

A Type Theory with Native Homotopy Universes

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The Programmers' Credo

- The Programmers' Credo

- Introduction
- Logical Relations
- Not a New Idea?
- Past Work
- TDLR
- Propositions
- Sets
- Groupoids
- Properties of Equality
- Function types
- Path Substitution
- KIPLING
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- Results Verified
- Meaning Explanation for Homotopy Types?
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“We do these things, not because they are easy, but because we thought they would be easy.”

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Introduction

Systems with univalence axiom:

- Book-HoTT
 - Univalence is just an axiom (constant)
 - Computation with univalence gets stuck.
- Cubical type theory
 - Not all the definitional equalities we want:

$$\text{transp}^i(pi)(\text{transp}^i(qi)a) \not\equiv \text{transp}^i((p \circ q)i)a$$

$$\text{transp}^i Aa \not\equiv a \quad (i \notin A)$$

Idea (Coquand [Coq11]): Define equality on each type by induction on the type structure.

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Logical Relations

Introduced by Gandy [Gan56].

The name 'logical relation' has been used for several different families of equivalence relations on the terms of A defined by recursion on A .

$$f \sim_{A \rightarrow B} g \stackrel{\text{def}}{=} \forall x, y : A. (x \sim_A y \Rightarrow fx \sim_B gy)$$

$$p \sim_{A \times B} q \stackrel{\text{def}}{=} \pi_1(p) \sim_A \pi_1(q) \wedge \pi_2(p) \sim_B \pi_2(q)$$

$$A \sim_{\mathcal{U}} B \stackrel{\text{def}}{=} A \simeq B$$

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Not a New Idea?

Recall Martin-Löf's meaning explanation [ML82]:

A canonical type A is defined by prescribing how a canonical object of type A is formed as well as how two equal canonical objects of type A are formed.

Suggests that equality is supposed to vary with the type.

Past Work

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Several attempts:

- Observational Type Theory (OTT) [AMS07] A 1-dimensional theory (sets and propositions)
- 2-dimensional type theory [LH12] A 2-dimensional type theory with equality reflection
- $\lambda \simeq$ [Pol14] An inconsistent system with $*$: $*$
- PHOML [ABC16] A 1-dimensional theory with univalence

Attempts to do this beyond dimension 2 end up in 'setoid hell'

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Presenting TDLR (pronounced 'toddler') — Two Dimensional Logical Relation theory. (Previously called $\lambda \simeq_2$)

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Presenting TDLR (pronounced 'toddler') — Two Dimensional Logical Relation theory. (Previously called $\lambda \simeq_2$)

Idea: A disciplined approach to creating a type theory by:

1. Using a proof assistant
2. Formalising syntax and semantics in groupoids simultaneously

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Work in progress — rules of deduction still in flux

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Idea: A disciplined approach to creating a type theory by:

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Work in progress — rules of deduction still in flux

Four judgement forms:

- $\Gamma \vdash_3 G \text{ gpd} \text{ — } G \text{ is a groupoid}$
- $\Gamma \vdash_2 A : G \text{ — } A \text{ is an object of groupoid } G$
- $\Gamma \vdash_1 t : A \text{ — } t \text{ is an element of set } A$
- $\Gamma \vdash_0 \delta : t \text{ — } \delta \text{ is a proof of proposition } t$

Propositions

Let there be propositions.

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Propositions

Let there be propositions. Let propositions have proofs.

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Propositions

Let there be propositions. Let propositions have proofs. Given propositions ϕ and ψ , let there be a proposition $\phi \Leftrightarrow \psi$

$$\frac{\Gamma, p : \phi \vdash \delta : \psi \quad \Gamma, q : \psi \vdash \epsilon : \phi}{\Gamma \vdash \text{univ}_0(p.\delta, q.\epsilon) : \phi \Leftrightarrow \psi}$$

$$\frac{\Gamma \vdash \delta : \phi \Leftrightarrow \psi \quad \Gamma \vdash \epsilon : \psi}{\Gamma \vdash \delta^+ \epsilon : \psi}$$

$$\frac{\Gamma \vdash \delta : \phi \Leftrightarrow \psi \quad \Gamma \vdash \epsilon : \psi}{\Gamma \vdash \delta^- \epsilon : \phi}$$

Sets

Let there be sets.

