Mathematics

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Chapter 1

Primitive Terms and Axioms

1.1 Primitive Terms

Let there be sets. We write A: Set for: A is a set.

For any set A, let there be *elements* of A. We write a : El(A) for: a is an element of A.

For any sets A and B, let there be functions from A to B. We write $f:A\to B$ iff f is a function from A to B.

For any function $f: A \to B$ and element a: El(A), let there be an element f(a): El(B), the value of the function f at the argument a.

1.2 Axioms

Axiom Schema 1.1 (Choice). Let P[X, Y, x, y] be a formula where X and Y are set variables, x : El(X) and y : El(Y). Then the following is an axiom.

Let A and B be sets. Assume that, for all a : El(A), there exists b : El(B) such that P[A, B, a, b]. Then there exists a function $f : A \to B$ such that $\forall a : El(A) . P[A, B, a, f(a)]$.

Axiom 1.2 (Pairing). For any sets A and B, there exists a set $A \times B$, the Cartesian product of A and B, and functions $\pi_1 : A \times B \to A$ and $\pi_2 : A \times B \to B$ such that, for all a : El(A) and b : El(B), there exists a unique $(a,b) : \text{El}(A \times B)$ such that $\pi_1(a,b) = a$ and $\pi_2(a,b) = b$.

Definition 1.3 (Injective). A function $f: A \to B$ is injective or an injection iff, for all x, y: El(A), if f(x) = f(y) then x = y.

Axiom Schema 1.4 (Separation). For every property P[X,x] where X is a set variable and x : El(X), the following is an axiom:

For every set A, there exists a set $S = \{x : \text{El}(A) \mid P[A, x]\}$ and an injection $i: S \to A$ such that, for all x : El(A), we have

$$(\exists y : S.i(y) = x) \Leftrightarrow P[A, x]$$
.

Axiom 1.5 (Infinity). There exists a set \mathbb{N} , an element $0 : \text{El}(\mathbb{N})$, and a function $s : \mathbb{N} \to \mathbb{N}$ such that:

- $\forall n : \text{El}(\mathbb{N}) . s(n) \neq 0$
- $\forall m, n : \text{El}(\mathbb{N}) . s(m) = s(n) \Rightarrow m = n.$

1.3 Consequences of the Axioms

1.3.1 Definitions

Definition 1.6. Let $f, g : A \to B$. We say f and g are equal, f = g, iff $\forall x : \text{El}(A) . f(x) = g(x)$.

Definition 1.7 (Surjective). A function $f: A \to B$ is *surjective* iff, for all y: El(B), there exists x: El(A) such that f(x) = y.

Definition 1.8 (Bijective). A function $f: A \to B$ is bijective or a bijection iff it is injective and surjective.

Sets A and B are equinumerous, $A \approx B$, iff there exists a bijection between them.

If we prove there exists a set X such that P(X), and that any two sets that satisfy P are bijective, then we may introduce a constant C and define "Let C be the set such that P(C)".

1.3.2 The Empty Set

Theorem 1.9. There exists a set which has no elements.

Proof:

 $\langle 1 \rangle 1$. Pick a set A

PROOF: By the Axiom of Infinity, a set exists.

 $\langle 1 \rangle 2$. Let: $S = \{x : \text{El}(A) \mid \bot\}$ with injection $i : S \to A$ Proof: Axiom of Separation.

 $\langle 1 \rangle 3$. S has no elements.

Theorem 1.10. If E and E' have no elements then $E \approx E'$.

Proof:

- $\langle 1 \rangle 1$. Let: E and E' have no elements.
- $\langle 1 \rangle 2$. PICK a function $F: E \to E'$.

