

STAT 578: Advanced Bayesian Modeling

Week 1 – Lesson 2

Random Variables, Distributions, and Densities

Fall 2019

Several Random Variables

Sometimes we must make probability statements about two or more random variables jointly.

For example, suppose there is a 10% chance that U exceeds V :

$$\Pr(U > V) = 0.1$$

The **joint distribution** of U and V defines all probability statements that concern them (and only them).

We can regard it as the distribution of the **random vector** (U, V) .

Joint and Marginal Densities

If U and V are either both discrete or jointly continuous, their joint distribution is characterized by a **joint density**

$$p(u, v)$$

For example,

$$\Pr(U > V) = \begin{cases} \sum_{u > v} \sum p(u, v) & \text{both discrete} \\ \iint_{u > v} p(u, v) \, du \, dv & \text{jointly continuous} \end{cases}$$

The individual distributions of U and V – their **marginal distributions** – have **marginal densities** that can be obtained from the joint:

$$p(u) = \begin{cases} \sum_v p(u, v) & \text{both discrete} \\ \int p(u, v) dv & \text{jointly continuous} \end{cases}$$

and similarly for $p(v)$.

Note: We use notation $p(\cdot)$ for any density (joint or marginal), distinguishing according to the symbols used for the arguments.

Joint Features

If g is a scalar function of U and V (both discrete or jointly continuous),

$$\mathbb{E}(g(U, V)) = \begin{cases} \sum_u \sum_v g(u, v) p(u, v) & \text{both discrete} \\ \iint g(u, v) p(u, v) du dv & \text{jointly continuous} \end{cases}$$

when this exists.

U and V have **covariance**

$$\text{cov}(U, V) = \text{E}\left((U - \text{E}(U))(V - \text{E}(V))\right)$$

and **correlation**

$$\frac{\text{cov}(U, V)}{\sqrt{\text{var}(U) \text{var}(V)}}$$

when these exist.

Conditioning

Conceptually, the **conditional distribution** of U given $V = v$ is how U would be distributed if V were fixed at value v .

For example:

- ▶ A randomly sampled adult has weight U and height V .

Then the conditional distribution of U given $V = 170\text{cm}$ is the distribution of weights of adults who are 170cm tall.

- ▶ A randomly sampled registered motor vehicle has had U different owners over the V years since it was made.

Then the conditional distribution of U given $V = 10$ is the distribution of the number of owners among 10-year-old vehicles.

The conditional distribution of U given $V = v$ may have a **conditional density**

$$p(u \mid v)$$

which defines conditional probabilities concerning U , given $V = v$.

For example, if U is continuous (given $V = v$) then

$$\Pr(U \in D \mid V = v) = \int_D p(u \mid v) du$$

Note: We use notation $p(\cdot \mid \cdot)$ for any conditional density, distinguishing according to the symbols used for the arguments.

A conditional density $p(u \mid v)$ has the same properties as an ordinary (marginal) density:

- ▶ It may be discrete or continuous.
- ▶ It is non-negative.
- ▶ It sums/integrates to 1 over u (its first argument).

Note: It generally does **not** sum/integrate to 1 over its second argument, e.g.,

$$\int p(u \mid v) dv \neq 1$$

If U and V have a joint density, it can be taken as

$$p(u, v) = p(v) p(u | v)$$

In general, $p(v) p(u | v)$ characterizes the joint distribution of U and V .

It can often be treated like a joint density, e.g., if V is continuous and U is discrete,

$$p(u) = \int p(v) p(u | v) dv$$

Commonly, we specify the conditional distribution of U given $V = v$ by name, with v as a parameter.

We use notation

$$U \mid V = v \sim \text{name}(\text{parameters that can depend on } v)$$

E.g., if V is distributed on $(0, 1)$ and

$$U \mid V = v \sim \text{Bin}(n, v)$$

then the conditional density is

$$p(u \mid v) = \binom{n}{u} v^u (1 - v)^{n-u} \quad u = 0, 1, \dots, n$$

E.g., if

$$U \mid V = v \sim N(v, \sigma^2)$$

then we can use conditional density

$$p(u \mid v) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(u-v)^2} \quad (\text{all } u)$$

Conditional Features

Features like means and variances can be defined for conditional distributions, with corresponding notation.

The **conditional expectation** of $g(U)$ given $V = v$:

$$\mathbb{E}(g(U) \mid V = v) = \begin{cases} \sum_u g(u) p(u \mid v) & U \text{ conditionally discrete} \\ \int g(u) p(u \mid v) du & U \text{ conditionally continuous} \end{cases}$$

(when it exists)

The **conditional variance** of U given $V = v$:

$$\text{var}(U \mid V = v) = \text{E}\left(\left(U - \text{E}(U \mid V = v)\right)^2 \mid V = v\right)$$

(when it exists)

Similarly, there are conditional standard deviations, medians, quantiles, etc.

More Variables

If random variables U, V, W have joint density

$$p(u, v, w)$$

then lower-order densities are obtained by marginalizing.

E.g., if U, V, W are jointly continuous,

$$p(u, v) = \int p(u, v, w) dw \qquad p(v) = \iint p(u, v, w) du dw$$

There may be joint conditional densities, like

$$p(u, v \mid w)$$

or densities conditional on more than one variable, like

$$p(u \mid v, w)$$

Properties extend to these more general cases, e.g., if U, V, W have a joint density, it can be taken as

$$p(w) p(u, v \mid w)$$

or as

$$p(v, w) p(u \mid v, w)$$

We will often multiply marginal and conditional densities, like

$$p(w) p(v \mid w) p(u \mid v, w)$$

to create something that will be treated like a joint density.

E.g., if V and W are jointly continuous,

$$p(u) = \iint p(w) p(v \mid w) p(u \mid v, w) dv dw$$

represents a marginal density for U .

Conditional densities satisfy relationships like those of unconditional densities.

E.g., if U and V are jointly continuous given $W = w$,

$$p(u \mid w) = \int p(u, v \mid w) dv$$

and we can replace $p(u, v \mid w)$ with

$$p(v \mid w) p(u \mid v, w)$$

when the densities exist.