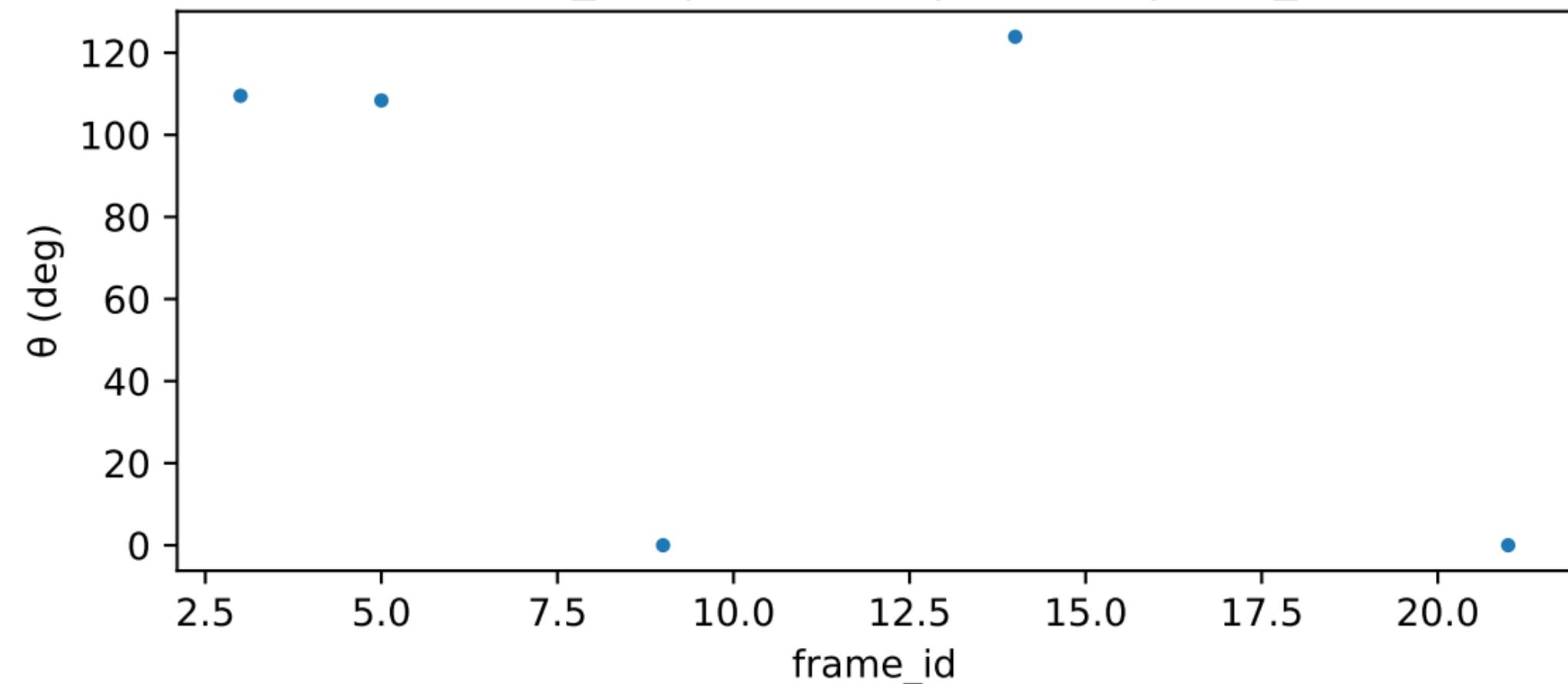


step 00: 00_init | points=5 | lines=0 | max_len=5



step 01: 01_after_first_link | points=5 | lines=2 | max_len=3

θ (deg)

