# Mathematics

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# Primitive Terms and Axioms

#### 1.1 Primitive Terms

Let there be sets. We write A: Set for: A is a set.

For any set A, let there be *elements* of A. We write a : El(A) for: a is an element of A.

For any sets A and B, let there be functions from A to B. We write  $f:A\to B$  iff f is a function from A to B.

For any function  $f: A \to B$  and element a: El(A), let there be an element f(a): El(B), the value of the function f at the argument a.

For any sets A and B, let there be a set  $A \times B$ , the Cartesian product of A and B, and functions  $\pi_1 : A \times B \to A$  and  $\pi_2 : A \times B \to B$ , the projections.

For any elements a : El(A) and b : El(B), let there be an element  $(a, b) : El(A \times B)$ , the *ordered pair* of a and b.

#### 1.2 Axioms

**Axiom 1.1** (Strong Extensionality). Let  $i: A \to B$ . Suppose that, for every y: El(B), there exists a unique x: El(A) such that i(x) = y. Then there exists a function  $i^{-1}: B \to A$  such that  $\forall x: \text{El}(A).i^{-1}(i(x)) = x$  and  $\forall y: \text{El}(B).i(i^{-1}(y)) = y$ .

Axiom 1.2 (Pairing).

- $\forall x : \text{El}(A) . \forall y : \text{El}(B) . \pi_1(x, y) = x$
- $\forall x : \text{El}(A) . \forall y : \text{El}(B) . \pi_2(x, y) = y$
- $\forall p : \text{El}(A \times B) . p = (\pi_1(p), \pi_2(p))$

**Definition 1.3** (Injective). A function  $f: A \to B$  is injective or an injection iff, for all x, y: El(A), if f(x) = f(y) then x = y.

**Axiom 1.4** (Separation). For every property P[X, x] where X is a set variable and x : El(X), the following is an axiom:

For every set A, there exists a set  $S = \{x : \text{El}(A) \mid P[A, x]\}$  and an injection  $i: S \to A$  such that, for all x : El(A), we have

$$(\exists y : S.i(y) = x) \Leftrightarrow P[A, x]$$
.

**Axiom 1.5** (Infinity). There exists a set  $\mathbb{N}$ , an element  $0 : \text{El}(\mathbb{N})$ , and a function  $s : \mathbb{N} \to \mathbb{N}$  such that:

- $\forall n : \text{El}(\mathbb{N}) . s(n) \neq 0$
- $\forall m, n : \text{El}(\mathbb{N}) . s(m) = s(n) \Rightarrow m = n.$

**Axiom 1.6** (Choice). Let R be a set and  $i: R \to A \times B$  an injection. Assume  $\forall a: \text{El}(A) . \exists r: \text{El}(R) . \pi_1(i(r)) = a$ . Then there exists a function  $f: A \to B$  such that  $\forall a: \text{El}(A) . \exists r: \text{El}(R) . i(r) = (a, f(a))$ .

## 1.3 Consequences of the Axioms

#### 1.3.1 Definitions

**Definition 1.7.** Let  $f, g: A \to B$ . We say f and g are equal, f = g, iff  $\forall x : \text{El}(A) . f(x) = g(x)$ .

**Definition 1.8** (Surjective). A function  $f: A \to B$  is *surjective* iff, for all y: El(B), there exists x: El(A) such that f(x) = y.

**Definition 1.9** (Bijective). A function  $f: A \to B$  is bijective or a bijection iff it is injective and surjective.

Sets A and B are equinumerous,  $A \approx B$ , iff there exists a bijection between them.

If we prove there exists a set X such that P(X), and that any two sets that satisfy P are bijective, then we may introduce a constant C and define "Let C be the set such that P(C)".

#### 1.3.2 The Empty Set

**Theorem 1.10.** There exists a set which has no elements.

Proof:

 $\langle 1 \rangle 1$ . Pick a set A

PROOF: By the Axiom of Infinity, a set exists.

