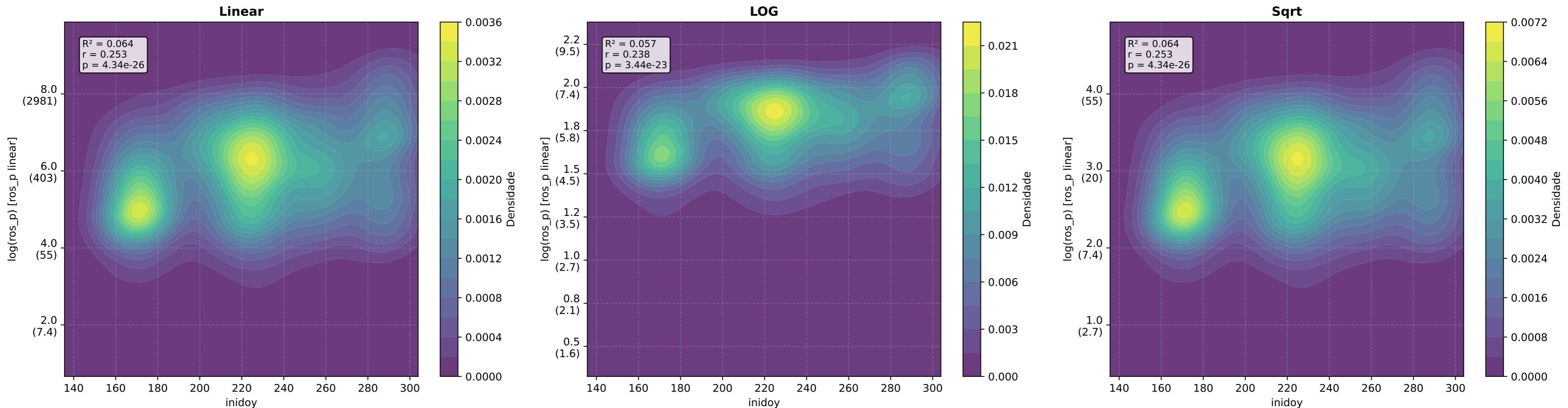
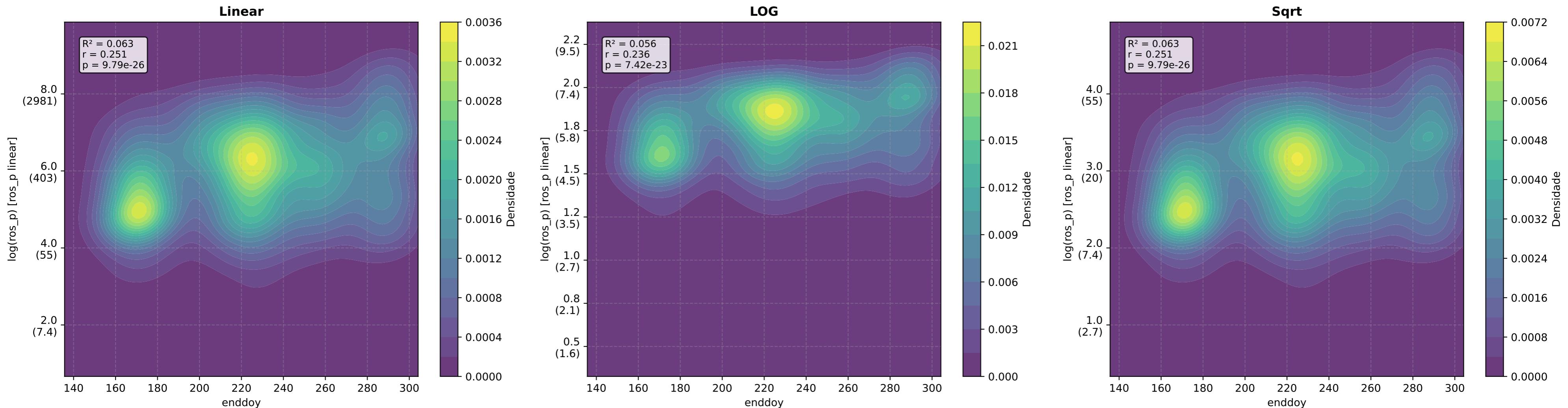


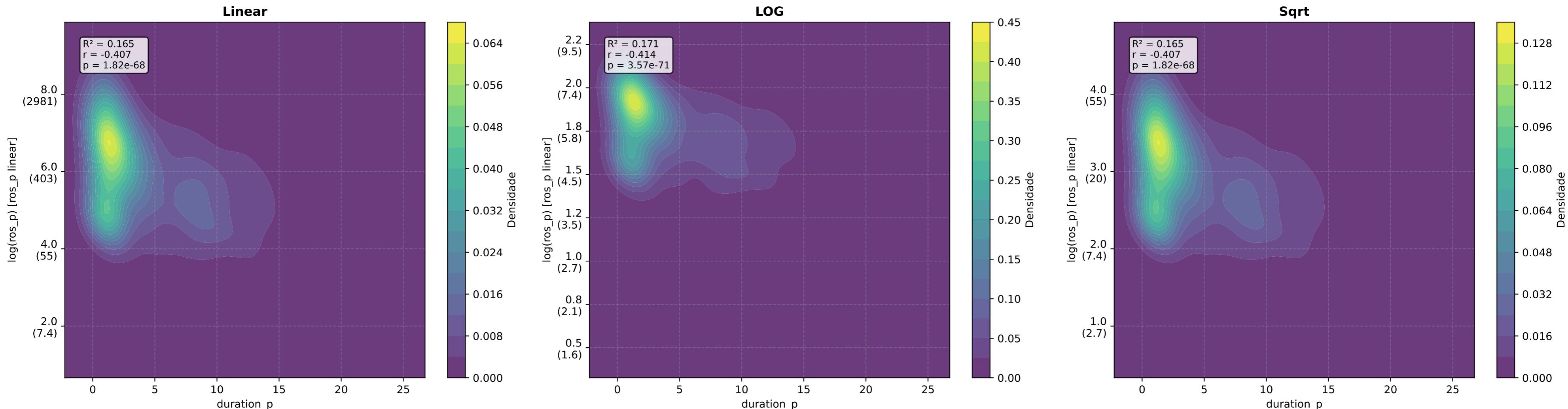
inidoy vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



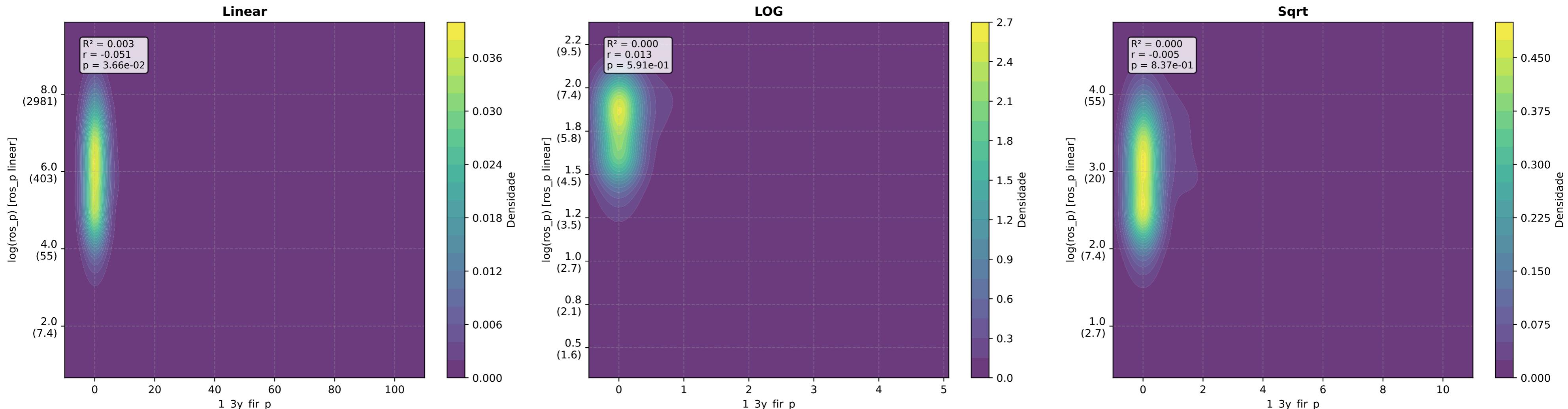
enddoy vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



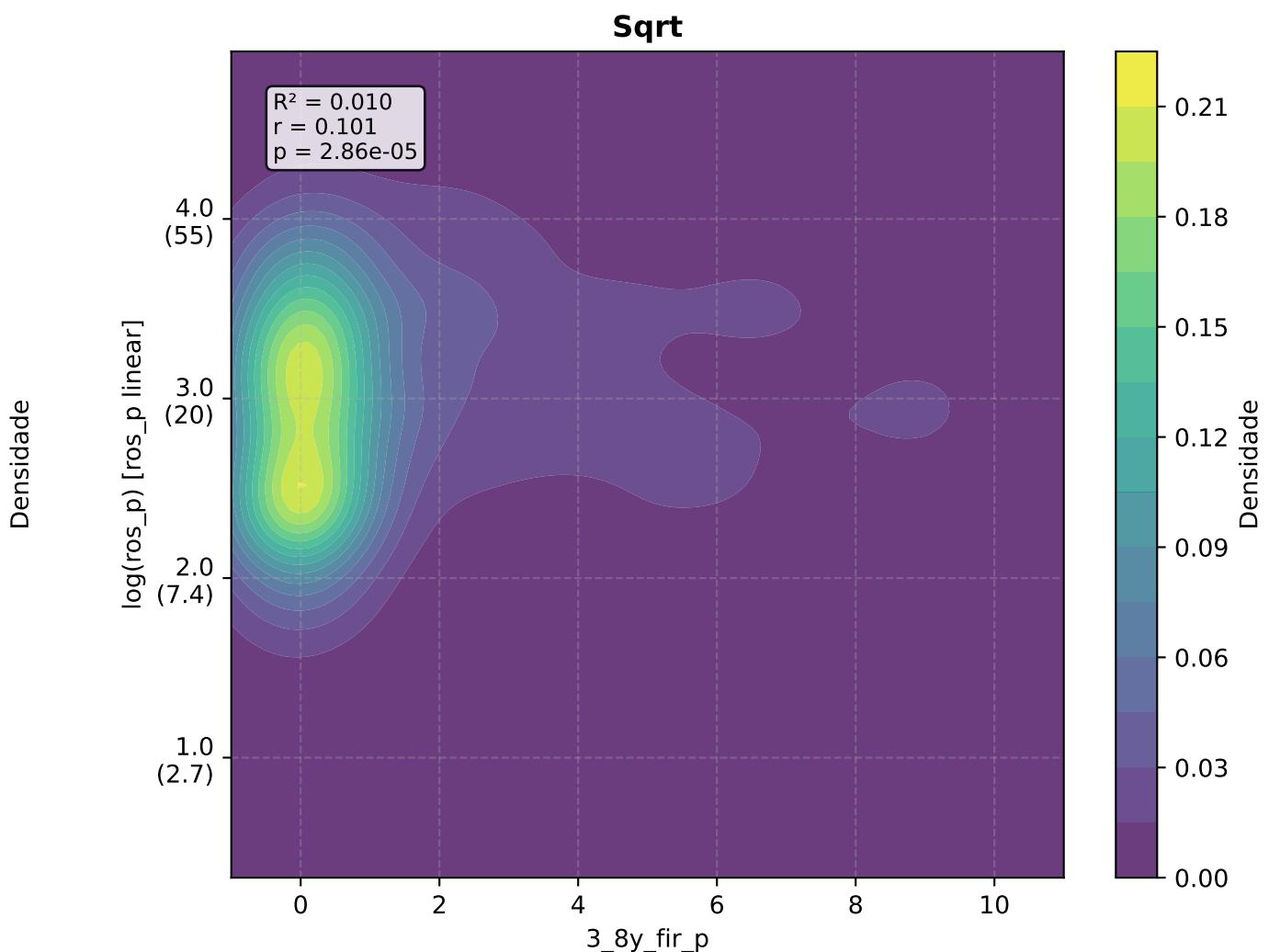
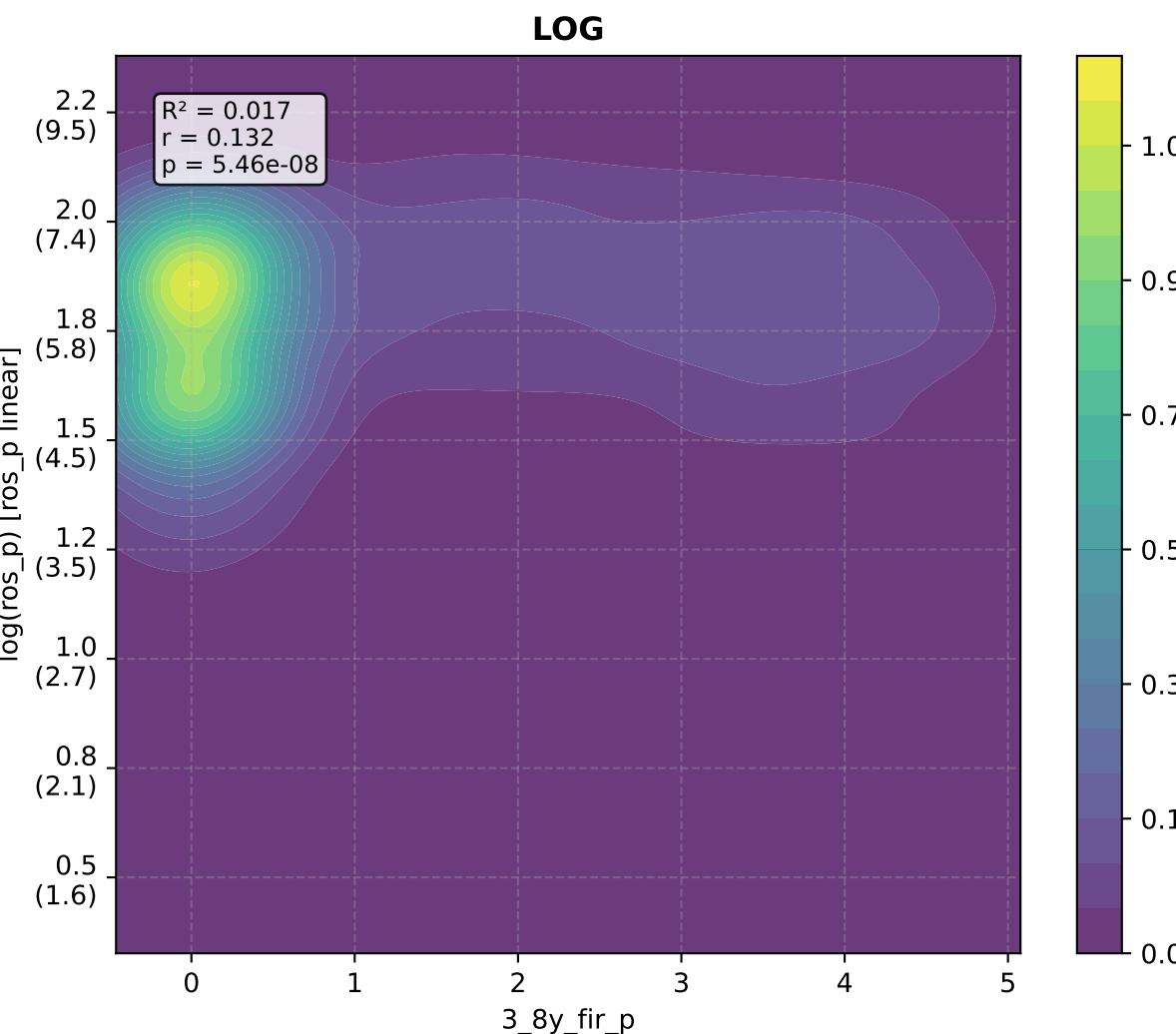
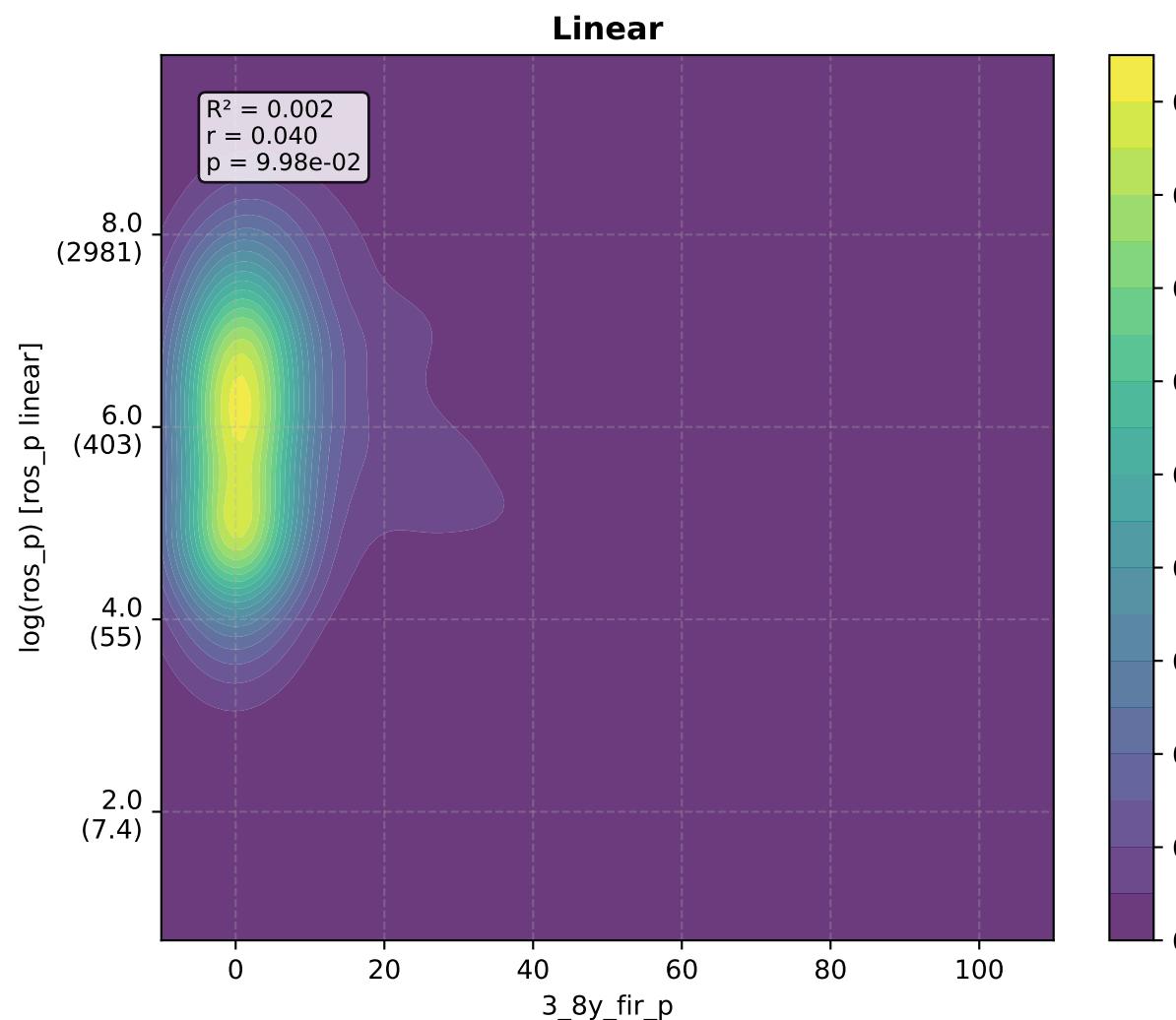
duration_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



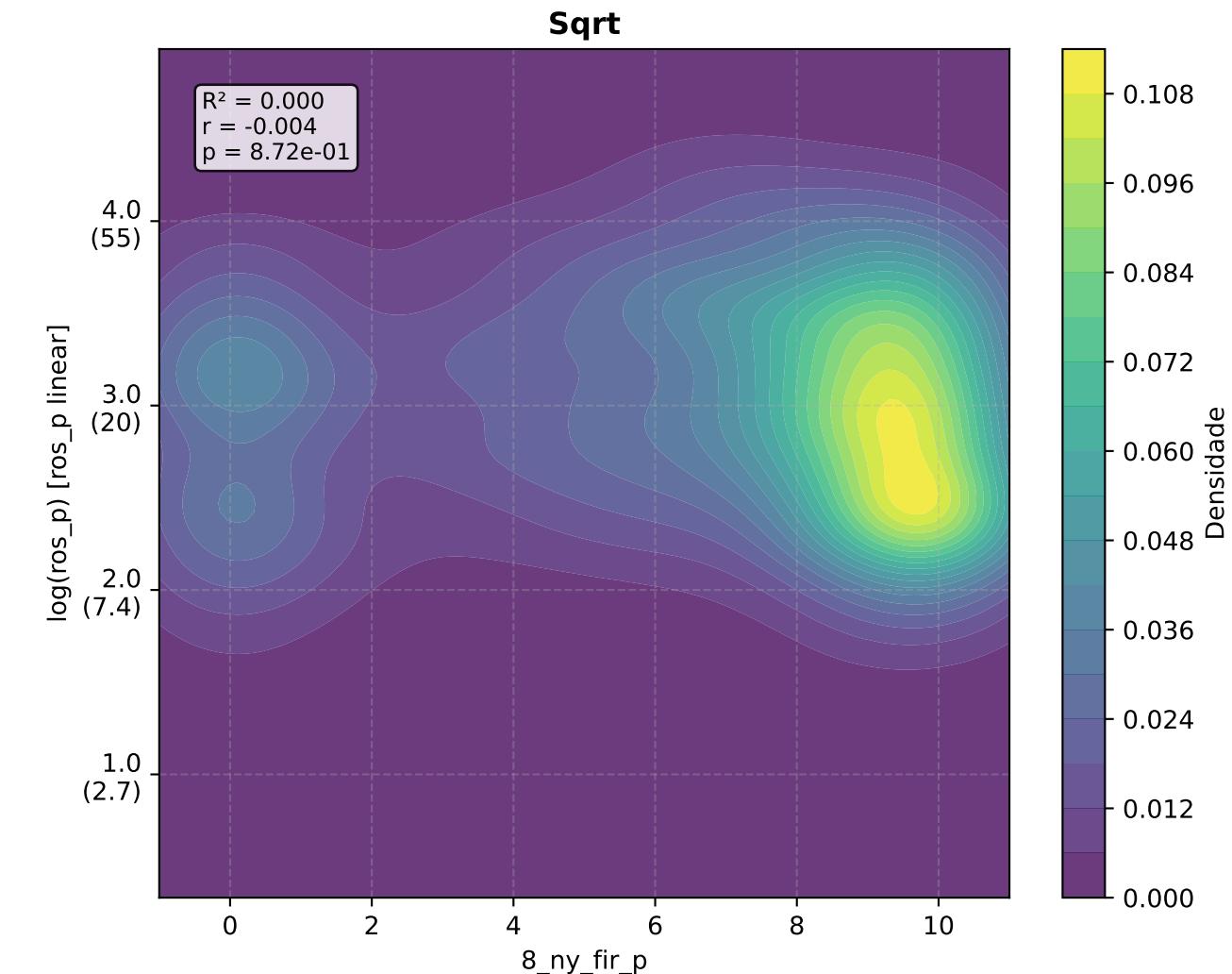
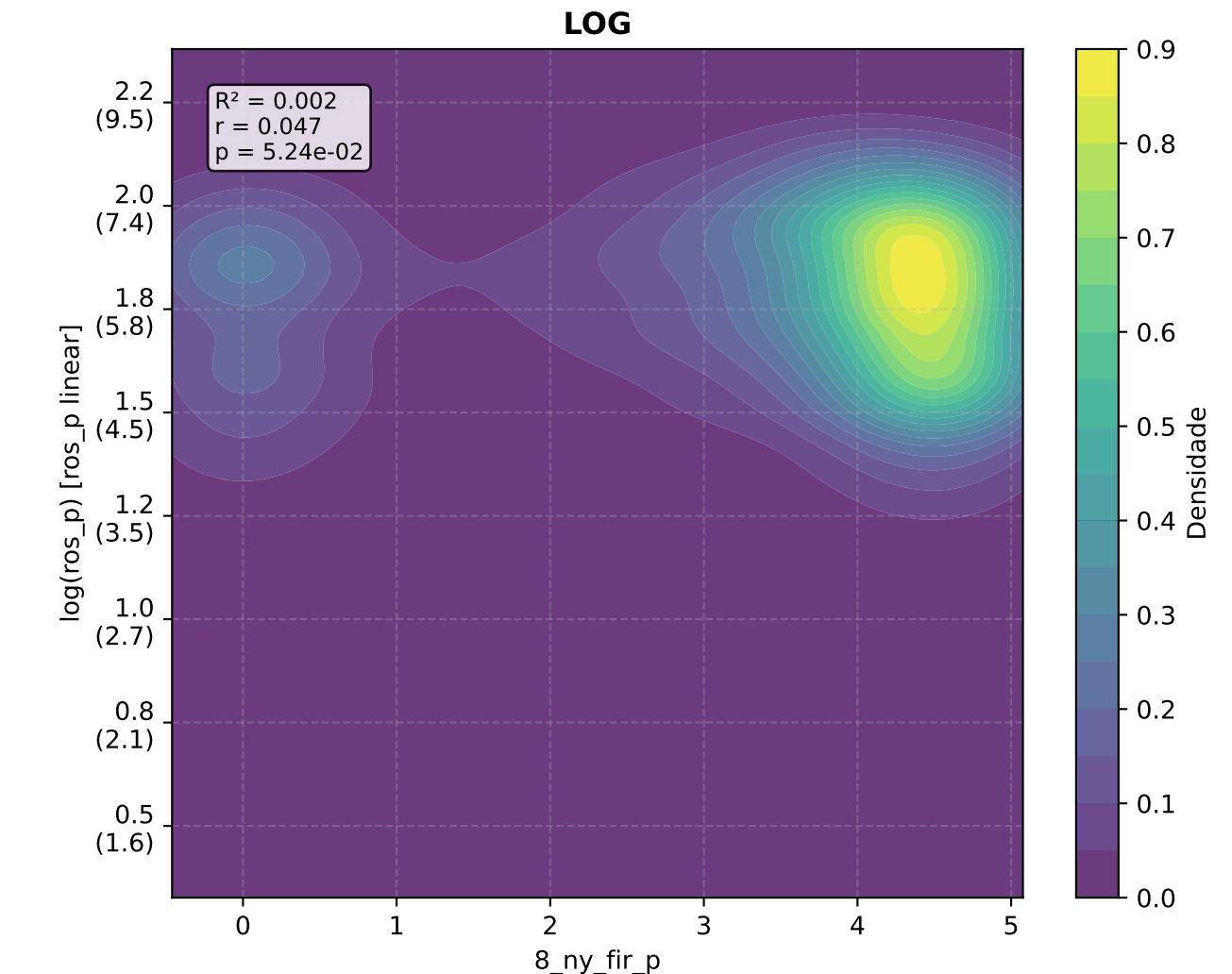
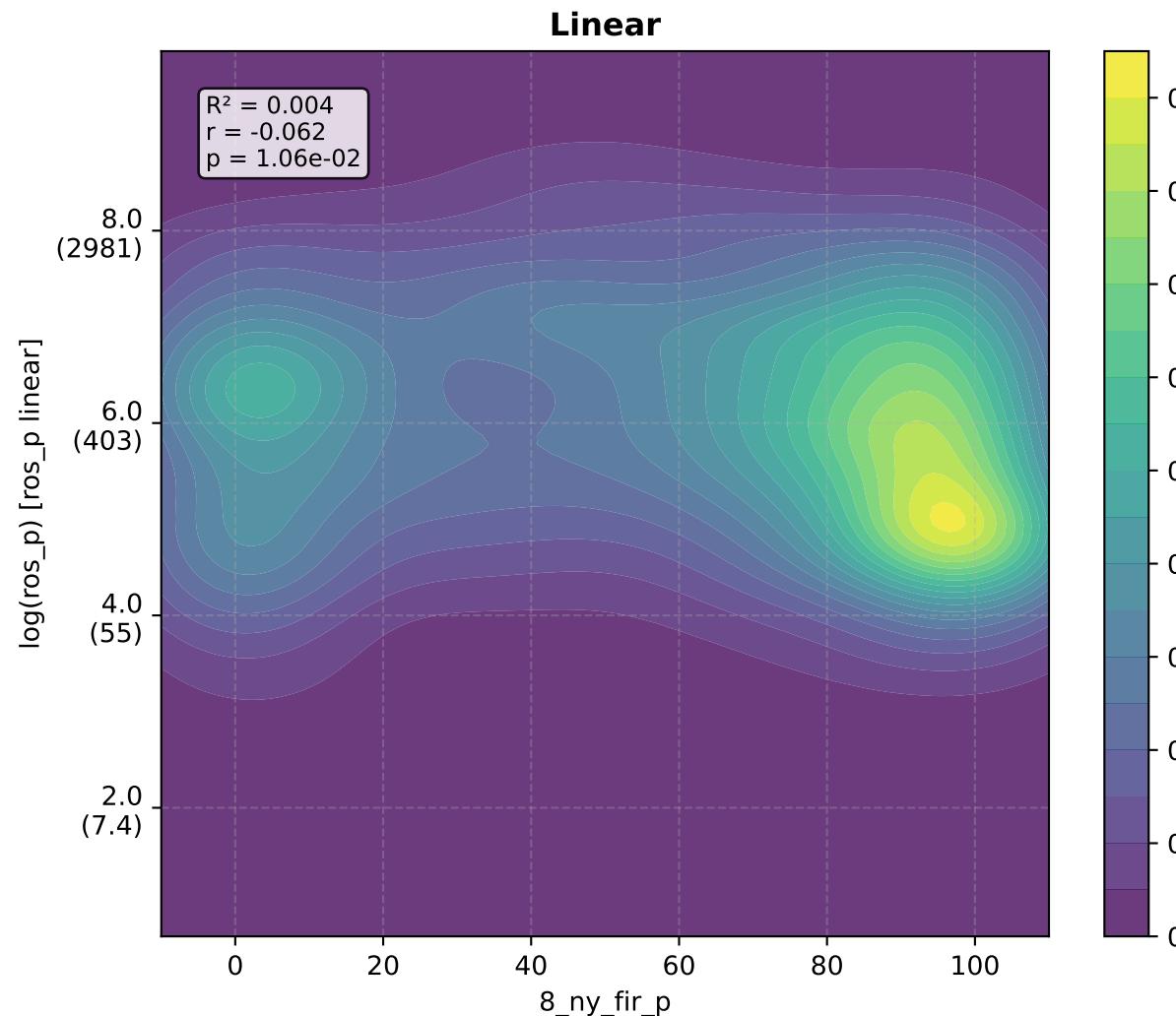
1_3y_fir_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



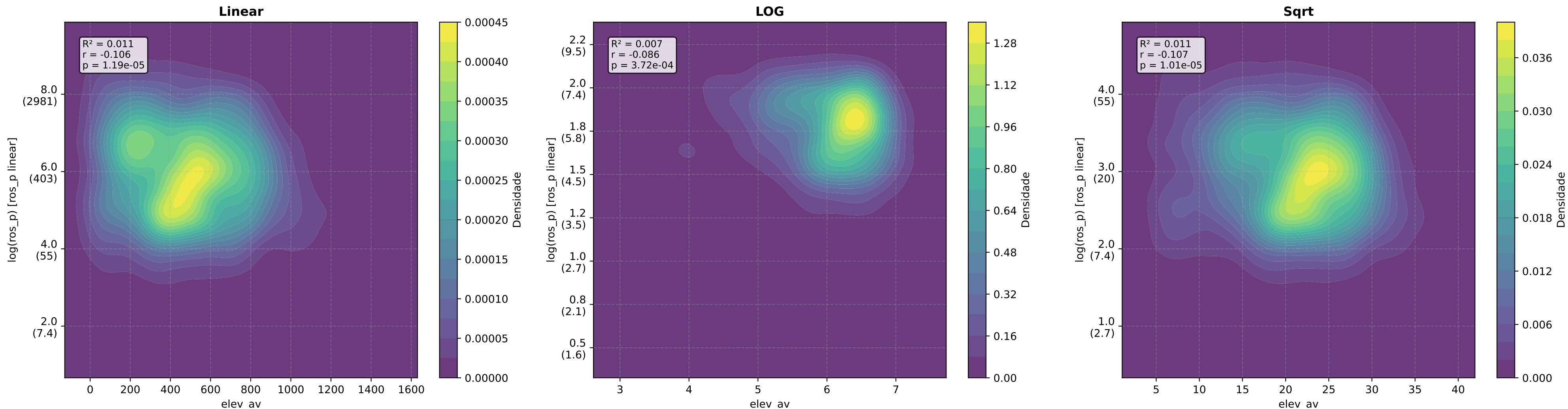
3_8y_fir_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



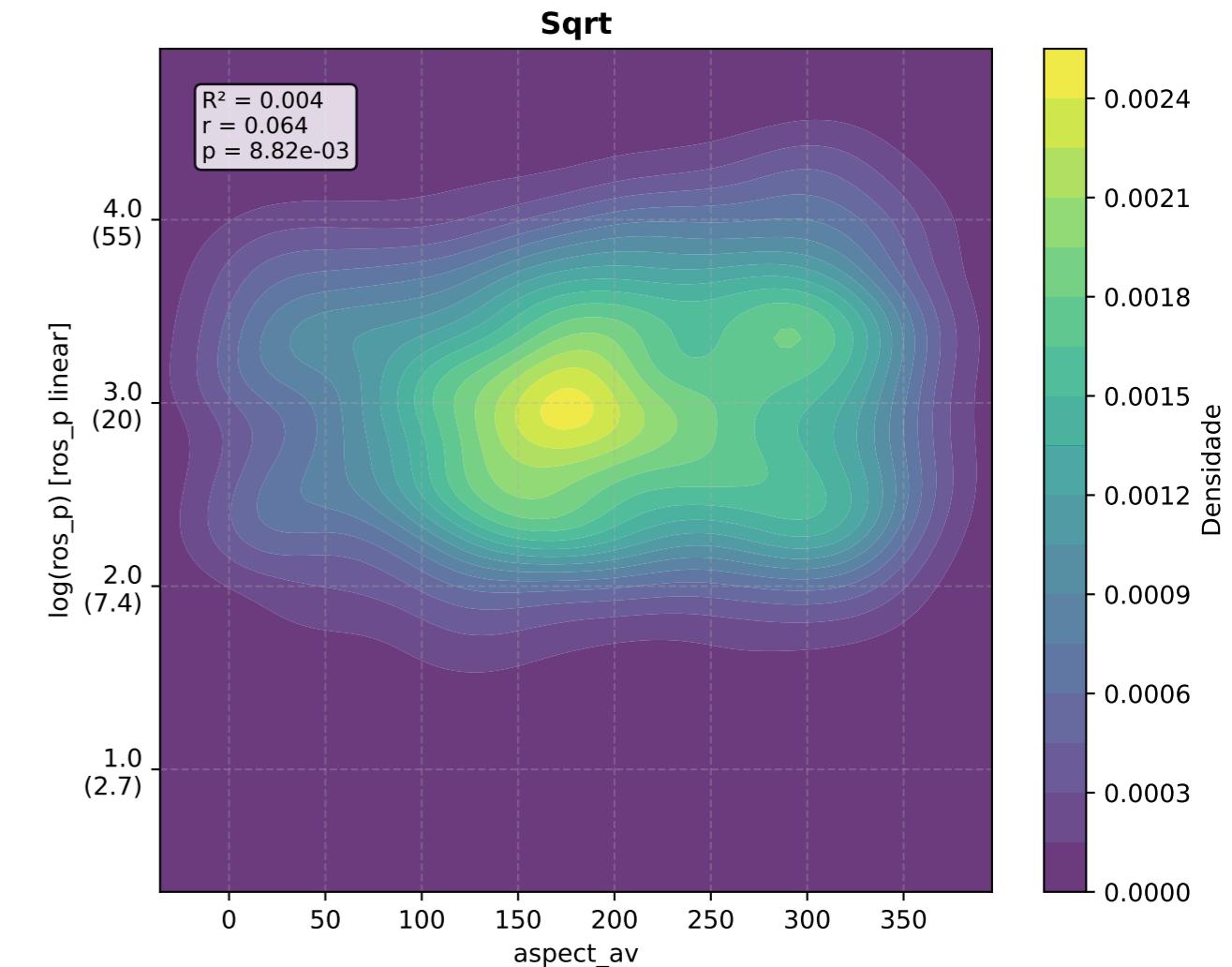
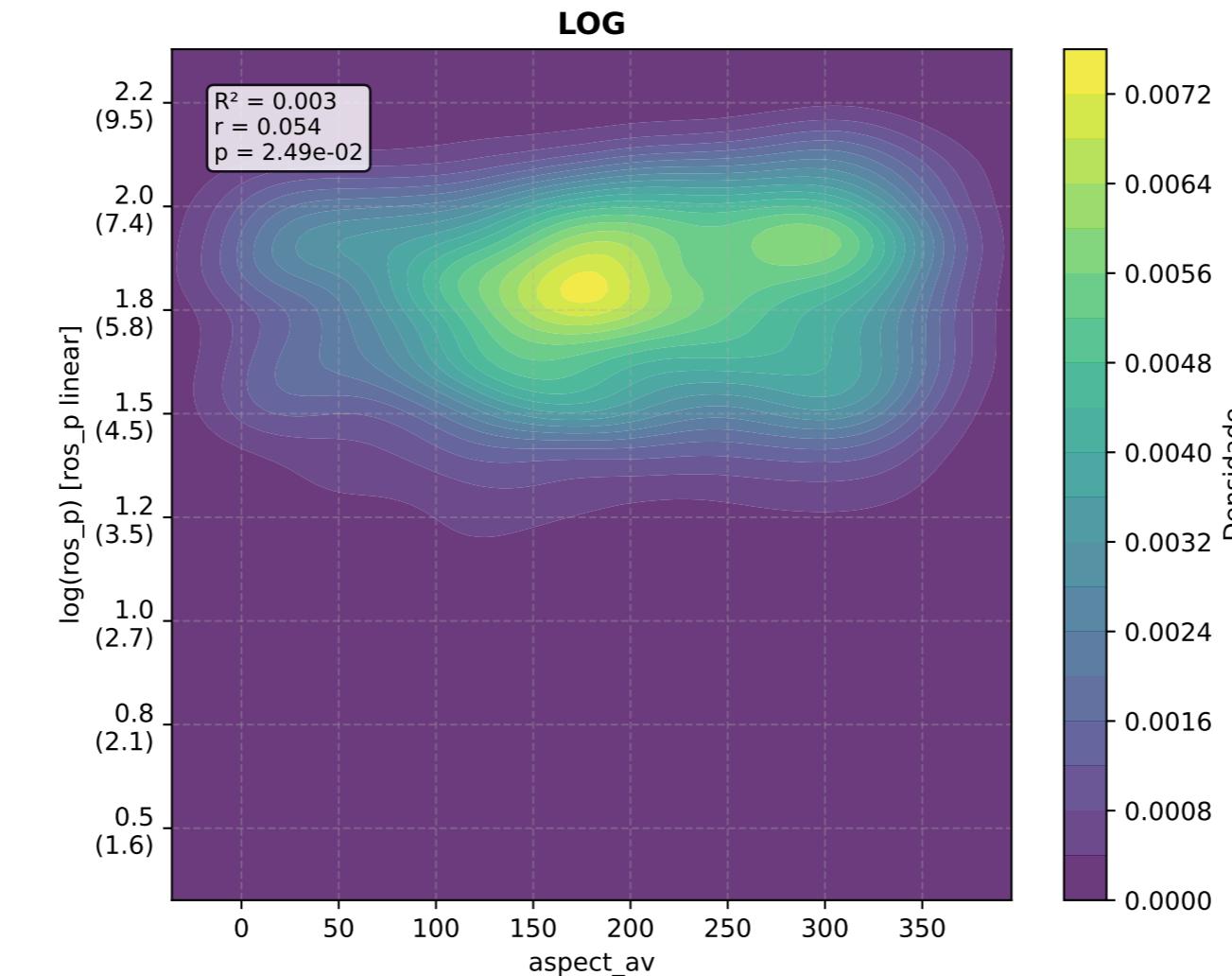
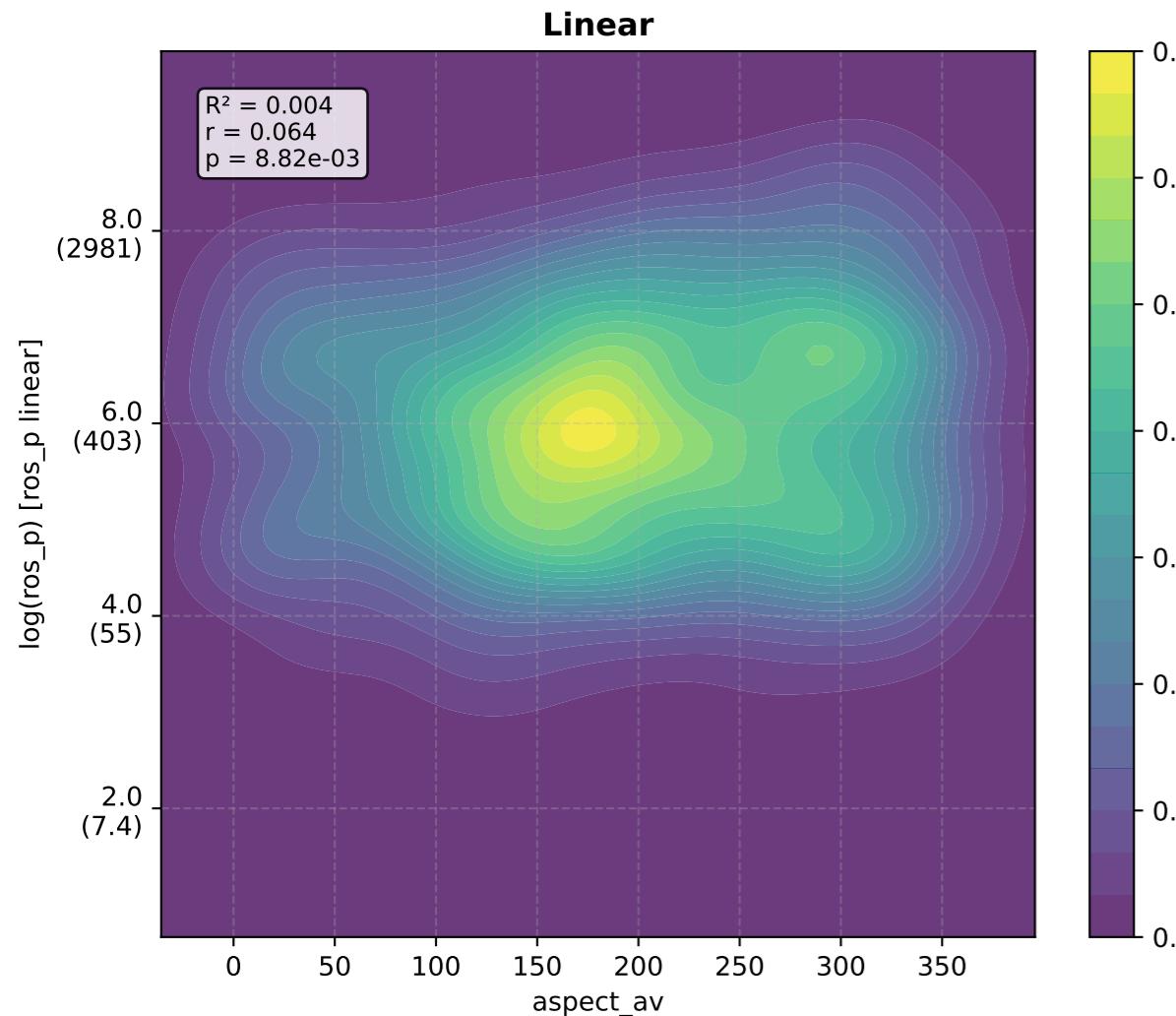
8_ny_fir_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



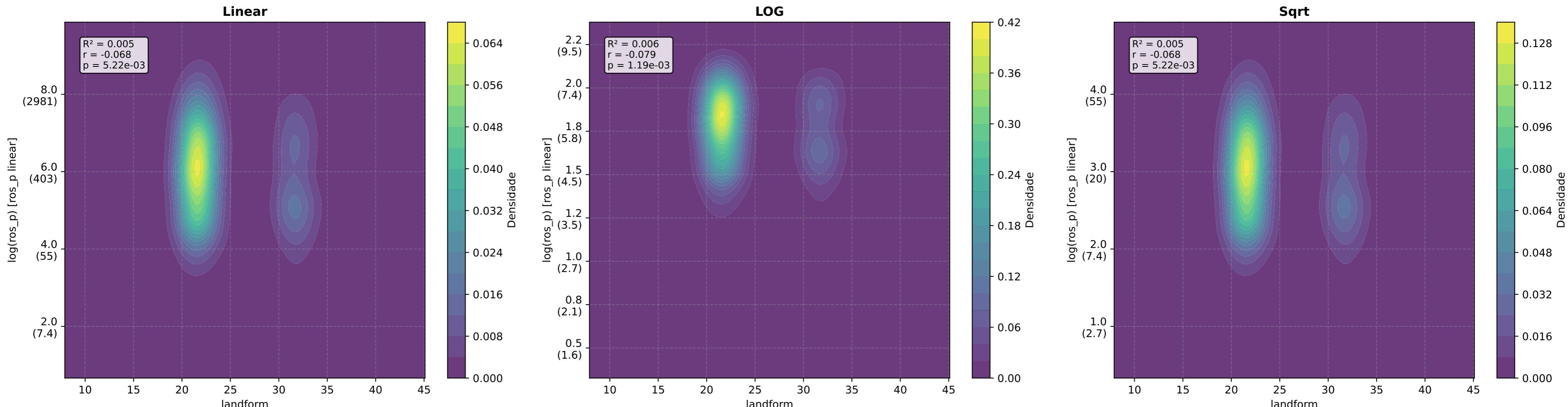
elev_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



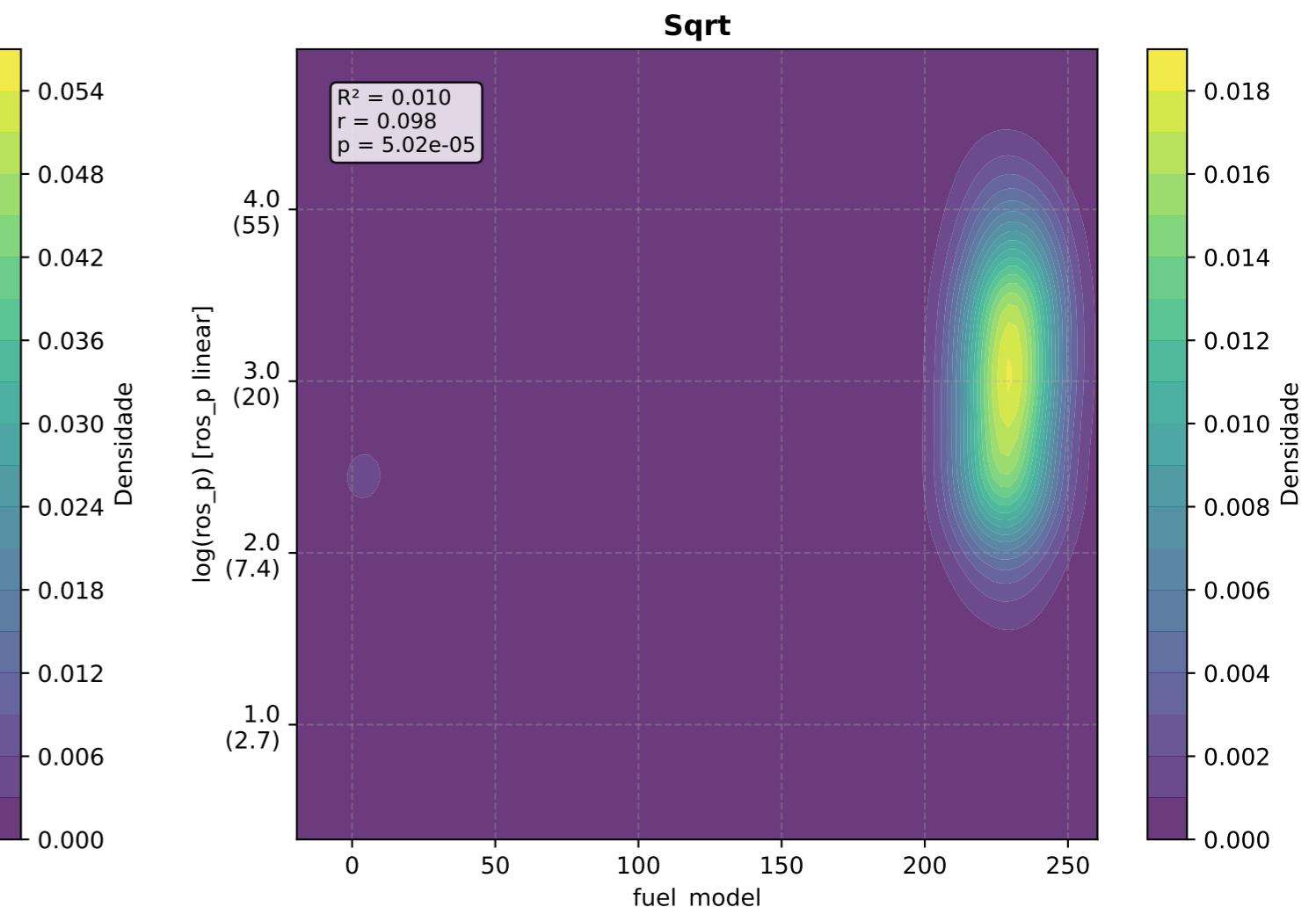
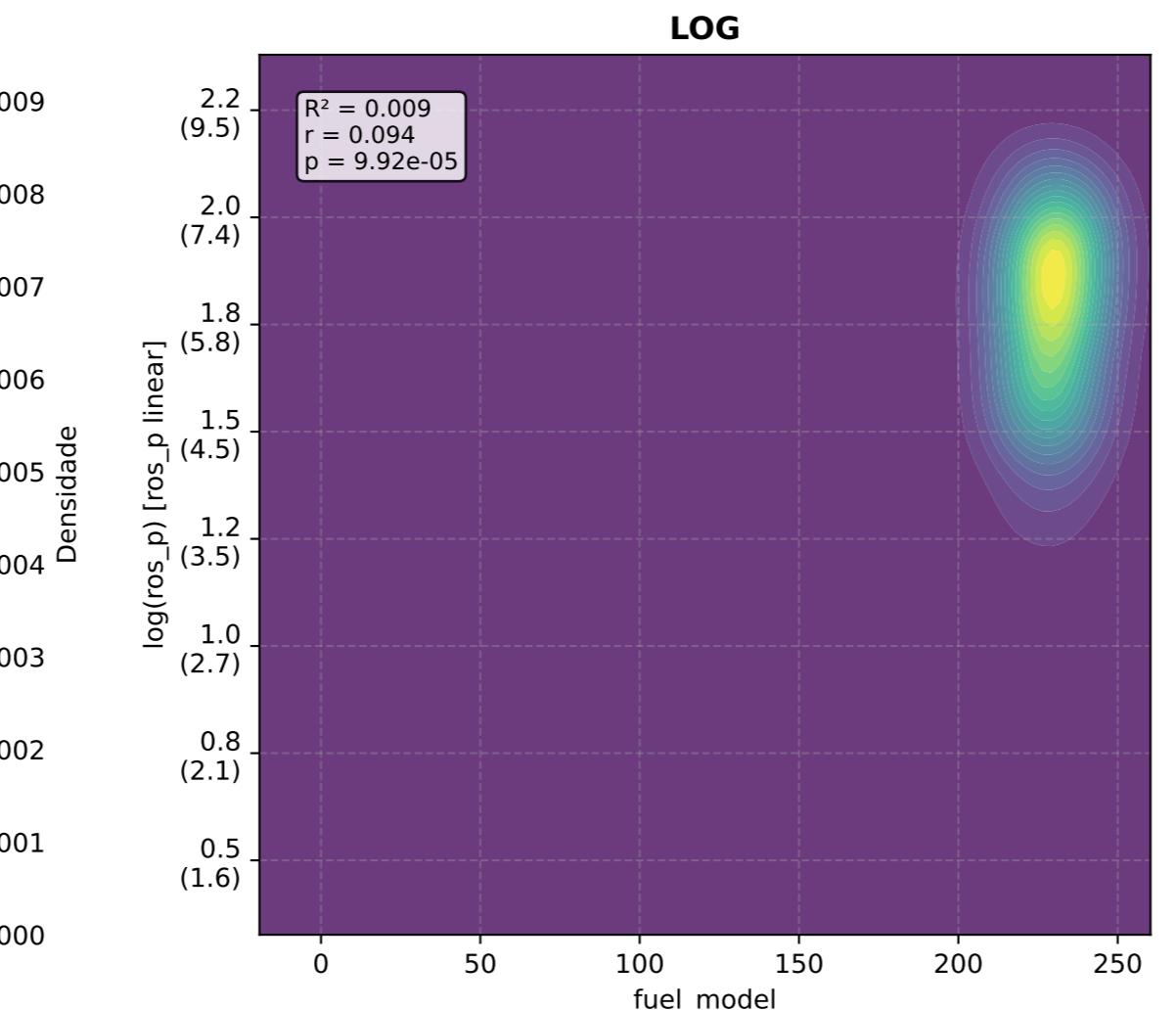
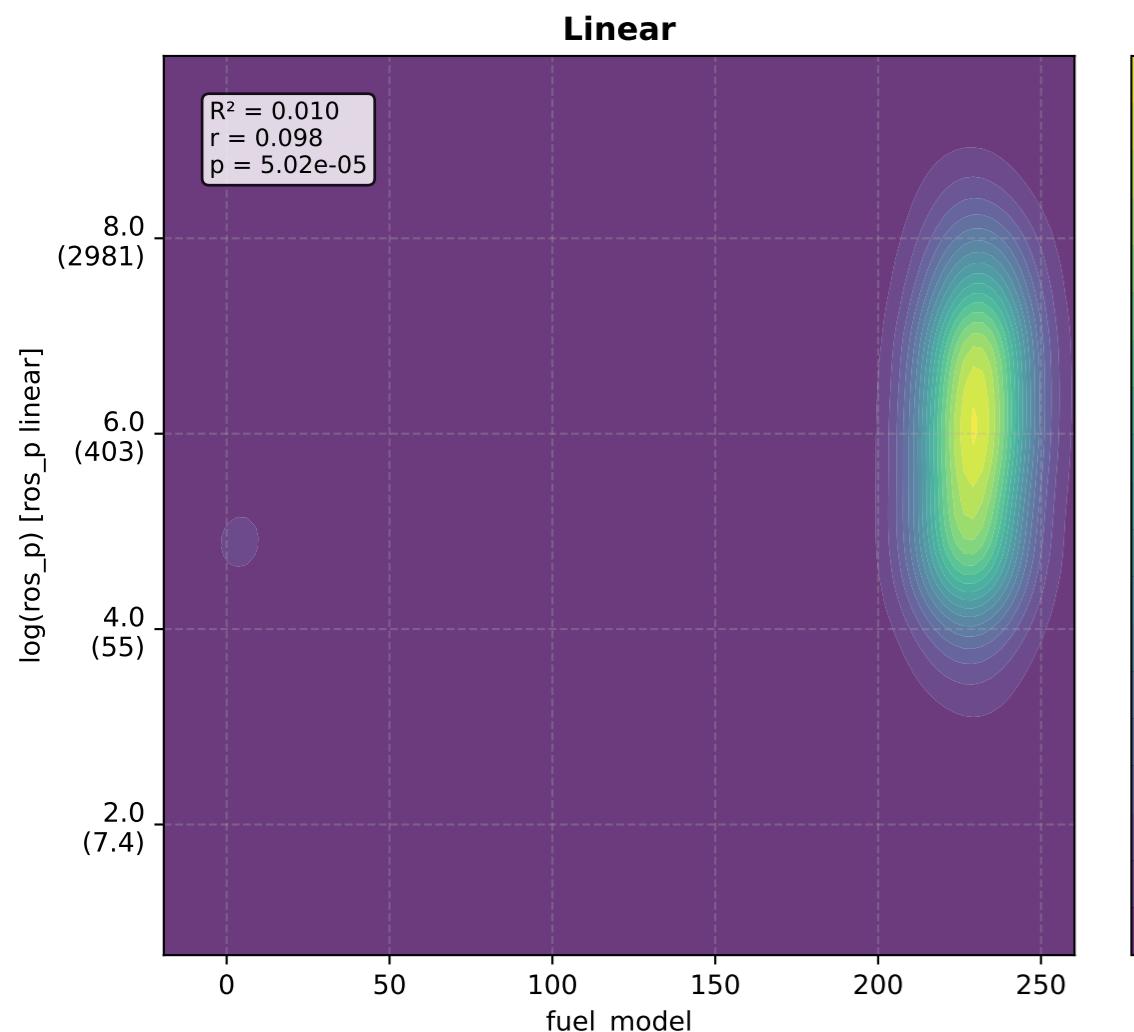
aspect_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



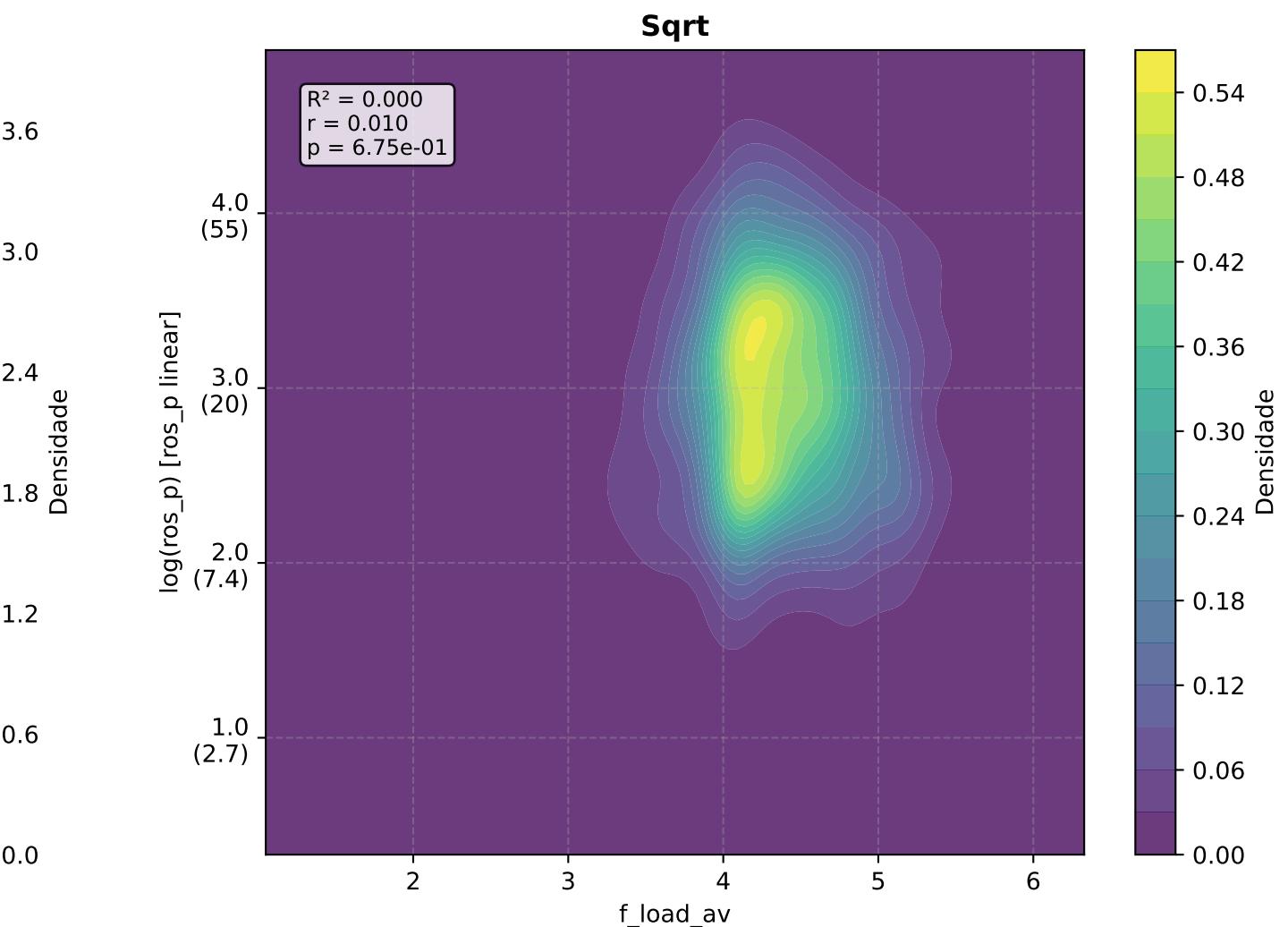
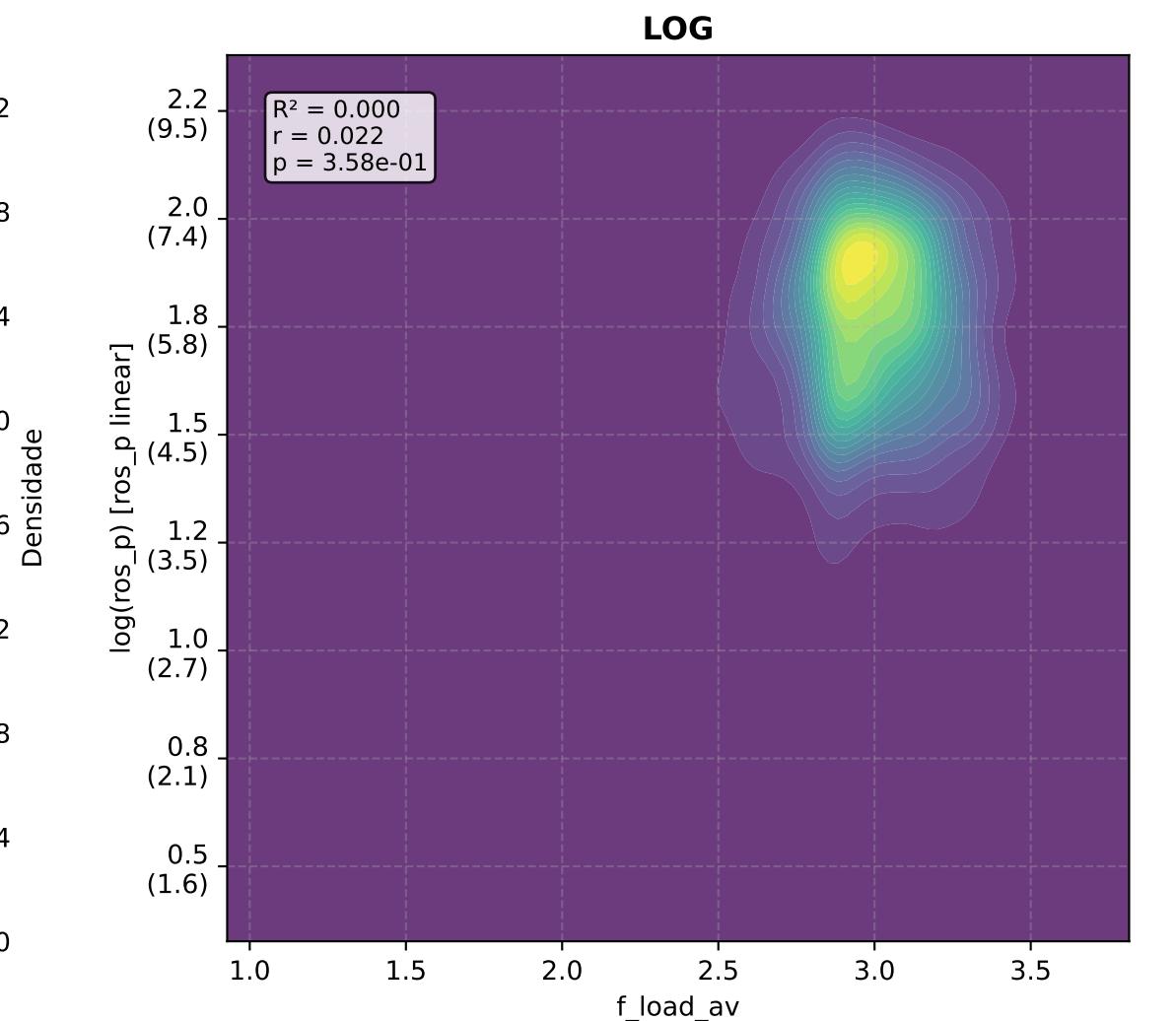
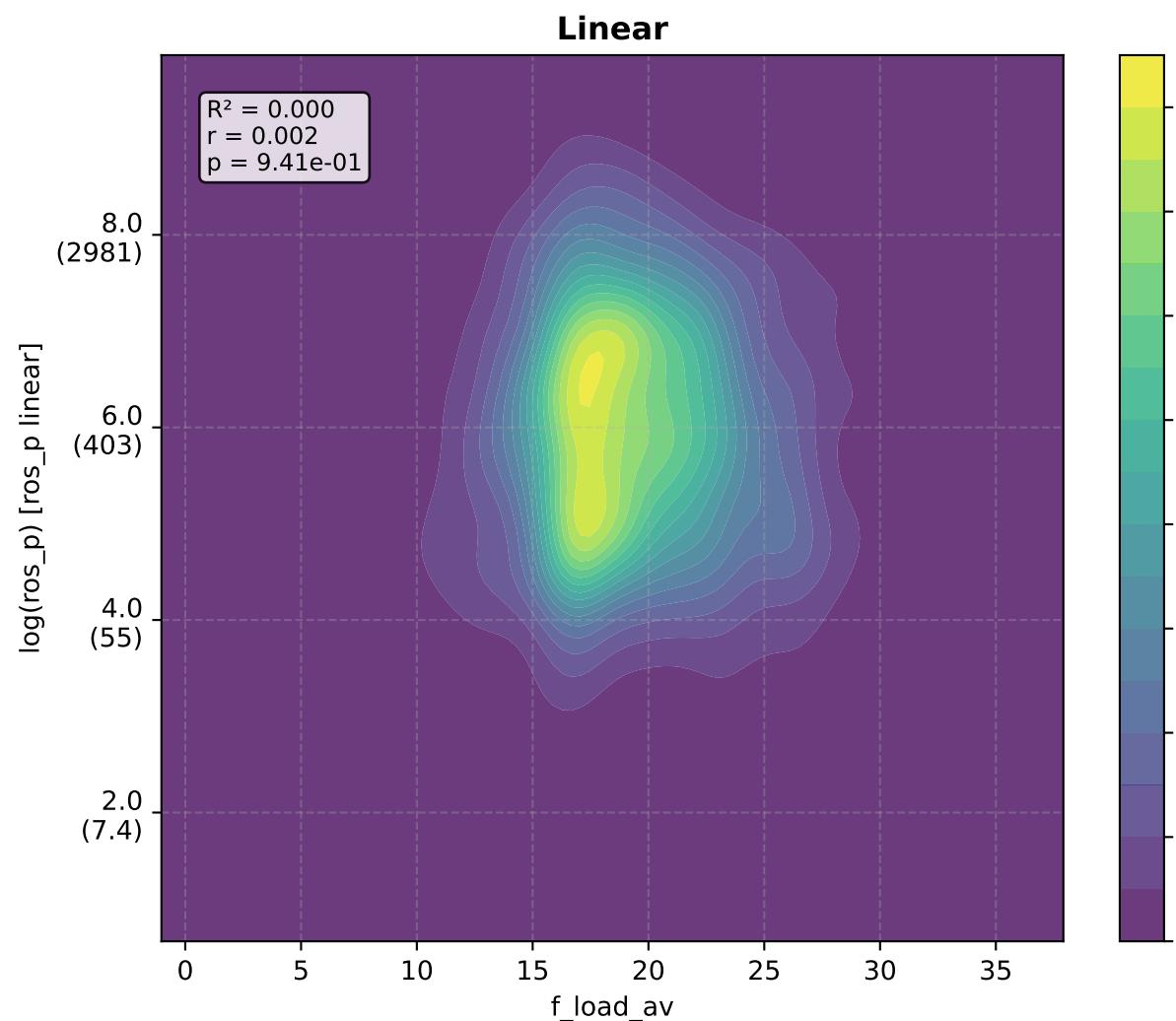
landform vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



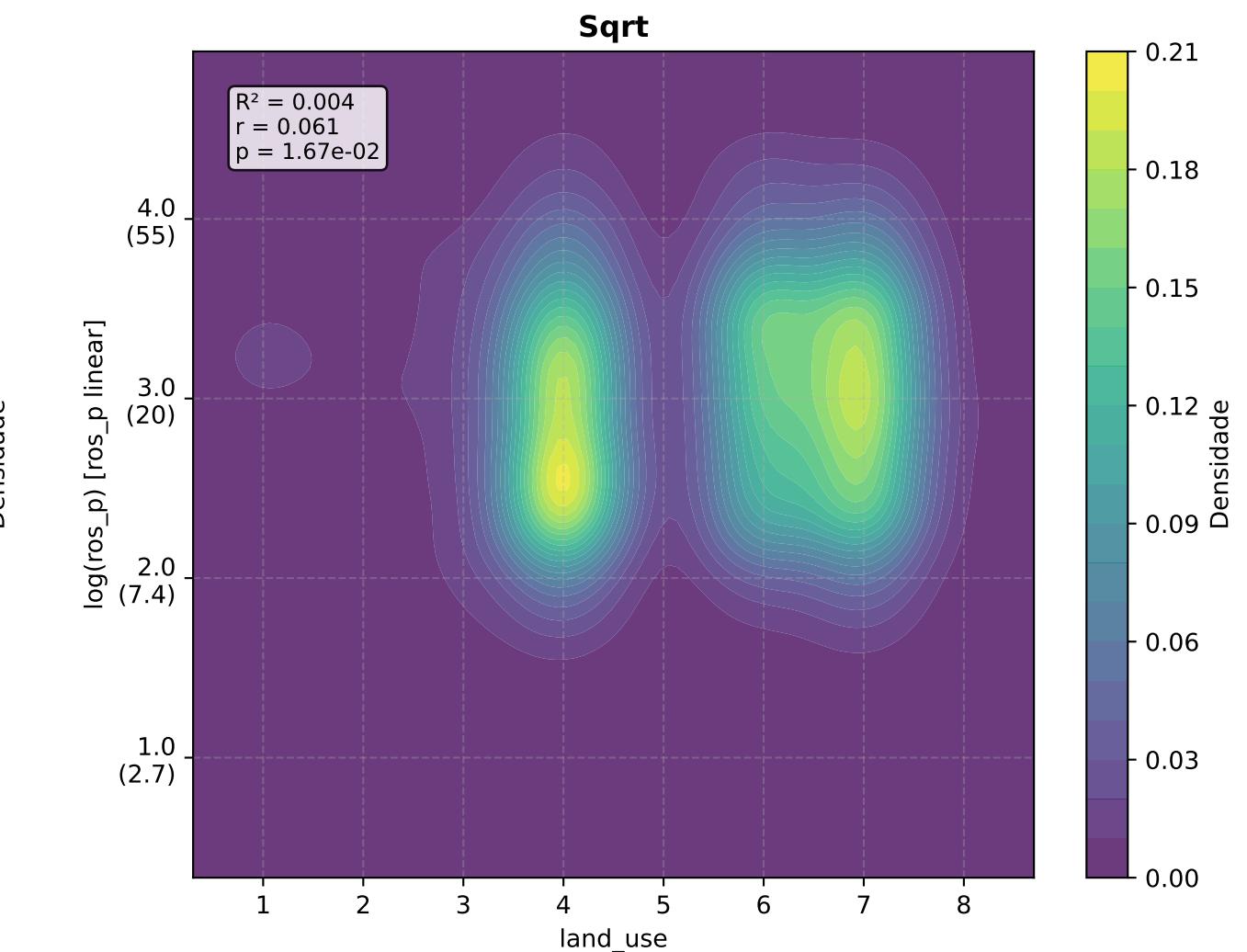
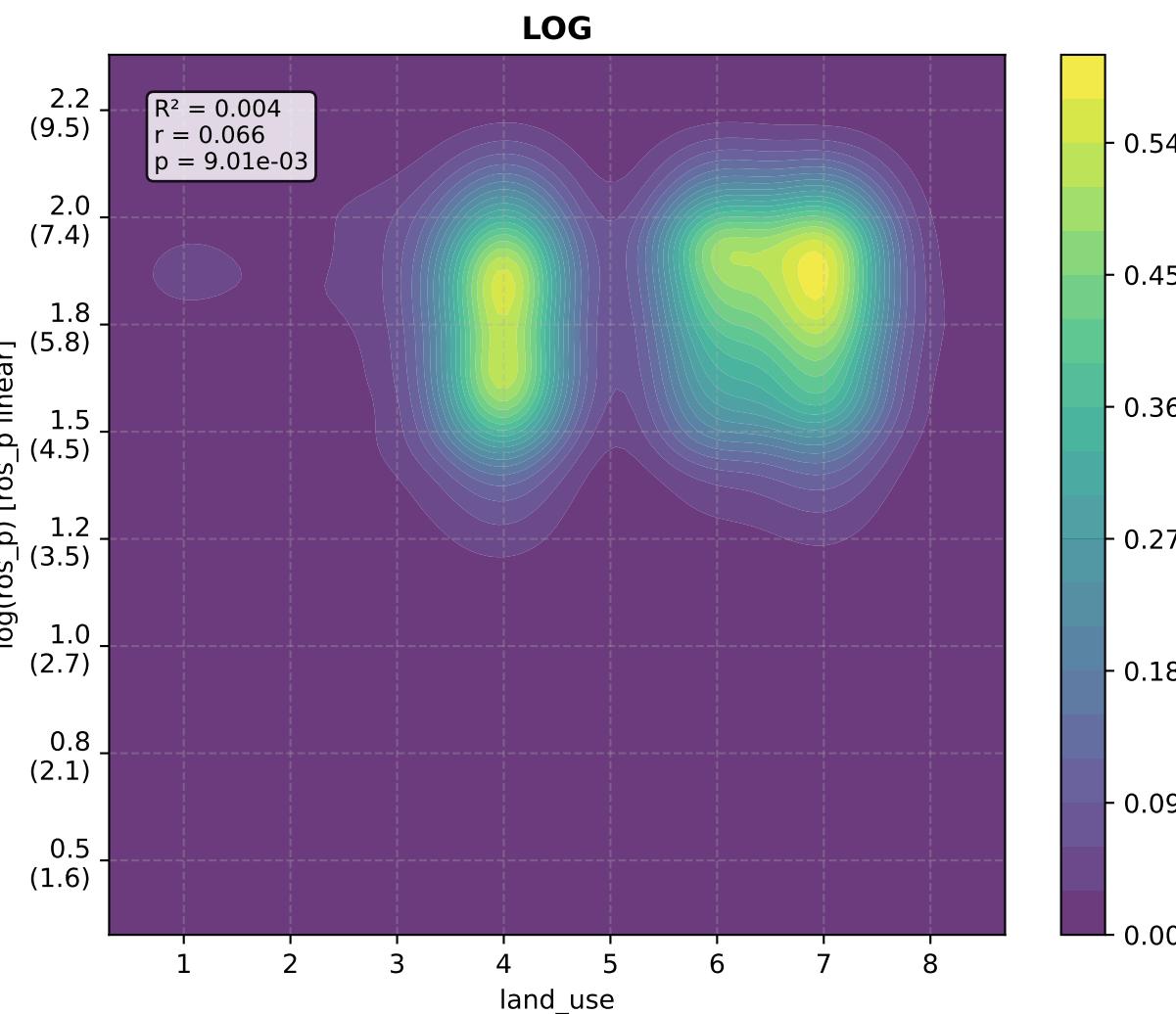
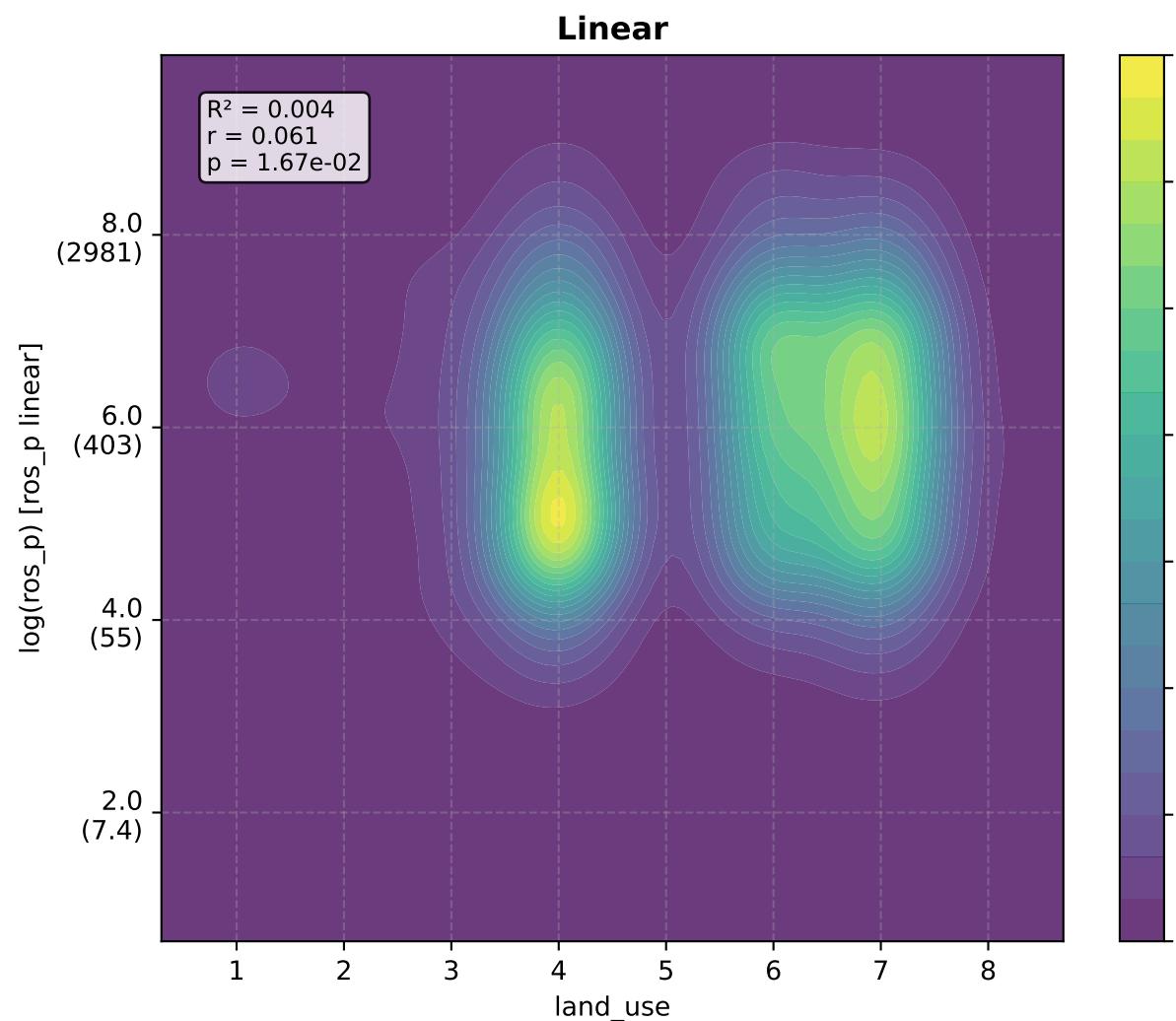
fuel_model vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



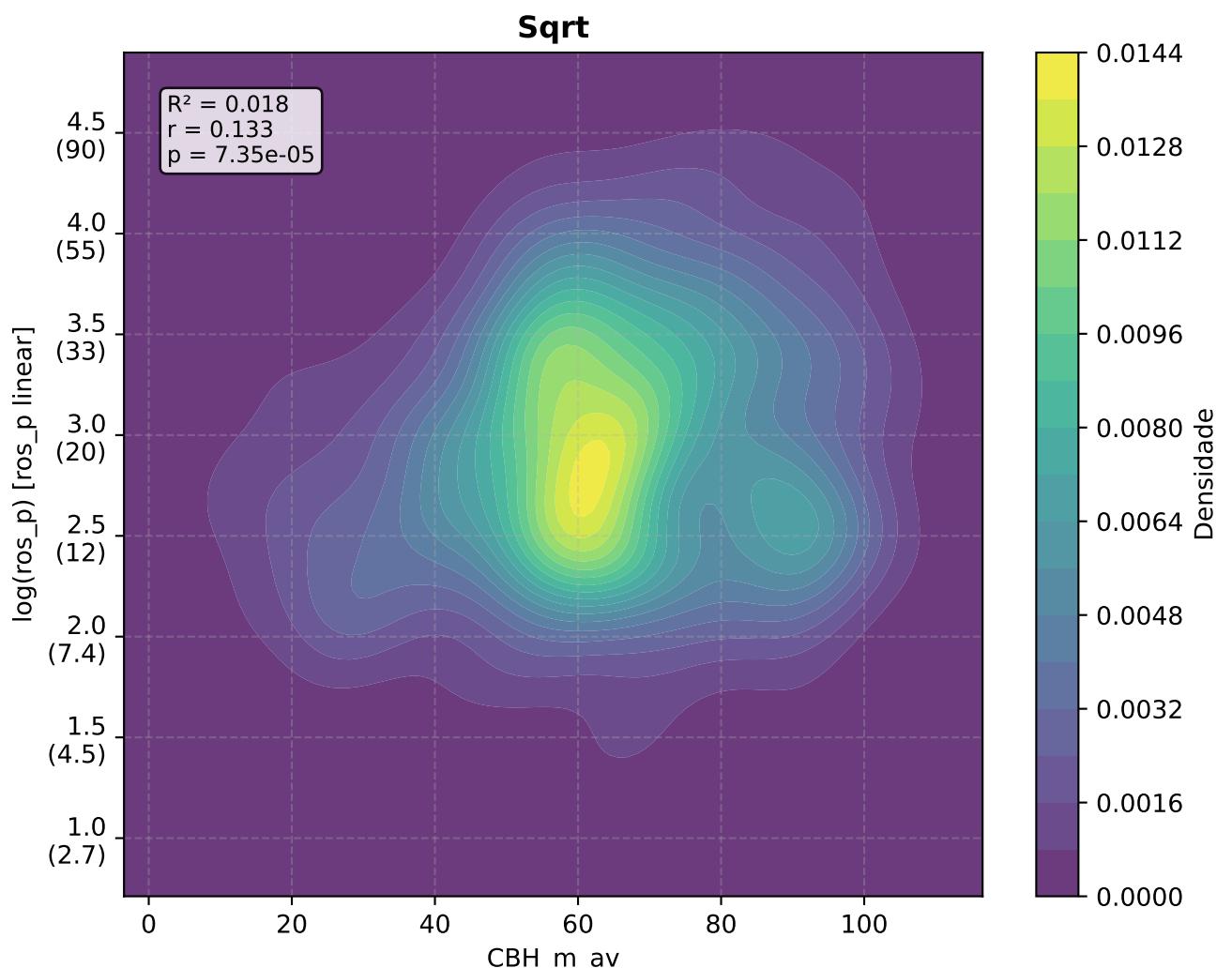
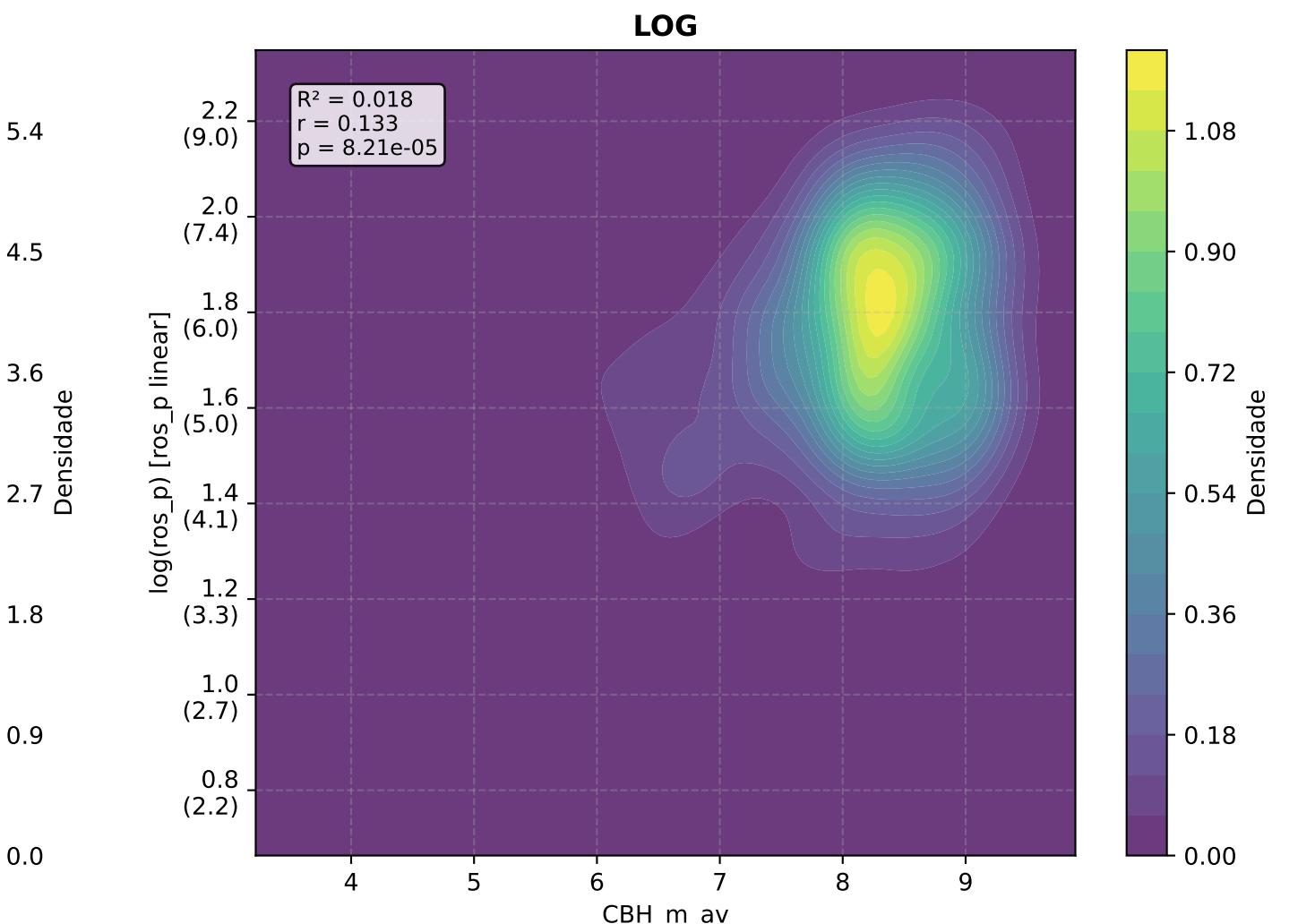
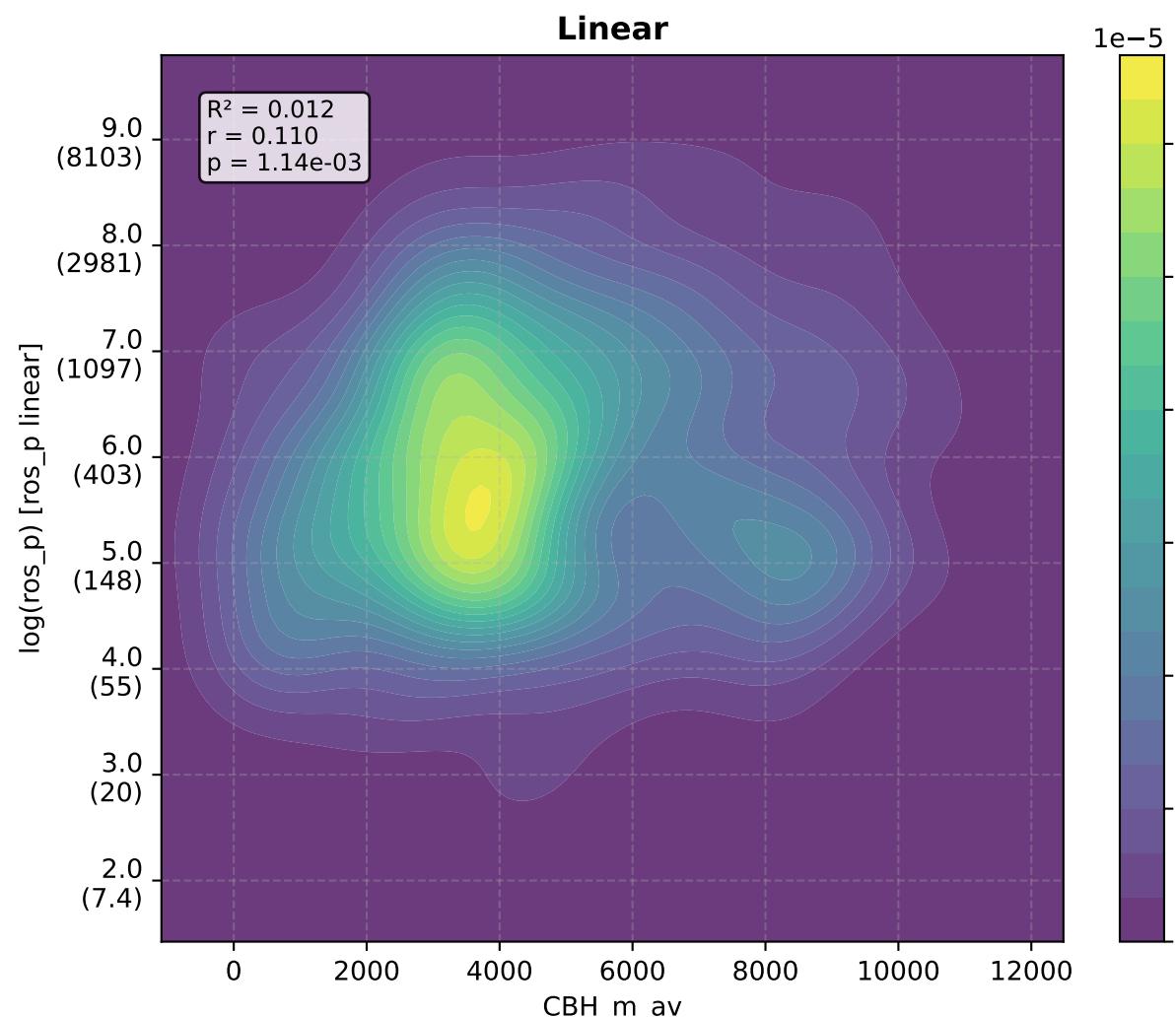
f_load_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



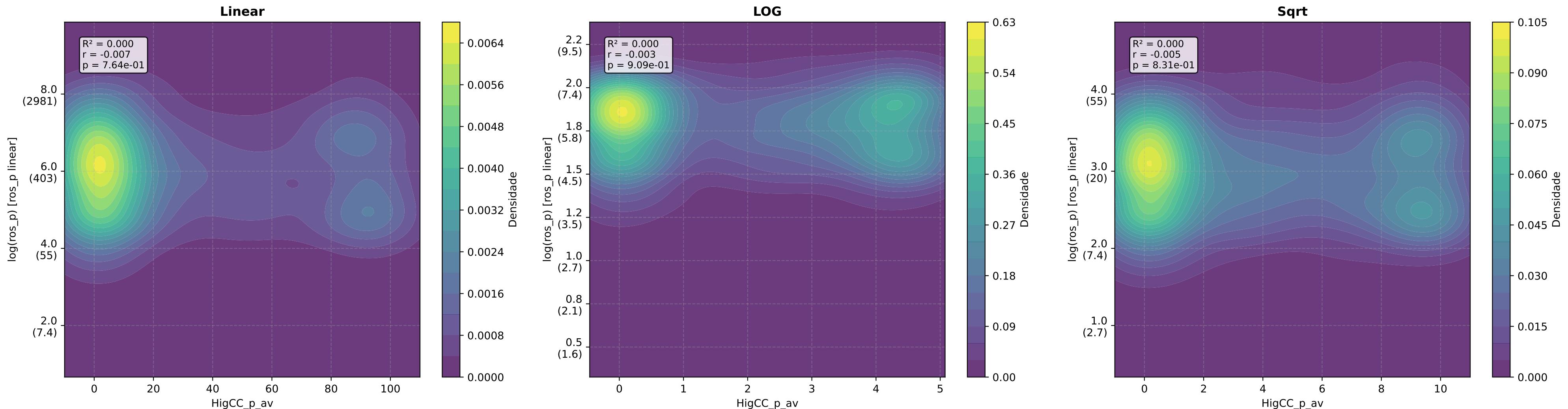
land_use vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



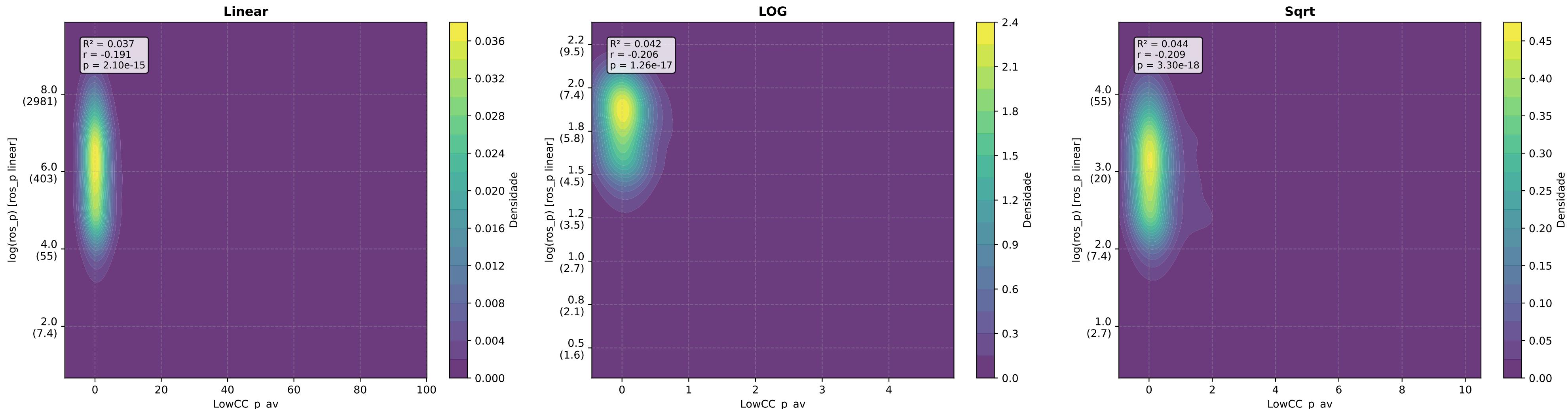
CBH_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



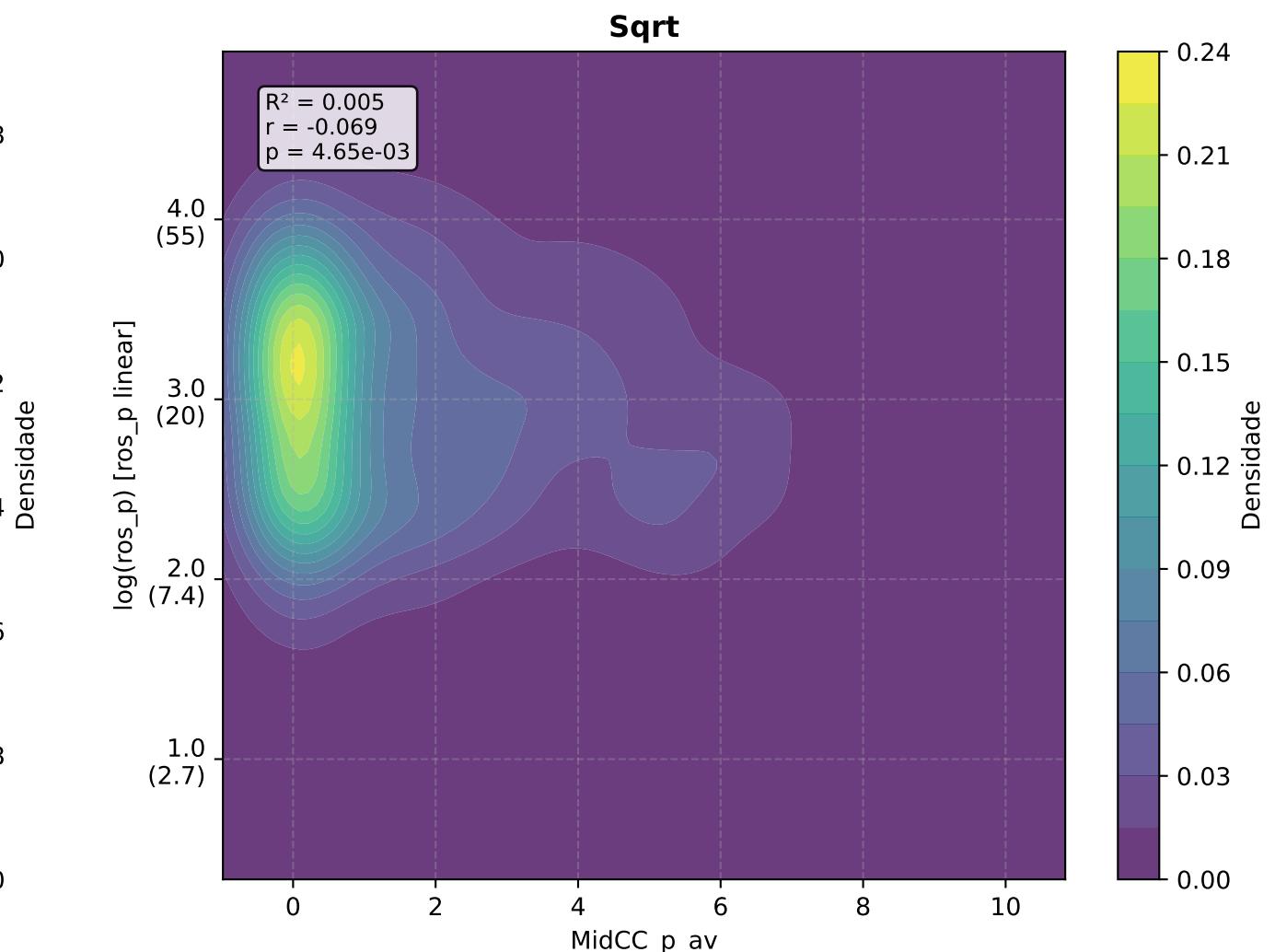
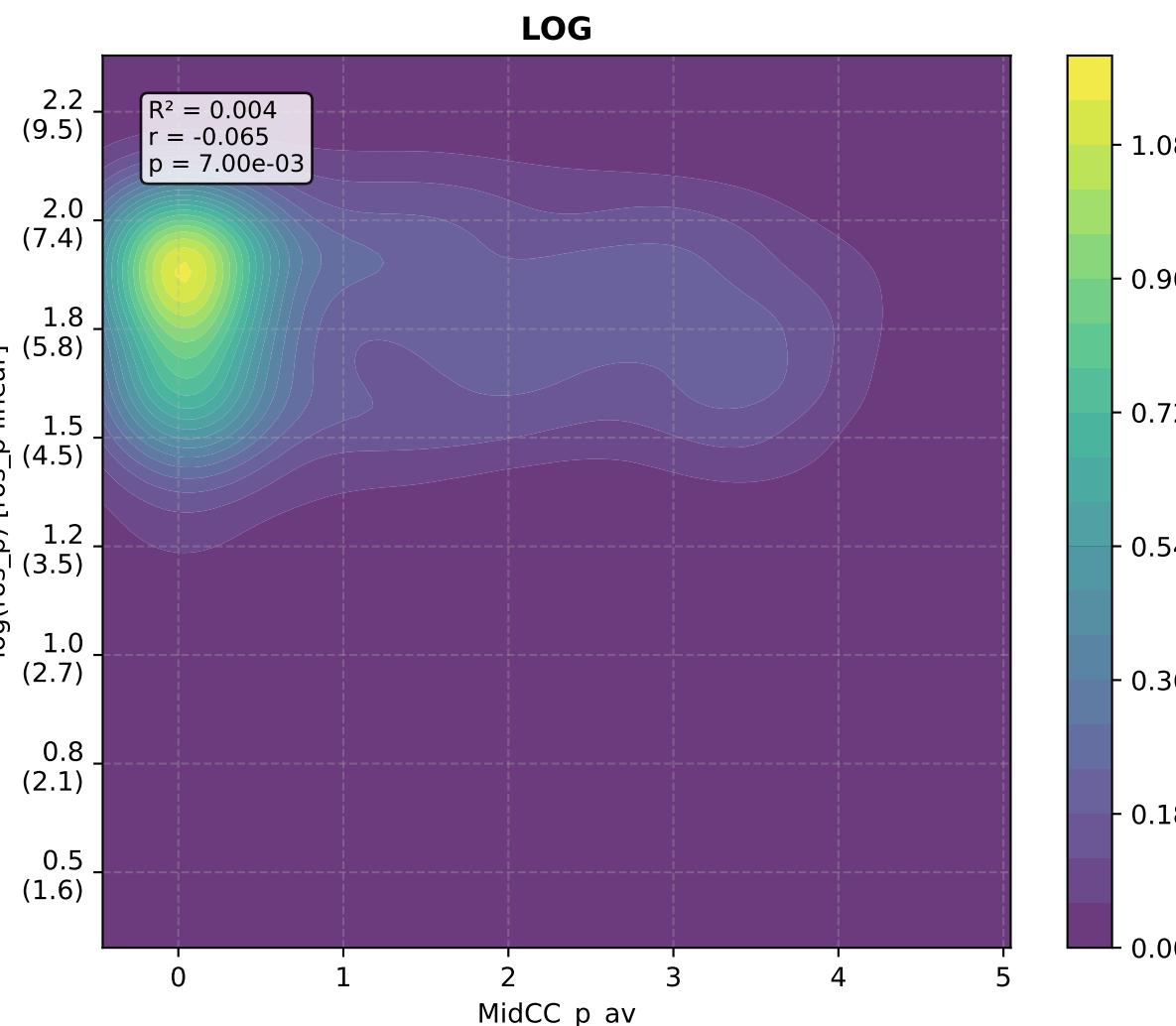
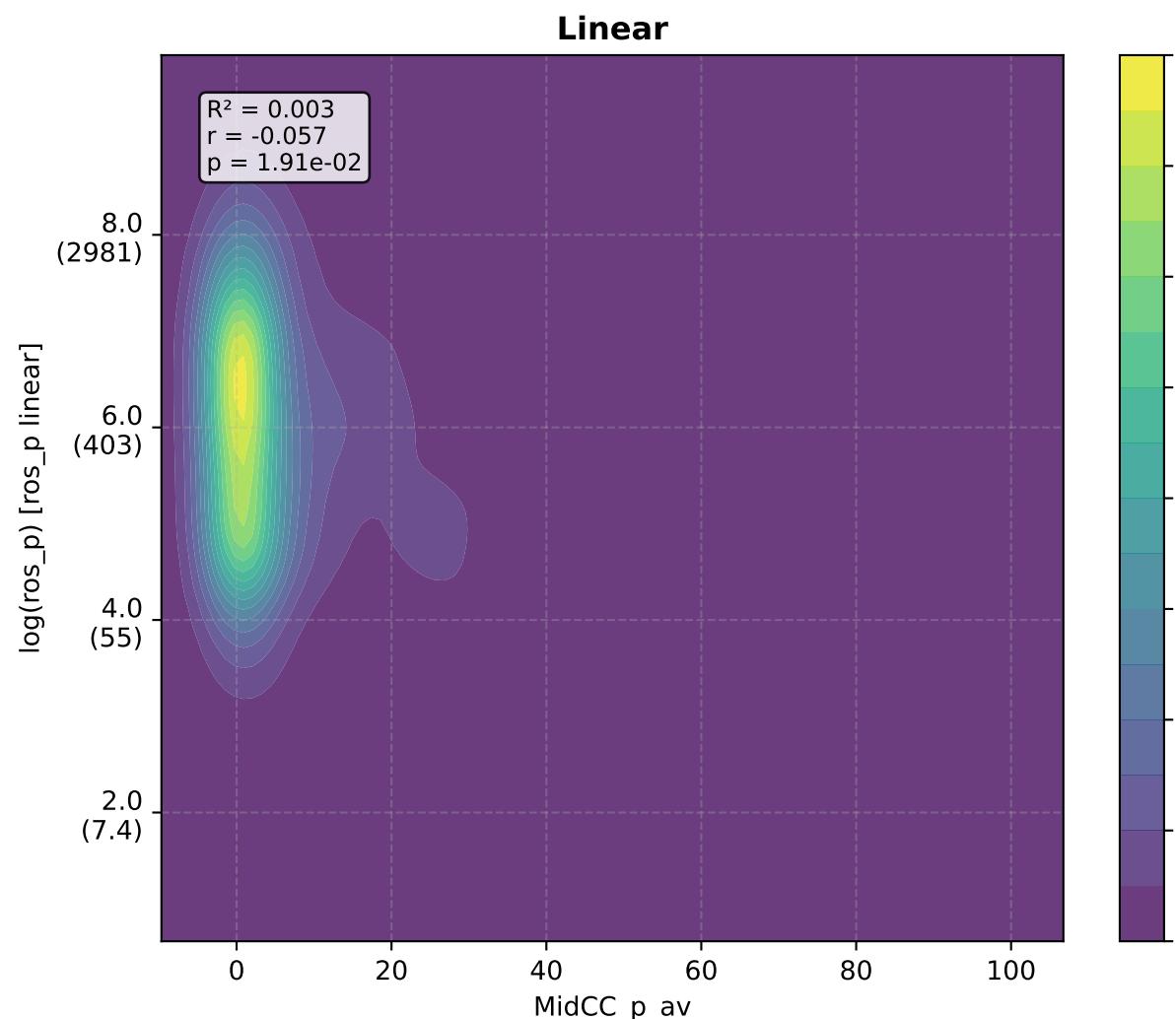
HigCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



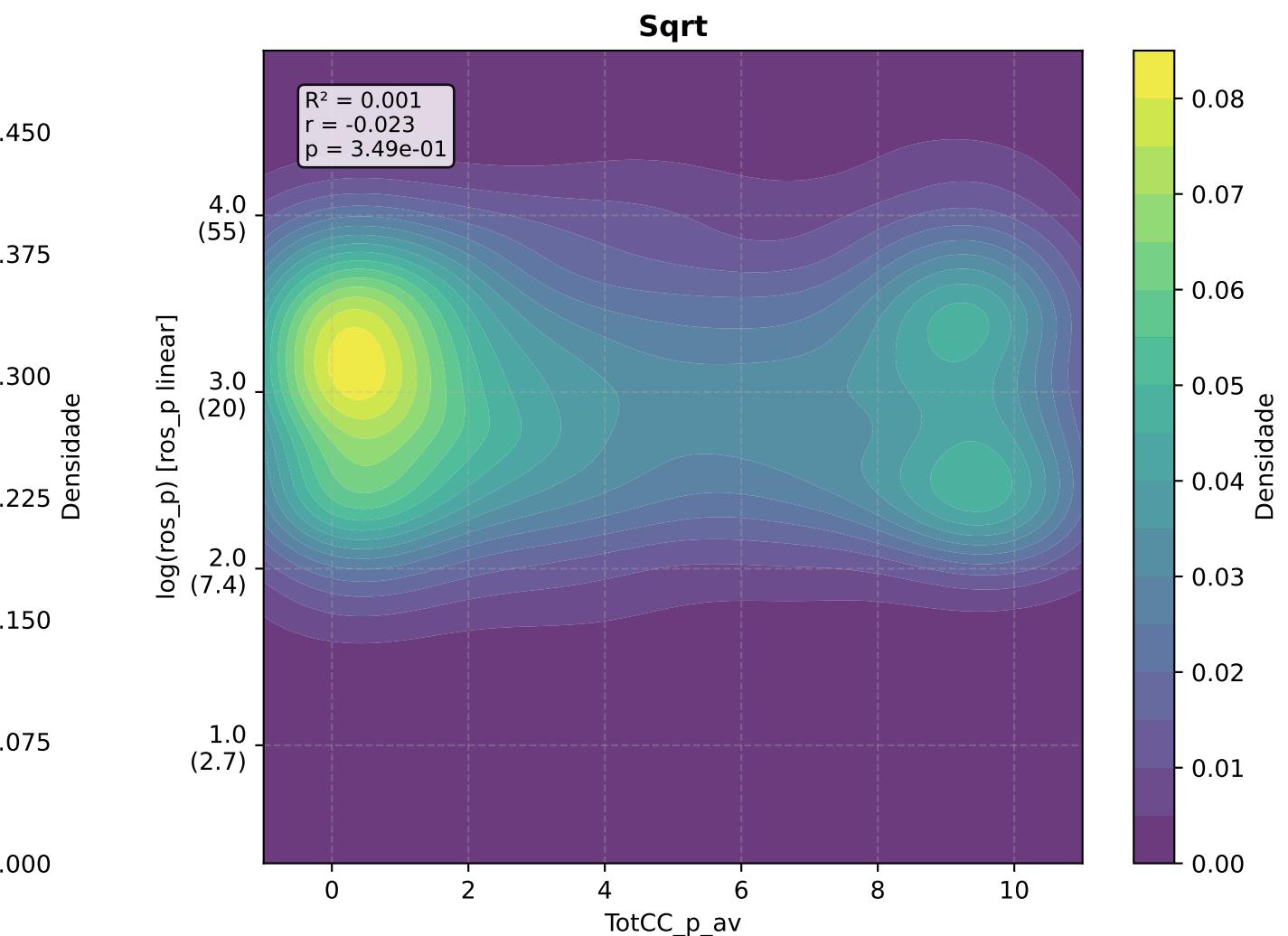
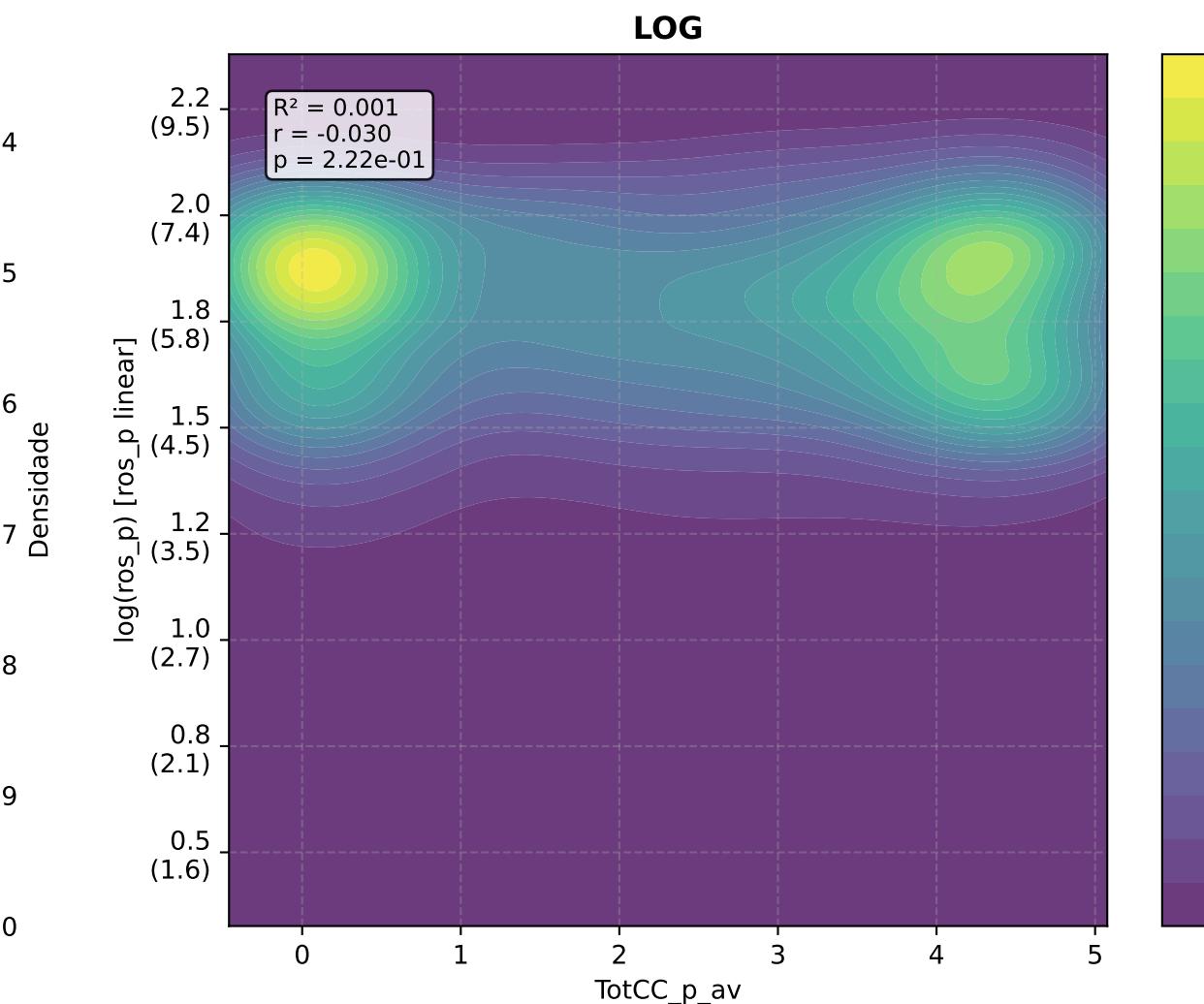
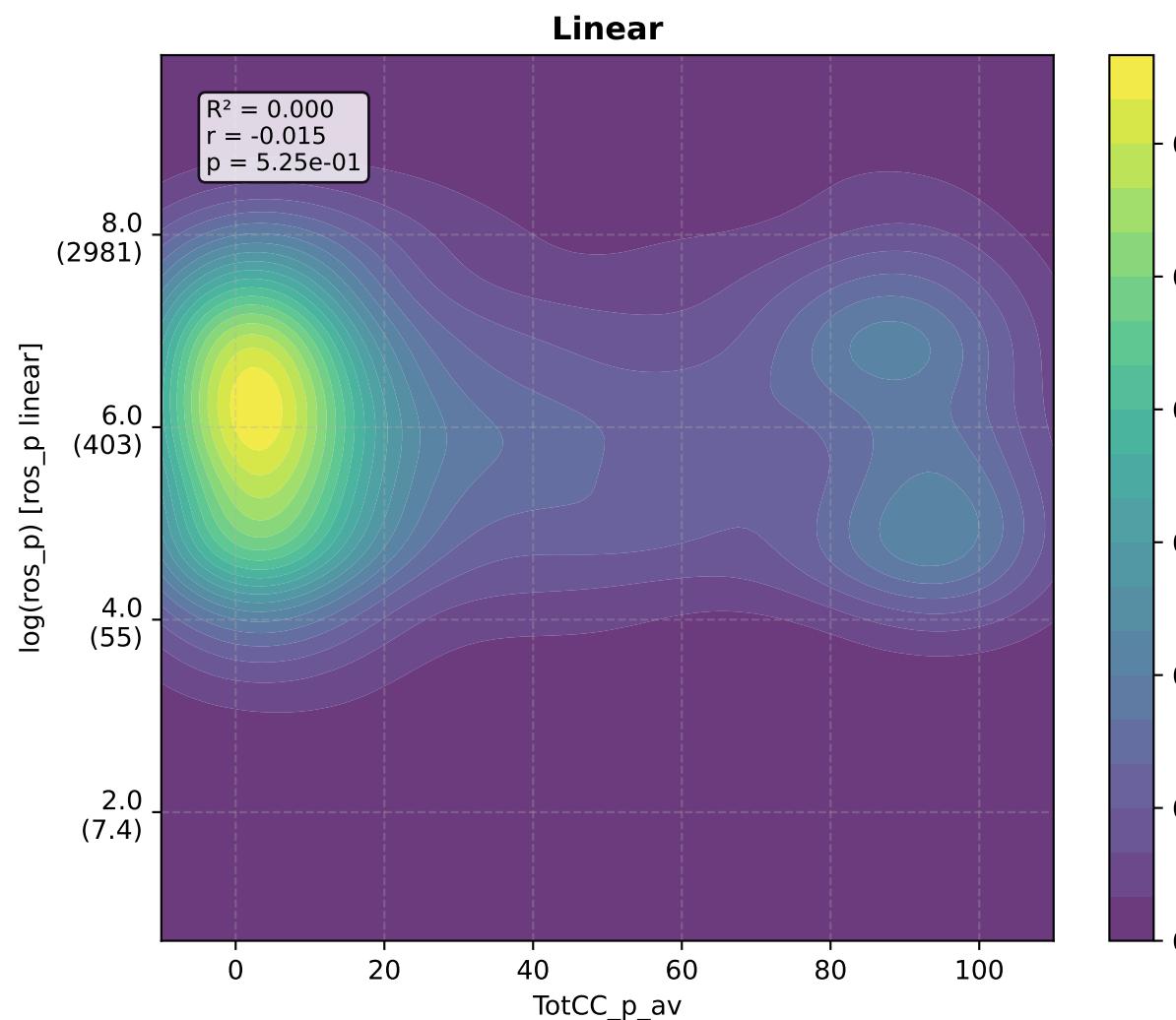
LowCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



