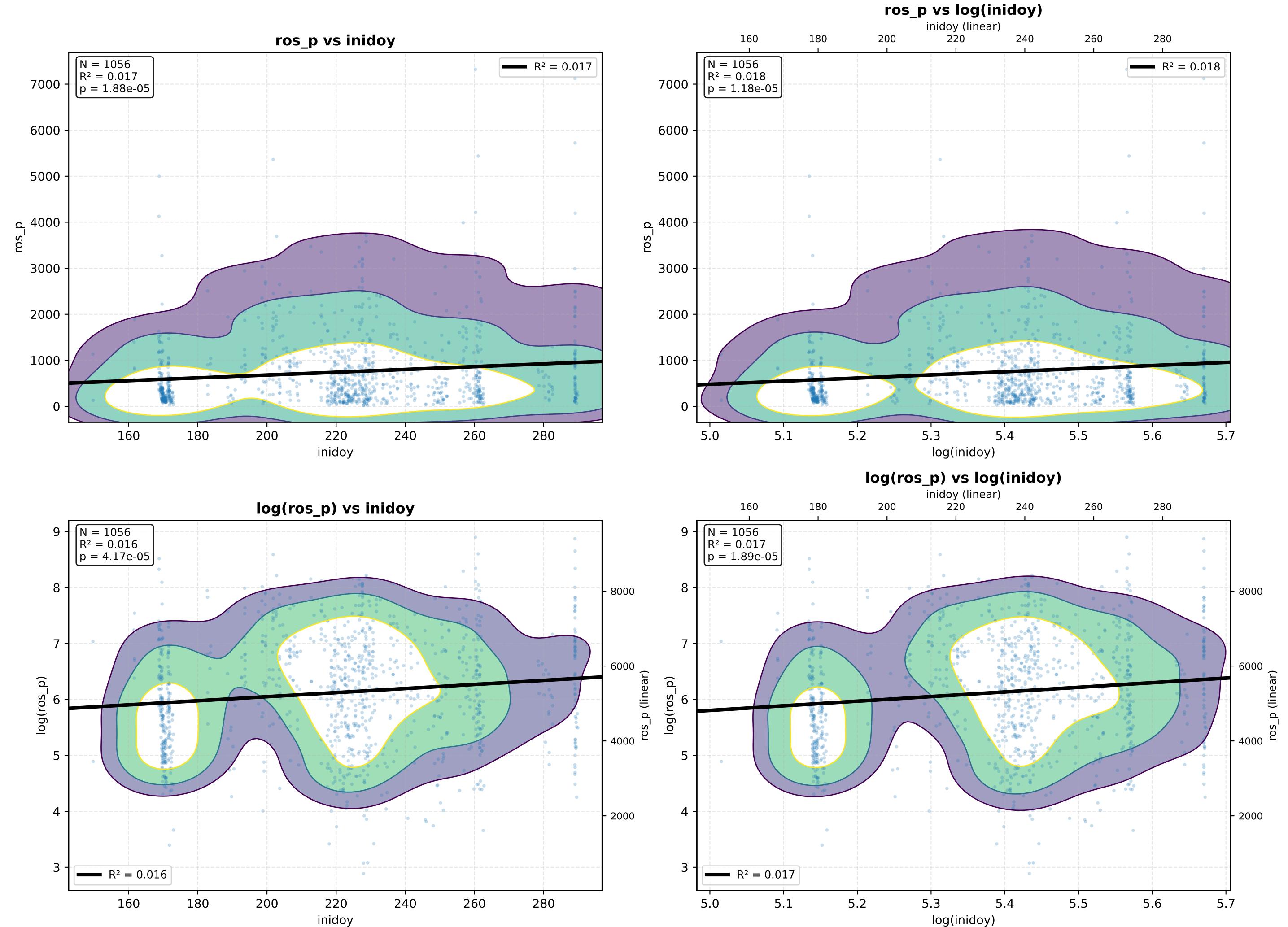
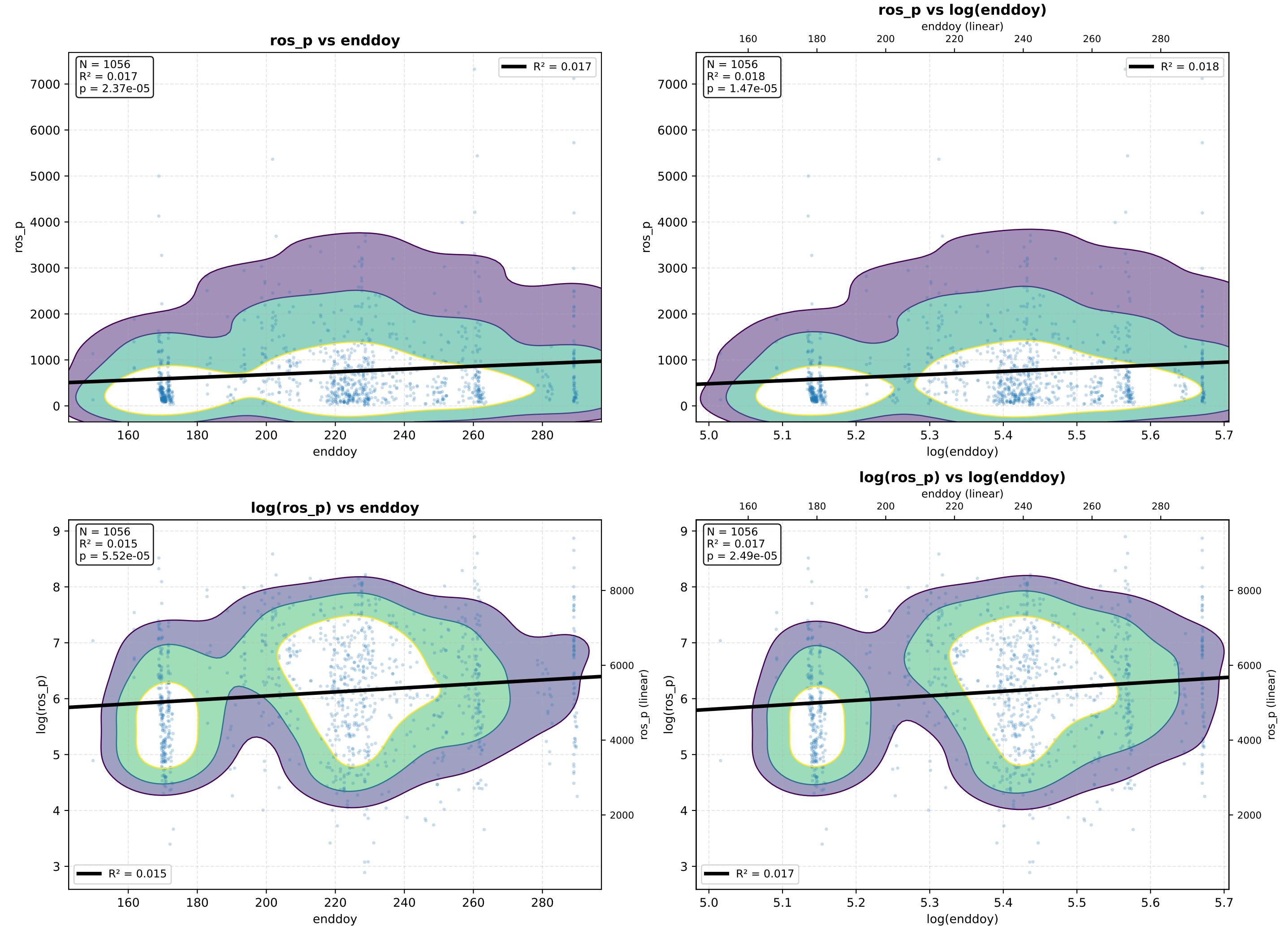


# inidoy – KDE Density + Regressão

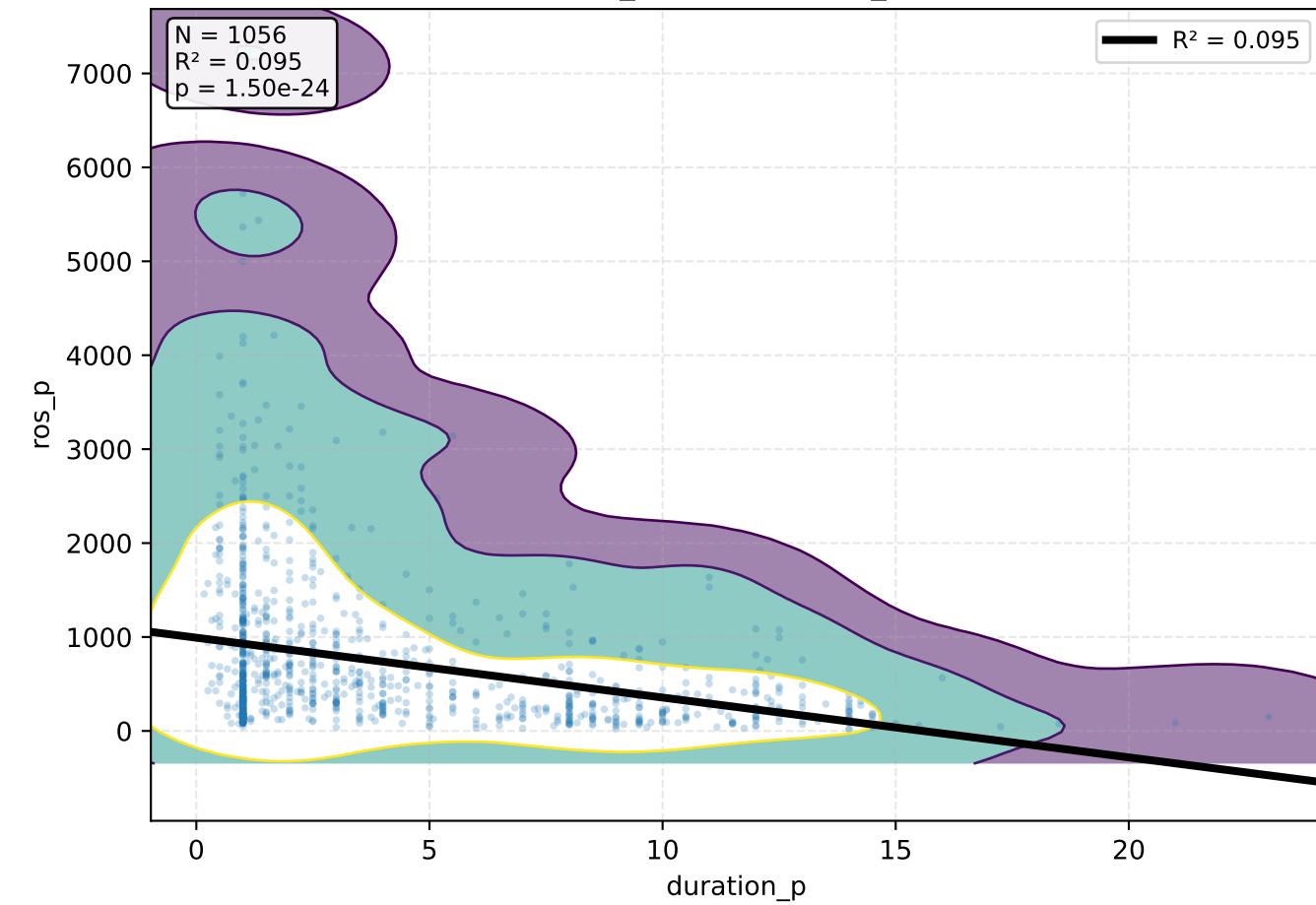


# enddoy – KDE Density + Regressão

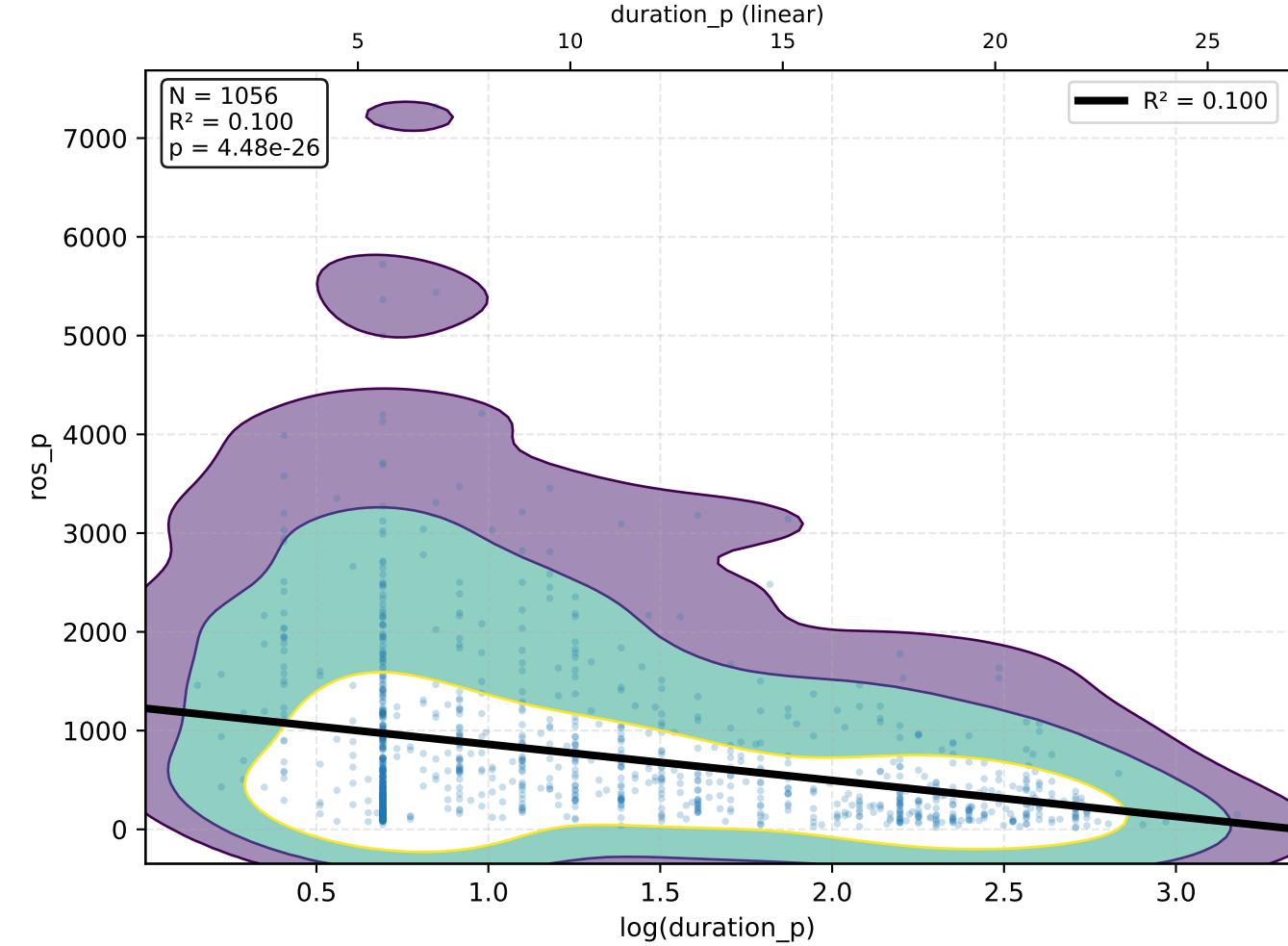


# duration\_p - KDE Density + Regressão

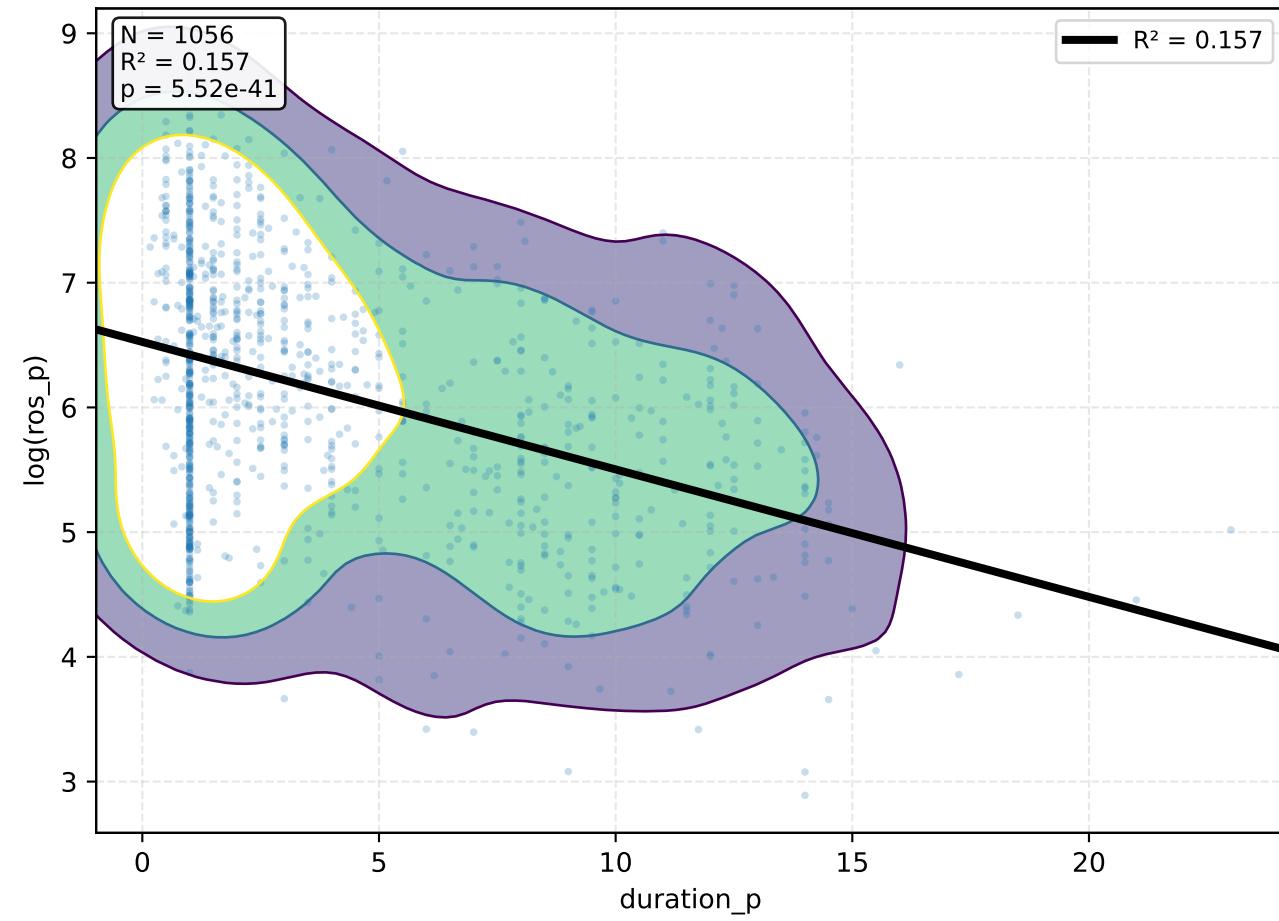
**ros\_p vs duration\_p**



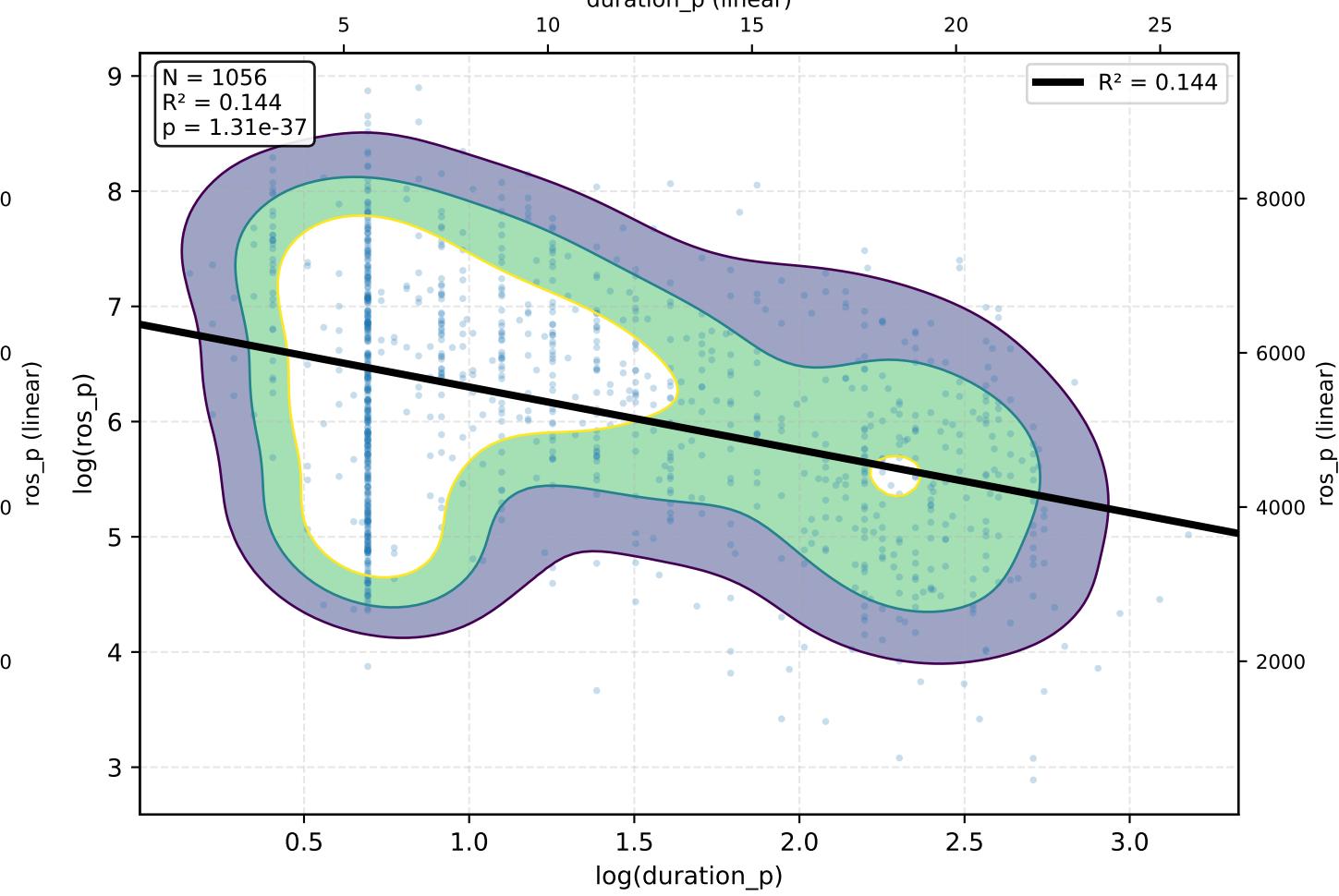
**ros\_p vs log(duration\_p)**



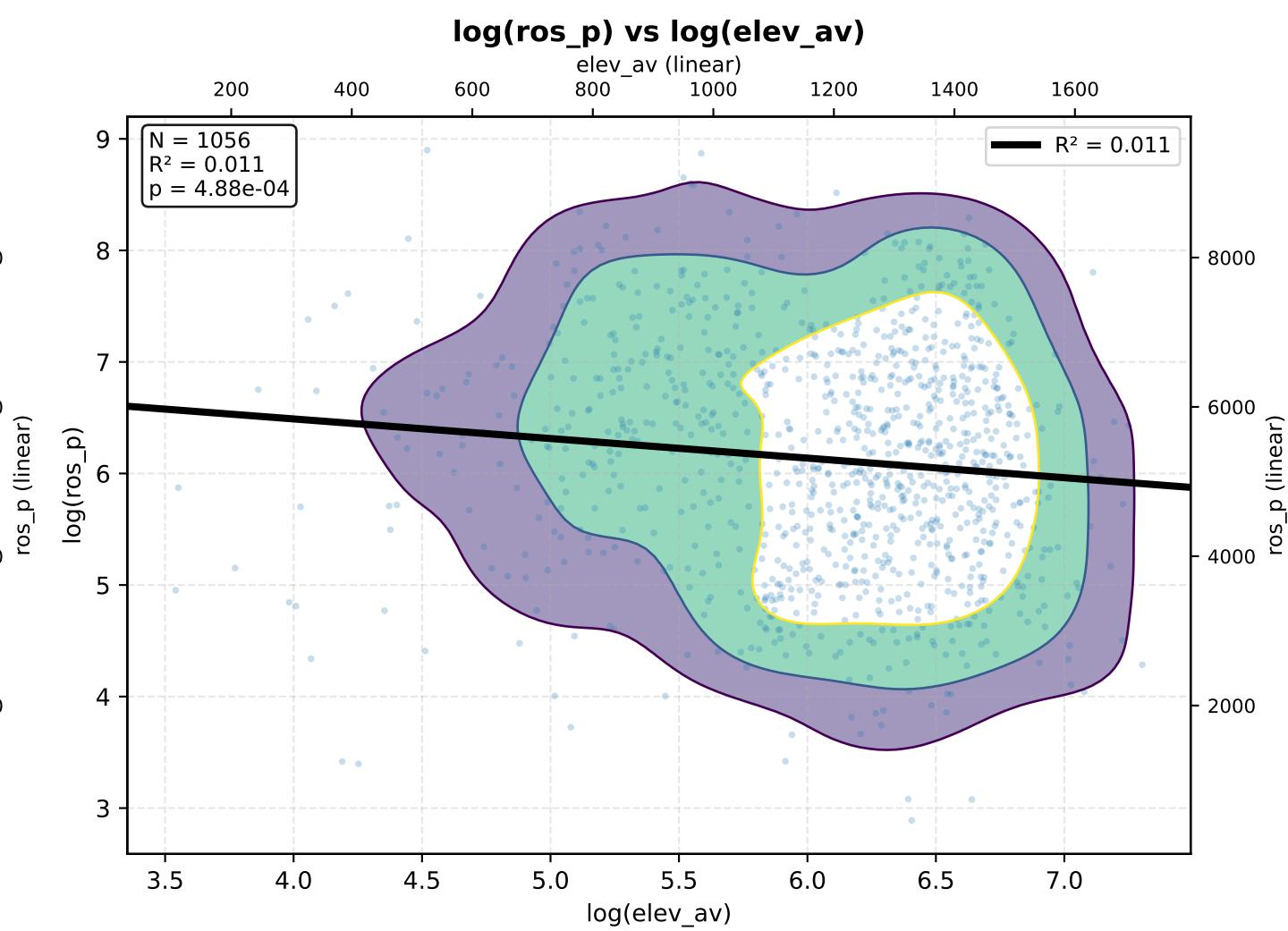
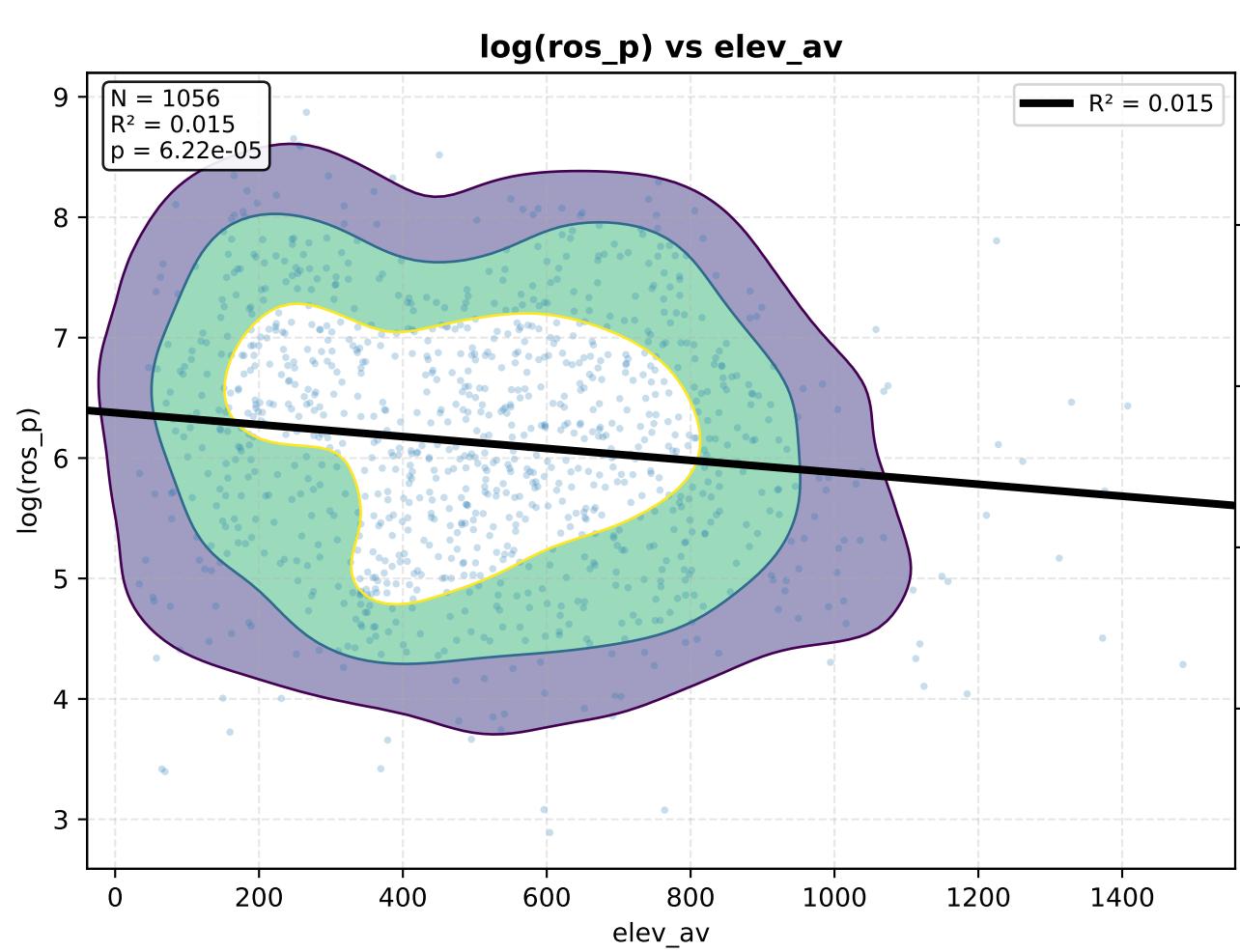
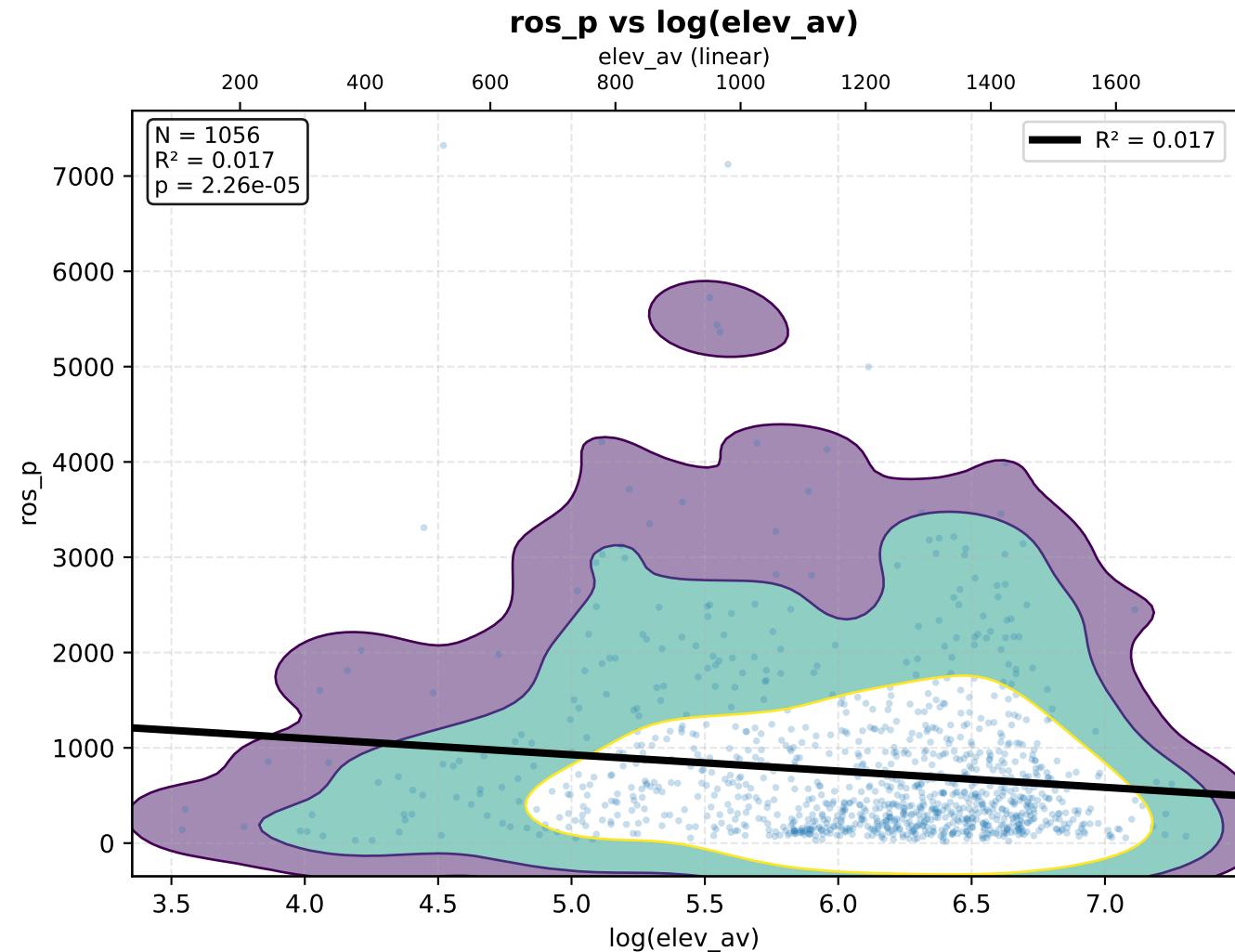
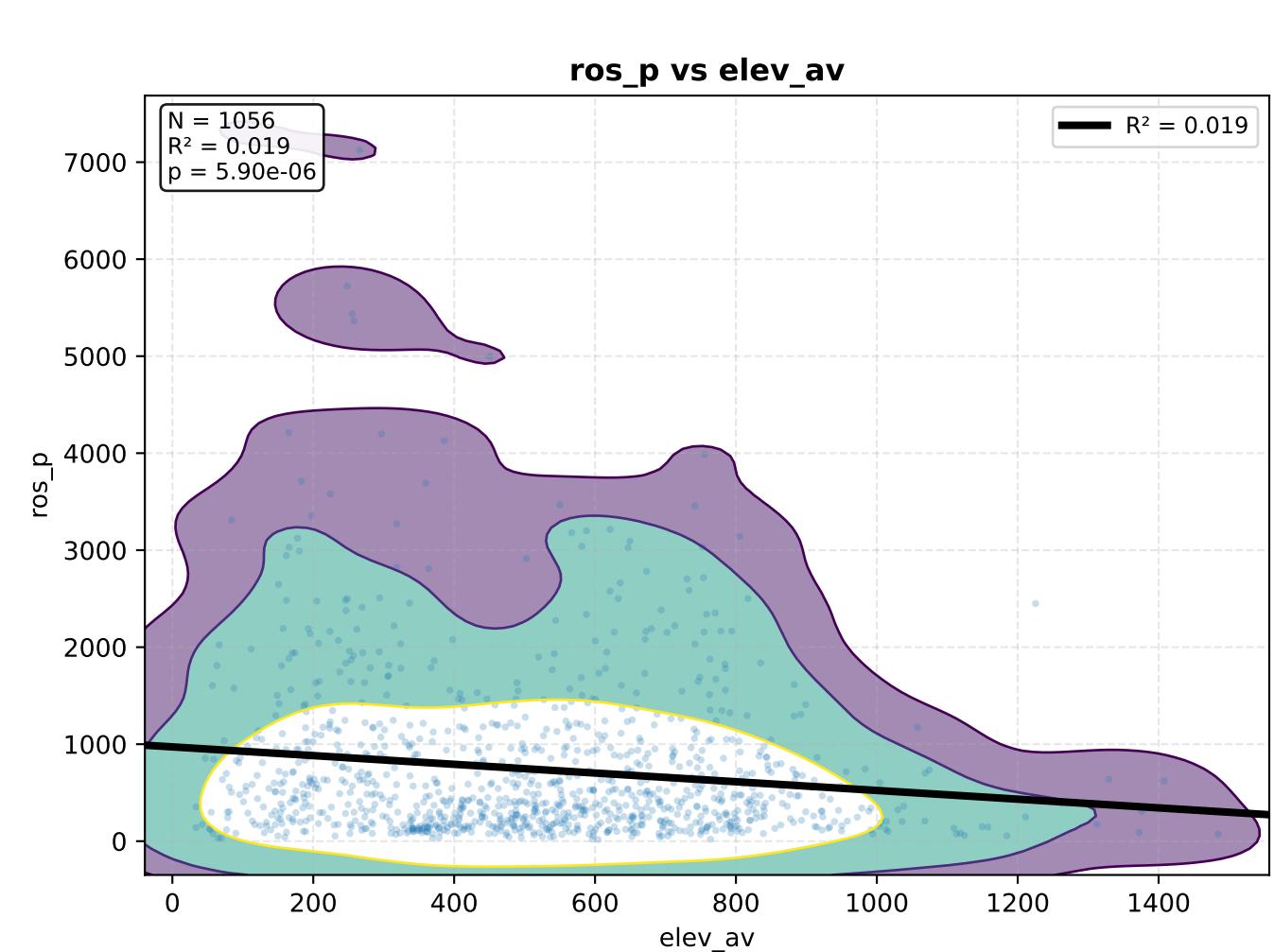
**log(ros\_p) vs duration\_p**



