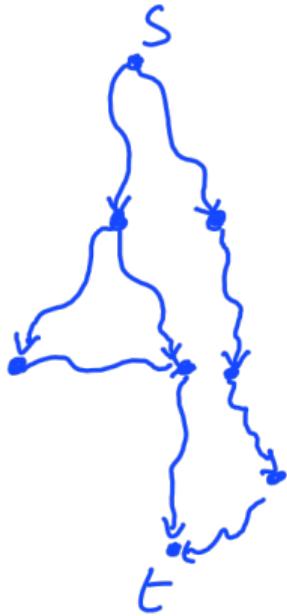
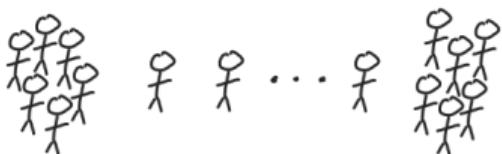


Parameterized Flows

Joint work with Hugo Gimbert
and Patrick Potzke



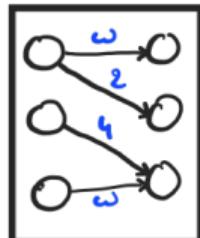
PaveDays
 Mai 2025

Model

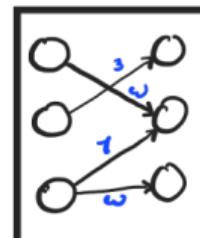
Finite set of states S

q_1 ○
 q_2 ○
 q_3 ○

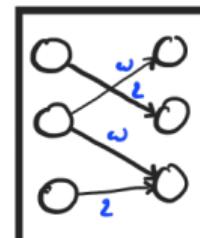
Finite set of tiles τ



a



b



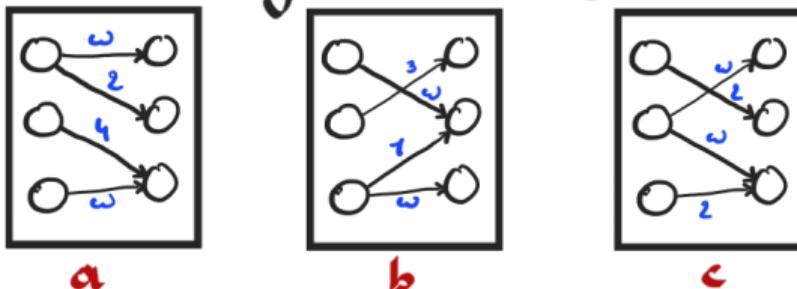
c

Model

Finite set of states S

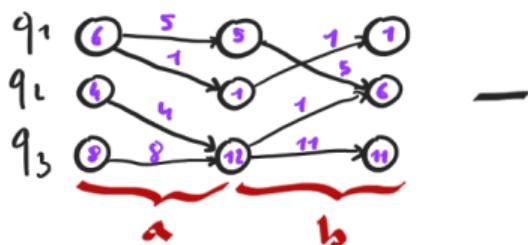
q_1 ○
 q_2 ○
 q_3 ○

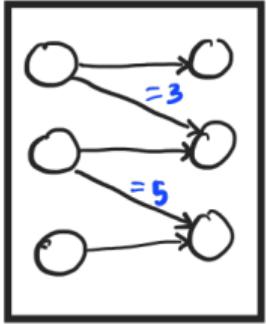
Finite set of tiles τ



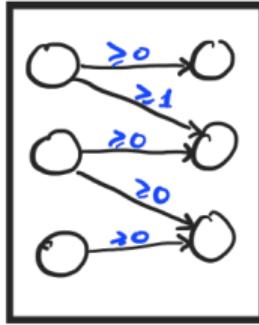
Configurations = N^S

Step = transfer of tokens $\leq x \in \tau$

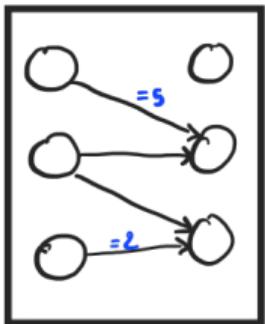




\approx VASS

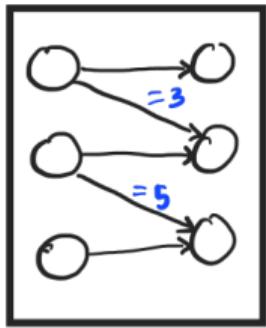


\approx Lossy
Broadcast.

