



# UNIVERSITÀ DI TRENTO

## Formal Method Mod. 2 (Model Checking)

### Laboratory 11

Giuseppe Spallitta

[giuseppe.spallitta@unitn.it](mailto:giuseppe.spallitta@unitn.it)

Università degli studi di Trento

May 25, 2022

# Timed systems

## Real time systems

- ▶ Correctness depends not only on the logical result but also on the time required to compute it.
- ▶ Common in safety-critical domains like: defense, transportation, health-care, space and avionics.

## Timed Transition System (TTS)

transitions are either discrete

or time-elapses,

all clocks increase of the same amount in time-elapses.

Model checking for TTS is **undecidable**.

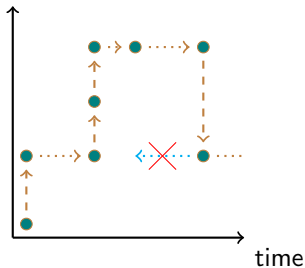
## Timed Automata (TA)

decidable restriction of TTS,

finite time abstraction:

clocks compared only to constants.

discrete

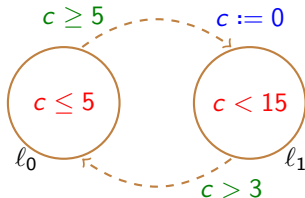


# Timed systems: representation

## Timed Automata (TA)

Explicit graph representation of discrete states (nodes) and transitions (edges).

Symbolic representation of temporal aspects via (convex) constraints (**location invariants**, **transition guards** and **resets**).



## Symbolic TTS

Logical formulae represent sets of states:  $p := \{s \mid s \models p\}$ .

Transition system symbolically represented by formula  $\varphi(X, X')$ .

There is a discrete transition from  $s_0$  to  $s_1$  iff  $s_0(X), s_1(X') \models \varphi(X, X')$ .

$$I = l_0 \rightarrow c \leq 5 \quad \wedge$$

$$I = l_1 \rightarrow c < 15 \quad \wedge$$

$$(I = l_1 \wedge I' = l_0) \rightarrow c > 3 \quad \wedge$$

$$(I = l_0 \wedge I' = l_1) \rightarrow (c \geq 5 \wedge c' = 0)$$

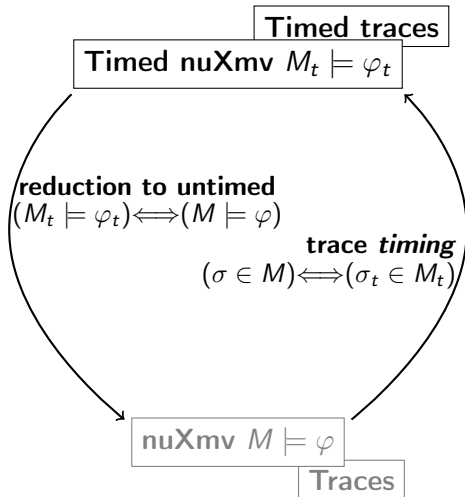
# Outline

---

1. Timed nuXmv
2. Timed and infinite traces
3. Exercises



# nuXmv for timed system: architecture



## 1. Timed nuXmv

# Timed nuXmv: input language [1/4]

---

## Overview

- ▶ Must start with `@TIME_DOMAIN continuous;`
- ▶ Symbolic description of infinite transition system using: `INIT`, `INVAR` and `TRANS` to specify initial, invariant and transition conditions.
- ▶ Model described as a synchronous composition of `MODULE` instances.
- ▶ Clock variables,
  - ▶ `time`: built-in clock variable,
  - ▶ convex invariants over clocks,
  - ▶ `URGENT`: forbid time elapse.

# Timed nuXmv: input language [2/4]

## Timed nuXmv adds

- ▶ `clock` variable type, all `clocks` increase of the same amount during timed transitions;
- ▶ `time`: built-in `clock`, can be used only in comparisons with constants;
- ▶ `noncontinuous` type modifier: symbol can change its assignment during timed transitions;
- ▶ `URGENT`: freeze time: when one of the `URGENT` conditions is satisfied only discrete transitions are allowed;
- ▶ `MTL0,∞` specifications, by “extending” LTL;

# Timed nuXmv: input language [3/4]

---

## Timed nuXmv updates

- ▶ TRANS constrain the discrete behaviour only,
- ▶ INVAR: clocks allowed in invariants with shape:  
`no_clock_expr -> convex_clock_expr;`
- ▶ LTL operators:  $X$ ,  $Y$ ,  $U$ ,  $S$ ,
- ▶ Bounded LTL operators.