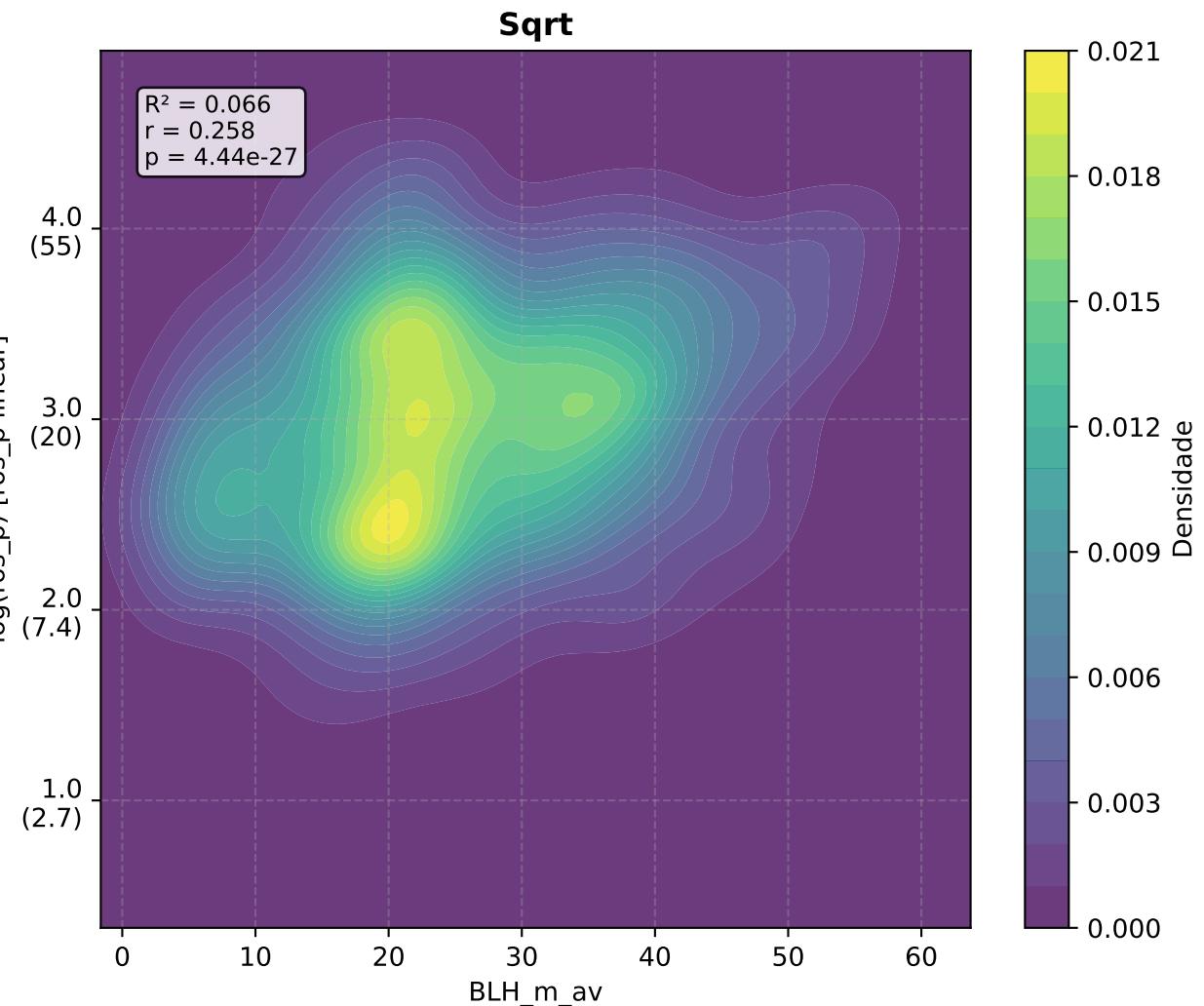
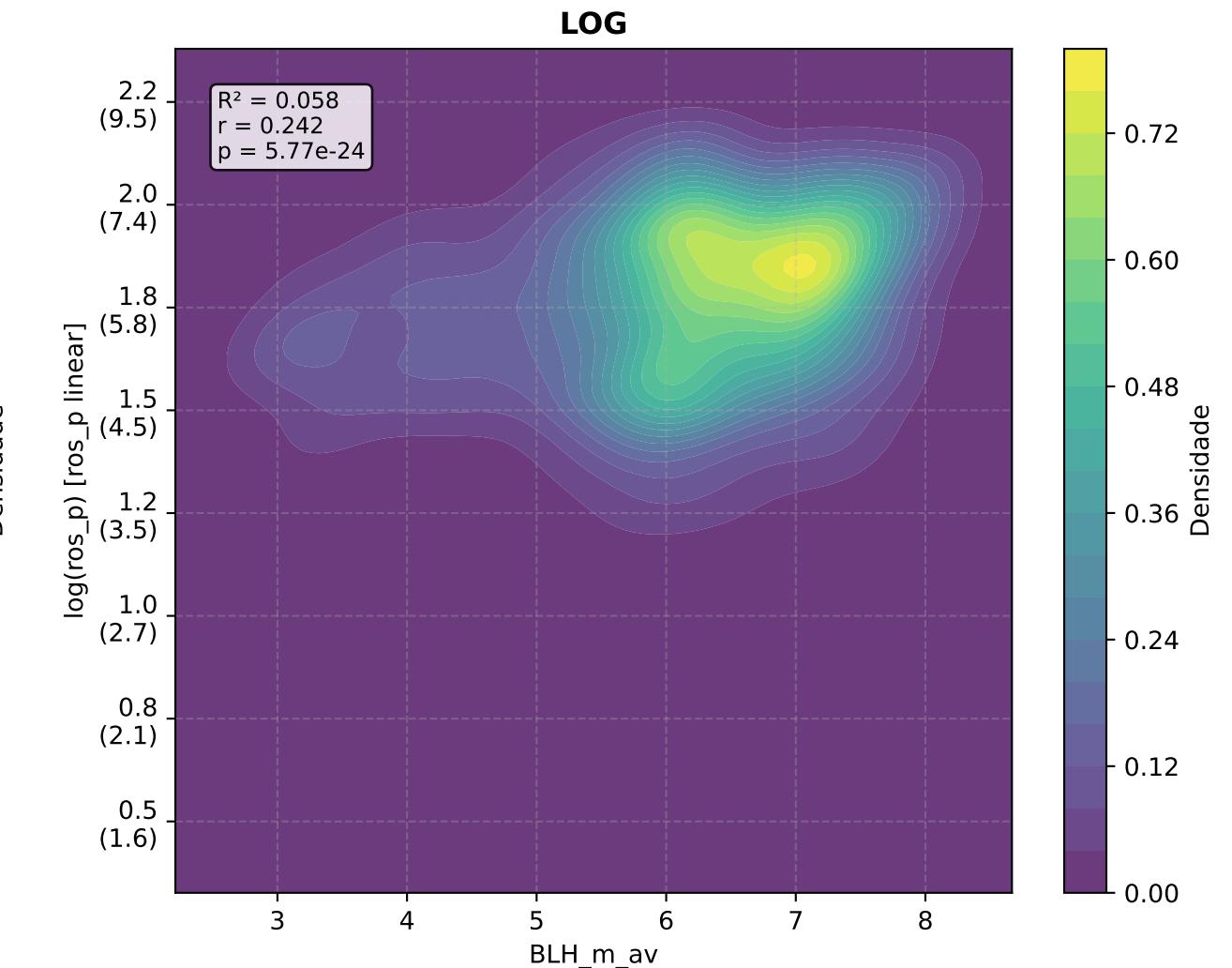
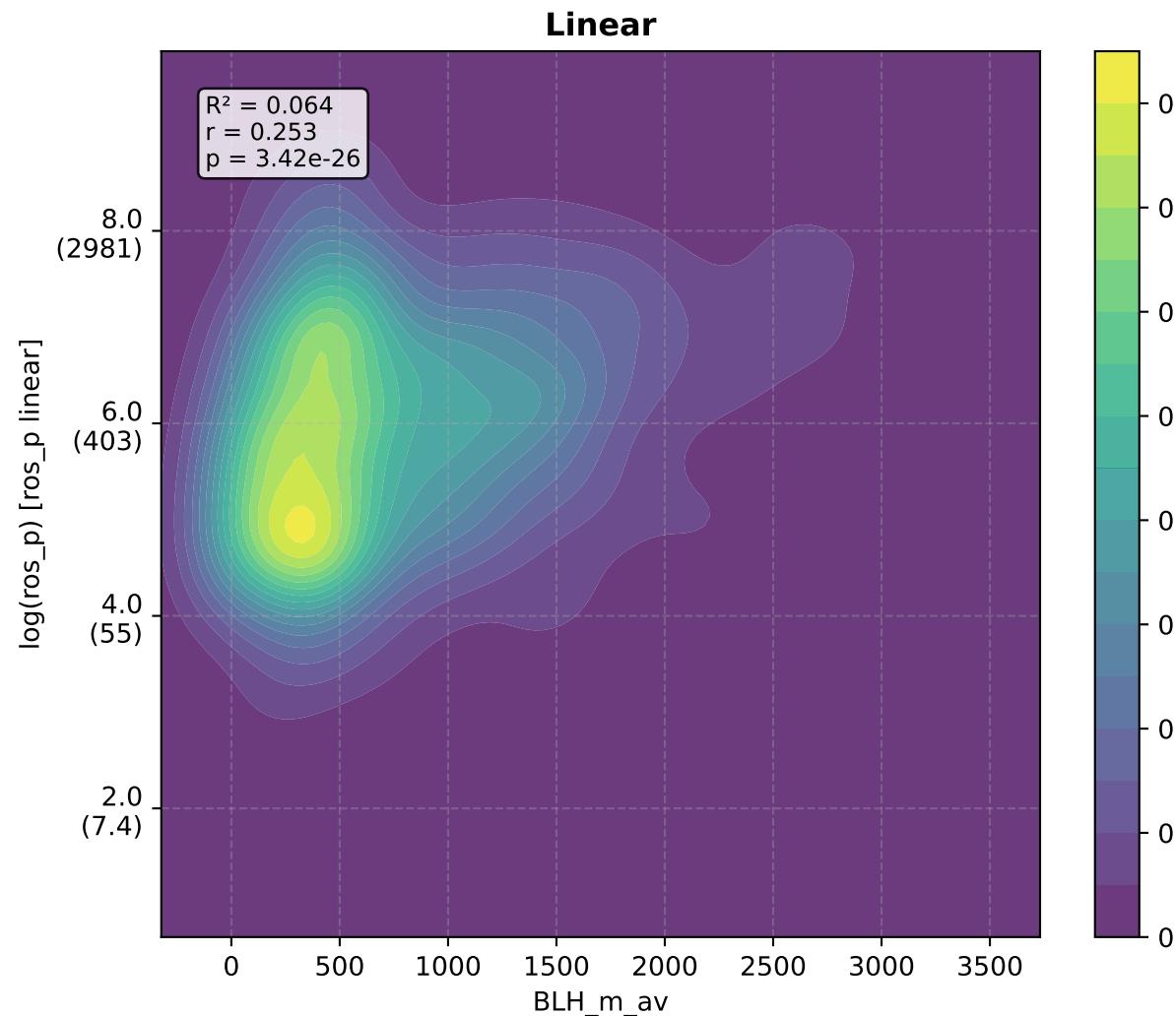
MidCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



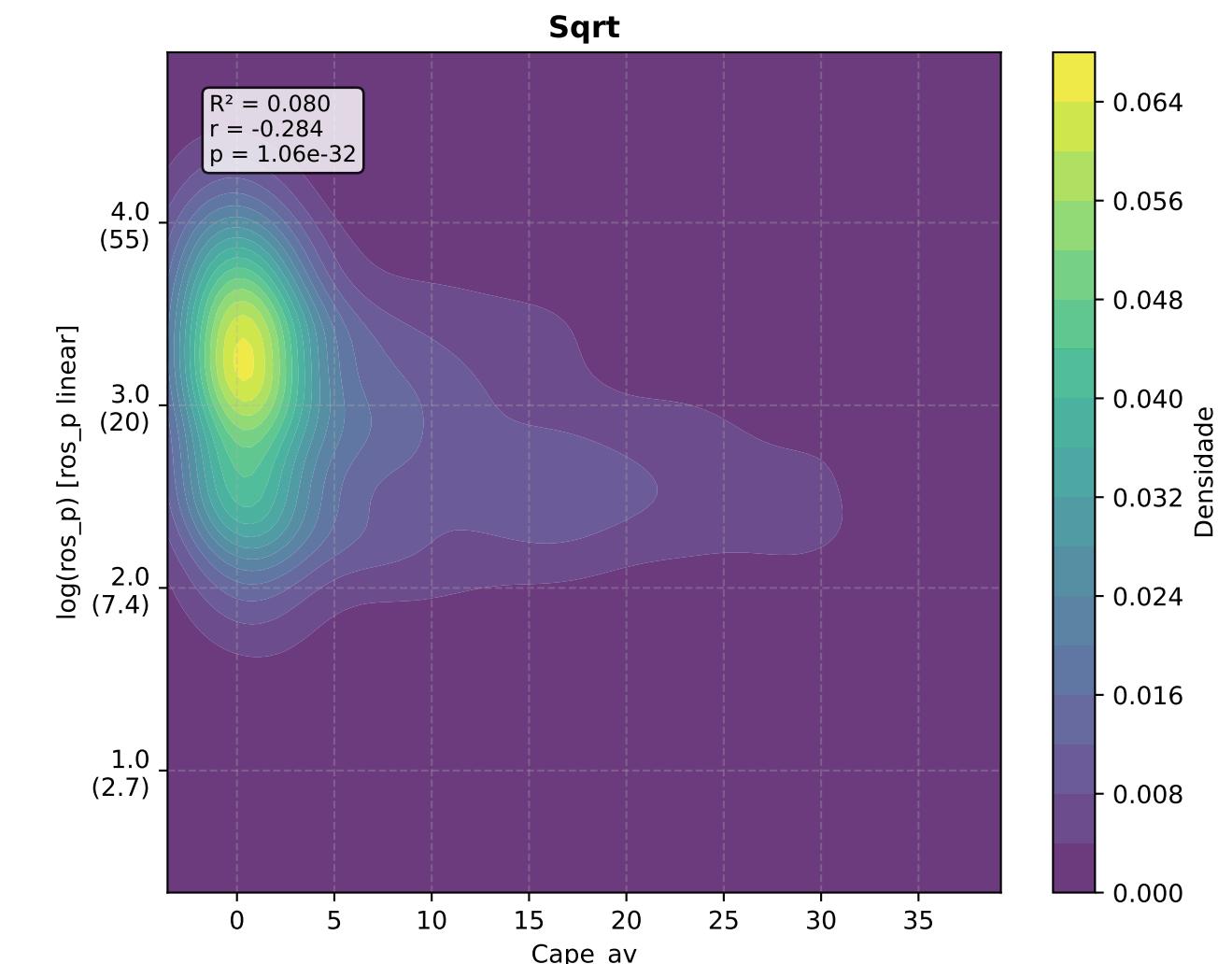
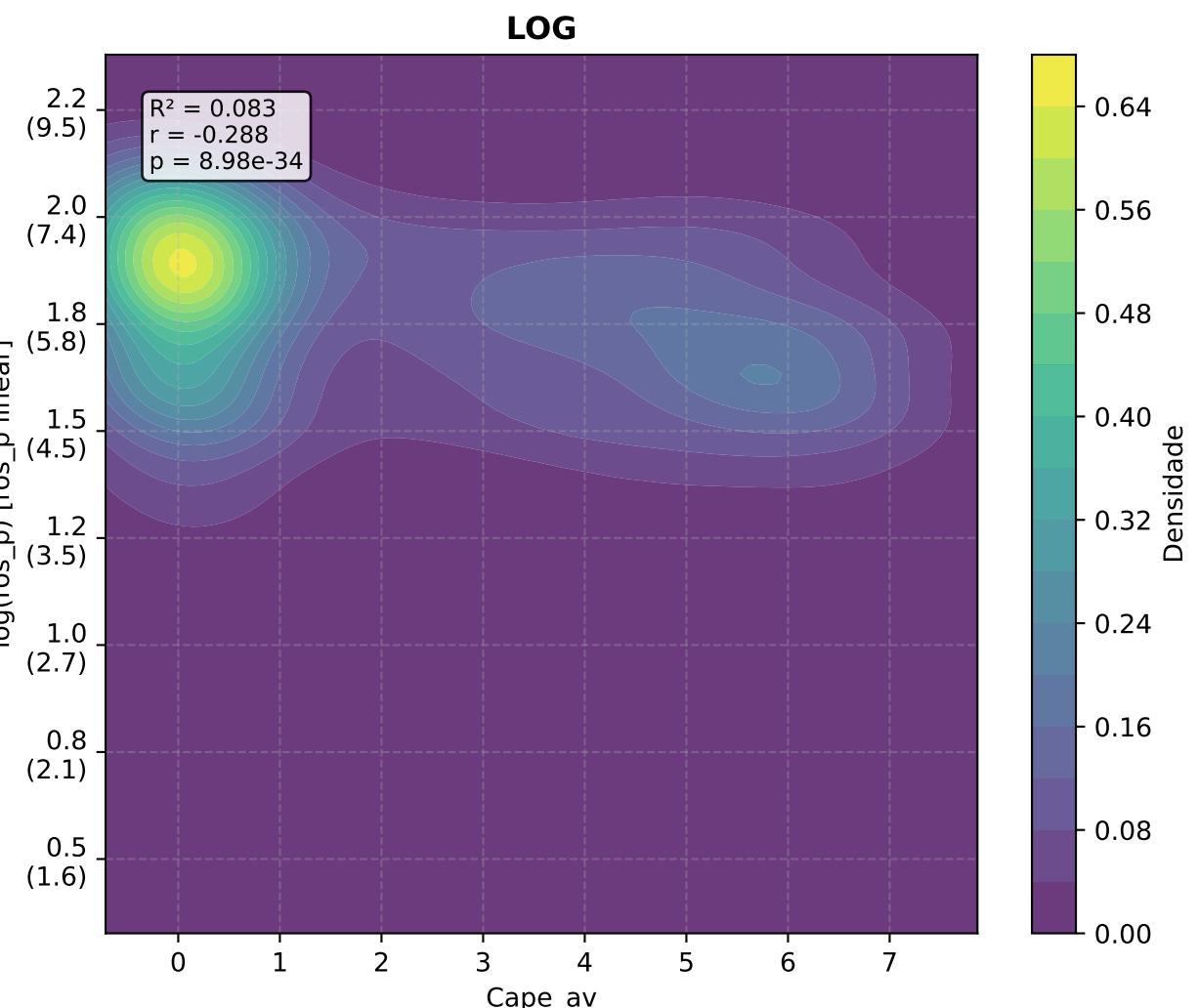
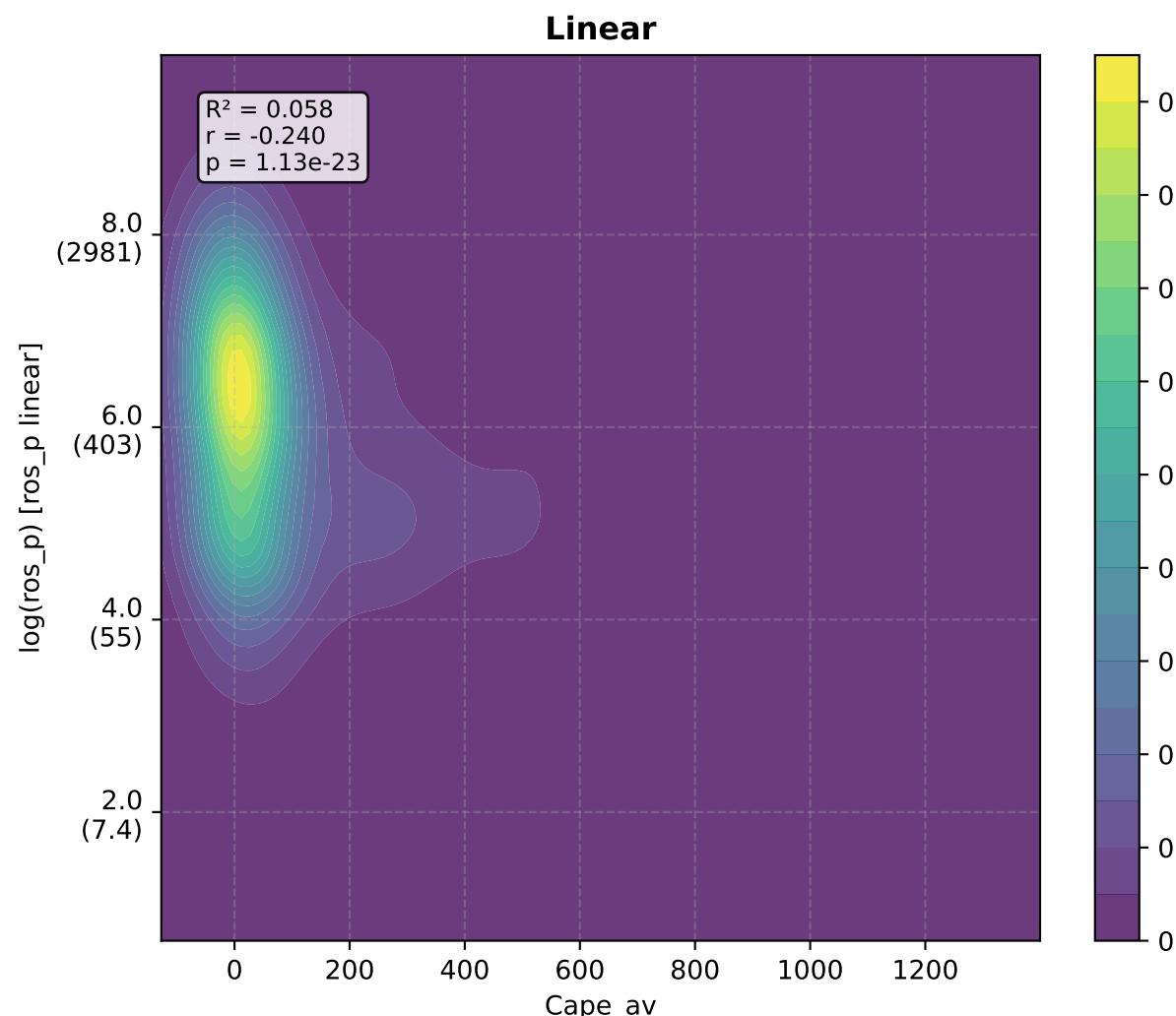
TotCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



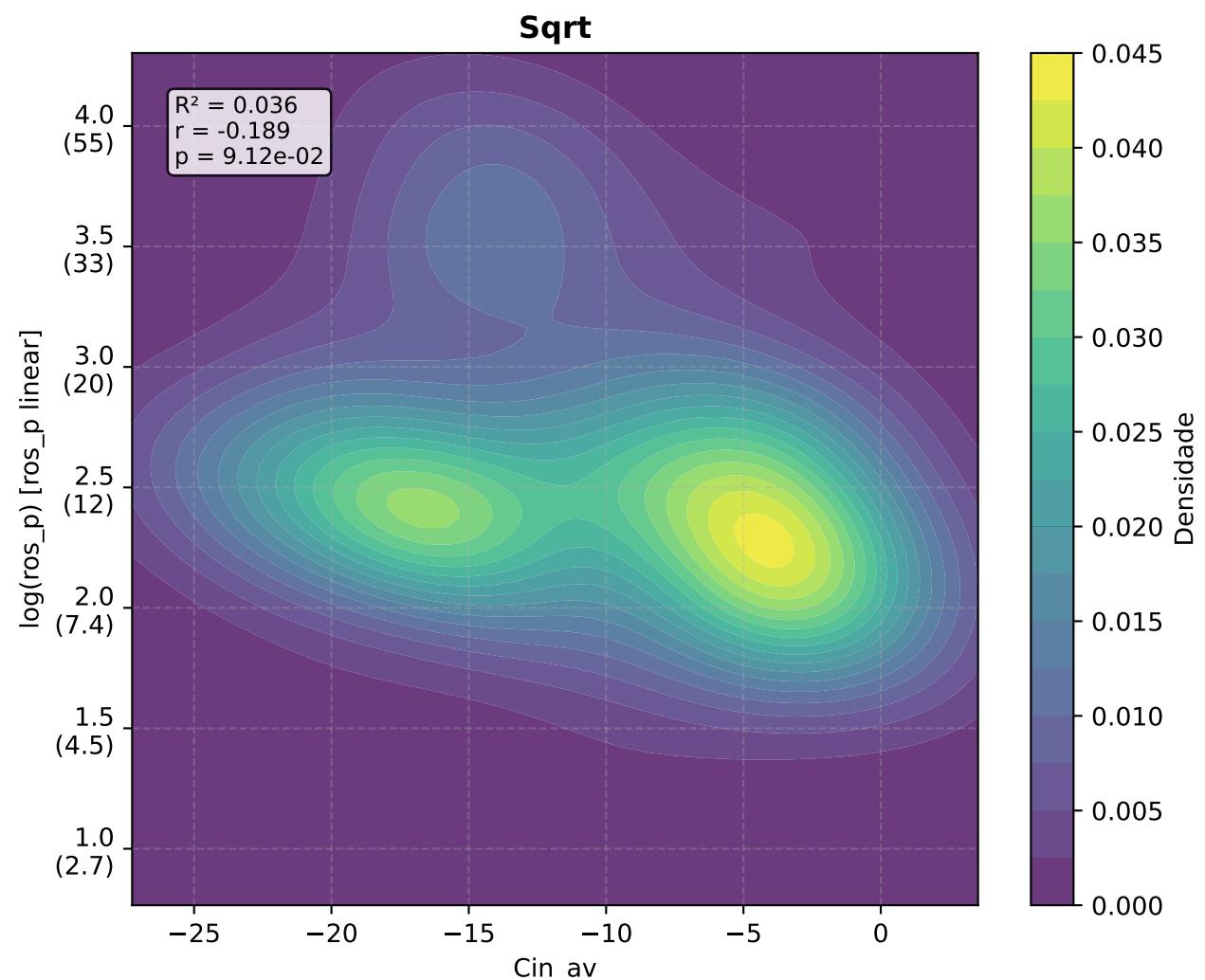
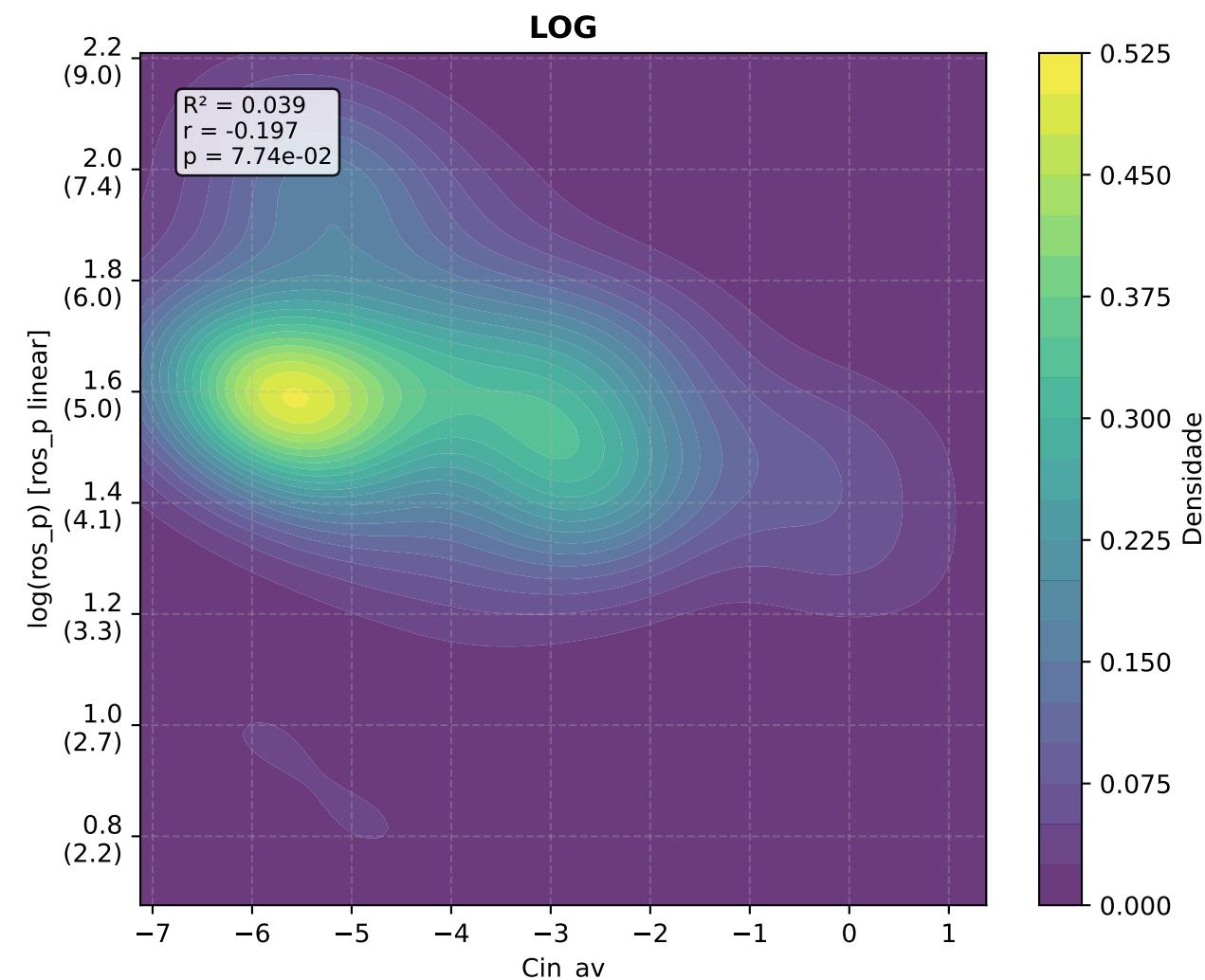
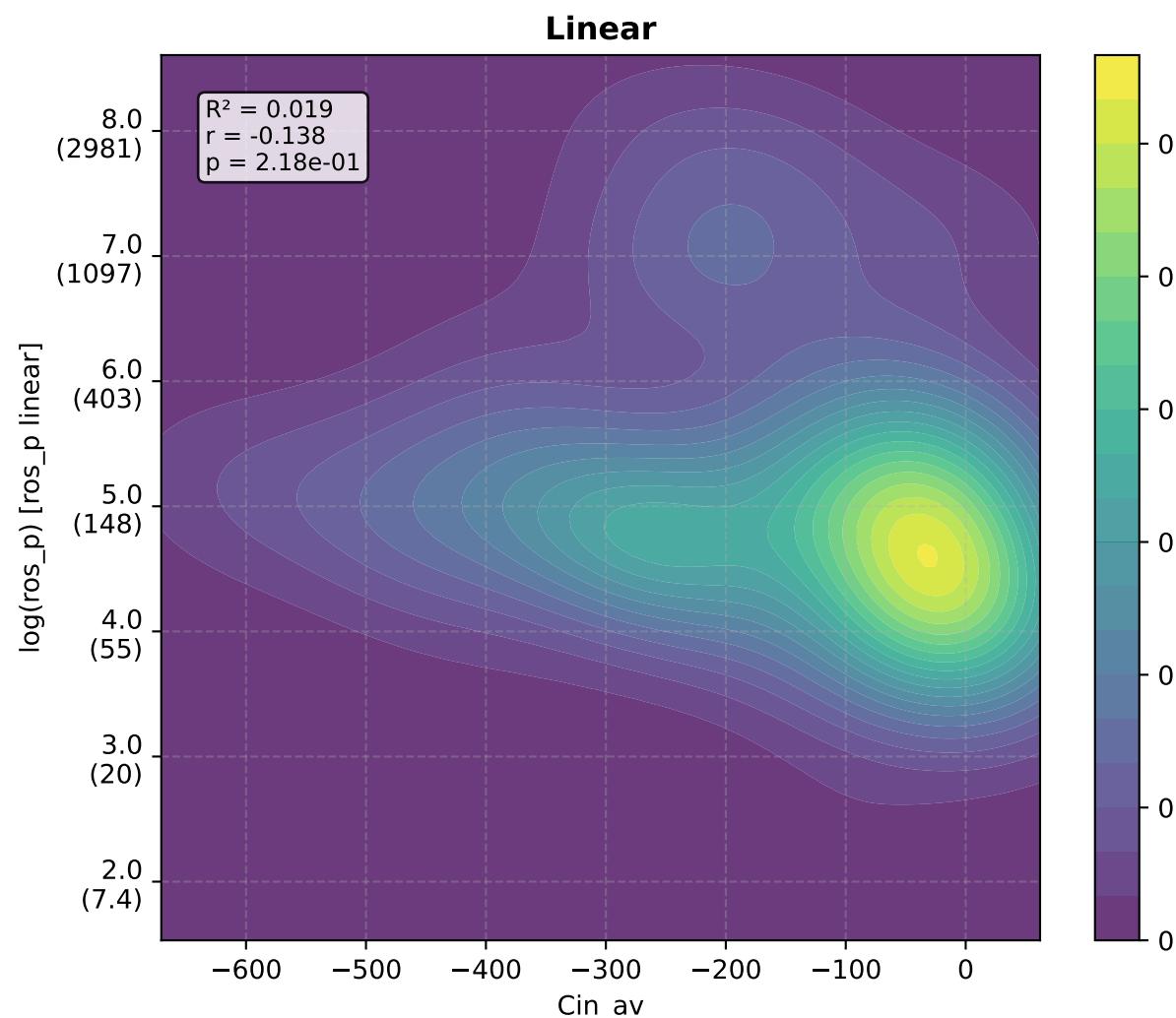
BLH_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



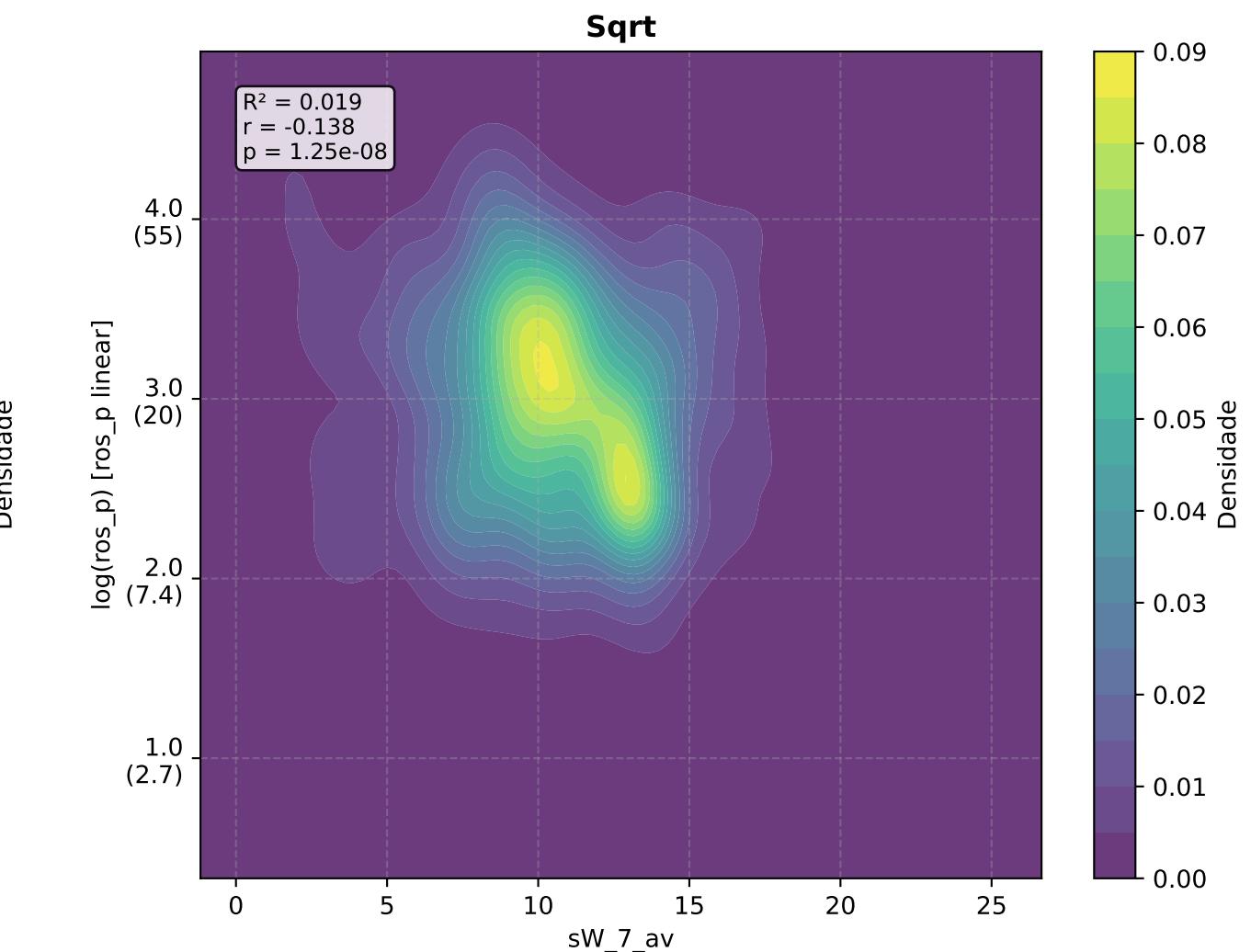
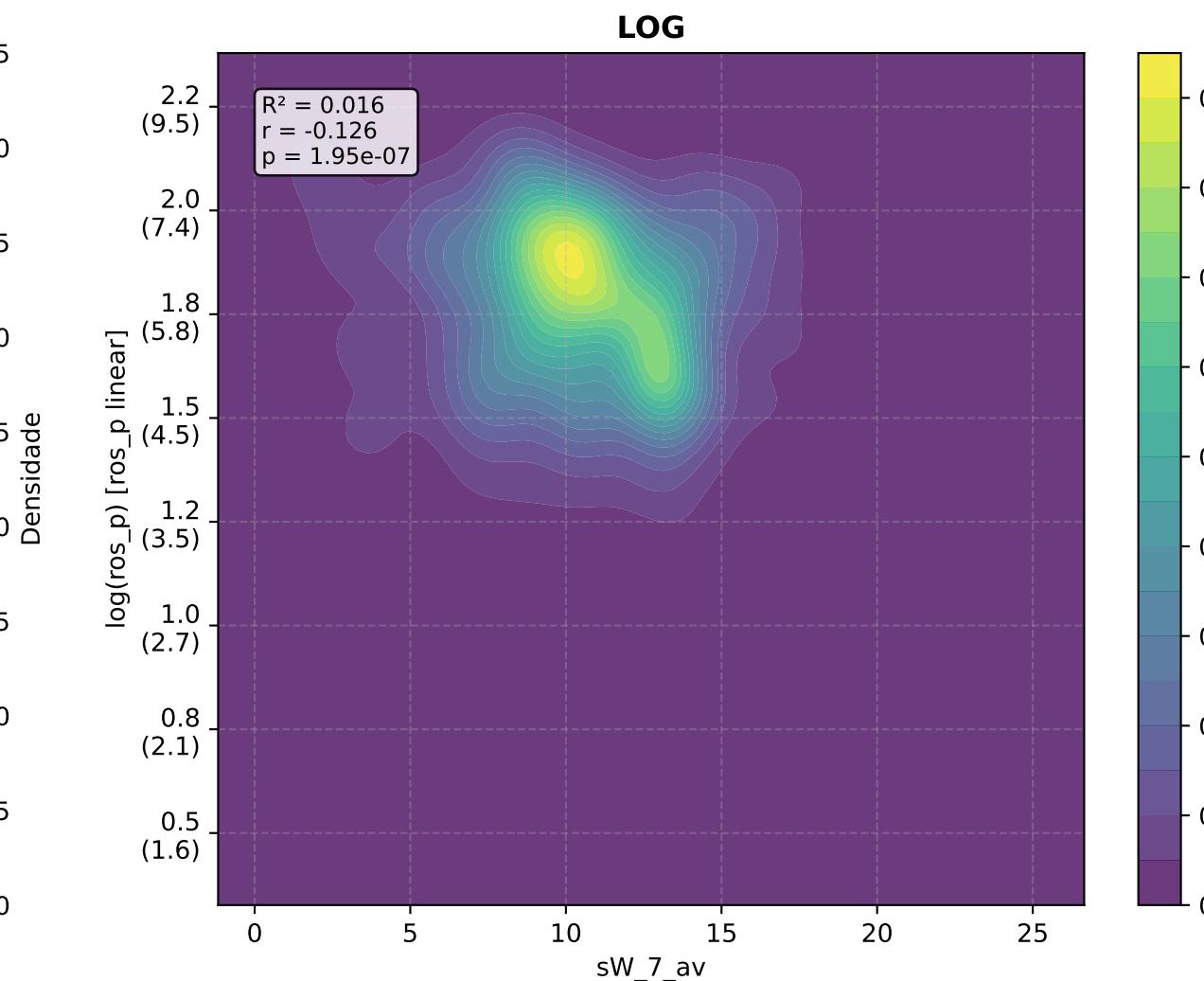
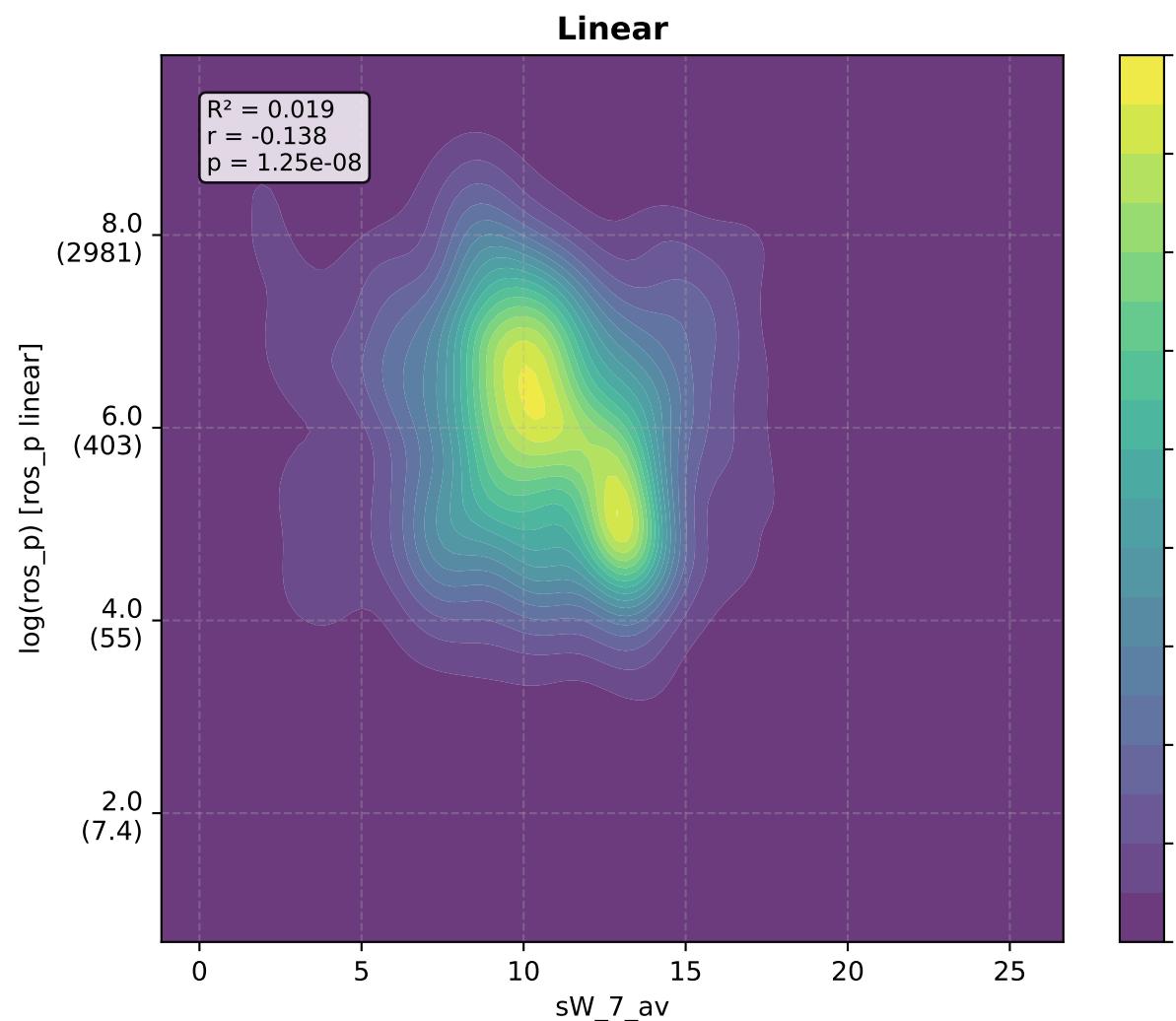
Cape_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



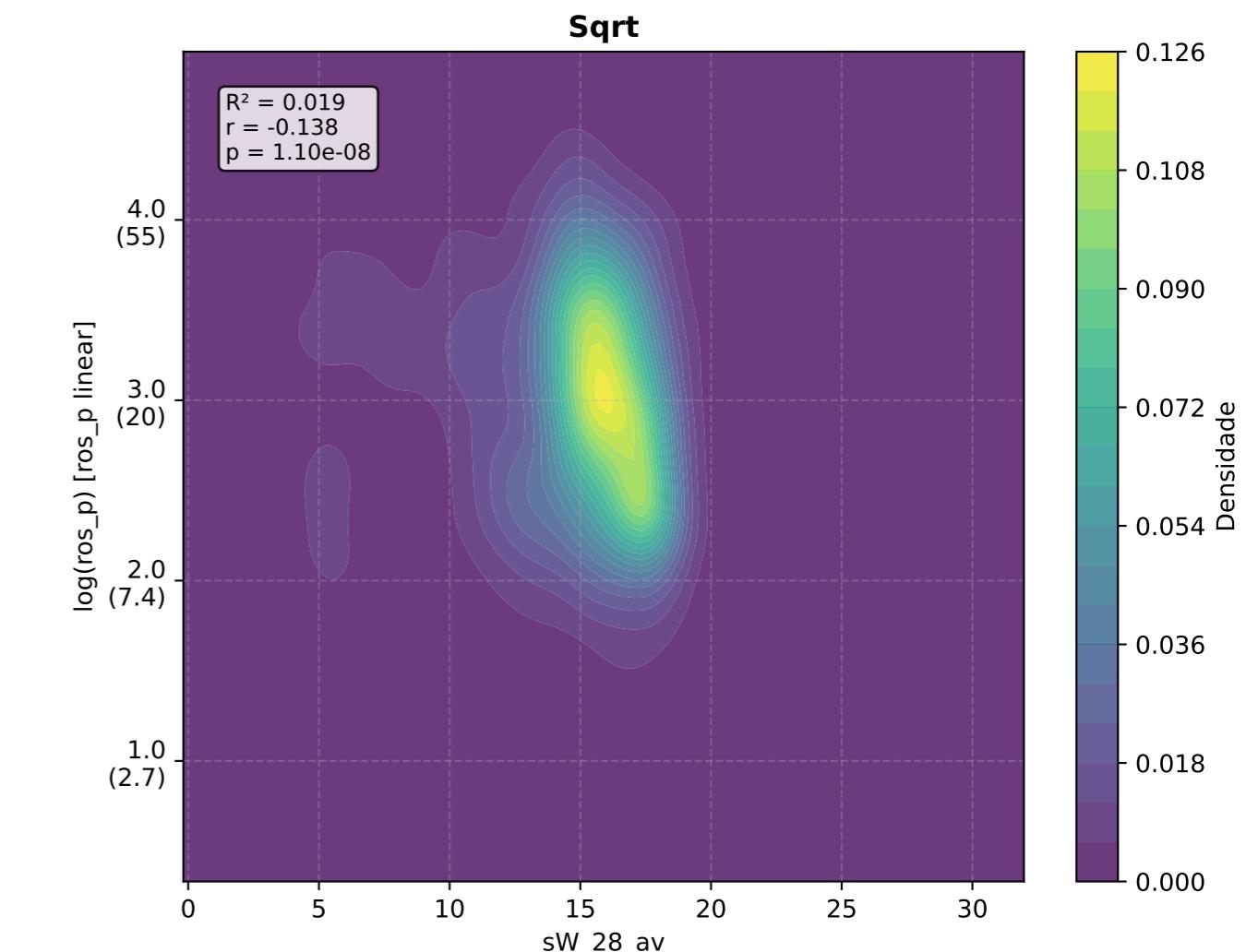
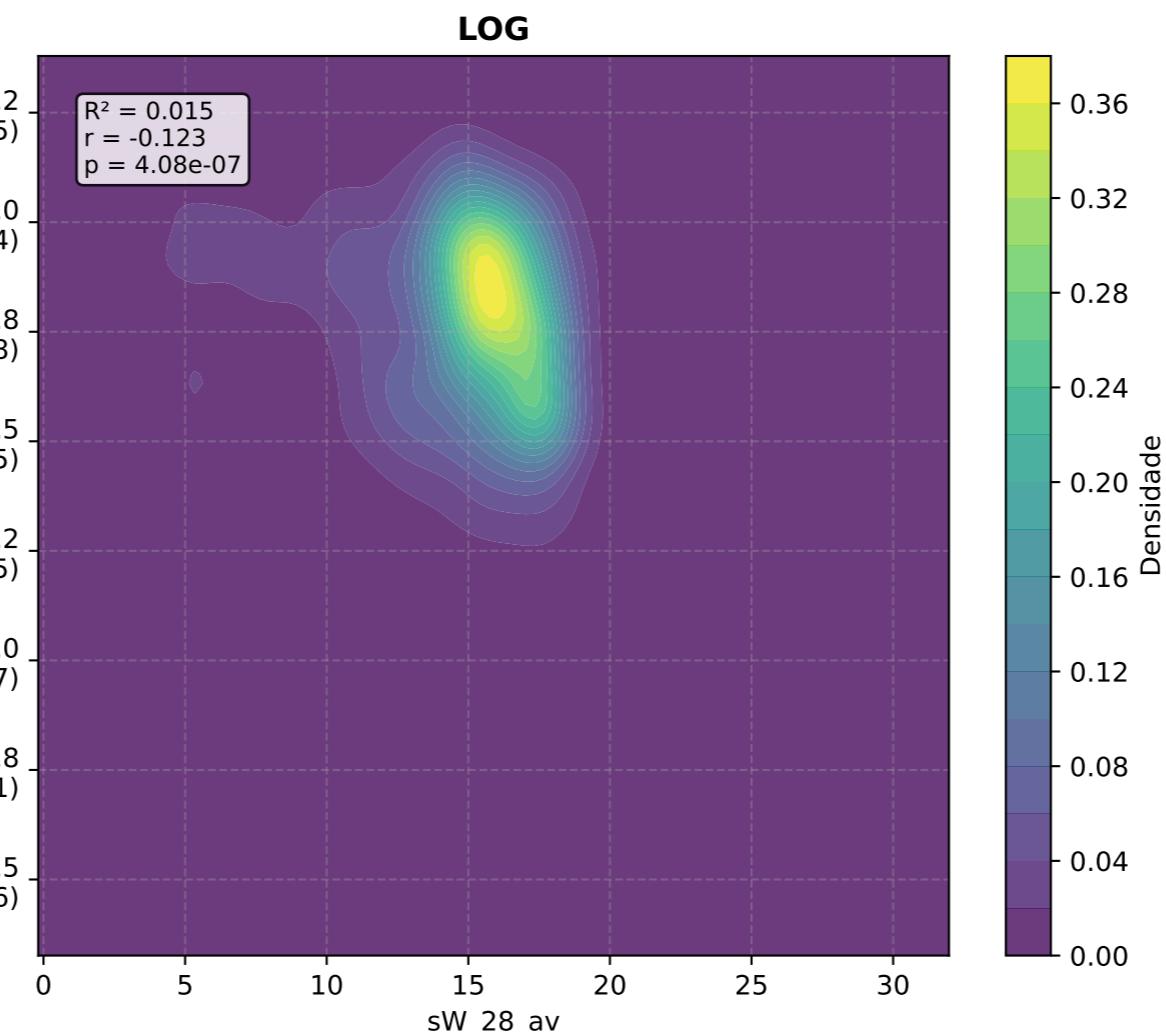
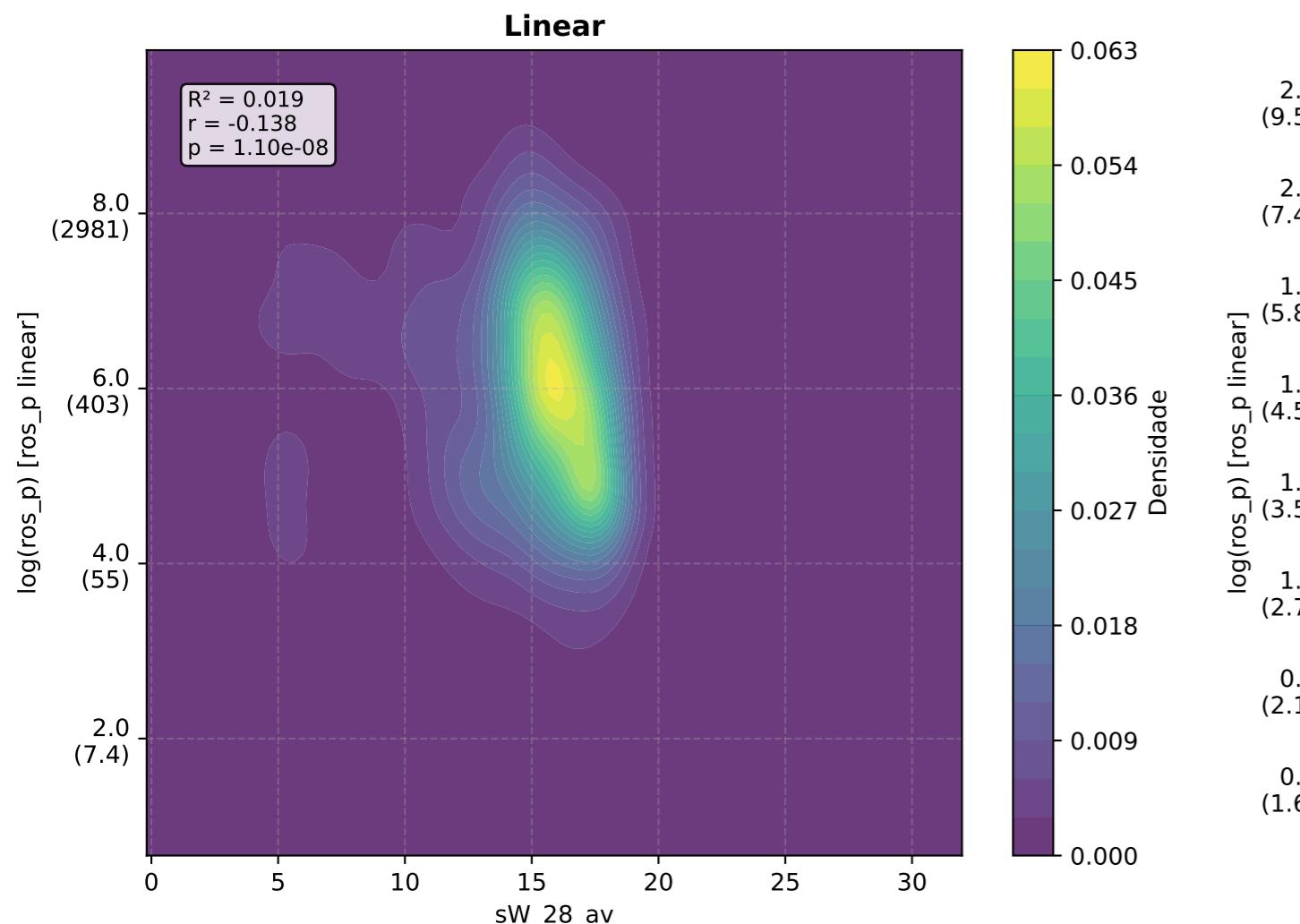
Cin_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



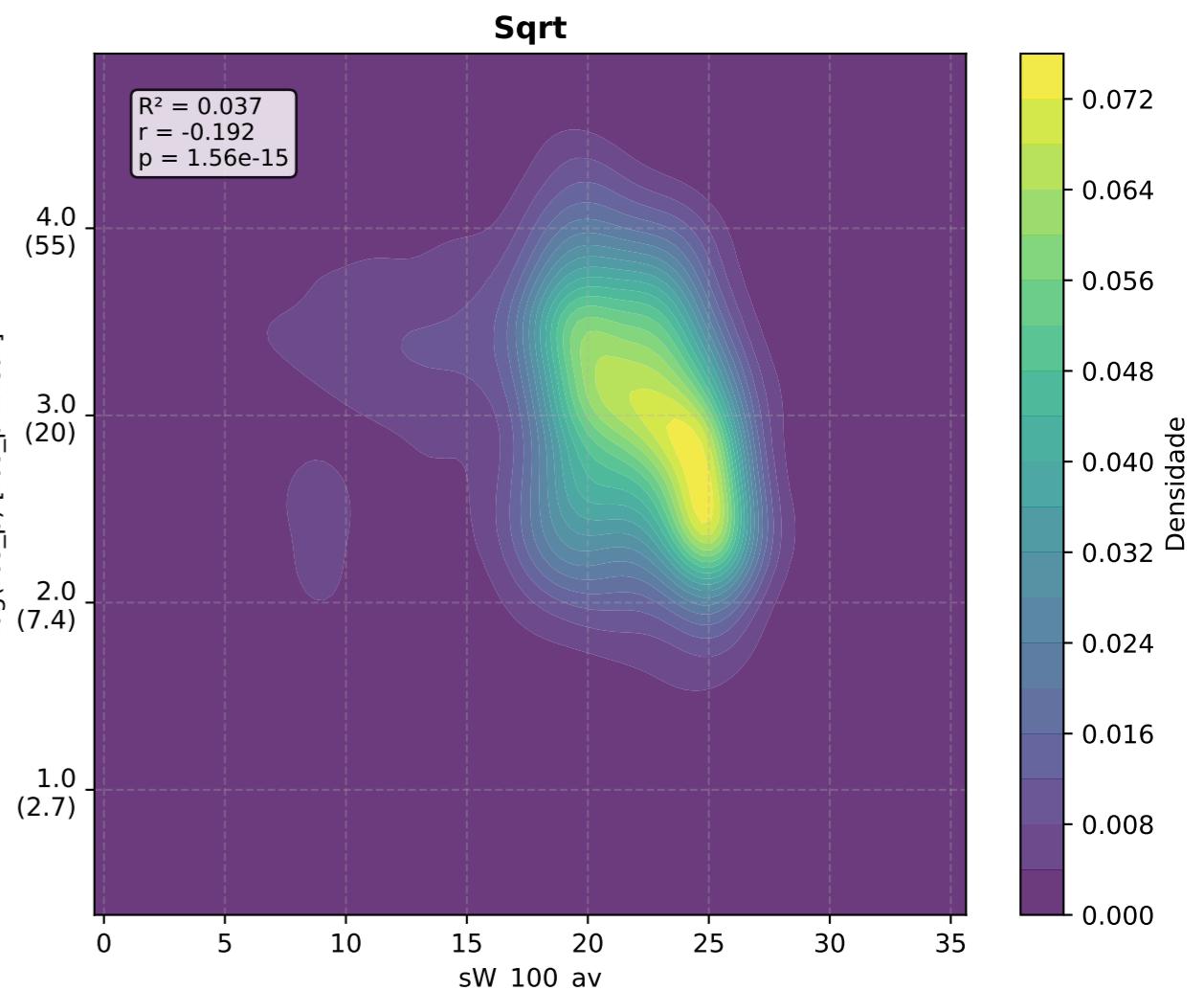
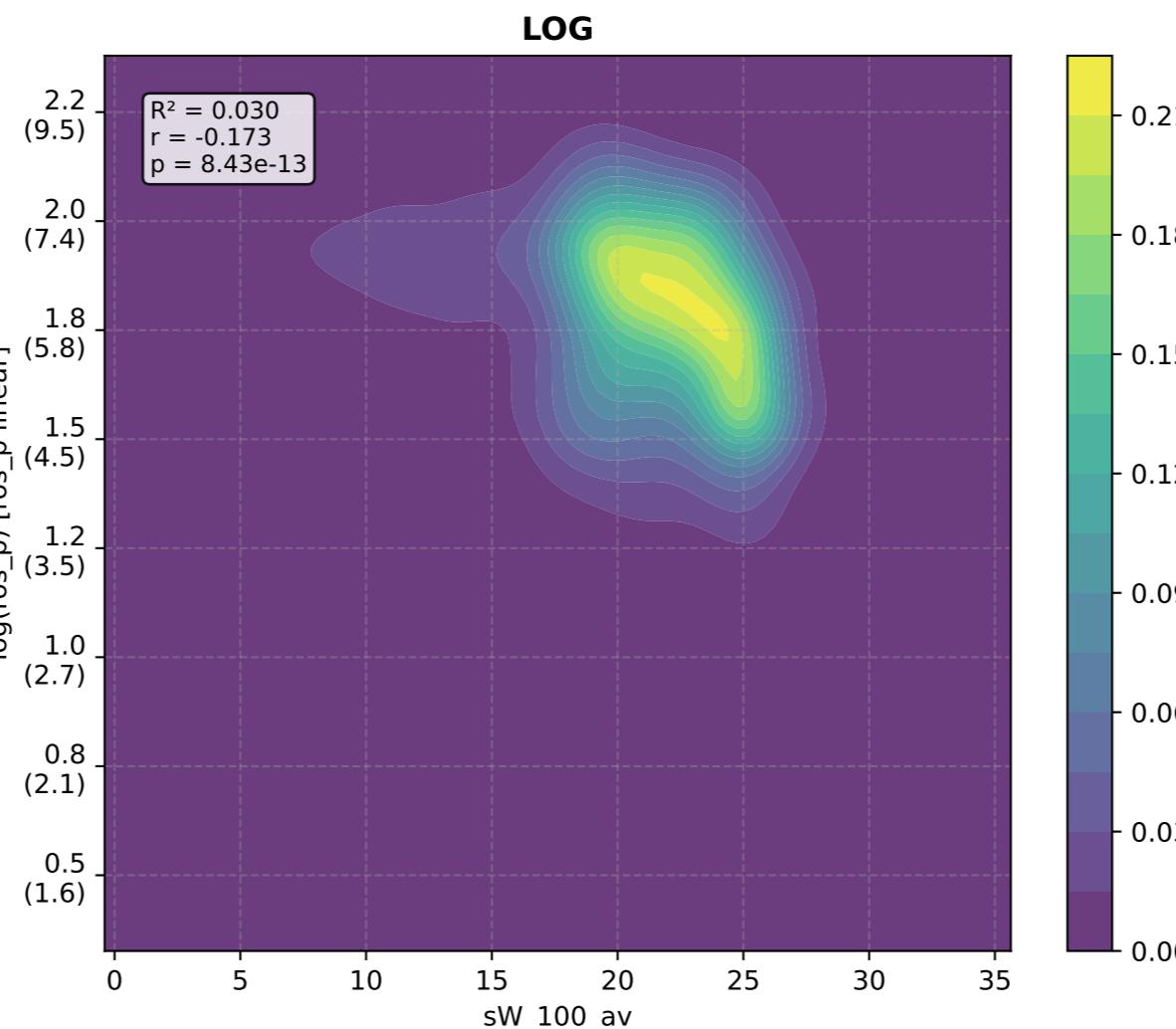
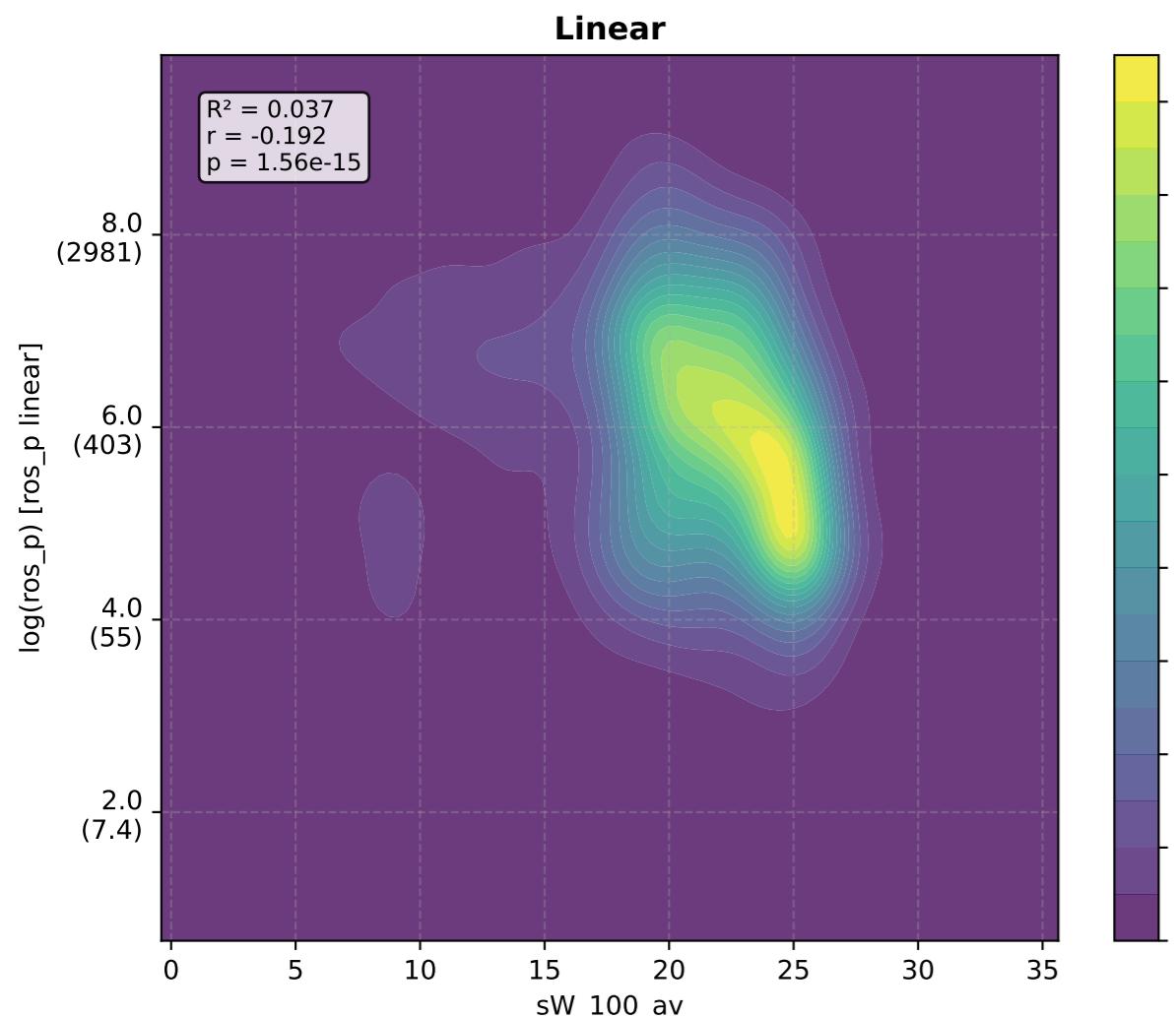
sW_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



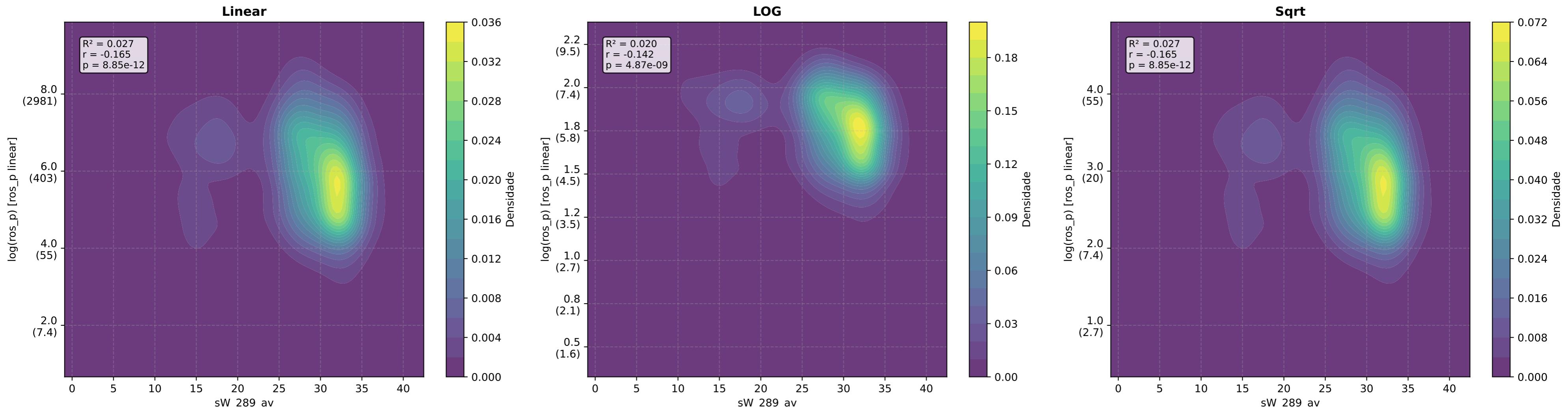
sW_28_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



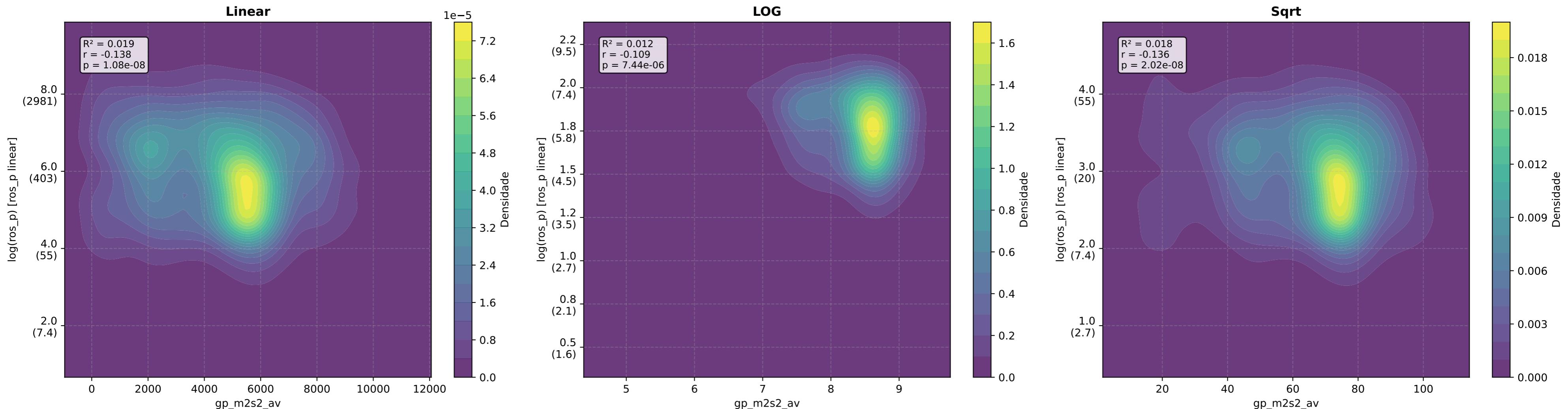
sW_100_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



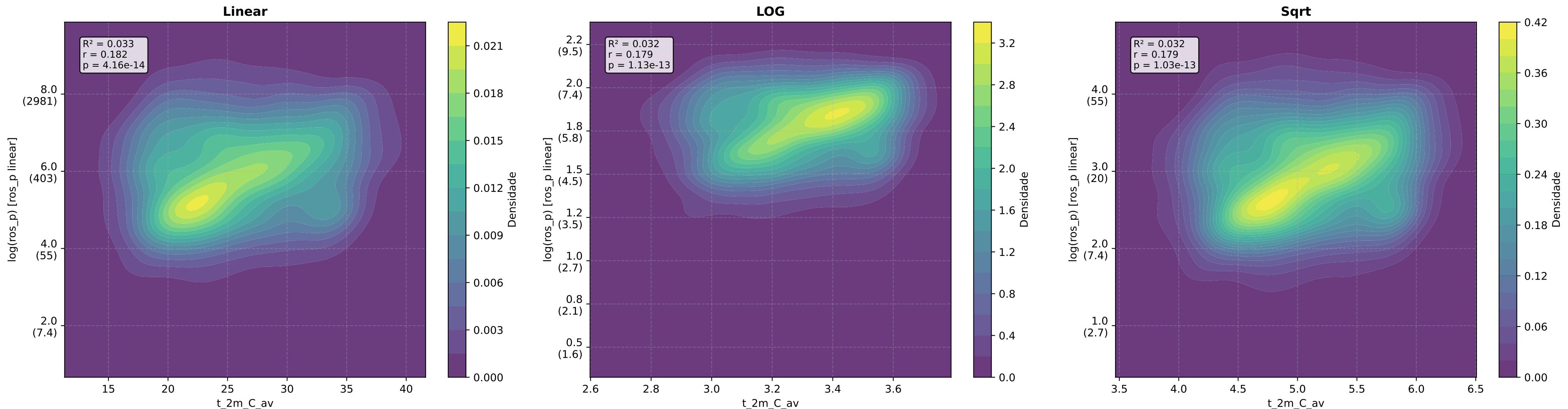
sW_289_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



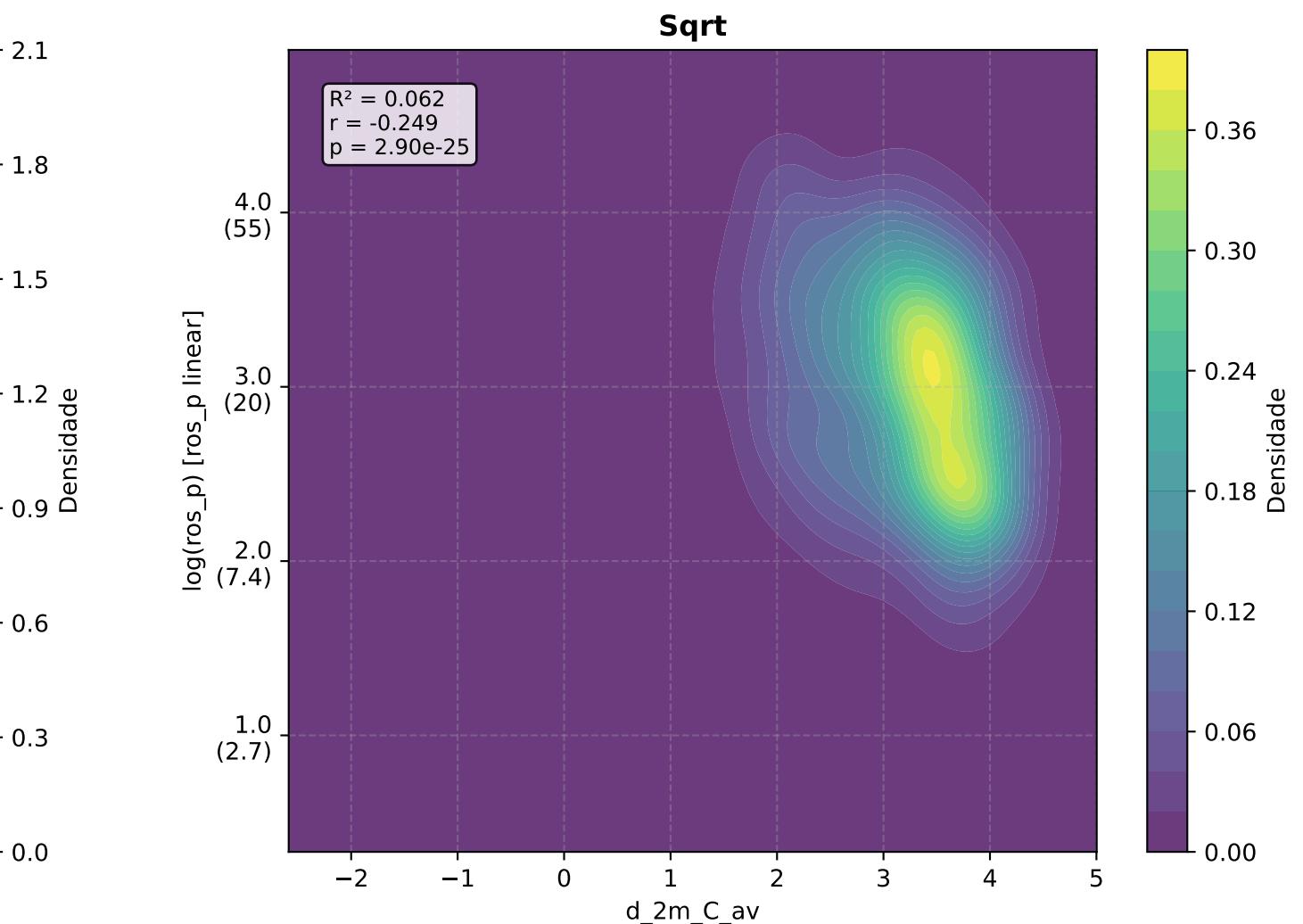
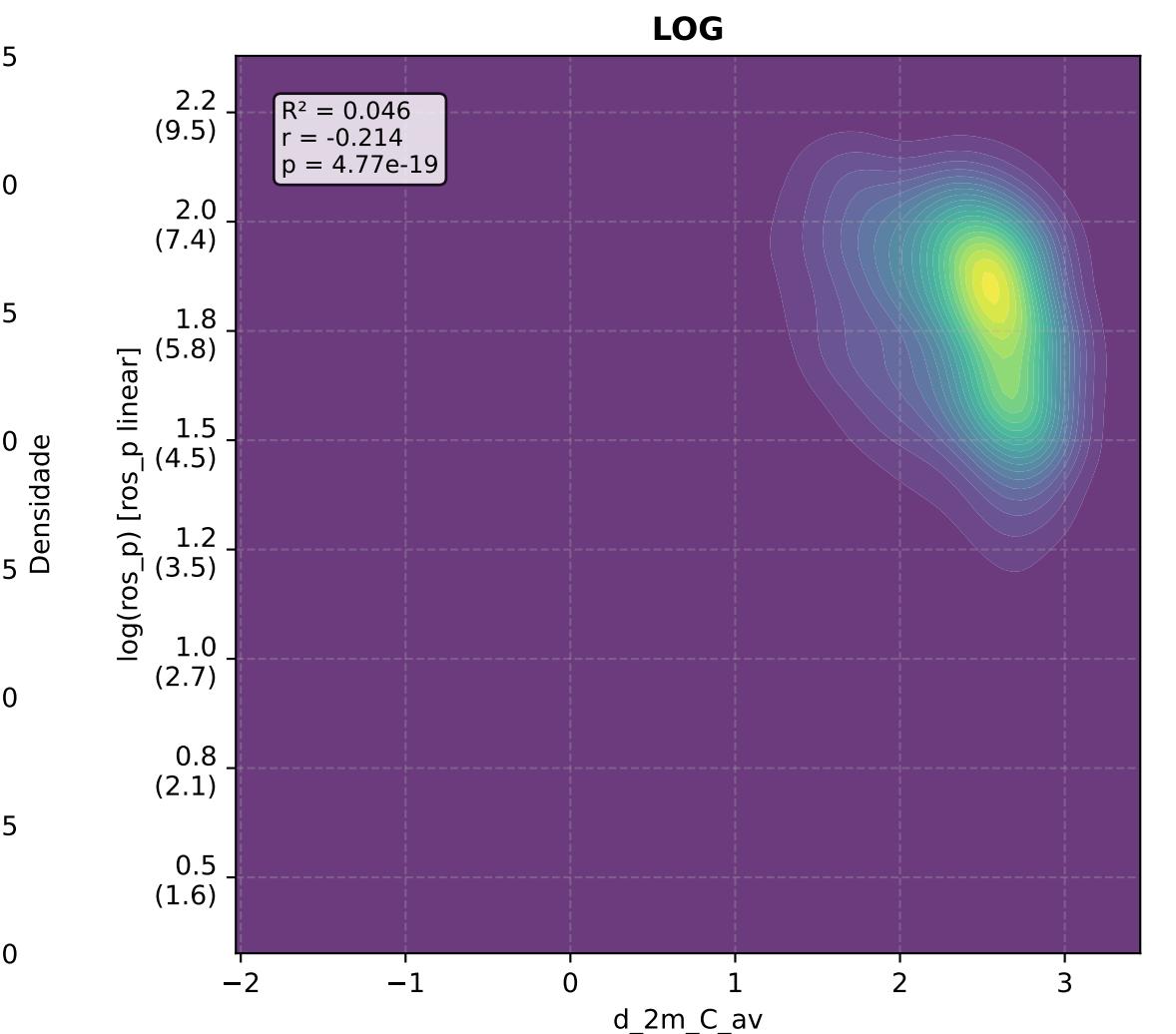
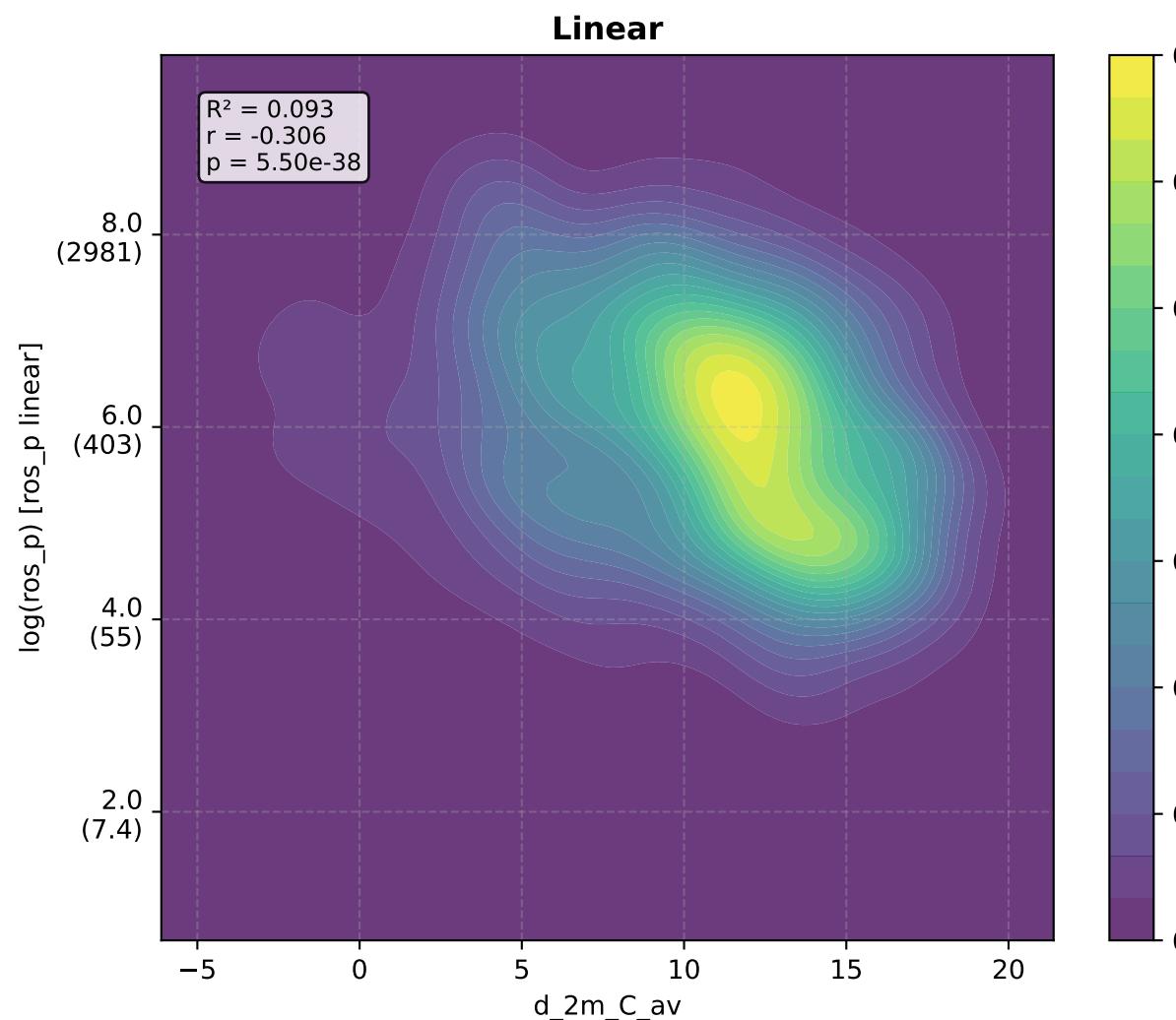
gp_m2s2_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



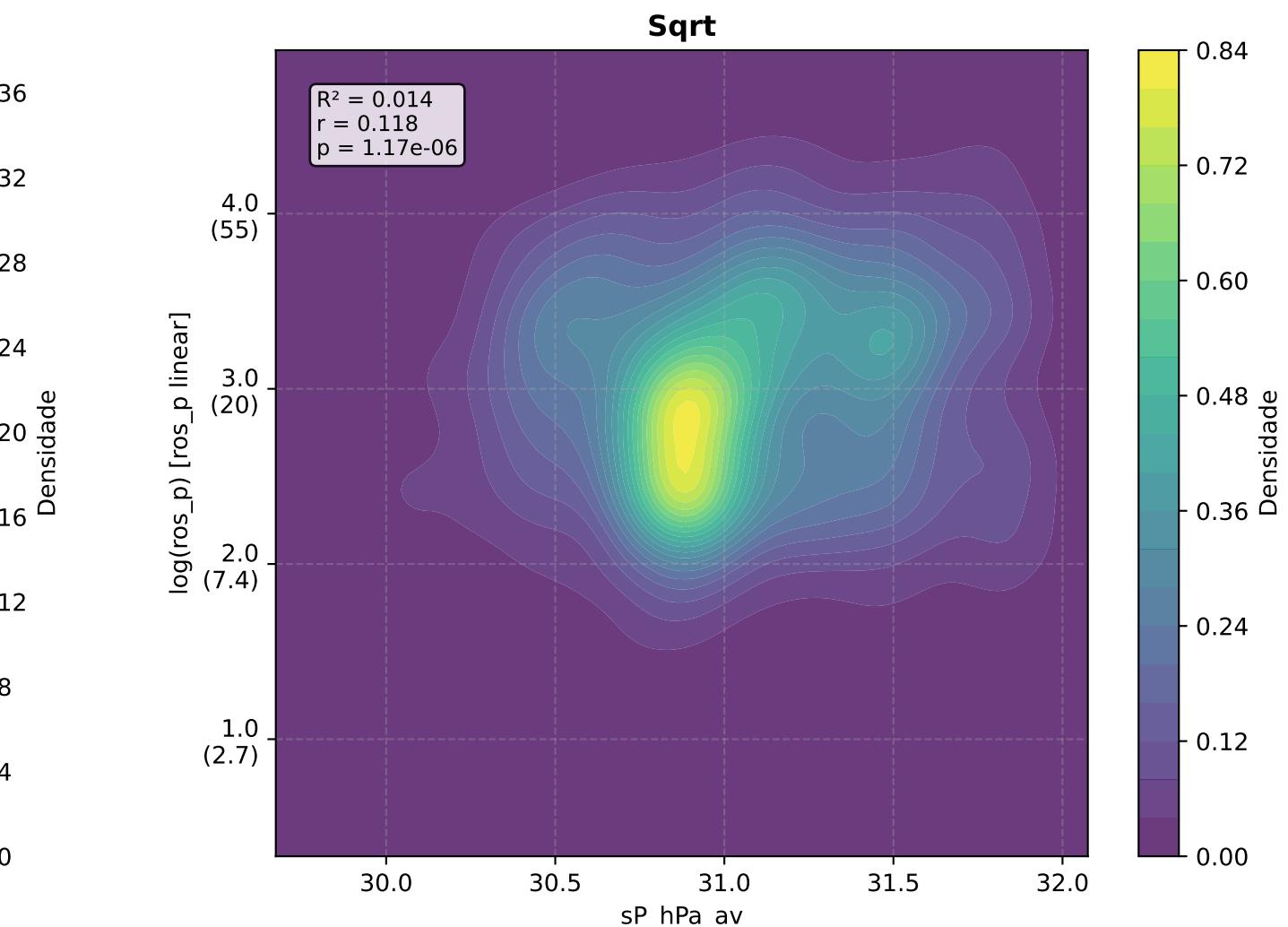
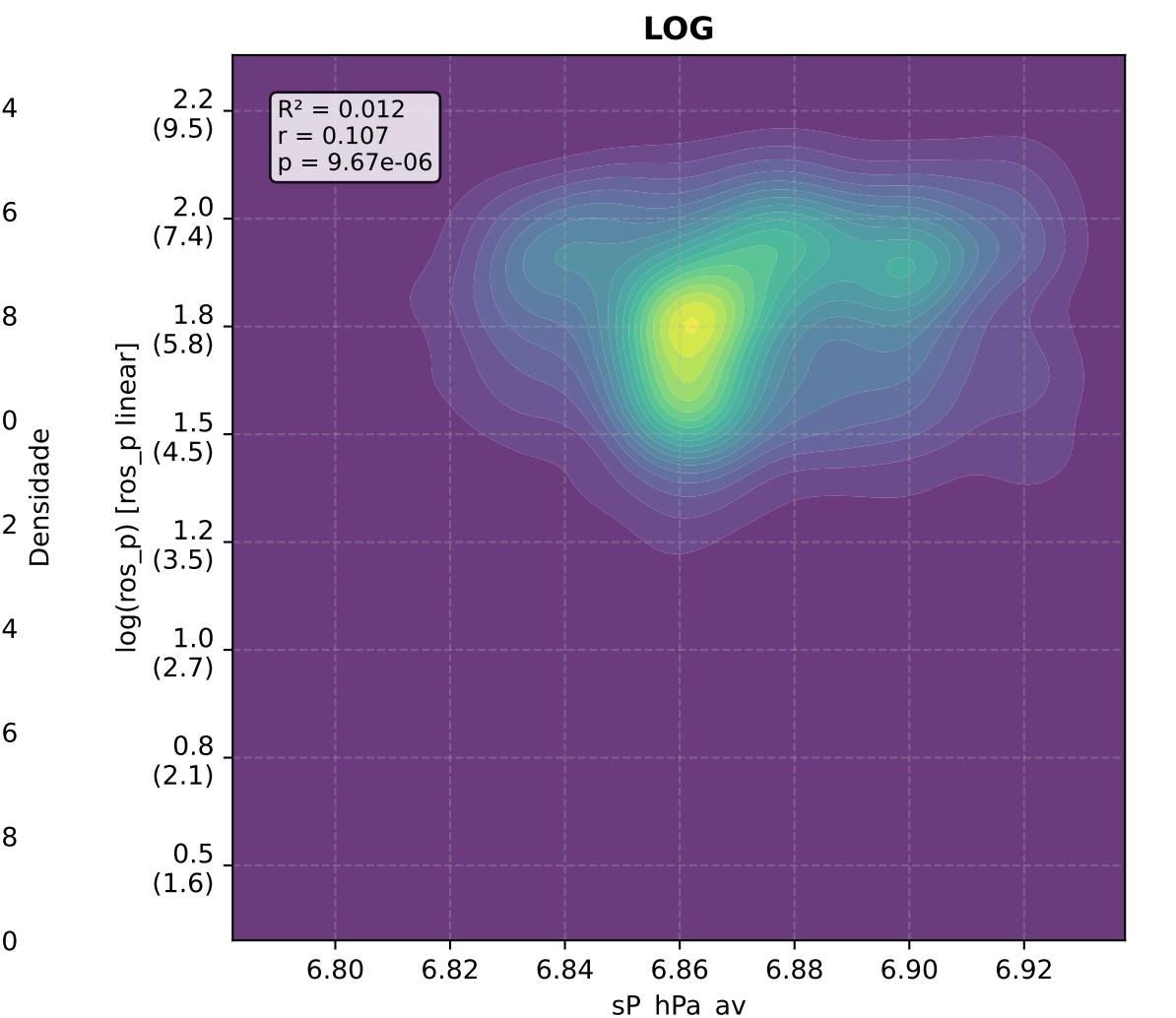
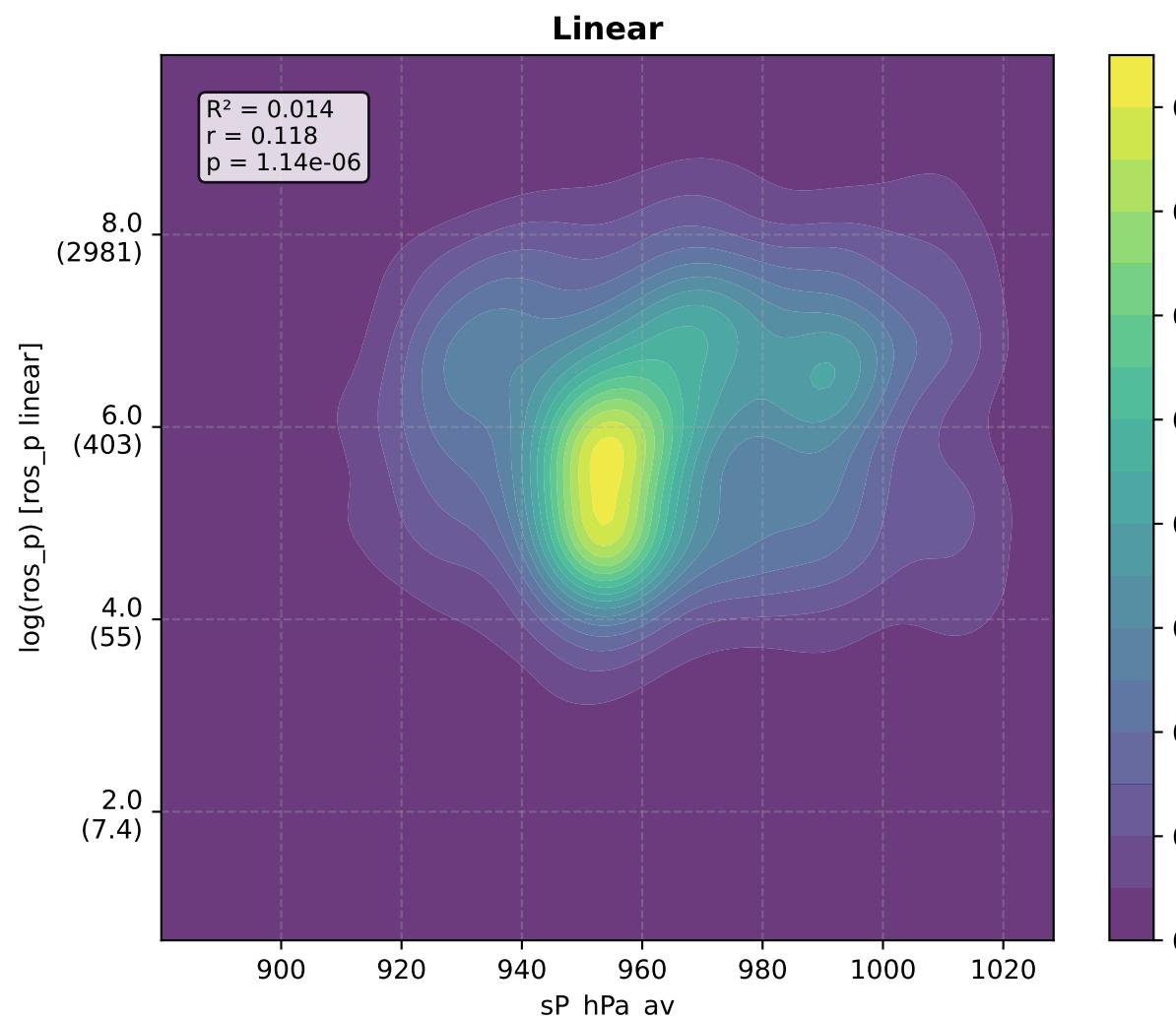
t_2m_C_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



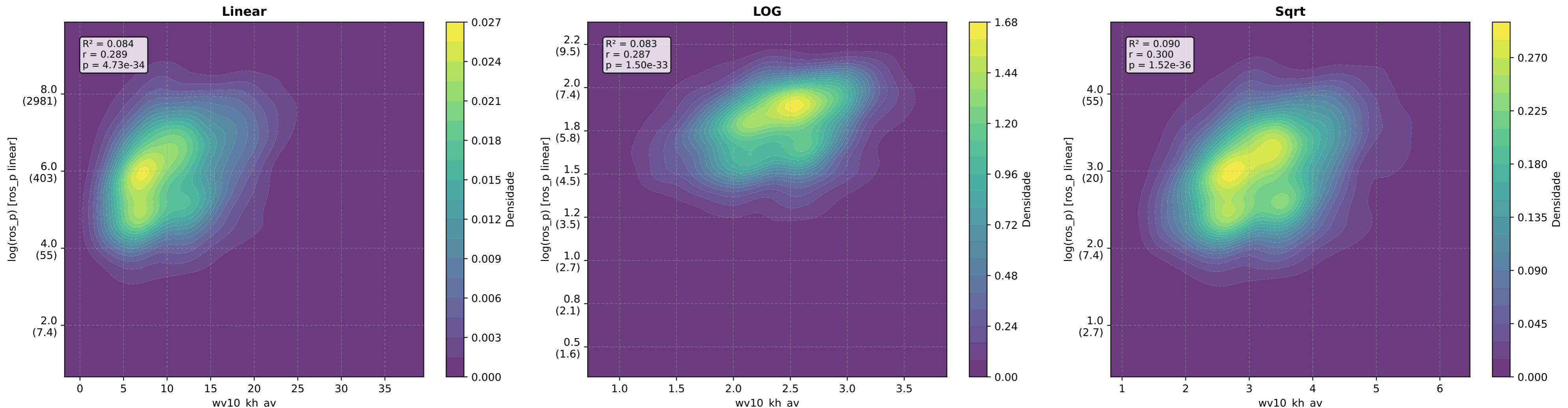
d_2m_C_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



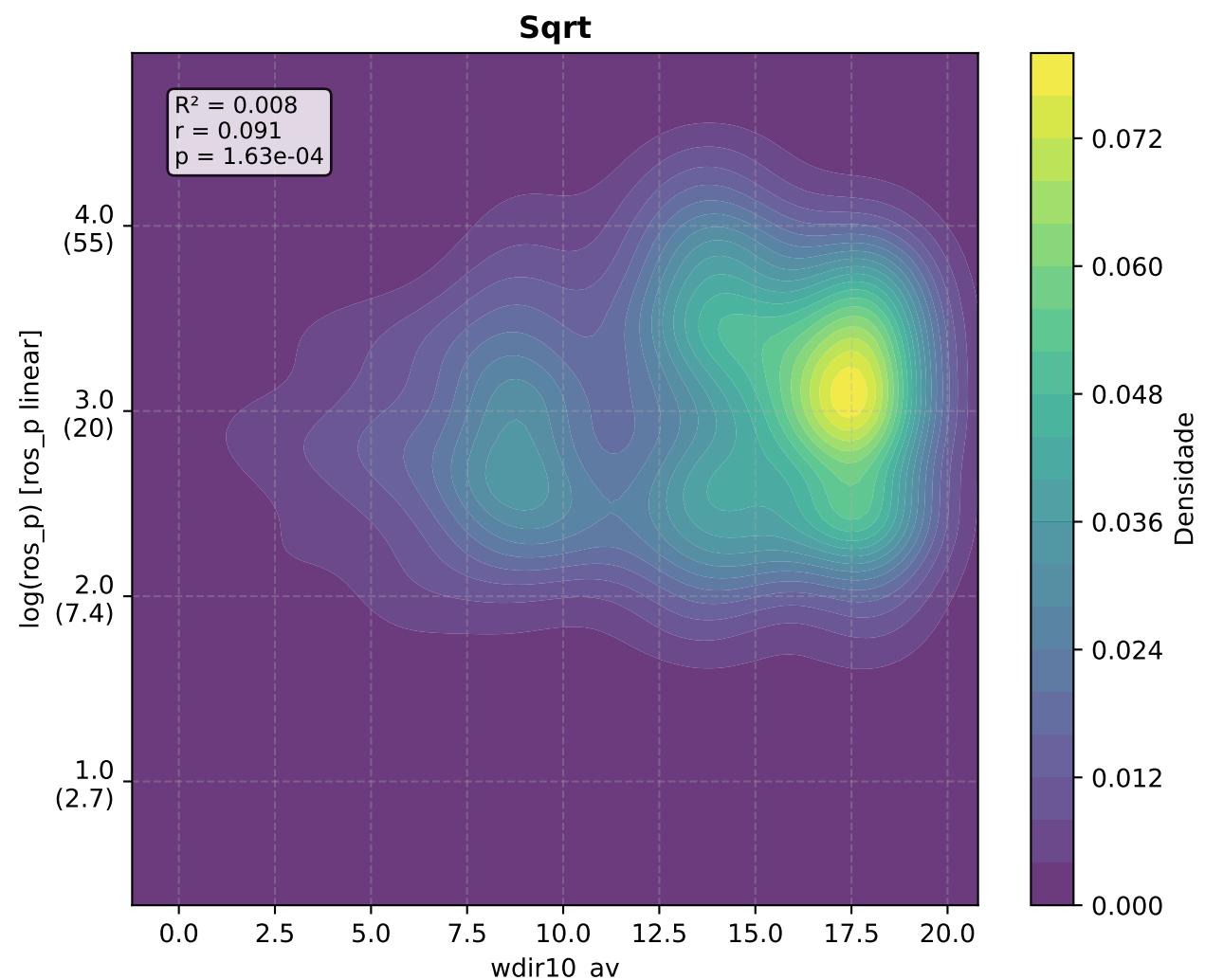
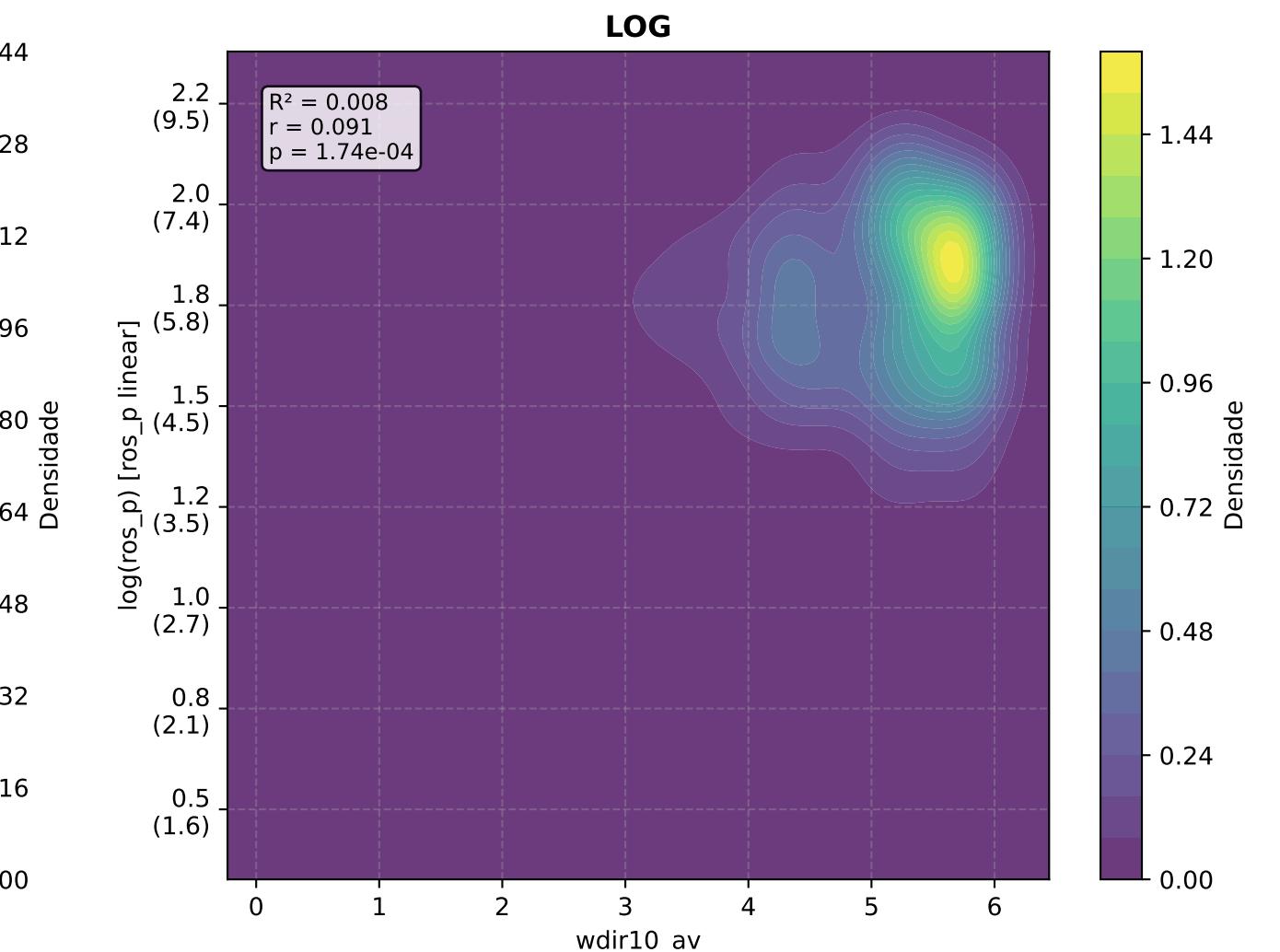
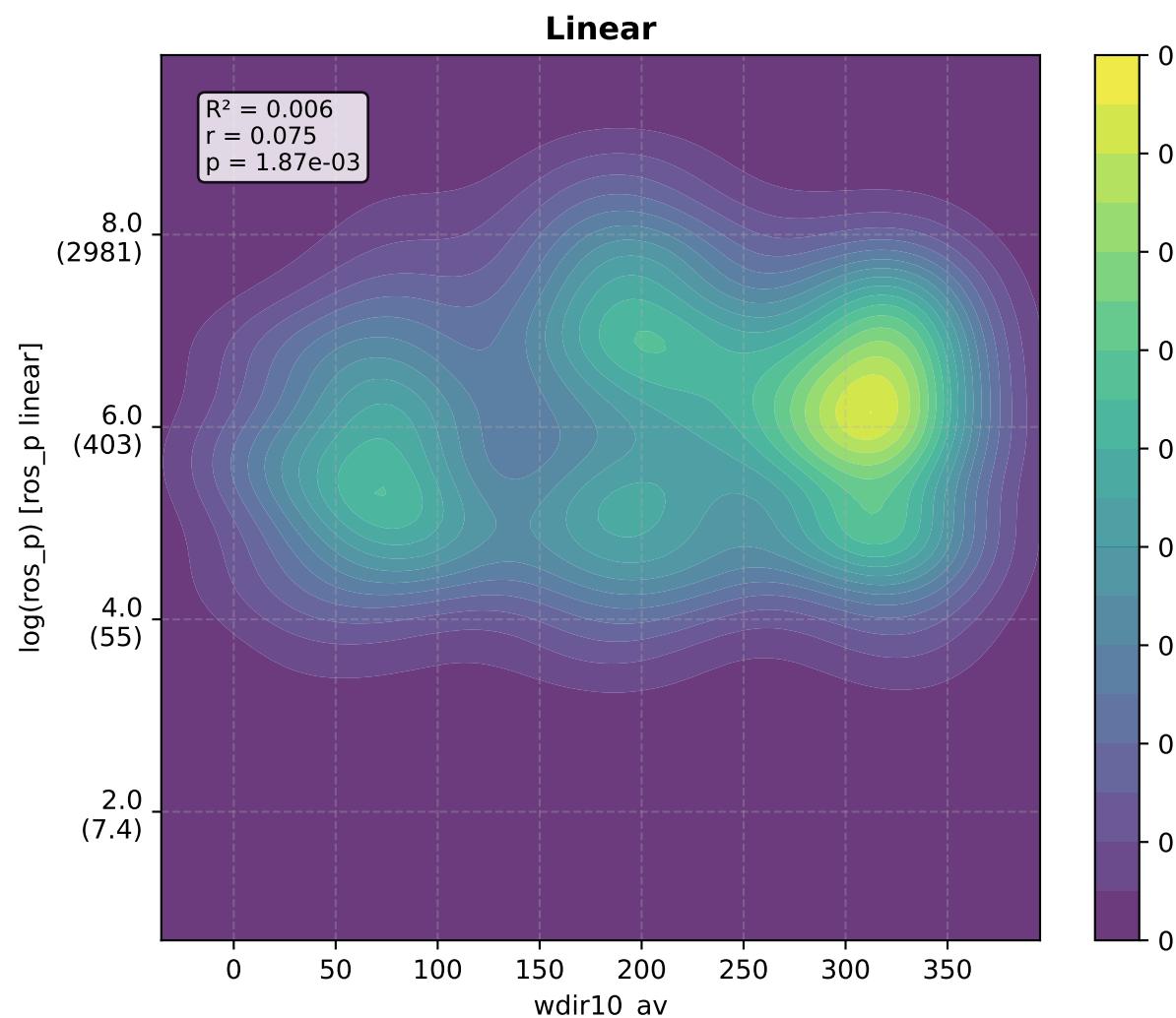
sP_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



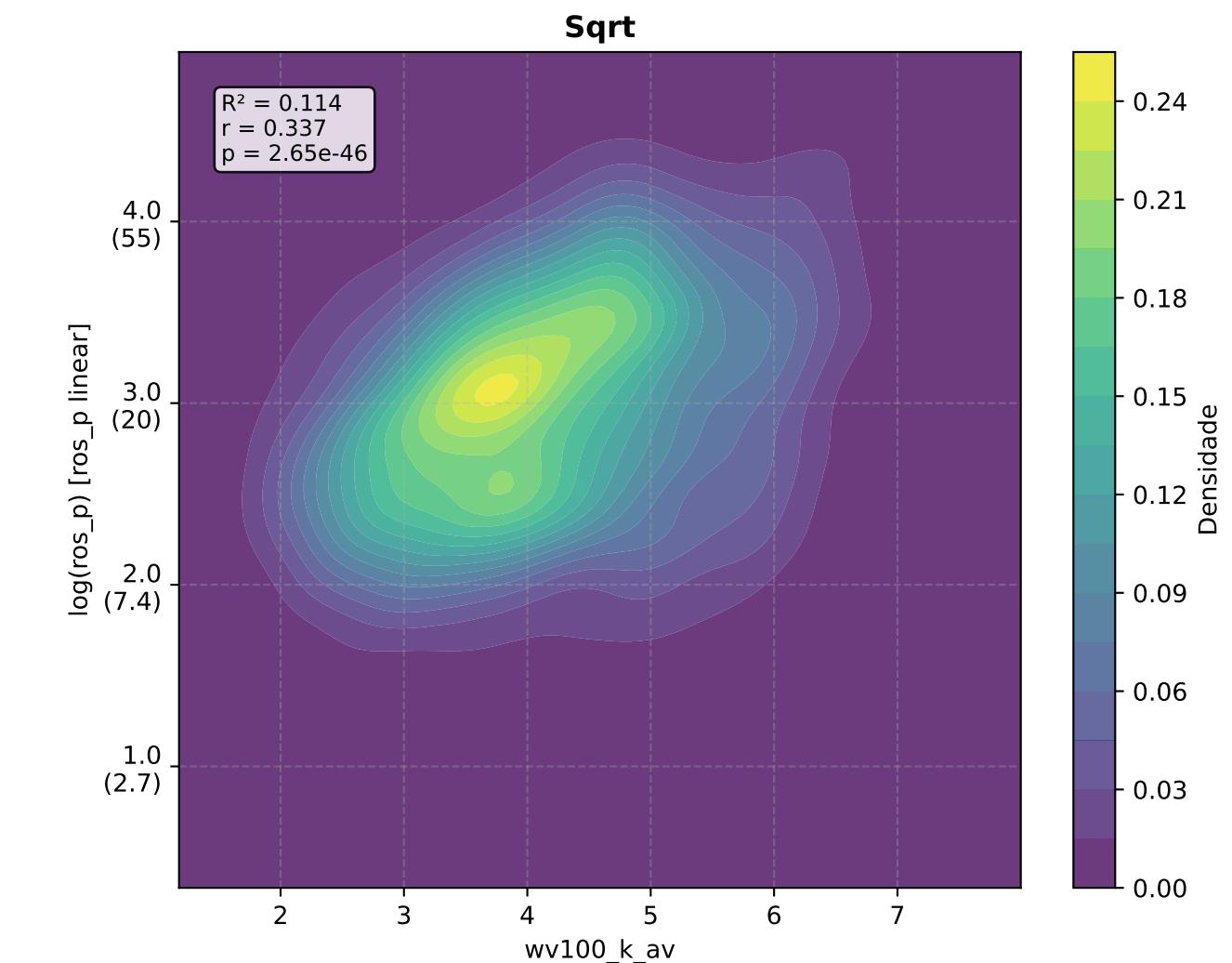
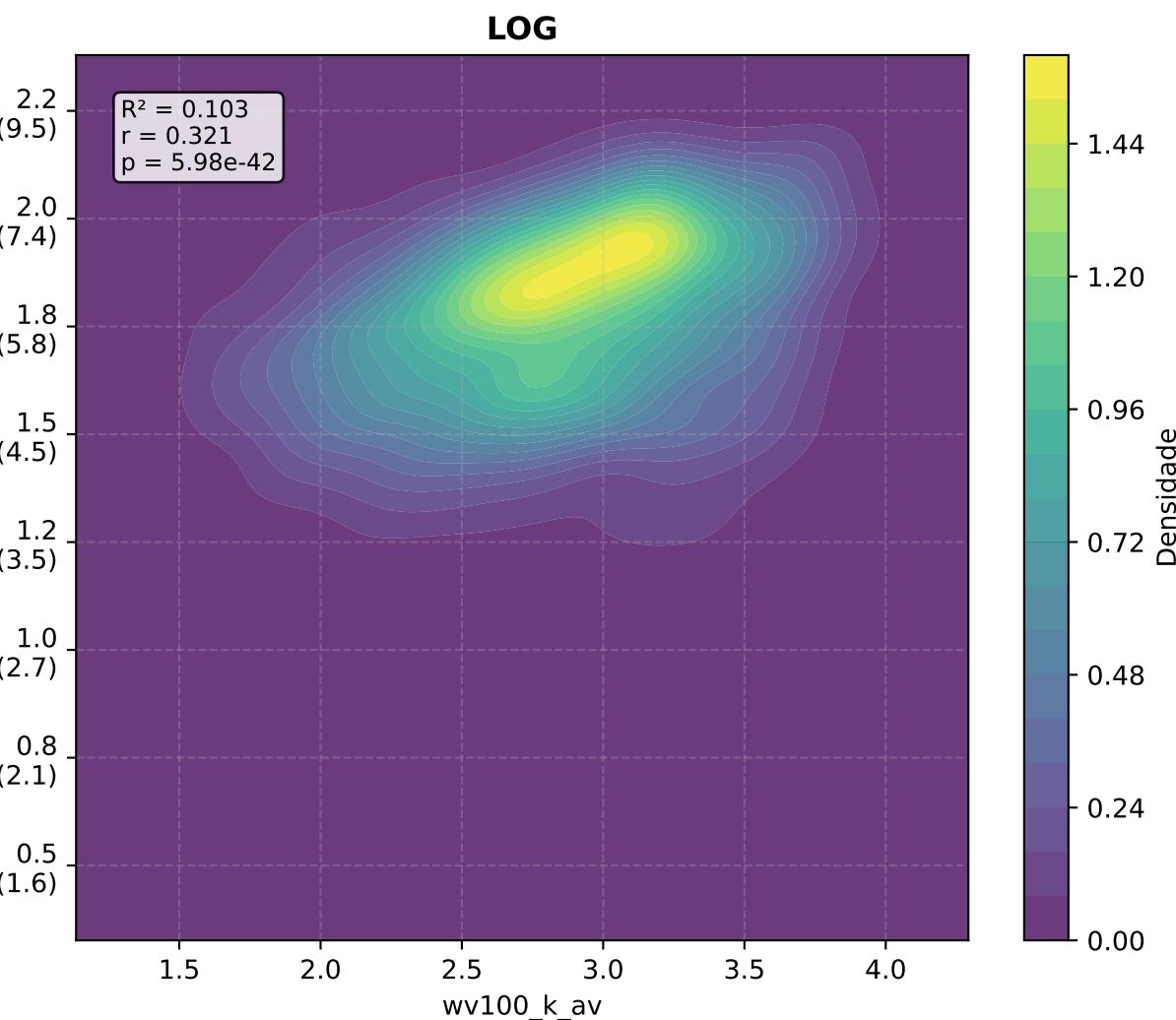
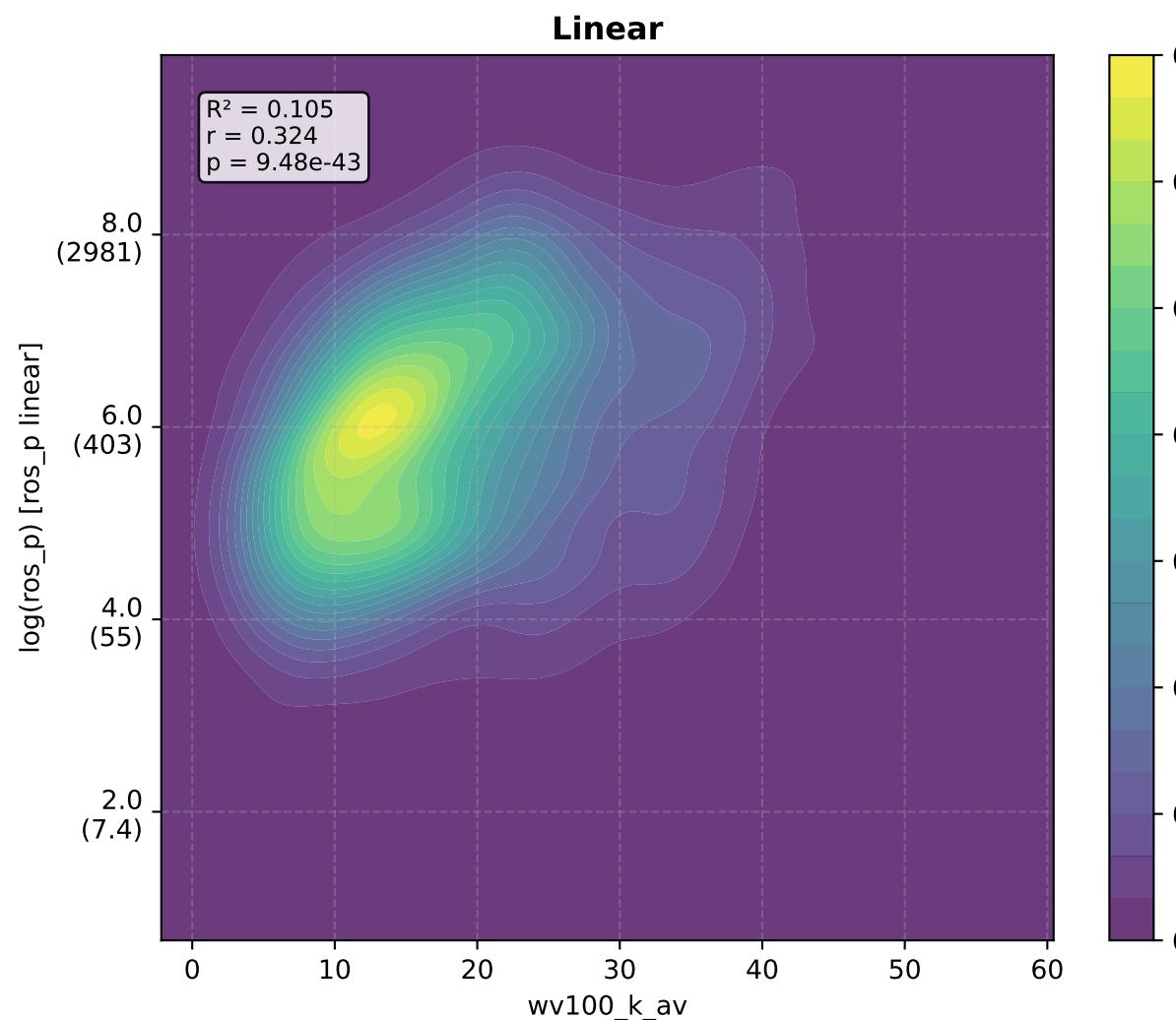
wv10_kh_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



