



Univerza v Ljubljani  
Fakulteta za računalništvo  
in informatiko

Naročnik  
Ime projekta

Fakulteta za računalništvo in informatiko  
Robotska roka

Ime proizvajalca  
Vrsta dokumentacije

UL FRI  
Električna dokumentacija

Modification date

19/10/2023

by (short name)

Number of pages 13

# SEZNAM OMAR

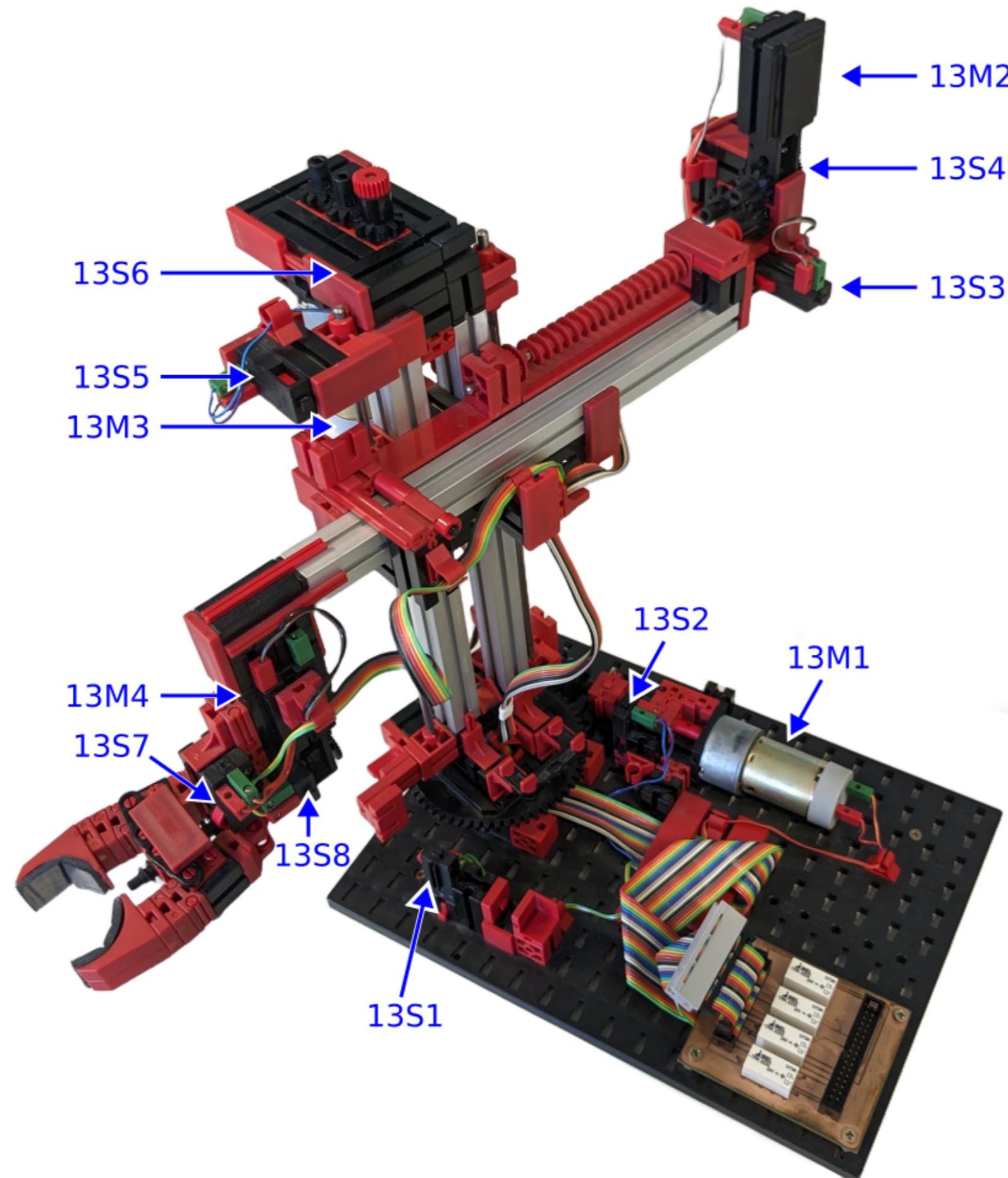
=FRI (Fakulteta za računalništvo in informatiko)

