

STAT 578: Advanced Bayesian Modeling

Week 4 – Lesson 3

Hierarchical Models: More Details

Fall 2019

Generalizing the Normal Hierarchical Model

Grouped Normal Samples

Let

$$y_{ij} = \text{\textit{i}th observation in group } j \qquad i = 1, \dots, n_j \qquad j = 1, \dots, J$$

so data are

$$y = (y_{11}, \dots, y_{n_1 1}, \quad y_{12}, \dots, y_{n_2 2}, \quad \dots, \quad y_{1J}, \dots, y_{n_J J})$$

Assume all independent, and assume identically distributed within groups:

$$y_{ij} \mid \theta_j \sim N(\theta_j, \sigma^2)$$

Note: We assume σ^2 is known and does not depend on group.

Remark: Typical for a completely randomized experiment with J treatments

Likelihood turns out to depend only on group averages:

$$\bar{y}_{\cdot j} = \frac{1}{n_j} \sum_{i=1}^{n_j} y_{ij} \quad j = 1, \dots, J$$

Their sampling variances are

$$\sigma_j^2 \equiv \text{var}(\bar{y}_{\cdot j} \mid \theta_j) = \sigma^2/n_j$$

(assumed known)

Thus, sampling model reduces to

$$\bar{y}_{\cdot j} \mid \theta_j \sim \text{indep. N}(\theta_j, \sigma_j^2)$$

(Normality of averages might be justified by central limit theorem, even if y_{ij} s are not exactly normally distributed.)

See BDA3, Sec. 5.4, for classical analysis.

Hierarchical Prior

As in 2016 polls example, let

$$\theta_1, \dots, \theta_J \mid \mu, \tau \sim \text{iid } N(\mu, \tau^2)$$

(as in a *one-way random effects* model – later).

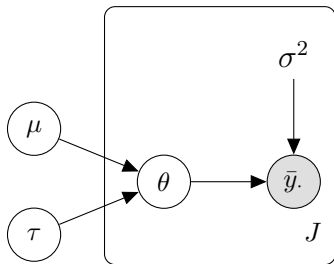
Consider product hyperprior for μ and τ :

$$p(\mu, \tau) = p(\mu) p(\tau)$$

Usually feasible to give μ an improper flat prior:

$$p(\mu) \propto 1$$

DAG Model



Note: Because it is on the plate, the σ^2 node is the constant *vector* $(\sigma_1^2, \dots, \sigma_J^2)$, and not the scalar σ^2 .

Posterior

See BDA3, Sec. 5.4, for derivation of posterior marginal density of τ :

$$p(\tau \mid y) \propto p(\tau) V_{\mu}^{1/2} \prod_{j=1}^J (\sigma_j^2 + \tau^2)^{-1/2} \exp\left(-\frac{(\bar{y}_{\cdot j} - \hat{\mu})^2}{2(\sigma_j^2 + \tau^2)}\right) \quad \tau > 0$$

where

$$V_{\mu}^{-1} = \sum_{j=1}^J \frac{1}{\sigma_j^2 + \tau^2} \qquad \hat{\mu} = \frac{\sum_{j=1}^J \frac{1}{\sigma_j^2 + \tau^2} \bar{y}_{\cdot j}}{\sum_{j=1}^J \frac{1}{\sigma_j^2 + \tau^2}}$$

BDA3 recommends (for $J > 2$)

$$p(\tau) \propto 1 \quad \tau > 0$$

BDA3, Sec. 5.4, also shows

$$\mu \mid \tau, y \sim \text{N}(\hat{\mu}, V_{\mu})$$

and

$$\theta_1, \dots, \theta_J \mid \mu, \tau, y \sim \text{indep. N}(\hat{\theta}_j, V_j)$$

where

$$\hat{\theta}_j = \frac{\frac{1}{\sigma_j^2} \bar{y}_{\cdot j} + \frac{1}{\tau^2} \mu}{\frac{1}{\sigma_j^2} + \frac{1}{\tau^2}} \qquad V_j = \frac{1}{\frac{1}{\sigma_j^2} + \frac{1}{\tau^2}}$$

Suggests how to simulate from posterior:

1. Draw τ_{sim} from $p(\tau \mid y)$ using an approximate numerical method.
2. Draw μ_{sim} from $p(\mu \mid \tau_{\text{sim}}, y)$.
3. Draw $\theta_{1\text{sim}}, \dots, \theta_{J\text{sim}}$ independently from

$$p(\theta_1 \mid \mu_{\text{sim}}, \tau_{\text{sim}}, y), \quad \dots, \quad p(\theta_J \mid \mu_{\text{sim}}, \tau_{\text{sim}}, y)$$

Extensions:

- ▶ For unknown σ^2 , provide a prior (such as scaled inverse chi-square).
- ▶ Allow sampling variances of original observations to differ by group, perhaps with a prior that makes them exchangeable (BDA3, Sec. 14.7).