

ELECENG 3CL4 Lab 2 Pre-lab

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1 Description of Laboratory Equipment

Pre-lab Question 1

The step response of the model $G(s)$ is in Equation 1. The derivation of the step response is shown below.

$$\begin{aligned}
 \mathcal{L}^{-1} \left\{ G(s) \frac{1}{s} \right\} &= \mathcal{L}^{-1} \left\{ \frac{A}{s(s\tau_m + 1)} \frac{1}{s} \right\} \\
 &= A \mathcal{L}^{-1} \left\{ \frac{1}{s^2(s\tau_m + 1)} \right\} \\
 &= A \mathcal{L}^{-1} \left\{ \frac{\tau_m^2}{s\tau_m + 1} - \frac{\tau_m}{s} + \frac{1}{s^2} \right\} \\
 &= A \left[\mathcal{L}^{-1} \left\{ \frac{\tau_m^2}{s\tau_m + 1} \right\} - \mathcal{L}^{-1} \left\{ \frac{\tau_m}{s} \right\} + \mathcal{L}^{-1} \left\{ \frac{1}{s^2} \right\} \right] \\
 &= A \left[\tau_m e^{-\frac{t}{\tau_m}} - \tau_m u(t) + t \right]
 \end{aligned} \tag{1}$$

Pre-lab Question 2

The step response is not bounded because the term t is not bounded.

2 Closed Loop System Identification

Pre-lab Question 3

(i) The output signal of the model can be expressed as:

$$\begin{aligned}
 Y(s) &= \frac{G_c(s)G(s)}{1 + H(s)G_c(s)G(s)} R(s) + \frac{G(s)}{1 + H(s)G_c(s)G(s)} T_d(s) \\
 &\quad + \frac{H(s)G_c(s)G(s)}{1 + H(s)G_c(s)G(s)} N(s)
 \end{aligned}$$

If we neglect the effects of the disturbance $T_d(s)$ and the noise $N(s)$, we are left with:

$$Y(s) = \frac{G_c(s)G(s)}{1 + H(s)G_c(s)G(s)} R(s)$$

When $H(s) = 1$ and we let $\Theta(s) = Y(s)$, we can find the transfer function $T(s)$ in Equation 2 (idk why this isn't working), which is equal to Equation 4a from the lab document.

$$\begin{aligned}
 T(s) &= \frac{\Theta(s)}{R(s)} \\
 &= \frac{\frac{G_c(s)G(s)}{1+H(s)G_c(s)G(s)} R(s)}{R(s)} \\
 &= \frac{G(s)G_c(s)}{1 + G(s)G_c(s)}
 \end{aligned} \tag{2}$$

- (ii) When we substitute $G(s) = \frac{A}{s(s\tau_m+1)}$ and $G_c(s) = K$ into Equation 2, and then substituting $\sqrt{\frac{KA}{\tau_m}} = \omega_n$ and $\frac{1}{2\omega_n\tau_m}$ into the result, we can derive Equation 3 which is equal to Equation 4b from the lab document:

$$\begin{aligned}
T(s) &= \frac{G(s)G_c(s)}{1 + G(s)G_c(s)} \\
&= \frac{\frac{A}{s(s\tau_m+1)}K}{1 + \frac{A}{s(s\tau_m+1)}K} \\
&= \frac{KA}{s(s\tau_m+1)(1 + \frac{A}{s(s\tau_m+1)}K)} \\
&= \frac{KA}{s(s\tau_m+1 + \frac{KA}{s})} \\
&= \frac{KA}{s^2\tau_m + s + KA} \\
&= \frac{KA/\tau_m}{s^2 + (1/\tau_m)s + KA/\tau_m} \\
&= \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}
\end{aligned} \tag{3}$$

Pre-lab Question 4

When given ζ and ω_n , we can derive Equation 4 for τ_m :

$$\begin{aligned}
\zeta &= \frac{1}{2\omega_n\tau_m} \\
\tau_m &= \frac{1}{2\omega_n\zeta}
\end{aligned} \tag{4}$$

By substituting Equation 4 into the equation for ω_n , we can derive Equation 5 for A :

$$\begin{aligned}
\omega_n &= \sqrt{\frac{KA}{\tau_m}} \\
\omega_n^2 &= \frac{KA}{\tau_m} \\
A &= \frac{\omega_n^2\tau_m}{K} \\
A &= \frac{\omega_n/2\zeta}{K}
\end{aligned} \tag{5}$$

2.1 Closed-loop System Identification from the Step Response

Pre-lab Question 5

The percent overshoot is determined at the peak time, T_p , of the step response. For the provided step response, this peak time occurs the first time $d\theta_{\text{step}}(t)/dt = 0$, which occurs

when $\omega_n \sqrt{1 - \zeta^2} t = \pi$. Therefore, the peak time T_p is equal to $\frac{\pi}{\omega_n \sqrt{1 - \zeta^2}}$. At the peak time, the peak value of the step response is $1 + \exp\left(-\zeta \pi / \sqrt{1 - \zeta^2}\right)$. Therefore, the percent overshoot can be defined as $P.O. = 100 \frac{(1 + \exp(-\zeta \pi / \sqrt{1 - \zeta^2})) - 1}{1} = 100 \exp\left(\frac{-\zeta \pi}{\sqrt{1 - \zeta^2}}\right)$.

