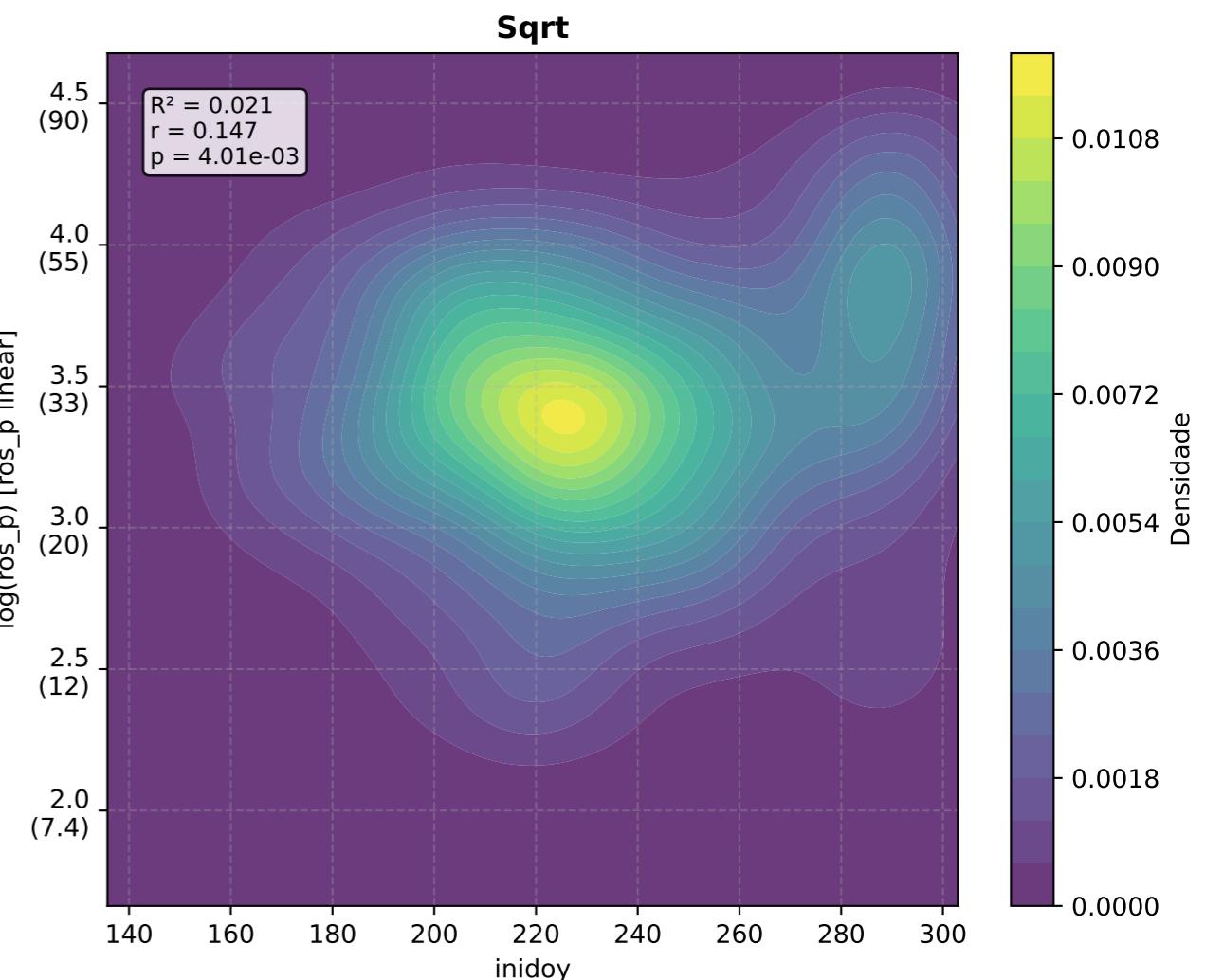
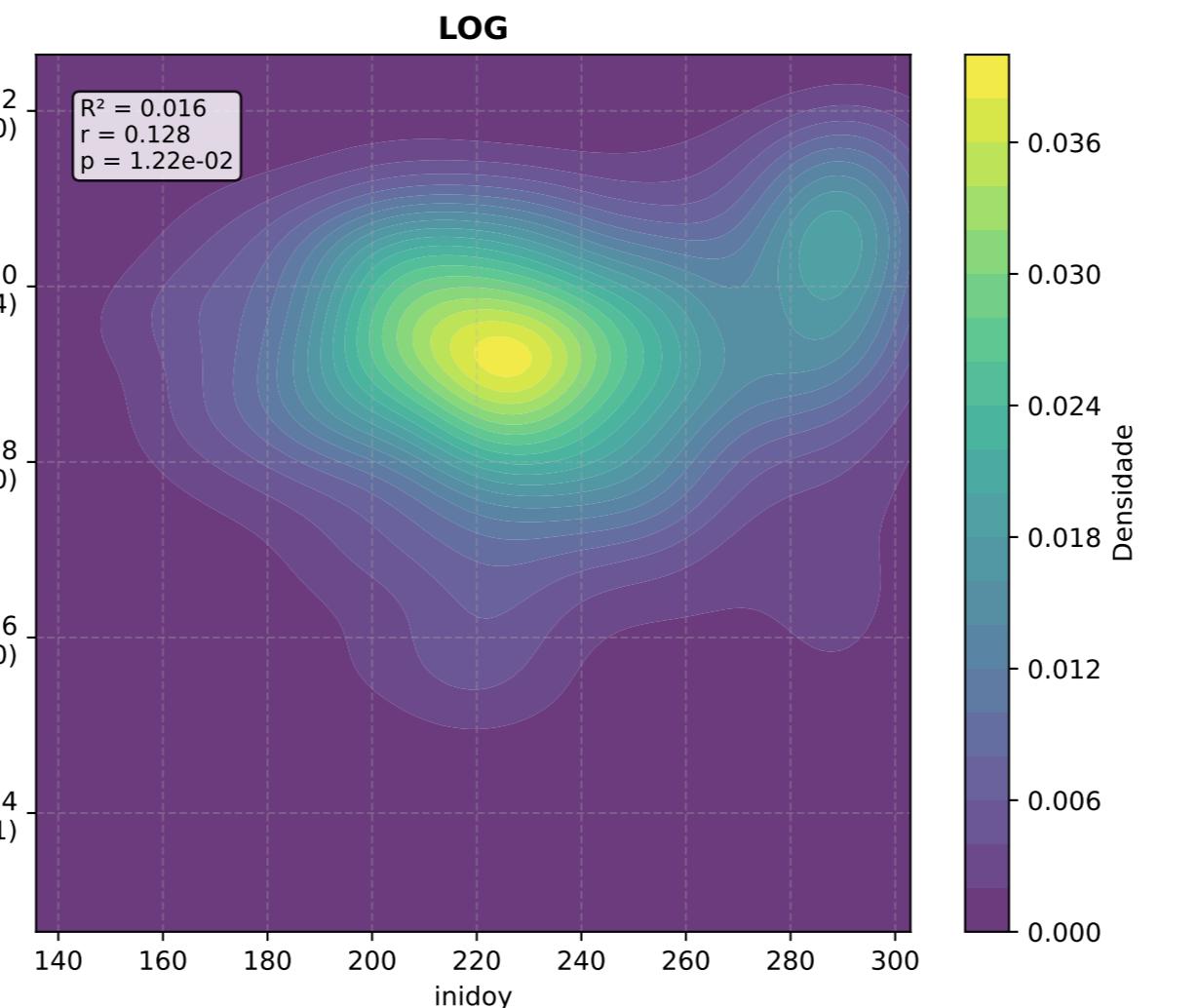
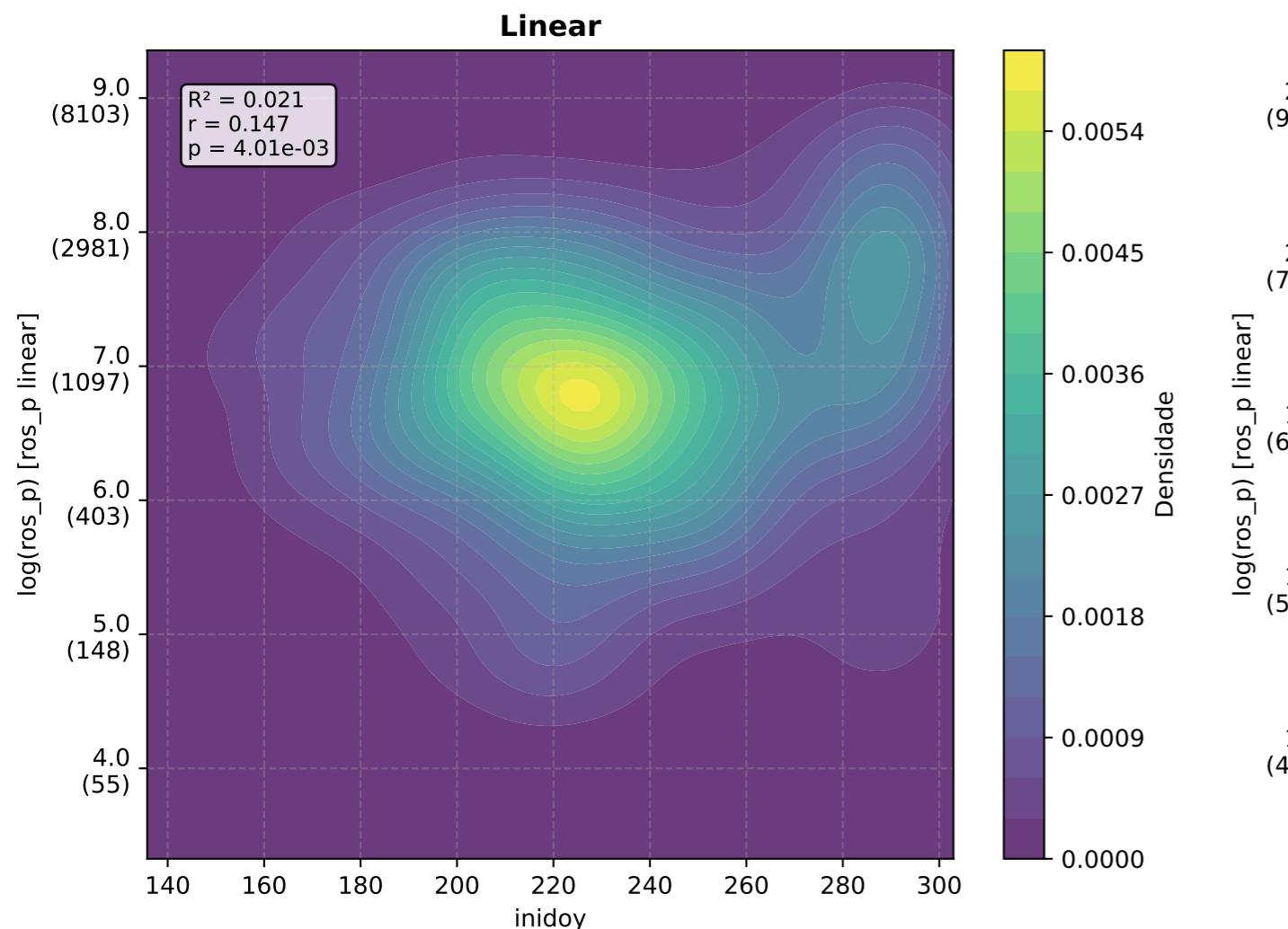
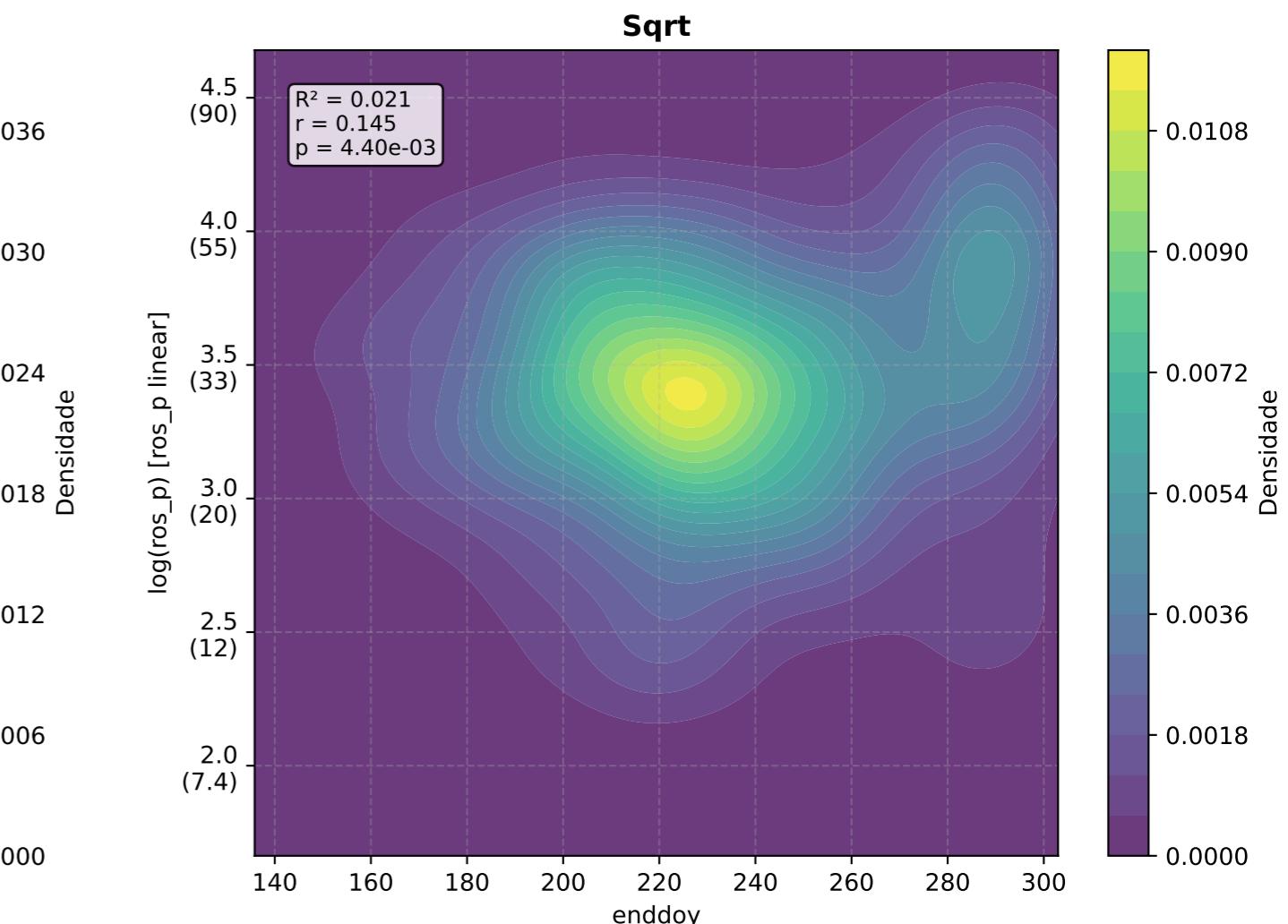
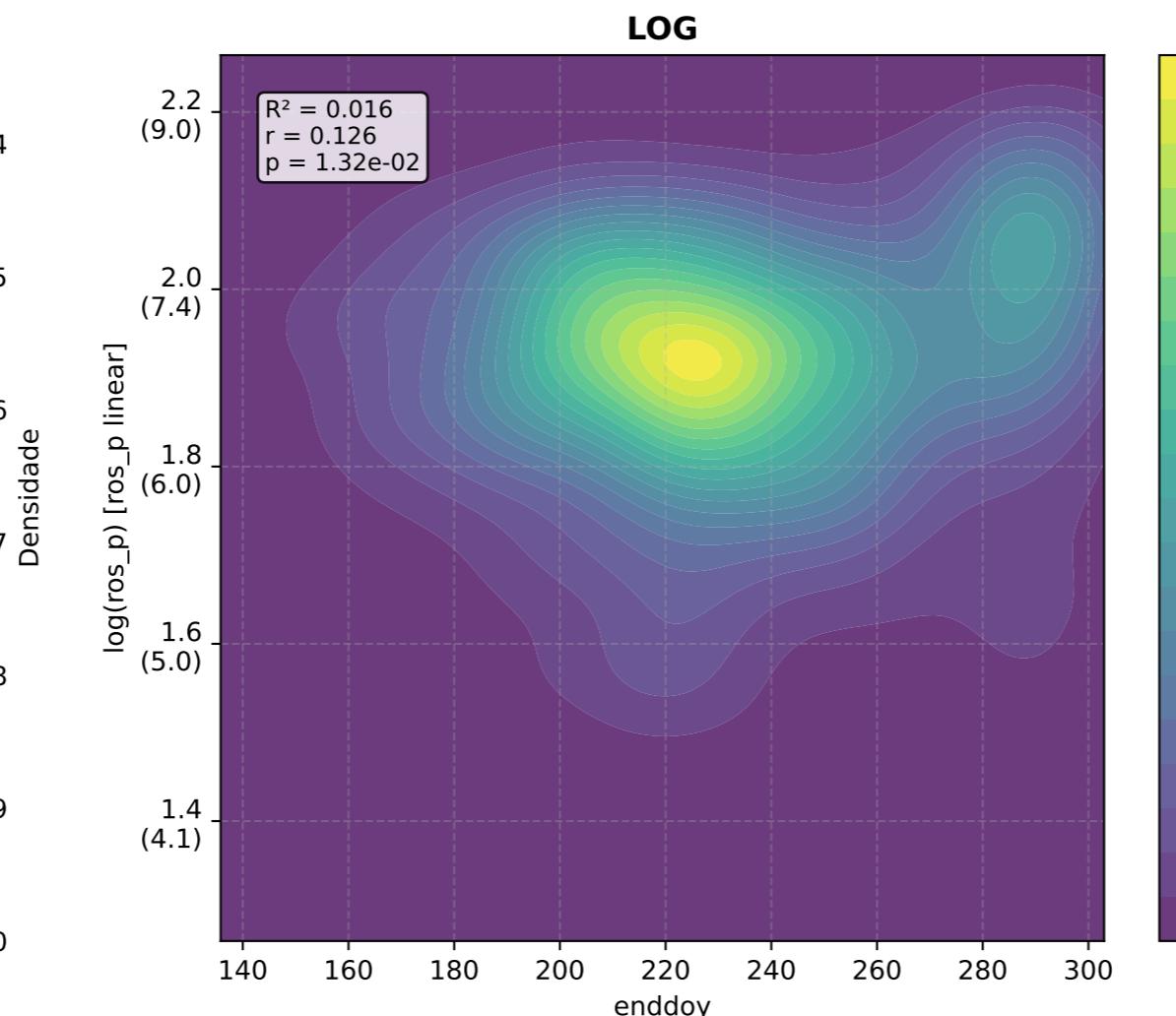
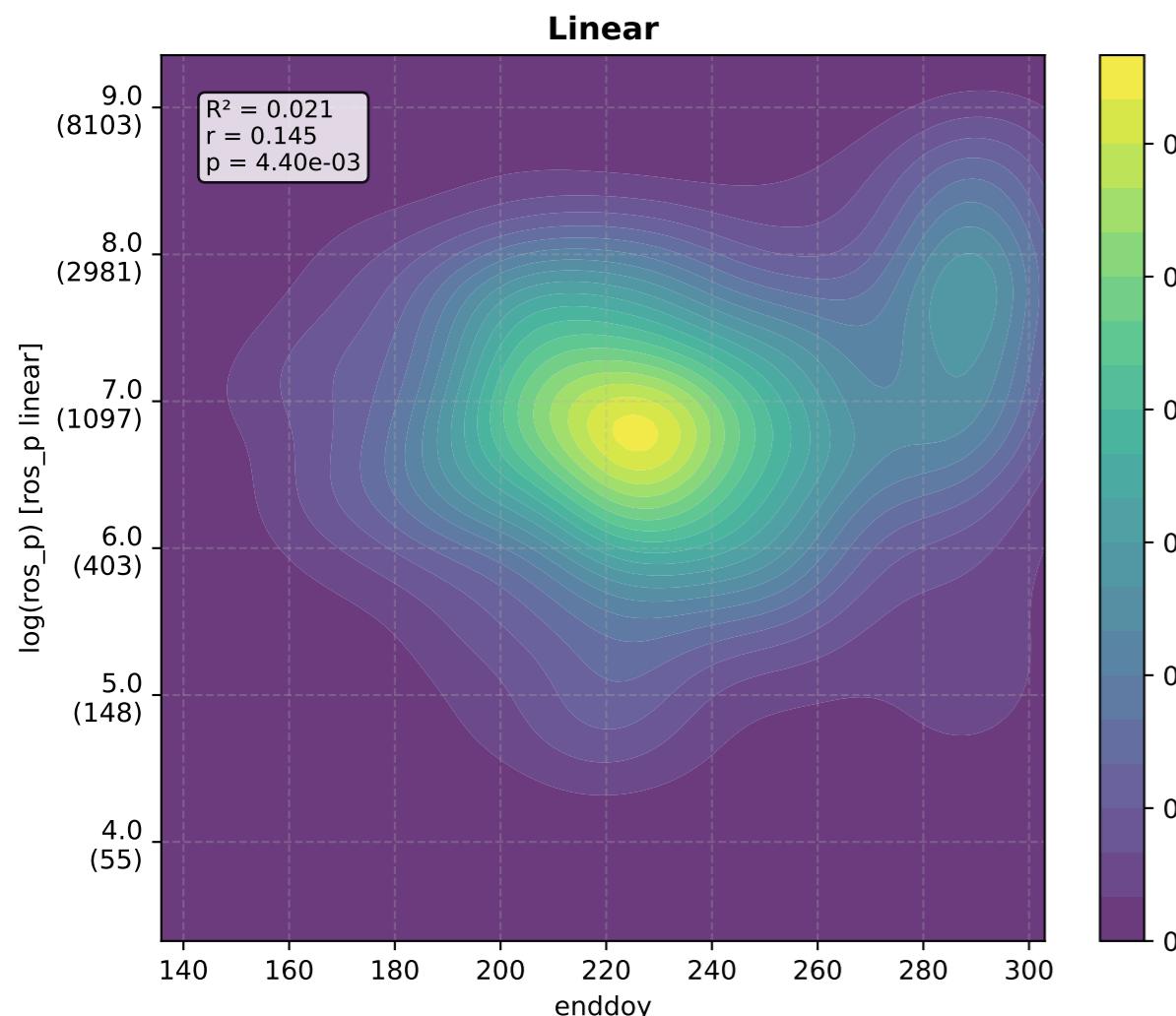


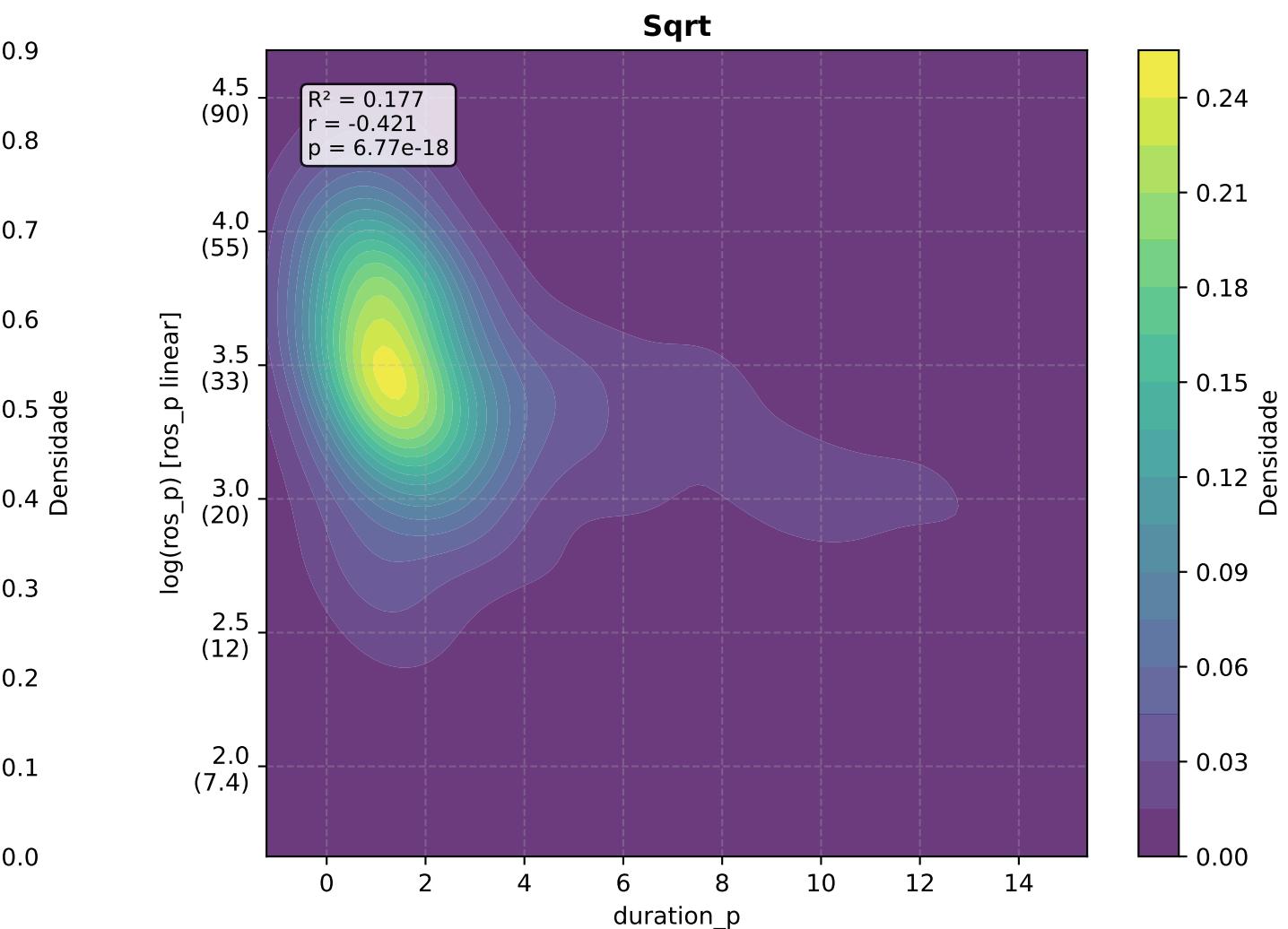
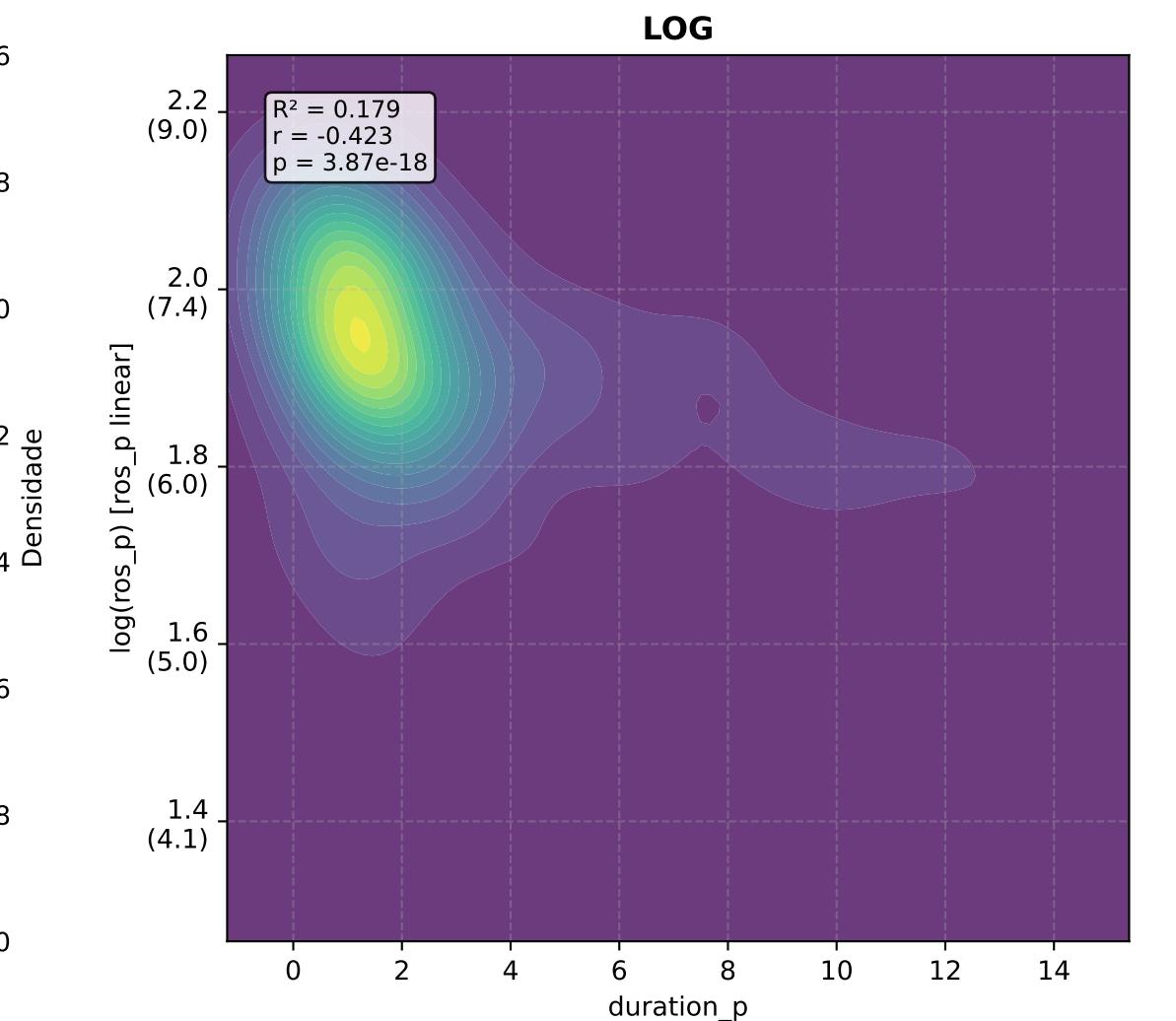
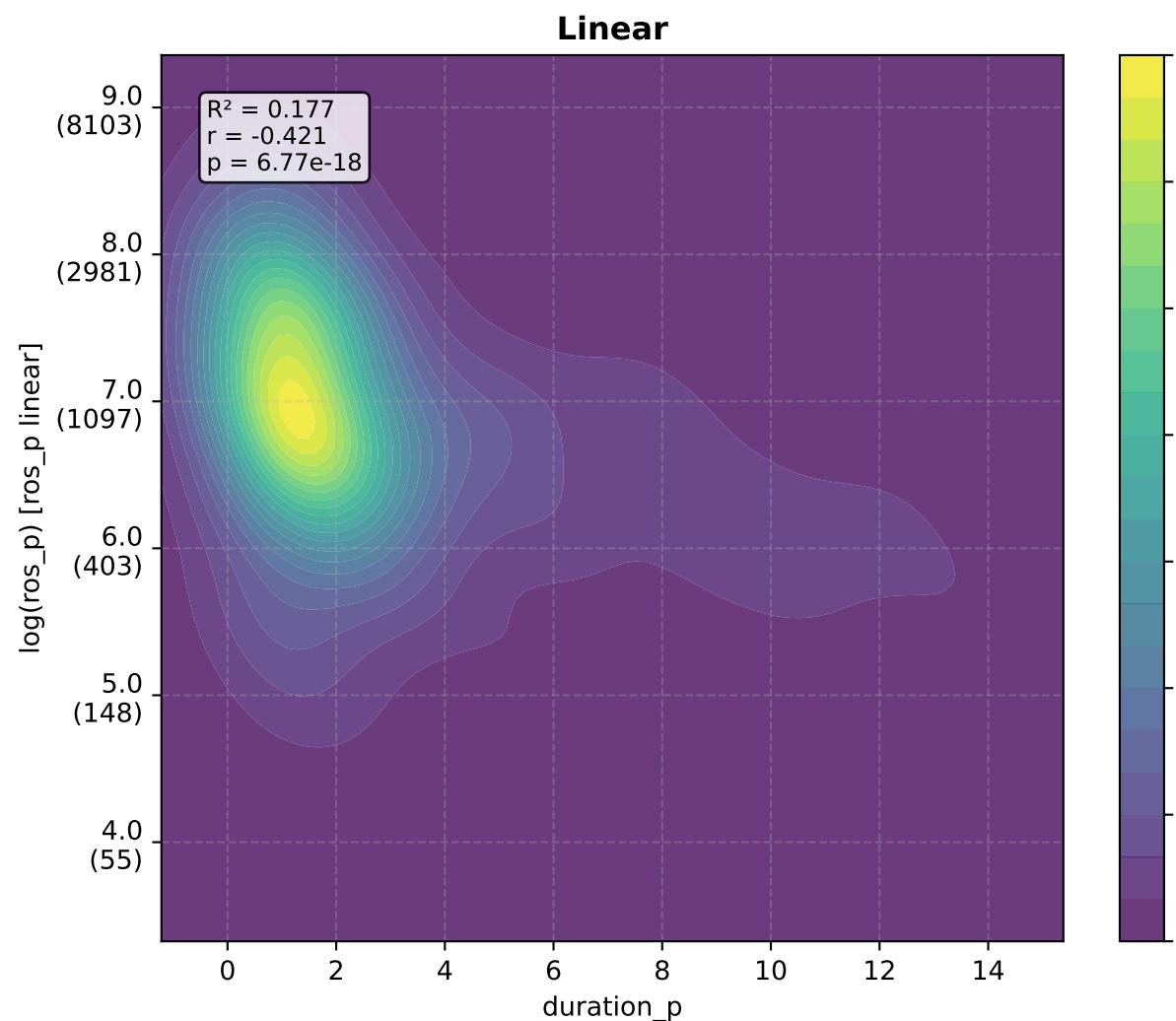
inidoy vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



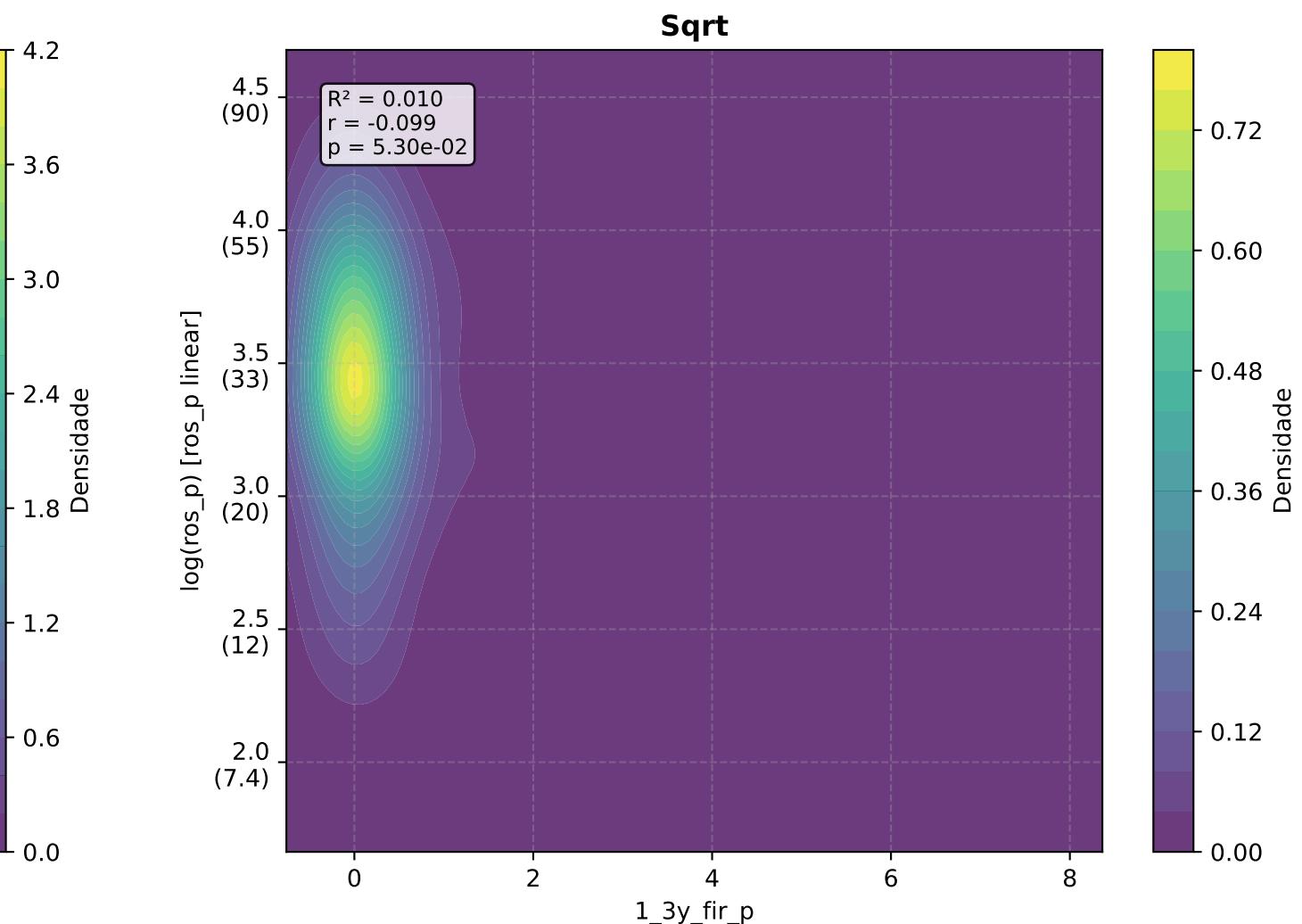
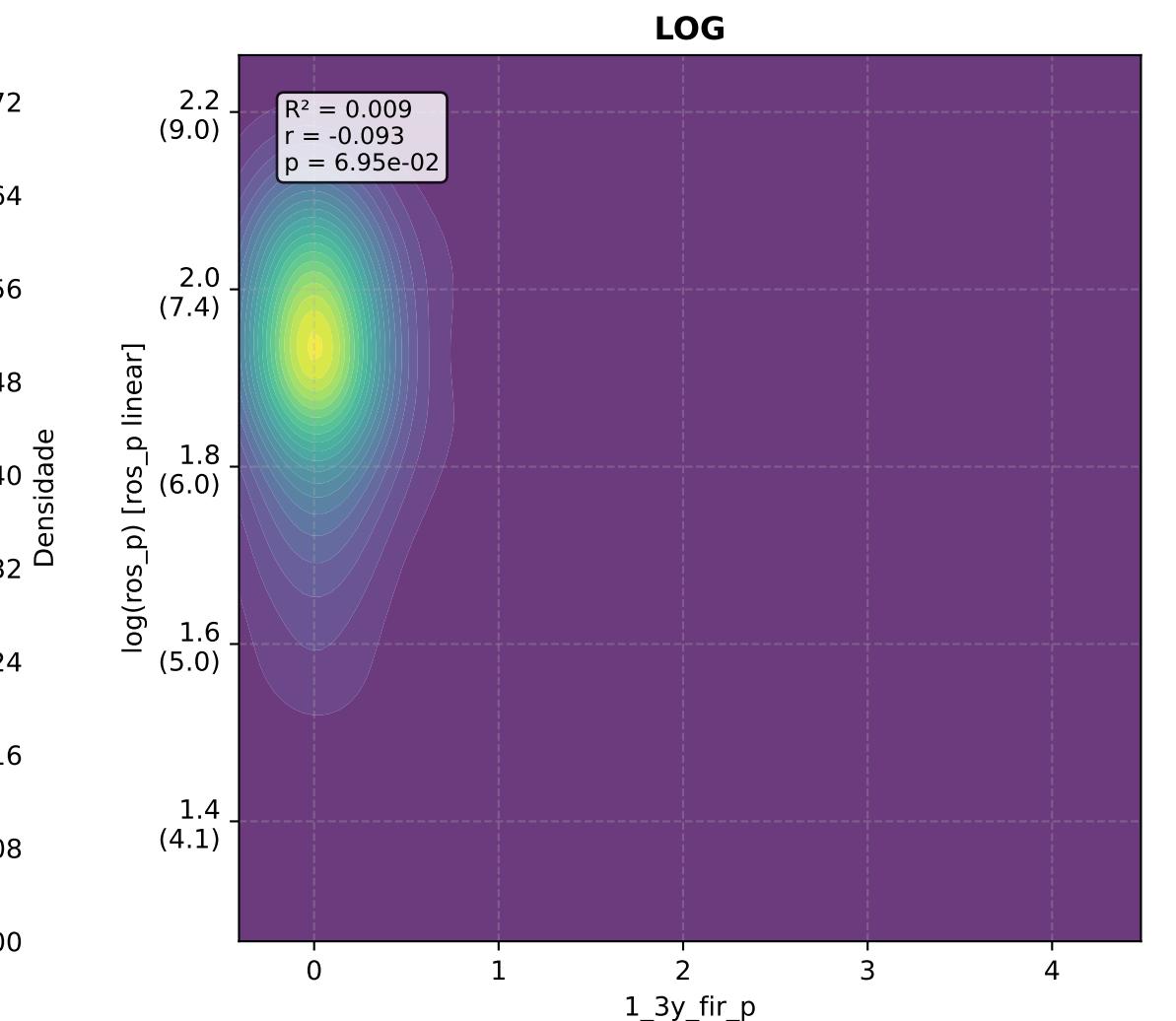
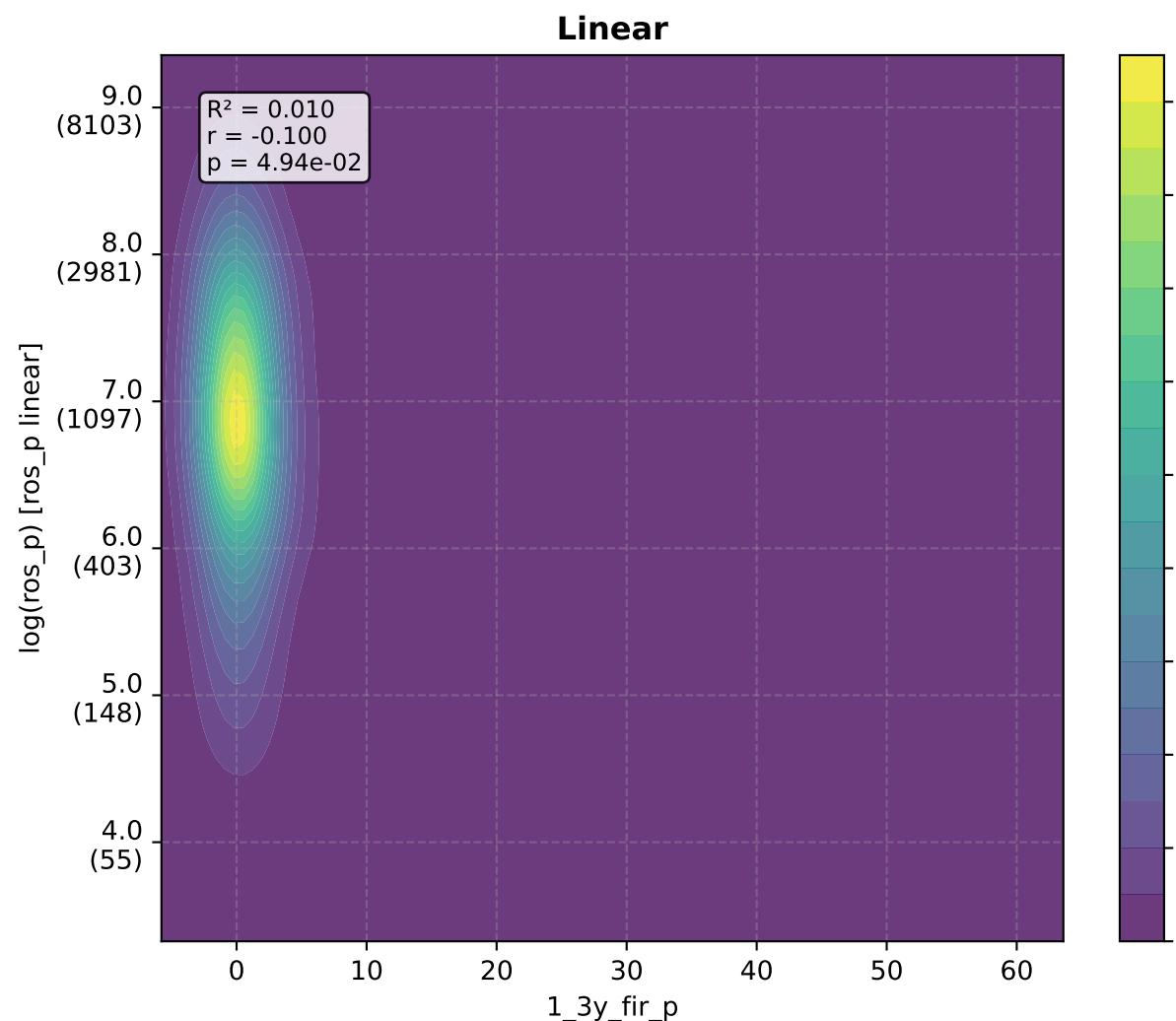
enddoy vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



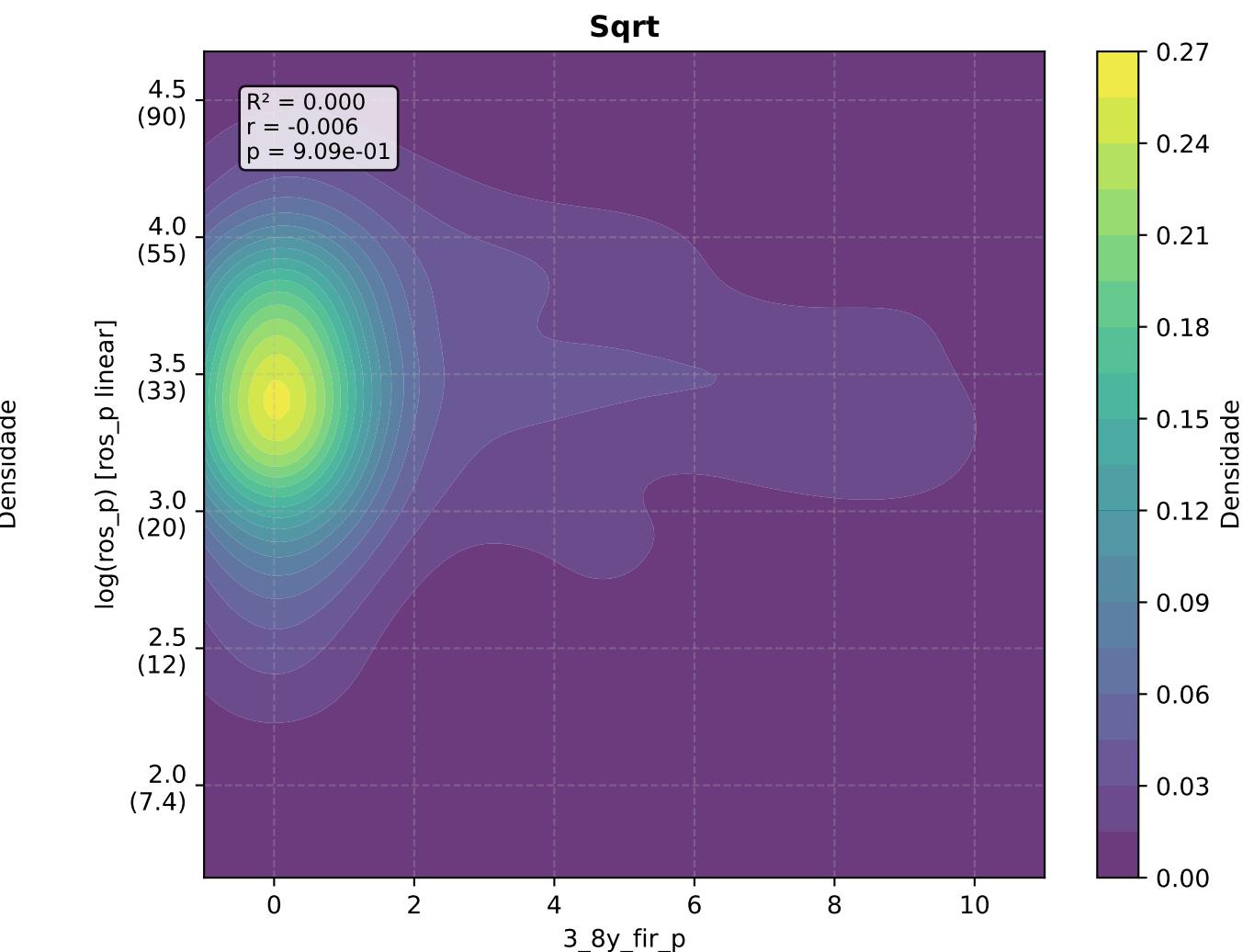
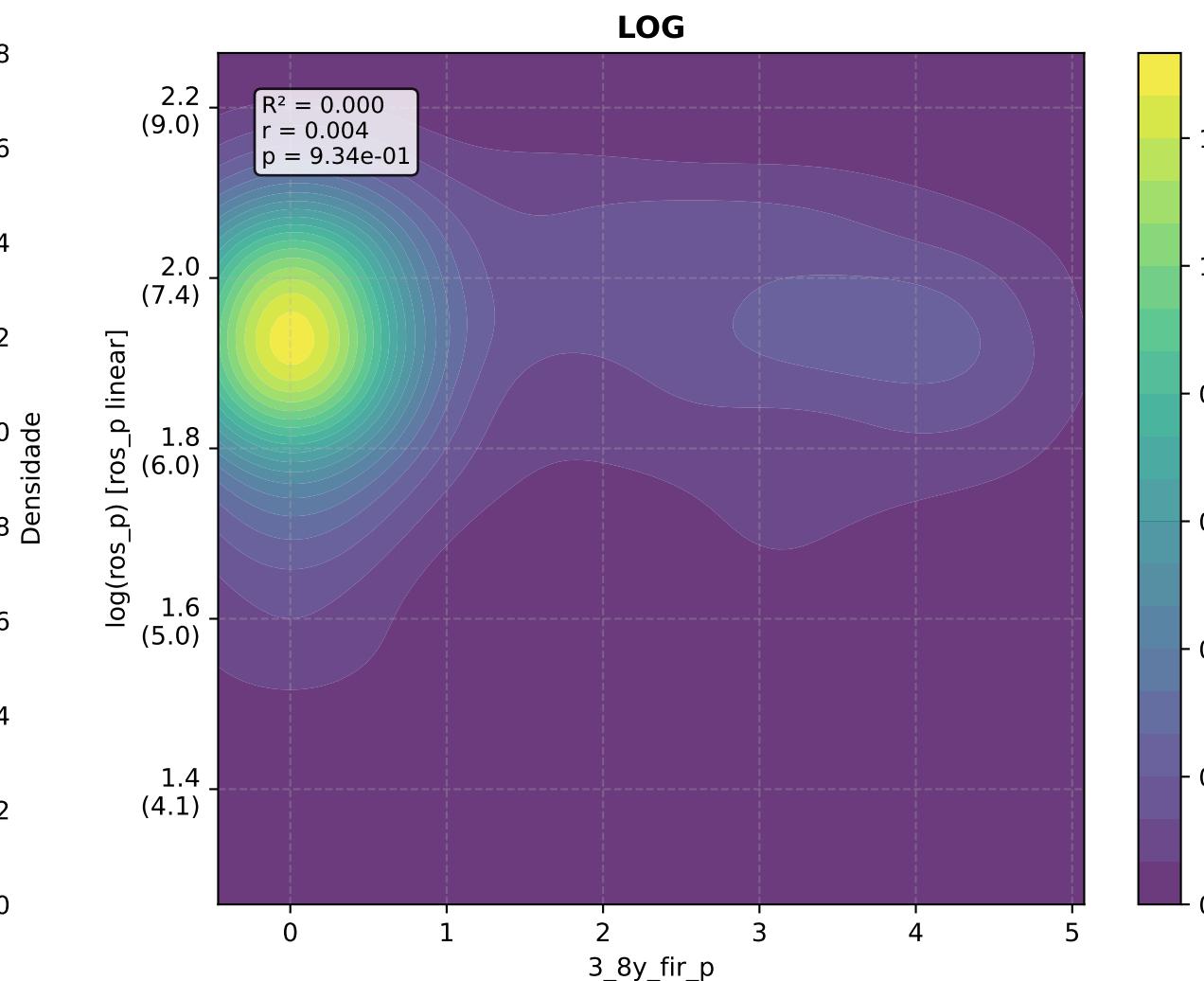
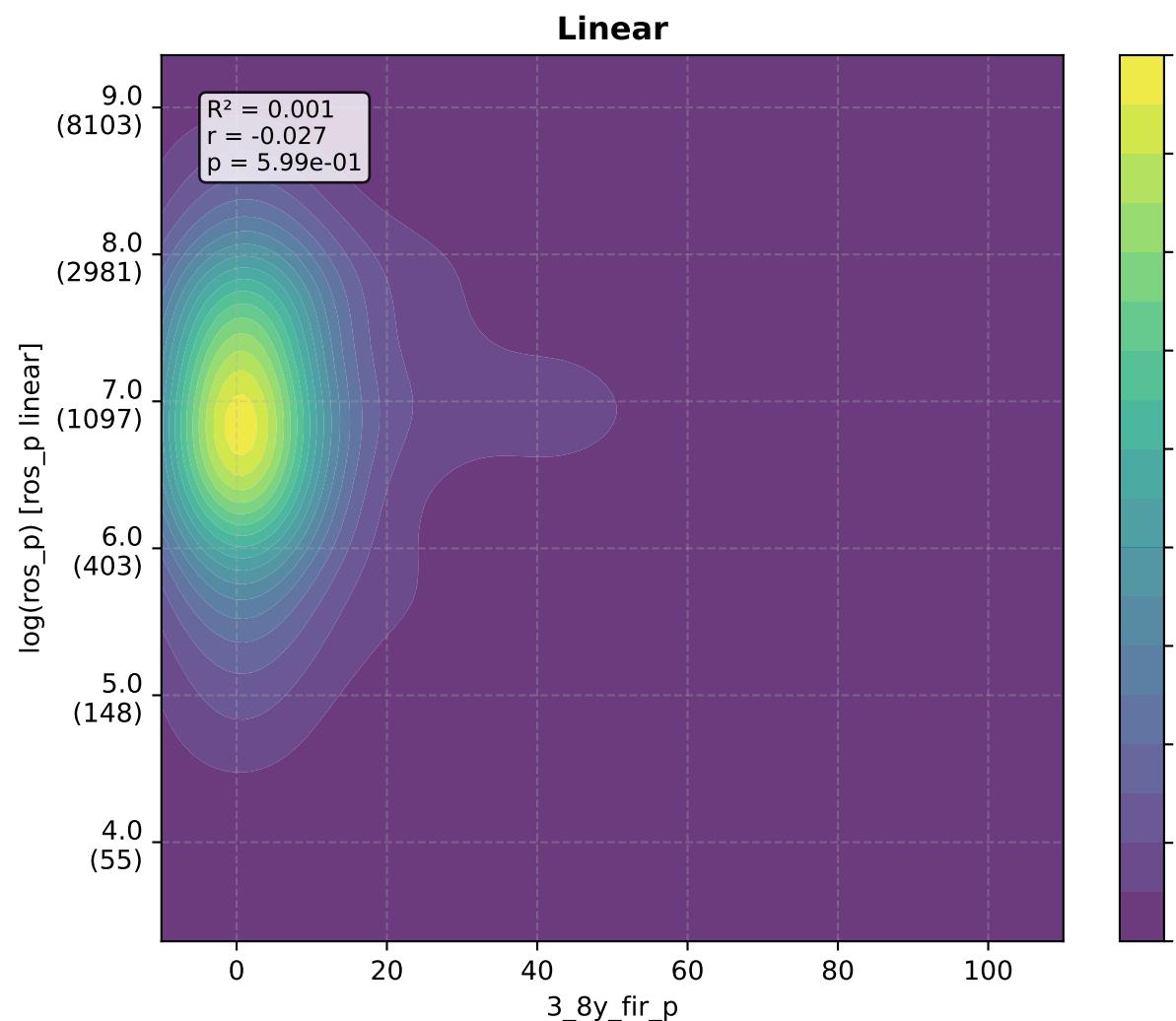
duration_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



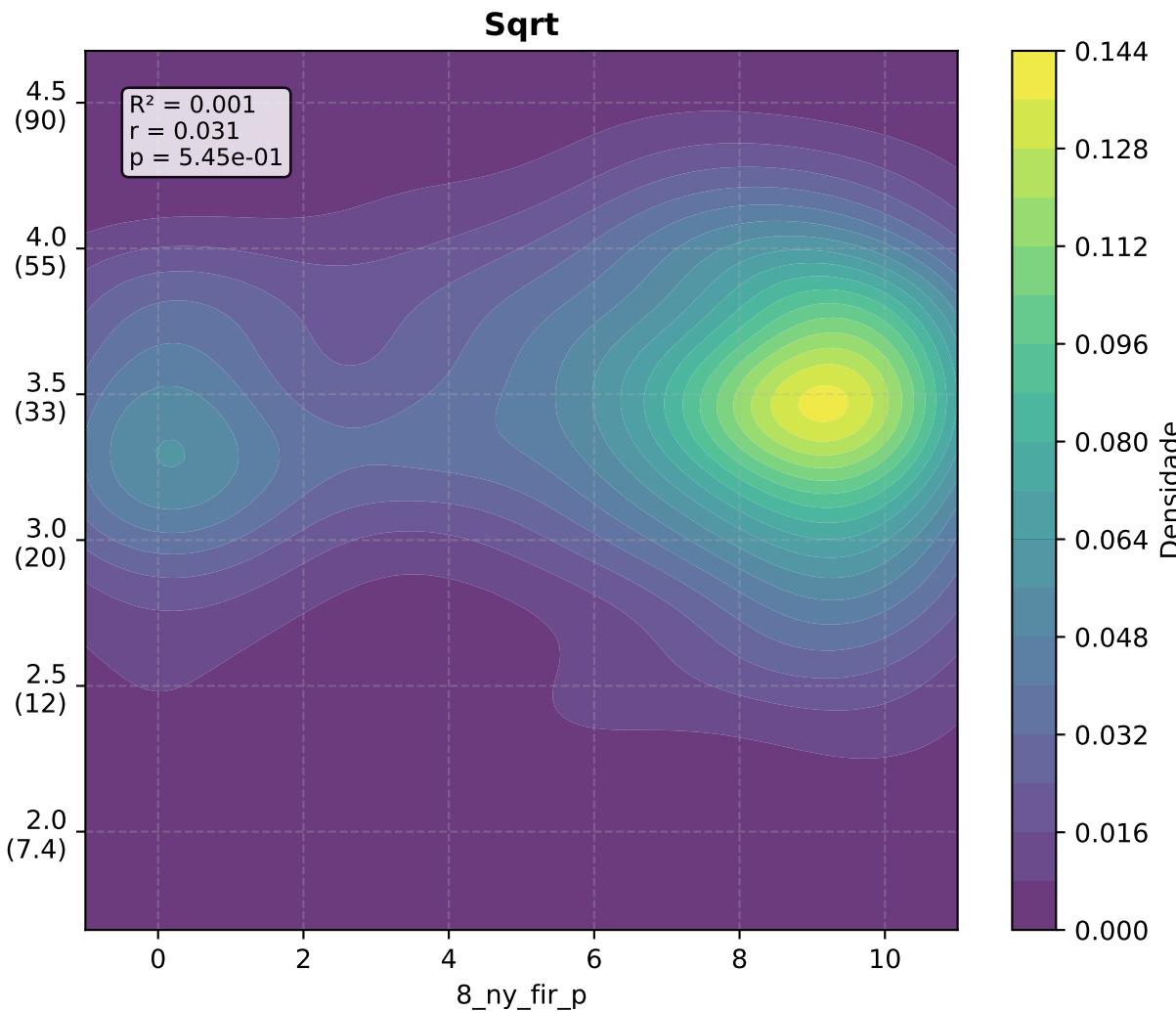
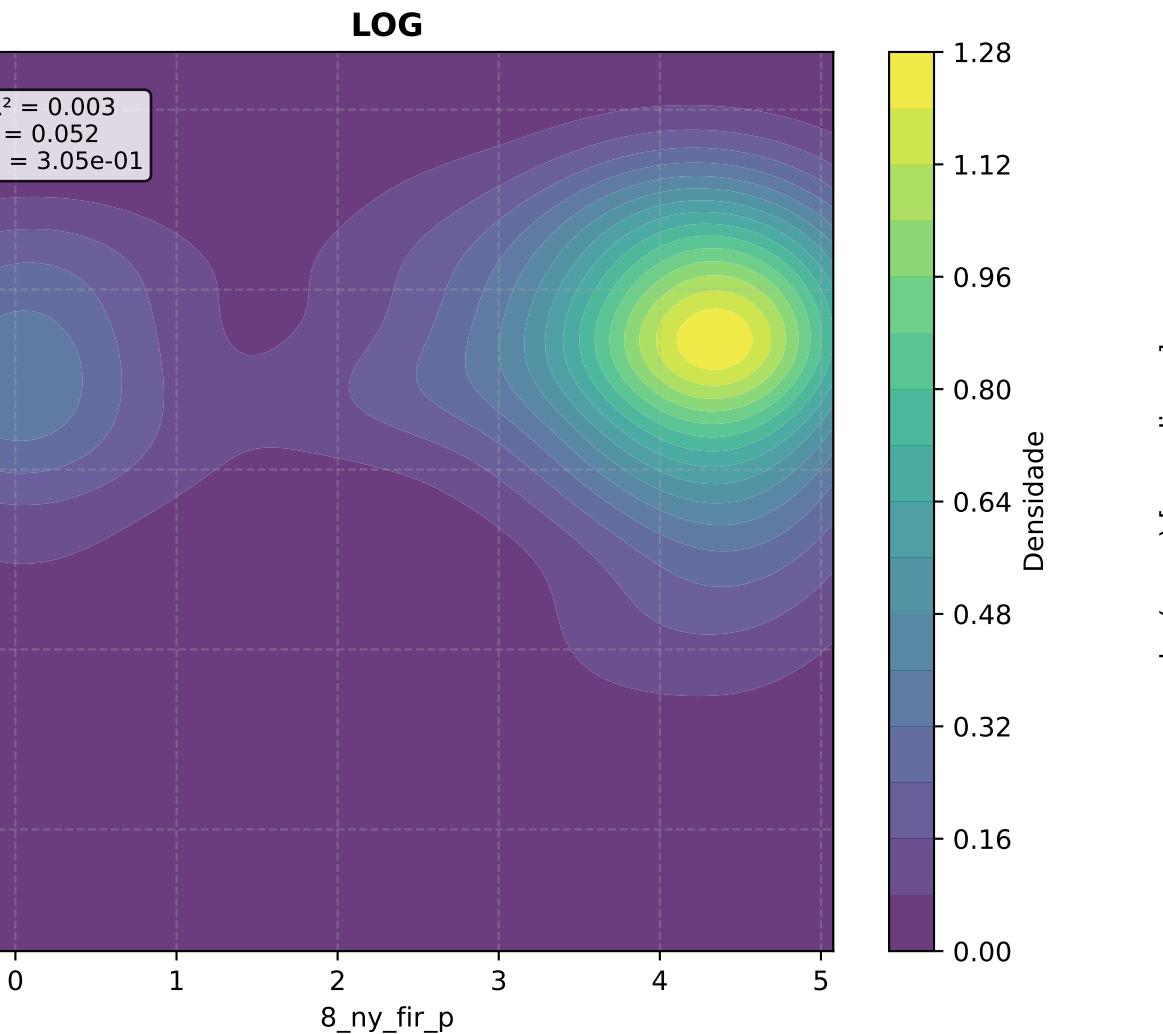
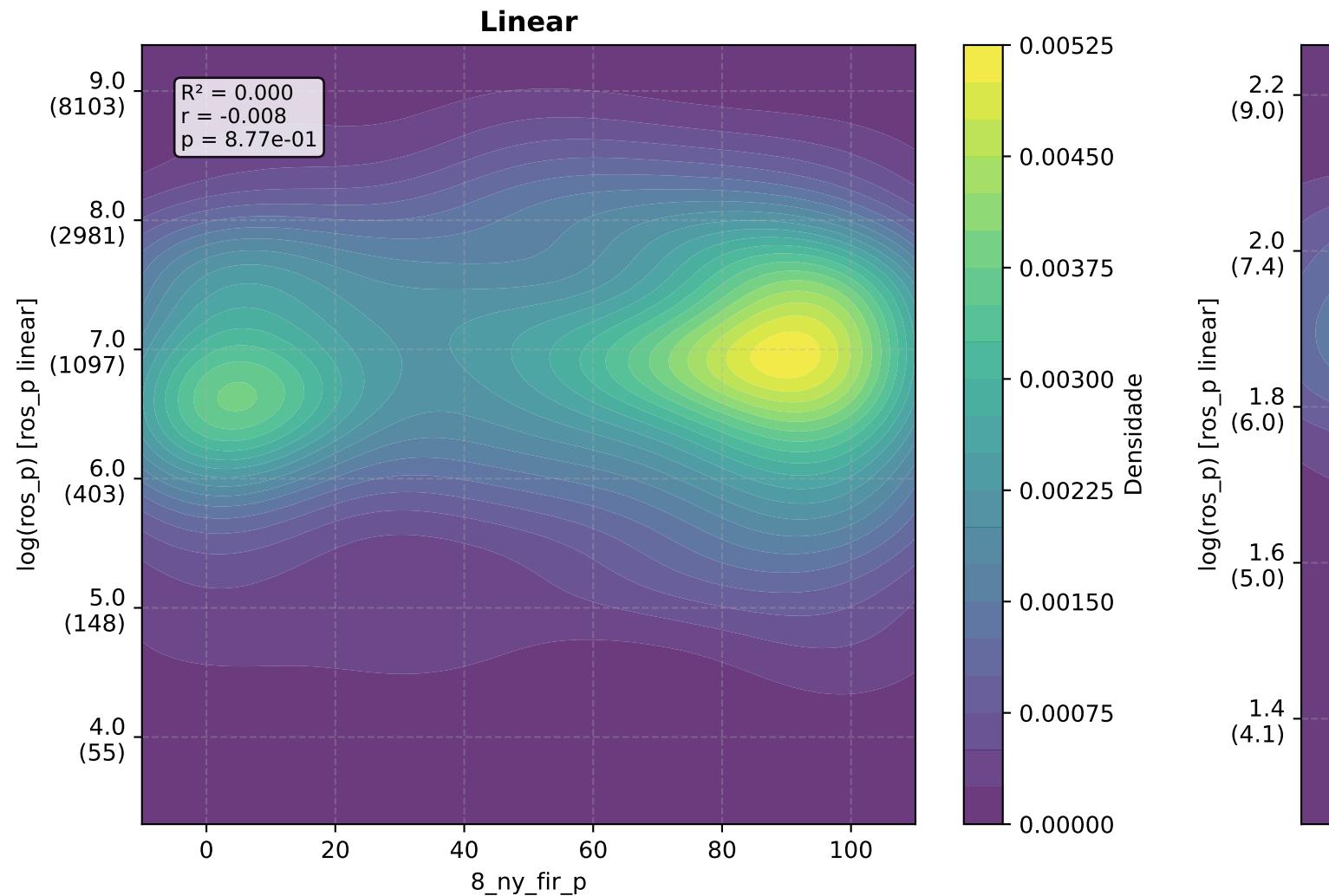
1_3y_fir_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



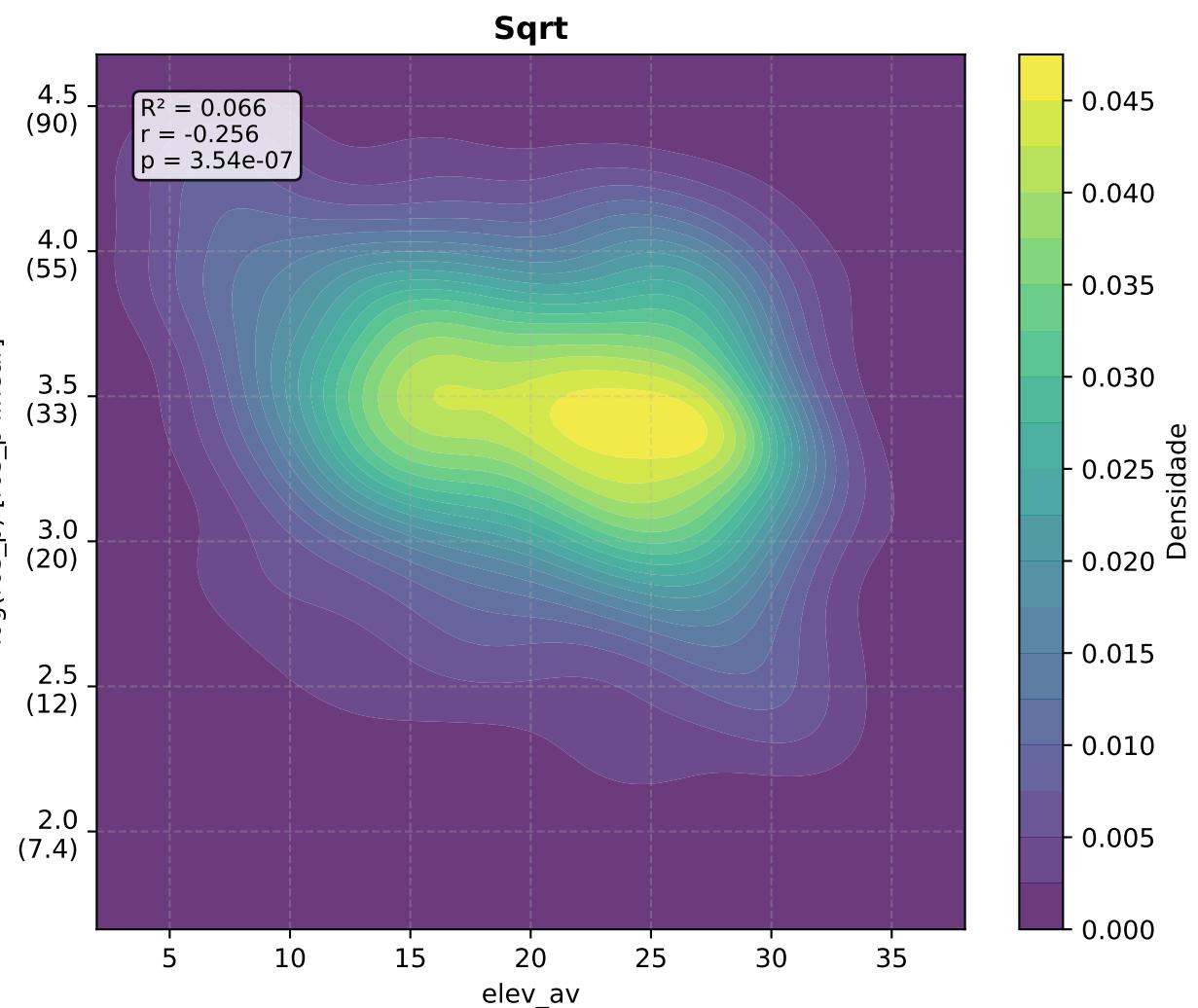
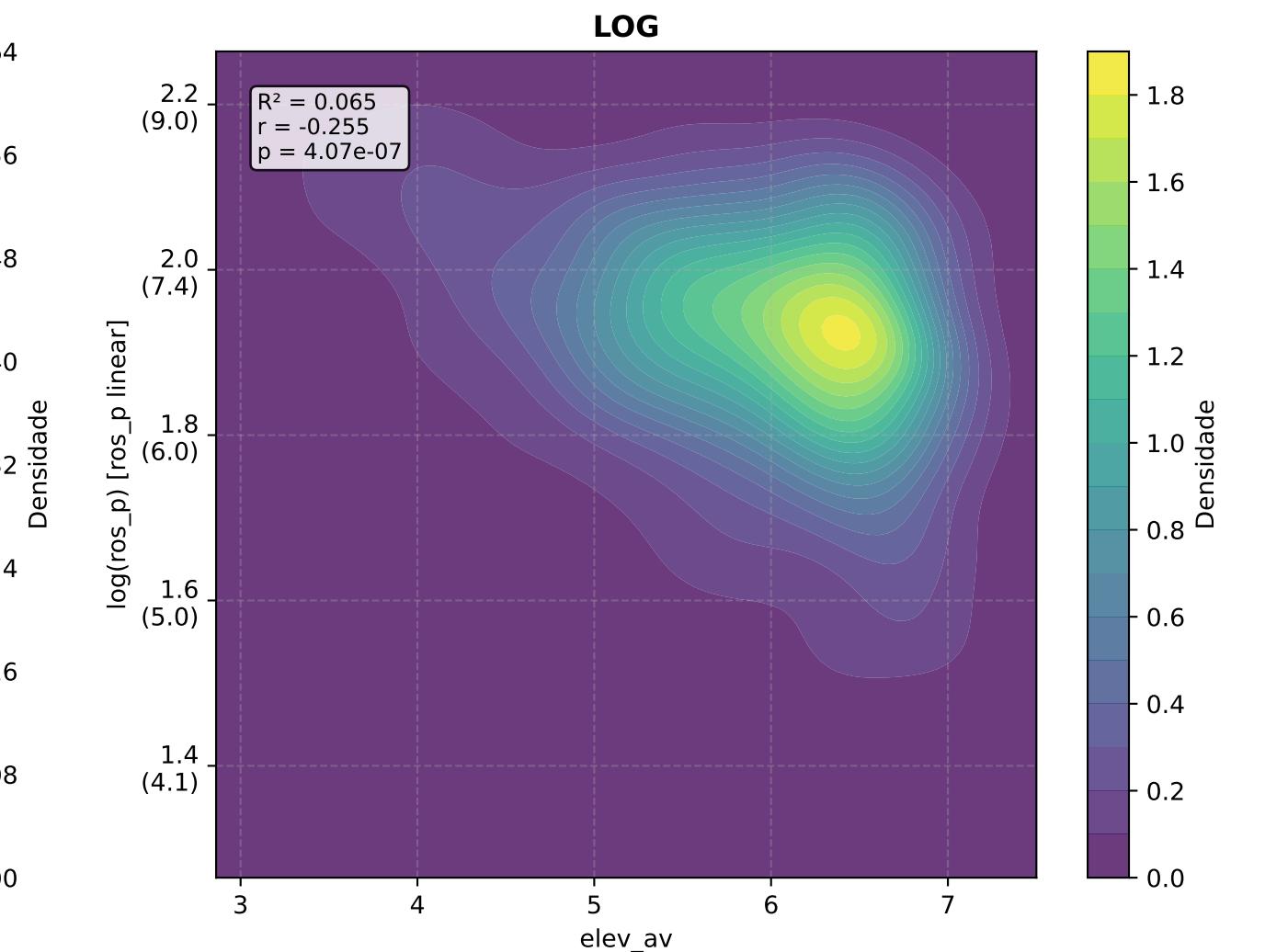
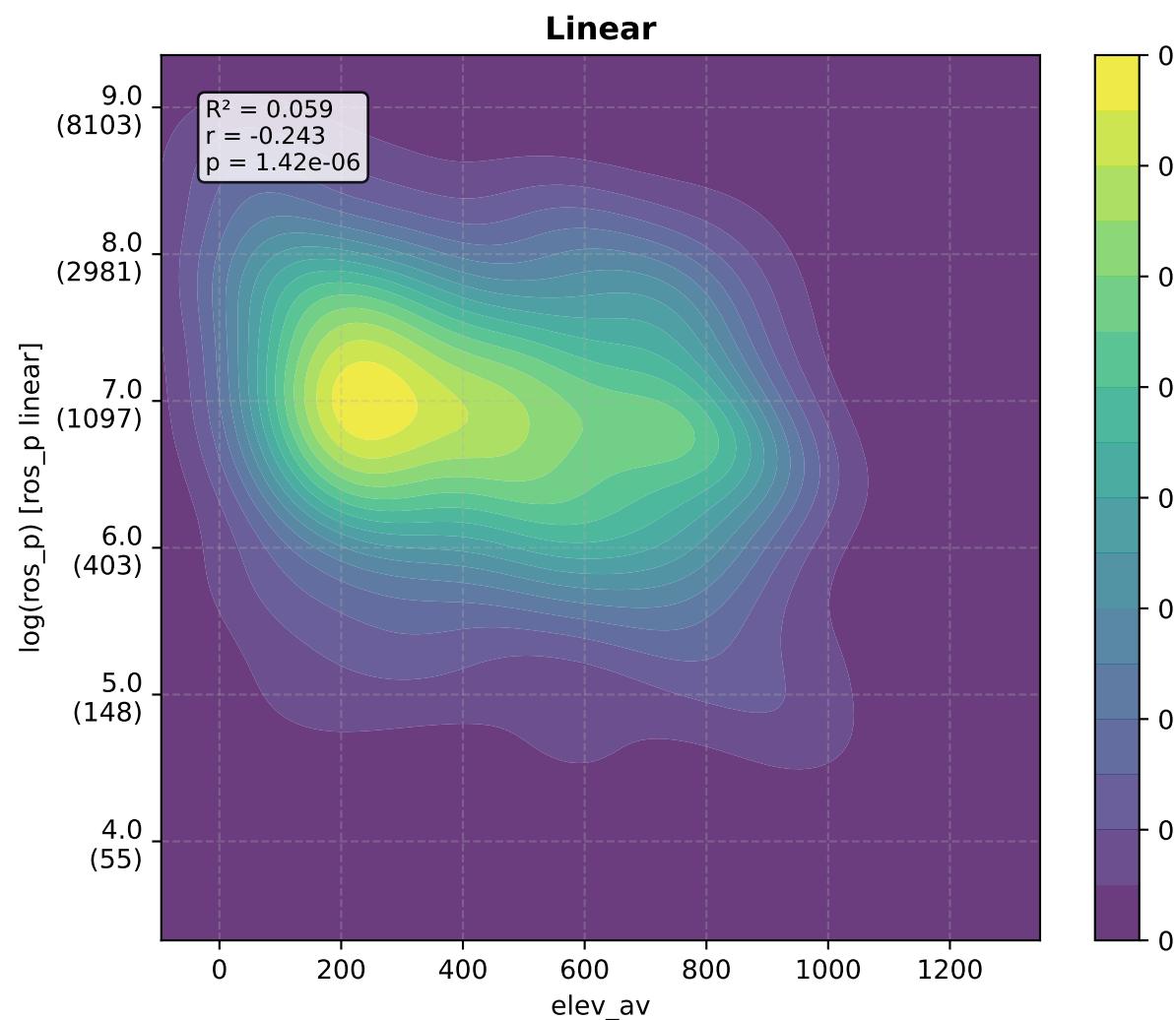
3_8y_fir_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



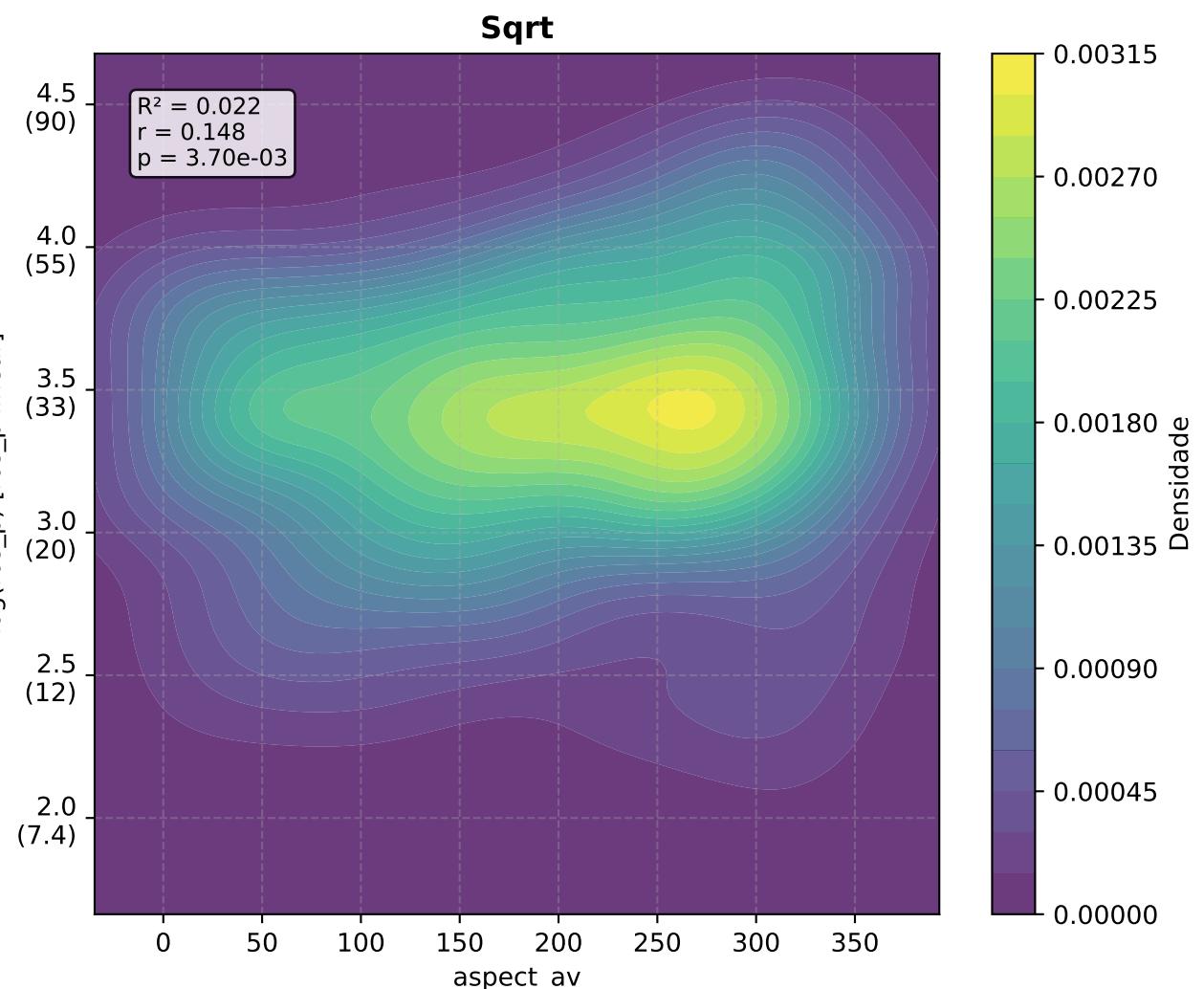
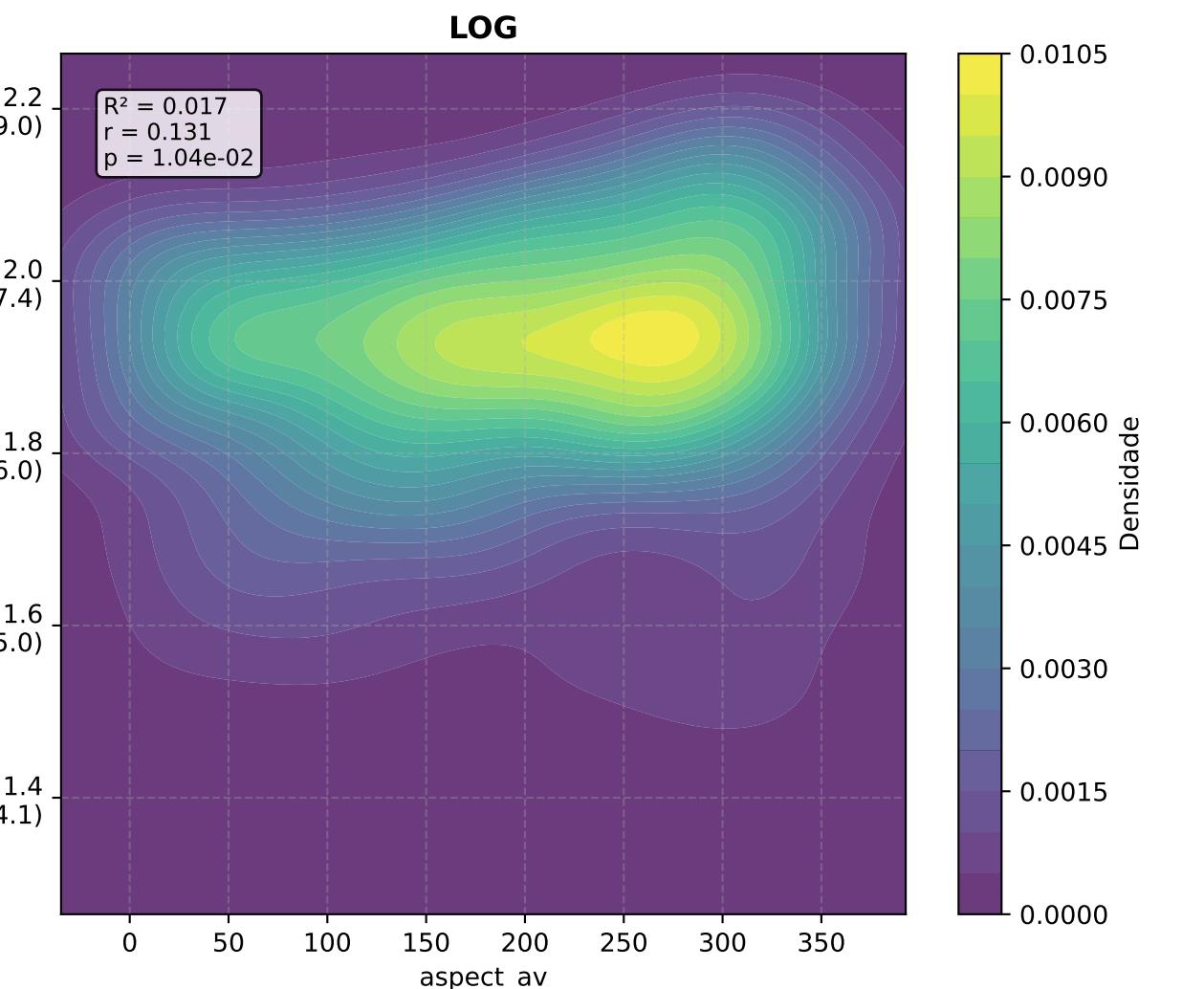
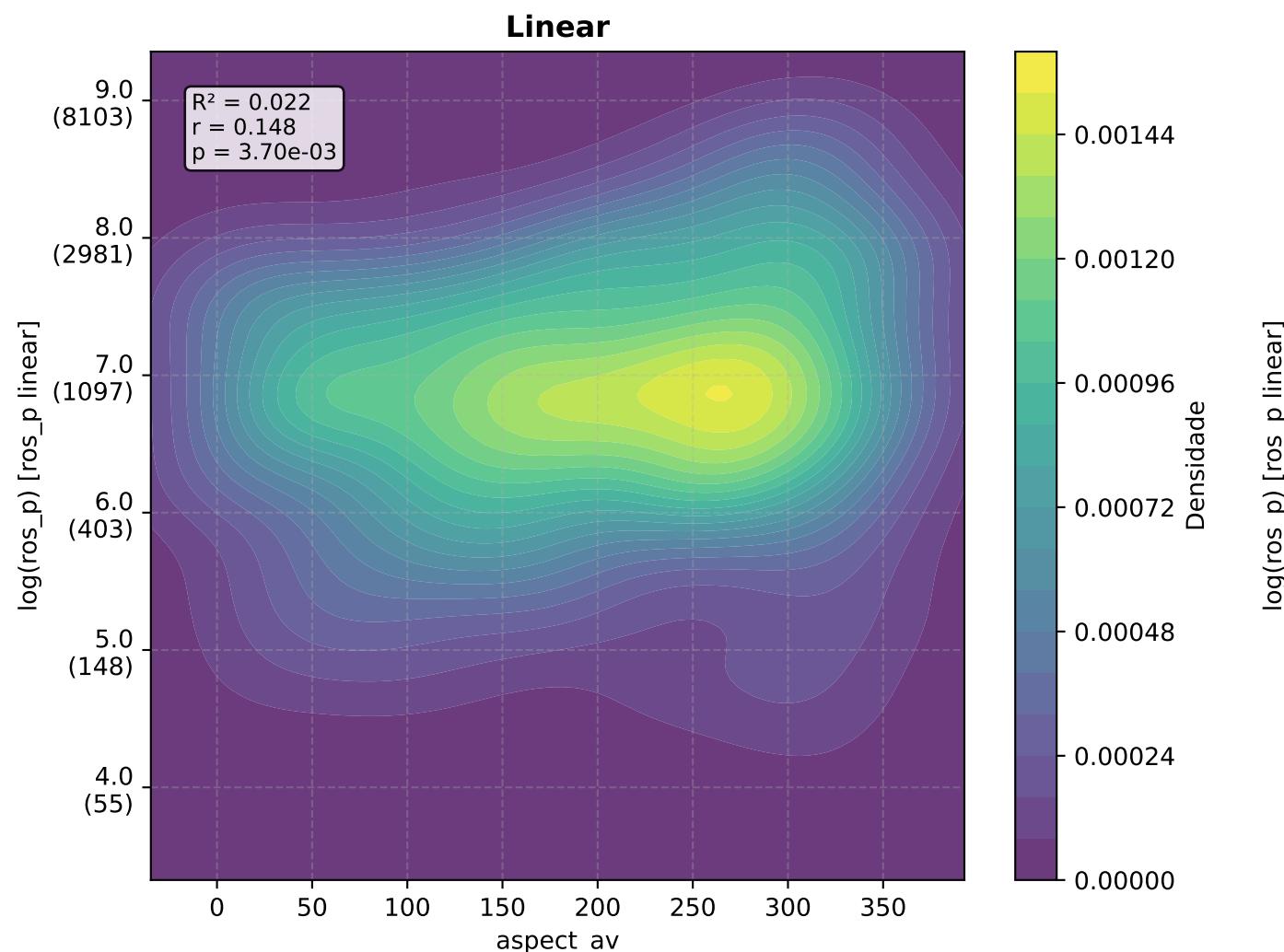
8_ny_fir_p vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