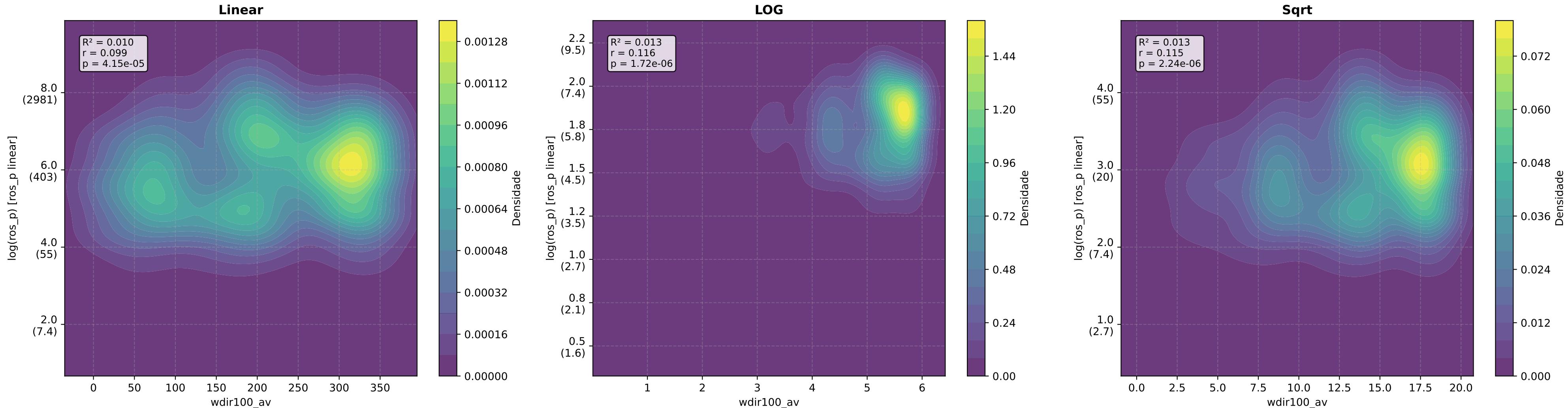
wdir10_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



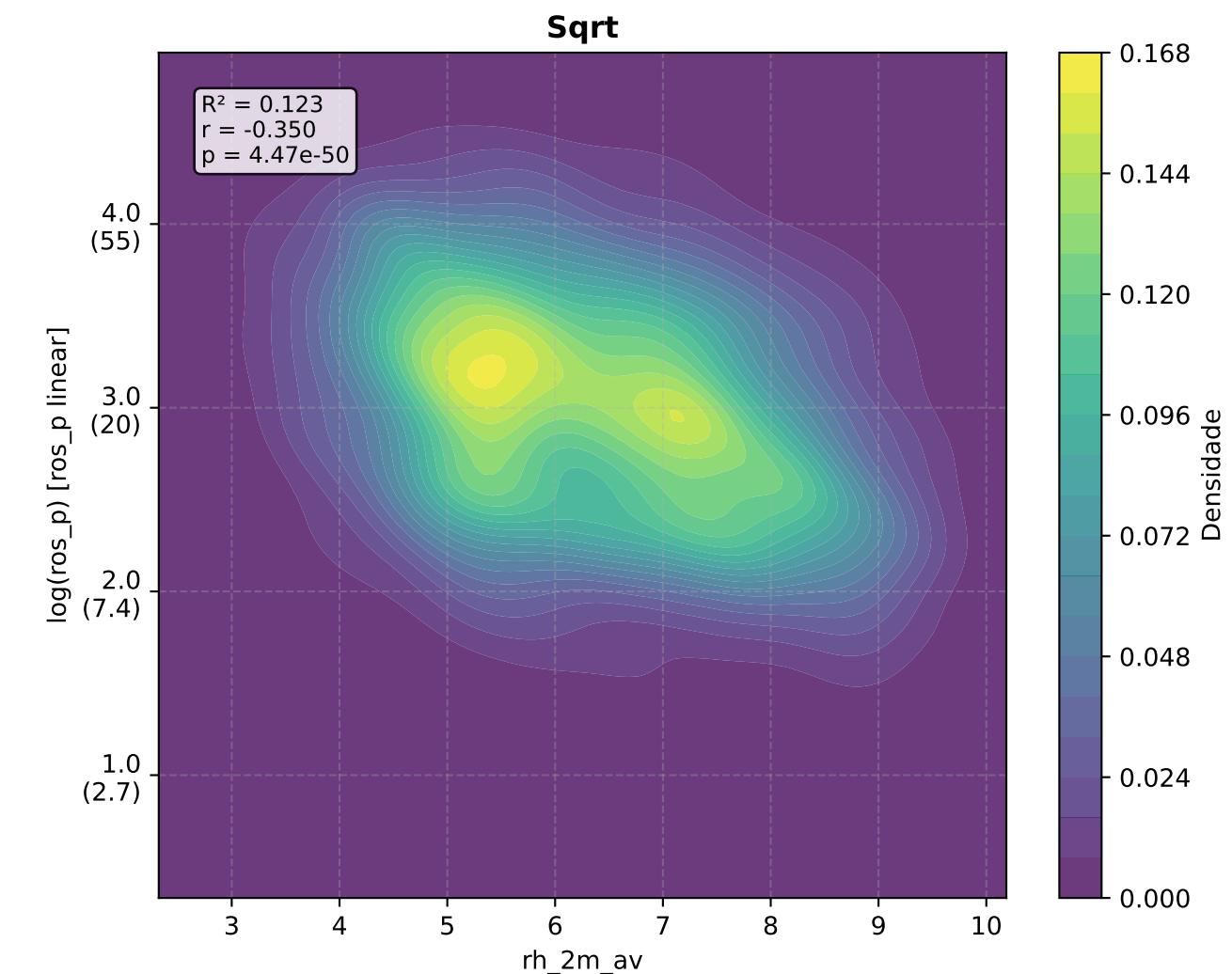
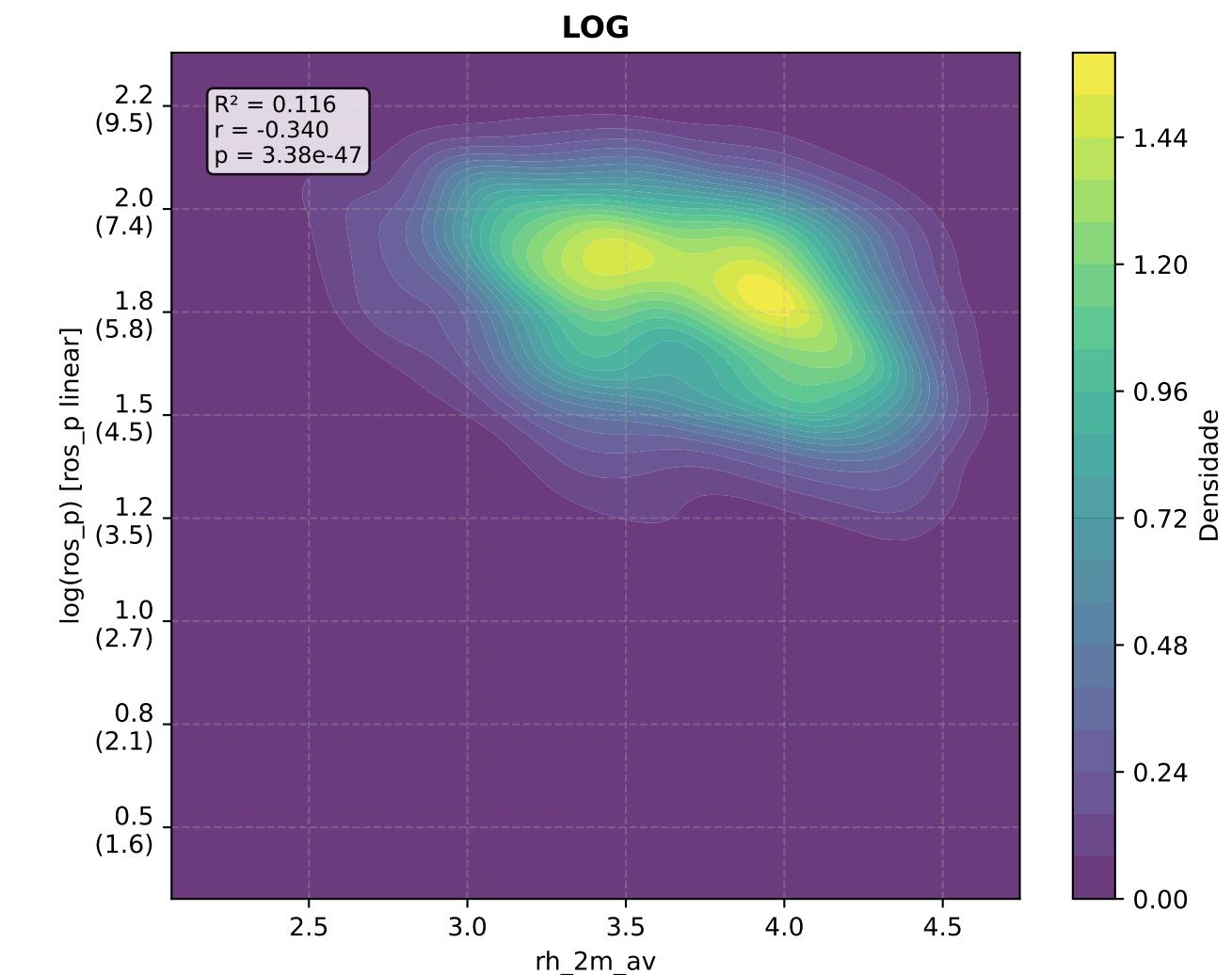
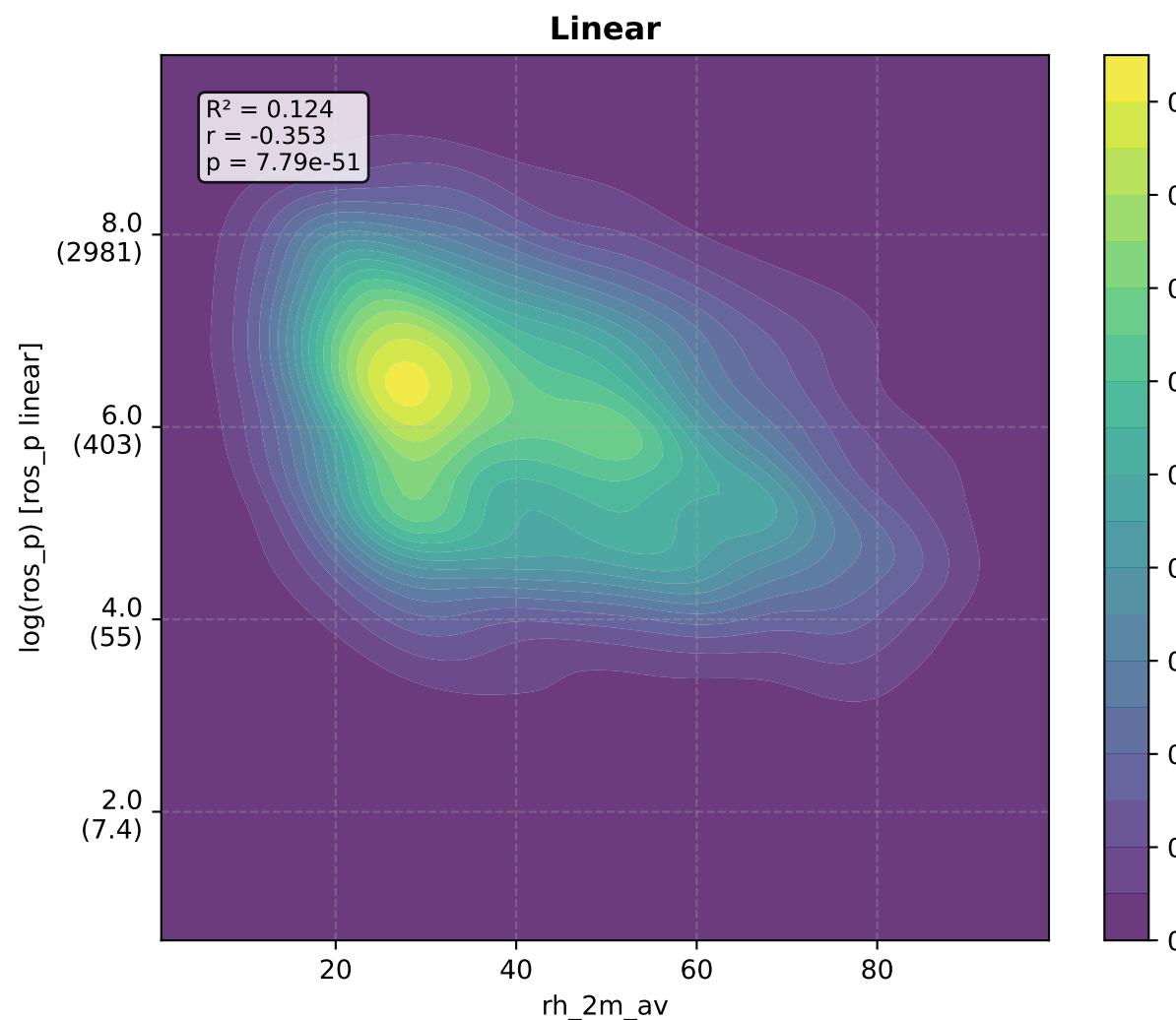
wv100_k_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



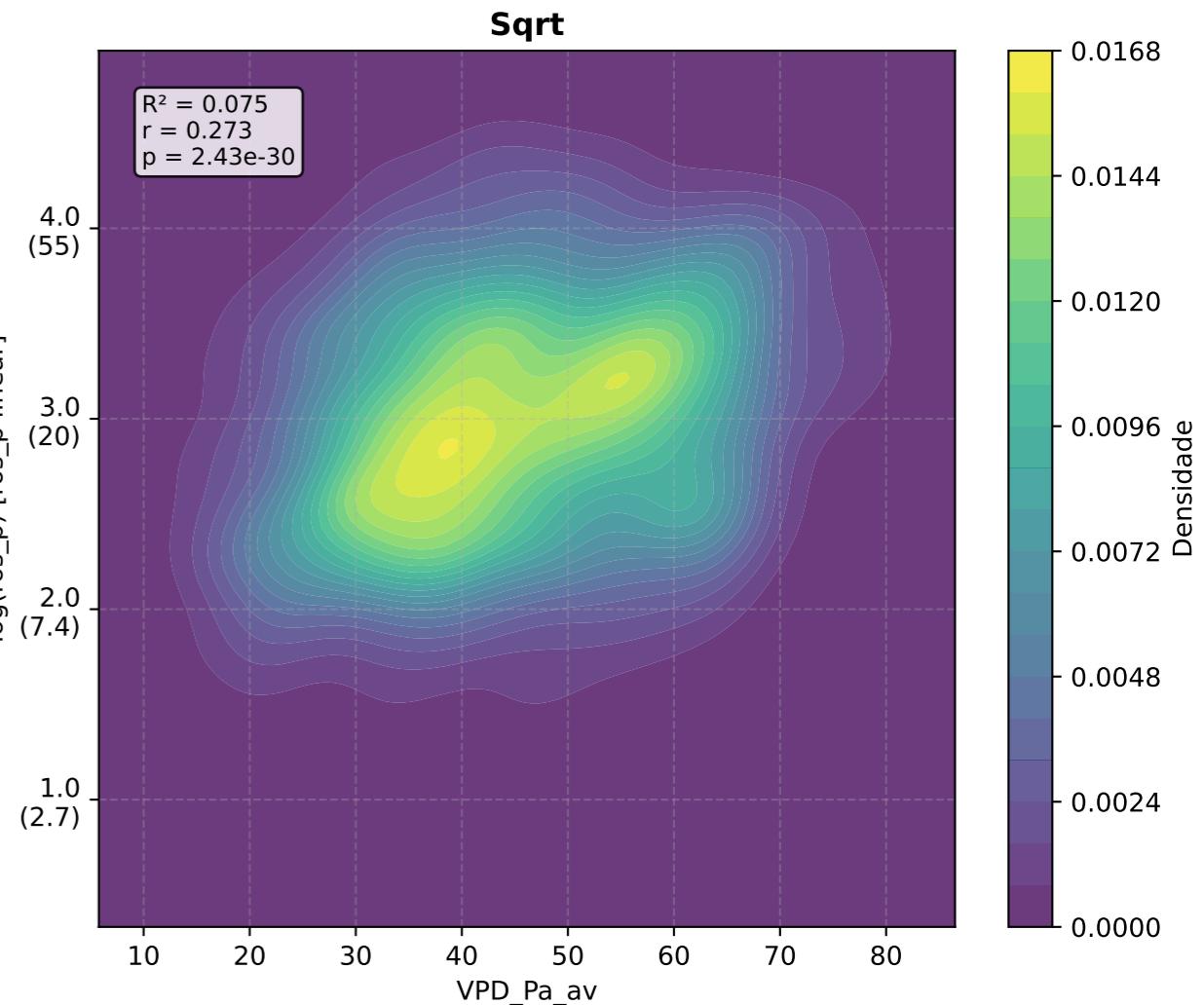
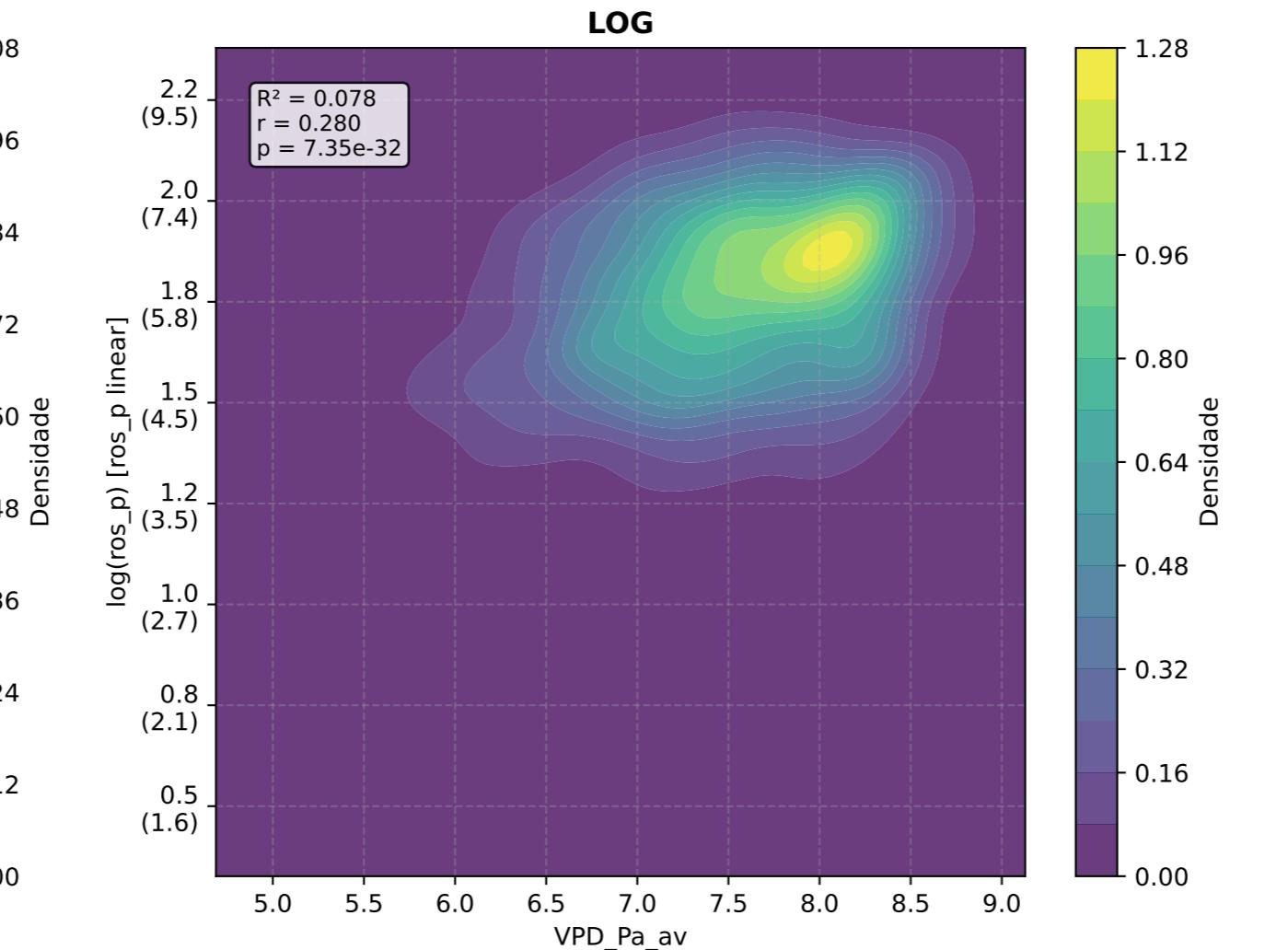
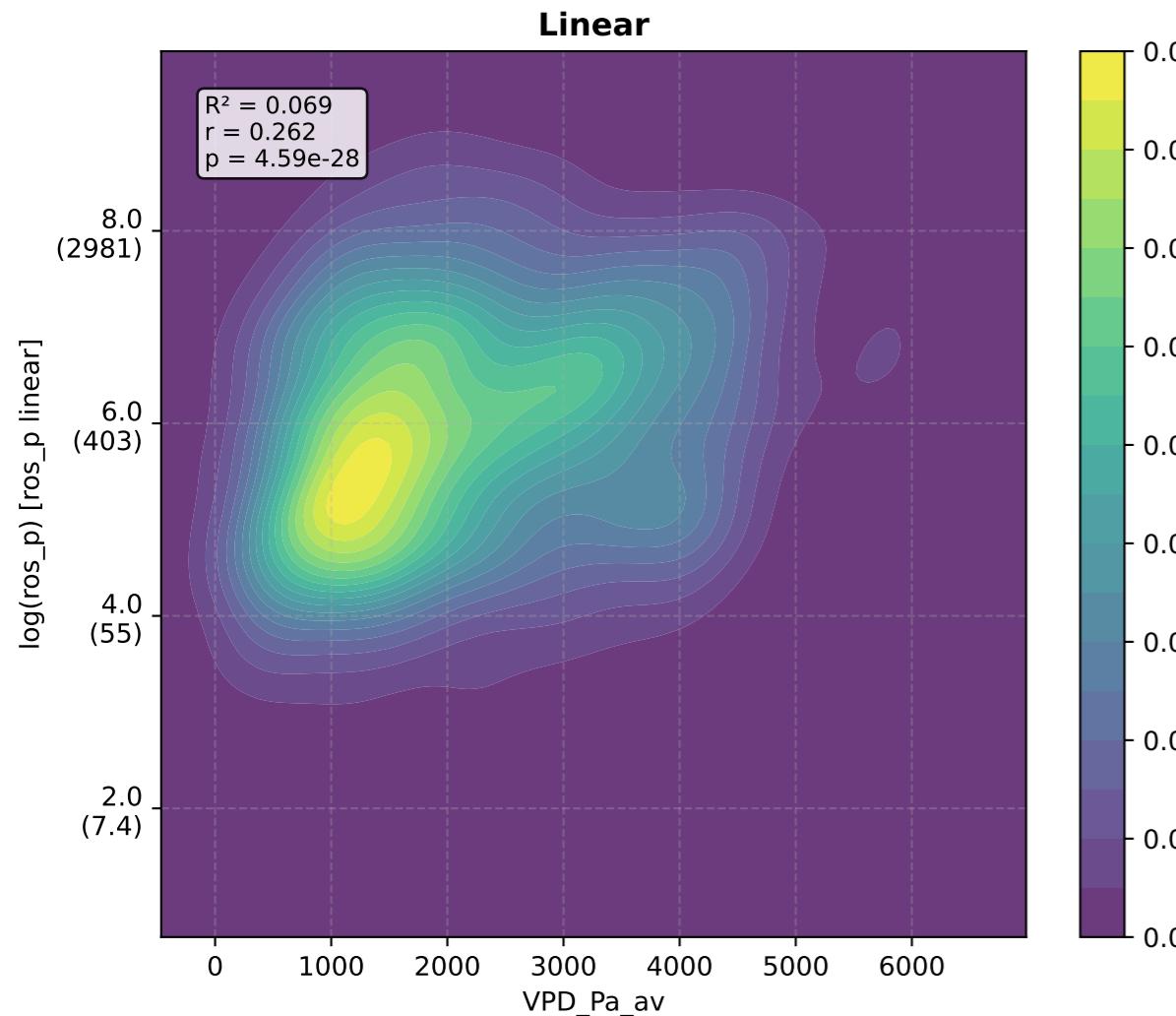
wdir100_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



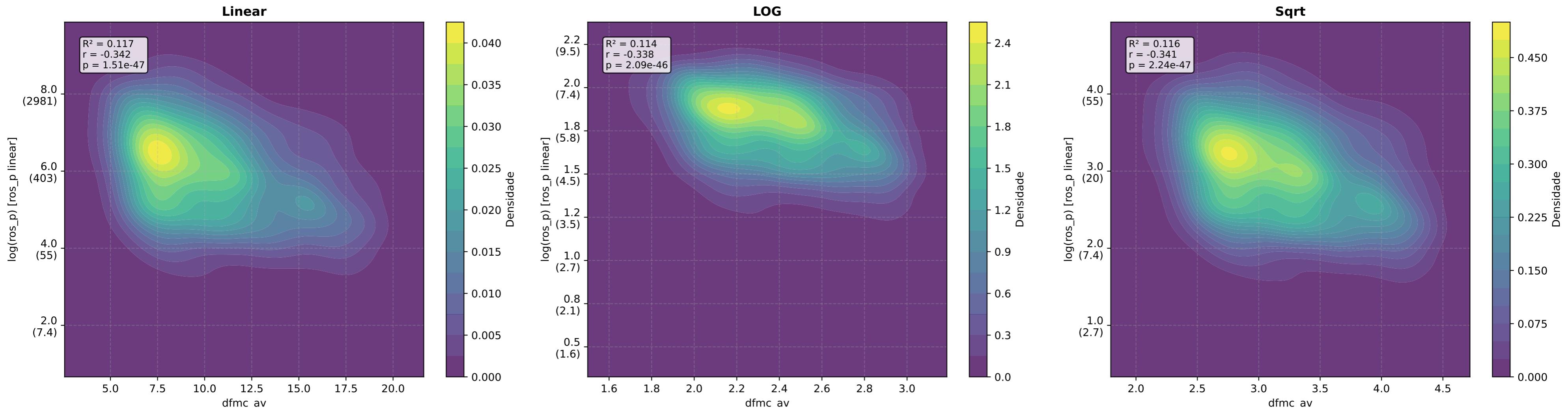
rh_2m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



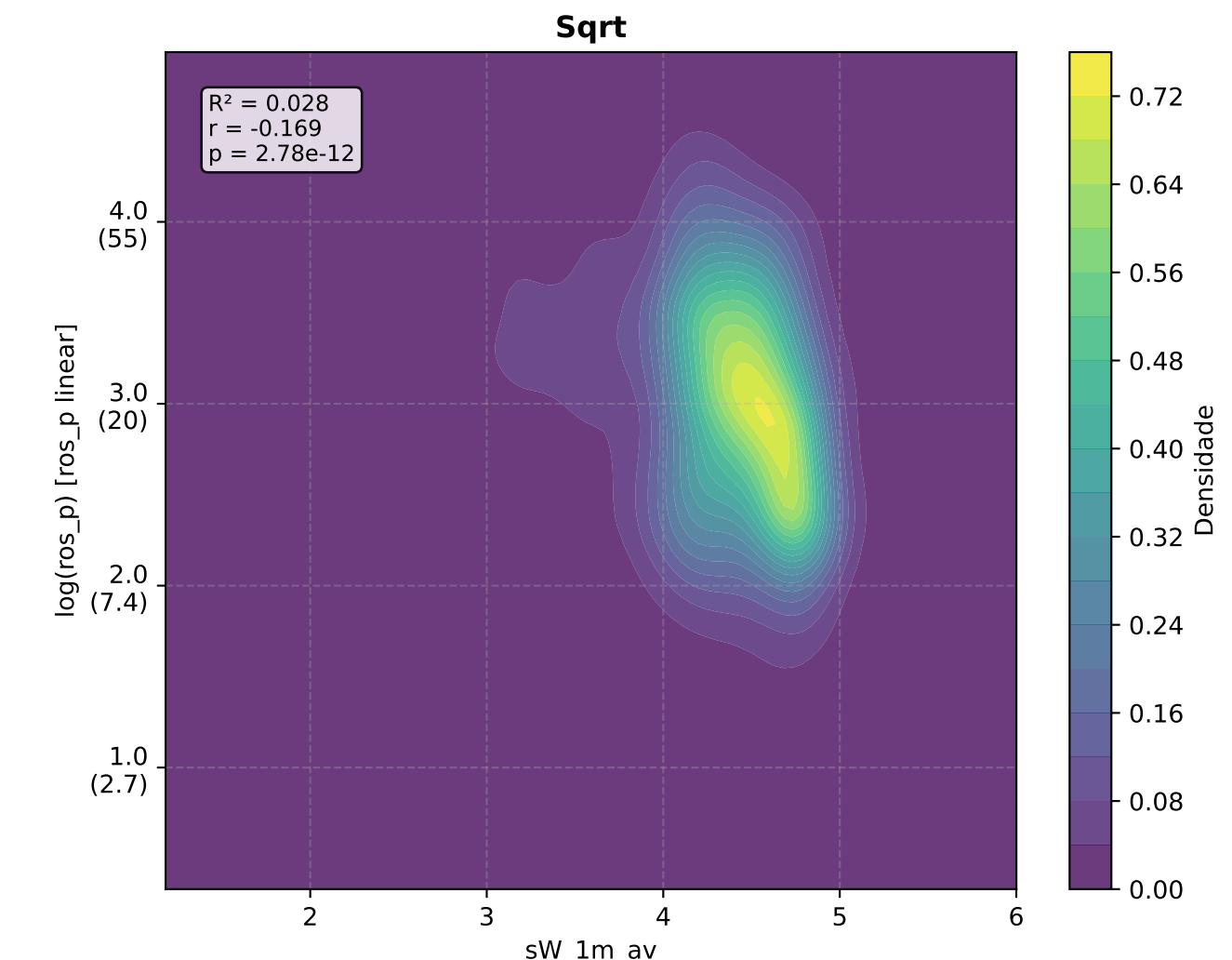
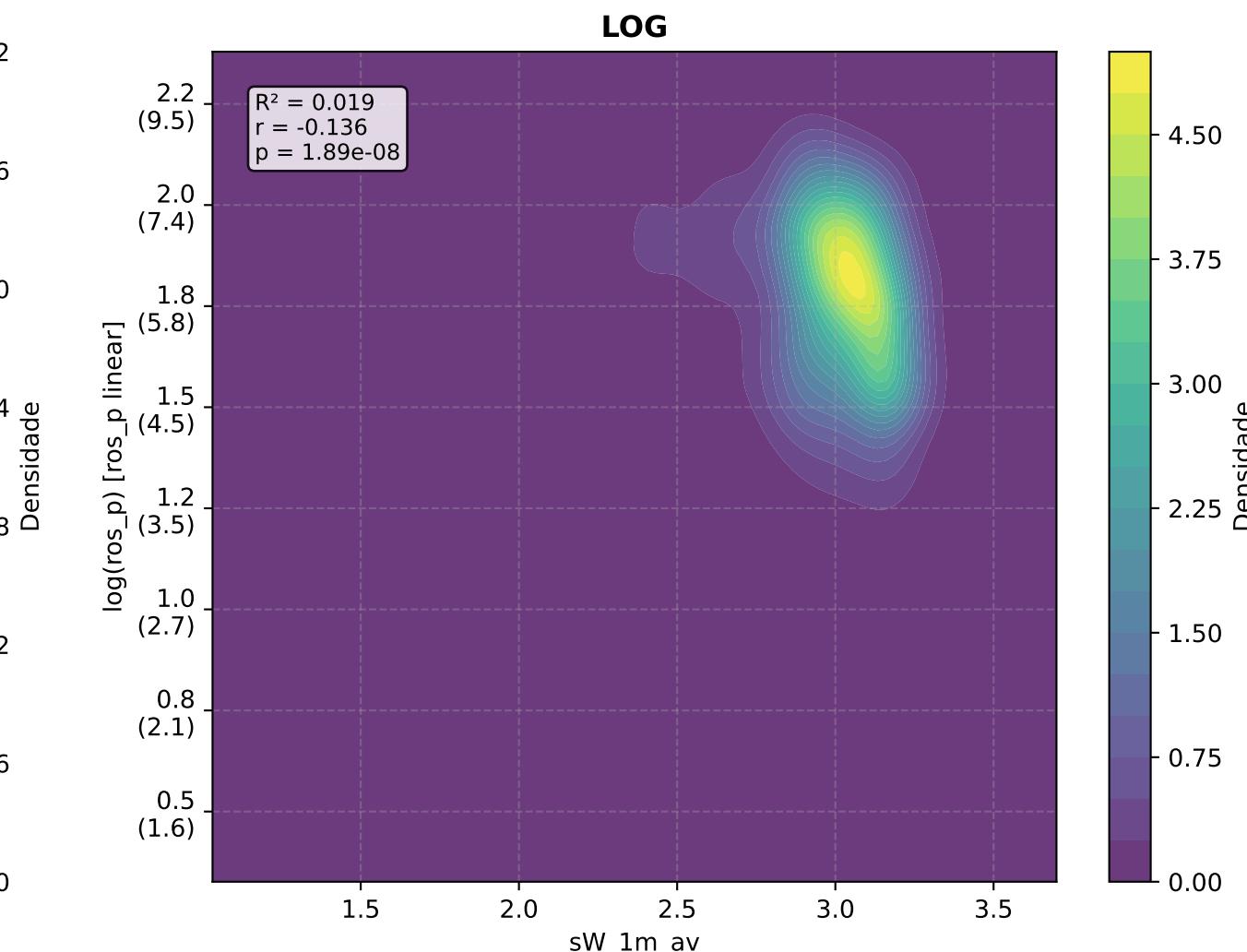
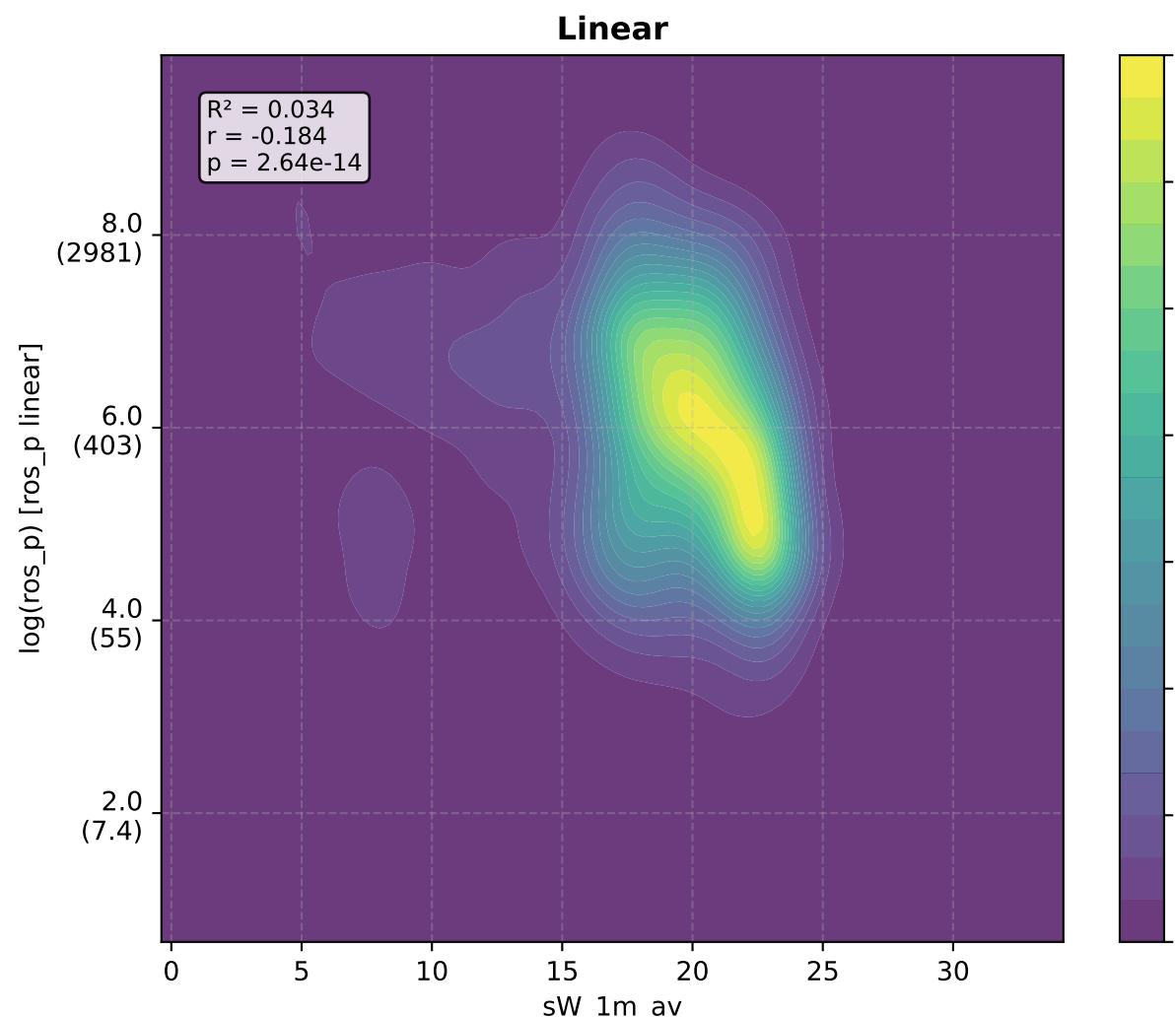
VPD_Pa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



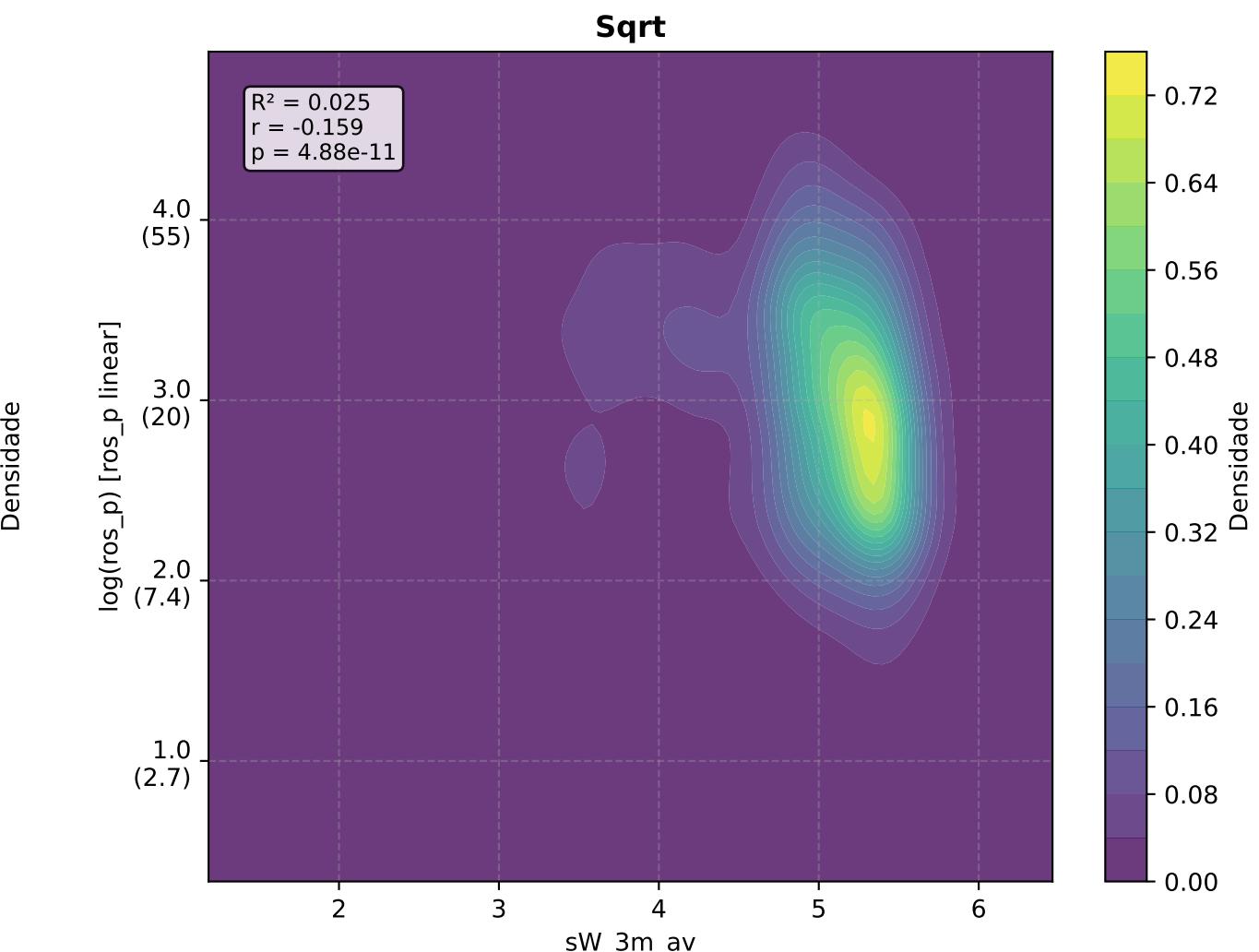
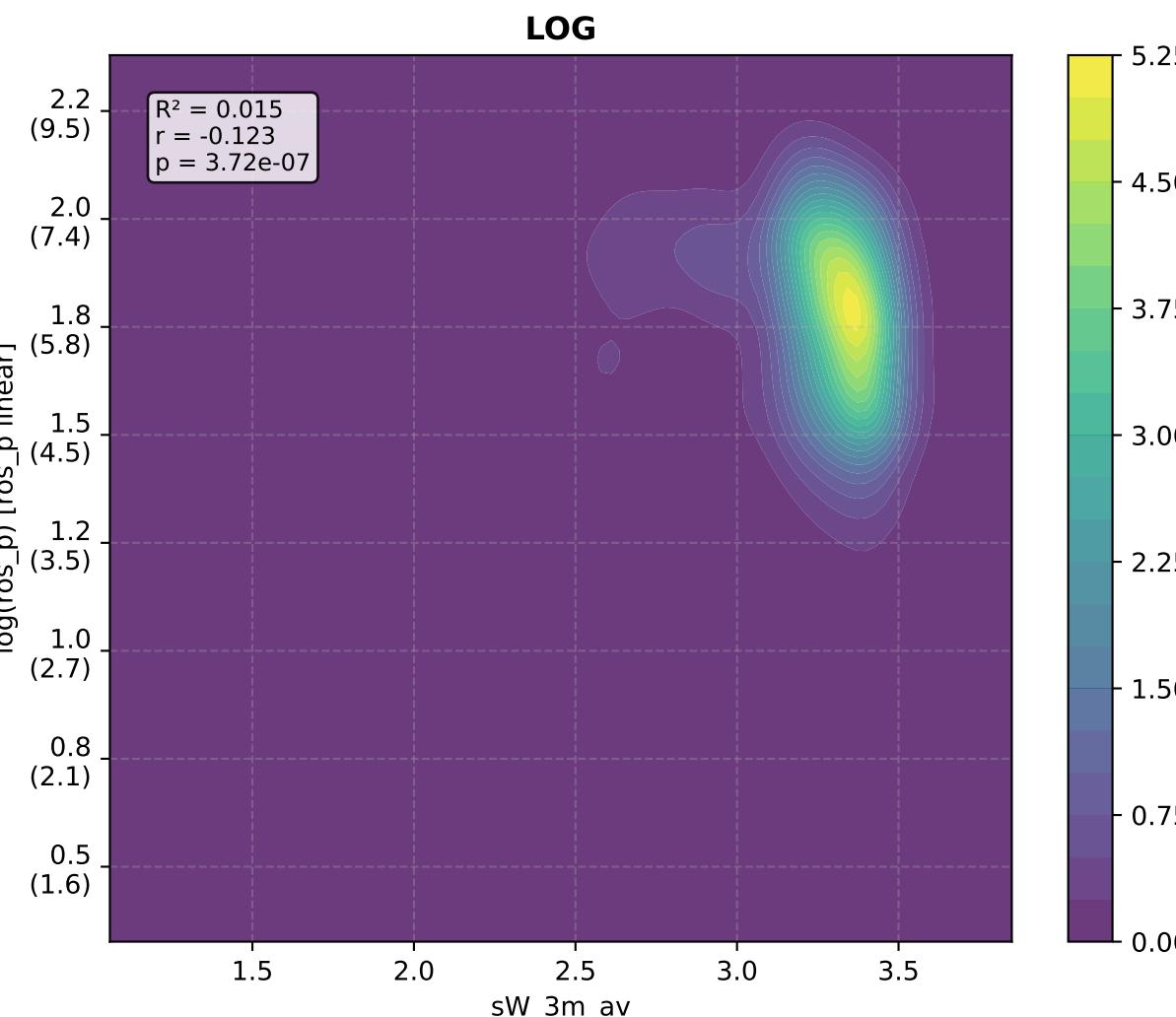
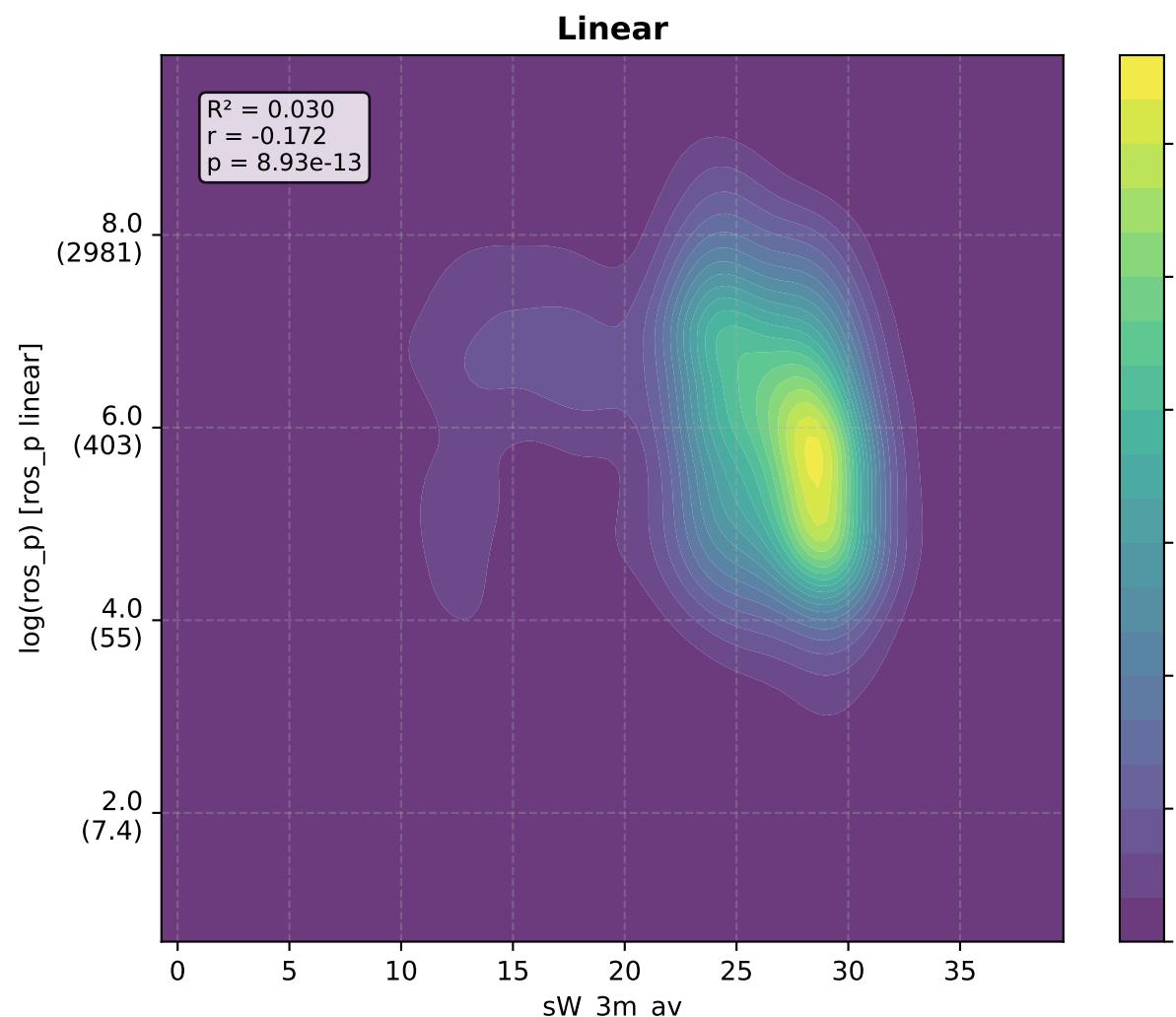
dfmc_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



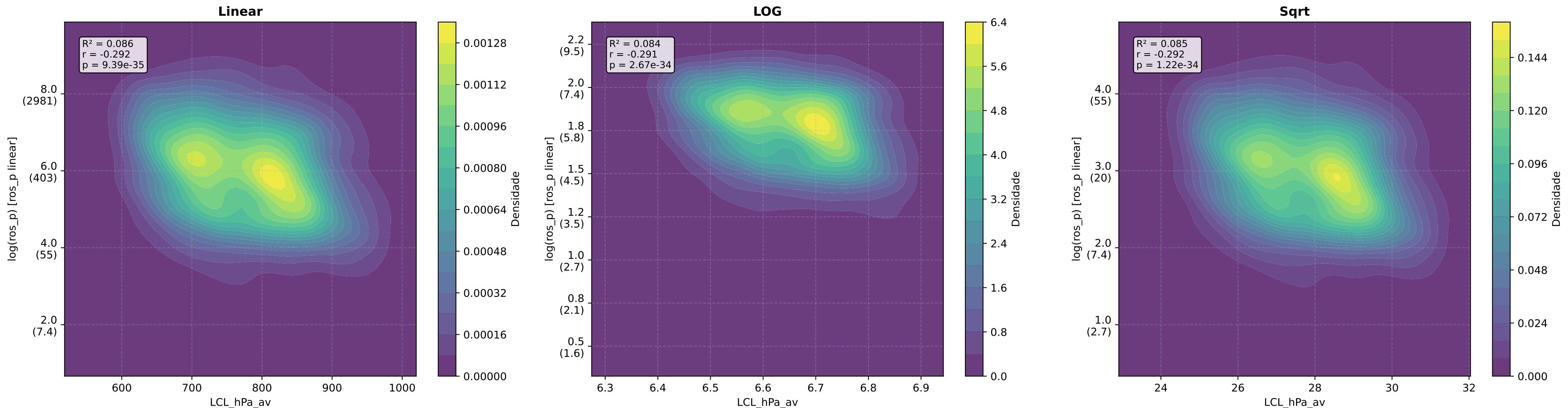
sW_1m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



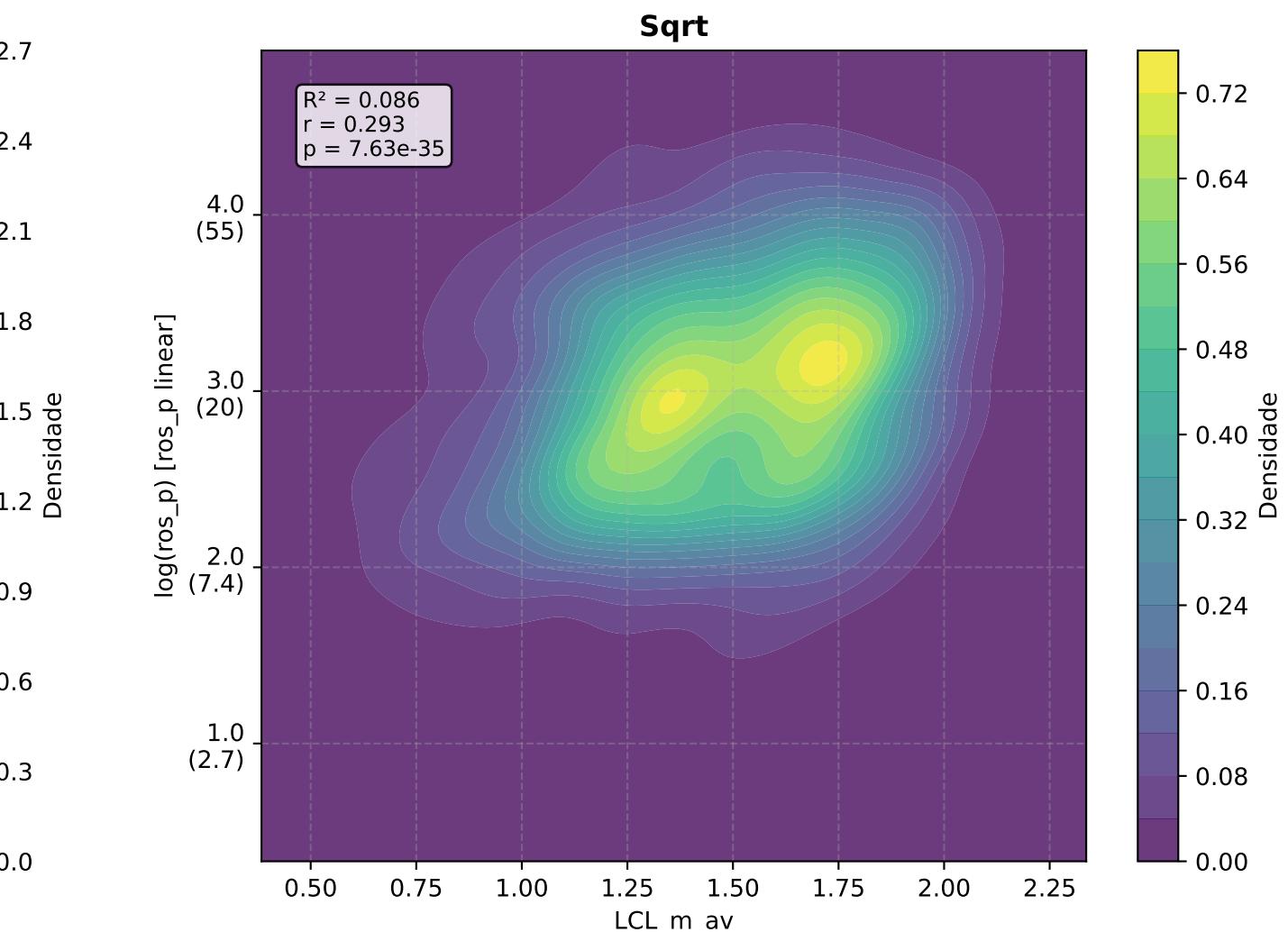
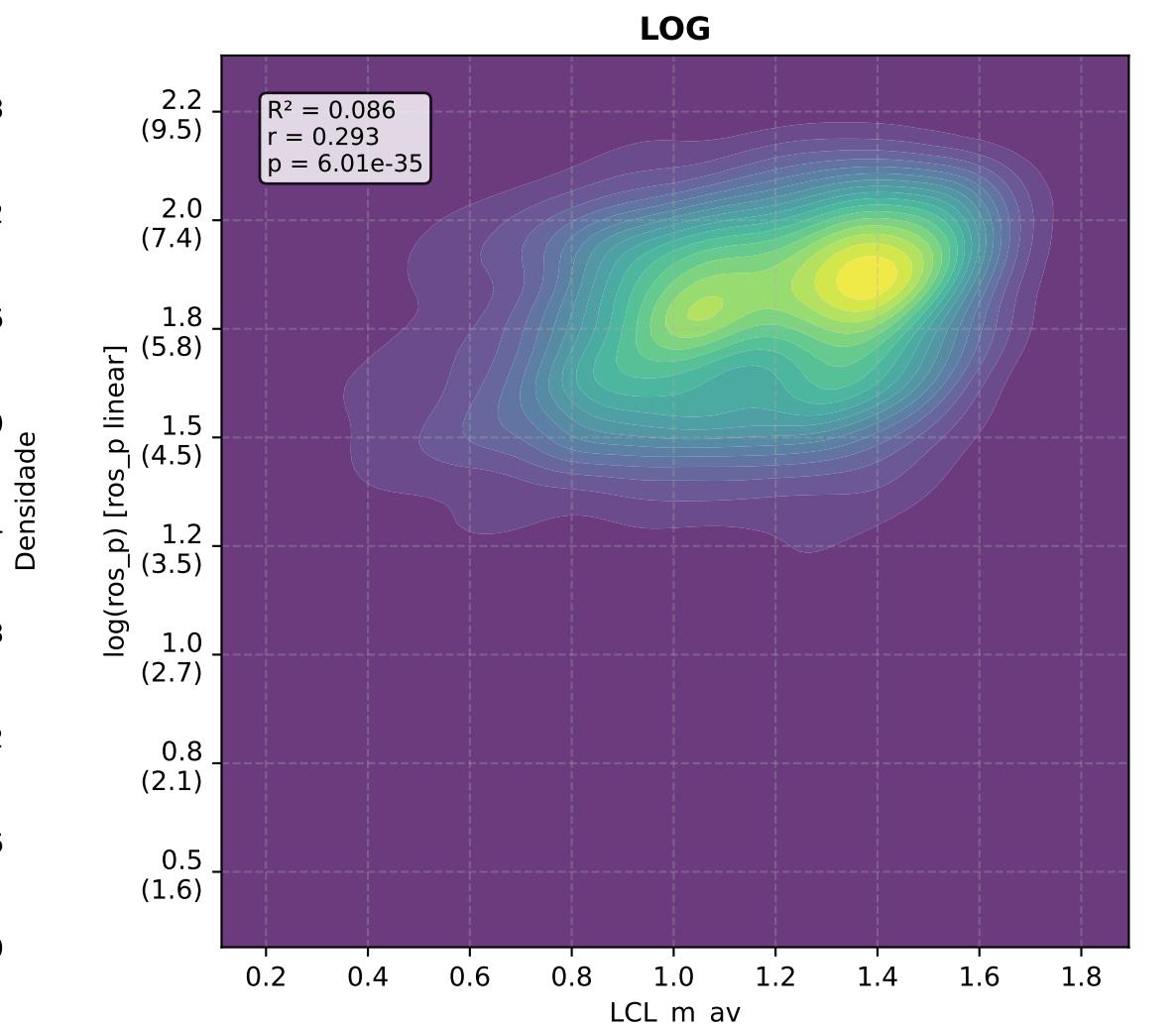
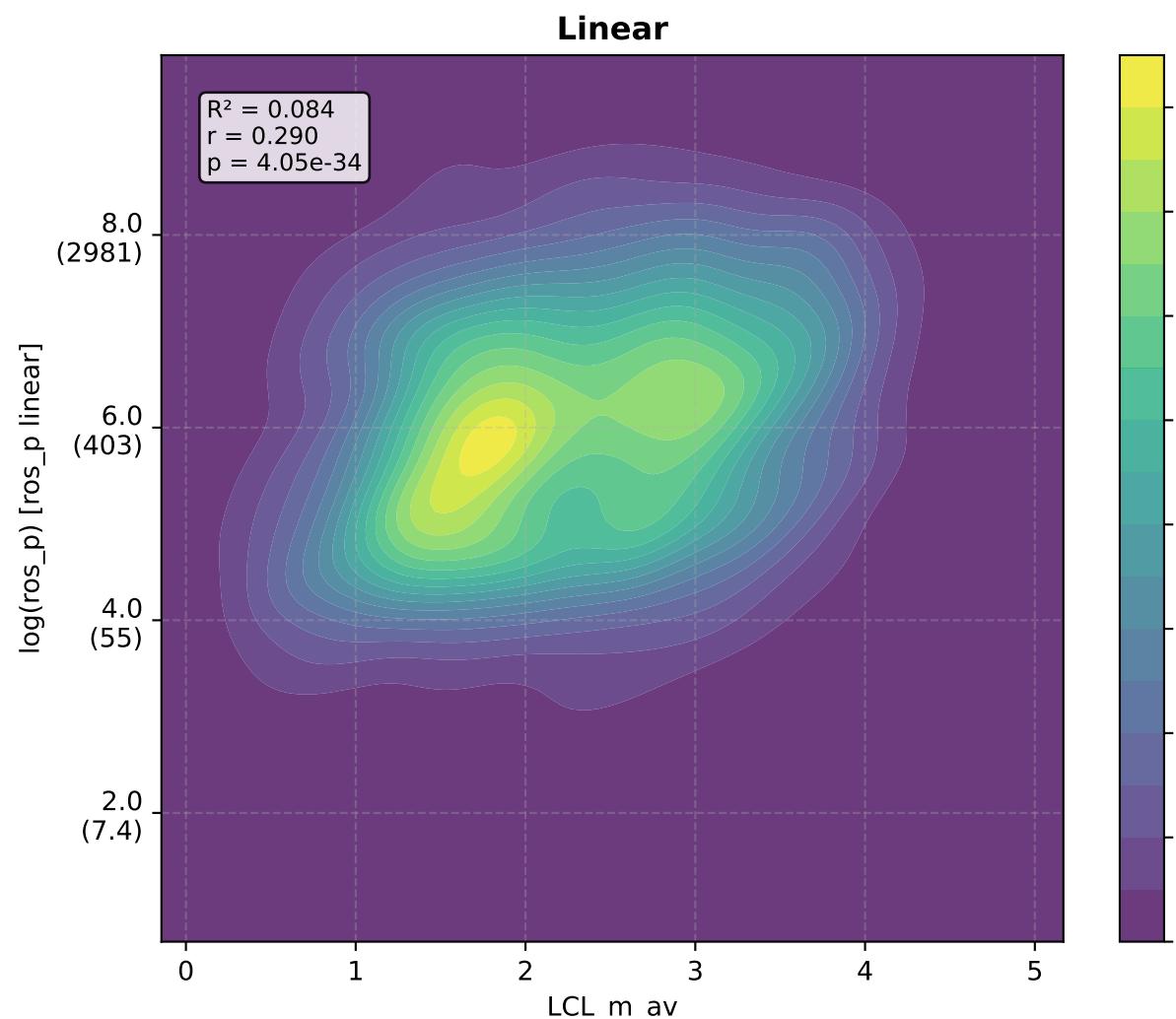
sW_3m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



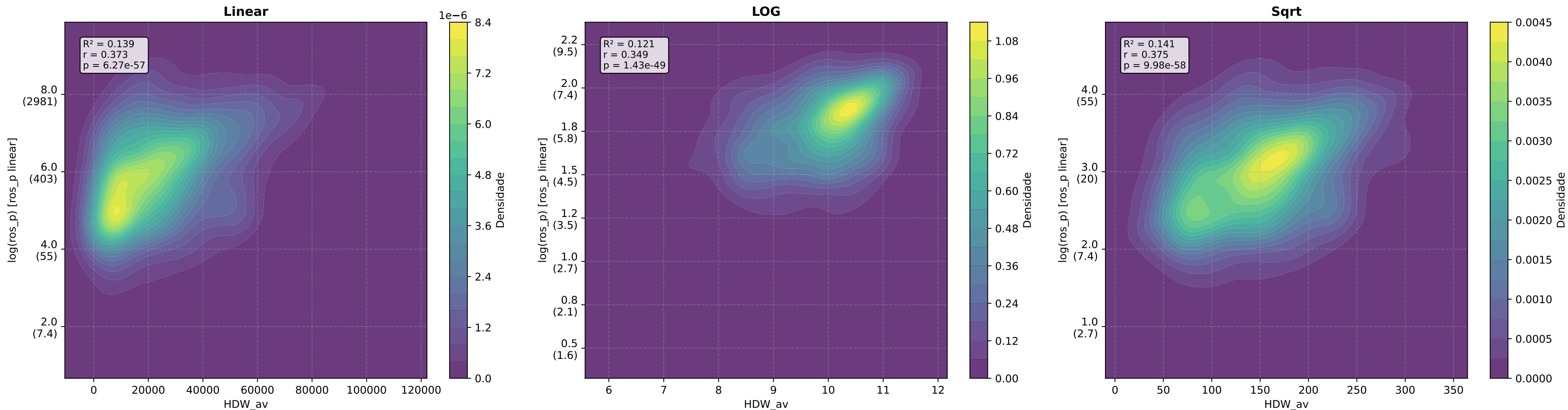
LCL_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



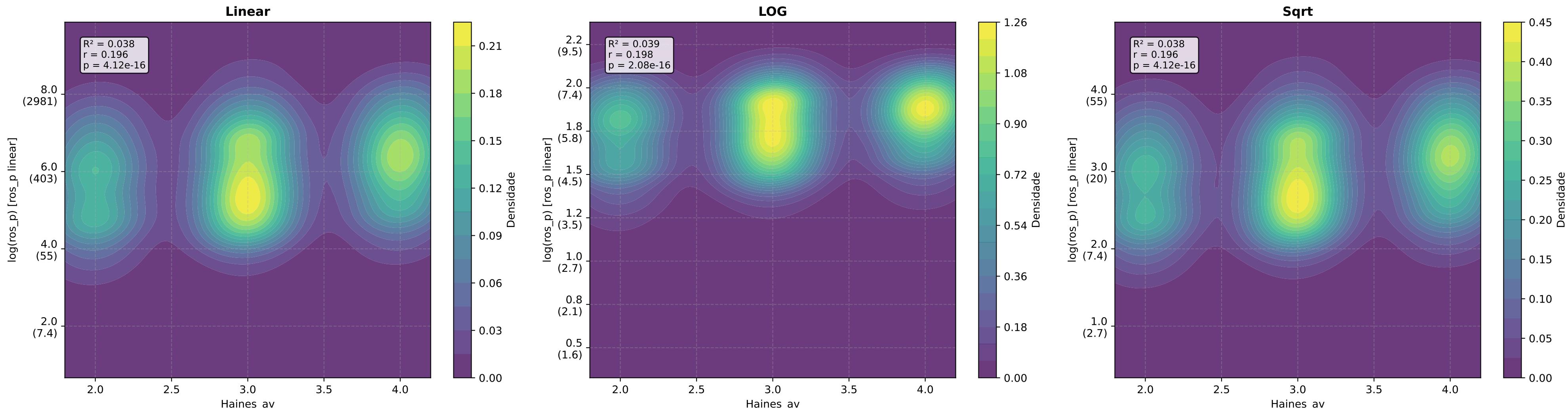
LCL_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



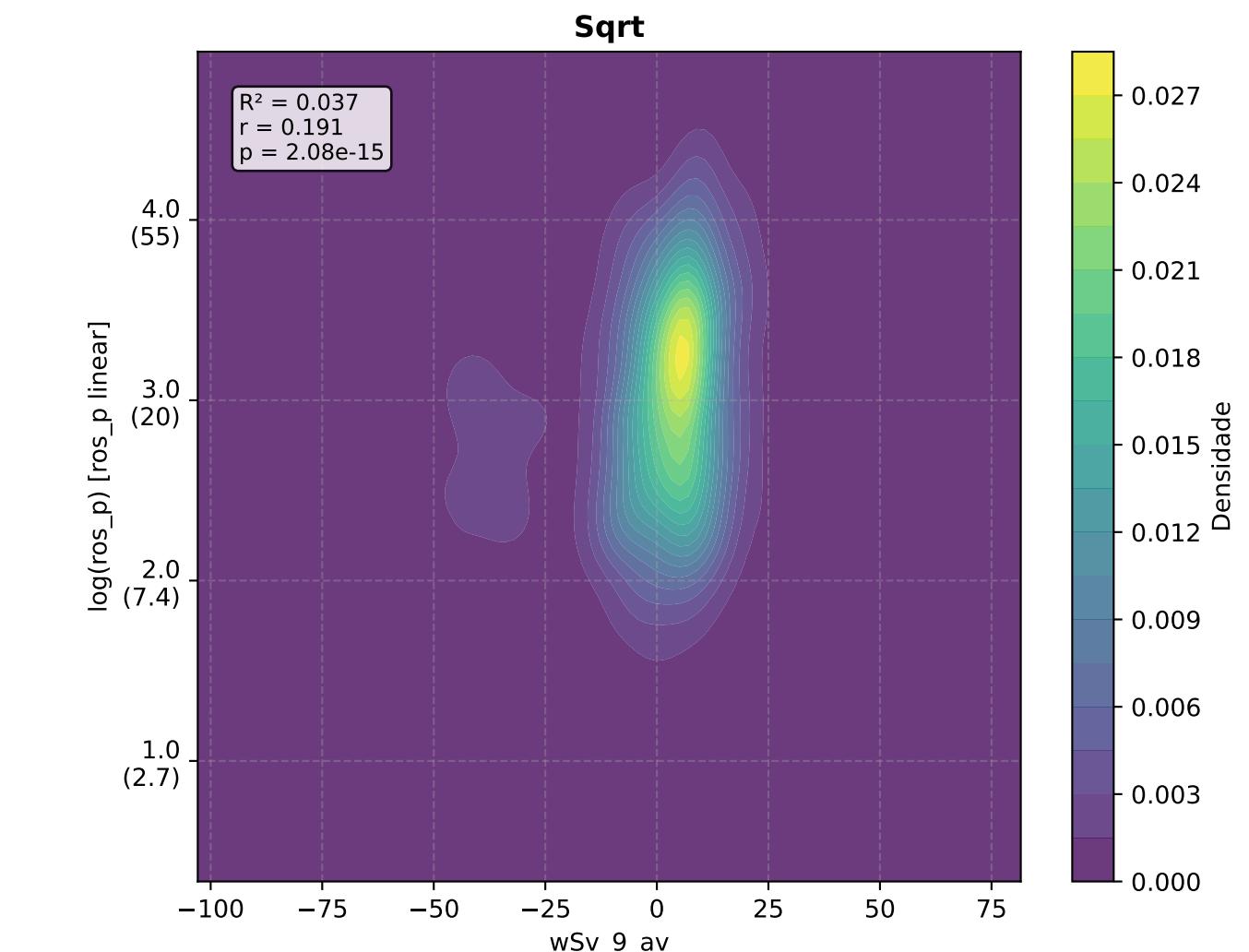
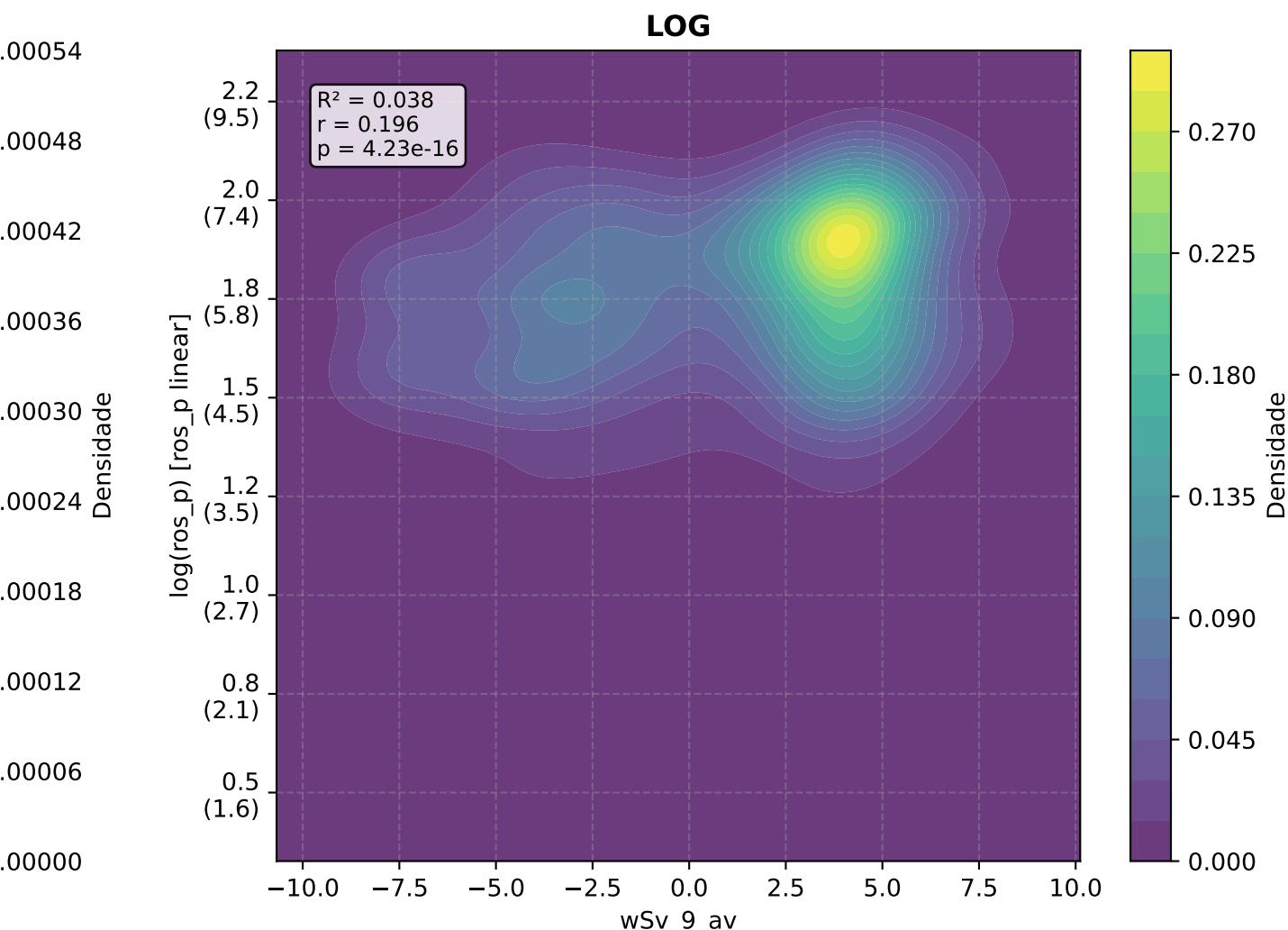
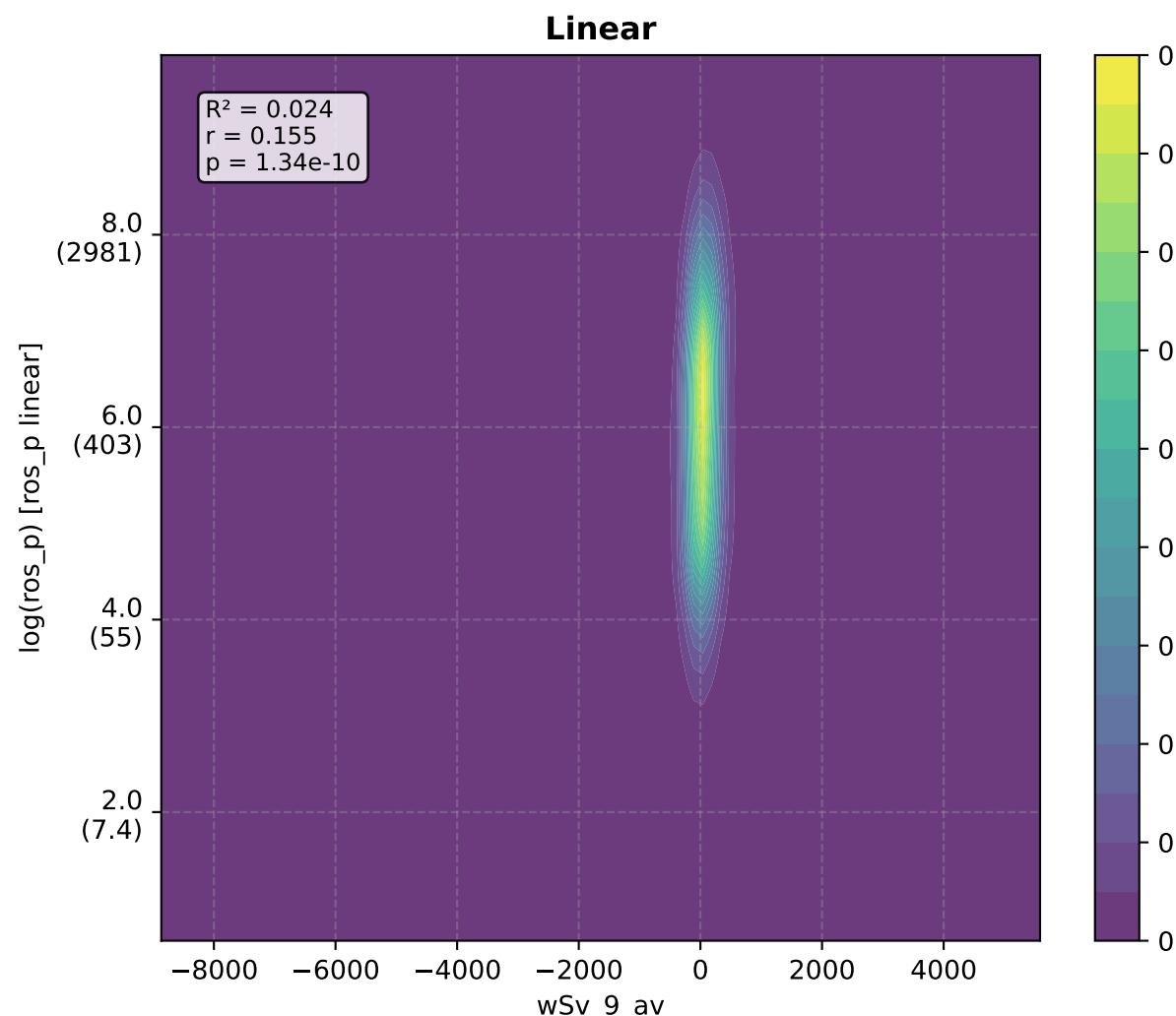
HDW_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



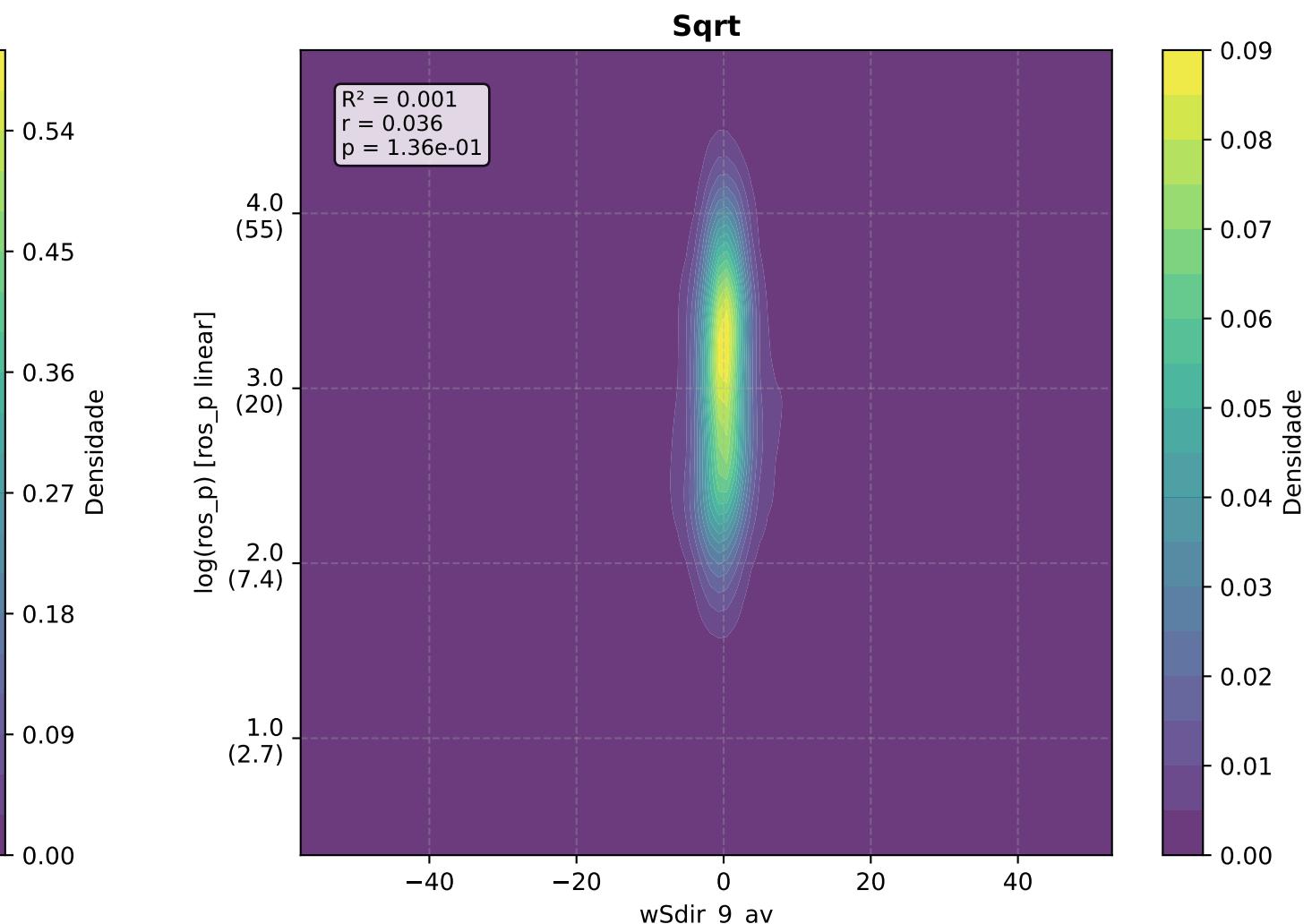
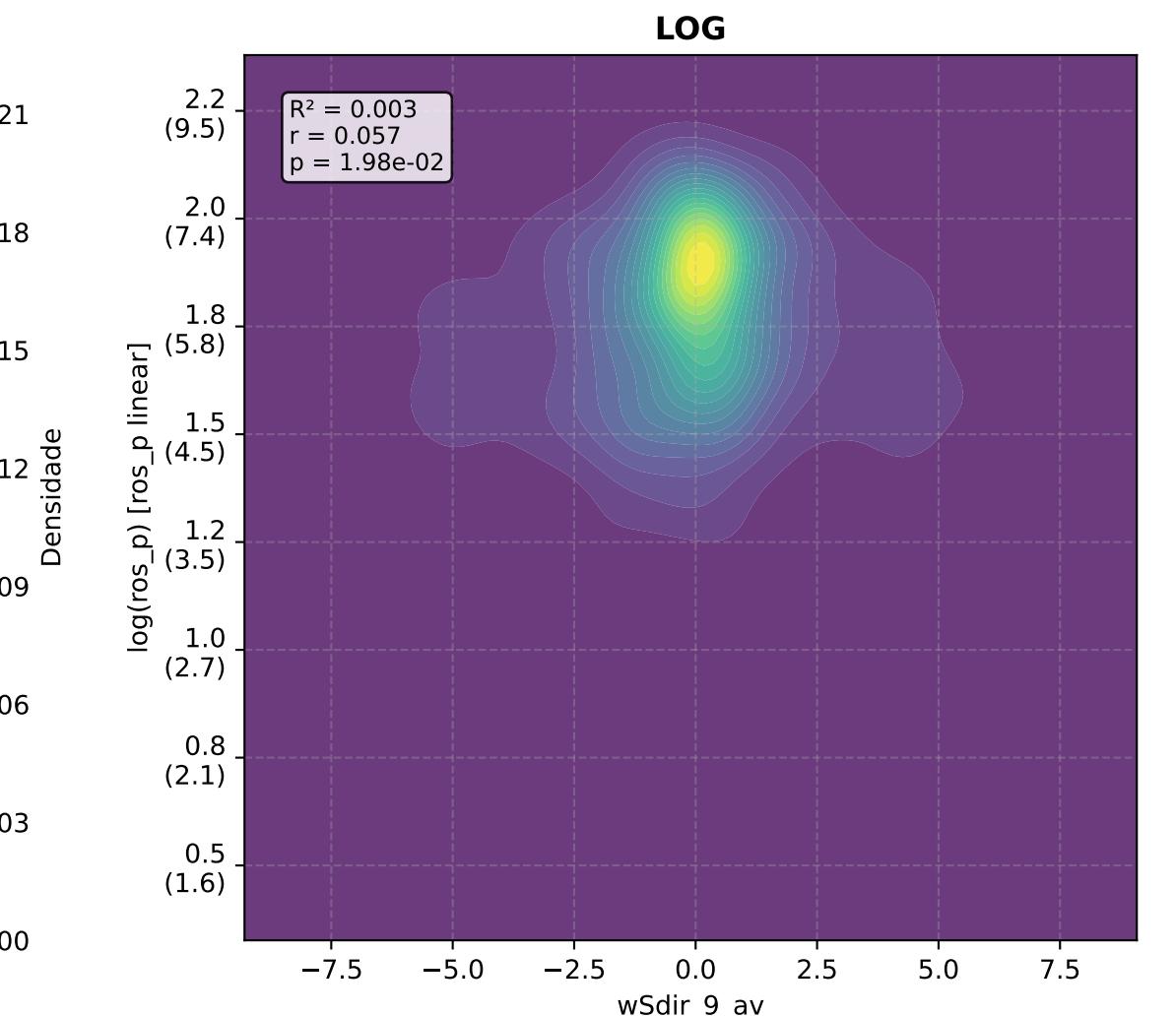
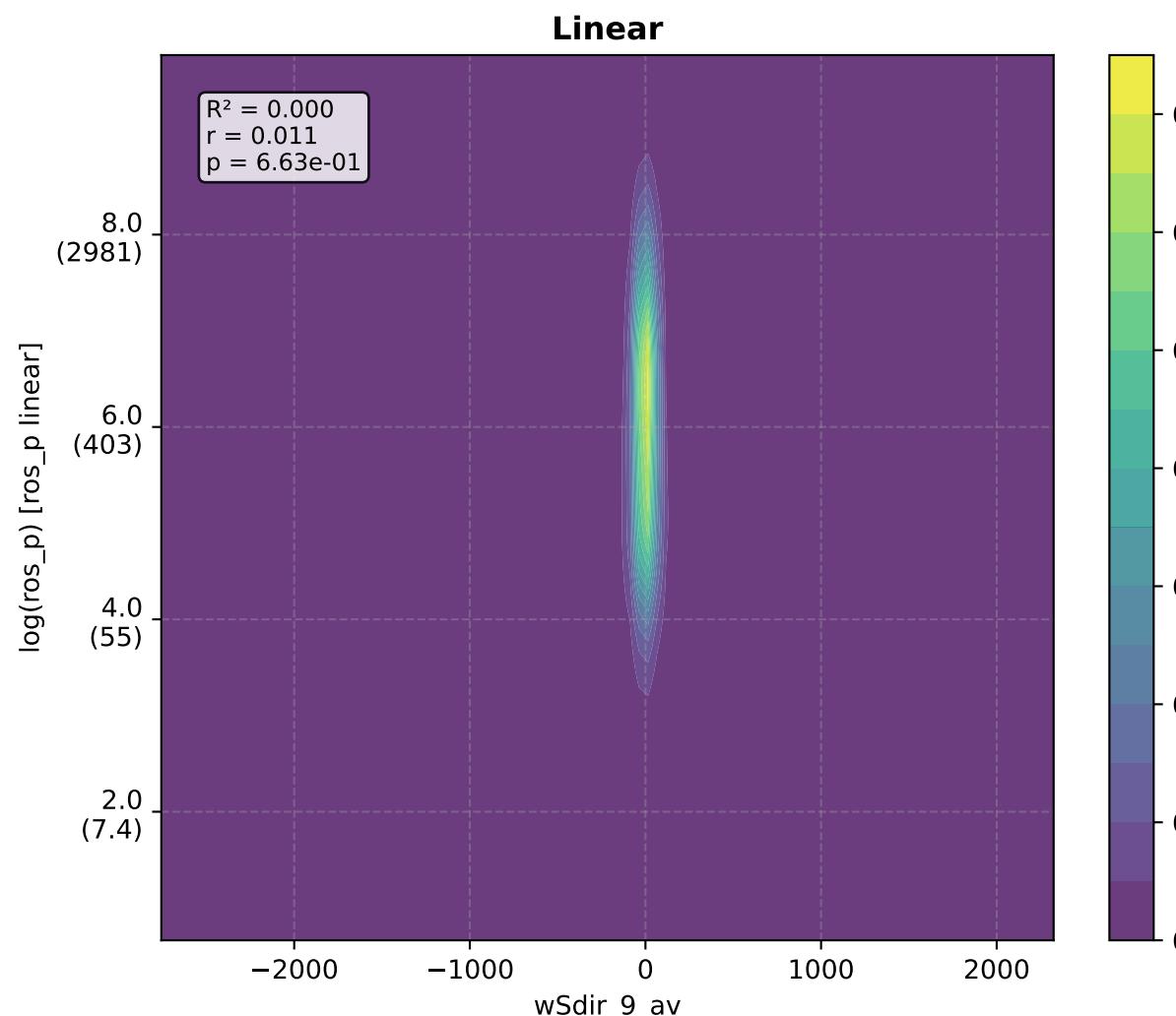
Haines_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



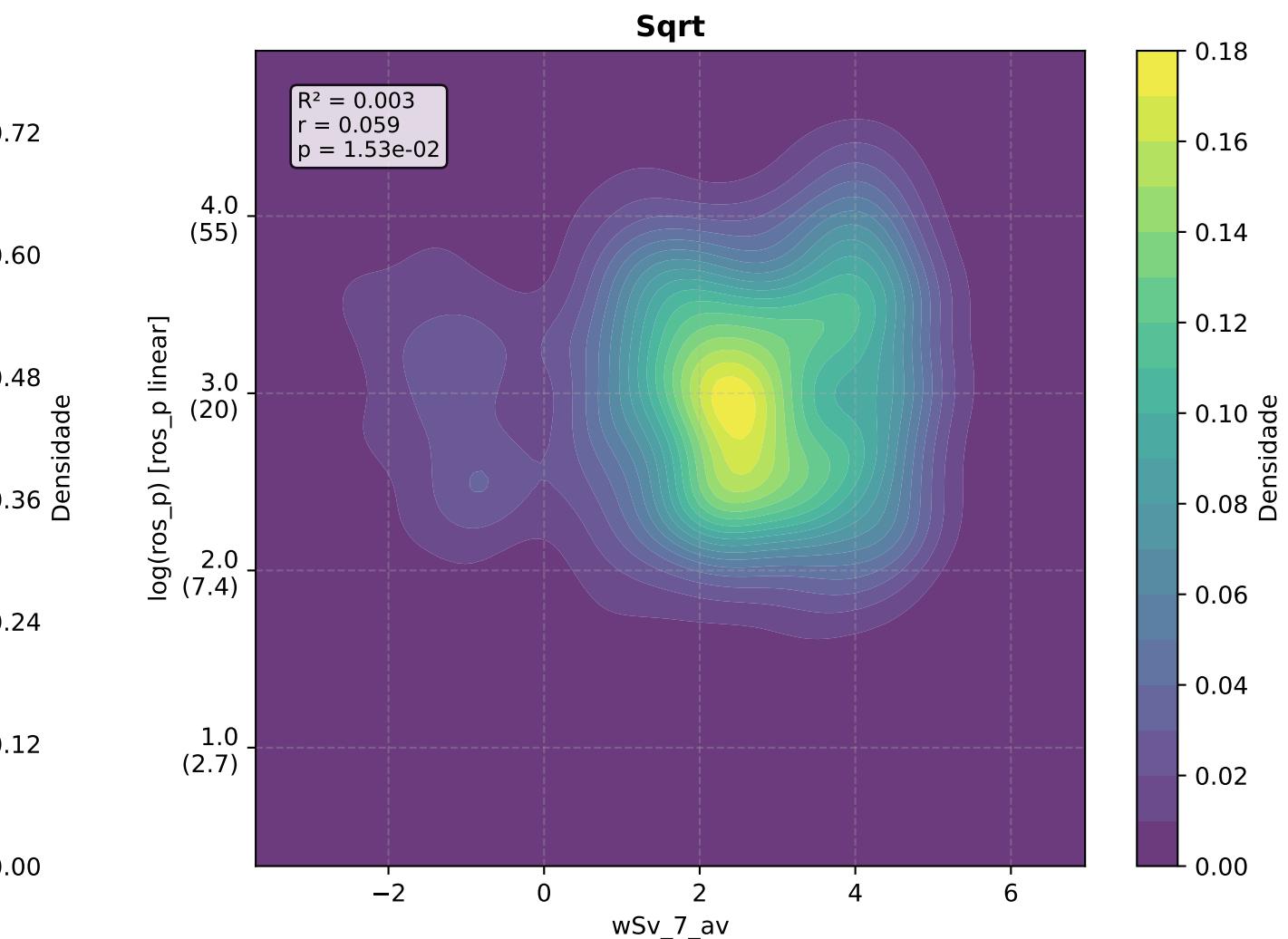
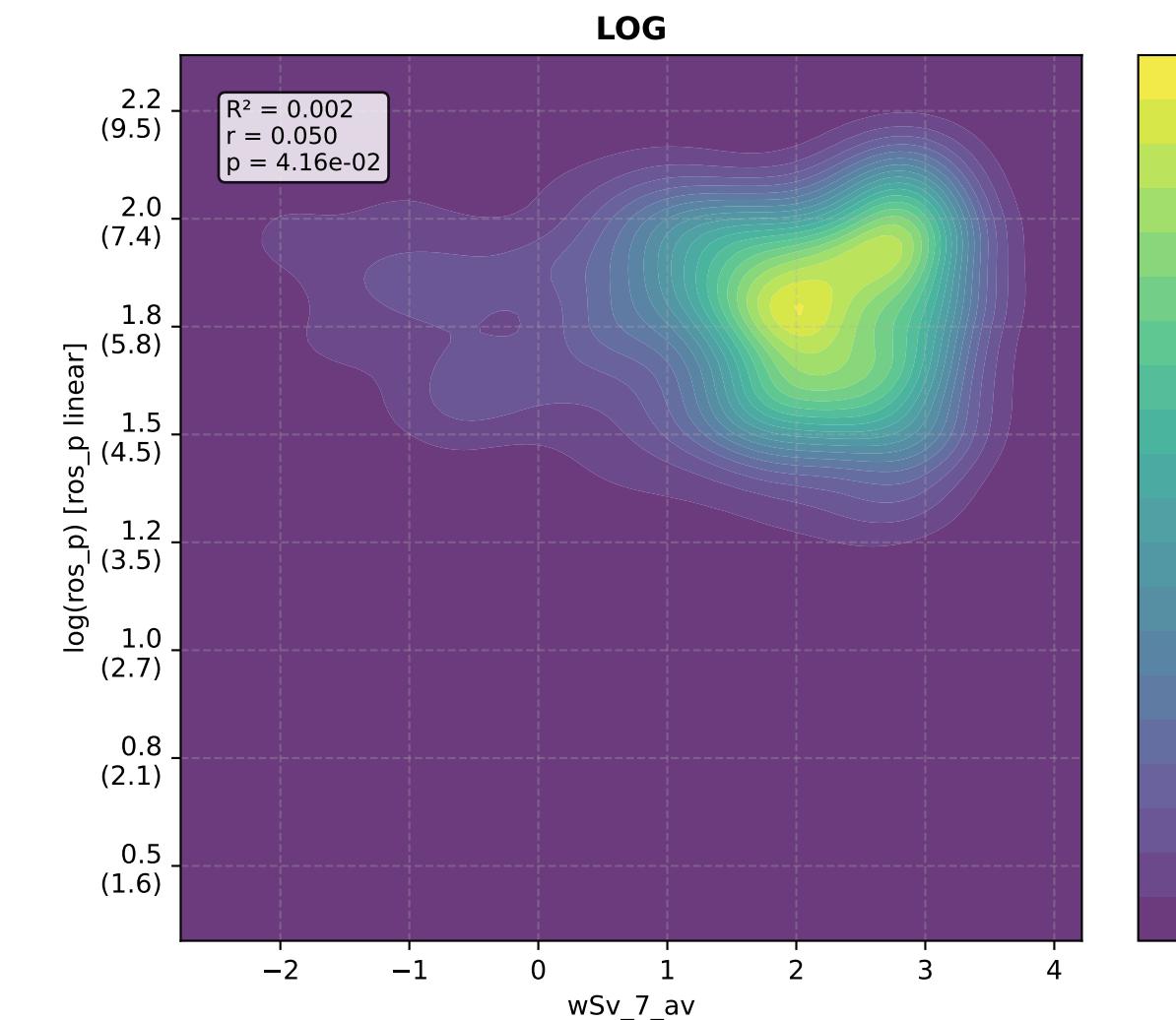
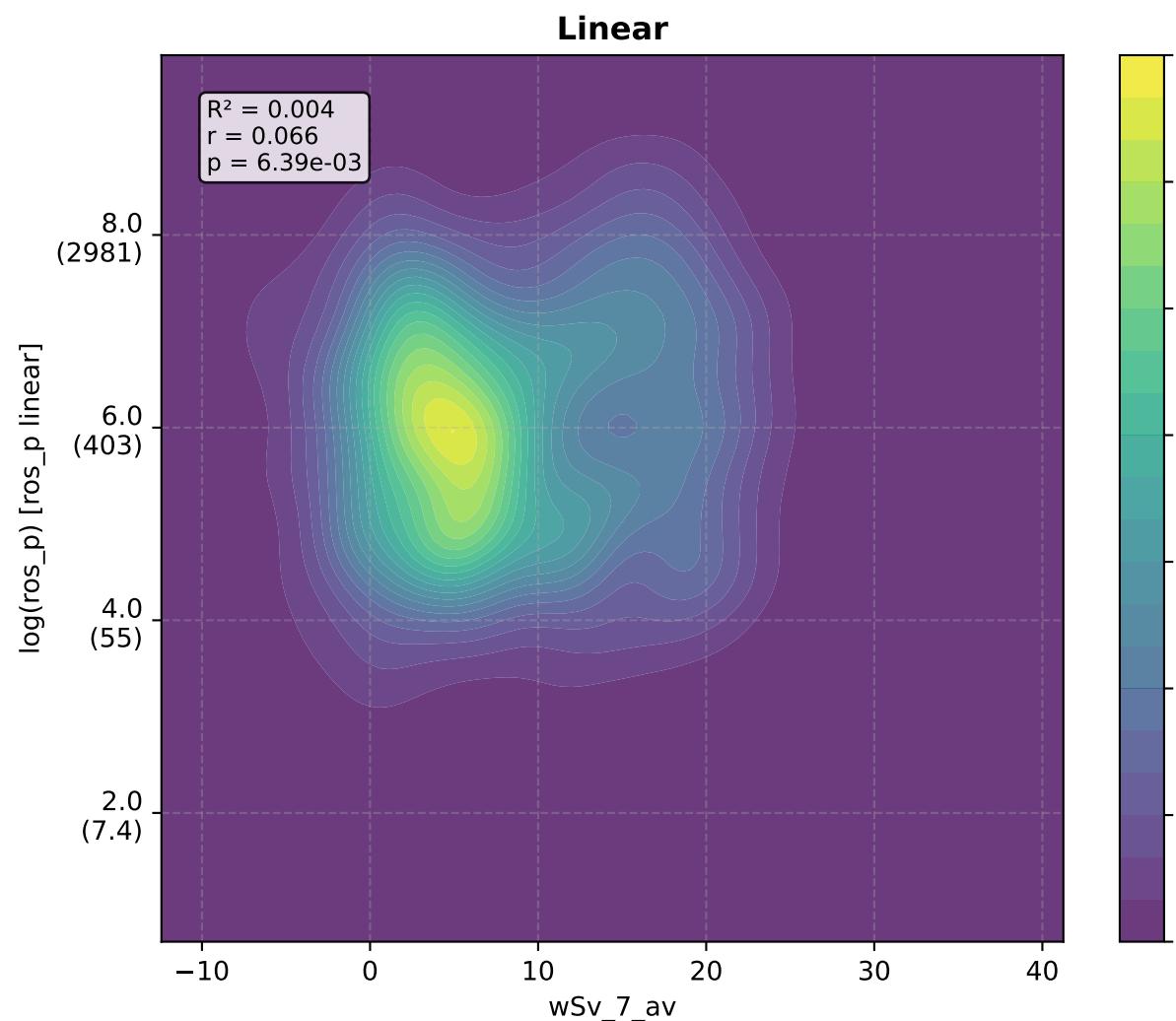
wSv_9_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



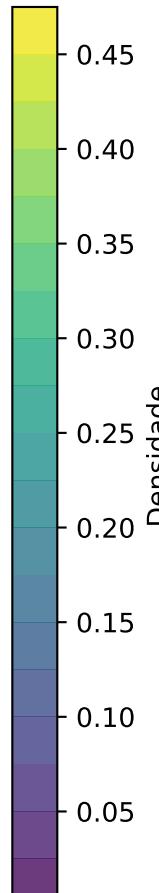
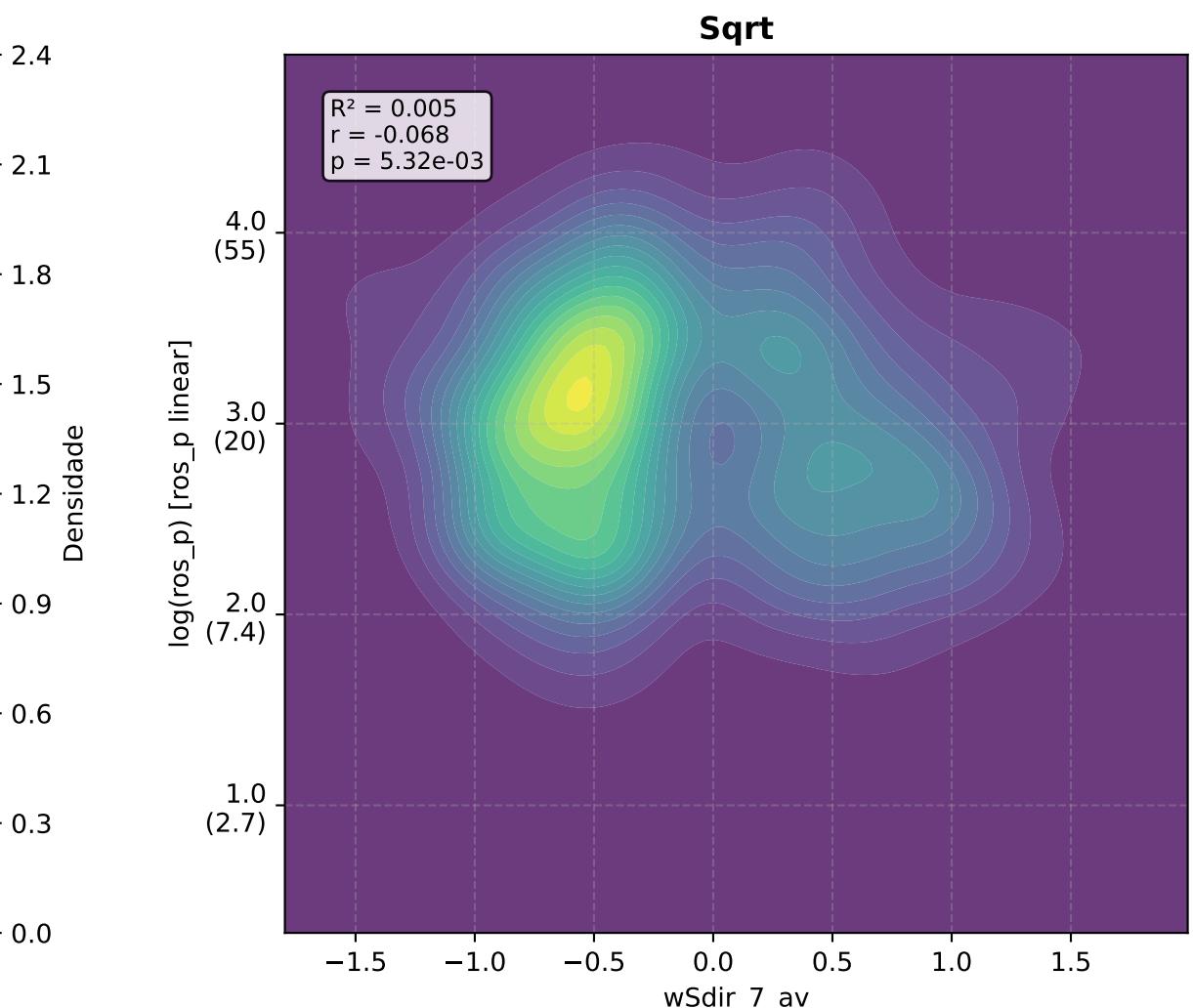
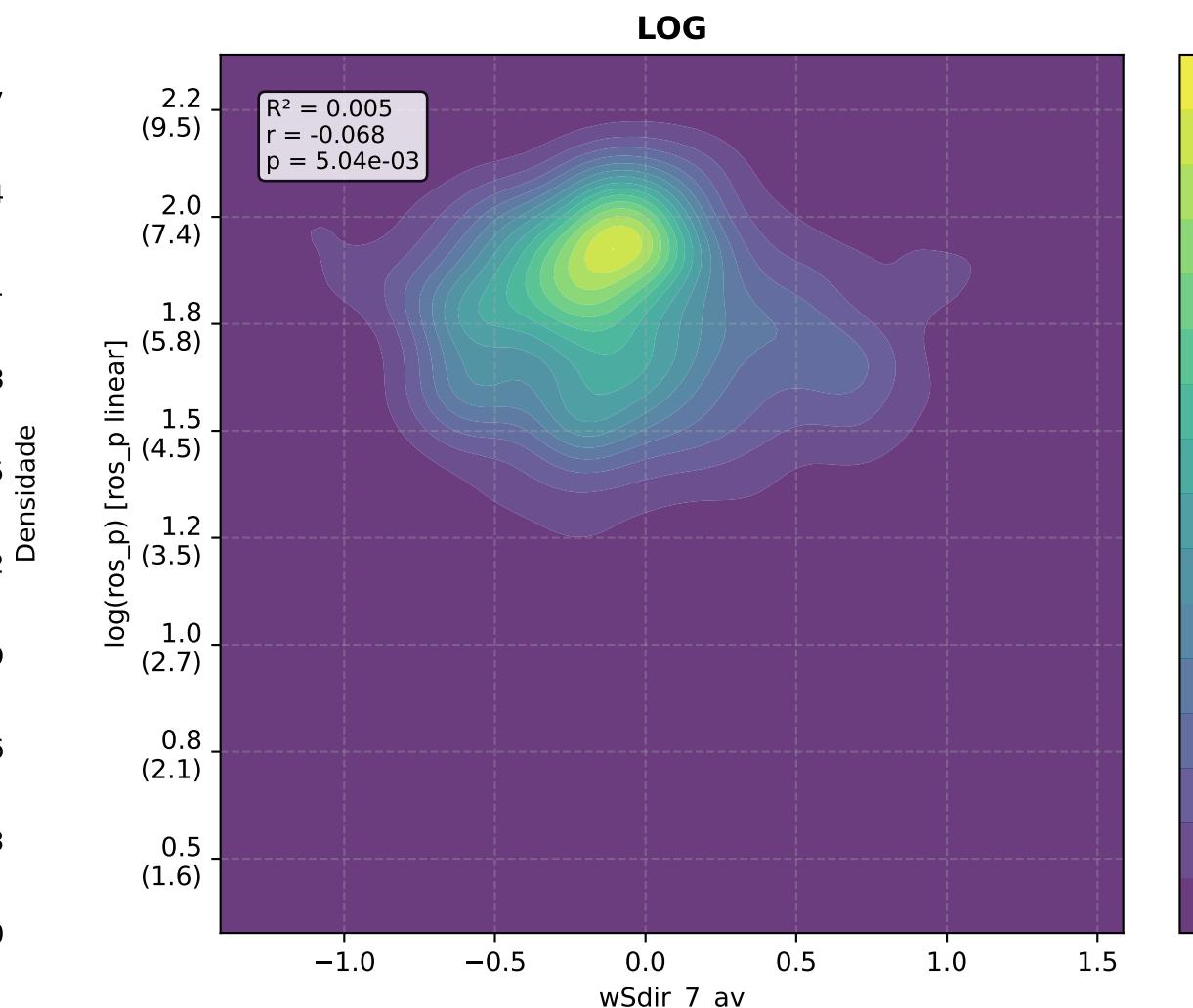
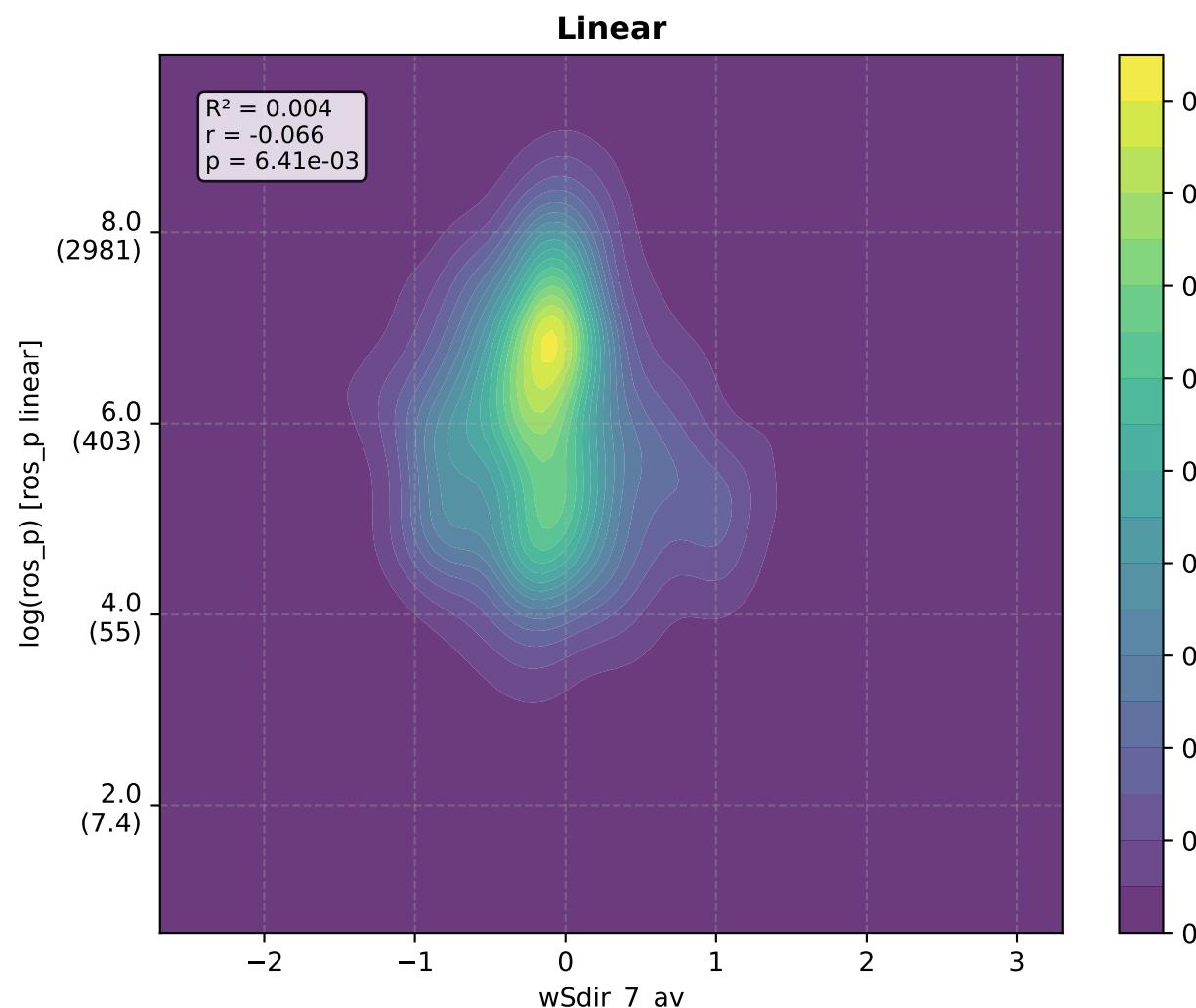
wSdir_9_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