**log(ros\_p) vs log(duration\_p)**

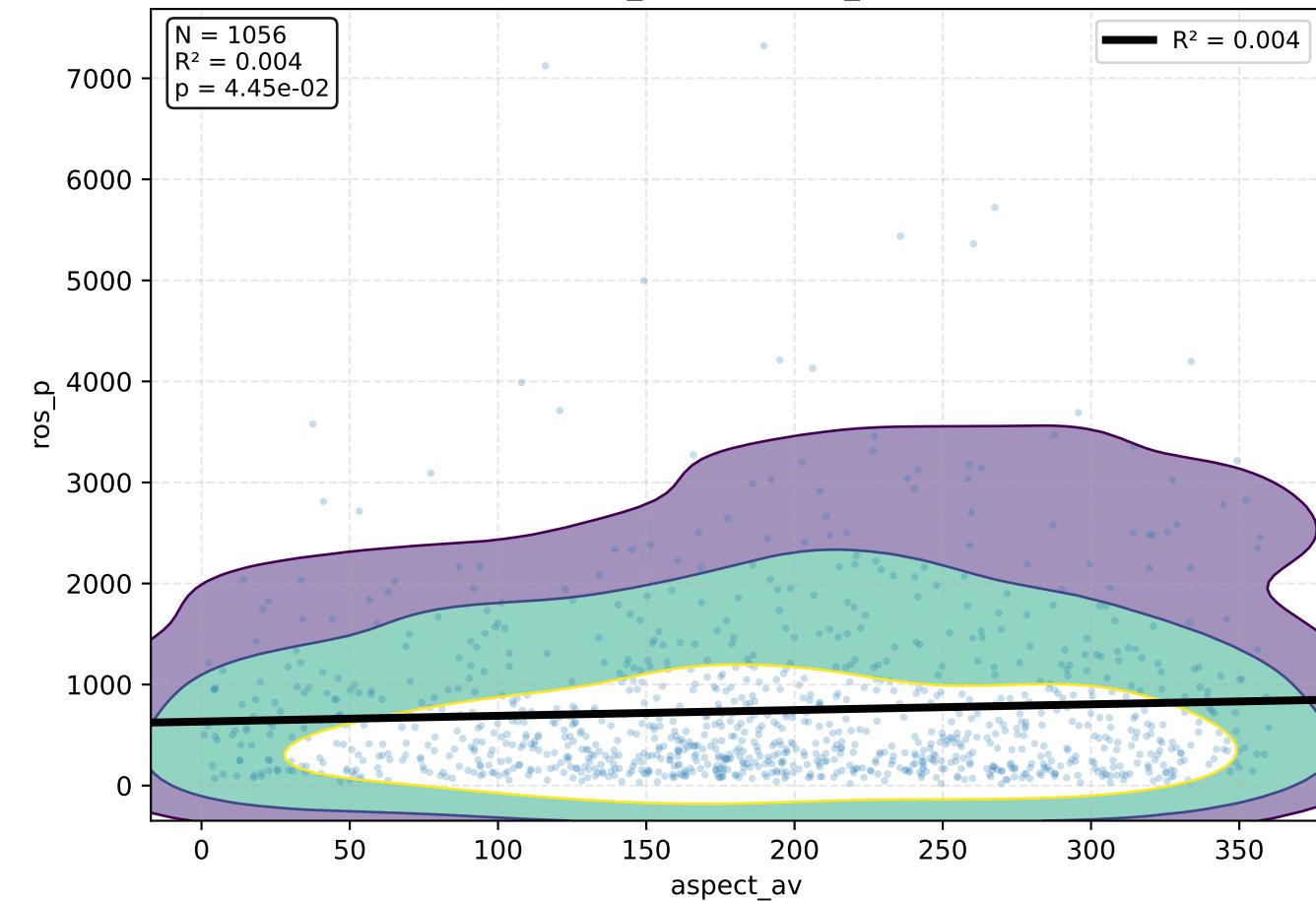


# elev\_av - KDE Density + Regressão

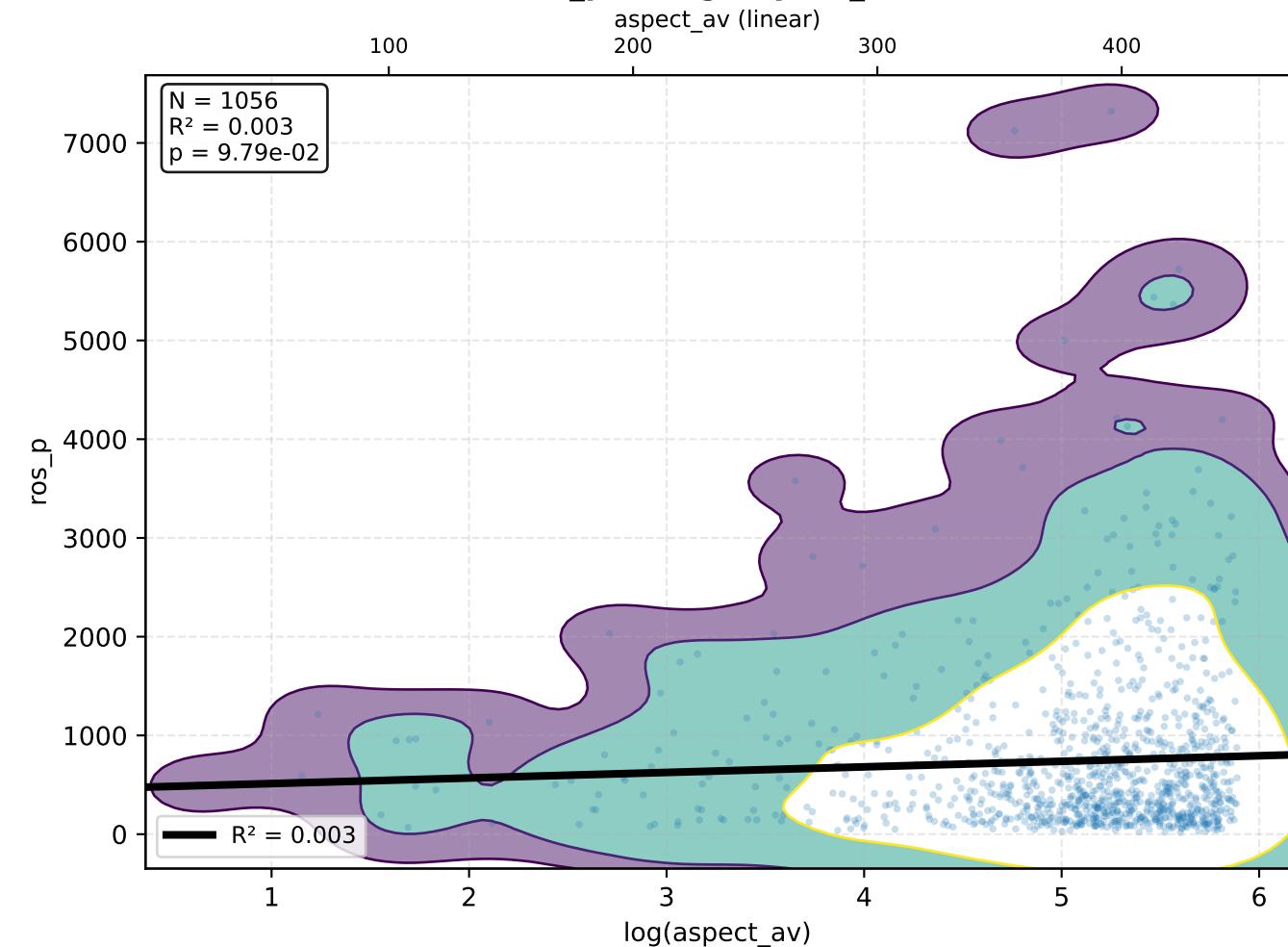


# aspect\_av – KDE Density + Regressão

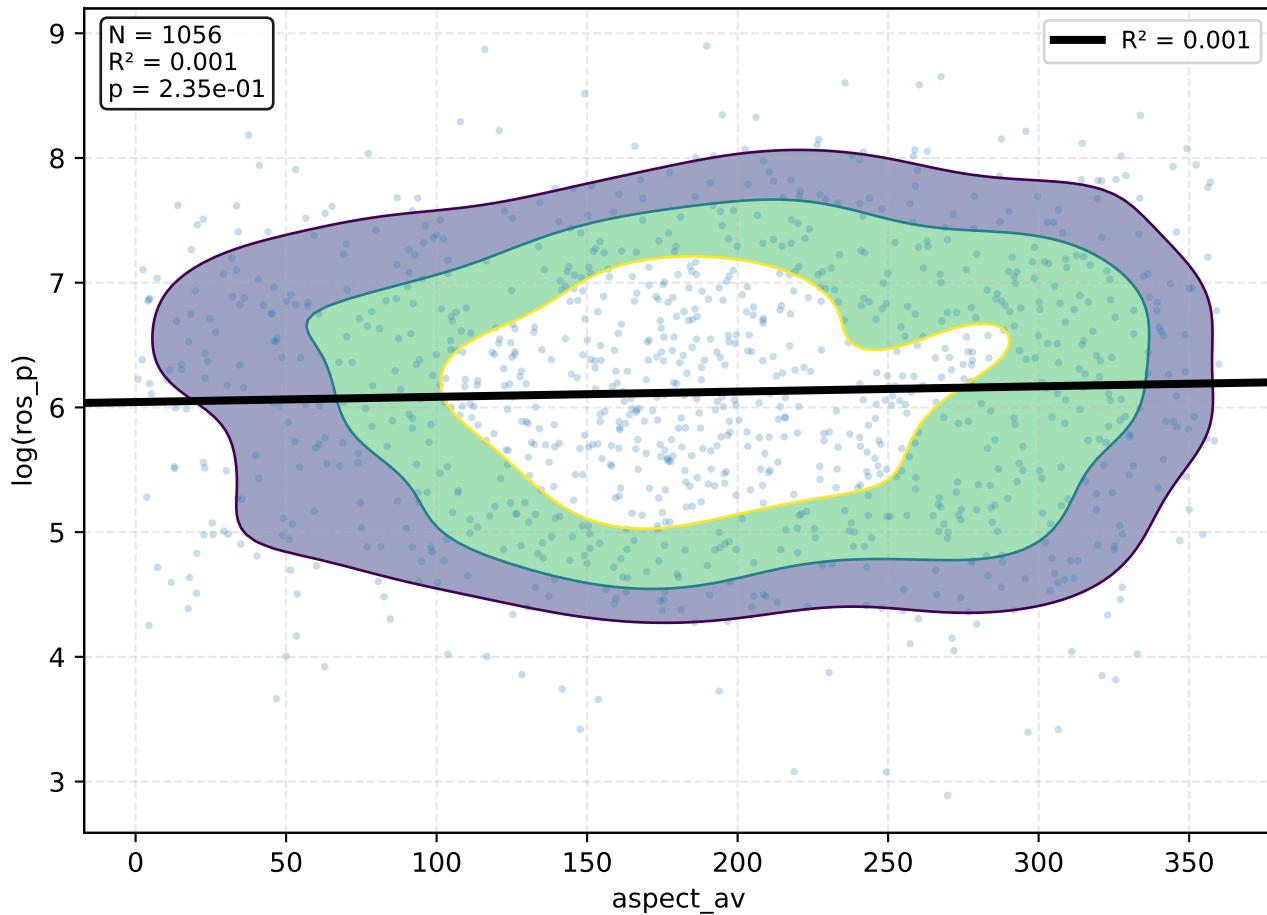
**ros\_p vs aspect\_av**



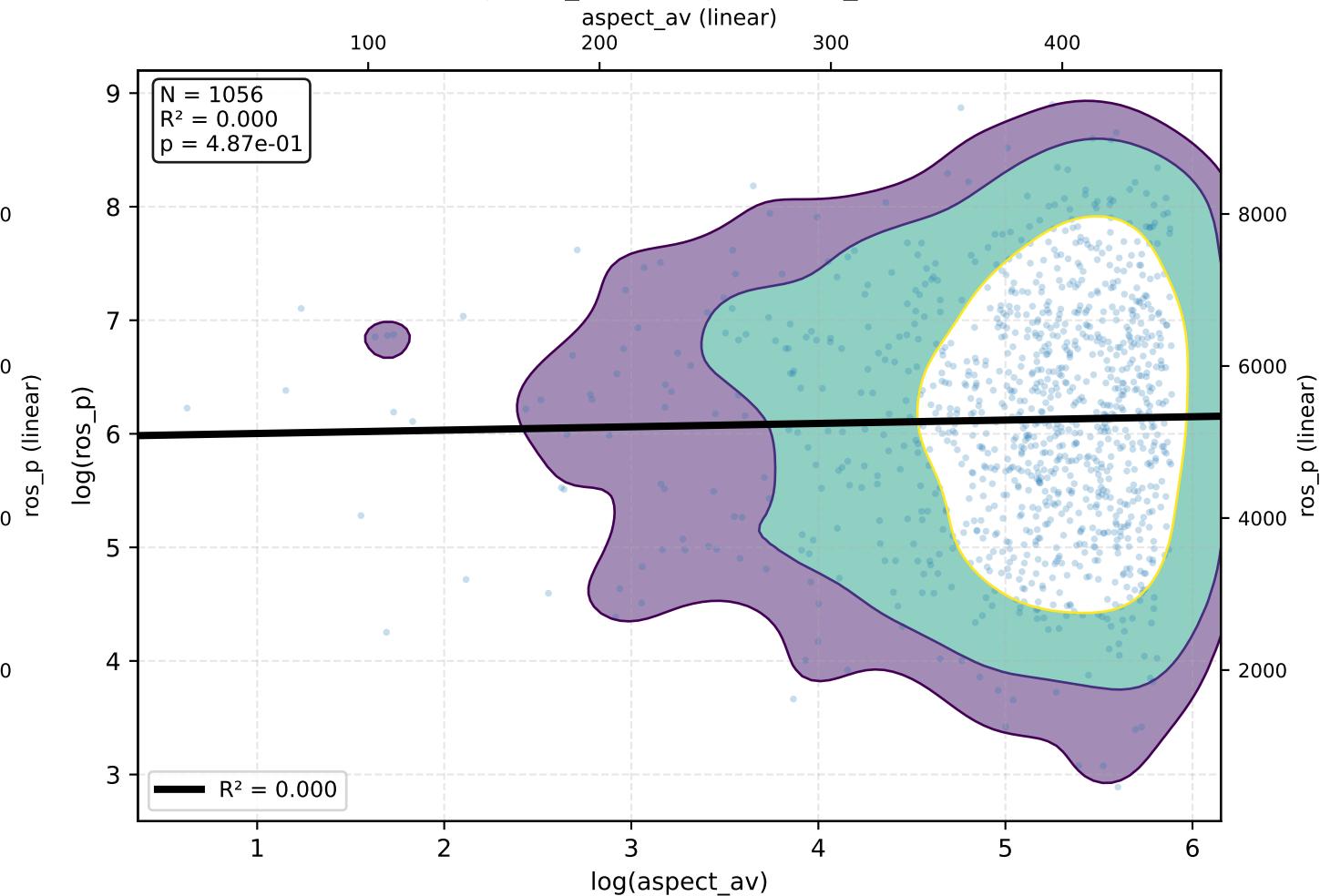
**ros\_p vs log(aspect\_av)**



**log(ros\_p) vs aspect\_av**

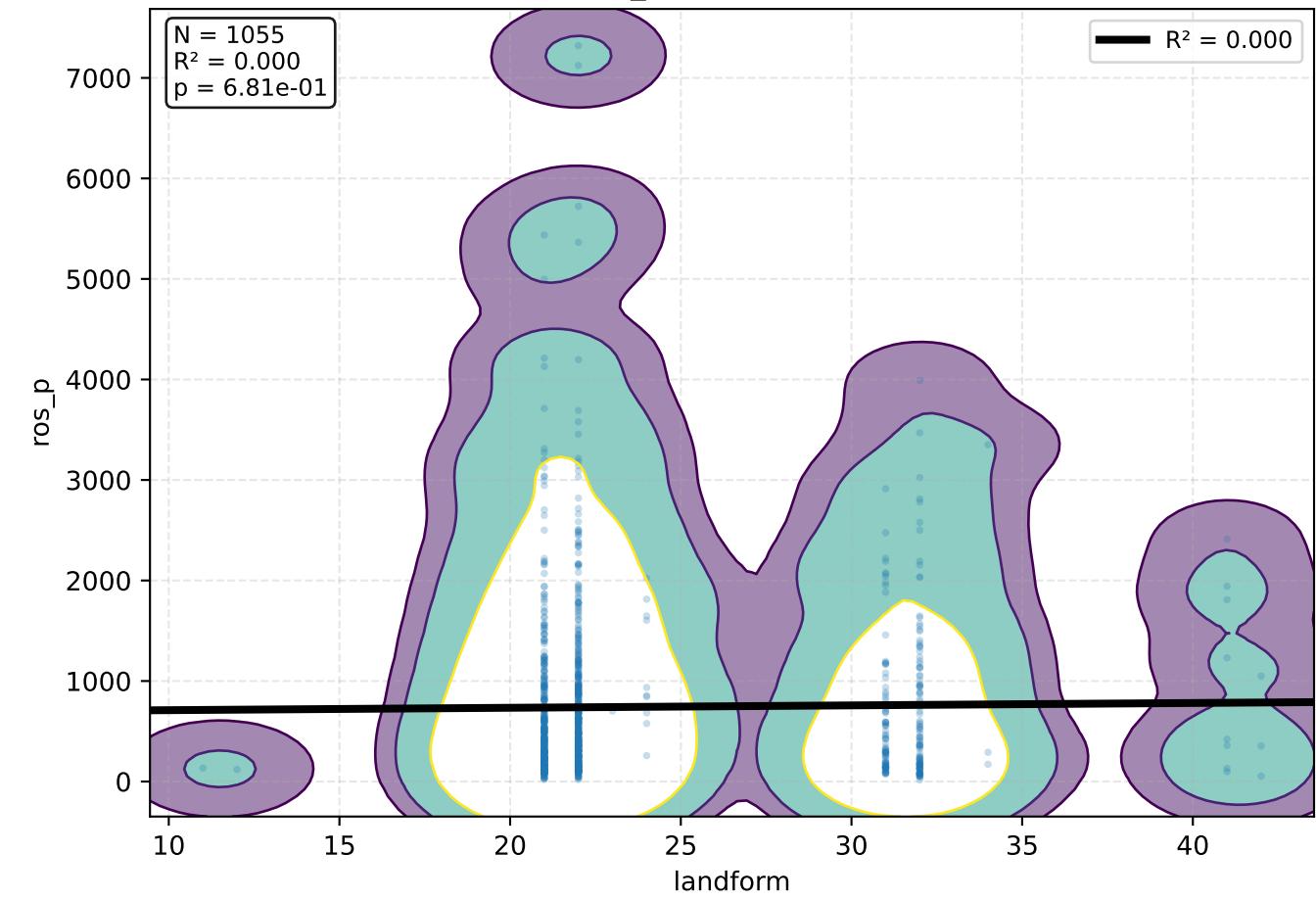


**log(ros\_p) vs log(aspect\_av)**

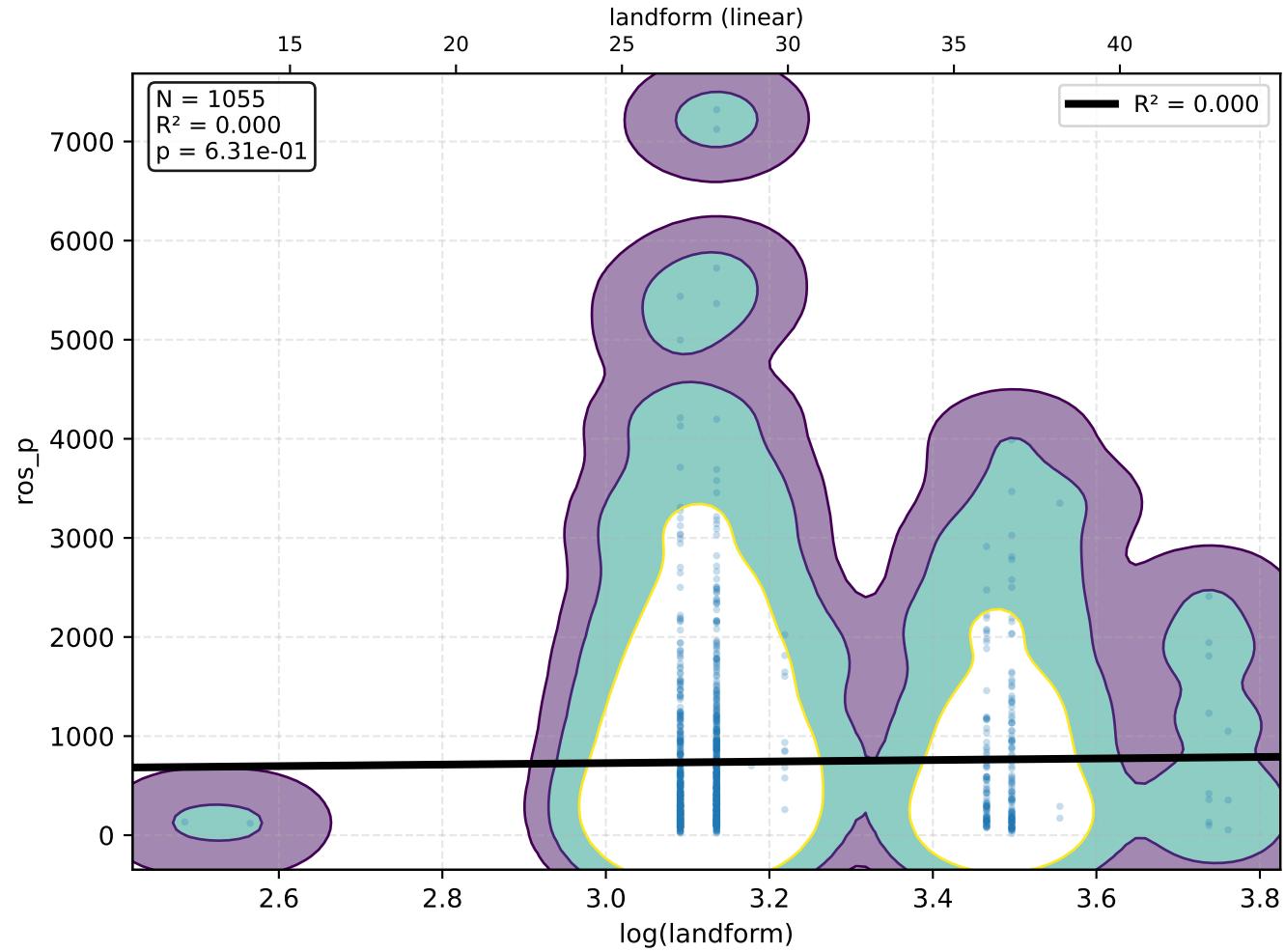


# landform – KDE Density + Regressão

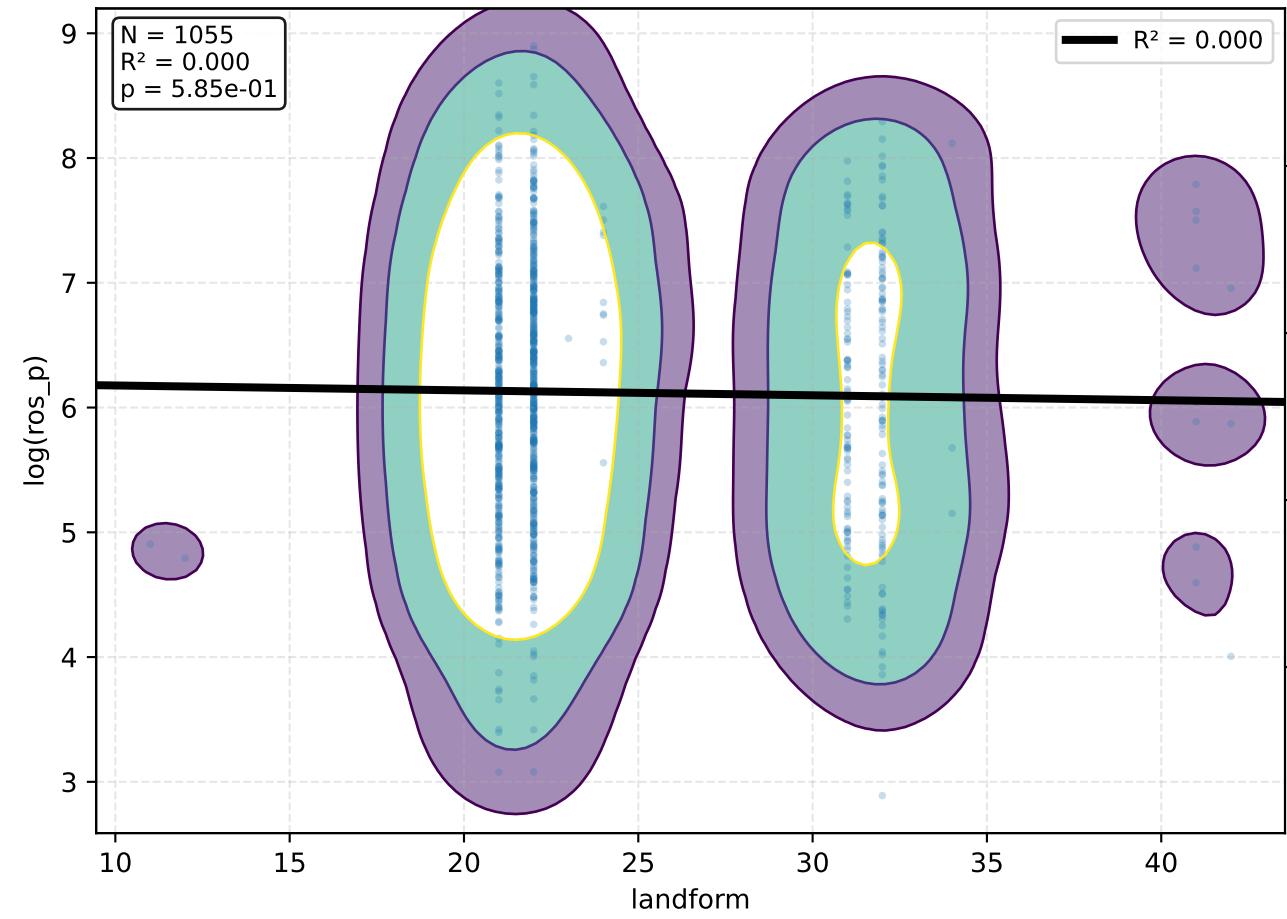
**ros\_p vs landform**



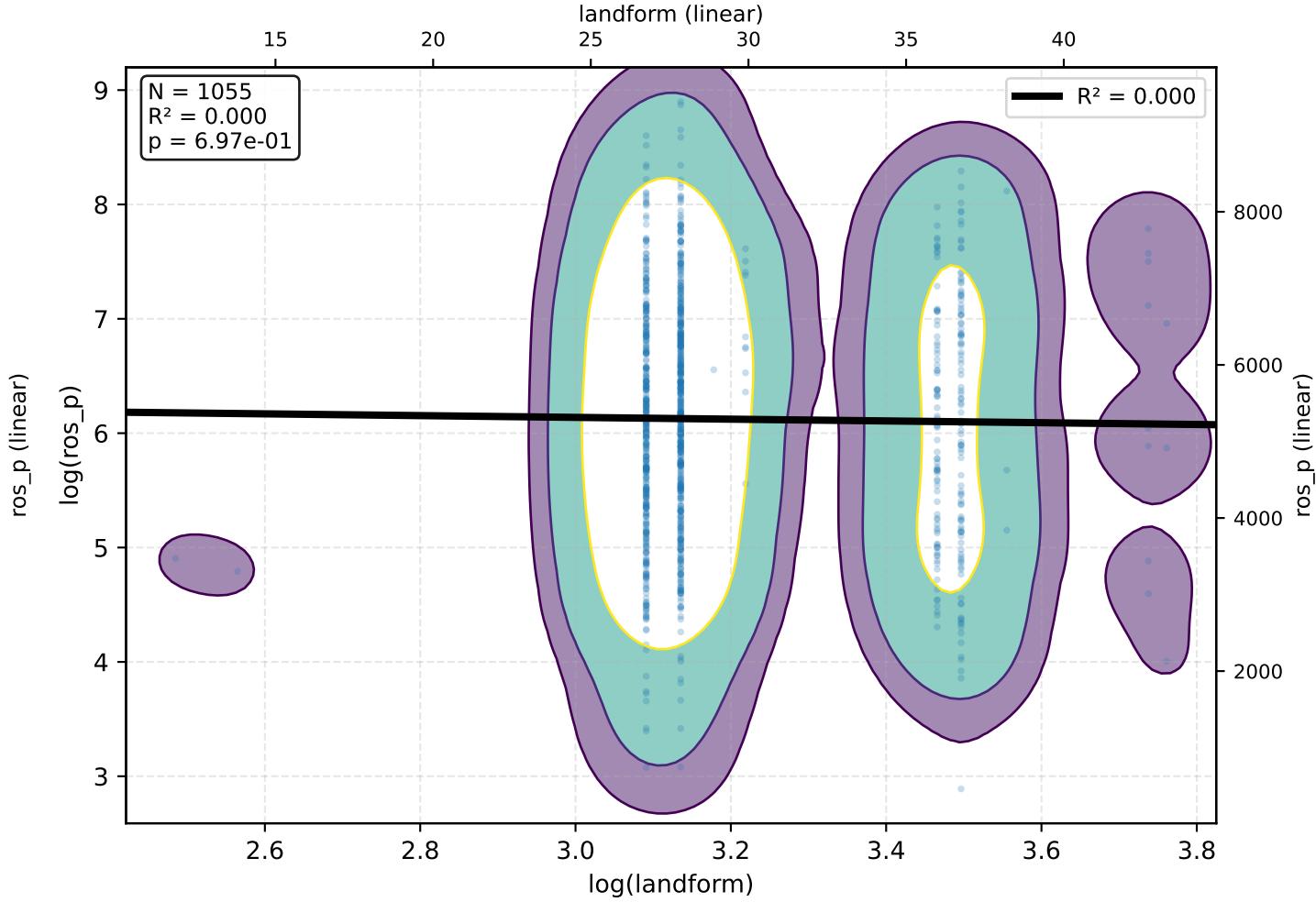
**ros\_p vs log(landform)**



**log(ros\_p) vs landform**

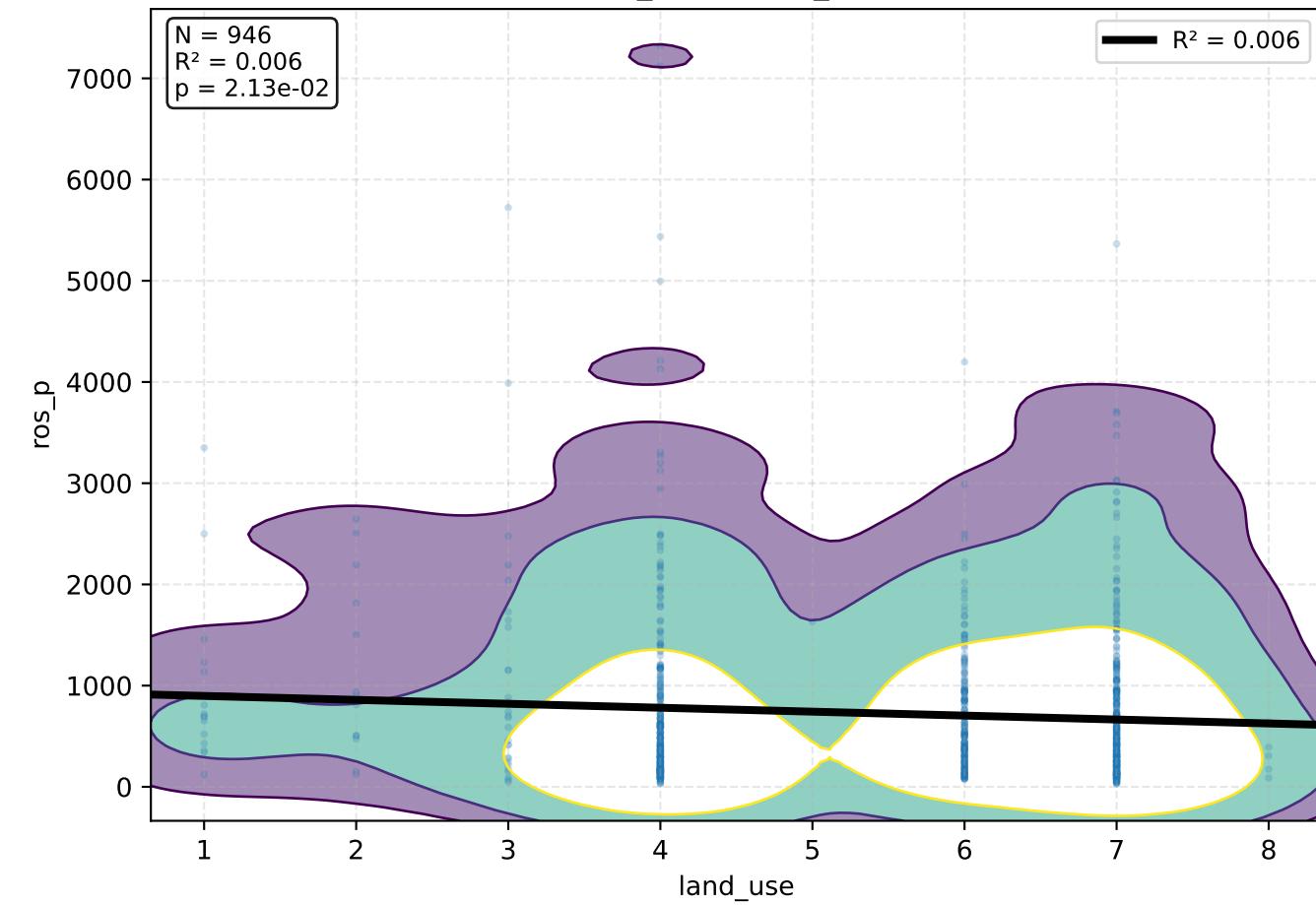


**log(ros\_p) vs log(landform)**

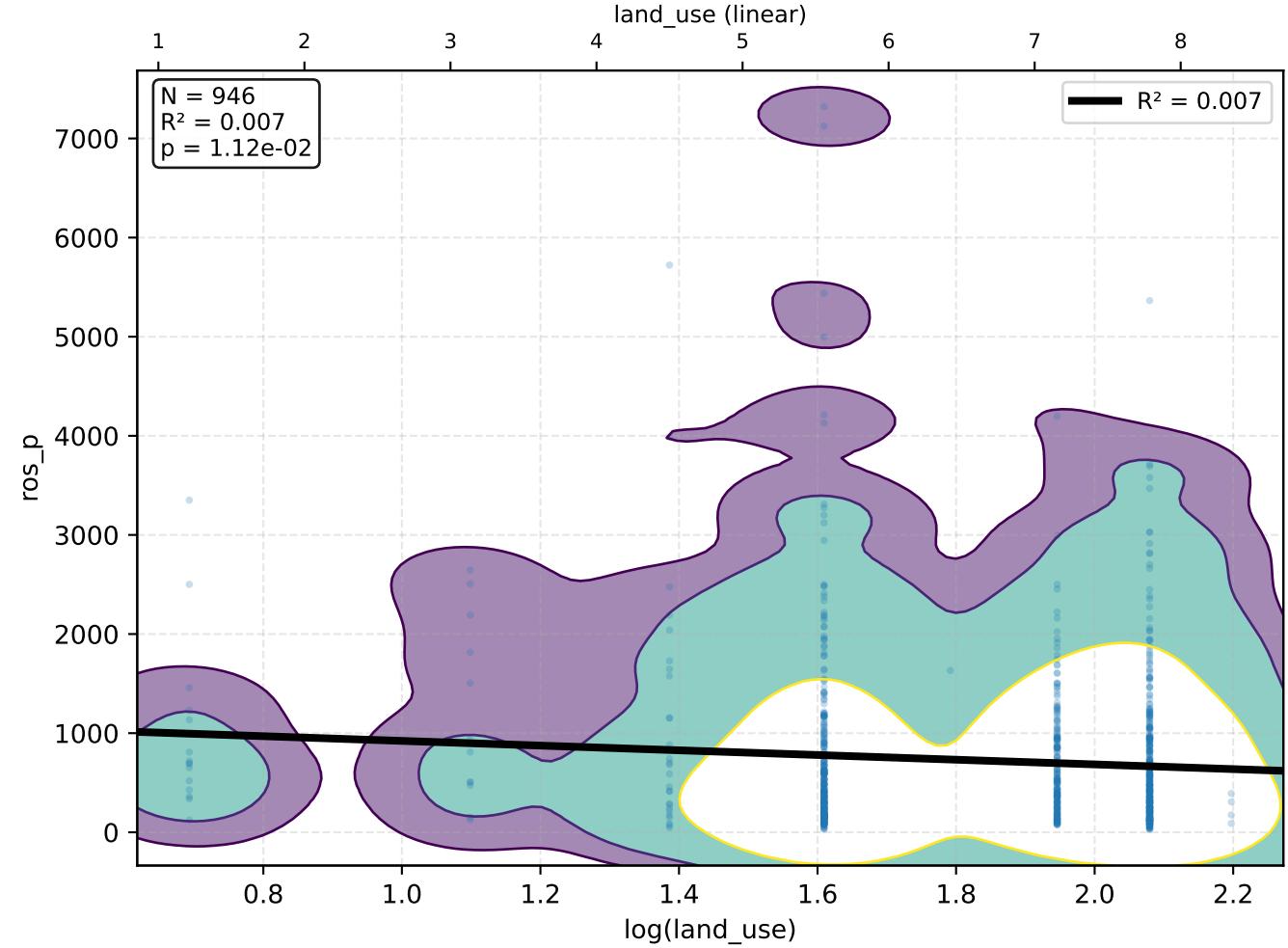


# land\_use – KDE Density + Regressão

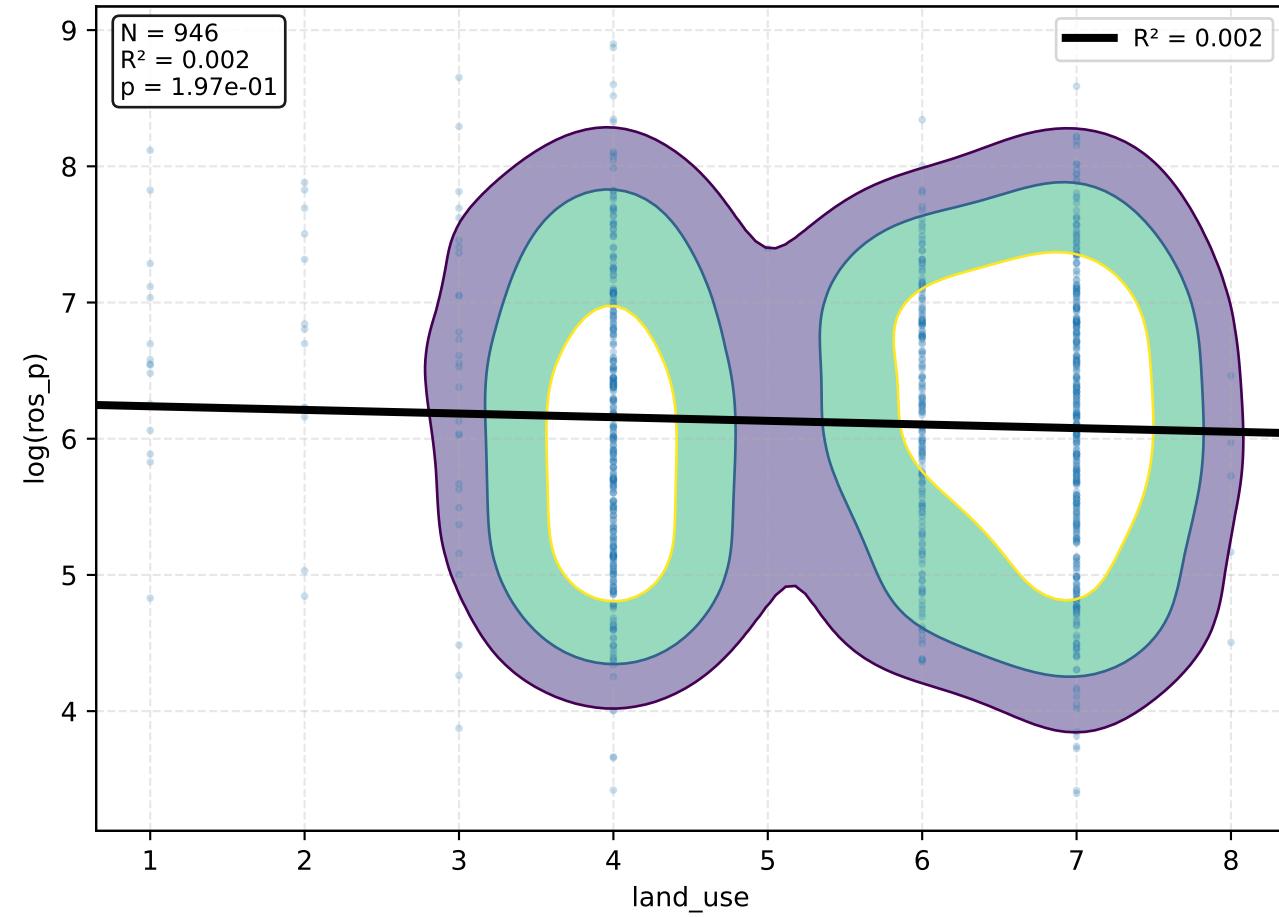
**ros\_p vs land\_use**



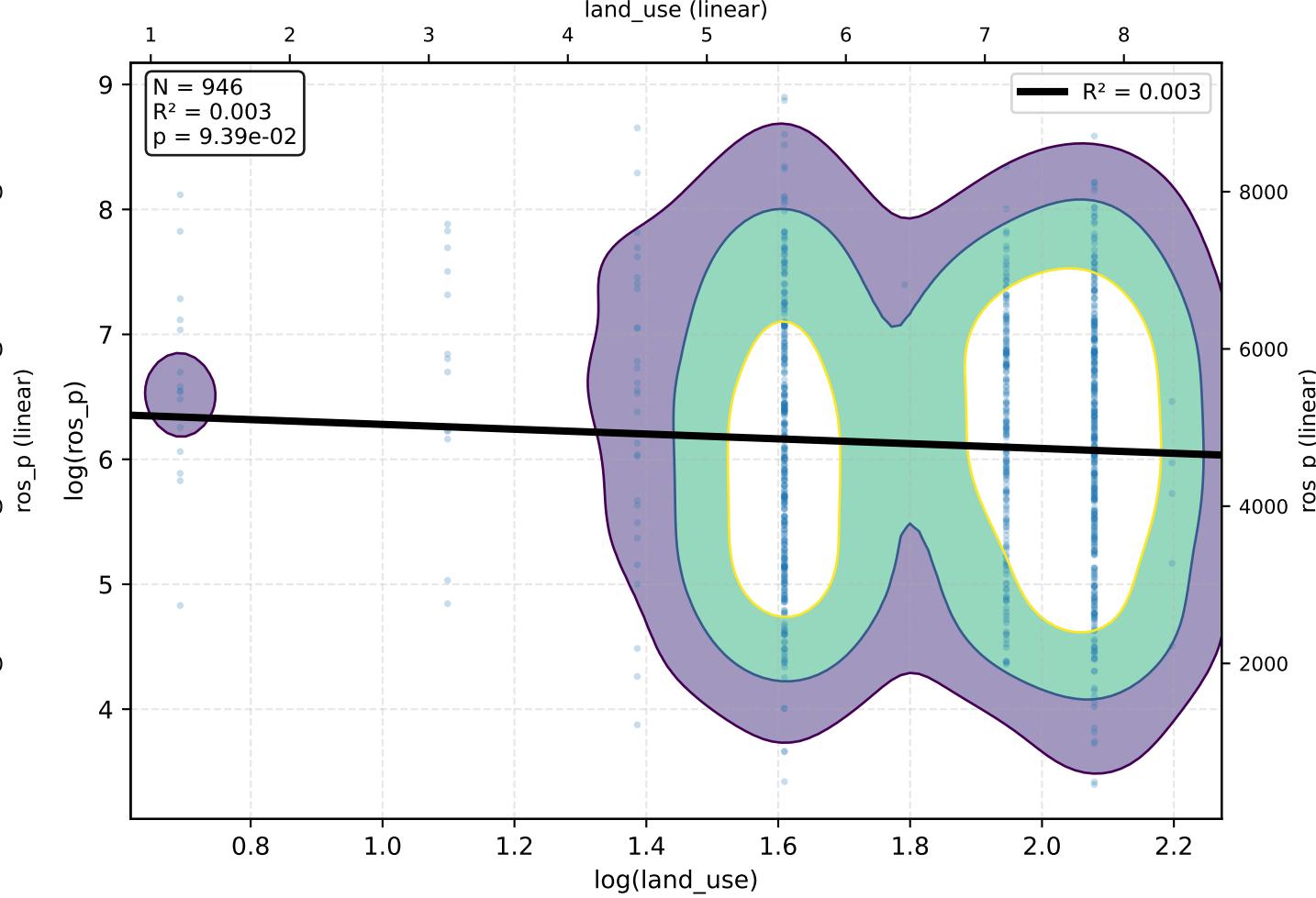
**ros\_p vs log(land\_use)**



**log(ros\_p) vs land\_use**

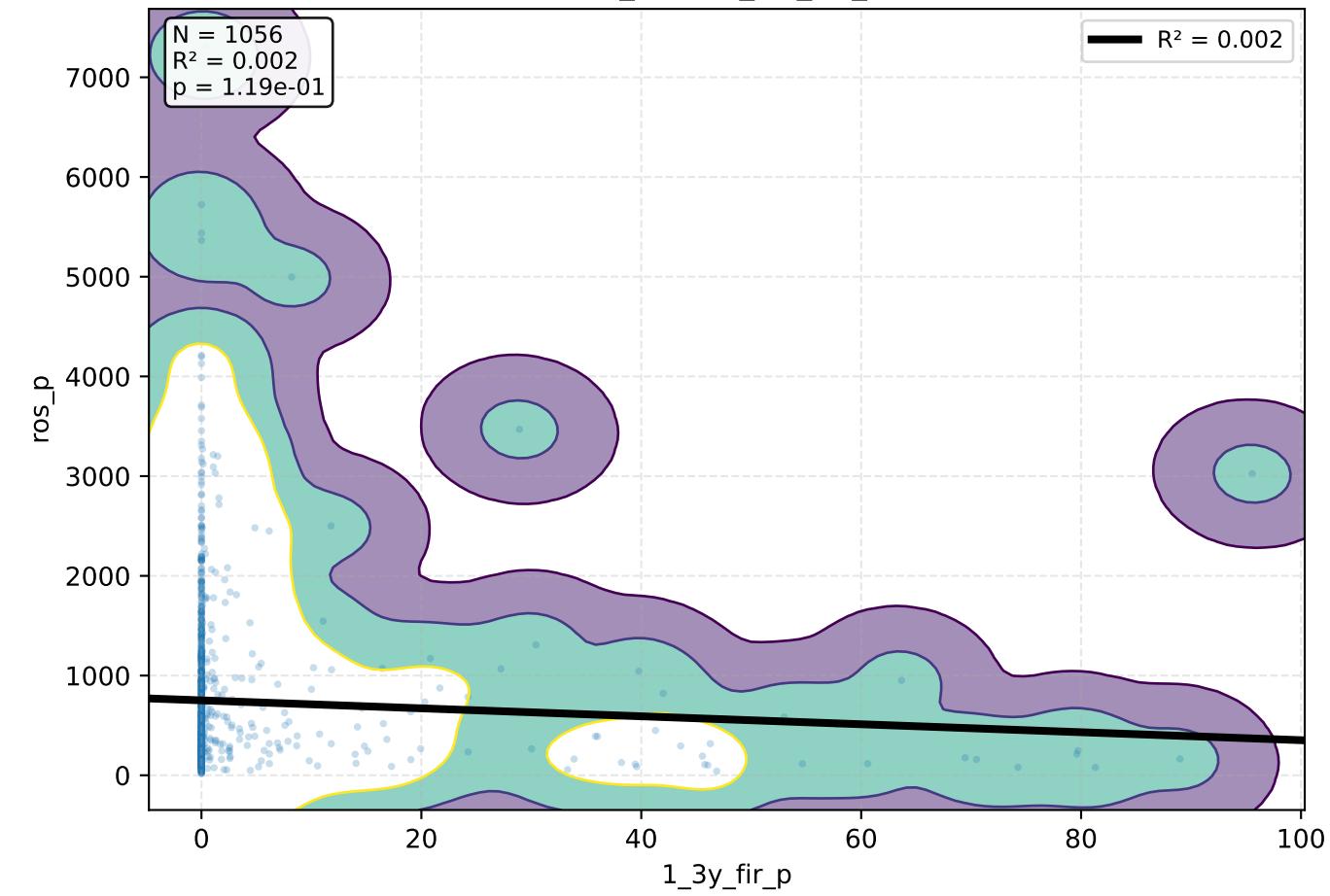


**log(ros\_p) vs log(land\_use)**

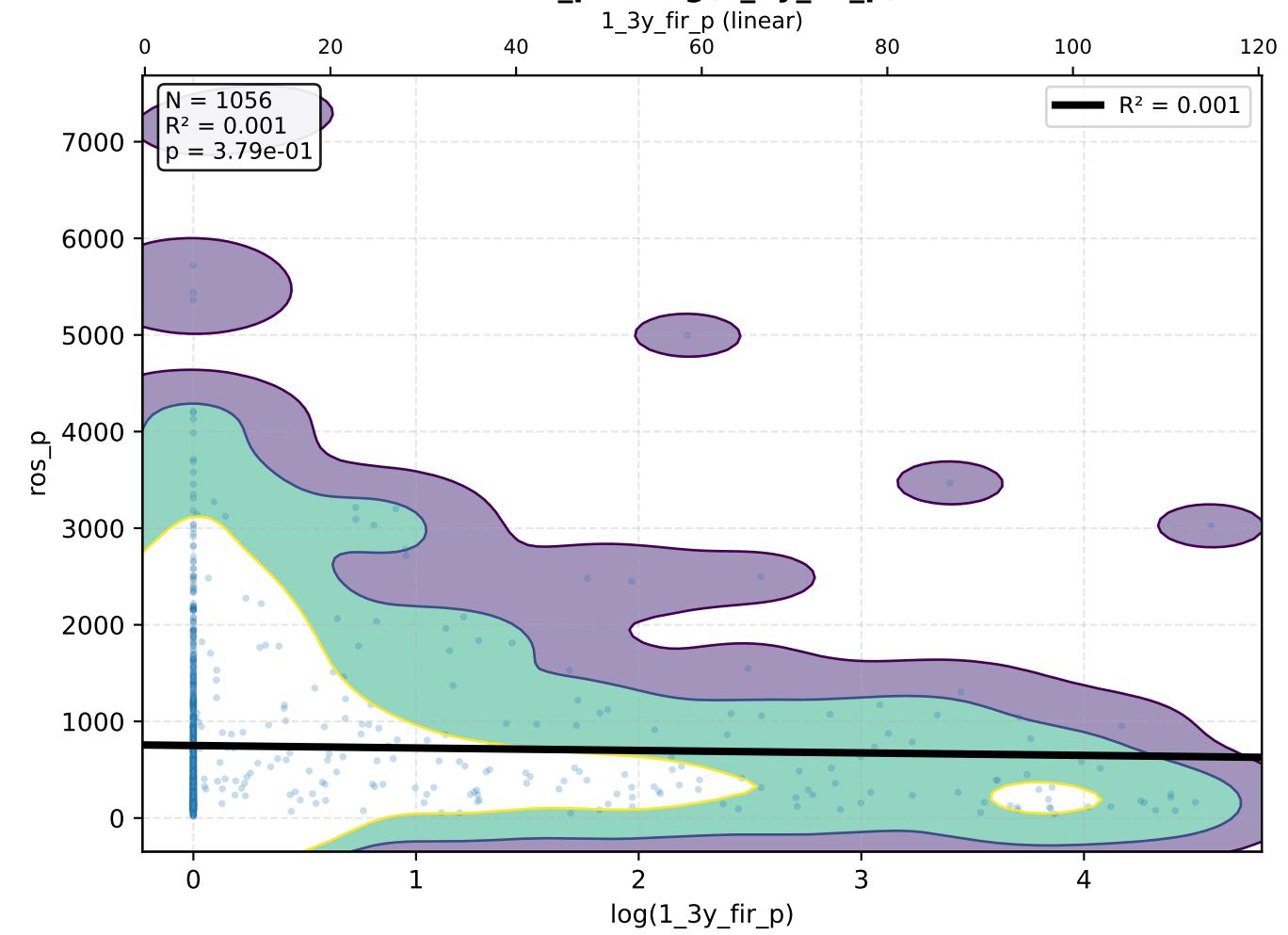


# 1\_3y\_fir\_p – KDE Density + Regressão

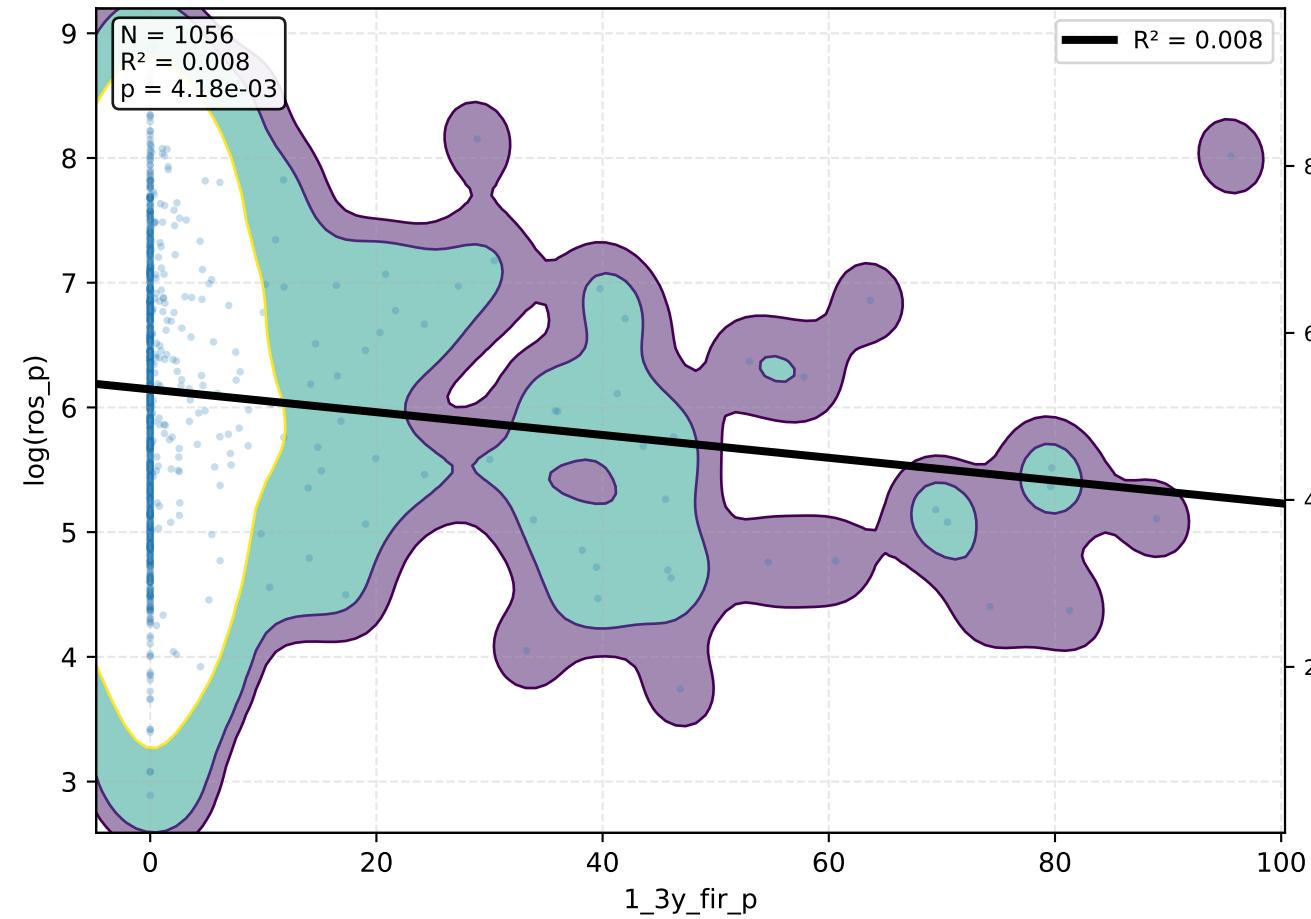
**ros\_p vs 1\_3y\_fir\_p**



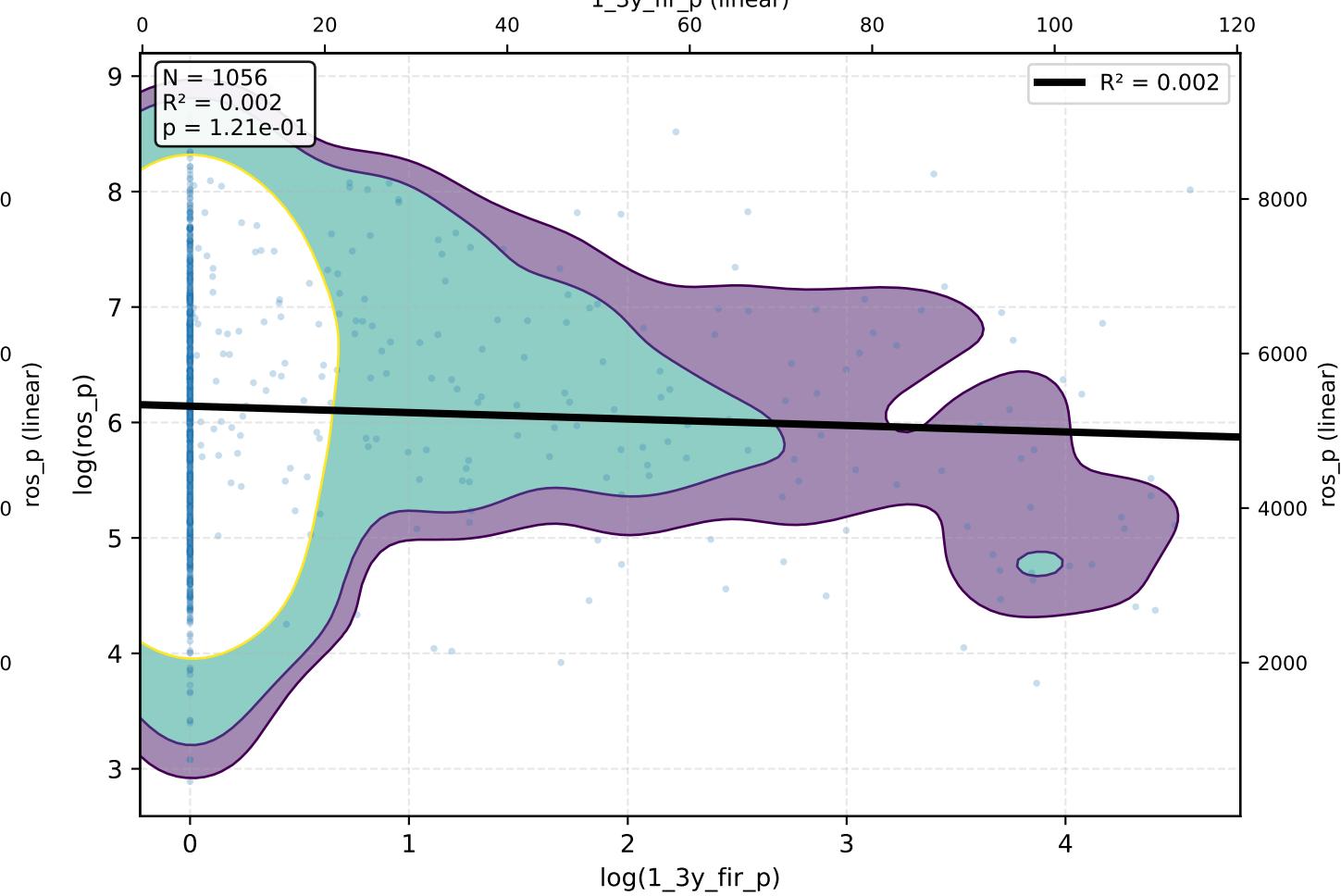
**ros\_p vs log(1\_3y\_fir\_p)**



**log(ros\_p) vs 1\_3y\_fir\_p**

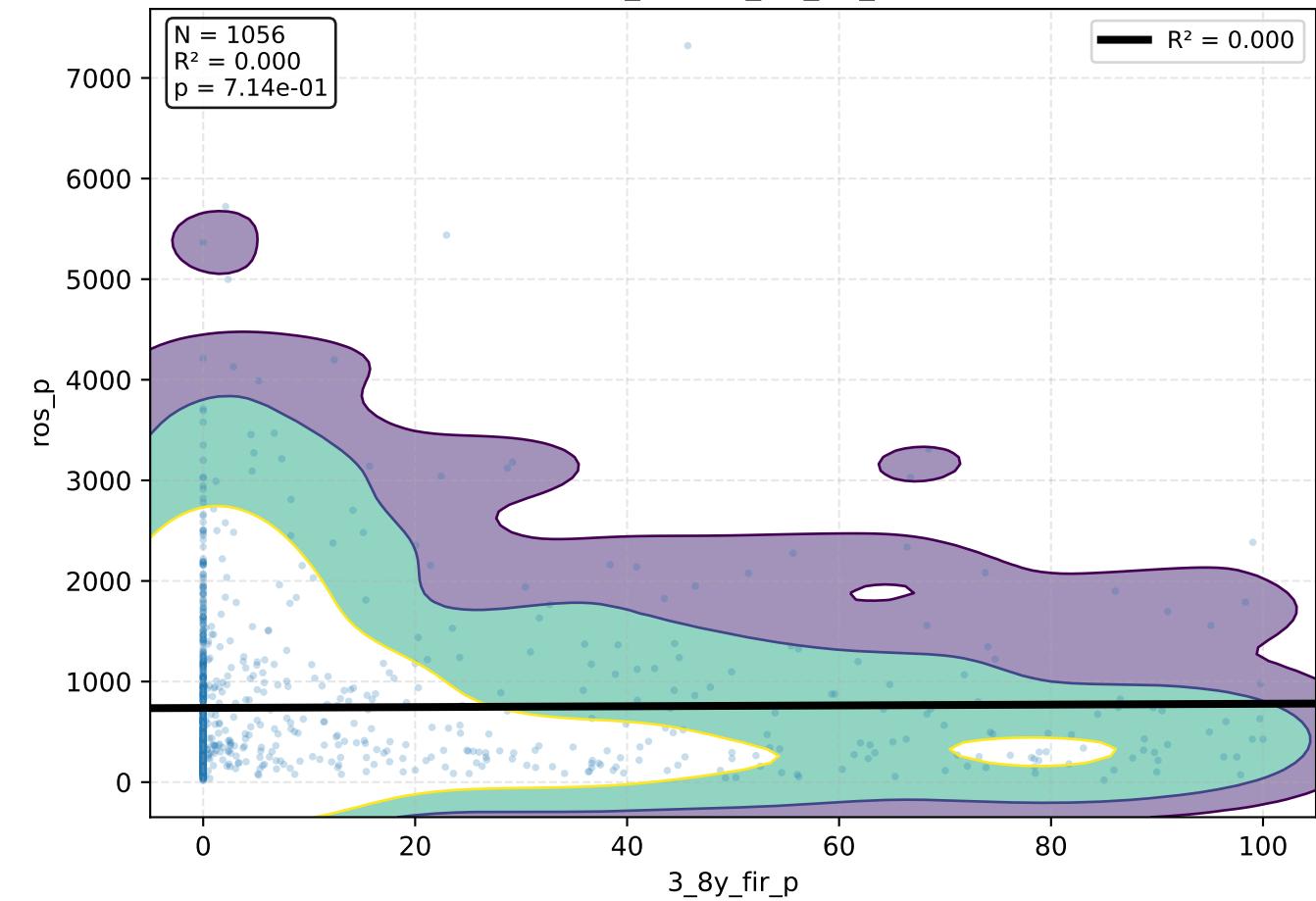


**log(ros\_p) vs log(1\_3y\_fir\_p)**

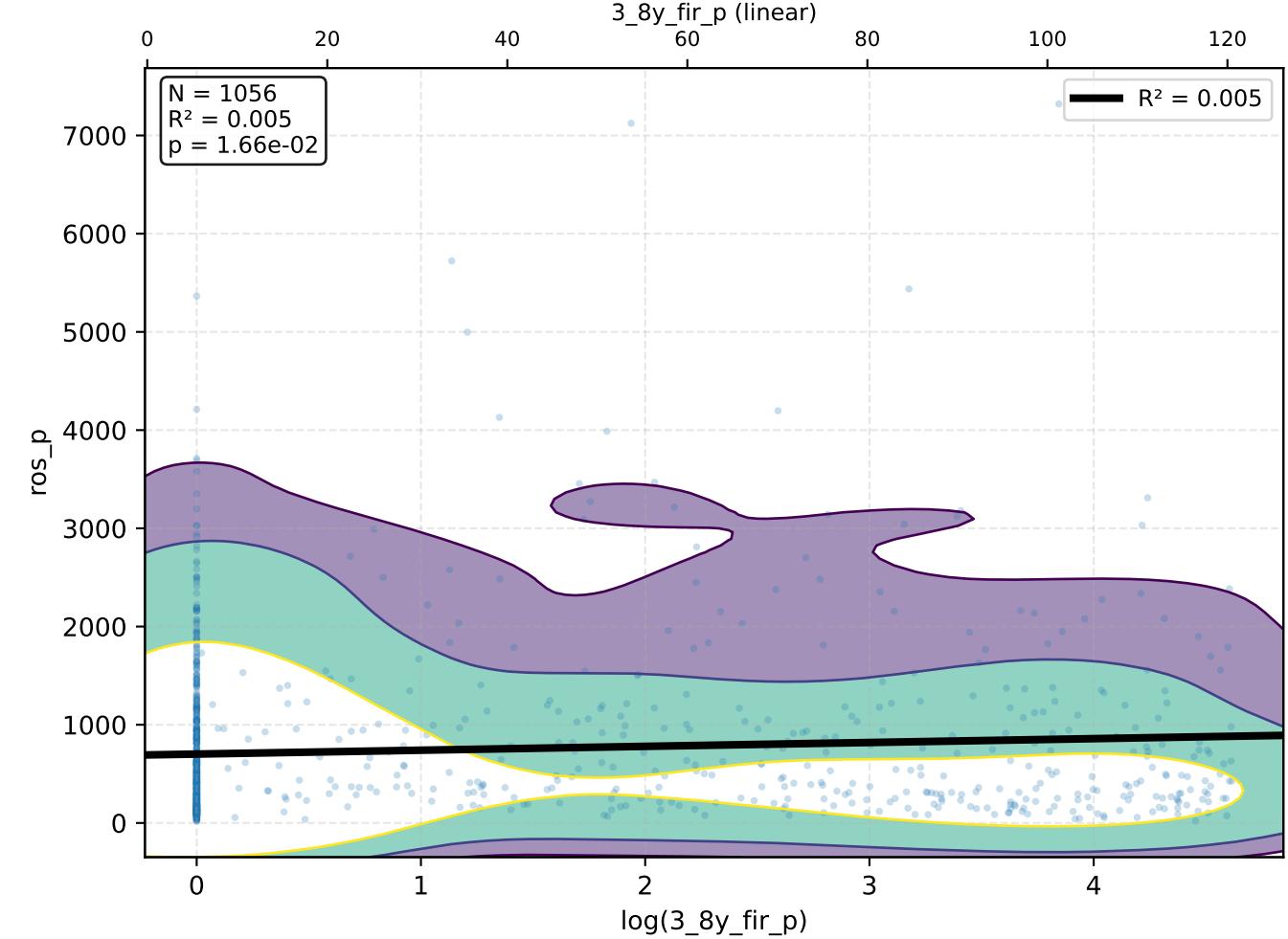


# 3\_8y\_fir\_p – KDE Density + Regressão

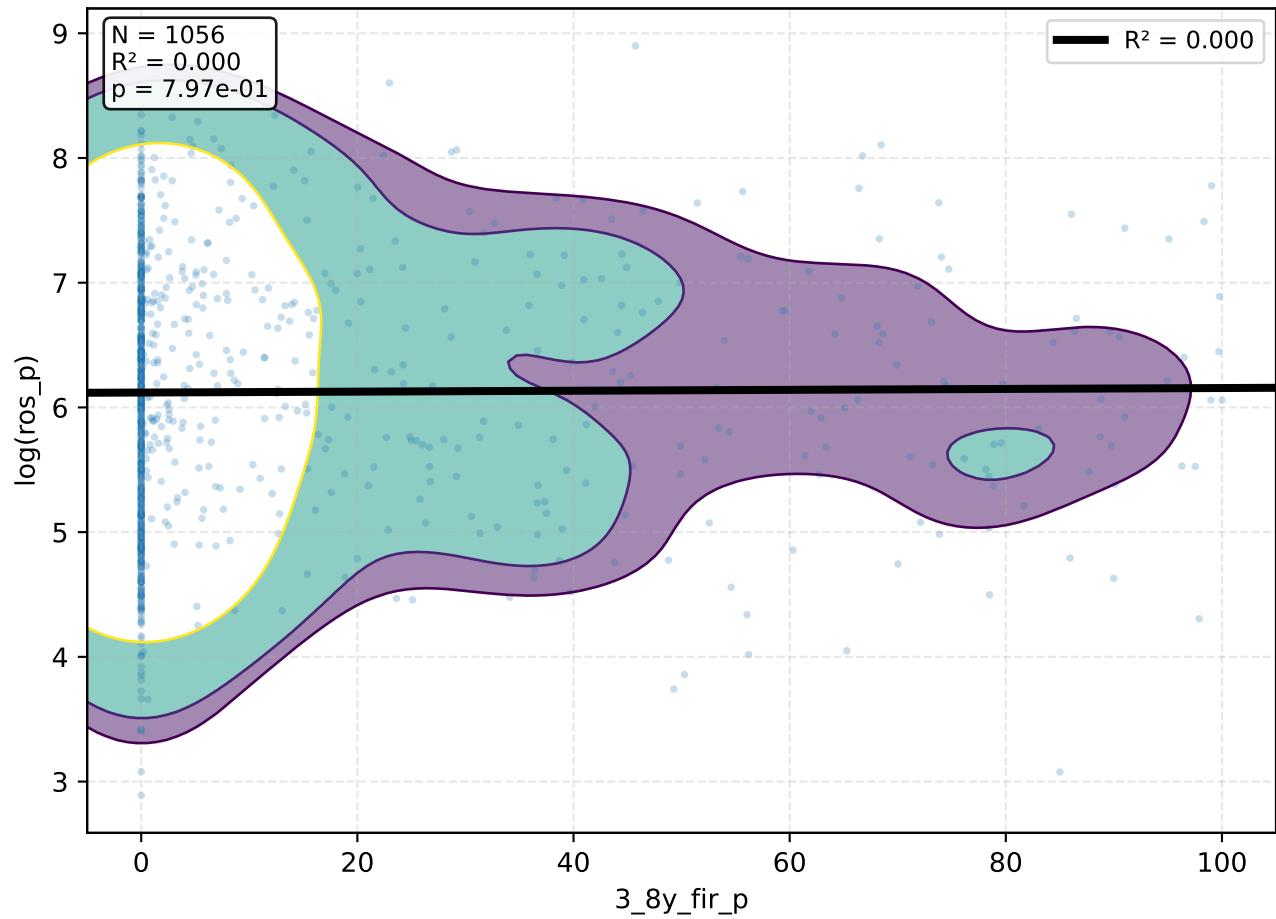
**ros\_p vs 3\_8y\_fir\_p**



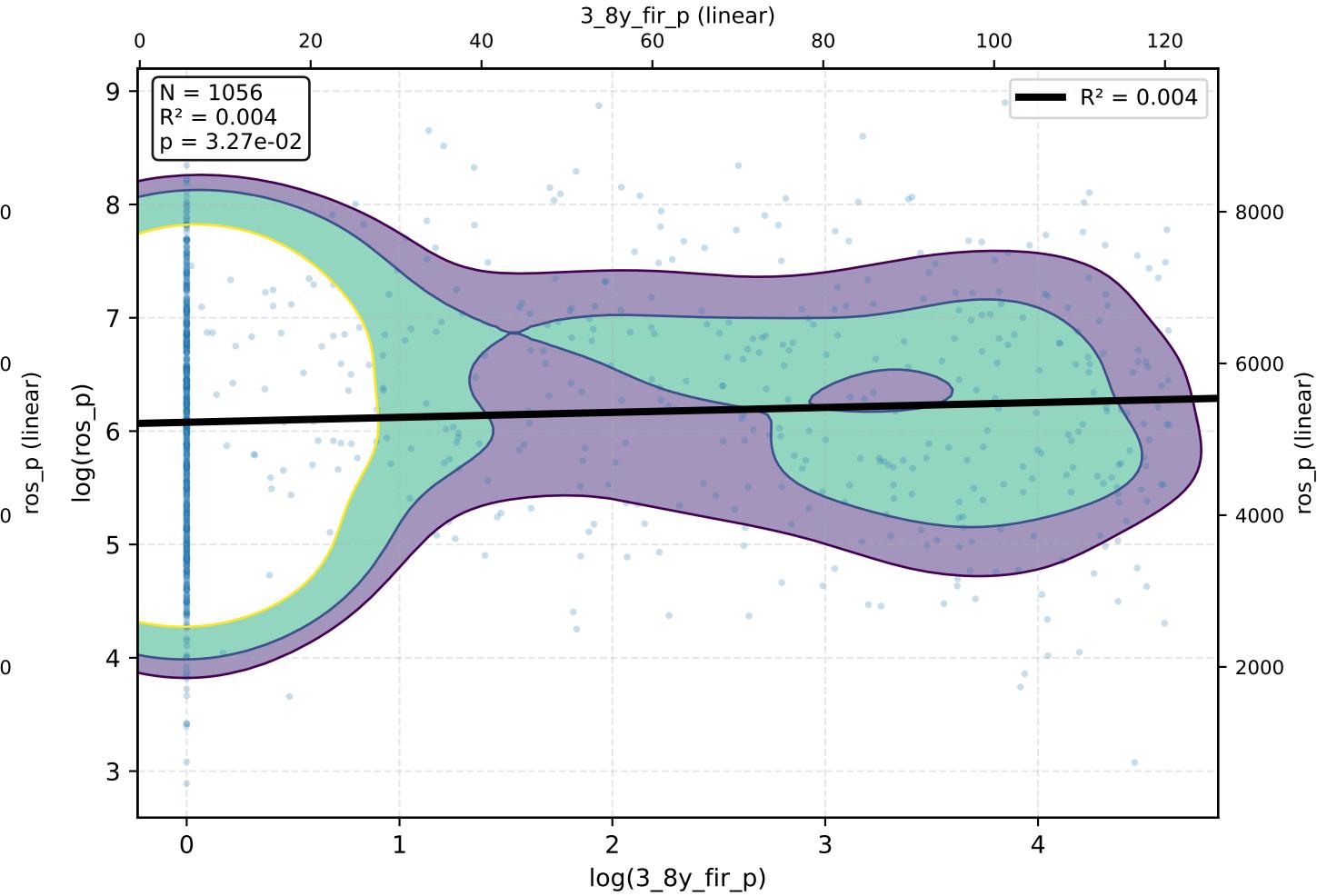
**ros\_p vs log(3\_8y\_fir\_p)**



**log(ros\_p) vs 3\_8y\_fir\_p**

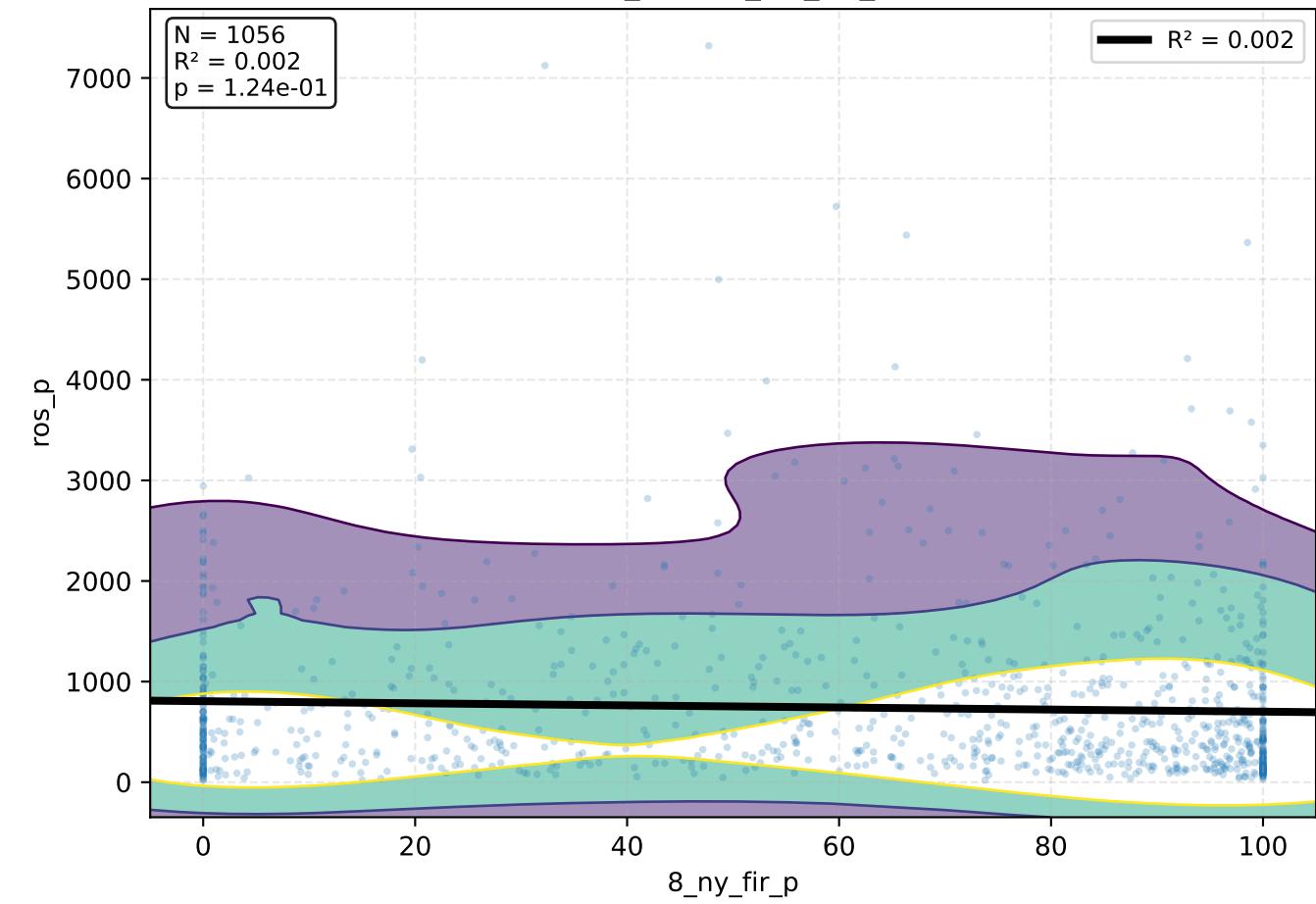


**log(ros\_p) vs log(3\_8y\_fir\_p)**

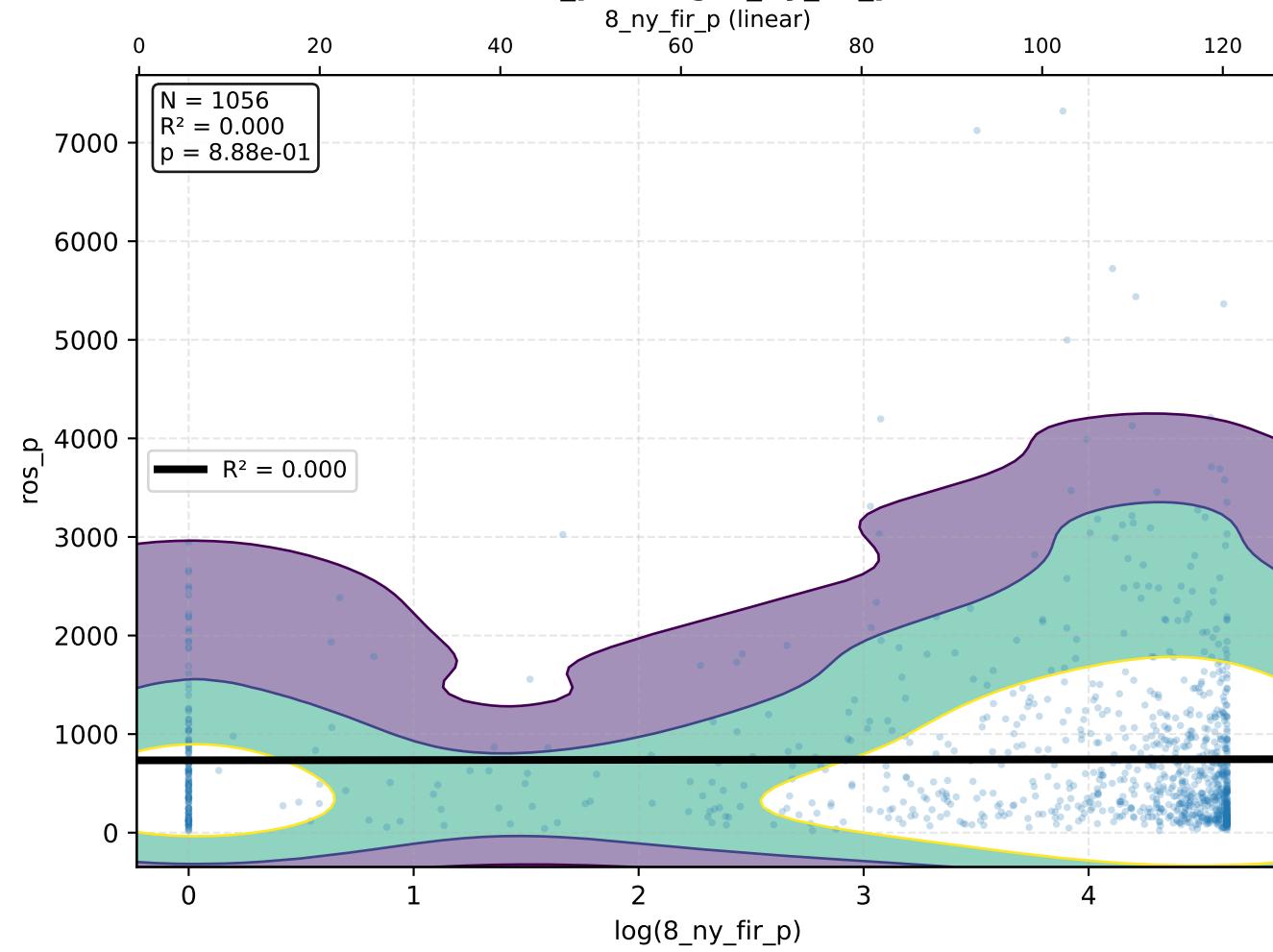


# 8\_ny\_fir\_p – KDE Density + Regressão

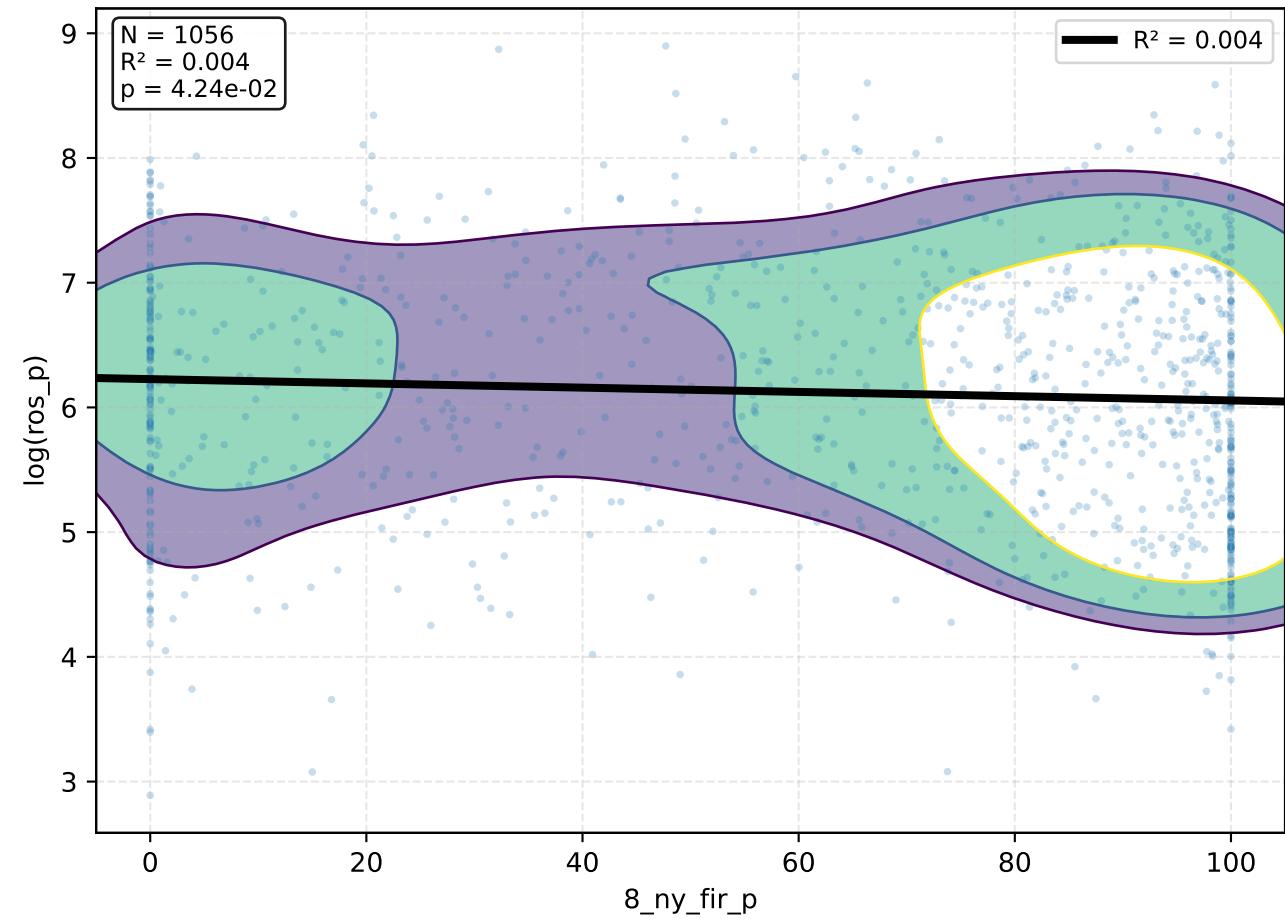
**ros\_p vs 8\_ny\_fir\_p**



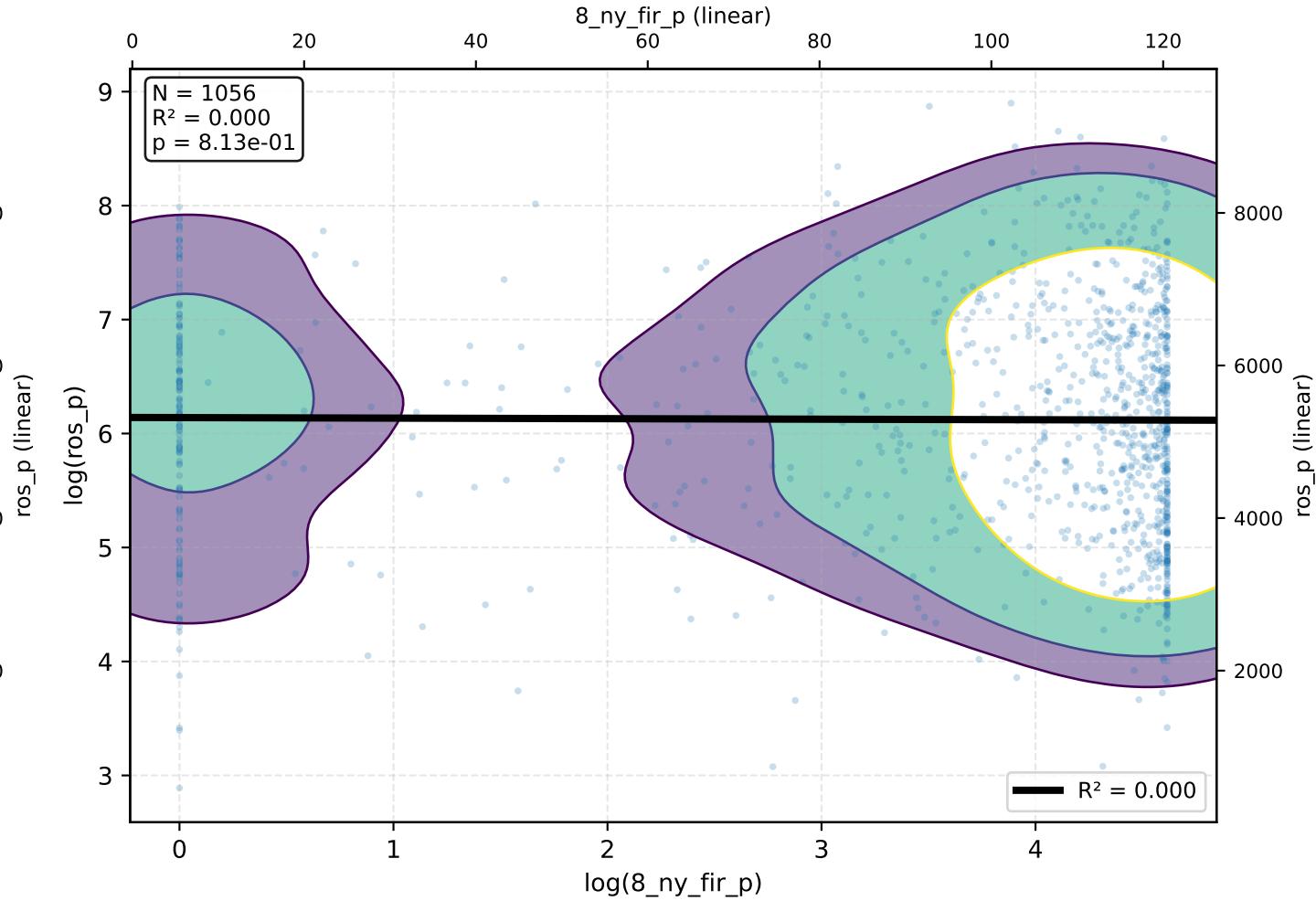
**ros\_p vs log(8\_ny\_fir\_p)**



**log(ros\_p) vs 8\_ny\_fir\_p**

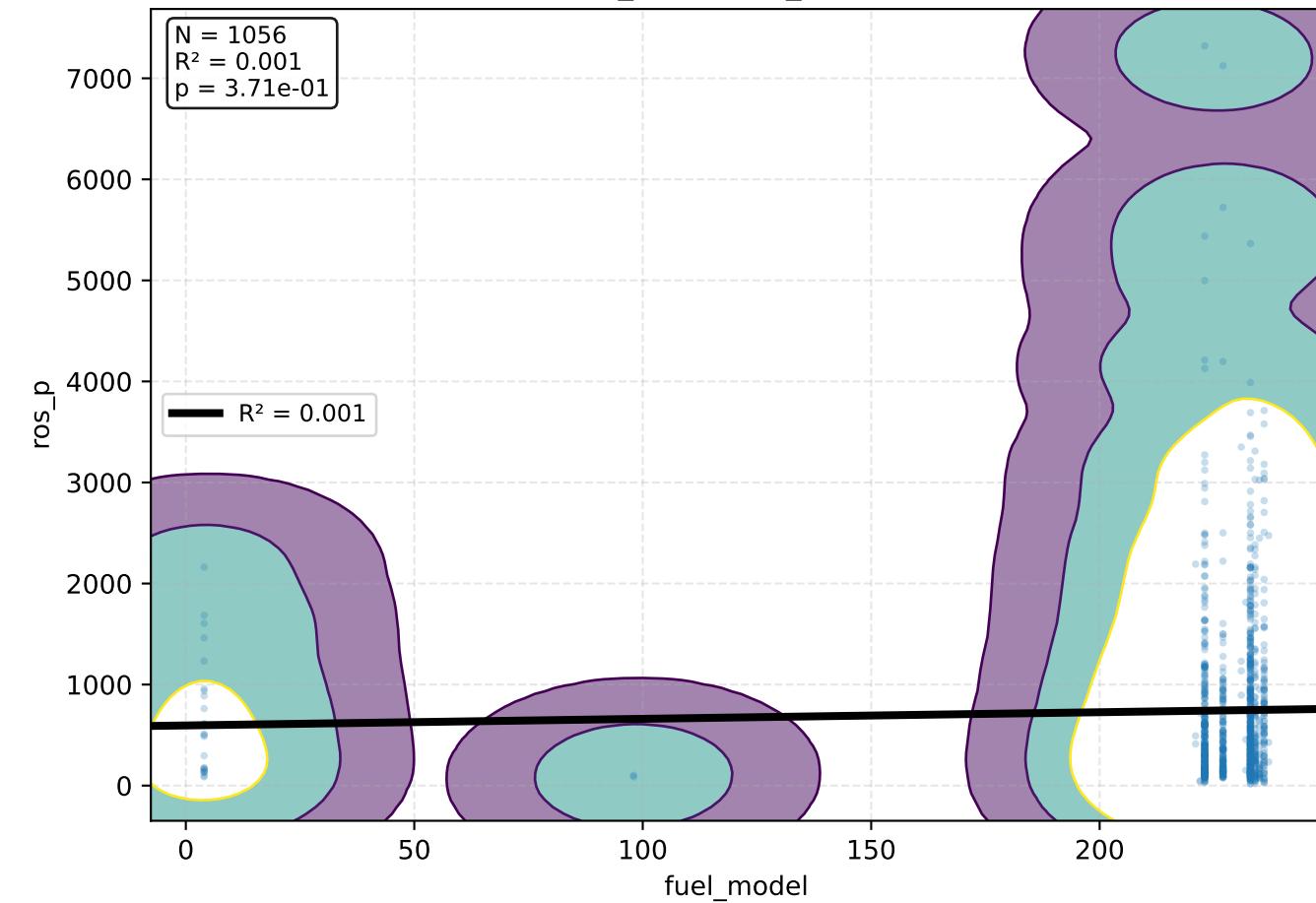


**log(ros\_p) vs log(8\_ny\_fir\_p)**

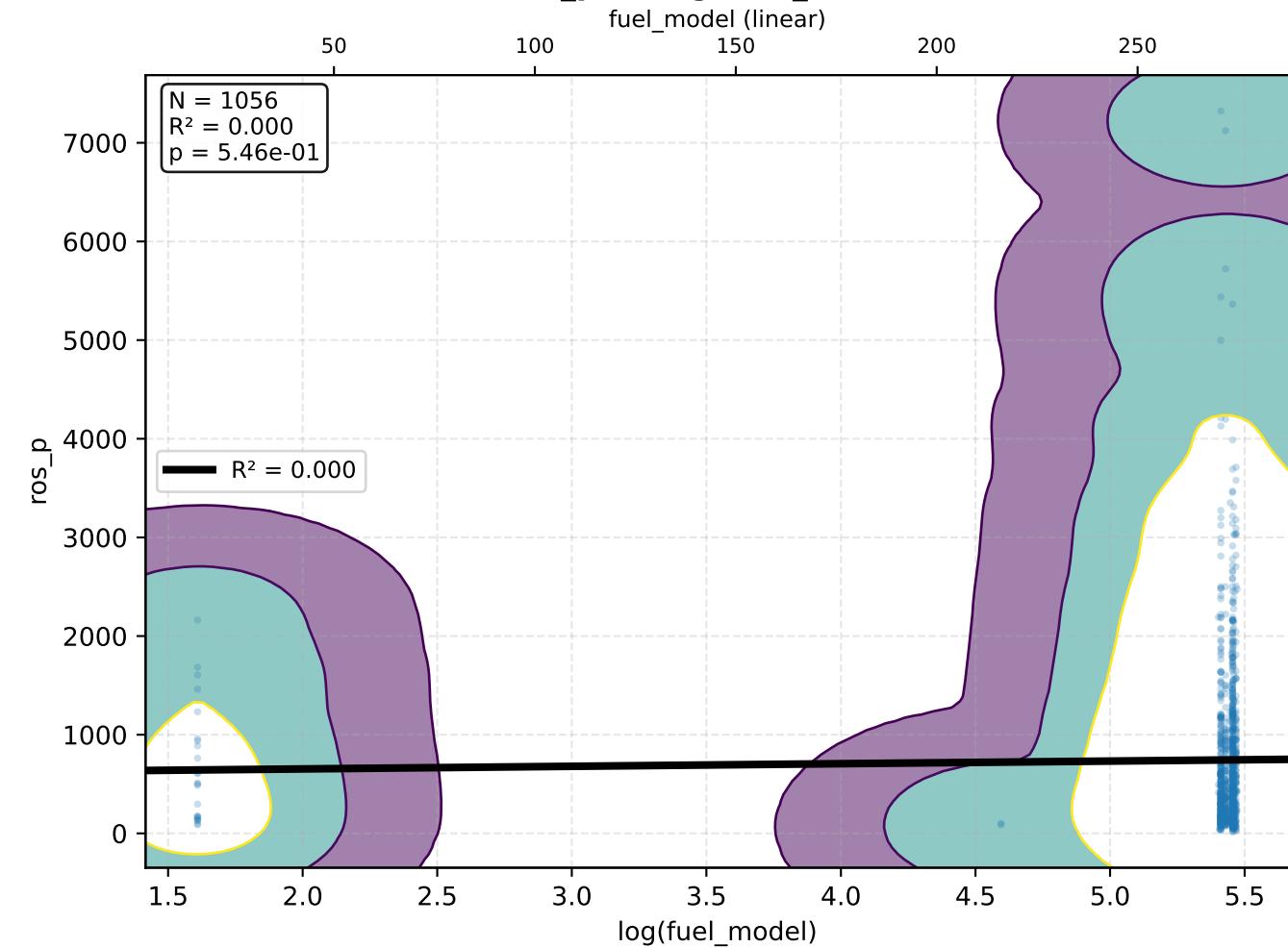


# fuel\_model – KDE Density + Regressão

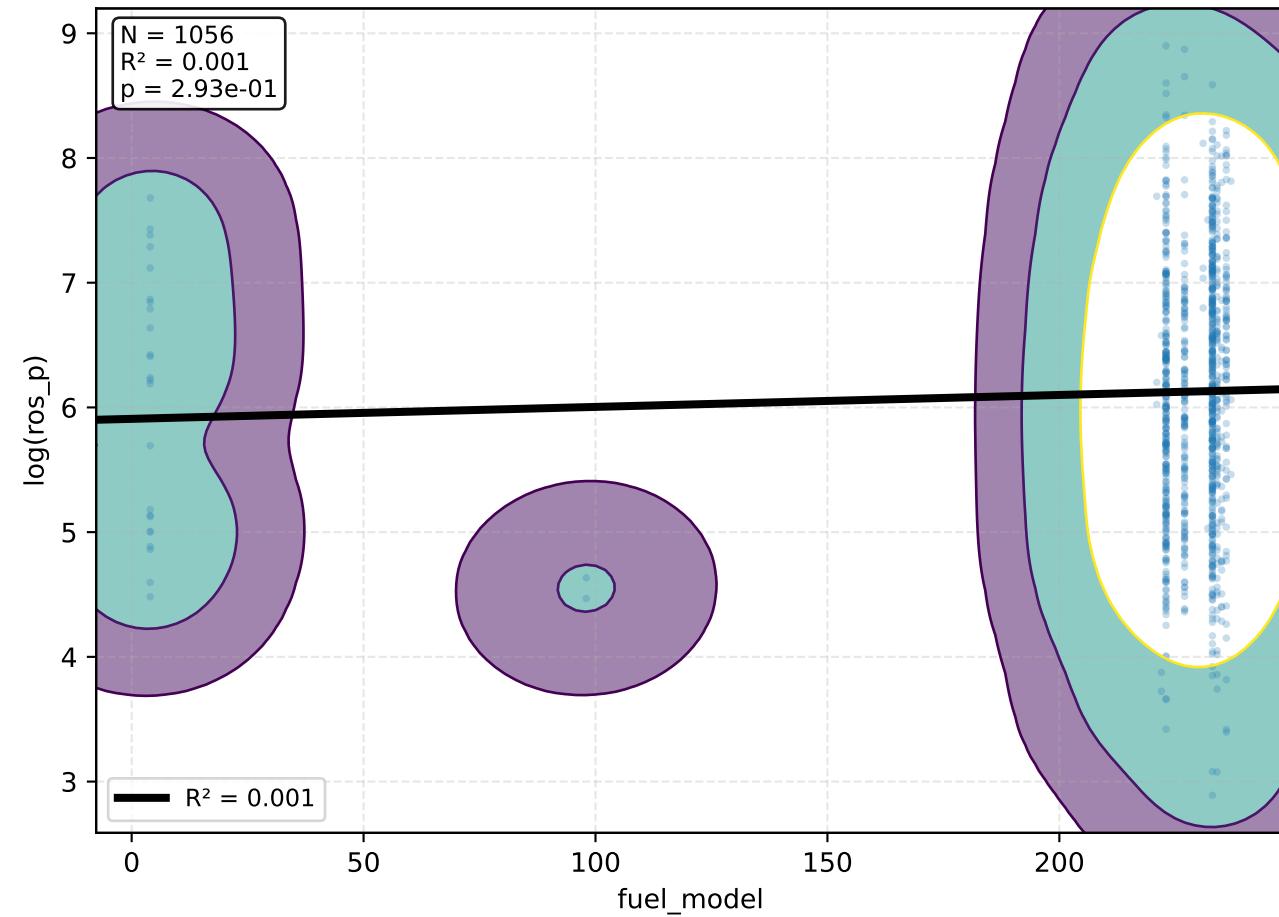
**ros\_p vs fuel\_model**



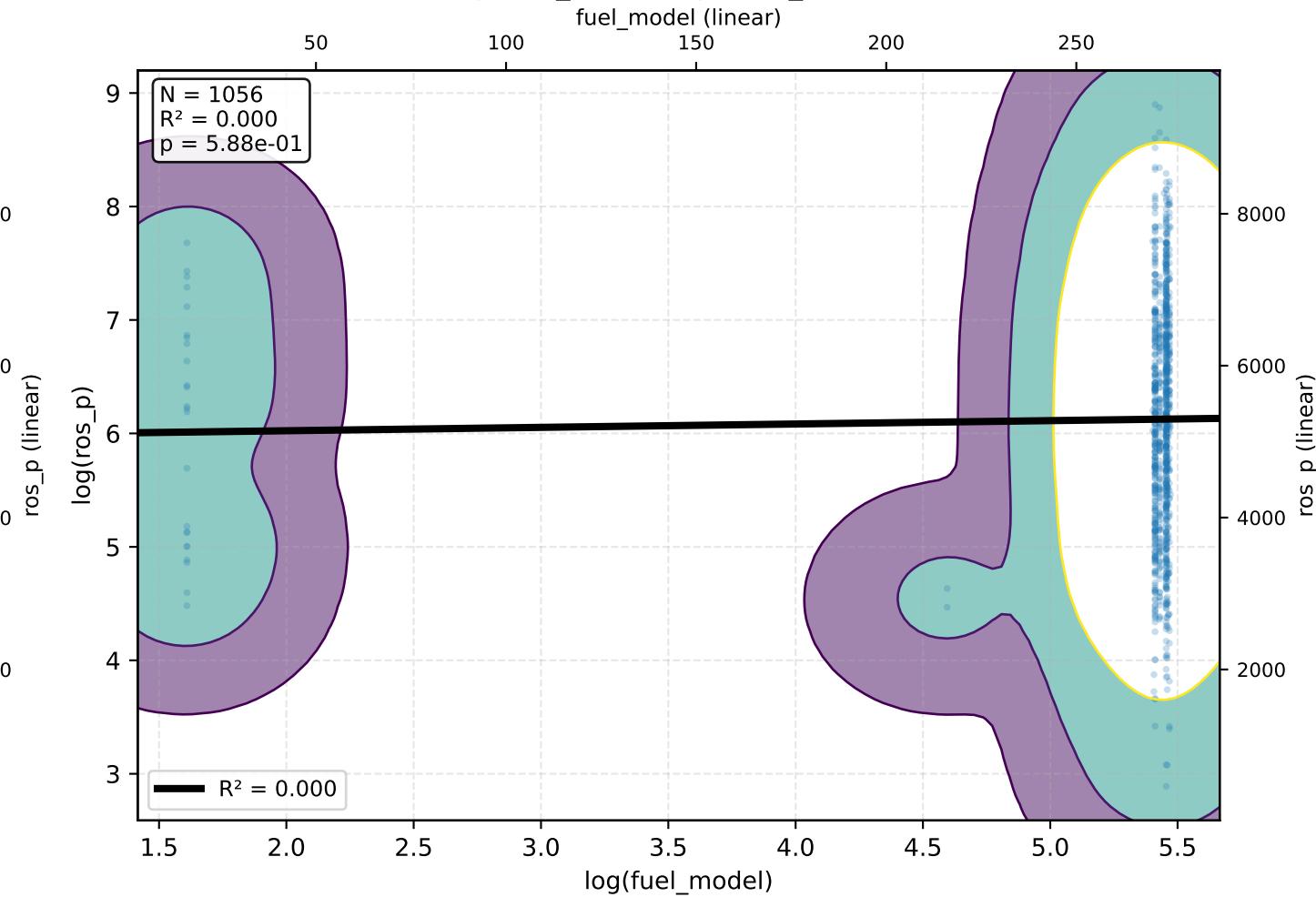
**ros\_p vs log(fuel\_model)**



**log(ros\_p) vs fuel\_model**

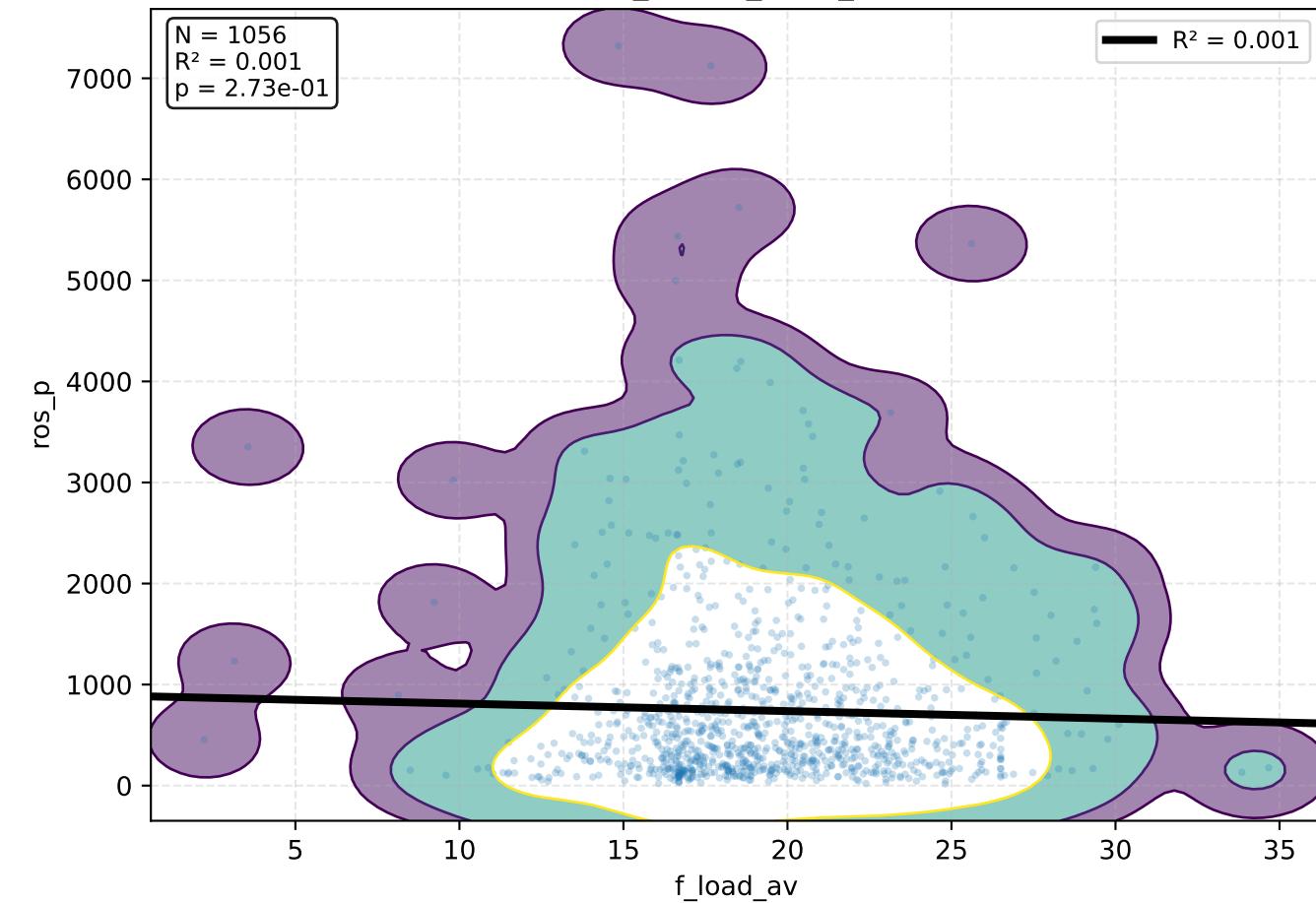


**log(ros\_p) vs log(fuel\_model)**

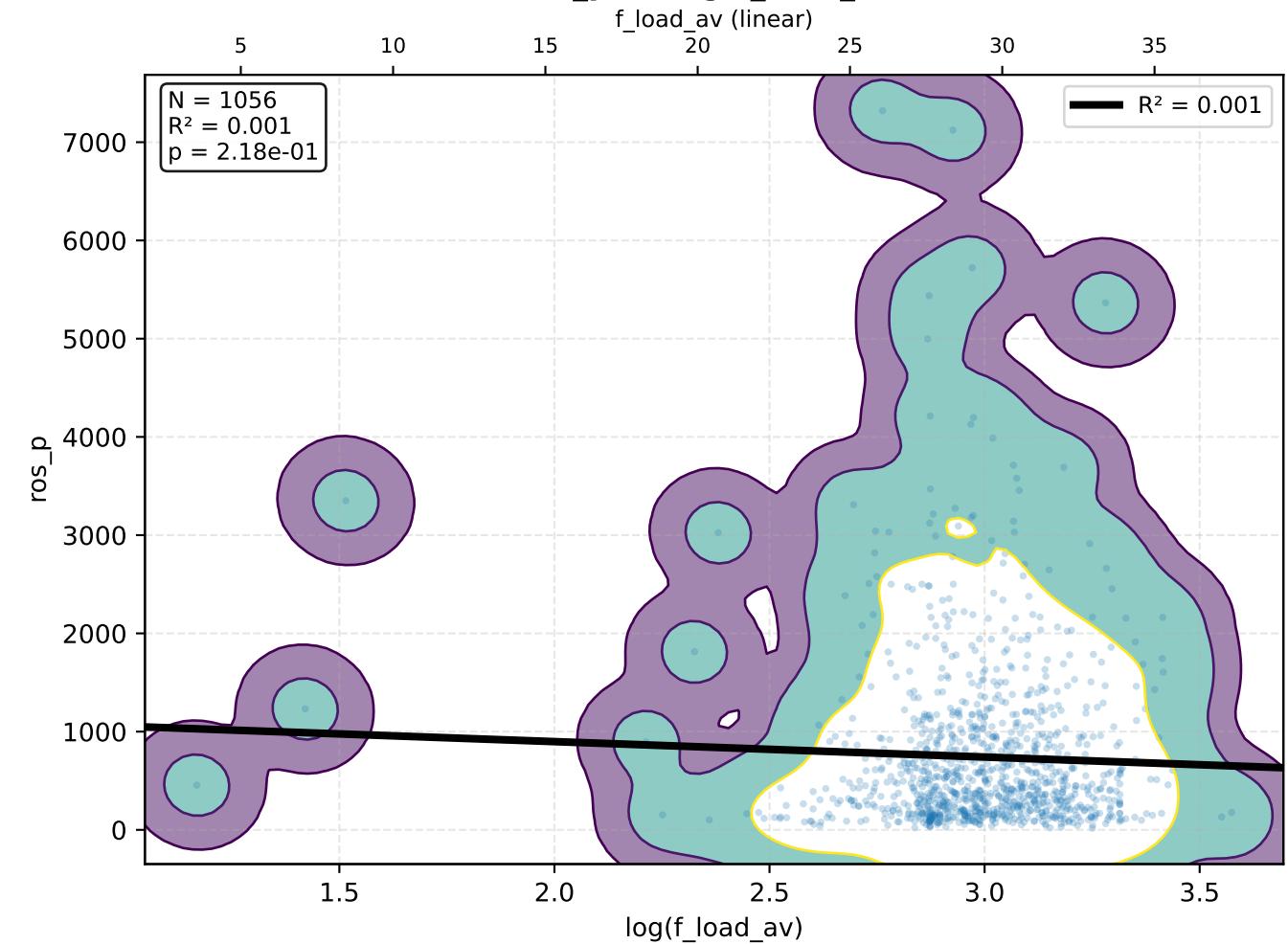


# f\_load\_av – KDE Density + Regressão

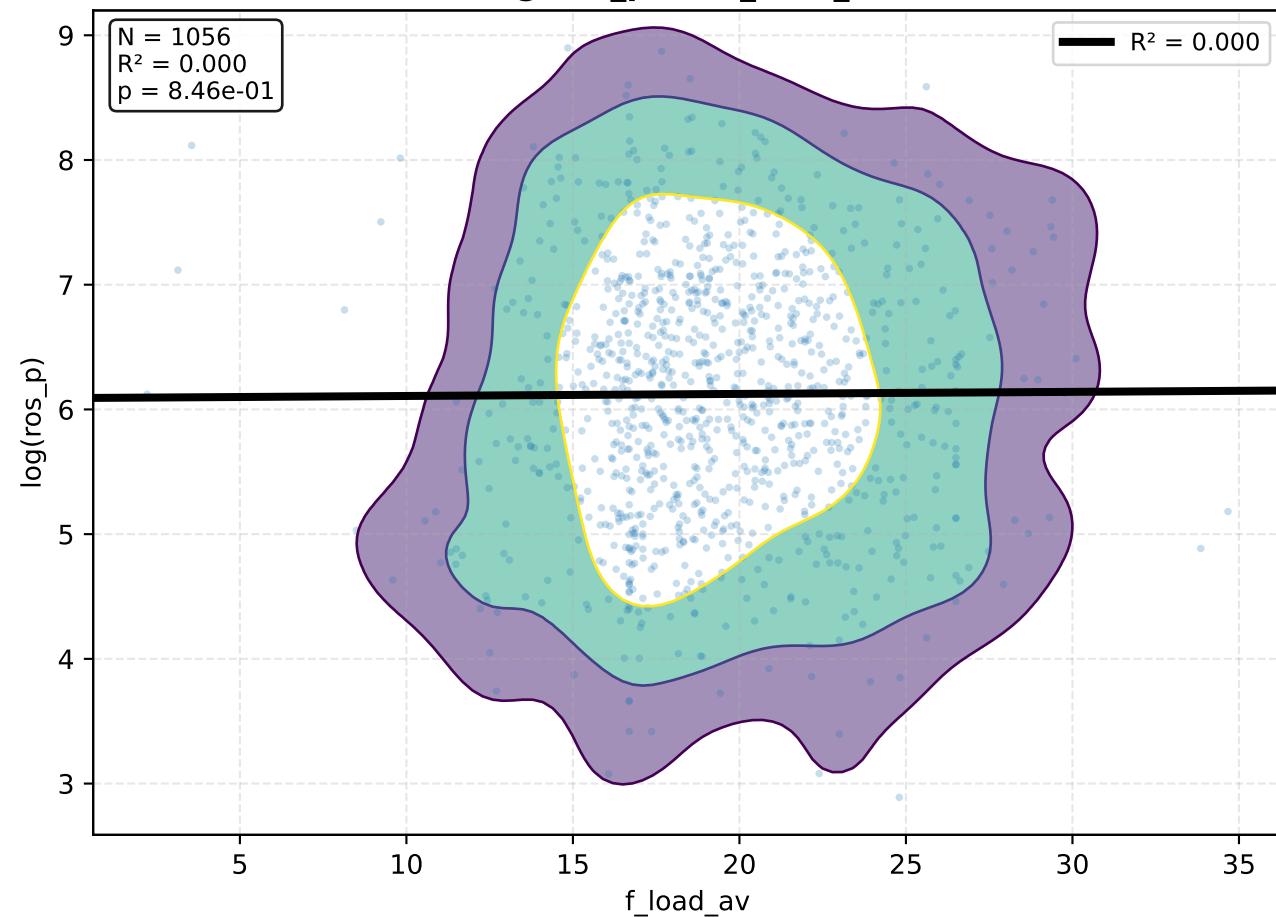
**ros\_p vs f\_load\_av**



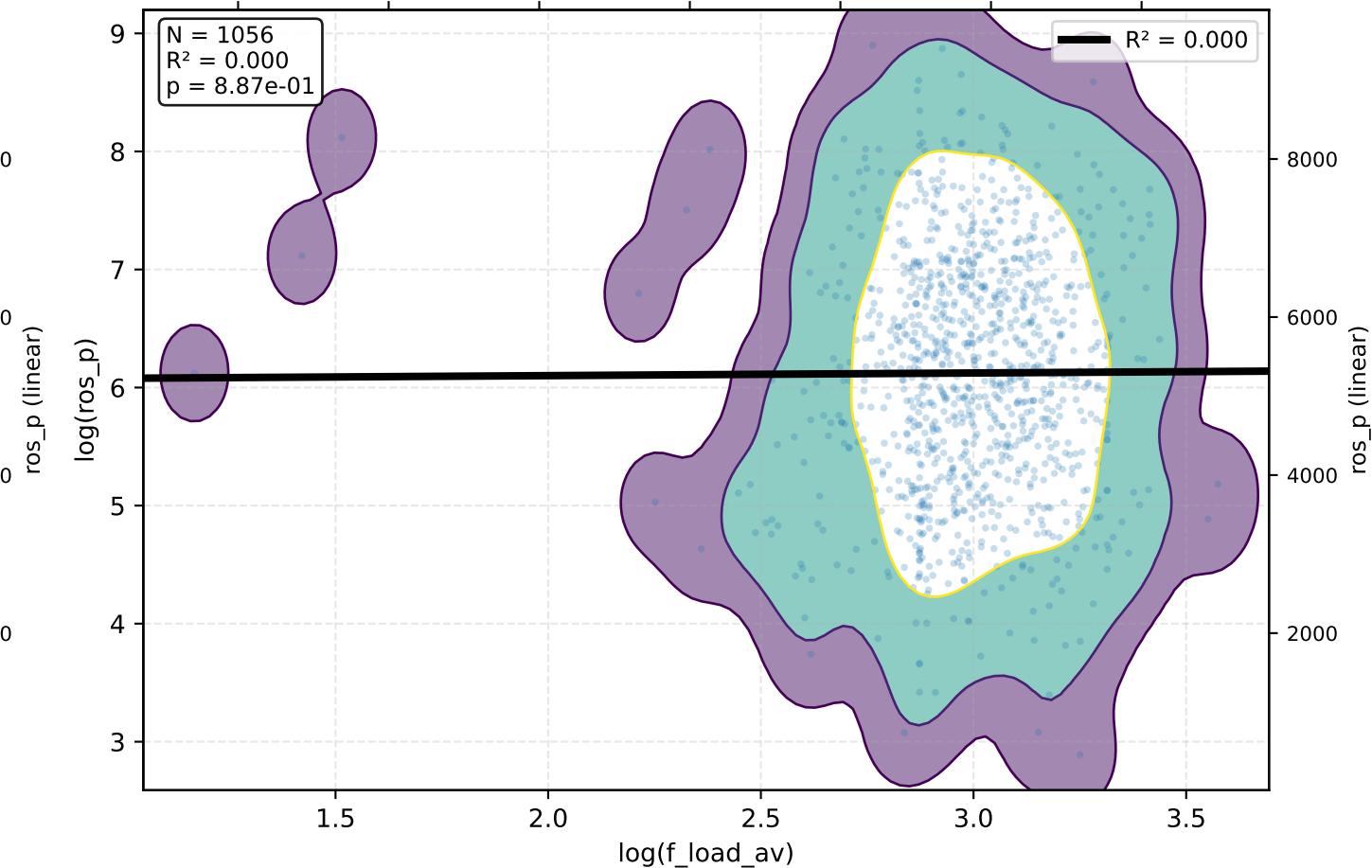
**ros\_p vs log(f\_load\_av)**



**log(ros\_p) vs f\_load\_av**

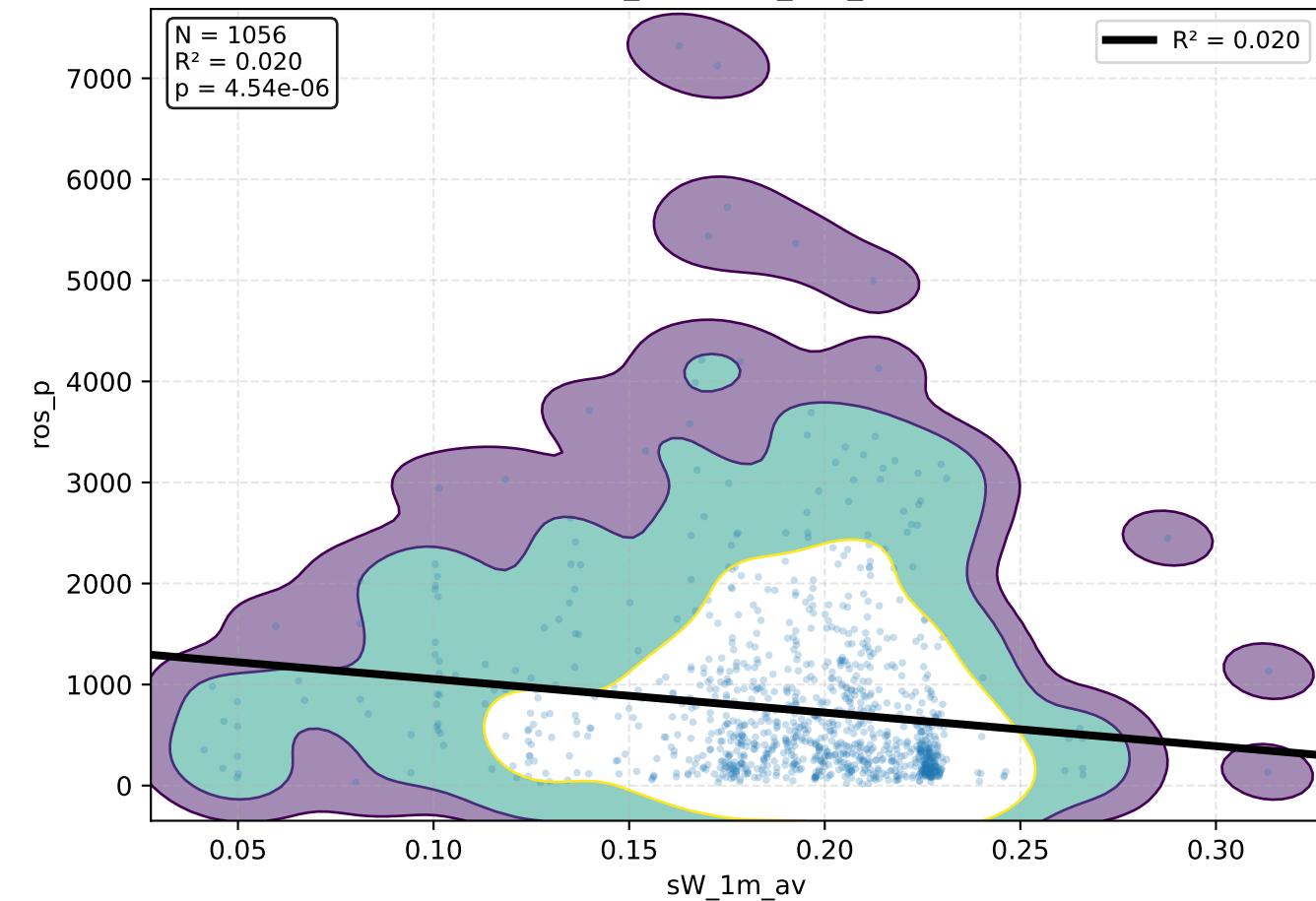


**log(ros\_p) vs log(f\_load\_av)**

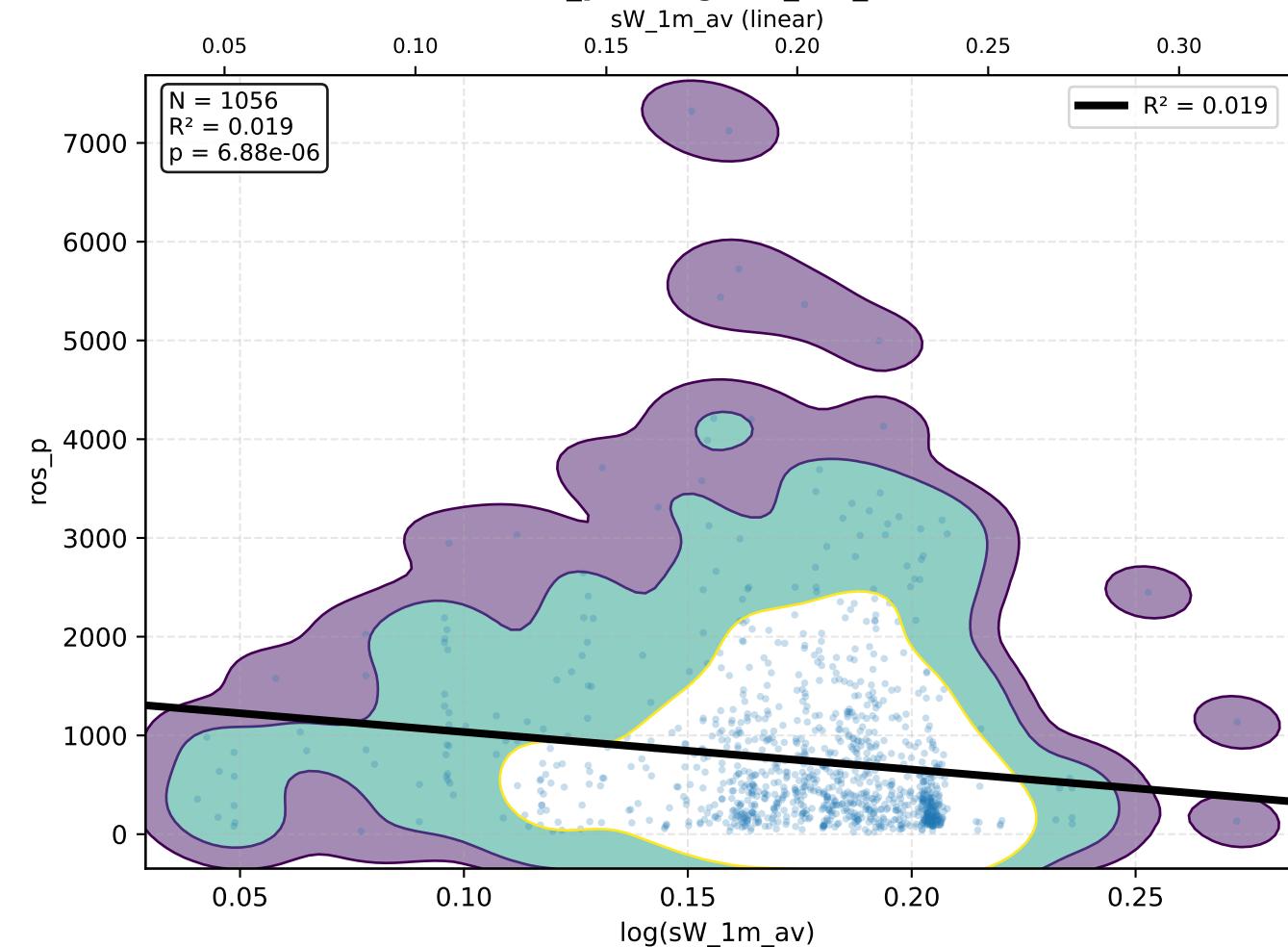


# sW\_1m\_av – KDE Density + Regressão

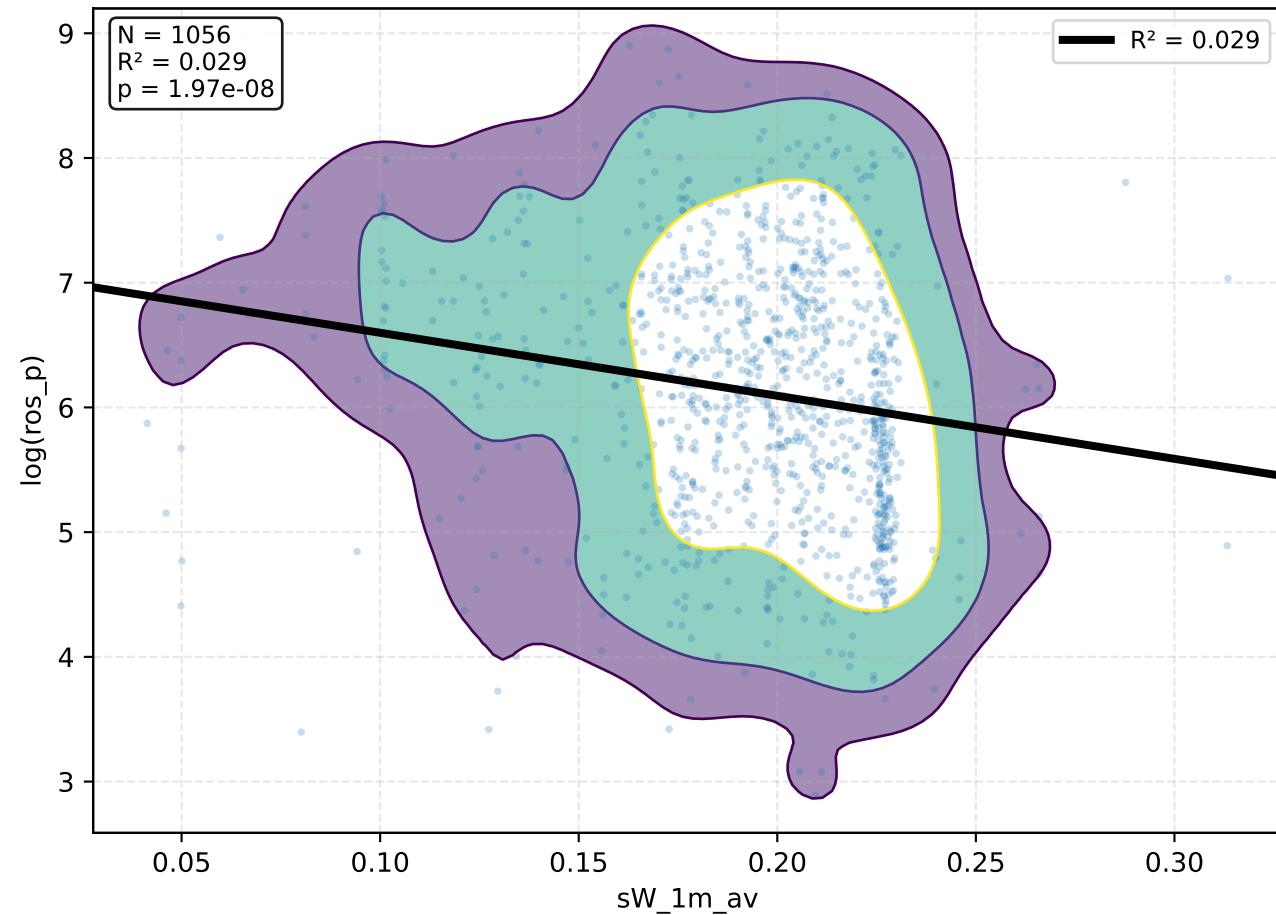
**ros\_p vs sW\_1m\_av**



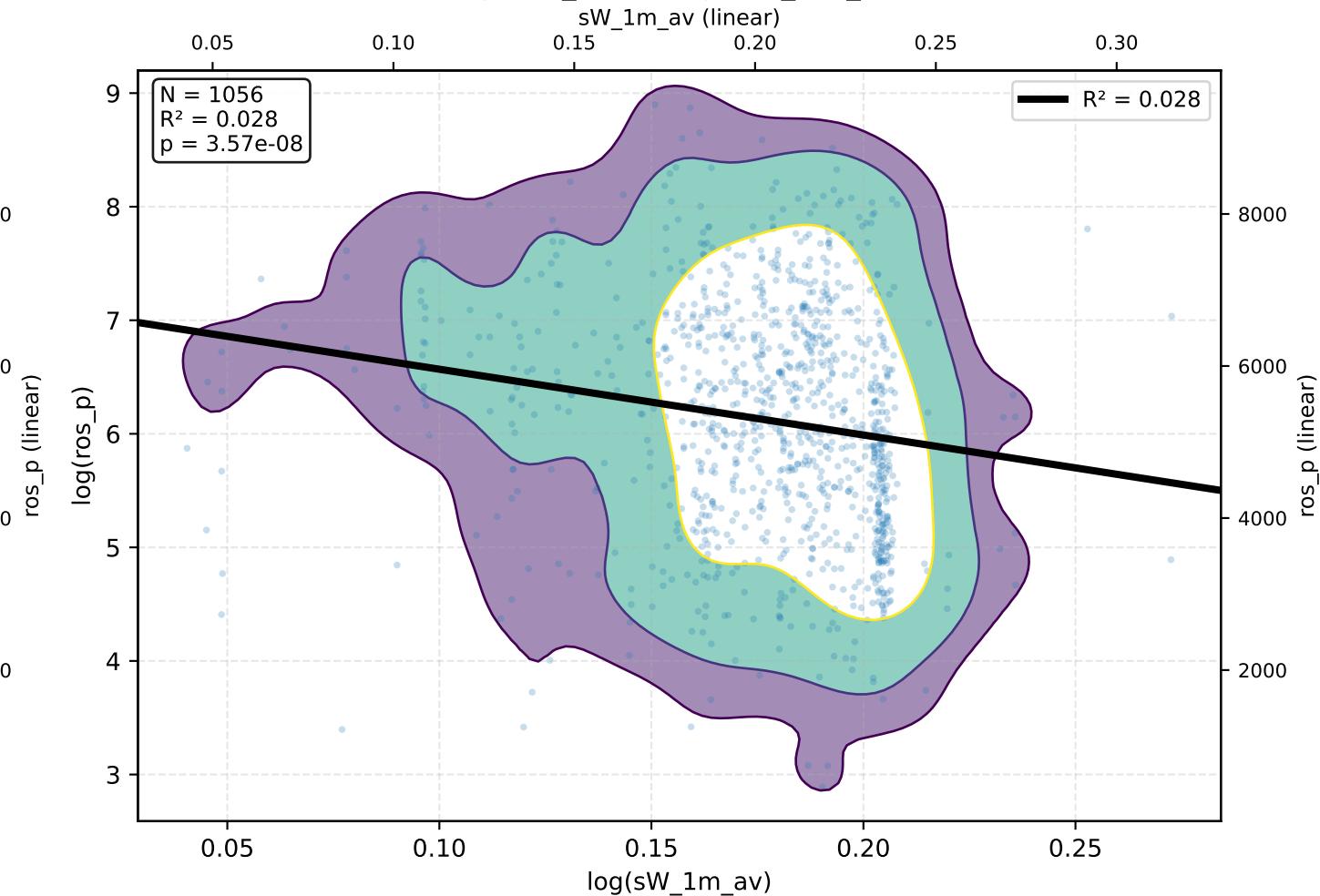
**ros\_p vs log(sW\_1m\_av)**



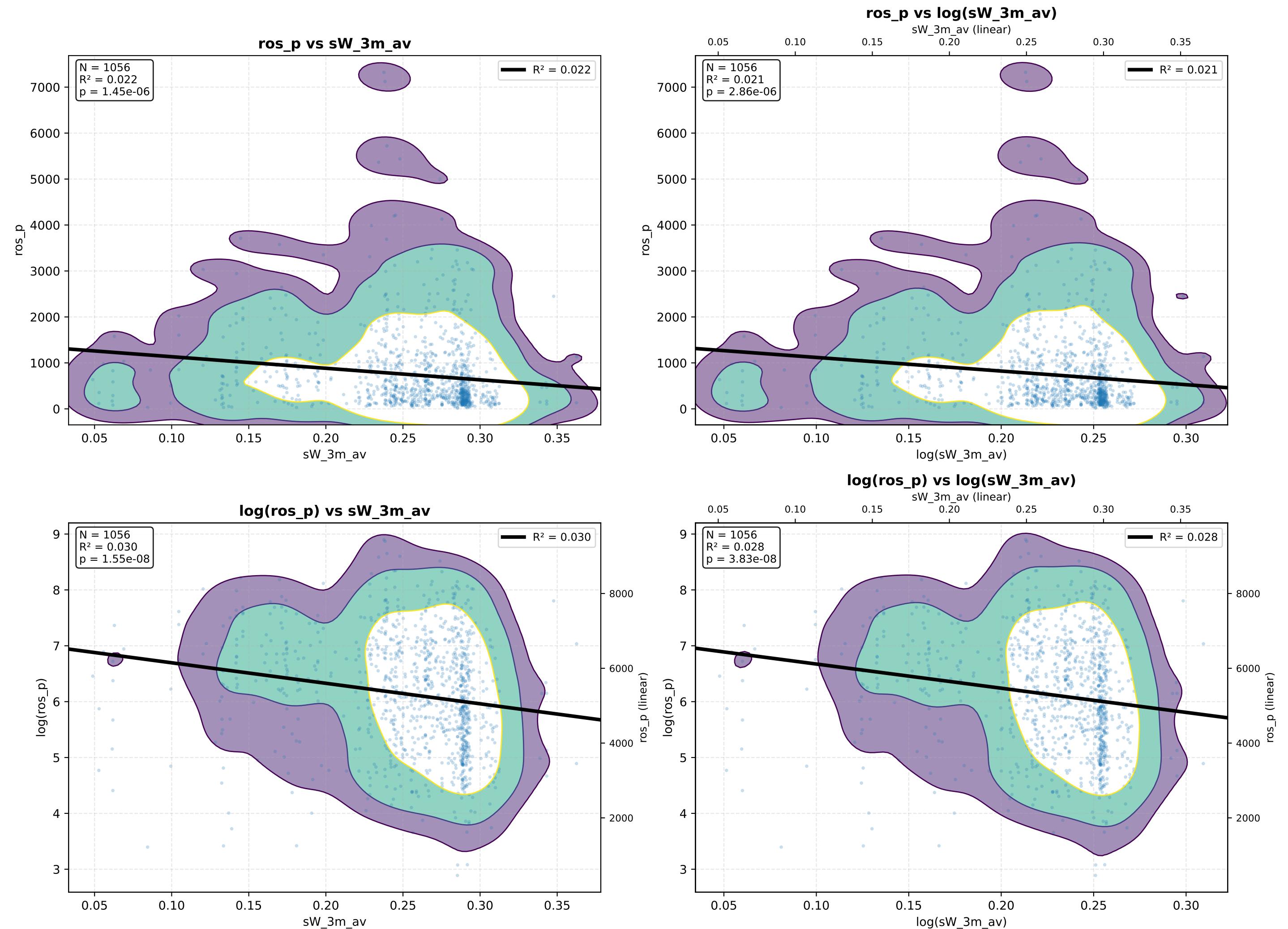
**log(ros\_p) vs sW\_1m\_av**



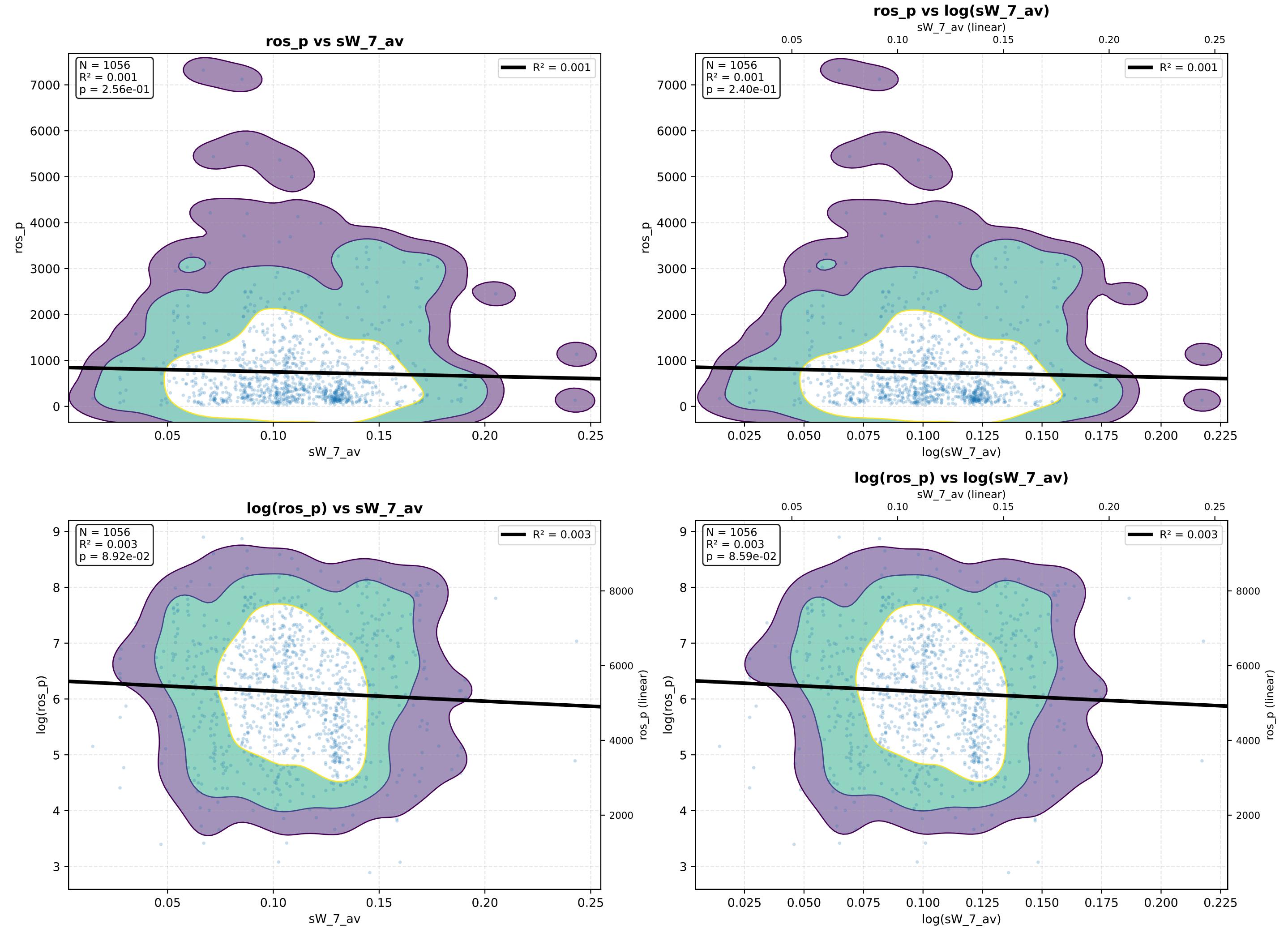
**log(ros\_p) vs log(sW\_1m\_av)**



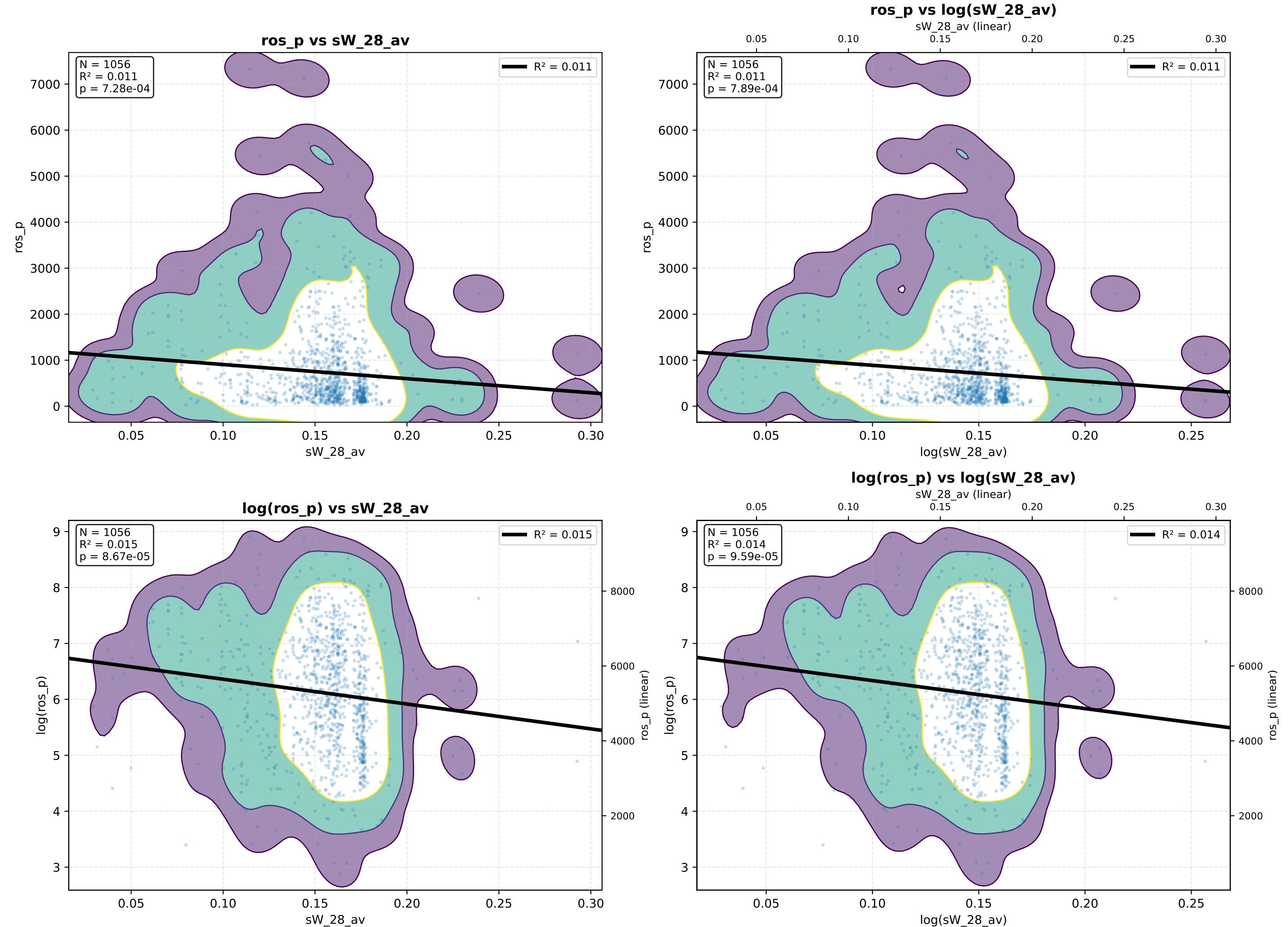
# sW\_3m\_av – KDE Density + Regressão



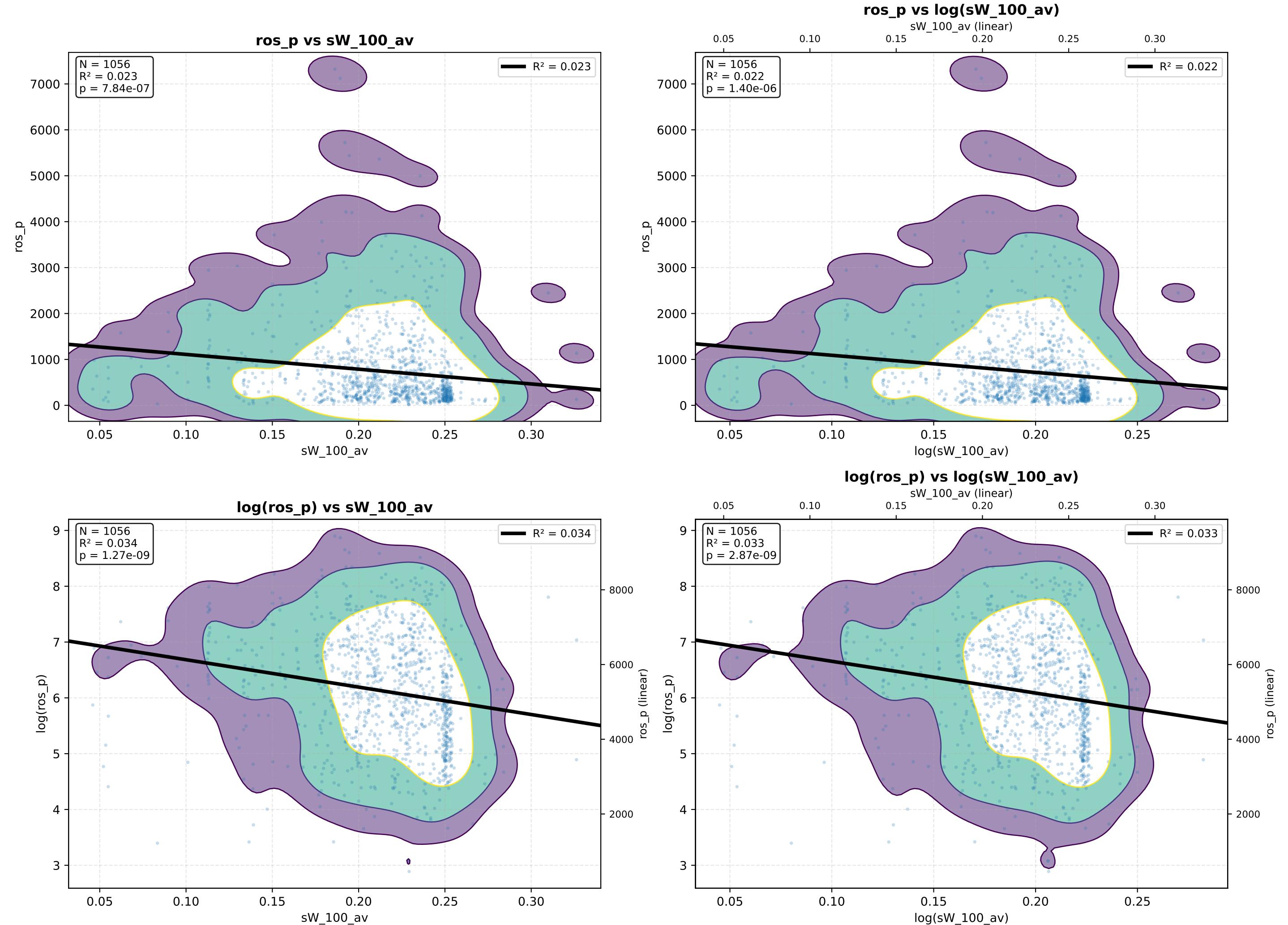
# sW\_7\_av - KDE Density + Regressão



# sW\_28\_av – KDE Density + Regressão

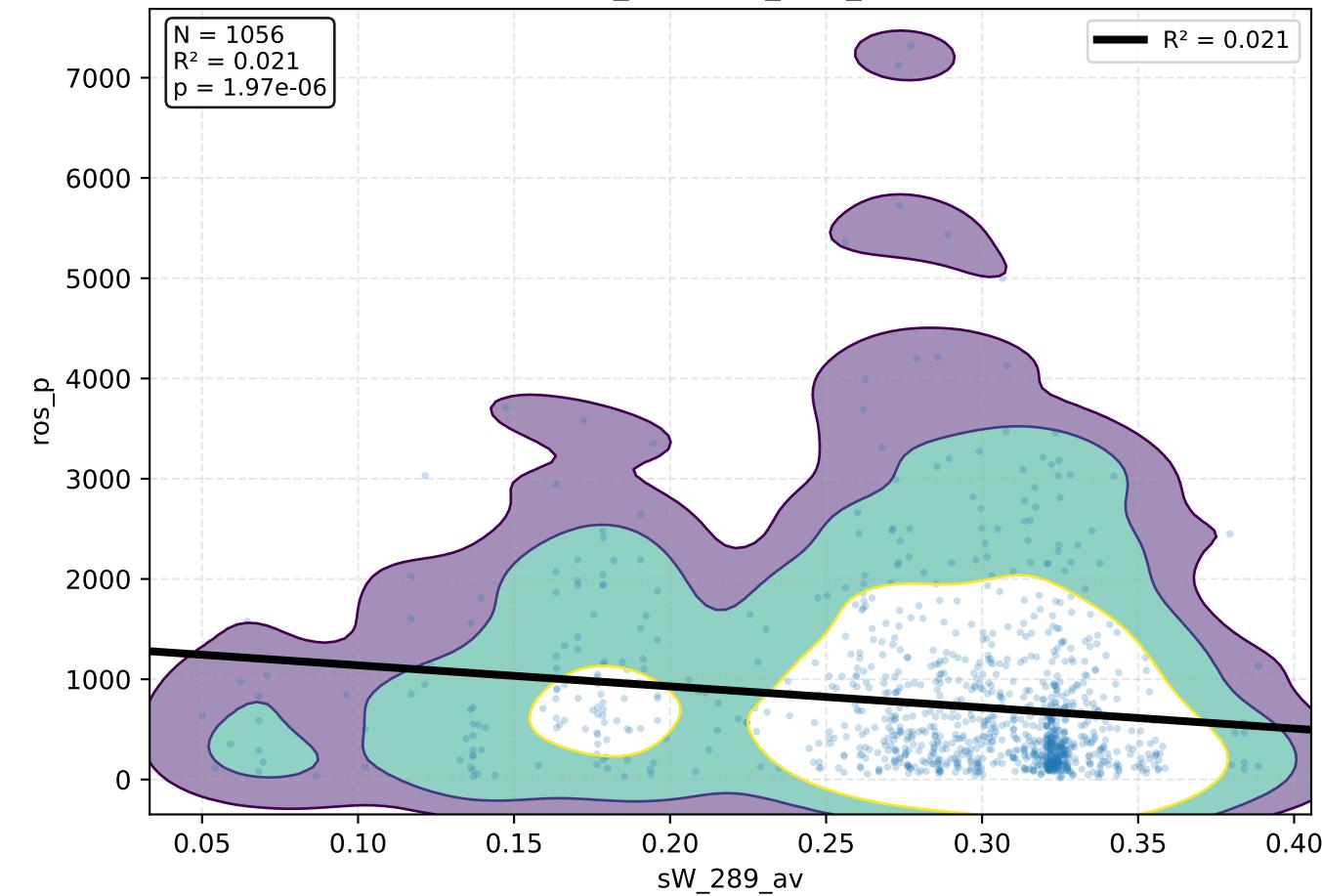


# sW\_100\_av - KDE Density + Regressão

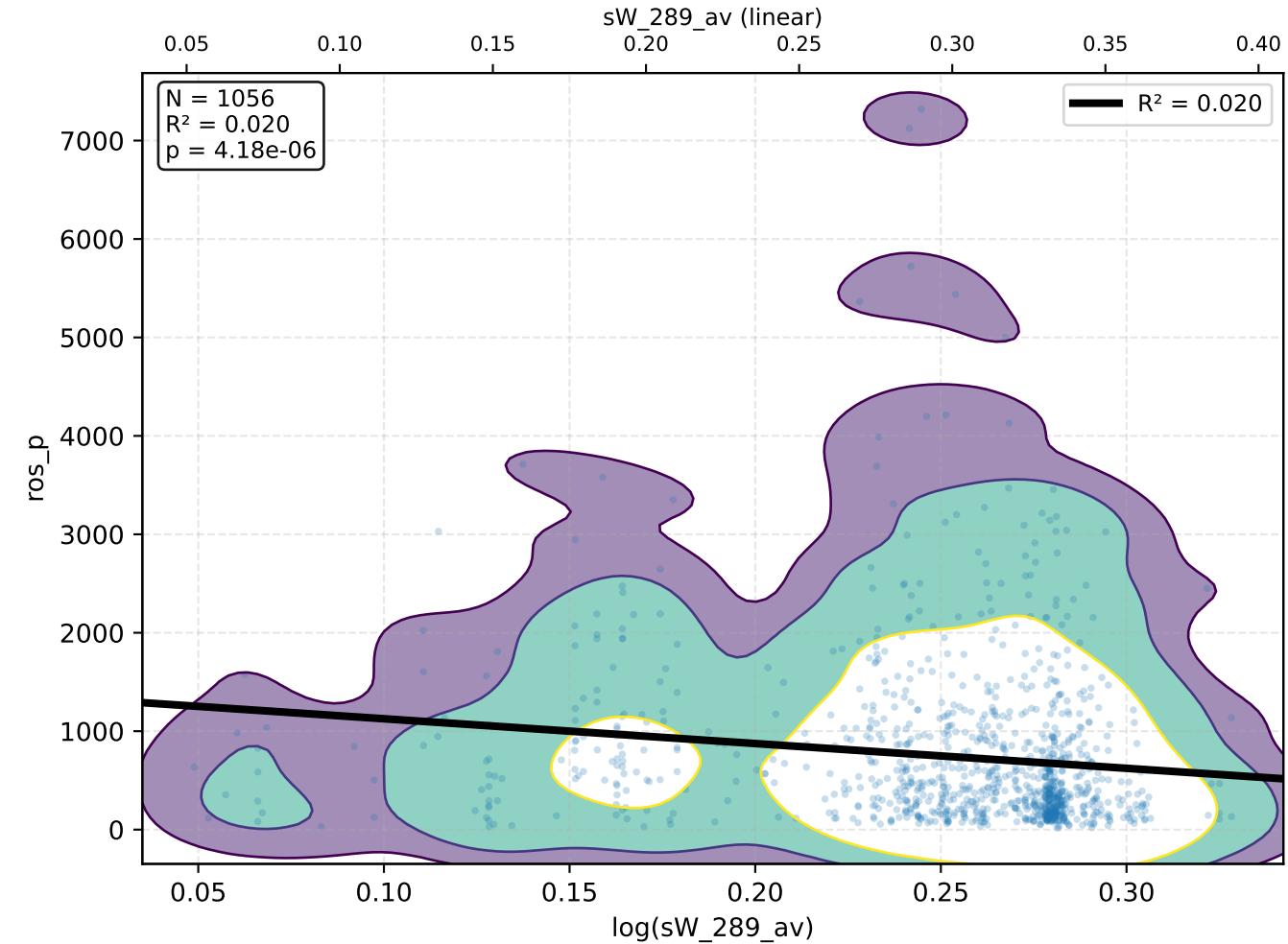


# sW\_289\_av - KDE Density + Regressão

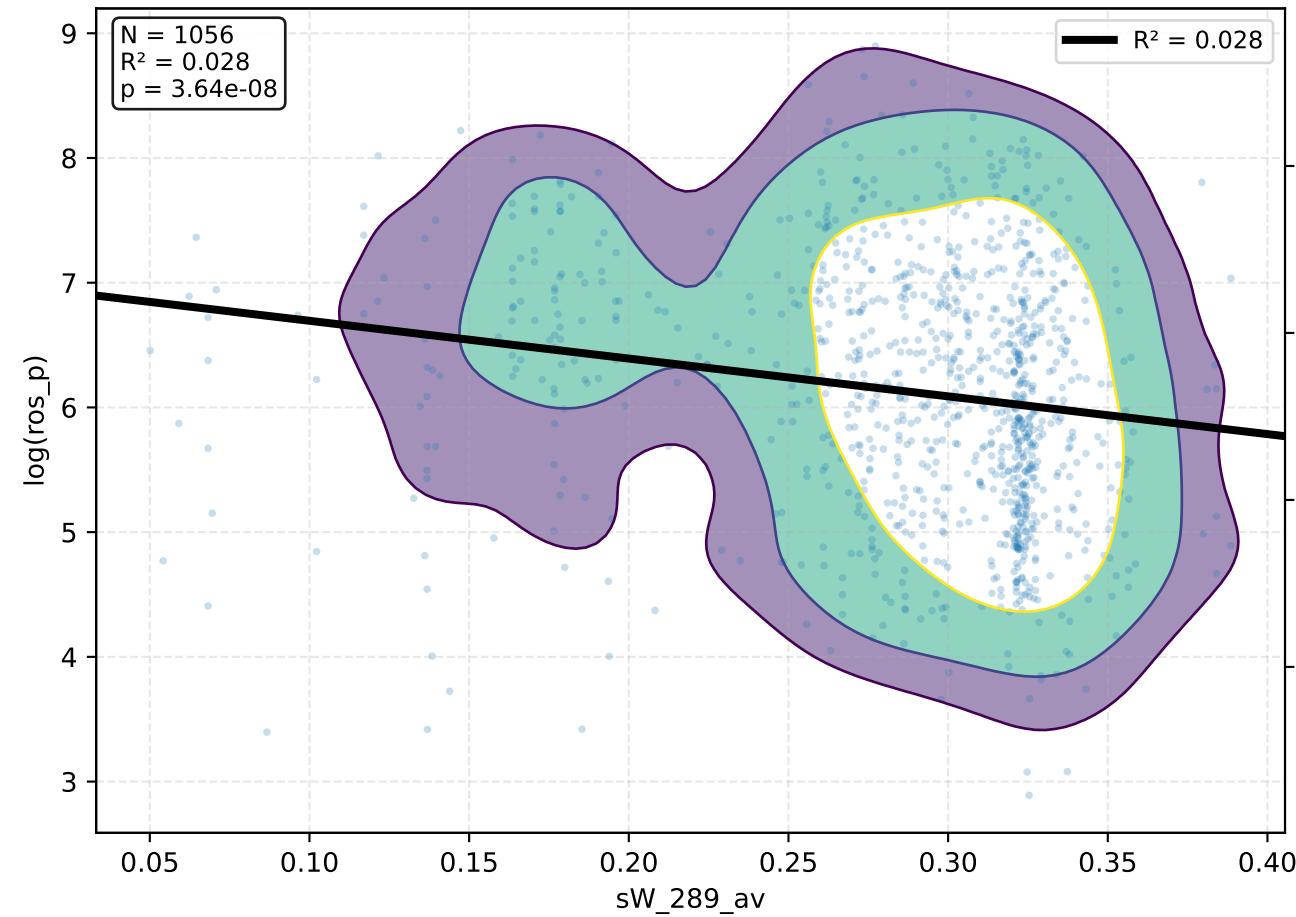
**ros\_p vs sW\_289\_av**



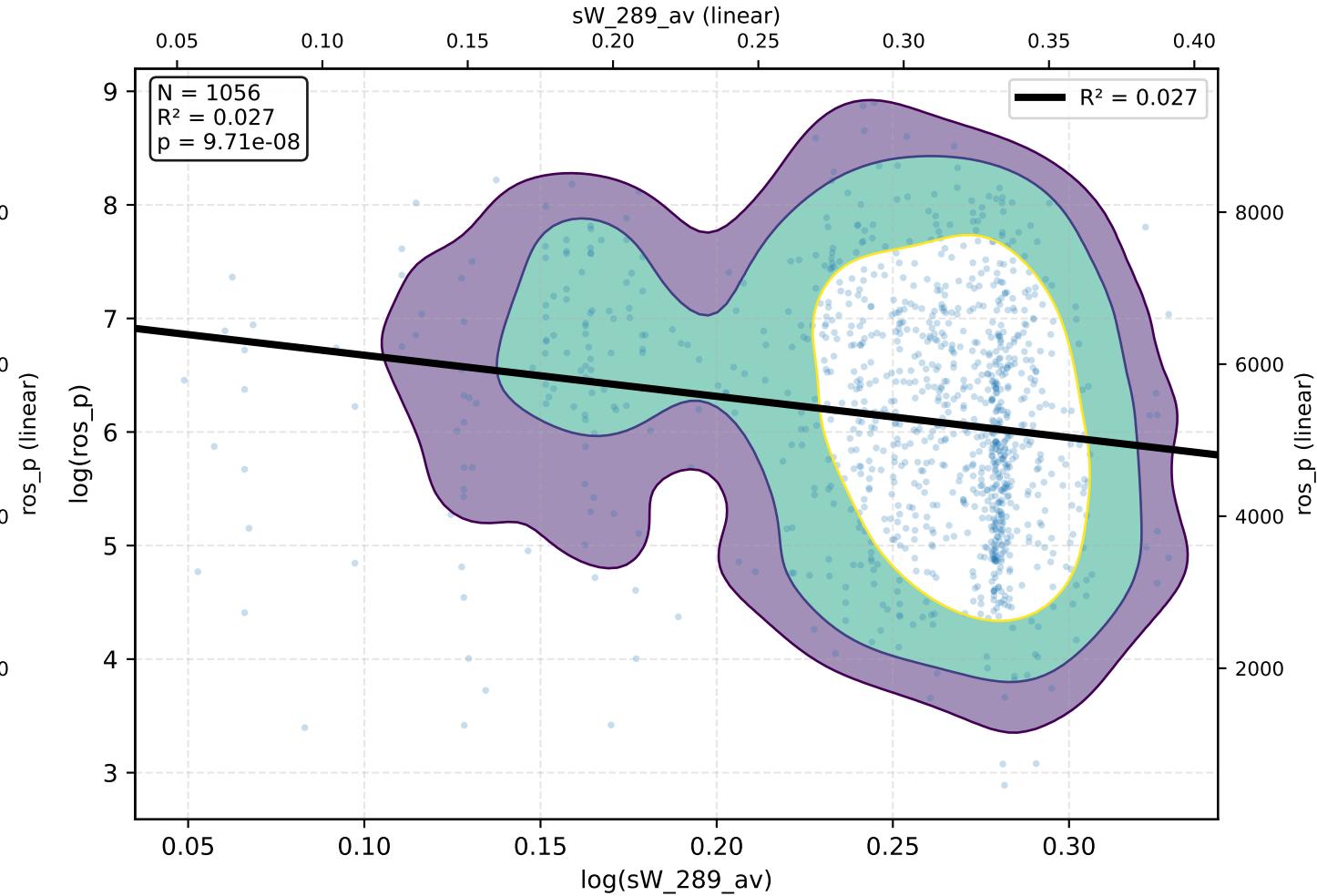
**ros\_p vs log(sW\_289\_av)**



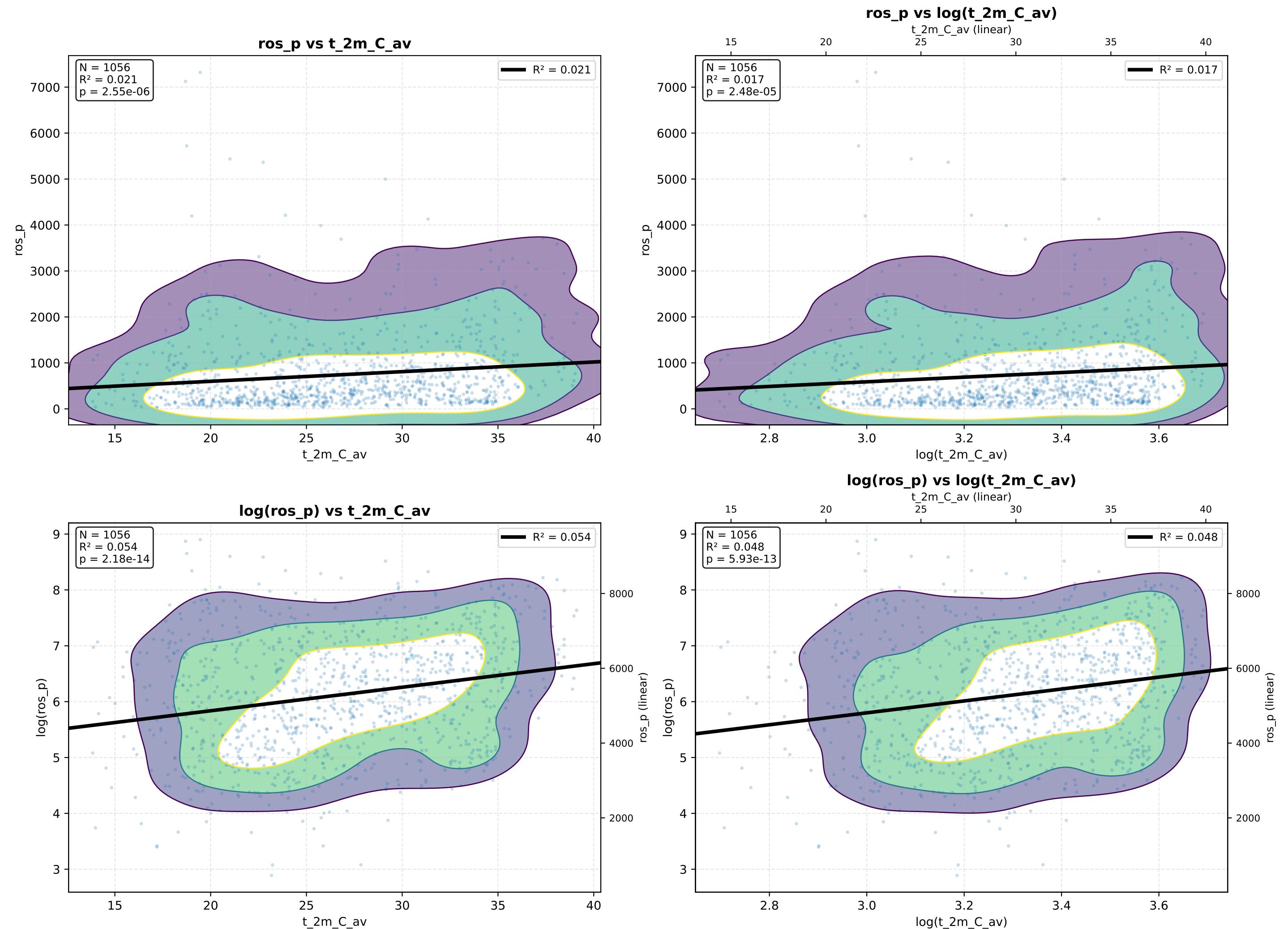
**log(ros\_p) vs sW\_289\_av**



**log(ros\_p) vs log(sW\_289\_av)**

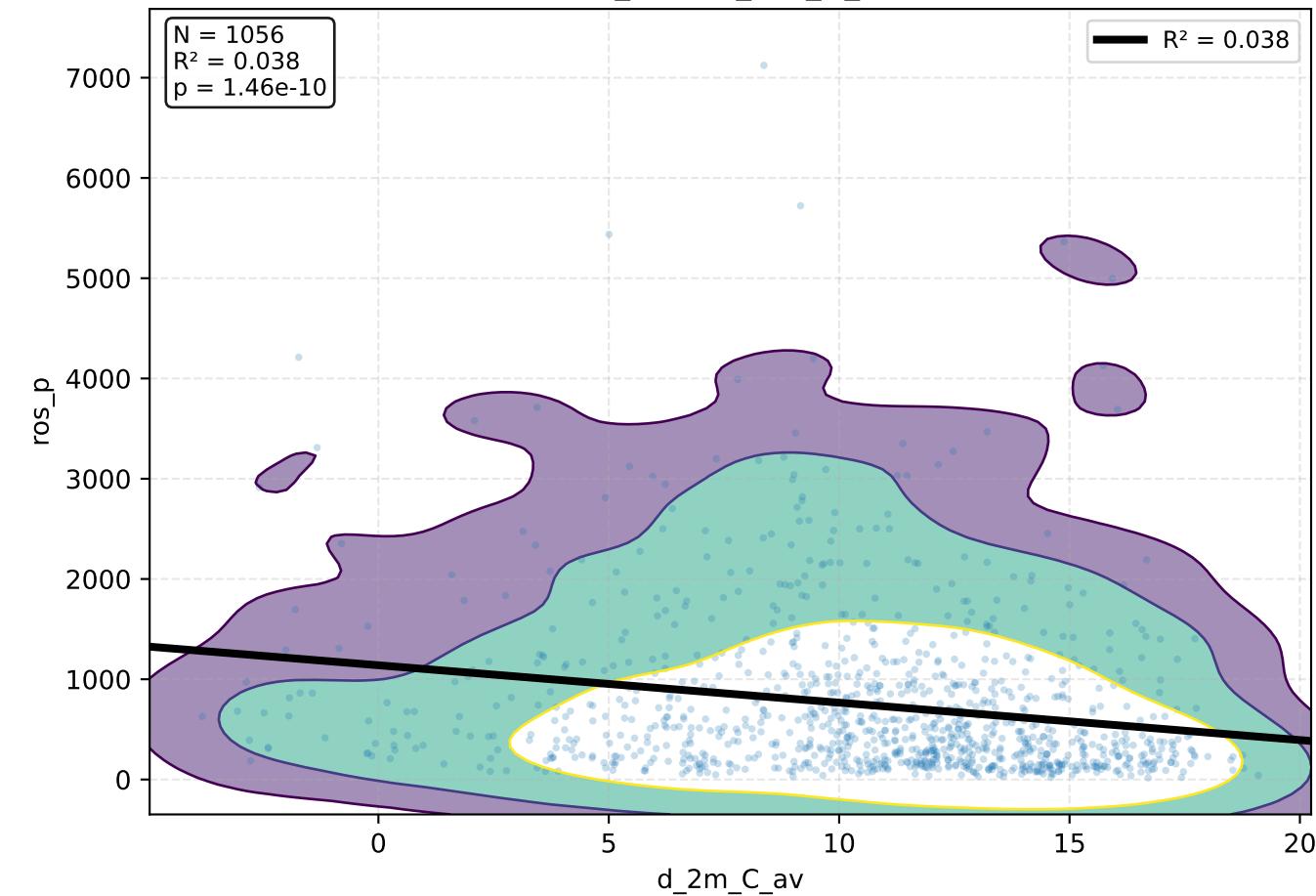


# t\_2m\_C\_av - KDE Density + Regressão

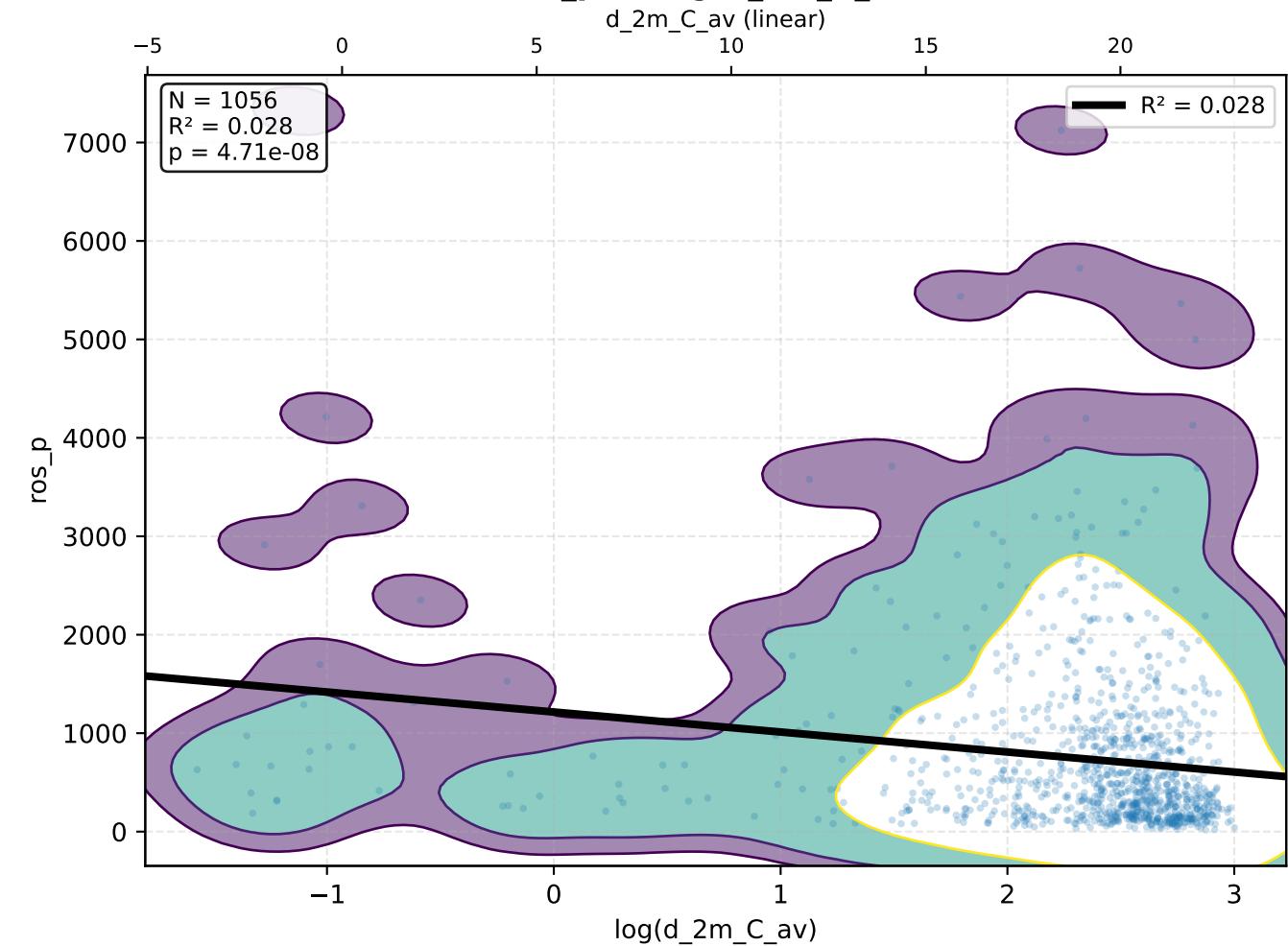


# d\_2m\_C\_av - KDE Density + Regressão

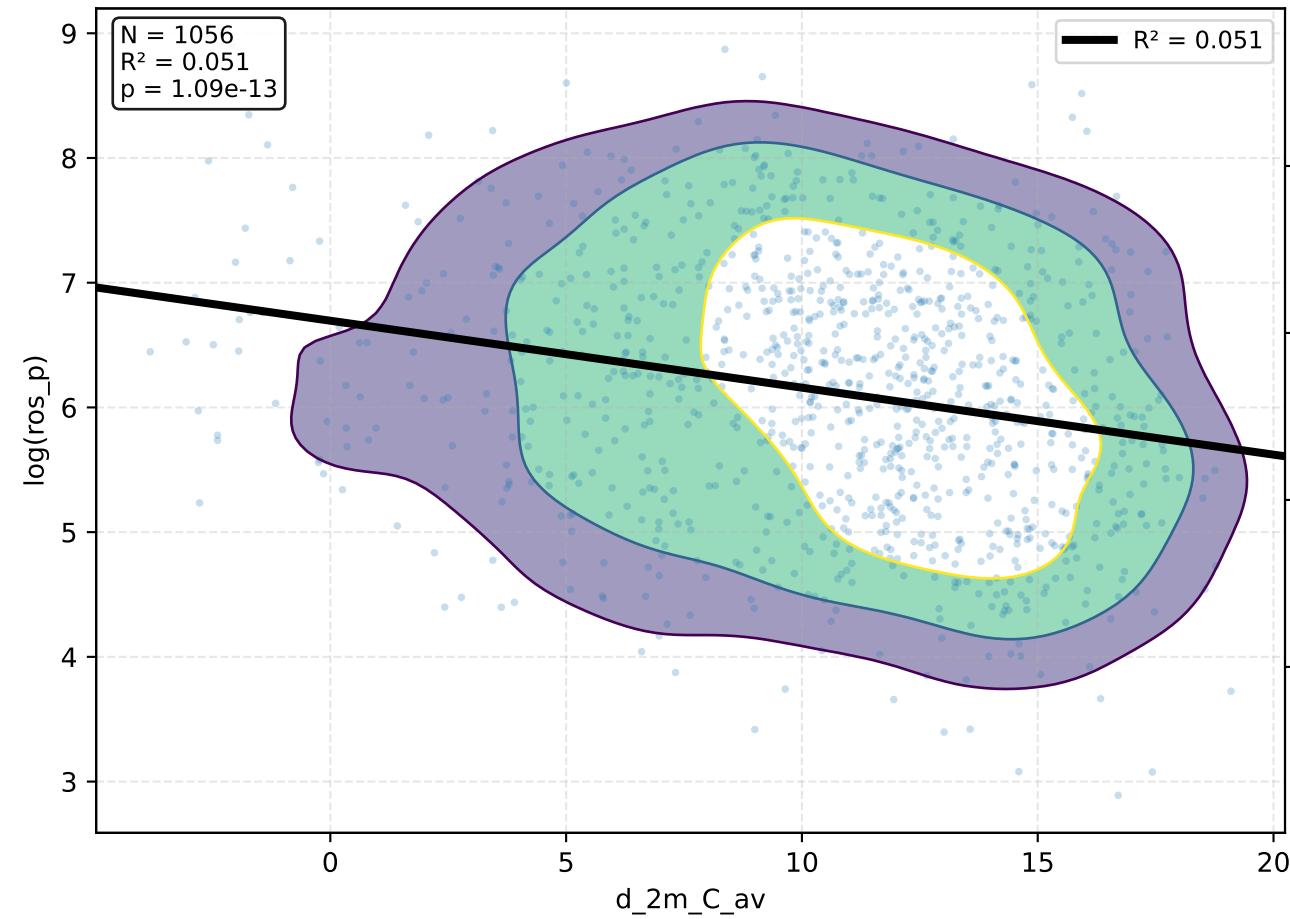
**ros\_p vs d\_2m\_C\_av**



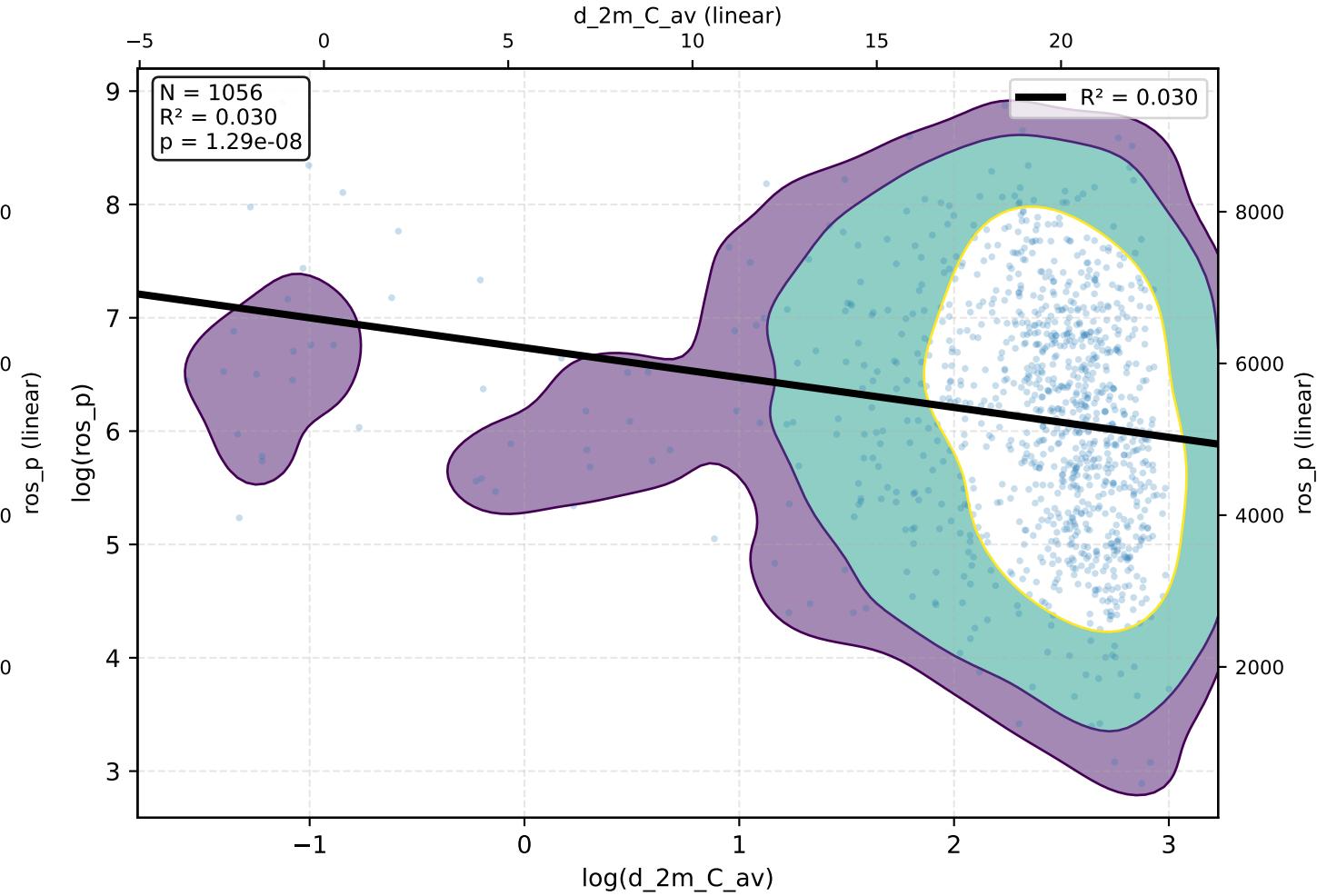
**ros\_p vs log(d\_2m\_C\_av)**



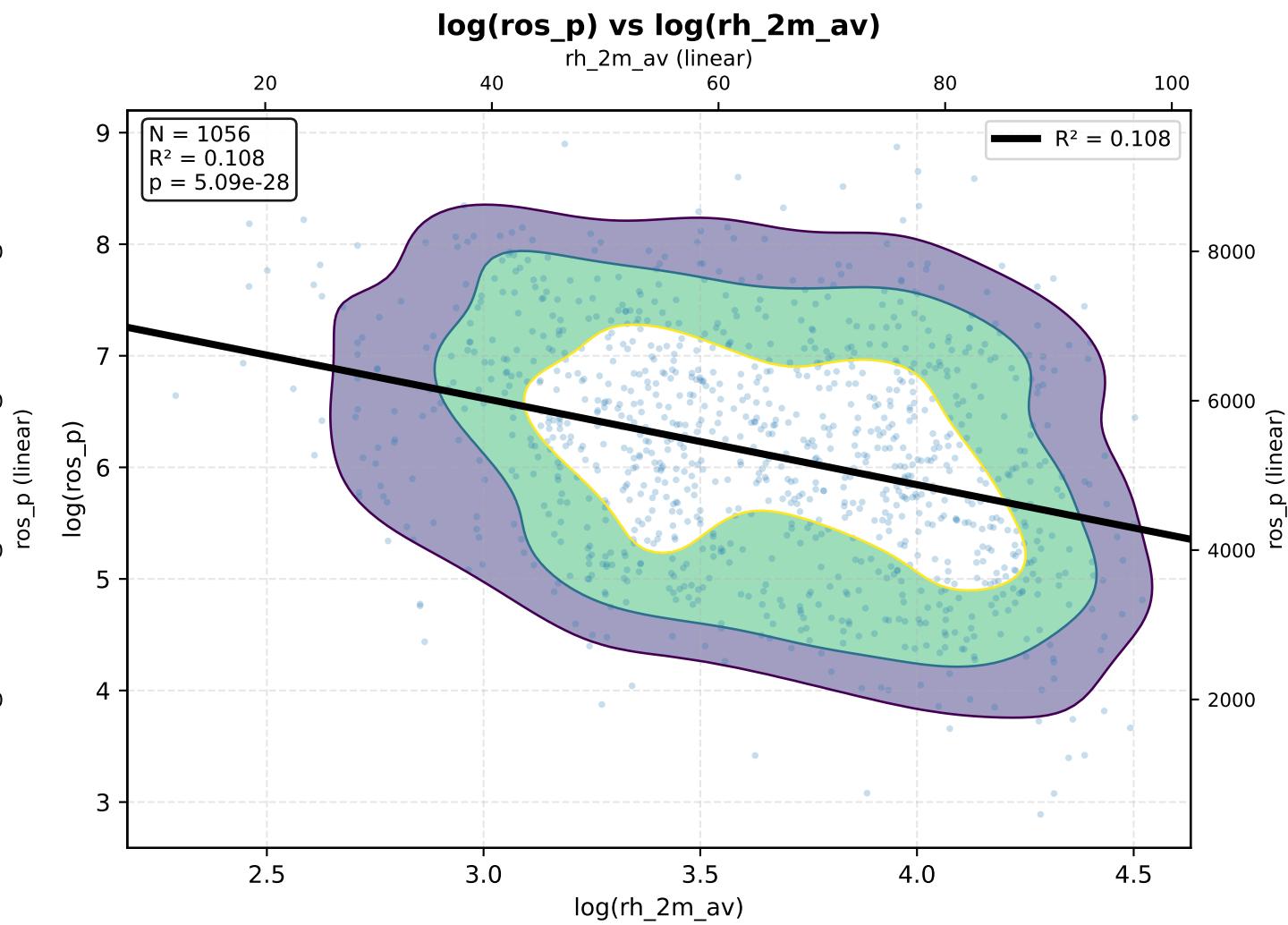
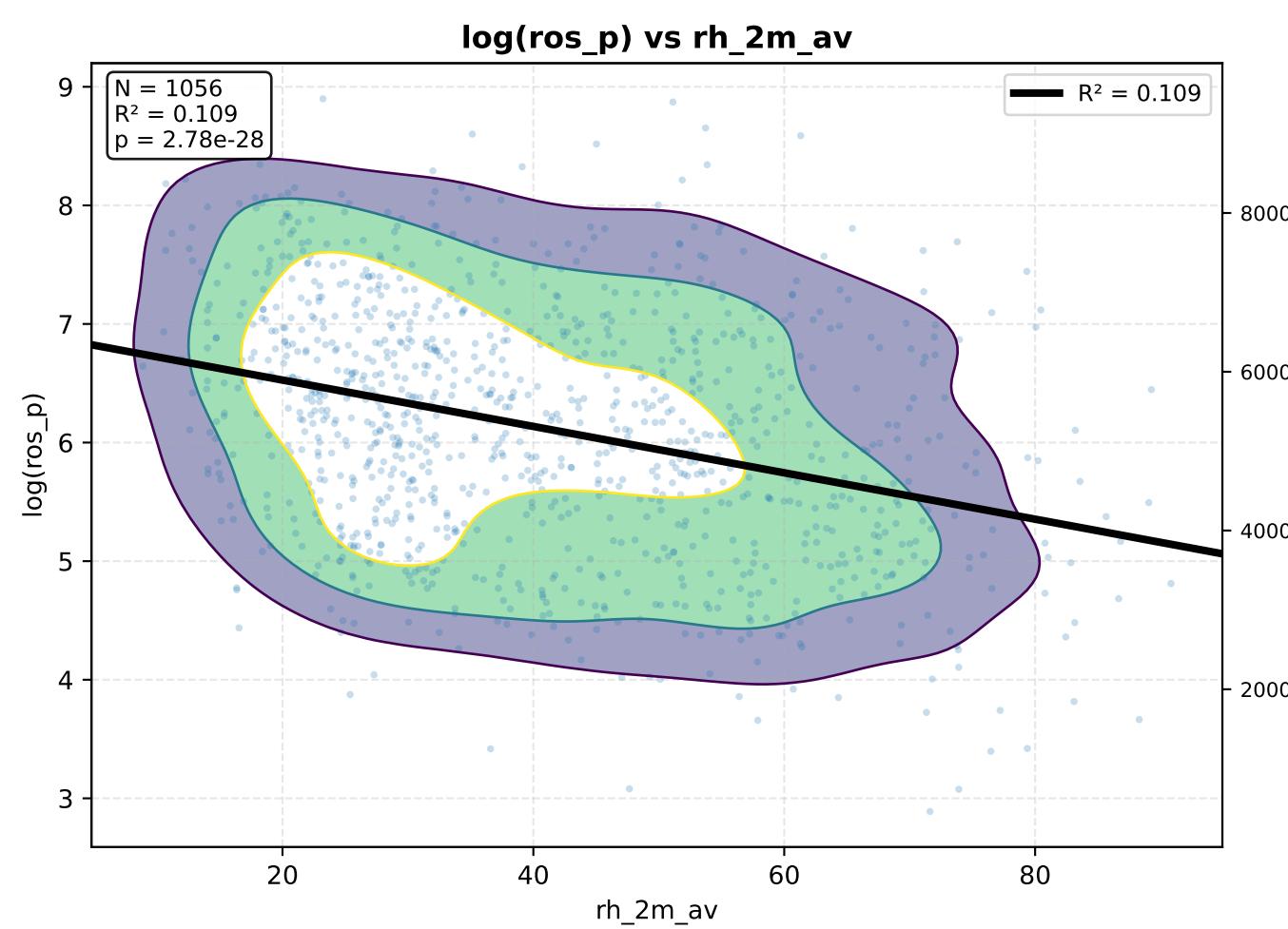
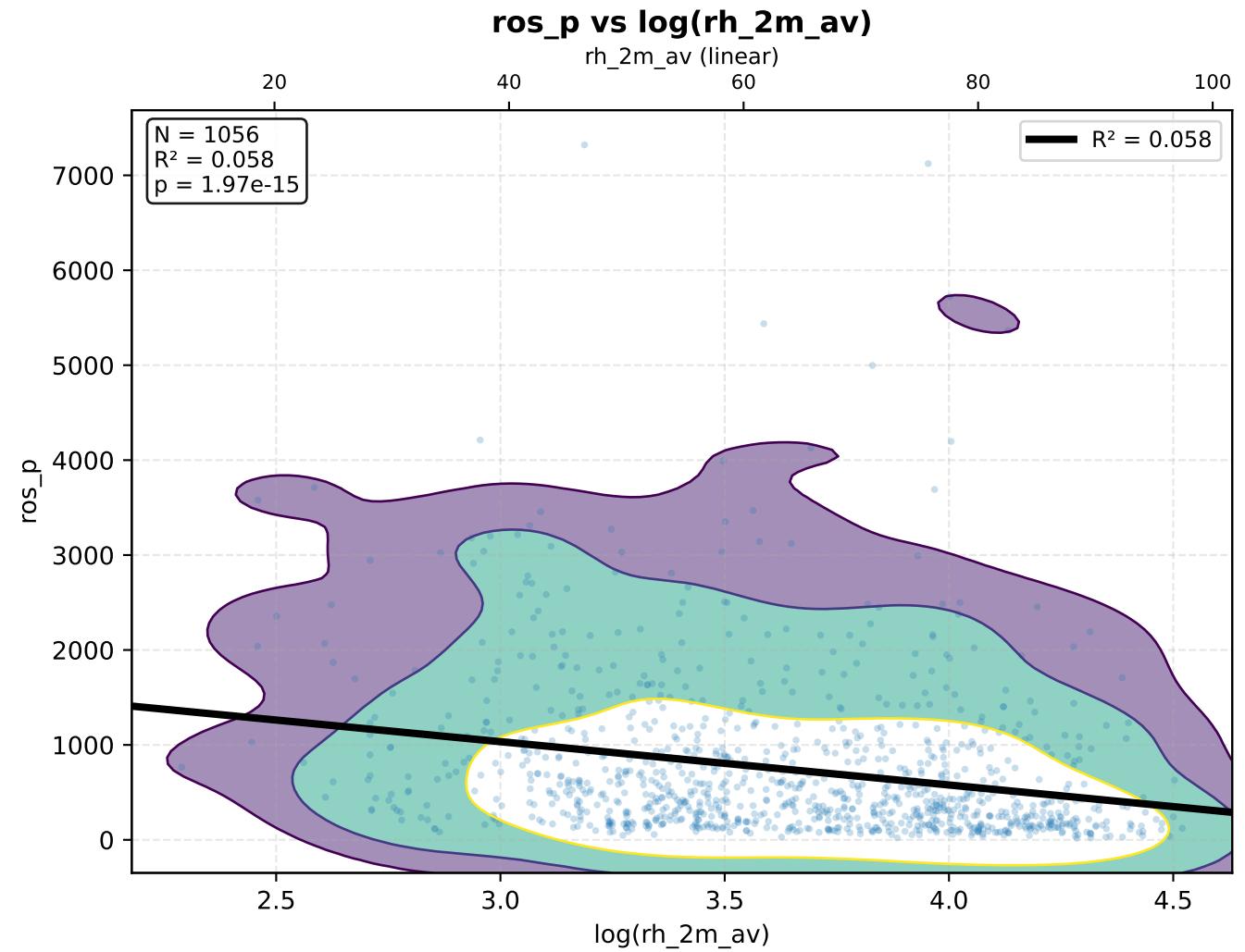
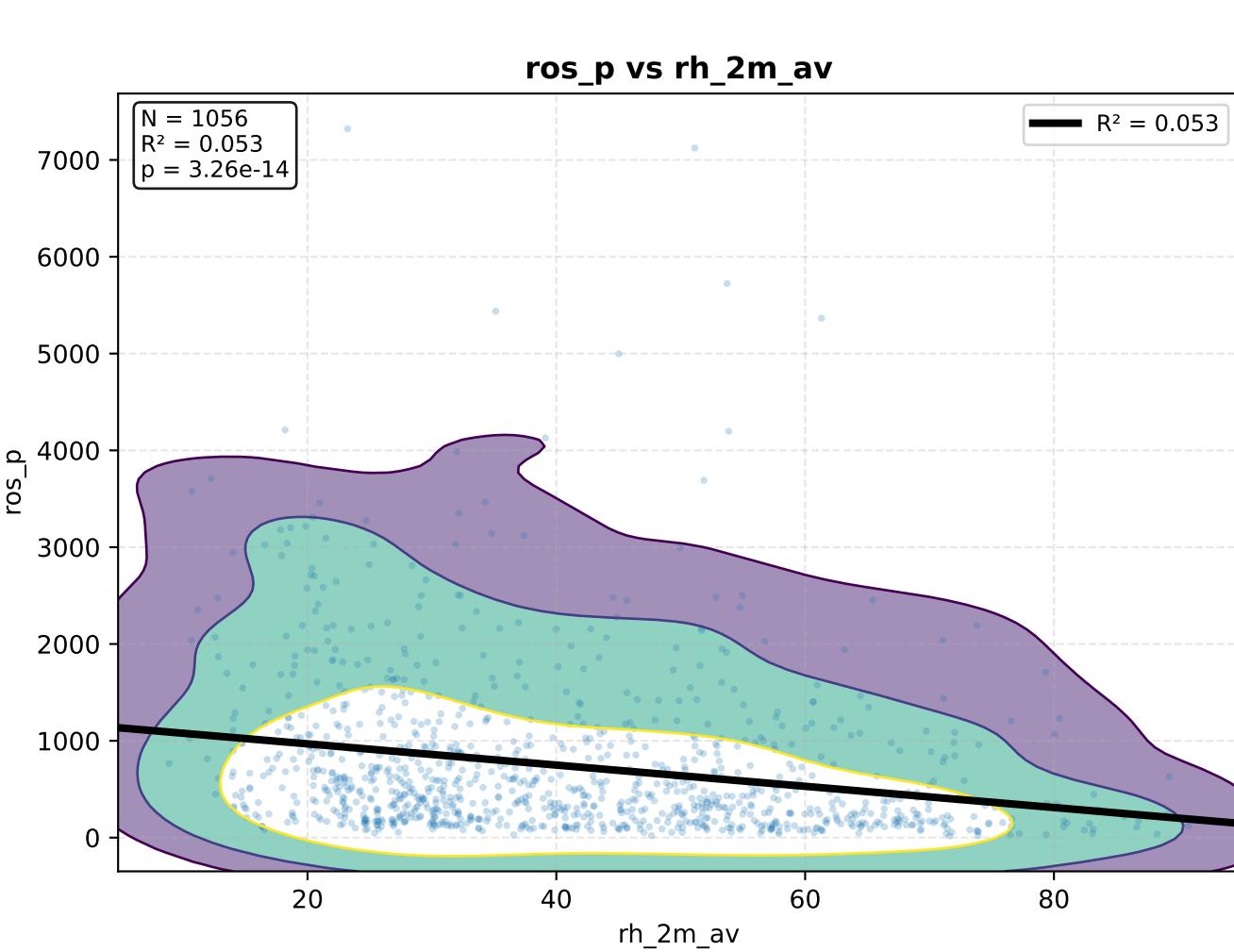
**log(ros\_p) vs d\_2m\_C\_av**



**log(ros\_p) vs log(d\_2m\_C\_av)**

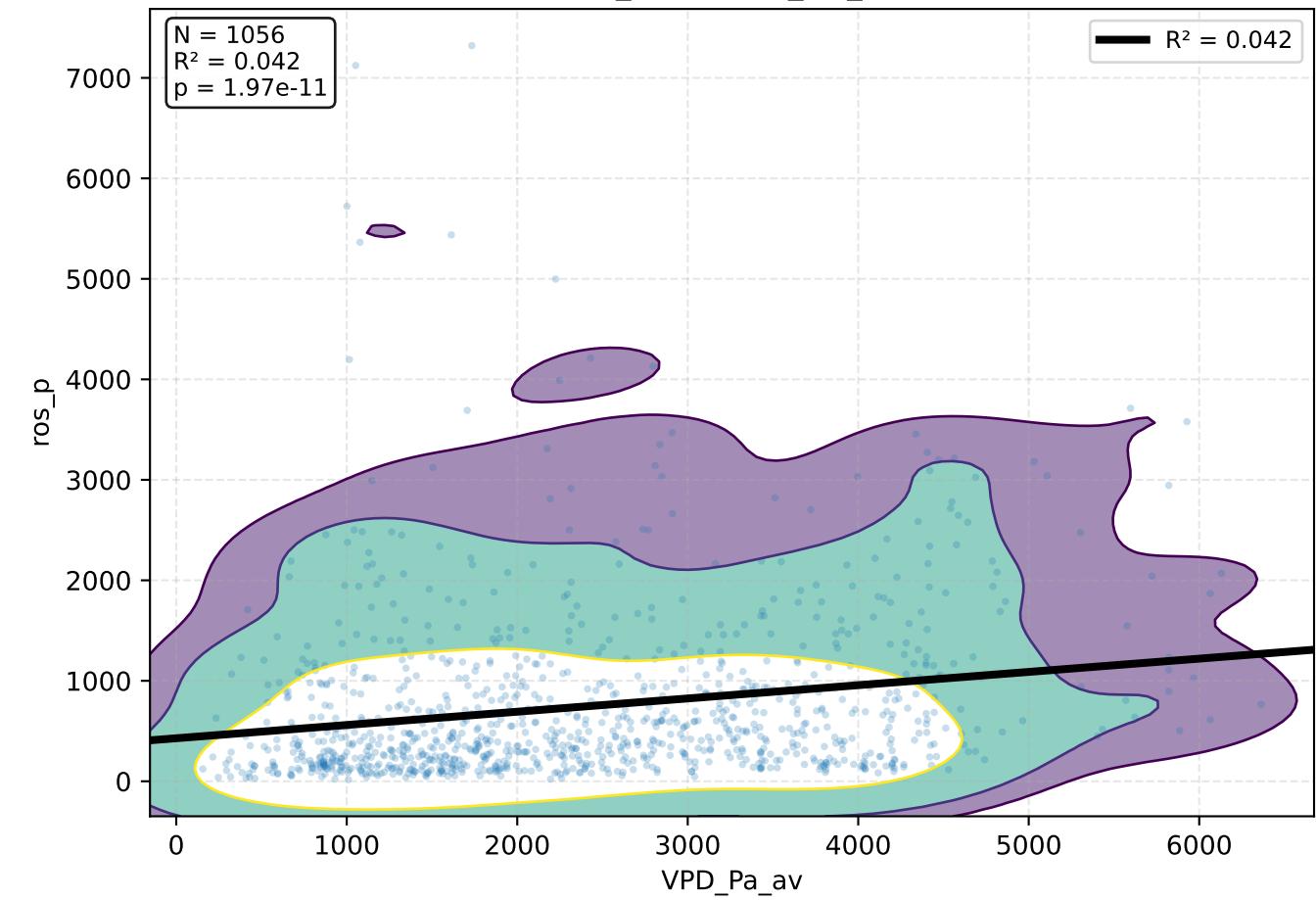


# rh\_2m\_av - KDE Density + Regressão

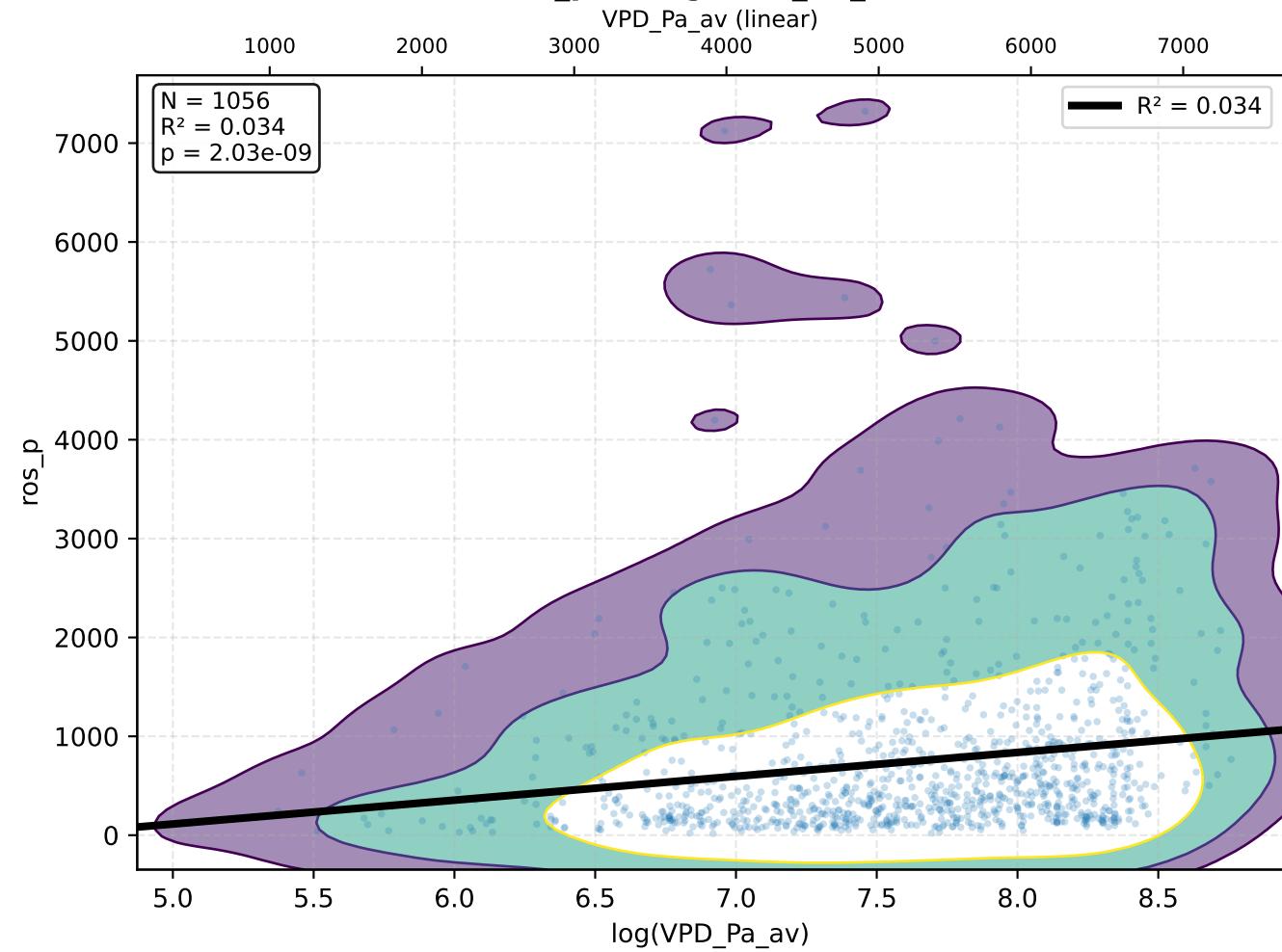


# VPD\_Pa\_av – KDE Density + Regressão

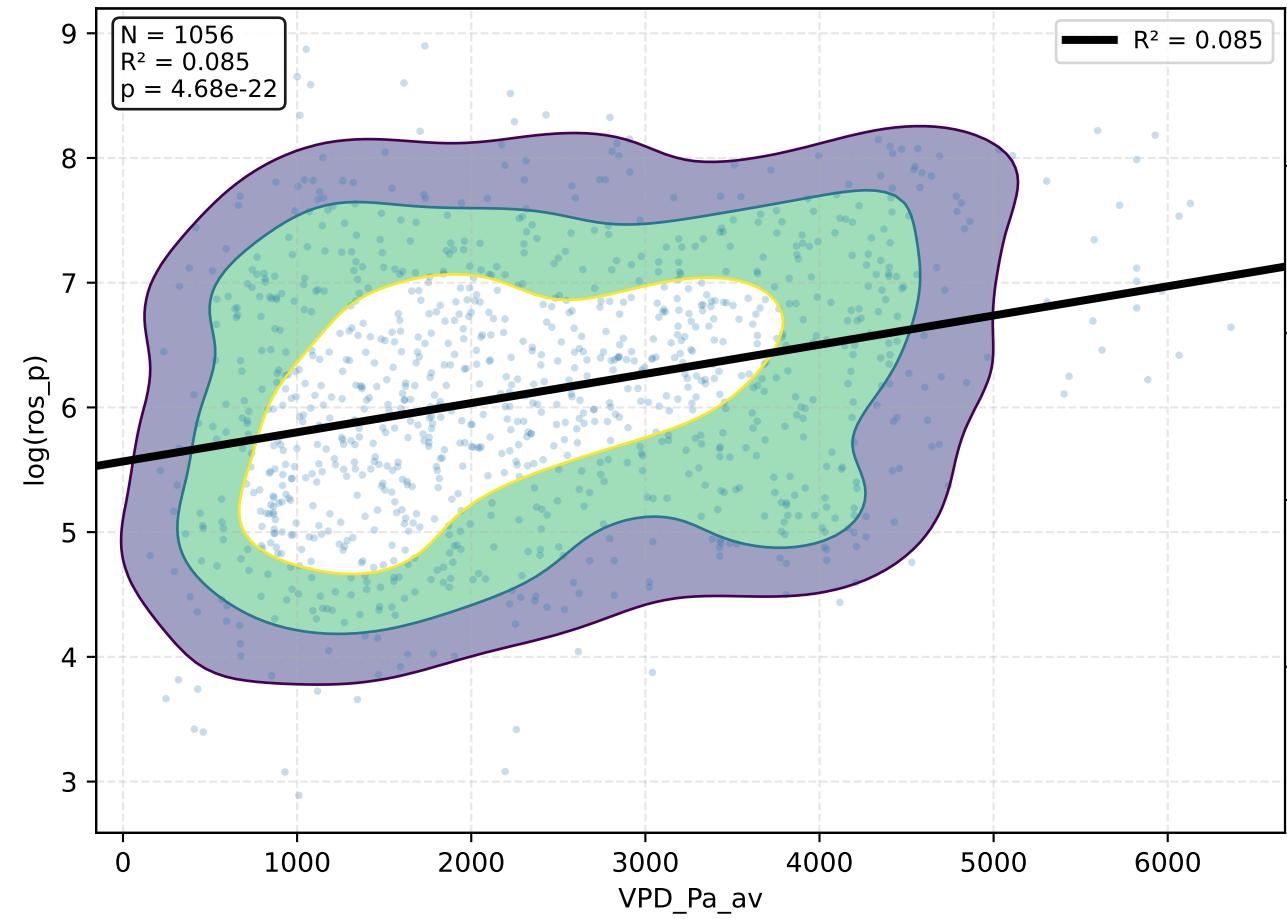
**ros\_p vs VPD\_Pa\_av**



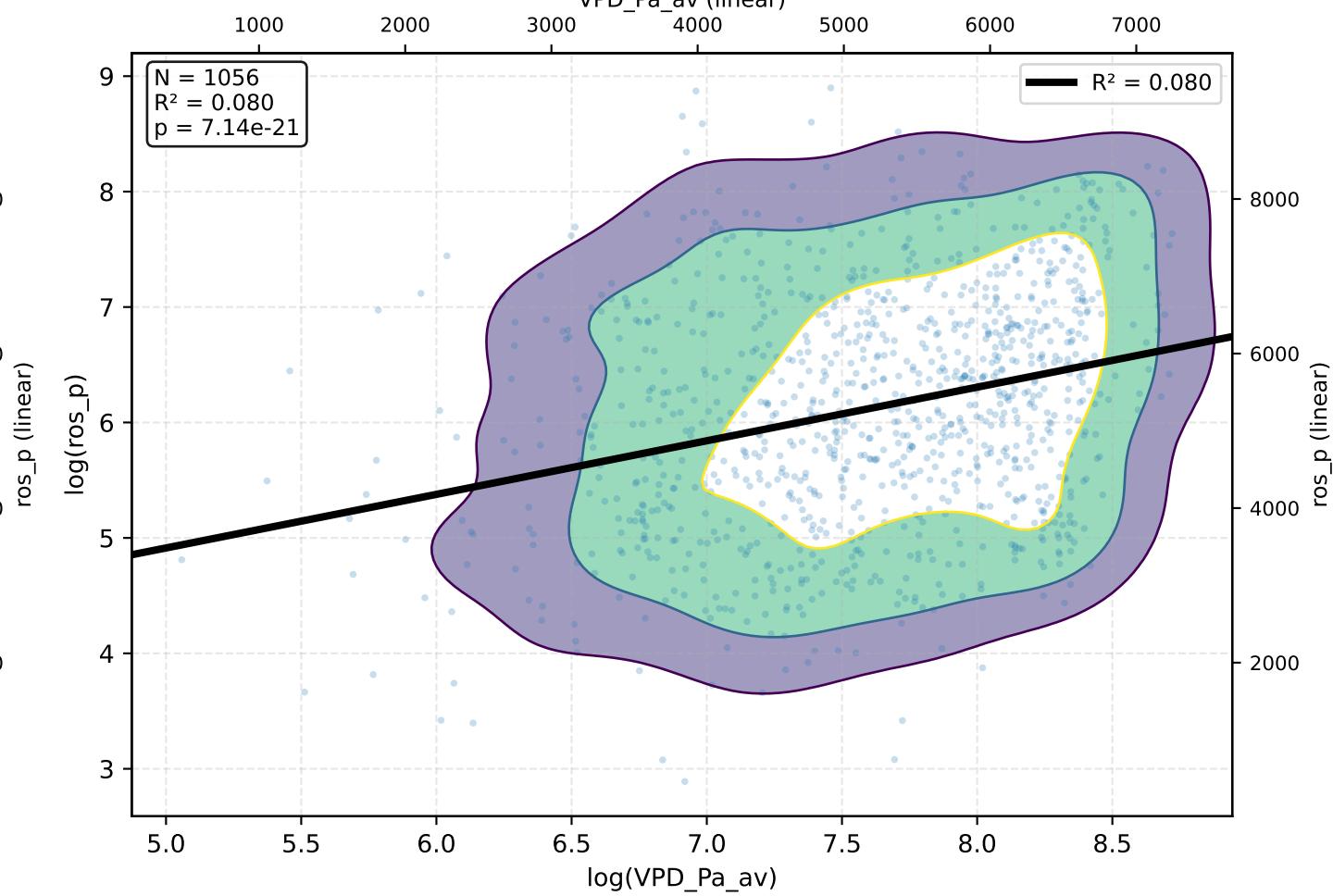
**ros\_p vs log(VPD\_Pa\_av)**



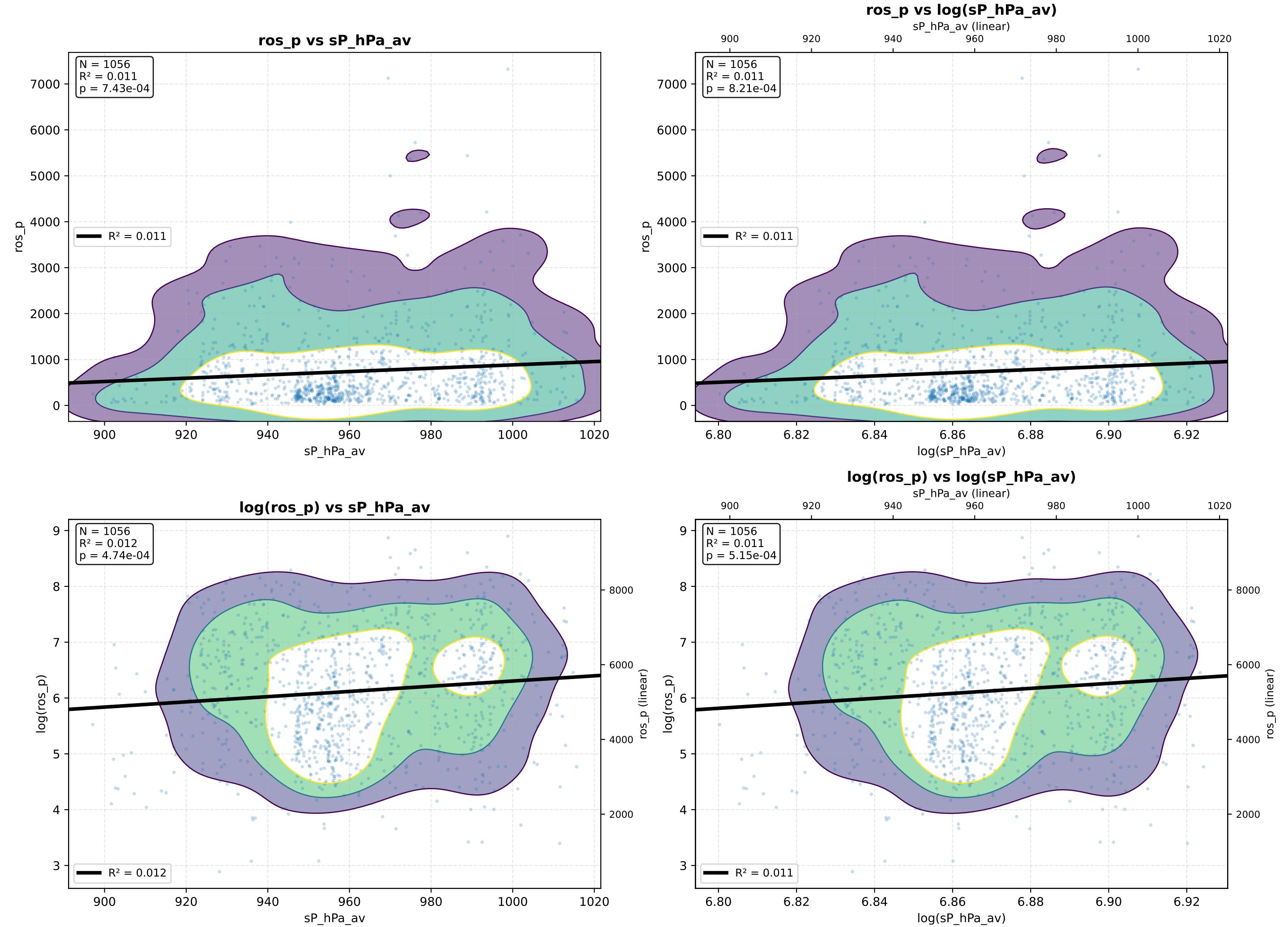
**log(ros\_p) vs VPD\_Pa\_av**



**log(ros\_p) vs log(VPD\_Pa\_av)**

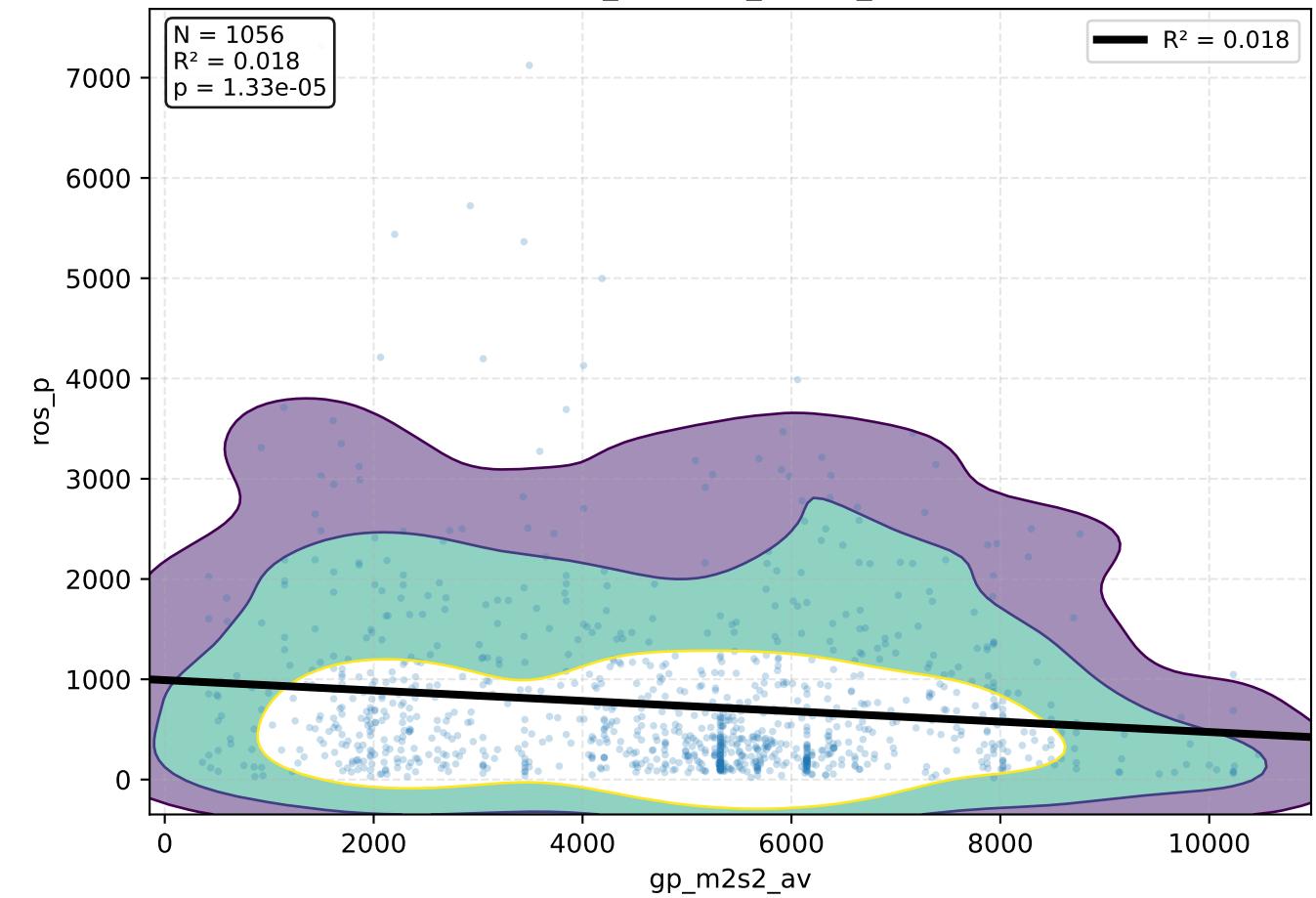


# sP\_hPa\_av – KDE Density + Regressão

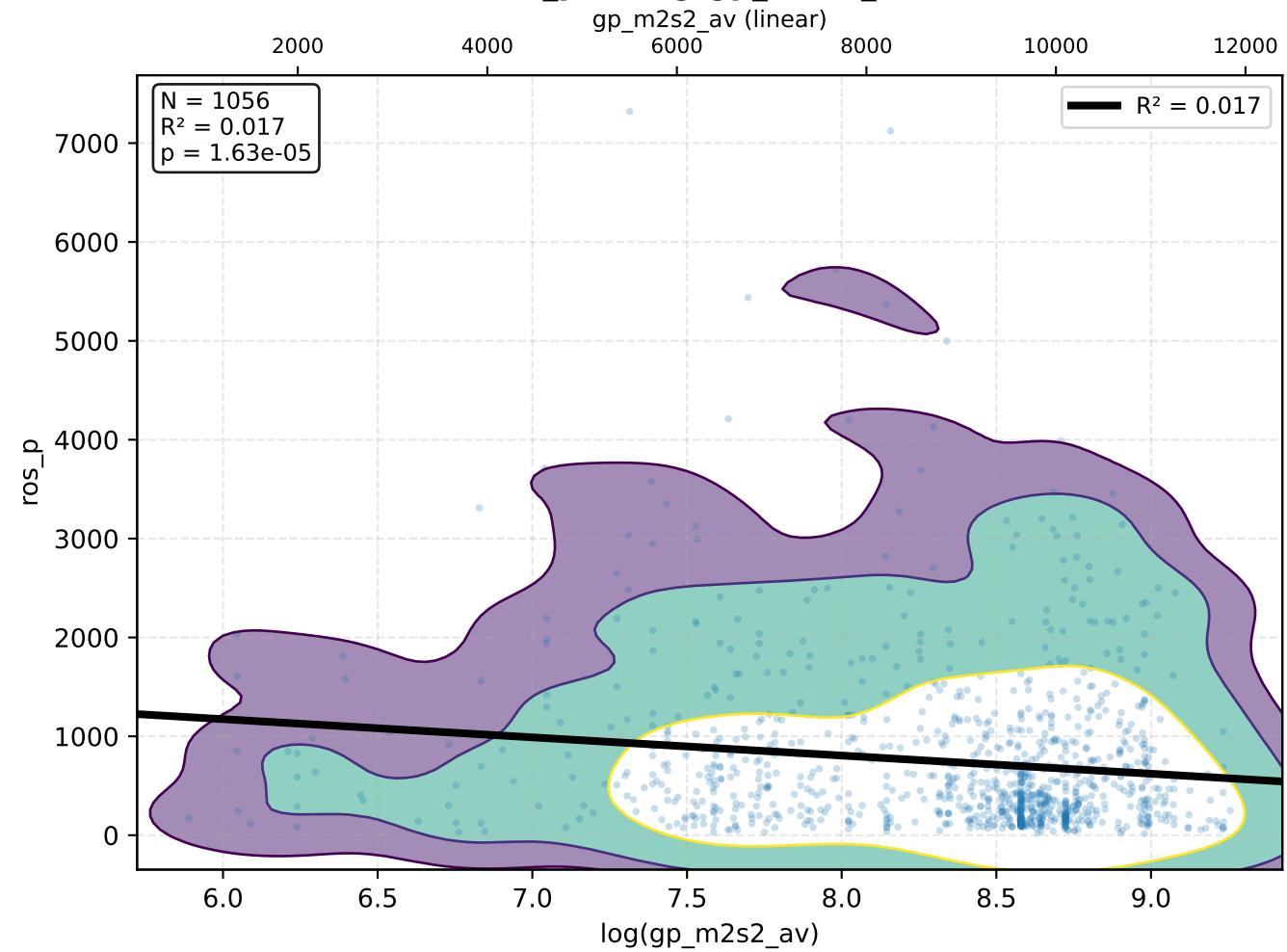


# gp\_m2s2\_av – KDE Density + Regressão

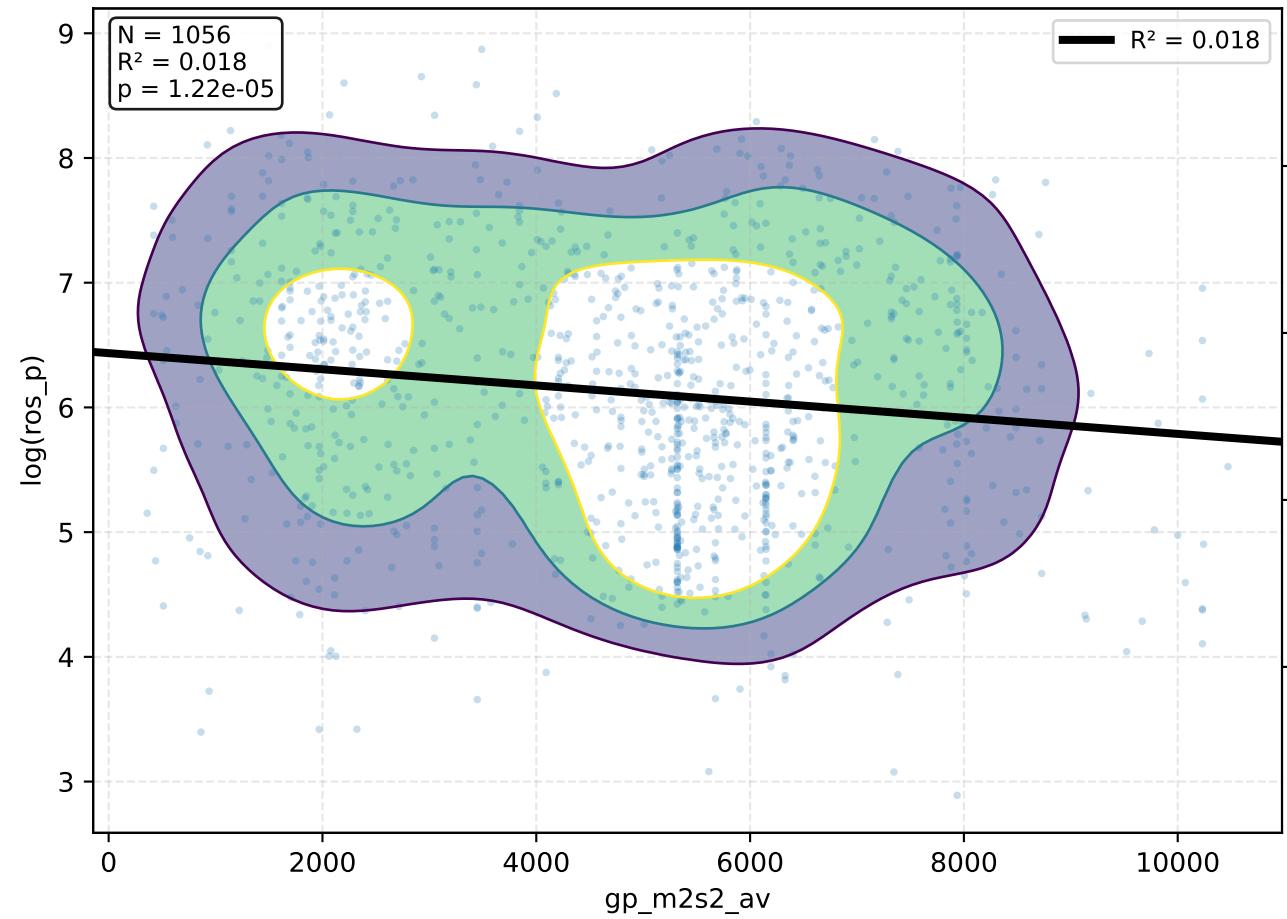
**ros\_p vs gp\_m2s2\_av**



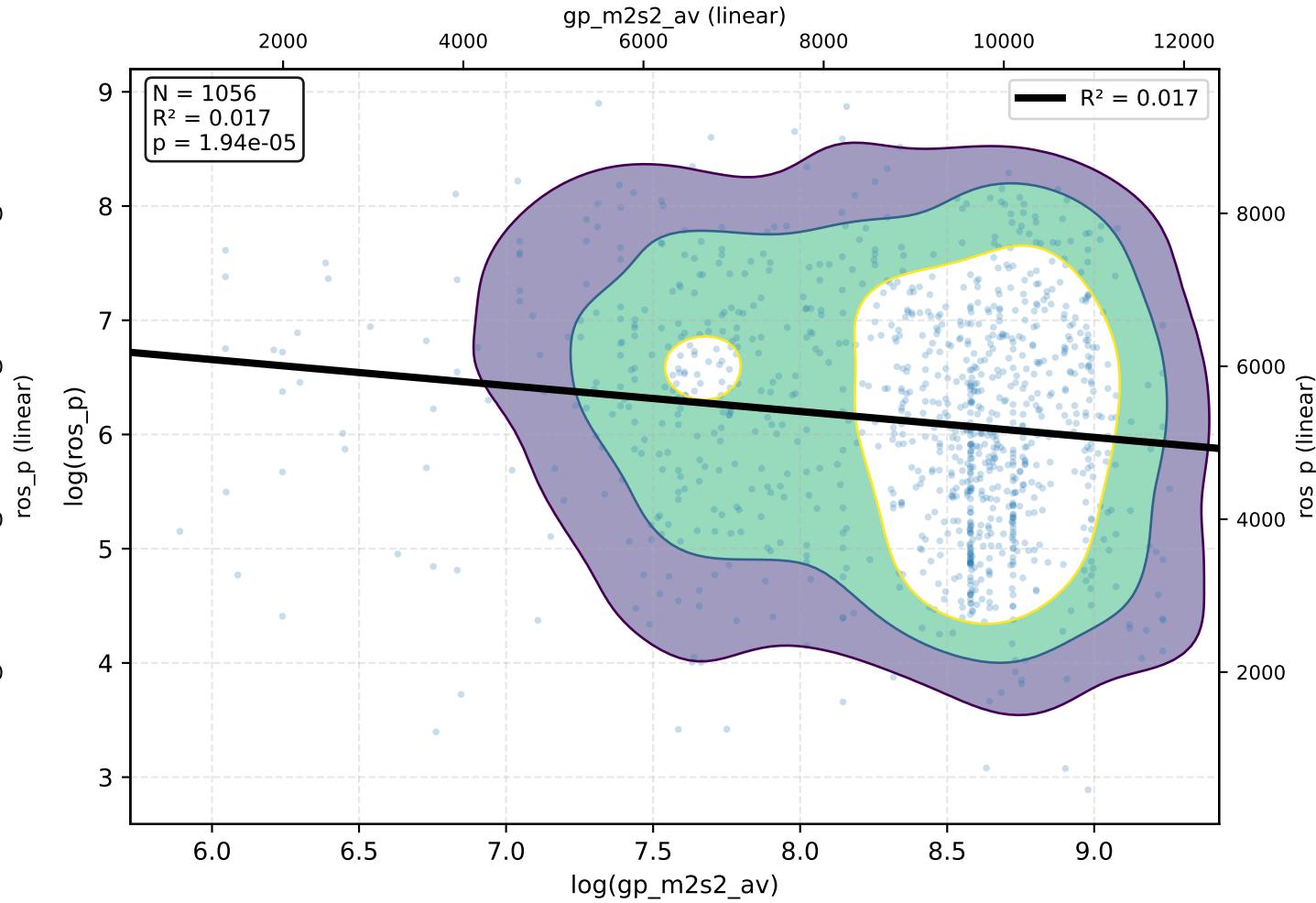
**ros\_p vs log(gp\_m2s2\_av)**



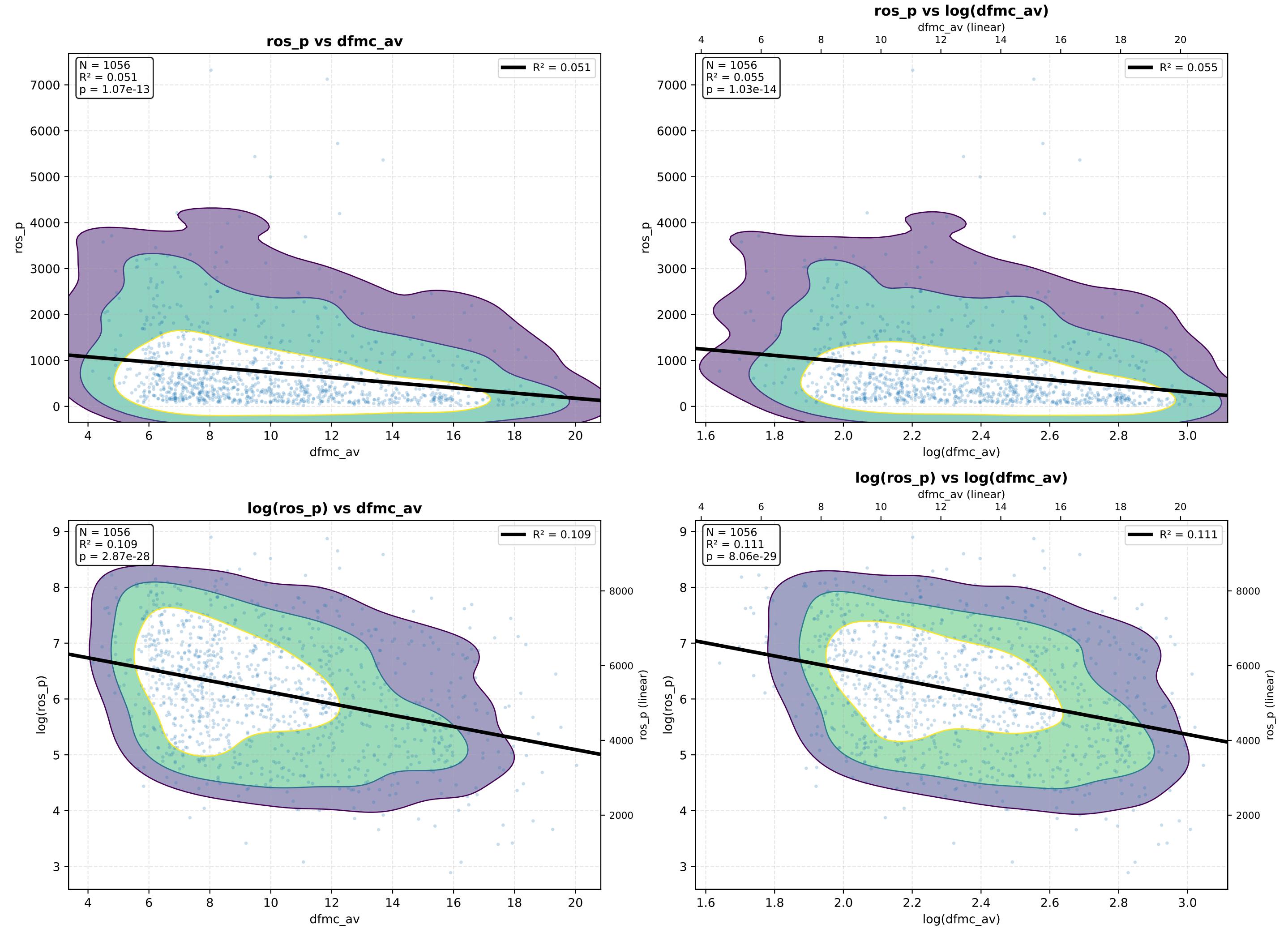
**log(ros\_p) vs gp\_m2s2\_av**



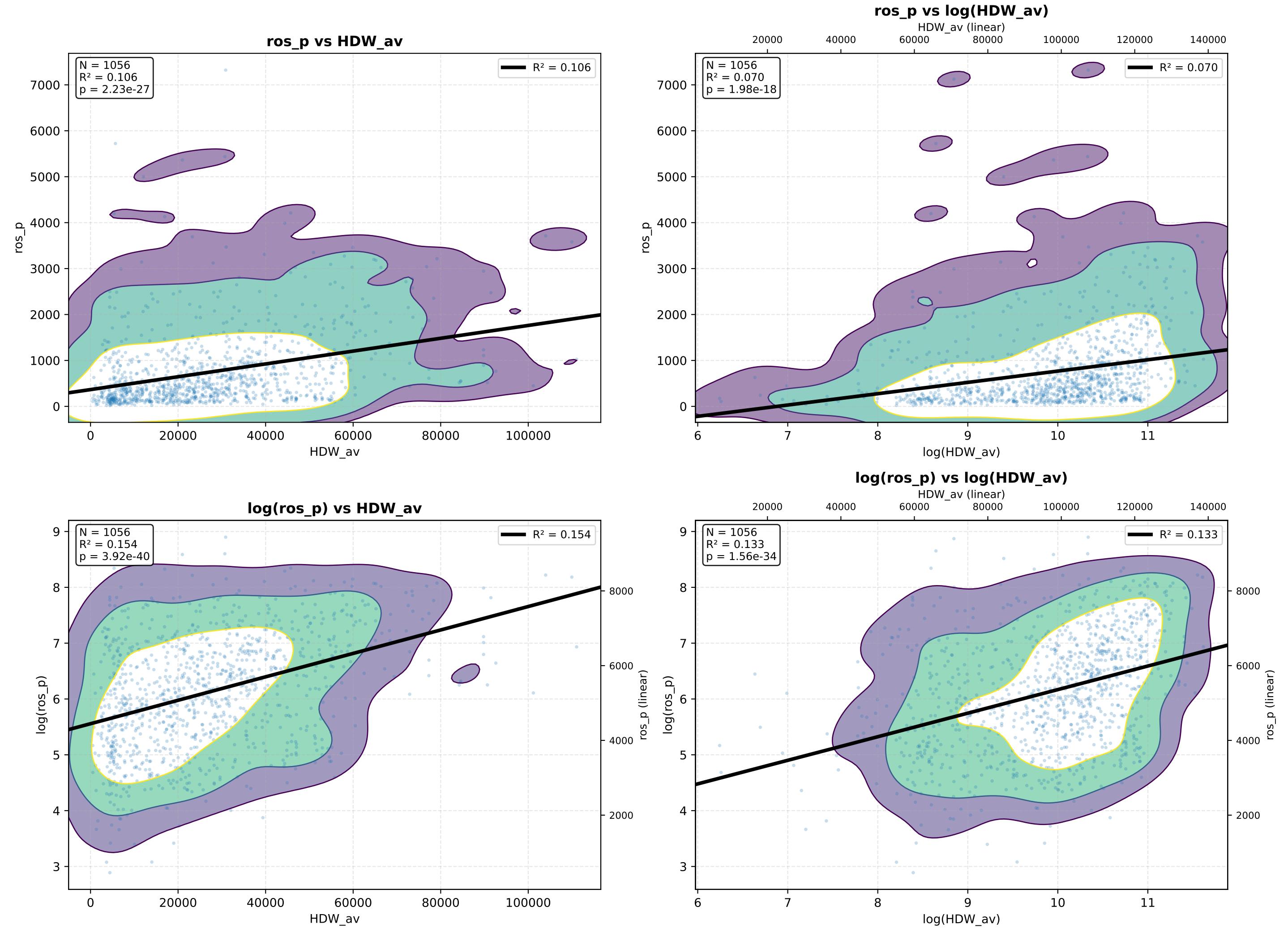
**log(ros\_p) vs log(gp\_m2s2\_av)**



# dfmc\_av - KDE Density + Regressão

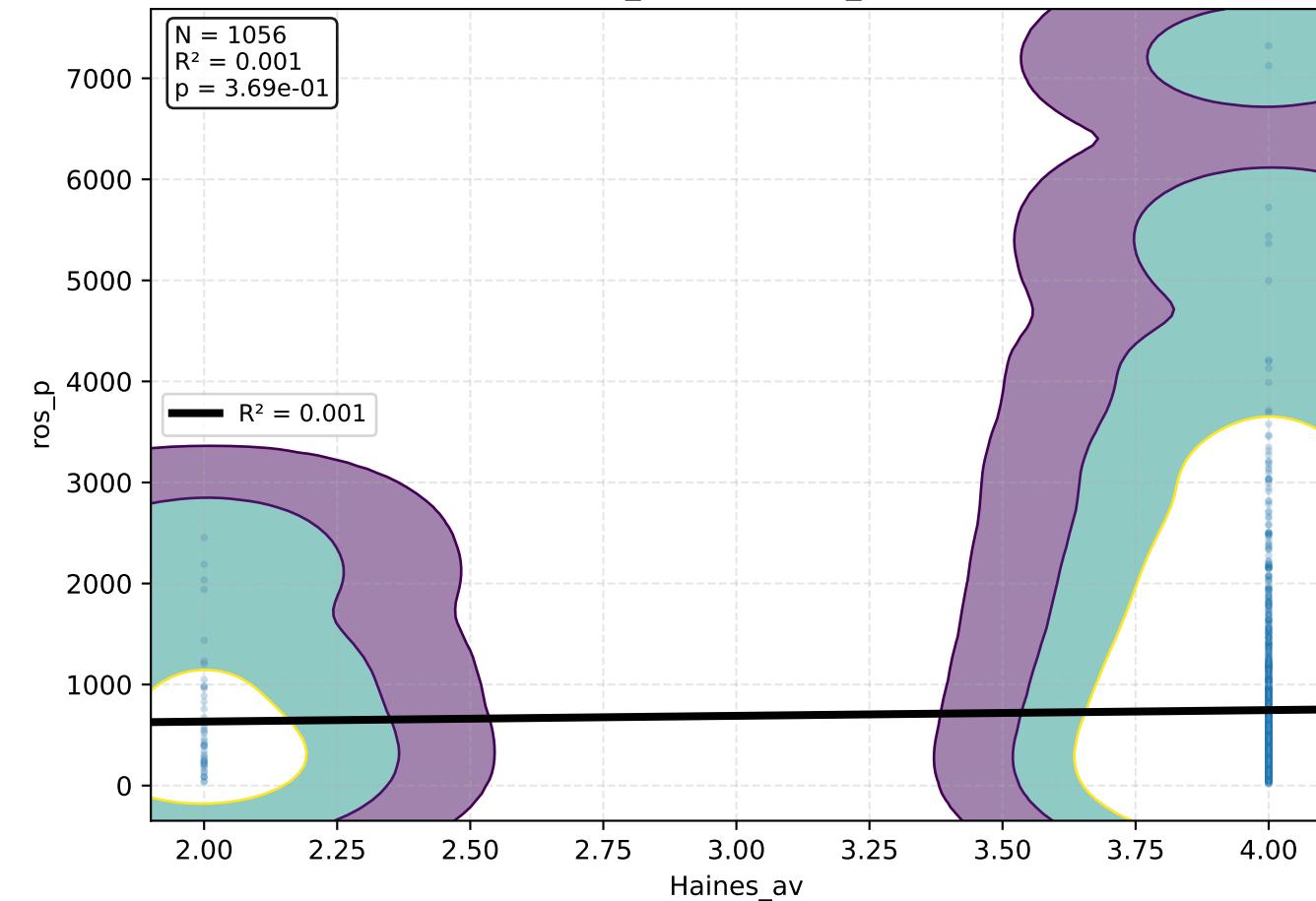


# HDW\_av - KDE Density + Regressão

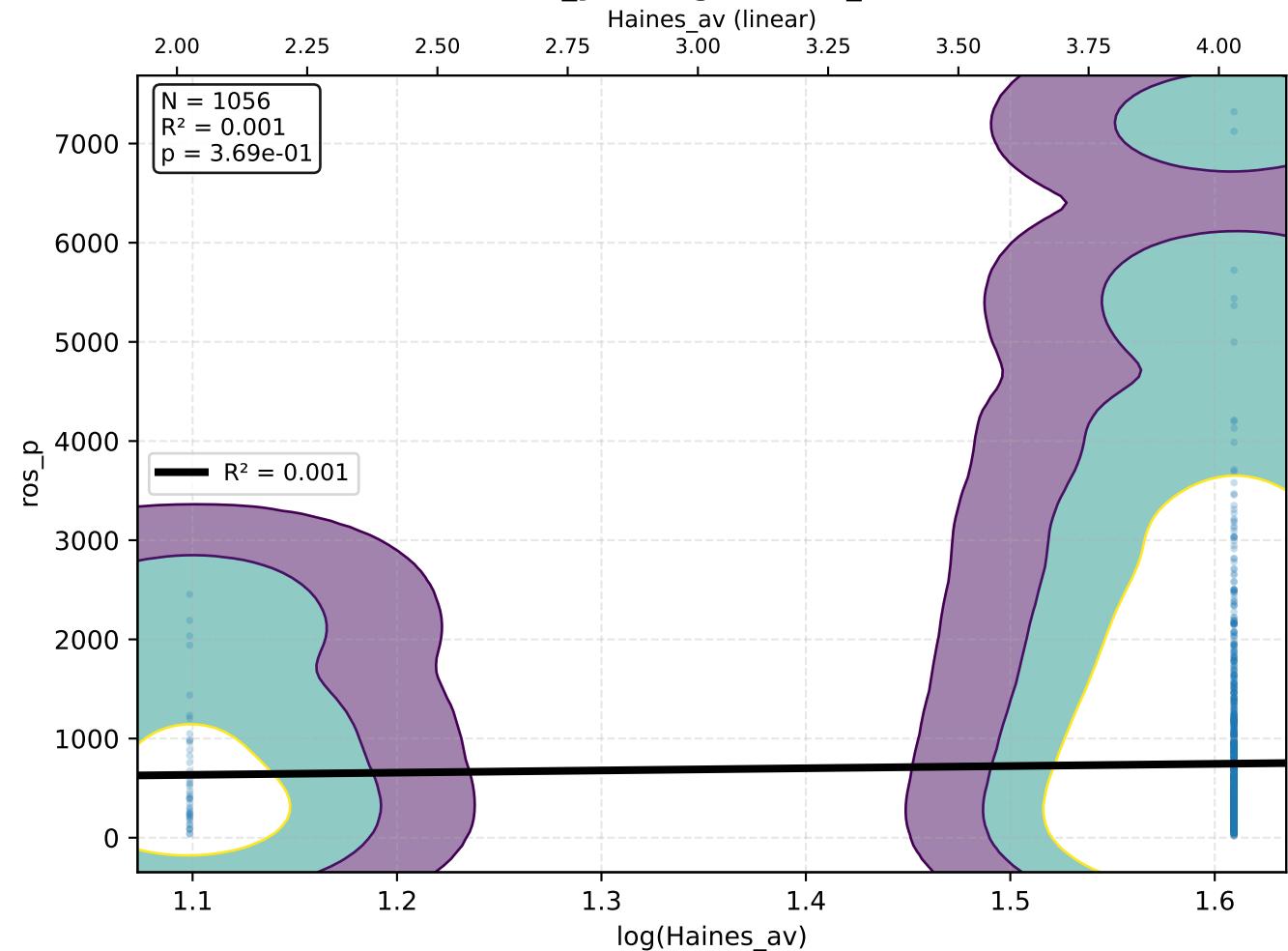


# Haines\_av – KDE Density + Regressão

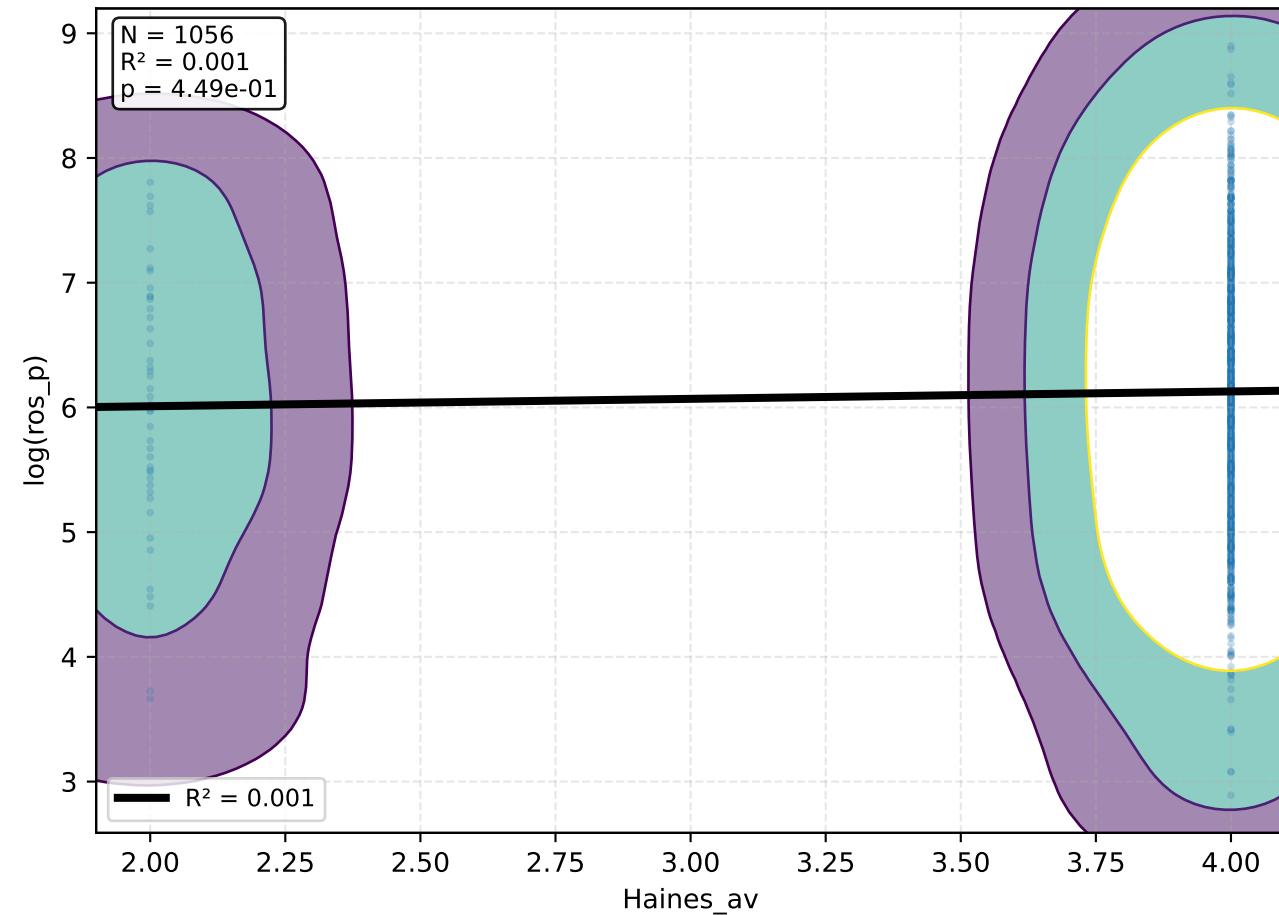
**ros\_p vs Haines\_av**



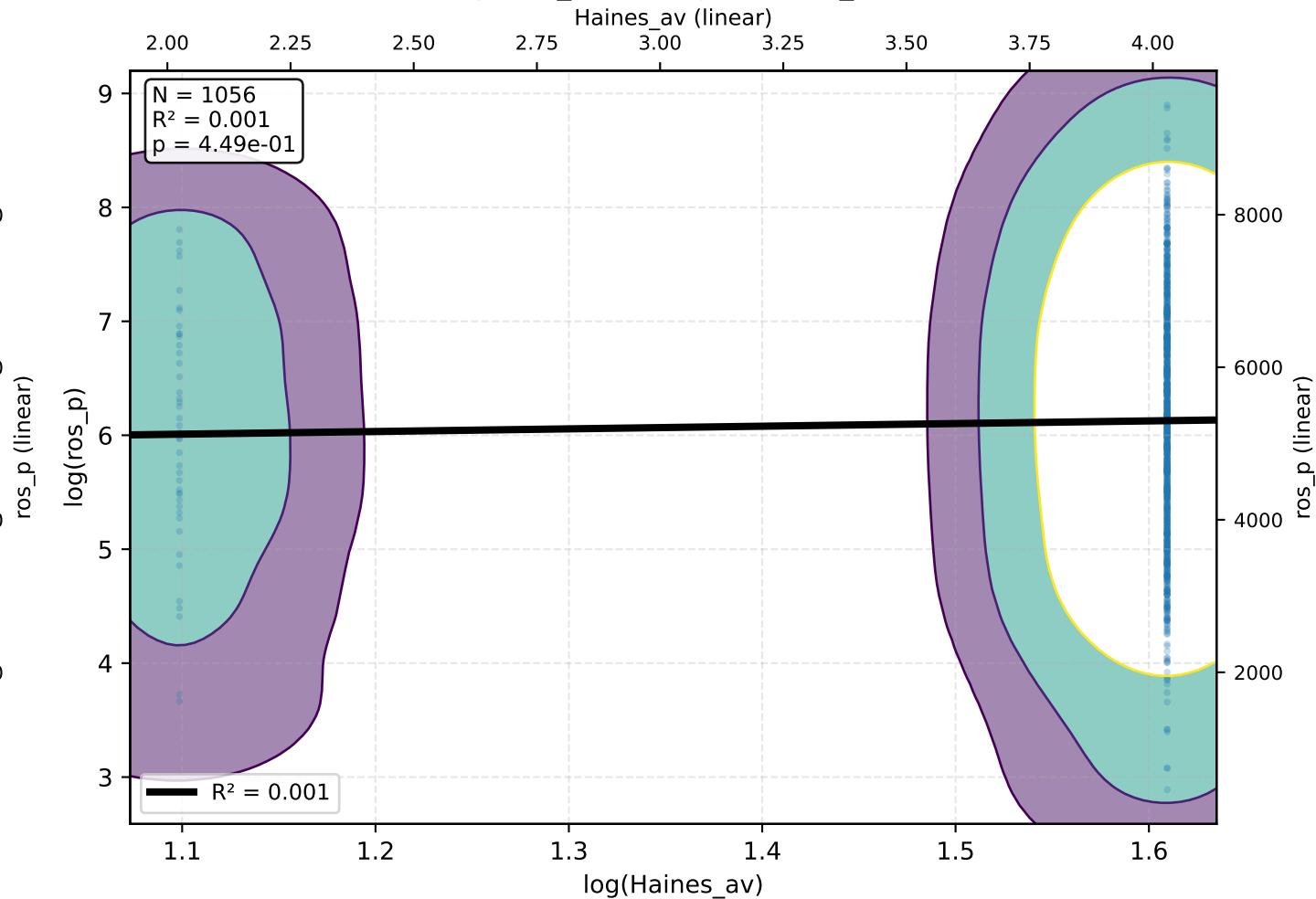
**ros\_p vs log(Haines\_av)**



**log(ros\_p) vs Haines\_av**

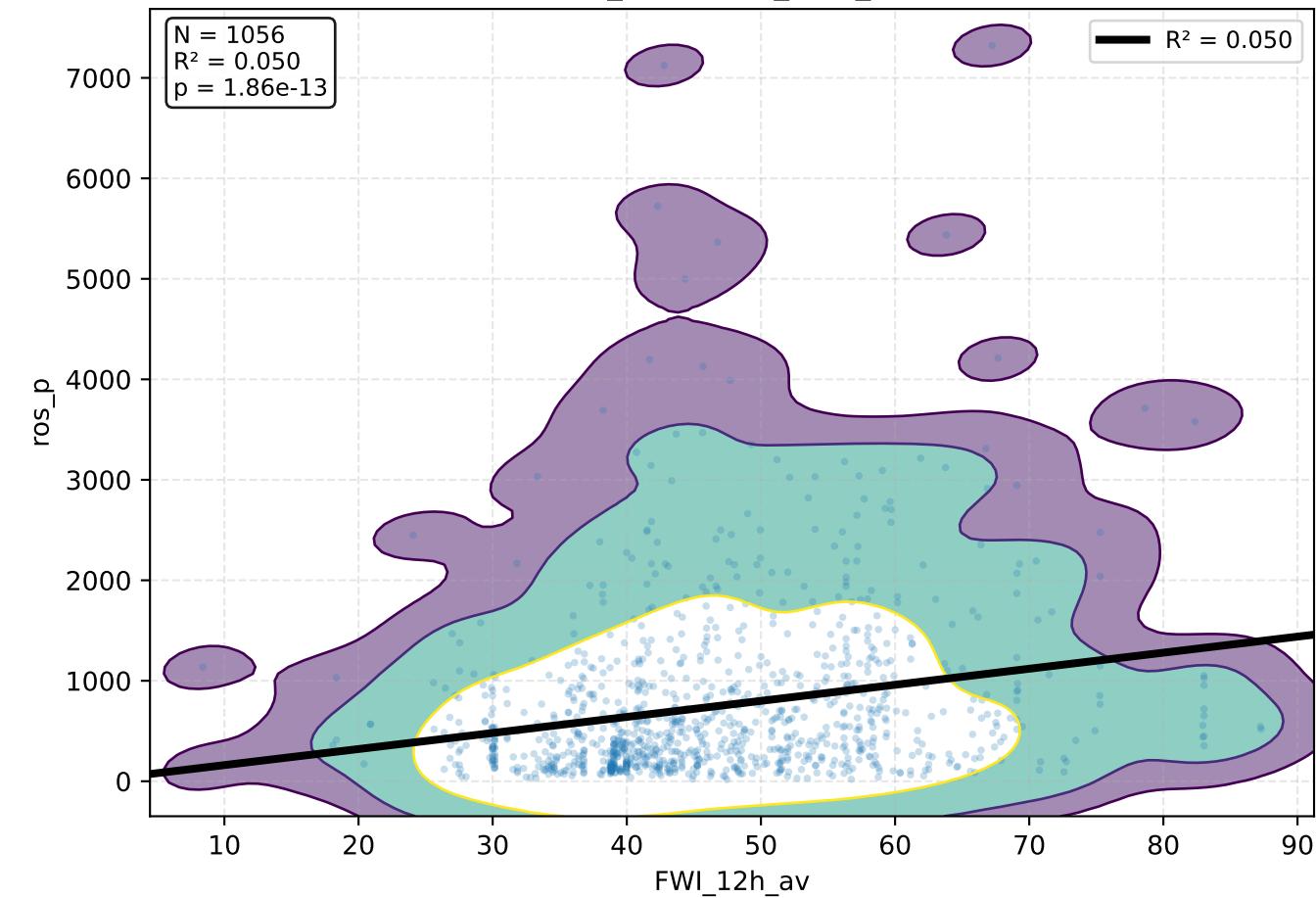


**log(ros\_p) vs log(Haines\_av)**

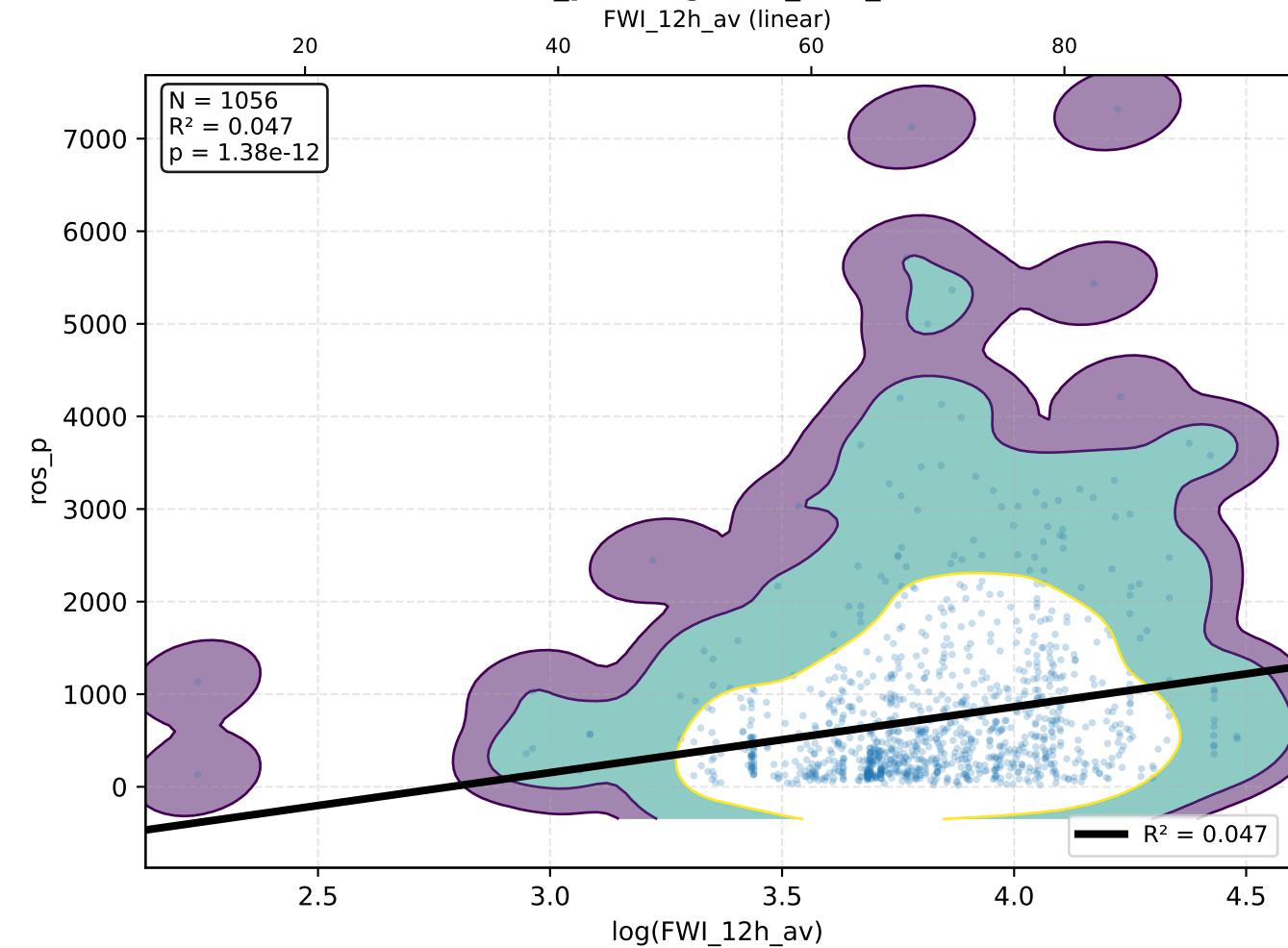


# FWI\_12h\_av – KDE Density + Regressão

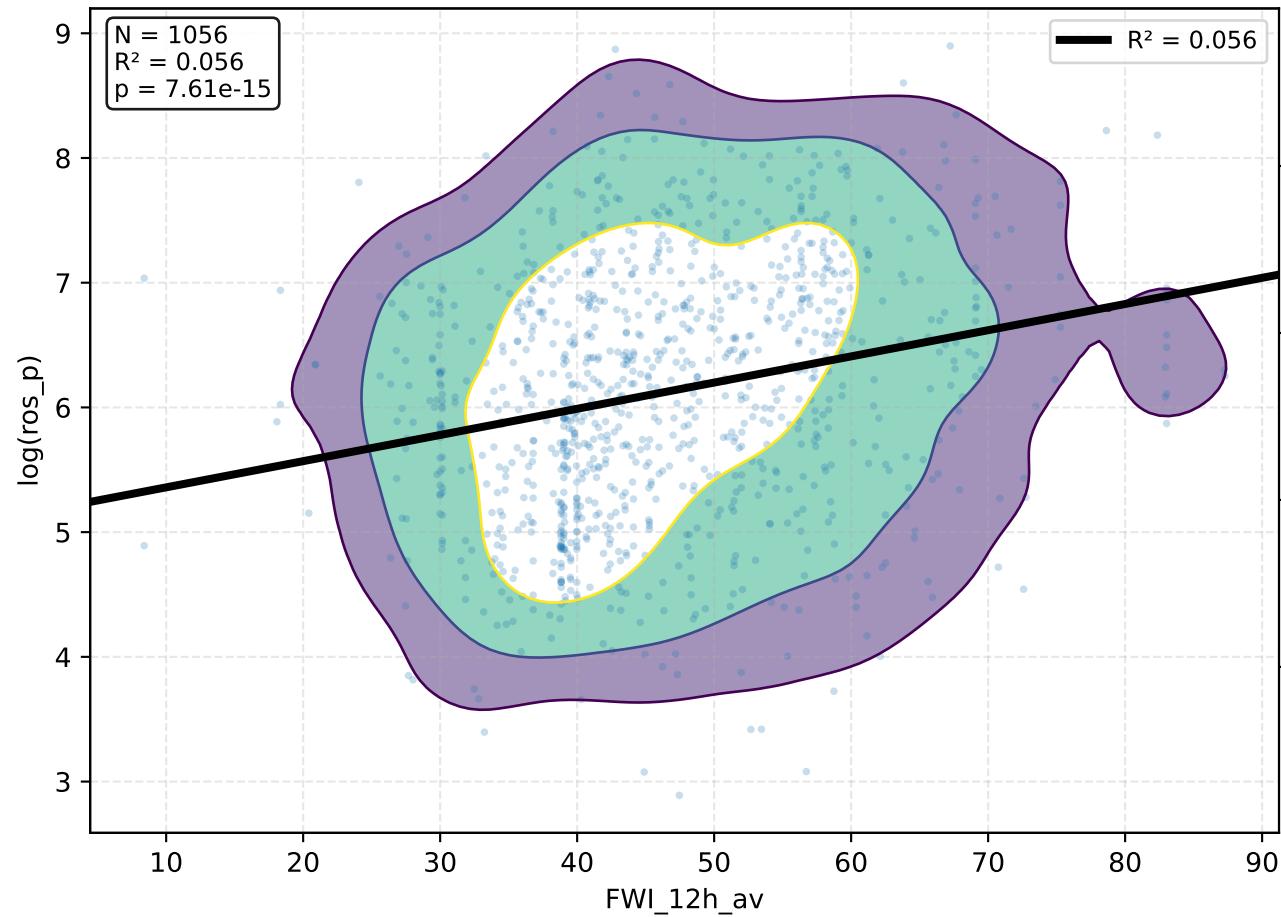
**ros\_p vs FWI\_12h\_av**



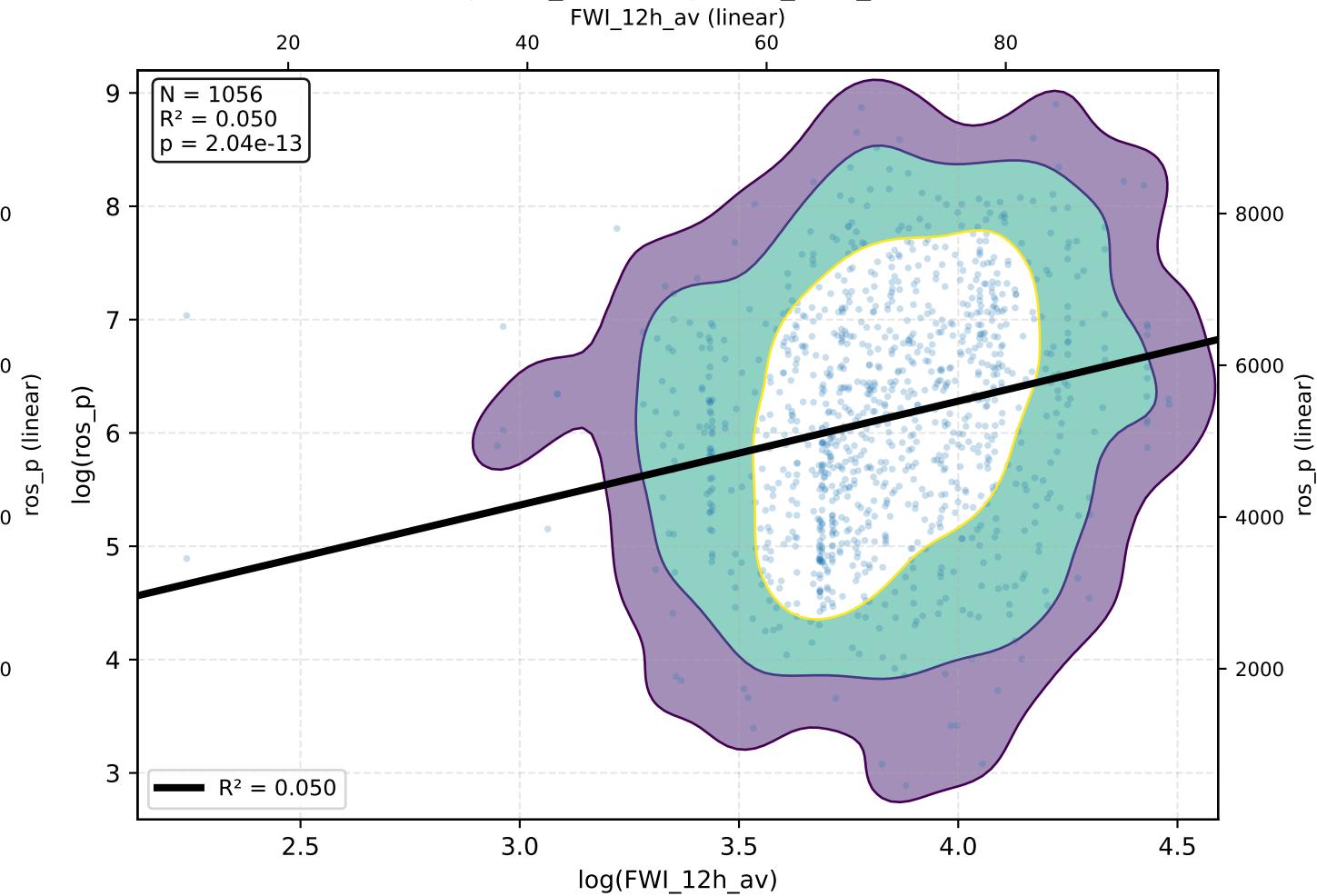
**ros\_p vs log(FWI\_12h\_av)**



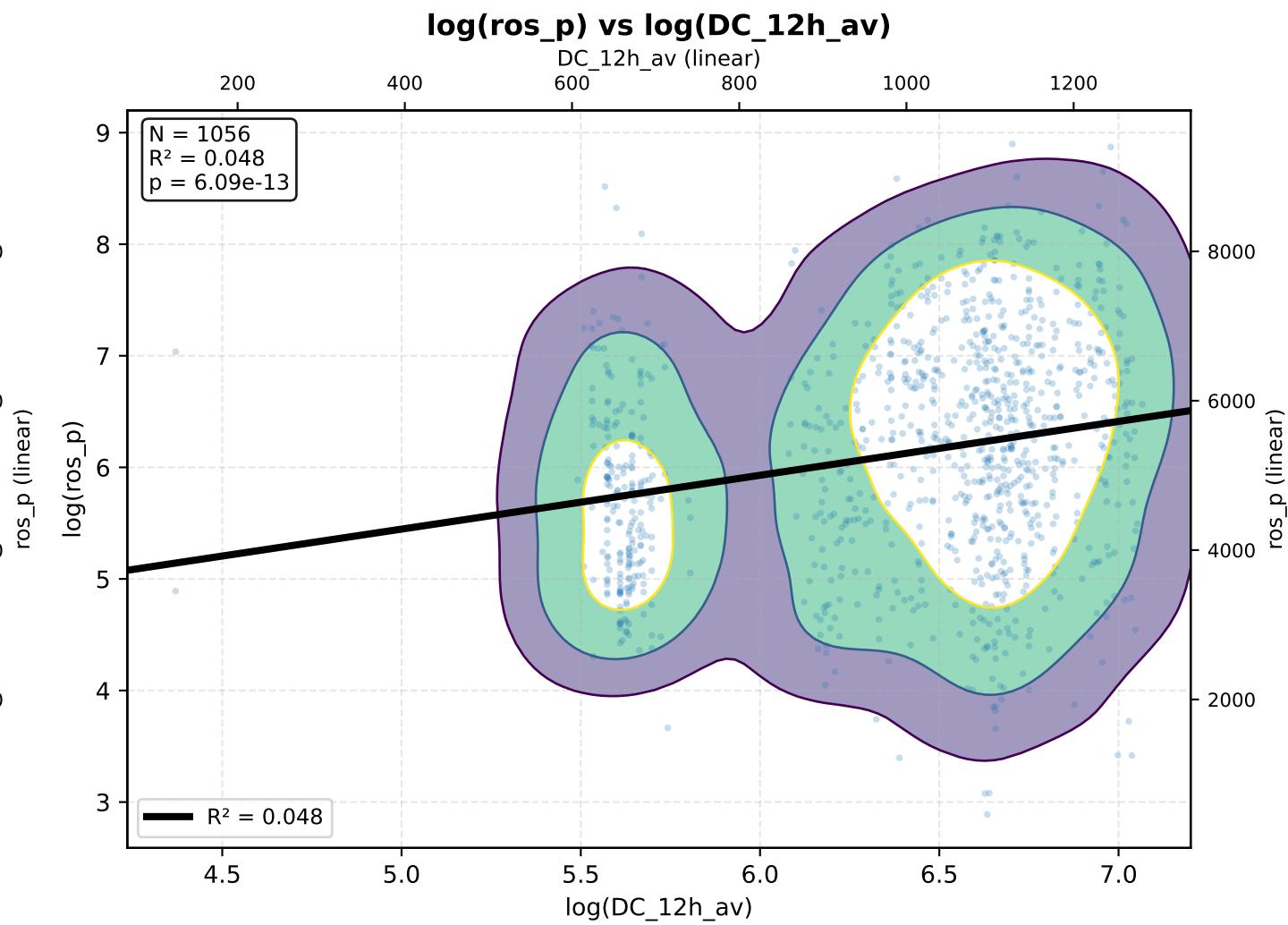
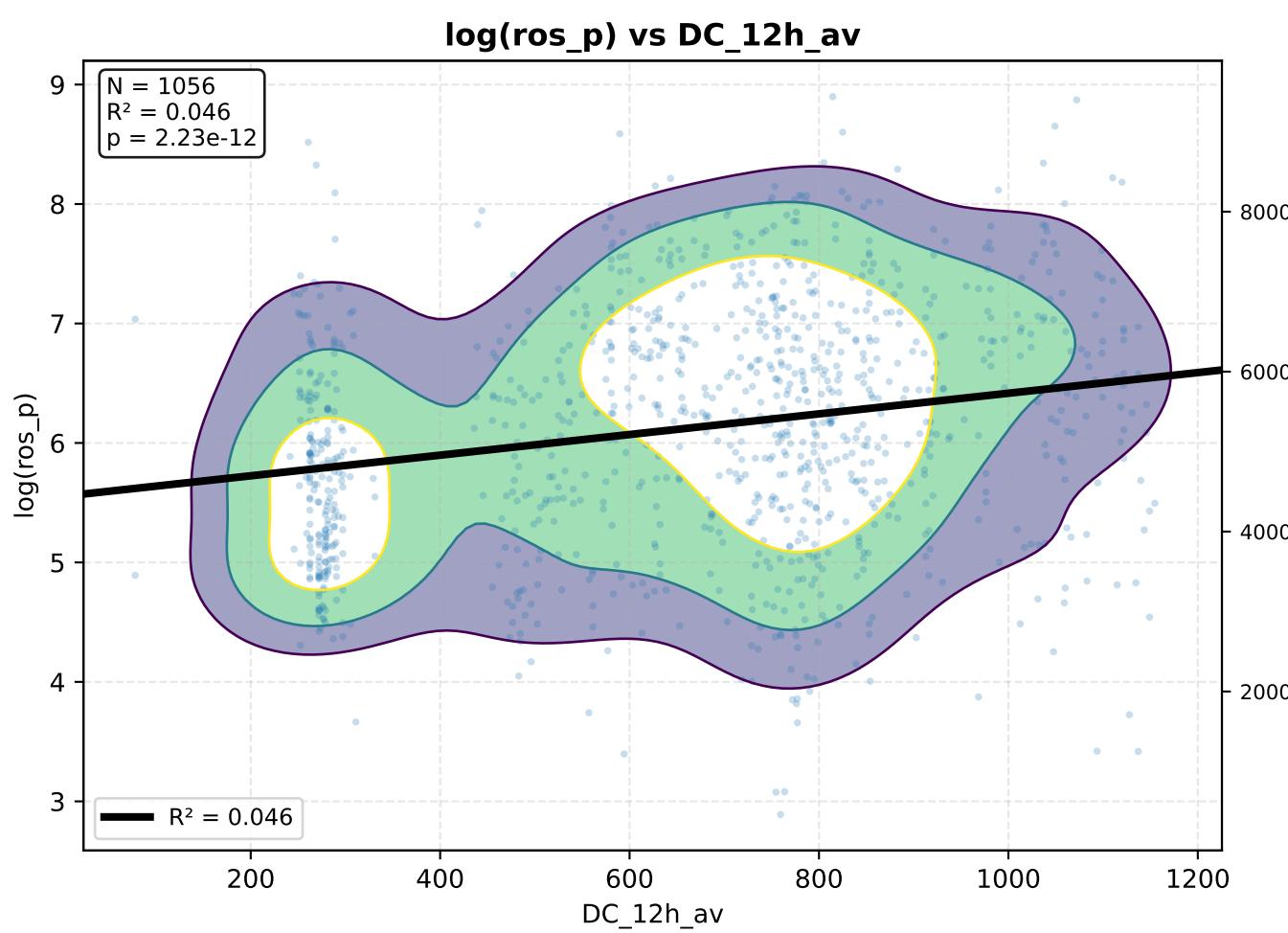
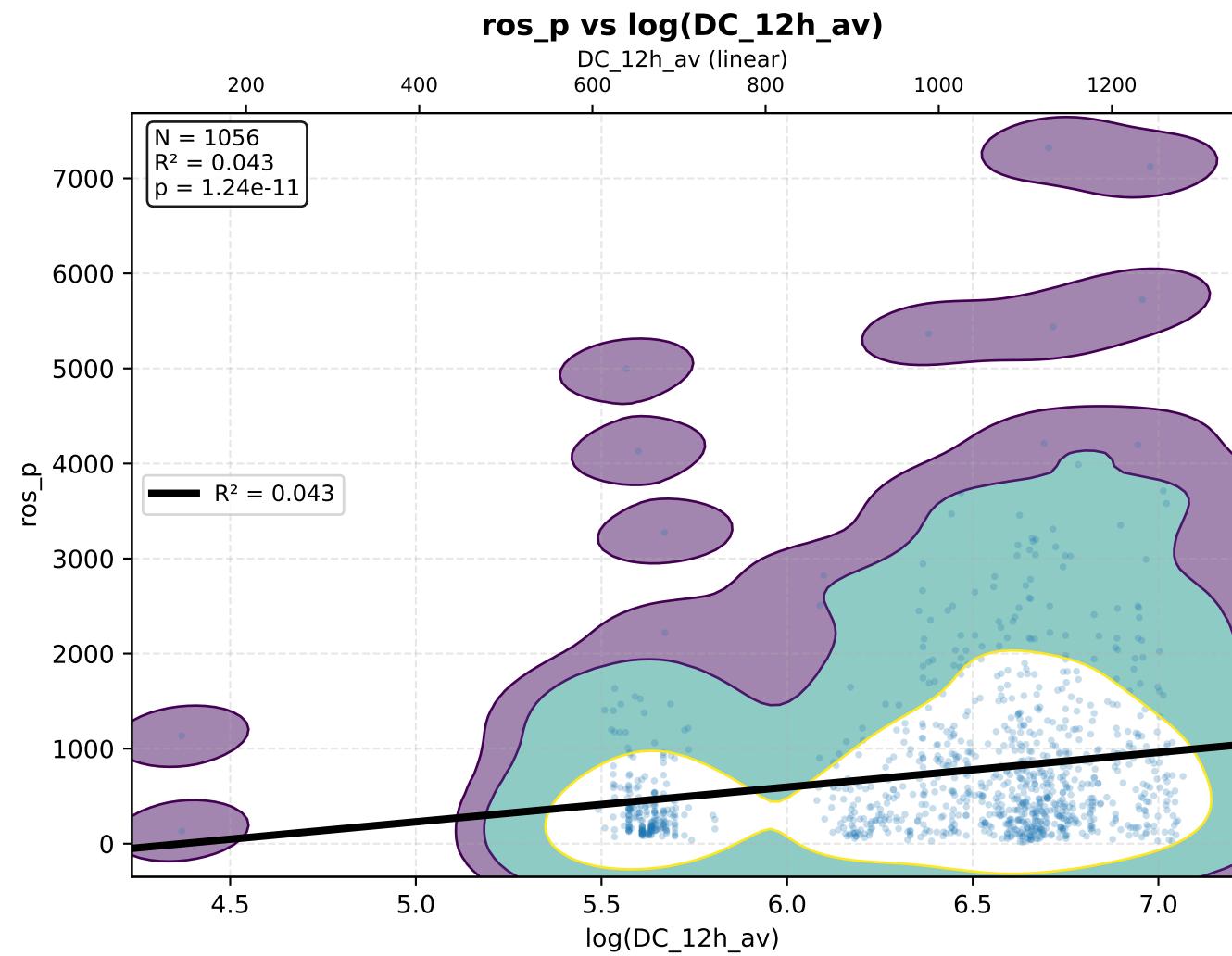
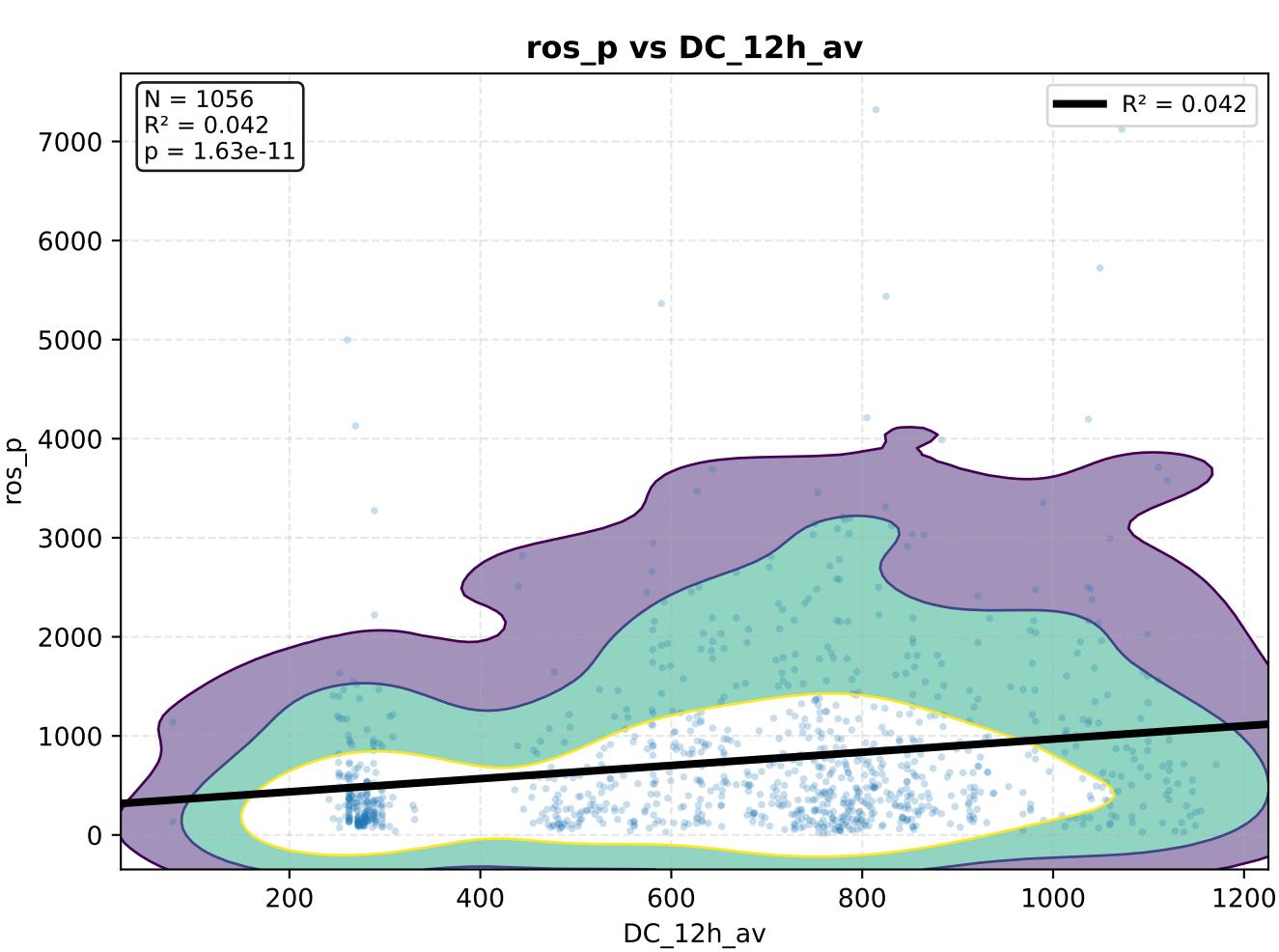
**log(ros\_p) vs FWI\_12h\_av**