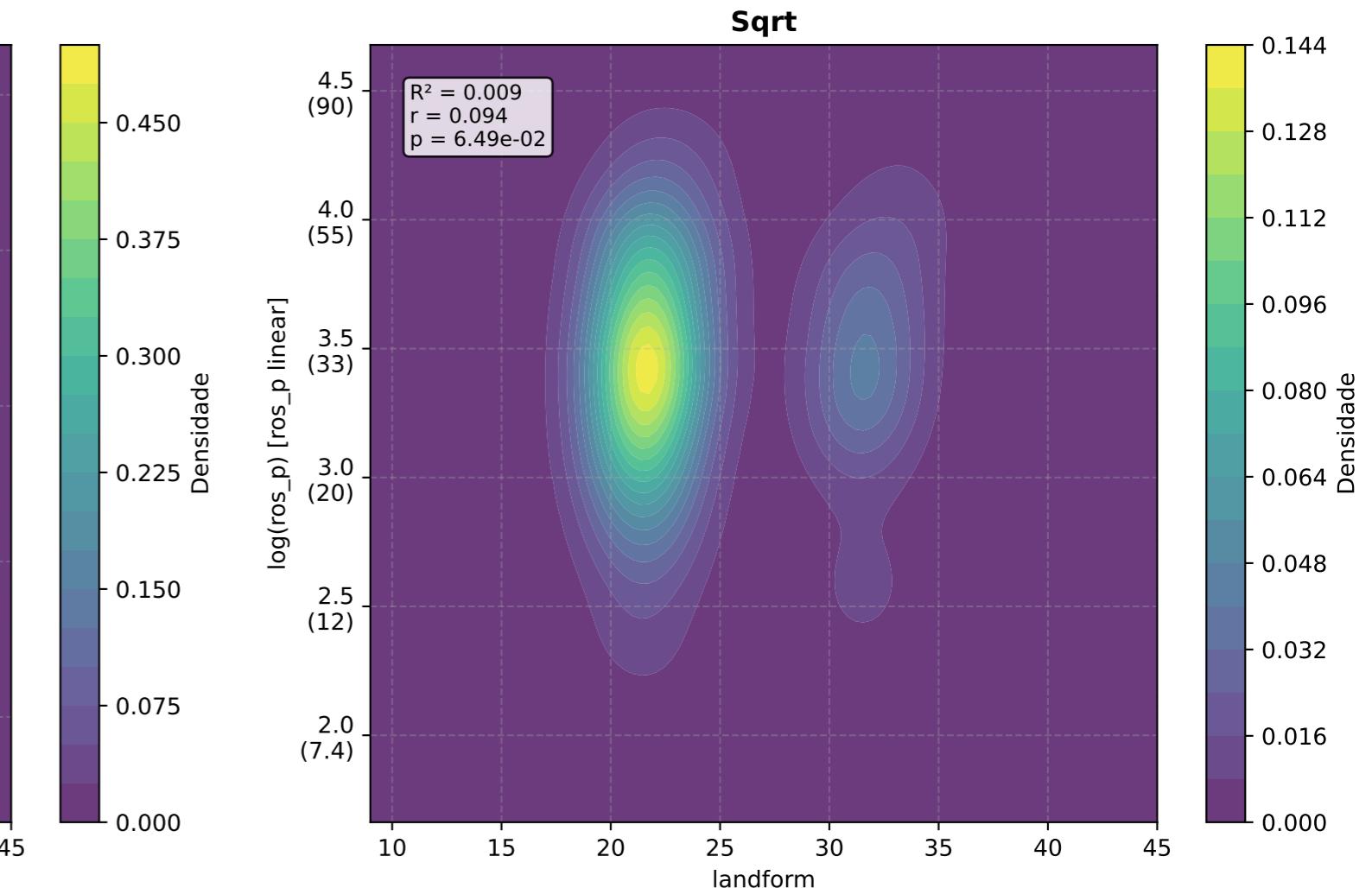
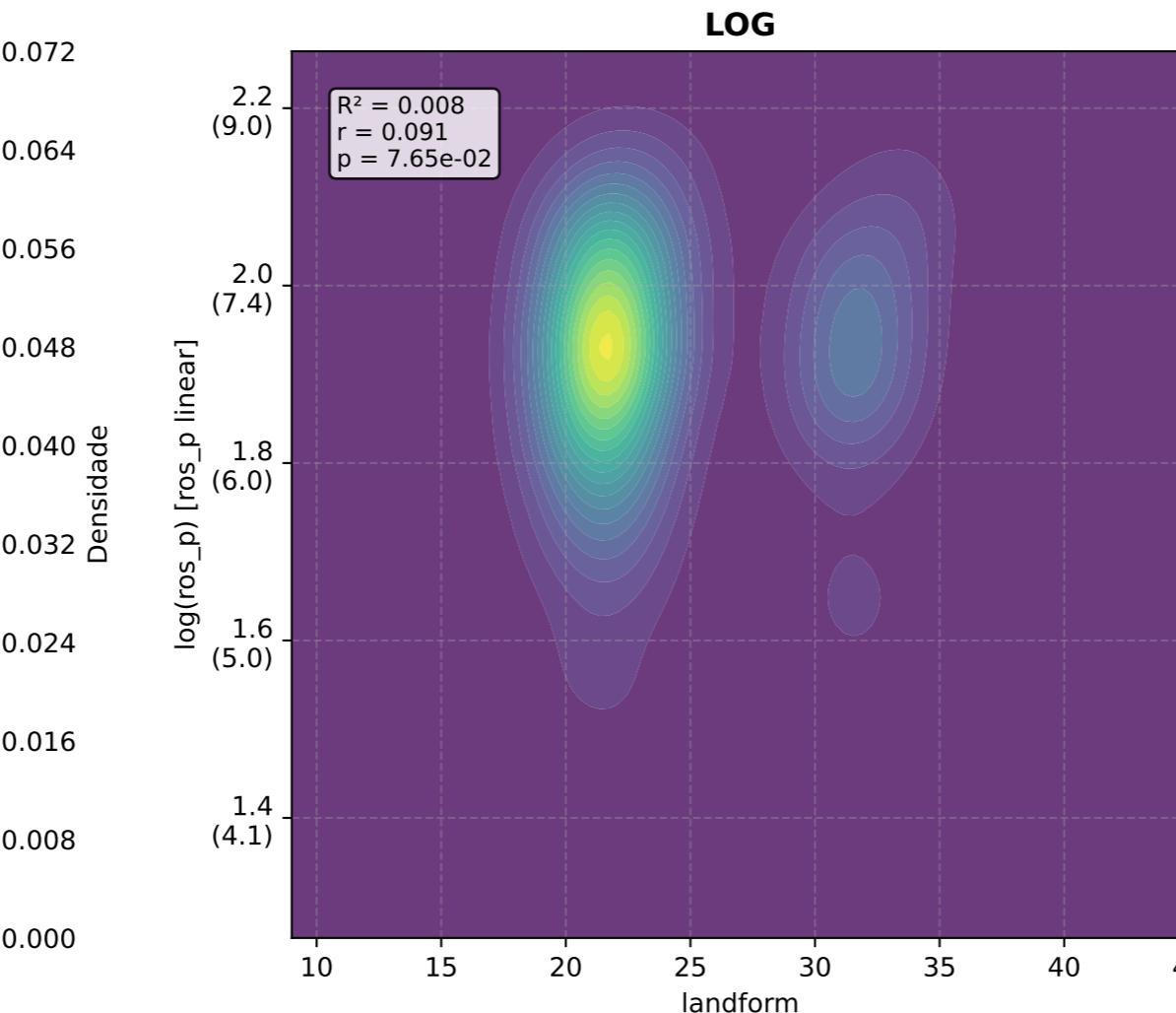
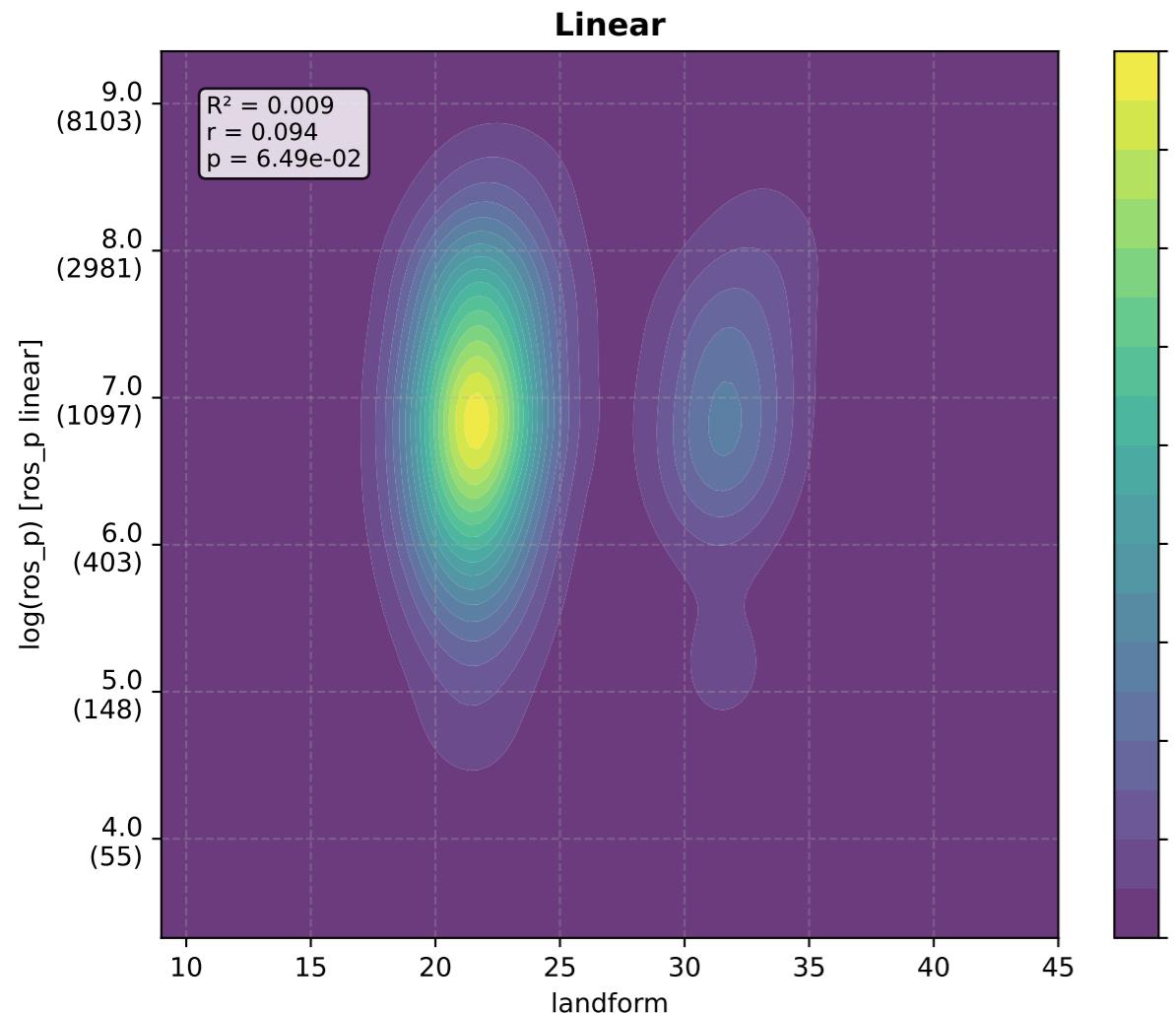
elev_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



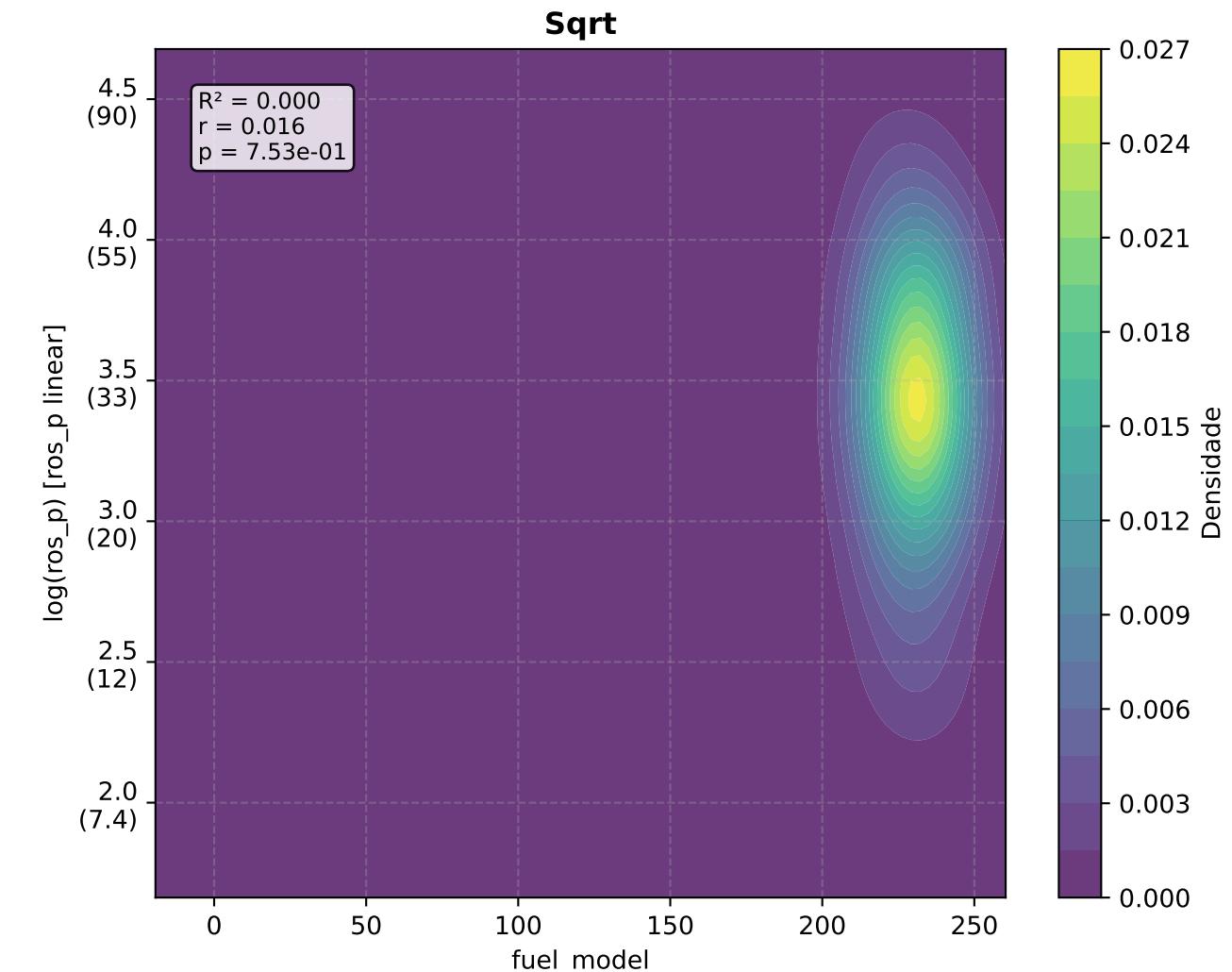
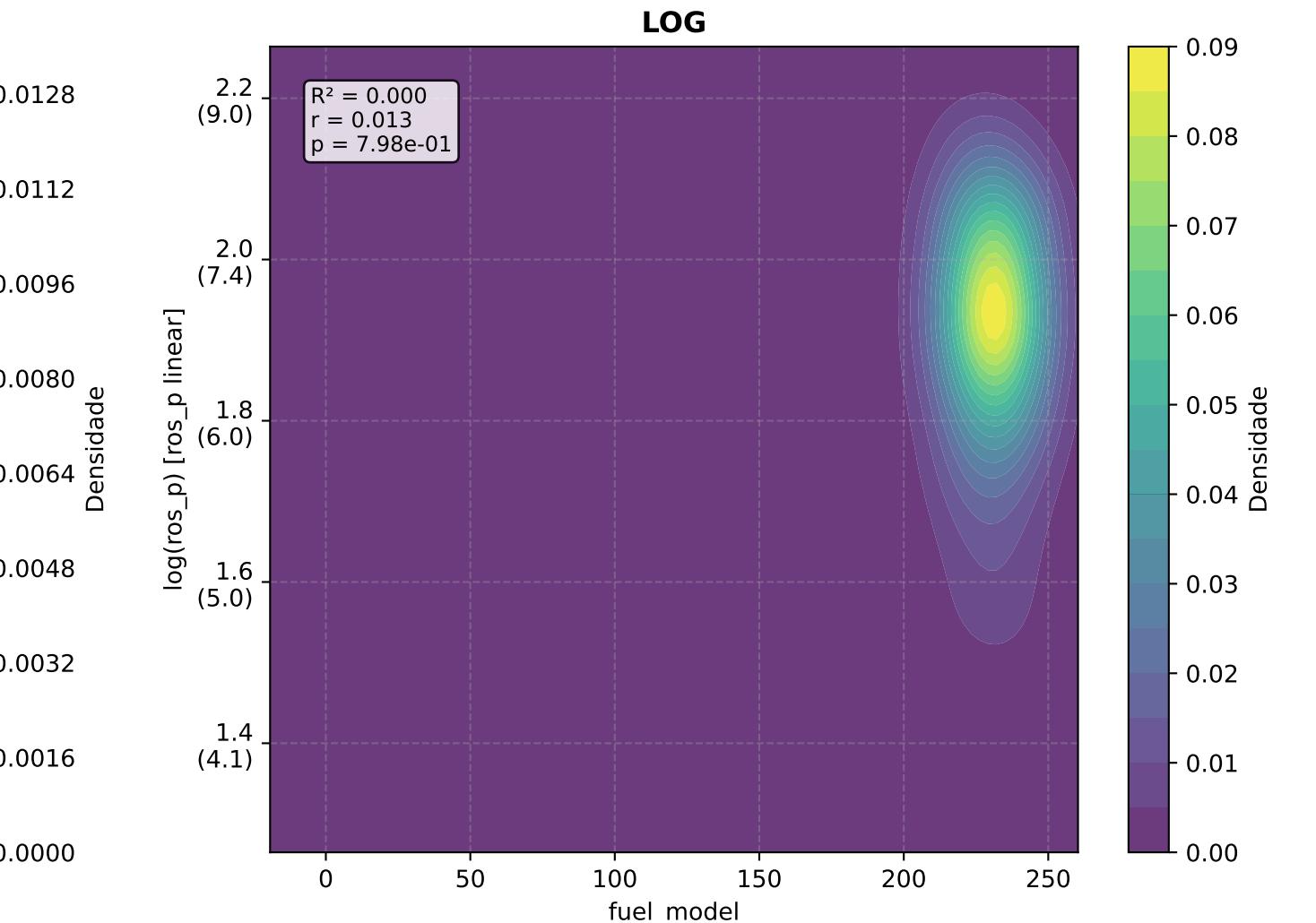
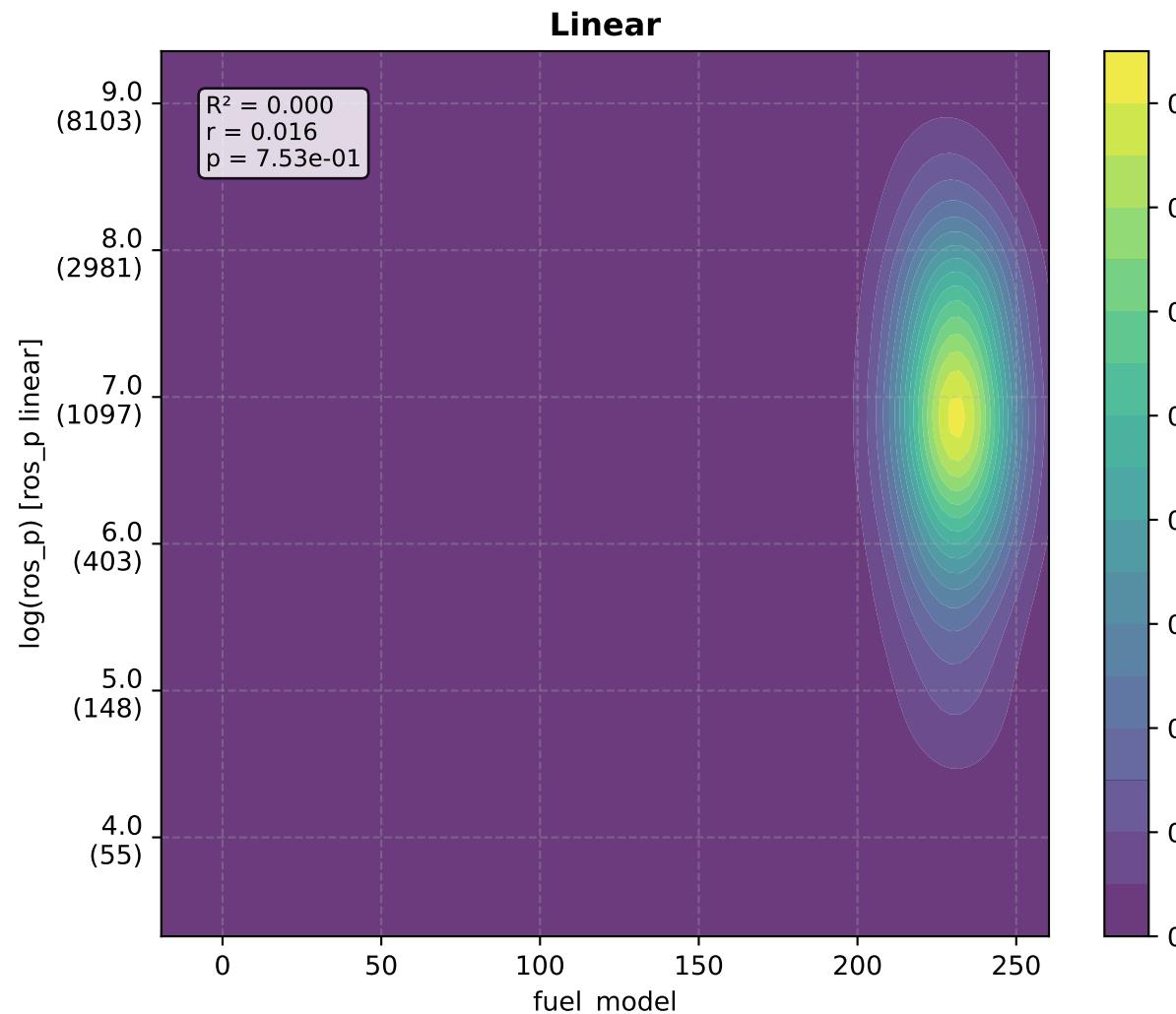
aspect_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



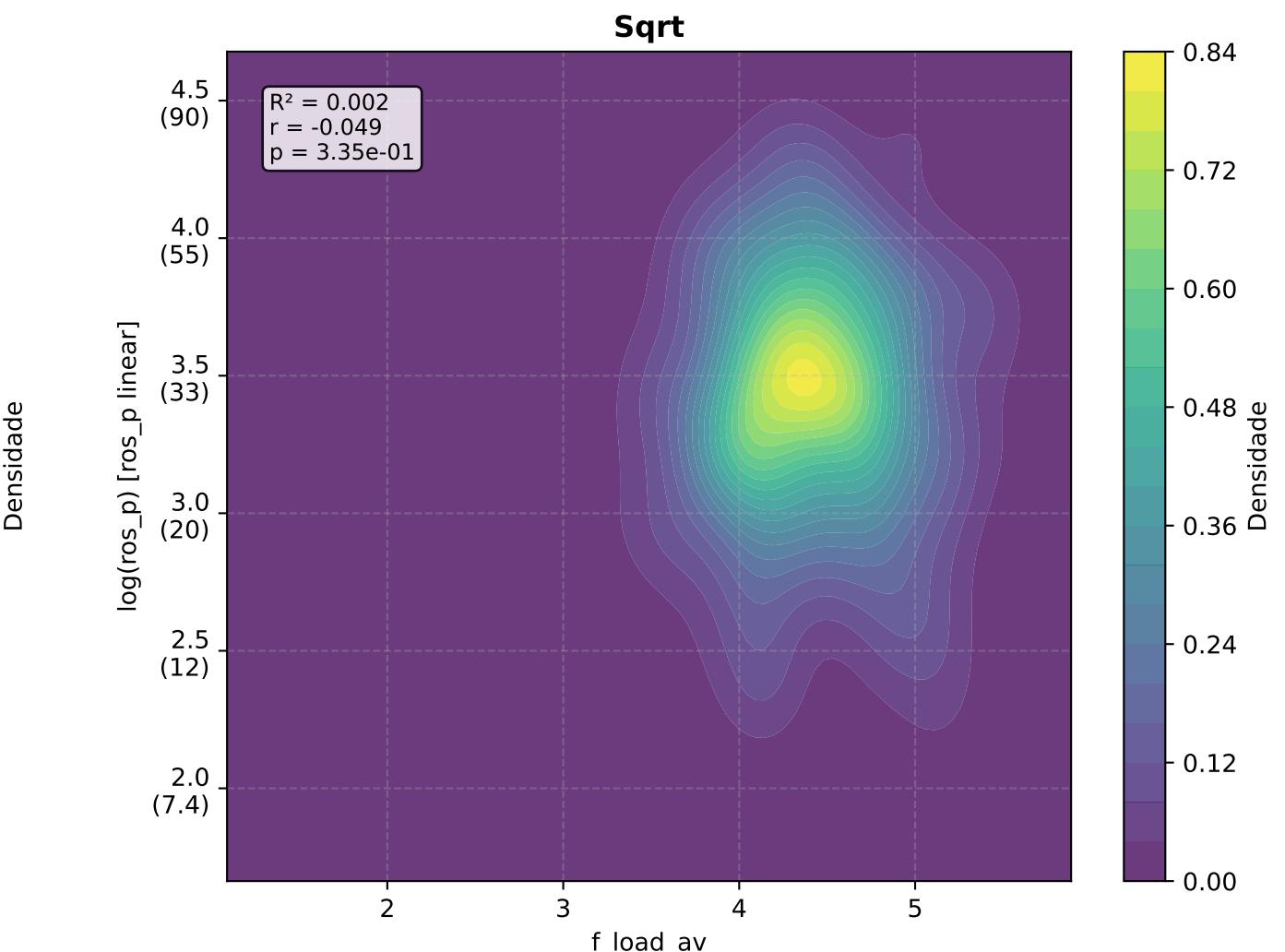
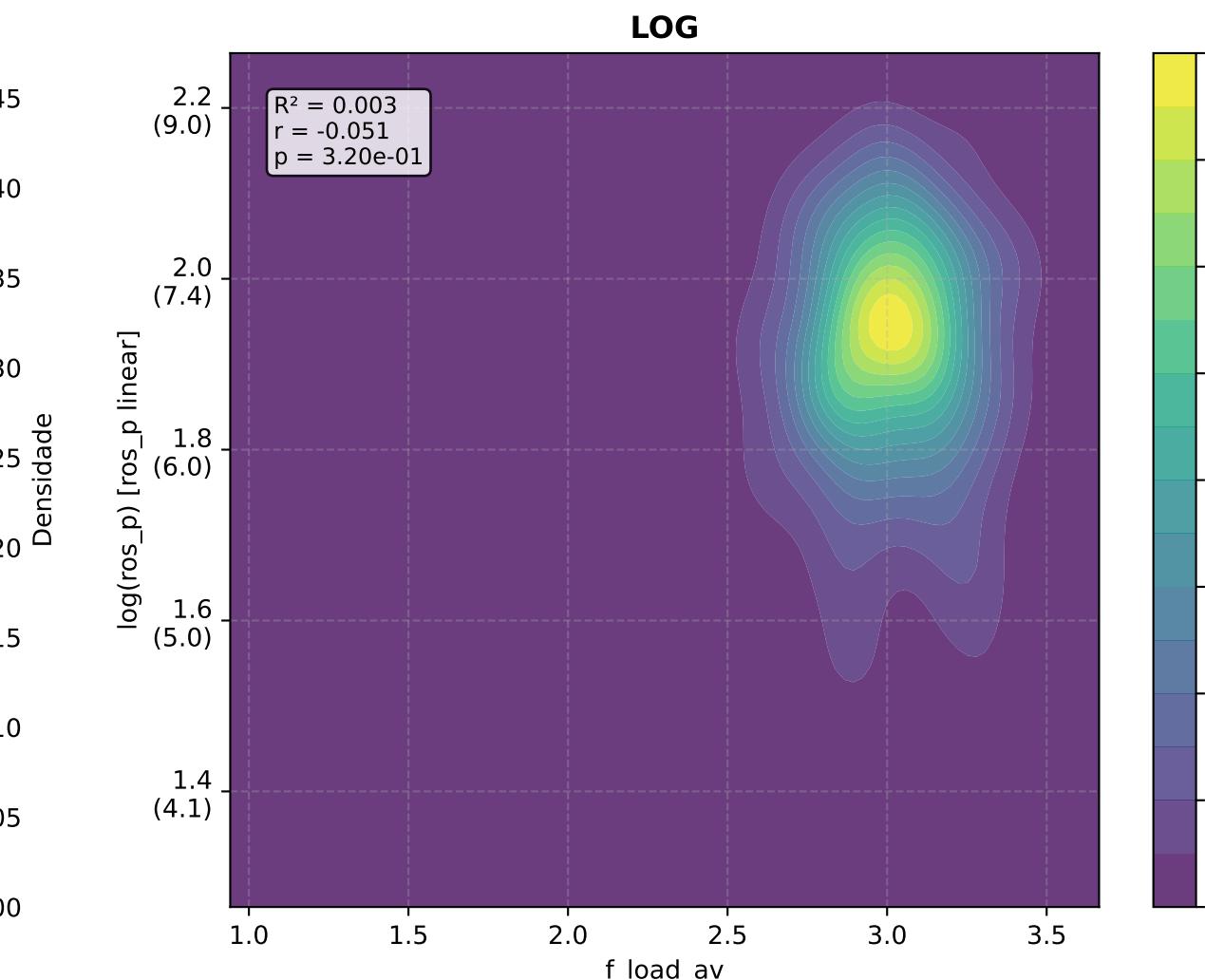
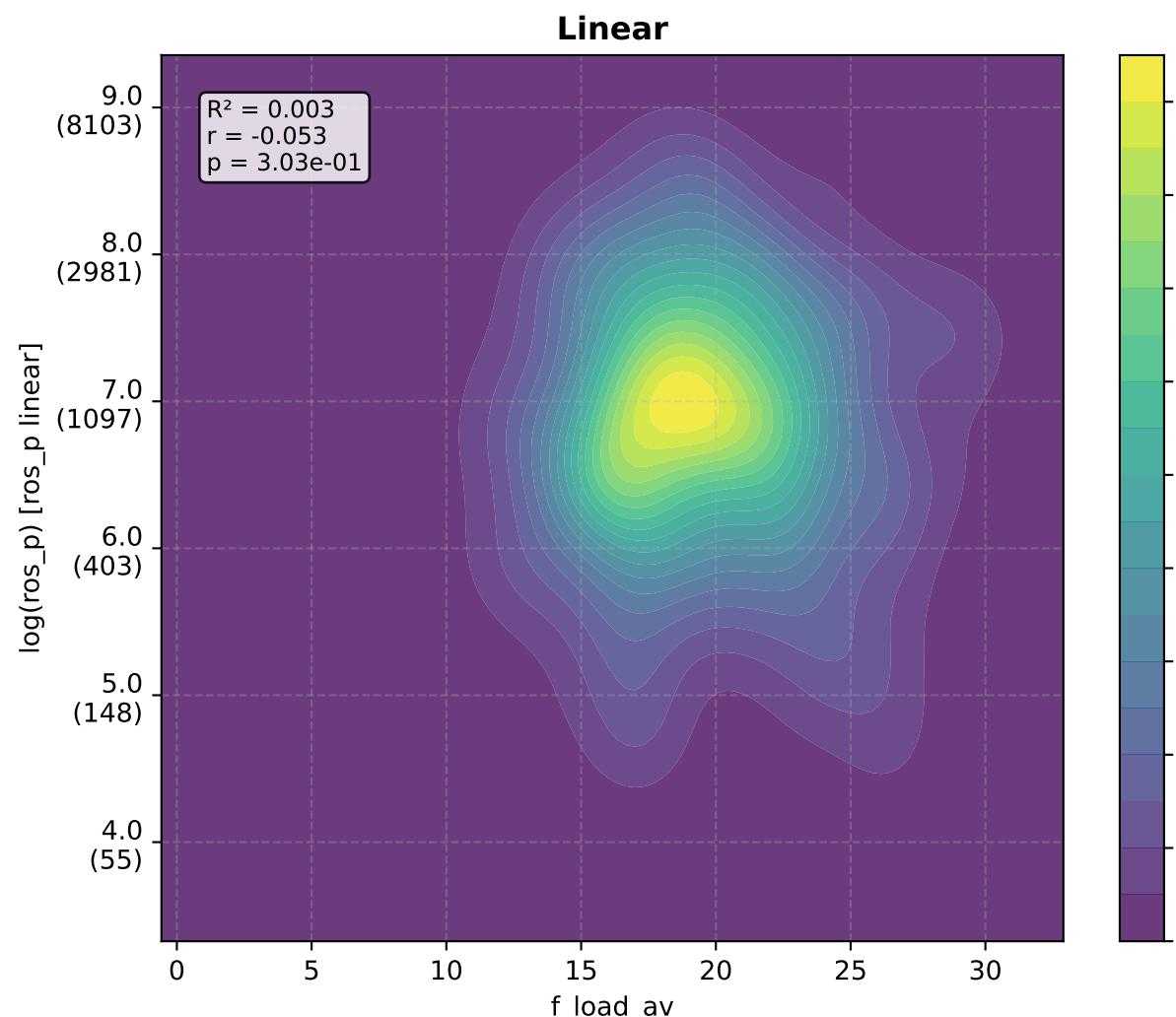
landform vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



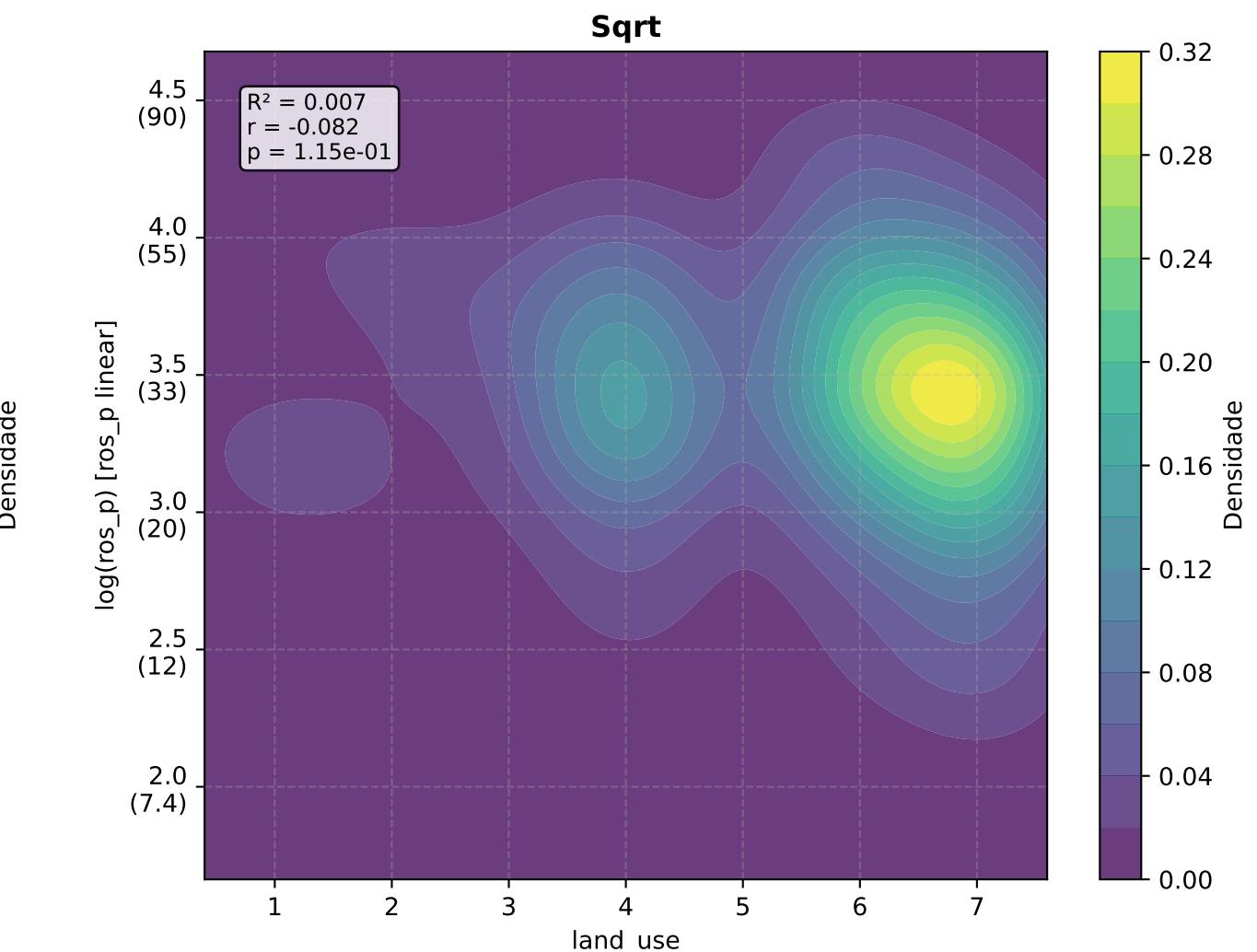
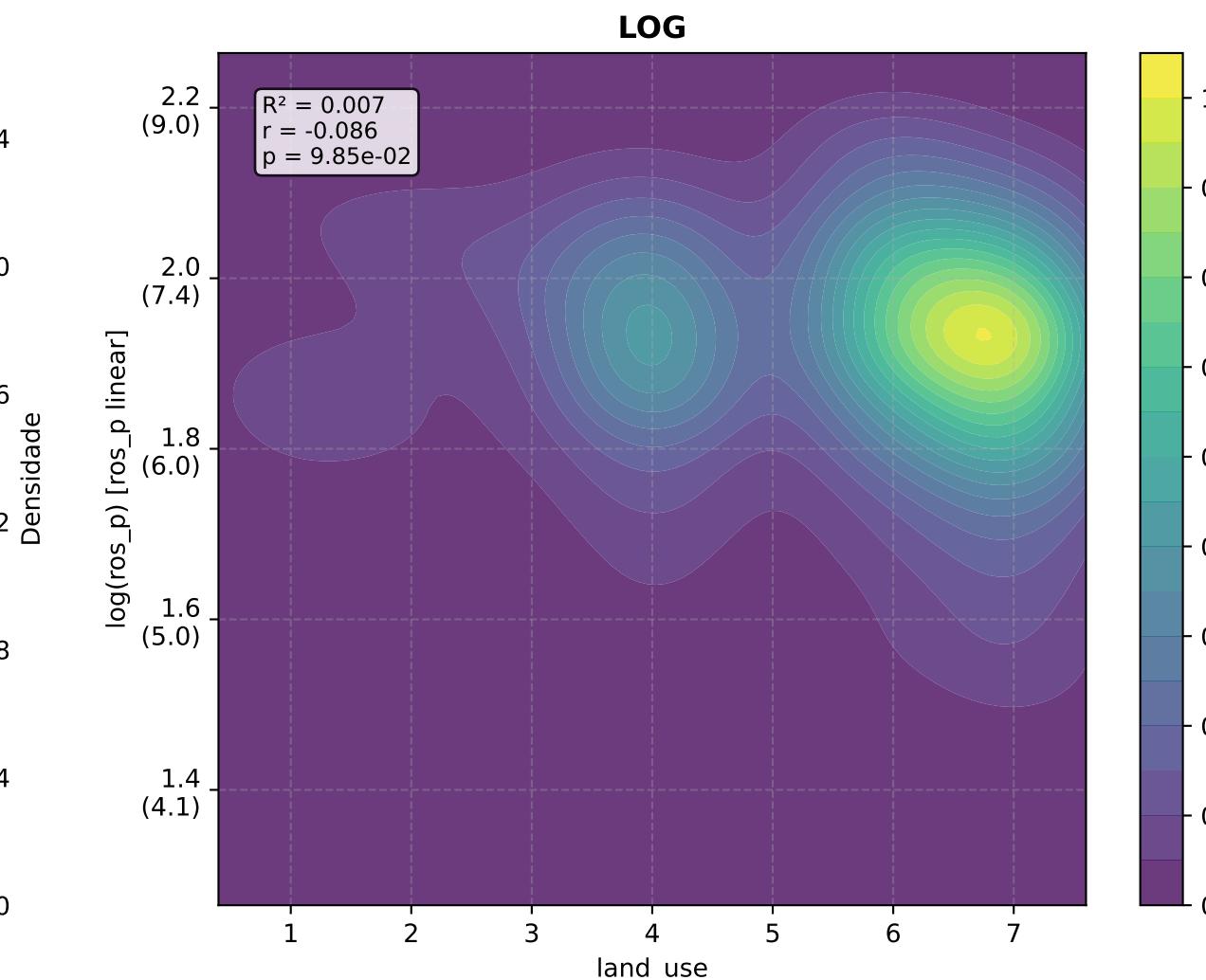
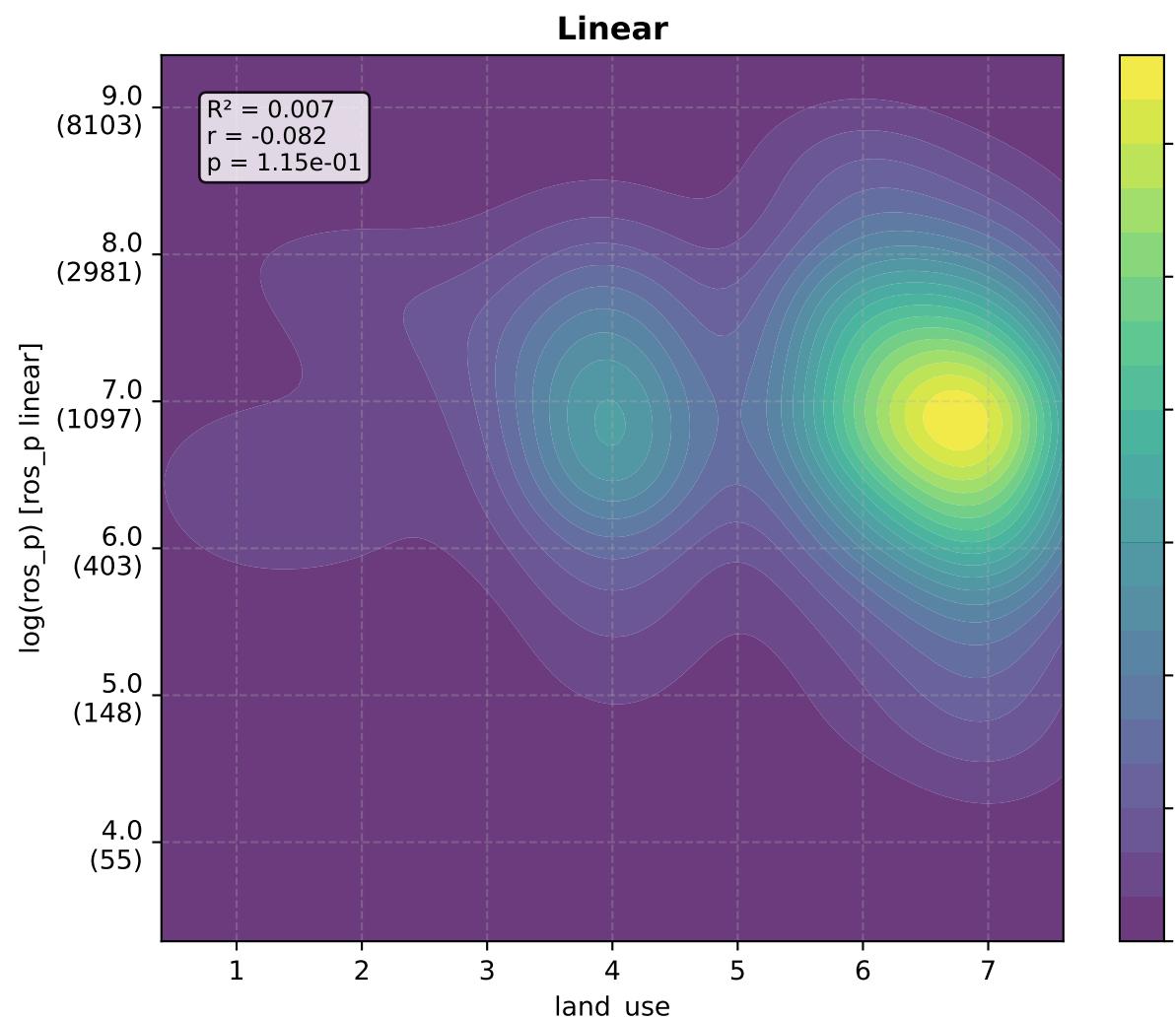
fuel_model vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



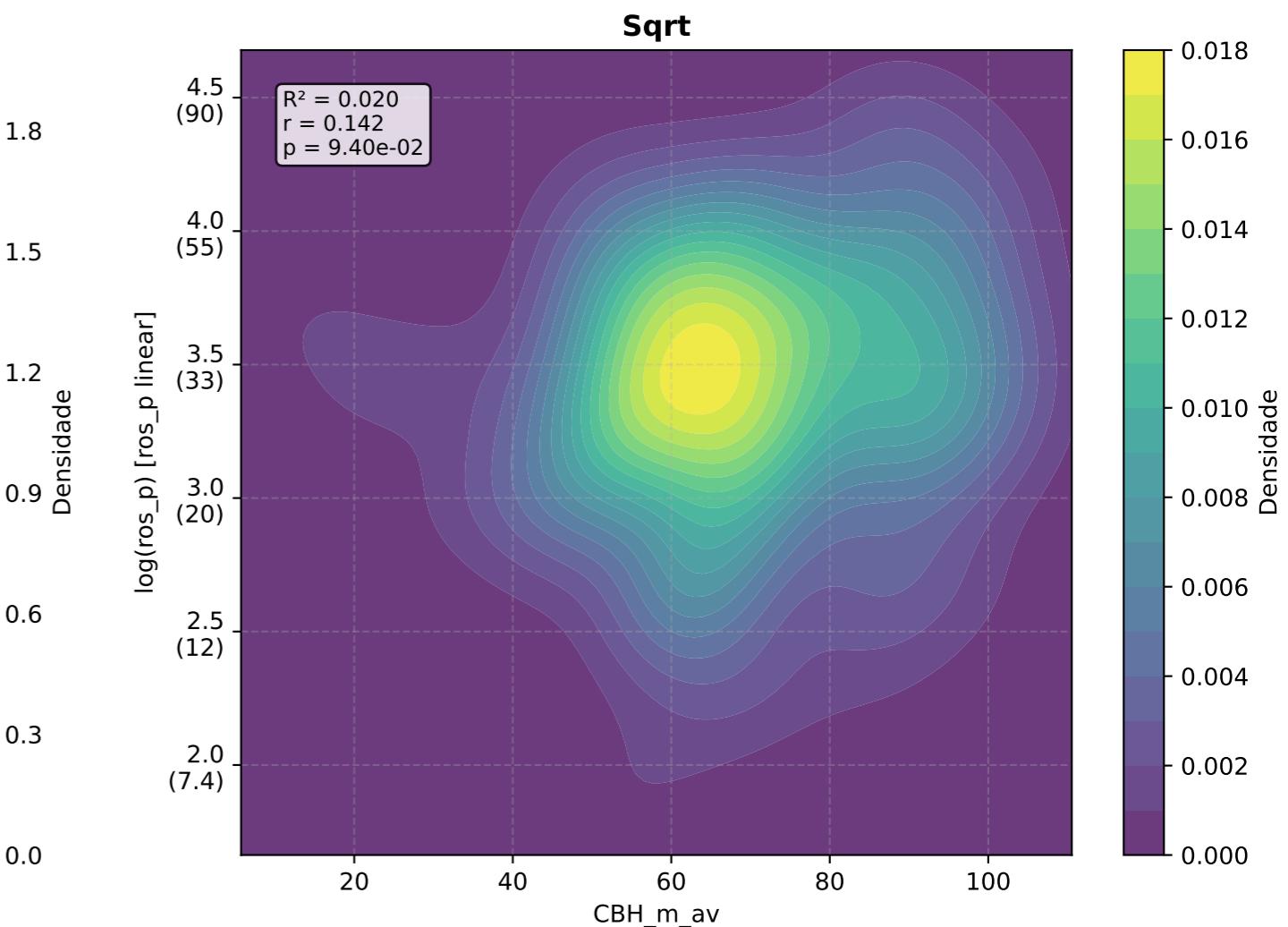
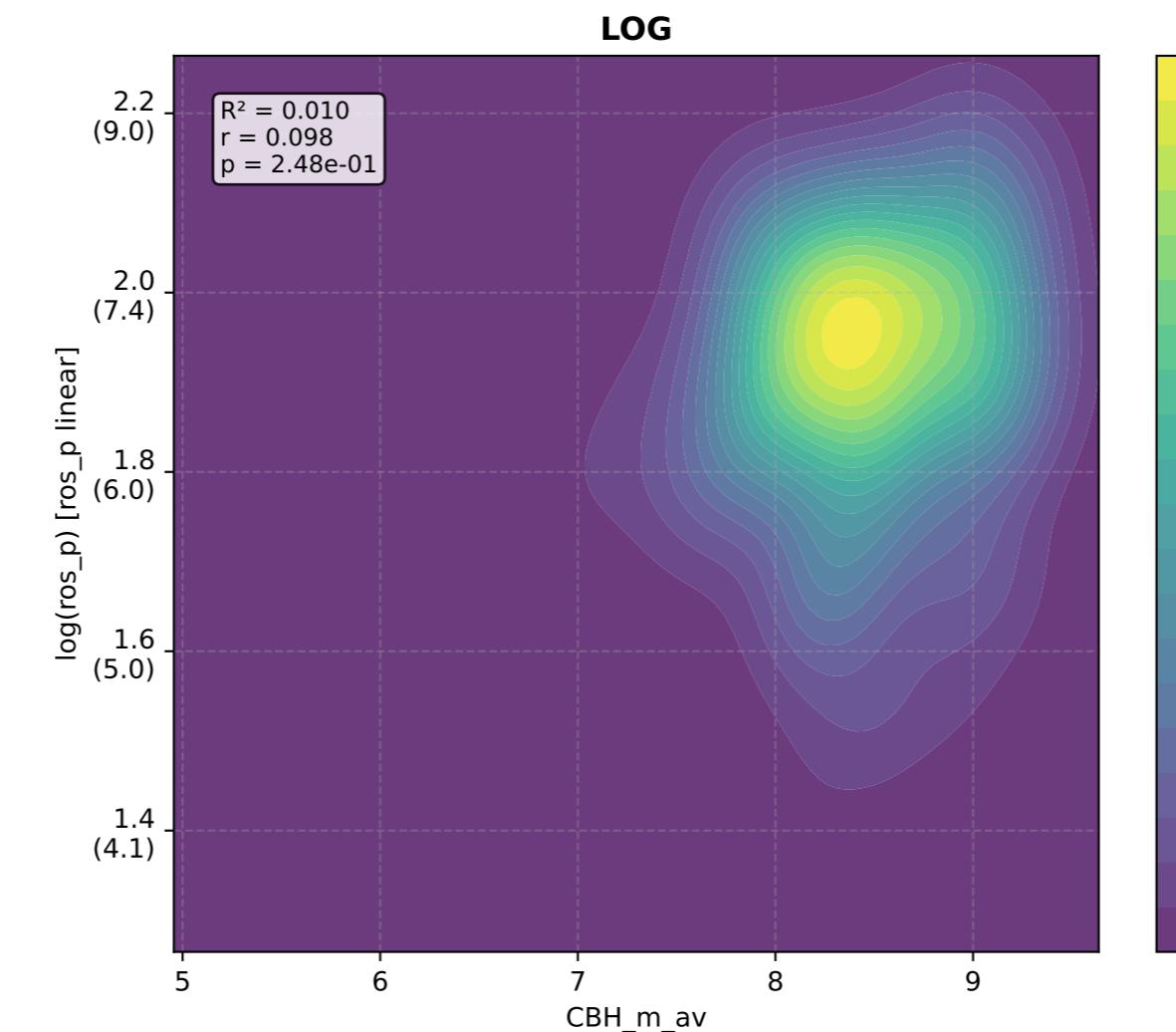
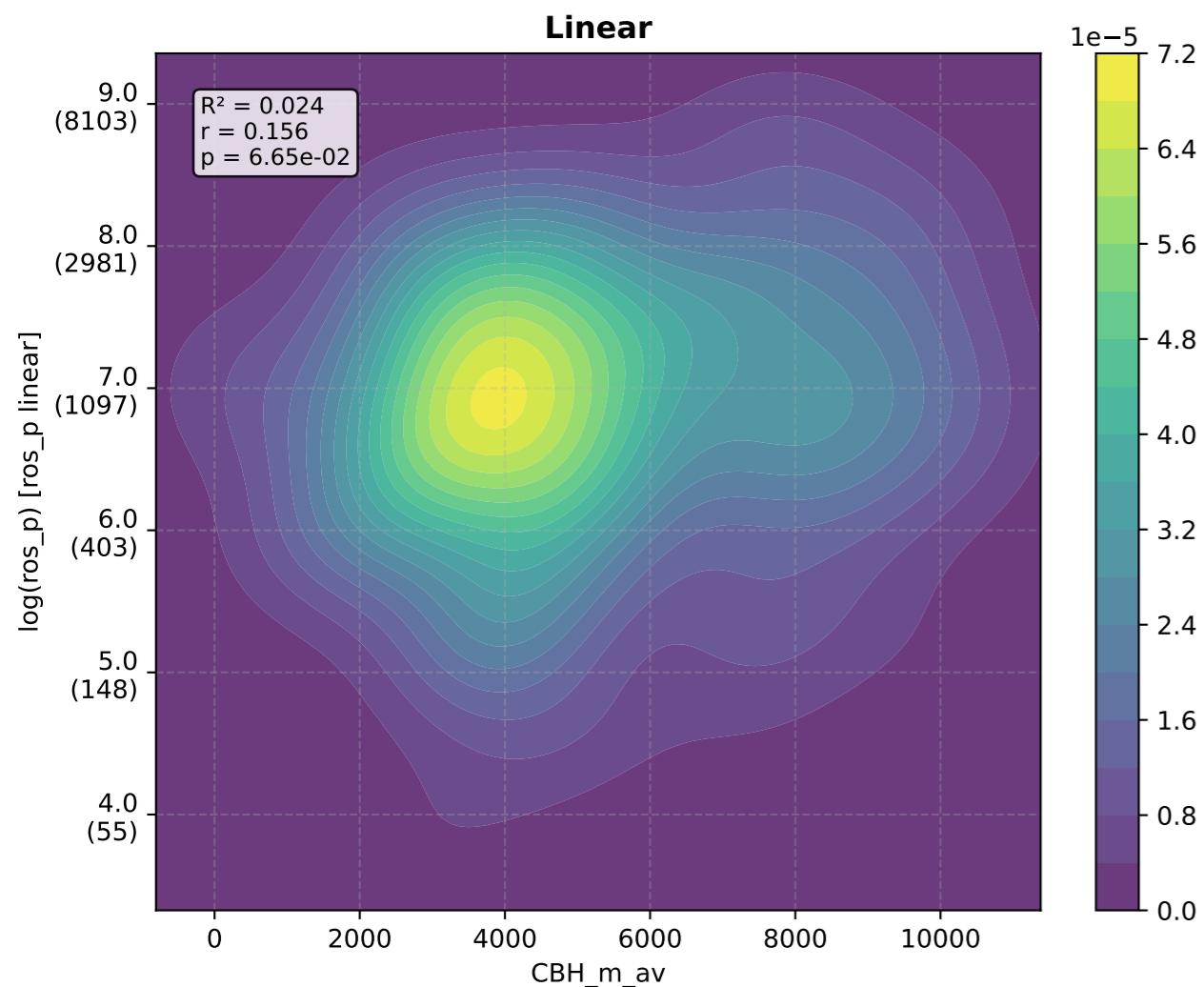
f_load_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



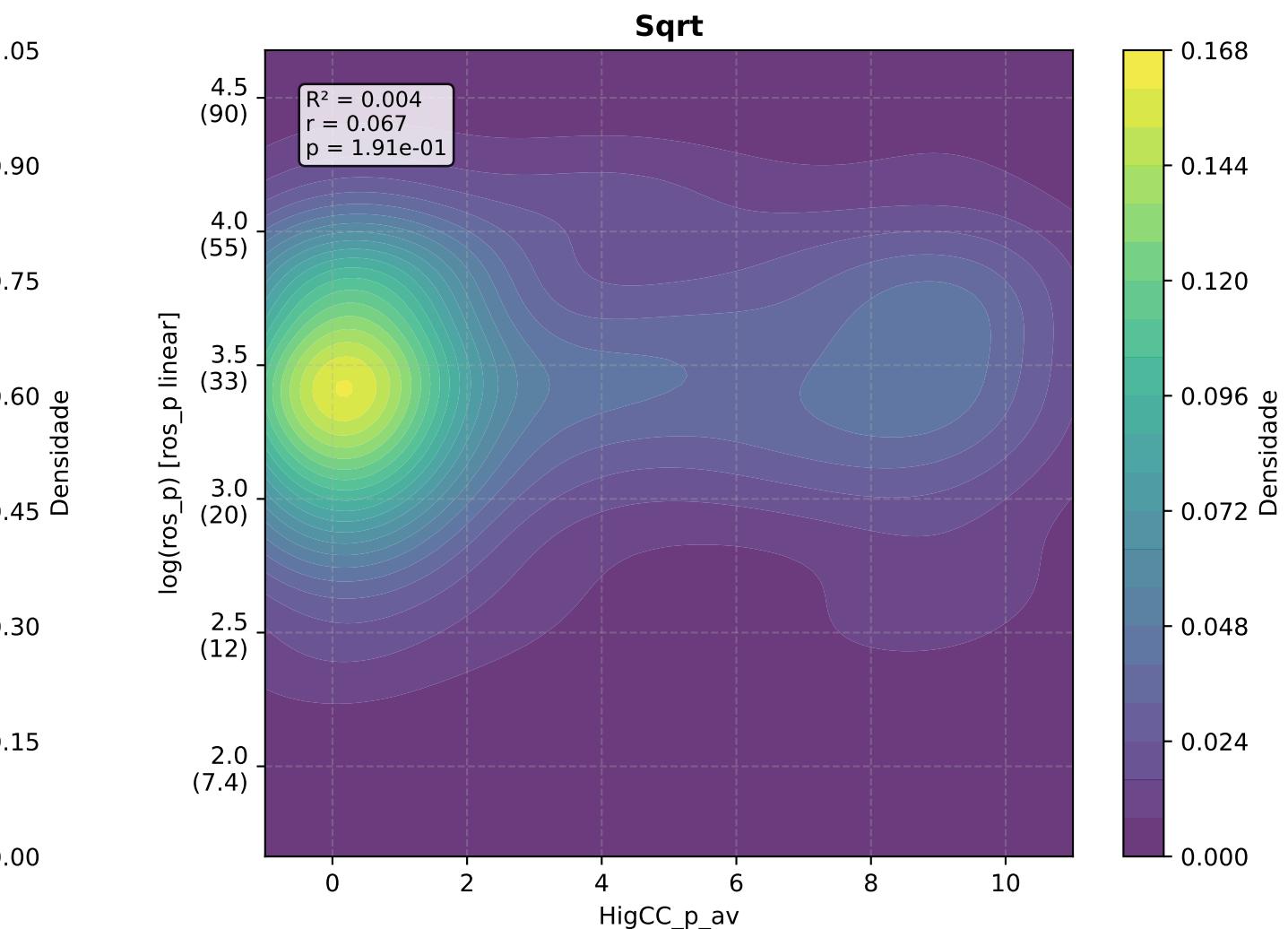
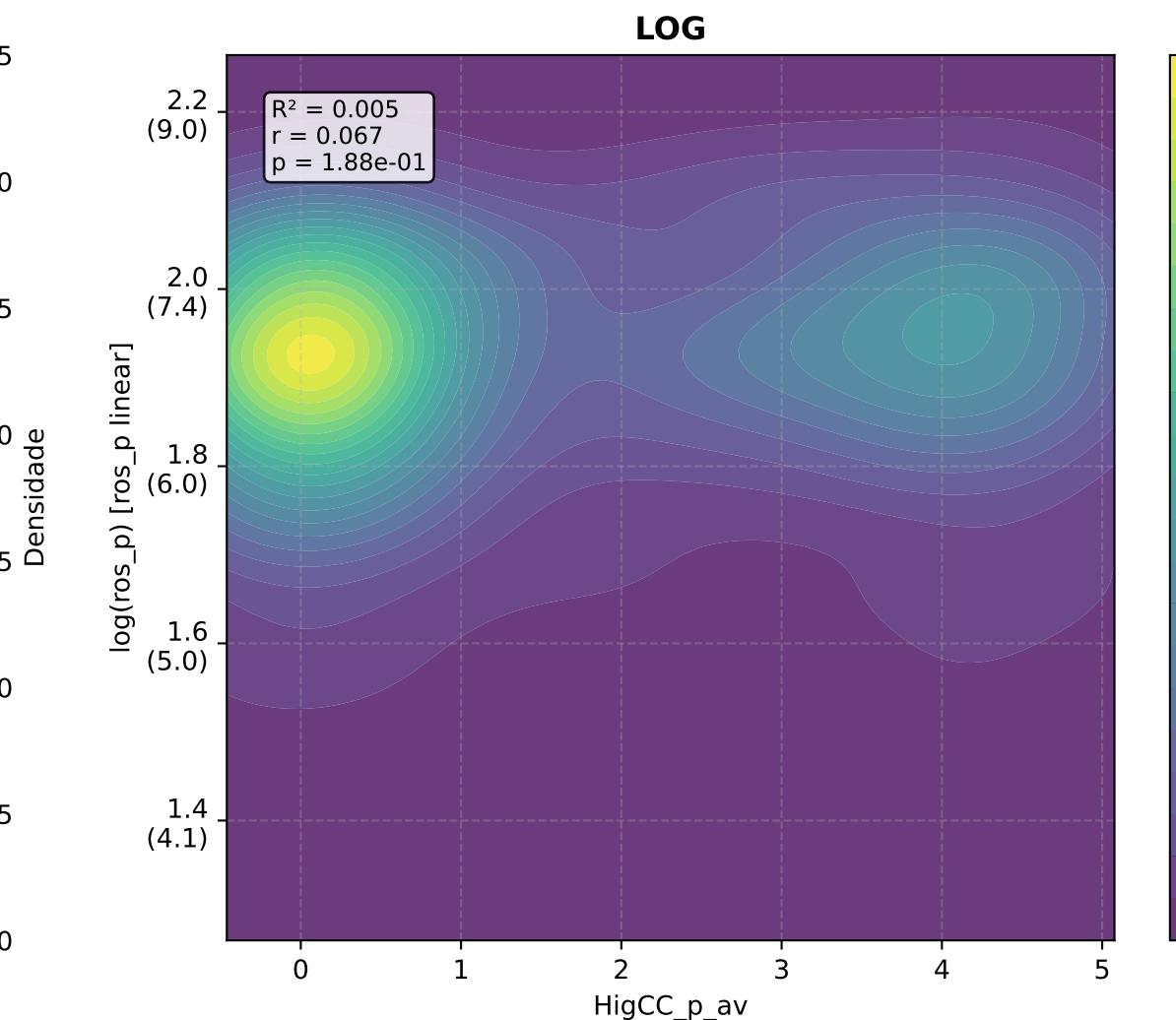
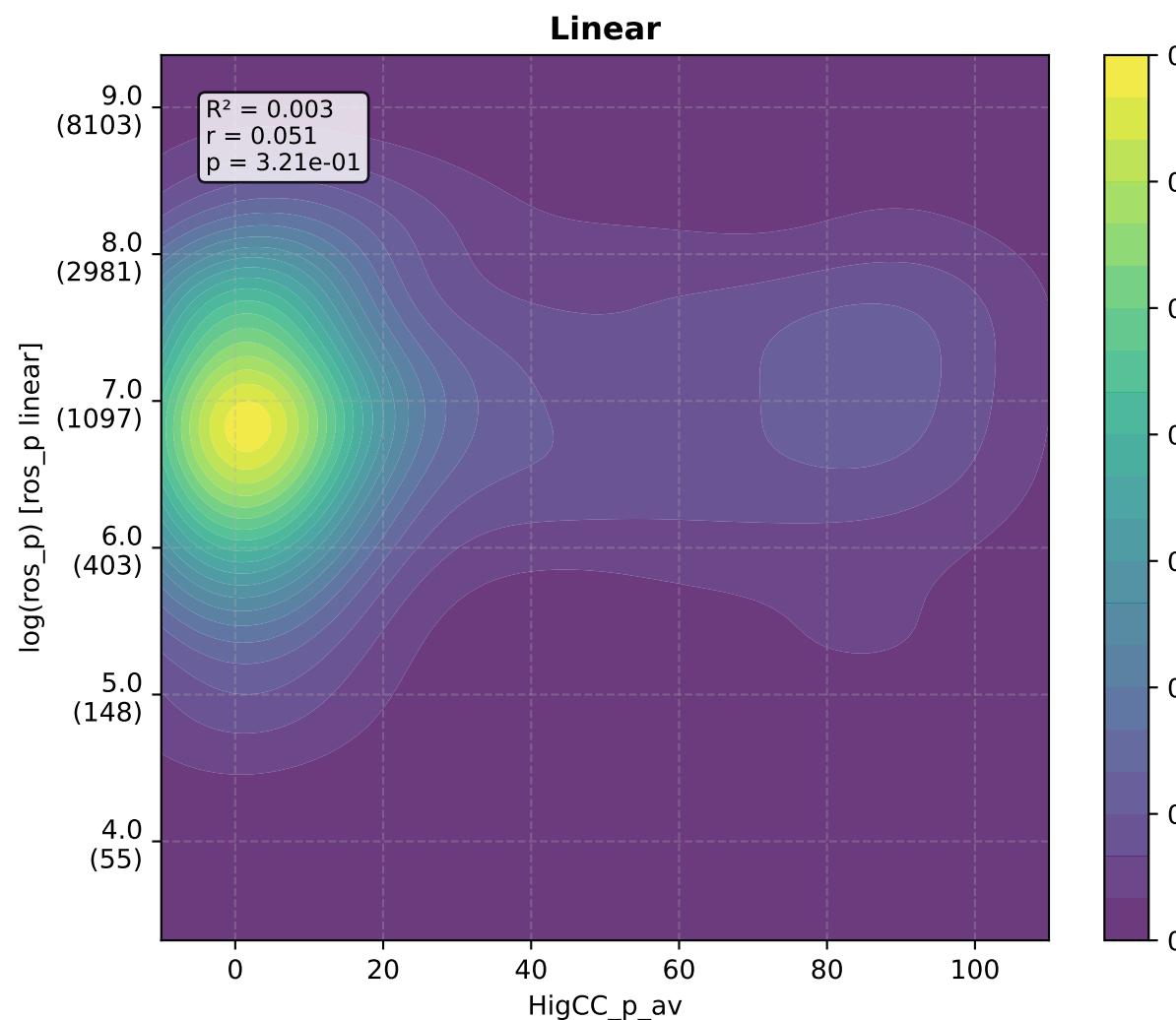
land_use vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



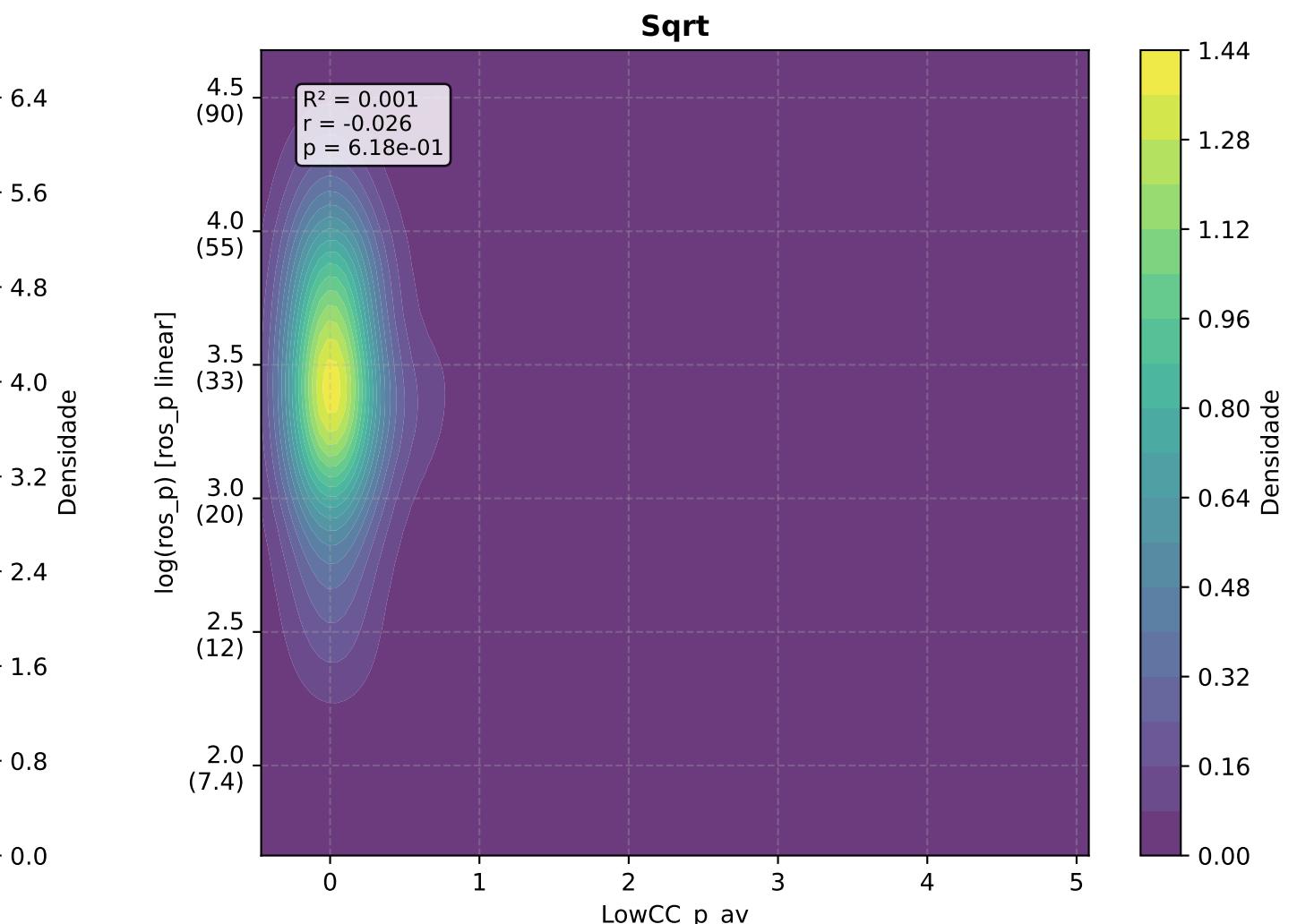
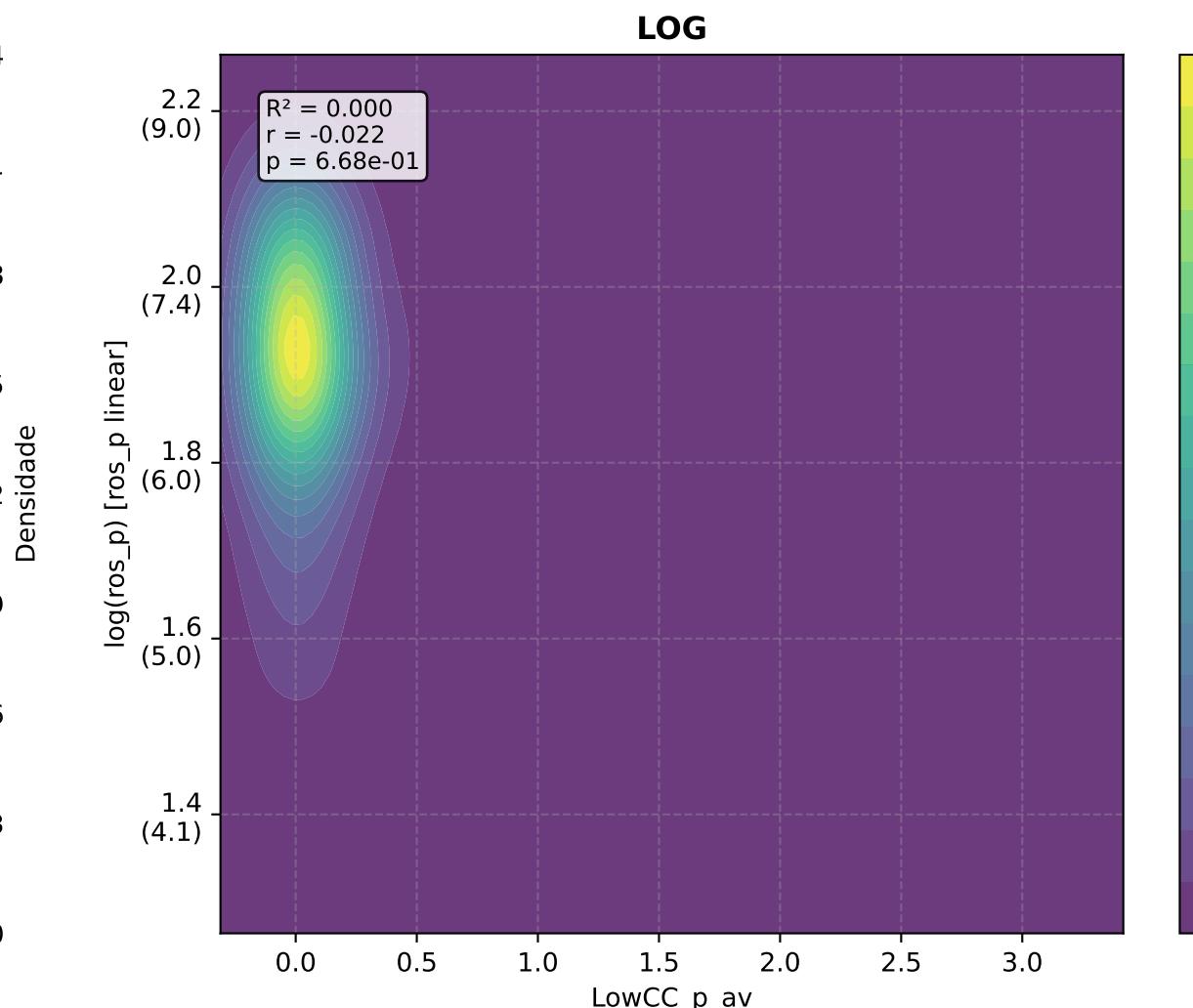
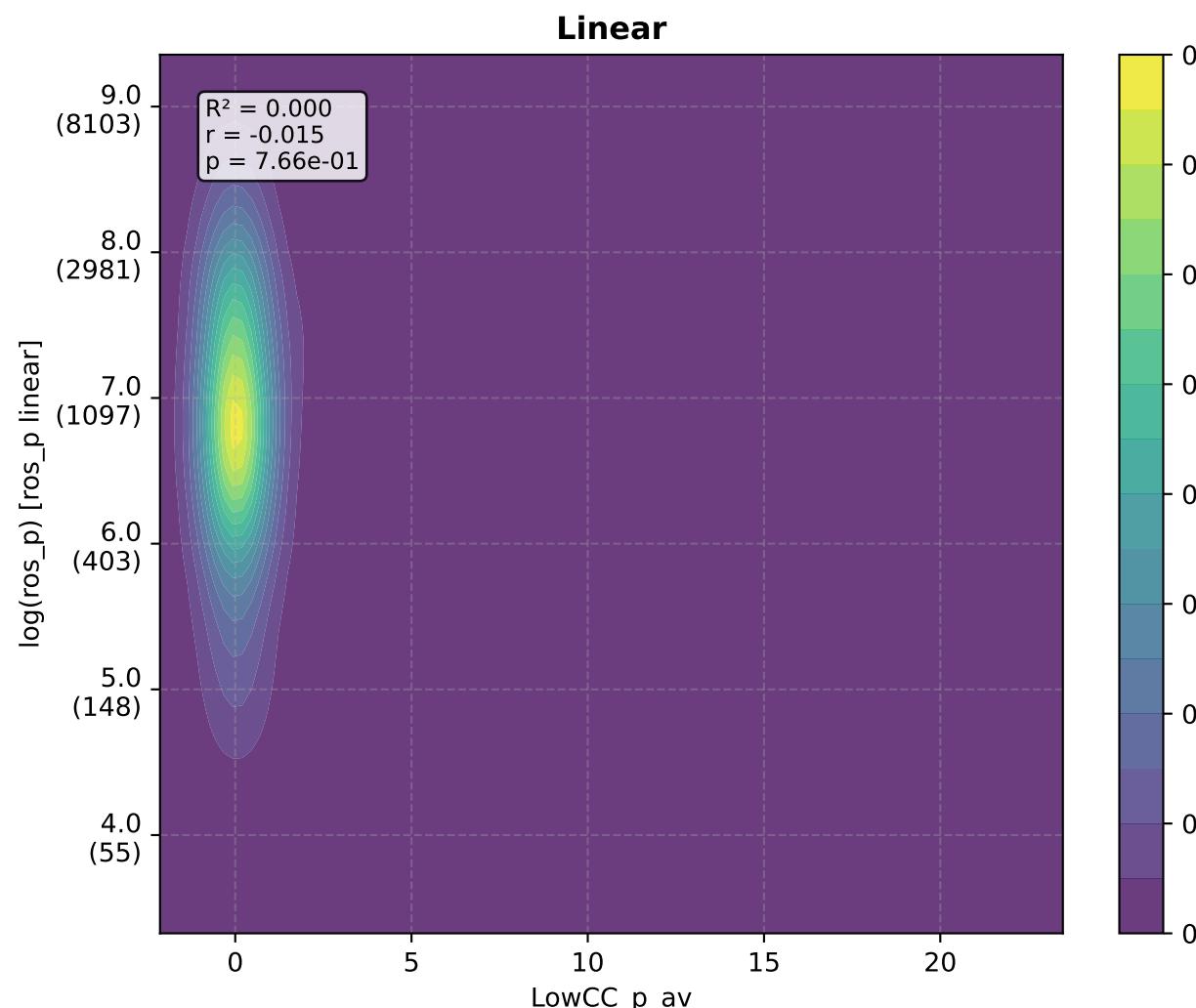
CBH_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



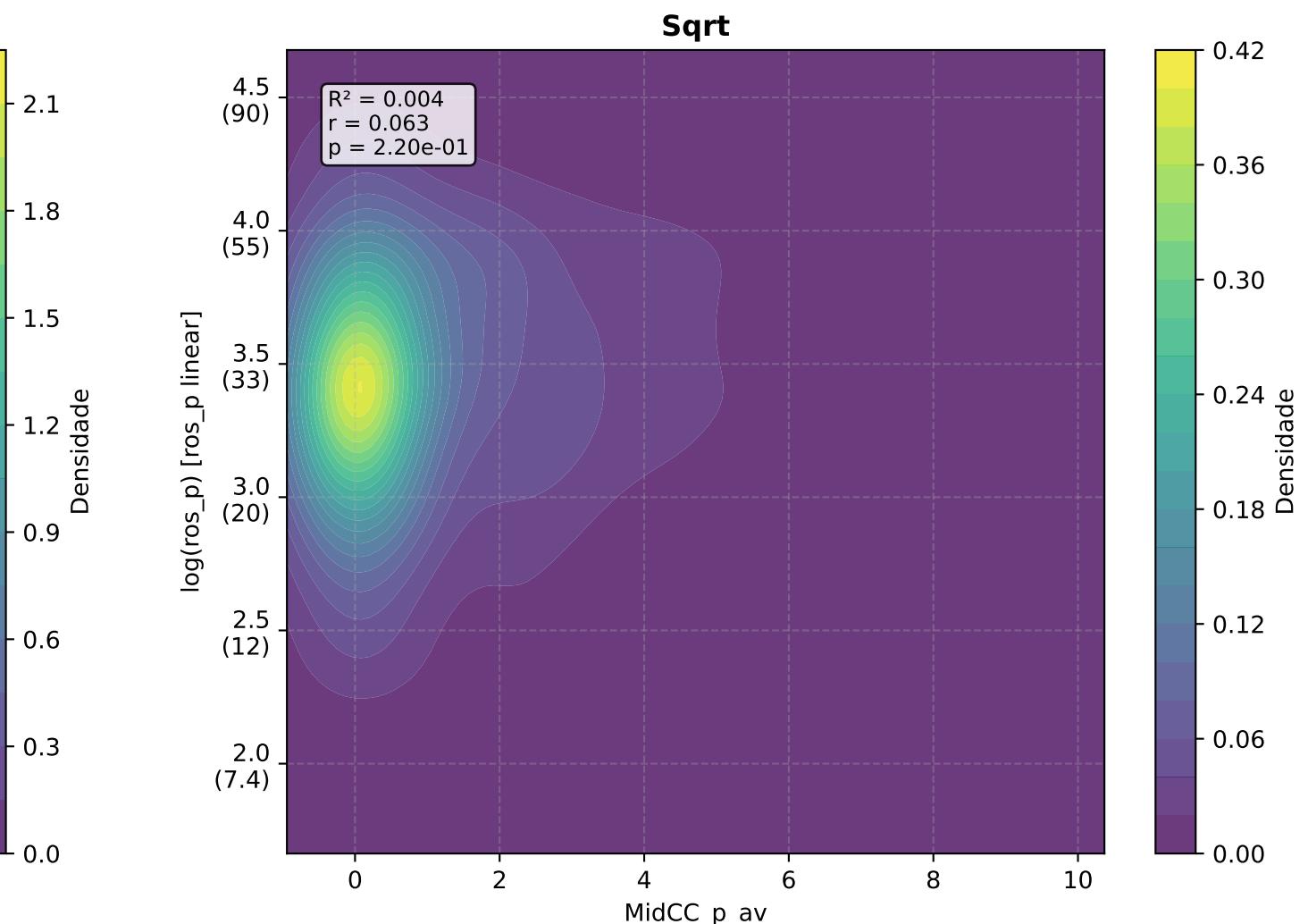
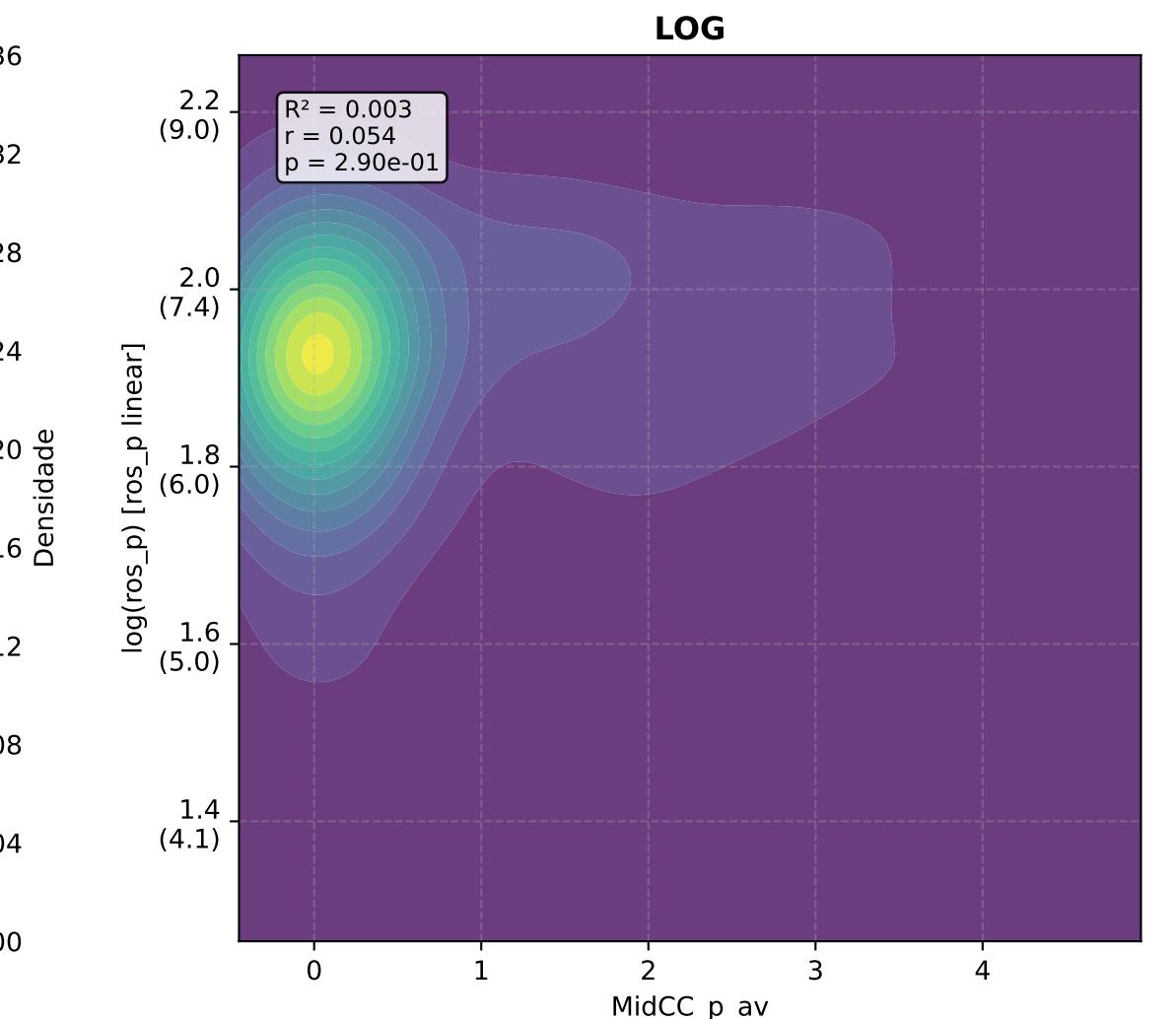
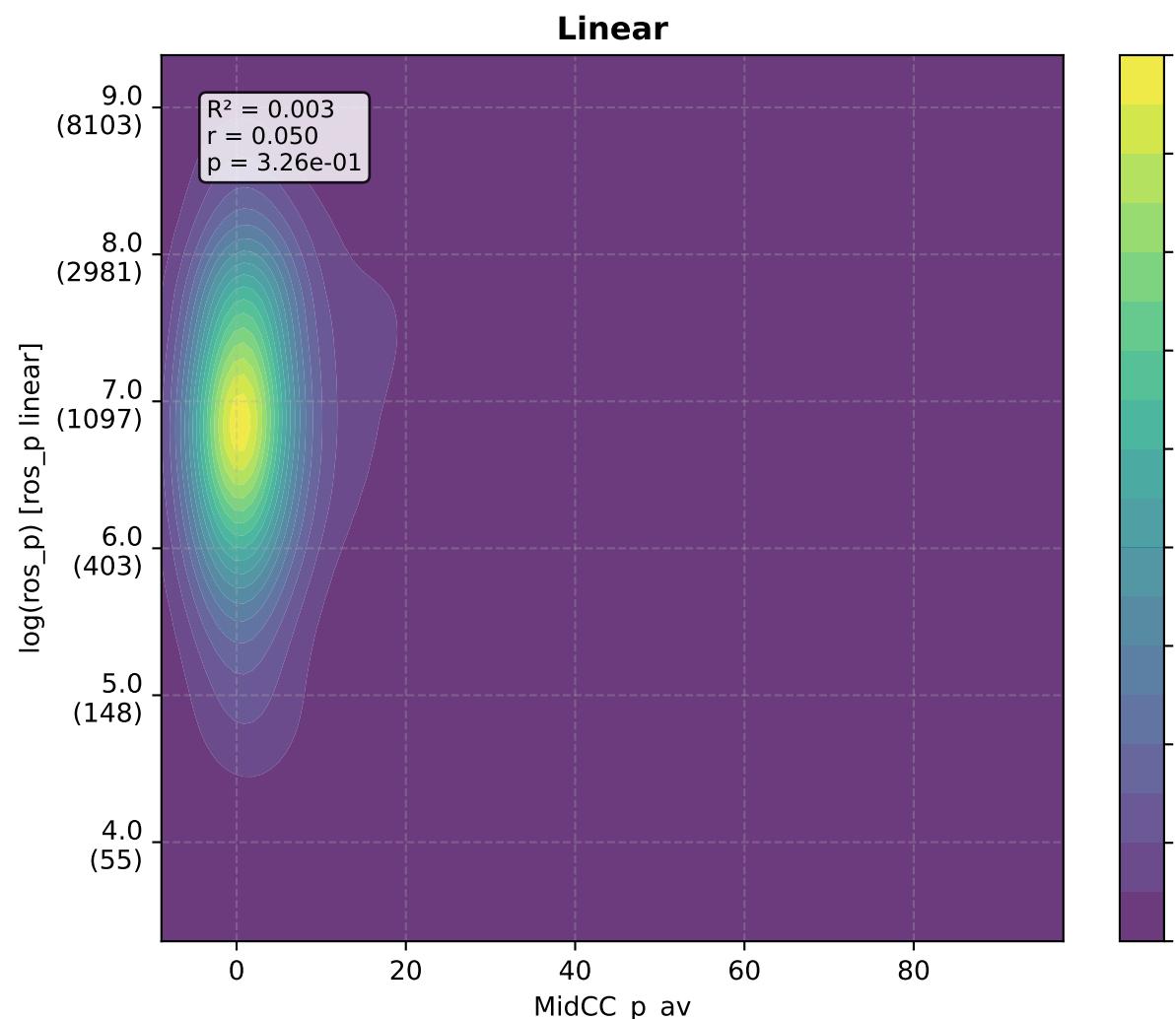
HigCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



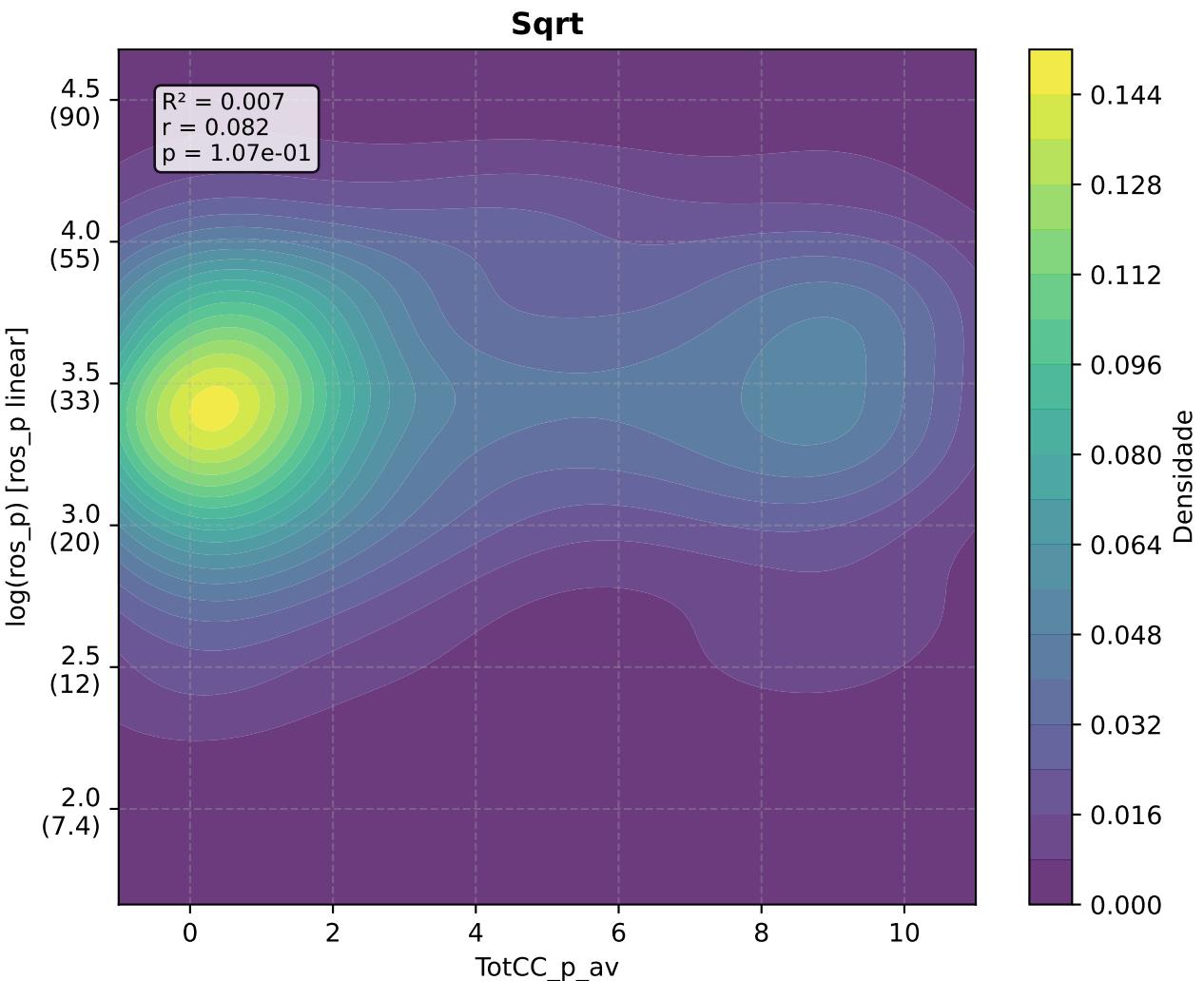
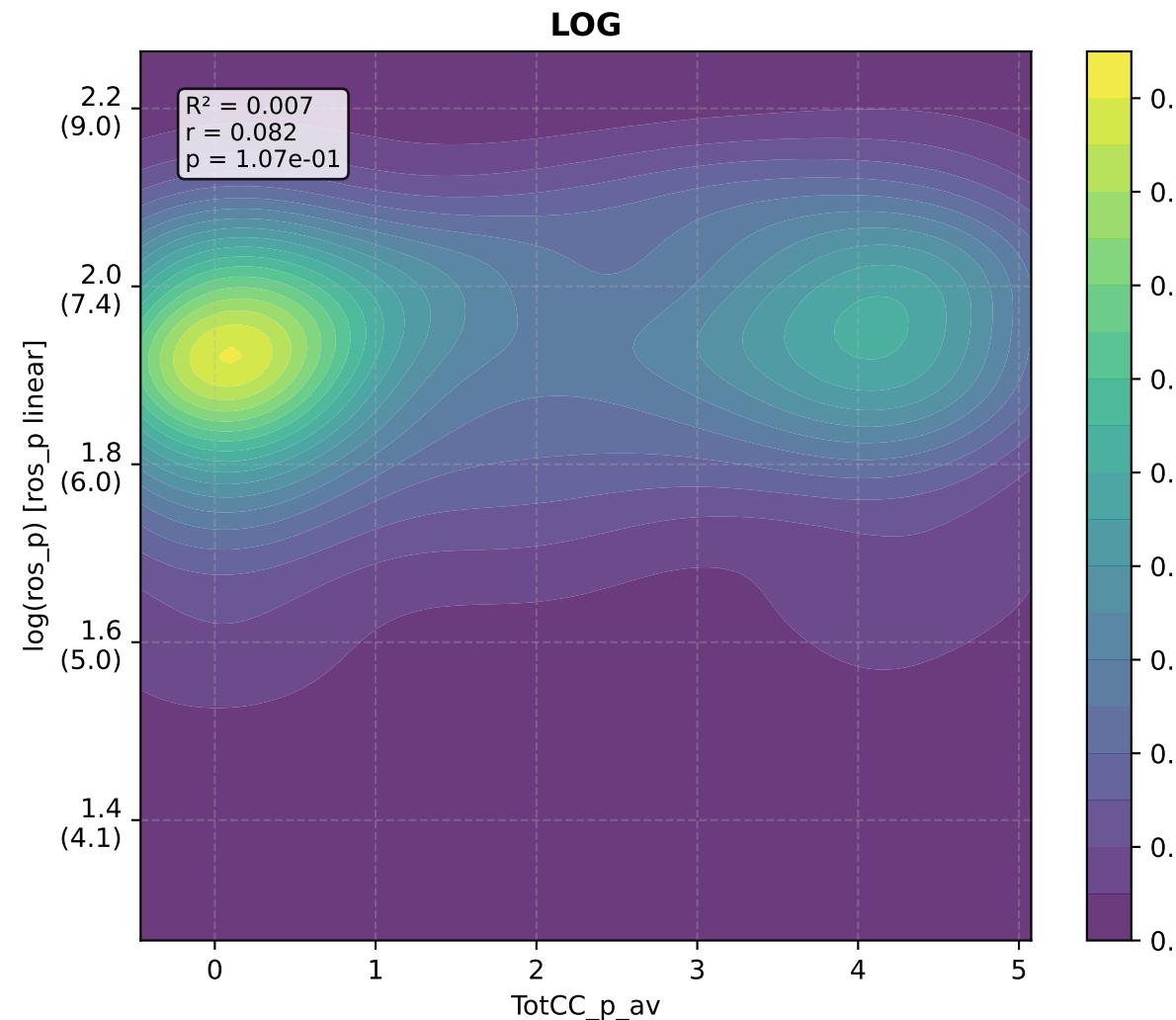
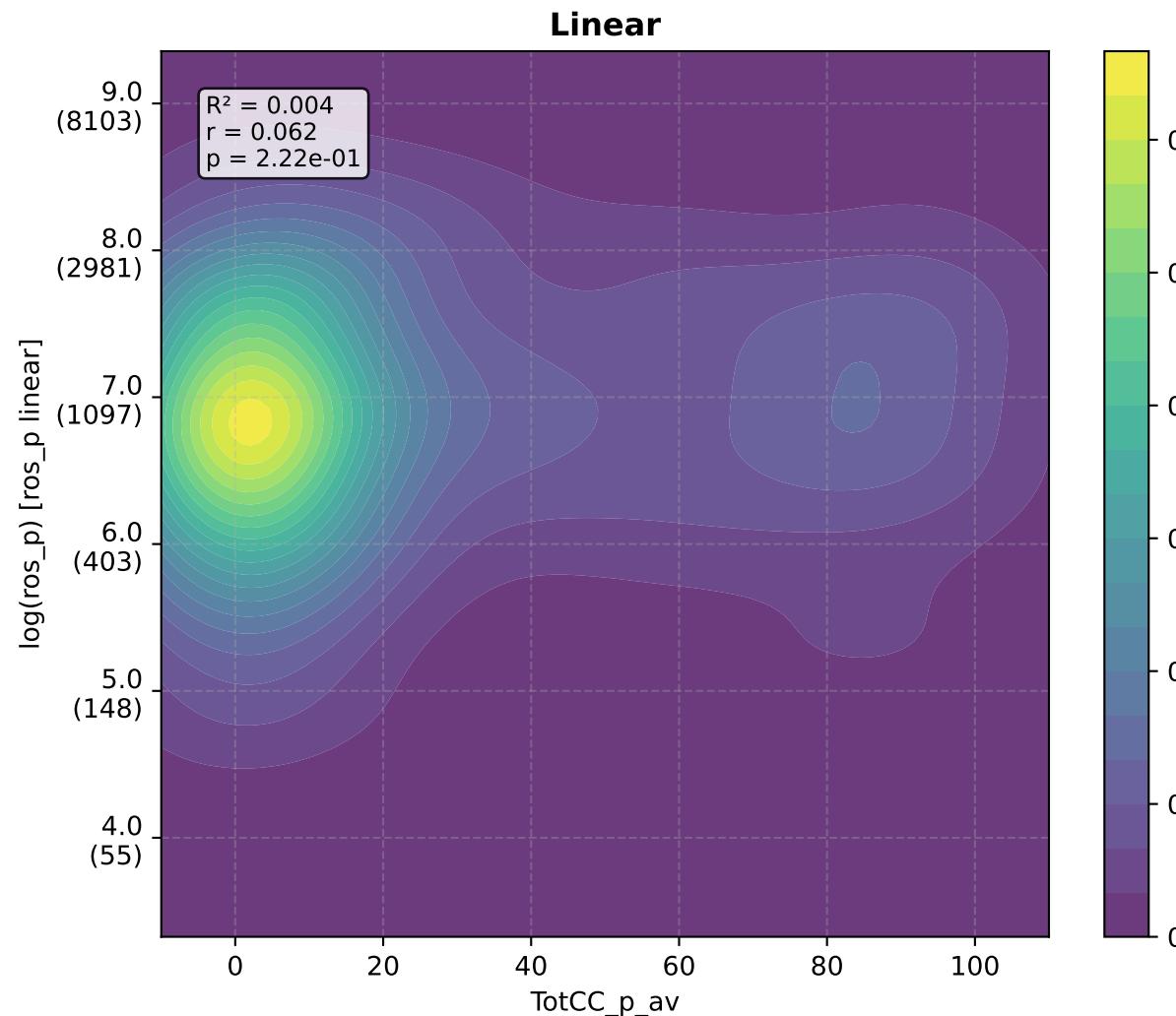
LowCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