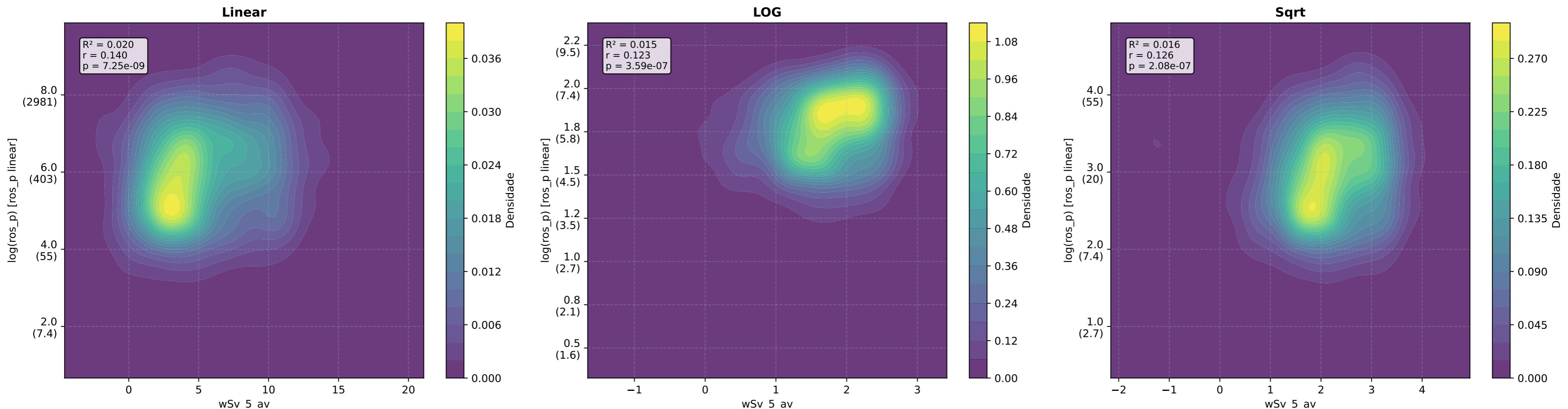
wSv_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



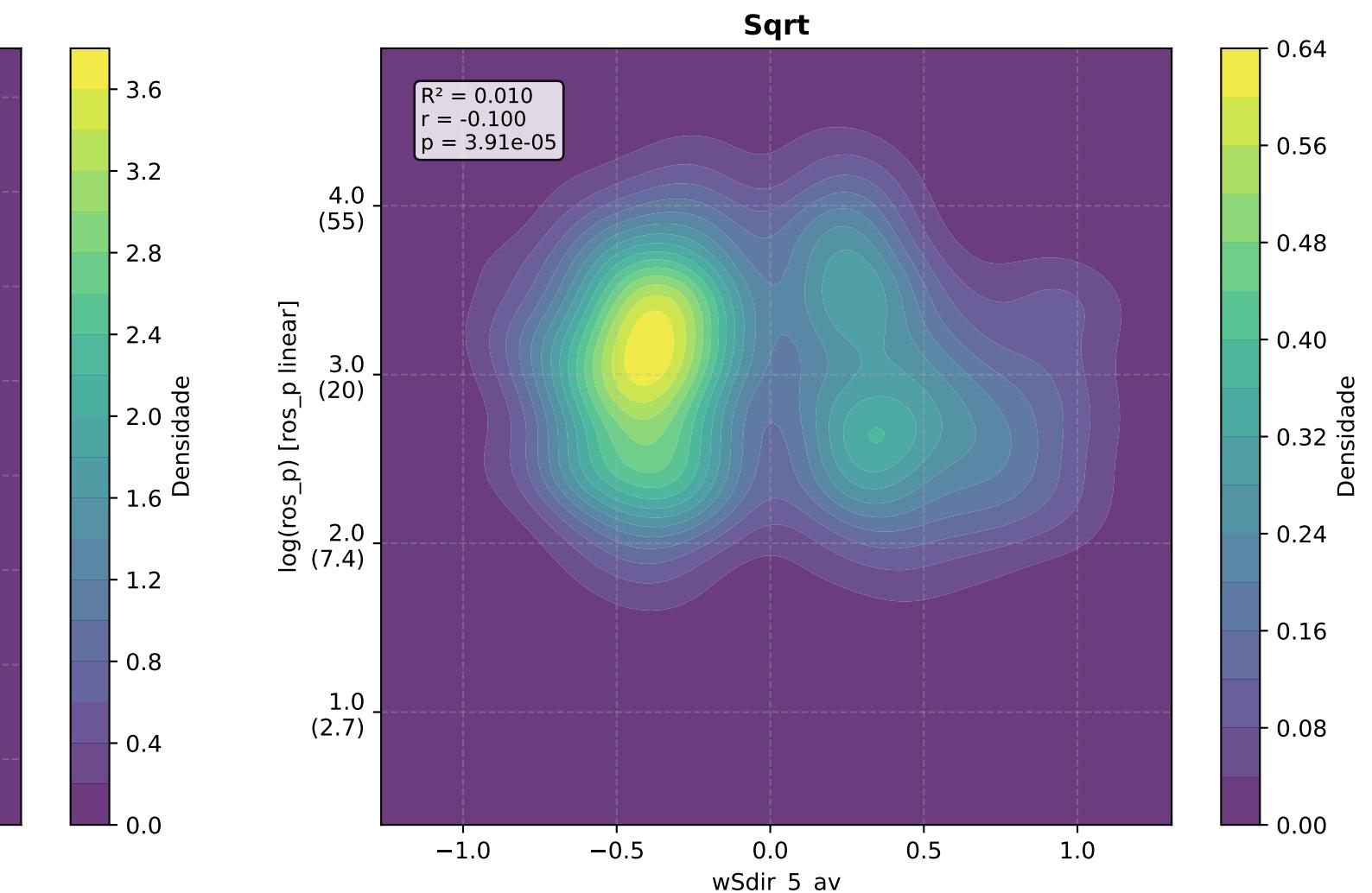
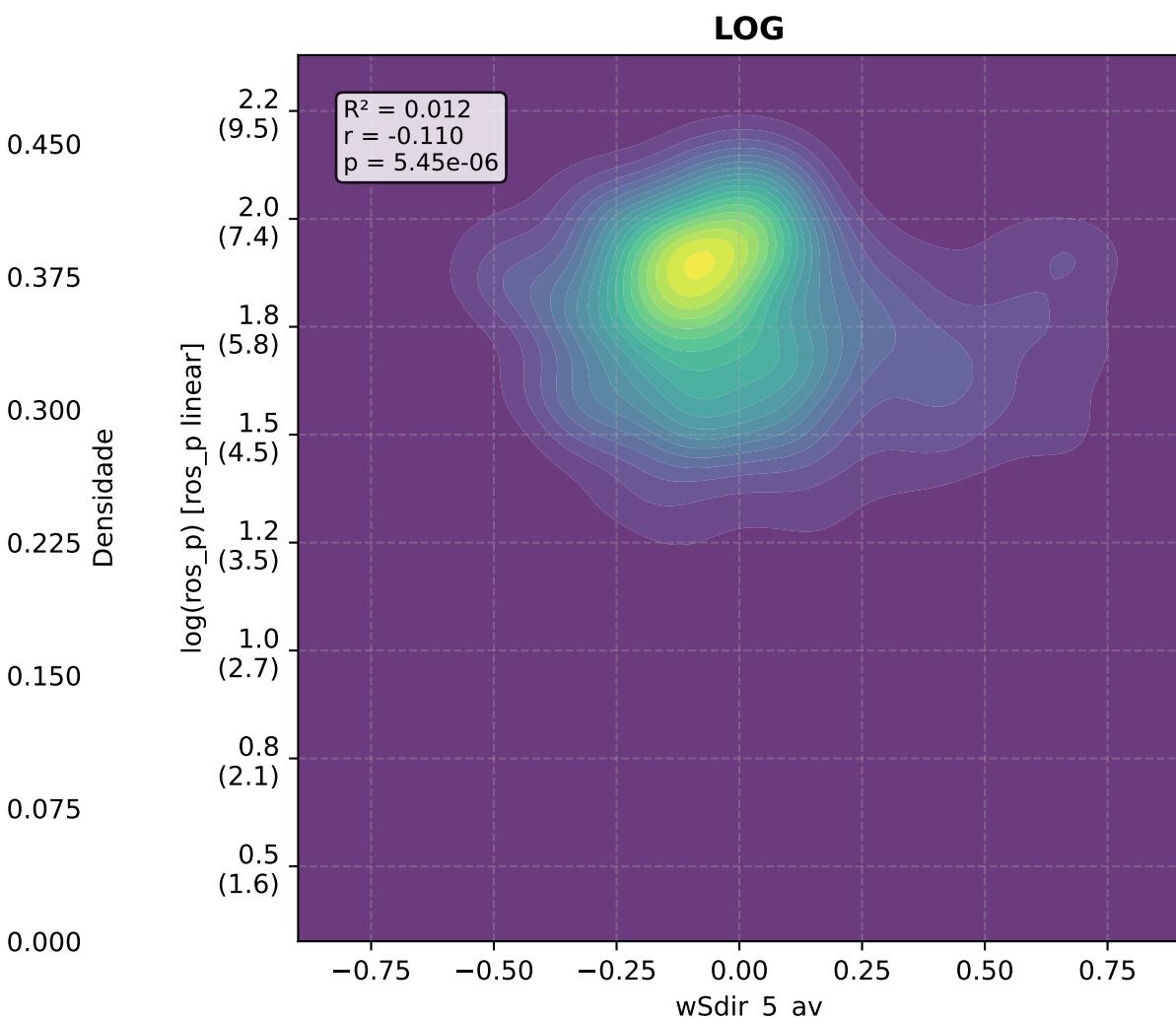
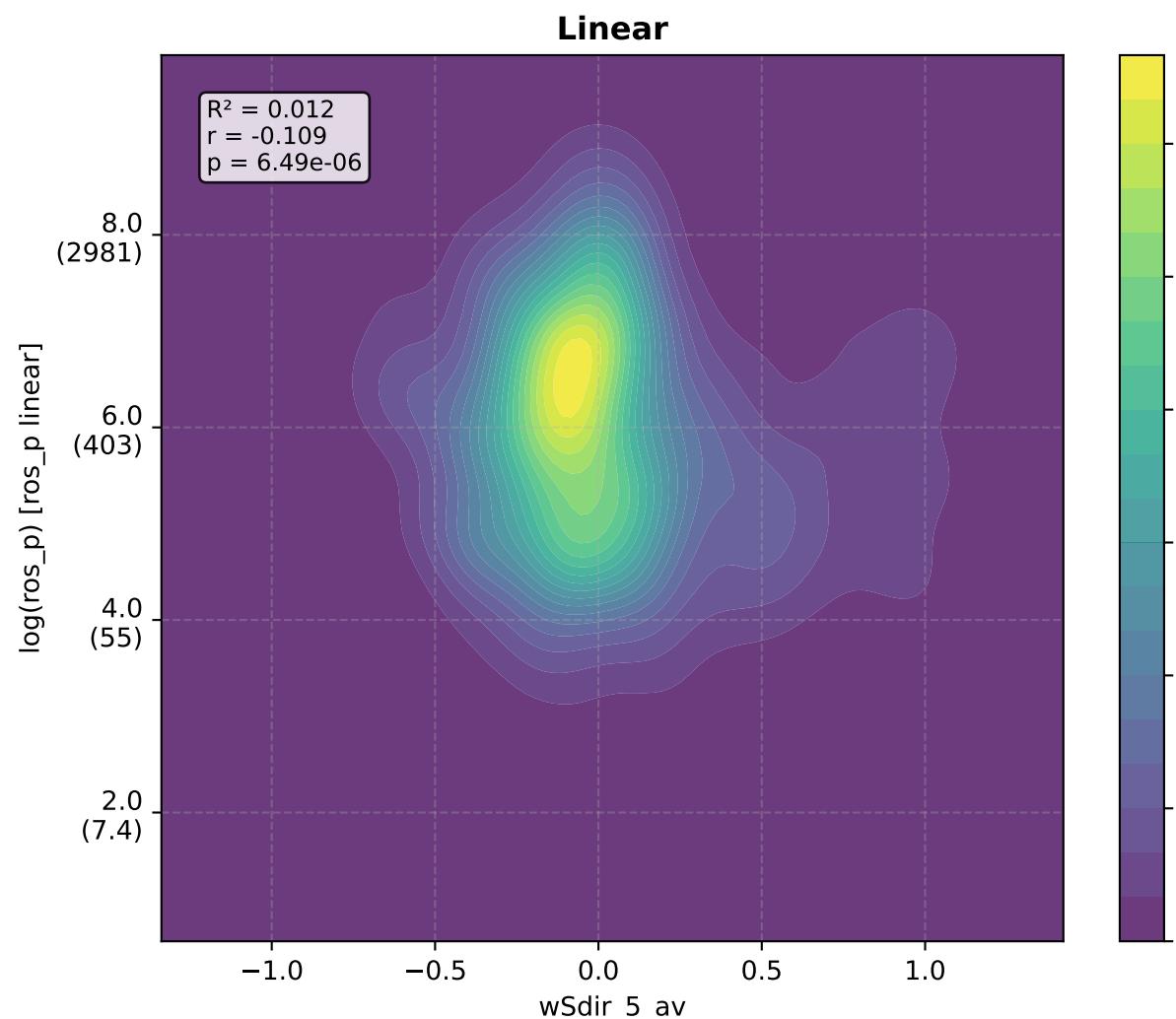
wSdir_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



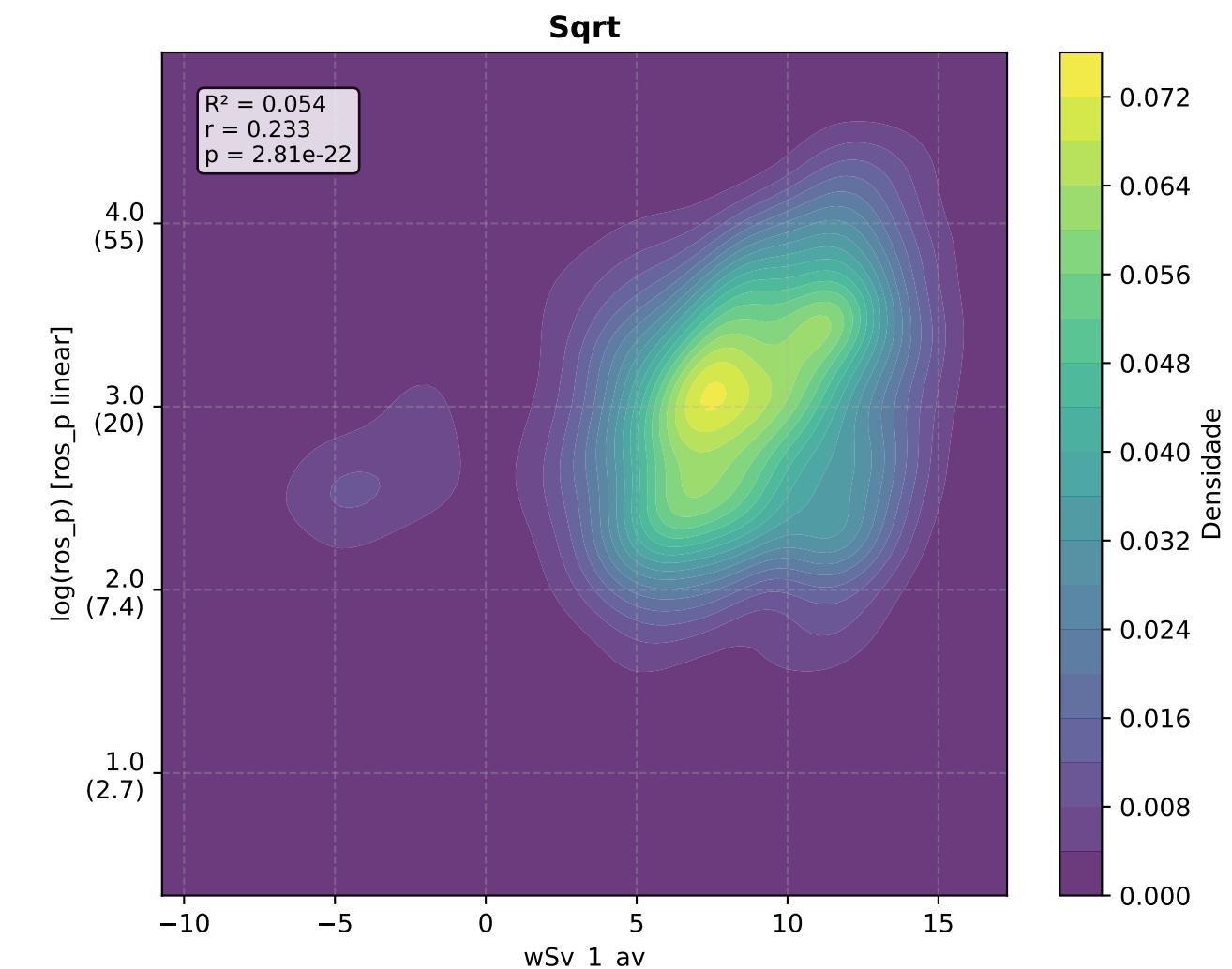
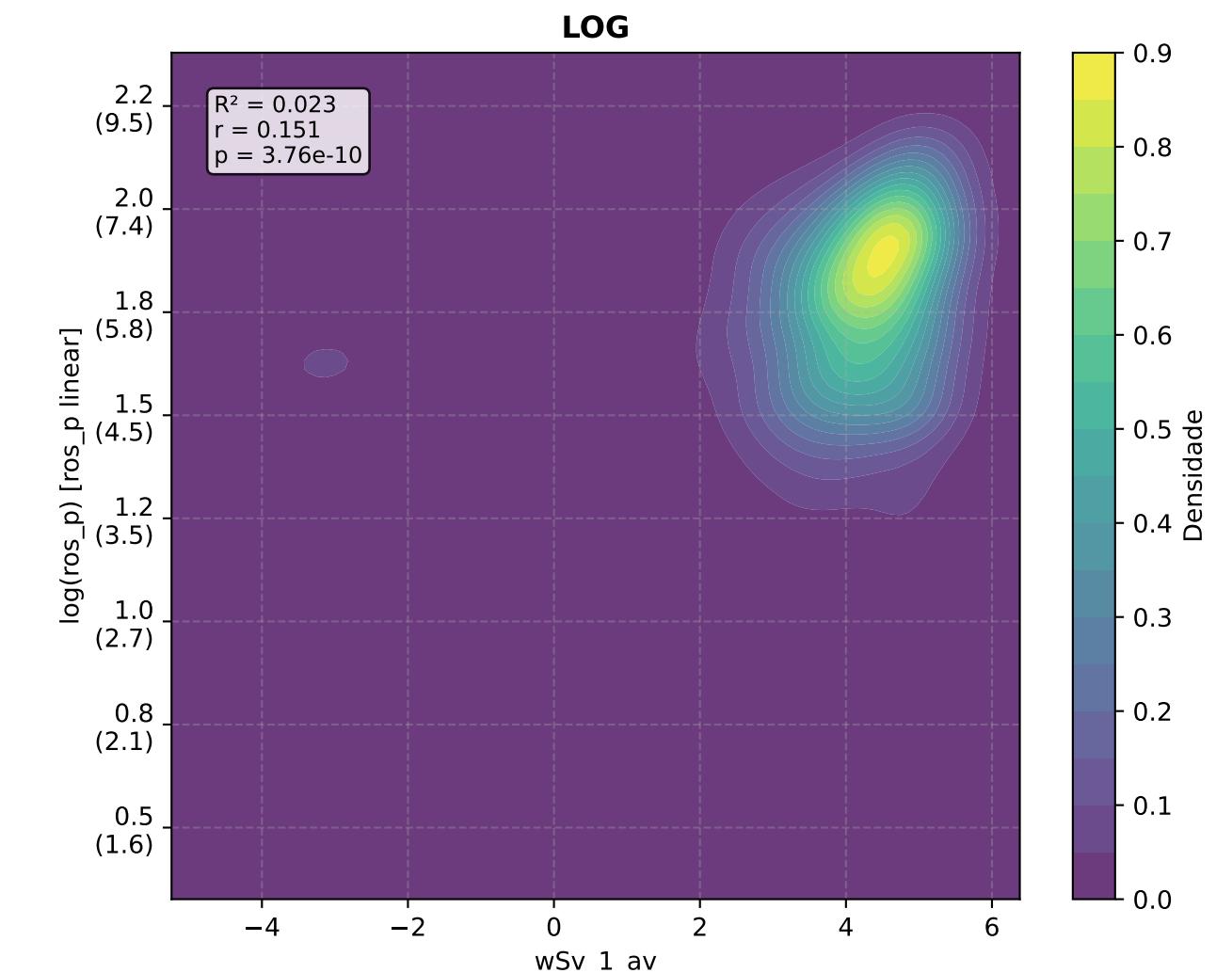
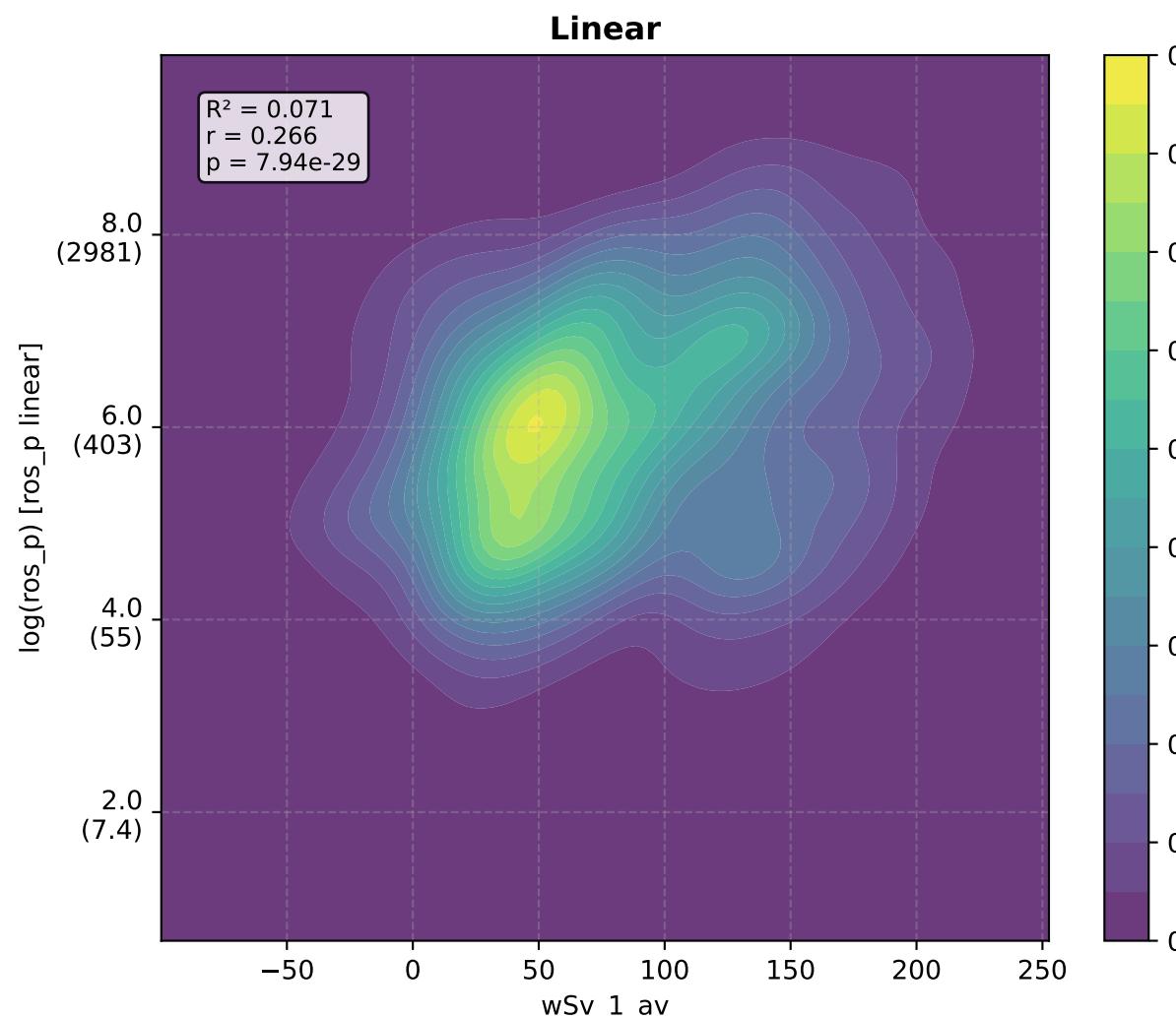
wSv_5_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



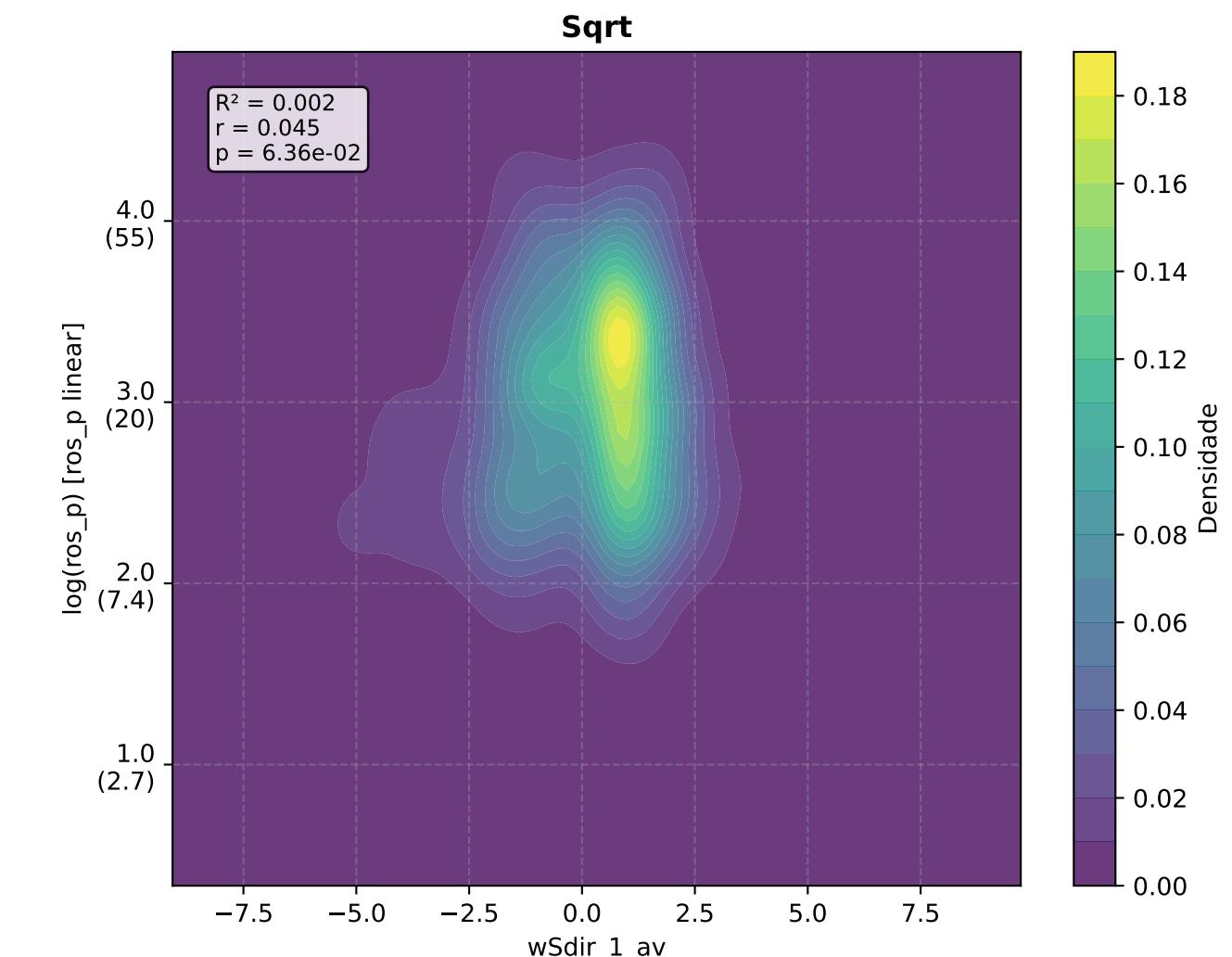
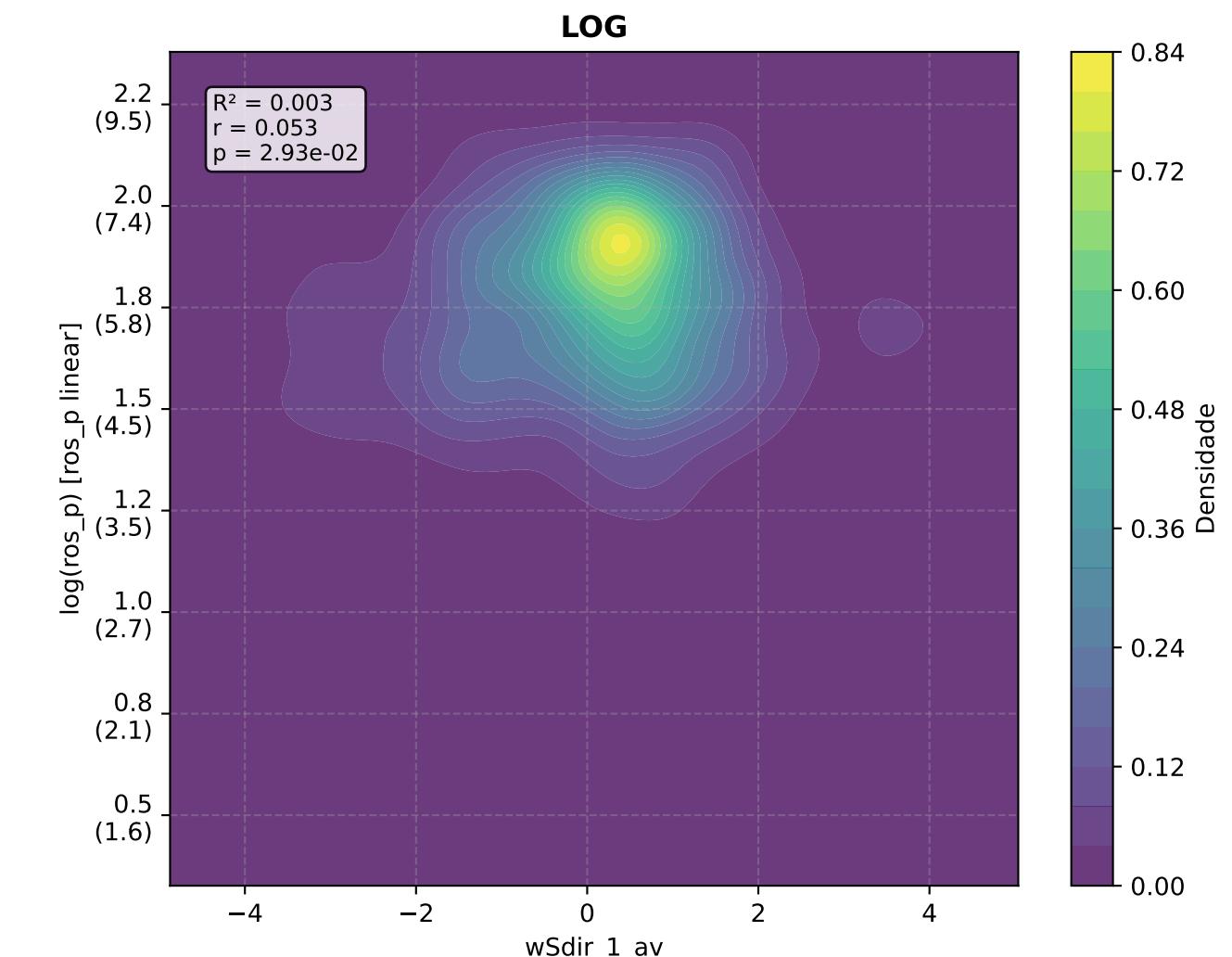
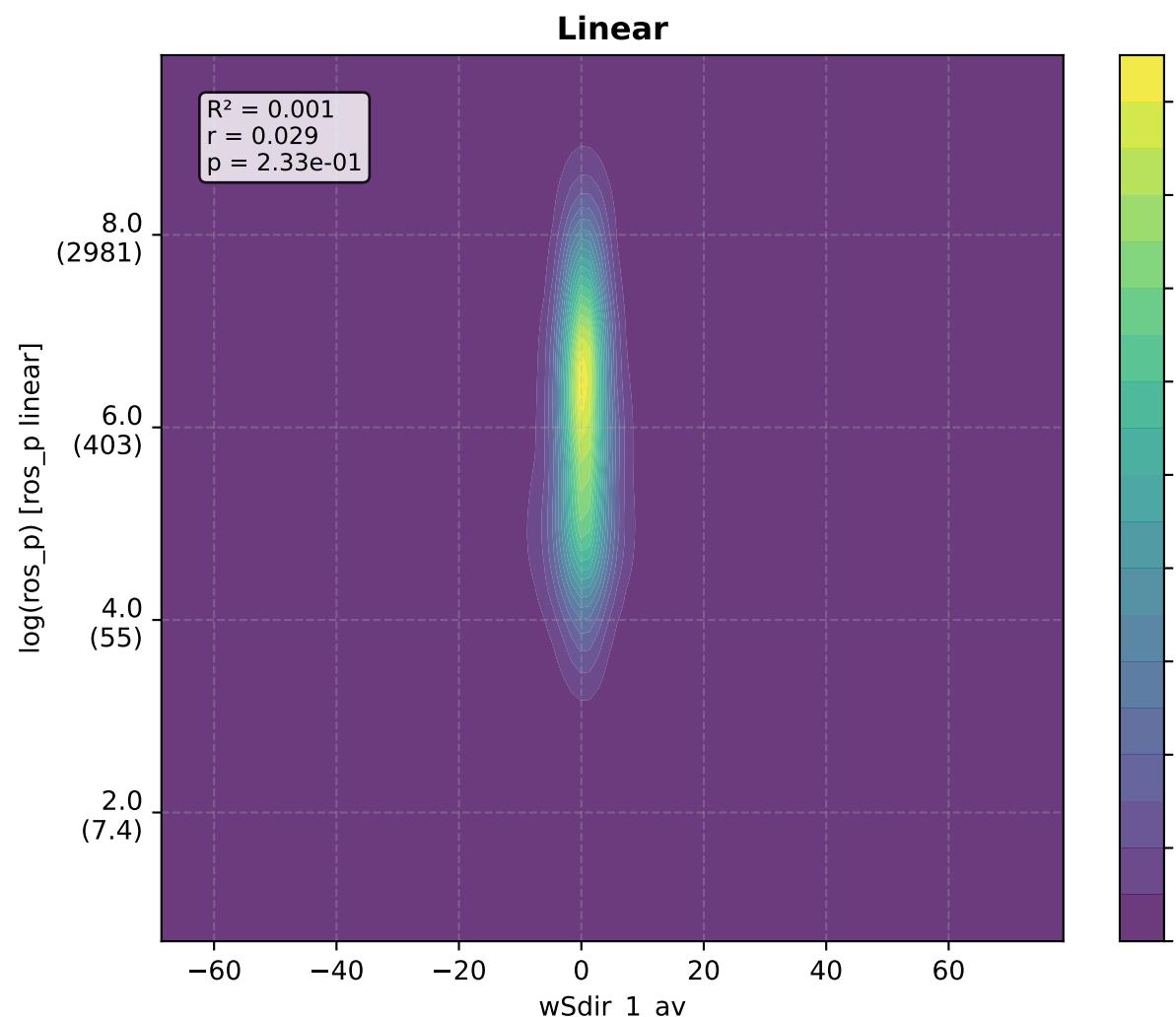
wSdir_5_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



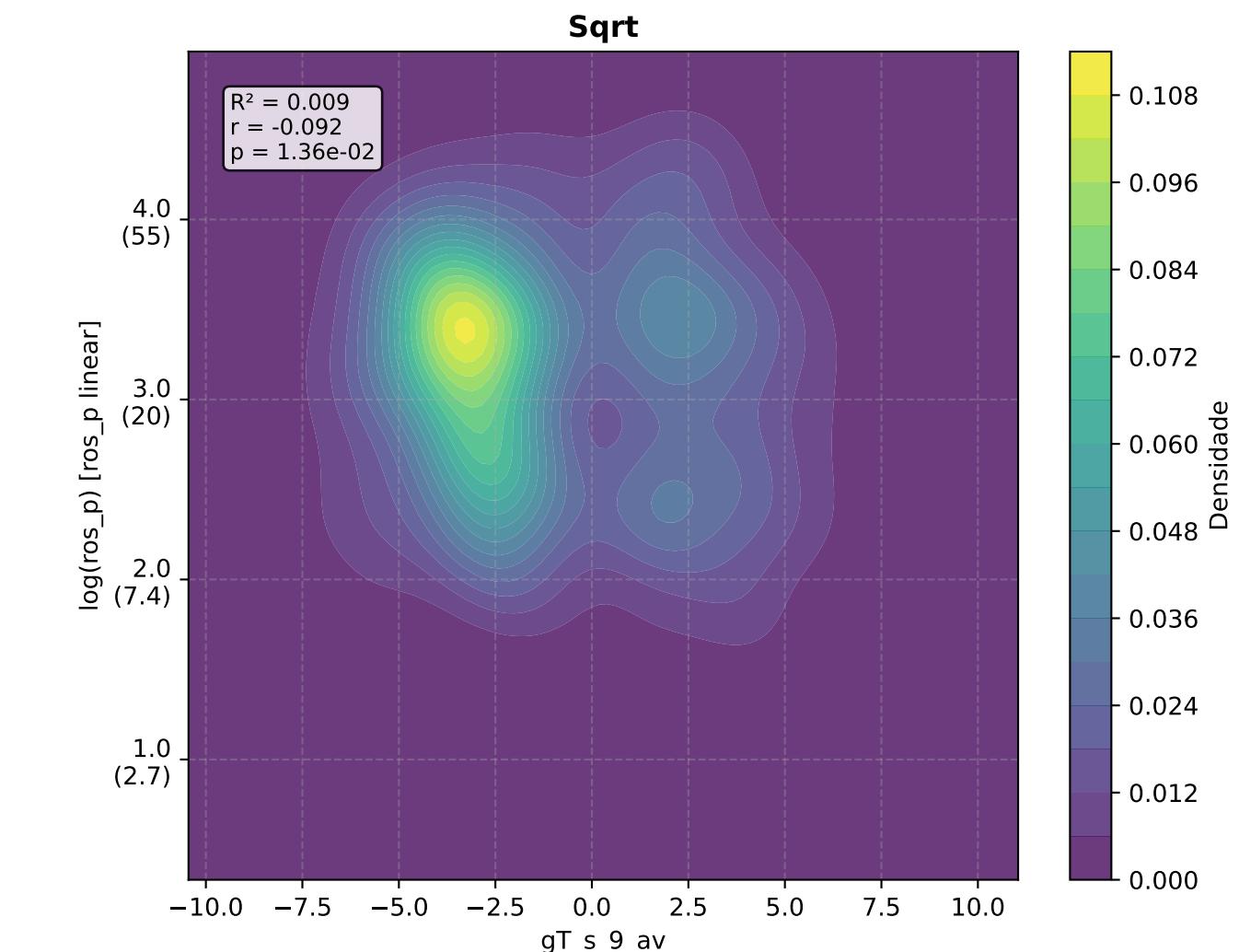
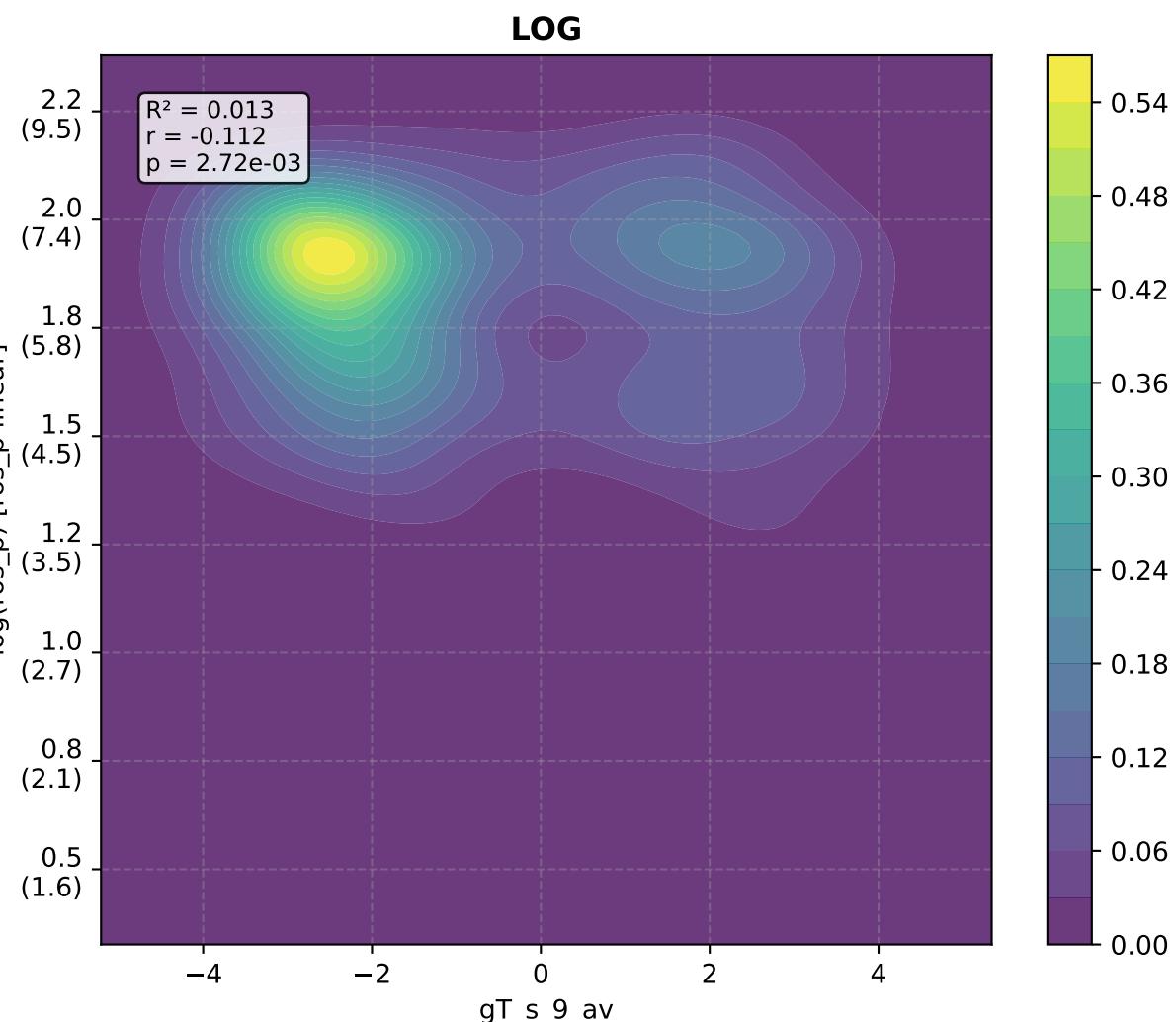
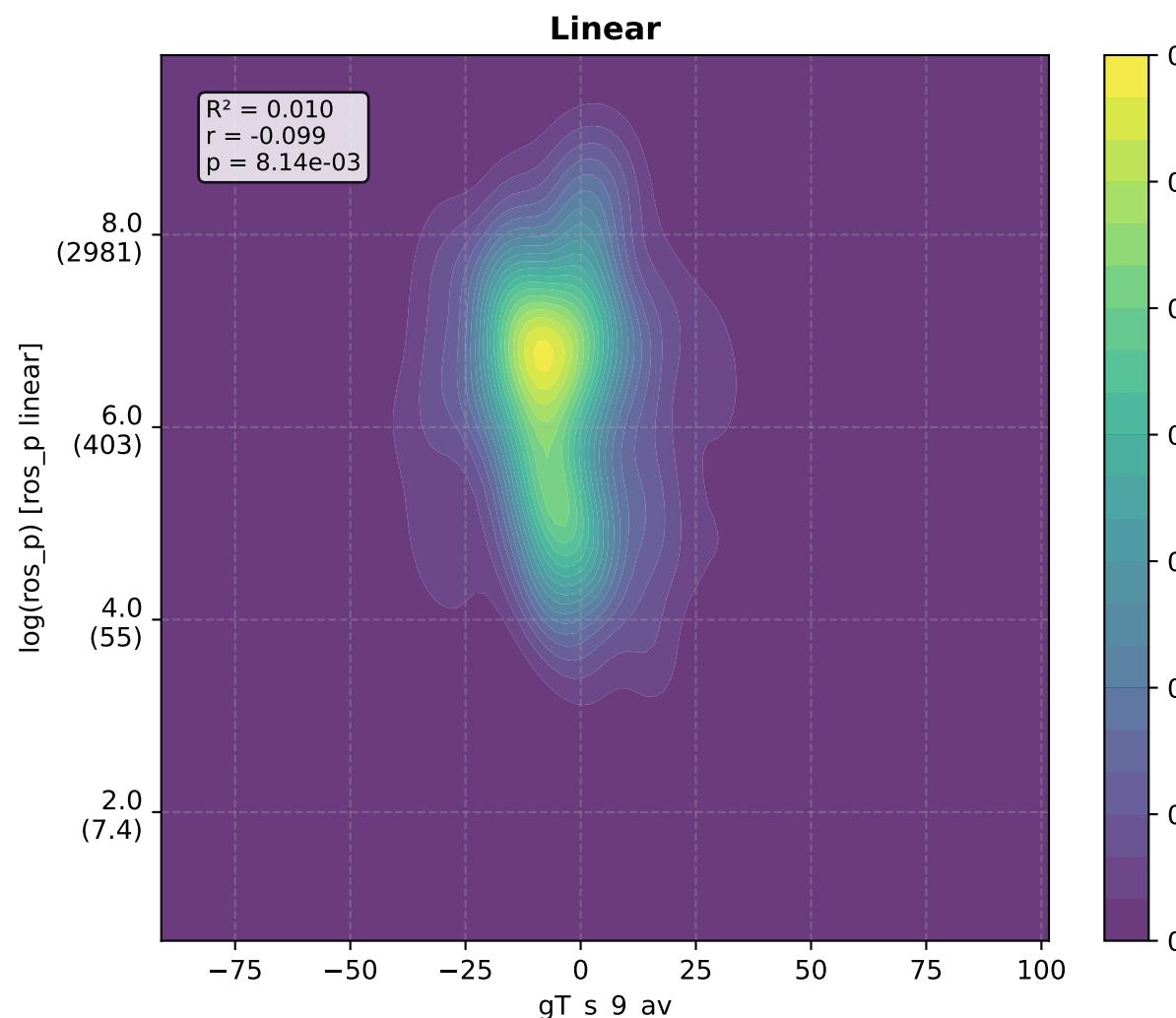
wSv_1_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



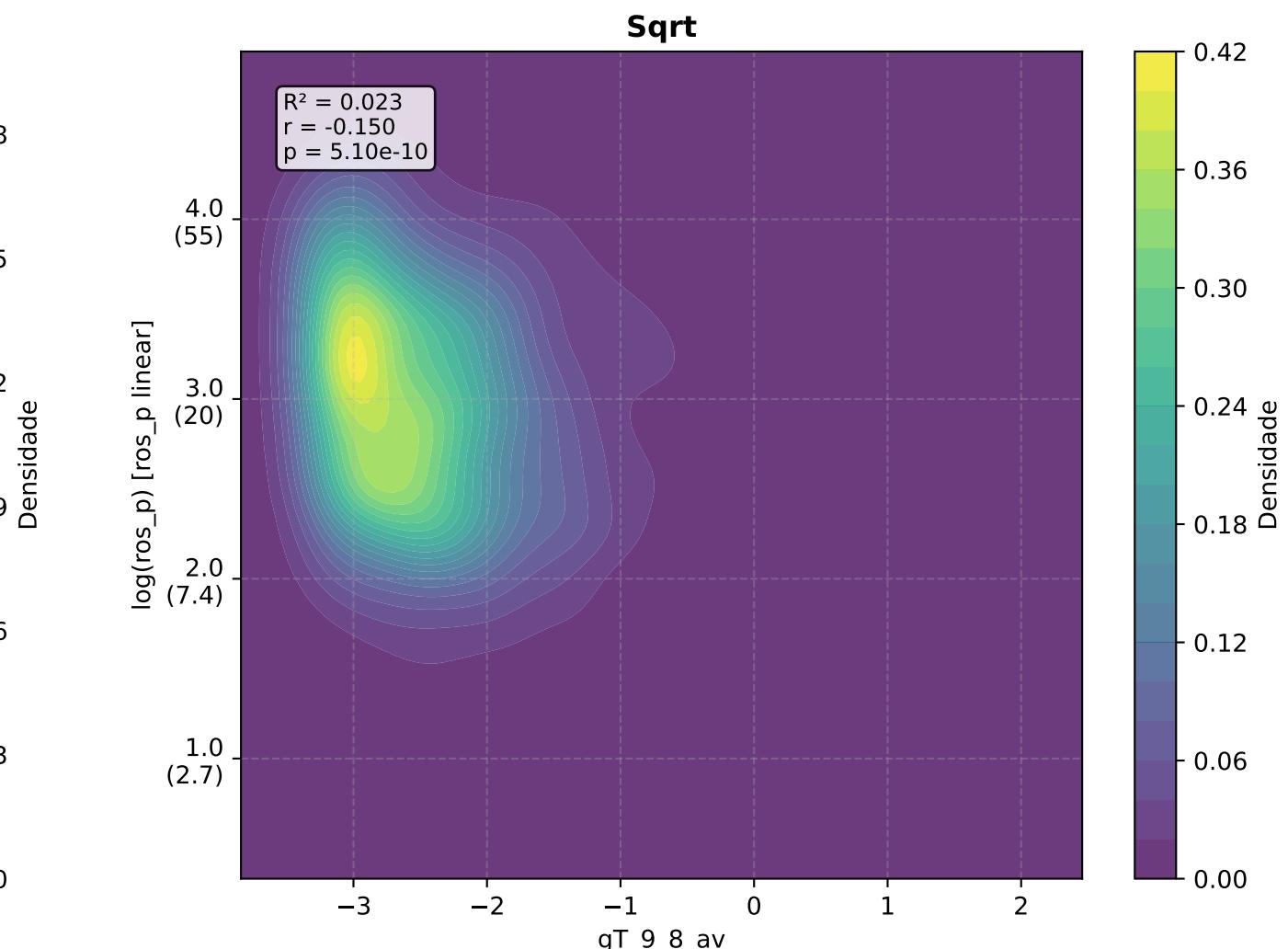
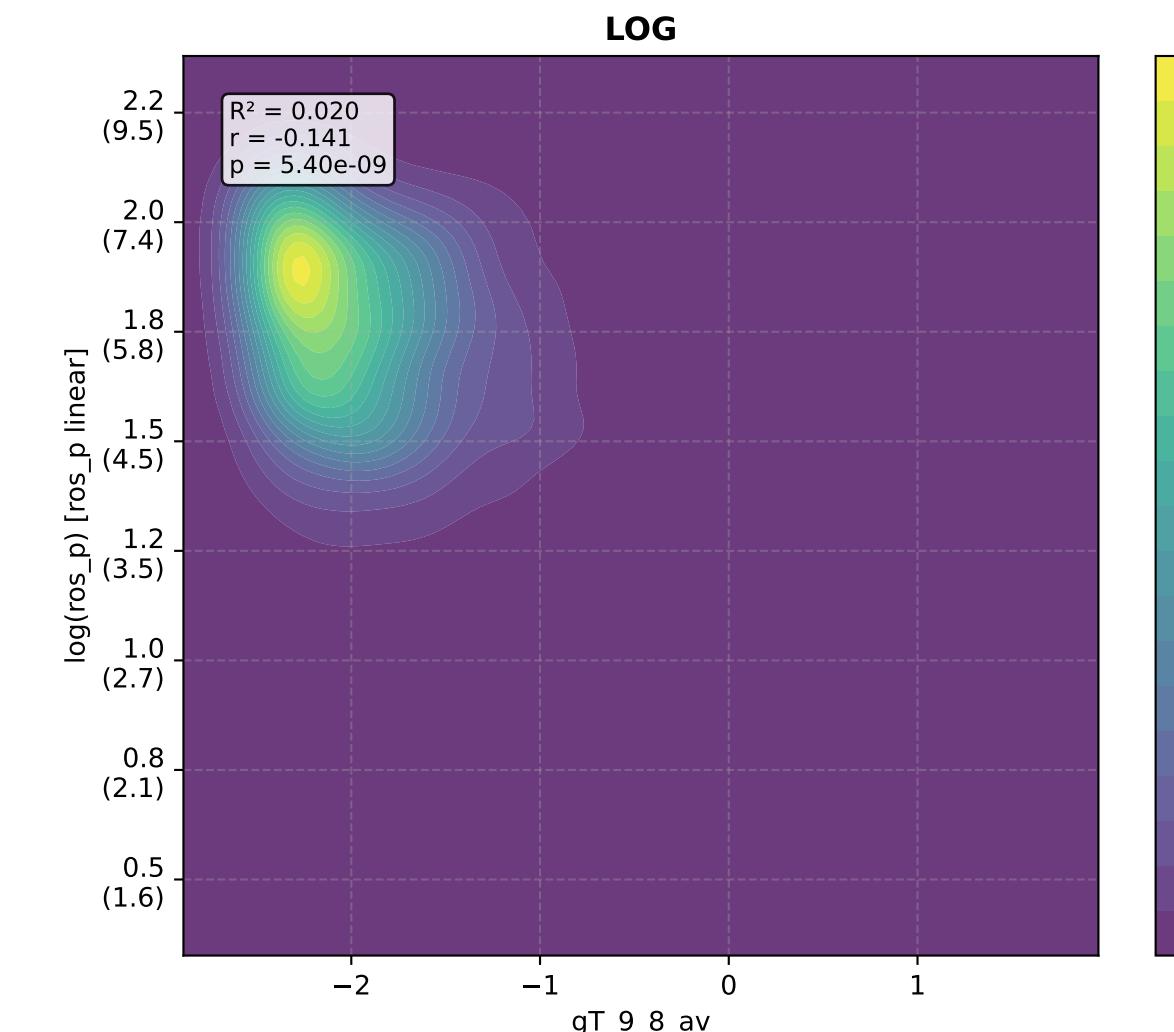
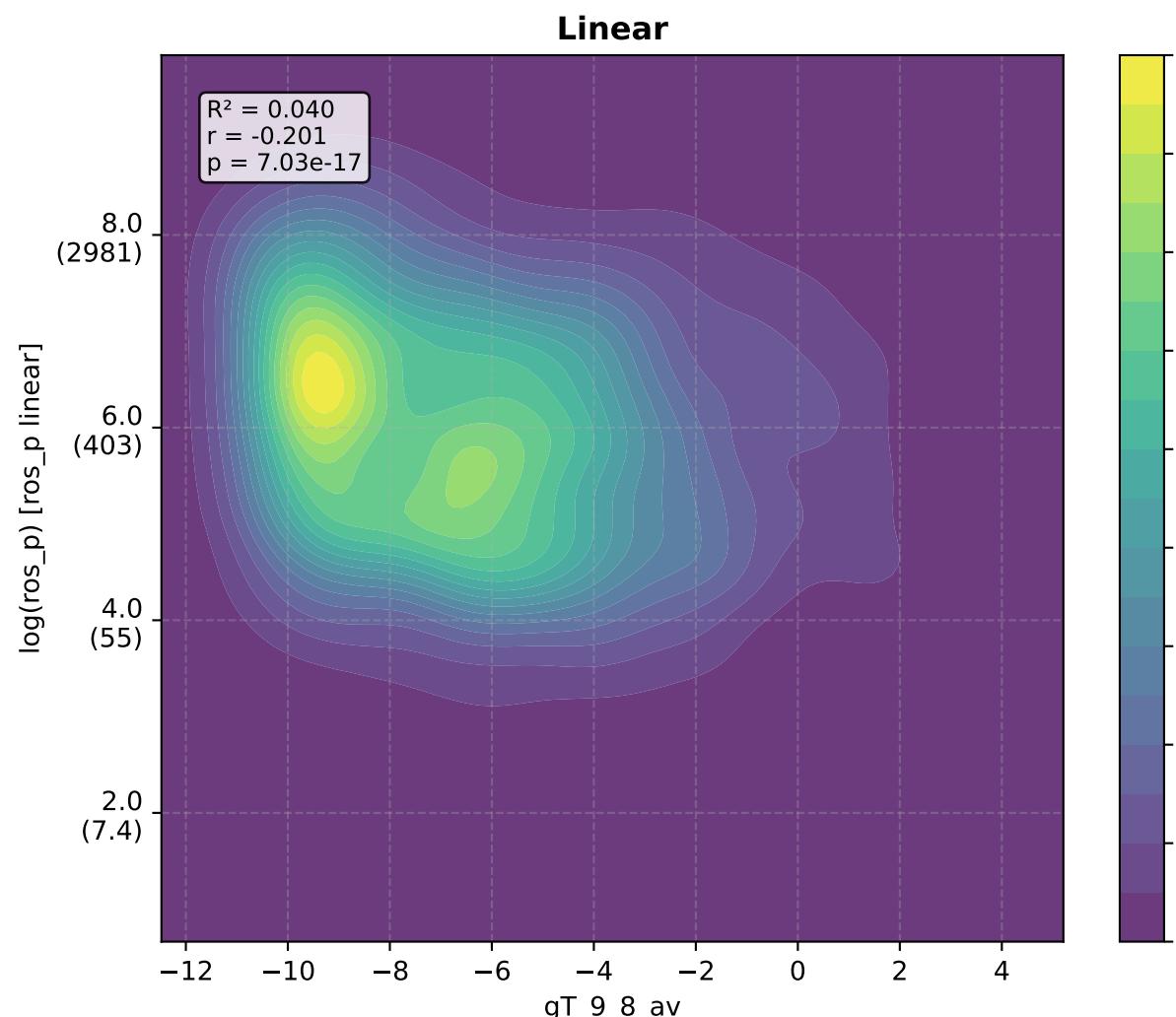
wSdir_1_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



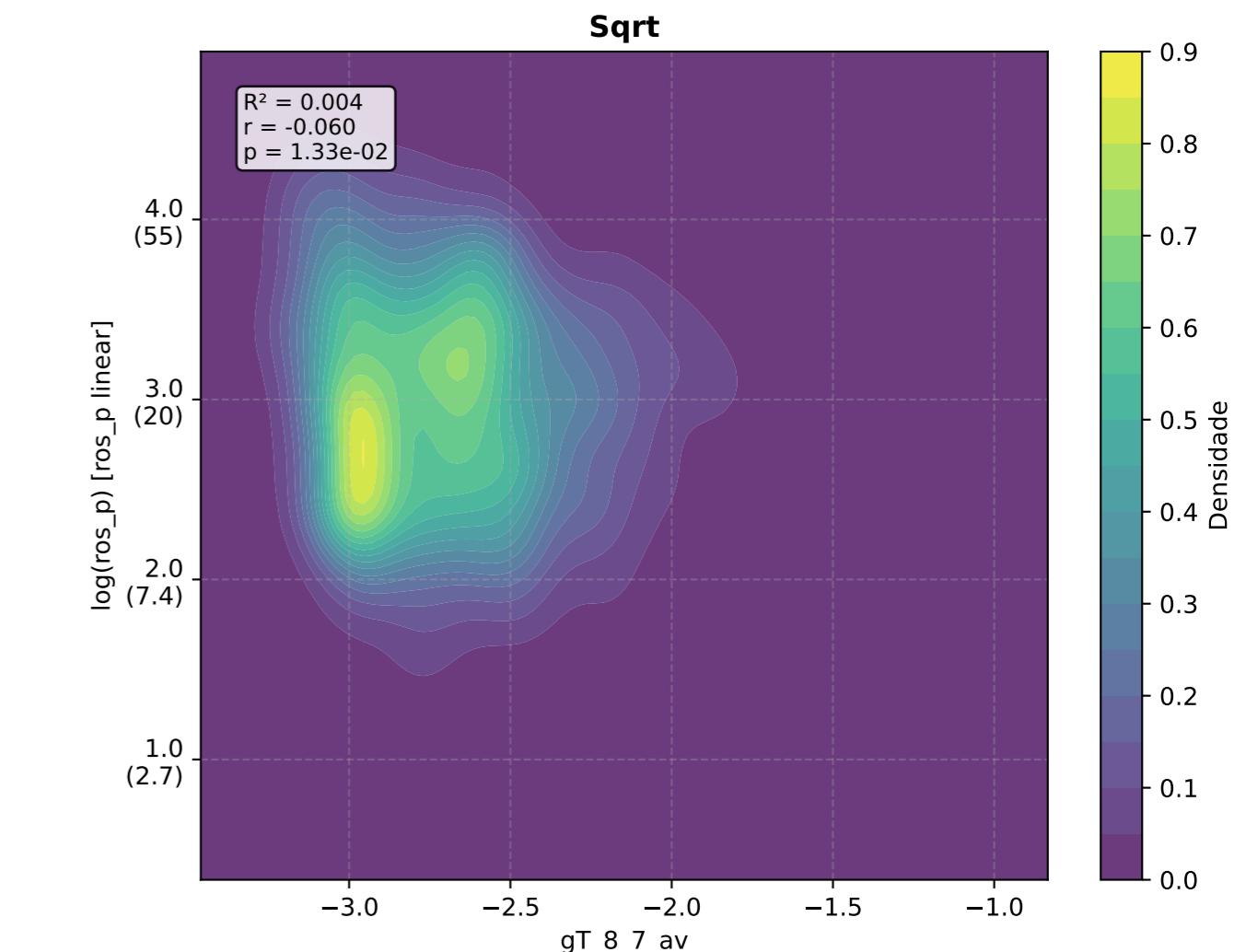
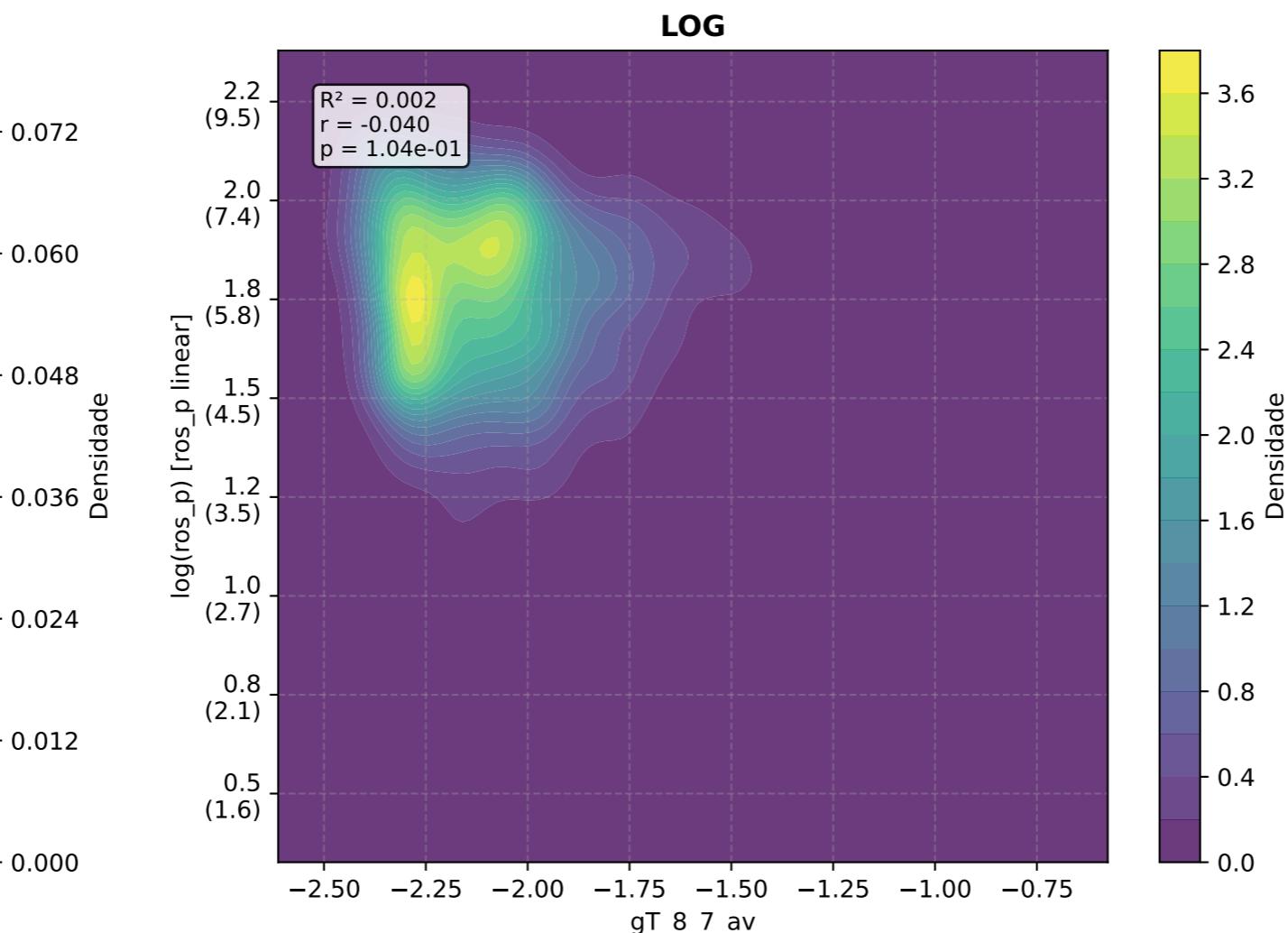
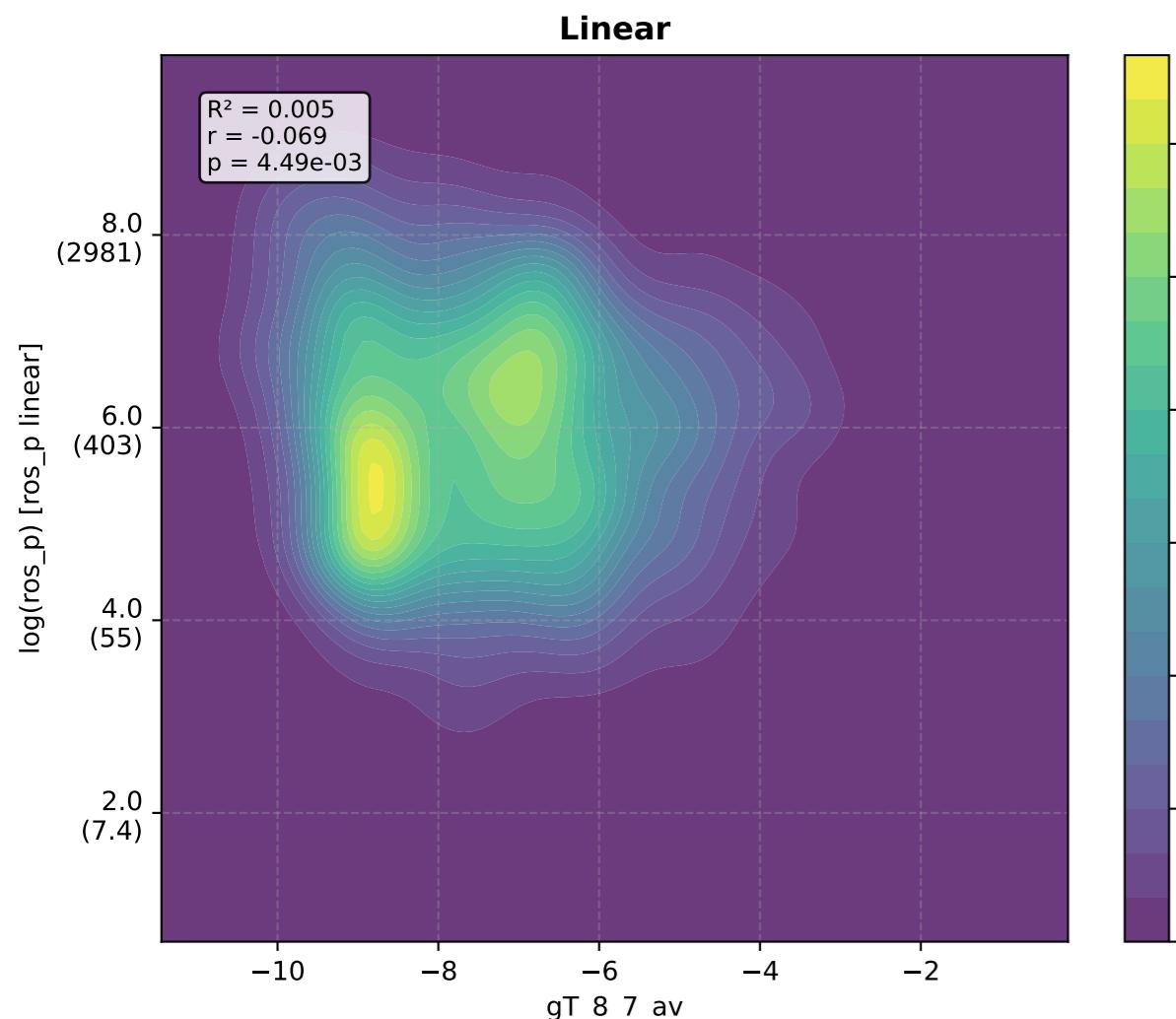
gT_s_9_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



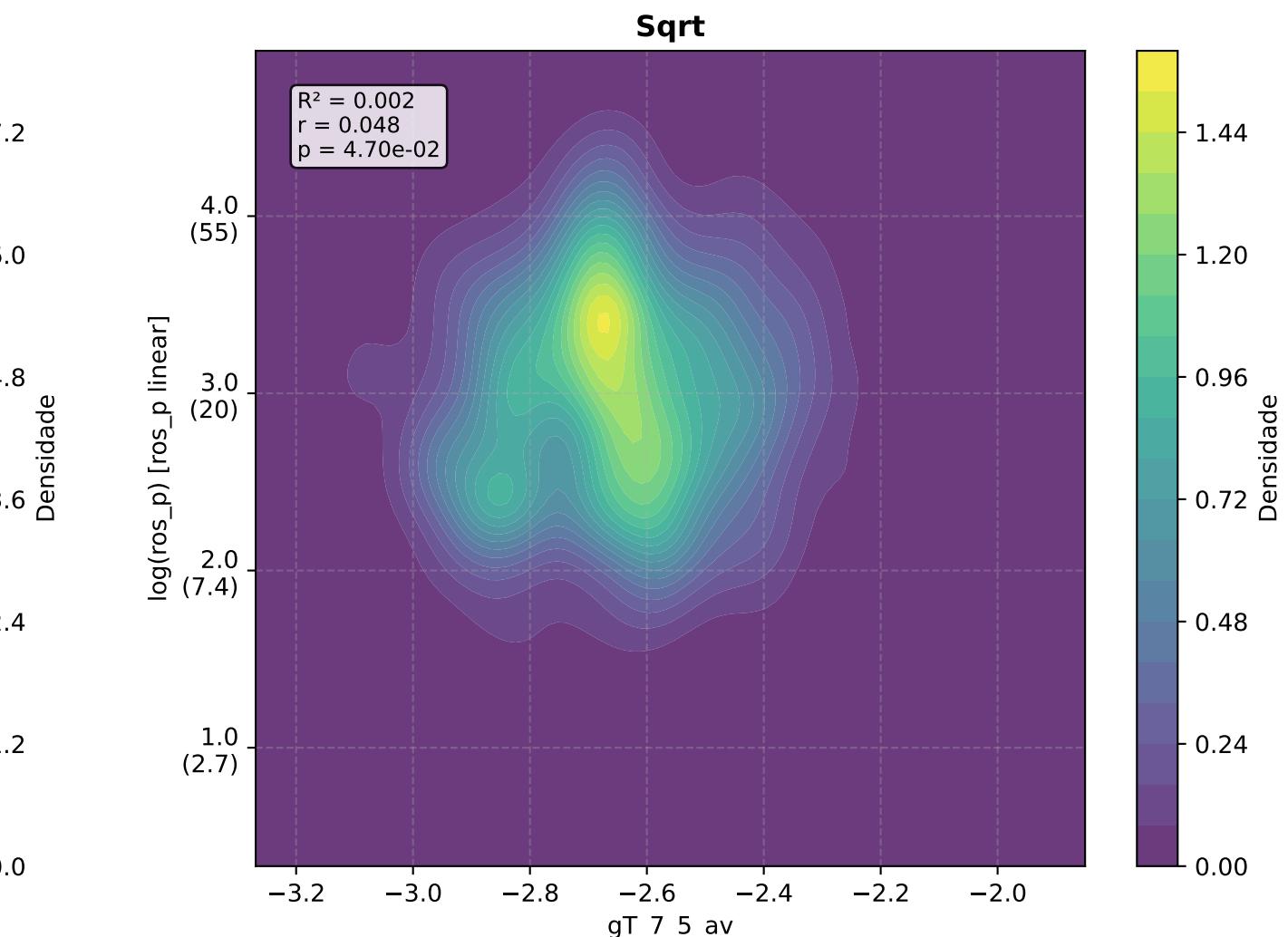
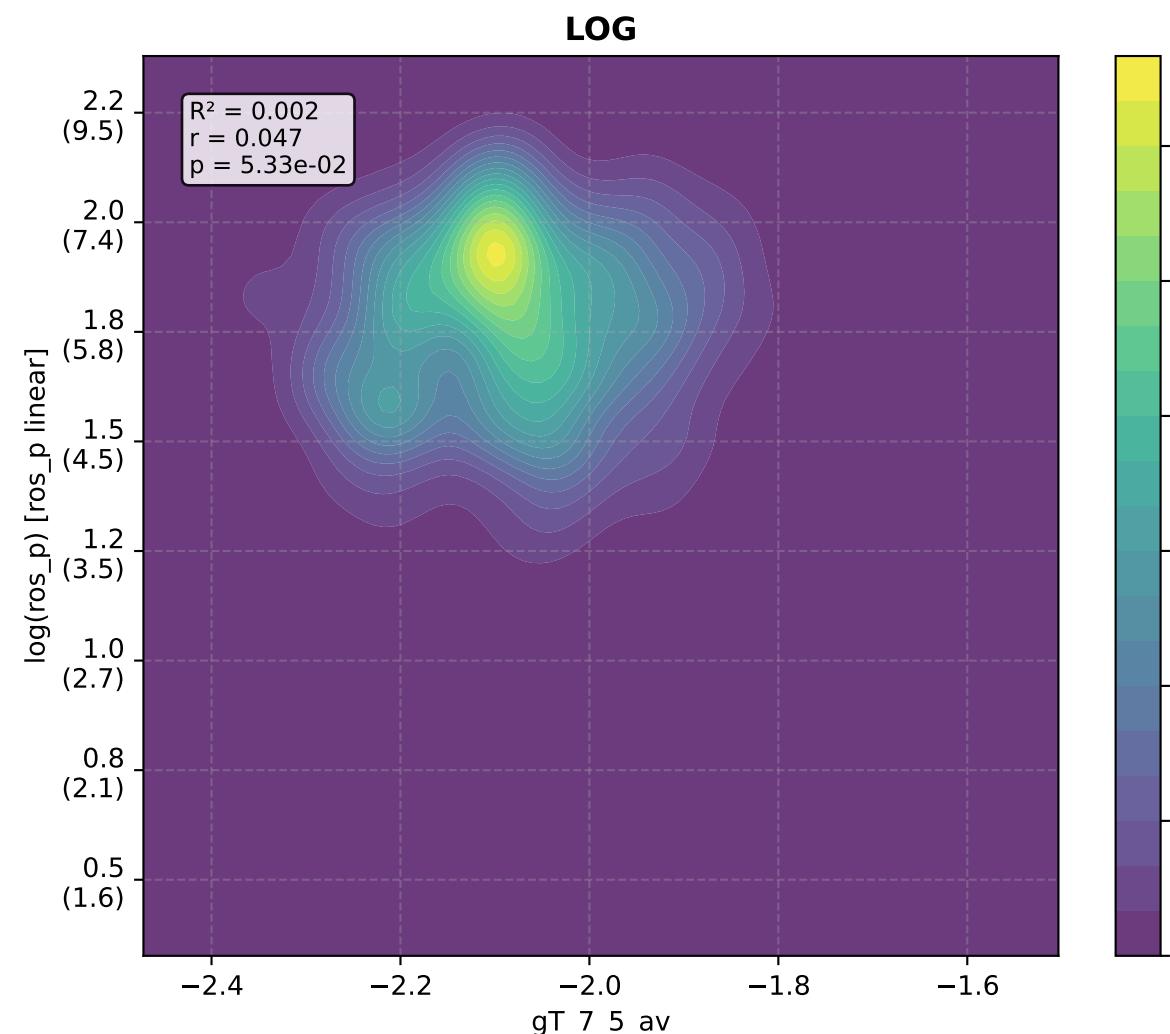
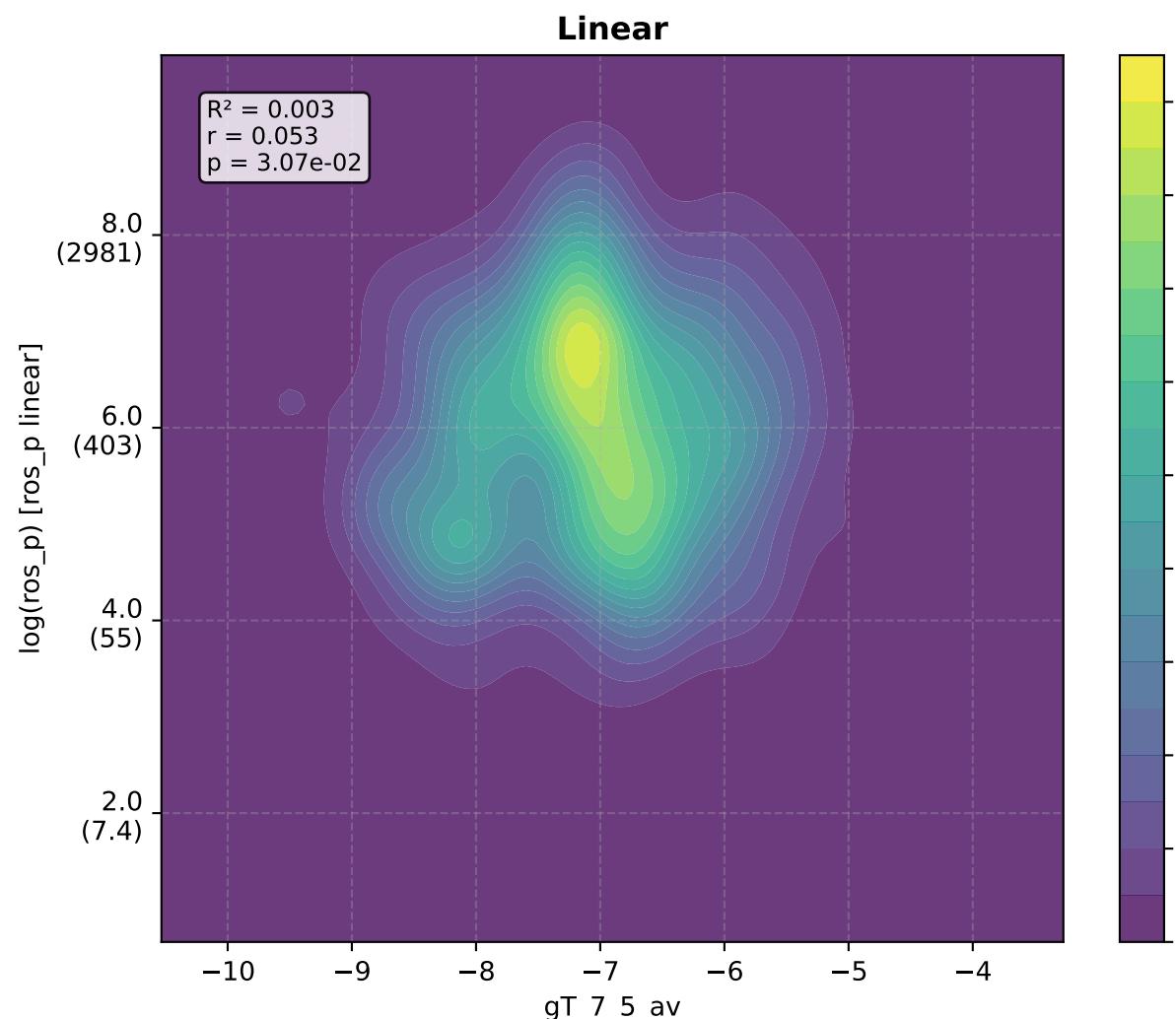
gT_9_8_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



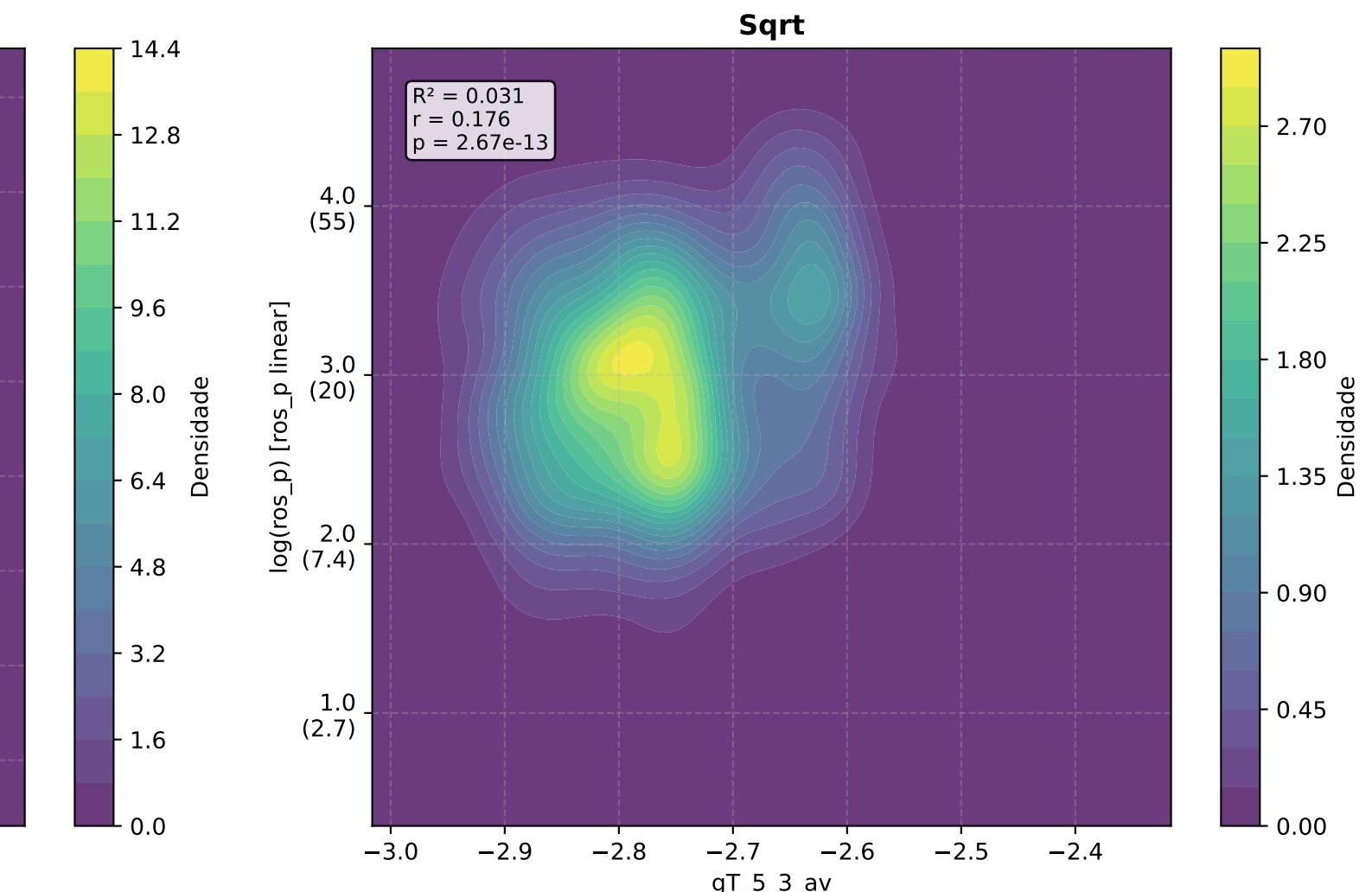
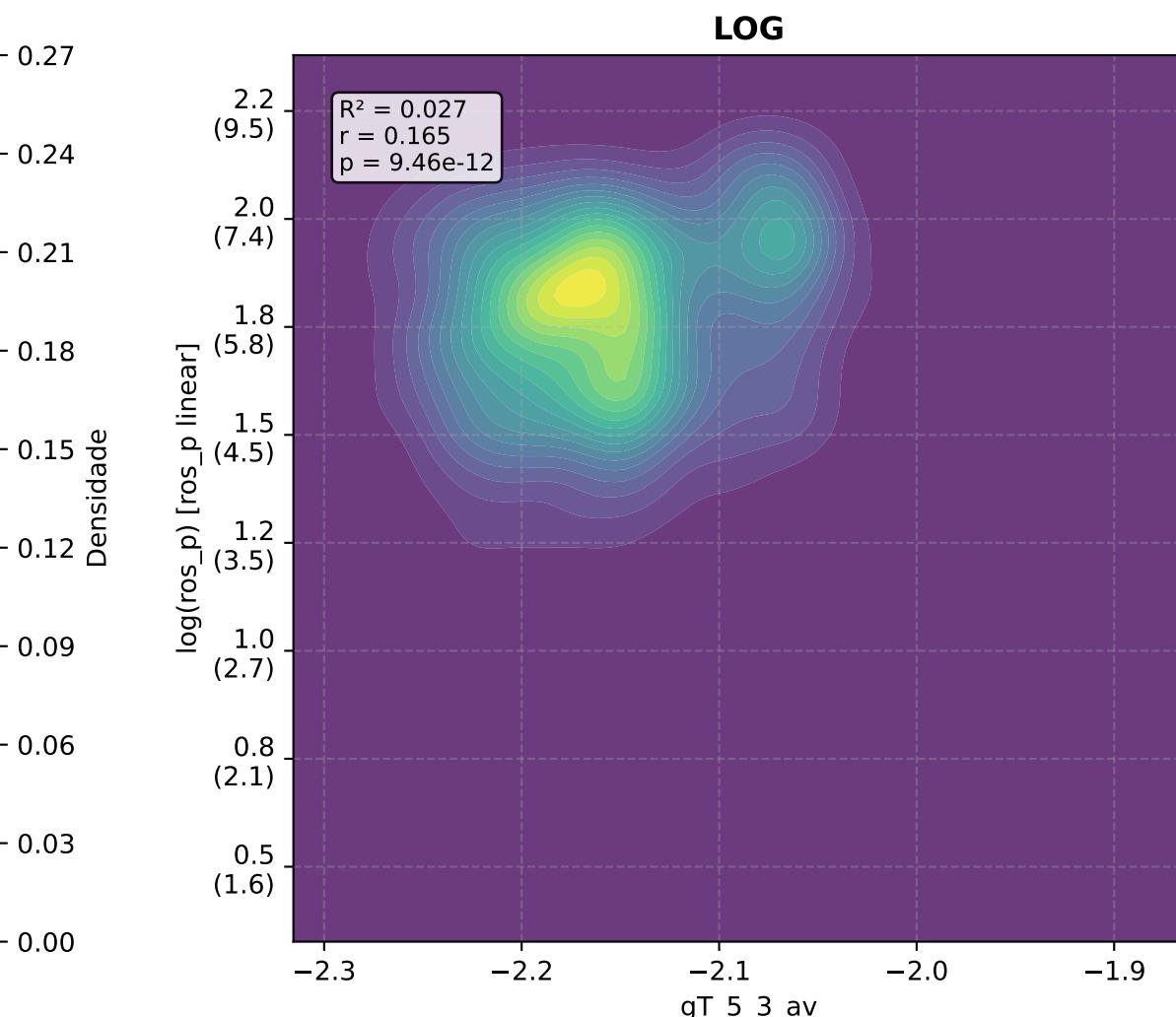
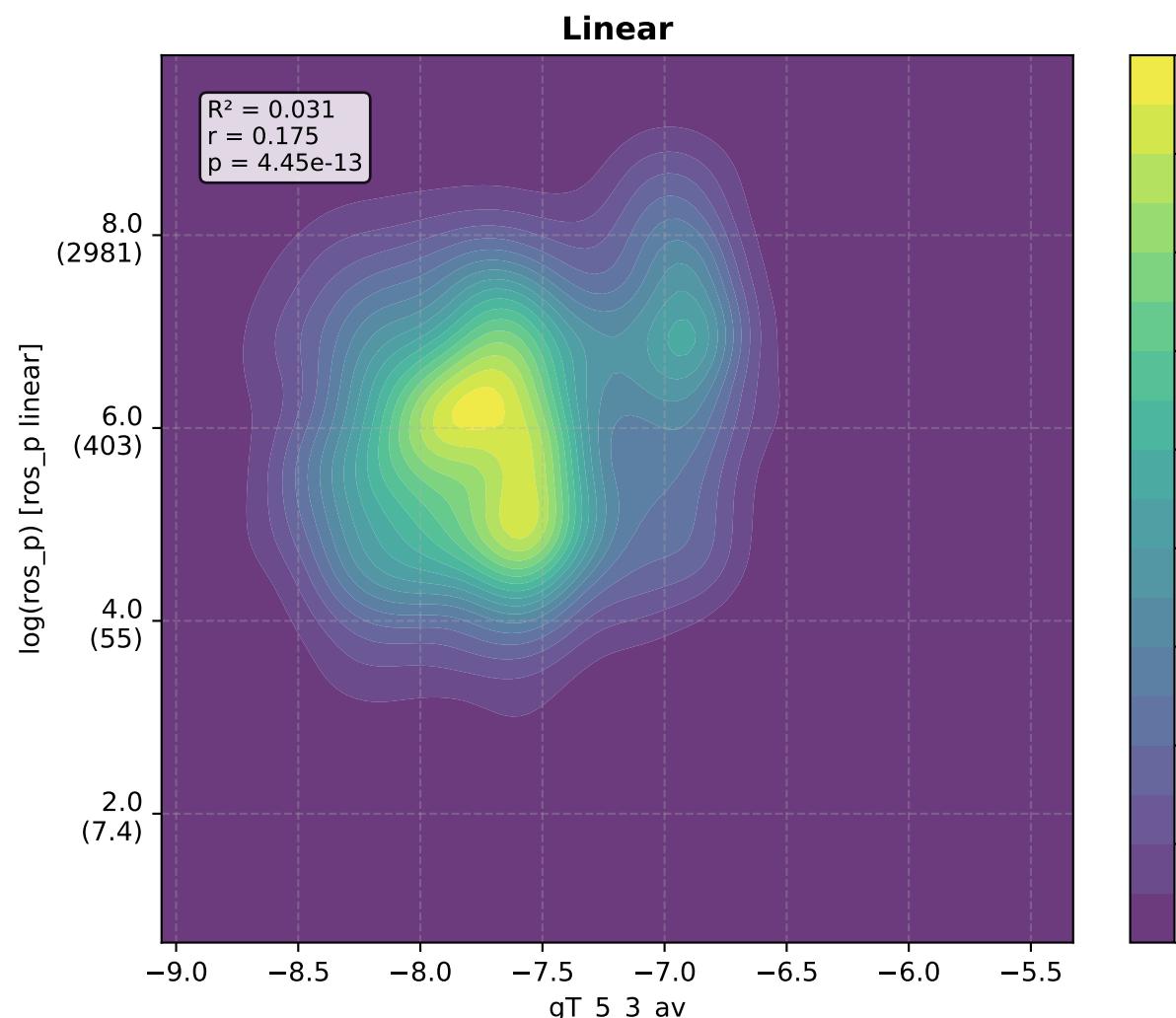
gT_8_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



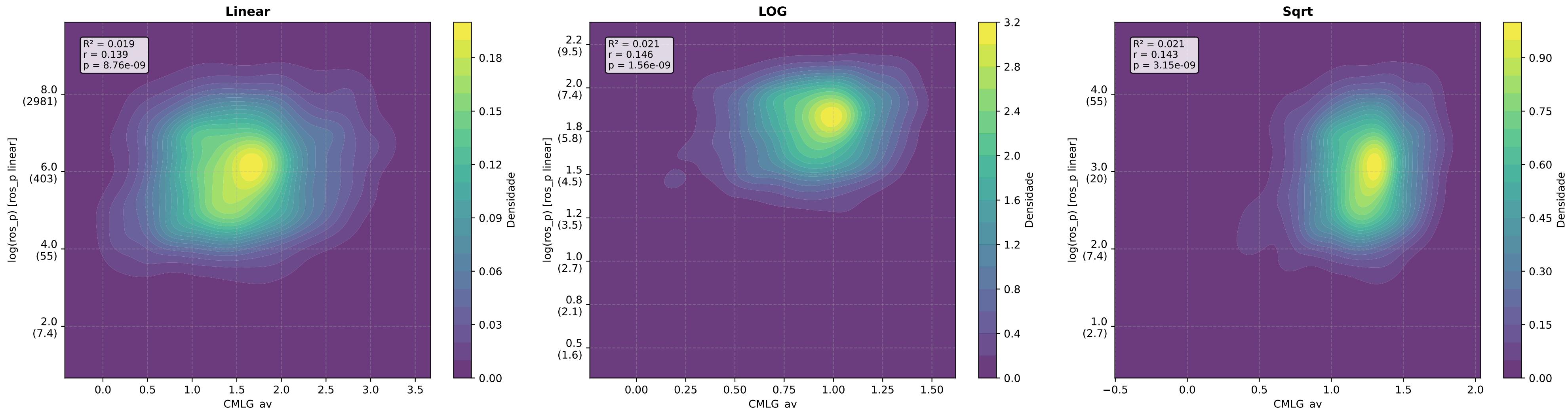
gT_7_5_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



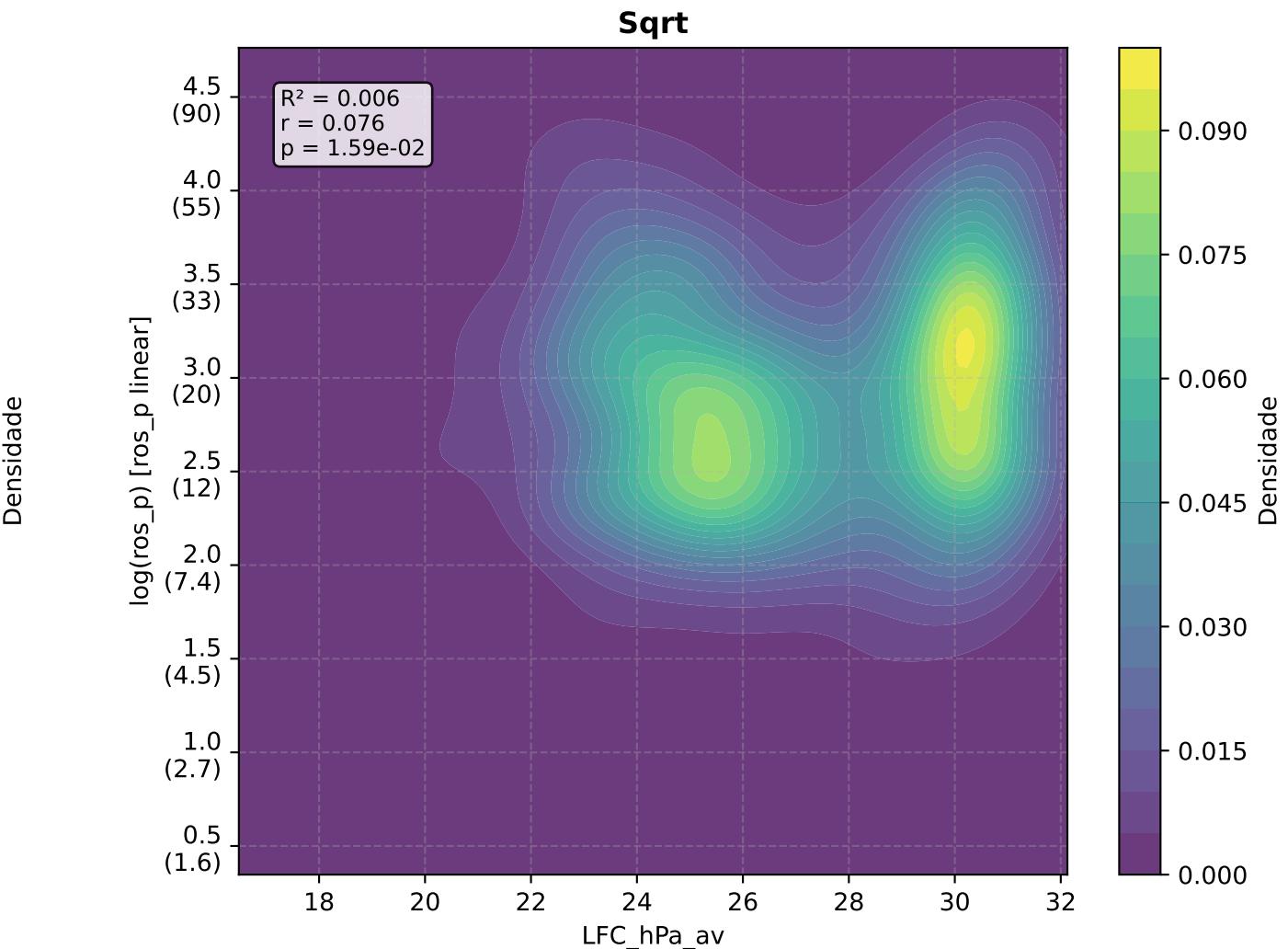
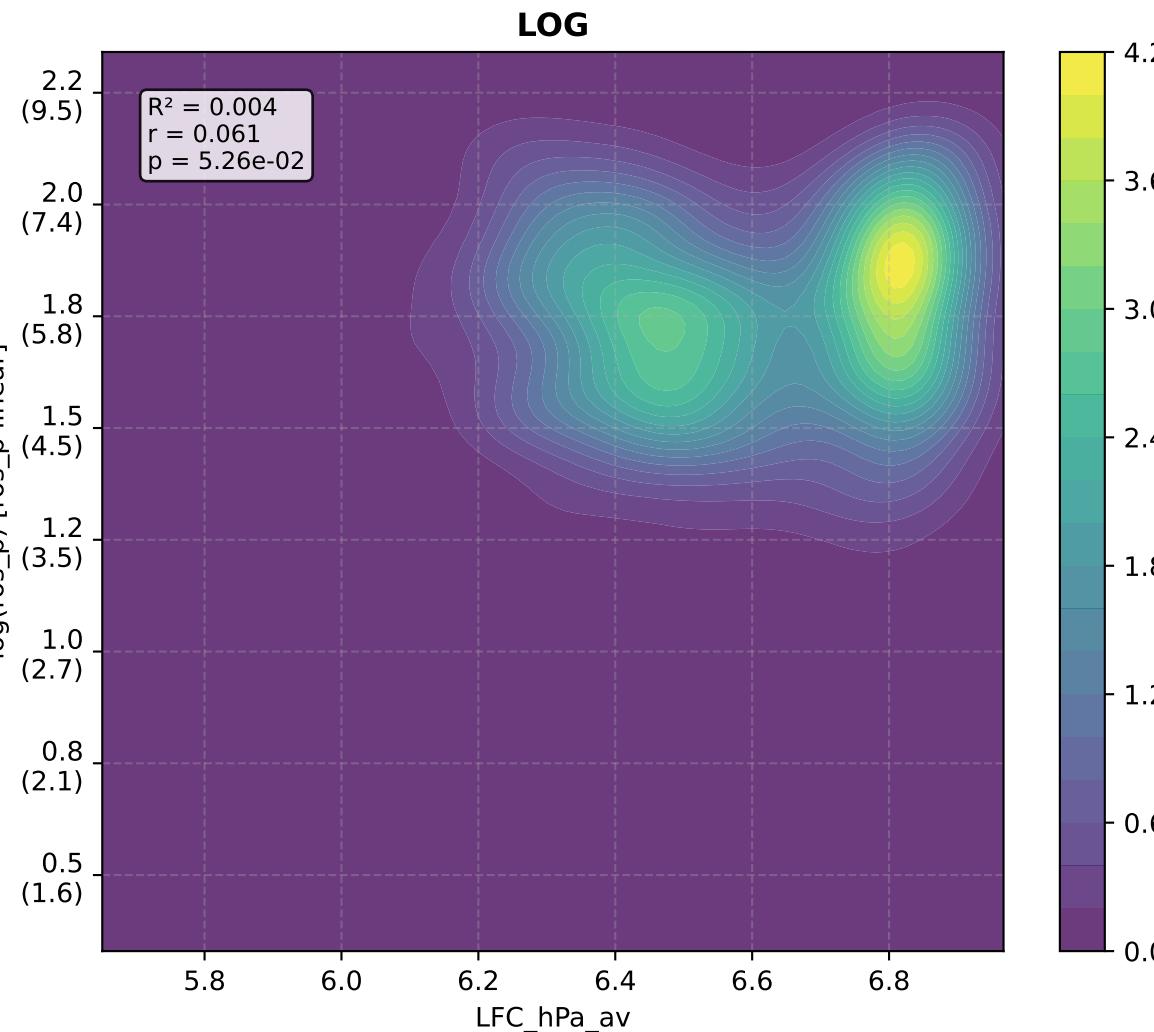
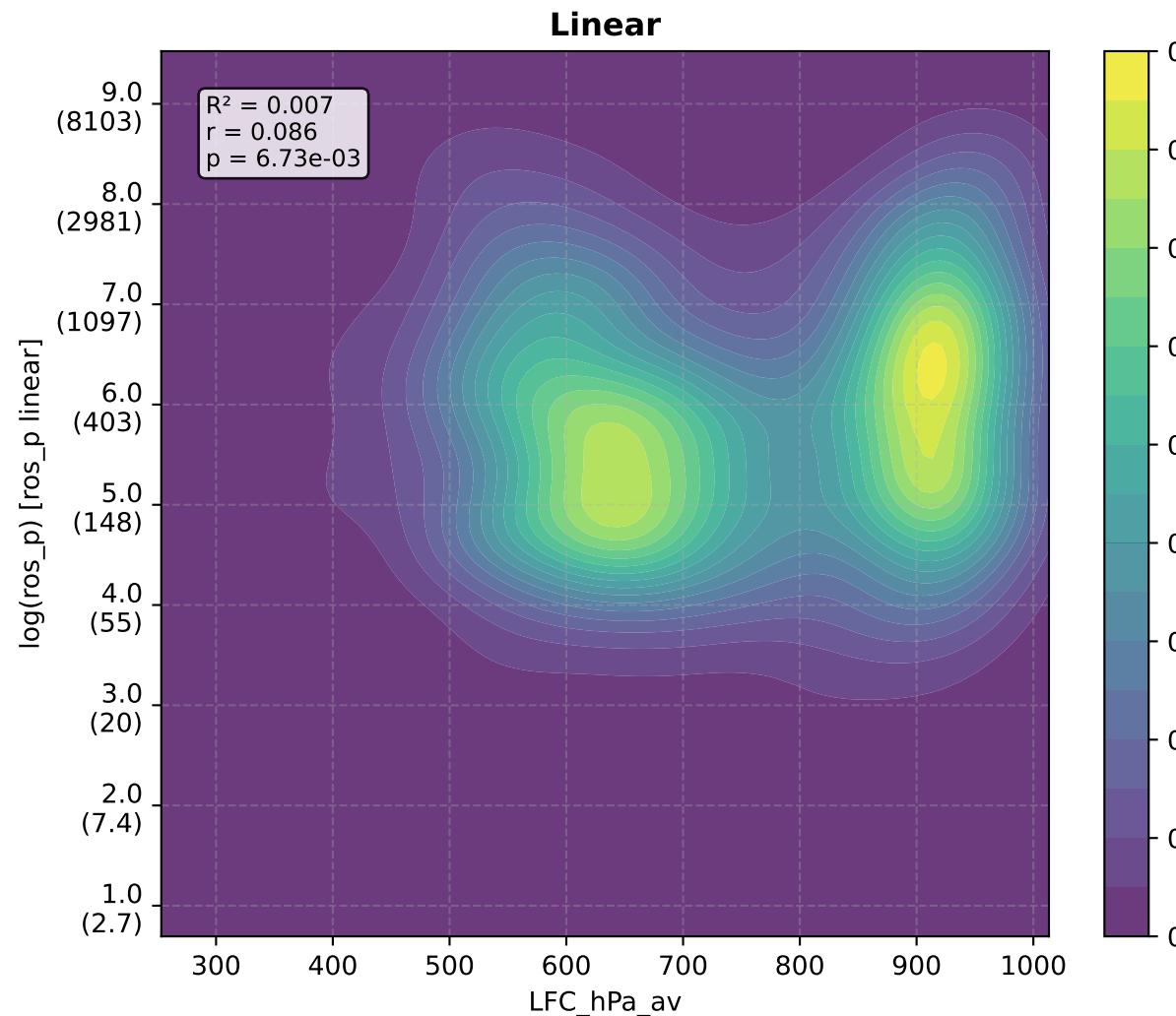
gT_5_3_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



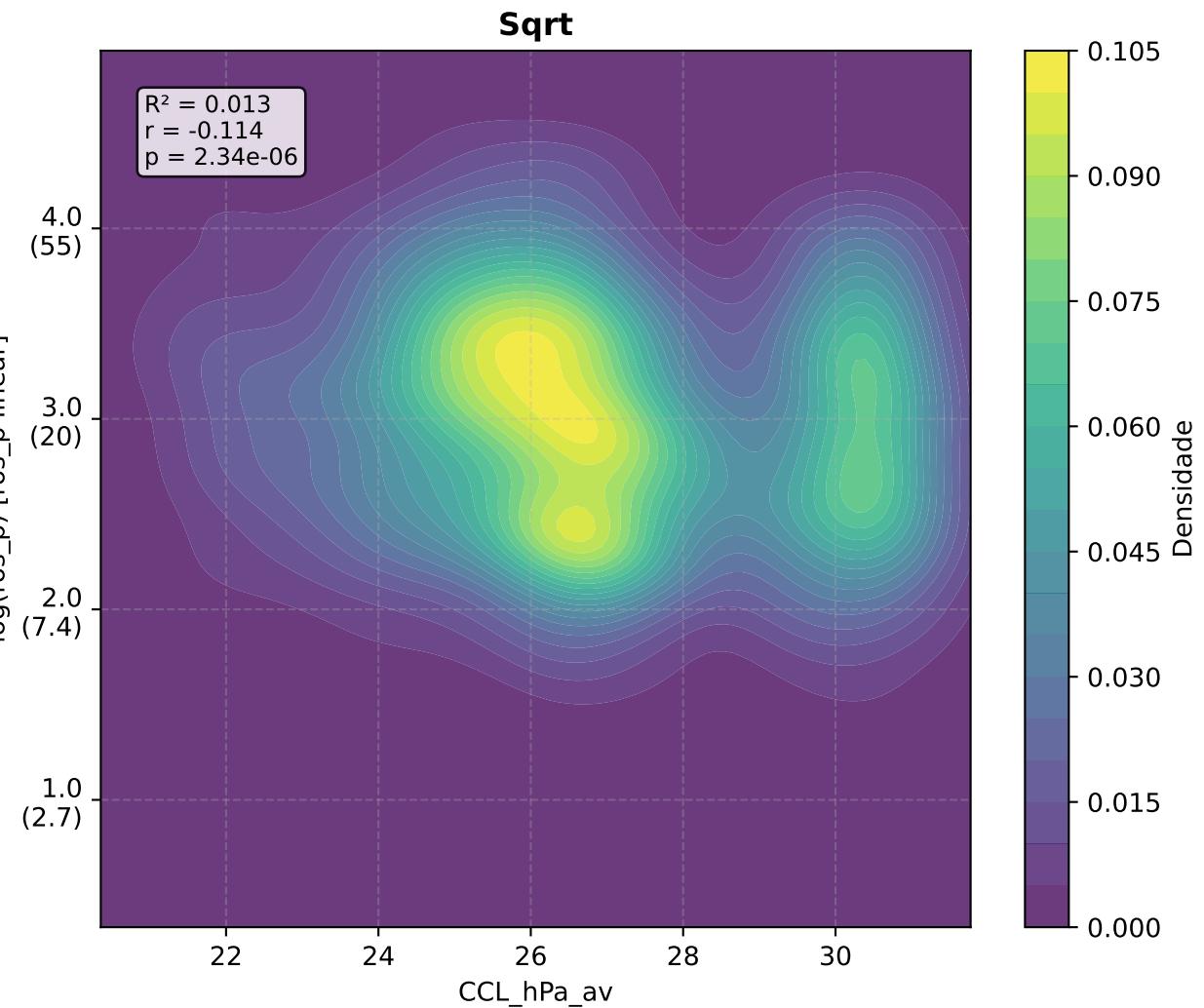
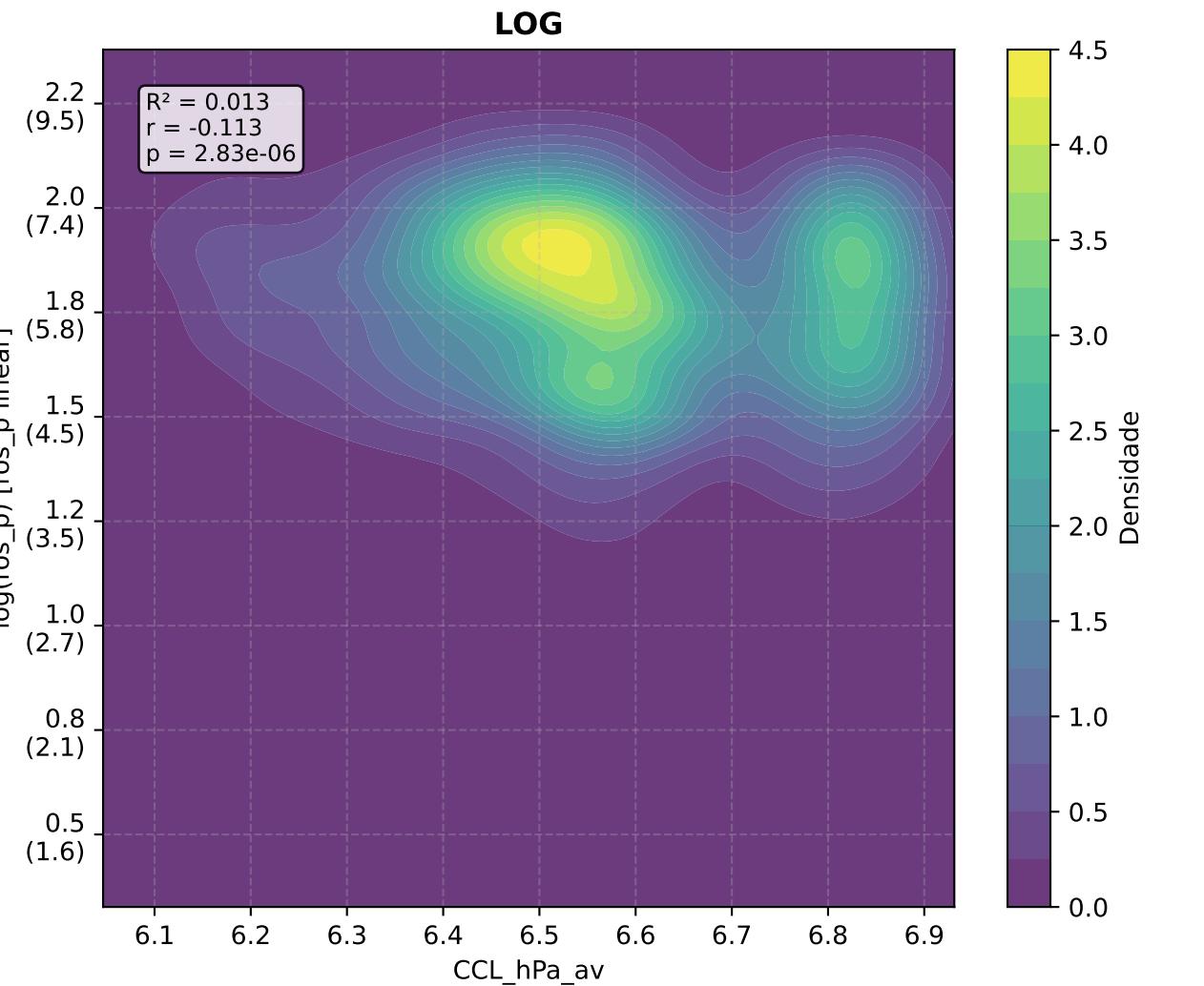
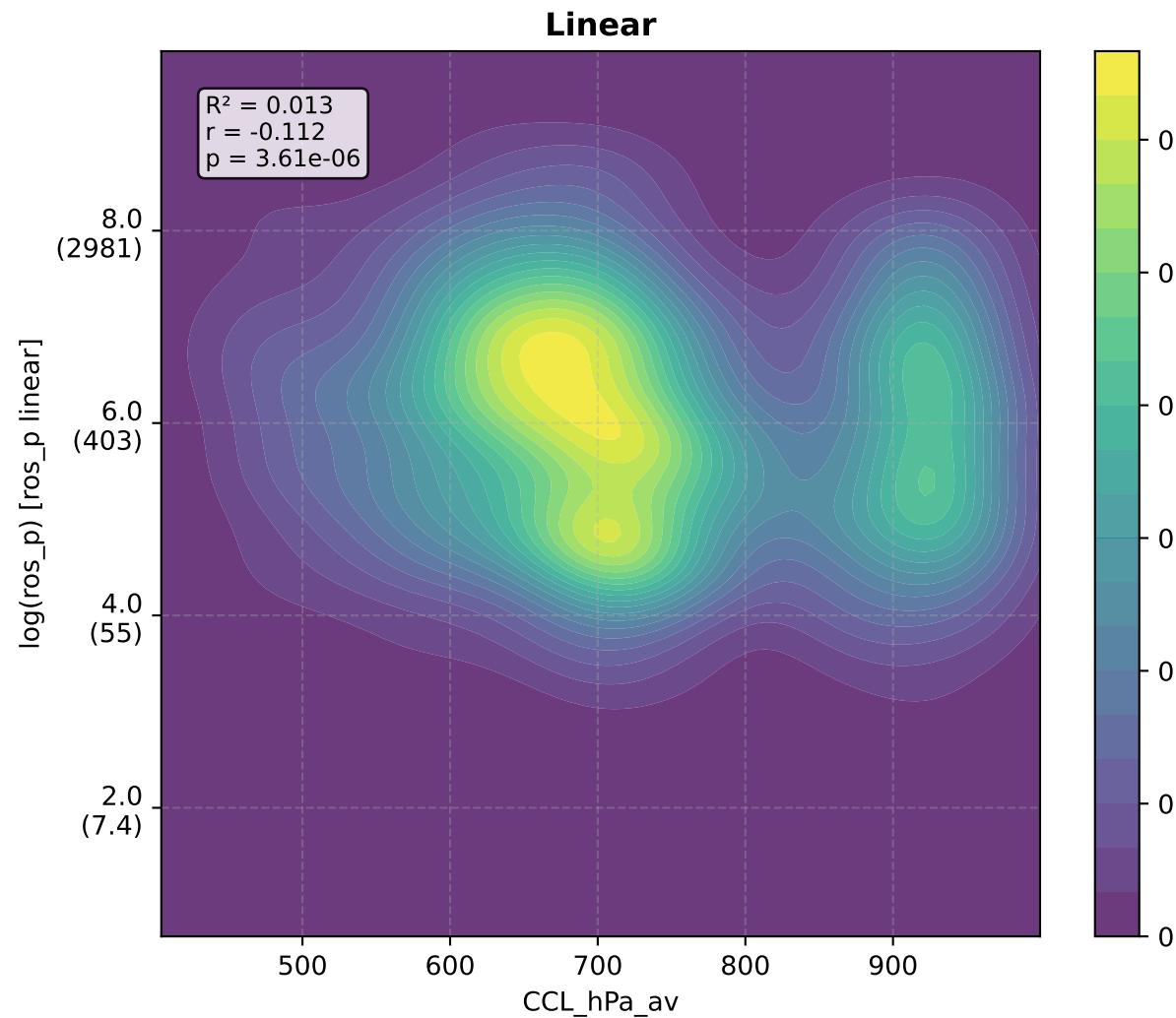
CMLG_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