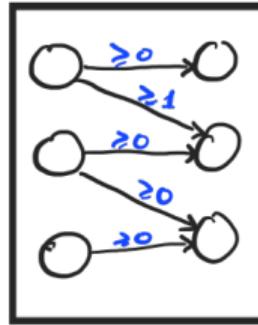


\approx VASS
with 0-test

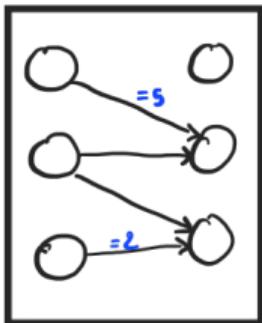
\approx Reliable Broadcast



\approx VASS

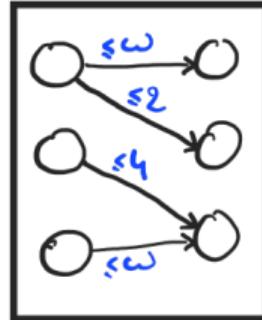


\approx Lossy
Broadcast.



\approx VASS
with 0-test

\approx Reliable Broadcast



\approx Locks ?

Sequential Flow Problem [Colcombet, Fijalkow, Ohlmann '20]

Input: Finite set of tiles $\tau \subseteq (\mathcal{N} \cup \{\omega\})^{S \times S}$

Source state $s_{rc} \in S$

Target state $t_{gt} \in S$

Question: $\forall N \in \mathbb{N}$,
there is a path from $(N \cdot s_{rc})$ to $(N \cdot t_{gt})$?

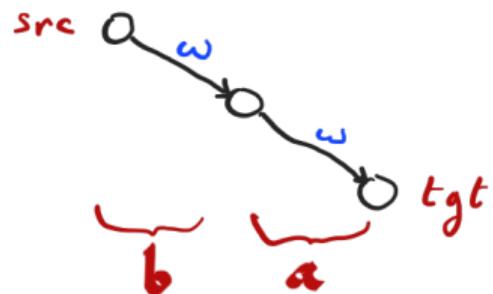
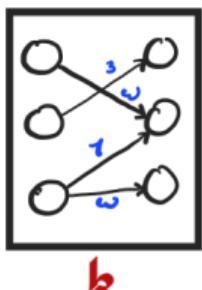
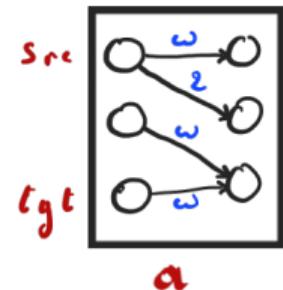
Sequential Flow Problem [Colcombet, Fijalkow, Ohlmann '20]

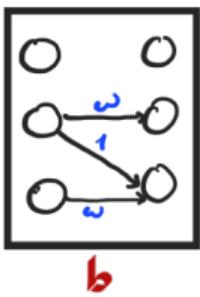
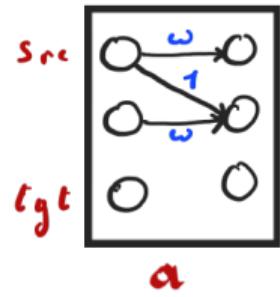
Input: Finite set of tiles $\tau \subseteq (\mathcal{N} \cup \{\omega\})^{S \times S}$

Source state $src \in S$

Target state $tgt \in S$

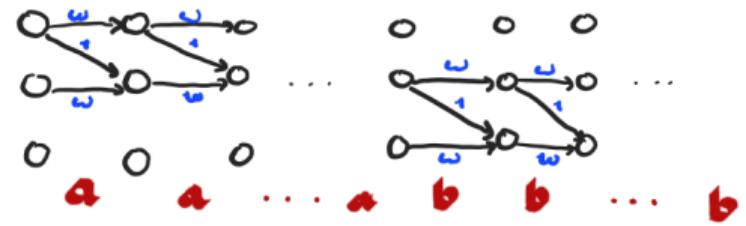
Question: $\forall N \in \mathbb{N}$,
there is a path from $(N \cdot src)$ to $(N \cdot tgt)$?

