190031187 CO-4 Home Assignment Radhahishna

1. Inertial & Non-Inertial Frames

Ann. An inertial reference is either at rest or moves with a const velocity. Non inertial frame is a reference frame that is accelerating either in linear fashion or reference frame that is accelerating either in linear fashion or notating around some axis.

Example: Inertial reference frames - A train moving with constant relocity

2. Galileo & Lorentz Transfel mations

Any: Lorentz Transformations, set of equs in relativity physics they related the space & time coordinates of two systems moving at a const velocity relative to each other required to describe high speed phenomenon approaching the speed of light, lorentz transformations formally express the relative concepts that space & time aren't absolute that length, time, a mass depend on the relative motion observer, & that the speed of light in vaccum is constant & independent of the motion of the observer of the source galilean transformations, set of equs in classical physics that relate the space & time coordinates of two systems

moving at a compt velocity relative to each other. Adequate to describe phenomena at speeds much smaller than the speed of light Galilean Transformations formally express the ideal that space & time are absolute that length time & mass are independent of the relative motion of the observer & that the speed of light depends upon the relative motion of the observer.

3. Time dilation & length contraction

Ime dilation: clocks moving relative to an observer runs more slowly compared to the clocks that are rest relative to the observer.

Twin Paradox: Illustrates questions on the relativity of time.

4. Variation of mass with relocity

And to explain the variation of mass with relocity consider the collision of two exactly similar balls A&B, each of mass in , moving in opposite direction along x-axis to speed u in frames s. After collision they coaleince into one body. The mass of a moving body appenriged than its rest mass.