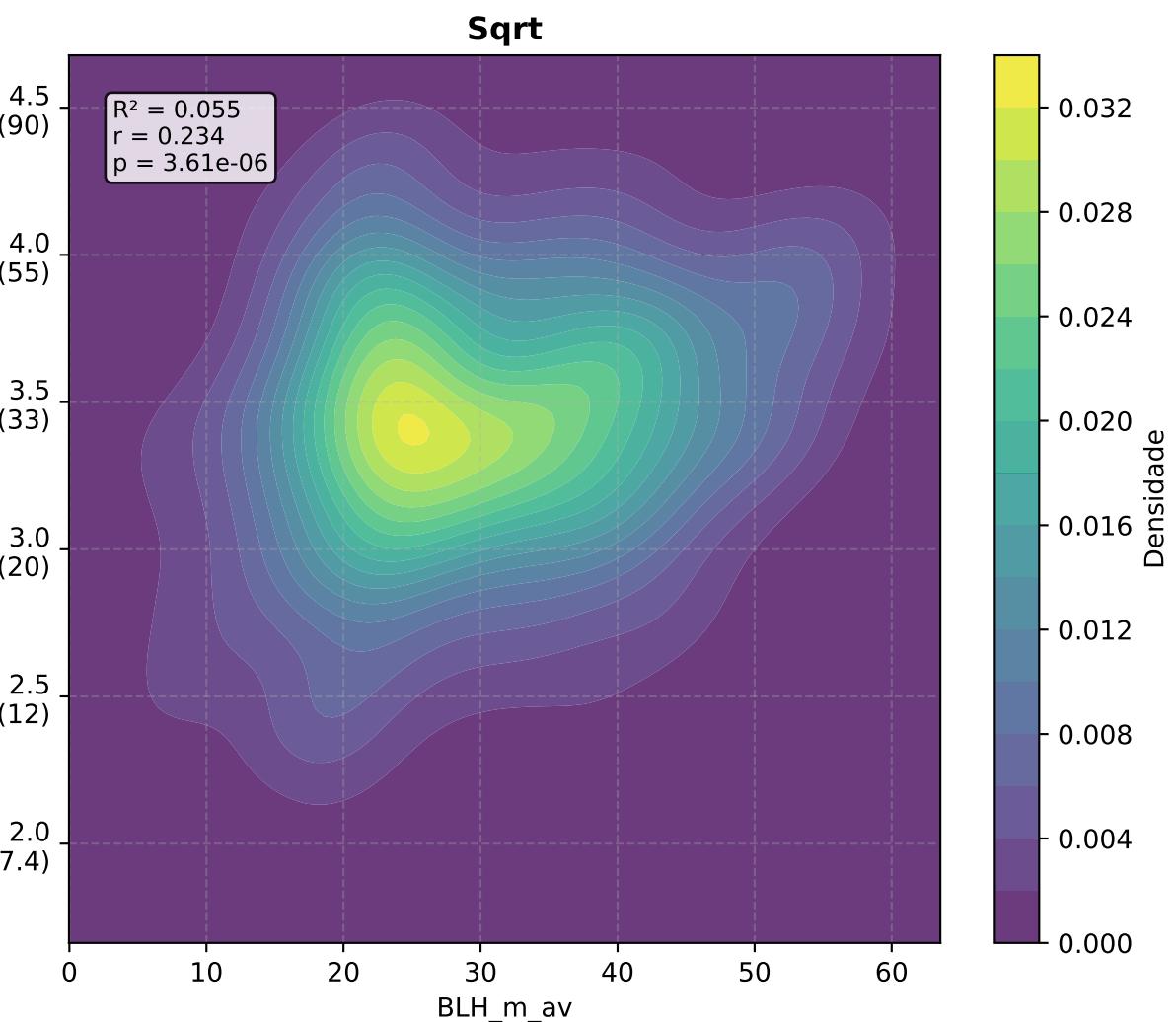
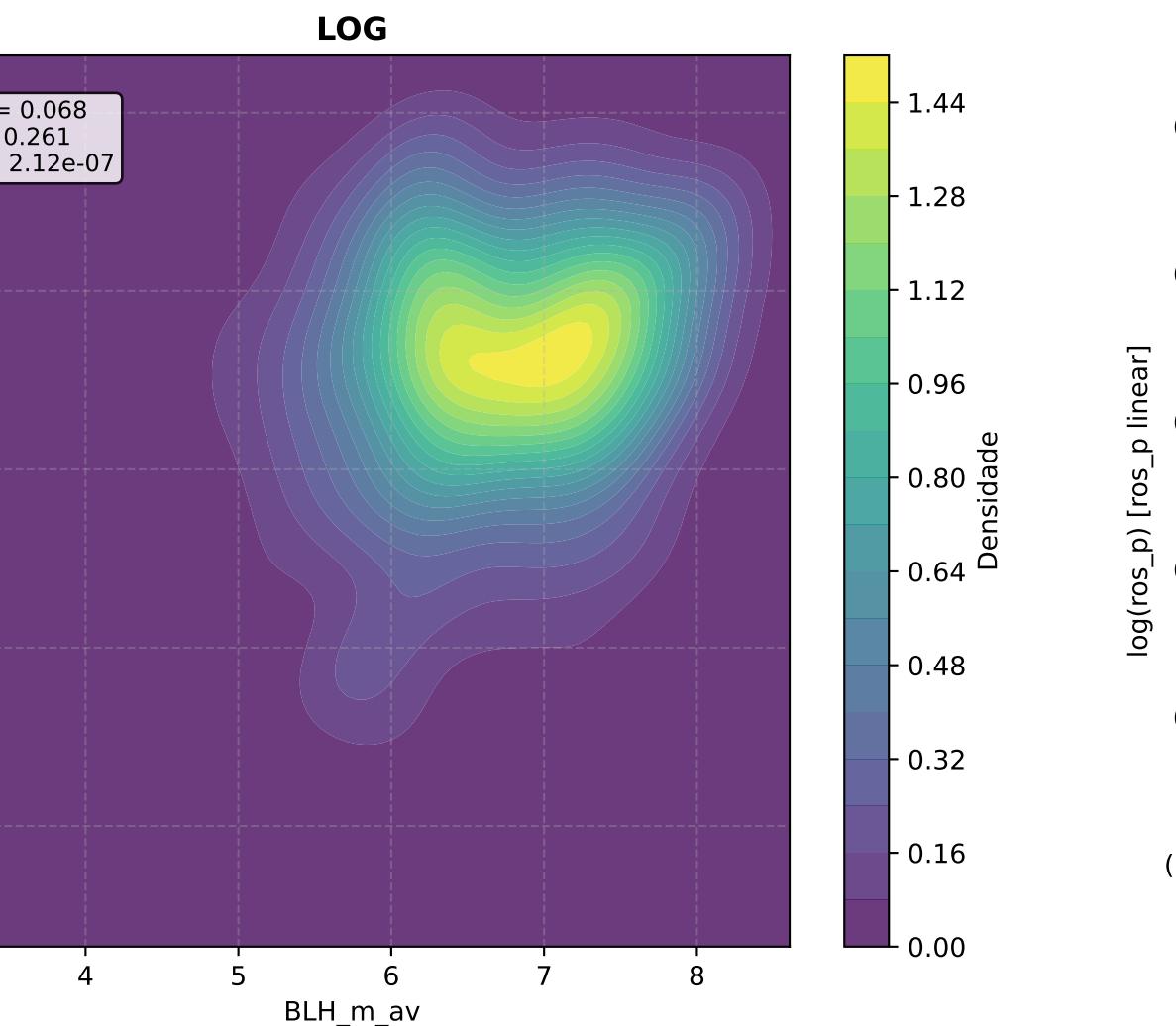
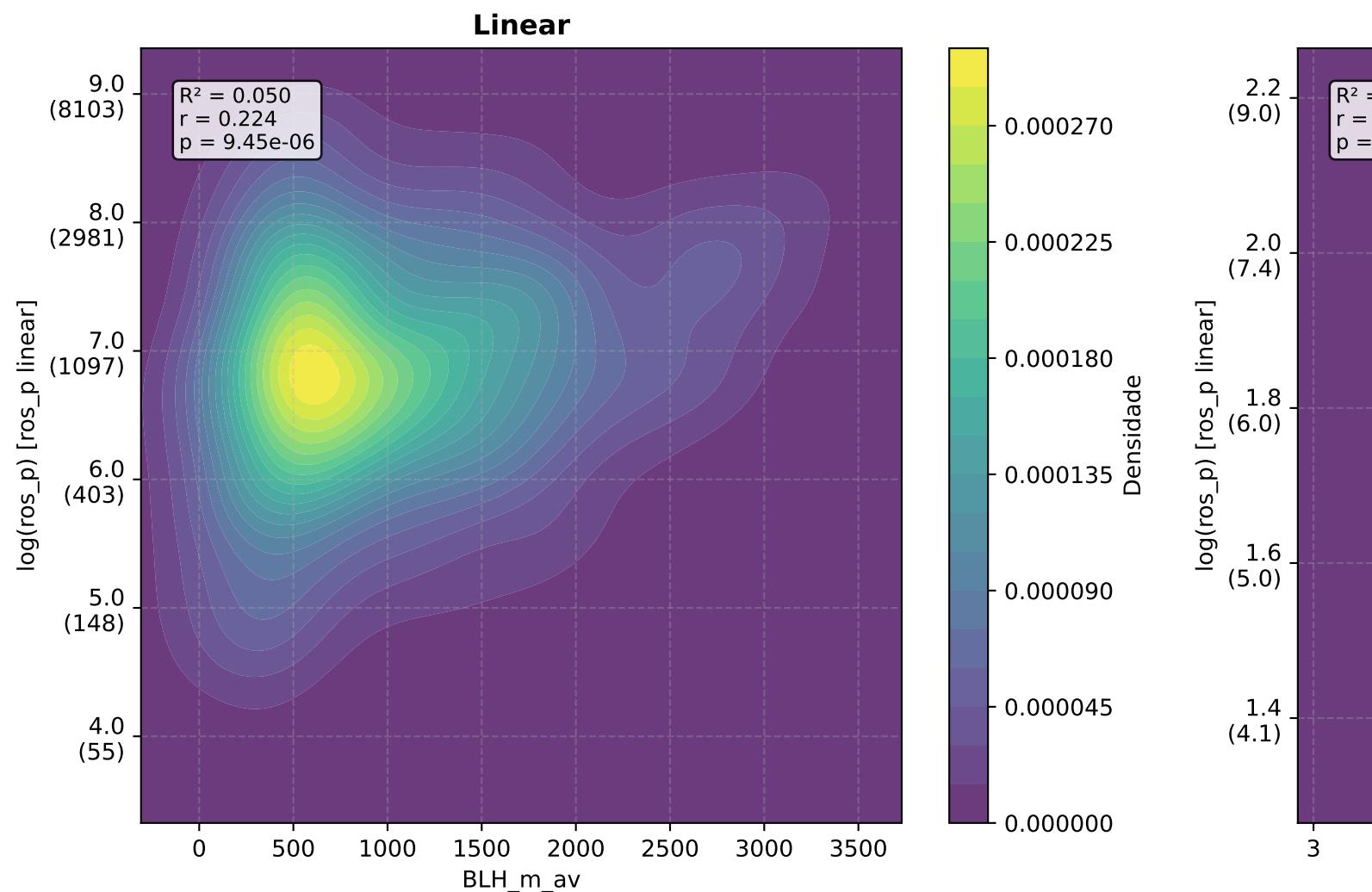
MidCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



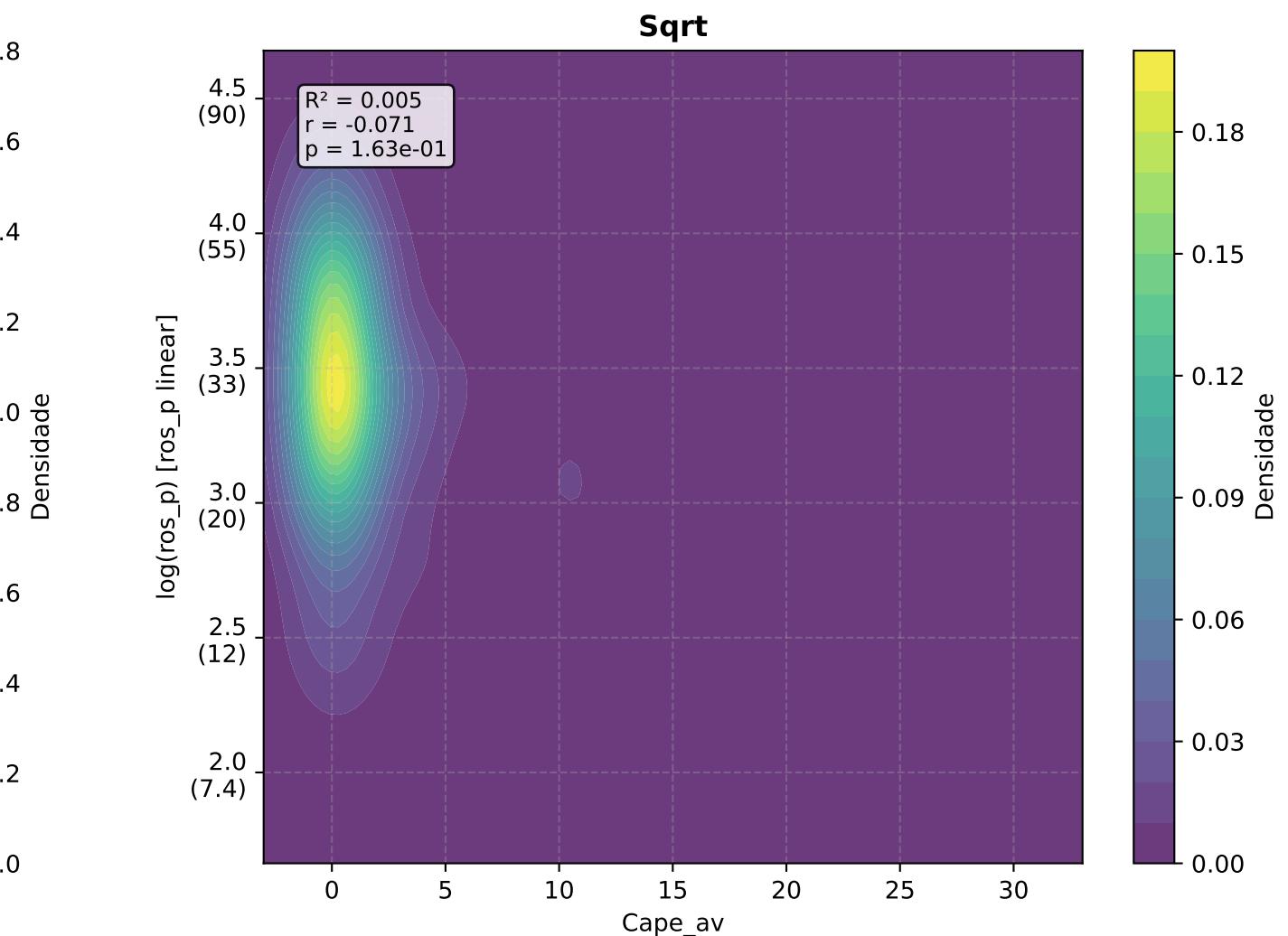
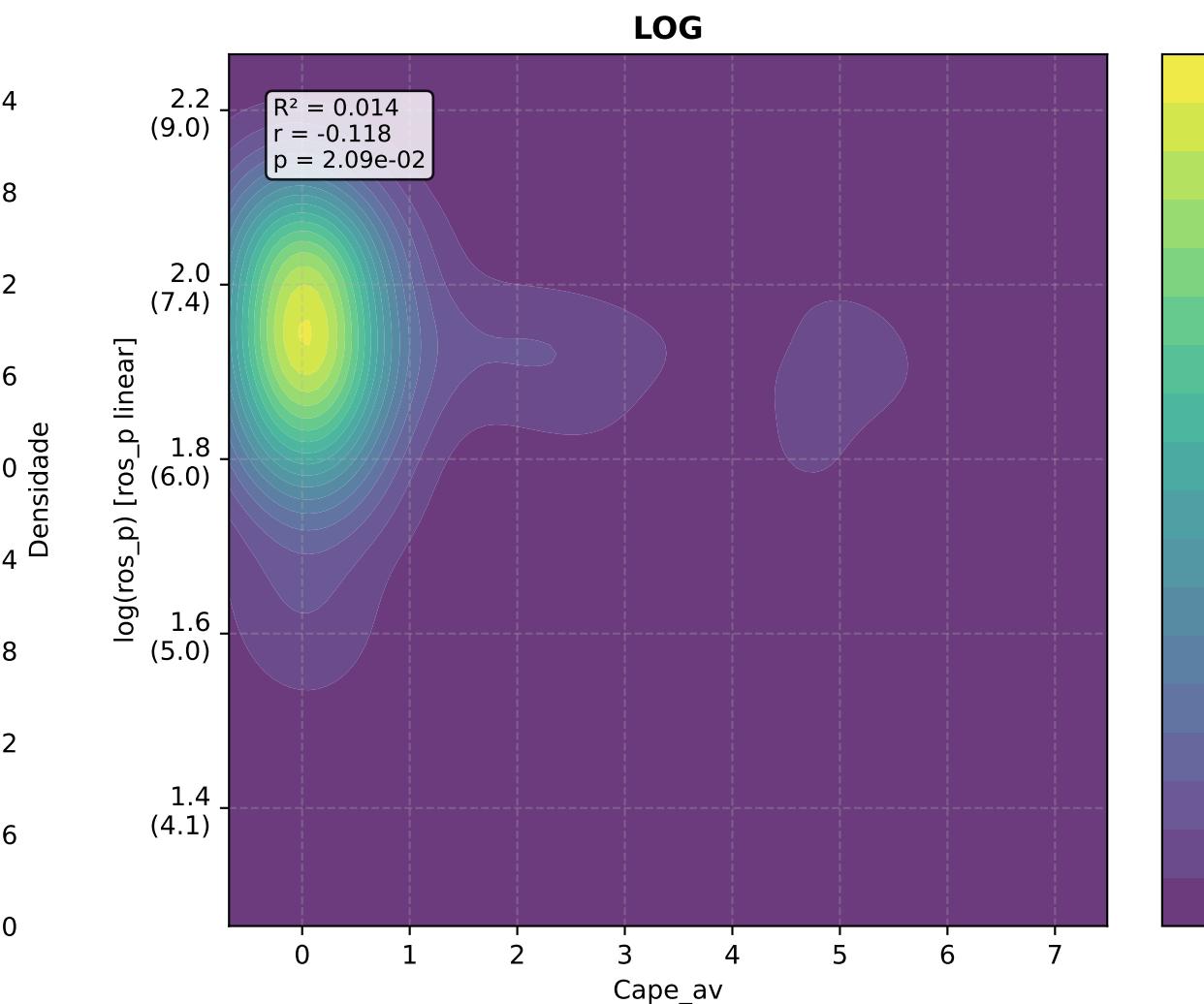
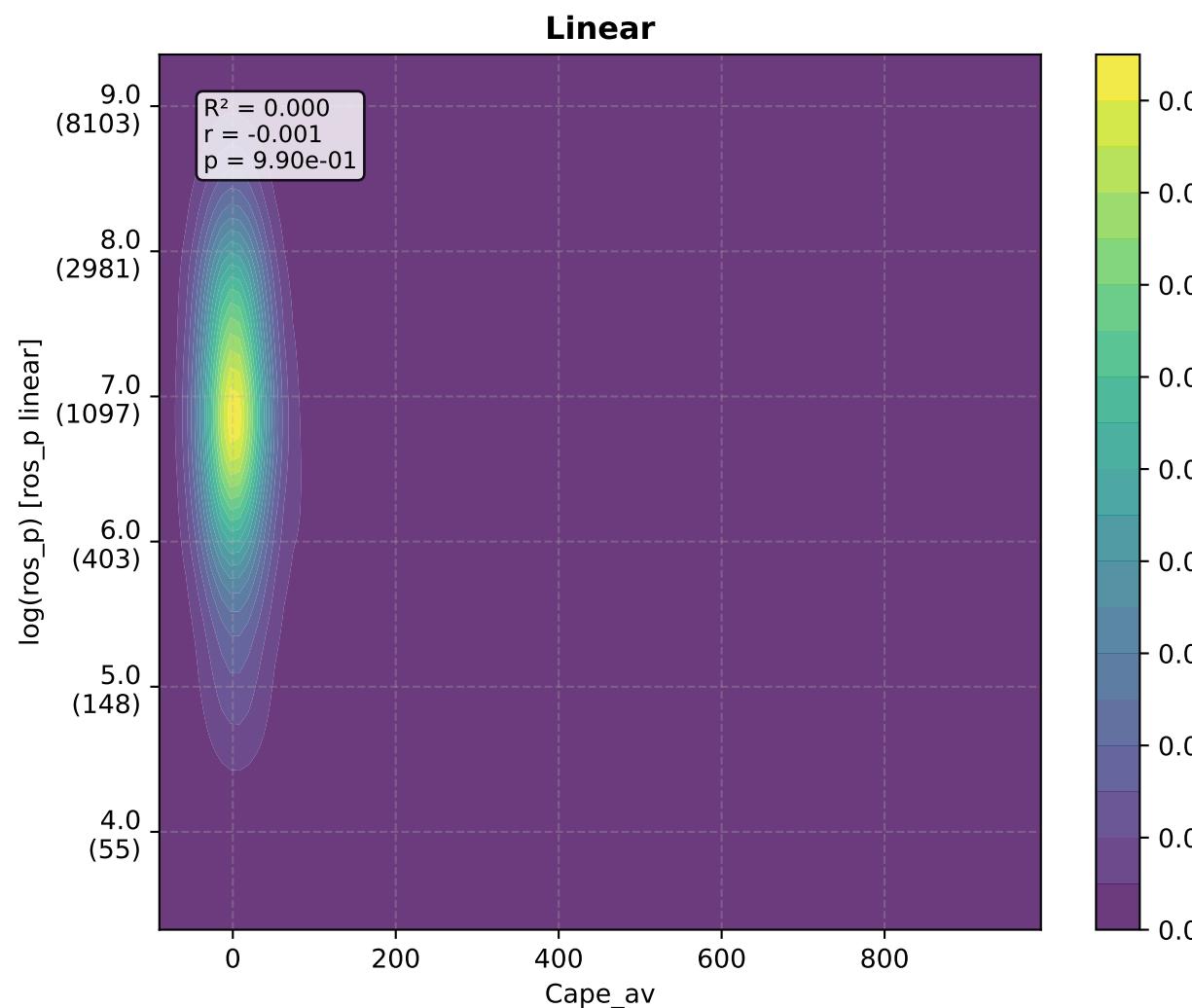
TotCC_p_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



BLH_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)

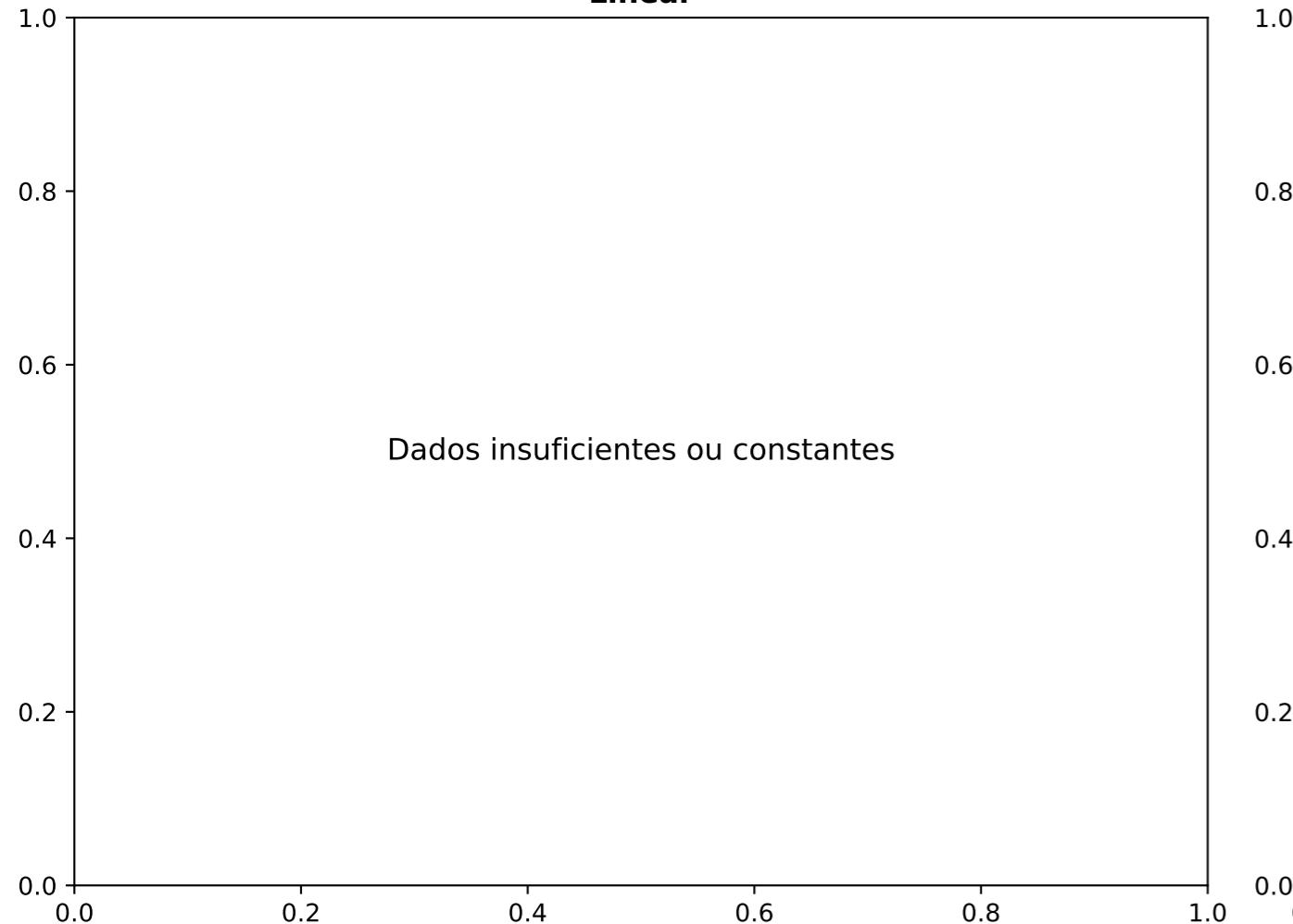


Cape_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)

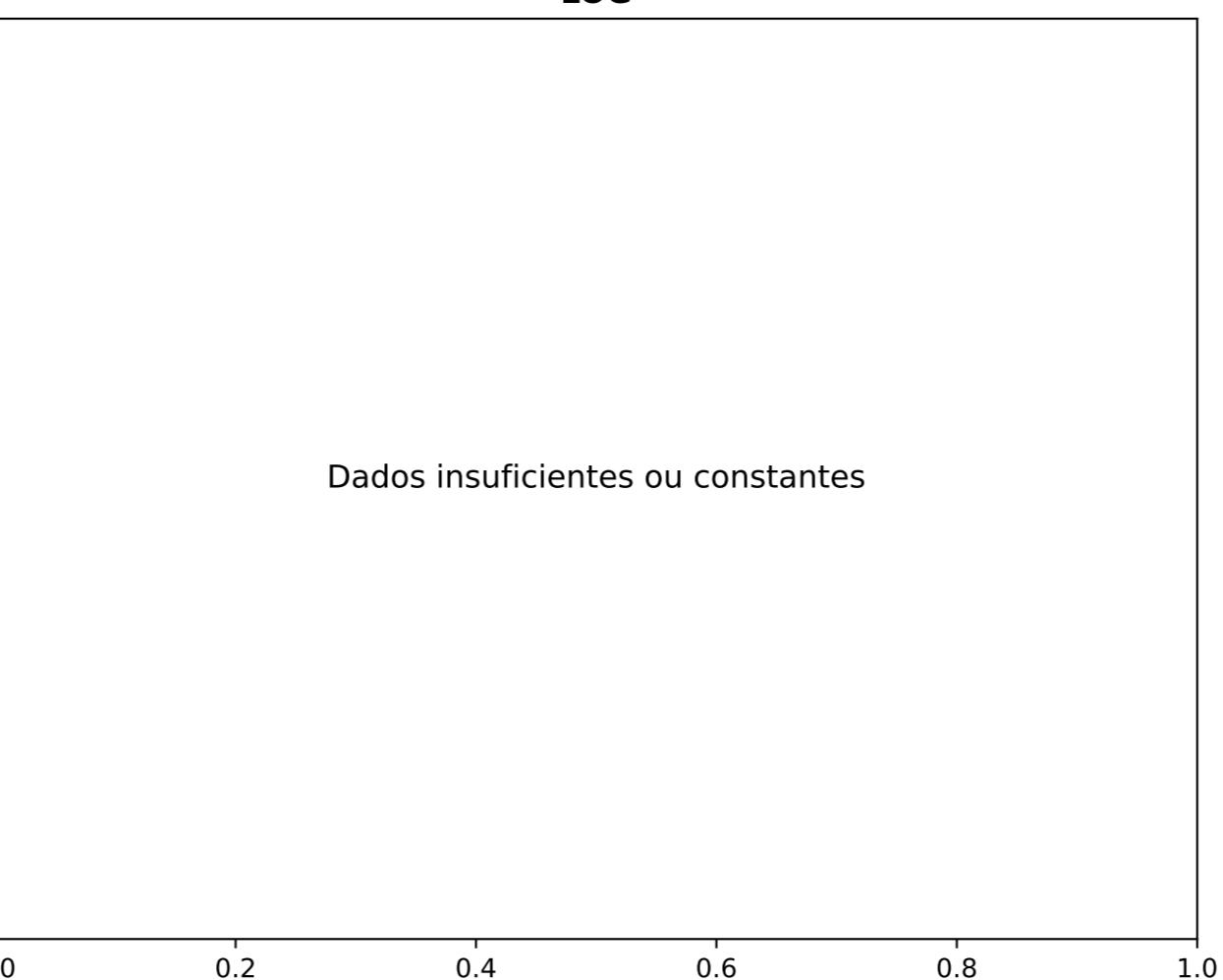


Cin_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)

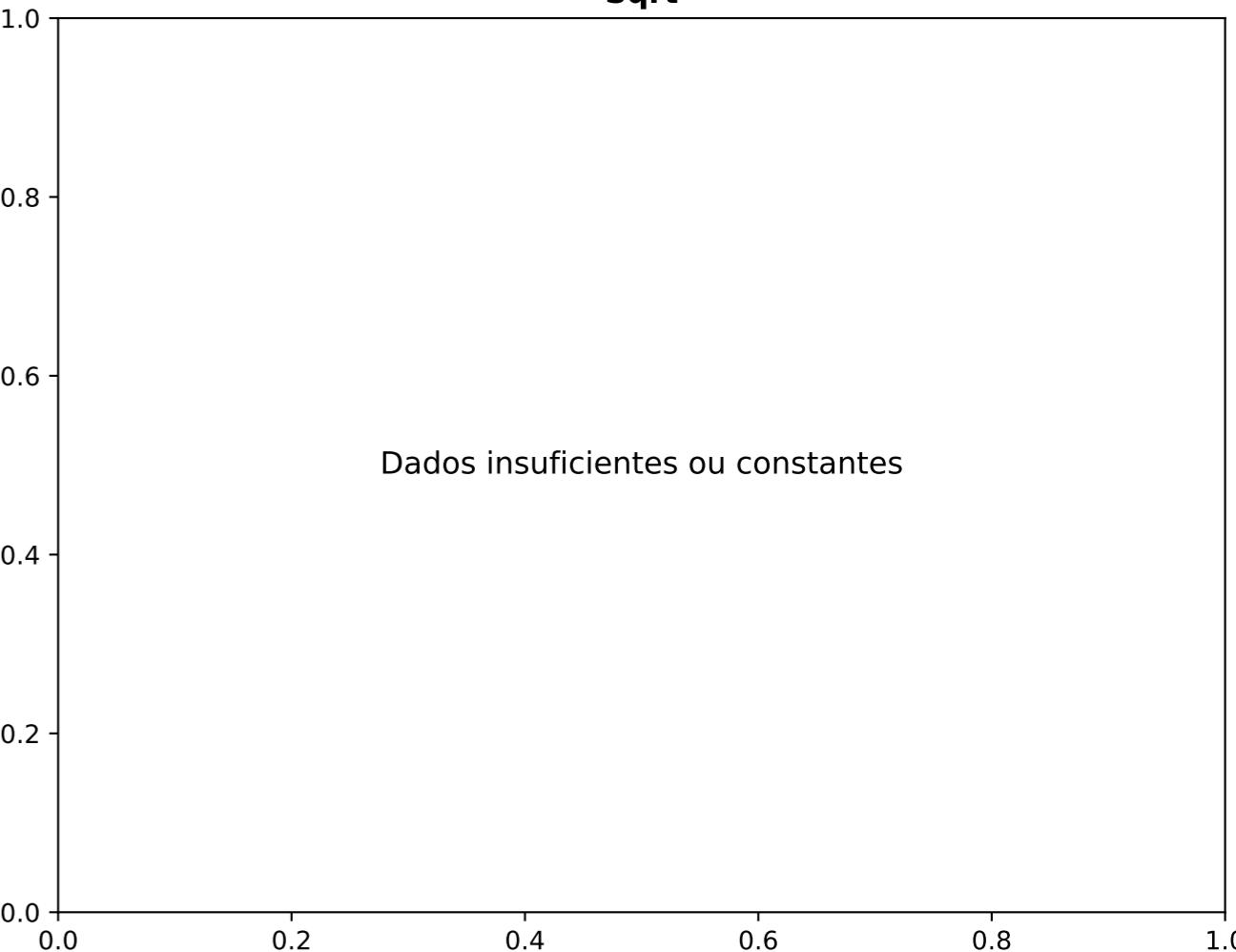
Linear



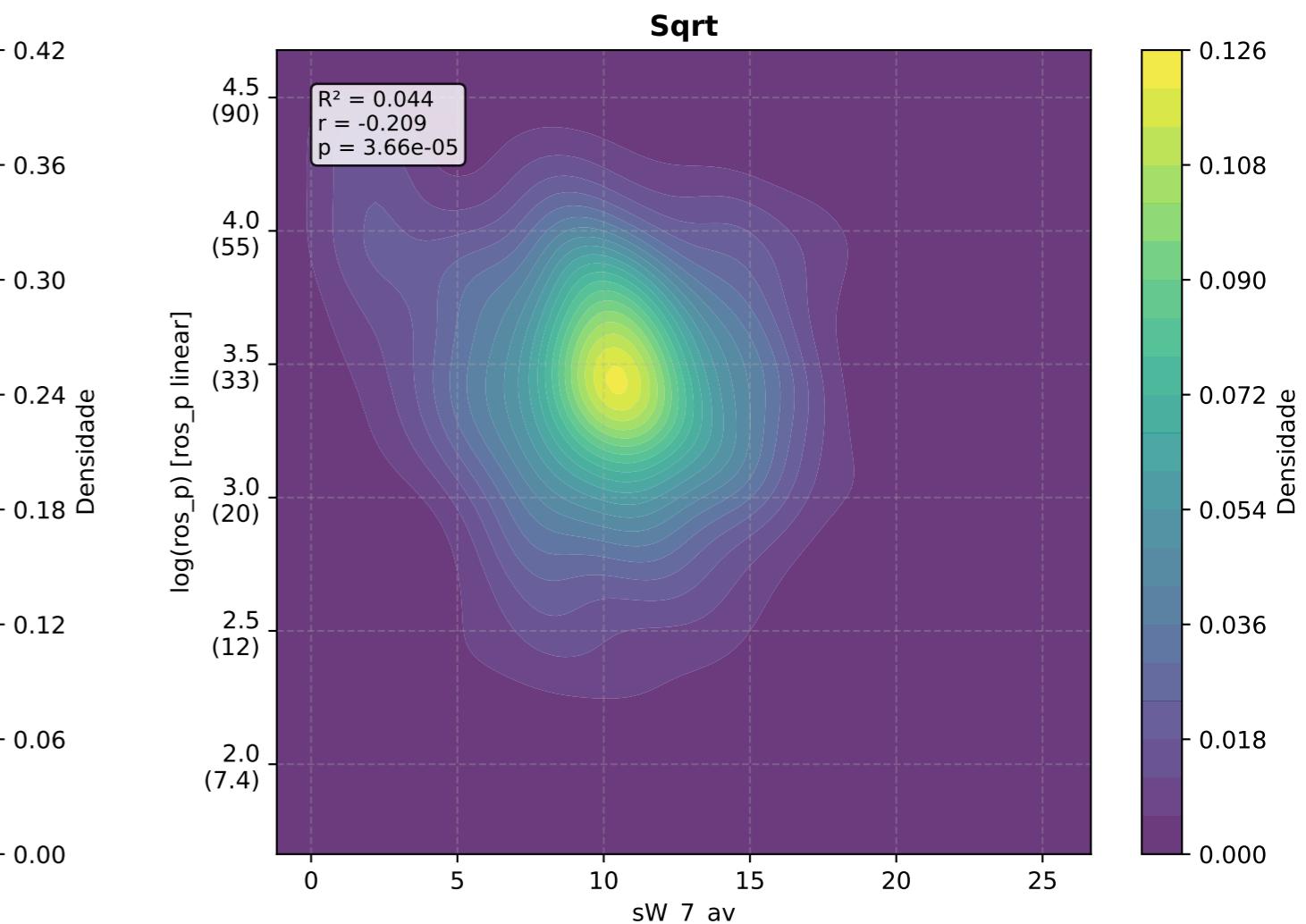
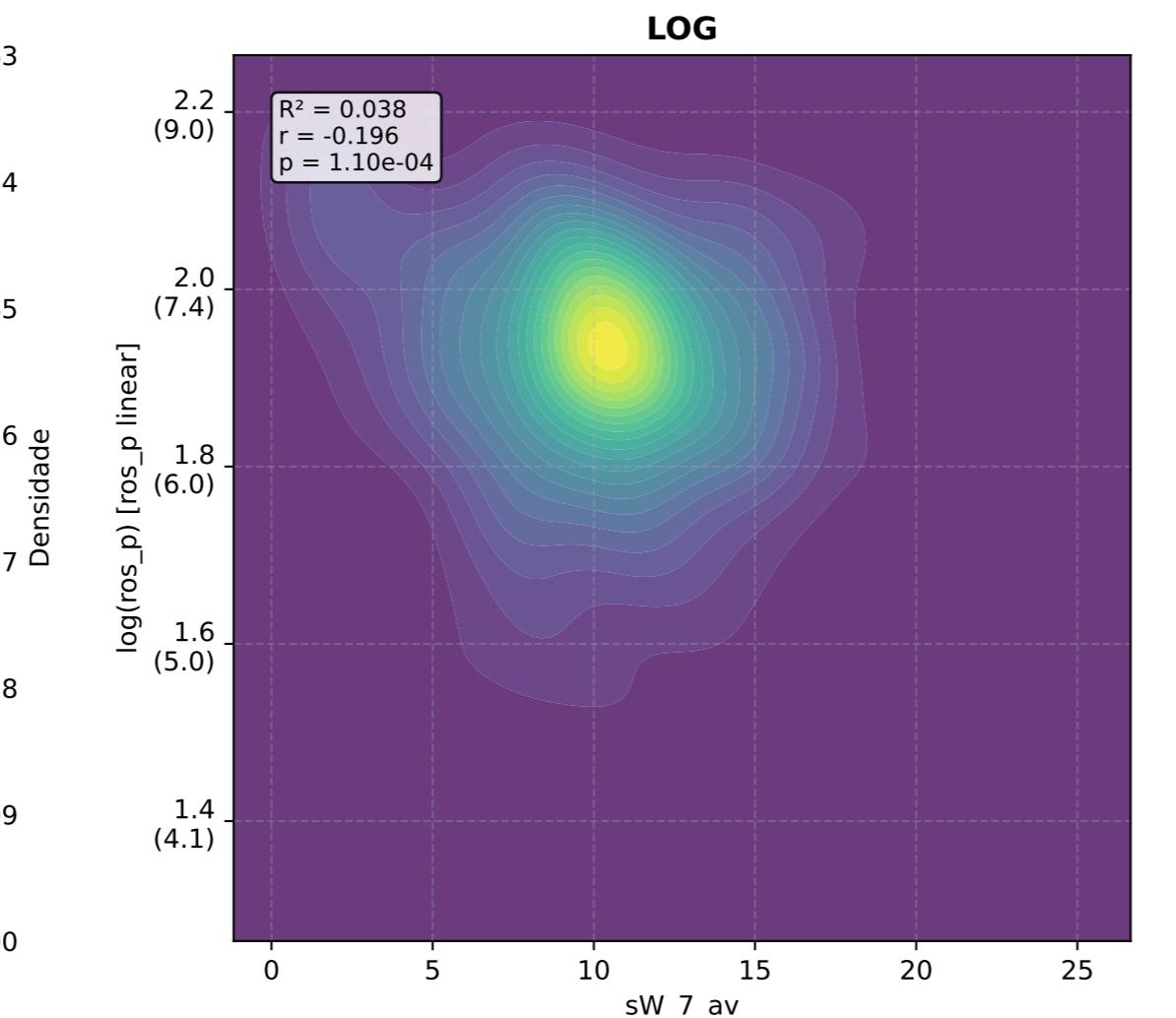
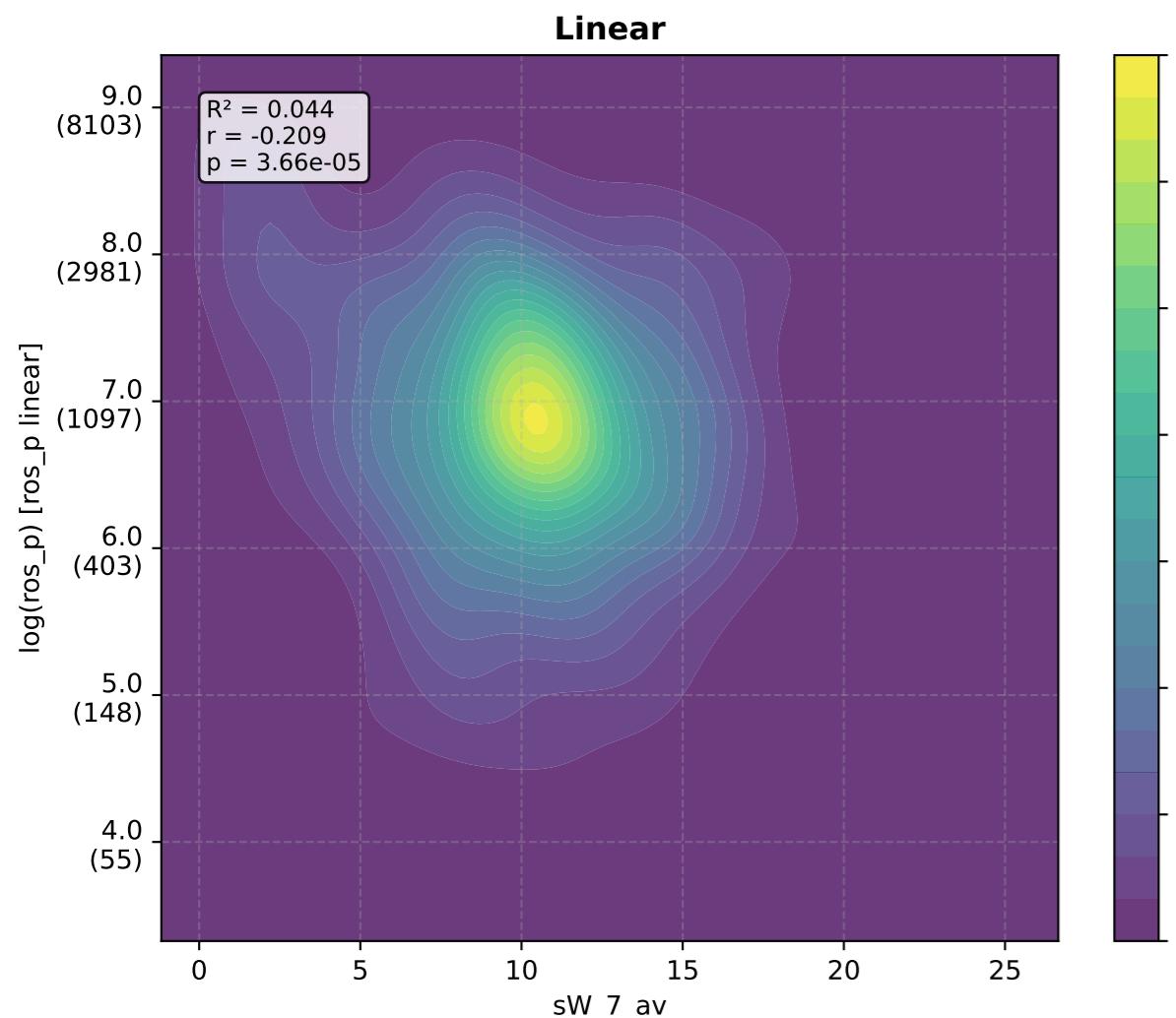
LOG



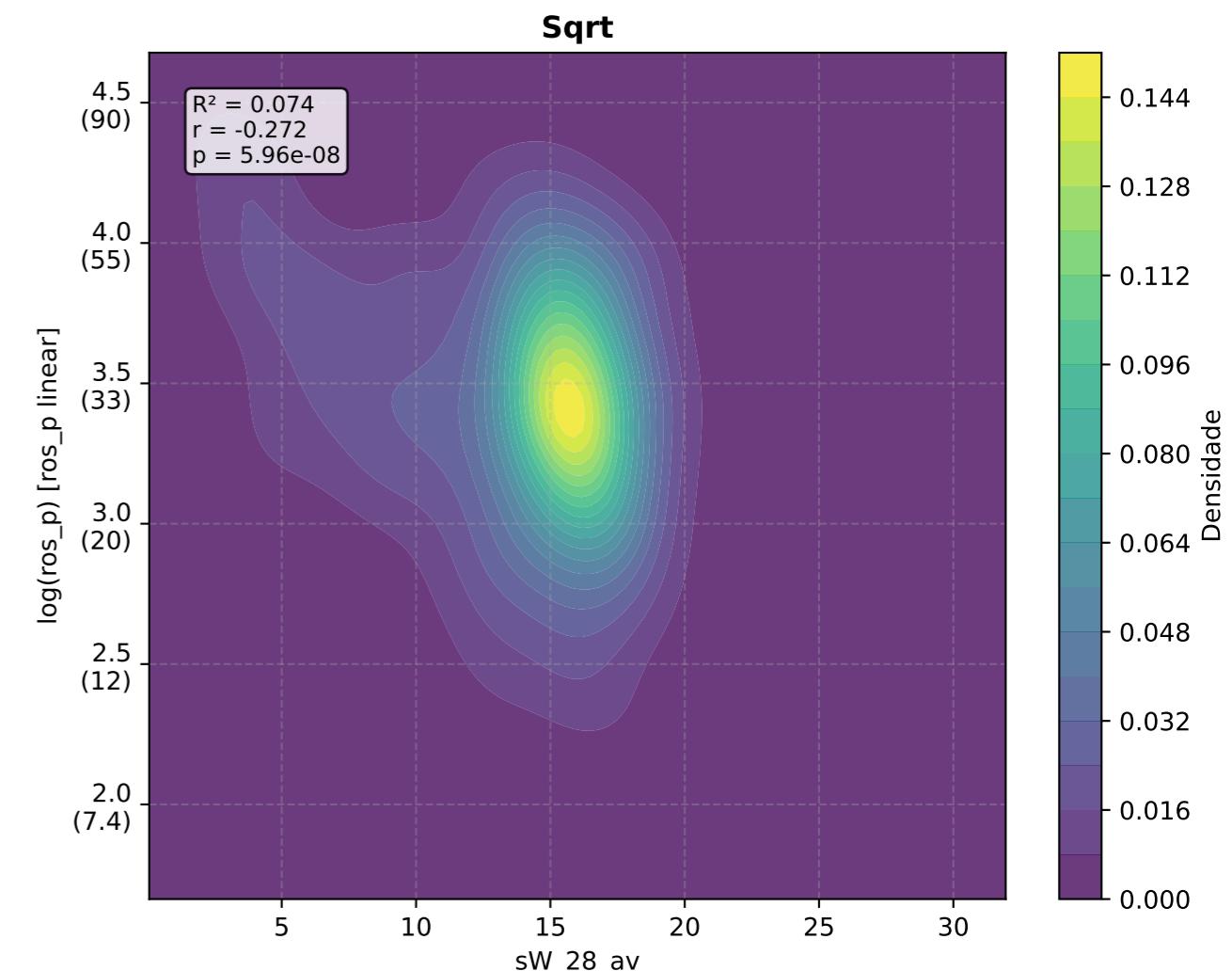
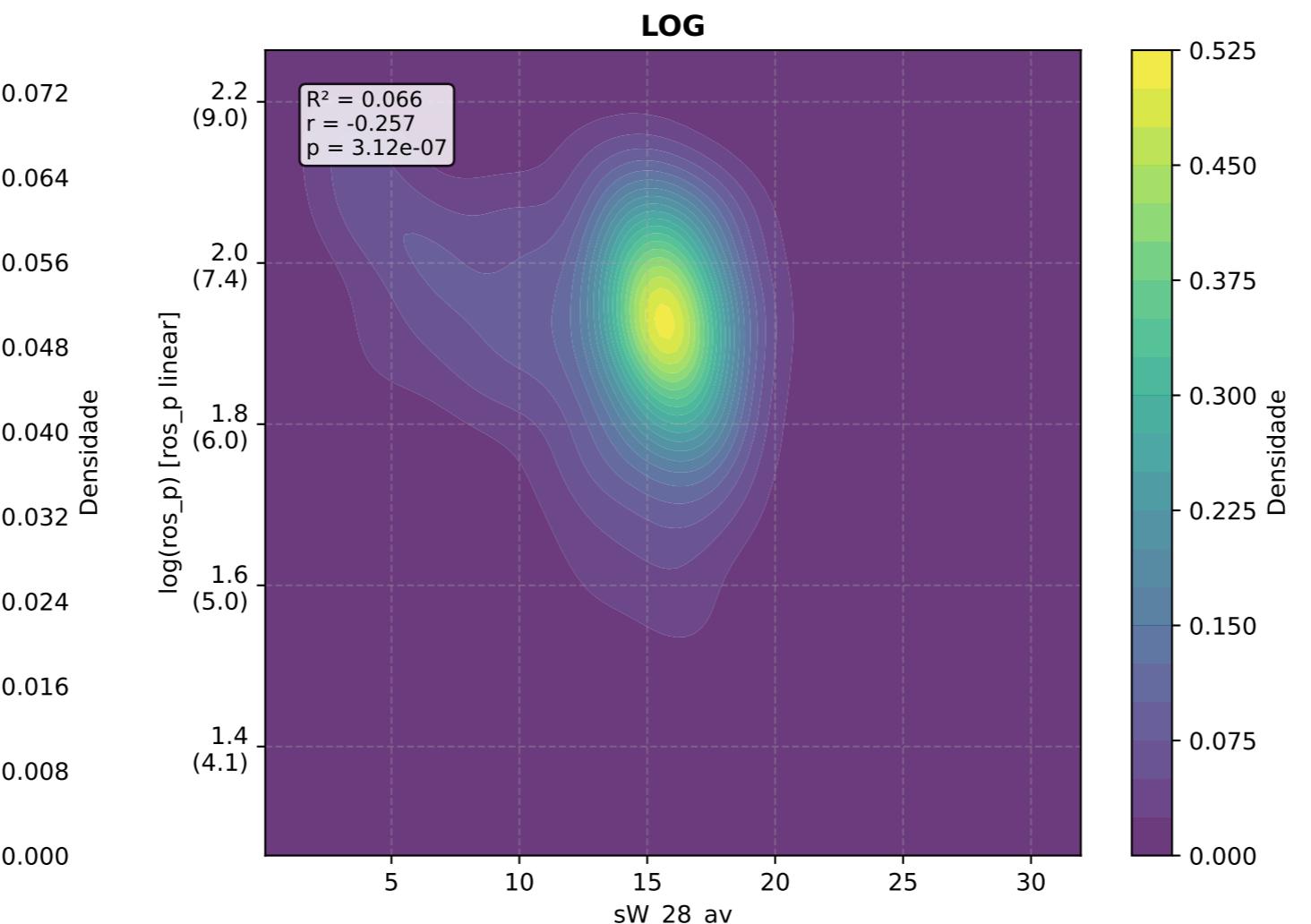
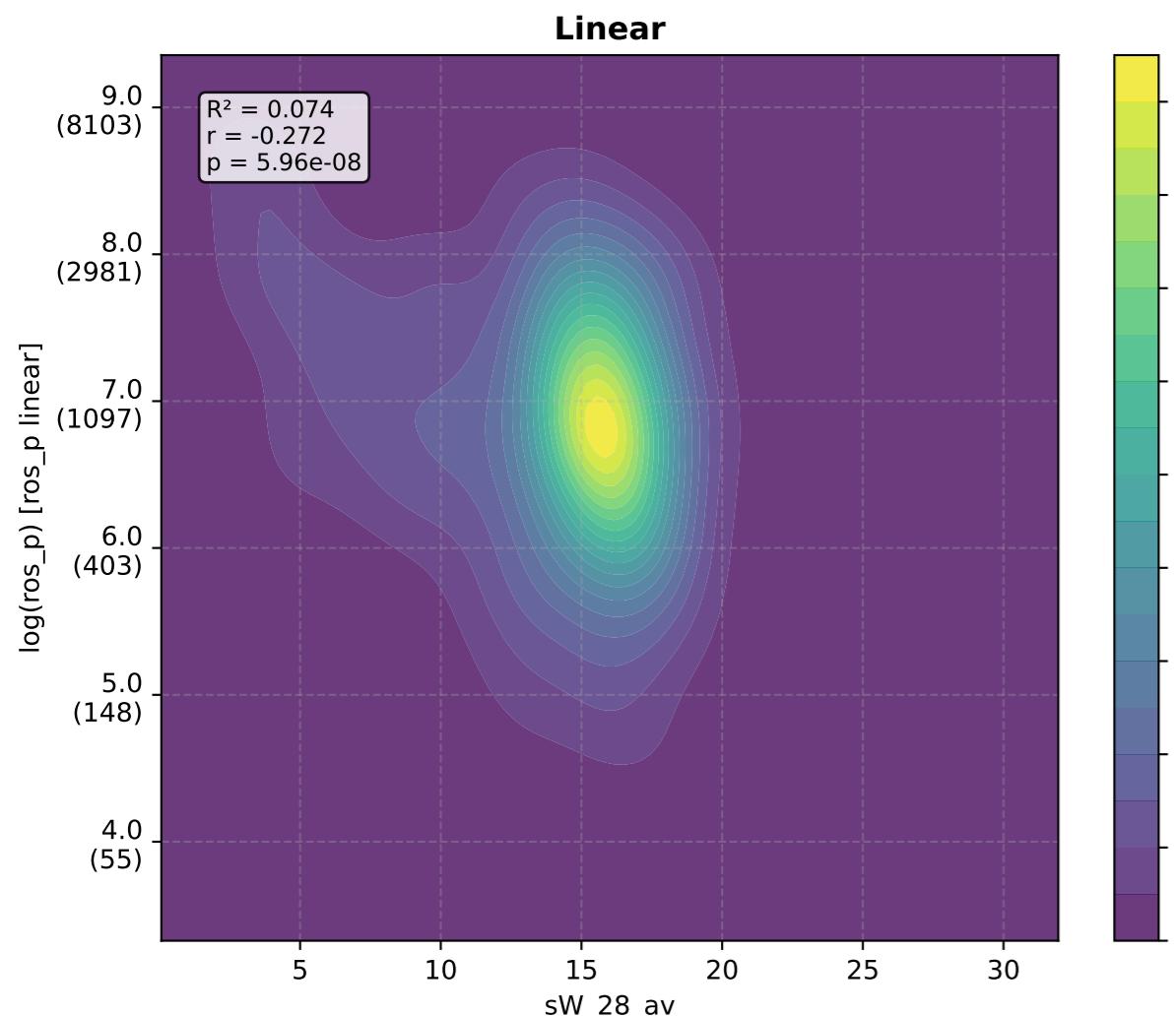
Sqrt



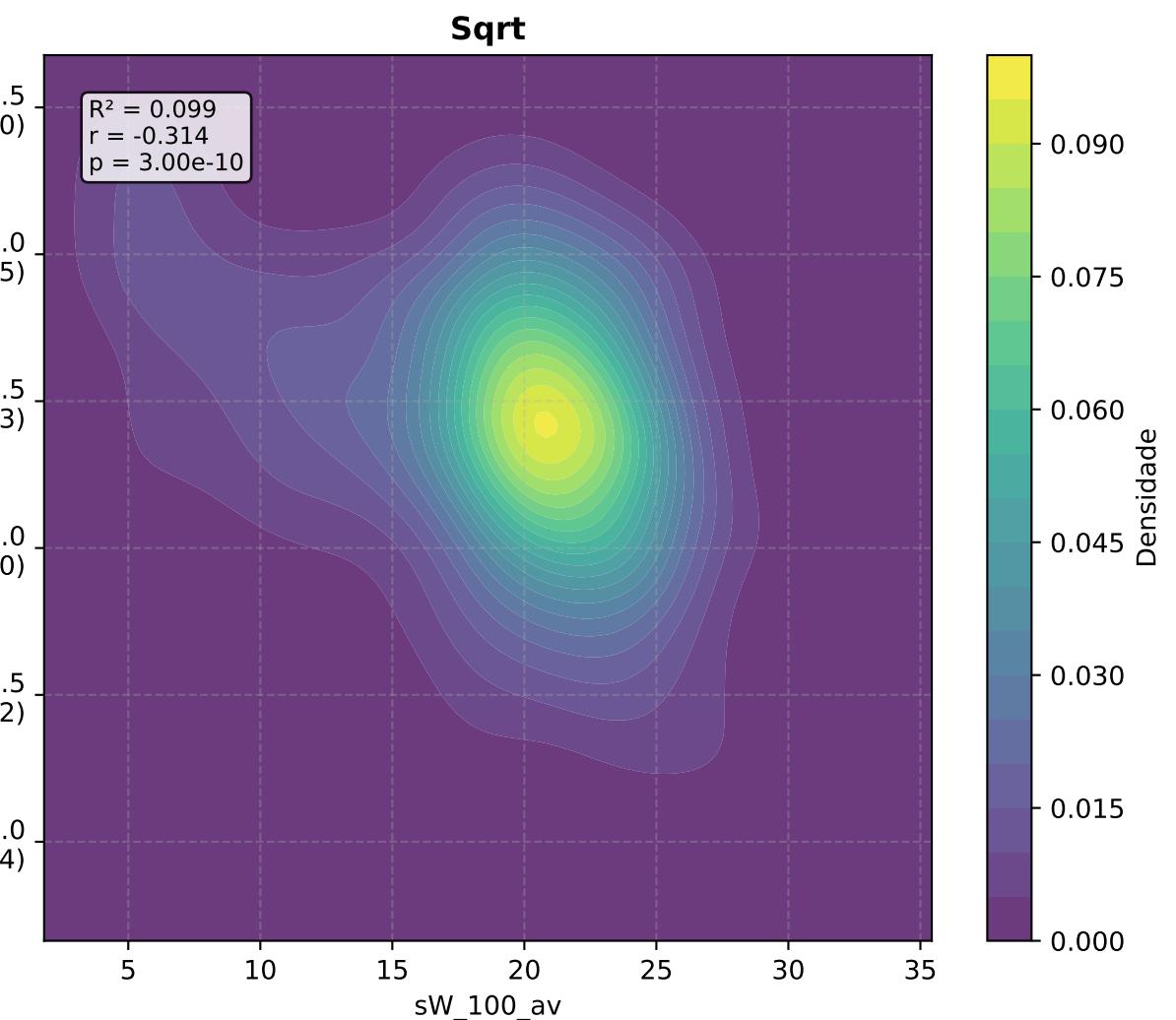
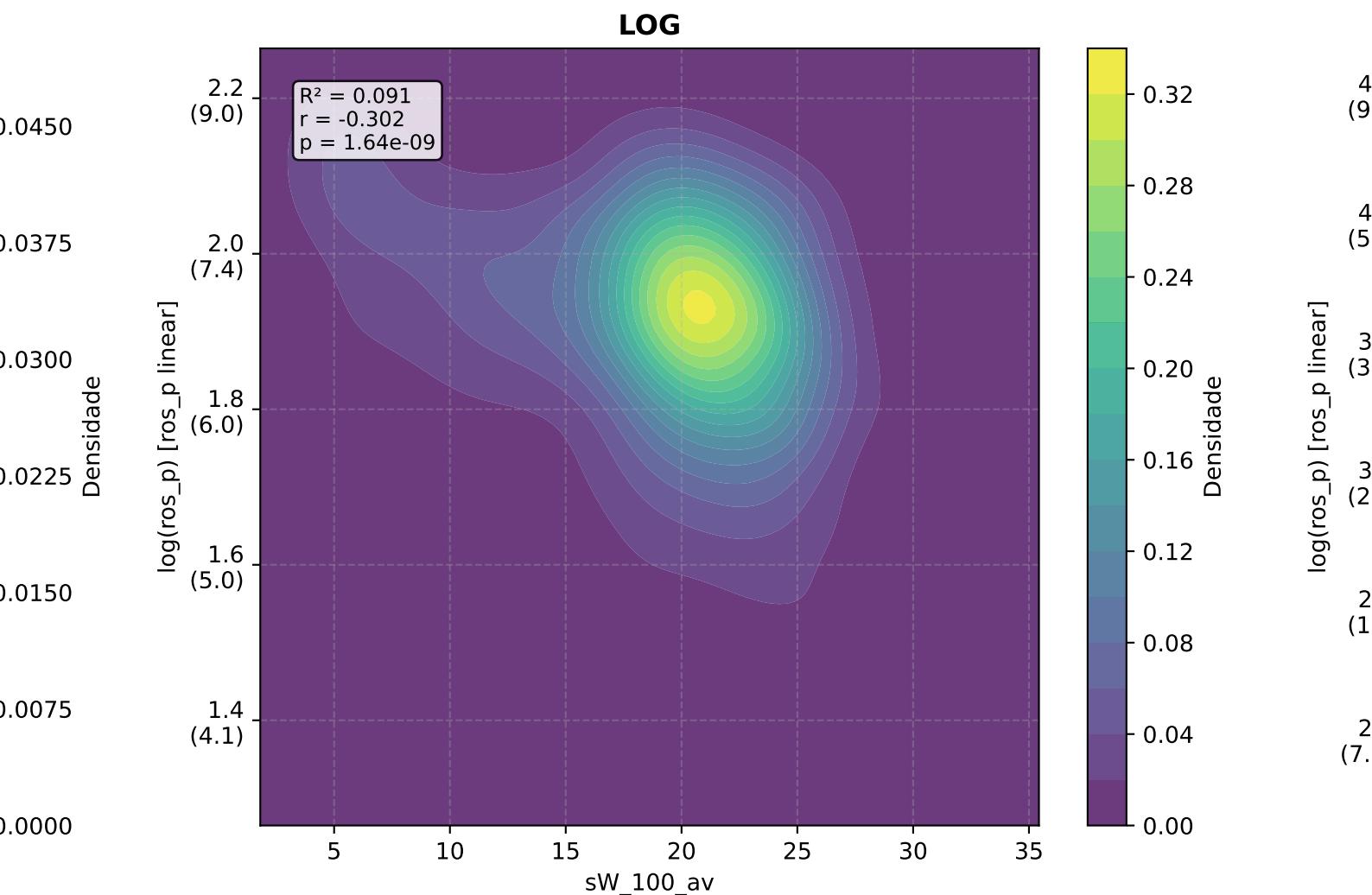
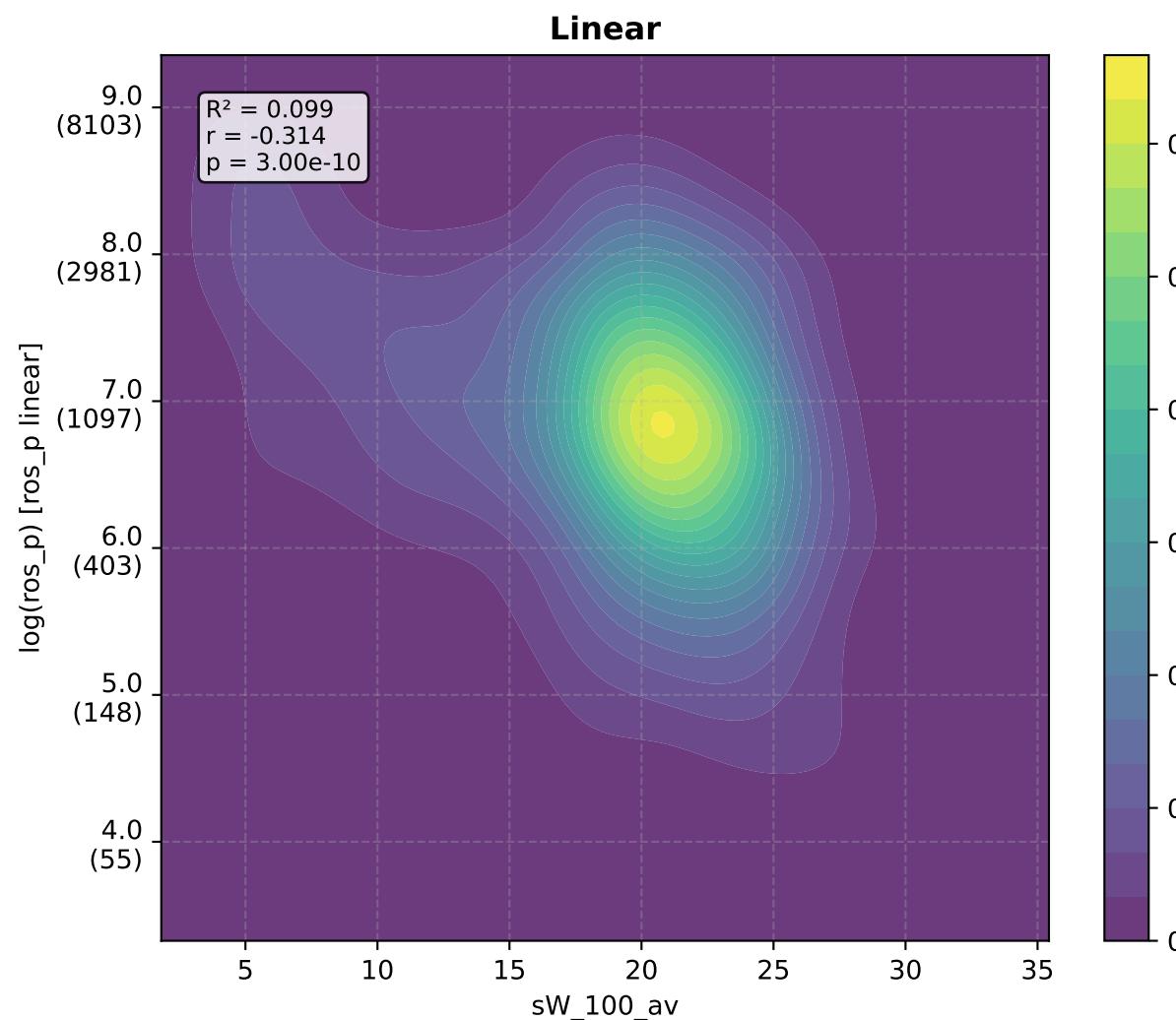
sW_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



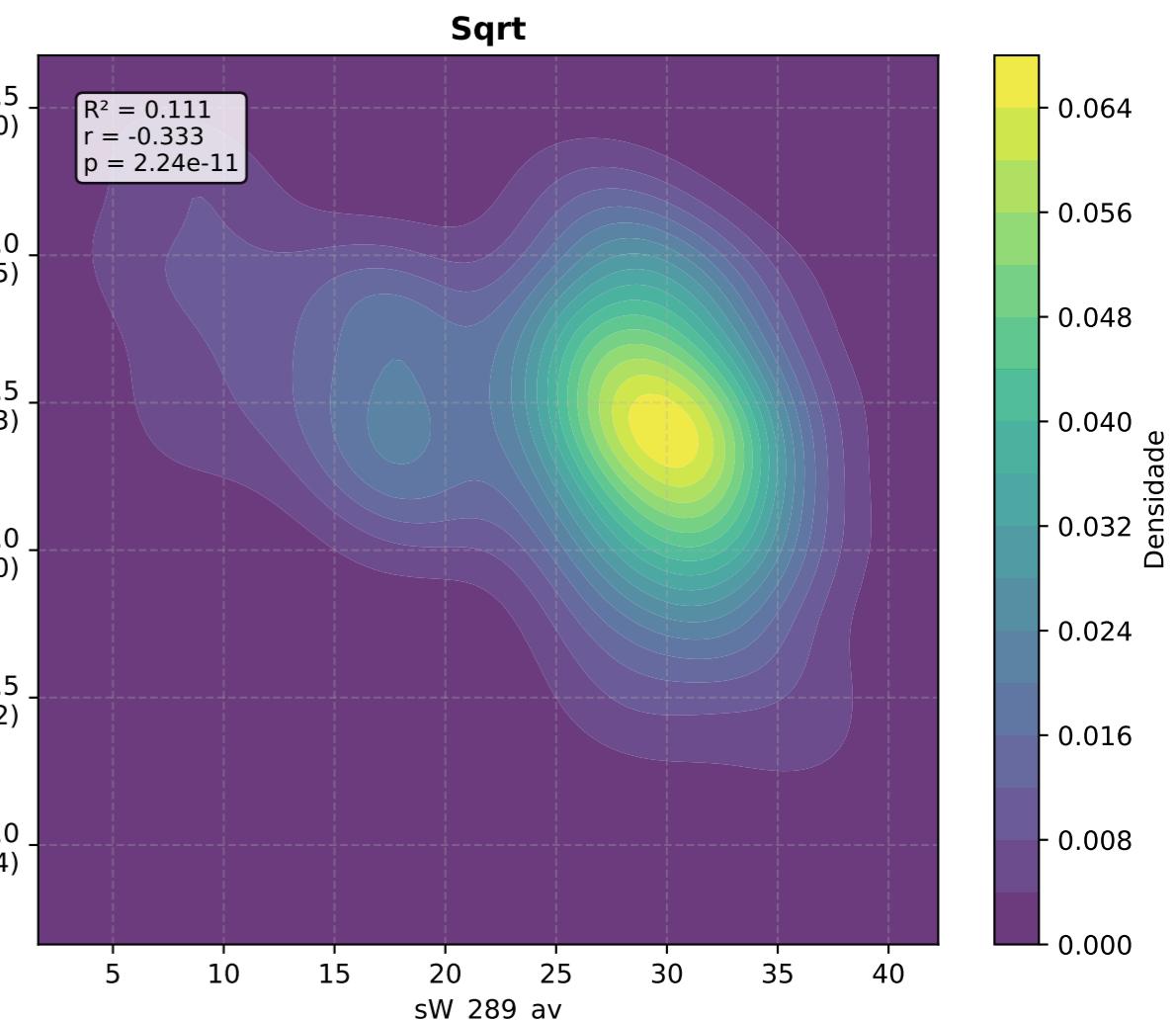
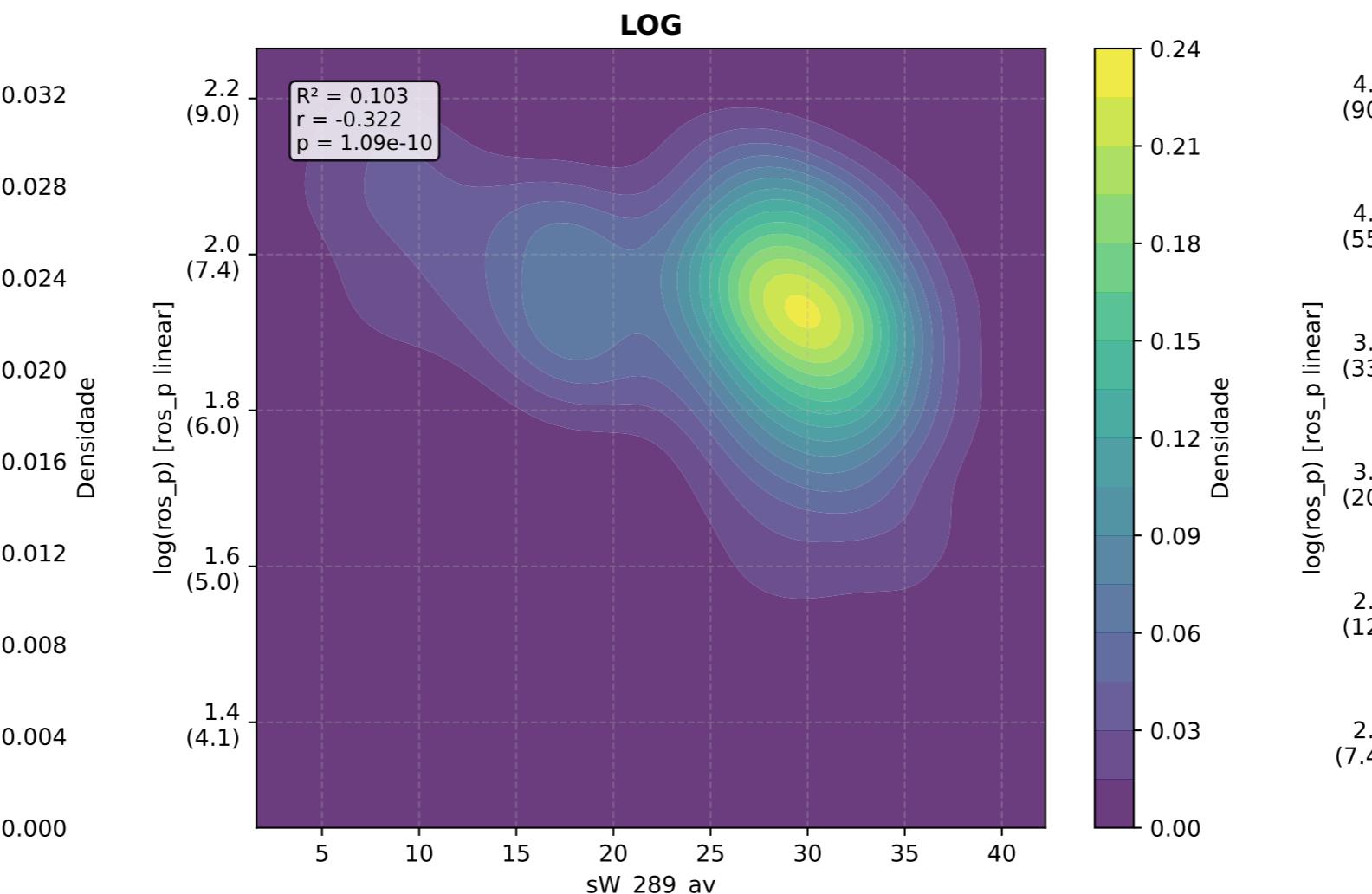
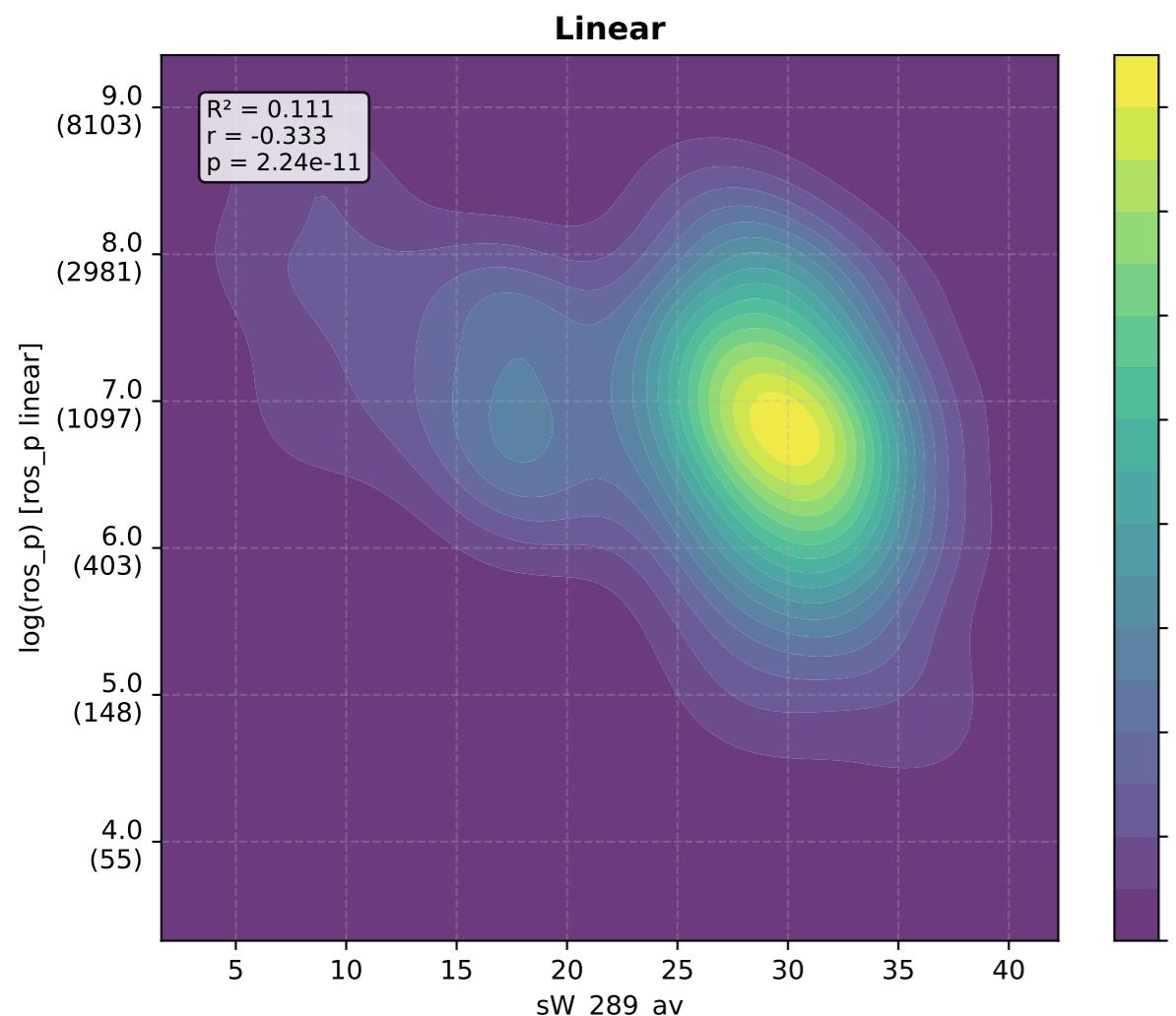
sW_28_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



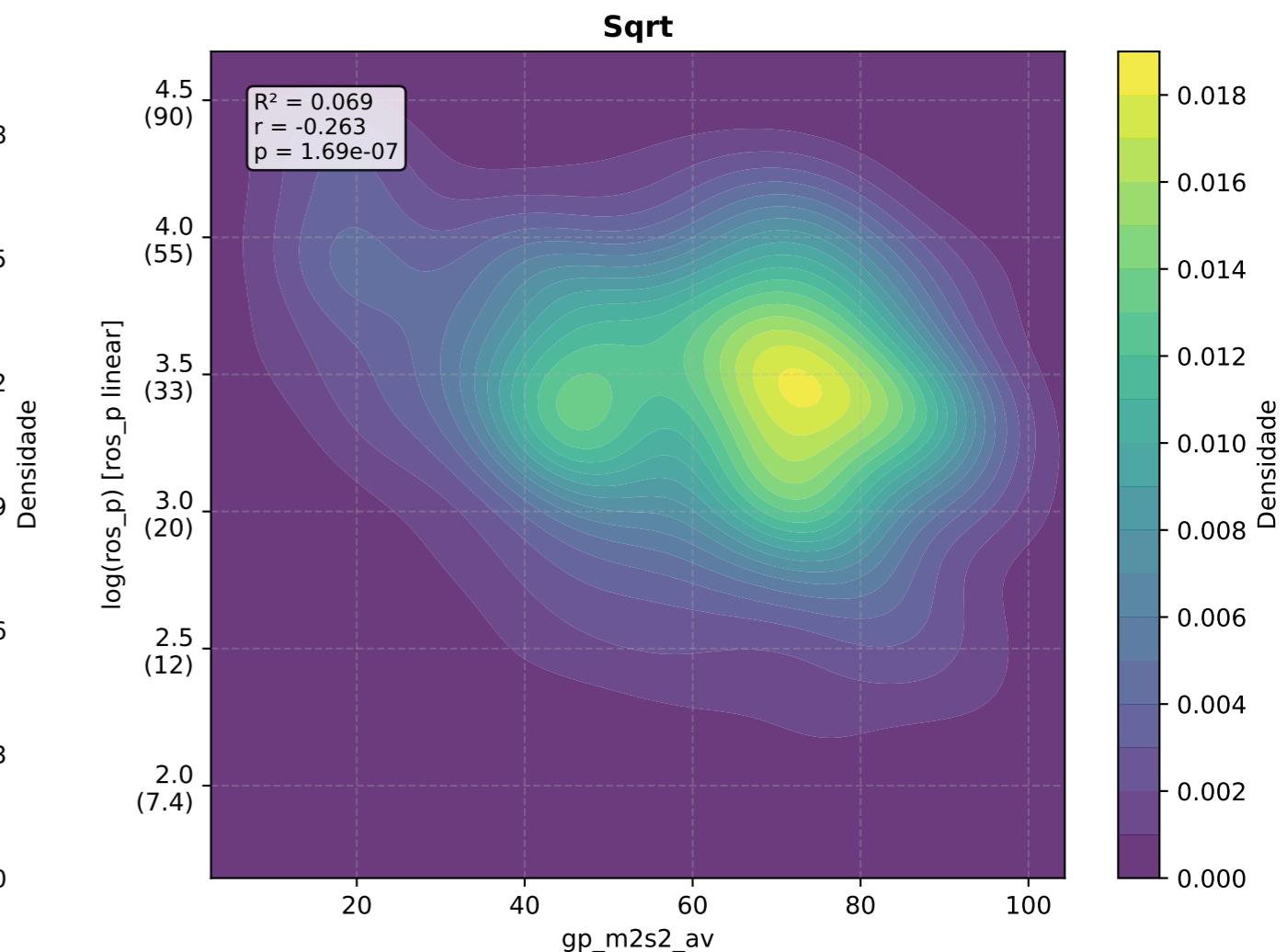
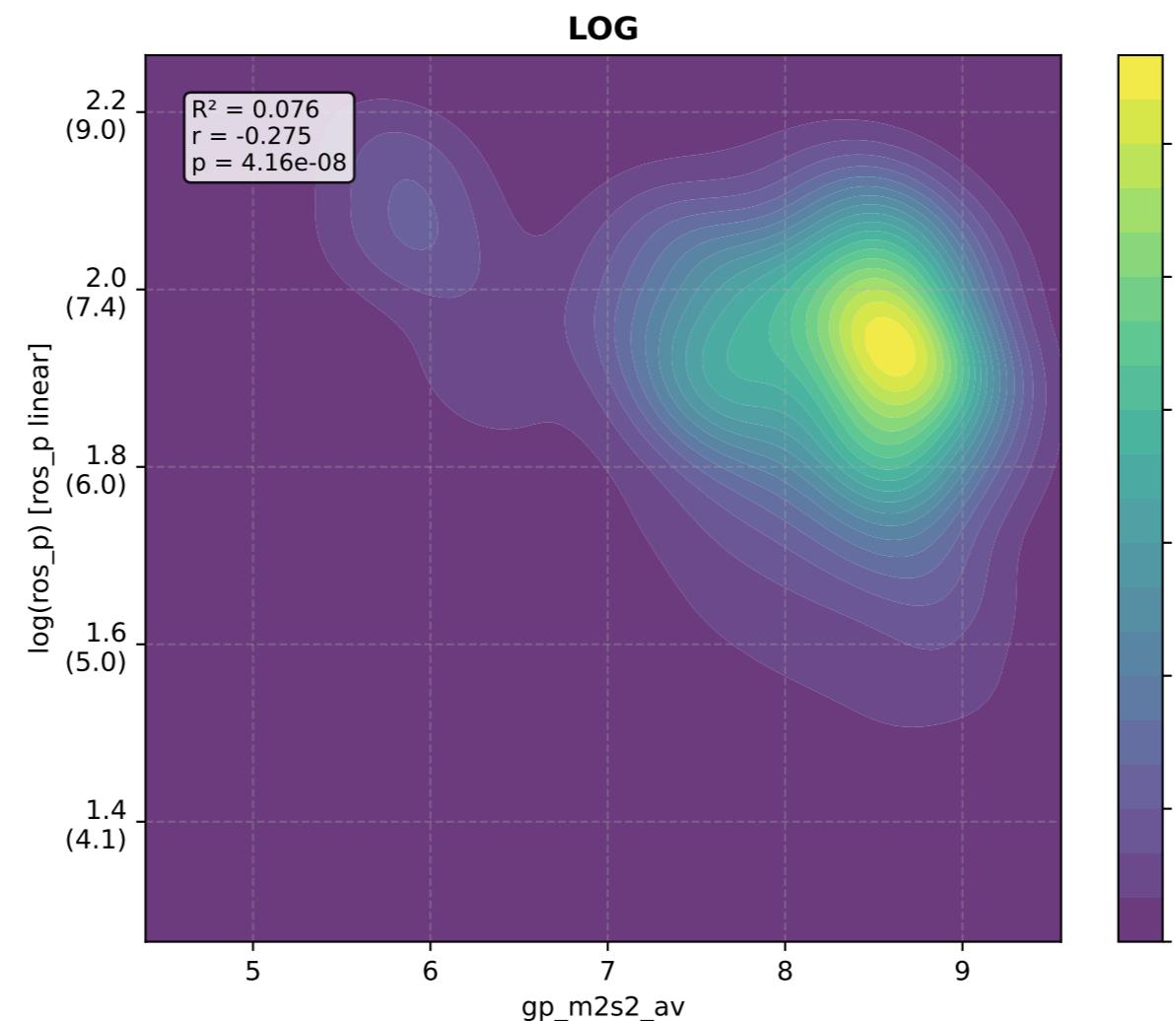
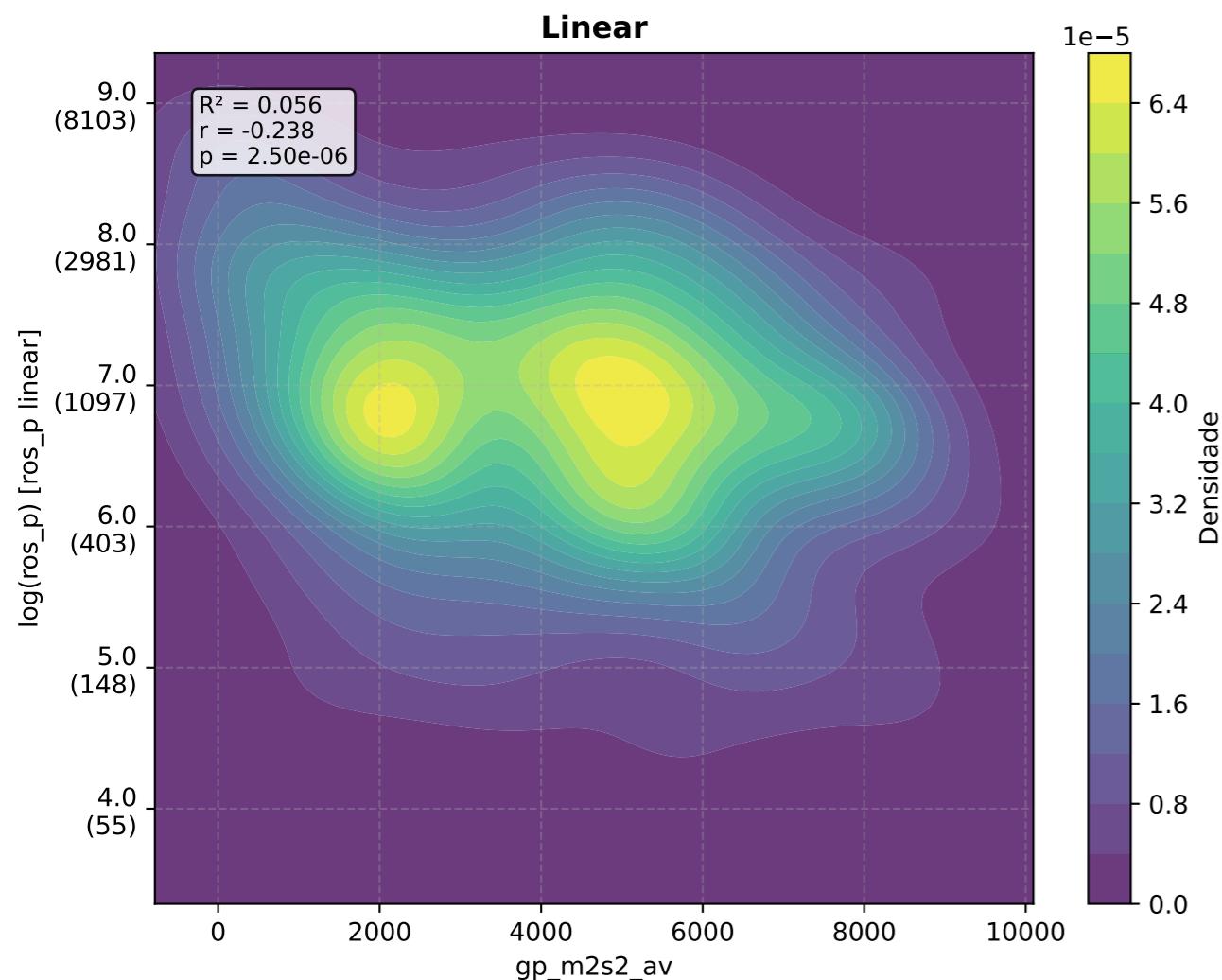
sW_100_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



