```
┌─────────────────────────────┐
│      view_frames Result     │
│                             │
│   Recorded at time: 103.571 │
└─────────────────────────────┘

                              ( map )
                                 │
                                 │  Broadcaster: /rtabmap/rtabmap
                                 │  Average rate: 20.292 Hz
                                 │  Most recent transform: 103.620 ( -0.049 sec old)
                                 │  Buffer length: 3.499 sec
                                 ▼
                              ( odom )
                                 │
                                 │  Broadcaster: /gazebo
                                 │  Average rate: 50.282 Hz
                                 │  Most recent transform: 103.561 ( 0.010 sec old)
                                 │  Buffer length: 3.540 sec
                                 ▼
                             ( chassis )
```

Broadcaster: /kinect_rotation
Average rate: 10000.000 Hz
Most recent transform: 0.000 (103.571 sec old)
Buffer length: 0.000 sec

Broadcaster: /rob_st_pub
Average rate: 10000.000 Hz
Most recent transform: 0.000 (103.571 sec old)
Buffer length: 0.000 sec

Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec

Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec

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Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec

Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec

Nodes: (link) (hokuyo) (arm_base_plate) (left_wheel_help) (left_wheel) (right_wheel_help) (right_wheel)

(link) →
Broadcaster: /rtabmap/find_object_3d
Average rate: 2.713 Hz
Most recent transform: 103.266 (0.305 sec old)
Buffer length: 3.317 sec
→ (object_12)

(arm_base_plate) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (arm_1)

(arm_1) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (arm_connector_1)

(arm_connector_1) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (arm_2)

(arm_2) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (hand_base_plate)

(hand_base_plate) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (palm)

(palm) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (left_finger)

(palm) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (right_finger)

(left_finger) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (left_finger_tip)

(right_finger) →
Broadcaster: /rob_st_pub
Average rate: 10.292 Hz
Most recent transform: 103.519 (0.052 sec old)
Buffer length: 3.498 sec
→ (right_finger_tip)