**log(ros\_p) vs log(FWI\_12h\_av)**

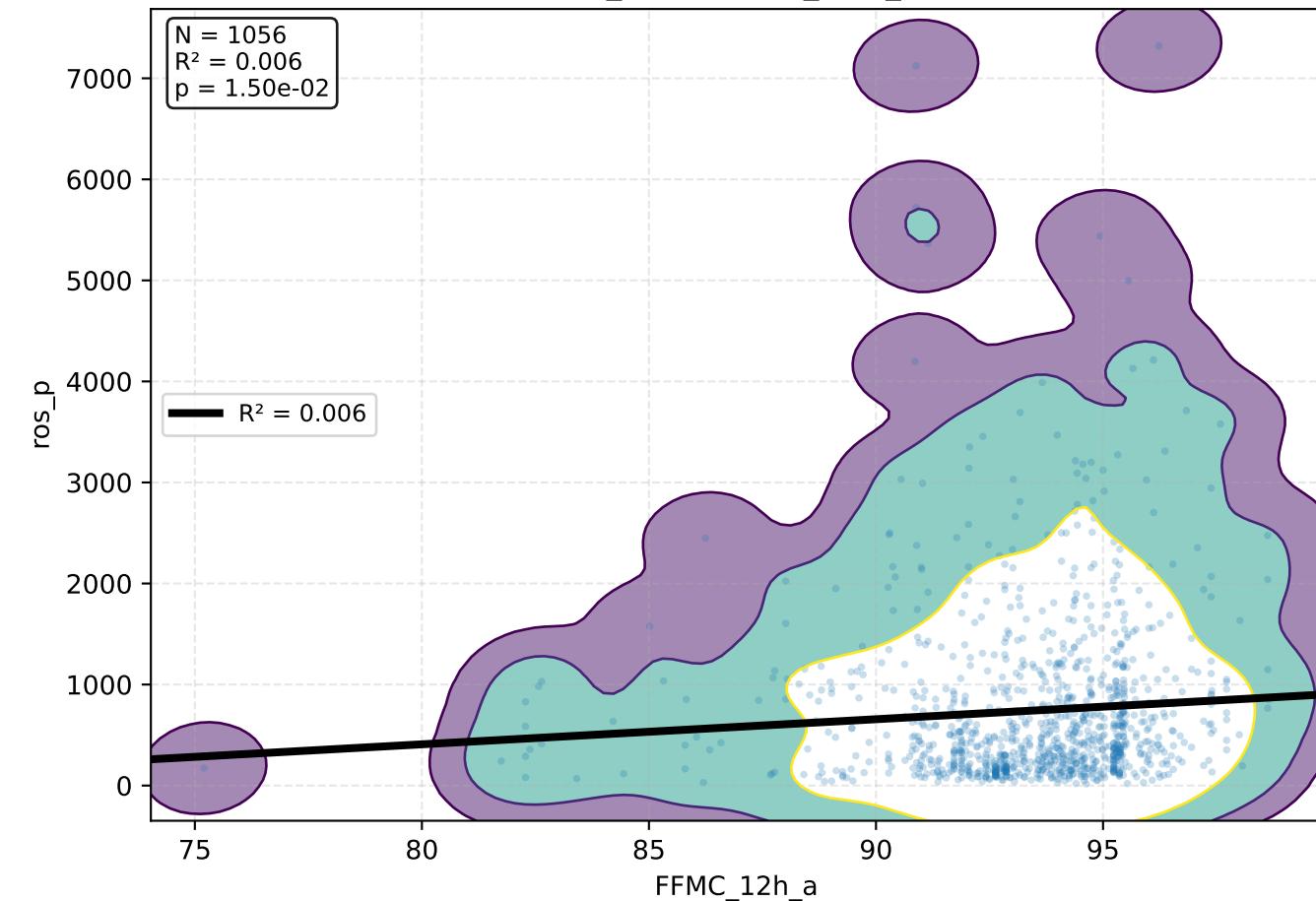


# DC\_12h\_av - KDE Density + Regressão

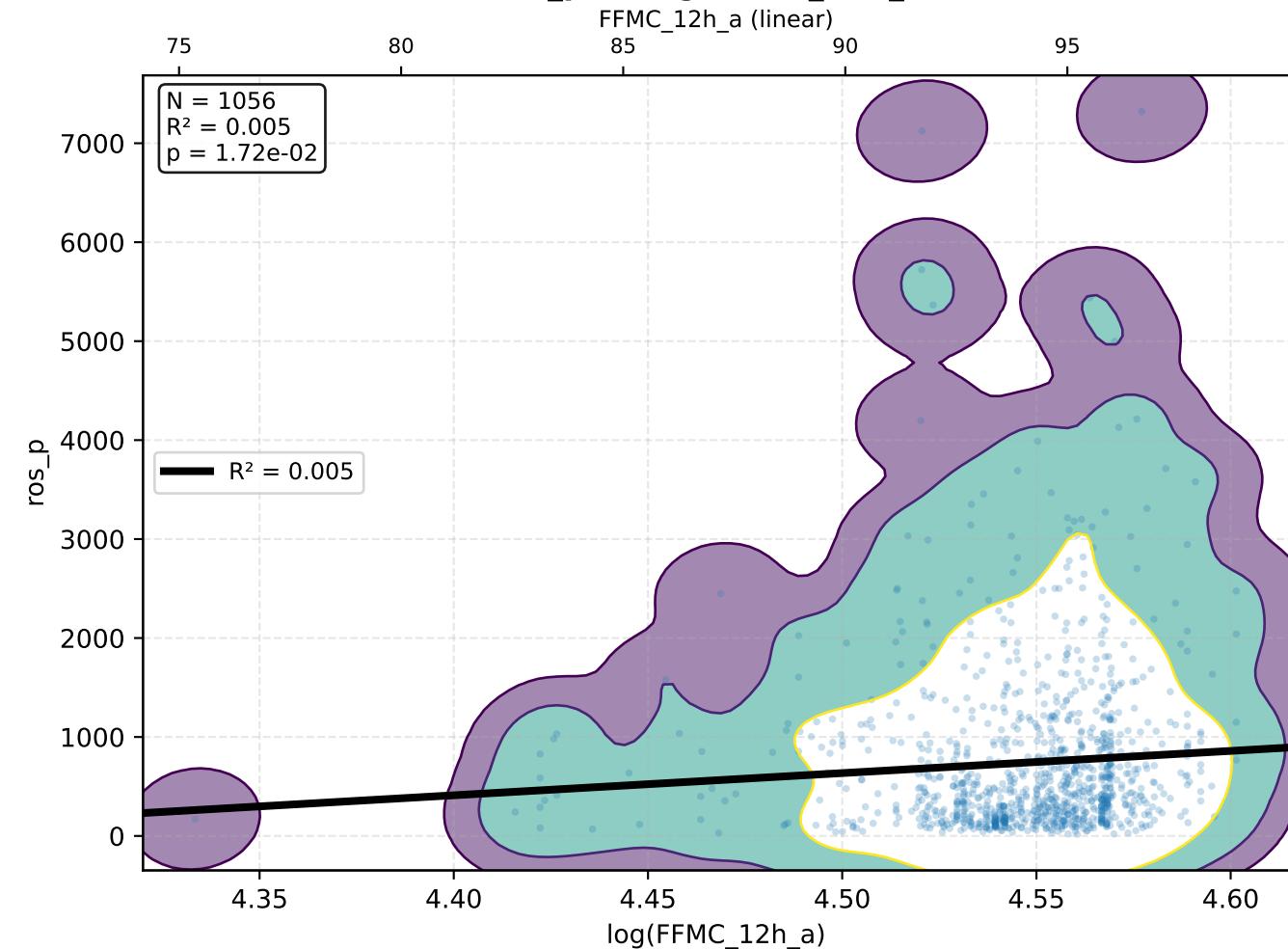


# FFMC\_12h\_a - KDE Density + Regressão

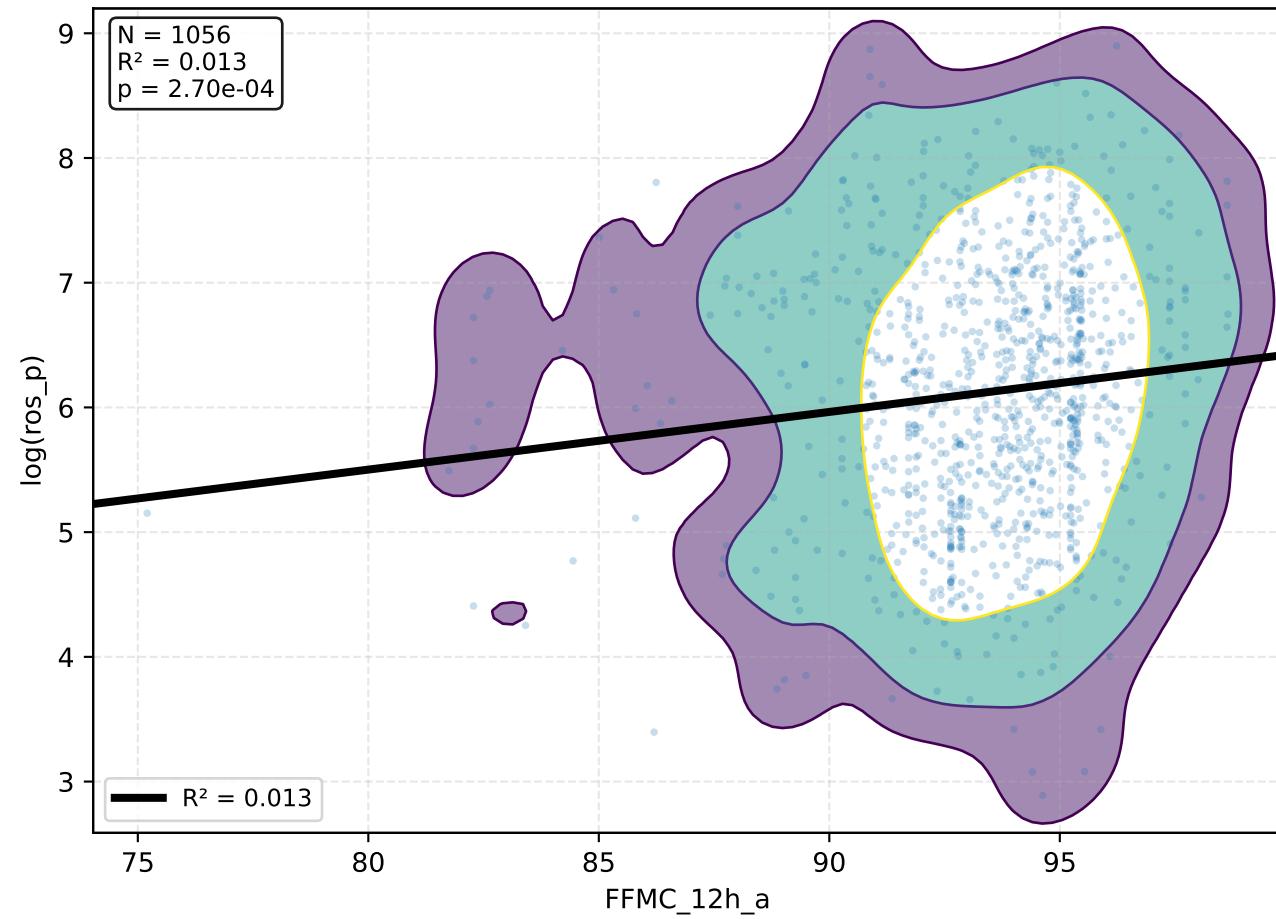
**ros\_p vs FFMC\_12h\_a**



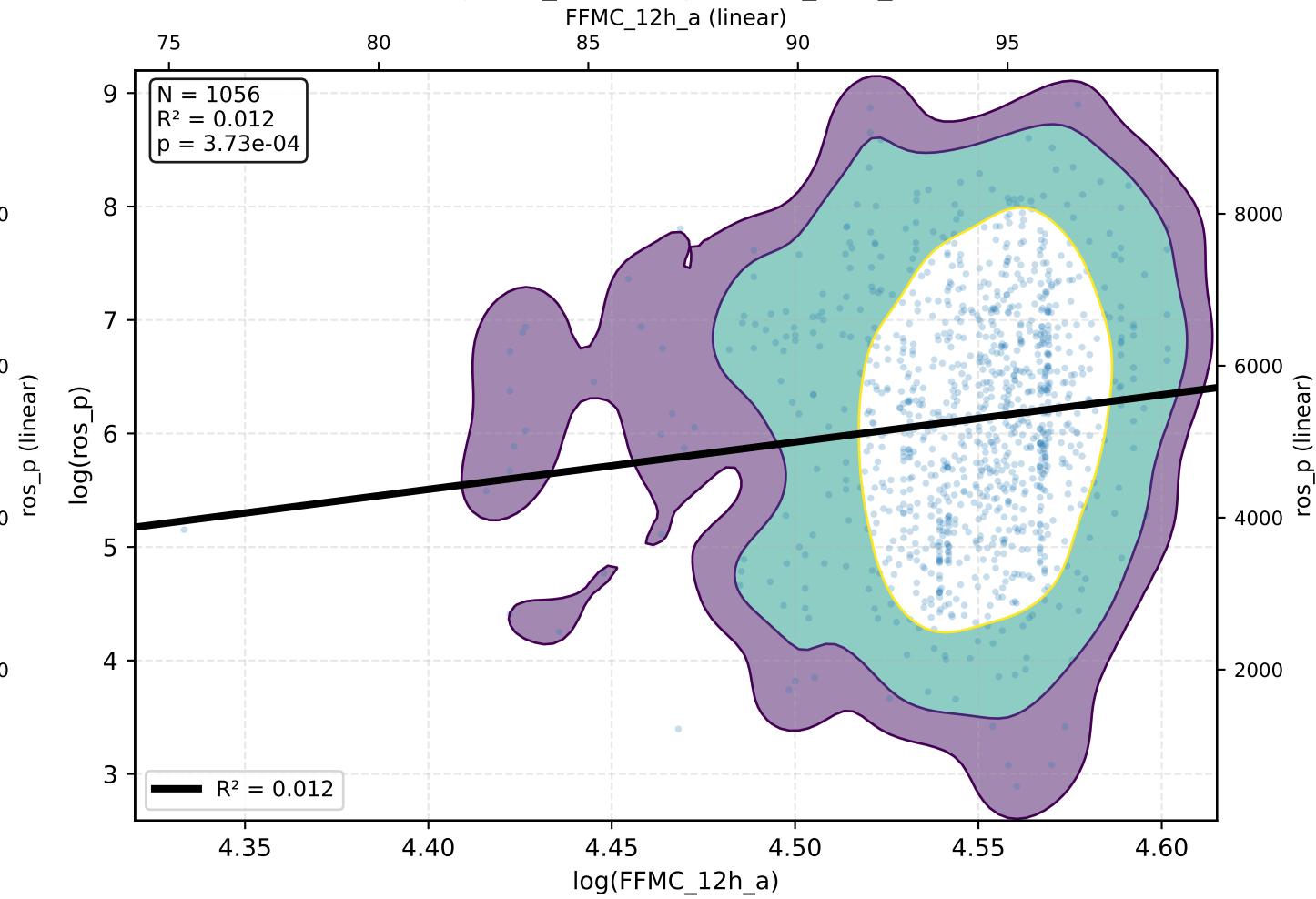
**ros\_p vs log(FFMC\_12h\_a)**



**log(ros\_p) vs FFMC\_12h\_a**

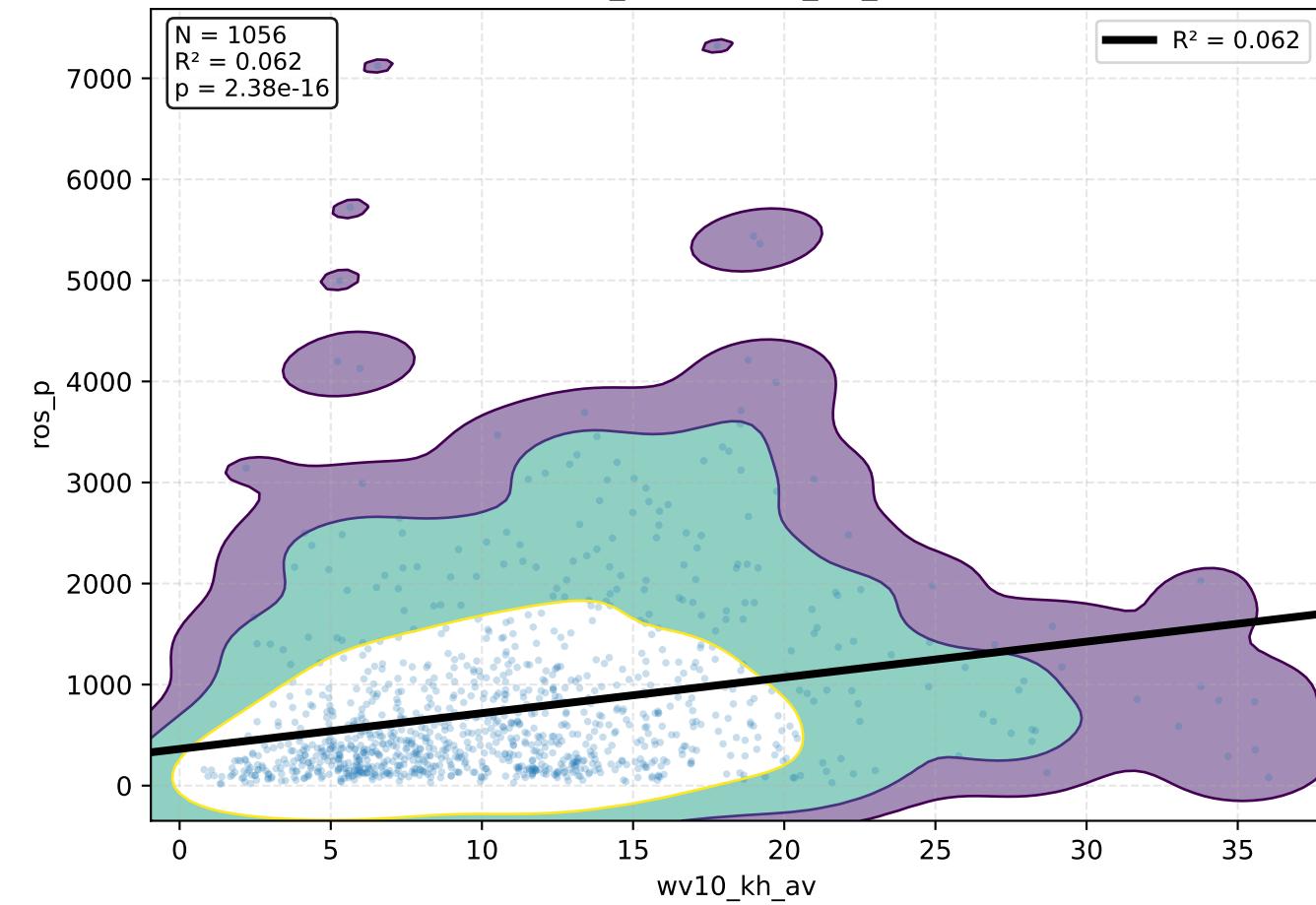


**log(ros\_p) vs log(FFMC\_12h\_a)**

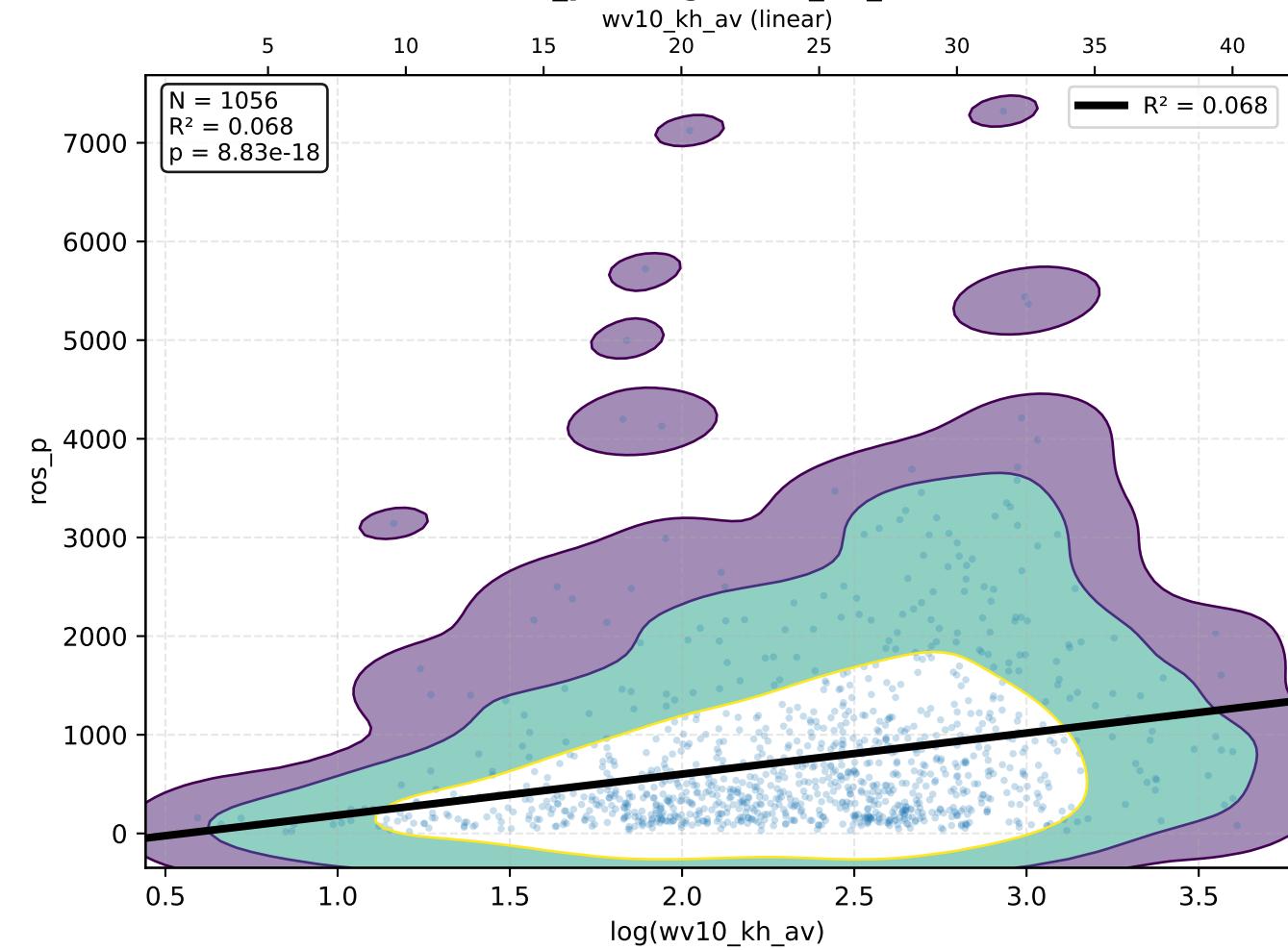


# wv10\_kh\_av – KDE Density + Regressão

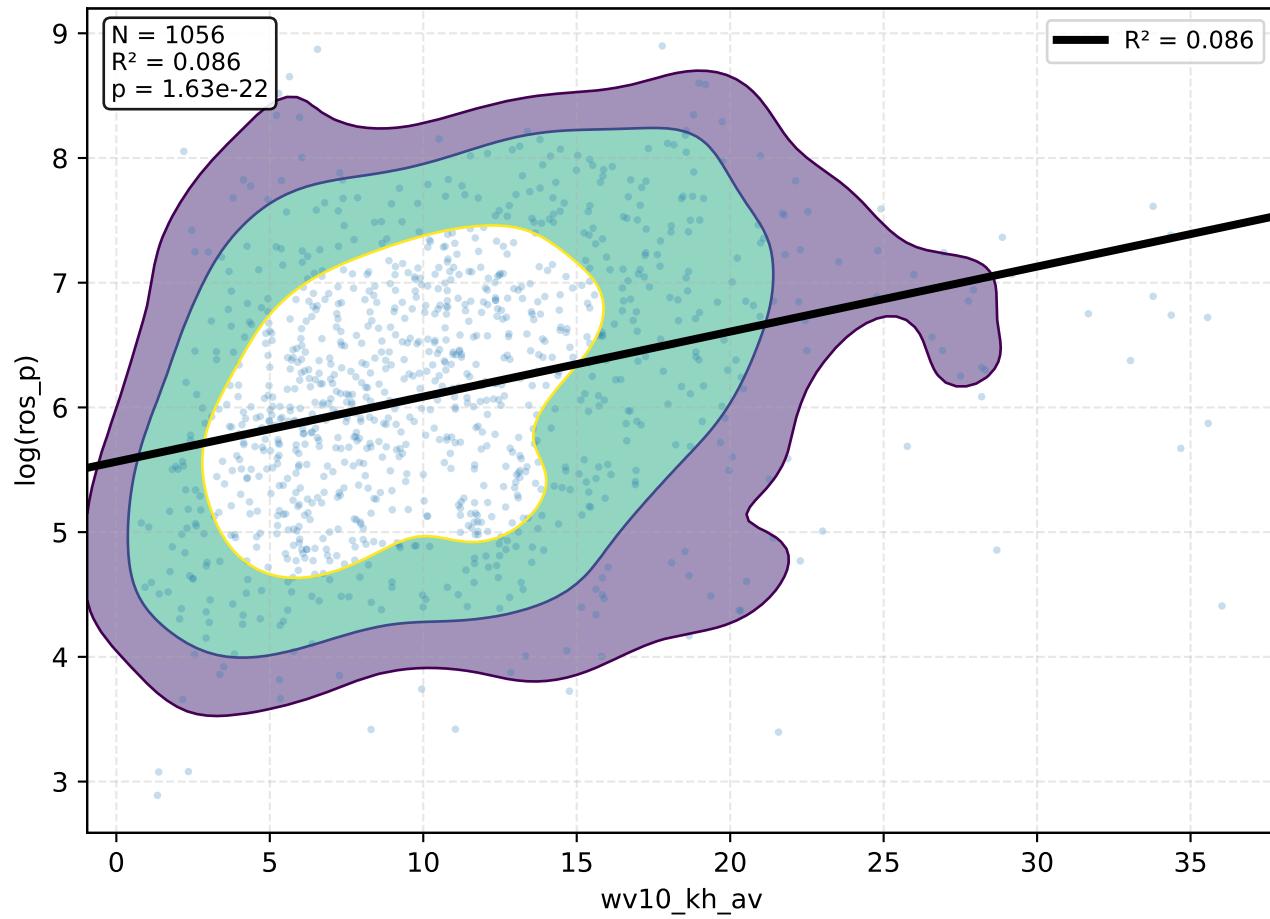
**ros\_p vs wv10\_kh\_av**



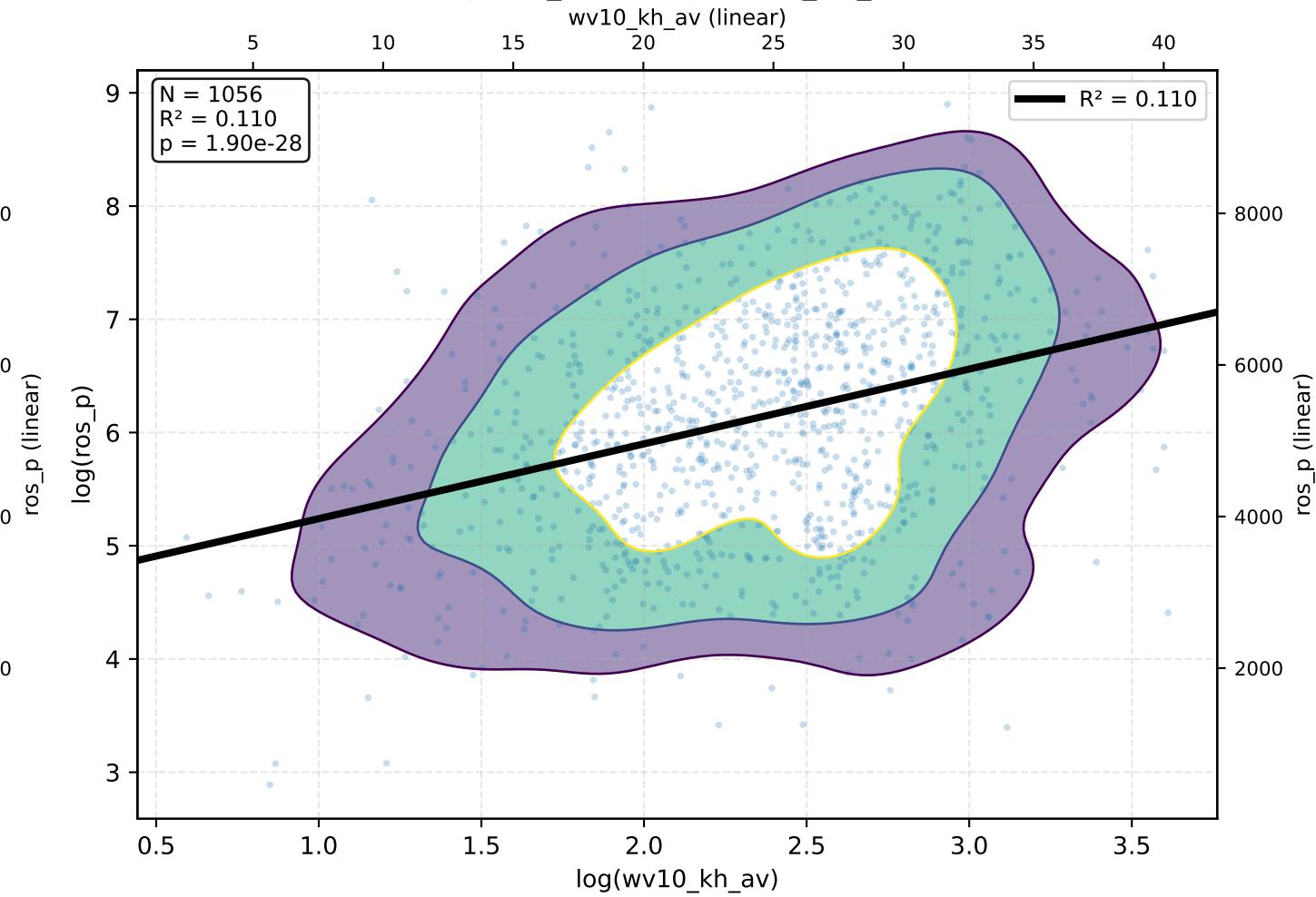
**ros\_p vs log(wv10\_kh\_av)**



**log(ros\_p) vs wv10\_kh\_av**

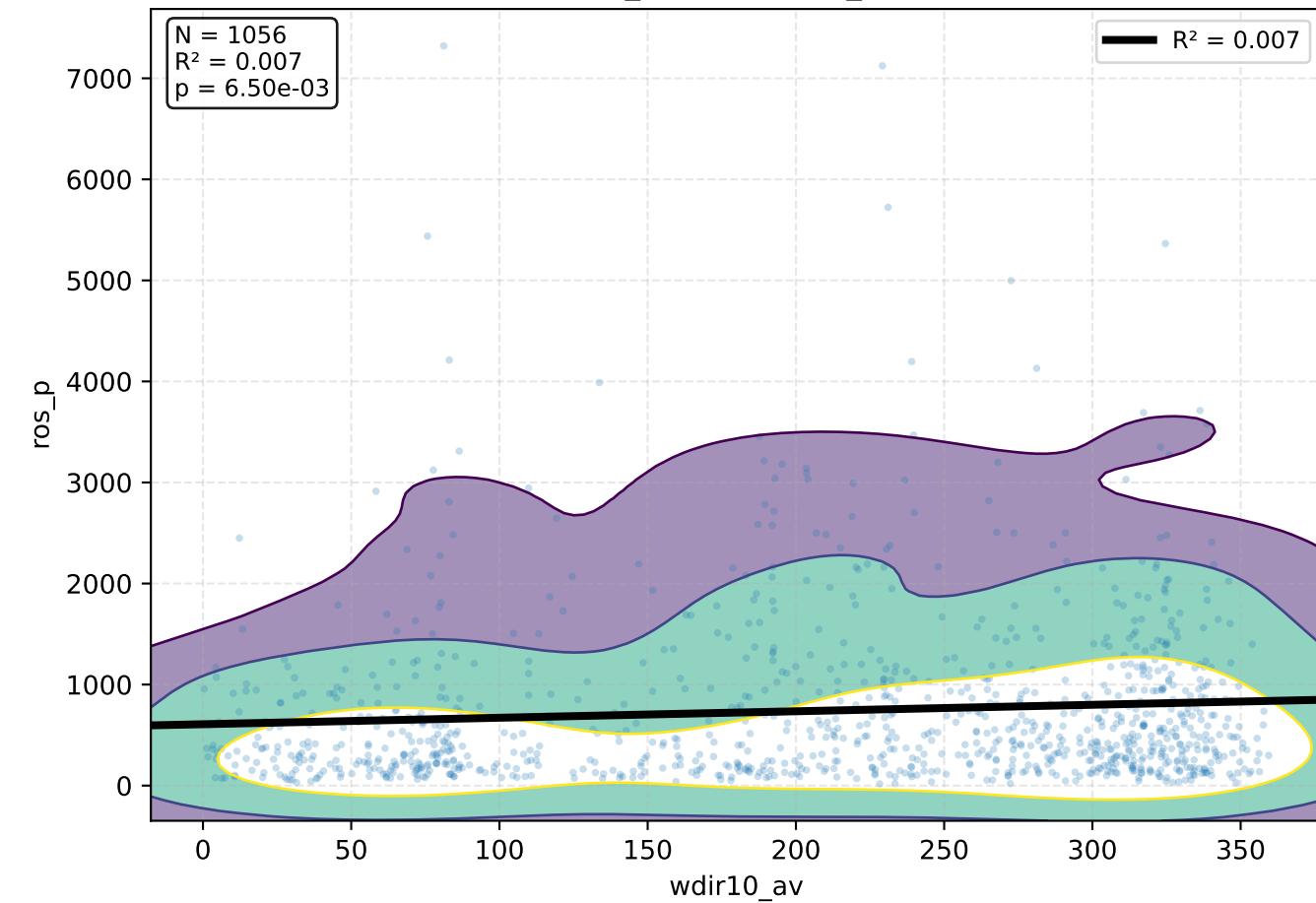


**log(ros\_p) vs log(wv10\_kh\_av)**

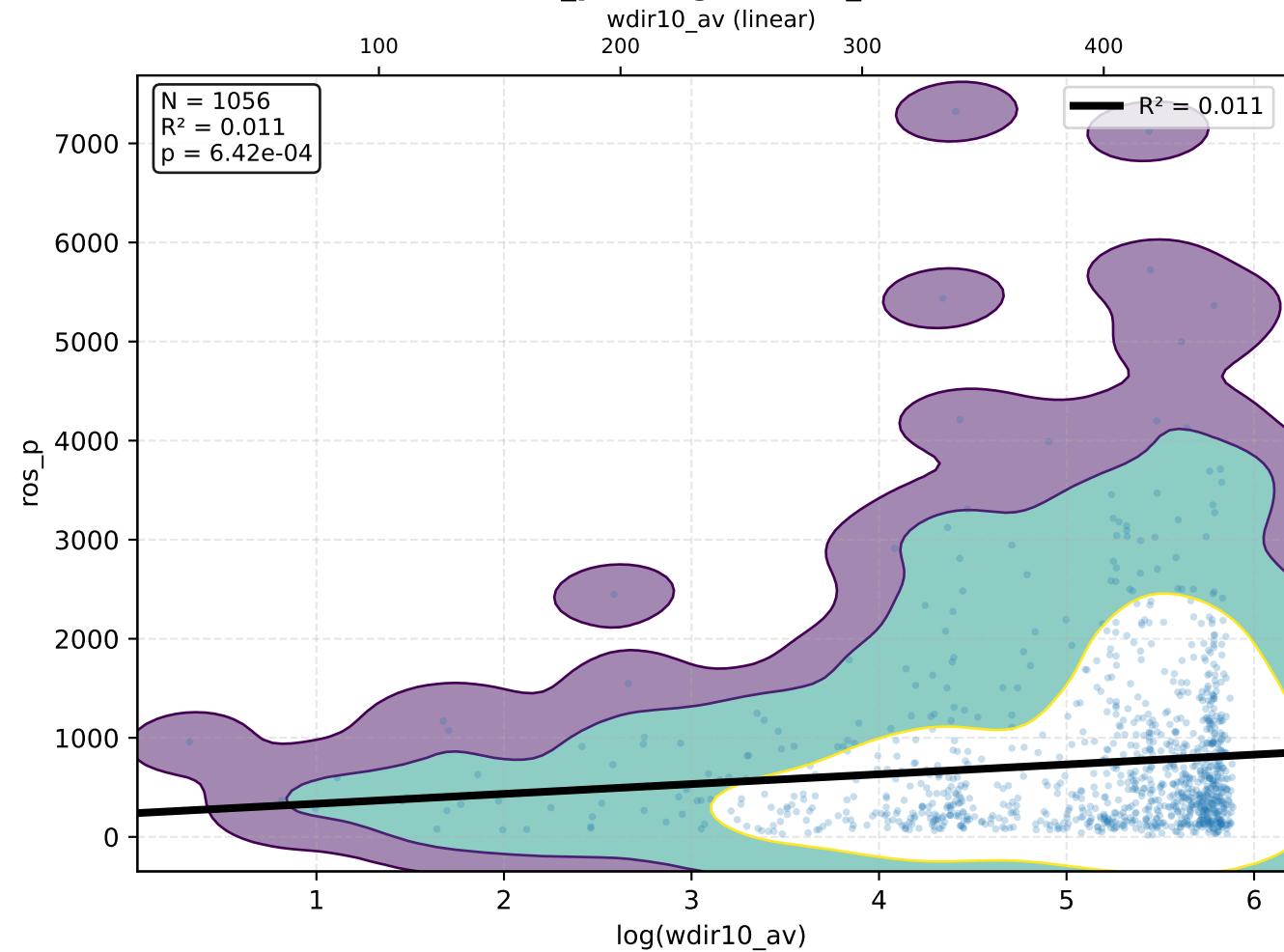


# wdir10\_av – KDE Density + Regressão

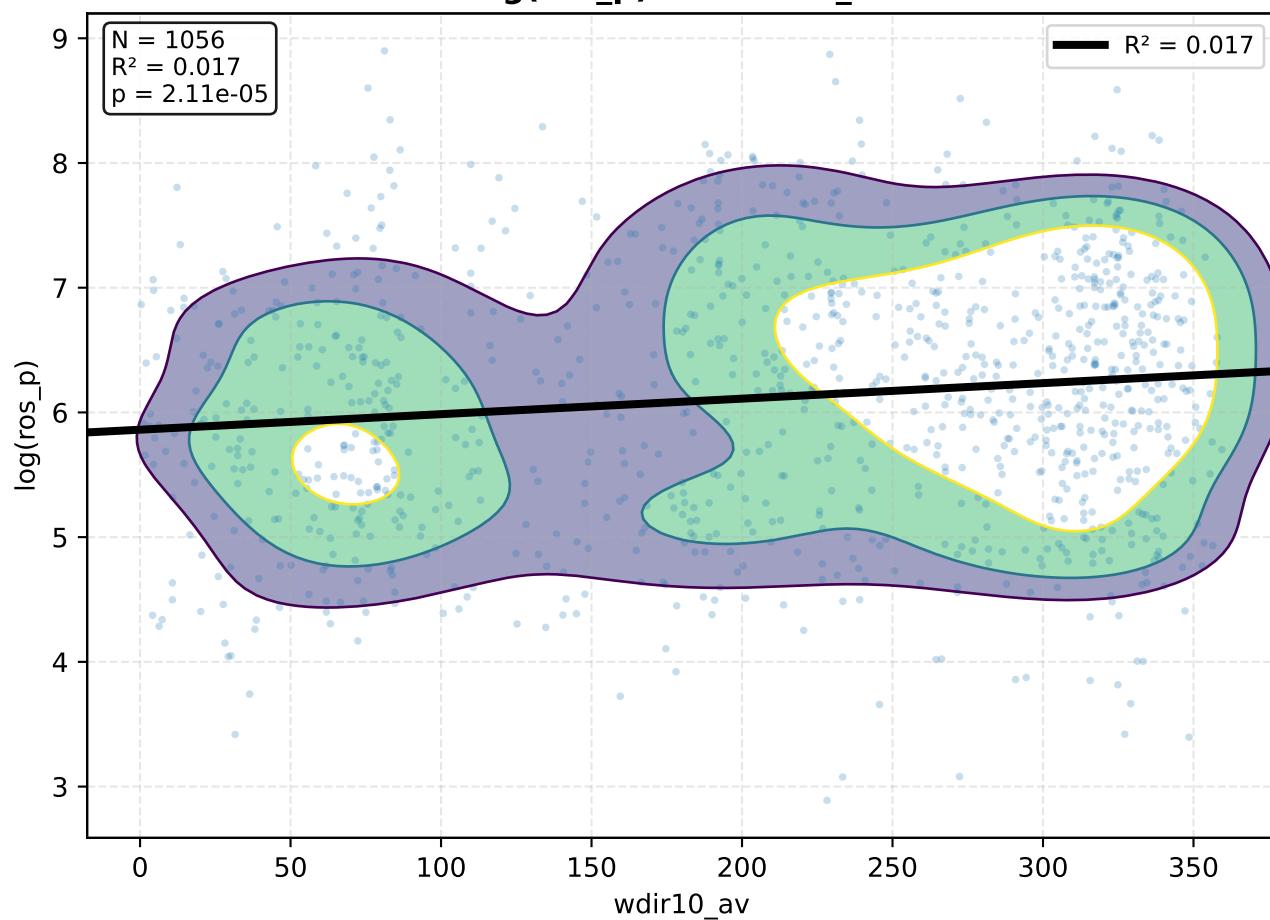
**ros\_p vs wdir10\_av**



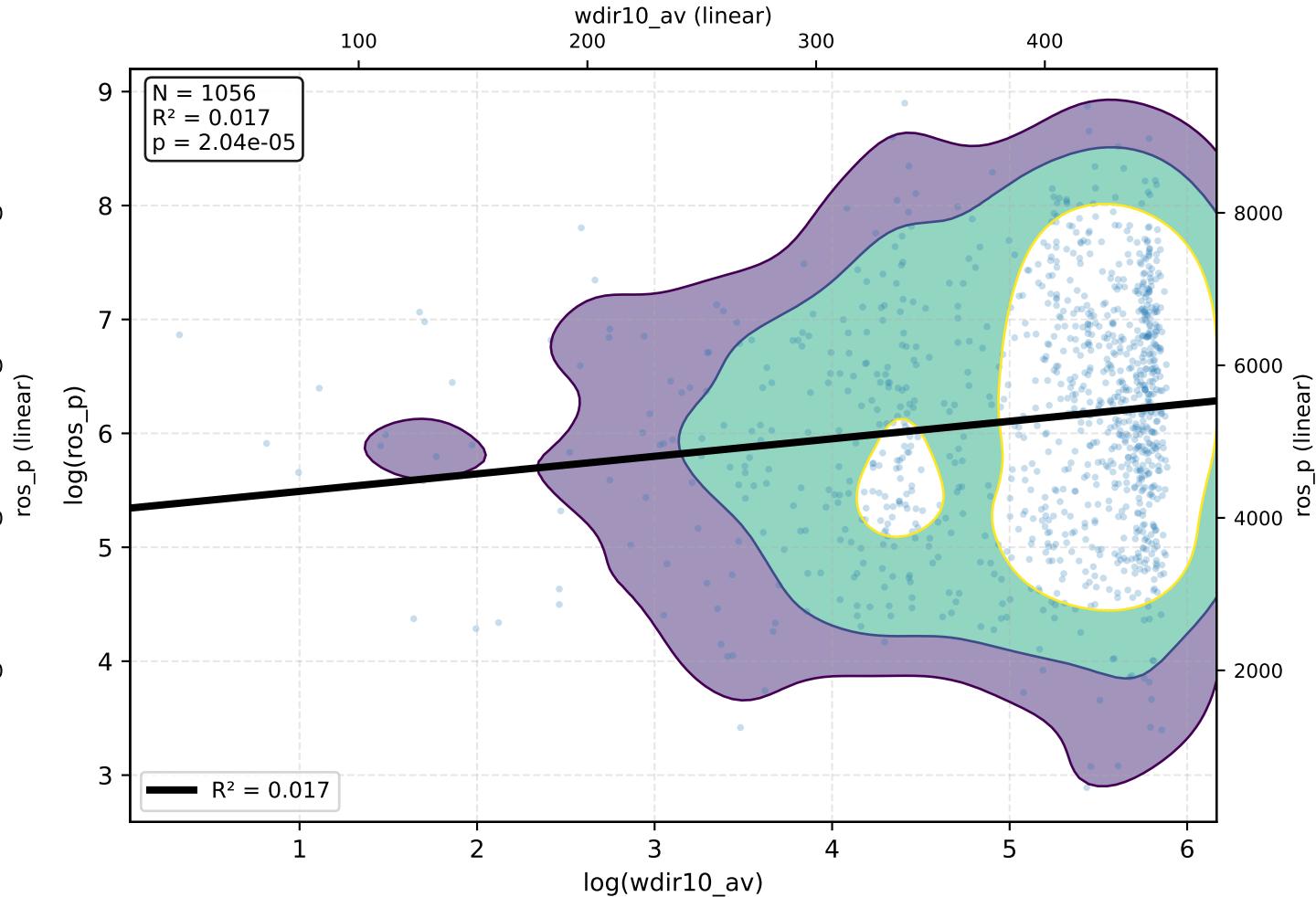
**ros\_p vs log(wdir10\_av)**



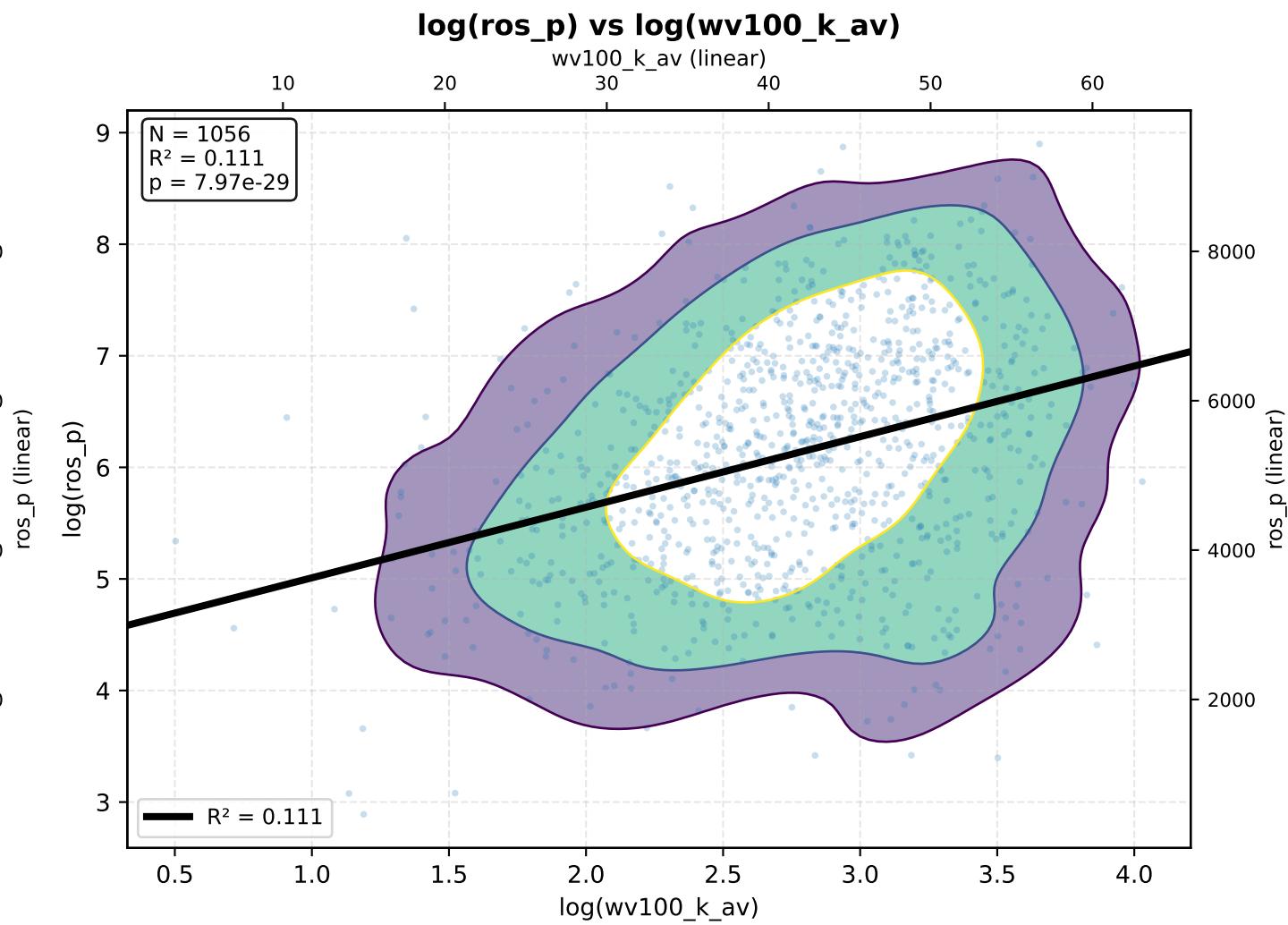
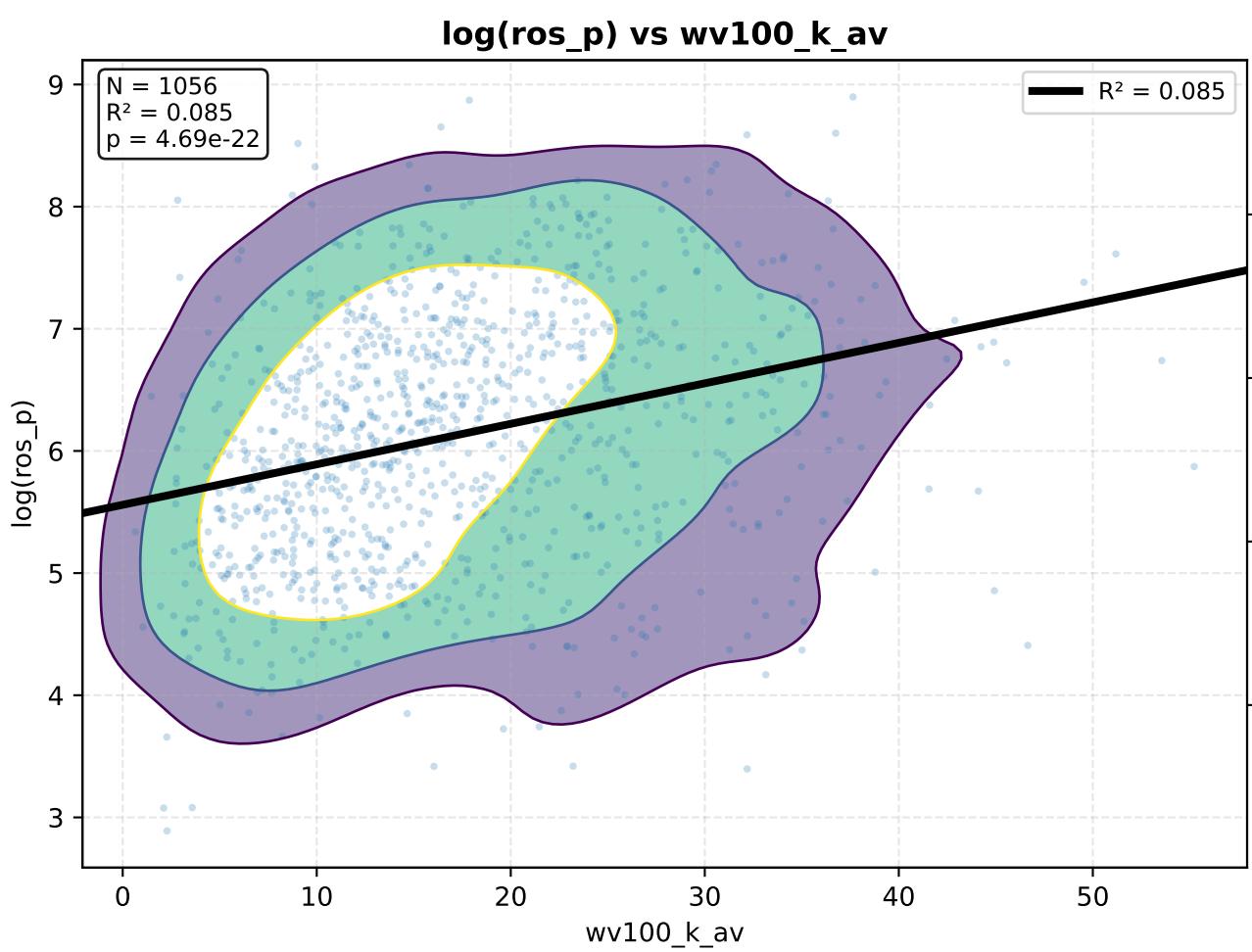
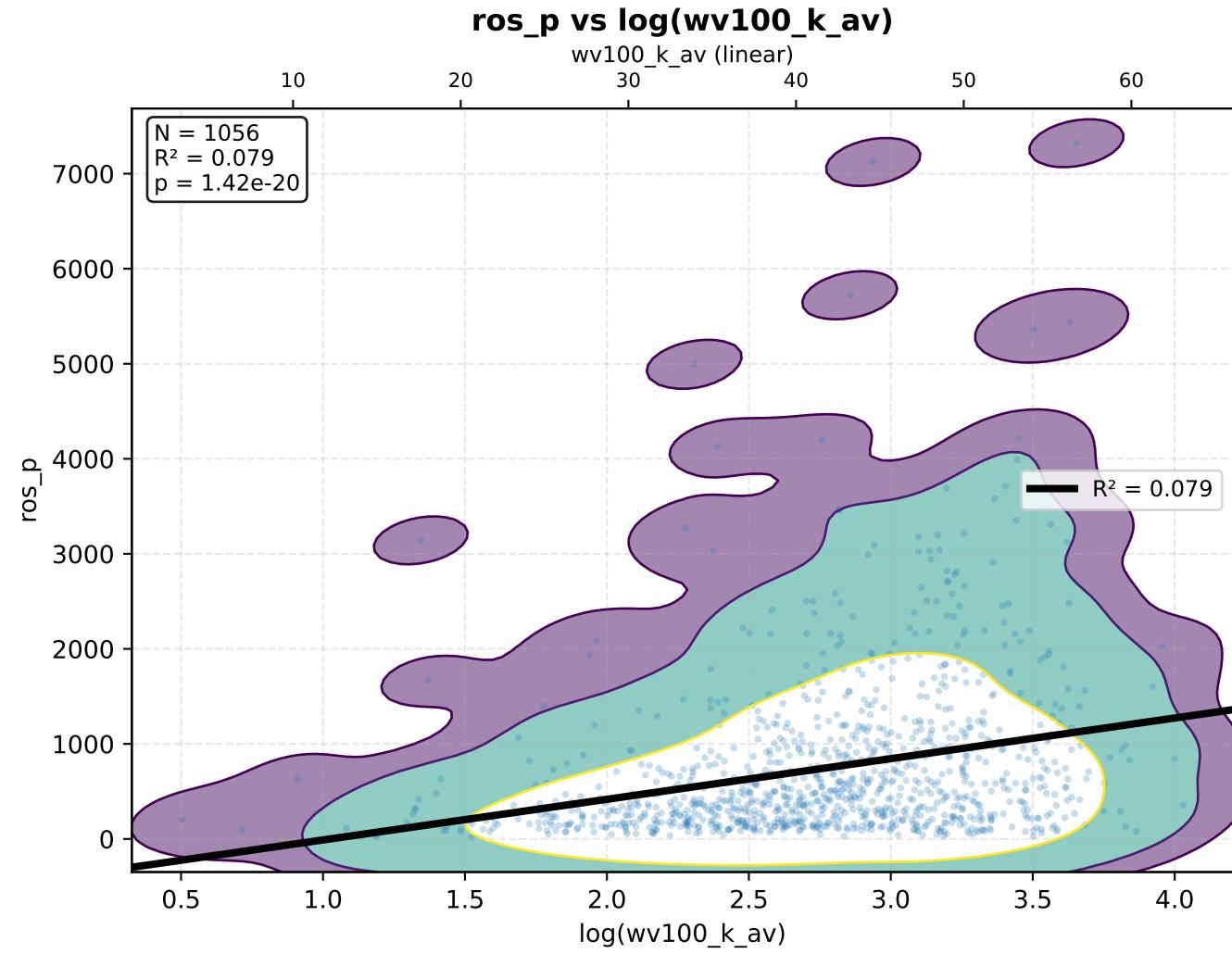
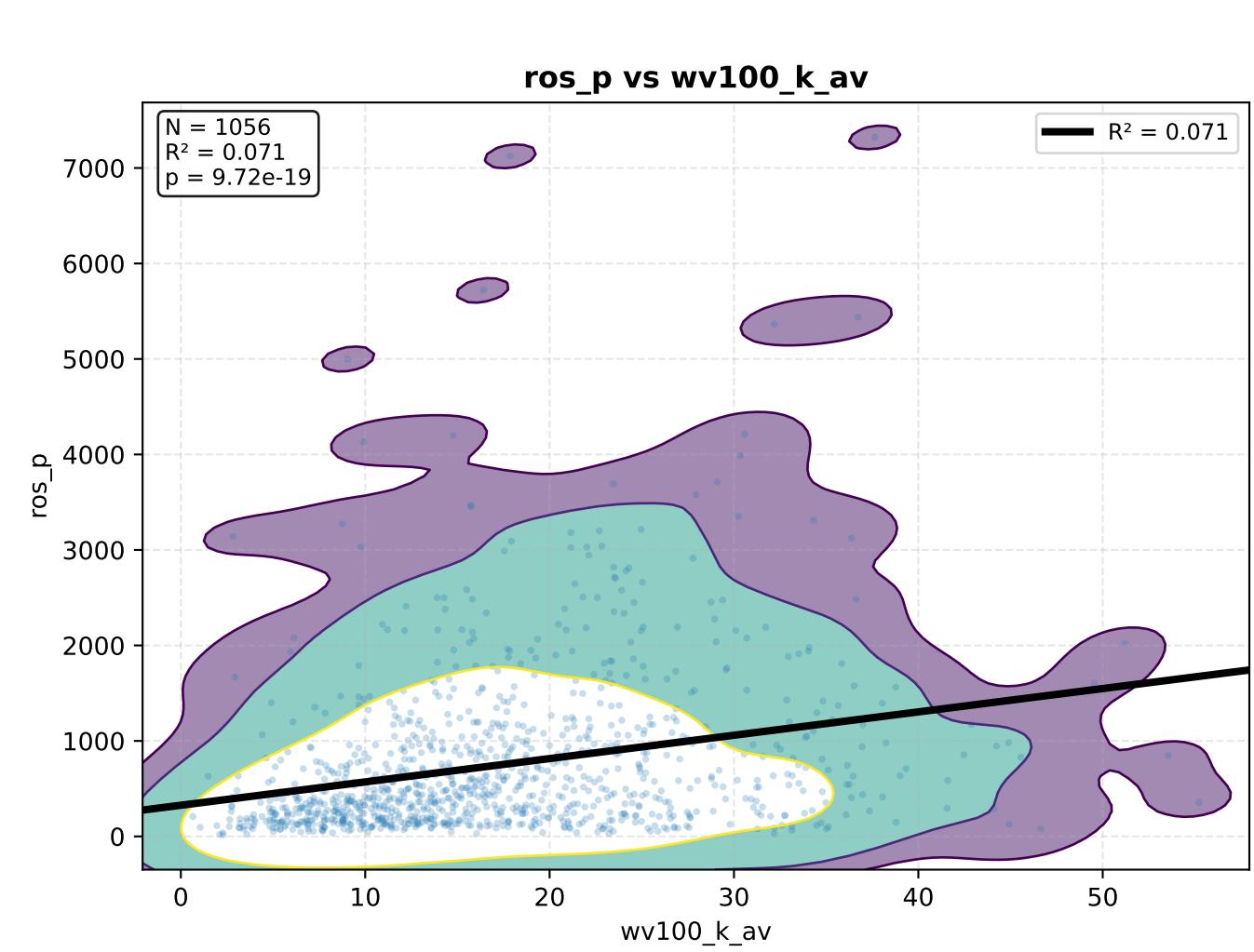
**log(ros\_p) vs wdir10\_av**



**log(ros\_p) vs log(wdir10\_av)**

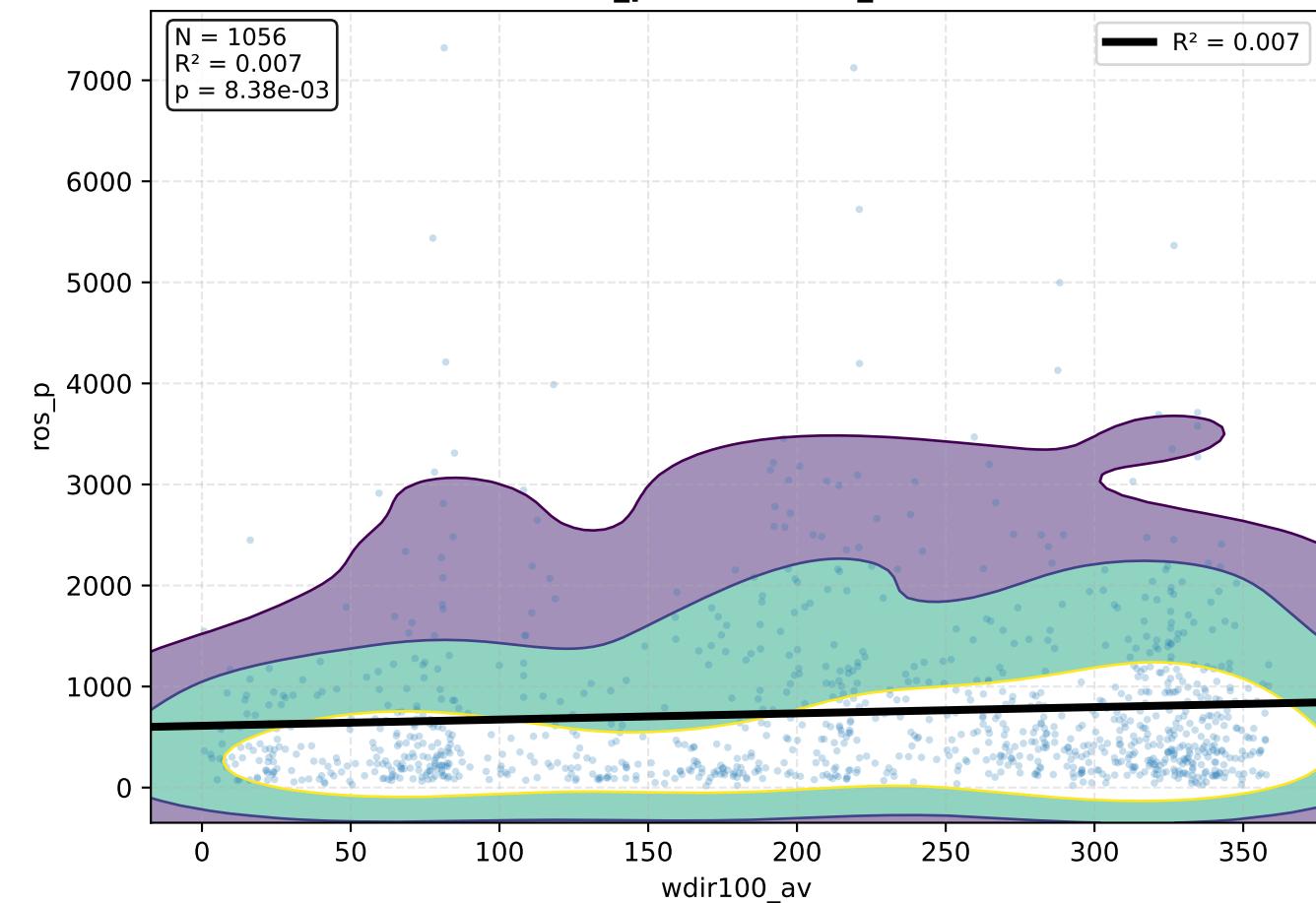


# wv100\_k\_av – KDE Density + Regressão

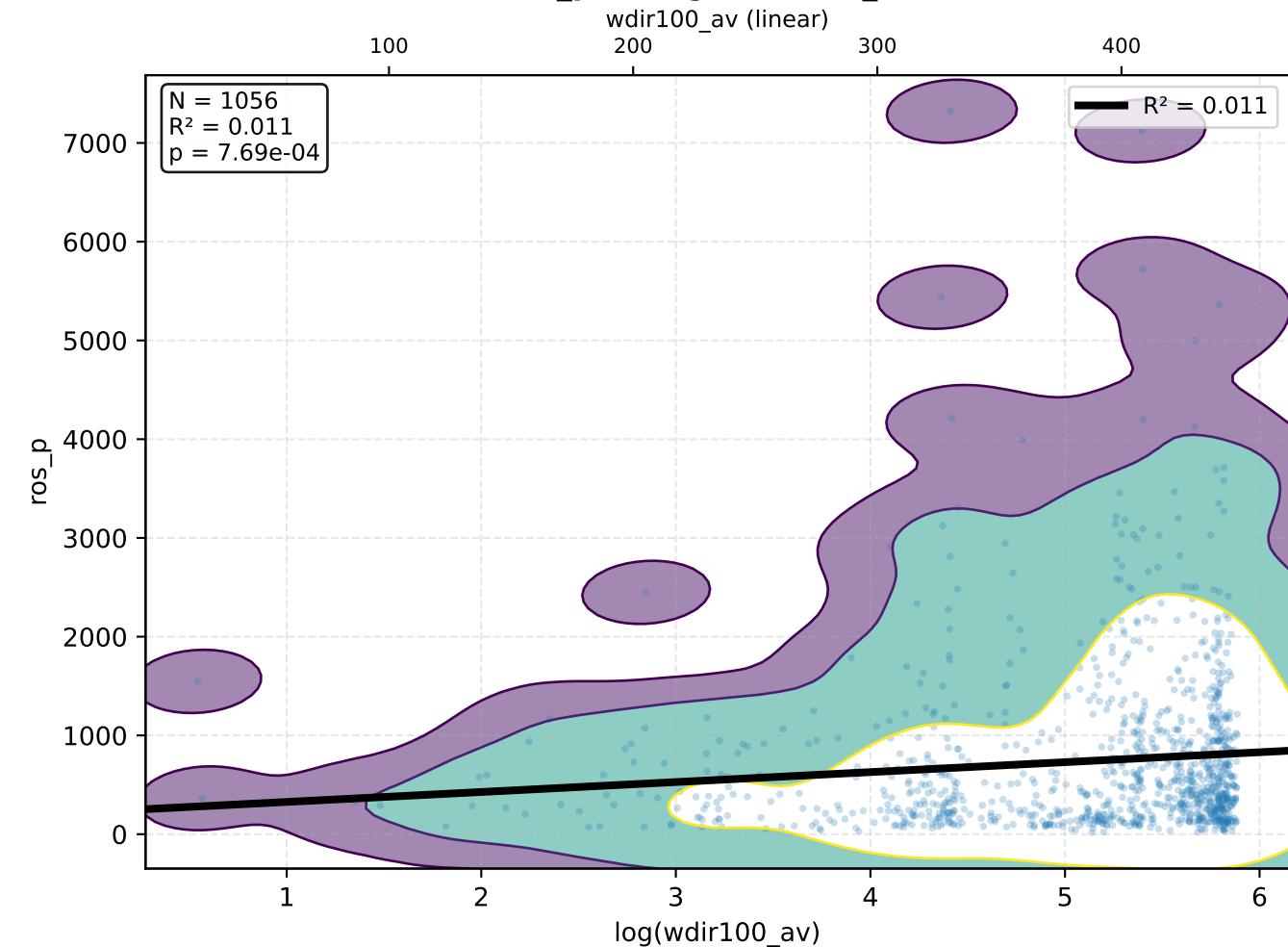


# wdir100\_av - KDE Density + Regressão

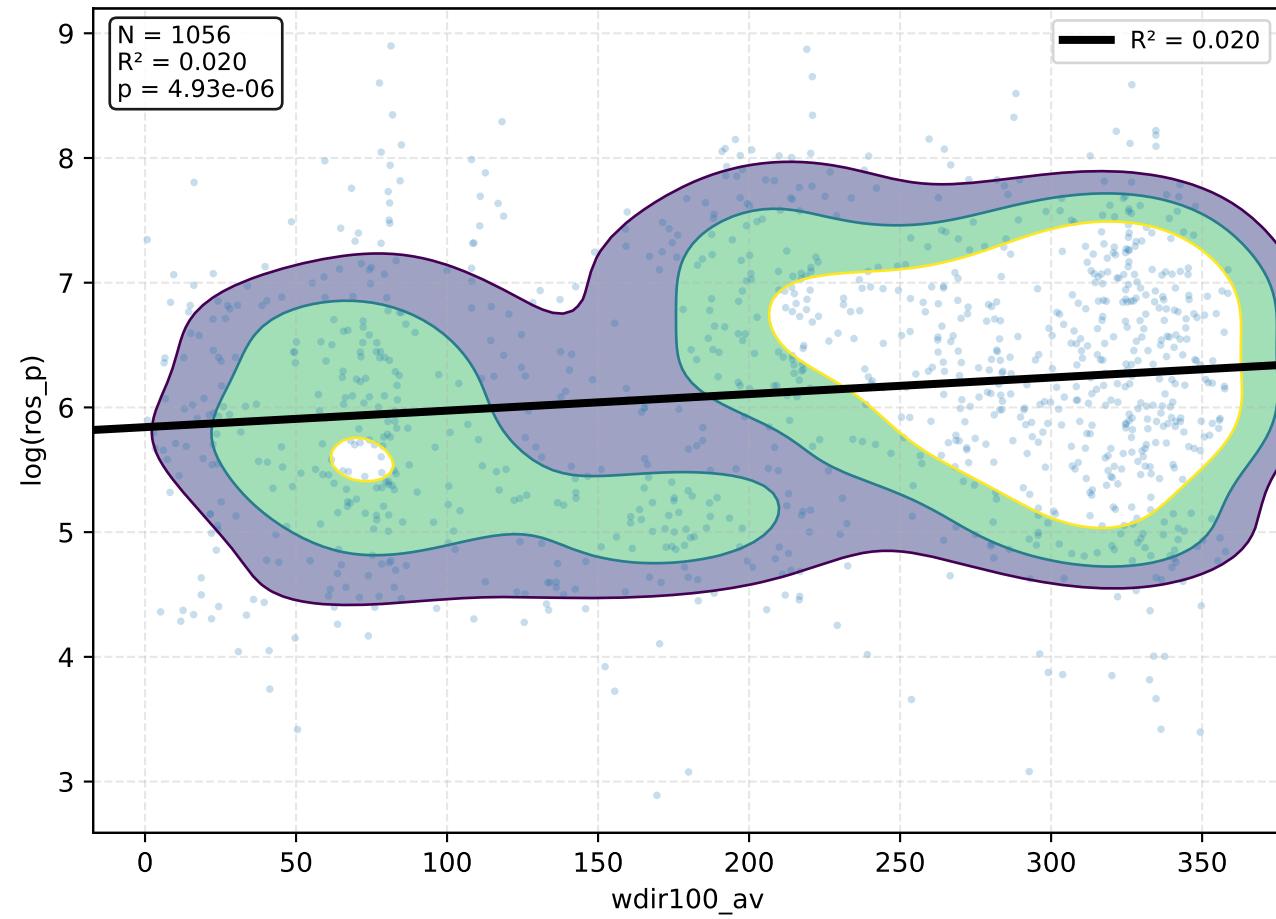
**ros\_p vs wdir100\_av**



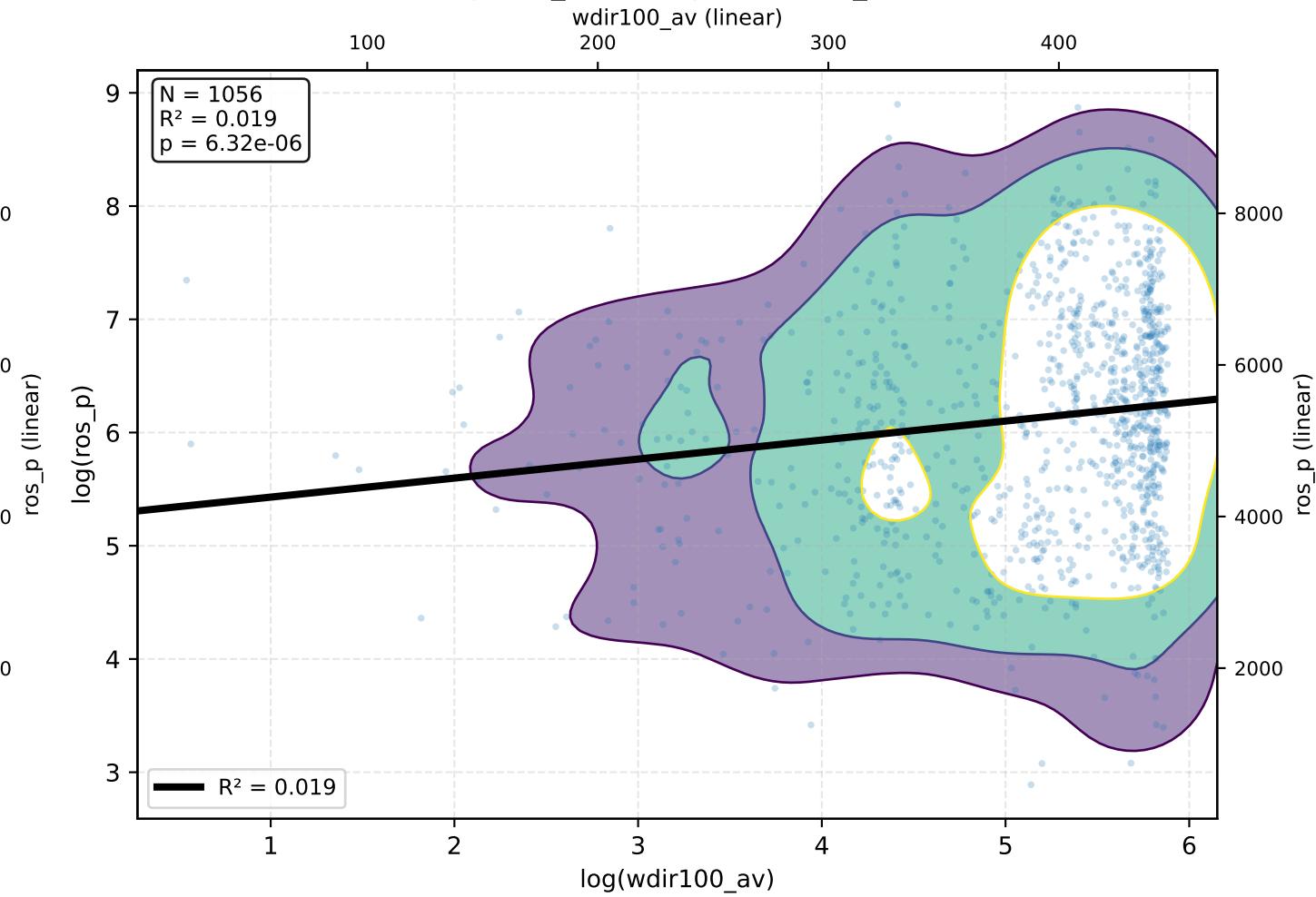
**ros\_p vs log(wdir100\_av)**



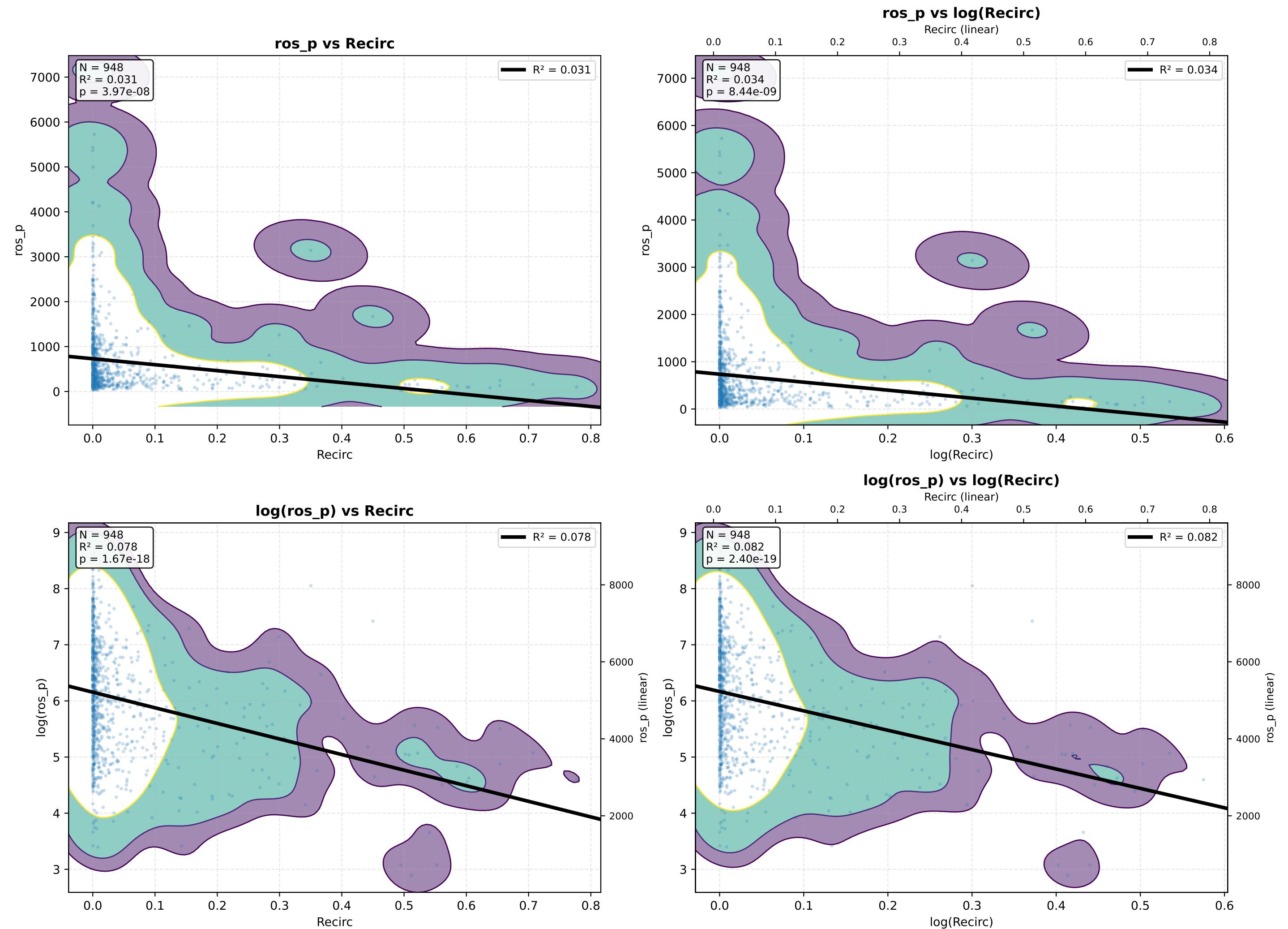
**log(ros\_p) vs wdir100\_av**



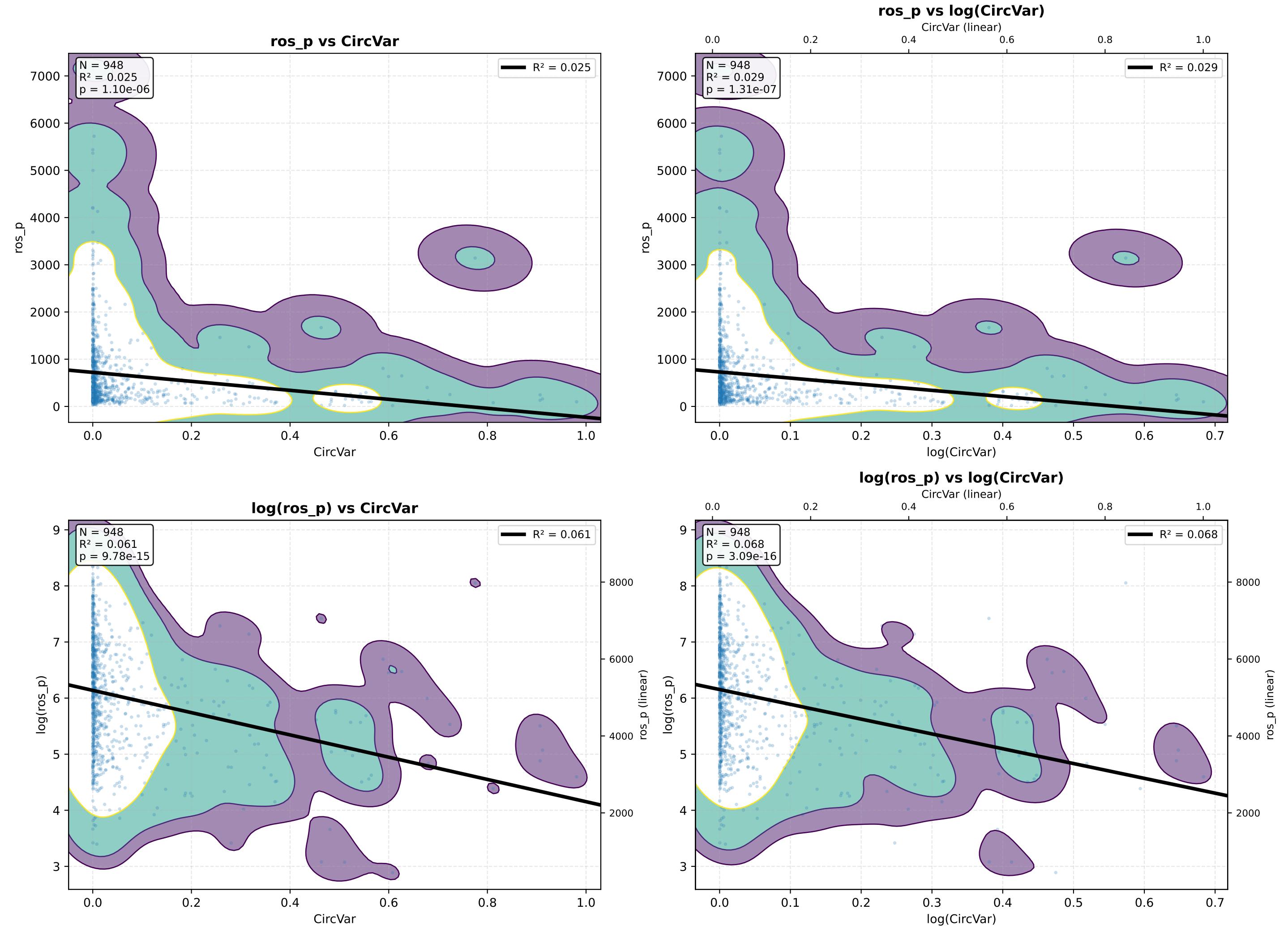
**log(ros\_p) vs log(wdir100\_av)**



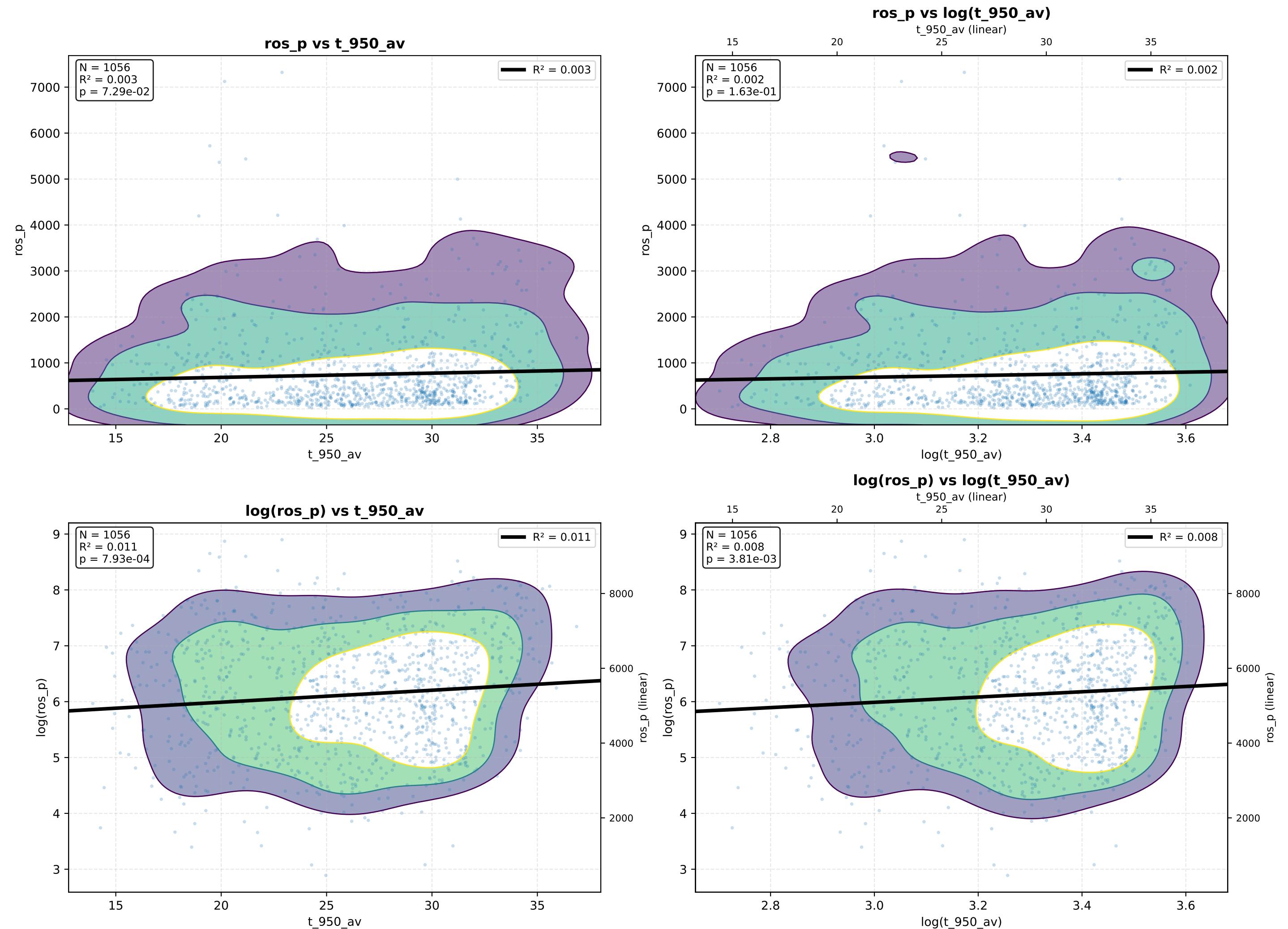
# Recirc – KDE Density + Regressão



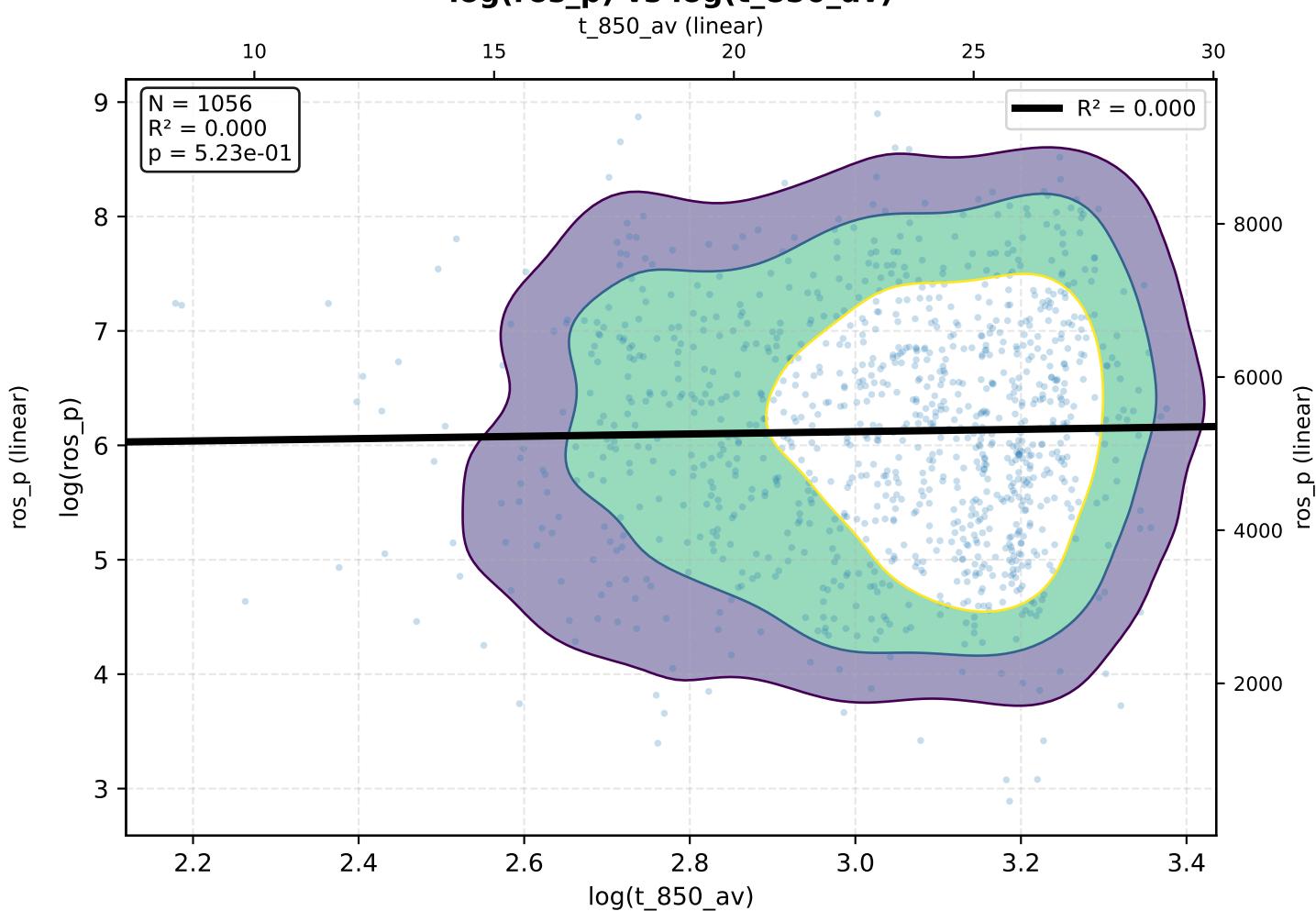
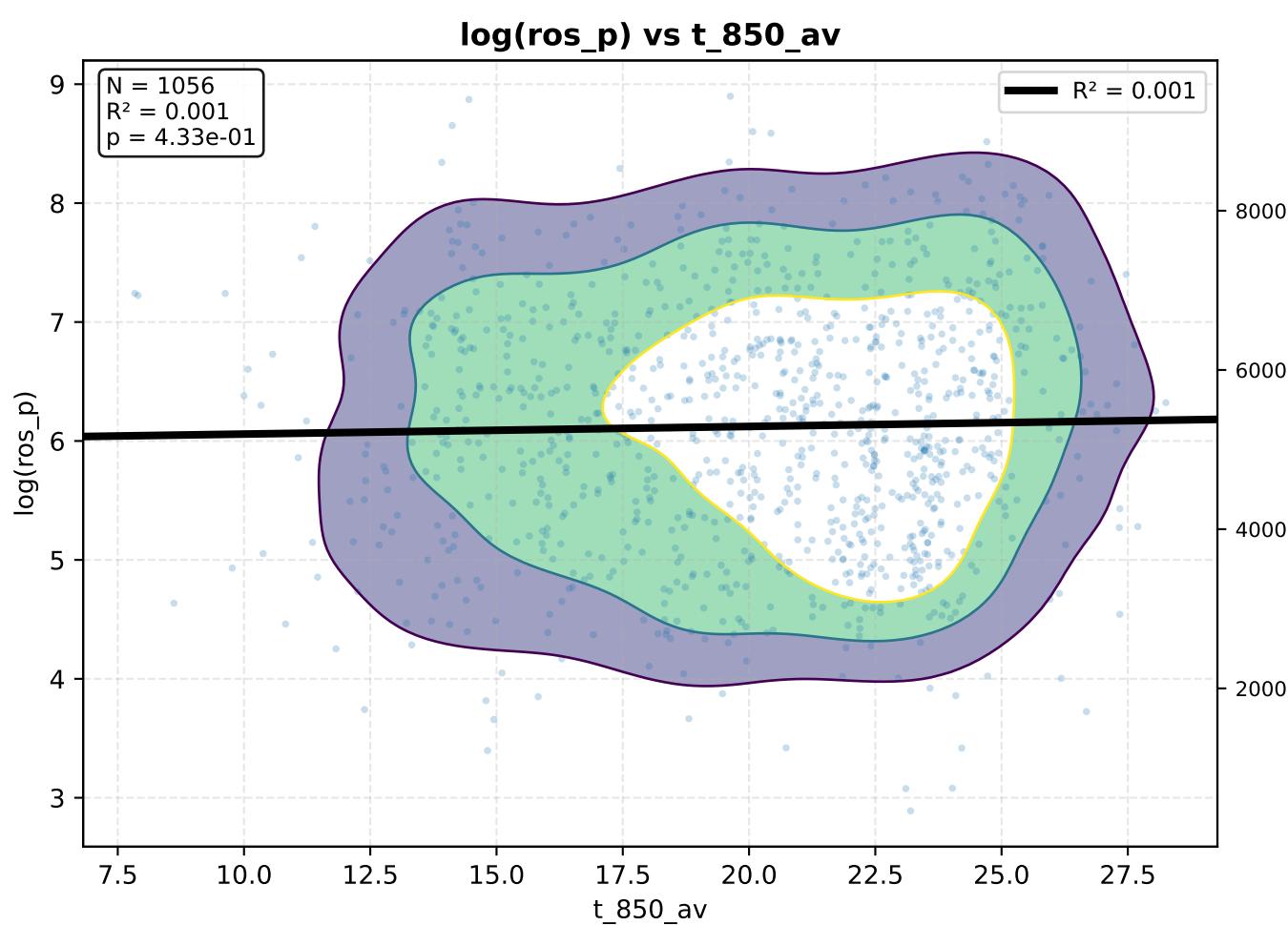
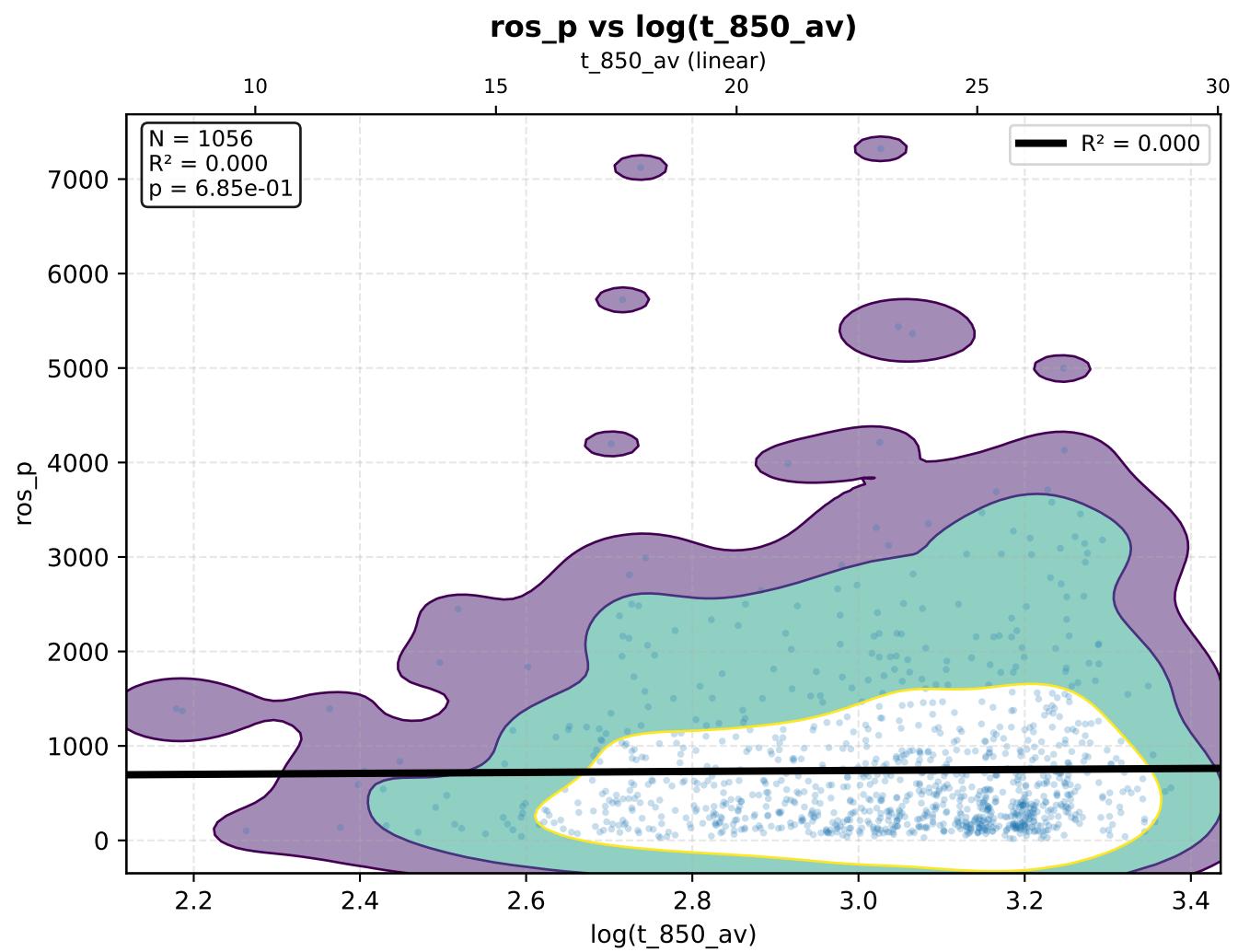
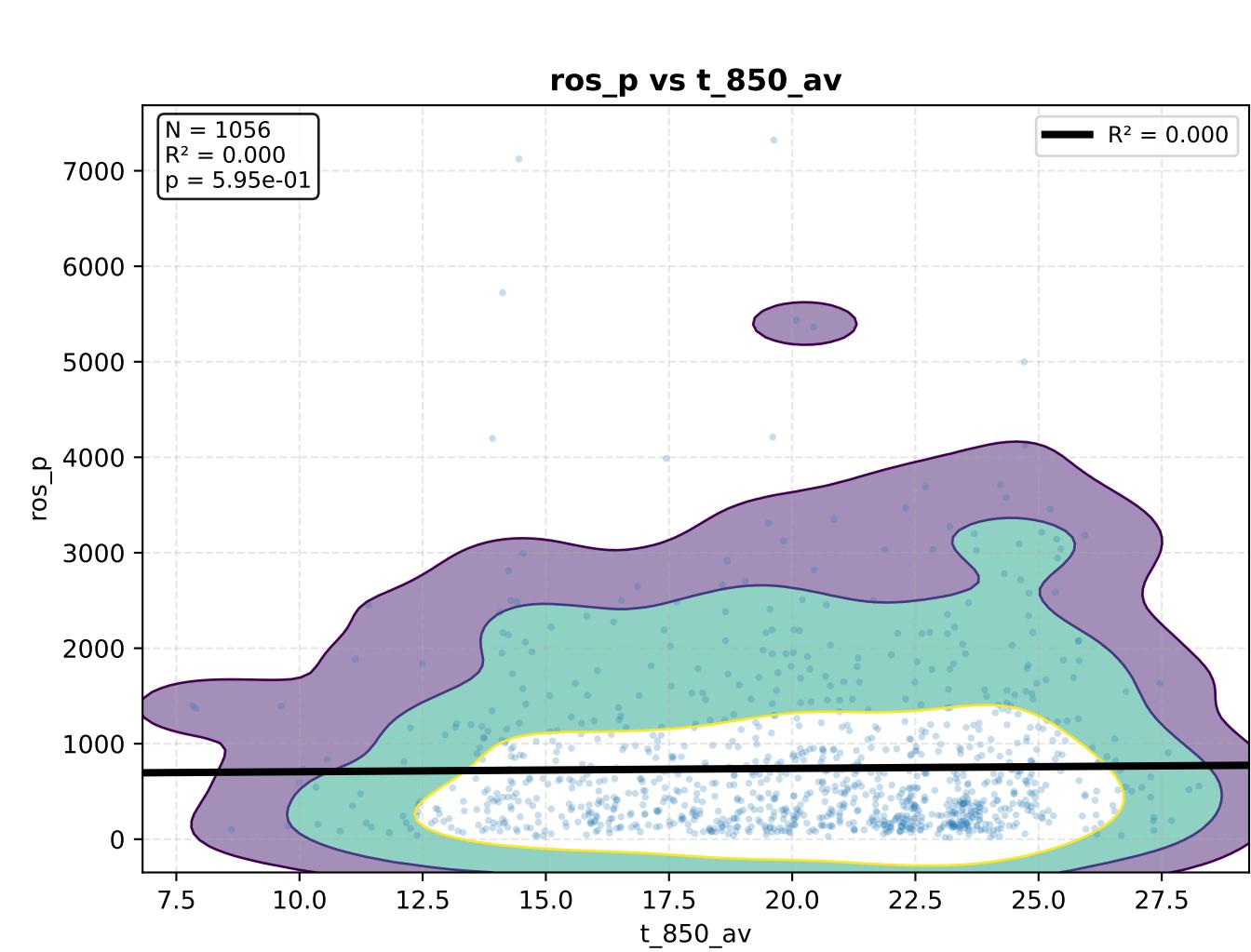
# CircVar – KDE Density + Regressão



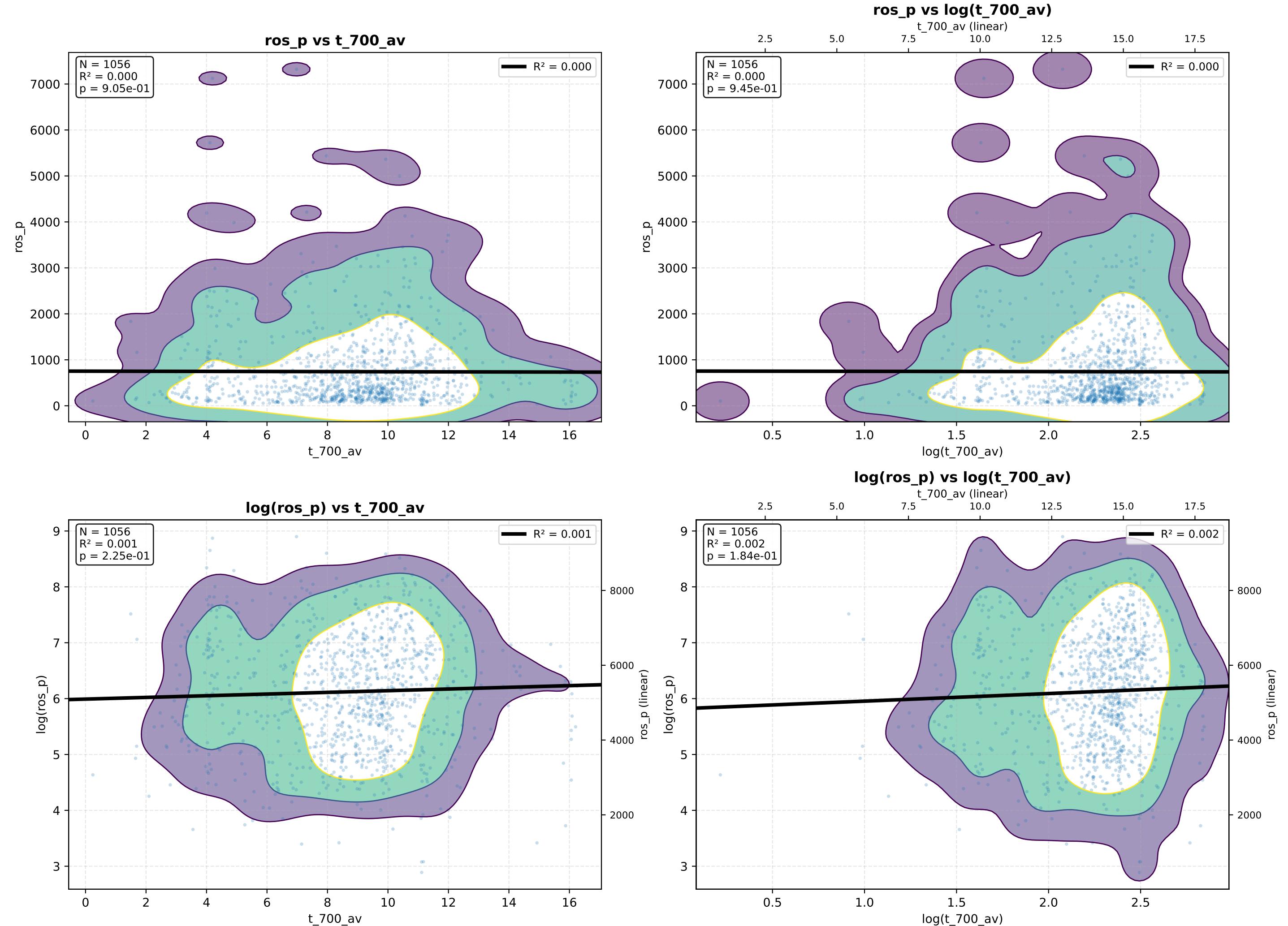
# t\_950\_av – KDE Density + Regressão



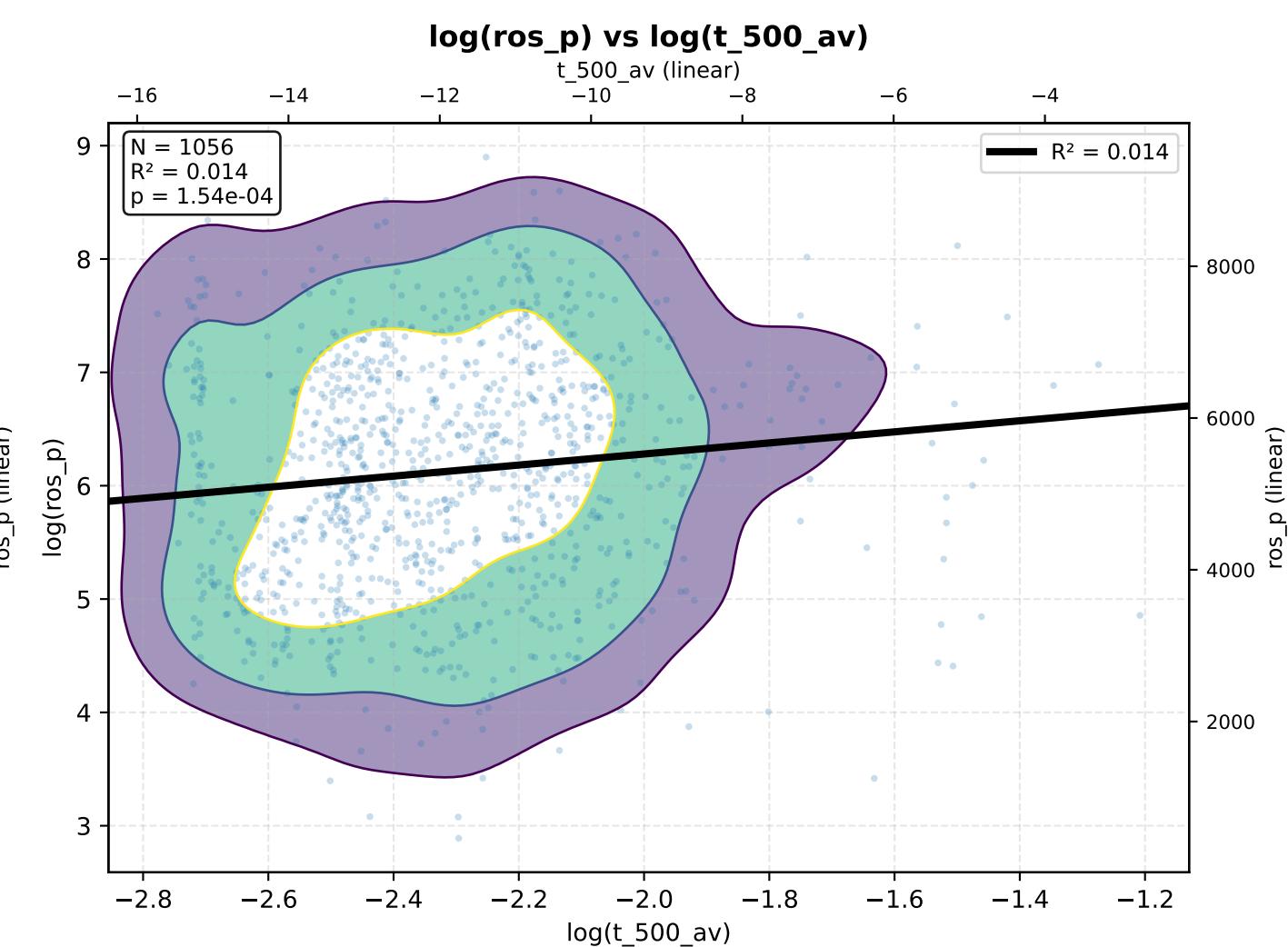
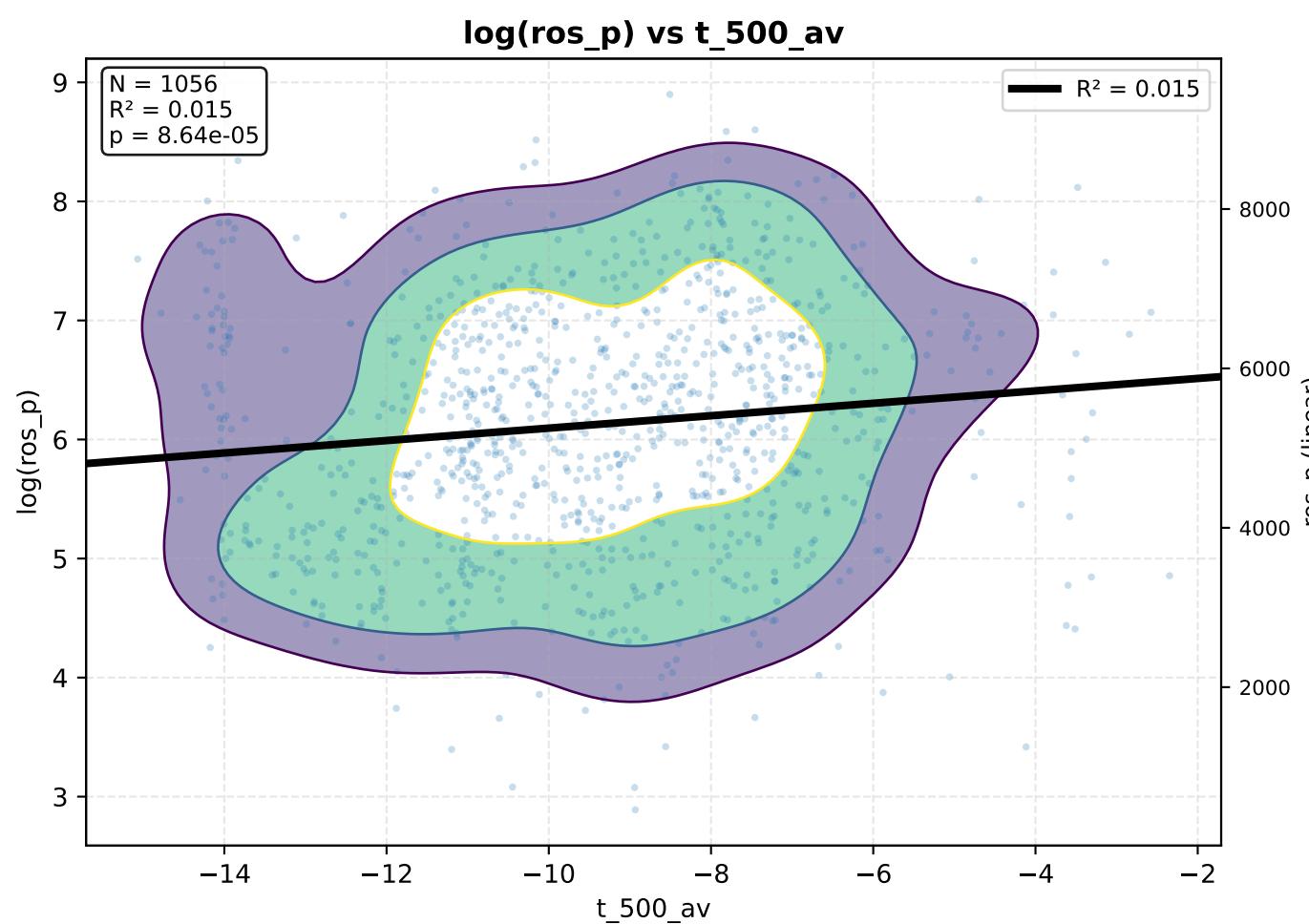
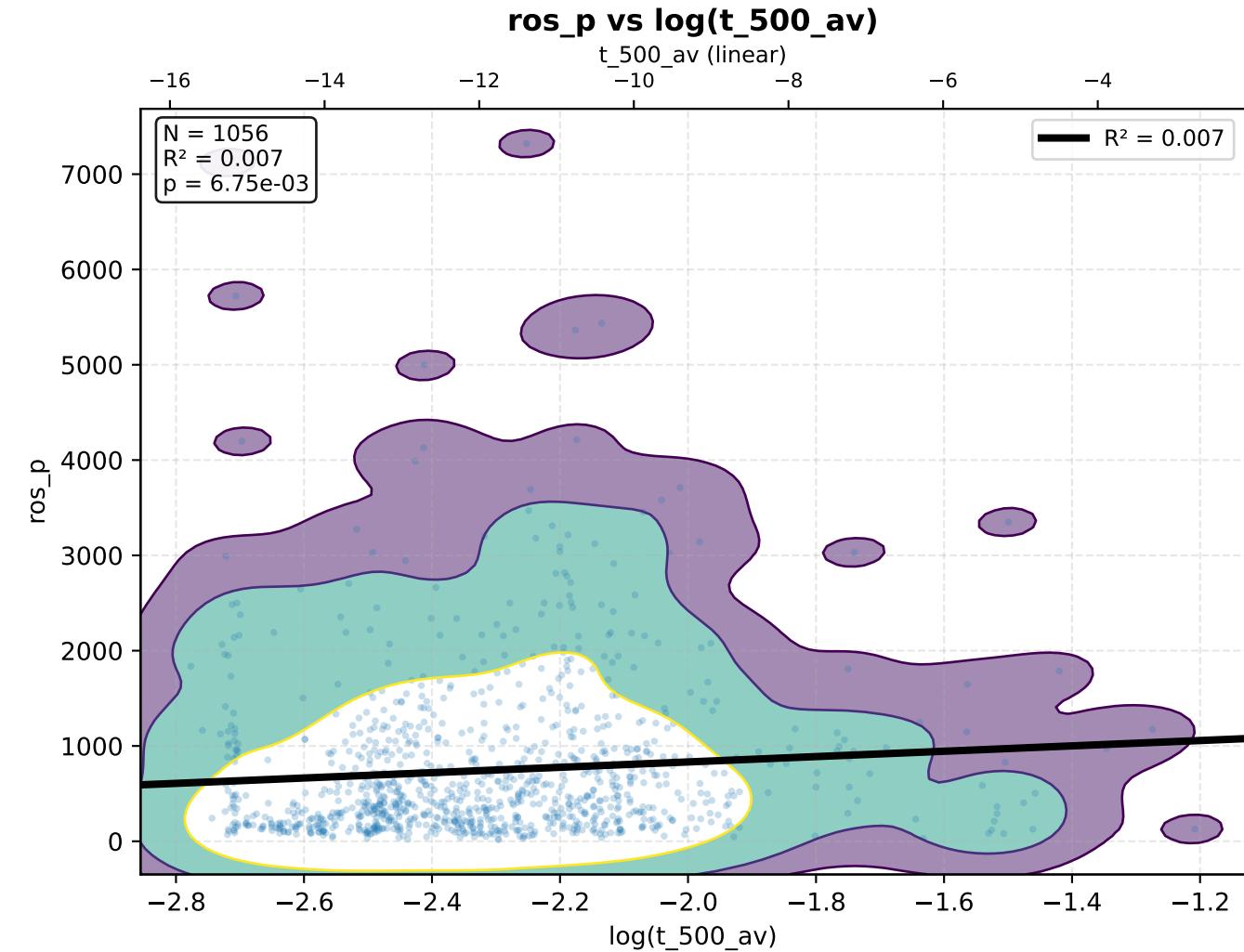
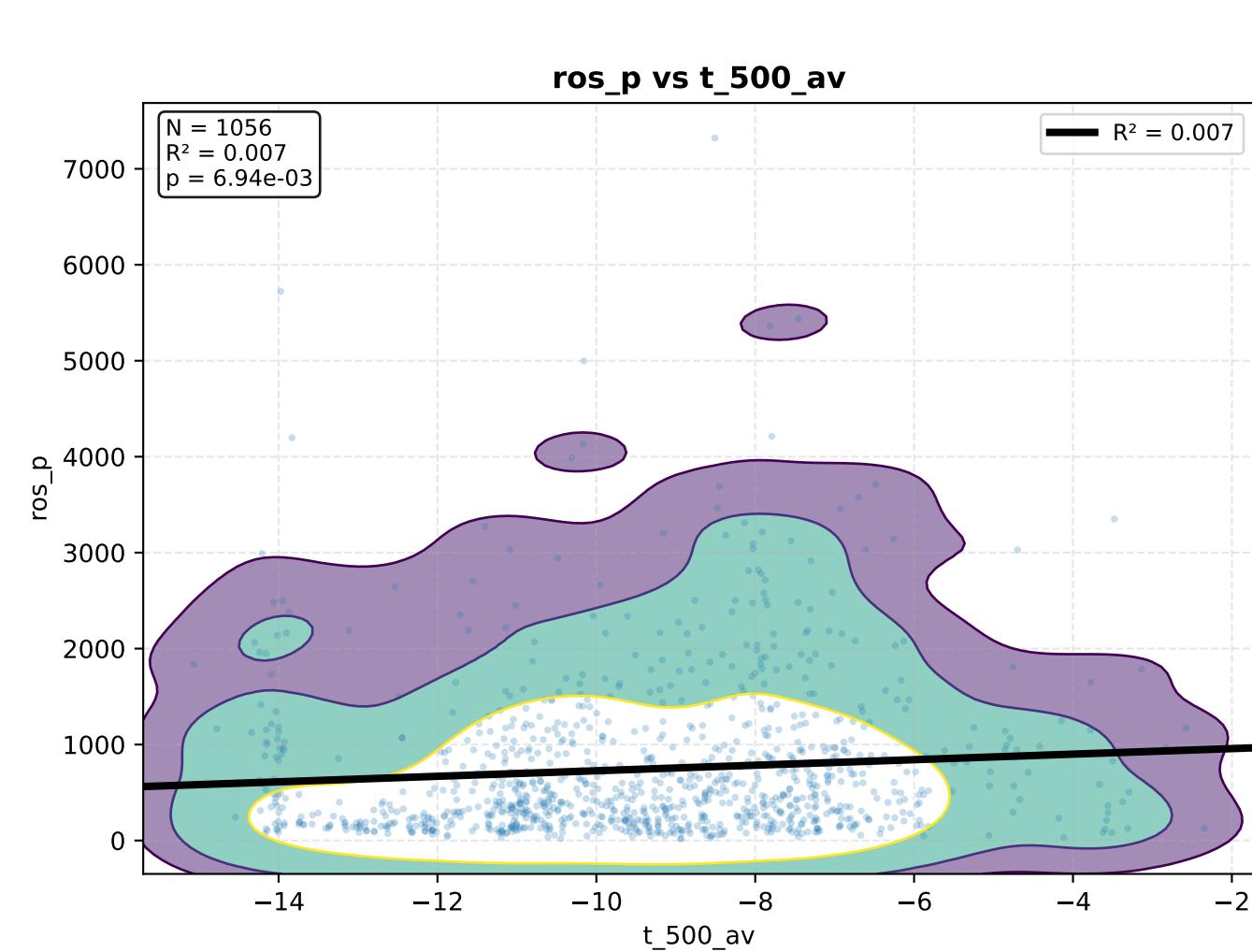
# t\_850\_av – KDE Density + Regressão



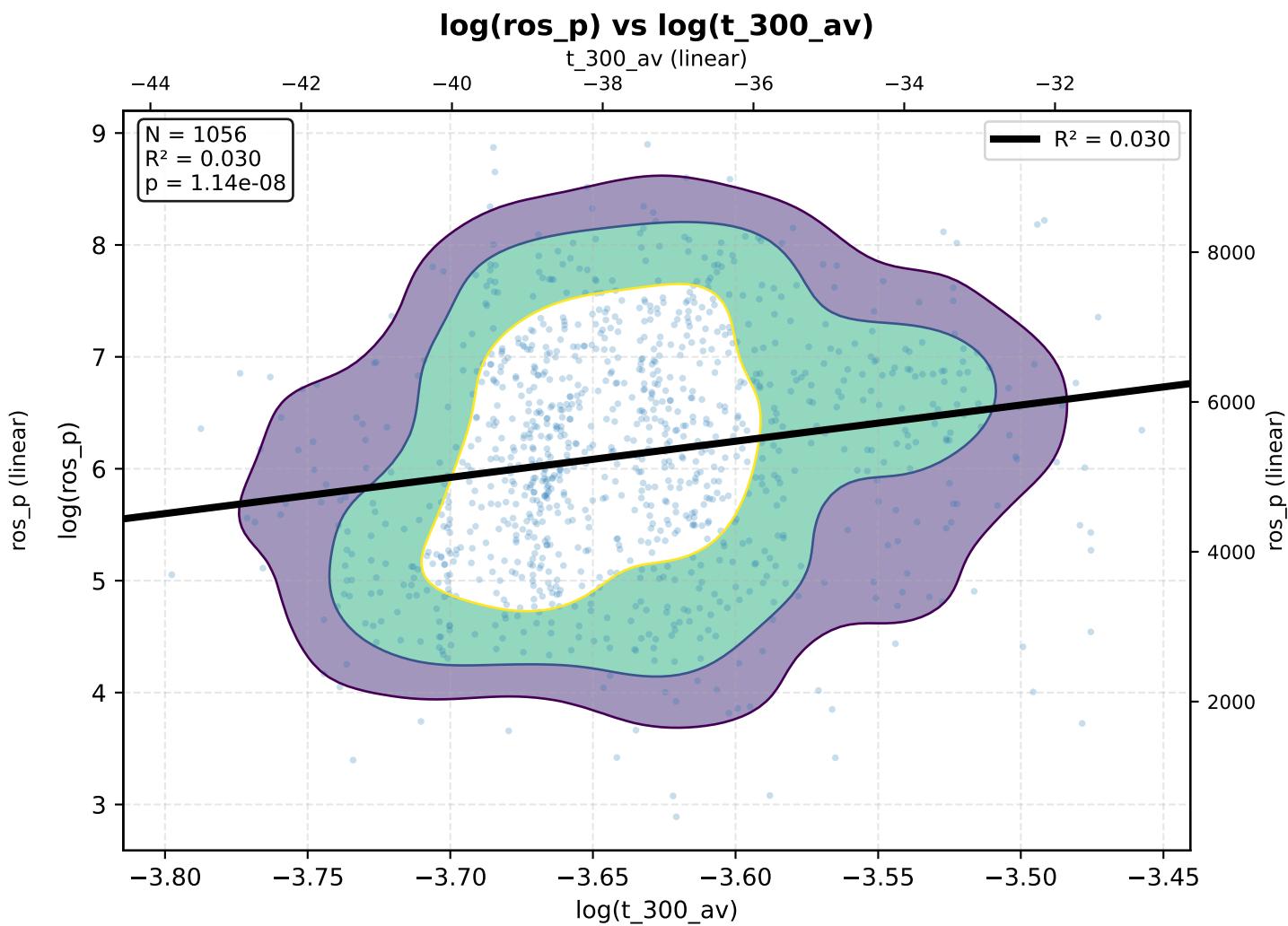
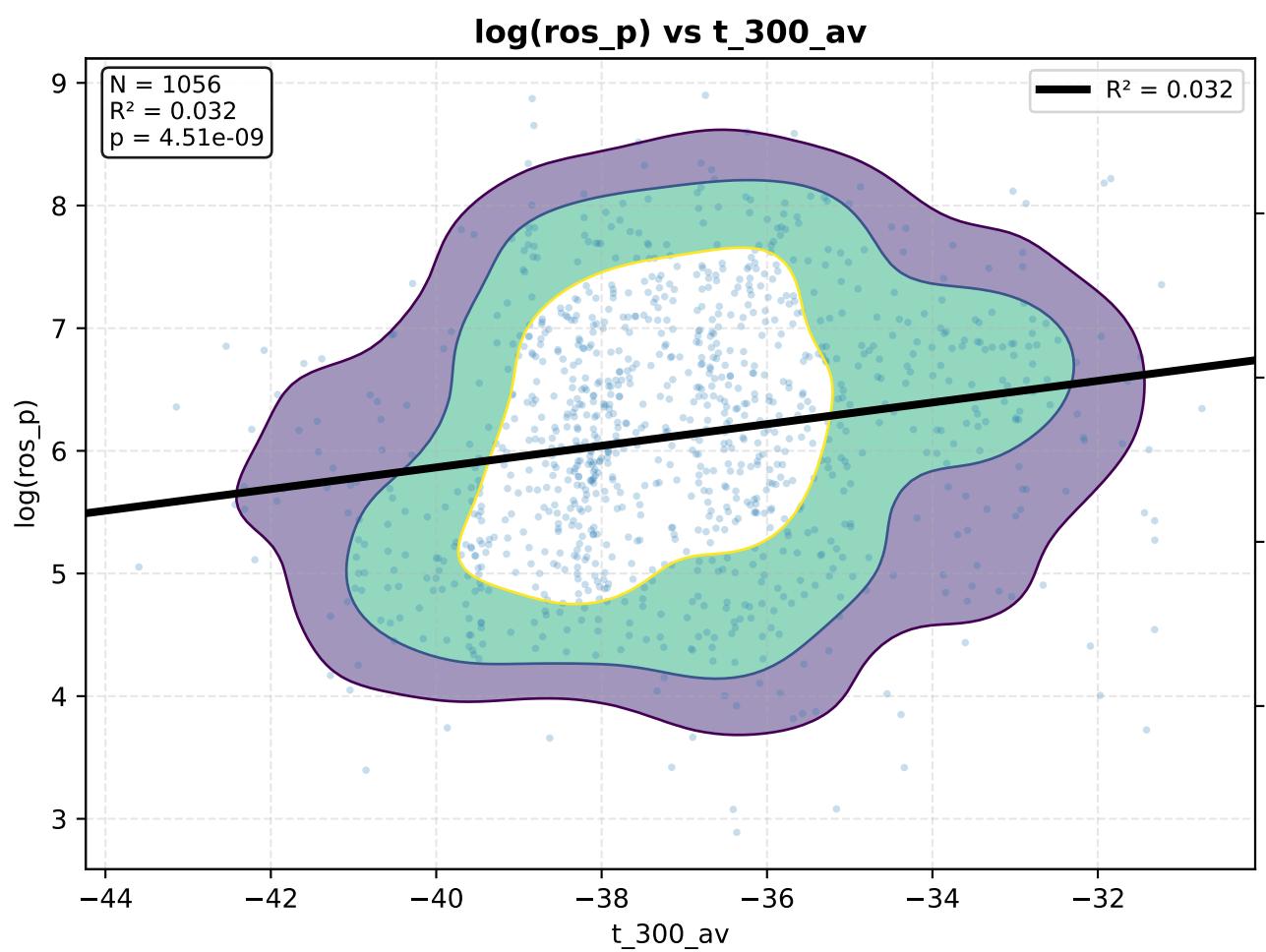
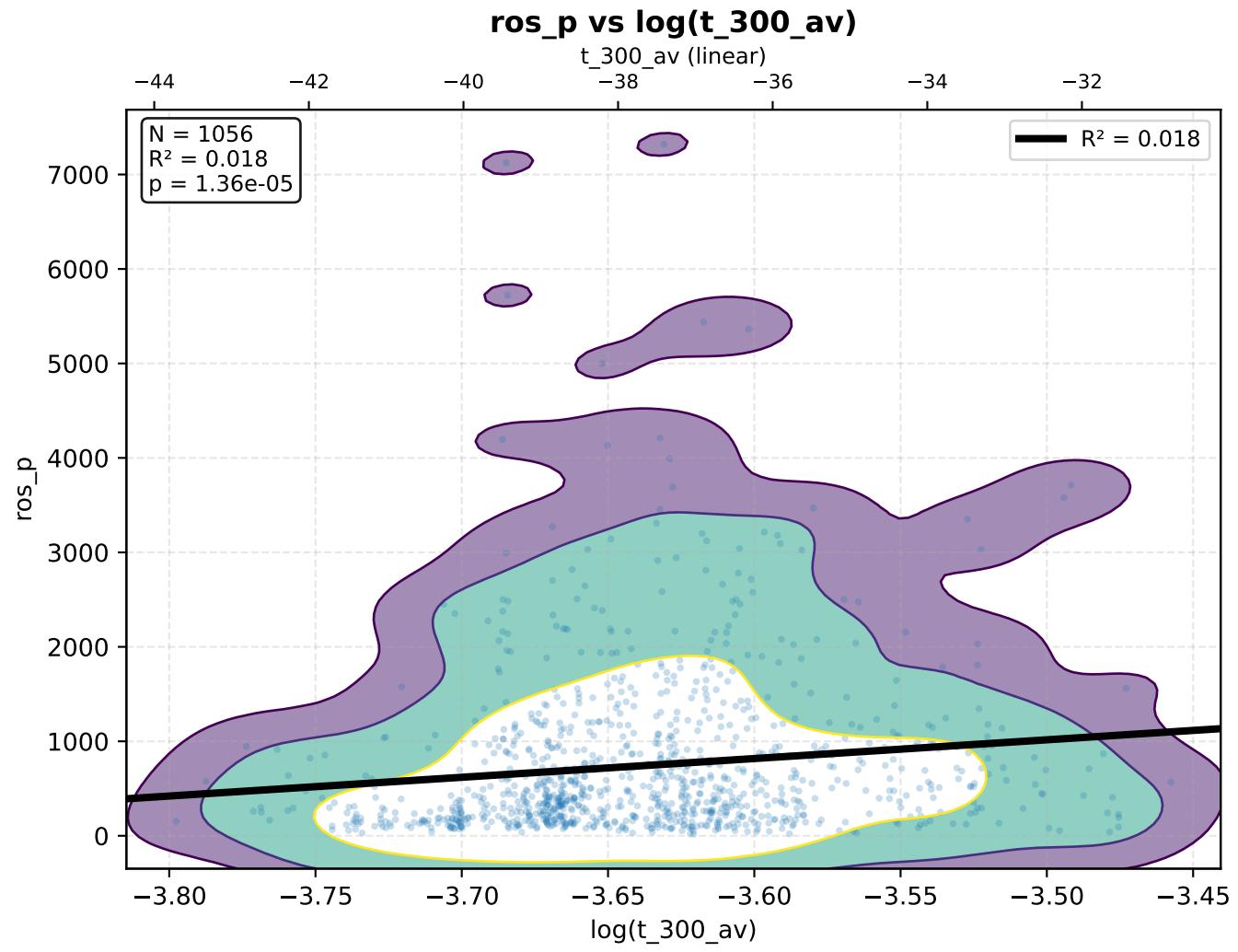
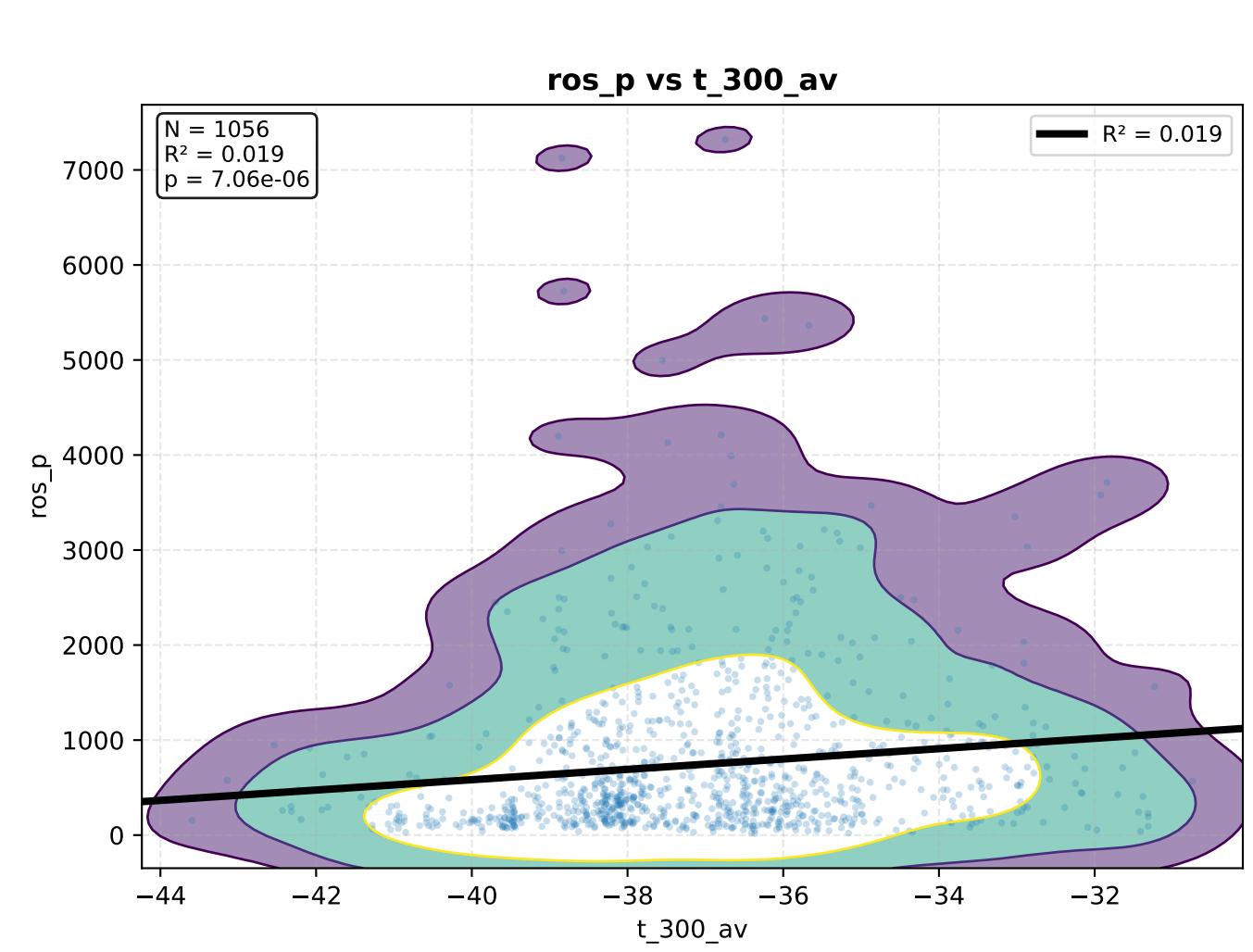
# t\_700\_av – KDE Density + Regressão



