## Mathematics

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September 20, 2023

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# Primitive Terms and Axioms

#### 1.1 Primitive Terms

Let there be sets. We write A: Set for: A is a set.

For any set A, let there be *elements* of A. We write a : El(A) for: a is an element of A.

For any sets A and B, let there be functions from A to B. We write  $f:A\to B$  iff f is a function from A to B.

For any function  $f: A \to B$  and element a: El(A), let there be an element f(a): El(B), the value of the function f at the argument a.

#### 1.2 Axioms

**Axiom Schema 1.1** (Choice). Let P[X, Y, x, y] be a formula where X and Y are set variables, x : El(X) and y : El(Y). Then the following is an axiom.

Let A and B be sets. Assume that, for all a : El(A), there exists b : El(B) such that P[A, B, a, b]. Then there exists a function  $f : A \to B$  such that  $\forall a : El(A) . P[A, B, a, f(a)]$ .

**Axiom 1.2** (Pairing). For any sets A and B, there exists a set  $A \times B$ , the Cartesian product of A and B, and functions  $\pi_1 : A \times B \to A$  and  $\pi_2 : A \times B \to B$  such that, for all a : El(A) and b : El(B), there exists a unique  $(a,b) : \text{El}(A \times B)$  such that  $\pi_1(a,b) = a$  and  $\pi_2(a,b) = b$ .

**Definition 1.3** (Injective). A function  $f: A \to B$  is injective or an injection iff, for all x, y: El(A), if f(x) = f(y) then x = y.

**Axiom Schema 1.4** (Separation). For every property P[X,x] where X is a set variable and x : El(X), the following is an axiom:

For every set A, there exists a set  $S = \{x : \text{El}(A) \mid P[A, x]\}$  and an injection  $i: S \to A$  such that, for all x: El(A), we have

$$(\exists y : S.i(y) = x) \Leftrightarrow P[A, x]$$
.

**Axiom 1.5** (Infinity). There exists a set  $\mathbb{N}$ , an element  $0 : \text{El}(\mathbb{N})$ , and a function  $s : \mathbb{N} \to \mathbb{N}$  such that:

- $\forall n : \text{El}(\mathbb{N}) . s(n) \neq 0$
- $\forall m, n : \text{El}(\mathbb{N}) . s(m) = s(n) \Rightarrow m = n.$

### 1.3 Consequences of the Axioms

#### 1.3.1 Definitions

**Definition 1.6.** Let  $f, g: A \to B$ . We say f and g are equal, f = g, iff  $\forall x : \text{El}(A) . f(x) = g(x)$ .

**Definition 1.7** (Surjective). A function  $f: A \to B$  is *surjective* iff, for all y: El(B), there exists x: El(A) such that f(x) = y.

**Definition 1.8** (Bijective). A function  $f: A \to B$  is bijective or a bijection iff it is injective and surjective.

Sets A and B are equinumerous,  $A \approx B$ , iff there exists a bijection between them.

If we prove there exists a set X such that P(X), and that any two sets that satisfy P are bijective, then we may introduce a constant C and define "Let C be the set such that P(C)".

**Definition 1.9** (Composition). Given  $f: A \to B$  and  $g: B \to C$ , let  $g \circ f$  be the function such that  $\forall a : \text{El}(A) . (g \circ f)(a) = g(f(a))$ .

#### 1.3.2 The Empty Set

**Theorem 1.10.** There exists a set which has no elements.

Proof:

 $\langle 1 \rangle 1$ . PICK a set A

Proof: By the Axiom of Infinity, a set exists.

 $\langle 1 \rangle 2$ . Let:  $S = \{x : \text{El}(A) \mid \bot \}$  with injection  $i : S \to A$ 

Proof: Axiom of Separation.

 $\langle 1 \rangle 3$ . S has no elements.

**Theorem 1.11.** If E and E' have no elements then  $E \approx E'$ .

Proof:

```
⟨1⟩1. Let: E and E' have no elements. 
⟨1⟩2. Pick a function F: E \to E'.
PROOF: Axiom of Choice since vacuously \forall x : \text{El}\left(E\right). \exists y : \text{El}\left(E'\right). \top. 
⟨1⟩3. F is injective.
PROOF: Vacuously, for all x,y: \text{El}\left(E\right), if F(x) = F(y) then x = y. 
⟨1⟩4. F is surjective.
PROOF: Vacuously, for all y: \text{El}\left(E\right), there exists x: \text{El}\left(E\right) such that F(x) = y.
```

**Definition 1.12** (Empty Set). The *empty set*  $\emptyset$  is the set with no elements.

#### 1.3.3 The Singleton

**Theorem 1.13.** There exists a set that has exactly one element.

#### Proof:

 $\langle 1 \rangle 1$ . PICK a set A that has an element.

PROOF: By the Axiom of Infinity, there exists a set that has an element.

 $\langle 1 \rangle 2$ . Pick a : El(A)

 $\langle 1 \rangle 3$ . PICK a set S and injection  $i: S \rightarrow A$  such that, for all x: El(A), there exists s: El(S) such that s=x if and only if x=a

 $\langle 1 \rangle 4$ . S has exactly one element.

**Theorem 1.14.** If A and B both have exactly one element then  $A \approx B$ .

#### Proof:

 $\langle 1 \rangle 1$ . Let: A and B both have exactly one element a and b respectively.

(1)2. Let:  $F: A \to B$  be the function such that, for all x: El(A), we have  $(x = a \land F(x) = b)$ 

 $\langle 1 \rangle 3$ . F is a bijection.

**Definition 1.15** (Singleton). Let 1 be the set that has exactly one element. Let \* be its element.

#### 1.3.4 Subsets

**Definition 1.16** (Subset). A *subset* of a set A consists of a set S and an injection  $i: S \rightarrow A$ . We write (S, i): Sub(A).

We say two subsets (S, i) and (T, j) are equal, (S, i) = (T, j), iff there exists a bijection  $\phi : S \approx T$  such that  $j \circ \phi = i$ .

**Definition 1.17** (Membership). Given (S, i): Sub(A) and a: El(A), we write  $a \in S$  for  $\exists s : \text{El}(S) . i(s) = a$ .

### 1.4 Composition

**Definition 1.18** (Composite). Let  $\phi : A \hookrightarrow B$  and  $\psi : B \hookrightarrow C$ . The *composite*  $\psi \circ \phi : A \hookrightarrow C$  is the relation such that  $a(\psi \circ \phi)c$  iff there exists b such that  $a\phi b$  and  $b\psi c$ .

**Definition 1.19** (Identity). For any set A, the *identity* function  $id_A : A \to A$  is the function defined by  $id_A(a) = a$ .

**Theorem 1.20.** Composition of relations is associative, and the identity function is an identity for composition. The composite of functions is a function. The composite of injective functions is injective. The composite of surjective functions is surjective. The composite of bijections is a bijection. A function  $f: A \to B$  is a bijection iff there exists a function  $f^{-1}: B \to A$  such that  $f^{-1}f = \mathrm{id}_A$  and  $ff^{-1} = \mathrm{id}_B$ , in which case  $f^{-1}$  is unique.

