

2282463

Requirements Specification

FRS AUS4 Camera

Information Classification

Introduced ECO

495446

Approved Date Page

Approved by Sven Stafner Issued by Daniel Velcic

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Requirements Specification FRS AUS4 Camera

Page
2
2
7
7
7 7
7
7
8
8
10
11
11
16
20
20
20
20
22
22 22
22
a)23



2282463

Requirements Specification

FRS AUS4 Camera

Issued by Daniel Velcic

1 General

1.1 Version history

Version	Author	Content		Date	
1.0	Adeliina Aho Tarkka	First version		2012-04-11	
2.0	Christer Aspman	General		2013-09-23	
		Added version handling on requirements	3		
		Updated requirements New vers	sion		
		UFR 523_Camera view_11 2			
		UFR 523_Camera view_14 2			
		UFR 523_Camera view_18 2			
		Deleted requirements			
		UFR 523_Camera view_20			
		UFR 523_Camera view_21			
		UFR 523_Camera view_22			
		New requirements			
		UFR 523_Camera view_23 to UFR 523_	_Camera view_58		
(3.0)	Christer Aspman	General		2013-02-01	
0		Added parameters and CAN signals.			
		Broken down requirements from UFR.			
		Merged with AER document.			
		Changed to FRS specification template			
		Changed requirement ID prefix from			
		UFR 523_Camera view_ to			
		FRS523_	1 4:6: 1		
		e g UFR 523_Camera view_58 is now in FRS523 58	ientified as		
		New version (0) due to new document to	amnlate		
		Updated requirements	New version		
		Opulied requirements	New version		
		Deleted requirements			
		78			
		New requirements			
		FRS523 59 to FRS523 112			
1	Christer Aspman	General		2013-12-19	
•	Saloto: Hopinal	Updated references			
		Updated abbreviations			
4					
		Updated requirements	New version		
		FRS523 14	3		
		FRS523 16	2		
	FRS523 109 2				
		FRS523_74	2		
		FRS523 87	2		
		FRS523 16	2		
		Deleted requirements	1		



2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page Daniel Velcic ssswmn sssnrg I S 8 3 (23)

				,
		AUS4_RFQ_1		1
		AUS4_RFQ_2]
		AUS4_RFQ_3]
		AUS4_RFQ_4]
		AUS4_RFQ_5		
		AUS4_RFQ_6		
		AUS4_RFQ_7		
		AUS4_RFQ_8		
		FRS523_59		
		FRS523_72		
		FRS523_107]
		FRS523_108		
		FRS523_89]
		FRS523_27		
		FRS523_10		
		FRS523_74]
		FRS523_24]
		FRS523_36]
		FRS523_59]
		FRS523_38]
		FRS523_72		
		FRS523_73]
		FRS523_46]
		FRS523_86		
		FRS523_95]
		FRS523_96]
		New requirements		
		FRS523_113 to FRS523_128		
2	Christer Aspman	General		2014-06-16
		Updated according to internal reviews		
		Updated according to new CAN specif		
		Requesting display and camera function	on moved to Utility	
		Management FRS.	Now yordian	-
		Updated requirements	New version	
		FRS523_30	2	
		FRS523_43	2	
		FRS523_90	2	
		FRS523_91	2	
		FRS523_115	2 2	
		FRS523_116 FRS523_121	2 2	
		FRS523_121 FRS523_122	2 2	
		FRS523_127	2	
		FRS523_127 FRS523_128	2	
		Deleted requirements	<u> </u>	1
		FRS523_13		1
		FRS523_13 FRS523_117		
		FRS523_118		
		FRS523_116 FRS523_119		
I		1110020_110		

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2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page Daniel Velcic ssswmn S 8 4 (23) sssnrg

		FRS523_120	
		FRS523_123	
		FRS523_124	
3	Christer Aspman	General	2014-06-27
		Removed Hazard analysis.	
		Added FRS523_129.	
4	Christer Aspman	Added timer for reverse camera.	2014-09-03
		Major cleaning. Removed a lot of requirements due to	
		double information.	
		Updated CAN-table.	
		Updated parameter names.	
		Name and a sector	
		New requirements	
		FRS523_130	
		FRS523_131	
		Updated requirements	
		FRS523 12	
		FRS523_14	
		FRS523_25	
		FRS523 39	
		FRS523_	
		FRS523_63	
		FRS523_64	
		FRS523_68	
		FRS523_69	
		110025_00	
		FRS523_82	
		FRS523_83	
		FRS523_90	
		FRS523_91	
		FRS523_99	
		FRS523_106	
		FRS523_127	
		FRS523_128	
		Deleted requirements	
		FRS523_11	
		FRS523_15	
		FRS523_17	
		FRS523 19	
		FRS523_28	
		FRS523_29	
		FRS523_30	
		FRS523_31	
		FRS523_32	
		FRS523_33	
		FRS523_34	
		FRS523_35	



