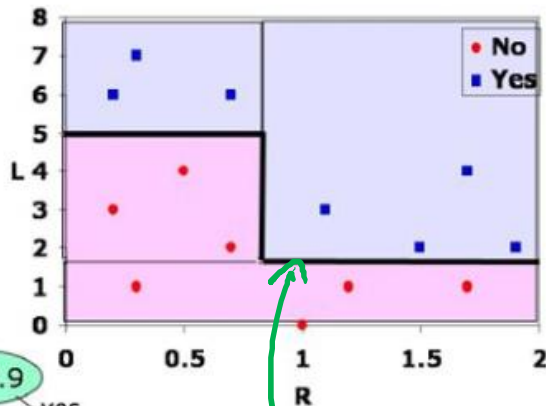
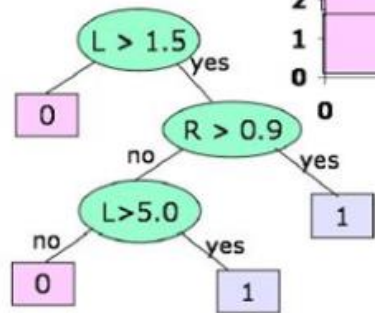
Algorithm:

1. Find example (\mathbf{x}^*, t^*) (from the stored training set) closest to the test instance \mathbf{x} . That is:

$$\mathbf{x}^* = \underset{\mathbf{x}^{(i)} \in \text{train. set}}{\operatorname{argmin}} \quad \text{distance}(\mathbf{x}^{(i)}, \mathbf{x})$$