# Timed nuXmv: input language [4/4]

## Specification

- ▶ Different operators to refer to the *discrete* next and *timed* next:  $X$ ,  $X_{\sim}$ ; symmetrically for the past:  $Y$ ,  $Y_{\sim}$ .
- ▶ Time interval semantic to handle open intervals: a predicate  $p$  might hold in an interval  $(a, b]$  for  $a, b \in \mathbb{R}$ .
- ▶ Operators to retrieve value of expression the next/last time an expression will hold/held:  $\text{time\_until}$ ,  $\text{time\_since}$ ,  $@F_{\sim}$  and  $@O_{\sim}$ .

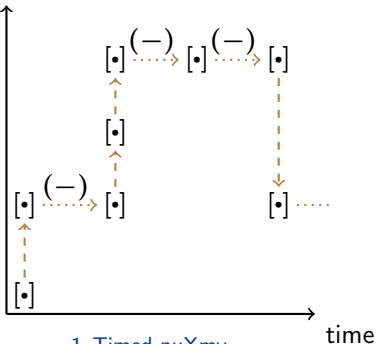


# Timed nuXmv: untiming

## Timed to untimed model

- ▶ clock symbols and time: variables of type real.
- ▶  $\delta$ : continuous positive variable, prescribes the amount of time elapse for every transition.
- ▶  $\iota$ : prescribes the alternation of singular  $[\cdot]$  and open  $(-)$  time intervals.

discrete



1. Timed nuXmv

# Timed nuXmv: untiming

## Properties rewriting

**MTL** *fragment*

$$F_{[0,5]} p$$

↓ rewrite

**LTL** *timed*

$$((\neg p U p) \wedge \text{time\_until}(p) \leq 5) \vee$$

$$((\neg p U \tilde{X} p) \wedge \text{time\_until}(p) < 5)$$

↓ untime

**LTL** *untimed*

$$((\neg p U p) \wedge (\text{time@}\tilde{F}p - \text{time} \leq 5) \vee$$

$$((\neg p U ((\neg \iota \wedge p) \vee X(\neg \iota \wedge p))) \wedge (\text{time@}\tilde{F}p - \text{time} < 5))$$

# Outline

---

1. Timed nuXmv
2. Timed and infinite traces
3. Exercises



# Timed and infinite traces

From untimed model execution to timed trace.

## Issue

nuXmv traces must have shape:  $\alpha\beta^\omega$ ,  
 $\alpha$  and  $\beta$  sequences of states.

Complete for finite state systems.

**TTS**: time monotonically increasing,  
infinite state system, **undecidable**.

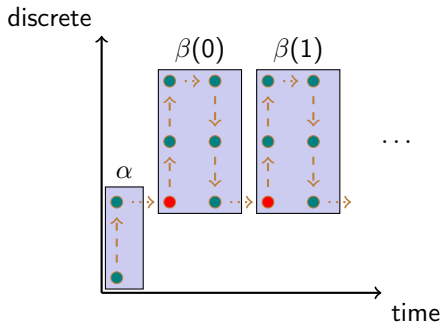
Identify traces expressible as:  $\alpha\beta(i)^\omega$ .

Same problem can be found in  
infinite state transition systems.

## Solution

Value assigned to variables at state  
 $s$  is function of the previous  
configuration assignments.

e.g.  $next(time) := time + \delta$



# Timed and infinite traces: operations

---

Three main operations on traces: **simulation**, **execution** and **completion**.

## Simulation

Build a possible execution of the model. The trace can be built automatically by the system or the user can choose each state from the list of possible ones.

Exploit SMT-solver to perform a discrete transition or time-elapse to obtain next configuration.



# Timed and infinite traces: operations

we don't do this

## Execution

Check if a trace belongs to the language of the model.

Exploit SMT-solver to prove that **for all** possible iterations all prescribed transition can be performed.

## Completion

A partial trace is completed so that it belongs to the model language.

Sound and complete technique requires to check if there **exists** a possible completion so that the completed trace belongs to the model language: quantifier alternation ( $\exists\forall$ ).

Adopt sound but incomplete approach.



# How to run: model [1/3]

---

- ▶ `./nuXmv -time -int`: start nuXmv interactively and enable commands for timed models.
- ▶ `go_time`: process the model.
- ▶ `write_untimed_model`: dump SMV model corresponding to the input timed system.