2282463

Requirements Specification

FRS AUS4 Camera

Issued by
Daniel Velcic

		FRS523_37 FRS523_40 FRS523_43 FRS523_44 FRS523_45 FRS523_47 FRS523_48 FRS523_49 FRS523_51 FRS523_58 FRS523_61 FRS523_65 FRS523_70 FRS523_70 FRS523_75 FRS523_79 FRS523_80 FRS523_81 FRS523_81 FRS523_84 FRS523_87 FRS523_93 FRS523_93 FRS523_94 FRS523_98 FRS523_105 FRS523_113 FRS523_114	
5	Daniel Velcic	General Updated according to internal reviews and comments. Updated requirements FRS523_16 FRS523_25 FRS523_53 FRS523_62 FRS523_127 FRS523_128	2015-04-13
6	Daniel Velcic	General Updated according to discussions in final OPL Updated requirements FRS523_42 FRS523_69	2015-09-07
7	Daniel Velcic	General Updated after fault detection in testing. Updated requirements FRS523_125 FRS523_126 FRS523_127 FRS523_128	2015-11-27



2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page Daniel Velcic Ssswmn sssnrg I S 8 6 (23)

8	Daniel Velcic	General Update after discussions of the Requirements Updated requirements FRS523_18 FRS523_52 FRS523_56 2.1 Parameters	2015-12-17
9	Daniel Velcic	General Update after discussions of the Requirements New requirements FRS523_132	2016-01-12
10	Daniel Velcic	General Update after discussions of the Requirements New requirements FRS523_133 Updated requirements FRS523_130 FRS523_132	2016-01-28
11	Daniel Velcic	General Corrections of the Requirements after Review Deleted requirements FRS523_132 for later SOP Updated requirements FRS523_125-128 Parameters (Speed Range to 255) ReverseCameraActiveTimer to 255 SteeringWheelPosition added Values FRS523_50 FRS523_52 FRS523_16	2016-02-26
12	Daniel Velcic	General Corrections of the Requirements after Review Updated requirements 2.2 Sensors and actuators 3.2 Can Communication requirements (Media) 3.2.1 Can Communication requirements (General Camera) 3.3.2 General requirements (Front Camera) 3.3.3 Can Communication requirements (Front Camera) 3.4.2 General requirements (Reverse Camera) 3.4.3 Can Communication requirements (Reverse Camera) FRS523_12 FRS523_23 FRS523_62 FRS523_66	2016-04-21



2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page
Daniel Velcic Ssswmn sssnrg I S 8 7 (23)

		FRS523_69 FRS523_133	
		New requirements FRS523_134 FRS523_135 FRS523_136	
13	Daniel Velcic	Updated requirements FRS523_52 FRS523_23	2016-04-25

1.2 Purpose

The purpose with this document is to list the functionality for the new infotainment system SRS 2126748, which will be possible to implement in both trucks and coaches. This document describes the camera functionality requirements.

1.3 Background

When driving a heavy vehicle it can sometime be difficult for the driver to have a good overview around the vehicle. In these situations a camera can be a great help and show areas that the driver otherwise would not have seen.

With a camera solution connected to the vehicle the driver can receive additional information to what can be seen via the mirrors. The camera solution will enable the driver to see areas around the vehicle that are difficult to see from the driver's seat, and can therefore detect and avoid hazardous situations. The cameras can also be used for monitoring body-builder functionality and loads.

1.4 General description of the function

A camera view shall be shown in the display of the infotainment system. The video image shall be provided via an available video input. The video source can be a directly connected camera or a camera ECU. It shall not be necessary to specify the purpose of the video input, i.e. it can be a reverse view camera, a front camera, etc. EOL parameters will define the purpose of each video input on each unique vehicle.