# t\_500\_av – KDE Density + Regressão

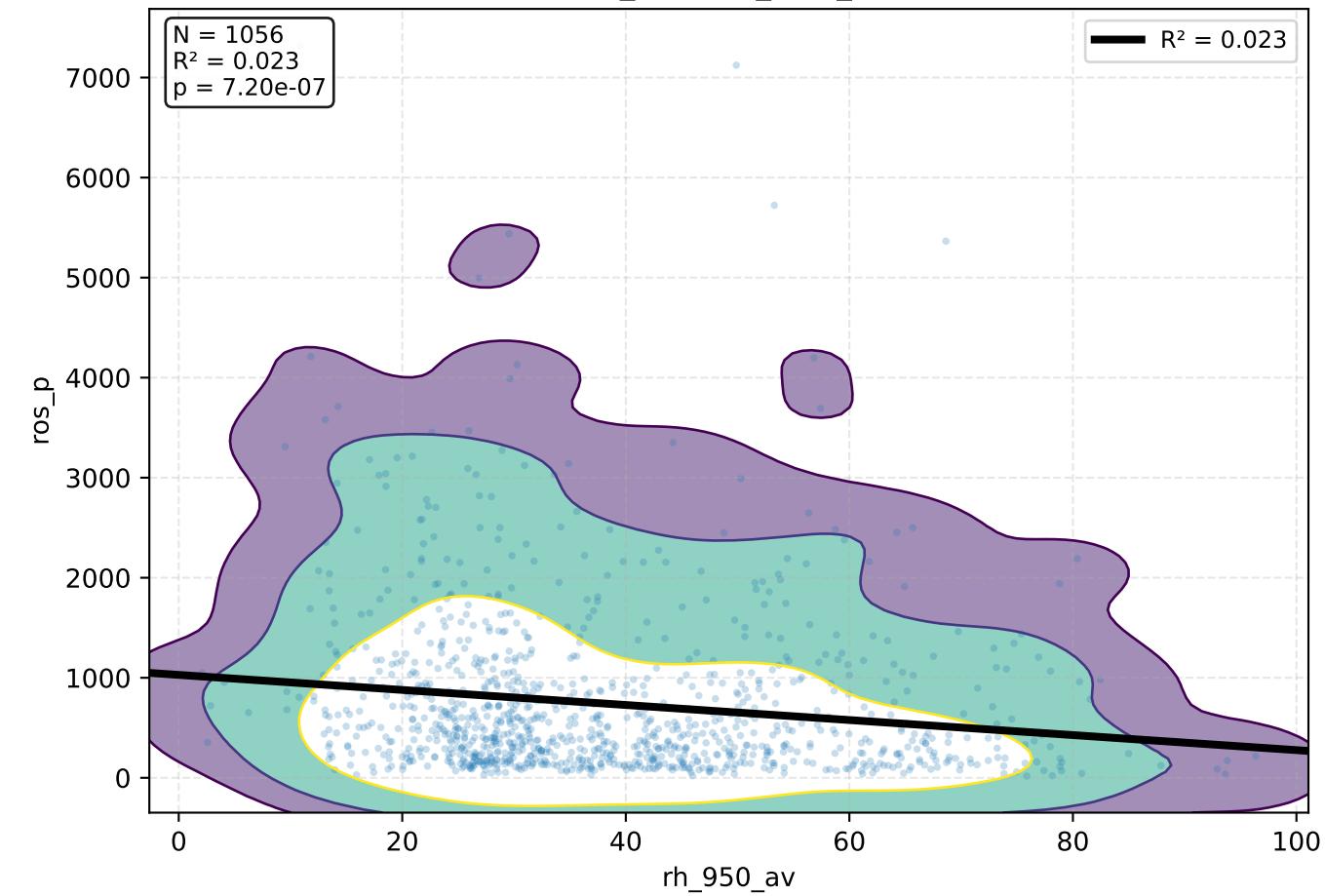


# t\_300\_av – KDE Density + Regressão

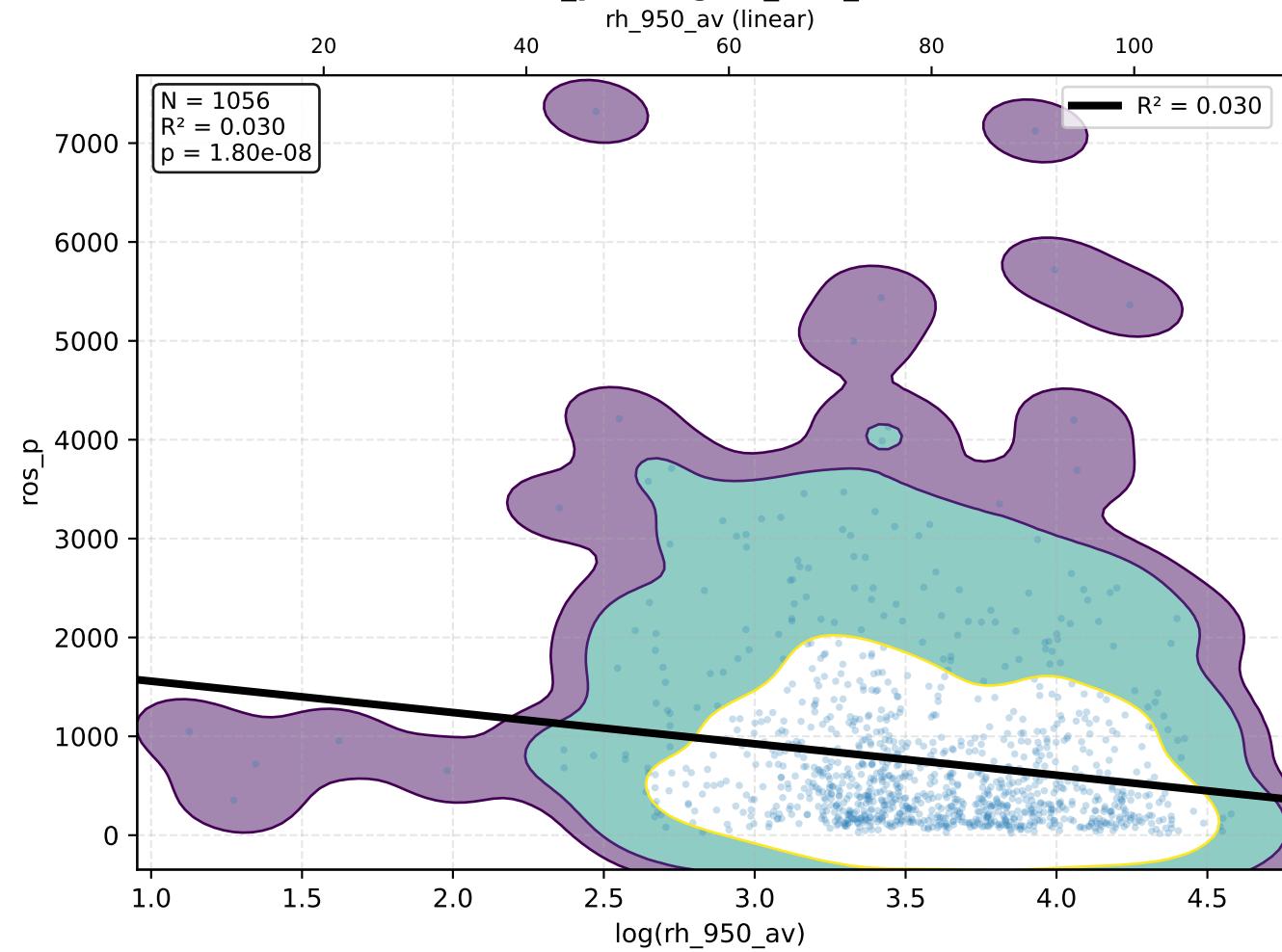


# rh\_950\_av – KDE Density + Regressão

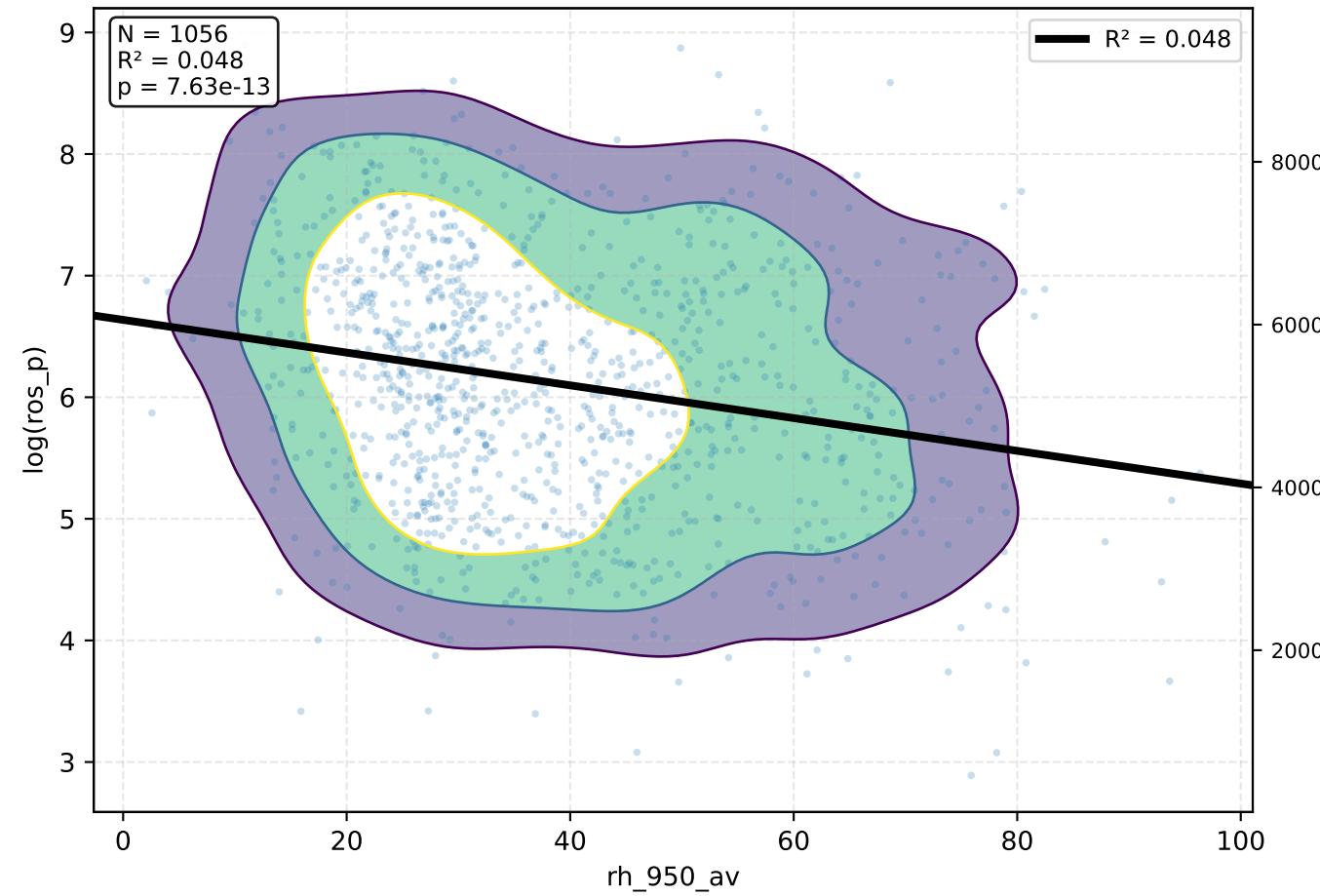
**ros\_p vs rh\_950\_av**



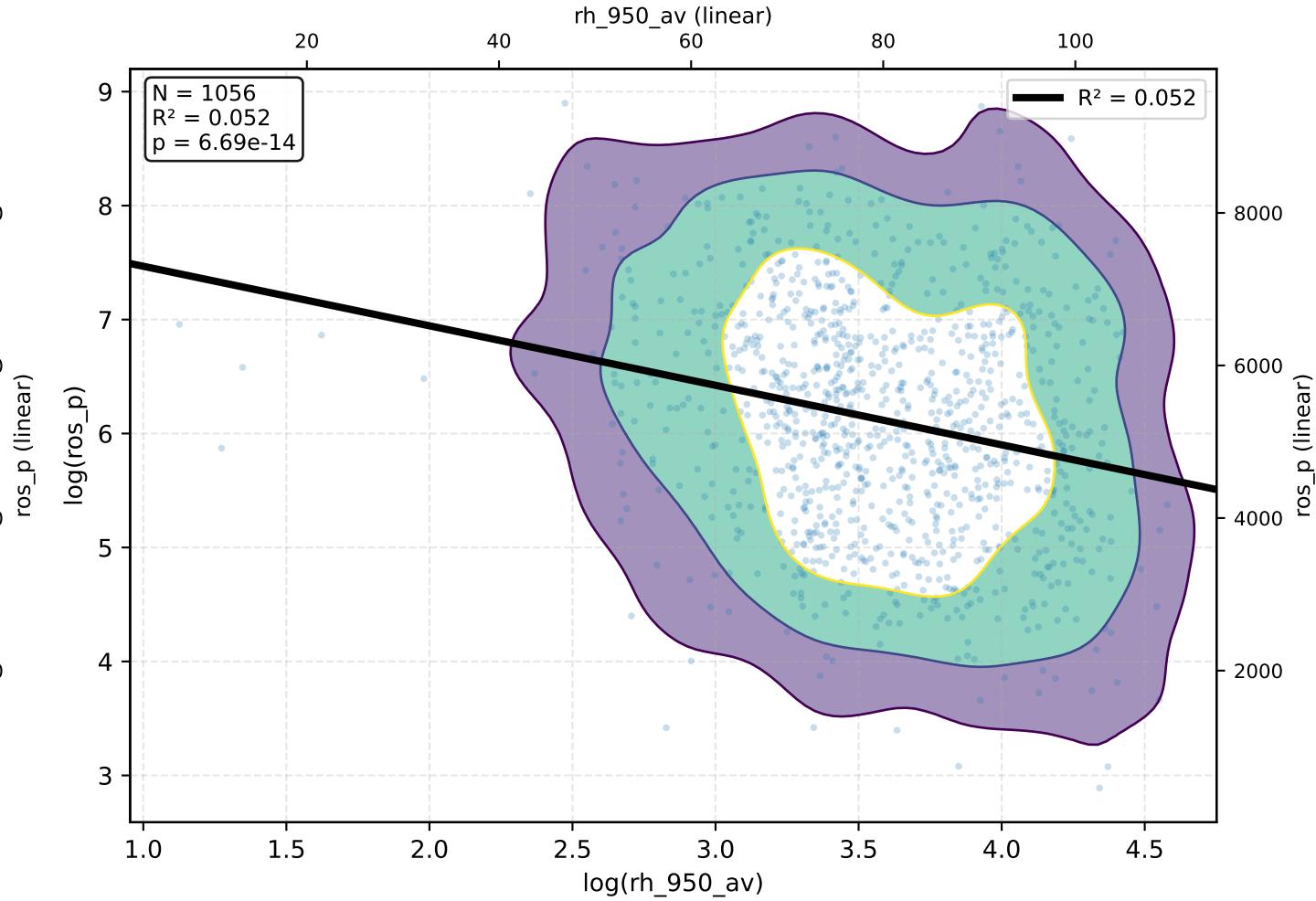
**ros\_p vs log(rh\_950\_av)**



**log(ros\_p) vs rh\_950\_av**

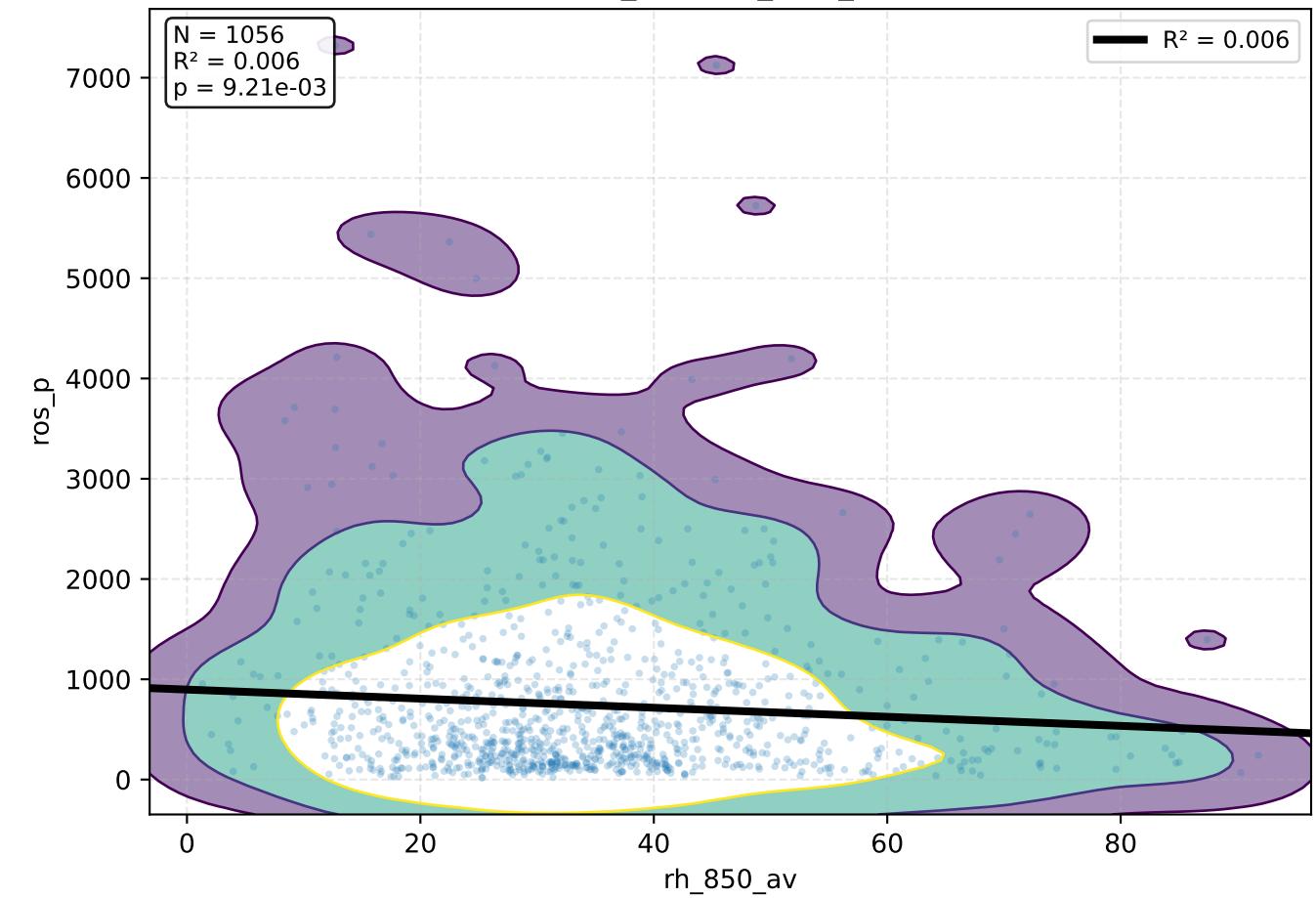


**log(ros\_p) vs log(rh\_950\_av)**

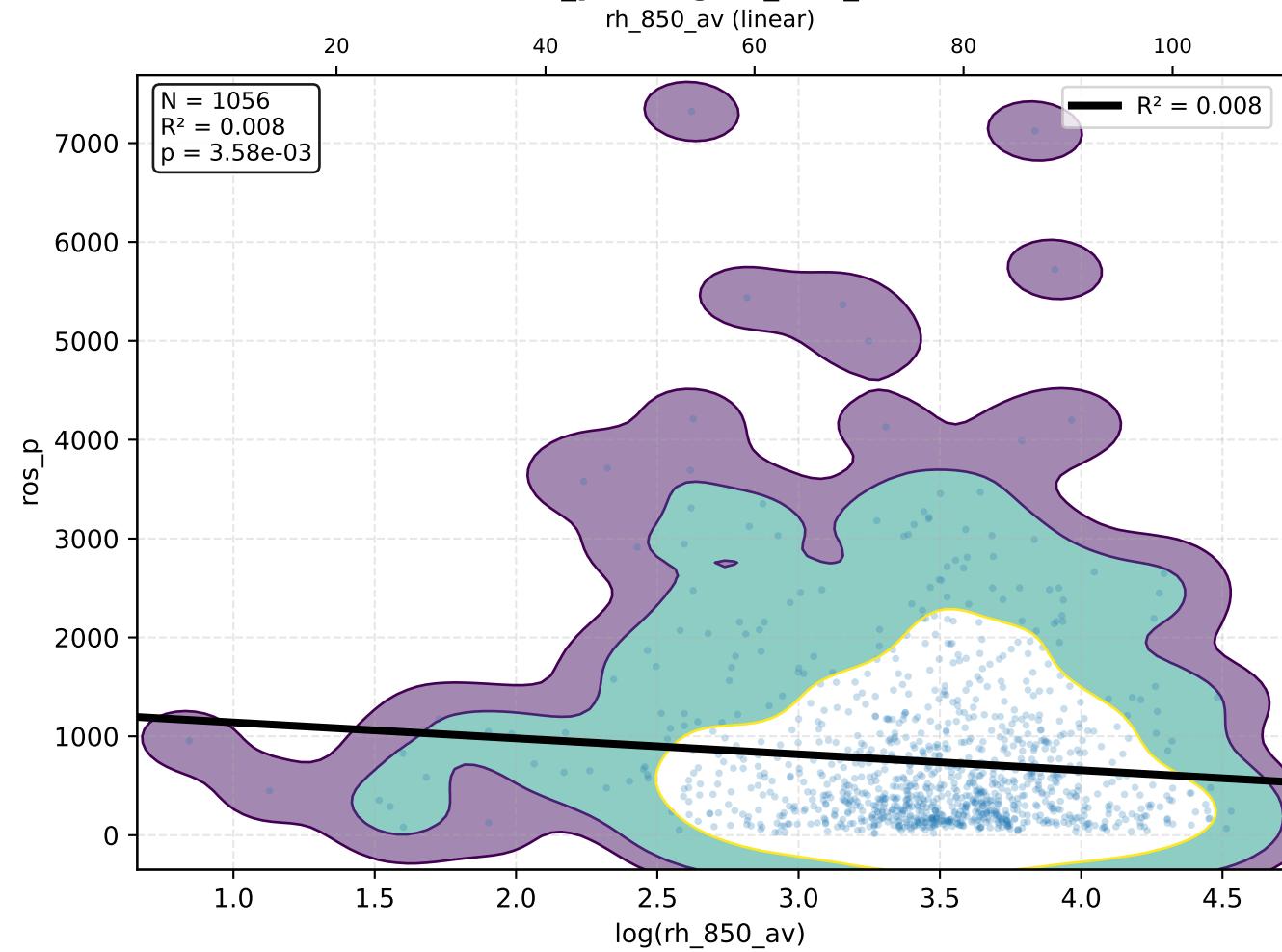


# rh\_850\_av – KDE Density + Regressão

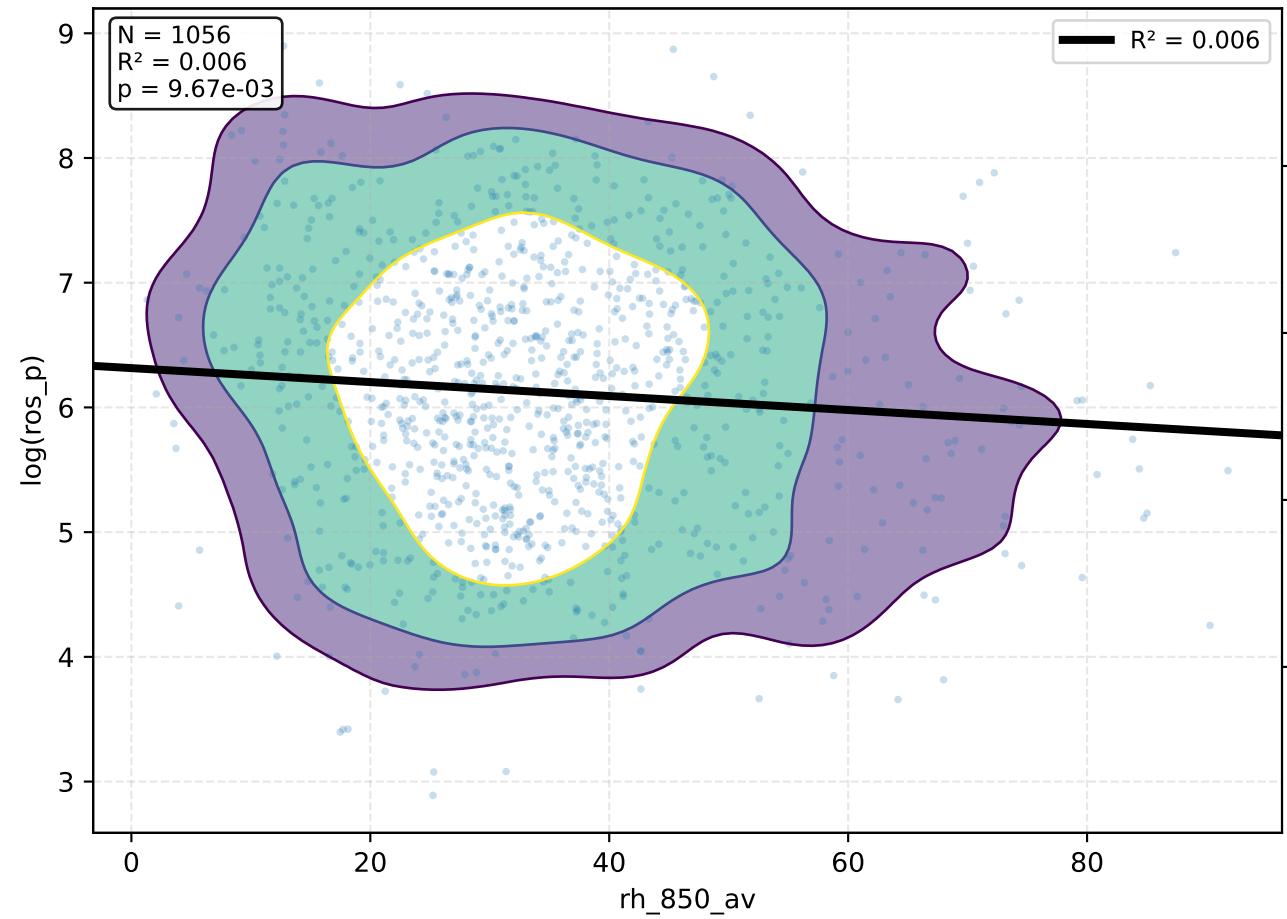
**ros\_p vs rh\_850\_av**



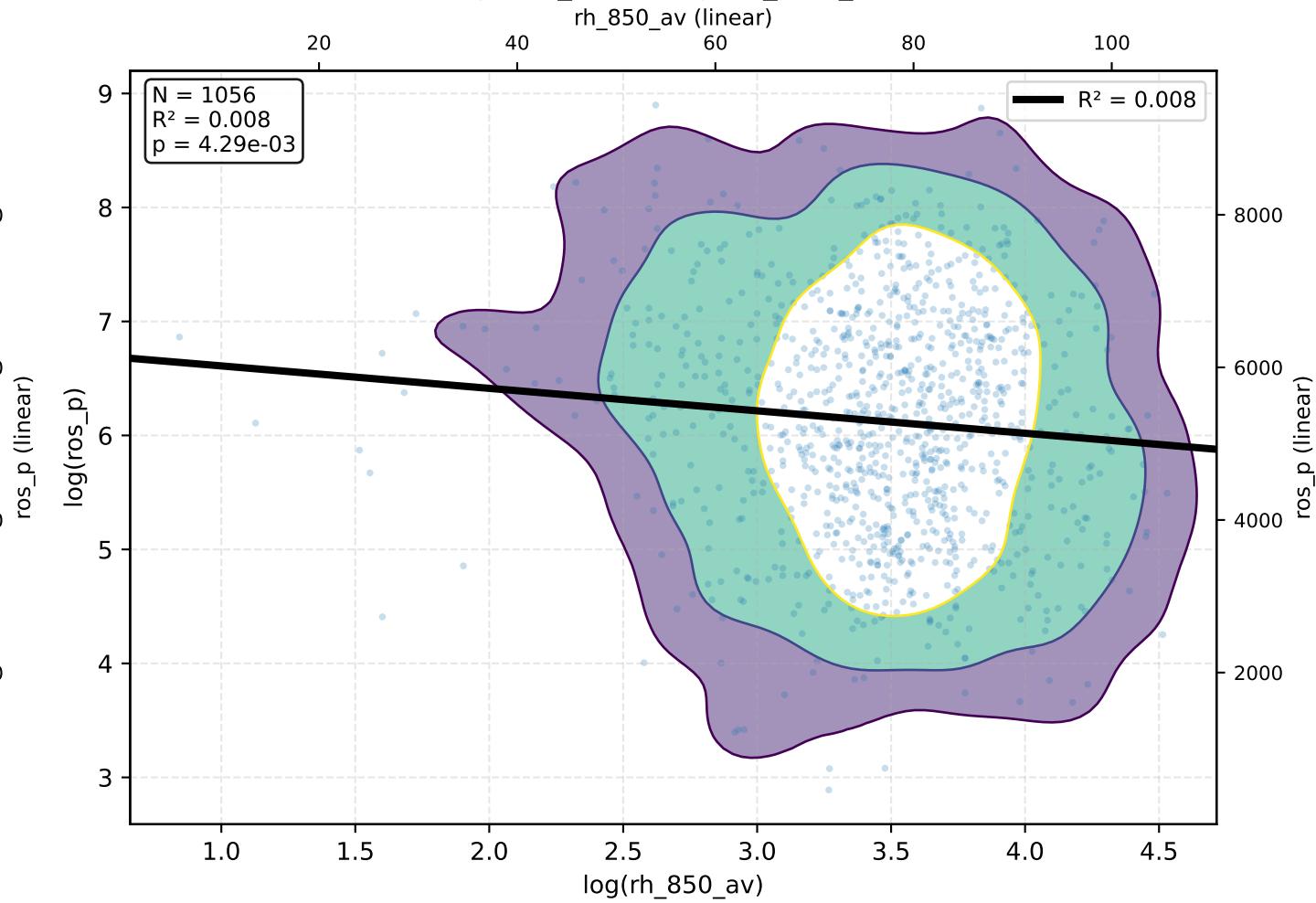
**ros\_p vs log(rh\_850\_av)**



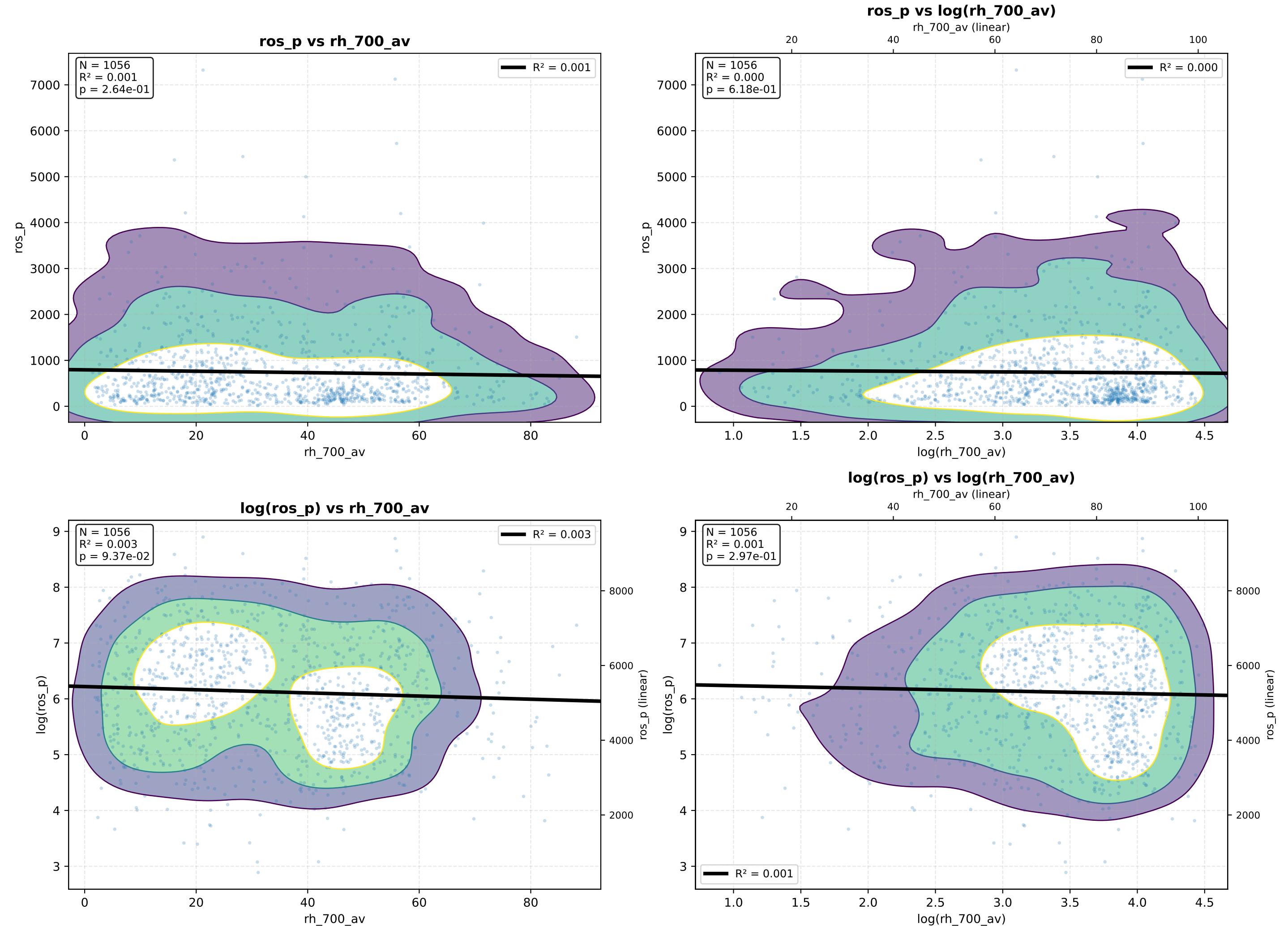
**log(ros\_p) vs rh\_850\_av**



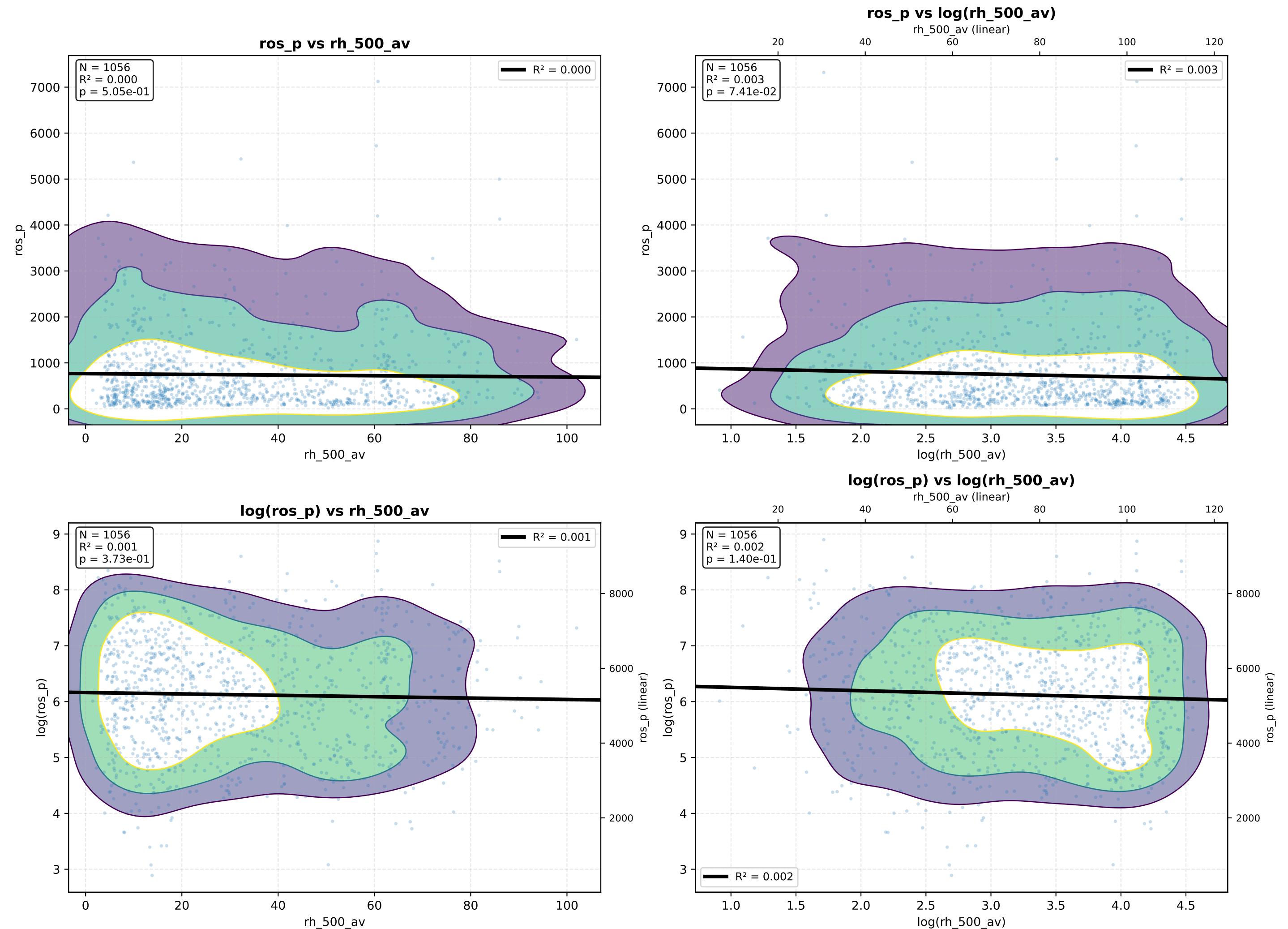
**log(ros\_p) vs log(rh\_850\_av)**



# rh\_700\_av – KDE Density + Regressão

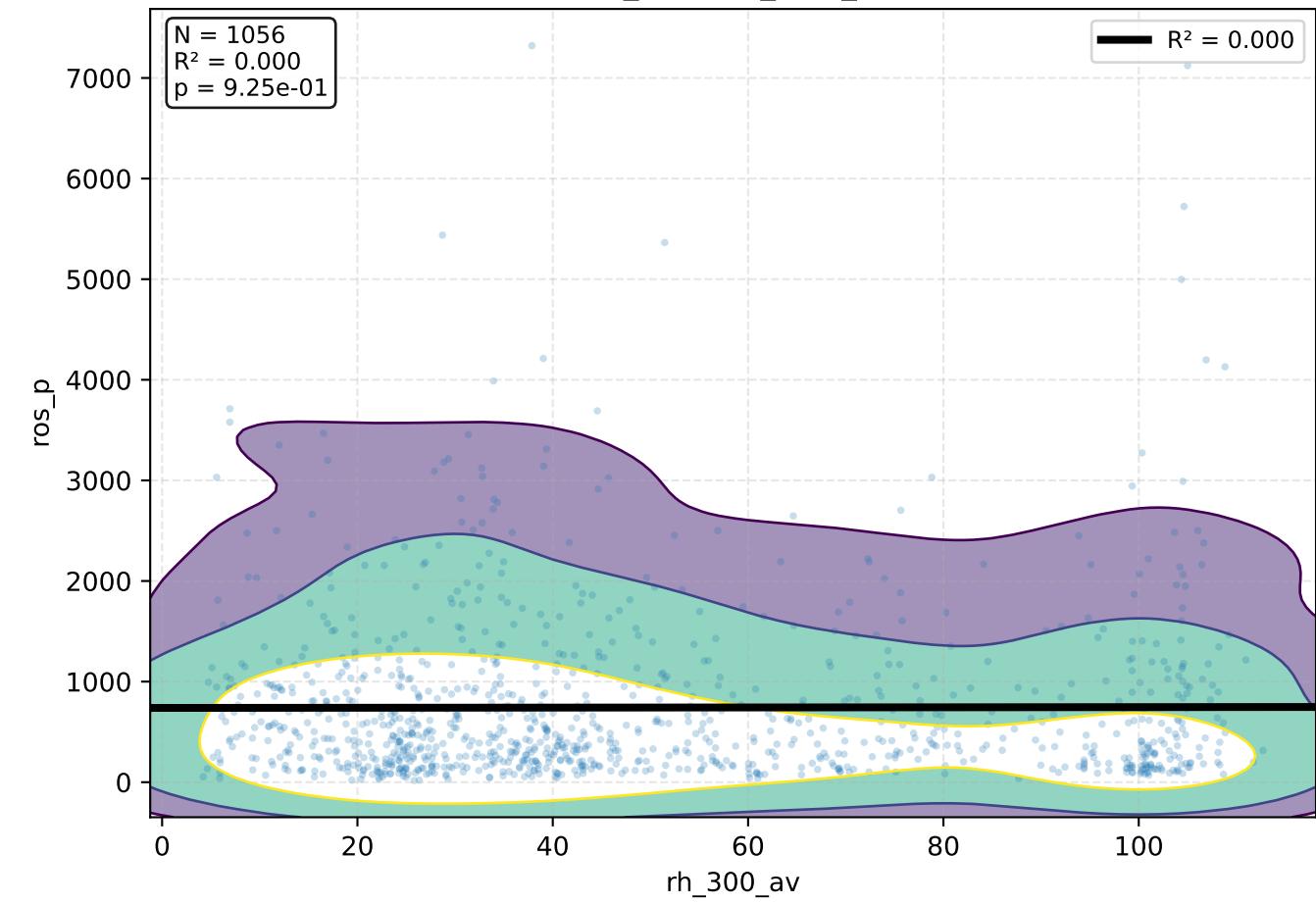


# rh\_500\_av – KDE Density + Regressão

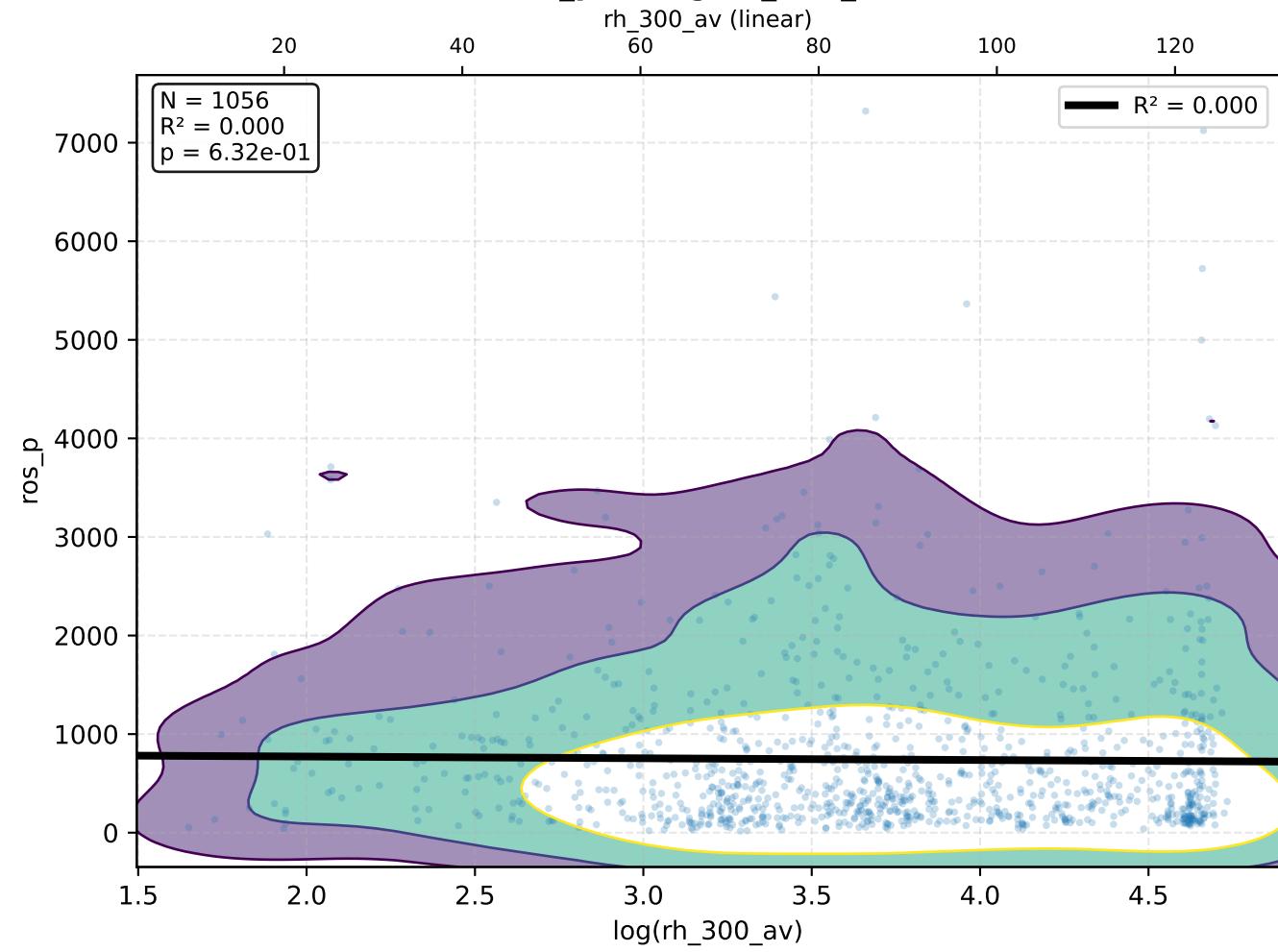


# rh\_300\_av – KDE Density + Regressão

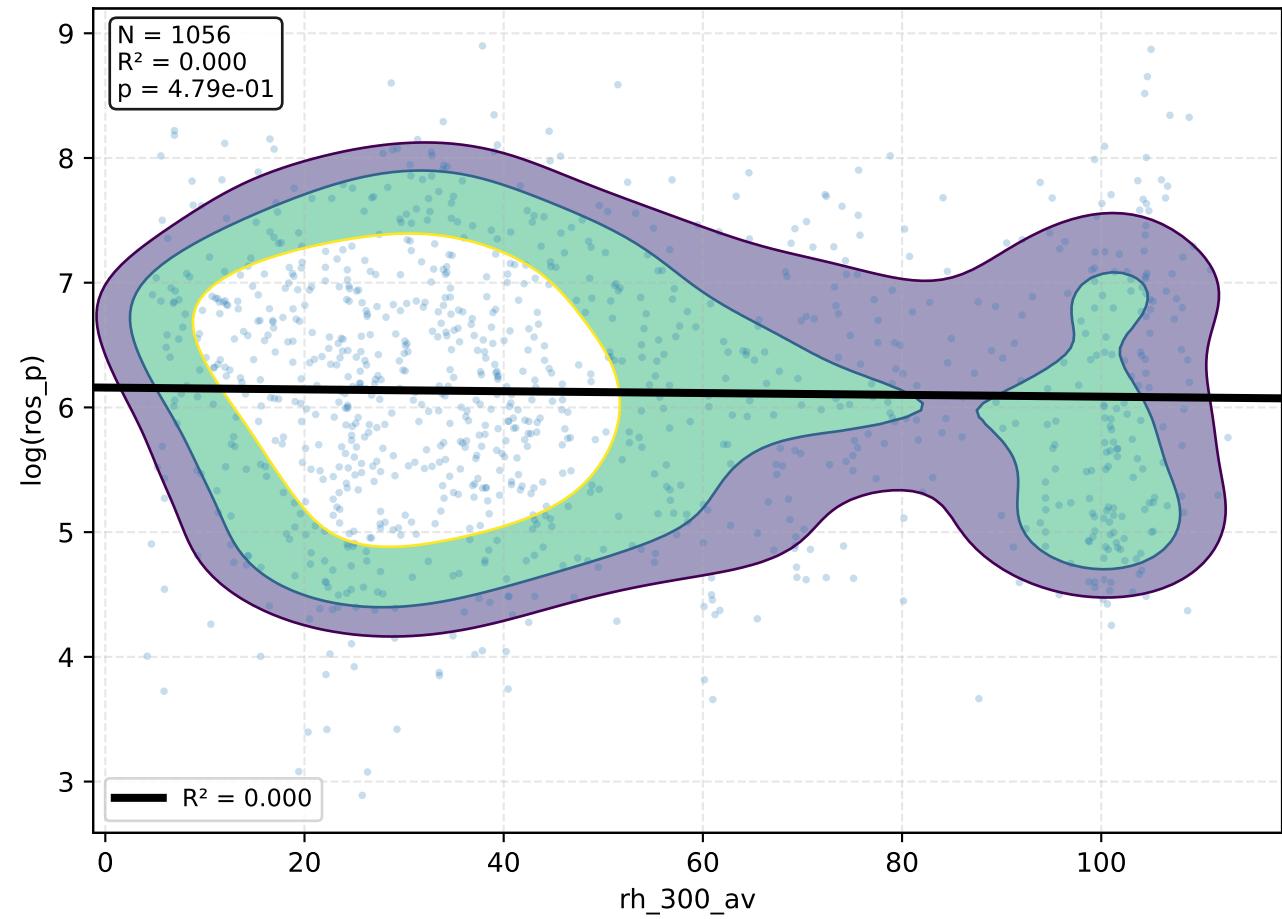
**ros\_p vs rh\_300\_av**



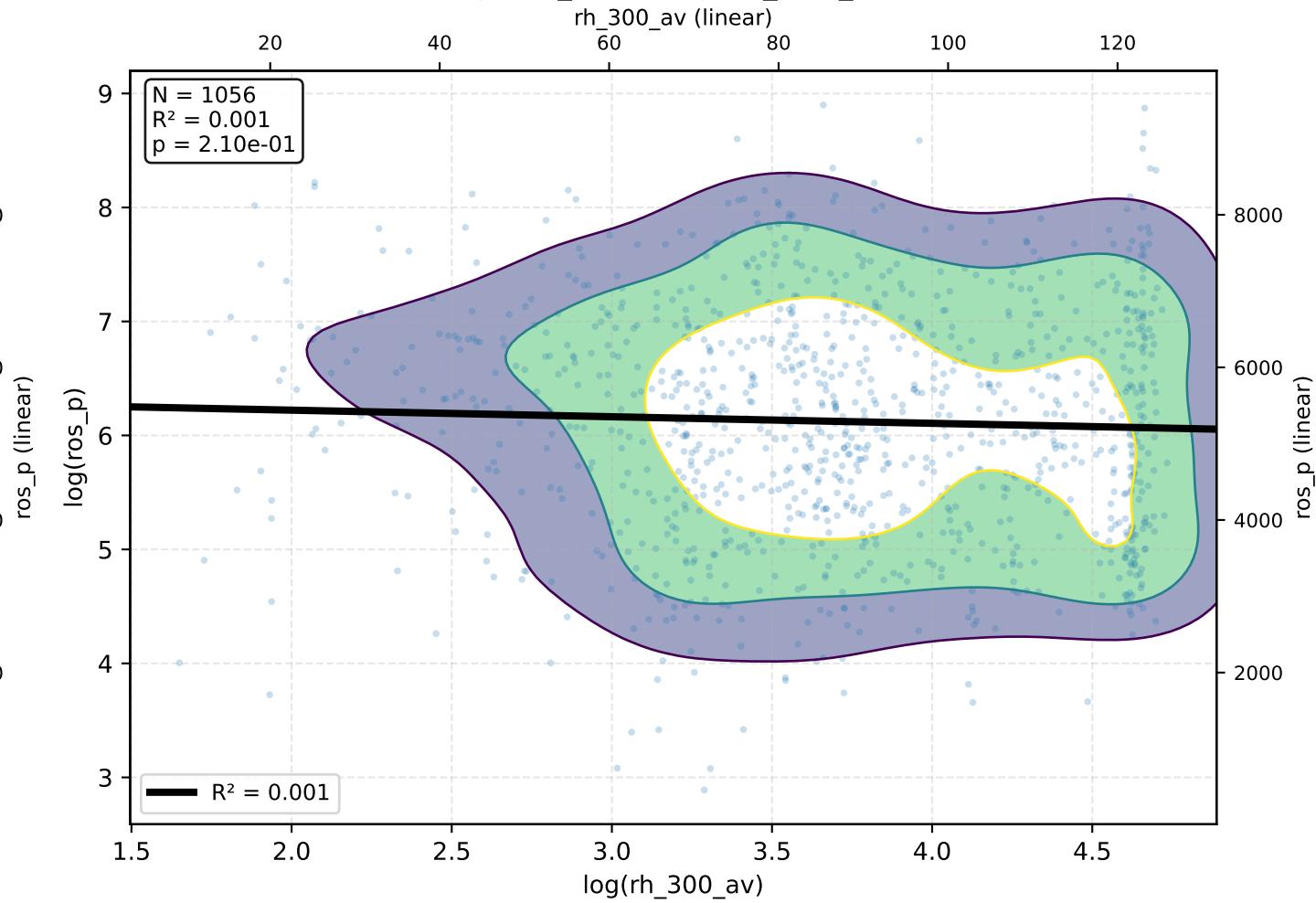
**ros\_p vs log(rh\_300\_av)**



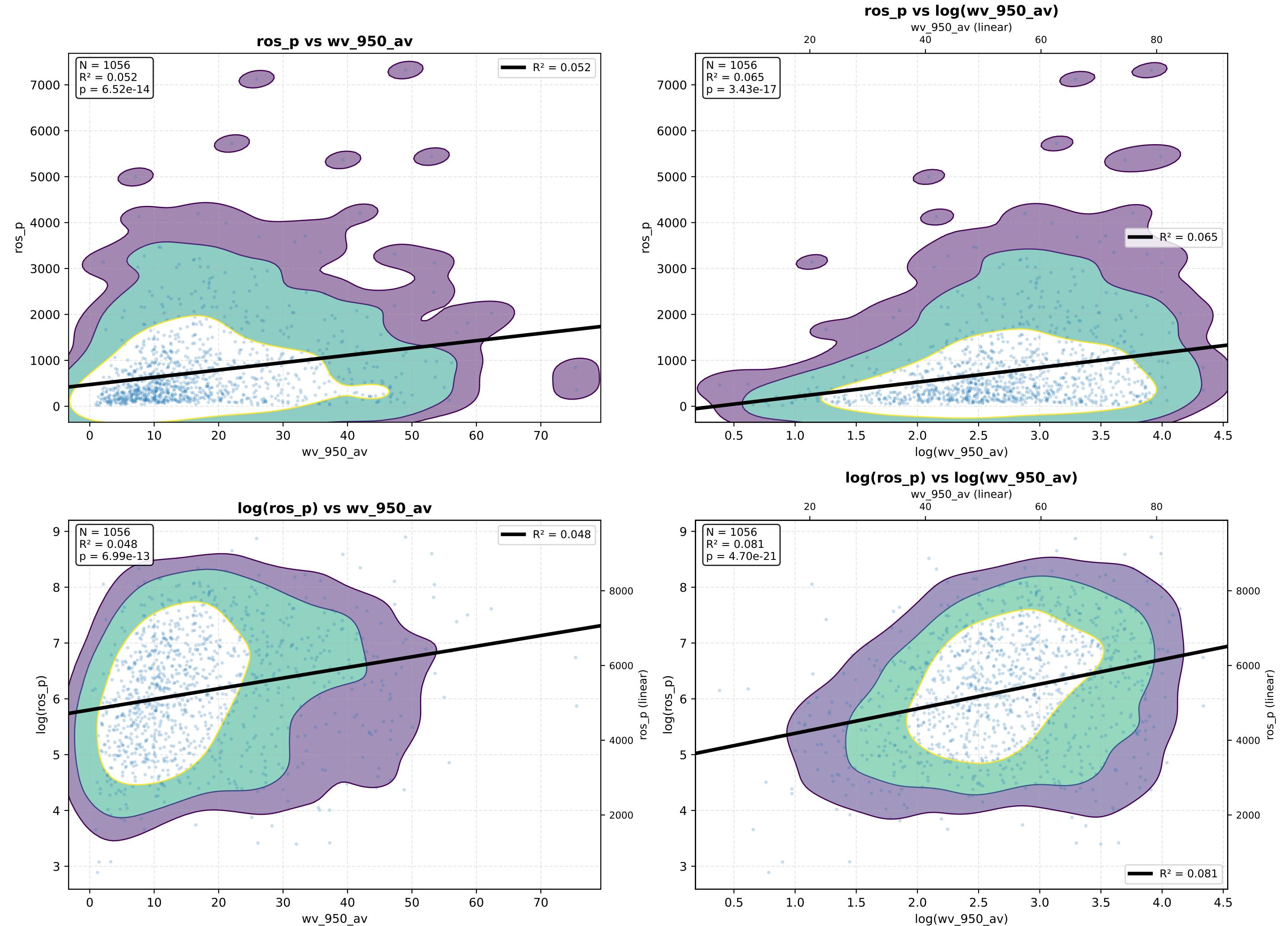
**log(ros\_p) vs rh\_300\_av**



**log(ros\_p) vs log(rh\_300\_av)**

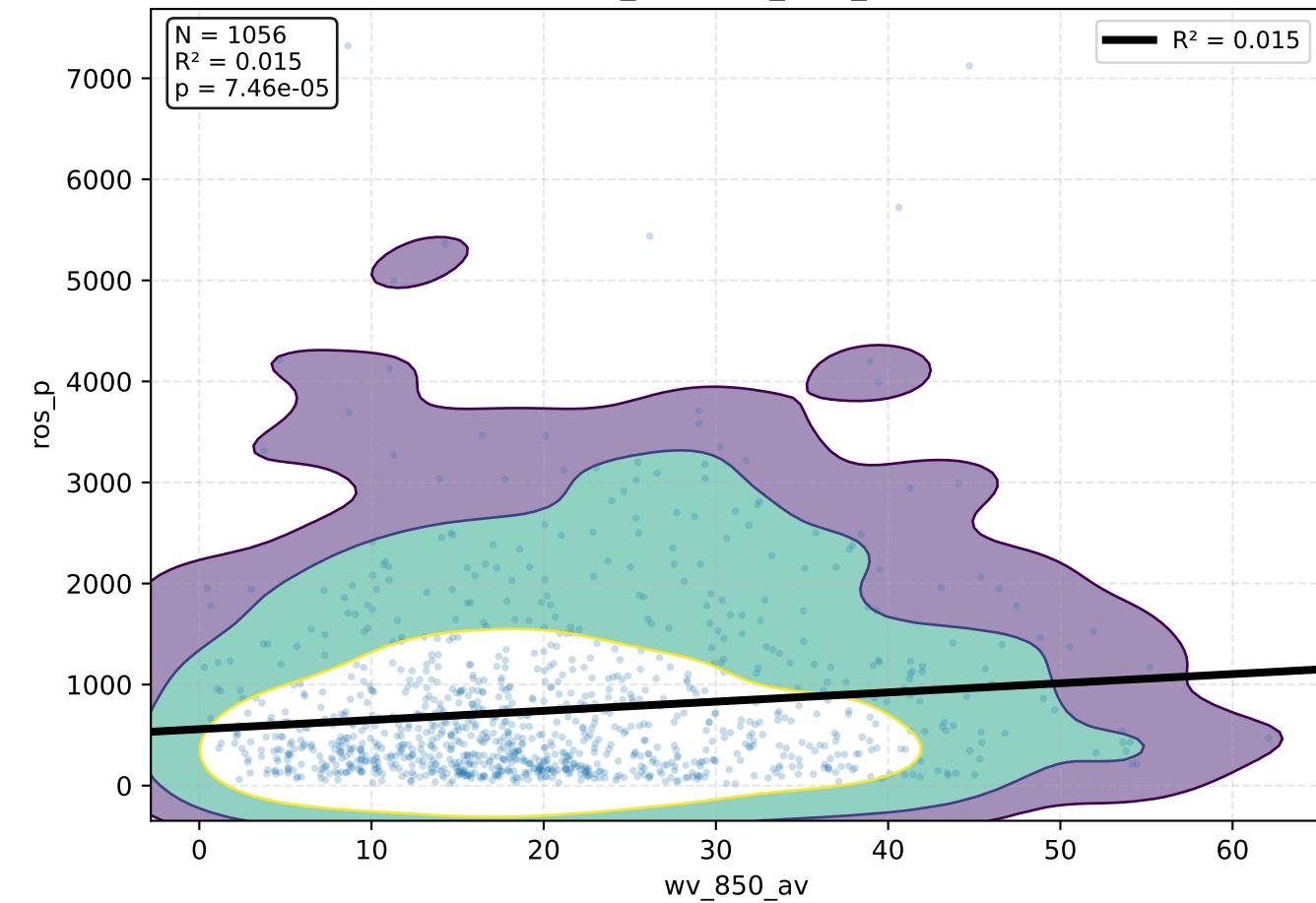


# wv\_950\_av - KDE Density + Regressão

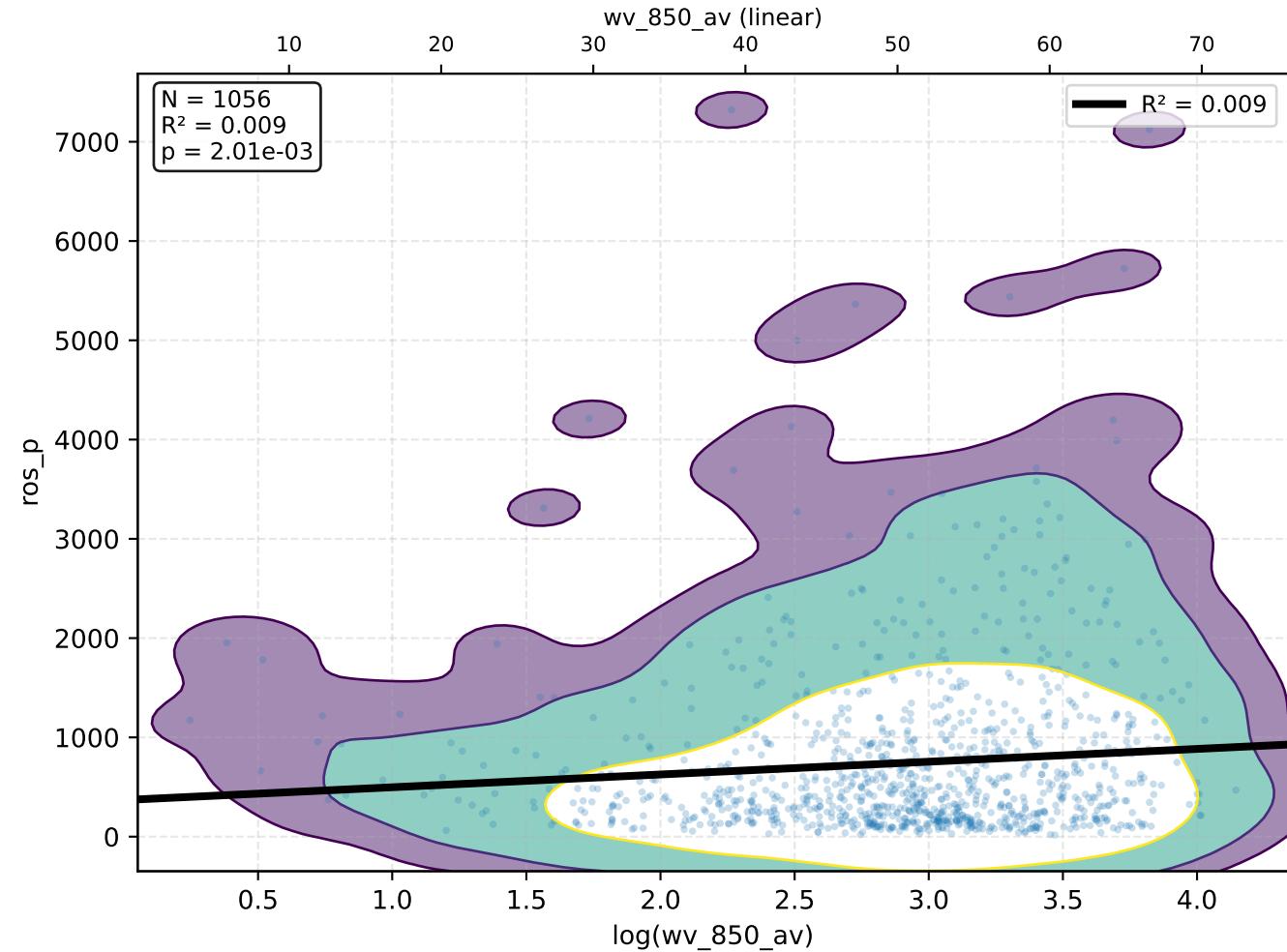


# wv\_850\_av - KDE Density + Regressão

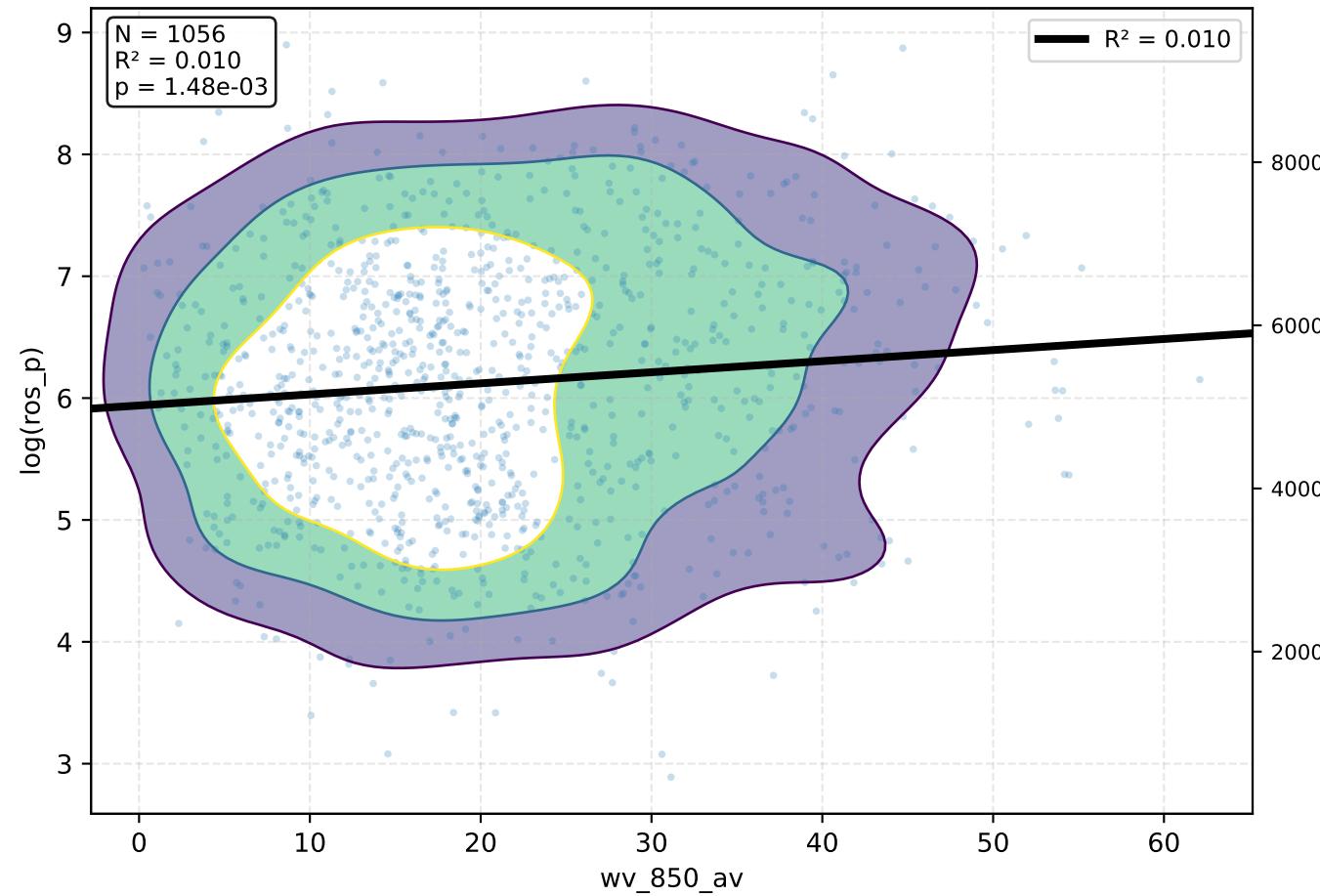
**ros\_p vs wv\_850\_av**



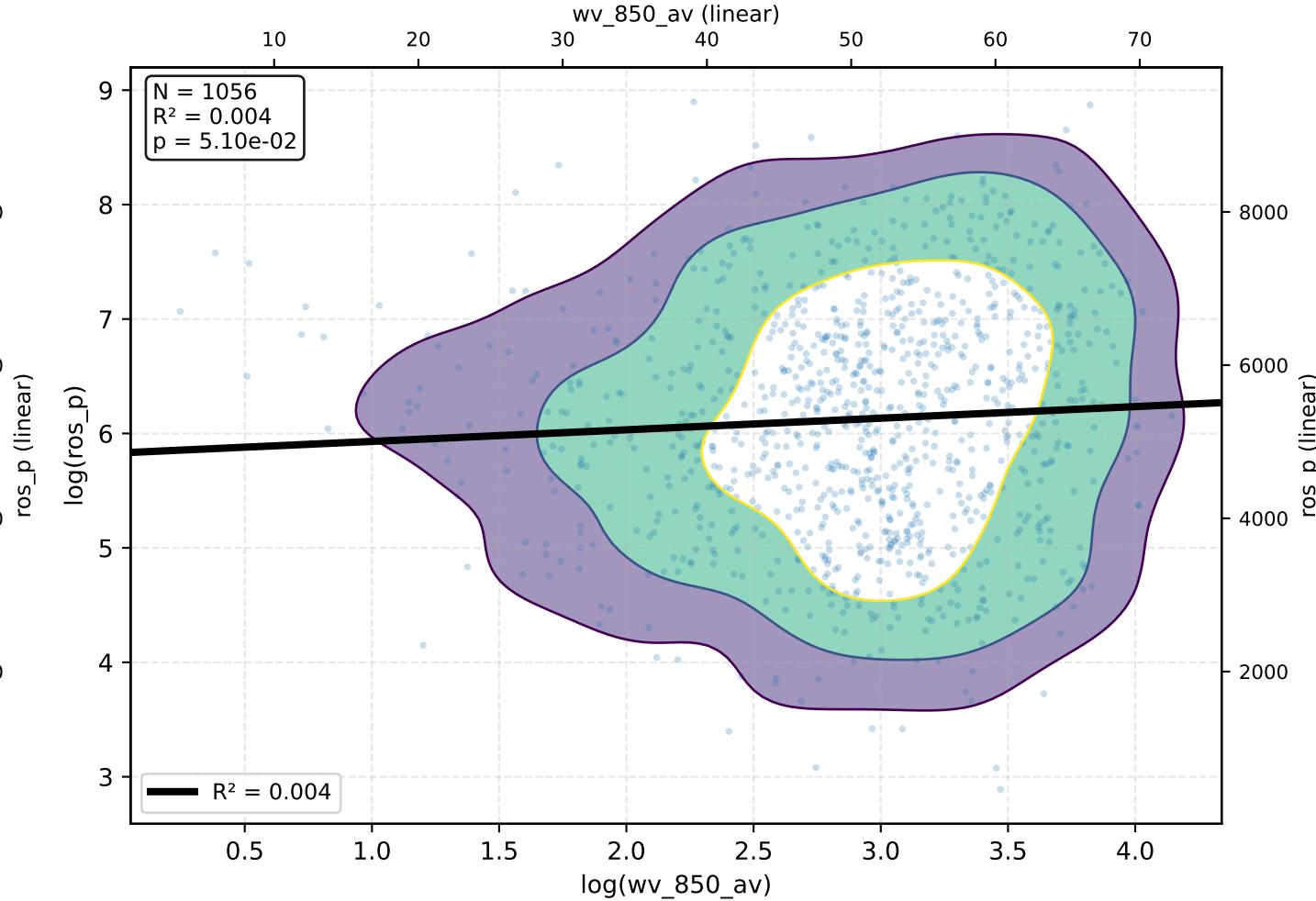
**ros\_p vs log(wv\_850\_av)**



**log(ros\_p) vs wv\_850\_av**

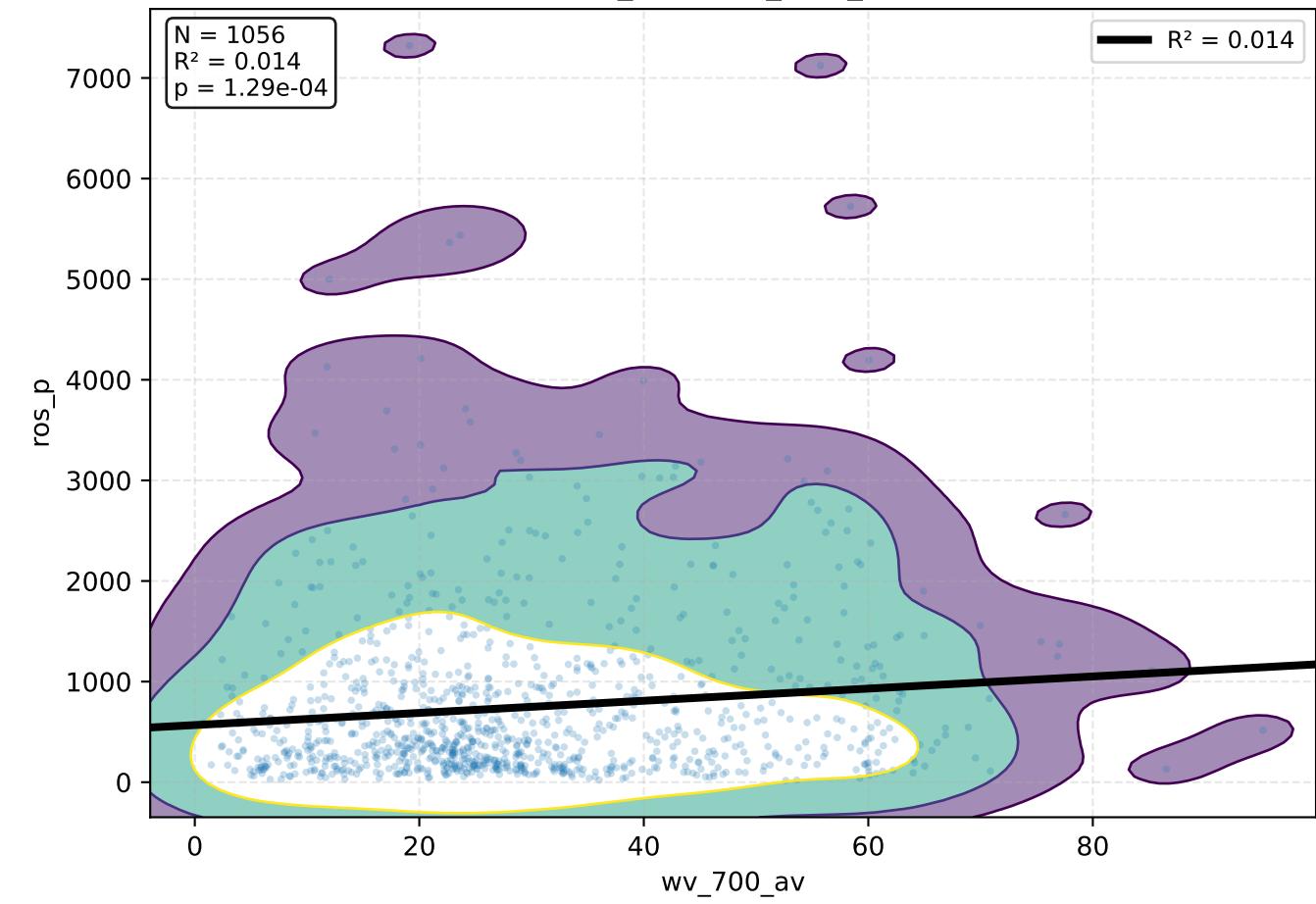


**log(ros\_p) vs log(wv\_850\_av)**

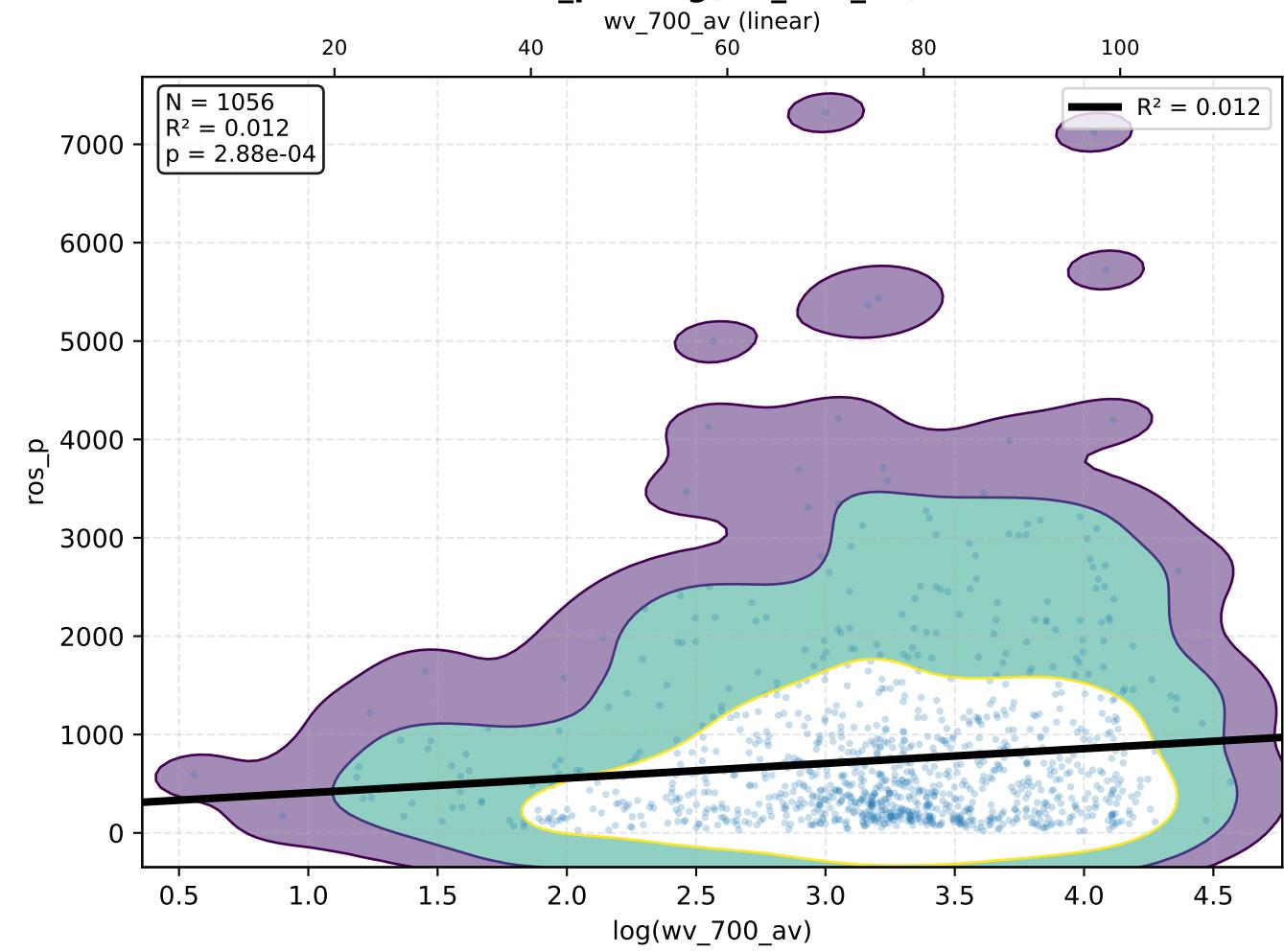


# wv\_700\_av - KDE Density + Regressão

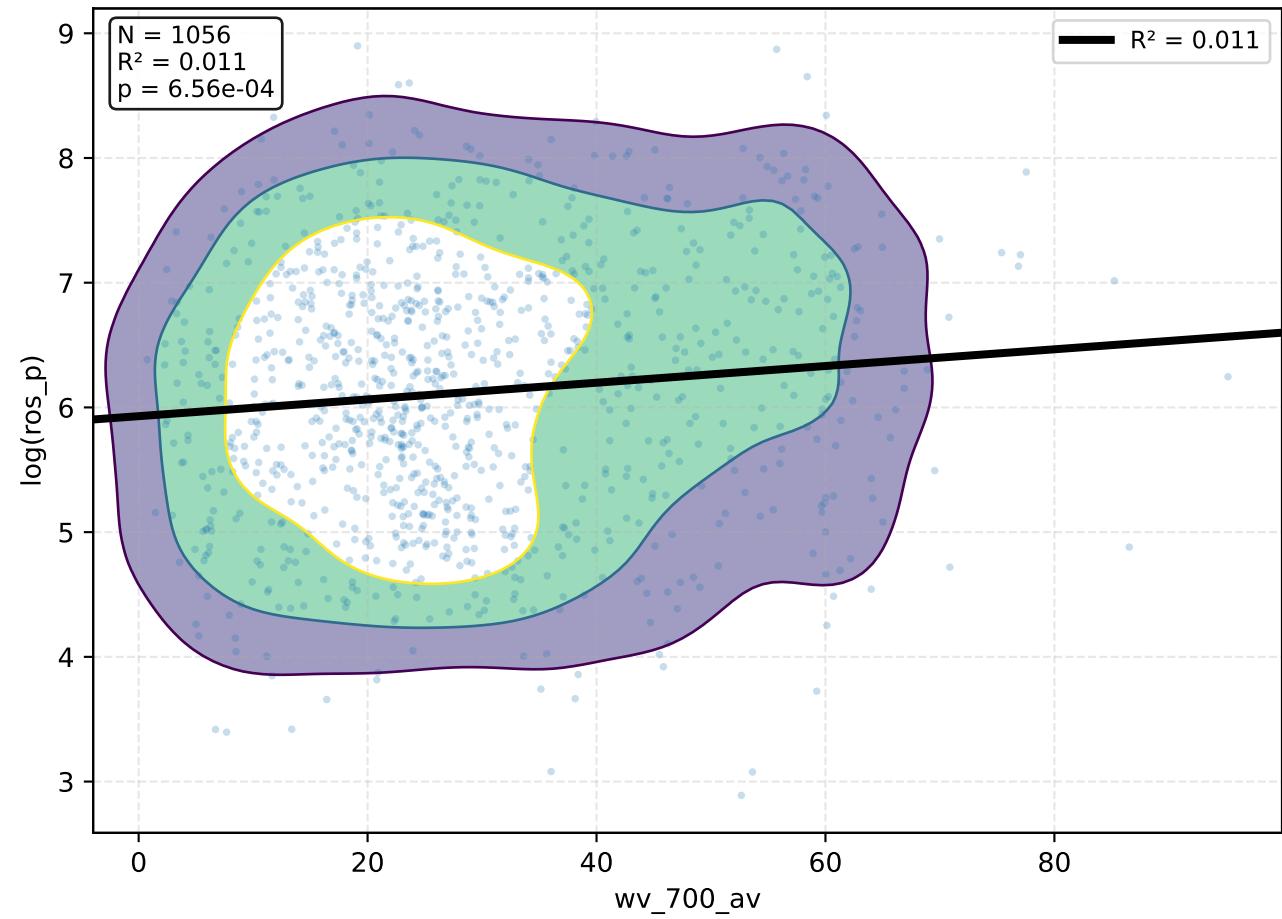
**ros\_p vs wv\_700\_av**



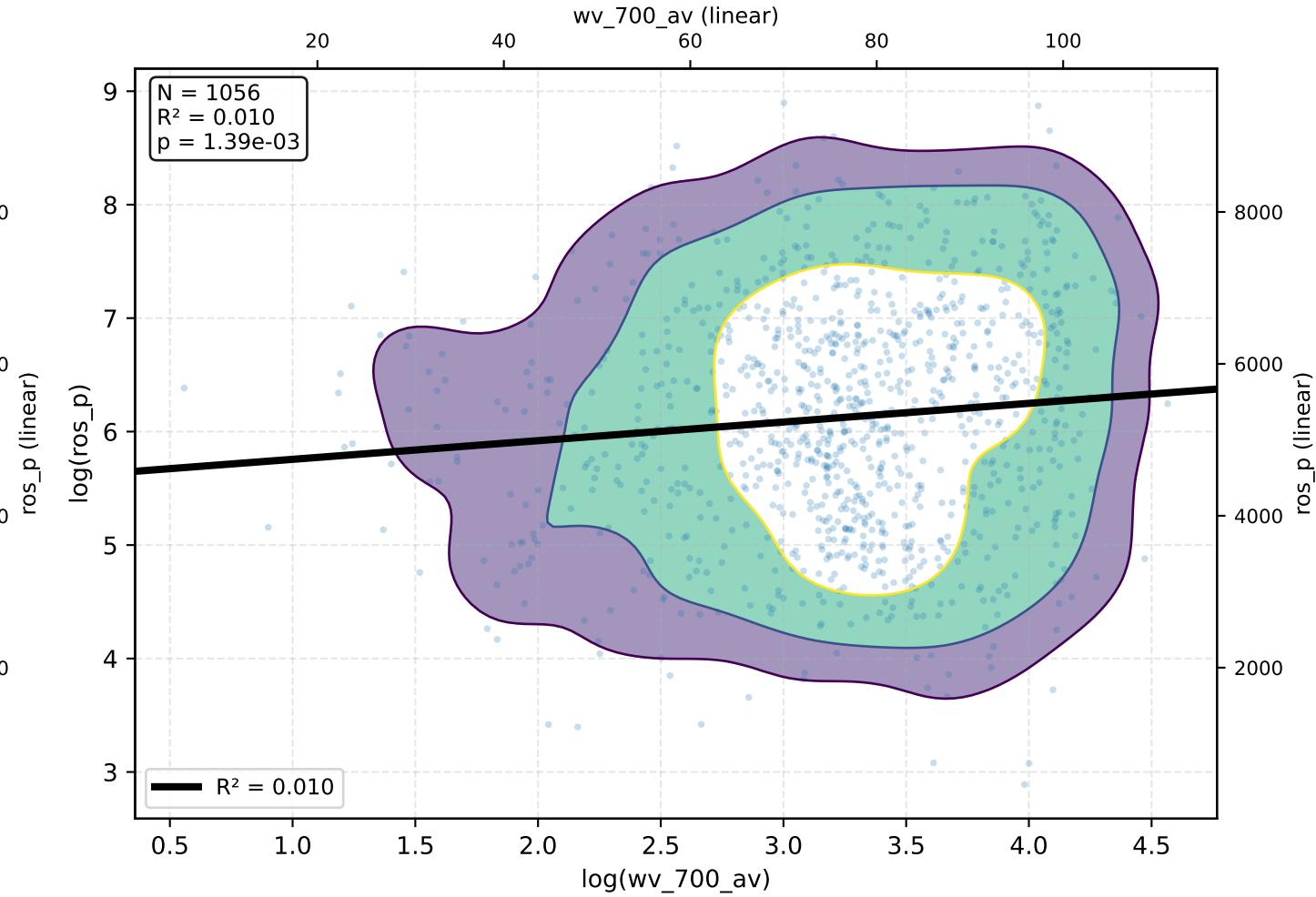
**ros\_p vs log(wv\_700\_av)**



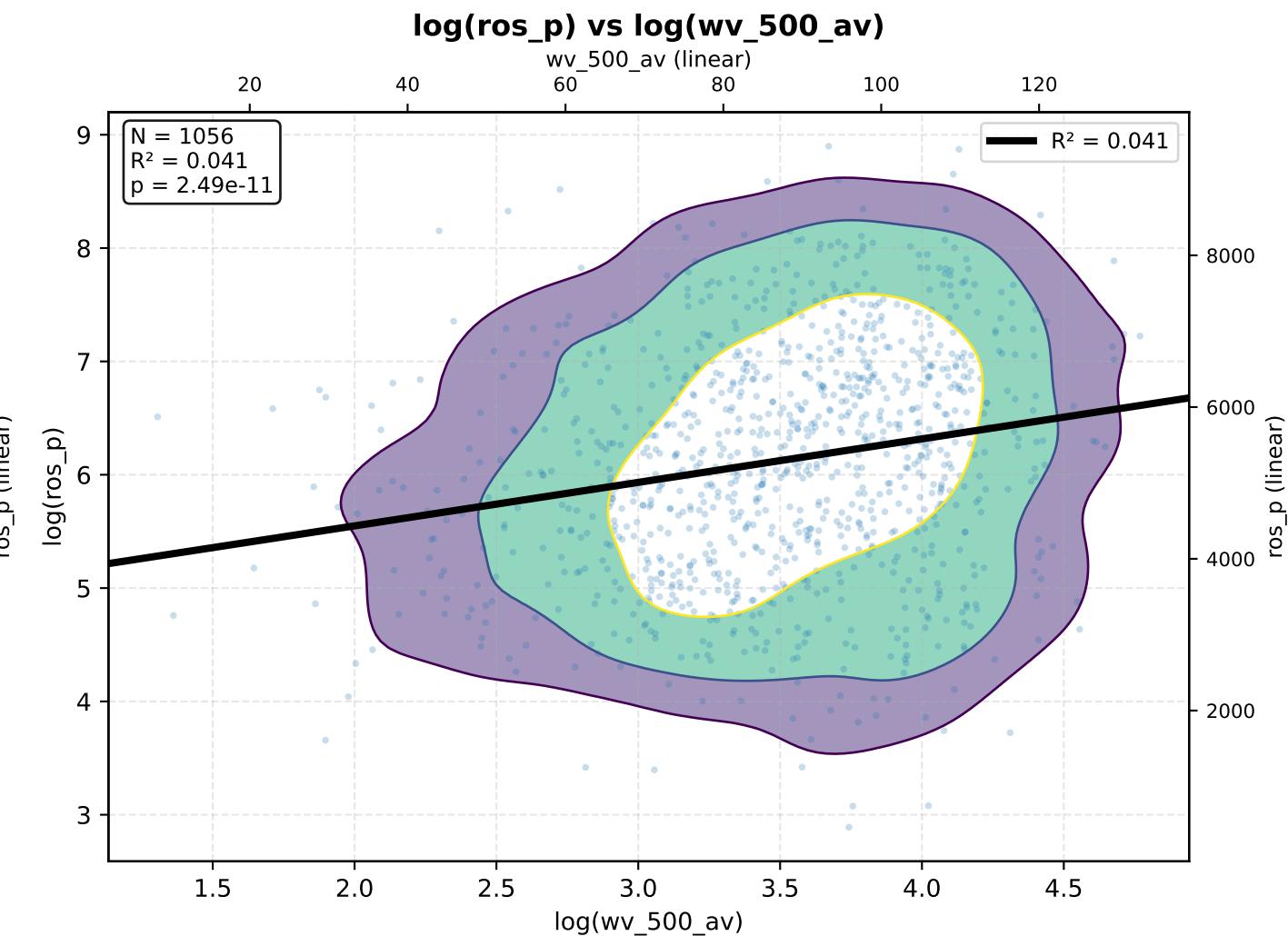
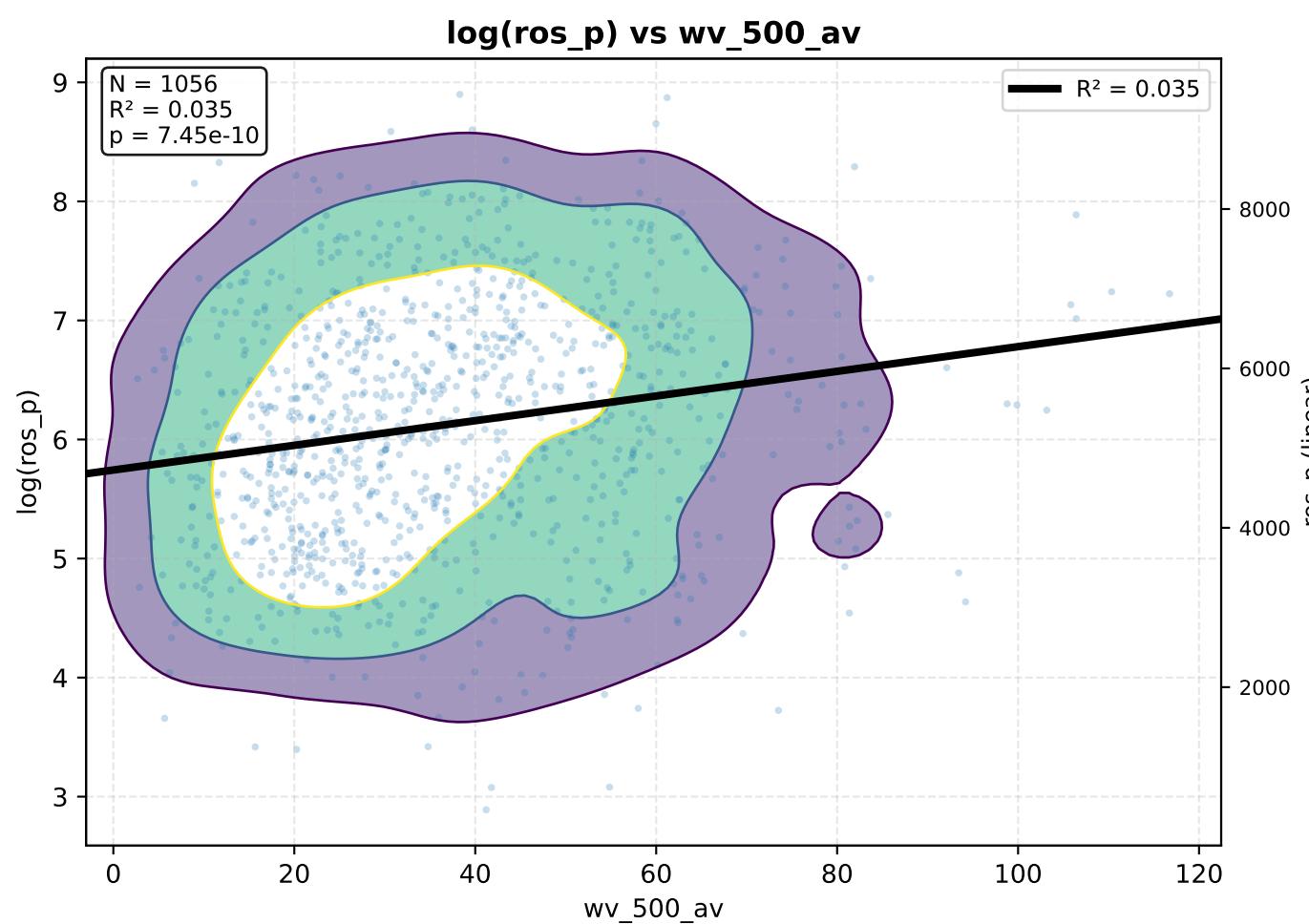
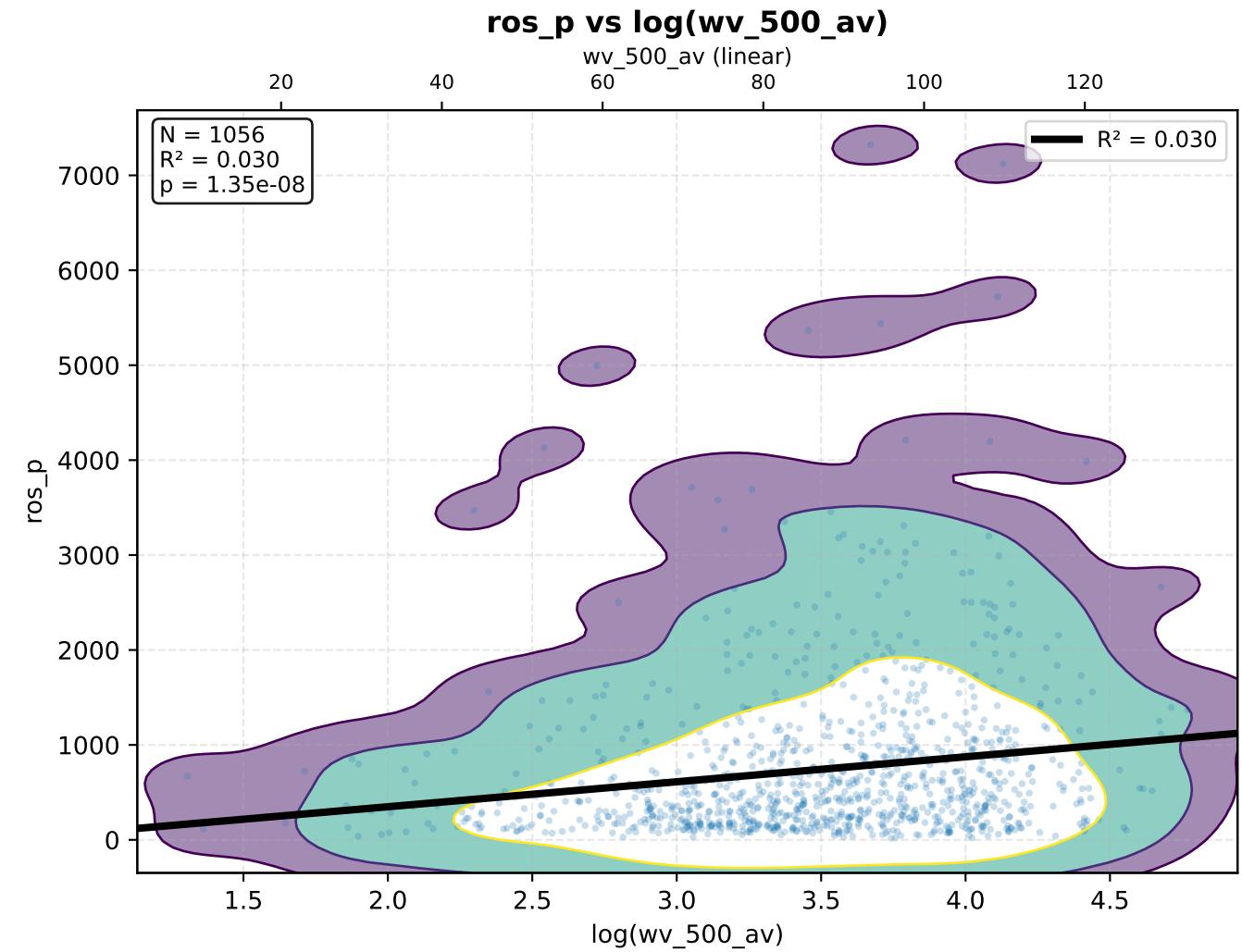
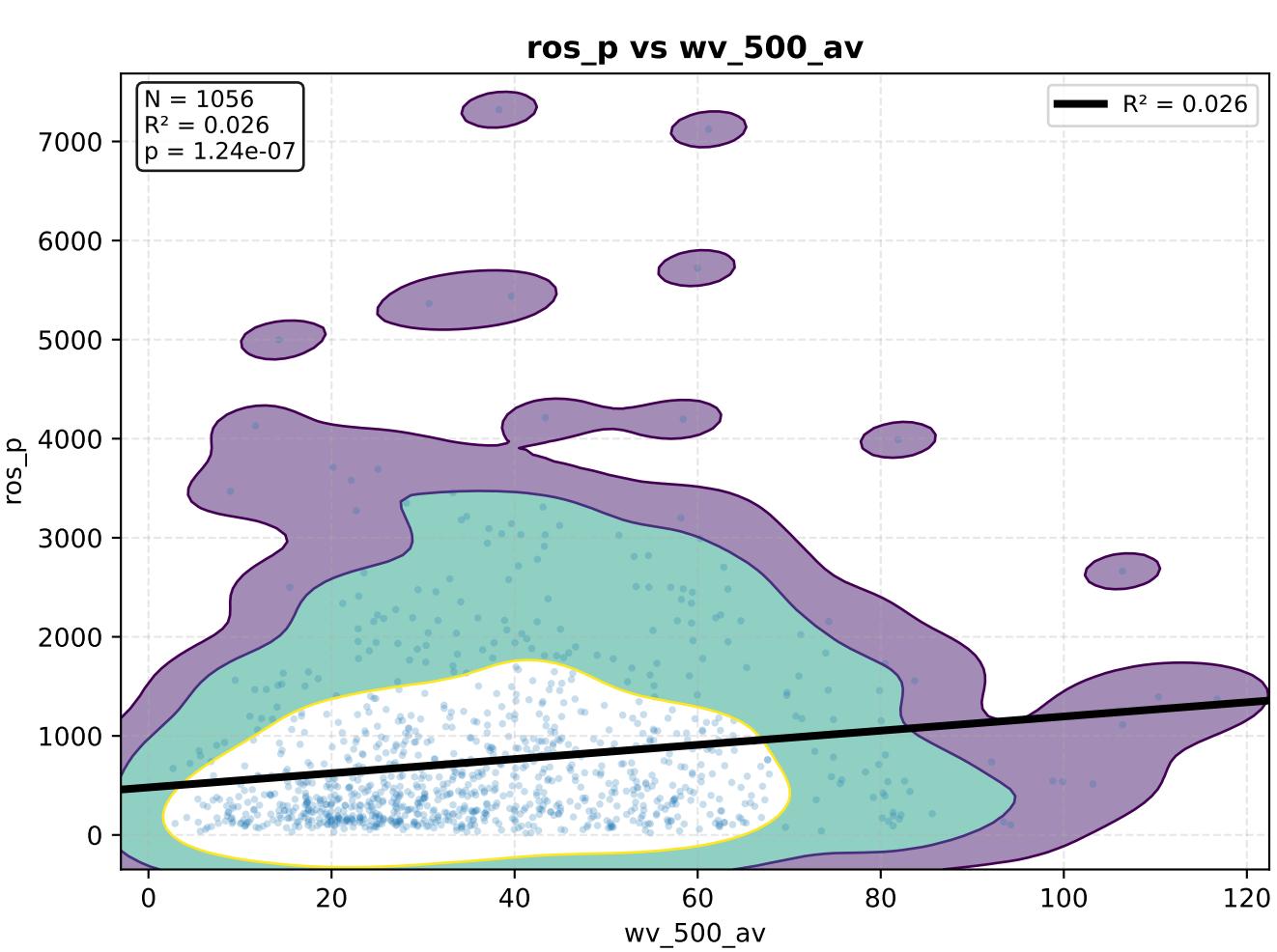
**log(ros\_p) vs wv\_700\_av**