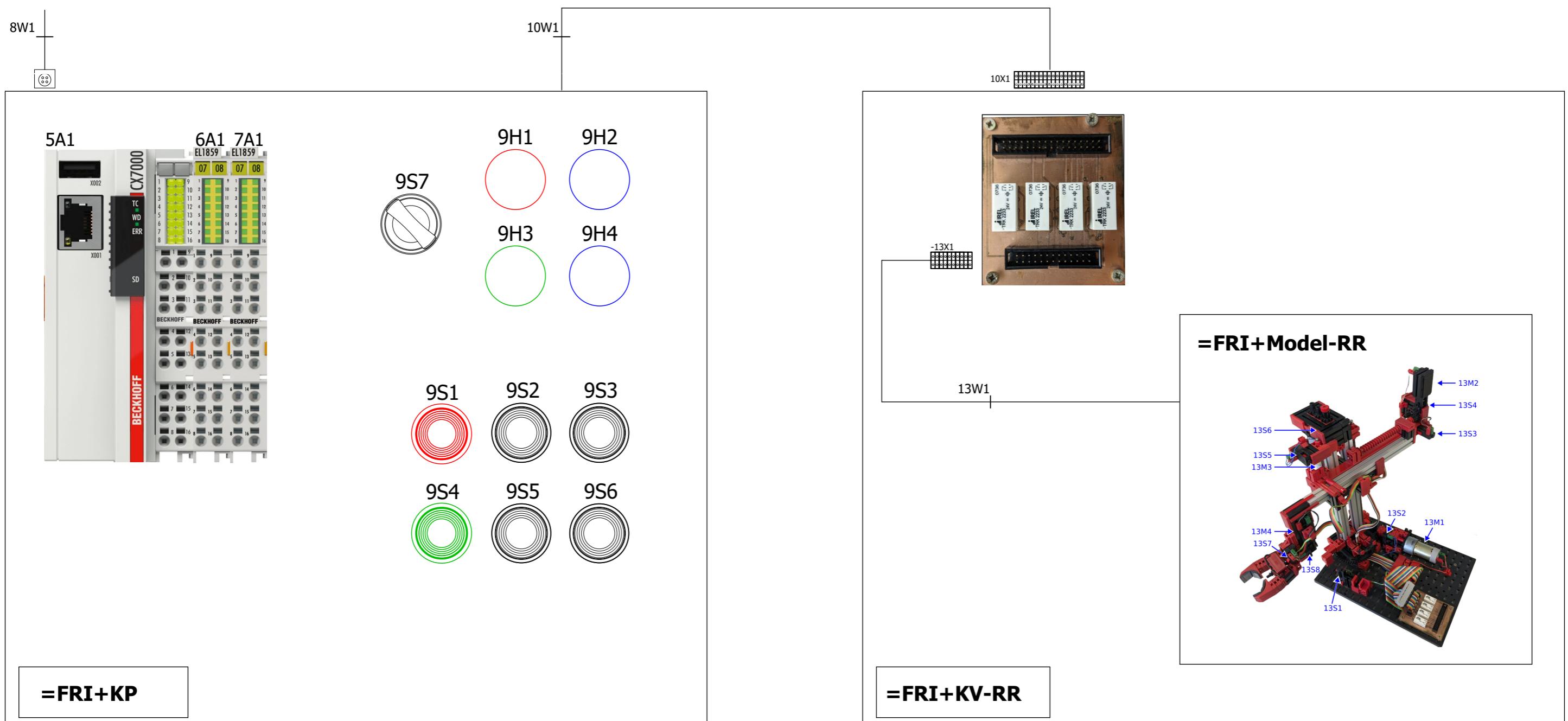
- +KP (Krmilna plošča)
- +KV - RR (Krmilno vezje - Robotska roka)
- +Model - RR (Model - Robotska roka)