The driver shall be able to activate the camera view via the infotainment system, but it shall also be possible to activate the camera view via a pin. When the camera view is active other functionality in the system, e.g. sound, shall not be affected.

Please note, the camera functionality shall not replace the rear view mirrors, but shall be possible to replace the front mirrors and side view mirrors.

1.5 Abbreviations

AUS	Audio System
CAN	Controller Area Network
НМІ	Human Machine Interface

1.6 References

- 1. 2126748 SRS Audio system
- 2282481 CAN COMMUNICATION SPECIFICATION



2282463

Requirements Specification

FRS AUS4 Camera

Checked 1 Checked 2 Information Classification Status Revision Page ssswmn sssnrg I S 8 8 (23)

Issued by Daniel Velcic

- Audio System AUS4
- 3. ISO/DIS 16505 Road Vehicles Ergonomic and performance aspects of Camera Monitoring Systems Requirements and test procedures .
- 4. 2003/97/EG DIRECTIVE 2003/97/EC OF THE EUROPEAN PARLIAMENT AND OF THE COUNCIL of 10 November 2003
- 5. Diagnostics specification, 2307207 (Standard)
- 6. FRS 2289909 Utility Management
- 7. 2128872 HW Requirement specification

2 Inputs/Outputs

2.1 Parameters

Туре	Name	Range	Unit
EOL	FrontCameraUpperSpeedLimit	0 – 255	km/h
EOL	FrontCameraUpperSpeedHysteresis	0 – 255	km/h
EOL	Camera1ReverseGeneralForwardDeactivationSpeed	0 – 255	km/h
EOL	Camera2ReverseGeneralForwardDeactivationSpeed	0 – 255	km/h
EOL	Camera1ReverseGeneralForwardHysteresis	0 – 255	km/h
EOL	Camera2ReverseGeneralForwardHysteresis	0 – 255	km/h
EOL	Camera1StartupTime	0 = off 1-5100	ms
EOL	Camera2StartupTime	0 = off 1-5100	ms
EOL	ReverseCameraActiveTimer	0 = NoTimer 1 - 255	s
EOL	Camera1	Off GeneralCamera ReverseCamera FrontCamera	
EOL	Camera2	Off GeneralCamera ReverseCamera FrontCamera	
EOL	ReverseGuidelinesCamera1	Off Image 1 To Image 10	
EOL	ReverseGuidelinesCamera2	Off Image1 To Image10	
EOL	GeneralCameraActivationWorklightCamera1	Off On	
EOL	GeneralCameraActivationWorklightCamera2	Off On	
EOL	GeneralCameraActivationDirectionIndicatorsCamera1	Off On	
EOL	GeneralCameraActivationDirectionIndicatorsCamera2	Off On	

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2282463

Requirements Specification

FRS AUS4 Camera

Issued by Daniel Velcic

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Туре	Name	Range	Unit
EOL	SteeringWheelPosition	LHD	
		RHD	
		Center (Bus)	
		None	

^{*}Camera1StartupTime and Camera2StartupTime in steps of 20ms



2282463

Requirements Specification

FRS AUS4 Camera

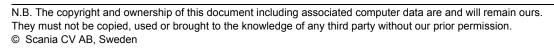
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CAN signals

Direction	Message	Signal
		WheelBasedVehicleSpeed
Received	CruiseControlVehSpeed	ParkingBrakeSwitch
		DirectionIndicatorRightIntended
		DirectionIndicatorLeftIntended
Received	CUVInformation	WorklightToggleSwitch
Received	ETC5	ReverseSwitch
		VideoLineIn1Available
		VideoLineIn2Available
		VideoLineIn3Available
Sent	MediaStreamSourceAvailable	VideoLineIn4Available
		VideoLineIn1Connected
		VideoLineIn2Connected
		VideoLineIn3Connected
Sent	MediaStreamSourceConnected	VideoLineIn4Connected

2.2 Sensors and actuators

Туре	Number	Name	Range	Unit	Description/Comment
Analogue in		Camera1 Activate	0-24	V	See Ref. 7 HW spec.
Analogue in		Camera2 Activate	0-24	V	See Ref. 7 HW spec.
Analogue out		Camera 1 wake-up	0-12	V	See Ref. 7 HW spec.
Analogue out		Camera 2 wake-up	0-12	V	See Ref. 7 HW spec.
Analogue in		Camera 1		CVBS (PAL and NTSC)	
Analogue in		Camera 2		CVBS (PAL and NTSC)	





