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# **ITA-6016 Machine Learning**

**Digital Assignment –Lab-4** 

**SUBMITTED TO: Dr\_Dominic Savio M** 

## **PERCEPTRON:**

### **CODE OF THE PROGRAM AND OUTPUT:**

```
In [1]: import pandas as pd
               import numpy as np
               import matplotlib.pyplot as plt
               from sklearn.preprocessing import MinMaxScaler
               import tensorflow as tf
              import keras
               import math
               from keras.models import Sequential
               from keras.layers import Dense
               %matplotlib inline
     In [2]: df = pd.read_csv('D:\\vit notes\\MCA Second Semester\\MachineLearning\\train27303.csv')
              df.head()
     Out[2]:
                          timestamp hourly_traffic_count
               0 2015-10-04 00:00:00
                                                    3
               1 2015-10-04 00:05:00
                                                   16
               2 2015-10-04 00:10:00
                                                    9
               3 2015-10-04 00:15:00
                                                   12
               4 2015-10-04 00:20:00
                                                   19
     In [3]: df1 = df.reset_index()['hourly_traffic_count']
              df1.head()
     Out[3]: 0
                     3
              1
                    16
              2
                     9
                    12
              3
               4
              Name: hourly_traffic_count, dtype: int64
In [4]: df1 = df1.iloc[:9792,]
       df1.tail()
Out[4]: 9787
              23
       9788
       9789
              16
       9790
             18
       9791
       Name: hourly_traffic_count, dtype: int64
In [5]: plt.figure(figsize=(20,10))
plt.plot(df1)
       plt.show()
```

```
In [7]: def create_dataset(dataset, window=1):
             dataX, dataY= [], []
             for i in range(len(dataset)-window-1):
                 a = dataset[i:(i+window),0]
                 dataX.append(a)
                 dataY.append(dataset[i+window,0])
             return np.array(dataX), np.array(dataY)
 In [8]: scaler = MinMaxScaler(feature_range=(0,1))
         df1 = scaler.fit_transform(np.array(df1).reshape(-1,1))
In [9]: training_size = int(len(df1)*0.80)
         test_size = len(df1)-training_size
         train_data, test_data = df1[0:training_size,:], df1[training_size:len(df1),:1]
In [10]: window = 288
         X_train,y_train = create_dataset(train_data,window)
         X_test, y_test = create_dataset(test_data,window)
In [11]: model = Sequential()
         model.add(Dense(40, input_dim=window, activation='relu'))
         model.add(Dense(50, activation='relu'))
         model.add(Dense(40, activation='relu'))
         model.add(Dense(1))
In [12]: opt = keras.optimizers.Adagrad(learning_rate = 0.05)
In [13]: model.compile(optimizer=opt ,loss='mean_squared_error')
```

#### In [14]: model.summary() Model: "sequential" Output Shape Layer (type) Param # dense (Dense) (None, 40) 11560 dense\_1 (Dense) (None, 50) 2050 dense\_2 (Dense) (None, 40) 2040 dense\_3 (Dense) (None, 1) 41 Total params: 15,691 Trainable params: 15,691 Non-trainable params: 0 In [15]: model.fit(X\_train, y\_train, epochs=100, batch\_size=10, verbose=1) Epoch 1/100 755/755 [==========] - 4s 3ms/step - loss: 0.0096 Epoch 2/100 755/755 [============] - 3s 3ms/step - loss: 0.0064 Epoch 3/100 755/755 [==========] - 3s 4ms/step - loss: 0.0058 Epoch 4/100 755/755 [=================] - 3s 4ms/step - loss: 0.0055 Epoch 5/100

```
In [16]: train_predict = model.predict(X_train)
          test_predict = model.predict(X_test)
          236/236 [========== ] - 1s 3ms/step
          53/53 [======== ] - 0s 3ms/step
In [17]: train_predict = scaler.inverse_transform(train_predict)
          test_predict = scaler.inverse_transform(test_predict)
          y_train = scaler.inverse_transform(y_train.reshape(-1, 1))
          y_test = scaler.inverse_transform(y_test.reshape(-1, 1))
In [18]: train_predict = train_predict.astype(int)
          test_predict = test_predict.astype(int)
          y_train = y_train.astype(int)
          y_test = y_test.astype(int)
In [19]: from sklearn.metrics import mean_squared_error, mean_absolute_error,r2_score
          print('RMSE-train:',math.sqrt(mean_squared_error(y_train,train_predict)))
          print('MAE-train:',mean_absolute_error(y_train,train_predict))
          print('R_2-train:',r2_score(y_train,train_predict))
          RMSE-train: 6.46107522840471
          MAE-train: 4.761399787910922
          R 2-train: 0.9264831054092415
In [20]: print('RMSE-test:',math.sqrt(mean_squared_error(y_test,test_predict)))
          print('MAE-test:',mean_absolute_error(y_test,test_predict))
          print('R_2-train:',r2_score(y_test,test_predict))
          RMSE-test: 7.463042676283176
          MAE-test: 5.743712574850299
          R 2-train: 0.8614505151272462
In [21]: # shift train predictions for plotting
       trainPredictPlot = np.empty_like(df1)
       trainPredictPlot[:, :] = np.nan
       trainPredictPlot[window:len(train_predict)+window, :] = train_predict
       # shift test predictions for plotting
       testPredictPlot = np.empty_like(df1)
       testPredictPlot[:, :] = np.nan
       testPredictPlot[len(train_predict)+(window*2)+1:len(df1)-1, :] = test_predict
       # plot baseline and predictions
       plt.figure(figsize=(20,10))
       plt.plot(scaler.inverse_transform(df1))
       plt.plot(trainPredictPlot)
       plt.plot(testPredictPlot)
       plt.show()
```