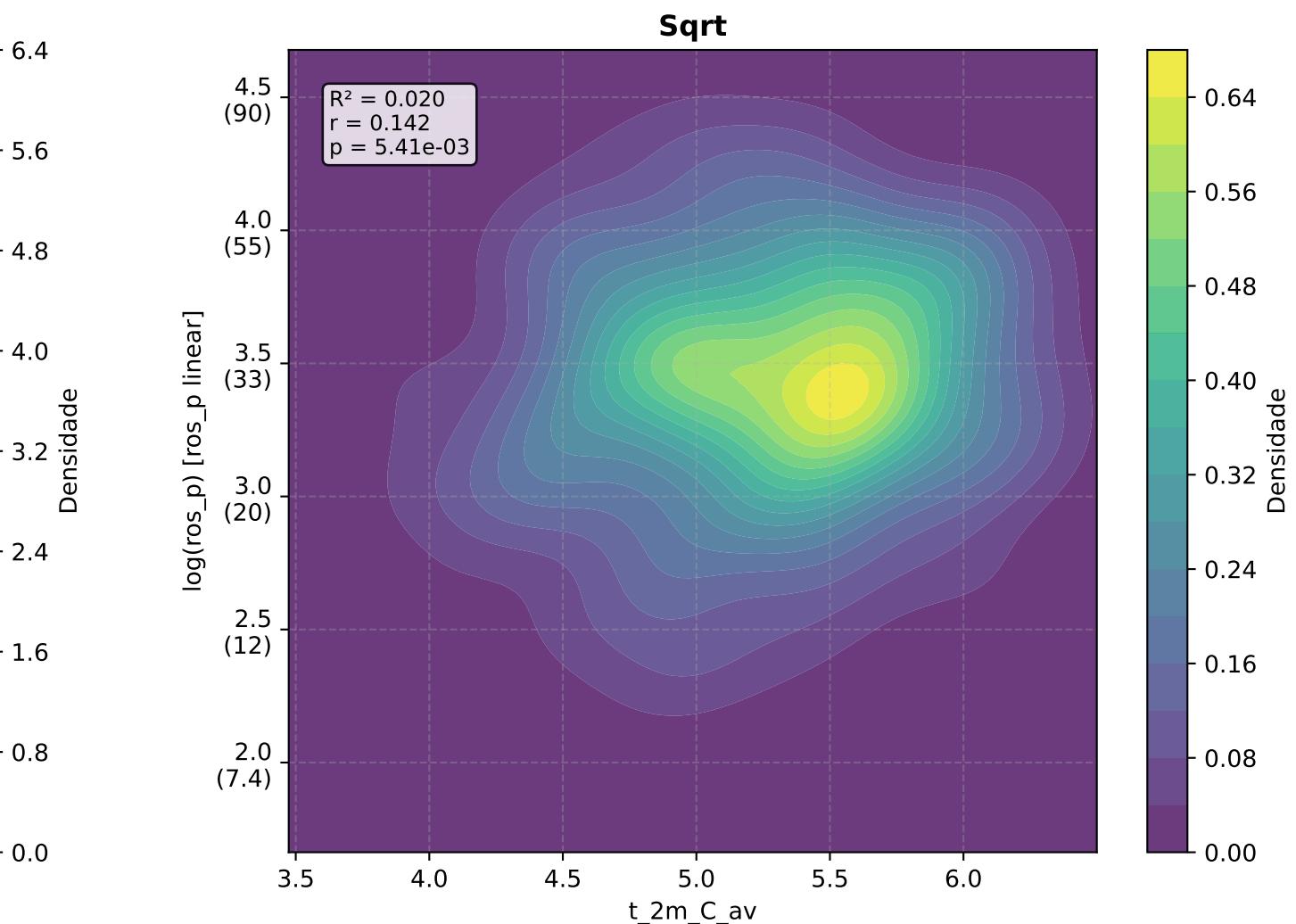
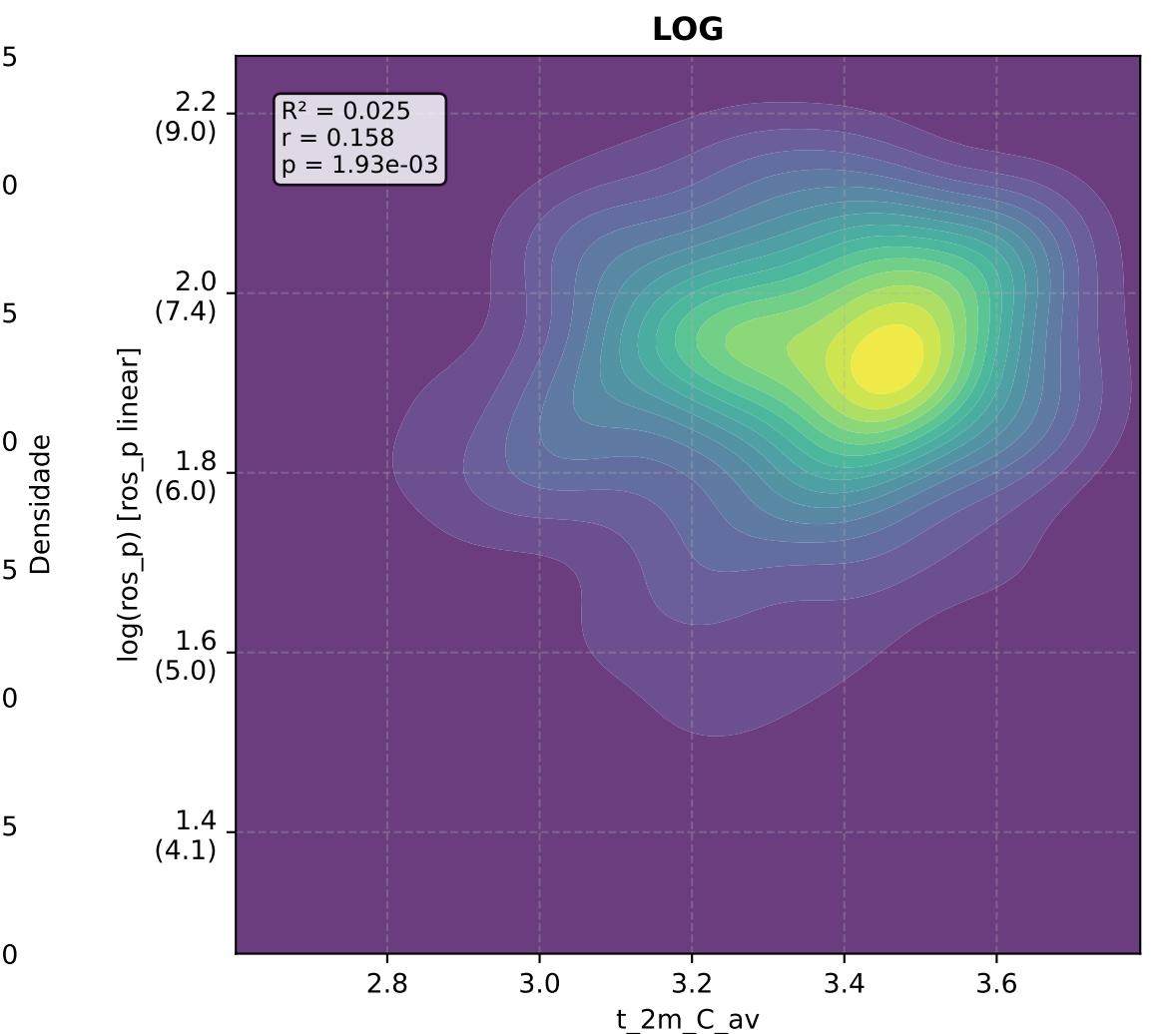
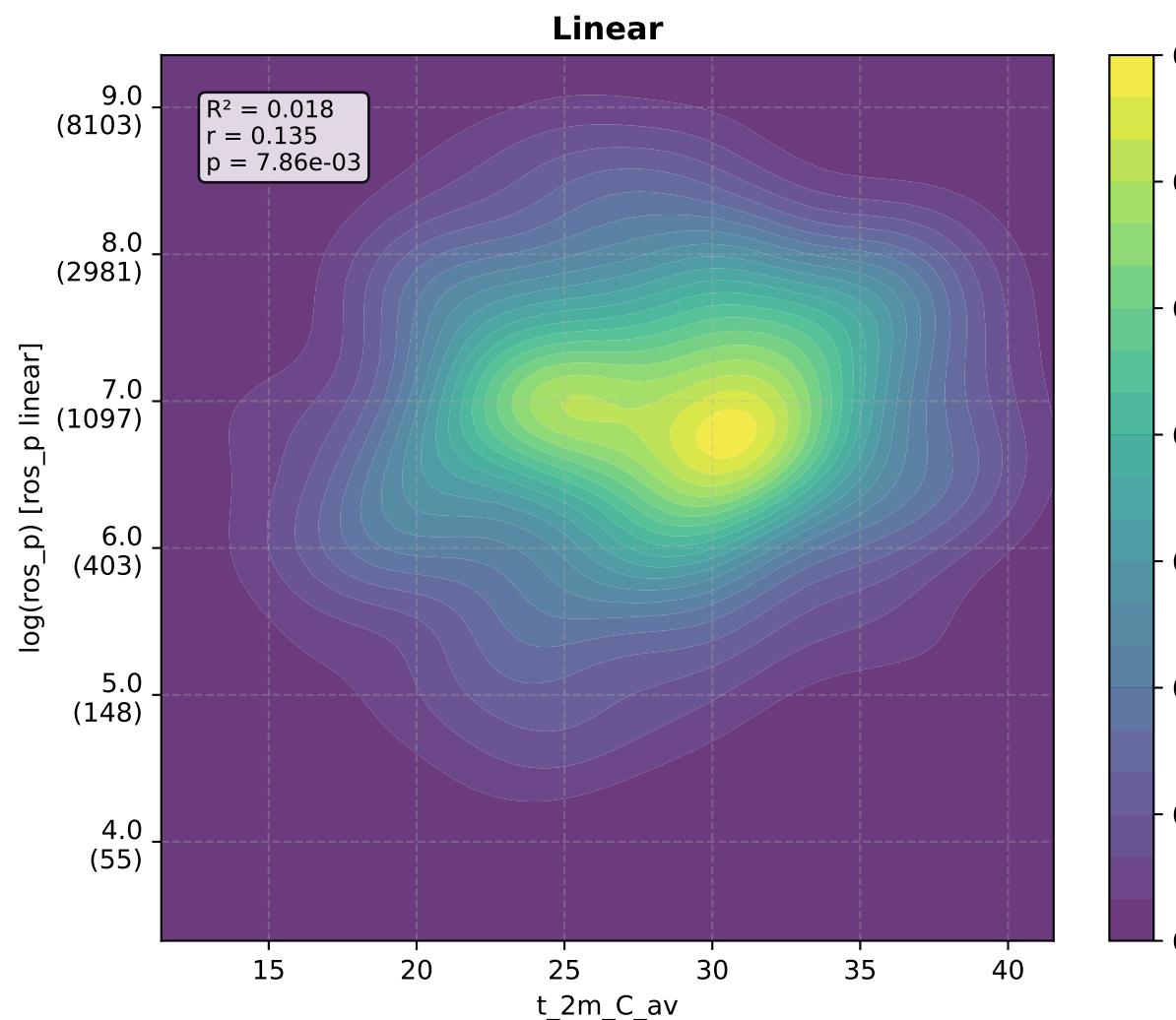
sW_289_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



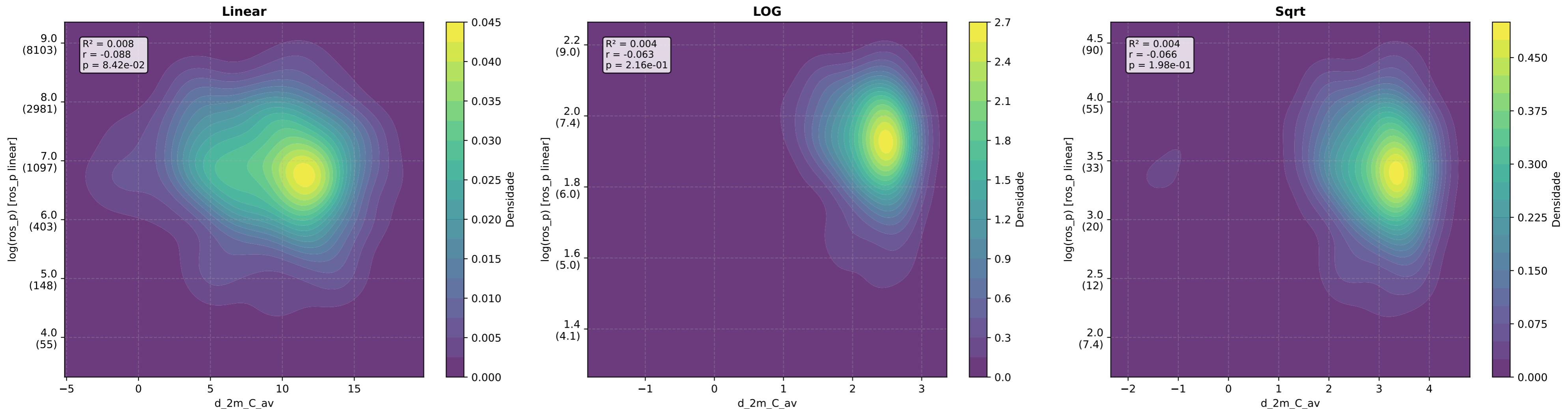
gp_m2s2_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



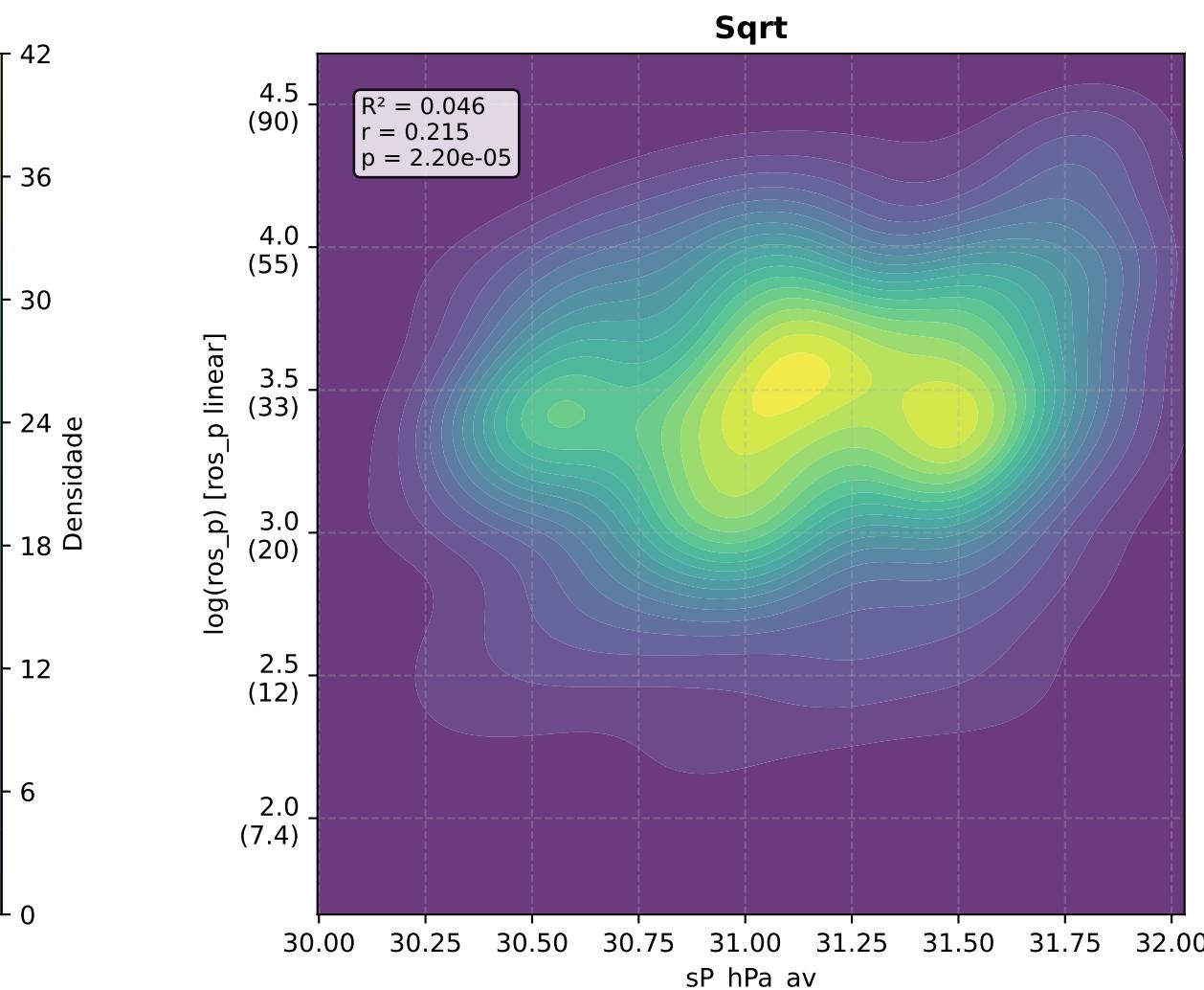
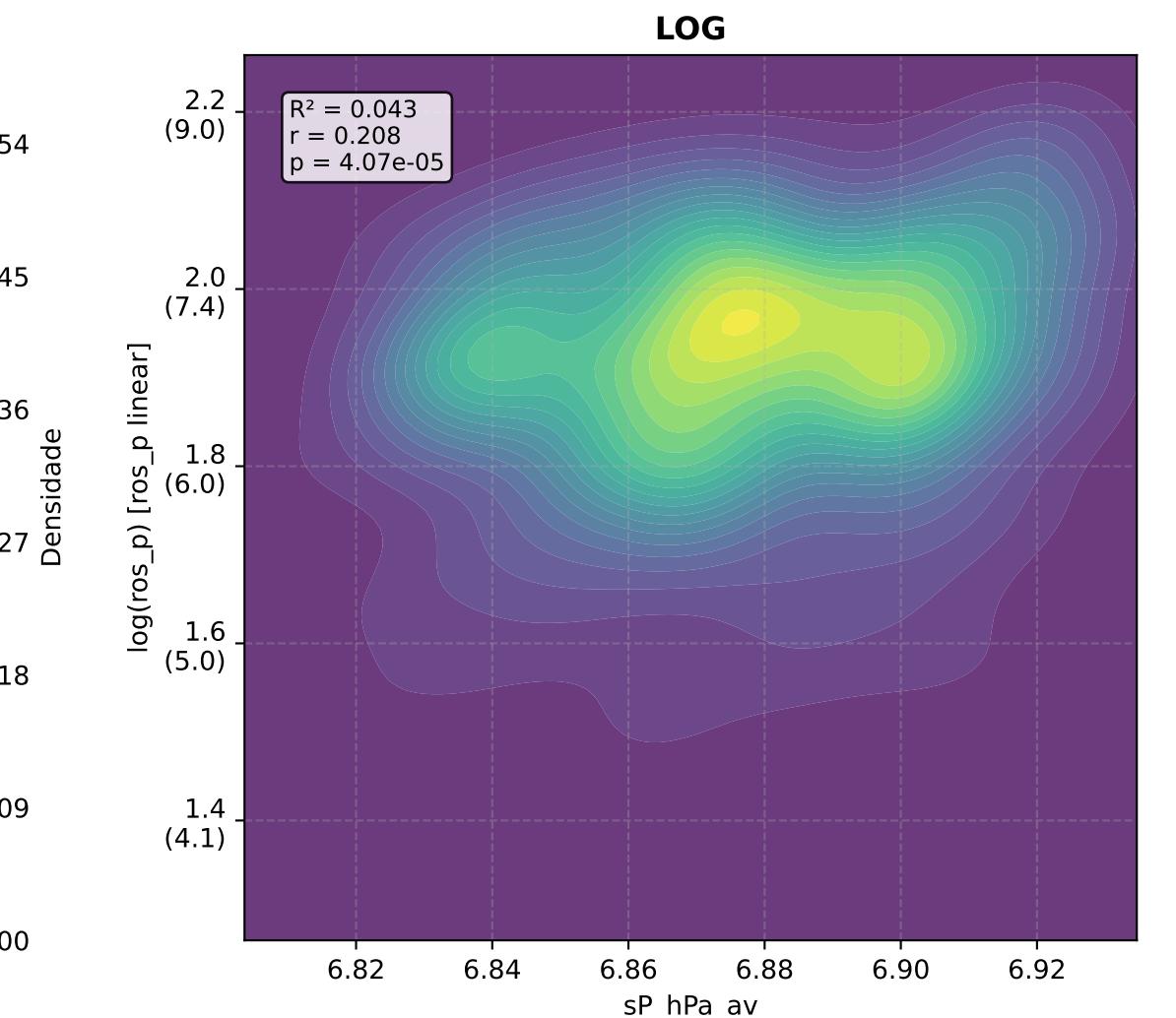
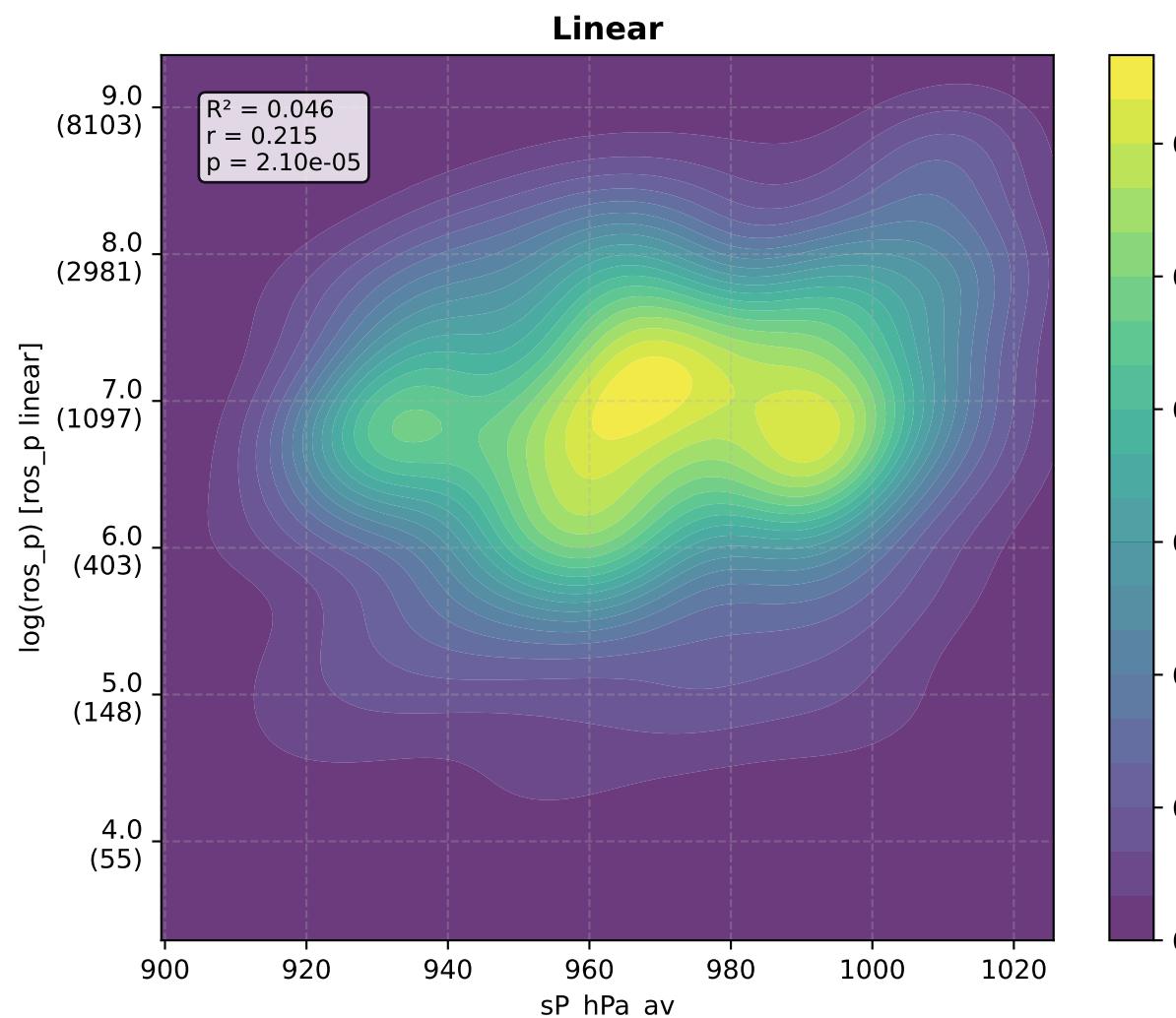
t_2m_C_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



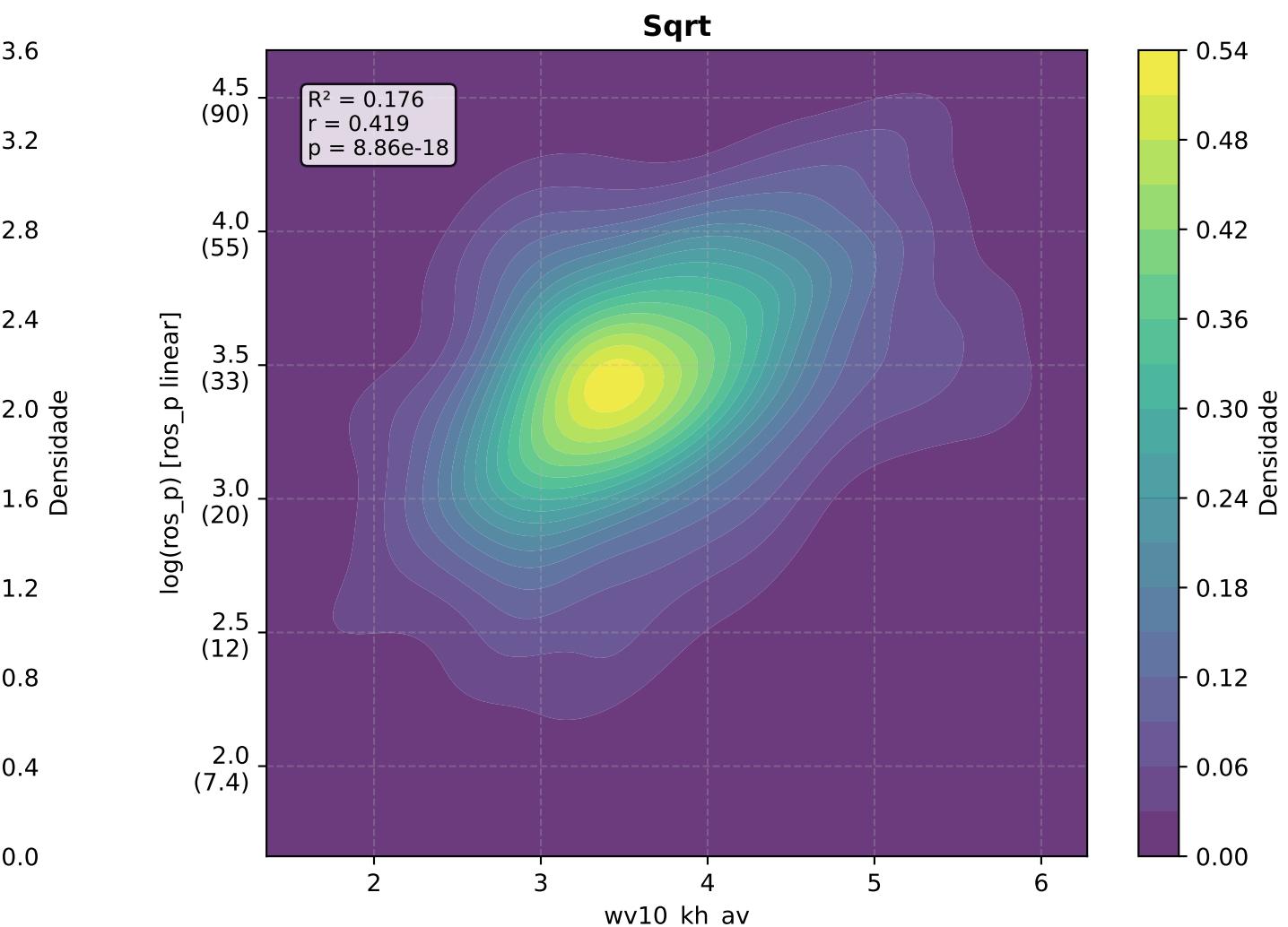
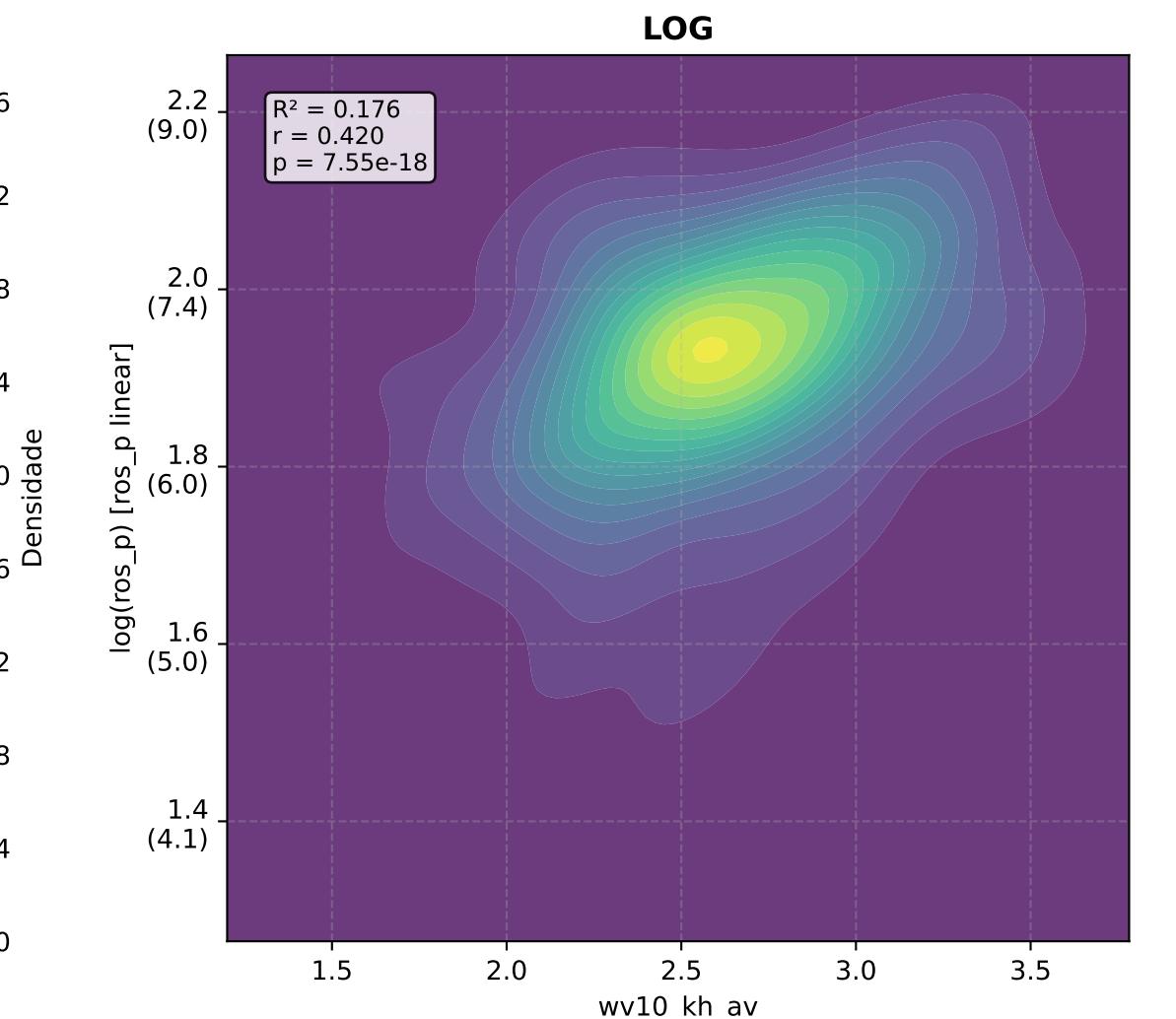
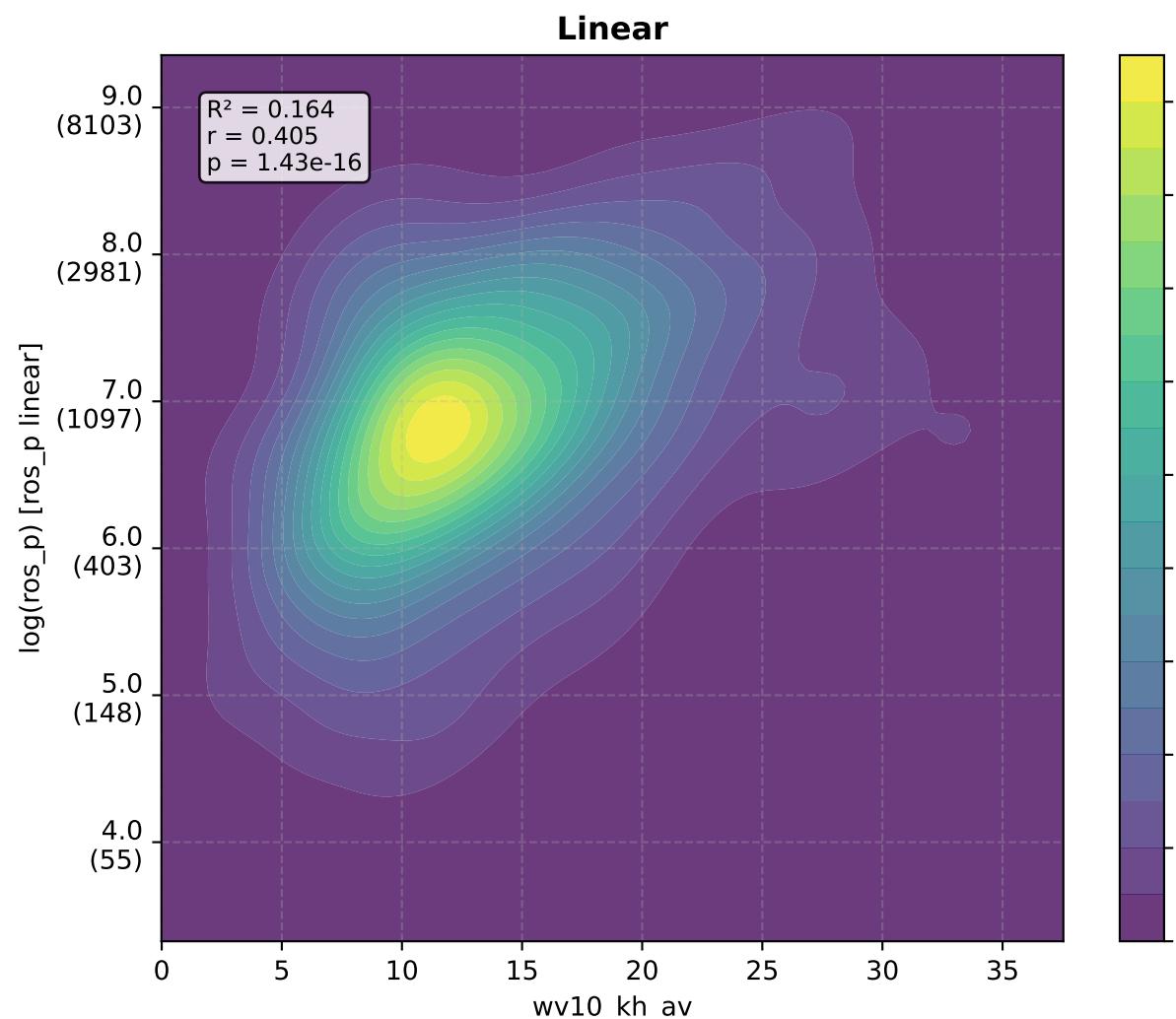
d_2m_C_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



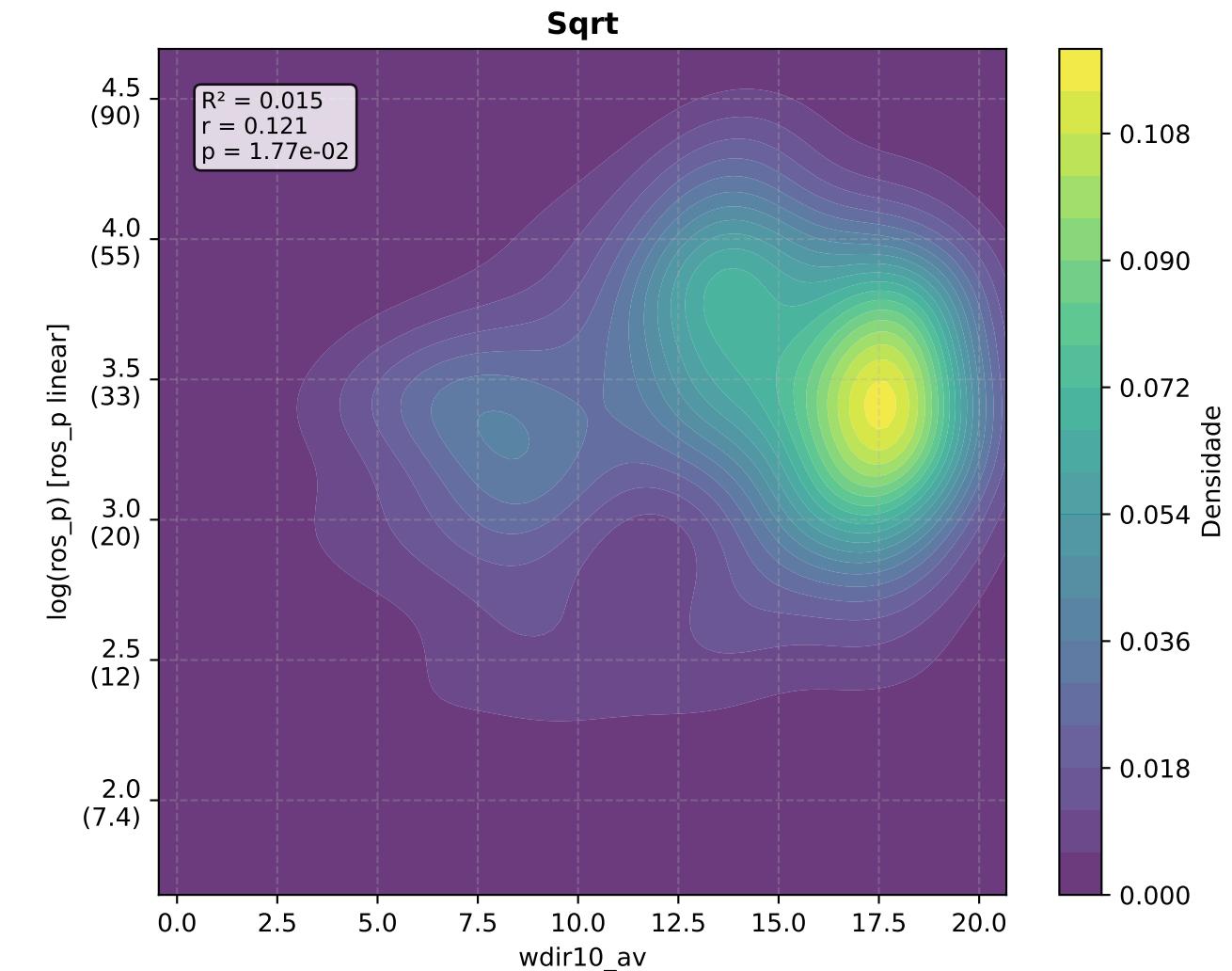
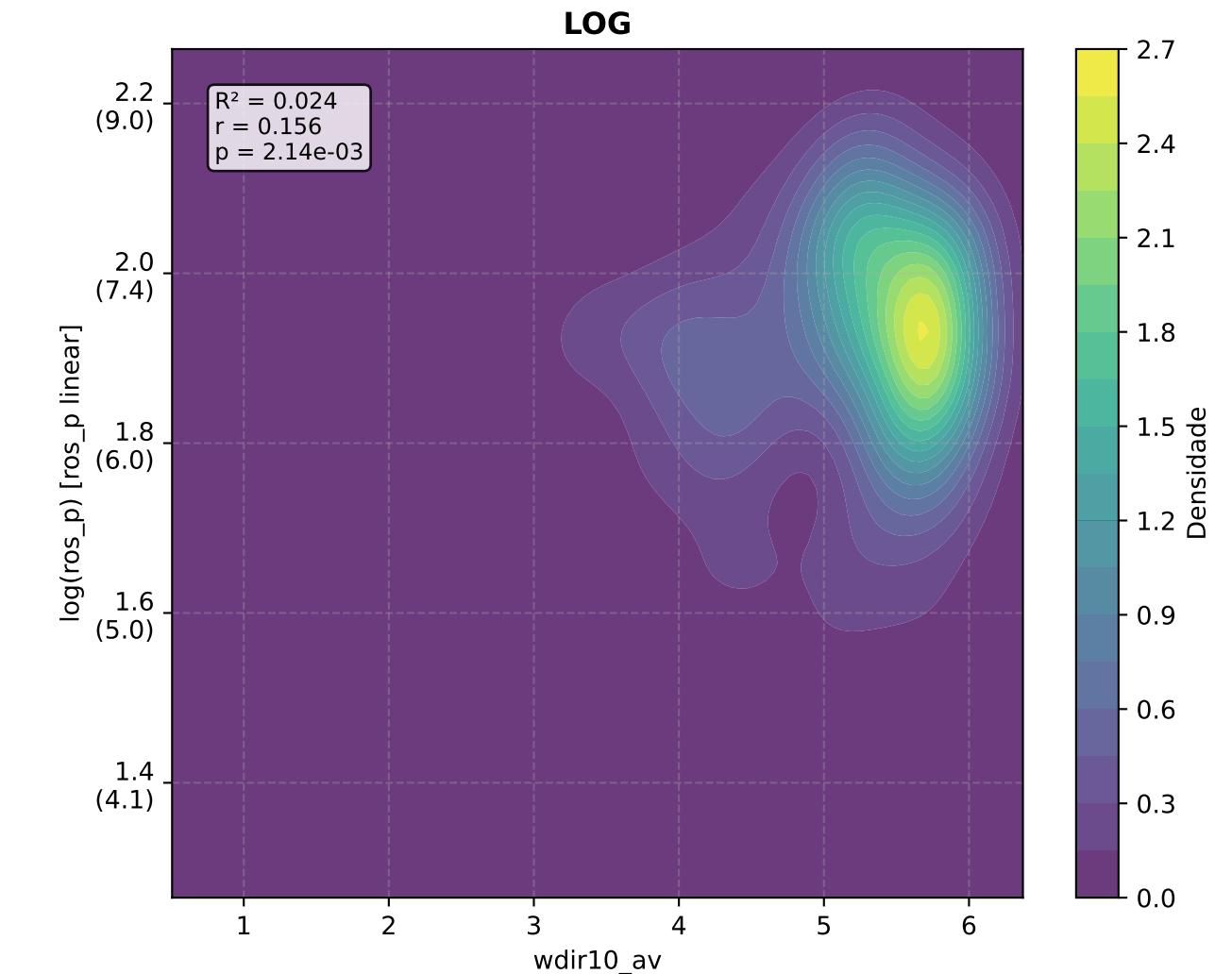
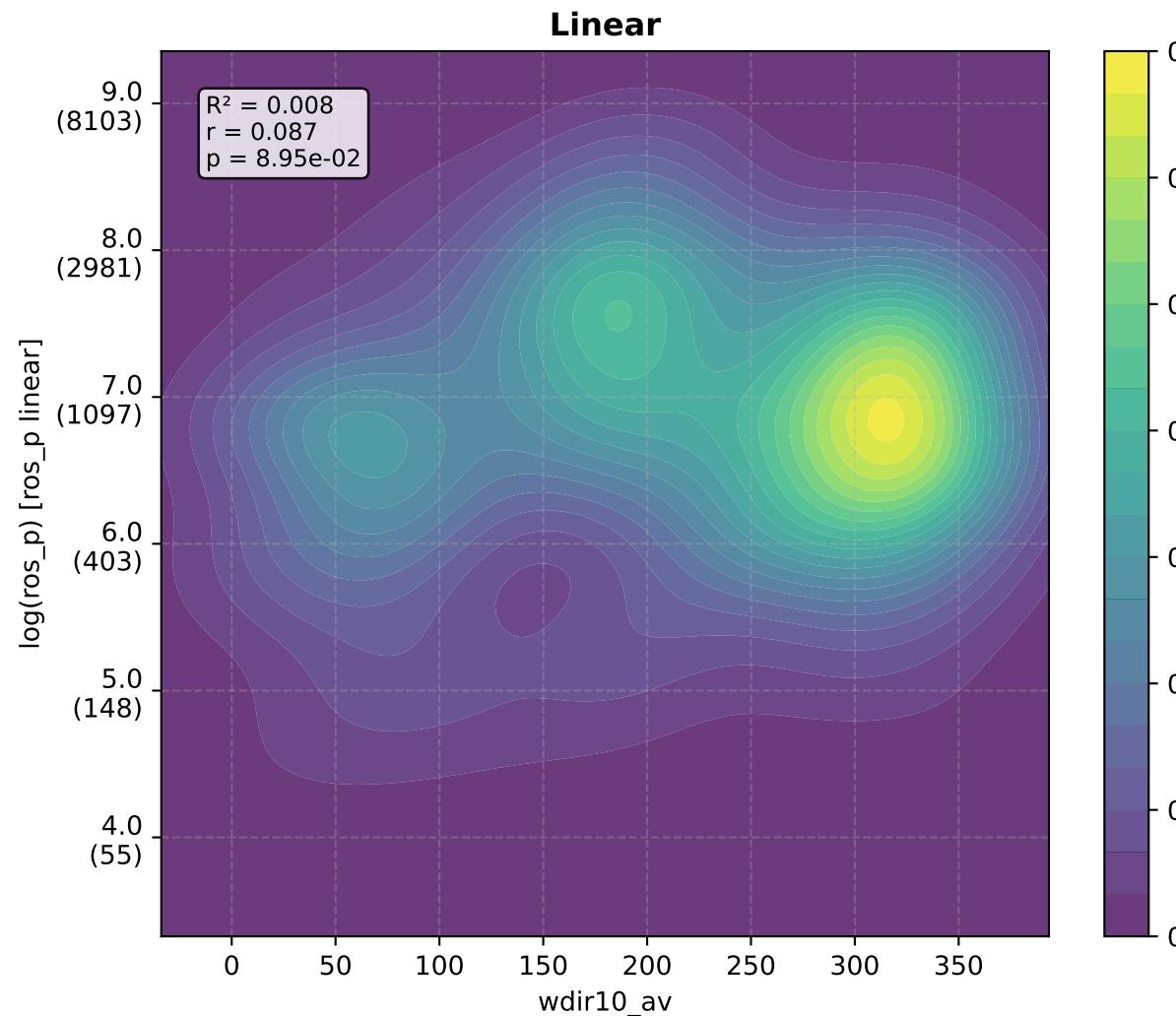
sP_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



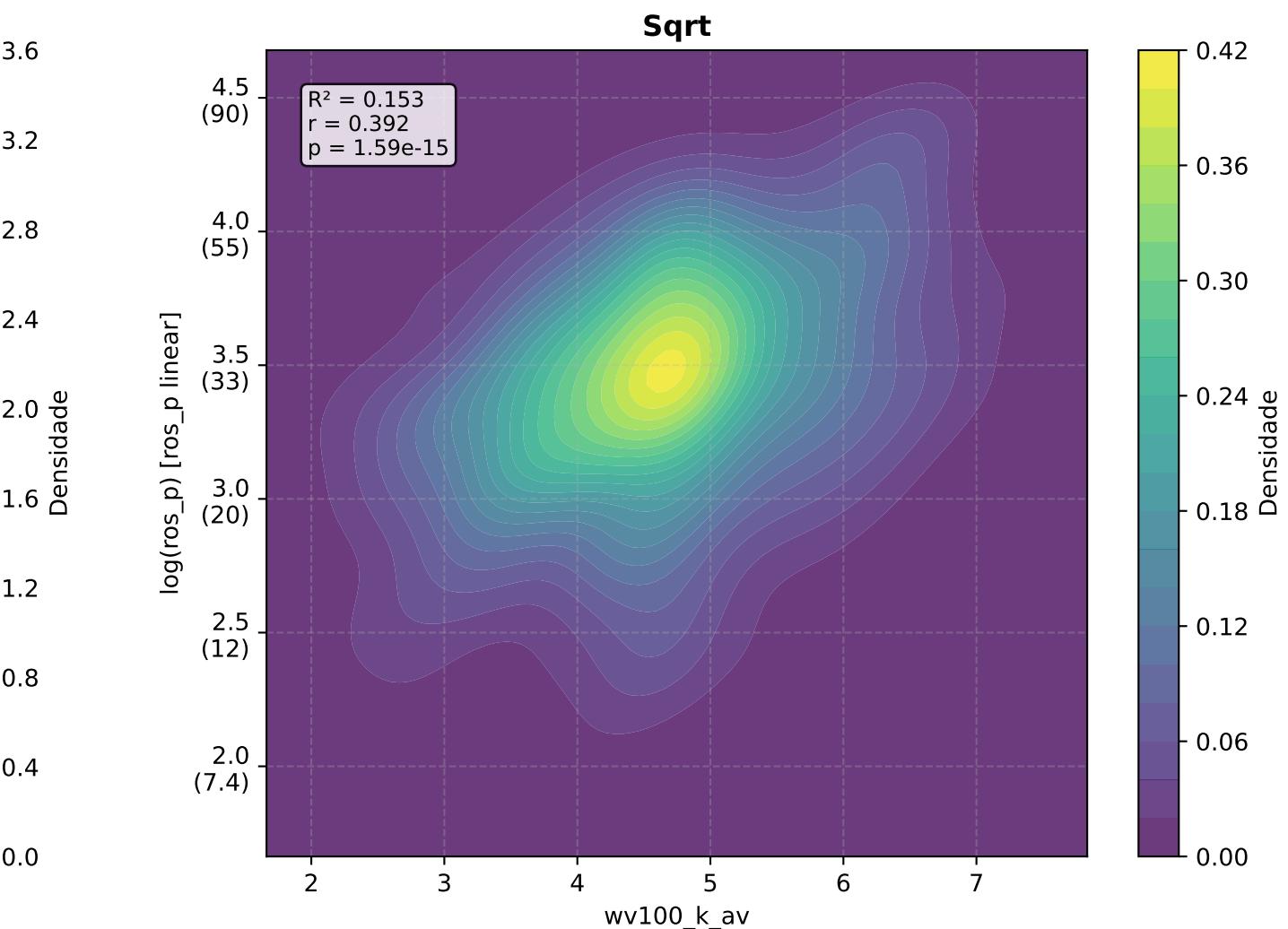
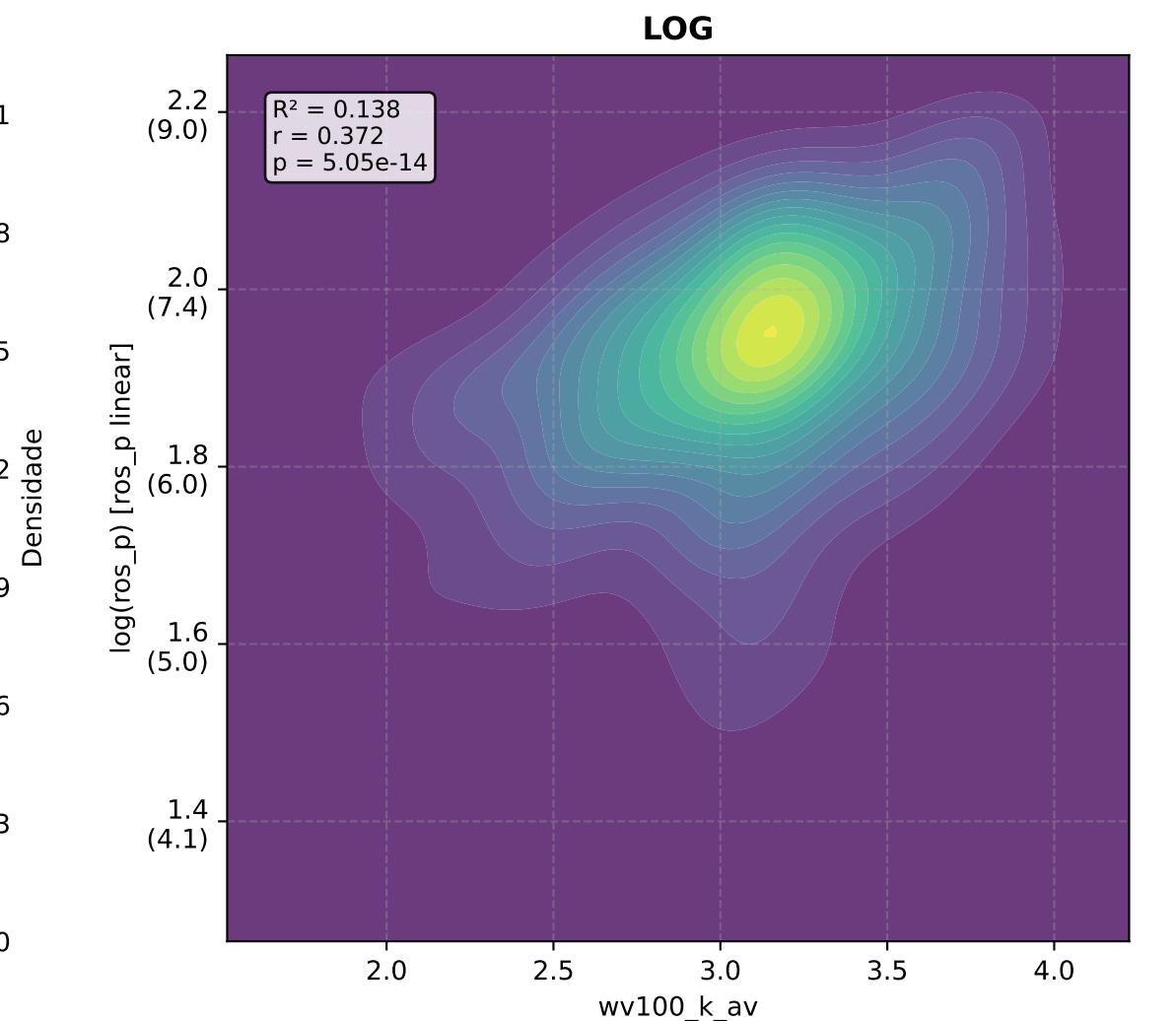
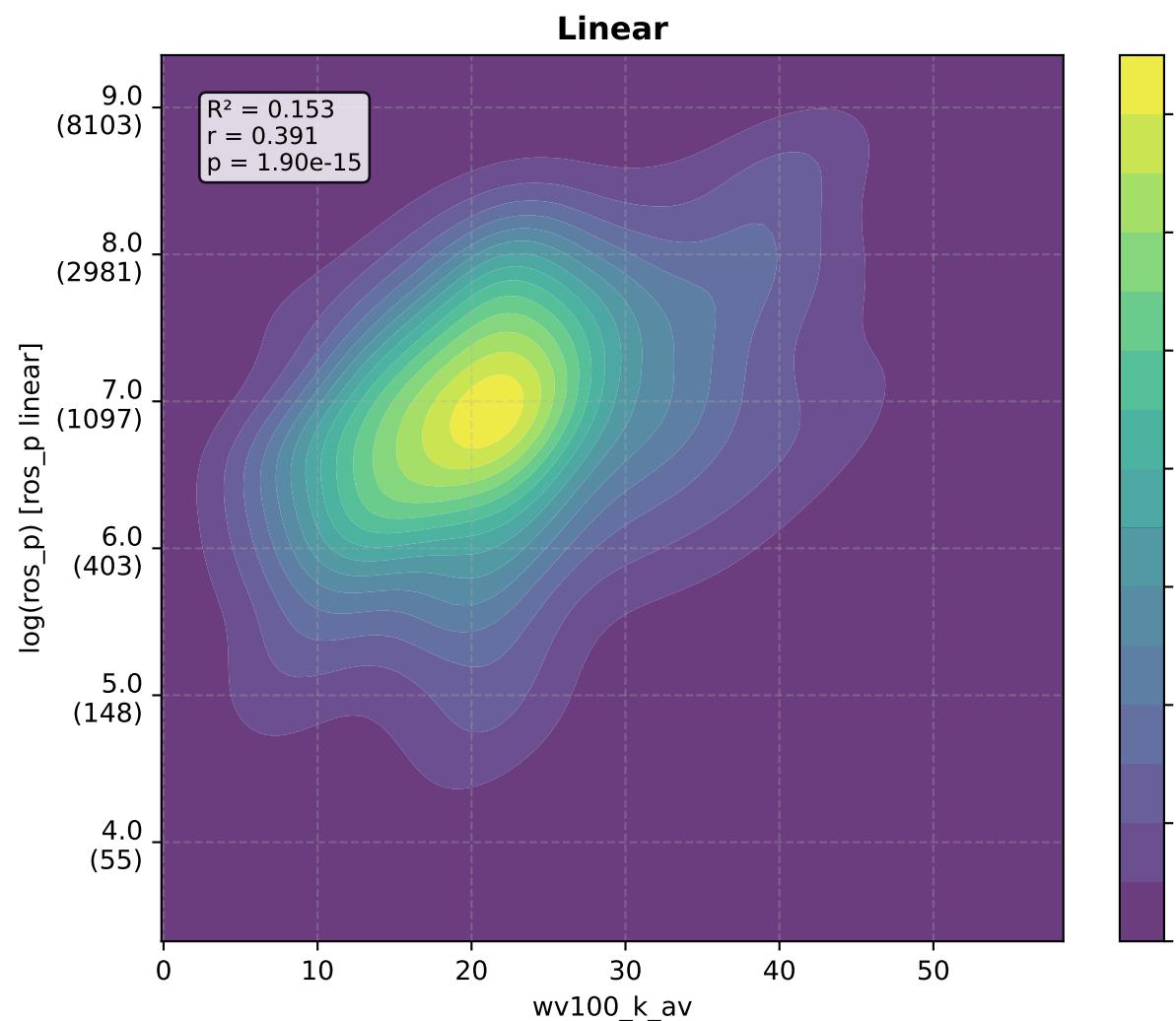
wv10_kh_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



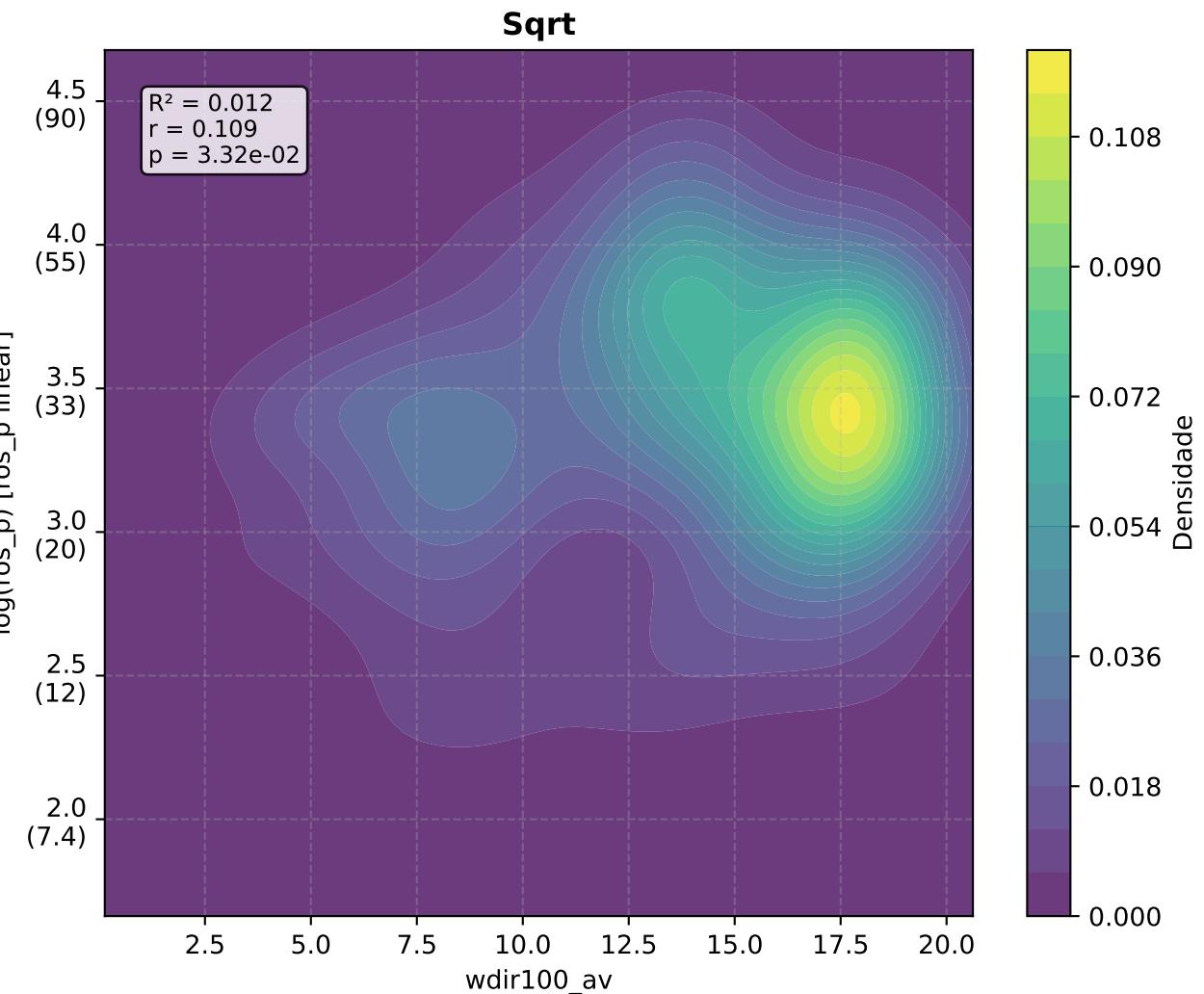
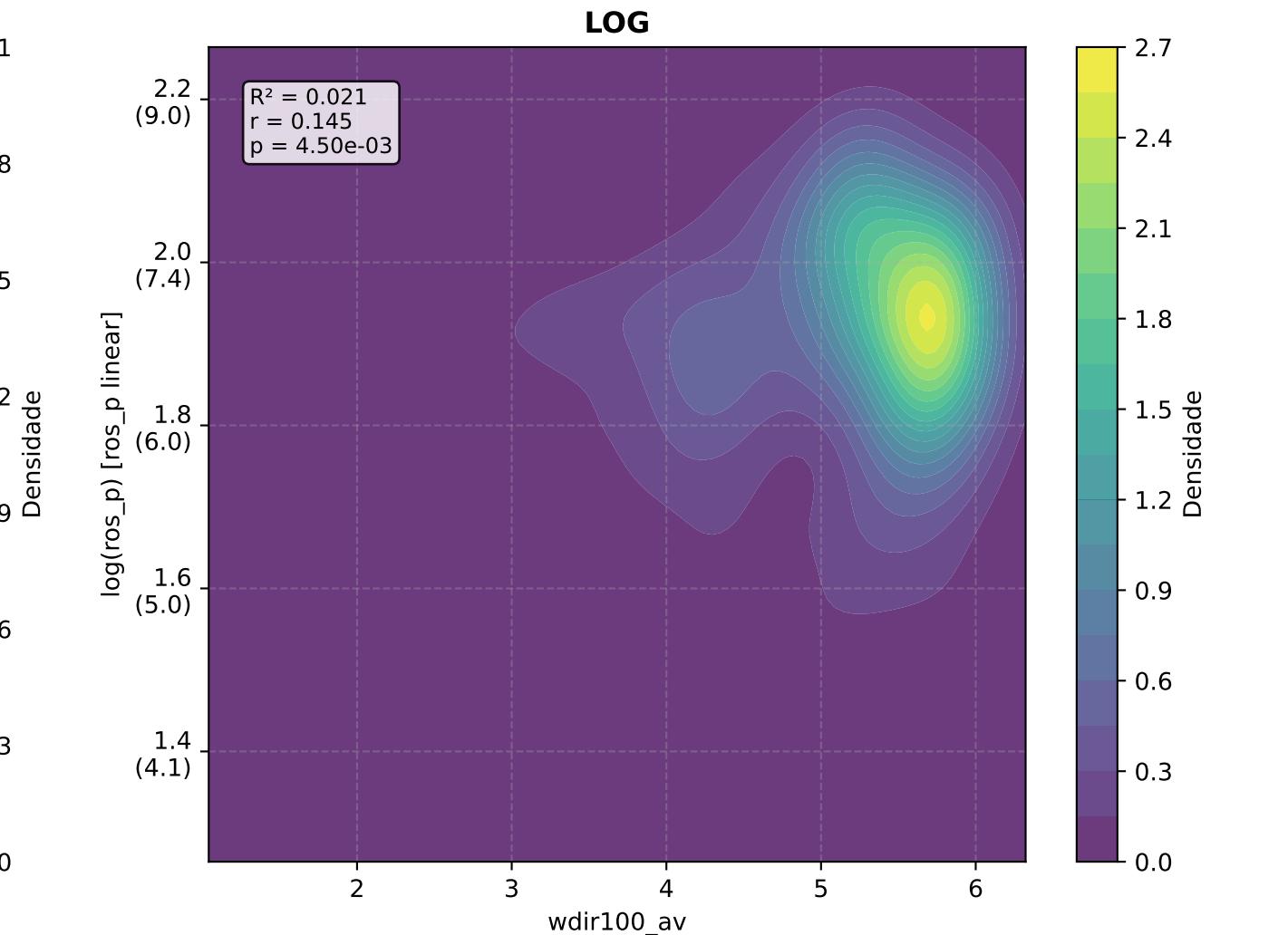
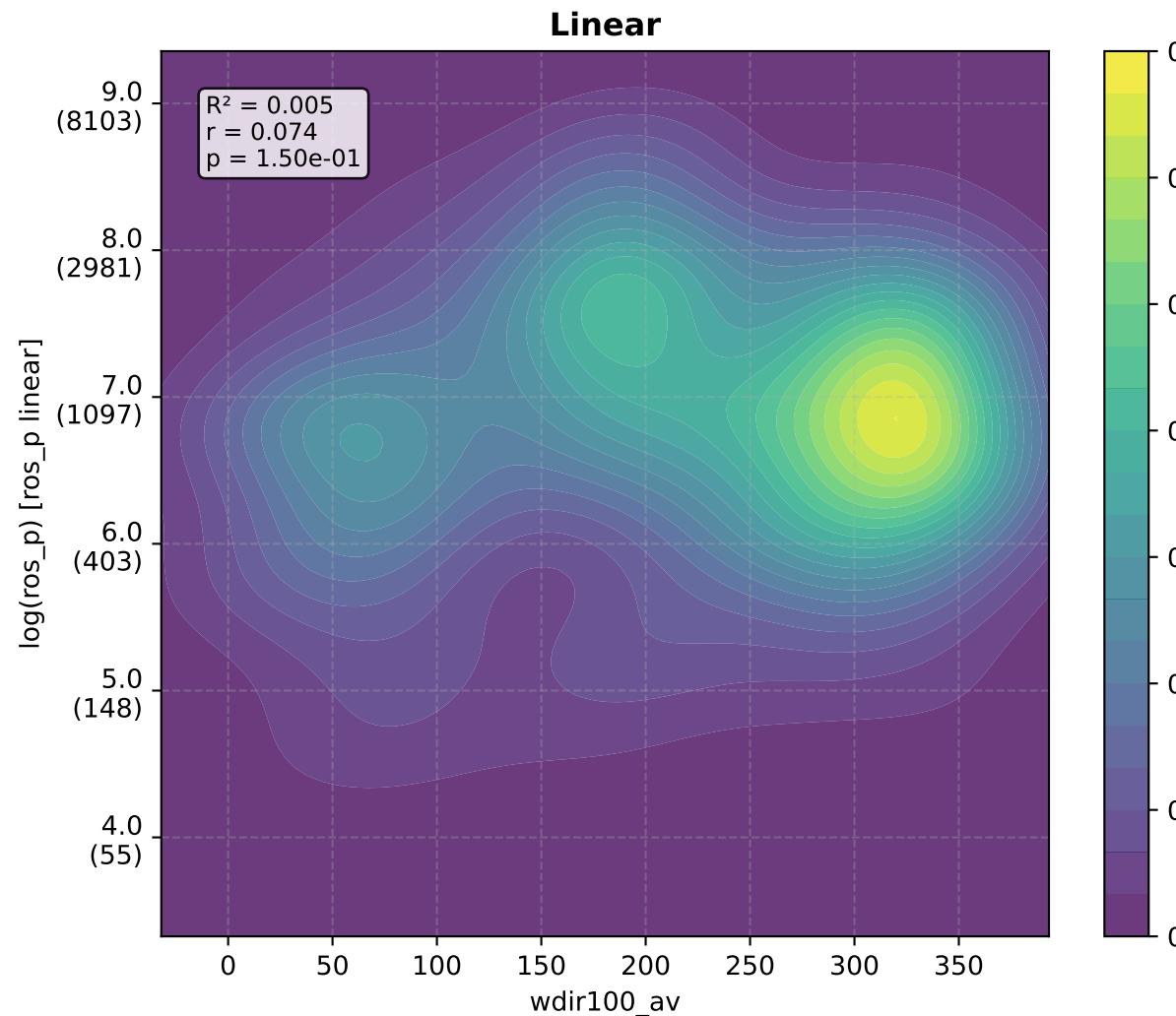
wdir10_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



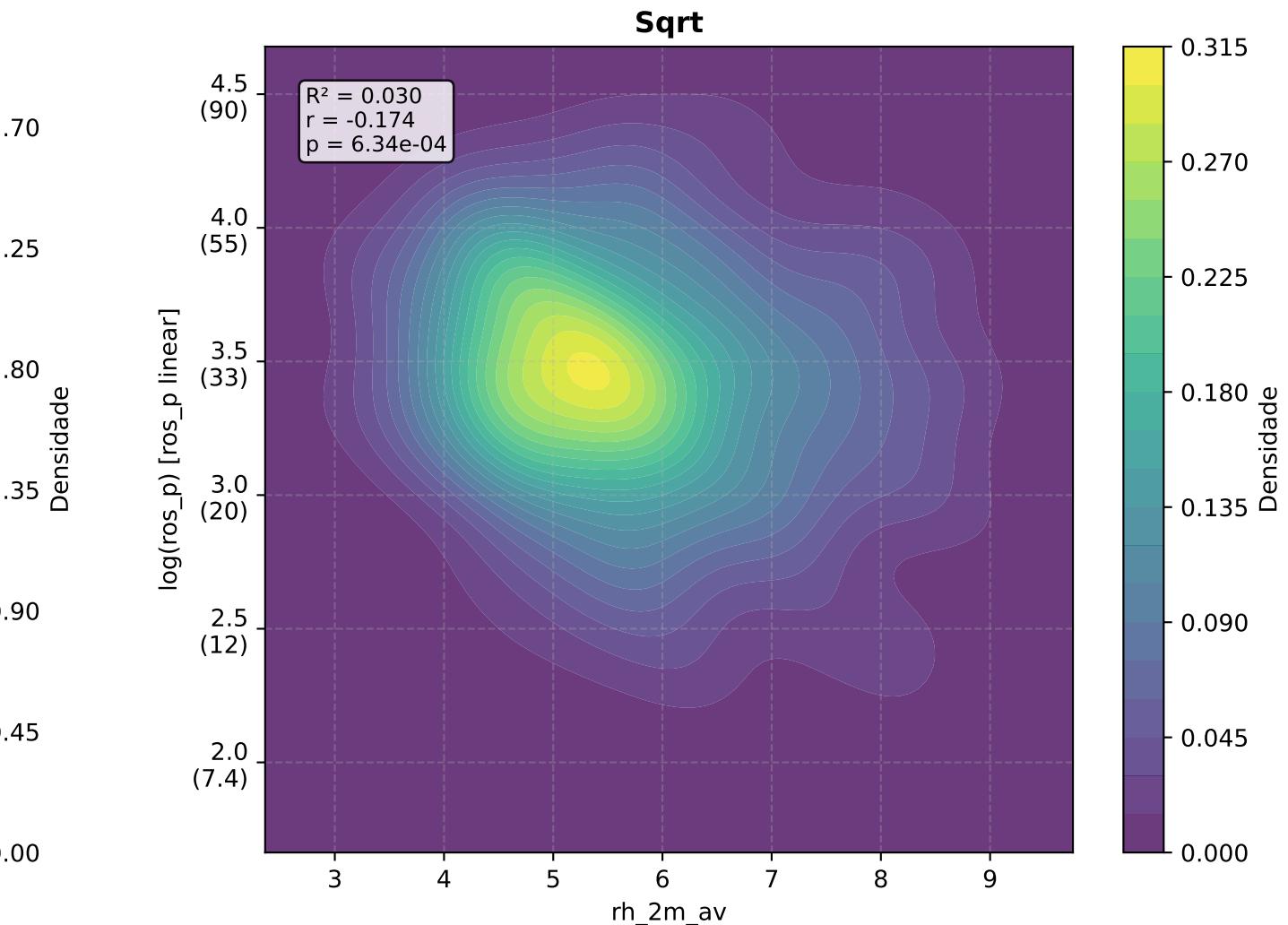
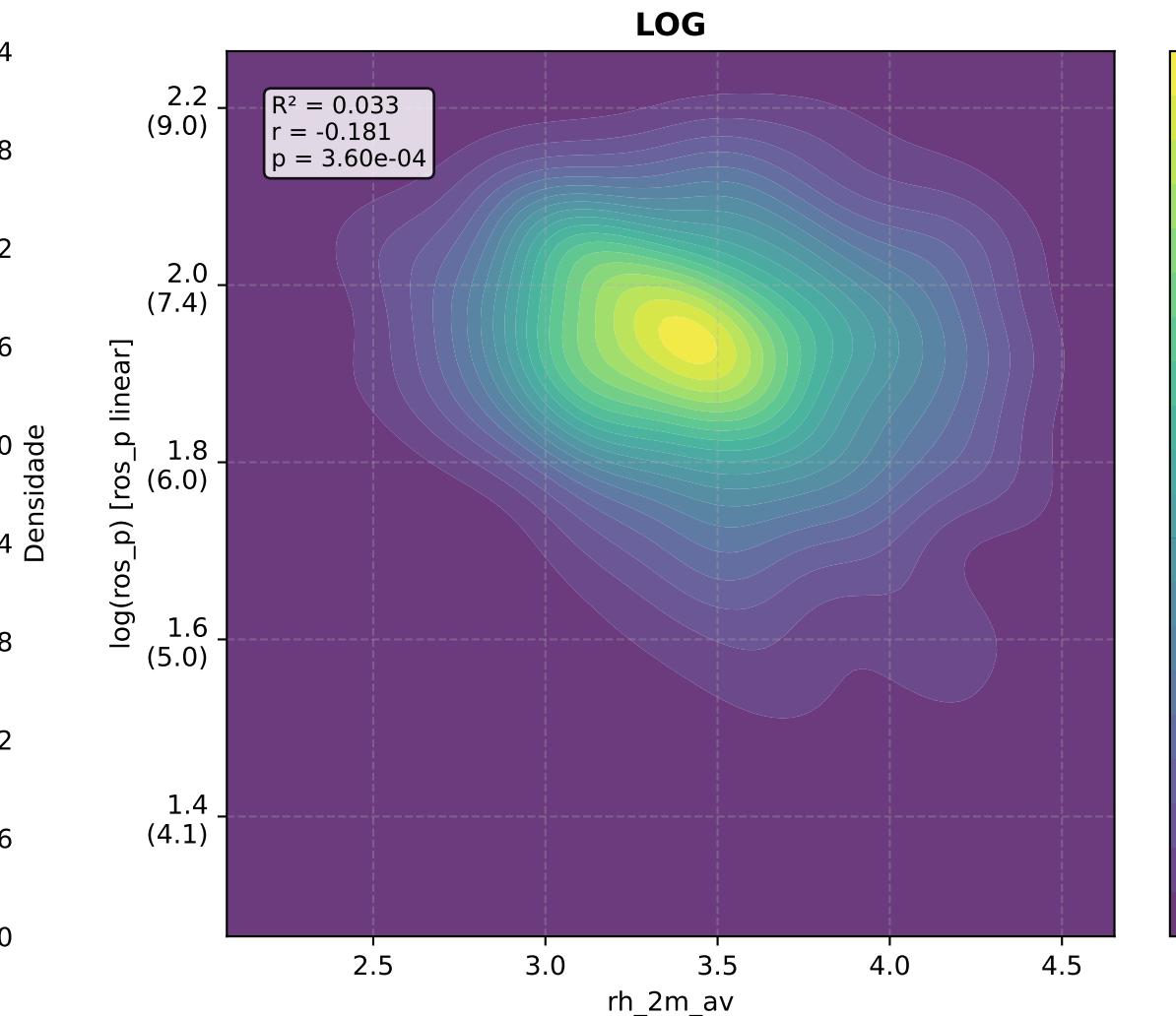
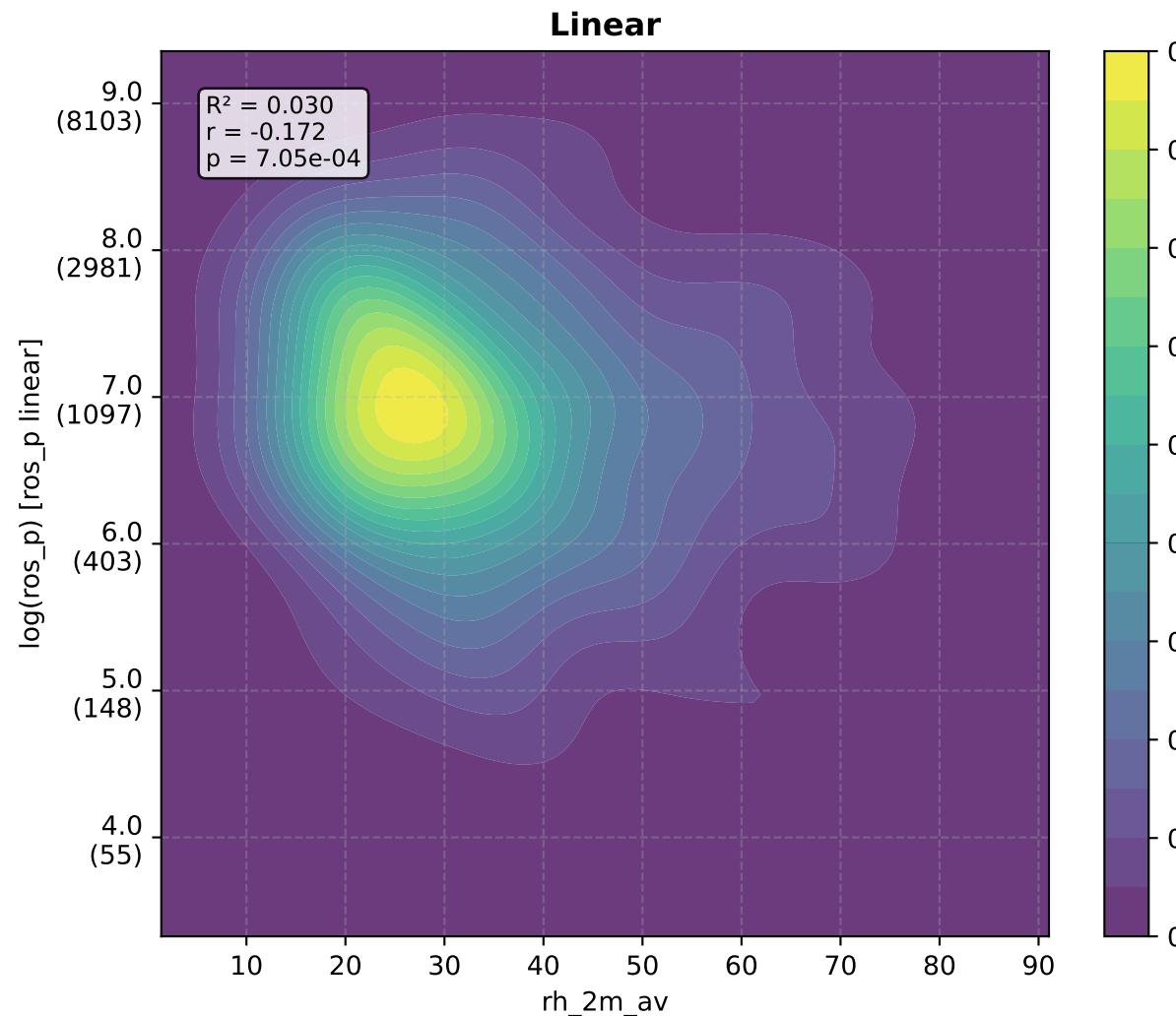
wv100_k_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



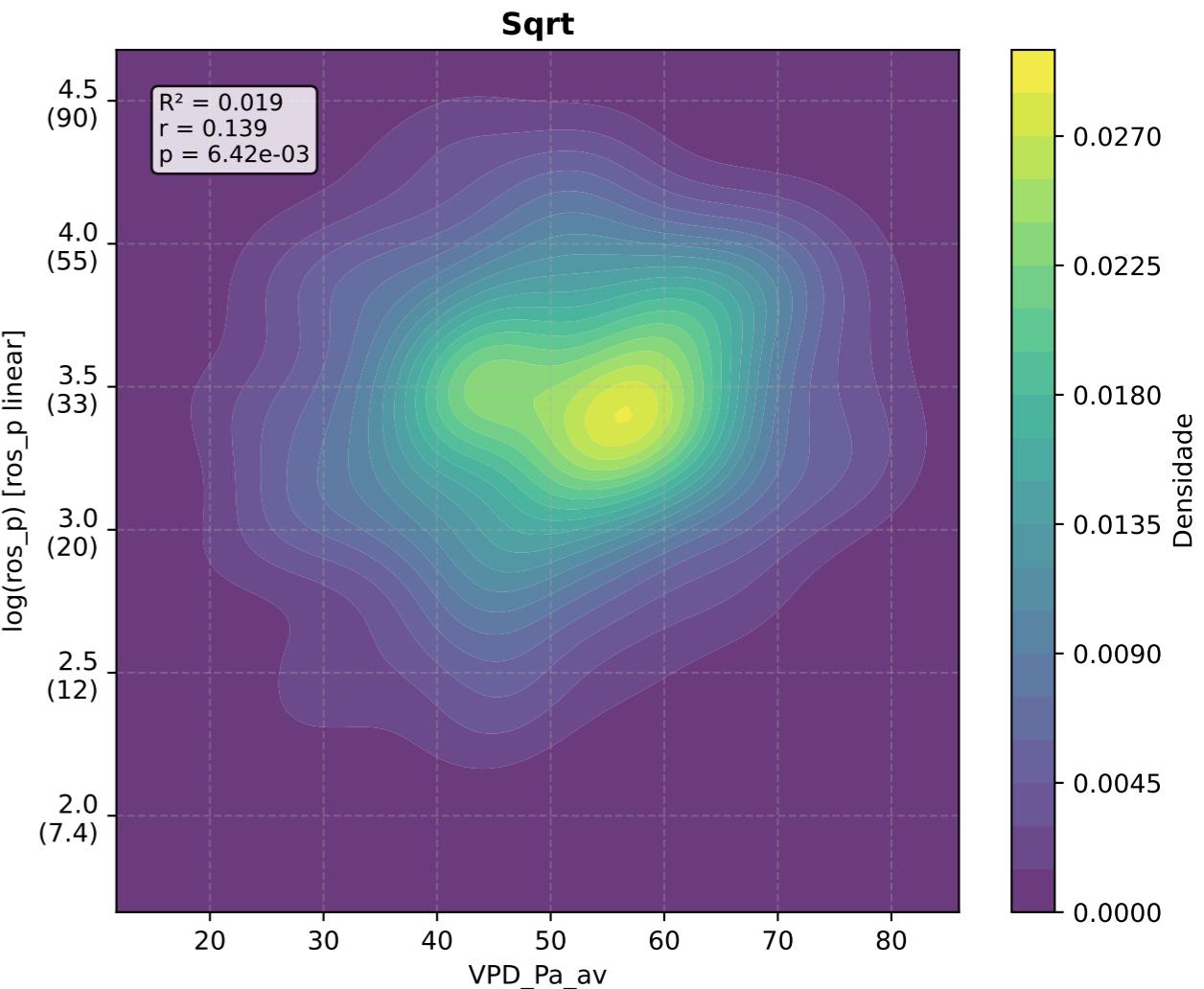
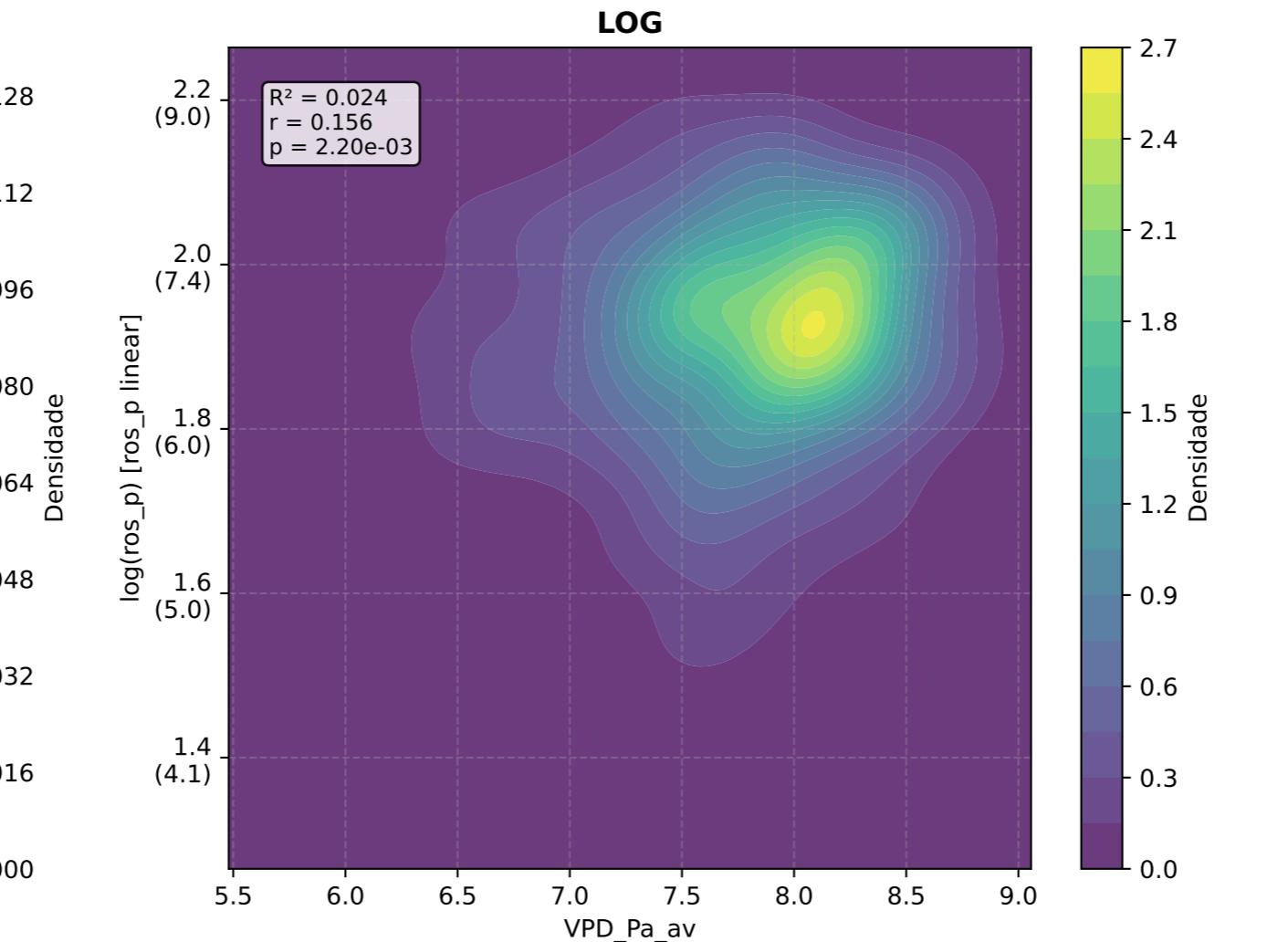
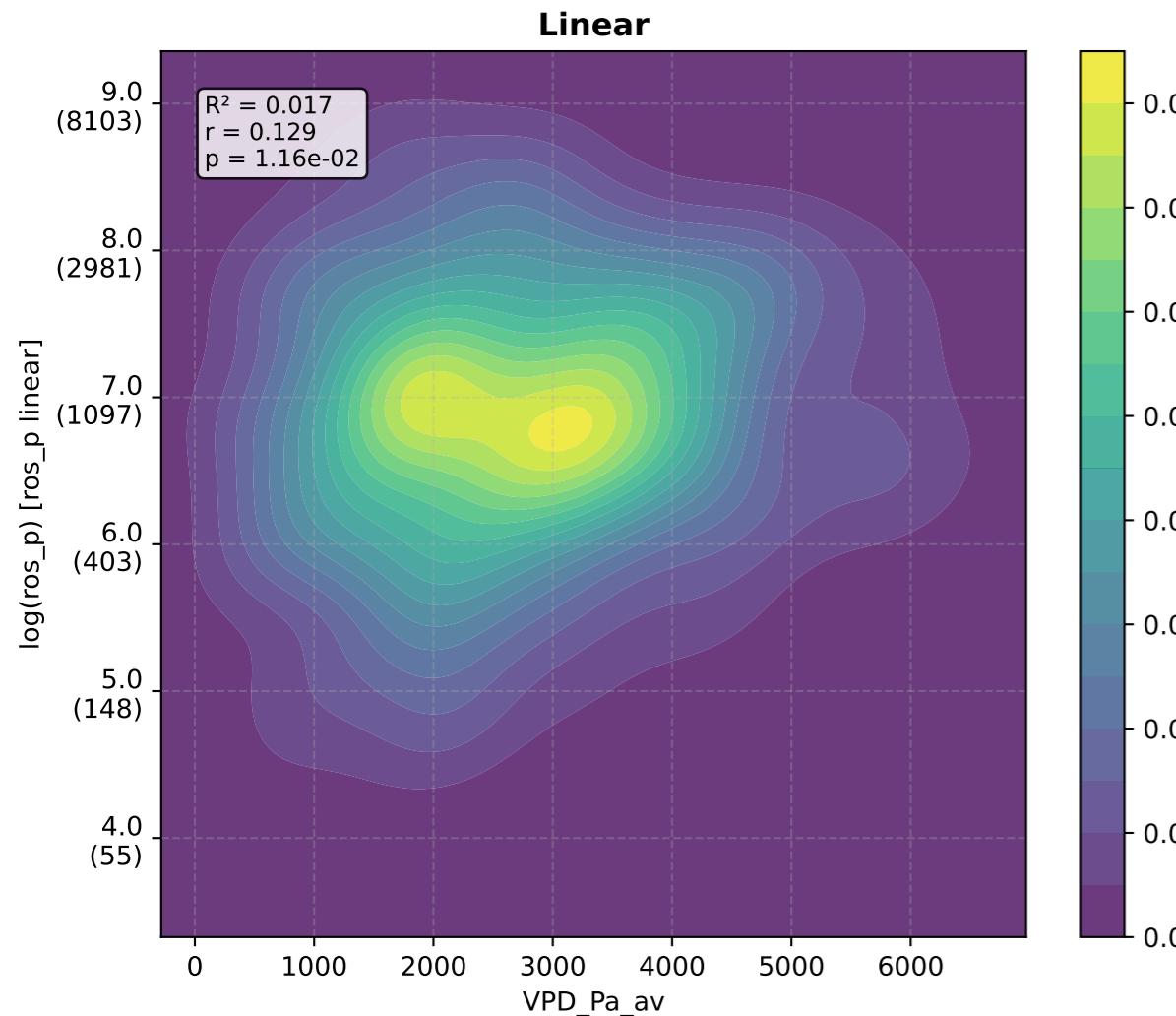
wdir100_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



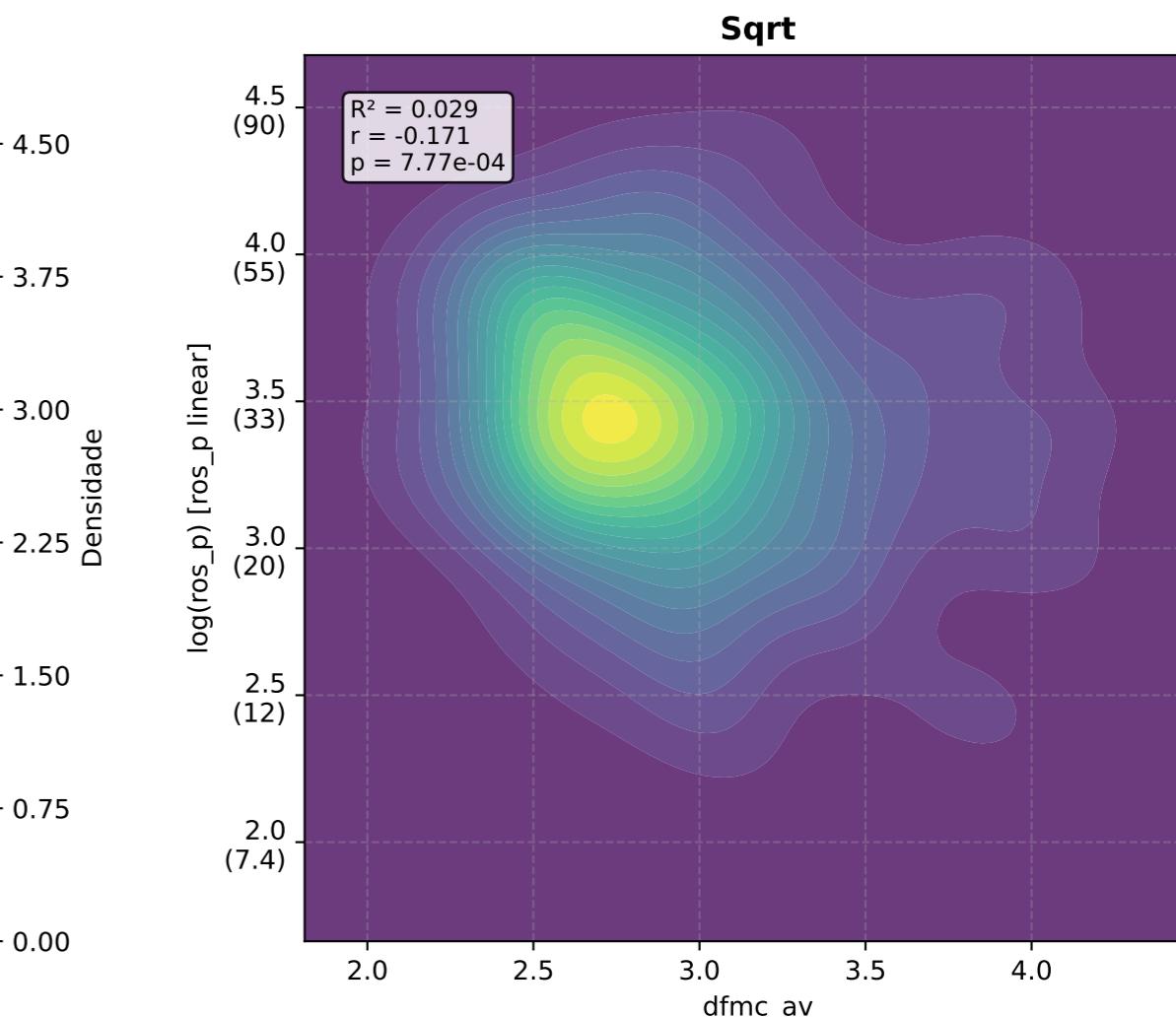
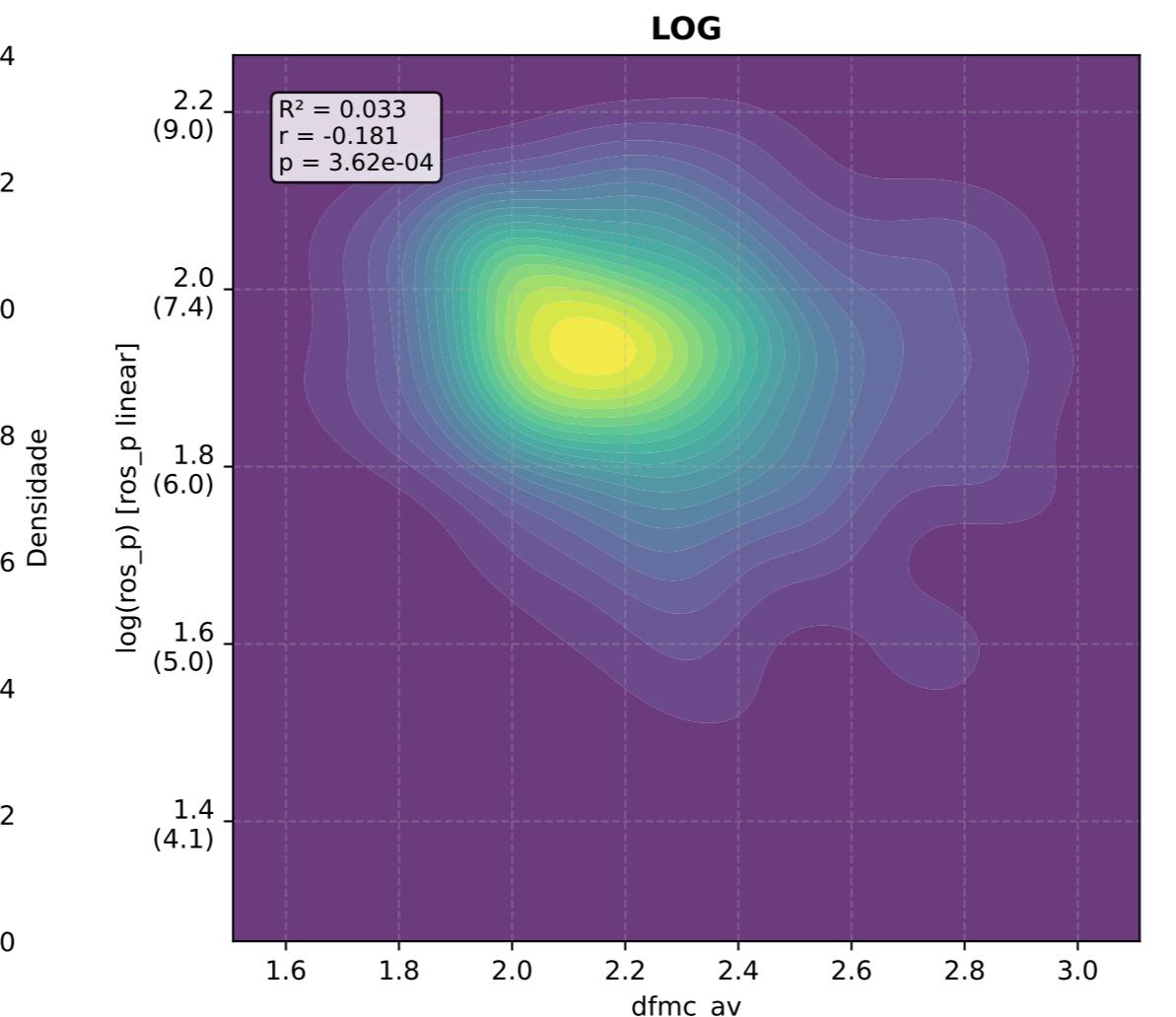
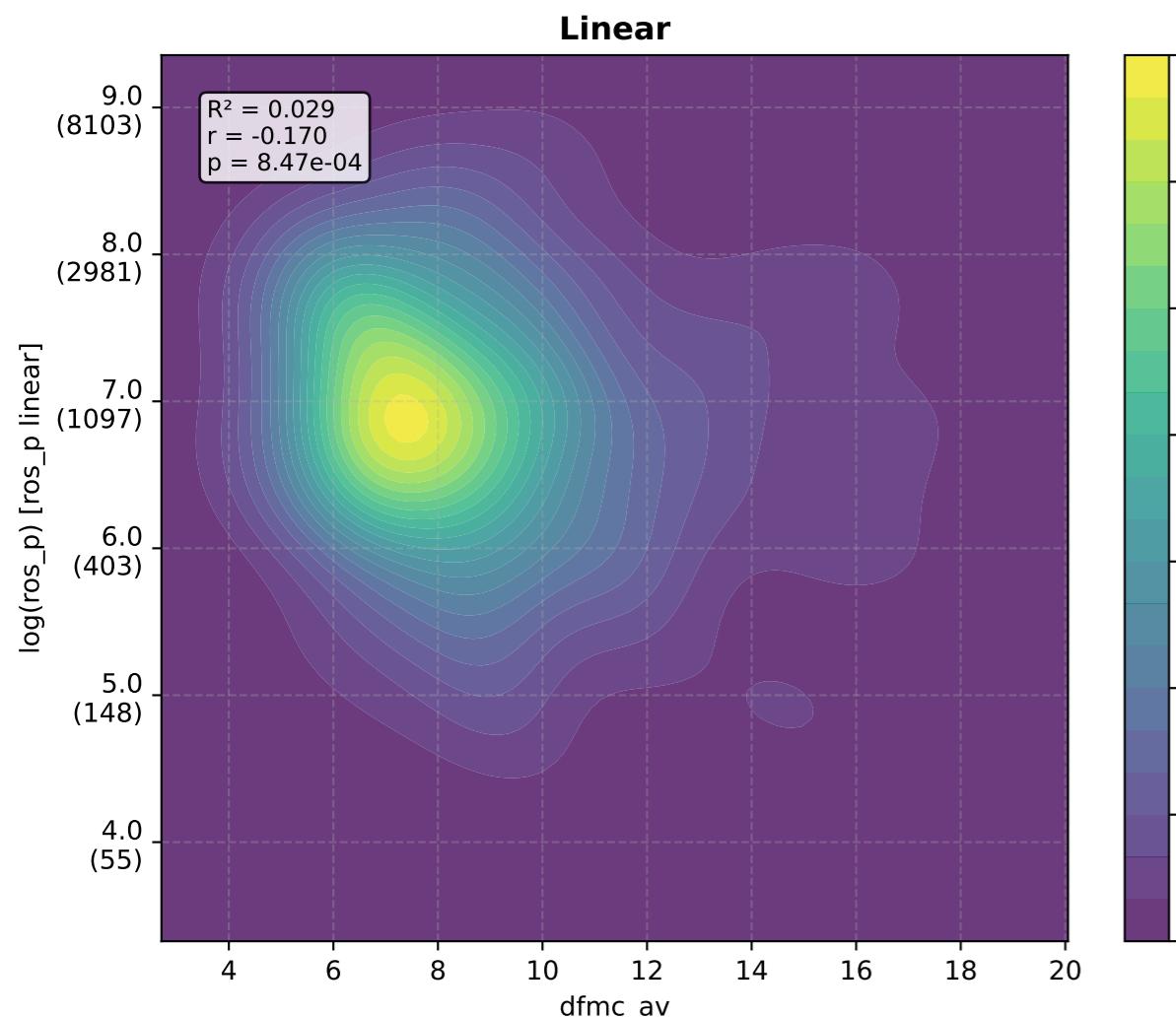
rh_2m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



