7. Local Beam Search

at any given time At the stant, these states are generated randomly the successors of these k states are computed with the help of Objective function. If any of these successors is the maximum value of the objective function, then the algorithm stops otherwise the (initial k states and k no of successors of the states = 2k) states are placed in a pool. The pool is then sorted numerically. The highest k states are selected as new initial states. This process continues until a maximum value is reached

function Beam Search (problem, k) return a solution states start with k randomly generated states

generate all successors of all k states
if any of the states = Solution, then return
the state

else select the k best successors

INTERNATION OF THE STREET

end

9. Minimax is a kind of back tracking algorithm that is used in decision making and game theory to find the optimal more for a player, assuming that your opponent plays optimally. It is widely used in two player games such as Tic-Tac-Toe, chess etc

In minimax the two players are colled maximizer and minimizer. The maximizer thes to get to highest score possible while the minimizer thes to do the opposite and get the lowest score possible

function MINIMAX- DECISION (state) return an action return arg max a & Actions MIN-VALUE (RESULT (state,a))

function MAX-VALUE (state) teturns a utility value if TERMINAL-TEST (state) then return UTILITY (state) $V \leftarrow -\infty$

Per each a in ACTIONS (state) do

V

MAX (V, MIN-VALUE (RESULT (s,a)))

return V

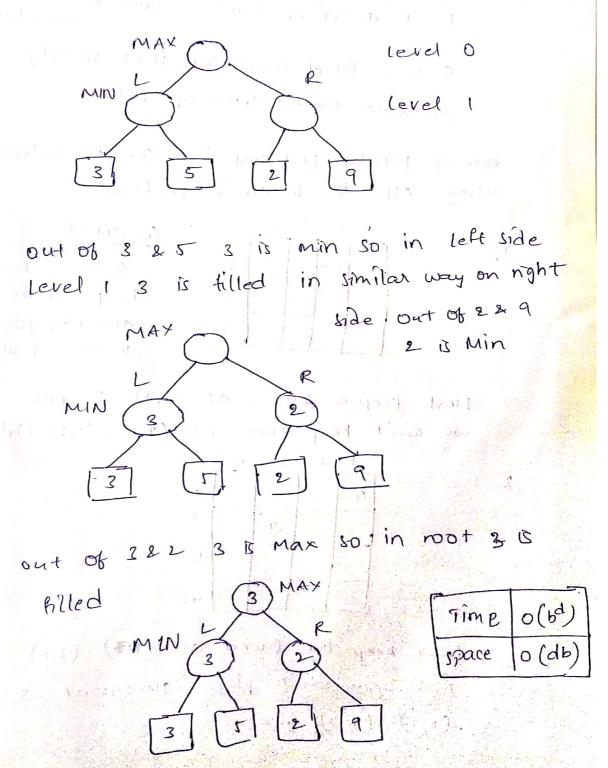
function MIN-VALUE (State) returns utility value if TERMINA-TEST (State) thenteturn UTILITY (Slate) v = 0

for each a in ACTIONS (State) do

V = MIN (V, MAX-VALUE (RESULT (1,9)))

retur V

lennaider a game which has 4 final states and paths to reach final state are from root to 4 leaves of a perfect binary tree as shown. Assume you are the maximizing player and you get the first chance to move i.e., you are the noot and your opponent at next level.



11. A constituent satisfaction problem is a problem that requires its solution within some limitations also known as constraints.

It consists of the following

X is a set of Variables
D is a set of Domains (one for each variable)

C is a set of constraints that specify allowable combinations of values

one of popular problems that can be solved using CSP: 13 4-Quicen problem

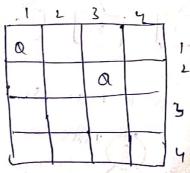
Constraint

4 Queens must be placed in non attacking positions in every now

First teep a queen at (1,1) so now we can't teep oneen at (2,1), (1,2), (2,2)

3

2



Now keep the Queen at (3,2)

Now you can't place queens at (3,3)

(2,3), (14,3)...eta

E NIL

our 1st more is wrong

Again start from 1st

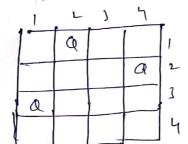
Now keep oncent at (2,1)

	1	2	3	4	ı .
1	×	a	Х		1
	X	X	X	1 1	2
1					3
-					, 4

Now keep another Oneen at (4,2)



Now keep third aveen at (1,3)



NOW one more Queen at (3,4)

<	a		,
-		+ 8	a
a		IP	
		Q	

Hence solved