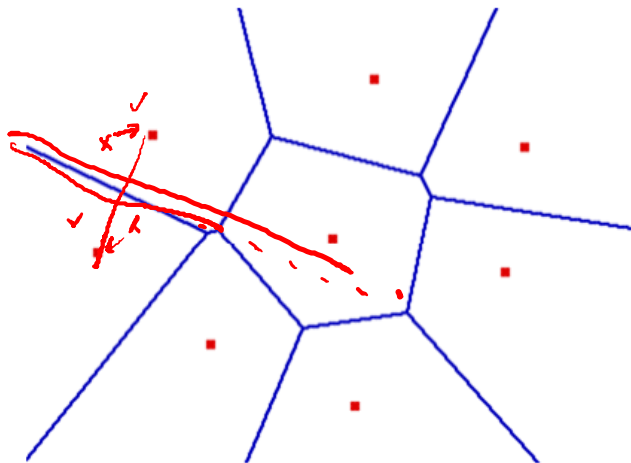
2. Output $y = t^*$

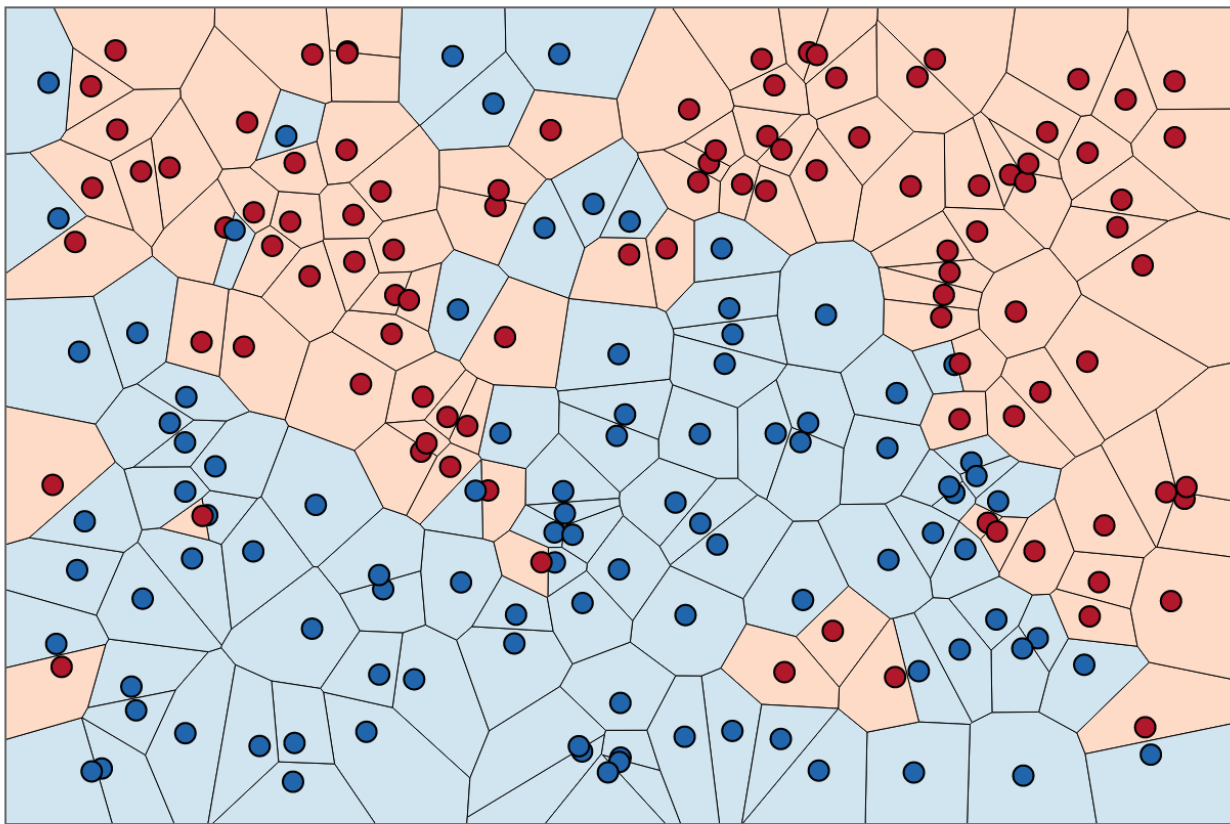
Recap: Decision Boundaries

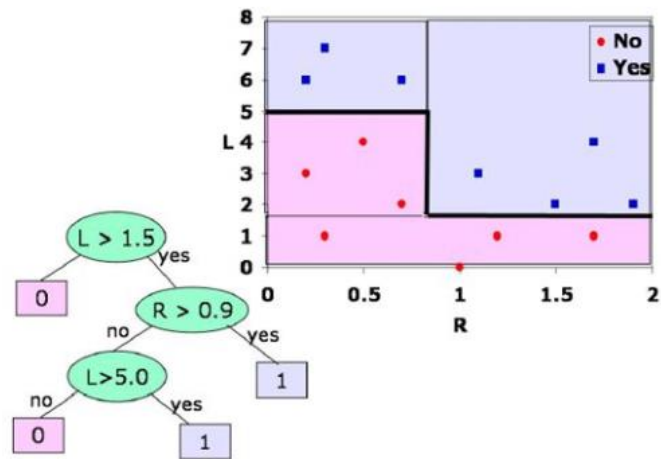
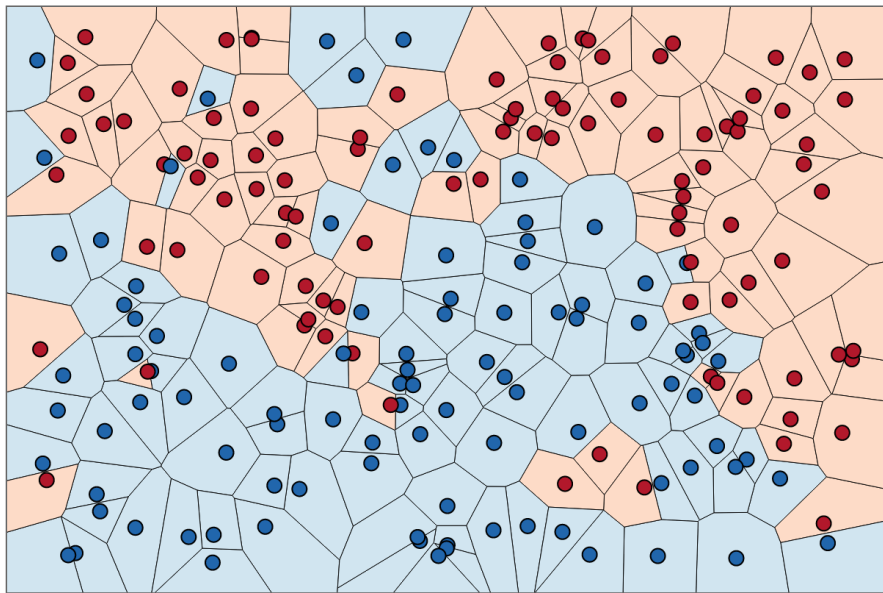
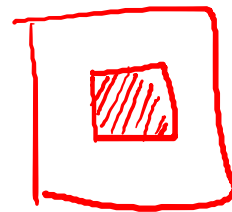


Decision Boundaries: The Voronoi Diagram

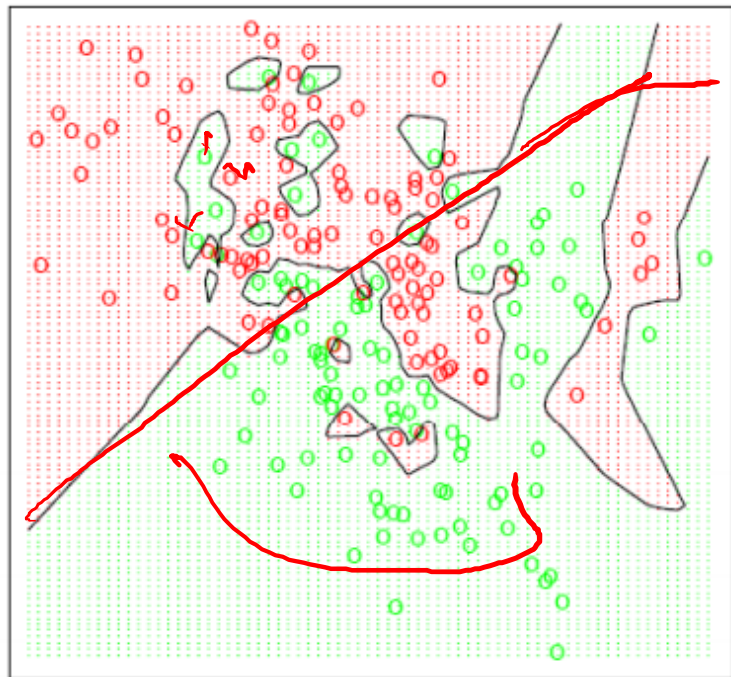
- Given a set of points, a **Voronoi diagram** describes the areas that are nearest to any given point.
- These areas can be viewed as zones of control.







Decision Boundaries

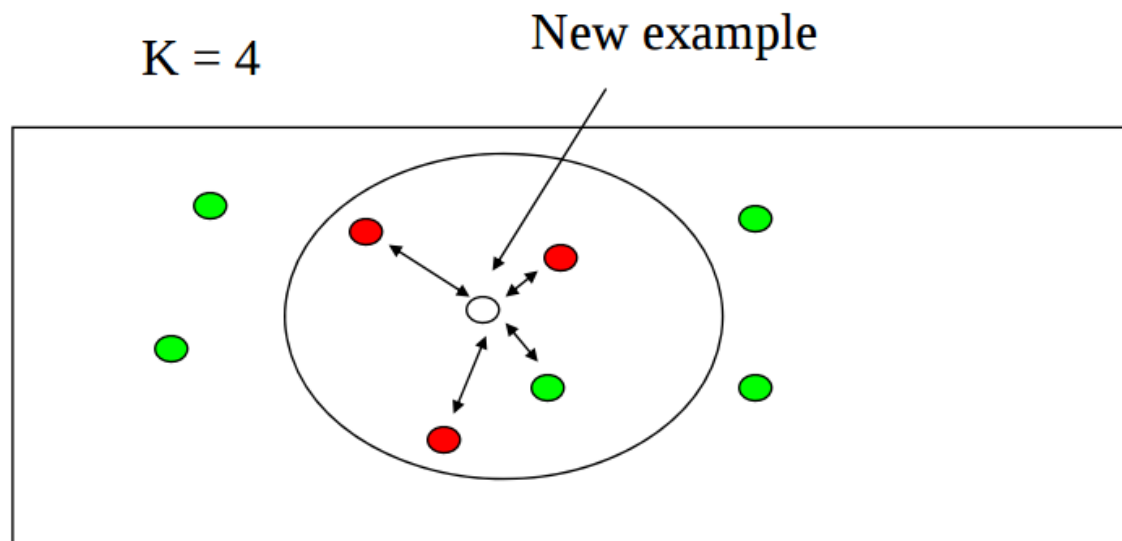


With large number of examples and possible noise in the labels, the decision boundary can become nasty!

