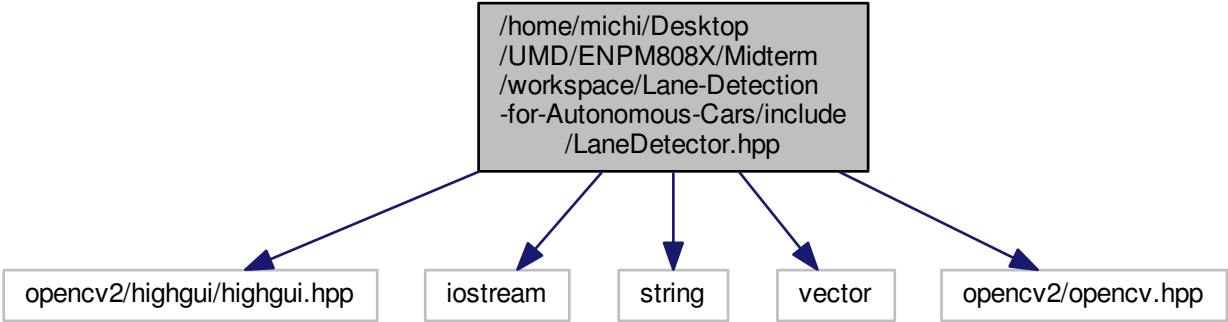


/home/michi/Desktop
/UMD/ENPM808X/Midterm
/workspace/Lane-Detection
-for-Autonomous-Cars/include
/LaneDetector.hpp



```
graph TD; A["/home/michi/Desktop  
/UMD/ENPM808X/Midterm  
/workspace/Lane-Detection  
-for-Autonomous-Cars/include  
/LaneDetector.hpp"] --> B["opencv2/highgui/highgui.hpp"]; A --> C["iostream"]; A --> D["string"]; A --> E["vector"]; A --> F["opencv2/opencv.hpp"];
```

The diagram illustrates the include dependencies for the file `/LaneDetector.hpp`. A central grey box at the top lists the full path to the file. Five blue arrows point from this box to five separate white boxes below, each representing an included header file.

opencv2/highgui/highgui.hpp

iostream

string

vector

opencv2/opencv.hpp