## ISS projekt 2024/25 "Podle hlasu poznáte je ..."

Autor: Radim Dvořák xdvorar00

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```
# needed
import os
import re
import glob
import soundfile as sf
from IPython.display import Audio
from IPython.display import display
# recommended ...
from scipy import signal
from scipy.io import wavfile
from scipy.fft import fft, ifft, fftfreq
import scipy.io
import matplotlib.pyplot as plt
import numpy as np
# read the file - change login to YOUR login
login = "xdvorar00"
zip file = login + ".zip"
assignment file =
"https://www.fit.vut.cz/study/course/ISS/public/proj2024-25/personal/"
+ zip_file
!wget $assignment file
!unzip -o $zip file
--2024-12-16 22:12:24--
https://www.fit.vut.cz/study/course/ISS/public/proj2024-25/personal/
xdvorar00.zip
Resolving www.fit.vut.cz (www.fit.vut.cz)... 147.229.9.65,
2001:67c:1220:809::93e5:941
Connecting to www.fit.vut.cz (www.fit.vut.cz)|147.229.9.65|:443...
connected.
HTTP request sent, awaiting response... 200 OK
Length: 217334 (212K) [application/zip]
Saving to: 'xdvorar00.zip.90'
xdvorar00.zip.90 100%[===========] 212.24K 232KB/s
2024-12-16 22:12:25 (232 KB/s) - 'xdvorar00.zip.90' saved
[217334/217334]
Archive: xdvorar00.zip
```

```
inflating: xdvorar00/BMW 318i Drive.wav
  inflating: xdvorar00/test i.wav
  inflating: xdvorar00/Audi A3 Drive.wav
  inflating: xdvorar00/test n.wav
  inflating: xdvorar00/BMW 1 Drive.wav
  inflating: xdvorar00/test r.wav
  inflating: xdvorar00/Mercedes 300SE Drive.wav
  inflating: xdvorar00/test d.wav
# load the data
# references will be in ref_signals, reference labels in ref_labels,
reference count in N ref.
# tests will be in test signals, test labels in test labels, test
count in N test.
def get signals(labs):
    signals = []
    N = len(labs)
    for car in labs:
      filename = login + "/" + car + ".wav"
      s, Fs = sf.read(filename)
      signals.append(s)
    return signals, N, Fs
def play signals(signals, Fs):
  for signal in signals:
    display(Audio(signal, rate=Fs))
files = glob.glob(login + "/*.wav")
names = [re.sub(login + "/", "", s) for s in files]
labels = [re.sub(".wav", "",s) for s in names]
print ("---- test signals -----")
r = re.compile("^test "); test labels = list(filter(r.match, labels))
print (test labels); test signals, N test, Fs =
get signals(test labels); play signals (test signals, Fs)
print ("----- reference signals -----")
r = re.compile("(?!^test )"); ref labels = list(filter(r.match,
labels))
print (ref labels); ref signals, N ref, Fs = get signals(ref labels);
play_signals (ref_signals, Fs)
---- test signals ----
['test_d', 'test_r', 'test_i', 'test_n']
<IPython.lib.display.Audio object>
<IPython.lib.display.Audio object>
<IPython.lib.display.Audio object>
<IPython.lib.display.Audio object>
```

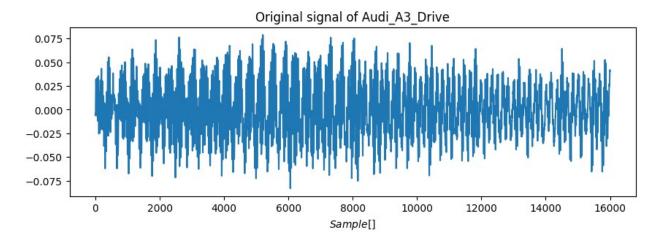
```
---- reference signals ------
['Audi_A3_Drive', 'BMW_318i_Drive', 'BMW_1_Drive',
'Mercedes_300SE_Drive']
<IPython.lib.display.Audio object>
<IPython.lib.display.Audio object>
<IPython.lib.display.Audio object>
<IPython.lib.display.Audio object>
```

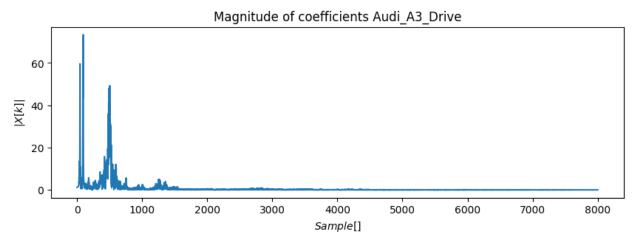
#### Diskrétní Fourierova transformace

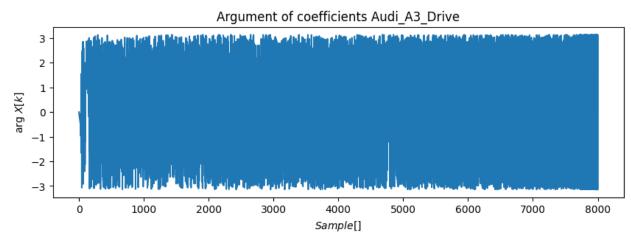
Nejprve si zobrazím refereční signály na časové doméně a zjistím si koeficienty DFT. Koeficienty budou uloženy v polích a to magnituda a argument ve samostatných polích. Tyto koeficienty nám stačí zjistit do N/2 vzorků, další už budou komplexně združené už dříve zjištěným. A pro každý signál si vytvořím spektrální diagram.