We end up overfitting the data

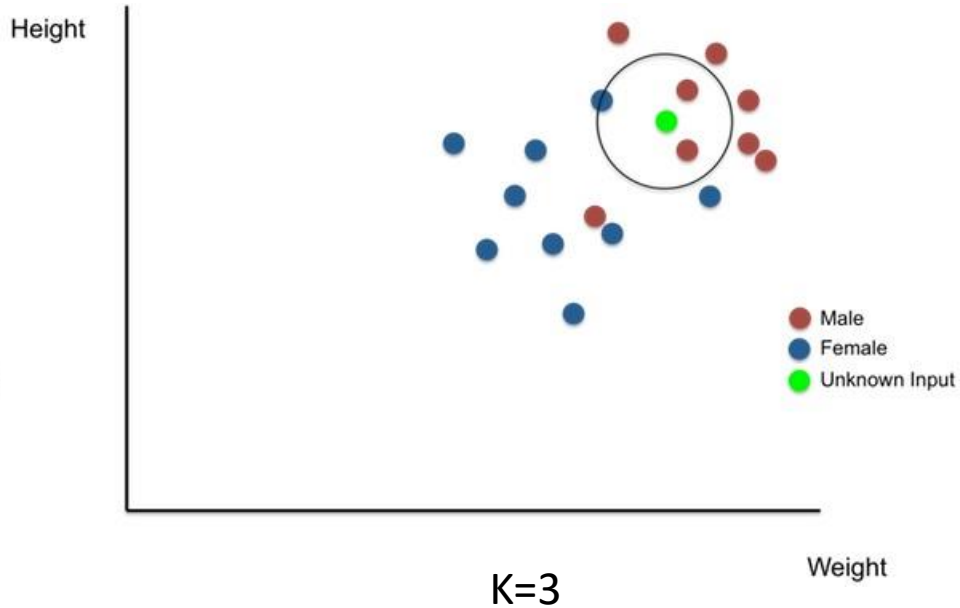
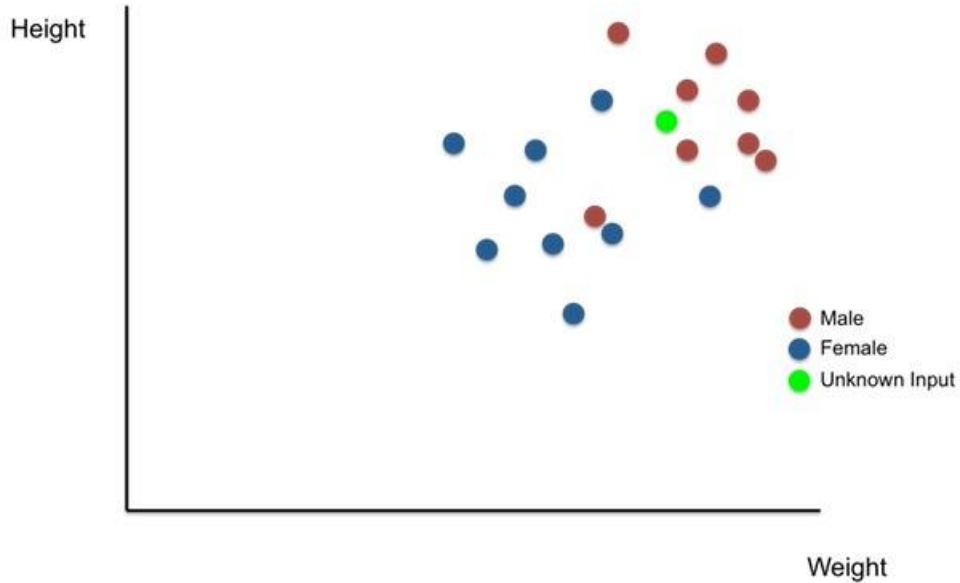
K-Nearest Neighbor

Example:

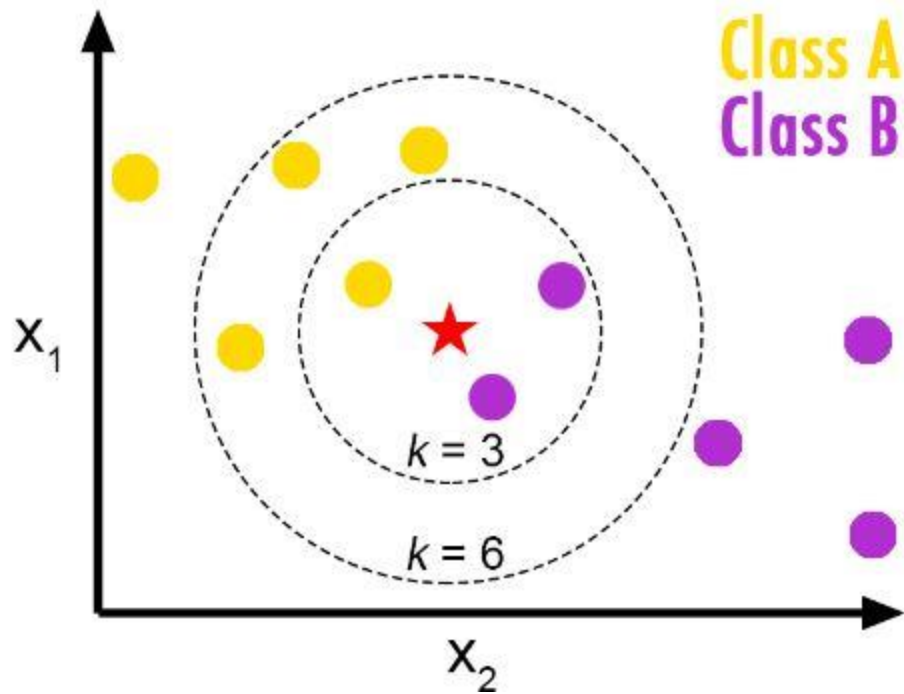


Find the k nearest neighbors and have them vote. Has a smoothing effect. This is especially good when there is noise in the class labels.

k-nearest neighbor classifier



k-nearest neighbor classifier



K is usually an odd number

k-NN

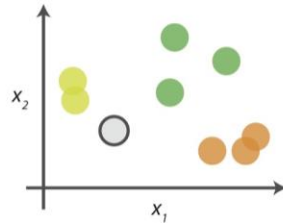
Algorithm (kNN):

1. Find k examples $\{\mathbf{x}^{(i)}, t^{(i)}\}$ closest to the test instance \mathbf{x}
2. Classification output is majority class

$$y = \arg \max_{t^{(z)}} \sum_{r=1}^k \delta(t^{(z)}, t^{(r)})$$

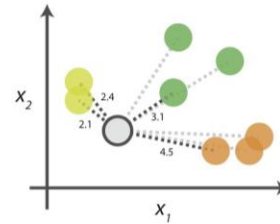
k-NN algorithm in pictures

0. Look at the data



Say you want to classify the grey point into a class. Here, there are three potential classes - lime green, green and orange.

1. Calculate distances



Start by calculating the distances between the grey point and all other points.

2. Find neighbours

Point Distance	
	2.1 → 1st NN
	2.4 → 2nd NN
	3.1 → 3rd NN
	4.5 → 4th NN

Next, find the nearest neighbours by ranking points by increasing distance. The nearest neighbours (NNs) of the grey point are the ones closest in dataspace.

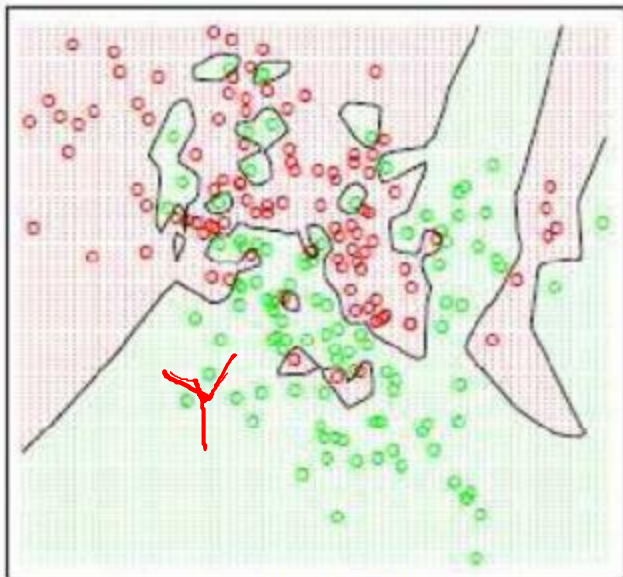
3. Vote on labels

Class	# of votes	
	2	→ Class wins the vote! Point is therefore predicted to be of class .
	1	
	1	