## How to run: verify [2/3]

---

- ▶ `timed_check_invar`: check invariants.
- ▶ `timed_check_ltlspec`: check LTL.

Mostly the same command line options of the corresponding commands for untimed models.



# How to run: simulation and traces [3/3]

---

- ▶ `timed_pick_state`: pick initial state.
- ▶ `timed_simulate`: simulate the model starting from a given state.
- ▶ `execute_traces`: re-execute stored traces.
- ▶ `execute_partial_traces`: try to complete stored traces.



# Semantics of temporal operators

---

Formally nuXmv uses a super-dense weakly-monotonic time model  $T \subset \mathbb{N} \times \mathbb{R}_0^+$ .

A time point is a pair  $\langle i, r \rangle$  where  $i \in \mathbb{N}$  “counts the discrete steps” and  $r \in \mathbb{R}_0^+$  is the time.

We say that  $\langle i, r \rangle < \langle i', r' \rangle$  iff  $i < i'$  or  $i = i'$  and  $r < r'$ .

# Semantics of temporal operators

$\sigma, t \models \phi$  is defined recursively on the structure of  $\phi$ :  
usual definition for predicates, conjunction and negation.

$\sigma, t \models \phi_1 U \phi_2$  iff there exists  $t' \geq t, \sigma, t' \models \phi_2$  and  
for all  $t'', t \leq t'' < t', \sigma, t'' \models \phi_1$

$\sigma, t \models \phi_1 S \phi_2$  iff there exists  $t' \leq t, \sigma, t' \models \phi_2$  and  
for all  $t'', t' < t'' \leq t, \sigma, t'' \models \phi_1$

$\sigma, t \models X\phi$  iff there exists  $t' > t, \sigma, t' \models \phi$  and  
there exists no  $t'', t < t'' < t'$

$\sigma, t \models \tilde{X}\phi$  iff for all  $t' > t$ , there exists  $t'', t < t'' < t', \sigma, t'' \models \phi$

$\sigma, t \models Y\phi$  iff  $t > 0$  and there exists  $t' < t, \sigma, t' \models \phi$  and  
there exists no  $t'', t' < t'' < t$

$\sigma, t \models \tilde{Y}\phi$  iff  $t > 0$  and for all  $t' < t$ ,  
there exists  $t'', t' < t'' < t, \sigma, t'' \models \phi$

# LTL- MTL properties [1/2]

---

Let  $k$ ,  $k_1$  and  $k_2$  be some constant real values such that  $0 \leq k \leq k_1 < k_2$  and let  $b$  a boolean symbol.  
The following properties true or false?

►  $\tilde{Y}_T$



# LTL- MTL properties [1/2]

---

Let  $k$ ,  $k_1$  and  $k_2$  be some constant real values such that  $0 \leq k \leq k_1 < k_2$  and let  $b$  a boolean symbol.

The following properties true or false?

- ▶  $\tilde{Y}_{\top}$  : false in the initial state.
- ▶  $(\neg Xb) \rightarrow (X\neg b)$



# LTL- MTL properties [1/2]

Let  $k$ ,  $k_1$  and  $k_2$  be some constant real values such that  $0 \leq k \leq k_1 < k_2$  and let  $b$  a boolean symbol.

The following properties true or false?

- ▶  $\tilde{Y} \top$  : false in the initial state.
- ▶  $(\neg X b) \rightarrow (X \neg b)$  : false, the first one holds in every time elapse, the second one holds only in discrete steps where  $\neg b$  holds in the next state.
- ▶  $(\neg \tilde{X} b) \rightarrow (\tilde{X} \neg b)$

# LTL- MTL properties [1/2]

Let  $k$ ,  $k_1$  and  $k_2$  be some constant real values such that  $0 \leq k \leq k_1 < k_2$  and let  $b$  a boolean symbol.

The following properties true or false?

- ▶  $\tilde{Y} \top$  : false in the initial state.
- ▶  $(\neg Xb) \rightarrow (X\neg b)$  : false, the first one holds in every time elapse, the second one holds only in discrete steps where  $\neg b$  holds in the next state.
- ▶  $(\neg \tilde{X} b) \rightarrow (\tilde{X} \neg b)$  : false, as above but for time elapses.
- ▶  $(X\neg b) \rightarrow (\neg Xb)$



# LTL- MTL properties [1/2]

Let  $k$ ,  $k_1$  and  $k_2$  be some constant real values such that  $0 \leq k \leq k_1 < k_2$  and let  $b$  a boolean symbol.