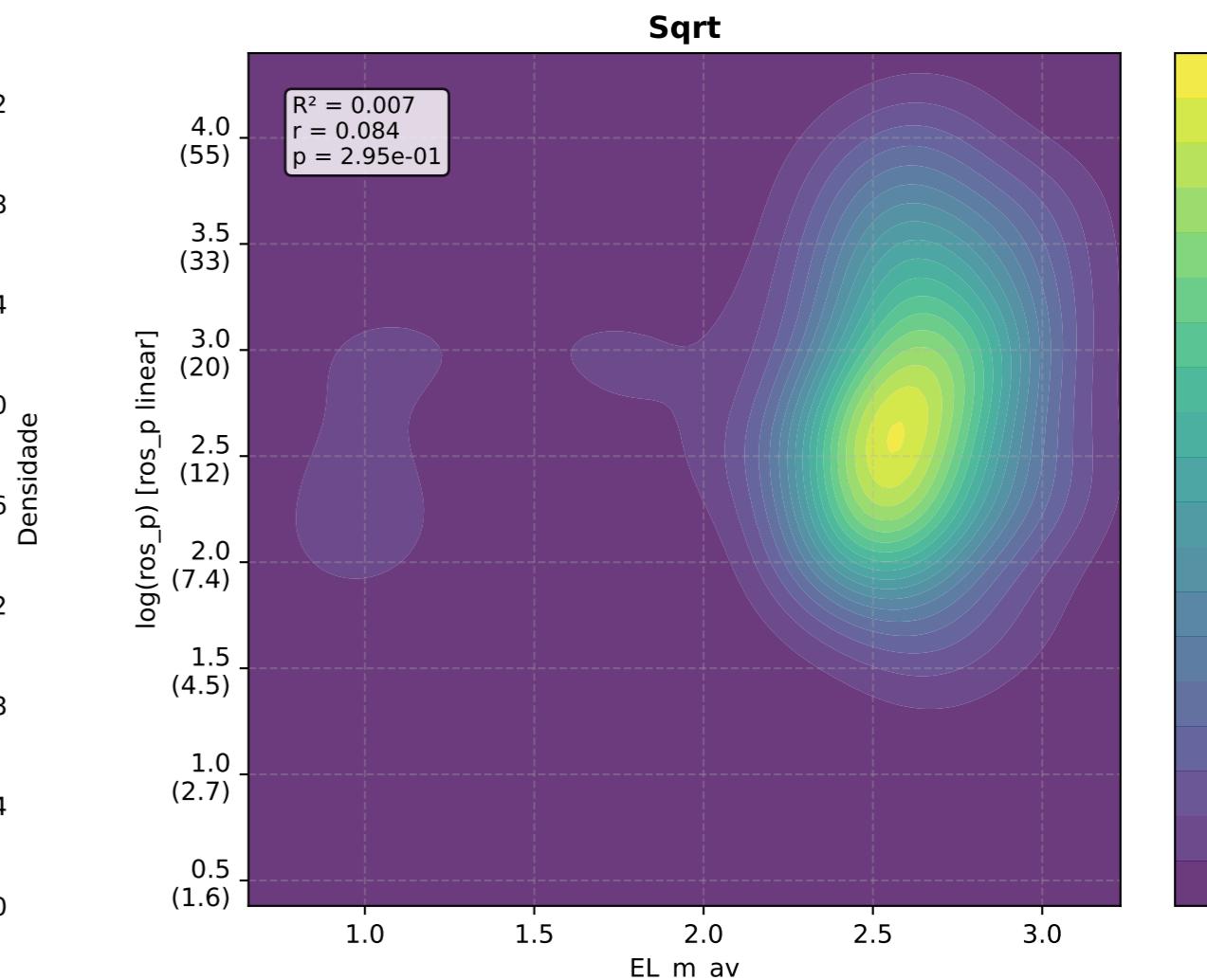
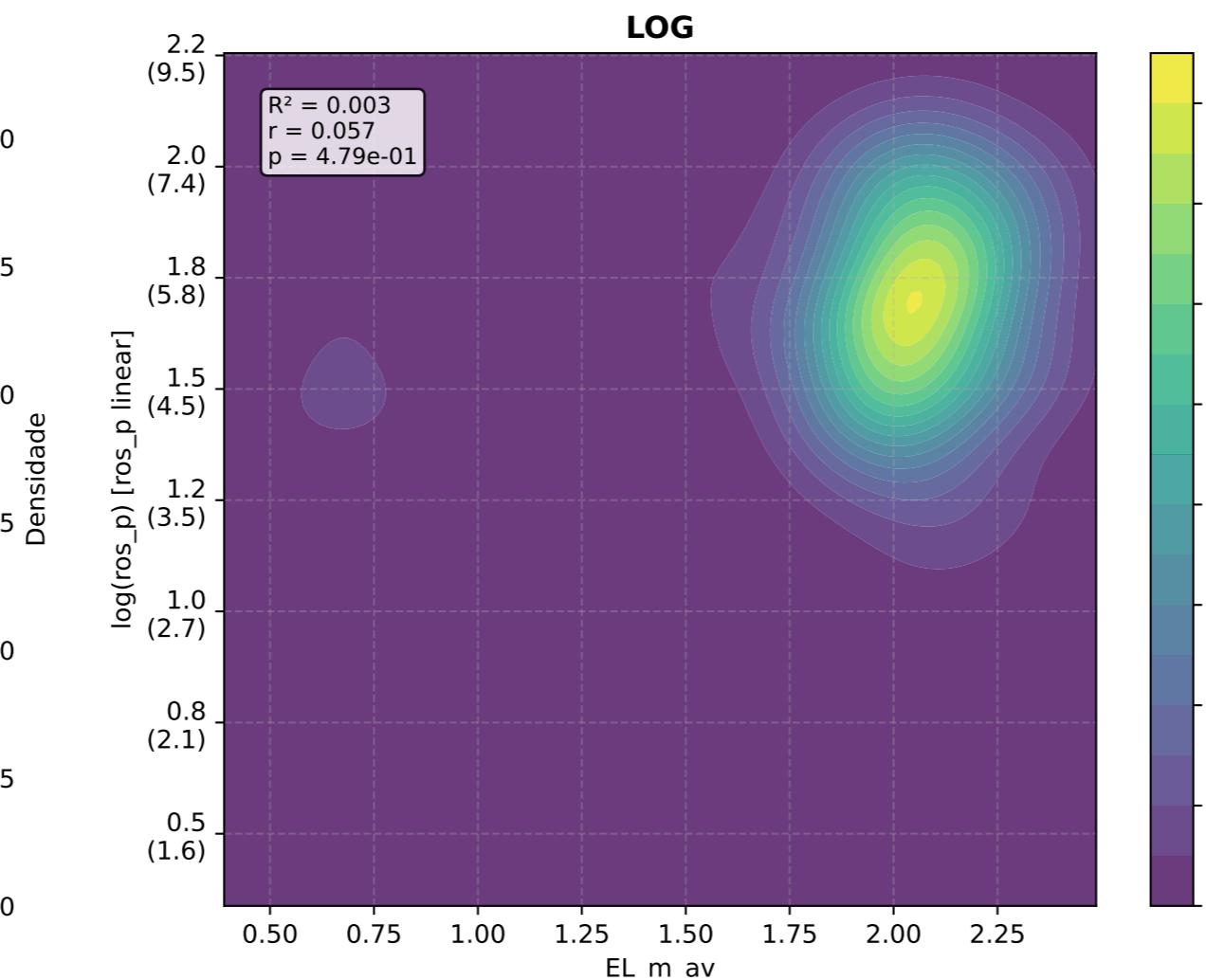
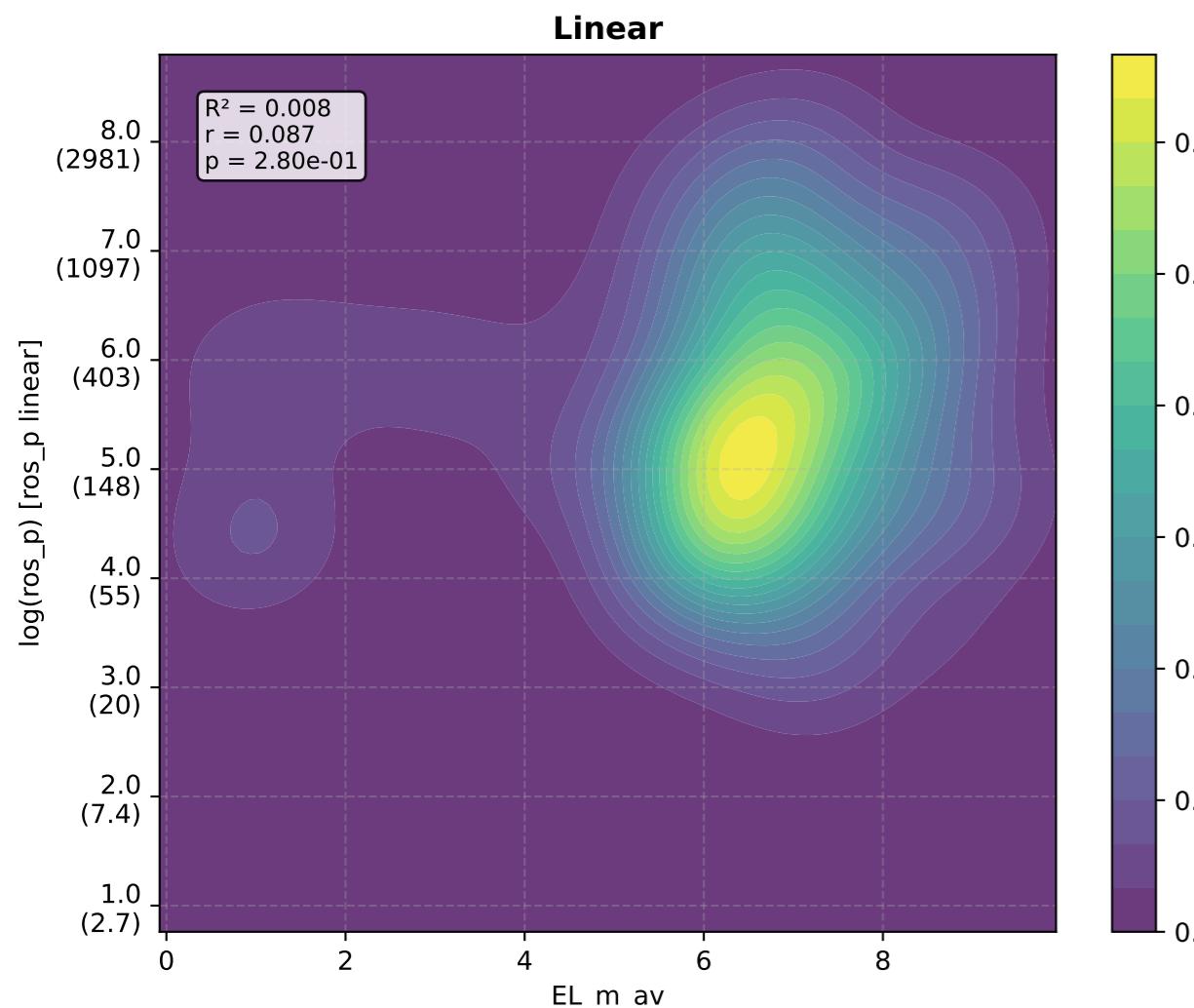
LFC_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



CCL_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



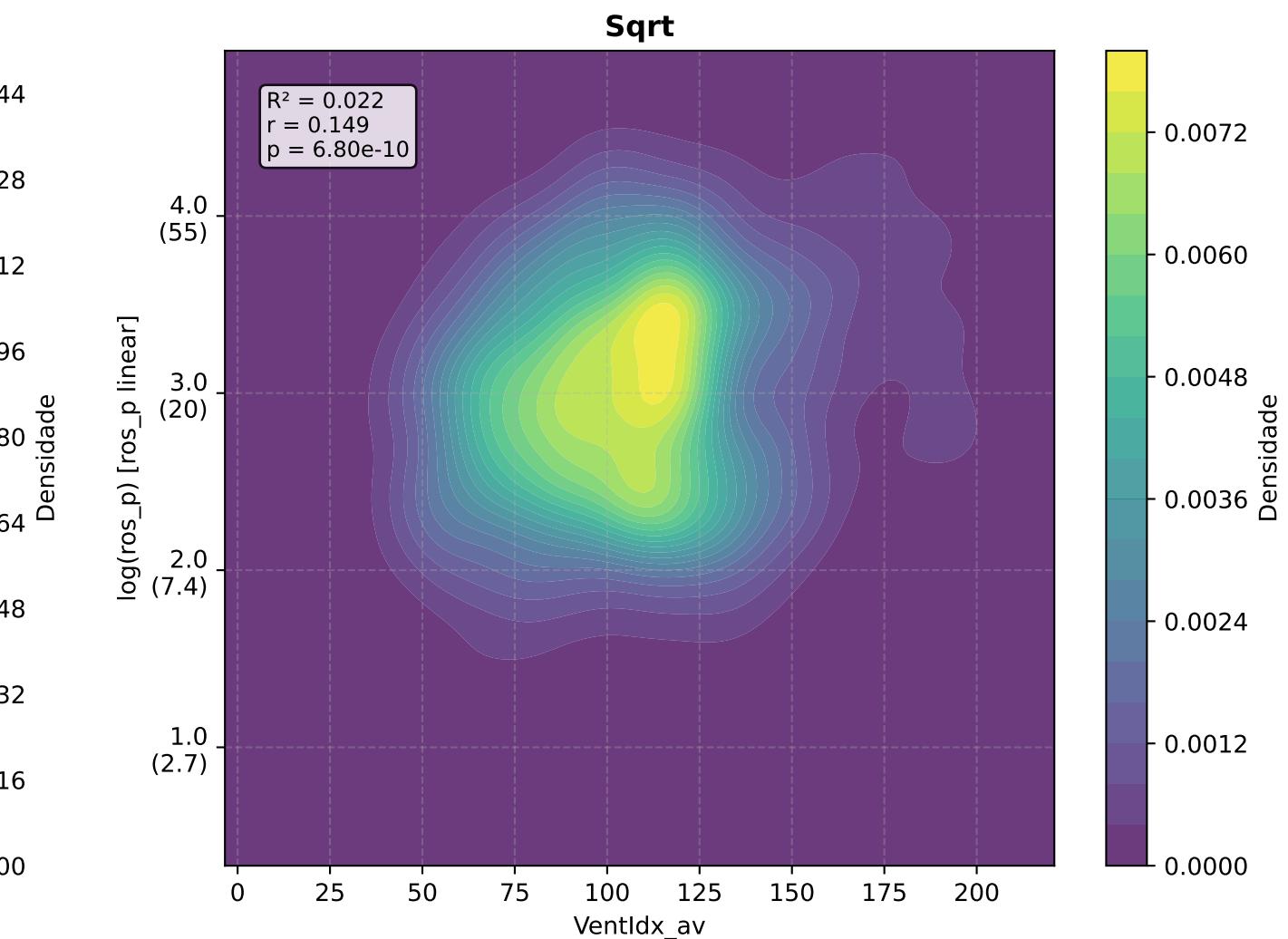
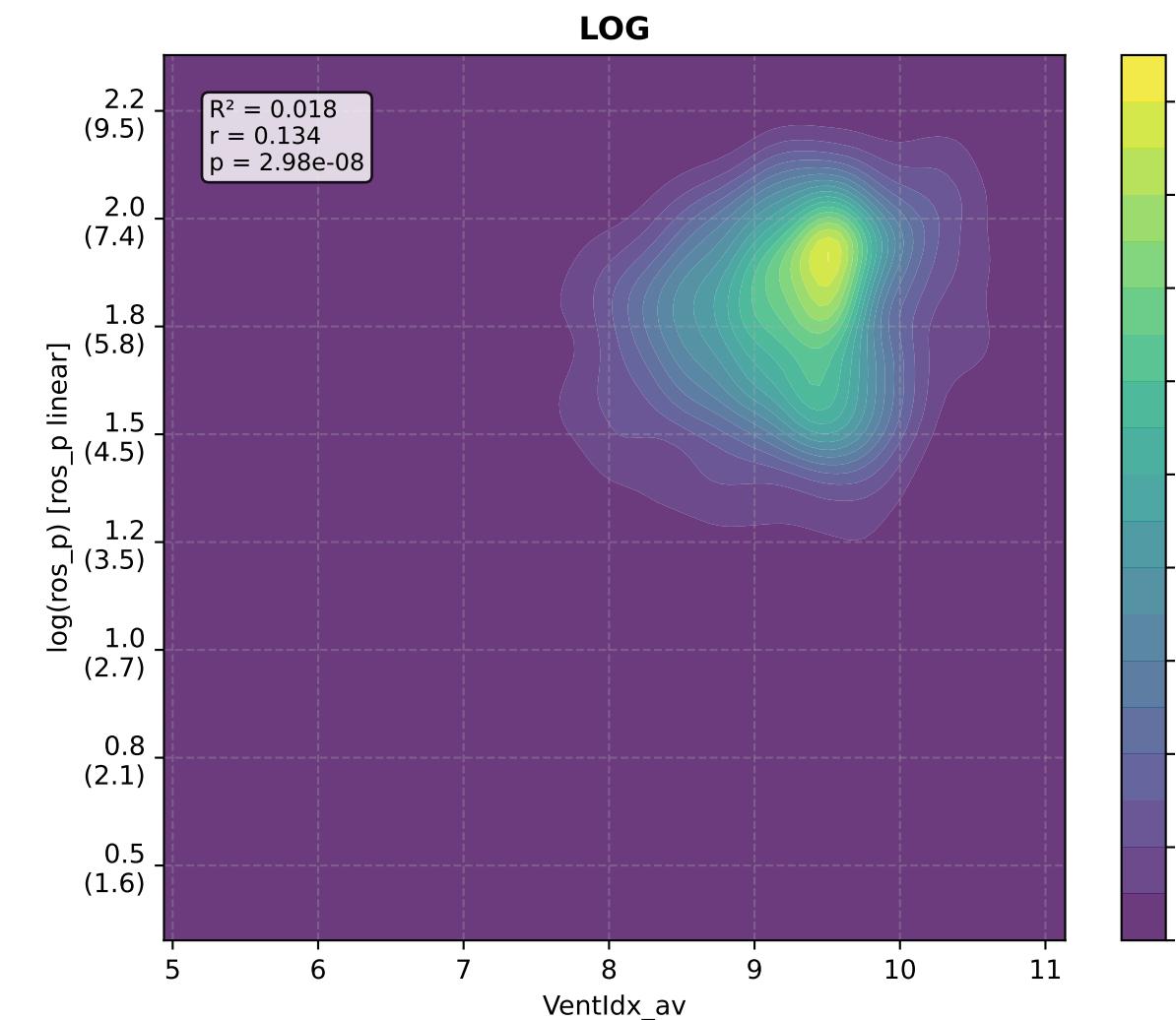
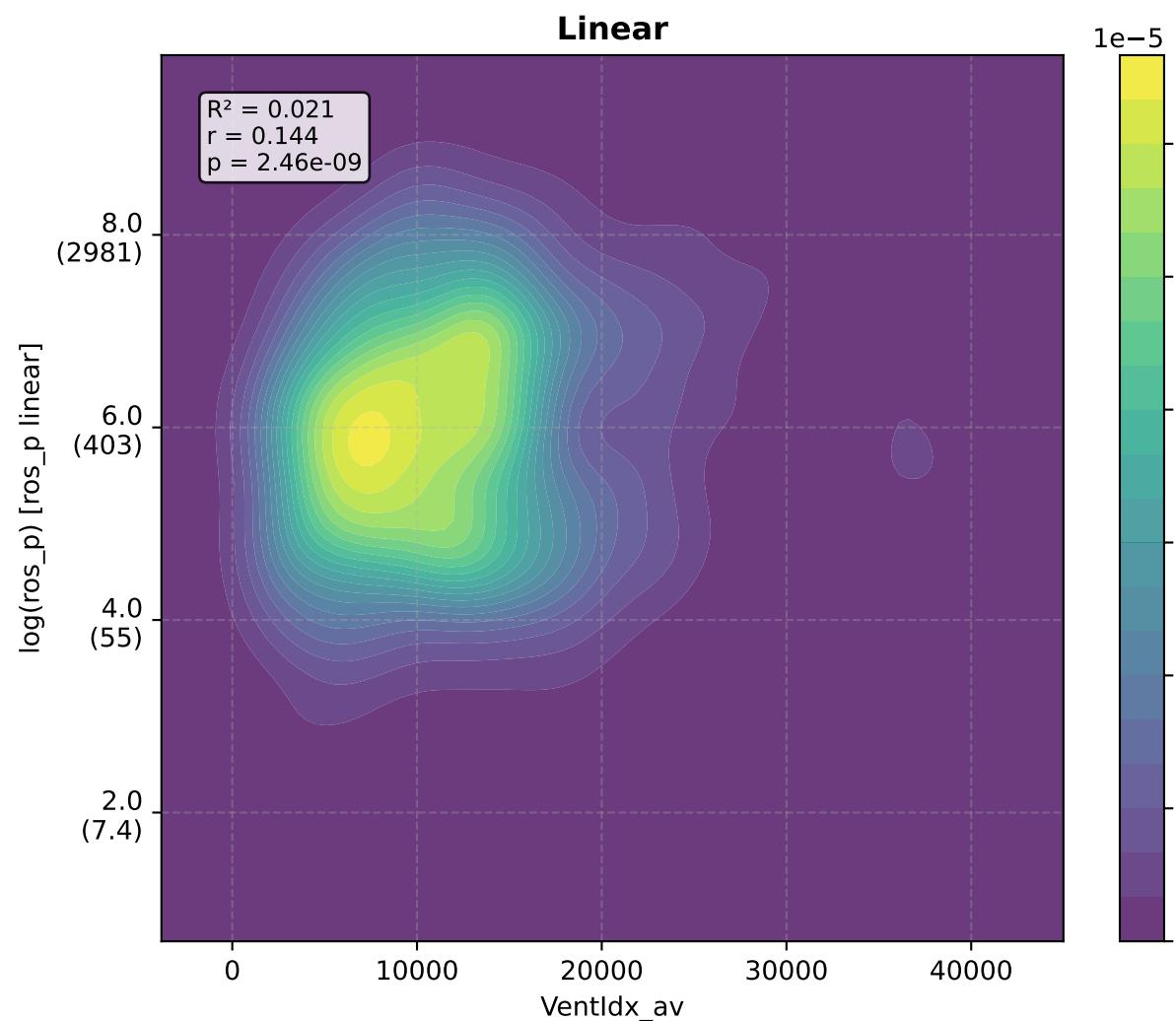
EL_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



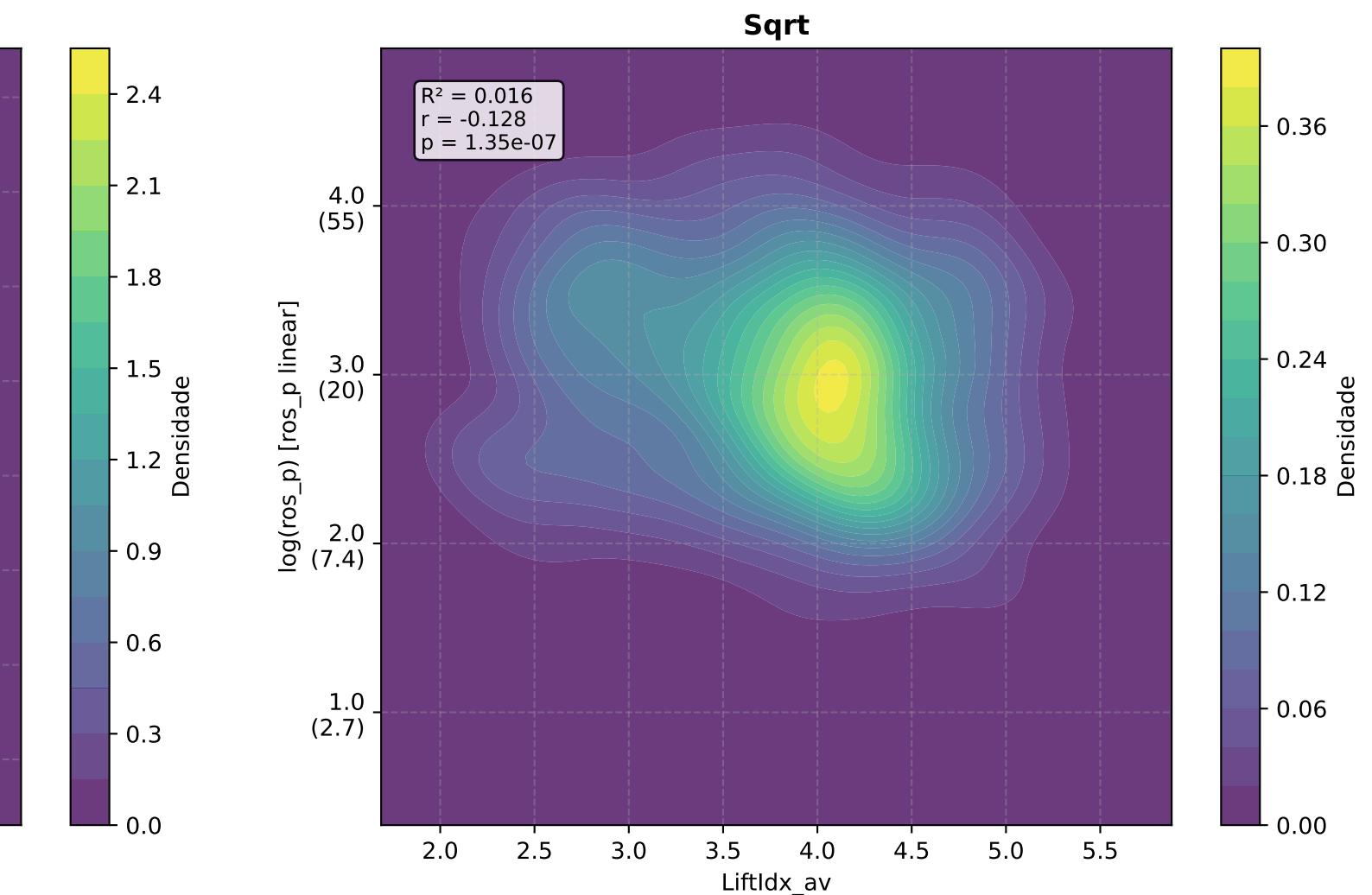
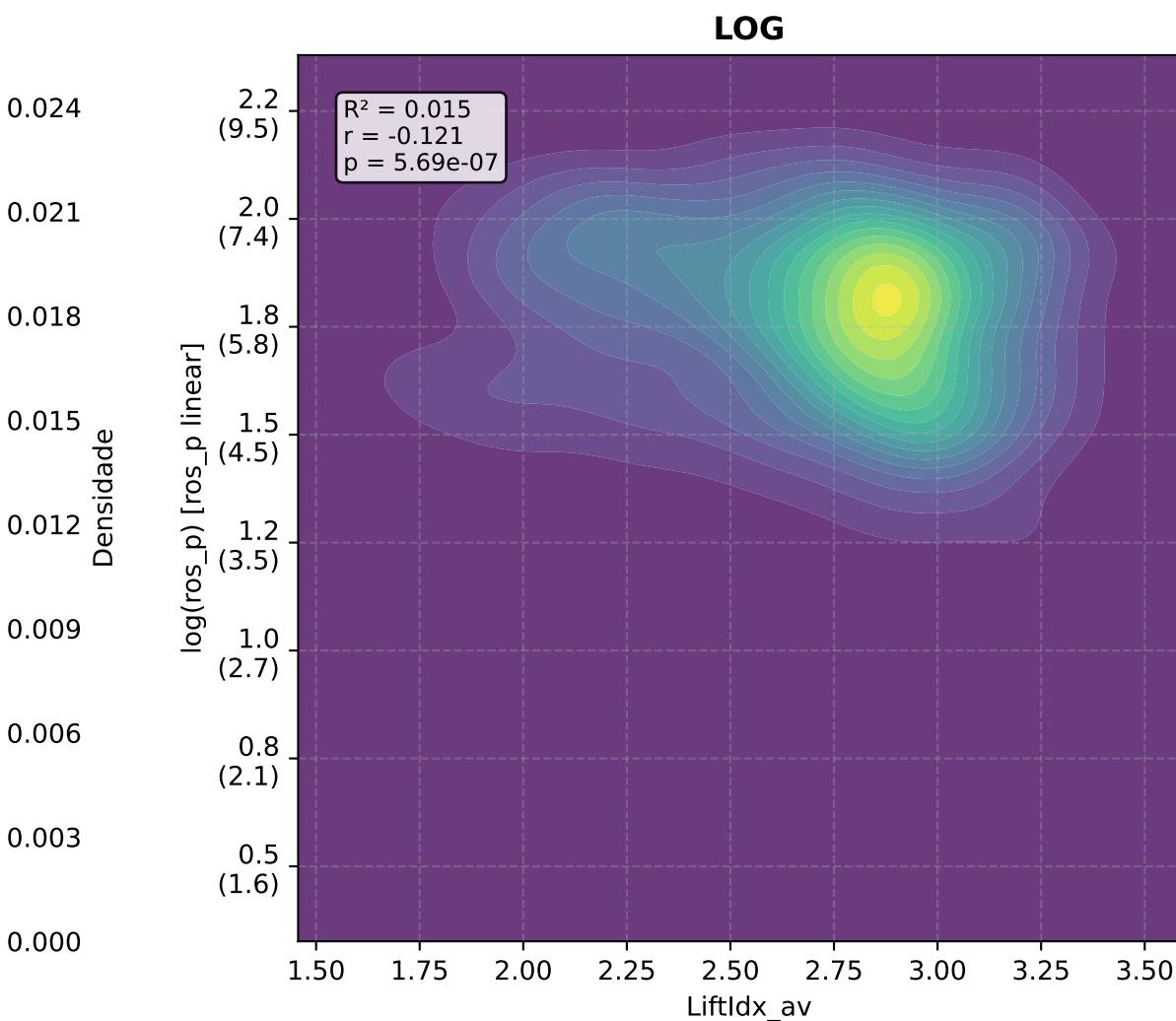
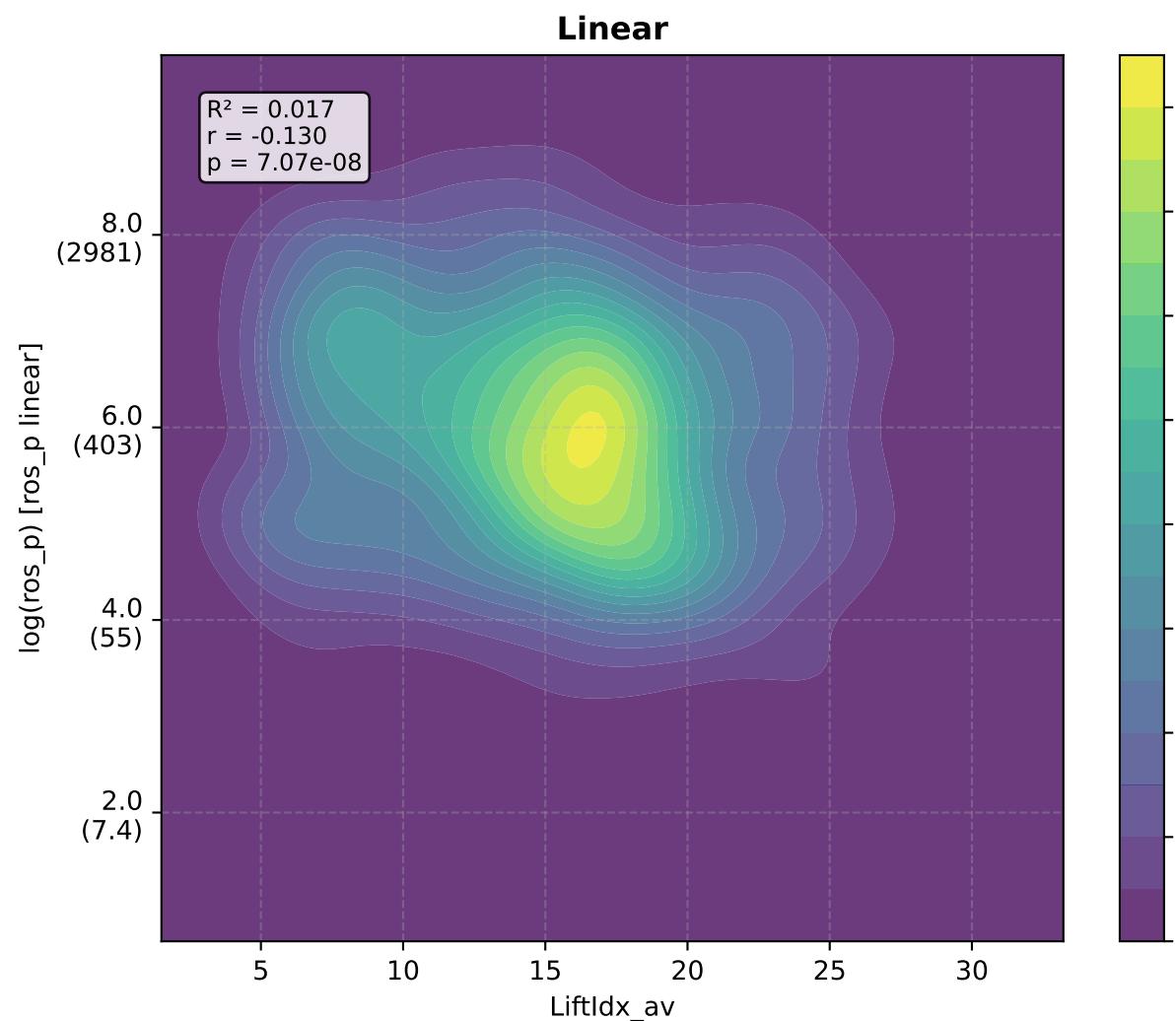
Densidade

Densidade

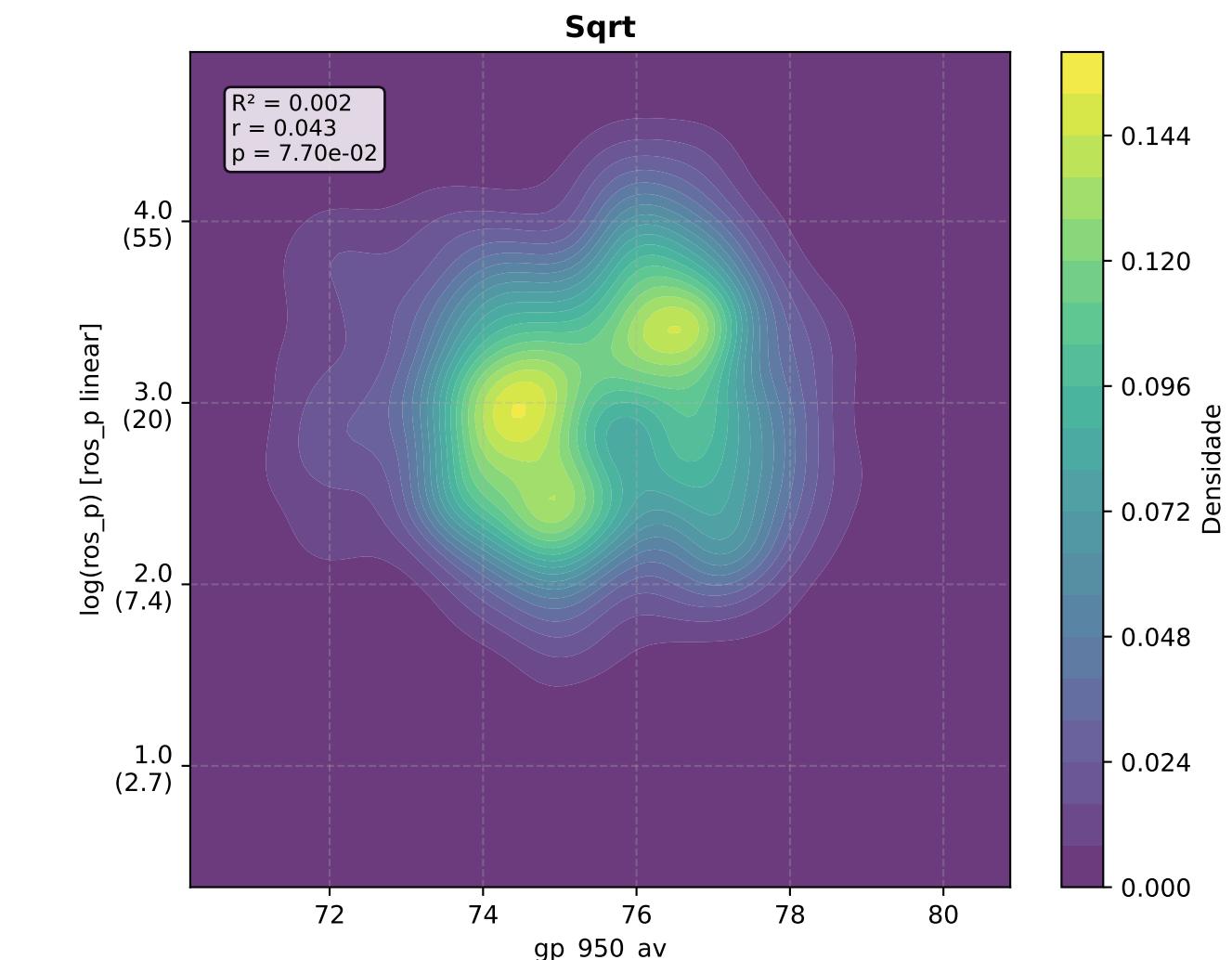
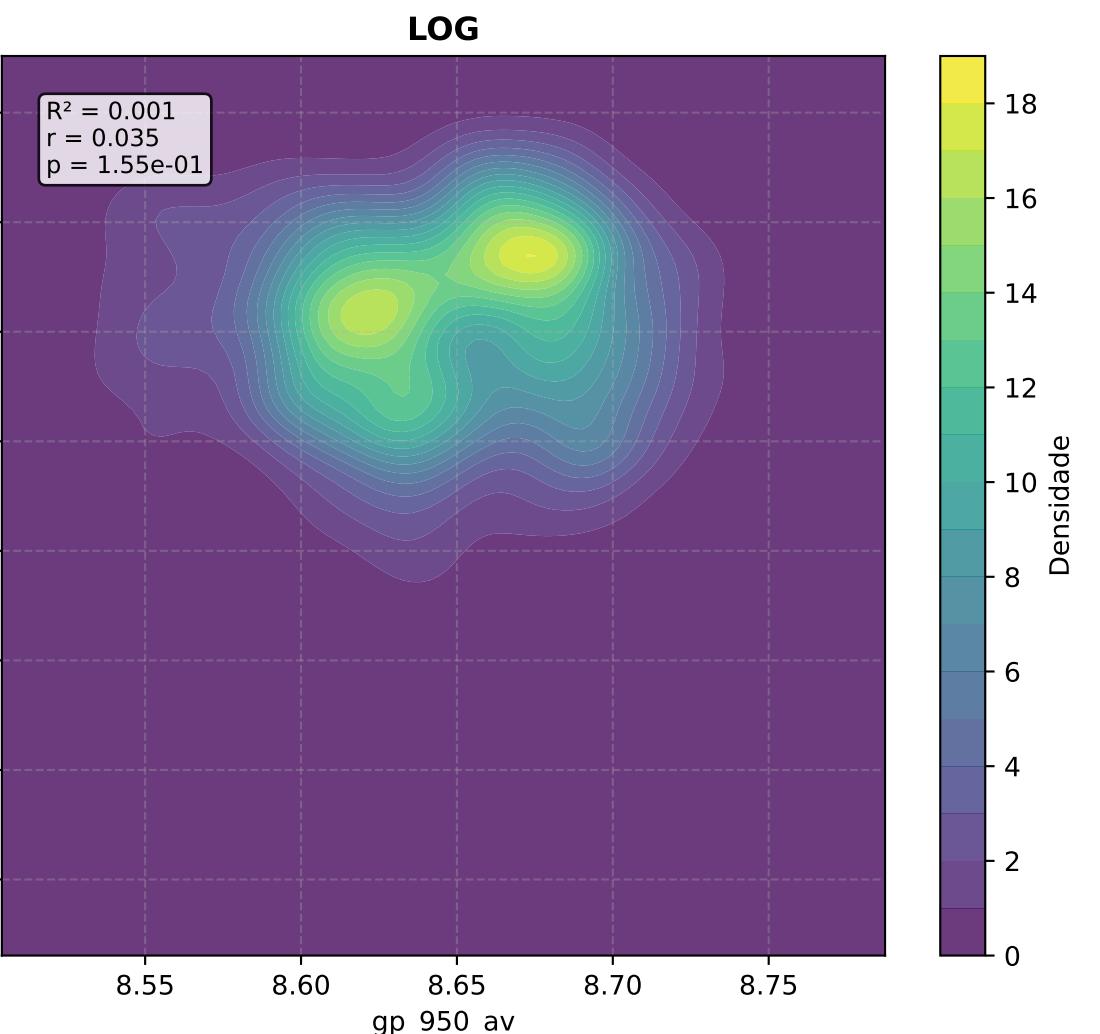
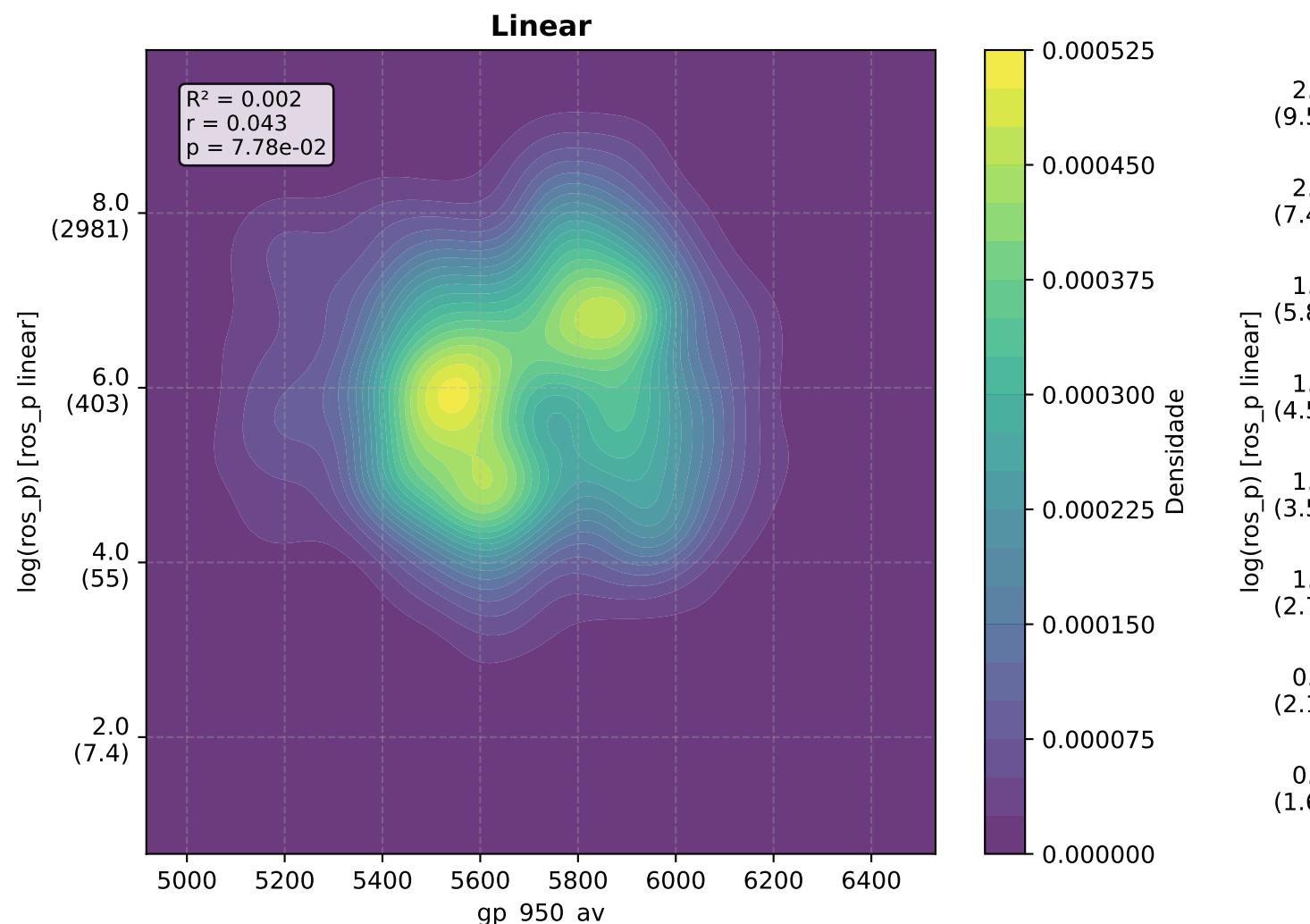
VentIdx_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



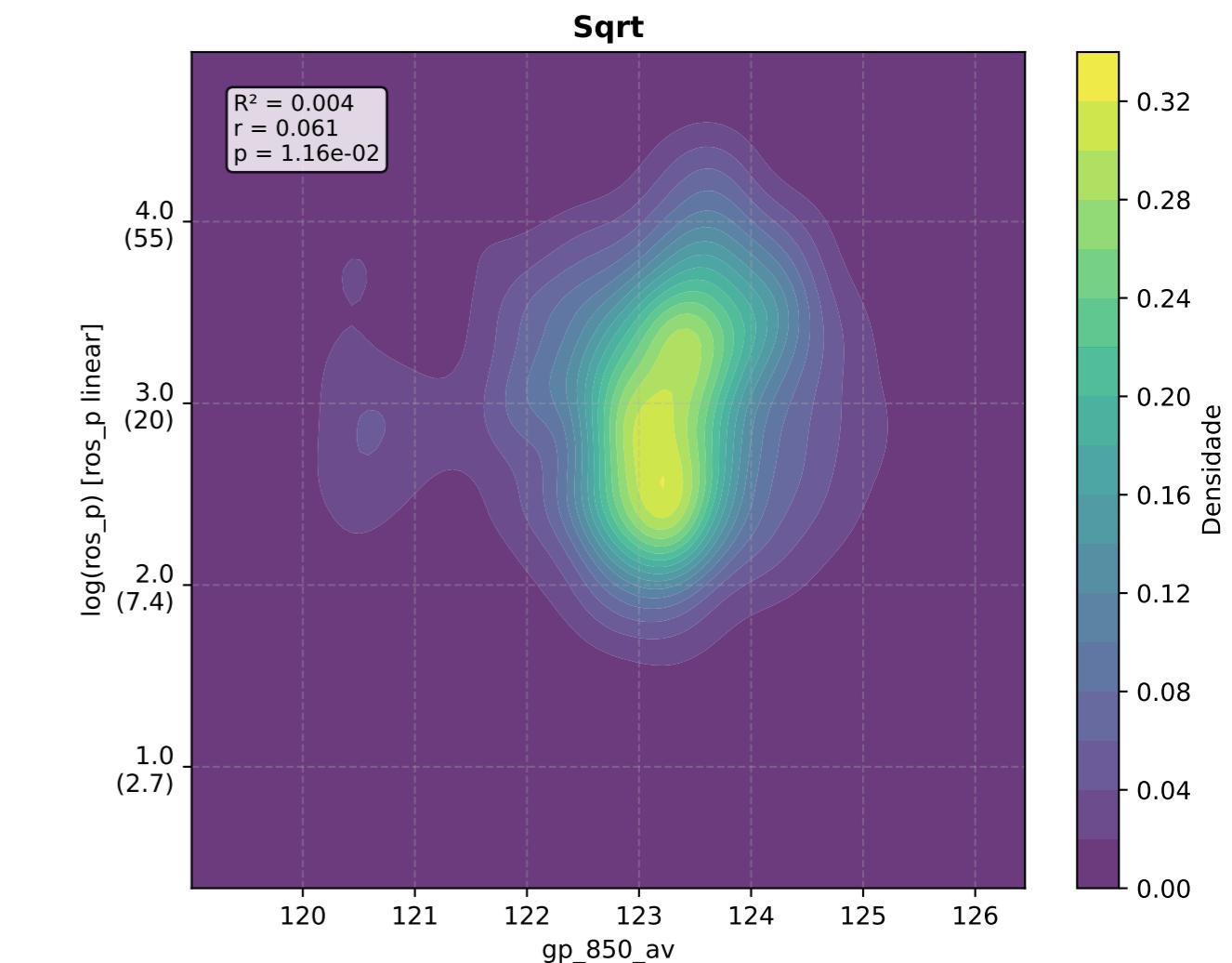
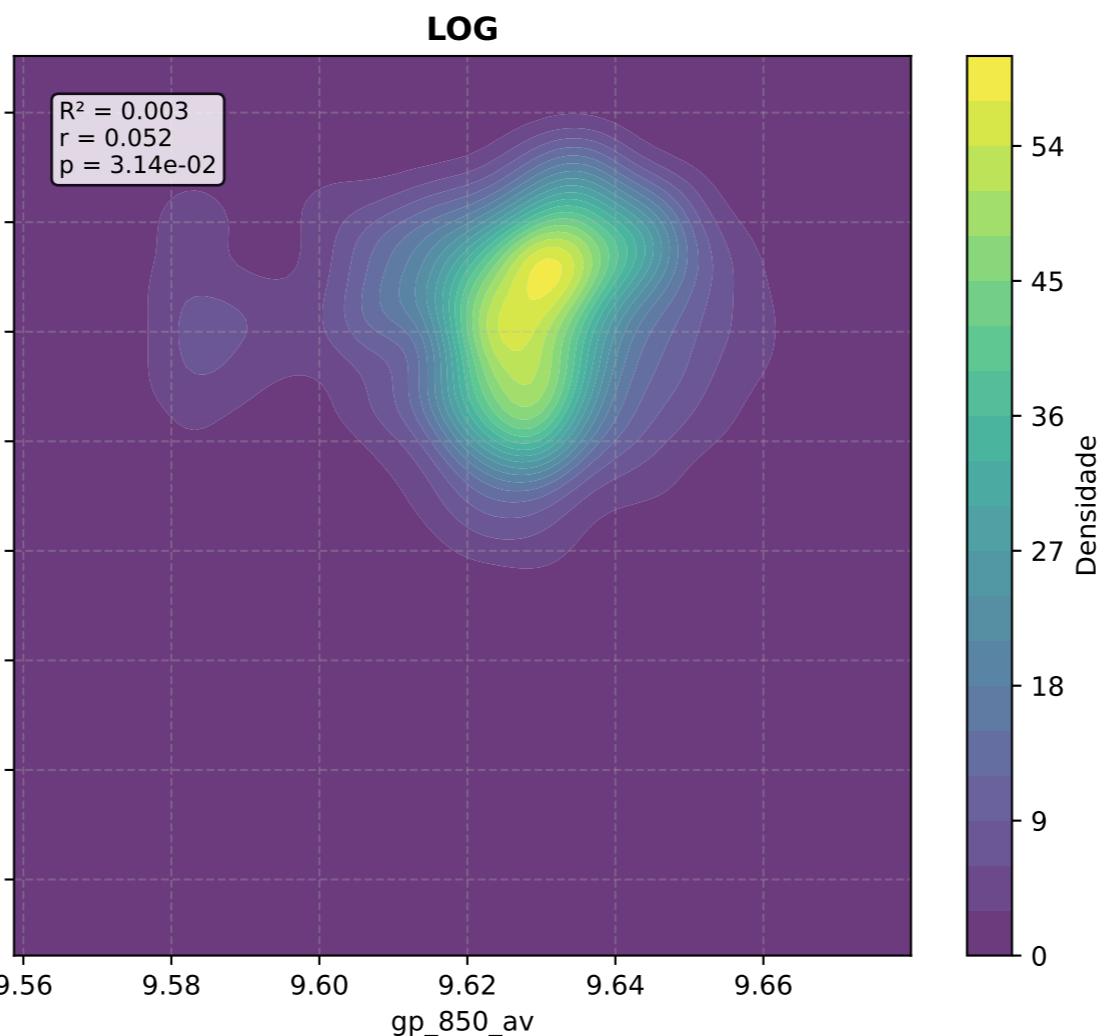
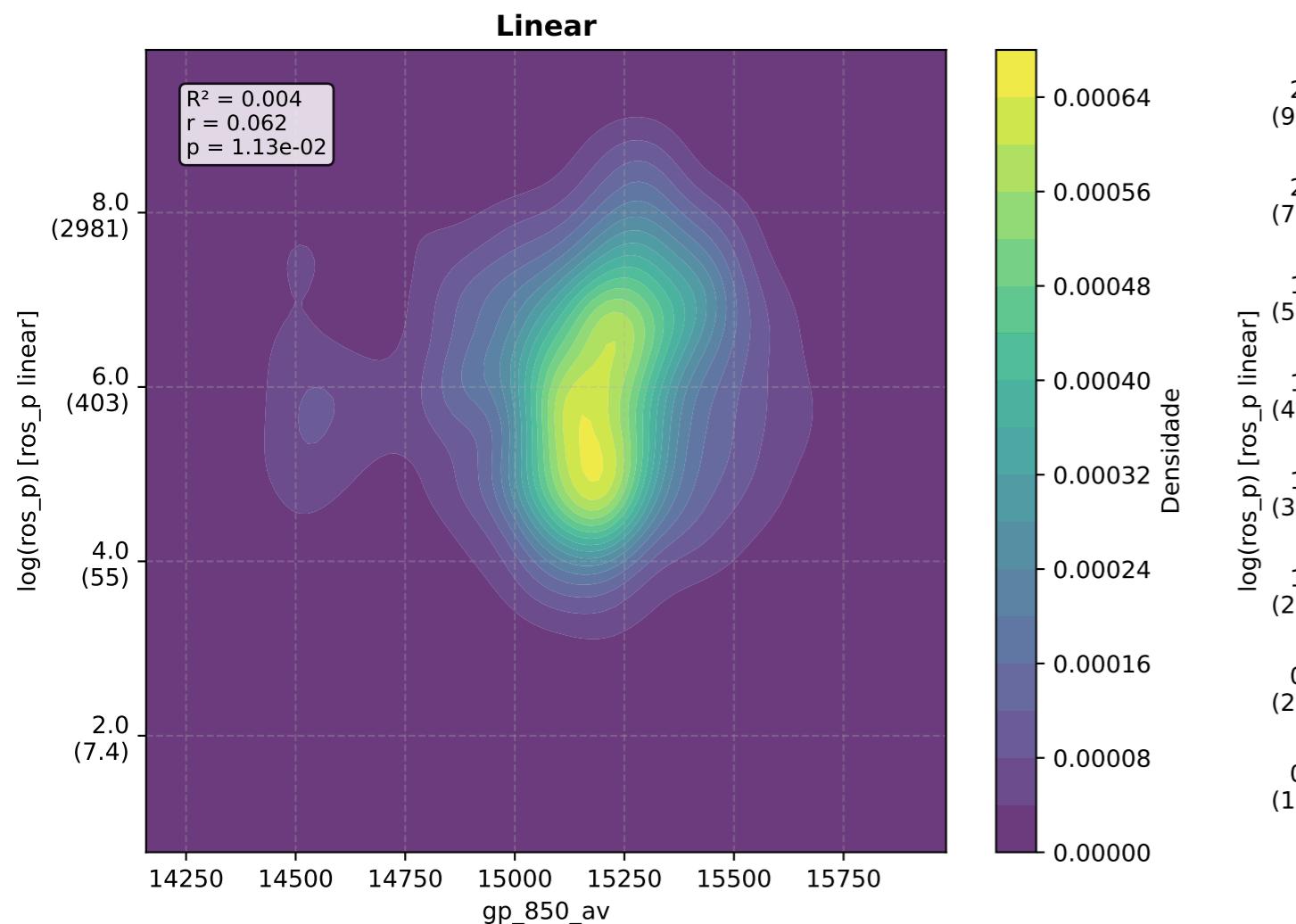
LiftIdx_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



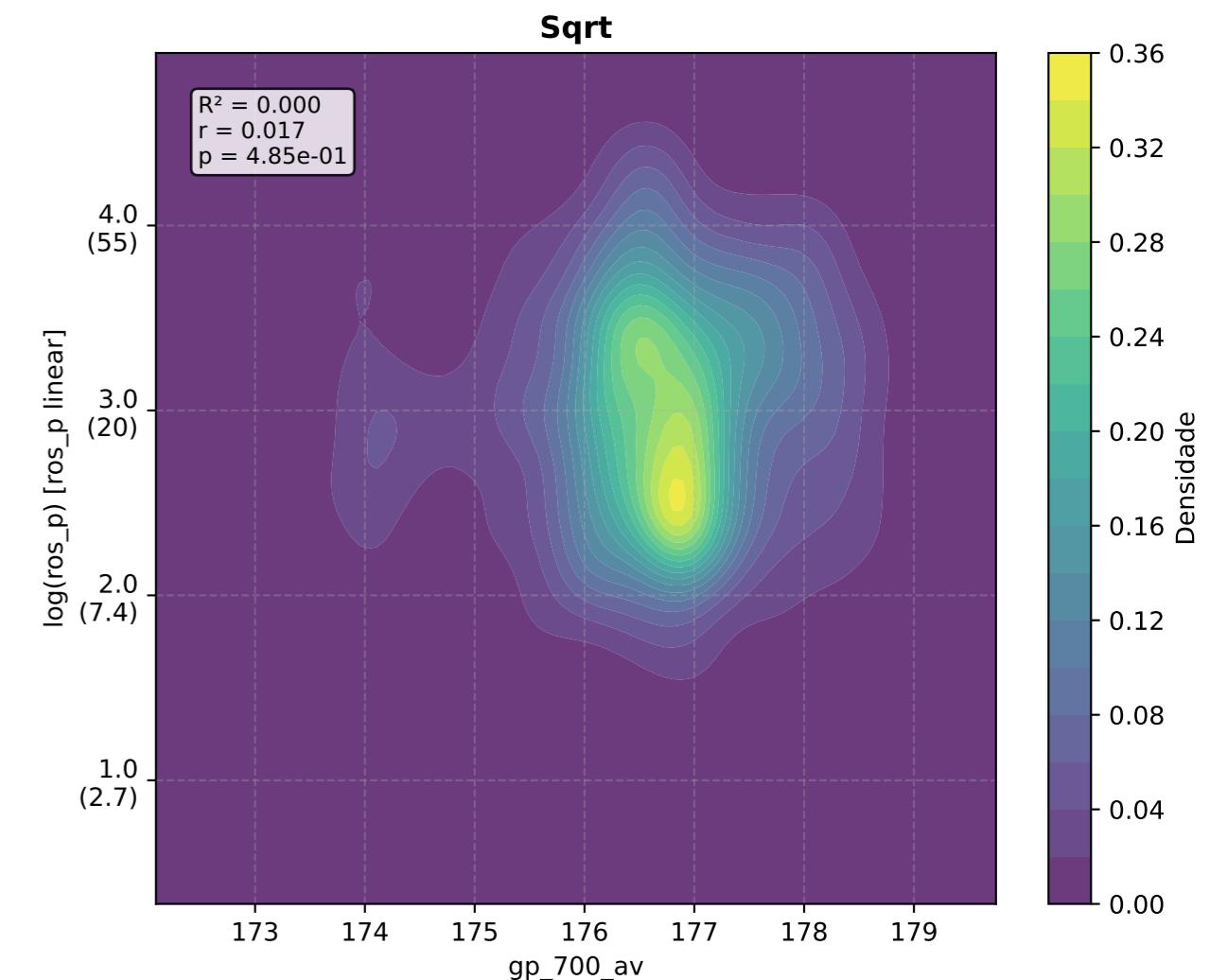
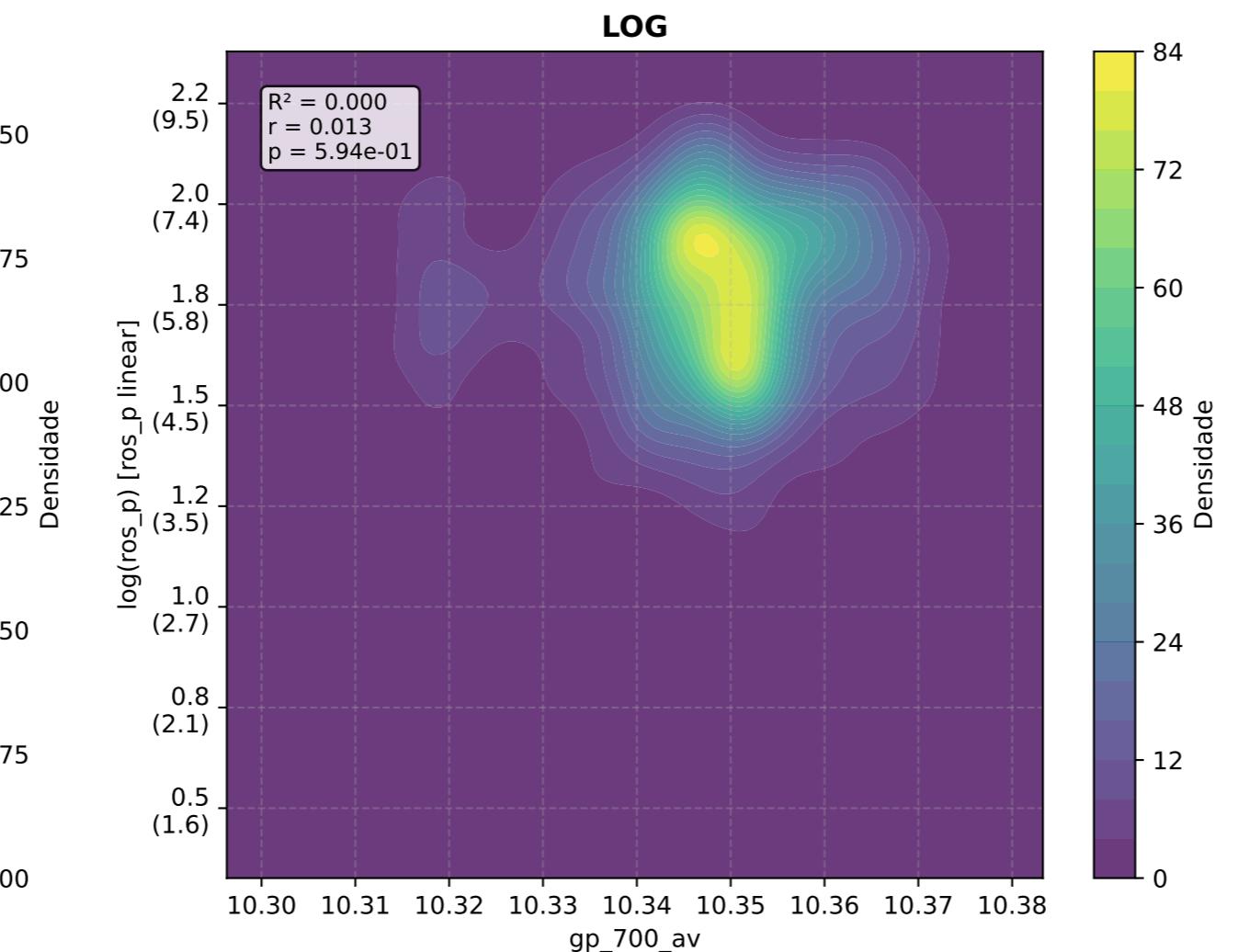
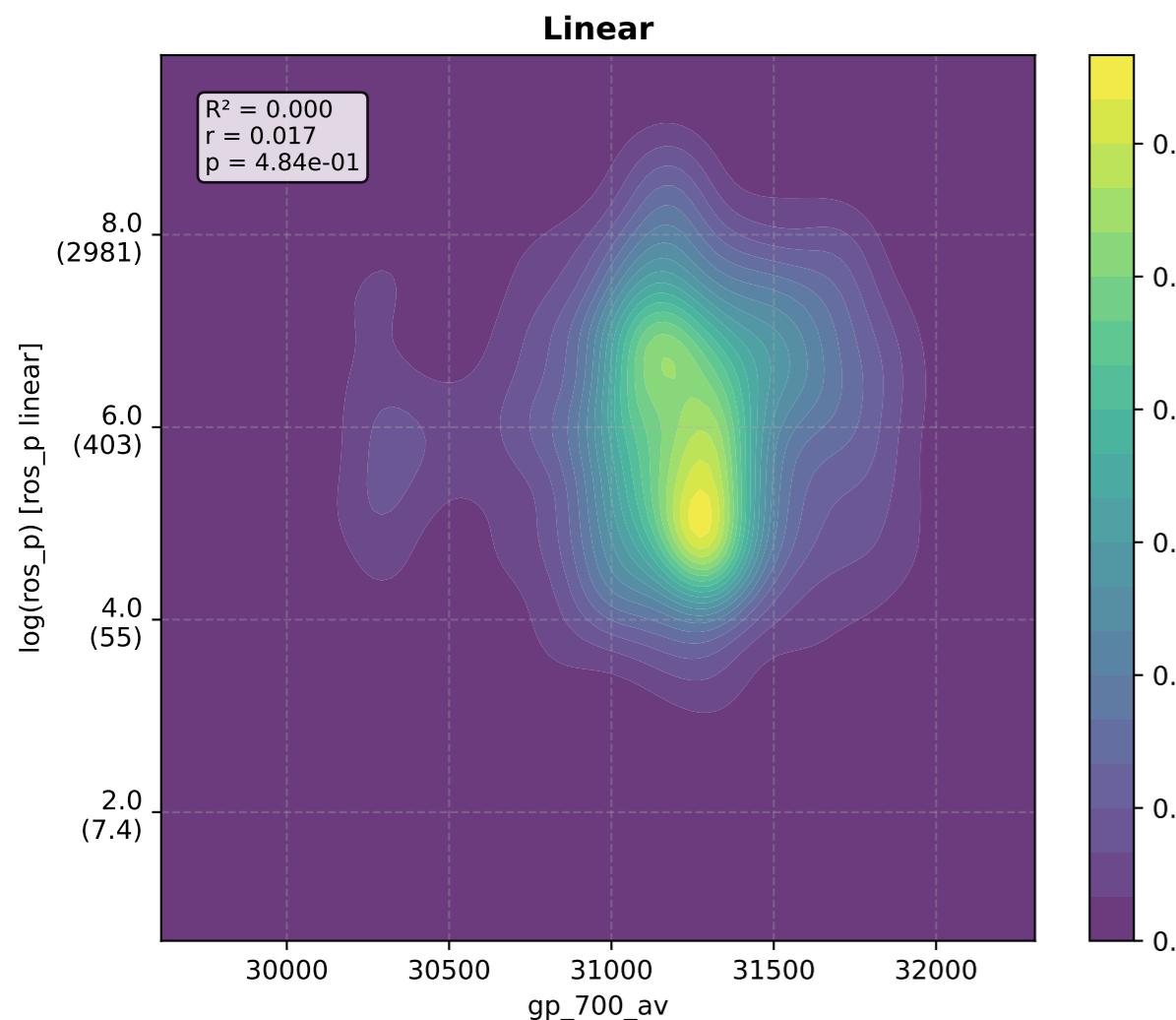
gp_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



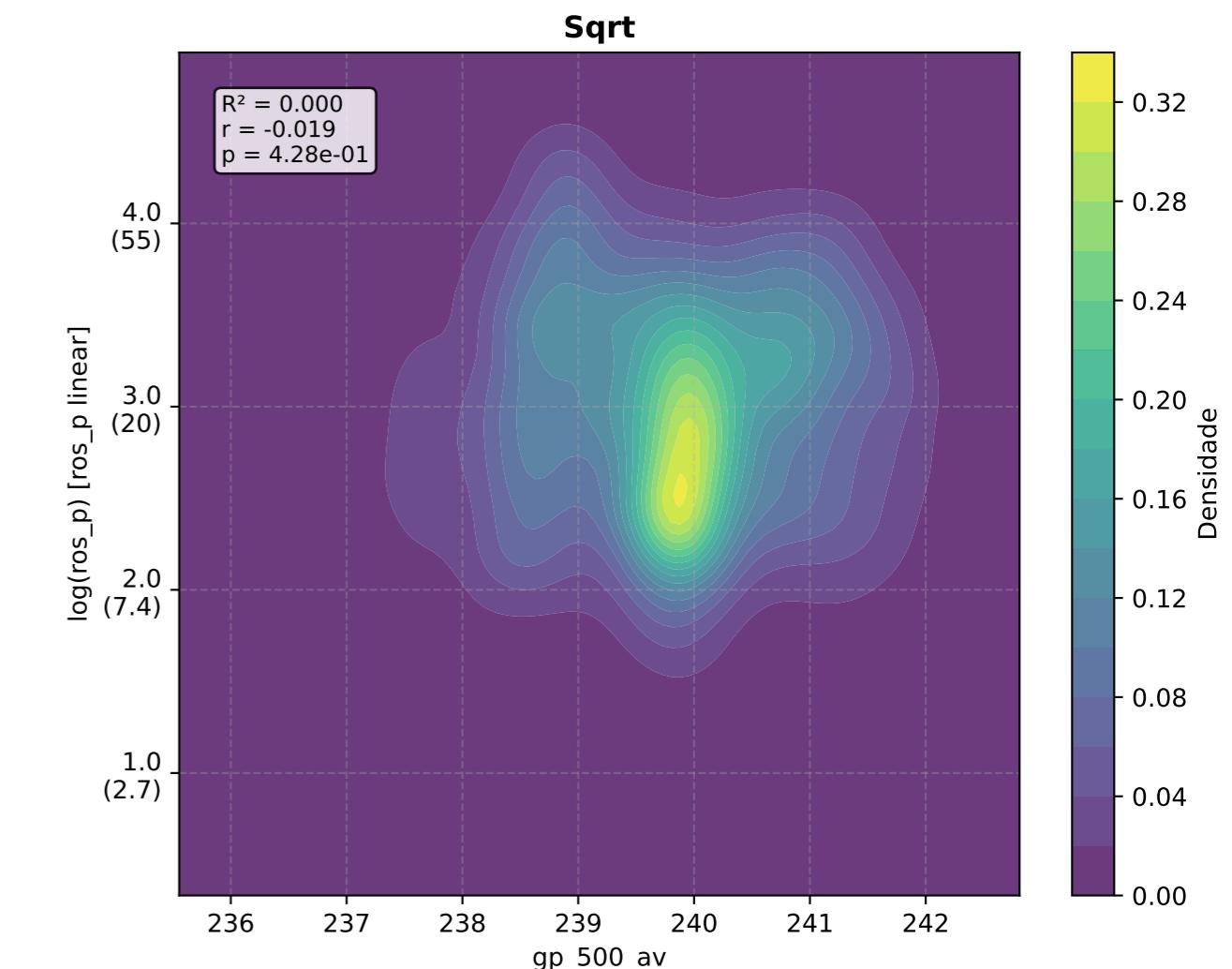
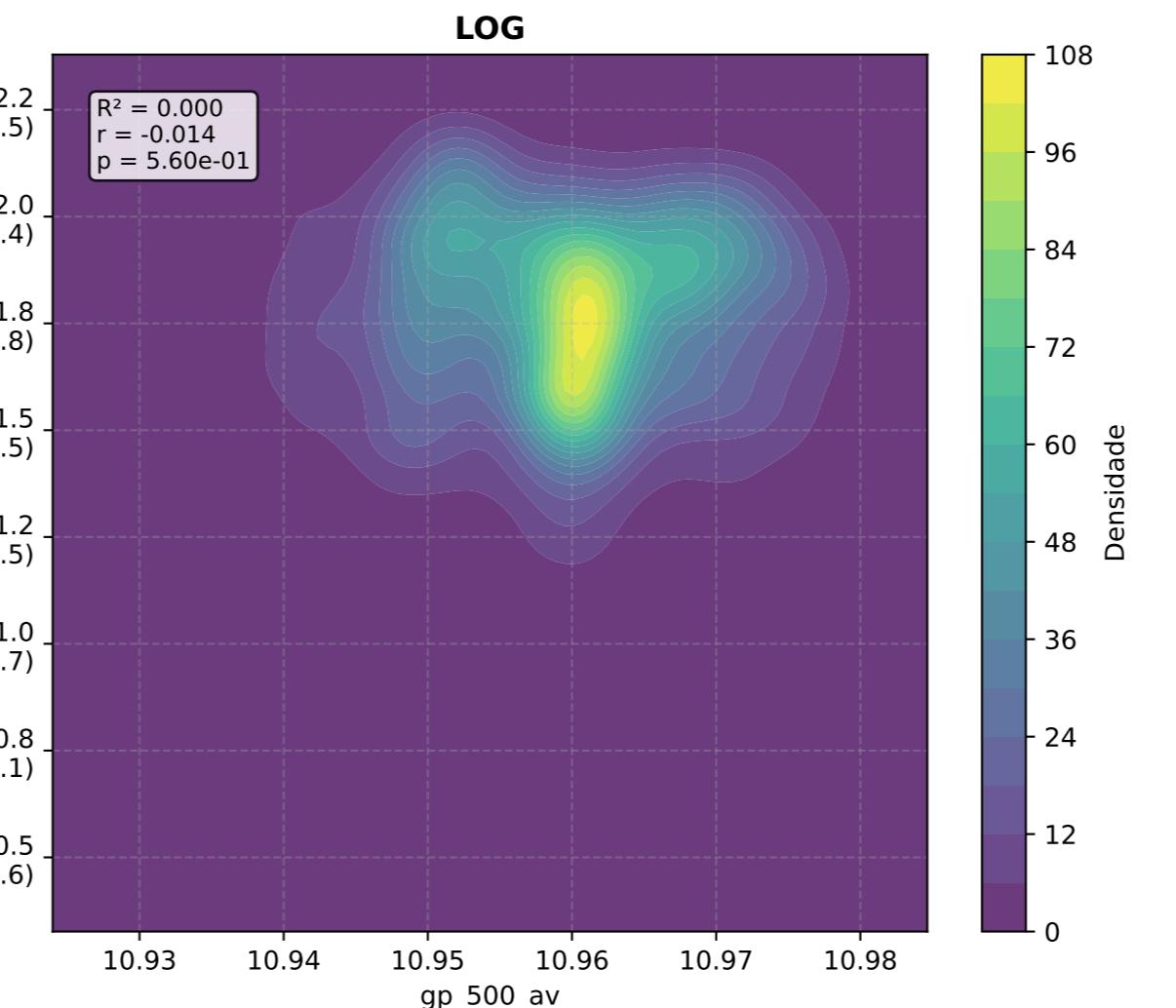
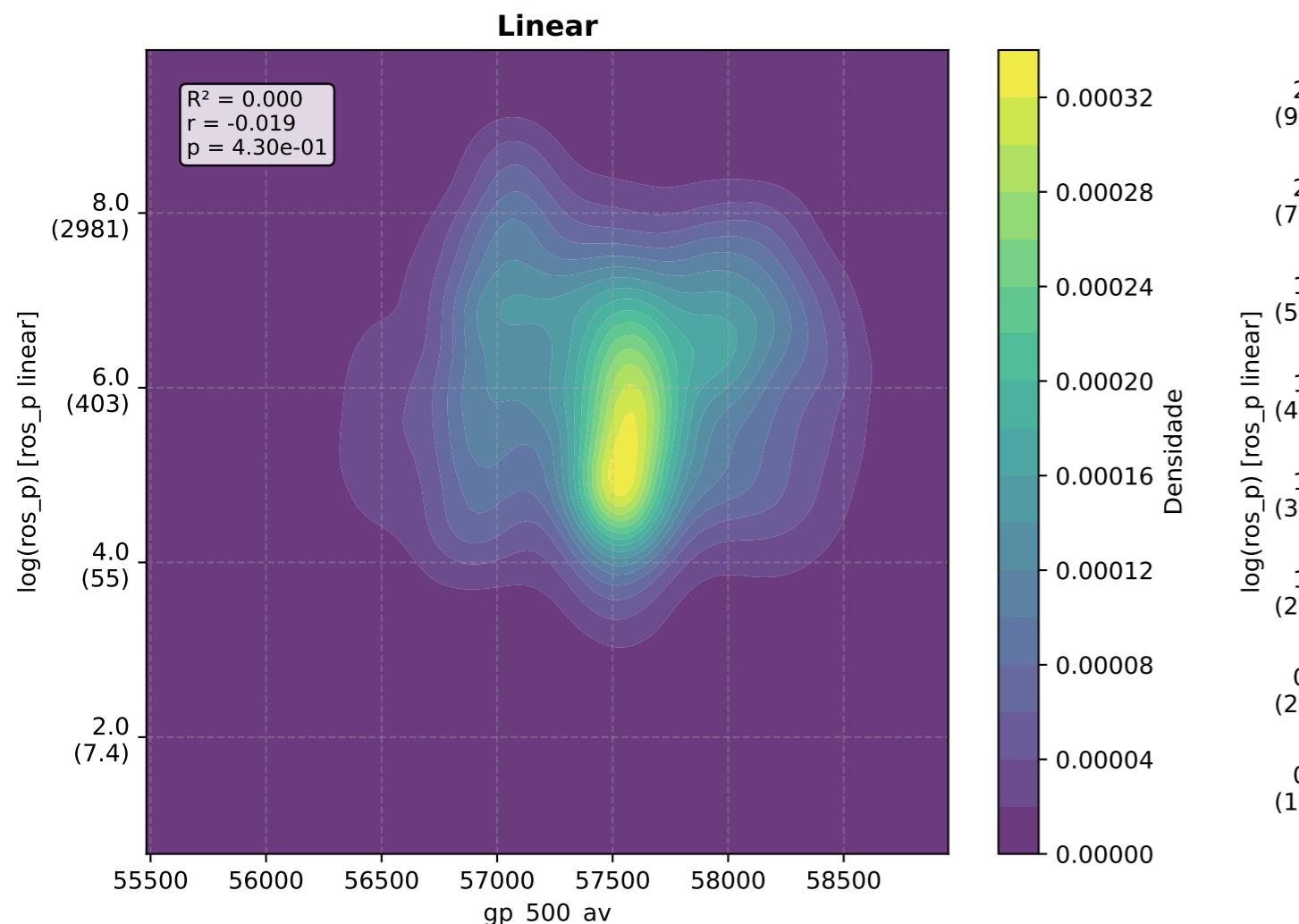
gp_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



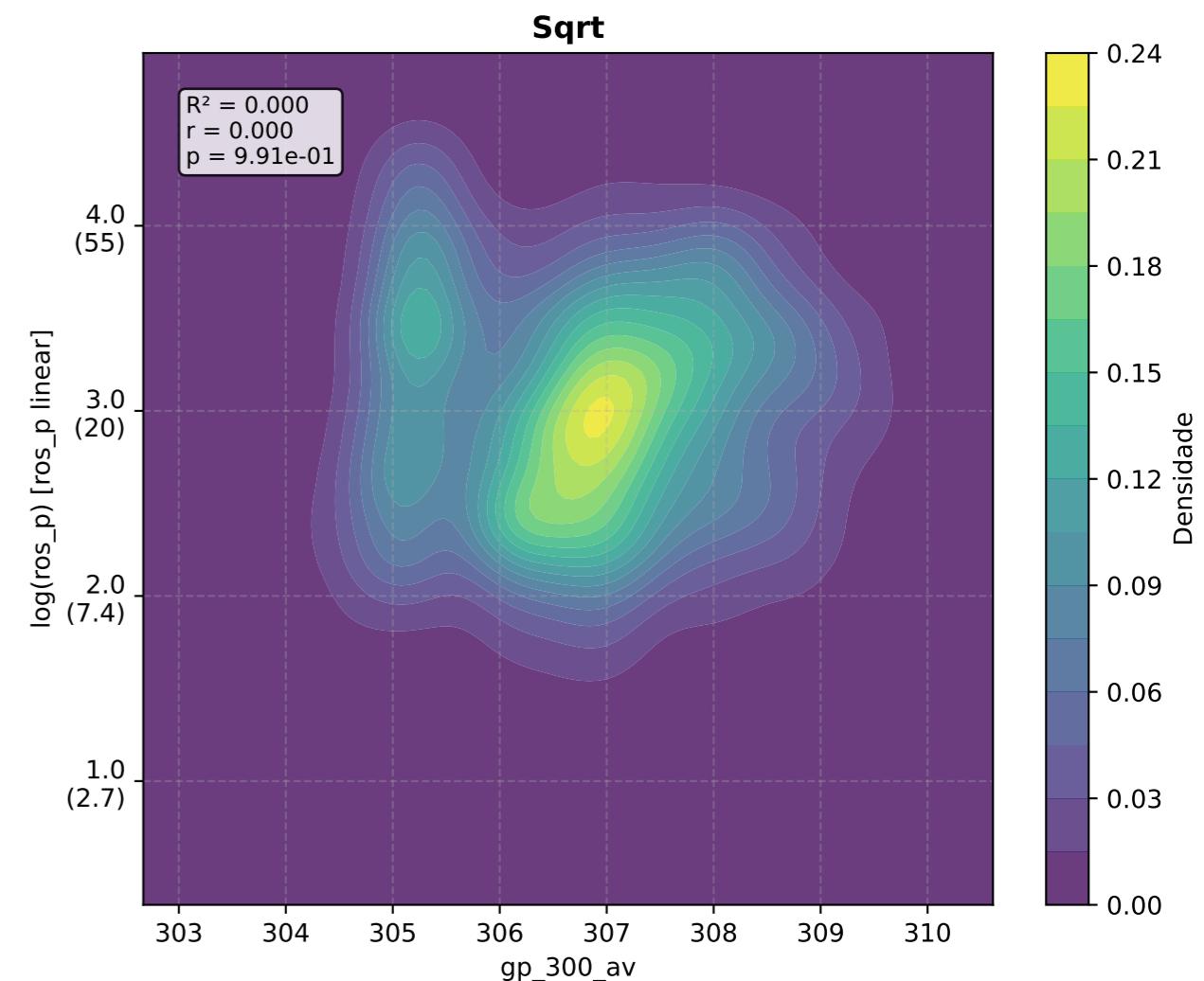
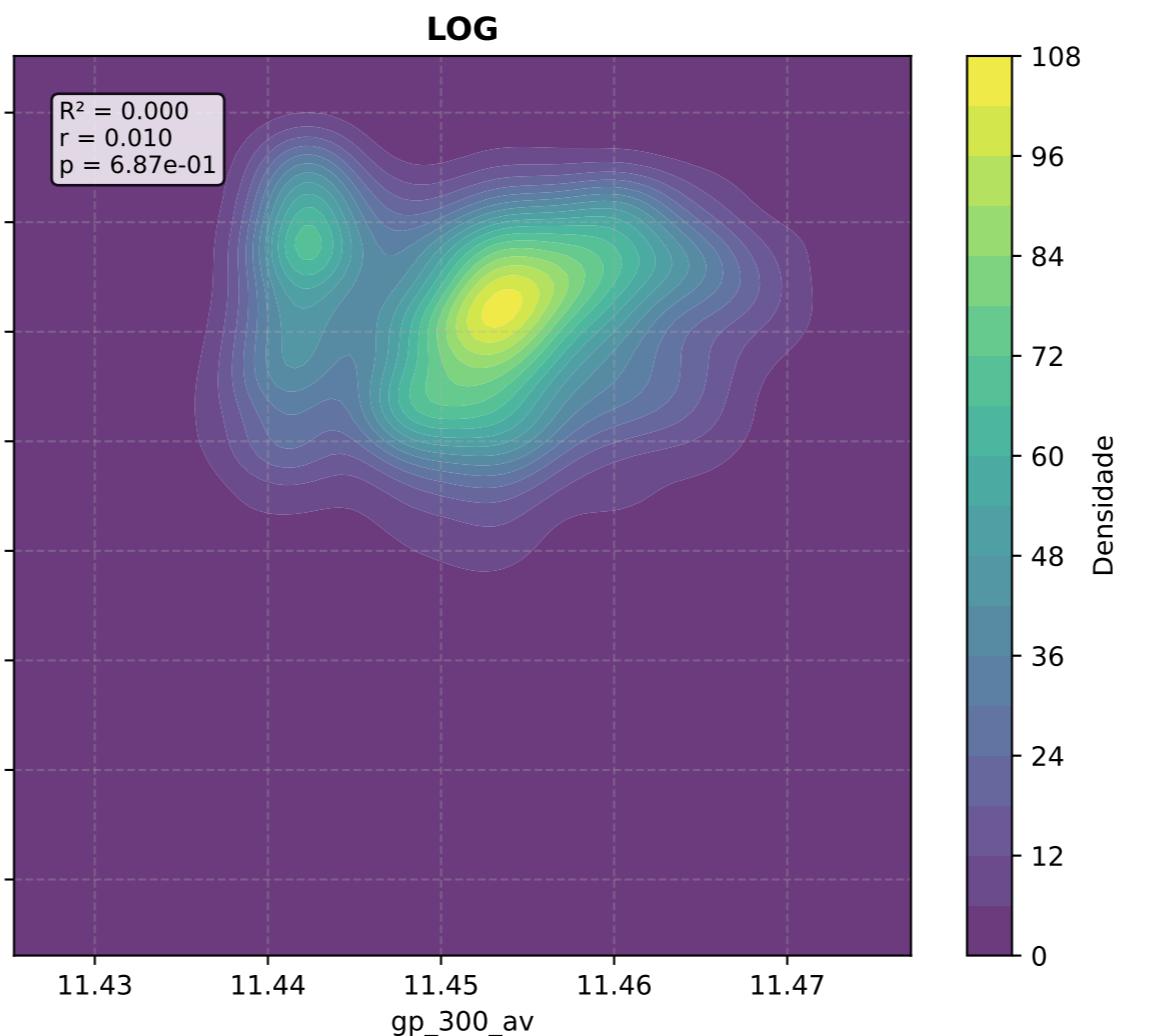
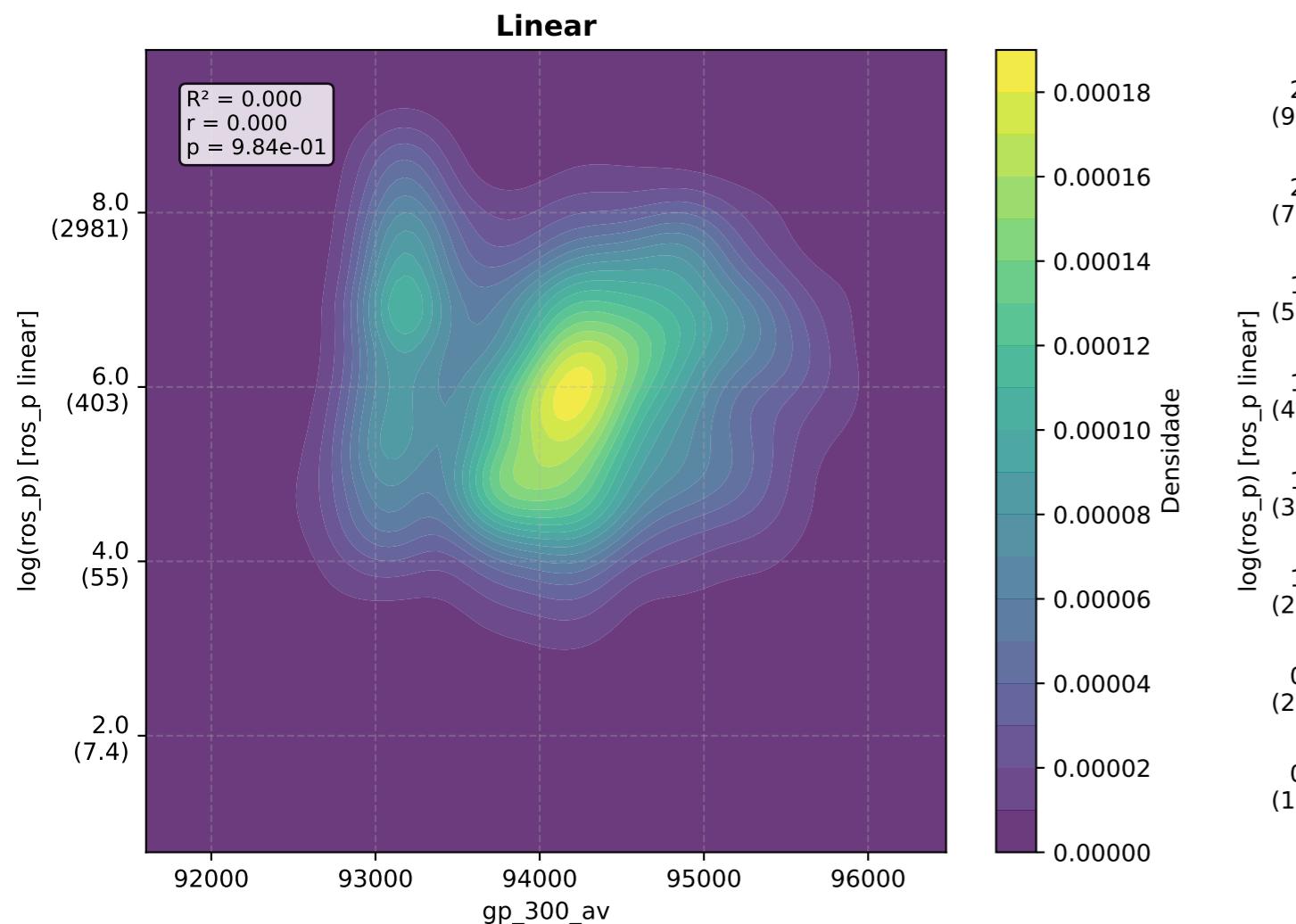
gp_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



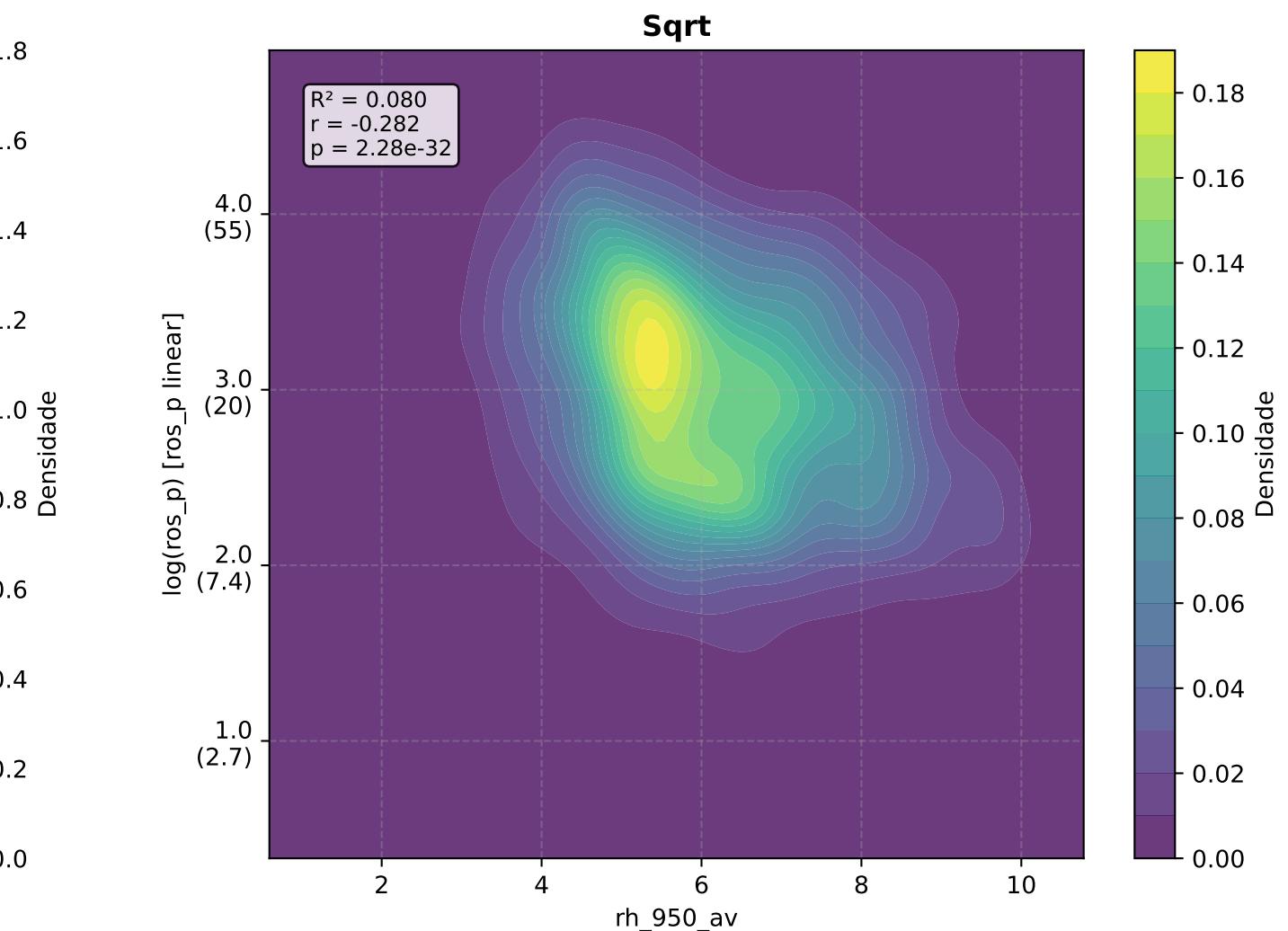
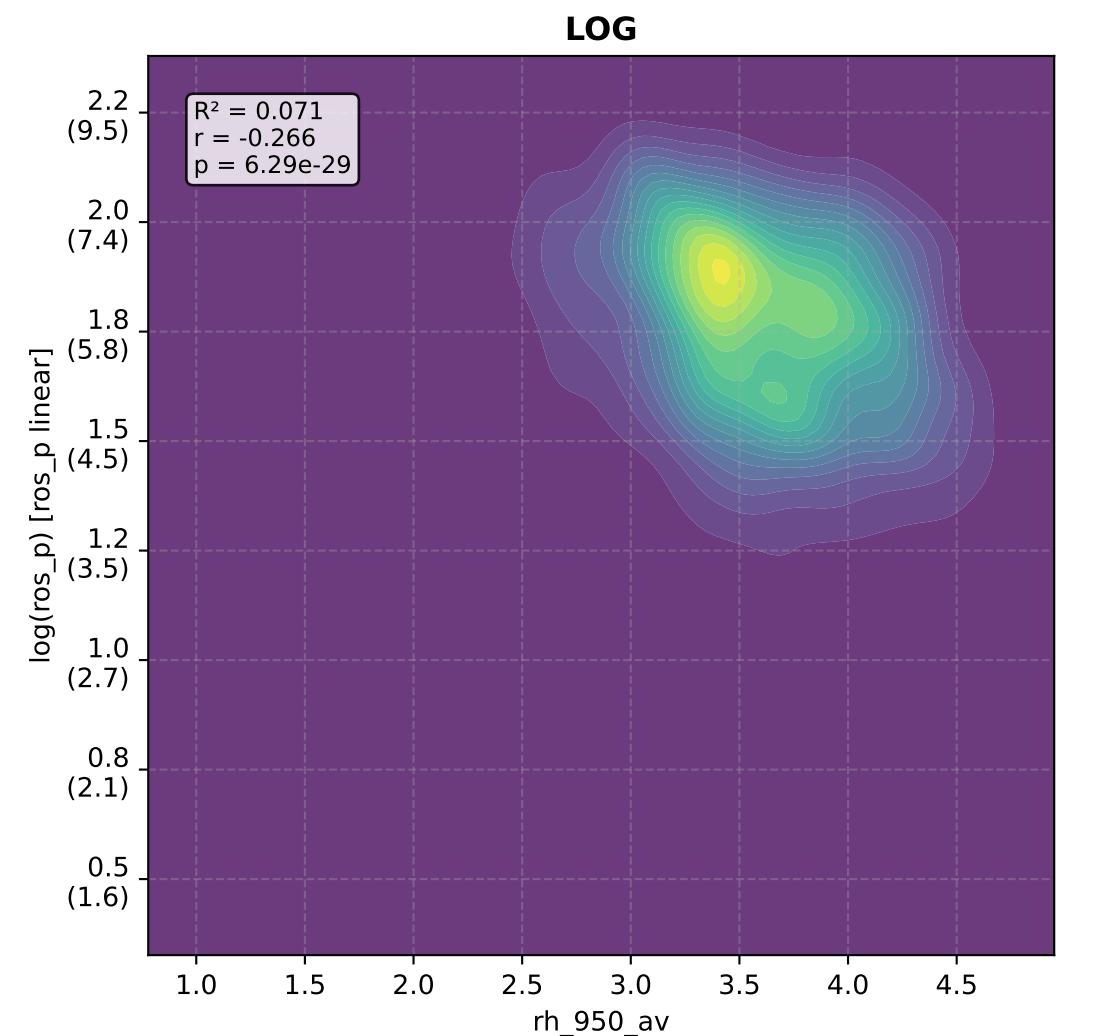
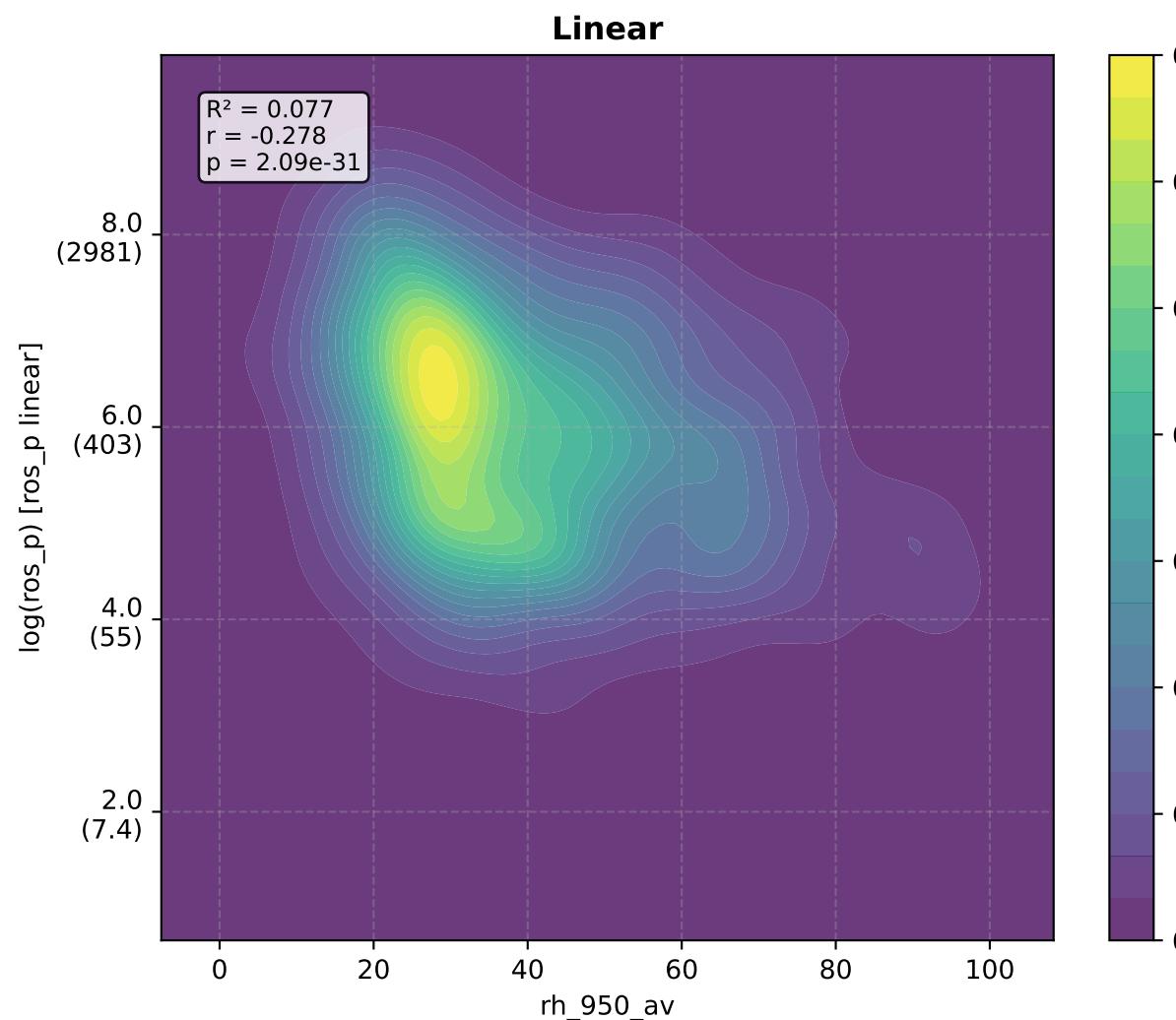
gp_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



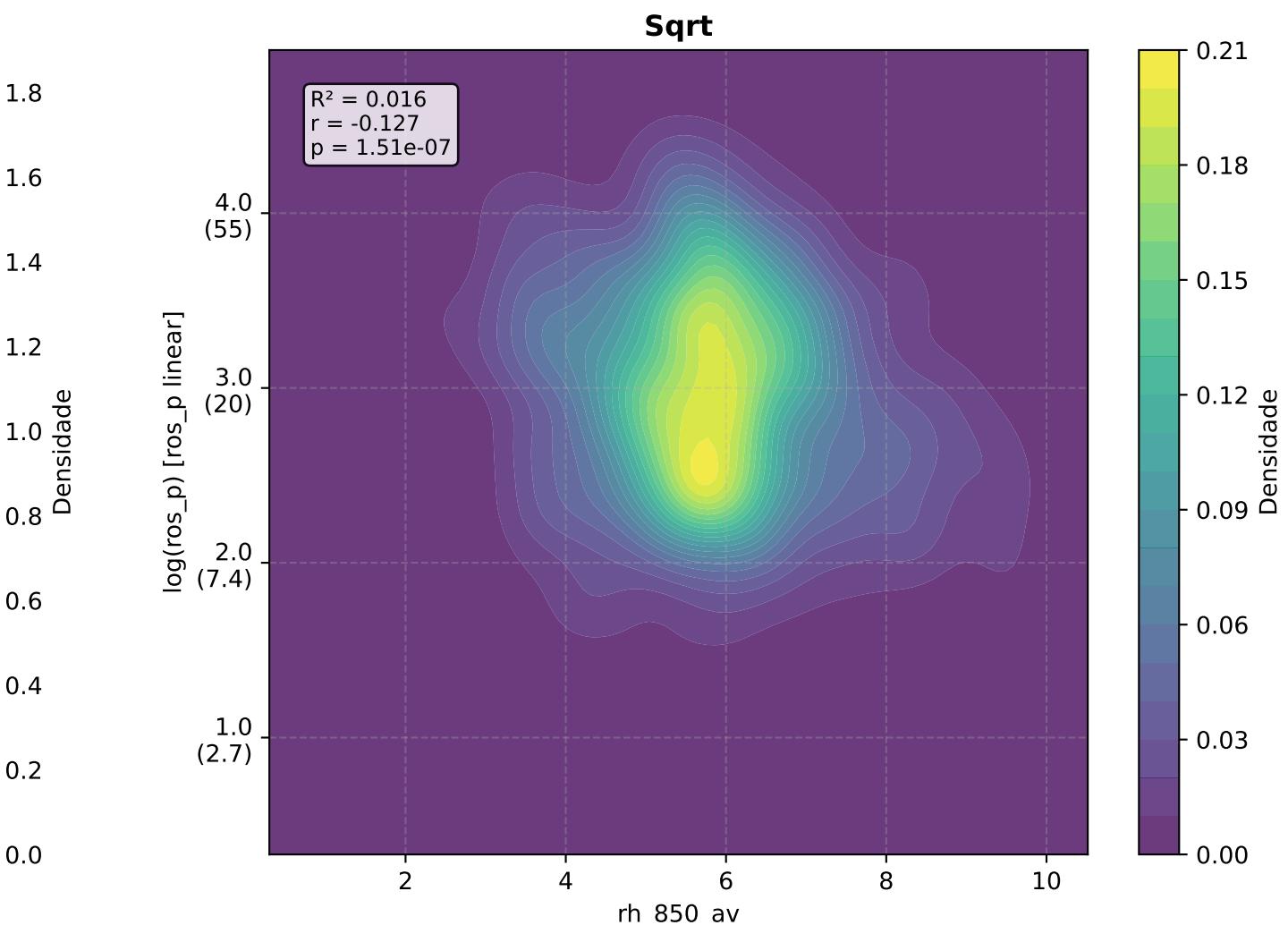
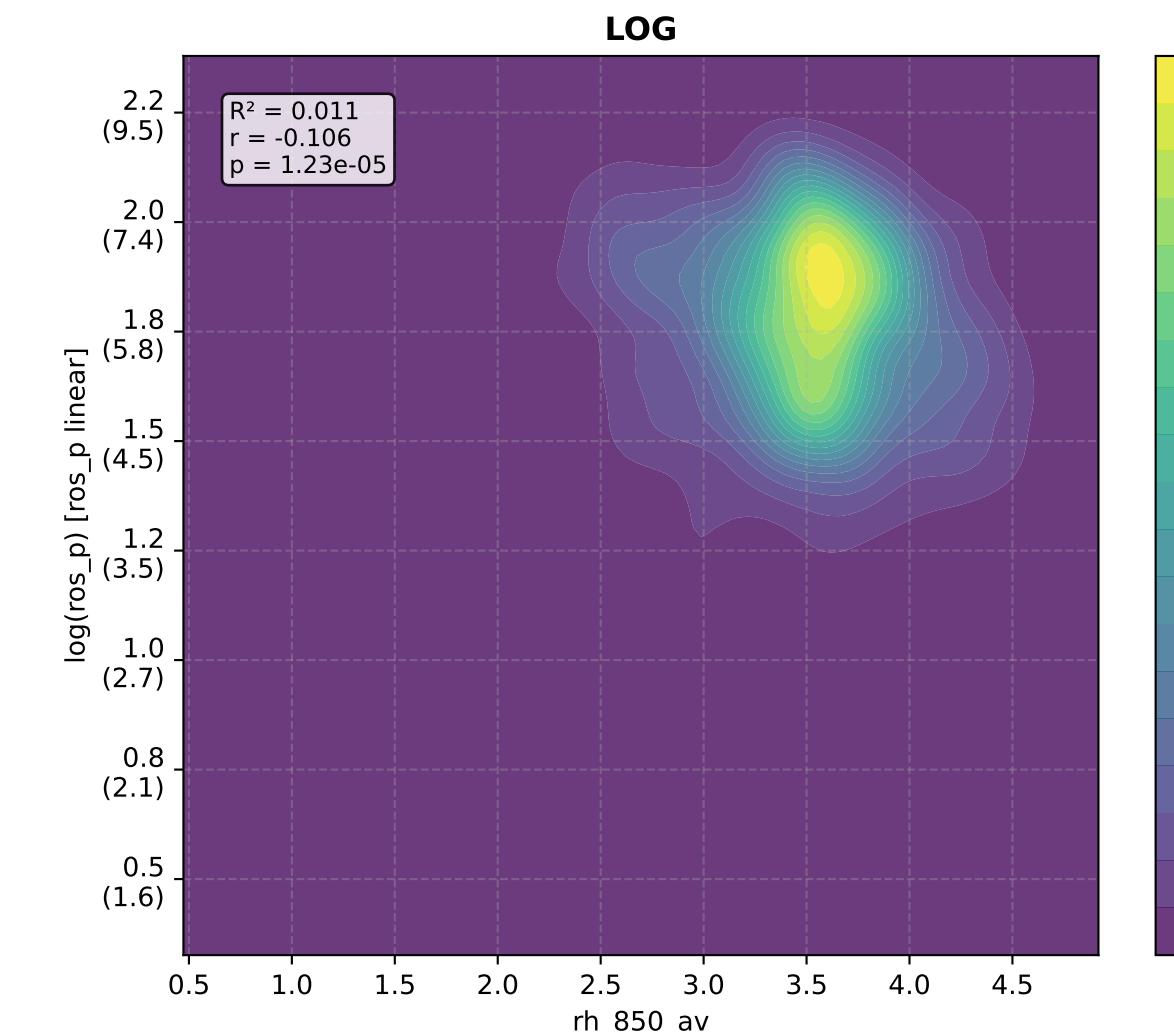
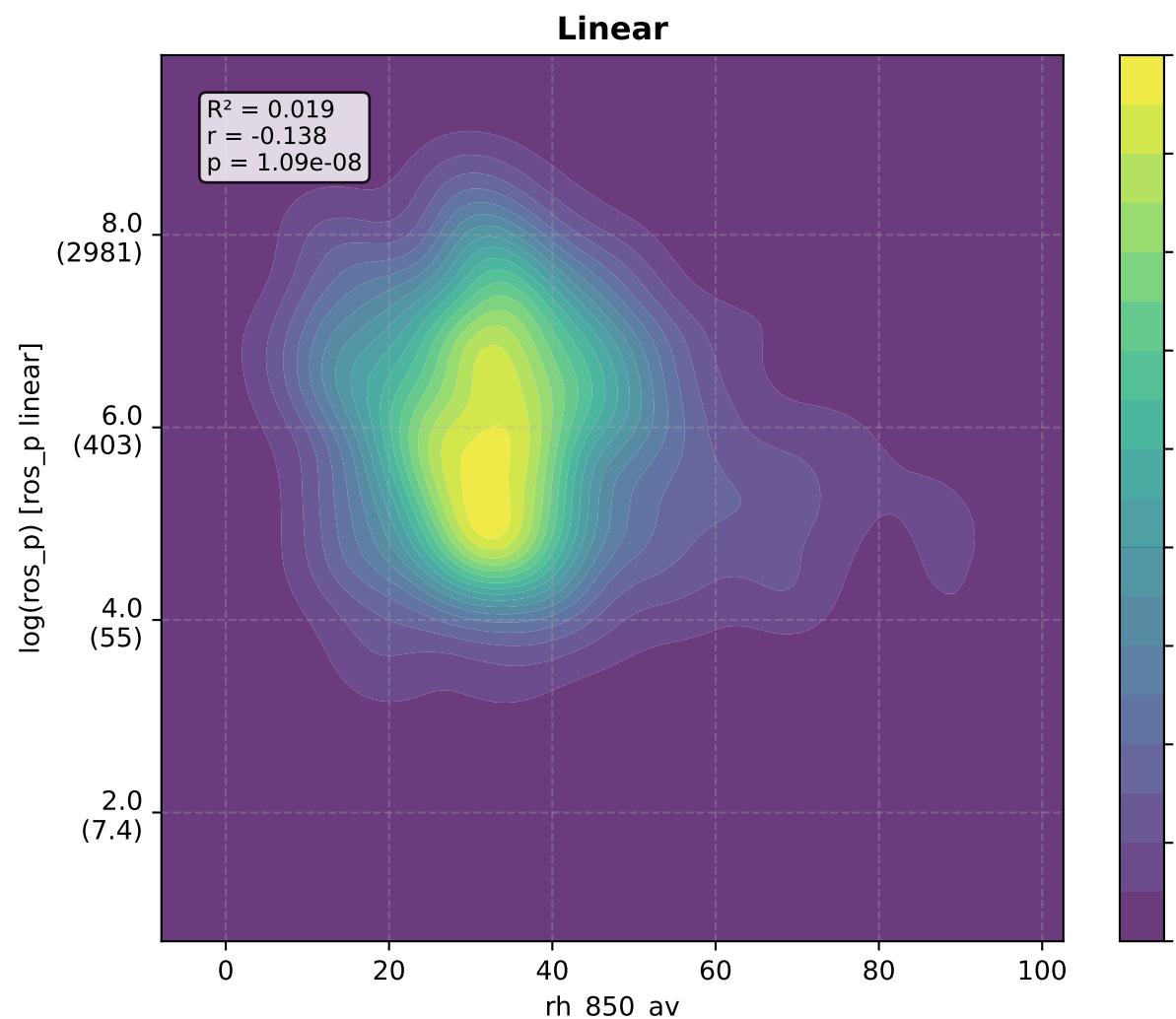
gp_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