#### 1.5 Axioms Part Two

**Axiom 1.21** (Power Set). For any set A, there exists a set  $\mathcal{P}A$ , the power set of A, and a relation  $\in$ :  $A \hookrightarrow \mathcal{P}A$ , called membership, such that, for any subset S of A, there exists a unique  $\overline{S} \in \mathcal{P}A$  such that, for all  $x \in A$ , we have  $x \in \overline{S}$  if and only if  $x \in S$ .

We usually write just S for  $\overline{S}$ .

**Axiom Schema 1.22** (Collection). Let P[X,Y,x] be a formula with set variables X and Y and an element variable  $x \in X$ . Then the following is an axiom. For any set A, there exists a set B, a function  $p:B \to A$ , a set Y and a relation  $M:B \hookrightarrow Y$  such that:

- $\forall b \in B.P[A, \{y \in Y : bMy\}, p(b)]$
- For all  $a \in A$ , if  $\exists Y.P[A, Y, a]$ , then there exists  $b \in B$  such that a = p(b).

**Definition 1.23** (Universe). Let  $E:U \hookrightarrow X$  be a relation. Let us say that a set A is *small* iff there exists  $u \in U$  such that  $A \approx \{x \in X : uEx\}$ .

Then (U, X, E) form a *universe* if and only if:

- $\mathbb{N}$  is U-small.
- For any *U*-small sets *A* and *B* and relation  $R:A \hookrightarrow B$ , the tabulation of *R* is *U*-small.
- If A is U-small then so is  $\mathcal{P}A$
- Let  $f: A \to B$  be a function. If B is U-small and  $f^{-1}(b)$  is U-small for all  $b \in B$ , then A is U-small.
- If  $p: B \twoheadrightarrow A$  is a surjective function such that A is U-small, then there exists a U-small set C, a surjection  $q: C \twoheadrightarrow A$ , and a function  $f: C \to B$  such that q = pf.

Axiom 1.24 (Universe). There exists a universe.

Let  $E:U \hookrightarrow X$  be a universe. We shall say a set is *small* iff it is *U*-small, and *large* otherwise.

#### 1.6 Cartesian Product

**Definition 1.25** (Cartesian Product). Let A and B be sets. The Cartesian product of A and B,  $A \times B$ , is the tabulation of the relation  $A \hookrightarrow B$  that holds for all  $a \in A$  and  $b \in B$ . The associated functions  $\pi_1 : A \times B \to A$  and  $\pi_2 : A \times B \to B$  are called the projections.

Given  $a \in A$  and  $b \in B$ , we write (a, b) for the unique element of  $A \times B$  such that  $\pi_1(a, b) = a$  and  $\pi_2(a, b) = b$ .

### 1.7 Quotient Sets

**Proposition 1.26.** Let  $\sim$  be an equivalence relation on X. Then there exists a set  $X/\sim$ , the quotient set of X with respect to  $\sim$ , and a surjective function  $\pi:X\twoheadrightarrow X/\sim$ , the canonical projection, such that, for all  $x,y:\operatorname{El}(X)$ , we have  $x\sim y$  if and only if  $\pi(x)=\pi(y)$ .

Further, if  $p: X \to Q$  is another quotient with respect to  $\sim$ , then there exists a unique bijection  $\phi: X/\sim \approx Q$  such that  $\phi \circ \pi = p$ .

### 1.8 Partitions

**Definition 1.27** (Partition). A partition of a set X is a set of pairwise disjoint subsets of X whose union is X.

## Category Theory

### 2.1 Categories

**Definition 2.1.** A category C consists of:

- a set Ob(C) of *objects*
- for any objects X and Y, a set Mor(X,Y) of morphisms from X to Y. We write  $f: X \to Y$  for f: El(Mor(X,Y)).
- for any objects X, Y and Z, a function  $\circ : \text{Mor}(Y, Z) \times \text{Mor}(X, Y) \to \text{Mor}(X, Z)$ , called *composition*.

such that:

- Given  $f: X \to Y$ ,  $g: Y \to Z$  and  $h: Z \to W$ , we have  $h \circ (g \circ f) = (h \circ g) \circ f$
- For any object X, there exists a morphism  $id_X : X \to X$ , the *identity morphism* on X, such that:
  - for any object Y and morphism  $f: Y \to X$  we have  $\mathrm{id}_X \circ f = f$
  - for any object Y and morphism  $f: X \to Y$  we have  $f \circ id_X = f$

The identity morphism on an object is unique.

**Definition 2.2.** Let **Set** be the category of small sets and functions.

Section.

Retraction.

Isomorphism.

Define the opposite category.

Initial object.

Terminal object.

Zero object.

**Proposition 2.3.** The empty set is initial in **Set**.

PROOF: For any set A, the nowhere-defined function is the unique function  $\emptyset \to A$ .  $\square$ 

Proposition 2.4. 1 is terminal in Set.

PROOF: For any set A, the constant function to \* is the only function  $A \to 1$ .

Proposition 2.5. There is no zero object in Set.

Proof: Since  $\emptyset \not\approx 1$ .  $\square$ 

### 2.2 Functors

**Definition 2.6** (Functor). Let  $\mathcal C$  and  $\mathcal D$  be categories. A functor  $F:\mathcal C\to\mathcal D$  consists of:

- a function  $F: \mathrm{Ob}(\mathcal{C}) \to \mathrm{Ob}(\mathcal{D})$
- for every morphism  $f:A\to B$  in  $\mathcal C$ , a morphism  $Ff:FA\to FB$  in  $\mathcal D$

such that:

- for all A : El(Ob(C)) we have  $Fid_A = id_{FA}$
- for any morphism  $f:A\to B$  and  $g:B\to C$  in  $\mathcal C,$  we have  $F(g\circ f)=Fg\circ Ff$

Define the identity functor, constant functors.

Functors preserve isomorphisms.

## Group Theory

**Definition 3.1.** Let  $\mathbf{Grp}$  be the category of small groups and group homomorphisms.

**Definition 3.2.** We identify any group G with the category with one object whose morphisms are the elements of G with composition given by the multiplication in G.

## Linear Algebra

**Definition 4.1.** For any field K, let  $\mathbf{Vect}_K$  be the category of small vector spaces over K and linear transformations.

Dual space functor  $\mathbf{Vect}_K^{\mathrm{op}} \to \mathbf{Vect}_K$ .

## Topology

### 5.1 Topological Spaces

**Definition 5.1** (Topological Space). Let X be a set and  $\mathcal{O} \subseteq \mathcal{P}X$ . Then we say  $(X, \mathcal{O})$  is a *topological space* iff:

- For any  $\mathcal{U} \subseteq \mathcal{O}$  we have  $\bigcup \mathcal{U} \in \mathcal{O}$ .
- For any  $U, V \in \mathcal{O}$  we have  $U \cap V \in \mathcal{O}$ .
- $X \in \mathcal{O}$

We call  $\mathcal{O}$  the *topology* of the topological space, and call its elements *open* sets. We shall often write X for the topological space  $(X, \mathcal{O})$ .