 $\langle 1 \rangle 2$ . Let:  $R: A \hookrightarrow A$  be the relation such that, for all  $x, y \in A$ , we have  $\neg (xRy)$ 

```
PROOF: By the Axiom of Comprehension.
\langle 1 \rangle 3. Let: |R| be the tabulation of R with projections p, q: |R| \to A.
       PROVE: |R| has no elements.
  PROOF: By the Axiom of Tabulations.
\langle 1 \rangle 4. Assume: for a contradiction r : \text{El}(|R|)
\langle 1 \rangle 5. \ p(r) Rq(r)
\langle 1 \rangle 6. Q.E.D.
  PROOF: This contradicts \langle 1 \rangle 2.
Theorem 1.11. If E and E' have no elements then E \approx E'.
Proof:
\langle 1 \rangle 1. Let: E and E' have no elements.
\langle 1 \rangle 2. Let: F: E \hookrightarrow E' be the relation such that, for all x: El(E) and y: El(E)
             El(E'), we have xFy.
  Proof: Axiom of Comprehension.
\langle 1 \rangle 3. F is a function.
  PROOF: Vacuously, for all x : El(E), there exists a unique y : El(E') such
  that xFy.
\langle 1 \rangle 4. F is injective.
  PROOF: Vacuously, for all x, y : \text{El}(E), if F(x) = F(y) then x = y.
\langle 1 \rangle 5. F is surjective.
  PROOF: Vacuously, for all y : El(E), there exists x : El(E) such that F(x) =
П
Definition 1.12 (Empty Set). The empty set \emptyset is the set with no elements.
1.3.3
           The Singleton
Theorem 1.13. There exists a set that has exactly one element.
Proof:
\langle 1 \rangle 1. PICK a set A that has an element.
  PROOF: By the Axiom of Infinity, there exists a set that has an element.
\langle 1 \rangle 2. Pick a : \text{El}(A)
\langle 1 \rangle 3. Let: R: A \hookrightarrow A be the relation such that, for all x, y: El(A), we have
              xRy if and only if x = y = a.
  PROOF: By the Axiom of Comprehension.
\langle 1 \rangle 4. Let: |R| be the tabulation of R with projections p, q: |R| \to A.
       Prove: |R| has exactly one element.
  PROOF: By the Axiom of Tabulations.
(1)5. Let: r : \text{El}(|R|) be the element such that p(r) = q(r) = a
  PROOF: Since aRa by \langle 1 \rangle 3.
\langle 1 \rangle 6. Let: s : \text{El}(|R|)
       Prove: s = r
```

```
\langle 1 \rangle 7. \ p(s)Rq(s)
PROOF: By the Axiom of Tabulations.
\langle 1 \rangle 8. \ p(s) = q(s) = a
PROOF: By \langle 1 \rangle 3.
\langle 1 \rangle 9. \ p(s) = p(r) and q(s) = q(r)
PROOF: By \langle 1 \rangle 5.
\langle 1 \rangle 10. \ s = r
PROOF: By the Axiom of Tabulations.
```

**Theorem 1.14.** If A and B both have exactly one element then  $A \approx B$ .

#### Proof:

- $\langle 1 \rangle 1$ . Let: A and B both have exactly one element.
- $\langle 1 \rangle 2$ . LET:  $F: A \hookrightarrow B$  be the relation such that, for all x: El(A) and y: El(B), we have xFy.
- $\langle 1 \rangle 3$ . F is a function.

PROOF: If xFy and xFy' then y = y' because B has only one element.

 $\langle 1 \rangle 4$ . F is injective.

PROOF: If F(x) = F(x') then x = x' because A has only one element.

- $\langle 1 \rangle 5$ . F is surjective.
  - $\langle 2 \rangle 1$ . Let: y : El(B)
  - $\langle 2 \rangle 2$ . Let: x be the element of A.
- $\langle 2 \rangle 3. \ F(x) = y$

**Definition 1.15** (Singleton). Let 1 be the set that has exactly one element. Let \* be its element.

#### 1.3.4 Subsets

**Definition 1.16** (Subset). A *subset* of a set A is a relation  $1 \hookrightarrow S$ . Given  $S: 1 \hookrightarrow S$  and a: El(A), we write  $a \in S$  for \*Sa.

**Theorem Schema 1.17.** For any property P[X,x] where X is a set variable and x : El(X), the following is a theorem:

For any set A, there exists a set B and injection  $i: B \to A$  such that, for all x: El(A), we have P[A,x] if and only if there exists b: El(B) such that i(b) = x.

#### Proof:

 $\langle 1 \rangle 1$ . Let:  $S: 1 \hookrightarrow A$  be the relation such that, for all e: El(1) and a: El(A), we have eSa if and only if P[A, a].

Proof: Axiom of Comprehension.