VPD_Pa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



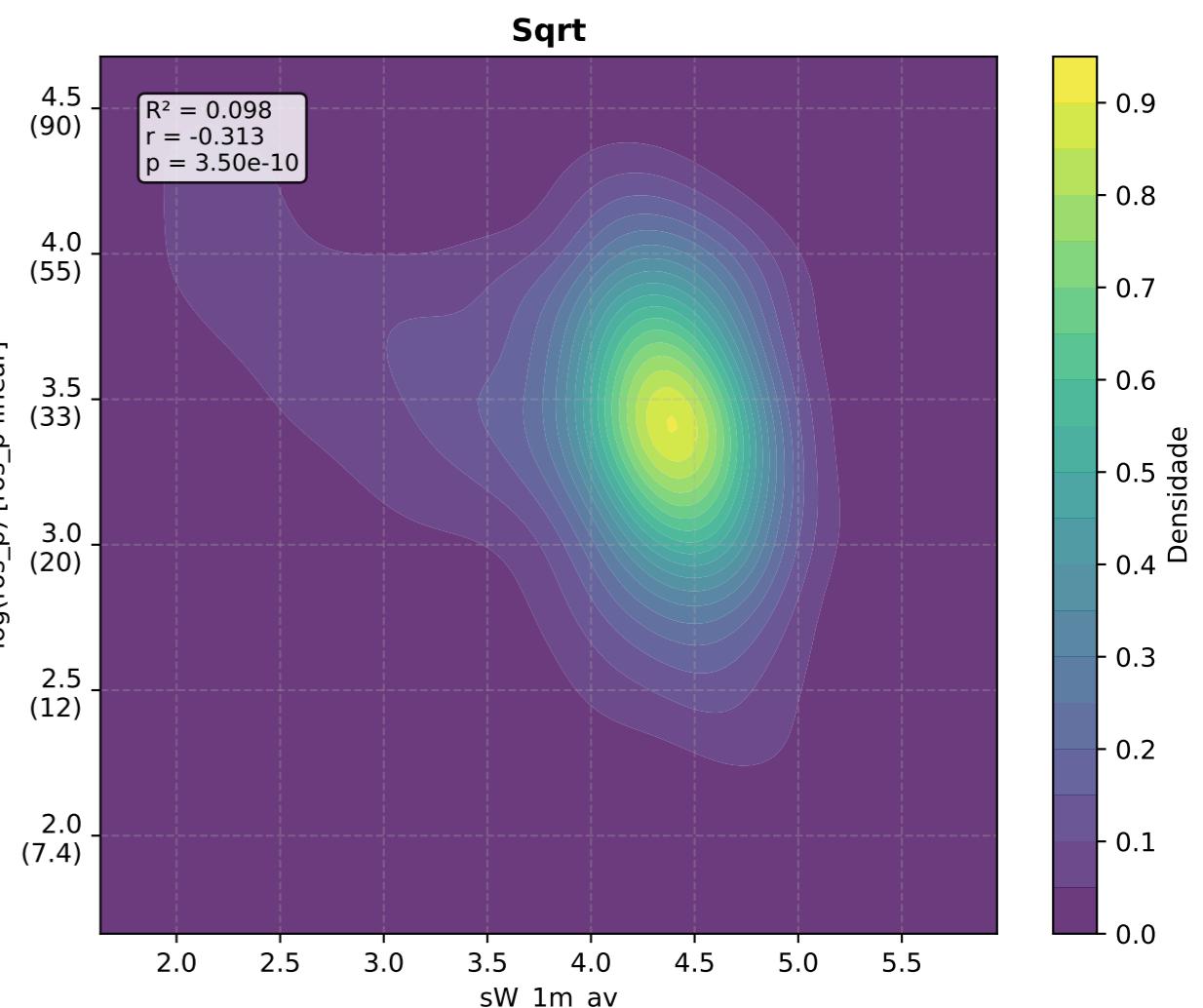
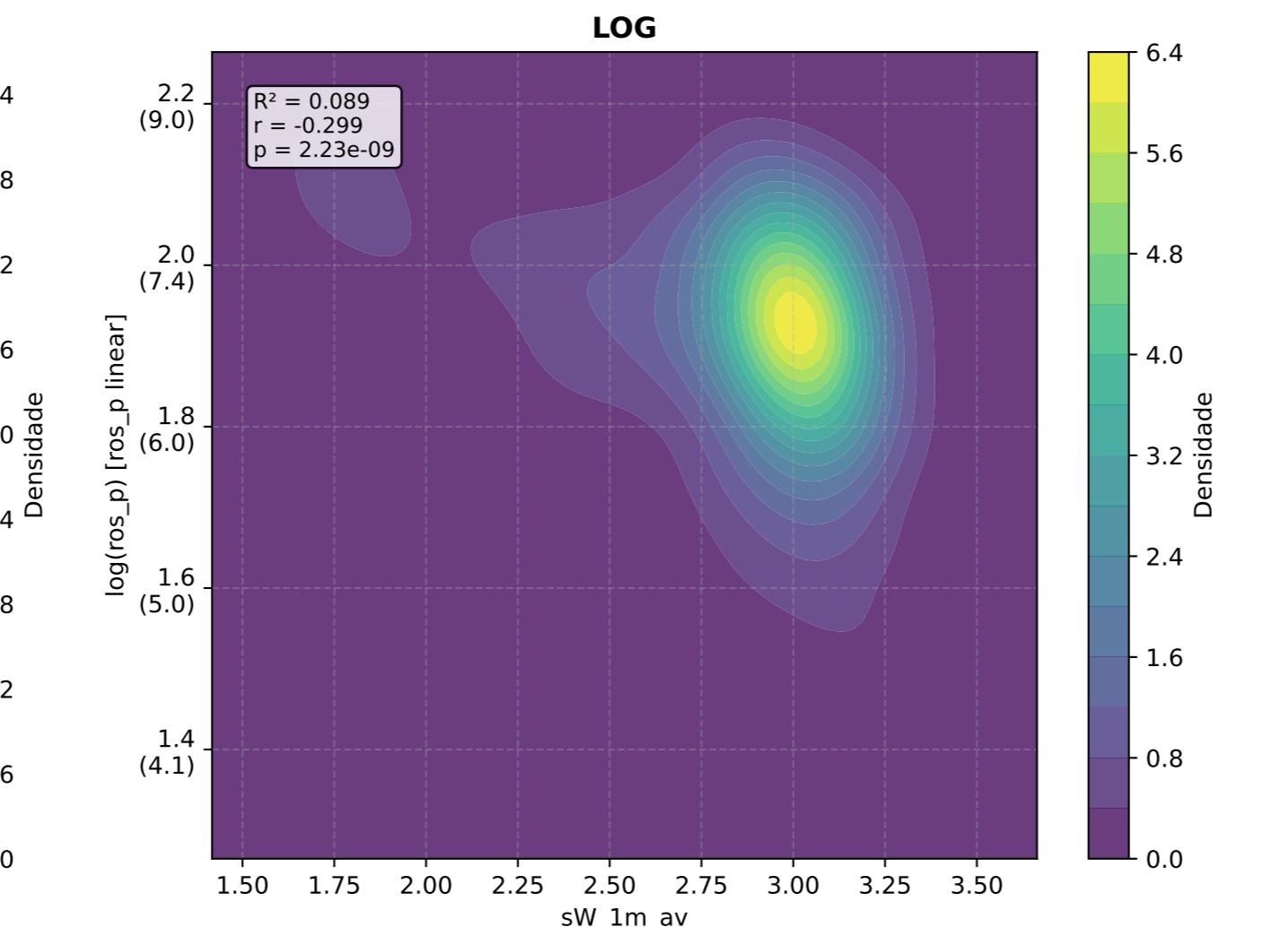
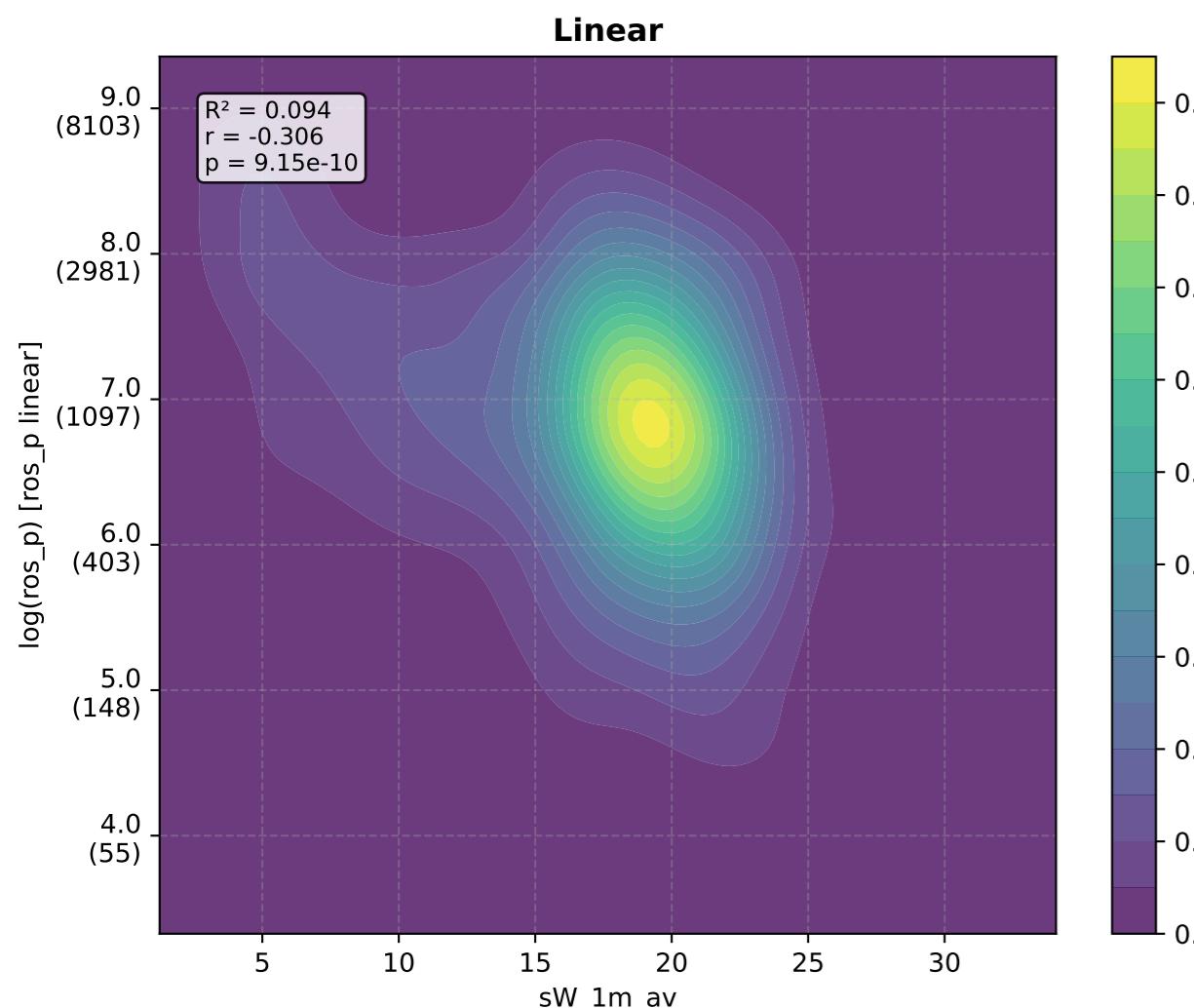
dfmc_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



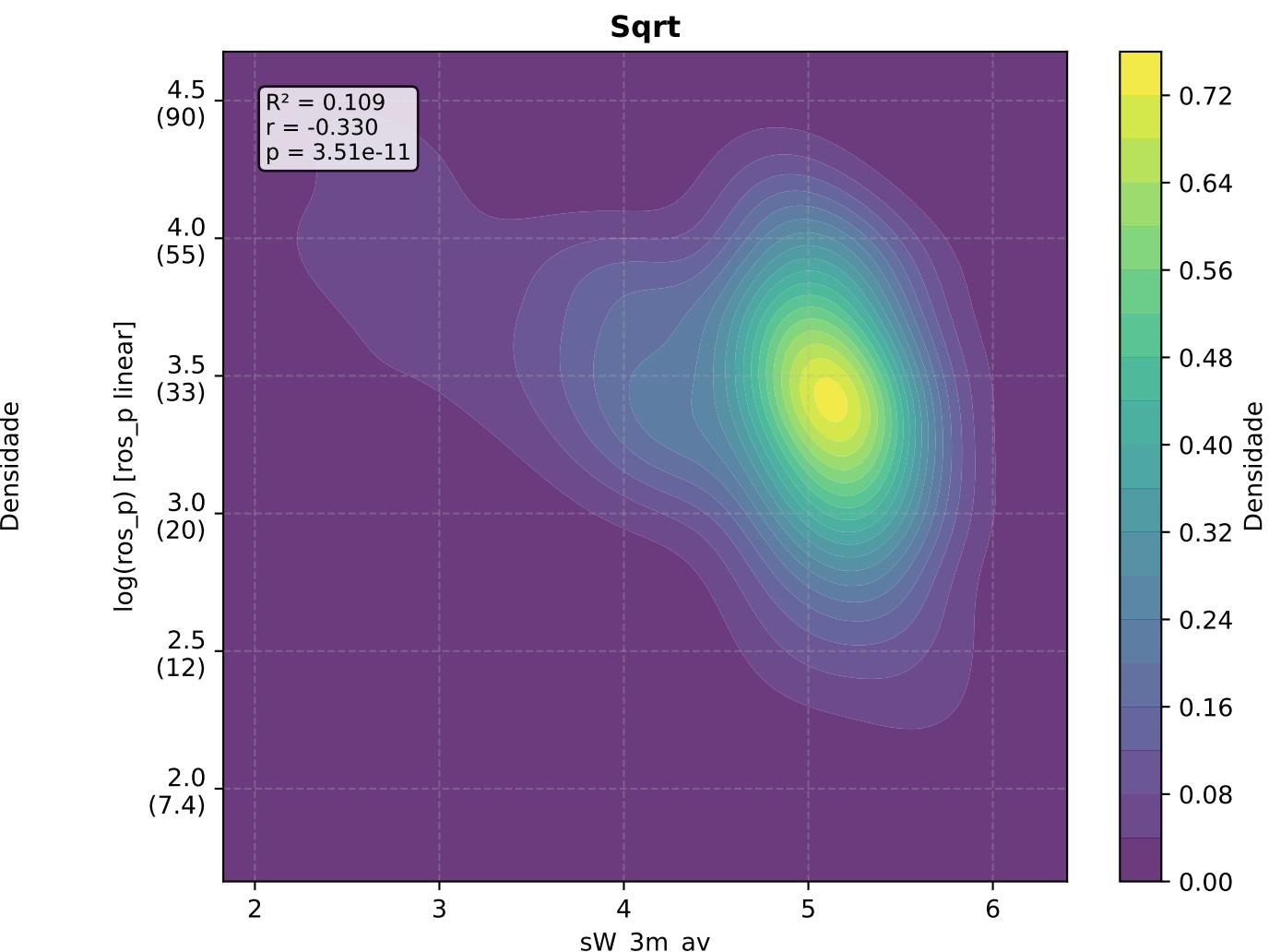
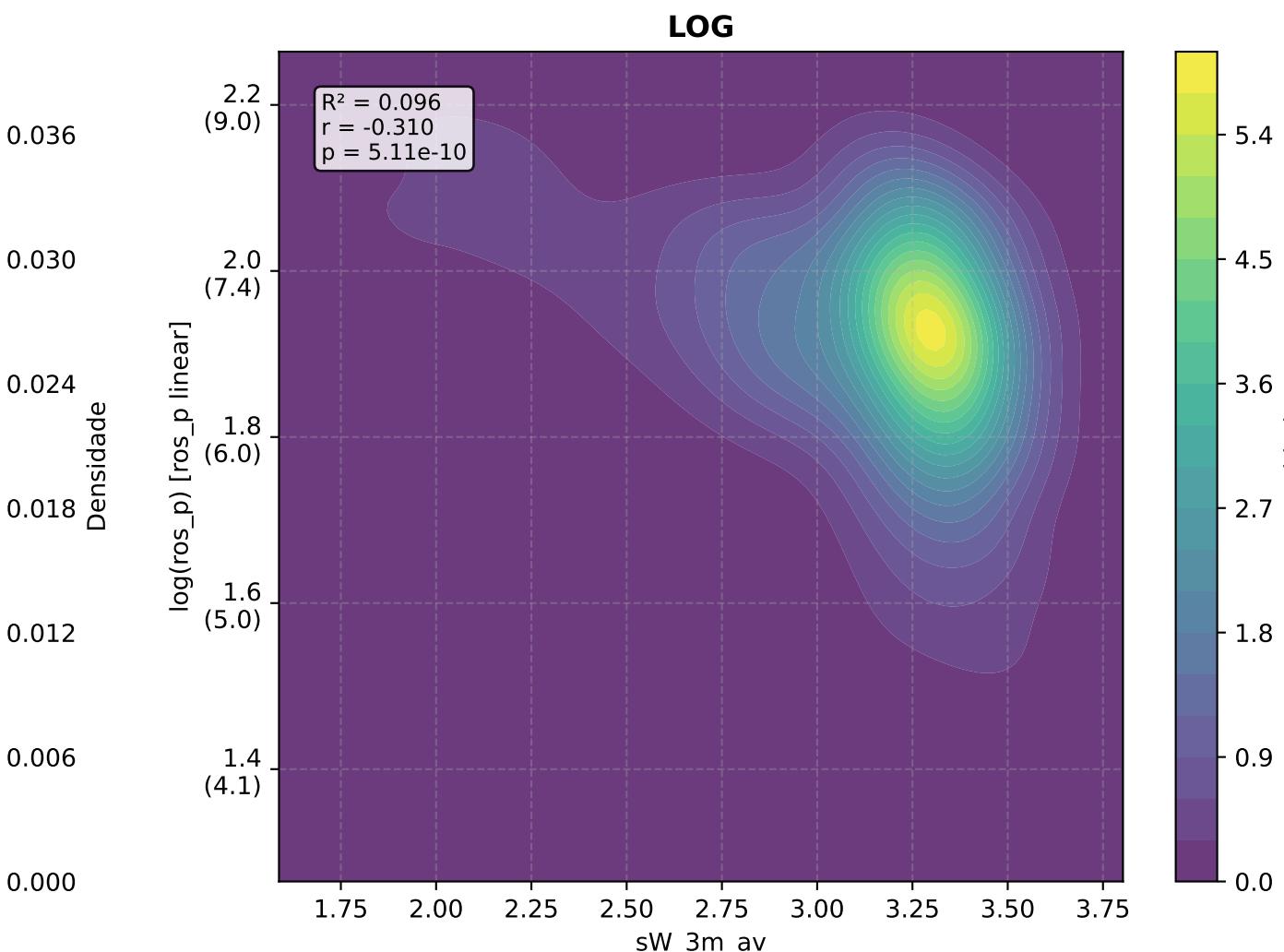
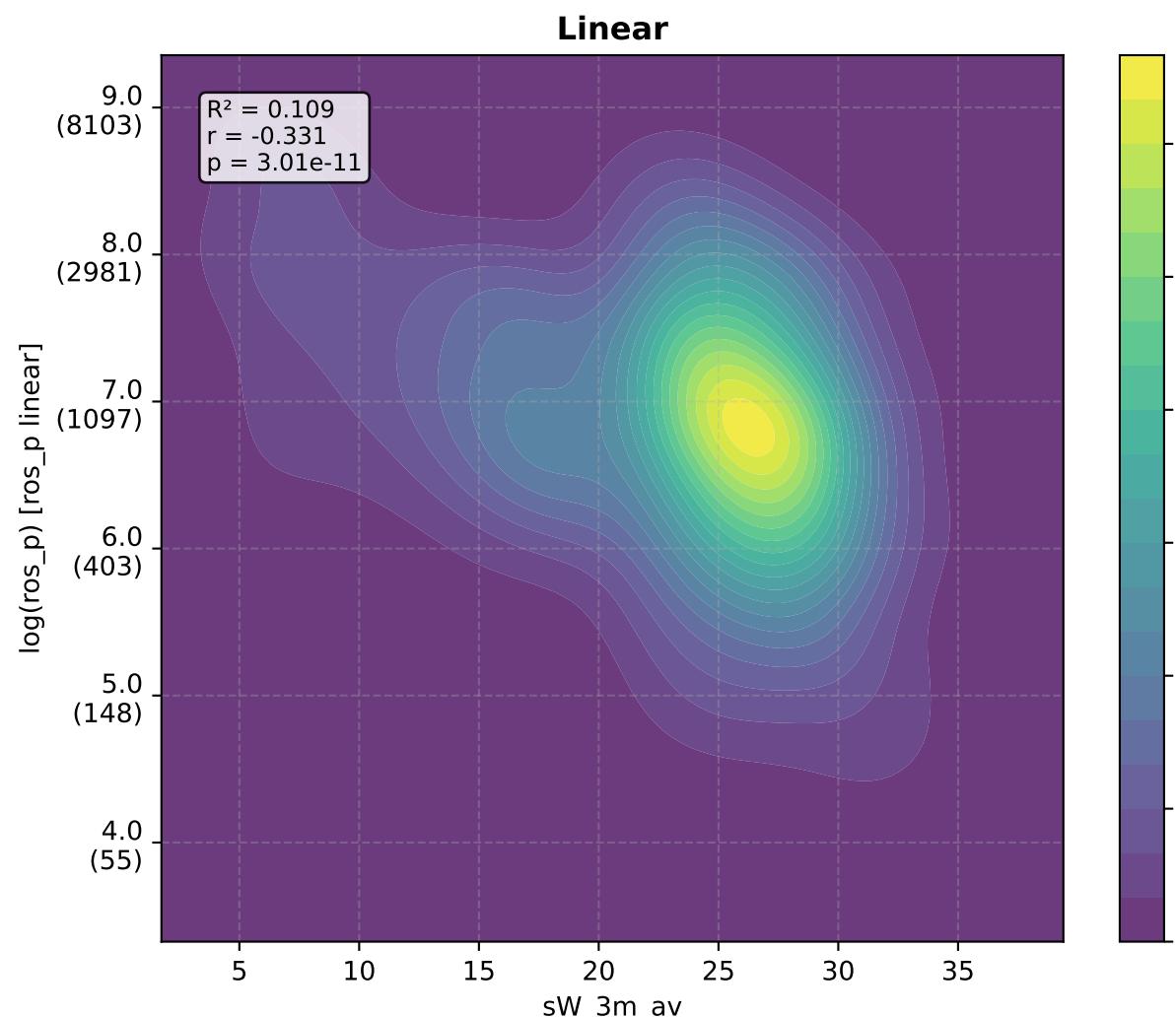
Densidade

A vertical color bar labeled "Densidade" at the bottom right. The scale ranges from 0.0 (dark purple) to 0.9 (yellow), with intermediate ticks at 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, and 0.9.

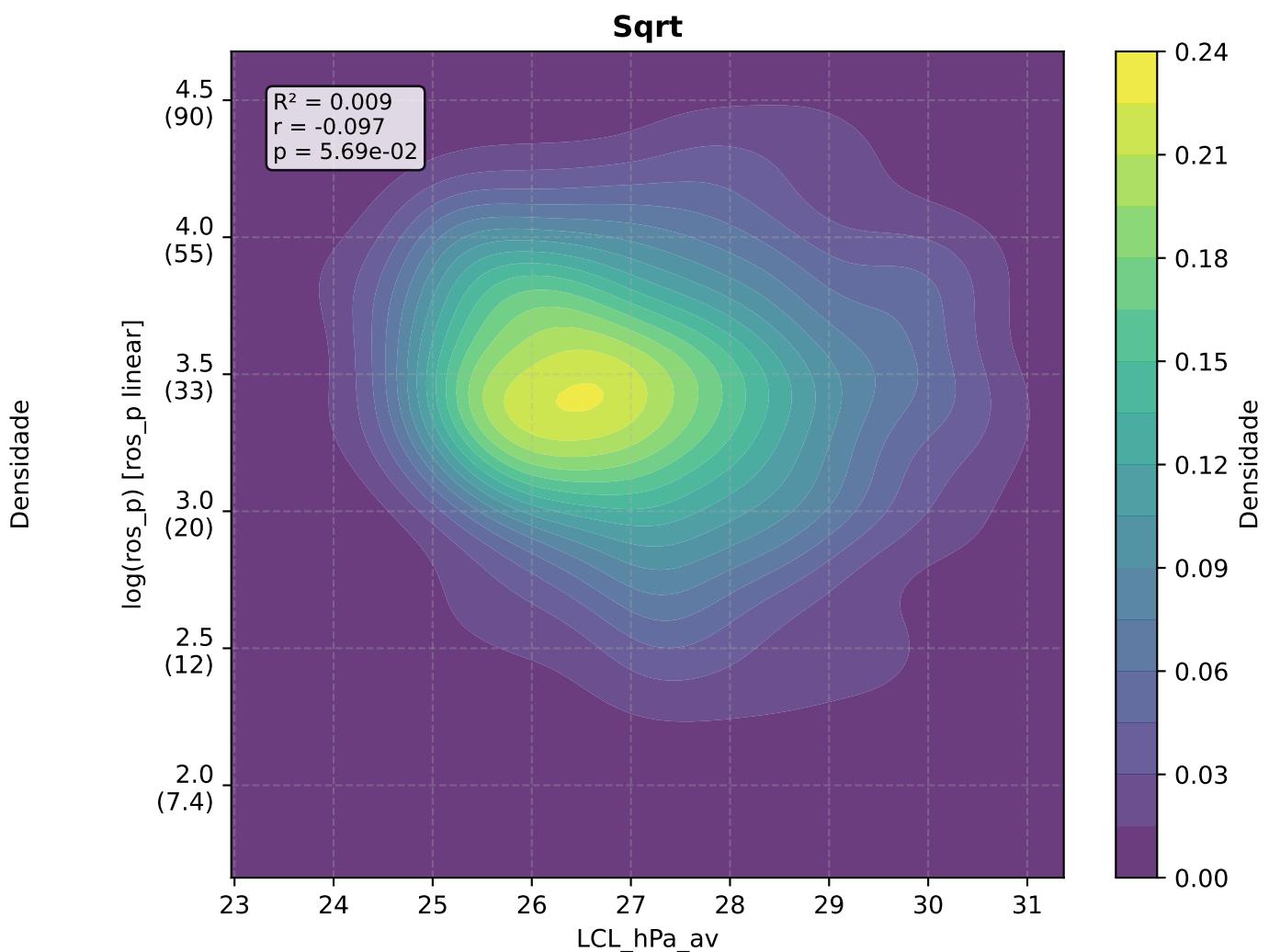
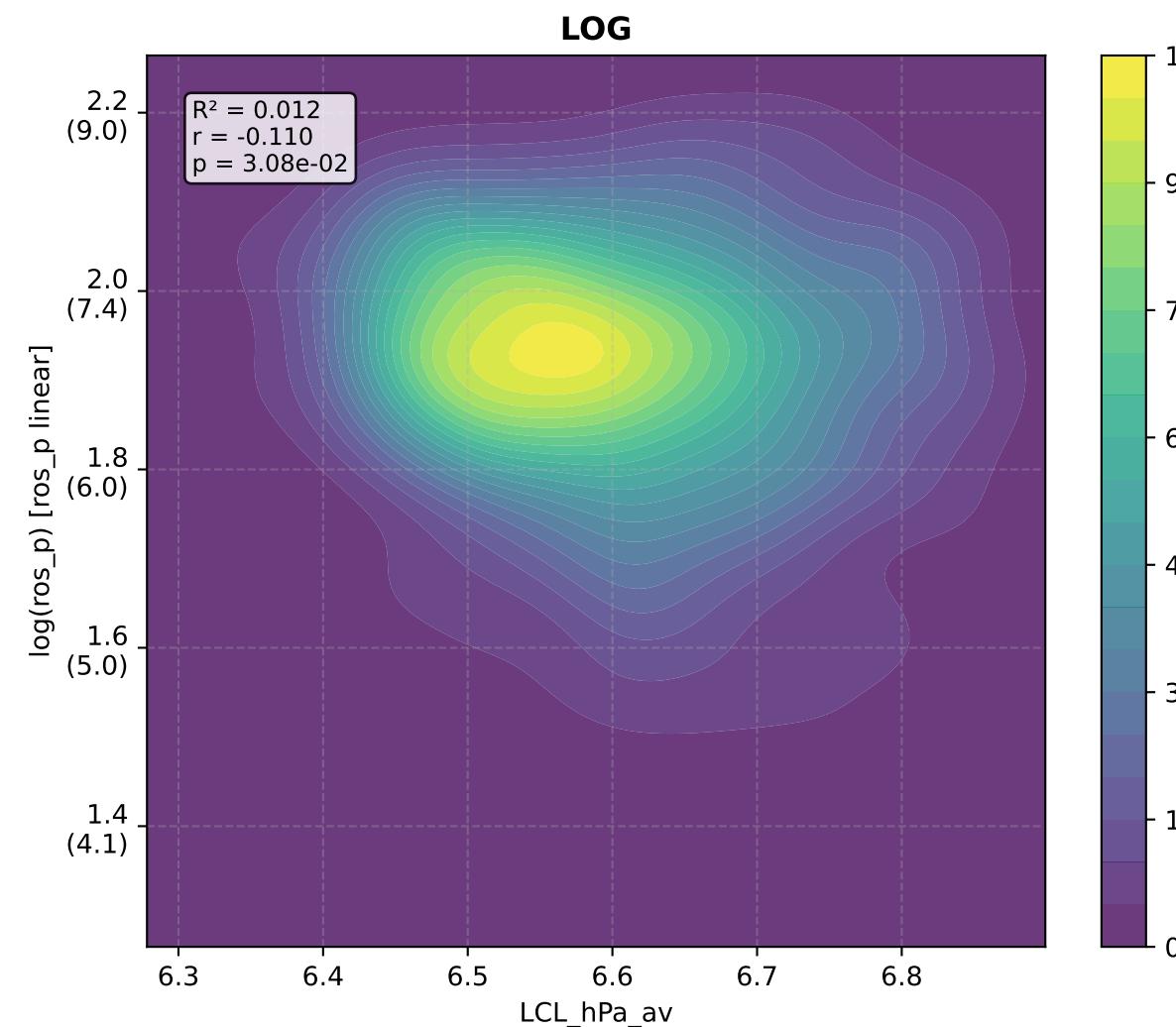
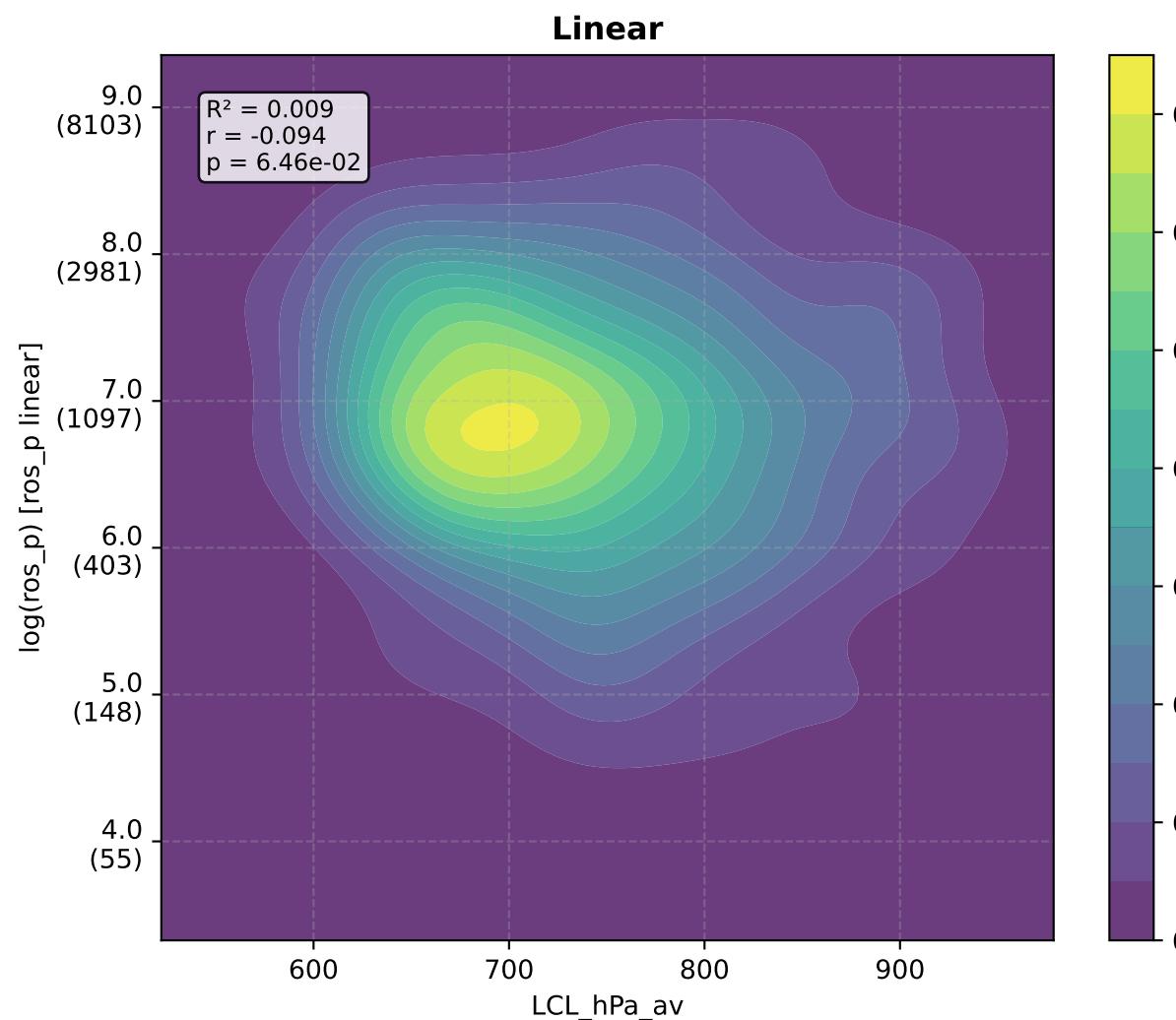
sW_1m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



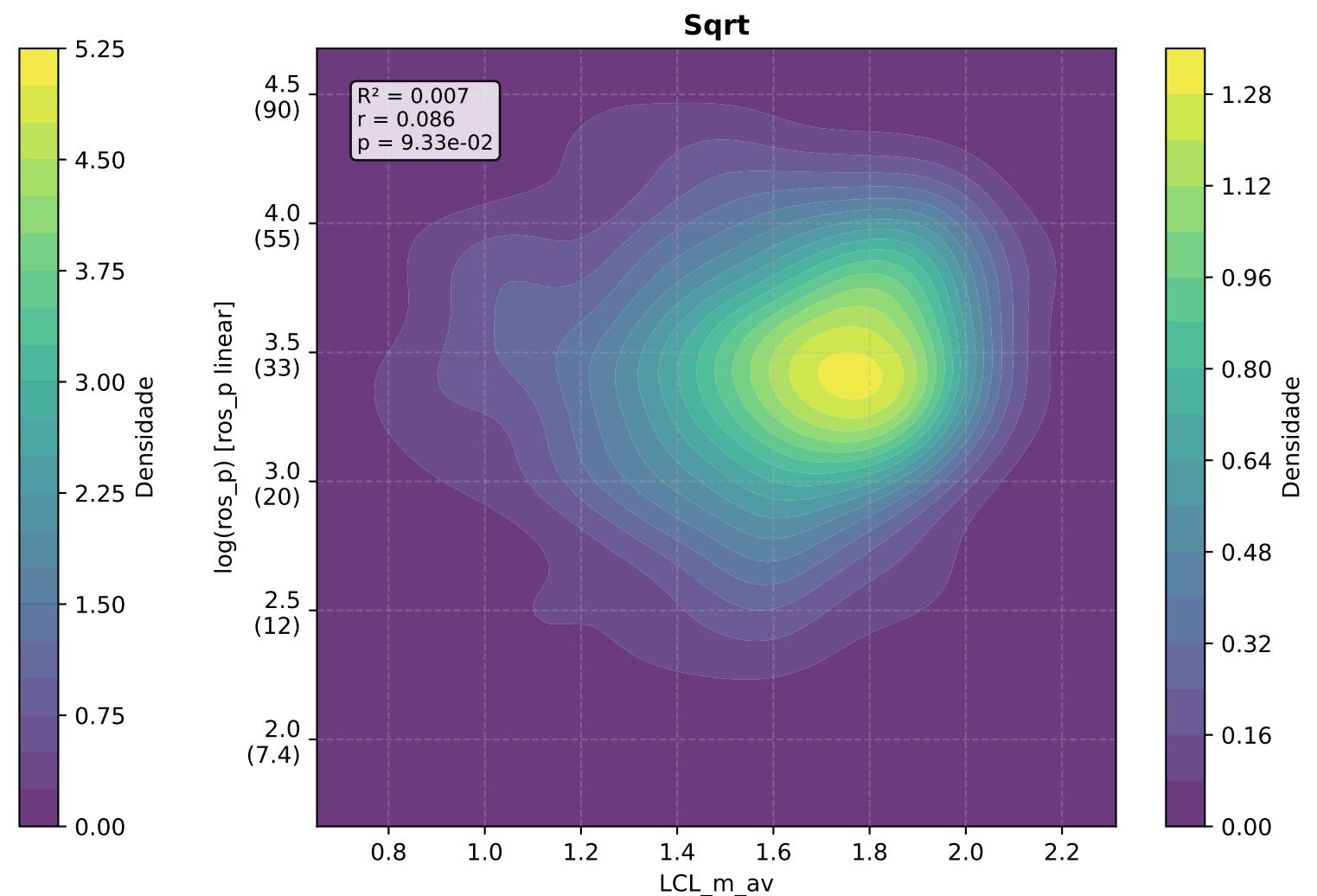
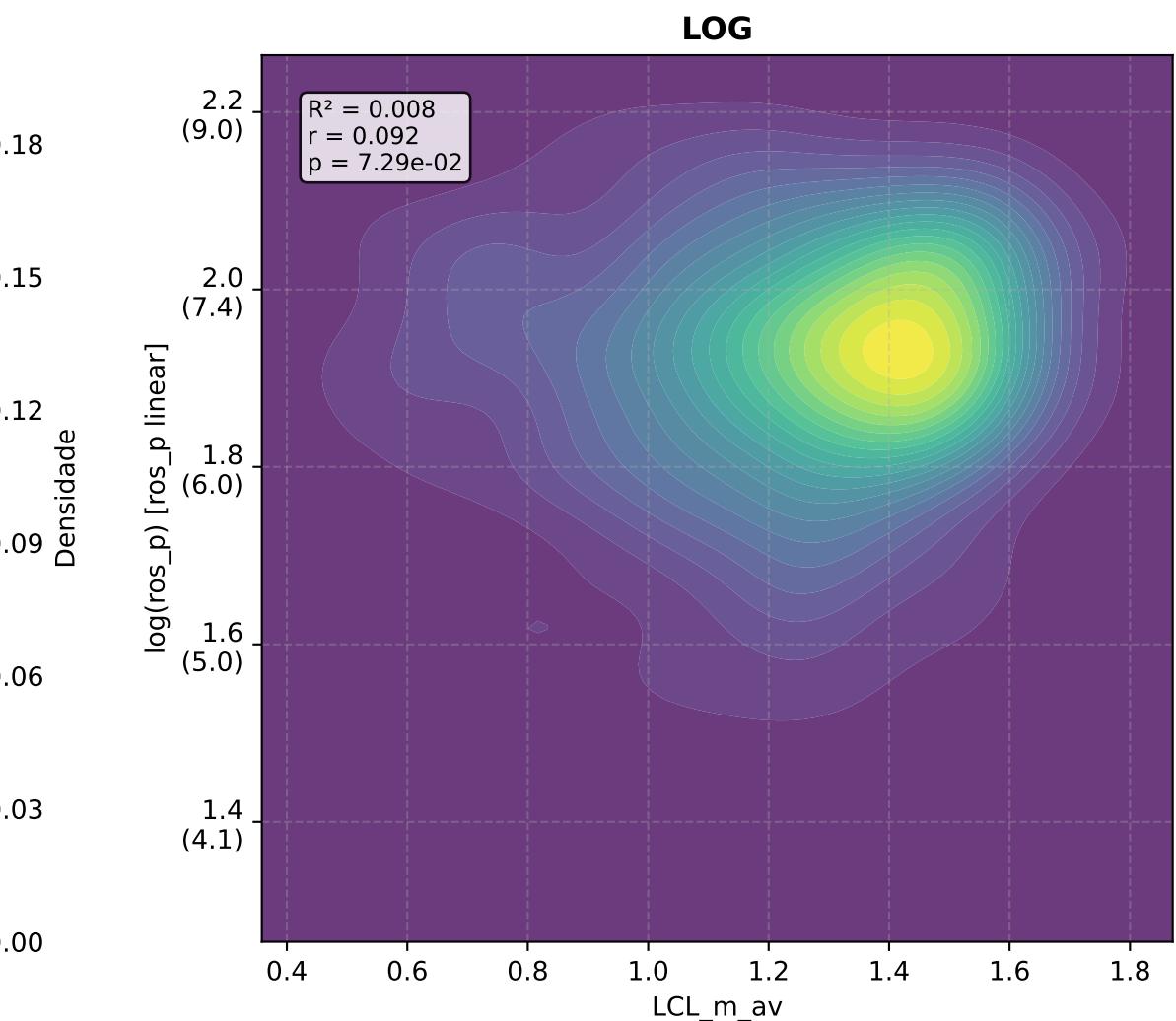
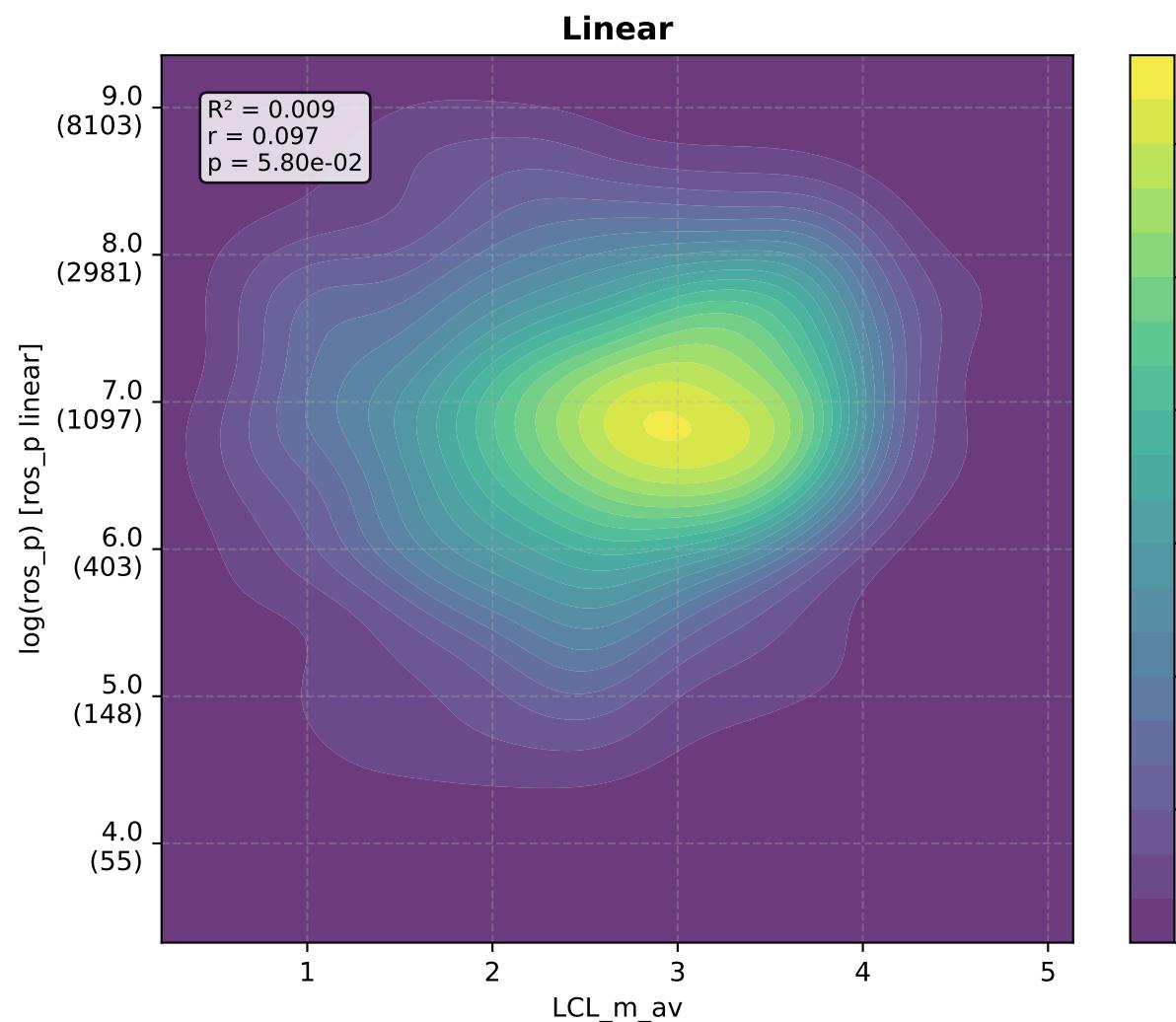
sW_3m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



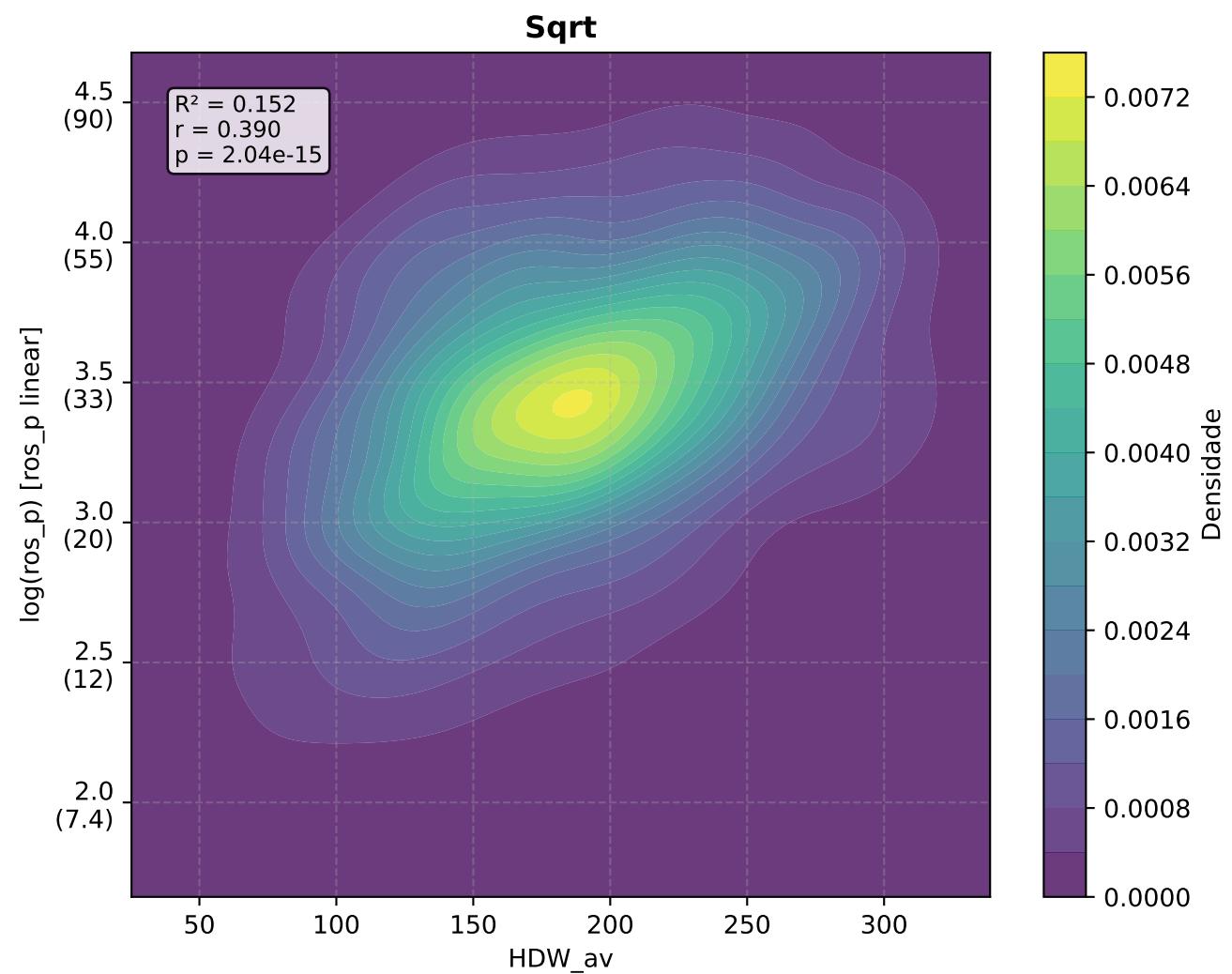
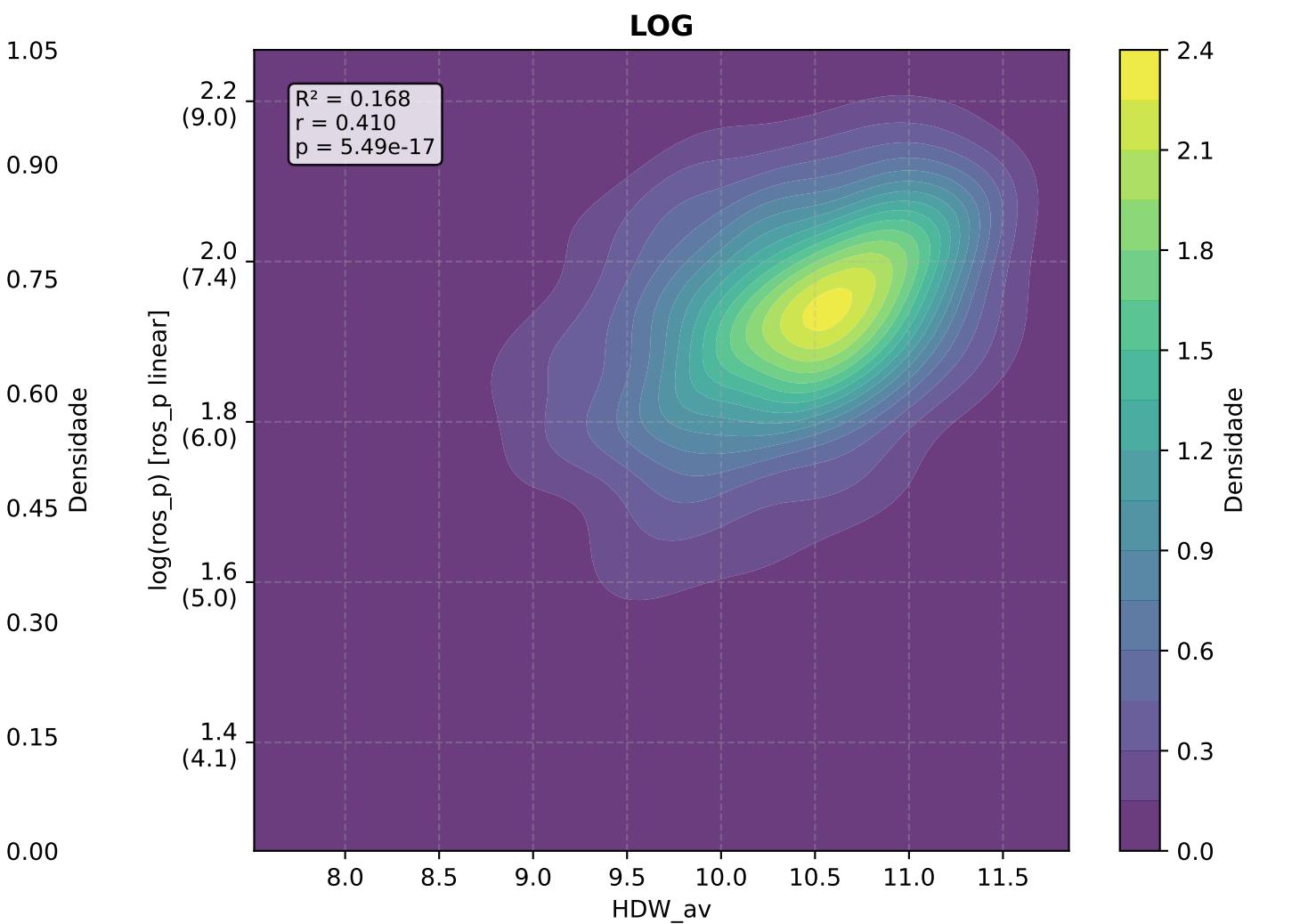
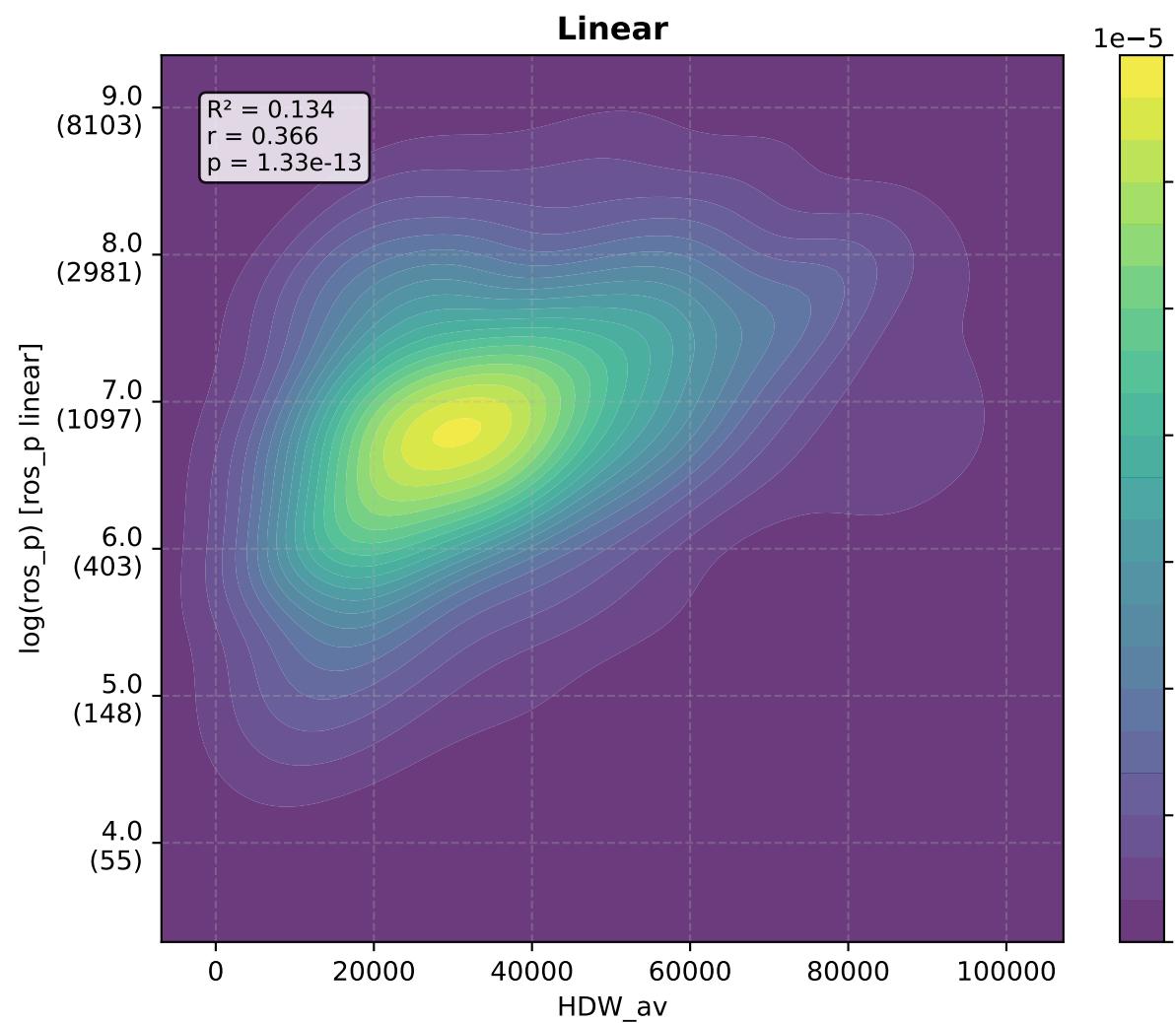
LCL_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



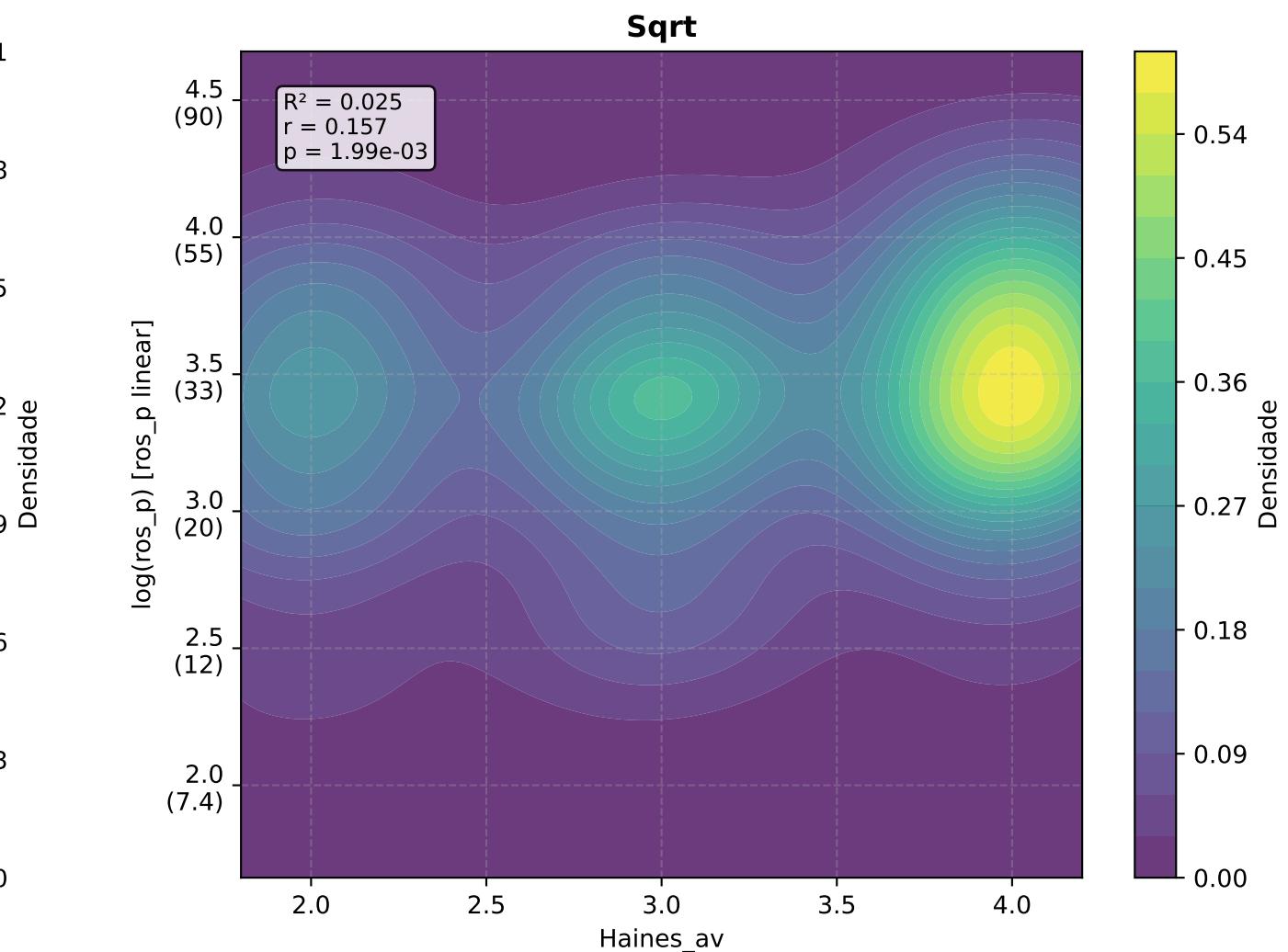
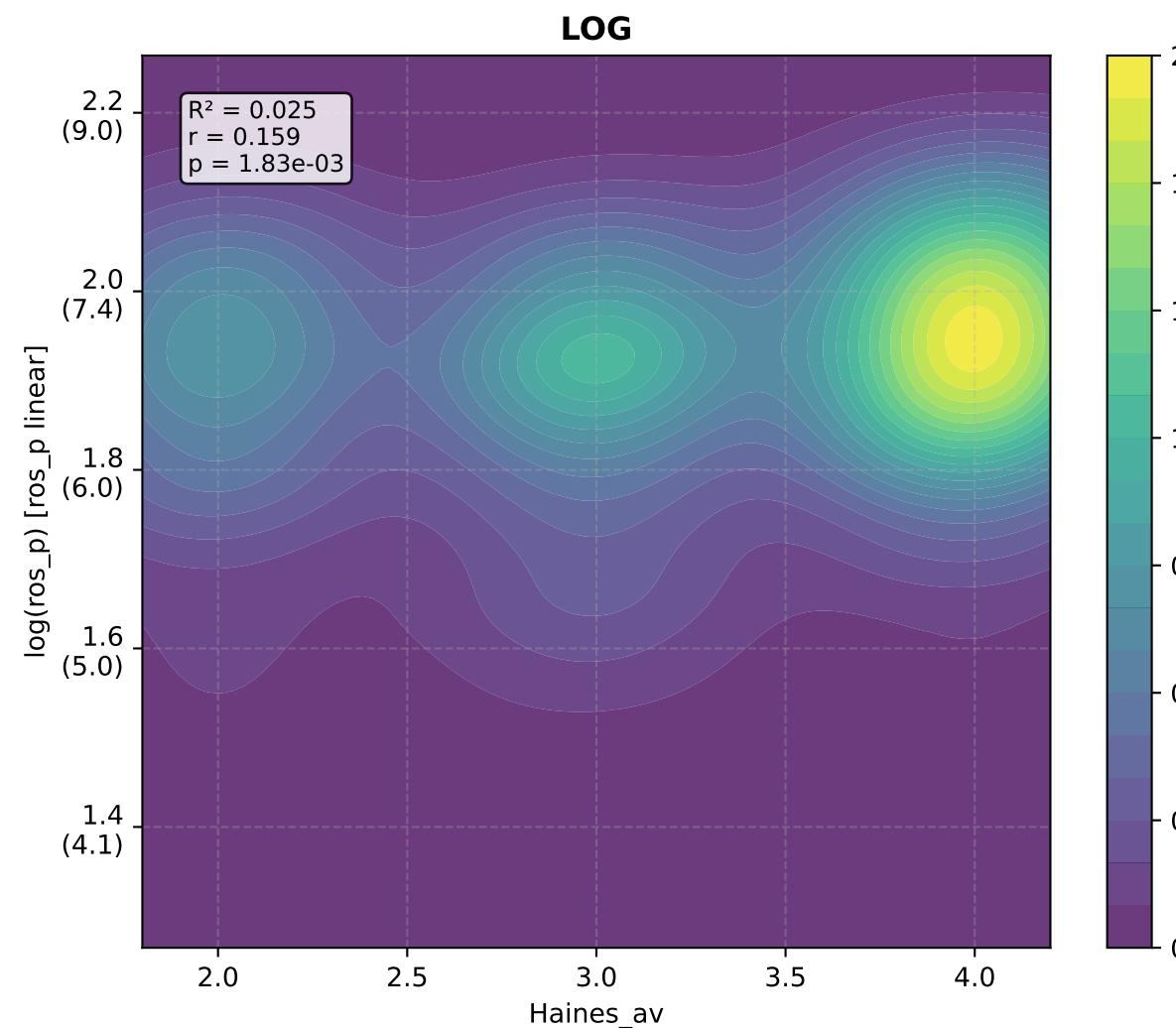
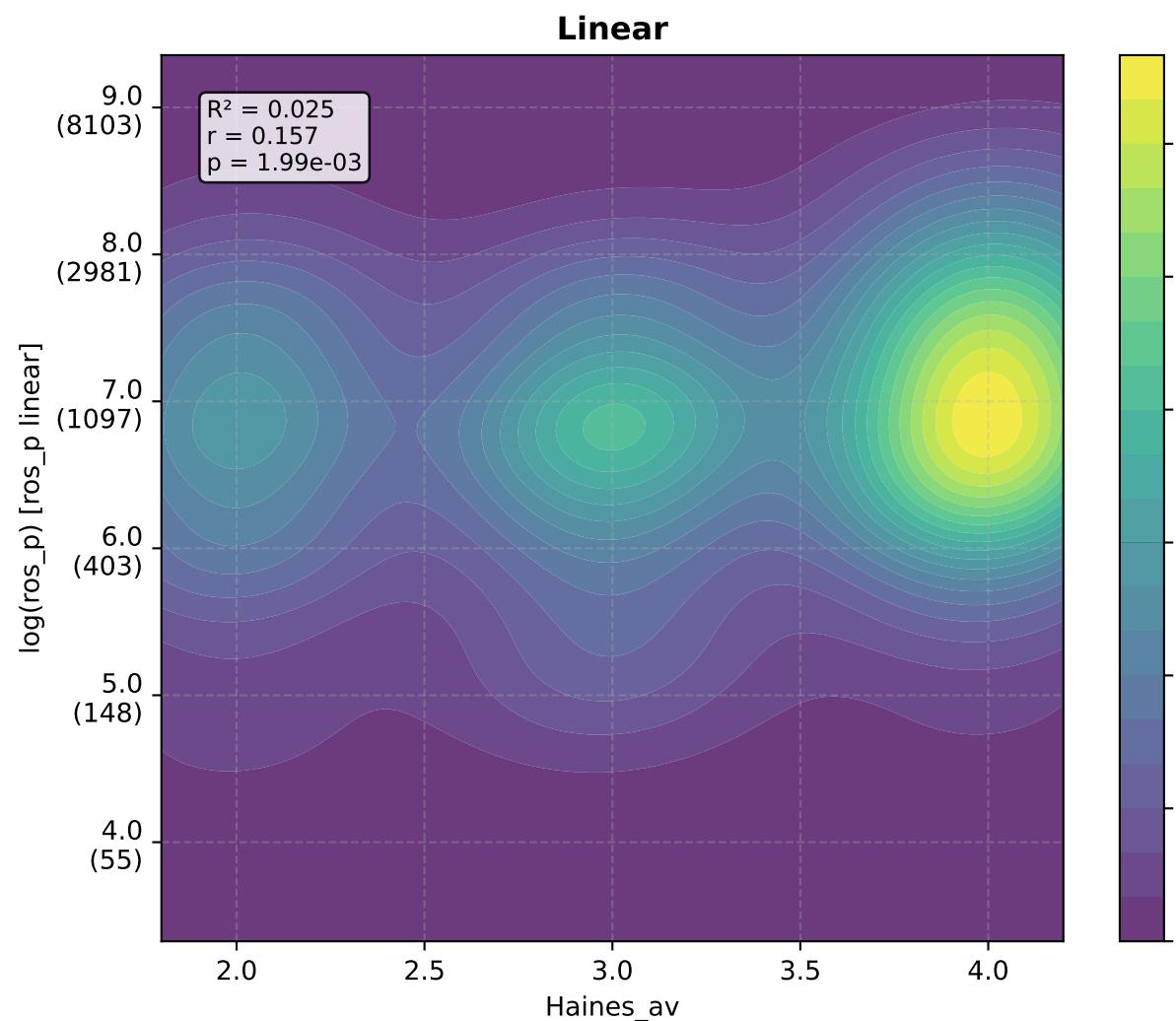
LCL_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



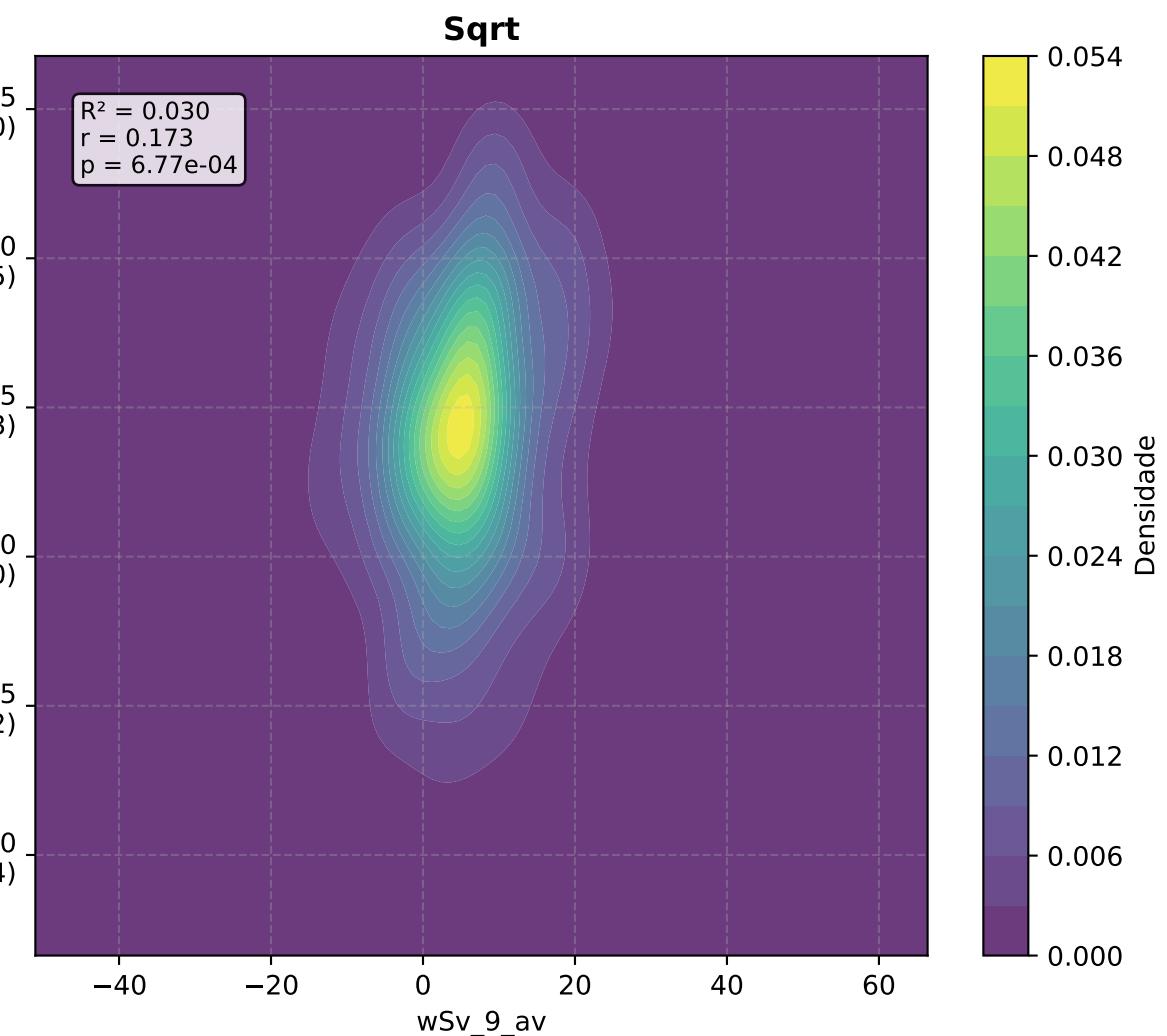
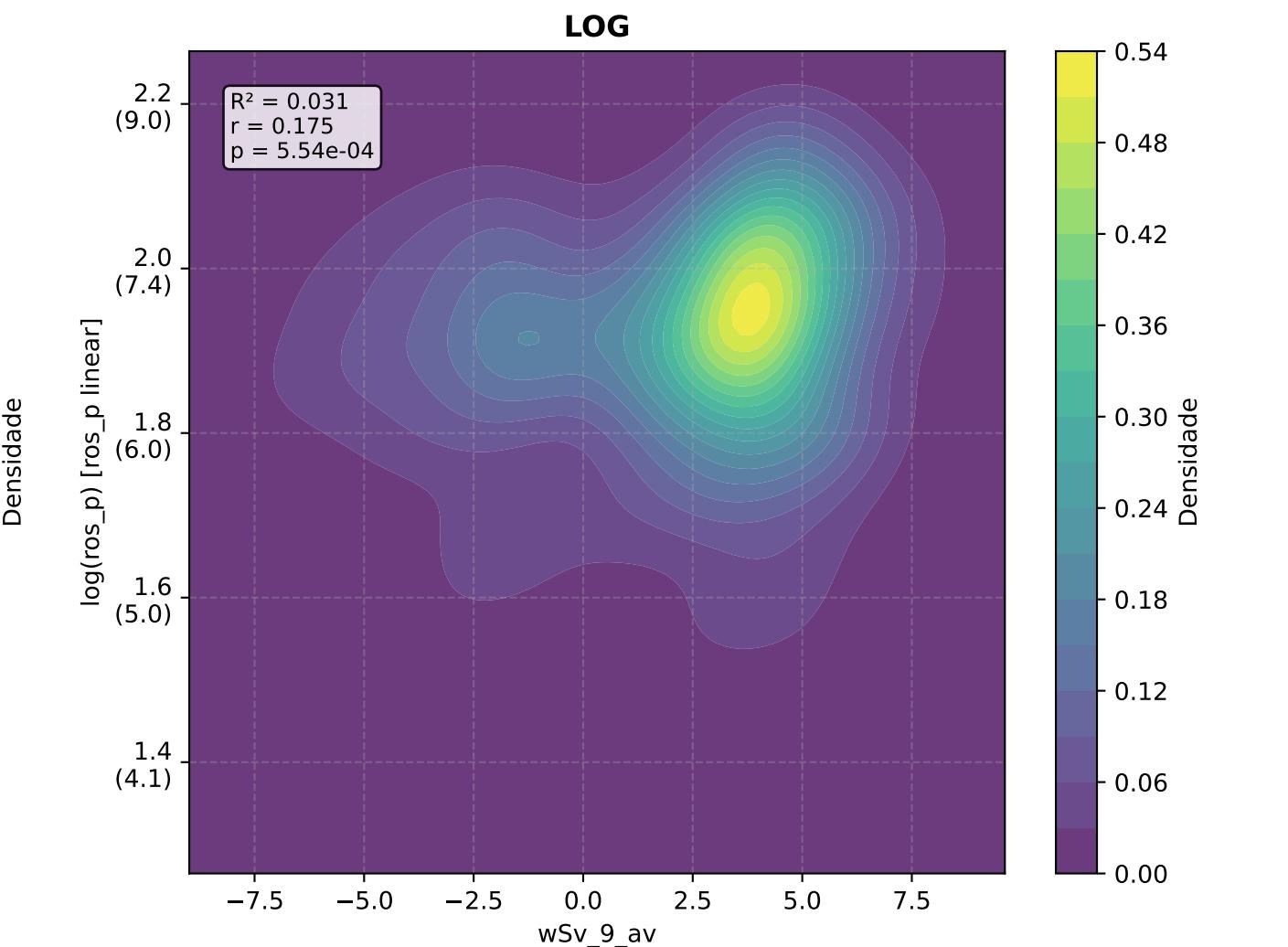
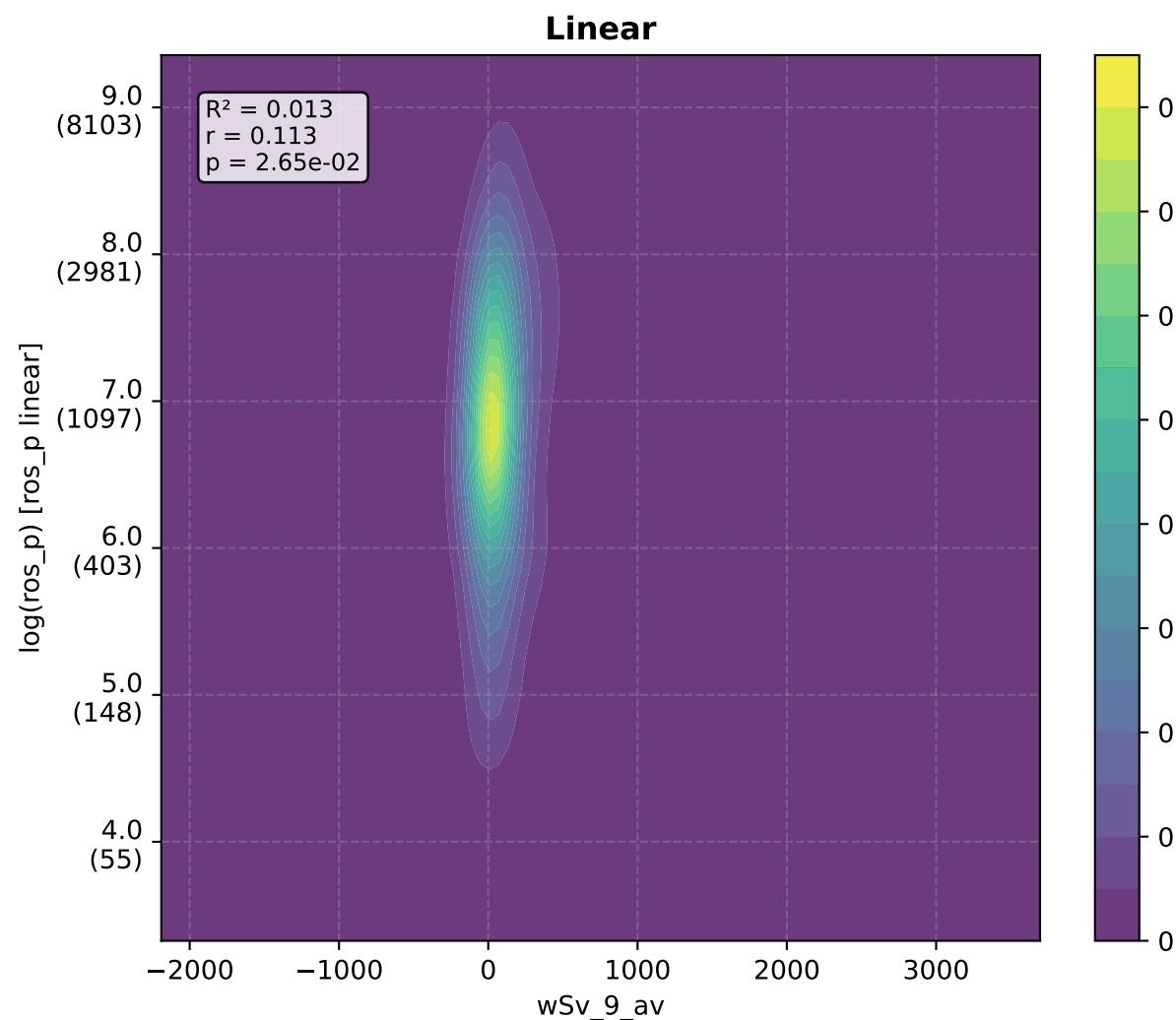
HDW_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



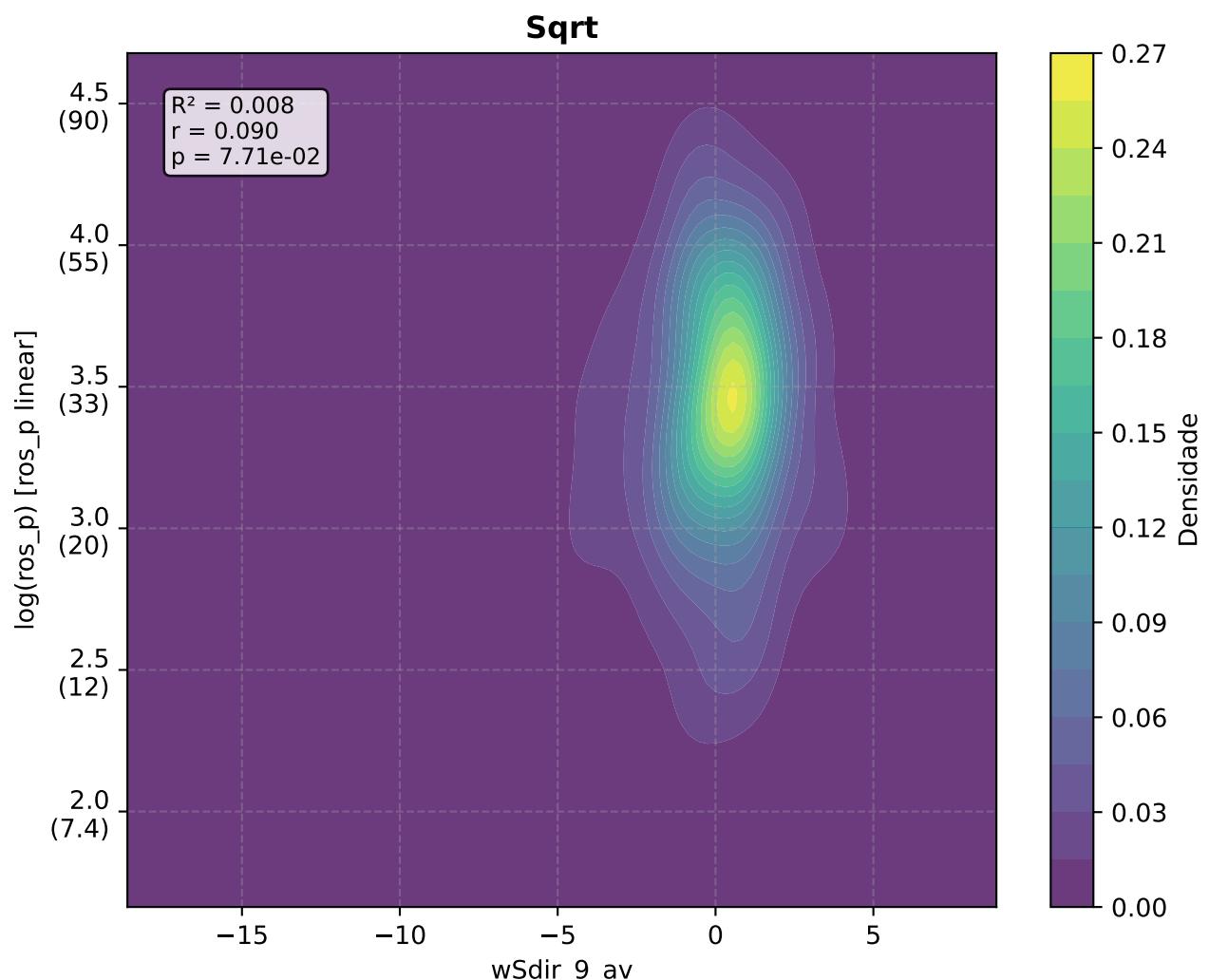
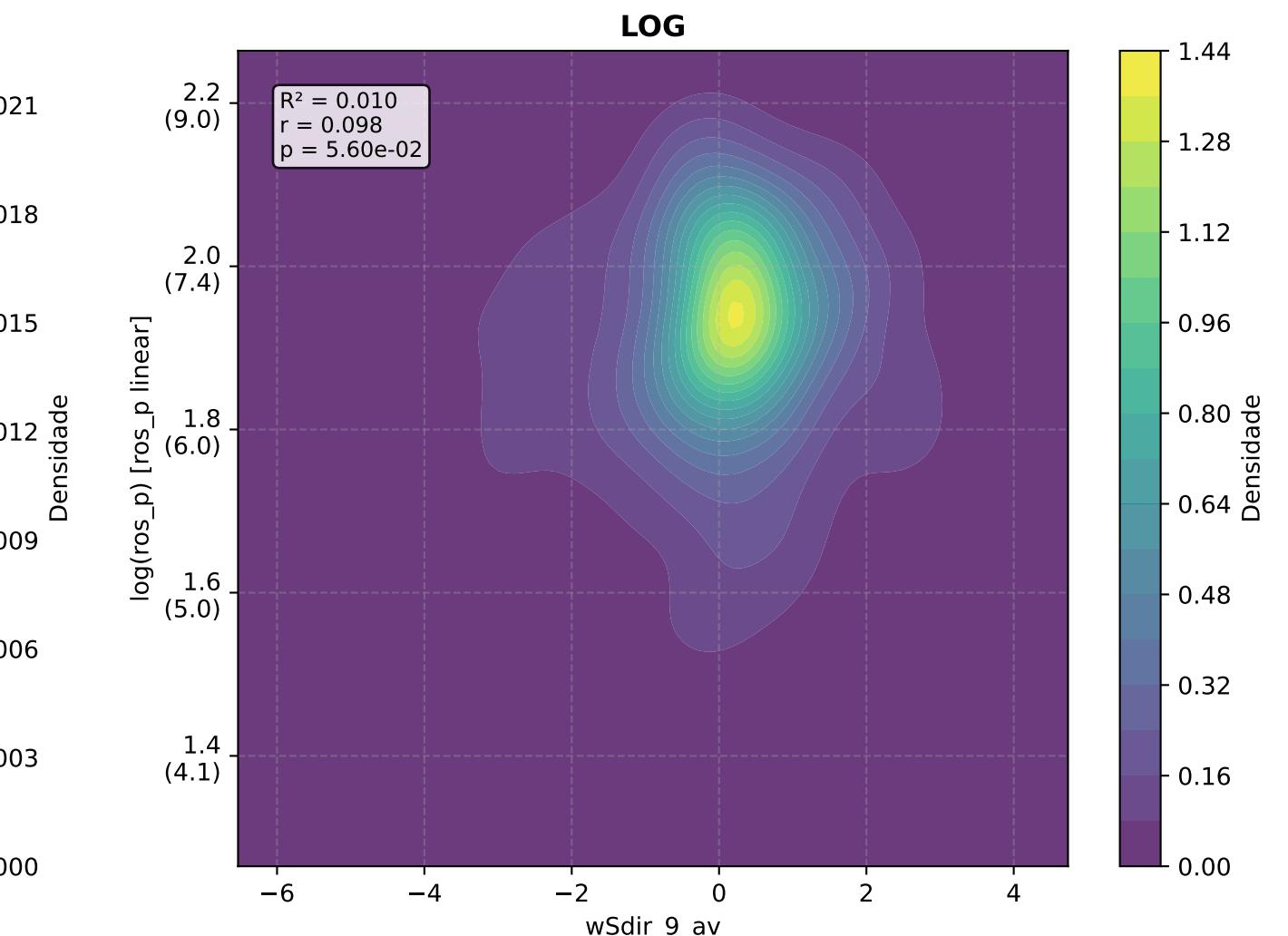
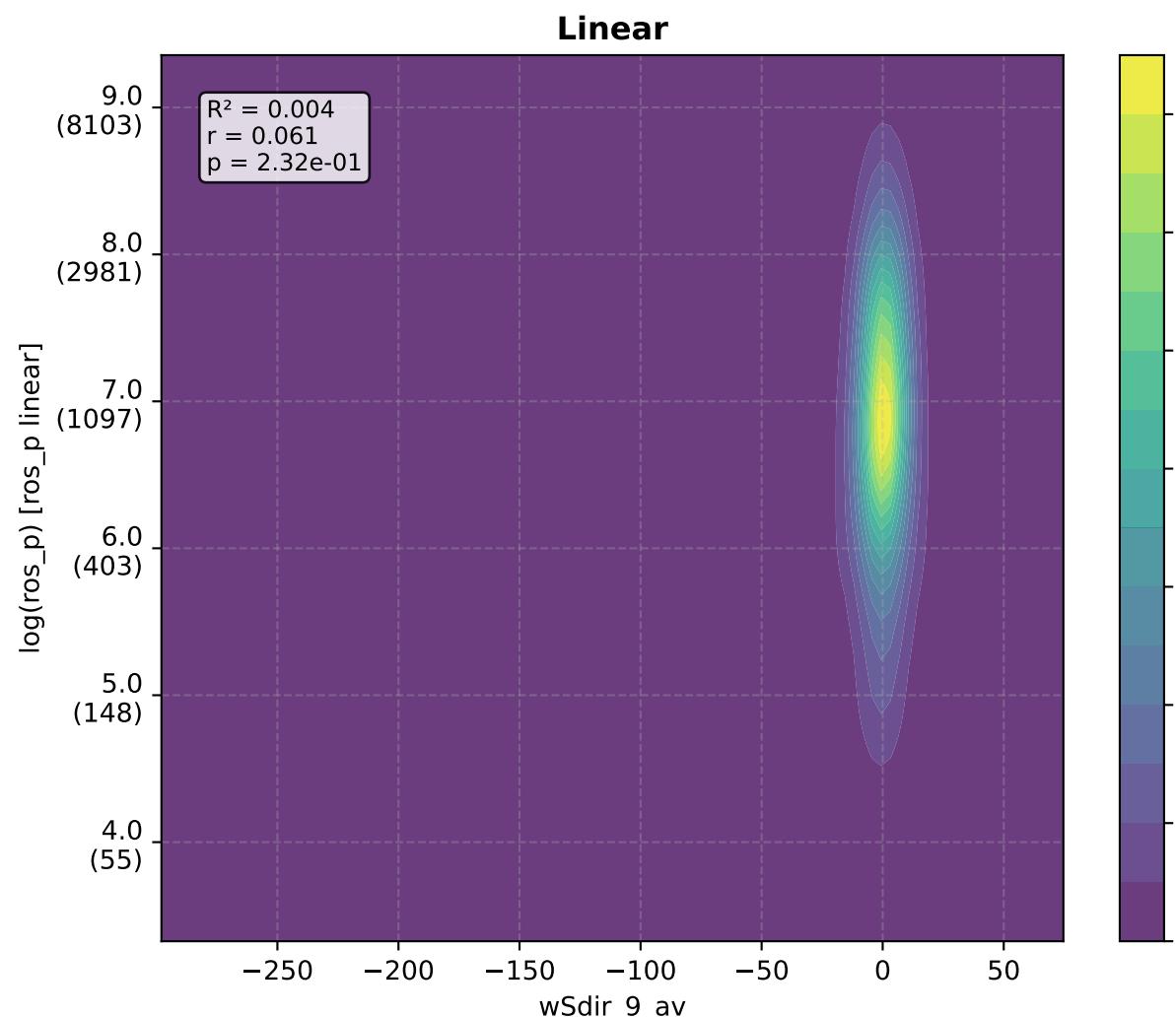
Haines_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