**Definition 5.2** (Closed Set). Let X be a topological space and  $A \subseteq X$ . Then A is *closed* iff X - A is open.

**Proposition 5.3.** A set B is open if and only if X - B is closed.

**Proposition 5.4.** Let X be a set and  $C \subseteq \mathcal{P}X$ . Then there exists a topology  $\mathcal{O}$  on X such that C is the set of closed sets if and only if:

- For any  $\mathcal{D} \subseteq \mathcal{C}$  we have  $\bigcap \mathcal{D} \in \mathcal{C}$
- For any  $C, D \in \mathcal{C}$  we have  $C \cup D \in \mathcal{C}$ .
- $\varnothing \in \mathcal{C}$

In this case,  $\mathcal{O}$  is unique and is given by  $\mathcal{O} = \{X - C : C \in \mathcal{C}\}.$ 

**Definition 5.5** (Neighbourhood). Let X be a topological space,  $Sx \in X$  and  $U \subseteq X$ . Then U is a *neighbourhood* of x, and x is an *interior* point of U, iff there exists an open set V such that  $x \in V \subseteq U$ .

**Proposition 5.6.** A set B is open if and only if it is a neighbourhood of each of its points.

**Proposition 5.7.** Let X be a set and  $\mathcal{N}: X \to \mathcal{P}X$ . Then there exists a topology  $\mathcal{O}$  on X such that, for all  $x \in X$ , we have  $\mathcal{N}_x$  is the set of neighbourhoods of x, if and only if:

- For all  $x \in X$  and  $N \in \mathcal{N}_x$  we have  $x \in N$
- For all  $x \in X$  we have  $X \in \mathcal{N}_x$
- For all  $x \in X$ ,  $N \in \mathcal{N}_x$  and  $V \subseteq \mathcal{P}X$ , if  $N \subseteq V$  then  $V \in \mathcal{N}_x$
- For all  $x \in X$  and  $M, N \in \mathcal{N}_x$  we have  $M \cap N \in \mathcal{N}_x$
- For all  $x \in X$  and  $N \in \mathcal{N}_x$ , there exists  $M \in \mathcal{N}_x$  such that  $M \subseteq N$  and  $\forall y \in M.M \in \mathcal{N}_y$ .

In this case,  $\mathcal{O}$  is unique and is given by  $\mathcal{O} = \{U : \forall x \in U.U \in \mathcal{N}_x\}.$ 

**Definition 5.8** (Exterior Point). Let X be a topological space,  $x \in X$  and  $B \subseteq X$ . Then x is an *exterior point* of B iff B - X is a neighbourhood of x.

**Definition 5.9** (Boundary Point). Let X be a topological space,  $x \in X$  and  $B \subseteq X$ . Then x is a boundary point of B iff it is neither an interior point nor an exterior point of B.

**Definition 5.10** (Interior). Let X be a topological space and  $B \subseteq X$ . The *interior* of B,  $B^{\circ}$ , is the set of all interior points of B.

**Proposition 5.11.** The interior of B is the union of all the open sets included in B.

**Definition 5.12** (Closure). Let X be a topological space and  $B \subseteq X$ . The *closure* of B,  $\overline{B}$ , is the set of all points that are not exterior points of B.

**Proposition 5.13.** The closure of B is the intersection of all the closed sets that include B.

**Proposition 5.14.** A set B is open iff  $X - B = \overline{X - B}$ .

**Proposition 5.15** (Kuratowski Closure Axioms). Let X be a set and  $\neg: \mathcal{P}X \to \mathcal{P}X$ . Then there exists a topology  $\mathcal{O}$  such that, for all  $B \subseteq X$ ,  $\overline{B}$  is the closure of B, if and only if:

- $\overline{\varnothing} = \varnothing$
- For all  $A \subseteq X$  we have  $A \subseteq \overline{A}$
- For all  $A \subseteq X$  we have  $\overline{\overline{A}} = \overline{A}$
- For all  $A, B \subseteq X$  we have  $\overline{A \cup B} = \overline{A} \cup \overline{B}$

In this case,  $\mathcal{O}$  is unique and is defined by  $\mathcal{O} = \{U : X - U = \overline{X - U}\}.$ 

#### 5.1.1 Subspaces

**Definition 5.16** (Subspace). Let X be a topological space and  $X_0 \subseteq X$ . The subspace topology on  $X_0$  is  $\{U \cap X_0 : U \text{ is open in } X\}$ .

**Example 5.17.** The unit sphere  $S^2$  is  $\{x \in \mathbb{R}^3 : ||x|| = 1\}$  as a subspace of  $\mathbb{R}^3$ .

#### 5.1.2 Topological Disjoint Union

**Definition 5.18.** Let X and Y be topological spaces. The *disjoint union* is X + Y where  $U \subseteq X + Y$  is open if and only if  $\kappa_1^{-1}(U)$  is open in X and  $\kappa_2^{-1}(U)$  is open in Y.

#### 5.1.3 Product Topology

**Definition 5.19** (Product Topology). Let  $\{X_{\lambda}\}_{{\lambda}\in\Lambda}$  be a family of topological spaces. The *product topology* on  $\prod_{{\lambda}\in\Lambda} X_{\lambda}$  is the coarsest topology such that every projection onto  $X_{\lambda}$  is continuous.

#### 5.1.4 Bases

**Definition 5.20** (Basis). Let X be a topological space. A *basis* for the topology on X is a set of open sets  $\mathcal{B}$  such that every open set is the union of a subset of  $\mathcal{B}$ 

#### 5.1.5 Subbases

**Definition 5.21** (Subbasis). Let X be a topological space. A *subbasis* for the topology on X is a subset  $S \subseteq \mathcal{P}X$  such that every open set is a union of finite intersections of S.

**Definition 5.22** (Space with Basepoint). A space with basepoint is a pair (X, x) where X is a topological space and x : El(X).

#### 5.1.6 Countability Axioms

**Definition 5.23** (Neighbourhood Basis). Let X be a topological space and  $x_0 : \text{El}(X)$ . A *neighbourhood basis* of  $x_0$  is a set  $\mathcal{U}$  of neighbourhoods of  $x_0$  such that every neighbourhood of  $x_0$  includes an element of  $\mathcal{U}$ .

**Definition 5.24** (First Countable). A topological space is *first countable* iff every point has a countable neighbourhood basis.

**Definition 5.25** (Second Countable). A topological space is *second countable* iff it has a countable basis.

Every second countable space is first countable.

A subspace of a first countable space is first countable.

A subspace of a second countable space is second countable.

 $\mathbb{R}^n$  is second countable.

An uncountable discrete space is first countable but not second countable.

**Proposition 5.26.** Let  $\{X_{\lambda}\}_{{\lambda}\in\Lambda}$  be a family of topological spaces such that no  $X_{\lambda}$  is indiscrete. If  $\Lambda$  is uncountable, then  $\prod_{{\lambda}\in\Lambda} X_{\lambda}$  is not first countable.