PROOF: Axiom of Choice since vacuously $\forall x : \text{El}(E) . \exists y : \text{El}(E') . \top$.

```
\langle 1 \rangle 3. F is injective.
  PROOF: Vacuously, for all x, y : El(E), if F(x) = F(y) then x = y.
\langle 1 \rangle 4. F is surjective.
  PROOF: Vacuously, for all y : El(E), there exists x : El(E) such that F(x) =
П
Definition 1.11 (Empty Set). The empty set \emptyset is the set with no elements.
          The Singleton
1.3.3
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Theorem 1.12. There exists a set that has exactly one element.

Proof:

 $\langle 1 \rangle 1$. PICK a set A that has an element. PROOF: By the Axiom of Infinity, there exists a set that has an element. $\langle 1 \rangle 2$. Pick a : El(A)

 $\langle 1 \rangle 3$. Let: $R: A \hookrightarrow A$ be the relation such that, for all x, y: El(A), we have xRy if and only if x = y = a.

PROOF: By the Axiom of Comprehension.

 $\langle 1 \rangle 4$. Let: |R| be the tabulation of R with projections $p, q: |R| \to A$. Prove: |R| has exactly one element. PROOF: By the Axiom of Tabulations.

(1)5. Let: r: El(|R|) be the element such that p(r) = q(r) = a

PROOF: Since aRa by $\langle 1 \rangle 3$.

 $\langle 1 \rangle 6$. Let: s : El(|R|)Prove: s = r

 $\langle 1 \rangle 7$. p(s)Rq(s)

PROOF: By the Axiom of Tabulations.

 $\langle 1 \rangle 8. \ p(s) = q(s) = a$ Proof: By $\langle 1 \rangle 3$.

 $\langle 1 \rangle 9$. p(s) = p(r) and q(s) = q(r)

Proof: By $\langle 1 \rangle 5$.

 $\langle 1 \rangle 10.$ s=r

Proof: By the Axiom of Tabulations.

Theorem 1.13. If A and B both have exactly one element then $A \approx B$.

Proof:

- $\langle 1 \rangle 1$. Let: A and B both have exactly one element.
- $\langle 1 \rangle 2$. Let: $F: A \hookrightarrow B$ be the relation such that, for all x: El(A) and y: El(B), we have xFy.

 $\langle 1 \rangle 3$. F is a function.

PROOF: If xFy and xFy' then y = y' because B has only one element.

 $\langle 1 \rangle 4$. F is injective.

PROOF: If F(x) = F(x') then x = x' because A has only one element.

```
\langle 1 \rangle5. F is surjective.

\langle 2 \rangle1. Let: y: El (B)

\langle 2 \rangle2. Let: x be the element of A.