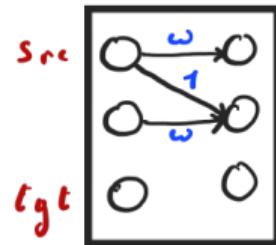




a

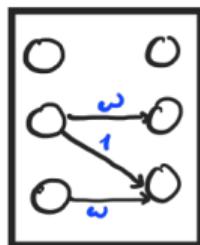
b





t_{gt}

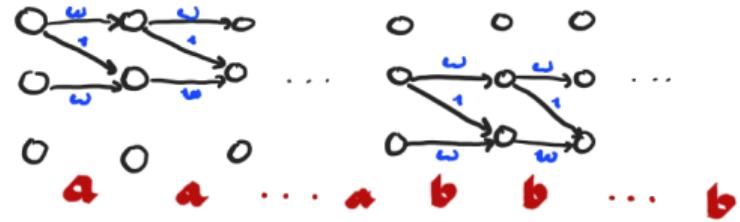
a

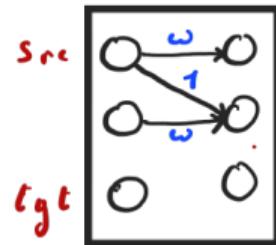


t_{gt}

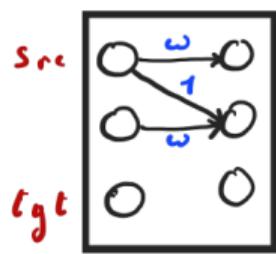
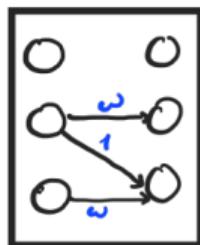
a

b

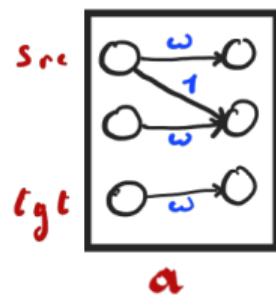
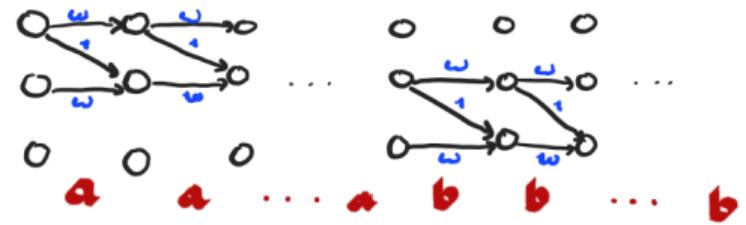
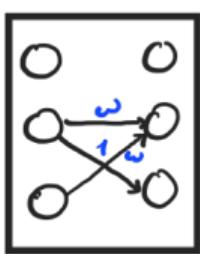




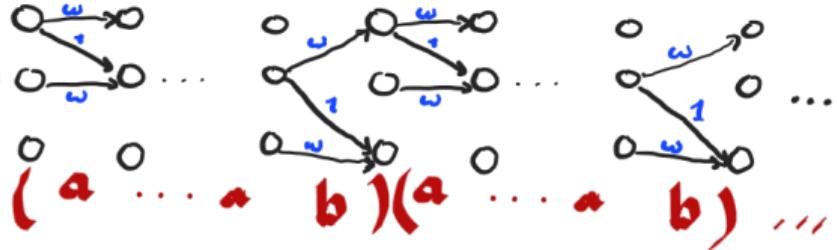
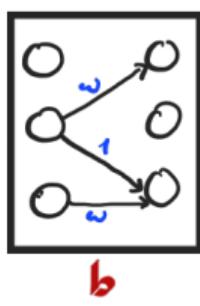
a



a



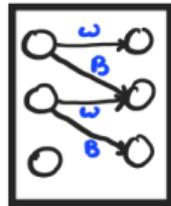
a



Monoid abstraction M

$1, 2, 3, \dots \rightsquigarrow B$

Elements =

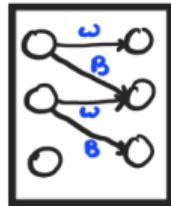


$$\{0, B, \omega\}^{S \times S}$$

Monoid abstraction M

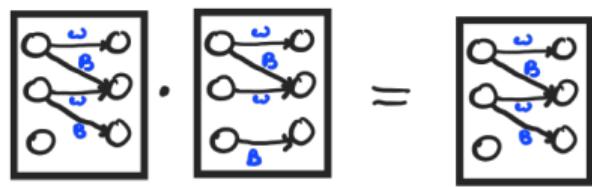
$1, 2, 3, \dots \rightsquigarrow B$

Elements:



$\{0, B, w\}^{S \times S}$

$$\text{Product: max-min } (\tau_0 \cdot \tau_1)[s, s'] = \max_{s'' \in S} \min(\tau_0[s, s''], \tau_1[s'', s'])$$

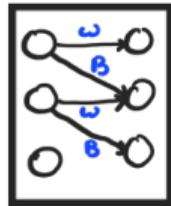


Morphism $\tau^* \rightarrow M$

Monoid abstraction M

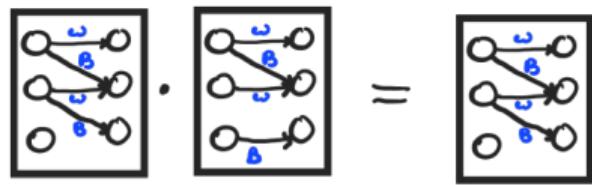
$1, 2, 3, \dots \rightsquigarrow B$

Elements:



$$\{O, B, \omega\}^{S \times S}$$

Product = max-min $\sim (\tau_0 \cdot \tau_1)[s, s'] = \max_{s'' \in S} \min(\tau_0[s, s''], \tau_1[s'', s'])$



Morphism $\tau^* \rightarrow M$

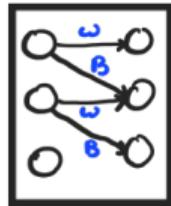
Problem:

$$\forall k, \quad \boxed{\begin{array}{c} \text{Diagram with } 4 \text{ states, } \\ \text{transitions: } \omega, B, B, \omega \end{array}}^k = \boxed{\begin{array}{c} \text{Diagram with } 2 \text{ states, } \\ \text{transitions: } \omega, B \end{array}}$$

Monoid abstraction M

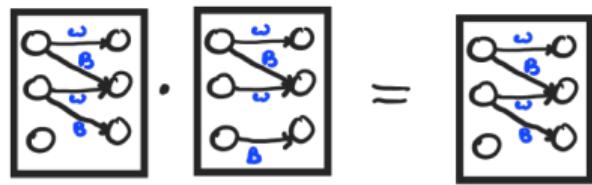
$1, 2, 3, \dots \rightsquigarrow B$

Elements:



$$\{0, B, \omega\}^{S \times S}$$

Product = max-min $\sim (\tau_0 \cdot \tau_1)[s, s'] = \max_{s'' \in S} \min(\tau_0[s, s''], \tau_1[s'', s'])$

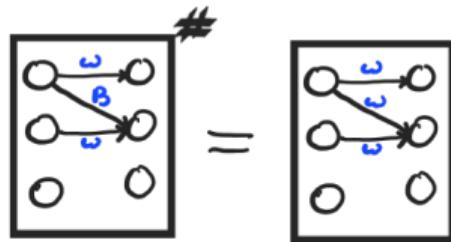


Morphism $\tau^* \rightarrow M$

Problem:

$$\forall k, \quad \boxed{\begin{array}{c} \text{square diagram} \\ \text{with } k \text{ states} \end{array}}^k = \boxed{\begin{array}{c} \text{square diagram} \\ \text{with } 2 \text{ states} \end{array}}$$

Define an operator φ (on idempotents)



Morphism φ from $\#$ -expressions to M
 $(a^{\#} b)^{\#}$

If there is a $\#$ -expression E
such that $\varphi(E)[\text{src}, \text{tgt}] = \omega$ then return Yes

↳ For all N , we can transfer N tokens
by replacing $\#$ with N .