**log(ros\_p) vs log(wv\_700\_av)**

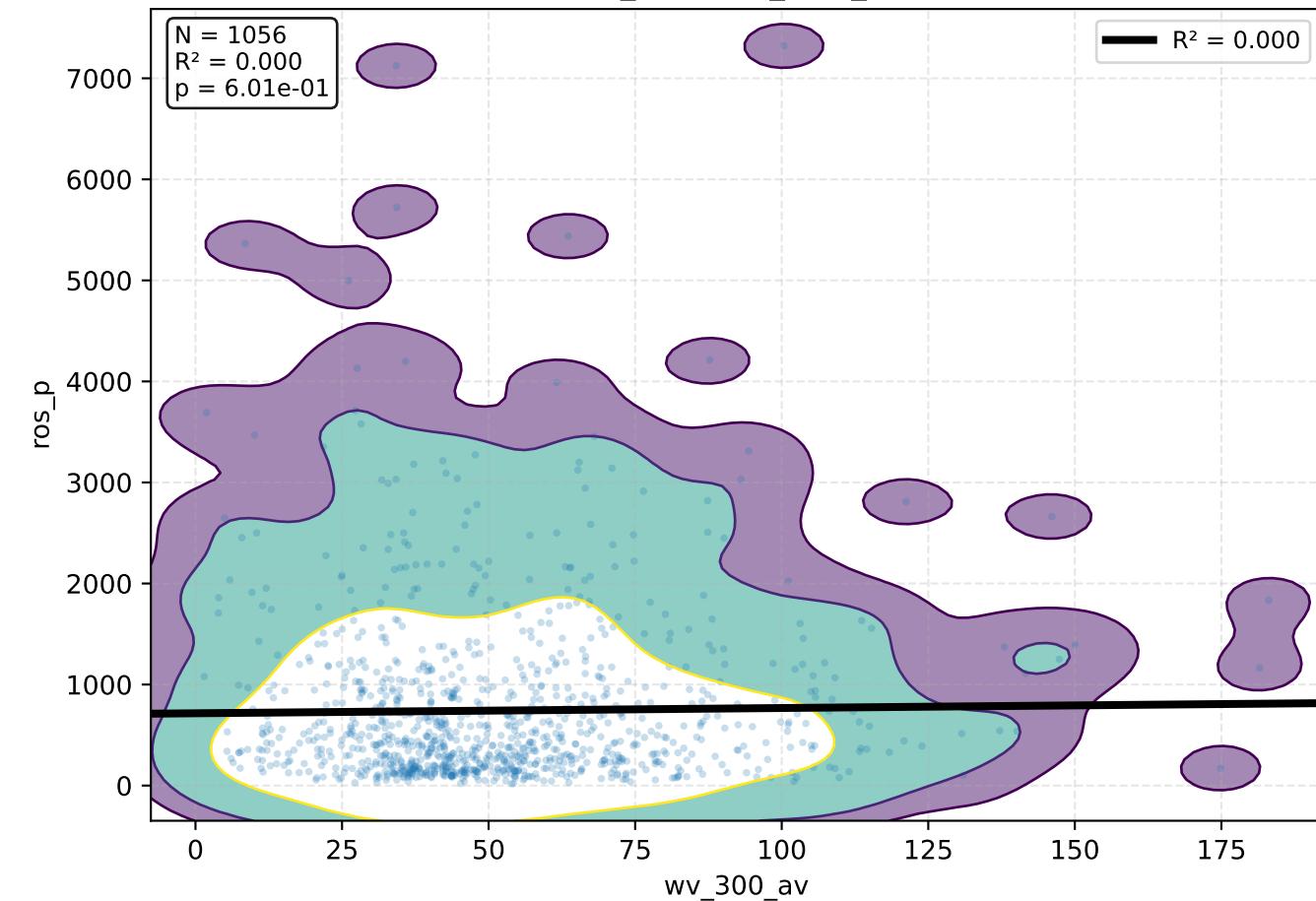


# wv\_500\_av - KDE Density + Regressão

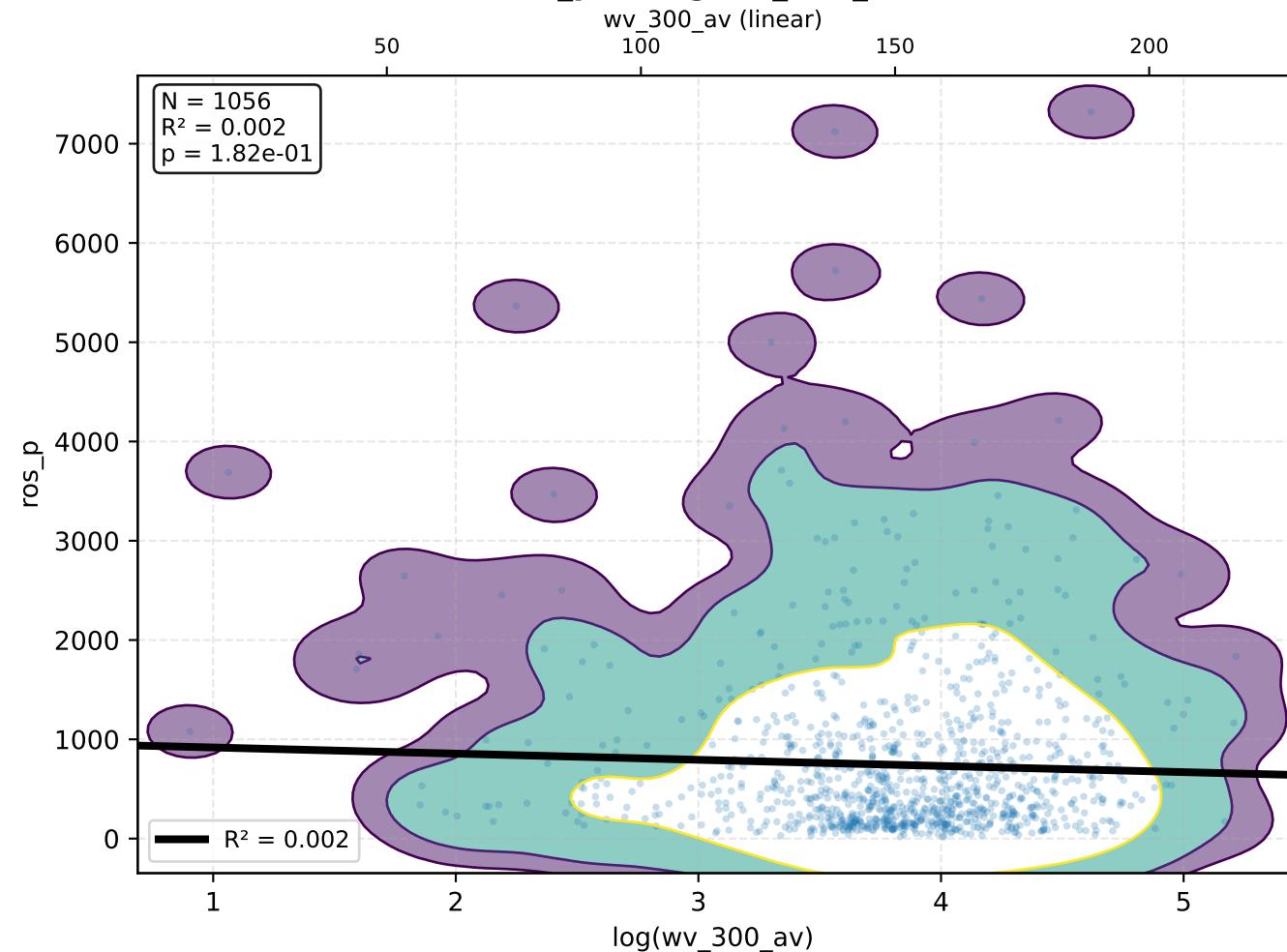


# wv\_300\_av - KDE Density + Regressão

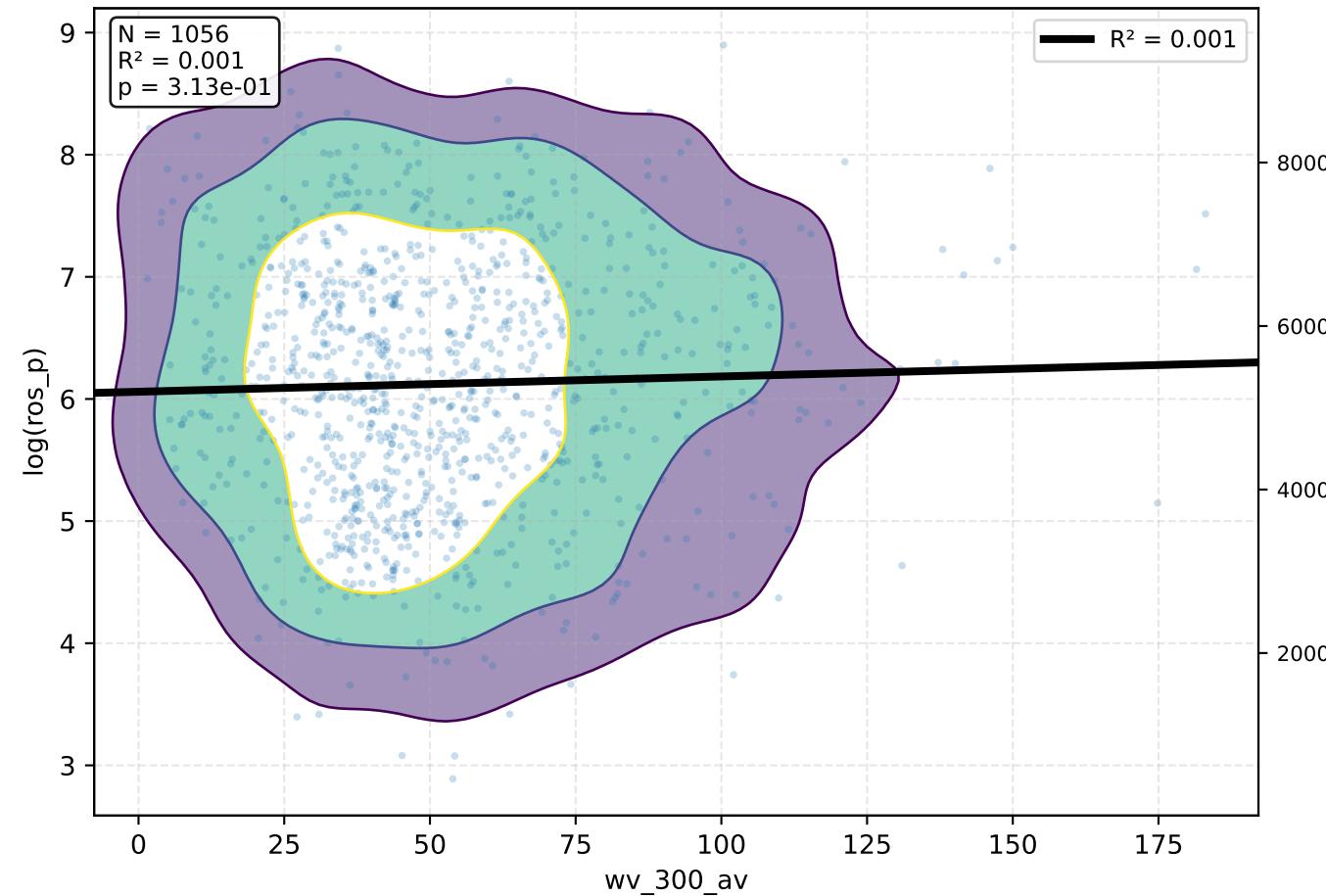
**ros\_p vs wv\_300\_av**



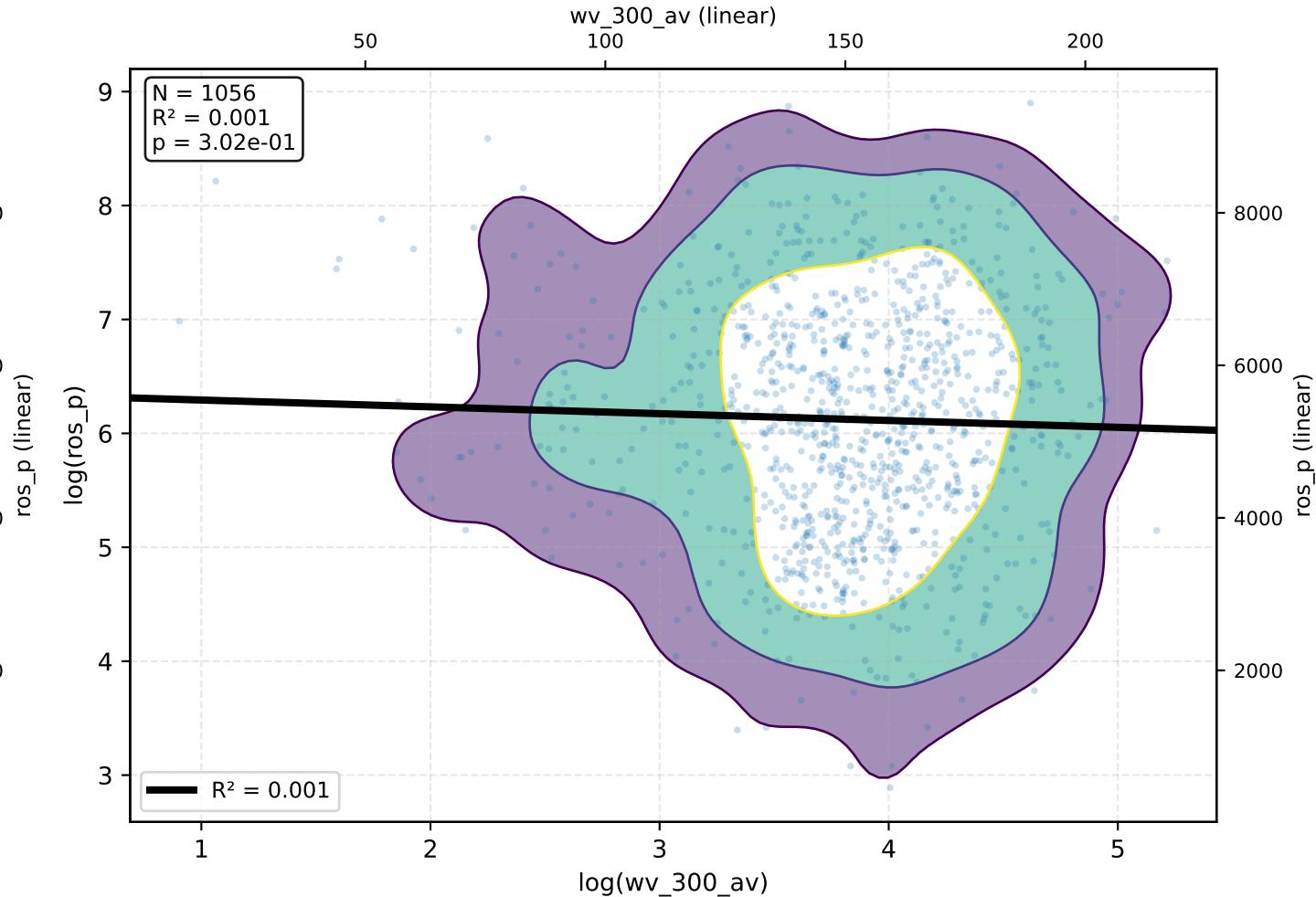
**ros\_p vs log(wv\_300\_av)**



**log(ros\_p) vs wv\_300\_av**

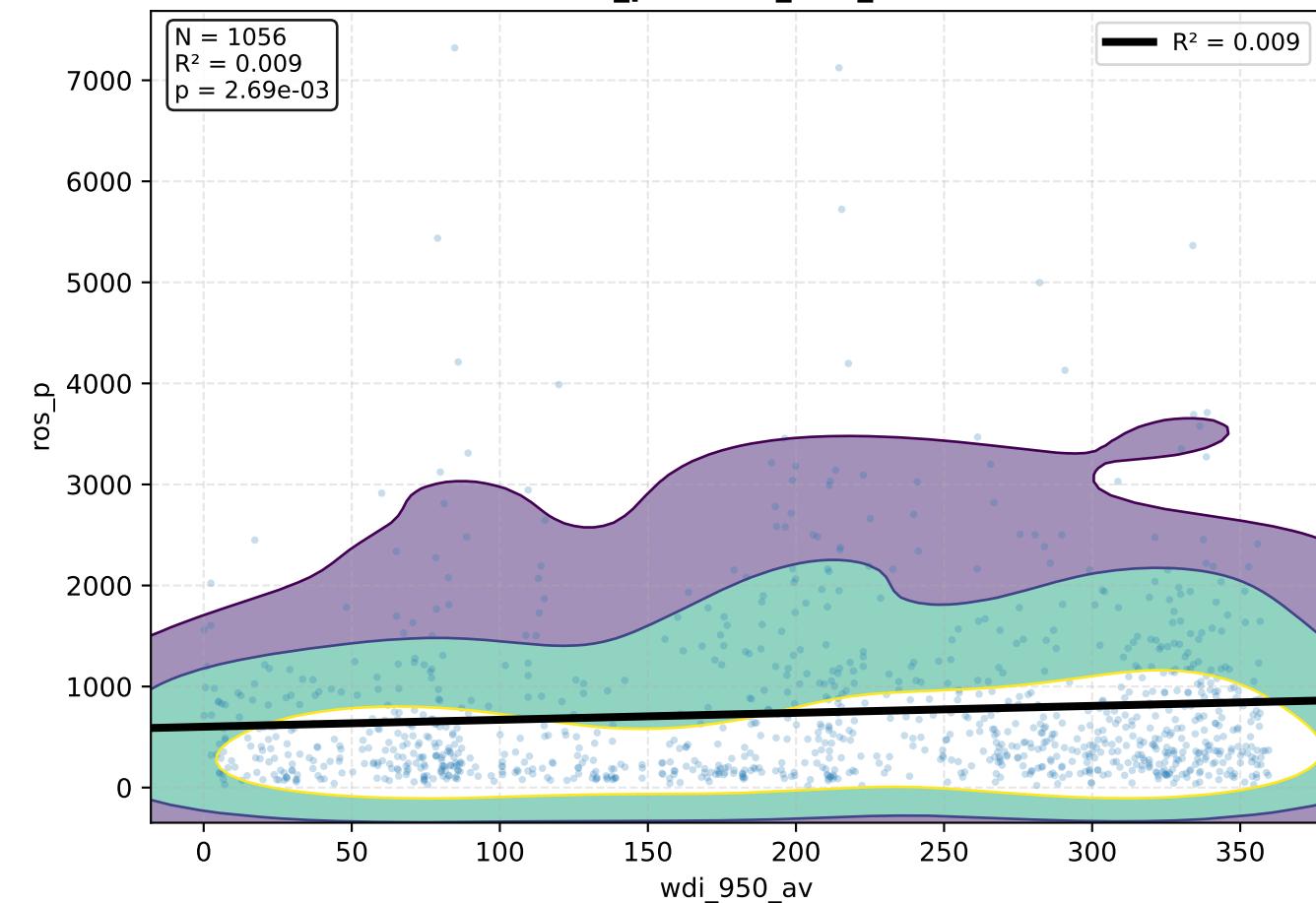


**log(ros\_p) vs log(wv\_300\_av)**

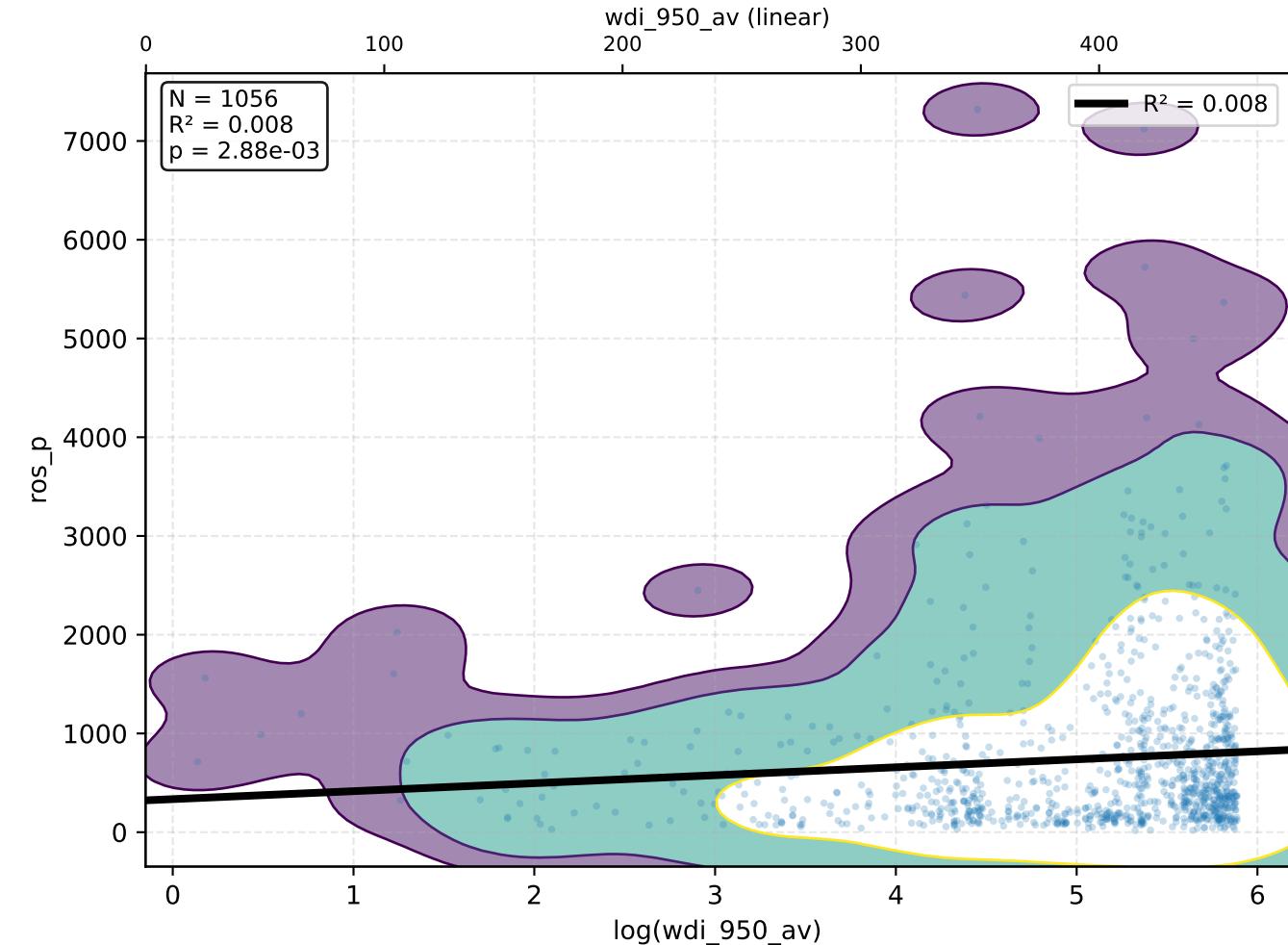


# wdi\_950\_av - KDE Density + Regressão

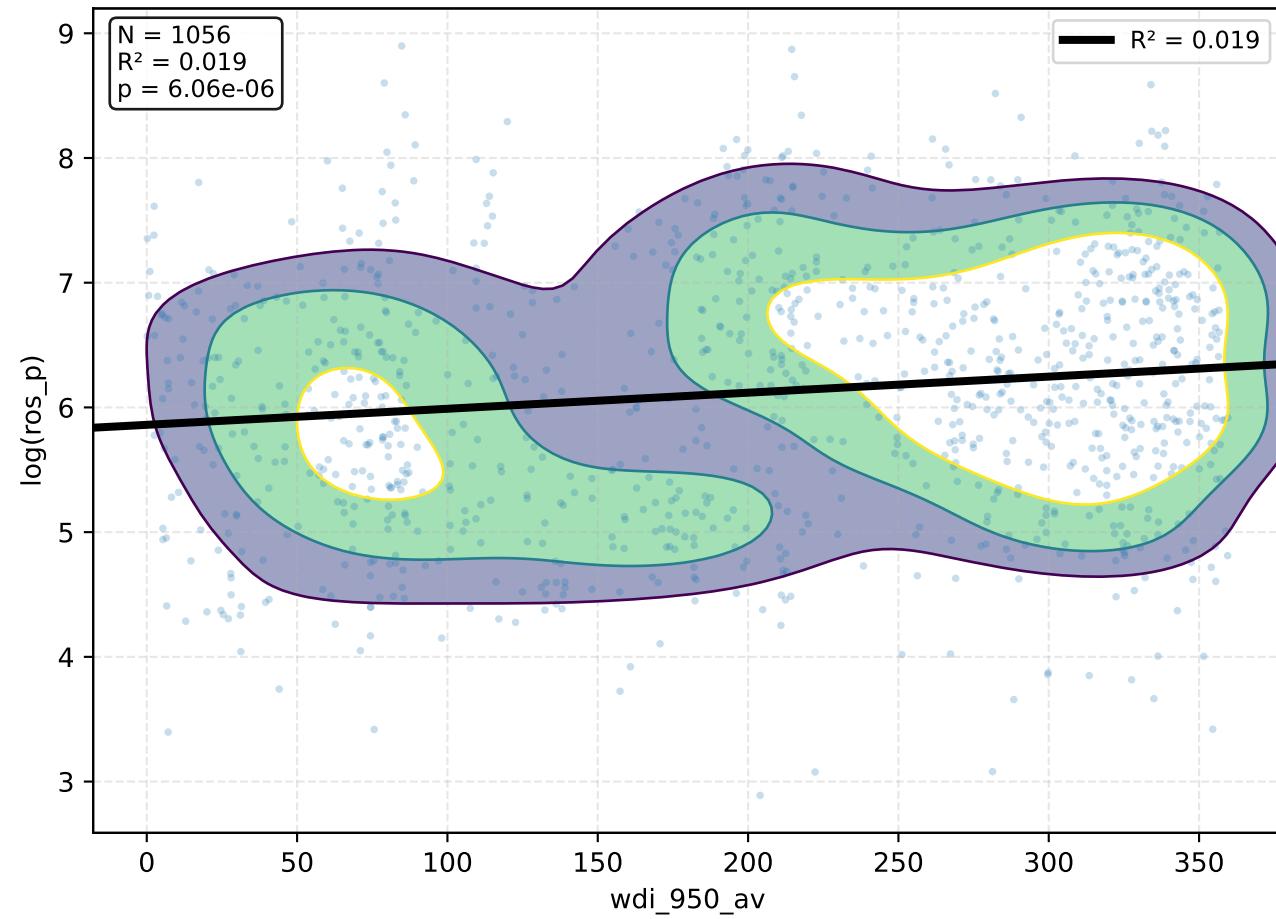
**ros\_p vs wdi\_950\_av**



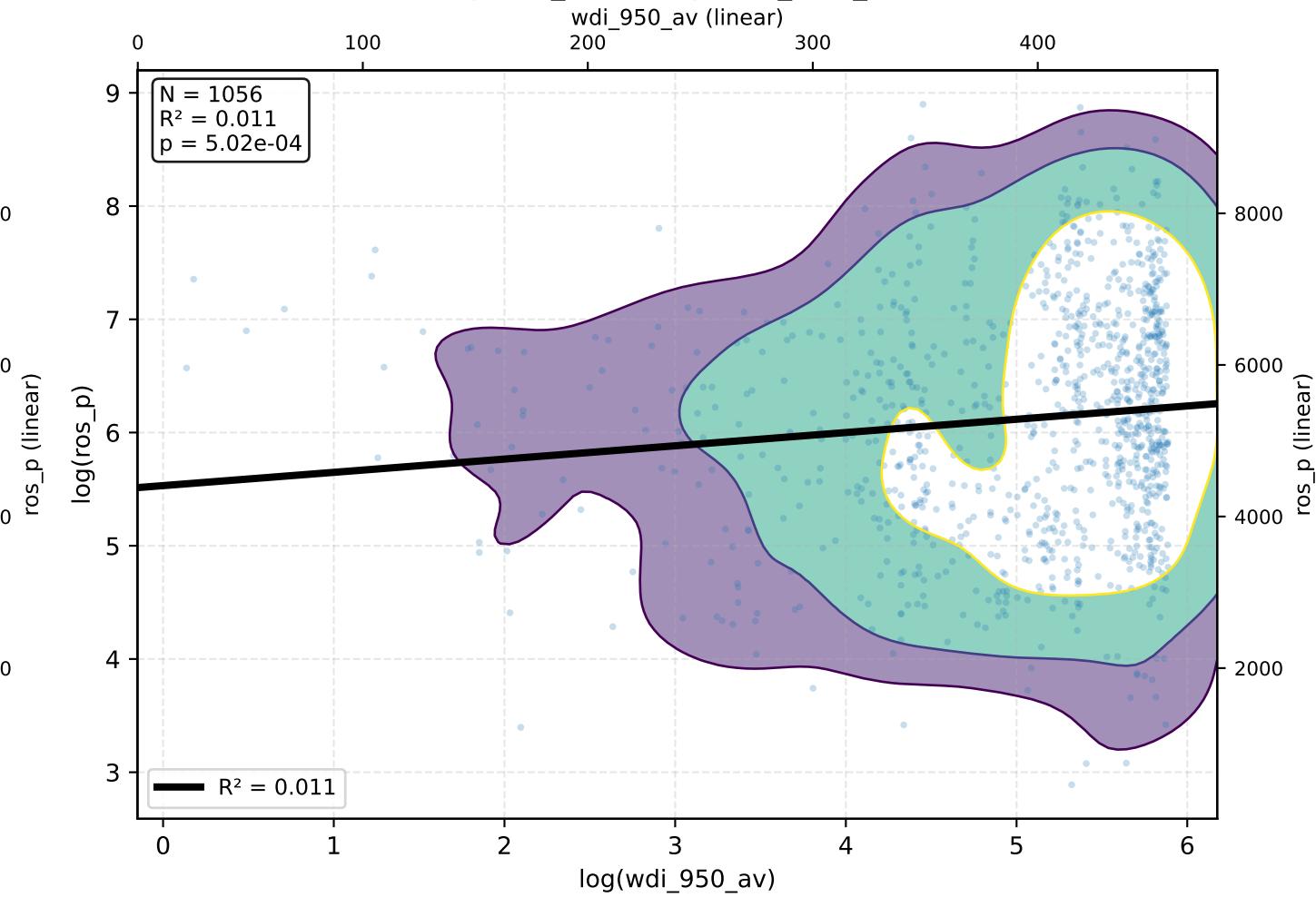
**ros\_p vs log(wdi\_950\_av)**



**log(ros\_p) vs wdi\_950\_av**

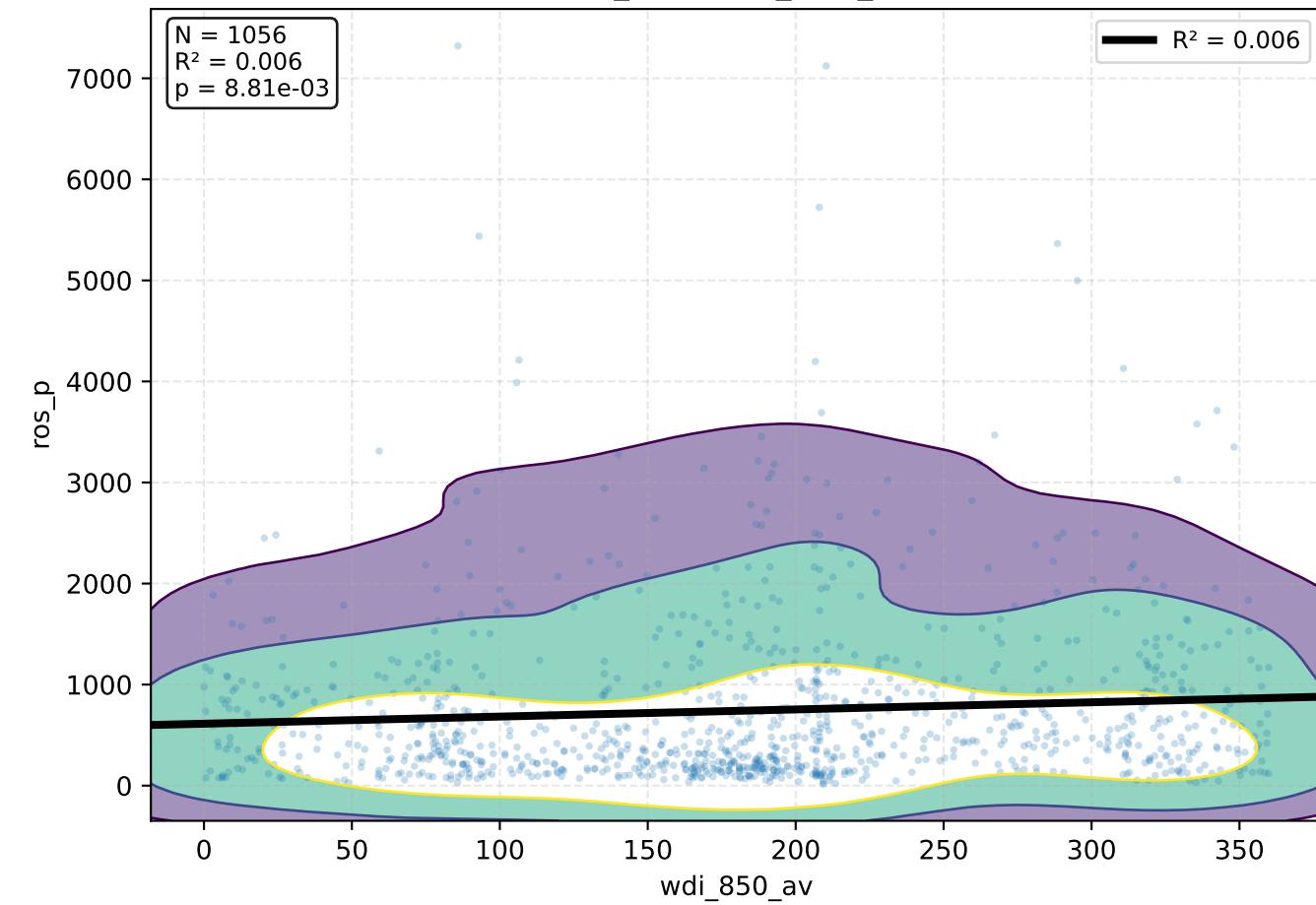


**log(ros\_p) vs log(wdi\_950\_av)**

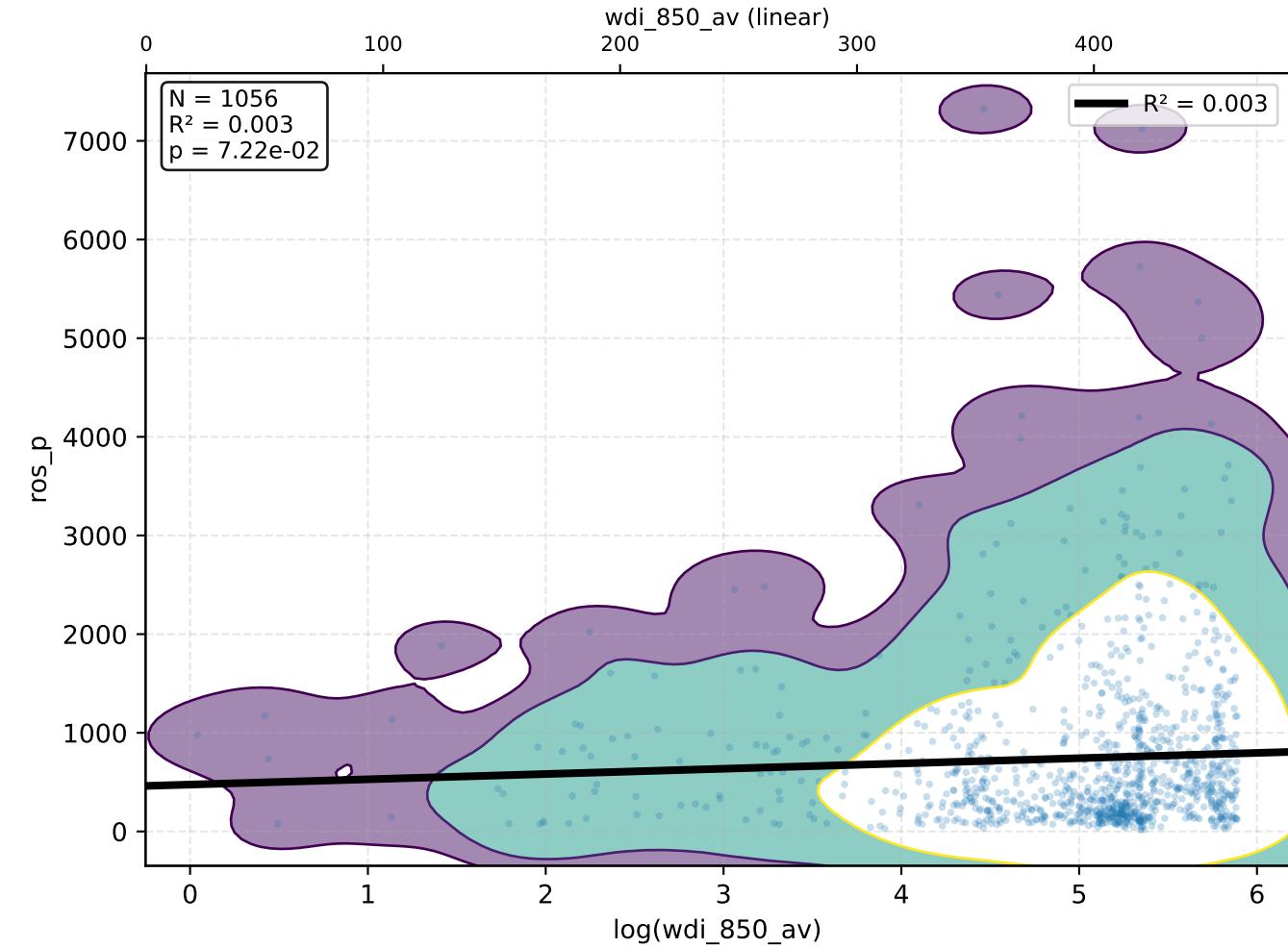


# wdi\_850\_av - KDE Density + Regressão

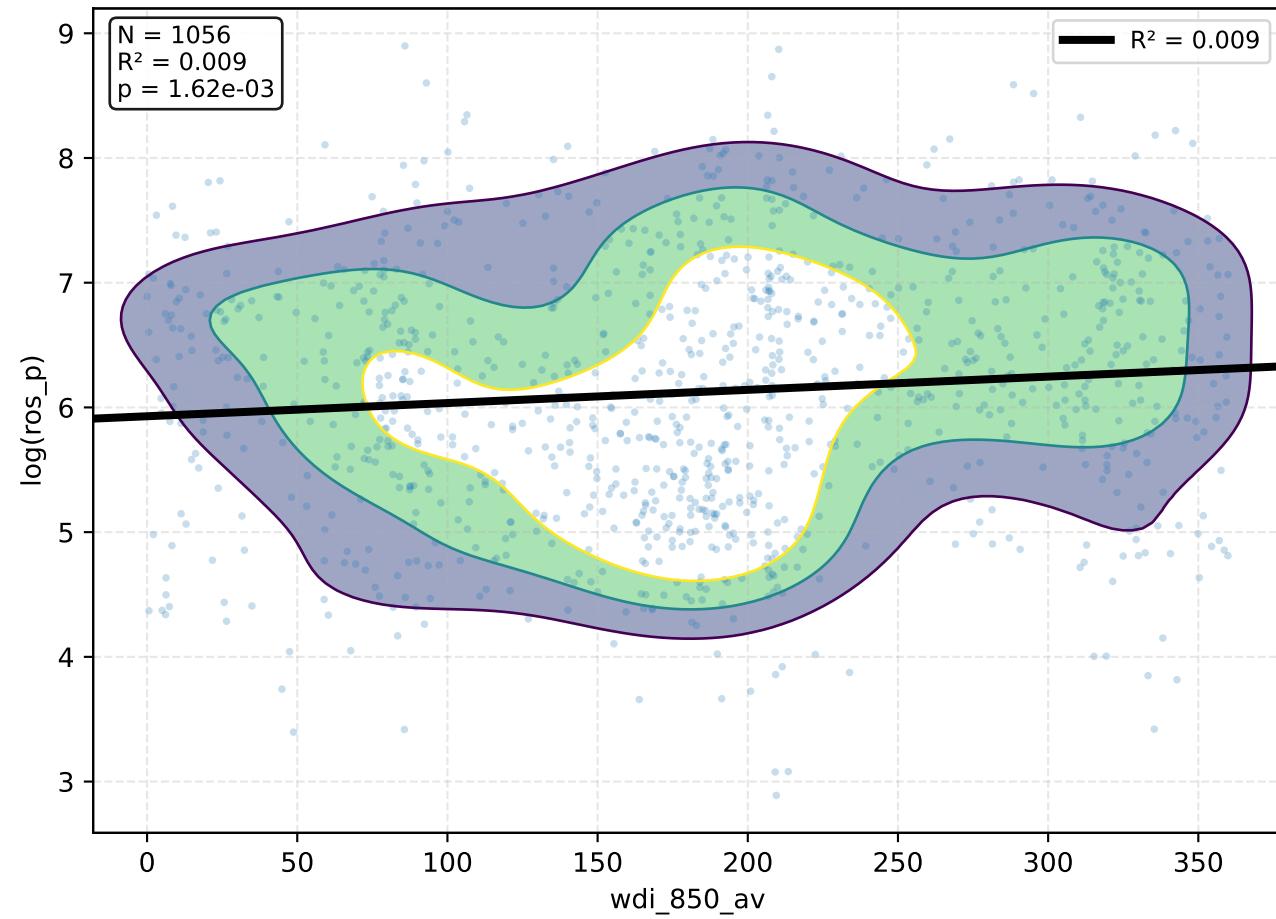
**ros\_p vs wdi\_850\_av**



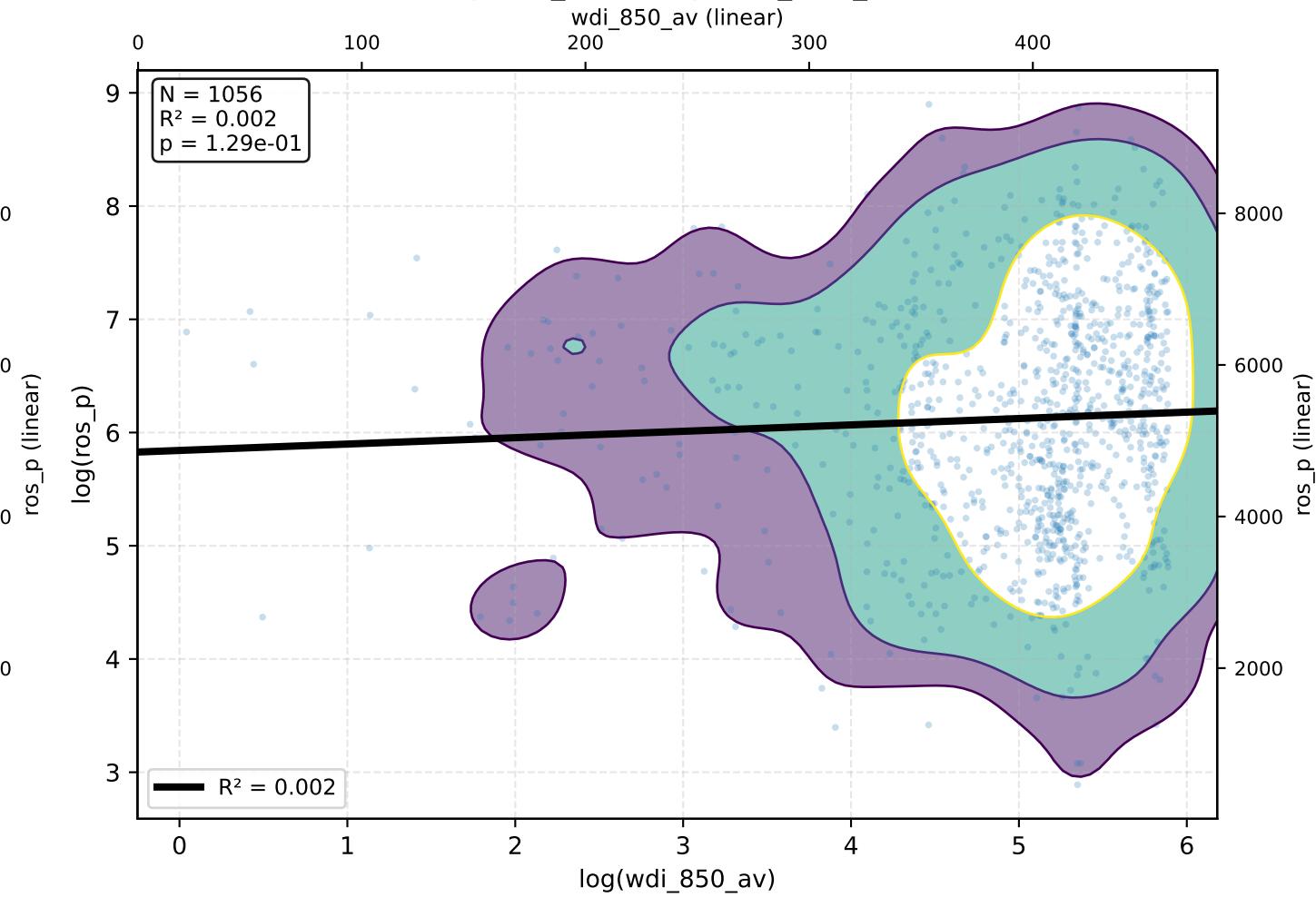
**ros\_p vs log(wdi\_850\_av)**



**log(ros\_p) vs wdi\_850\_av**

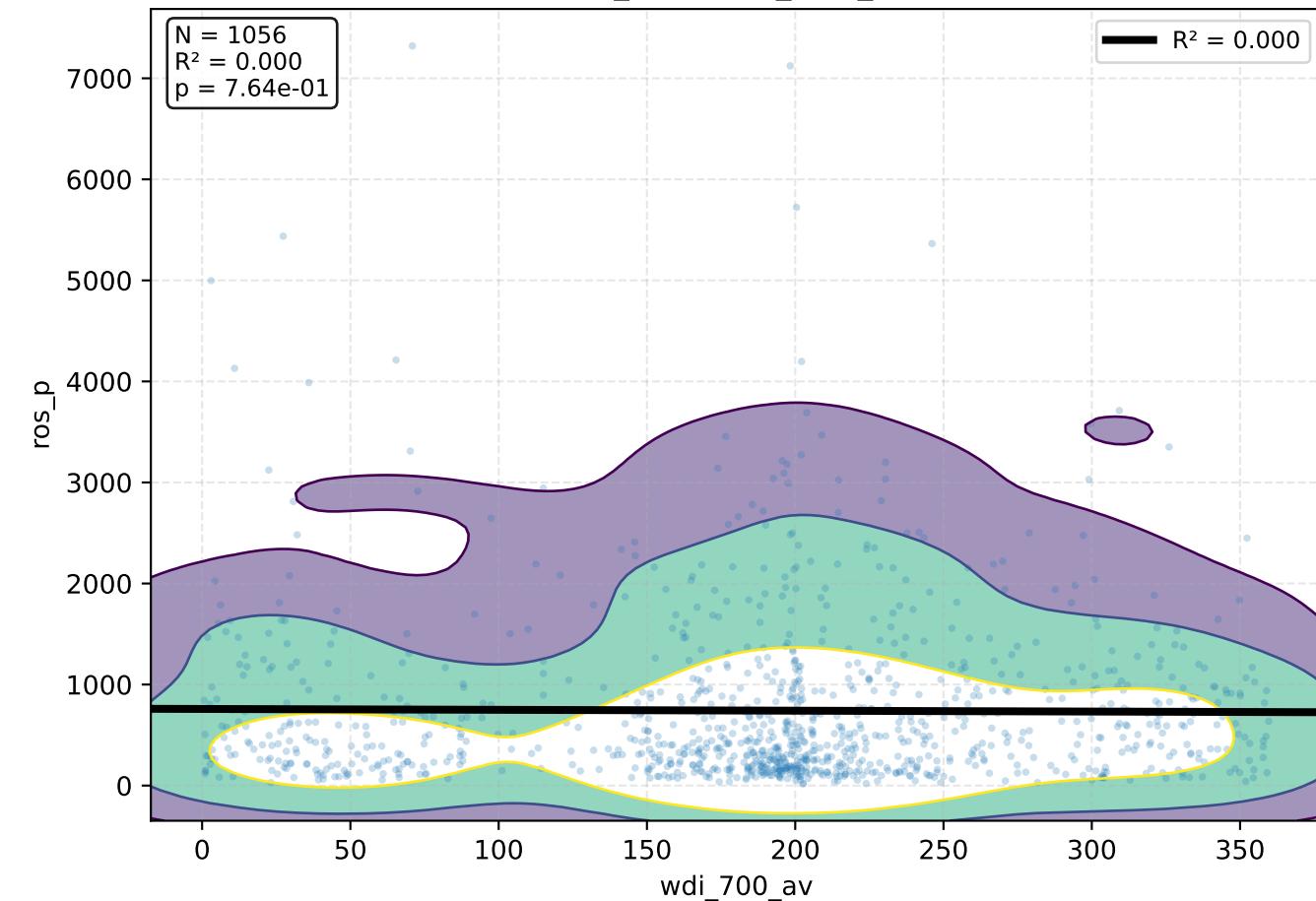


**log(ros\_p) vs log(wdi\_850\_av)**

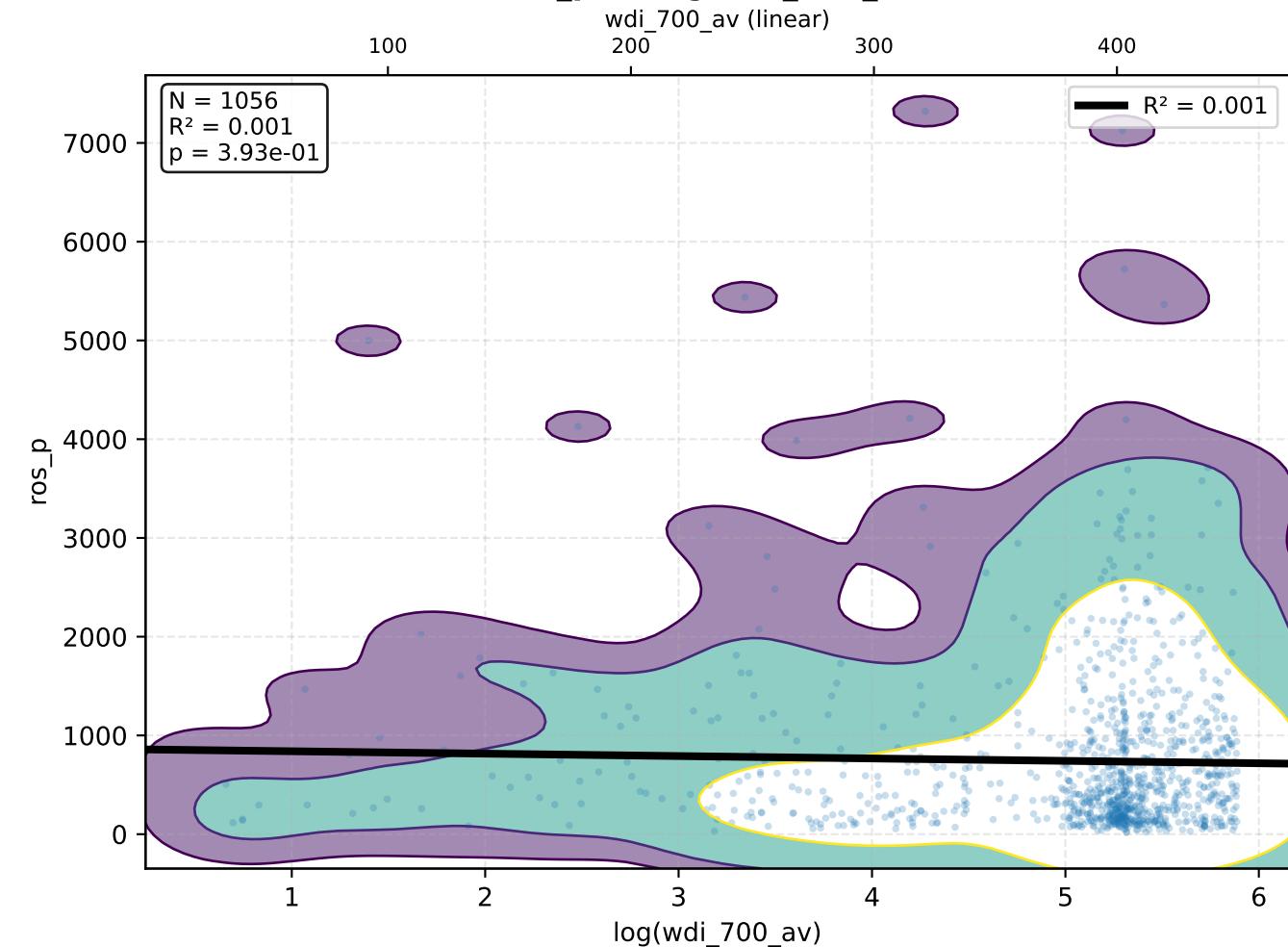


# wdi\_700\_av - KDE Density + Regressão

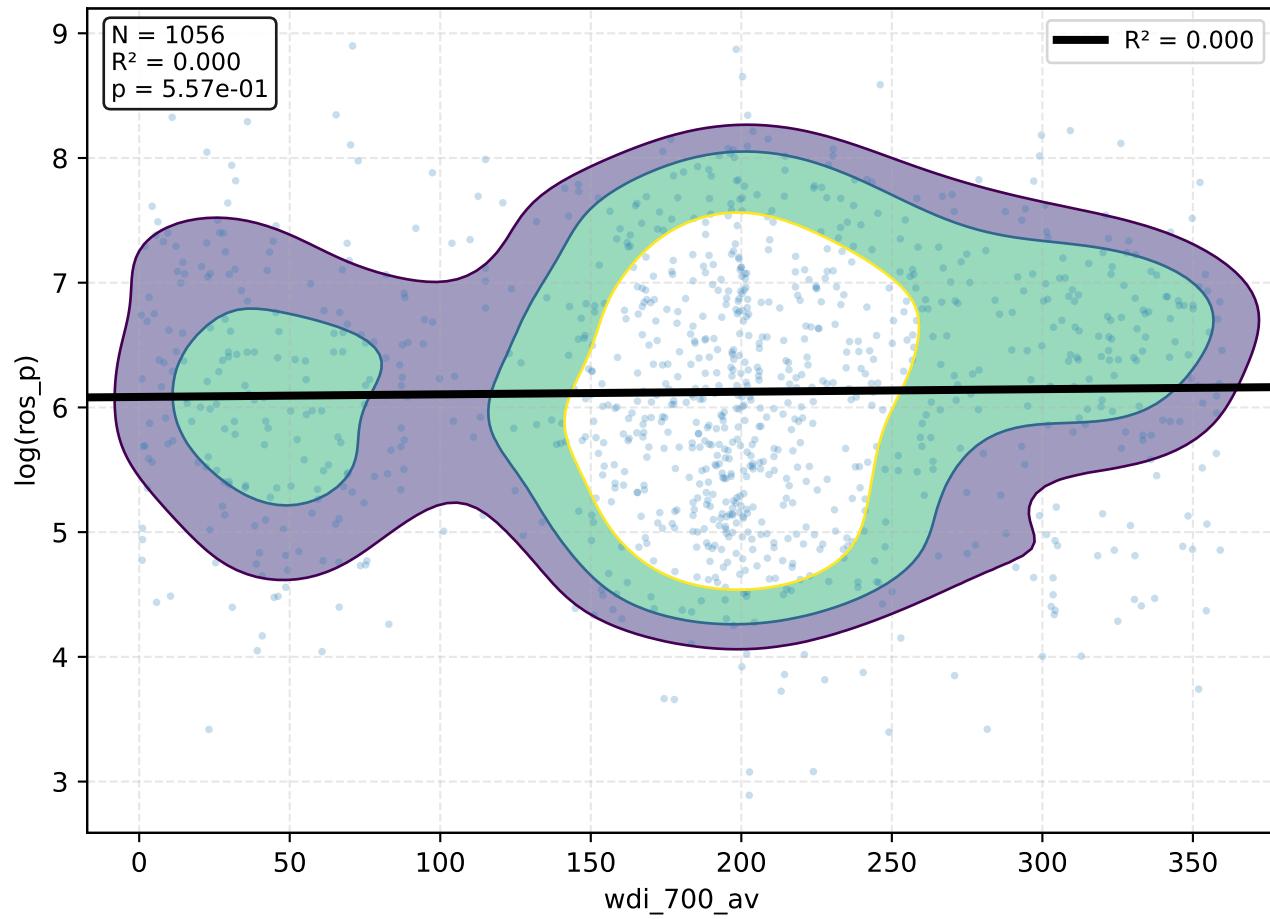
**ros\_p vs wdi\_700\_av**



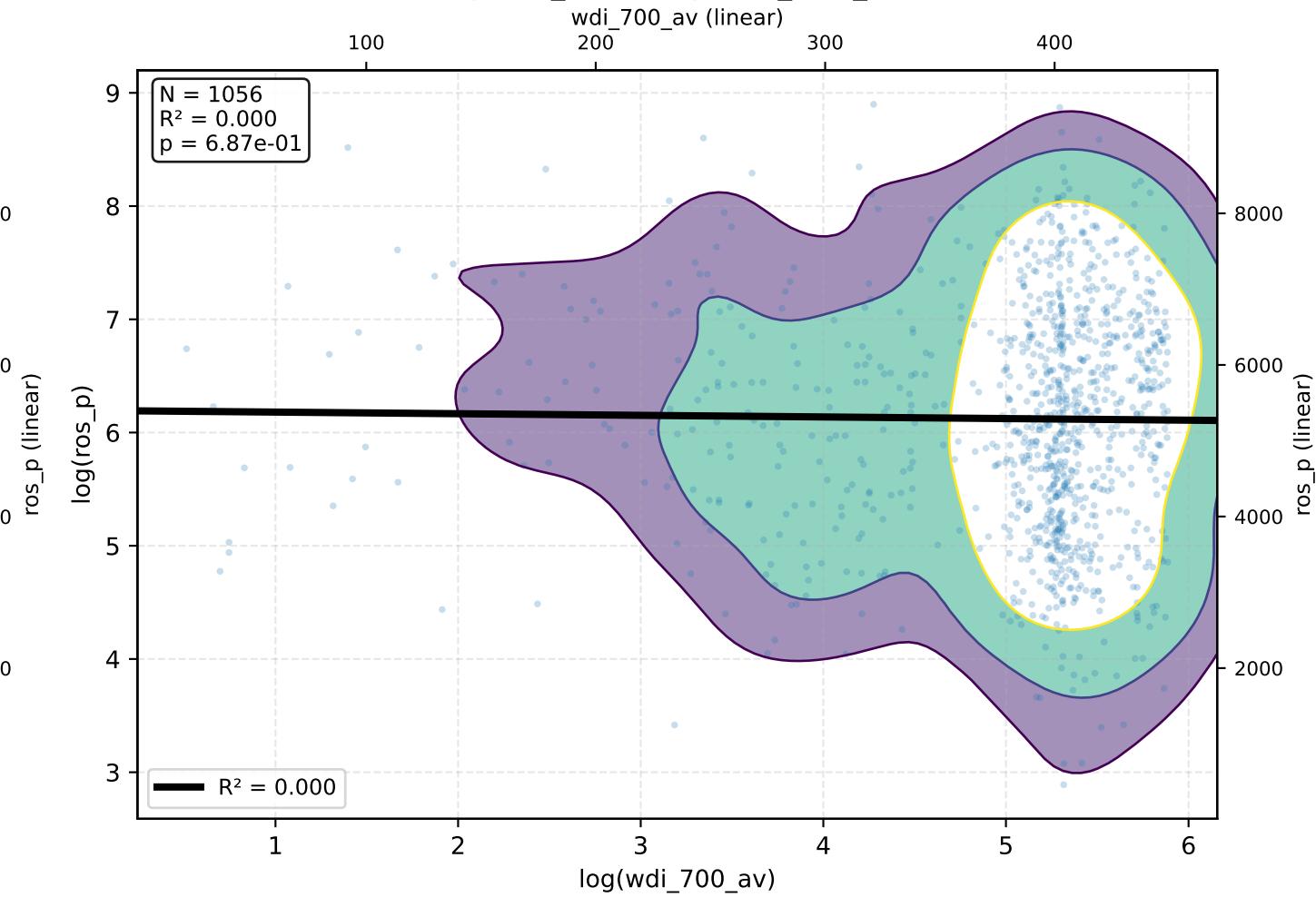
**ros\_p vs log(wdi\_700\_av)**



**log(ros\_p) vs wdi\_700\_av**

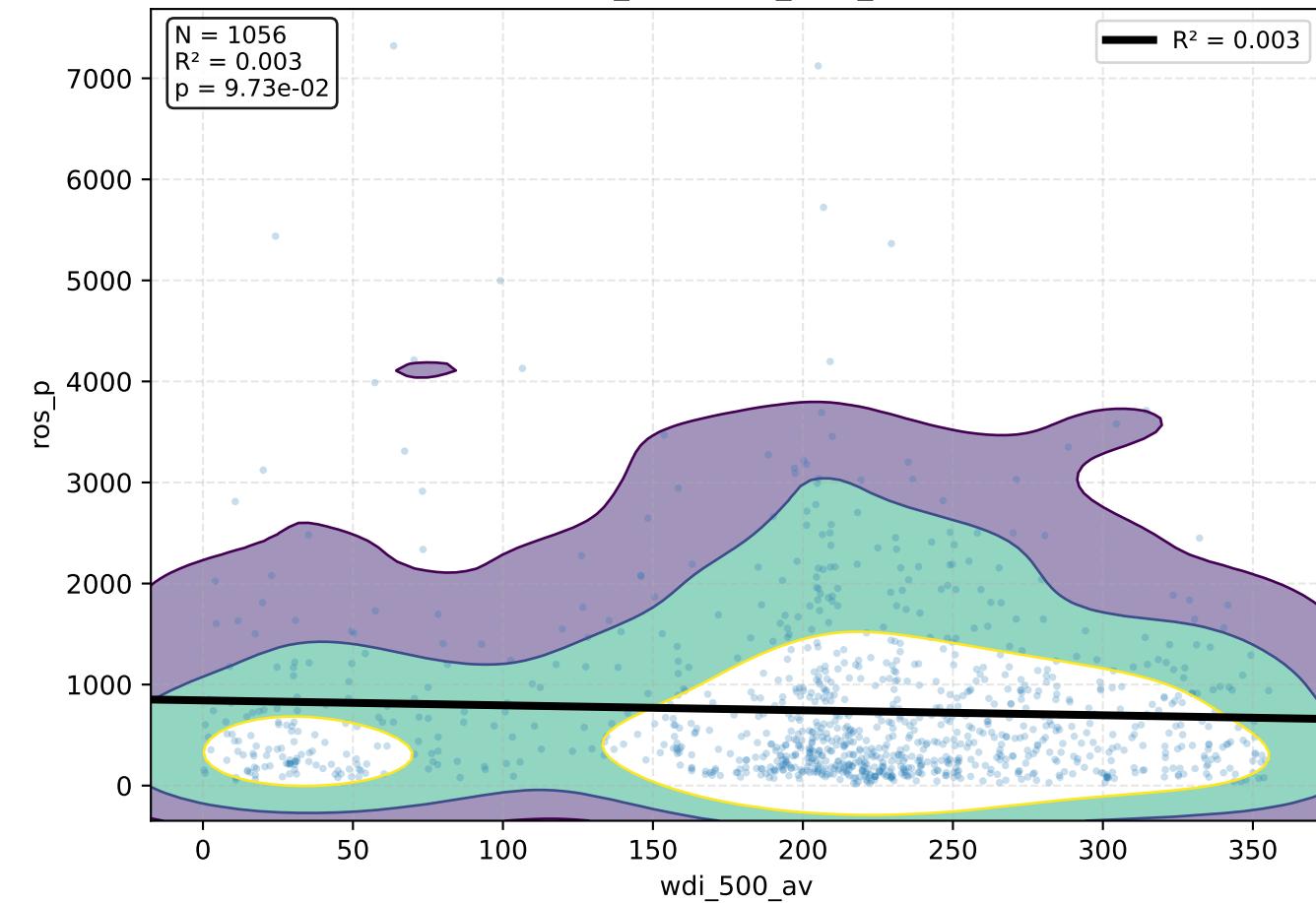


**log(ros\_p) vs log(wdi\_700\_av)**

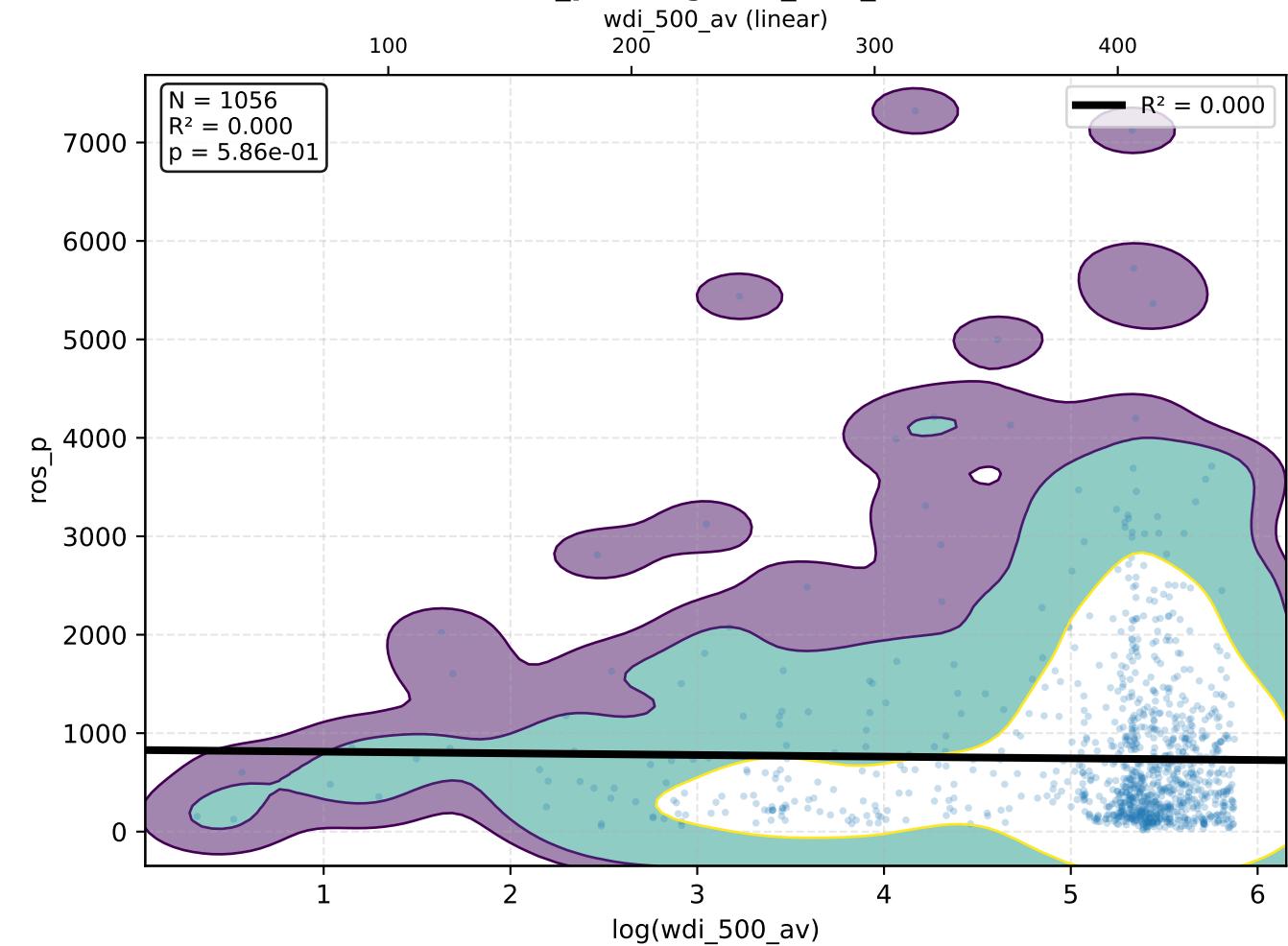


# wdi\_500\_av - KDE Density + Regressão

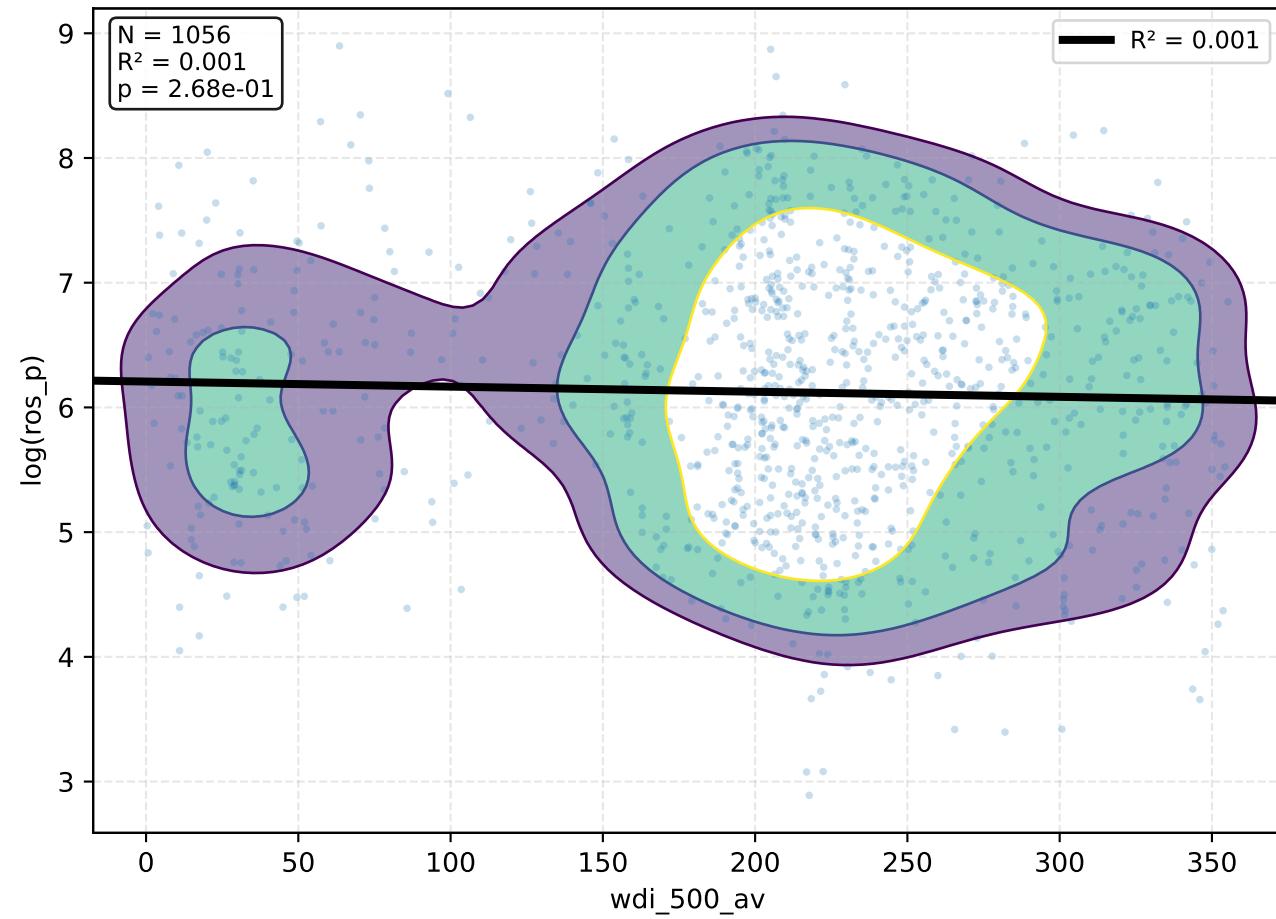
**ros\_p vs wdi\_500\_av**



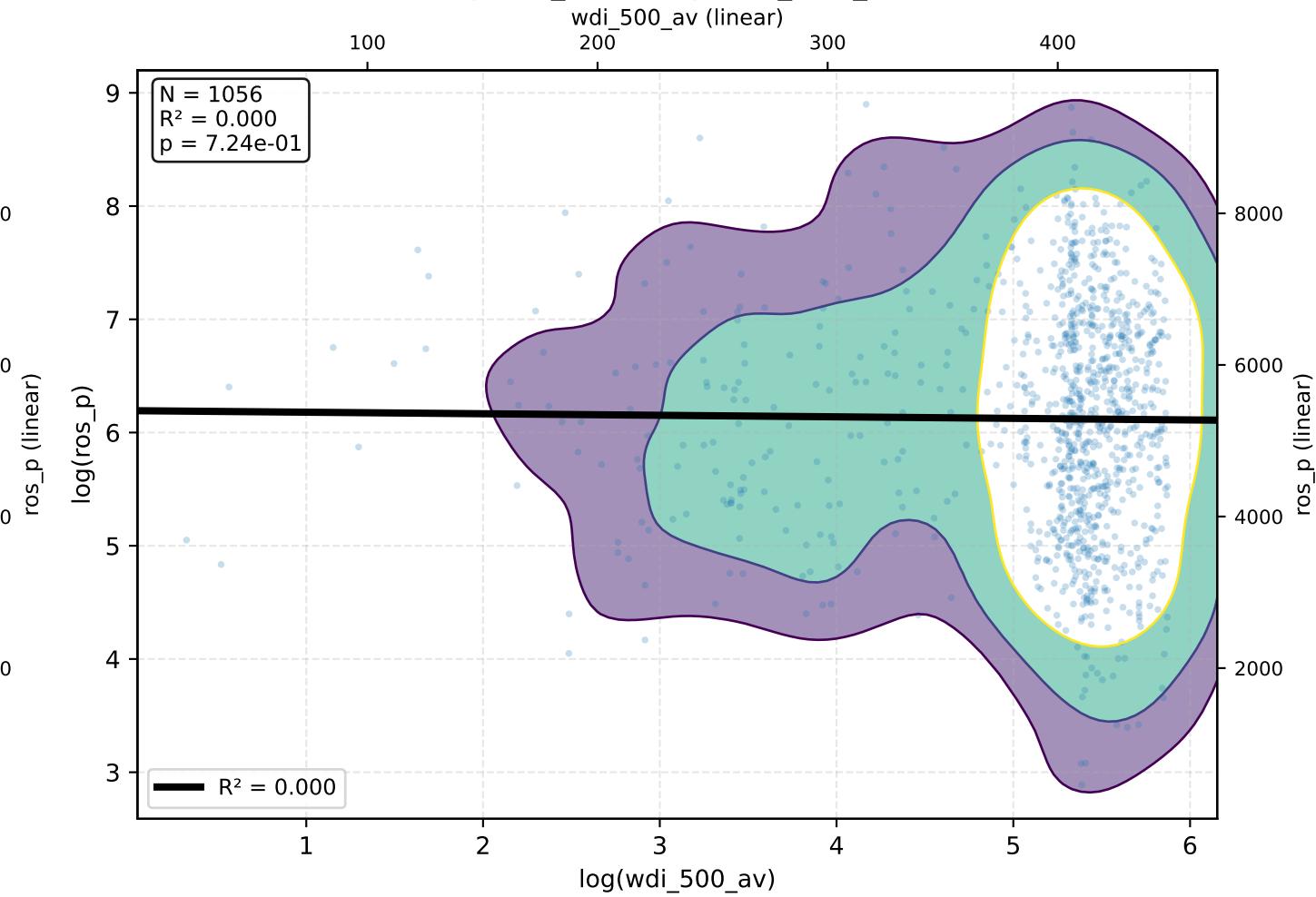
**ros\_p vs log(wdi\_500\_av)**



**log(ros\_p) vs wdi\_500\_av**

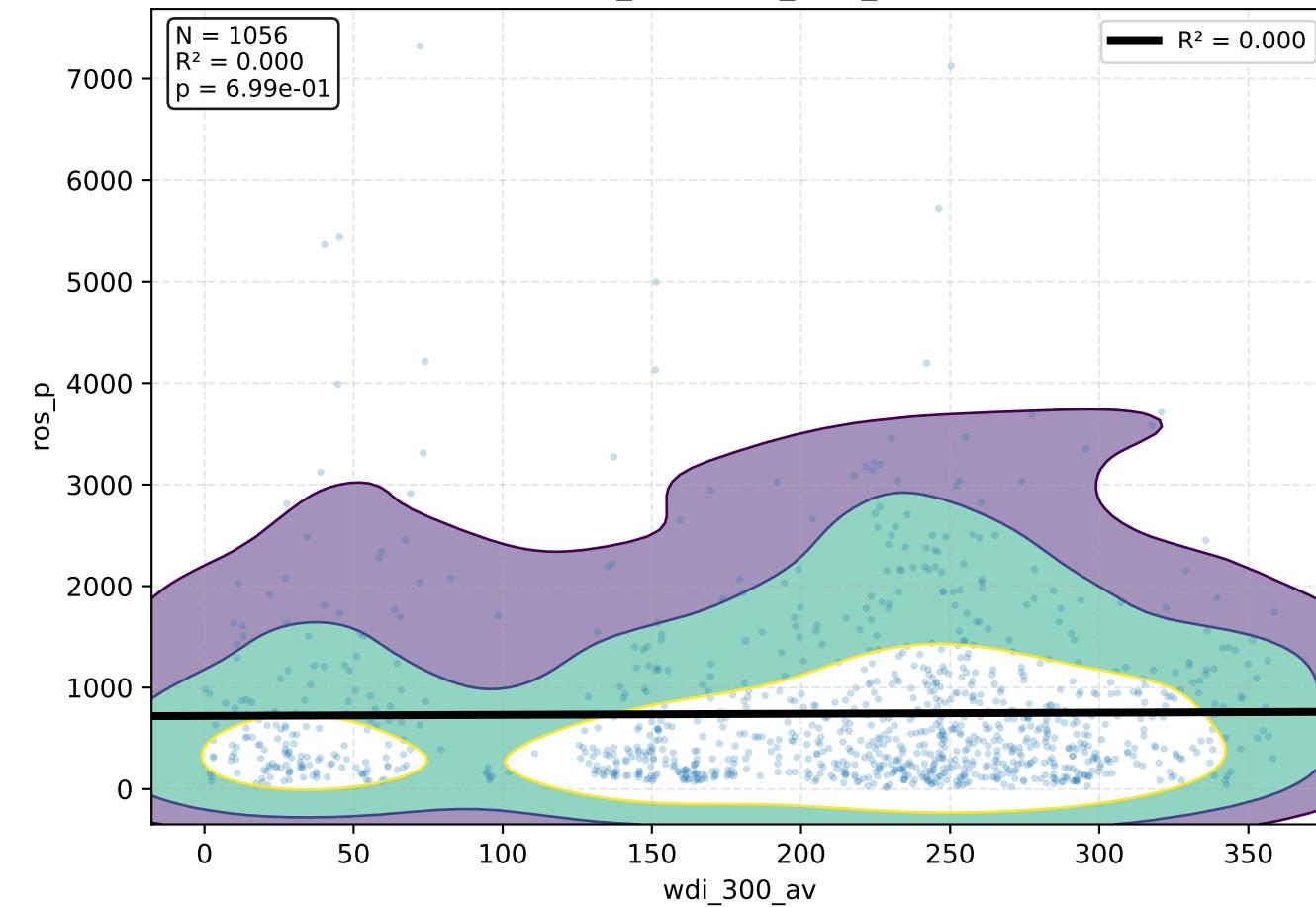


**log(ros\_p) vs log(wdi\_500\_av)**

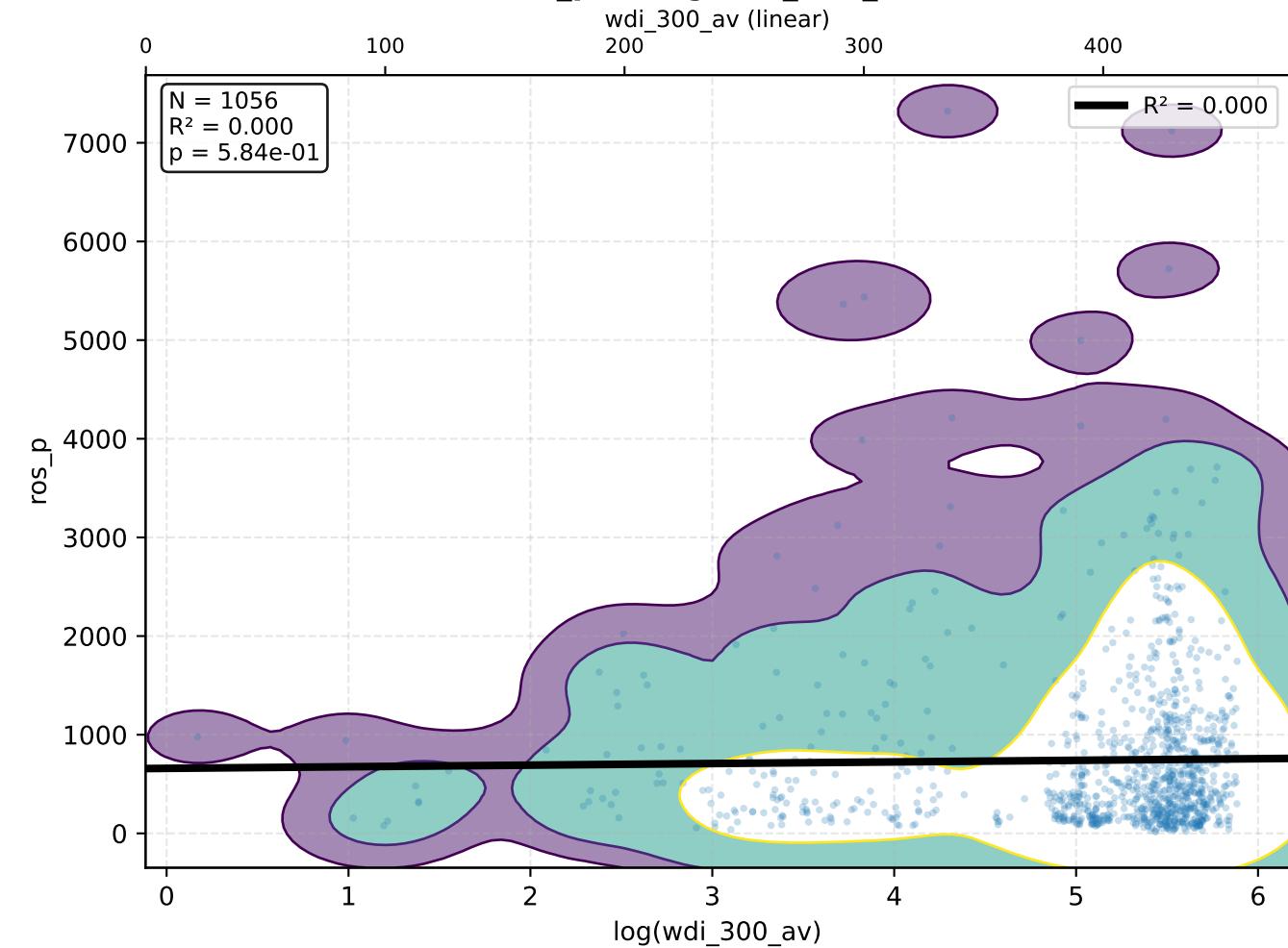


# wdi\_300\_av - KDE Density + Regressão

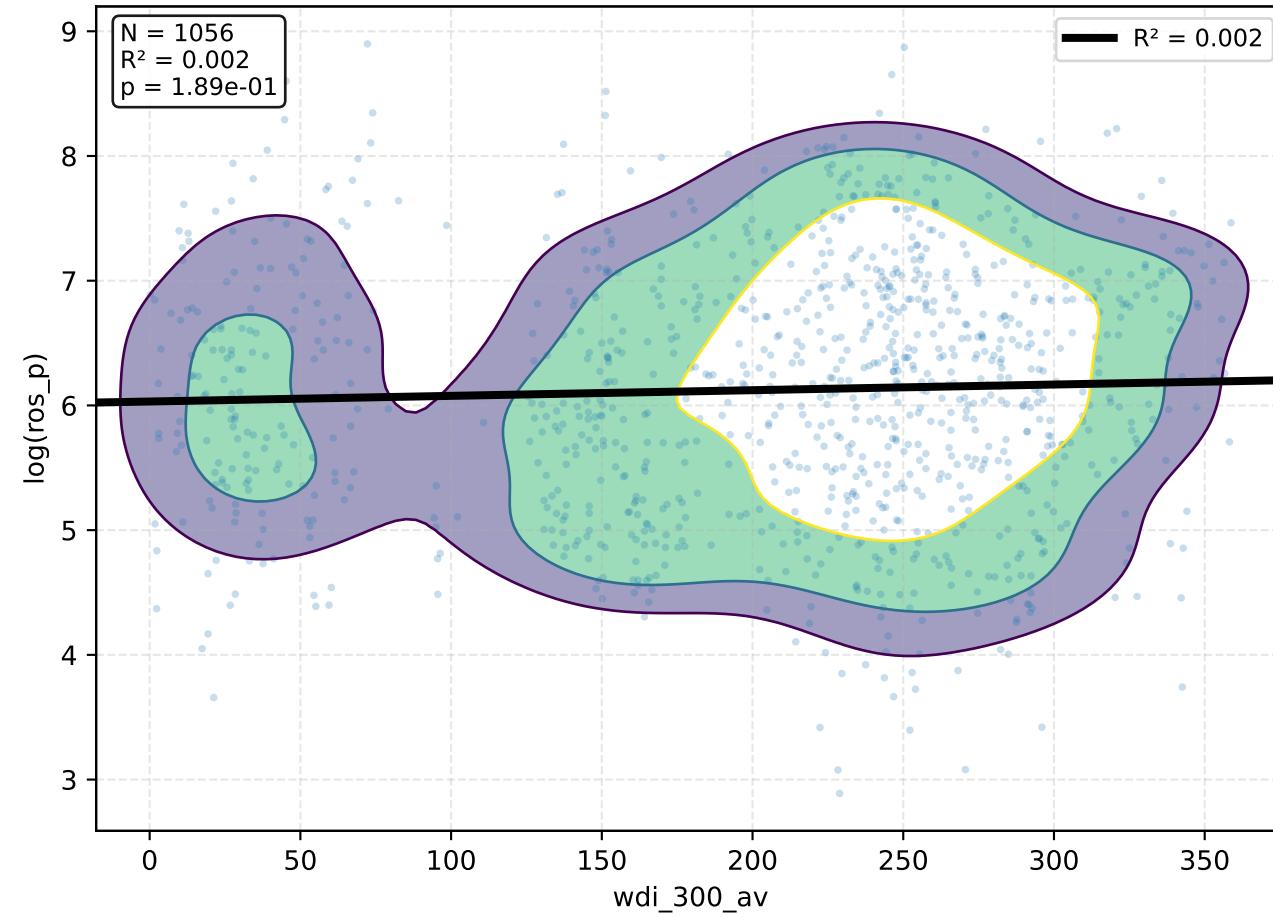
**ros\_p vs wdi\_300\_av**



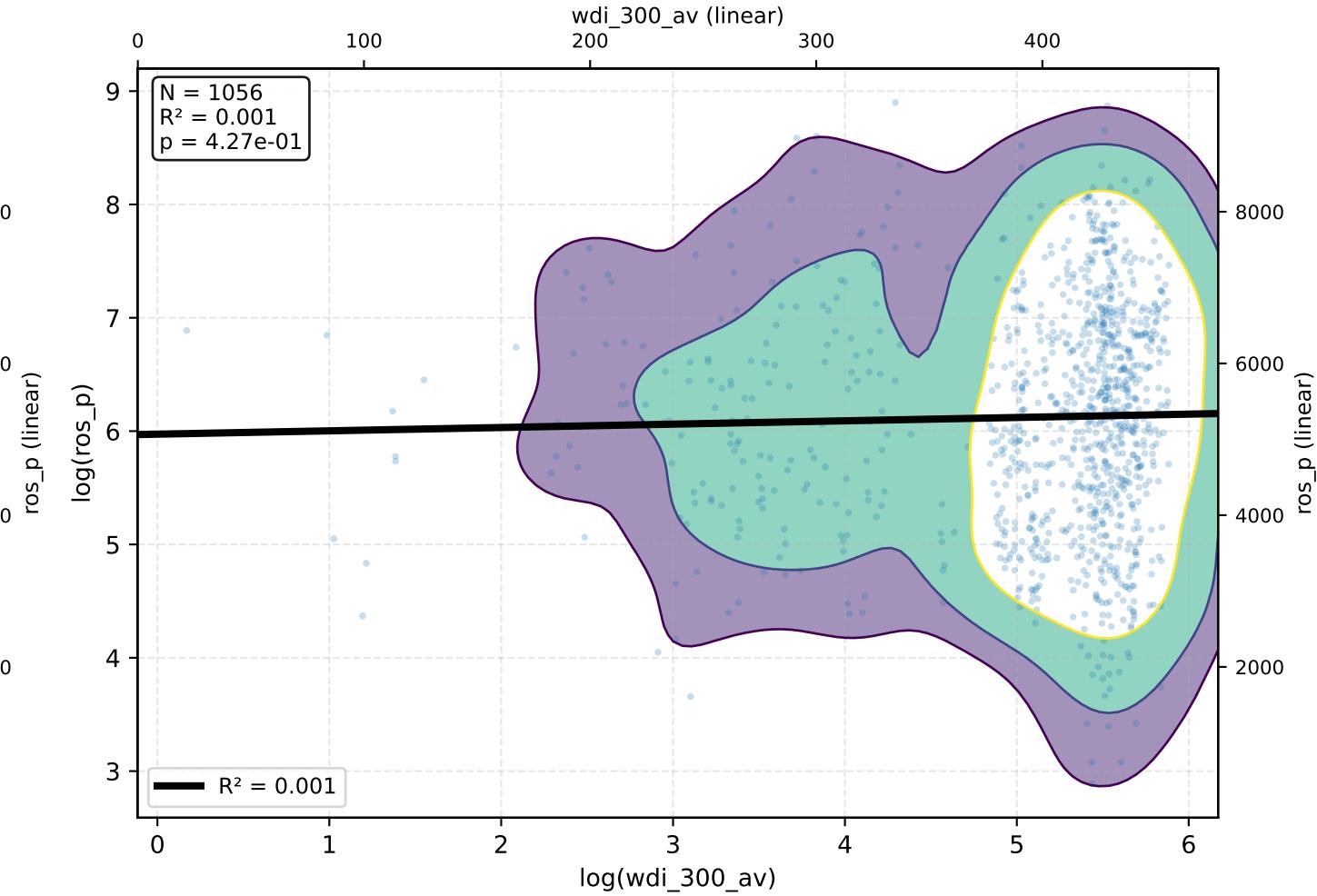
**ros\_p vs log(wdi\_300\_av)**



**log(ros\_p) vs wdi\_300\_av**

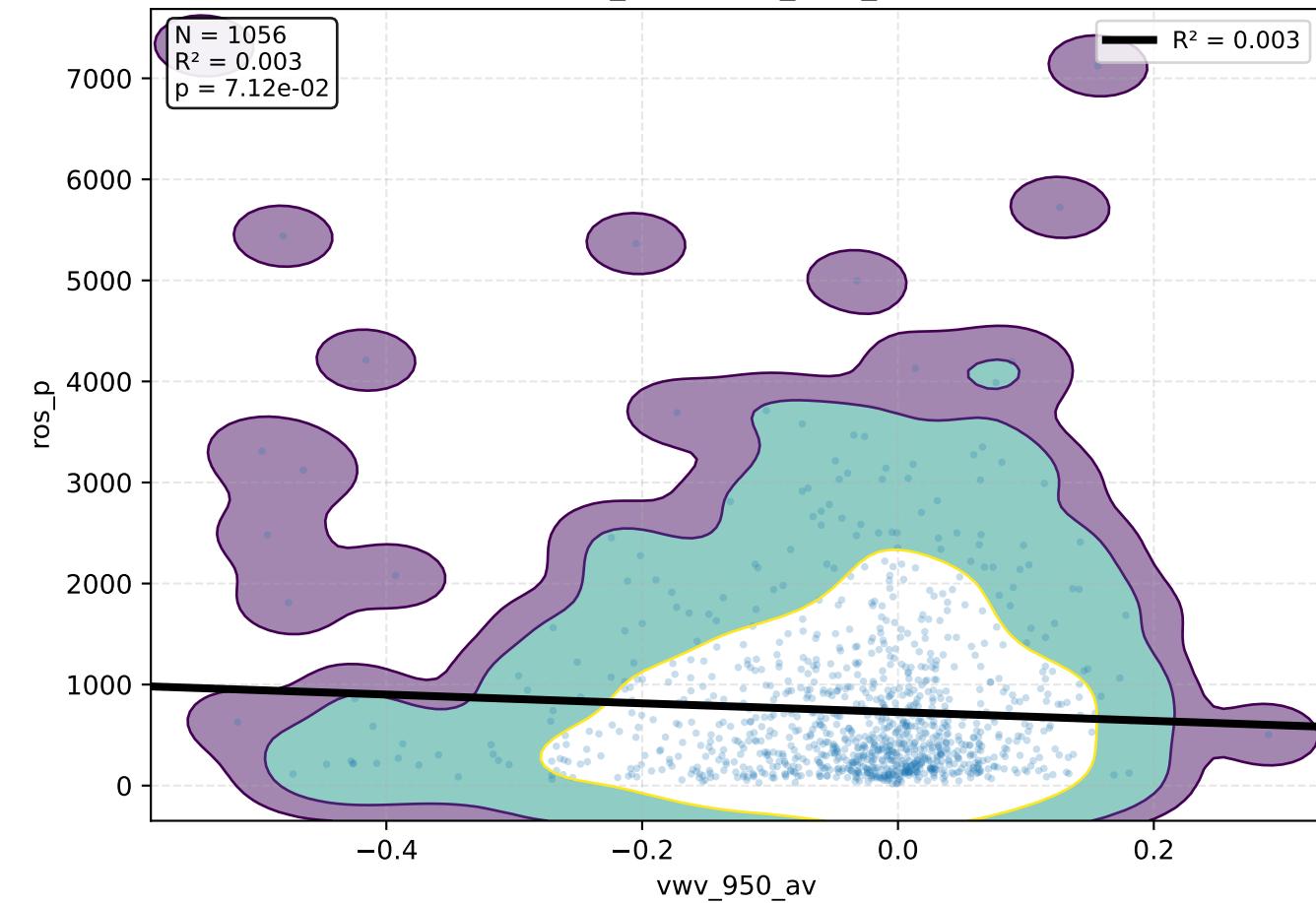


**log(ros\_p) vs log(wdi\_300\_av)**

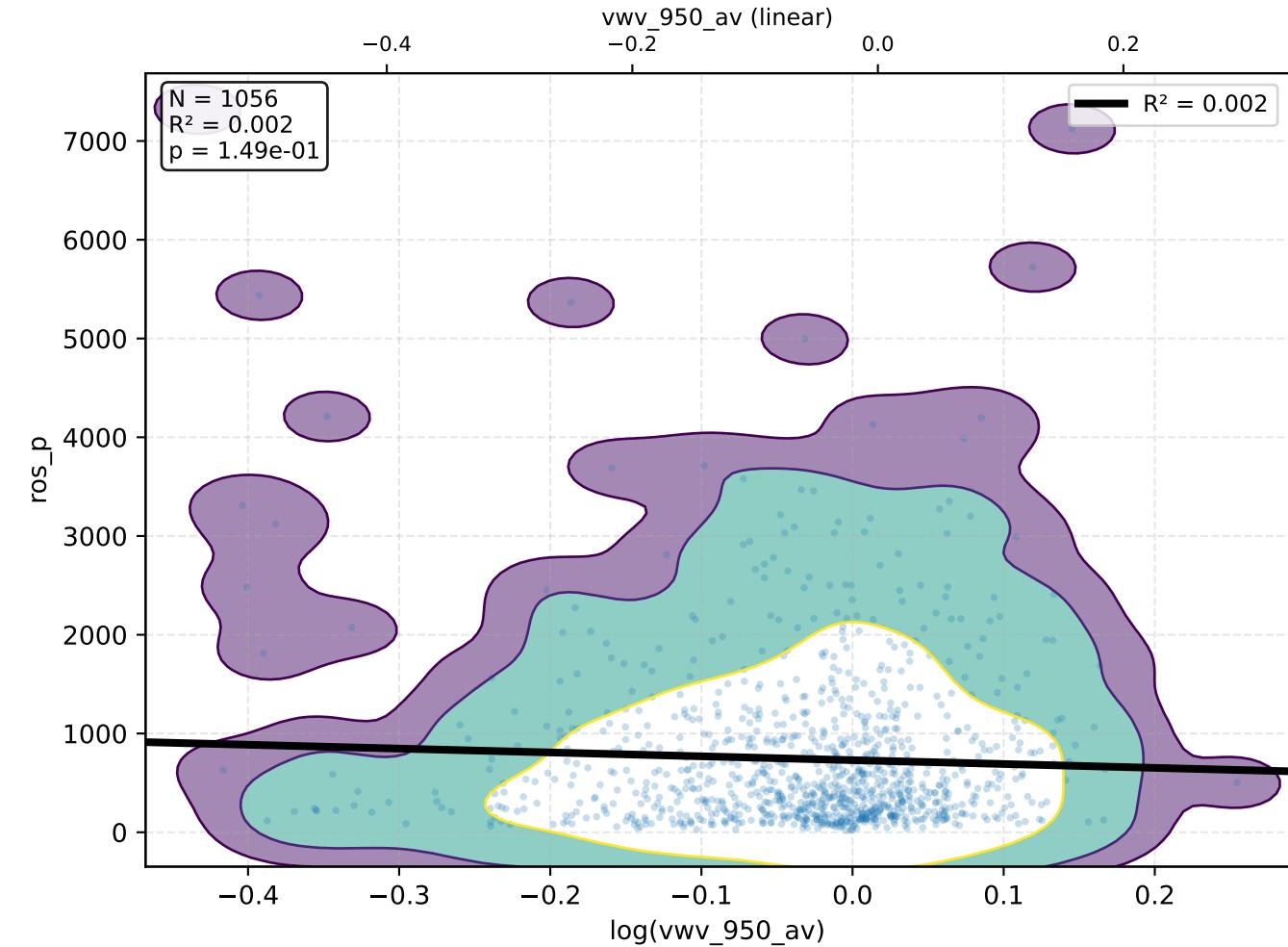


# vwv\_950\_av – KDE Density + Regressão

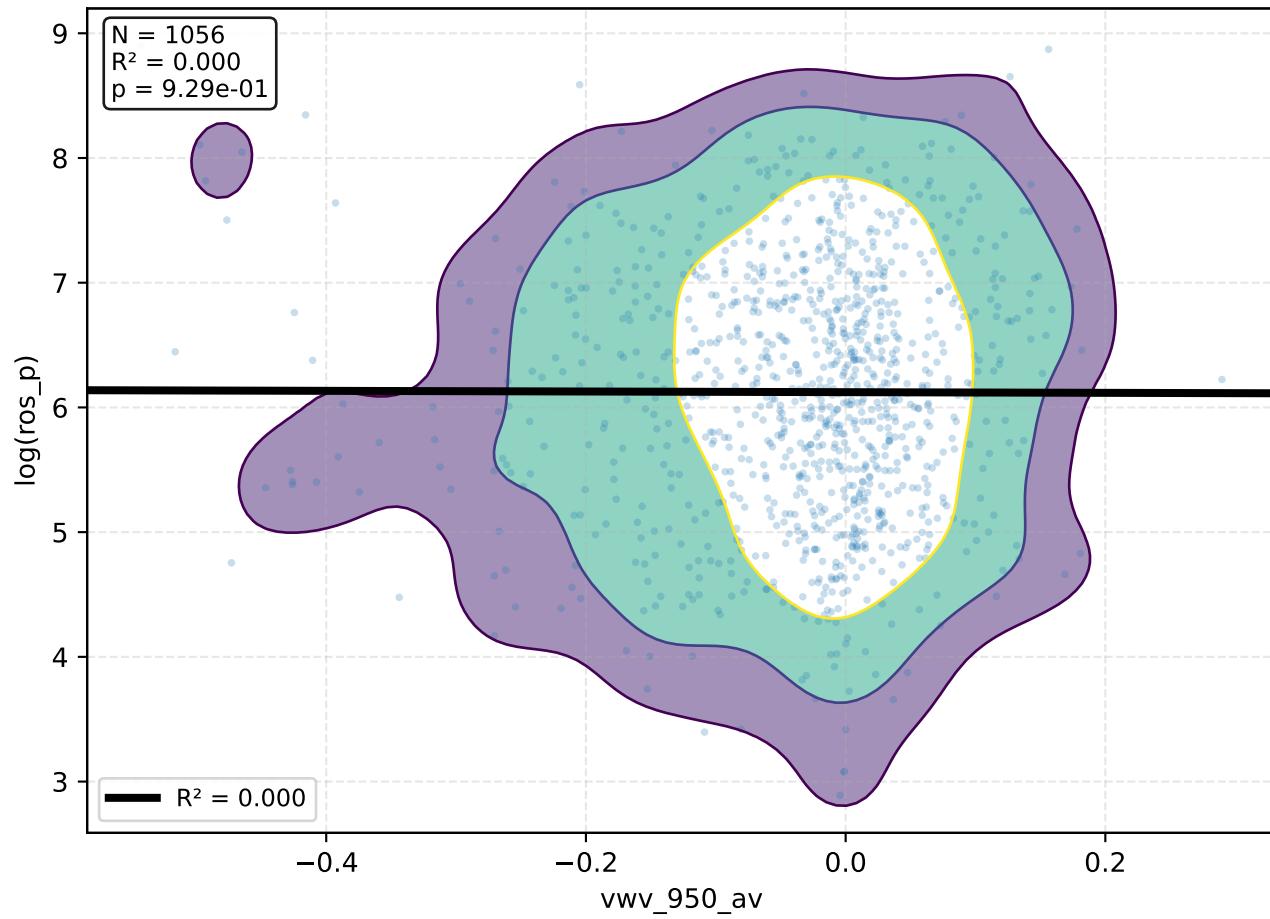
**ros\_p vs vwv\_950\_av**



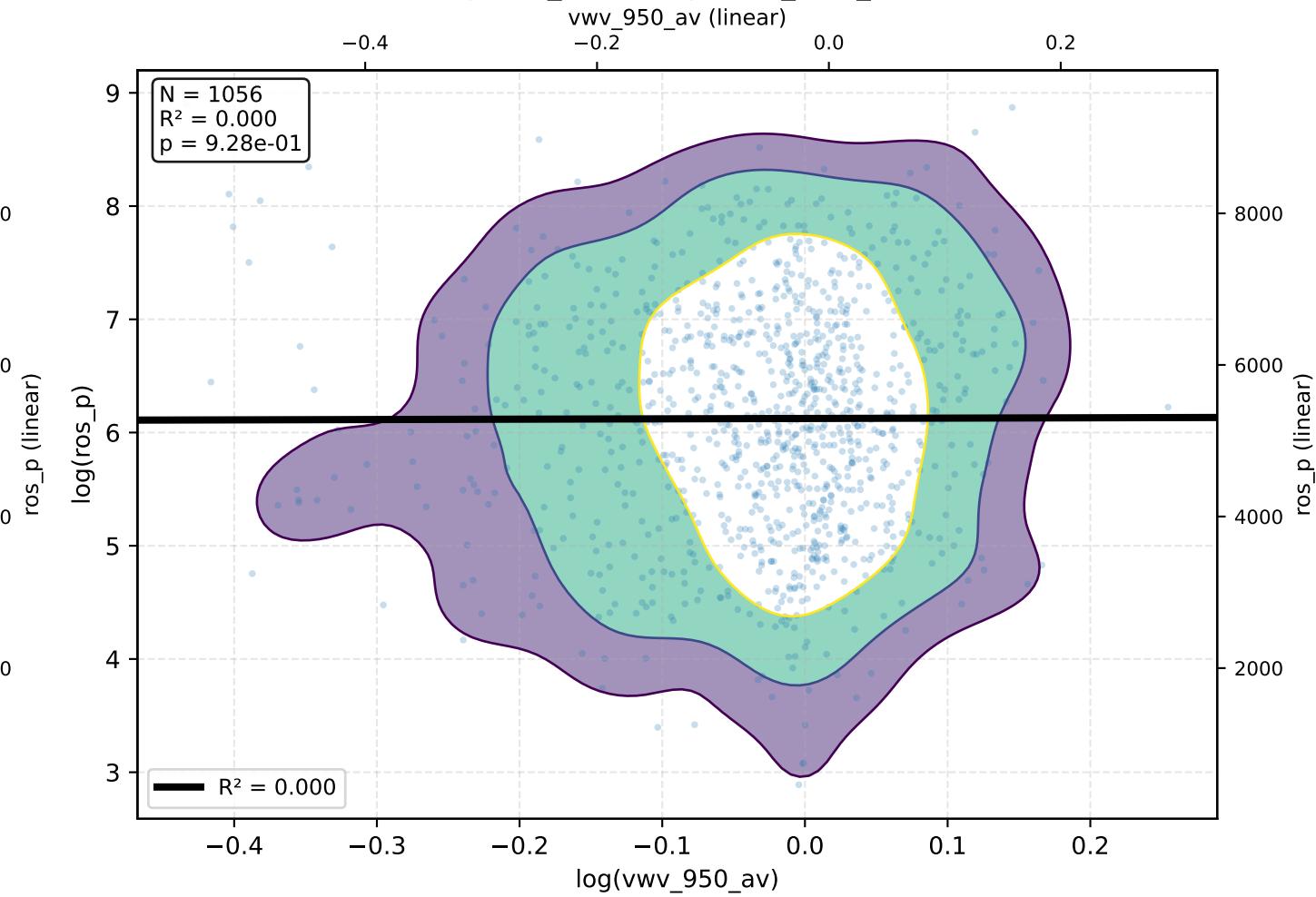
**ros\_p vs log(vwv\_950\_av)**



**log(ros\_p) vs vwv\_950\_av**

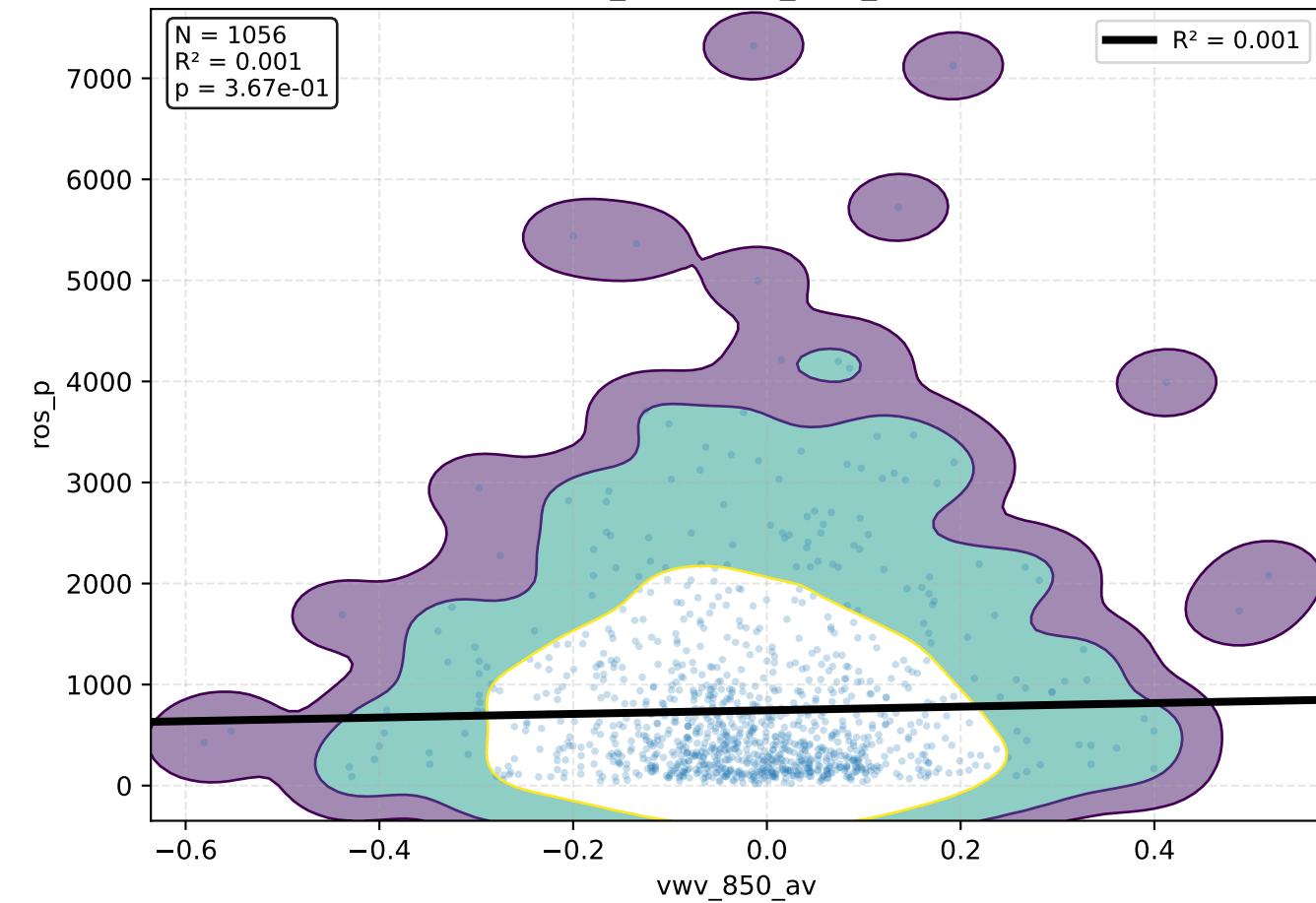


**log(ros\_p) vs log(vwv\_950\_av)**

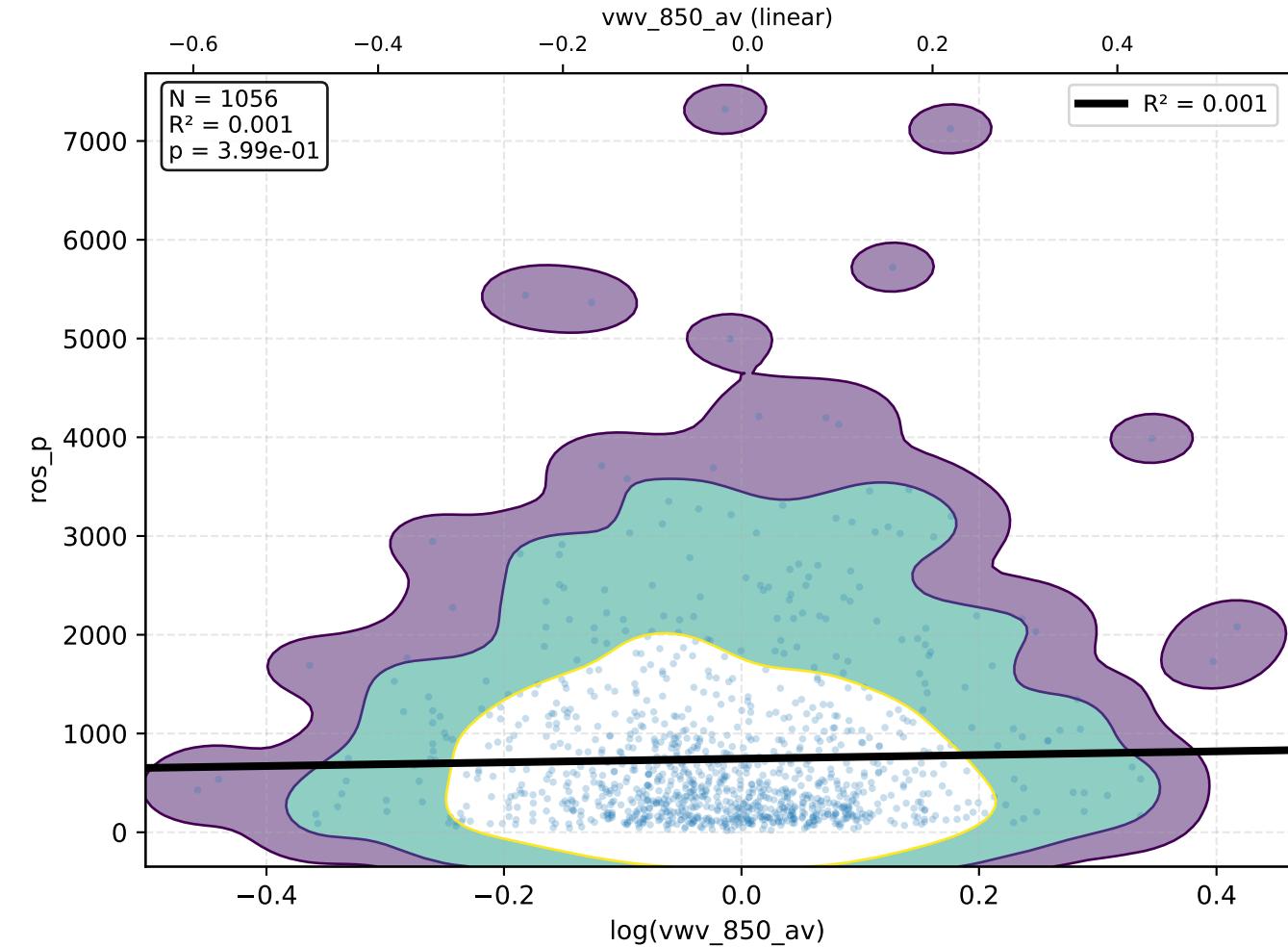


# vwv\_850\_av – KDE Density + Regressão

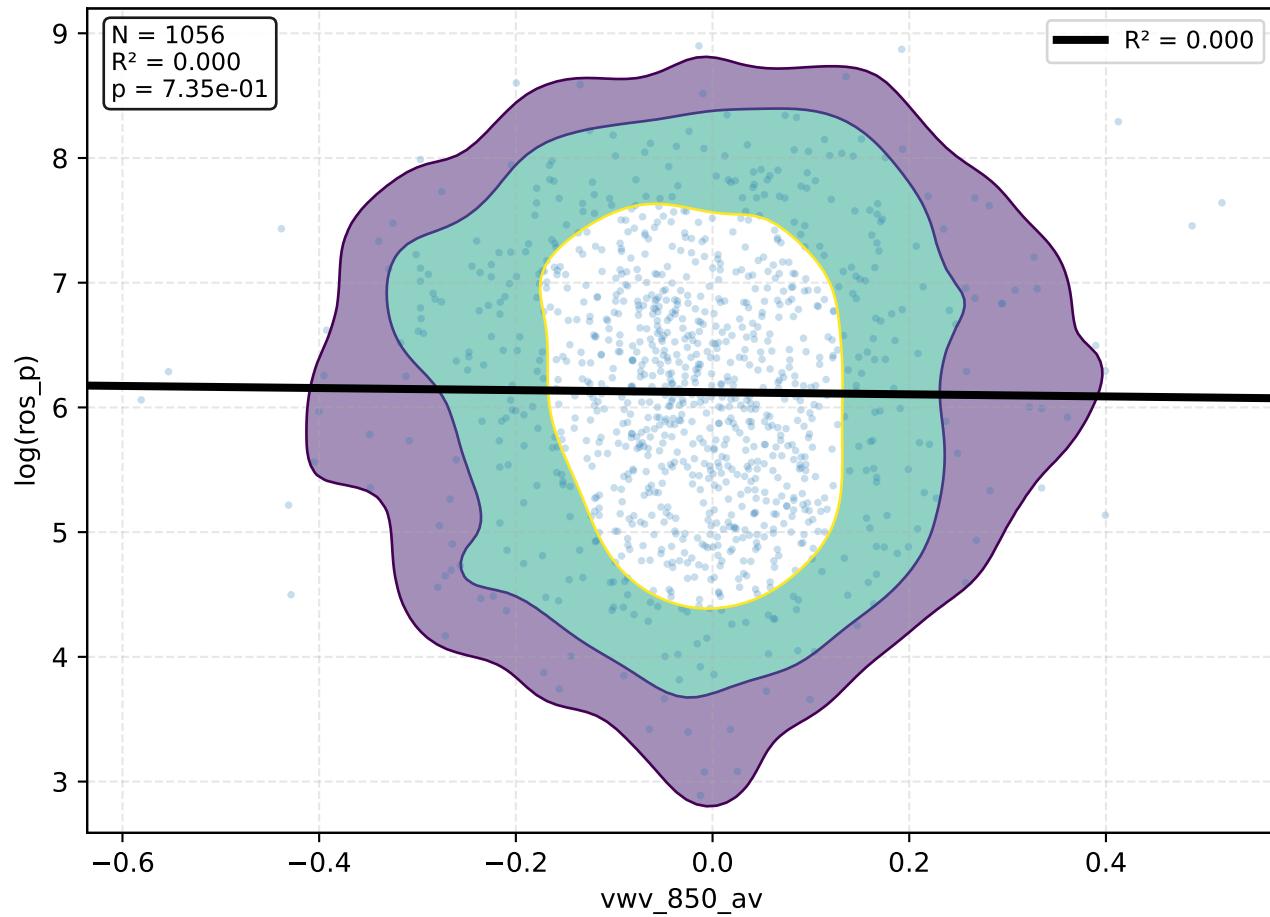
**ros\_p vs vwv\_850\_av**



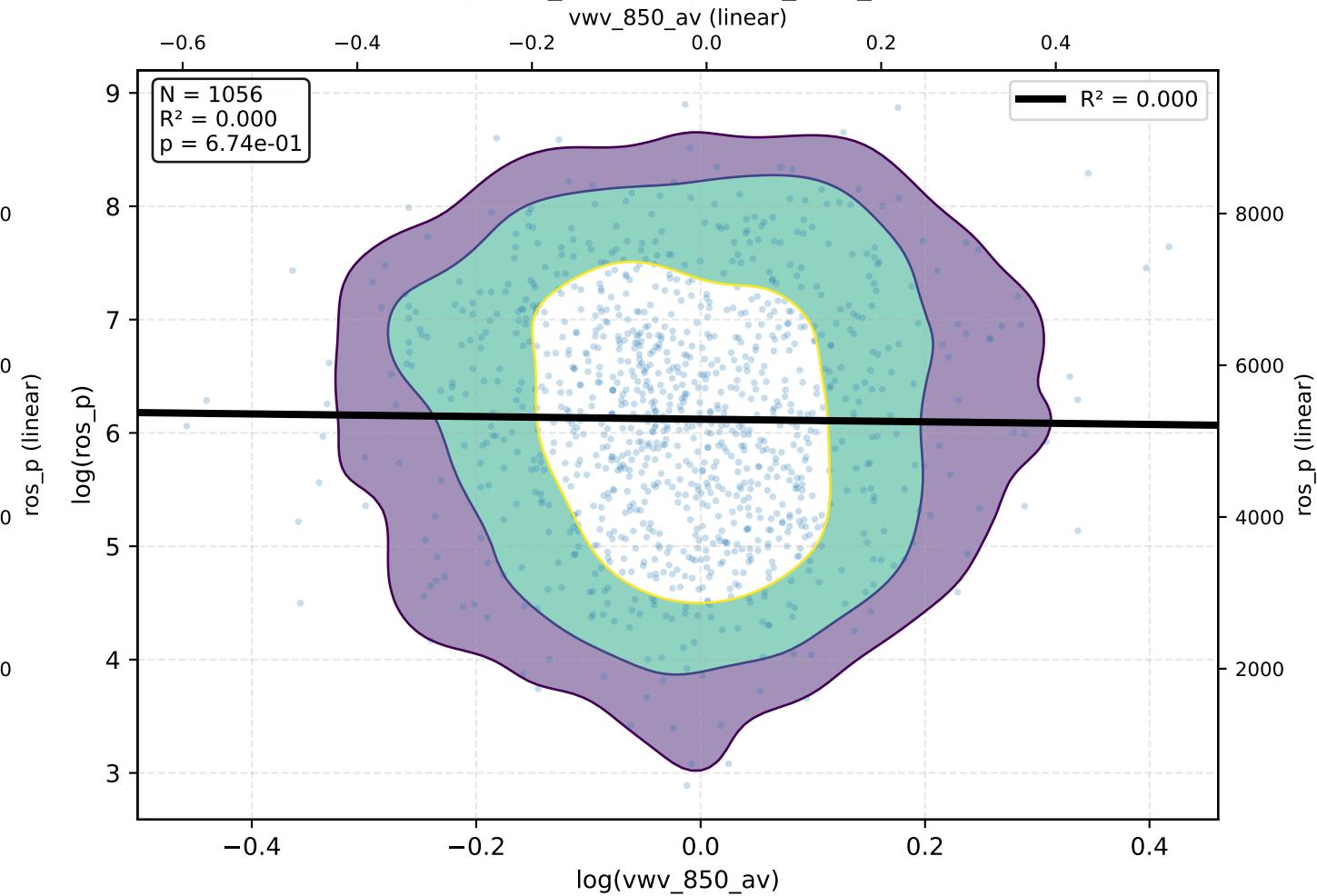
**ros\_p vs log(vwv\_850\_av)**



**log(ros\_p) vs vwv\_850\_av**

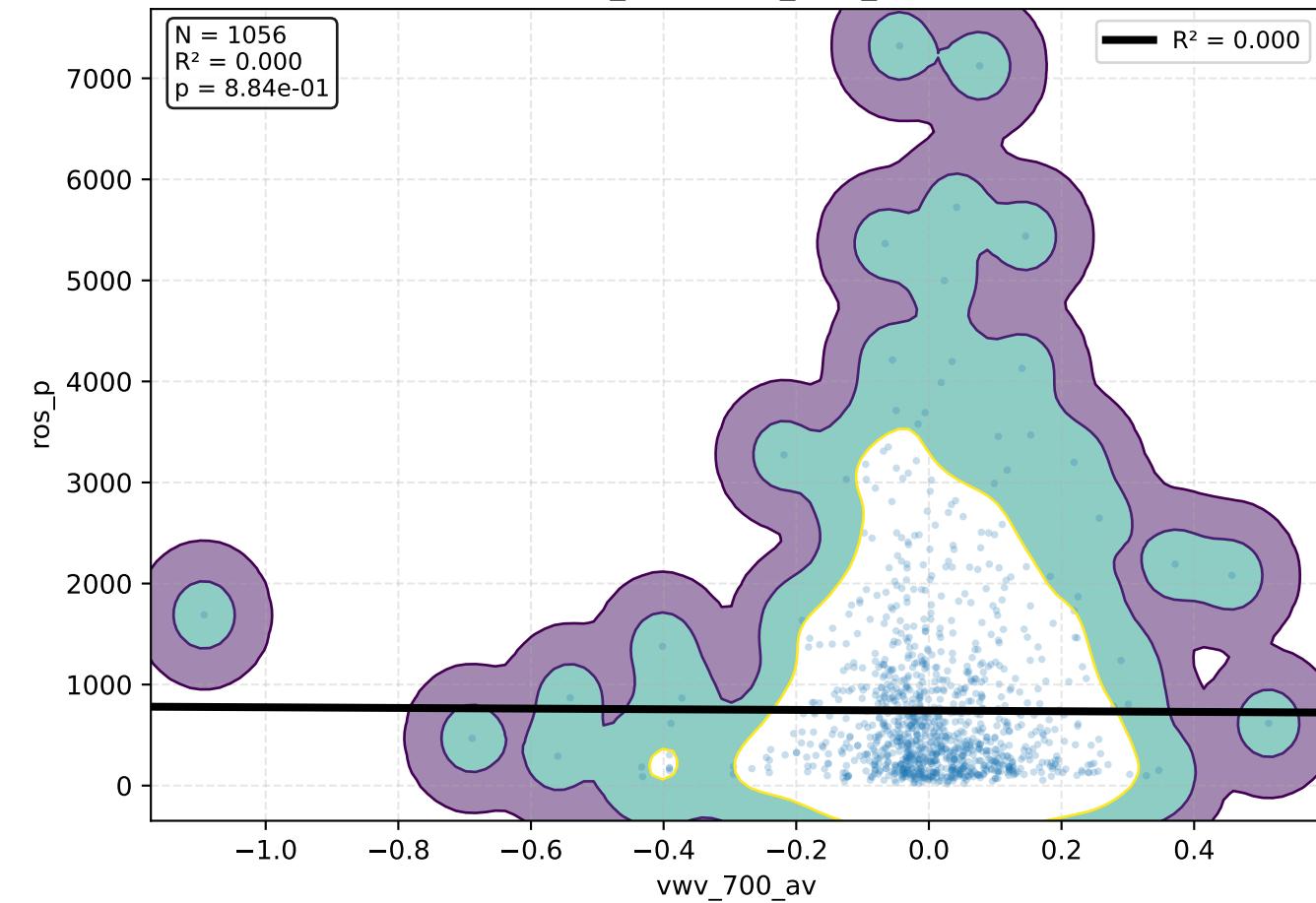


**log(ros\_p) vs log(vwv\_850\_av)**

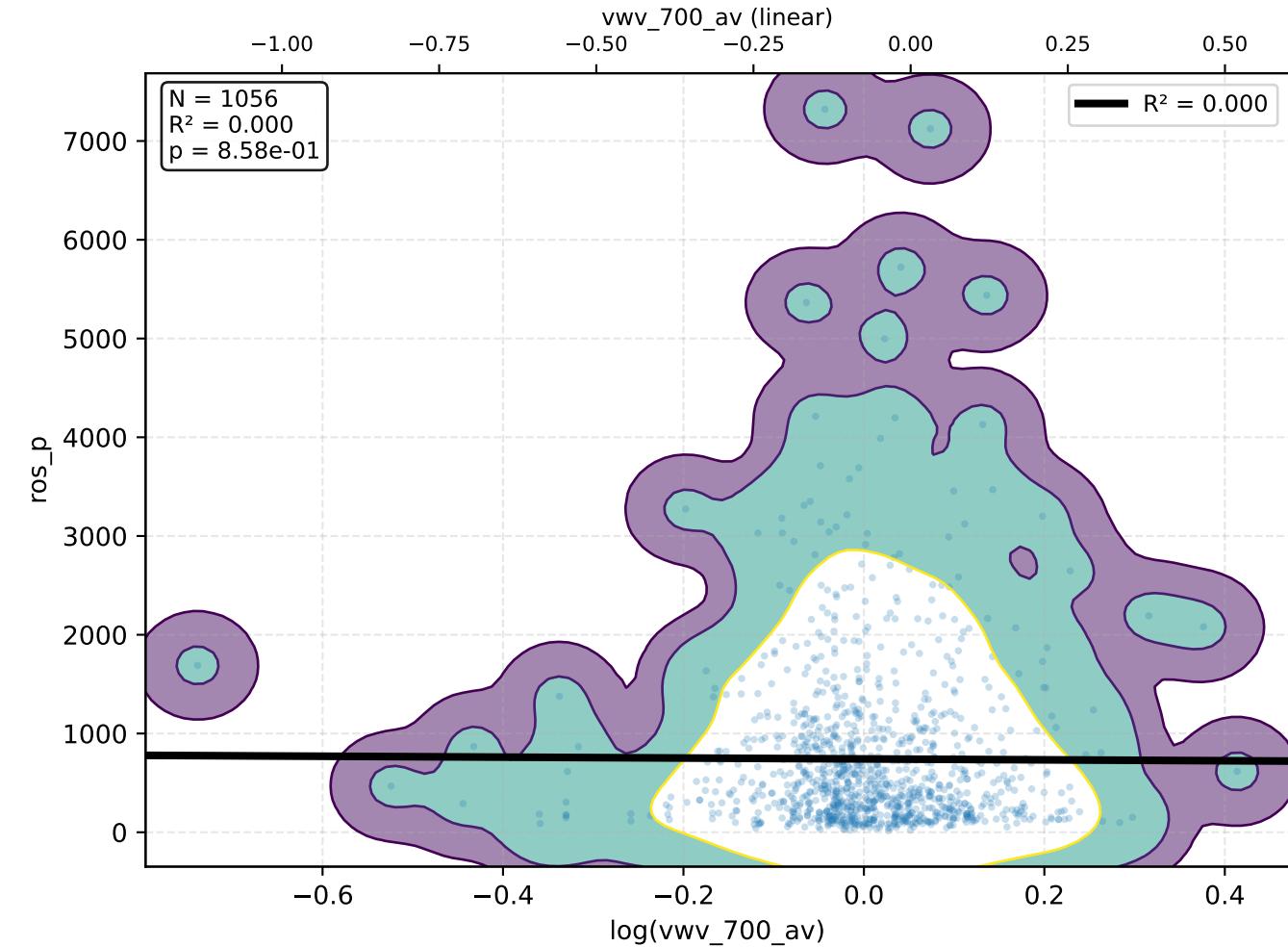


# vwv\_700\_av – KDE Density + Regressão

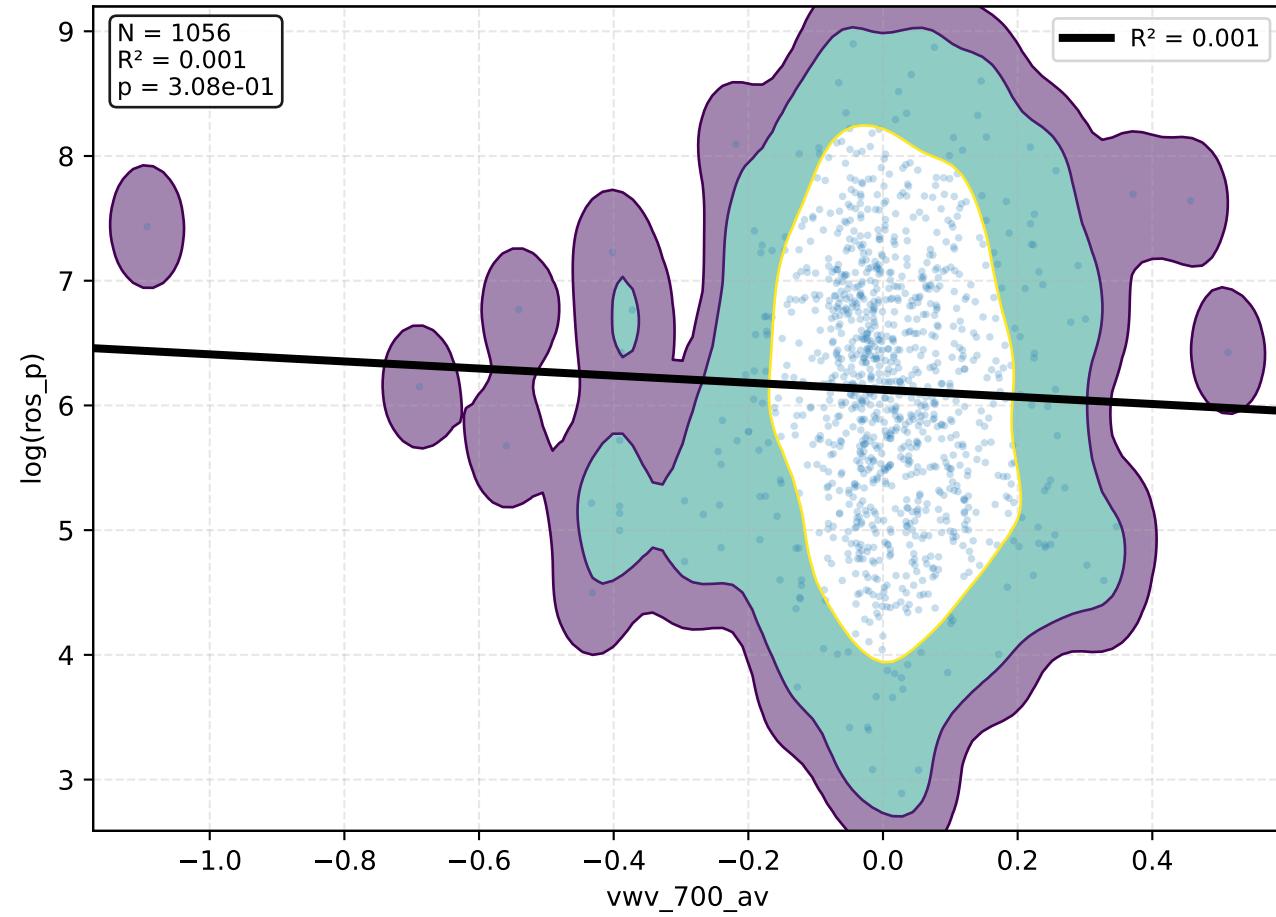
**ros\_p vs vwv\_700\_av**



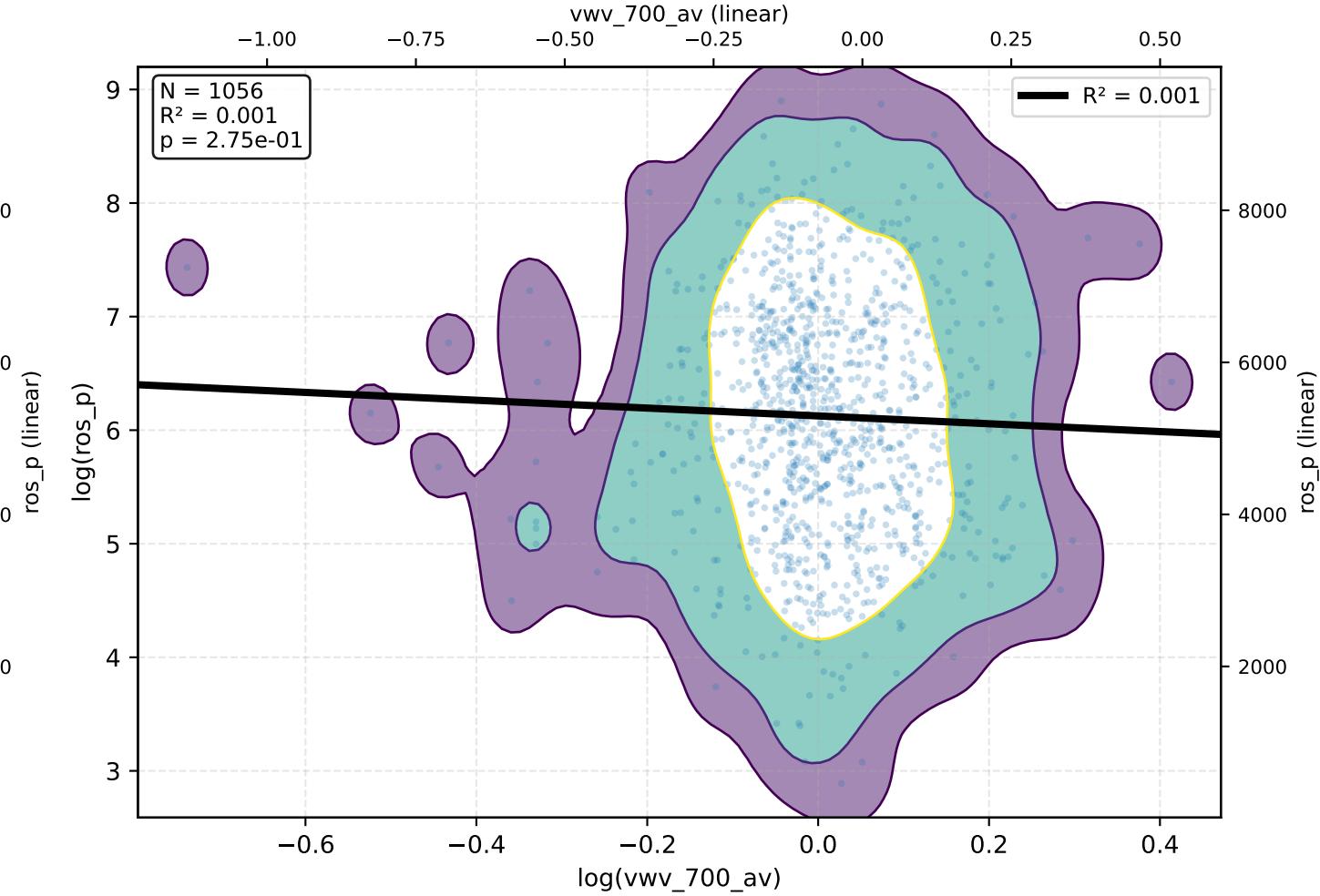
**ros\_p vs log(vwv\_700\_av)**



**log(ros\_p) vs vwv\_700\_av**

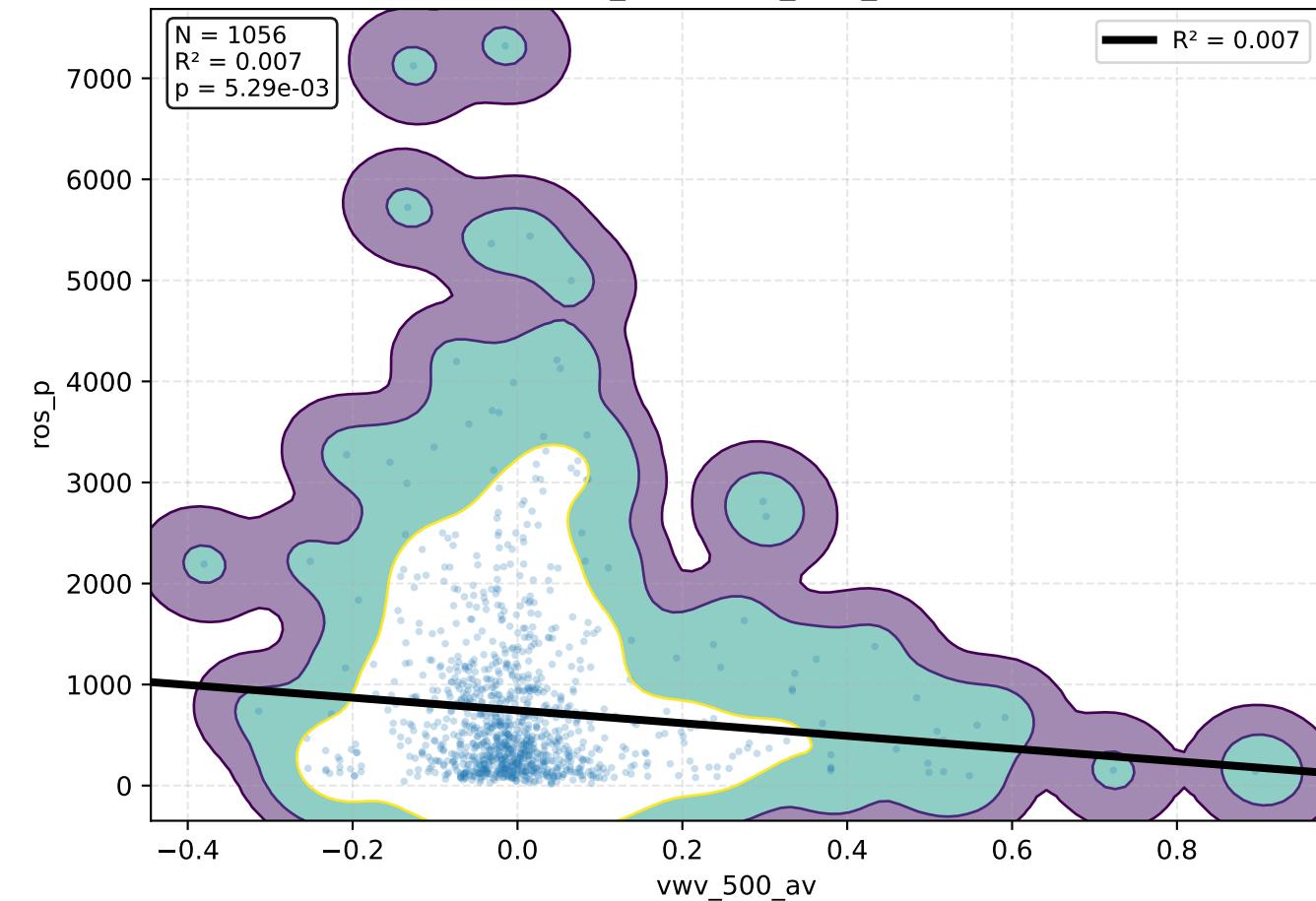


**log(ros\_p) vs log(vwv\_700\_av)**

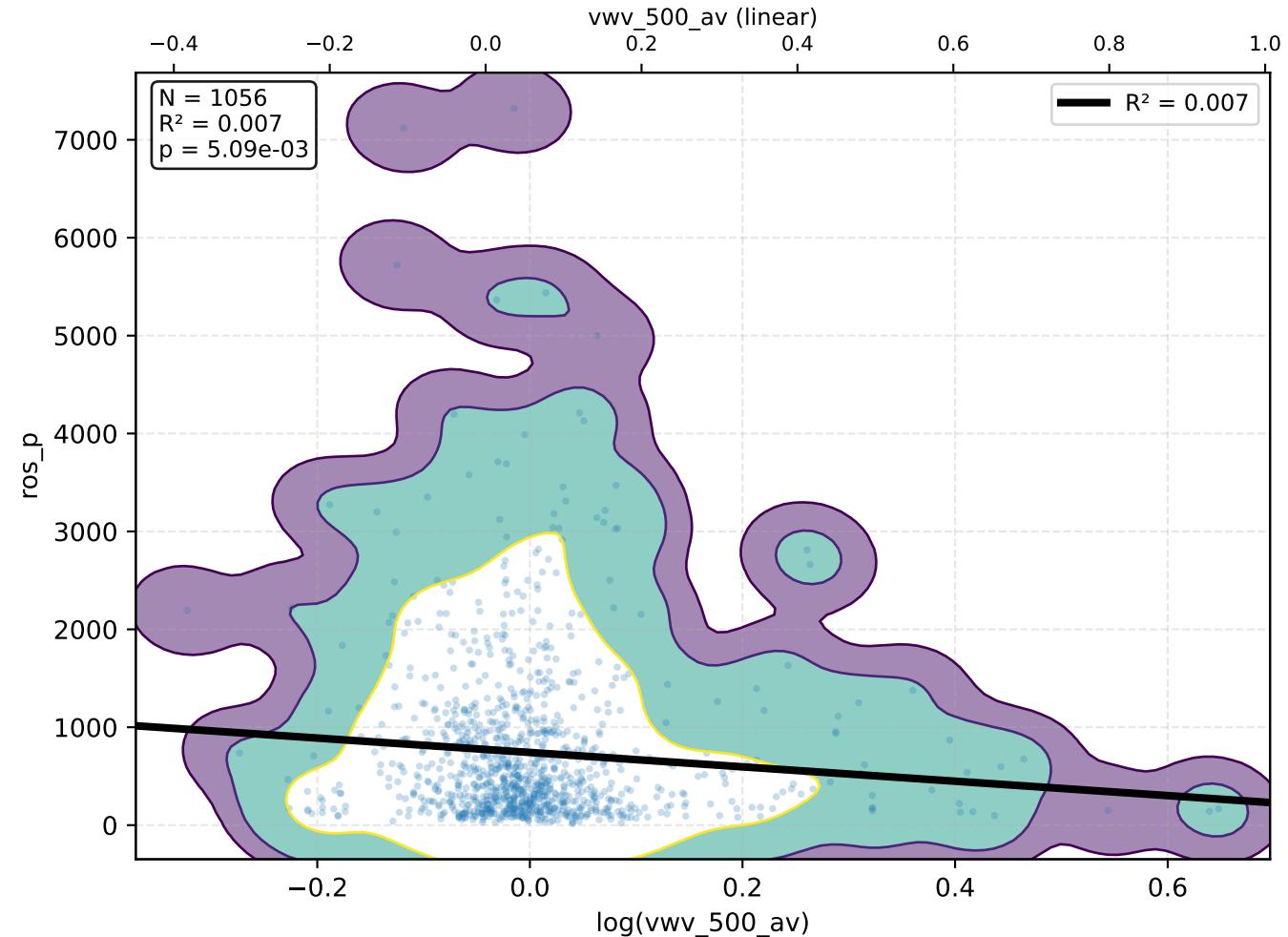


# vwv\_500\_av – KDE Density + Regressão

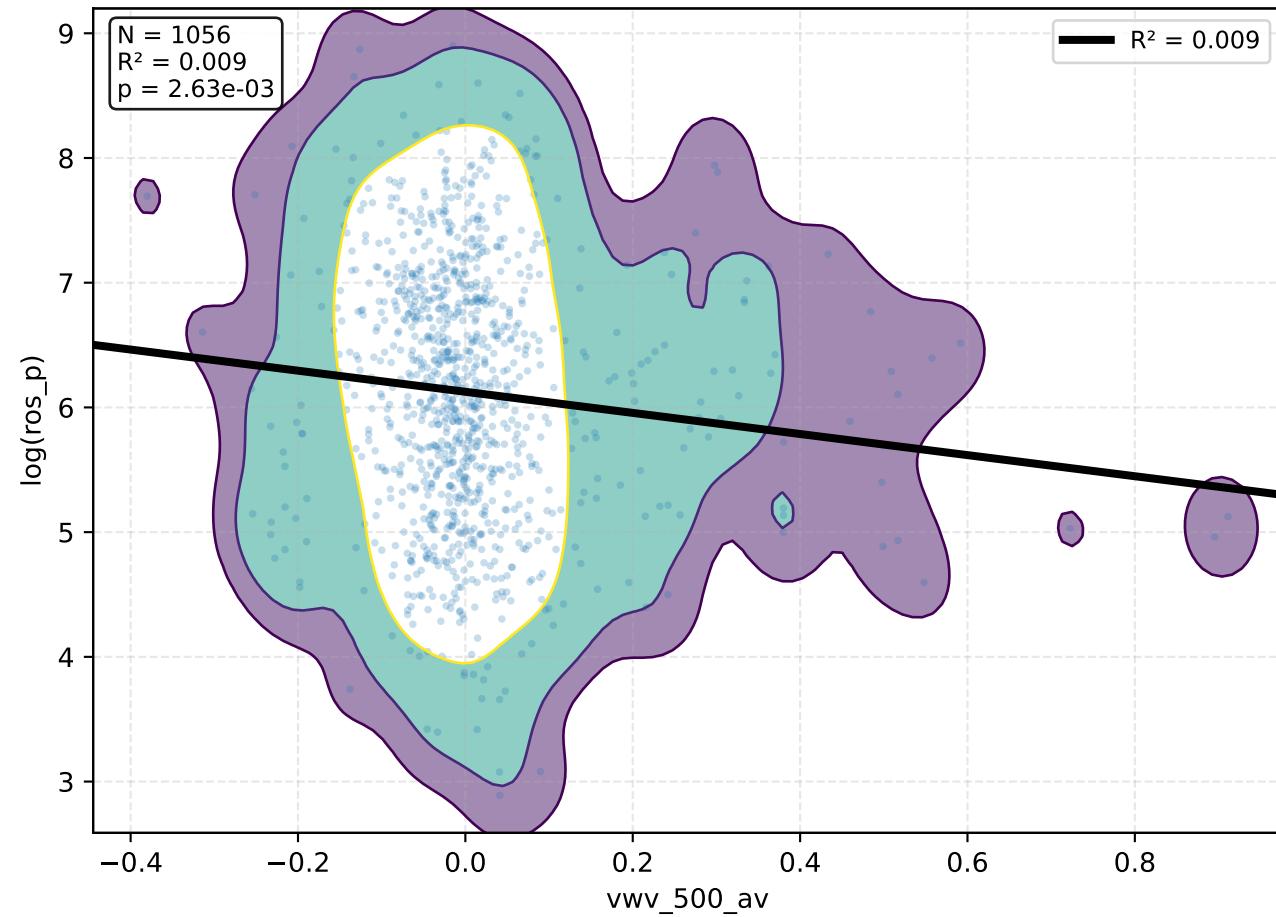
**ros\_p vs vwv\_500\_av**



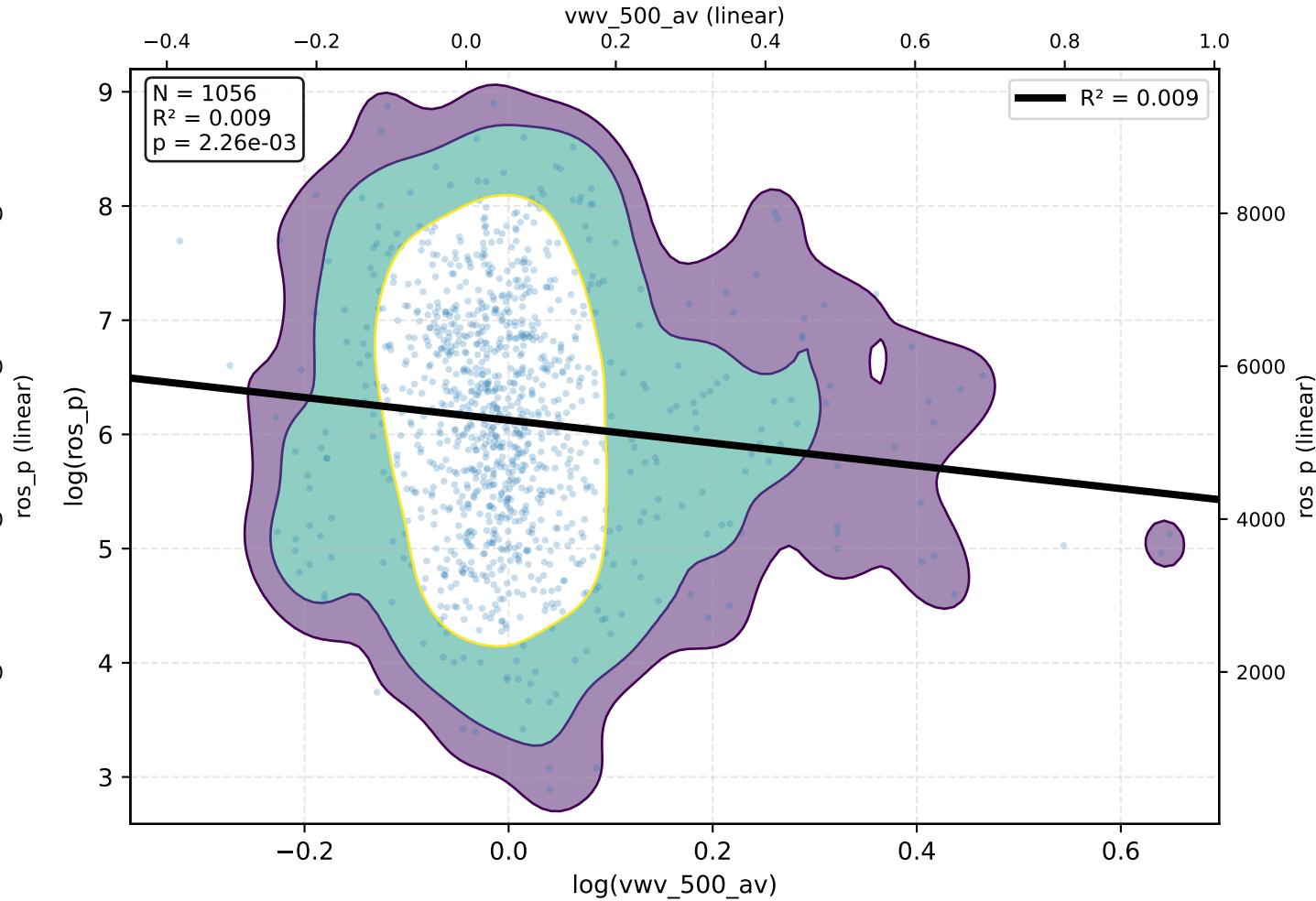
**ros\_p vs log(vwv\_500\_av)**



**log(ros\_p) vs vwv\_500\_av**

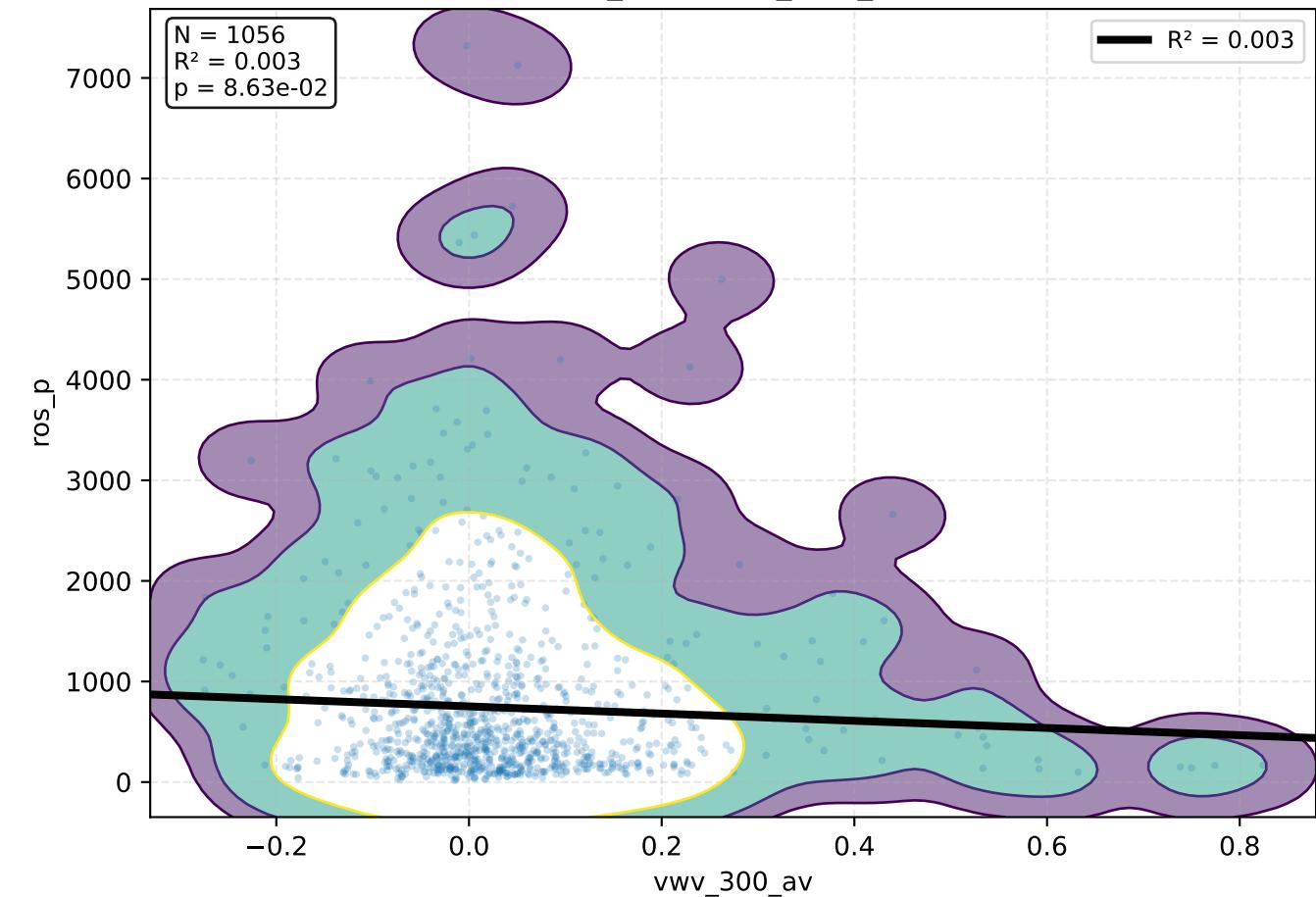


**log(ros\_p) vs log(vwv\_500\_av)**

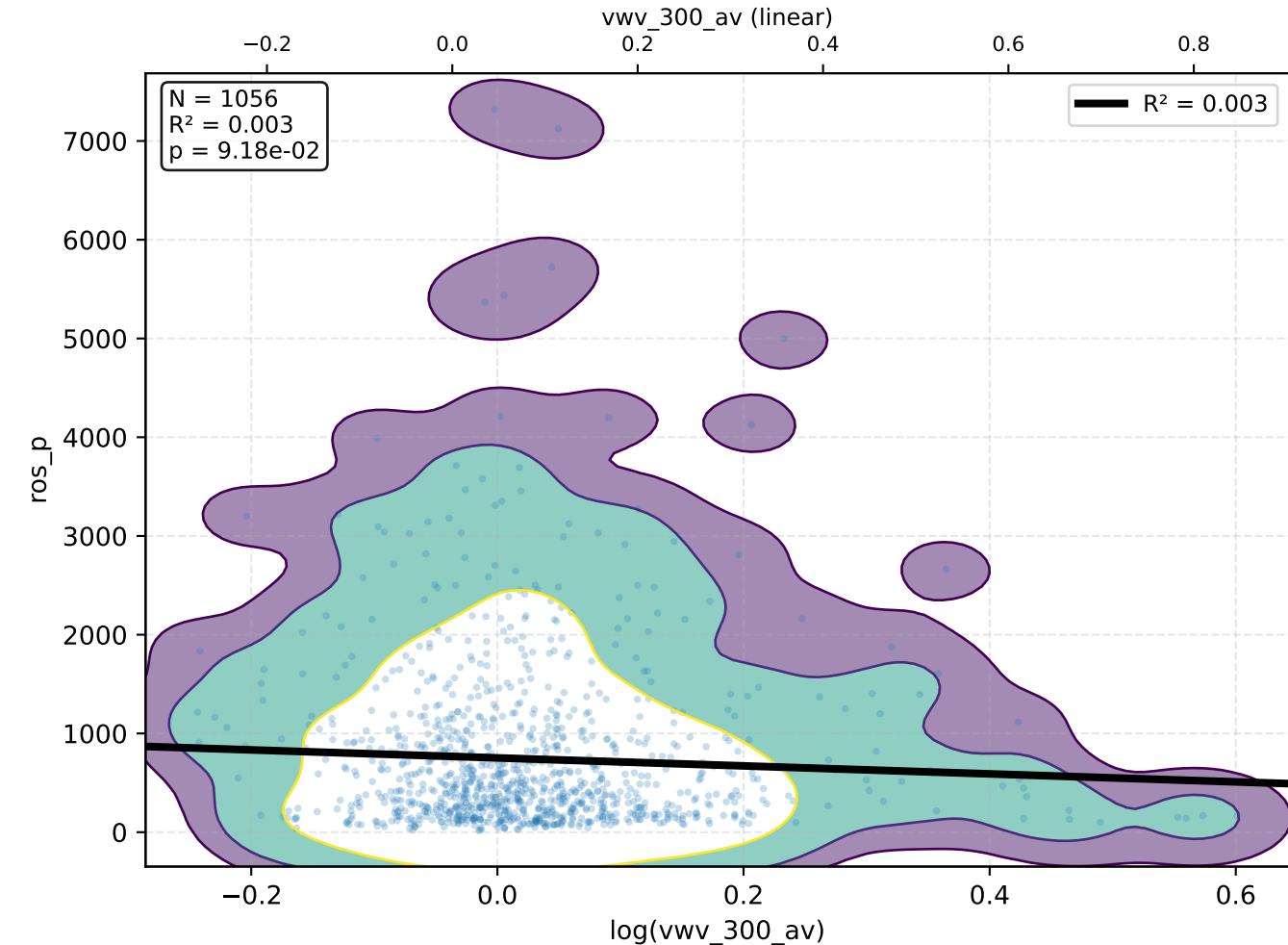


# vwv\_300\_av – KDE Density + Regressão

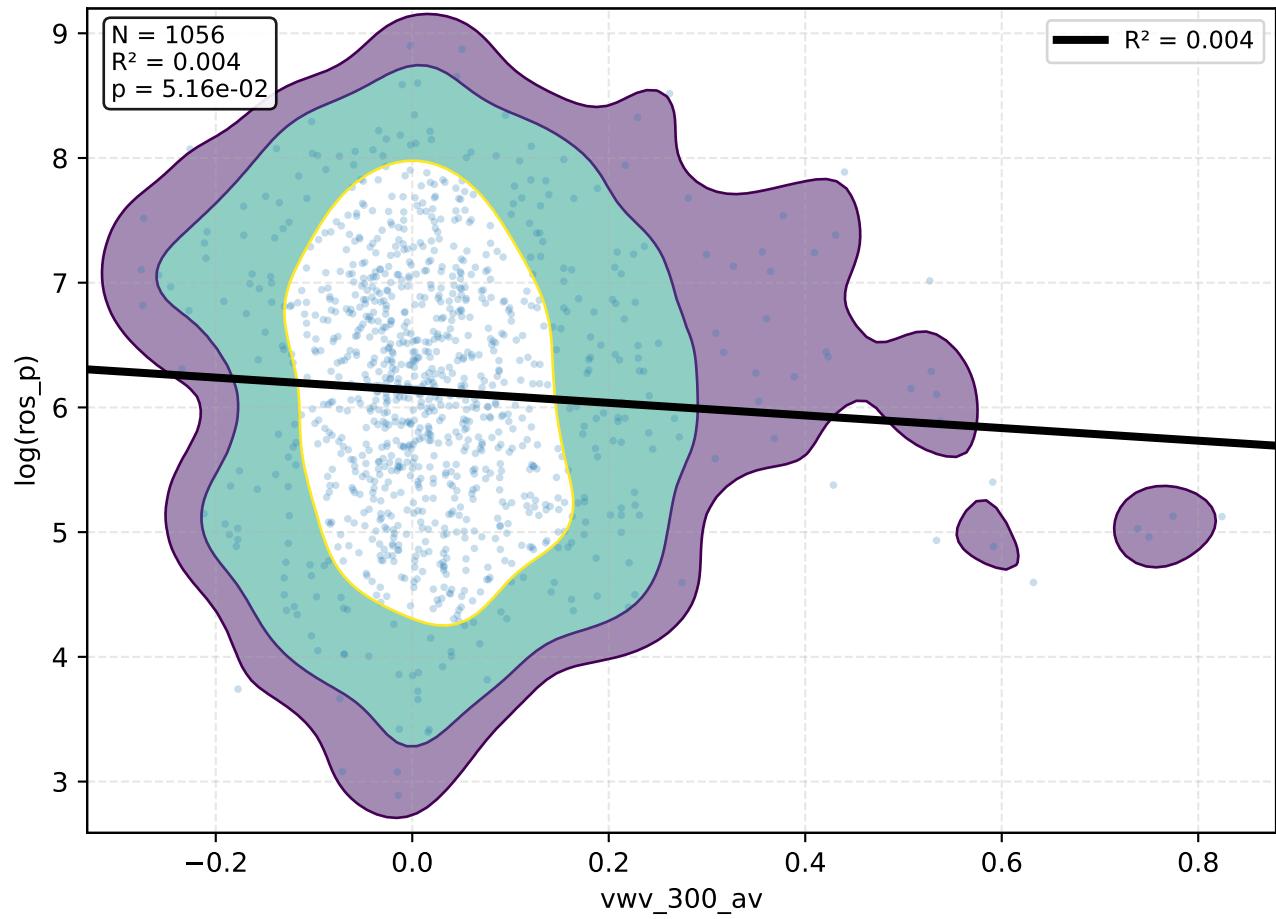
**ros\_p vs vwv\_300\_av**



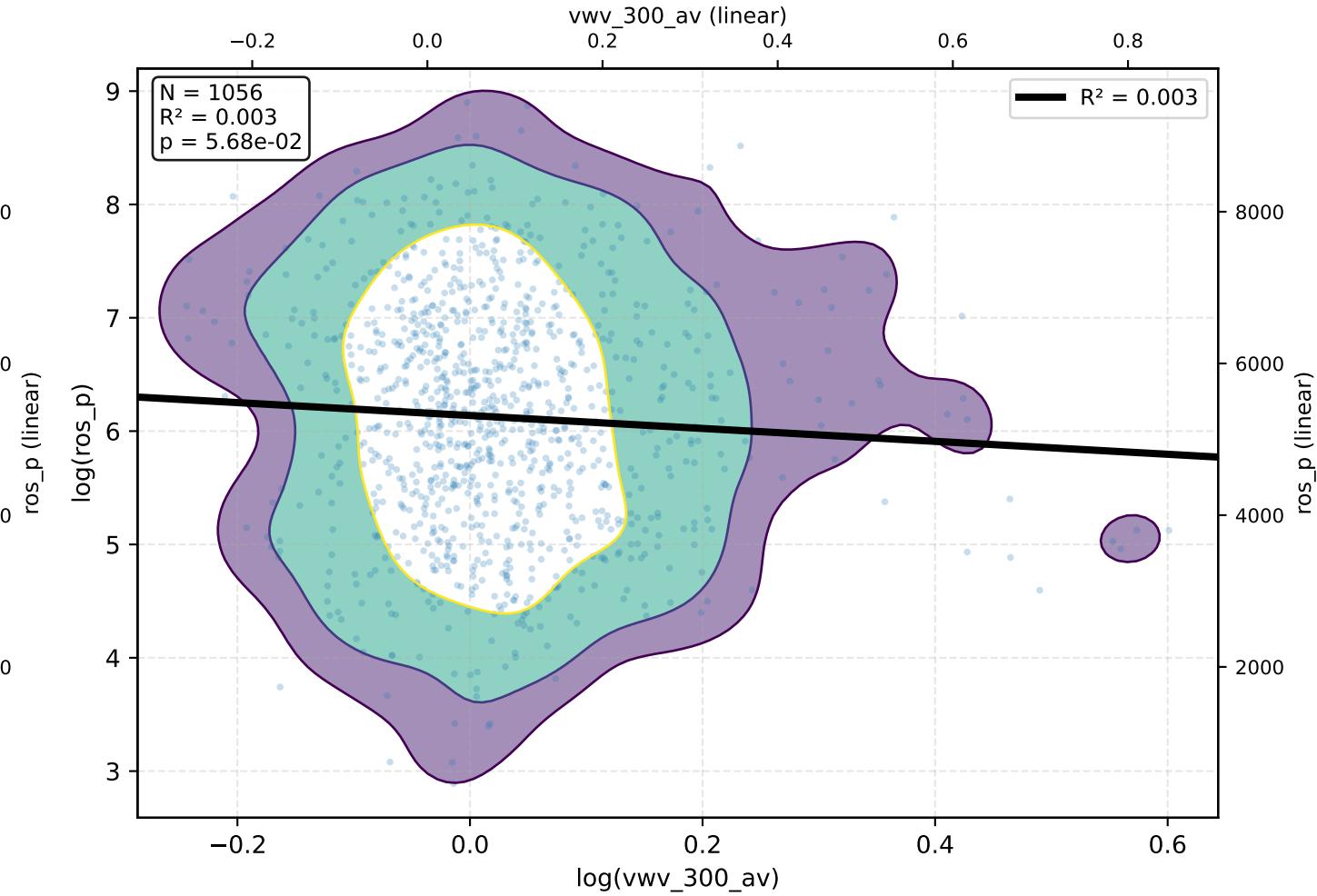
**ros\_p vs log(vwv\_300\_av)**



**log(ros\_p) vs vwv\_300\_av**

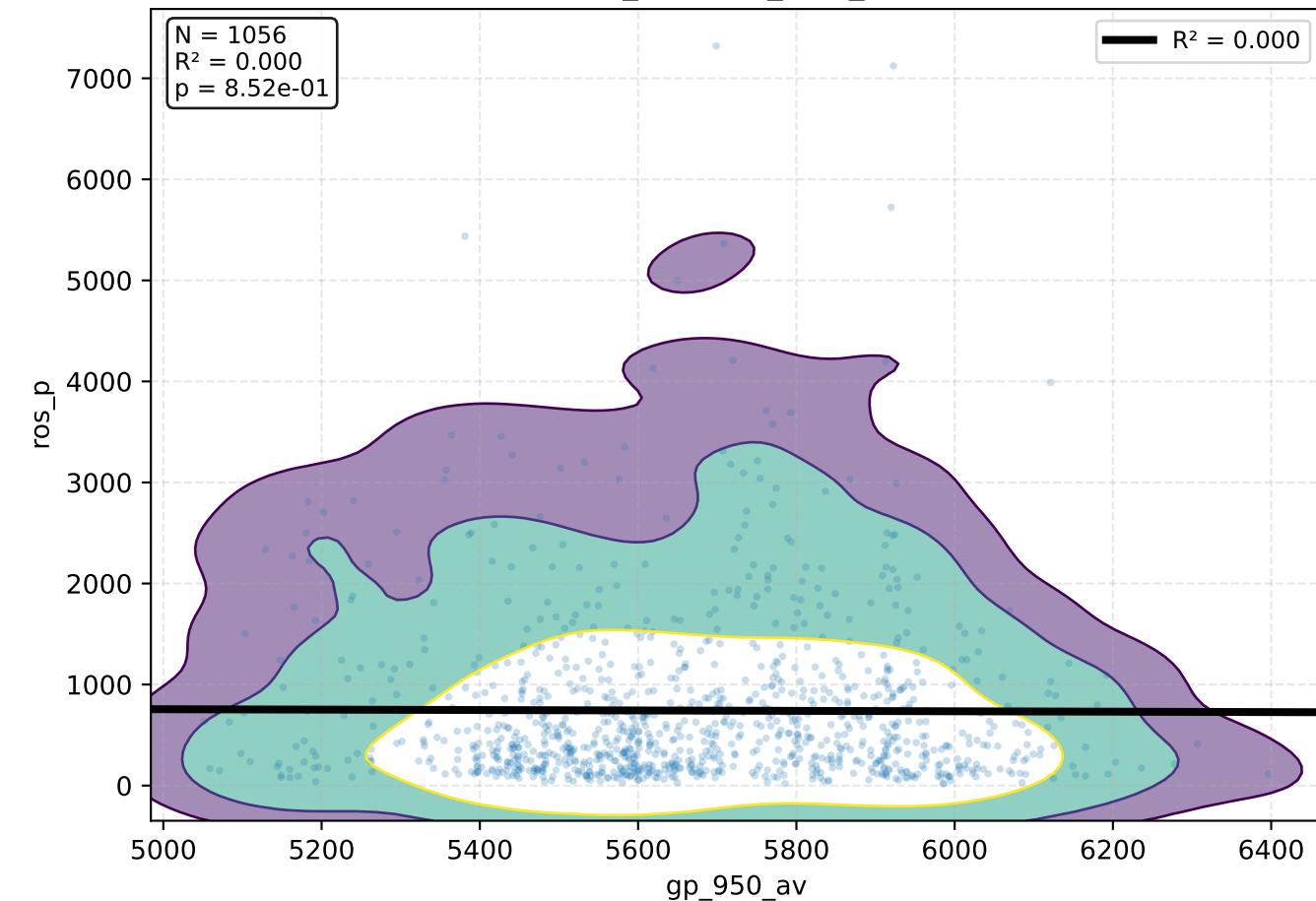


**log(ros\_p) vs log(vwv\_300\_av)**

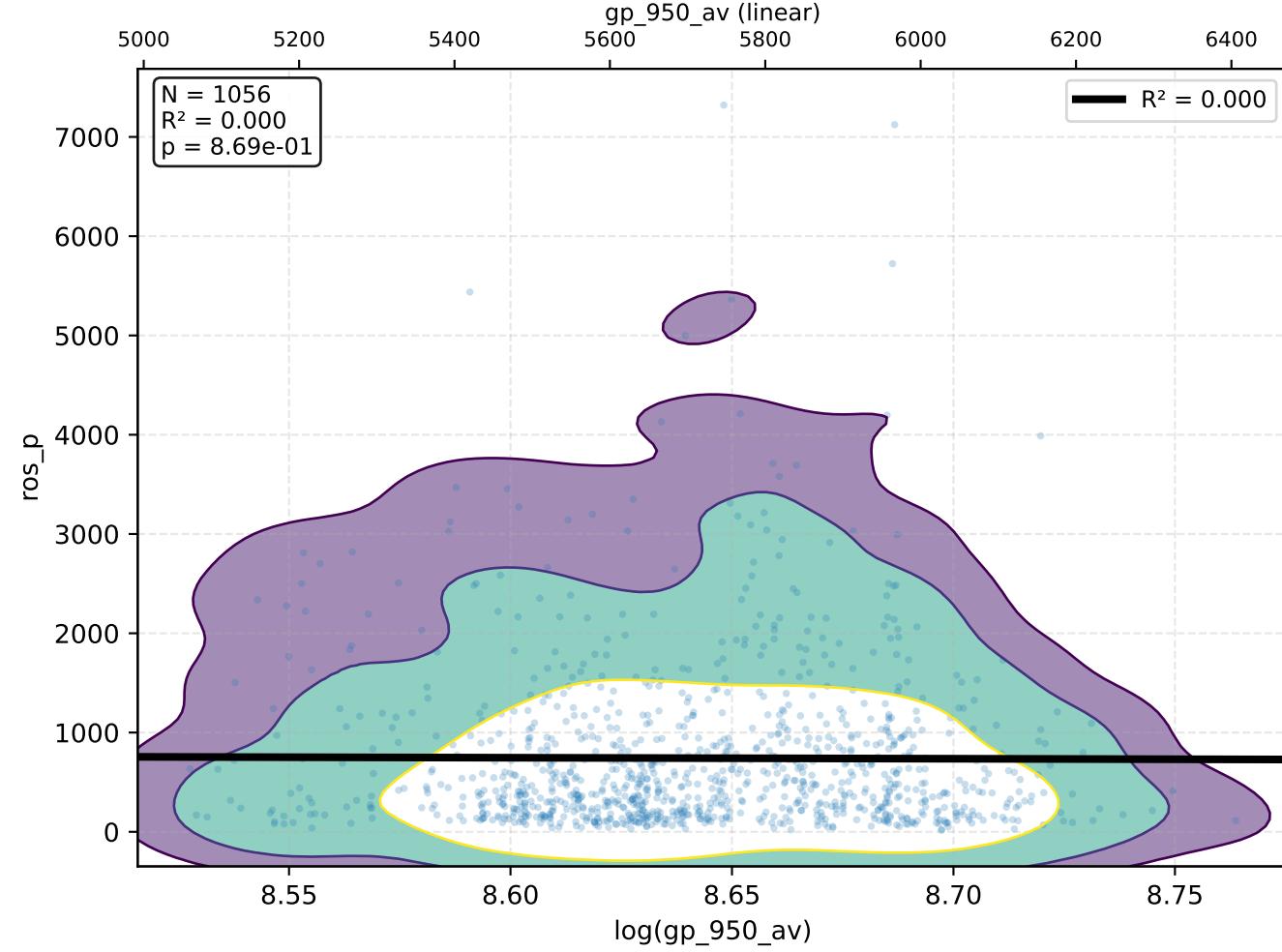


# gp\_950\_av - KDE Density + Regressão

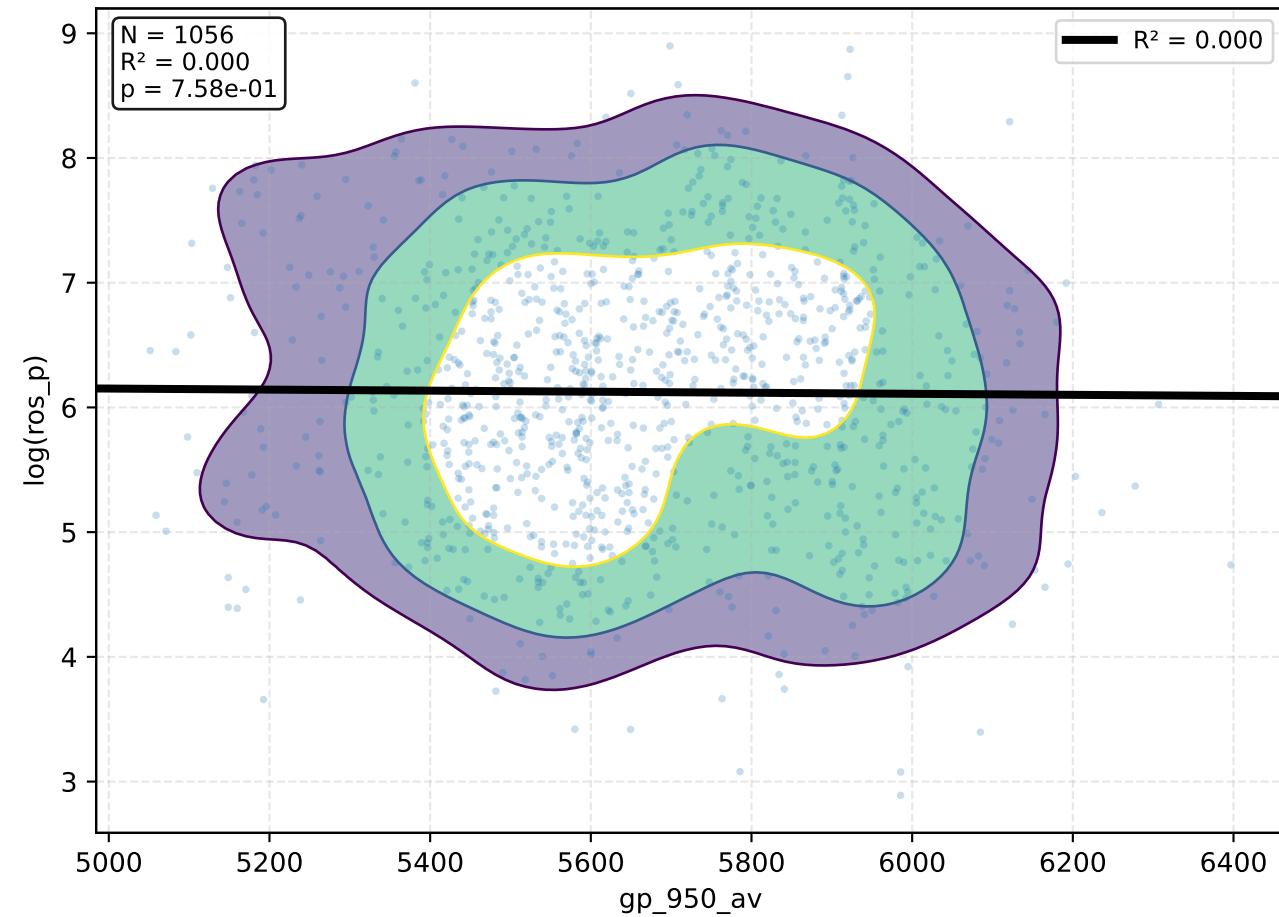
**ros\_p vs gp\_950\_av**



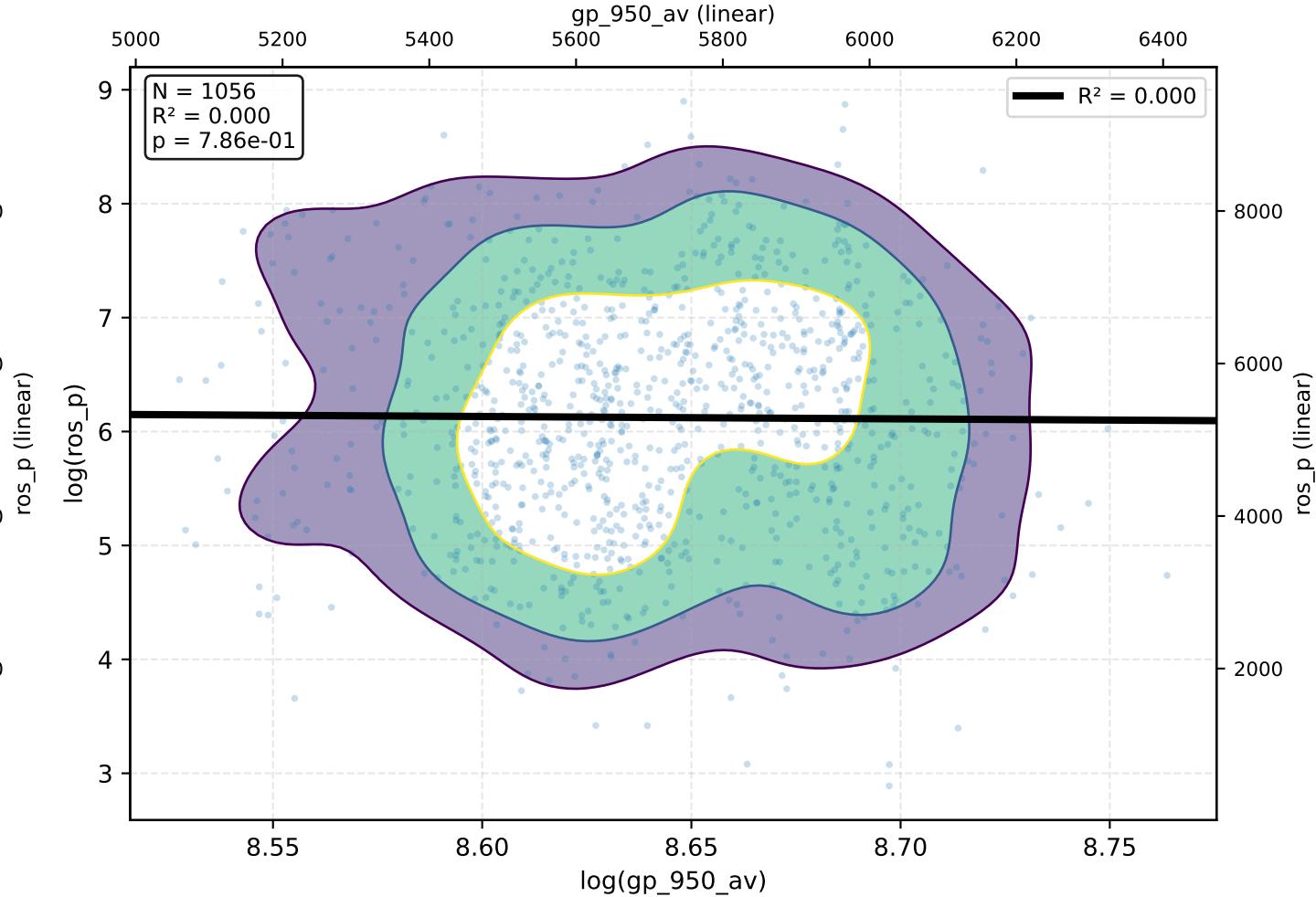
**ros\_p vs log(gp\_950\_av)**



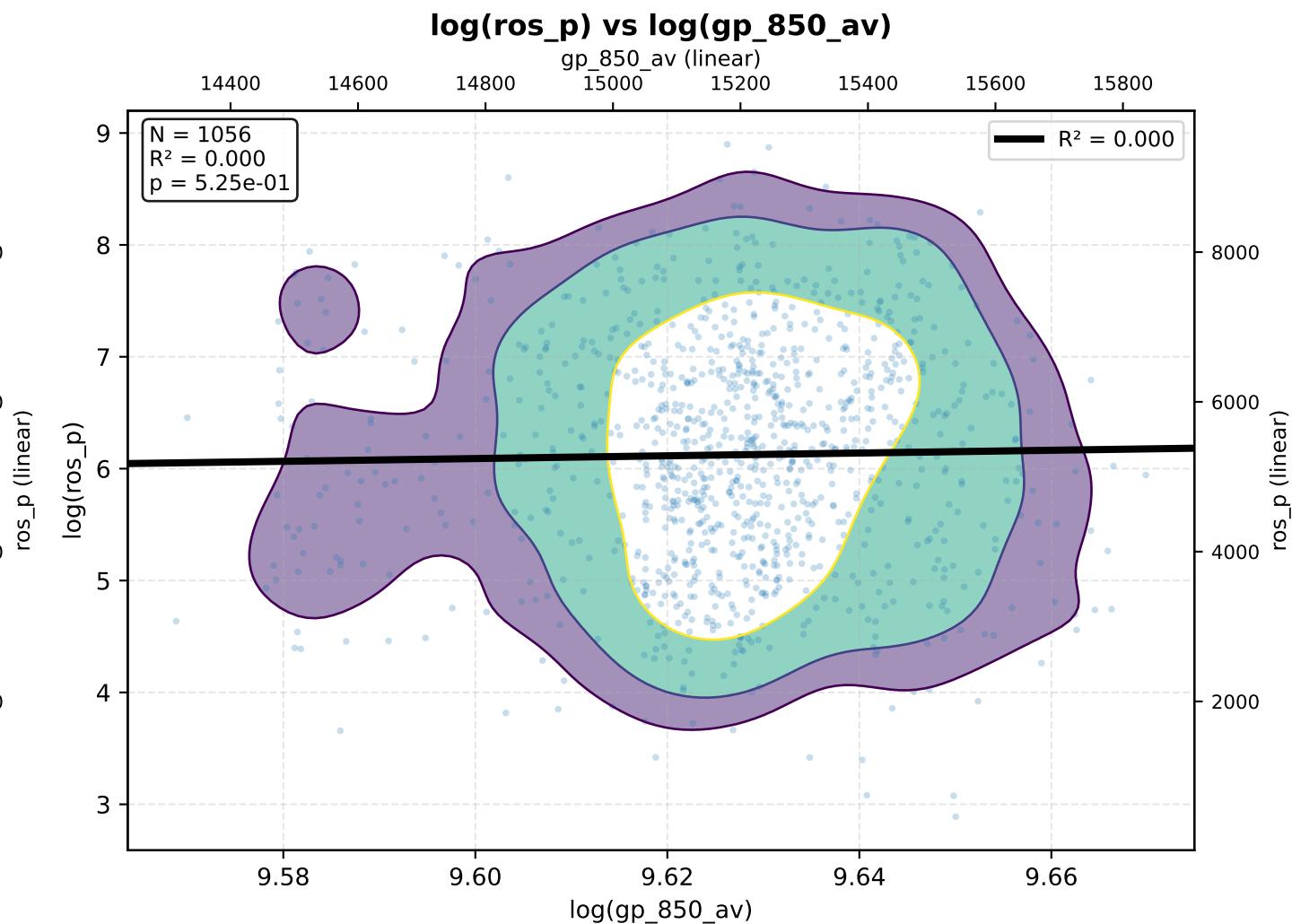
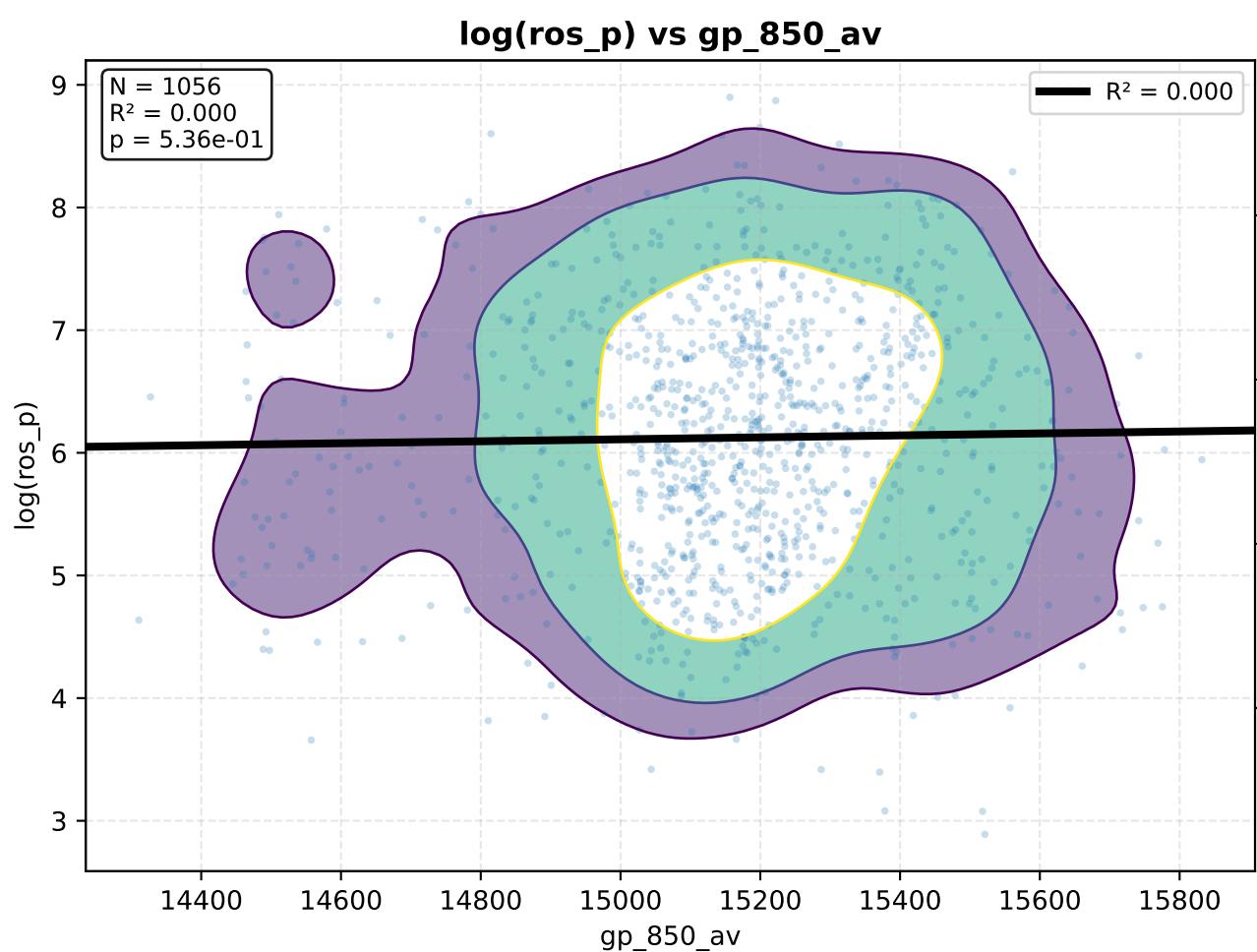
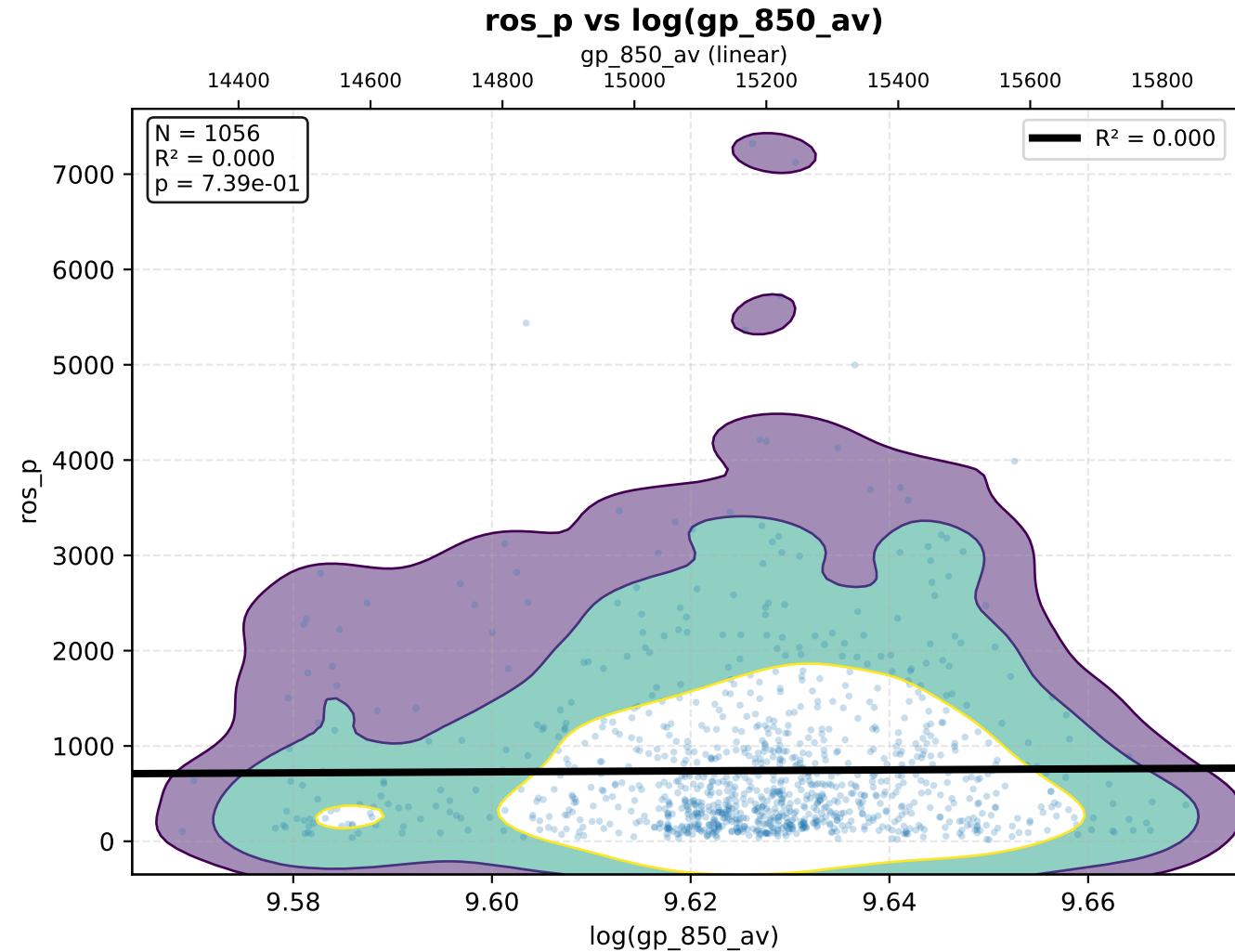
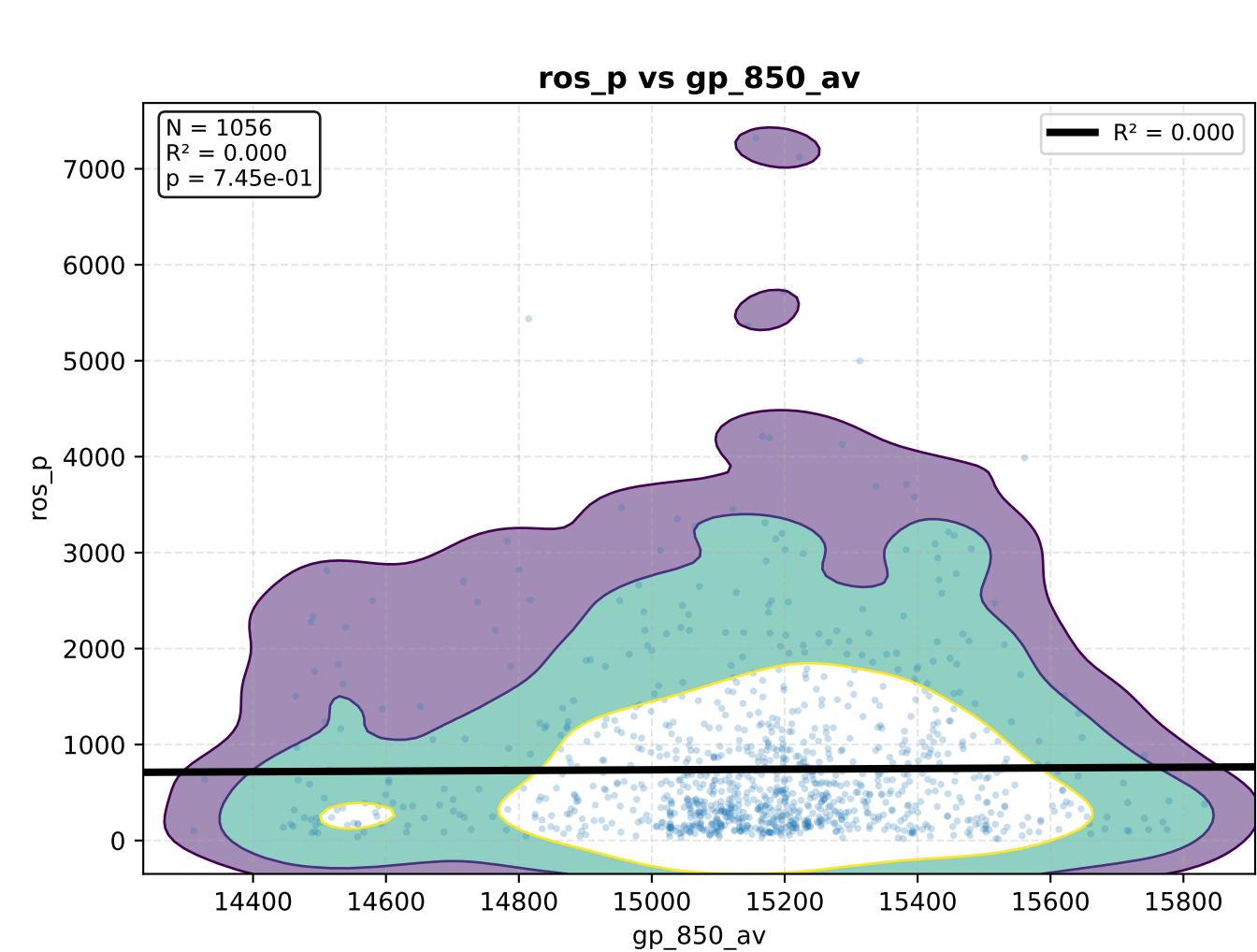
**log(ros\_p) vs gp\_950\_av**



