Saturday NN.S.k kalyani 20-6-2020 3rd B. Tech est-C 2 Marles loop optimization is most valuable machine Independent optimization because program's inner loop takes bulle to time of a prognamener of we decrease the no. of instructions in our inner loop then the running time of a program may be Improved even if we encrease the amount of cade outside that loop. 2A) Direct Acyclic Grouph: - 18 a tool that depicts the structure of basic blocks, helps to see the flow Of values following among the baric blocks, and offers optimization too. DAG provides easy transformation on basic blocks DAG can be un--determ: leaf node represent identifierx names. DAG is a pictorial representation of basic blod DAG is constructed for constructed for the basic block and transformation are applied. Ex: m: nxp where n=1, p=2, 9=3 The DAG is constructed on

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Algebraic transformations can be used to simple the set of expressions computed by a basic block This can be done by the following:

- a. Edentify Rules
- b. strength Reduction
- c. constant folding
- d. Associativity and commutativity

machine dependent code optimization performs, based on the characteristics of the machine like Instruction rets used, addressing Target code.

Graph coloring allocates register and attempts to minimize the copt of spills by building a Interface graph based on how a variable Interact and Interface with each other.

* Graph coloring technique of finding at least no. of colors required to color a graph such that no adjacent vertices will have the same color. The resultant graph is called as k-coloring graph.

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principal source of code optimization:

There are many ways in which a compiler can suprove a program few of them are shown below:

- 1. Function preserving transformation
- Exacommon Sub-expression elimination
 - + copy propogation
 - + pead code elimination
 - + constant folding
- 2. Common sub-expression elimination
- 3. copy propogation
 - 4. pead code elimination
 - 5. compile time evaluation
 - + constant Folding
 - * constant propogation
 - 6. Loop optimization
 - + code motion
 - * loop invariant method
 - * strength Reduction
 - 1. Furction preserving transformation: There are some ways in which a compiler can emprove the program efficiency without chainging

the function it compiltes.

2. common sub-expression elimination; An occurrence of an Expression Els called as common sub-expression if e was pressionly computed and the value of variables was previously computed, and the value of variable in E have not changed since previous come at we can avoid re-computing expression if we can use the previously computed value.

Ex: a: b+c

3. copy propogation: An Assignment Etatement of the form f:= g is called as copy statement + we can peduce the copying statements if possible so that program code will be minimize

FX: x:=4;

S:= x * f(x) =) S:= 4 x f(y)

4. pead cade elimination: - A variable is said to be live in a program was withthe It its value is used subsequently.

+ optimization can be performed by eliminating such dead code.

Ex: X:=4+1

y: =5 =) d:=5

5. compiler Time Evaluation: It is a process of shifting of computation from runtime to compile time if provides possible. So that we can solve execution time.

a) constant folding: computation of constants are done at compile time Instead of runtime

Ex: float d=5 length; -float d=5, length; length= (21/7) &d; length = 3.1428 x d;

b) constant propogation: The value or variable ix replaced and computation of expression is done at compile time

er: float pi = 3.14, x=5, area; area = pi + T x r; => float pi = 3.149 r=5, area; area = 2.14 5 x 5;

6. Loop optimization: the running time of a program may be Improved if we decrease the no. of Instructions in the loop body even if we Increase the amount of code outside the loop.

a) code motion: which moves code outride the loop with out effecting the output.

Ex: while [izlimit-2]

t=limit-2
while (ic=t)
&

```
b. loop invarient: which eliminates variables
 whose value will not be changed in the loop.
 tx: for (1=0;1c=10;1++)
k=(yx5) +50; for(120;12=10;1++)
 c) Reduction in steagth: which replaces on
  expensive operation by cheapen operation.
  for (i=1; i = 50; i++)
        count = i x 7; => for (i=1; ic=50; i++)

print ("/-d", count); {
                        temp = count + 7;
                  Prints ("-1-d", count
```

Various Ixxues in code Guneration:

code generation is the final phase of a compilation process.

Issues in the perign of code Overenabot:

1. Input to the code generalor:

The is intermediate representation of the Generator is the Intermediate Source program produced by the front end along with Information in the Symbol table.

- 2. The Torget Program: The Instruction-set architecture of the toright machine has a Significant impact on constructing a good code generator that produces high quality machine code.
- * The most common target-machine architecture are RISC, CISC, stack based.
- * The output of the code generator is an object code the object code normally comes in
- => Absolute code:
 It is a machine code that contains reference to actual address with in program's pace
 the generated absolute code can be placed
 directly in the memory and execution can be
 done Immediabely.

Pe-locatable machine code: precution requires linking and loading operations.

* A set of re-locatable object maddles can be linked together and loaded for execution with help of linker and loader.

Assembly language code: It produces an output

ix some what easier.

After generating Assembly language code, we need to use the translator Assembler to produce an executable code.

3. Instruction selection: The code generalor must map the Intermediate representation program into a code sequence that can be executed by the target machine.

a. Register allocation & assignment: Register on the are the fastest computational unit on the target machine, but we usually to not have enough of them to hold all values.

the use of Register is often divided into

the set of variables that will recide in regist at each point in the program.

2. Register Assignment deving which he pick the specific register in which a variable will maide in

Scanned with CamScanner

174101A0584 R3=) ty tuis in P3 ty:=t, x to MUL R3, RO, R, ts is in Ru Ry=)ts t5 := t3 * t1 MUL Ry, Rz, Po to ix in Rg 125=) 66 ADD RS, R3, R4 to := ty + to to is in Ro P5=>+6 ST X, RS x:= +6 to is in x