# **BACKPROPOGATION:**

### **CODE OF THE PROGRAM AND OUTPUT:**

## **Backpropogation Algorithm**

```
In [1]: import numpy as np
         import matplotlib.pyplot as plt
In [2]: #synthetic data with noise
         np.random.seed(10)
         X = 2*np.random.rand(1, 50) - 1
         T = np.sin(2*np.pi*X) + 0.3*np.random.randn(1, 50)
         N = np.size(T,1)
         plt.scatter(X, T)
         plt.show()
           1.5
           1.0
           0.5
           0.0
          -0.5
          -1.0
          -1.5
              -1.00 -0.75 -0.50 -0.25 0.00
                                          0.25
```

In [3]: # NN implementaion with feed-forward propagation and backprojection
def Neural\_Network\_Simple(LR,beta,max\_ite,input\_nodes,hidden\_nodes,output\_nodes):

```
In [3]: # NN implementaion with feed-forward propagation and backprojection
        def Neural_Network_Simple(LR,beta,max_ite,input_nodes,hidden_nodes,output_nodes):
            # weight initialization function
            W_1 = np.random.randn(hidden_nodes, input_nodes)
            W_2 = np.random.randn(output_nodes, hidden_nodes)
            B_1 = np.zeros((hidden_nodes, 1))
            B_2 = np.zeros((output_nodes, 1))
            # gradient descent with momentum
            Vdw_1 = np.random.randn(hidden_nodes, input_nodes)
            Vdw_2 = np.random.randn(output_nodes, hidden_nodes)
            Vdb_1 = np.zeros((hidden_nodes, 1))
            Vdb_2 = np.zeros((output_nodes, 1))
            # cost initialization
            Cost = np.zeros((max_ite,1))
            for i in range(max_ite):
                #feed-forward propagation
                A_1 = W_1.dot(X) + np.tile(B_1, (1, N))
                Z_1 = (np.exp(A_1) - np.exp(-A_1)) / (np.exp(A_1) + np.exp(-A_1))
                A_2 = W_2.dot(Z_1) + np.tile(B_2, (1, N))
                Z_2 = A_2
                #back propagation
                del 2 = Z 2 - T
                del_1 = W_2.T.dot(del_2) * (1 - Z_1 ** 2)
                #gradient
                dw_2 = del_2.dot(Z_1.T)
                dw_1 = del_1.dot(X.T)
```

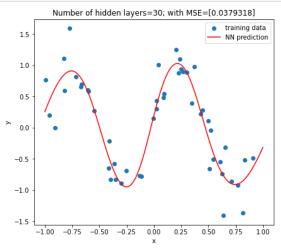
```
dw_2 = del_2.dot(Z_1.T)
                        dw_1 = del_1.dot(X.T)
                        db_2 = np.sum(del_2, 1)
                        db_1 = np.sum(del_1, 1).reshape(hidden_nodes,1)
                        #GD with momentum
                       Vdw_2 = beta * Vdw_2 + (1 - beta) * dw_2
                        Vdw_1 = beta * Vdw_1 + (1 - beta) * dw_1
                        Vdb_2 = beta * Vdb_2 + (1 - beta) * db_2
                       Vdb_1 = beta * Vdb_1 + (1 - beta) * db_1
                        #update weight and bias with batch GD
                       W_2 = W_2 - LR * Vdw_2
                       W_1 = W_1 - LR * Vdw_1
                        B_2 = B_2 - LR * Vdb_2
                       B_1 = B_1 - LR * Vdb_1
                       Cost[i] = 0.5 * np.sum(del_2**2)/N
                   return W_1,W_2,B_1,B_2,Cost
    In [4]: # prediction with forward propagation
              def forwardNN_reg(W_1,W_2,B_1,B_2,X):
                   A_1 = W_1.dot(X) + np.tile(B_1, (1, 1))
                   Z_1 = (np.exp(A_1) - np.exp(-A_1)) / (np.exp(A_1) + np.exp(-A_1))
                   A_2 = W_2.dot(Z_1) + np.tile(B_2, (1, 1))
                   pred = A_2
                   return pred
    In [5]: W 1,W 2,B 1,B 2,Cost = Neural Network Simple(0.01,0.8,5000,1,3,1)
              x_pre =np.linspace(-1,1,100).reshape(1,100)
              y_pre =forwardNN_reg(W_1,W_2,B_1,B_2,x_pre)
       plt.xiabel( x );plt.yiabel( y )
plt.title('Number of hidden layers=' + str(3) + '; with MSE=' + str(Cost[-1]))
       plt.legend()
       plt.subplot(1,2,2)
       plt.scatter(np.linspace(0,4999,5000),Cost)
       plt.xlabel('Number of iterations');plt.ylabel('MSE')
       plt.title('Cost function convergence plot')
                Number of hidden lavers=3; with MSE=[0.04701319]
                                                                        Cost function convergence plot

    training data

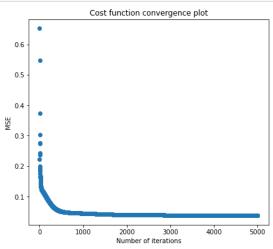
          1.5
                                                           0.8
          1.0
          0.5
                                                           0.6
                                                          MSE
          0.0
                                                           0.4
         -0.5
                                                           0.2
         -1.0
             -1.00 -0.75 -0.50 -0.25 0.00
                                    0.25
                                         0.50
                                             0.75
                                                                      1000
                                                                             2000
                                                                                     3000
                                                                                            4000
                                                                             Number of iterations
In [6]. W 1 W 2 R 1 R 2 Cost = Neural Network Simple(0 01 0 8 5000 1 30 1)
```

```
plt.xlabel('x');plt.ylabel('y')
plt.title('Number of hidden layers=' + str(30) + '; with MSE=' + str(Cost[-1]))
plt.legend()

plt.subplot(1,2,2)
plt.scatter(np.linspace(0,4999,5000),Cost)
plt.xlabel('Number of iterations');plt.ylabel('MSE')
plt.title('Cost function convergence plot')
plt.show()
```