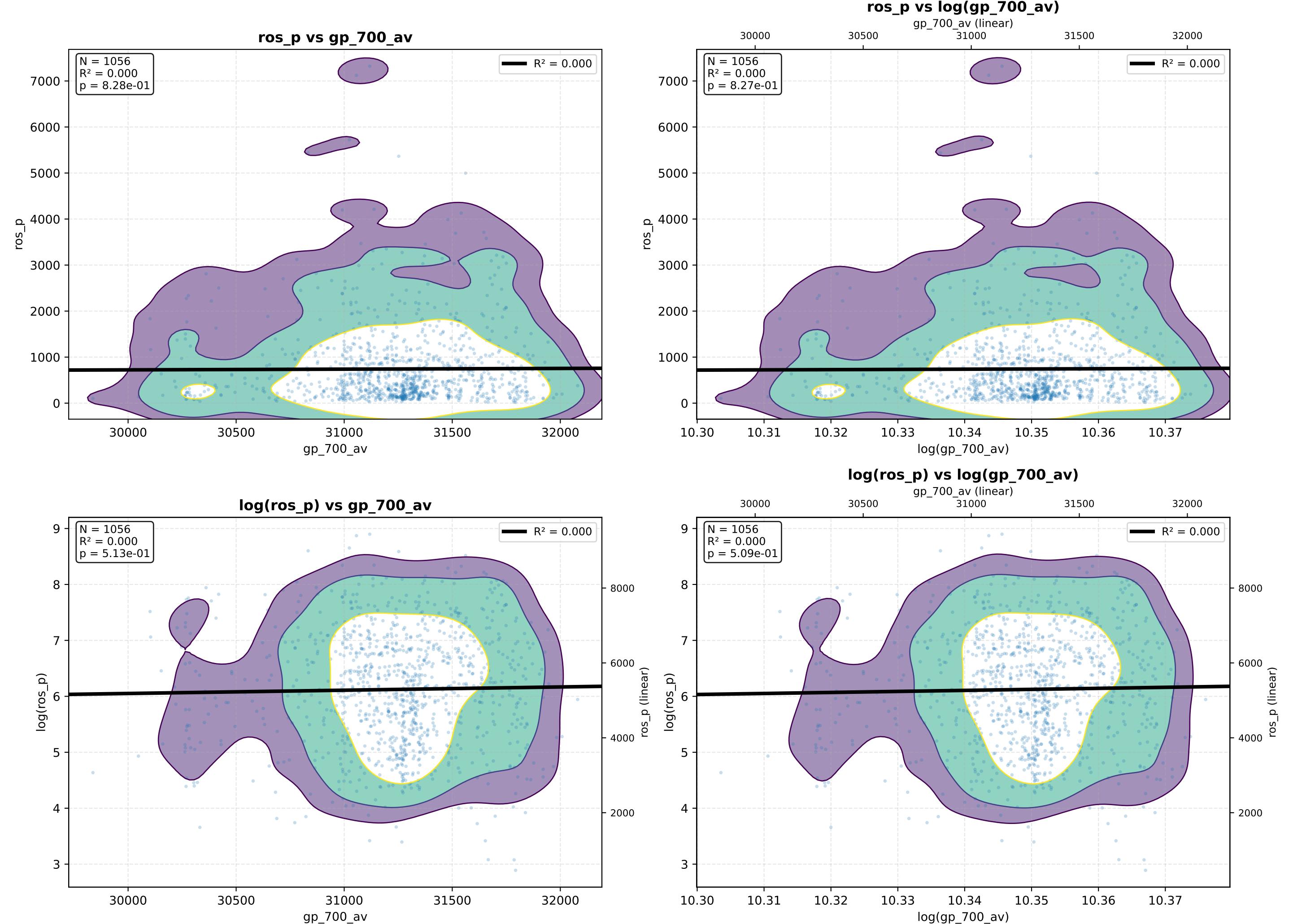
**log(ros\_p) vs log(gp\_950\_av)**



# gp\_850\_av - KDE Density + Regressão

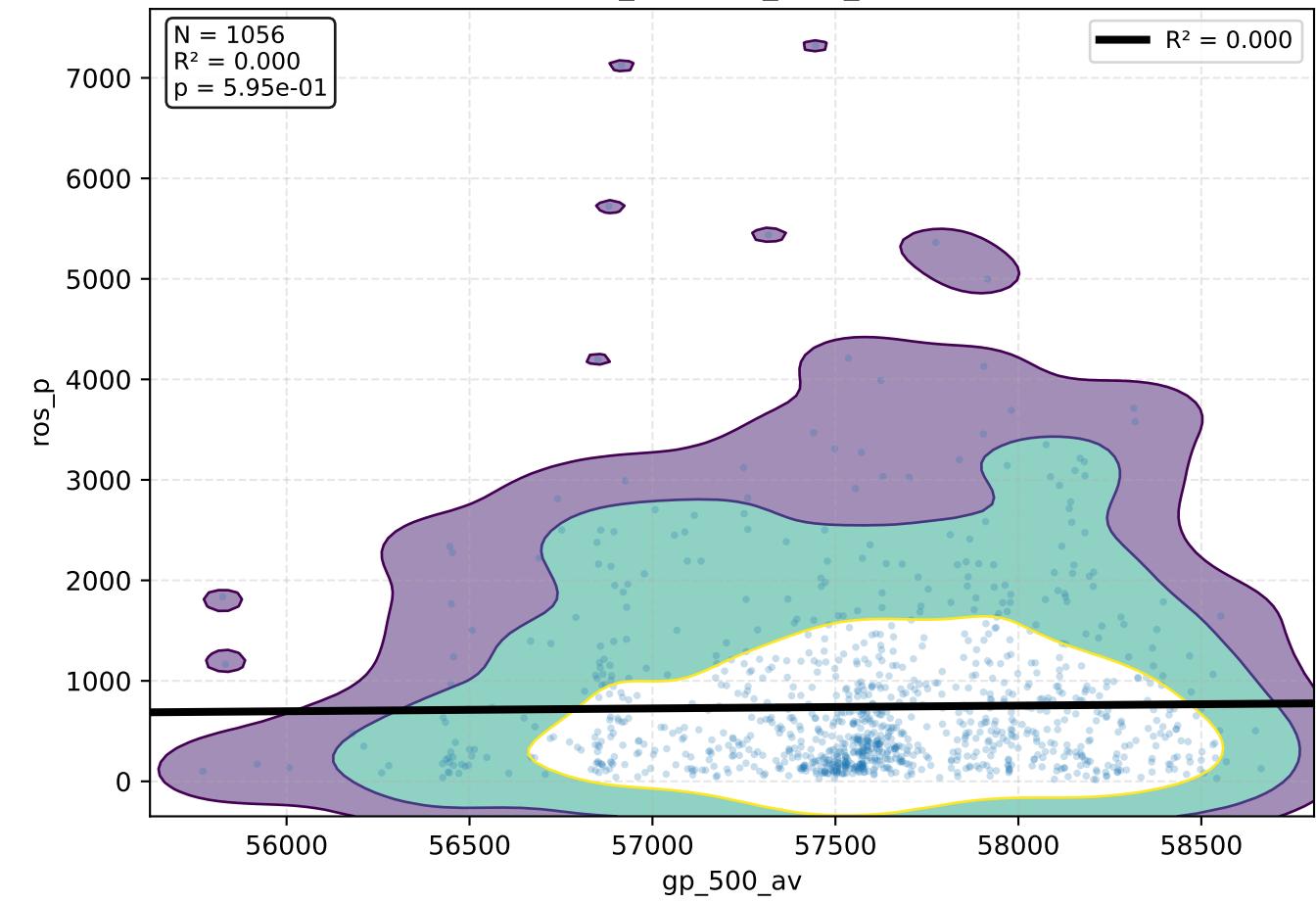


# gp\_700\_av - KDE Density + Regressão

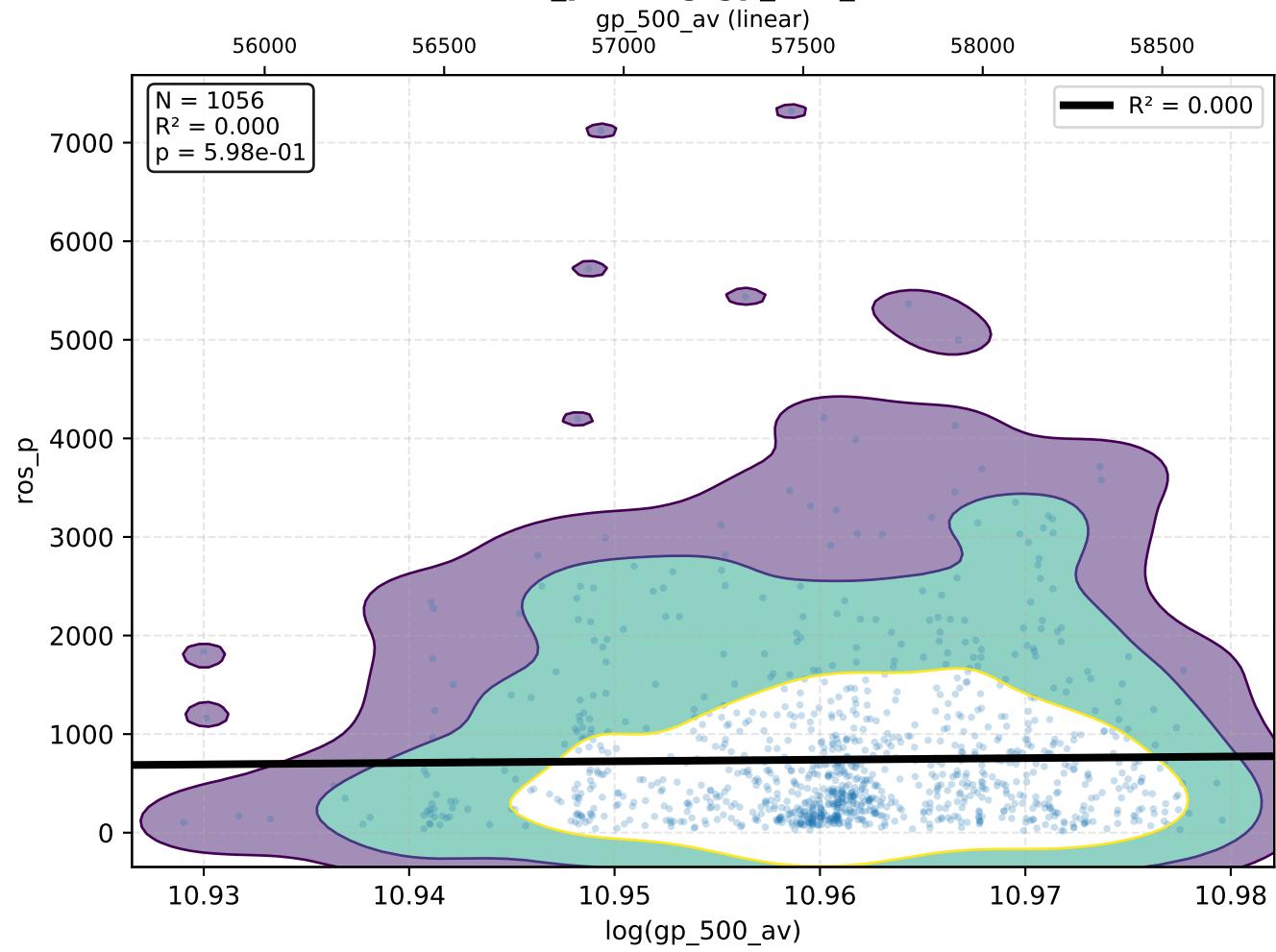


# gp\_500\_av - KDE Density + Regressão

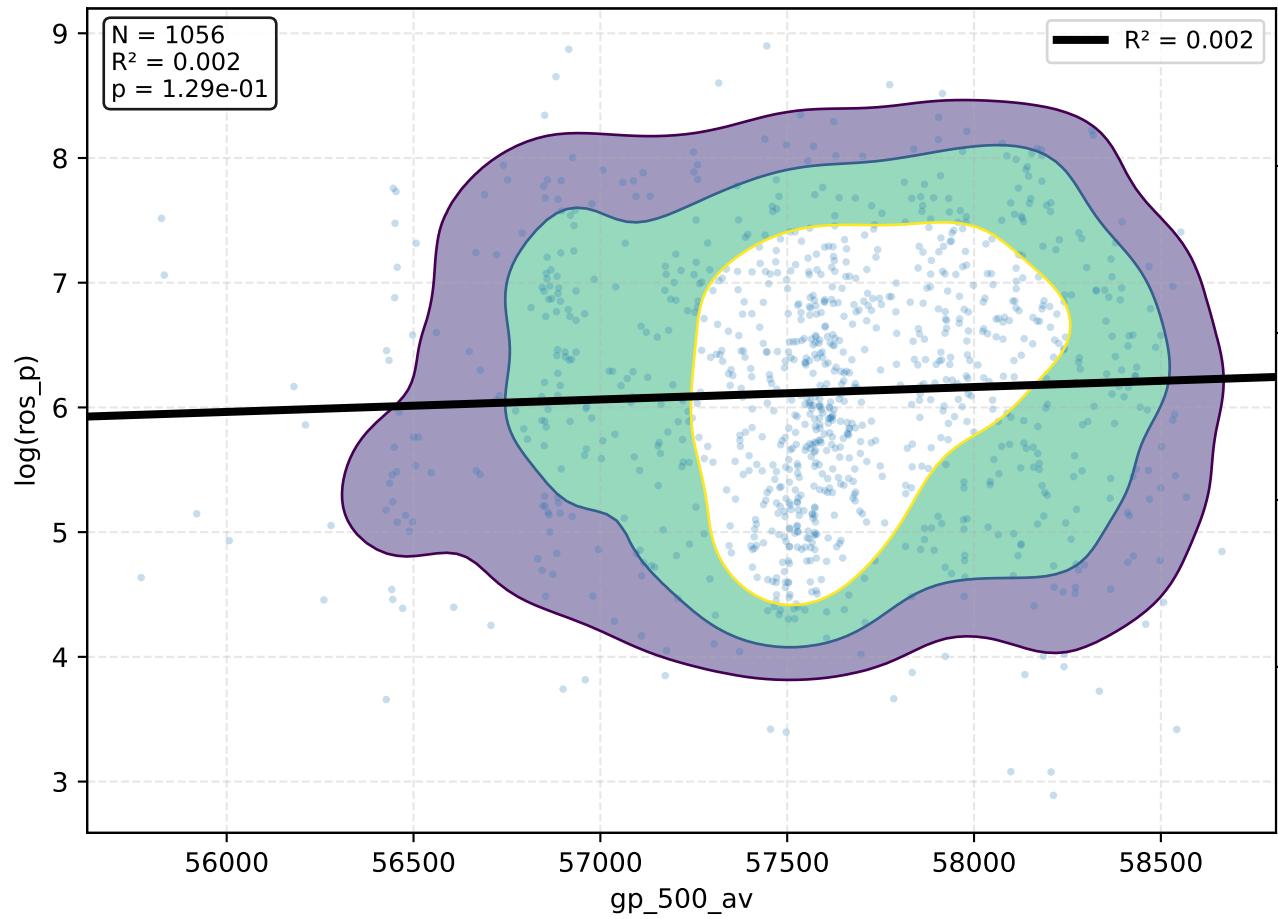
**ros\_p vs gp\_500\_av**



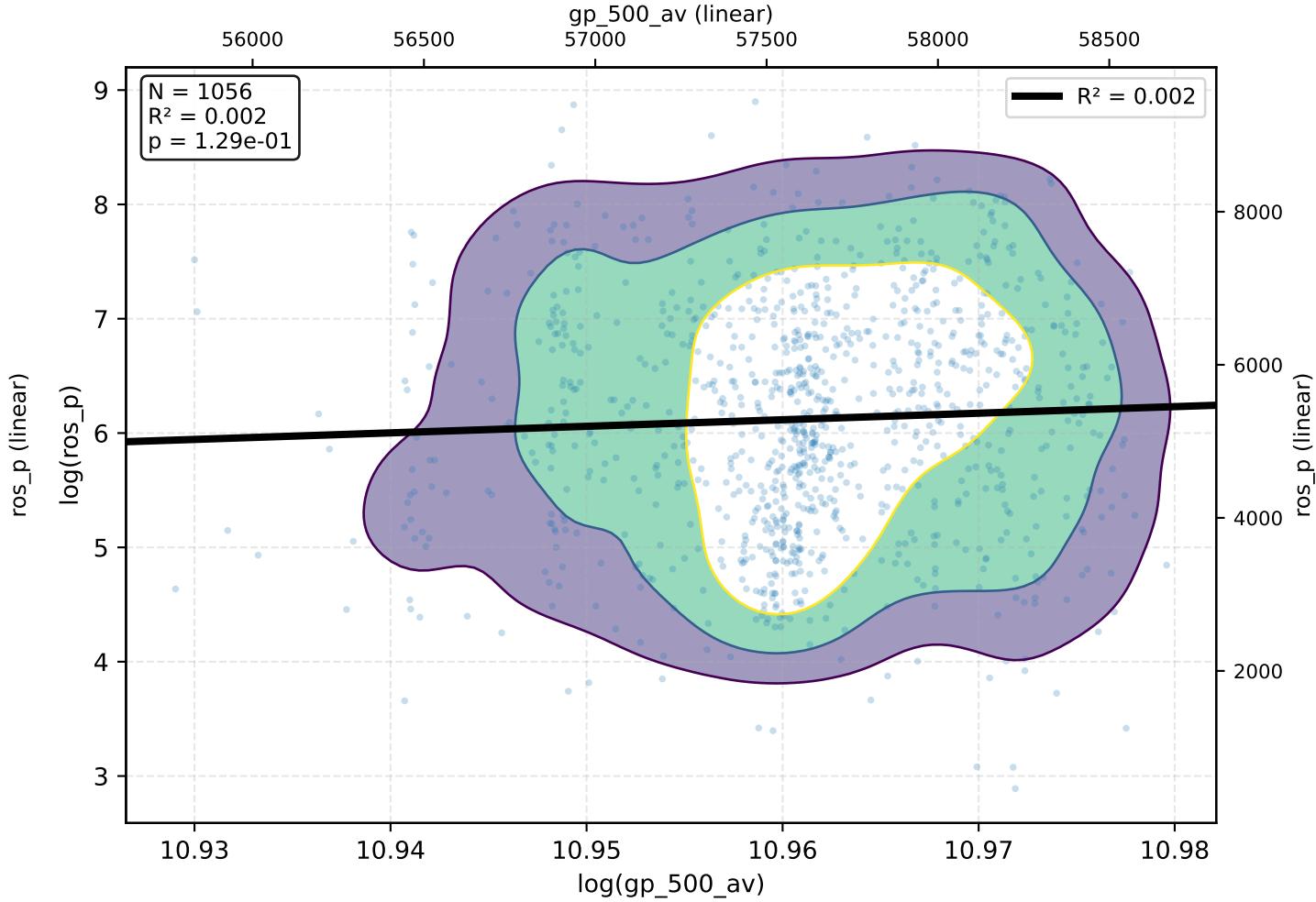
**ros\_p vs log(gp\_500\_av)**



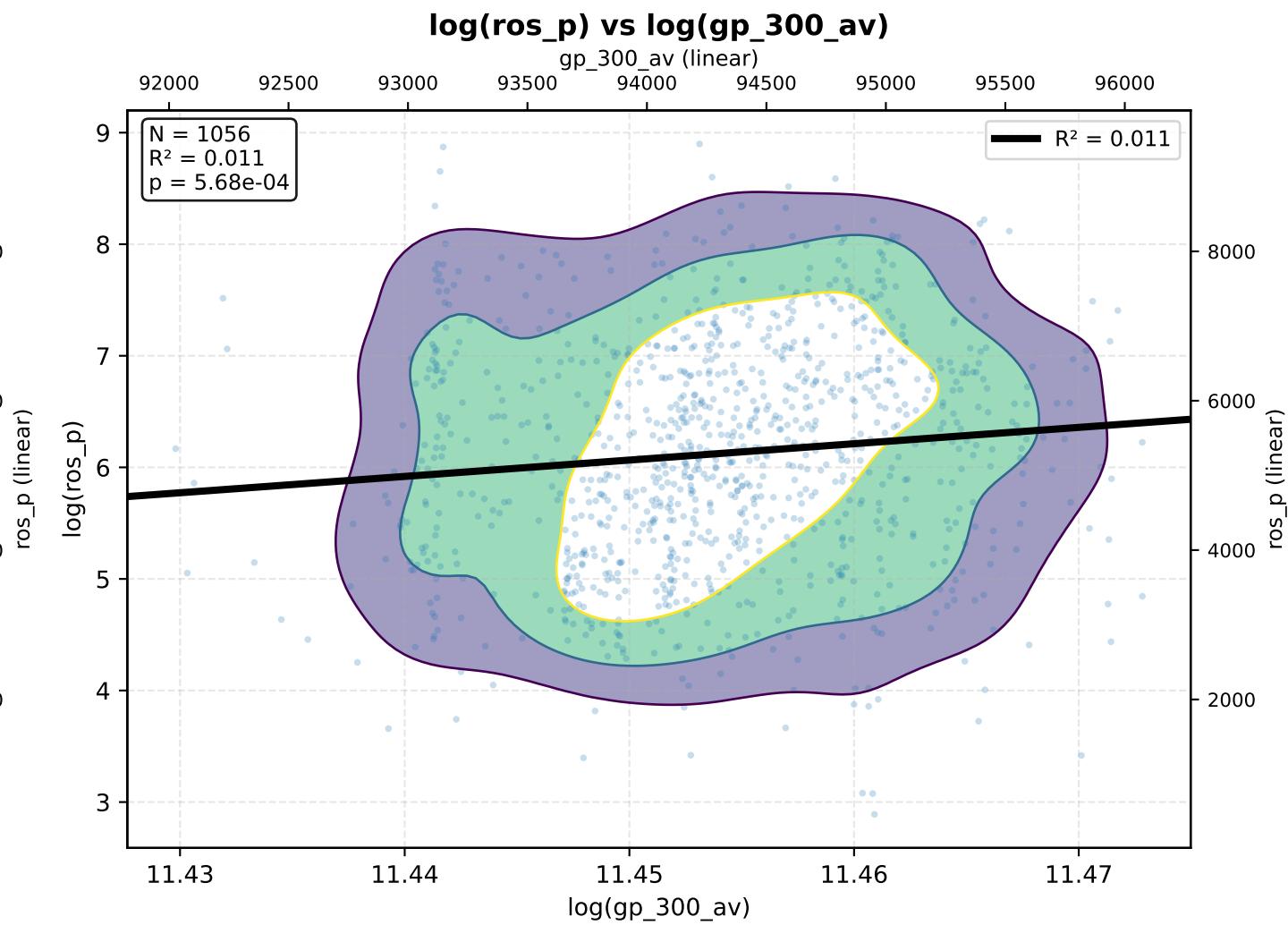
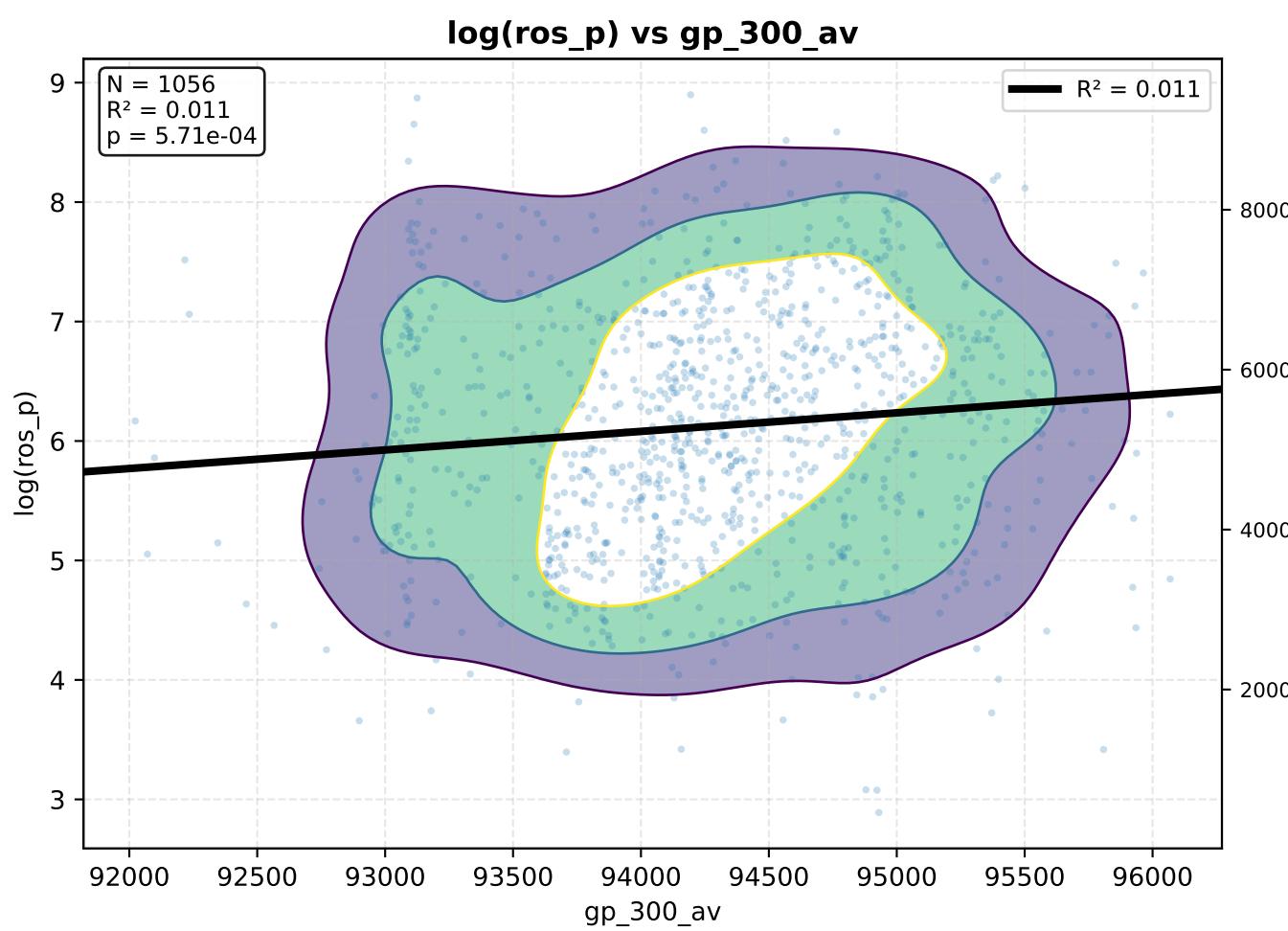
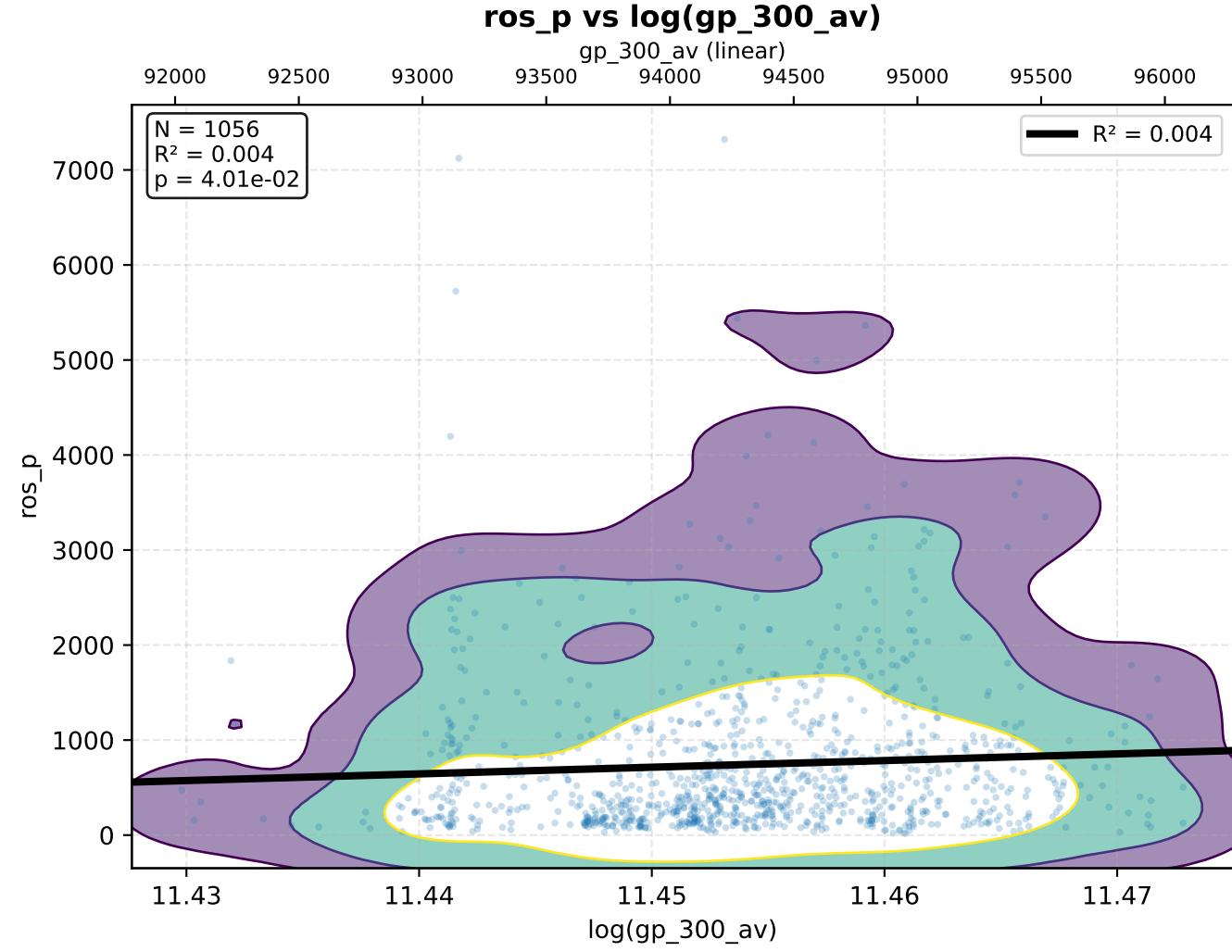
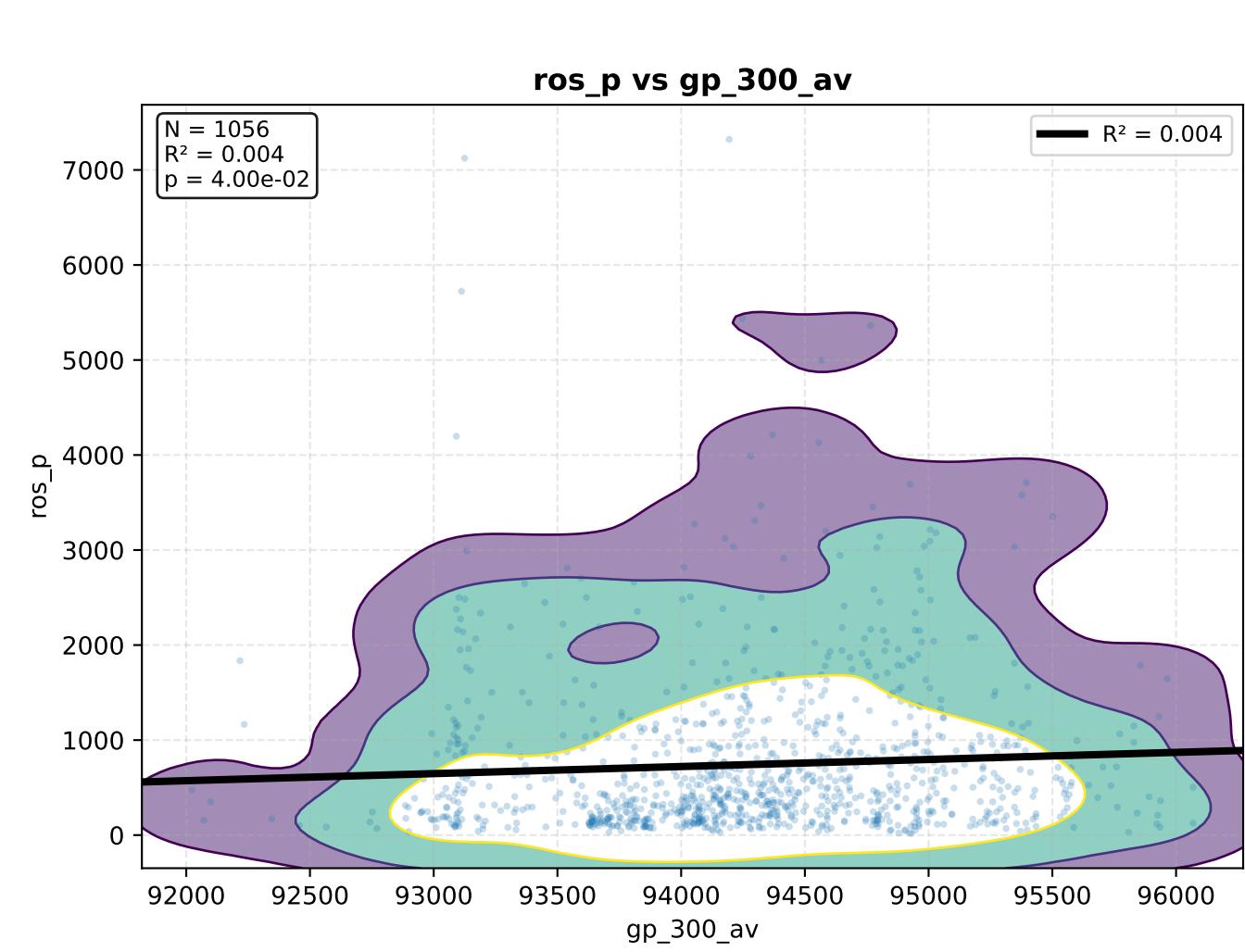
**log(ros\_p) vs gp\_500\_av**



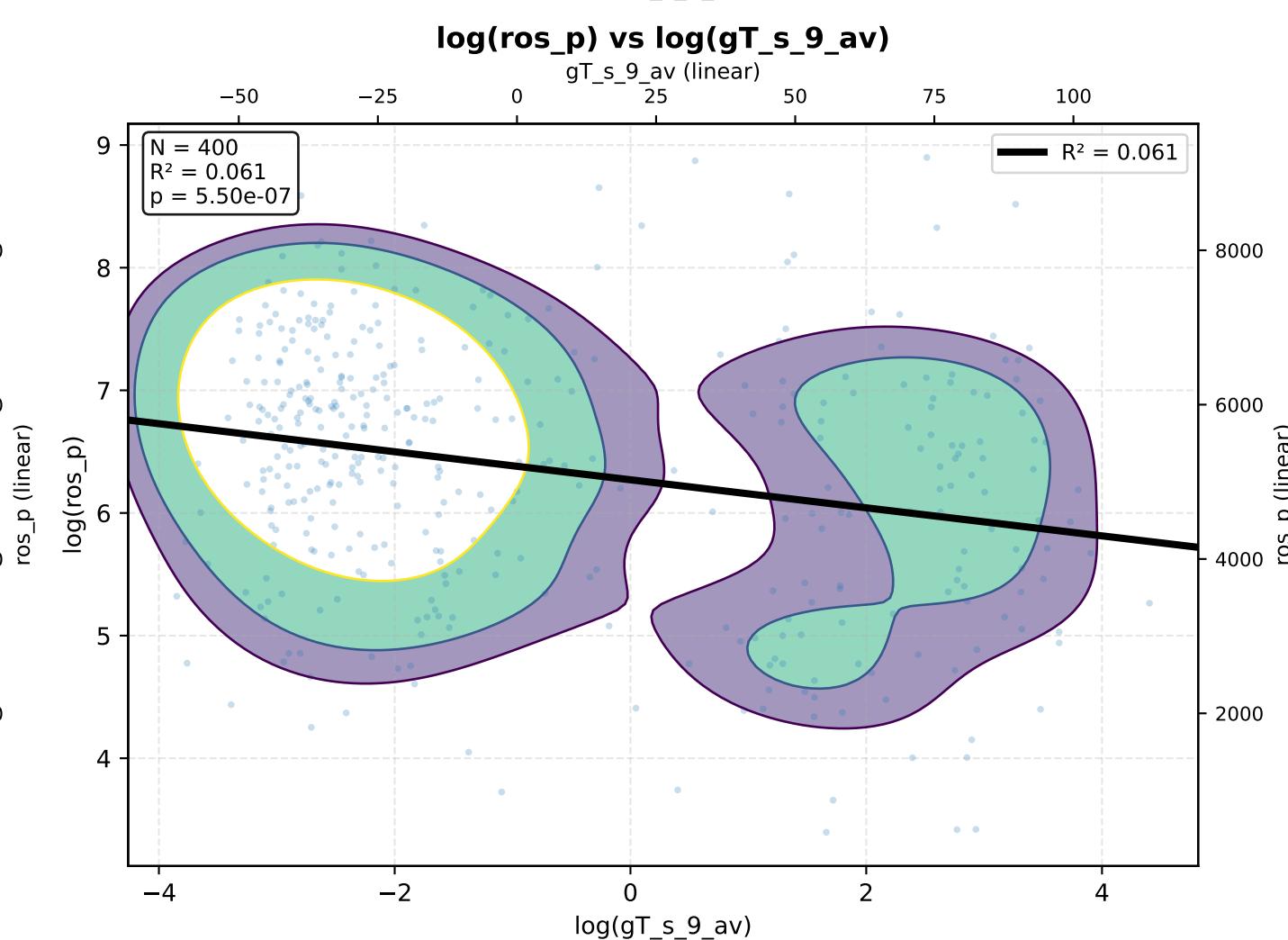
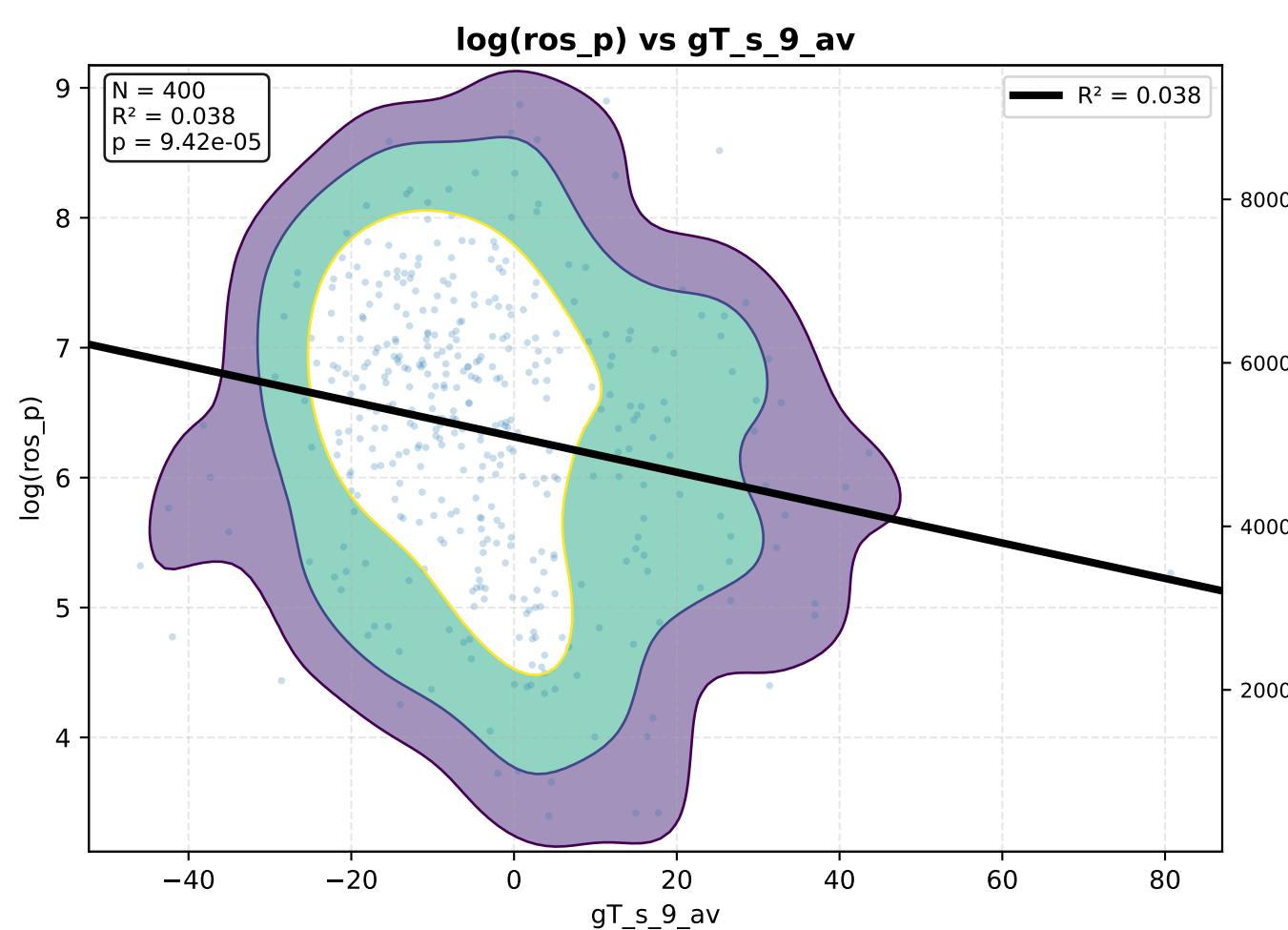
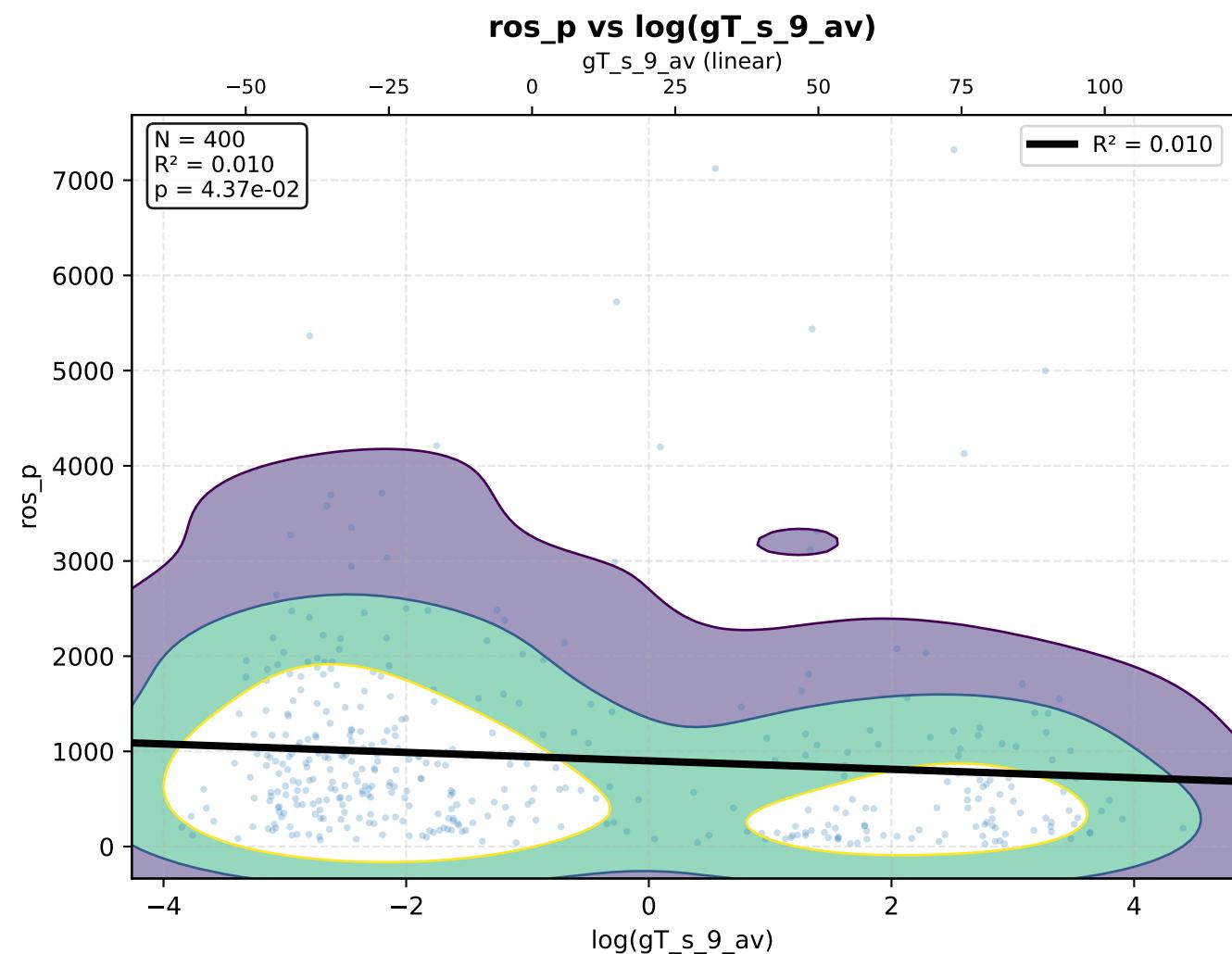
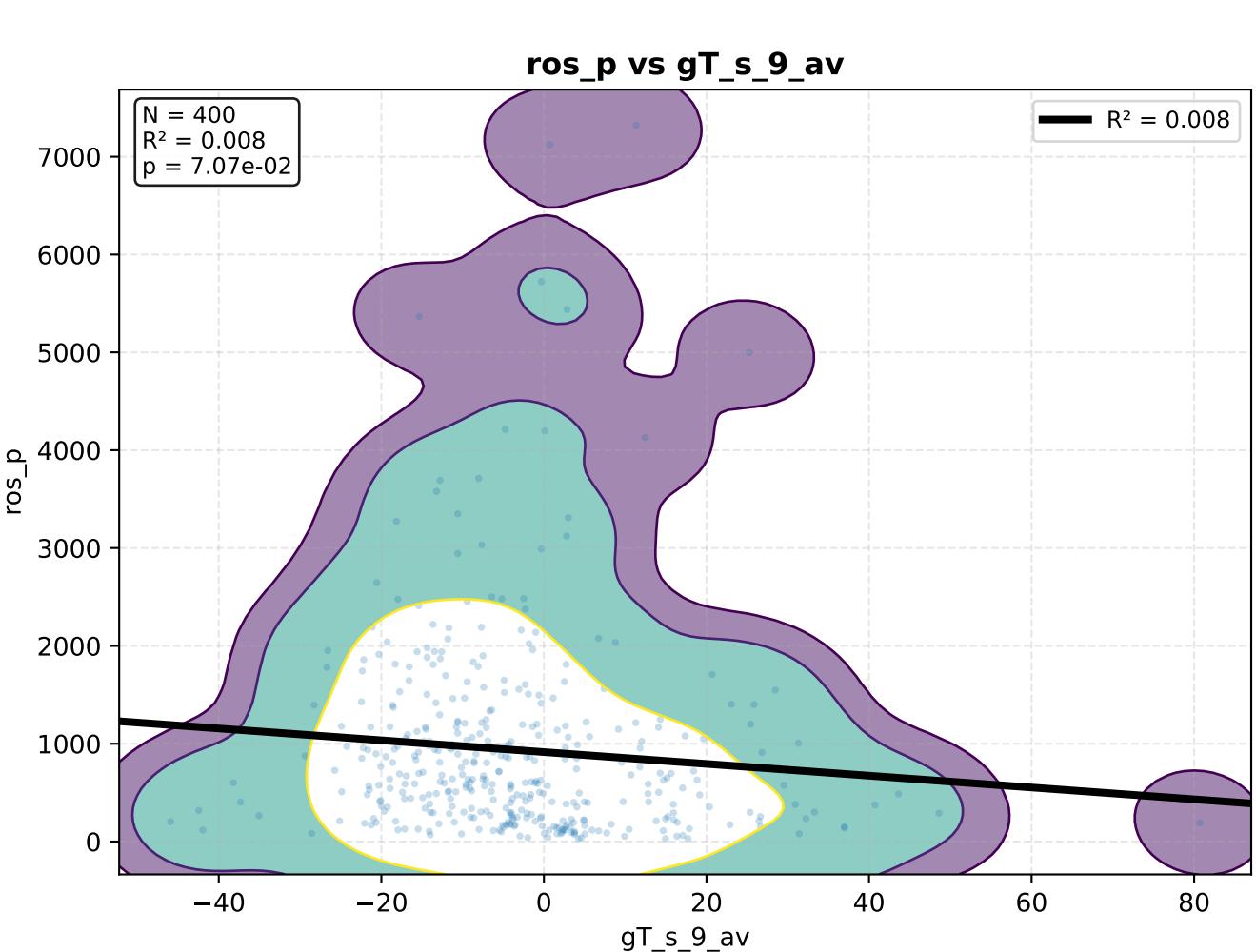
**log(ros\_p) vs log(gp\_500\_av)**



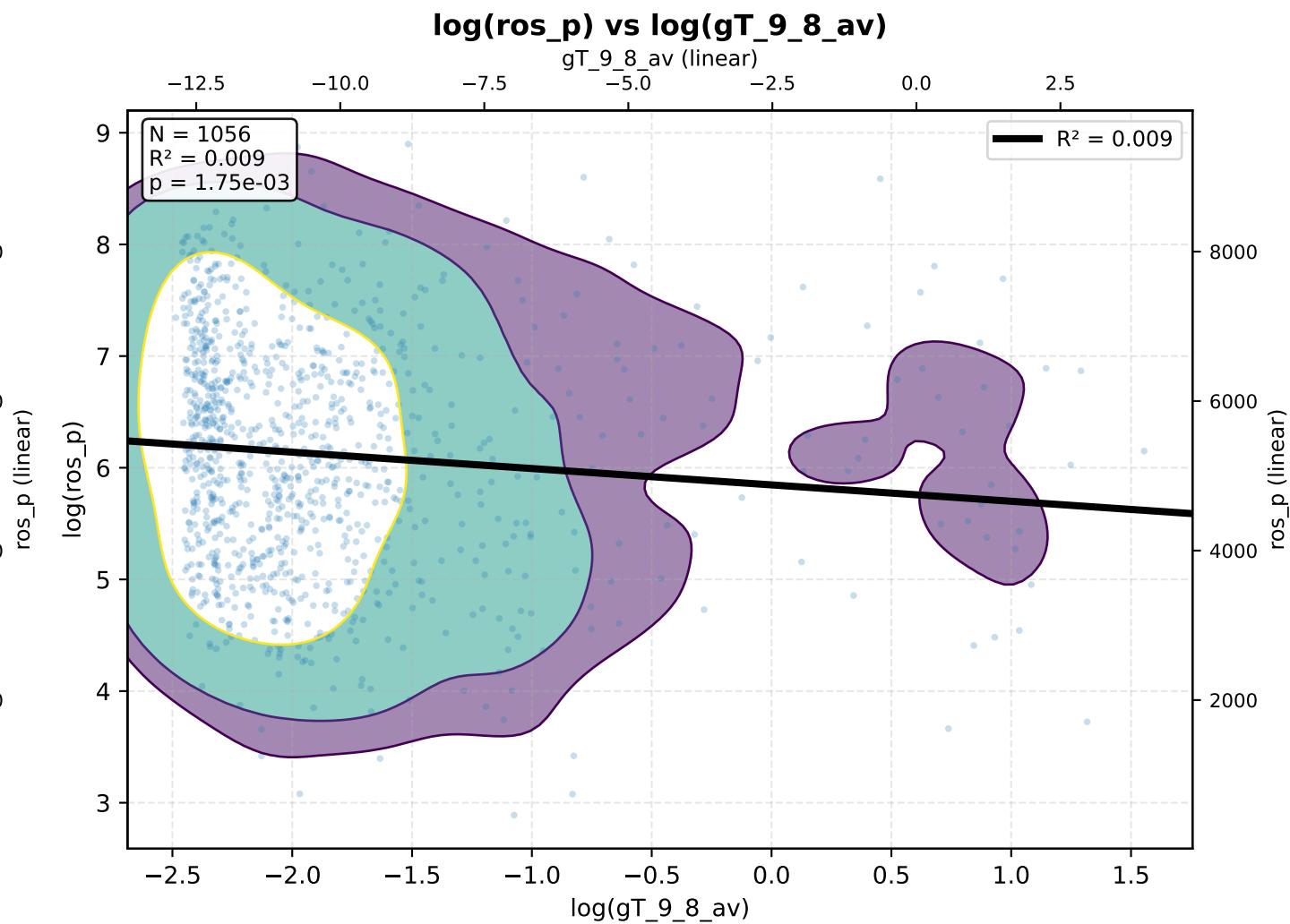
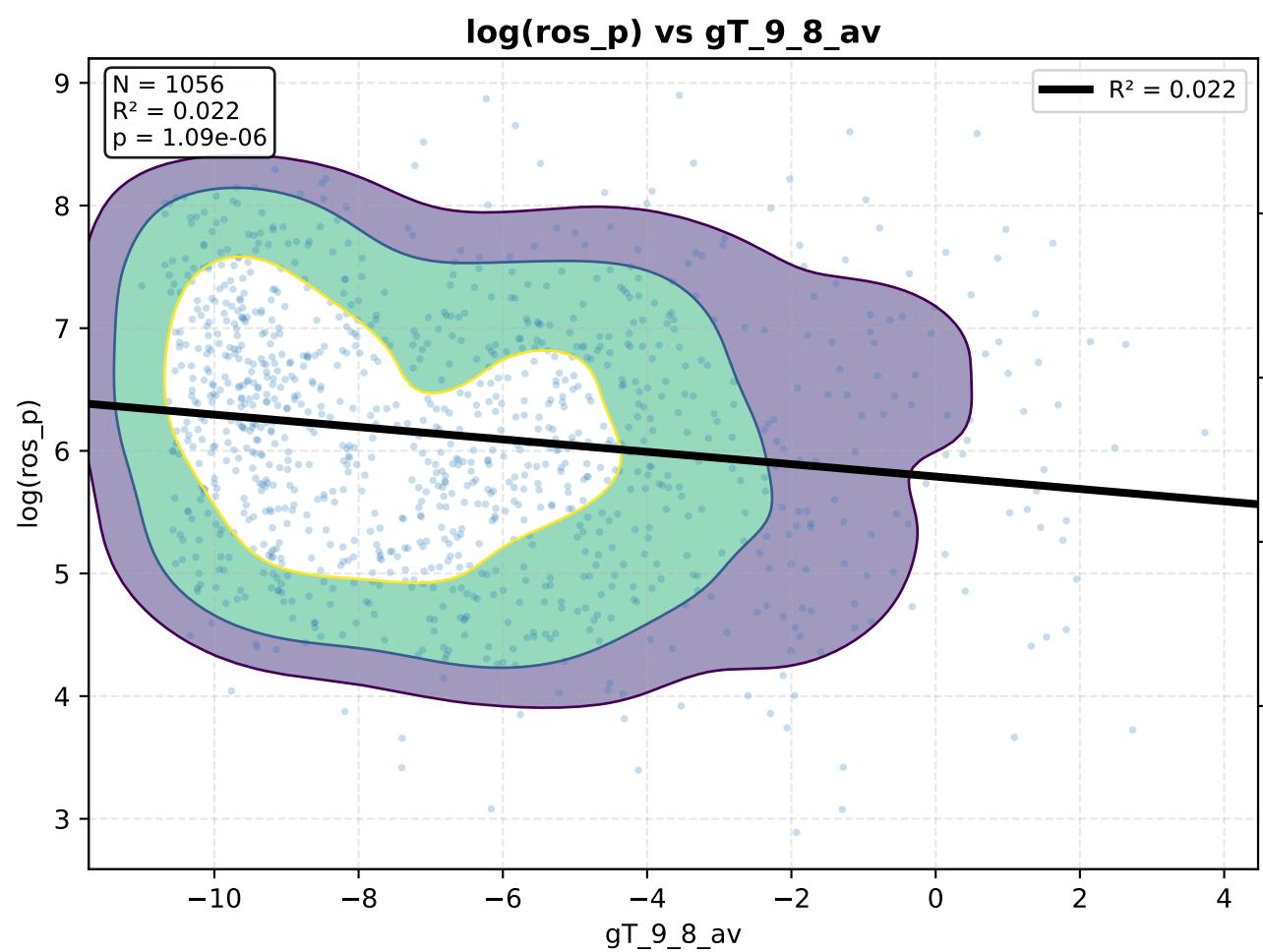
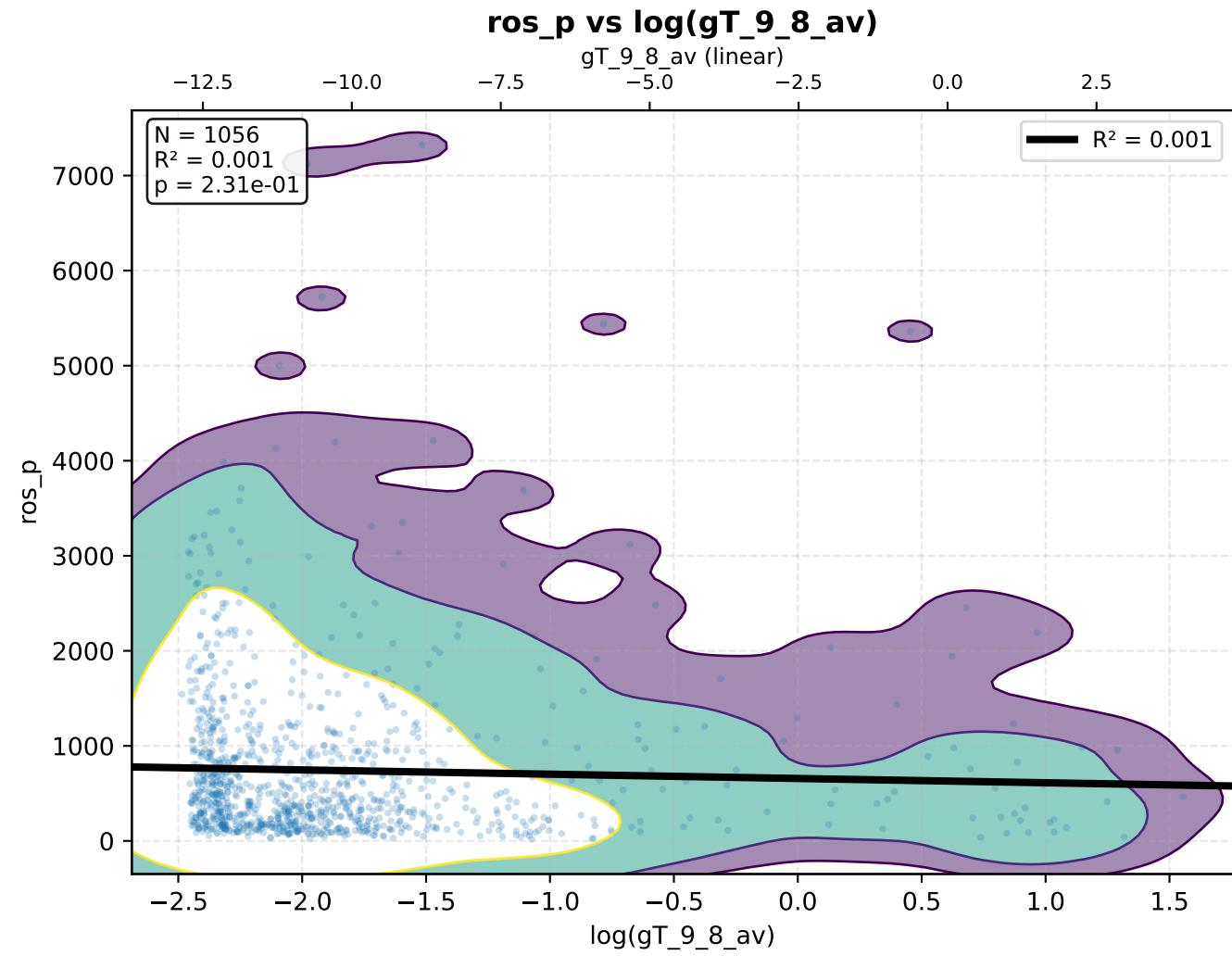
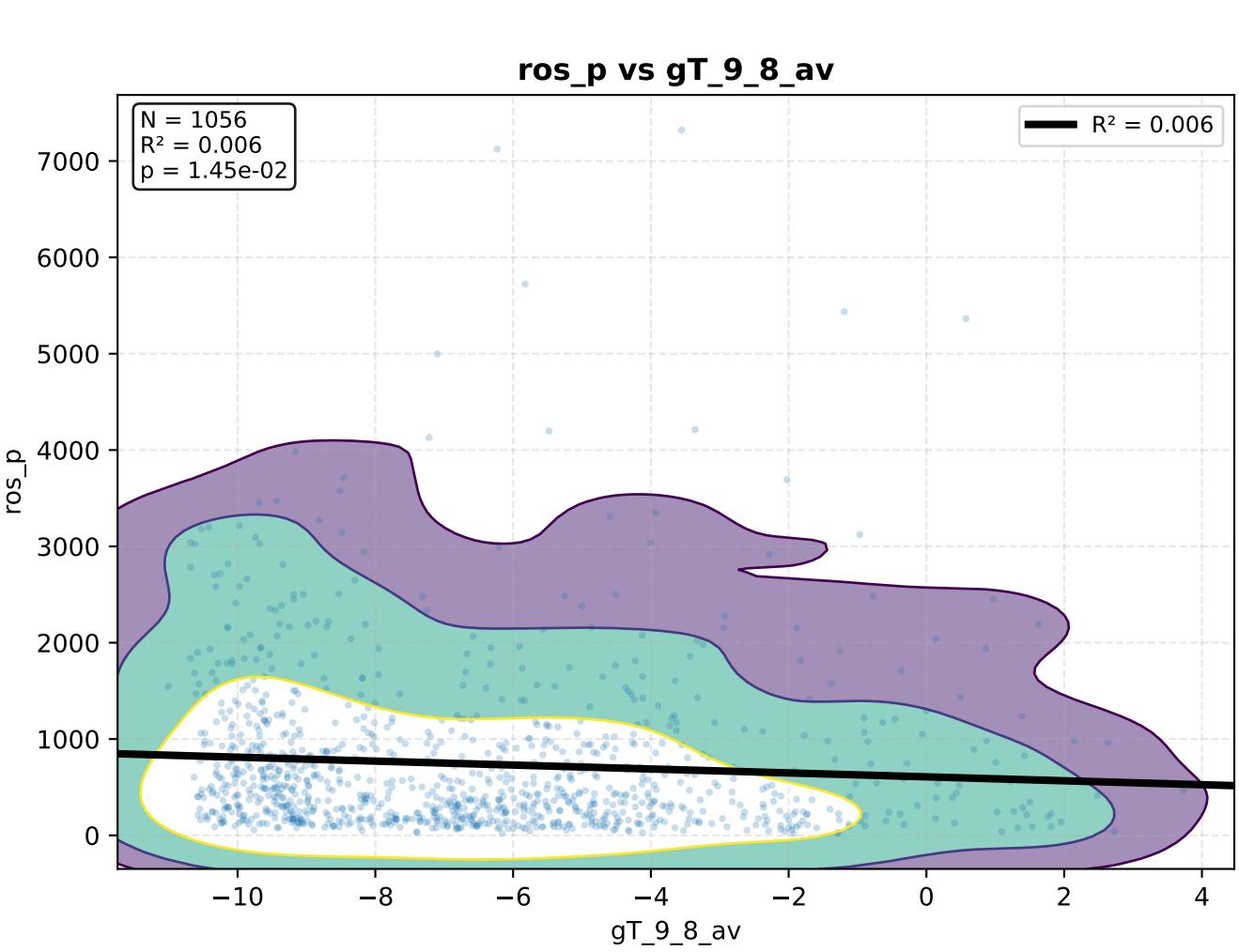
# gp\_300\_av - KDE Density + Regressão



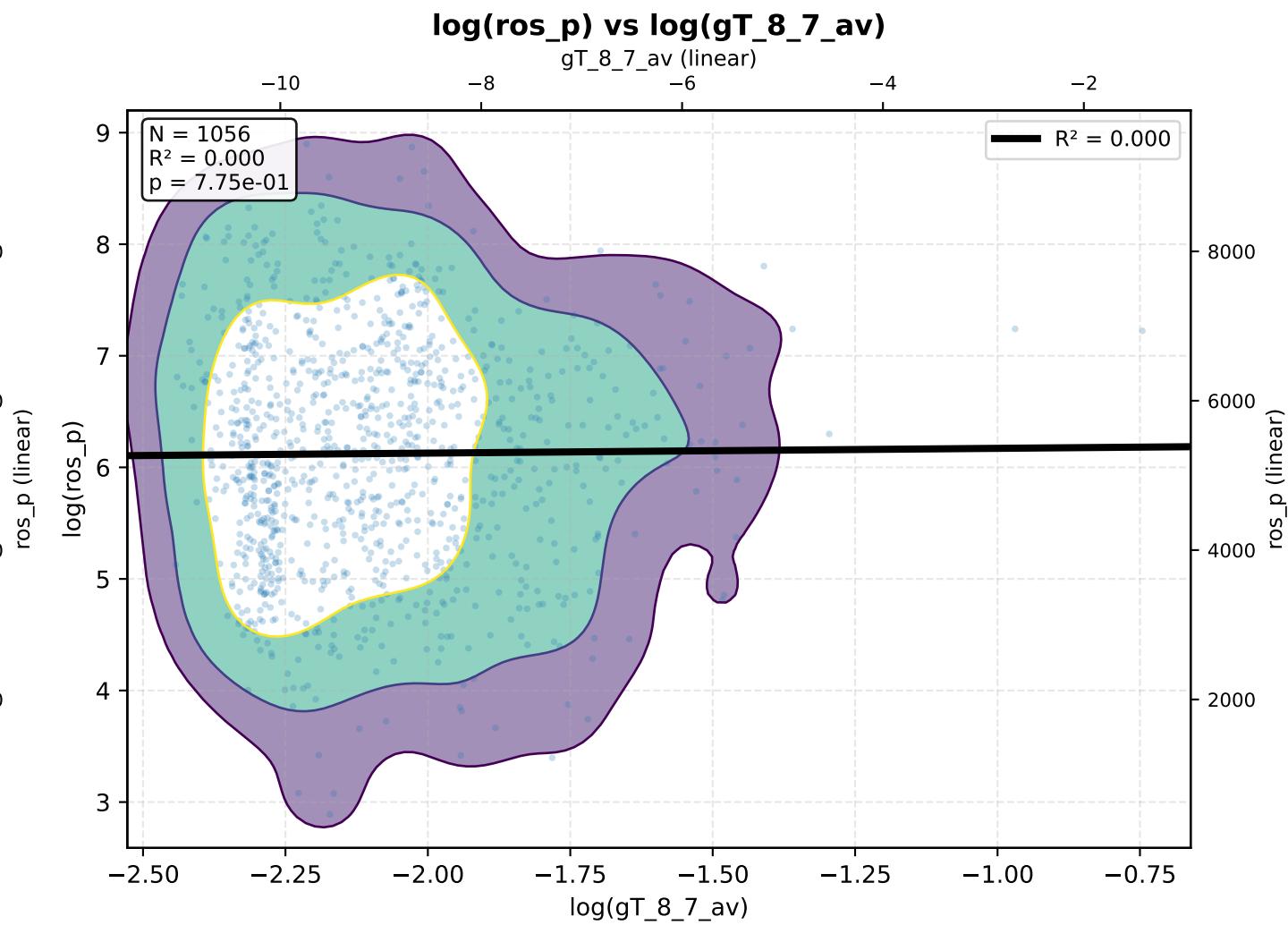
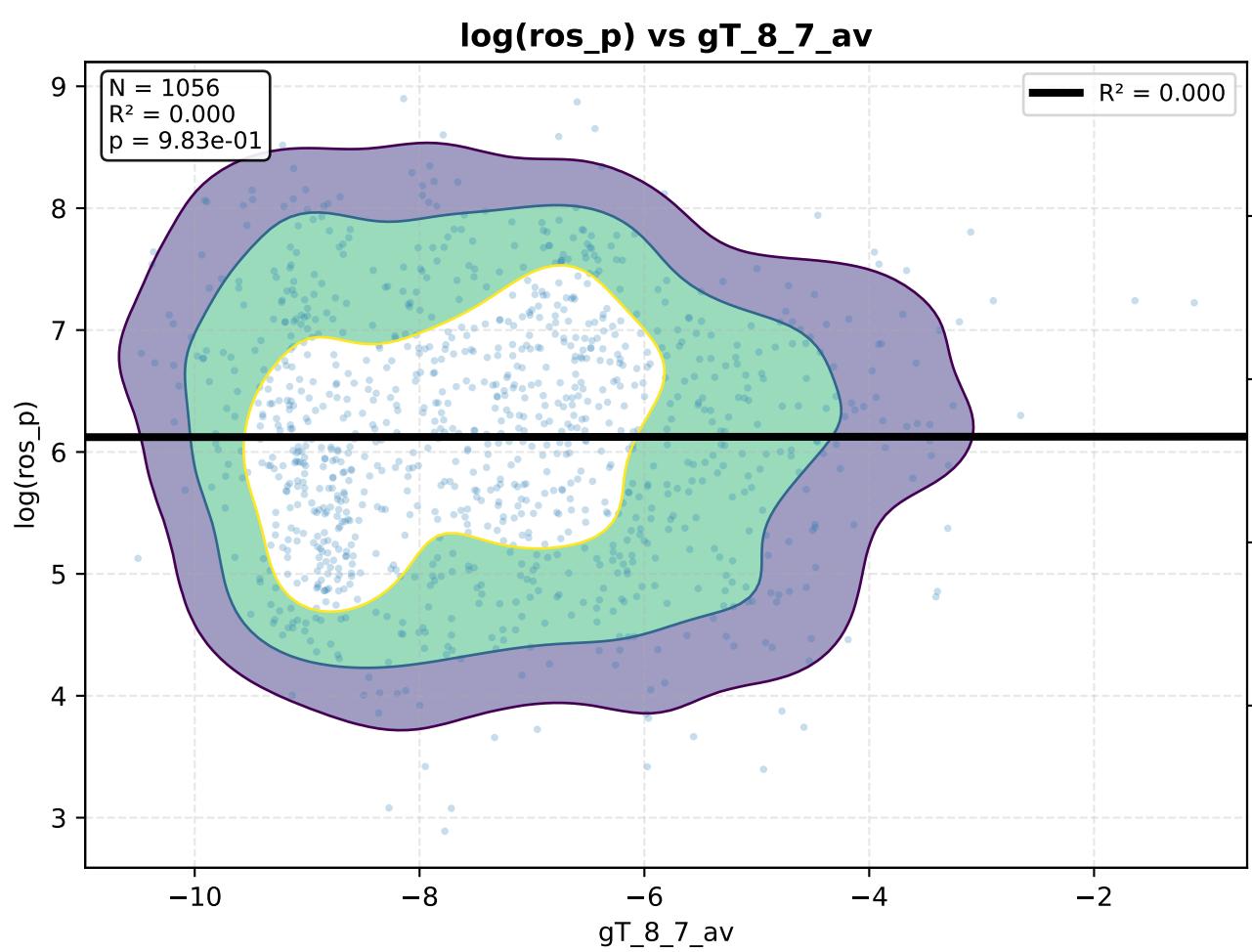
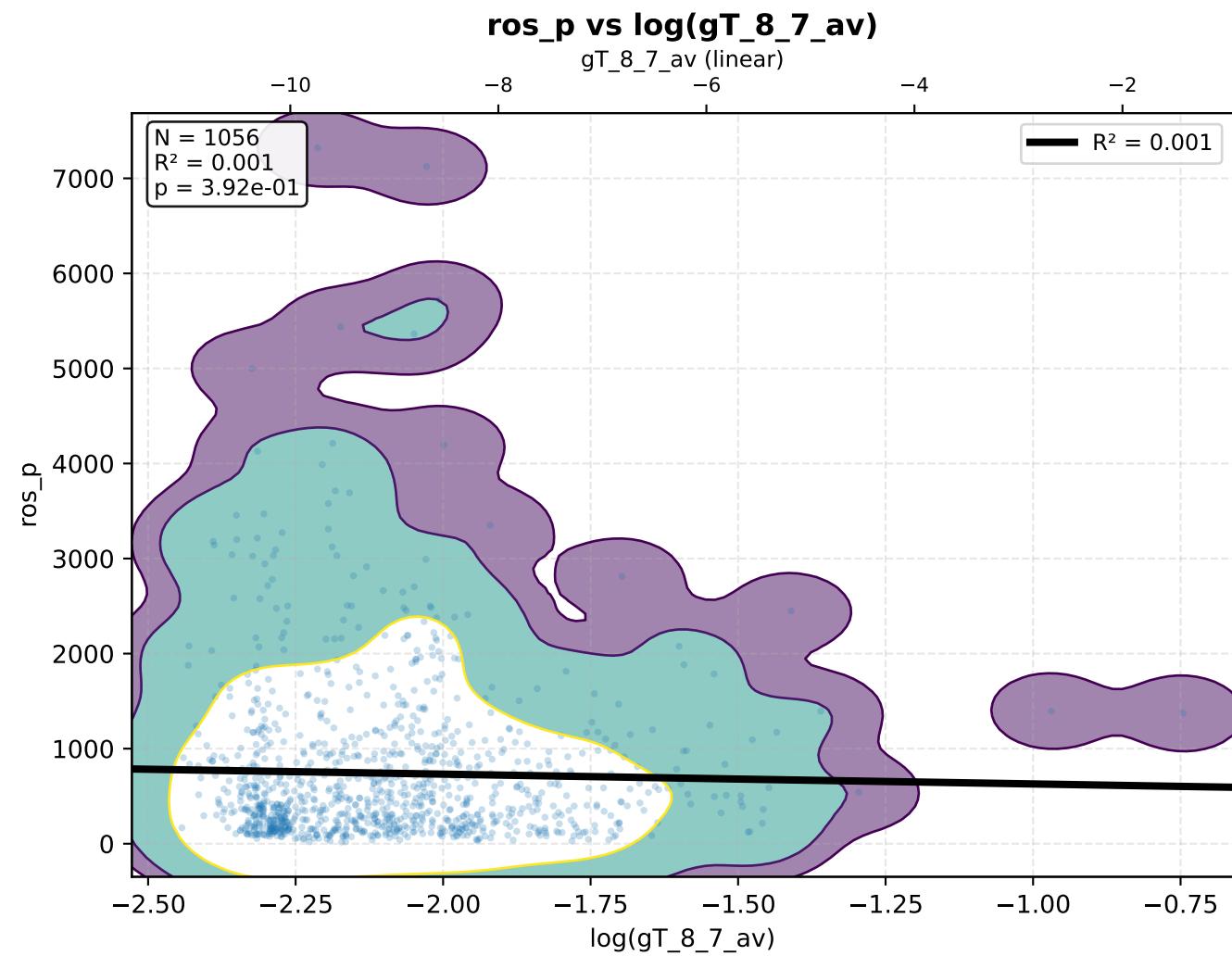
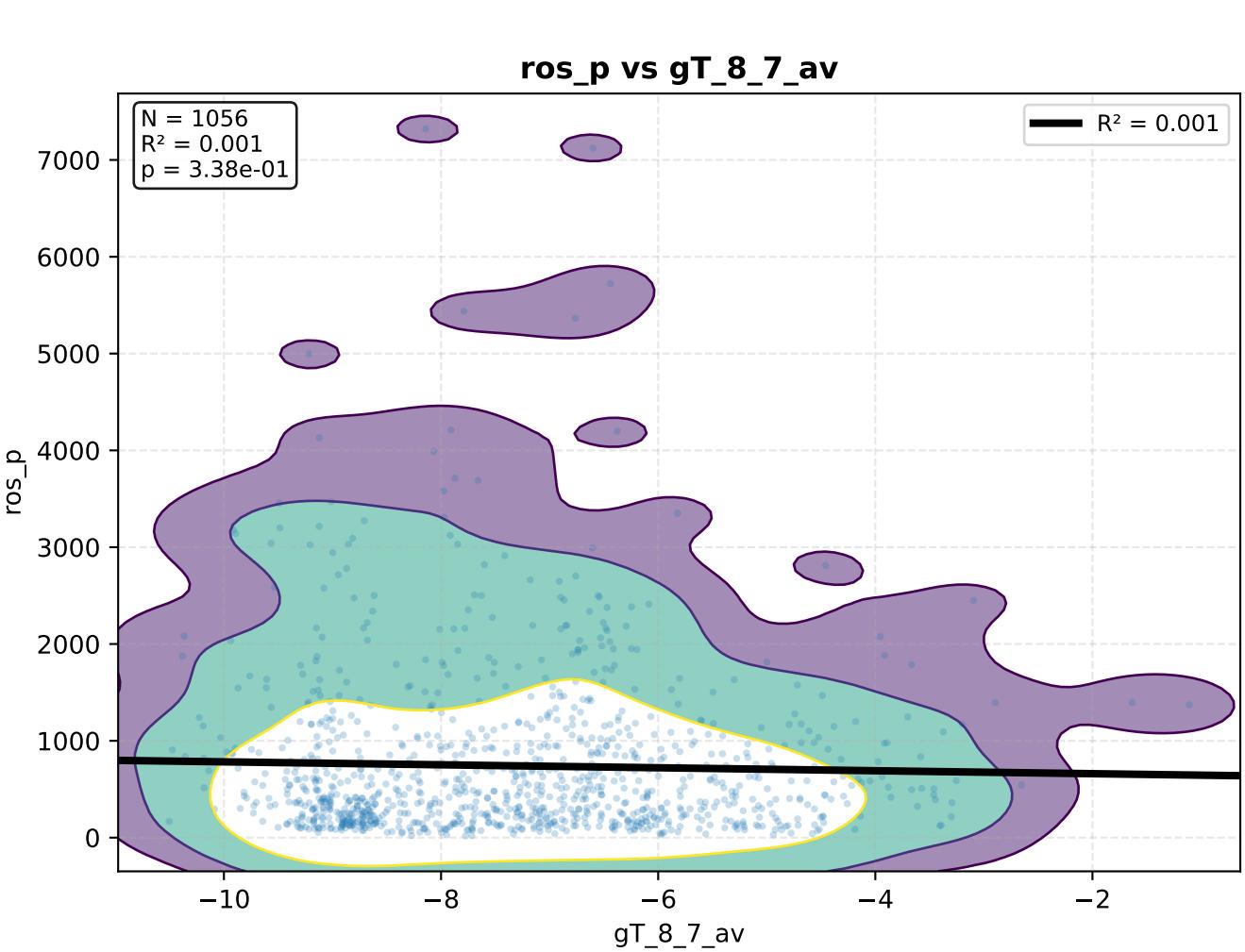
# gT\_s\_9\_av – KDE Density + Regressão



# gT\_9\_8\_av - KDE Density + Regressão

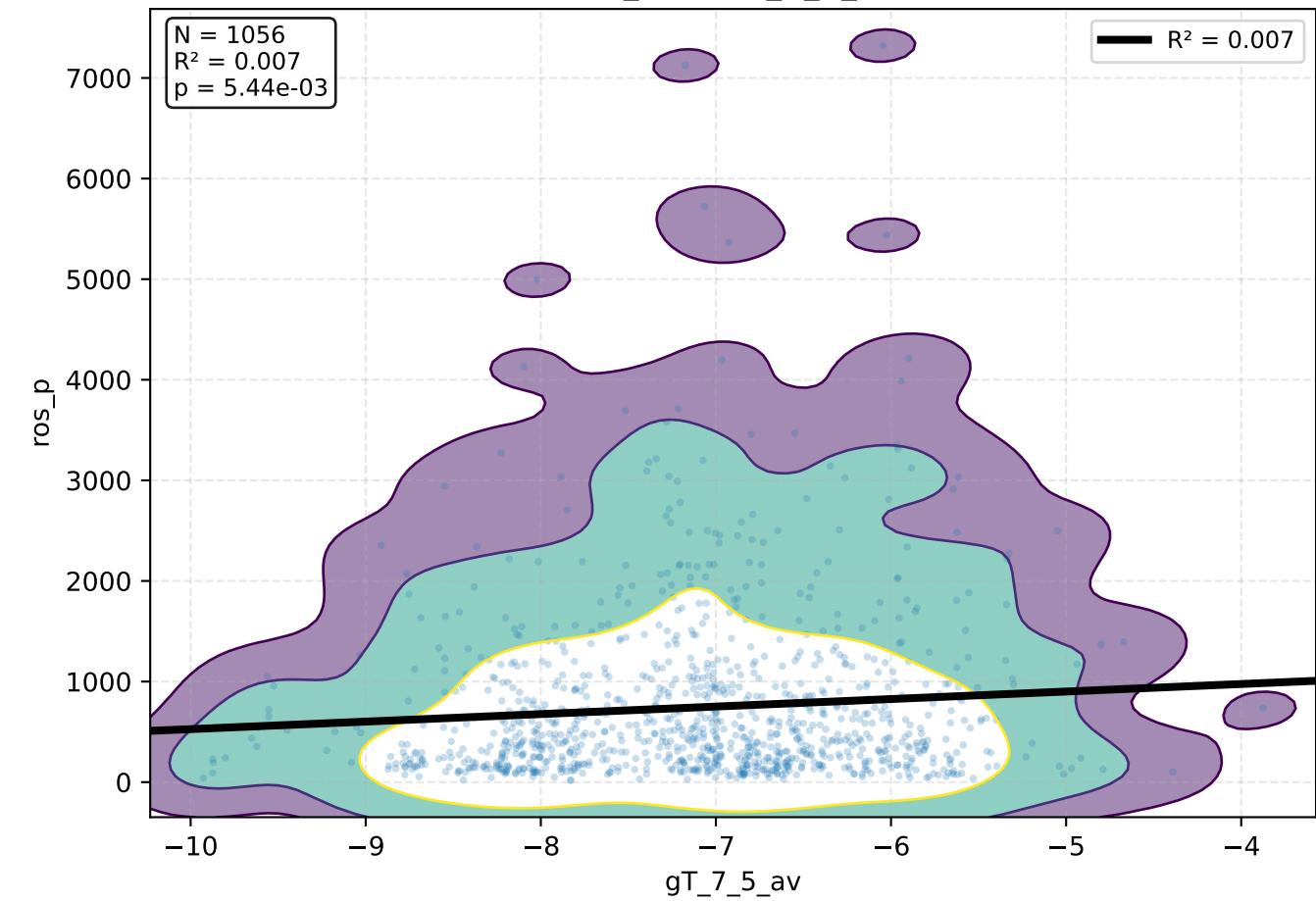


# gT\_8\_7\_av - KDE Density + Regressão

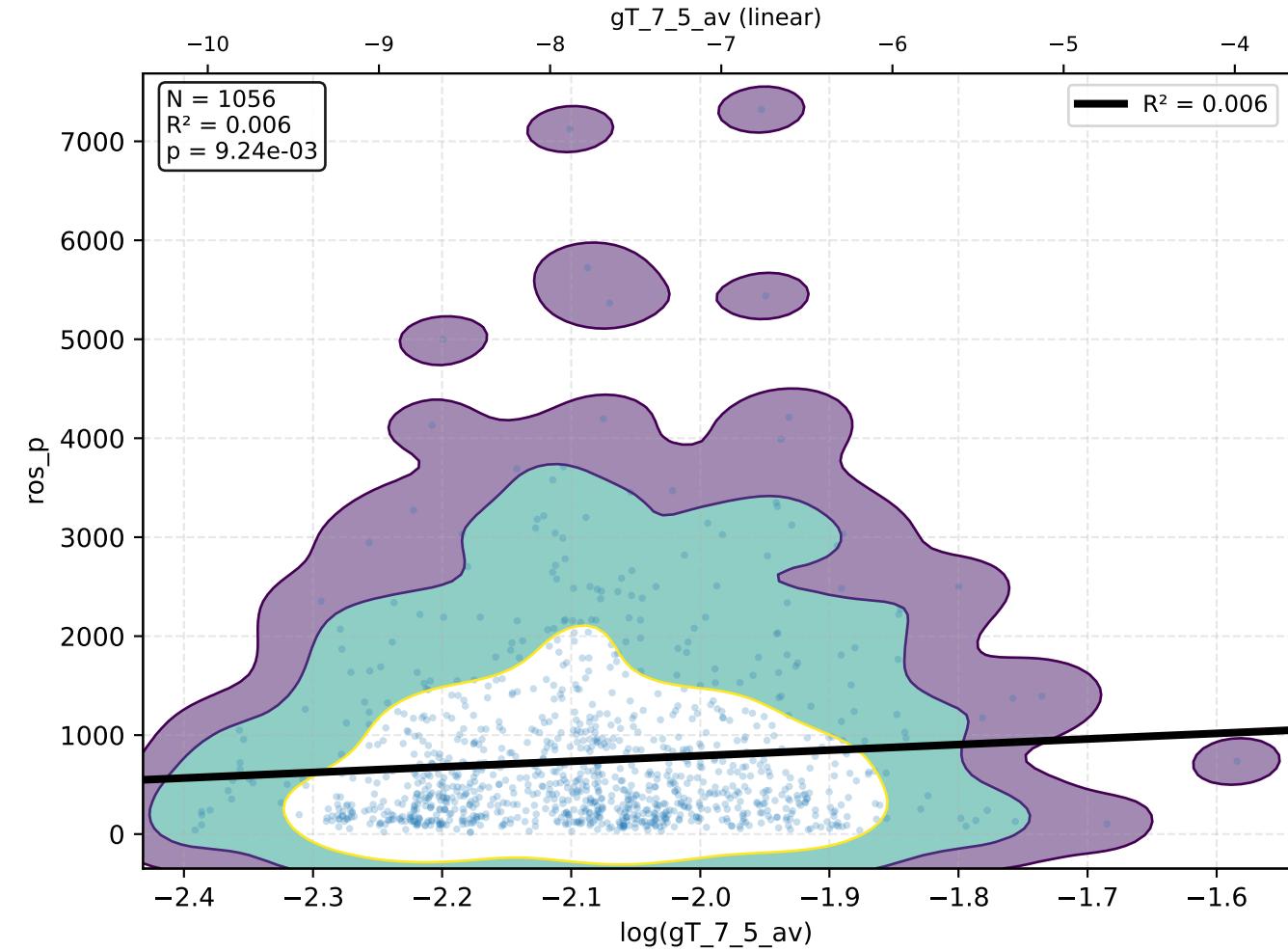


# gT\_7\_5\_av - KDE Density + Regressão

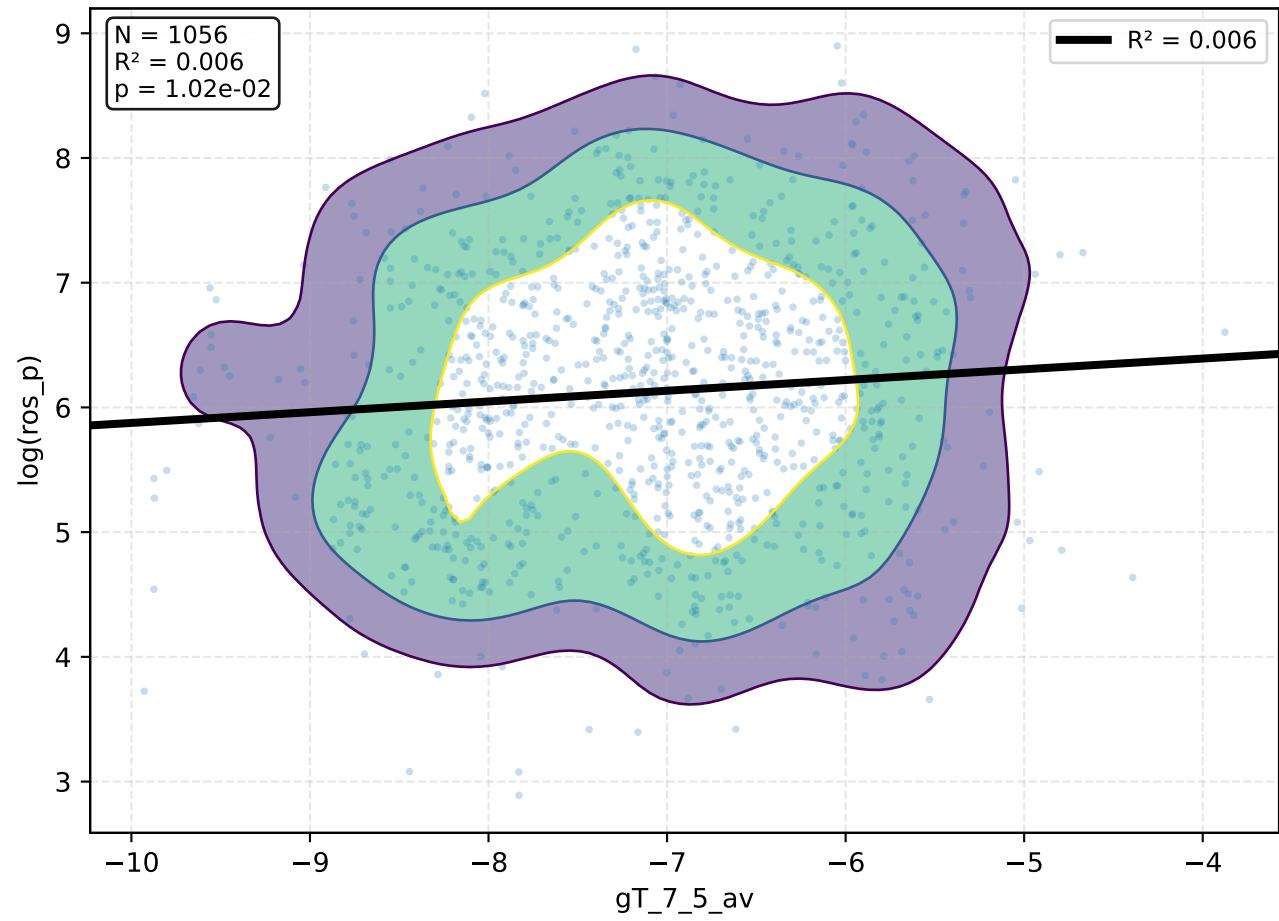
**ros\_p vs gT\_7\_5\_av**



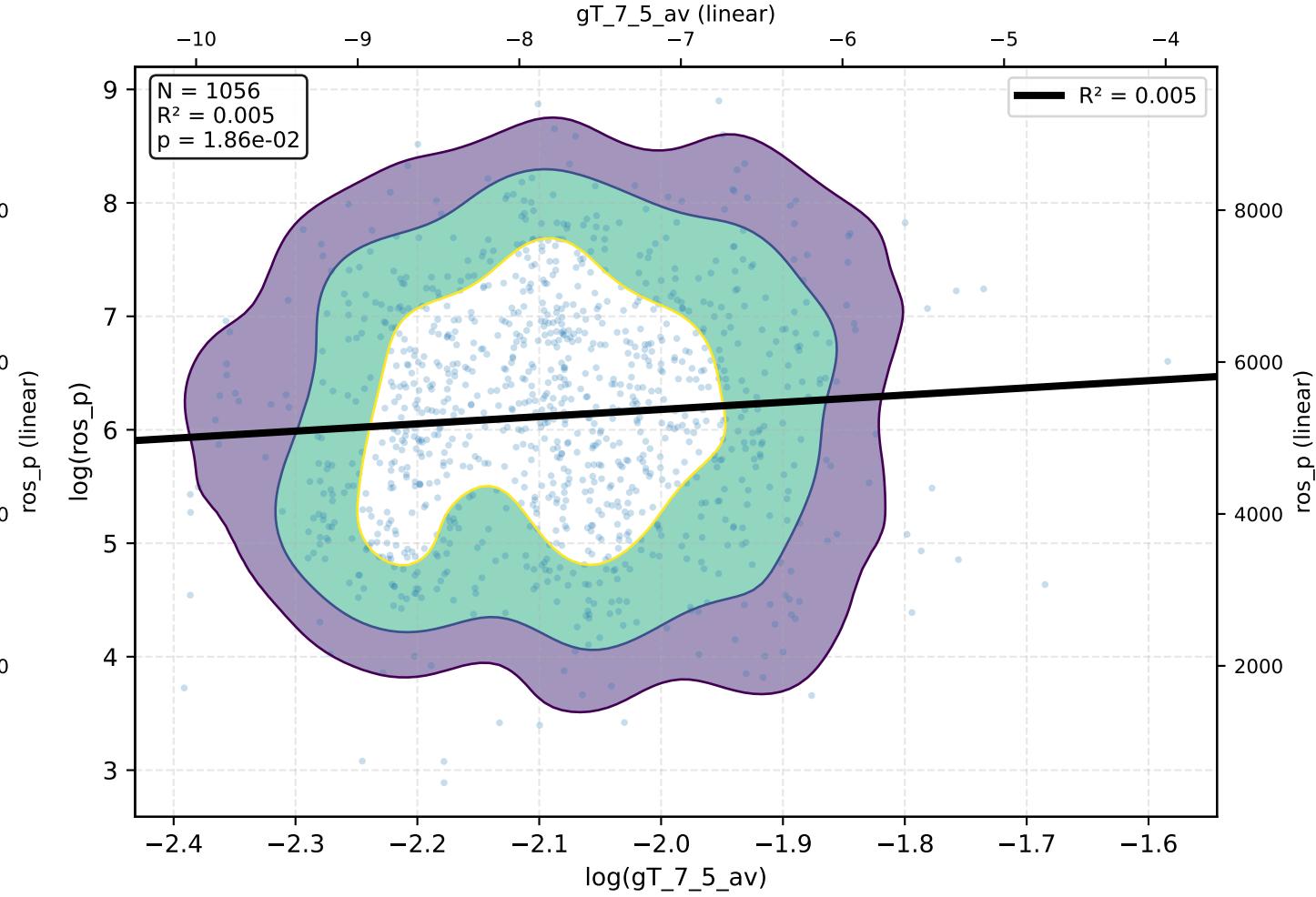
**ros\_p vs log(gT\_7\_5\_av)**



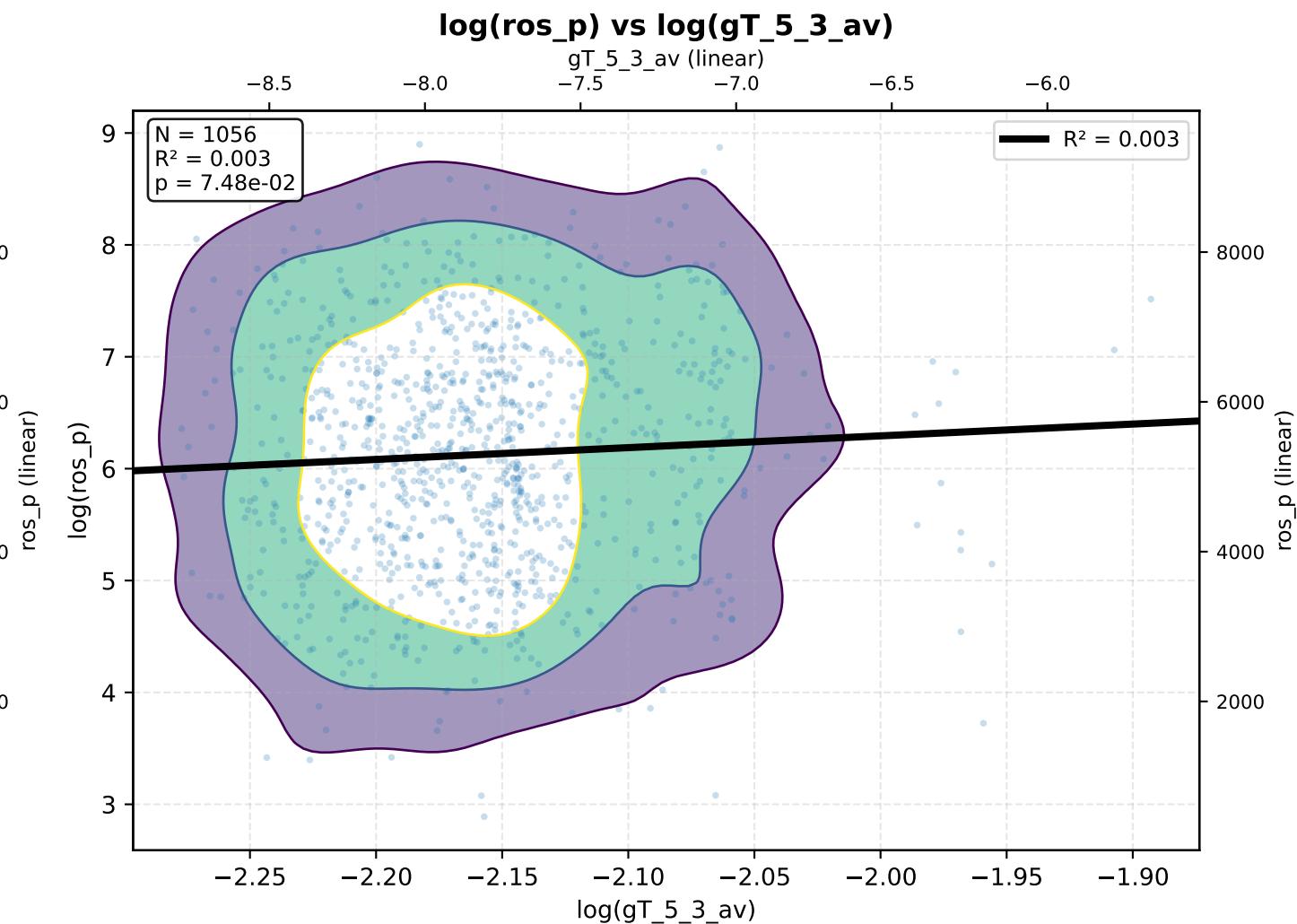
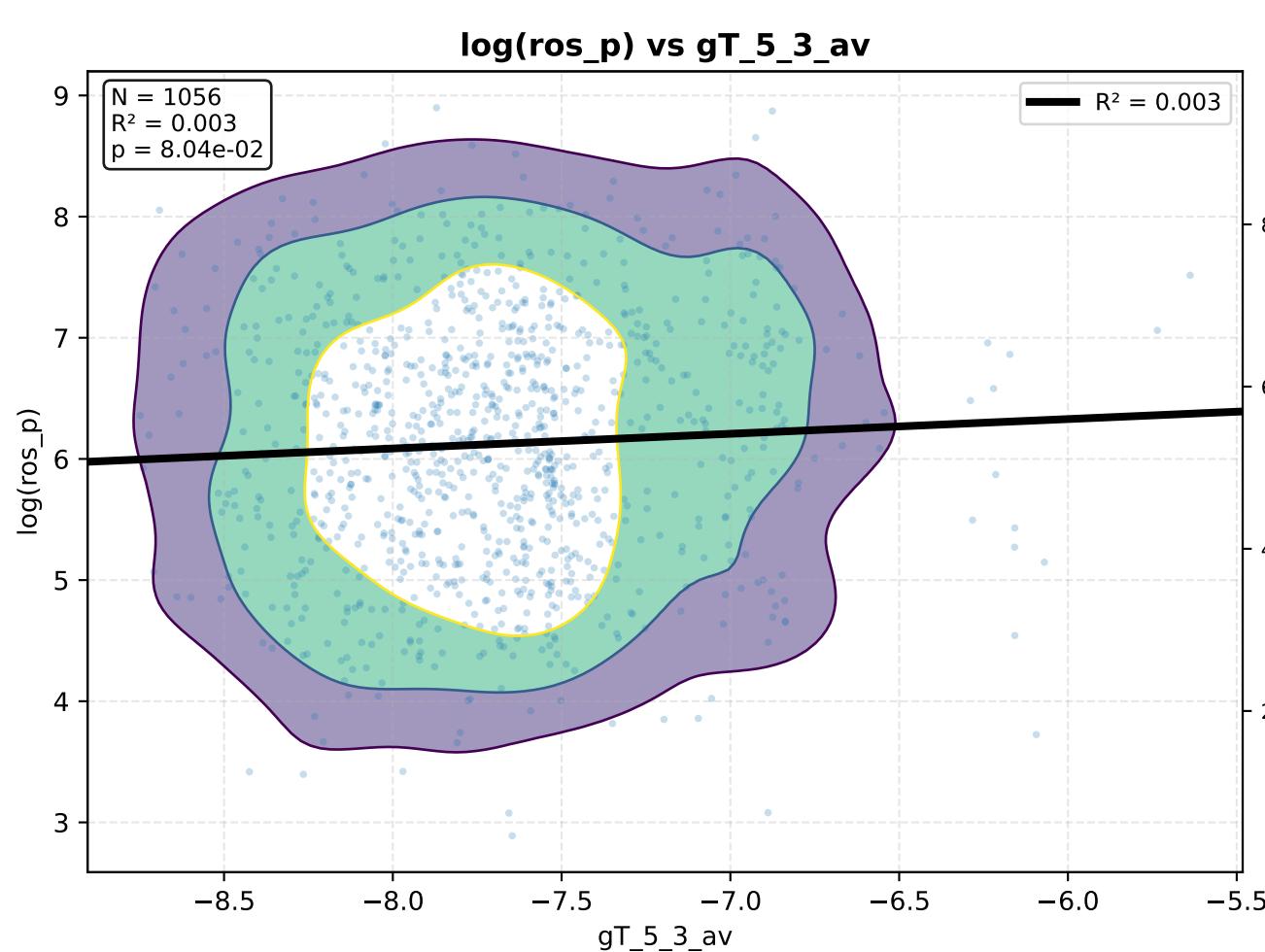
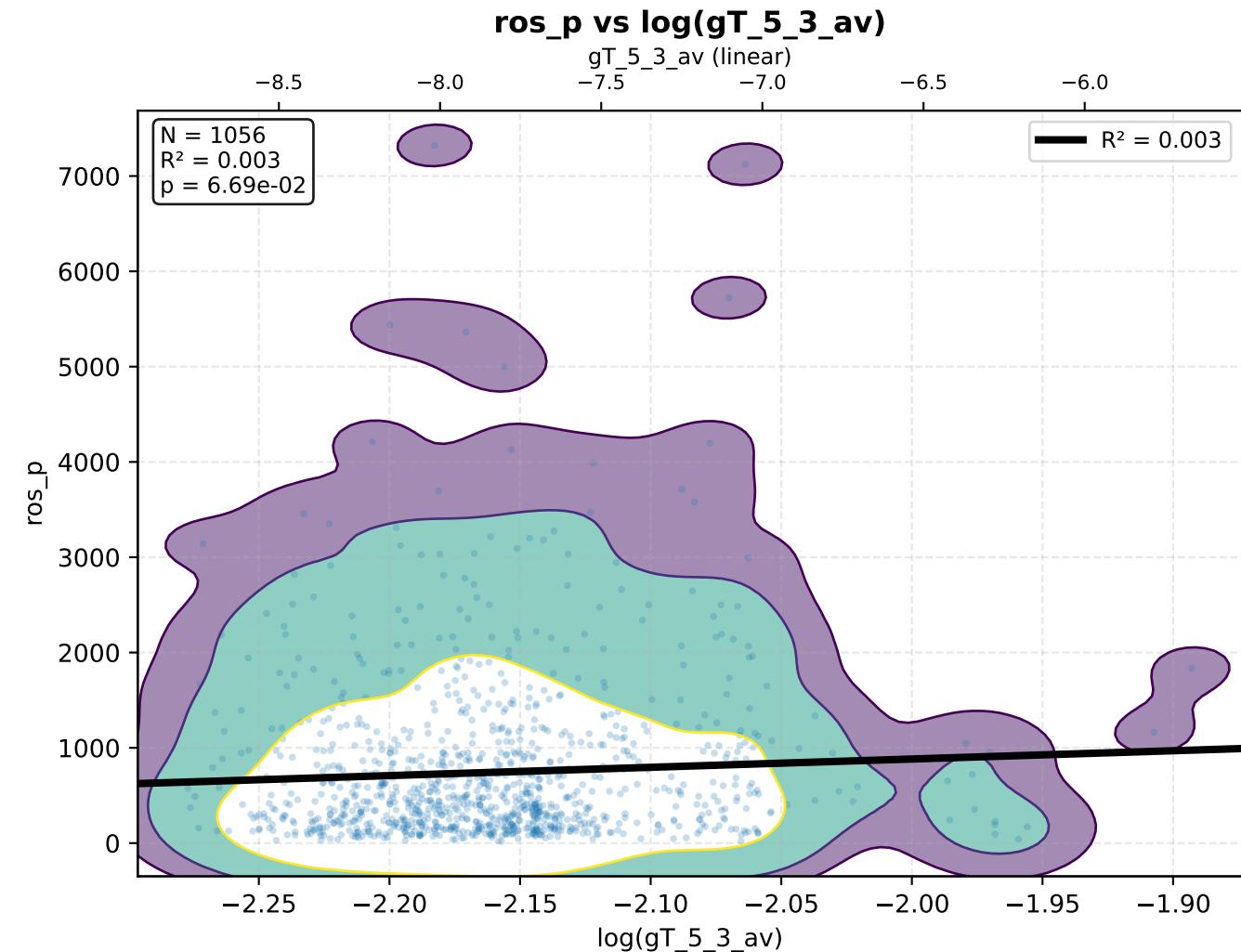
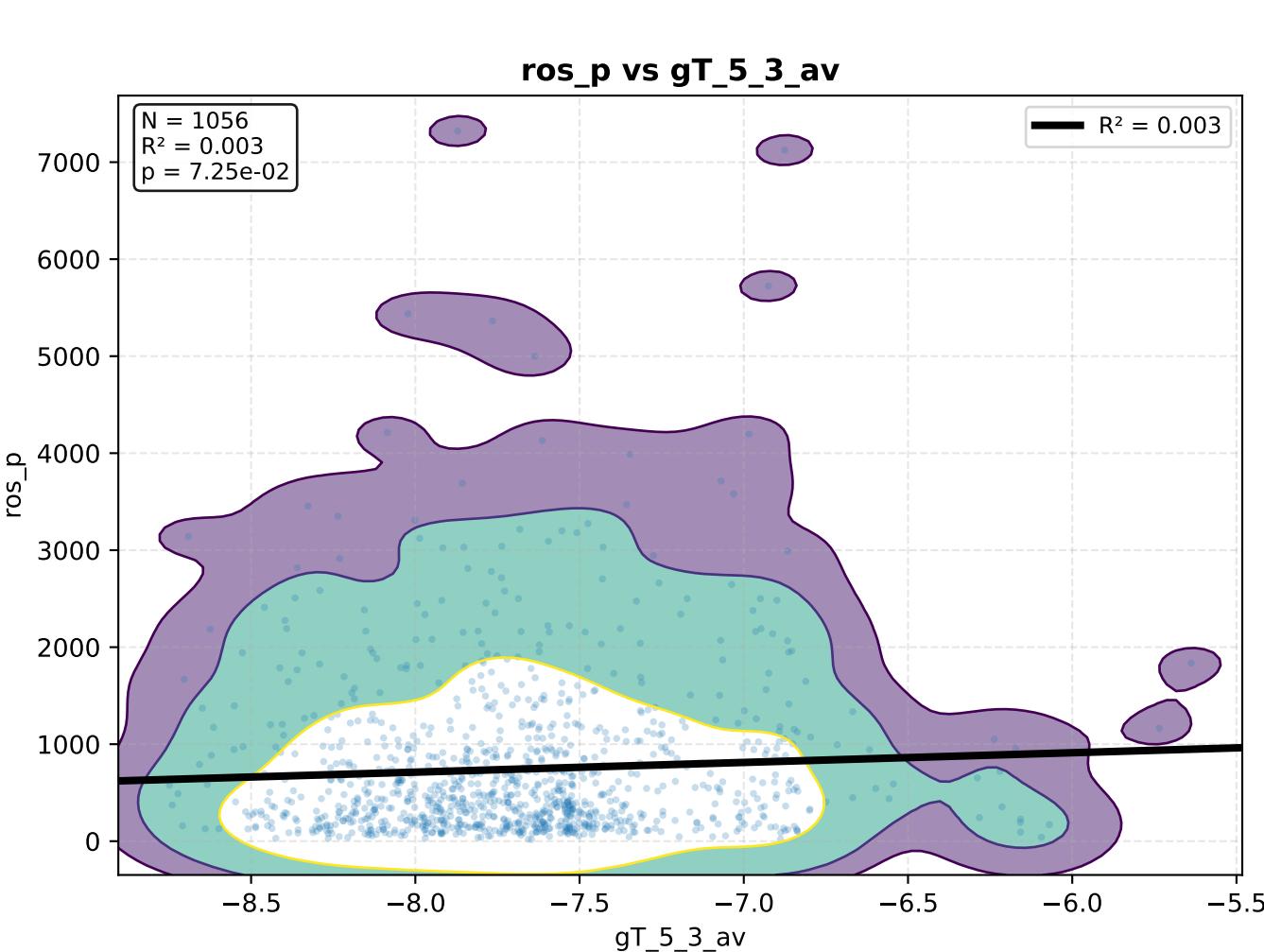
**log(ros\_p) vs gT\_7\_5\_av**



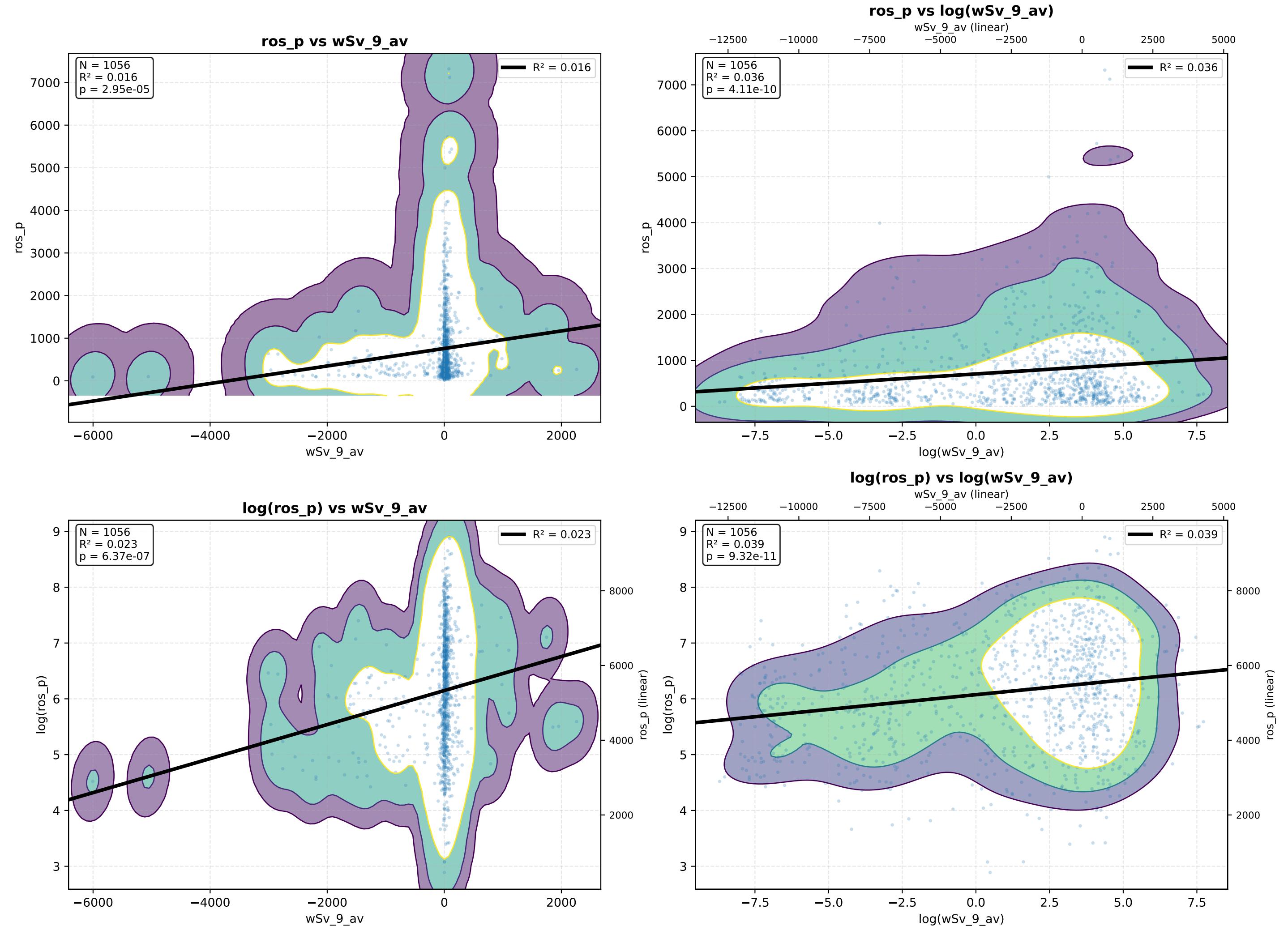
**log(ros\_p) vs log(gT\_7\_5\_av)**



# gT\_5\_3\_av - KDE Density + Regressão

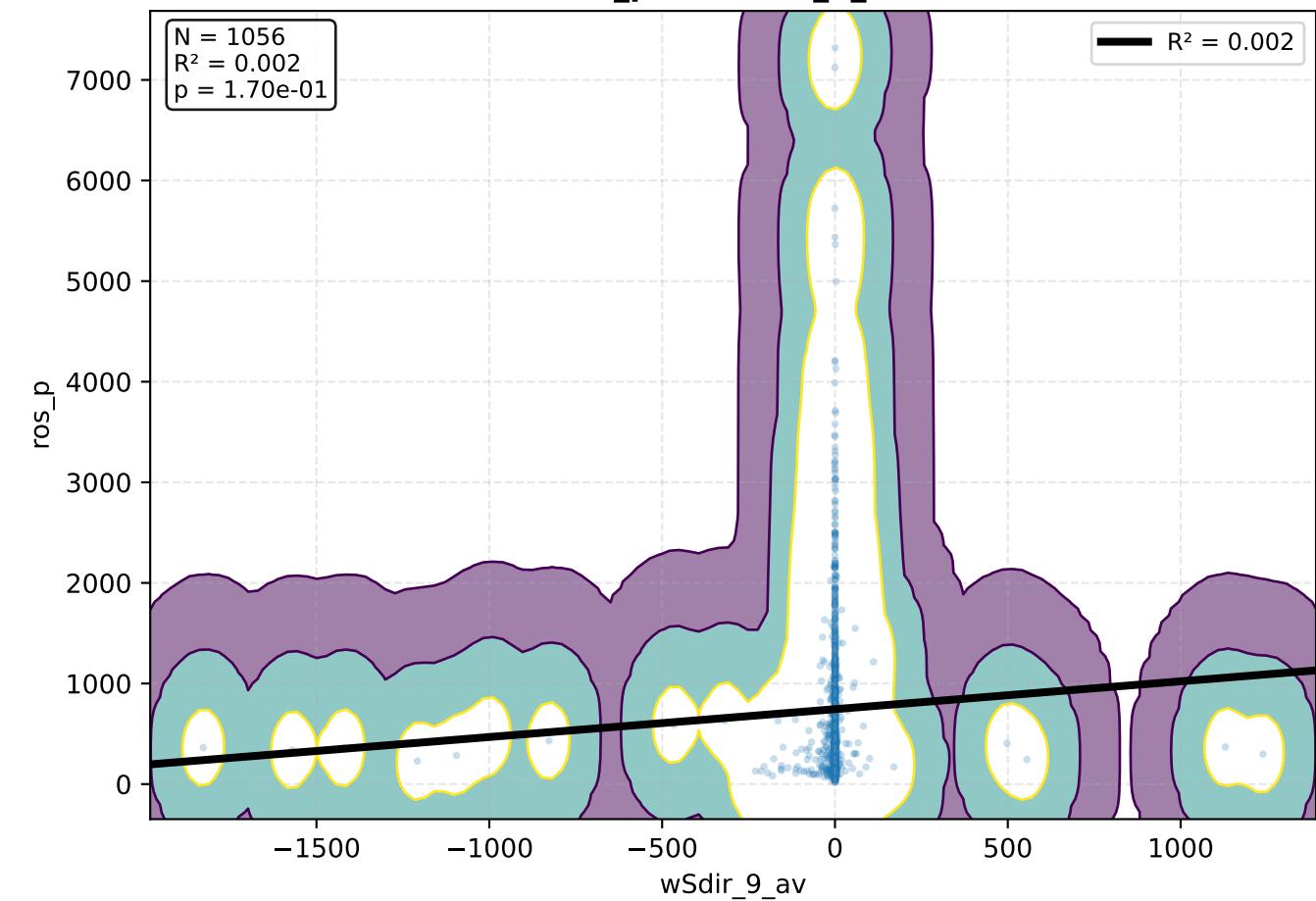


# wSv\_9\_av - KDE Density + Regressão

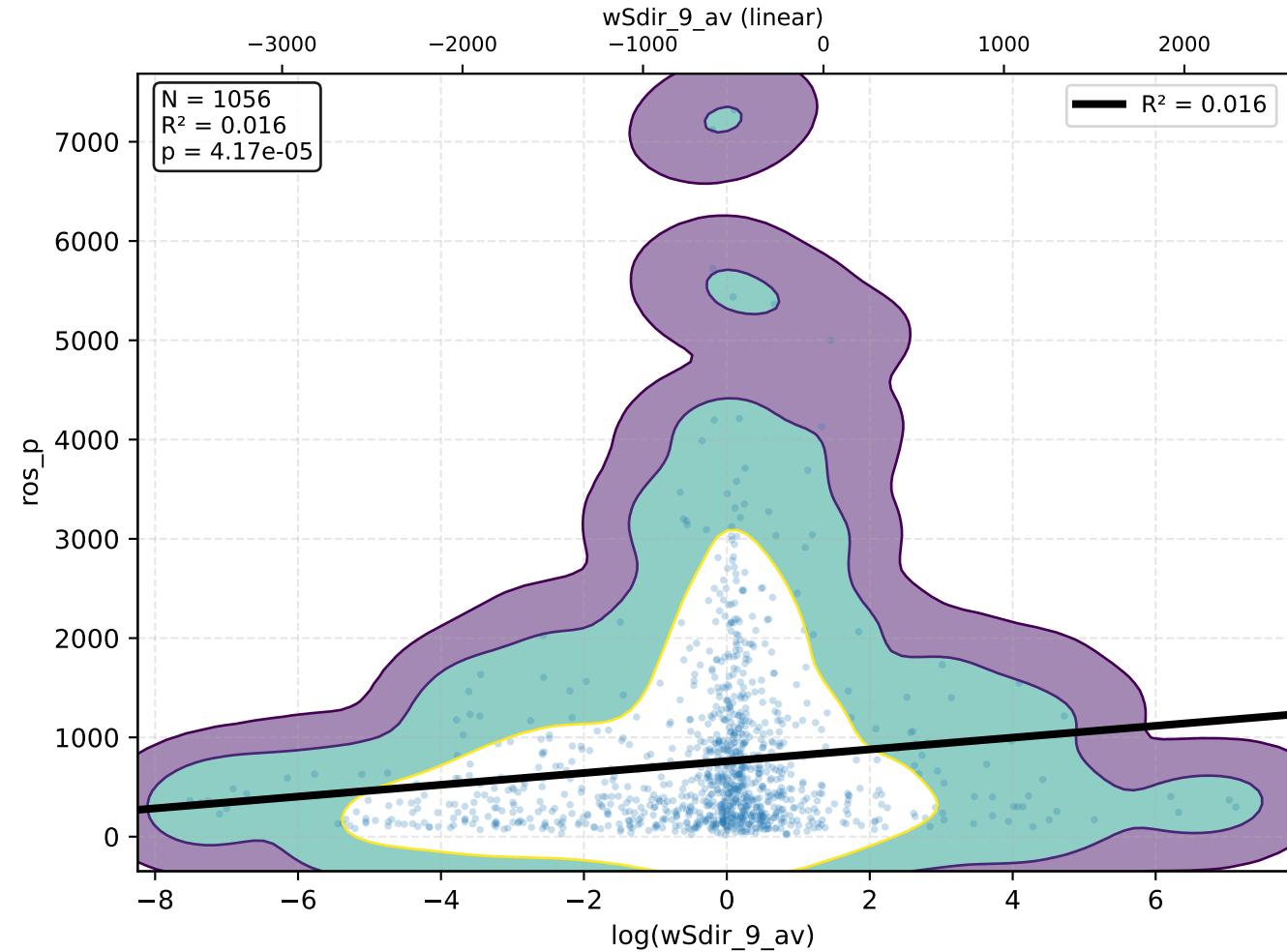


# wSdir\_9\_av - KDE Density + Regressão

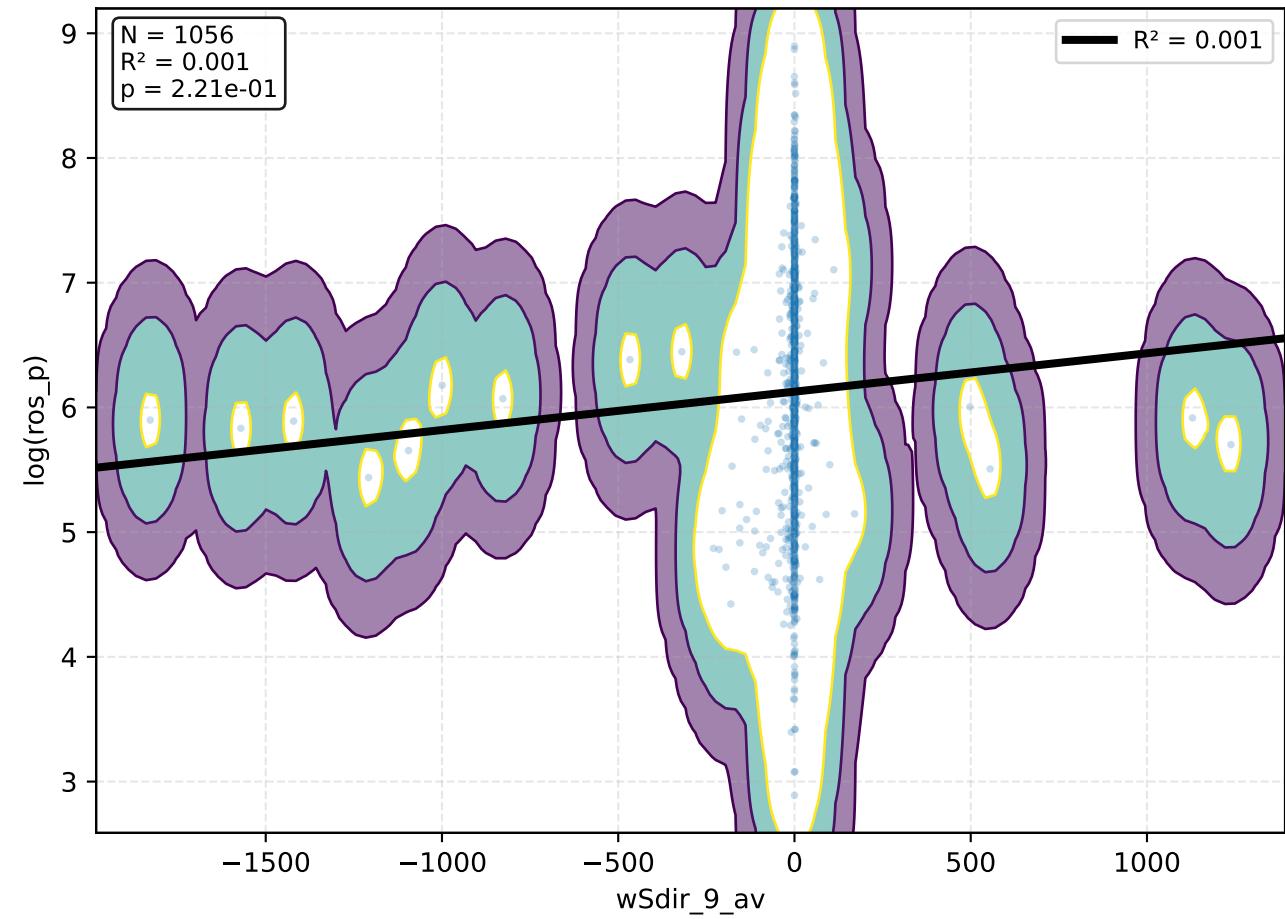
**ros\_p vs wSdir\_9\_av**



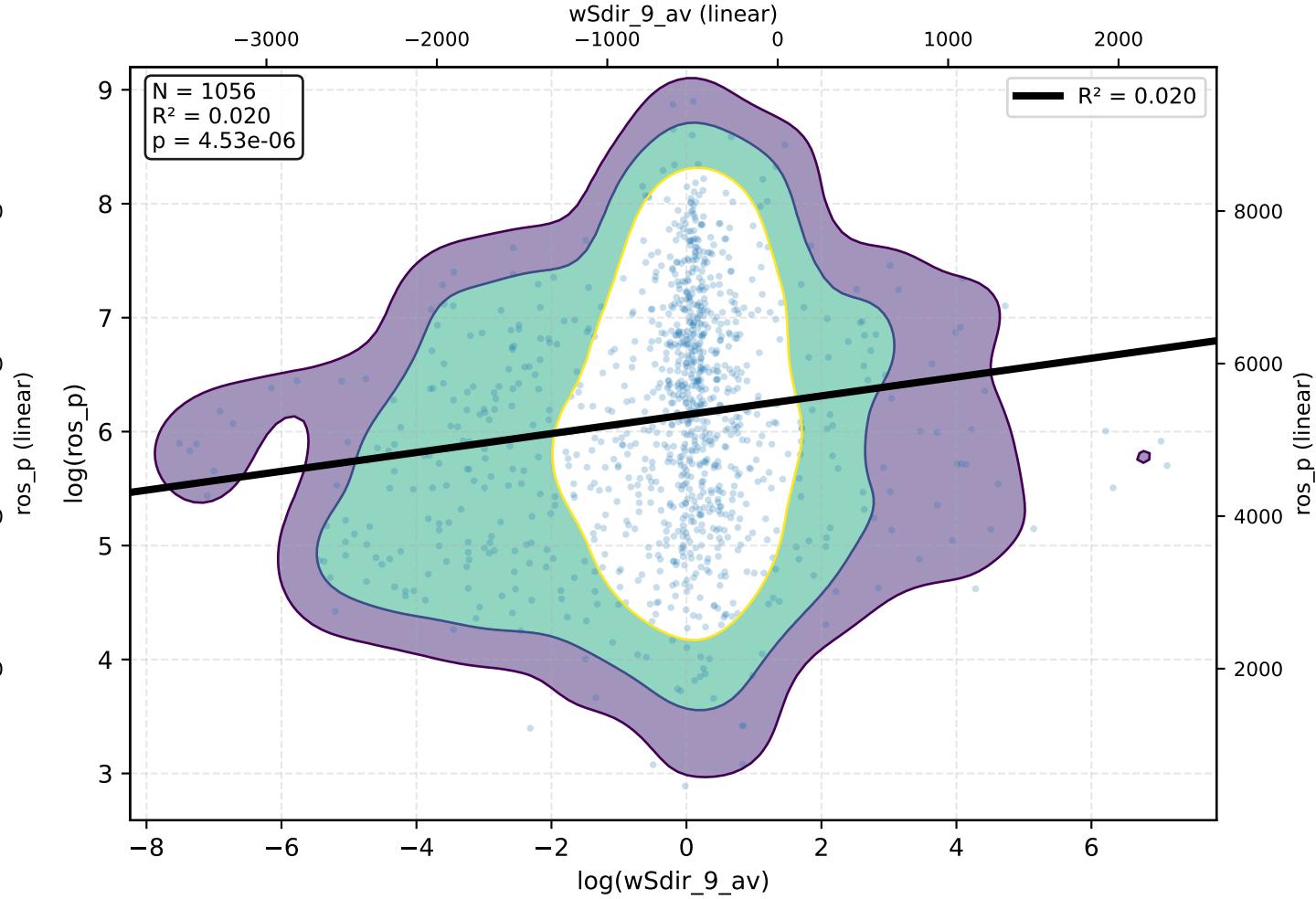
**ros\_p vs log(wSdir\_9\_av)**



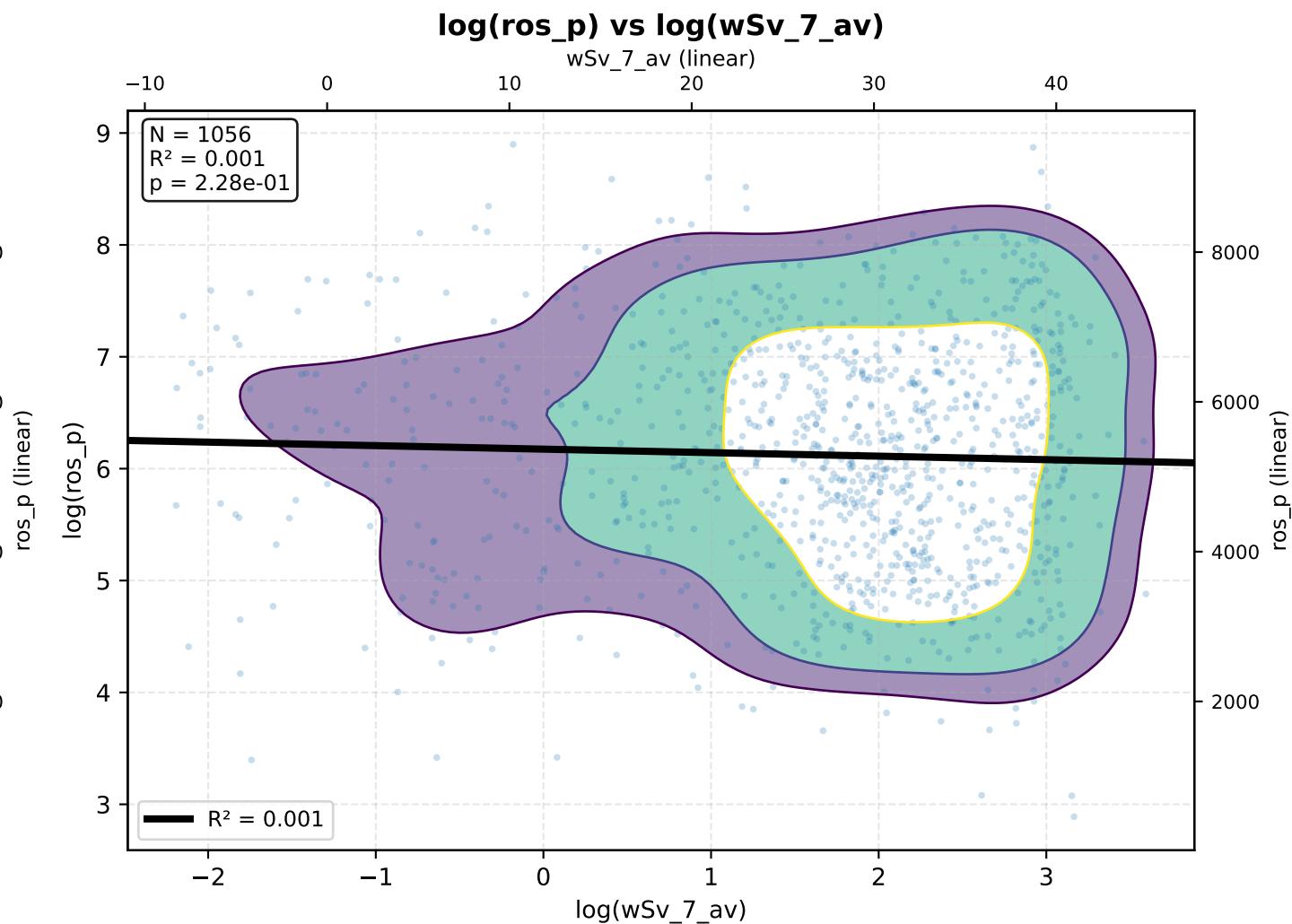
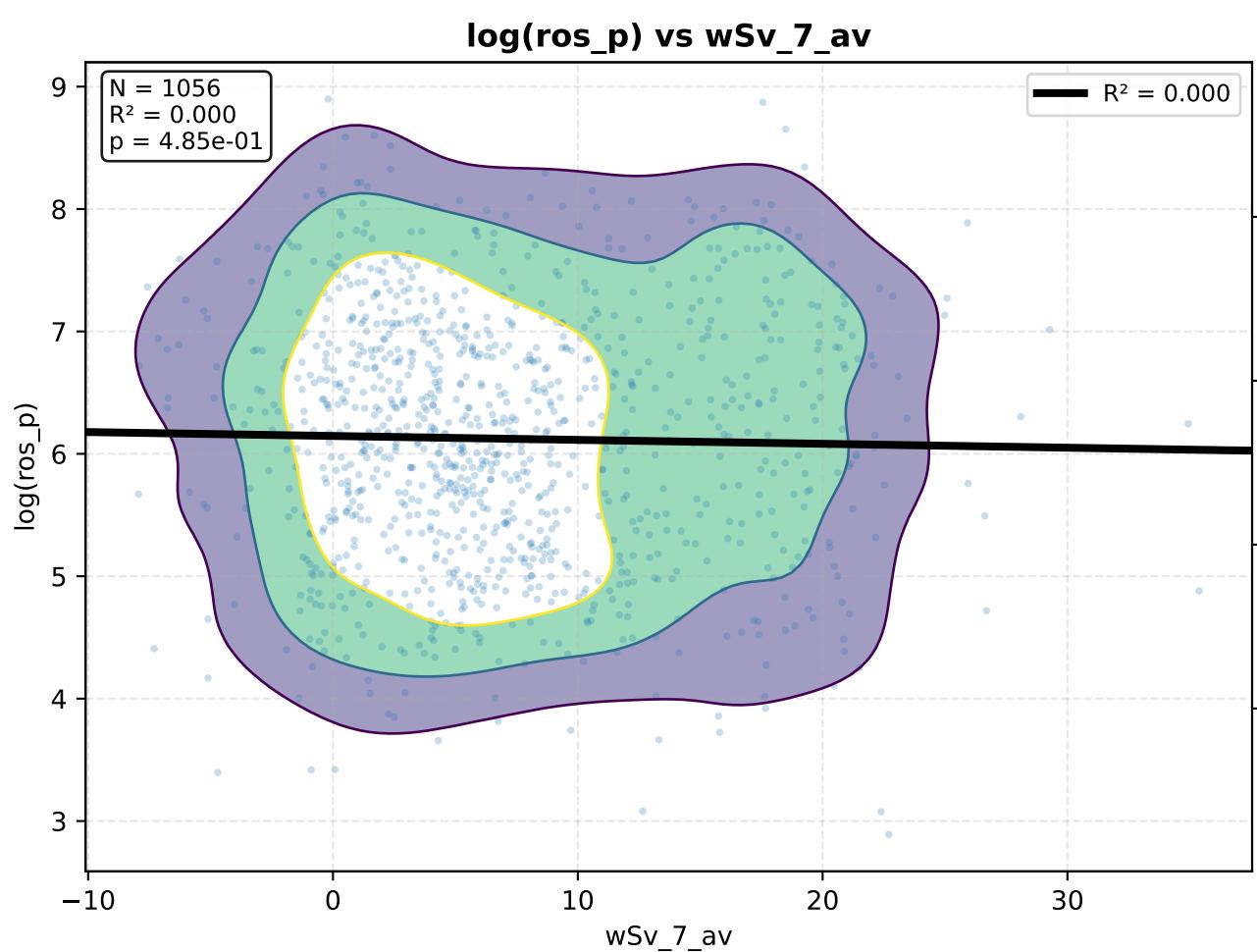
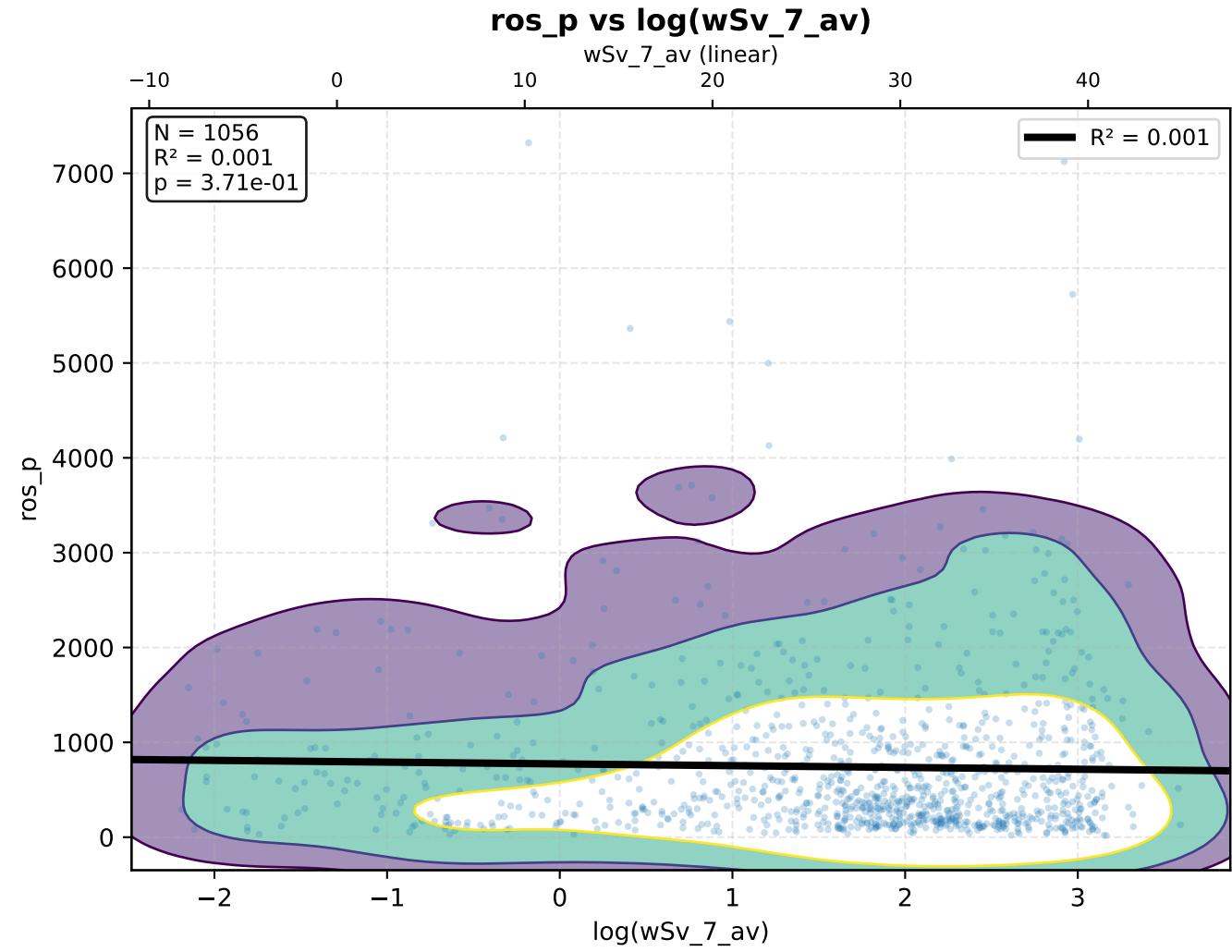
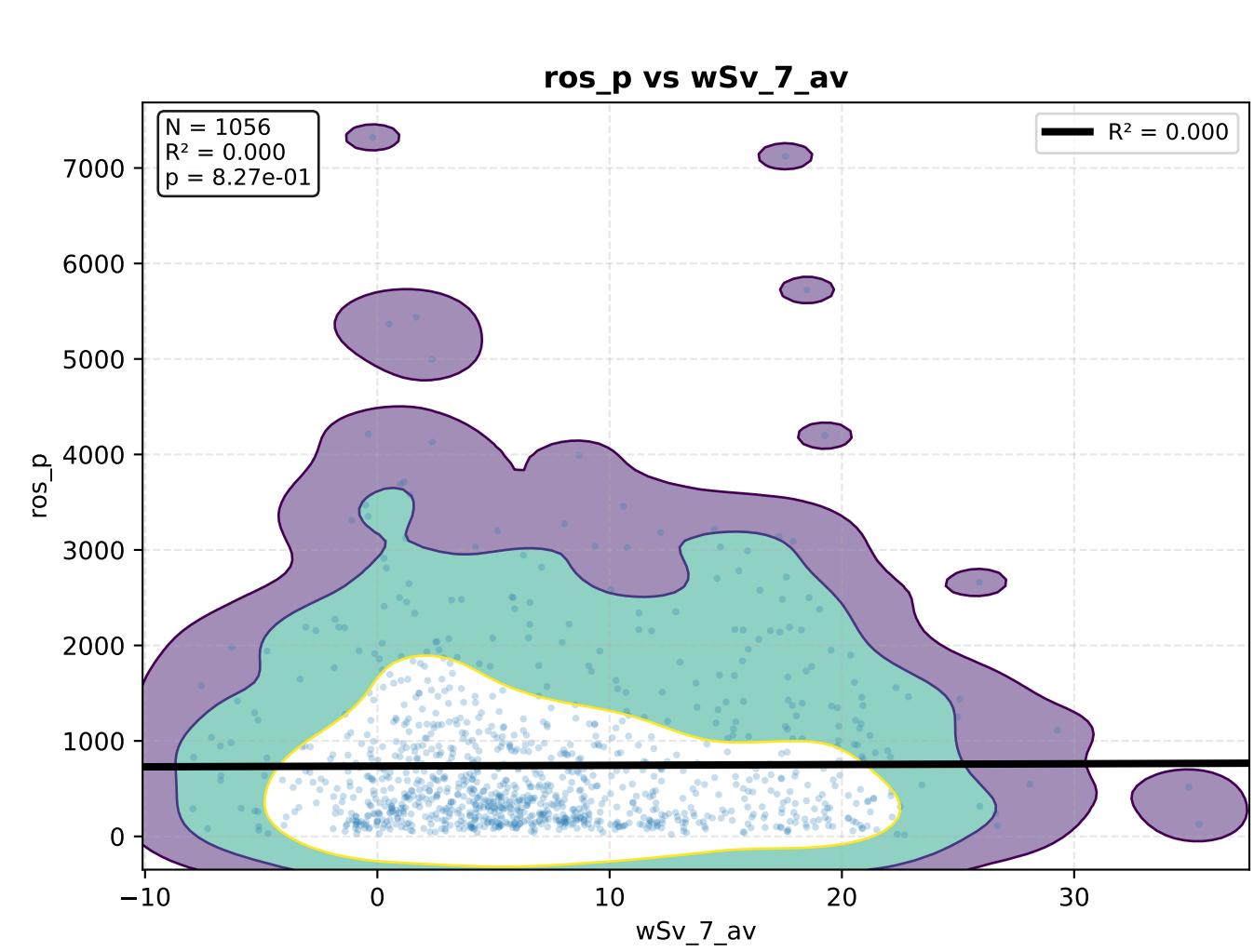
**log(ros\_p) vs wSdir\_9\_av**