2282463

Requirements Specification

FRS AUS4 Camera

Checked 1 Checked 2 Information Classification Status Revision Page **Daniel Velcic** ssswmn S 8 11 (23) sssnrg

3 **Function requirements**

2 Camera inputs shall be available. OSD (On Screen Display) shall be possible, e.g. to show help lines, distance marks or menu items on the camera image. The camera image shall never freeze since the system may be safety critical. The hardware shall therefore be designed to minimize freezes and delays, for example the video image shall not be affected by the system software. The system shall support both the PAL and NTSC video format. The system needs to automatically detect the format used and make necessary adjustments to be able to show the camera image without any user interaction.

3.1 General

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Req-ID	ver	Requirement
FRS523_110	1	The camera function shall be available in performance step Standard.
FRS523_9	1	The camera image shall be shown on the display of the system. The image shall be provided via a video input. The video source can be a directly connected camera or via a camera ECU.
FRS523_12	3	It shall be possible to activate and deactivate each camera input automatically, e.g. via a reverse signal or speed signal on CAN. manually, via hard key. via hardware pin (DigIn 1 and DigIn 2) on the head unit. via command on CAN. Since the use for each input is unknown the conditions must be configurable via EOL parameters. See Ref. 6 FRS 2289909 Utility Management for details regarding camera commanded via CAN.
FRS523_14	4	If no camera is detected and an attempt to activate a camera is initiated according to any of the cases in FRS523_12 the system shall ignore this command, and a notification shall be presented to the user that no camera is connected.
FRS523_16	3	When the camera view is deactivated, the system shall transit to the latest used view other than the camera view, or the view for the active source, in case the source where changed during the camera was active. If the system was turned on by activation of a camera, the system shall shift to the last state, e g On, with last used source, or Standby Standby Power save Off See Ref. 1 SRS for power-states.
FRS523_18	3	The camera image shall not be frozen or delayed. The camera functionality is safety critical and the implementation of the camera function and the whole system needs to be designed to avoid frozen or delayed camera images. Due to this the supplier shall provide to Scania relevant parts of the

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2282463

Requirements Specification

FRS AUS4 Camera

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,				
		system design and test protocols to proof that the camera functionality is not causing any freezes or delays.		
FRS523_23	2	The infotainment system shall be equipped with a 12V Camera ON output signal (pins for 12V out 1 and 12V out 2) when the camera view is active (Pins that become 12V). There shall be one for each camera input.		
FRS523_25	3	The infotainment system shall show input from a connected camera with maximum 100 ms delay. I e what appears outside the vehicle shall be visible not later than after 100 ms in the display. The requirement affects both the Camera delay and the Camera at Cold Start up.		
FRS523_53	2	The start-up time on the system, from State = Off until a camera-image is showing on the display shall be no more than 3s. See Ref. 1 SRS for ECU states.		
FRS523_54	1	When the infotainment-system is running and a camera-view is commanded on CAN, or automatically activated due to a CAN-signal there shall be no more than 500 ms latency in the Infotainment system until the image is showing on the display. Please note that this requirement assumes a camera image is already available, any camera-delay is not covered. See Ref. 6 FRS 2289909 Utility Management for details regarding camera commanded via CAN.		
FRS523_26	1	The Camera interface shall support most camera systems on the aftermarket. See Ref.1 SRS for more information.		
FRS523_99	3 X	The purpose for each video input is decided by parameters. Camera 1 functionality shall be defined by parameter Camera1. Camera 2 functionality shall be defined by parameter Camera2. If parameter Camera1[2] = Off The camera shall be deactivated. GeneralCamera The camera shall work as general camera. ReverseCamera The camera shall work as reverse camera. FrontCamera The camera shall work as front camera.		
FRS523_39	3	Audio playback and information sent on CAN, regarding other functions in the infotainment system, shall not be affected by the camera function. E g Radio information and navigation information shall still be available, accessible in the instrument cluster and possible to control by steering wheel buttons.		
FRS523_60	1	The camera image shall not flicker when the infotainment system is changing between states.		
FRS523_62	3	It shall be possible to activate the camera view and show a camera image on the		