The following properties true or false?

- ▶  $\tilde{Y} \top$  : false in the initial state.
- ▶  $(\neg Xb) \rightarrow (X\neg b)$  : false, the first one holds in every time elapse, the second one holds only in discrete steps where  $\neg b$  holds in the next state.
- ▶  $(\neg \tilde{X} b) \rightarrow (\tilde{X} \neg b)$  : false, as above but for time elapses.
- ▶  $(X\neg b) \rightarrow (\neg Xb)$  : true, the first one holds iff there is a discrete step and  $\neg b$  holds in the next state, hence  $Xb$  is false.
- ▶  $(\tilde{X} \neg b) \rightarrow (\neg \tilde{X} b)$

# LTL- MTL properties [1/2]

Let  $k$ ,  $k_1$  and  $k_2$  be some constant real values such that  $0 \leq k \leq k_1 < k_2$  and let  $b$  a boolean symbol.

The following properties true or false?

- ▶  $\tilde{Y}\top$  : false in the initial state.
- ▶  $(\neg Xb) \rightarrow (X\neg b)$  : false, the first one holds in every time elapse, the second one holds only in discrete steps where  $\neg b$  holds in the next state.
- ▶  $(\neg \tilde{X} b) \rightarrow (\tilde{X}\neg b)$  : false, as above but for time elapses.
- ▶  $(X\neg b) \rightarrow (\neg Xb)$  : true, the first one holds iff there is a discrete step and  $\neg b$  holds in the next state, hence  $Xb$  is false.
- ▶  $(\tilde{X}\neg b) \rightarrow (\neg \tilde{X}b)$  : true, as above but for time elapses.
- ▶  $(G\tilde{X}\top) \rightarrow ((Gb) \vee (G\neg b))$

# LTL- MTL properties [1/2]

Let  $k$ ,  $k_1$  and  $k_2$  be some constant real values such that  $0 \leq k \leq k_1 < k_2$  and let  $b$  a boolean symbol.

The following properties true or false?

- ▶  $\tilde{Y}\top$  : false in the initial state.
- ▶  $(\neg Xb) \rightarrow (X\neg b)$  : false, the first one holds in every time elapse, the second one holds only in discrete steps where  $\neg b$  holds in the next state.
- ▶  $(\neg \tilde{X} b) \rightarrow (\tilde{X}\neg b)$  : false, as above but for time elapses.
- ▶  $(X\neg b) \rightarrow (\neg Xb)$  : true, the first one holds iff there is a discrete step and  $\neg b$  holds in the next state, hence  $Xb$  is false.
- ▶  $(\tilde{X}\neg b) \rightarrow (\neg \tilde{X}b)$  : true, as above but for time elapses.
- ▶  $(G\tilde{X}\top) \rightarrow ((Gb) \vee (G\neg b))$  : true, the first part implies that we never perform a discrete transition and the truth value of  $b$  can only change in discrete transitions.



# LTL- MTL properties [2/2]

---

See files in examples.



# Outline

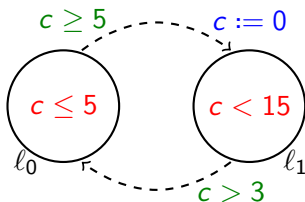
---

1. Timed nuXmv
2. Timed and infinite traces
3. Exercises



# Simple timed automaton

Write the SMV model corresponding to the timed automaton in the figure.



## Properties

- ▶ from location  $\ell_0$  we always reach  $\ell_1$  within 5 time units;
- ▶ if we are in  $\ell_1$  then for the next 3 time units we remain in  $\ell_1$ ;
- ▶ if just arrived in  $\ell_1$  then for the next 3 time units we remain in  $\ell_1$ .

# Timed thermostat

---

- ▶ a thermostat has 2 states: *on* and *off*;
  - ▶ if the temperature is below 18 degrees the thermostat switches *on*.
  - ▶ if the temperature is above 18 degrees the thermostat switches *off*.
- ▶ Every time the thermostat misure the temperature in the room, the temperature increases (if *on*) or decreases (if *off*) by  $dt$  (with respect to the previous check);
- ▶ the thermostat measures the temperature at most ( $\leq$ ) every  $max\_dt$  time units.
- ▶ the temperature initially is in  $[18 - max\_dt; 18 + max\_dt]$ .

Verify that the temperature is always in  $[18 - 2max\_dt; 18 + 2max\_dt]$

# Homework

---

Try to encode the timed automata shown in the theoretical slide about timed automata.