- $\langle 1 \rangle$ 2. Let: B be the tabulation of S with projections  $p: B \to 1$  and  $i: B \to A$ . Proof: Axiom of Tabulations.
- $\langle 1 \rangle 3$ . *i* is injective.
  - $\langle 2 \rangle 1$ . Let: r, s : El(B)

```
\langle 2 \rangle 2. Assume: i(r) = i(s)
   \langle 2 \rangle 3. \ p(r) = p(s)
      Proof: Since 1 has only one element.
   \langle 2 \rangle 4. r = s
      Proof: Axiom of Tabulations.
\langle 1 \rangle 4. For all x : \text{El}(A), we have P[A, x] if and only if there exists b : \text{El}(B)
        such that i(b) = x.
   \langle 2 \rangle 1. Let: x : \text{El}(A)
   \langle 2 \rangle 2. If P[A, x] then there exists b : El(B) such that i(b) = x
      \langle 3 \rangle 1. Assume: P[A, x]
      \langle 3 \rangle 2. *Sx
          Proof: \langle 1 \rangle 1
      \langle 3 \rangle 3. There exists b : \text{El}(B) such that p(b) = * and i(b) = x
          Proof: Axiom of Tabulations.
   \langle 2 \rangle 3. For all b : \text{El}(B) we have P[A, i(b)]
      \langle 3 \rangle 1. Let: b : \text{El}(B)
      \langle 3 \rangle 2. p(b)Si(b)
          Proof: Axiom of Tabulations.
      \langle 3 \rangle 3. \ P[A, i(b)]
          Proof: \langle 1 \rangle 1
```

## 1.4 Composition

**Definition 1.18** (Composite). Let  $\phi : A \hookrightarrow B$  and  $\psi : B \hookrightarrow C$ . The *composite*  $\psi \circ \phi : A \hookrightarrow C$  is the relation such that  $a(\psi \circ \phi)c$  iff there exists b such that  $a\phi b$  and  $b\psi c$ .

**Definition 1.19** (Identity). For any set A, the *identity* function  $id_A : A \to A$  is the function defined by  $id_A(a) = a$ .

**Theorem 1.20.** Composition of relations is associative, and the identity function is an identity for composition. The composite of functions is a function. The composite of injective functions is injective. The composite of surjective functions is surjective. The composite of bijections is a bijection. A function  $f: A \to B$  is a bijection iff there exists a function  $f^{-1}: B \to A$  such that  $f^{-1}f = \mathrm{id}_A$  and  $ff^{-1} = \mathrm{id}_B$ , in which case  $f^{-1}$  is unique.

#### 1.5 Axioms Part Two

**Axiom 1.21** (Power Set). For any set A, there exists a set  $\mathcal{P}A$ , the power set of A, and a relation  $\in$ :  $A \hookrightarrow \mathcal{P}A$ , called membership, such that, for any subset S of A, there exists a unique  $\overline{S} \in \mathcal{P}A$  such that, for all  $x \in A$ , we have  $x \in \overline{S}$  if and only if  $x \in S$ .

We usually write just S for  $\overline{S}$ .

**Axiom Schema 1.22** (Collection). Let P[X, Y, x] be a formula with set variables X and Y and an element variable  $x \in X$ . Then the following is an axiom. For any set A, there exists a set B, a function  $p: B \to A$ , a set Y and a

•  $\forall b \in B.P[A, \{y \in Y : bMy\}, p(b)]$ 

relation  $M: B \hookrightarrow Y$  such that:

• For all  $a \in A$ , if  $\exists Y.P[A,Y,a]$ , then there exists  $b \in B$  such that a = p(b).

**Definition 1.23** (Universe). Let  $E: U \hookrightarrow X$  be a relation. Let us say that a set A is *small* iff there exists  $u \in U$  such that  $A \approx \{x \in X : uEx\}$ .

Then (U, X, E) form a *universe* if and only if:

- $\mathbb{N}$  is U-small.
- For any U-small sets A and B and relation  $R:A\hookrightarrow B$ , the tabulation of R is U-small.
- If A is U-small then so is  $\mathcal{P}A$
- Let  $f: A \to B$  be a function. If B is U-small and  $f^{-1}(b)$  is U-small for all  $b \in B$ , then A is U-small.
- If  $p: B \twoheadrightarrow A$  is a surjective function such that A is U-small, then there exists a U-small set C, a surjection  $q: C \twoheadrightarrow A$ , and a function  $f: C \to B$  such that q = pf.

**Axiom 1.24** (Universe). There exists a universe.

Let  $E:U\hookrightarrow X$  be a universe. We shall say a set is small iff it is U-small, and large otherwise.