\langle 2 \rangle3. F(x) = y
```

Definition 1.14 (Singleton). Let 1 be the set that has exactly one element. Let * be its element.

1.3.4 Subsets

Definition 1.15 (Subset). A *subset* of a set A is a relation $1 \hookrightarrow S$. Given $S: 1 \hookrightarrow S$ and a: El(A), we write $a \in S$ for *Sa.

Theorem Schema 1.16. For any property P[X,x] where X is a set variable and x : El(X), the following is a theorem:

For any set A, there exists a set B and injection $i: B \to A$ such that, for all x: El(A), we have P[A, x] if and only if there exists b: El(B) such that i(b) = x.

Proof:

 $\langle 1 \rangle 1$. LET: $S: 1 \hookrightarrow A$ be the relation such that, for all e: El(1) and a: El(A), we have eSa if and only if P[A, a].

Proof: Axiom of Comprehension.

- $\langle 1 \rangle$ 2. Let: B be the tabulation of S with projections $p: B \to 1$ and $i: B \to A$. Proof: Axiom of Tabulations.
- $\langle 1 \rangle 3$. *i* is injective.
 - $\langle 2 \rangle 1$. Let: r, s : El(B)
 - $\langle 2 \rangle 2$. Assume: i(r) = i(s)
 - $\langle 2 \rangle 3. \ p(r) = p(s)$

PROOF: Since 1 has only one element.

 $\langle 2 \rangle 4. \ r = s$

Proof: Axiom of Tabulations.

- $\langle 1 \rangle 4$. For all x : El(A), we have P[A, x] if and only if there exists b : El(B) such that i(b) = x.
 - $\langle 2 \rangle 1$. Let: x : El(A)
 - $\langle 2 \rangle 2$. If P[A, x] then there exists b : El(B) such that i(b) = x
 - $\langle 3 \rangle 1$. Assume: P[A, x]
 - $\langle 3 \rangle 2. *Sx$

Proof: $\langle 1 \rangle 1$

 $\langle 3 \rangle 3$. There exists b : El(B) such that p(b) = * and i(b) = x

Proof: Axiom of Tabulations.

- $\langle 2 \rangle 3$. For all b : El(B) we have P[A, i(b)]
 - $\langle 3 \rangle 1$. Let: b : El(B)
 - $\langle 3 \rangle 2. \ p(b)Si(b)$

Proof: Axiom of Tabulations.

 $\langle 3 \rangle 3. P[A, i(b)]$

Proof: $\langle 1 \rangle 1$

1.4 Composition

Definition 1.17 (Composite). Let $\phi : A \hookrightarrow B$ and $\psi : B \hookrightarrow C$. The *composite* $\psi \circ \phi : A \hookrightarrow C$ is the relation such that $a(\psi \circ \phi)c$ iff there exists b such that $a\phi b$ and $b\psi c$.

Definition 1.18 (Identity). For any set A, the *identity* function $id_A : A \to A$ is the function defined by $id_A(a) = a$.

Theorem 1.19. Composition of relations is associative, and the identity function is an identity for composition. The composite of functions is a function. The composite of injective functions is injective. The composite of surjective functions is surjective. The composite of bijections is a bijection. A function $f: A \to B$ is a bijection iff there exists a function $f^{-1}: B \to A$ such that $f^{-1}f = \mathrm{id}_A$ and $ff^{-1} = \mathrm{id}_B$, in which case f^{-1} is unique.

1.5 Axioms Part Two

Axiom 1.20 (Power Set). For any set A, there exists a set $\mathcal{P}A$, the power set of A, and a relation \in : $A \hookrightarrow \mathcal{P}A$, called membership, such that, for any subset S of A, there exists a unique $\overline{S} \in \mathcal{P}A$ such that, for all $x \in A$, we have $x \in \overline{S}$ if and only if $x \in S$.

We usually write just S for \overline{S} .

Axiom Schema 1.21 (Collection). Let P[X,Y,x] be a formula with set variables X and Y and an element variable $x \in X$. Then the following is an axiom. For any set A, there exists a set B, a function $p:B \to A$, a set Y and a relation $M:B \hookrightarrow Y$ such that:

- $\forall b \in B.P[A, \{y \in Y : bMy\}, p(b)]$
- For all $a \in A$, if $\exists Y.P[A, Y, a]$, then there exists $b \in B$ such that a = p(b).

Definition 1.22 (Universe). Let $E:U \hookrightarrow X$ be a relation. Let us say that a set A is *small* iff there exists $u \in U$ such that $A \approx \{x \in X : uEx\}$.

Then (U, X, E) form a *universe* if and only if:

- \mathbb{N} is U-small.
- For any *U*-small sets *A* and *B* and relation $R: A \hookrightarrow B$, the tabulation of *R* is *U*-small.
- If A is U-small then so is $\mathcal{P}A$
- Let $f: A \to B$ be a function. If B is U-small and $f^{-1}(b)$ is U-small for all $b \in B$, then A is U-small.

• If $p: B \to A$ is a surjective function such that A is U-small, then there exists a U-small set C, a surjection $q: C \to A$, and a function $f: C \to B$ such that q = pf.

Axiom 1.23 (Universe). There exists a universe.

Let $E:U \hookrightarrow X$ be a universe. We shall say a set is small iff it is U-small, and large otherwise.

1.6 Cartesian Product

