

A Real-time Model Predictive Control of a Non-linear Robotic System Using a Physics Engine

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Abstract—The abstract goes here.

I. INTRODUCTION

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August 26, 2015

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II. CONCLUSION

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ACKNOWLEDGMENT

The authors would like to thank...

REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to L^AT_EX*, 3rd ed. Harlow, England: Addison-Wesley, 1999.