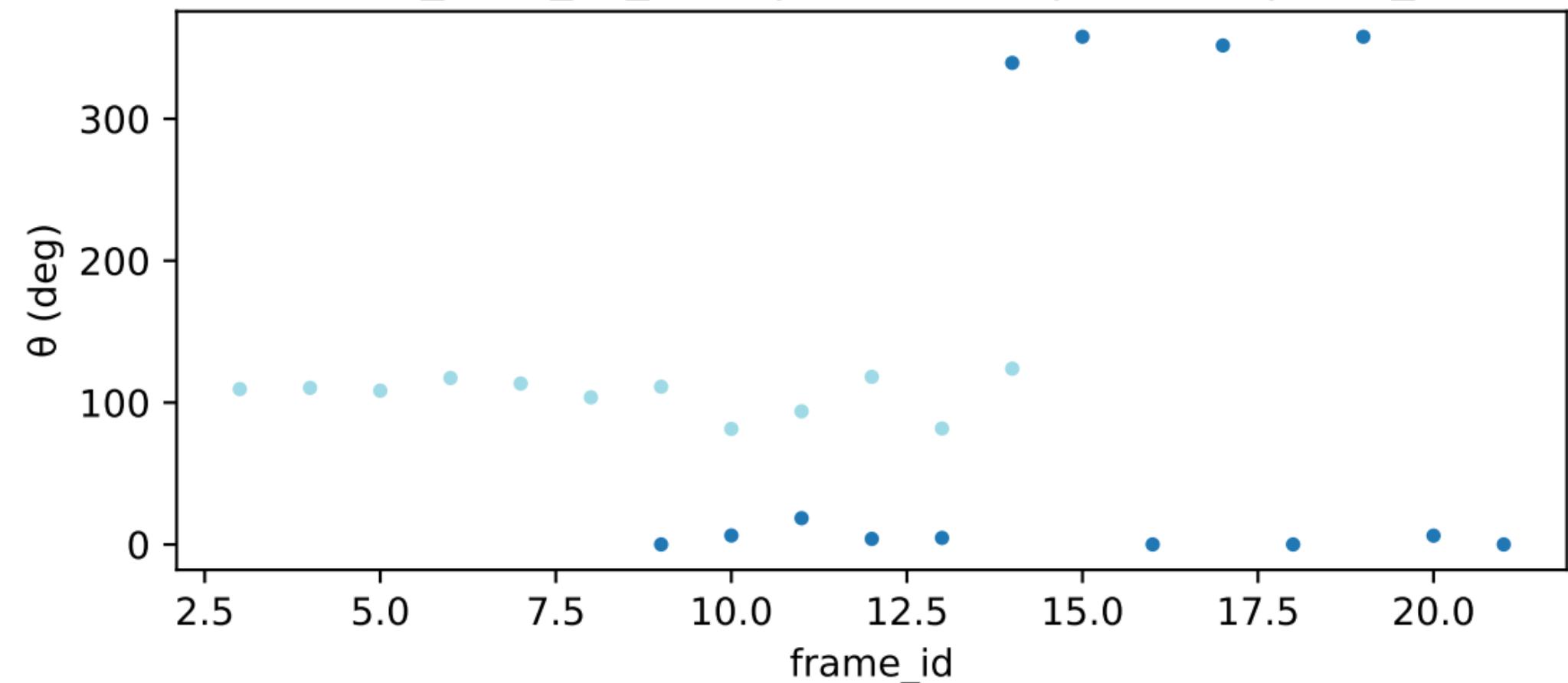
120
100
80
60
40
20
0

2.5 5.0 7.5 10.0 12.5 15.0 17.5 20.0

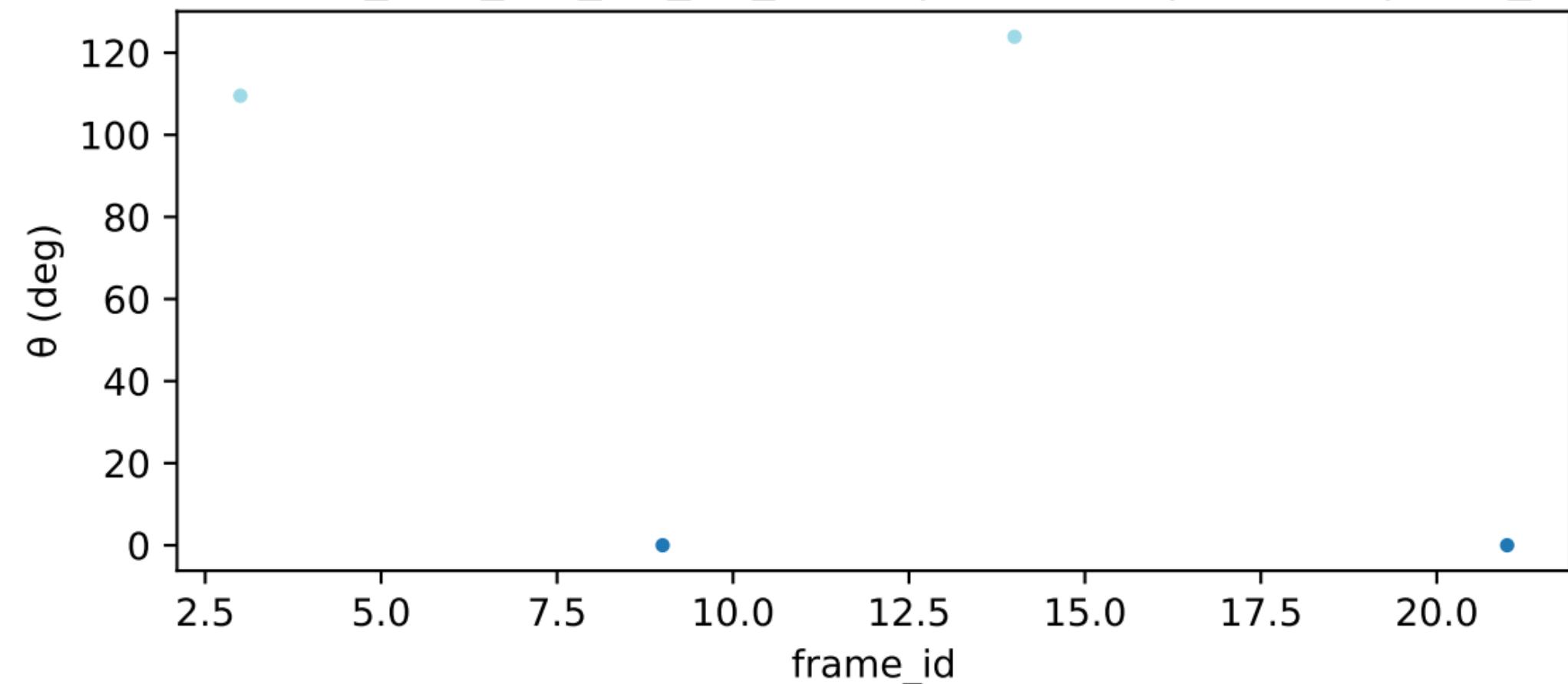