Definition 1.24 (Cartesian Product). Let A and B be sets. The *Cartesian product* of A and B, $A \times B$, is the tabulation of the relation $A \hookrightarrow B$ that holds for all $a \in A$ and $b \in B$. The associated functions $\pi_1 : A \times B \to A$ and $\pi_2 : A \times B \to B$ are called the *projections*.

Given $a \in A$ and $b \in B$, we write (a, b) for the unique element of $A \times B$ such that $\pi_1(a, b) = a$ and $\pi_2(a, b) = b$.

1.7 Quotient Sets

Proposition 1.25. Let \sim be an equivalence relation on X. Then there exists a set X/\sim , the quotient set of X with respect to \sim , and a surjective function $\pi: X \twoheadrightarrow X/\sim$, the canonical projection, such that, for all $x,y: \mathrm{El}(X)$, we have $x \sim y$ if and only if $\pi(x) = \pi(y)$.

Further, if $p: X \to Q$ is another quotient with respect to \sim , then there exists a unique bijection $\phi: X/\sim \approx Q$ such that $\phi \circ \pi = p$.

Chapter 2

Topology

2.1 Topological Spaces

Definition 2.1 (Topological Space). Let X be a set and $\mathcal{O} \subseteq \mathcal{P}X$. Then we say (X, \mathcal{O}) is a topological space iff:

- For any $\mathcal{U} \subseteq \mathcal{O}$ we have $\bigcup \mathcal{U} \in \mathcal{O}$.
- For any $U, V \in \mathcal{O}$ we have $U \cap V \in \mathcal{O}$.
- $X \in \mathcal{O}$

We call \mathcal{O} the *topology* of the topological space, and call its elements *open* sets. We shall often write X for the topological space (X, \mathcal{O}) .

Definition 2.2 (Closed Set). Let X be a topological space and $A \subseteq X$. Then A is *closed* iff X - A is open.

Proposition 2.3. A set B is open if and only if X - B is closed.

Proposition 2.4. Let X be a set and $C \subseteq \mathcal{P}X$. Then there exists a topology \mathcal{O} on X such that C is the set of closed sets if and only if:

- For any $\mathcal{D} \subseteq \mathcal{C}$ we have $\bigcap \mathcal{D} \in \mathcal{C}$
- For any $C, D \in \mathcal{C}$ we have $C \cup D \in \mathcal{C}$.
- $\varnothing \in \mathcal{C}$

In this case, \mathcal{O} is unique and is given by $\mathcal{O} = \{X - C : C \in \mathcal{C}\}.$

Definition 2.5 (Neighbourhood). Let X be a topological space, $Sx \in X$ and $U \subseteq X$. Then U is a *neighbourhood* of x, and x is an *interior* point of U, iff there exists an open set V such that $x \in V \subseteq U$.

Proposition 2.6. A set B is open if and only if it is a neighbourhood of each of its points.

Proposition 2.7. Let X be a set and $\mathcal{N}: X \to \mathcal{P}X$. Then there exists a topology \mathcal{O} on X such that, for all $x \in X$, we have \mathcal{N}_x is the set of neighbourhoods of x, if and only if:

- For all $x \in X$ and $N \in \mathcal{N}_x$ we have $x \in N$
- For all $x \in X$ we have $X \in \mathcal{N}_x$
- For all $x \in X$, $N \in \mathcal{N}_x$ and $V \subseteq \mathcal{P}X$, if $N \subseteq V$ then $V \in \mathcal{N}_x$
- For all $x \in X$ and $M, N \in \mathcal{N}_x$ we have $M \cap N \in \mathcal{N}_x$
- For all $x \in X$ and $N \in \mathcal{N}_x$, there exists $M \in \mathcal{N}_x$ such that $M \subseteq N$ and $\forall y \in M.M \in \mathcal{N}_y$.

In this case, \mathcal{O} is unique and is given by $\mathcal{O} = \{U : \forall x \in U.U \in \mathcal{N}_x\}.$

Definition 2.8 (Exterior Point). Let X be a topological space, $x \in X$ and $B \subseteq X$. Then x is an *exterior point* of B iff B - X is a neighbourhood of x.

Definition 2.9 (Boundary Point). Let X be a topological space, $x \in X$ and $B \subseteq X$. Then x is a boundary point of B iff it is neither an interior point nor an exterior point of B.

Definition 2.10 (Interior). Let X be a topological space and $B \subseteq X$. The *interior* of B, B° , is the set of all interior points of B.

Proposition 2.11. The interior of B is the union of all the open sets included in B.

Definition 2.12 (Closure). Let X be a topological space and $B \subseteq X$. The *closure* of B, \overline{B} , is the set of all points that are not exterior points of B.

Proposition 2.13. The closure of B is the intersection of all the closed sets that include B.

Proposition 2.14. A set B is open iff $X - B = \overline{X - B}$.

Proposition 2.15 (Kuratowski Closure Axioms). Let X be a set and $\neg: \mathcal{P}X \to \mathcal{P}X$. Then there exists a topology \mathcal{O} such that, for all $B \subseteq X$, \overline{B} is the closure of B, if and only if:

- $\overline{\varnothing} = \varnothing$
- For all $A \subseteq X$ we have $A \subseteq \overline{A}$
