Progress Report by week for Etch a Pic

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Week 1 (02/08/2016)

Our initial meeting, we outlined the project and our ideas for it. We identified clear steps that we needed to take for our project and defined a finished prototype, while leaving the specifications of a final product still open for major changes based on our findings in the preliminary parts of the project. We came up with a parts list for our project and sent the list into the CT club for funding and for it to be ordered.

Week 2 (02/15/2016)

We defined that we wanted to use the Raspberry Pi in order to run our servos. We decided that we would be using Github and PyCharm for the code we write in Python. We started writing the code to test using the servo motors with the Pi and the GPIOs. We confirmed that our servo motor of choice will have excellent capabilities in regards to both control and resolution. For next week: make sure Git and Pycharm are up and running and bring the Pi to the meeting.

Week 3 (02/22/2016)