#### Proof:

- $\langle 1 \rangle 1$ . For all  $\lambda : \text{El}(\Lambda)$ , Pick  $U_{\lambda}$  open in  $X_{\lambda}$  such that  $\emptyset \neq U_{\lambda} \neq X_{\lambda}$ .
- $\langle 1 \rangle 2$ . For all  $\lambda : \text{El}(\lambda)$ , PICK  $x_{\lambda} \in U_{\lambda}$ .
- $\langle 1 \rangle$ 3. Assume: for a contradiction B is a countable neighbourhood basis for  $(x_{\lambda})_{{\lambda} \in {\Lambda}}$ .
- $\langle 1 \rangle 4$ . PICK  $\lambda \in \Lambda$  such that, for all  $U \in B$ , we have  $\pi_{\lambda}(U) = X_{\lambda}$
- $\langle 1 \rangle$ 5. There is no  $U \in \lambda$  such that  $U \subseteq \pi_{\lambda}^{-1}(U_{\lambda})$
- $\langle 1 \rangle 6$ . Q.E.D.

PROOF: This is a contradiction.

#### 5.2 Continuous Functions

**Definition 5.27** (Continuous). Let X and Y be topological spaces. A function  $f: X \to Y$  is *continuous* iff, for every open set V in Y, the inverse image  $f^{-1}(V)$  is open in X.

**Proposition 5.28.** 1.  $id_X$  is continuous

- 2. The composite of two continuous functions is continuous.
- 3. If  $f: X \to Y$  is continuous and  $X_0 \subseteq X$  then  $f \upharpoonright X_0 : X_0 \to Y$  is continuous.
- 4. If  $f: X + Y \to Z$ , then f is continuous iff  $f \circ \kappa_1 : X \to Z$  and  $f \circ \kappa_2 : Y \to Z$  are continuous.
- 5. If  $f: Z \to X \times Y$ , then f is continuous iff  $\pi_1 \circ f$  and  $\pi_2 \circ f$  are continuous.

**Definition 5.29** (Homeomorphism). Let X and Y be topological spaces. A homeomorphism between X and Y is a bijection  $f: X \approx Y$  such that f and  $f^{-1}$  are continuous.

**Definition 5.30** (Retraction). Let X be a topological space and A a subspace of X. A continuous function  $\rho: X \to A$  is a *retraction* iff  $\rho \upharpoonright A = \mathrm{id}_A$ . We say A is a *retract* of X iff there exists a retraction.

**Definition 5.31.** Let **Top** be the category of small topological spaces and continuous functions.

Forgetful functor  $\mathbf{Top} \to \mathbf{Set}$ .

Basepoint preserving continuous functor.

### 5.3 Convergence

**Definition 5.32** (Convergence). Let X be a topological space. Let  $(x_n)$  be a sequence in X. A point a : El(X) is a *limit* of the sequence iff, for every neighbourhood U of a, there exists  $n_0$  such that  $\forall n \ge n_0.x_n \in U$ .

Convergence in a product space is pointwise convergence.

If  $f: X \to Y$  is continuous and  $x_n \to l$  in X then  $f(x_n) \to f(l)$  in Y.

Example 5.33. The converse does not hold.

Let X be the set of all continuous functions  $[0,1] \to [-1,1]$  under the product topology. Let  $i: X \to L^2([0,1])$  be the inclusion.

If  $f_n \to f$  then  $i(f_n) \to i(f)$  — Lebesgue convergence theorem.

We prove that i is not continuous.

Assume for a contradiction i is continuous. Choose a neighbourhood K of 0 in X such that  $\forall \phi \in K_{\epsilon}$ .  $\int \phi^2 < 1/2$ . Let  $K = \prod_{\lambda \in [0,1]} U_{\lambda}$  where  $U_{\lambda} = [-1,1]$  except for  $\lambda = \lambda_1, \ldots, \lambda_n$ . Let  $\phi$  be the function that is 0 at  $\lambda_1, \ldots, \lambda_n$  and 1 everywhere else. Then  $\phi \in K$  but  $\int \phi^2 = 1$ .

**Proposition 5.34.** The converse does hold for first countable spaces. If  $f: X \to Y$  where X is first countable, and Y is a topological space, and whenever  $x_n \to x$  then  $f(x_n) \to f(x)$ , then f is continuous.

### 5.4 Connected Spaces

**Definition 5.35** (Connected). A topological space is *connected* iff it is not the union of two nonempty open disjoint subsets.

**Proposition 5.36.** The continuous image of a connected space is connected.

**Proposition 5.37.** Let X be a topological space and  $A, B \subseteq X$ . If  $X = A \cup B$ ,  $A \cap B \neq \emptyset$ , and A and B are connected, then X is connected.

**Proposition 5.38.** If X and Y are nonempty topological spaces, then  $X \times Y$  is connected if and only if X and Y are connected.

**Definition 5.39** (Path-connected). A topological space X is path-connected iff, for any points  $a, b \in X$ , there exists a continuous function  $\alpha : [0, 1] \to X$ , called a path, such that  $\alpha(0) = a$  and  $\alpha(1) = b$ .

**Proposition 5.40.** The continuous image of a path connected space is path connected.

**Proposition 5.41.** Let X be a topological space and  $A, B \subseteq X$ . If  $X = A \cup B$ ,  $A \cap B \neq \emptyset$ , and A and B are path connected, then X is path connected.

**Proposition 5.42.** If X and Y are nonempty topological spaces, then  $X \times Y$  is path connected if and only if X and Y are path connected.

### 5.5 Hausdorff Spaces

**Definition 5.43** (Hausdorff). A topological space is a *Hausdorff* space or a  $T_2$  space iff any two distinct points have disjoint neighbourhoods.

**Proposition 5.44.** In a Hausdorff space, a sequence has at most one limit.

**Proposition 5.45.** 1. Every subspace of a Hausdorff space is Hausdorff.

- 2. The disjoint union of two Hausdorff spaces is Hausdorff.
- 3. The product of two Hausdorff spaces is Hausdorff.

**Proposition 5.46.** Let A be a topological space and B a Hausdorff space. Let  $f, g: A \to B$  be continuous. Let  $X \subseteq A$  be dense. If f and g agree on X, then f = g.

#### Proof:

- $\langle 1 \rangle 1$ . Assume: for a contradiction  $a \in A$  and  $f(a) \neq g(a)$ .
- $\langle 1 \rangle 2$ . PICK disjoint neighbourhoods U and V of f(a) and g(a) respectively.
- $\langle 1 \rangle 3$ . Pick  $x \in f^{-1}(U) \cap g^{-1}(V)$
- $\langle 1 \rangle 4. \ f(x) = g(x) \in U \cap V$
- $\langle 1 \rangle$ 5. Q.E.D.

Proof: This is a contradiction.

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**Proposition 5.47.** Let X and Y be metric spaces. Let  $f: X \to Y$  be uniformly continuous. Let  $\hat{X}$  and  $\hat{Y}$  be the completions of X and Y. Then f extends uniquely to a continuous map  $\hat{X} \to \hat{Y}$ .