hist = pd.DataFrame(history.history)



```
In [7]: from tensorflow import keras
        from tensorflow.keras import layers
In [8]: model_NN = keras.models.Sequential()
        model_NN.add(layers.Dense(units=30,activation='tanh',input_dim=1))
        model_NN.add(layers.Dense(units=1))
        optimiz = keras.optimizers.SGD(lr=0.2, momentum=0.8, decay=0.0, nesterov=False)
        model_NN.compile(loss="mean_squared_error",optimizer=optimiz,metrics=['mean_absolute_error', 'mean_squared_error'])
        history = model_NN.fit(X.T,T.T,batch_size=50,epochs=1500)
        \label{local-cond} C:\ProgramData\Anaconda3\lib\site-packages\keras\optimizer_v2\gradient\_descent.py:108:\ UserWarning:\ The `lr` argument is deprecated, use `learning\_rate` instead.
         super(SGD, self).__init__(name, **kwargs)
        Epoch 1/1500
        1/1 [-----
                      Epoch 2/1500
                               =======] - 0s 16ms/step - loss: 0.4878 - mean_absolute_error: 0.5975 - mean_squared_error: 0.4878
        Epoch 3/1500
                             ========] - 0s 0s/step - loss: 0.4914 - mean absolute error: 0.5837 - mean squared error: 0.4914
        1/1 [======
        Epoch 4/1500
                                       ==] - 0s 0s/step - loss: 0.4881 - mean_absolute_error: 0.5809 - mean_squared_error: 0.4881
        Epoch 5/1500
        1/1 [======
                              :=======] - 0s 0s/step - loss: 0.4914 - mean_absolute_error: 0.5891 - mean_squared_error: 0.4914
        Epoch 6/1500
                           :========] - 0s 0s/step - loss: 0.4876 - mean_absolute_error: 0.5894 - mean_squared_error: 0.4876
        Epoch 7/1500
                         =========] - 0s 0s/step - loss: 0.4853 - mean_absolute_error: 0.5899 - mean_squared_error: 0.4853
        1/1 [======
        Fnoch 8/1500
In [9]: import pandas as pd
```

```
In [9]: import pandas as pd
hist = pd.DataFrame(history.history)
hist.head(10)
```

Out[9]:		loss	mean_absolute_error	mean_squared_error
	0	0.500394	0.617545	0.500394
	1	0.487786	0.597534	0.487786
	2	0.491409	0.583684	0.491409
	3	0.488079	0.580928	0.488079
	4	0.491431	0.589096	0.491431
	5	0.487643	0.589445	0.487643
	6	0.485289	0.589922	0.485289
	7	0.487575	0.593041	0.487575
	8	0.486082	0.597627	0.486082

0.598421

9 0.486323

```
In [10]: plt.figure(figsize=(15,6))
   plt.subplot(1,2,1)
   plt.scatter(X, T,label = 'training data')
   plt.plot(np.transpose(x_pre),model_NN.predict(np.transpose(x_pre)),'r',label = 'NN prediction from Keras')
   plt.xlabel('x');plt.ylabel('y')
   plt.title('Number of hidden layers=' + str(30) + '; with MSE=' + str(hist['mean_squared_error'].iloc[-1]))
   plt.subplot(1,2,2)
   plt.scatter(np.linspace(0,1499,1500),hist['mean_squared_error'])
   plt.xlabel('Number of iterations');plt.ylabel('MSE')
   plt.title('Cost function convergence plot from Keras')
```

0.486323