#### 1.6 Cartesian Product

**Definition 1.25** (Cartesian Product). Let A and B be sets. The *Cartesian product* of A and B,  $A \times B$ , is the tabulation of the relation  $A \hookrightarrow B$  that holds for all  $a \in A$  and  $b \in B$ . The associated functions  $\pi_1 : A \times B \to A$  and  $\pi_2 : A \times B \to B$  are called the *projections*.

Given  $a \in A$  and  $b \in B$ , we write (a, b) for the unique element of  $A \times B$  such that  $\pi_1(a, b) = a$  and  $\pi_2(a, b) = b$ .

# 1.7 Quotient Sets

**Proposition 1.26.** Let  $\sim$  be an equivalence relation on X. Then there exists a set  $X/\sim$ , the quotient set of X with respect to  $\sim$ , and a surjective function  $\pi: X \twoheadrightarrow X/\sim$ , the canonical projection, such that, for all  $x,y: \mathrm{El}(X)$ , we have  $x \sim y$  if and only if  $\pi(x) = \pi(y)$ .

Further, if  $p: X \twoheadrightarrow Q$  is another quotient with respect to  $\sim$ , then there exists a unique bijection  $\phi: X/\sim \approx Q$  such that  $\phi \circ \pi = p$ .

# Topology

# 2.1 Topological Spaces

**Definition 2.1** (Topological Space). Let X be a set and  $\mathcal{O} \subseteq \mathcal{P}X$ . Then we say  $(X, \mathcal{O})$  is a *topological space* iff:

- For any  $\mathcal{U} \subseteq \mathcal{O}$  we have  $\bigcup \mathcal{U} \in \mathcal{O}$ .
- For any  $U, V \in \mathcal{O}$  we have  $U \cap V \in \mathcal{O}$ .
- $X \in \mathcal{O}$

We call  $\mathcal{O}$  the topology of the topological space, and call its elements open sets. We shall often write X for the topological space  $(X, \mathcal{O})$ .

**Definition 2.2** (Closed Set). Let X be a topological space and  $A \subseteq X$ . Then A is *closed* iff X - A is open.

**Proposition 2.3.** A set B is open if and only if X - B is closed.

**Proposition 2.4.** Let X be a set and  $C \subseteq \mathcal{P}X$ . Then there exists a topology  $\mathcal{O}$  on X such that C is the set of closed sets if and only if:

- For any  $\mathcal{D} \subseteq \mathcal{C}$  we have  $\bigcap \mathcal{D} \in \mathcal{C}$
- For any  $C, D \in \mathcal{C}$  we have  $C \cup D \in \mathcal{C}$ .
- $\varnothing \in \mathcal{C}$

In this case,  $\mathcal{O}$  is unique and is given by  $\mathcal{O} = \{X - C : C \in \mathcal{C}\}.$ 

**Definition 2.5** (Neighbourhood). Let X be a topological space,  $Sx \in X$  and  $U \subseteq X$ . Then U is a *neighbourhood* of x, and x is an *interior* point of U, iff there exists an open set V such that  $x \in V \subseteq U$ .

**Proposition 2.6.** A set B is open if and only if it is a neighbourhood of each of its points.

**Proposition 2.7.** Let X be a set and  $\mathcal{N}: X \to \mathcal{P}X$ . Then there exists a topology  $\mathcal{O}$  on X such that, for all  $x \in X$ , we have  $\mathcal{N}_x$  is the set of neighbourhoods of x, if and only if:

- For all  $x \in X$  and  $N \in \mathcal{N}_x$  we have  $x \in N$
- For all  $x \in X$  we have  $X \in \mathcal{N}_x$
- For all  $x \in X$ ,  $N \in \mathcal{N}_x$  and  $V \subseteq \mathcal{P}X$ , if  $N \subseteq V$  then  $V \in \mathcal{N}_x$
- For all  $x \in X$  and  $M, N \in \mathcal{N}_x$  we have  $M \cap N \in \mathcal{N}_x$
- For all  $x \in X$  and  $N \in \mathcal{N}_x$ , there exists  $M \in \mathcal{N}_x$  such that  $M \subseteq N$  and  $\forall y \in M.M \in \mathcal{N}_y$ .