PROOF: The extension maps  $\lim_{n\to\infty} x_n$  to  $\lim_{n\to\infty} f(x_n)$ .  $\square$ 

## 5.6 Separable Spaces

**Definition 5.48** (Separable). A topological space is *separable* iff it has a countable dense subset.

Every second countable space is separable.

## 5.7 Sequential Compactness

**Definition 5.49** (Sequentially Compact). A topological space is *sequentially compact* iff every sequence has a convergent subsequence.

### 5.8 Compactness

**Definition 5.50** (Compact). A topological space is *compact* iff every open cover has a finite subcover.

**Proposition 5.51.** Let X be a compact topological space. Let P be a set of open sets such that, for all  $U, V \in P$ , we have  $U \cup V \in P$ . Assume that every point has an open neighbourhood in P. Then  $X \in P$ .

#### Proof:

- $\langle 1 \rangle 1$ . P is an open cover of X $\langle 1 \rangle 2$ . PICK a finite subcover  $U_1, \dots, U_n \in P$
- $\langle 1 \rangle 3. \ X = U_1 \cup \cdots \cup U_n \in P$

**Corollary 5.51.1.** Let f be a compact space and  $f: X \to \mathbb{R}$  be locally bounded. Then f is bounded.

PROOF: Take  $P = \{U \text{ open in } X : f \text{ is bounded on } U\}$ .  $\square$ 

**Proposition 5.52.** The continuous image of a compact space is compact.

**Proposition 5.53.** A closed subspace of a compact space is compact.

**Proposition 5.54.** Let X and Y be nonempty spaces. Then the following are equivalent.

- 1. X and Y are compact.
- 2. X + Y is compact.
- 3.  $X \times Y$  is compact.

**Proposition 5.55.** A compact subspace of a Hausdorff space is closed.

**Proposition 5.56.** A continuous bijection from a compact space to a Hausdorff space is a homeomorphism.

**Proposition 5.57.** A first countable compact space is sequentially compact.

## 5.9 Quotient Spaces

**Definition 5.58** (Quotient Space). Let X be a topological space and  $\sim$  an equivalence relation on X. The *quotient topology* on  $X/\sim$  is defined by: U:  $\mathrm{El}(\mathcal{P}X)$  is open in  $X/\sim$  if and only if  $\pi^{-1}(U)$  is open in X.

**Proposition 5.59.** Let X and Y be topological spaces. Let  $\sim$  be an equivalence relation on X. Let  $f: X/\sim \to Y$ . Then f is continuous if and only if  $f\circ \pi$  is continuous.

**Proposition 5.60.** Let X and Y be topological spaces. Let  $\sim$  be an equivalence relation on X. Let  $\phi: Y \to X/\sim$ .

Assume that, for all  $y \in Y$ , there exists a neighbourhood U of y and a continuous function  $\Phi: U \to X$  such that  $\pi \circ \Phi = \phi \upharpoonright U$ . Then  $\phi$  is continuous.

**Proposition 5.61.** A quotient of a connected space is connected.

**Proposition 5.62.** A quotient of a path connected space is path connected.

**Proposition 5.63.** Let X be a topological space and  $\sim$  an equivalence relation on X. If  $X/\sim$  is Hausdorff then every equivalence class of  $\sim$  is closed in X.

**Definition 5.64.** Let X be a topological space and  $A_1, \ldots, A_r \subseteq X$ . Then  $X/A_1, \ldots, A_r$  is the quotient space of X with respect to  $\sim$  where  $x \sim y$  iff x = y or  $\exists i (x \in A_i \land y \in A_i)$ .

**Definition 5.65** (Cone). Let X be a topological space. The *cone over* X is the space  $(X \times [0,1])/(X \times \{1\})$ .

**Definition 5.66** (Suspension). Let X be a topological space. The *suspension* of X is the space

$$\Sigma X := (X \times [-1,1])/(X \times \{-1\}), (X \times \{1\})$$

**Definition 5.67** (Wedge Product). Let  $x_0 \in X$  and  $y_0 \in Y$ . The wedge product  $X \vee Y$  is  $(X \times \{y_0\}) \cup (\{x_0\} \times Y)$  as a subspace of  $X \times Y$ .

**Definition 5.68** (Smash Product). Let  $x_0 \in X$  and  $y_0 \in Y$ . The *smash product*  $X \wedge Y$  is  $(X \times Y)/(X \vee Y)$ .

Example 5.69.  $D^n/S^{n-1} \cong S^n$ 

Proof:

 $\langle 1 \rangle 1$ . Let:  $\phi: D^n/S^{n-1} \to S^n$  be the function induced by the map  $D^n \to S^n$  that maps the radii of  $D^n$  onto the meridians of  $S^n$  from the north to the south pole.

 $\langle 1 \rangle 2$ .  $\phi$  is a bijection.

 $\langle 1 \rangle 3$ .  $\phi$  is a homeomorphism.

PROOF: Since  $D^n/S^{n-1}$  is compact and  $S^n$  is Hausdorff.

5.10 Gluing

**Definition 5.70** (Gluing). Let X and Y be topological spaces,  $X_0 \subseteq X$  and  $\phi: X_0 \to Y$  a continuous map. Then  $Y \cup_{\phi} X$  is the quotient space  $(X+Y)/\sim$ , where  $\sim$  is the equivalence relation generated by  $x \sim \phi(x)$  for all x : El(X).

**Proposition 5.71.** *Y* is a subspace of  $Y \cup_{\phi} X$ .

**Definition 5.72.** Let X be a topological space and  $\alpha: X \cong X$  a homeomorphism. Then  $(X \times [0,1])/\alpha$  is the quotient space of  $X \times [0,1]$  by the equivalence relation generated by  $(x,0) \sim (\alpha(x),1)$  for all  $x: \mathrm{El}(X)$ .

**Definition 5.73** (Möbius Strip). The *Möbius strip* is  $([-1,1] \times [0,1])/\alpha$  where  $\alpha(x) = -x$ .

**Definition 5.74** (Klein Bottle). The *Klein bottle* is  $(S^1 \times [0,1])/\alpha$  where  $\alpha(z) = \overline{z}$ .

**Proposition 5.75.** Let M be the Möbius strip and K the Klein bottle. Then  $M \cup_{\mathrm{id}_{\partial M}} M \cong K$ .