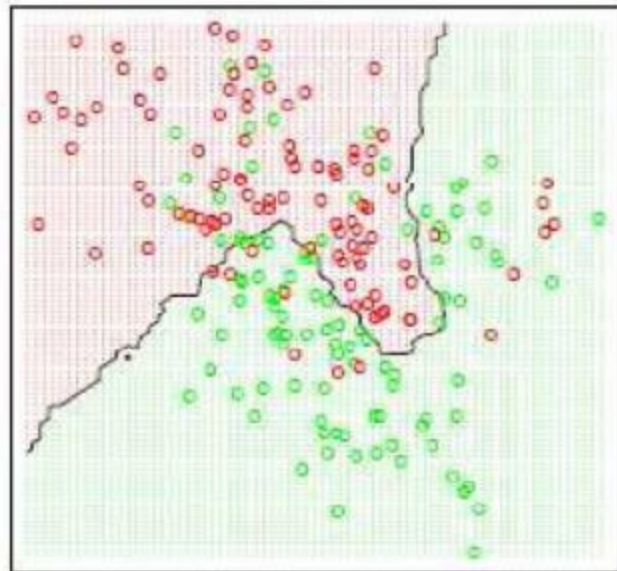
Vote on the predicted class labels based on the classes of the k nearest neighbours. Here, the labels were predicted based on the k=3 nearest neighbours.

Effect of K

K=1



K=15



Figures from Hastie, Tibshirani and Friedman (Elements of Statistical Learning)

Larger k produces smoother boundary effect and can reduce the impact of class label noise.

$\left[\begin{array}{c} \leftarrow d \rightarrow \end{array} \right]$

Complexity of k-NN

N
 \mathbb{R}^d

- Training

- Time:

$O(1)$

$O(1)$

- Space:

$O(Nd)$

$O(Nd)$

- Testing

- Time:

$O(Nd)$

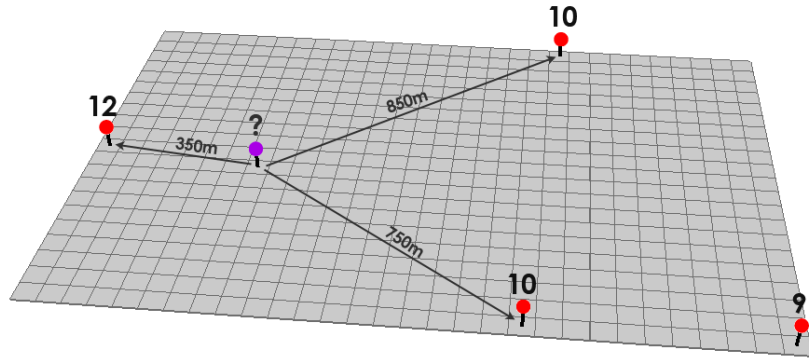
$O(Nd + k \log k)$

- Space:

$O(d)$

$O(kd) ?$

Weighted k-NN

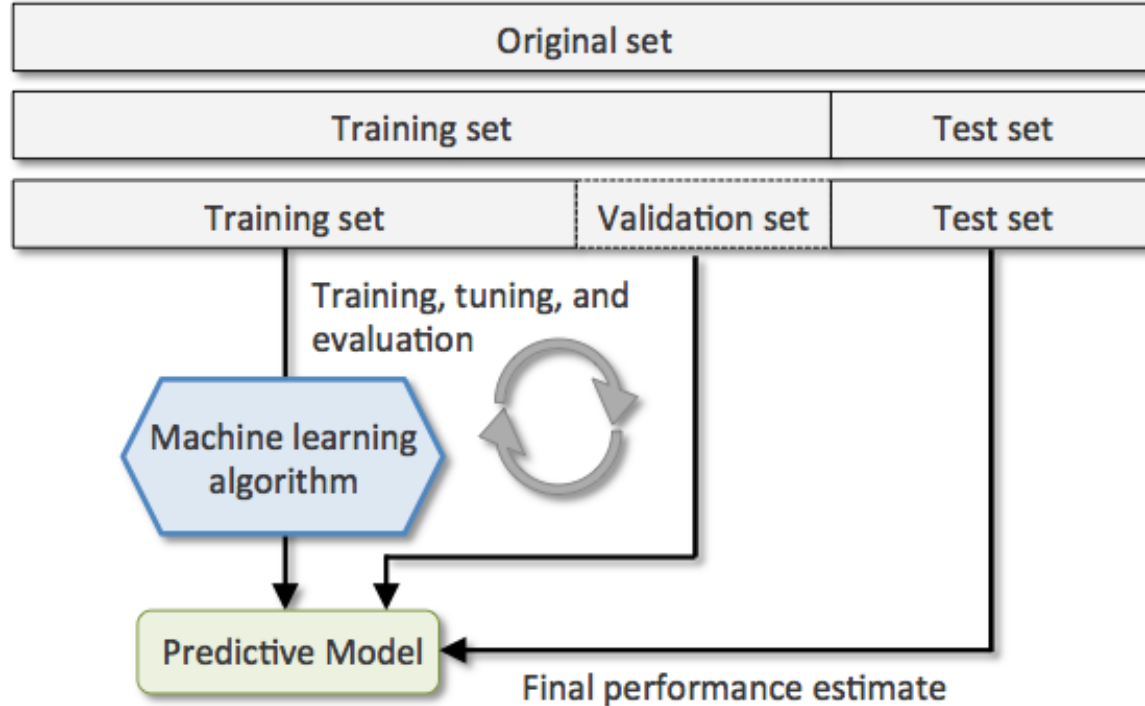


- Helps in case of class skew

How to choose k ?

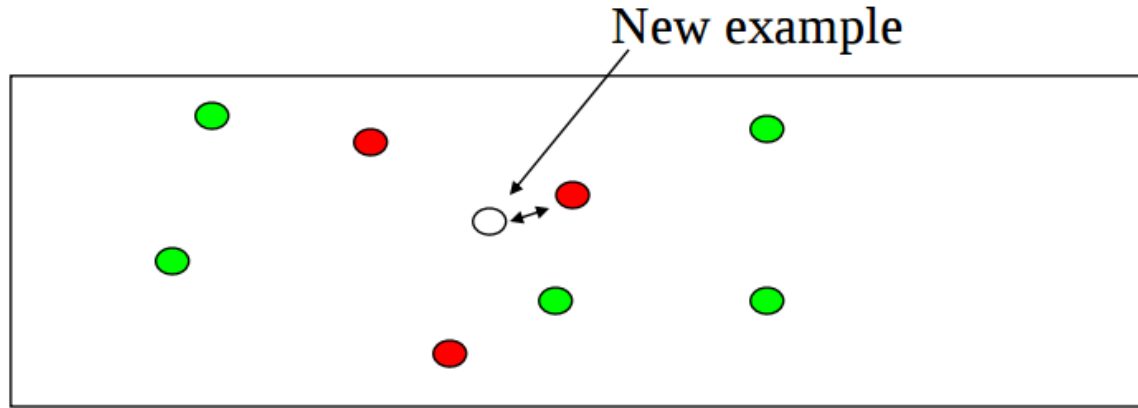


Rule of thumb: $k < \sqrt{n}$, where n is the number of training examples



Nearest neighbor classifier

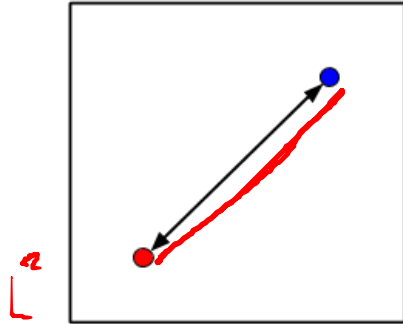
- Given a new example x , find the its closest training example $\langle x^i, y^i \rangle$ and predict y^i