In this case,  $\mathcal{O}$  is unique and is given by  $\mathcal{O} = \{U : \forall x \in U.U \in \mathcal{N}_x\}.$ 

**Definition 2.8** (Exterior Point). Let X be a topological space,  $x \in X$  and  $B \subseteq X$ . Then x is an *exterior point* of B iff B - X is a neighbourhood of x.

**Definition 2.9** (Boundary Point). Let X be a topological space,  $x \in X$  and  $B \subseteq X$ . Then x is a boundary point of B iff it is neither an interior point nor an exterior point of B.

**Definition 2.10** (Interior). Let X be a topological space and  $B \subseteq X$ . The *interior* of B,  $B^{\circ}$ , is the set of all interior points of B.

**Proposition 2.11.** The interior of B is the union of all the open sets included in B.

**Definition 2.12** (Closure). Let X be a topological space and  $B \subseteq X$ . The *closure* of B,  $\overline{B}$ , is the set of all points that are not exterior points of B.

**Proposition 2.13.** The closure of B is the intersection of all the closed sets that include B.

**Proposition 2.14.** A set B is open iff  $X - B = \overline{X - B}$ .

**Proposition 2.15** (Kuratowski Closure Axioms). Let X be a set and  $\neg: \mathcal{P}X \to \mathcal{P}X$ . Then there exists a topology  $\mathcal{O}$  such that, for all  $B \subseteq X$ ,  $\overline{B}$  is the closure of B, if and only if:

- $\overline{\varnothing} = \varnothing$
- For all  $A \subseteq X$  we have  $A \subseteq \overline{A}$
- For all  $A \subseteq X$  we have  $\overline{\overline{A}} = \overline{A}$
- For all  $A, B \subseteq X$  we have  $\overline{A \cup B} = \overline{A} \cup \overline{B}$

In this case,  $\mathcal{O}$  is unique and is defined by  $\mathcal{O} = \{U : X - U = \overline{X - U}\}.$ 

#### 2.1.1 Subspaces

**Definition 2.16** (Subspace). Let X be a topological space and  $X_0 \subseteq X$ . The subspace topology on  $X_0$  is  $\{U \cap X_0 : U \text{ is open in } X\}$ .

#### 2.1.2 Topological Disjoint Union

**Definition 2.17.** Let X and Y be topological spaces. The *disjoint union* is X+Y where  $U\subseteq X+Y$  is open if and only if  $\kappa_1^{-1}(U)$  is open in X and  $\kappa_2^{-1}(U)$  is open in Y.

#### 2.1.3 Product Topology

**Definition 2.18.** Let X and Y be topological spaces. The *product topology* on  $X \times Y$  is the set of all subsets  $W \subseteq X \times Y$  such that, for all  $(x, y) \in W$ , there exist neighbourhoods U of x in X and Y of y in Y such that  $U \times V \subseteq W$ .

#### 2.1.4 Bases

**Definition 2.19** (Basis). Let X be a topological space. A *basis* for the topology on X is a set of open sets  $\mathcal{B}$  such that every open set is the union of a subset of  $\mathcal{B}$ 

#### 2.1.5 Subbases

**Definition 2.20** (Subbasis). Let X be a topological space. A *subbasis* for the topology on X is a subset  $S \subseteq \mathcal{P}X$  such that every open set is a union of finite intersections of S.

#### 2.2 Continuous Functions

**Definition 2.21** (Continuous). Let X and Y be topological spaces. A function  $f: X \to Y$  is *continuous* iff, for every open set V in Y, the inverse image  $f^{-1}(V)$  is open in X.

**Proposition 2.22.** 1.  $id_X$  is continuous

- 2. The composite of two continuous functions is continuous.
- 3. If  $f: X \to Y$  is continuous and  $X_0 \subseteq X$  then  $f \upharpoonright X_0 : X_0 \to Y$  is continuous.
- 4. If  $f: X + Y \to Z$ , then f is continuous iff  $f \circ \kappa_1 : X \to Z$  and  $f \circ \kappa_2 : Y \to Z$  are continuous.
- 5. If  $f: Z \to X \times Y$ , then f is continuous iff  $\pi_1 \circ f$  and  $\pi_2 \circ f$  are continuous.

**Definition 2.23** (Homeomorphism). Let X and Y be topological spaces. A homeomorphism between X and Y is a bijection  $f: X \approx Y$  such that f and  $f^{-1}$  are continuous.

## 2.3 Convergence

**Definition 2.24** (Convergence). Let X be a topological space. Let  $(x_n)$  be a sequence in X. A point a : El(X) is a *limit* of the sequence iff, for every neighbourhood U of a, there exists  $n_0$  such that  $\forall n \ge n_0.x_n \in U$ .