#### Proof:

```
\langle 1 \rangle 1. Let: f: ([-1,1] \times [0,1]) + ([-1,1] \times [0,1]) \rightarrow S^1 \times [0,1] be the function that maps \kappa_1(\theta,t) to (e^{\pi i \theta/2},t) and \kappa_2(\theta,t) to (-e^{-\pi i \theta/2},t). \langle 1 \rangle 2. f induces a bijection M \cup_{\mathrm{id}_{\partial M}} M \approx K \langle 1 \rangle 3. f is a homeomorphism.
```

### 5.11 Metric Spaces

**Definition 5.76** (Metric Space). Let X be a set and  $d: X^2 \to \mathbb{R}$ . We say (X, d) is a *metric space* iff:

- For all  $x, y \in X$  we have  $d(x, y) \ge 0$
- For all  $x, y \in X$  we have d(x, y) = 0 iff x = y
- For all  $x, y \in X$  we have d(x, y) = d(y, x)
- (Triangle Inequality) For all  $x, y, z \in X$  we have  $d(x, z) \leq d(x, y) + d(y, z)$

We call d the *metric* of the metric space (X, d). We often write X for the metric space (X, d).

**Definition 5.77** (Topology of a Metric Space). Let (X,d) be a metric space. The topology *induced* by the metric d is defined by: for  $V \subseteq X$ , we have V is open if and only if, for all  $x \in V$ , there exists  $\epsilon > 0$  such that  $\{y \in X : d(x,y) < \epsilon\} \subseteq V$ .

**Definition 5.78** (Metrizable). A topological space is *metrizable* iff there exists a metric that induces its topology.

**Proposition 5.79.** Every metrizable space is Hausdorff.

Every metrizable space is first countable.

A metric space is compact if and only if it is sequentially compact.

A metric space is separable if and only if it is second countable.

## 5.12 Complete Metric Spaces

**Definition 5.80** (Complete). A metric space is *complete* iff every Cauchy sequence converges.

**Example 5.81.**  $\mathbb{R}$  is complete.

**Proposition 5.82.** The product of two complete metric spaces is complete.

**Proposition 5.83.** Every compact metric space is complete.

**Proposition 5.84.** Let X be a complete metric space and  $A \subseteq X$ . Then A is complete if and only if A is closed.

**Definition 5.85** (Completion). Let X be a metric space. A *completion* of X is a complete metric space  $\hat{X}$  and injection  $i: X \rightarrow \hat{X}$  such that:

- The metric on X is the restriction of the metric on  $\hat{X}$
- X is dense in  $\hat{X}$ .

**Proposition 5.86.** Let  $i_1: X \to Y_1$  and  $i_2: X \to Y_2$  be completions of X. Then there exists a unique isometry  $\phi: Y_1 \cong Y_2$  such that  $\phi \circ i_1 = i_2$ .

PROOF: Define  $\phi(\lim_{n\to\infty} i_1(x_n)) = \lim_{n\to\infty} i_2(x_n)$ .  $\square$ 

Theorem 5.87. Every metric space has a completion.

PROOF: Let  $\hat{X}$  be the set of Cauchy sequences in X quotiented by  $\sim$  where  $(x_n) \sim (y_n)$  if and only if  $d(x_n, y_n) \to 0$ .  $\square$ 

#### 5.13 Manifolds

**Definition 5.88** (Manifold). An *n*-dimensional manifold is a second countable Hausdorff space locally homeomorphic to  $\mathbb{R}^n$ .

## Homotopy Theory

### 6.1 Homotopies

**Definition 6.1** (Homotopy). Let X and Y be topological spaces. Let  $f,g:X\to Y$  be continuous. A homotopy between f and g is a continuous function  $h:X\times [0,1]\to Y$  such that

- $\forall x : \text{El}(X) . h(x, 0) = f(x)$
- $\forall x : \text{El}(X) . h(x, 1) = g(x)$

We say f and g are *homotopic*,  $f \simeq g$ , iff there exists a homotopy between them. Let [X,Y] be the set of all homotopy classes of functions  $X \to Y$ .

**Proposition 6.2.** Let  $f, f': X \to Y$  and  $g, g': Y \to Z$  be continuous. If  $f \simeq f'$  and  $g \simeq g'$  then  $g \circ f \simeq g' \circ f'$ .

**Definition 6.3.** Let **HTop** be the category whose objects are the small topological spaces and whose morphisms are the homotopy classes of continuous functions.

**Definition 6.4.** A functor  $F: \mathbf{Top} \to \mathcal{C}$  is homotopy invariant iff, for any topological spaces X, Y and continuous functions  $f, g: X \to Y$ , if  $f \simeq g$  then Hf = Hg.

Basepoint-preserving homotopy.

### 6.2 Homotopy Equivalence

**Definition 6.5** (Homotopy Equivalence). Let X and Y be topological spaces. A homotopy equivalence between X and Y,  $f: X \simeq Y$ , is a continuous function  $f: X \to Y$  such that there exists a continuous function  $g: Y \to X$ , the homotopy inverse to f, such that  $g \circ f \simeq \operatorname{id}_X$  and  $f \circ g \simeq \operatorname{id}_Y$ .

**Definition 6.6** (Contractible). A topological space X is *contractible* iff  $X \simeq 1$ .

**Example 6.7.**  $\mathbb{R}^n$  is contractible.

**Example 6.8.**  $D^n$  is contractible.

**Definition 6.9** (Deformation Retract). Let X be a topological space and A a subspace of X. A retraction  $\rho: X \to A$  is a deformation retraction iff  $i \circ \rho \simeq \mathrm{id}_X$ , where i is the inclusion  $A \to X$ . We say A is a deformation retract of X iff there exists a deformation retraction.

**Definition 6.10** (Strong Deformation Retract). Let X be a topological space and A a subspace of X. A strong deformation retraction  $\rho: X \to A$  is a continuous function such that there exists a homotopy  $h: X \times [0,1] \to X$  between  $i \circ \rho$  and  $\mathrm{id}_X$  such that, for all  $a: \mathrm{El}(X)$  and  $t: \mathrm{El}([0,1])$ , we have h(a,t)=a.

We say A is a strong deformation retract of X iff a strong deformation retraction exists.

**Example 6.11.**  $\{0\}$  is a strong deformation retract of  $\mathbb{R}^n$  and of  $D^n$ .

**Example 6.12.**  $S^1$  is a strong deformation retract of the torus  $S^1 \times D^2$ .

**Example 6.13.**  $S^{n-1}$  is a strong deformation retract of  $D^n - \{0\}$ .

**Example 6.14.** For any topological space X, the singleton consisting of the vertex is a strong deformation retract of the cone over X.

## Simplicial Complexes

**Definition 7.1** (Simplex). A k-dimensional simplex or k-simplex in  $\mathbb{R}^n$  is the convex hull  $s(x_0, \ldots, x_k)$  of k+1 points in general position.

**Definition 7.2** (Face). A *sub-simplex* or *face* of  $s(x_0, ..., x_k)$  is the convex hull of a subset of  $\{x_0, ..., x_k\}$ .

**Definition 7.3** (Simplicial Complex). A *simplicial complex* in  $\mathbb{R}^n$  is a set K of simplices such that:

- for every simplex s in K, every face of s is in K.
- The intersection of two simplices  $s_1, s_2 \in K$  is either empty or is a face of both  $s_1$  and  $s_2$ .
- K is locally finite, i.e. every point of  $\mathbb{R}^n$  has a neighbourhood that only intersects finitely many elements of K.

The topological space underlying K is  $|K| = \bigcup K$  as a subspace of  $\mathbb{R}^n$ .