frame_id



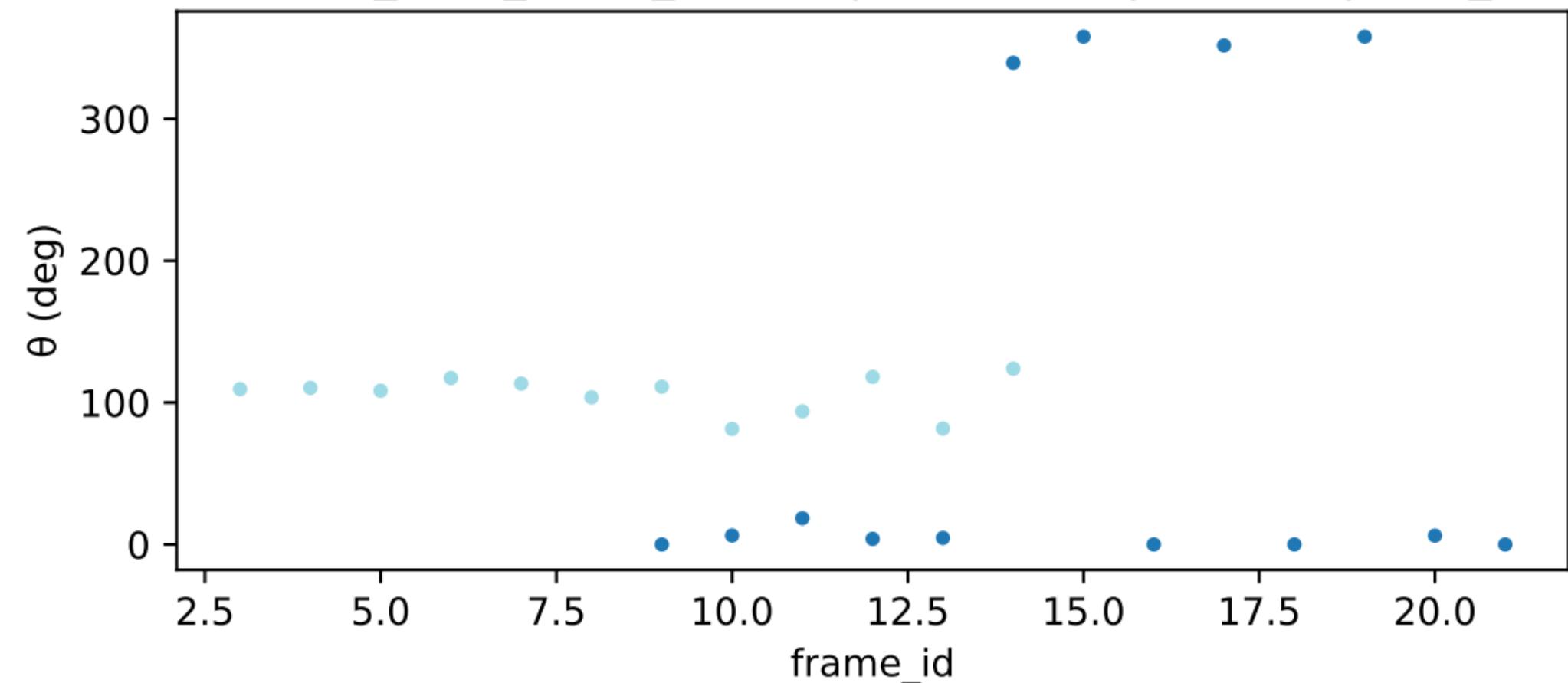
step 02: 02_after_fill_gaps | points=25 | lines=2 | max_len=13