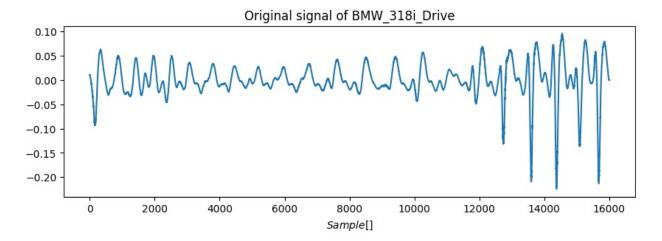
```
N = Fs
n = np.arange(0,N)
ref dft = np.empty(N ref,dtype=object)
ref_dft_mag = np.empty(N_ref,dtype=object)
ref dft arg = np.empty(N ref,dtype=object)
# Pro každý refereční signál udělej DFT
for ref index in range(N ref):
  plt.figure(figsize=(10,3))
  plt.plot(n, ref signals[ref index])
  ref dft[ref index] = np.fft.fft(ref signals[ref index])
  # Stačí jenom N/2 vzorků
  kall = np.arange(0, int(N/2) + 1)
 # Získání magnitudy a argumentu koeficintů
  ref dft mag[ref index] = np.abs(ref dft[ref index][kall])
  ref dft arg[ref index] = np.angle(ref dft[ref index][kall])
  plt.title("Original signal of " + ref labels[ref index])
  plt.xlabel('$Sample []$')
  plt.figure(figsize=(10,3))
  plt.title("Magnitude of DFT coefficients " + ref labels[ref index])