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2282463

Requirements Specification

FRS AUS4 Camera

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		infotainment systems display by activating the activation-pins (DigIn 1 and DigIn 2) for each camera. I e:
		If: - Camera1Activate is Active
		The System shall show the picture from camera 1. For NotActive no picture shown from Camera 1.
		If: - Camera2Activate is Active
		The System shall show the picture from camera 2. For NotActive no picture shown from Camera 2.
FRS523_111	1	The activation of cameras via the activation-pins Camera1Activate and Camera2Activate shall override the speed-limitations on displaying camera described in FRS523_106.
FRS523_63	2	If the infotainment system is configured with one camera input (via parameters Camera1 and Camera2) the hard key shall be configured to toggle between 1. camera input 2. no camera Front cameras must not be manually deactivated.
FRS523_64	2	If the infotainment system is configured with two camera inputs (via parameters Camera1 and Camera2) the hard key shall be configured to toggle between: 1. camera input 1 2. camera input 2 3. Not applicable Front cameras must not be manually deactivated. See also prioritization of cameras FRS523_104. See also requirement FRS523_16 for deactivation.
FRS523_66	2	The camera wake-up signal (output pin 12V out 1 and 12V out 2) (see FRS523_23) shall become active without any delay when a camera view activation event is received.
FRS523_67	1	The camera wake-up signal (see FRS523_23) shall be active high before the camera view is activated.
FRS523_68	2	Each camera input shall be able to detect if a valid camera image is sent on the camera input. The camera input shall provide a stable image before the camera view is activated. If no stable image is available but conditions to activate the camera view is fulfilled the function shall continue to search for a stable image from the camera and activate the camera view as soon as an image is available.
FRS523_69	3	For each input configured in parameters Camera1 and Camera2 the infotainment system shall search for a valid signal for each camera at startup of the system. If a camera is not physically connected then a blue screen shall be visible with the



2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page
Daniel Velcic ssswmn sssnrg I S 8 14 (23)

		message "No camera	a connected".		
FRS523_100	1	If a time is specified in parameter Camera1StartupTime a predefined image shall be displayed while activating camera 1. The image shall be displayed as soon as the decision to start the camera is made and during the specified time. This is to allow the camera hardware a start-up latency and provide the user with information while the camera is starting. The same applies for camera 2 in parameter Camera2StartupTime .			
FRS523_101	1		In general a configured front camera shall have higher priority than reverse camera and general camera. Requirement FRS523_104 clarifies this.		
FRS523_102	1		ed reverse camera shat t FRS523_104 clarifie	all have higher priority than a general s this.	
FRS523_103	1		nera inputs are equally Requirement FRS523	configured input 1 shall have higher104 clarifies this.	
FRS523_112	1	If several conditions are fulfilled that activates a camera, the camera shall remain activated until all conditions that deactivates the camera are fulfilled. E g an automatic activation due to speed in parallel with a separate CAN-request shall keep the camera active until a CAN-request for deactivation is received.			
FRS523_135	1	parameters Camera (from Setup menu or shown with the name 1 is Camera 1 and Camera 1.	I and Camera2) the C Camera Screen). In the of the Screen attache amera 2 for Camera in	h at least one camera input (via amera settings view shall be available ne Camera settings a preview screen is ed to it. The default name for Camera input aput 2. This can be renamed to an arbitrary in the top bar of the Camera Screen.	
FRS523_136	1		ange to inactive (disag	or and bottom bar will be active for 6 ppear). The name of the Camera will be	
FRS523_104	1	If conditions for both camera inputs are fulfilled simultaneously the prioritization shall follow the table below. Configuration according to parameters Camera1 and Camera2 . Conditions in this case can be hard pin, CAN-requests and other CAN-signals (speed-signals, brake-signals, gear).			
		Camera1	Camera2	Prioritized input	
		Off	Off	n/a	
		Off	GeneralCam	2	
		Off	Reverse	2	
		Off	Front	2	
	,	GeneralCam	Off	1	
		GeneralCam	GeneralCam	Initially 1 but possible to toggle with HMI	
		GeneralCam	Reverse	Initially 2 but possible to toggle with HMI	
		GeneralCam	Front	2	
		Reverse	Off	1	
		Reverse	GeneralCam	Initially 1 but possible to toggle with HMI	
		Reverse	Reverse	Initially 1 but possible to toggle with HMI	
		Reverse	Front	2	



2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page
Daniel Velcic ssswmn sssnrg I S 8 15 (23)

		Front	Off	1
		Front	GeneralCam	1
		Front	Reverse	1
		Front	Front	1
FRS523_133	2	Expected HMI Implementation shall be as described below: Overridable is equivalent with a possibility to escape the Screen with either CAN signal, Hard Pin and Camera Hard key. Non-Overridable means no possibility to escape the Screen with either CAN signal, Hard Pin or Camera Hard key. See Ref. 15 in DeviationList_NotIncludedPoints.		

