



Boids

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What are Boids?

Bird-oid Objects

Flocking Rules

Boids: Bird-oid Objects

- Artificial life program by Craig Reynolds
- Simulates flocking behavior of birds
- Used in movies (*Batman Returns* (1992)), video games (*Half-Life*), teams of robots, swarm robotics, optimizing tasks (Cui, Zhihua; Shi, Zhongzhi (2009). "Boid particle swarm optimisation")

Flocking Rules

- Separation
 - Boids keep a minimum distance from each other
 - Steer away from each other if they are too close
- Alignment
 - Boids align themselves to each other
 - Steer towards the average direction other local boids move in
- Cohesion
 - Boids stay together
 - Steer towards the average position of other local boids

Motivation and Goals

Reproduce Craig Reynolds' results

Observe emergent behavior

What did we want to achieve?

- Reproduce Craig Reynolds' results
- Implement a way to adjust the flocking rules and observe how they influence the flocking
- Add additional features, and observe how the flocking behavior changes

Exploring emergent behavior:

- Flocks form, move together
- Flocks split and reform after avoiding obstacles

Implementation

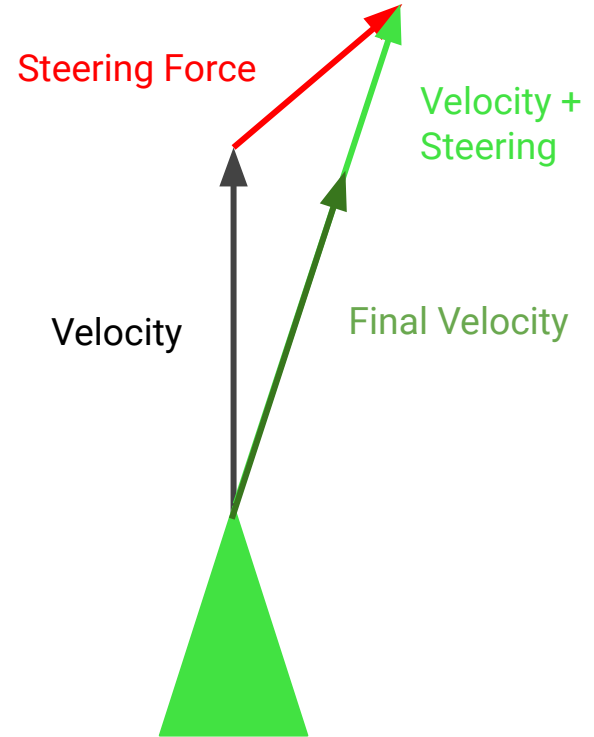
Steering

Pygame

Actor, boid and predator forces

Steering

- Boids start with random position and velocity
- Outside influences apply “steering forces” to the boid
 - E.g. flocking forces, obstacle avoidance, fleeing from predators
- Sum of all these forces is added to the velocity vector
- Magnitude of the velocity vector is capped to the boid’s maximum speed

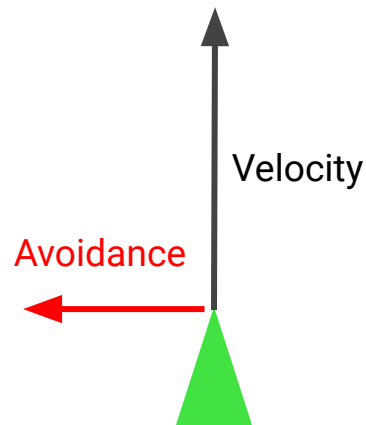


Pygame: Main Simulation Loop

- Made for Game Development but works great for interactive simulations
 - Easy to implement sliders, buttons
 - Every frame is one timestep in the simulation. Pygame calculates dt for us: the time in milliseconds between frames
1. Pygame events are handled; buttons and sliders
 2. Update dt and use it in our simulation step:
 - Get boid neighbors
 - Get predators/prey
 - Update forces, velocities and positions
 3. Draw visuals on the canvas and update the display

Actor Forces

- Actors: both predators and boids are “actors”
 - All actors calculate obstacle avoidance. Two types:
 - Circle obstacle (easy to implement)
 - Wall obstacles (more difficult)