  plt.ylabel('$|X[k]|$')
  plt.xlabel('$Sample []$')
  plt.plot(kall,ref dft mag[ref index])
```

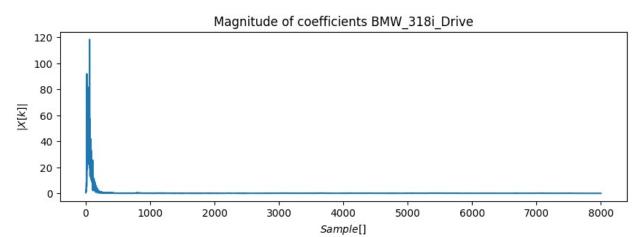
```
plt.figure(figsize=(10,3))
plt.title("Argument of DFT coefficients " + ref_labels[ref_index])
plt.ylabel('arg $X[k]$')
plt.xlabel('$Sample []$')
plt.plot(kall,ref_dft_arg[ref_index])
```

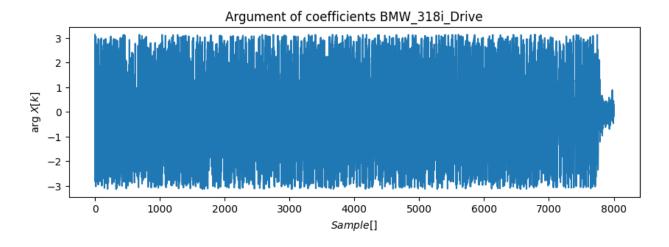


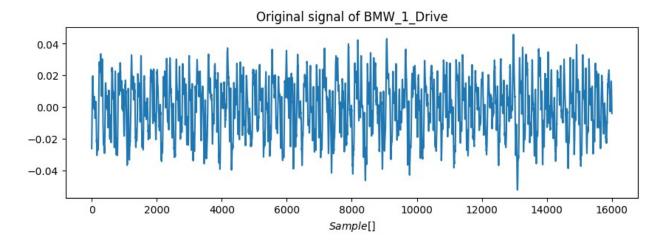


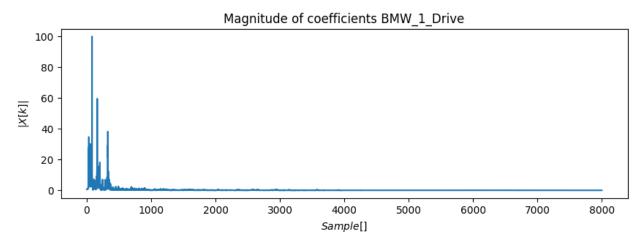


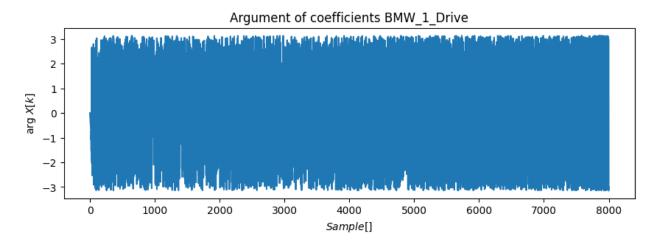


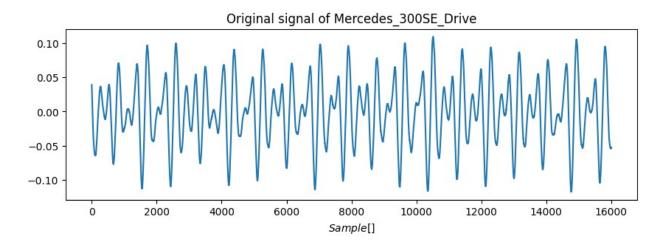


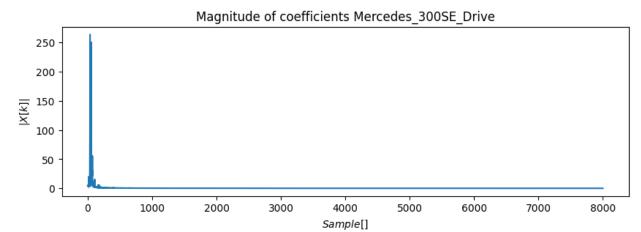


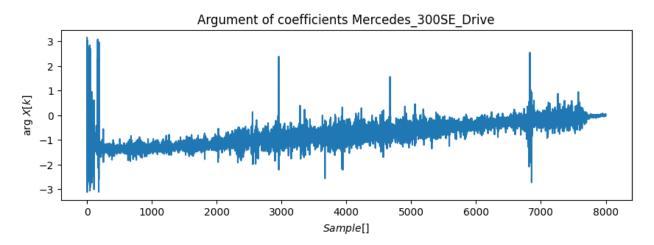








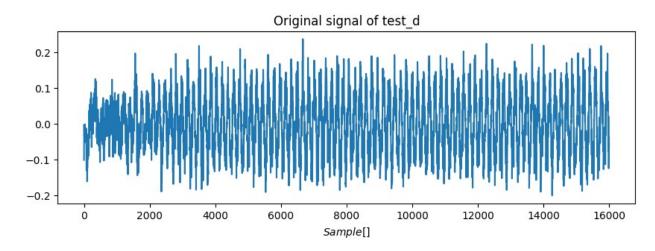


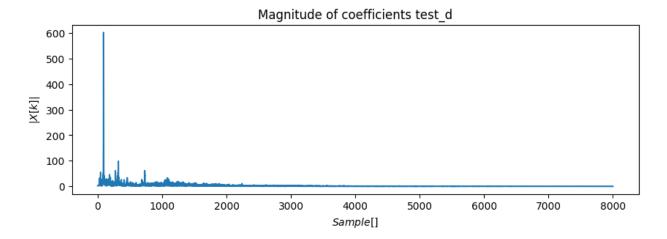


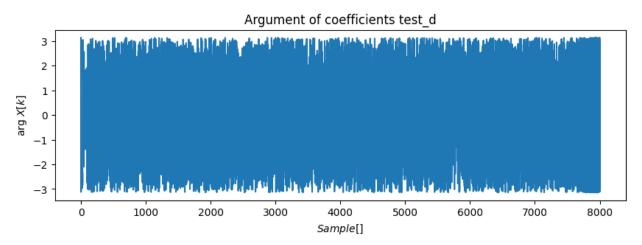
Ůplně stejný postup použiji na testované signály.