## 2.4 Connected Spaces

**Definition 2.25** (Connected). A topological space is *connected* iff it is not the union of two nonempty open disjoint subsets.

**Proposition 2.26.** The continuous image of a connected space is connected.

**Proposition 2.27.** Let X be a topological space and  $A, B \subseteq X$ . If  $X = A \cup B$ ,  $A \cap B \neq \emptyset$ , and A and B are connected, then X is connected.

**Proposition 2.28.** If X and Y are nonempty topological spaces, then  $X \times Y$  is connected if and only if X and Y are connected.

**Definition 2.29** (Path-connected). A topological space X is path-connected iff, for any points  $a, b \in X$ , there exists a continuous function  $\alpha : [0,1] \to X$ , called a path, such that  $\alpha(0) = a$  and  $\alpha(1) = b$ .

**Proposition 2.30.** The continuous image of a path connected space is path connected.

**Proposition 2.31.** Let X be a topological space and  $A, B \subseteq X$ . If  $X = A \cup B$ ,  $A \cap B \neq \emptyset$ , and A and B are path connected, then X is path connected.

**Proposition 2.32.** If X and Y are nonempty topological spaces, then  $X \times Y$  is path connected if and only if X and Y are path connected.

# 2.5 Hausdorff Spaces

**Definition 2.33** (Hausdorff). A topological space is a *Hausdorff* space or a  $T_2$  space iff any two distinct points have disjoint neighbourhoods.

**Proposition 2.34.** In a Hausdorff space, a sequence has at most one limit.

**Proposition 2.35.** 1. Every subspace of a Hausdorff space is Hausdorff.

- 2. The disjoint union of two Hausdorff spaces is Hausdorff.
- 3. The product of two Hausdorff spaces is Hausdorff.

### 2.6 Compactness

**Definition 2.36** (Compact). A topological space is *compact* iff every open cover has a finite subcover.

**Proposition 2.37.** Let X be a compact topological space. Let P be a set of open sets such that, for all  $U, V \in P$ , we have  $U \cup V \in P$ . Assume that every point has an open neighbourhood in P. Then  $X \in P$ .

#### PROOF:

```
\langle 1 \rangle 1. P is an open cover of X
\langle 1 \rangle 2. PICK a finite subcover U_1, \dots, U_n \in P
\langle 1 \rangle 3. X = U_1 \cup \dots \cup U_n \in P
```

**Corollary 2.37.1.** Let f be a compact space and  $f: X \to \mathbb{R}$  be locally bounded. Then f is bounded.

PROOF: Take  $P = \{U \text{ open in } X : f \text{ is bounded on } U\}$ .  $\square$ 

**Proposition 2.38.** The continuous image of a compact space is compact.

**Proposition 2.39.** A closed subspace of a compact space is compact.

**Proposition 2.40.** Let X and Y be nonempty spaces. Then the following are equivalent.

- 1. X and Y are compact.
- 2. X + Y is compact.
- 3.  $X \times Y$  is compact.

**Proposition 2.41.** A compact subspace of a Hausdorff space is closed.

**Proposition 2.42.** A continuous bijection from a compact space to a Hausdorff space is a homeomorphism.

# 2.7 Quotient Spaces

**Definition 2.43** (Quotient Space). Let X be a topological space and  $\sim$  an equivalence relation on X. The *quotient topology* on  $X/\sim$  is defined by: U:  $\mathrm{El}(\mathcal{P}X)$  is open in  $X/\sim$  if and only if  $\pi^{-1}(U)$  is open in X.

**Proposition 2.44.** Let X and Y be topological spaces. Let  $\sim$  be an equivalence relation on X. Let  $f: X/\sim \to Y$ . Then f is continuous if and only if  $f\circ \pi$  is continuous.

**Proposition 2.45.** Let X and Y be topological spaces. Let  $\sim$  be an equivalence relation on X. Let  $\phi: Y \to X/\sim$ .

Assume that, for all  $y \in Y$ , there exists a neighbourhood U of y and a continuous function  $\Phi: U \to X$  such that  $\pi \circ \Phi = \phi \upharpoonright U$ . Then  $\phi$  is continuous.

**Proposition 2.46.** A quotient of a connected space is connected.

**Proposition 2.47.** A quotient of a path connected space is path connected.

**Proposition 2.48.** Let X be a topological space and  $\sim$  an equivalence relation on X. If  $X/\sim$  is Hausdorff then every equivalence class of  $\sim$  is closed in X.