Boid Forces

- Flocking forces
 - First find all neighbors
 - Separation: find neighbors within separation radius
 - Alignment: find average velocity of flock
 - Cohesion: find average position of flock
- Fleeing force
 - Find closest predator
 - Predict predator's future position using its current velocity
 - Steer away from that position

Predator Forces

- Pursuit Force
 - Find closest boid
 - Calculate future position using it's current velocity
 - Steer towards that position

Demonstration

Difficulties

And how we solved them

Visualization

Version control

Jittering of the boids

Visuals: Live interactive animation

Matplotlib +

- Familiar
- Wide use in science
- Focus on plotting data
- (Static and animated plotting)

=> Video demonstration

Pygame -

- Unfamiliar
- Less known for simulations
- Not as comprehensive (smaller team, less features)
- (probably sucks for static plotting)

Visuals: Live interactive animation

Matplotlib -

- No advice on *interactive live* animations
- Complicated to make this work
- IDE problems
 - Python 3.x version matters for *live* animations

Pygame +

- Made for live user interactions
- By design lightweight & easy to use, even at low levels
- Easy to learn, good docs
- Even matplotlib backends are easily integrated (any visuals)
- ...just works (even Win95)

Resolution: switching to pygame & adapt

Version control

- git vcs (GitHub)
- Visualization challenges made things worse & delayed progress
- Pycharm:
 - Built-in vcs can be confusing
 - Hidden & environment files caused merge conflicts
 - Failed resolution: CodeWithMe parallel coding & git don't agree
 - Adapting boids' locations to pygame's pixel based system

Resolutions:

multiple 'main' files, coordinate merging, swap dev roles

Jittering of the boids (emergent bug)

- Appearance of glitching mid-air, caused by frame-to-frame change of direction

=> video demonstration

Resolution:

Smooth animation (rotation) over last few frames

Conclusions

What did we accomplish/learn?

Emergent behavior

Further research

Emergence: intuitive & qualitative analysis

- Do the boids look like actual swarms? **Yes**
- Did we reproduce emergent group behavior? Does the entity (flock) have properties its parts (boids) do not have on their own? **Yes**
(<https://en.wikipedia.org/wiki/Emergence>)
 - Moving 'through'/around an obstacle makes no sense individually
 - Predator avoidance when in a group looks quite realistic

=> These observations imply locally adaptive behavior on the individual level is *sufficient* for the flocking appearance and seemingly coordinated/orchestrated movement at the swarm level.

Emergence: quantitative analysis

- How can we quantify this 'flocking appearance'? What is 'seemingly coordinated movement'?
- How to measure 'swarminess'? How to identify 'emergence' quantitatively?

=> efforts to answer these questions have begun recently (2016 onwards)

Further research

- Predator avoidance / evasive maneuvers
- Pack hunting
- How do swarms form?
- How do swarms start and stop motion? Parallels to cell biology (cell to cell communication, oscillatory behavior)?
- How do swarming species differ?

Sources

- <https://www.red3d.com/cwr/boids/>
(the basic flocking behavior)
- <https://www.cs.toronto.edu/~dt/siggraph97-course/cwr87/>
(Reynolds' paper from 1987 "Herds, Flocks, and Schools: A Distributed Behavioral Model")
- <https://www.red3d.com/cwr/steer/gdc99/>
(Reynolds' paper from 1999 "Steering Behaviors For Autonomous Characters")
- <https://www.red3d.com/cwr/>
(Reynolds' homepage with portrait)
- <https://gamedevelopment.tutsplus.com/series/understanding-steering-behaviors--gamedev-12732>
(more recent take on the algorithms with programming examples, written by Fernando Bevilacqua ([Homepage](#)))
- <https://matplotlib.org/>
- <https://www.pygame.org/docs/>
- <https://pygamewidgets.readthedocs.io/en/latest/>
(user interactions like sliders and buttons)

Sources

- <https://en.wikipedia.org/wiki/Emergence>
“In [philosophy](#), [systems theory](#), [science](#), and [art](#), **emergence** occurs when an entity is observed to have properties its parts do not have on their own, properties or behaviors which emerge only when the parts interact in a wider whole.” [source]:
 - <https://plato.stanford.edu/archives/spr2012/entries/properties-emergent/>
- https://link.springer.com/chapter/10.1007/978-3-319-41000-5_12
(quantifying swarming behaviour, 2016, abstract tackles my questions spot-on)
- Other robotics papers start to emerge (2018 onwards)