## 7.1 Cell Decompositions

**Definition 7.4** (n-cell). An n-cell is a topological space homeomorphic to  $\mathbb{R}^n$ .

**Definition 7.5** (Cell Decomposition). Let X be a topological space. A *cell decomposition* of X is a partition of X into subspaces that are n-cells.

**Definition 7.6** (*n*-skeleton). Given a cell decomposition of X, the *n*-skeleton  $X^n$  is the union of all the cells of dimension  $\leq n$ .

## 7.2 CW-complexes

**Definition 7.7** (CW-Complex). A *CW-complex* consists of a topological space X and a cell decomposition  $\mathcal{E}$  of X such that:

- 1. Characteristic Maps For every n-cell  $e \in \mathcal{E}$ , there exists a continuous map  $\Phi_e: D^n \to X$  such that  $\Phi((D^n)^\circ) = e$ , the corestriction  $\Phi_e: (D^n)^\circ \approx e$  is a homeomorphism, and  $\Phi_e(S^n)$  is the union of all the cells in  $\mathcal{E}$  of dimension < n.
- 2. Closure Finiteness For all  $e \in \mathcal{E}$ , we have  $\overline{e}$  intersects only finitely many other cells in  $\mathcal{E}$ .
- 3. Weak Topology Given  $A \subseteq X$ , we have A is closed iff for all  $e \in \mathcal{E}$ ,  $A \cap \overline{e}$  is closed.

**Proposition 7.8.** If a cell decomposition  $\mathcal{E}$  satisfies the Characteristic Maps axiom, then for every n-cell  $e \in \mathcal{E}$  we have  $\overline{e} = \Phi_e(D^n)$ . Therefore  $\overline{e}$  is compact and  $\overline{e} - e = \Phi_e(S^{n-1}) \subseteq X^{n-1}$ .

Proof:

 $\langle 1 \rangle 1. \ e \subseteq \Phi_e(D^n) \subseteq \overline{e}$ 

Proof:

$$e = \Phi_e((D^n)^\circ)$$

$$\subseteq \Phi_e(D^n)$$

$$= \Phi_e(\overline{(D^n)^\circ})$$

$$\subseteq \overline{\Phi_e((D^n)^\circ)}$$

$$= \overline{e}$$

 $\langle 1 \rangle 2$ .  $\Phi_e(D^n)$  is compact.

PROOF: Because  $D^n$  is compact.

 $\langle 1 \rangle 3$ .  $\Phi_e(D^n)$  is closed.

$$\langle 1 \rangle 4. \ \Phi_e(D^n) = \overline{e}$$

## Topological Groups

**Definition 8.1** (Topological Group). A topological group is a group G with a topology such that the function  $G^2 \to G$  that maps (x, y) to  $xy^{-1}$  is continuous.

**Example 8.2.**  $GL(n,\mathbb{R})$  and  $GL(n,\mathbb{C})$  are topological groups.

**Proposition 8.3.** Any subgroup of a topological group is a topological group under the subspace topology.

**Definition 8.4** (Homogeneous Space). A homogeneous space is a topological space of the form G/H, where G is a topological group and H is a normal subgroup of G, under the quotient topology.

**Proposition 8.5.** Let G be a topological group and H a normal subgroup of G. Then G/H is Hausdorff if and only if H is closed.

Proof: See Bourbaki, N., General Topology. III.12

#### 8.1 Continuous Actions

**Definition 8.6** (Continuous Action). Let G be a topological group and X a topological space. A *continuous action* of G on X is a continuous function  $\cdot: G \times X \to X$  such that:

- $\forall x : \text{El}(X) . ex = x$
- $\forall g, h : \text{El}(G) . \forall x : \text{El}(X) . g(hx) = (gh)x$

A G-space consists of a topological space X and a continuous action of G on X.

**Definition 8.7** (Orbit). Let X be a G-space and  $x \in X$ . The *orbit* of x is  $\{gx : g \in G\}$ .

The orbit space X/G is the set of all orbits under the quotient topology.

**Proposition 8.8.** Define an action of SO(2) on  $S^2$  by

$$g(x_1, x_2, x_3) = (g(x_1, x_2), x_3)$$
.

Then  $S^2/SO(2) \cong [-1, 1]$ .

#### Proof:

- $\langle 1 \rangle 1$ . Let:  $f_3: S^2/SO(2) \to [-1,1]$  be the function induced by  $\pi_3: S^2 \to [-1,1]$
- $\langle 1 \rangle 2$ .  $f_3$  is bijective.  $\langle 1 \rangle 3$ .  $S^2/SO(2)$  is compact.

PROOF: It is the continuous image of  $S^2$  which is compact.

- $\langle 1 \rangle 4$ . [-1,1] is Hausdorff.
- $\langle 1 \rangle 5$ .  $f_3$  is a homeomorphism.

**Definition 8.9** (Stabilizer). Let X be a G-space and  $x \in X$ . The stabilizer of  $x \text{ is } G_x := \{g : \text{El}(G) \mid gx = x\}.$ 

**Proposition 8.10.** The function that maps  $gG_x$  to gx is a continuous bijection from  $G/G_x$  to Gx.

#### Proof:

- $\langle 1 \rangle 1$ . If  $gG_x = hG_x$  then gx = hx.
  - $\langle 2 \rangle 1$ . Assume:  $gG_x = hG_x$

  - $\langle 2 \rangle 2. \ g^{-1}h \in G_x$  $\langle 2 \rangle 3. \ g^{-1}hx = x$
  - $\langle 2 \rangle 4$ . gx = hx
- $\langle 1 \rangle 2$ . If gx = hx then  $gG_x = hG_x$ .

PROOF: Similar.

 $\langle 1 \rangle 3$ . The function is continuous.

Proof: Proposition 5.59.

## Topological Vector Spaces

**Definition 9.1** (Topological Vector Space). Let K be either  $\mathbb{R}$  or  $\mathbb{C}$ . A topological vector space over K consists of a vector space E over K and a topology on E such that:

- Substraction is a continuous function  $E^2 \to E$
- Multiplication is a continuous function  $K \times E \to E$

**Proposition 9.2.** Every topological vector space is a topological group under addition.

Proof: Immediate from the definition.  $\Box$ 

**Theorem 9.3.** The usual topology on a finite dimensional vector space over K is the only one that makes it into a Hausdorff topological vector space.

PROOF: See Bourbaki. Elements de Mathematique, Livre V: Espaces Vectoriels Topologiques, Th. 2, p. 18  $\square$ 

**Proposition 9.4.** Let E be a topological vector space and  $E_0$  a subspace of E. Then  $\overline{E_0}$  is a subspace of E.

**Definition 9.5.** Let E be a topological vector space. The topological space associated with E is  $E/\{0\}$ .

## 9.1 Cauchy Sequences

**Definition 9.6** (Cauchy Sequence). Let E be a topological vector space. A sequence  $(x_n)$  in E is a *Cauchy sequence* iff, for every neighbourhood U of 0, there exists  $n_0$  such that  $\forall m, n \ge n_0.x_n - x_m \in U$ .