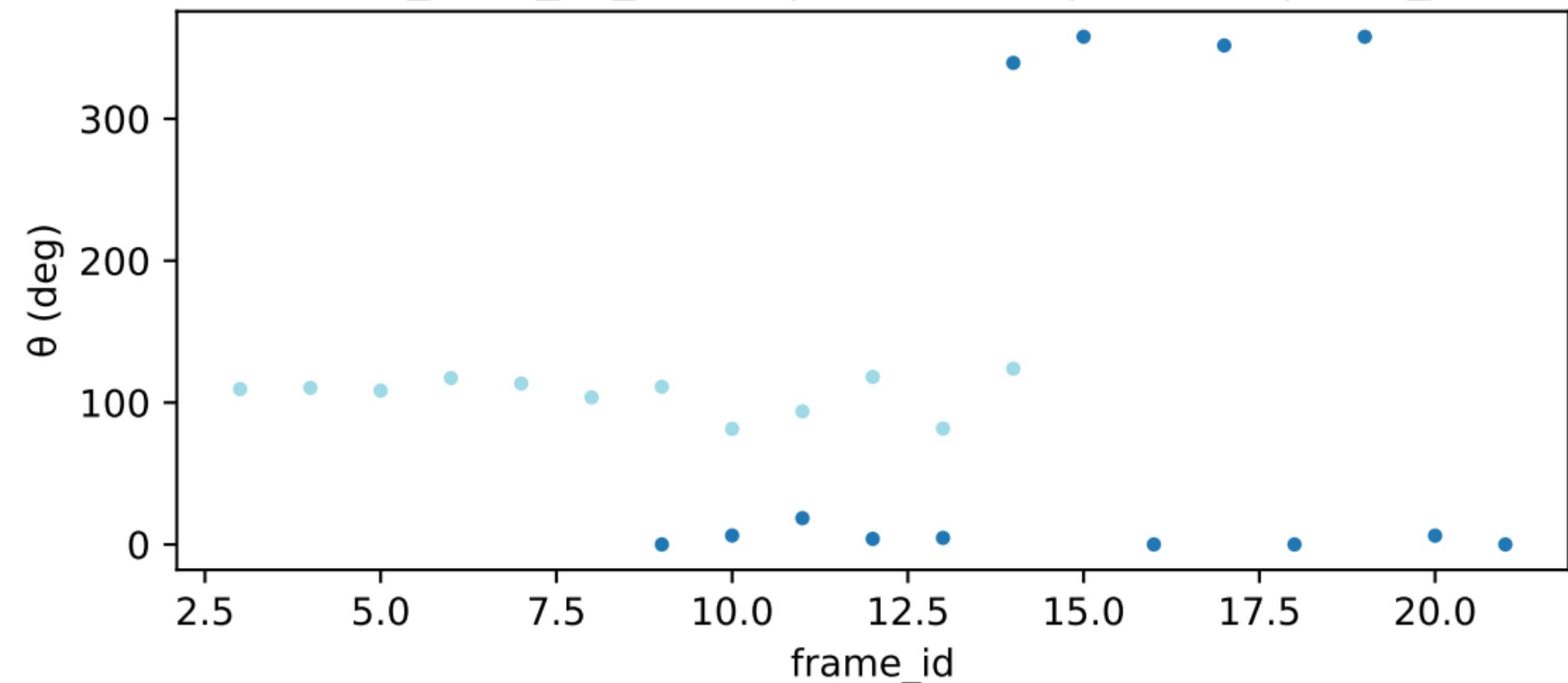
step 03: 03a_new_pnt_list_for_final1 | points=4 | lines=2 | max_len=2