- For all $A \subseteq X$ we have $\overline{\overline{A}} = \overline{A}$
- For all $A, B \subseteq X$ we have $\overline{A \cup B} = \overline{A} \cup \overline{B}$

In this case, \mathcal{O} is unique and is defined by $\mathcal{O} = \{U : X - U = \overline{X - U}\}.$

2.1.1 Subspaces

Definition 2.16 (Subspace). Let X be a topological space and $X_0 \subseteq X$. The subspace topology on X_0 is $\{U \cap X_0 : U \text{ is open in } X\}$.

Example 2.17. The unit sphere S^2 is $\{x \in \mathbb{R}^3 : ||x|| = 1\}$ as a subspace of \mathbb{R}^3 .

2.1.2 Topological Disjoint Union

Definition 2.18. Let X and Y be topological spaces. The *disjoint union* is X + Y where $U \subseteq X + Y$ is open if and only if $\kappa_1^{-1}(U)$ is open in X and $\kappa_2^{-1}(U)$ is open in Y.

2.1.3 Product Topology

Definition 2.19. Let X and Y be topological spaces. The *product topology* on $X \times Y$ is the set of all subsets $W \subseteq X \times Y$ such that, for all $(x, y) \in W$, there exist neighbourhoods U of x in X and Y of y in Y such that $U \times V \subseteq W$.

2.1.4 Bases

Definition 2.20 (Basis). Let X be a topological space. A *basis* for the topology on X is a set of open sets \mathcal{B} such that every open set is the union of a subset of \mathcal{B} .

2.1.5 Subbases

Definition 2.21 (Subbasis). Let X be a topological space. A *subbasis* for the topology on X is a subset $S \subseteq \mathcal{P}X$ such that every open set is a union of finite intersections of S.

2.2 Continuous Functions

Definition 2.22 (Continuous). Let X and Y be topological spaces. A function $f: X \to Y$ is *continuous* iff, for every open set V in Y, the inverse image $f^{-1}(V)$ is open in X.

Proposition 2.23. 1. id_X is continuous

- 2. The composite of two continuous functions is continuous.
- 3. If $f: X \to Y$ is continuous and $X_0 \subseteq X$ then $f \upharpoonright X_0 : X_0 \to Y$ is continuous.
- 4. If $f: X + Y \to Z$, then f is continuous iff $f \circ \kappa_1 : X \to Z$ and $f \circ \kappa_2 : Y \to Z$ are continuous.
- 5. If $f: Z \to X \times Y$, then f is continuous iff $\pi_1 \circ f$ and $\pi_2 \circ f$ are continuous.

Definition 2.24 (Homeomorphism). Let X and Y be topological spaces. A homeomorphism between X and Y is a bijection $f: X \approx Y$ such that f and f^{-1} are continuous.

2.3 Convergence

Definition 2.25 (Convergence). Let X be a topological space. Let (x_n) be a sequence in X. A point a : El(X) is a *limit* of the sequence iff, for every neighbourhood U of a, there exists n_0 such that $\forall n \ge n_0.x_n \in U$.

2.4 Connected Spaces

Definition 2.26 (Connected). A topological space is *connected* iff it is not the union of two nonempty open disjoint subsets.

Proposition 2.27. The continuous image of a connected space is connected.

Proposition 2.28. Let X be a topological space and $A, B \subseteq X$. If $X = A \cup B$, $A \cap B \neq \emptyset$, and A and B are connected, then X is connected.

Proposition 2.29. If X and Y are nonempty topological spaces, then $X \times Y$ is connected if and only if X and Y are connected.

Definition 2.30 (Path-connected). A topological space X is path-connected iff, for any points $a, b \in X$, there exists a continuous function $\alpha : [0,1] \to X$, called a path, such that $\alpha(0) = a$ and $\alpha(1) = b$.

Proposition 2.31. The continuous image of a path connected space is path connected.

Proposition 2.32. Let X be a topological space and $A, B \subseteq X$. If $X = A \cup B$, $A \cap B \neq \emptyset$, and A and B are path connected, then X is path connected.

Proposition 2.33. If X and Y are nonempty topological spaces, then $X \times Y$ is path connected if and only if X and Y are path connected.

2.5 Hausdorff Spaces

Definition 2.34 (Hausdorff). A topological space is a *Hausdorff* space or a T_2 space iff any two distinct points have disjoint neighbourhoods.

Proposition 2.35. In a Hausdorff space, a sequence has at most one limit.

Proposition 2.36. 1. Every subspace of a Hausdorff space is Hausdorff.

- 2. The disjoint union of two Hausdorff spaces is Hausdorff.
- 3. The product of two Hausdorff spaces is Hausdorff.

2.6 Compactness

Definition 2.37 (Compact). A topological space is *compact* iff every open cover has a finite subcover.

Proposition 2.38. Let X be a compact topological space. Let P be a set of open sets such that, for all $U, V \in P$, we have $U \cup V \in P$. Assume that every point has an open neighbourhood in P. Then $X \in P$.

PROOF:

```
\langle 1 \rangle 1. P is an open cover of X

\langle 1 \rangle 2. PICK a finite subcover U_1, \dots, U_n \in P

\langle 1 \rangle 3. X = U_1 \cup \dots \cup U_n \in P
```

Corollary 2.38.1. Let f be a compact space and $f: X \to \mathbb{R}$ be locally bounded. Then f is bounded.

PROOF: Take $P = \{U \text{ open in } X : f \text{ is bounded on } U\}$. \square

Proposition 2.39. The continuous image of a compact space is compact.

Proposition 2.40. A closed subspace of a compact space is compact.

Proposition 2.41. Let X and Y be nonempty spaces. Then the following are equivalent.

- 1. X and Y are compact.
- 2. X + Y is compact.
- 3. $X \times Y$ is compact.

Proposition 2.42. A compact subspace of a Hausdorff space is closed.

Proposition 2.43. A continuous bijection from a compact space to a Hausdorff space is a homeomorphism.

2.7 Quotient Spaces

Definition 2.44 (Quotient Space). Let X be a topological space and \sim an equivalence relation on X. The *quotient topology* on X/\sim is defined by: U: $\mathrm{El}(\mathcal{P}X)$ is open in X/\sim if and only if $\pi^{-1}(U)$ is open in X.

Proposition 2.45. Let X and Y be topological spaces. Let \sim be an equivalence relation on X. Let $f: X/\sim \to Y$. Then f is continuous if and only if $f\circ \pi$ is continuous.

Proposition 2.46. Let X and Y be topological spaces. Let \sim be an equivalence relation on X. Let $\phi: Y \to X/\sim$.

Assume that, for all $y \in Y$, there exists a neighbourhood U of y and a continuous function $\Phi: U \to X$ such that $\pi \circ \Phi = \phi \upharpoonright U$. Then ϕ is continuous.

Proposition 2.47. A quotient of a connected space is connected.

Proposition 2.48. A quotient of a path connected space is path connected.

Proposition 2.49. Let X be a topological space and \sim an equivalence relation on X. If X/\sim is Hausdorff then every equivalence class of \sim is closed in X.

Definition 2.50. Let X be a topological space and $A_1, \ldots, A_r \subseteq X$. Then $X/A_1, \ldots, A_r$ is the quotient space of X with respect to \sim where $x \sim y$ iff x = y or $\exists i (x \in A_i \land y \in A_i)$.

Definition 2.51 (Cone). Let X be a topological space. The *cone over* X is the space $(X \times [0,1])/(X \times \{1\})$.

Definition 2.52 (Suspension). Let X be a topological space. The *suspension* of X is the space

$$\Sigma X := (X \times [-1, 1])/(X \times \{-1\}), (X \times \{1\})$$

Definition 2.53 (Wedge Product). Let $x_0 \in X$ and $y_0 \in Y$. The wedge product $X \vee Y$ is $(X \times \{y_0\}) \cup (\{x_0\} \times Y)$ as a subspace of $X \times Y$.

Definition 2.54 (Smash Product). Let $x_0 \in X$ and $y_0 \in Y$. The *smash product* $X \wedge Y$ is $(X \times Y)/(X \vee Y)$.

Example 2.55. $D^n/S^{n-1} \cong S^n$

Proof:

 $\langle 1 \rangle 1$. Let: $\phi: D^n/S^{n-1} \to S^n$ be the function induced by the map $D^n \to S^n$ that maps the radii of D^n onto the meridians of S^n from the north to the south pole.

 $\langle 1 \rangle 2$. ϕ is a bijection.

 $\langle 1 \rangle 3$. ϕ is a homeomorphism.

PROOF: Since D^n/S^{n-1} is compact and S^n is Hausdorff.

2.8 Gluing

Definition 2.56 (Gluing). Let X and Y be topological spaces, $X_0 \subseteq X$ and $\phi: X_0 \to Y$ a continuous map. Then $Y \cup_{\phi} X$ is the quotient space $(X + Y)/\sim$, where \sim is the equivalence relation generated by $x \sim \phi(x)$ for all x : El(X).

Proposition 2.57. Y is a subspace of $Y \cup_{\phi} X$.

Definition 2.58. Let X be a topological space and $\alpha: X \cong X$ a homeomorphism. Then $(X \times [0,1])/\alpha$ is the quotient space of $X \times [0,1]$ by the equivalence relation generated by $(x,0) \sim (\alpha(x),1)$ for all $x: \mathrm{El}(X)$.

Definition 2.59 (Möbius Strip). The *Möbius strip* is $([-1,1] \times [0,1])/\alpha$ where $\alpha(x) = -x$.

Definition 2.60 (Klein Bottle). The *Klein bottle* is $(S^1 \times [0,1])/\alpha$ where $\alpha(z) = \overline{z}$.

Proposition 2.61. Let M be the Möbius strip and K the Klein bottle. Then $M \cup_{\mathrm{id}_{\partial M}} M \cong K$.

Proof:

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\langle 1 \rangle 1. LET: f: ([-1,1] \times [0,1]) + ([-1,1] \times [0,1]) \to S^1 \times [0,1] be the function that maps \kappa_1(\theta,t) to (e^{\pi i\theta/2},t) and \kappa_2(\theta,t) to (-e^{-\pi i\theta/2},t). \langle 1 \rangle 2. f induces a bijection M \cup_{\mathrm{id}_{\partial M}} M \approx K \langle 1 \rangle 3. f is a homeomorphism.
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2.9 Metric Spaces

Definition 2.62 (Metric Space). Let X be a set and $d: X^2 \to \mathbb{R}$. We say (X, d) is a *metric space* iff:

- For all $x, y \in X$ we have $d(x, y) \ge 0$
- For all $x, y \in X$ we have d(x, y) = 0 iff x = y
- For all $x, y \in X$ we have d(x, y) = d(y, x)