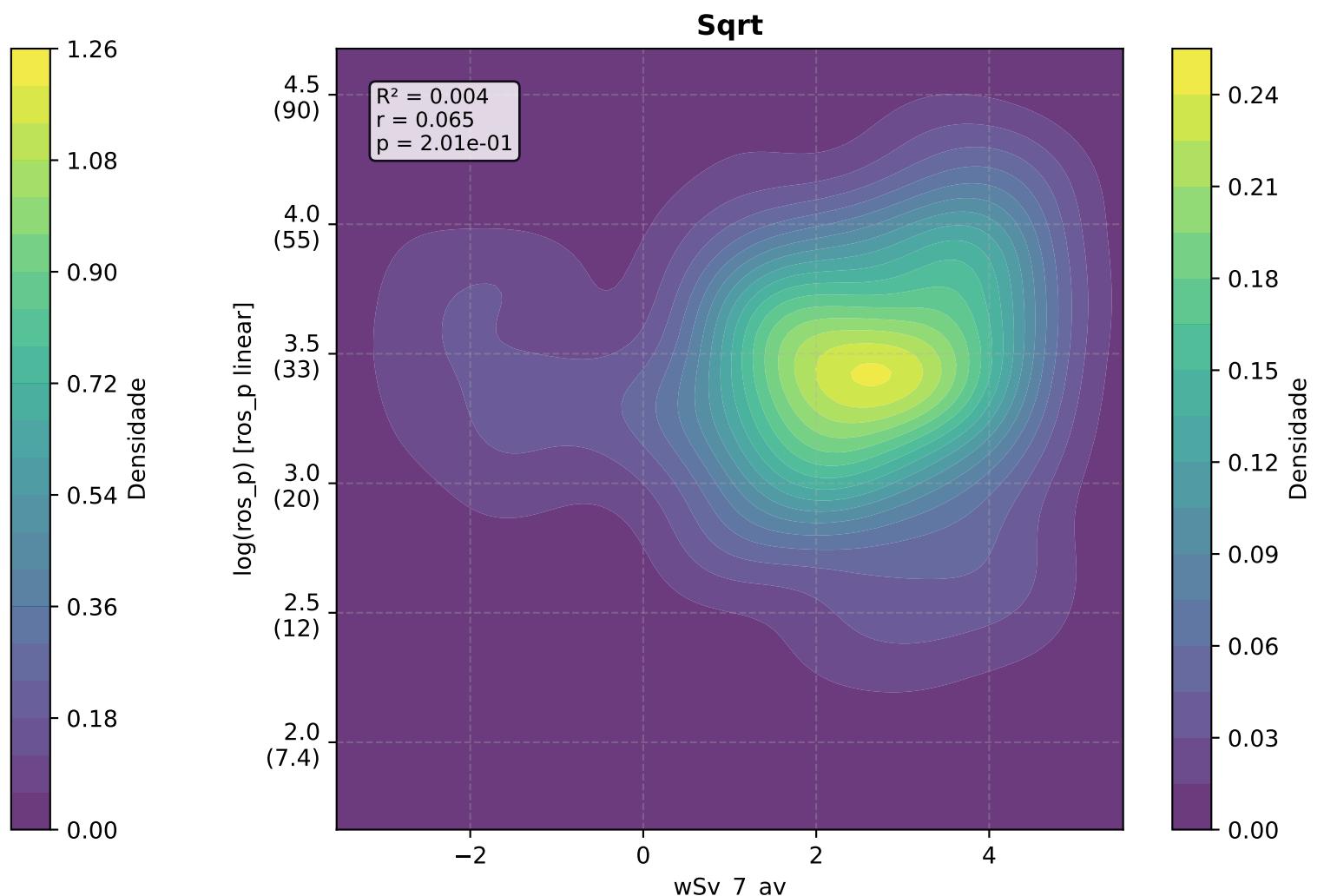
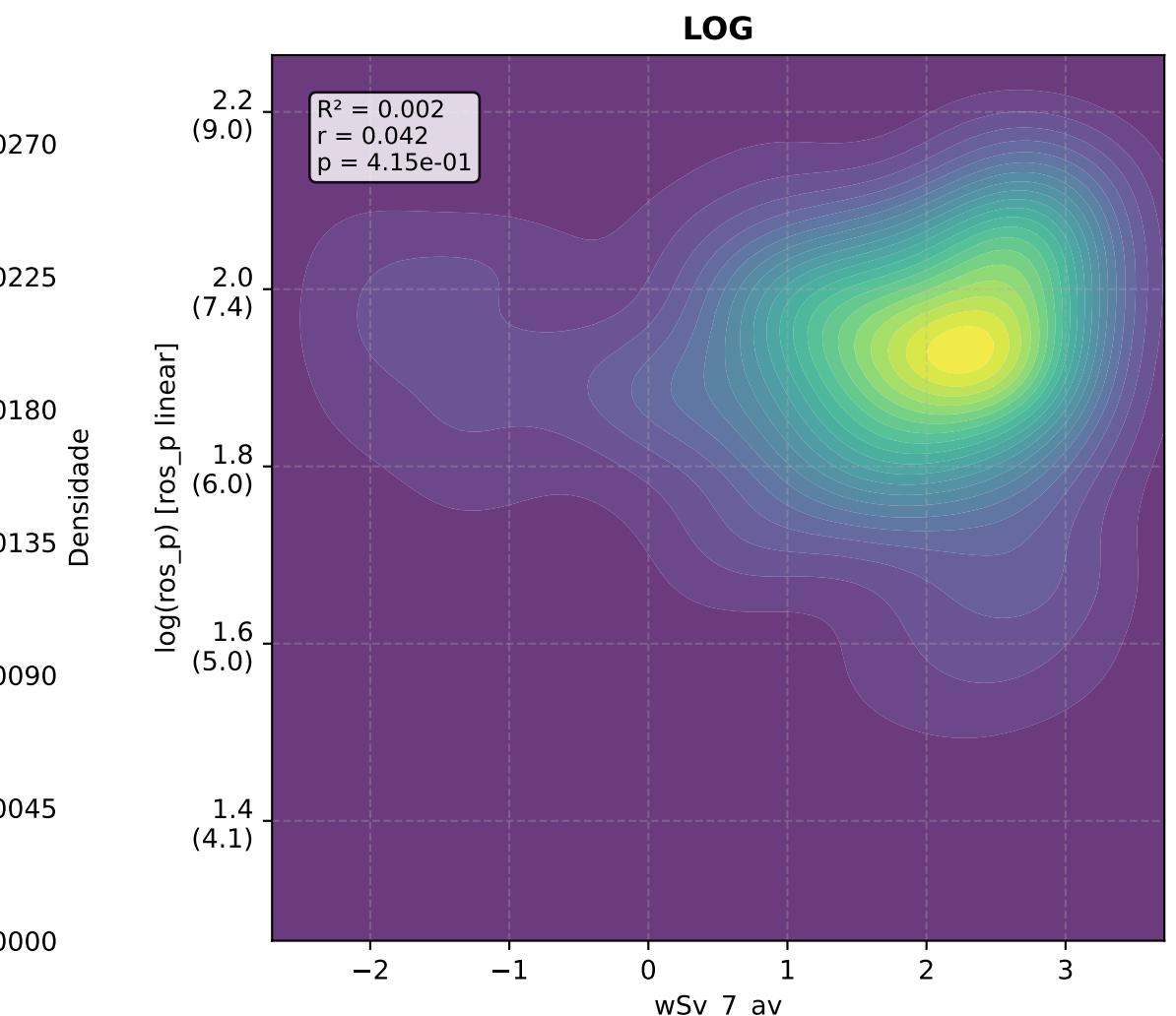
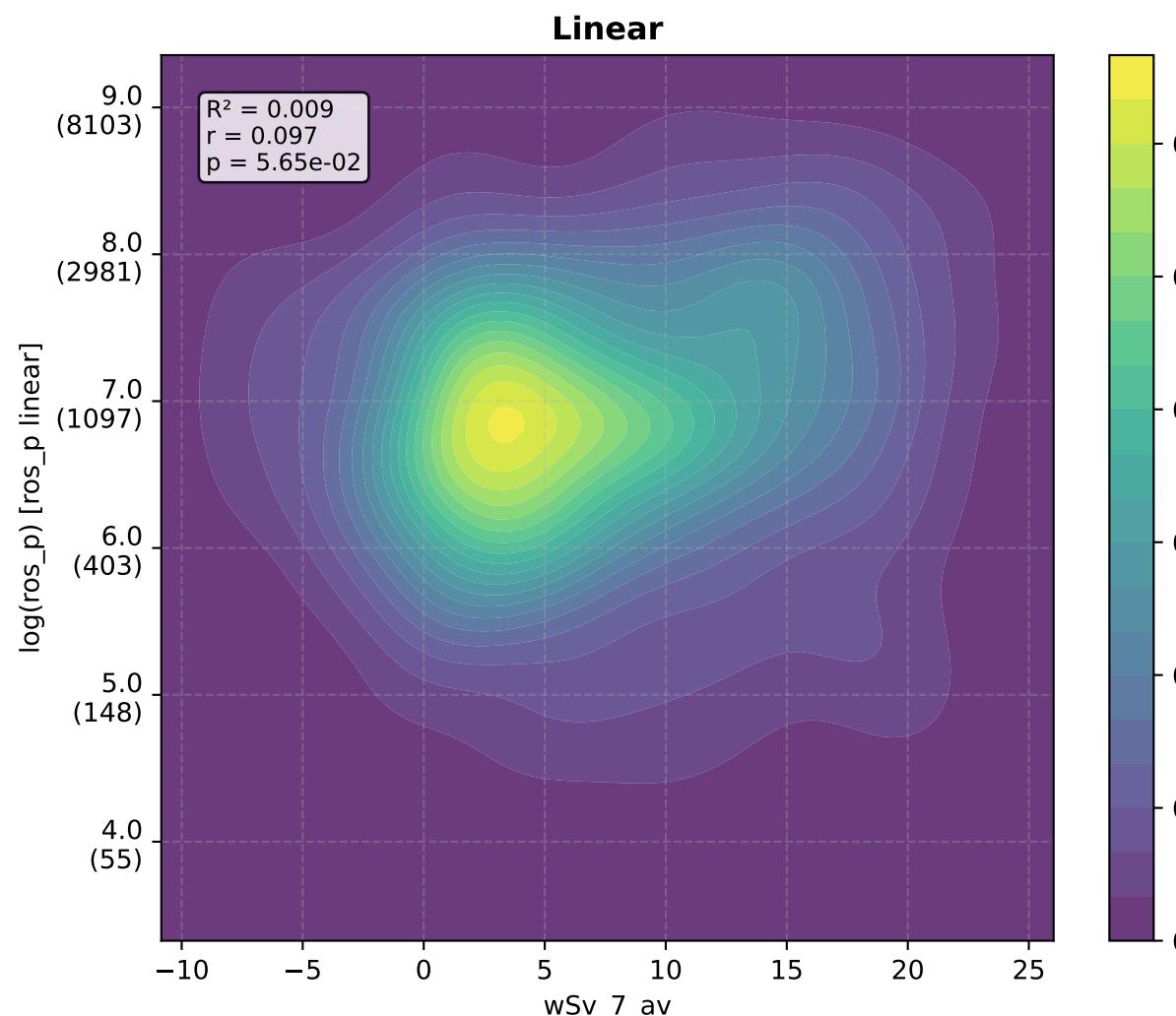
wSv_9_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



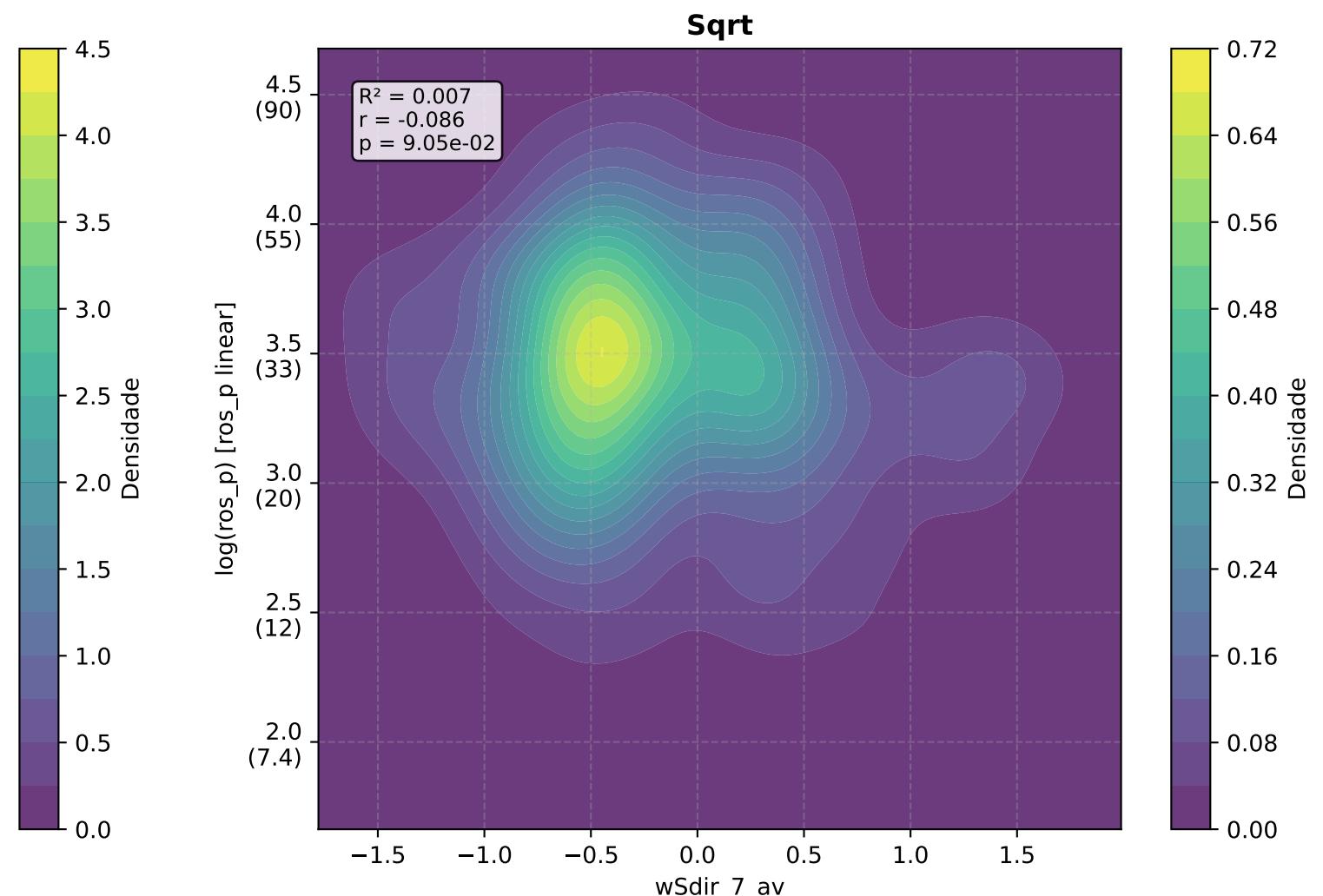
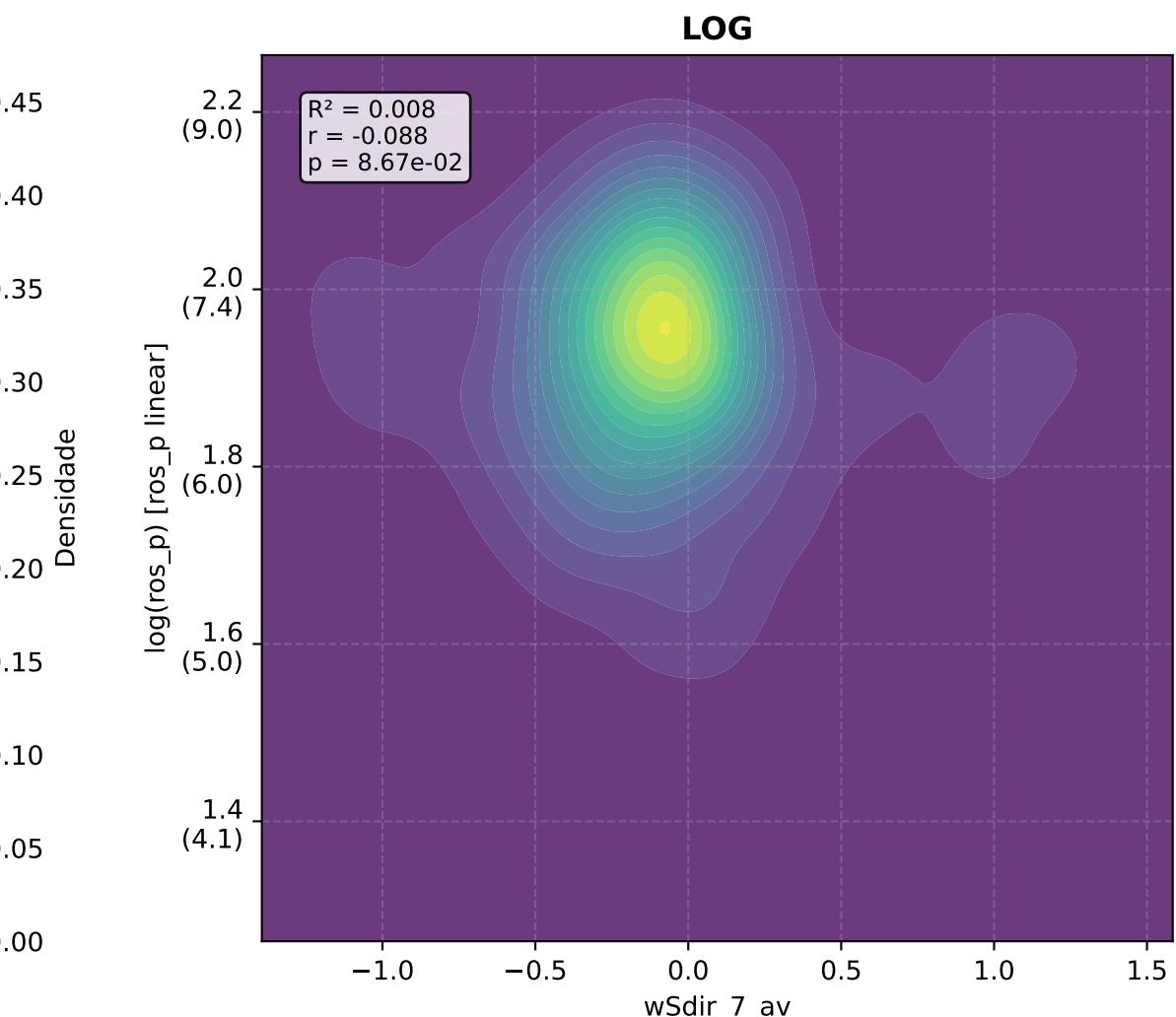
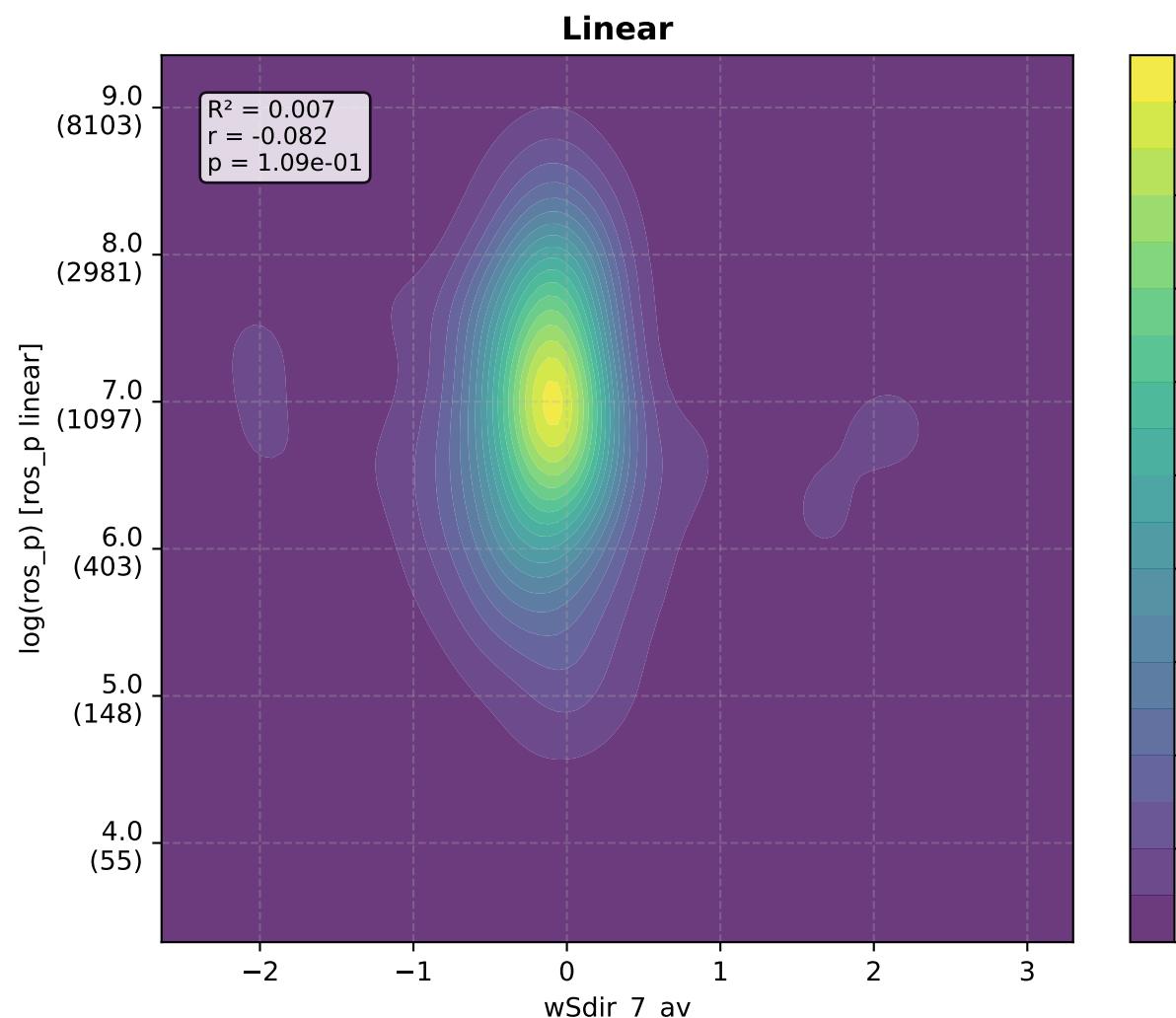
wSdir_9_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



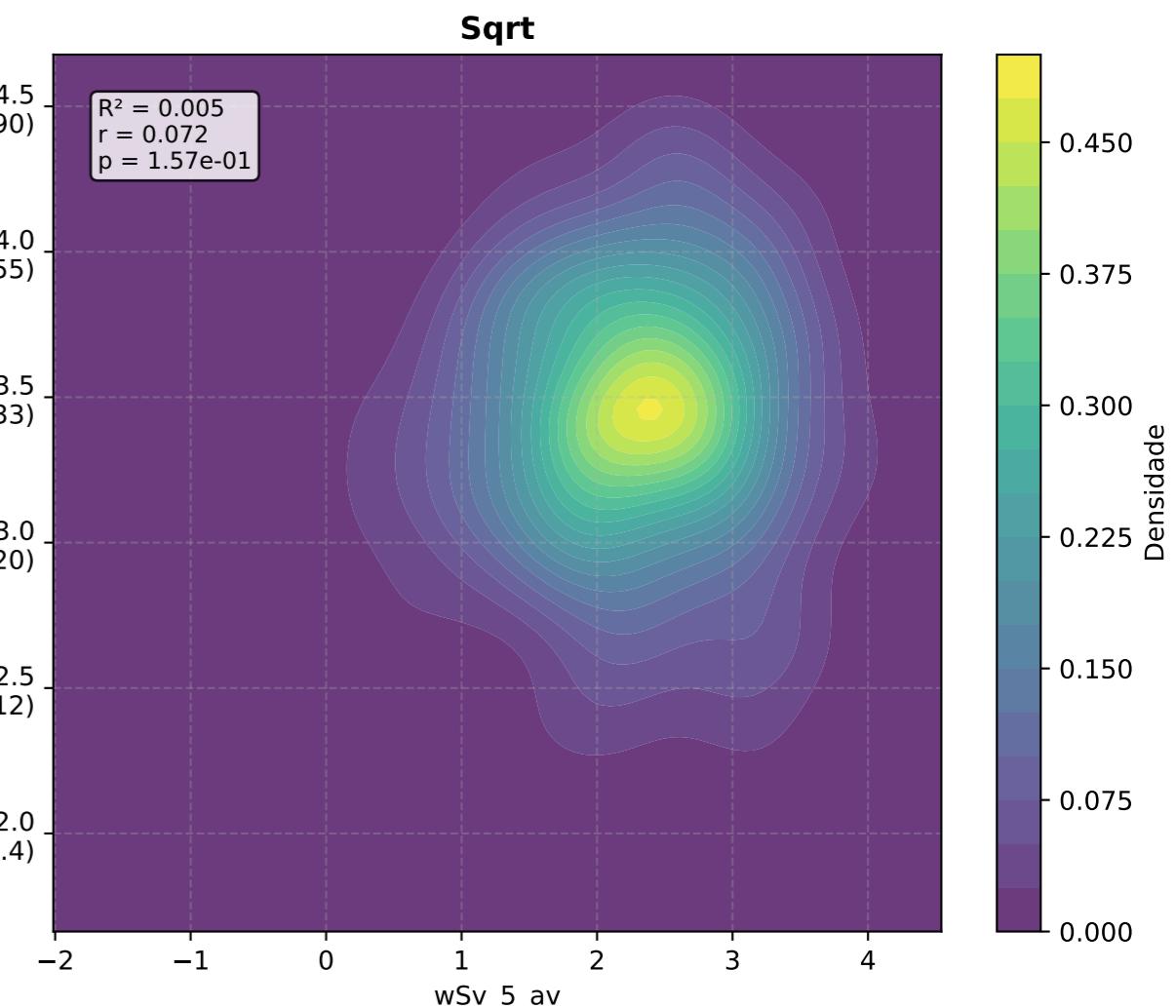
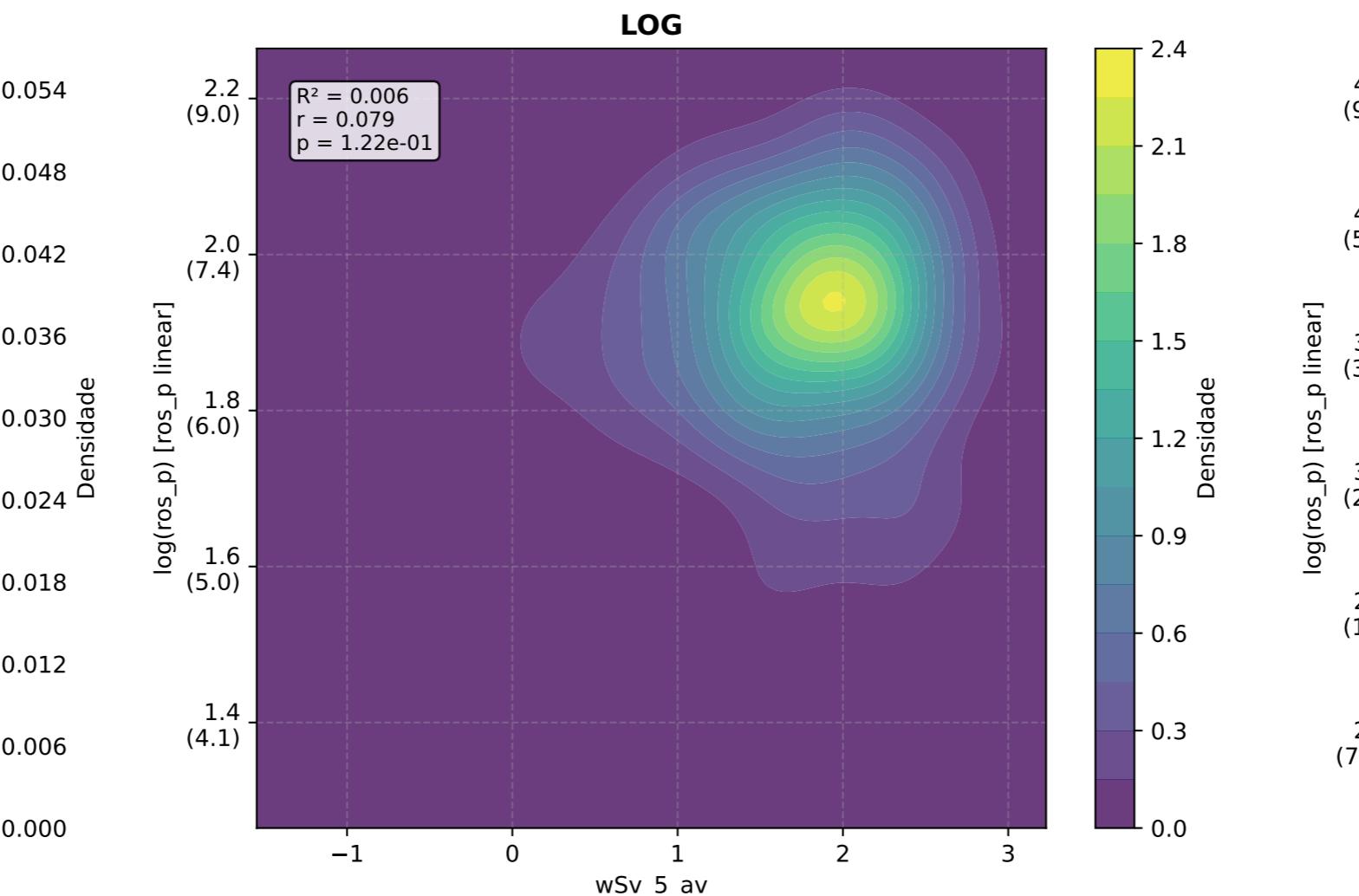
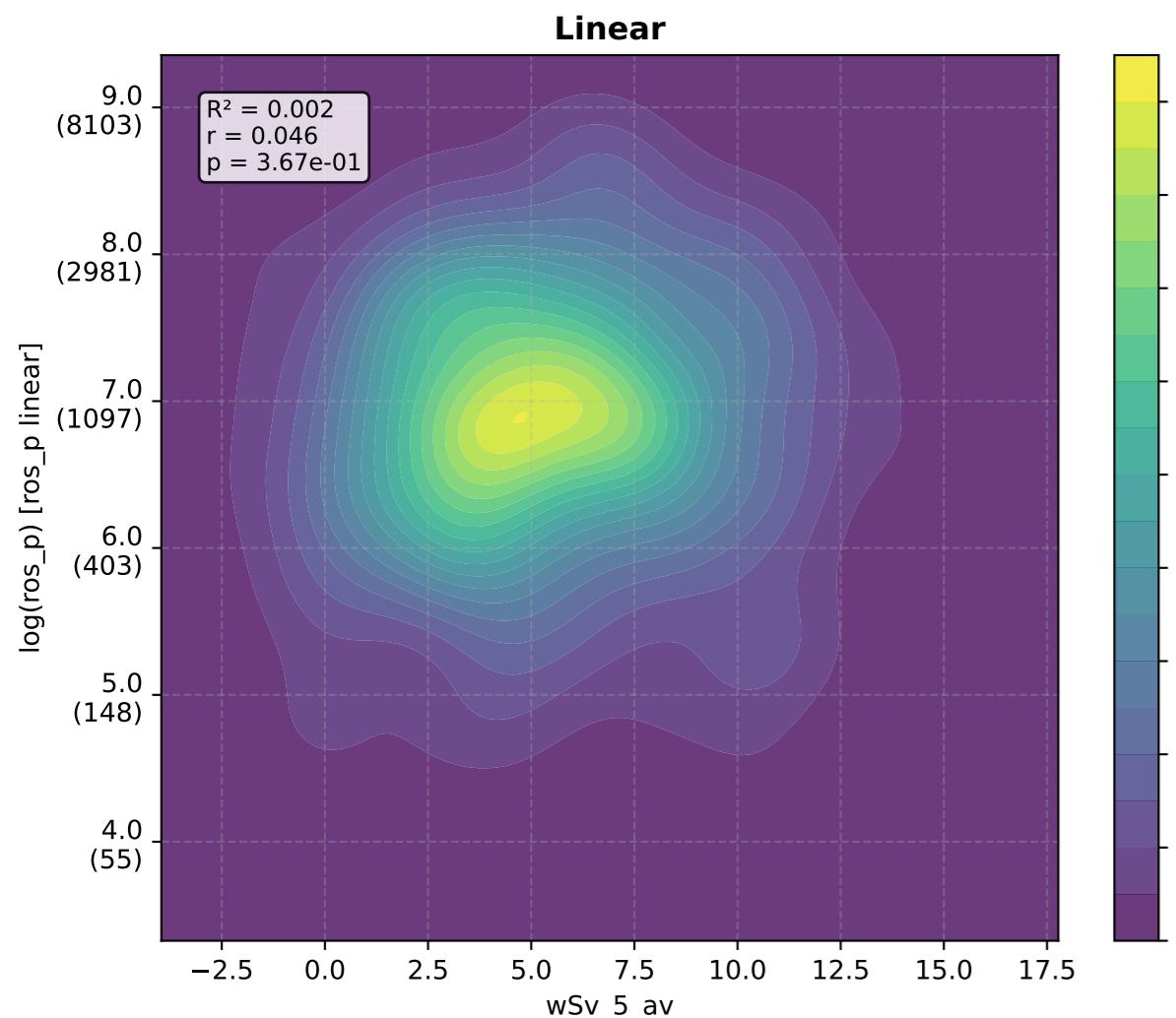
wSv_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



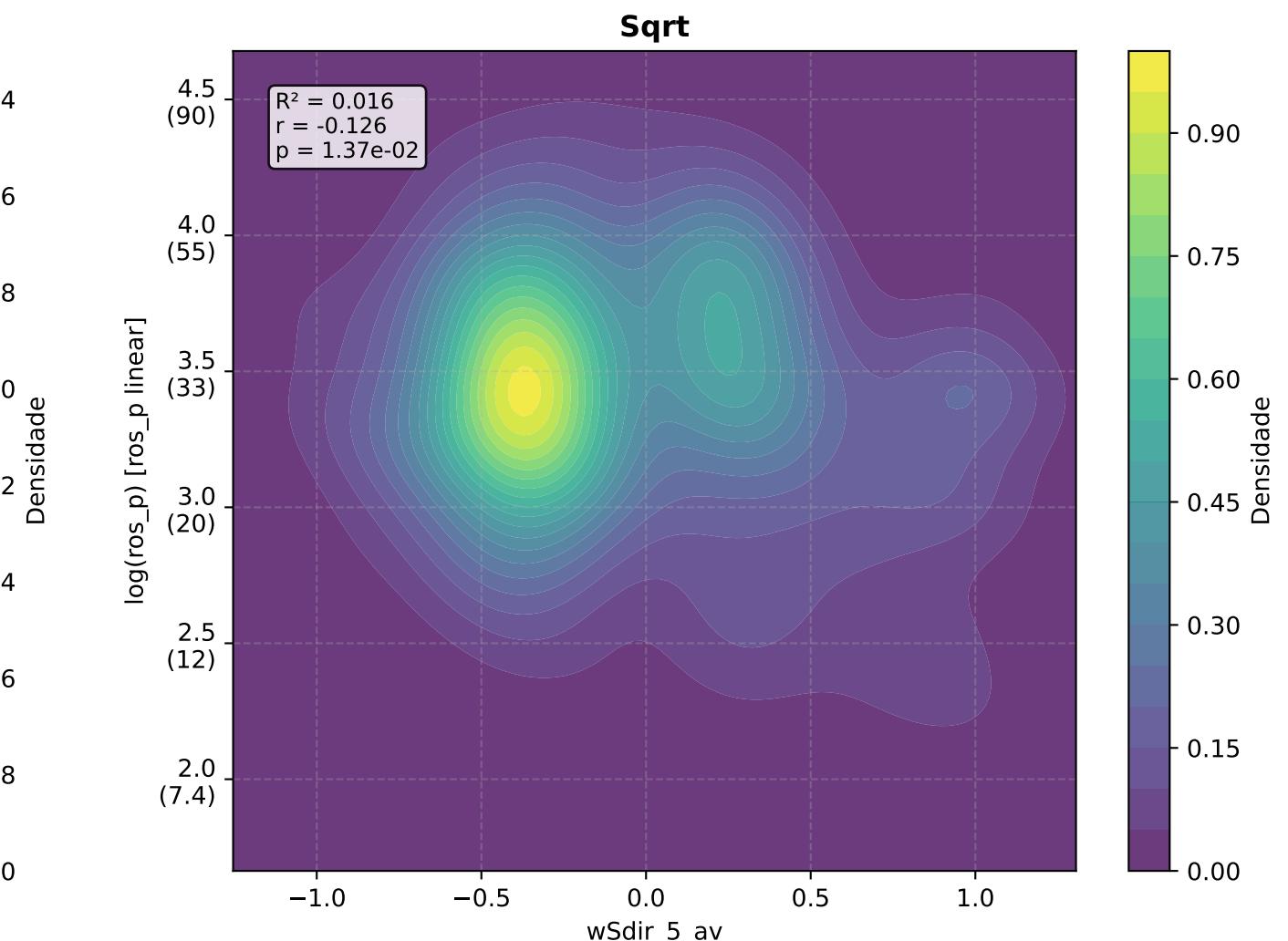
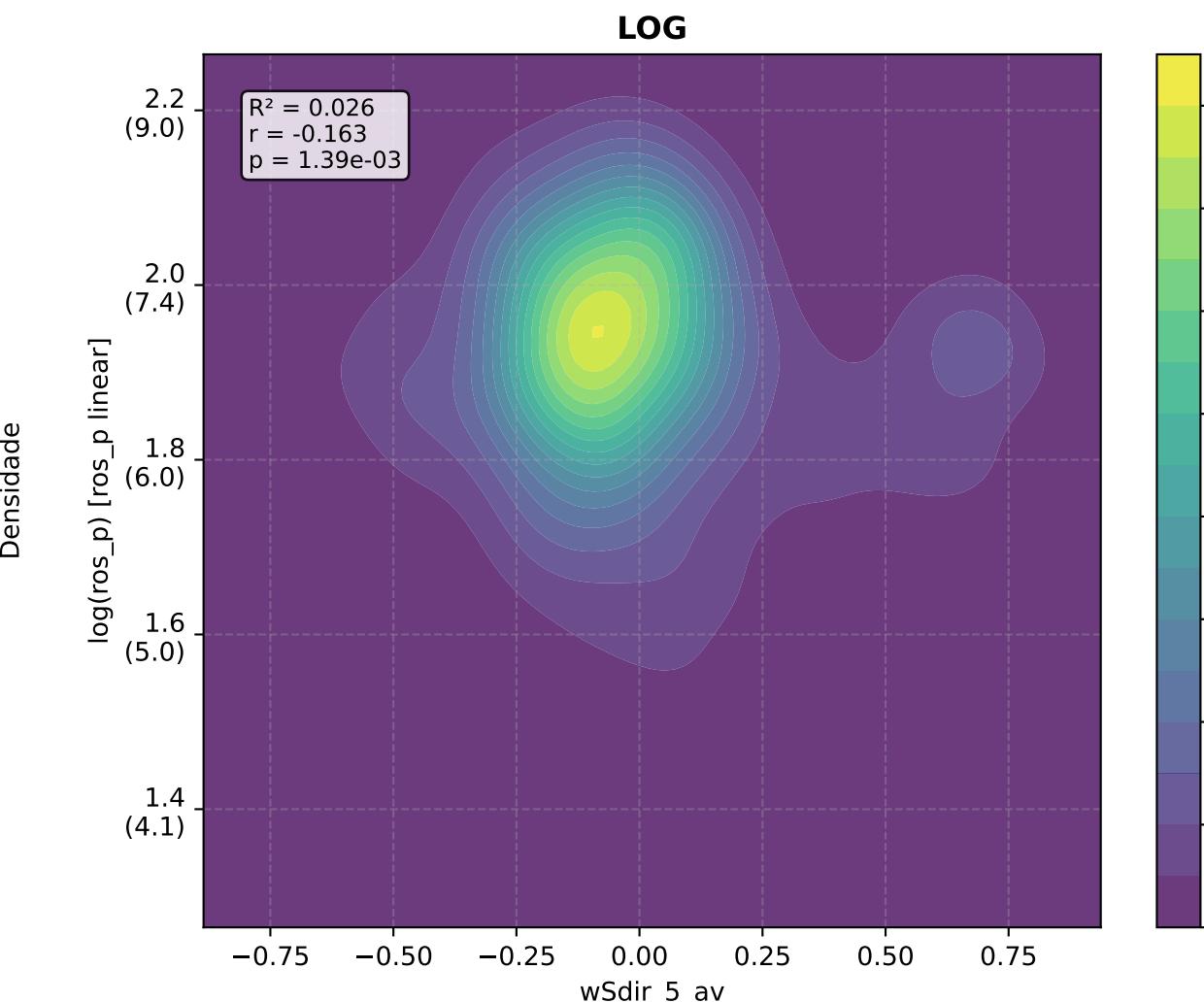
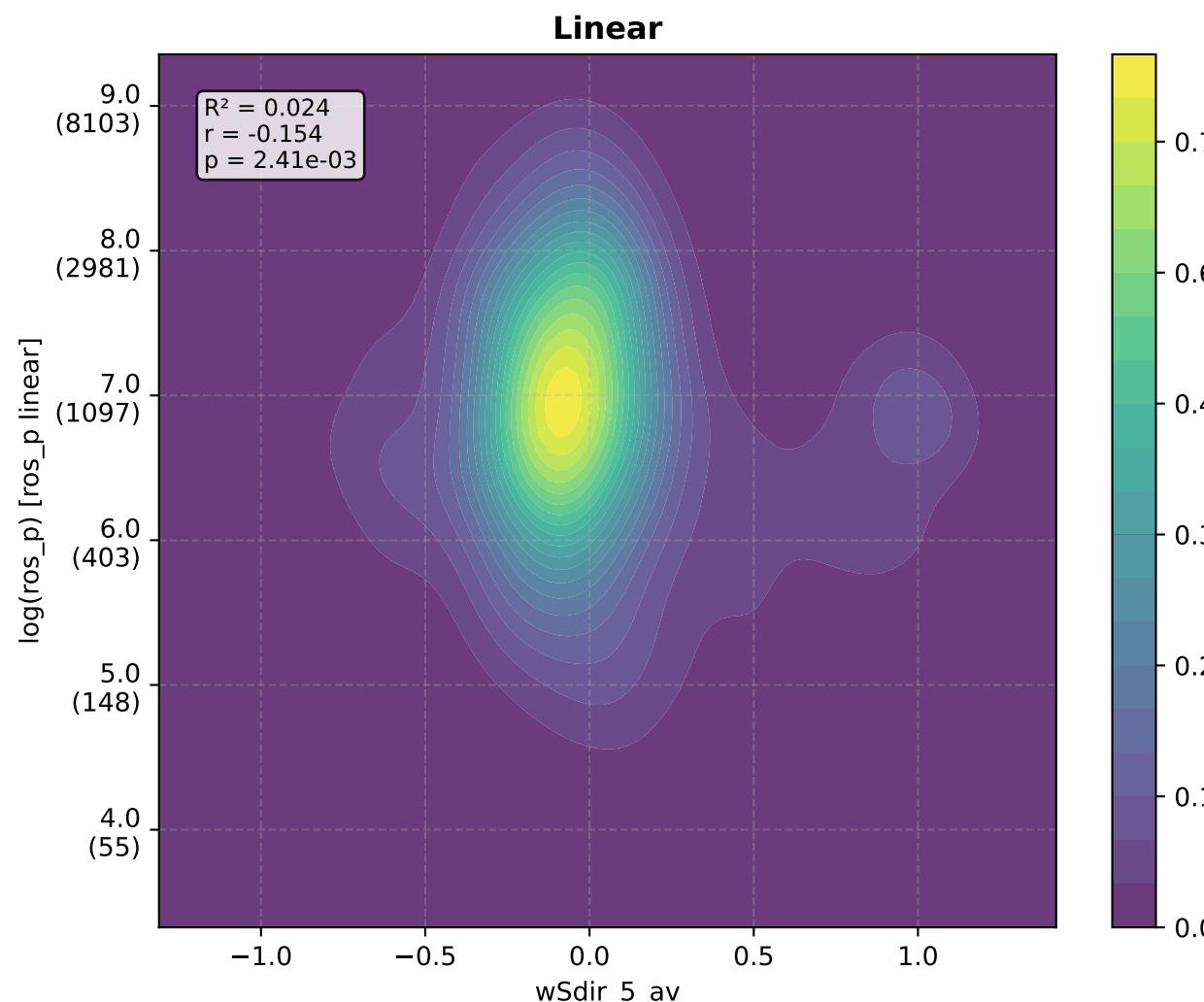
wSdir_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



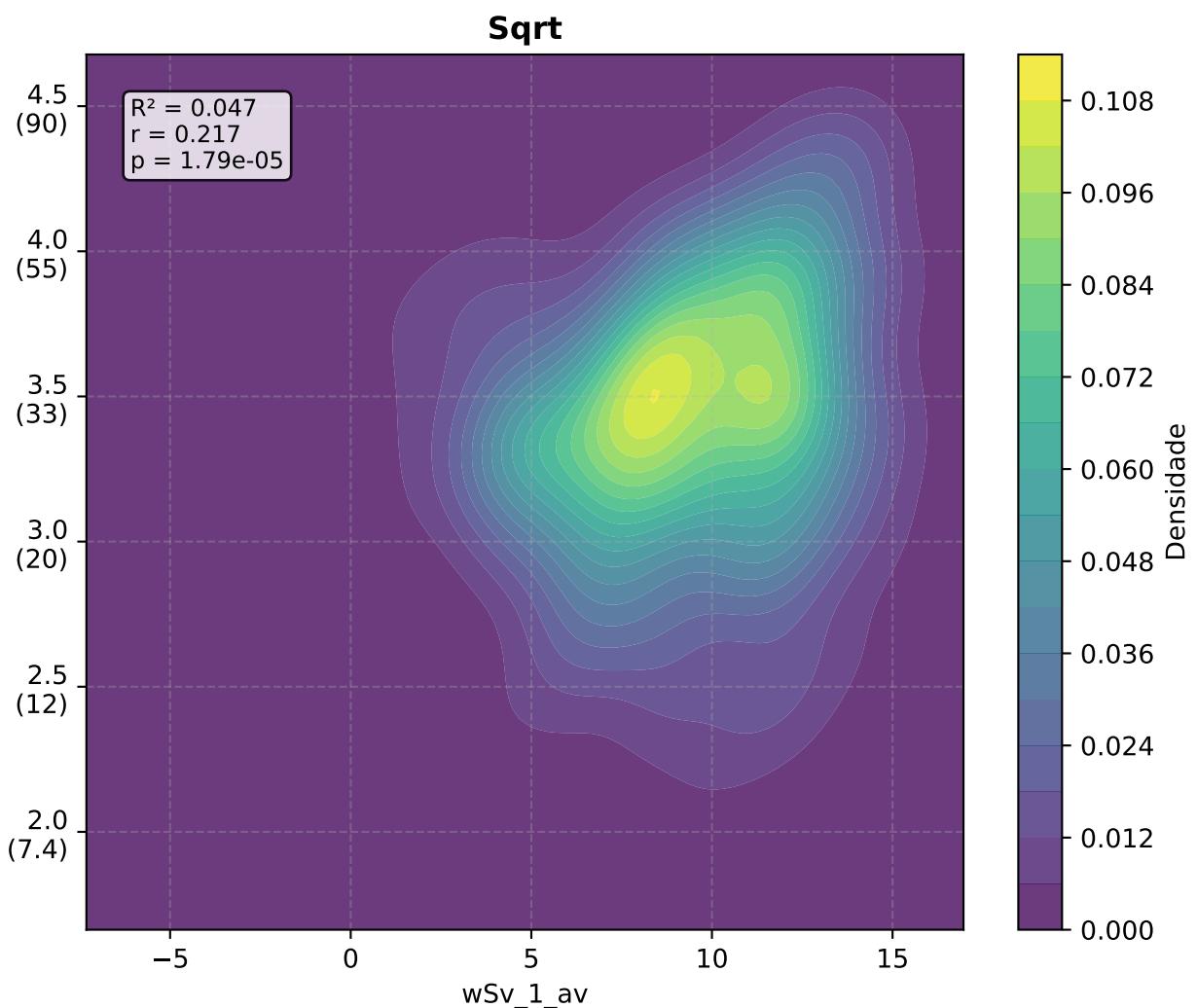
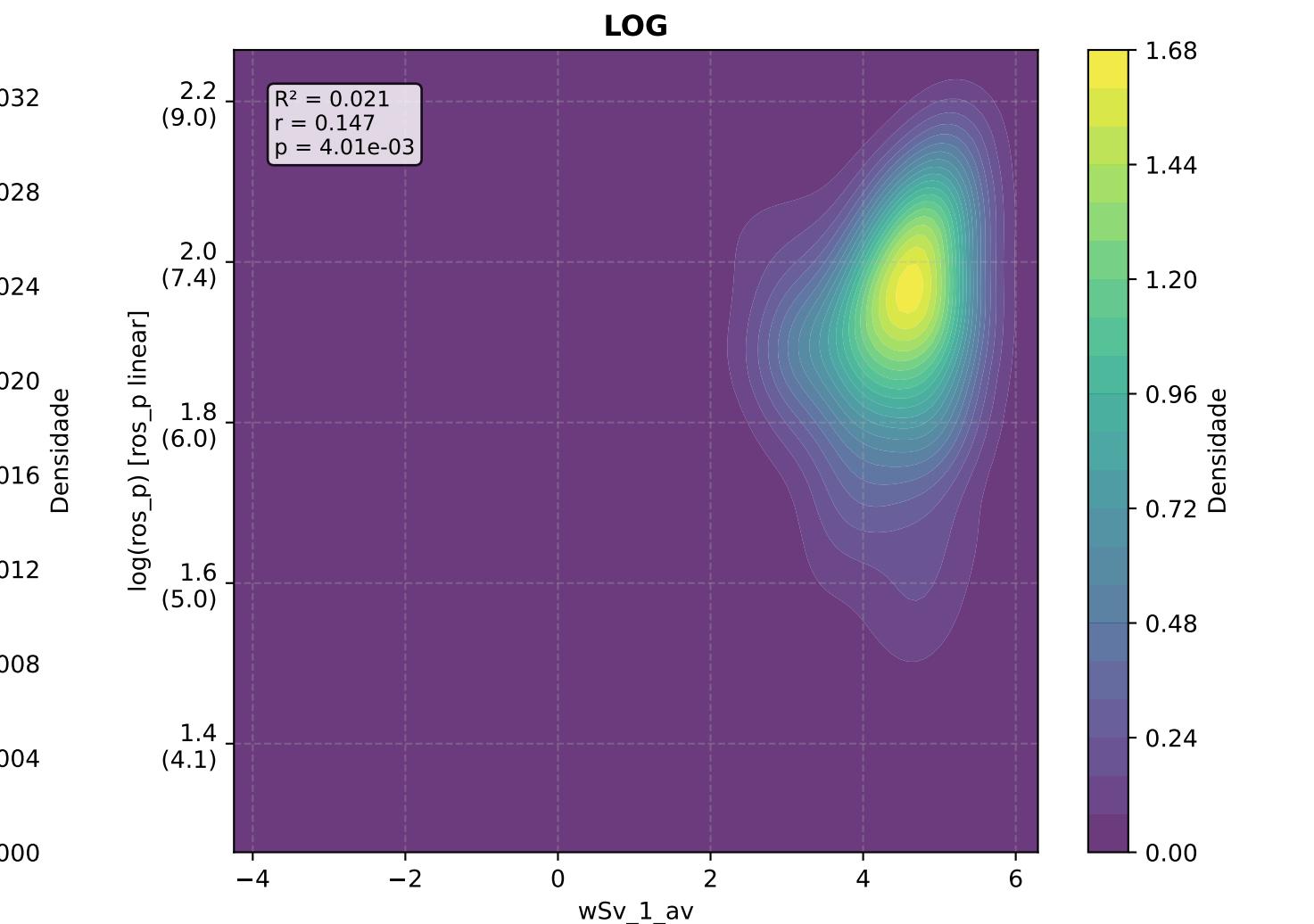
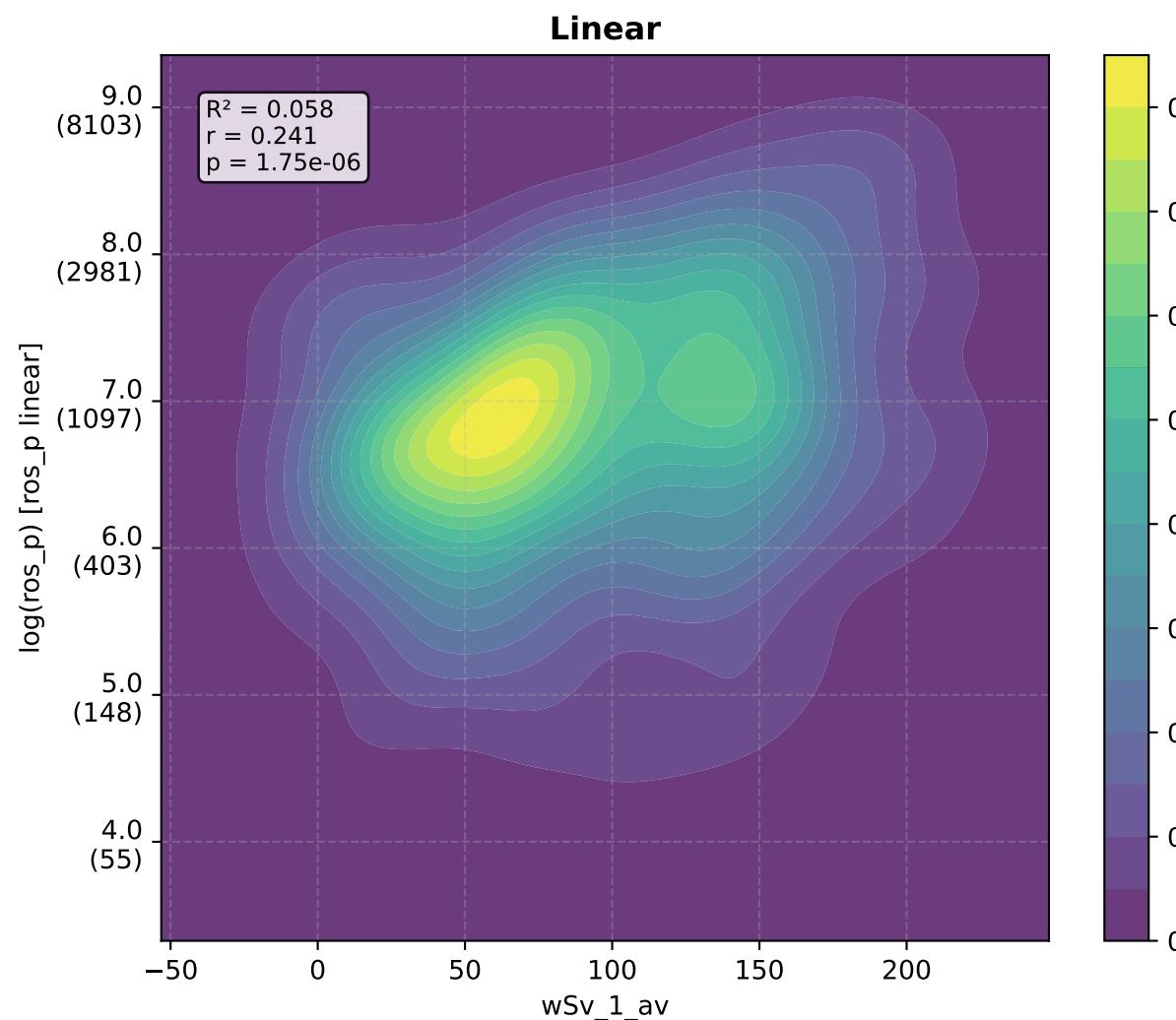
wSv_5_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



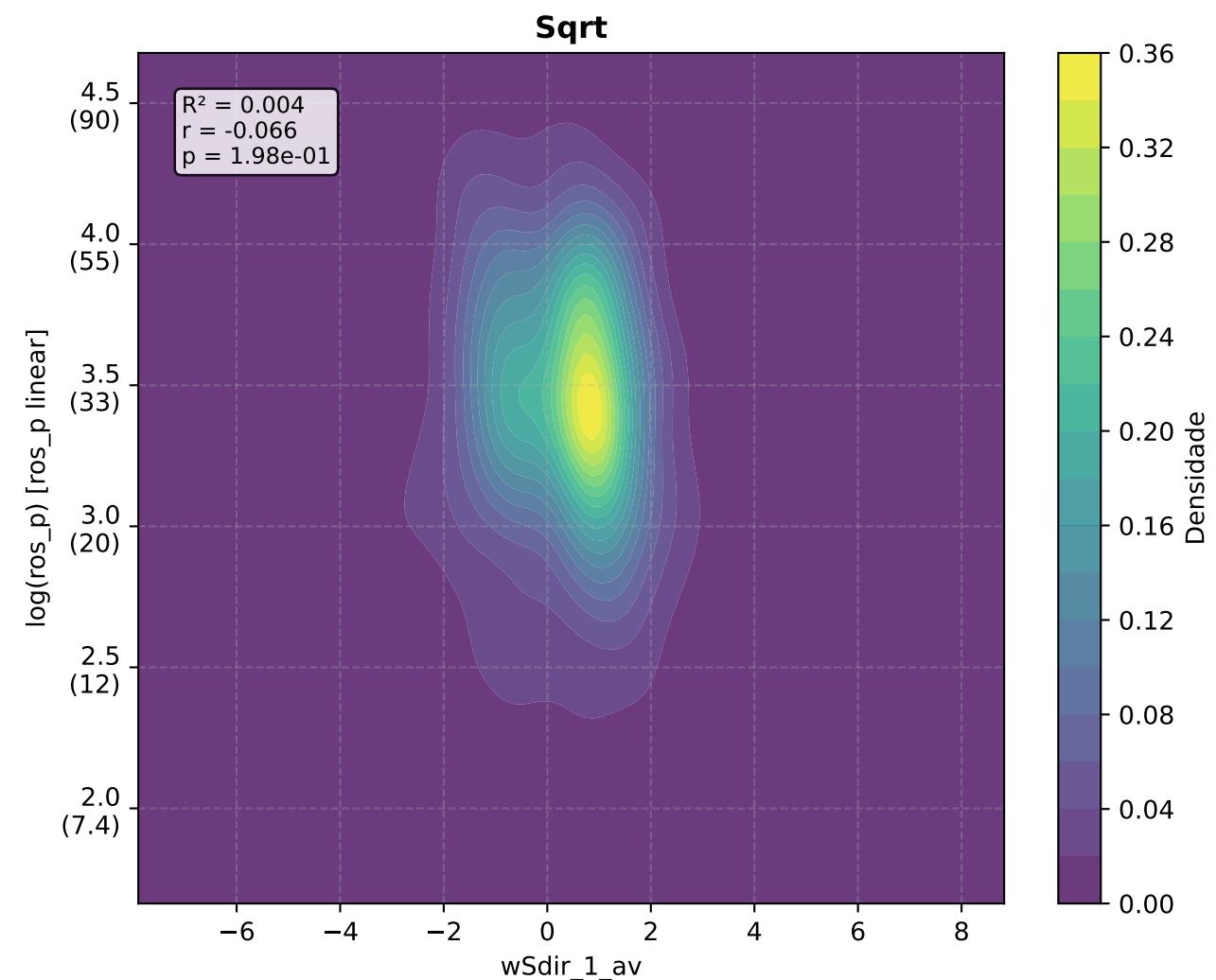
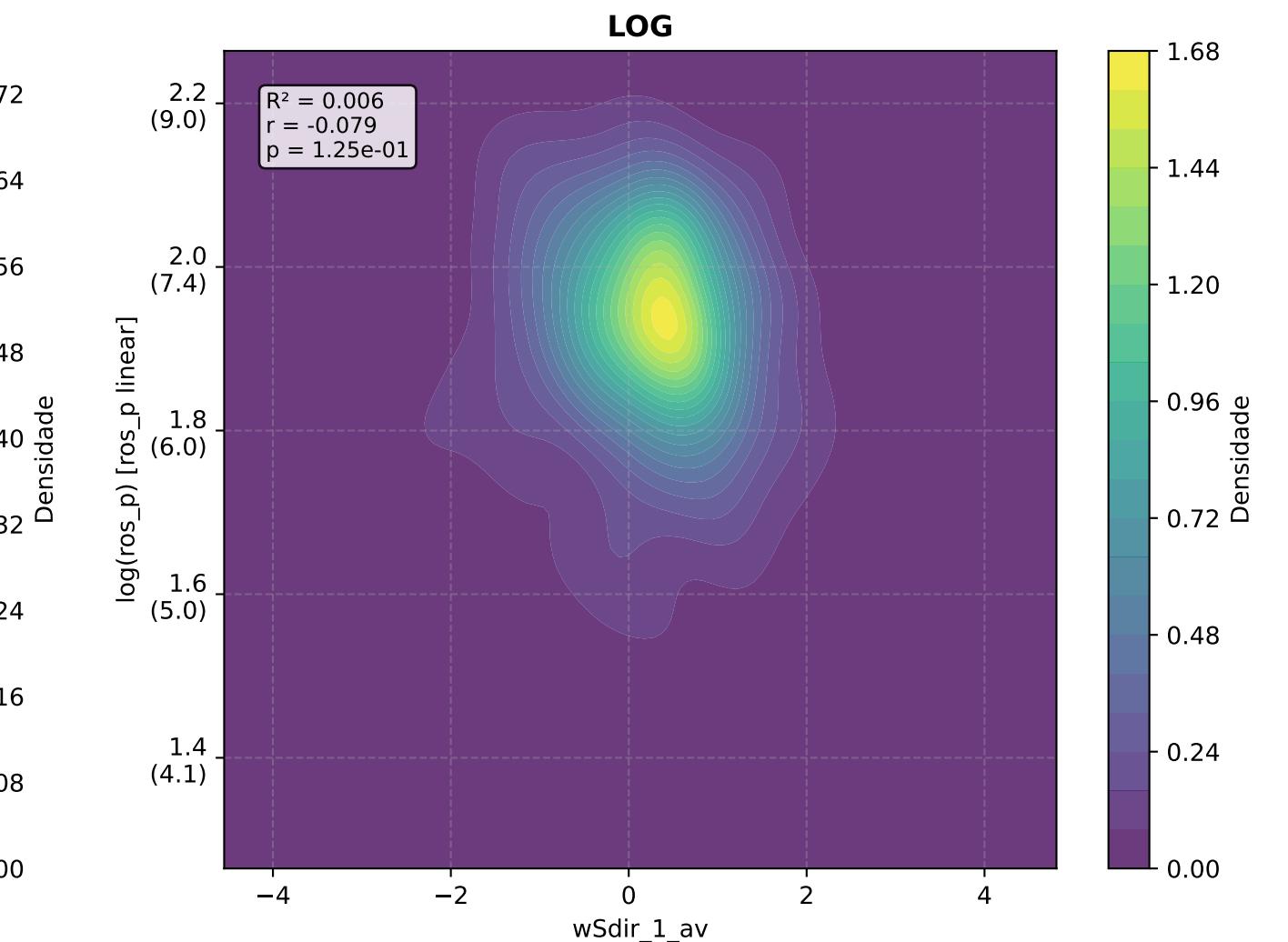
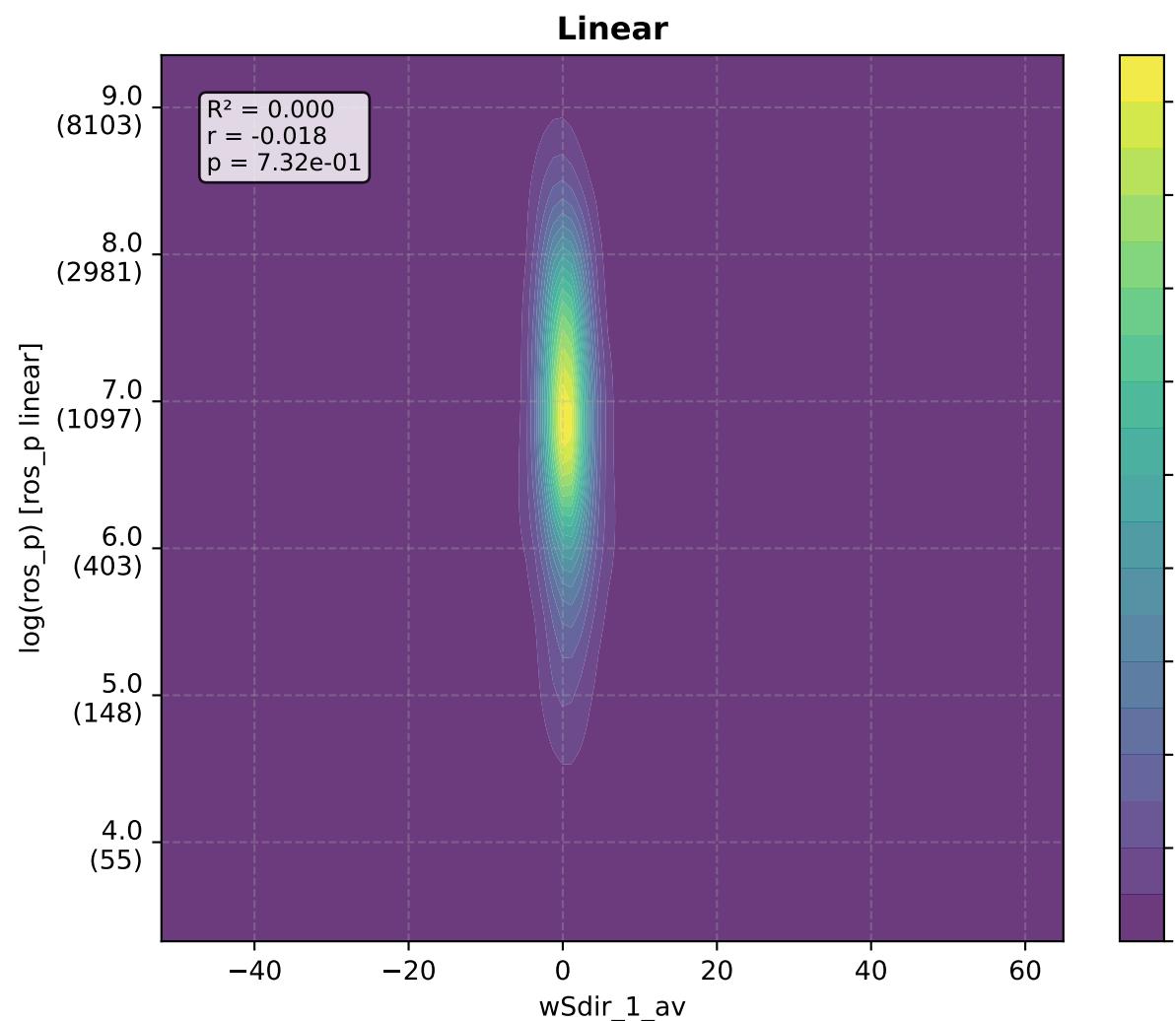
wSdir_5_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



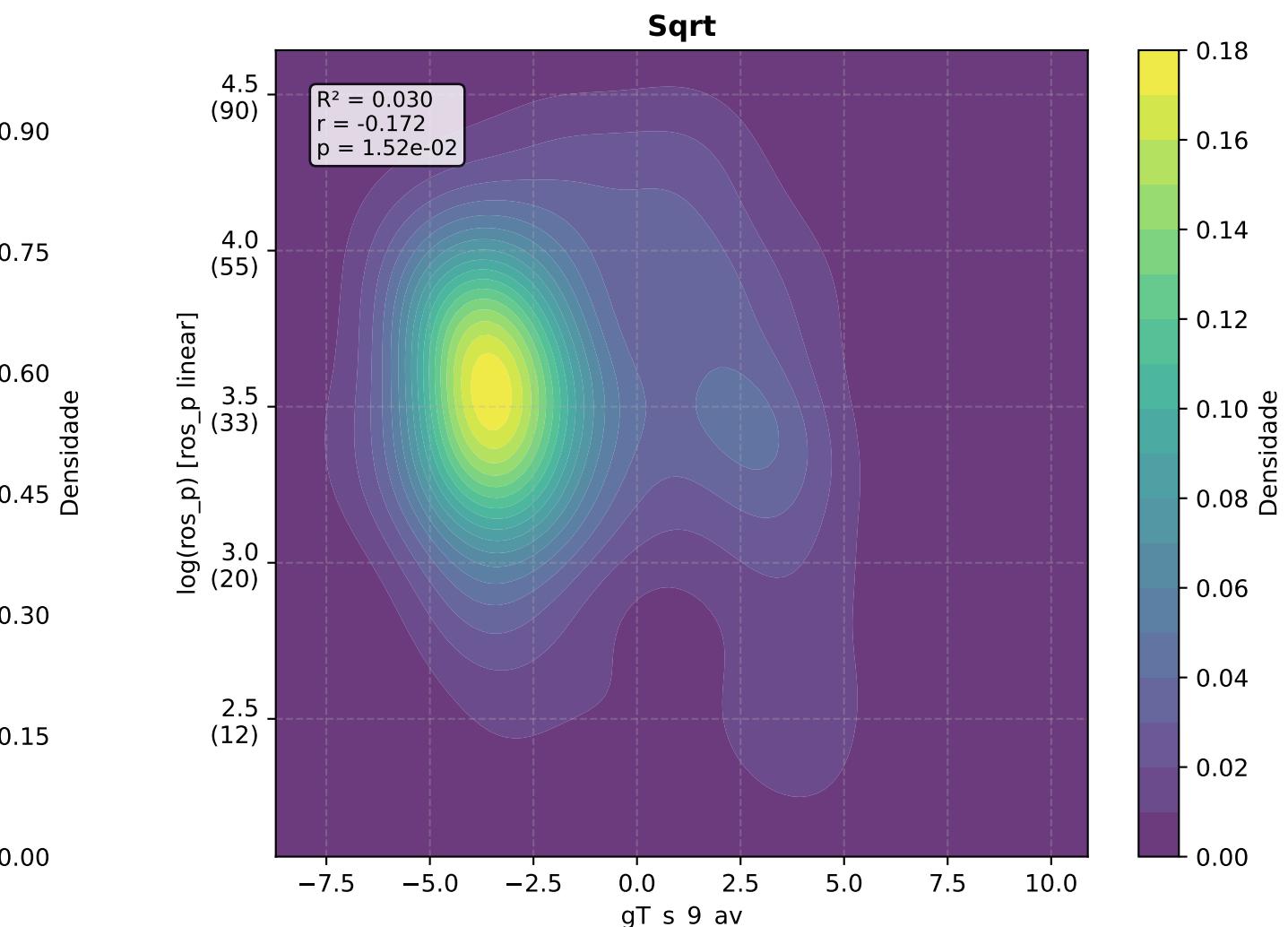
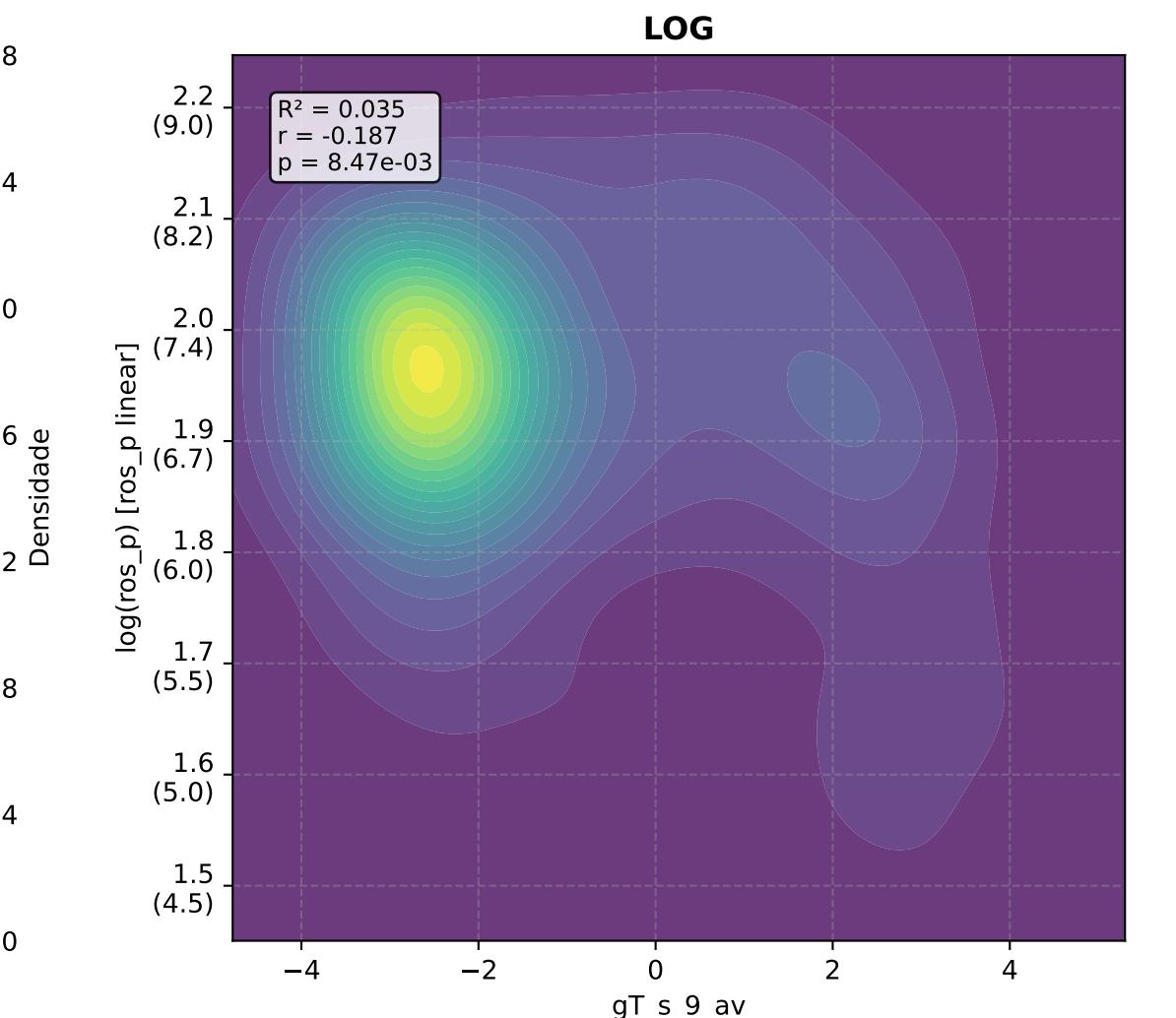
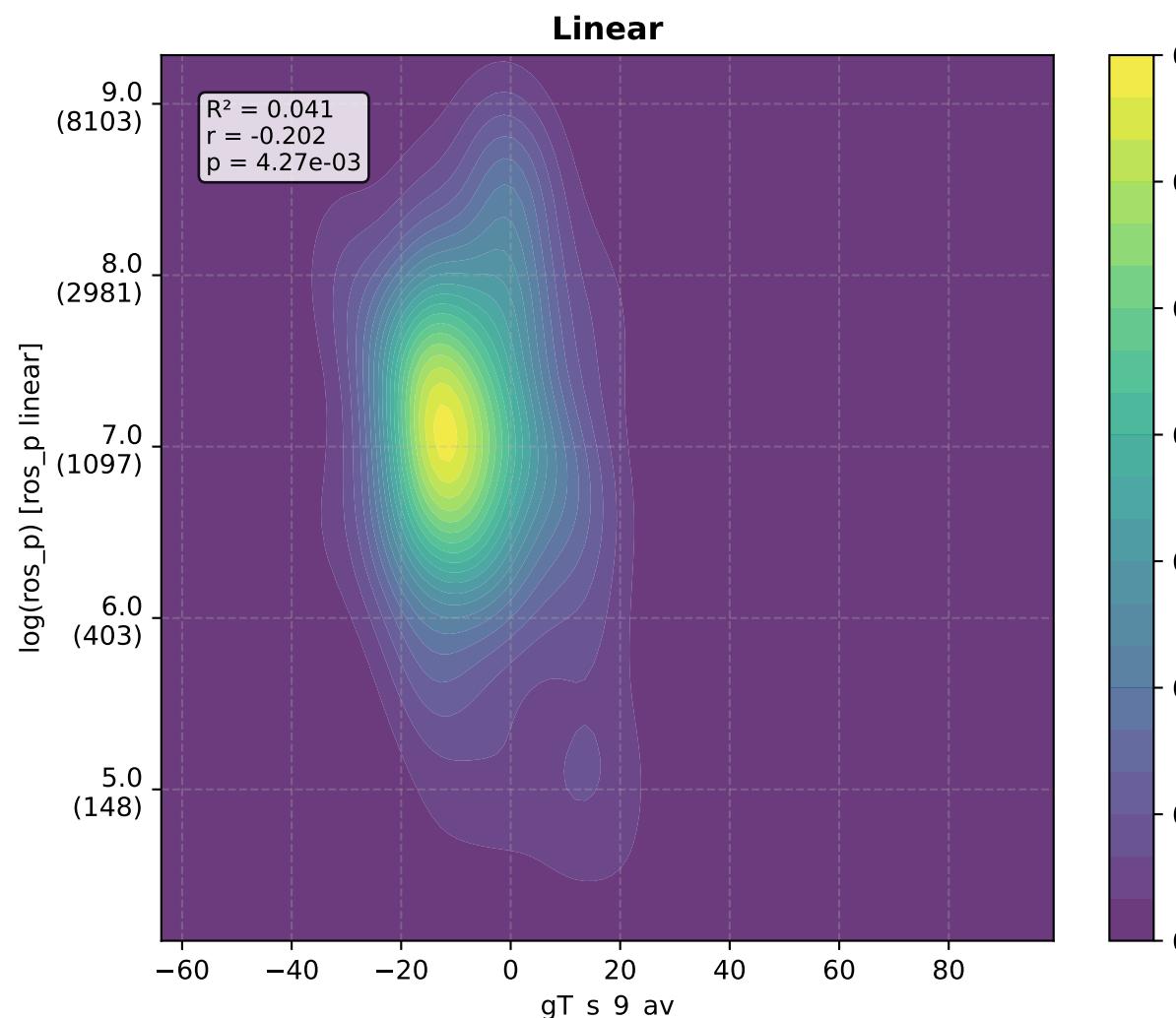
wSv_1_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



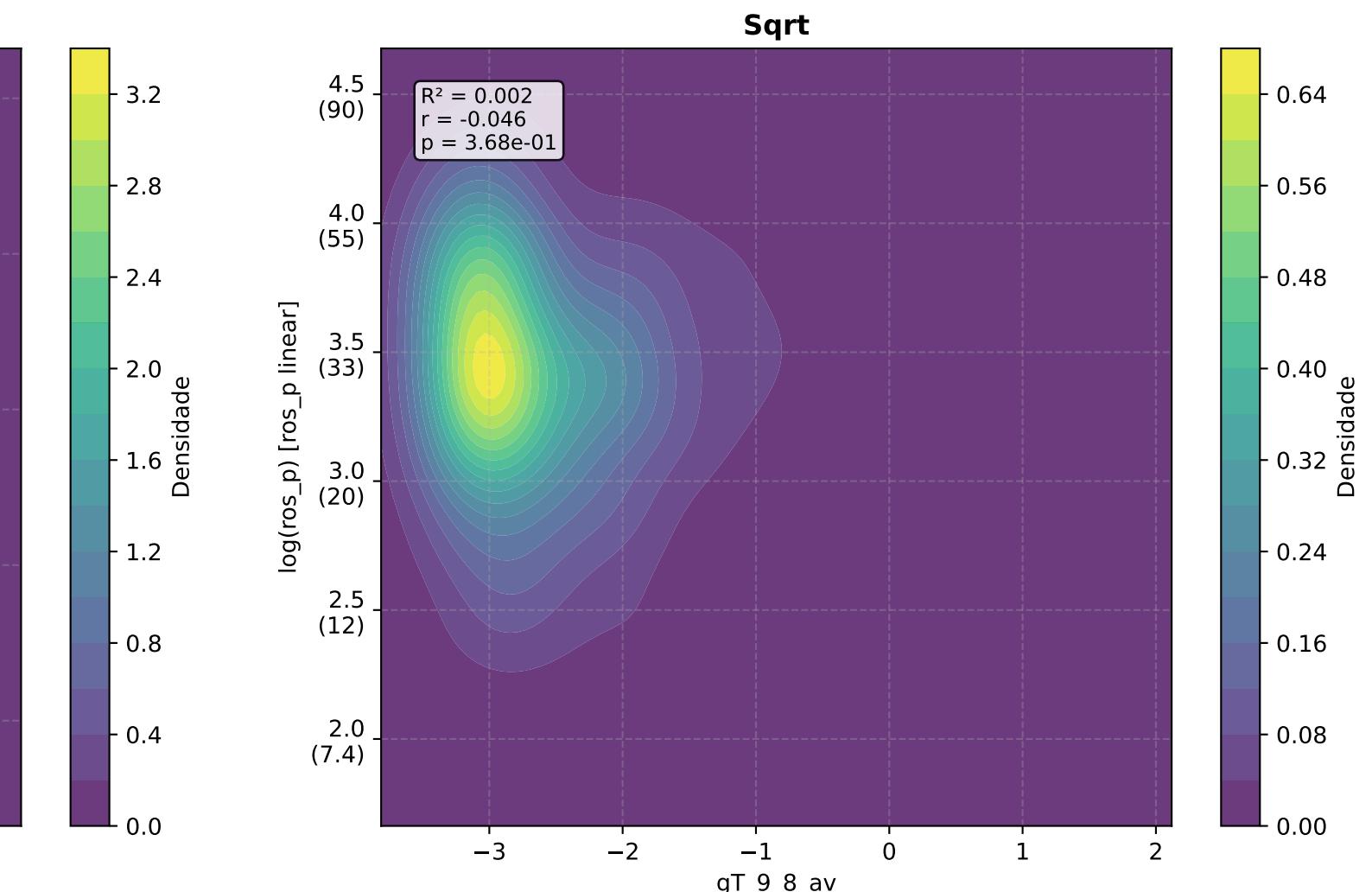
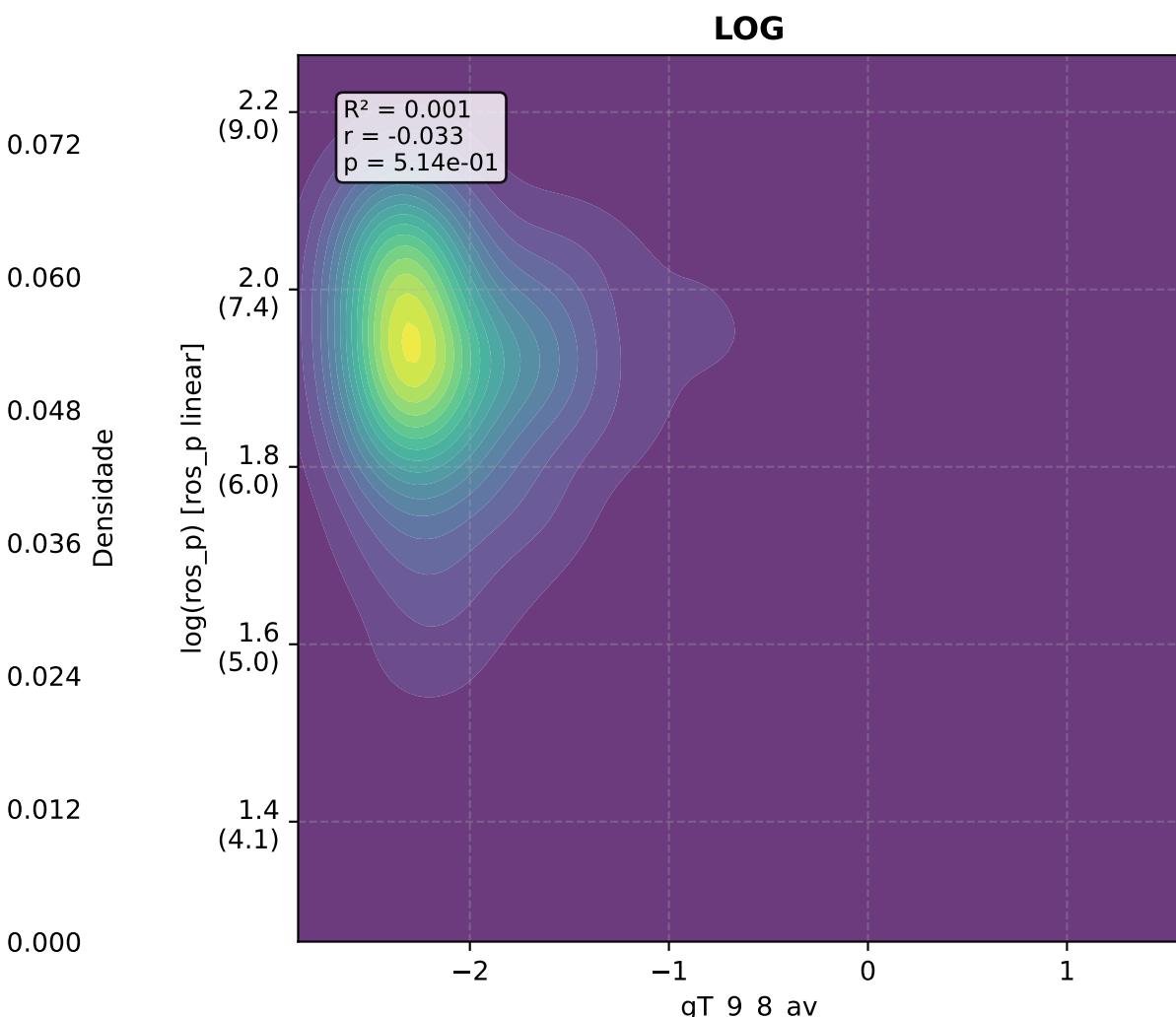
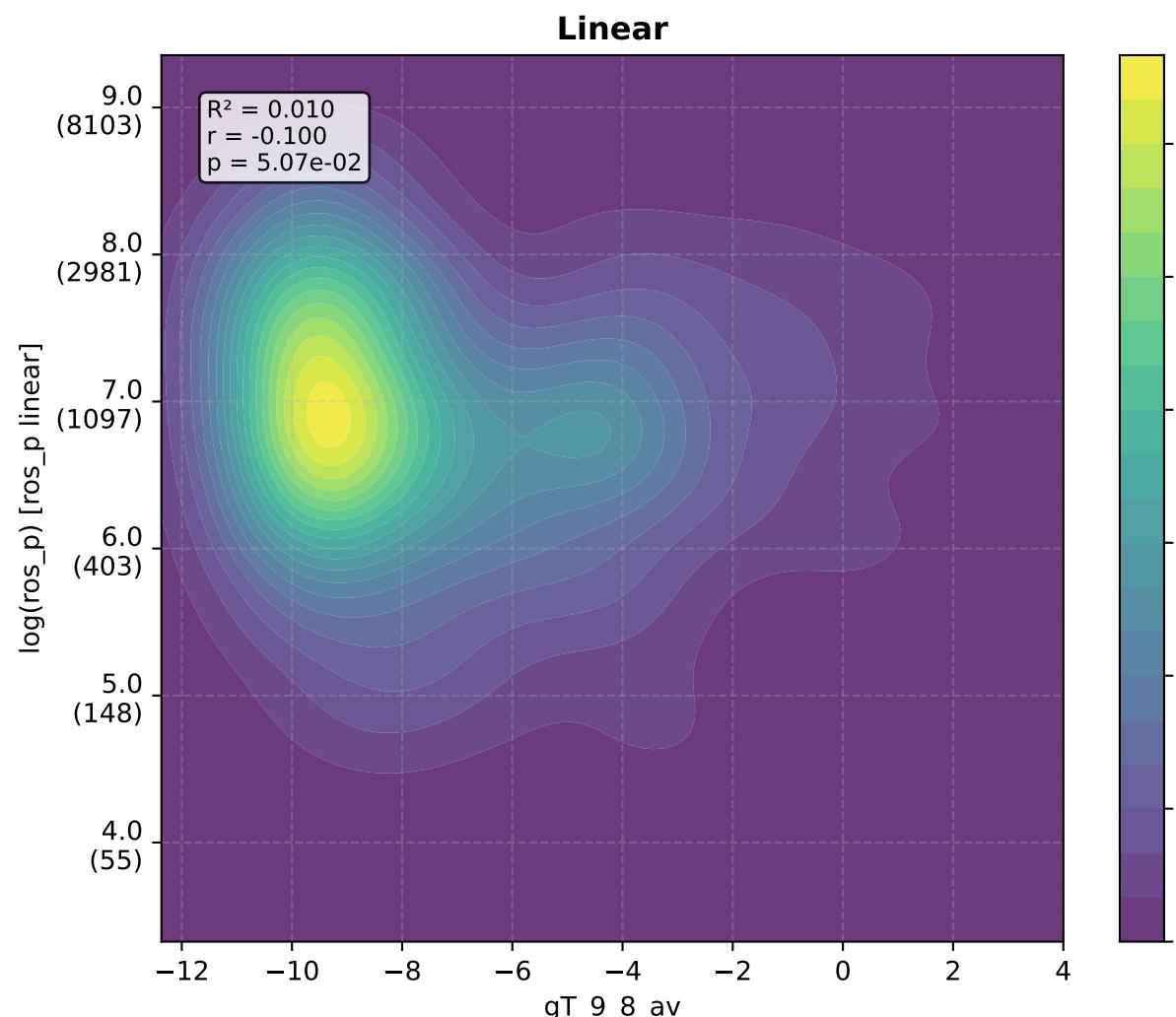
wSdir_1_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



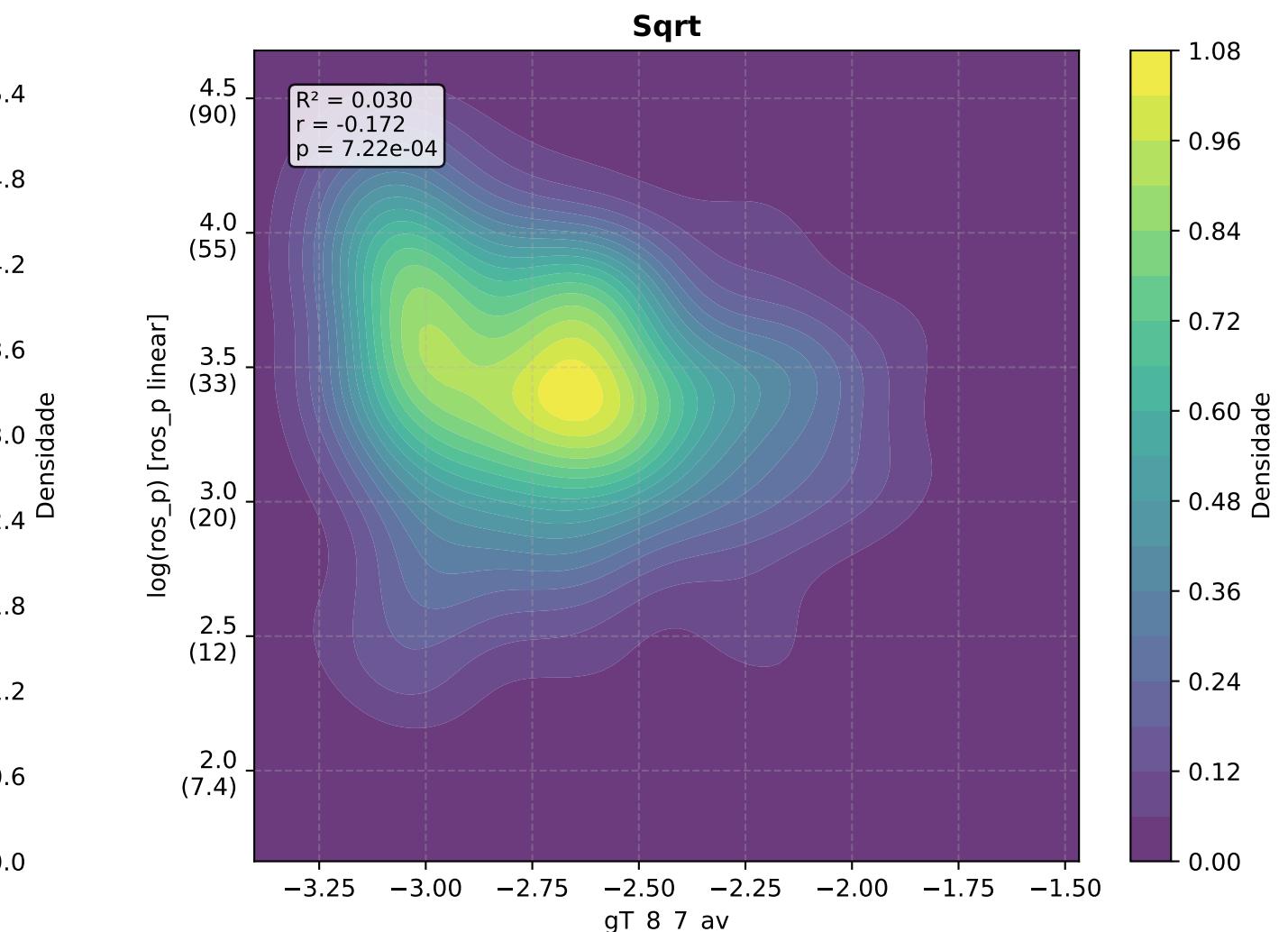
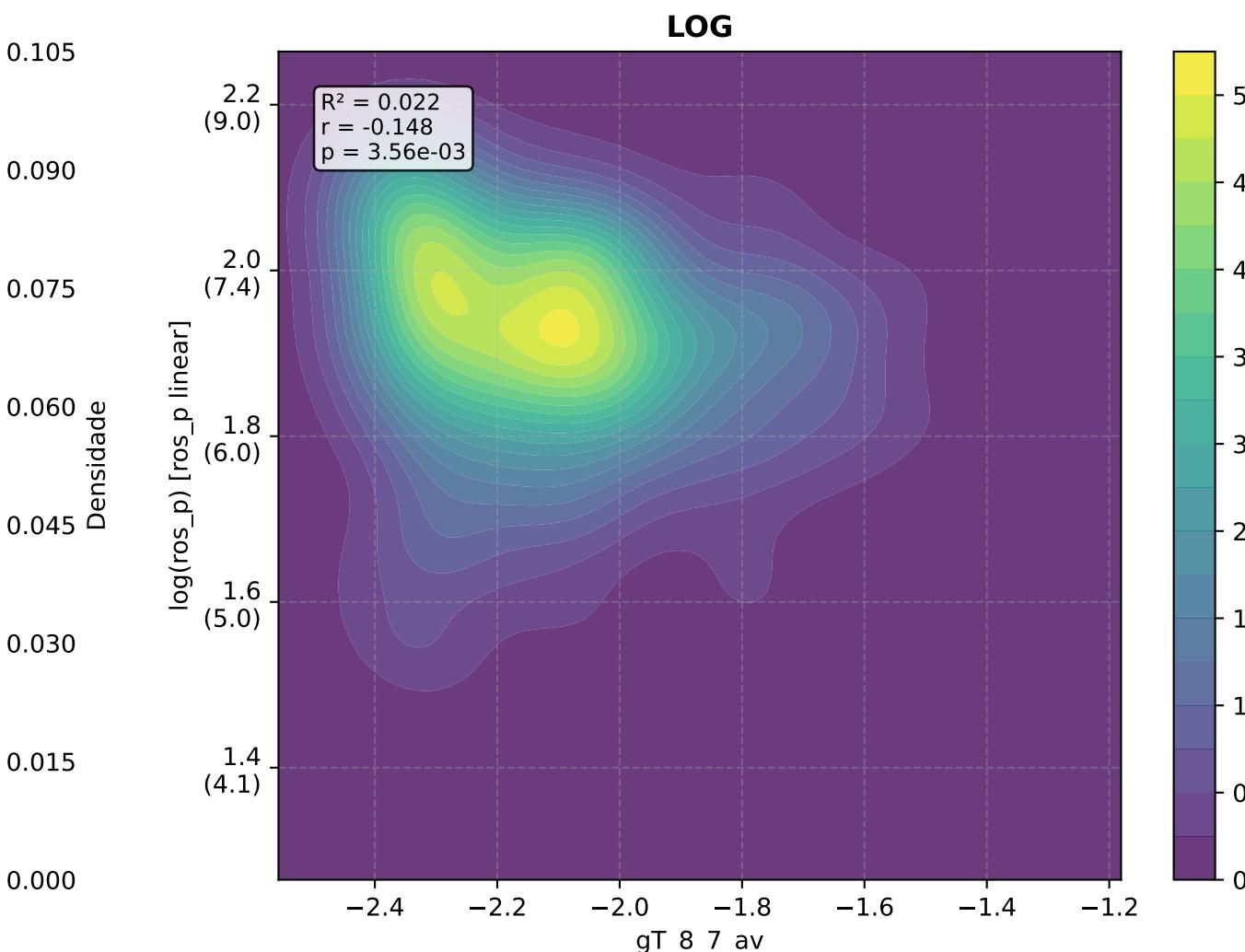
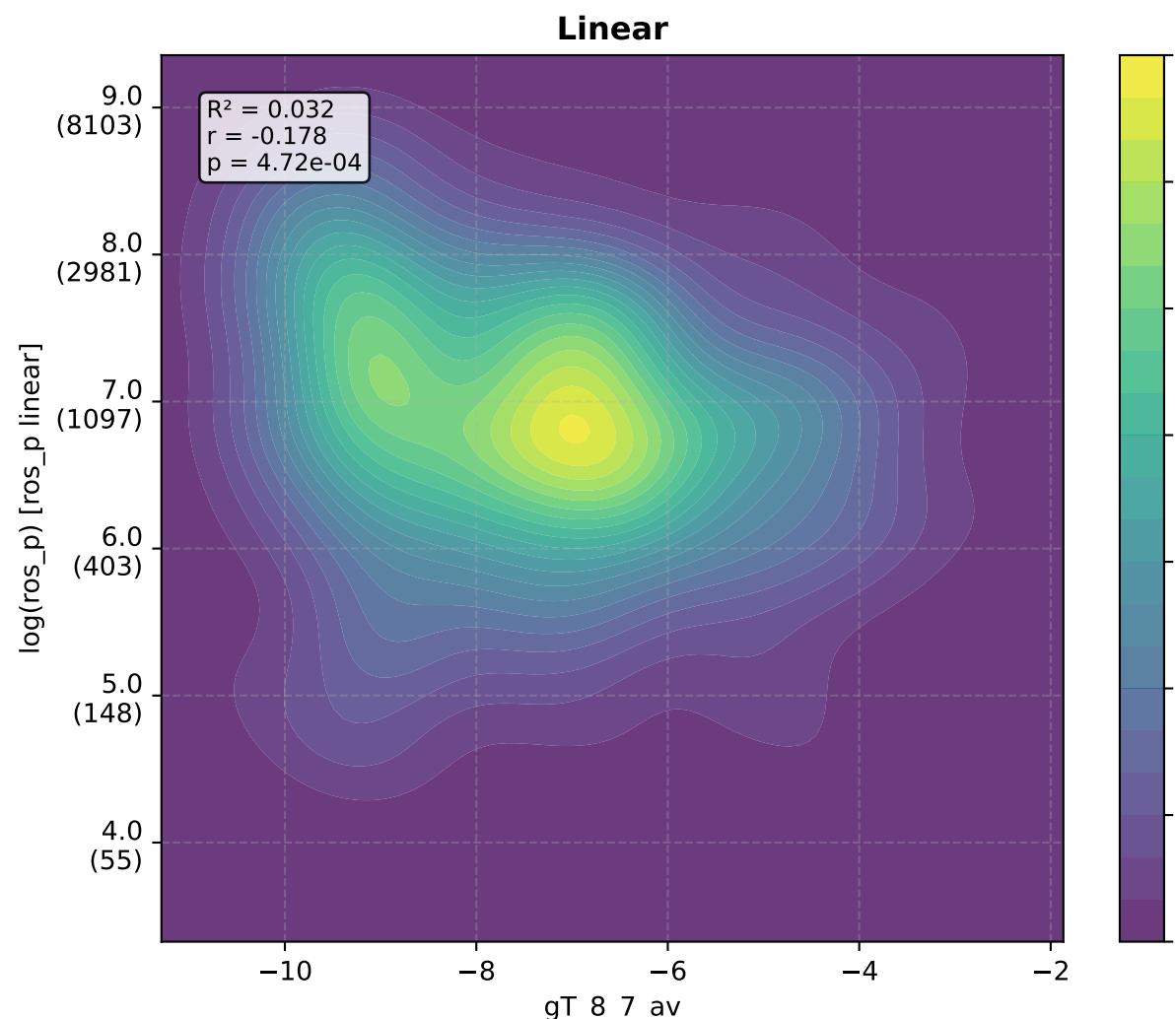
gT_s_9_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