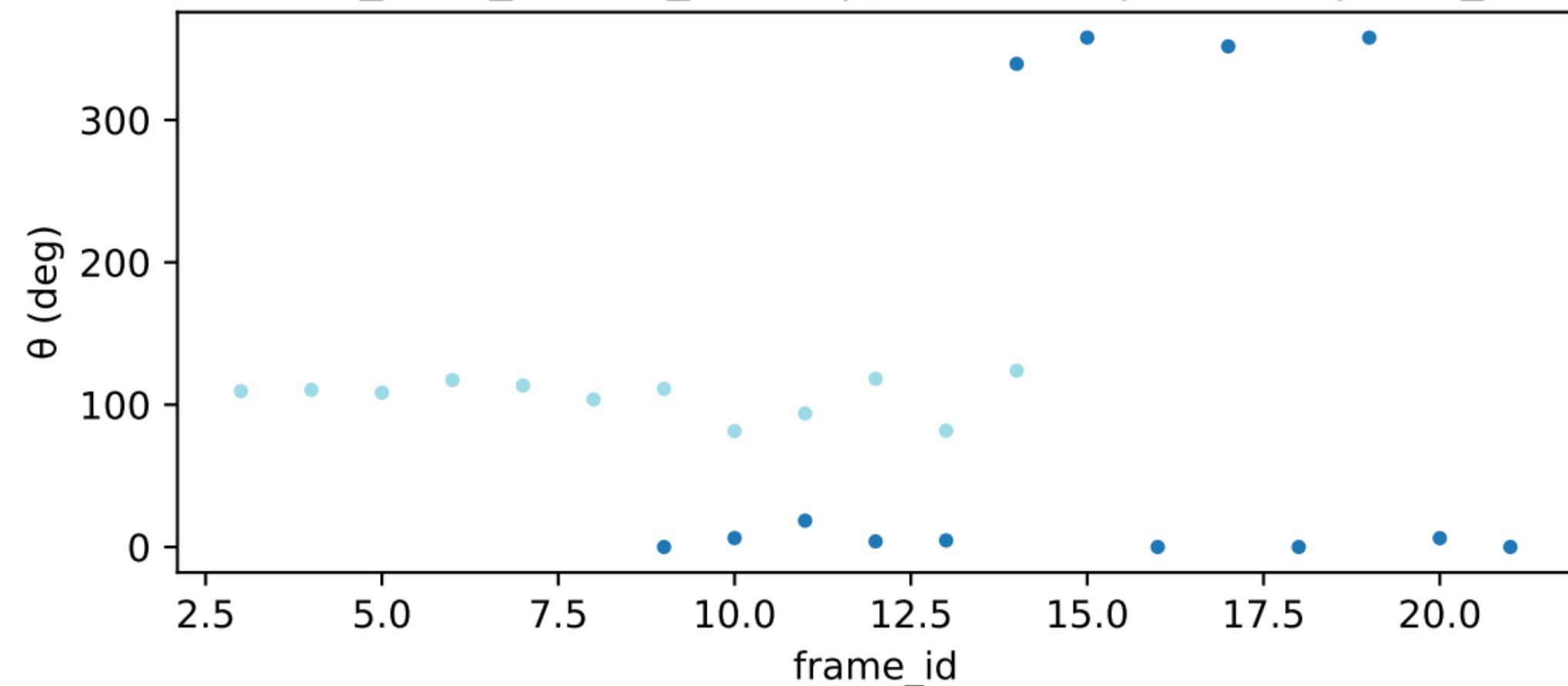
step 03: 03b_after_final1_update | points=25 | lines=2 | max_len=13