- (Triangle Inequality) For all $x, y, z \in X$ we have $d(x, z) \leq d(x, y) + d(y, z)$

We call d the *metric* of the metric space (X, d). We often write X for the metric space (X, d).

Definition 2.63 (Topology of a Metric Space). Let (X,d) be a metric space. The topology *induced* by the metric d is defined by: for $V \subseteq X$, we have V is open if and only if, for all $x \in V$, there exists $\epsilon > 0$ such that $\{y \in X : d(x,y) < \epsilon\} \subseteq V$.

Definition 2.64 (Metrizable). A topological space is *metrizable* iff there exists a metric that induces its topology.

Proposition 2.65. Every metrizable space is Hausdorff.

2.10 Complete Metric Spaces

Definition 2.66 (Complete). A metric space is *complete* iff every Cauchy sequence converges.

Example 2.67. \mathbb{R} is complete.

Proposition 2.68. The product of two complete metric spaces is complete.

Proposition 2.69. Every compact metric space is complete.

Proposition 2.70. Let X be a complete metric space and $A \subseteq X$. Then A is complete if and only if A is closed.

Definition 2.71 (Completion). Let X be a metric space. A *completion* of X is a complete metric space \hat{X} and injection $i: X \rightarrowtail \hat{X}$ such that:

- The metric on X is the restriction of the metric on \hat{X}
- X is dense in \hat{X} .

Proposition 2.72. Let $i_1: X \to Y_1$ and $i_2: X \to Y_2$ be completions of X. Then there exists a unique isometry $\phi: Y_1 \cong Y_2$ such that $\phi \circ i_1 = i_2$.

PROOF: Define $\phi(\lim_{n\to\infty} i_1(x_n)) = \lim_{n\to\infty} i_2(x_n)$. \square

Theorem 2.73. Every metric space has a completion.

PROOF: Let \hat{X} be the set of Cauchy sequences in X quotiented by \sim where $(x_n) \sim (y_n)$ if and only if $d(x_n, y_n) \to 0$. \square

Chapter 3

Topological Groups

Definition 3.1 (Topological Group). A topological group is a group G with a topology such that the function $G^2 \to G$ that maps (x, y) to xy^{-1} is continuous.

Example 3.2. $GL(n,\mathbb{R})$ and $GL(n,\mathbb{C})$ are topological groups.

Proposition 3.3. Any subgroup of a topological group is a topological group under the subspace topology.

Definition 3.4 (Homogeneous Space). A homogeneous space is a topological space of the form G/H, where G is a topological group and H is a normal subgroup of G, under the quotient topology.

Proposition 3.5. Let G be a topological group and H a normal subgroup of G. Then G/H is Hausdorff if and only if H is closed.

Proof: See Bourbaki, N., General Topology. III.12

3.1 Continuous Actions

Definition 3.6 (Continuous Action). Let G be a topological group and X a topological space. A *continuous action* of G on X is a continuous function $\cdot: G \times X \to X$ such that:

- $\forall x : \text{El}(X) . ex = x$
- $\forall g, h : \text{El}(G) . \forall x : \text{El}(X) . g(hx) = (gh)x$

A G-space consists of a topological space X and a continuous action of G on X.

Definition 3.7 (Orbit). Let X be a G-space and $x \in X$. The *orbit* of x is $\{gx : g \in G\}$.

The *orbit space* X/G is the set of all orbits under the quotient topology.

Proposition 3.8. Define an action of SO(2) on S^2 by $g(x_1, x_2, x_3) = (g(x_1, x_2), x_3)$. Then $S^2/SO(2) \cong [-1,1]$.

Proof:

- $\langle 1 \rangle 1.$ Let: $f_3: S^2/SO(2) \rightarrow$ [-1,1] be the function induced by $\pi_3: S^2 \rightarrow$ [-1, 1]
- $\langle 1 \rangle 2$. f_3 is bijective.
- $\langle 1 \rangle 3.$ $S^2/SO(2)$ is compact.

PROOF: It is the continuous image of S^2 which is compact.

- $\langle 1 \rangle 4$. [-1,1] is Hausdorff.
- $\langle 1 \rangle 5$. f_3 is a homeomorphism.

Definition 3.9 (Stabilizer). Let X be a G-space and $x \in X$. The stabilizer of $x \text{ is } G_x := \{g : \text{El}(G) \mid gx = x\}.$

Proposition 3.10. The function that maps gG_x to gx is a continuous bijection from G/G_x to Gx.

Proof:

- $\langle 1 \rangle 1$. If $gG_x = hG_x$ then gx = hx.
 - $\langle 2 \rangle 1$. Assume: $gG_x = hG_x$

 - $\langle 2 \rangle 2.$ $g^{-1}h \in G_x$ $\langle 2 \rangle 3.$ $g^{-1}hx = x$
 - $\langle 2 \rangle 4$. gx = hx
- $\langle 1 \rangle 2$. If gx = hx then $gG_x = hG_x$.

Proof: Similar.

 $\langle 1 \rangle 3$. The function is continuous.

Proof: Proposition 2.45.

Chapter 4

Topological Vector Spaces

Definition 4.1 (Topological Vector Space). Let K be either \mathbb{R} or \mathbb{C} . A topological vector space over K consists of a vector space E over K and a topology on E such that:

- Substraction is a continuous function $E^2 \to E$
- Multiplication is a continuous function $K \times E \to E$

Proposition 4.2. Every topological vector space is a topological group under addition.

PROOF: Immediate from the definition. \Box

Theorem 4.3. The usual topology on a finite dimensional vector space over K is the only one that makes it into a Hausdorff topological vector space.