**log(ros\_p) vs log(wSdir\_9\_av)**

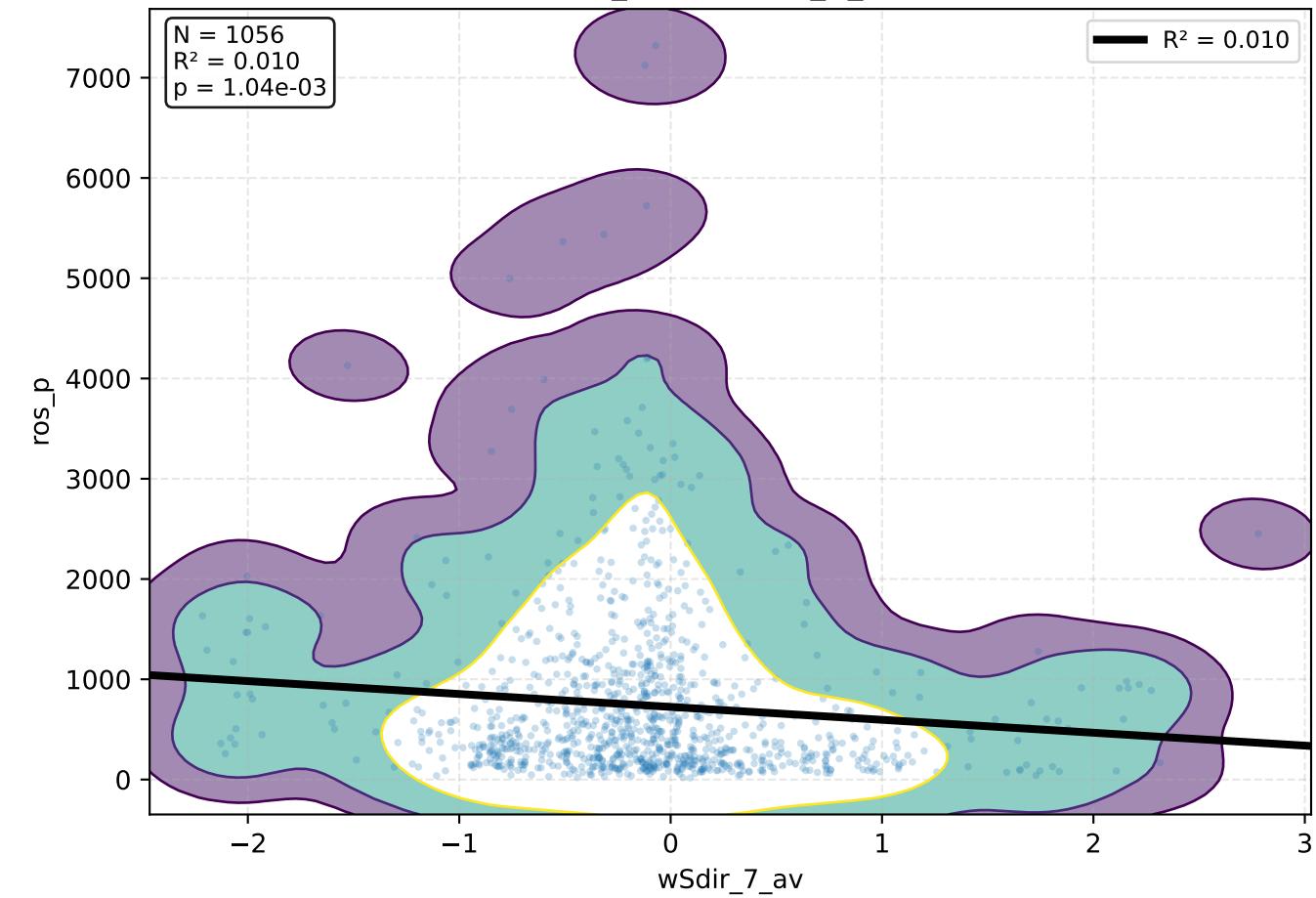


# wSv\_7\_av - KDE Density + Regressão

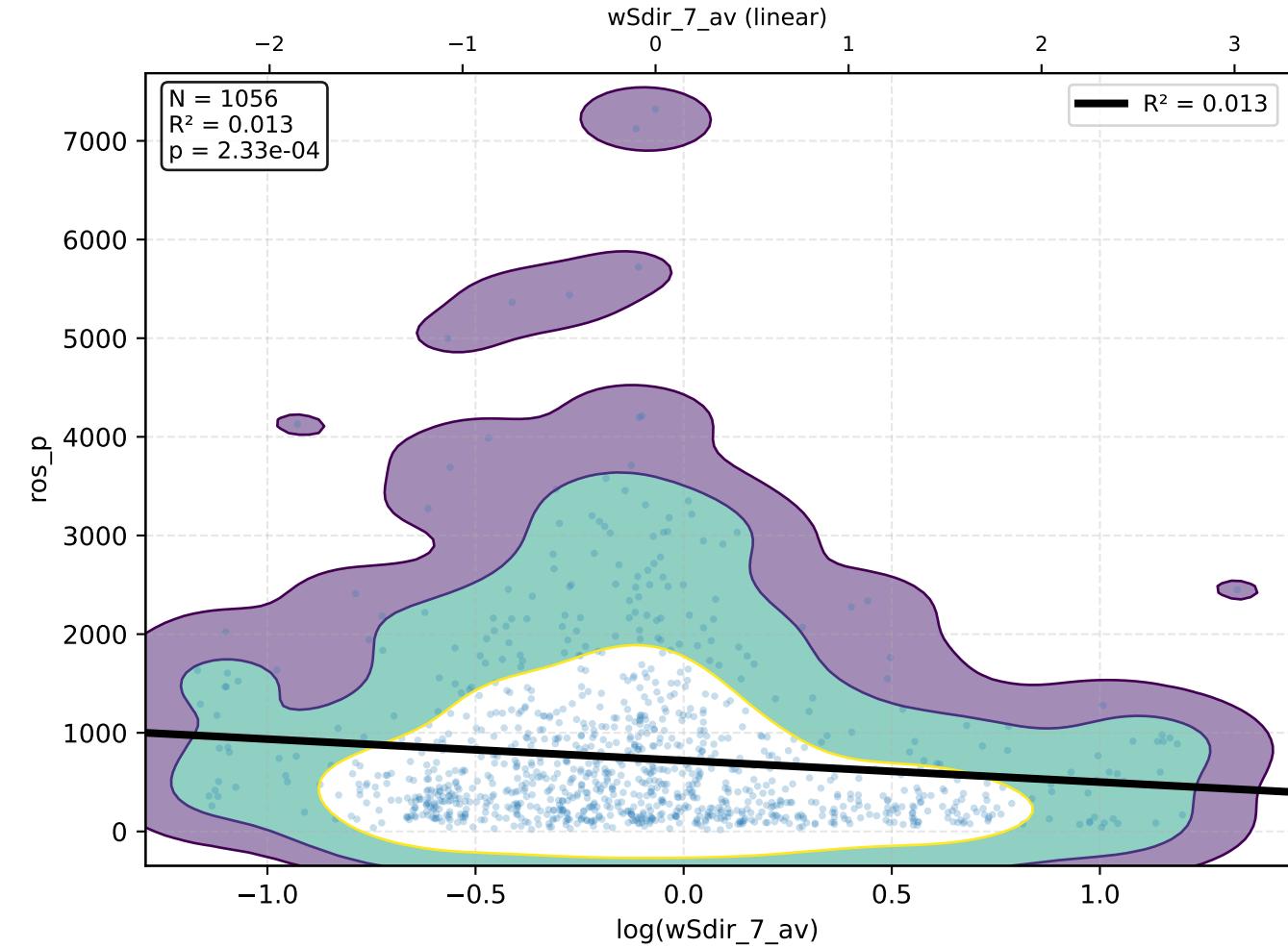


# wSdir\_7\_av - KDE Density + Regressão

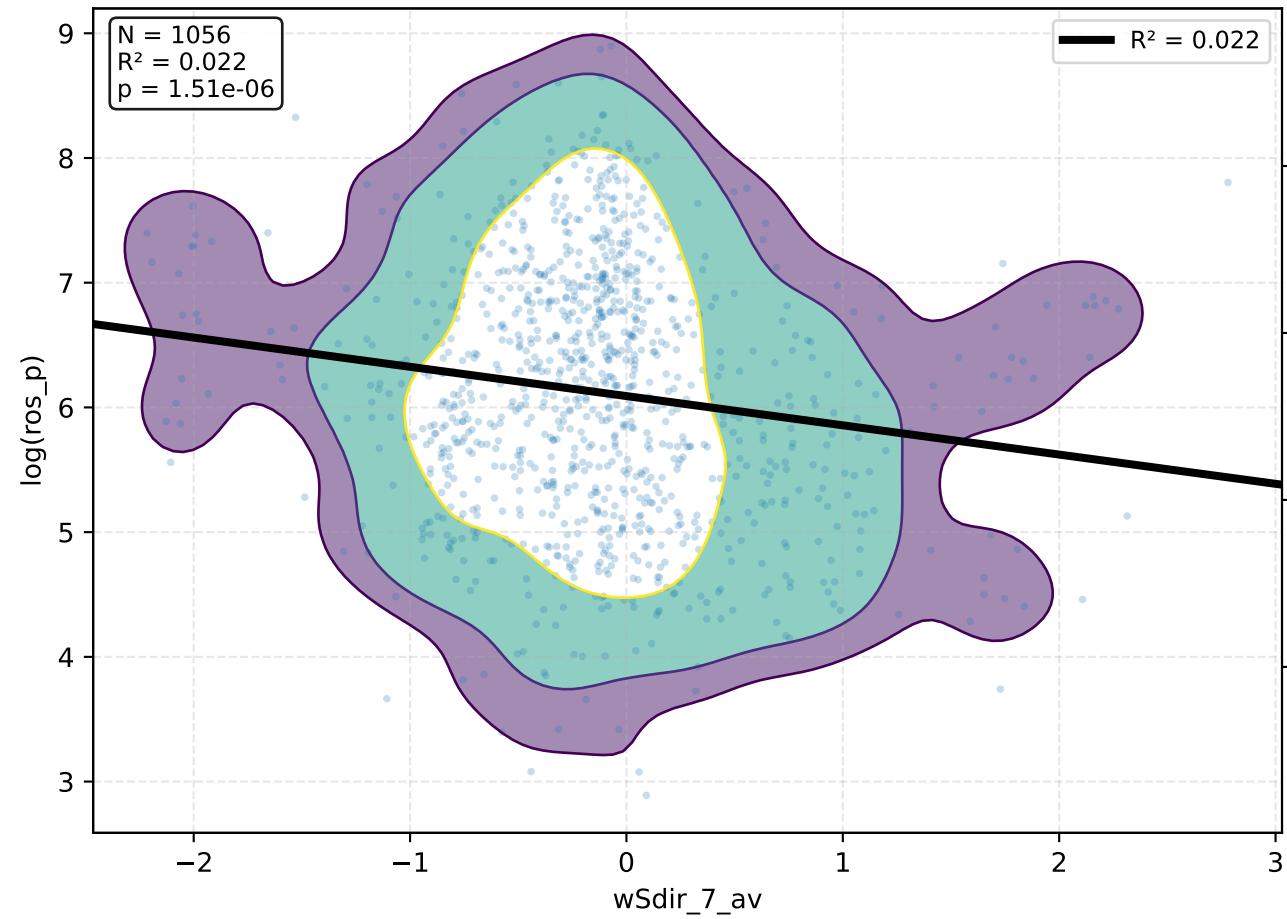
**ros\_p vs wSdir\_7\_av**



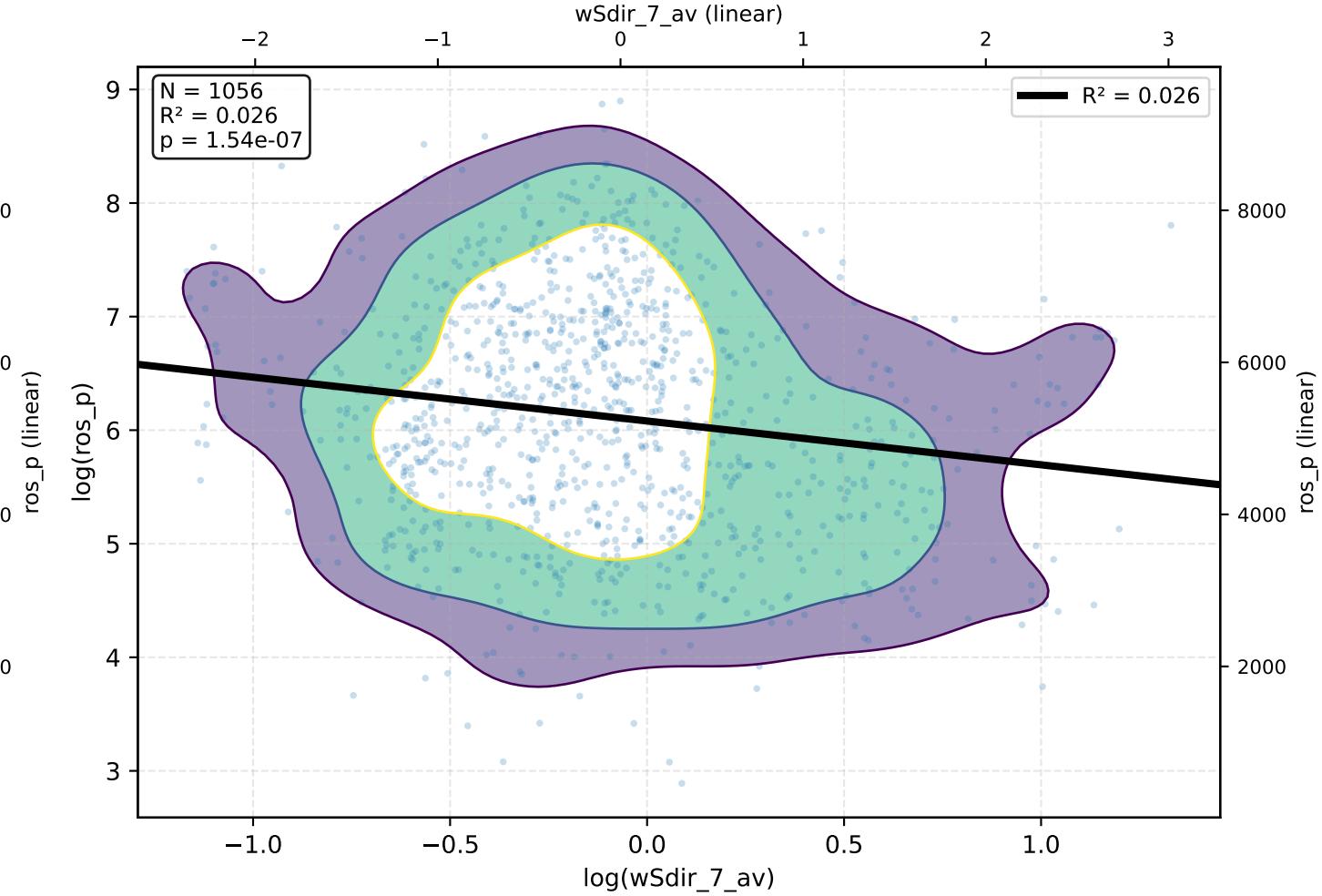
**ros\_p vs log(wSdir\_7\_av)**



**log(ros\_p) vs wSdir\_7\_av**

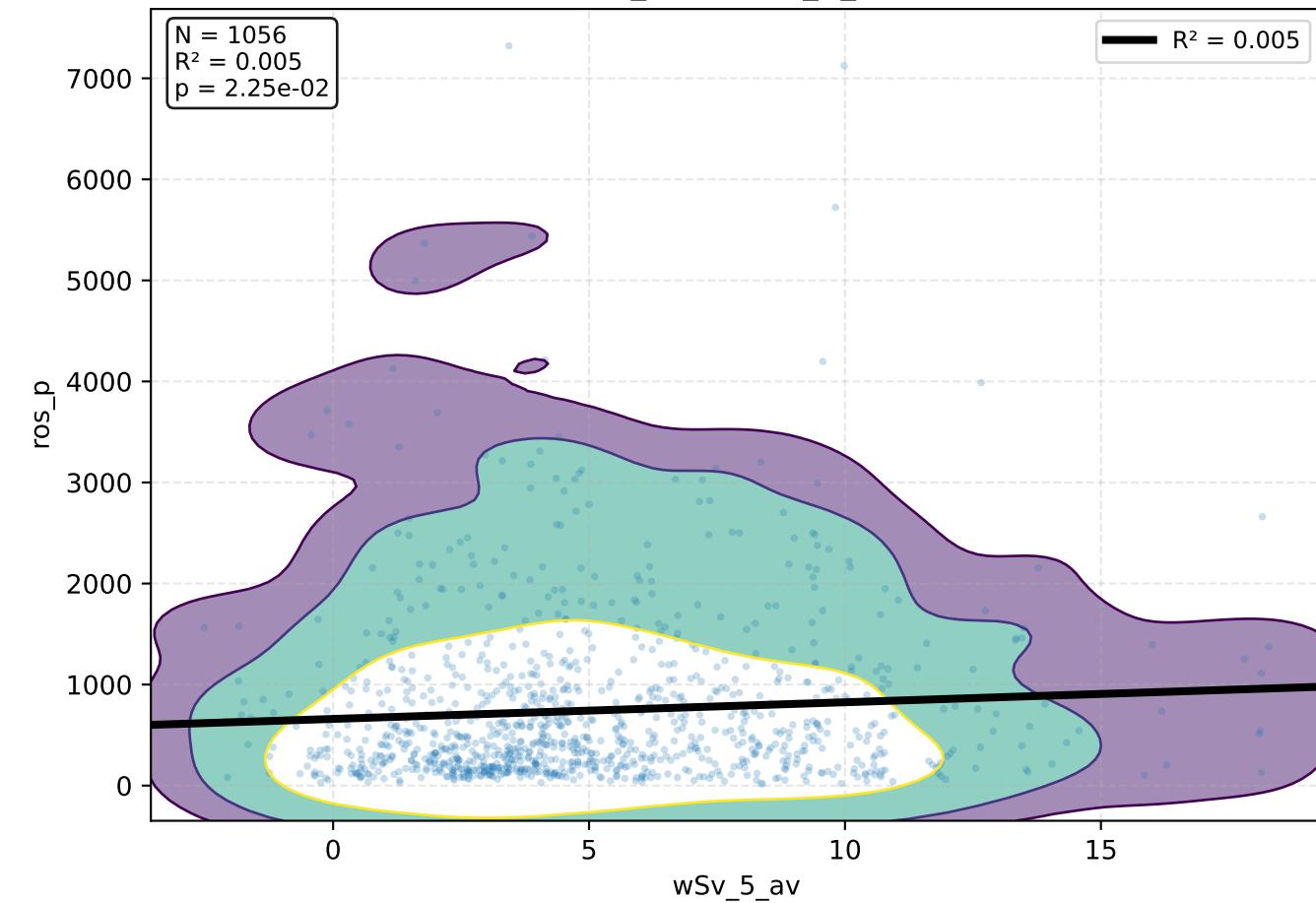


**log(ros\_p) vs log(wSdir\_7\_av)**

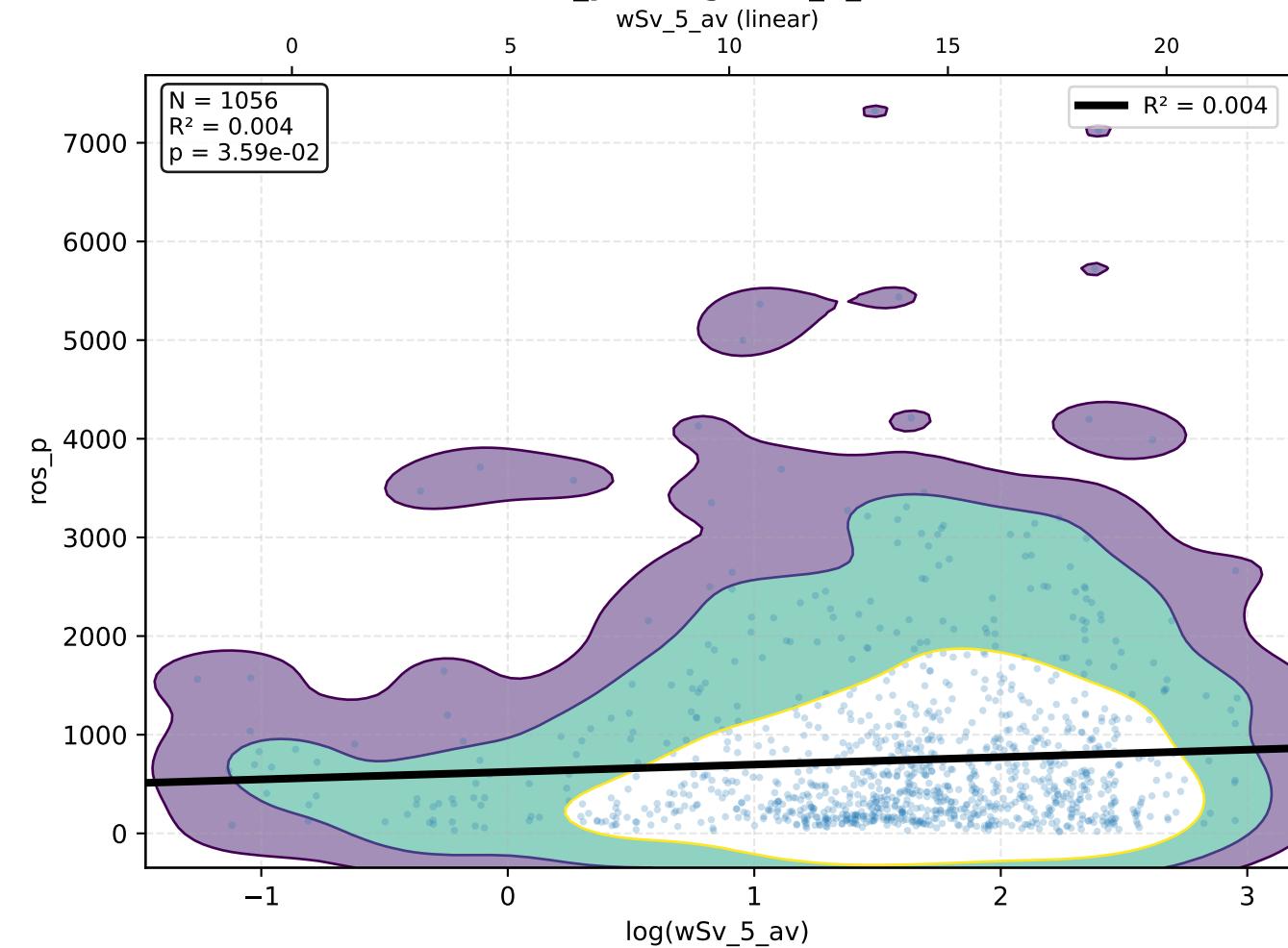


# wSv\_5\_av - KDE Density + Regressão

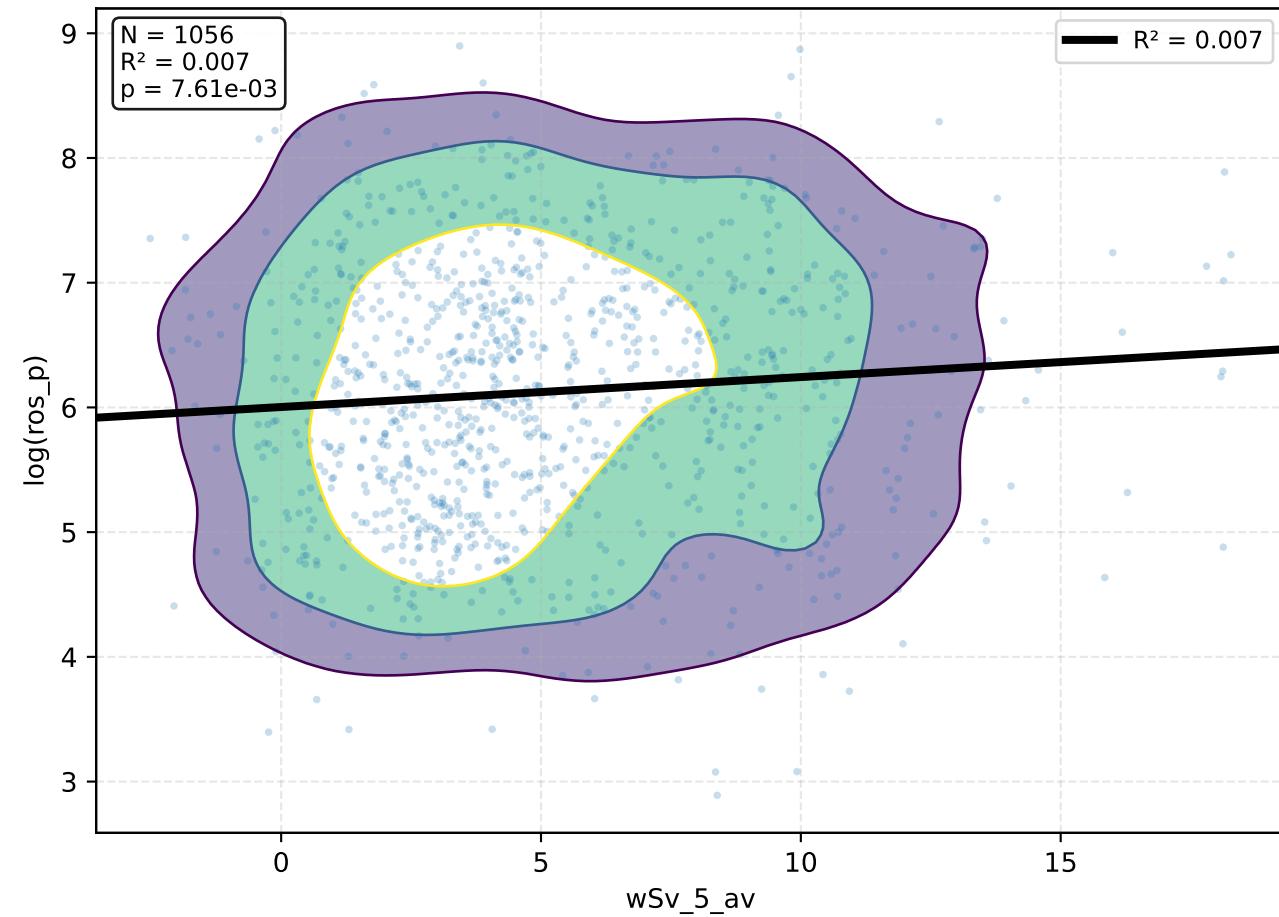
**ros\_p vs wSv\_5\_av**



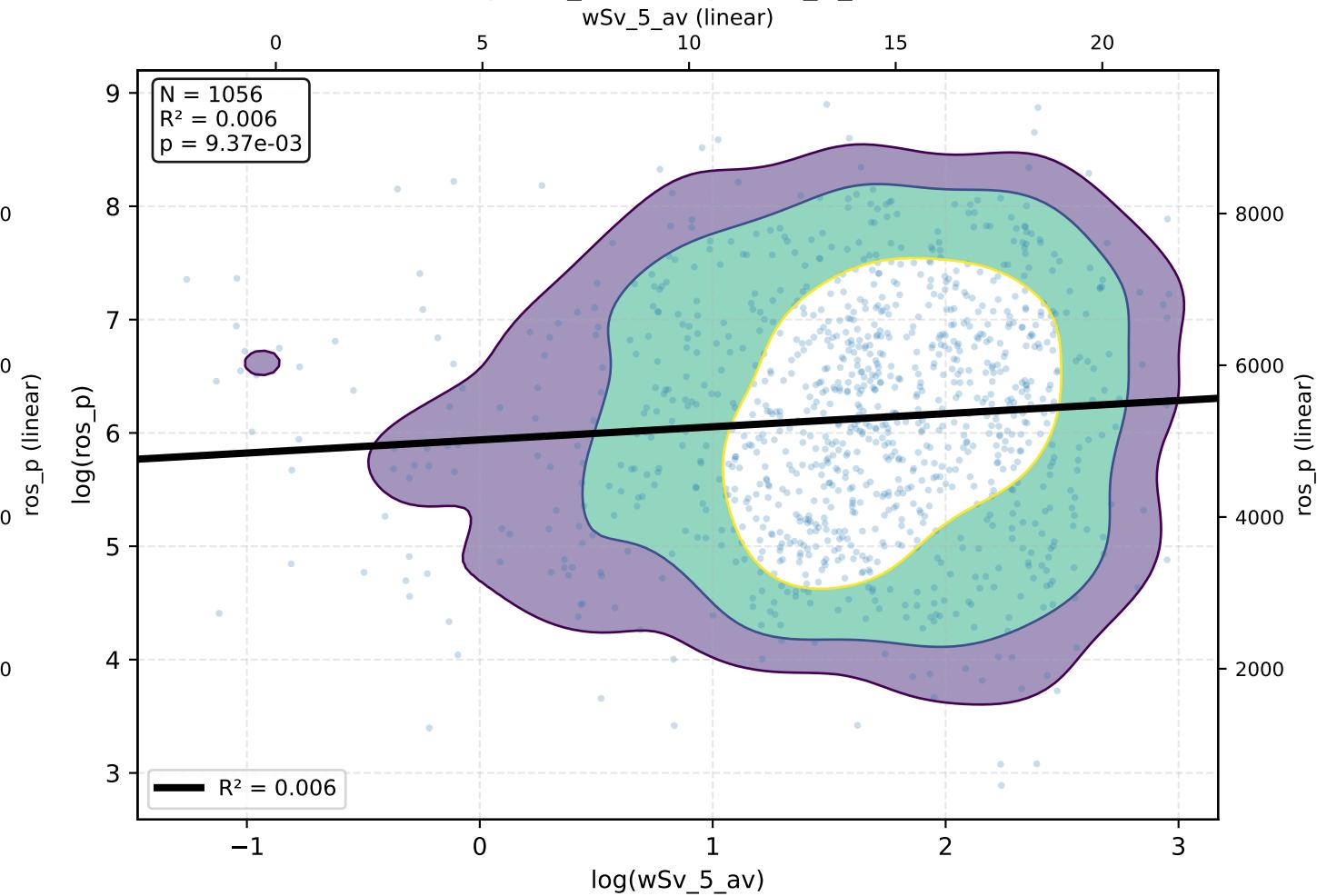
**ros\_p vs log(wSv\_5\_av)**



**log(ros\_p) vs wSv\_5\_av**

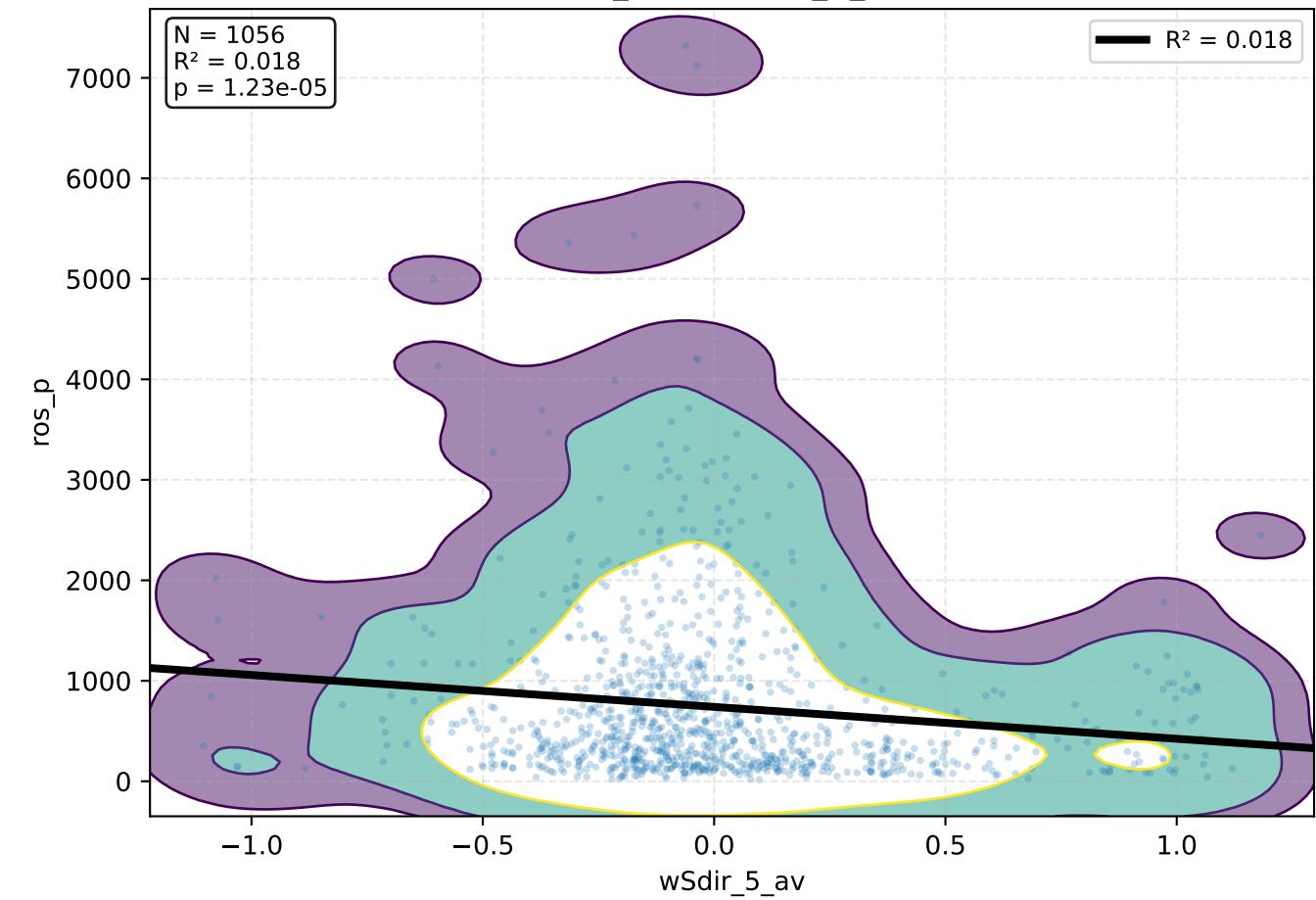


**log(ros\_p) vs log(wSv\_5\_av)**

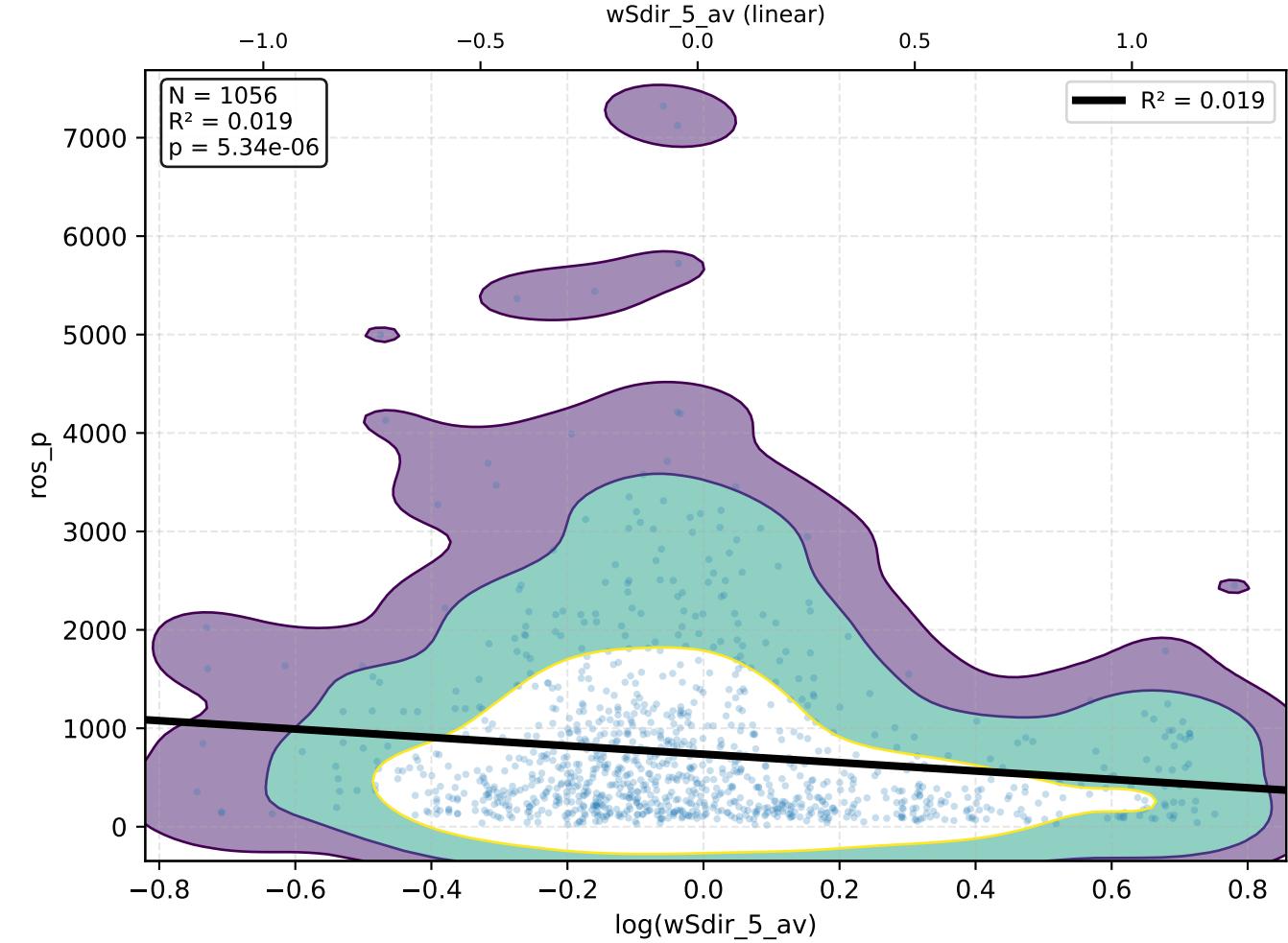


# wSdir\_5\_av - KDE Density + Regressão

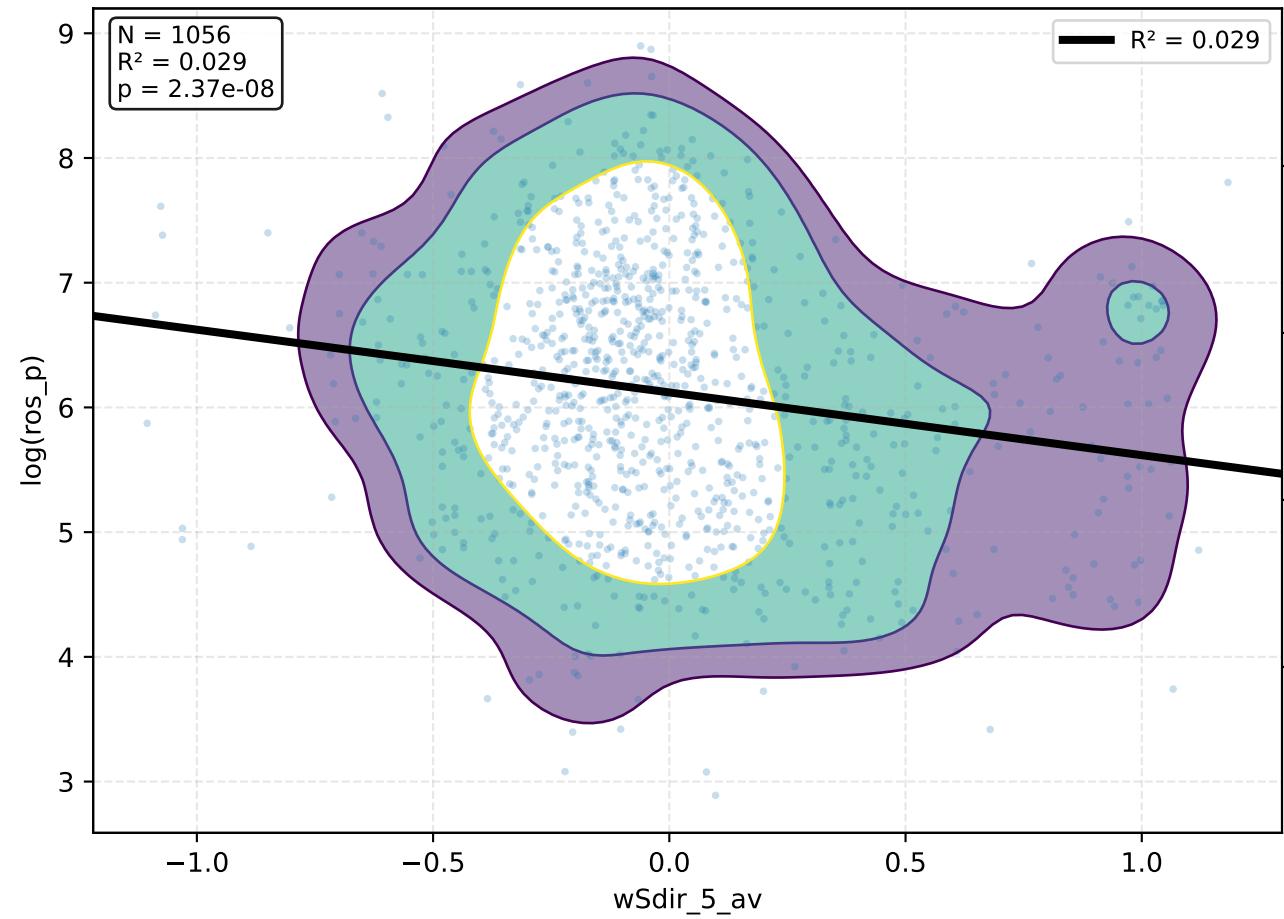
**ros\_p vs wSdir\_5\_av**



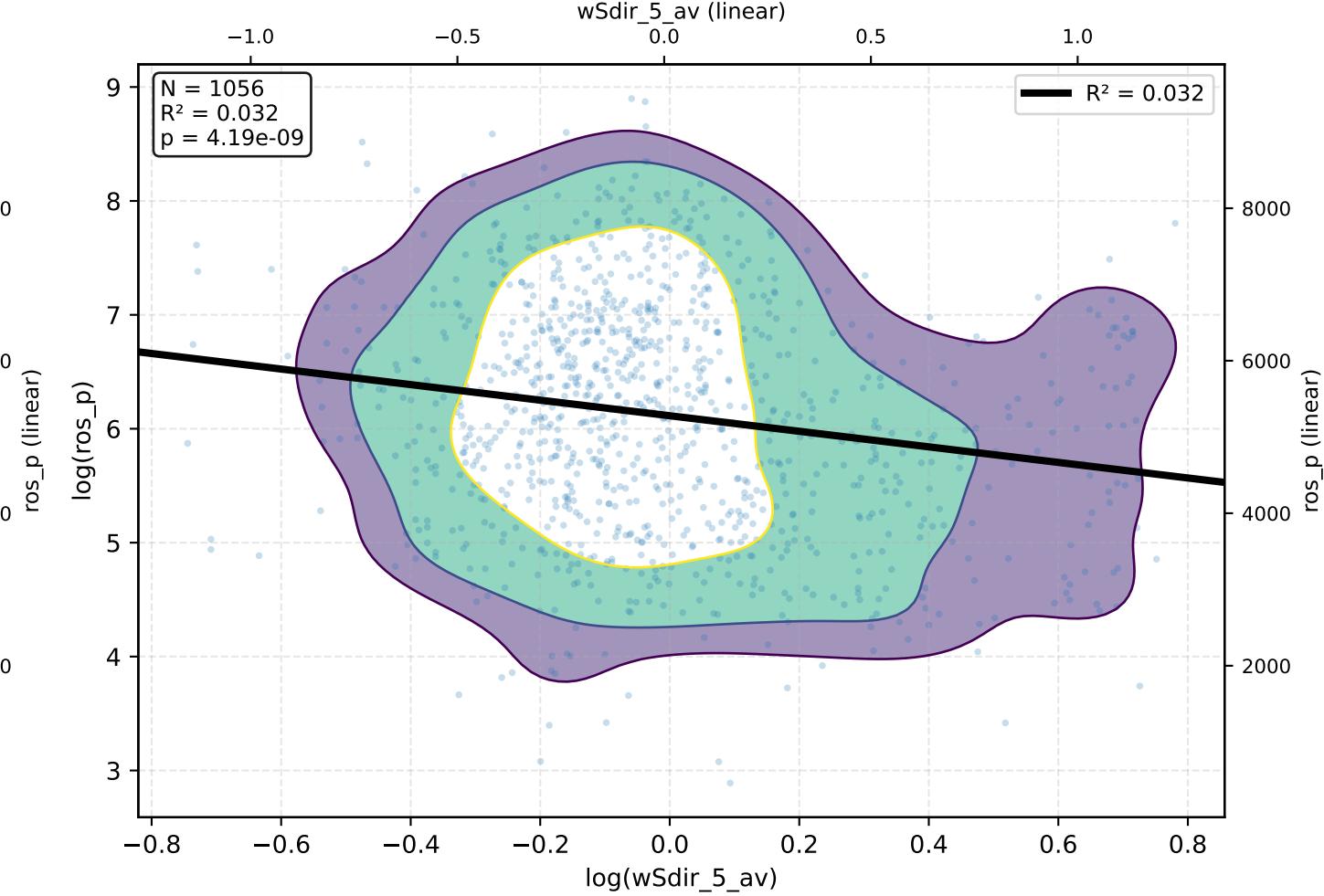
**ros\_p vs log(wSdir\_5\_av)**



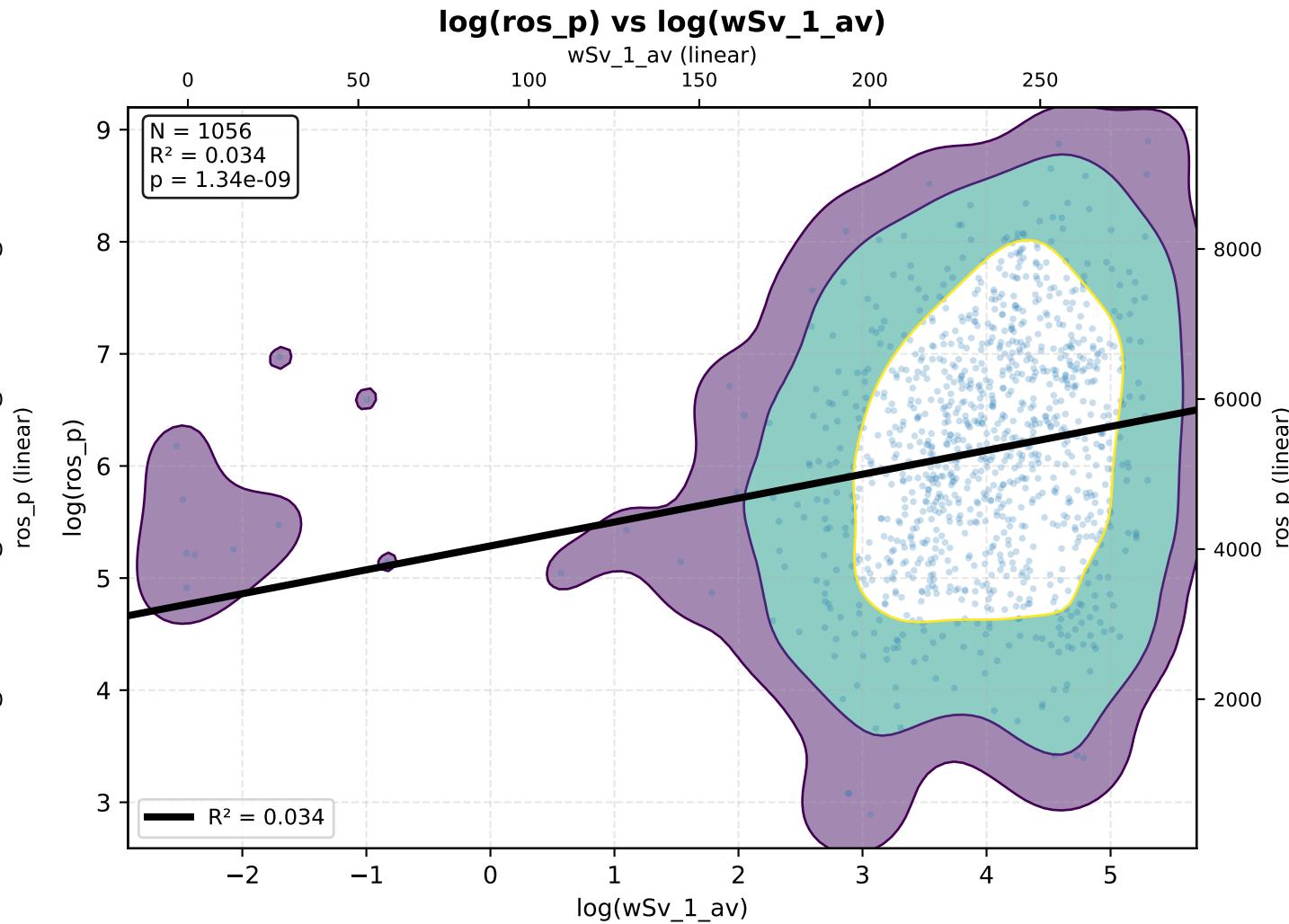
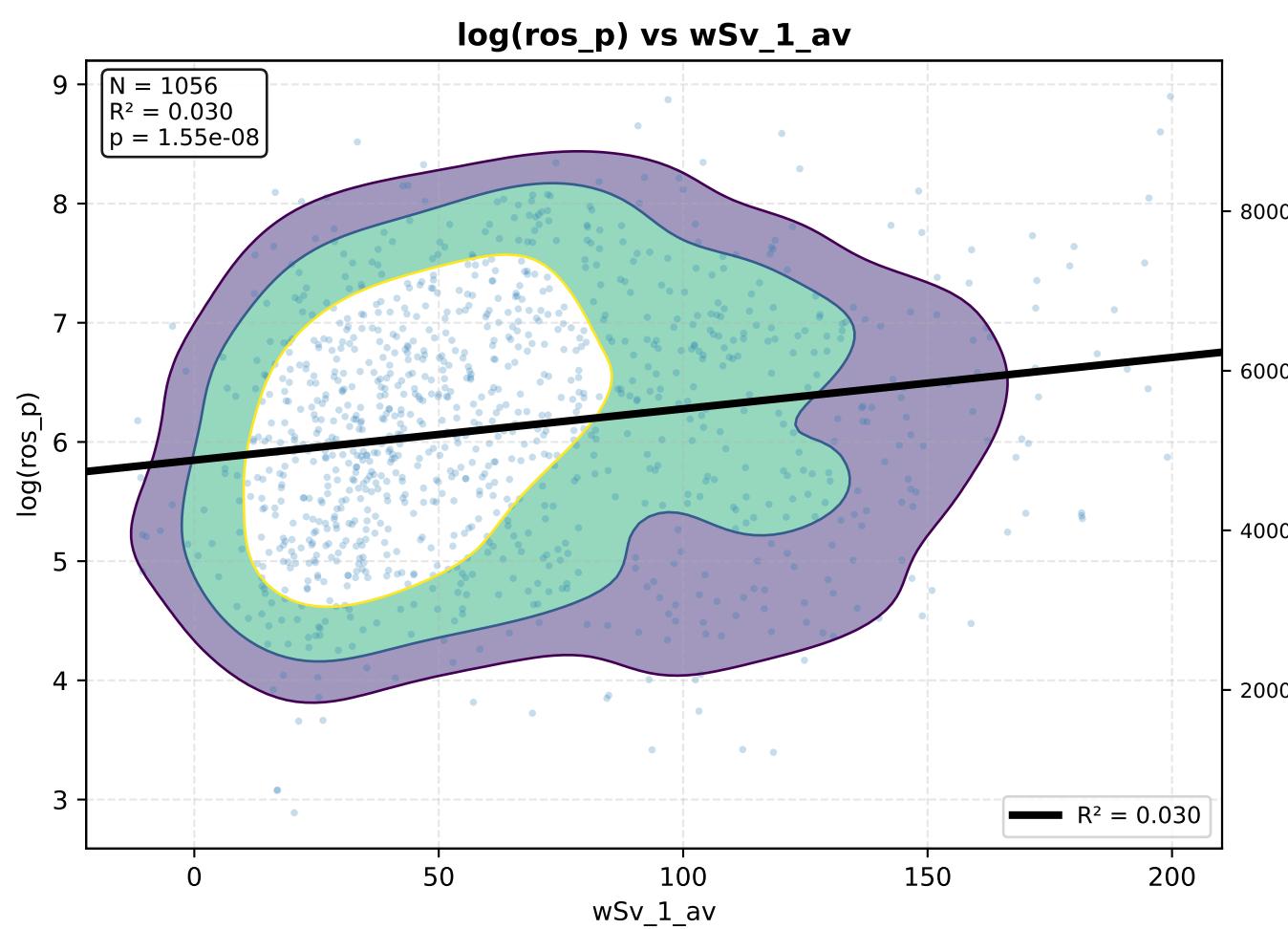
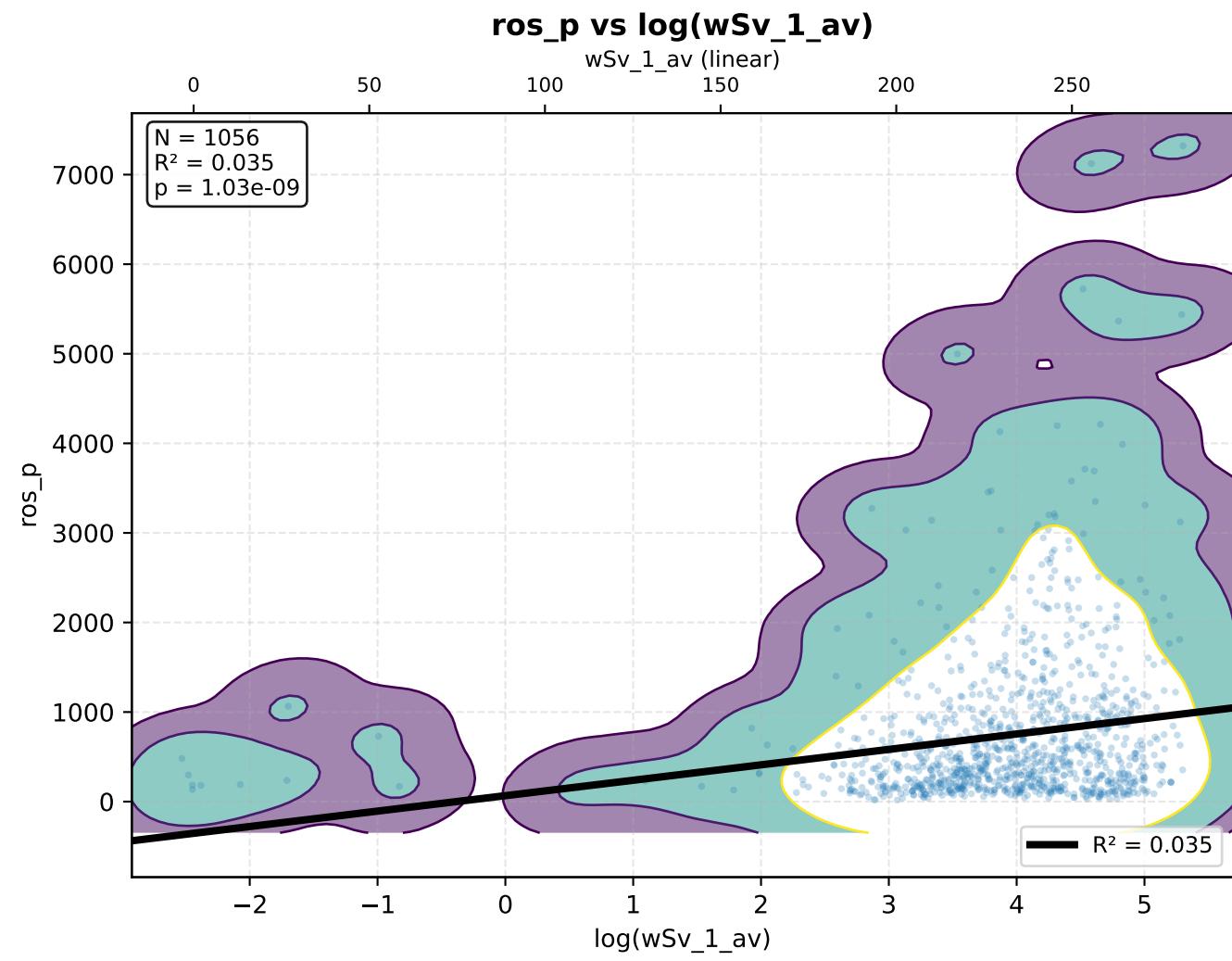
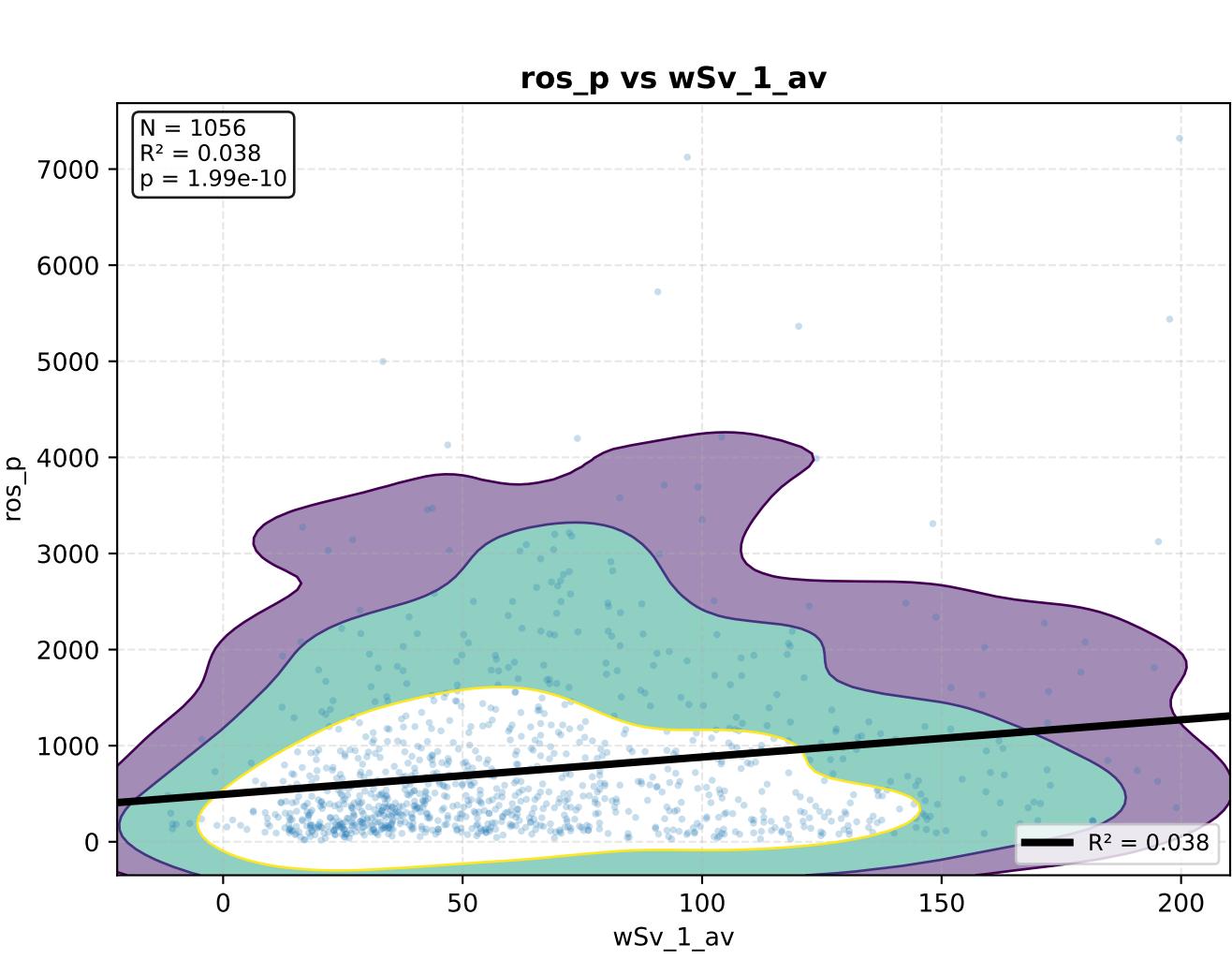
**log(ros\_p) vs wSdir\_5\_av**



**log(ros\_p) vs log(wSdir\_5\_av)**

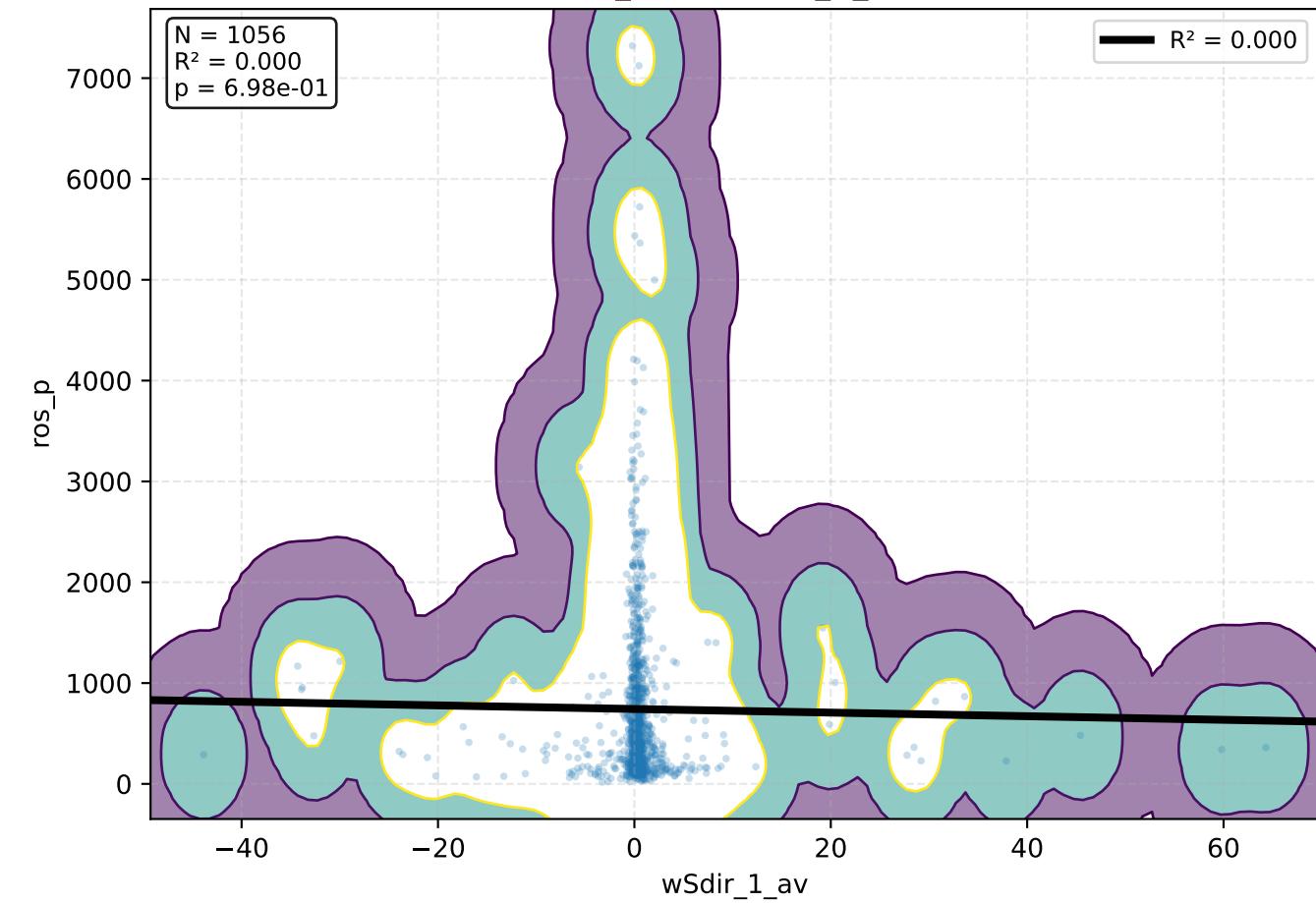


# wSv\_1\_av - KDE Density + Regressão

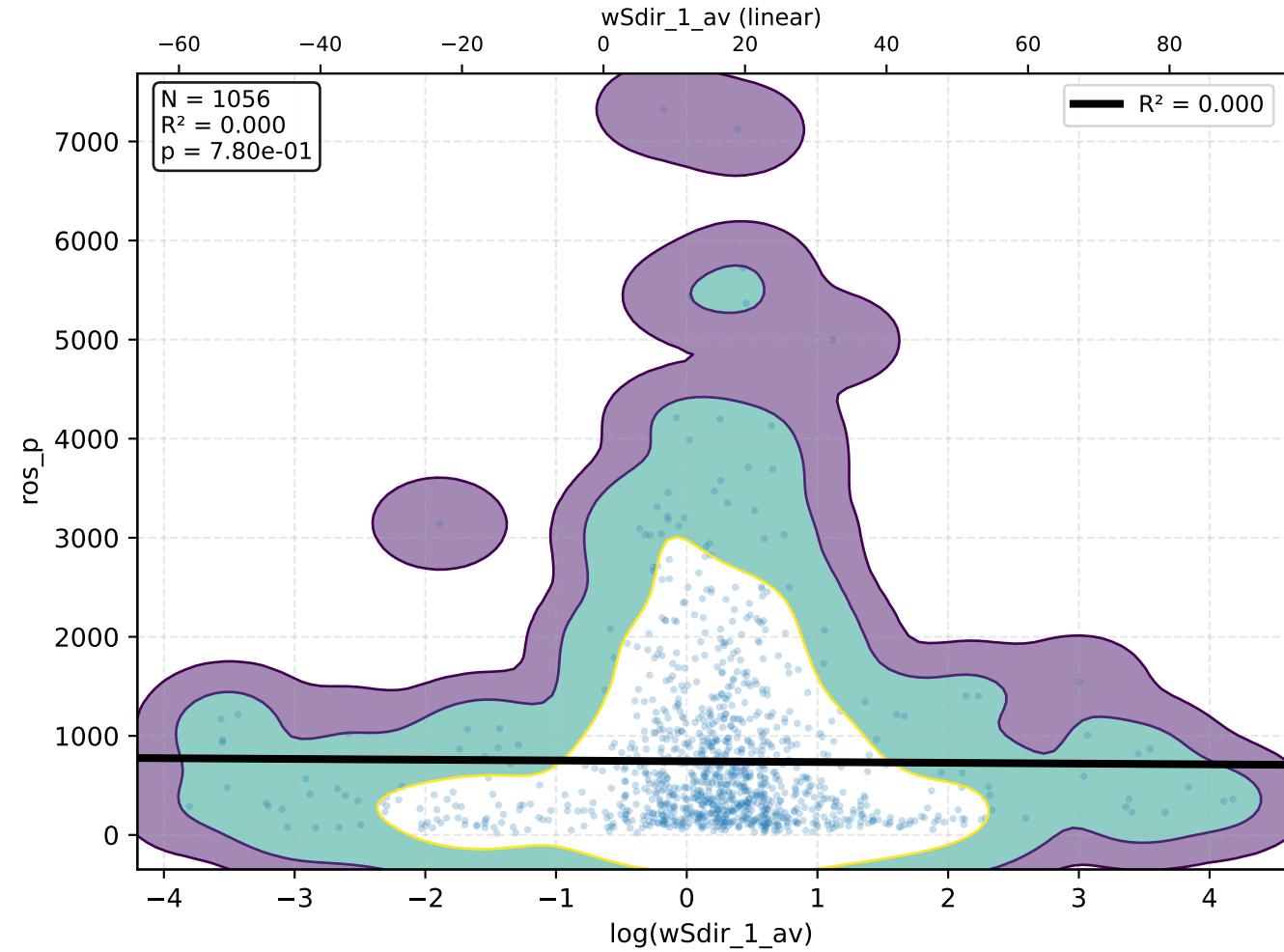


# wSdir\_1\_av - KDE Density + Regressão

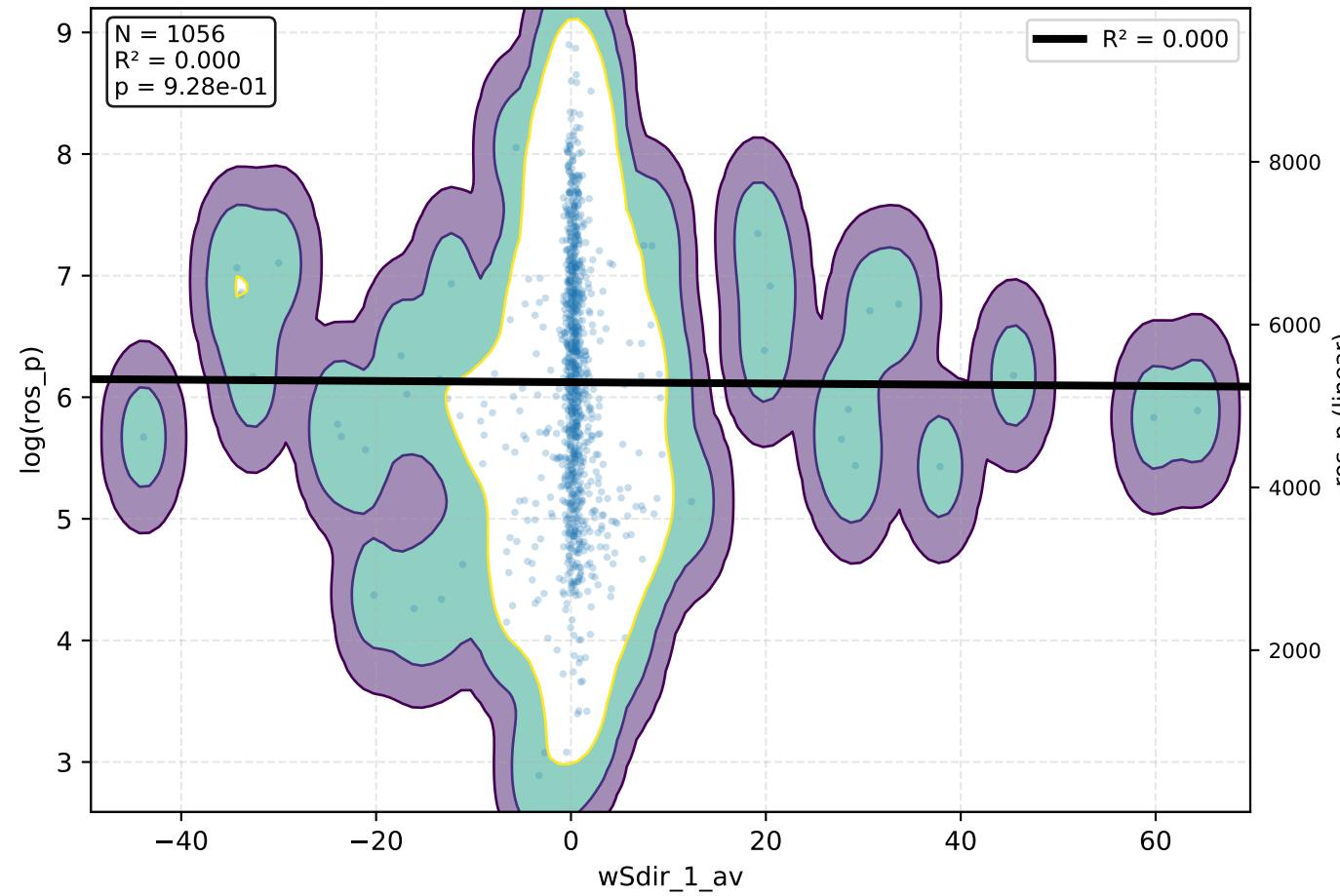
**ros\_p vs wSdir\_1\_av**



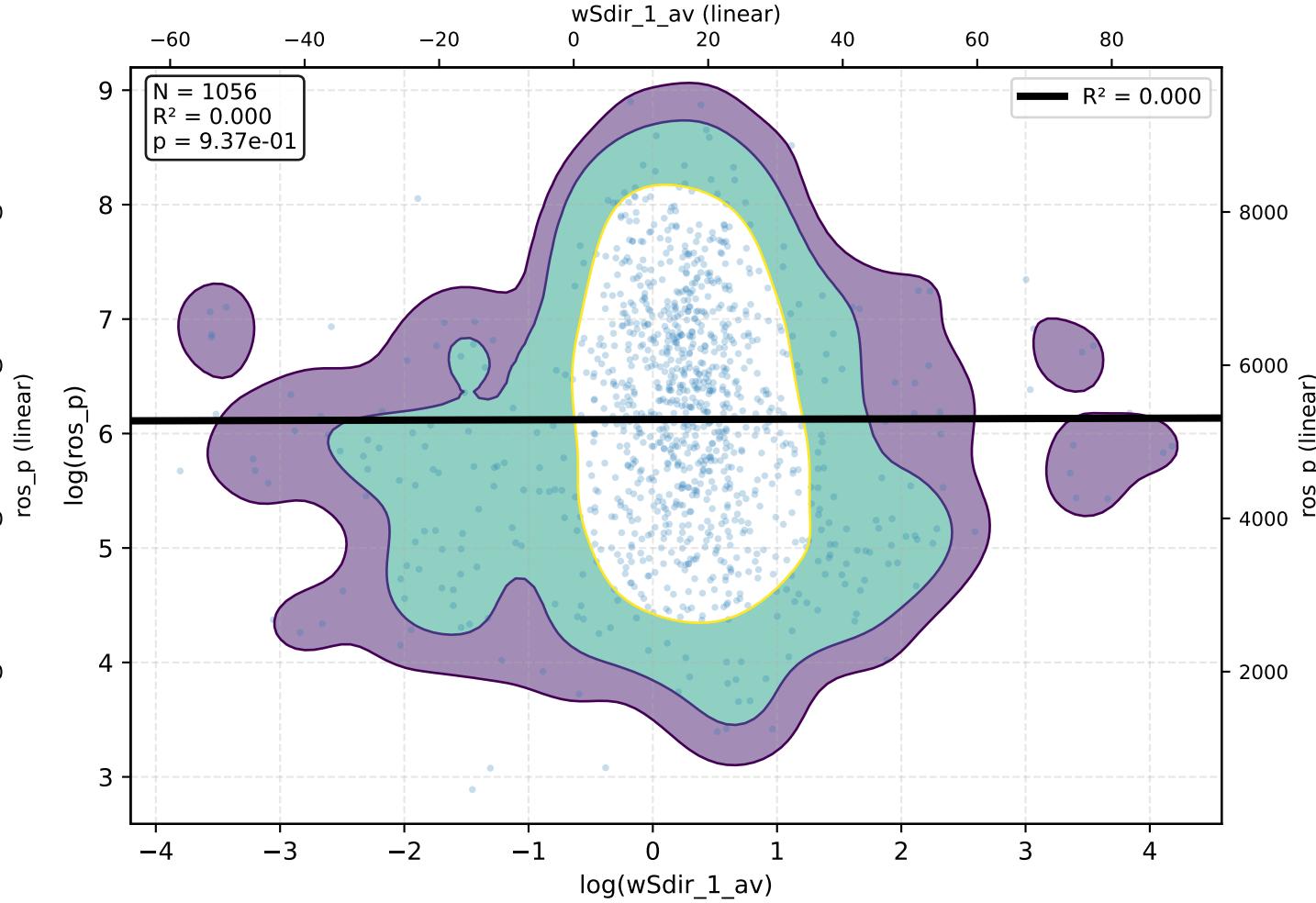
**ros\_p vs log(wSdir\_1\_av)**



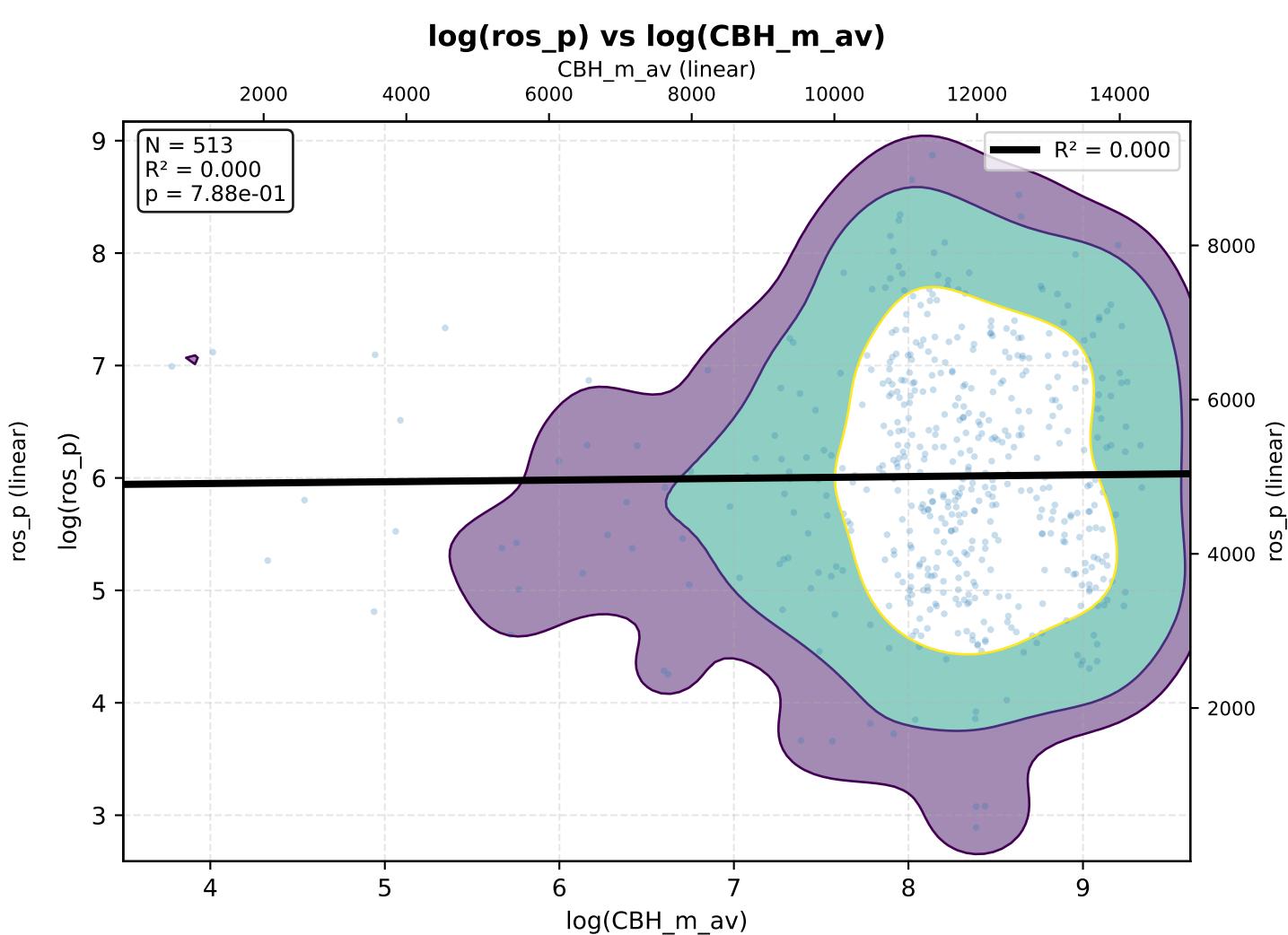
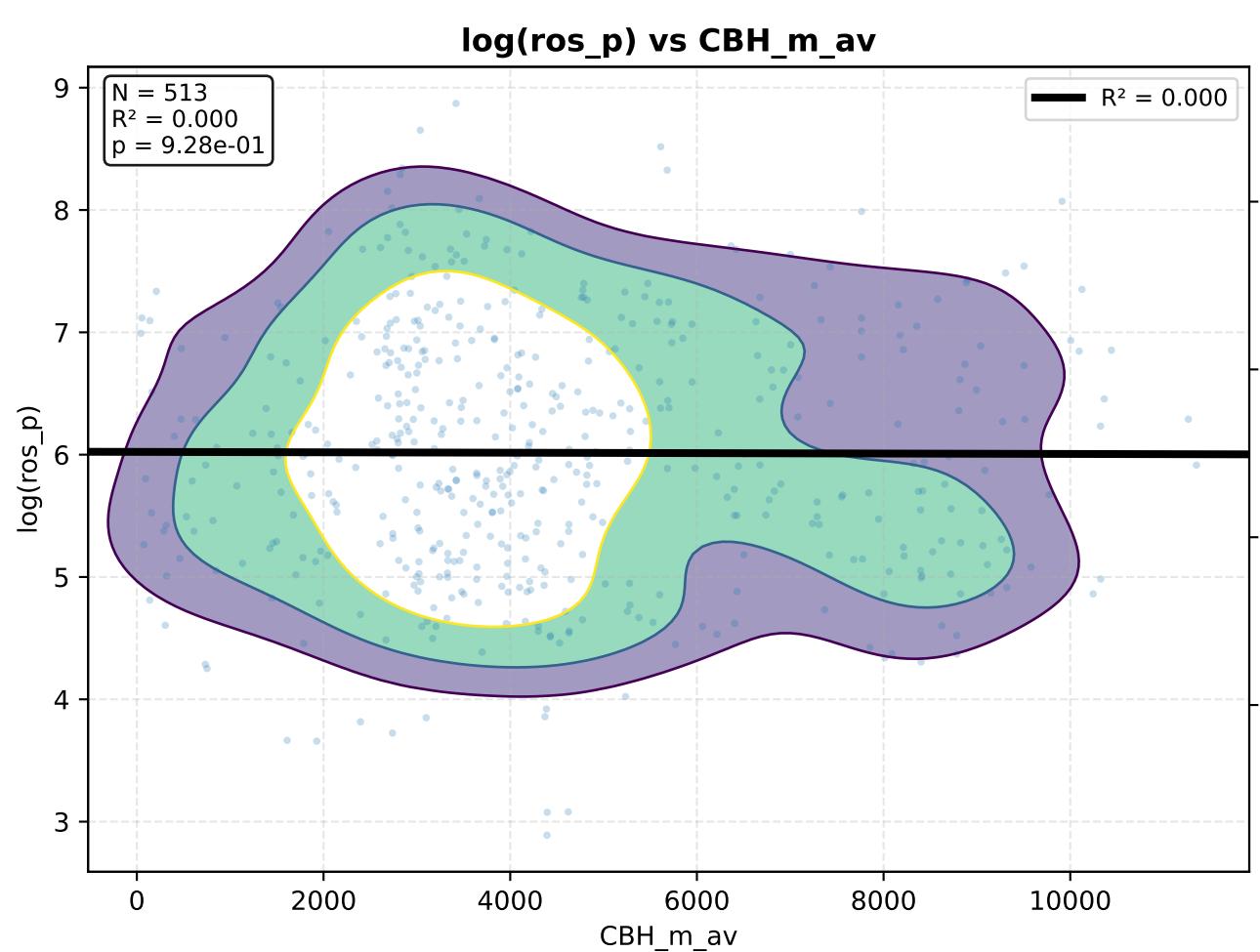
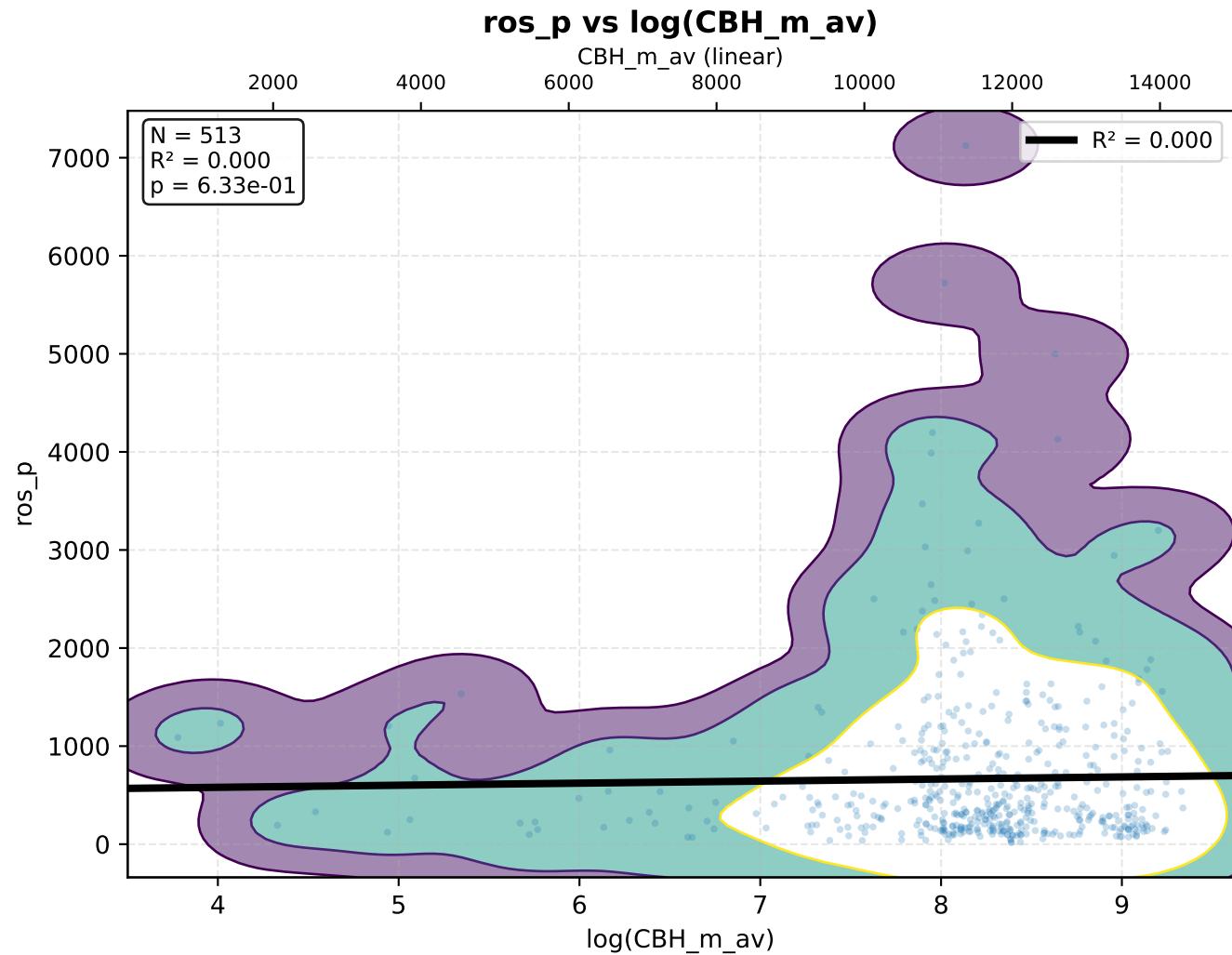
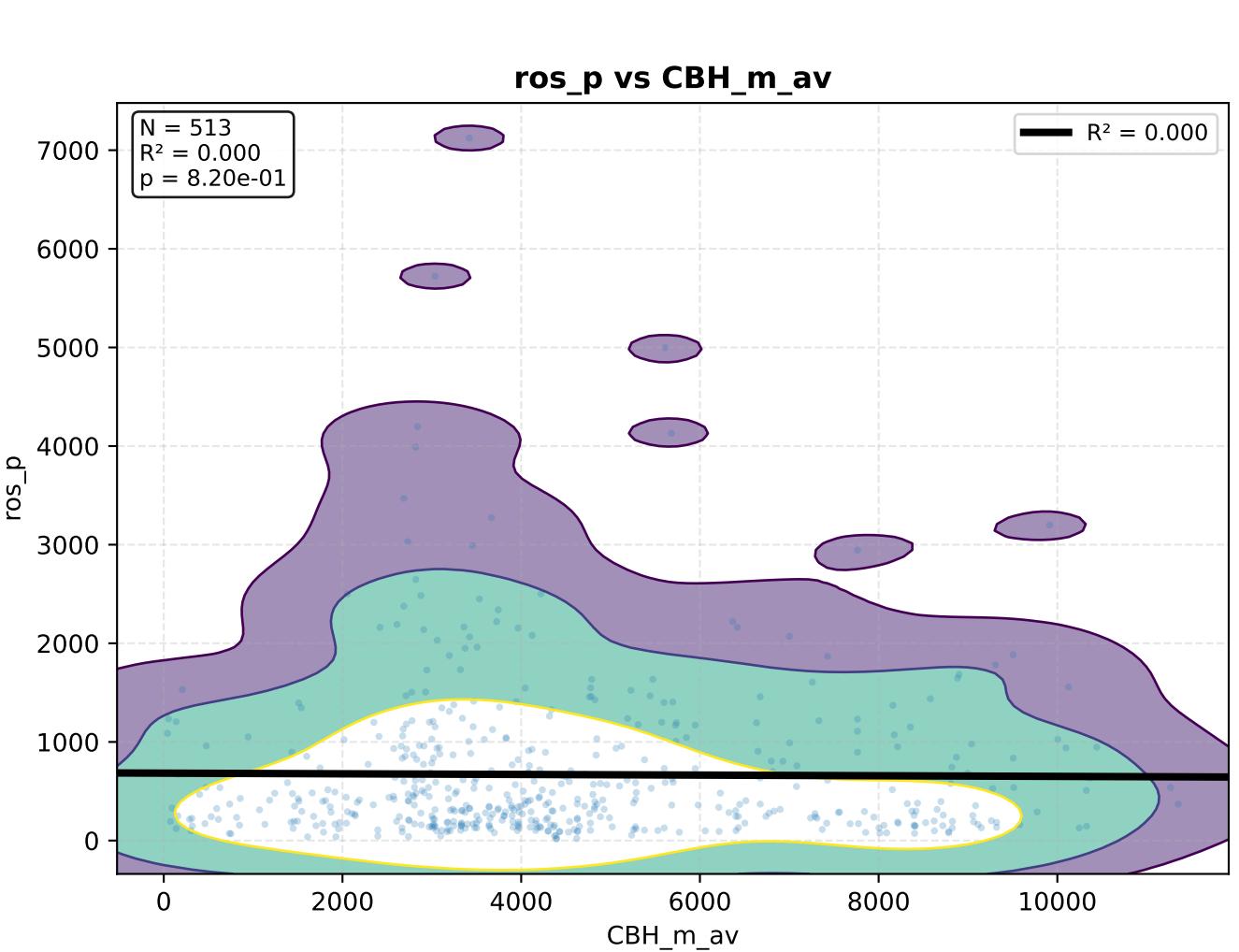
**log(ros\_p) vs wSdir\_1\_av**



**log(ros\_p) vs log(wSdir\_1\_av)**

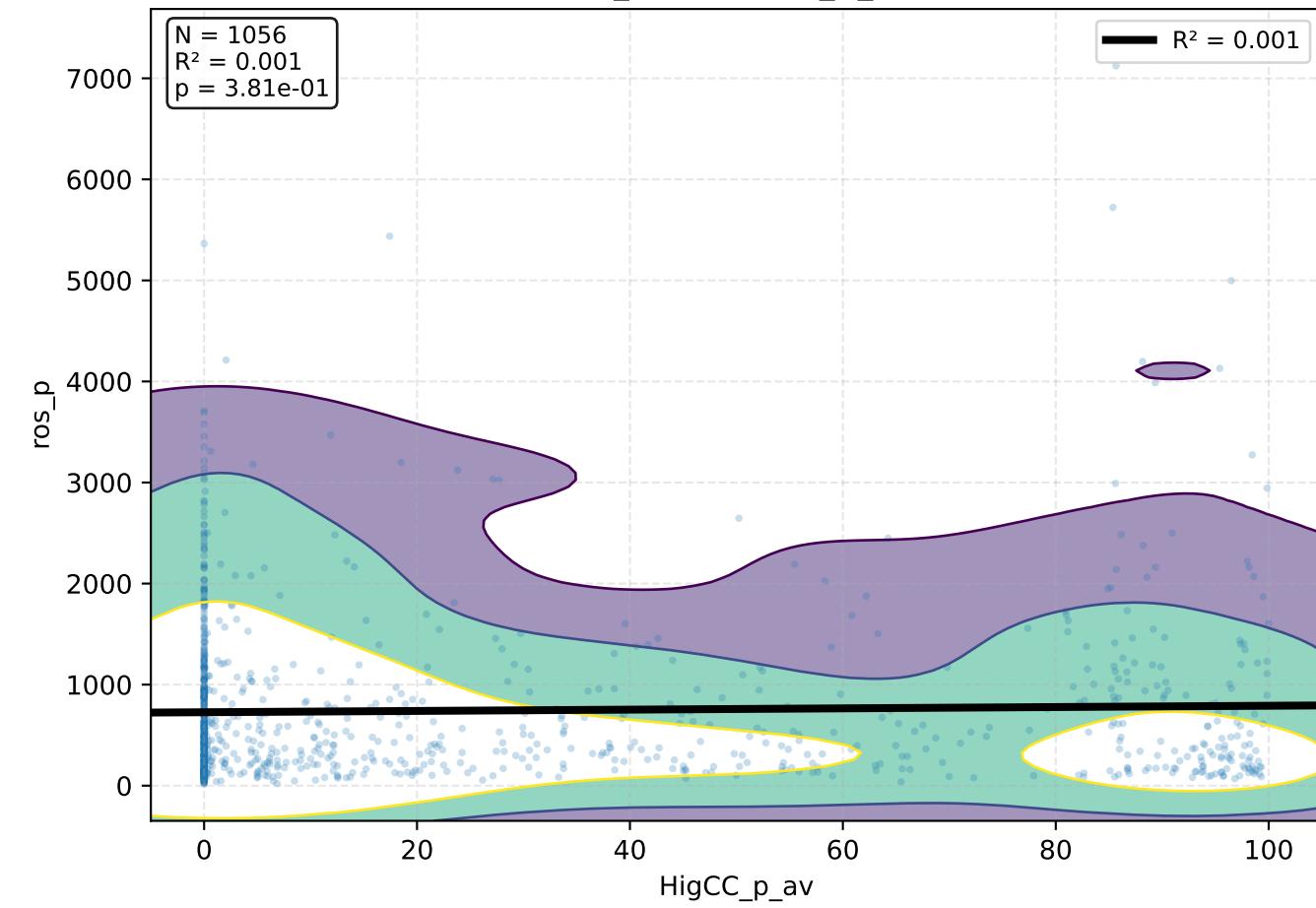


# CBH\_m\_av - KDE Density + Regressão

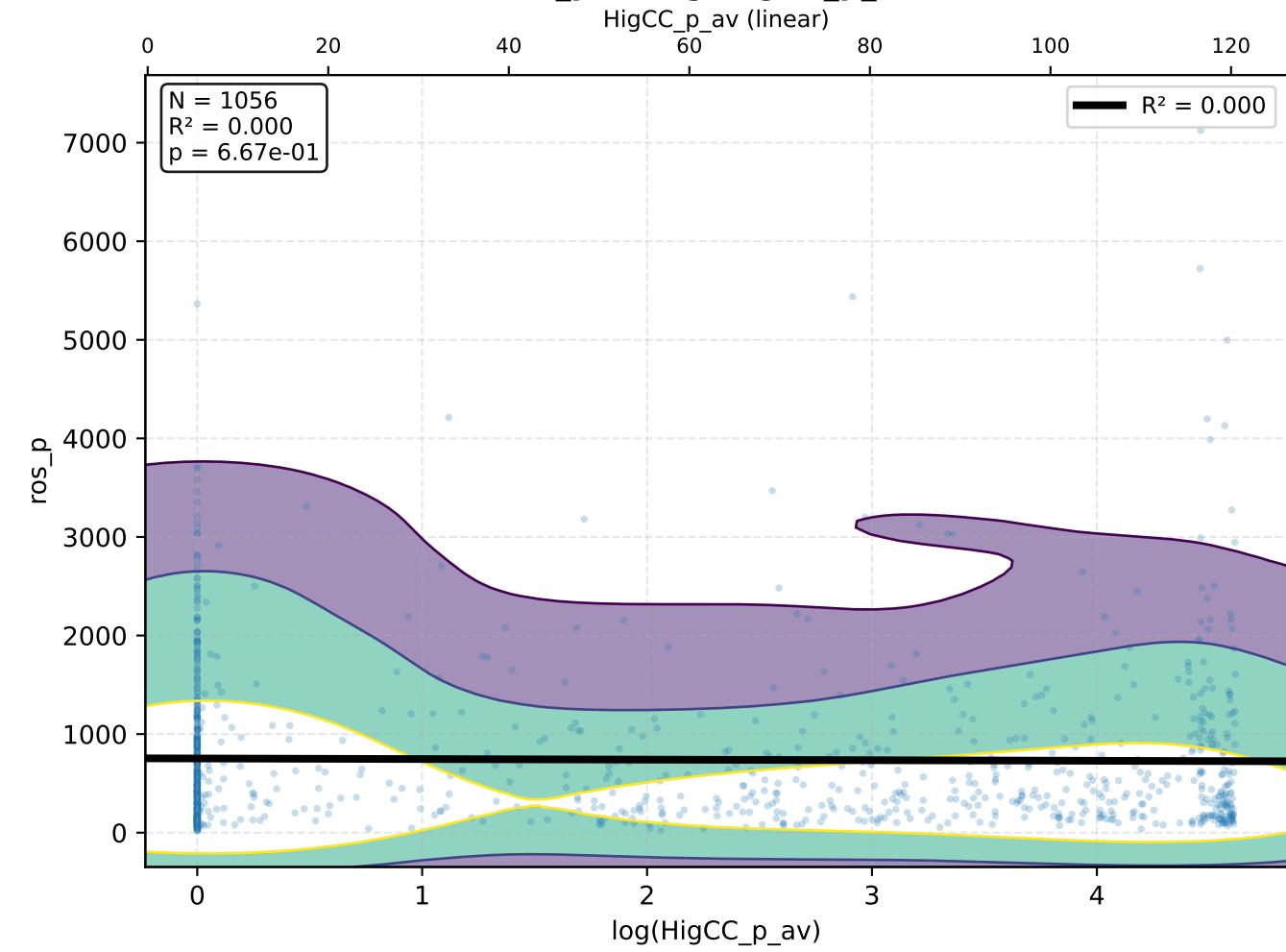


# HigCC\_p\_av – KDE Density + Regressão

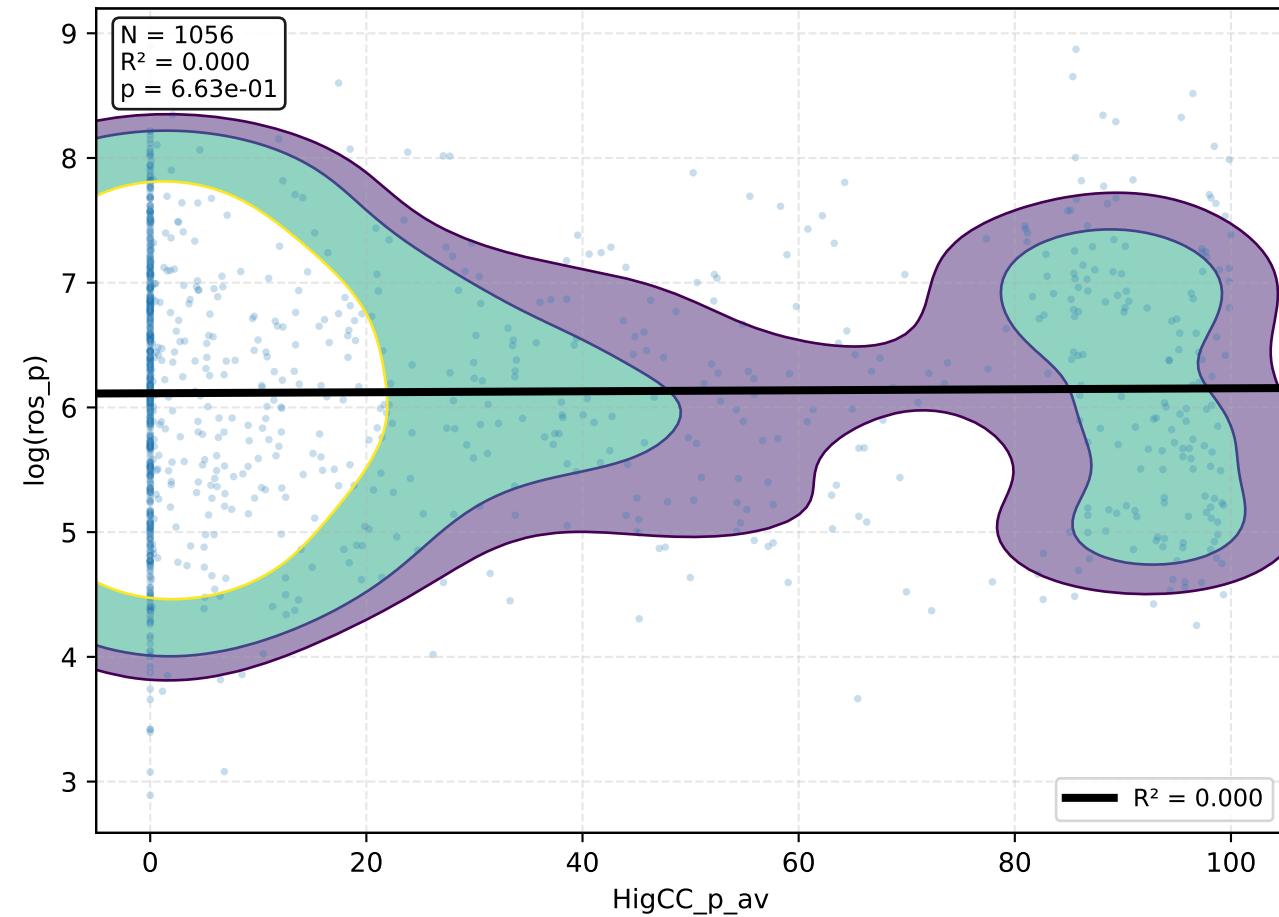
**ros\_p vs HigCC\_p\_av**



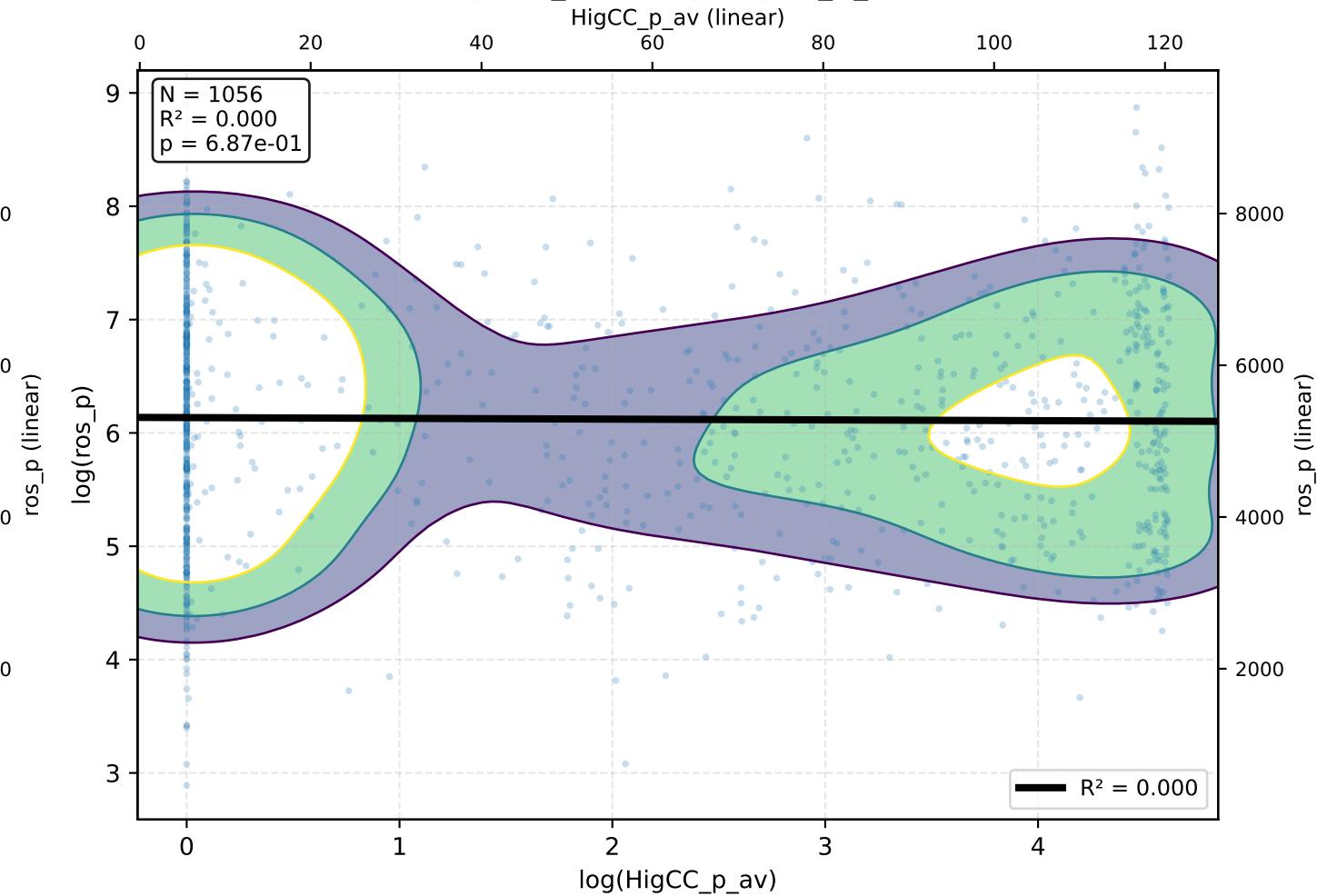
**ros\_p vs log(HigCC\_p\_av)**



**log(ros\_p) vs HigCC\_p\_av**

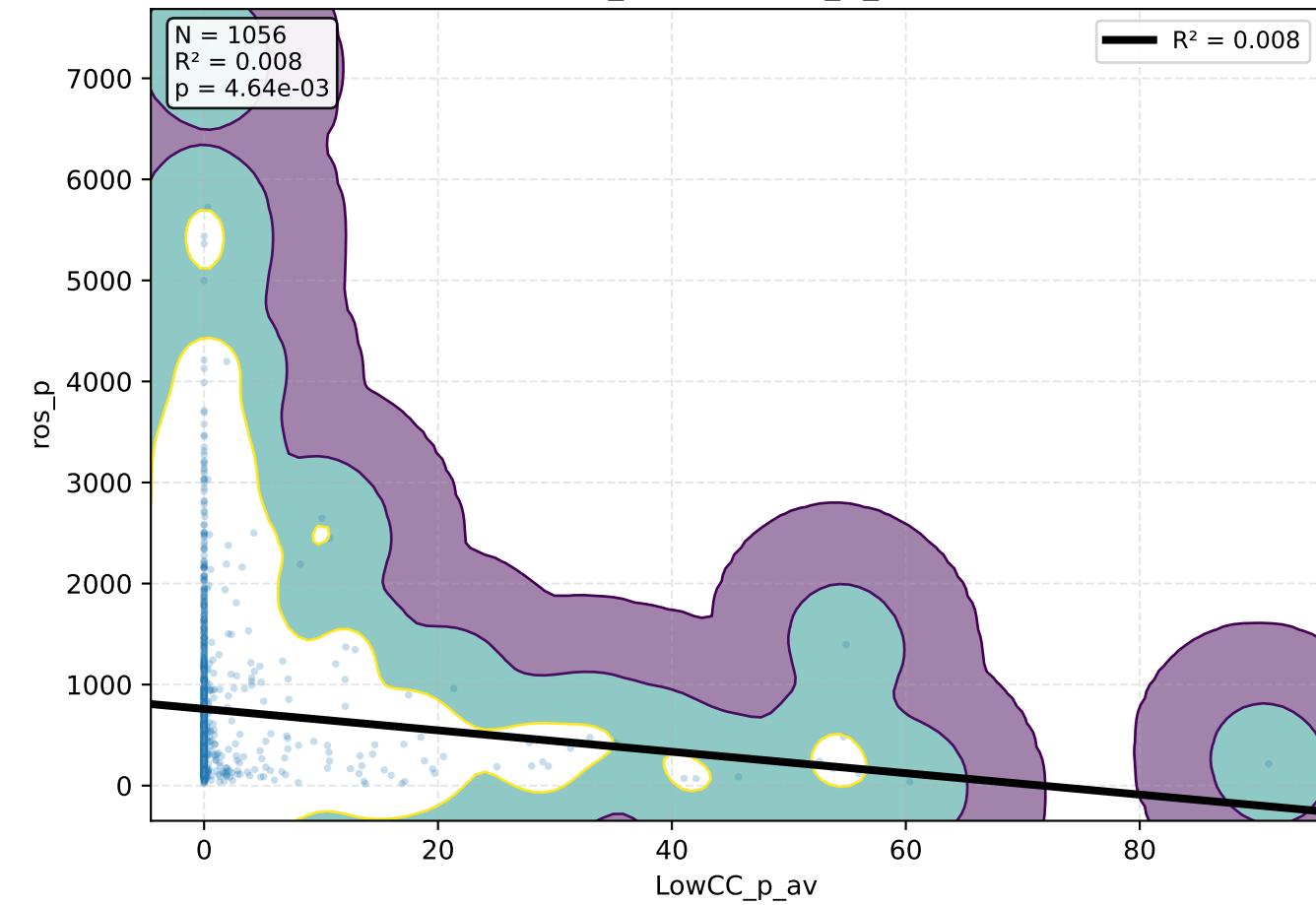


**log(ros\_p) vs log(HigCC\_p\_av)**

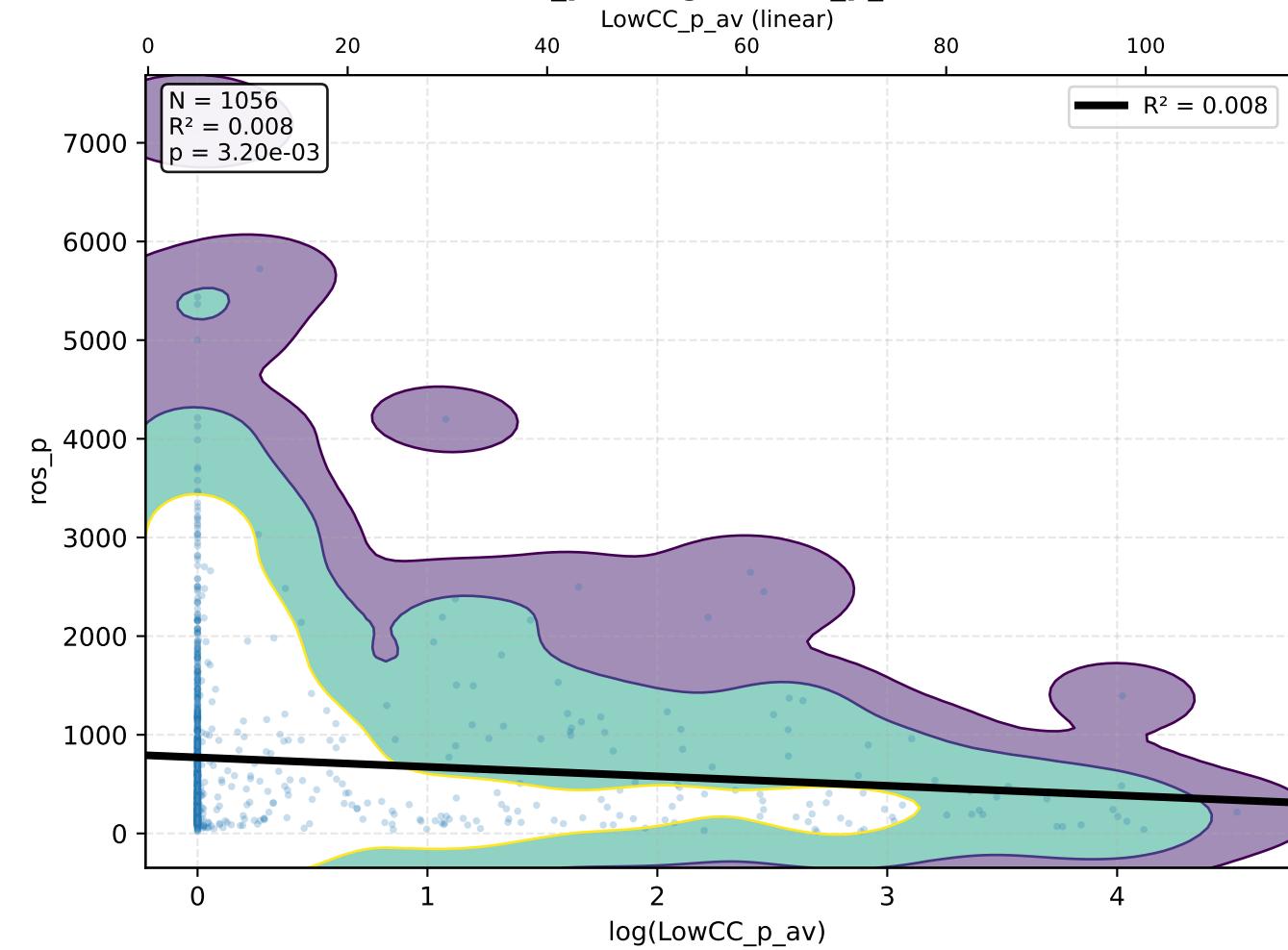


# LowCC\_p\_av – KDE Density + Regressão

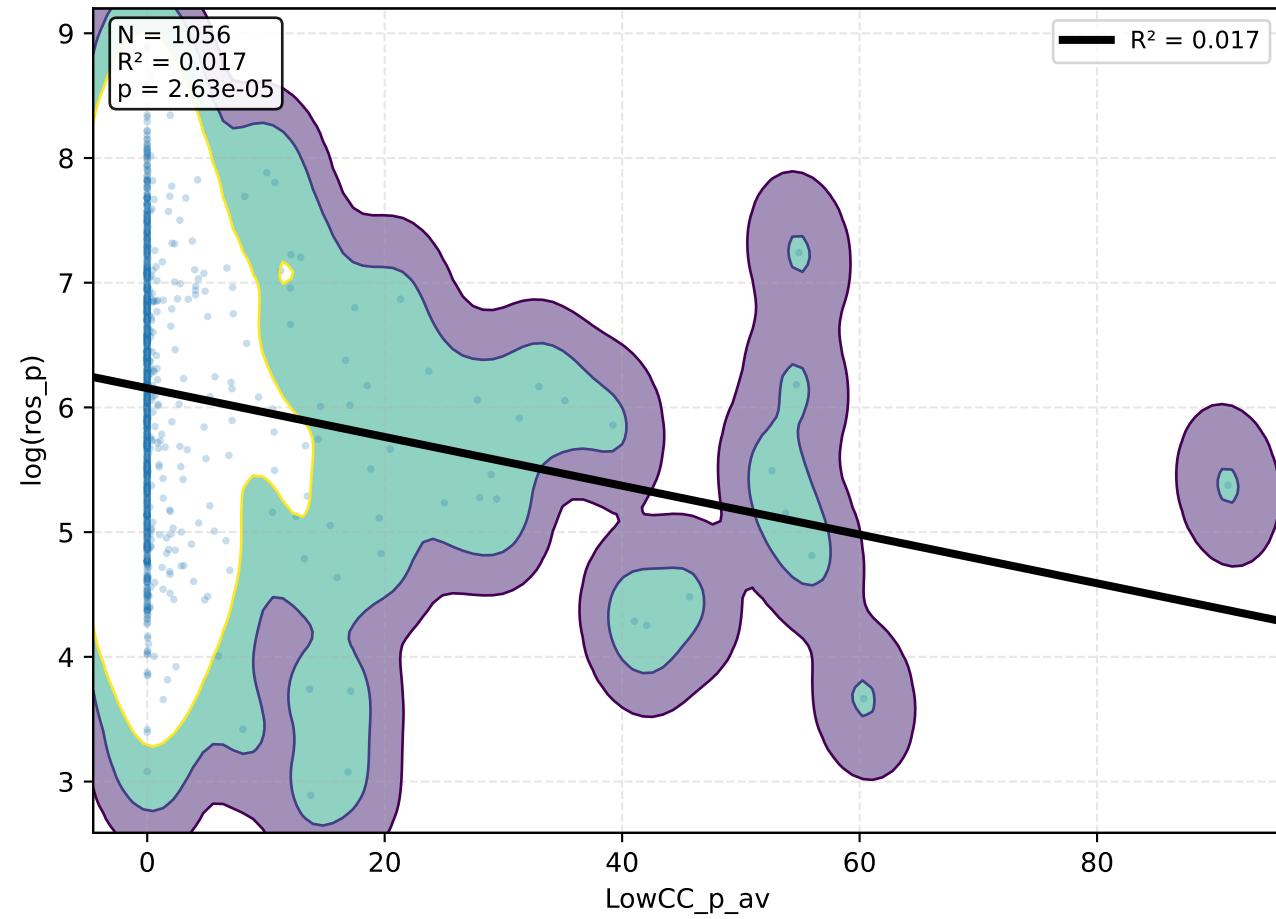
**ros\_p vs LowCC\_p\_av**



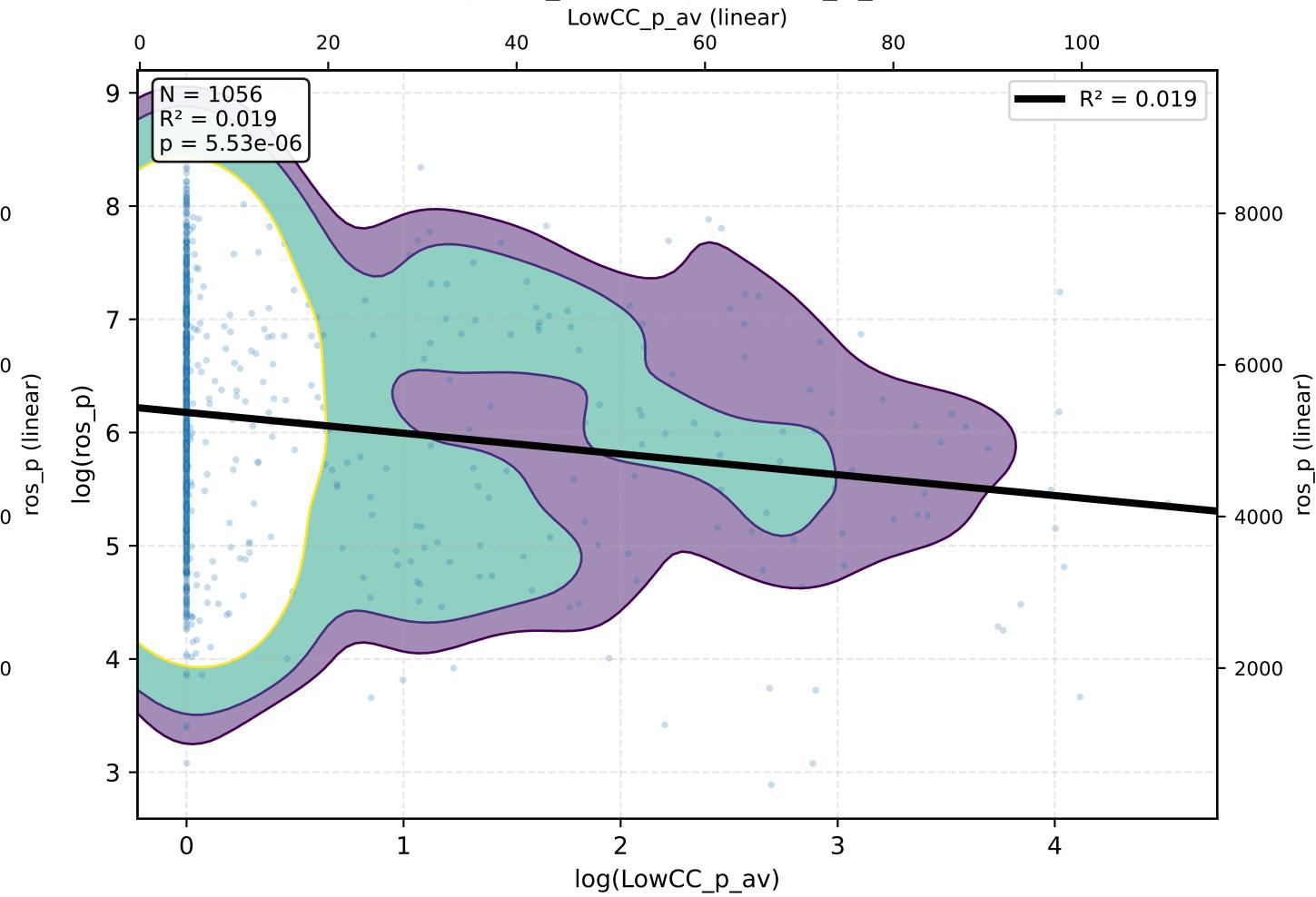
**ros\_p vs log(LowCC\_p\_av)**



**log(ros\_p) vs LowCC\_p\_av**

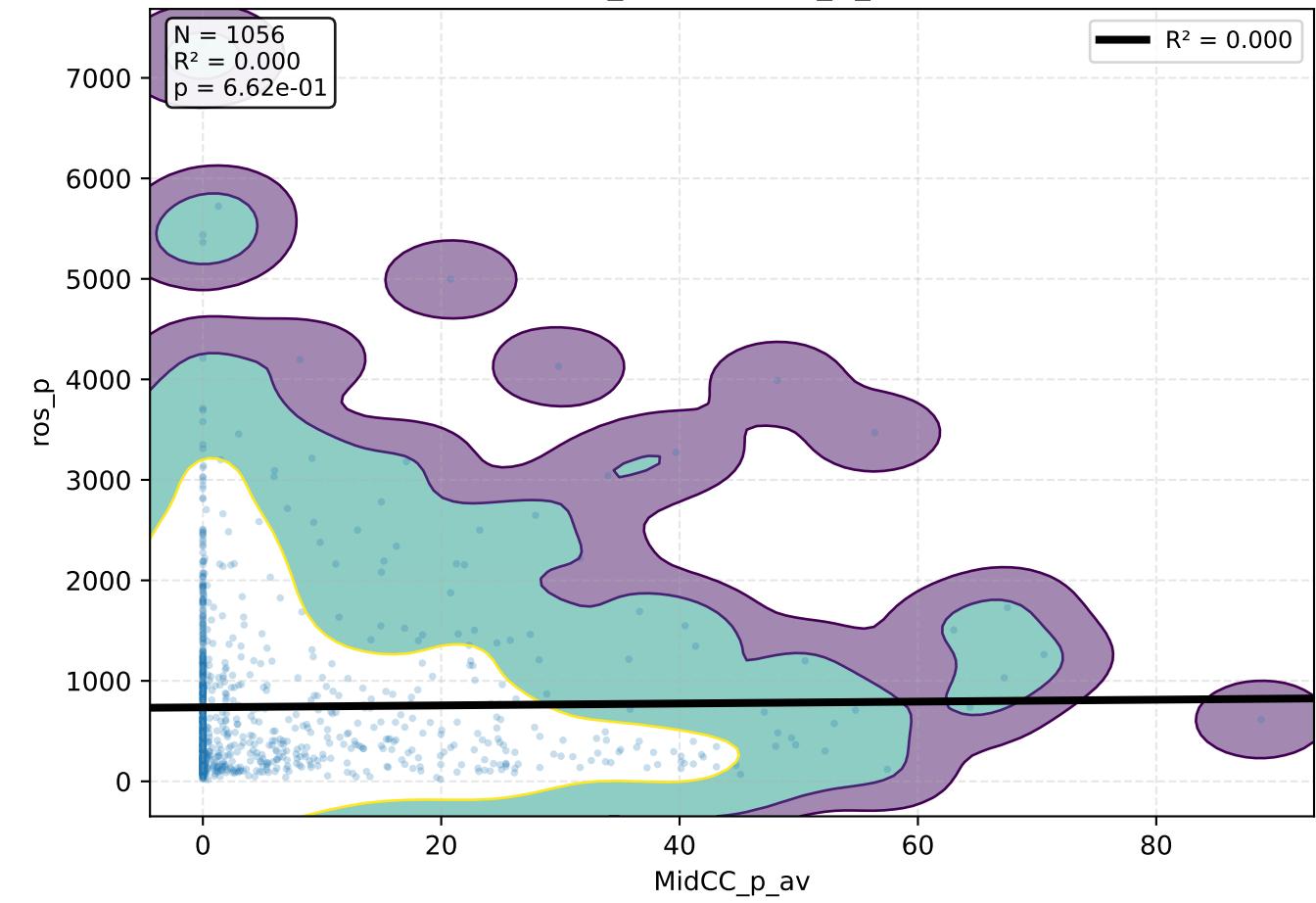


**log(ros\_p) vs log(LowCC\_p\_av)**

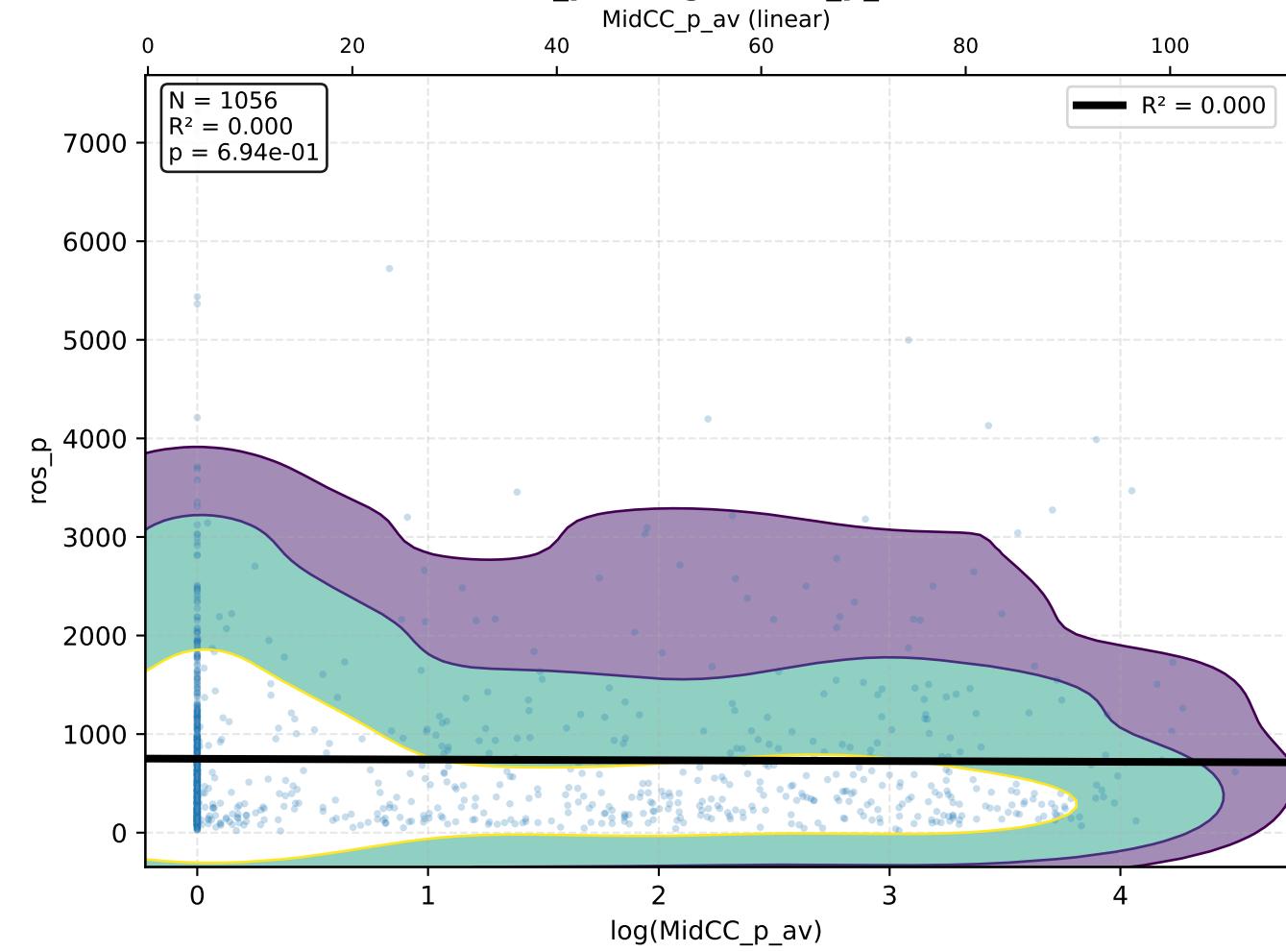


# MidCC\_p\_av – KDE Density + Regressão

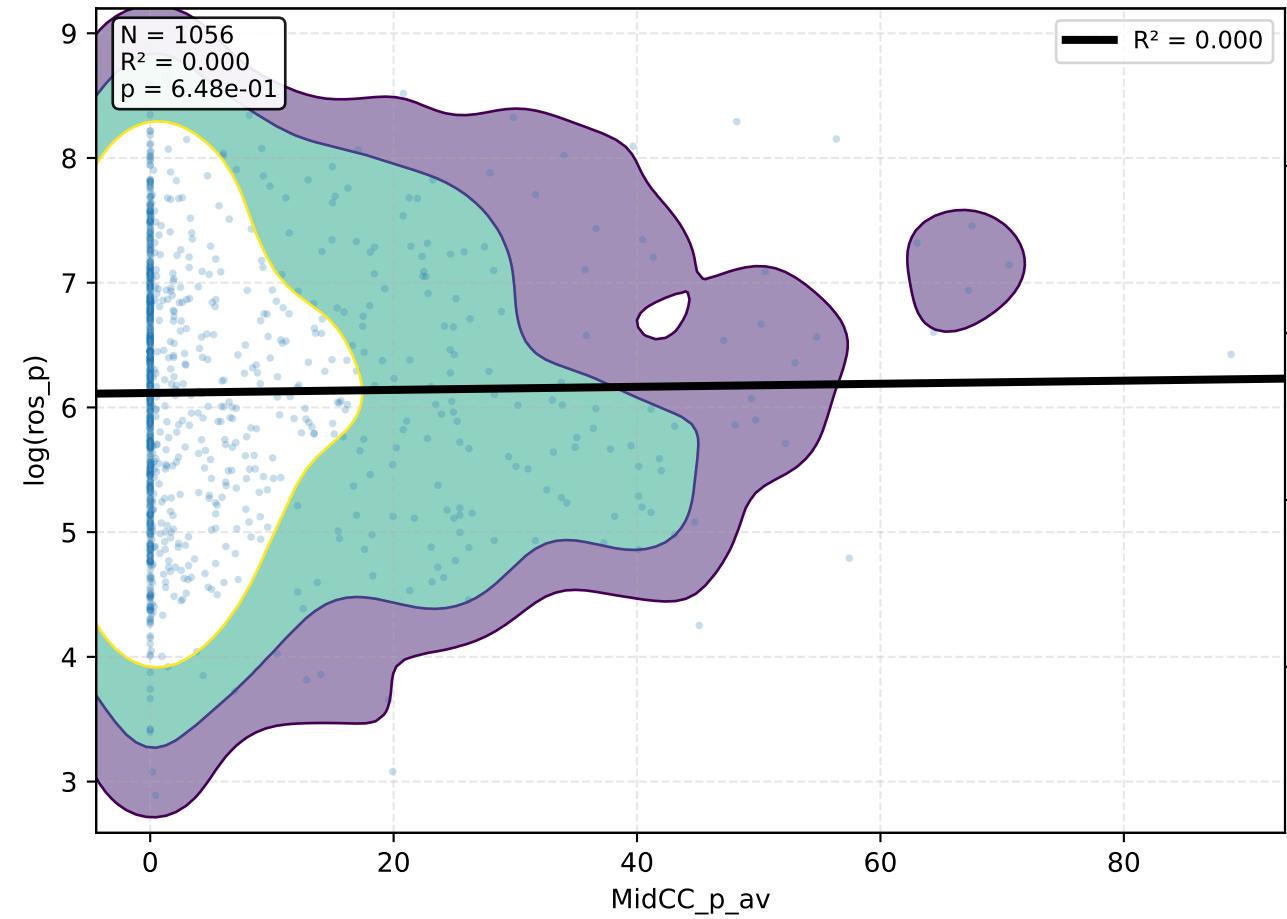
**ros\_p vs MidCC\_p\_av**



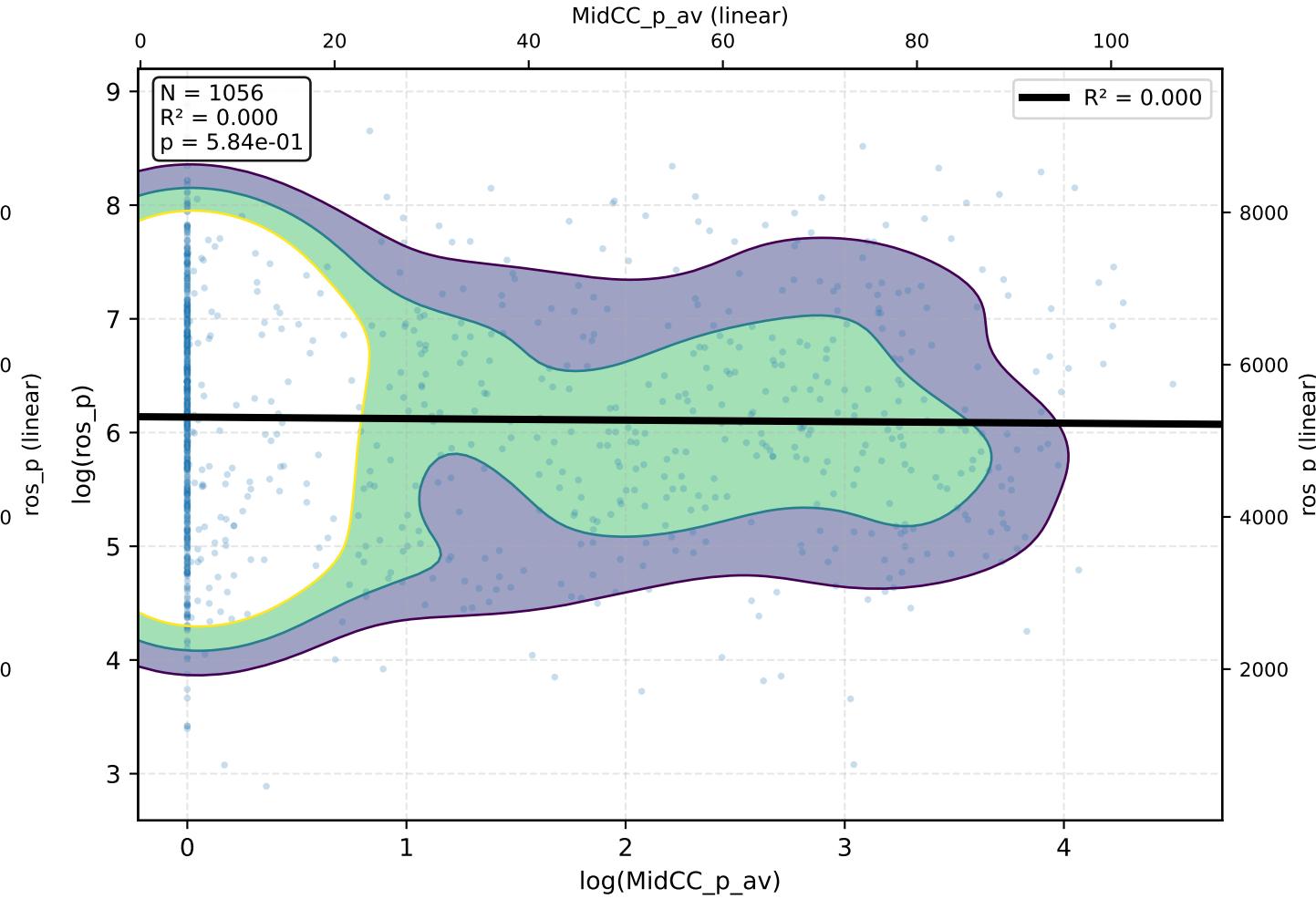
**ros\_p vs log(MidCC\_p\_av)**



**log(ros\_p) vs MidCC\_p\_av**

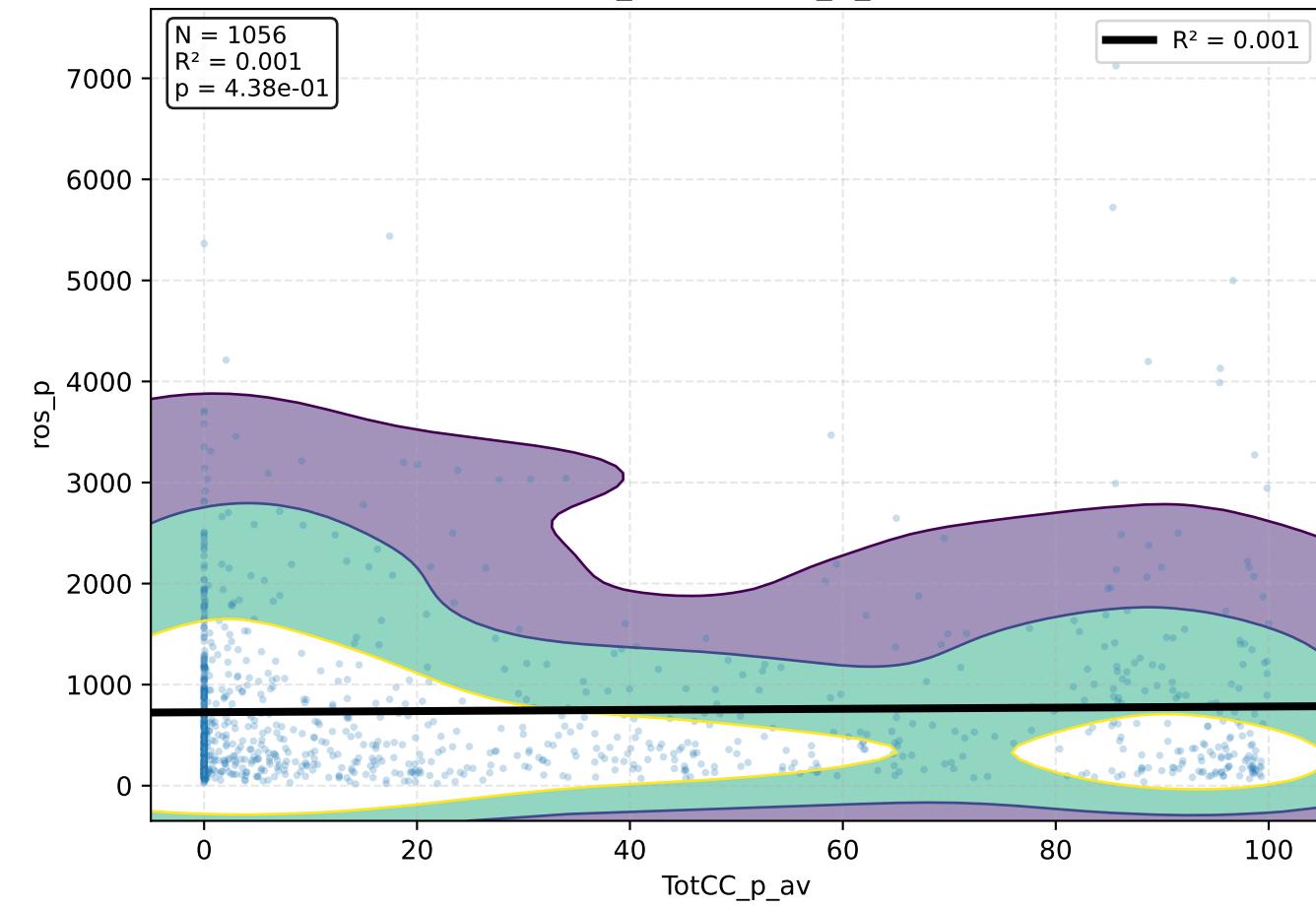


**log(ros\_p) vs log(MidCC\_p\_av)**

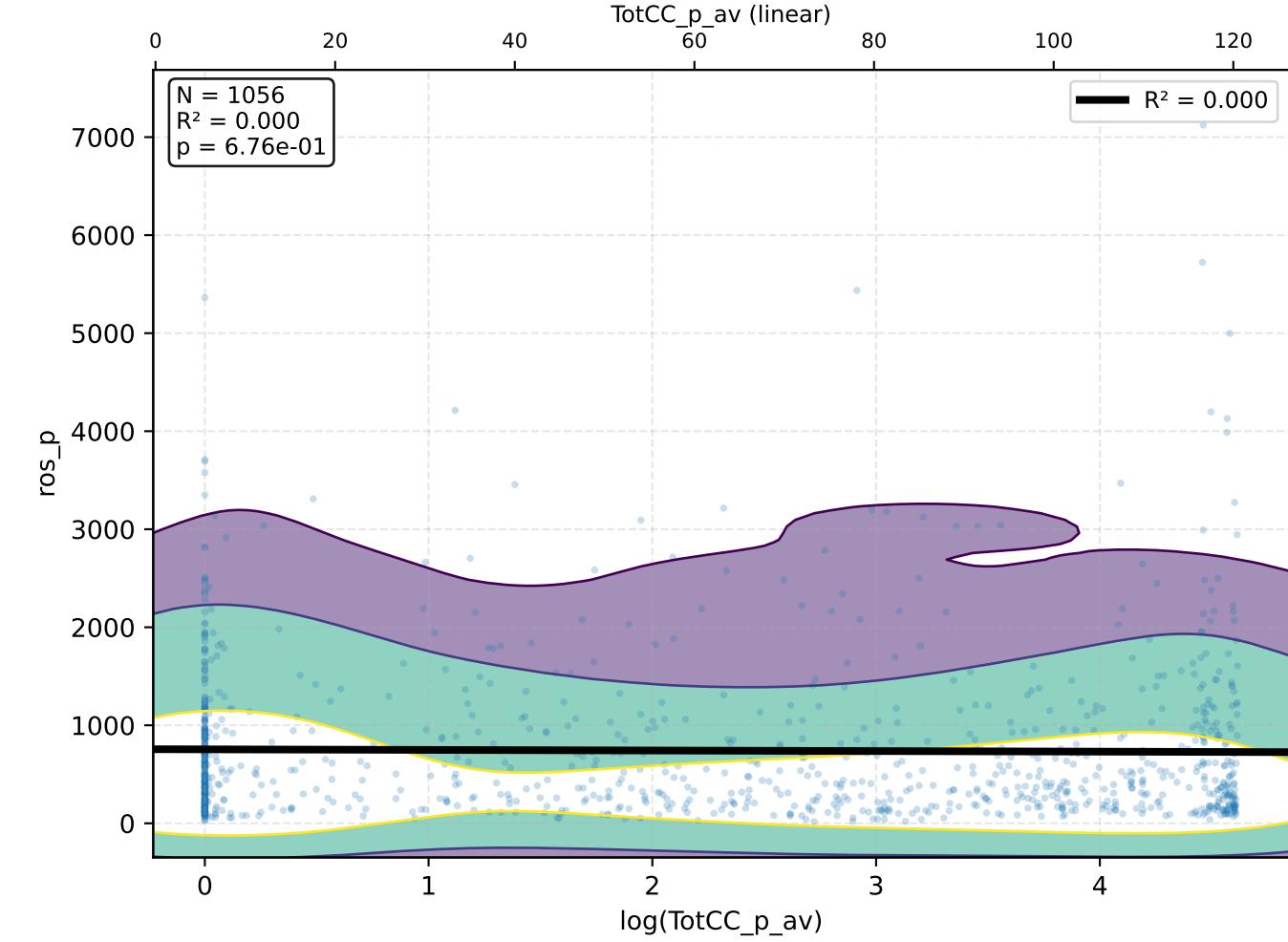


# TotCC\_p\_av – KDE Density + Regressão

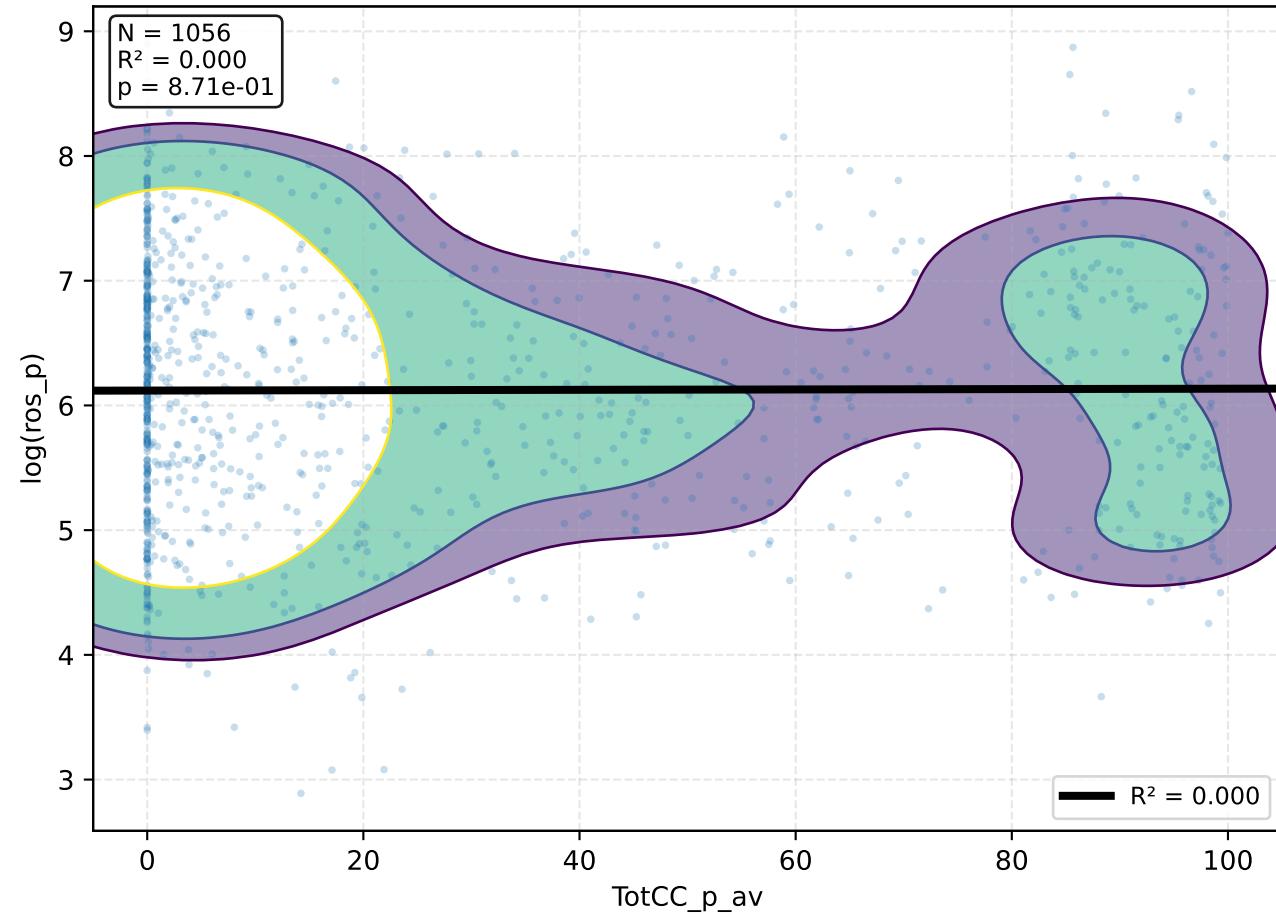
**ros\_p vs TotCC\_p\_av**



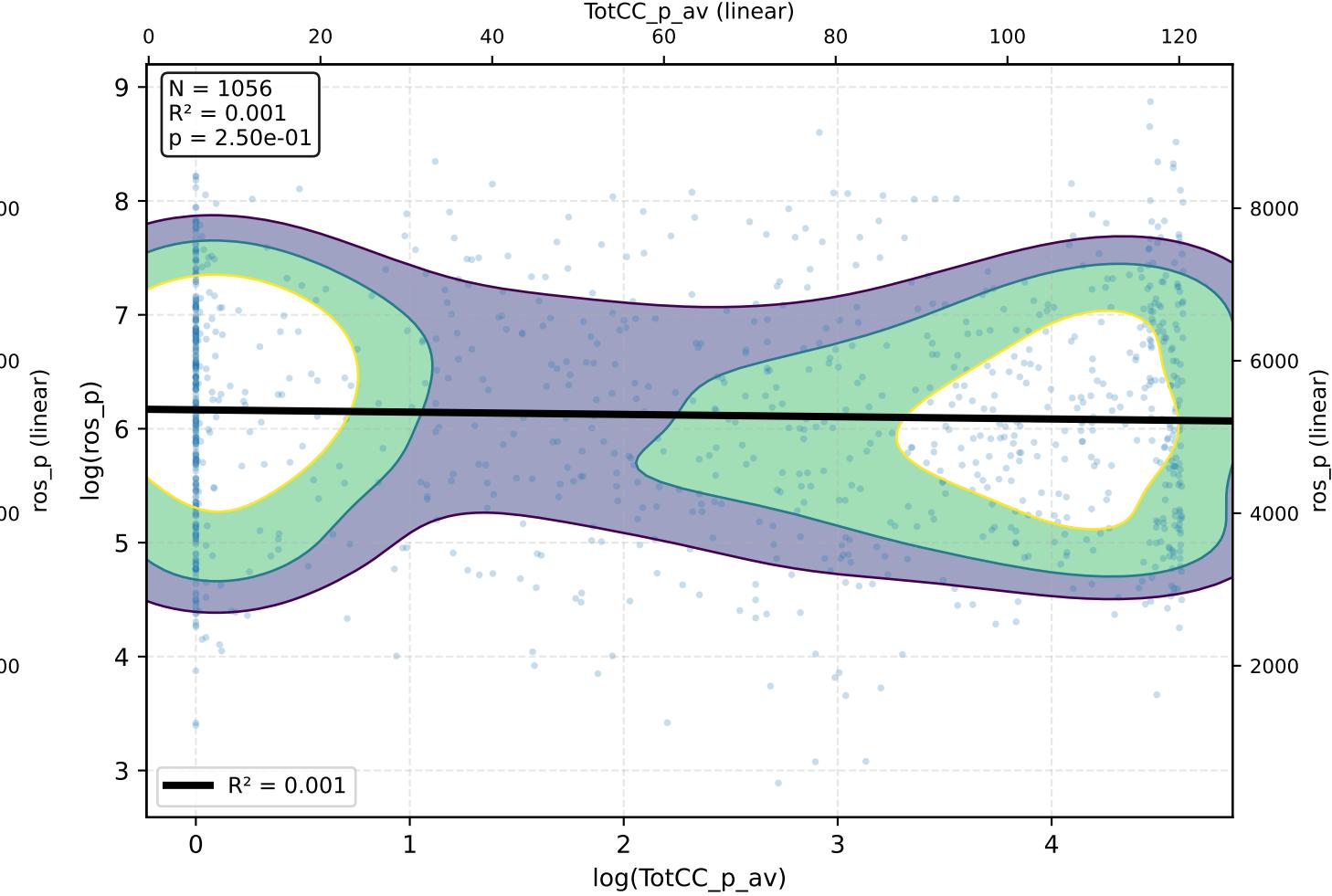
**ros\_p vs log(TotCC\_p\_av)**



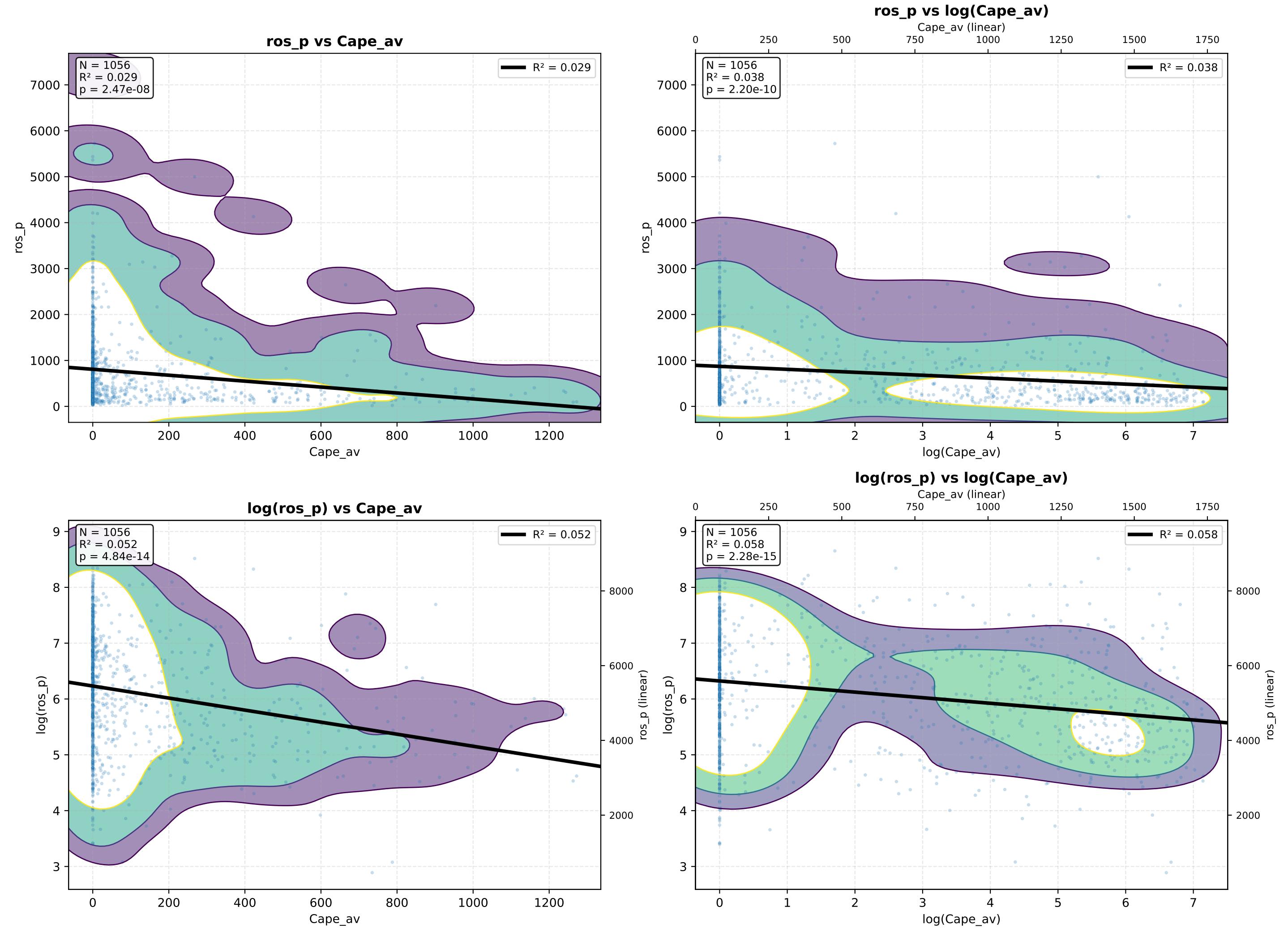
**log(ros\_p) vs TotCC\_p\_av**



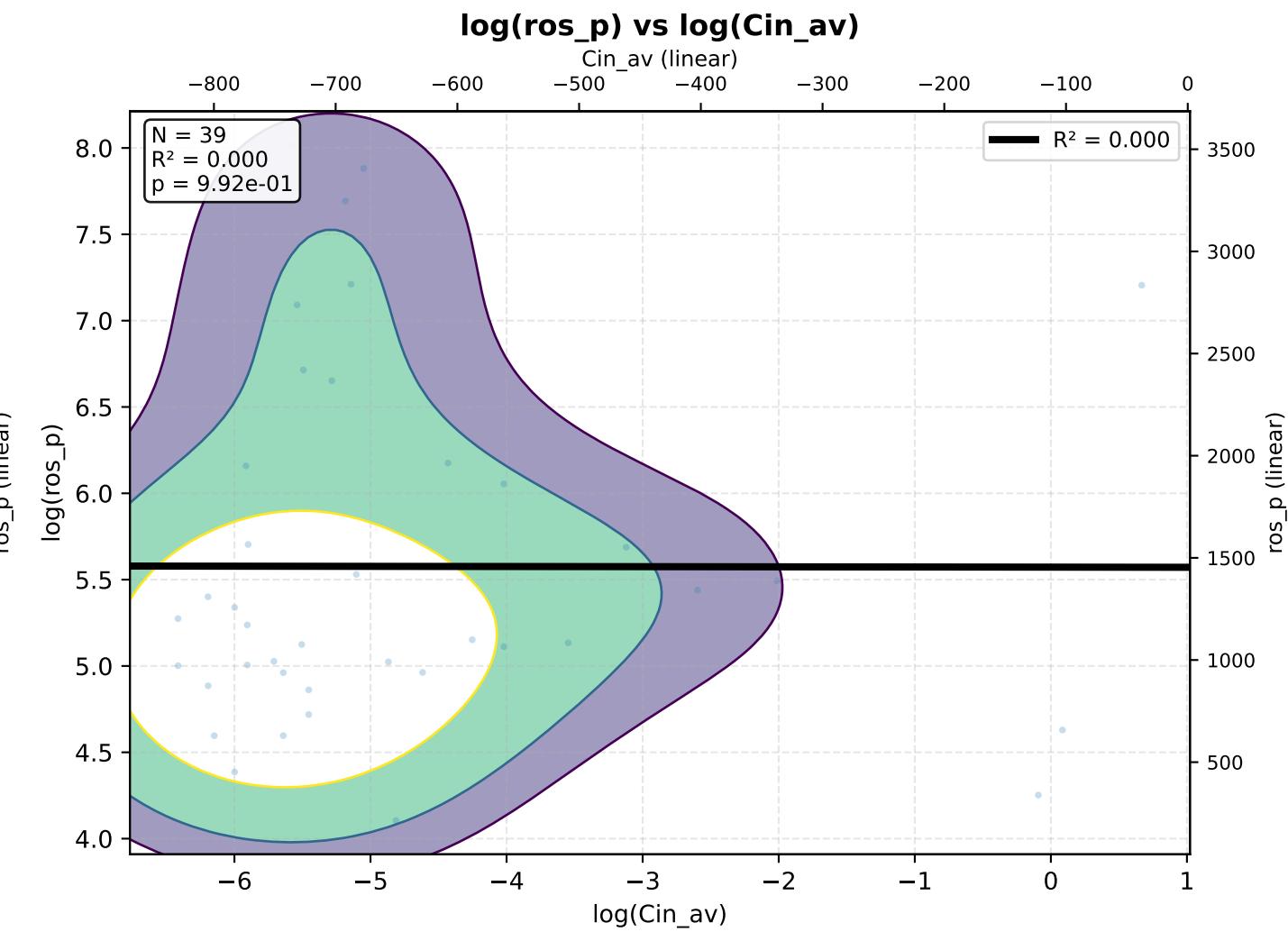
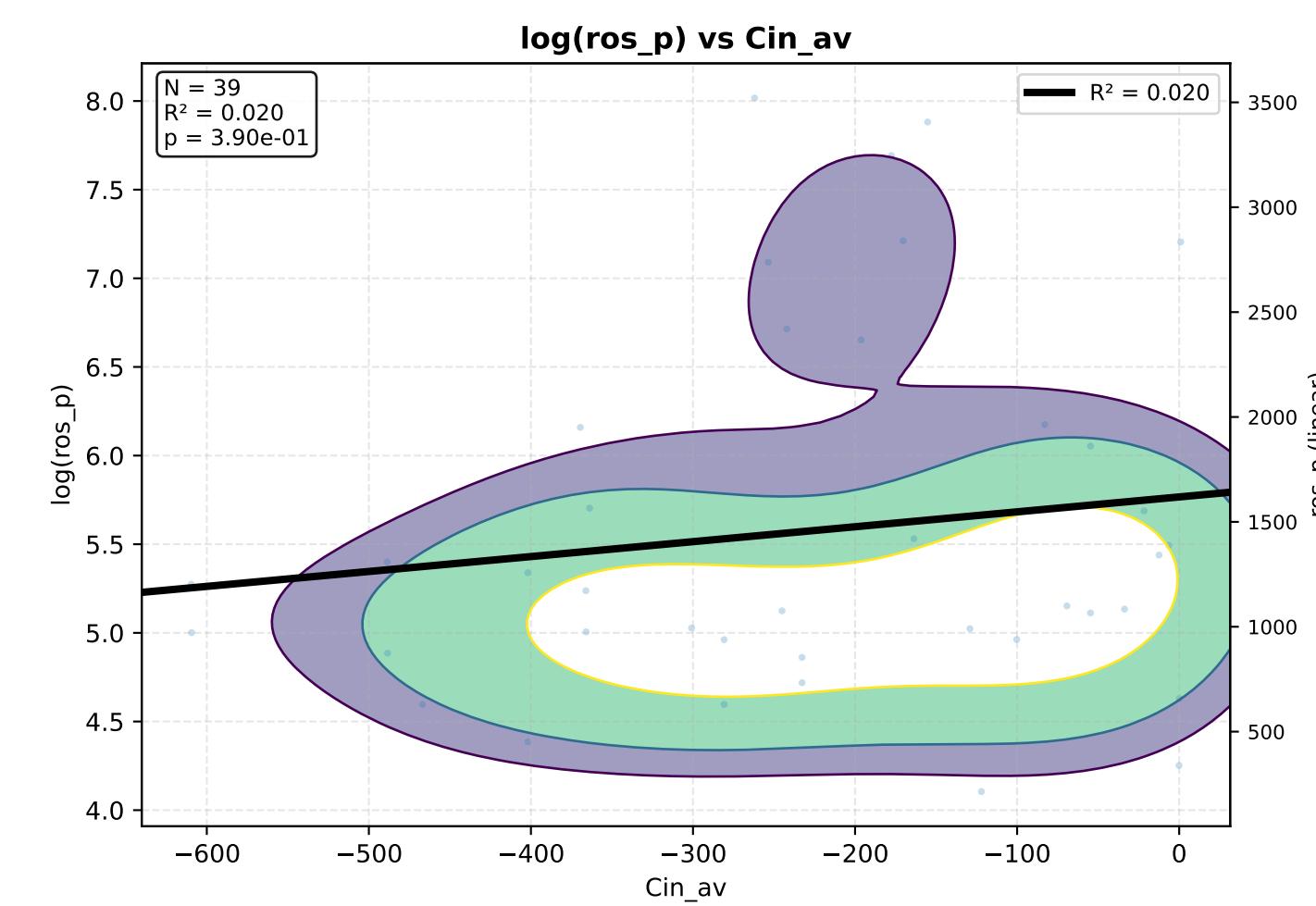
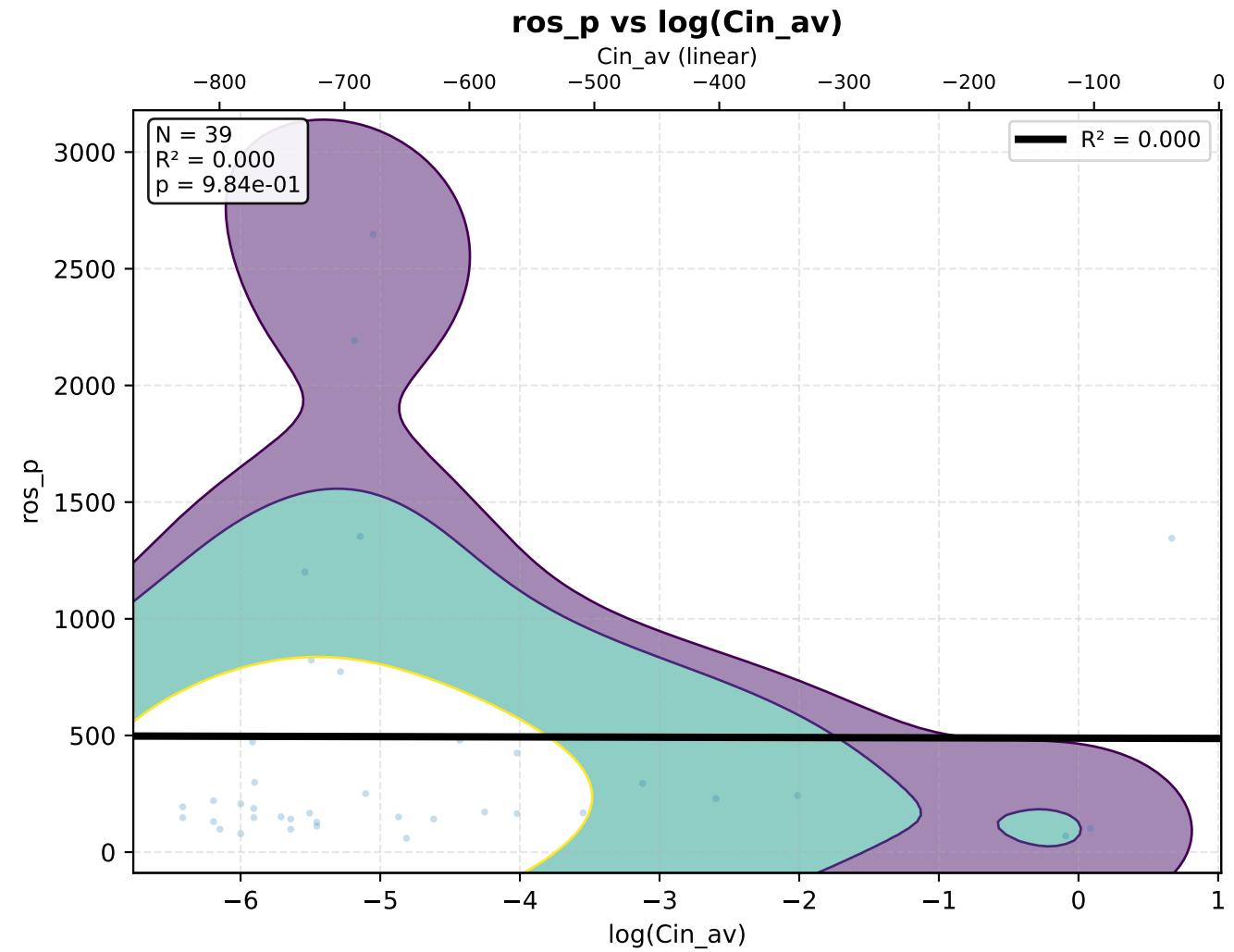
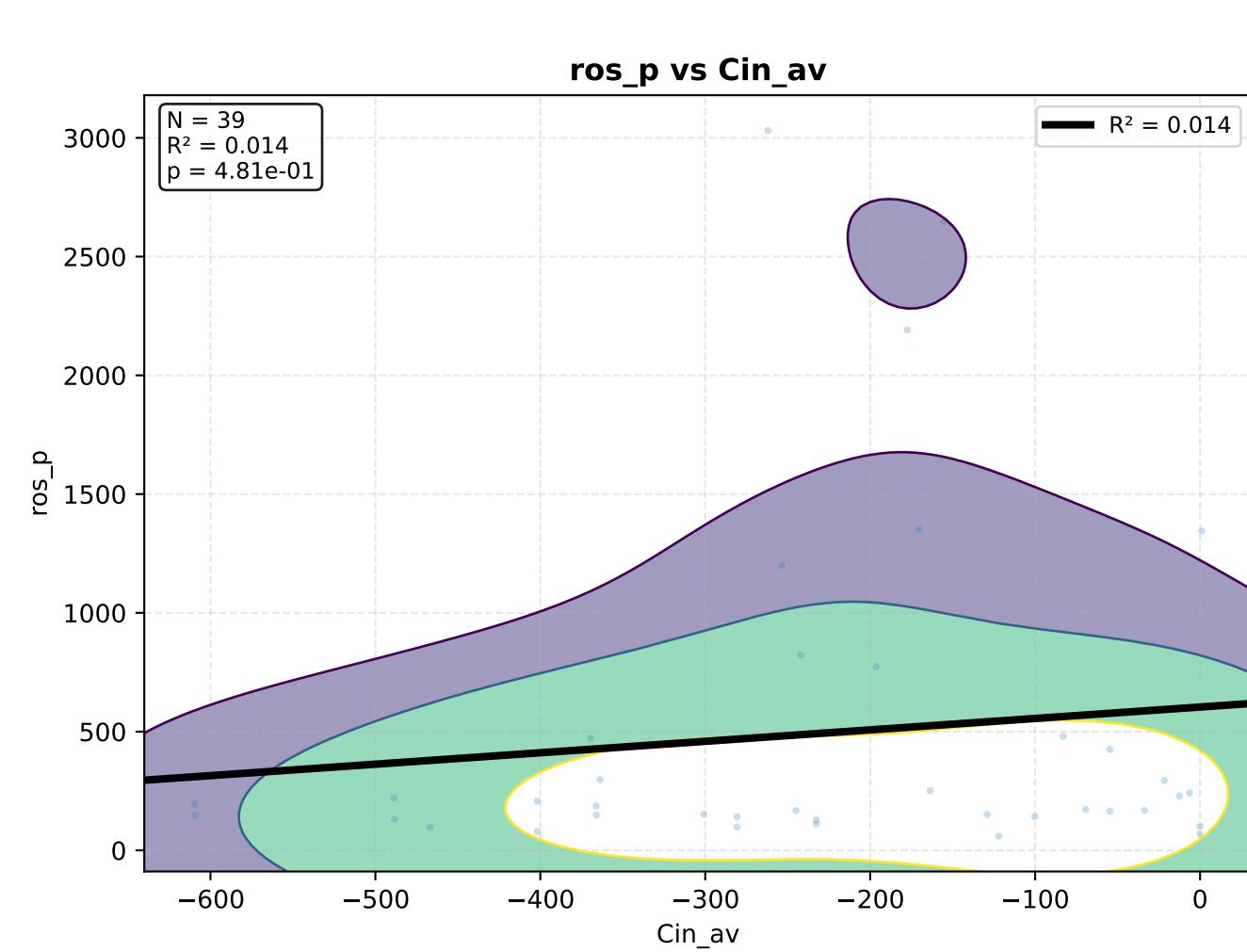
**log(ros\_p) vs log(TotCC\_p\_av)**