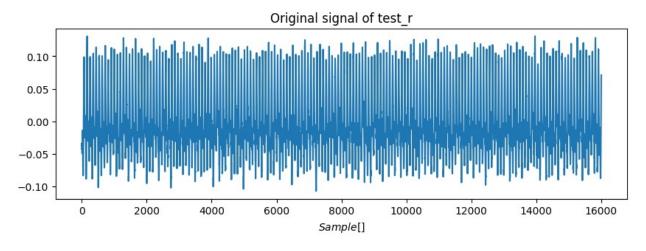
```
test_dft = np.empty(N_ref,dtype=object)
test_dft_mag = np.empty(N_test,dtype=object)
test_dft_arg = np.empty(N_test,dtype=object)
```

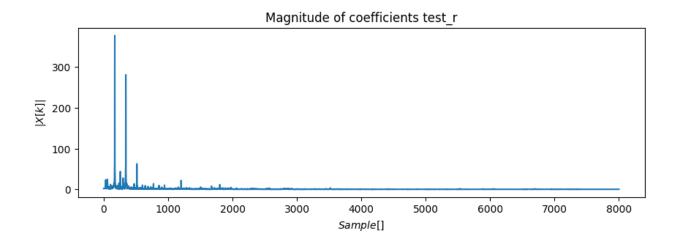
```
# Pro každý testovací signál udělej DFT
for test index in range(N test):
  plt.figure(figsize=(10,3))
  plt.plot(n, test signals[test index])
 test dft[test index] = np.fft.fft(test signals[test index])
  # Stačí jenom N/2 vzorků
  kall = np.arange(0, int(N/2) + 1)
 # Získání magnitudy a argumentu koeficintů
  test dft mag[ref index] = np.abs(test dft[test index][kall])
  test_dft_arg[ref_index] = np.angle(test_dft[test_index][kall])
  plt.title("Original signal of " + test labels[test index])
  plt.xlabel('$Sample []$')
  plt.figure(figsize=(10,3))
  plt.title("Magnitude of DFT coefficients " +
test labels[test index])
  plt.ylabel('$|X[k]|$')
  plt.xlabel('$Sample []$')
  plt.plot(kall,test_dft_mag[ref_index])
  plt.figure(figsize=(10,3))
  plt.title("Argument of DFT coefficients " + test labels[test index])
  plt.ylabel('arg $X[k]$')
  plt.xlabel('$Sample []$')
  plt.plot(kall,test dft arg[ref index])
```

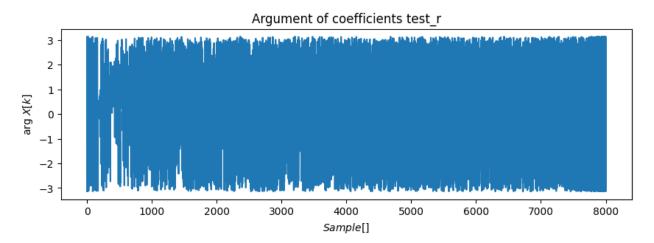


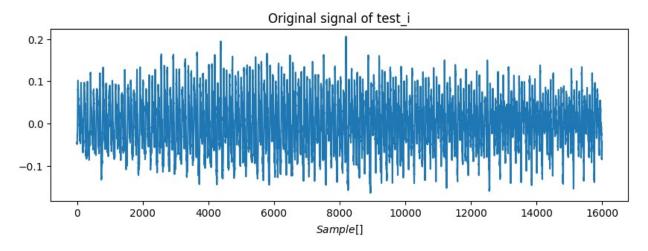


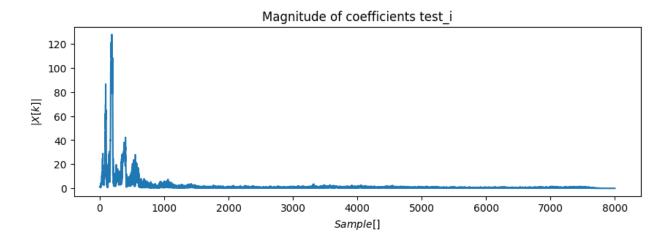


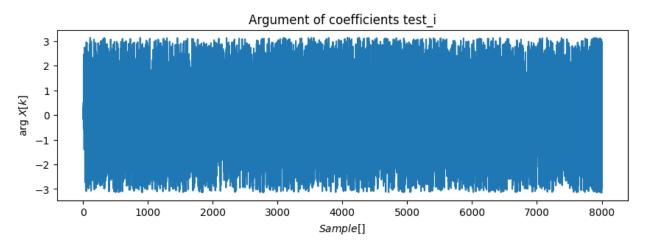


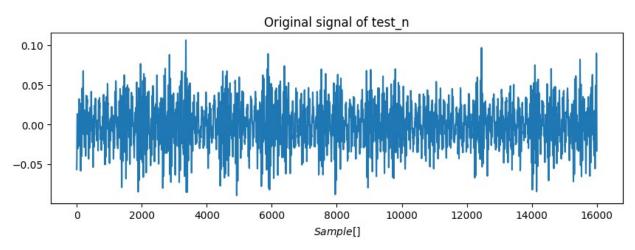


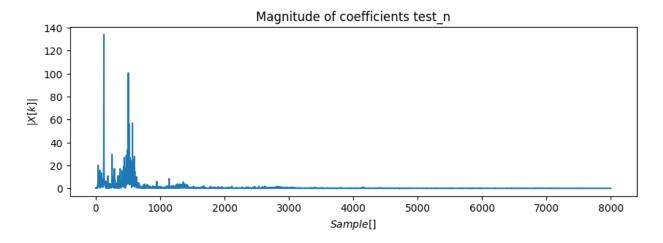


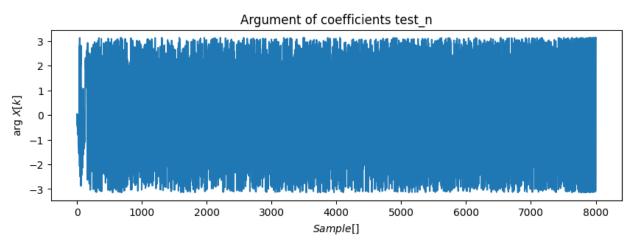












### Frekveční doména

V této části zkombinuju násobění koeficientů DFT testovacího signálu a známého signálu a a vynásobení vzorků obou signálů a následné provedení DFT. Oba způsoby budou váhově ohodnoceny Tímto získáme podobnost ve frekveční doméně.

```
#weighs for calculating weighted coefficient
w1 = .8
w2 = .7
for test_index in range(N_test):
    corr_index = 0
    for ref_index in range(N_ref):
        prev_corr = 0
        corr = w1 * sum(test_dft[test_index] * ref_dft[ref_index]) + w2 *
sum(test_signals[test_index] * ref_signals[ref_index])
        if corr > prev_corr:
            corr_index = ref_index
            prev_corr = corr
```

```
print("Test sample: " + test_labels[test_index] + " Reference
