

Design and Analysis of Algorithms

Graphs 3: Depth-First Search

Daniel Shannon

April 20th, 2022

3.3.3

For all nodes u, v , either $[pre[u], post[u]]$ is completely within $[pre[v], post[v]]$, or the other way around, or there is no overlap. Why? $pre[u]$ to $post[u]$ is the time u is on the stack.

This is because each $[pre[u], post[u]]$ is completely within $[pre[v], post[v]]$ because only unexplored nodes are added to the stack. So, when a node is added to the stack (u), all of the nodes for (v) will be discovered before the stack is emptied and returns to u . This is because v cannot be added to the exploration of u . The name depth-first sort of implies this, too. If we start at a node (u), we search as deep as we can before returning to u , so any v searches will take less time than u .

3.3.5

What is the running time of DFS?

The running time of DFS is $O(N)$

```
procedure explore(G,v)
Input: G(V,E) is a graph; v is in V
Output: visited(u) is set to true for all nodes u reachable from v
    previsit(v)                //c1
    visisted(v)=true           //c2
    for each edge (v,u) in E:   //N(E)
        if not visited(u): explore(u) //c3
    postvisit(v)
```

It appears that the running time is $O(N)$, or or $O(E)$, since we call explore on depending on the size of the Edges. Each edge is explored 1 time!