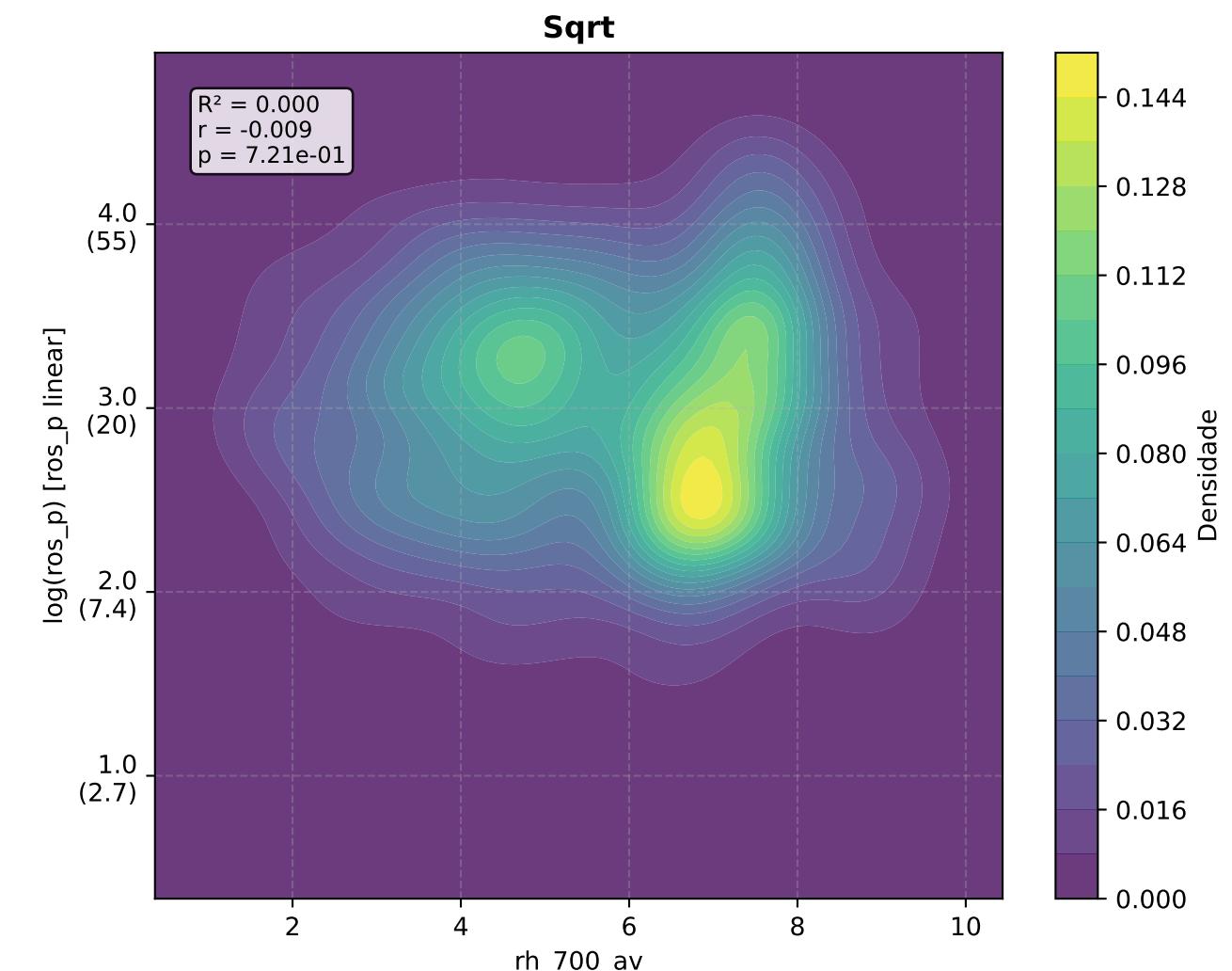
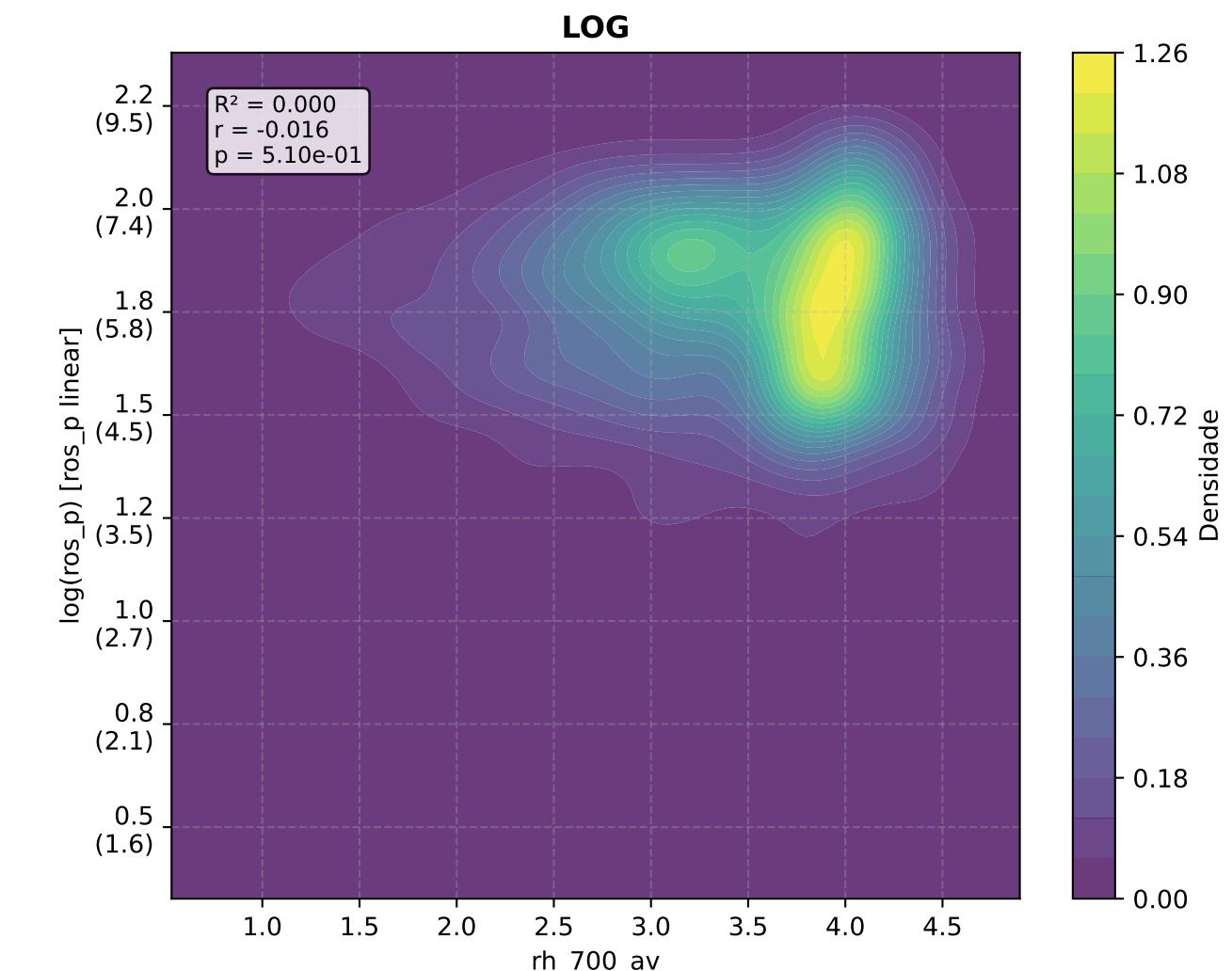
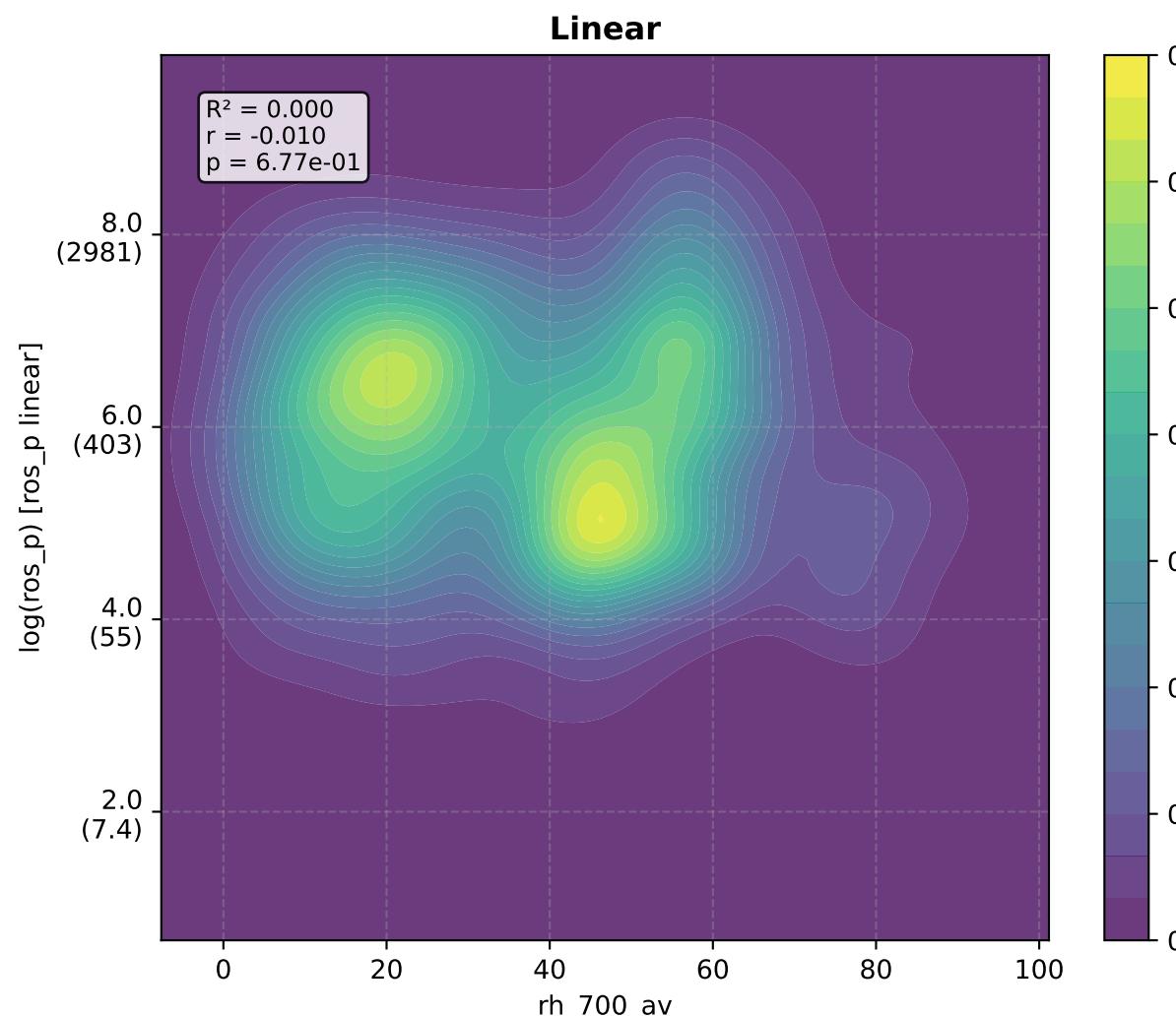
rh_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



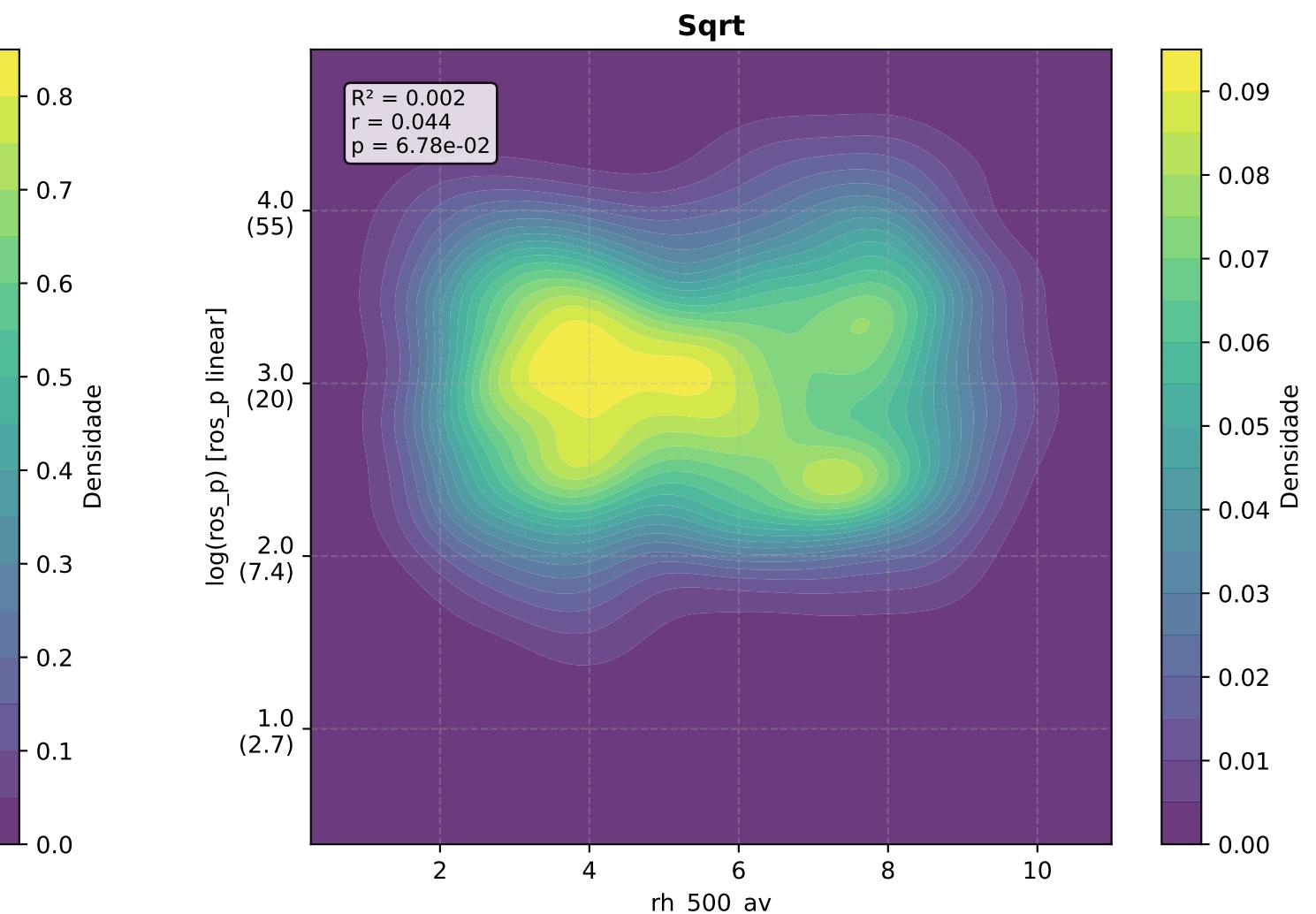
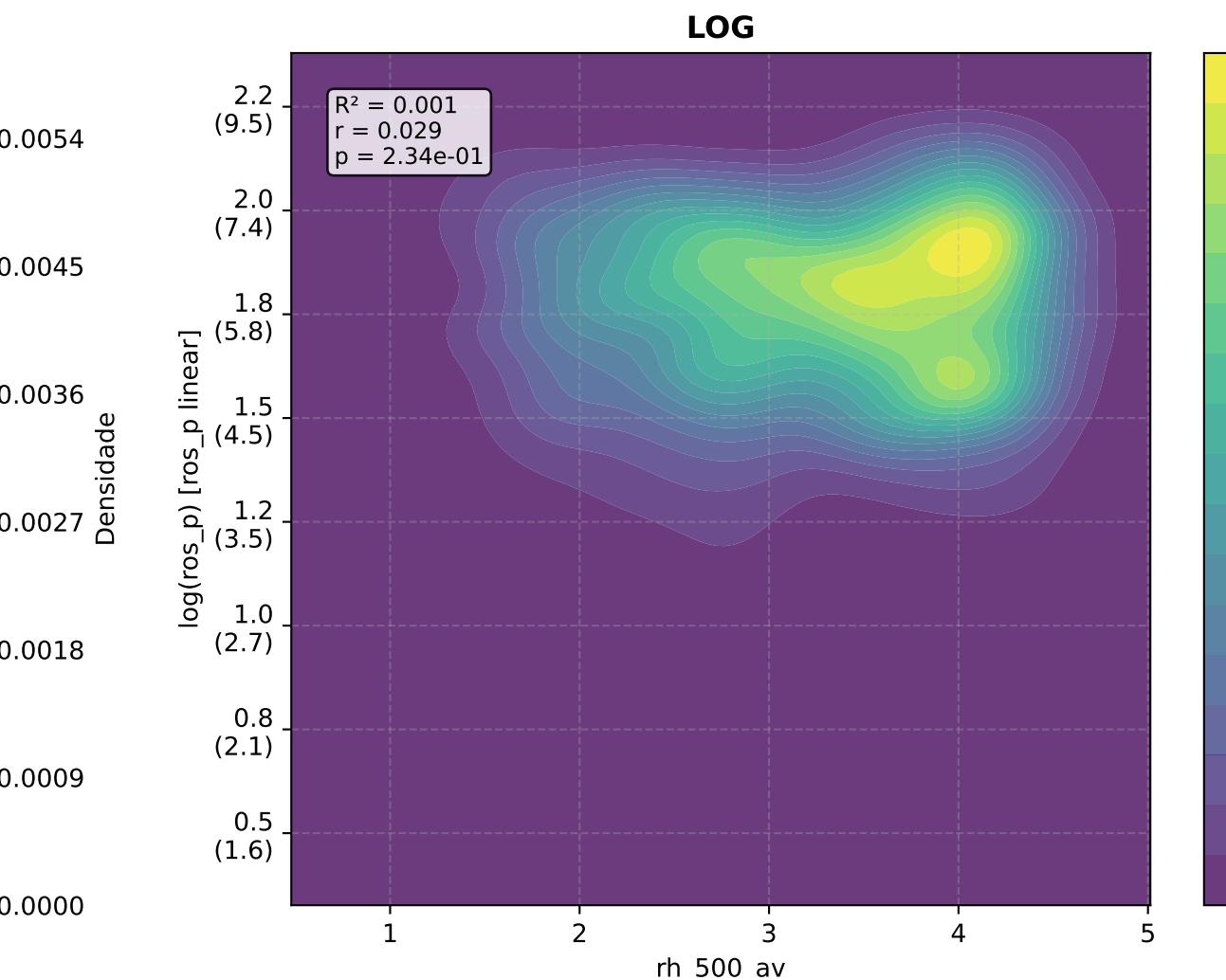
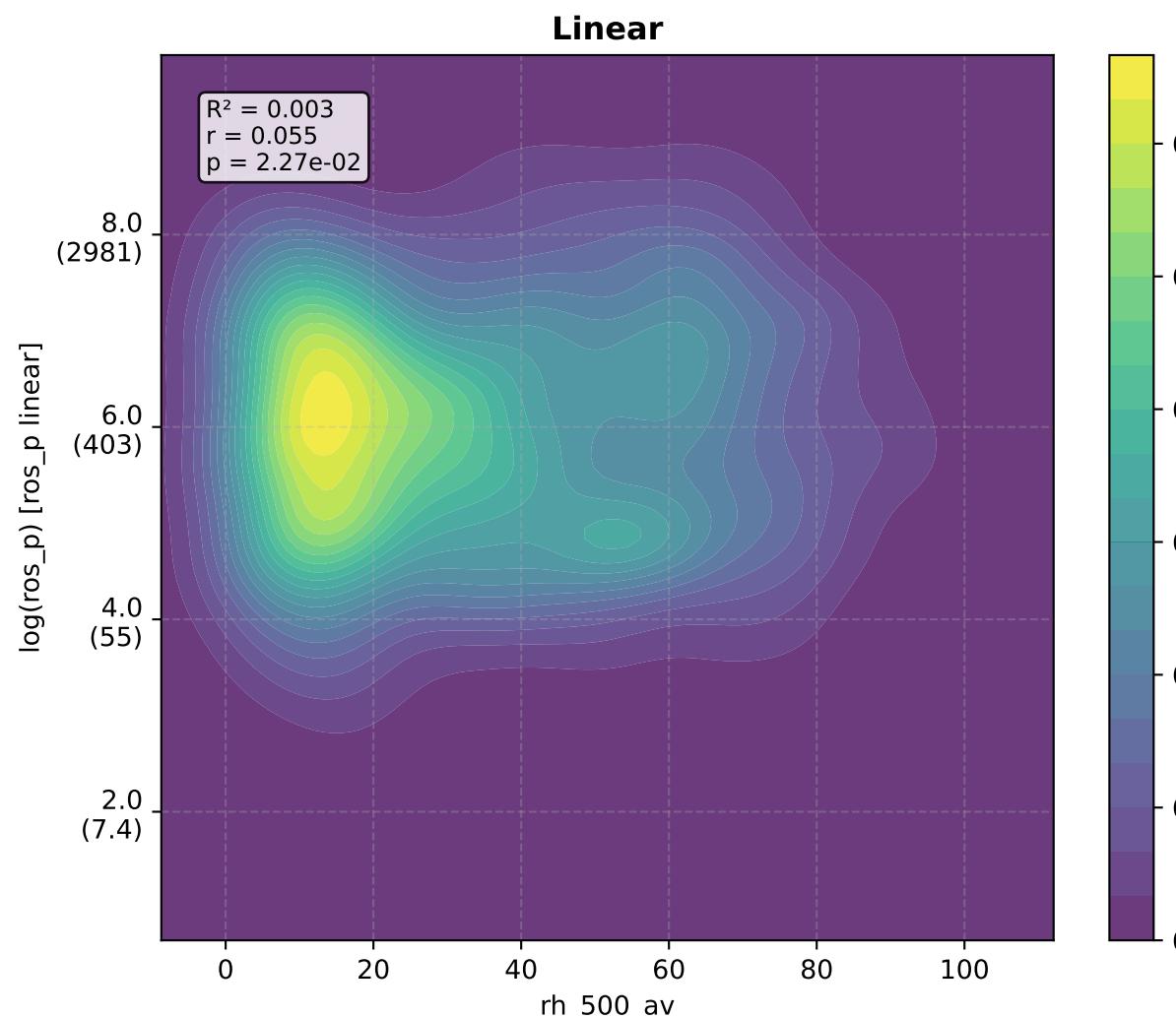
rh_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



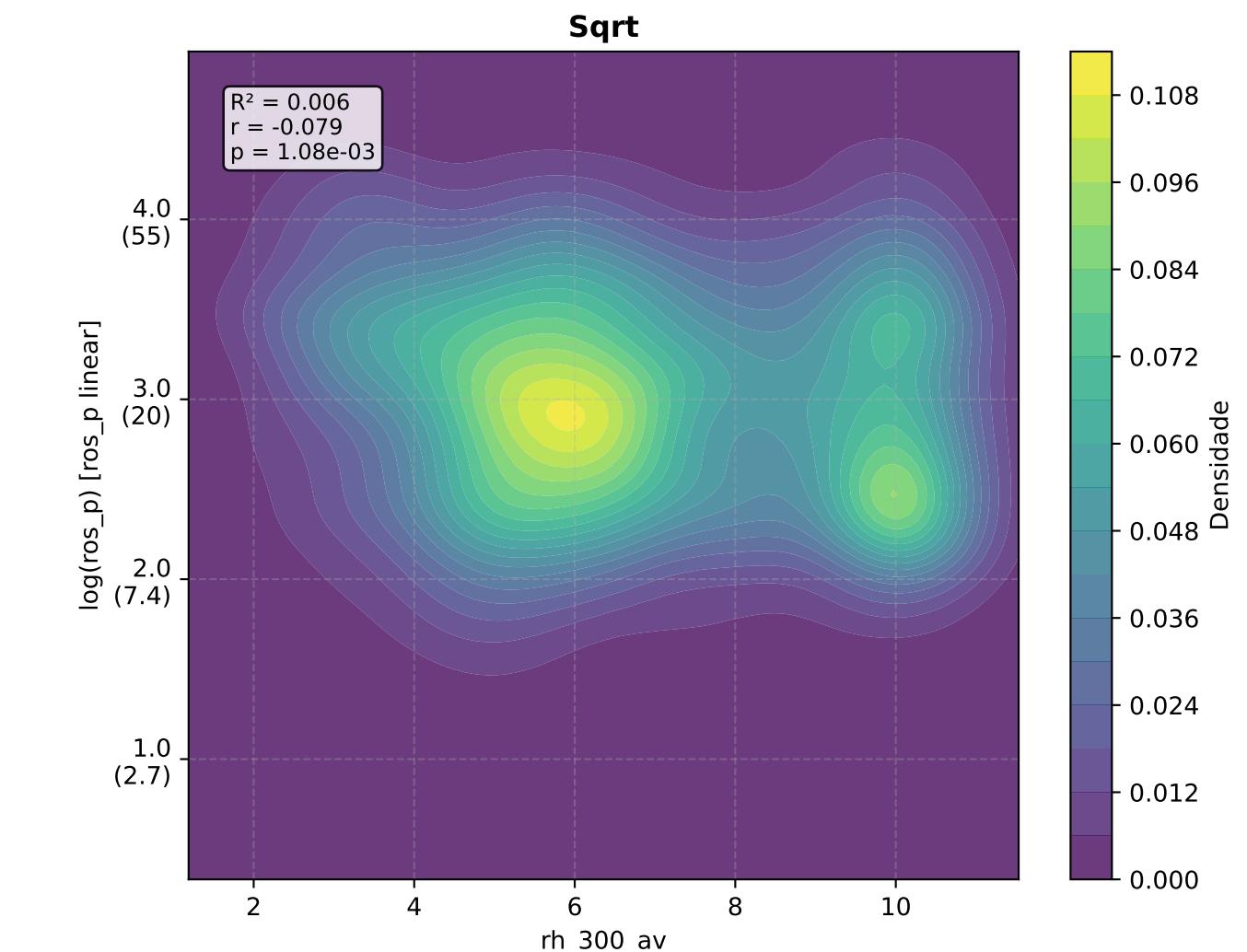
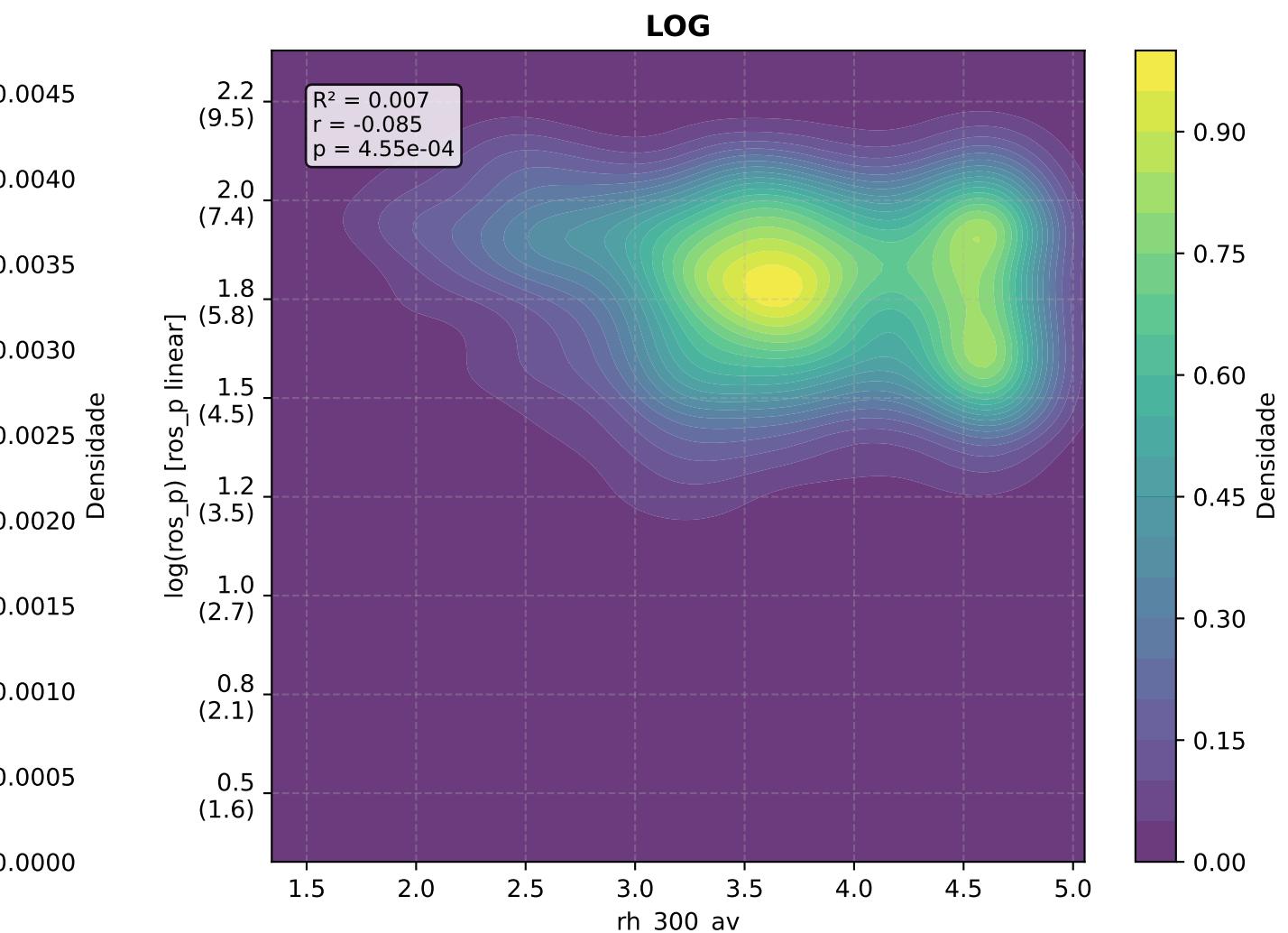
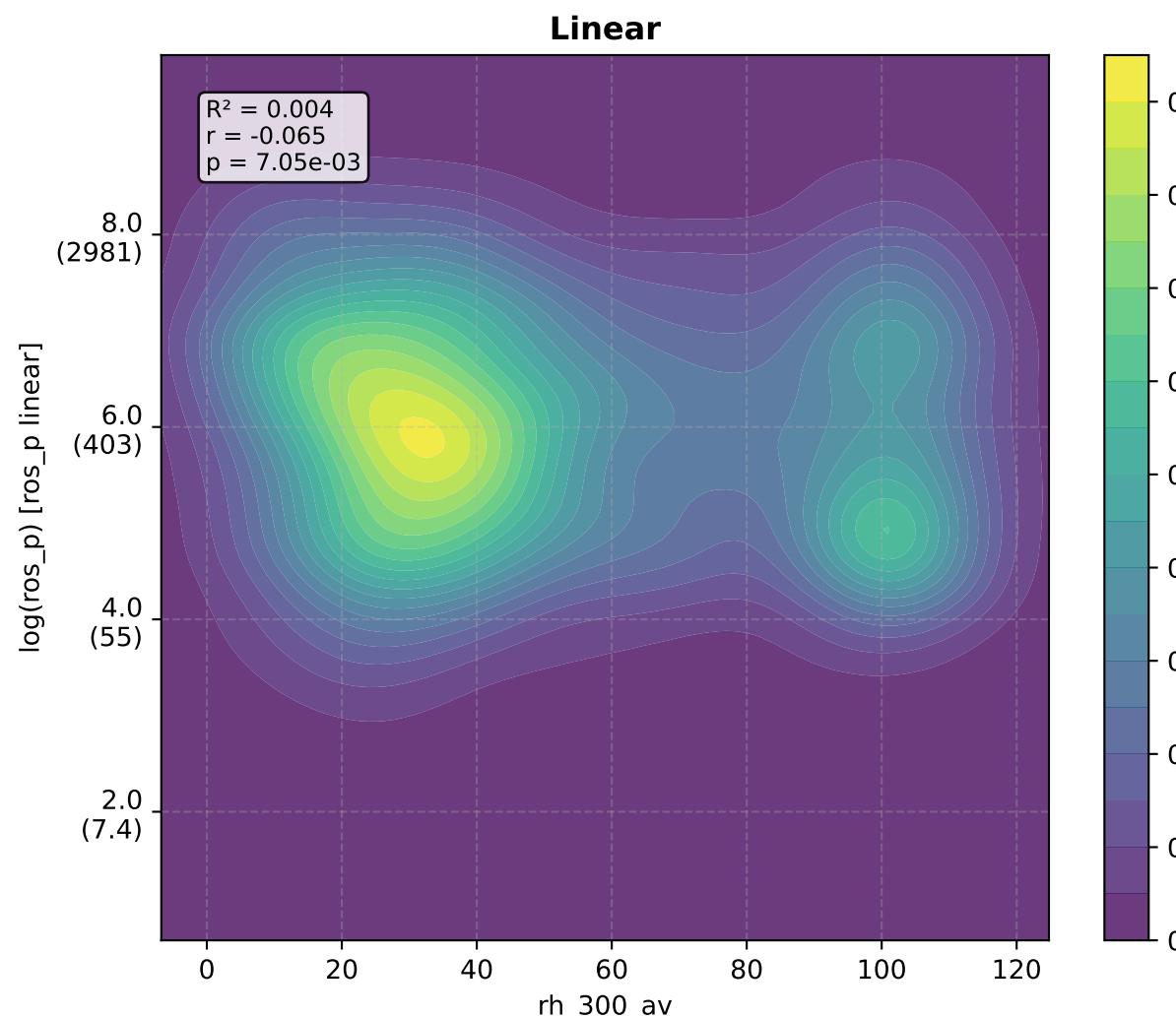
rh_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



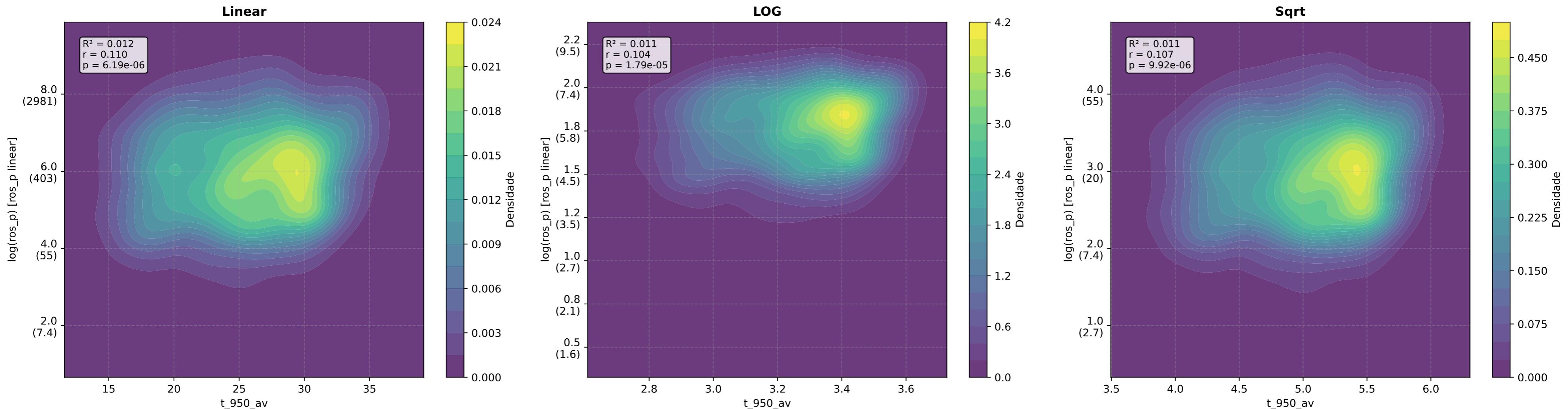
rh_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



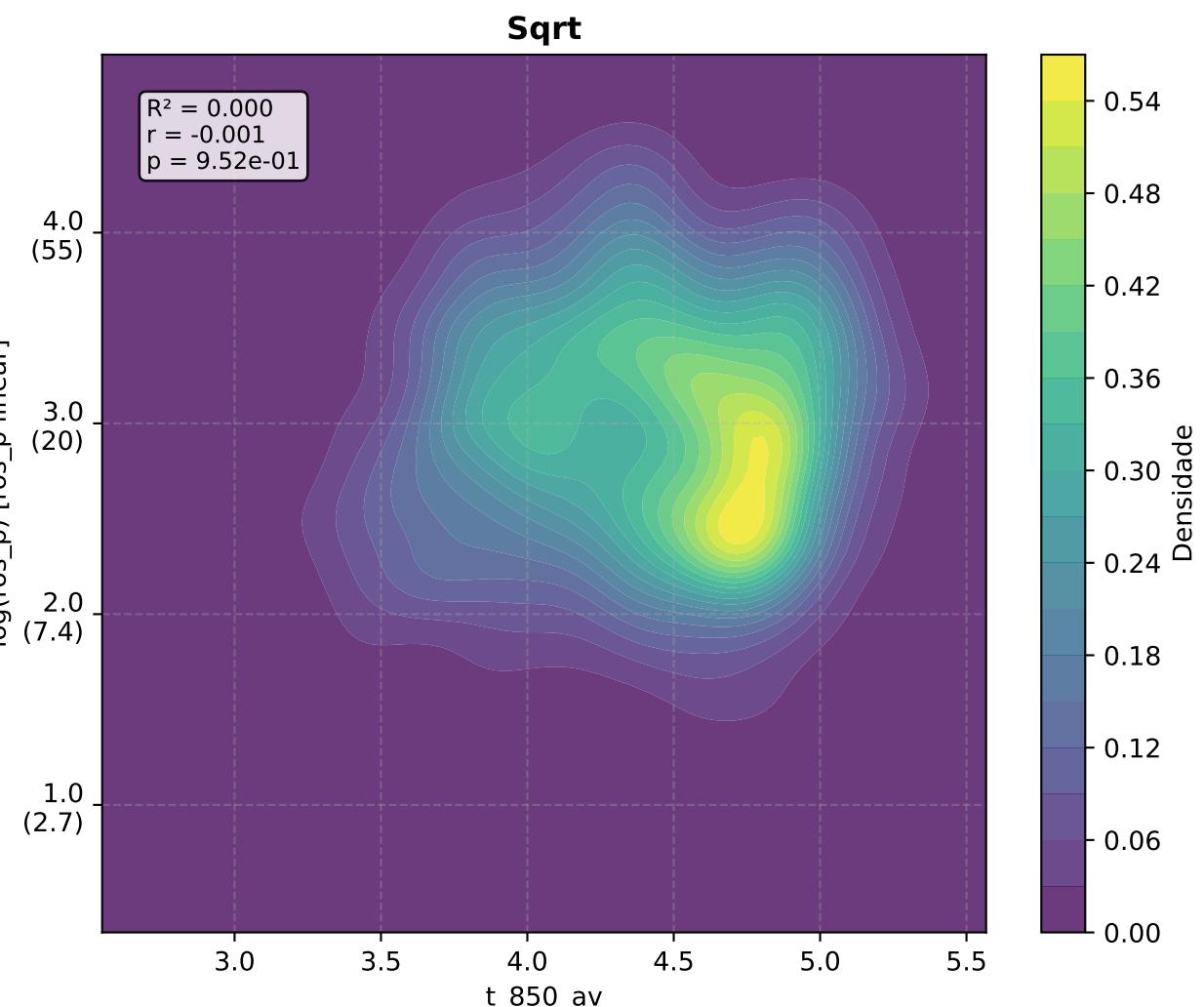
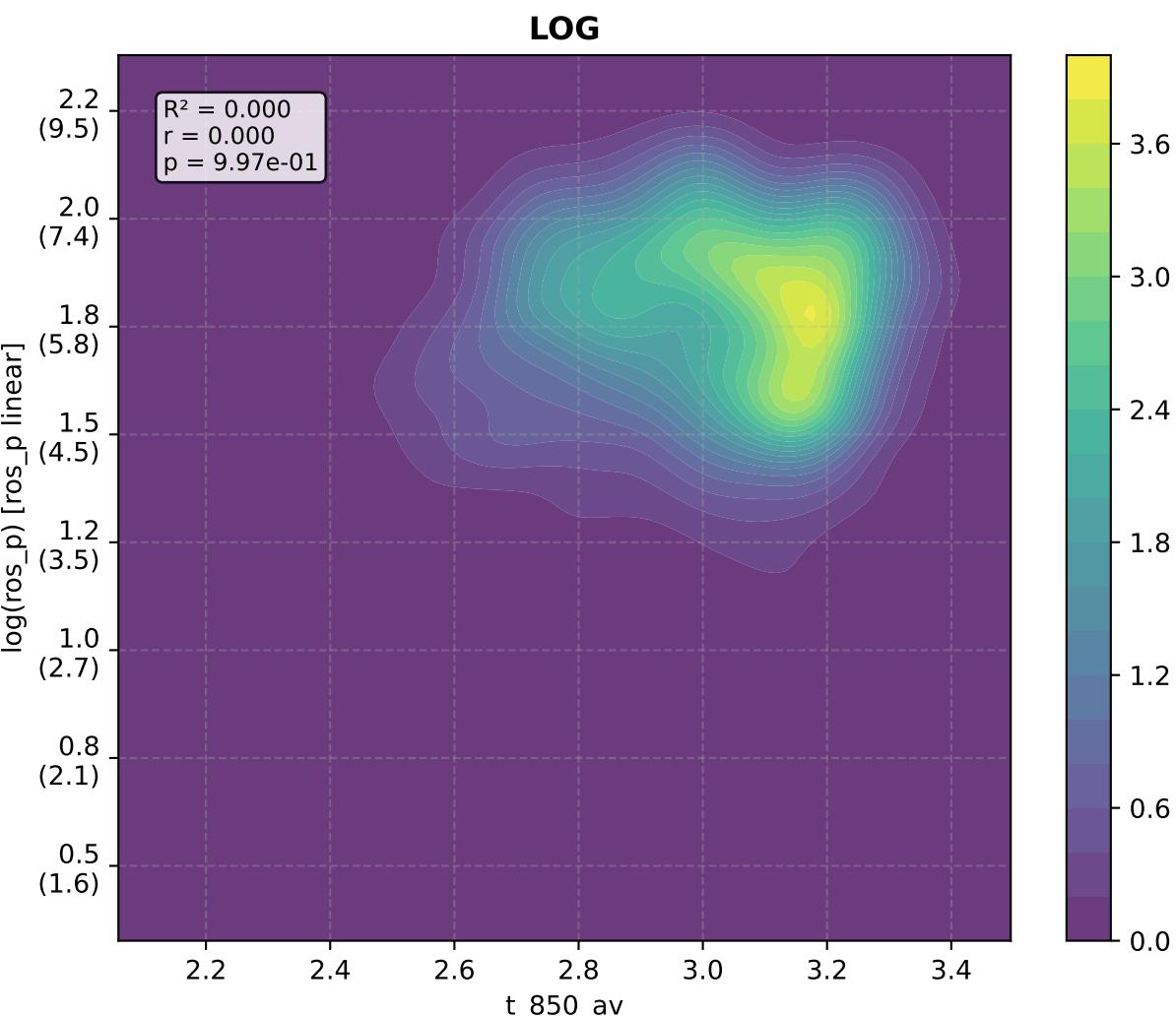
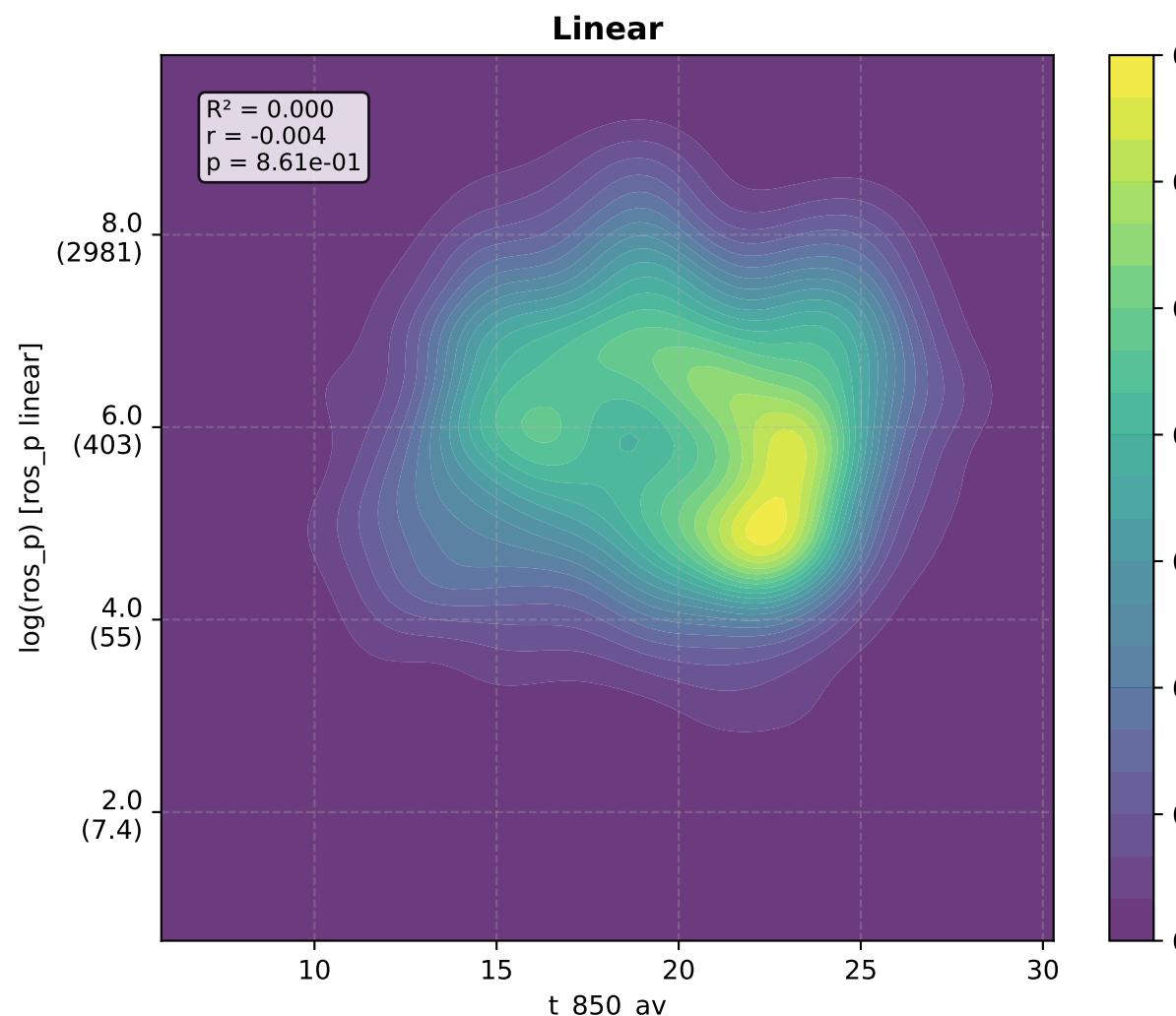
rh_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



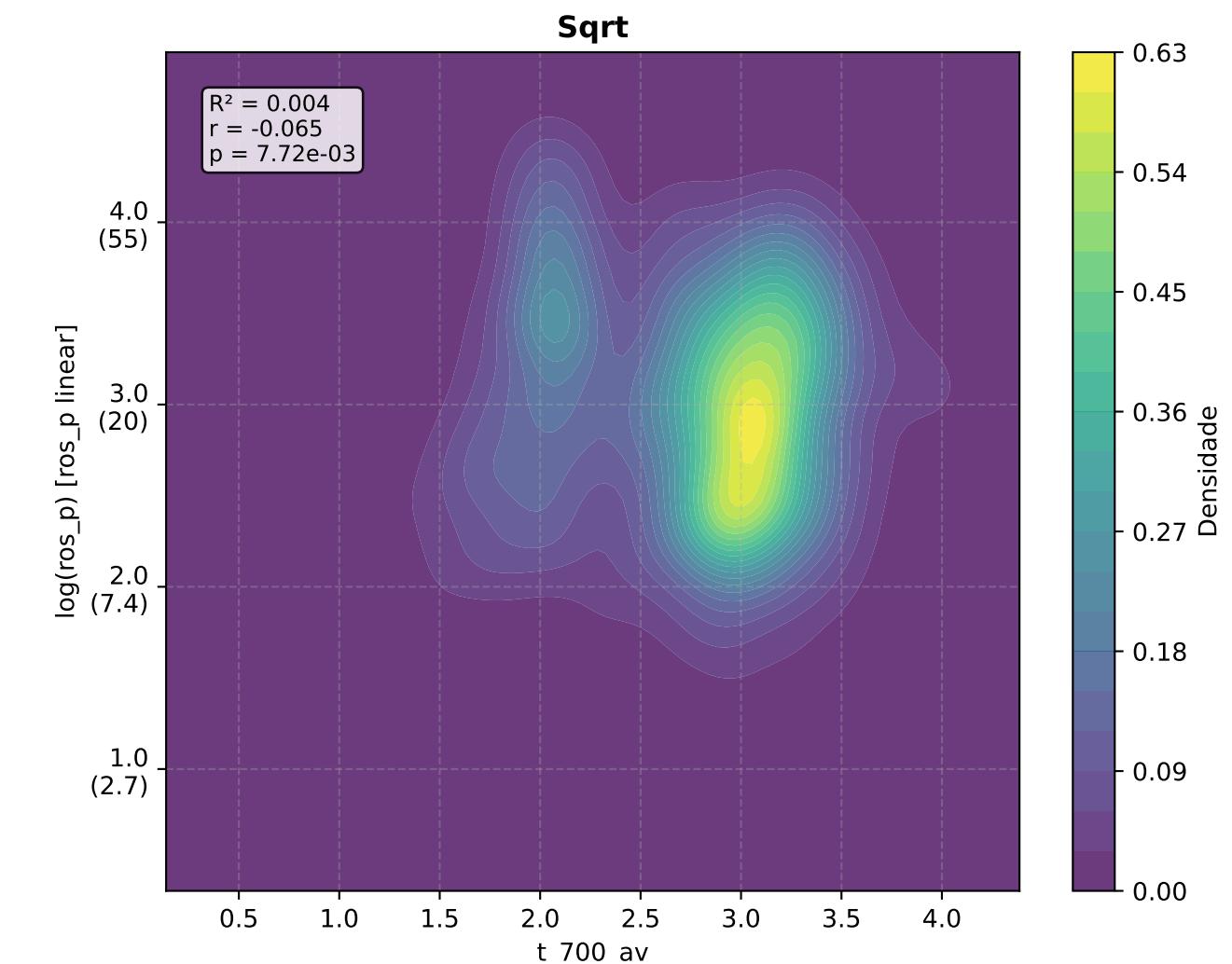
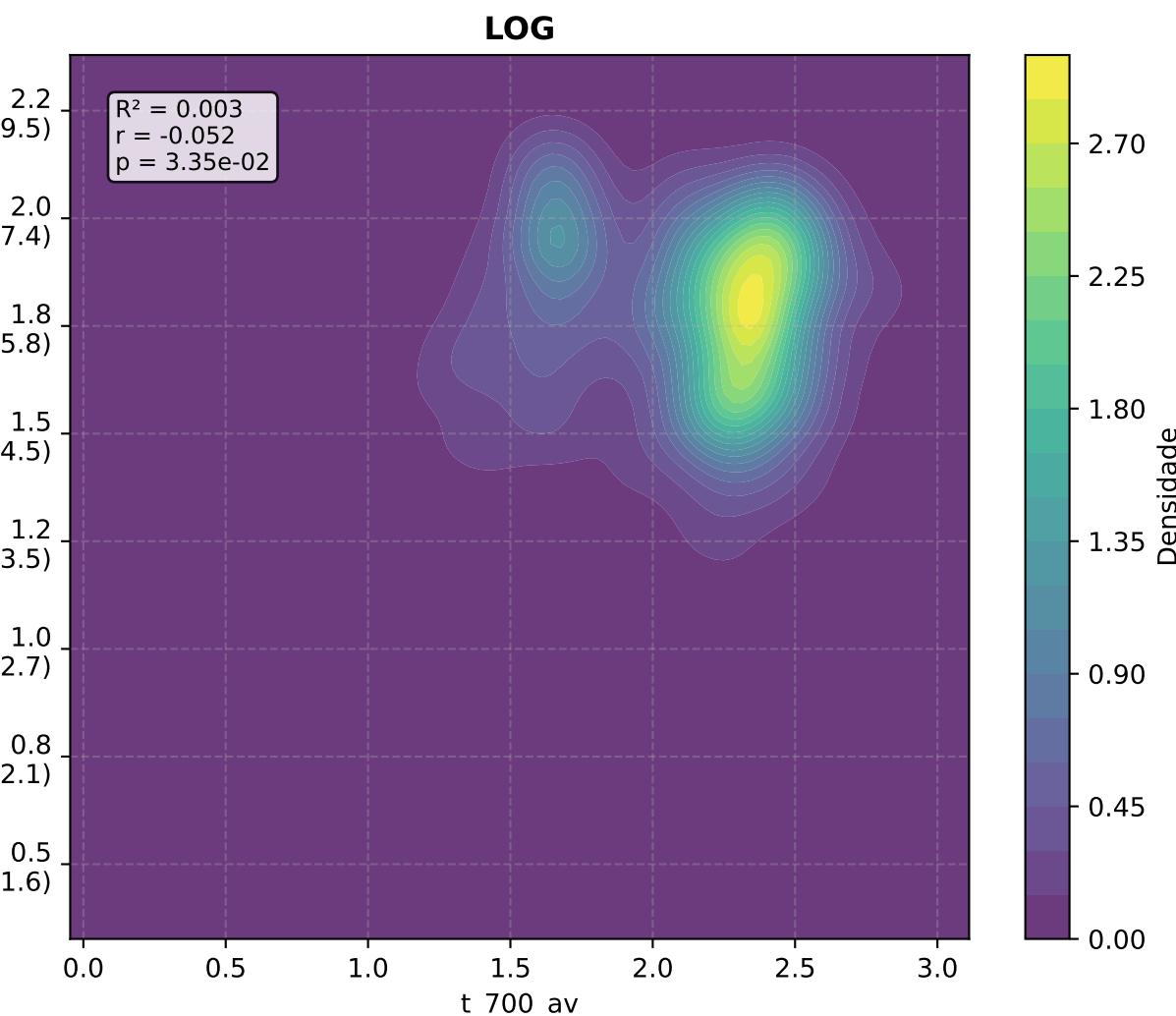
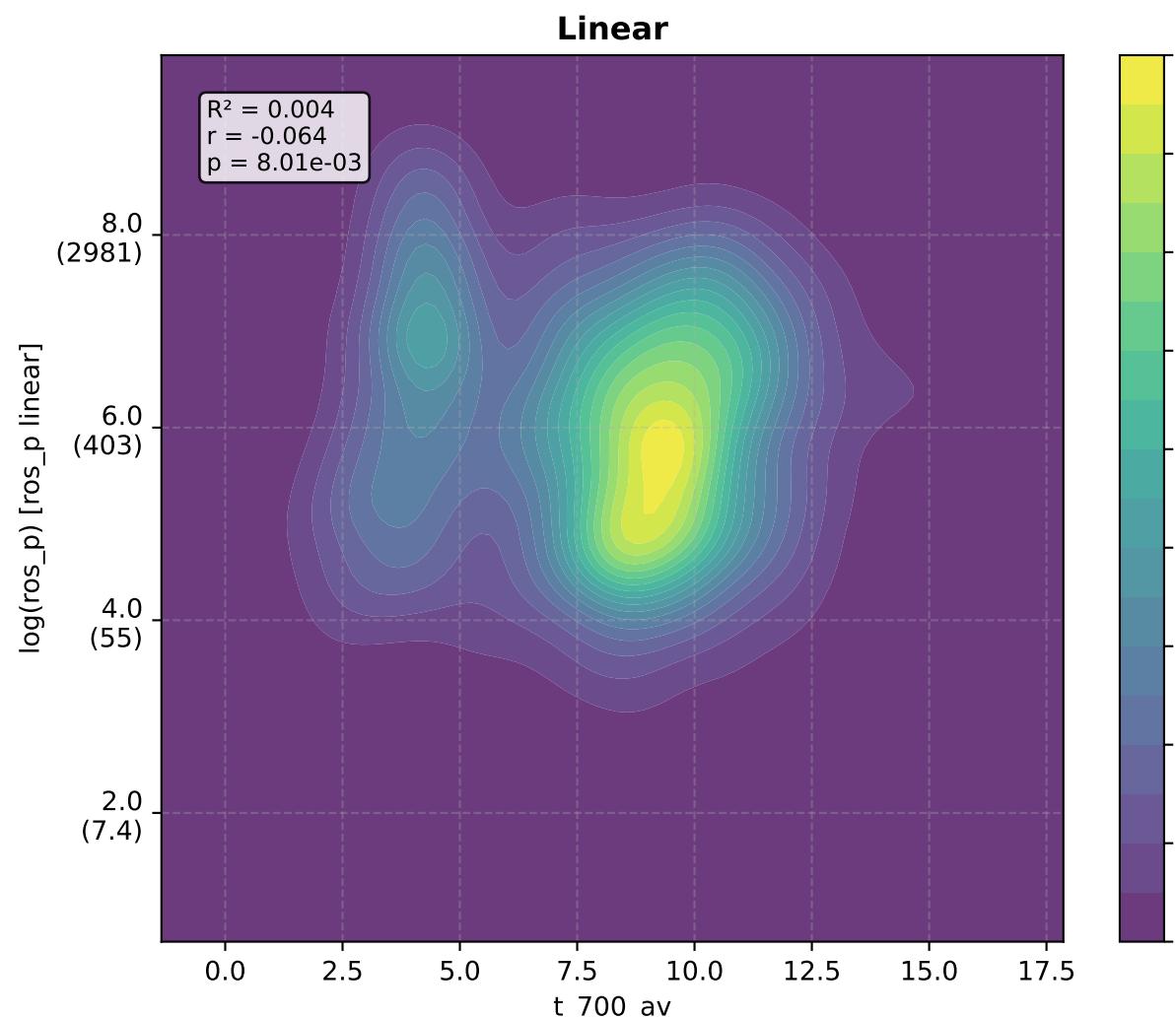
t_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



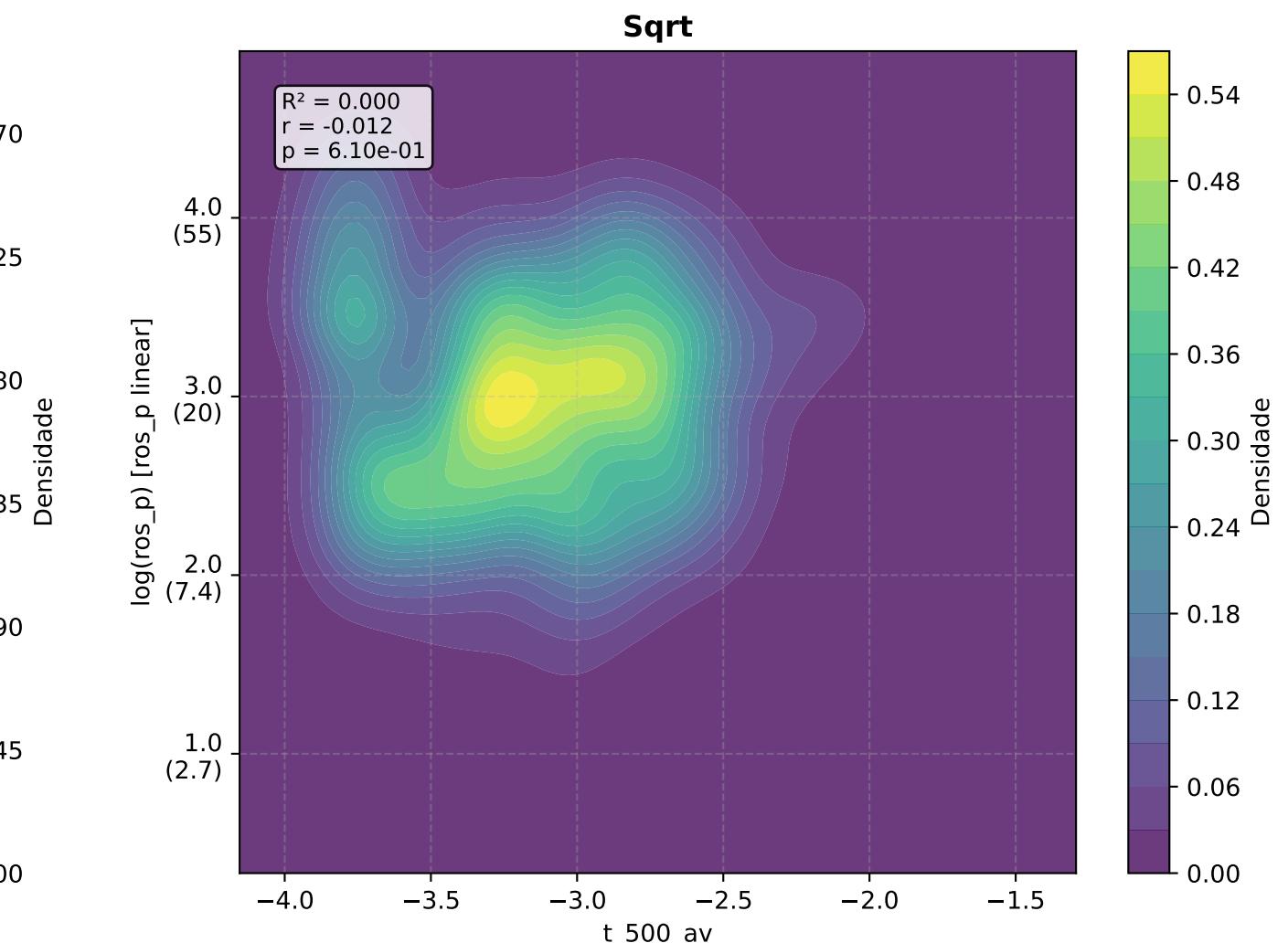
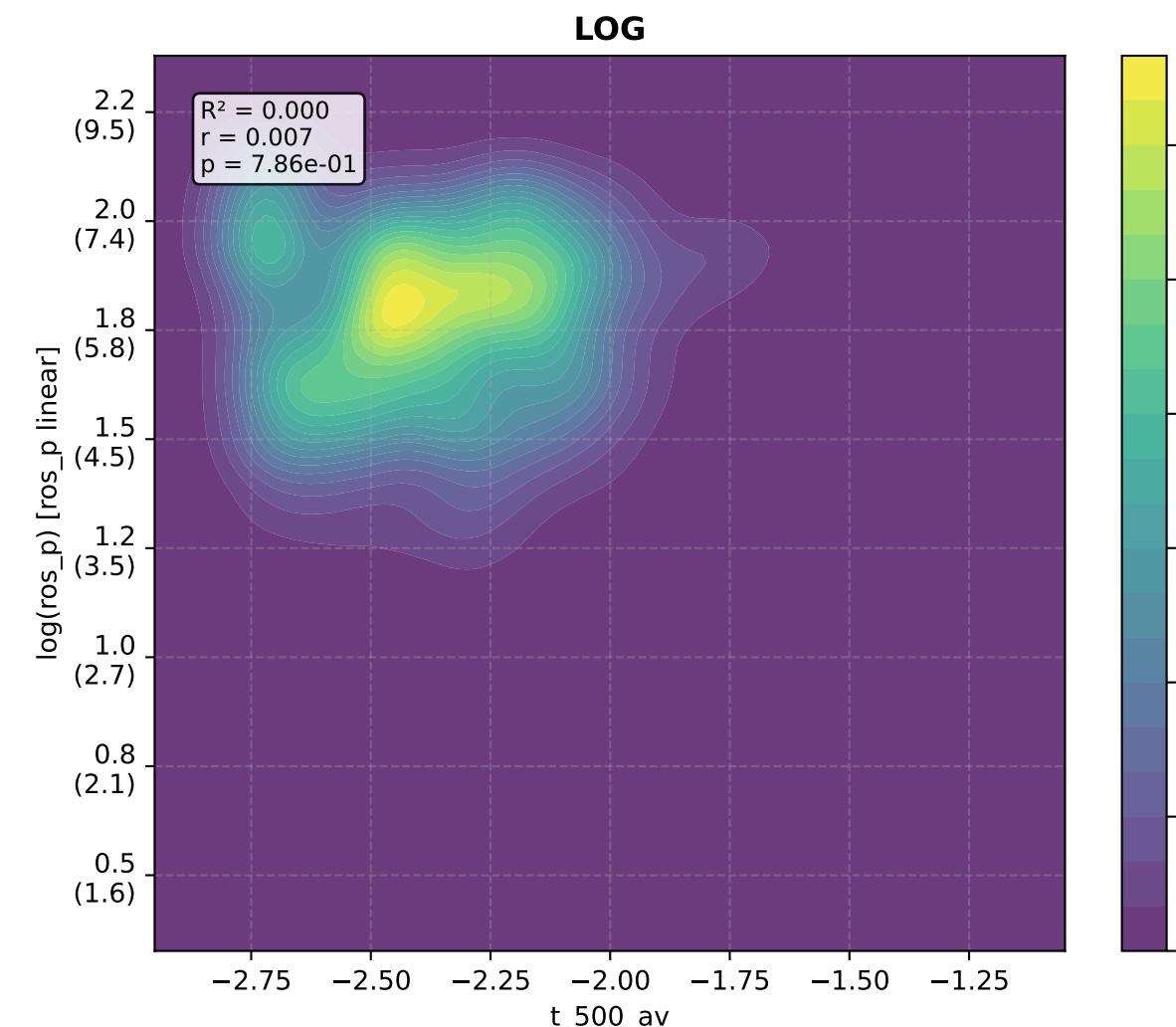
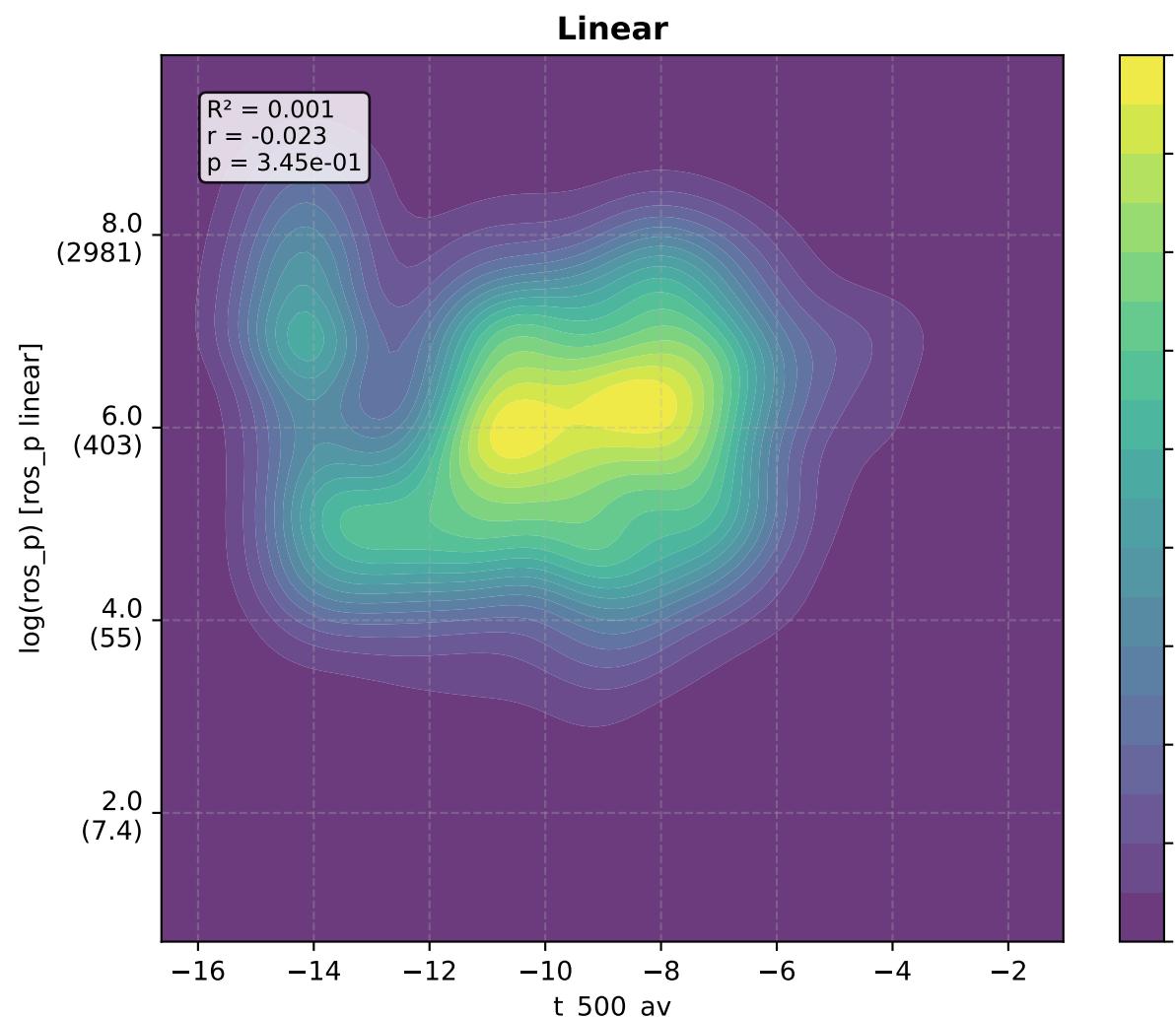
t_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



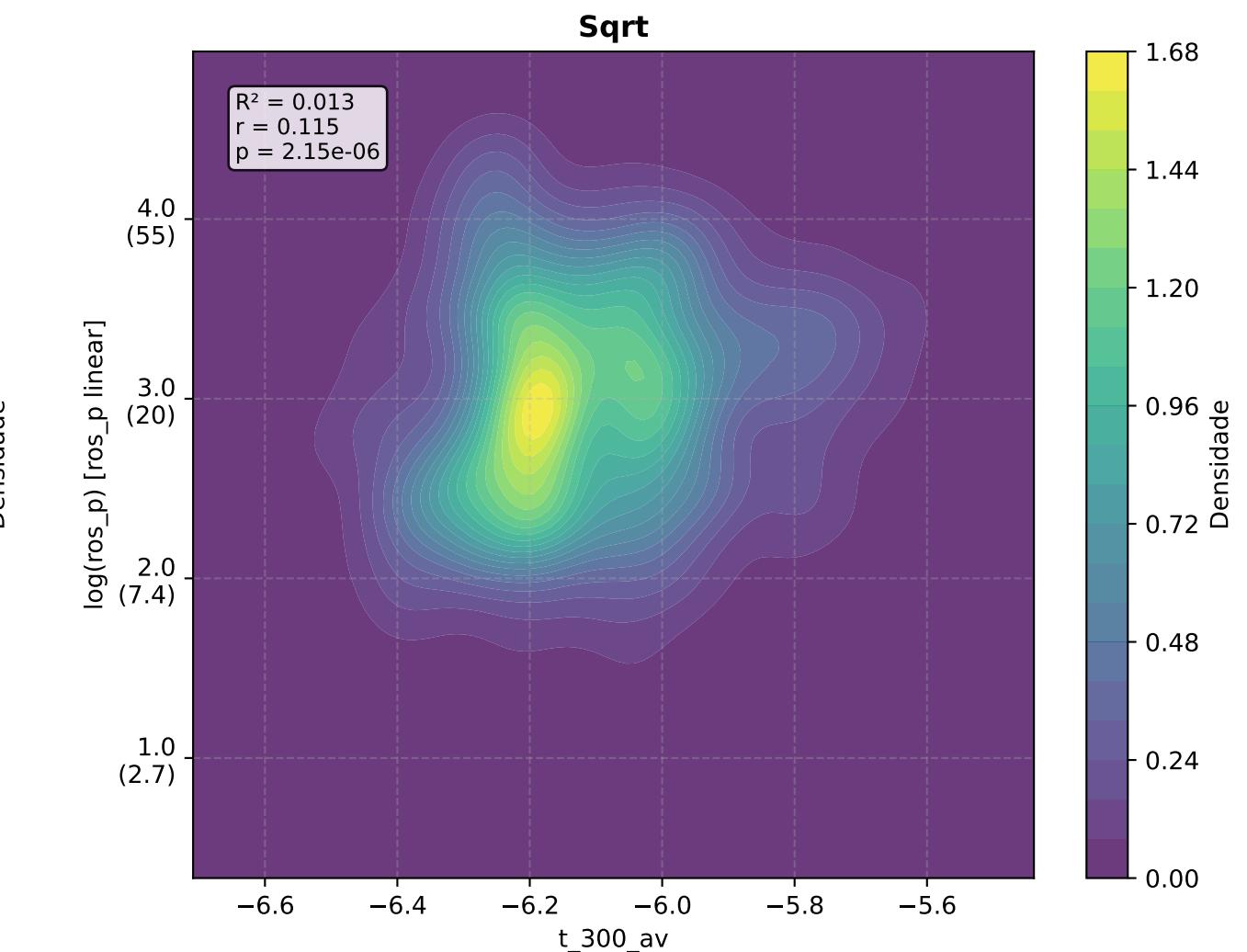
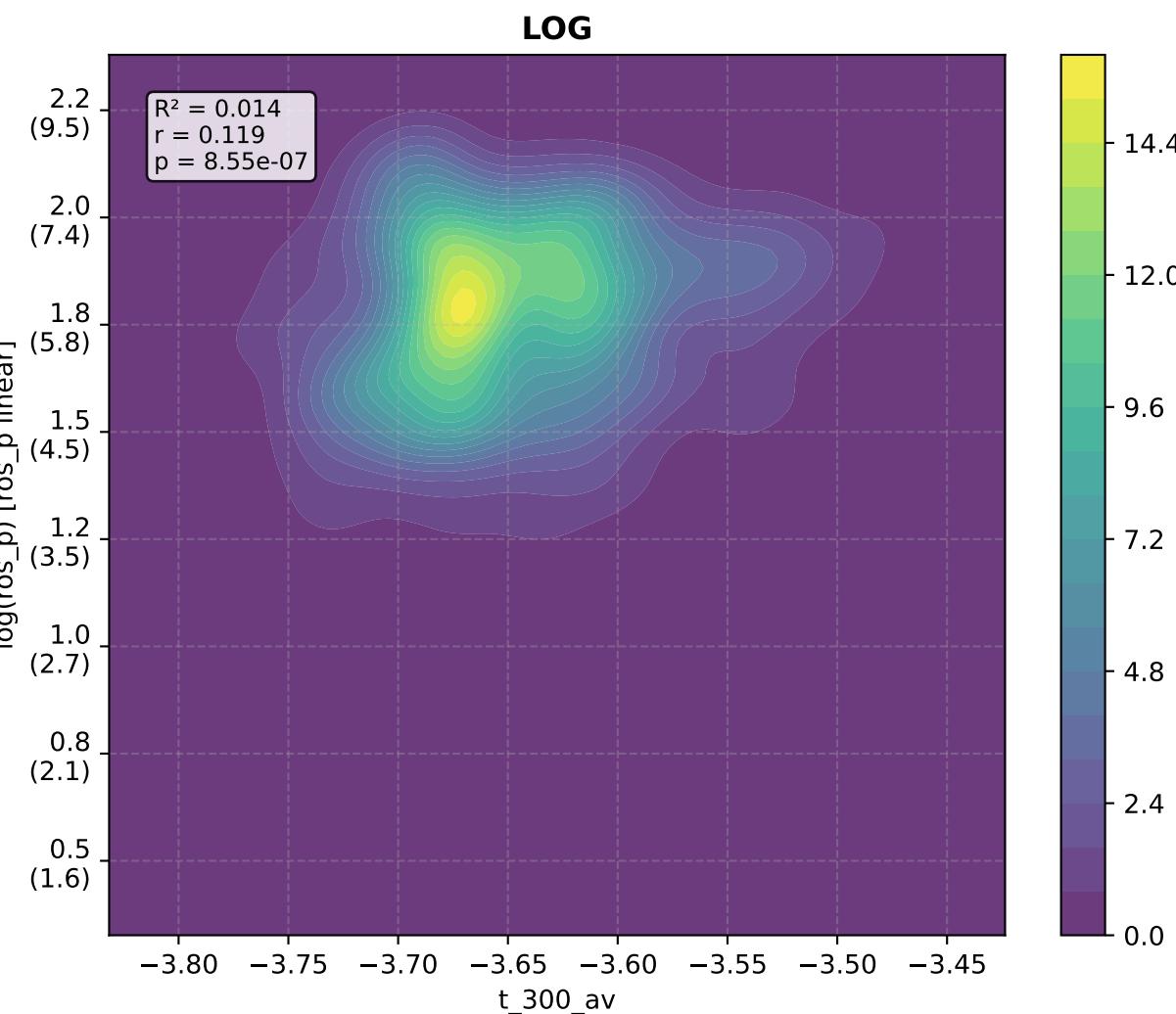
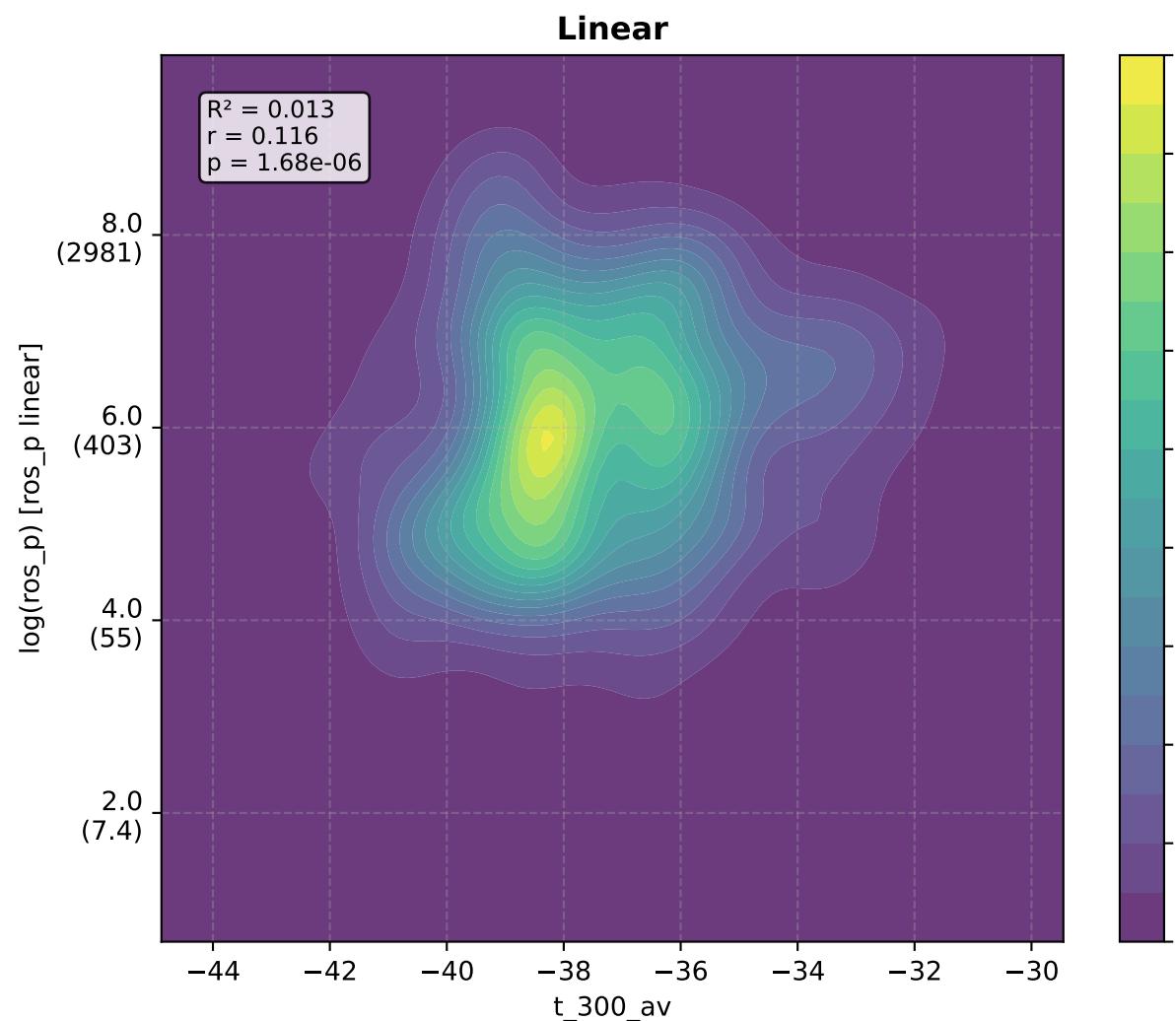
t_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



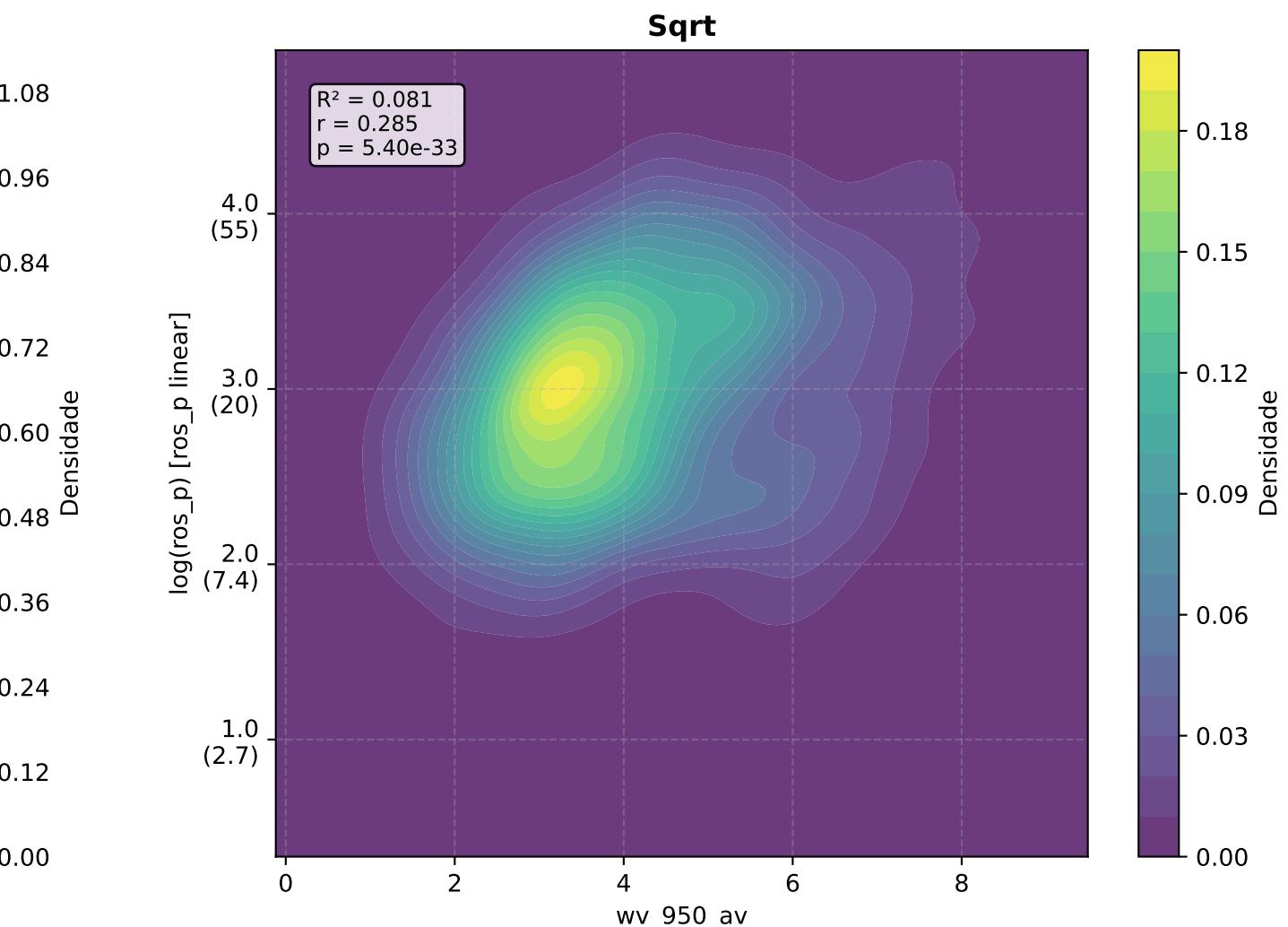
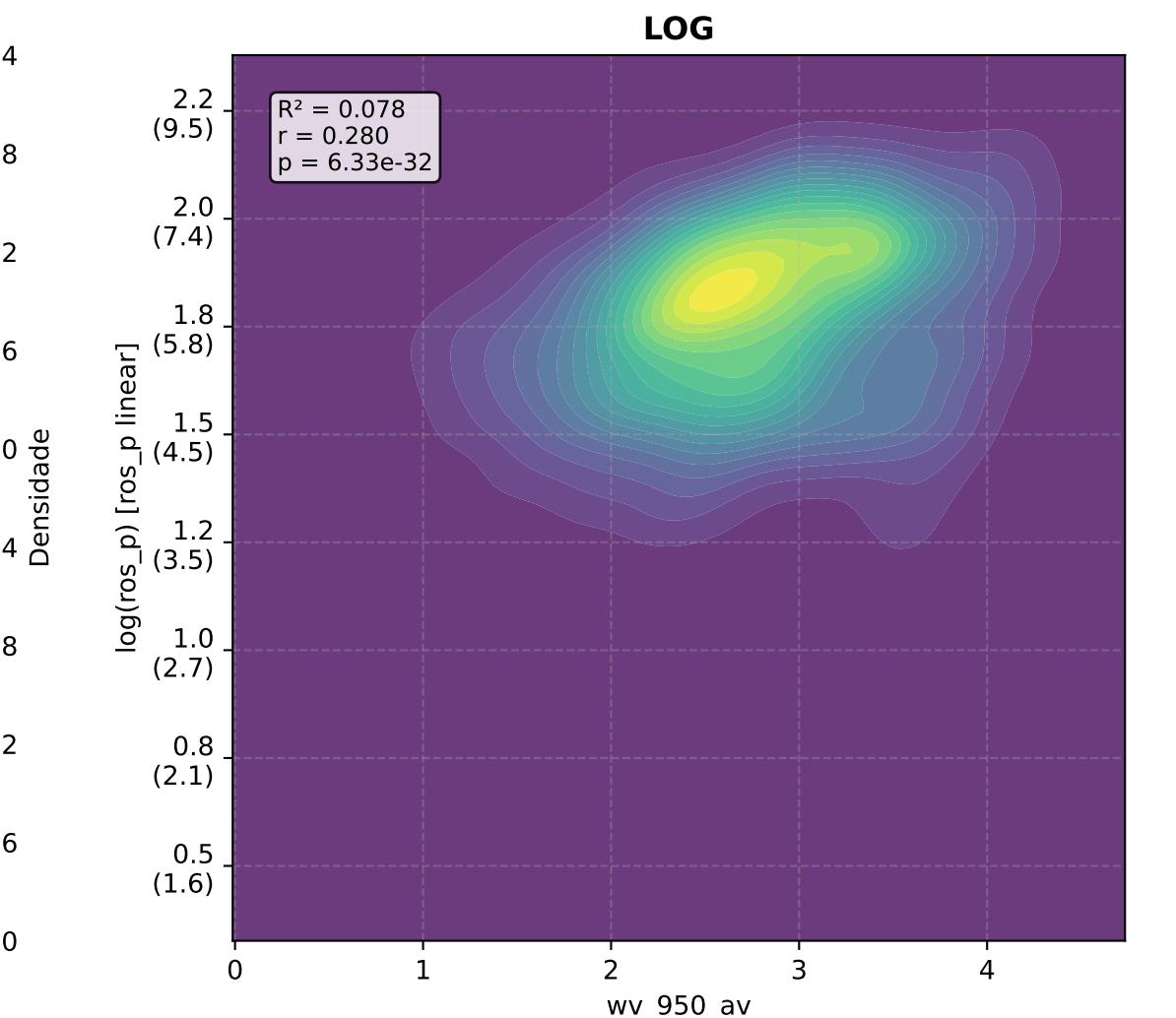
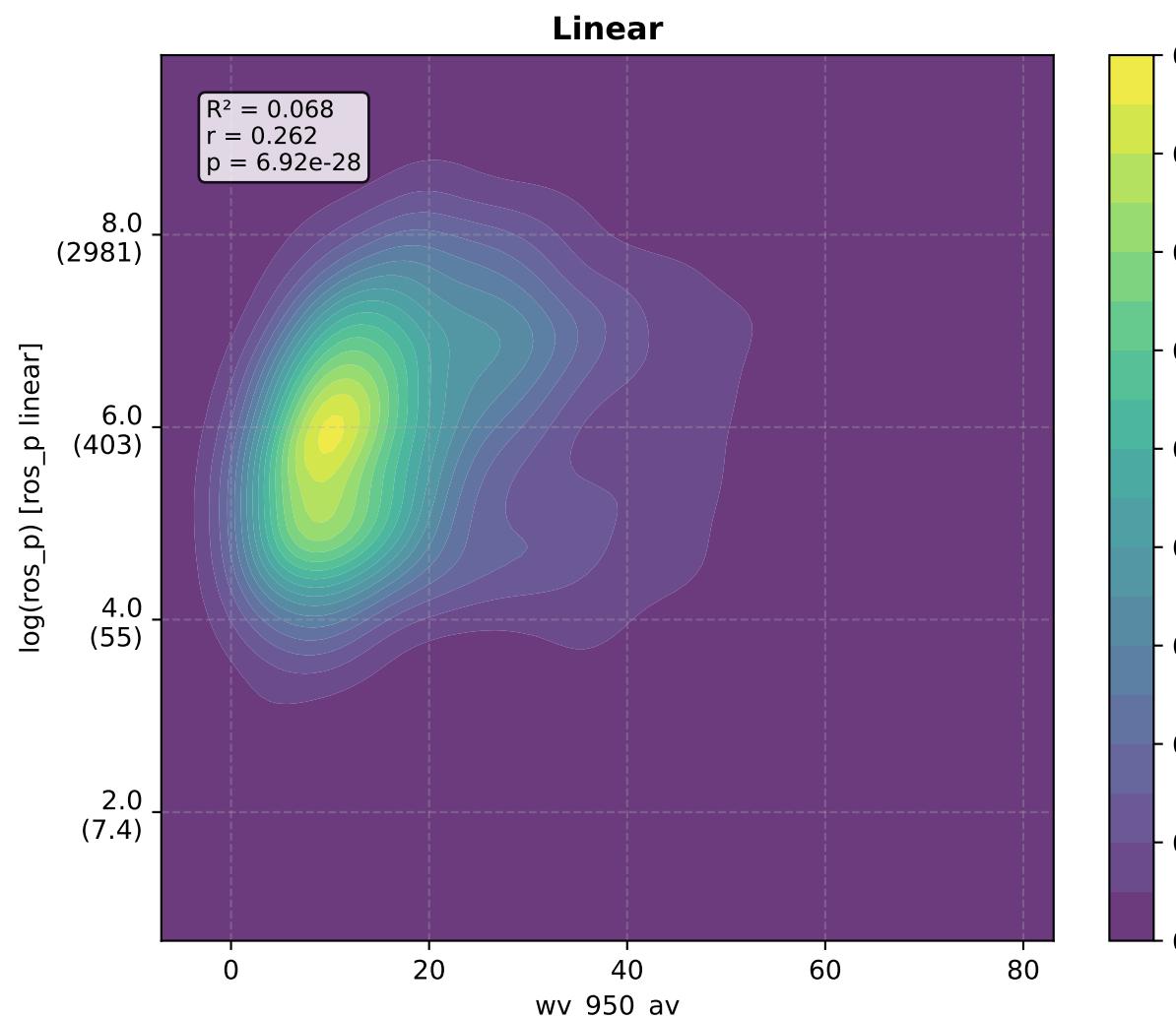
t_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



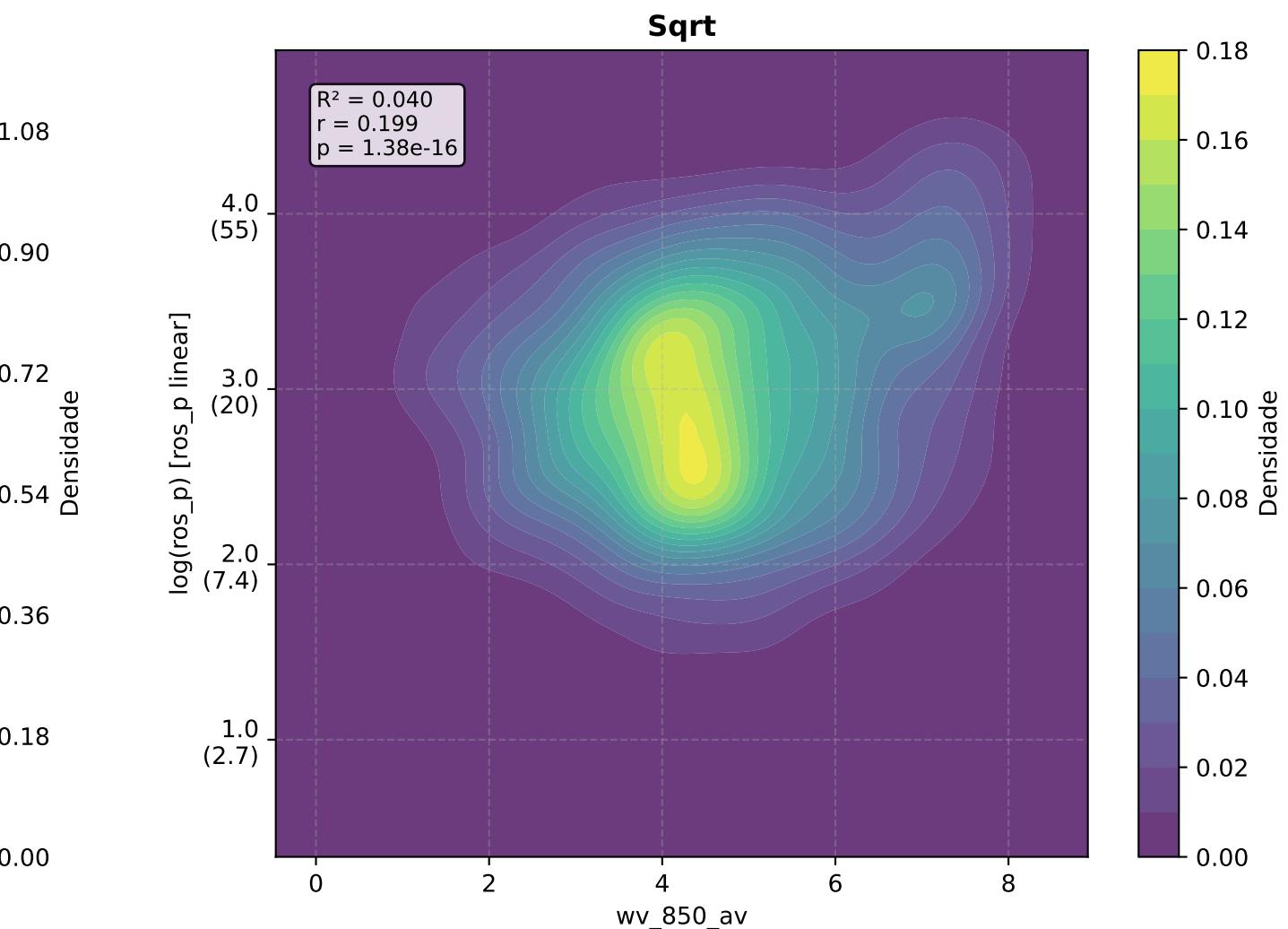
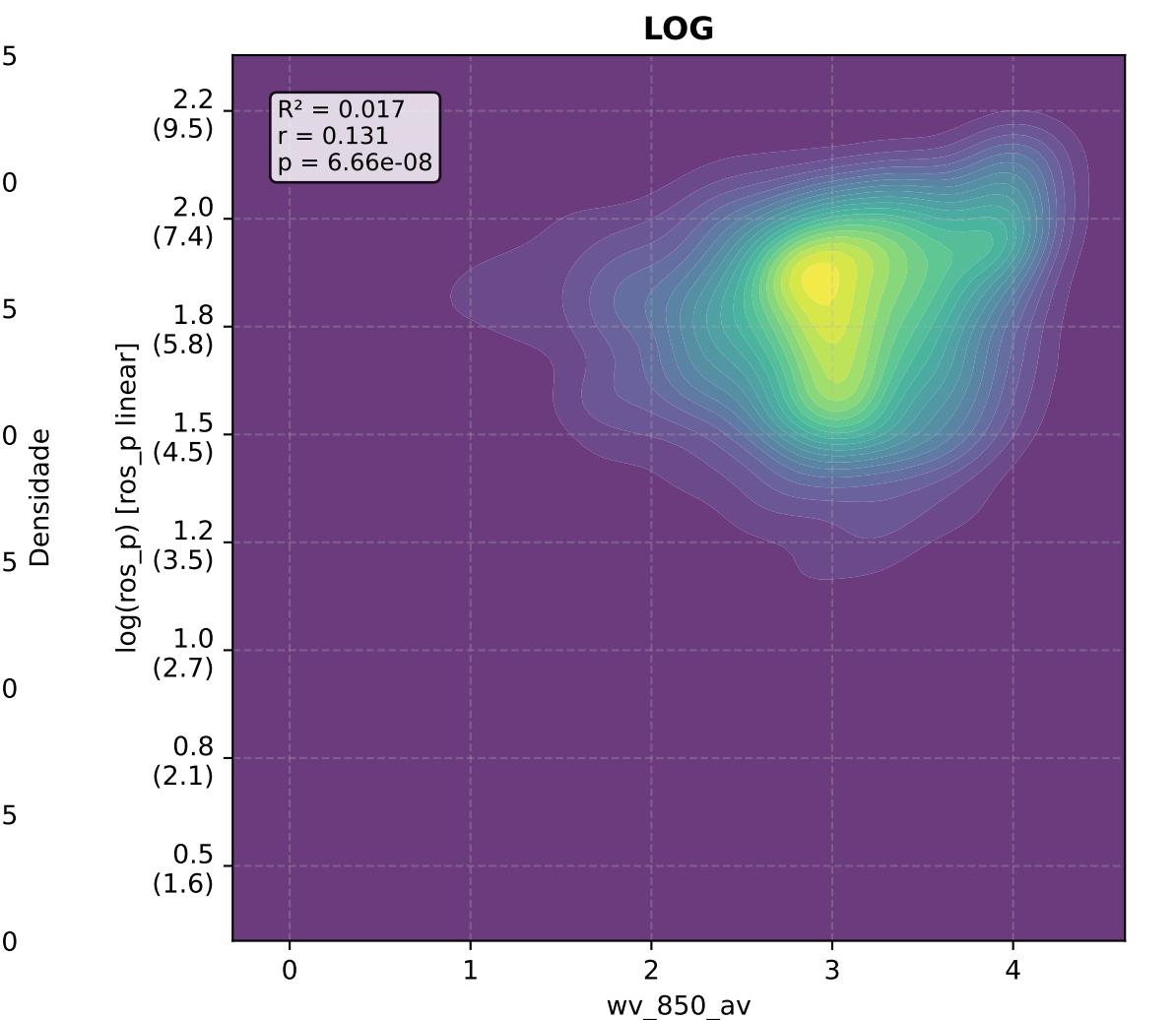
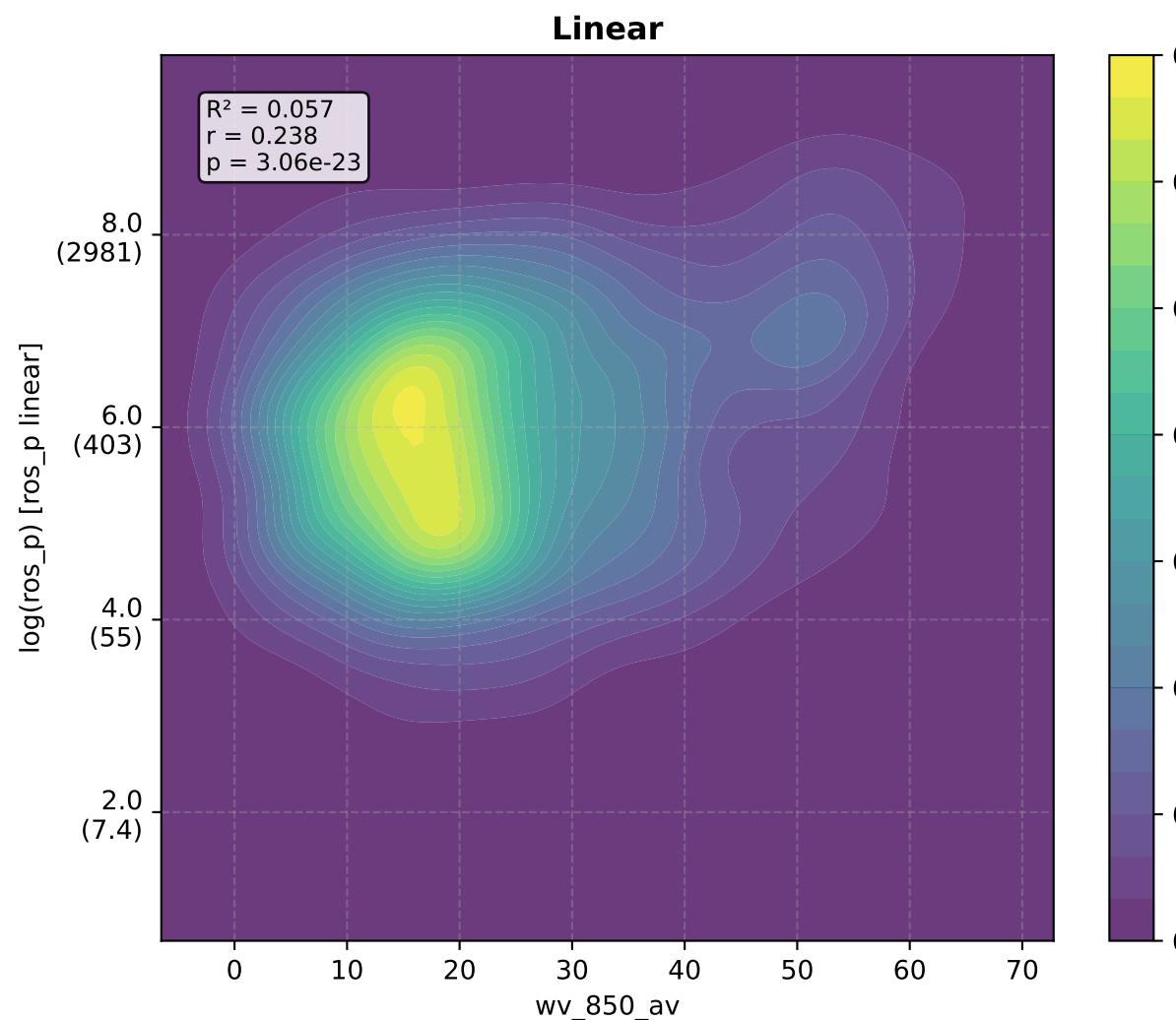
t_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



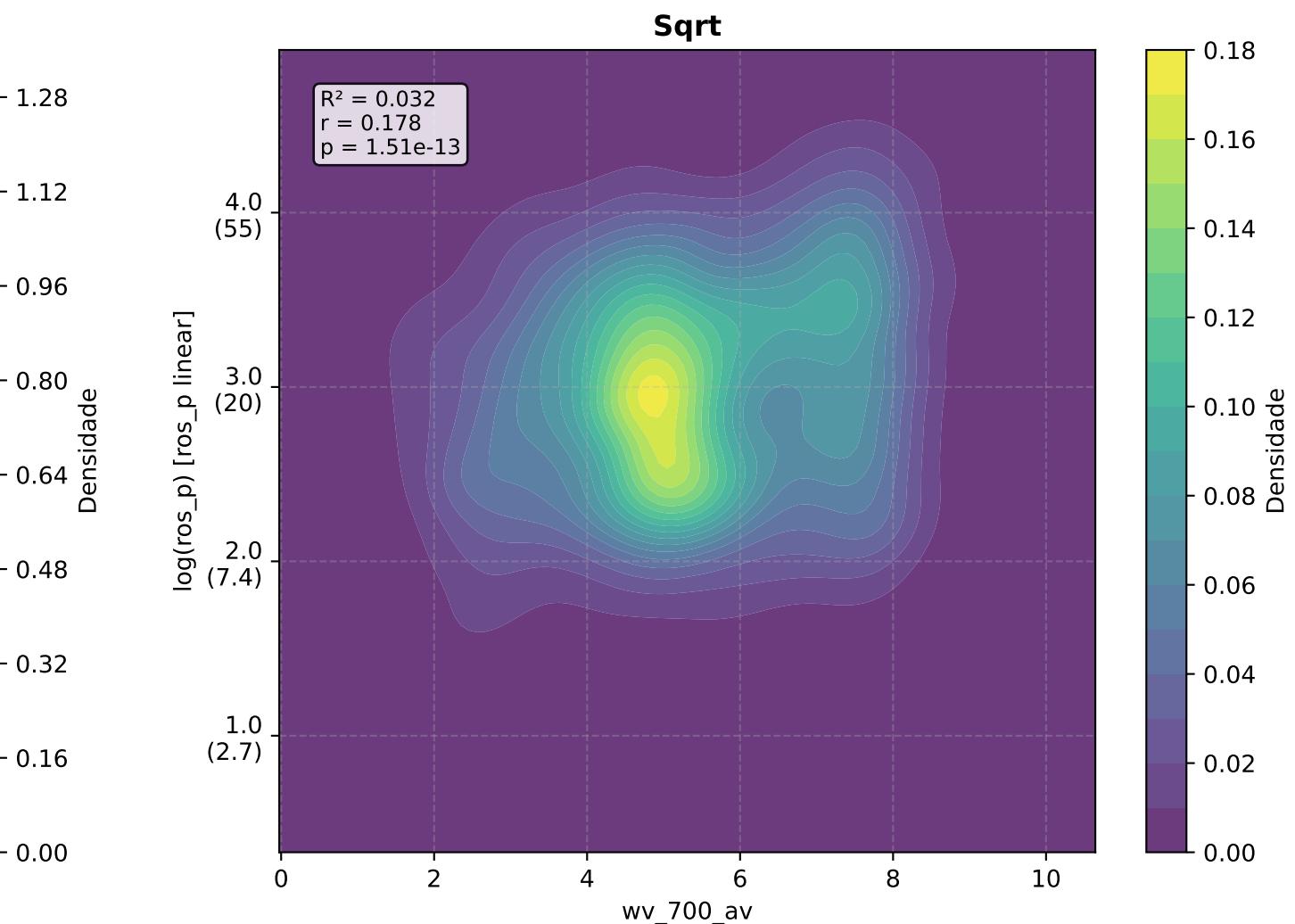
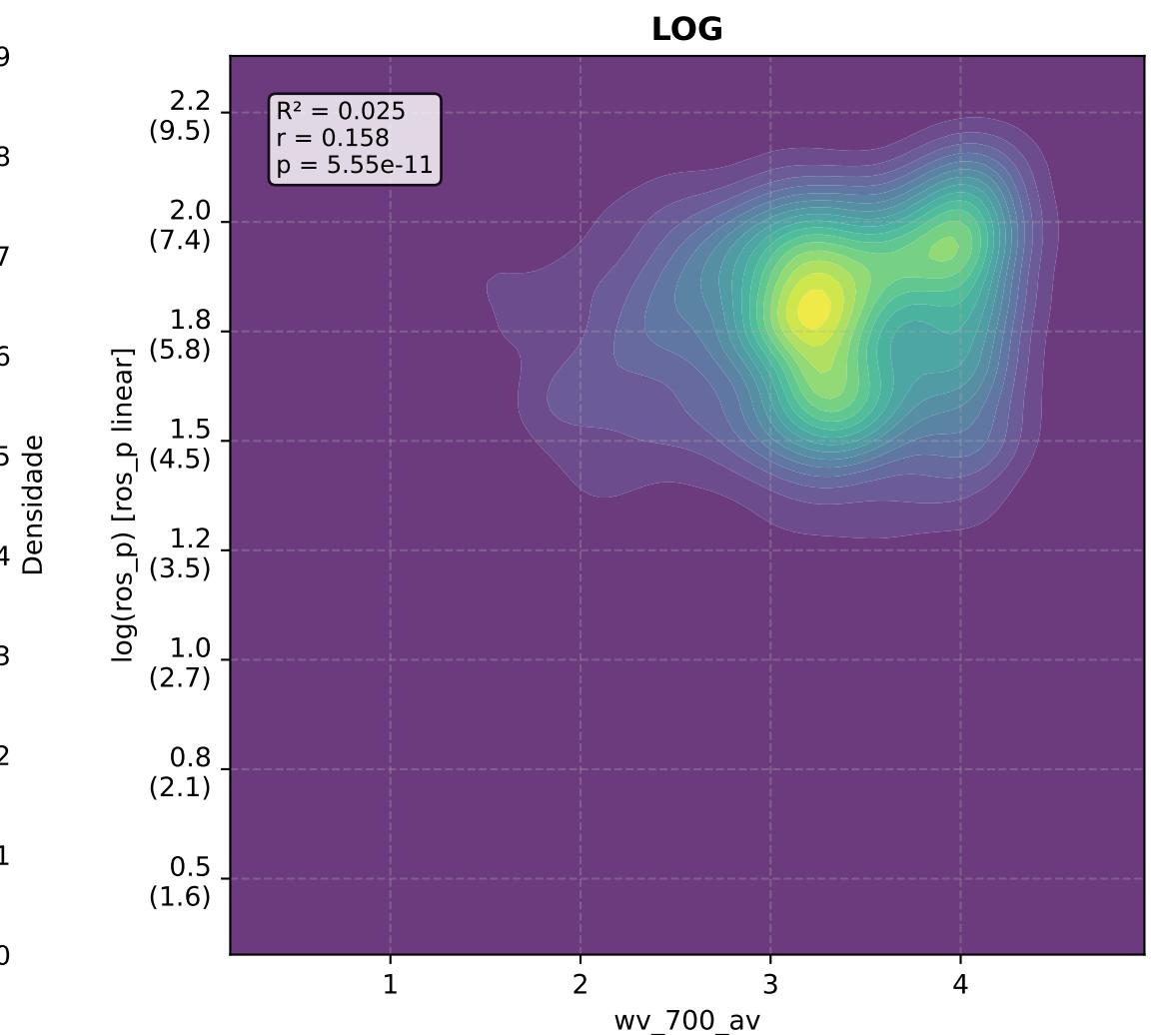
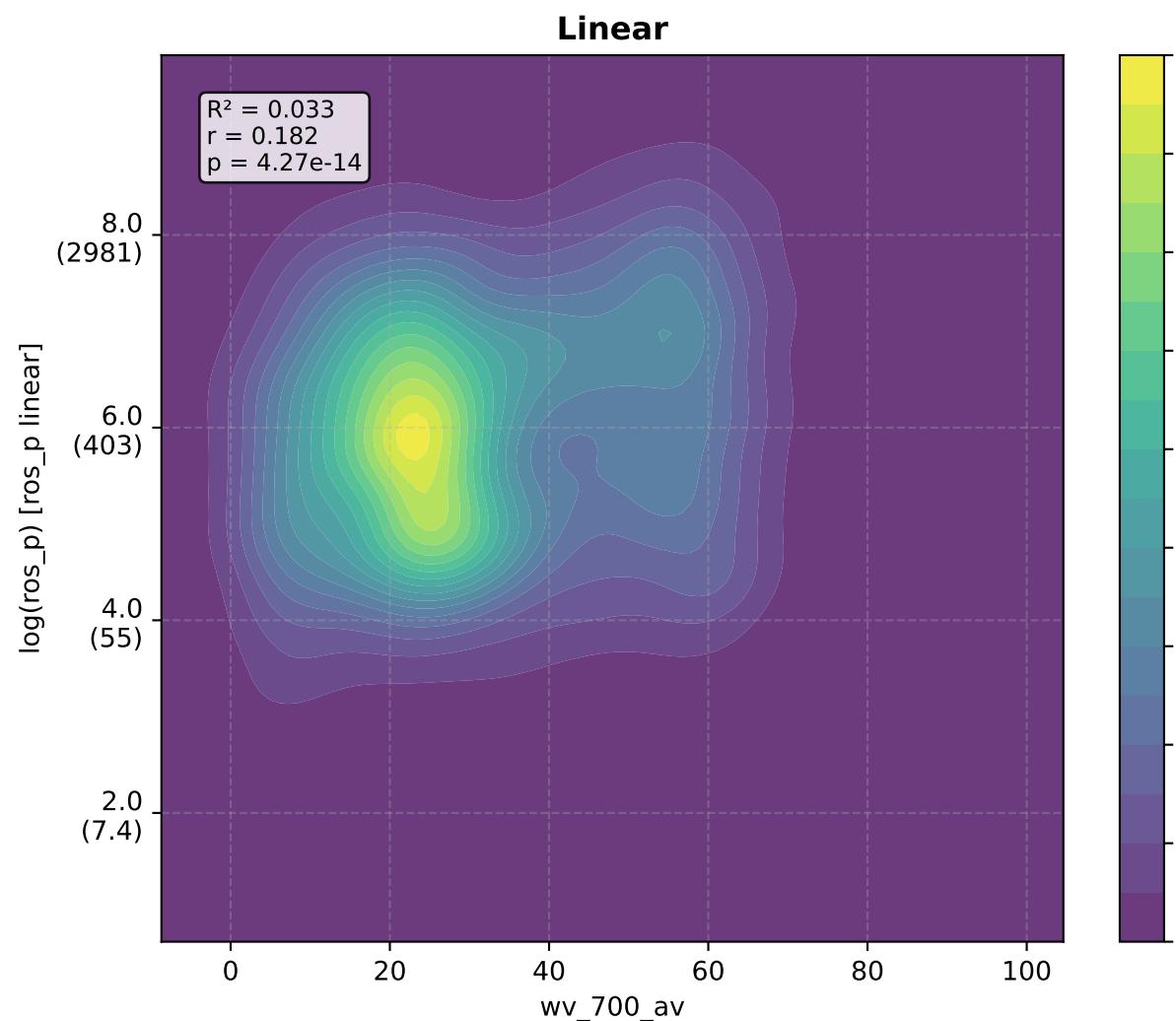
wv_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



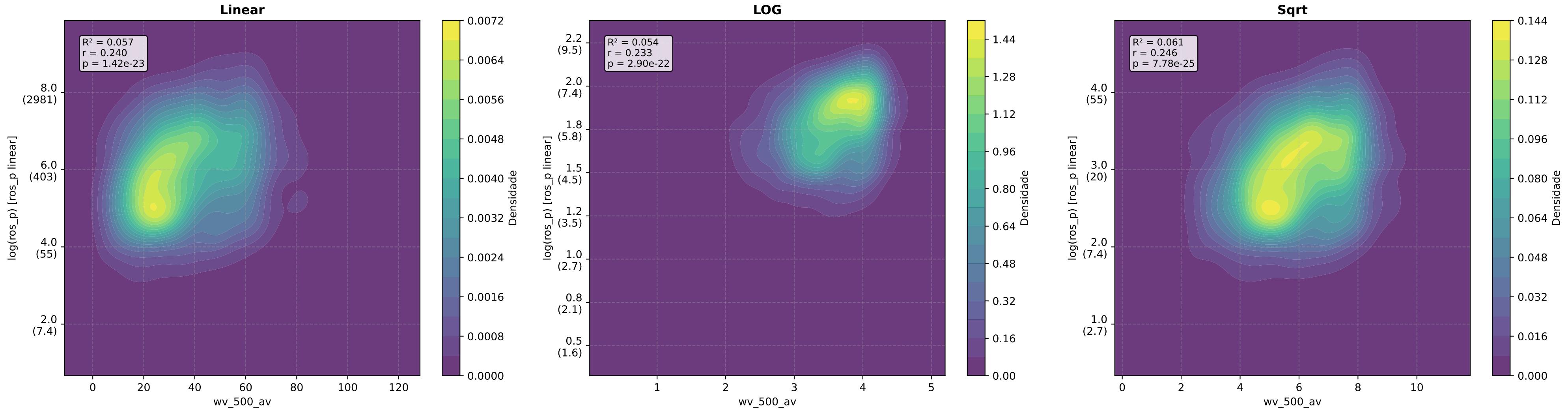
wv_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