	Expected HMI Implementation							
Came	га Туре	HMI Behavior Based on Camera Activation Source						
Camera Type 1	nera Type 1 Camera Type 2	CAN	Signal	Hard Pin (Digin1/Digin2)		Camera HK (Face Plate)		
		Camera 1	Camera 2	Camera 1	Camera 2	Camera 1	Camera 2	
Off	Off	N/A	N/A	N/A	N/A	N/A	N/A	
Off	GeneralCam	N/A	Non-Overridable	N/A	Non-Overridable	N/A	Overridable	
Off	Reverse	N/A	Overridable	N/A	Non-Overridable	N/A	Overridable	
Off	Front	N/A	Non-Overridable	N/A	Non-Overridable	N/A	Overridable	
GeneralCam	Off	Non-Overridable	N/A	Non-Overridable	N/A	Overridable	N/A	
GeneralCam	GeneralCam	Non-Overridable	Non-Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
GeneralCam	Reverse	Non-Overridable	Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
GeneralCam	Front	Non-Overridable	Non-Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
Reverse	Off	Overridable	N/A	Non-Overridable	N/A	Overridable	N/A	
Reverse	GeneralCam	Overridable	Non-Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
Reverse	Reverse	Overridable	Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
Reverse	Front	Overridable	Non-Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
Front	Off	Non-Overridable	N/A	Non-Overridable	N/A	Overridable	N/A	
Front	GeneralCam	Non-Overridable	Non-Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
Front	Reverse	Non-Overridable	Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	
Front	Front	Non-Overridable	Non-Overridable	Non-Overridable	Non-Overridable	Overridable	Overridable	





2282463

Requirements Specification

FRS AUS4 Camera

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3.2 CAN Communication requirements (Media)

Req-ID	ver	Requirement
FRS523_115	2	MediaStreamSourceAvailable.VideoLineIn1Available shall be set as follows:
		SourceNotAvailable. If no camera is available on input 1.
		 General camera. If input 1 is configured as a general camera.
		 RearViewCameraAvailable. If input 1 is configured as rear view
		camera.
		 FrontViewCameraAvailable. If input 1 is configured as front view
		camera.
		Not available. If none of the above above applies.
FRS523_116	2	MediaStreamSourceAvailable.VideoLineIn2Available shall be set as follows:
		SourceNotAvailable. If no camera is available on input 2.
		General camera. If input 2 is configured as a general camera.
		RearViewCameraAvailable. If input 2 is configured as rear view
		camera.
		FrontViewCameraAvailable. If input 2 is configured as front view
		camera.
		Not available. If none of the above above applies.
FRS523_121	2	MediaStreamSourceConnected.VideoLineIn1Connected shall be set as follows:
		Not connected. If no camera is connected on input 1.
		Connected. If a camera is connected on input 1.
		Error. If an error is detected on the connection for camera 1.
		Not available. If none of the above applies.
FRS523_122	2	MediaStreamSourceConnected.VideoLineIn2Connected shall be set as follows:
_		 Not connected. If no camera is connected on input 2.
		Connected. If a camera is connected on input 2.
		Error. If an error is detected on the connection for camera 2.
		Not available. If none of the above applies.
FRS523_131	1	MediaStreamSourceConnected.VideoLineIn3Connected
		MediaStreamSourceConnected.VideoLineIn4Connected
		MediaStreamSourceAvailable.VideoLineIn3Available
		MediaStreamSourceAvailable.VideoLineIn4Available
	1	Shall all be set to NotAvailable .



2282463

Requirements Specification

FRS AUS4 Camera

Checked 1 Checked 2 Information Classification Status Revision Page ssswmn sssnrg I S 8 17 (23)

Issued by Daniel Velcic

3.2.1 CAN Communication requirements (General Camera)

FRS523_125	2	If parameter Camera1 = GeneralCamera
		and
		If parameter GeneralCameraActivationWorklightCamera1 = on
		the camera 1 view shall be activated when signal
		CUVInformation.WorklightToggleSwitch = On.
		The camera shall be active as long as the condition above is true or until manually
		deselected.
FRS523_126	1	If parameter Camera2 = GeneralCamera
		and
		If parameter GeneralCameraActivationWorklightCamera2 = on
		the camera 2 view shall be activated when signal
		CUVInformation.WorklightToggleSwitch = On.
		The camera shall be active as long as the condition above is true or until manually
		deselected.