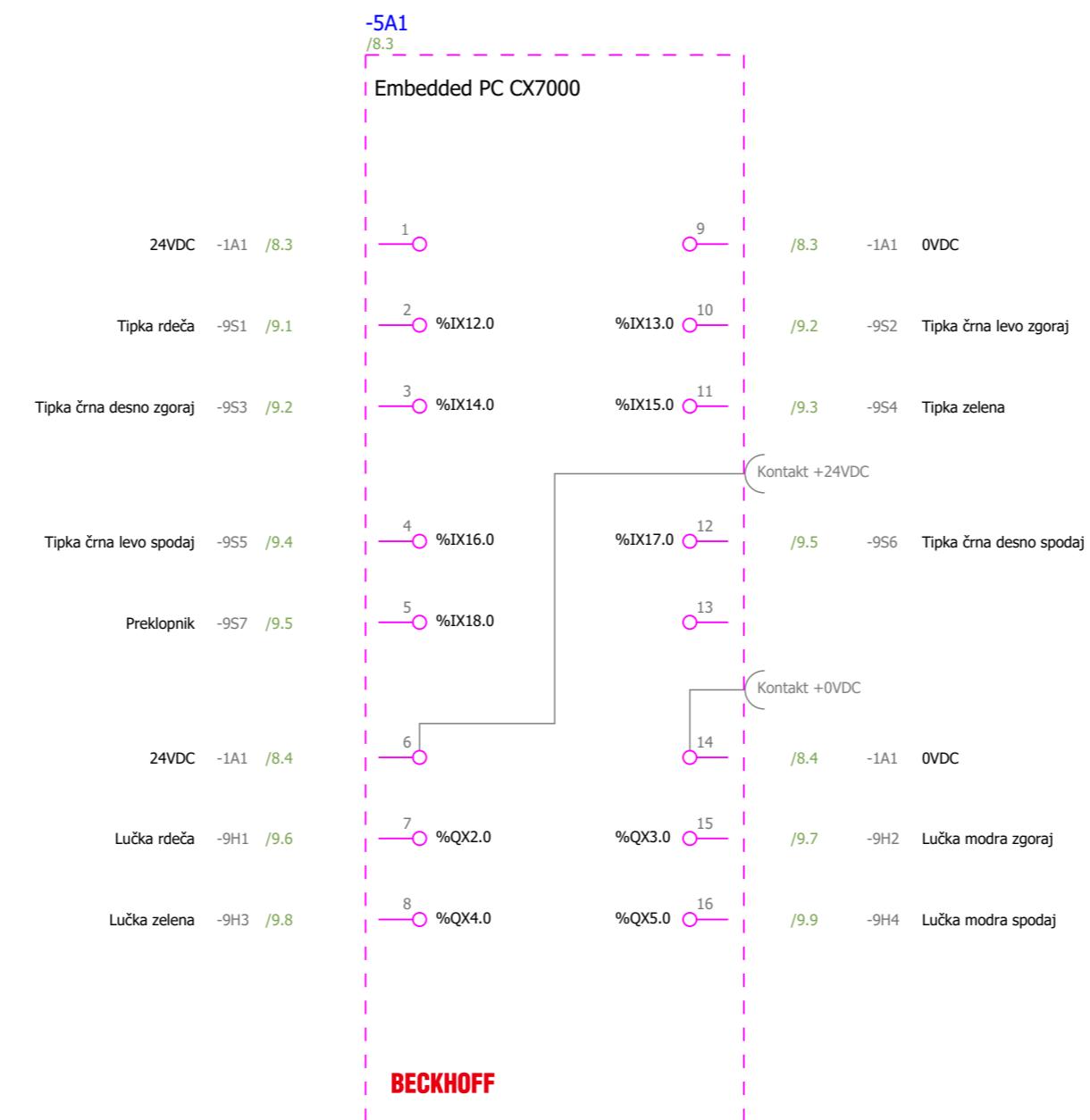
# OZNAKE ELEMENTOV

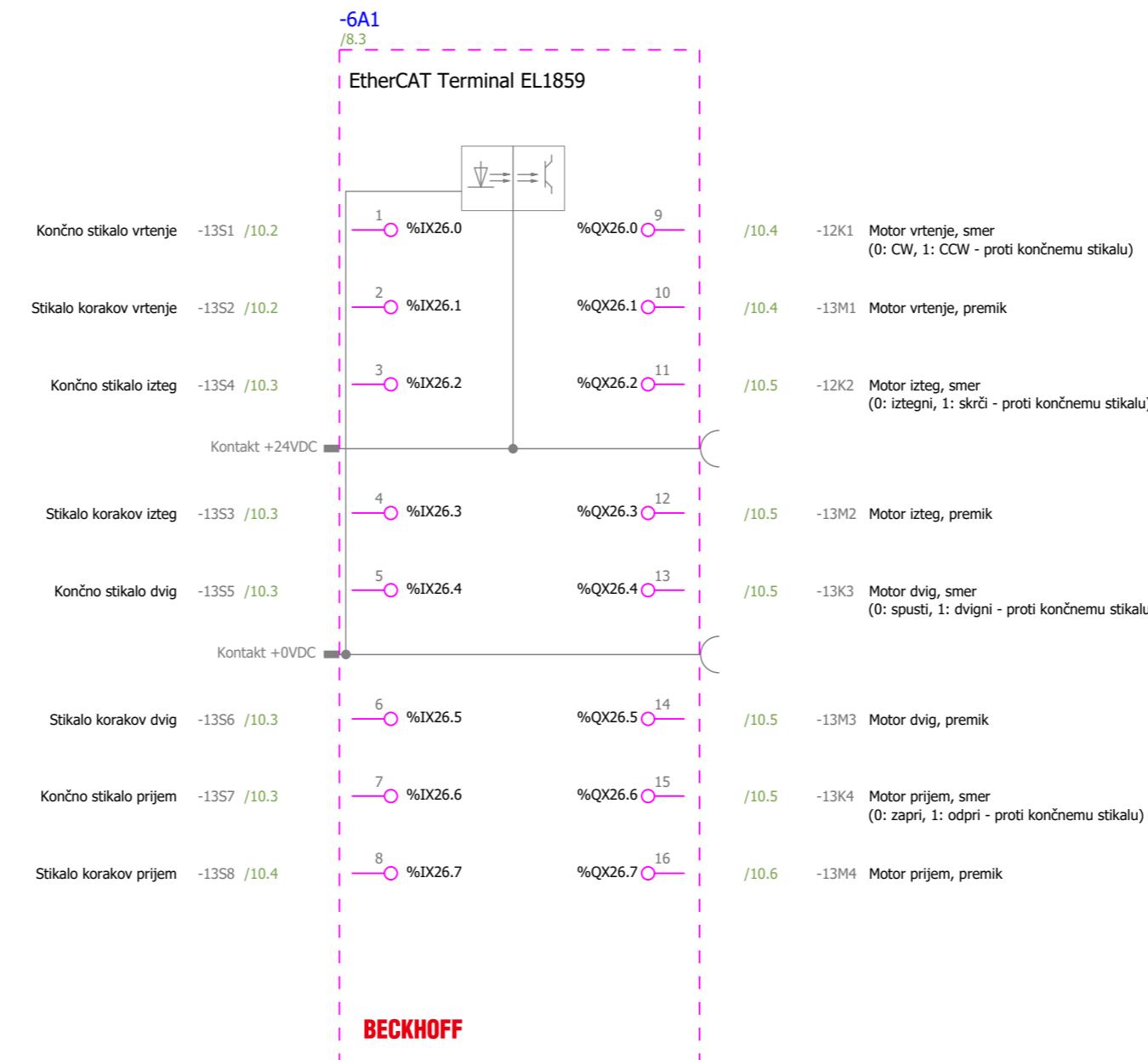
- T - usmernik
- A - PLC in IO terminal
- K - rele
- M - motor
- B - senzor
- S - tipka / preklopnik / stikalo
- H - lučka
- X - konektor
- W - kabel
- R - upor
- Y - ventil