**Definition 9.7** (Complete Topological Vector Space). A topological vector space is *complete* iff every Cauchy sequence converges.

#### 9.2 Seminorms

**Definition 9.8** (Seminorm). Let E be a vector space over K. A *seminorm* on E is a function  $\| \| : E \to \mathbb{R}$  such that:

- 1.  $\forall x : \text{El}(E) . ||x|| \ge 0$
- 2.  $\forall \alpha : \text{El}(K) . \forall x : \text{El}(E) . ||\alpha x|| = |\alpha||x||$
- 3. Triangle Inequality  $\forall x, y : \text{El}(E) . ||x + y|| \le ||x|| + ||y||$

**Example 9.9.** The function that maps  $(x_1, \ldots, x_n)$  to  $|x_i|$  is a seminorm on  $\mathbb{R}^n$ .

**Definition 9.10.** Let E be a vector space over K. Let  $\Lambda$  be a set of seminorms on E. The topology generated by  $\Lambda$  is the topology generated by the subbasis consisting of all sets of the form  $B_{\epsilon}^{\lambda}(x) = \{y \in E : \lambda(y-x) < \epsilon\}$  for  $\epsilon > 0, \ \lambda \in \Lambda$  and  $x : \mathrm{El}(E)$ .

**Proposition 9.11.** E is a topological vector space under this topology. It is Hausdorff iff, for all x : El(E), if  $\forall \lambda \in \Lambda. \lambda(x) = 0$  then x = 0.

### 9.3 Fréchet Spaces

**Definition 9.12** (Pre-Fréchet Space). A *pre-Fréchet space* is a Hausdorff topological vector space whose topology is generated by a countable set of seminorms.

**Proposition 9.13.** Let E be a pre-Fréchet space whose topology is generated by the family of seminorms  $\{\| \|_n : n \in \mathbb{Z}^+ \}$ . Then

$$d(x,y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \frac{\|x - y\|_n}{1 + \|x - y\|_n}$$

is a metric that induces the same topology. The two definitions of Cauchy sequence agree.

**Definition 9.14** (Fréchet Space). A *Fréchet space* is a complete pre-Fréchet space.

## 9.4 Normed Spaces

**Definition 9.15** (Normed Space). Let E be a vector space over K. A norm on E is a function  $\| \ \| : E \to \mathbb{R}$  is a seminorm such that,  $\forall x \in E. \|x\| = 0 \Leftrightarrow x = 0$ . A normed space consists of a vector space with a norm.

**Proposition 9.16.** If E is a normed space then d(x,y) = ||x-y|| is a metric on E that makes E into a topological vector space. The two definitions of Cauchy sequence agree on E.

**Proposition 9.17.** Let  $\| \ \|$  be a seminorm on the vector space E. Then  $\| \ \|$  defines a norm on  $E/\{0\}$ .

**Proposition 9.18.** Let E and F be normed spaces. Any continuous linear map  $E \to F$  is uniformly continuous.

**Definition 9.19.** For  $p \ge 1$ . let  $\mathcal{L}^p(\mathbb{R}^n)$  be the vector space of all Lebesgue-measurable functions  $f: \mathbb{R}^n \to \mathbb{R}$  such that  $|f|^p$  is Lebesgue-integrable. Then

$$||f||_p := \sqrt{p} \int_{\mathbb{R}^n} |f(x)|^p dx$$

defines a seminorm on  $\mathcal{L}^p(\mathbb{R}^n)$ . Let

$$L^p(\mathbb{R}^n) := \mathcal{L}^p(\mathbb{R}^n)/\overline{\{0\}}$$
.

### 9.5 Inner Product Spaces

**Proposition 9.20.** If E is an inner product space then  $||x|| = \sqrt{\langle x, x \rangle}$  is a norm on E.

### 9.6 Banach Spaces

**Definition 9.21** (Banach Space). A Banach space is a complete normed space.

**Example 9.22.** For any topological space X, the set C(X) of bounded continuous functions  $X \to \mathbb{R}$  is a Banach space under  $||f|| = \sup_{x \in X} |f(x)|$ .

Proposition 9.23. The completion of a normed space is a Banach space.

**Proposition 9.24.** Let E and F be normed spaces. Let  $f: E \to F$  be a continuous linear map. Then the extension to the completions  $\hat{E} \to \hat{F}$  is linear.

**Proposition 9.25.**  $L^p(\mathbb{R}^n)$  is a Banach space.

**Proposition 9.26.**  $C(\mathbb{R})$  is first countable but not second countable.

PROOF: For every sequence of 0s and 1s  $s=(s_n)$ , let  $f_s$  be a continuous bounded function whose value at n is  $s_n$ . Then the set of all  $f_s$  is an uncountable discrete set in  $C(\mathbb{R})$ . Hence  $C(\mathbb{R})$  is not second countable.

It is first countable because it is metrizable.  $\Box$ 

## 9.7 Hilbert Spaces

**Definition 9.27** (Hilbert Space). A *Hilbert space* is a complete inner product space.

**Example 9.28.** The set of square-integrable functions is the set of Lebesgue integrable functions  $[-\pi, \pi] \to \mathbb{R}$  quotiented by:  $f \sim g$  iff  $\{x \in [-\pi, \pi] : f(x) \neq g(x)\}$  has measure 0. This is a Hilbert space under

$$\langle f, g \rangle = \frac{1}{\pi} \int_{-\pi} \pi f(x) g(x) dx$$
.

**Proposition 9.29.** The completion of an inner product space is a Hilbert space.

An infinite dimensional Hilbert space with the weak topology is not first countable.

### 9.8 Locally Convex Spaces

**Definition 9.30** (Locally Convex Space). A topological vector space is *locally convex* iff every neighbourhood of 0 includes a convex neighbourhood of 0.

**Proposition 9.31.** A topological vector space is locally convex if and only if its topology is generated by a set of seminorms.

PROOF: See Köthe, G. Topological Vector Spaces 1. Section 18.

**Proposition 9.32.** A locally convex topological vector space is a pre-Fréchet space if and only if it is metrizable.

Proof: See Köthe, G. Topological Vector Spaces 1. Section 18.  $\square$ 

**Example 9.33.** Let E be an infinite dimensional Hilbert space. Let E' be the same vector space under the *weak topology*, the coarsest topology such that every continuous linear map  $E \to \mathbb{R}$  is continuous as a map  $E' \to \mathbb{R}$ . Then E is locally convex Hausdorff but not metrizable.

Proof: See Dieudonne, J. A., Treatise on Analysis, Vol. II, New York and London: Academic Press, 1970, p. 76.

**Definition 9.34** (Thom Space). Let E be a vector bundle with a Riemannian metric,  $DE = \{x : \text{El}(E) \mid ||x|| \le 1\}$  its disc bundle and  $SE := \{v : \text{El}(E) \mid ||v|| = 1\}$  its sphere bundle. The *Thom space* of E is the quotient space DE/SE.