2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page
Daniel Velcic ssswmn sssnrg I S 8 18 (23)

FRS523_127	4	Driver position side is decided by parameter SteeringWheelPosition . If SteeringWheelPosition = LHD driver position is to the left. If SteeringWheelPosition = RHD driver position is to the right.
		For a vehicle with the driver position on the left side: If parameter Camera1 = GeneralCamera and
		If parameter GeneralCameraActivationDirectionIndicatorsCamera1 is set to on the camera 1 view shall be activated when CUVInformation.DirectionIndicatorLeftIntended = Off
		and CUVInformation.DirectionIndicatorRightIntended = On
		The camera shall be active as long as this signal combination is received. The same applies for camera 2 but with parameters GeneralCameraActivationDirectionIndicatorsCamera2 and
		Camera2.
FRS523_128	4	For a vehicle with the driver position on the right side: If parameter Camera1 = GeneralCamera and
		If parameter GeneralCameraActivationDirectionIndicatorsCamera1 is set to on the camera 1 view shall be activated when
		CUVInformation.DirectionIndicatorRightIntended = Off
		and CUVInformation.DirectionIndicatorLeftIntended = On
		The camera shall be active as long as this signal combination is received. The same applies for camera 2 but with parameters
		GeneralCameraActivationDirectionIndicatorsCamera2 and Camera2.
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2282463

Requirements Specification

FRS AUS4 Camera

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FRS523_106

If a camera is configured as GeneralCamera, according to parameter **Camera1** or **Camera2**, the camera view shall be automatically deactivated after a certain speed forward.

lf

ETC5. ReverseSwitch = Off

and

 CruiseControlVehSpeed.WheelBasedVehicleSpeed
 (Camera[1, 2]ReverseGeneralForwardDeactivationSpeed + Camera[1, 2]ReverseGeneralForwardHysteresis)

The camera view shall be deactivated.

It shall not be possible to manually activate the camera view again while CruiseControlVehSpeed.WheelBasedVehicleSpeed > (Camera[1, 2]ReverseGeneralForwardDeactivationSpeed.

See also requirement FRS523 16 for deactivation.





2282463

Requirements Specification

FRS AUS4 Camera

Issued by Checked 1 Checked 2 Information Classification Status Revision Page
Daniel Velcic ssswmn sssnrg I S 8 20 (23)

3.3 Front camera

3.3.1 Background

Legislation requires the driver to have clear sight around the front corner of the passenger side of the truck. Usually this requirement is met by mounting a mirror above the windscreen on the passenger side but other solutions are allowed. An alternative solution is to use a camera, mounted above the windscreen, instead of the mirror and use a display in the instrument panel to show the camera image. This solution is regulated in directive 2003/97/EG. According to the directive the display used to show the front camera image must be dedicated to show the front camera image when the vehicle is moving with a speed below 30 km/h. Over this speed the front camera image may be turned off and the display may be used to show other information, for example navigation or radio information.

3.3.2 General Requirements (Front Camera)

Req-ID	ver	Requirement
FRS523_41	1	The system shall comply with directive 2003/97/EG.
FRS523_57	2	The system shall comply with relevant parts of ISO standard ISO/DIS 16505. The relevant parts is display reflections, display visability and start-up time. Relevant use-cases could e g be Direct light in the display Cold Start Visibility in the display
FRS523_55	1	The system shall comply with new directives that affect camera-systems for commercial vehicles. The supplier shall discuss with Scania about possible new requirements that need to be considered.
FRS523_42	1	The front camera view shall work without any other camera systems connected to the system. Any of the two composite video inputs shall be possible to configure as a front camera via EOL. The second camera need not be connected.
FRS523_56	2	When conditions are fulfilled and when the front camera view is active it shall not be possible to replace the camera view in the display, not by the HMI or via CAN. The System should not enter standby when pressing the left rotary knob.