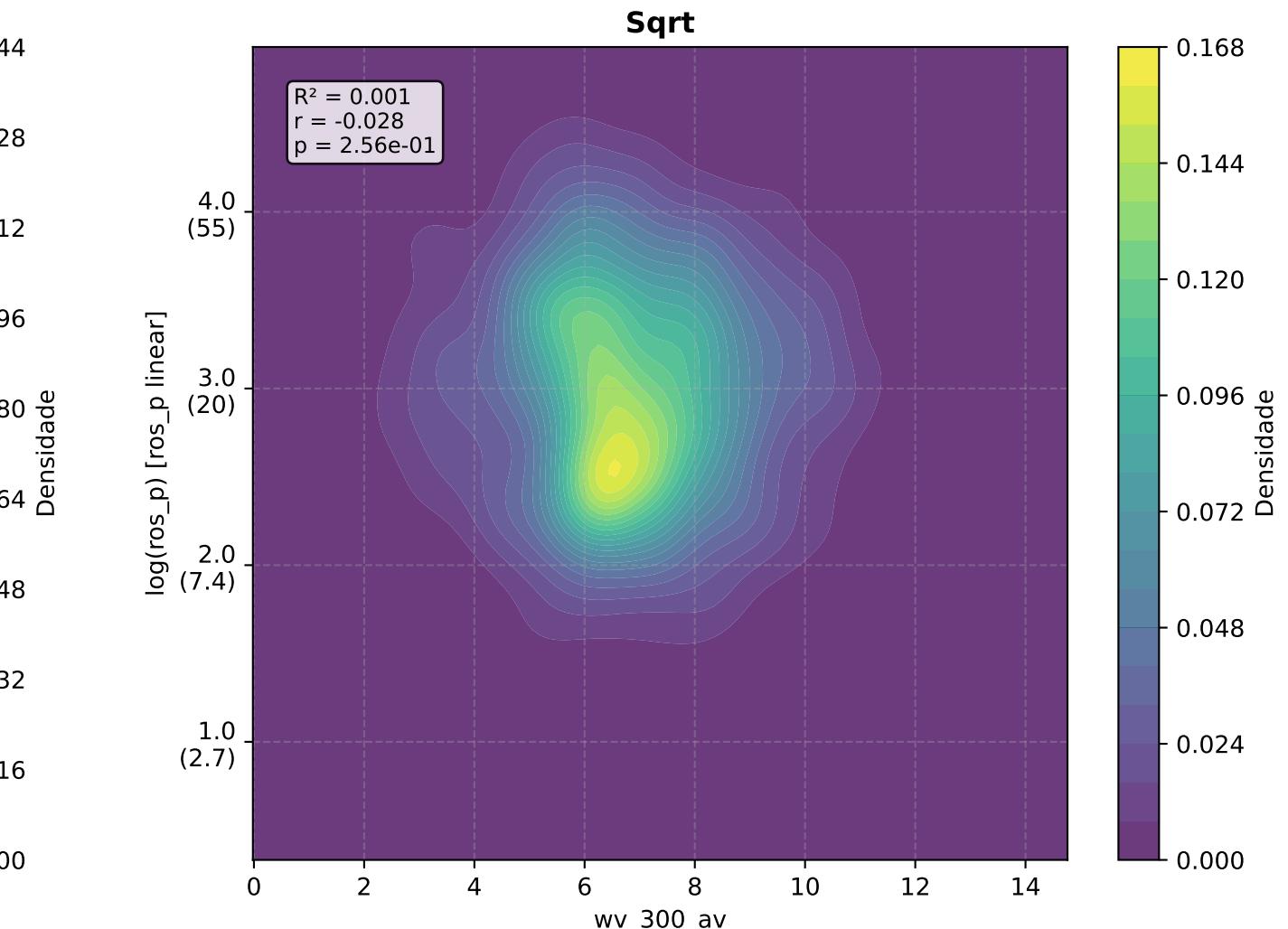
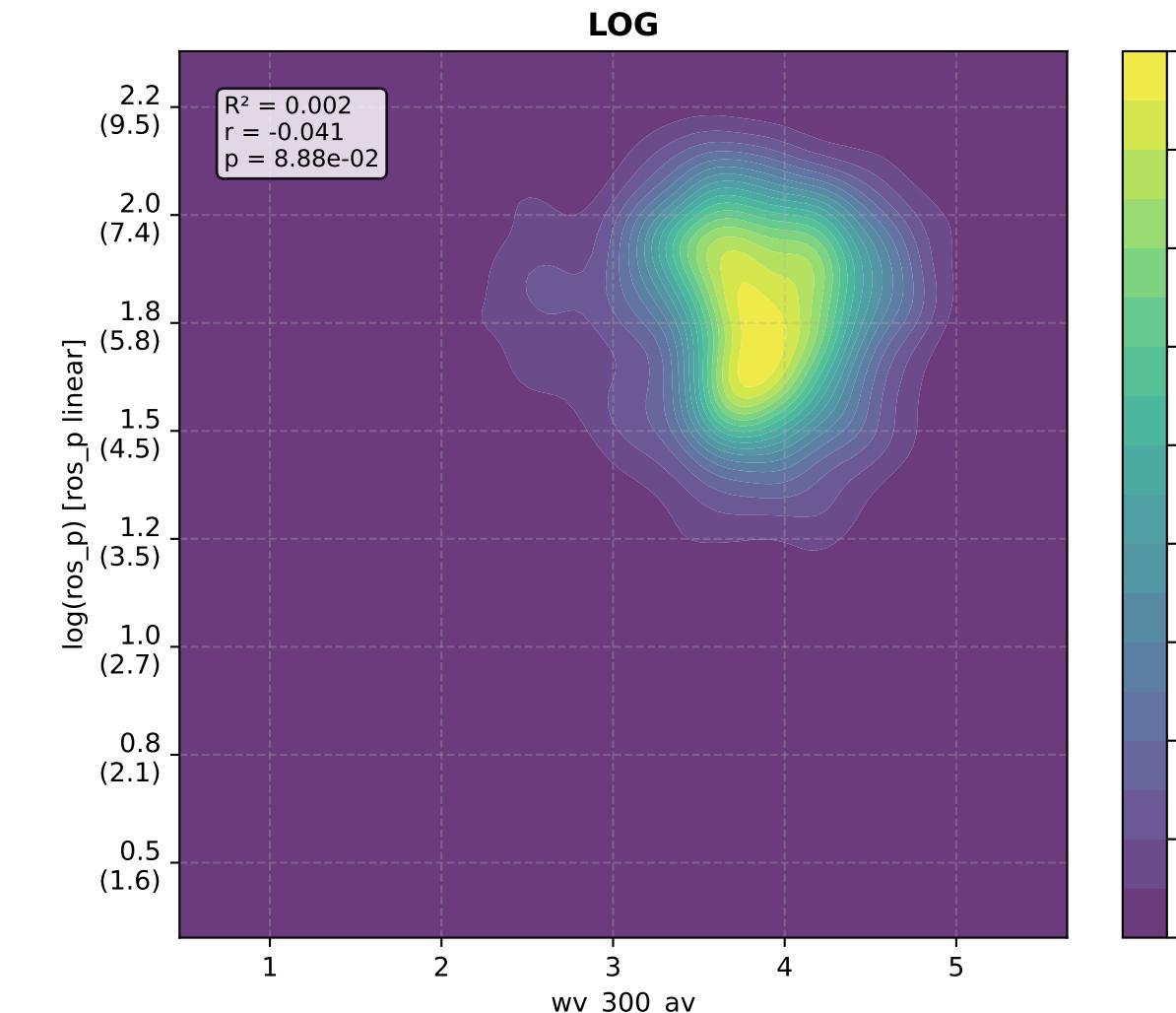
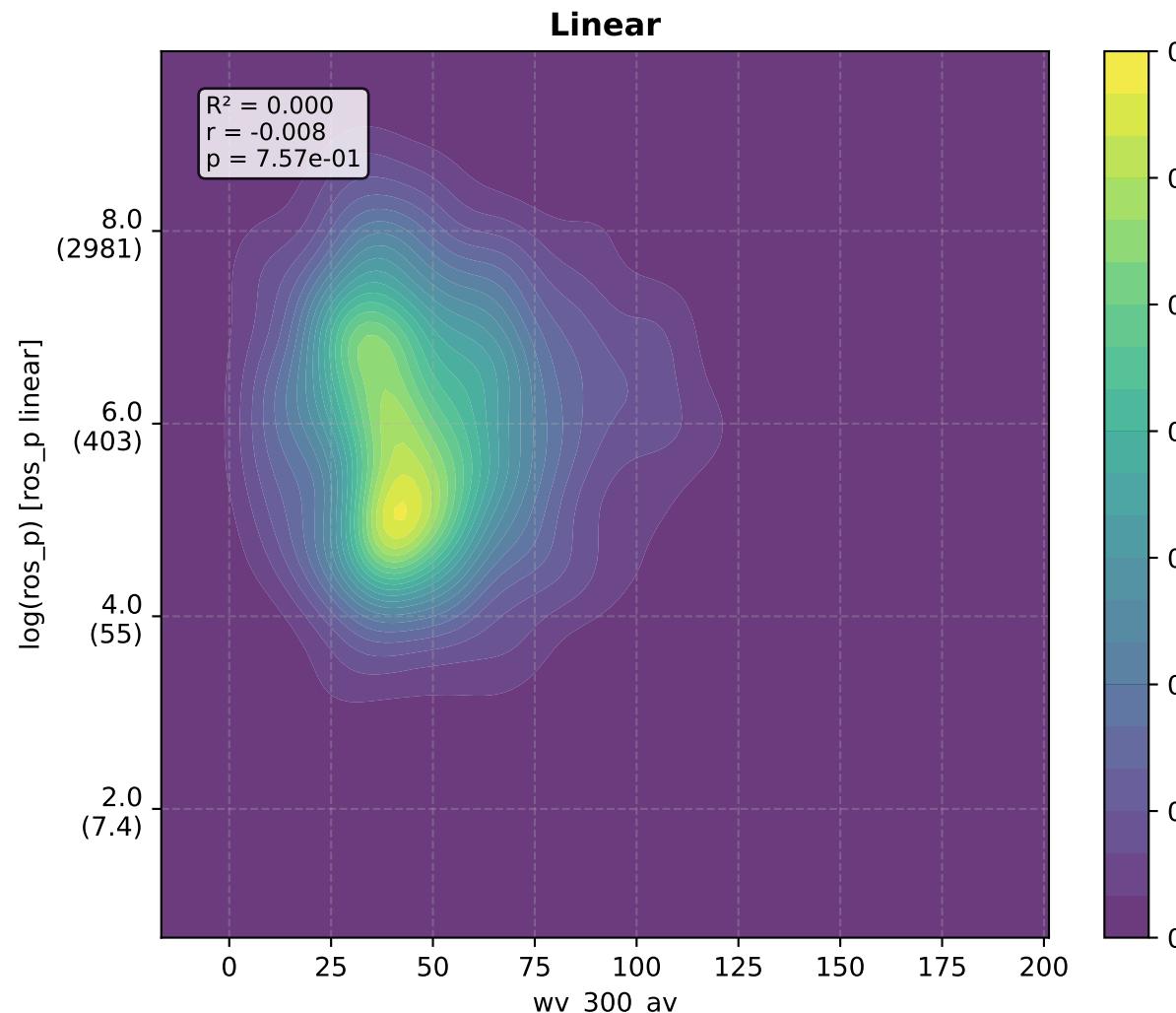
wv_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



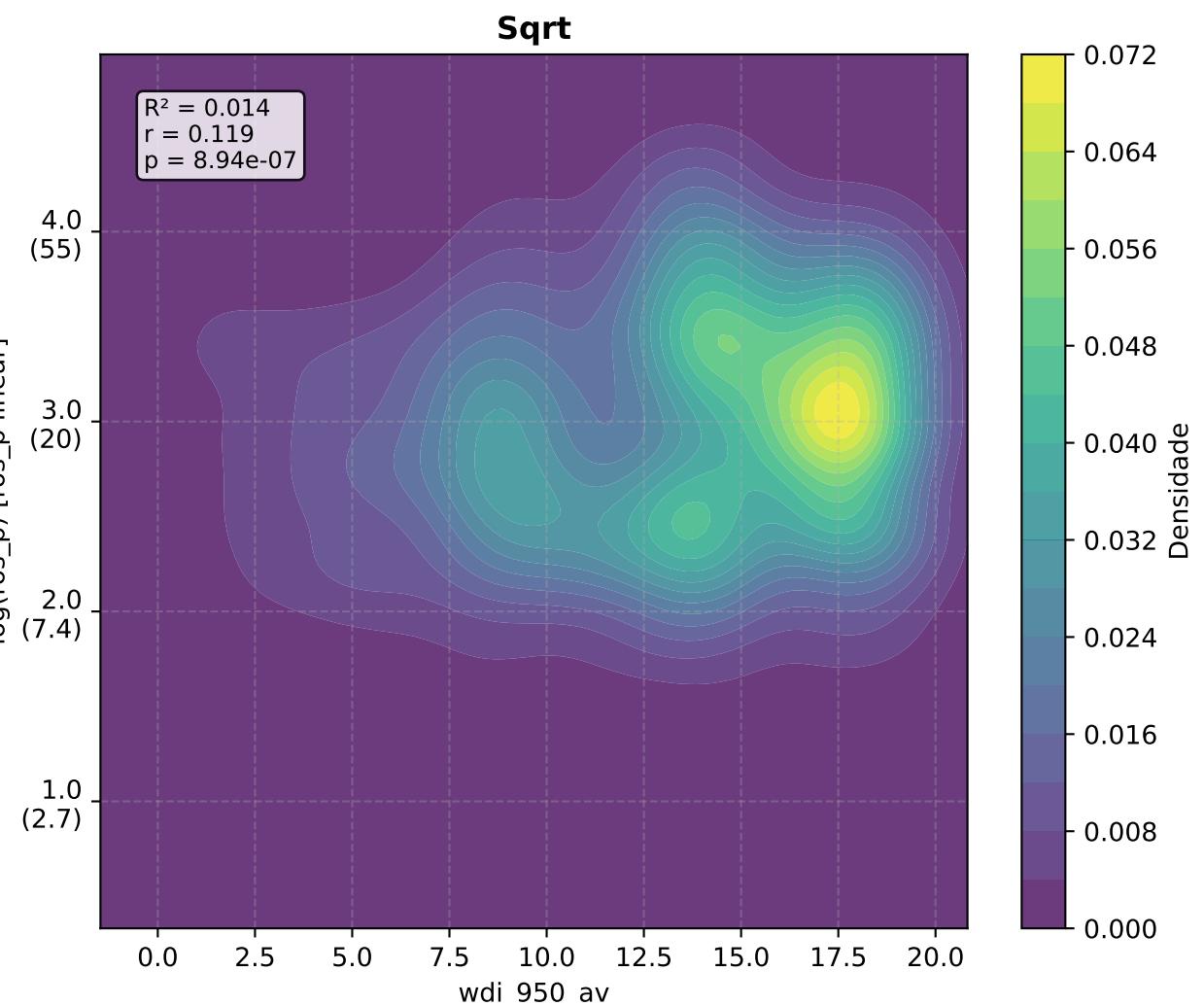
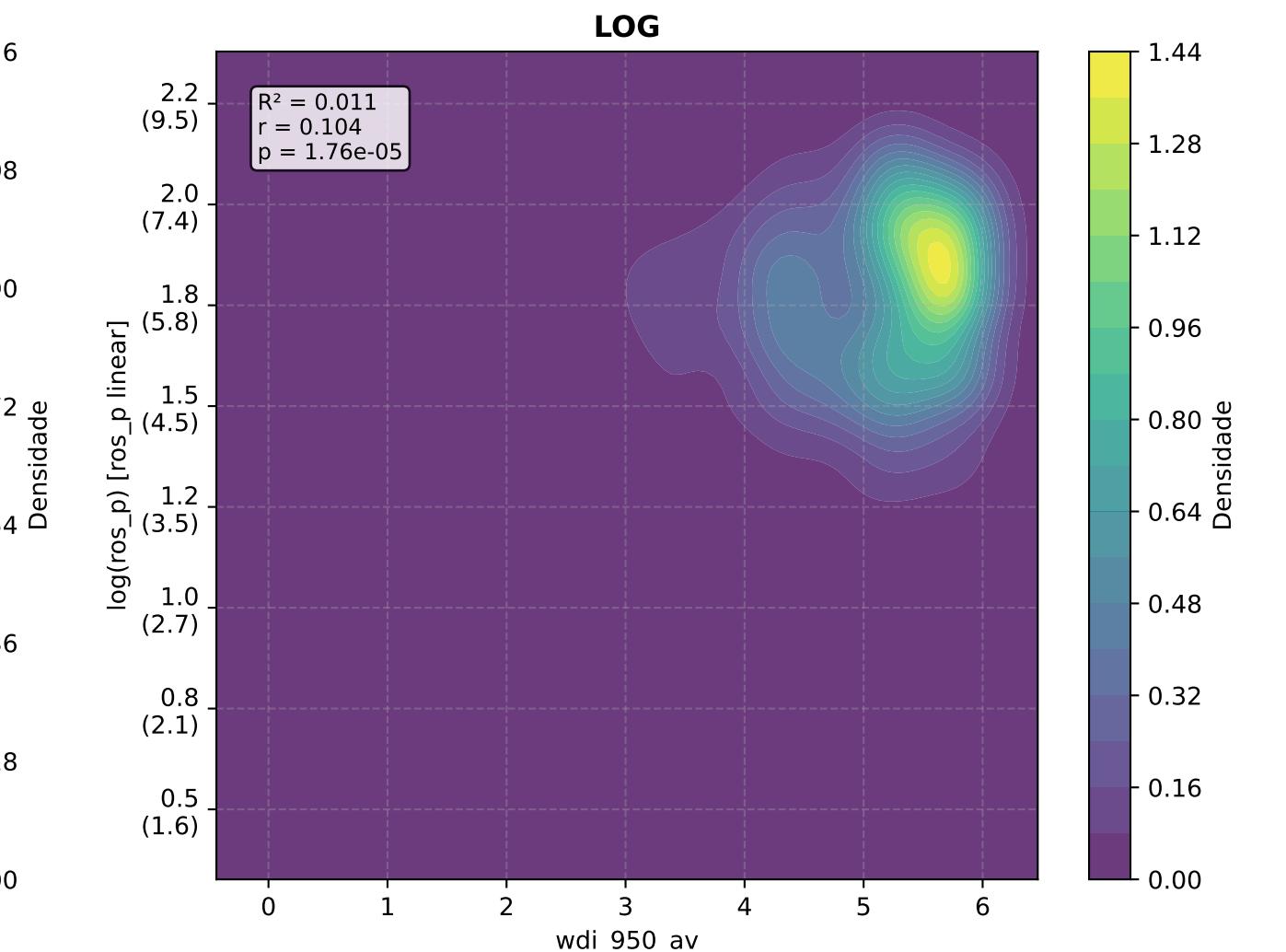
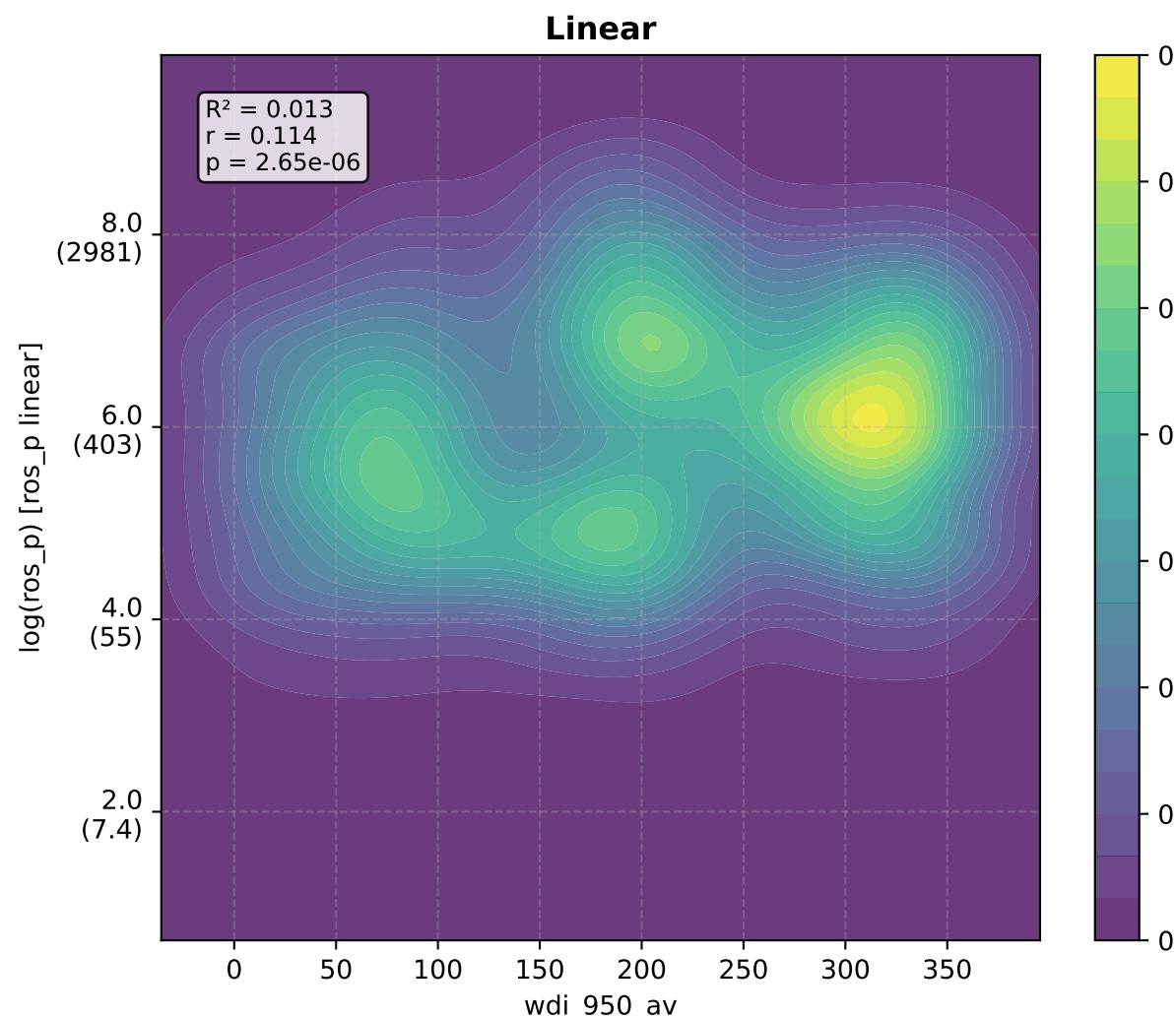
wv_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



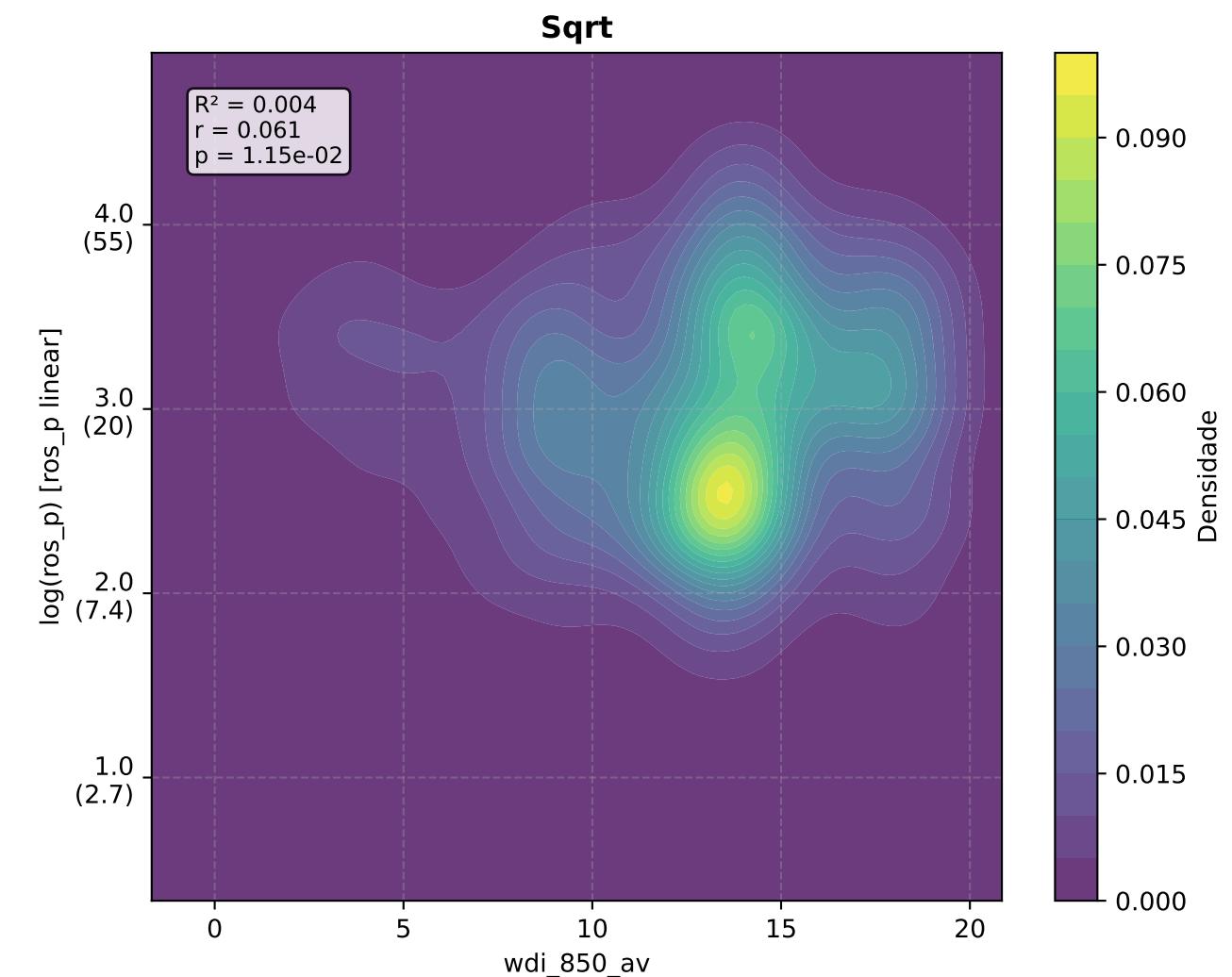
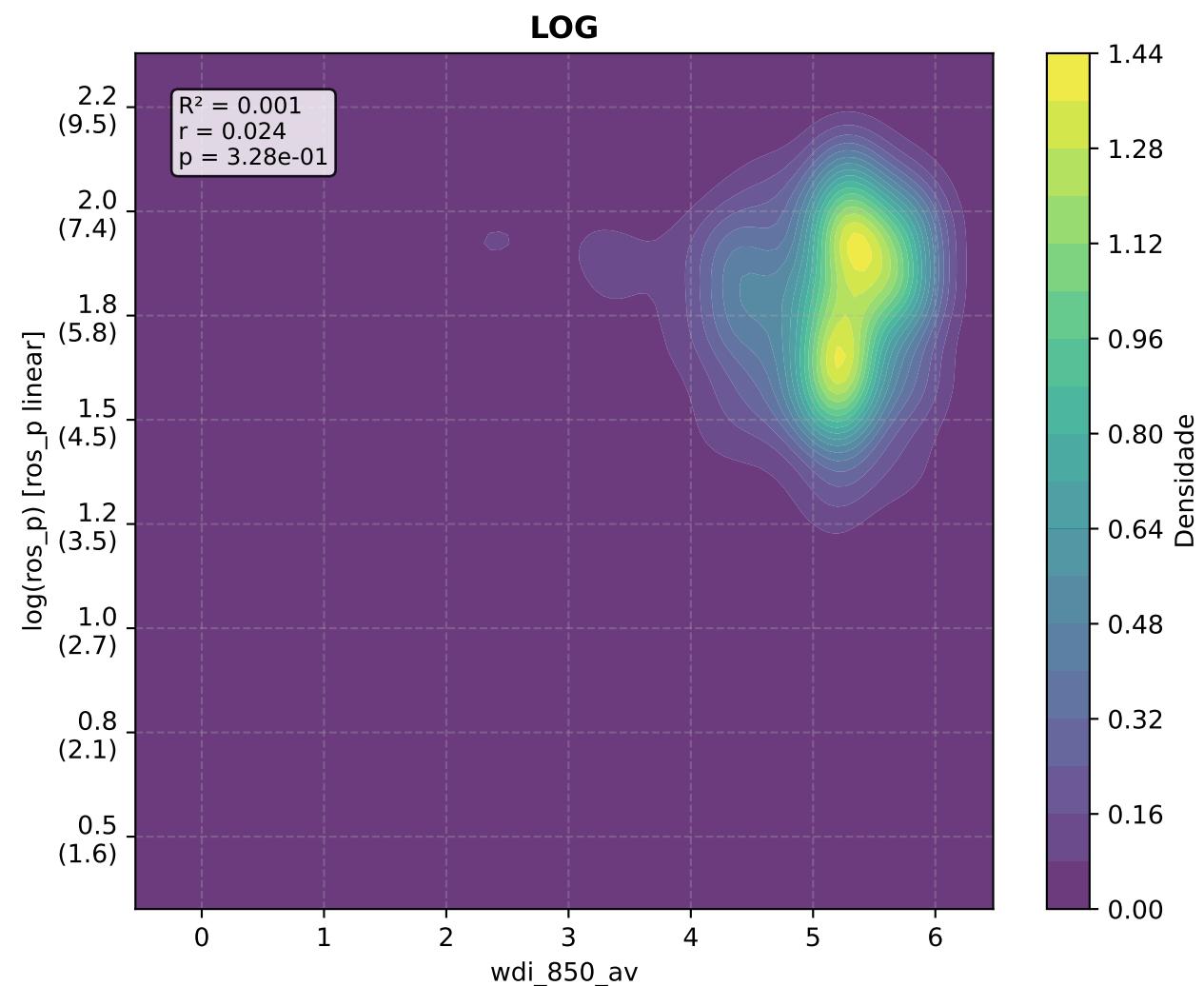
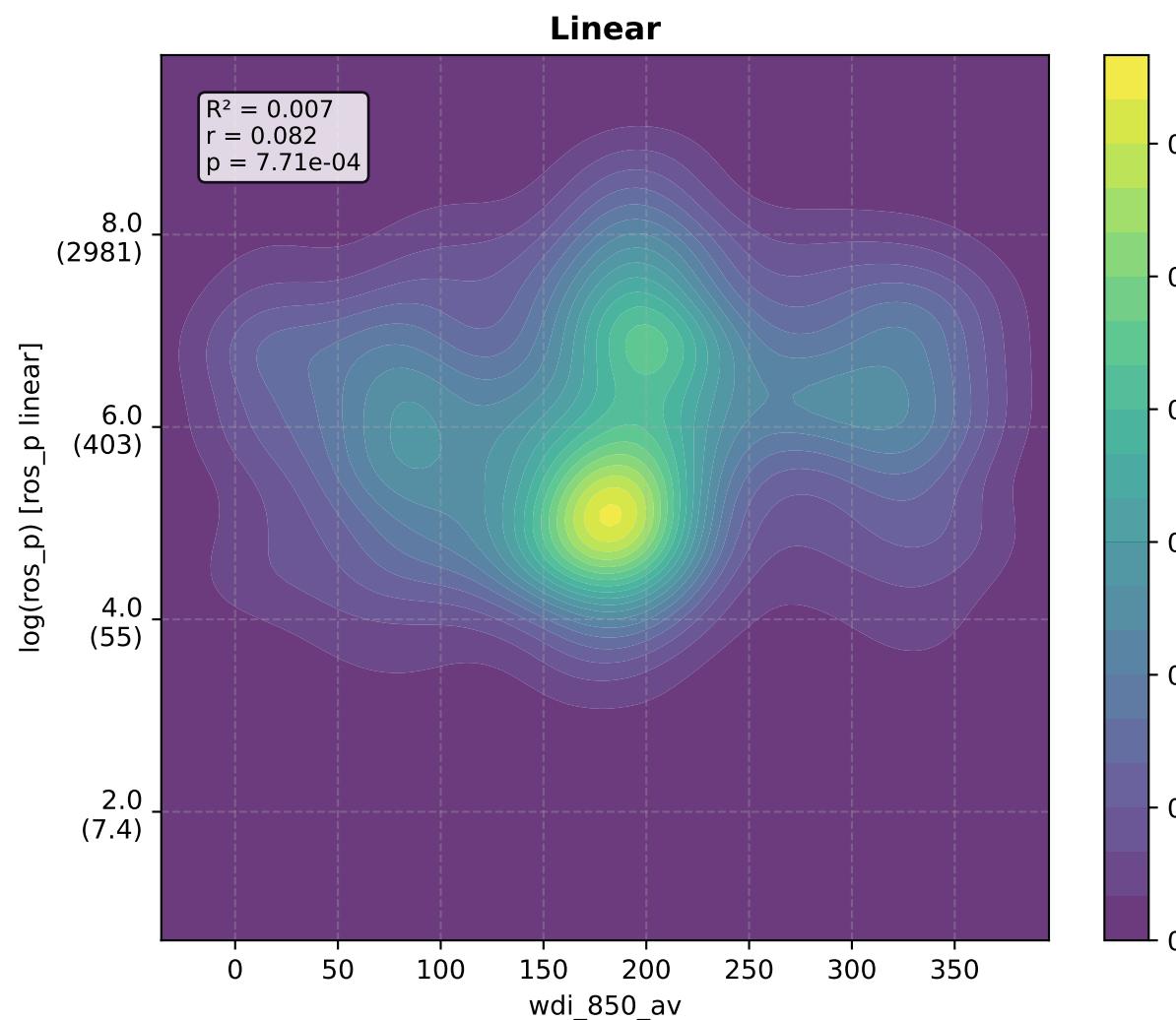
wv_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



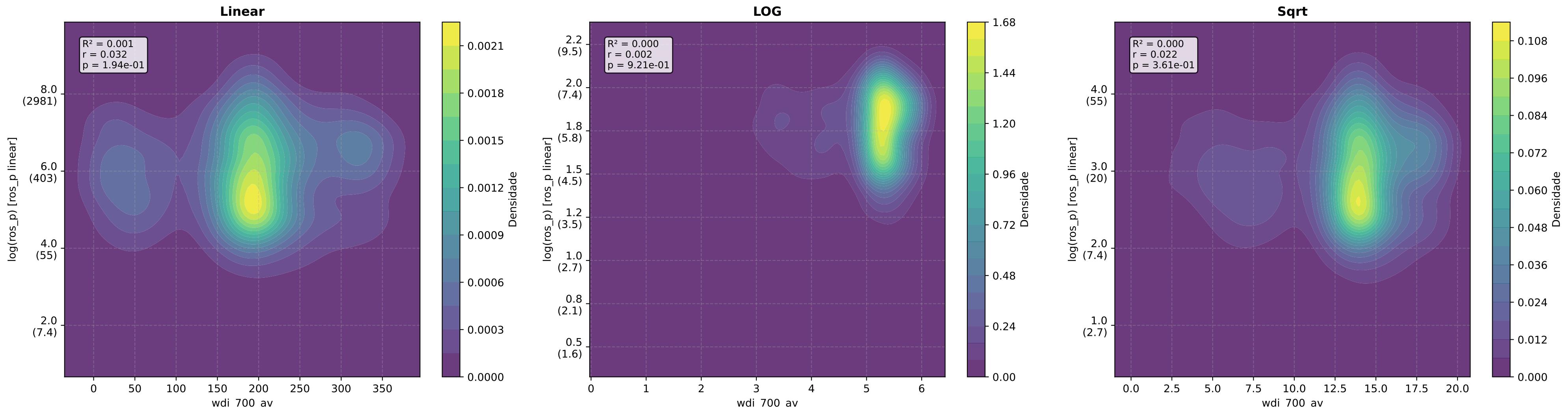
wdi_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



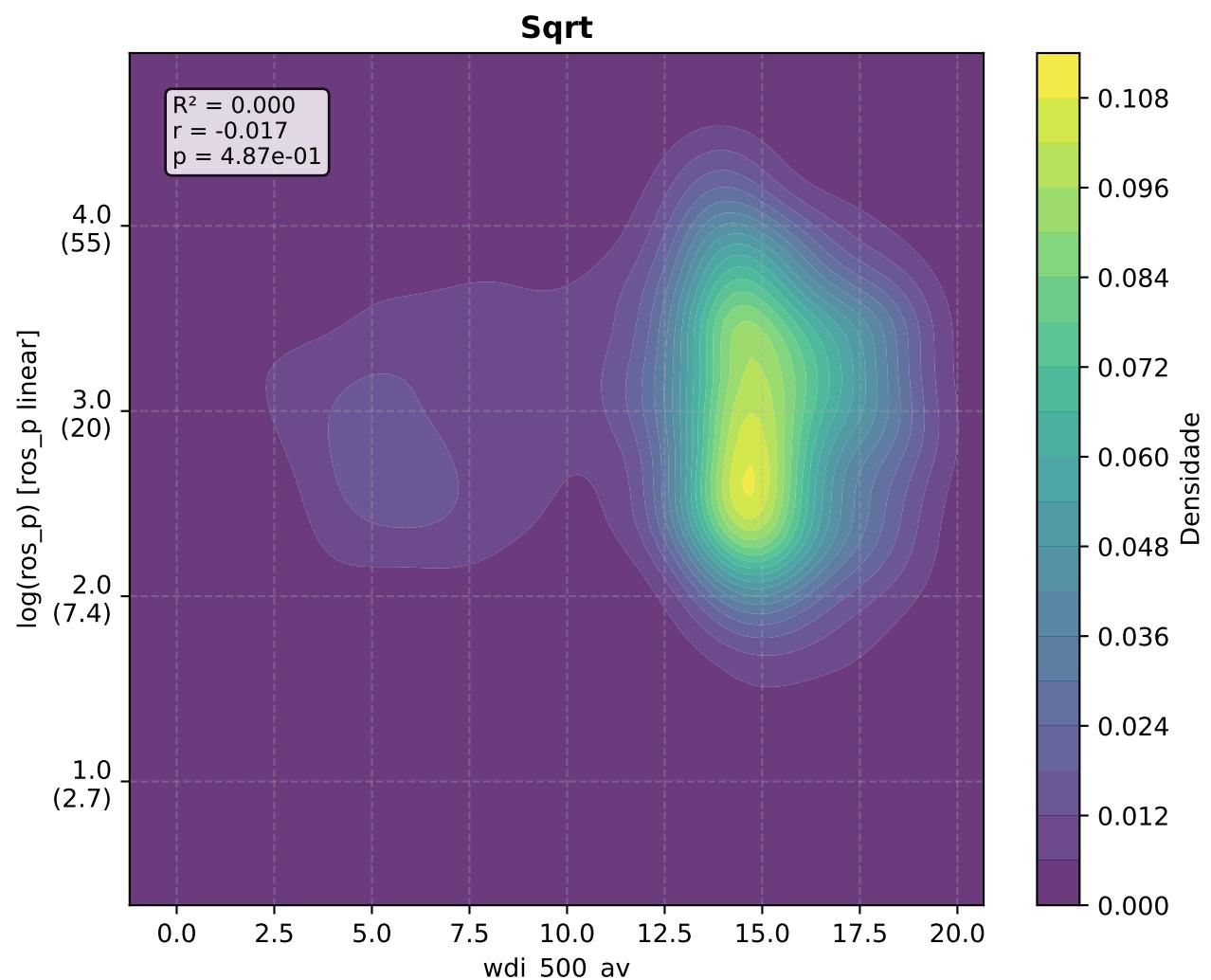
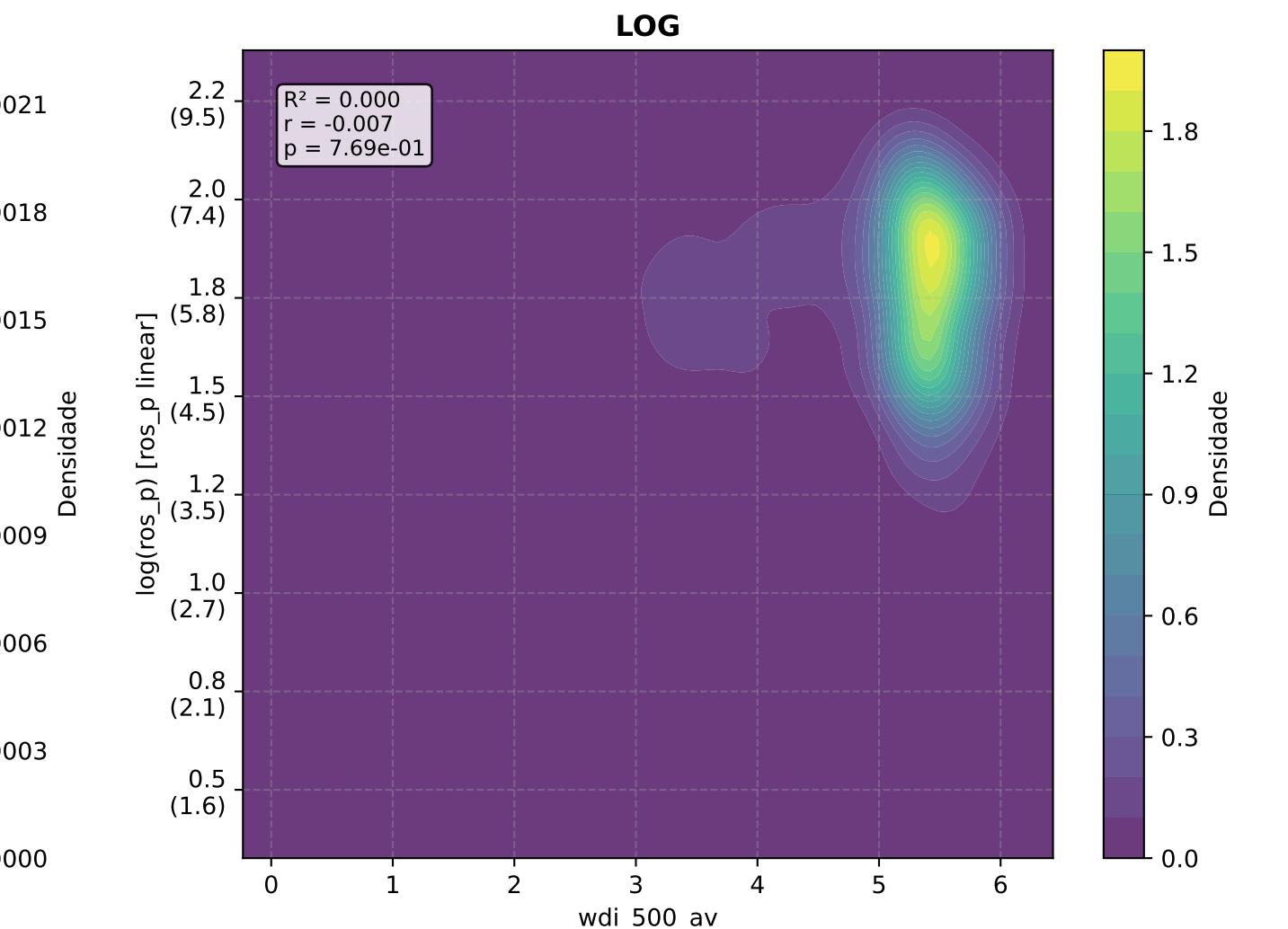
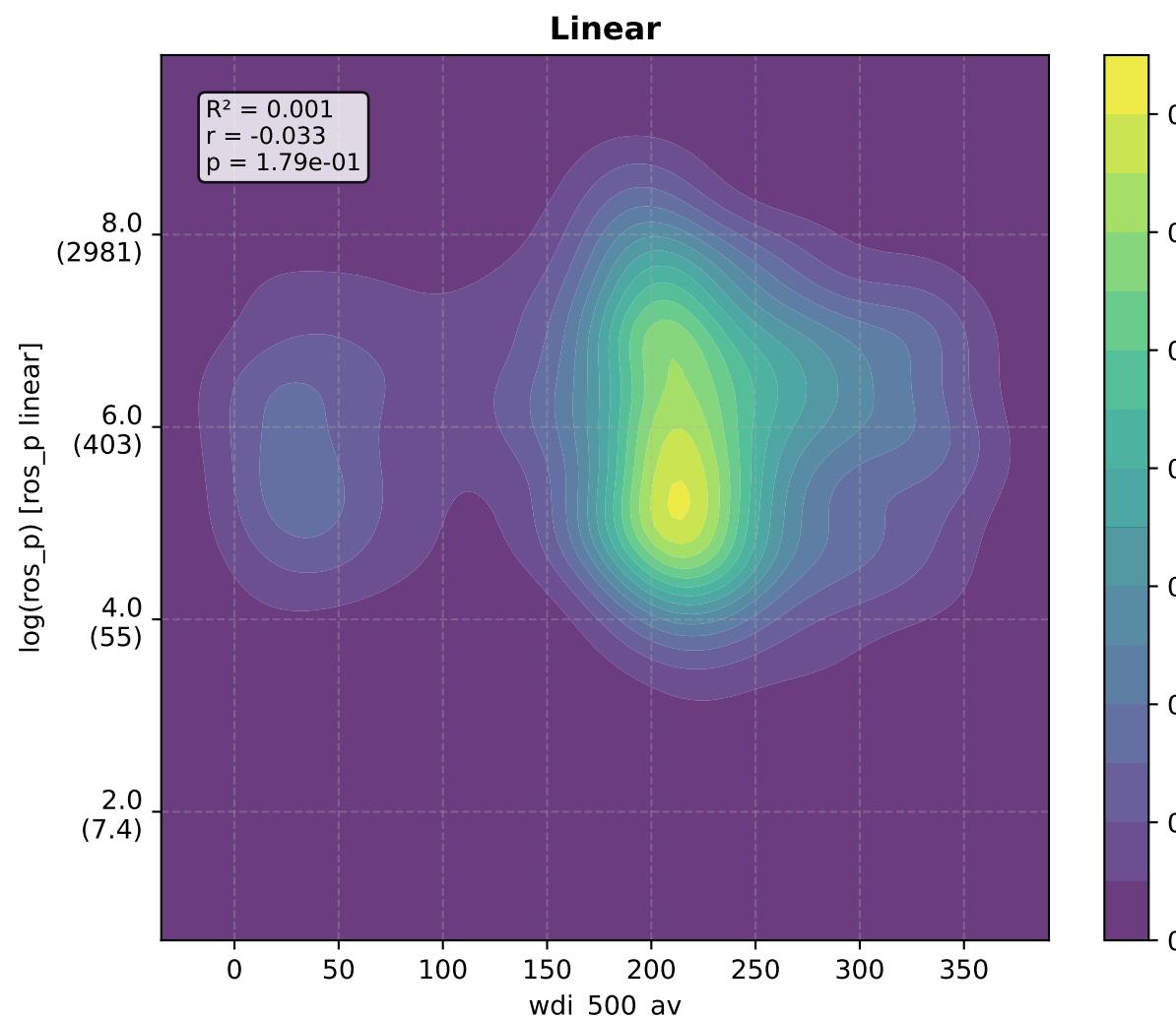
wdi_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



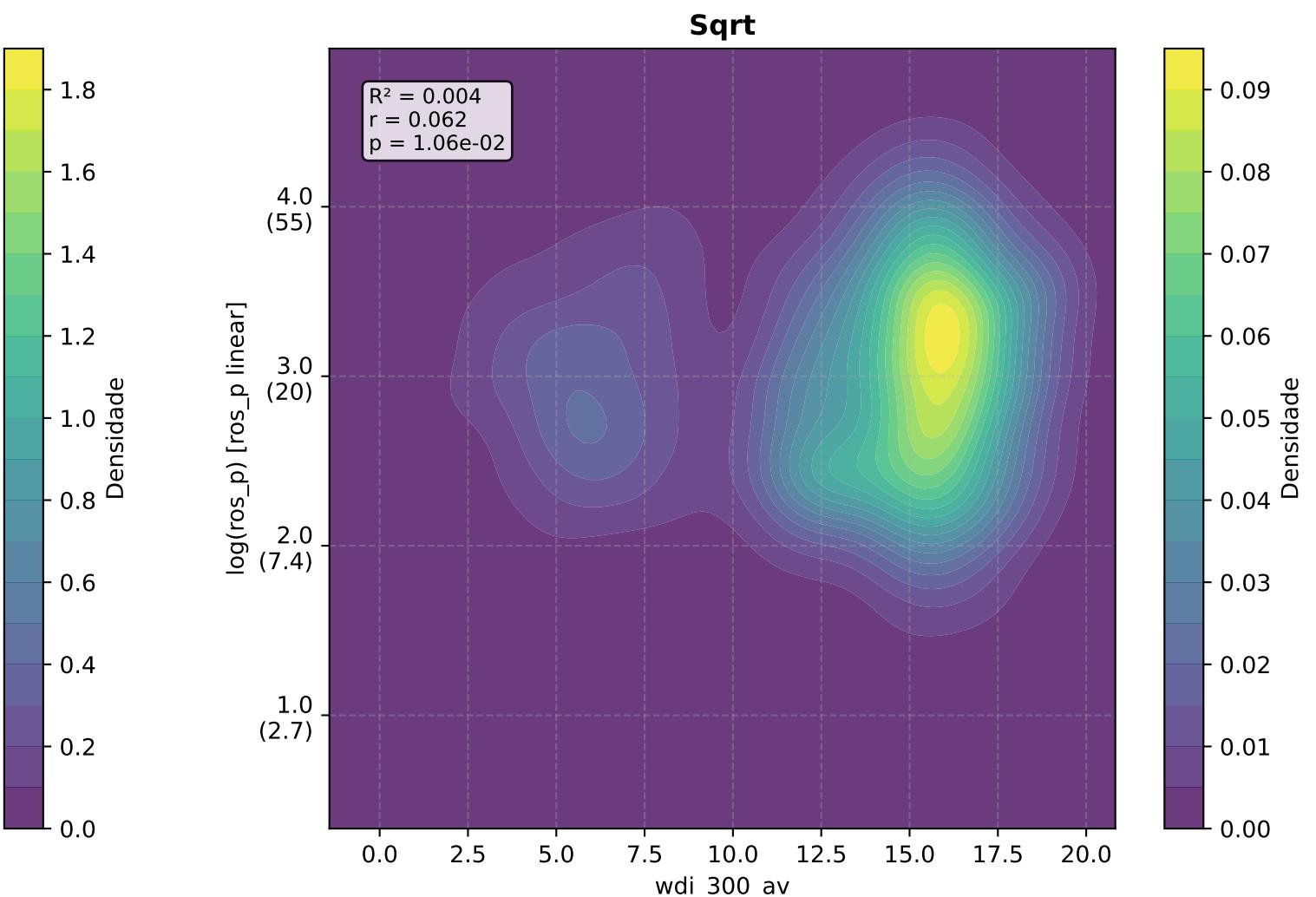
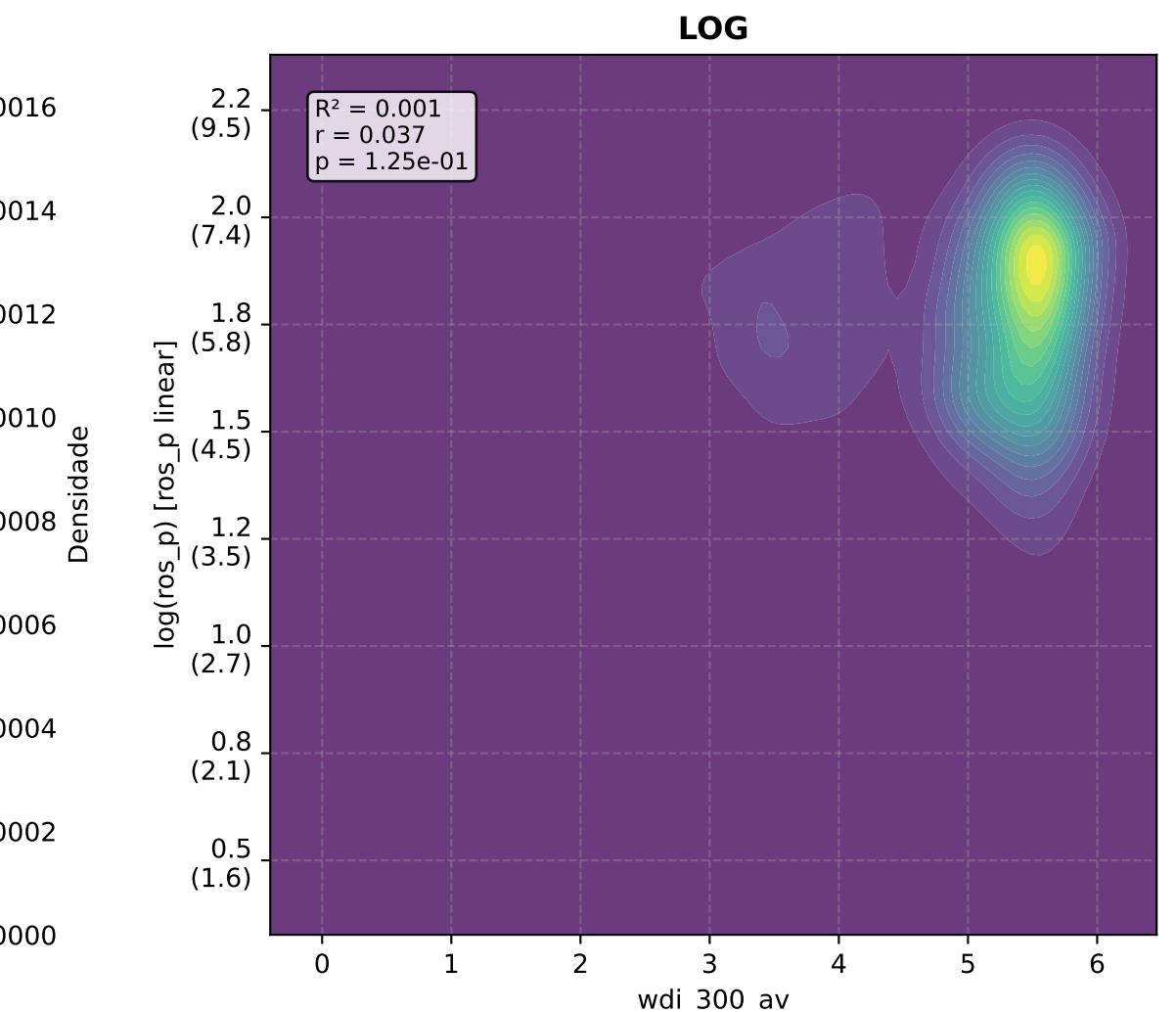
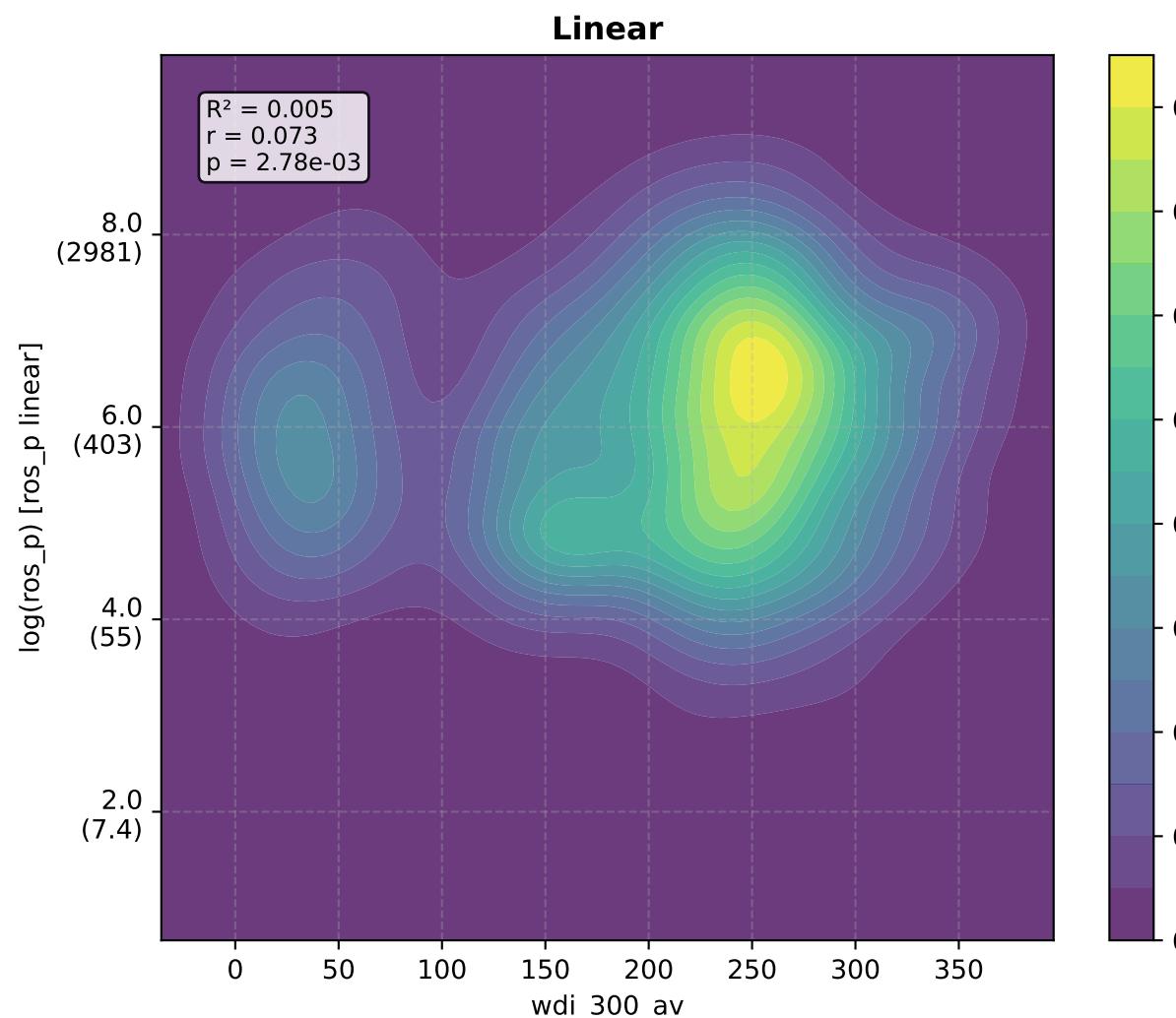
wdi_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



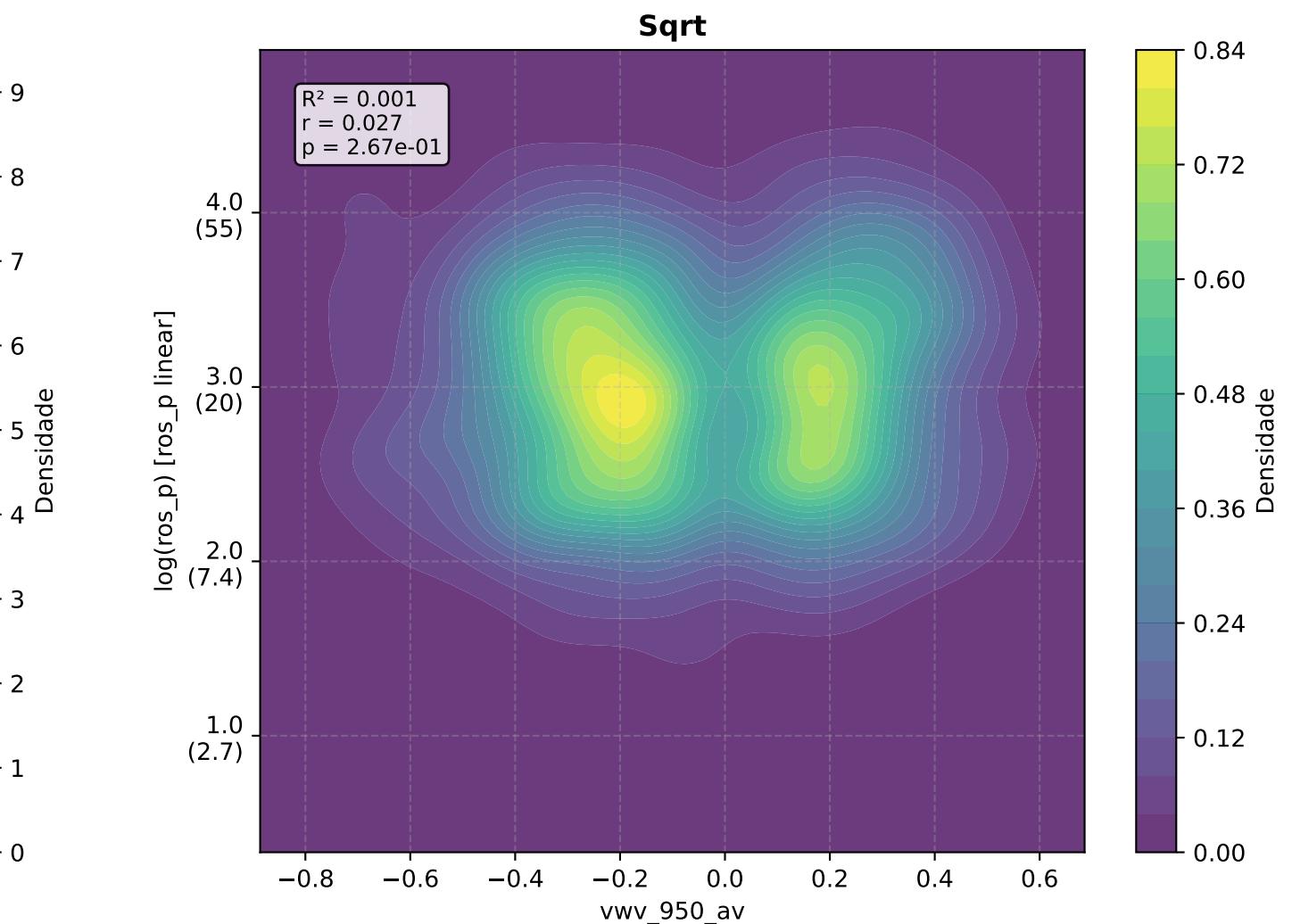
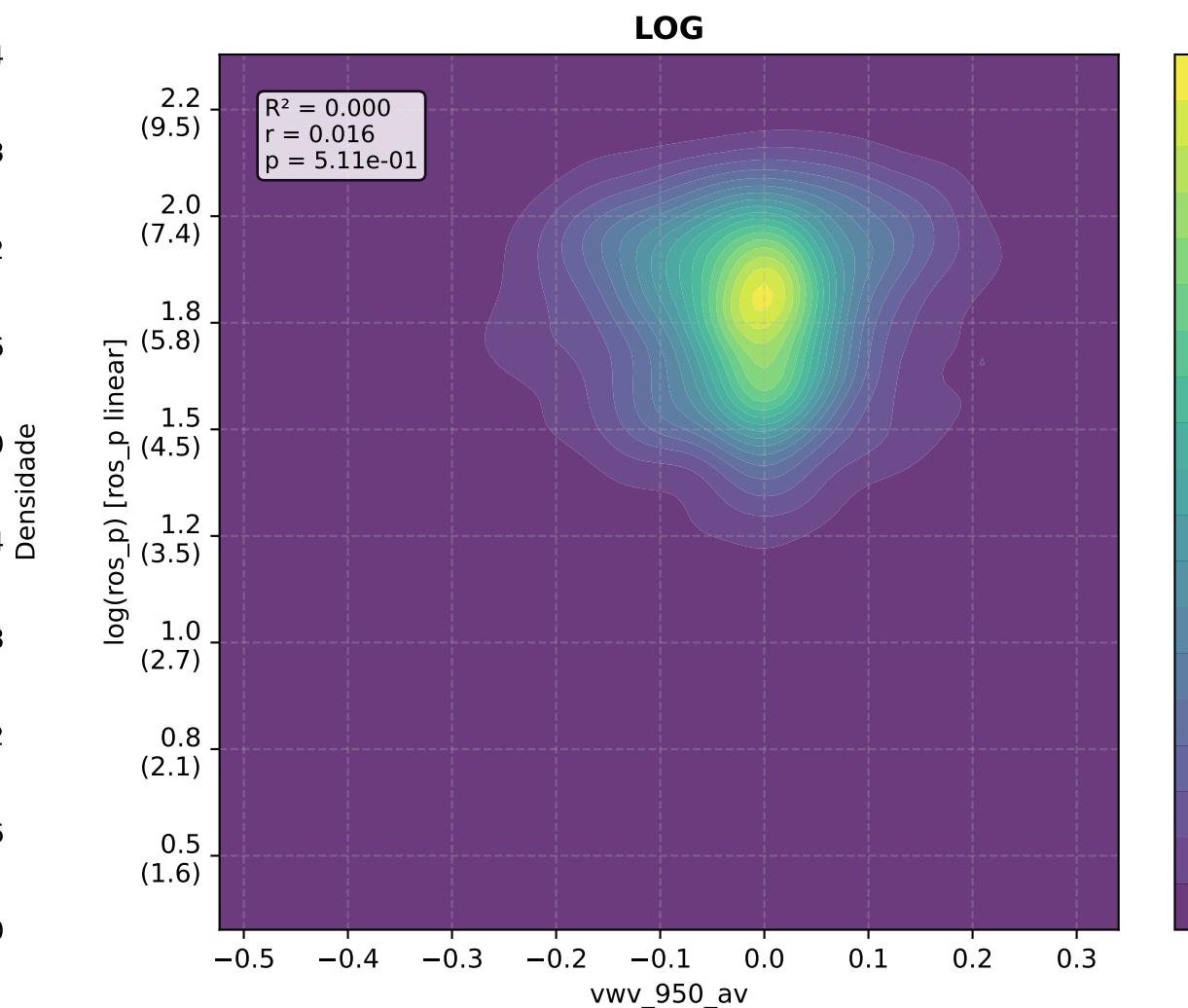
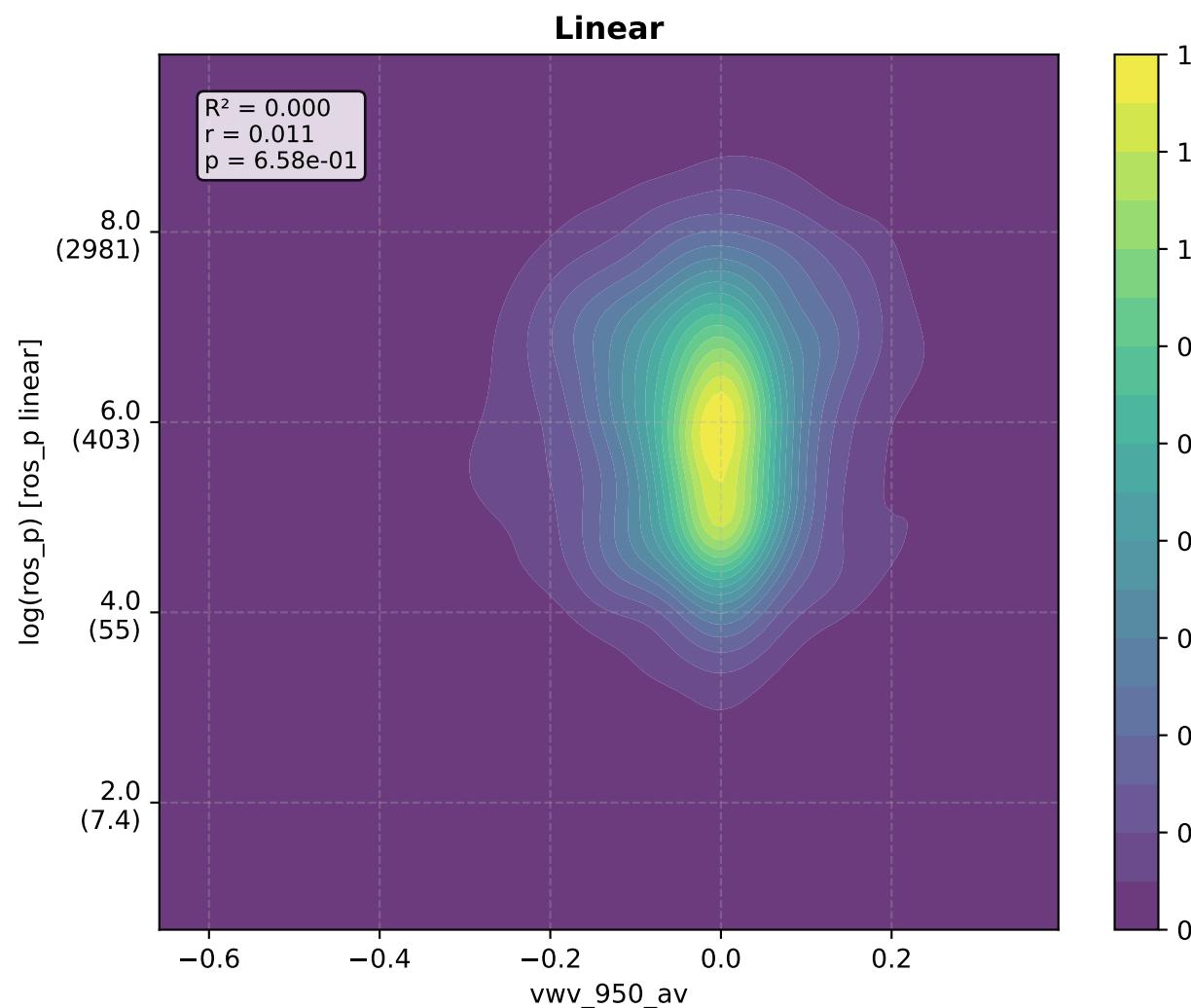
wdi_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



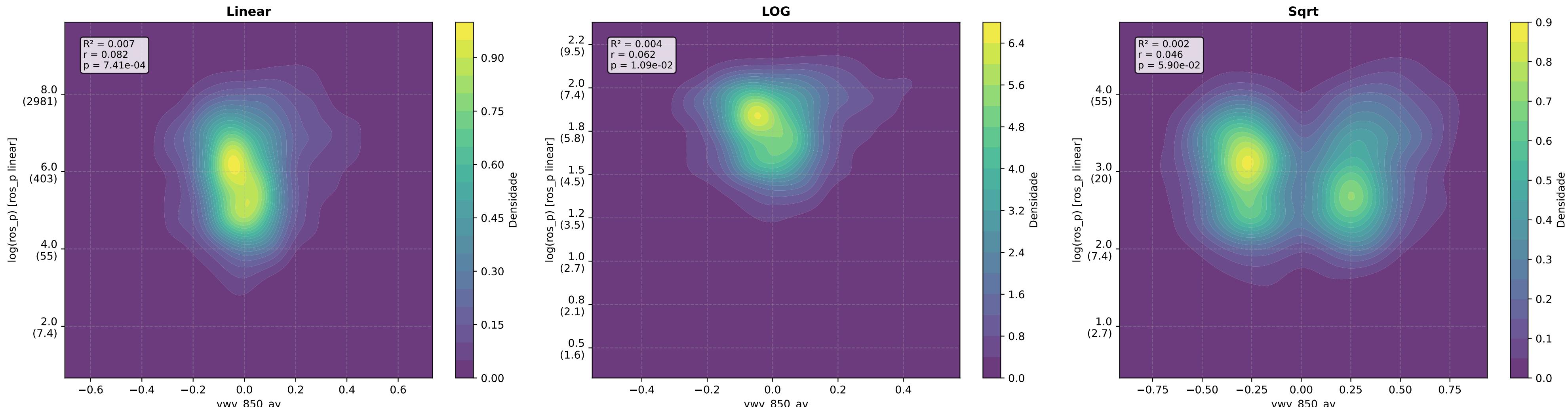
wdi_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



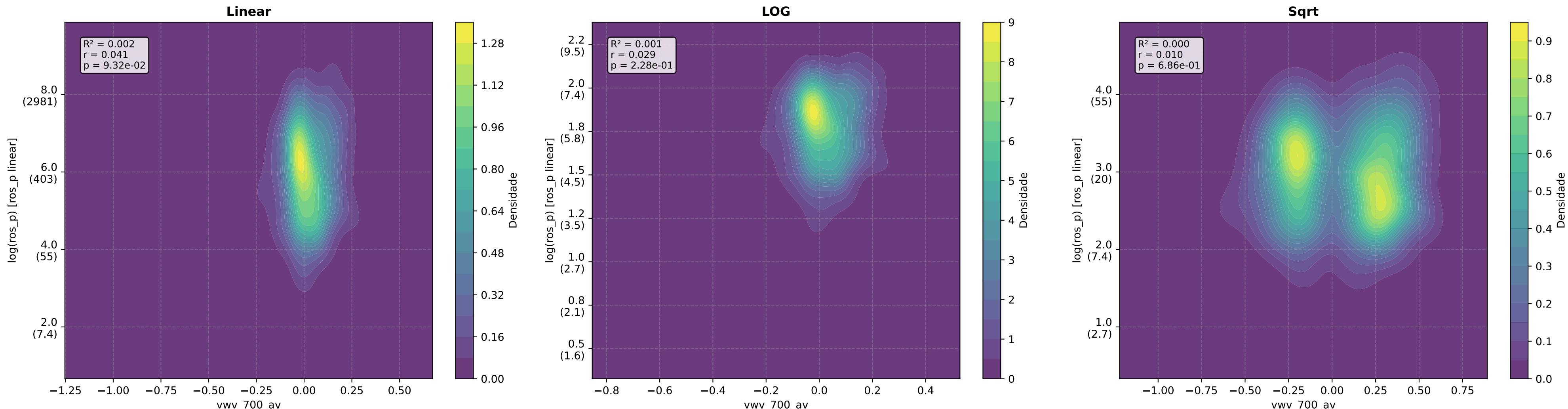
vwv_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



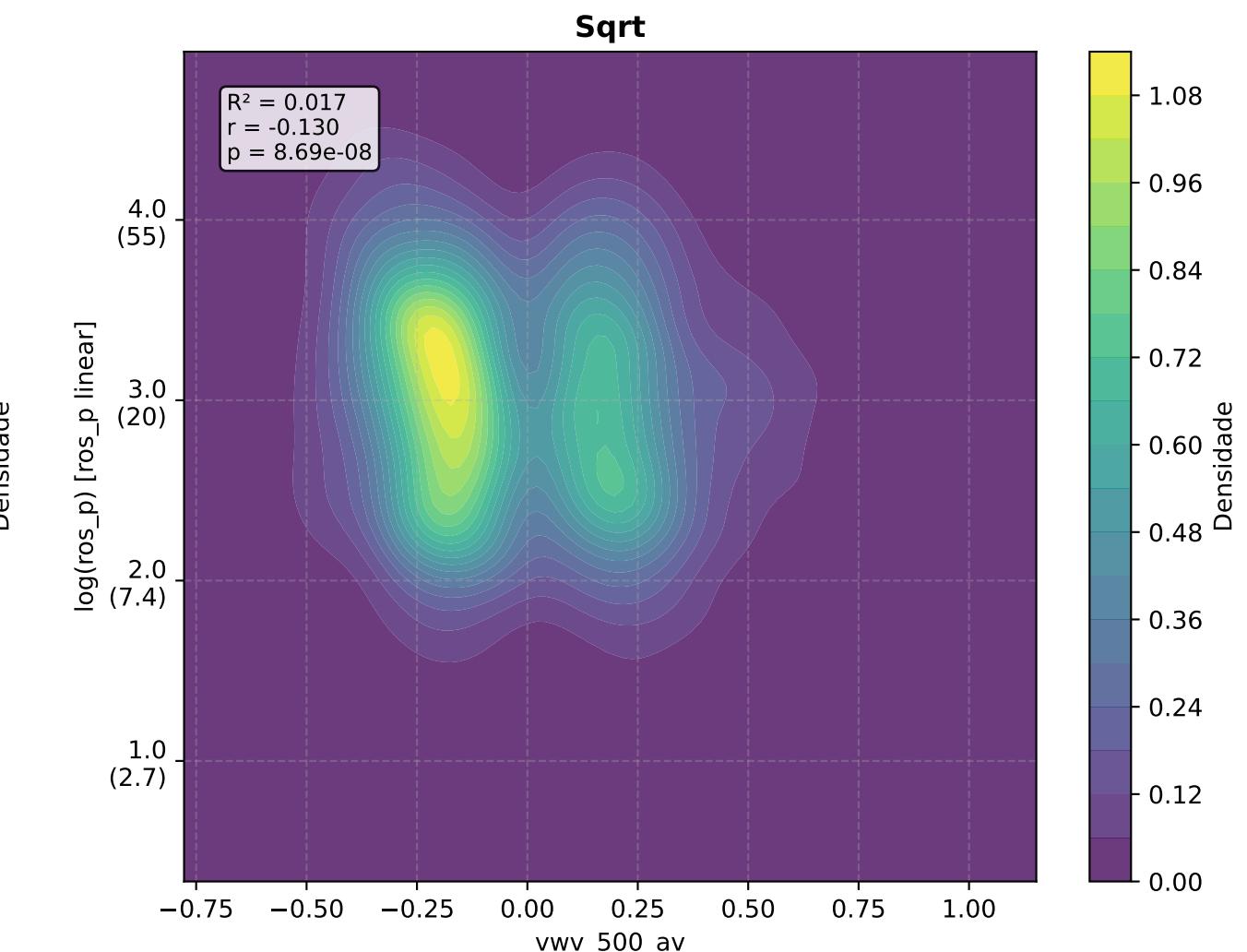
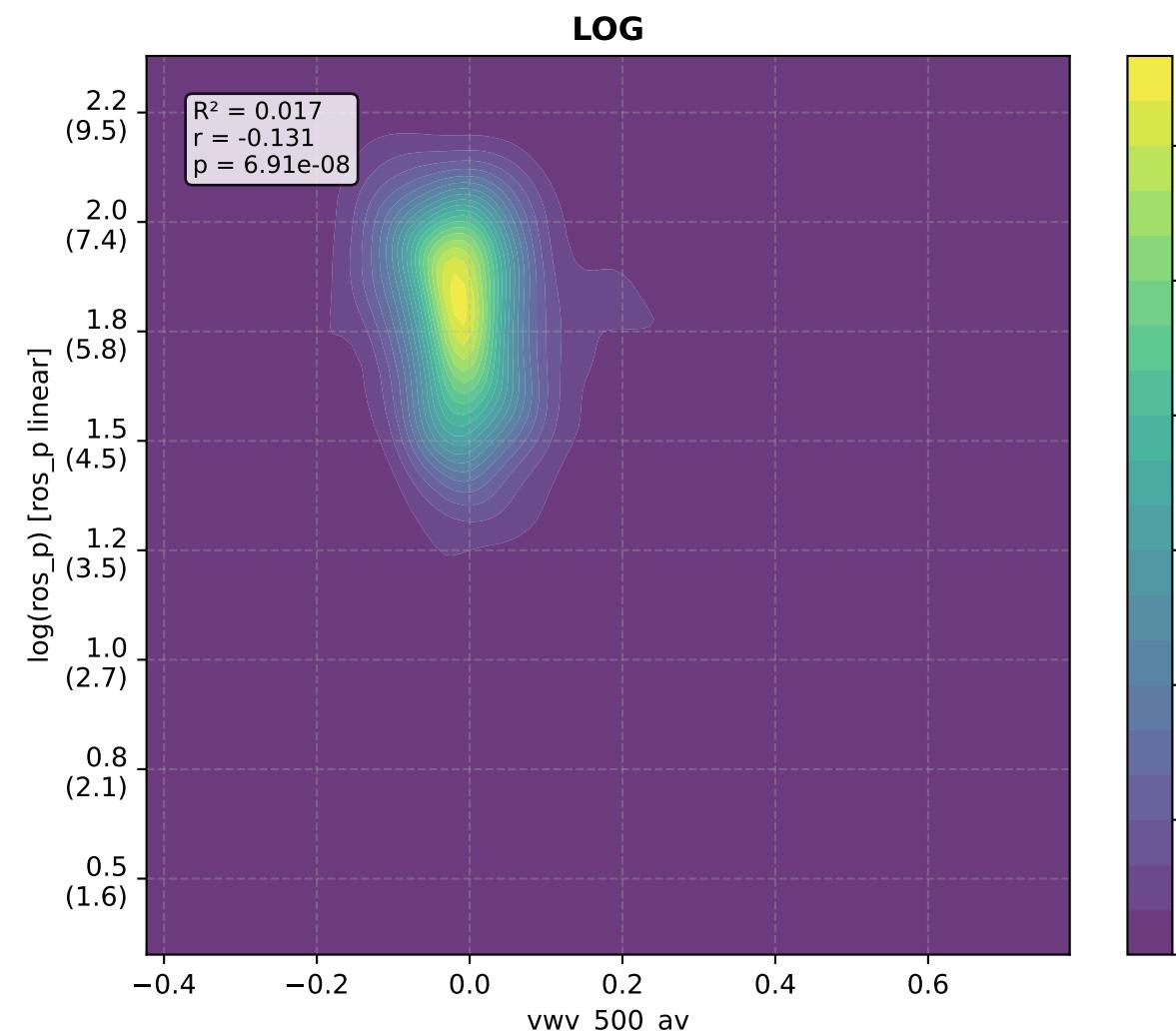
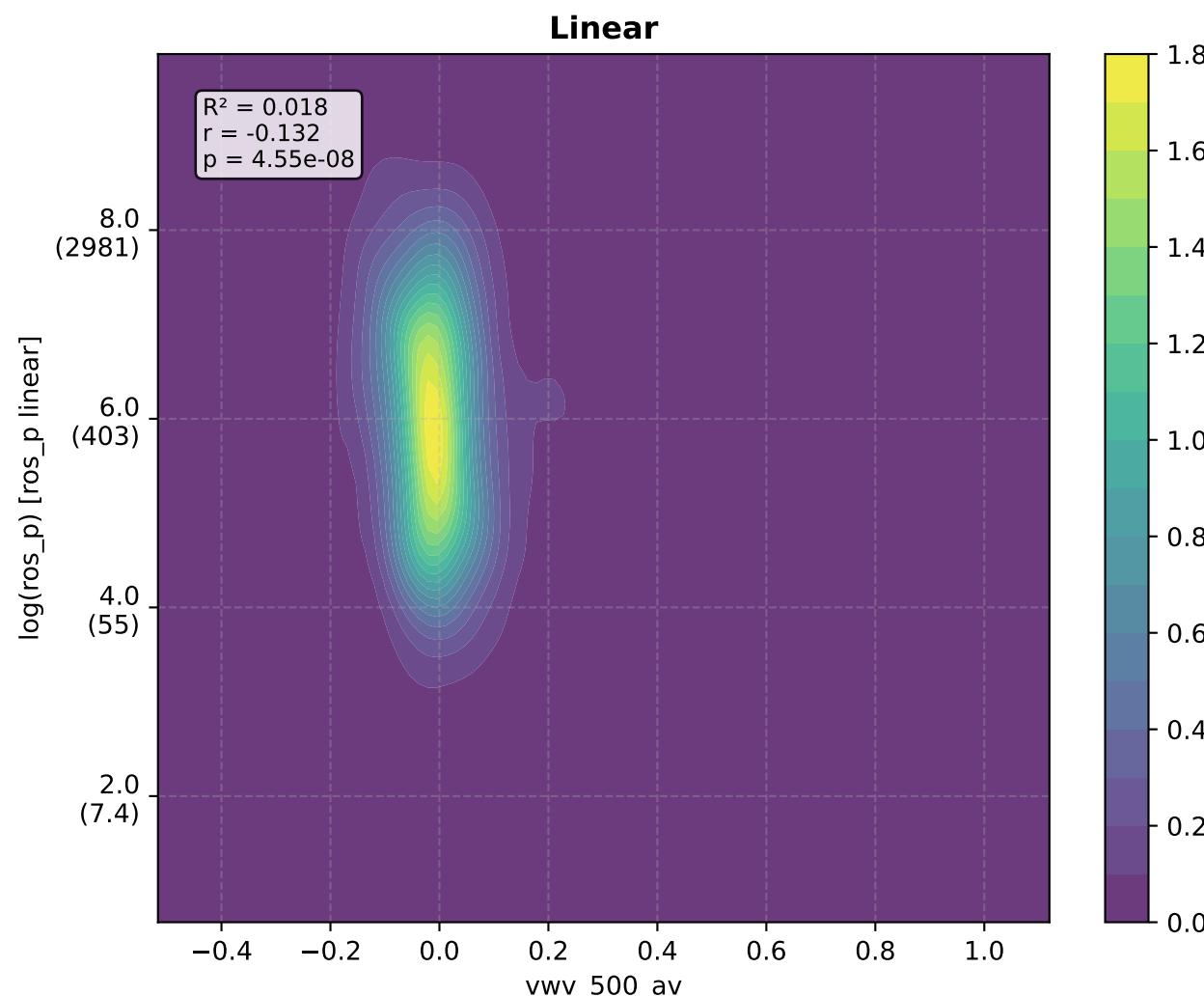
vwv_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



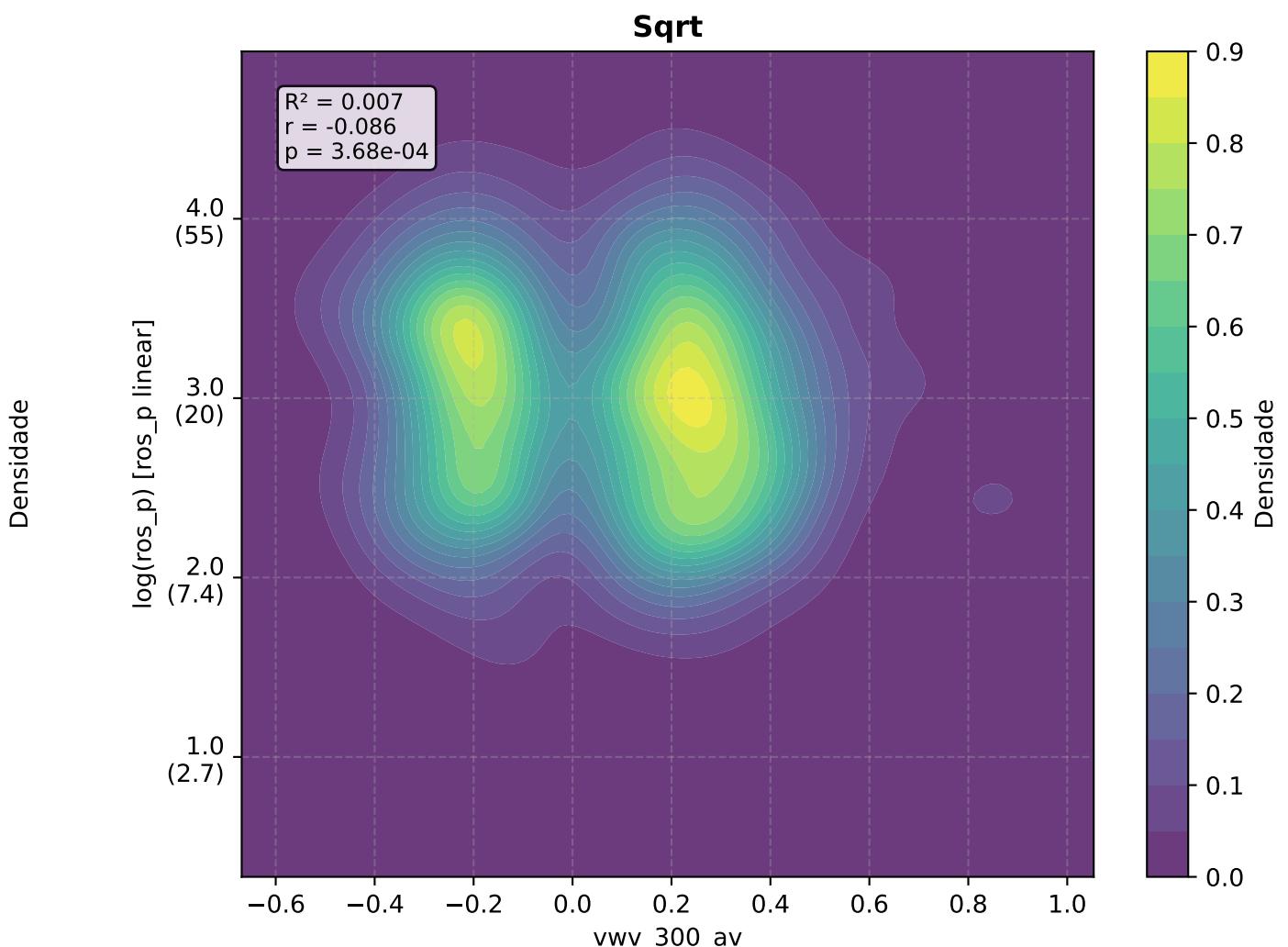
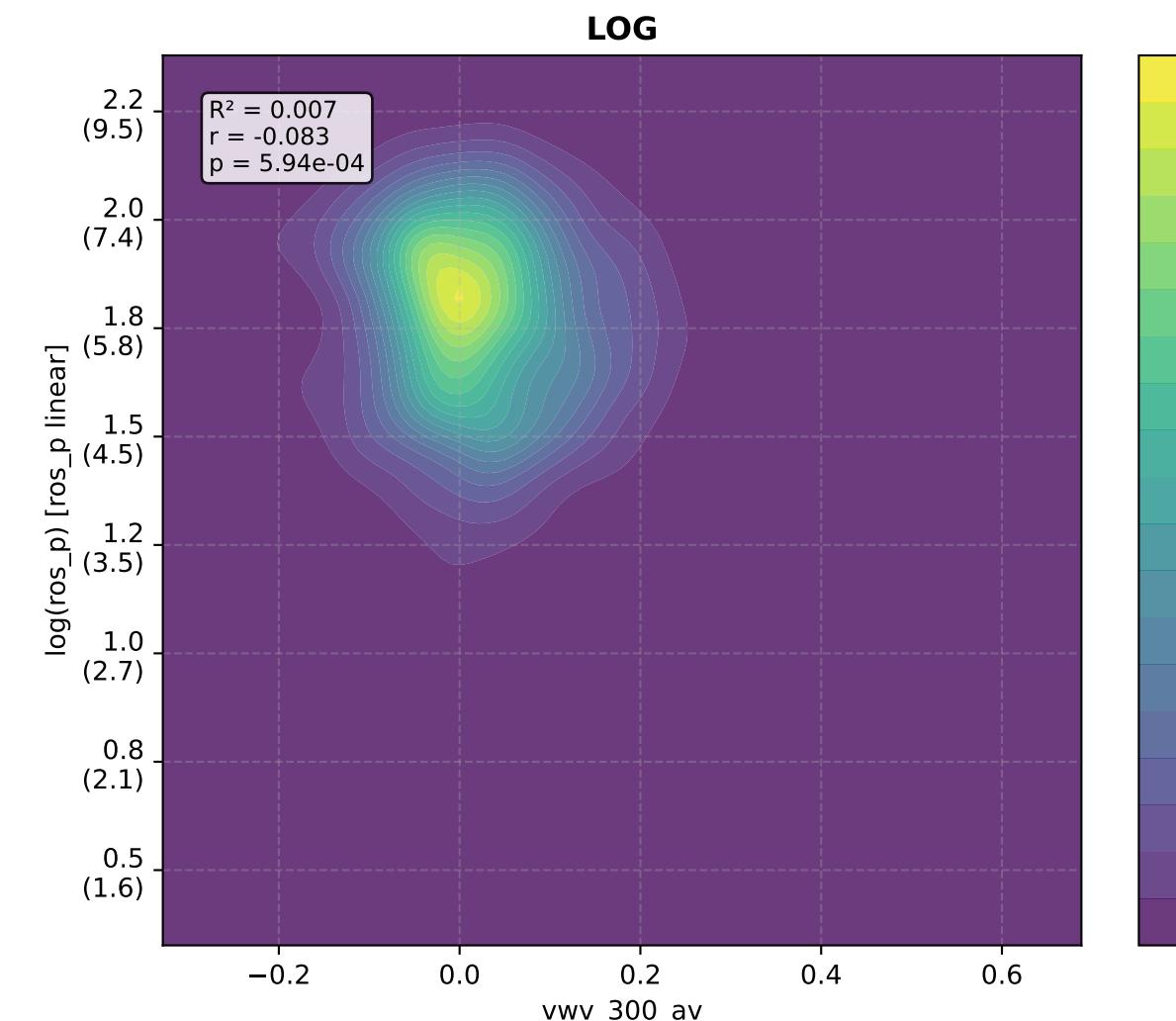
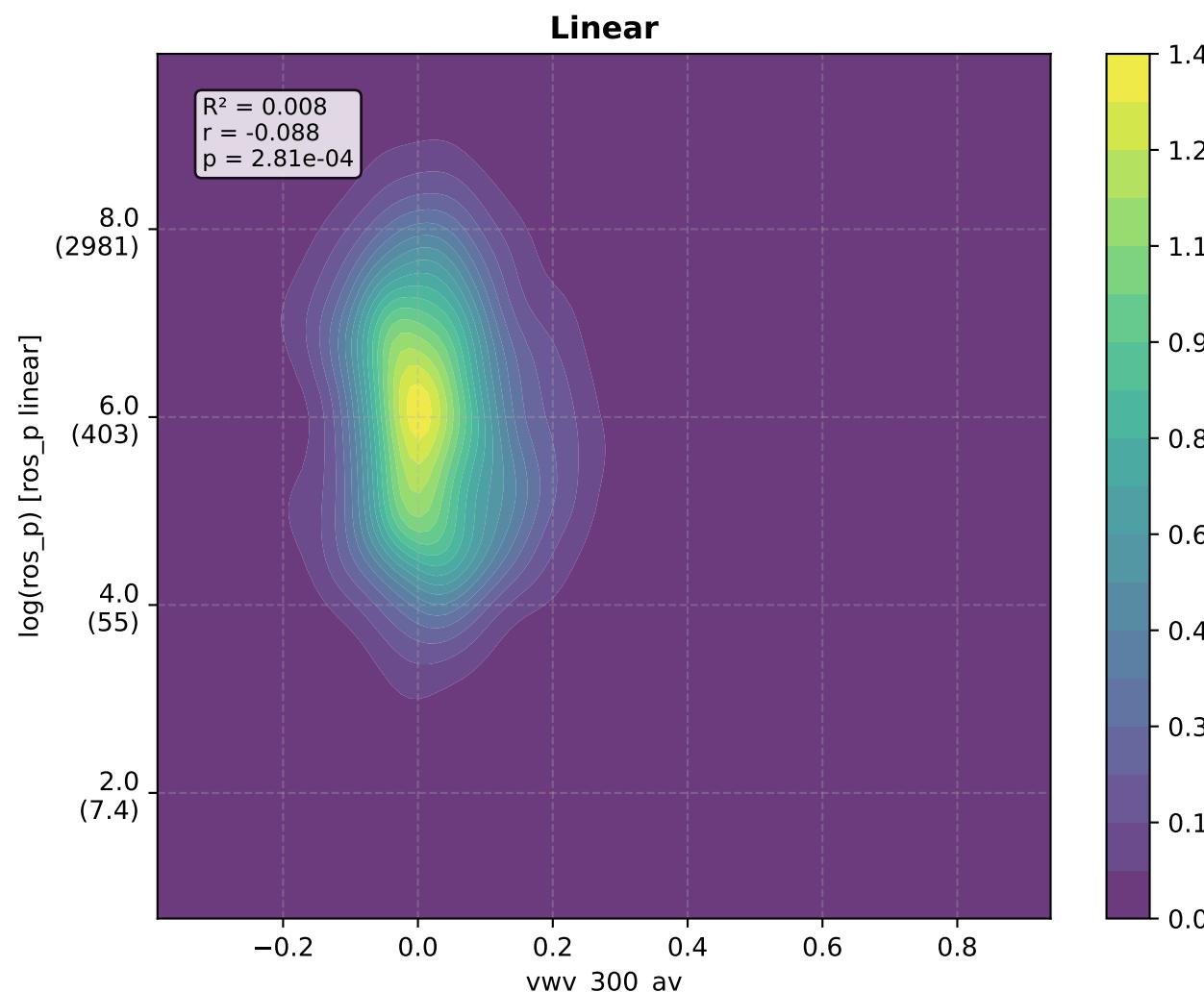
vwv_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



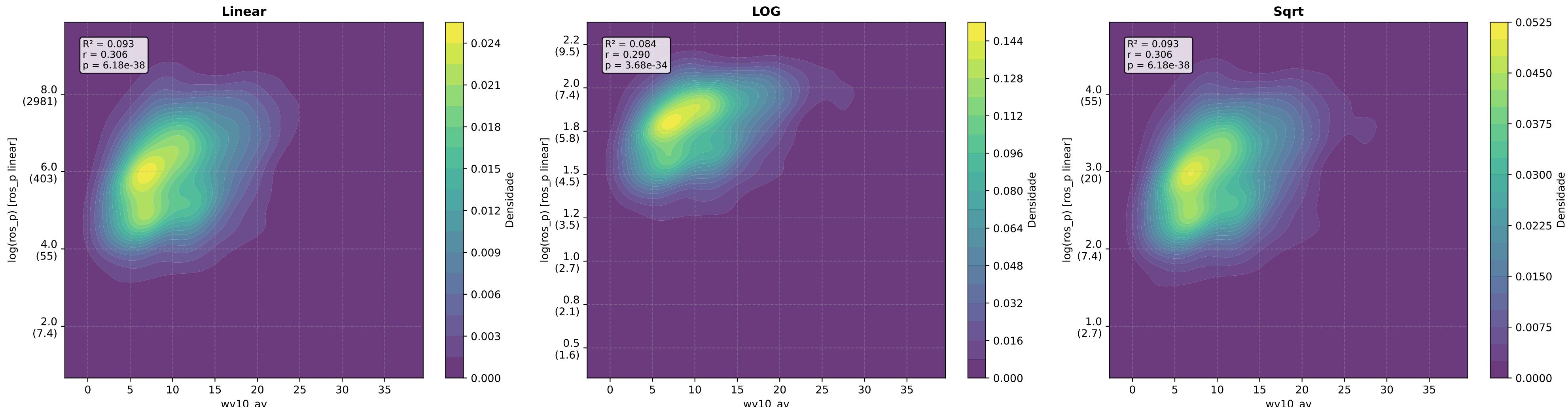
vwv_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



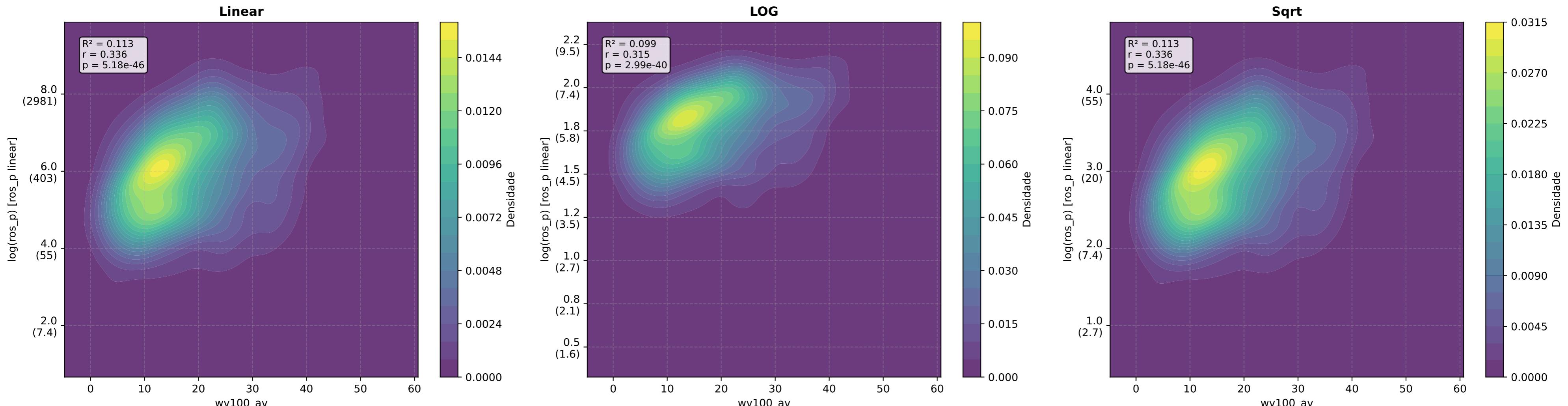
vwv_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



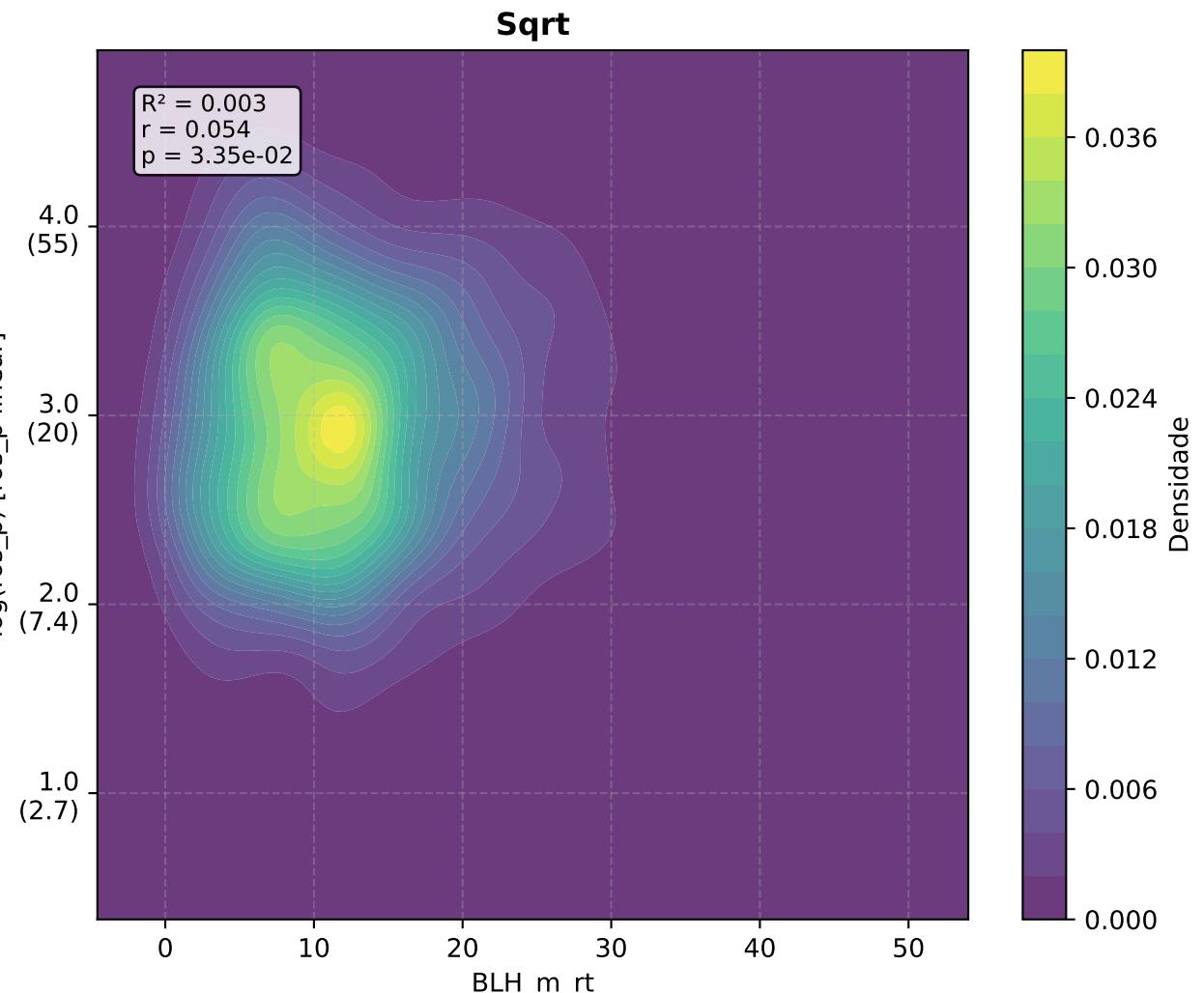
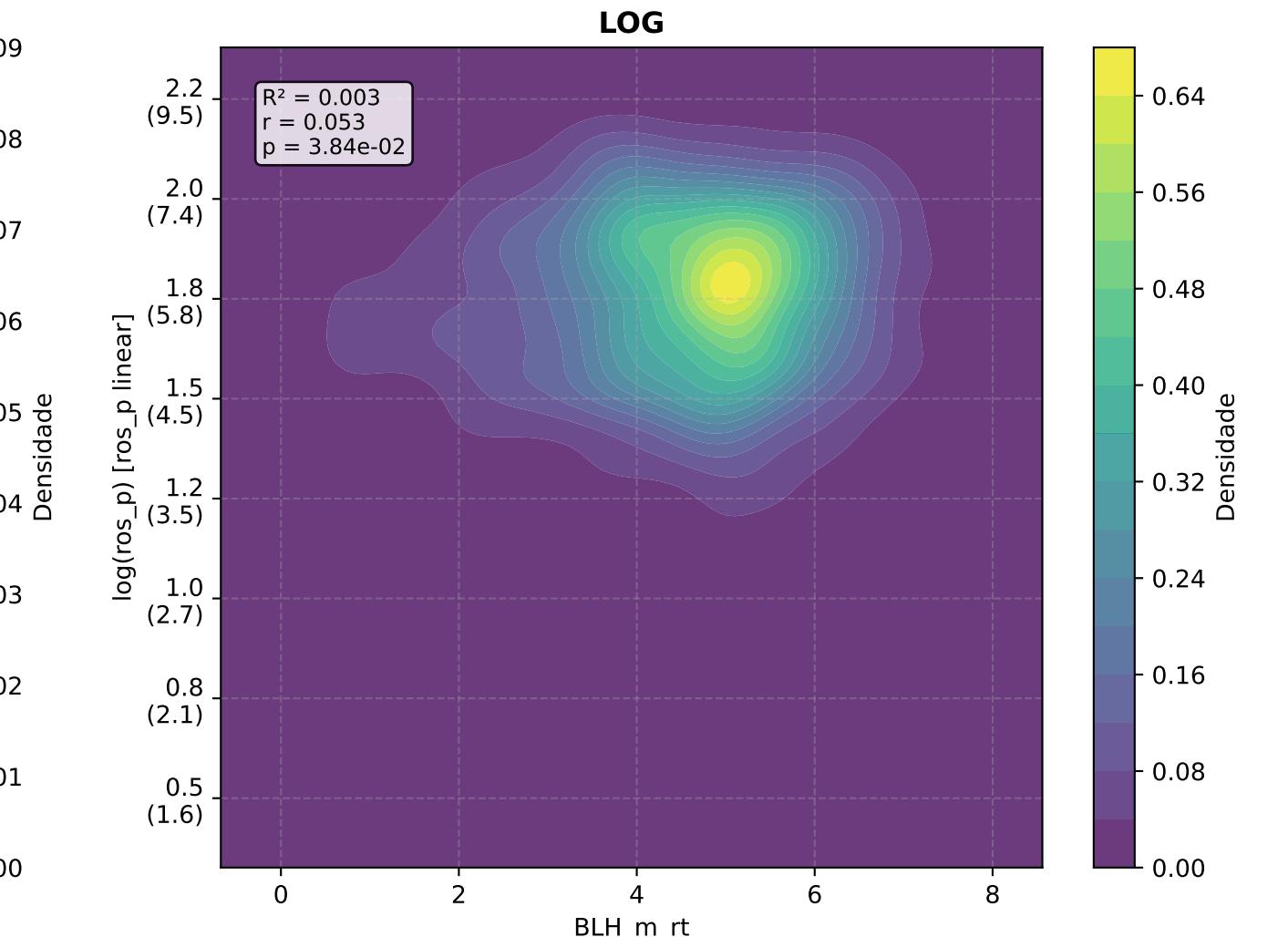
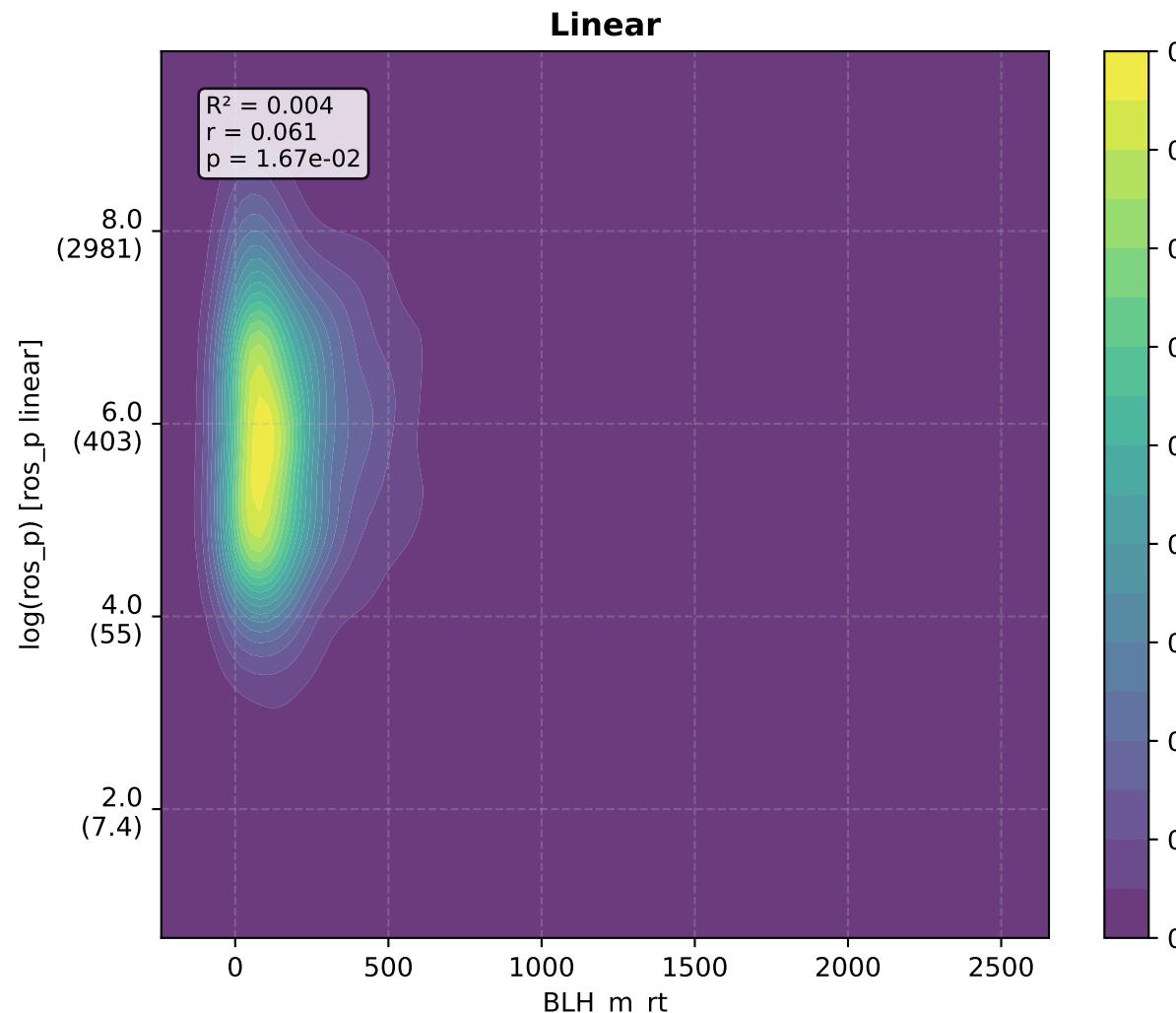
wv10_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



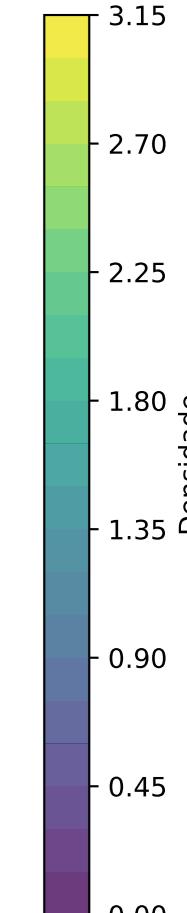
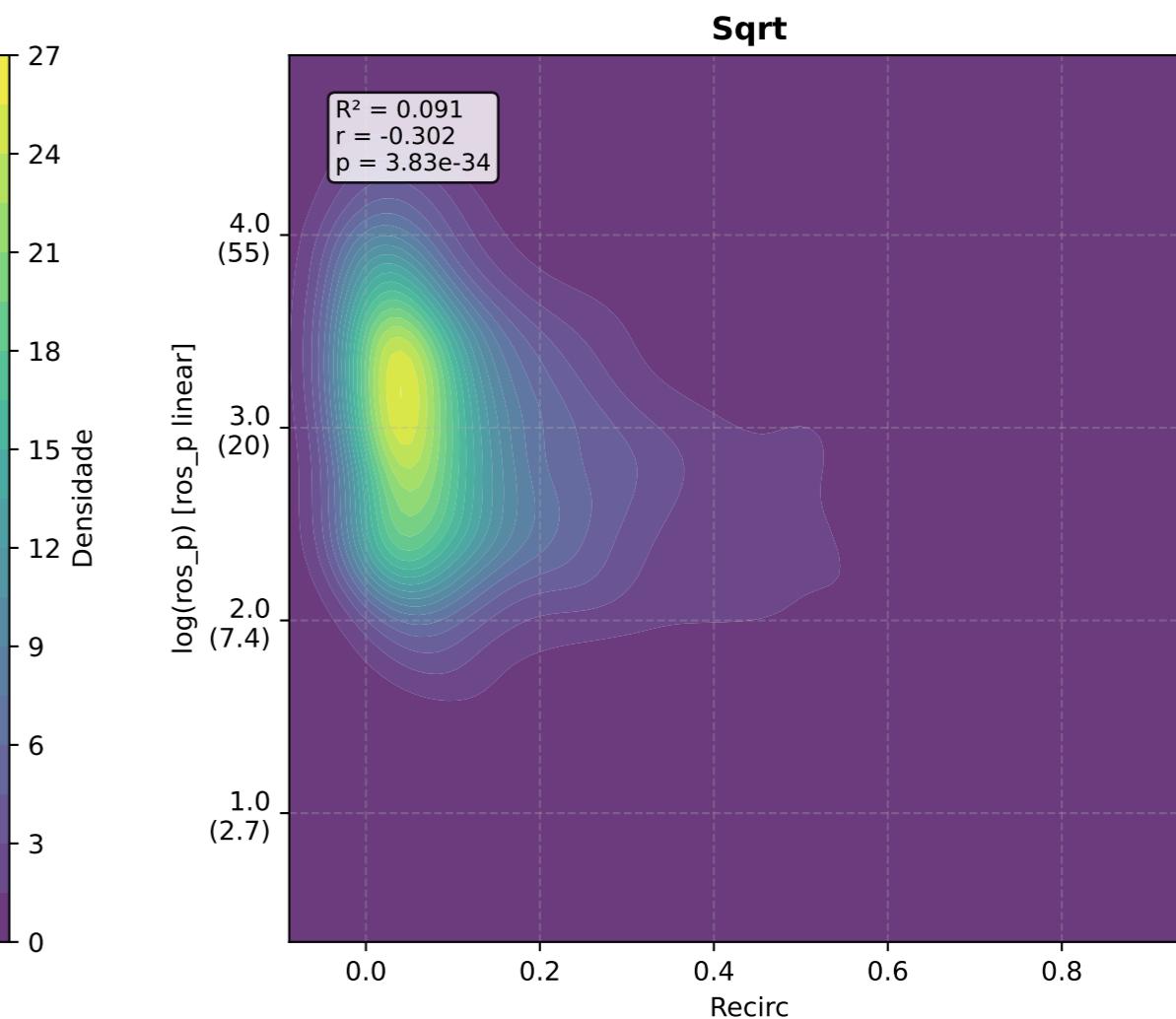
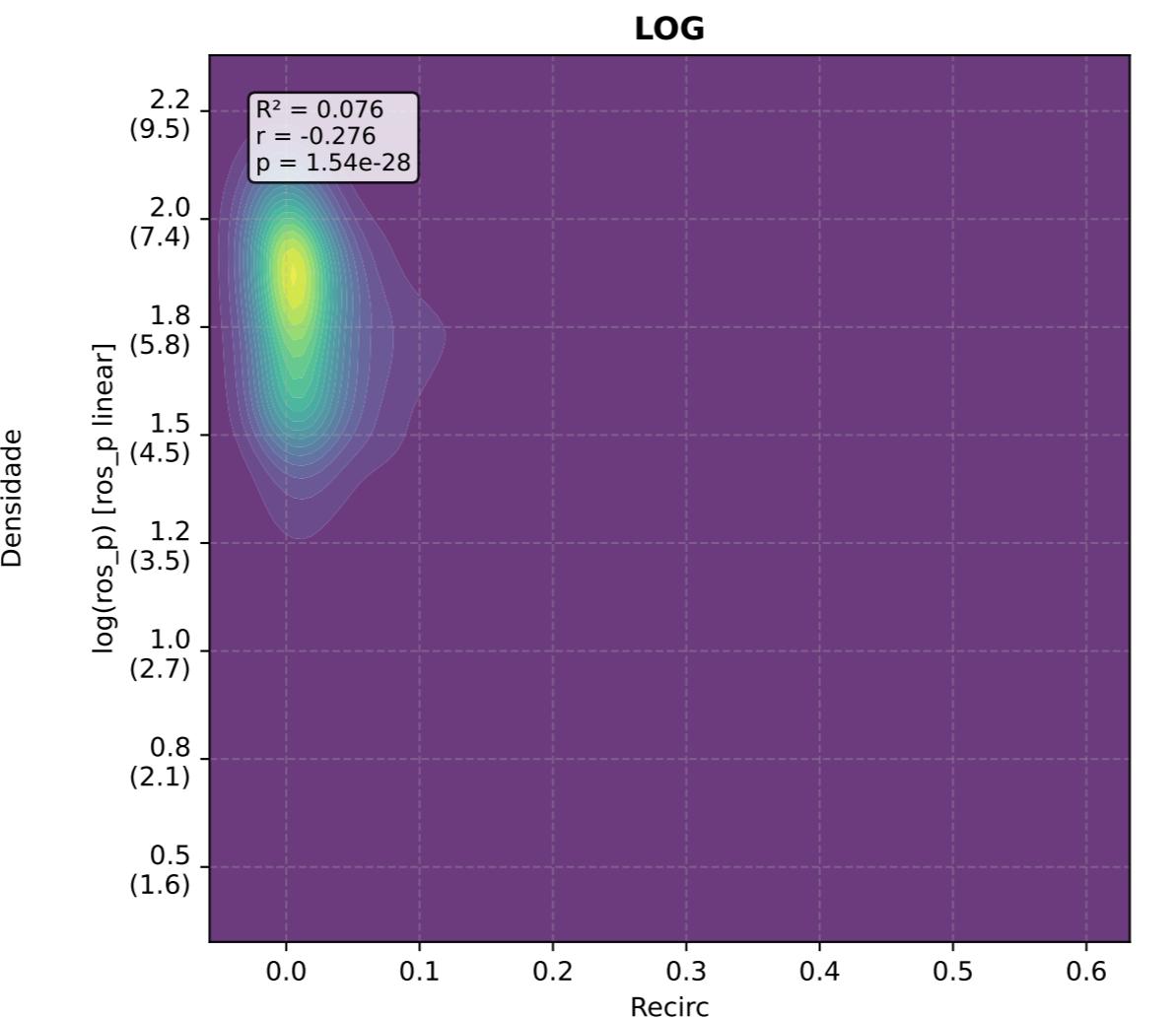
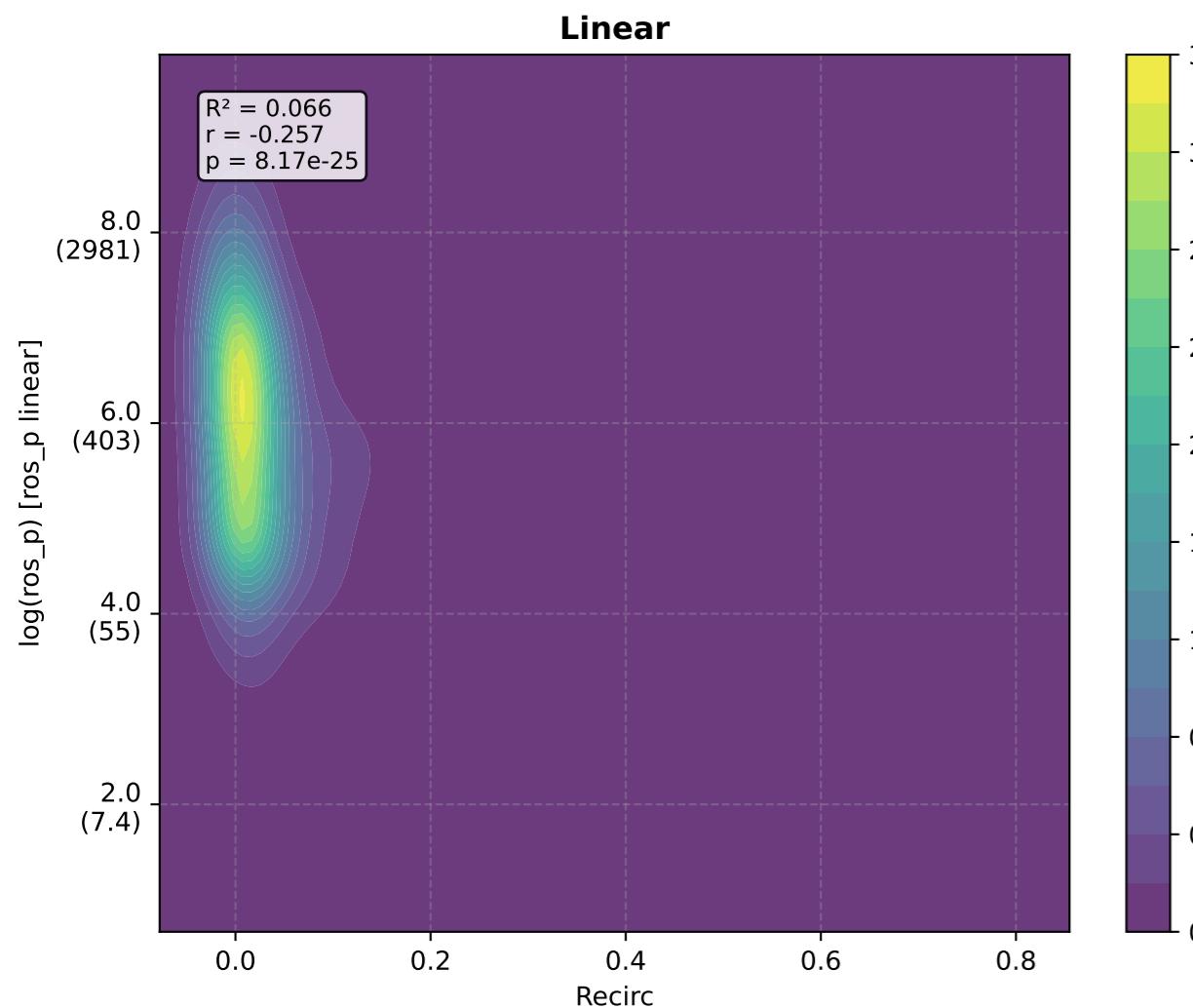
wv100_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