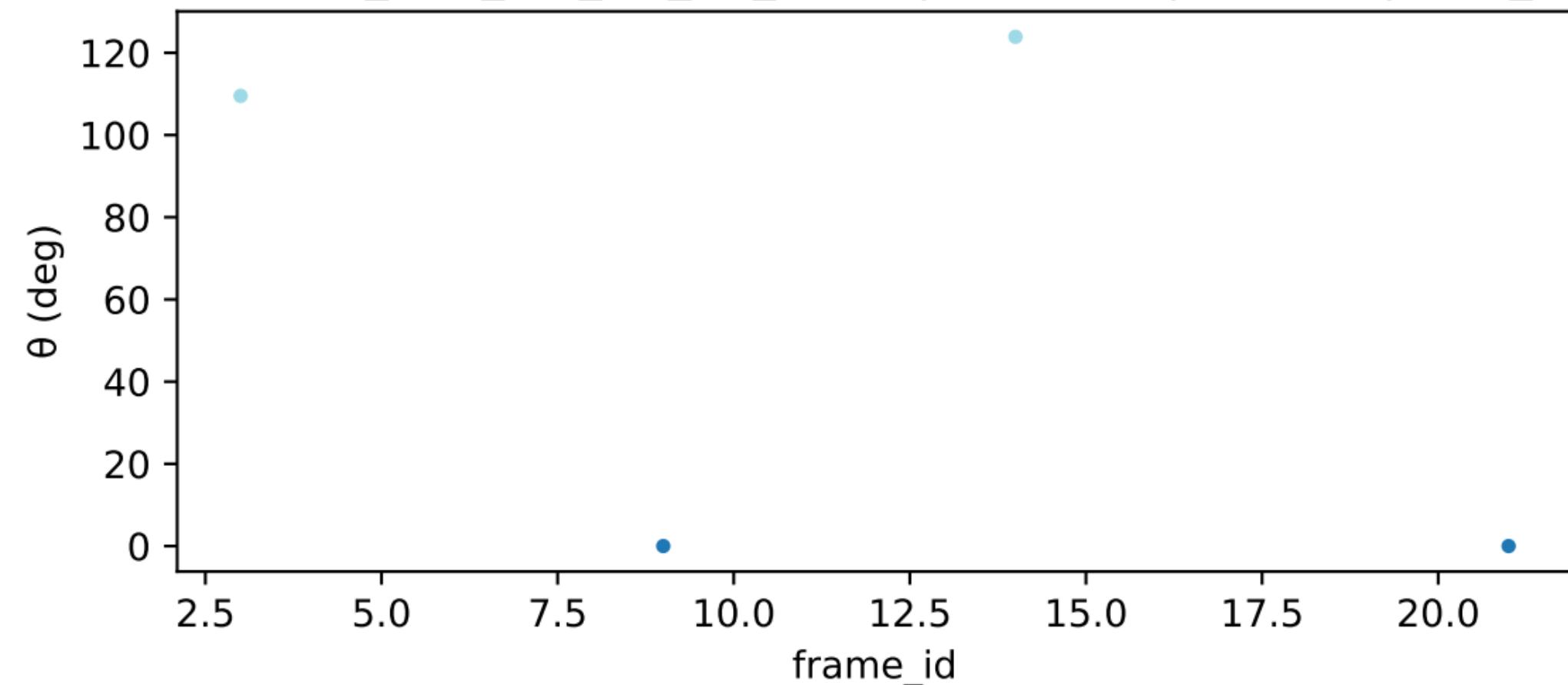
step 04: 04_after_fill_gaps2 | points=25 | lines=2 | max_len=13