3.3.3 CAN communication requirements (Front Camera)

Req-ID	ver	Requirement
FRS523_83	2	The front camera activation speed is defined by parameter FrontCameraUpperSpeedLimit
		If front camera view is deactivated and
		ETC5.ReverseSwitch = Off and
		CruiseControlVehSpeed.ParkingBrakeSwitch = ParkingBrakeNotSet and
		CruiseControlVehSpeed.WheelBasedVehicleSpeed =< FrontCameraUpperSpeedLimit
		any camera configured as front camera shall be activated.



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TECHNICAL PRODUCT DATA

2282463

Requirements Specification

FRS AUS4 Camera

Checked 1 Checked 2 Information Classification Status Revision Page ssswmn sssnrg I S 8 21 (23)

FRS523_82	2	If the vehicle speed is above a certain speed the infotainment system shall switch to the view displayed before the front camera view was activated.
		The deactivation speed is decided by parameter:
		FrontCameraUpperSpeedLimit and a hysteresis parameter FrontCameraUpperSpeedHysteresis.
		If front camera view is activated and CruiseControlVehSpeed.WheelBasedVehicleSpeed >
		FrontCameraUpperSpeedLimit + FrontCameraUpperSpeedHysteresis
		any camera configured as front camera shall be deactivated.





2282463

Requirements Specification

FRS AUS4 Camera

Checked 1 Checked 2 Information Classification Status Revision Page ssswmn sssnrg I S 8 22 (23)

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3.4 Reverse camera

3.4.1 Background

With a camera input configured as a reverse camera (at EOL coding and aftermarket) it is possible to see help lines on the display when reversing. The help lines are used to aid the driver to the correct place when parking and to draw the help lines correctly on the display they need to be adapted to the vehicles specification, on trucks this is especially important since each truck is configured and built for a special purpose. For the camera system the help lines are stored as static images in the infotainment system.

3.4.2 General requirements (Reverse Camera)

Req-ID	ver	Requirement
FRS523_50	1	If the reverse camera is connected as camera 1 the reverse guidelines shall be selected by parameter ReverseGuidelinesCamera1 . If the reverse camera is connected as camera 2 the reverse guidelines shall be selected by parameter ReverseGuidelinesCamera2 . One option in the parameters selection is to have the reverse guidelines completely off.
FRS523_52	3	If the help lines function is enabled by parameterization, this will be shown when Reverse Camera view is activated. If parameter ReverseGuidlinesCamera1 or ReverseGuidlinesCamera2 is Off (0) then the option shall not be selectable in the HMI. See Ref. 16 in DeviationList_NotIncludedPoints.
FRS523_129	1	Camera view manually activated
_		If the reverse camera is manually activated it shall only be deactivated manually or according to requirement FRS523_91.
FRS523_88	1	Reverse help lines
_		If the camera input in configured as a reverse camera the infotainment system shall be able to show reverse help guidelines in the display on top of the camera image.
FRS523_134	1	Notification when Reversing
_	M	If the vehicle is reversing and configured with a rear camera the driver should be notified on the camera screen to pay attention of the surroundings.



2282463

Requirements Specification

FRS AUS4 Camera

Checked 1 Checked 2 Information Classification Status Revision Page ssswmn sssnrg I S 8 23 (23)

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3.4.3 CAN communication requirements (Reverse Camera)

Req-ID	ver	Requirement
FRS523_90	3	The camera view shall be automatically activated when an indication that the truck will start reversing is sent to the infotainment system via CAN. If reversed camera view is deactivated and - ETC5.ReverseSwitch = On reversed camera shall be activated.
FRS523_130	2	If reverse camera view has been automatically activated and - ETC5.ReverseSwitch = Off the reverse camera shall remain activated according to the time specified in parameter ReverseCameraActiveTimer or until deactivated according to requirement FRS523_91. Note that if ReverseCameraActiveTimer = 0 means the reverse camera will remain activated for 0 seconds. Note that this will not apply if the reverse Camera has been manually activated via HK or activated via Hard pin.
RS523_91	3	The reverse camera view shall be automatically deactivated after a certain speed forward. If ETC5.ReverseSwitch = Off and CruiseControlVehSpeed.WheelBasedVehicleSpeed > Camera[1, 2]ReverseGeneralForwardDeactivationSpeed + Camera[1, 2]ReverseGeneralForwardHysteresis deactivate camera view. This is valid when the reverse camera has been automatically or manually activated. See also requirement FRS523_16 for deactivation.