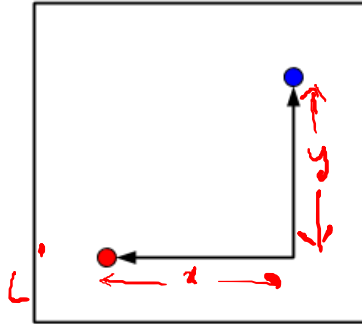
“Closest” →

Distance measures

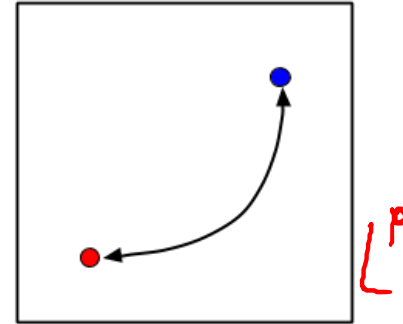
Euclidean



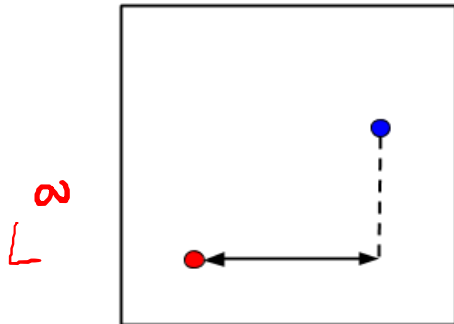
Manhattan



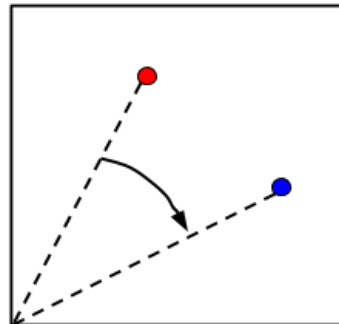
Minkowski



Chebychev



Cosine Similarity



Hamming



$[y_1, y_2, \dots, y_n]$
 $[x_1, x_2, \dots, x_n]$
 m, n

Distance measures

Minkowski distance:

$$d_p = \|x_i - y_i\|_p = \sqrt[p]{\sum_{i=1}^n |x_i - y_i|^p}$$

Chebyshev distance:

$$d_\infty = \|x_i - y_i\|_\infty = \max_{i=1..n} |x_i - y_i|$$

Cosine distance:

$$d_{cos} = 1 - \frac{\sum_{i=1}^n x_i * y_i}{\sqrt{\sum_{i=1}^n (x_i)^2} * \sqrt{\sum_{i=1}^n (y_i)^2}}$$

Mahalanobis
distance:

$$d_M = \sqrt{\sum_{i=1}^n |x_i - y_i|^2 / s_i^2}$$

Euclidean distance:

$$d_2 = \|x_i - y_i\|_2 = \sqrt{\sum_{i=1}^n |x_i - y_i|^2}$$

Manhattan:

$$d_1 = \|x_i - y_i\|_1 = \sum_{i=1}^n |x_i - y_i|$$

Minkowski distance:

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Distance based on
Pearson correlation:

$$d_{corr} = 1 - \frac{\sum_{i=1}^n (x_i - \bar{x}) * (y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} * \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}}$$

Mahalanobis
distance:

$$d_M = \sqrt{\sum_{i=1}^n |x_i - y_i|^2 / s_i^2}$$

Hellinger
distance:

$$d_H = \frac{1}{\sqrt{2}} \sqrt{\sum_{i=1}^n |\sqrt{x_i} - \sqrt{y_i}|^2}$$

Euclidean distance:

$$d_2 = \|x_i - y_i\|_2 = \sqrt{\sum_{i=1}^n |x_i - y_i|^2}$$

Manhattan:

$$d_1 = \|x_i - y_i\|_1 = \sum_{i=1}^n |x_i - y_i|$$

Bray-Curtis
distance:

$$d_{BC} = \sum_{i=1}^n |x_i - y_i| / \sum_{i=1}^n |x_i + y_i|$$

Canberra:

$$d_C = \sum_{i=1}^n |x_i - y_i| / (|x_i| + |y_i|)$$

Properties and Issues with k-NN

- Non-parametric
- ‘Lazy’ learner (c.f. ‘eager’ learner in decision trees)
- Simple baseline (after 0-effort baselines)
- GOOD
 - No training
 - Learns highly non-linear decision boundaries
- BAD
 - Need to keep all training points around
 - Curse of dimensionality ! (suggested #dims < 20)

Properties and Issues with k-NN

- If some attributes (coordinates of \mathbf{x}) have larger **ranges**, they are treated as more important

$[0-1 \quad 2M-3M]$



Properties and Issues with k-NN

- If some attributes (coordinates of \mathbf{x}) have larger **ranges**, they are treated as more important
 - ▶ normalize scale
 - ▶ Simple option: Linearly scale the range of each feature to be, e.g., in range $[0,1]$
 - ▶ Linearly scale each dimension to have 0 mean and variance 1 (compute mean μ and variance σ^2 for an attribute x_j and scale: $(x_j - m)/\sigma$)

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Properties and Issues with k-NN

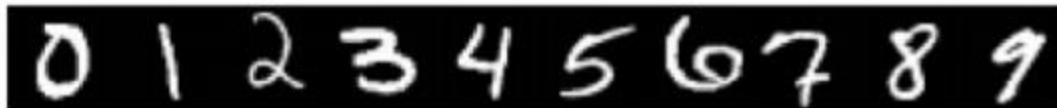
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- **Irrelevant, correlated** attributes add noise to distance measure
 - ▶ eliminate some attributes
 - ▶ or vary and possibly adapt weight of attributes
- **Non-metric** attributes (symbols)
 - ▶ Hamming distance

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Some use cases for k-NN

- Decent performance when lots of data



- Yann LeCunn – MNIST Digit Recognition
 - Handwritten digits
 - 28x28 pixel images: $d = 784$
 - 60,000 training samples
 - 10,000 test samples
- Nearest neighbour is competitive

	Test Error Rate (%)
Linear classifier (1-layer NN)	12.0
K-nearest-neighbors, Euclidean	5.0
K-nearest-neighbors, Euclidean, deskewed	2.4
K-NN, Tangent Distance, 16x16	1.1
K-NN, shape context matching	0.67
1000 RBF + linear classifier	3.6
SVM deg 4 polynomial	1.1
2-layer NN, 300 hidden units	4.7
2-layer NN, 300 HU, [deskewing]	1.6
LeNet-5, [distortions]	0.8
Boosted LeNet-4, [distortions]	0.7

Some use cases for k-NN

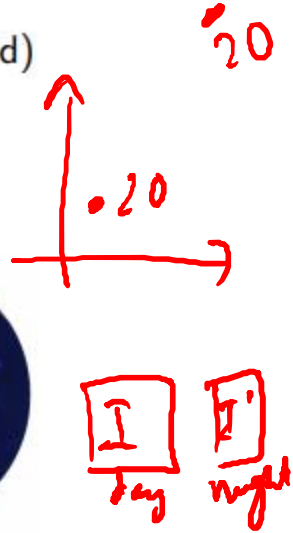
- Problem: Where (e.g., which country or GPS location) was this picture taken?