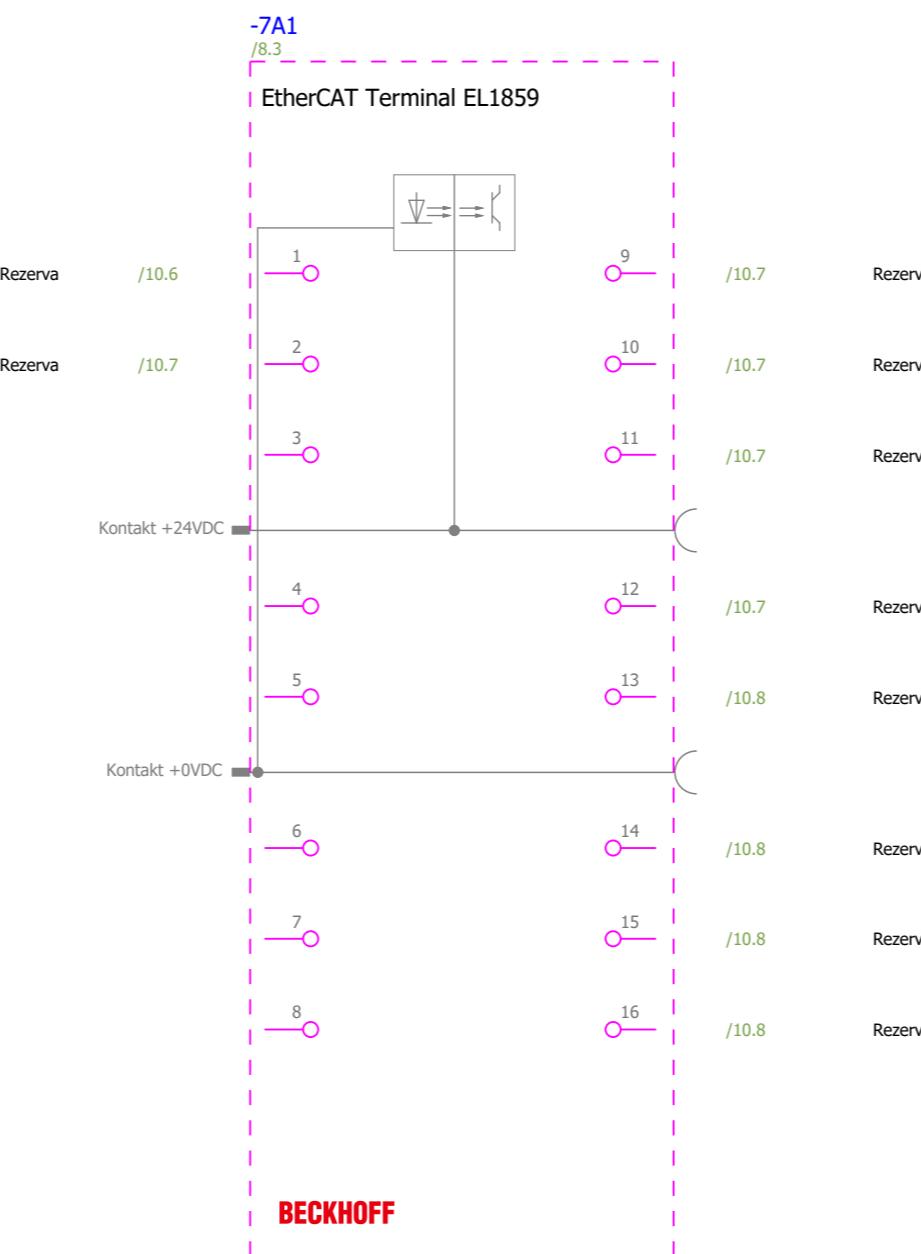
# MOTORJI in SENZORJI

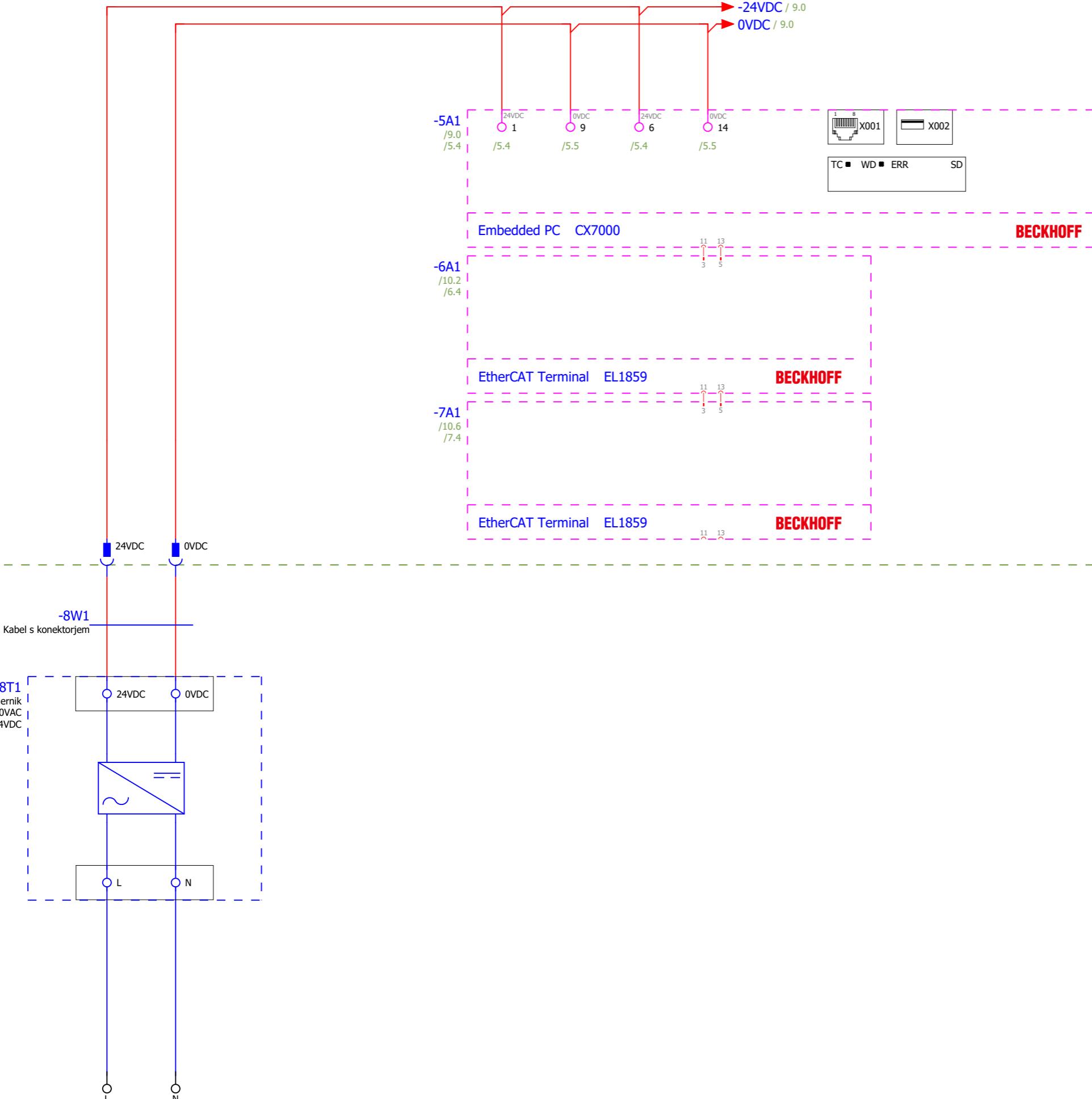