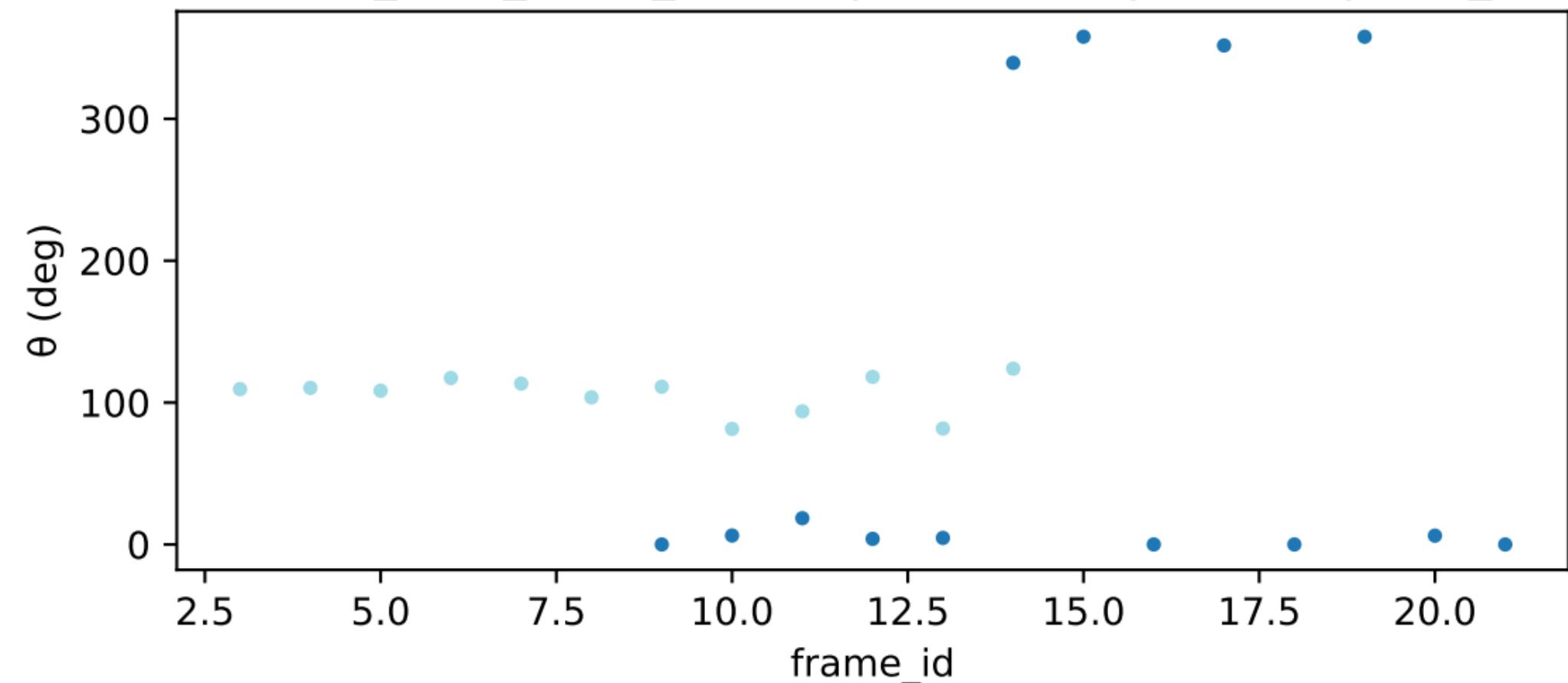
step 05: 05_after_minlen_filter1 | points=25 | lines=2 | max_len=13