[Paper: James Hays, Alexei A. Efros. im2gps: estimating geographic information from a single image. CVPR'08. Project page: <http://graphics.cs.cmu.edu/projects/im2gps/>]

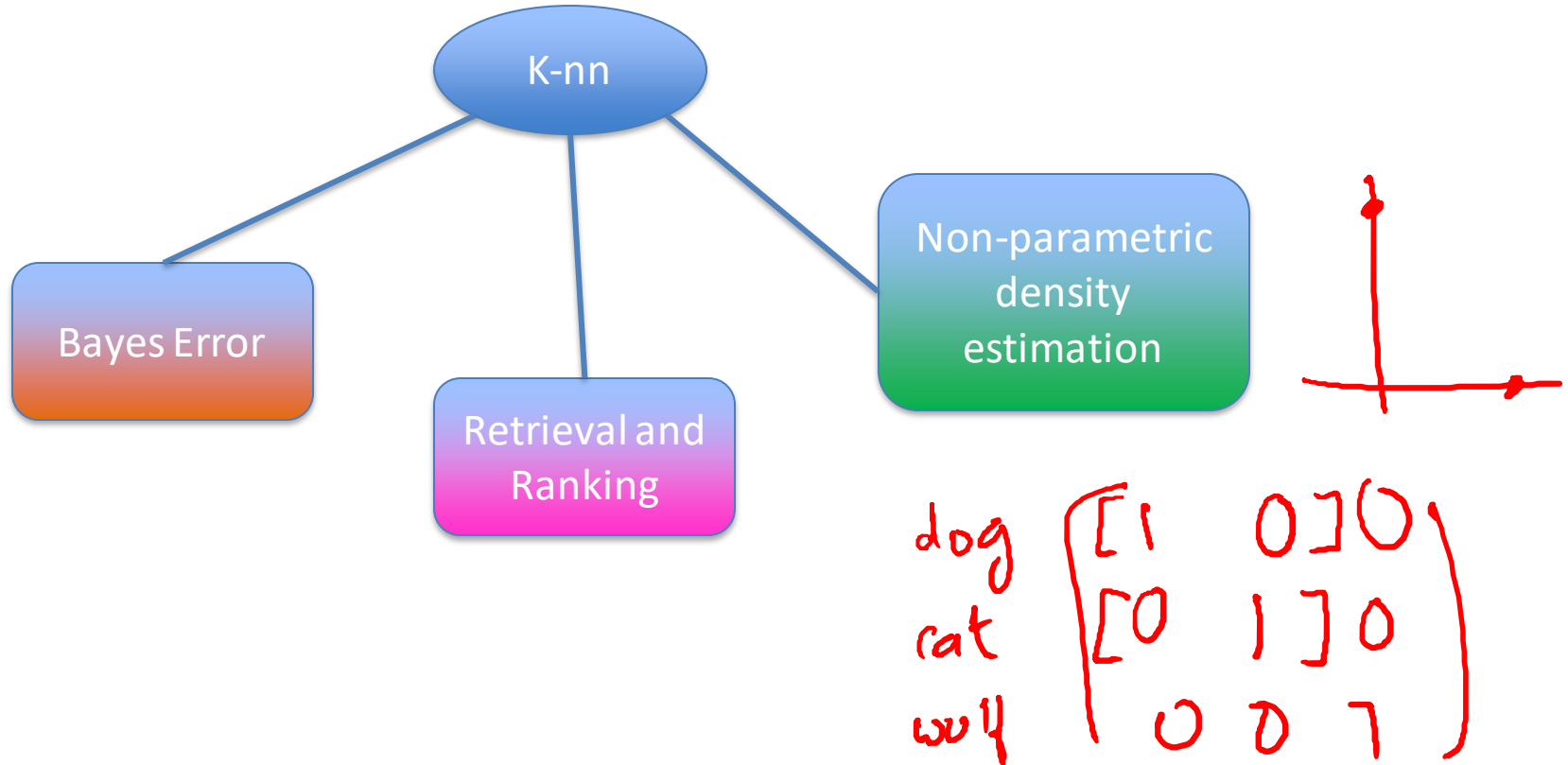
Some use cases for k-NN

- Problem: Where (eg, which country or GPS location) was this picture taken?
 - ▶ Get 6M images from Flickr with gps info (dense sampling across world)
 - ▶ Represent each image with meaningful features
 - ▶ Do kNN (large k better, they use $k = 120$)!



[Paper: James Hays, Alexei A. Efros. im2gps: estimating geographic information from a single image. CVPR'08. Project page: <http://graphics.cs.cmu.edu/projects/im2gps/>]

Related topics



$$\text{PROBABILITY} = \frac{\text{EVENT}}{\text{OUTCOMES}}$$



Data – a probability-based perspective

- The basis for Statistical Learning Theory



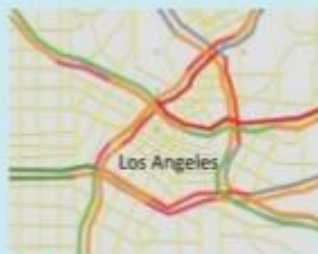
Then we observe candies drawn from some bag: ● ● ● ● ● ● ● ● ● ●

- Domain described by random variables (r.v.)
 - $X = \{\text{apple, grape}\}$
 - $b_i \in [1,5]$
- **Data = Instantiation of some or all r.v.'s in the domain**

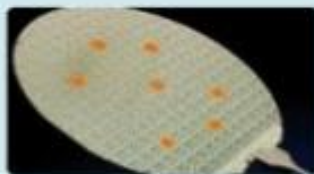
Uncertainty arises from many sources

Process Uncertainty

Processes contain
"randomness"



Uncertain travel times



Semiconductor yield

Data Uncertainty

Data input is uncertain



GPS Uncertainty



Testimony



{Paris Airport}

Ambiguity



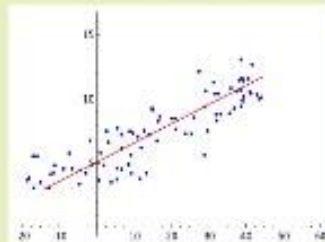
Contaminated?
Rumors

{John Smith, Dallas}
{John Smith, Kansas}

Conflicting Data

Model Uncertainty

All modeling is approximate



Fitting a curve to data



Forecasting a hurricane
(www.noaa.gov)

Data: a probabilistic perspective

Output

	DBAName	AKAName	Address	City	State	Zip
t1	John Veliotis Sr.	Johnnyo's	3465 S Morgan ST	Chicago	IL	60608
t2	John Veliotis Sr.	Johnnyo's	3465 S Morgan ST	Chicago	IL	60609
t3	John Veliotis Sr.	Johnnyo's	3465 S Morgan ST	Chicago	IL	60609
t4	Johnnyo's	Johnnyo's	3465 S Morgan ST	Cicago	IL	60608