$$(a^N b)^N$$

Simon's theorem

- Finite Monoid M
- Alphabet Σ
- Morphism $\varphi: \Sigma^* \rightarrow M$

Factorisation tree for $w \in \Sigma^*$
 M -labelled tree

Leaves = w

Nodes: Product nodes



Iteration nodes



Simon's theorem

- Finite Monoid M
- Alphabet Σ
- Morphism $\varphi: \Sigma^* \rightarrow M$

Factorisation tree for $w \in \Sigma^*$
 M -labelled tree

Leaves = w

Nodes: Product nodes Iteration nodes



Théorème

$\forall w \in \Sigma^*$, there is a factorisation tree for w of height $\leq 3|M|$

Application

If there is no expression E
such that $\varphi(E)[s_{rc}, t_{gt}] = \omega$ then return No

↳ Every word can be evaluated by
a tree of height $\leq 3|M|$

↳ Show that a word evaluated
by a tree of height h
has flow $\leq g(h, |M|)$

Application

If there is no expression E

such that $\varphi(E)[s_{rc}, t_{gt}] = \omega$ then return No

↳ Every word can be evaluated by
a tree of height $\leq 3|M|$

↳ Show that a word evaluated
by a tree of height h
has flow $\leq g(h, |M|)$

Théorème

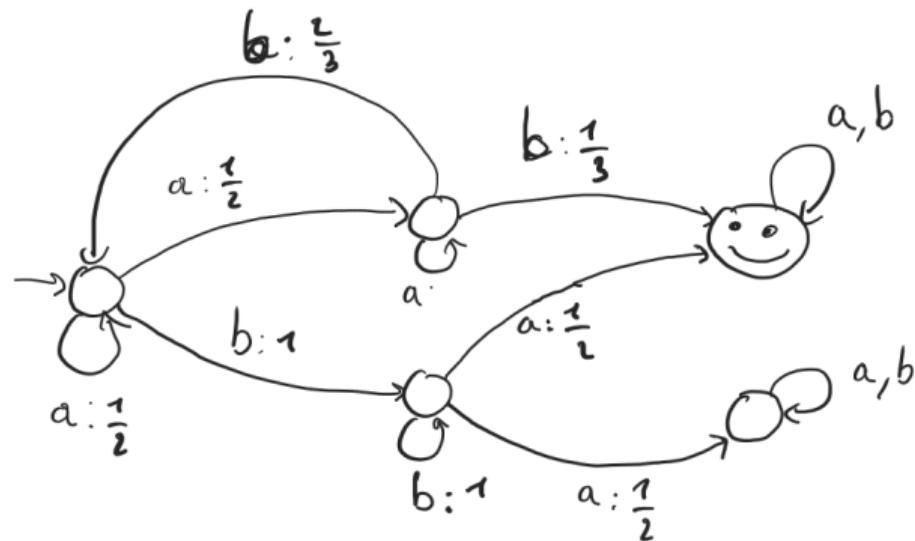
(by Saturation)

The parameterized flow problem is in EXPTIME

Application

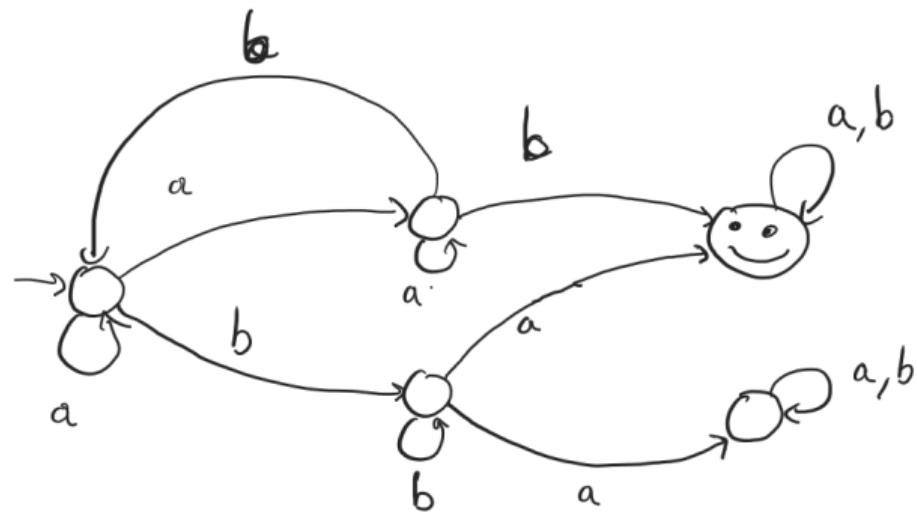
Parameterized PDPs.

