

# MISRA-C (QUICK overview)

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## *What is MISRA C?*

**MISRA C = Motor Industry Software Reliability Association.**

A set of coding guidelines created for safety-critical systems:

- Automotive
- Aerospace
- Defense
- Medical devices
- Industrial controllers

These systems cannot afford crashes, so MISRA provides strict rules to avoid unsafe C coding.

## *Why MISRA C Exists (Real reasons)?*

- Normal C language is:
- Too flexible
- Allows dangerous behaviors
- No runtime protections
- Undefined behavior (UB)
- Implementation dependent features

MISRA C removes all risky features → makes software predictable, testable, safe.

MISRA C compliance is not a built-in feature of most standard IDEs; it is typically achieved using specialized third-party static analysis tools. Tools like Parasoft C/C++test integrate into popular IDEs to provide comprehensive MISRA rule enforcement and reporting.

Quick overview of some useful rules that need to follow during development:

### **1) Always initialize variables**

**Rule idea:** Never read an automatic (local) variable before you set it to a known value.

#### **Bad example:**

```
int sum(void) {  
    int s;          // uninitialized  
    s += 10;       // UB: reading s to add to it  
    return s;  
}
```

### **Good example:**

```
void f(void) {  
    int x = 0; // initialized  
    if (x == 0) {  
        do_something();  
    }  
}
```

## **2) No magic numbers**

**Rule idea:** Use named constants instead of bare numbers so intent and range are clear.

### **Bad example:**

```
buffer[index] = value; // assume index < 256 somewhere else  
if (speed > 63) stop();
```

### **Good example:**

```
#define MAX_SPEED 63  
#define BUFFER_SIZE 256  
  
if (speed > MAX_SPEED) stop();  
if (index < BUFFER_SIZE) buffer[index] = value;
```

## **3) Avoid dynamic memory in safety-critical code:**

**Rule idea:** Prefer static (compile-time) allocations in safety-critical embedded systems.  
It means No malloc() or calloc().

### **Why this is bad / effects**

- Non-deterministic timing: allocation may take variable time.
- Fragmentation: long run-time can fragment heap, later malloc() fails.
- Failure handling complexity: must check every allocation and handle failures — often dangerous.
- Hard to certify: dynamic memory makes formal verification harder.

## **4) Bounds-check arrays**

**Rule idea:** Never index arrays without first checking that the index is within valid bounds.

### **Bad example:**

```
char buf[10];
```

```
buf[len] = '\0'; // if len >= 10 -> overflow
```

### Good example:

```
if (len < sizeof(buf)) {  
    buf[len] = '\0';  
} else {  
    // handle error  
}
```

## 5) Avoid complex expressions with side-effects

**Rule idea:** Don't write expressions that change multiple variables or rely on unsequenced behavior. Break into simple steps.

How one-liner violates rule

```
a = b++ + ++c;
```

modifying b and c inside expression and using them is confusing and can be UB depending on sequence points/ordering.

### Bad example:

```
i = ++j + j++; // undefined (modifies j multiple times without sequence)
```

```
arr[i++] = i; // undefined: modifying i and reading i in same expression
```

### Good example: (Break into steps)

```
j = j + 1;
```

```
int tmp = j + (j - 1); // or whatever intended
```

```
i = tmp;
```

```
int idx = i;
```

```
i = i + 1;
```

```
arr[idx] = i;
```

## **6) Use braces {} for all control blocks**

**Rule idea:** Always put braces around if, for, while bodies, even single-line ones.

### **How one-liner violates rule?**

`if (cond) do_a(); do_b();` — visually may look like both are in if, but only first is.

## **7) Switch must have default case**

**Rule idea:** Always include a default: branch in switch so unexpected enumeration values are handled.

### **Good example:**

```
switch (state) {  
    case STATE_IDLE: do_idle(); break;  
    case STATE_RUN: do_run(); break;  
    default: handle_unexpected_state(); break;  
}
```

## **8) Check all return values**

**Rule idea:** Functions that return status or size must be checked and handle.

## **10) Explicit conversions**

**Rule idea:** Avoid implicit casts that change type or sign; use explicit casts and check ranges.

That means no implicit narrowing or mixed signed/unsigned.

here is simple example

`uint8_t x = 300; or int i = -1; unsigned u = i;` — implicit conversions silently change value.

### **Bad example:**

```
uint8_t x = 300; // 300 truncated modulo 256 -> 44
```

```
int a = -1; unsigned b = a; // b becomes large positive
```

```
if (i < u) ... // surprising result
```

**Good example:**

```
int temp = 300;  
if (temp >= 0 && temp <= UINT8_MAX) {  
    uint8_t x = (uint8_t)temp;  
} else {  
    // handle error  
}
```