Conflicts

Does not obey data distribution

Conflict



Proposed Cleaned Dataset

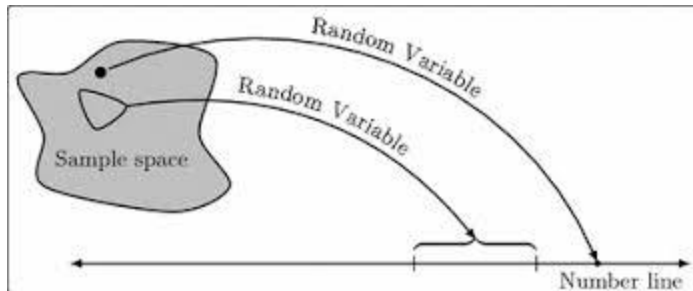
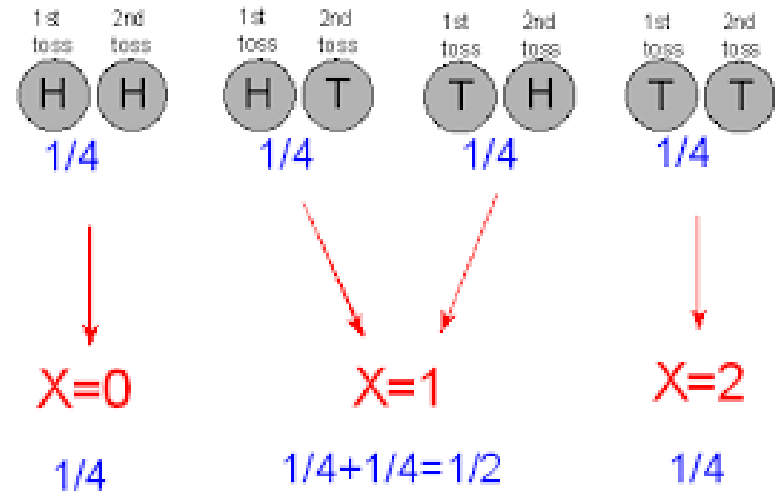
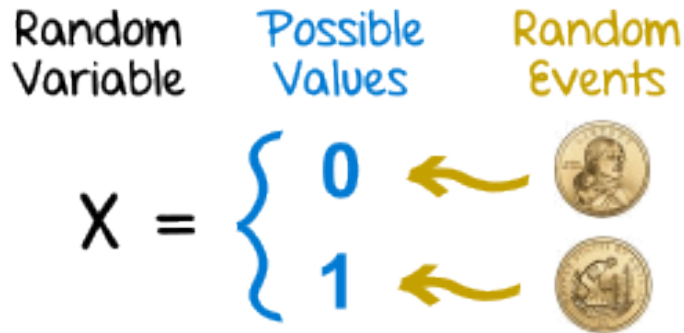
	DBAName	Address	City	State	Zip
t1	John Veliotis Sr.	3465 S Morgan ST	Chicago	IL	60608
t2	John Veliotis Sr.	3465 S Morgan ST	Chicago	IL	60608
t3	John Veliotis Sr.	3465 S Morgan ST	Chicago	IL	60608
t4	John Veliotis Sr.	3465 S Morgan ST	Chicago	IL	60608

Marginal Distribution of Cell Assignments

Cell	Possible Values	Probability
t2.Zip	60608	0.84
	60609	0.16
t4.City	Chicago	0.95
	Cicago	0.05
t4.DBAName	John Veliotis Sr.	0.99
	Johnnyo's	0.01

Random Variables

R.V. = A numerical value from a random experiment



Random variables

- A **discrete random variable** can assume a countable number of values.
 - Number of steps to the top of the Eiffel Tower*



Random variables

- A **discrete random variable** can assume a countable number of values.
 - Number of steps to the top of the Eiffel Tower*
- A **continuous random variable** can assume any value along a given interval of a number line.
 - The time a tourist stays at the top once s/he gets there



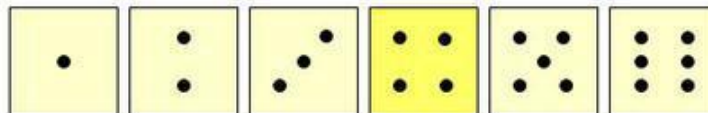
*Believe it or not, the answer ranges from 1,652 to 1,789. See [Great Buildings](#)



Discrete Random Variables

- Can only take on a countable number of values

Examples:



- Roll a die twice**

Let X be the number of times 4 comes up
(then X could be 0, 1, or 2 times)

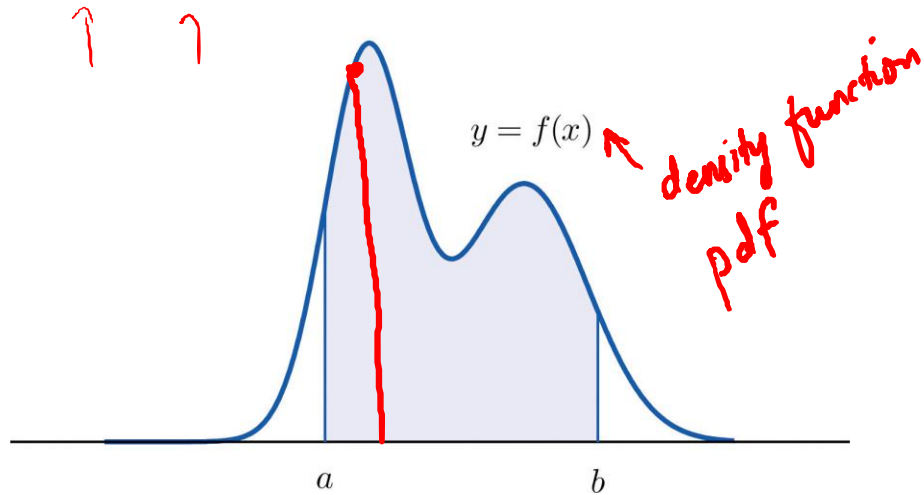
- Toss a coin 5 times.**

Let X be the number of heads
(then $X = 0, 1, 2, 3, 4, \text{ or } 5$)

