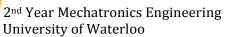


www.raejeong.com





Objective

My passion is in the field of Robotics and I am taking the initiative to create an open source robotic arm platform using 3D printing and the Robot Operating System.

Skills Summary

C++ ROS Git Arduino Python RViz/Gazebo Machining PLC

MATLAB Ubuntu Linux Solidworks Raspberry Pi

Work Experience

Robotics Research and Development Engineer :: MakeLab

May 2015 – Aug 2015

- Leading the research and development of a light weight robotic arm design and software implementation.
- Using ROS for the framework, motion planning of the arm and Arduino for PID control of the joints.
- Modular actuator and robotic arm design for a 4 DOF robotic arm with 1 kg payload and 1 meter reach.
- Documenting and managing on the development of the robotic arm as an Open Source project.

Systems Integration Engineer:: Wilco Machine & Mold

Sept 2014 - Dec 2014

- Design and implementation of an automated temperature control system using Unitronics PLC.
- Experience with a variety of machining tools such as a CNC mill and lathe.
- High precision part design for sealing plate and vacuum chambers using Solidworks.

Software Engineer:: Polar

Jan 2014 - April 2014

- Small feature implementations and bug fixes using Python mainly.
- Development of an IRC bot for a more efficient development cycle.

Projects and Activities

Open Source Modular Robotic Arm Project :: Mechatronics

Affordable/Functional/Open Source

- Open source project to create a functional and affordable robotic platform.
- Continuation of the robotics research and development from MakeLab.
- Small team of engineering students working closely with the client and the UW robotics team.
- Completing the minimum viable product for the Robotic Arm Project and releasing to the public.
- Goal of \$2500 for anyone to build the robotic arm from anywhere.

3D Printer Design and Build :: Mechanical

Affordable/Customizable/Accurate

- Fused deposition modeling 3D printer design and build. Inspired by the Ultimaker design.
- 3D printer model designed in Solidworks, and manufactured through 3D printing and laser cutting.
- Documenting CAD, BOM, Software and tutorials.

Education

University of Waterloo B.A.Sc., Mechatronics Engineering – Class of 2018 – 2B Academic Term