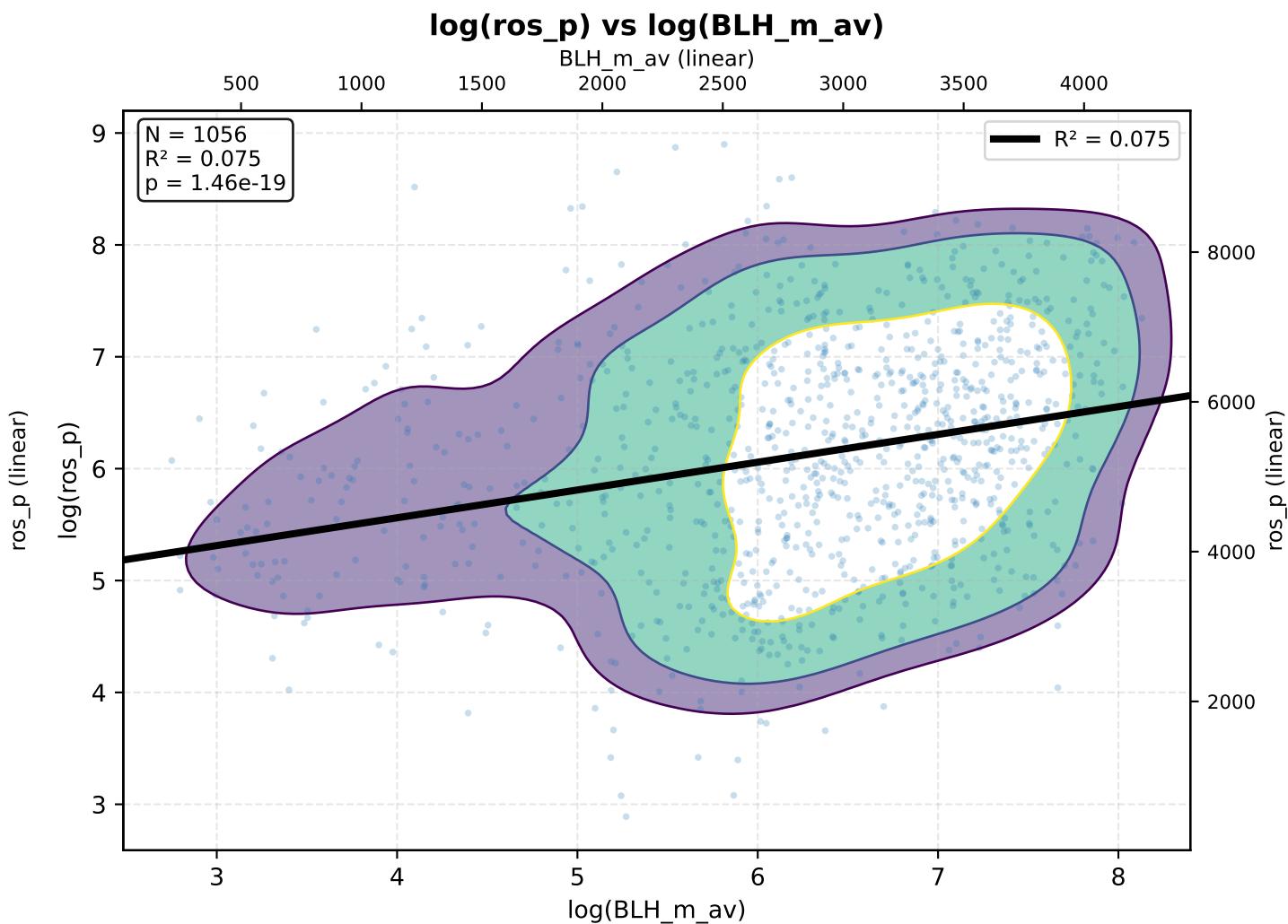
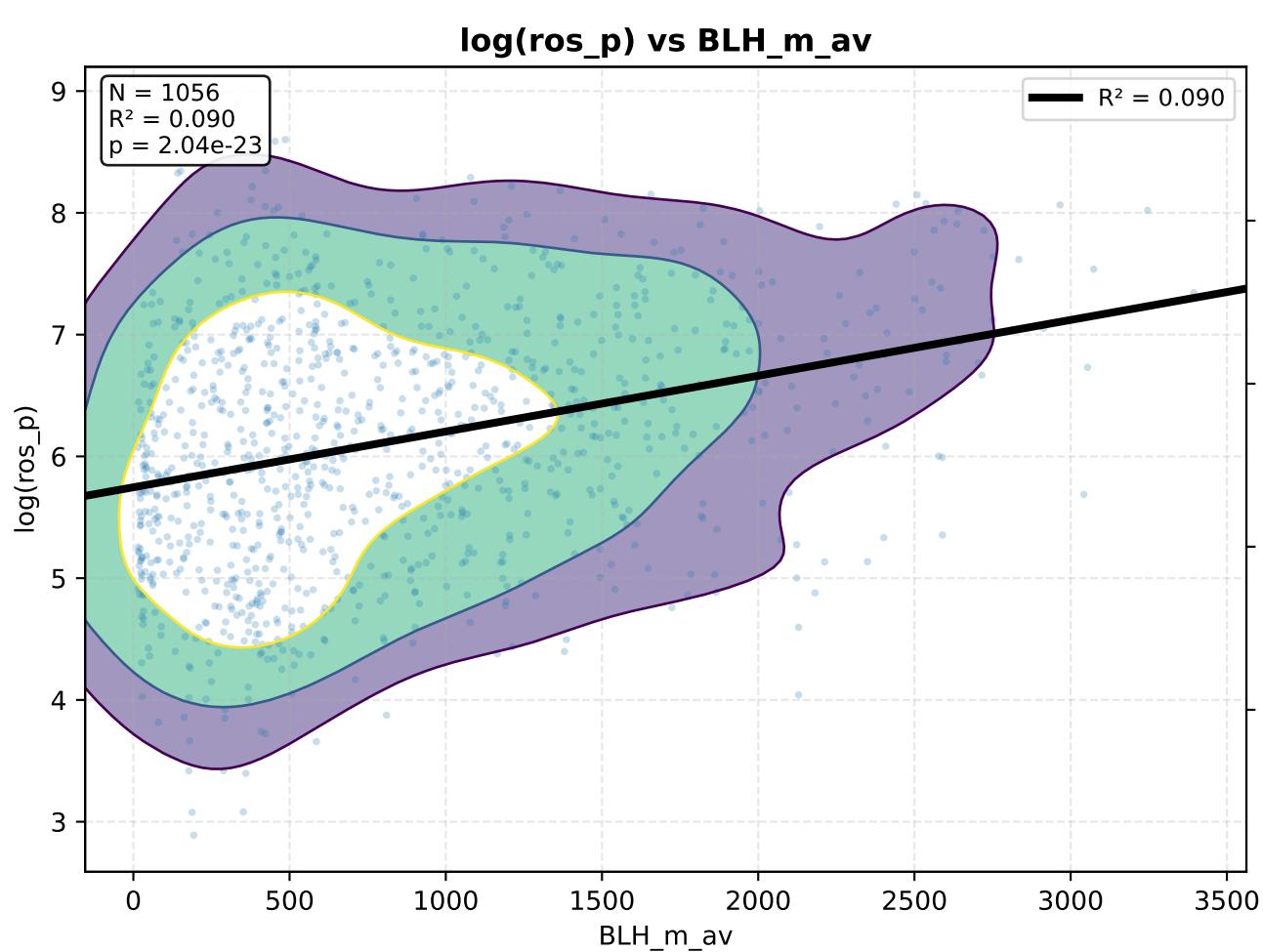
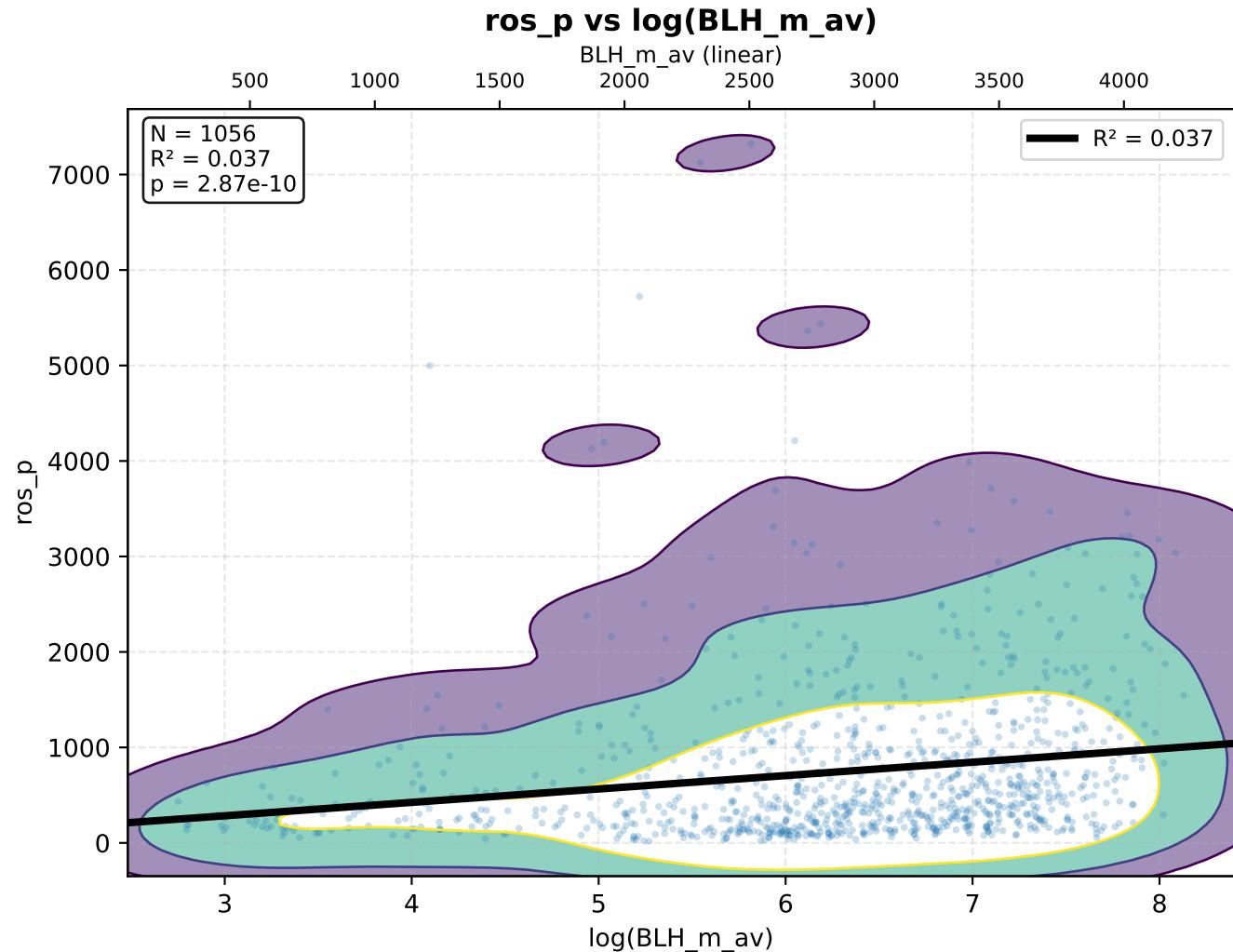
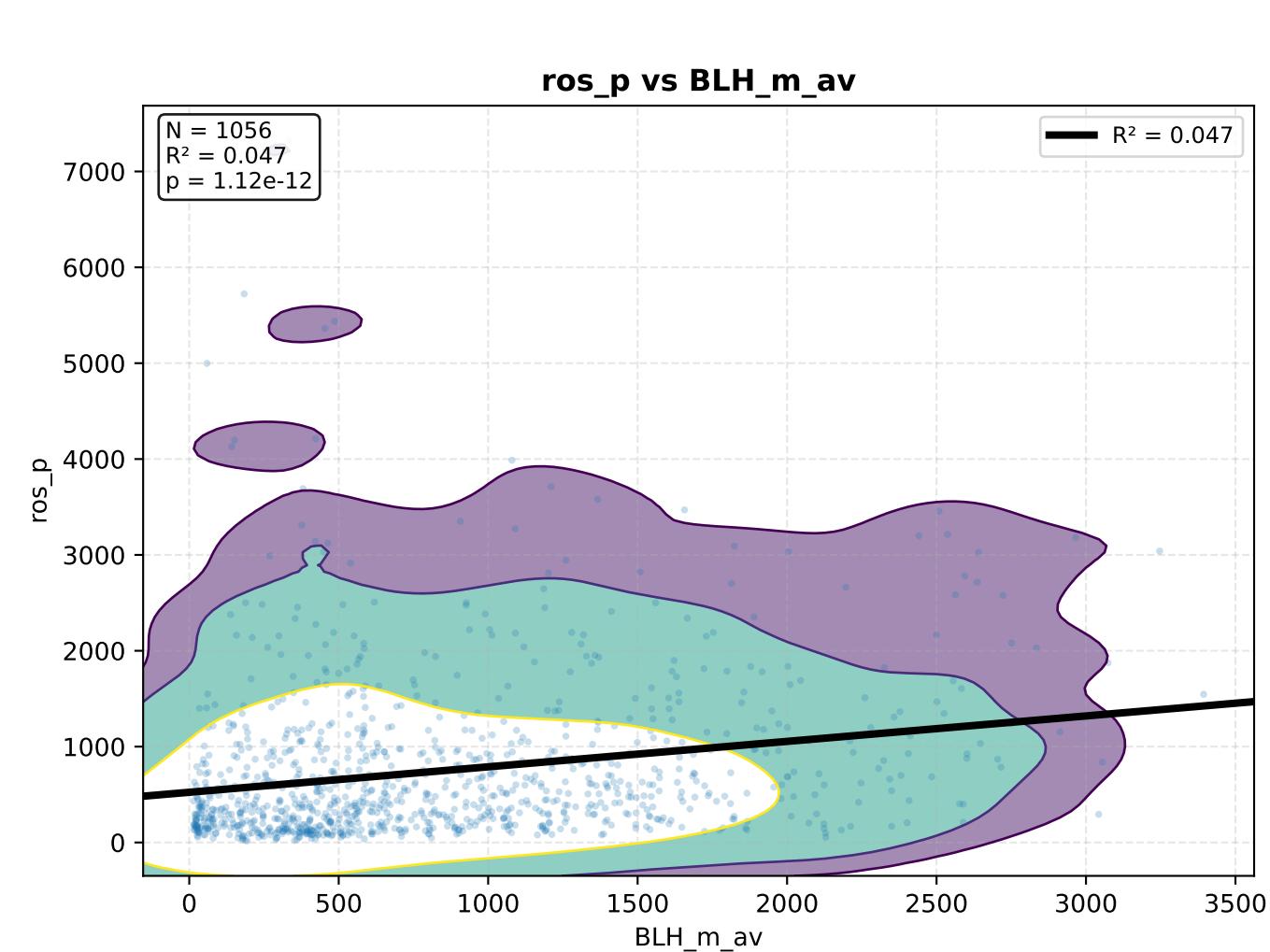
# Cape\_av - KDE Density + Regressão



# Cin\_av - KDE Density + Regressão

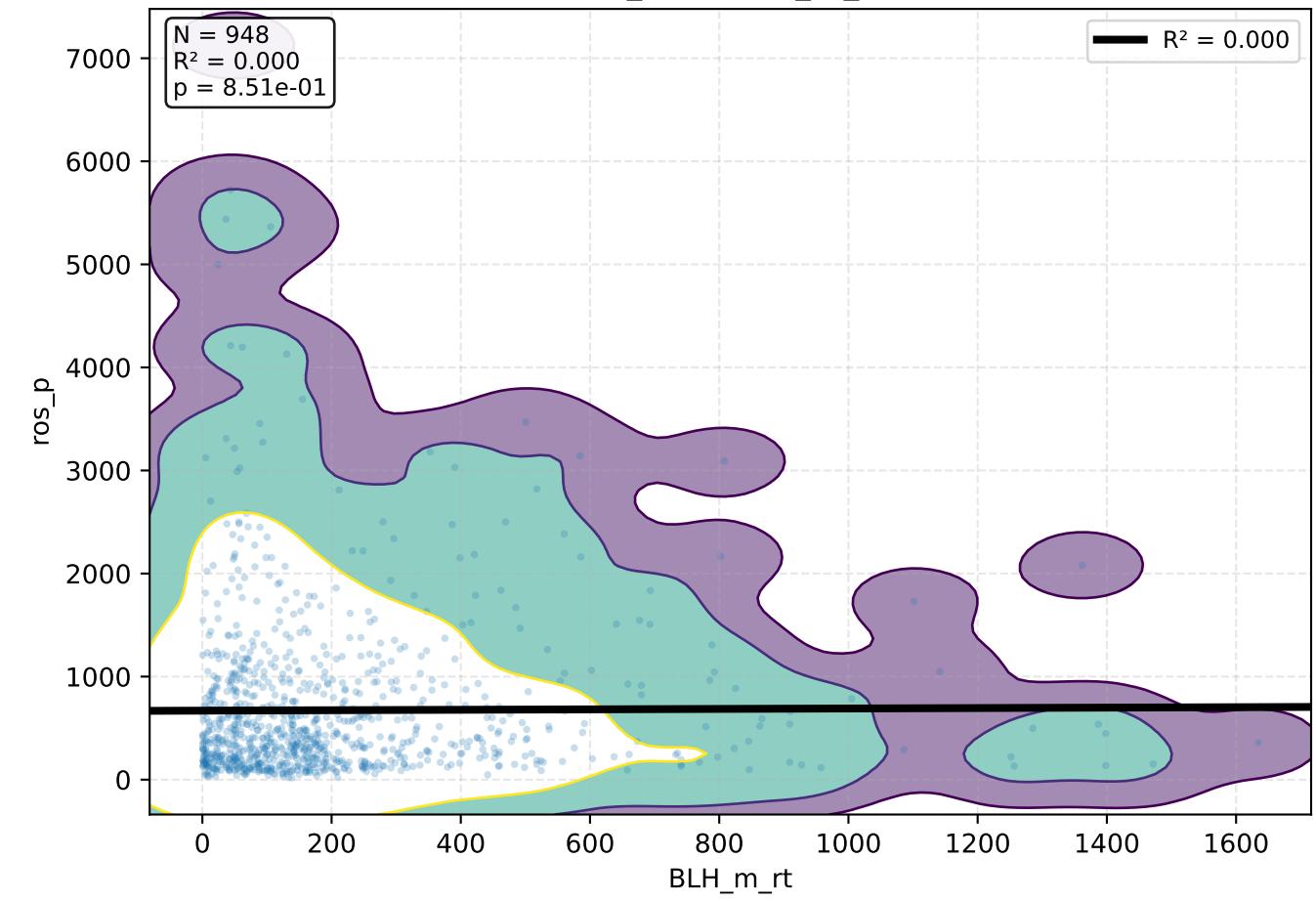


# BLH\_m\_av - KDE Density + Regressão

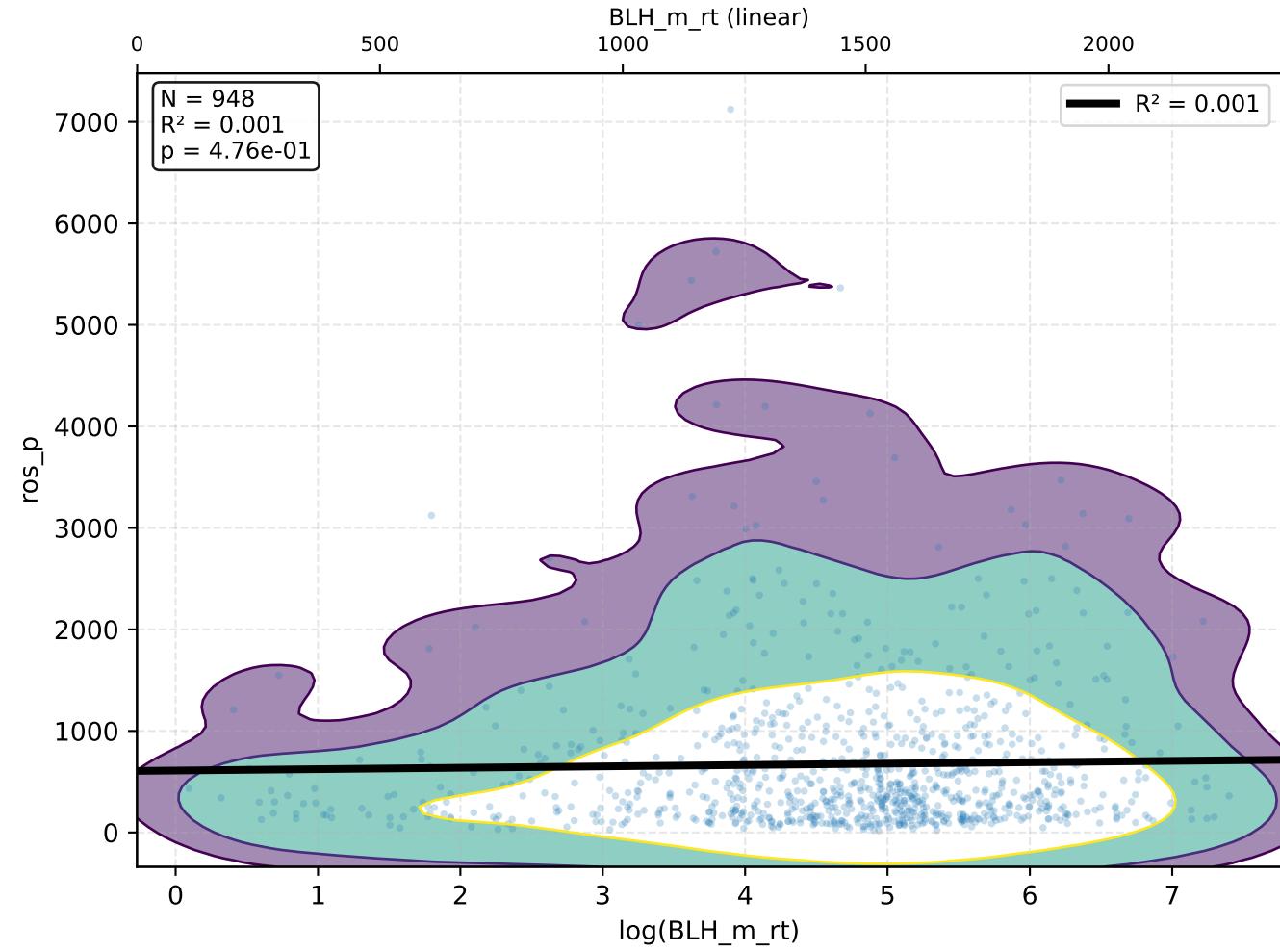


# BLH\_m\_rt - KDE Density + Regressão

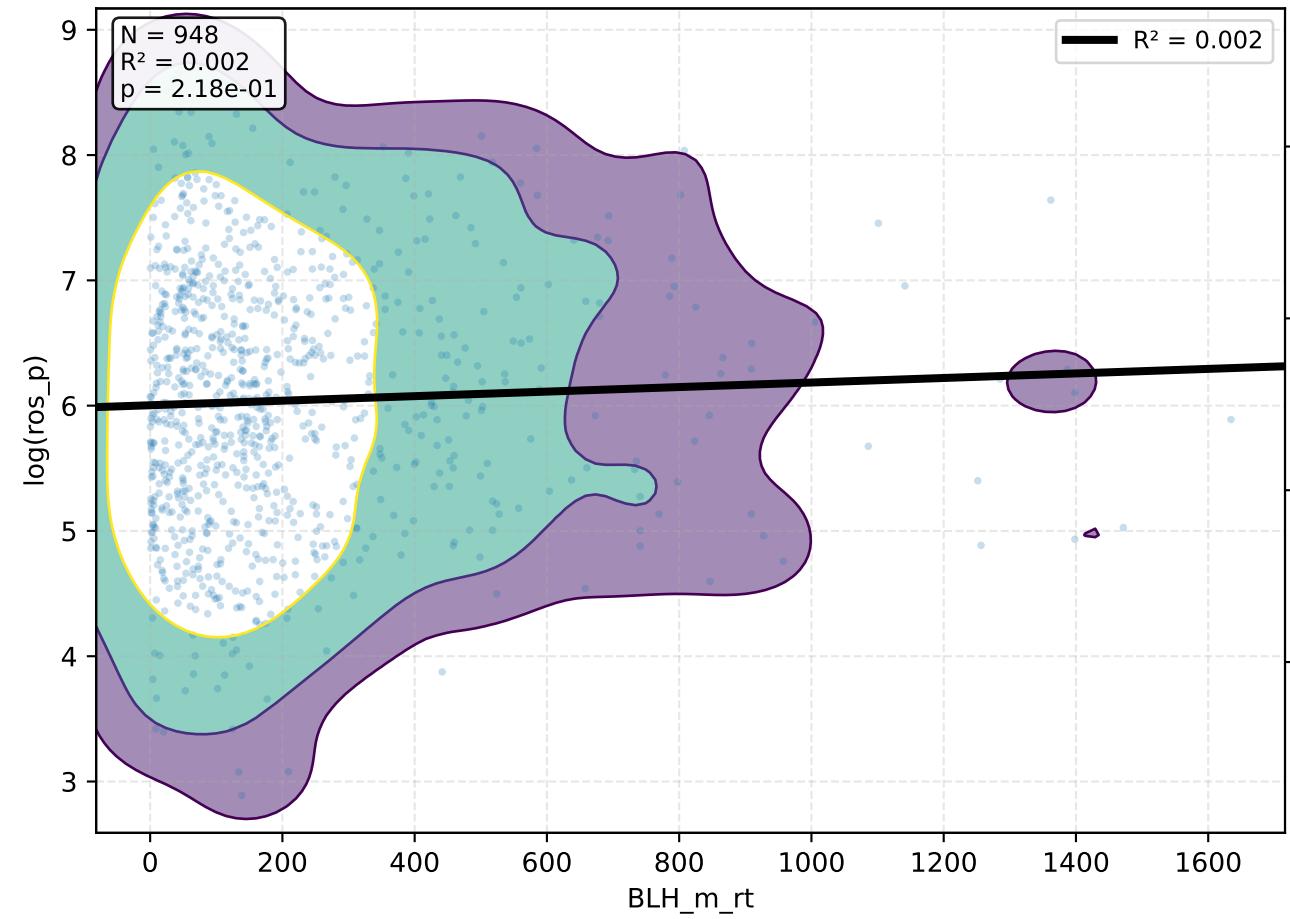
**ros\_p vs BLH\_m\_rt**



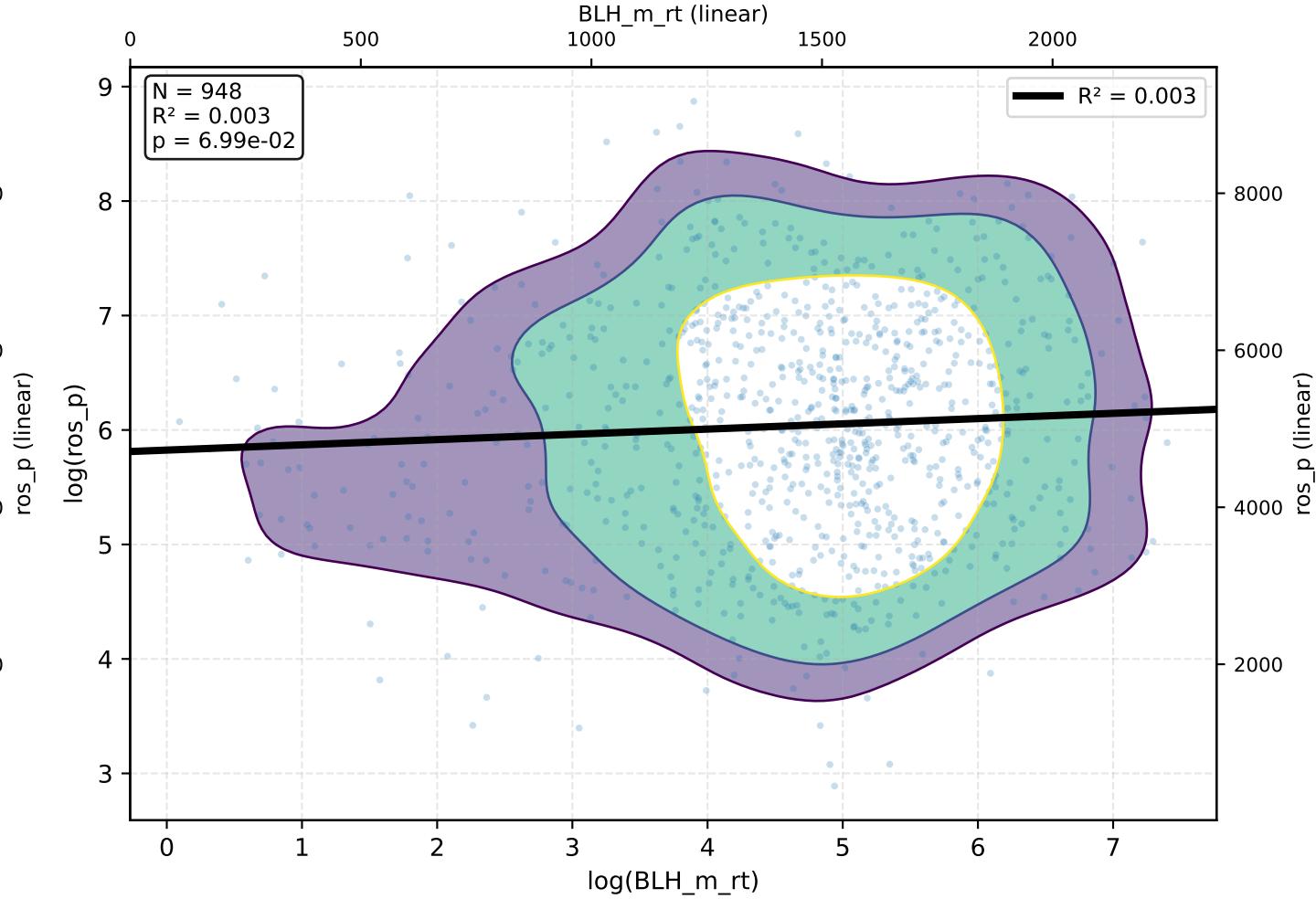
**ros\_p vs log(BLH\_m\_rt)**



**log(ros\_p) vs BLH\_m\_rt**

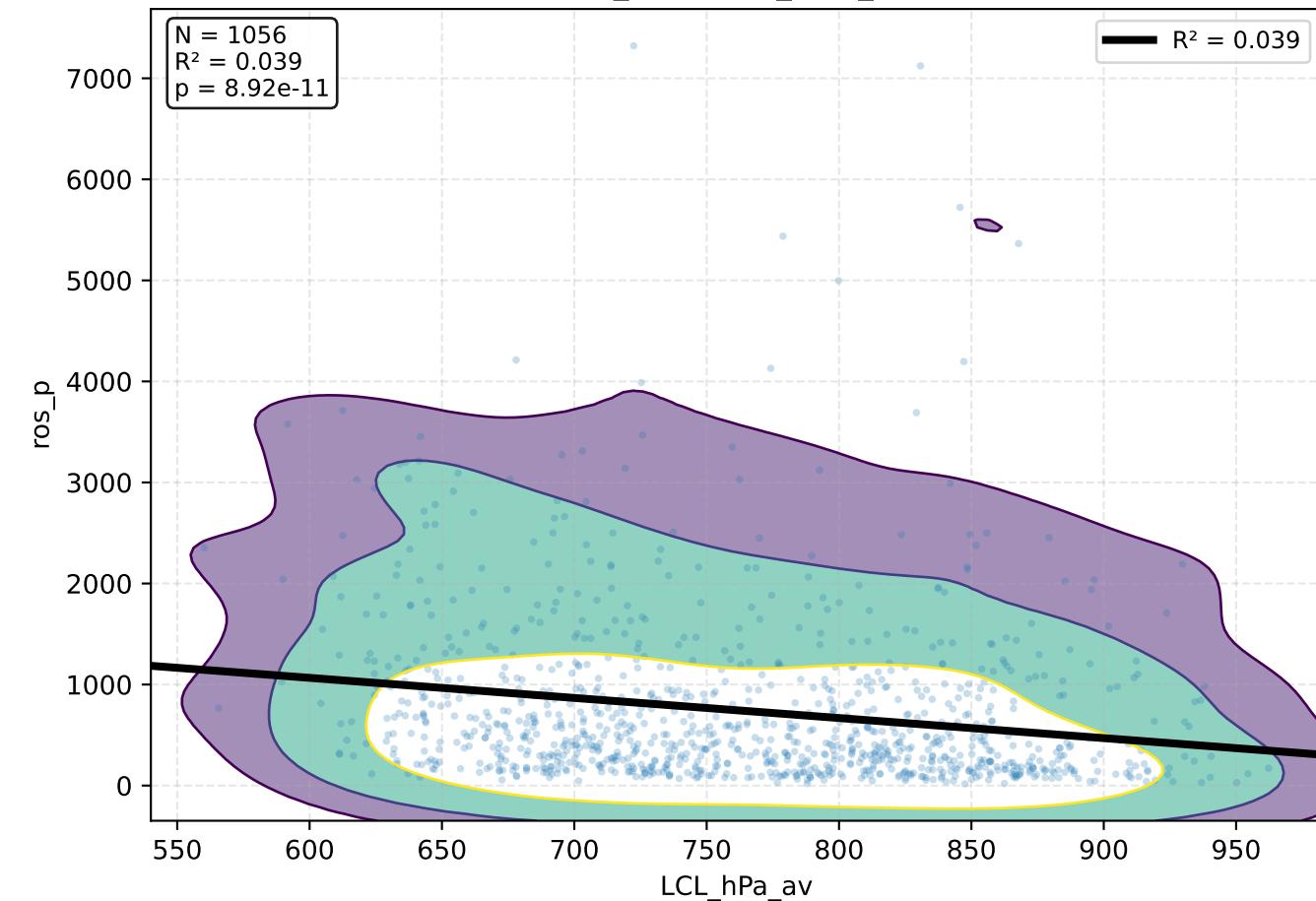


**log(ros\_p) vs log(BLH\_m\_rt)**

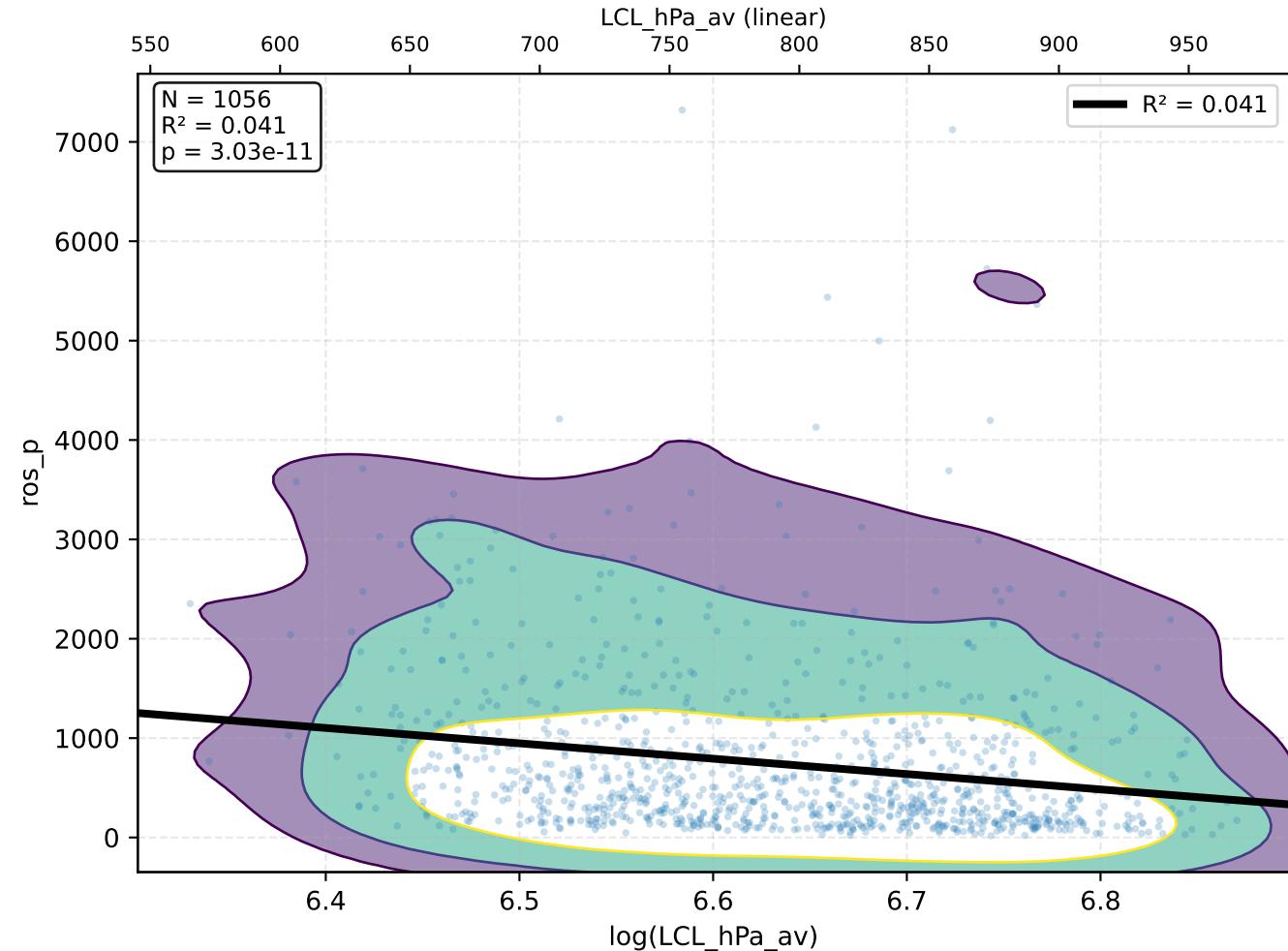


# LCL\_hPa\_av - KDE Density + Regressão

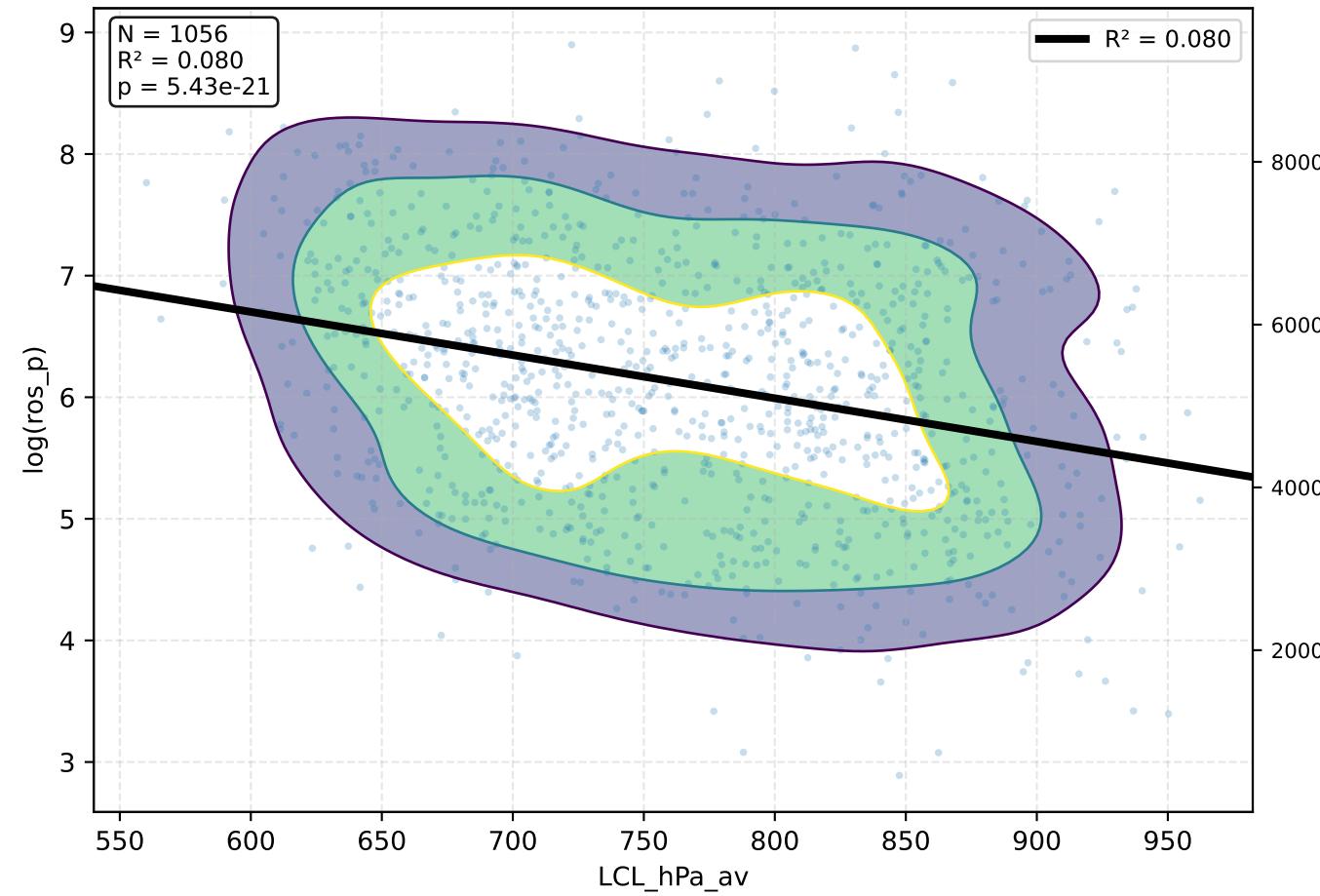
**ros\_p vs LCL\_hPa\_av**



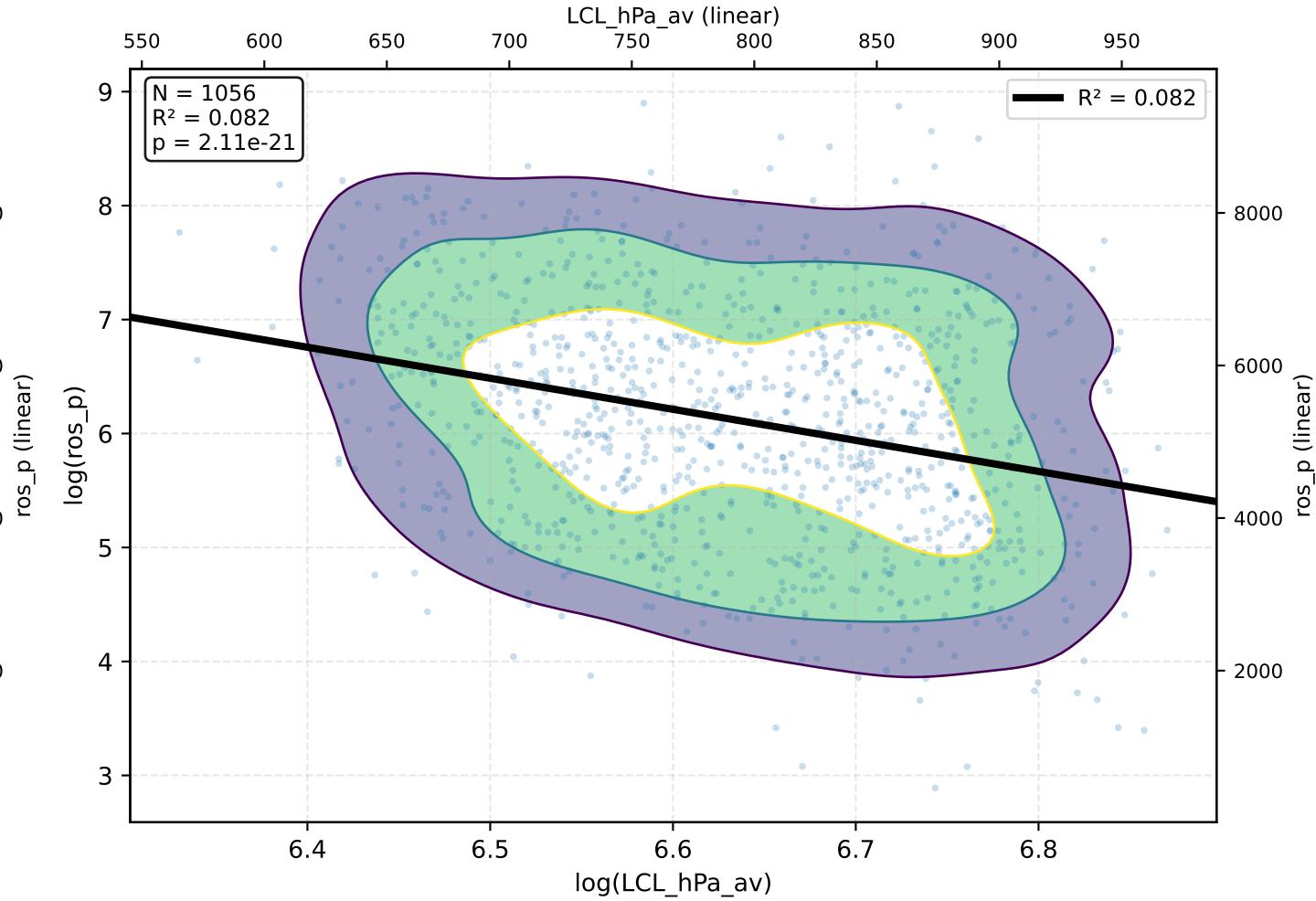
**ros\_p vs log(LCL\_hPa\_av)**



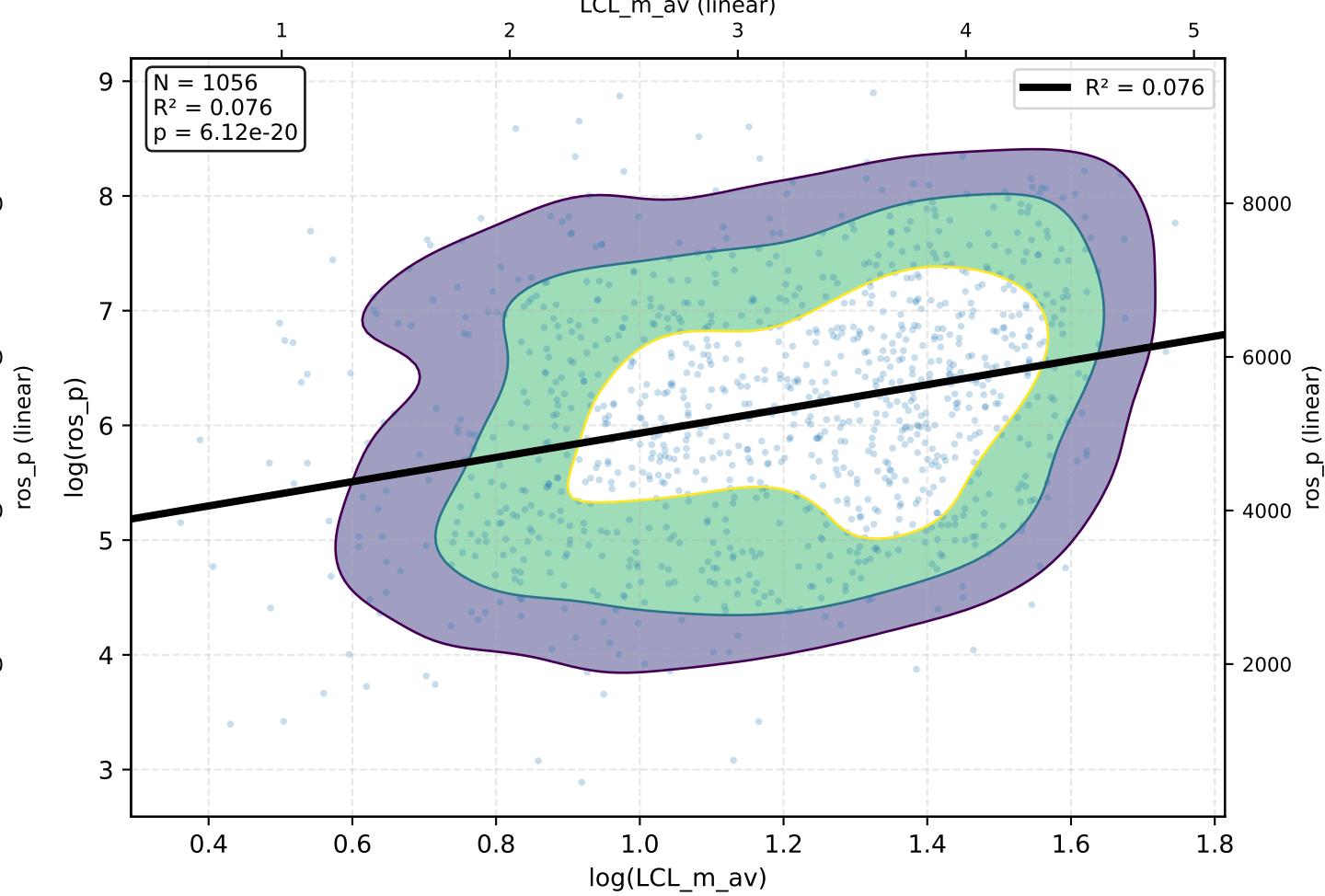
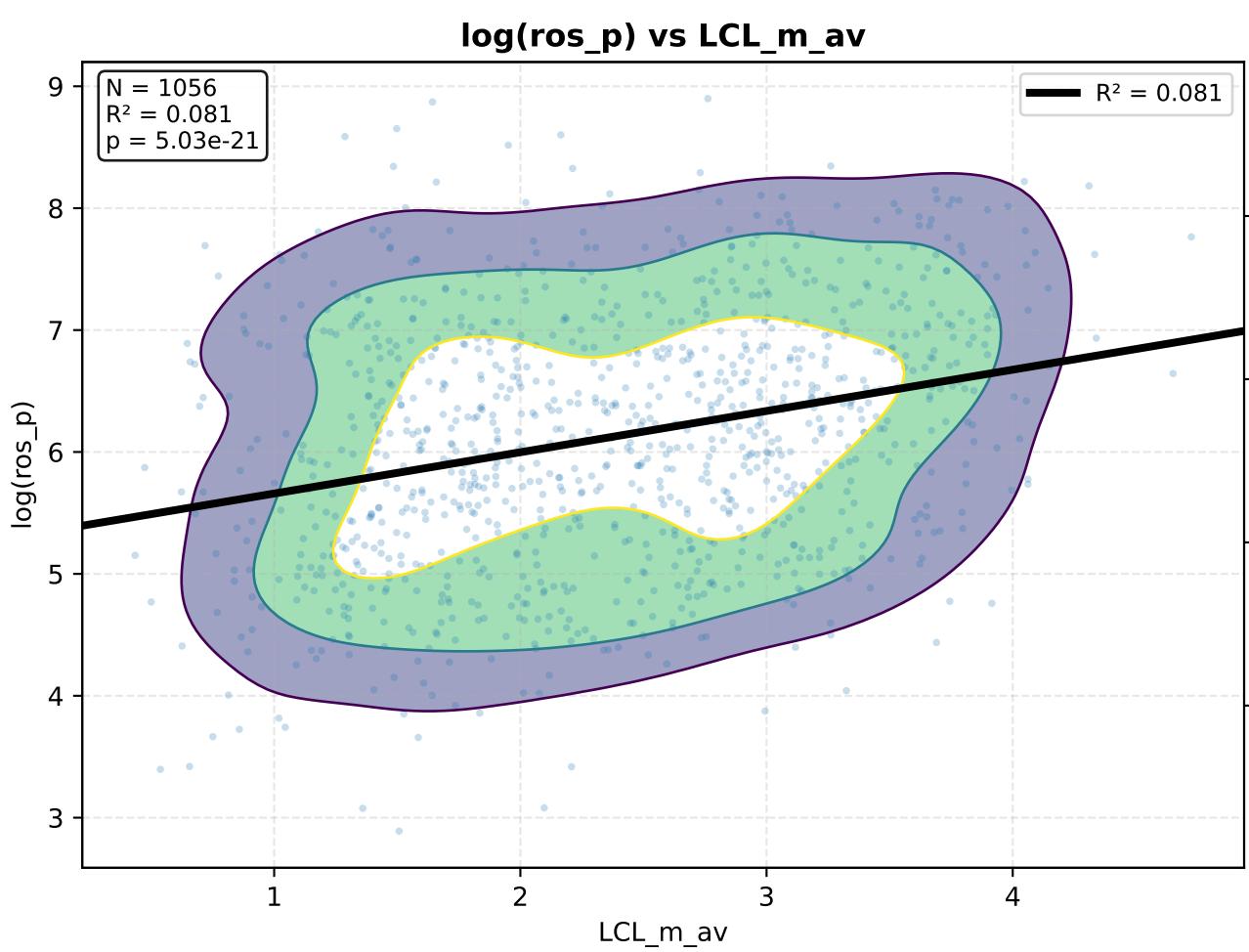
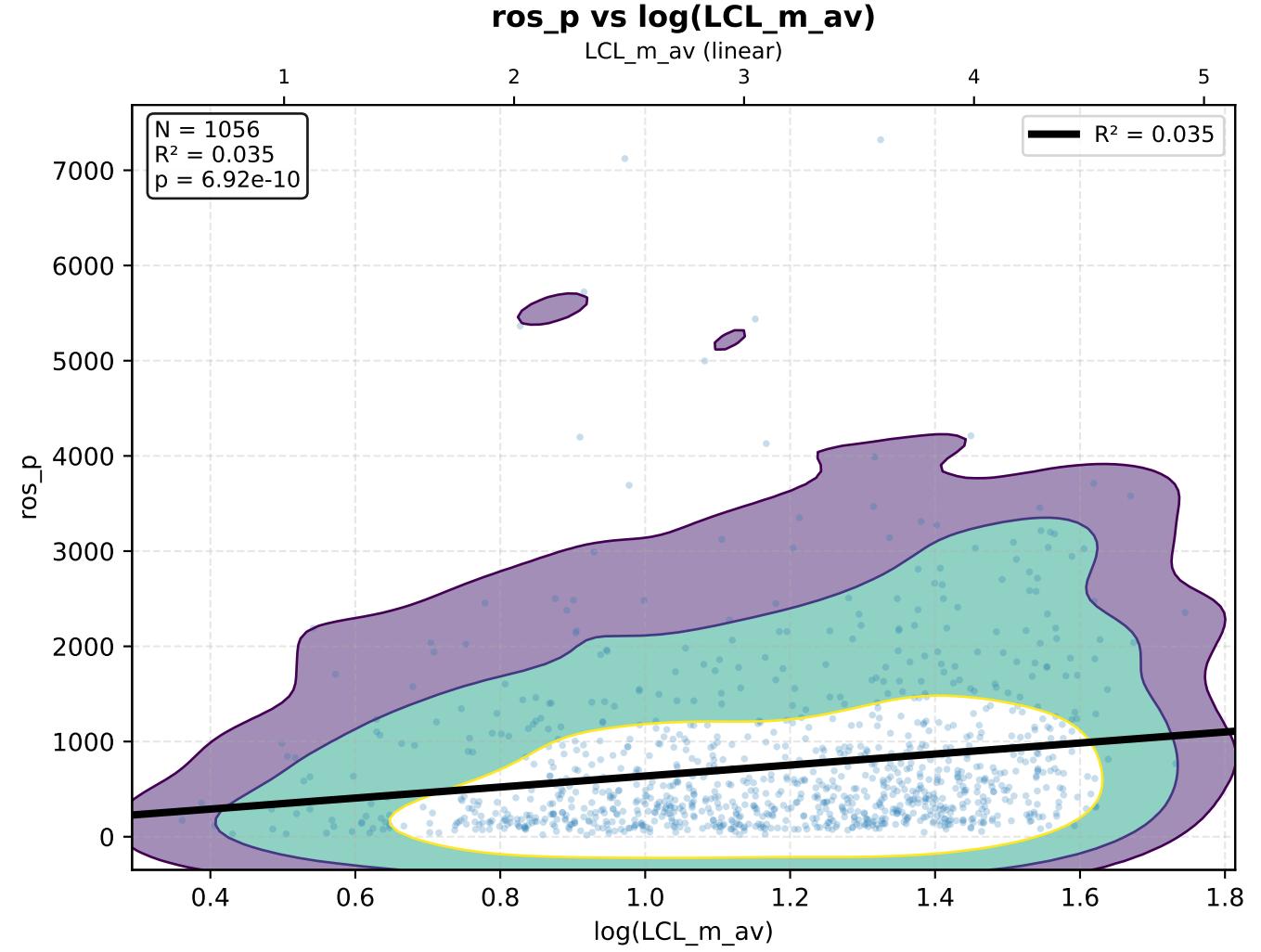
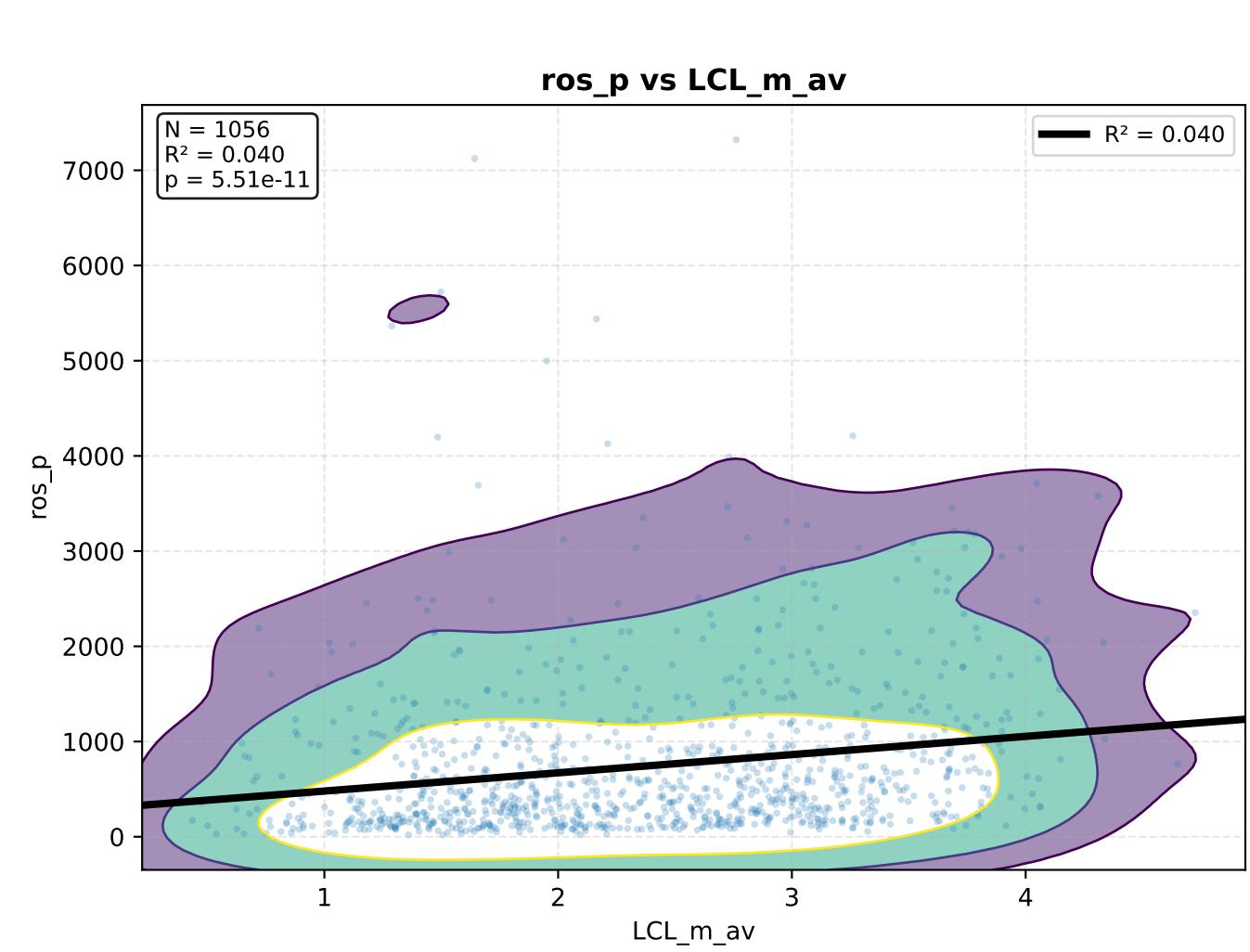
**log(ros\_p) vs LCL\_hPa\_av**



**log(ros\_p) vs log(LCL\_hPa\_av)**

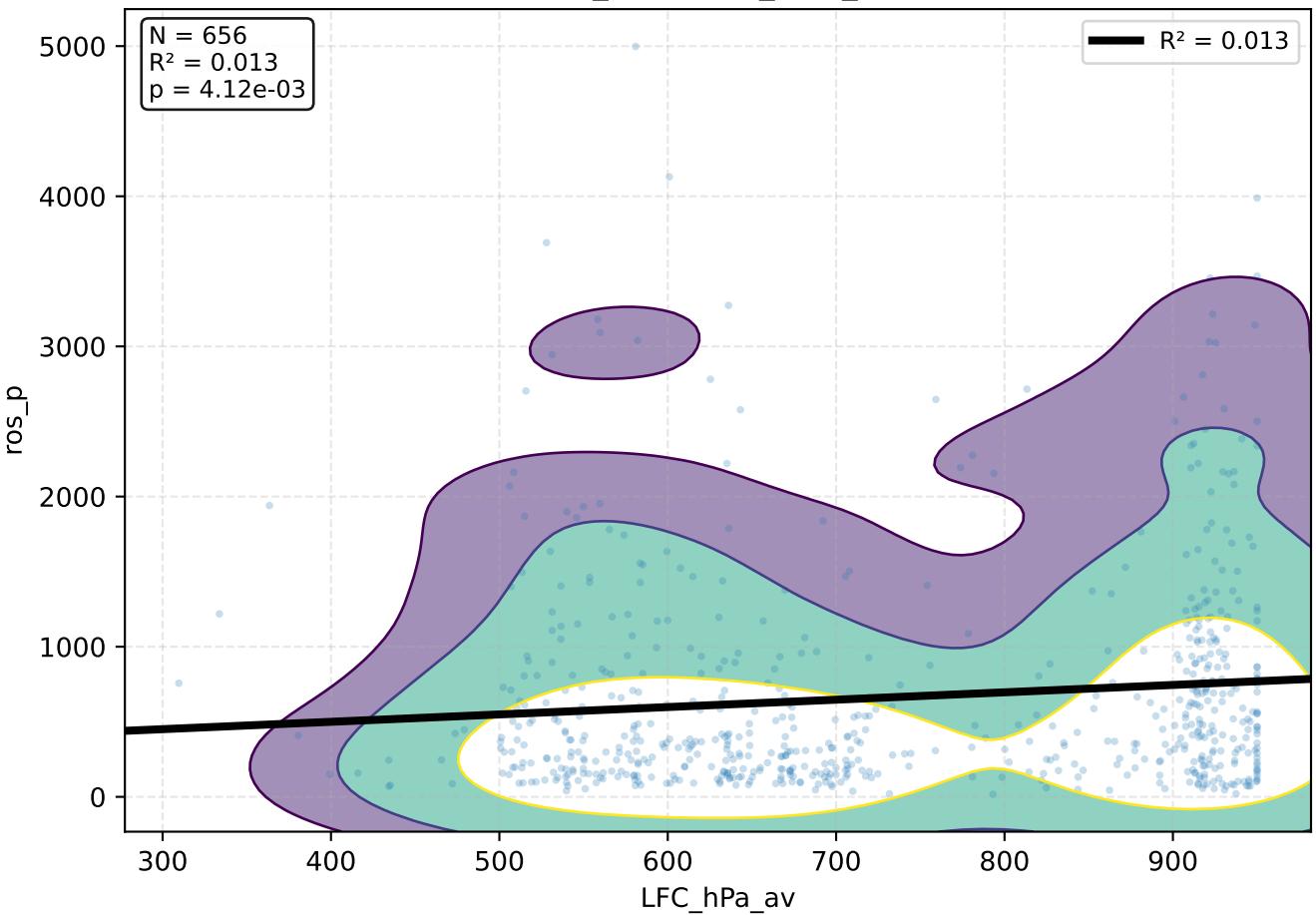


# LCL\_m\_av – KDE Density + Regressão

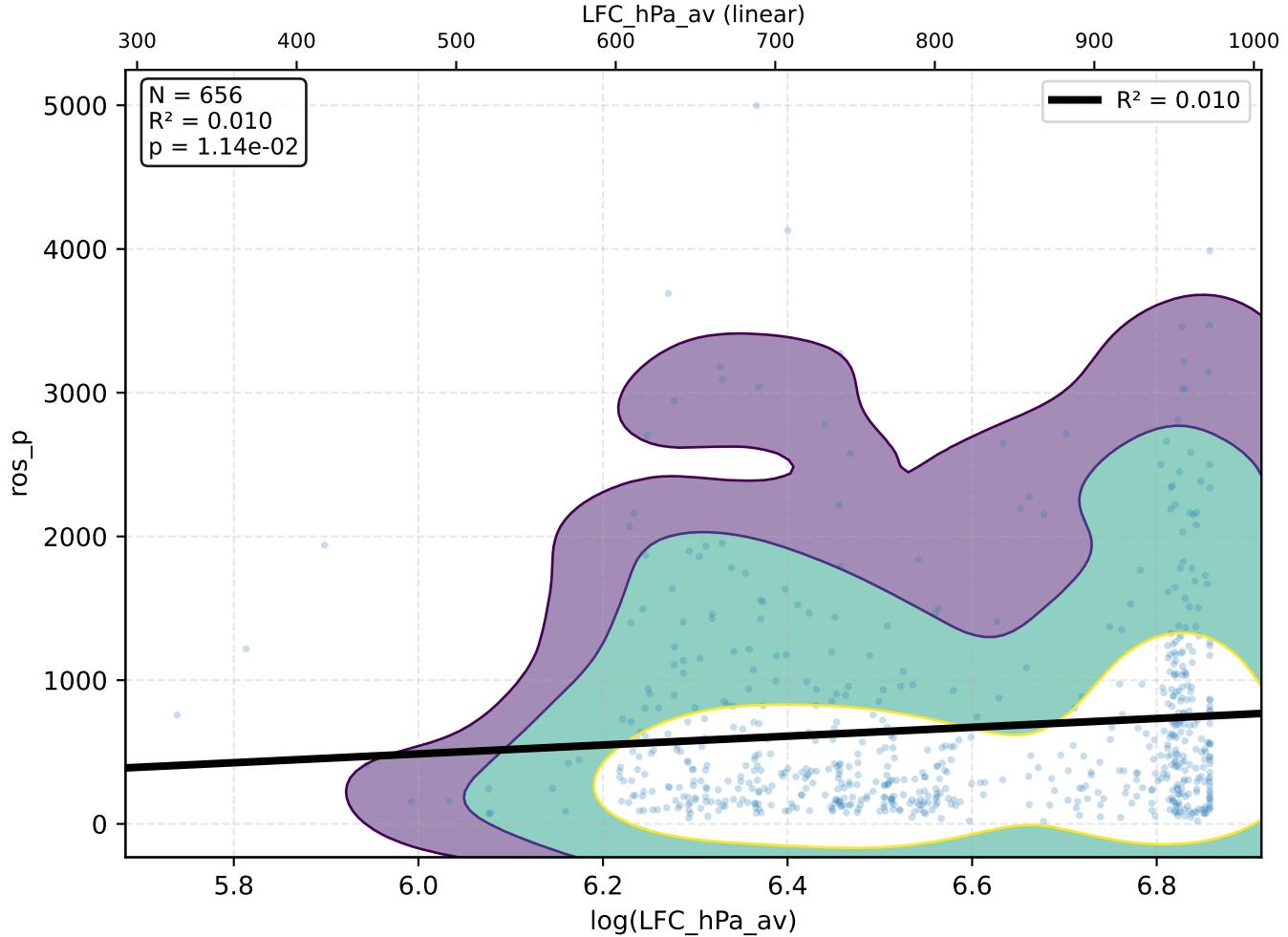


# LFC\_hPa\_av – KDE Density + Regressão

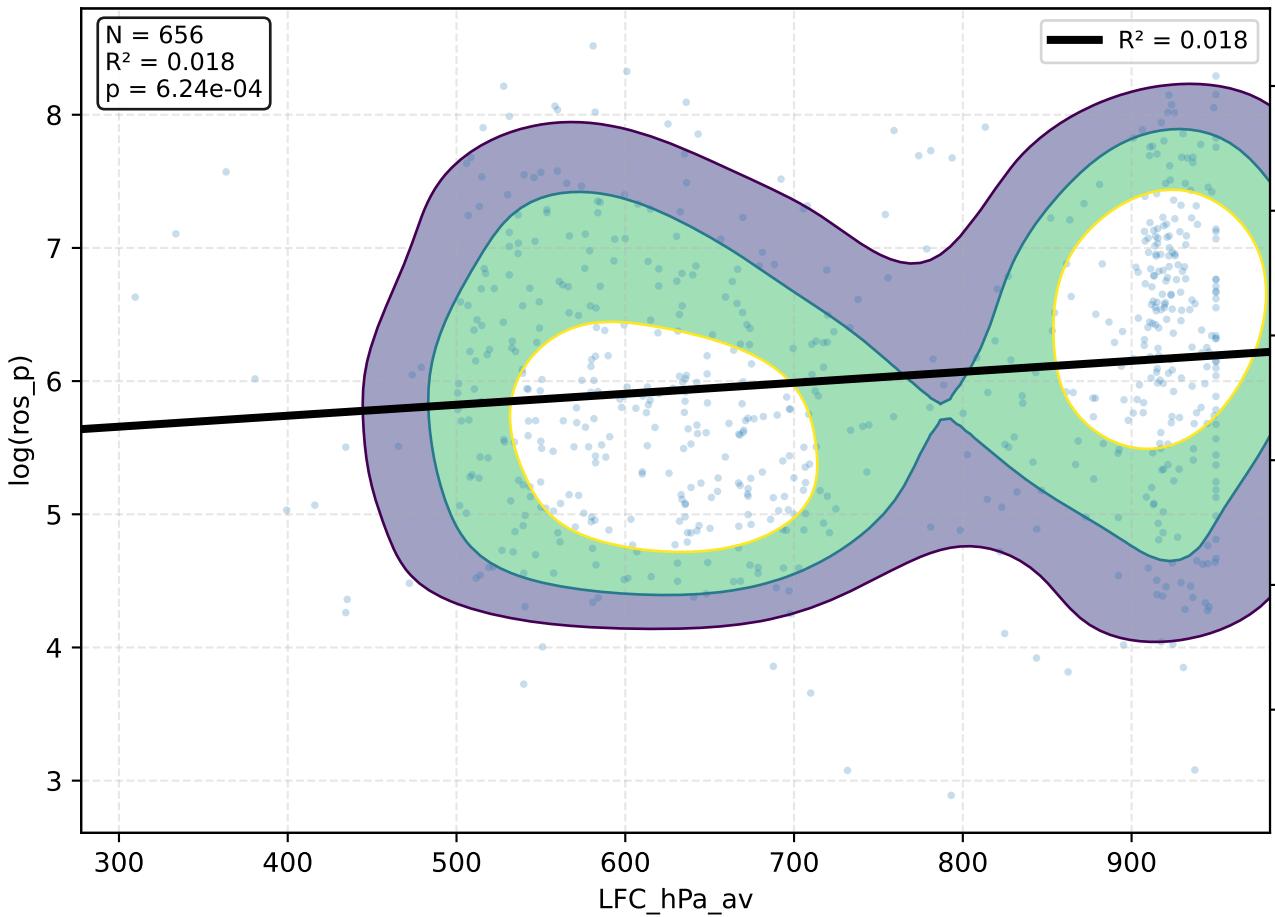
**ros\_p vs LFC\_hPa\_av**



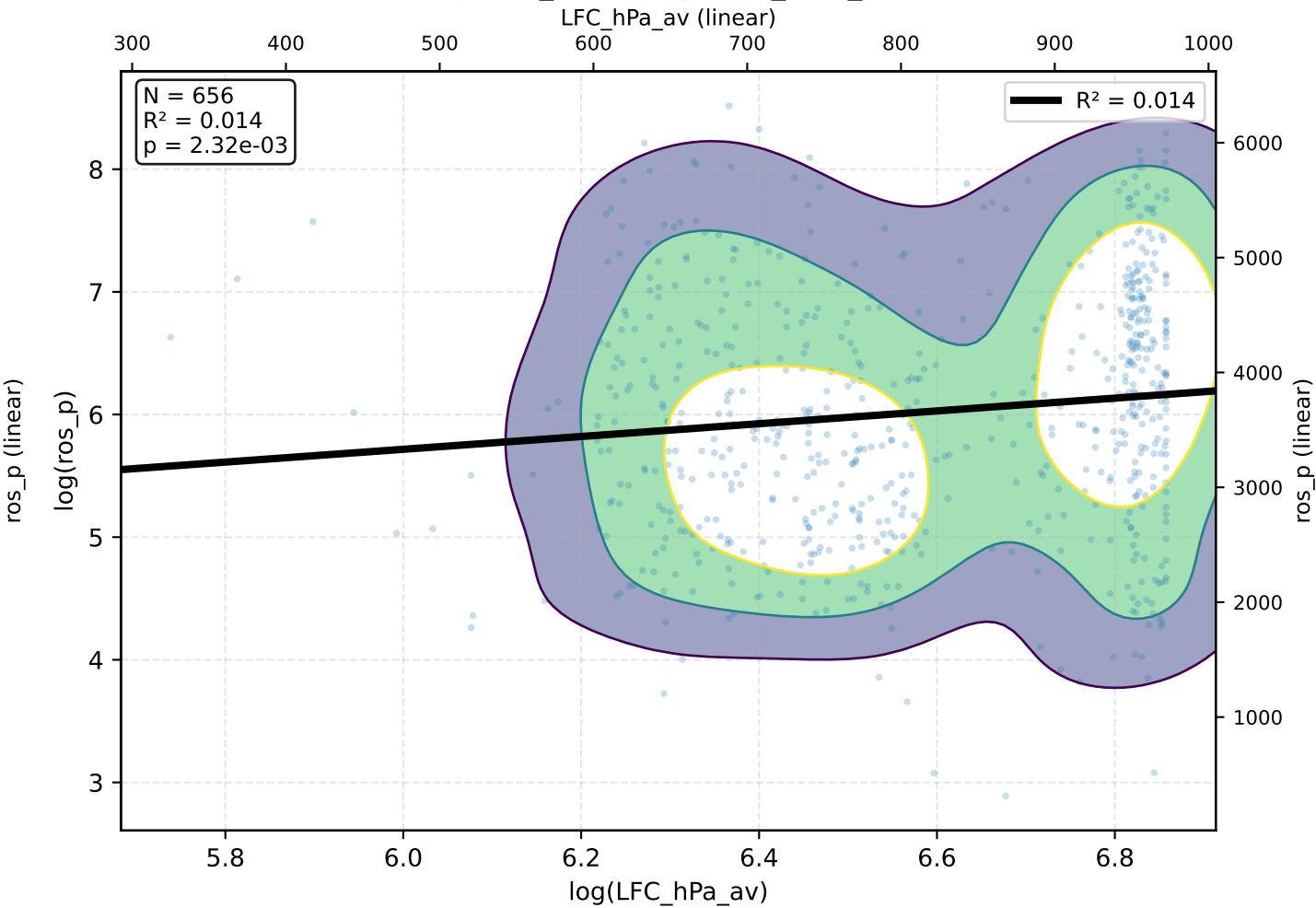
**ros\_p vs log(LFC\_hPa\_av)**



**log(ros\_p) vs LFC\_hPa\_av**

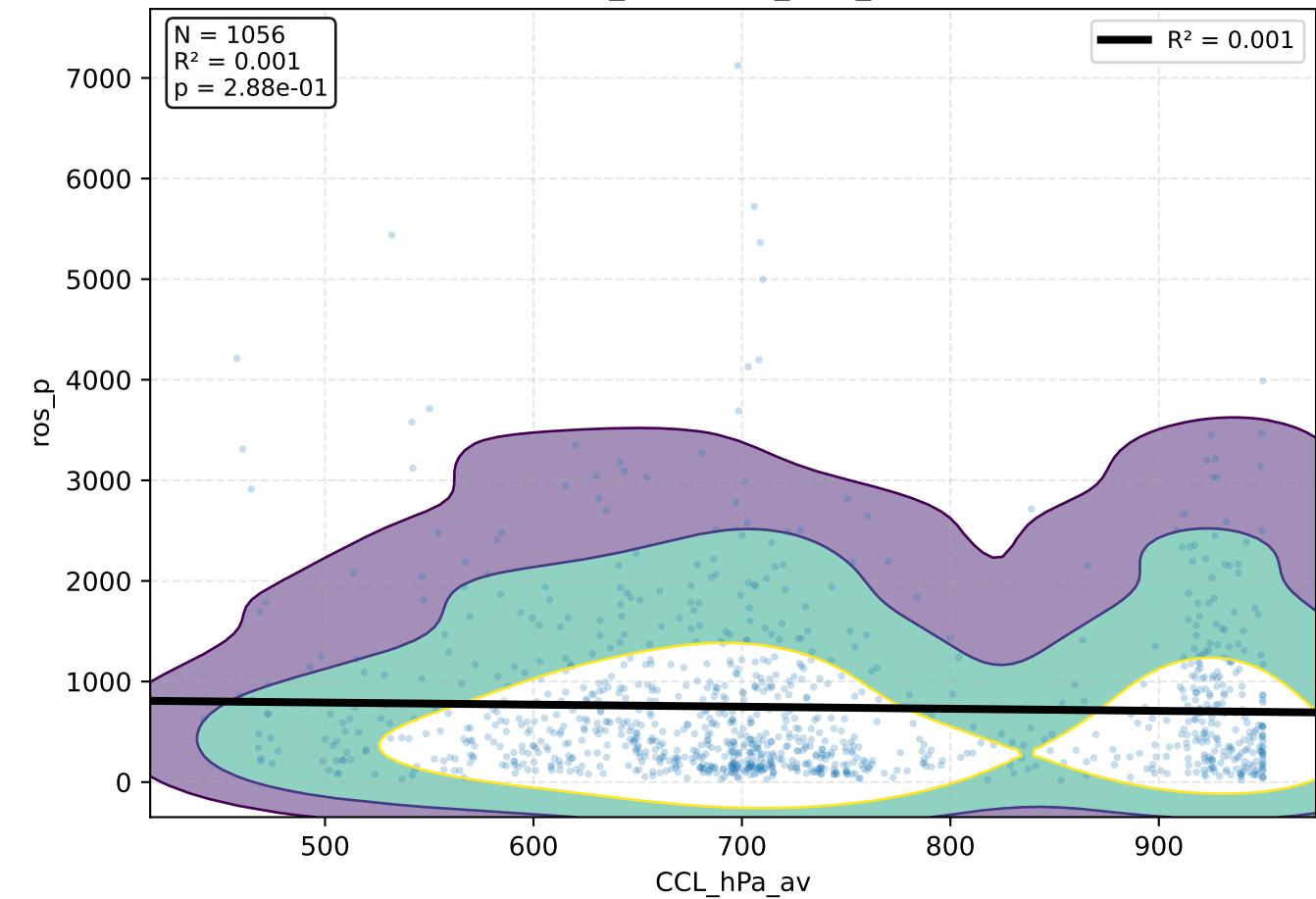


**log(ros\_p) vs log(LFC\_hPa\_av)**

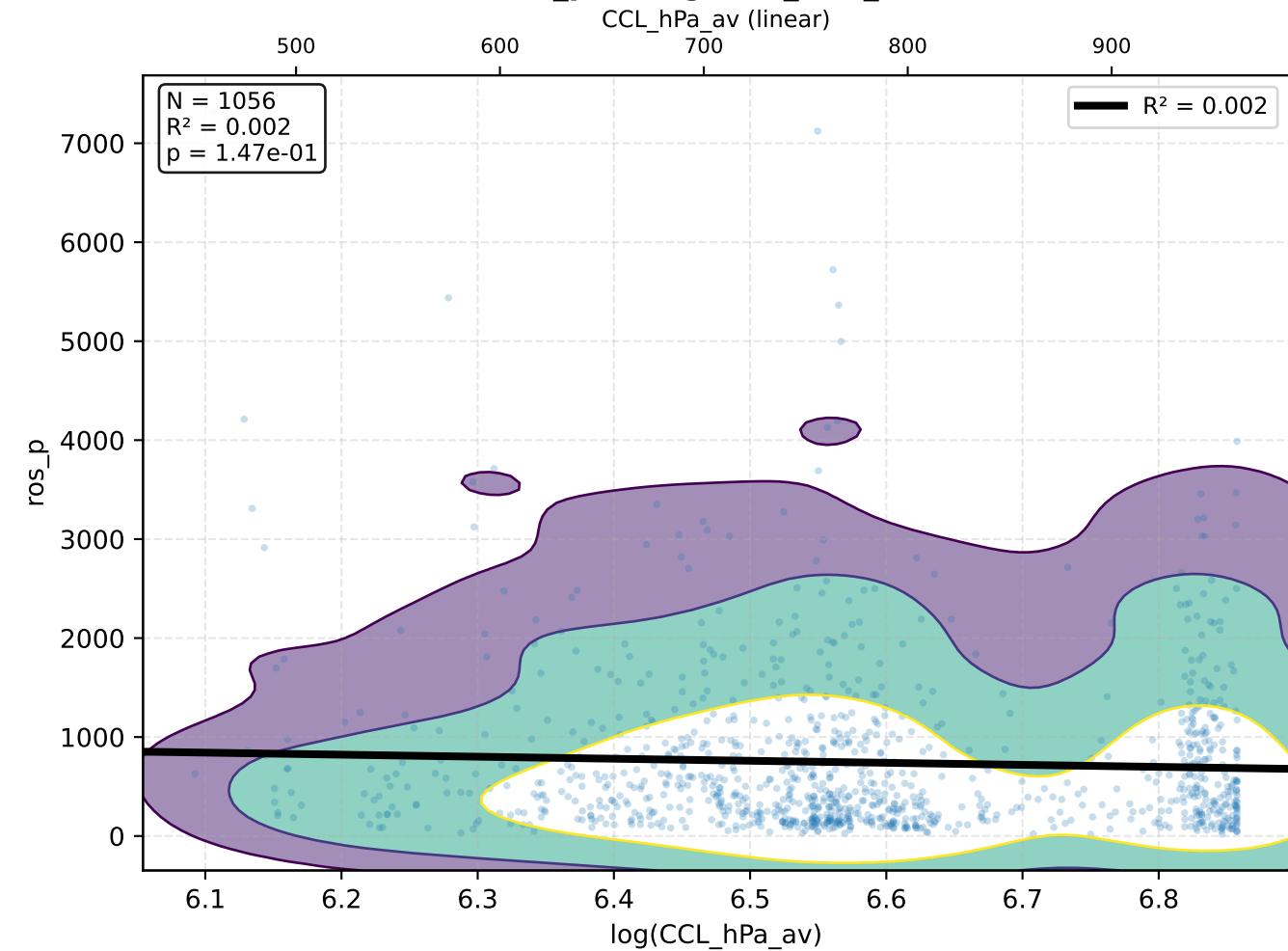


# CCL\_hPa\_av – KDE Density + Regressão

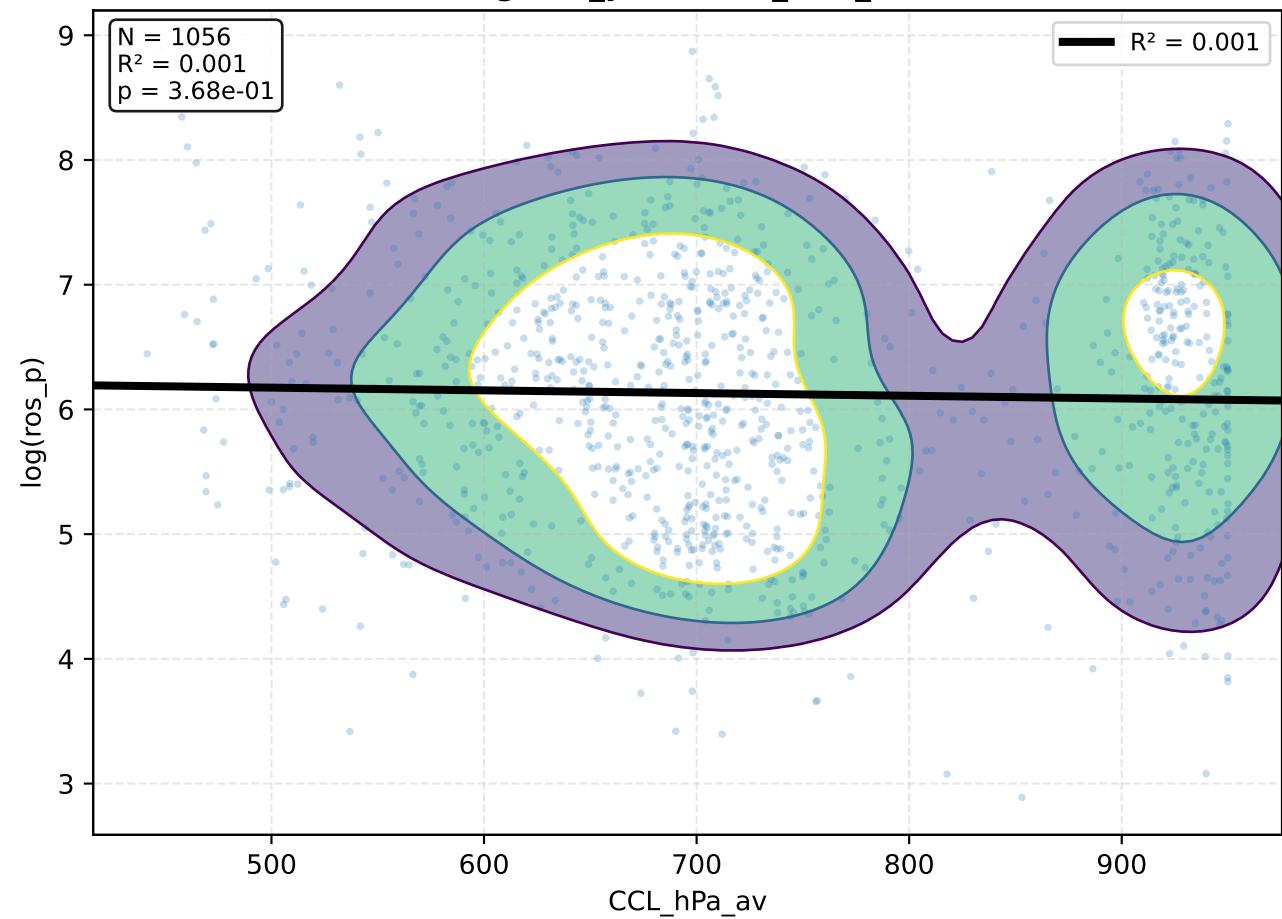
**ros\_p vs CCL\_hPa\_av**



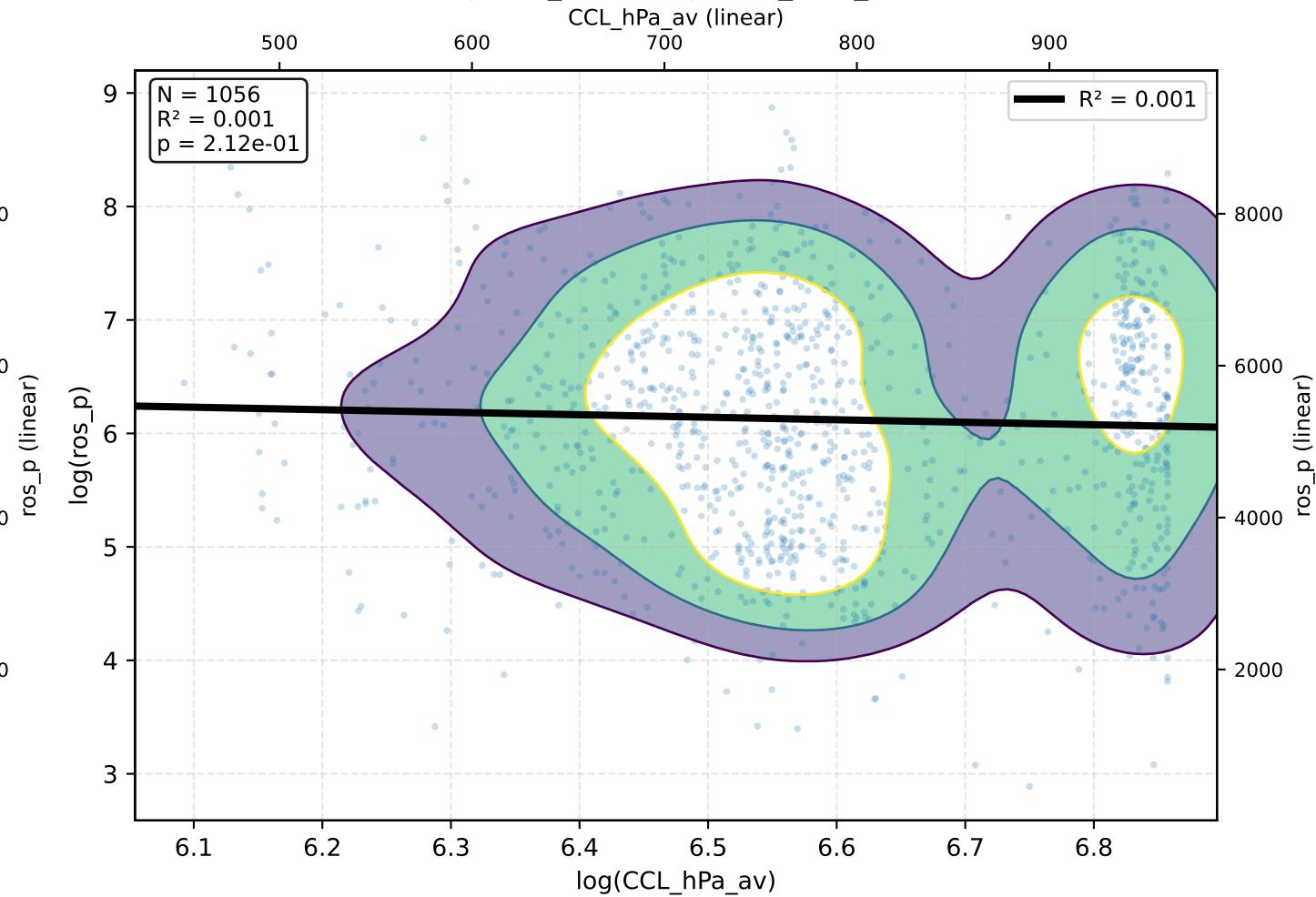
**ros\_p vs log(CCL\_hPa\_av)**



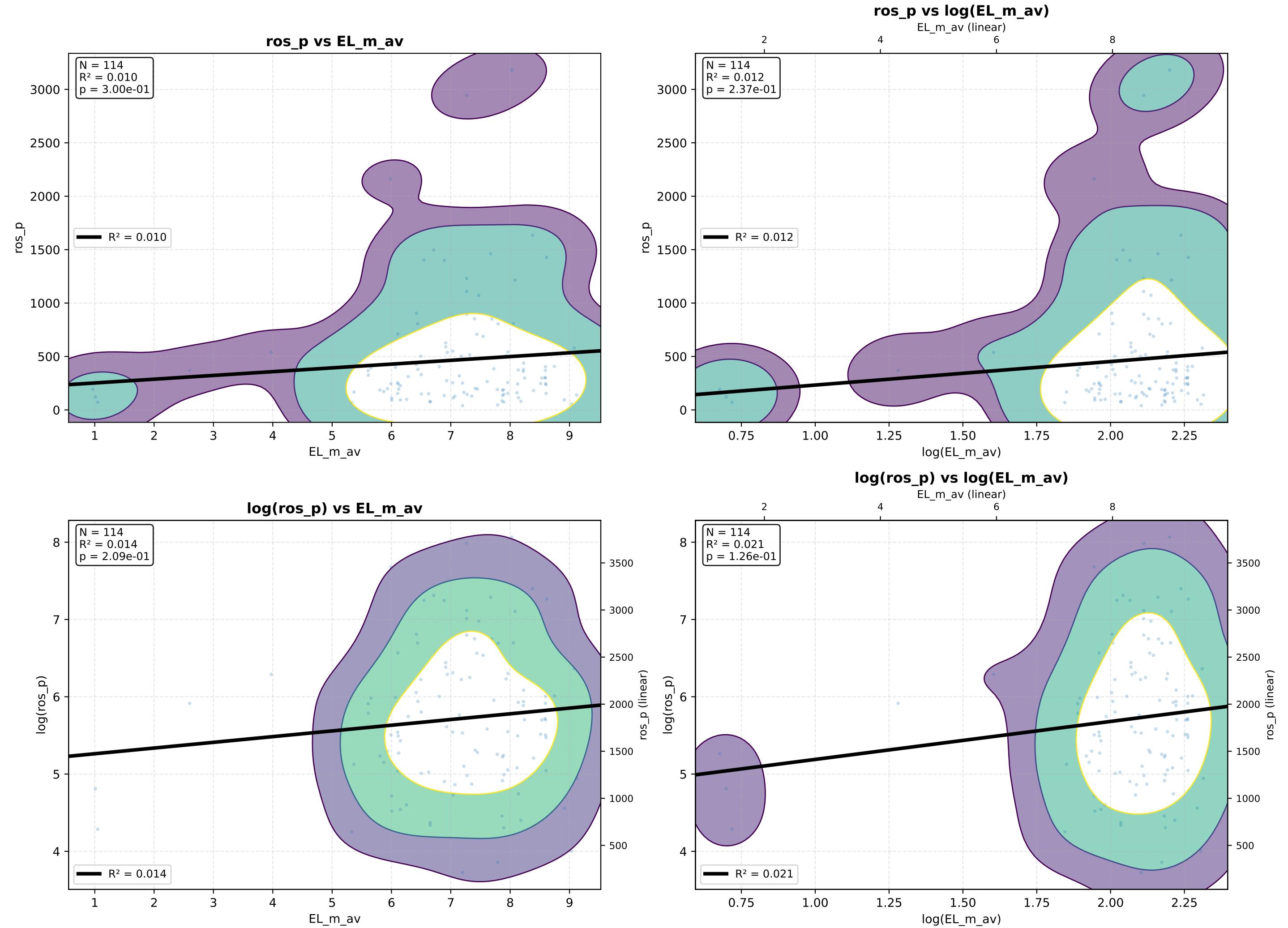
**log(ros\_p) vs CCL\_hPa\_av**



**log(ros\_p) vs log(CCL\_hPa\_av)**

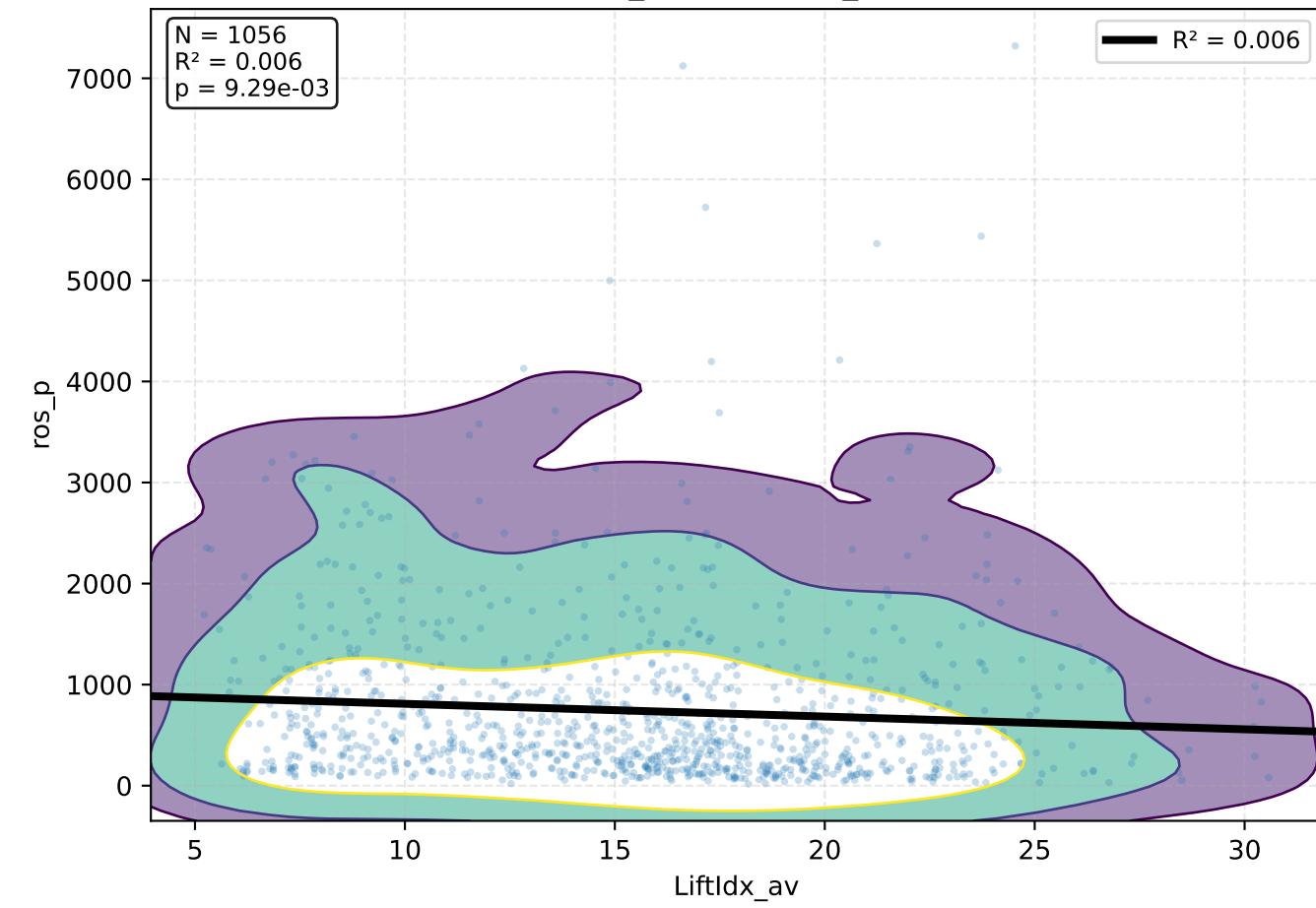


# EL\_m\_av – KDE Density + Regressão

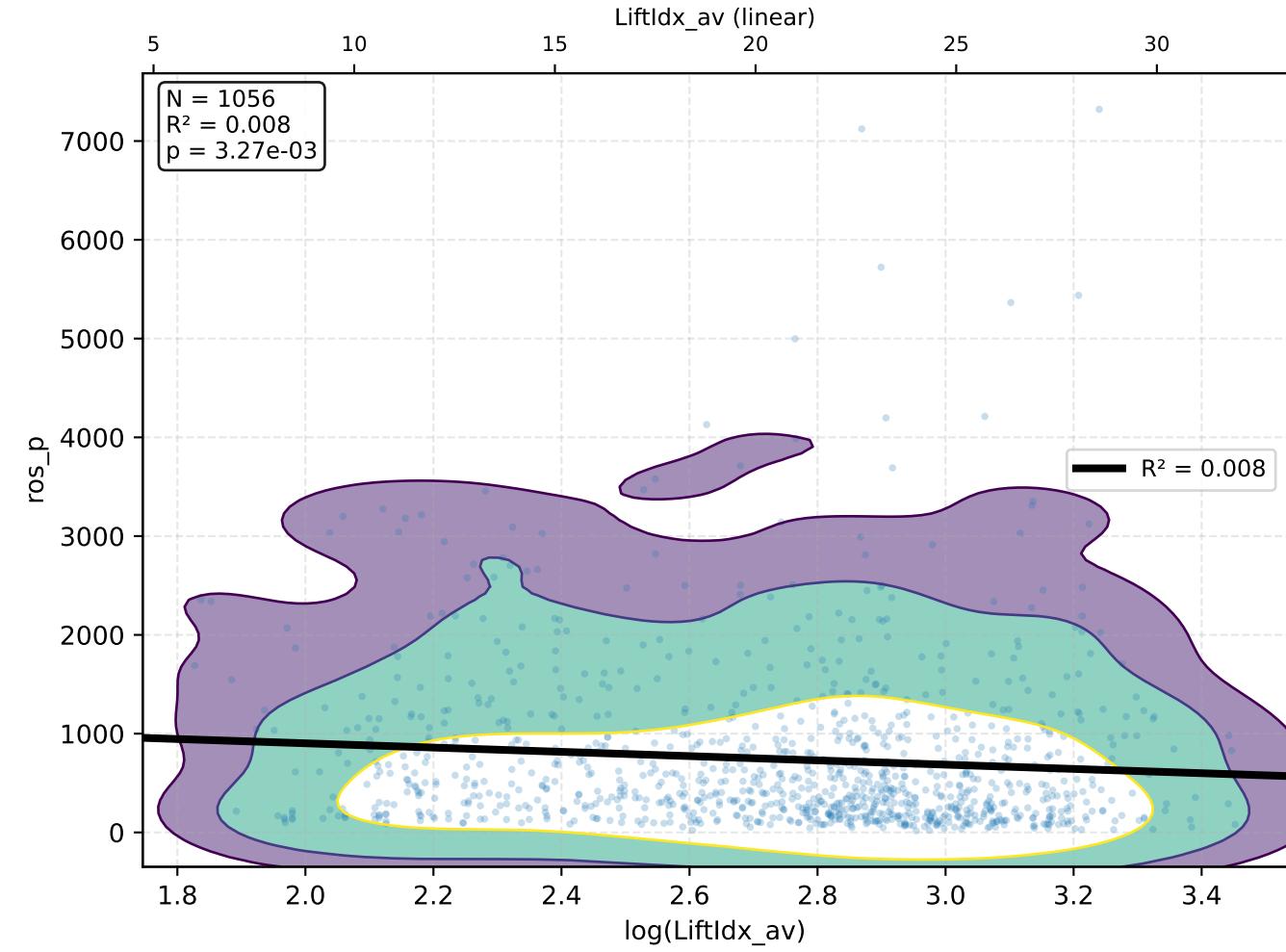


# LiftIdx\_av – KDE Density + Regressão

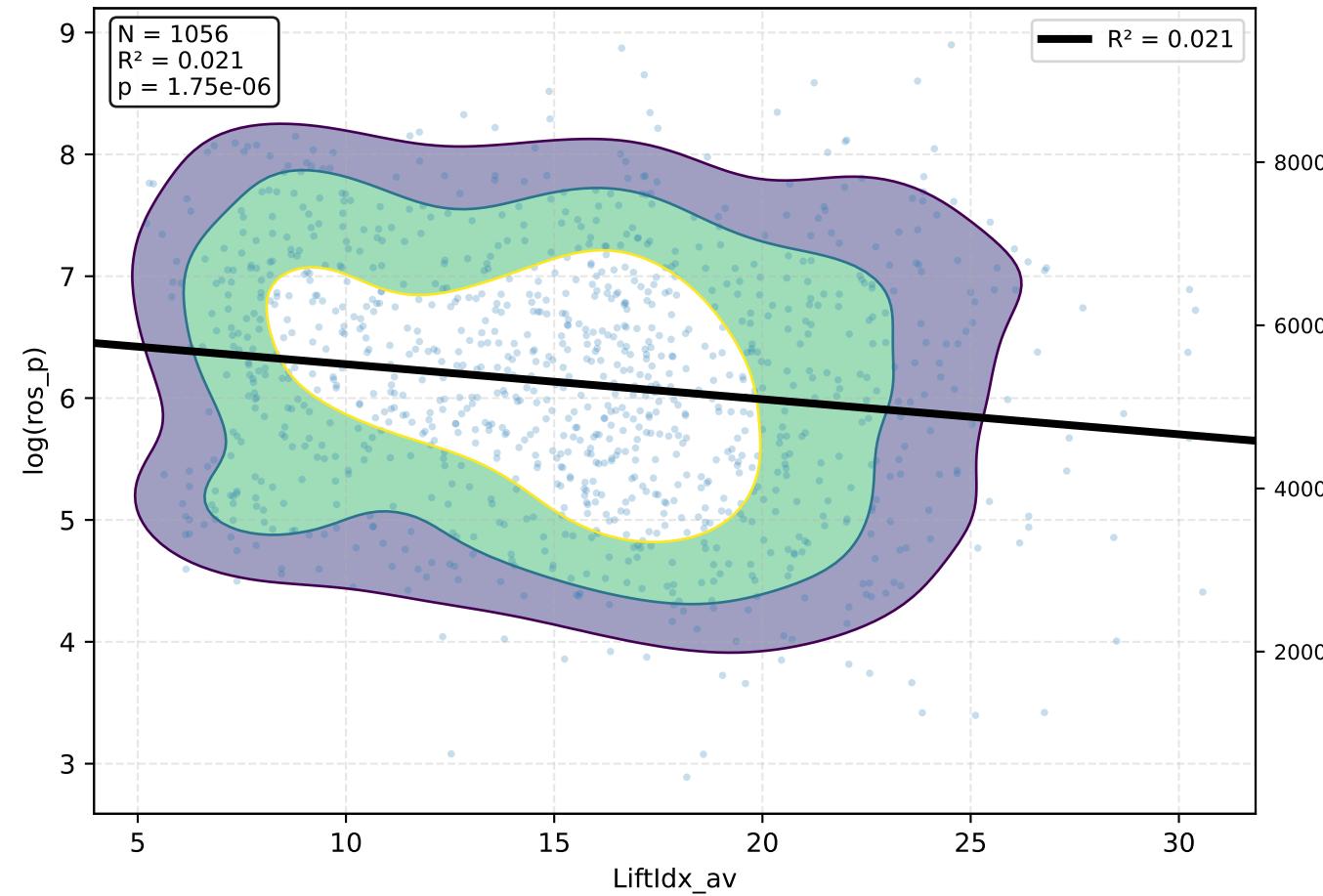
**ros\_p vs LiftIdx\_av**



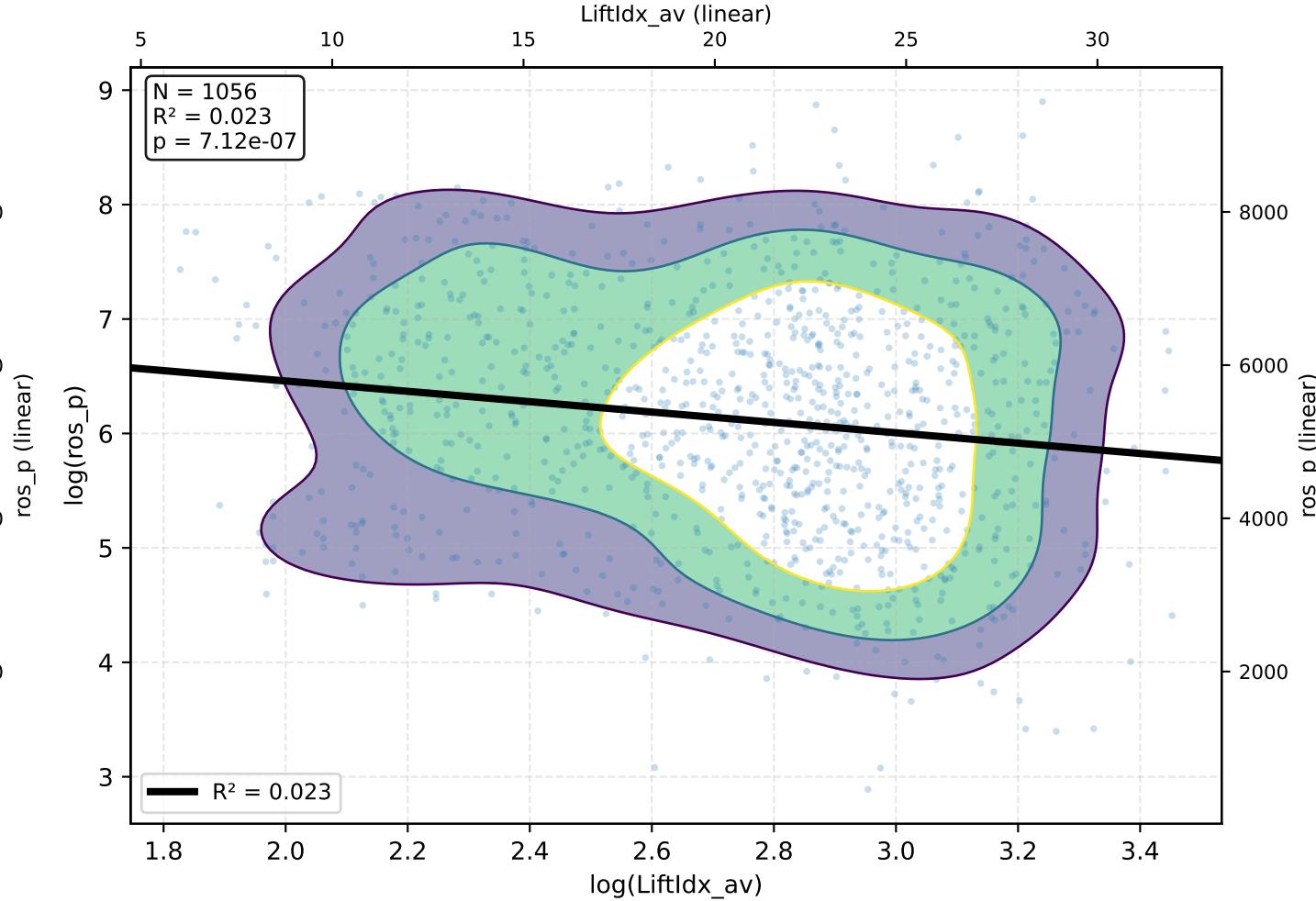
**ros\_p vs log(LiftIdx\_av)**



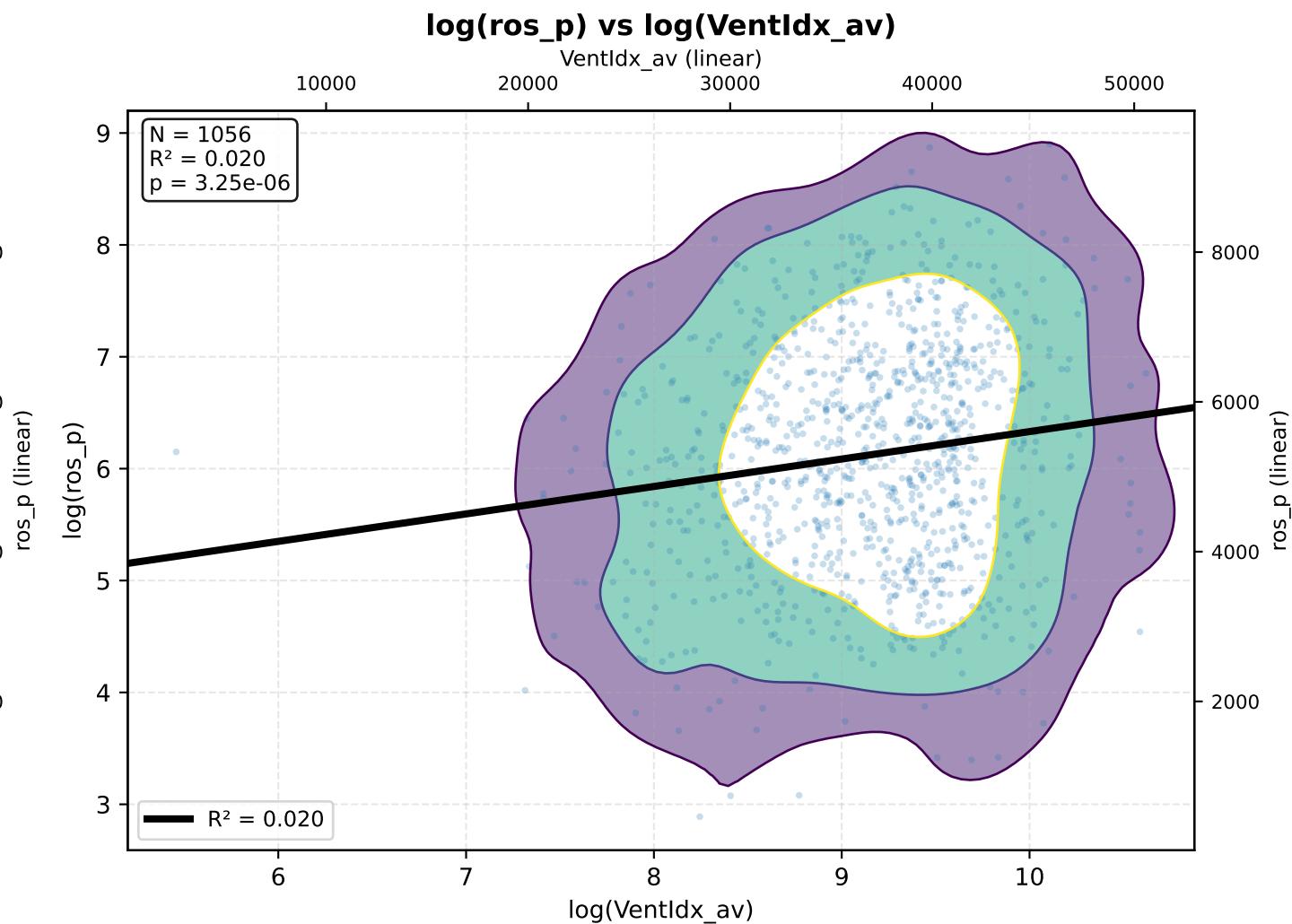
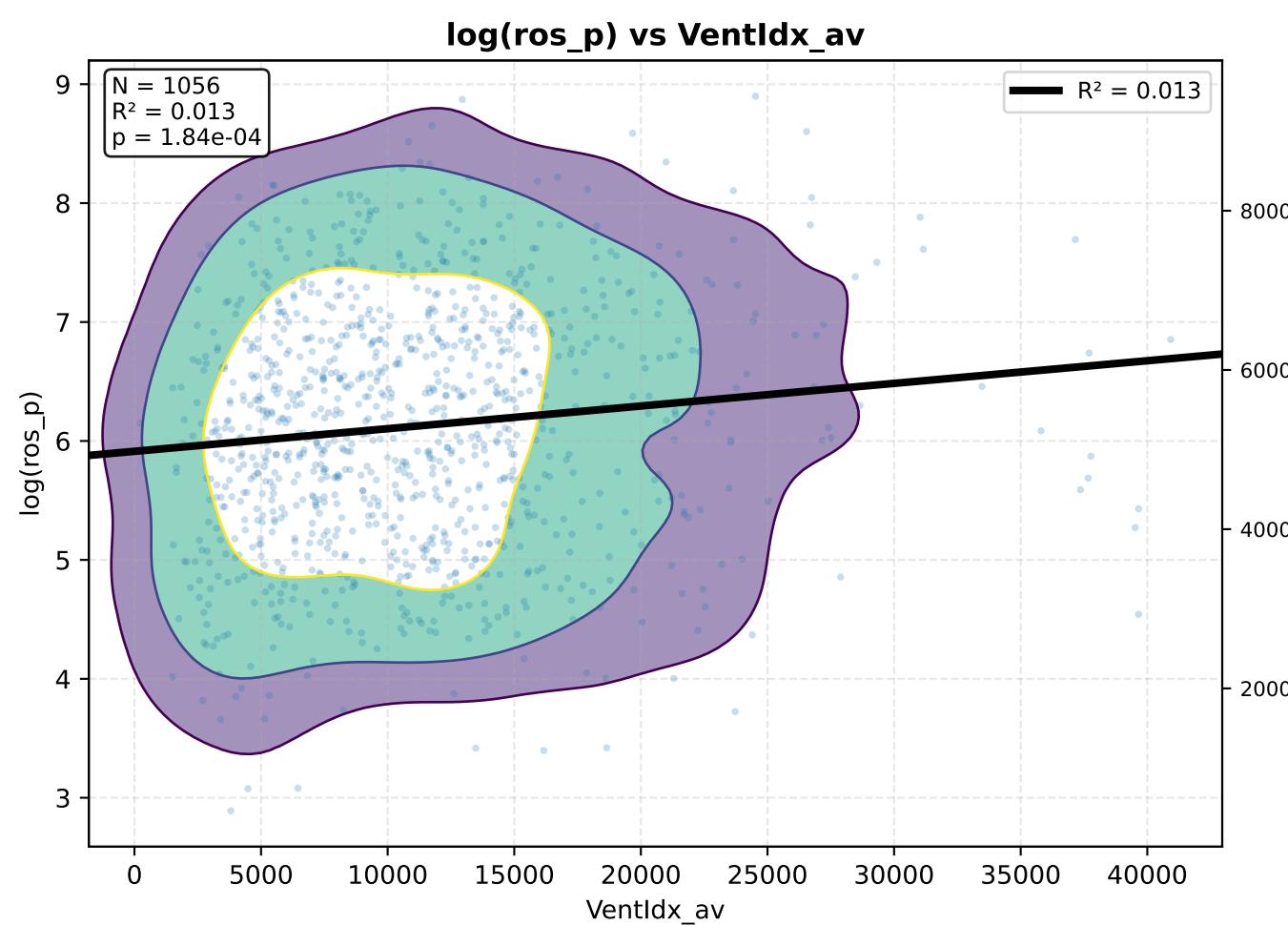
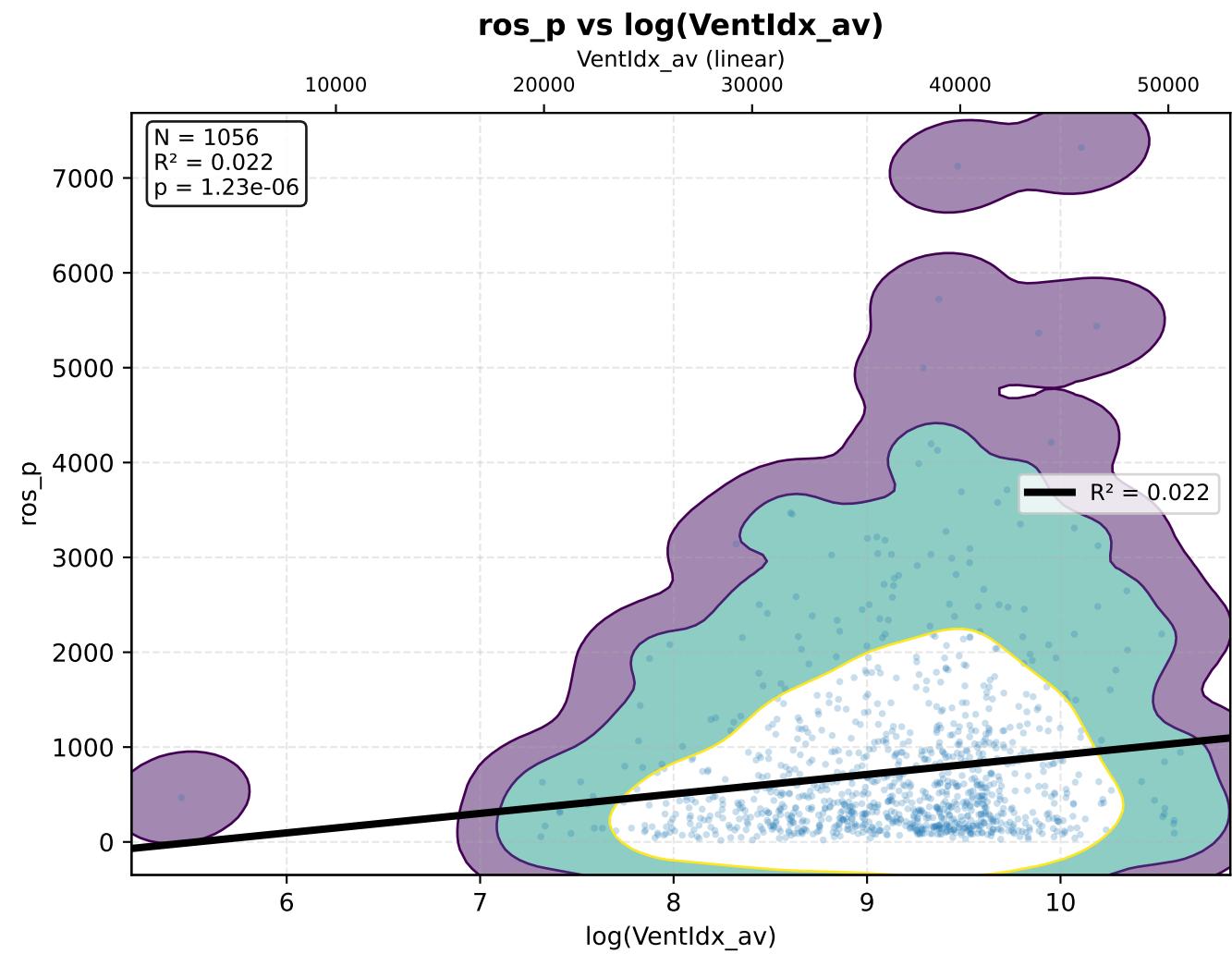
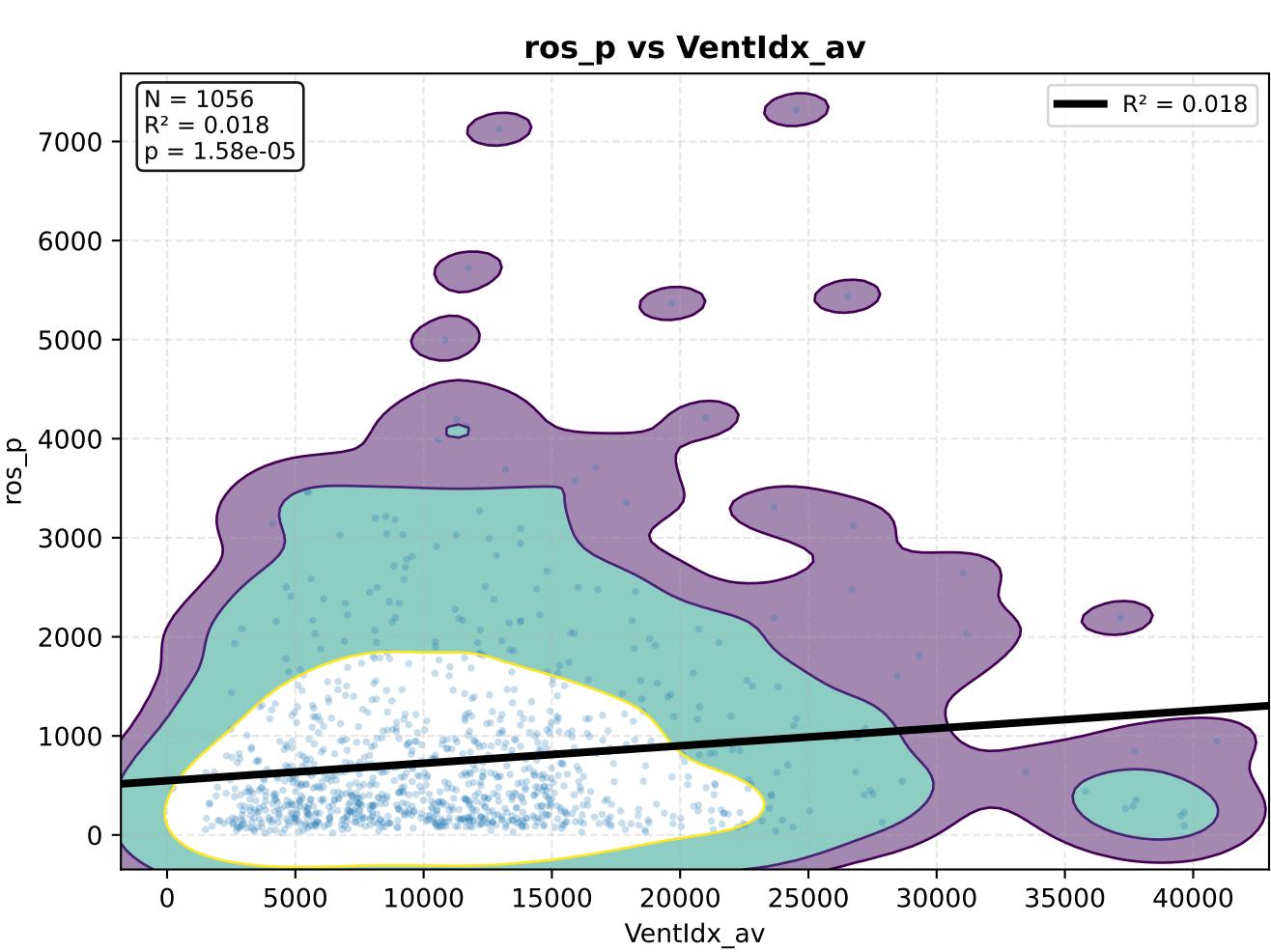
**log(ros\_p) vs LiftIdx\_av**



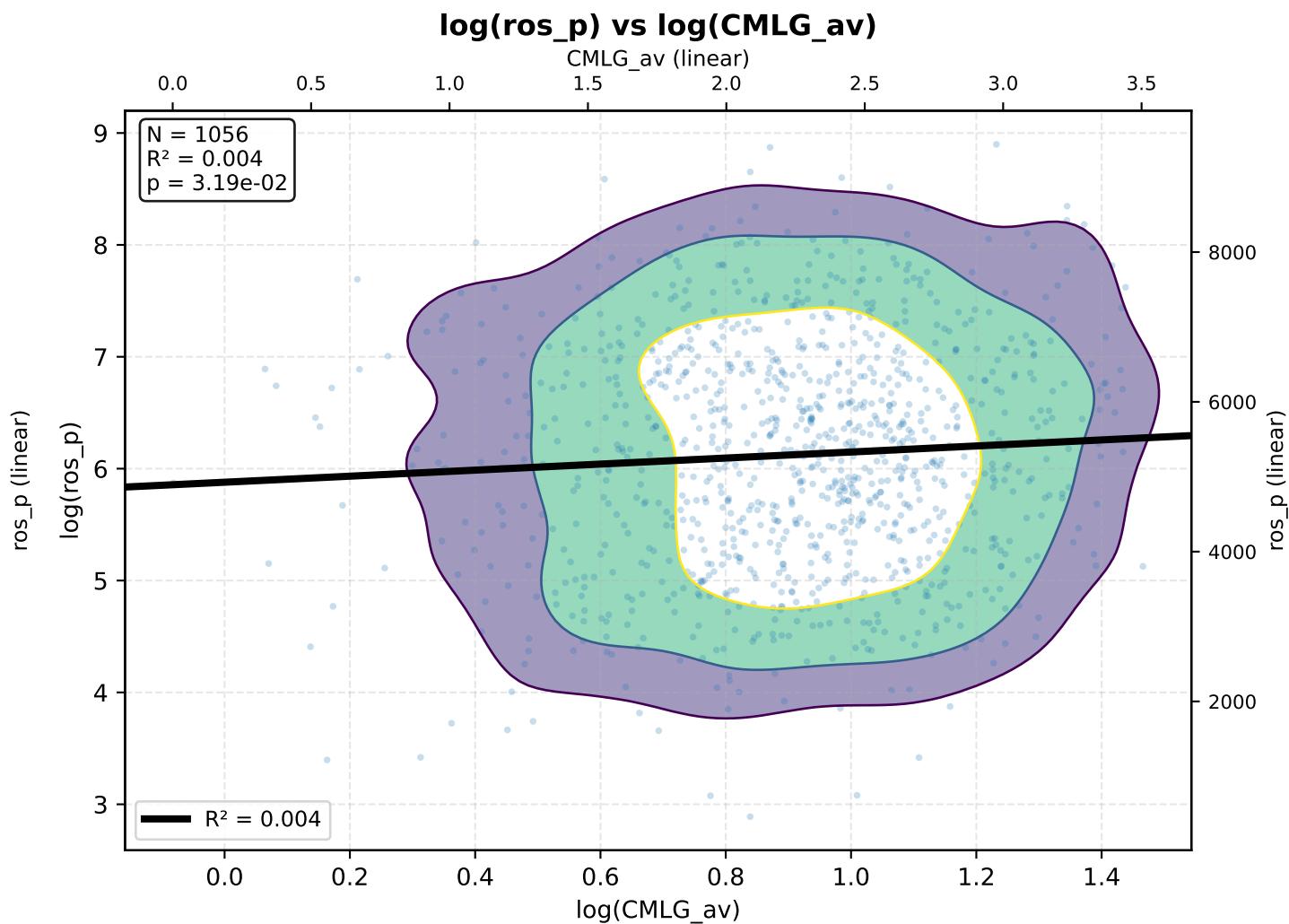
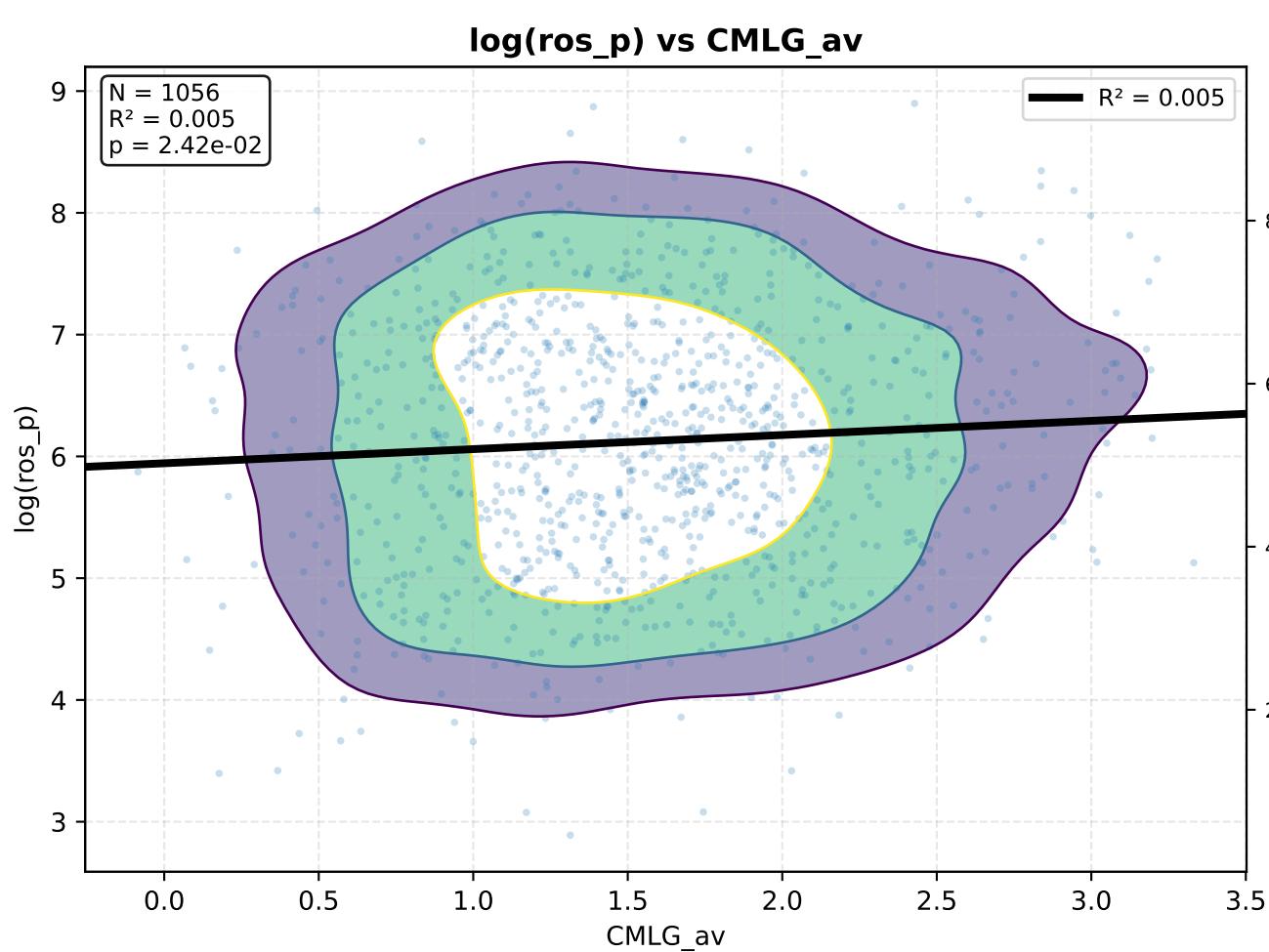
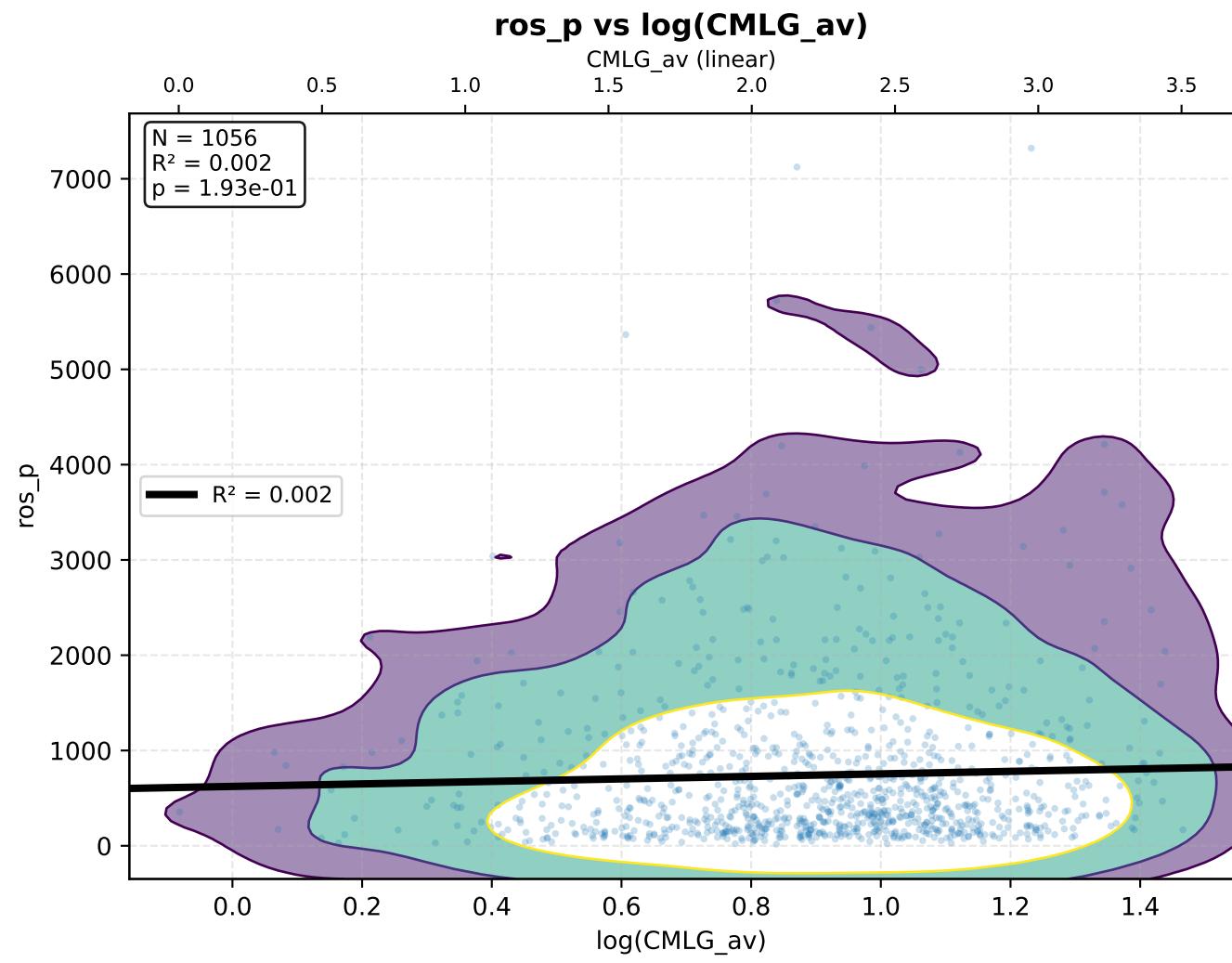
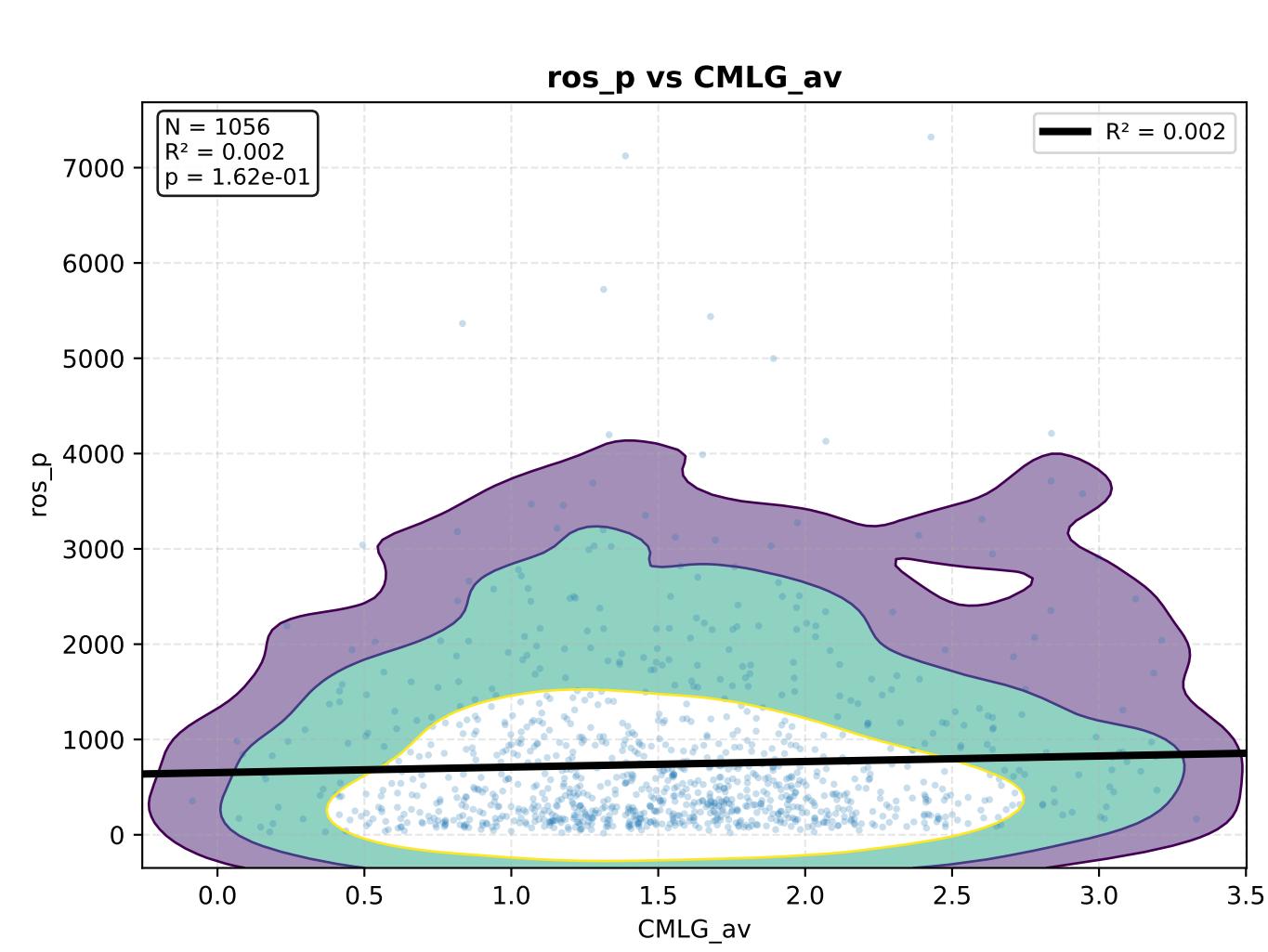
**log(ros\_p) vs log(LiftIdx\_av)**



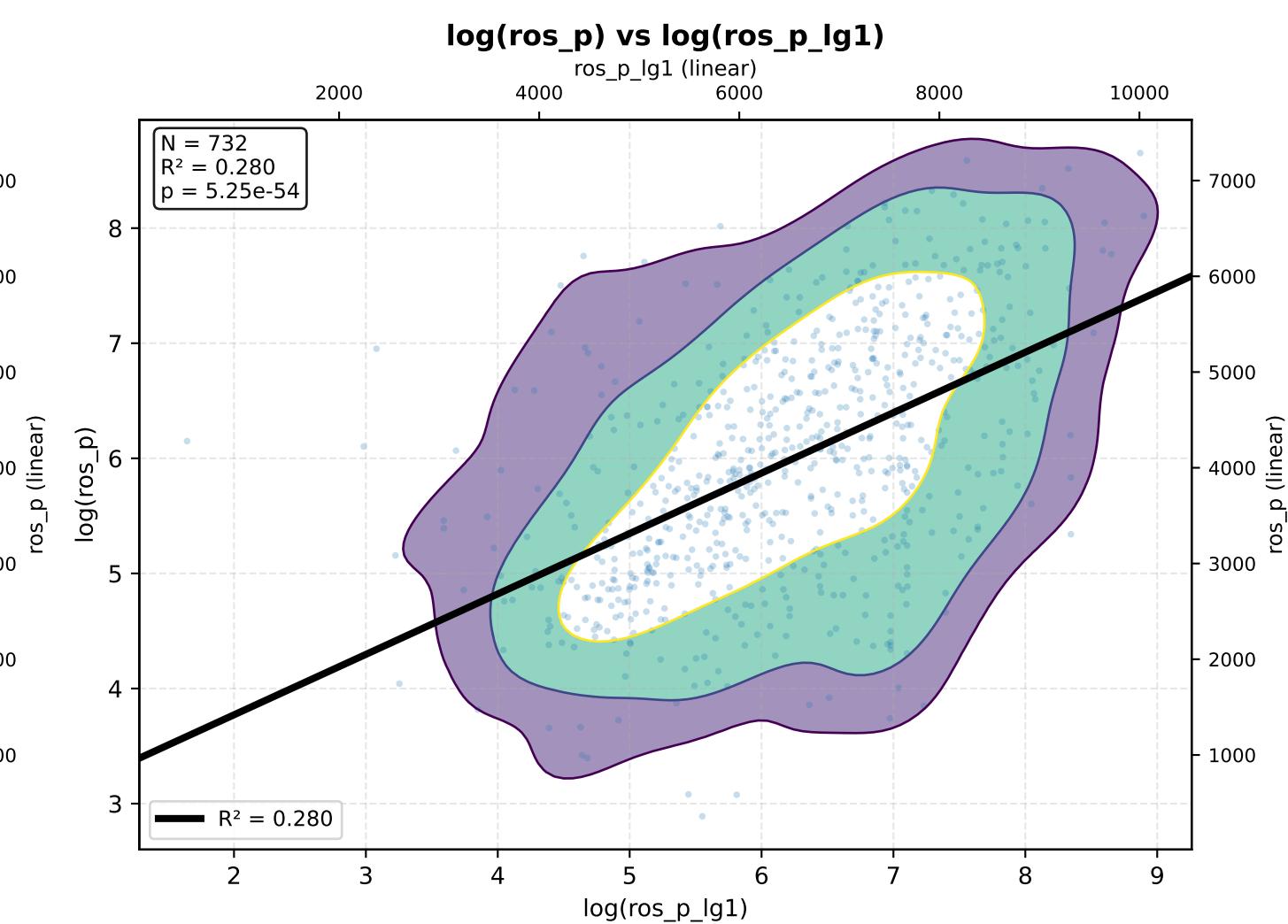
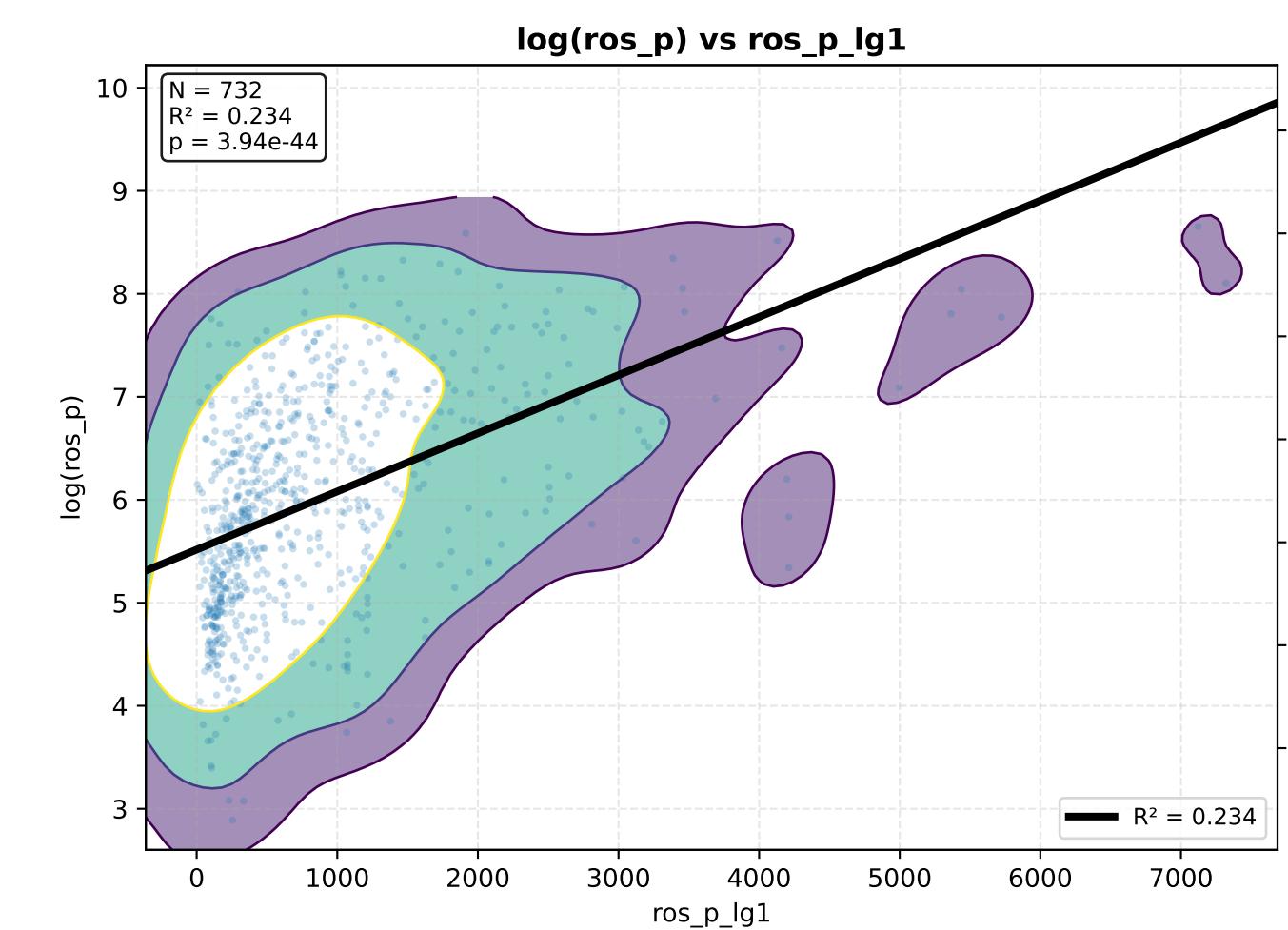
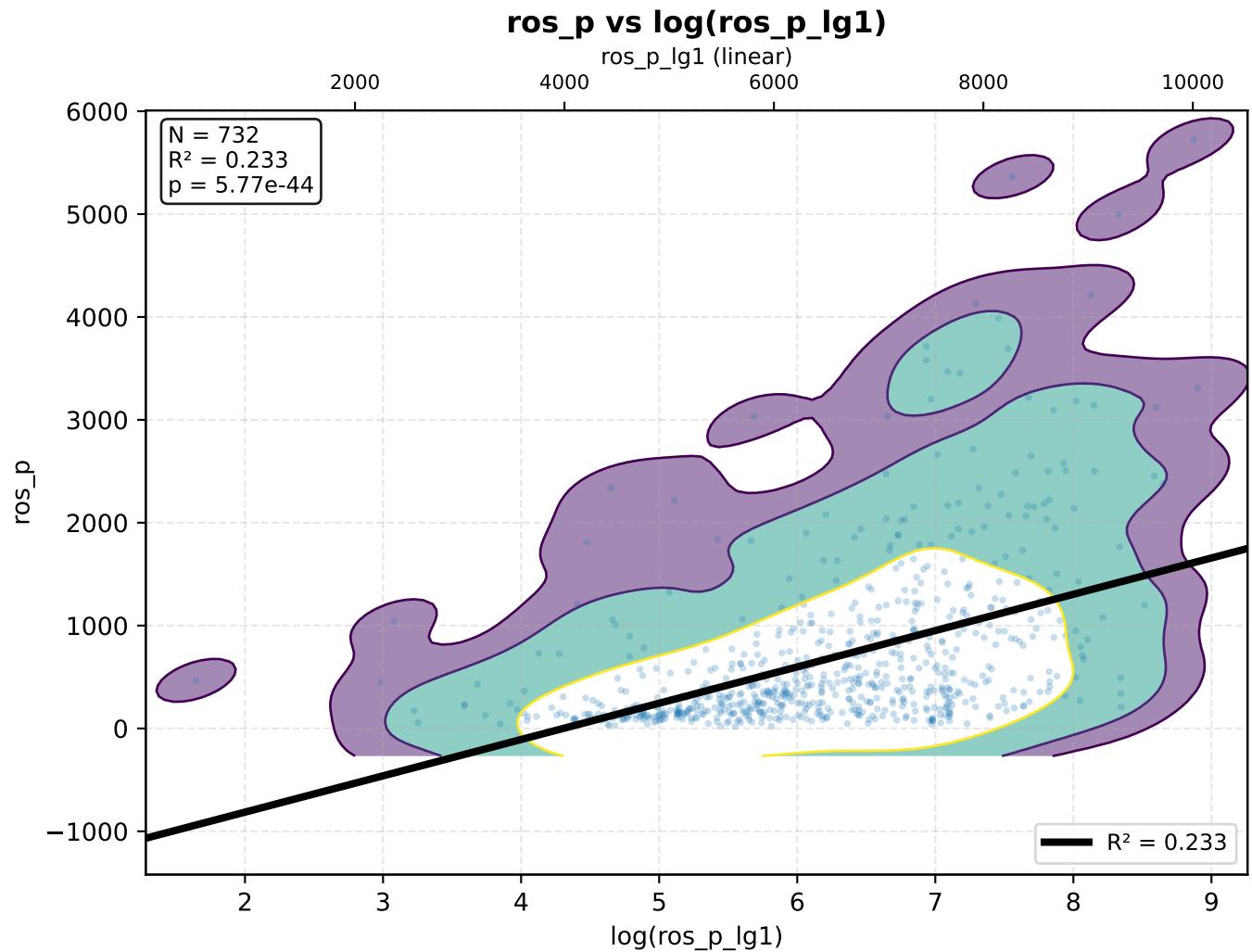
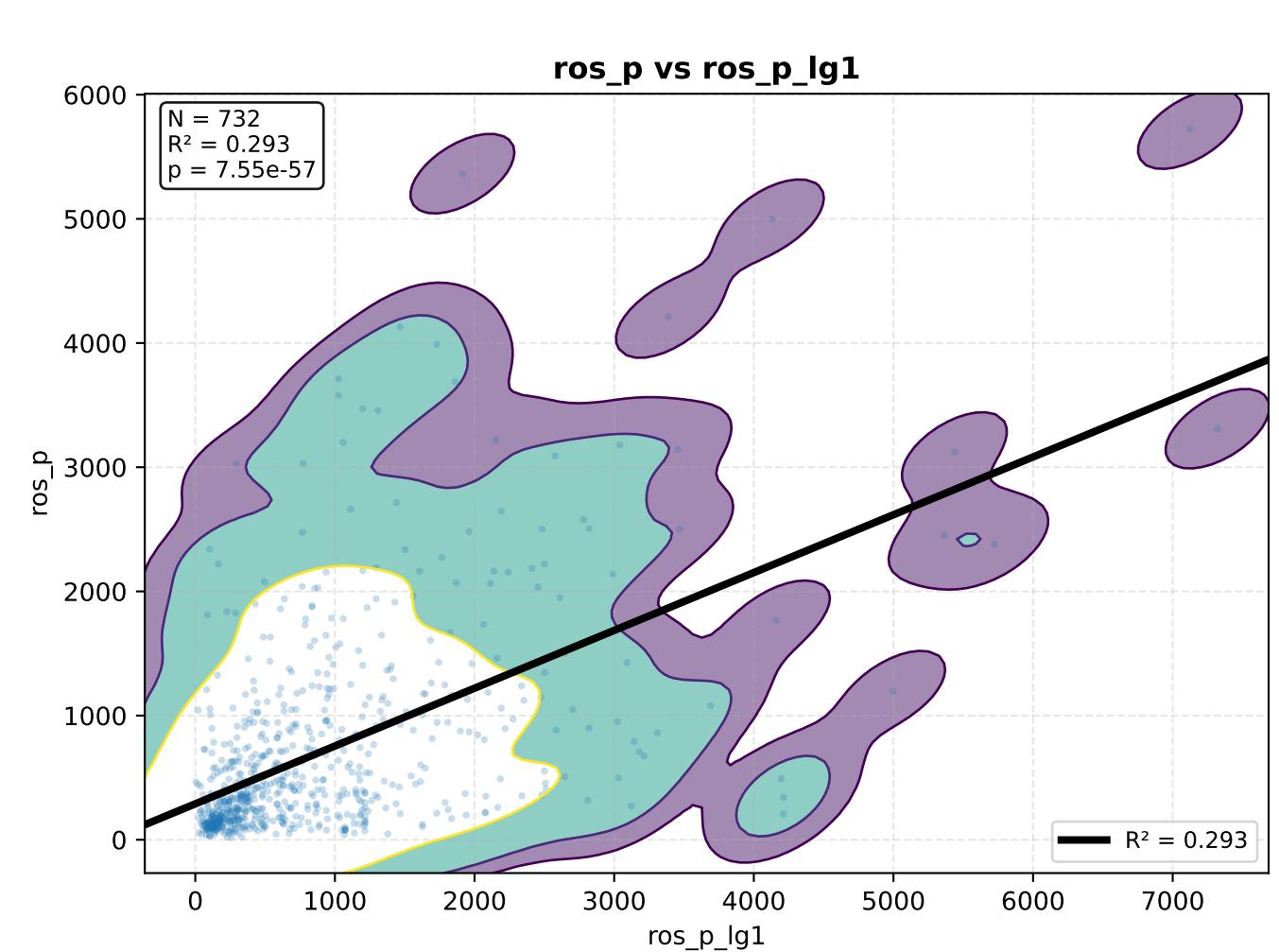
# VentIdx\_av – KDE Density + Regressão



# CMLG\_av – KDE Density + Regressão



# ros\_p\_lg1 – KDE Density + Regressão



f\_start - KDE Density + Regressão