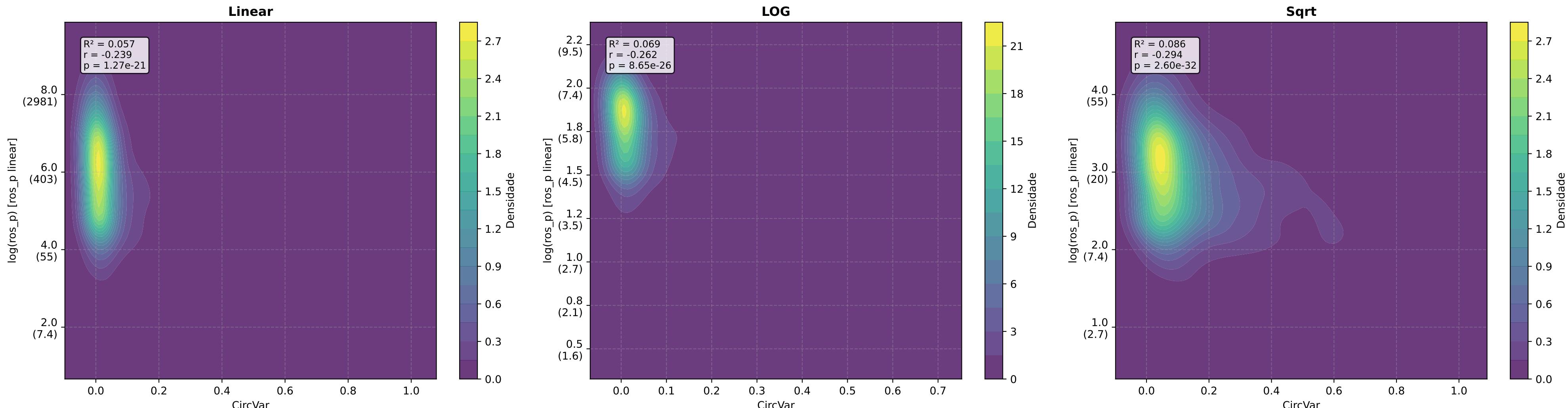
BLH_m_rt vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



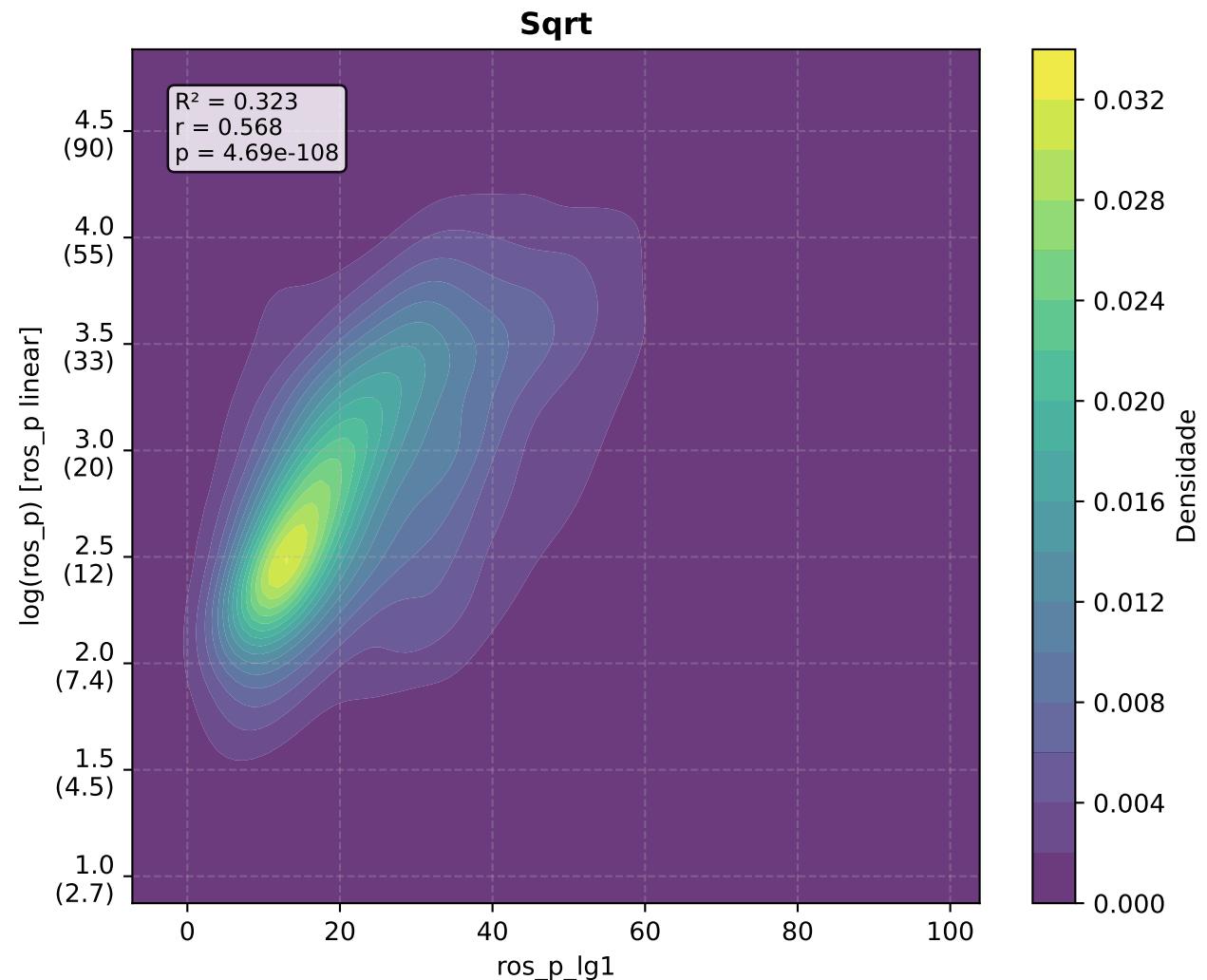
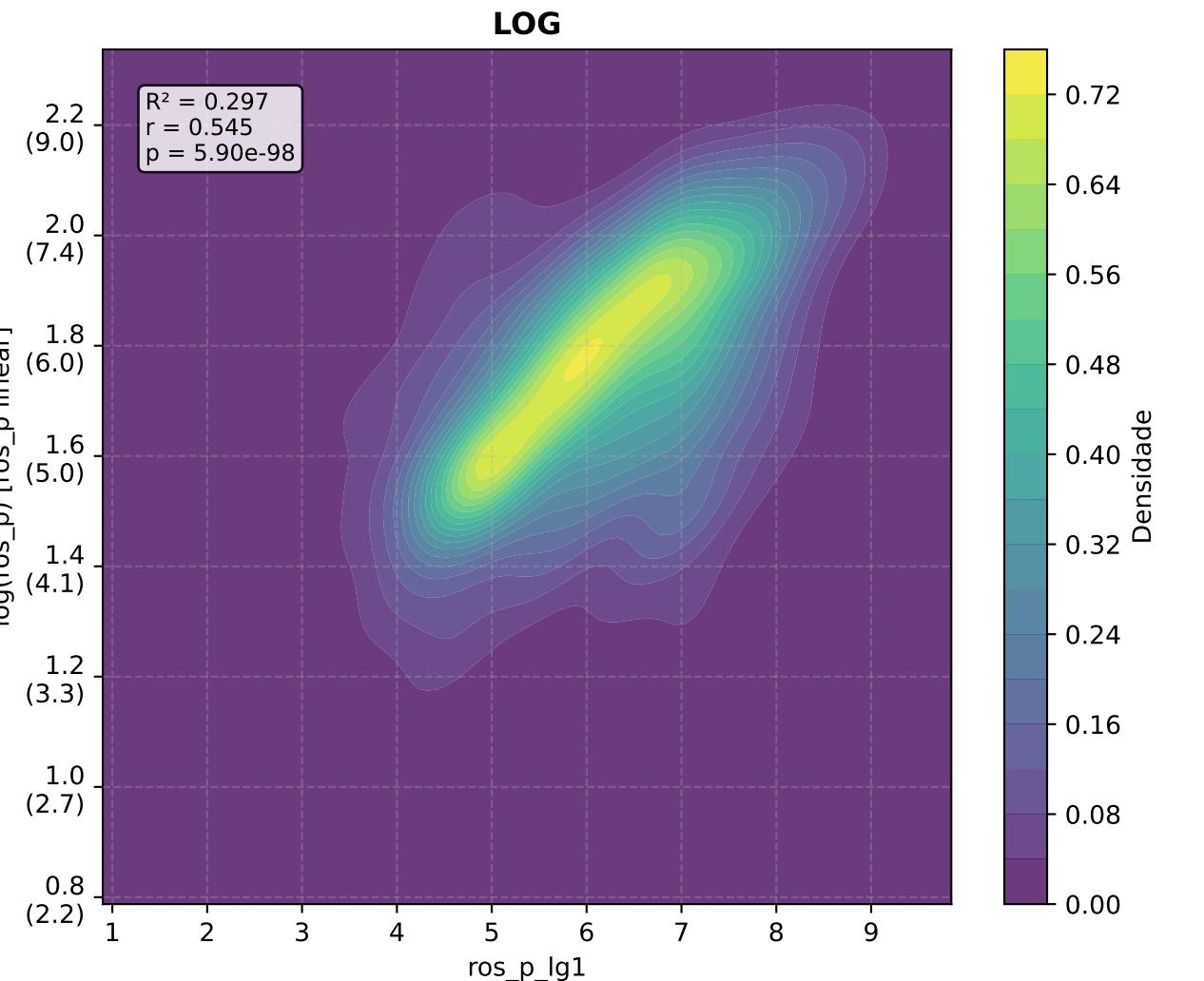
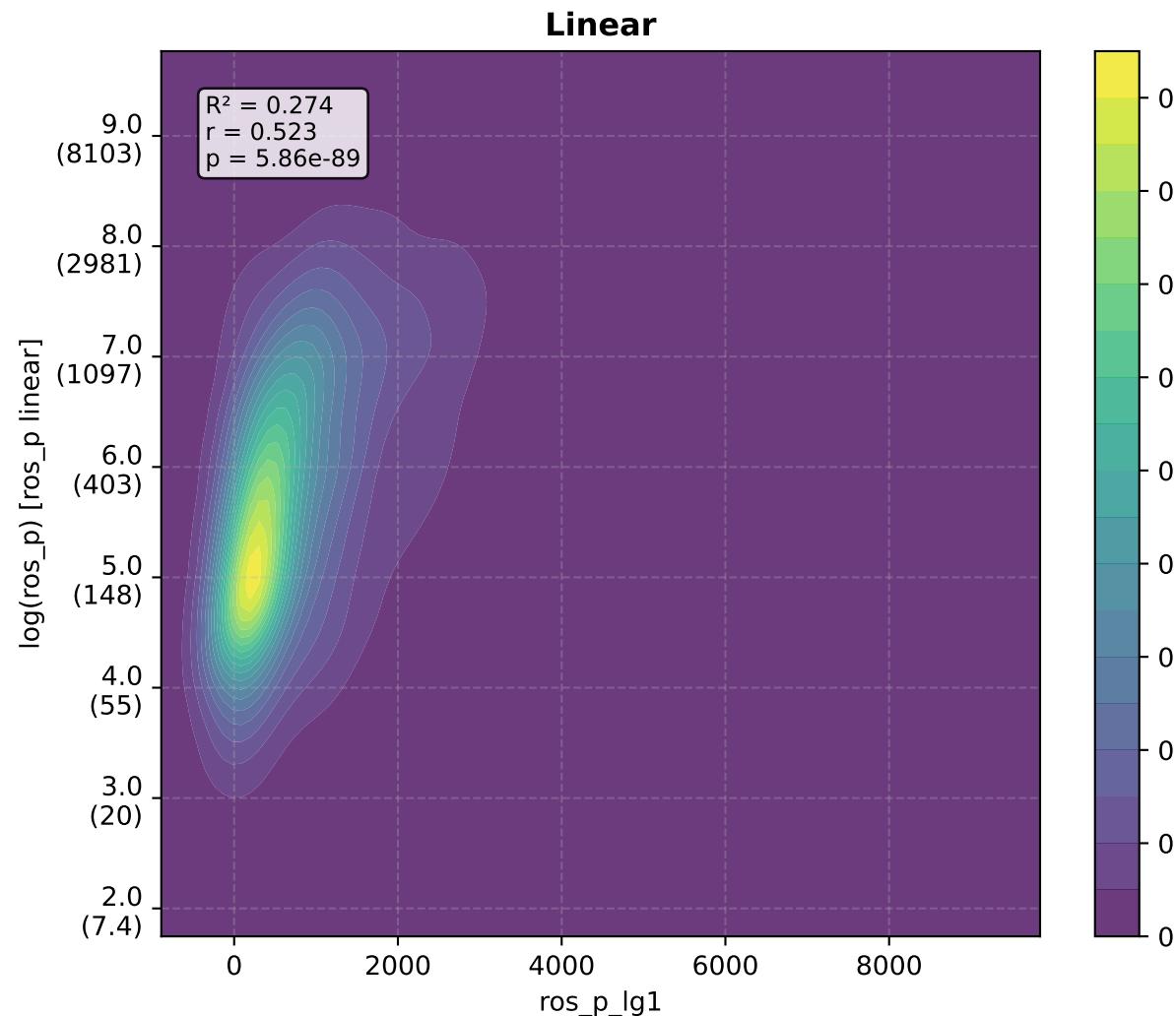
Recirc vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



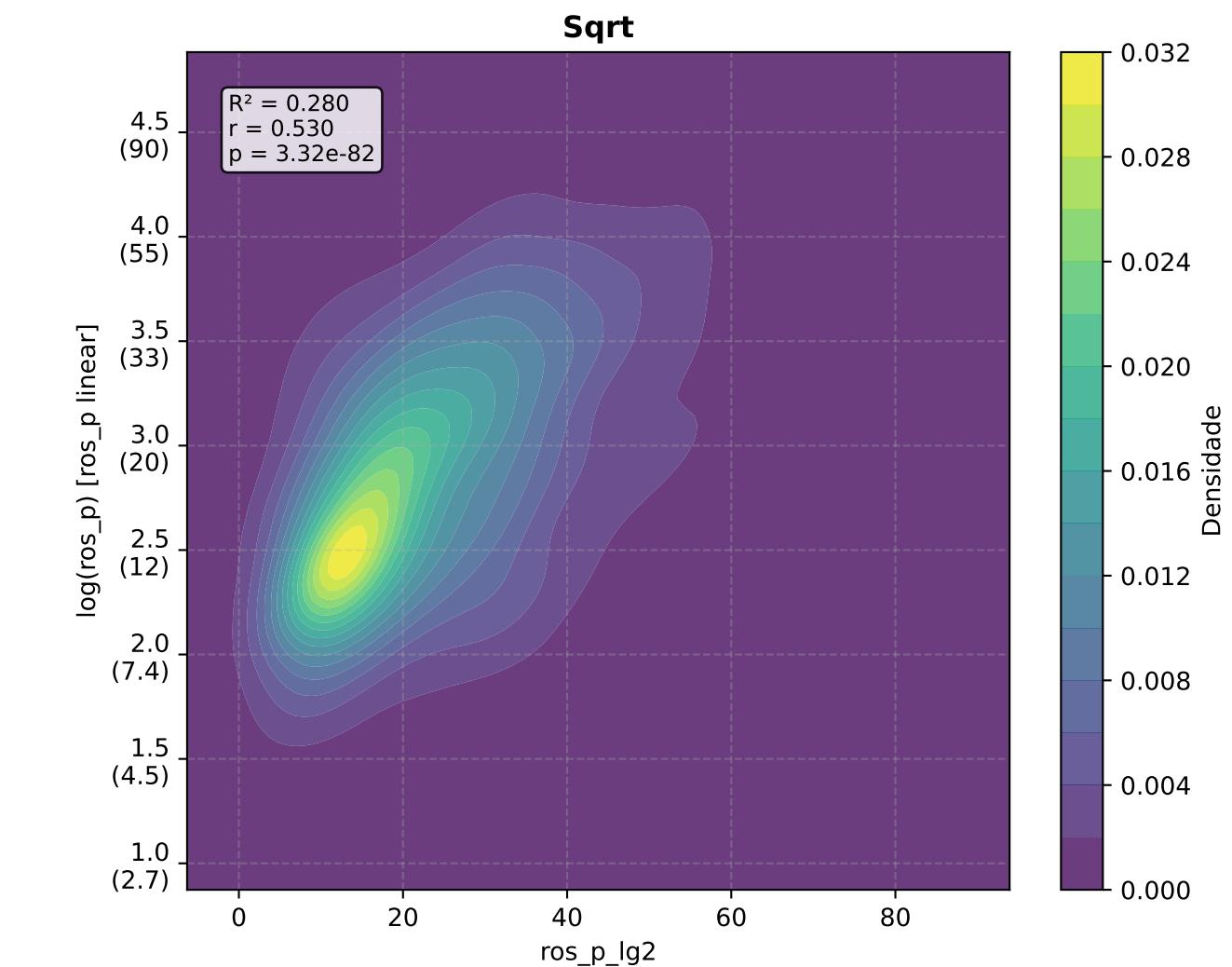
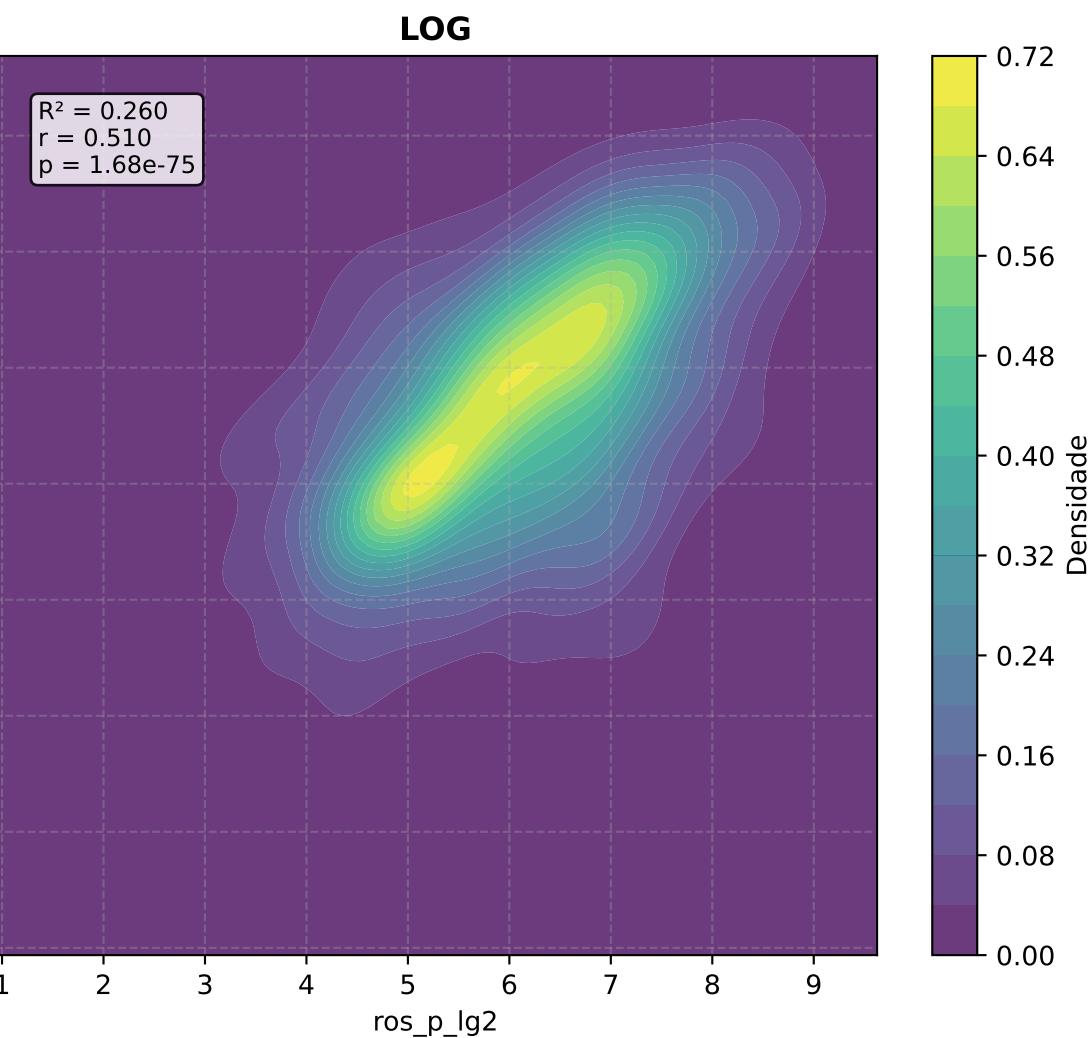
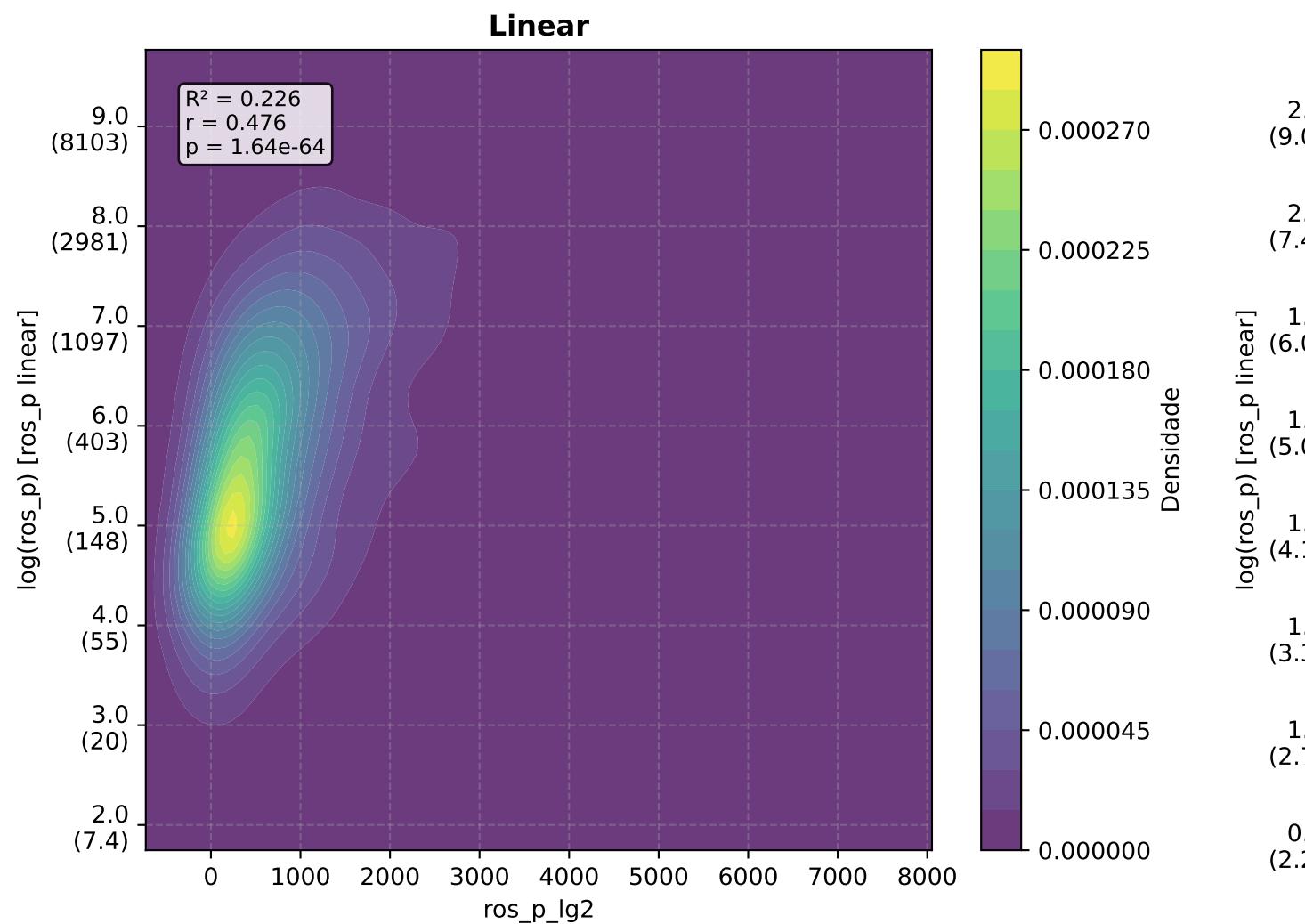
CircVar vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



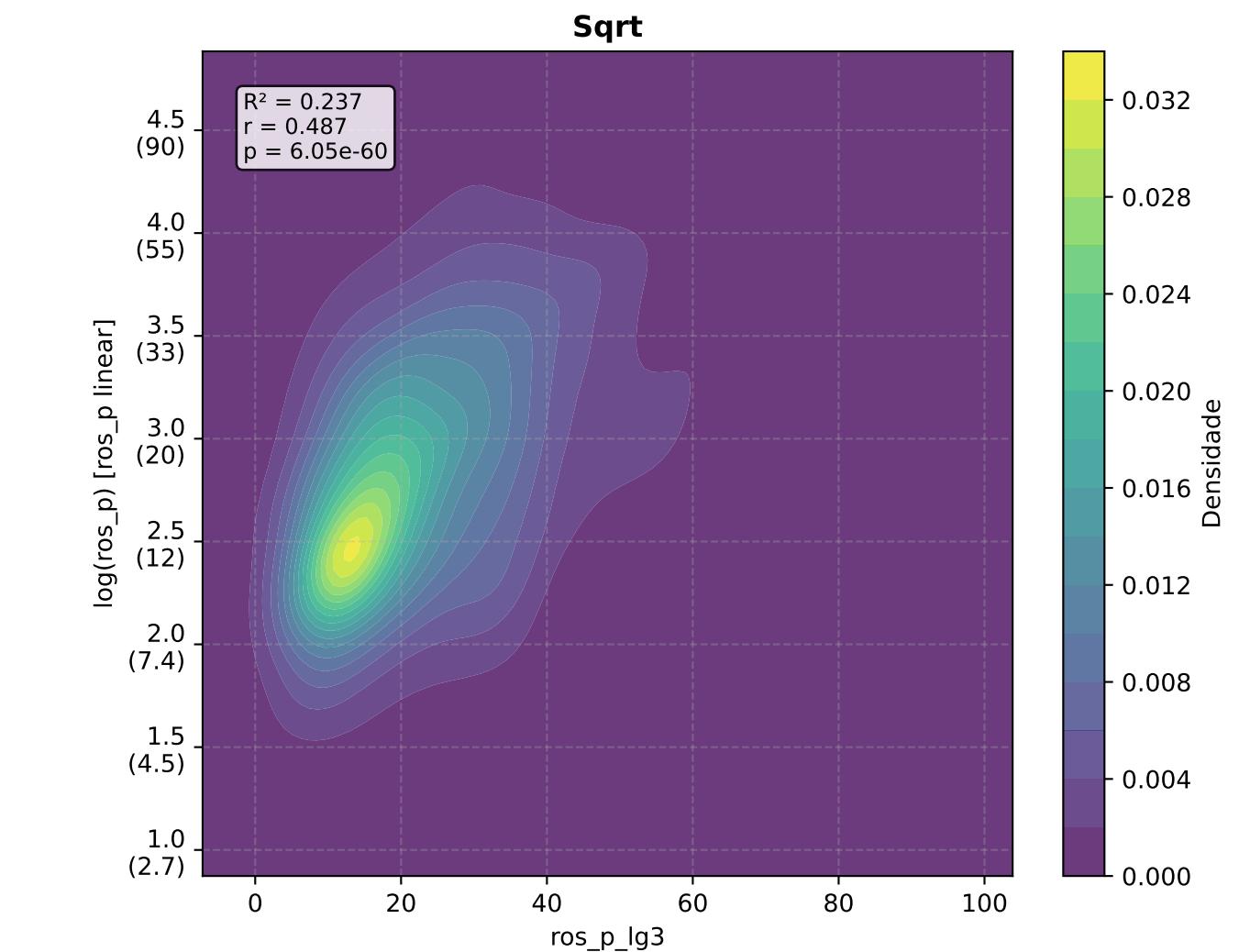
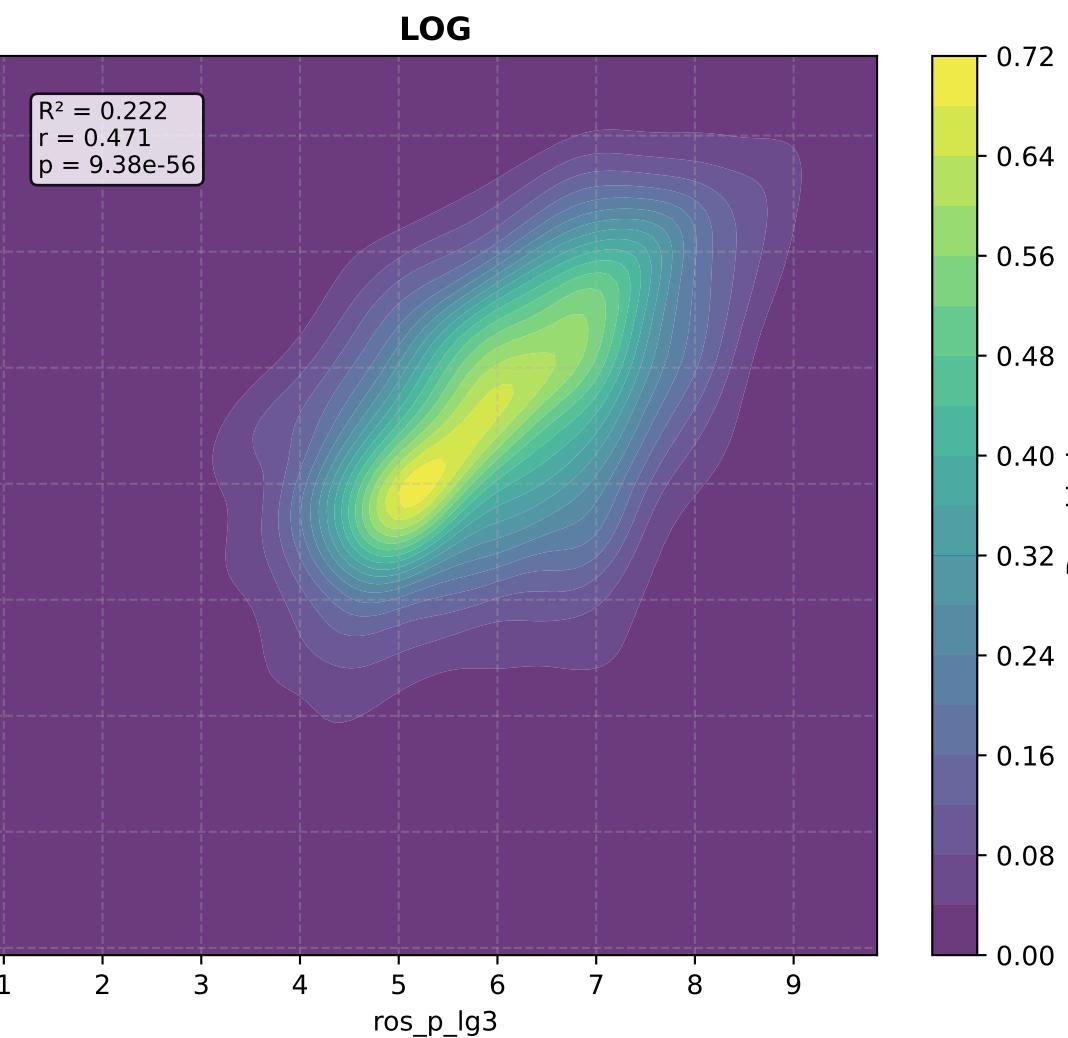
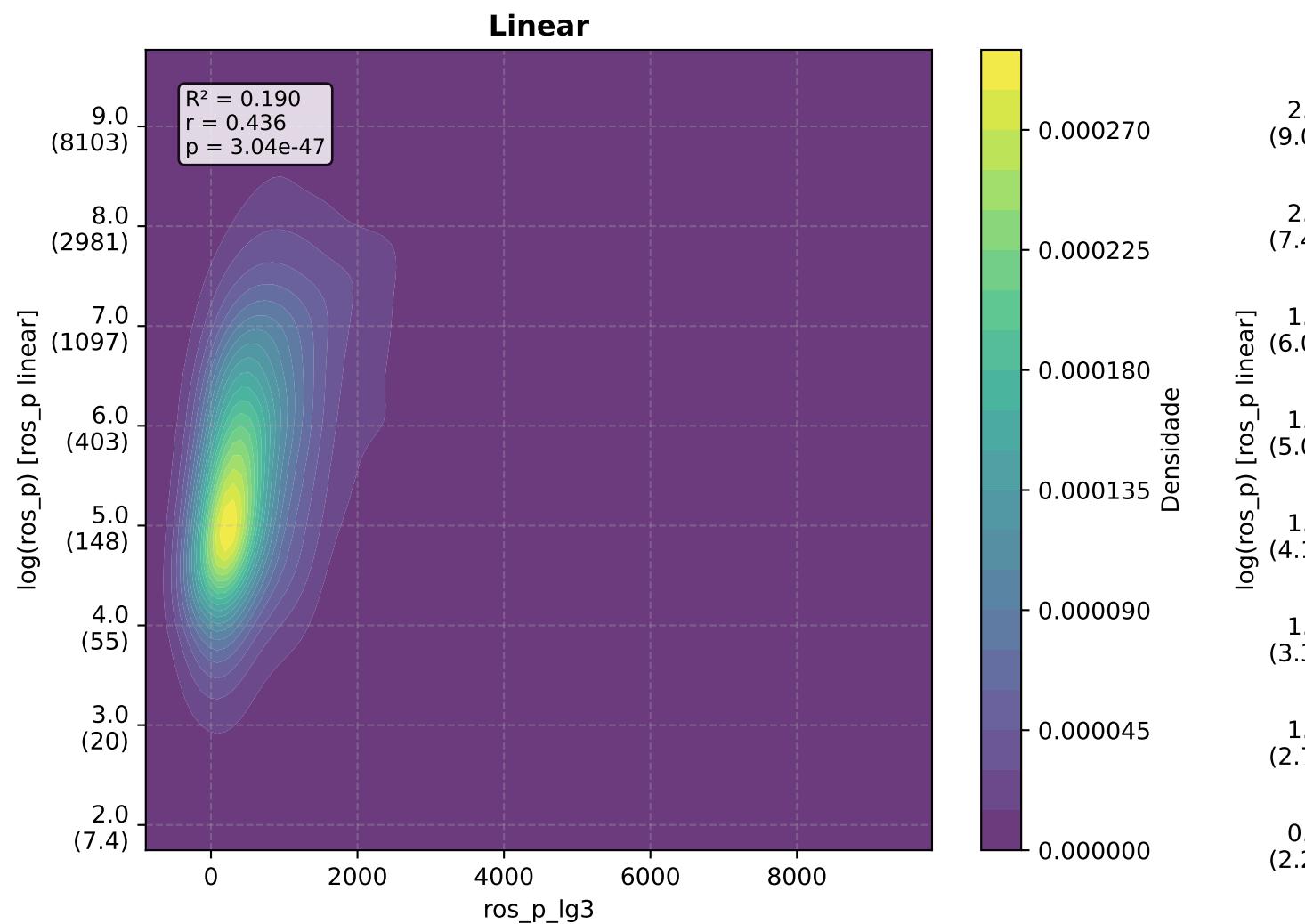
ros_p_lg1 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



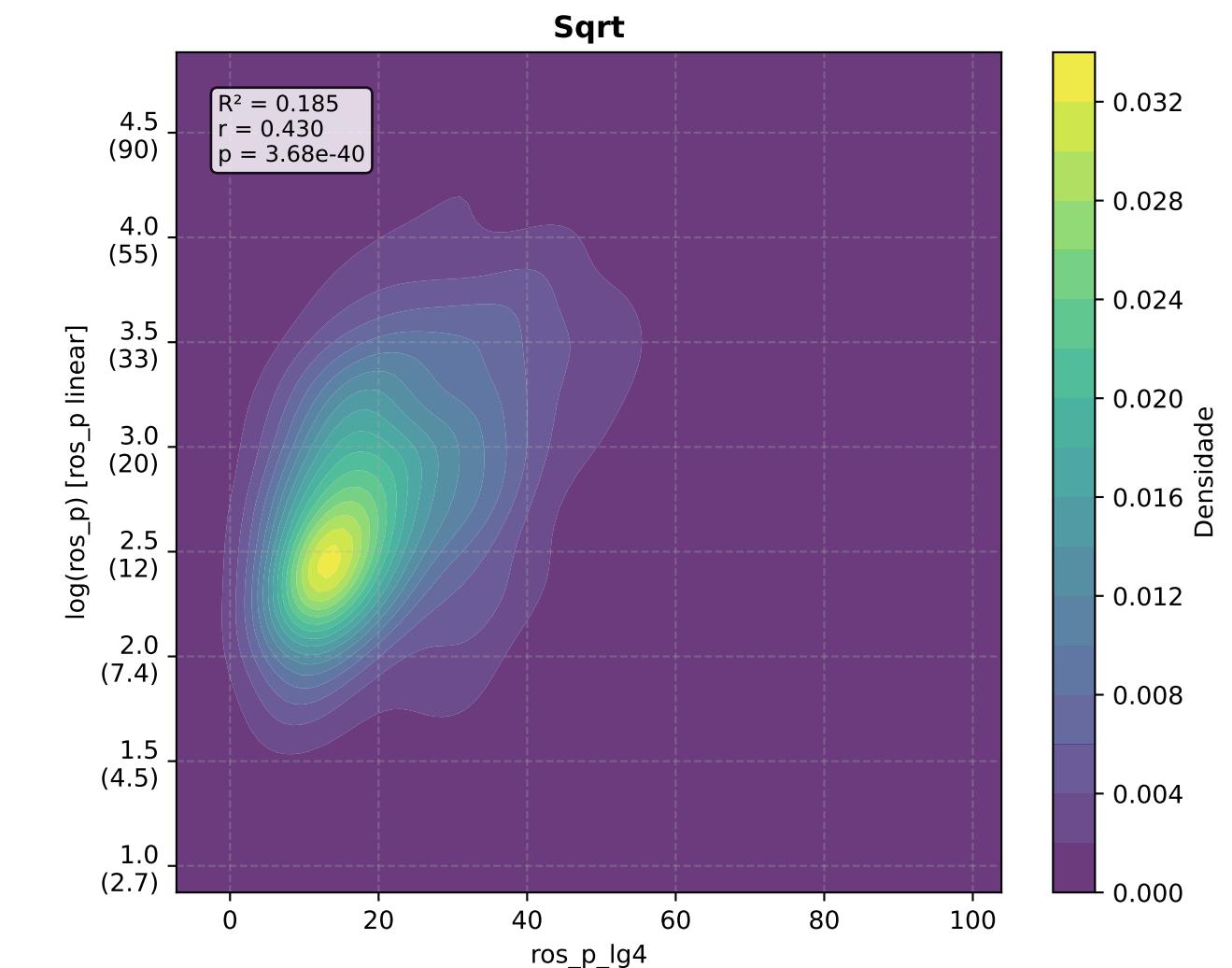
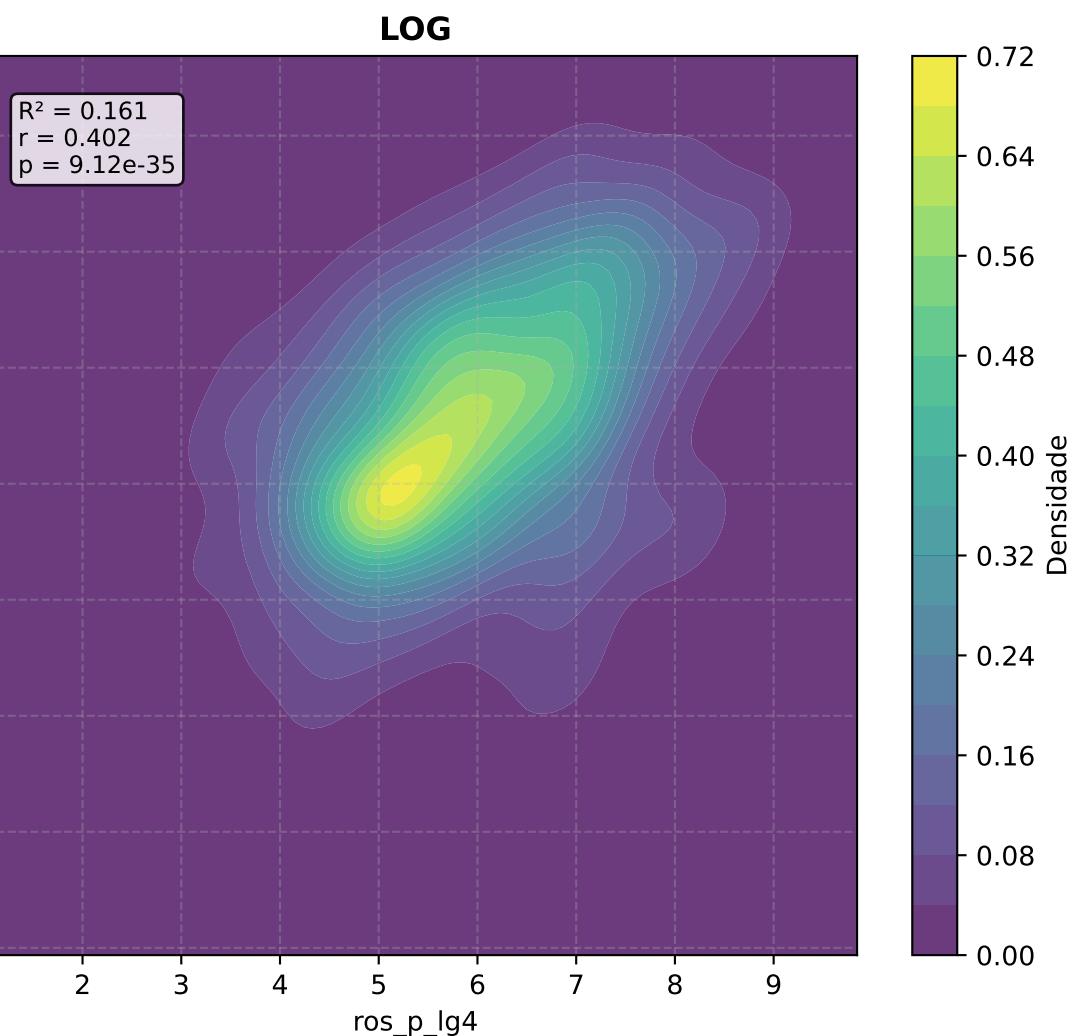
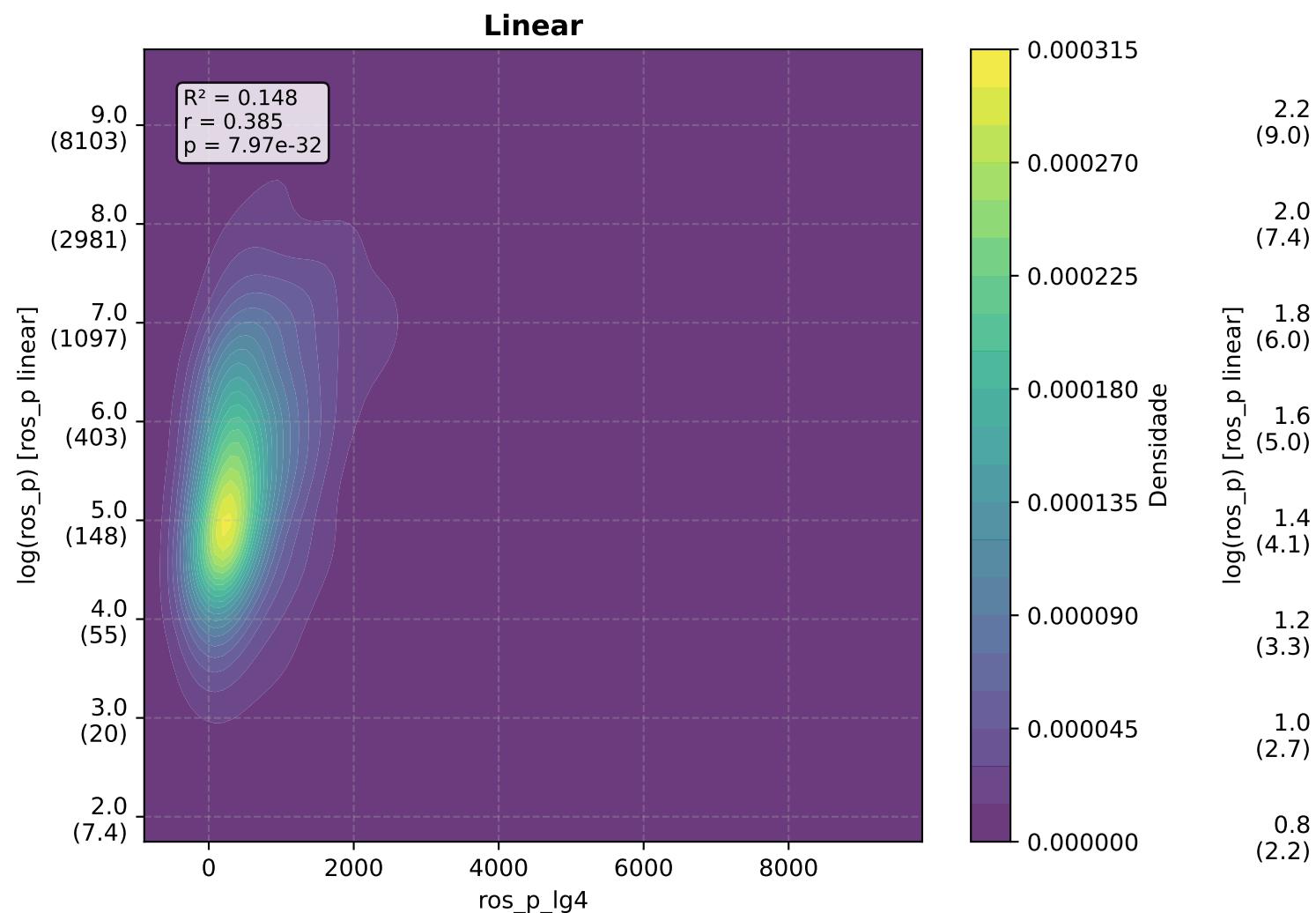
ros_p_lg2 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



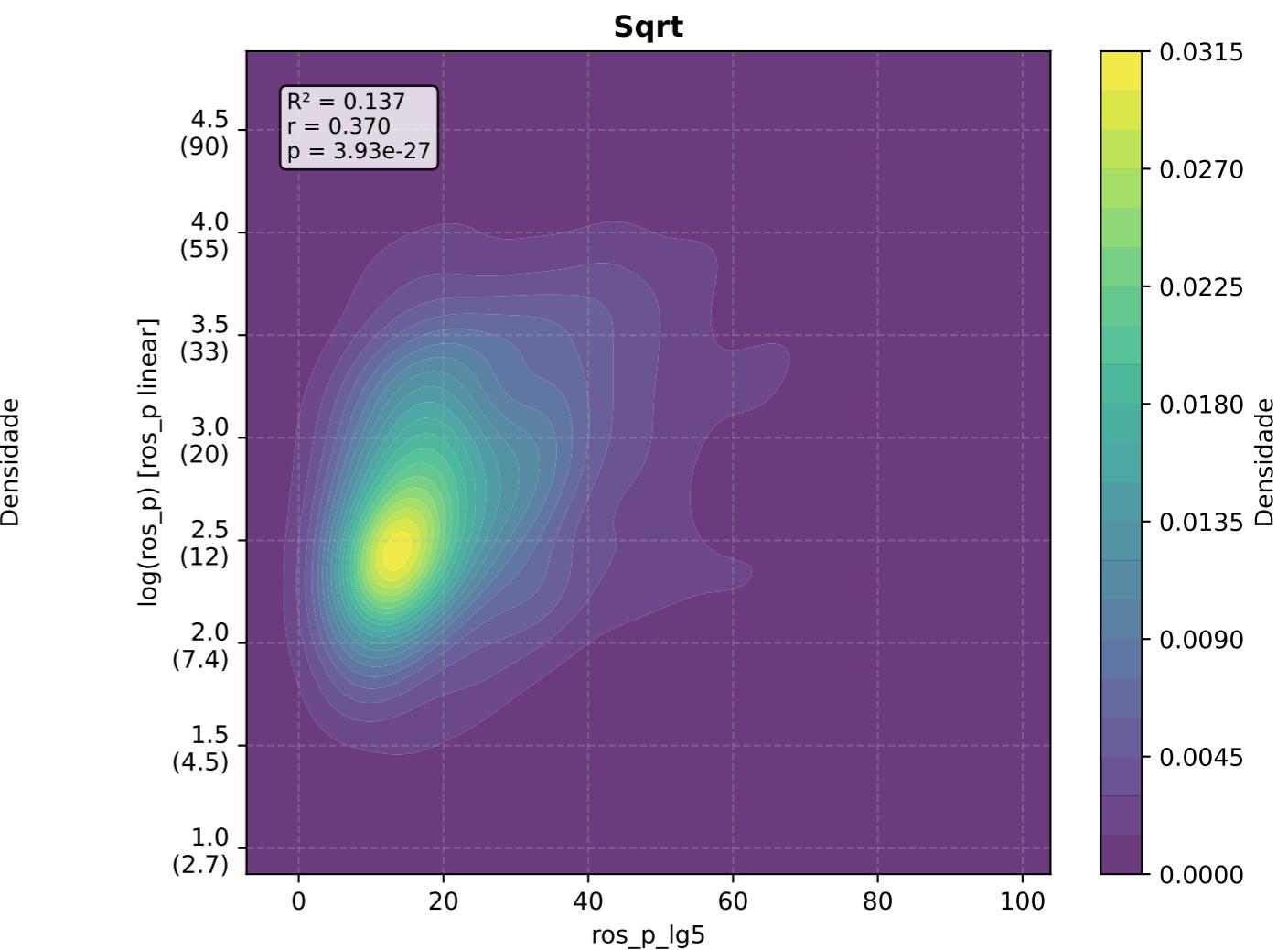
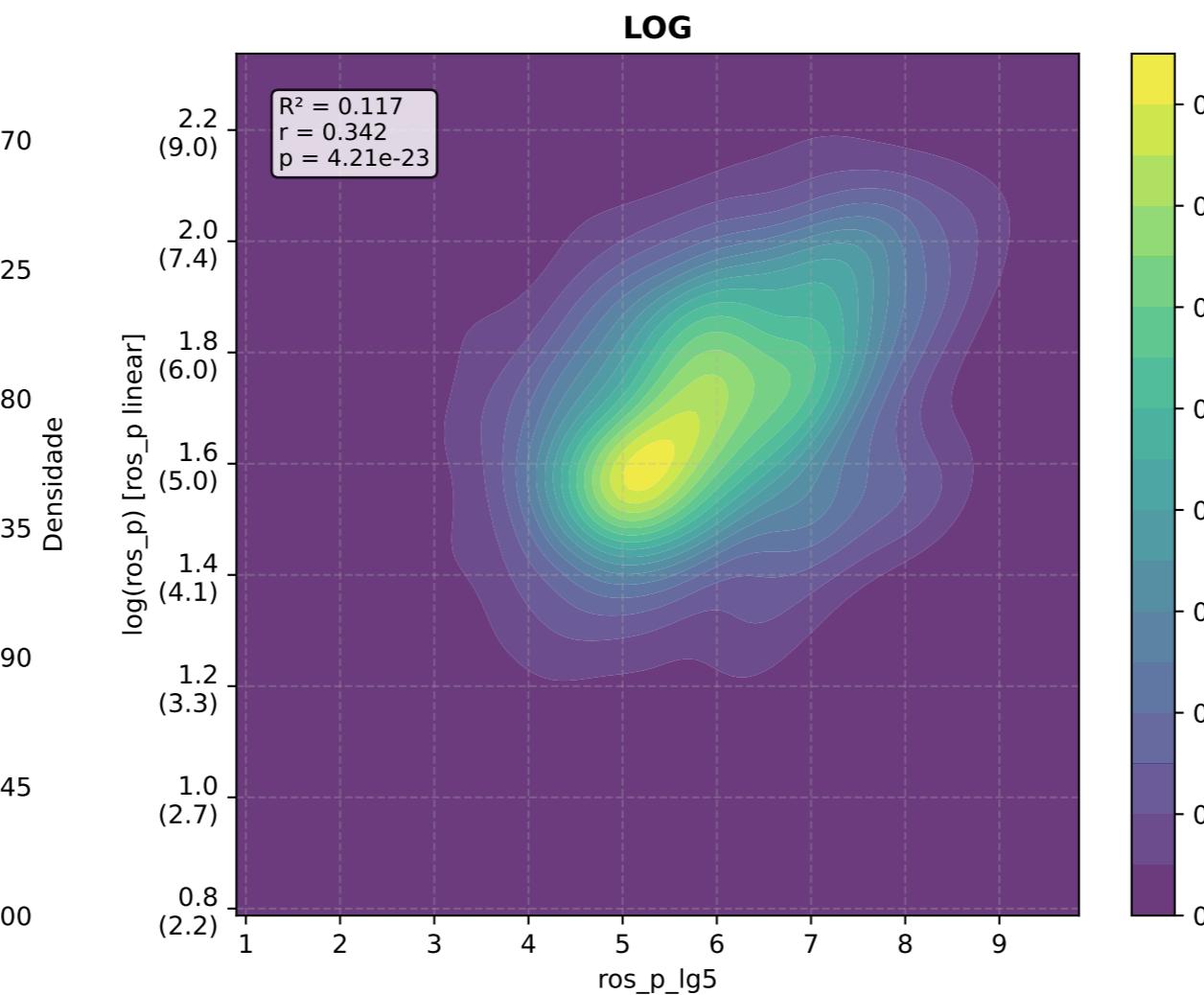
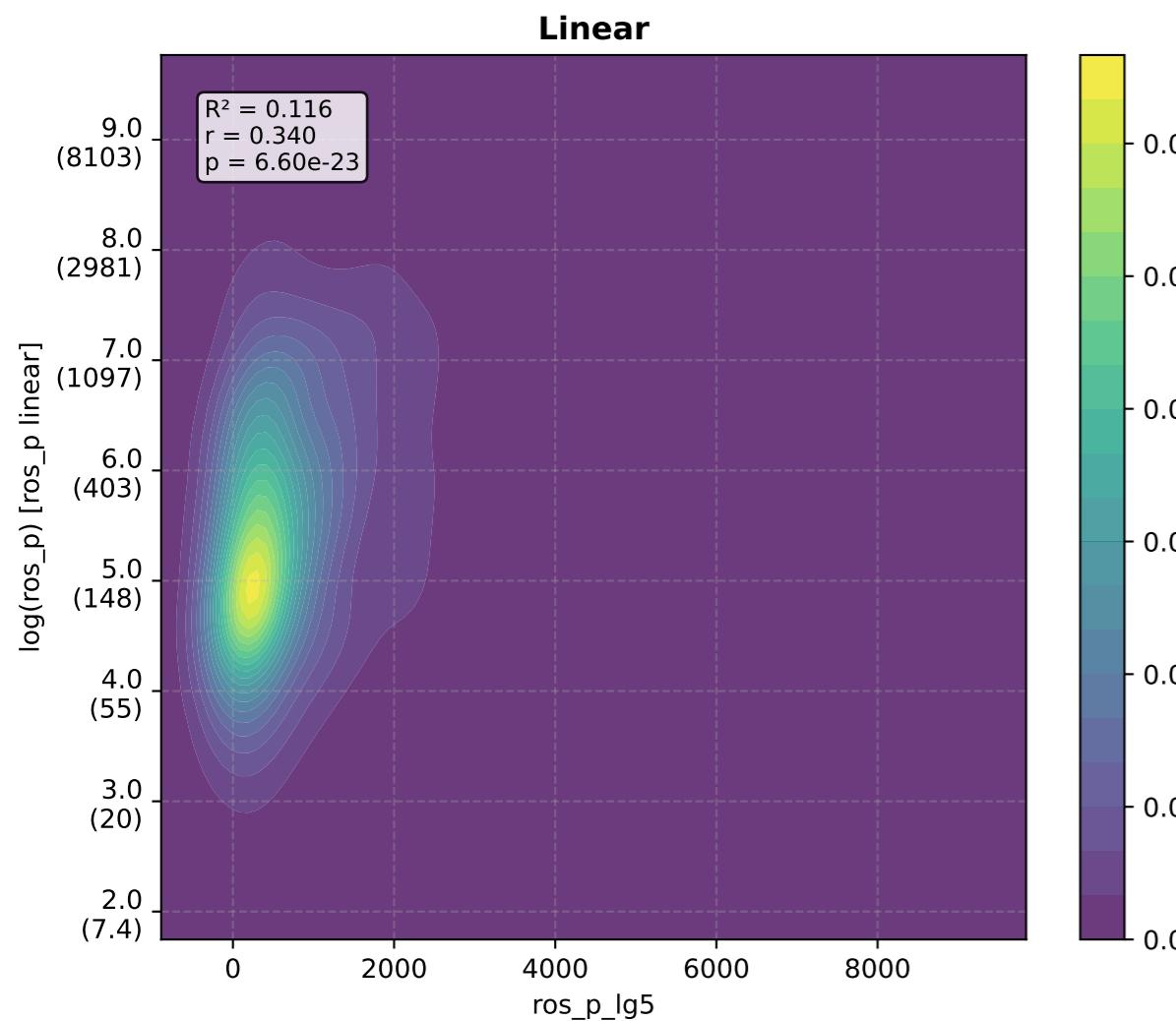
ros_p_lg3 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



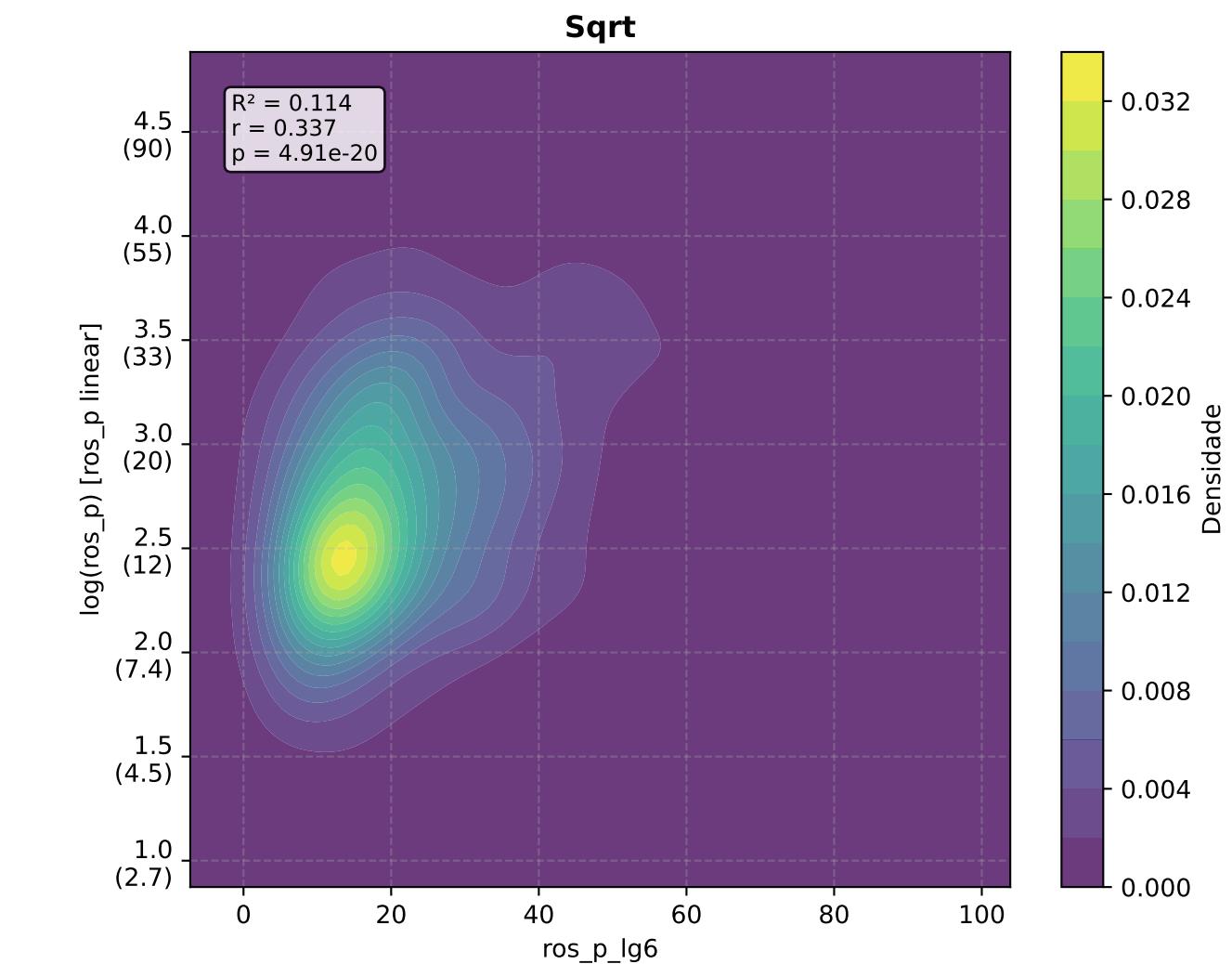
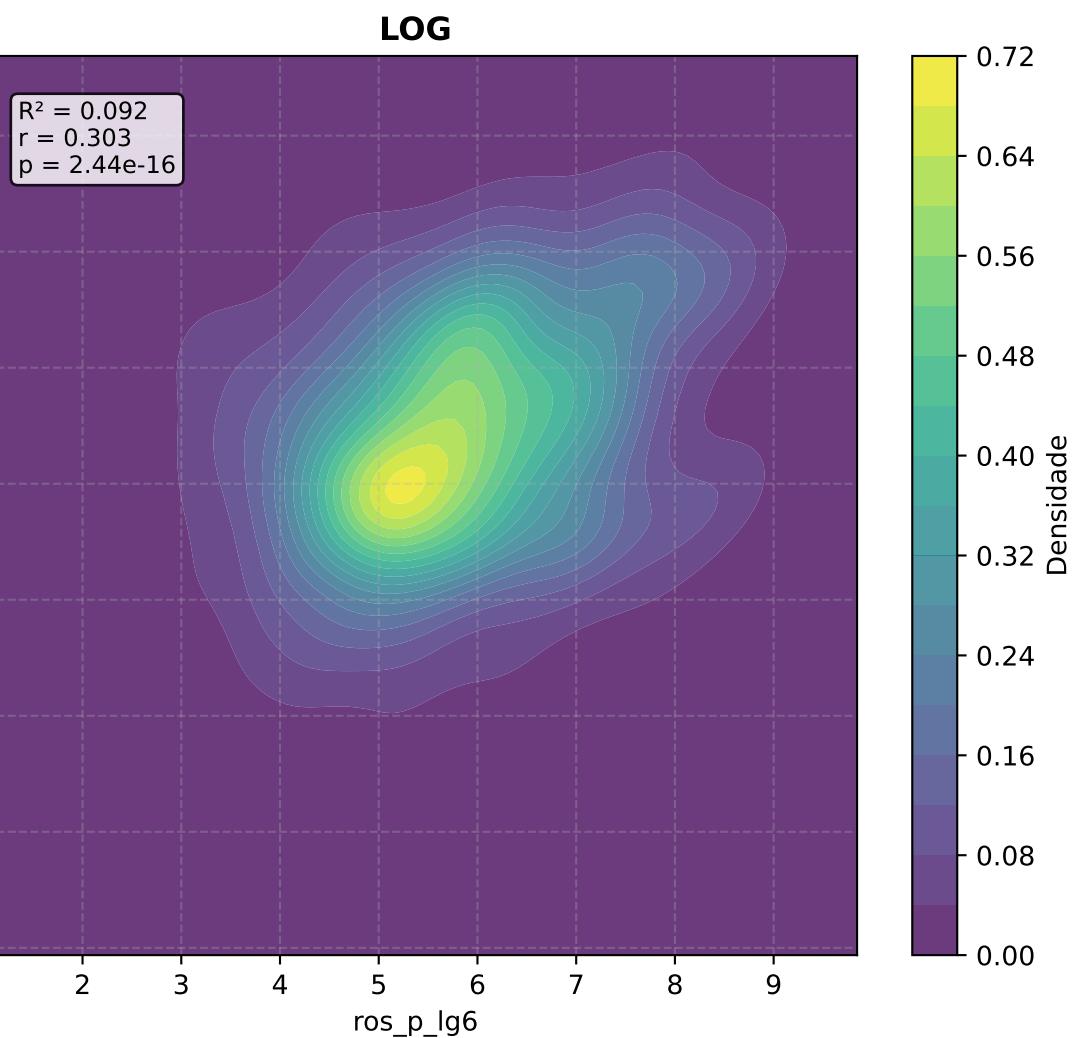
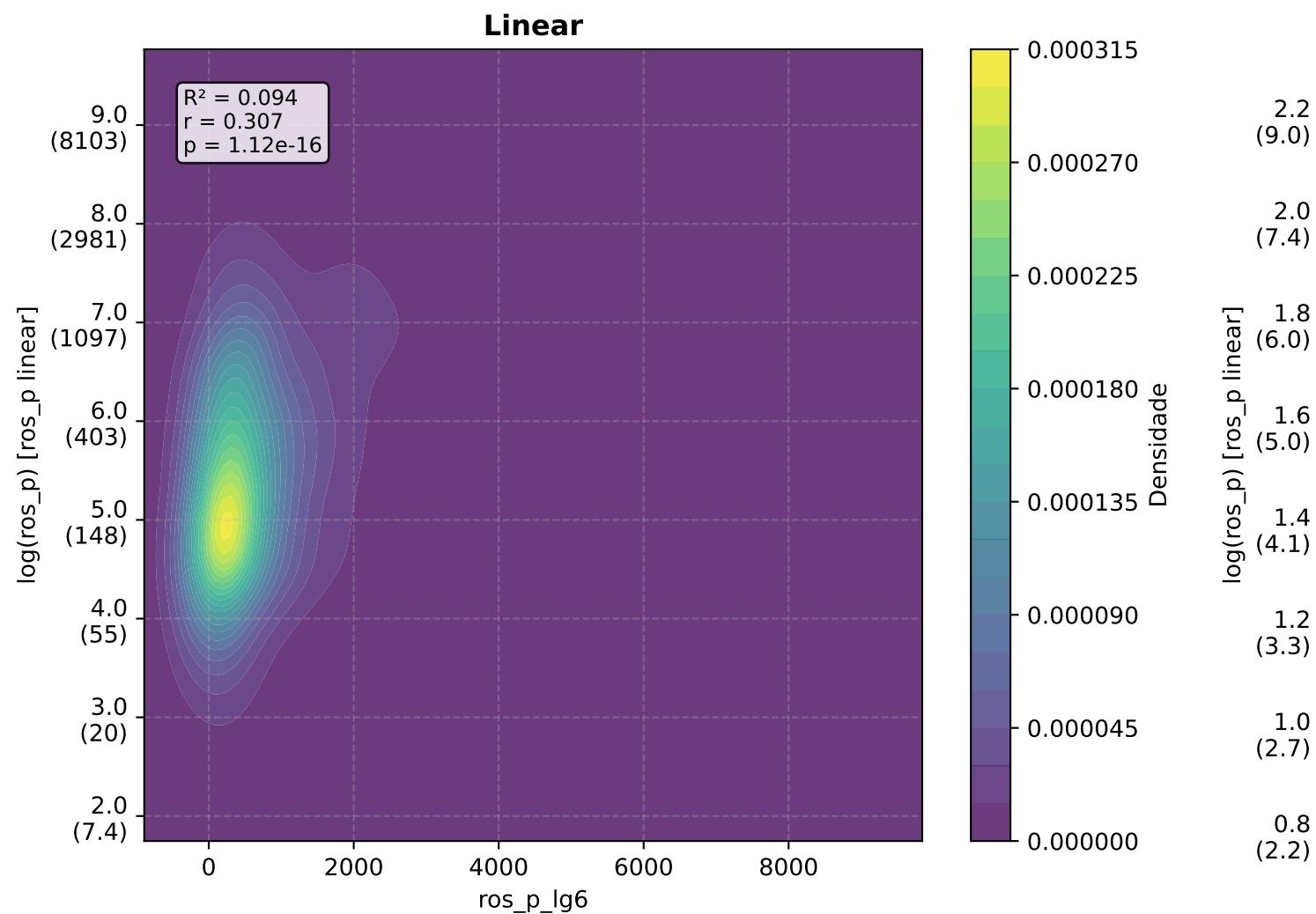
ros_p_lg4 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



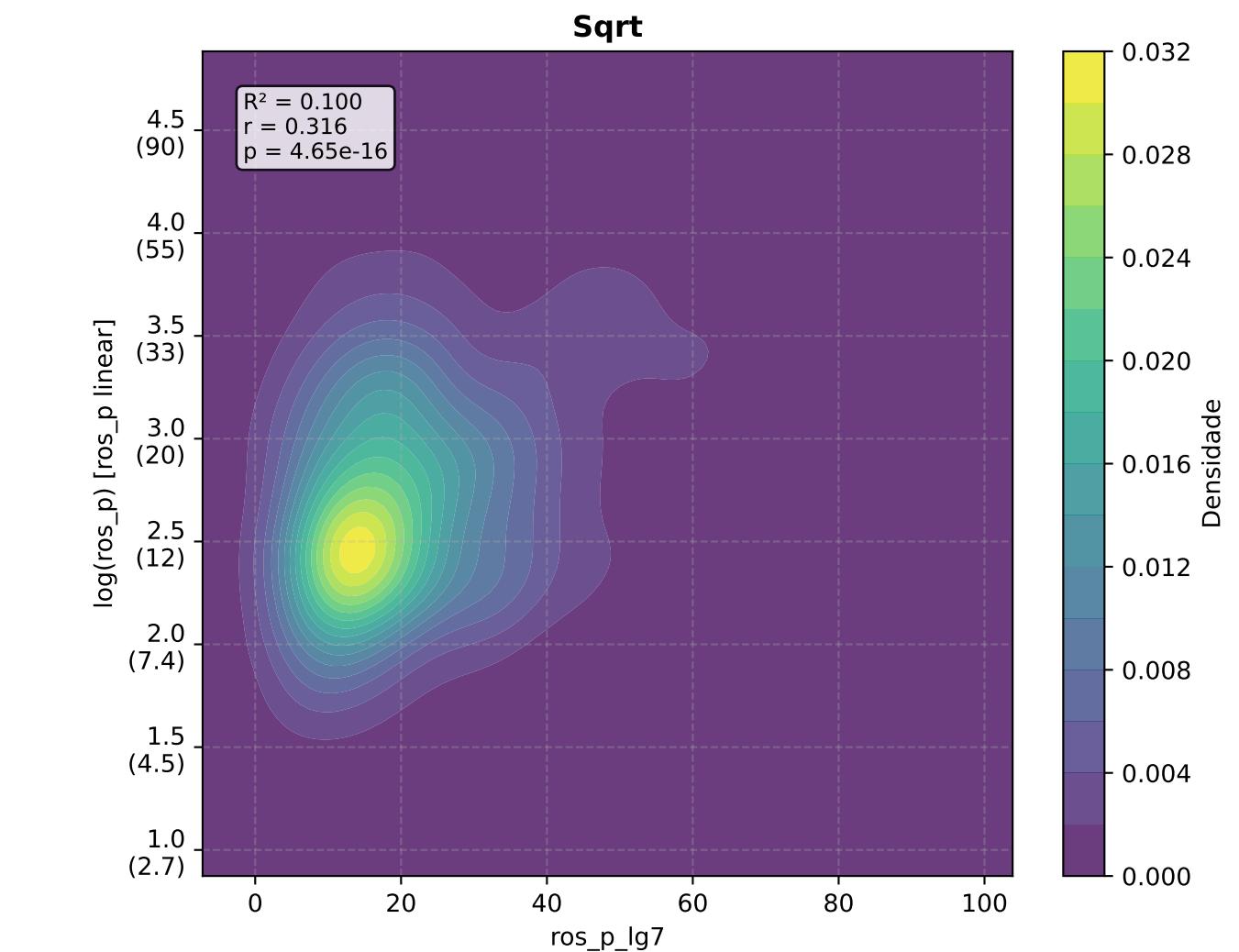
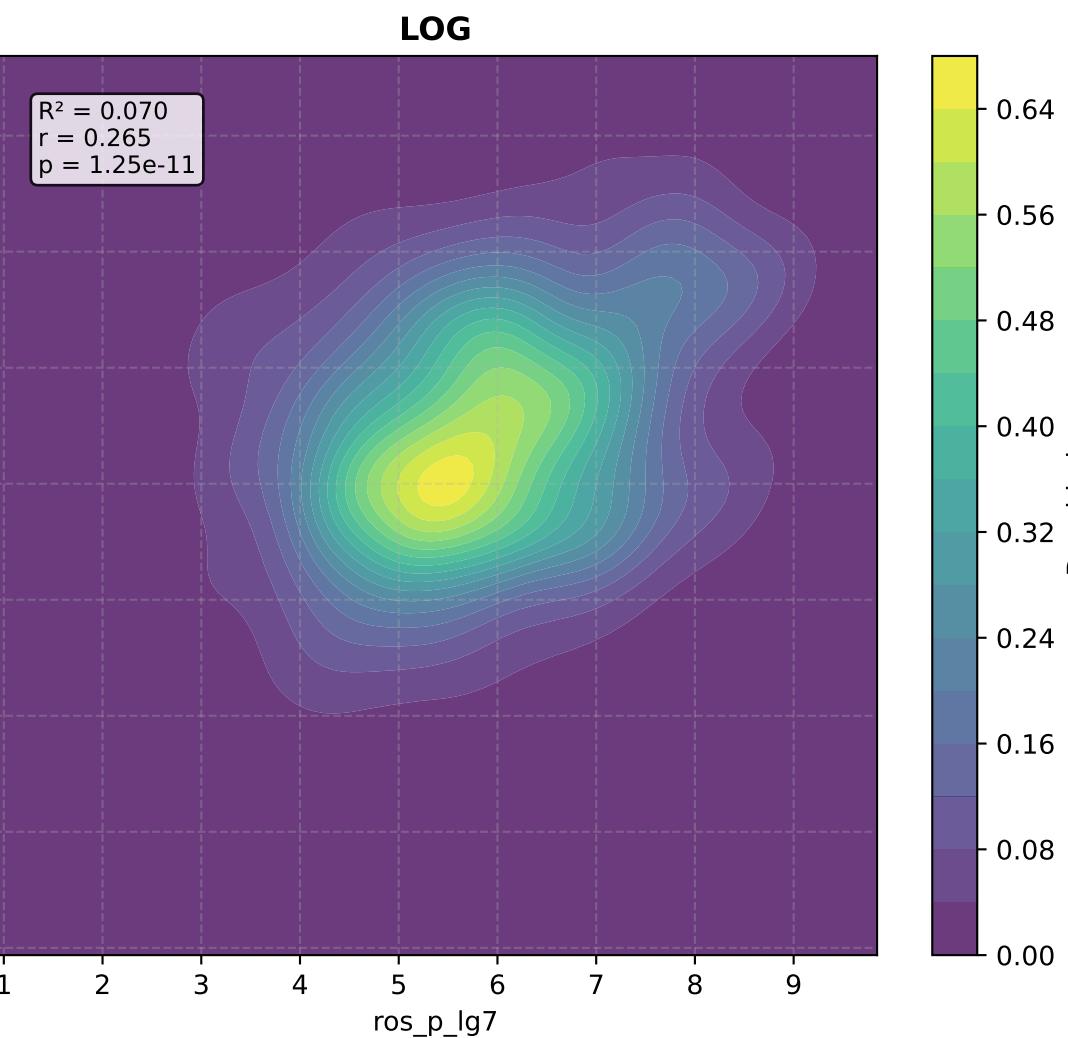
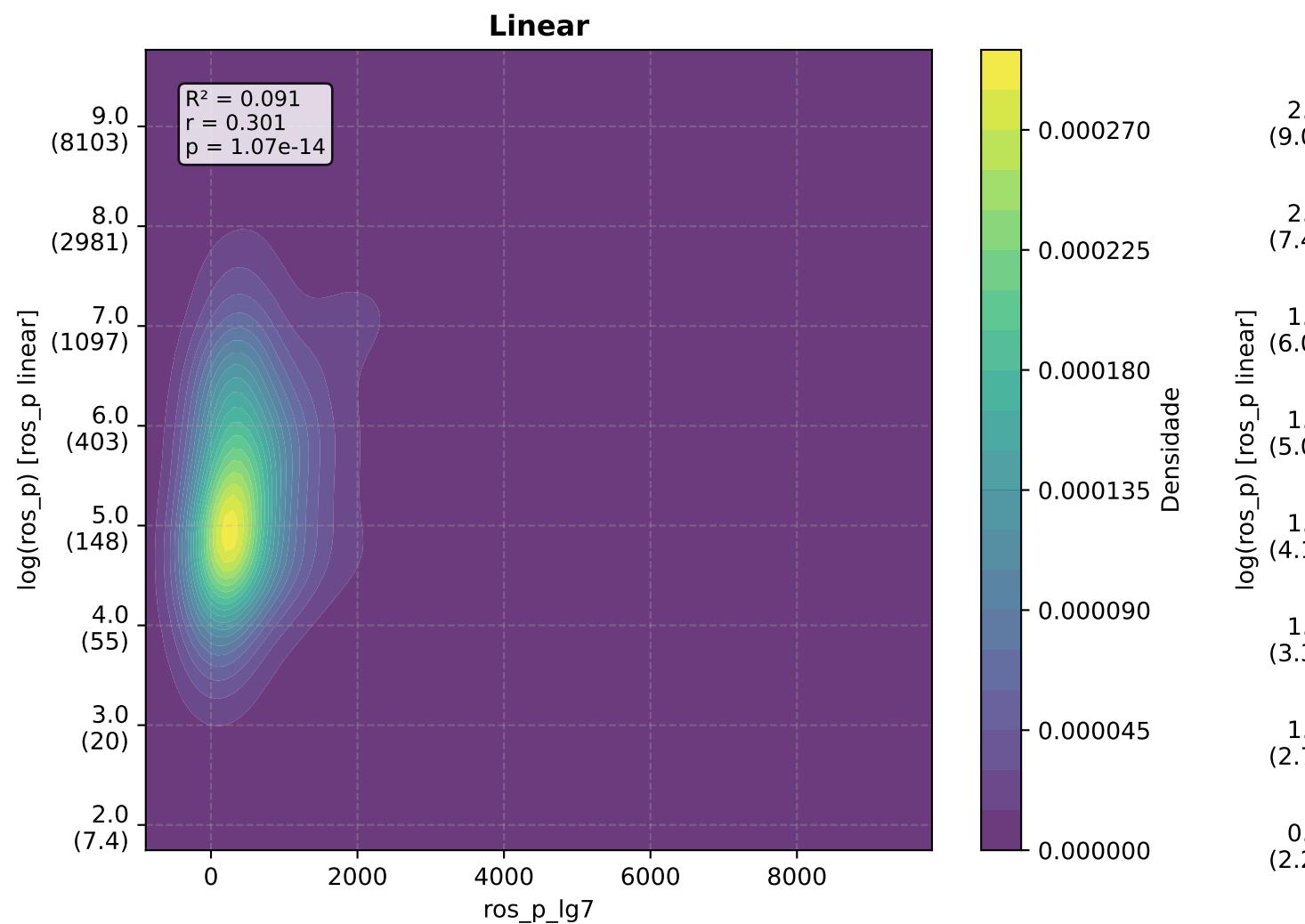
ros_p_lg5 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



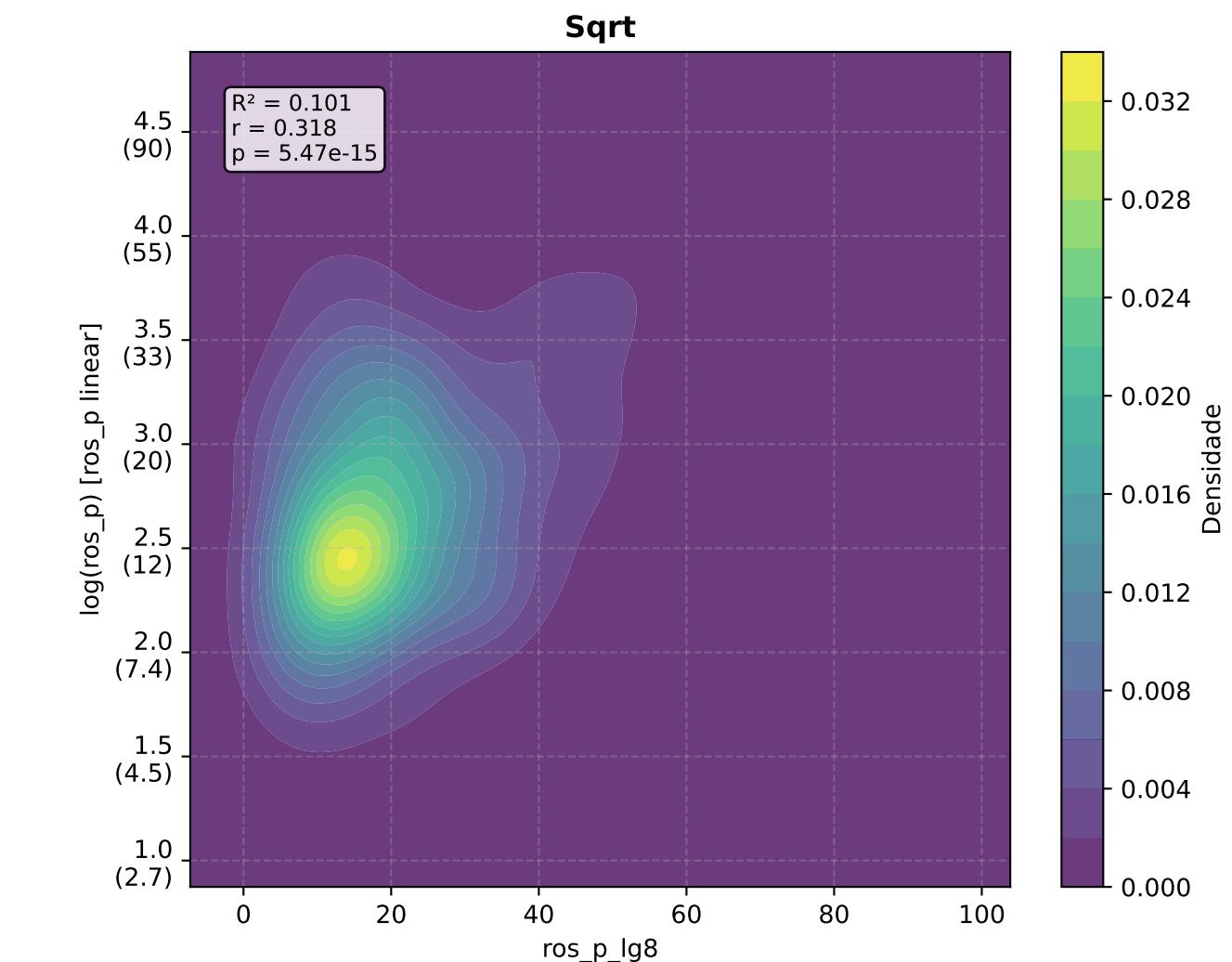
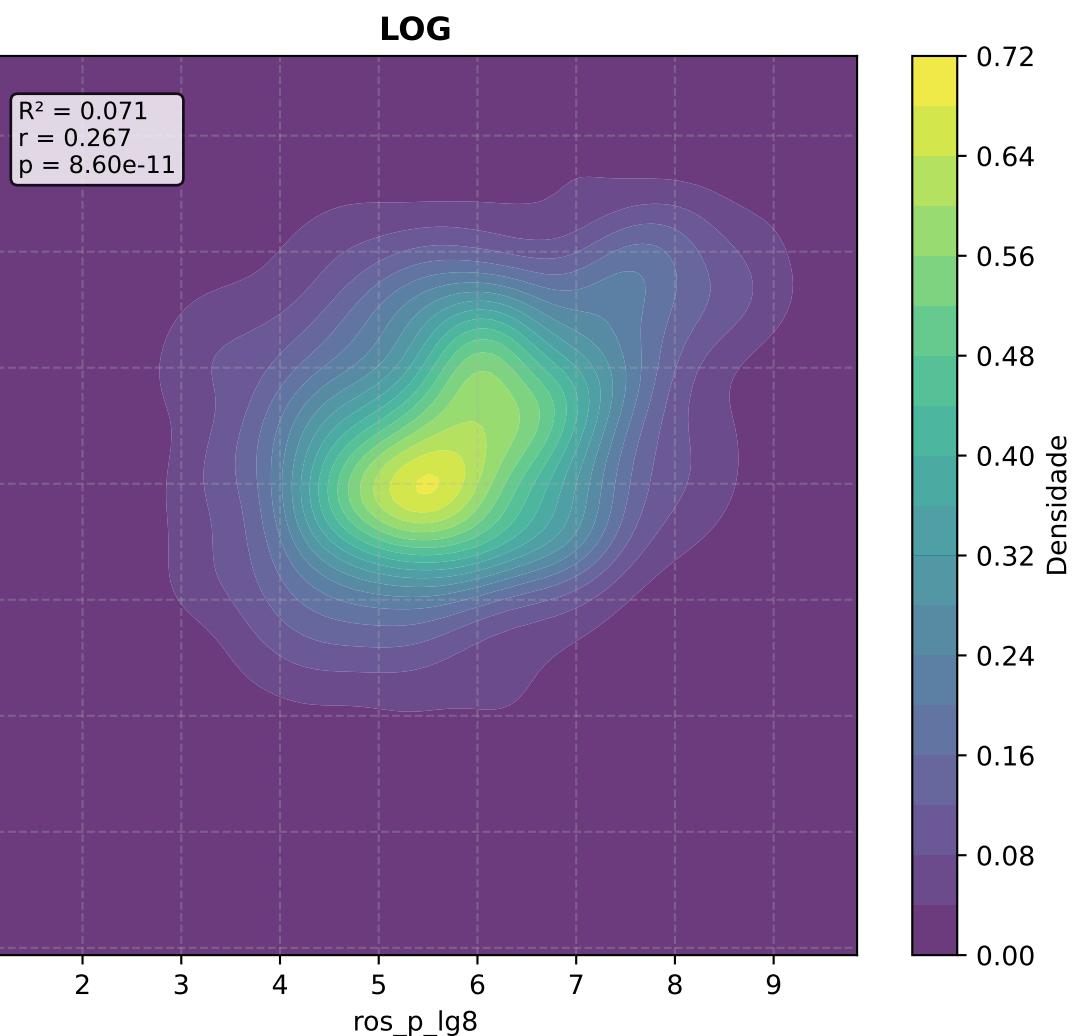
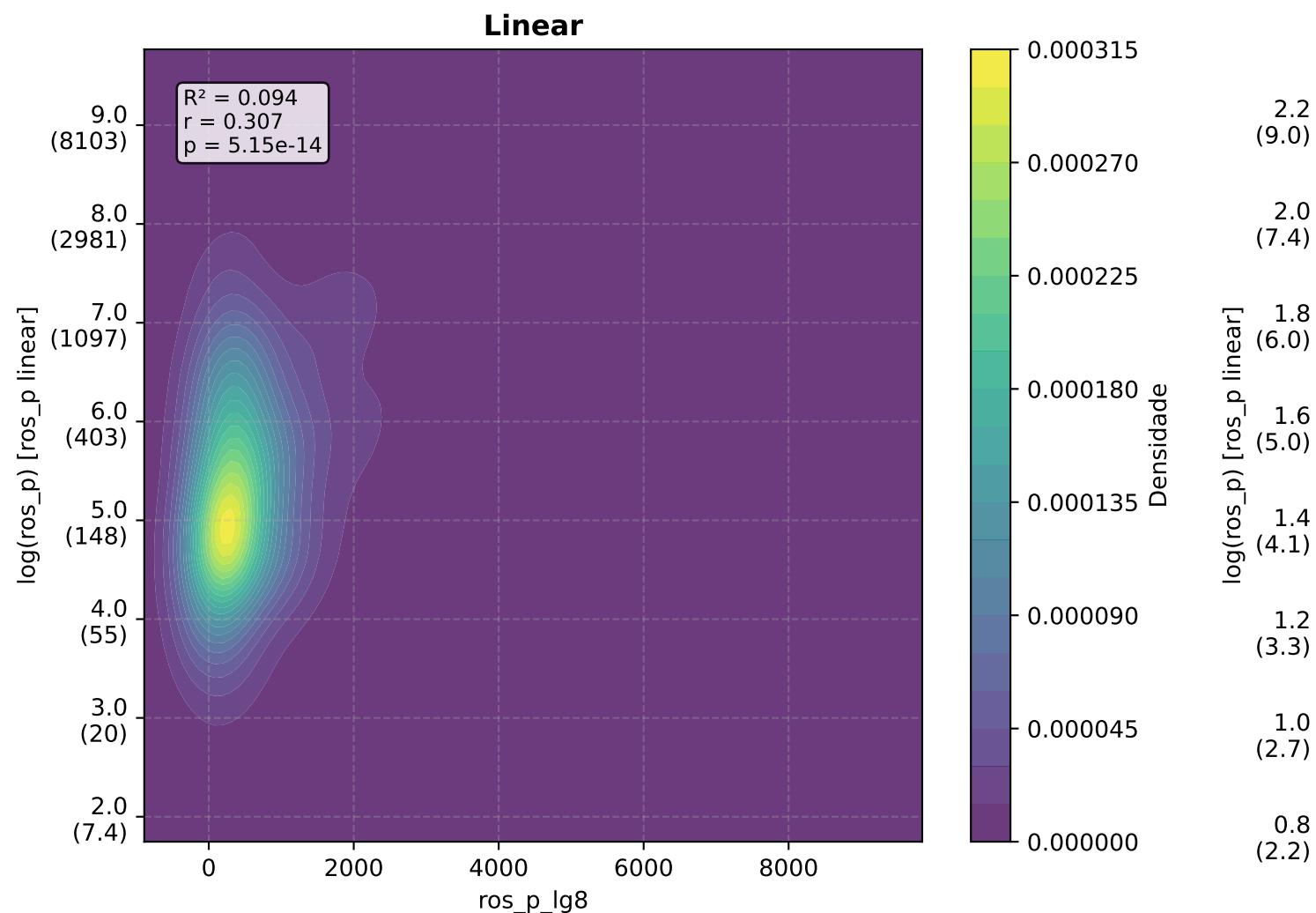
ros_p_lg6 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



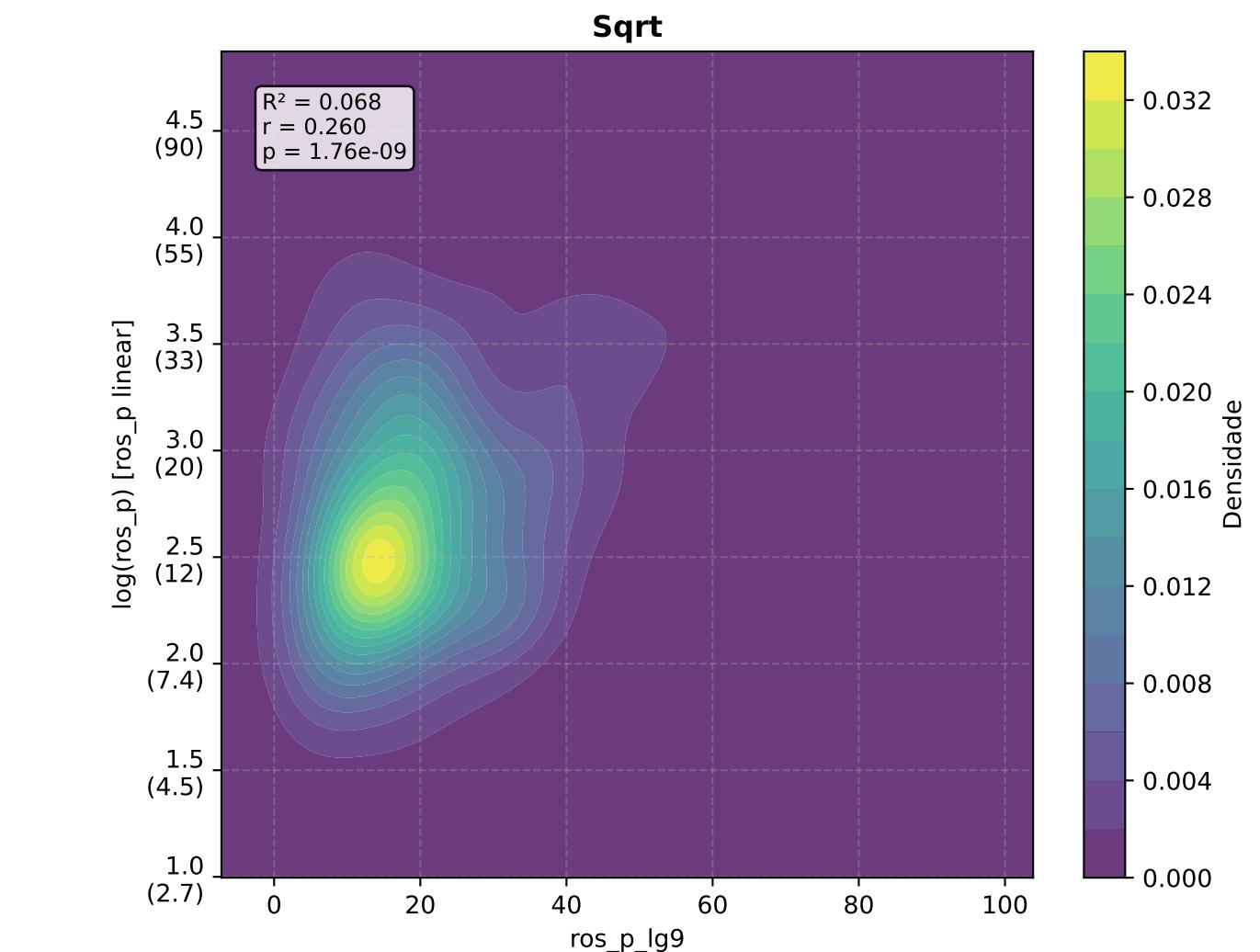
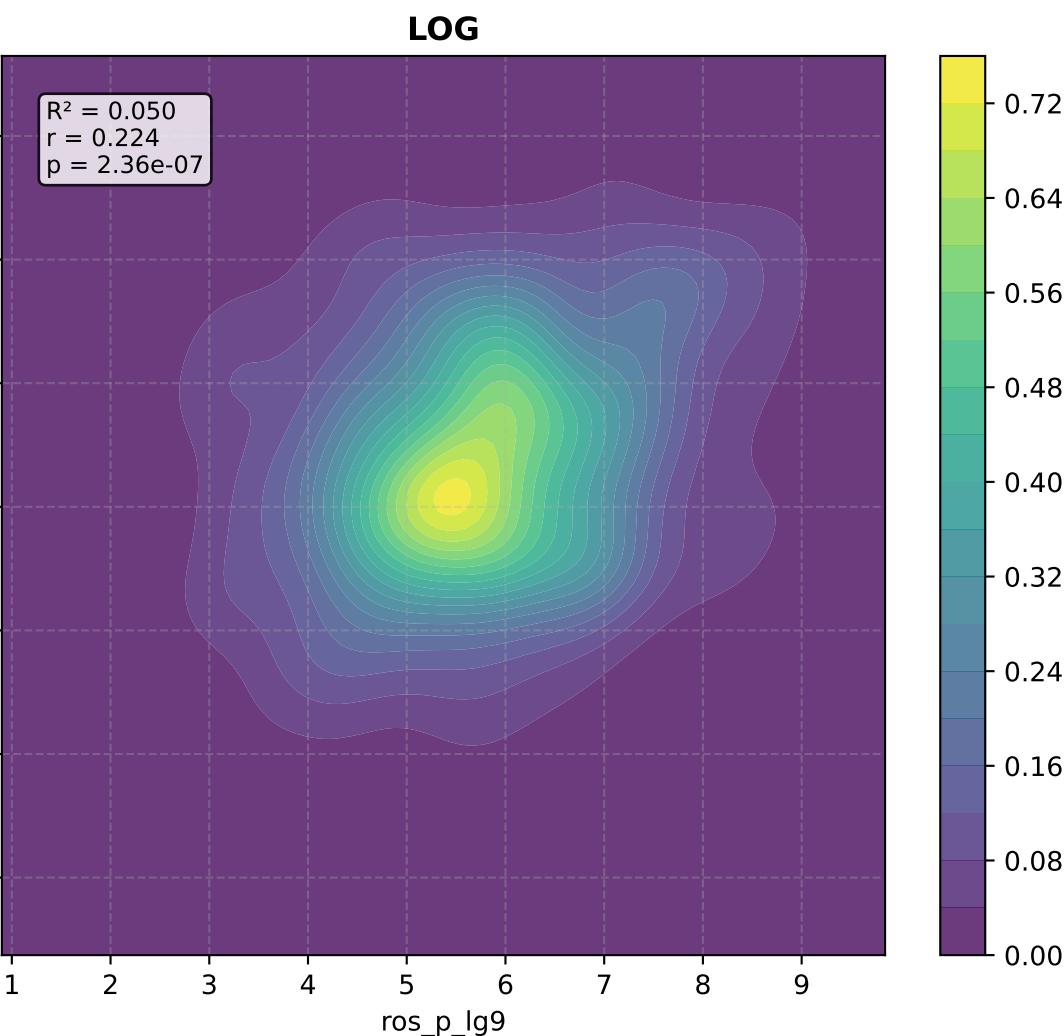
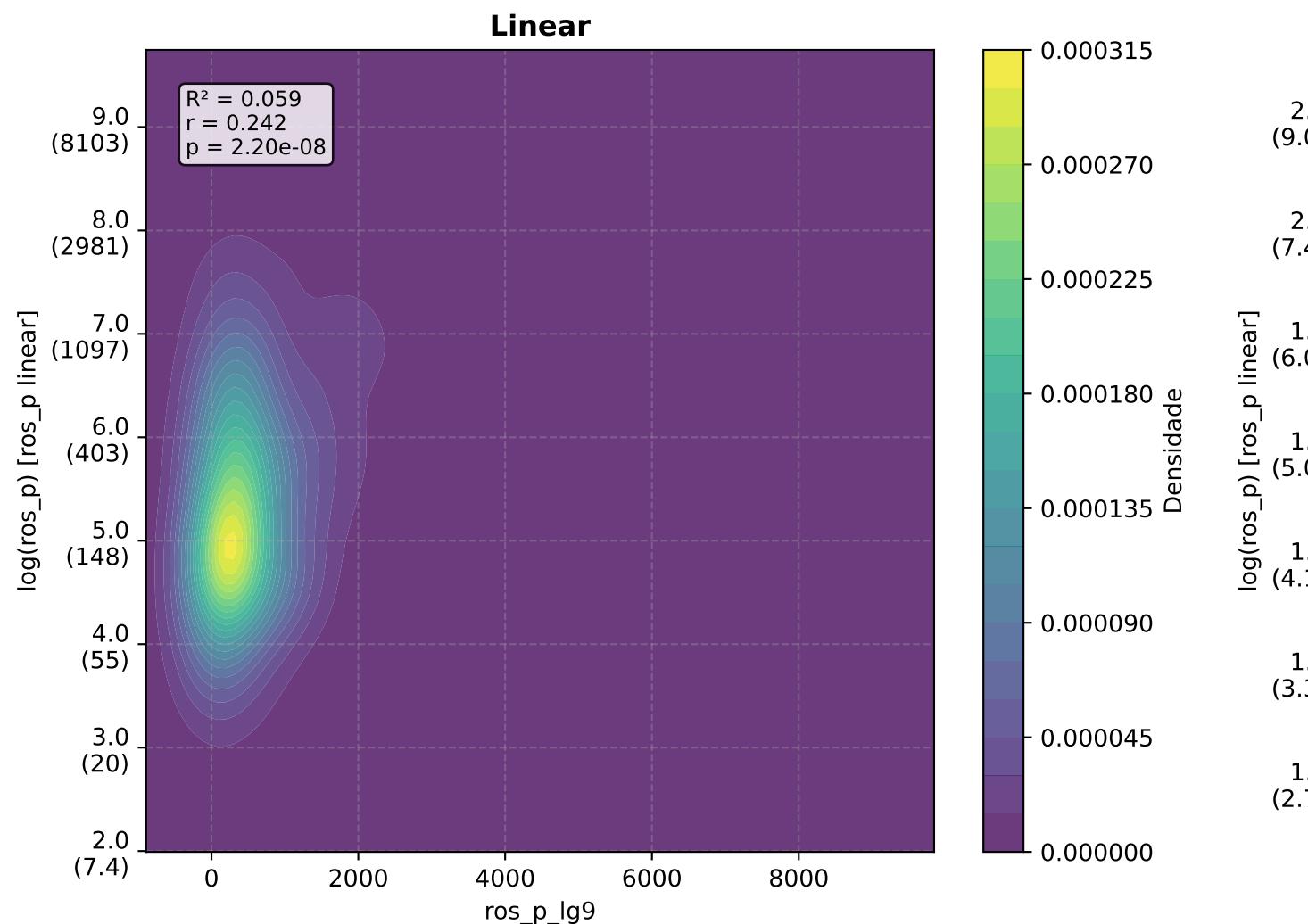
ros_p_lg7 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



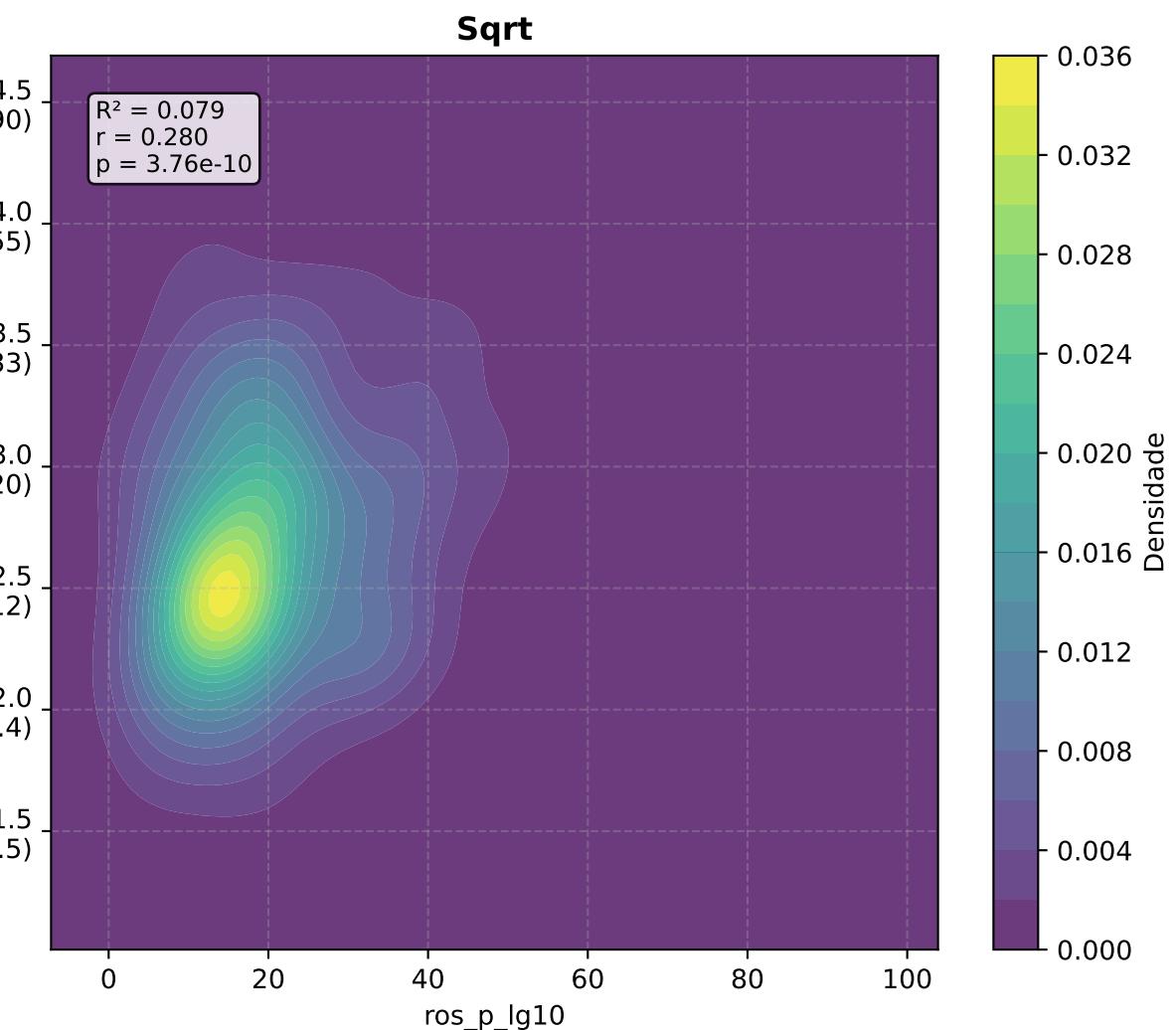
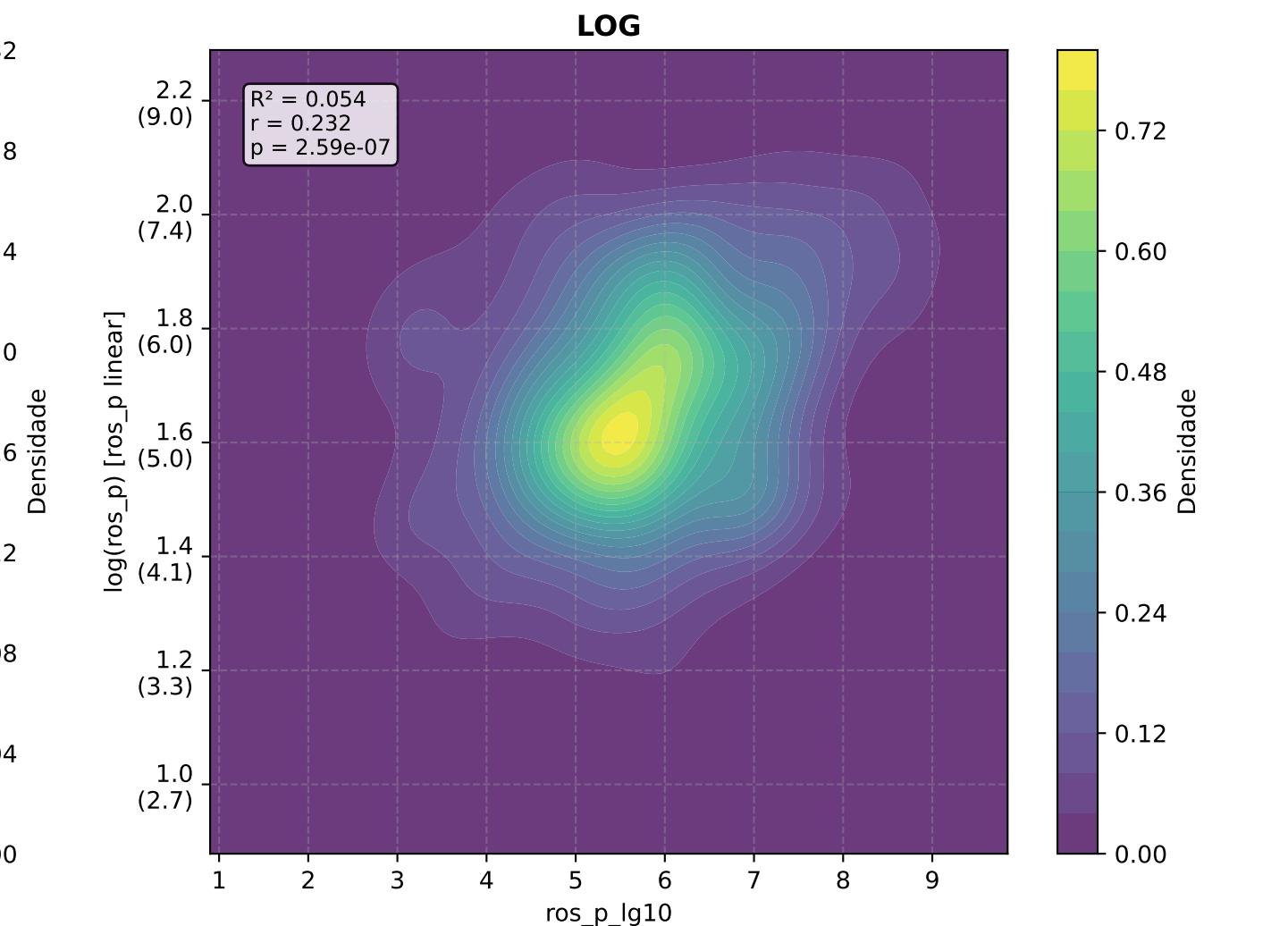
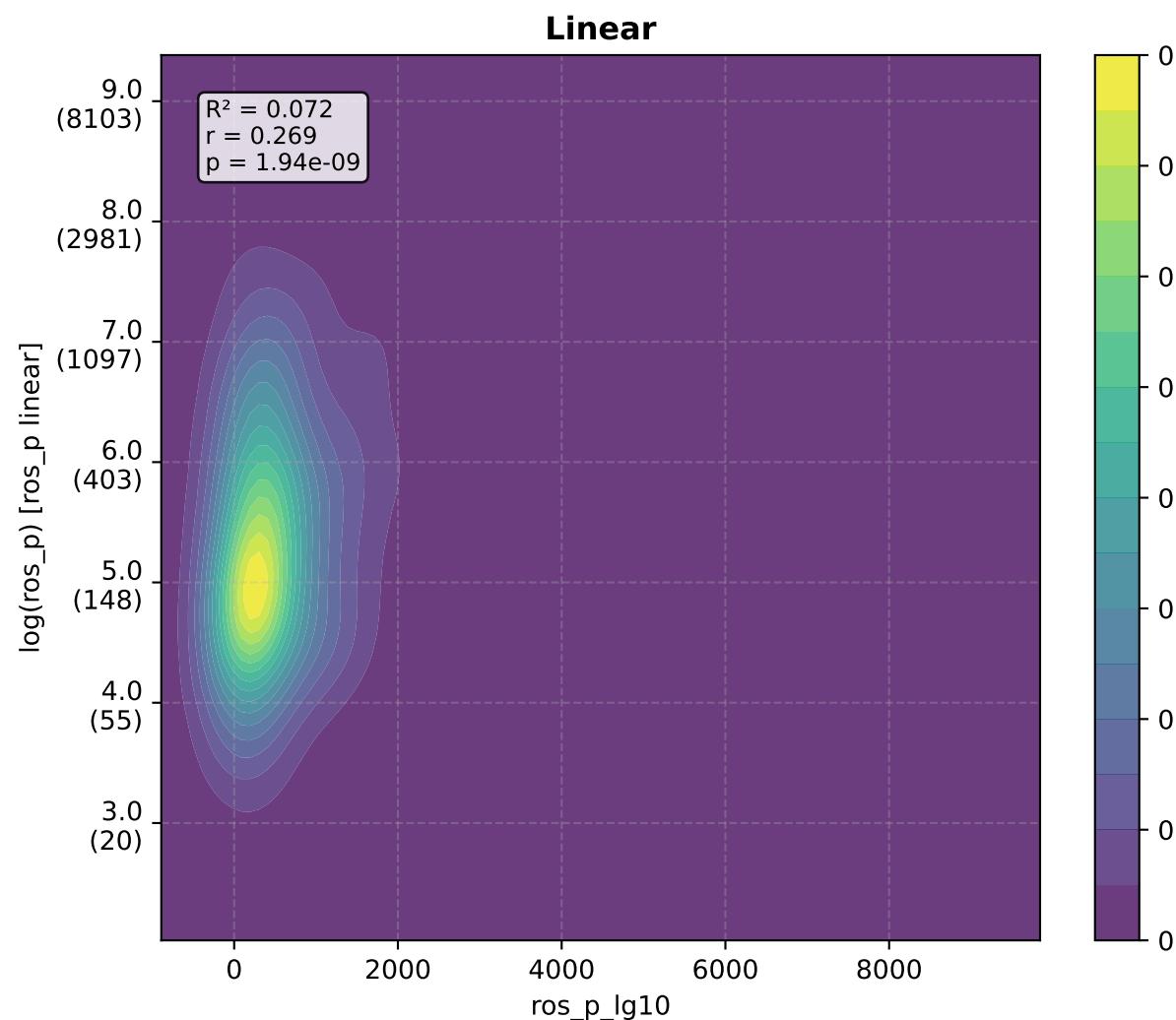
ros_p_lg8 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



ros_p_lg9 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



ros_p_lg10 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



f_start vs ros_p - KDE Cloud (Linear, LOG & Sqrt)