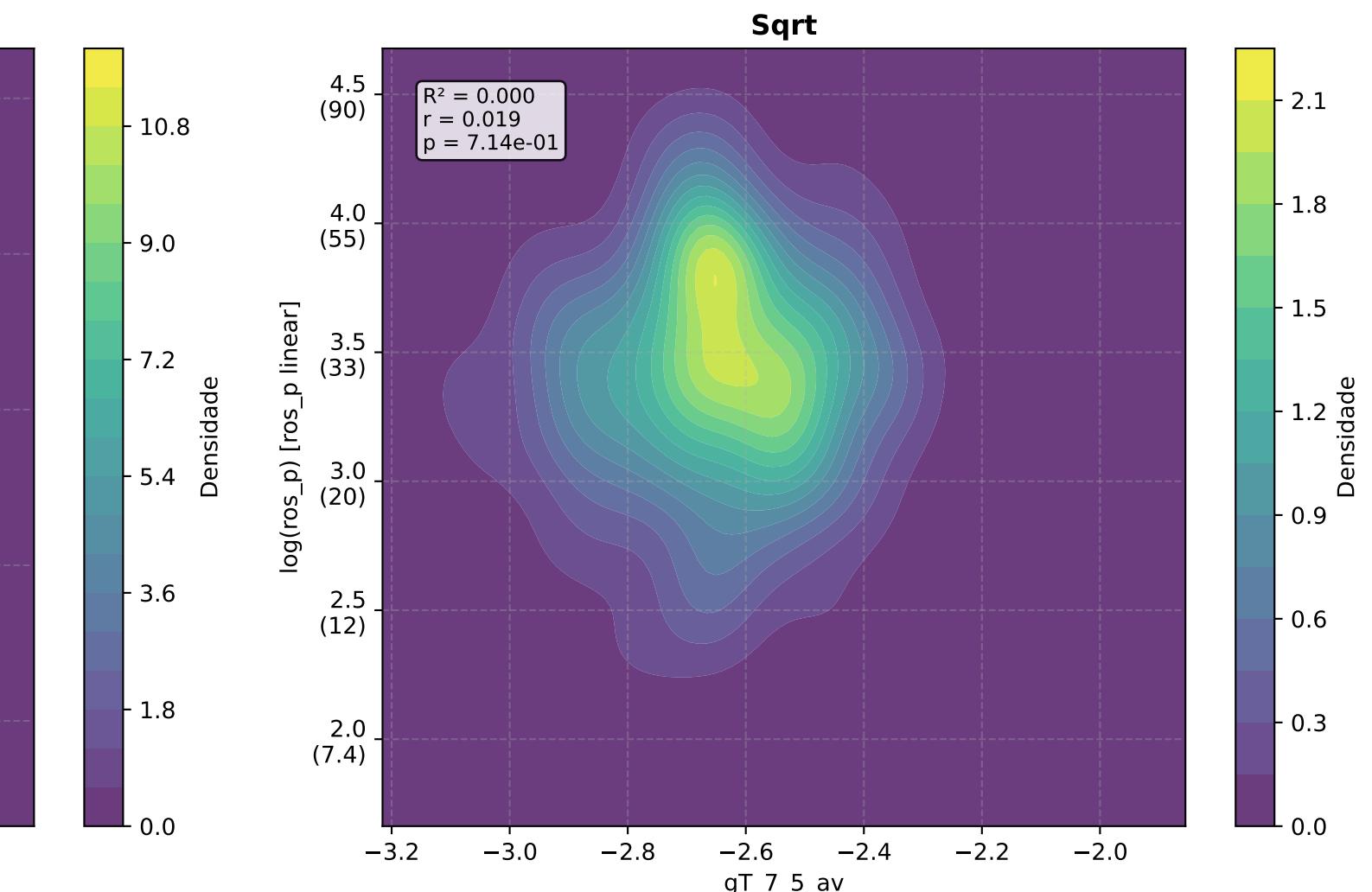
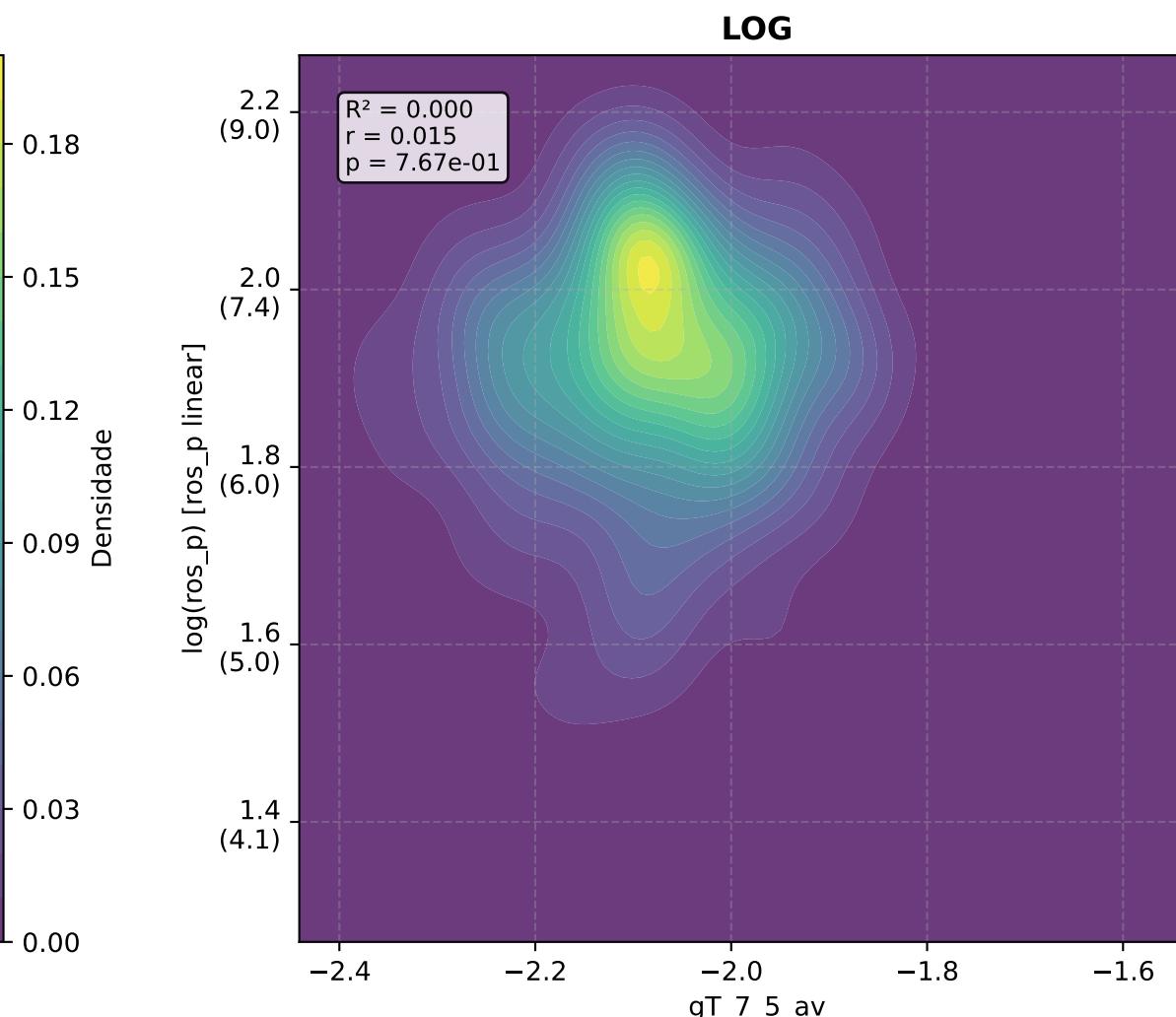
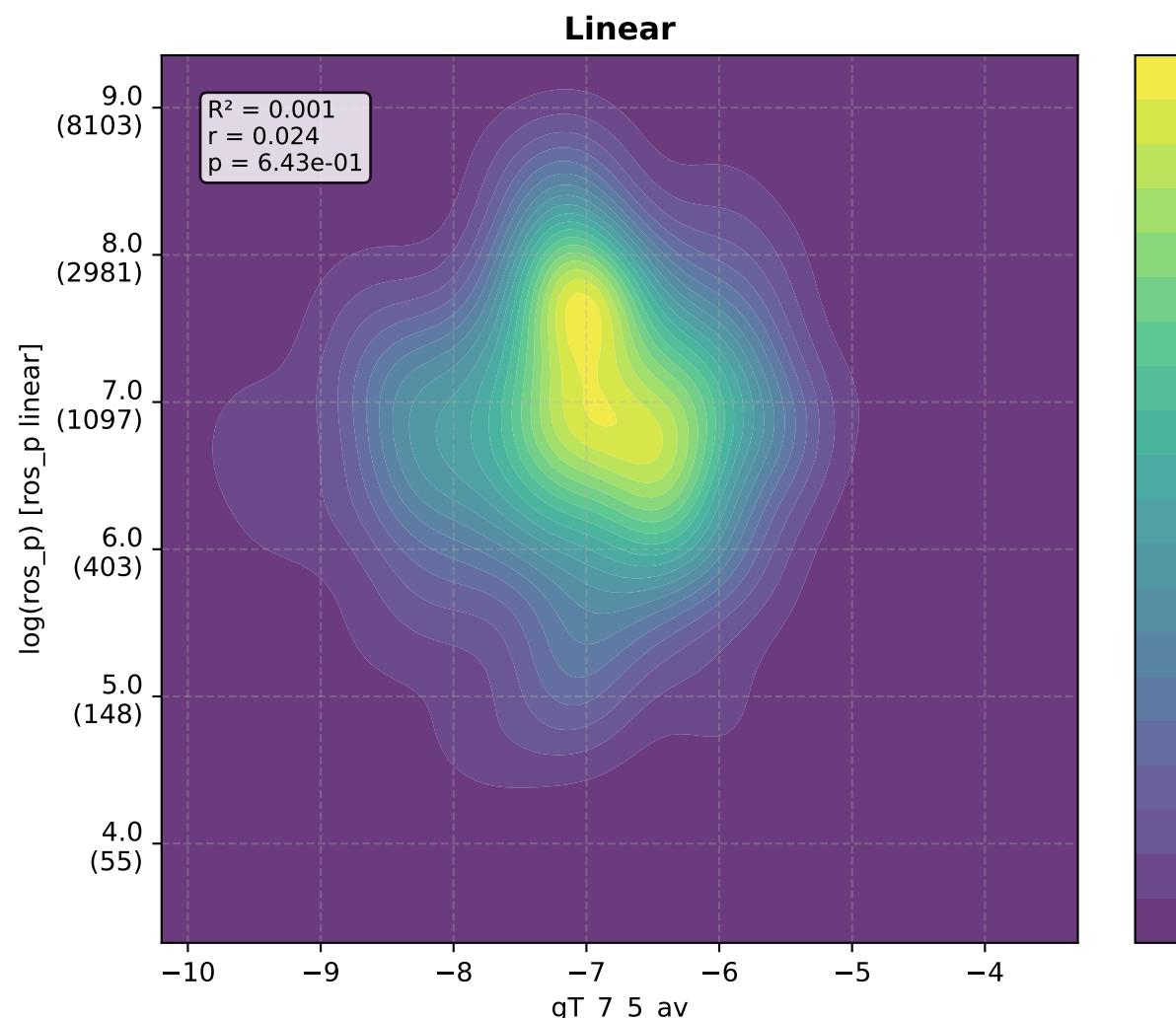
gT_9_8_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



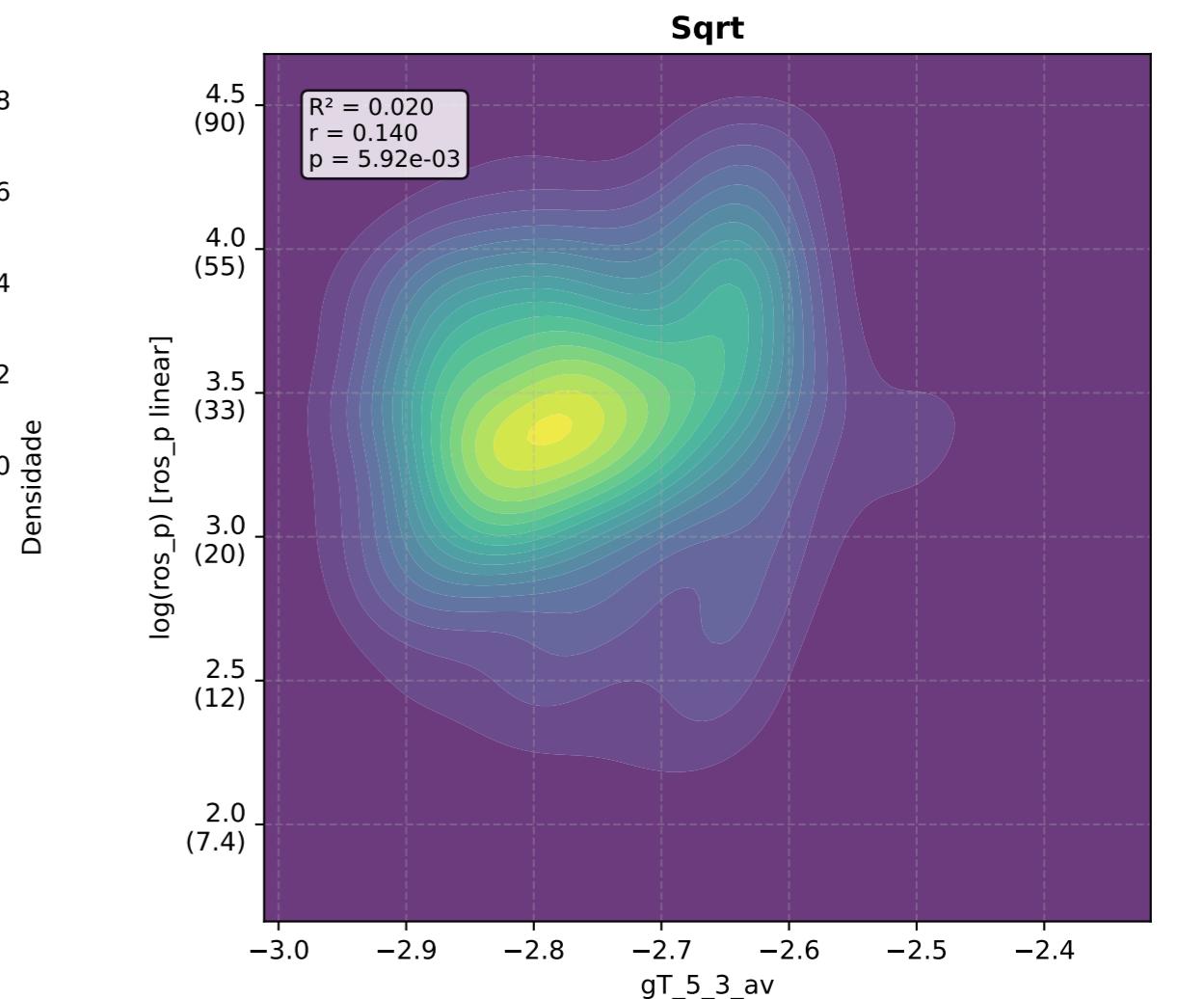
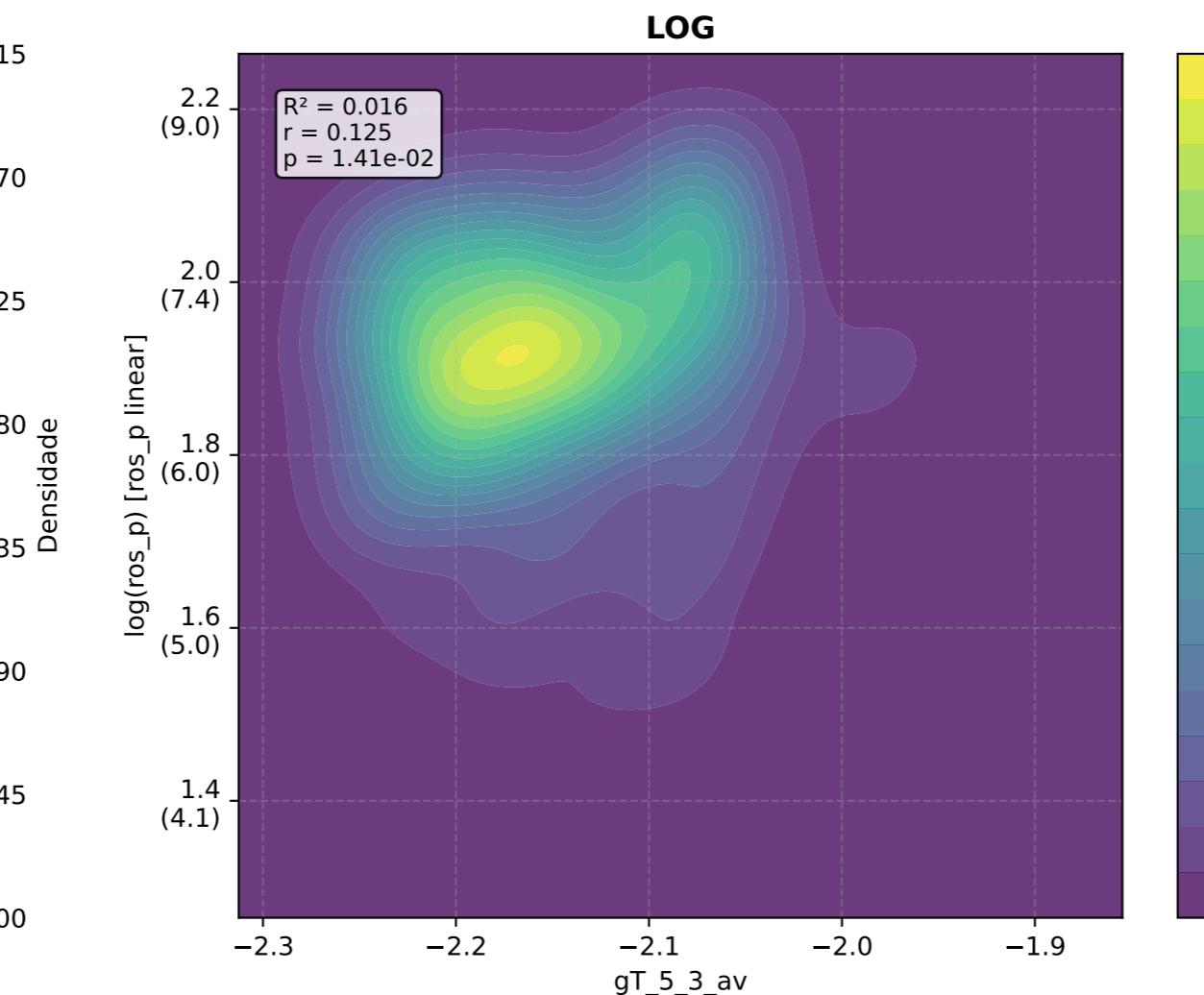
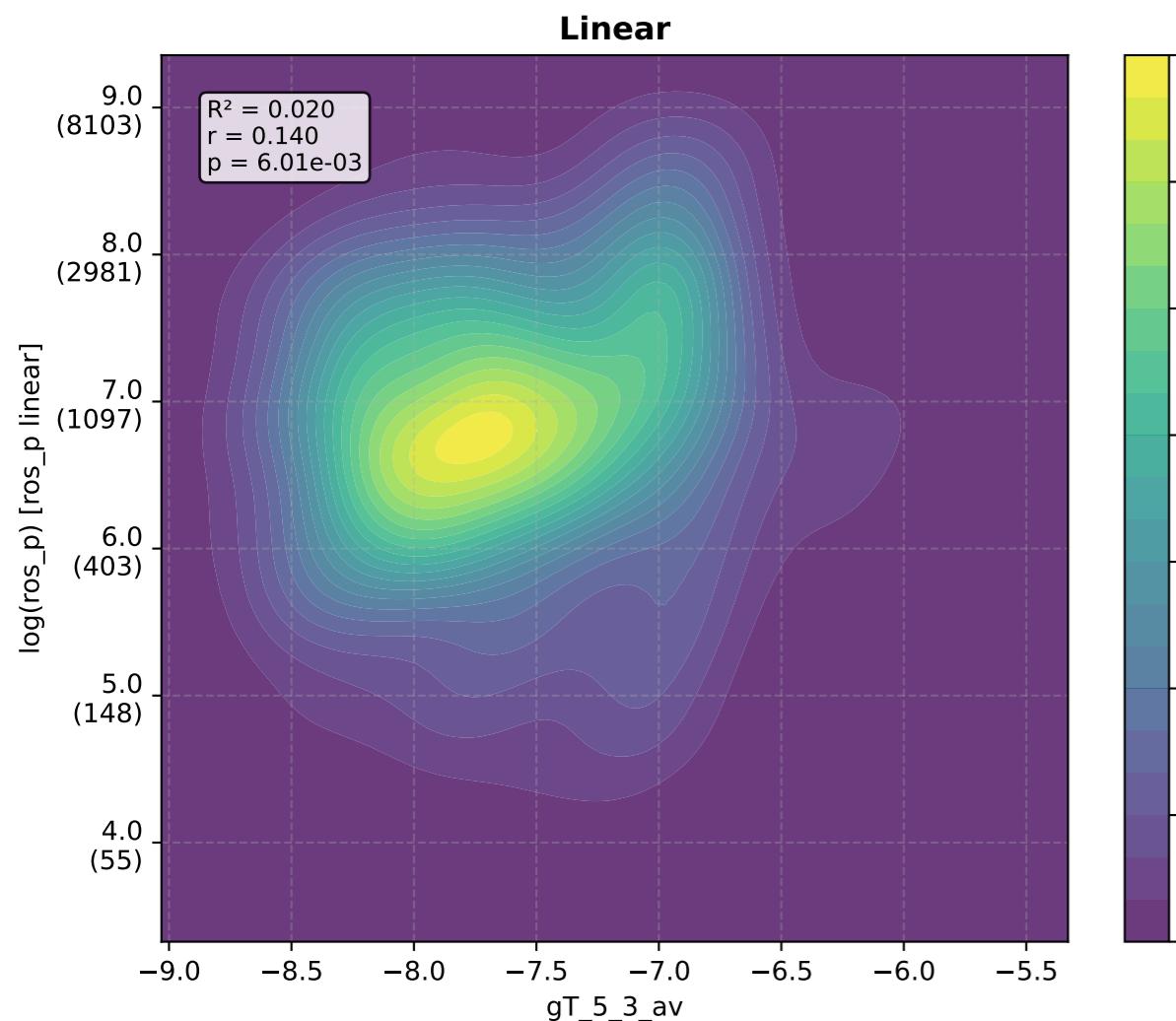
gT_8_7_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



gT_7_5_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



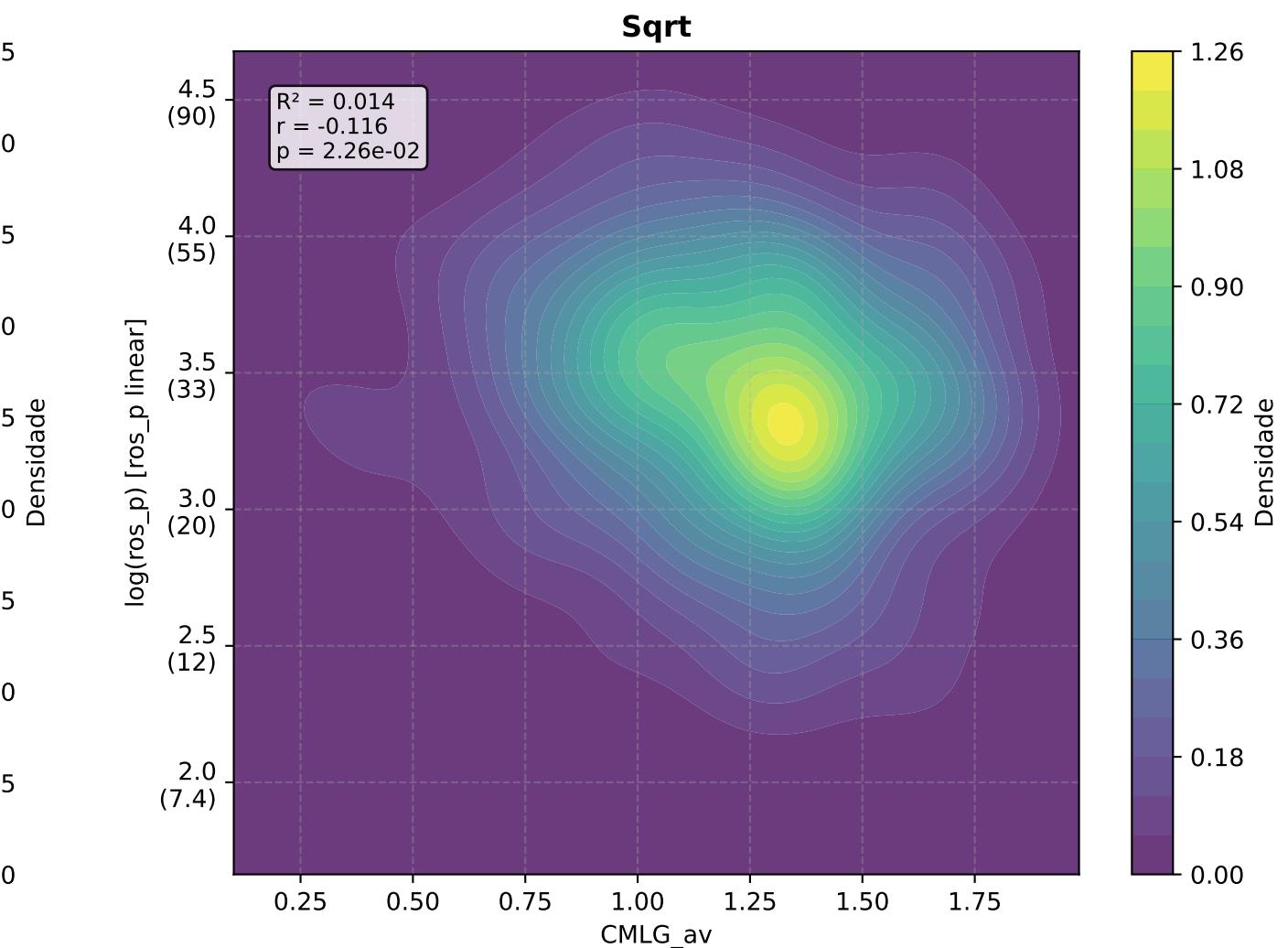
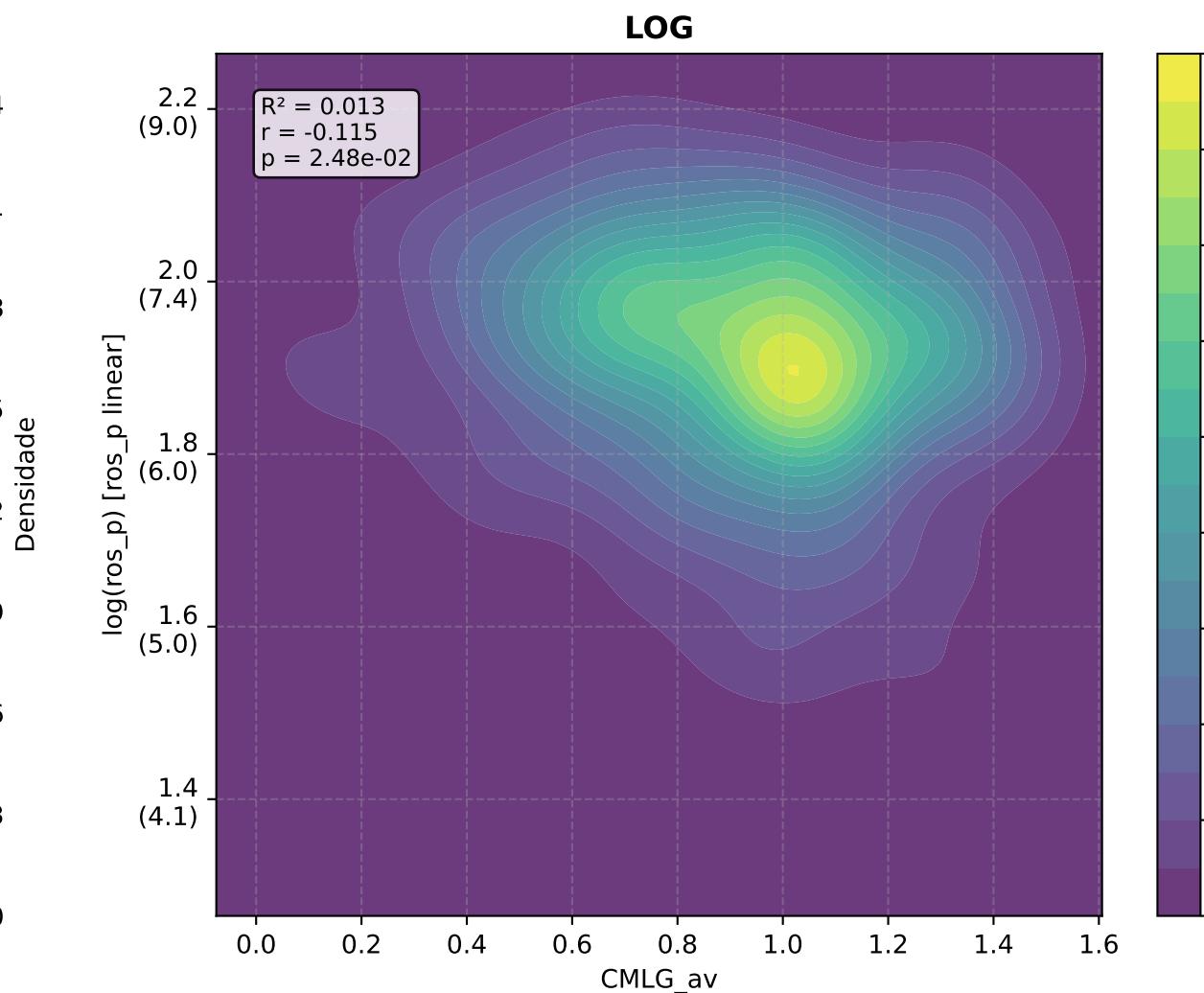
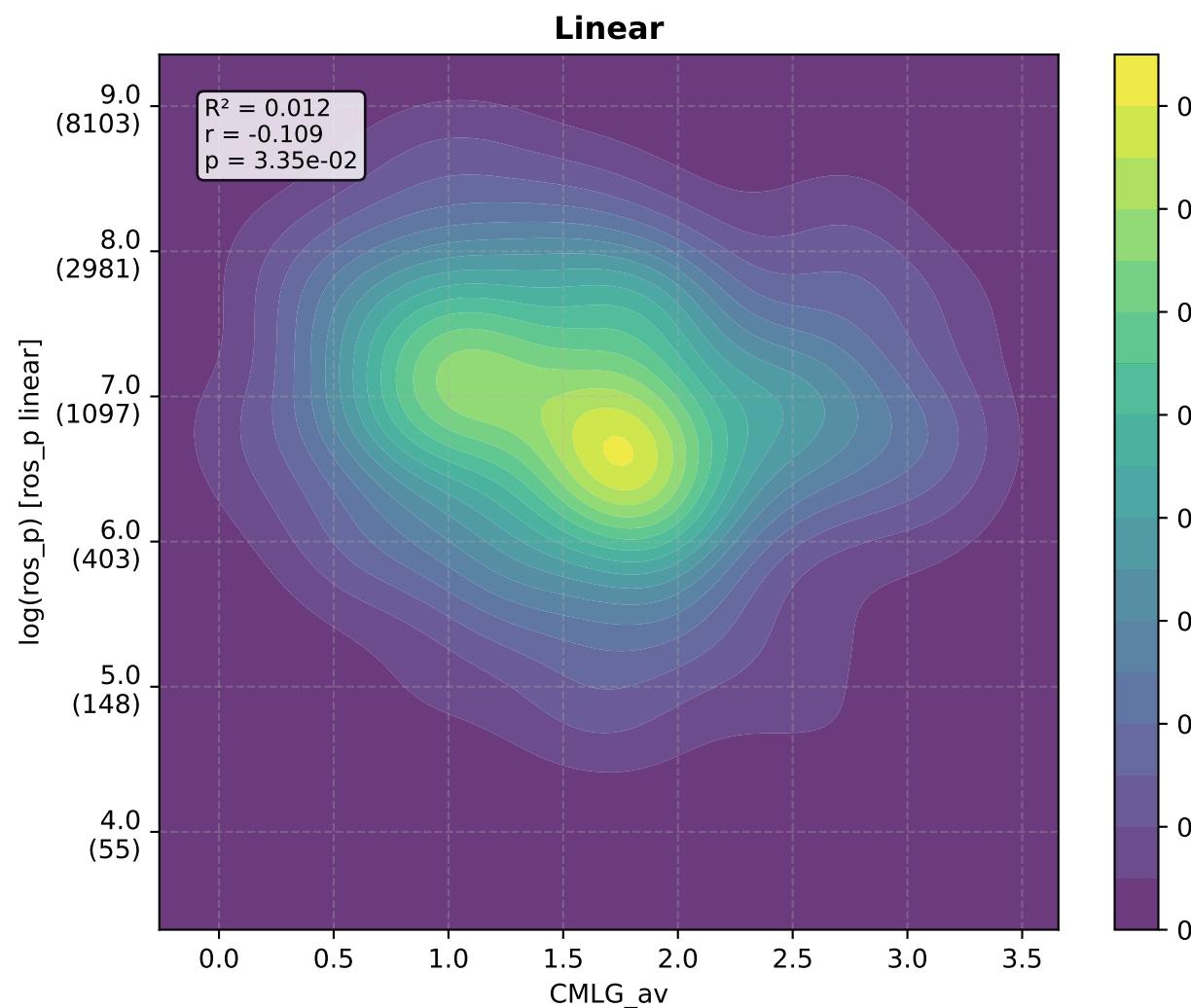
gT_5_3_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



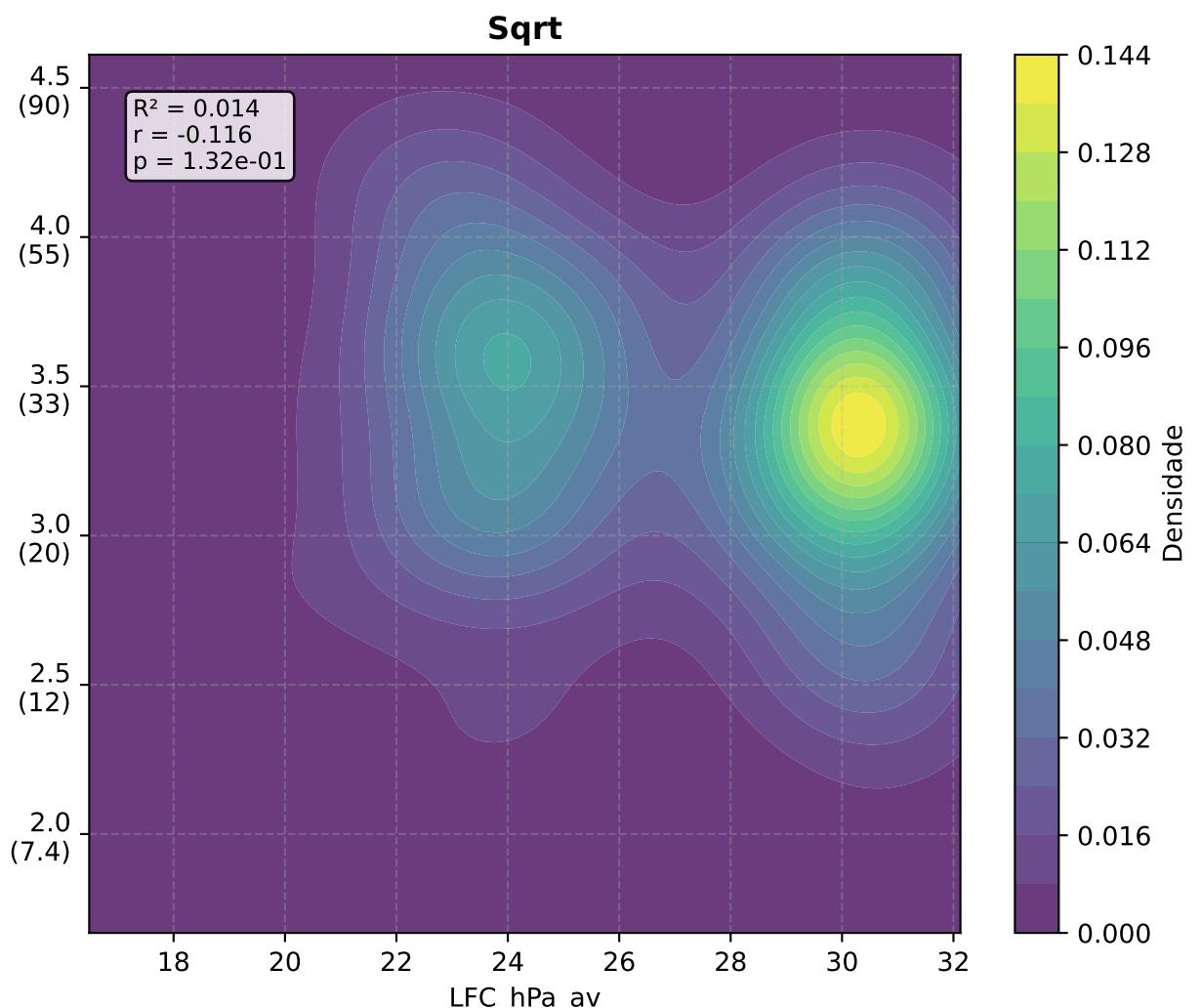
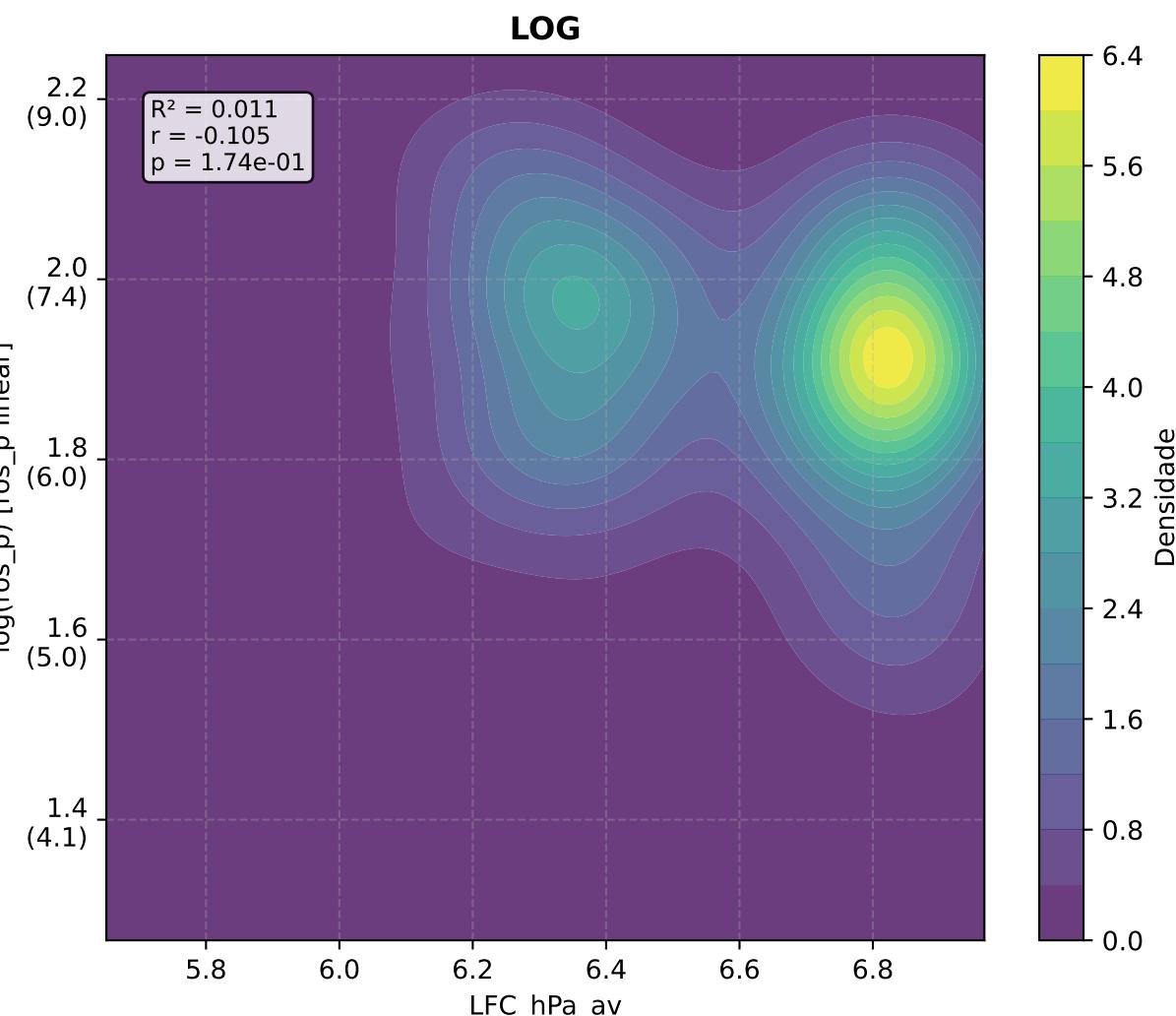
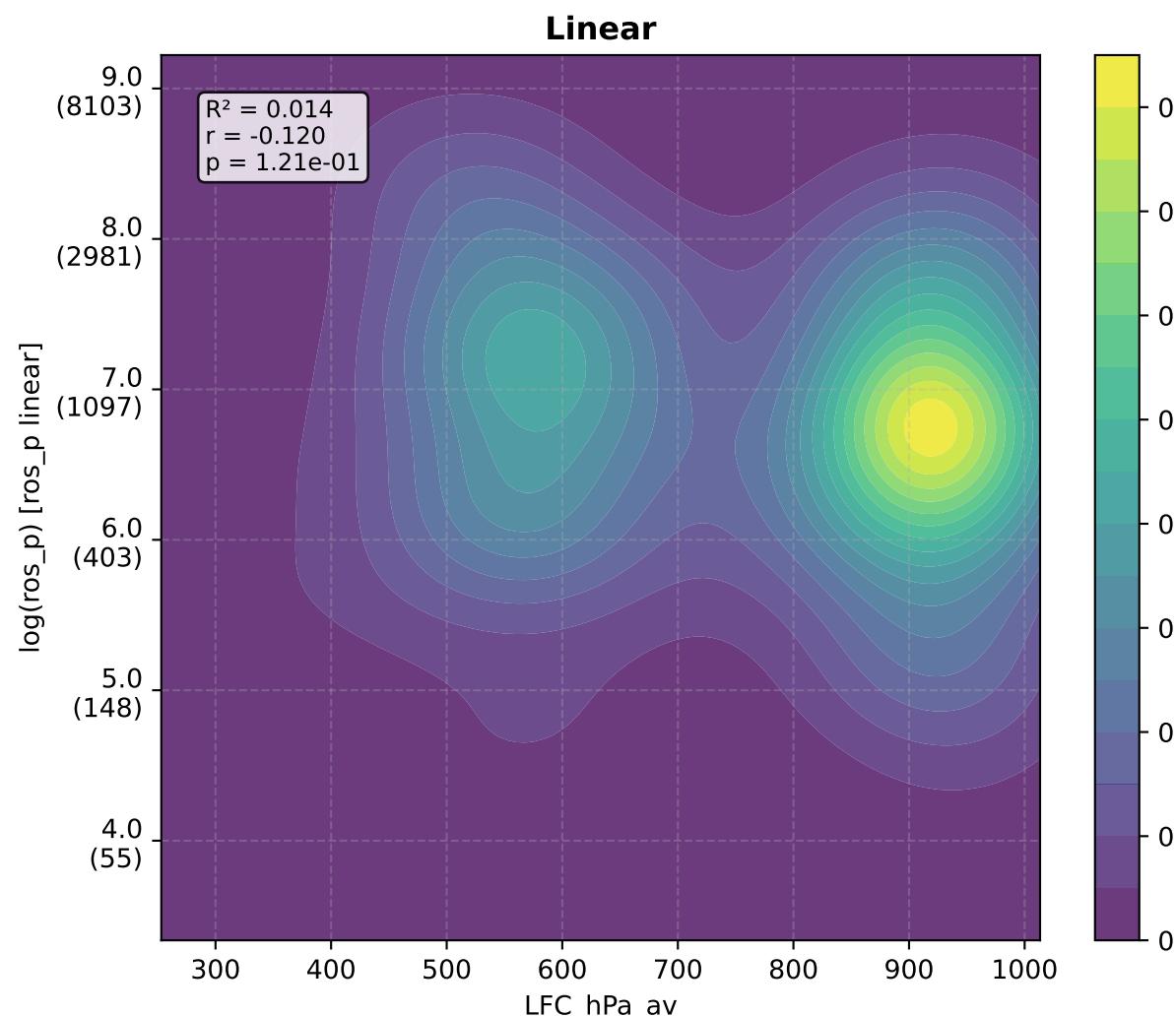
Densidade

3.6
3.2
2.8
2.4
2.0
1.6
1.2
0.8
0.4
0.0

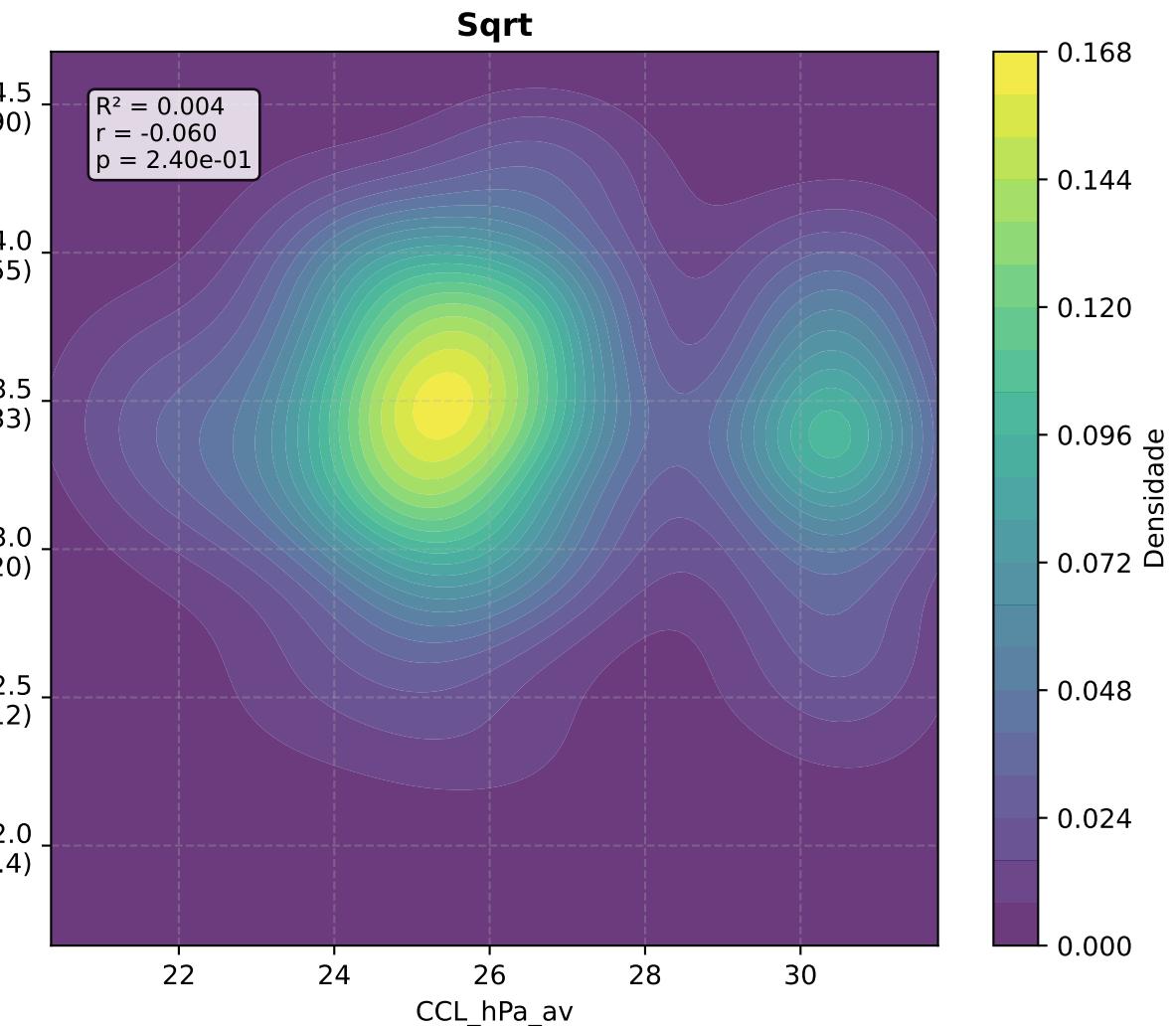
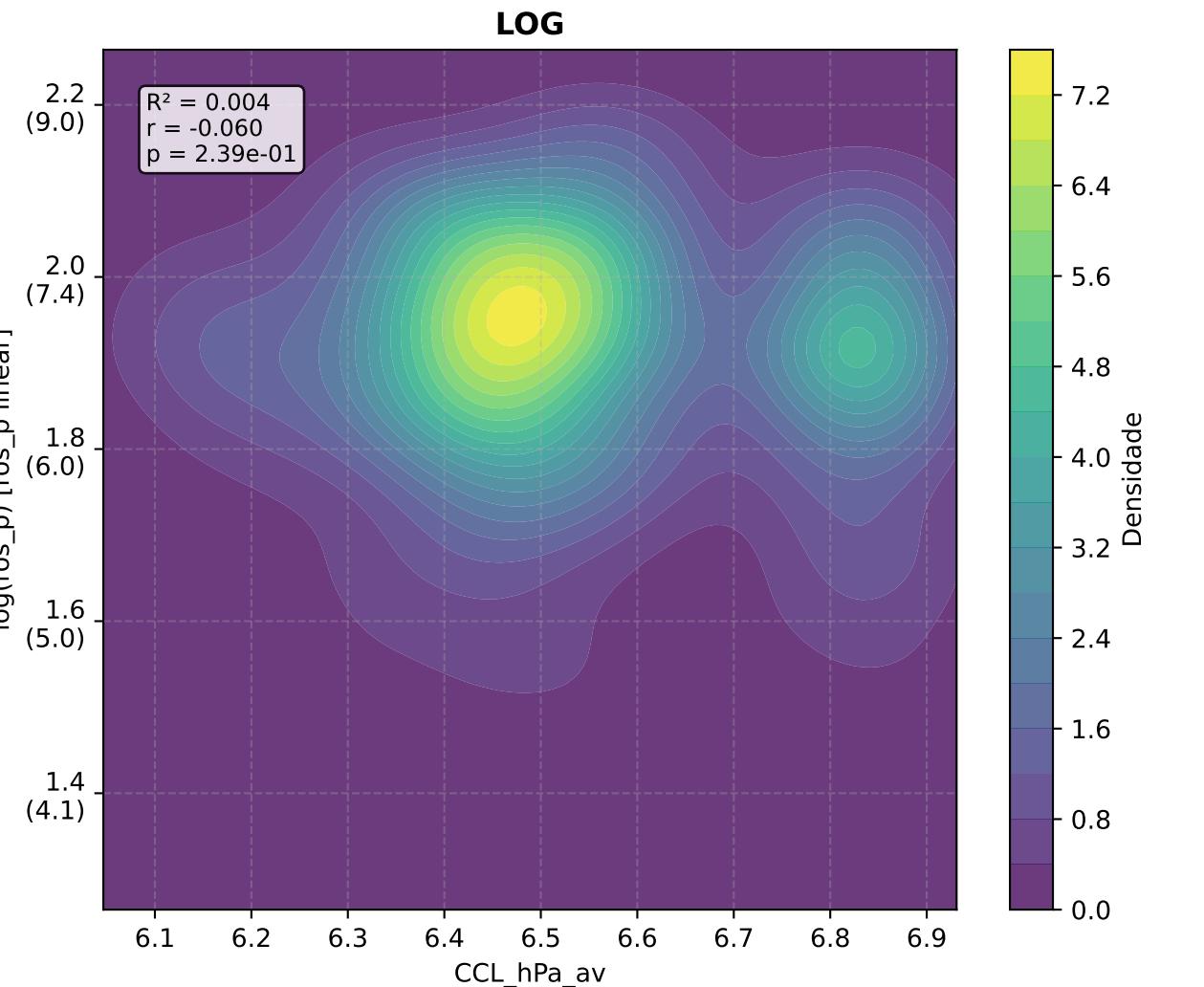
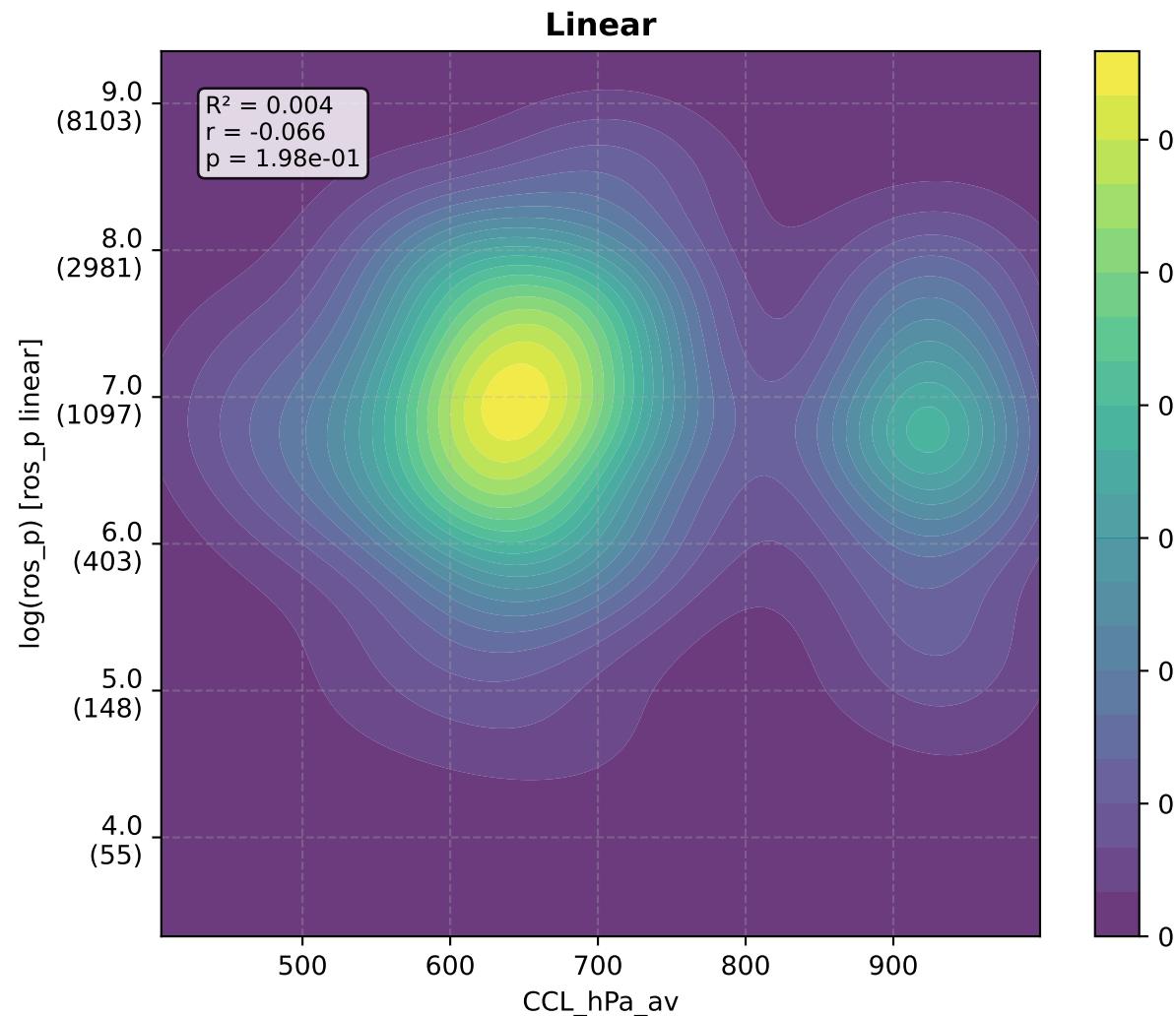
CMLG_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



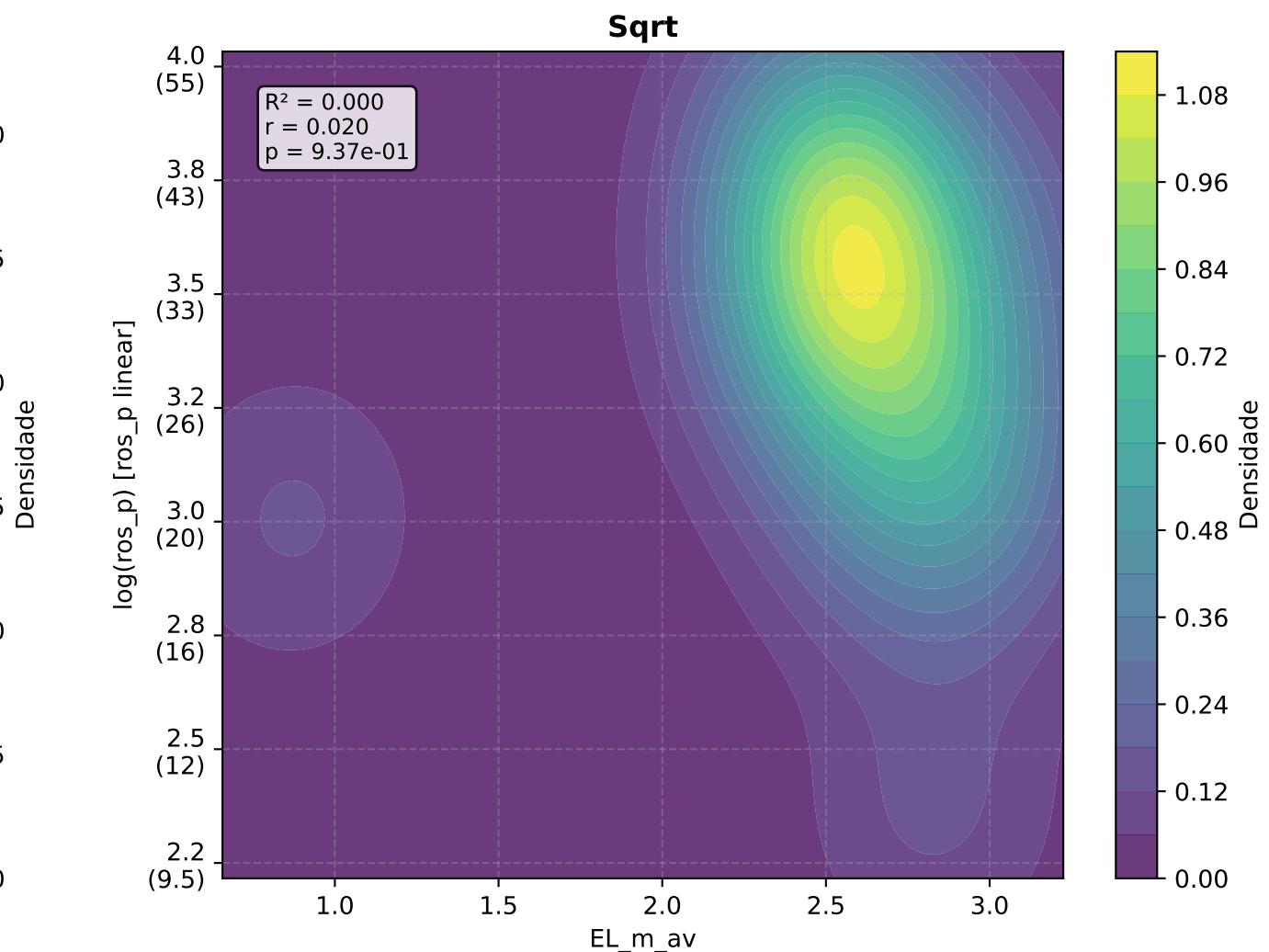
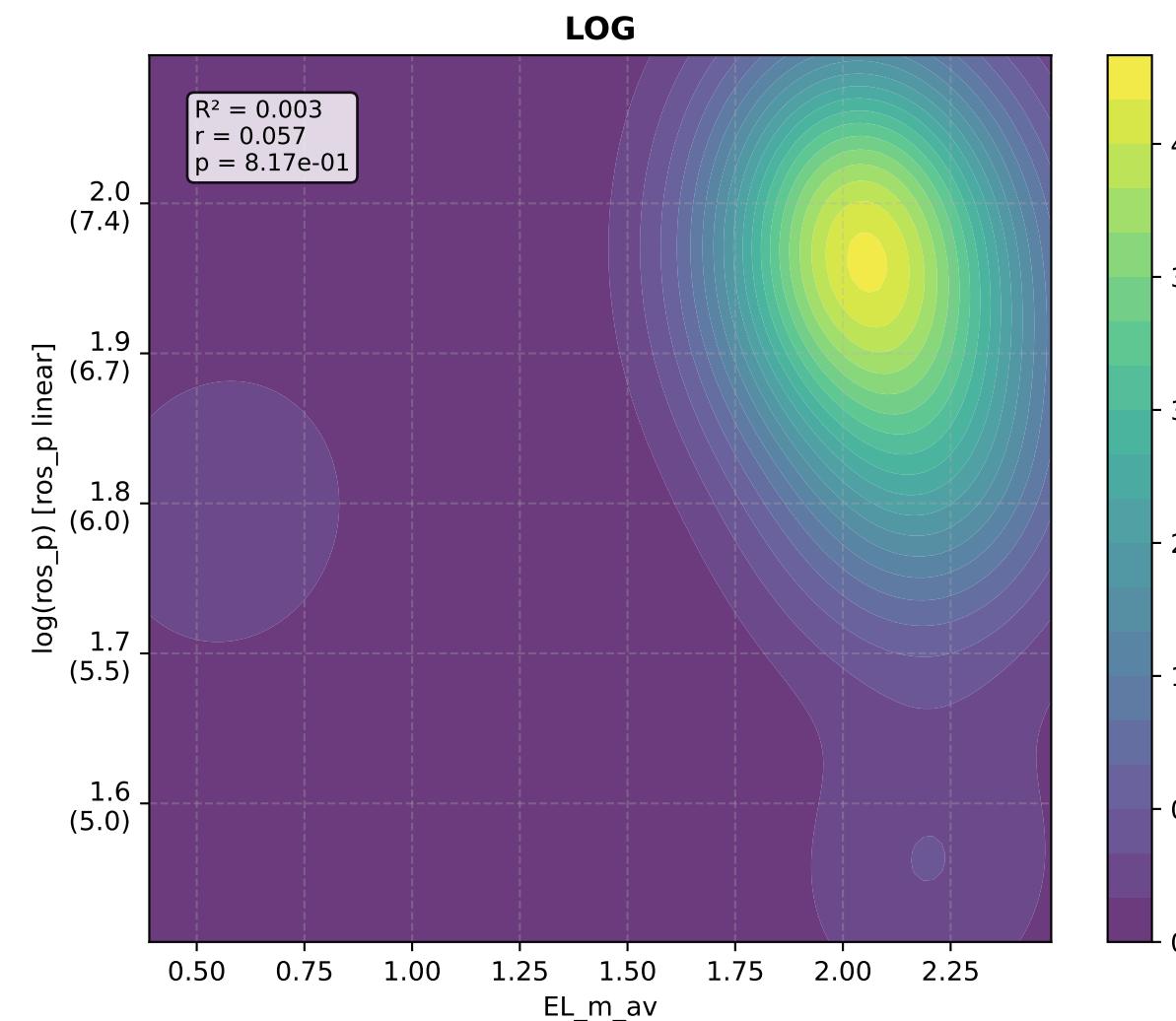
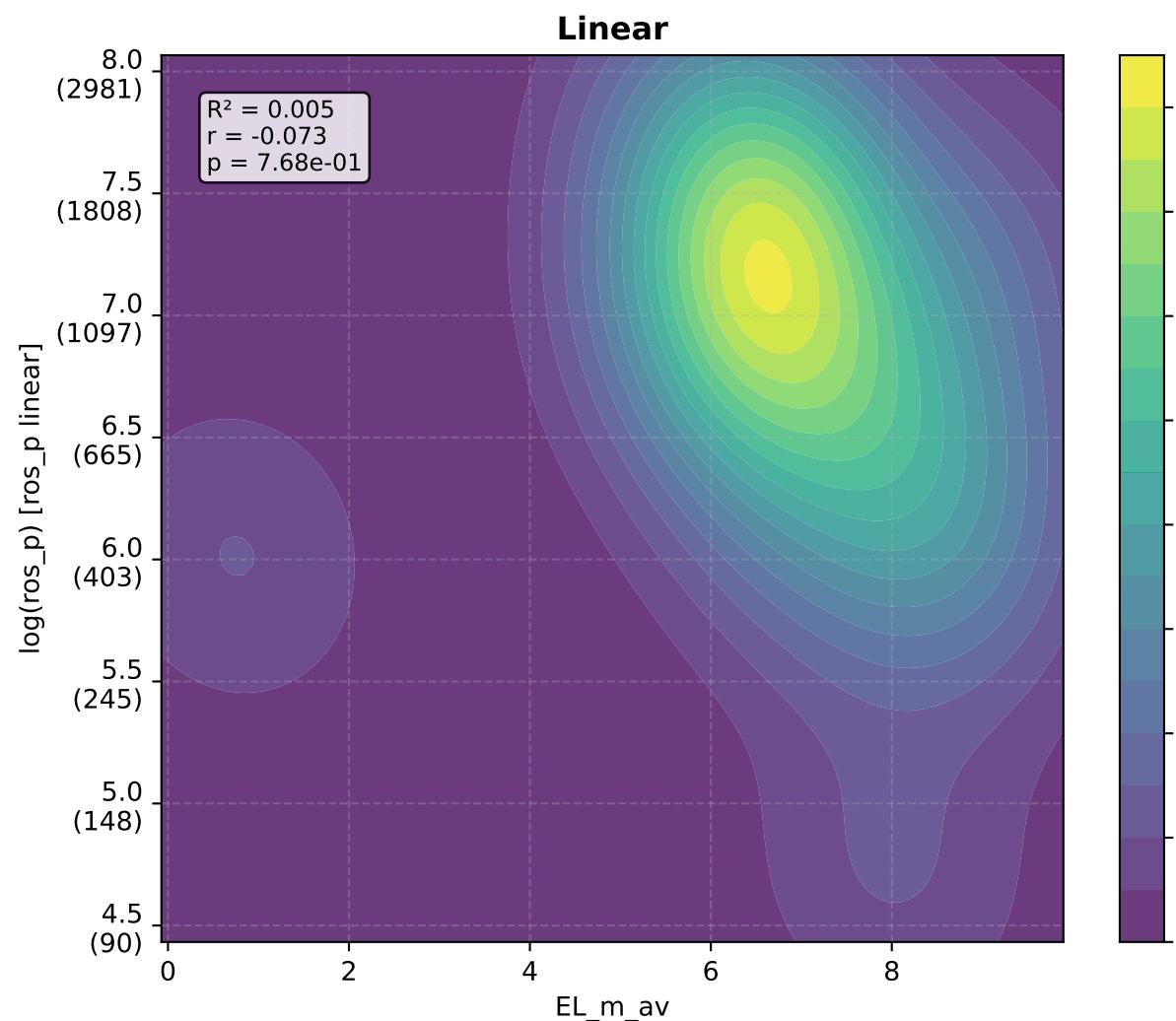
LFC_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



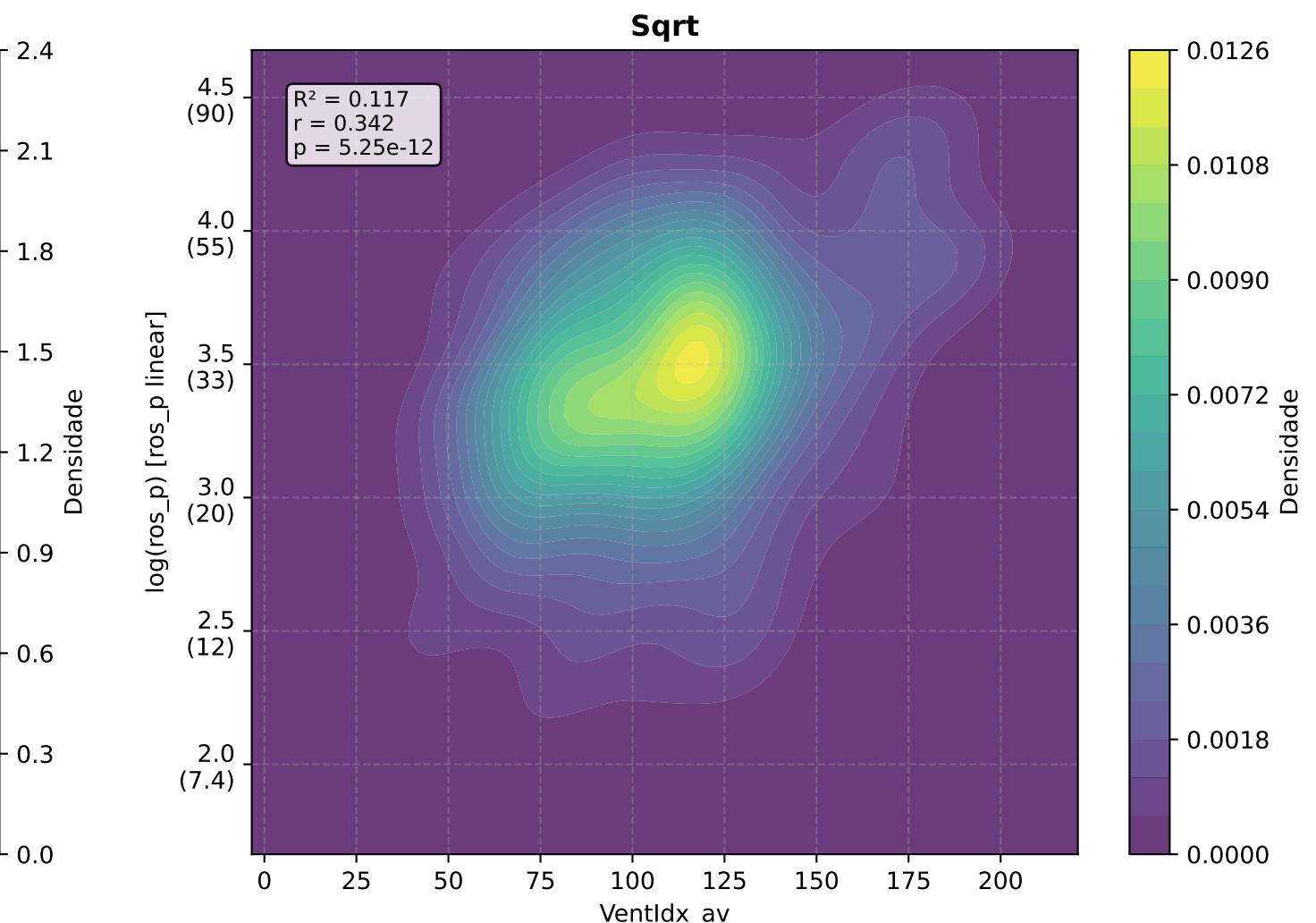
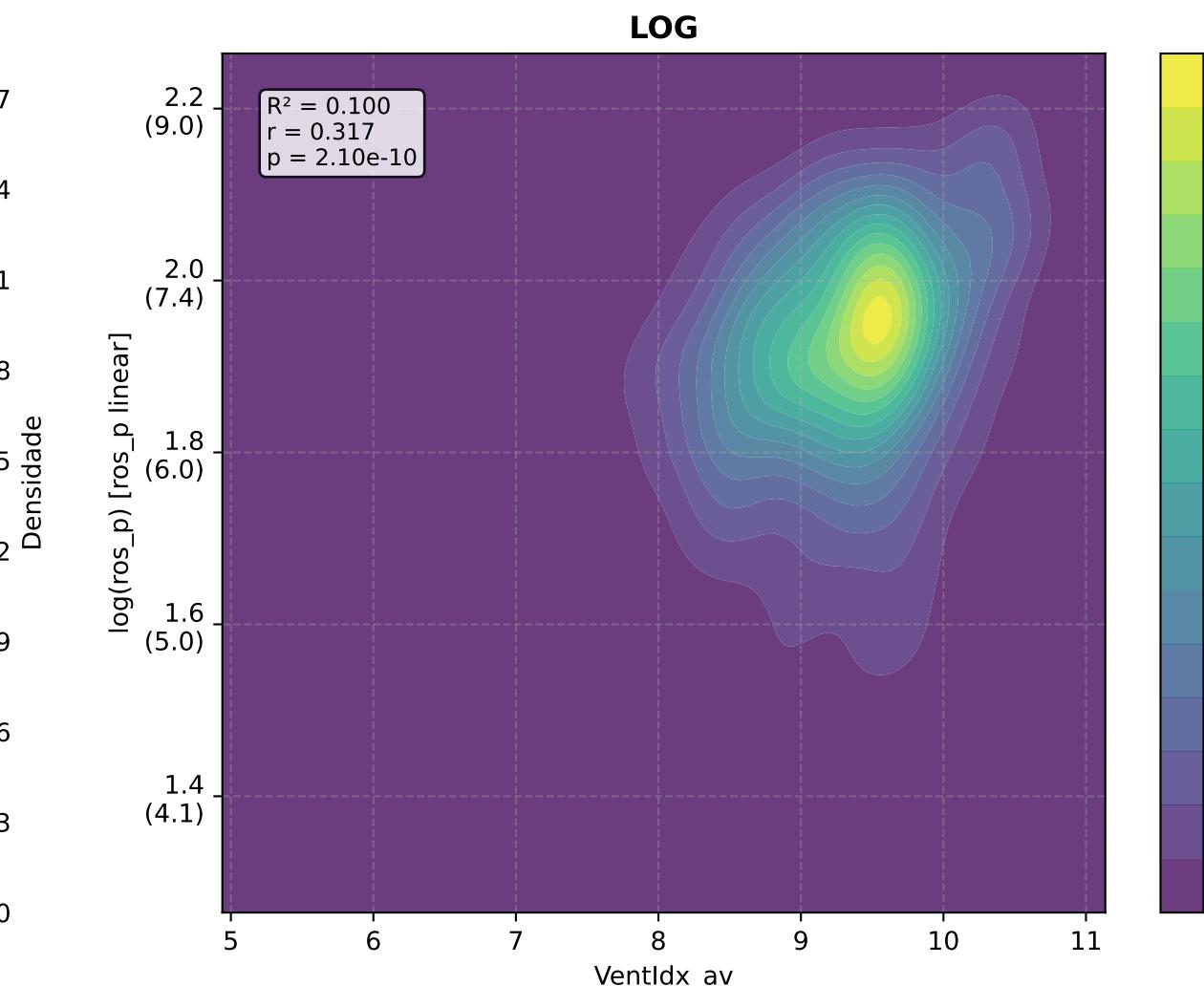
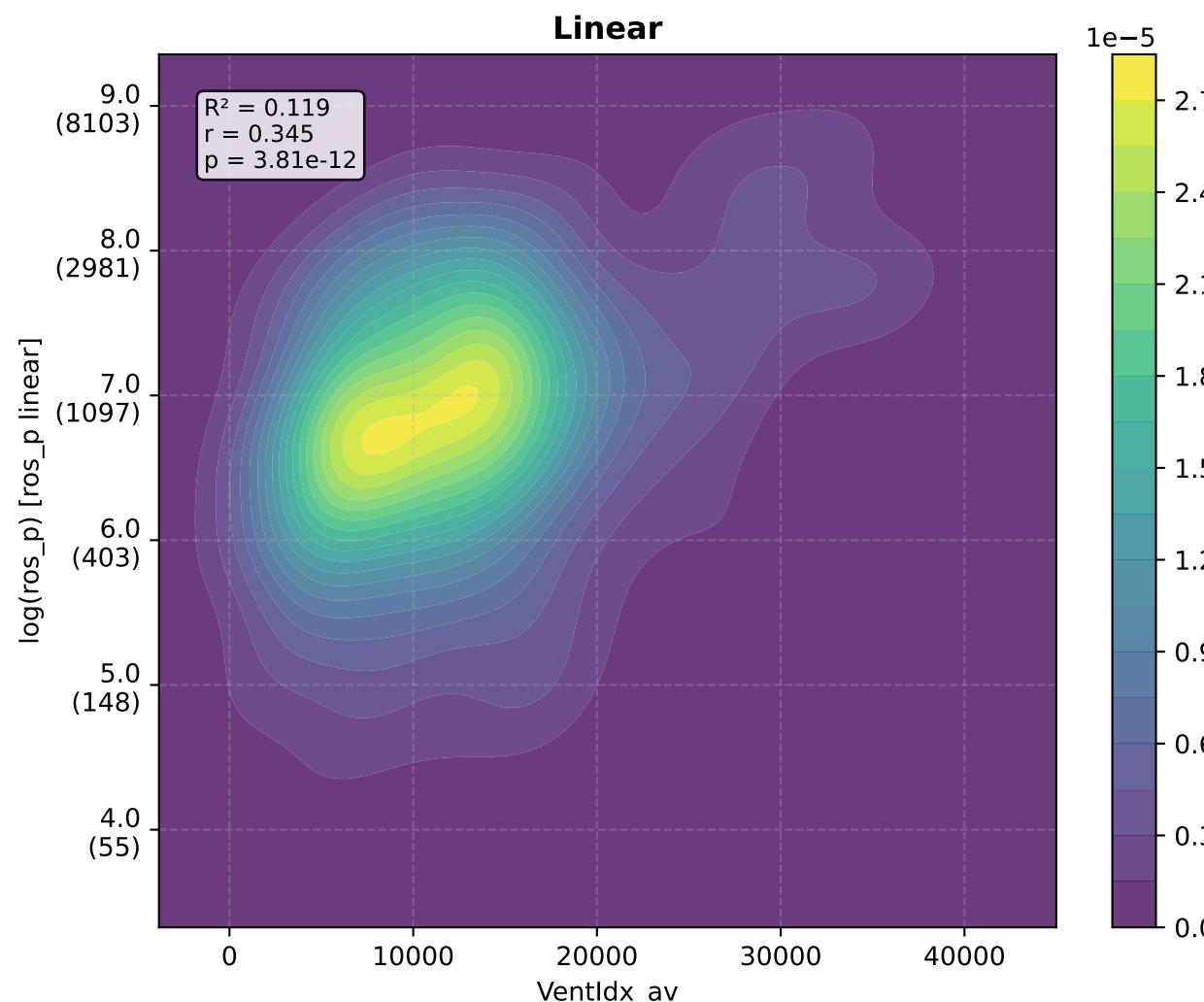
CCL_hPa_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



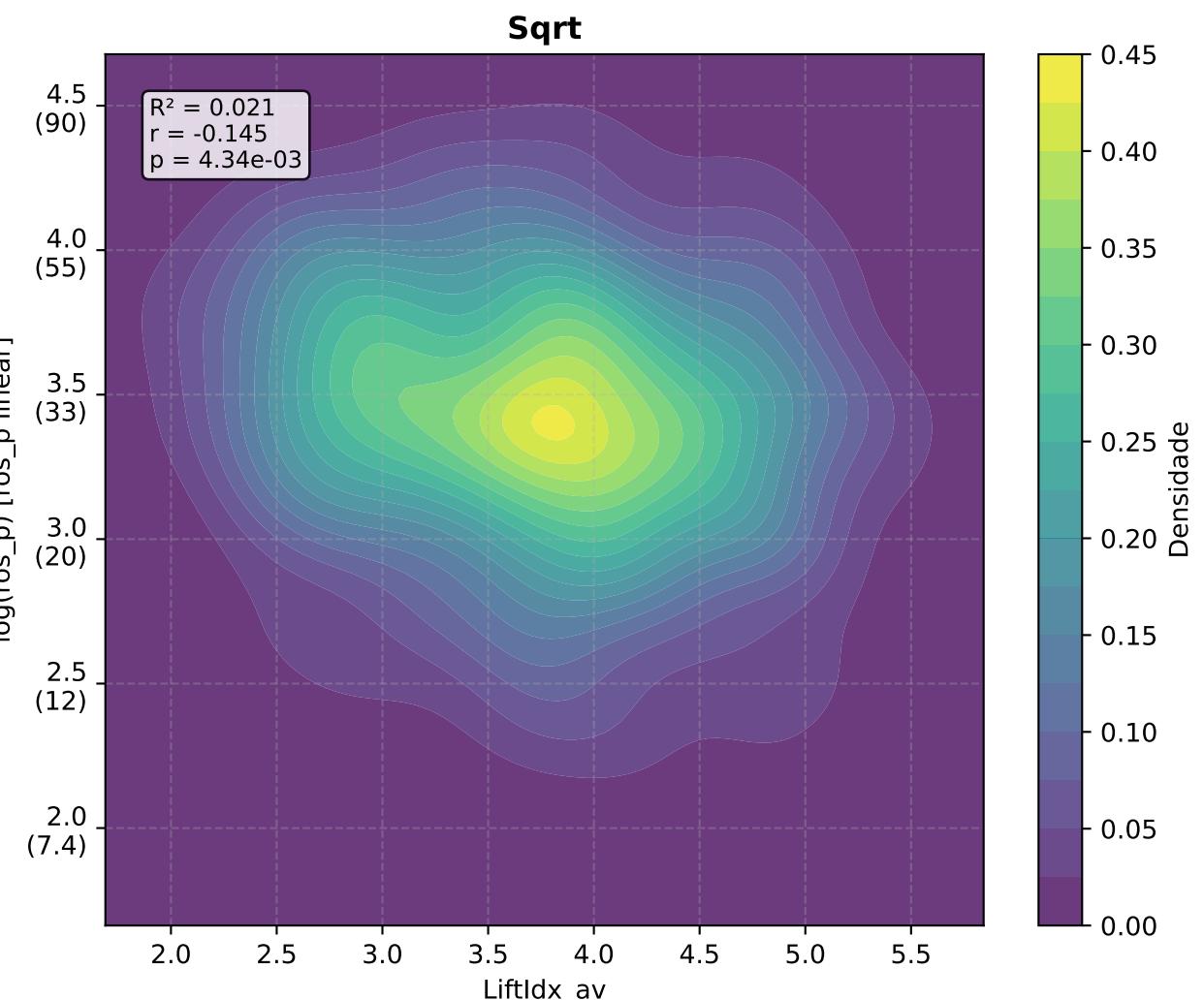
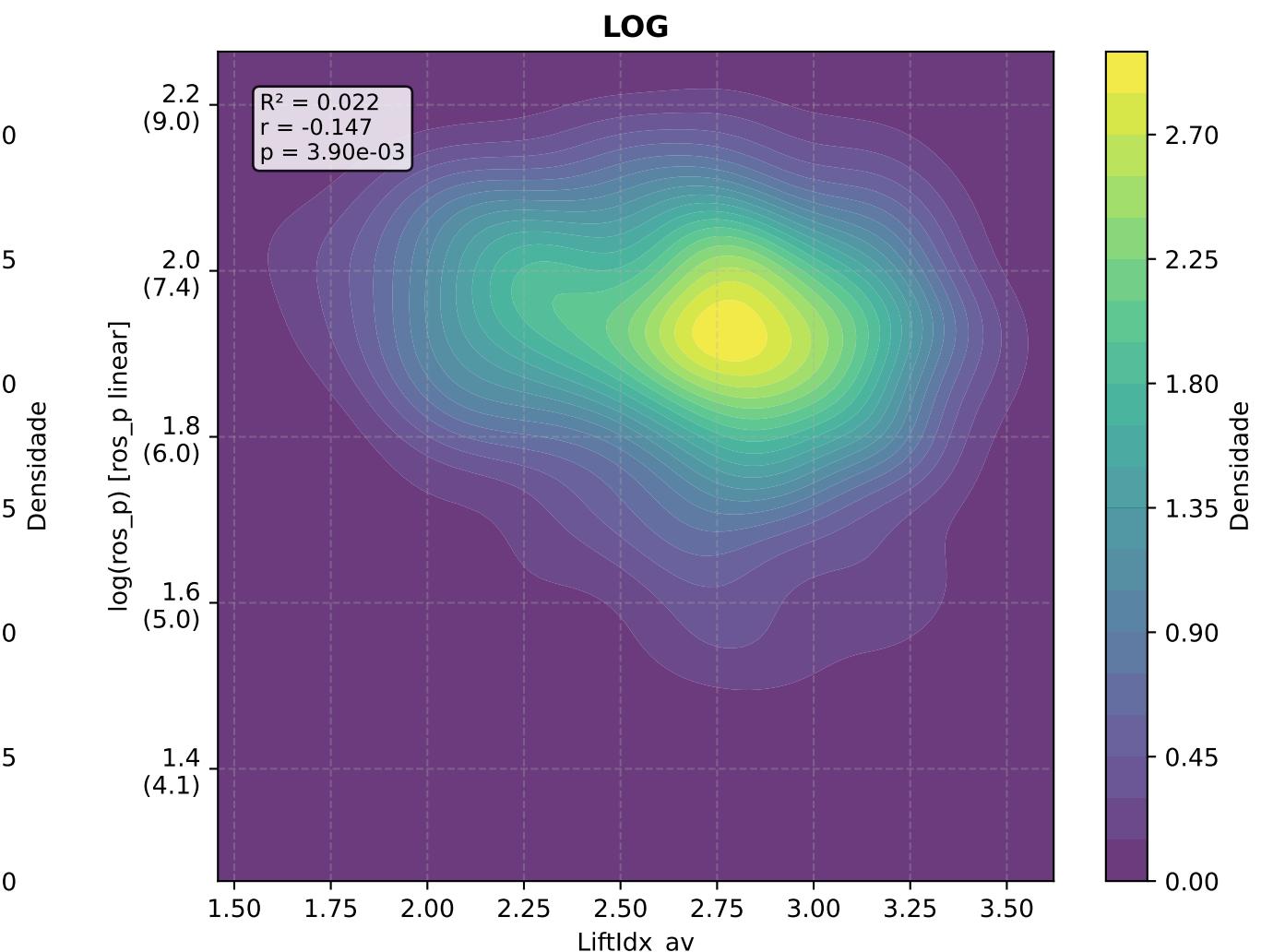
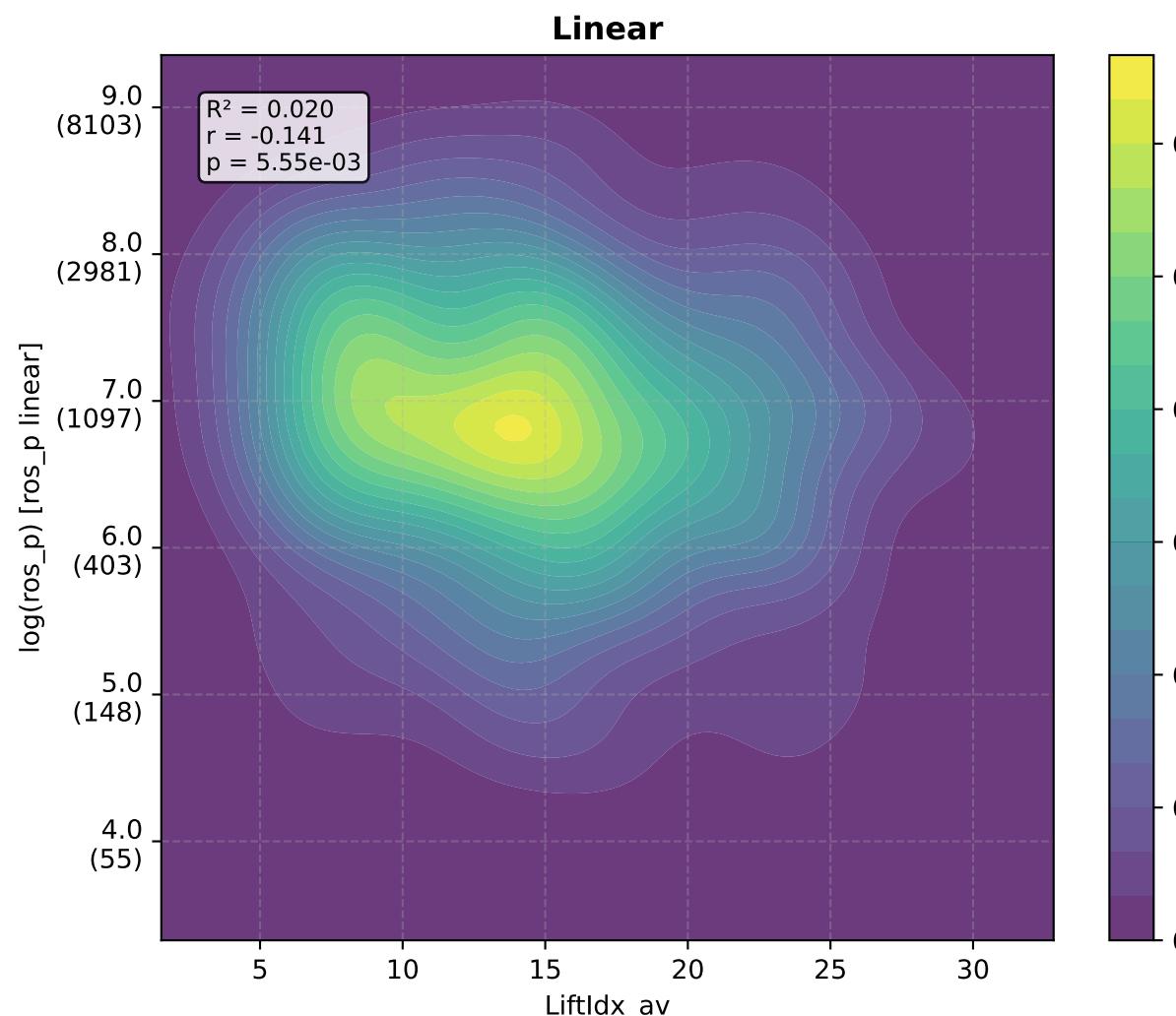
EL_m_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