Pre-lab Question 6

As discussed in the solution to Pre-lab Question 5, the peak time occurs the first time $d\theta_{\text{step}}(t)/dt = 0$, which occurs when $\omega_n \sqrt{1 - \zeta^2} t = \pi$. Therefore, the peak time T_p is equal to $\frac{\pi}{\omega_n \sqrt{1 - \zeta^2}}$.

Pre-lab Question 7

From the equation for P.O., you can calculate ζ as:

$$\begin{aligned}
 P.O. &= 100 \exp\left(\frac{-\zeta \pi}{\sqrt{1 - \zeta^2}}\right) \\
 \frac{P.O.}{100} &= \exp\left(\frac{-\zeta \pi}{\sqrt{1 - \zeta^2}}\right) \\
 \ln\left(\frac{P.O.}{100}\right) &= \frac{-\zeta \pi}{\sqrt{1 - \zeta^2}} \\
 \frac{(\ln(\frac{P.O.}{100}))^2}{\pi^2} &= \frac{\zeta^2}{1 - \zeta^2} \\
 \frac{(\ln(\frac{P.O.}{100}))^2}{\pi^2} &= 1 - \frac{1}{1 + \zeta^2} \\
 1 - \frac{(\ln(\frac{P.O.}{100}))^2}{\pi^2} &= \frac{1}{1 + \zeta^2} \\
 1 + \zeta^2 &= \frac{1}{\left(1 - \frac{(\ln(\frac{P.O.}{100}))^2}{\pi^2}\right)} \\
 \zeta^2 &= \frac{1}{\left(1 - \frac{(\ln(\frac{P.O.}{100}))^2}{\pi^2}\right)} - 1 \\
 \zeta &= \sqrt{\frac{1}{\left(1 - \frac{(\ln(\frac{P.O.}{100}))^2}{\pi^2}\right)} - 1} \tag{6}
 \end{aligned}$$

ok lets try something thats probably a bit easier

$$\begin{aligned}
 T_p &= \frac{\pi}{\omega_n \sqrt{1 - \zeta^2}} \\
 \omega_n &= \frac{\pi}{T_p \sqrt{1 - \zeta^2}} \tag{7}
 \end{aligned}$$

2.2 Closed-Loop System Identification using the Frequency Response

Pre-lab Question 8

$$\begin{aligned}
 \frac{d}{d\omega} |\omega_n^2 - \omega^2 + j2\zeta\omega_n\omega|^2 &= \overbrace{2(\omega_n^2 - \omega^2 + j2\zeta\omega_n\omega) \frac{d}{d\omega} (\omega_n^2 - \omega^2 + j2\zeta\omega_n\omega)}^{\text{apply chain rule}} \\
 &= 2(\omega_n^2 - \omega^2 + j2\zeta\omega_n\omega)(-2\omega + j2\zeta\omega_n) \\
 0 &= 4(\omega_n^2 - \omega^2 + j2\zeta\omega_n\omega)(-\omega + j\zeta\omega_n) \\
 0 &= (\omega_n^2 - \omega^2 + j2\zeta\omega_n\omega)(-\omega + j\zeta\omega_n) \\
 &= (\omega_n^2 - (\omega_n\sqrt{1-2\zeta^2})^2 + j2\zeta\omega_n\sqrt{1-2\zeta^2})(-\sqrt{1-2\zeta^2} + j\zeta\omega_n) =
 \end{aligned} \tag{8}$$

Pre-lab Question 9

$$\begin{aligned}
 M_p^2 &= \max_{\omega} |T(j\omega)|^2 \\
 &= |T(j\omega_p)|^2 \\
 &= \frac{\omega_n^4}{\left| \omega_n^2 - (\omega_n\sqrt{1-2\zeta^2})^2 + j2\zeta\omega_n^2\sqrt{1-2\zeta^2} \right|^2} \\
 &= \frac{\omega_n^4}{\left| \omega_n^2 - \omega_n^2(1-2\zeta^2) + j2\zeta\omega_n^2\sqrt{1-2\zeta^2} \right|^2} \\
 &= \frac{\omega_n^4}{\left| \omega_n^2 \left(j2\zeta\sqrt{1-2\zeta^2} + 2\zeta^2 \right) \right|^2} \\
 &= \frac{\omega_n^4}{\omega_n^4(4\zeta^4 + 4\zeta^2(1-2\zeta^2))} \\
 &= \frac{1}{4\zeta^2(\zeta^2 + 1 - 2\zeta^2)} \\
 &= \frac{1}{4\zeta^2(1 - \zeta^2)}
 \end{aligned} \tag{9}$$

Pre-lab Question 10

$$\begin{aligned}
 M_p^2 &= \frac{1}{4\zeta^2(1 - \zeta^2)} \\
 4\zeta^2(1 - \zeta^2) &= \frac{1}{M_p^2}
 \end{aligned} \tag{10}$$