Almost-sure reachability.



Goal: reach ☺ with probability 1.

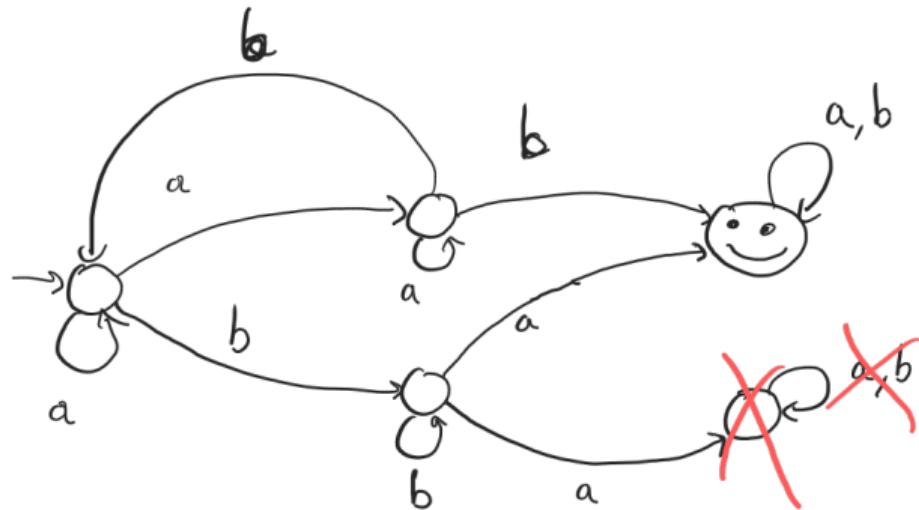
Almost-sure reachability.



→ Erase probabilities

Goal: reach ☺ with probability 1.

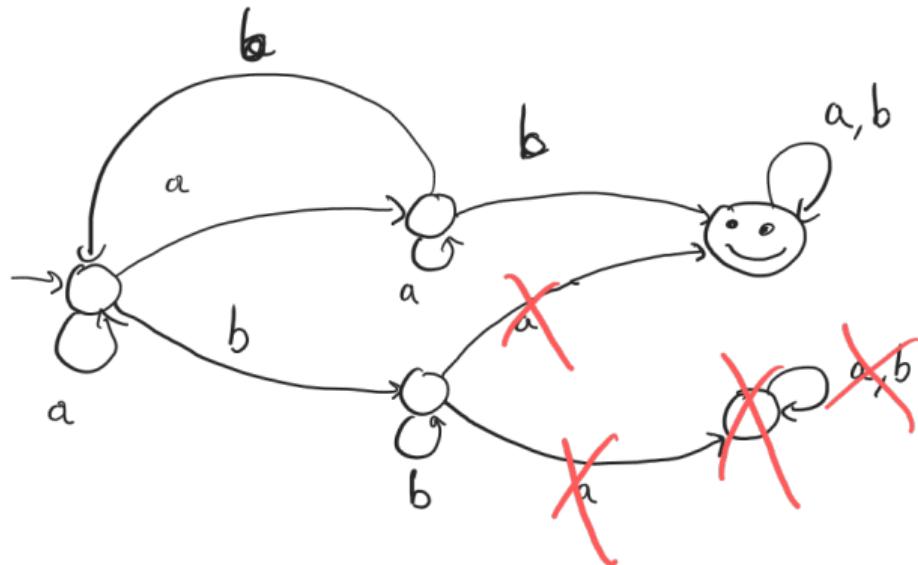
Almost-sure reachability.



Goal: reach ☺ with probability 1.

- Erase probabilities
- Compute winning region as greatest fix-point.
 - ↳ Repeatedly remove states from which ☺ is not reachable.