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Let there be sets.

Let sets have elements.

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Let there be sets.

Let sets have elements.

Given $a, b : S$, let there be a proposition $a =_S b$ and proof $r(a) : a =_S a$.

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Let there be sets.

Let sets have elements.

Given $a, b : S$, let there be a proposition $a =_S b$ and proof $r(a) : a =_S a$.

Given sets S, T , let there be a set $S \simeq T$ of *bijections*.

$$\frac{\Gamma, x : S \vdash t : T \quad \Gamma, y : T \vdash s : S \quad \Gamma, x : S, y : T \vdash \delta : (x =_S s) \Leftrightarrow (t =_T y)}{\Gamma \vdash \text{univ}_1(x.t, y.s, xy.\delta) : S \simeq T}$$
$$\frac{\Gamma \vdash e : S \simeq T \quad \Gamma \vdash s : S}{\Gamma \vdash e^+ s : T}$$
$$\frac{\Gamma \vdash e : S \simeq T \quad \Gamma \vdash t : T}{\Gamma \vdash e^- t : S}$$
$$\frac{\Gamma \vdash e : S \simeq T \quad \Gamma \vdash s : S \quad \Gamma \vdash t : T}{\Gamma \vdash e^-(s, t) : (s = e^- t) \Leftrightarrow (e^+ s = t)}$$

Groupoids

Let there be groupoids.

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Let there be groupoids.

Let groupoids have objects.

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Groupoids

Let there be groupoids.

Let groupoids have objects.

Given $a, b : G$, let there be a set $a =_G b$ and element $r(a) : a =_G a$.

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Let there be groupoids.

Let groupoids have objects.

Given $a, b : G$, let there be a set $a =_G b$ and element $r(a) : a =_G a$.

Given groupoids G, H , let there be a groupoid $G \simeq H$.

$$\frac{\Gamma, x : G \vdash t : H \quad \Gamma, y : H \vdash s : G \quad \Gamma, x : G, y : H \vdash e : (x =_G s) \simeq (t =_H y)}{\Gamma \vdash \text{univ}_2(x.t, y.s, xy.e) : G \simeq H}$$

$$\frac{\Gamma \vdash \phi : G \simeq H \quad \Gamma \vdash s : G}{\Gamma \vdash \phi^+ s : H}$$

$$\frac{\Gamma \vdash \phi : G \simeq H \quad \Gamma \vdash t : H}{\Gamma \vdash \phi^- t : G}$$

$$\frac{\Gamma \vdash \phi : S \simeq T \quad \Gamma \vdash s : S \quad \Gamma \vdash t : T}{\Gamma \vdash \phi^-(s, t) : (s =_G \phi^- t) \simeq (\phi^+ s = t)}$$

Properties of Equality

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Define symmetry:

$$\frac{\Gamma \vdash \delta : \phi \Leftrightarrow \psi}{\Gamma \vdash \text{sym}_0(\delta) \stackrel{\text{def}}{=} \text{univ}_0(p.\delta^- p, p.\delta^+ p) : \psi \Leftrightarrow \phi}$$

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Properties of Equality

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$$\frac{\Gamma \vdash e : S \simeq T}{\Gamma \vdash \text{sym}_1(e) \stackrel{\text{def}}{=} \text{univ}_1(x.e^- x, y.e^+(y), xy.\text{sym}_0(e^=(x, y))) : T \simeq S}$$

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Properties of Equality

Define symmetry:

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$$\frac{\Gamma \vdash e : S \simeq T}{\Gamma \vdash \text{sym}_1(e) \stackrel{\text{def}}{=} \text{univ}_1(x.e^- x, y.e^+(y), xy.\text{sym}_0(e^=(x, y))) : T \simeq S}$$

$$\frac{\Gamma \vdash e : G \simeq H}{\Gamma \vdash \text{sym}_2(e) \stackrel{\text{def}}{=} \text{univ}_2(x.e^- x, y.e^+ y, xy.\text{sym}_1(e^=(x, y))) : H \simeq G}$$

Can define transitivity.