sample: " + ref_labels[corr_index] + " Similarity:",abs(corr))

Test sample: test_d Reference sample: BMW_318i_Drive Similarity:
13565.797480192652
Test sample: test_r Reference sample: BMW_318i_Drive Similarity:
1739.8864989906517
Test sample: test_i Reference sample: Mercedes_300SE_Drive Similarity:
2463.1724542112975
Test sample: test_n Reference sample: Mercedes_300SE_Drive Similarity:
9178.395137480304
```

## Dynamic time warping

Z výsledků je patrné že toto není velmi efektivní metoda, protože přiřazuje ke dvou testovacím vzorkům stejný známý signál. Jako další algoritmus zvaný Dynamic time warping(DTW), které dokáže posoudit zda dva signály se liší v rychlosti. Pro každý testovací signál porovnám pomocí tohoto algoritmu každý známý signál.

```
!pip install fastdtw
from fastdtw import fastdtw
for test index in range(N test):
  corr index = 0
  for ref index in range(N_ref):
    prev corr = 0
    distance, =
fastdtw(ref_signals[ref_index],test signals[test index])
    if distance < prev corr:</pre>
      corr index = ref index
      prev corr = distance
  print("Test sample: " + test labels[test index] + " Reference
sample: " + ref labels[corr index] + " Distance:",distance)
Requirement already satisfied: fastdtw in
/usr/local/lib/python3.10/dist-packages (0.3.4)
Requirement already satisfied: numpy in
/usr/local/lib/python3.10/dist-packages (from fastdtw) (1.26.4)
Test sample: test d Reference sample: Audi A3 Drive Distance:
860.1330871582031
Test sample: test_r Reference sample: Audi_A3_Drive Distance:
575.8416748046875
Test sample: test i Reference sample: Audi A3 Drive Distance:
744.1375122070312
Test sample: test n Reference sample: Audi A3 Drive Distance:
403.6739501953125
```

### Závěr

S použitými dvěma metodami jsem nedokázal ůčinně dokázat, jaké nahrávky patří k sobě. A nedokázal jsem ani odhalit jestli je nějaká nenáleží k známé nahrávce.

# Seznam použité literatury

- [1] https://stackoverflow.com/questions/20644599/similarity-between-two-signals-looking-for-simple-measure
- [2] https://en.wikipedia.org/wiki/Dynamic\_time\_warping
- [3] https://dsp.stackexchange.com/questions/76673/what-algorithm-can-i-use-to-compare-two-signals-similarity
- [4] Hlasy v mojí hlavě