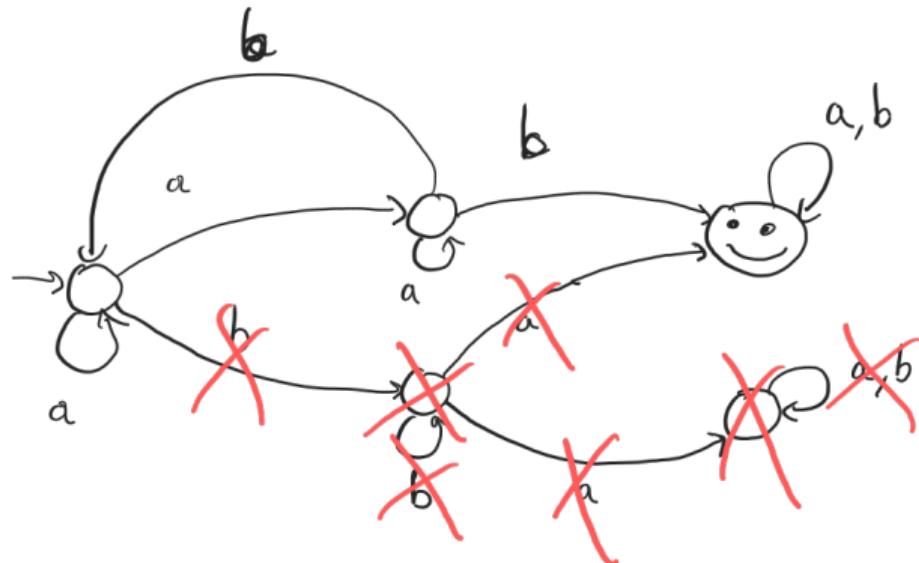
Almost-sure reachability.



Goal: reach ☺ with probability 1.

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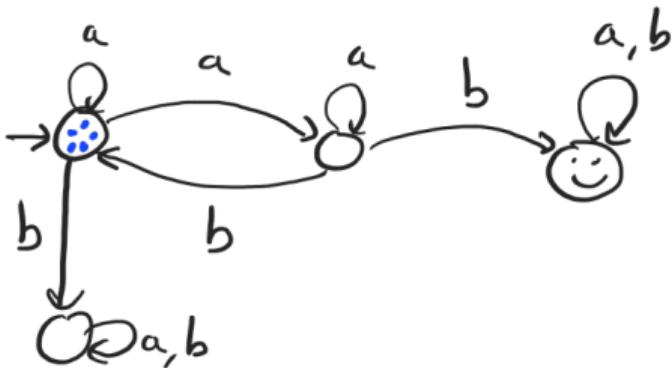
Almost-sure reachability.



Goal: reach ☺ with probability 1.

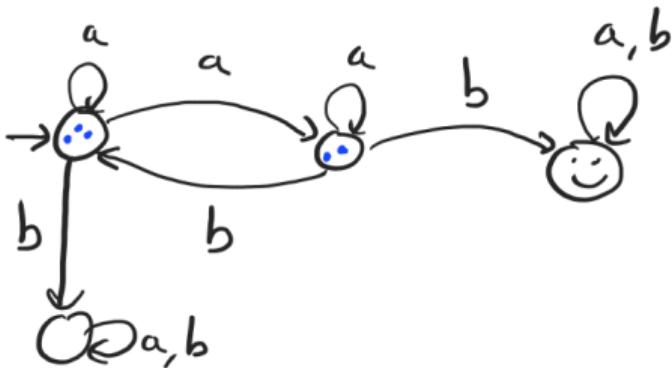
- Erase probabilities
- Compute winning region as greatest fix-point.
 - ↳ Repeatedly remove states from which ☺ is not reachable.

Parameterized MDPs



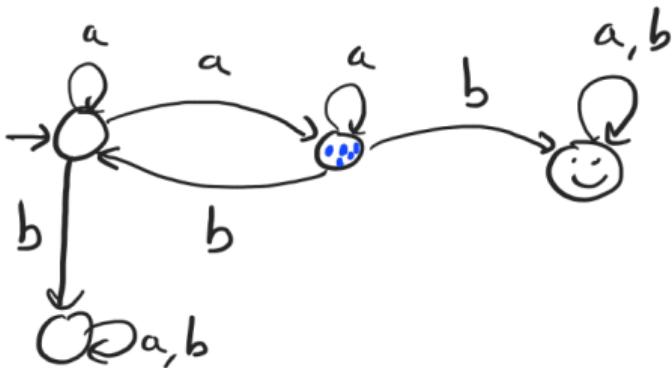
- Put N tokens in the initial state
- Each token reacts independently to the selected action.
- Try to make them all reach 😊