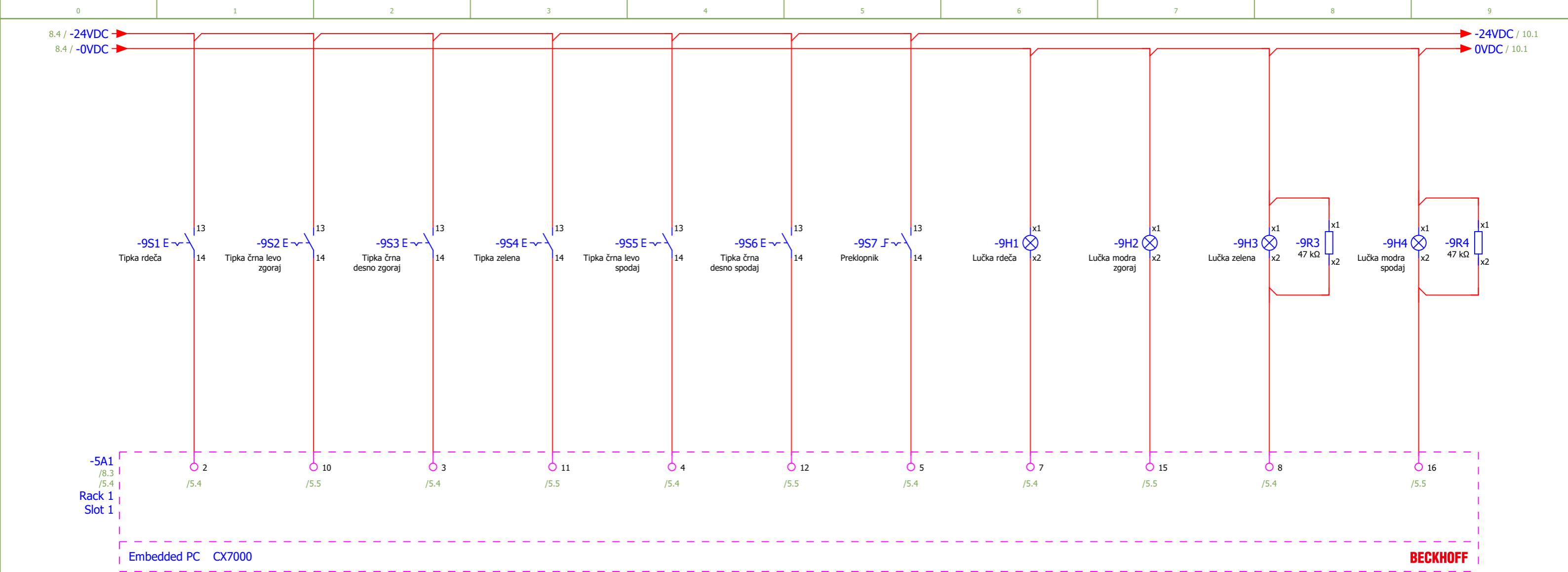




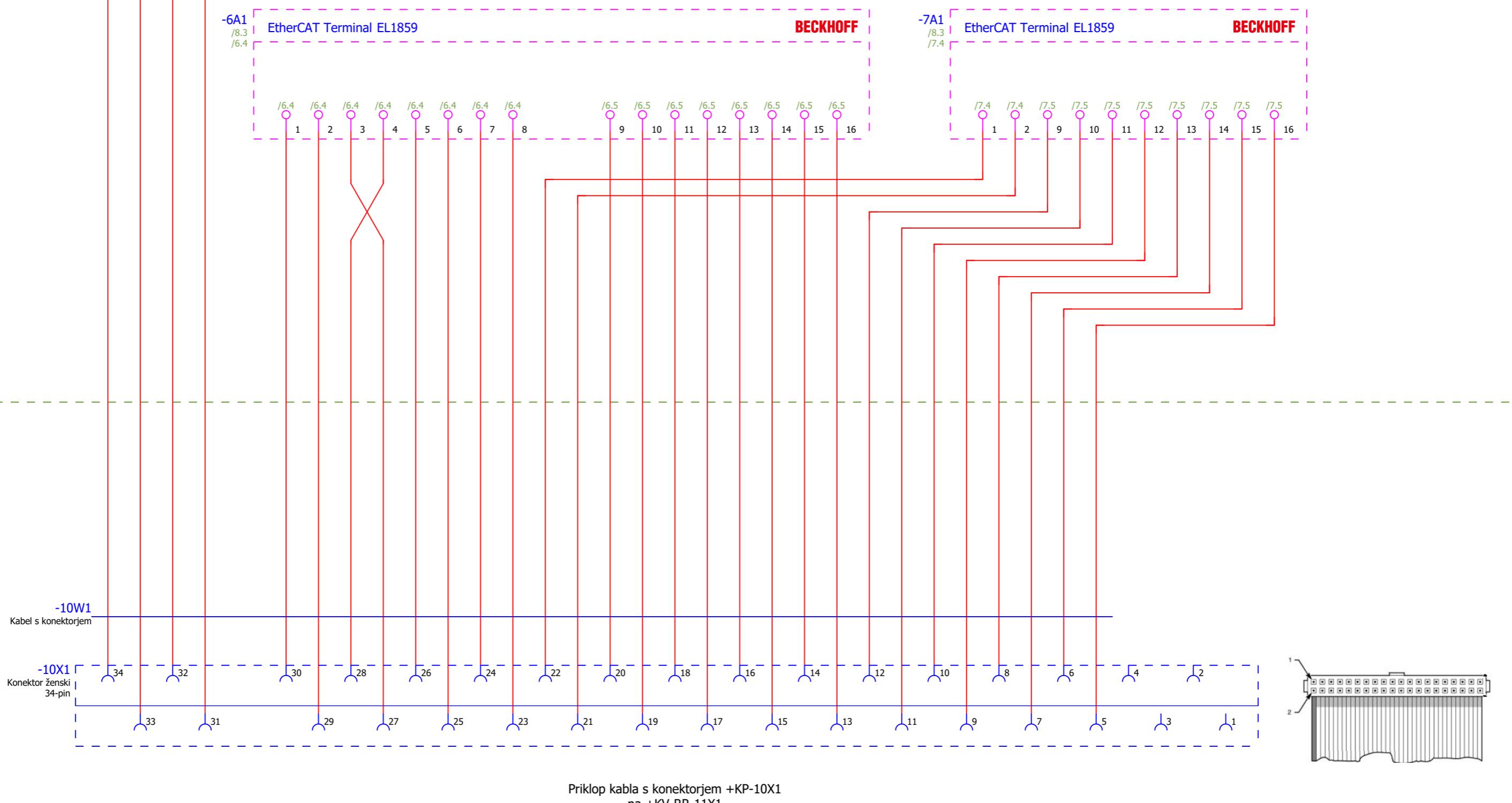