## 2.8 Metric Spaces

**Definition 2.49** (Metric Space). Let X be a set and  $d: X^2 \to \mathbb{R}$ . We say (X, d) is a *metric space* iff:

- For all  $x, y \in X$  we have  $d(x, y) \ge 0$
- For all  $x, y \in X$  we have d(x, y) = 0 iff x = y
- For all  $x, y \in X$  we have d(x, y) = d(y, x)
- (Triangle Inequality) For all  $x, y, z \in X$  we have  $d(x, z) \leq d(x, y) + d(y, z)$

We call d the *metric* of the metric space (X, d). We often write X for the metric space (X, d).

**Definition 2.50** (Topology of a Metric Space). Let (X,d) be a metric space. The topology induced by the metric d is defined by: for  $V \subseteq X$ , we have V is open if and only if, for all  $x \in V$ , there exists  $\epsilon > 0$  such that  $\{y \in X : d(x,y) < \epsilon\} \subseteq V$ .

**Definition 2.51** (Metrizable). A topological space is *metrizable* iff there exists a metric that induces its topology.

**Proposition 2.52.** Every metrizable space is Hausdorff.

# **Topological Groups**

**Definition 3.1** (Topological Group). A topological group is a group G with a topology such that the function  $G^2 \to G$  that maps (x, y) to  $xy^{-1}$  is continuous.

**Example 3.2.**  $GL(n,\mathbb{R})$  and  $GL(n,\mathbb{C})$  are topological groups.

**Proposition 3.3.** Any subgroup of a topological group is a topological group under the subspace topology.

**Definition 3.4** (Homogeneous Space). A homogeneous space is a topological space of the form G/H, where G is a topological group and H is a normal subgroup of G, under the quotient topology.

**Proposition 3.5.** Let G be a topological group and H a normal subgroup of G. Then G/H is Hausdorff if and only if H is closed.

Proof: See Bourbaki, N., General Topology. III.12

#### 3.1 Continuous Actions

**Definition 3.6** (Continuous Action). Let G be a topological group and X a topological space. A *continuous action* of G on X is a continuous function  $\cdot: G \times X \to X$  such that:

- $\forall x : \text{El}(X) . ex = x$
- $\forall g, h : \text{El}(G) . \forall x : \text{El}(X) . g(hx) = (gh)x$

A G-space consists of a topological space X and a continuous action of G on X.

**Definition 3.7** (Orbit). Let X be a G-space and  $x \in X$ . The *orbit* of x is  $\{gx : g \in G\}$ .

# Topological Vector Spaces

**Definition 4.1** (Topological Vector Space). Let K be either  $\mathbb{R}$  or  $\mathbb{C}$ . A topological vector space over K consists of a vector space E over K and a topology on E such that:

- Substraction is a continuous function  $E^2 \to E$
- Multiplication is a continuous function  $K \times E \to E$

**Proposition 4.2.** Every topological vector space is a topological group under addition.

Proof: Immediate from the definition.  $\square$ 

**Theorem 4.3.** The usual topology on a finite dimensional vector space over K is the only one that makes it into a Hausdorff topological vector space.

PROOF: See Bourbaki. Elements de Mathematique, Livre V: Espaces Vectoriels Topologiques, Th. 2, p. 18  $\square$ 

**Proposition 4.4.** Let E be a topological vector space and  $E_0$  a subspace of E. Then  $\overline{E_0}$  is a subspace of E.

**Definition 4.5.** Let E be a topological vector space. The topological space associated with E is  $E/\{0\}$ .

# 4.1 Cauchy Sequences

**Definition 4.6** (Cauchy Sequence). Let E be a topological vector space. A sequence  $(x_n)$  in E is a *Cauchy sequence* iff, for every neighbourhood U of 0, there exists  $n_0$  such that  $\forall m, n \ge n_0.x_n - x_m \in U$ .

**Definition 4.7** (Complete Topological Vector Space). A topological vector space is *complete* iff every Cauchy sequence converges.