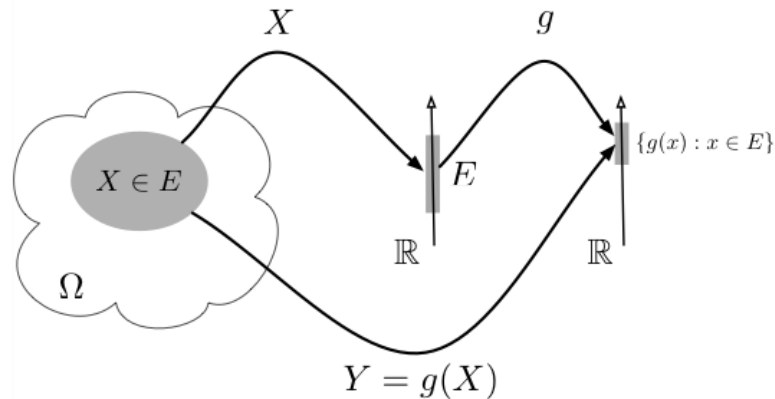


Continuous random variable

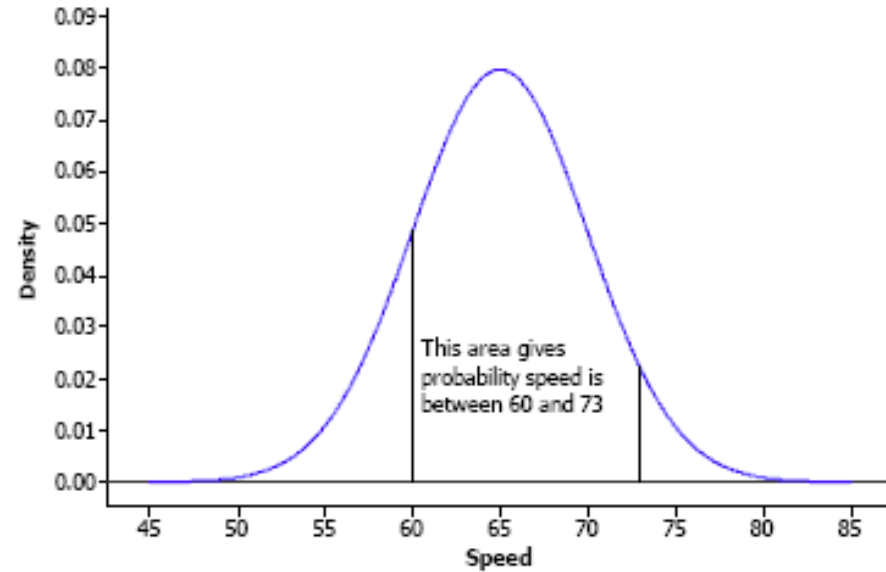
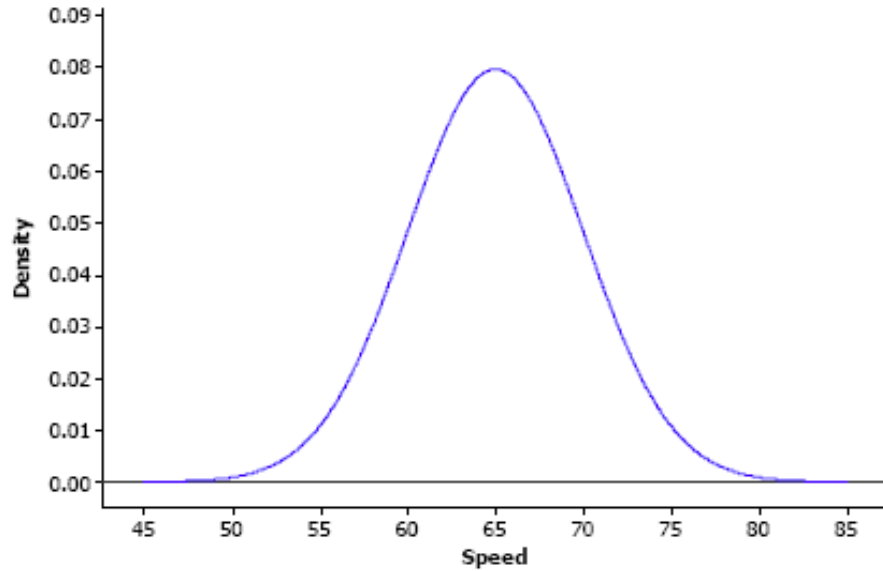
$P(a < X < b) = \text{area of shaded region}$



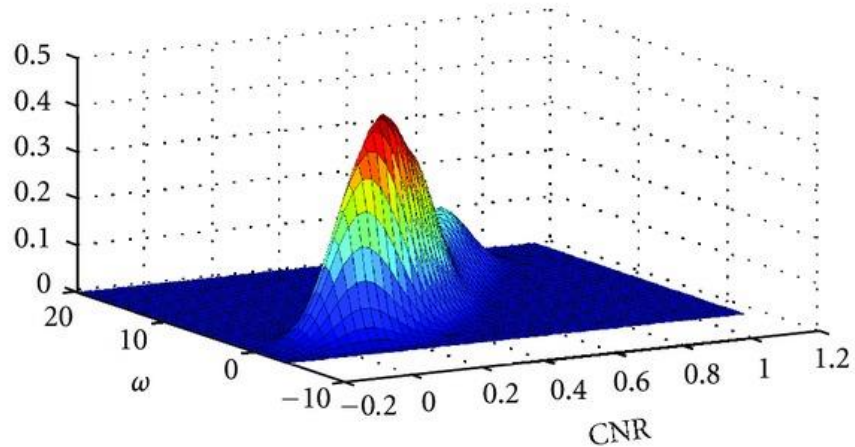
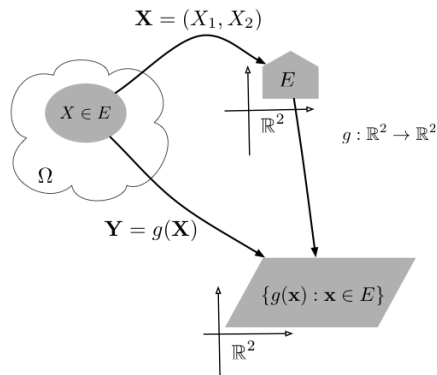
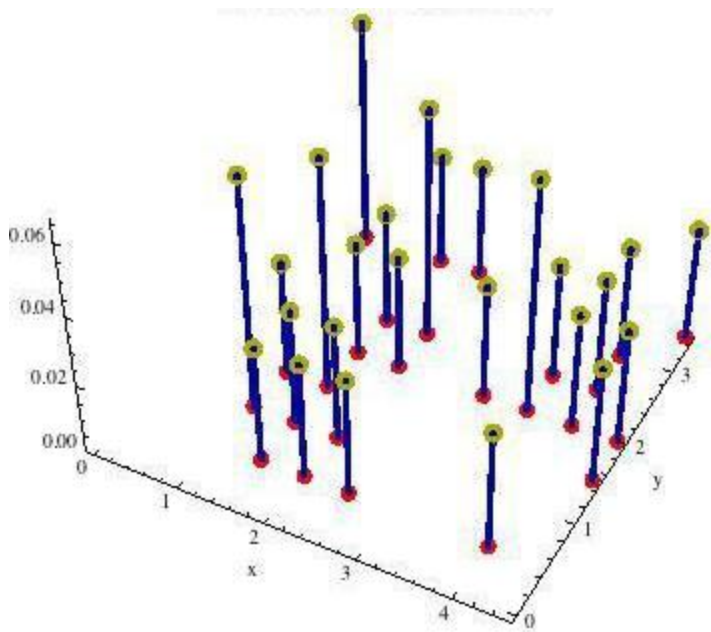
$$P(Y = 0.2) = 0$$



Continuous random variable



Random vectors



References and Reading

- https://en.wikipedia.org/wiki/K-nearest_neighbors_algorithm
- Euclidean v/s Cosine distance
 - Code example: <https://cmry.github.io/notes/euclidean-v-cosine>
 - <https://stackoverflow.com/a/53175061>
 - <https://www.quora.com/Why-cosine-is-better-than-Euclidean-in-high-dimensional-data-as-in-text-documents>