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Given sets S, T , there is a set $S \rightarrow T$ of *functions*:

$$\frac{\Gamma, x : S \vdash t : T}{\Gamma \vdash \lambda x. t : S \rightarrow T} \quad \frac{\Gamma \vdash f : S \rightarrow T \quad \Gamma \vdash s : S}{\Gamma \vdash f s : T}$$

$$(f =_{S \rightarrow T} g) \equiv (\forall x, y : S. x =_S y \rightarrow f x =_T g y)$$

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Given sets S, T , there is a set $S \rightarrow T$ of *functions*:

$$\frac{\Gamma, x : S \vdash t : T}{\Gamma \vdash \lambda x. t : S \rightarrow T} \quad \frac{\Gamma \vdash f : S \rightarrow T \quad \Gamma \vdash s : S}{\Gamma \vdash f s : T}$$

$$(f =_{S \rightarrow T} g) \equiv (\forall x, y : S. x =_S y \rightarrow f x =_T g y)$$

Given groupoids G, H , there is a groupoid $G \rightarrow H$ of *groupoid functors* and *natural isomorphisms*

$$\frac{\Gamma, x : G \vdash t : H}{\Gamma \vdash \lambda x. t : G \rightarrow H} \quad \frac{\Gamma \vdash f : G \rightarrow H \quad \Gamma \vdash s : G}{\Gamma \vdash f s : H}$$

$$(f =_{G \rightarrow H} g) \equiv (\forall x, y : G. x =_G y \rightarrow f x =_H g y)$$

Path Substitution

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Given $a : A$, $e : A \simeq B$ and $b : B$, write $a \sim_e b$ for $a =_A e^-(b)$.

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Path Substitution

Given $a : A$, $e : A \simeq B$ and $b : B$, write $a \sim_e b$ for $a =_A e^-(b)$.

Given substitutions $\rho, \sigma : \Gamma \rightarrow \Delta$, a *path substitution* or *path* τ from ρ to σ $\tau : \rho \sim \sigma$, is given by:

- for every $x : T$ in Δ , a term $\Gamma \vdash \tau(x) : \rho(x) \sim_{T[[\tau]]} \sigma(x)$

Simultaneously, given $\tau : \rho \sim \sigma$ and $\Delta \vdash t : T$, define $\Gamma \vdash t[[\tau]] : t[\rho] \sim_{T[[\tau]]} t[\sigma]$.

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McBride [McB10] introduced KIPLING:

- A standard approach: syntax first, then semantics

data Context : Set

$\llbracket _ \rrbracket C : \text{Context} \rightarrow \text{Set}$

data Type : Context \rightarrow Set

$\llbracket _ \rrbracket T : \forall \{\Gamma\} \rightarrow \text{Type } \Gamma \rightarrow \llbracket \Gamma \rrbracket C \rightarrow \text{Set}$

data Term : $\forall \Gamma \rightarrow \text{Type } \Gamma \rightarrow \text{Set}$

$\llbracket _ \rrbracket t : \forall \{\Gamma\} \{A\} \rightarrow \text{Term } \Gamma A \rightarrow (\gamma : \llbracket \Gamma \rrbracket C) \rightarrow \llbracket A \rrbracket T \gamma$

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McBride [McB10] introduced KIPLING:

- From [McB10]:

data $\text{Context}_2 : \text{Set}$

$\llbracket _ \rrbracket C_2 : \text{Context}_2 \rightarrow \text{Set}$

data $\text{Type}_2 : \text{Context}_2 \rightarrow \text{Set}$

$\llbracket _ \rrbracket T_2 : \forall \Gamma \rightarrow \text{Type}_2 \Gamma \rightarrow \llbracket \Gamma \rrbracket C_2 \rightarrow \text{Set}$

data $\text{Term}_2 : \forall \Gamma \rightarrow (\llbracket \Gamma \rrbracket C_2 \rightarrow \text{Set}) \rightarrow \text{Set}$

$\llbracket _ \rrbracket t_2 : \forall \{\Gamma\} \{S\} \rightarrow \text{Term}_2 \Gamma S \rightarrow (\gamma : \llbracket \Gamma \rrbracket C_2) \rightarrow S \gamma$

Think of $\text{Term}_2 \Gamma S$ as the type of all terms t such that $\Gamma \vdash t : A$ for some A such that $\llbracket A \rrbracket T_2 = S$.

- If s and t are definitionally equal in the object theory, then $\llbracket s \rrbracket$ and $\llbracket t \rrbracket$ are *definitionally* equal in Agda!

Postulate universes of groupoids, setoids and propositions.

Add computation rules to Agda

The Formalisation

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data $Cx : Set$
 $\llbracket _ \rrbracket C : Cx \rightarrow \text{Groupoid}$

data $_ \vdash_2 _ : \forall \Gamma \rightarrow \text{Fibration}_2 \llbracket \Gamma \rrbracket C \rightarrow Set$ **where**

$\llbracket _ \rrbracket_2 : \forall \{\Gamma\} \{T\} \rightarrow \Gamma \vdash_2 T \rightarrow \text{Section}_2 T$

data $\text{Sub } \Gamma : Cx \rightarrow Set$

$\llbracket _ \rrbracket S : \forall \{\Gamma\} \{\Delta\} \rightarrow \text{Sub } \Gamma \Delta \rightarrow \text{Groupoid-Functor } \llbracket \Gamma \rrbracket C \llbracket \Delta \rrbracket C$

data $\text{PathSub } \{\Gamma\} : \forall \{\Delta\} \rightarrow \text{Sub } \Gamma \Delta \rightarrow \text{Sub } \Gamma \Delta \rightarrow Set$

$\llbracket _ \rrbracket PS : \forall \{\Gamma \Delta\} \{\rho \sigma : \text{Sub } \Gamma \Delta\} \rightarrow \text{PathSub } \rho \sigma \rightarrow$
 $\text{Groupoid-NatIso } \llbracket \rho \rrbracket S \llbracket \sigma \rrbracket S$

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Results Verified

1. TLDR has sound semantics in Agda extended by the new computation rules.

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1. TLDR has sound semantics in Agda extended by the new computation rules.
2. Path substitution is well defined.
3. If Agda with the new computation rules is consistent, then TDLR is consistent.

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4. Corollary: if Agda with equality reflection is consistent, then TDLR is consistent.

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Future work:

- Normalisation by evaluation
- Calculation involving univalence: $K(G, 1)$
- Three-dimensional version

Meaning Explanation for Homotopy Types?

To know a proposition is to know how to construct a canonical proof.

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To know a proposition is to know how to construct a canonical proof.
To know a set is to know how to construct a canonical element, and
to know the proposition $a = b$ for canonical elements a, b

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Meaning Explanation for Homotopy Types?

To know a proposition is to know how to construct a canonical proof.

To know a set is to know how to construct a canonical element, and to know the proposition $a = b$ for canonical elements a, b

To know a groupoid is to know how to construct a canonical object, and to know the set $a = b$ for canonical objects a, b

Etc.

Gives a meaning explanation for n -types for all finite n .

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Etc.

Gives a meaning explanation for n -types for all finite n .

To know a type is to know how to construct a canonical object, and to know the type $a = b$ for canonical objects a, b .

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Thank you!

Source code available at: github.com/radams78/TLDR

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