ADVANCED BAYESIAN MODELING

Bayesian Tools and Integration

Review: Notation and Concepts

Sampling density of data
$$y$$
 (likelihood in θ): $p(y \mid \theta)$

Prior density:
$$p(\theta)$$

Posterior density (by Bayes' rule):

$$p(\theta \mid y) = \frac{p(\theta) p(y \mid \theta)}{p(y)} \propto p(\theta) p(y \mid \theta)$$

 $\theta = (\theta_1, \dots, \theta_d)$

Bayesian tools are based on $p(\theta \mid y)$:

- Posterior means and standard deviations
- Posterior probabilities
- Marginal posterior densities
- Posterior quantiles
- Posterior intervals
- Posterior predictions

Note: θ is almost always jointly continuous (even if y is discrete).

Therefore, most tools involve integration ...

Posterior Expectations

Many tools are posterior expectations of some scalar function $h(\theta)$,

$$E(h(\theta) \mid y) = \int h(\theta) p(\theta \mid y) d\theta$$

which can be a multidimensional integral.

E.g., posterior mean of
$$\theta_j$$
: $h(\theta) = \theta_j$

E.g., posterior variance of
$$\theta_j$$
: $h(\theta) = (\theta_j - E(\theta_j \mid y))^2$

(Note: h can also depend on y)

4

A posterior probability is just a type of posterior expectation:

$$\Pr(\theta \in A \mid y) = \int_{A} p(\theta \mid y) d\theta$$
$$= \int 1_{A}(\theta) p(\theta \mid y) d\theta = \operatorname{E}(1_{A}(\theta) \mid y)$$

where 1_A represents an indicator function:

$$1_A(\theta) = \begin{cases} 1, & \theta \in A \\ 0, & \text{otherwise} \end{cases}$$

Posterior Marginals

Let

$$\theta_{-j} = \theta$$
 without θ_j

Then the marginal posterior density of θ_j is

$$p(\theta_j \mid y) = \int p(\theta \mid y) d\theta_{-j}$$

Posterior Quantiles and Intervals

The posterior (lower) α quantile q_{α} of θ_{j} is defined implicitly in terms of an integral:

$$\alpha = \Pr(\theta_j \le q_\alpha \mid y) = \int_{-\infty}^{q_\alpha} p(\theta_j \mid y) d\theta_j$$

For example, the median is $q_{0.5}$.

A central $(1 - \alpha)100\%$ posterior interval for θ_j is just defined in terms of posterior quantiles:

$$(q_{\alpha/2}, q_{1-\alpha/2})$$

.

Posterior Prediction

An observable (but unobserved) \tilde{y} with sampling density

$$p(\tilde{y} \mid \theta)$$
 (conditionally independent of y)

has posterior predictive density

$$p(\tilde{y} \mid y) = \int p(\tilde{y} \mid \theta) p(\theta \mid y) d\theta$$

If \tilde{y} is continuous, also use integration to find posterior predictive expectations (including probabilities).

٤

Priors and Integration

There are also integrations based on the prior.

The normalizing factor is an example:

$$p(y) = \int p(y \mid \theta) p(\theta) d\theta$$

If the prior is proper, there are also prior expectations and probabilities:

$$E(h(\theta))$$
 $Pr(\theta \in A) = E(1_A(\theta))$

These are defined by integrations involving the prior.

(