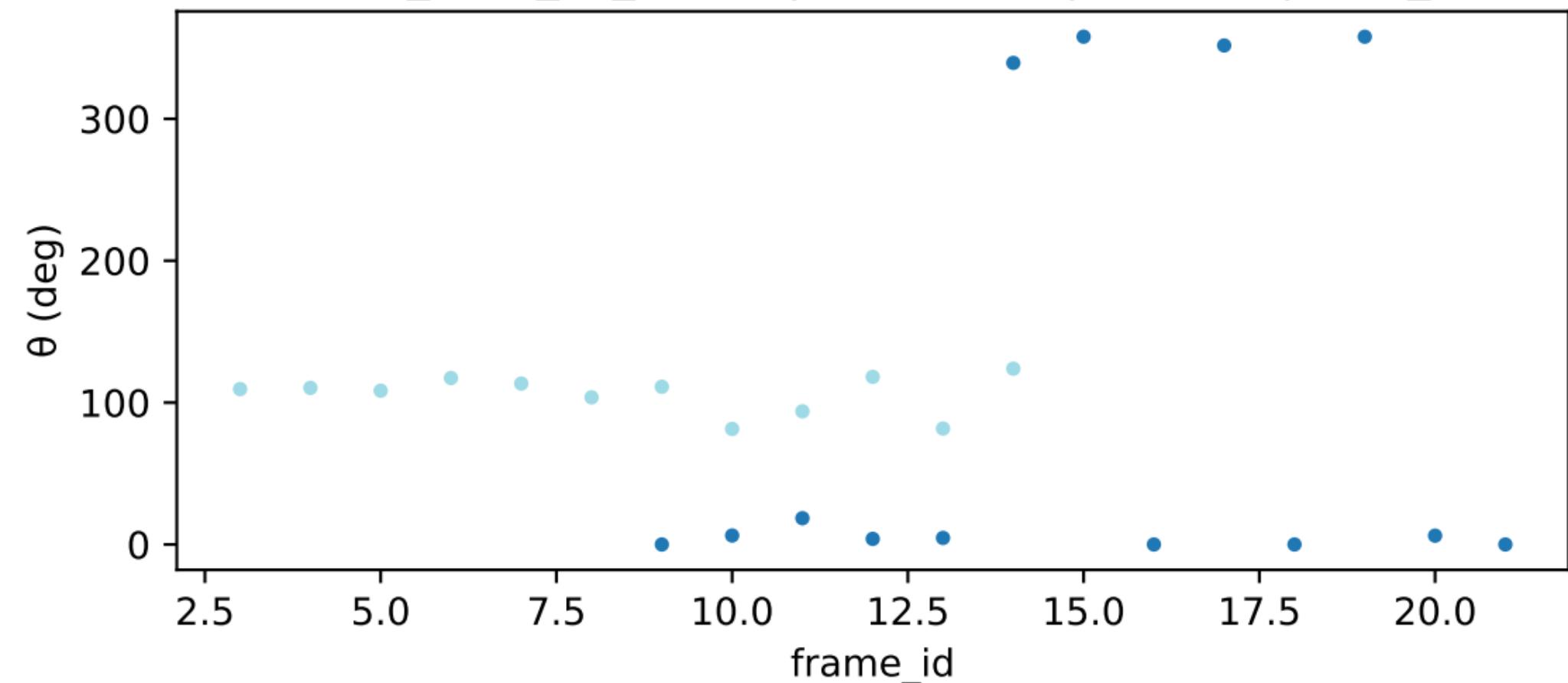
step 06: 06a_new_pnt_list_for_final2 | points=4 | lines=2 | max_len=2



step 06: 06b_after_final2_update | points=25 | lines=2 | max_len=13



step 07: 07_after_fill_gaps3 | points=25 | lines=2 | max_len=13



step 08: 08_after_minlen_filter2_final | points=25 | lines=2 | max_len=13