#### 4.2 Seminorms

**Definition 4.8** (Seminorm). Let E be a vector space over K. A seminorm on E is a function  $\| \| : E \to \mathbb{R}$  such that:

- 1.  $\forall x : \text{El}(E) . ||x|| \ge 0$
- 2.  $\forall \alpha : \text{El}(K) . \forall x : \text{El}(E) . ||\alpha x|| = |\alpha||x||$
- 3. Triangle Inequality  $\forall x, y : \text{El}(E) . ||x + y|| \le ||x|| + ||y||$

**Example 4.9.** The function that maps  $(x_1, \ldots, x_n)$  to  $|x_i|$  is a seminorm on  $\mathbb{R}^n$ .

**Definition 4.10.** Let E be a vector space over K. Let  $\Lambda$  be a set of seminorms on E. The topology generated by  $\Lambda$  is the topology generated by the subbasis consisting of all sets of the form  $B_{\epsilon}^{\lambda}(x) = \{y \in E : \lambda(y-x) < \epsilon\}$  for  $\epsilon > 0, \lambda \in \Lambda$  and x : El(E).

**Proposition 4.11.** E is a topological vector space under this topology. It is Hausdorff iff, for all x : El(E), if  $\forall \lambda \in \Lambda.\lambda(x) = 0$  then x = 0.

## 4.3 Fréchet Spaces

**Definition 4.12** (Pre-Fréchet Space). A *pre-Fréchet space* is a Hausdorff topological vector space whose topology is generated by a countable set of seminorms.

**Proposition 4.13.** Let E be a pre-Fréchet space whose topology is generated by the family of seminorms  $\{\| \|_n : n \in \mathbb{Z}^+ \}$ . Then

$$d(x,y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \frac{\|x - y\|_n}{1 + \|x - y\|_n}$$

is a metric that induces the same topology. The two definitions of Cauchy sequence agree.

**Definition 4.14** (Fréchet Space). A *Fréchet space* is a complete pre-Fréchet space.

# 4.4 Normed Spaces

**Definition 4.15** (Normed Space). Let E be a vector space over K. A norm on E is a function  $\| \ \| : E \to \mathbb{R}$  is a seminorm such that,  $\forall x \in E. \|x\| = 0 \Leftrightarrow x = 0$ . A normed space consists of a vector space with a norm.

**Proposition 4.16.** If E is a normed space then d(x,y) = ||x-y|| is a metric on E that makes E into a topological vector space. The two definitions of Cauchy sequence agree on E.

**Proposition 4.17.** Let  $\| \ \|$  be a seminorm on the vector space E. Then  $\| \ \|$  defines a norm on  $E/\overline{\{0\}}$ .

## 4.5 Inner Product Spaces

**Proposition 4.18.** If E is an inner product space then  $||x|| = \sqrt{\langle x, x \rangle}$  is a norm on E.

## 4.6 Banach Spaces

**Definition 4.19** (Banach Space). A Banach space is a complete normed space.

**Example 4.20.** For any topological space X, the set C(X) of bounded continuous functions  $X \to \mathbb{R}$  is a Banach space under  $||f|| = \sup_{x \in X} |f(x)|$ .

## 4.7 Hilbert Spaces

**Definition 4.21** (Hilbert Space). A *Hilbert space* is a complete inner product space.

**Example 4.22.** The set of square-integrable functions is the set of Lebesgue integrable functions  $[-\pi, \pi] \to \mathbb{R}$  quotiented by:  $f \sim g$  iff  $\{x \in [-\pi, \pi] : f(x) \neq g(x)\}$  has measure 0. This is a Hilbert space under

$$\langle f, g \rangle = \frac{1}{\pi} \int_{-\pi} \pi f(x) g(x) dx$$
.

# 4.8 Locally Convex Spaces

**Definition 4.23** (Locally Convex Space). A topological vector space is *locally convex* iff every neighbourhood of 0 includes a convex neighbourhood of 0.

**Proposition 4.24.** A topological vector space is locally convex if and only if its topology is generated by a set of seminorms.

PROOF: See Köthe, G. Topological Vector Spaces 1. Section 18.  $\square$ 

**Proposition 4.25.** A locally convex topological vector space is a pre-Fréchet space if and only if it is metrizable.

PROOF: See Köthe, G. Topological Vector Spaces 1. Section 18.

**Example 4.26.** Let E be an infinite dimensional Hilbert space. Let E' be the same vector space under the *weak topology*, the coarsest topology such that every continuous linear map  $E \to \mathbb{R}$  is continuous as a map  $E' \to \mathbb{R}$ . Then E is locally convex Hausdorff but not metrizable.

Proof: See Dieudonne, J. A., Treatise on Analysis, Vol. II, New York and London: Academic Press, 1970, p. 76.