NA>_BOT

YANG ZHILI ZHANG YUEQIAN YE TINGMAO ZHAO JINGYING





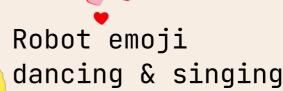
Speech2Text then take action

Recognize Master and follow.















call robot go catch the ball







Auto search and navigation

recognize the master then back