Parameterized MDPs



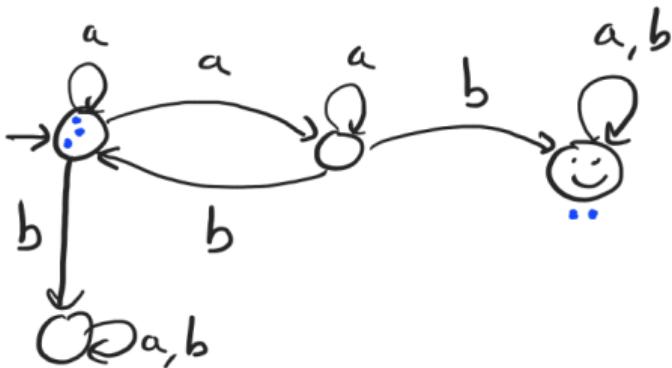
- Put N tokens in the initial state
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Parameterized MDPs



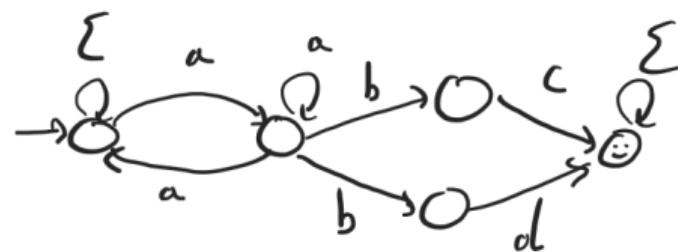
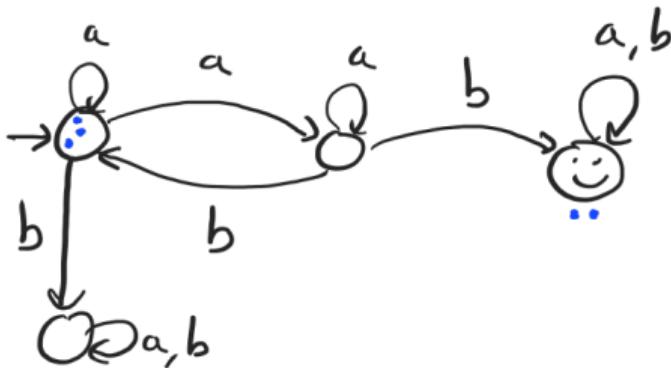
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Parameterized MDPs



- Put N tokens in the initial state
- Each token reacts independently to the selected action.
- Try to make them all reach ☺

Parameterized MDPs



- Put N tokens in the initial state
- Each token reacts independently to the selected action.
- Try to make them all reach ☺

Characterisation of winning MDPs

Winning region \hookrightarrow \oplus is always reachable with proba > 0.
 \hookrightarrow Never leave the region

+ Winning region is \downarrow -closed

\exists winning strategy
 \Leftrightarrow

$\exists W \subseteq N^S \times \Sigma$

- W is \downarrow -closed
- $\forall (v, a) \in W$, if $v \xrightarrow{a} v'$ then $v' \in W$
- $\forall v \in W$, \exists a path $v \rightsquigarrow F$ in W
- $N\text{-init} \subseteq W$

$W \leftarrow N^S \times \mathbb{C}$

\mathcal{D}_0

If $\exists (v, v') \in W$, $v \xrightarrow{\sim} v'$ with $v' \notin W$ ①

| $W \leftarrow W \setminus v'$

If $\exists v \in W$, $v \not\xrightarrow{\sim} F$ in W ②

| $W \leftarrow W \setminus v$

Until fixpoint

If $I \subseteq W \rightarrow \text{yes}$

Else $\rightarrow \text{No}$

① \rightarrow Easy

② \rightarrow Sequential flow problem

Theorem

The Random population control problem
is Exptime-complete.

Proof: Show that

winning strat $\Rightarrow \exists$ a region within the winning region in which at all times we have

- ↳ large crowds of tokens ω
- ↳ small sets of isolated tokens $\leq |S|$

Future work

Applications to - Verification

- Flows in infinite graphs

Quantitative objectives for parameterized MDPs

Speed of victory

" " "