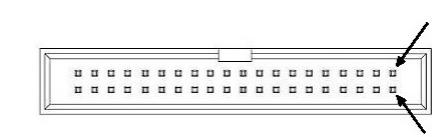
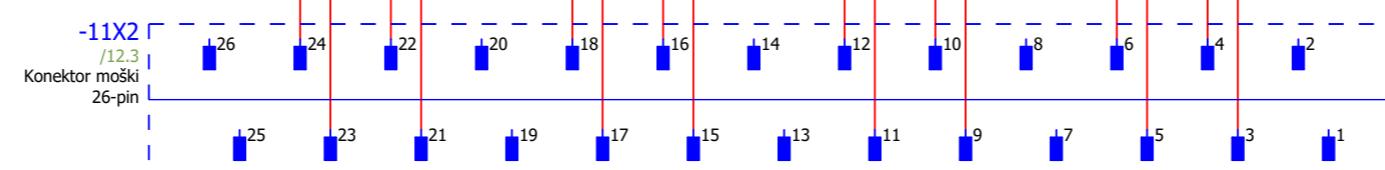
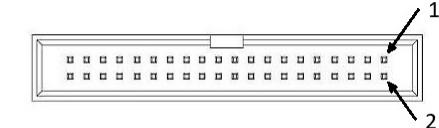
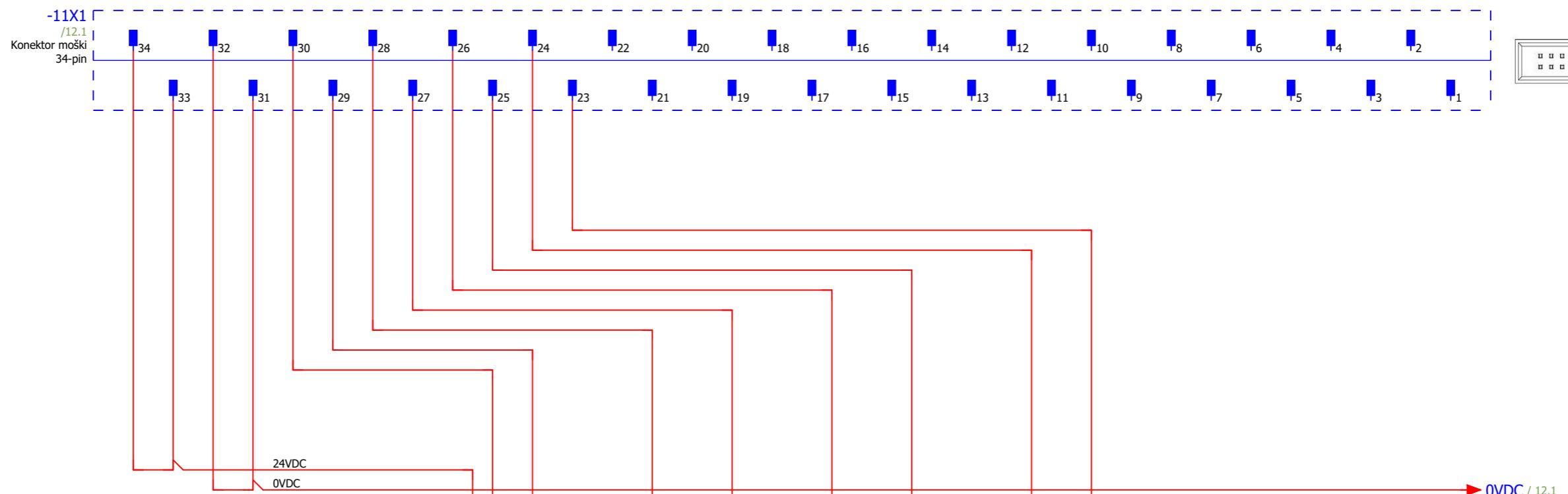