PROOF: See Bourbaki. Elements de Mathematique, Livre V: Espaces Vectoriels Topologiques, Th. 2, p. 18 \square

Proposition 4.4. Let E be a topological vector space and E_0 a subspace of E. Then $\overline{E_0}$ is a subspace of E.

Definition 4.5. Let E be a topological vector space. The topological space associated with E is $E/\{0\}$.

4.1 Cauchy Sequences

Definition 4.6 (Cauchy Sequence). Let E be a topological vector space. A sequence (x_n) in E is a *Cauchy sequence* iff, for every neighbourhood U of 0, there exists n_0 such that $\forall m, n \ge n_0.x_n - x_m \in U$.

Definition 4.7 (Complete Topological Vector Space). A topological vector space is *complete* iff every Cauchy sequence converges.

4.2 Seminorms

Definition 4.8 (Seminorm). Let E be a vector space over K. A *seminorm* on E is a function $\| \| : E \to \mathbb{R}$ such that:

- 1. $\forall x : \text{El}(E) . ||x|| \ge 0$
- 2. $\forall \alpha : \text{El}(K) . \forall x : \text{El}(E) . ||\alpha x|| = |\alpha||x||$
- 3. Triangle Inequality $\forall x, y : \text{El}(E) . ||x + y|| \le ||x|| + ||y||$

Example 4.9. The function that maps (x_1, \ldots, x_n) to $|x_i|$ is a seminorm on \mathbb{R}^n .

Definition 4.10. Let E be a vector space over K. Let Λ be a set of seminorms on E. The topology generated by Λ is the topology generated by the subbasis consisting of all sets of the form $B_{\epsilon}^{\lambda}(x) = \{y \in E : \lambda(y-x) < \epsilon\}$ for $\epsilon > 0, \lambda \in \Lambda$ and x : El(E).

Proposition 4.11. E is a topological vector space under this topology. It is Hausdorff iff, for all x : El(E), if $\forall \lambda \in \Lambda.\lambda(x) = 0$ then x = 0.

4.3 Fréchet Spaces

Definition 4.12 (Pre-Fréchet Space). A *pre-Fréchet space* is a Hausdorff topological vector space whose topology is generated by a countable set of seminorms.

Proposition 4.13. Let E be a pre-Fréchet space whose topology is generated by the family of seminorms $\{\| \|_n : n \in \mathbb{Z}^+ \}$. Then

$$d(x,y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \frac{\|x - y\|_n}{1 + \|x - y\|_n}$$

is a metric that induces the same topology. The two definitions of Cauchy sequence agree.

Definition 4.14 (Fréchet Space). A *Fréchet space* is a complete pre-Fréchet space.

4.4 Normed Spaces

Definition 4.15 (Normed Space). Let E be a vector space over K. A norm on E is a function $\| \ \| : E \to \mathbb{R}$ is a seminorm such that, $\forall x \in E. \|x\| = 0 \Leftrightarrow x = 0$. A normed space consists of a vector space with a norm.

Proposition 4.16. If E is a normed space then d(x,y) = ||x-y|| is a metric on E that makes E into a topological vector space. The two definitions of Cauchy sequence agree on E.

Proposition 4.17. Let $\| \ \|$ be a seminorm on the vector space E. Then $\| \ \|$ defines a norm on $E/\overline{\{0\}}$.

4.5 Inner Product Spaces

Proposition 4.18. If E is an inner product space then $||x|| = \sqrt{\langle x, x \rangle}$ is a norm on E.

4.6 Banach Spaces

Definition 4.19 (Banach Space). A *Banach space* is a complete normed space.

Example 4.20. For any topological space X, the set C(X) of bounded continuous functions $X \to \mathbb{R}$ is a Banach space under $||f|| = \sup_{x \in X} |f(x)|$.

4.7 Hilbert Spaces

Definition 4.21 (Hilbert Space). A *Hilbert space* is a complete inner product space.

Example 4.22. The set of square-integrable functions is the set of Lebesgue integrable functions $[-\pi, \pi] \to \mathbb{R}$ quotiented by: $f \sim g$ iff $\{x \in [-\pi, \pi] : f(x) \neq g(x)\}$ has measure 0. This is a Hilbert space under

$$\langle f, g \rangle = \frac{1}{\pi} \int_{-\pi} \pi f(x) g(x) dx$$
.

4.8 Locally Convex Spaces

Definition 4.23 (Locally Convex Space). A topological vector space is *locally convex* iff every neighbourhood of 0 includes a convex neighbourhood of 0.

Proposition 4.24. A topological vector space is locally convex if and only if its topology is generated by a set of seminorms.

PROOF: See Köthe, G. Topological Vector Spaces 1. Section 18.

Proposition 4.25. A locally convex topological vector space is a pre-Fréchet space if and only if it is metrizable.

PROOF: See Köthe, G. Topological Vector Spaces 1. Section 18. \square

Example 4.26. Let E be an infinite dimensional Hilbert space. Let E' be the same vector space under the *weak topology*, the coarsest topology such that every continuous linear map $E \to \mathbb{R}$ is continuous as a map $E' \to \mathbb{R}$. Then E is locally convex Hausdorff but not metrizable.

Proof: See Dieudonne, J. A., Treatise on Analysis, Vol. II, New York and London: Academic Press, 1970, p. 76.

Definition 4.27 (Thom Space). Let E be a vector bundle with a Riemannian metric, $DE = \{x : \text{El}(E) \mid ||x|| \le 1\}$ its disc bundle and $SE := \{v : \text{El}(E) \mid ||v|| = 1\}$ its sphere bundle. The *Thom space* of E is the quotient space DE/SE.