



## Objective

My passion is in the field of Robotics and I am taking the initiative to create an open source robotic arm platform using 3D printing and the Robot Operating System.

## Skills Summary

C++	ROS	Git	Arduino
Python	RViz/Gazebo	Machining	PLC
MATLAB	Ubuntu Linux	Solidworks	Raspberry Pi

## Work Experience

### Robotics Research and Development Engineer :: MakeLab

May 2015 – Aug 2015

- Leading the research and development of a light weight robotic arm design and software implementation.
- Using ROS for the framework, motion planning of the arm and Arduino for PID control of the joints.
- Modular actuator and robotic arm design for a 4 DOF robotic arm with 1 kg payload and 1 meter reach.
- Documenting and managing on the development of the robotic arm as an Open Source project.

### Systems Integration Engineer :: Wilco Machine & Mold

Sept 2014 – Dec 2014

- Design and implementation of an automated temperature control system using Unitronics PLC.
- Experience with a variety of machining tools such as a CNC mill and lathe.
- High precision part design for sealing plate and vacuum chambers using Solidworks.

### Software Engineer :: Polar

Jan 2014 – April 2014

- Small feature implementations and bug fixes using Python mainly.
- Development of an IRC bot for a more efficient development cycle.

## Projects and Activities

### Open Source Modular Robotic Arm Project :: Mechatronics

Affordable/Functional/Open Source

- Open source project to create a functional and affordable robotic platform.
- Continuation of the robotics research and development from MakeLab.
- Small team of engineering students working closely with the client and the UW robotics team.
- Completing the minimum viable product for the Robotic Arm Project and releasing to the public.
- Goal of \$2500 for anyone to build the robotic arm from anywhere.

### 3D Printer Design and Build :: Mechanical

Affordable/Customizable/Accurate

- Fused deposition modeling 3D printer design and build. Inspired by the Ultimaker design.
- 3D printer model designed in Solidworks, and manufactured through 3D printing and laser cutting.
- Documenting CAD, BOM, Software and tutorials.

## Education

University of Waterloo B.A.Sc., Mechatronics Engineering – Class of 2018 – 2B Academic Term