9.9 / -24VDC  
9.9 / -0VDC

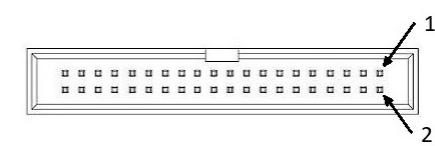
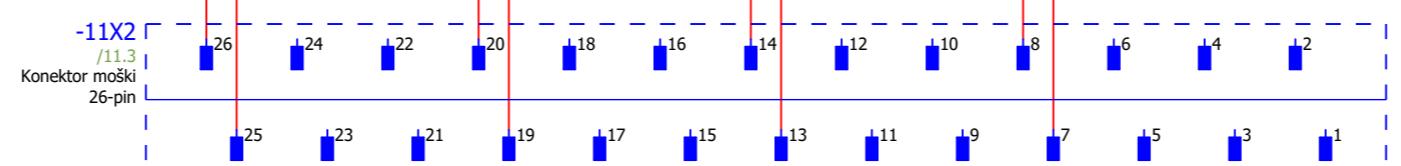
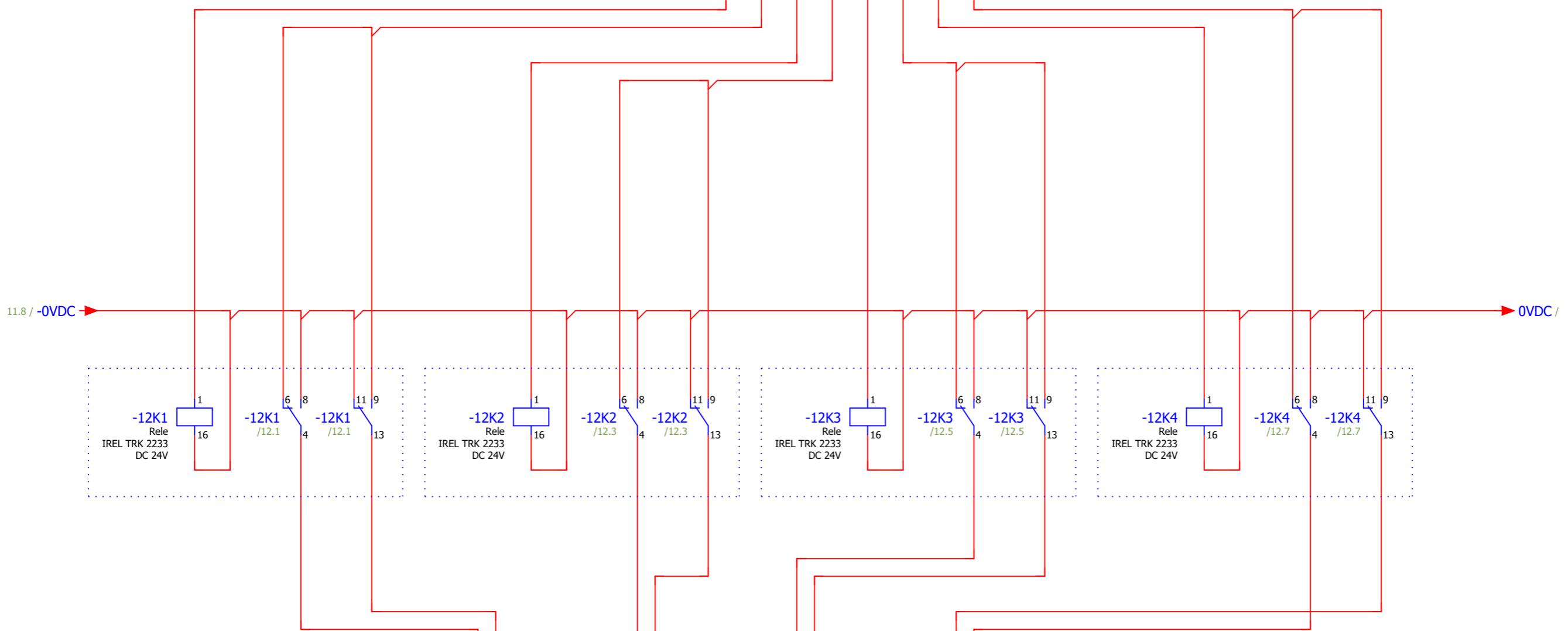
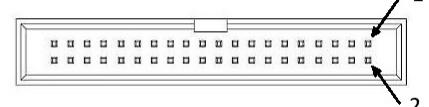
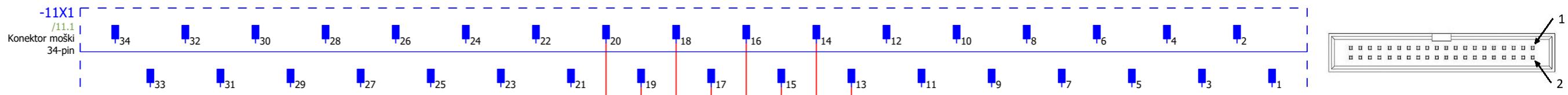


Priklop kabla s konektorjem +KP-10X1  
na +KV-RR-11X1



Priklop kabla s konektorjem +KV-RR-13X1  
na +KV-RR-11X2

Priklop kabla s konektorjem +KP-10X1  
na +KV-RR-11X1



Priklop kabla s konektorjem +KV-RR-13X1  
na +KV-RR-11X2

8 4 /12.2  
6 13 /12.2  
9 11 /12.2

8 4 /12.4  
6 13 /12.4  
9 11 /12.4

8 4 /12.5  
6 13 /12.6  
9 11 /12.5

8 4 /12.7  
6 13 /12.8  
9 11 /12.7

+ KV-RR

Priklop kabla s konektorjem +KV-RR-13X1  
na +KV-RR-11X2