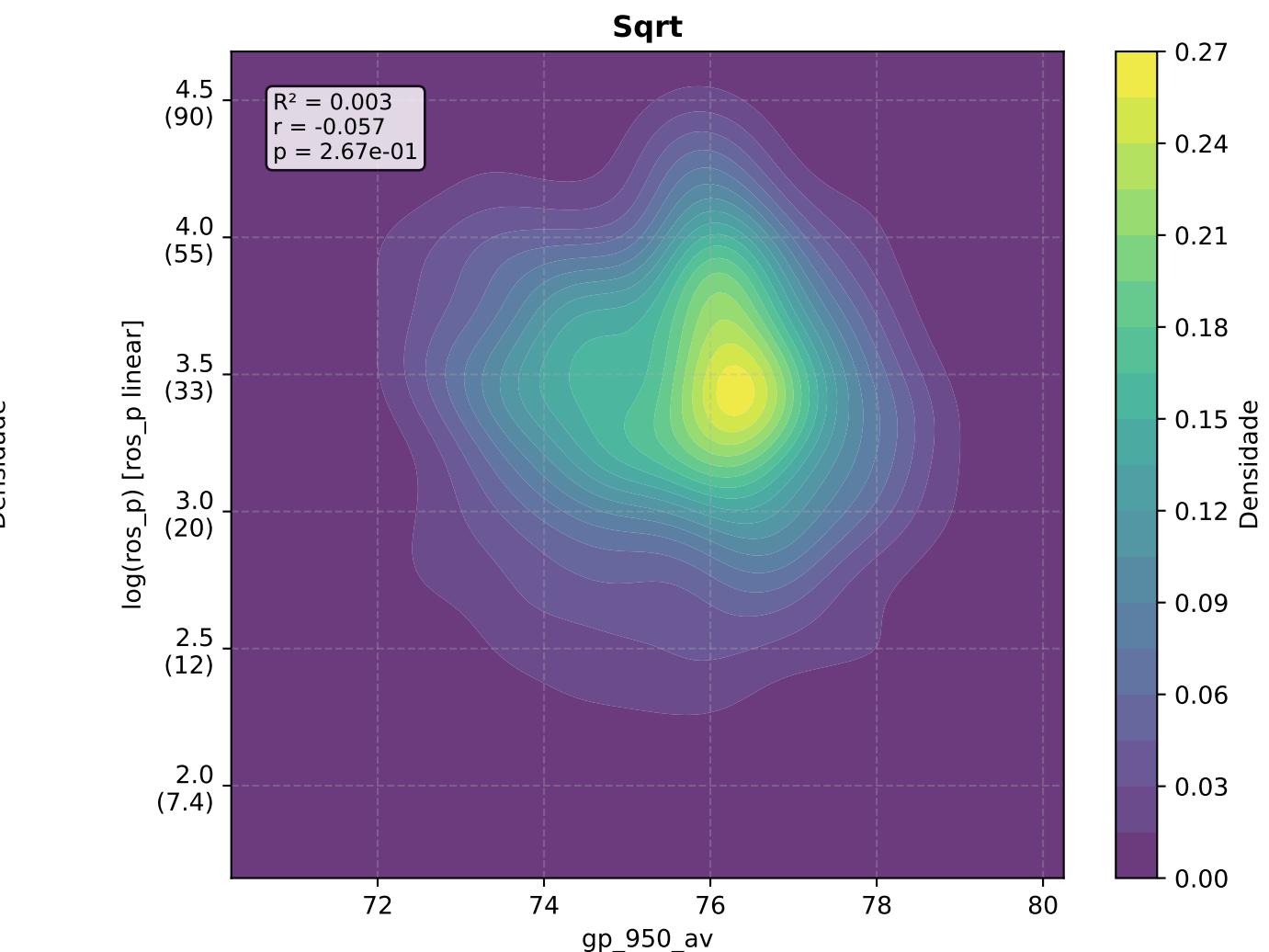
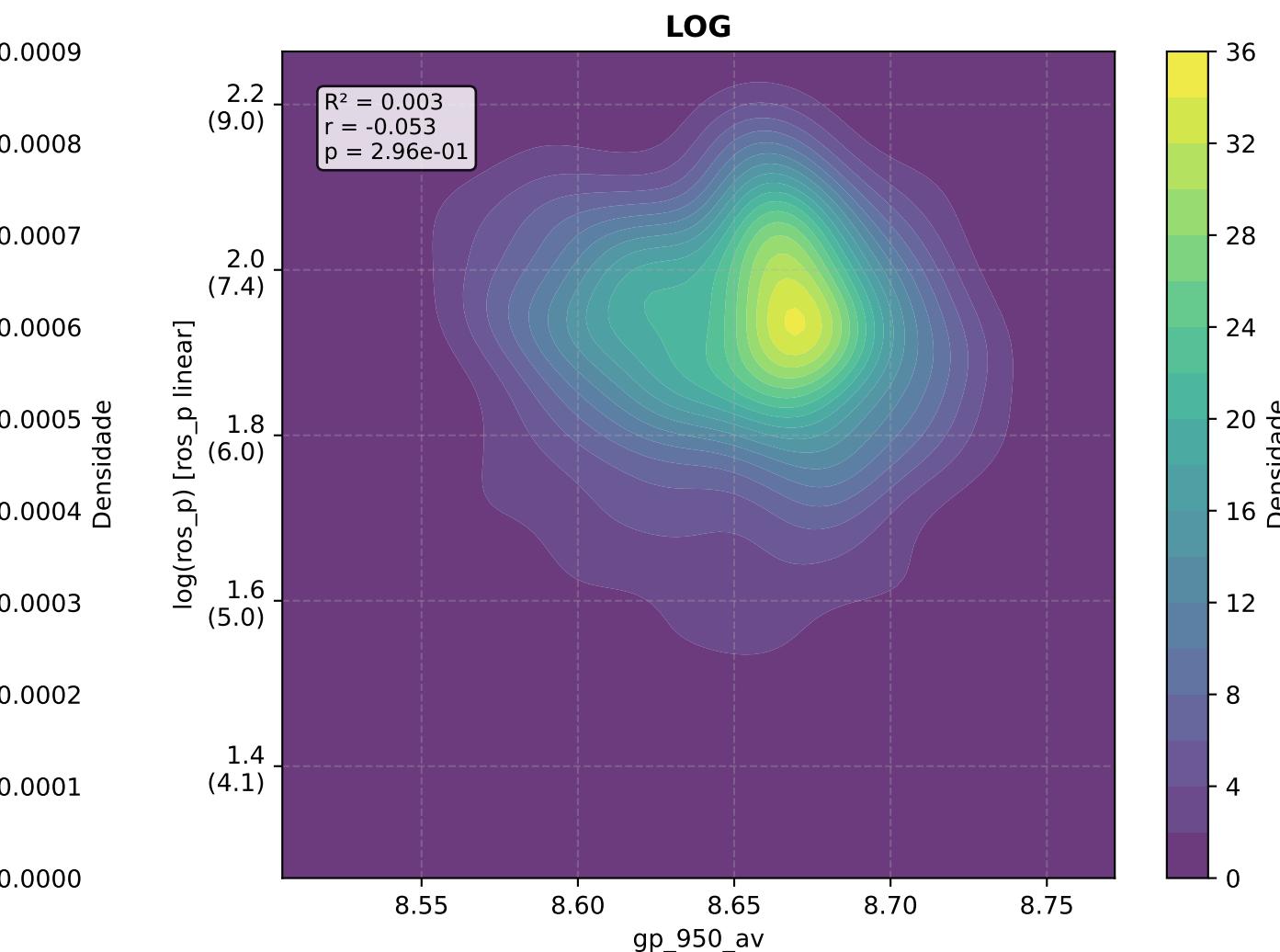
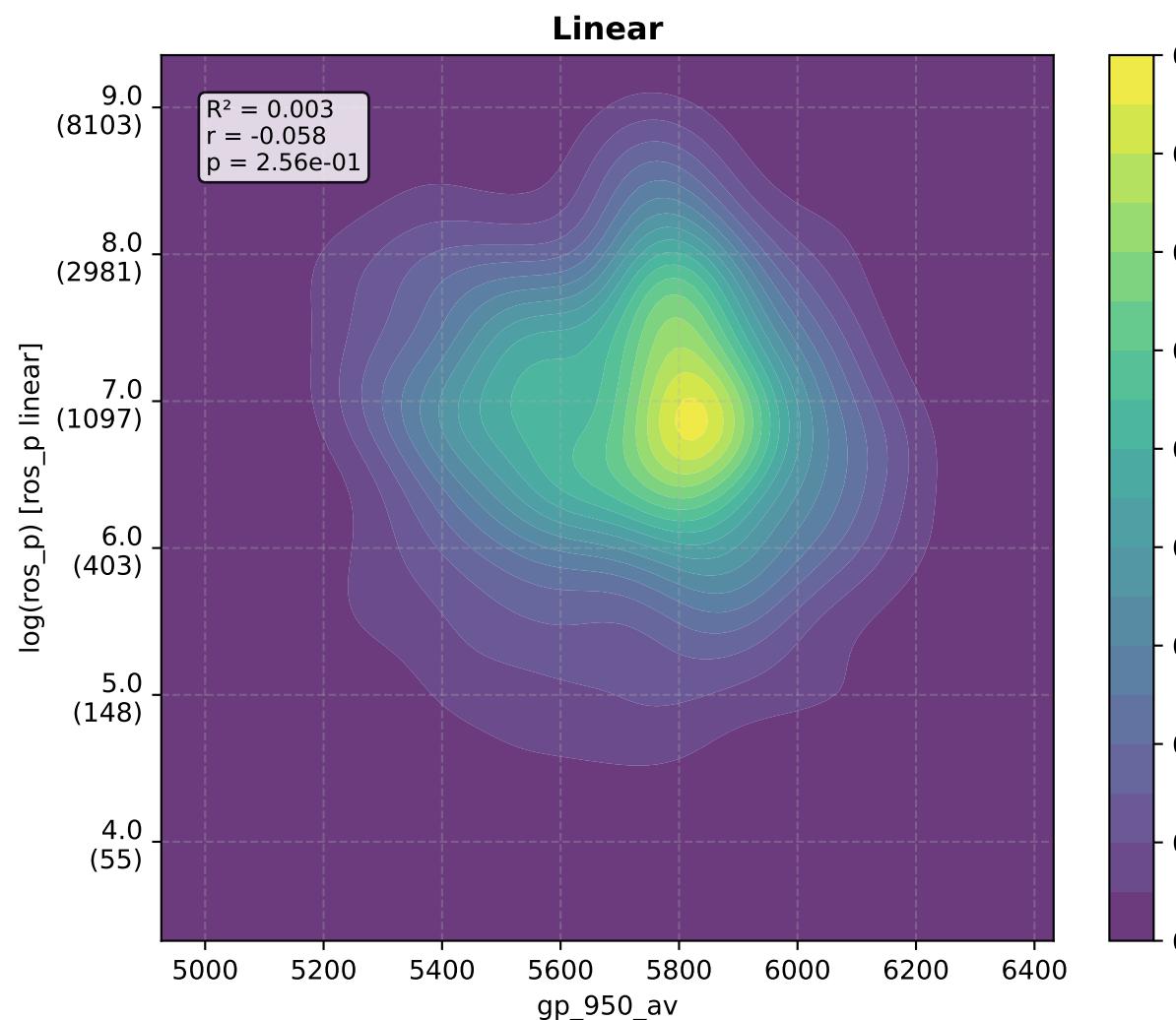
VentIdx_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



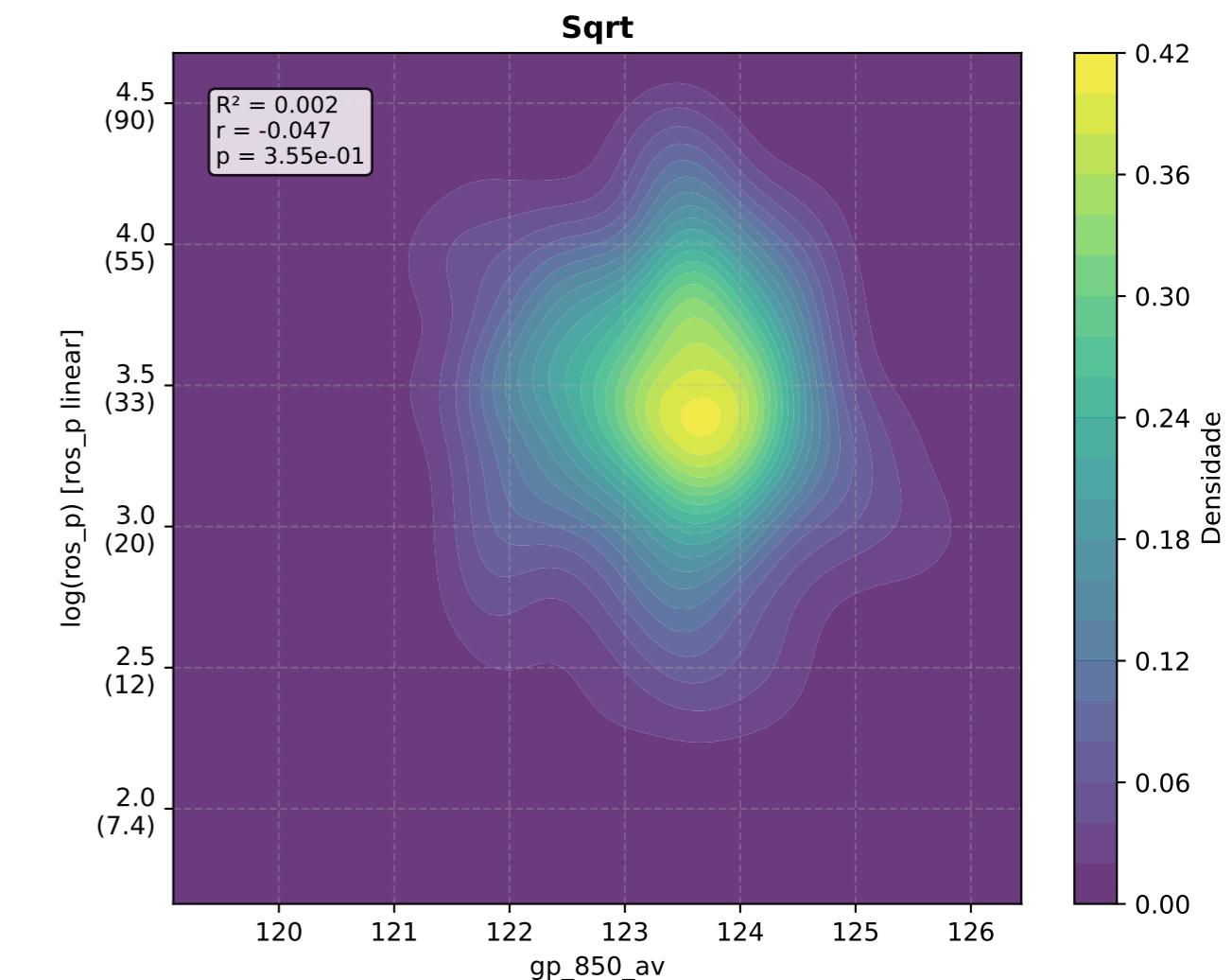
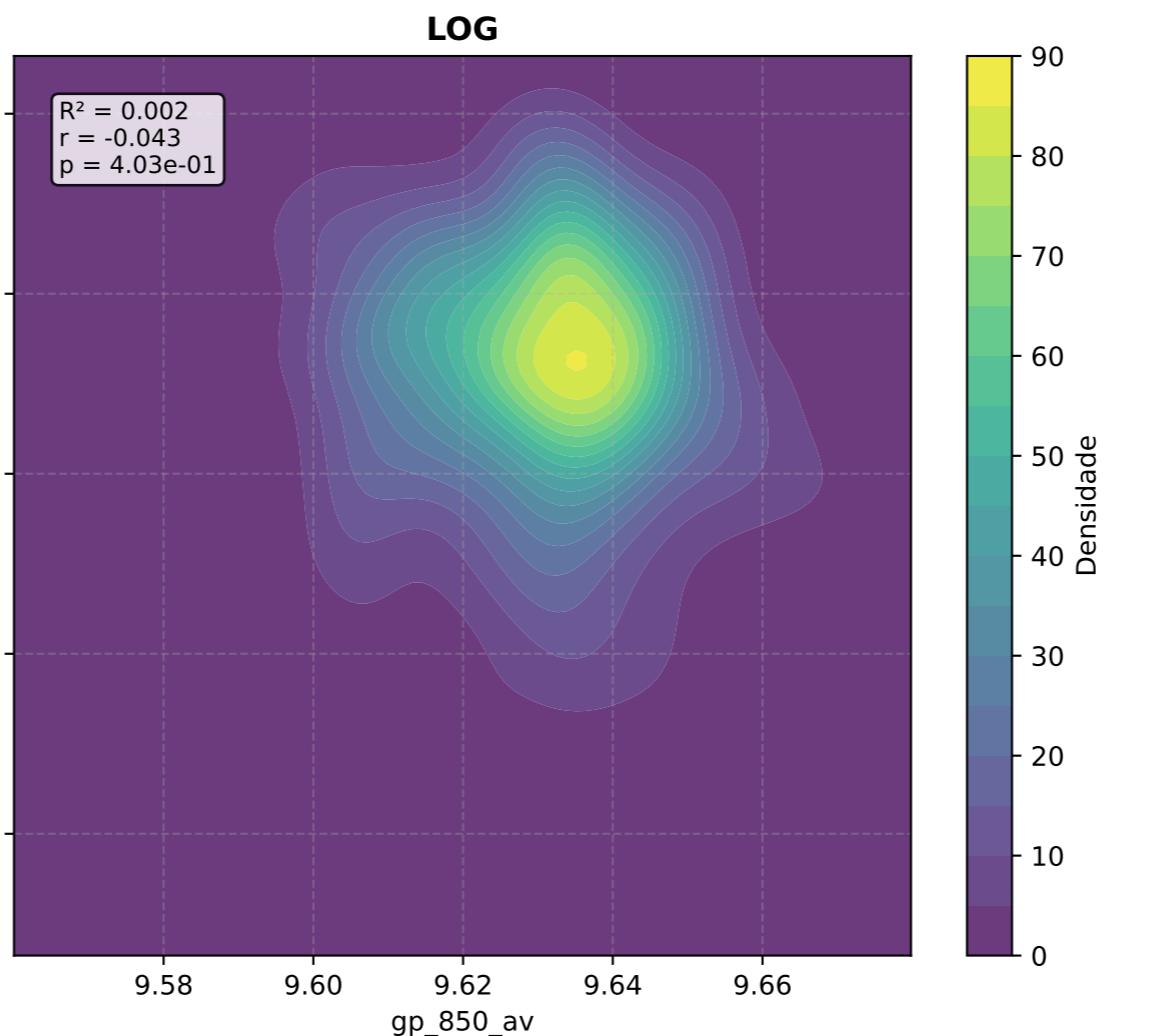
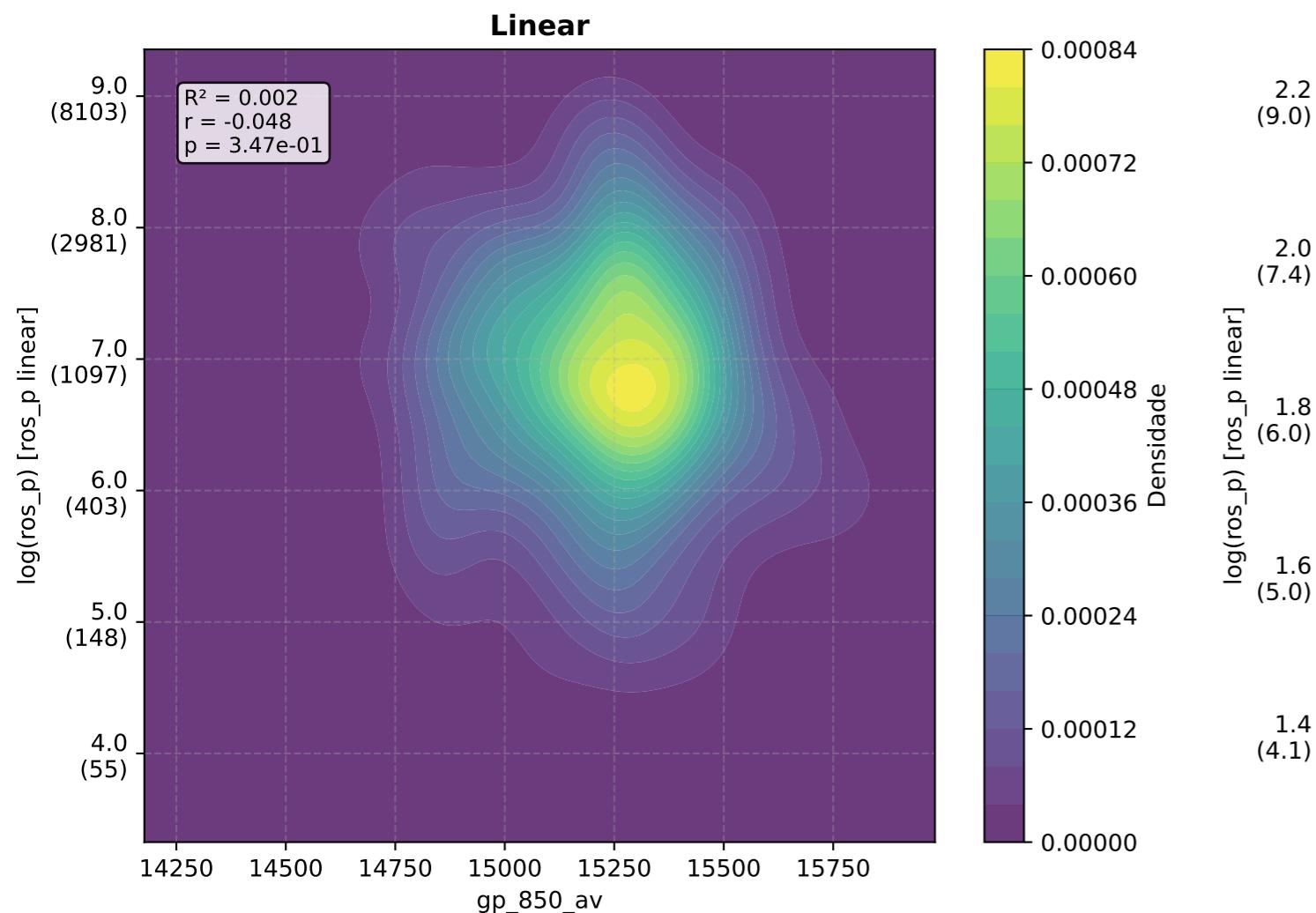
LiftIdx_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



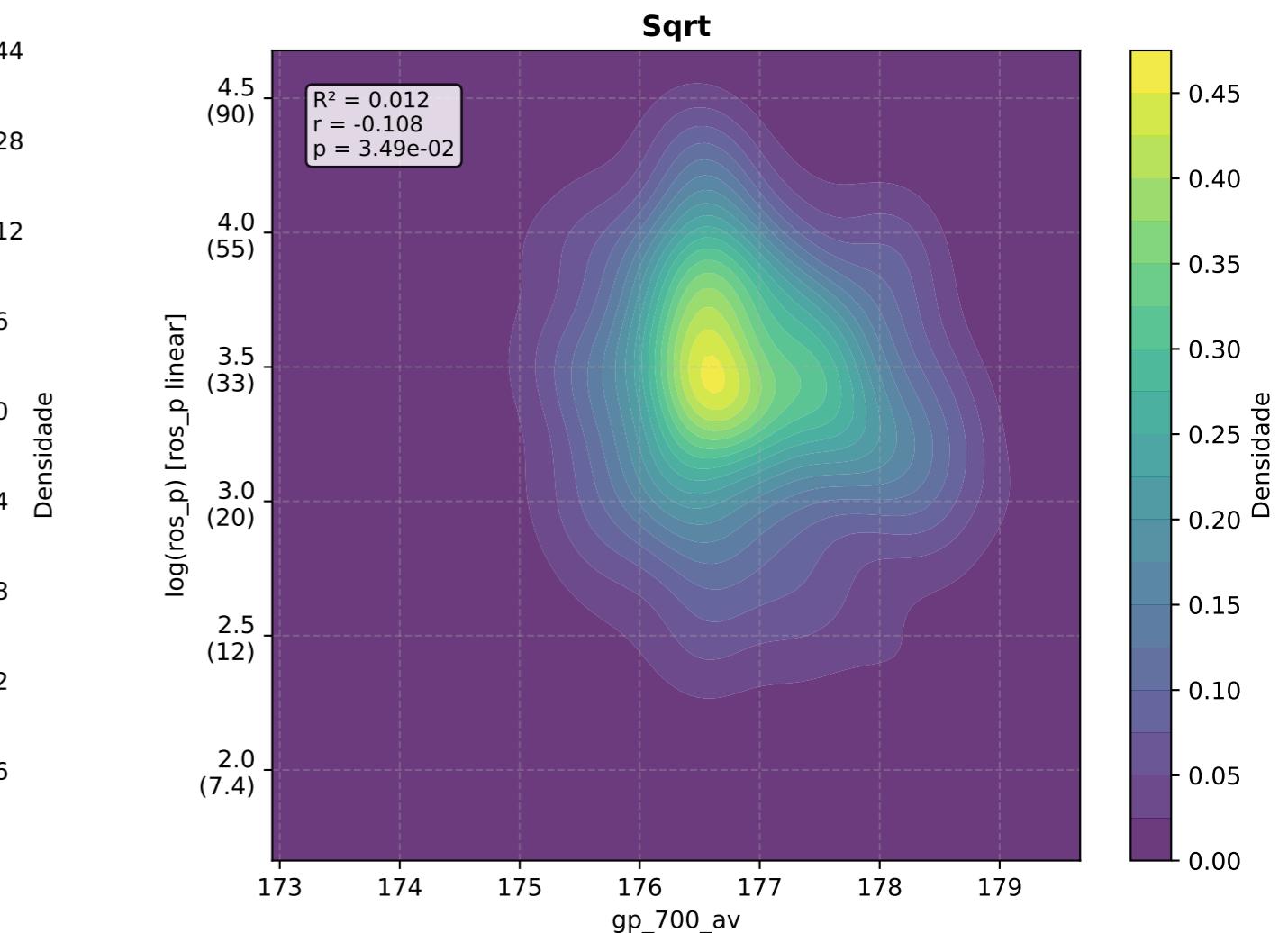
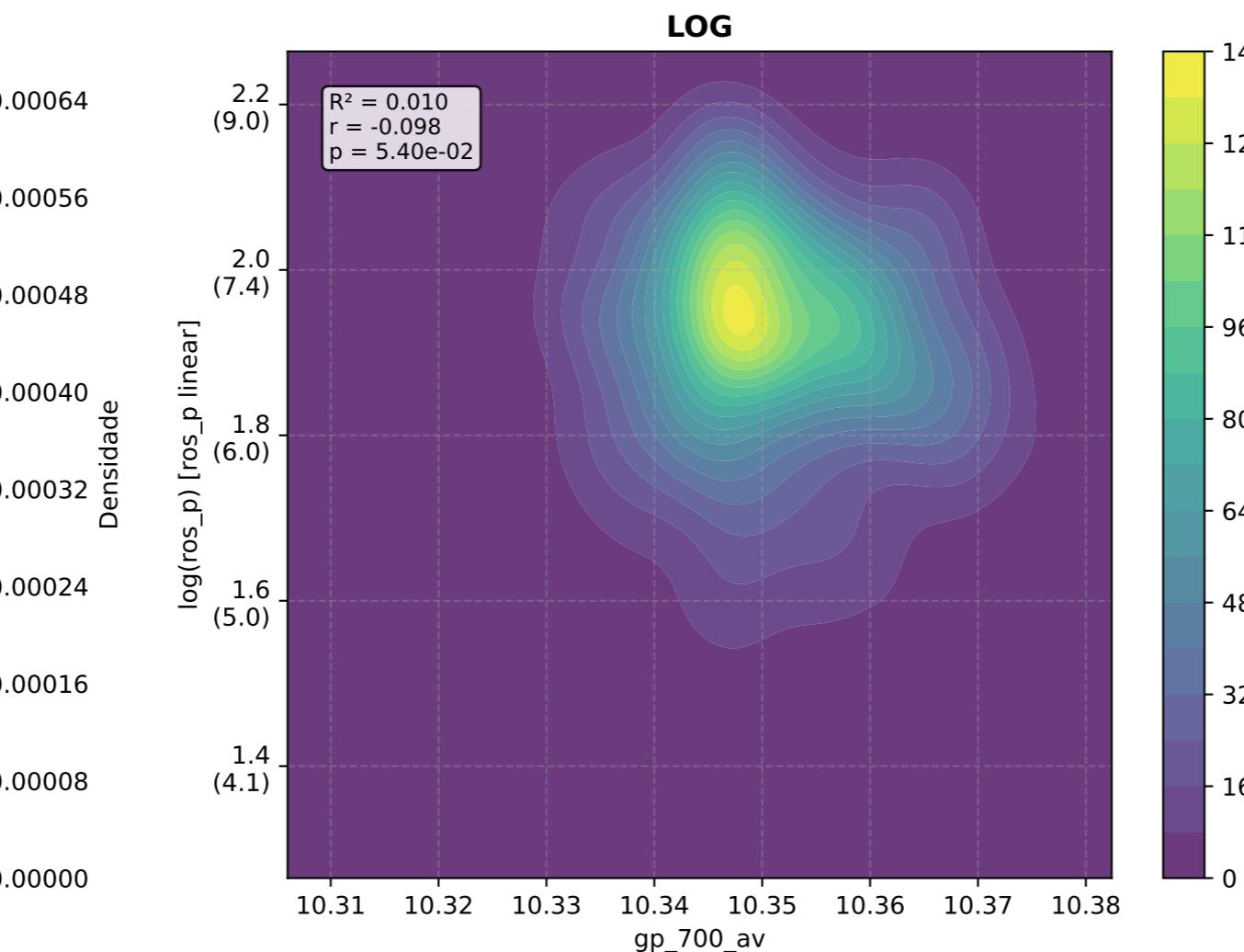
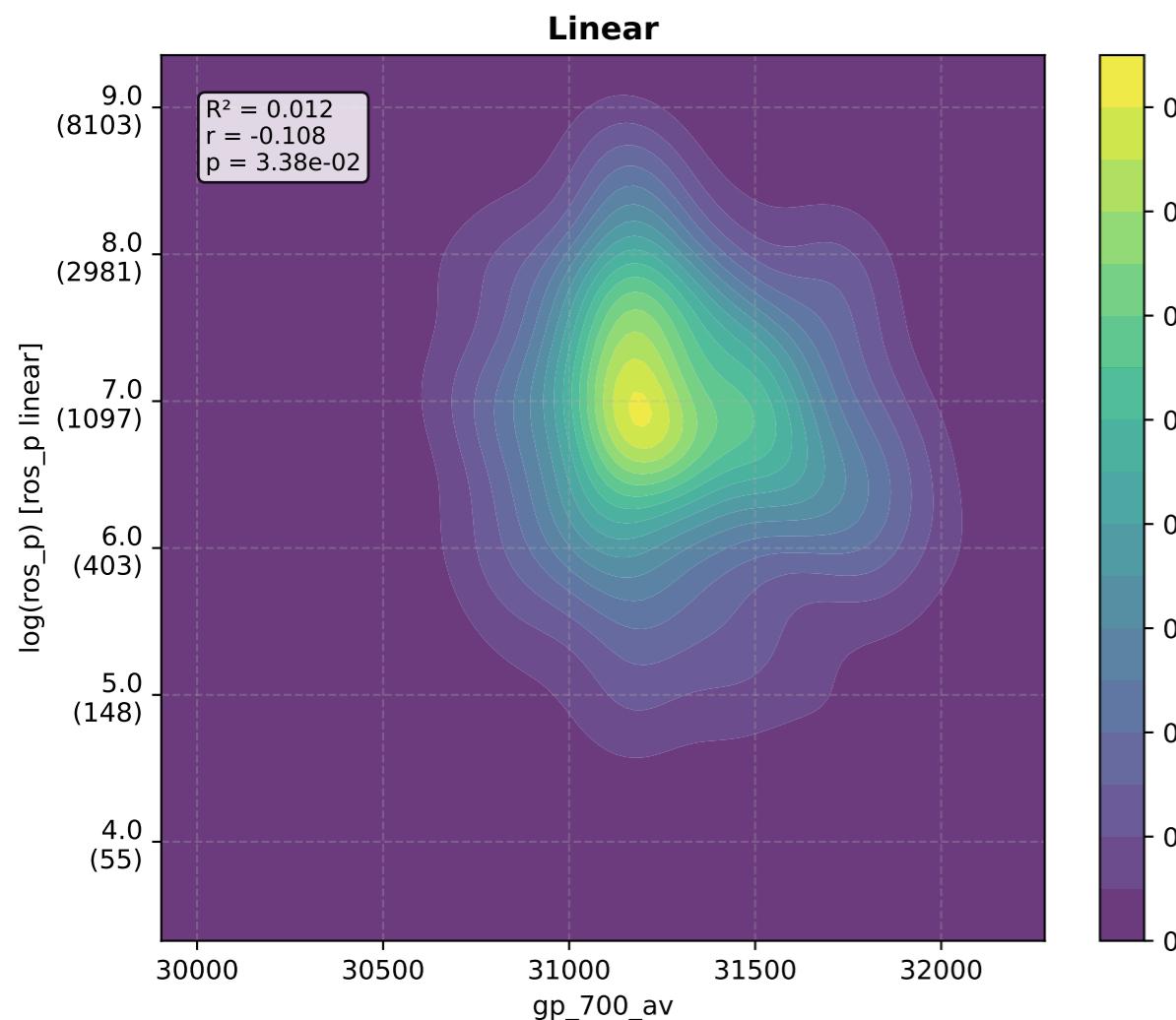
gp_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



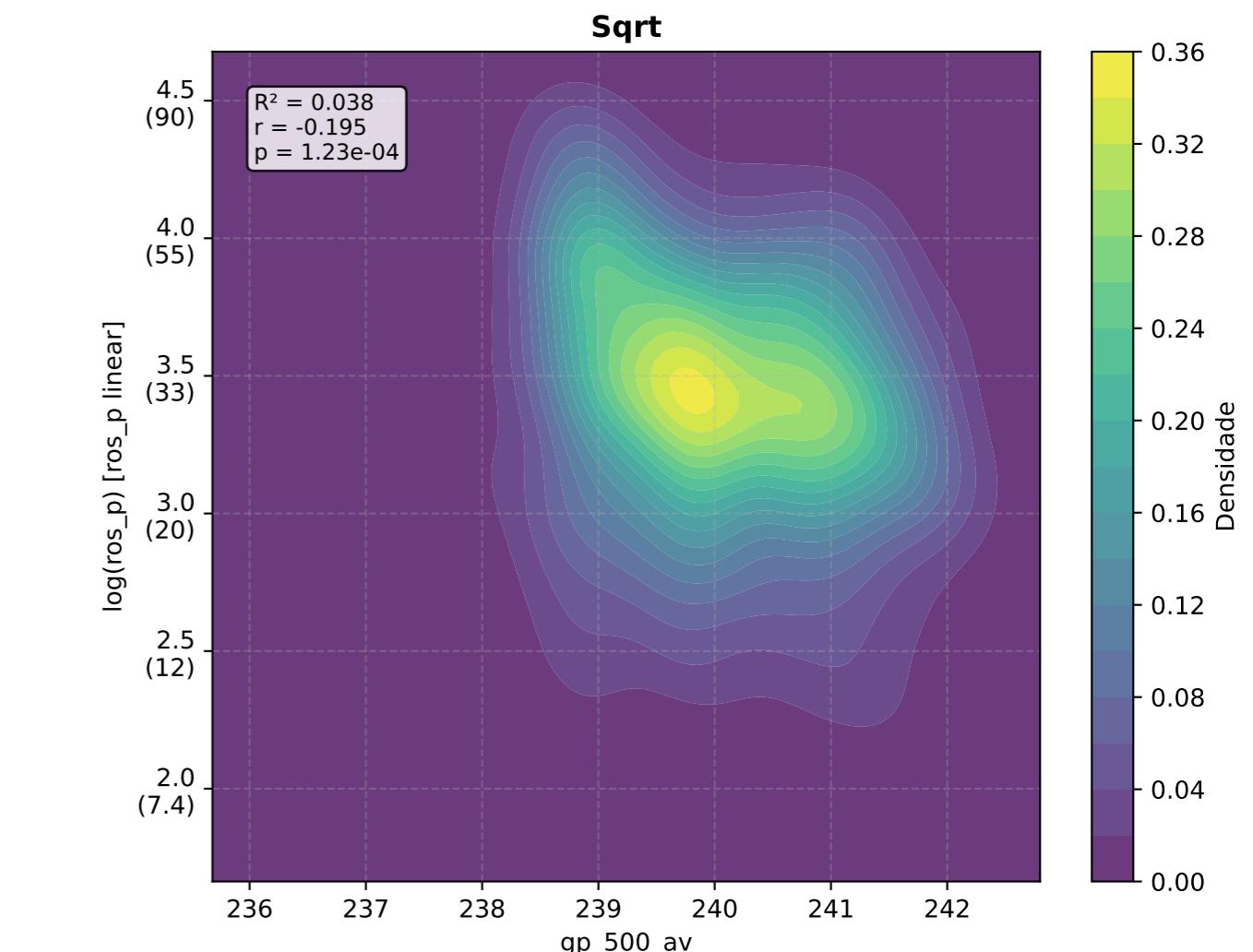
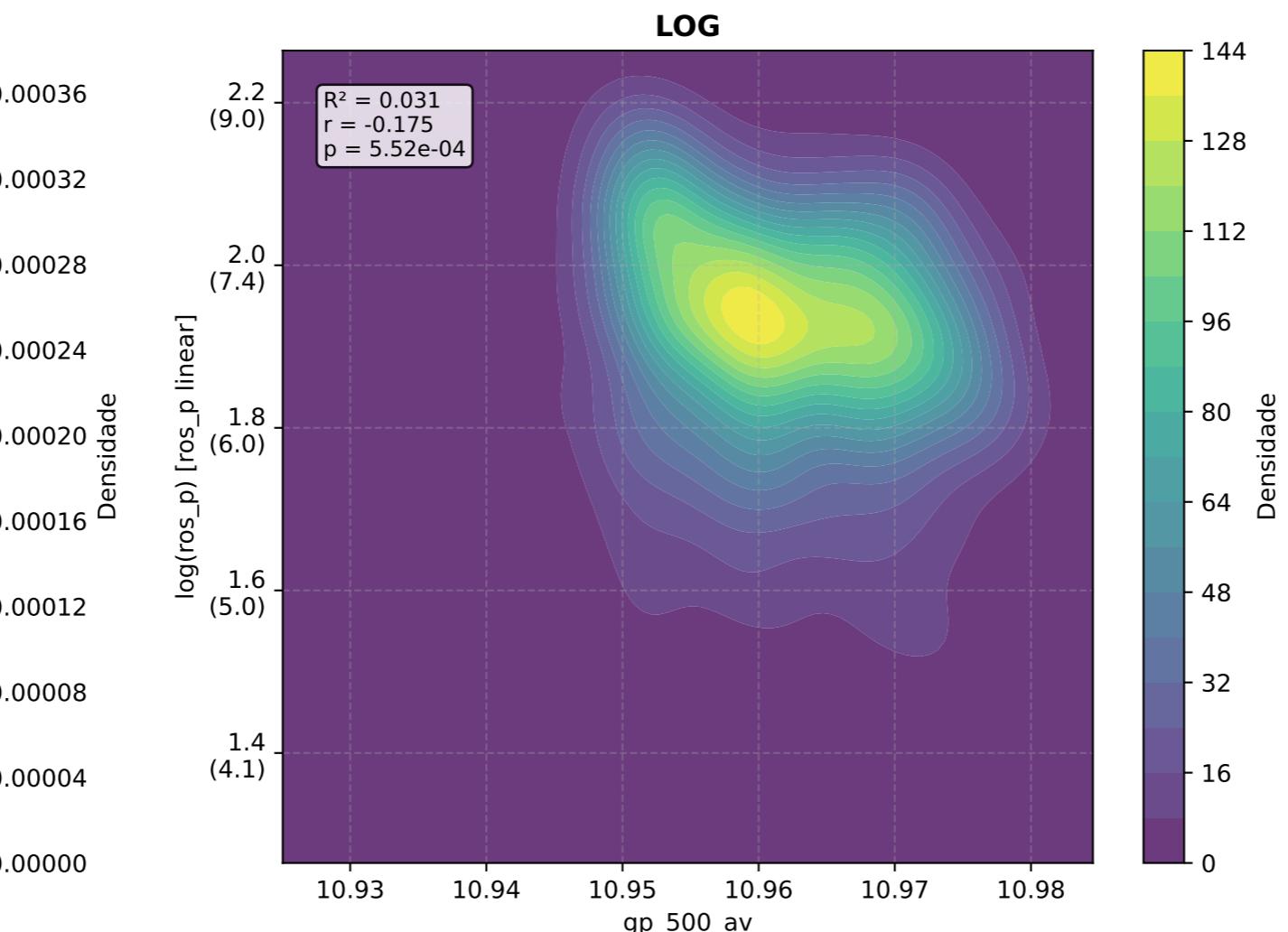
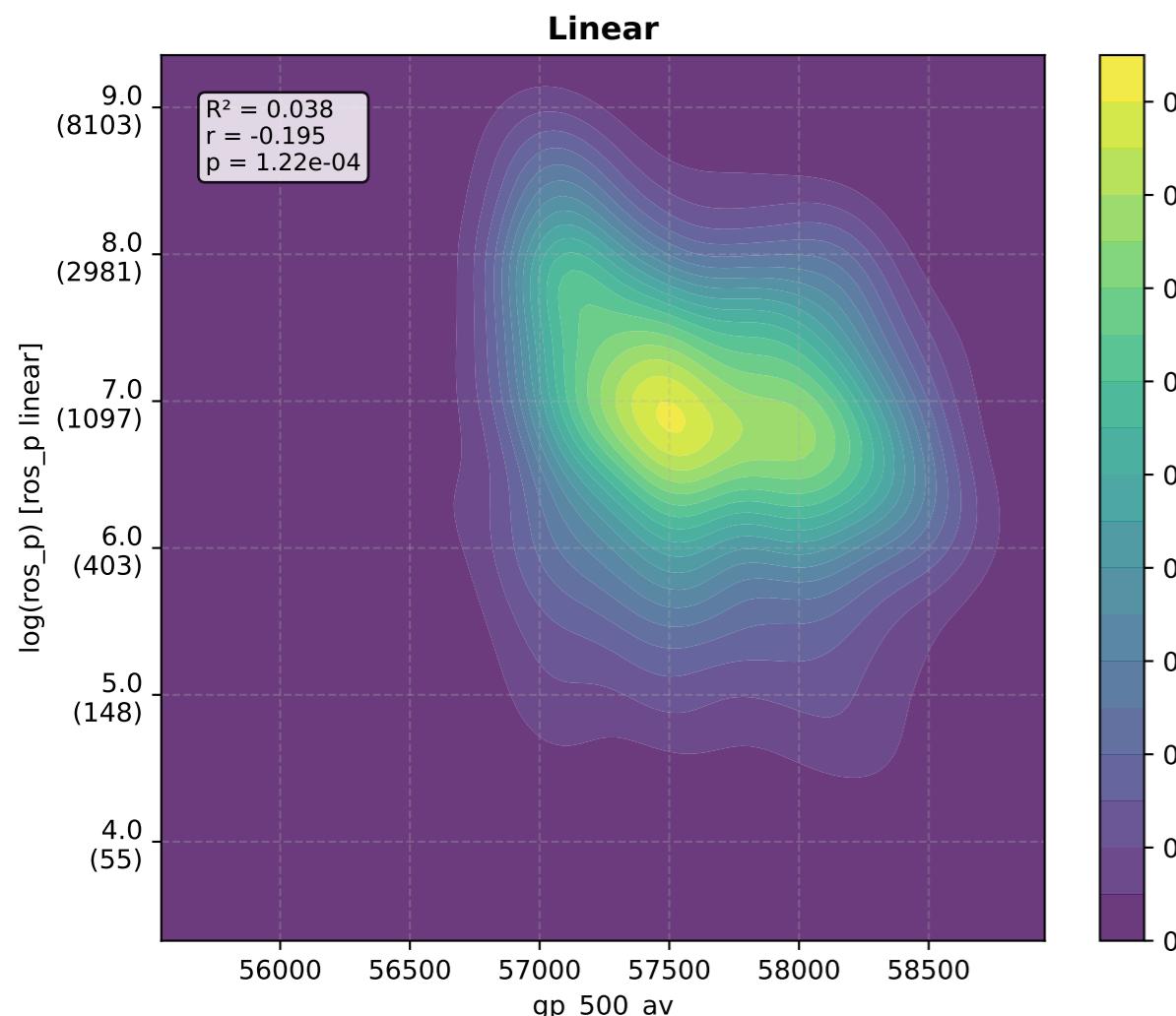
gp_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



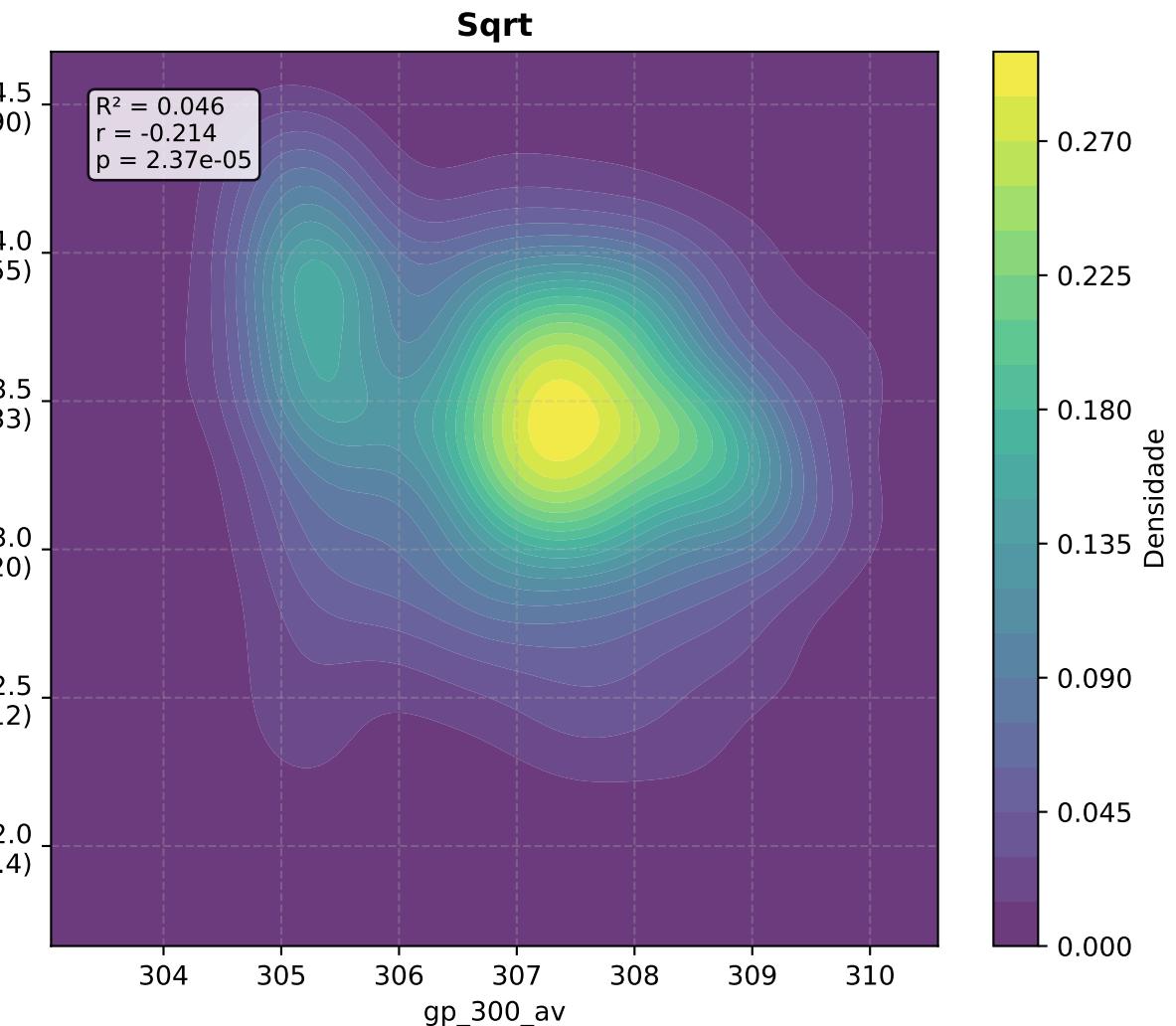
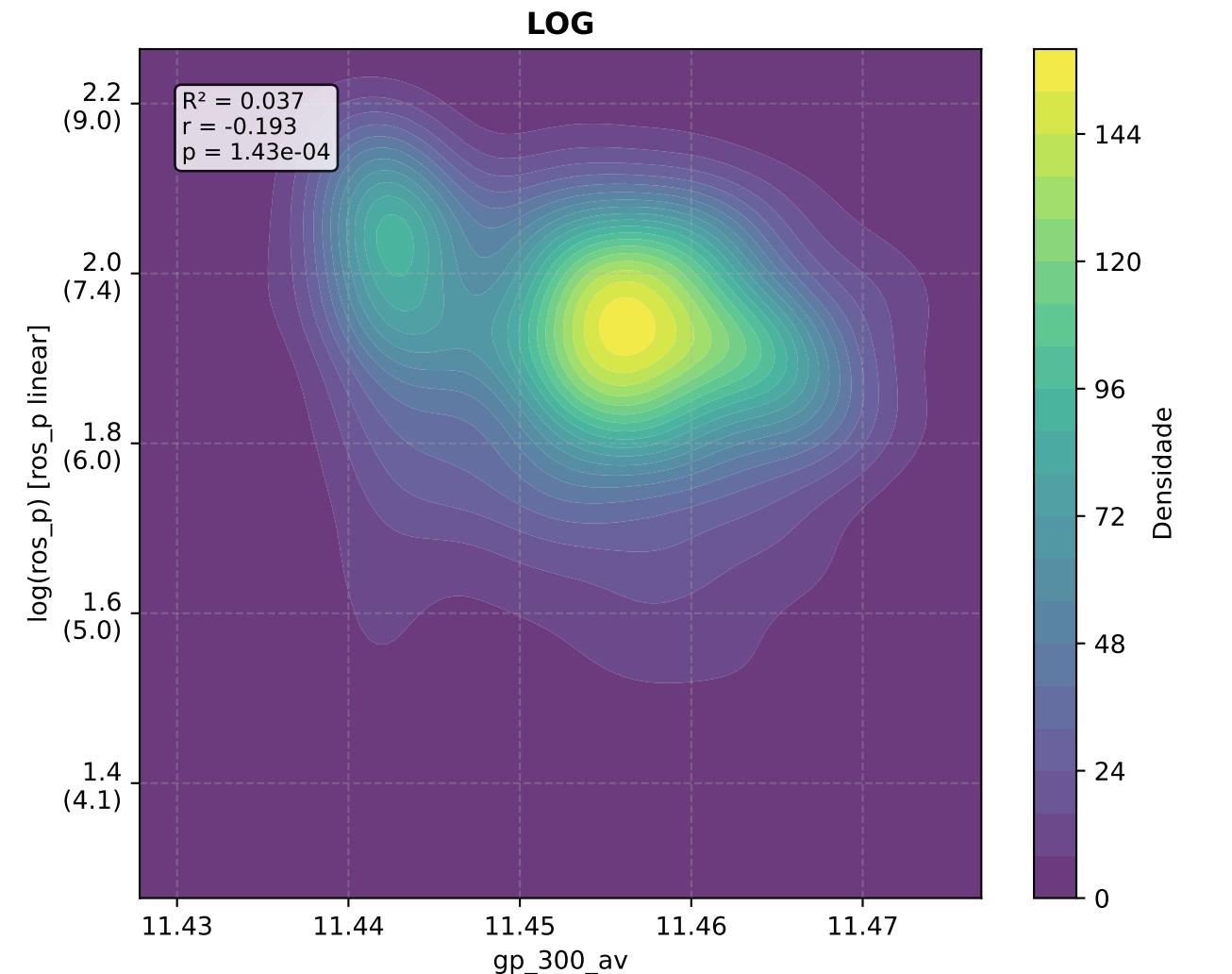
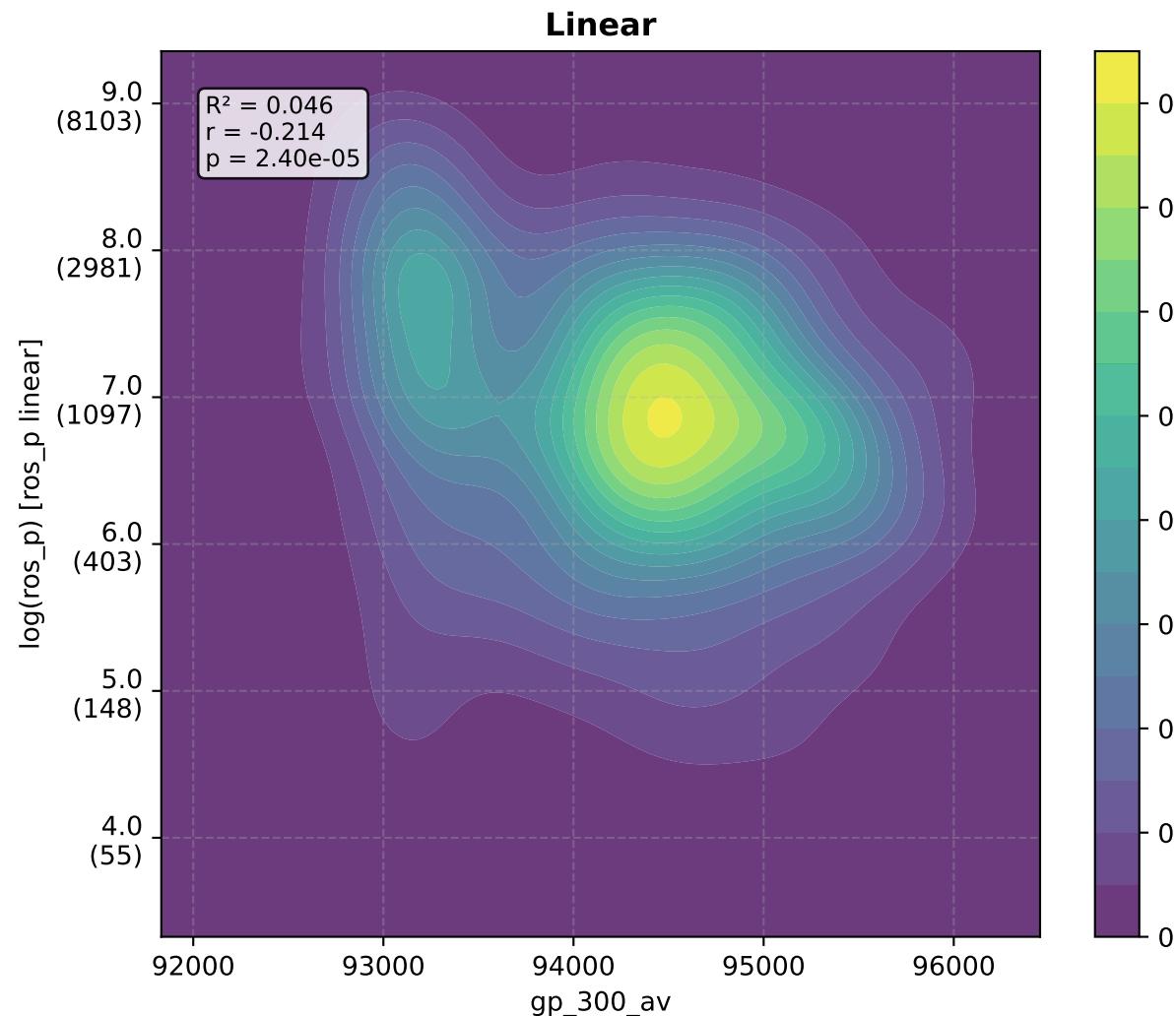
gp_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



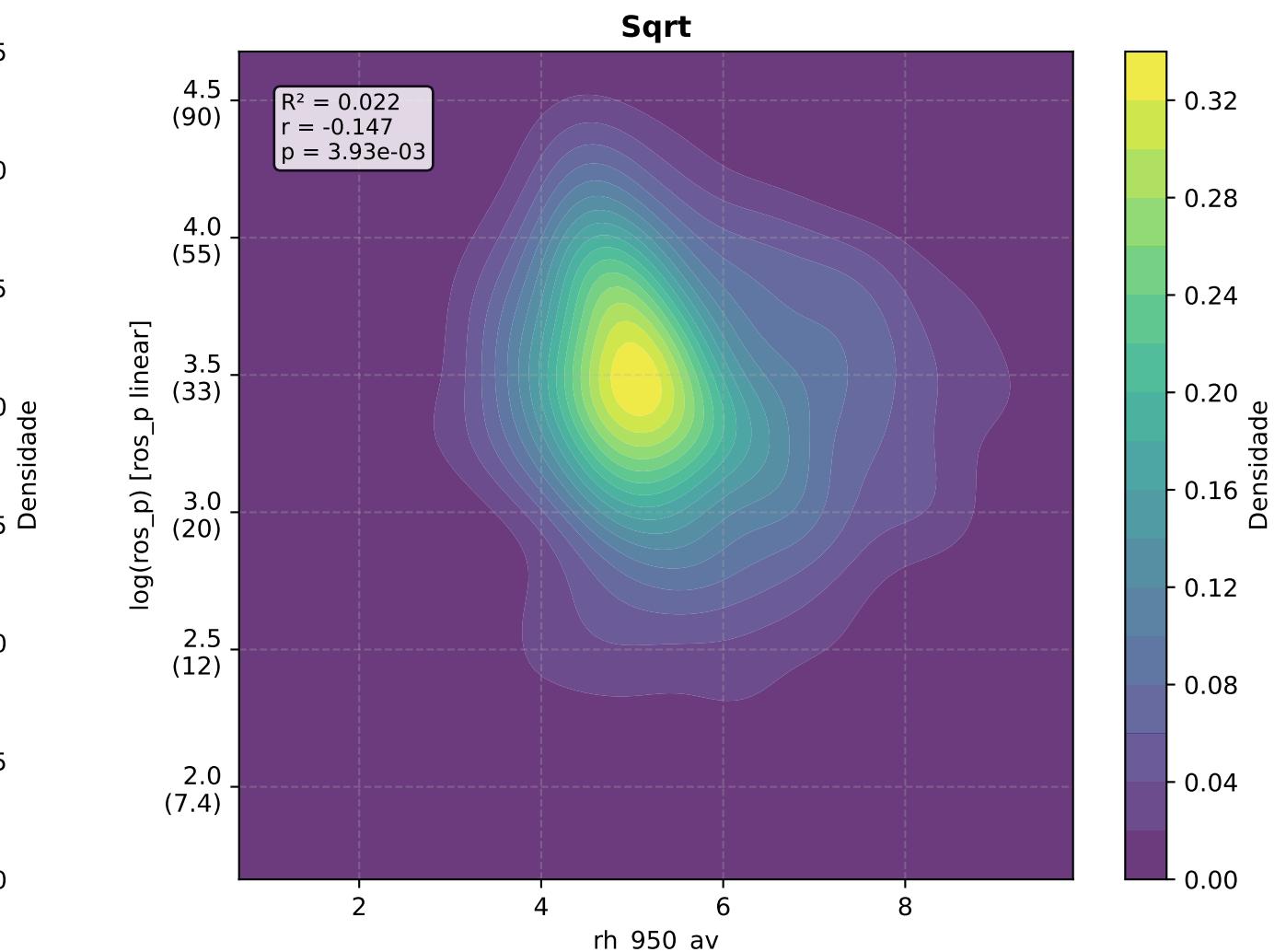
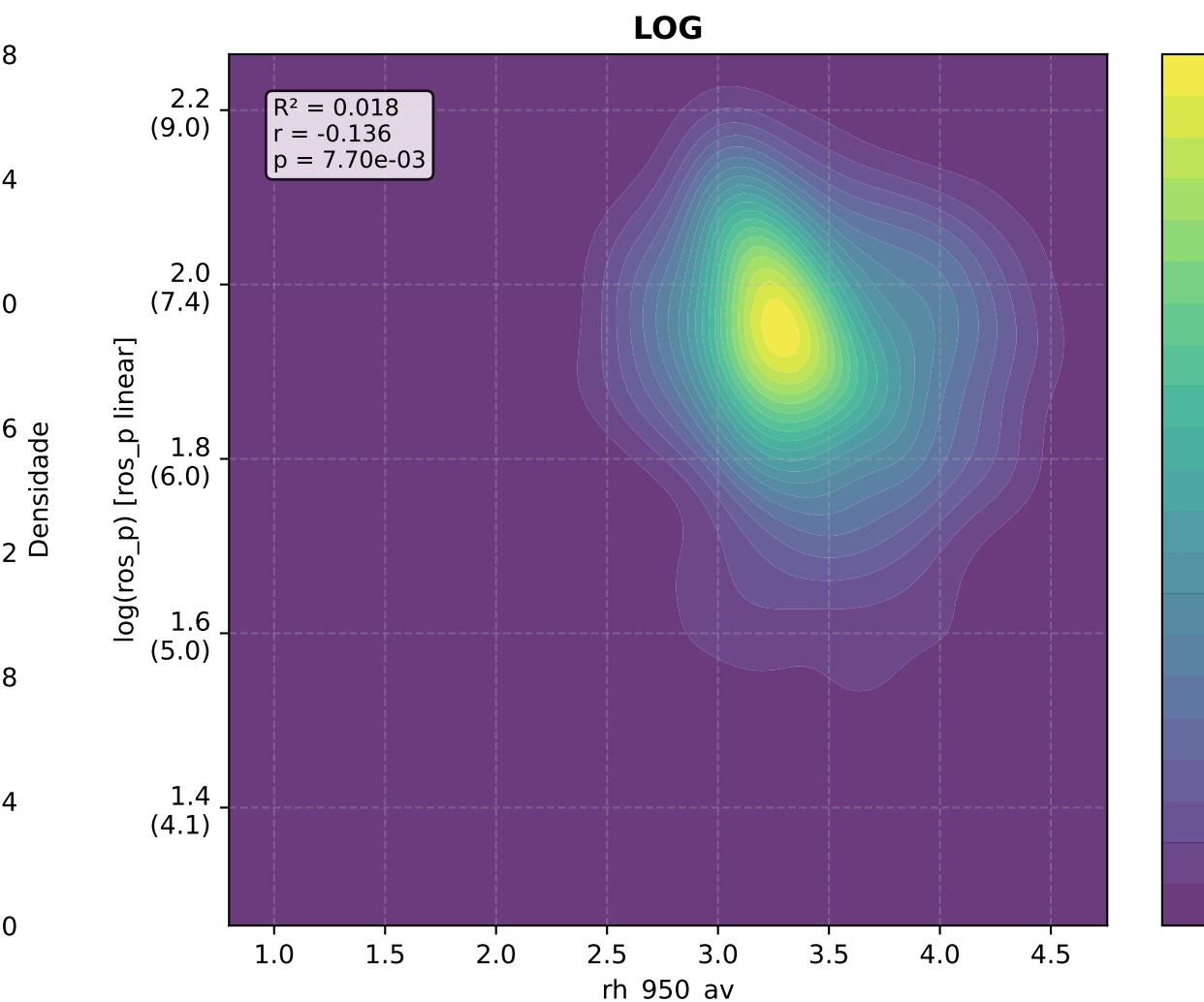
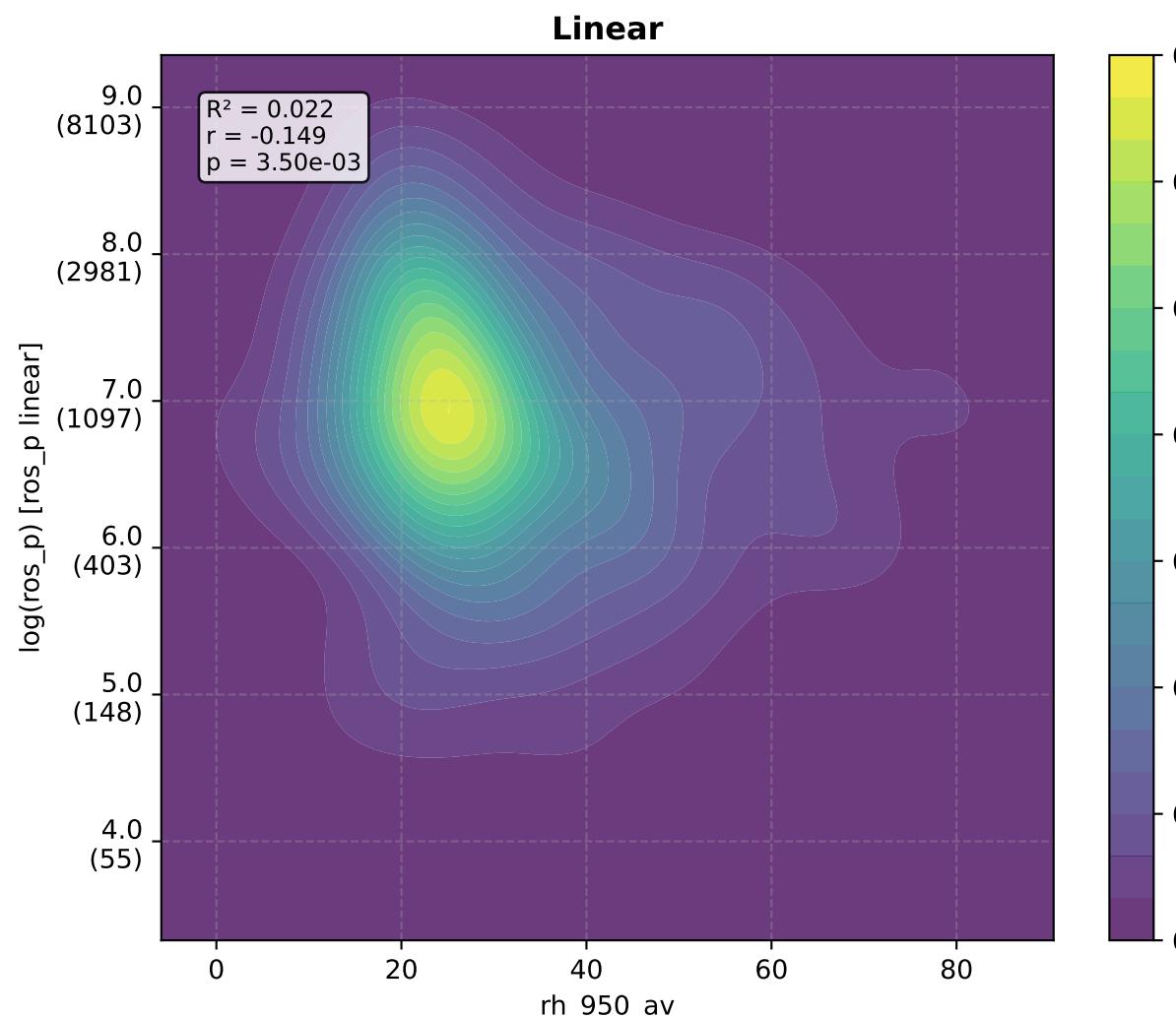
gp_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



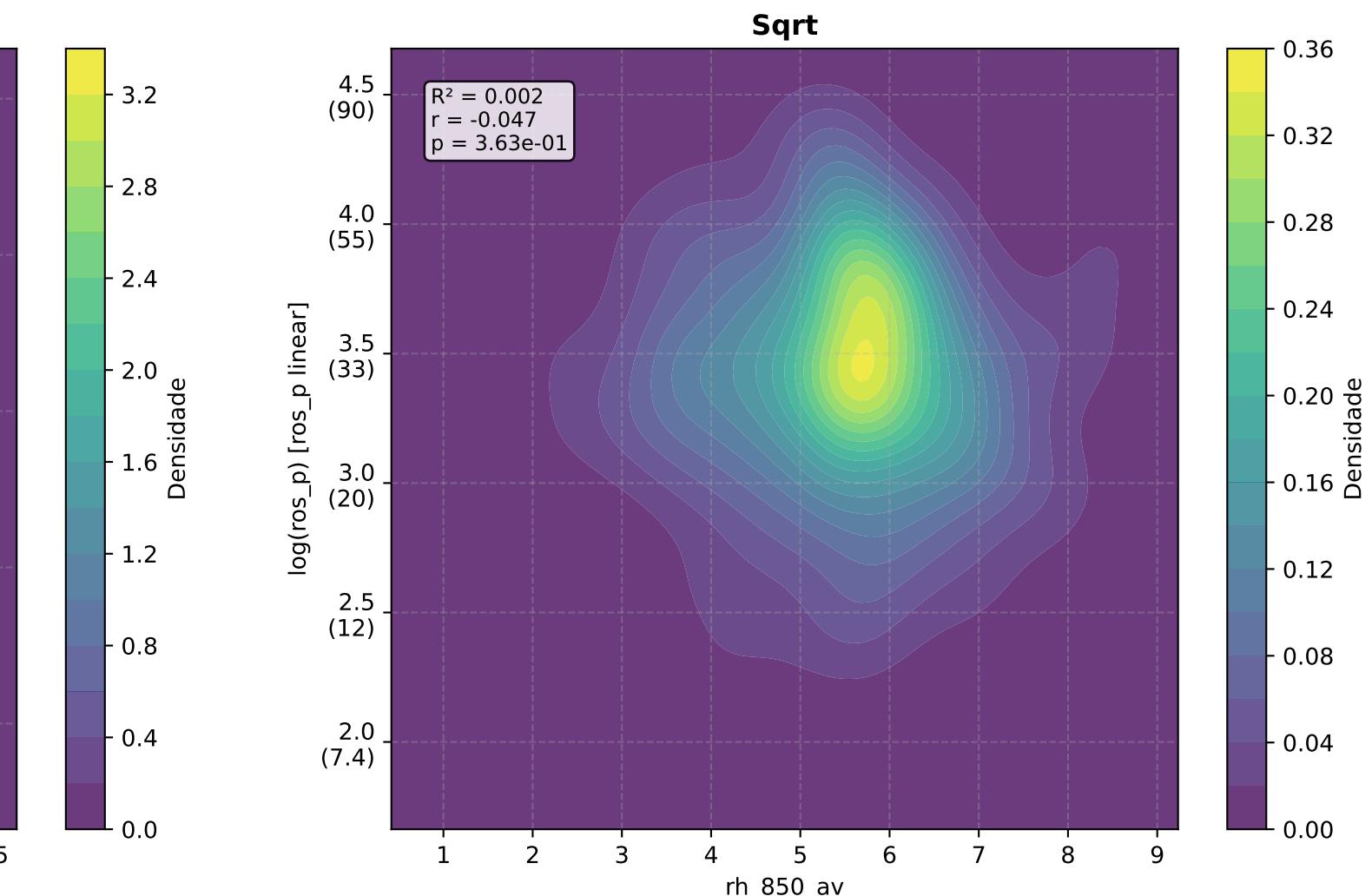
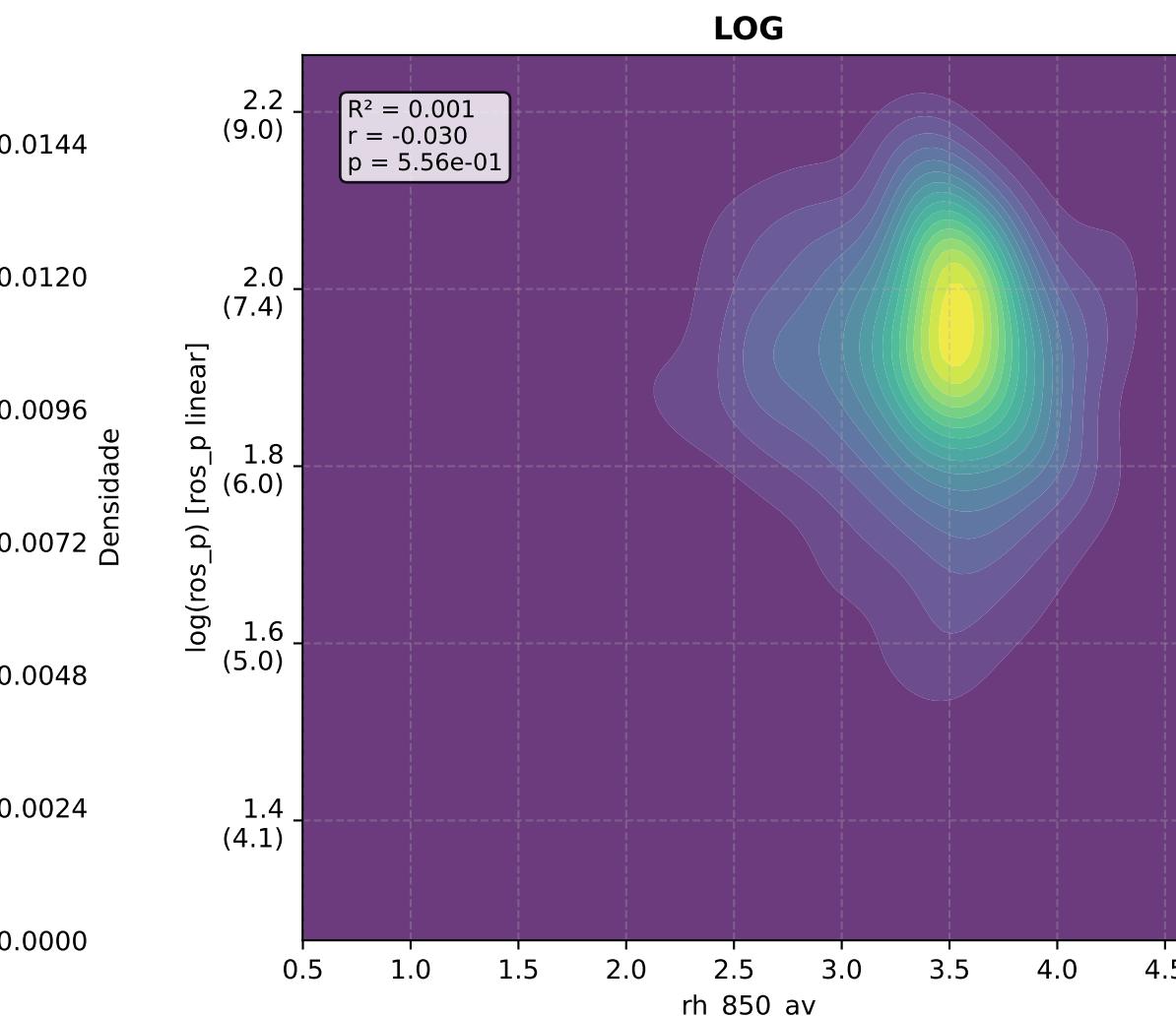
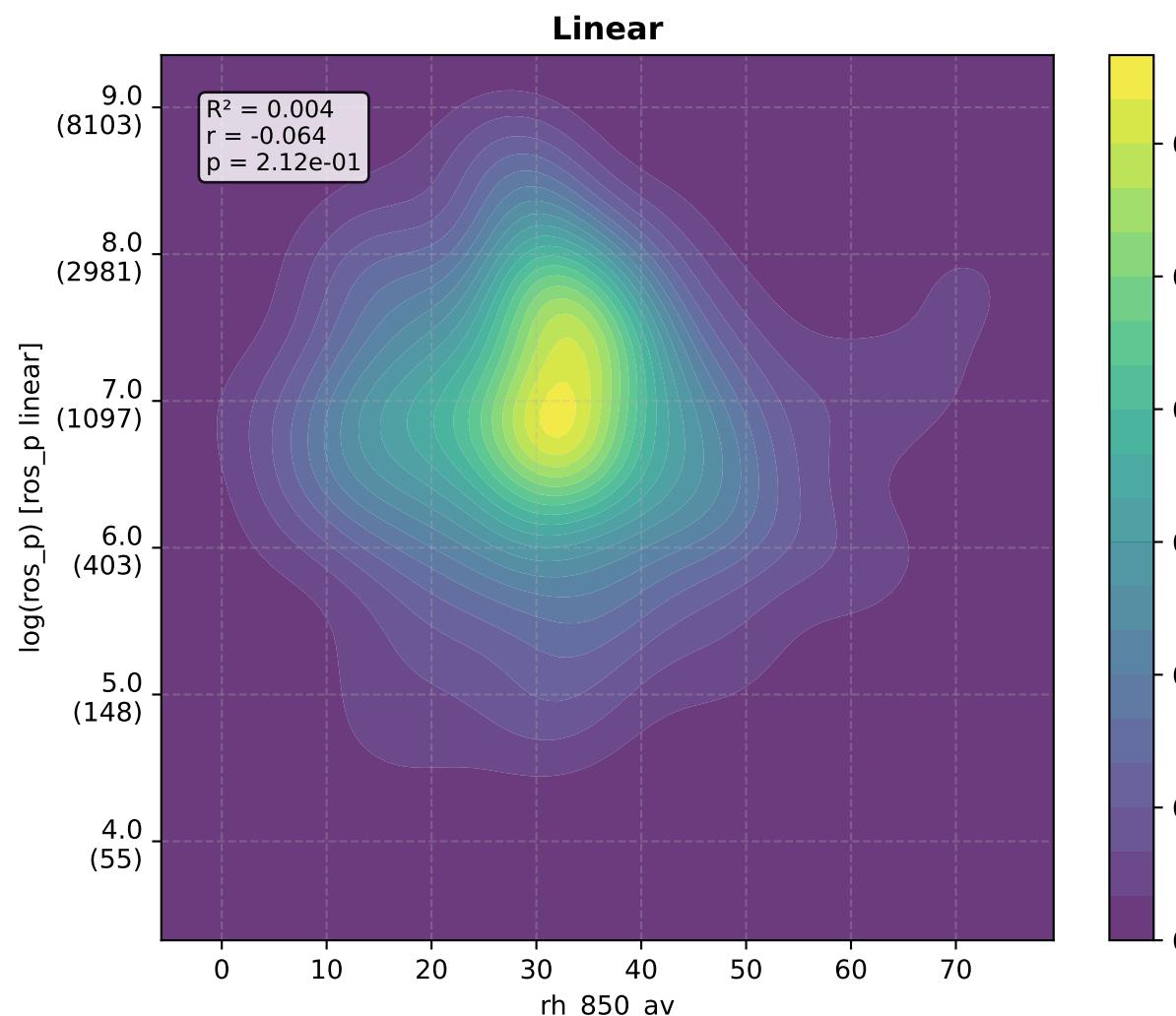
gp_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



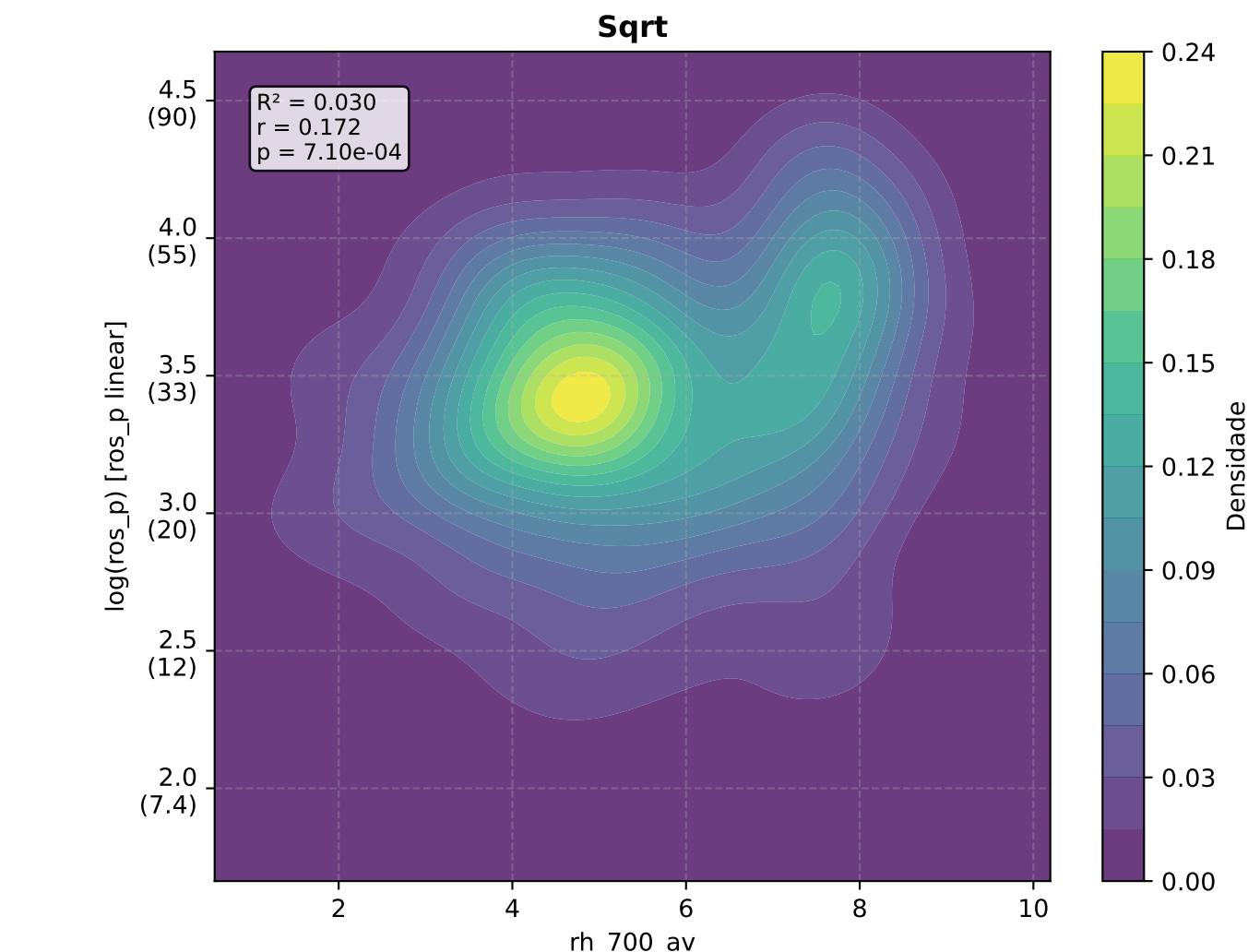
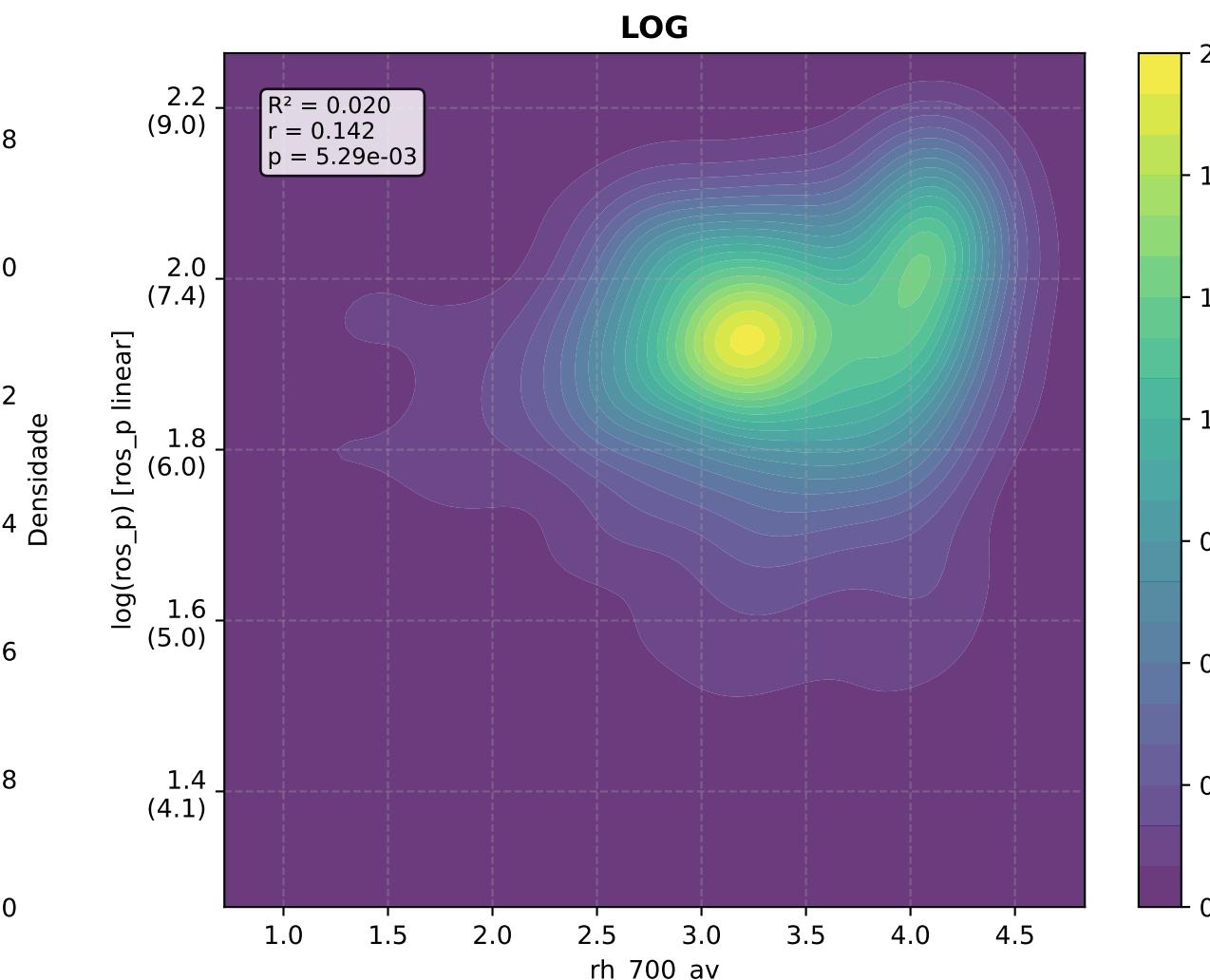
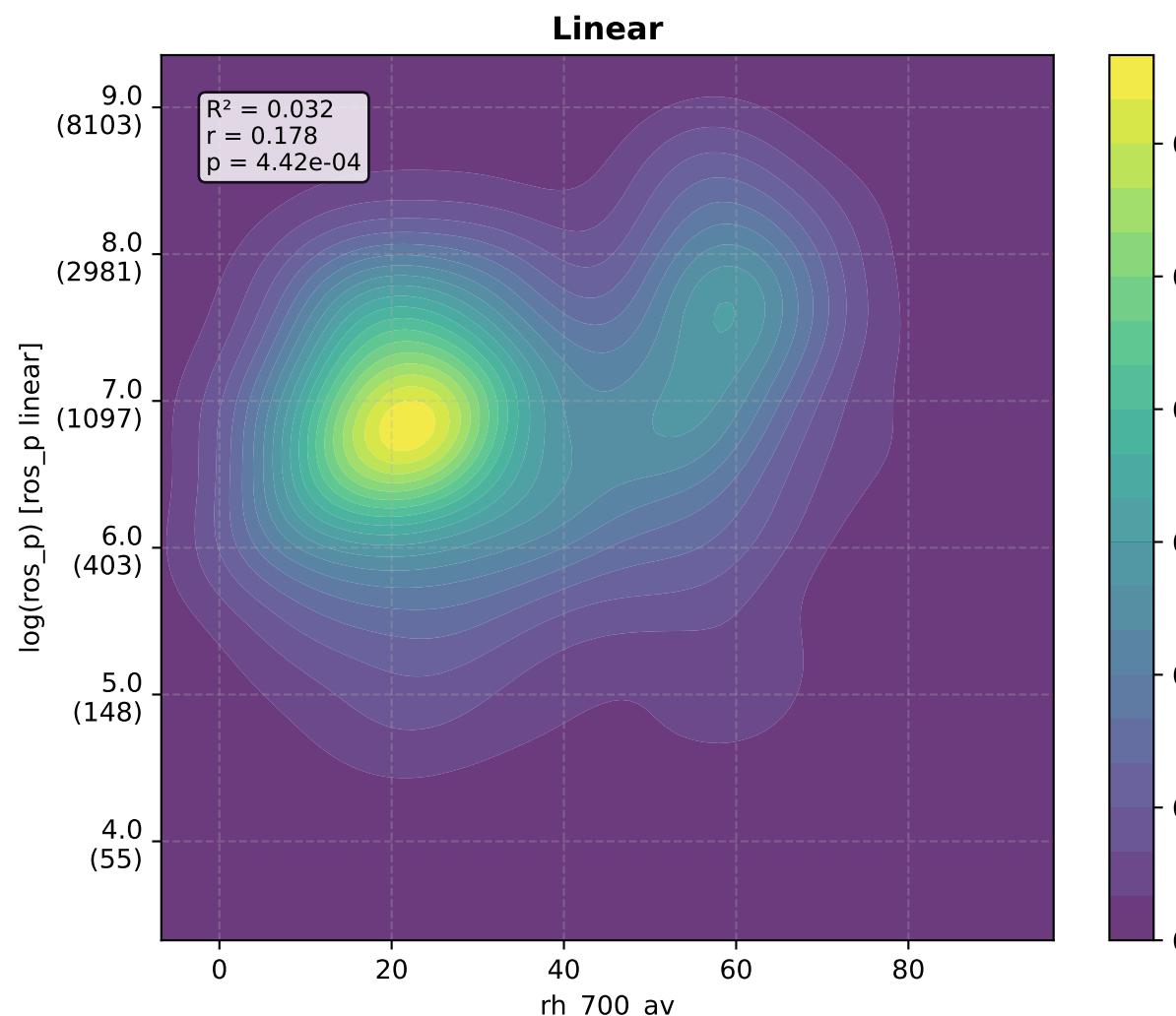
rh_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



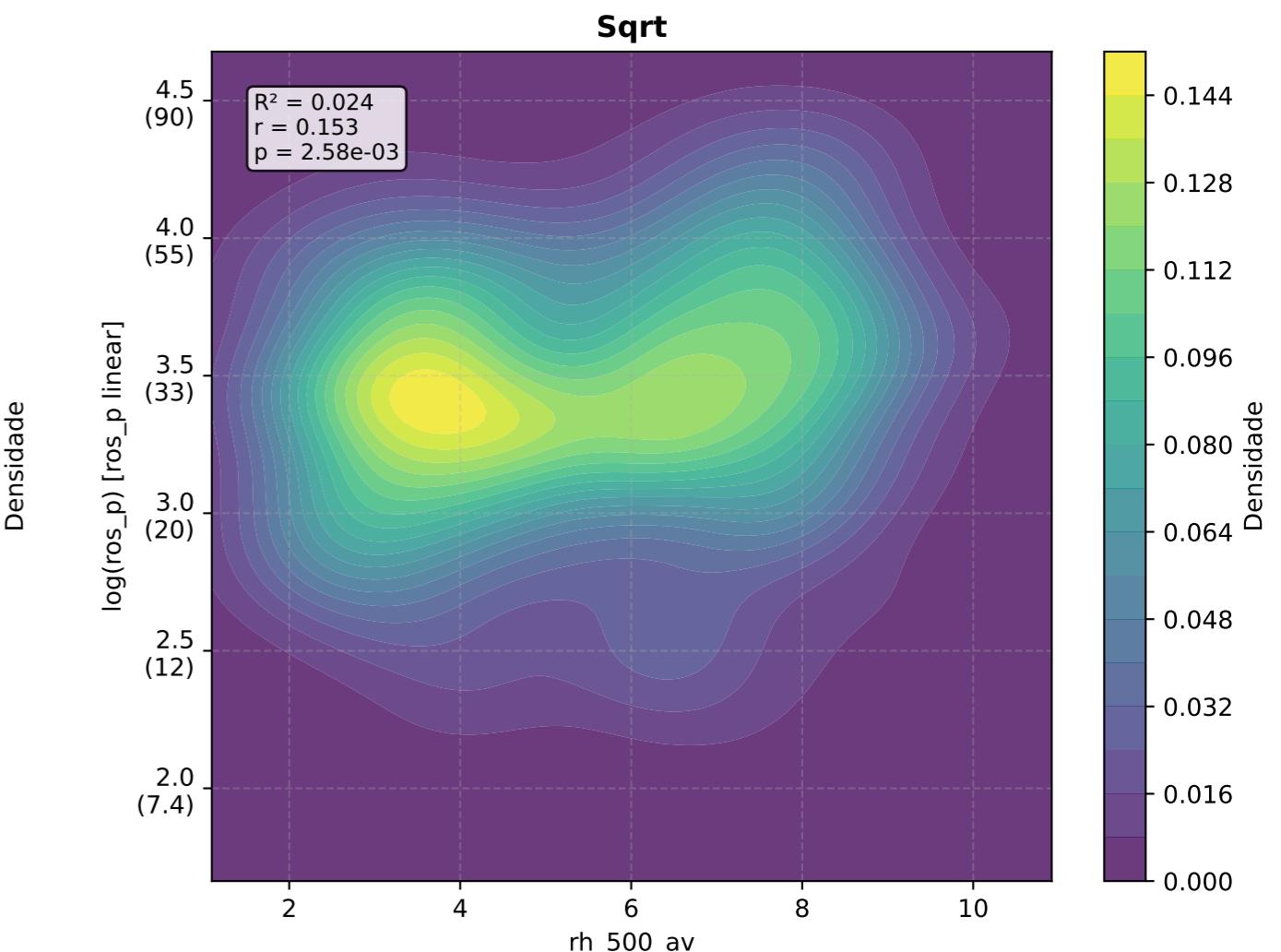
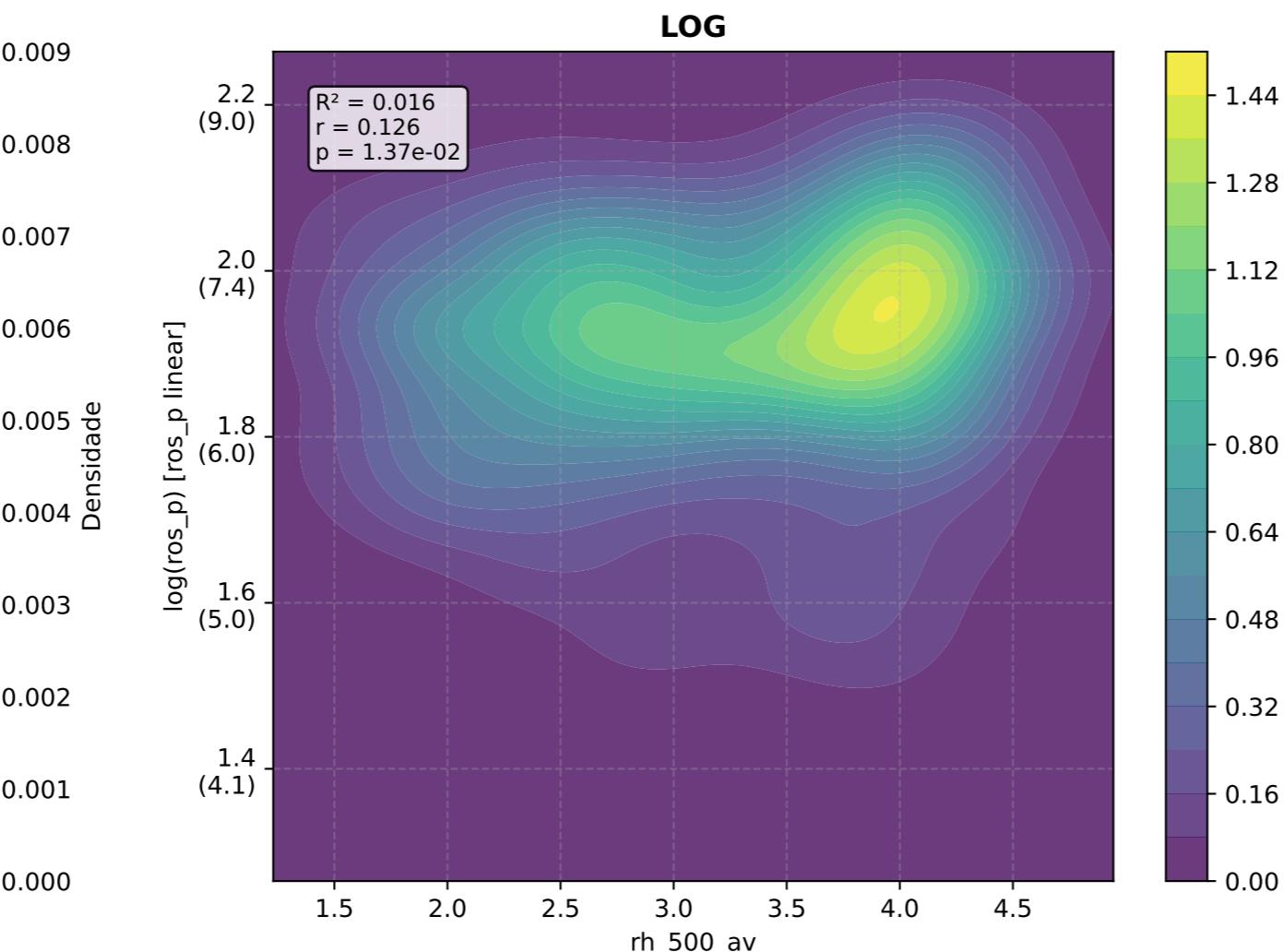
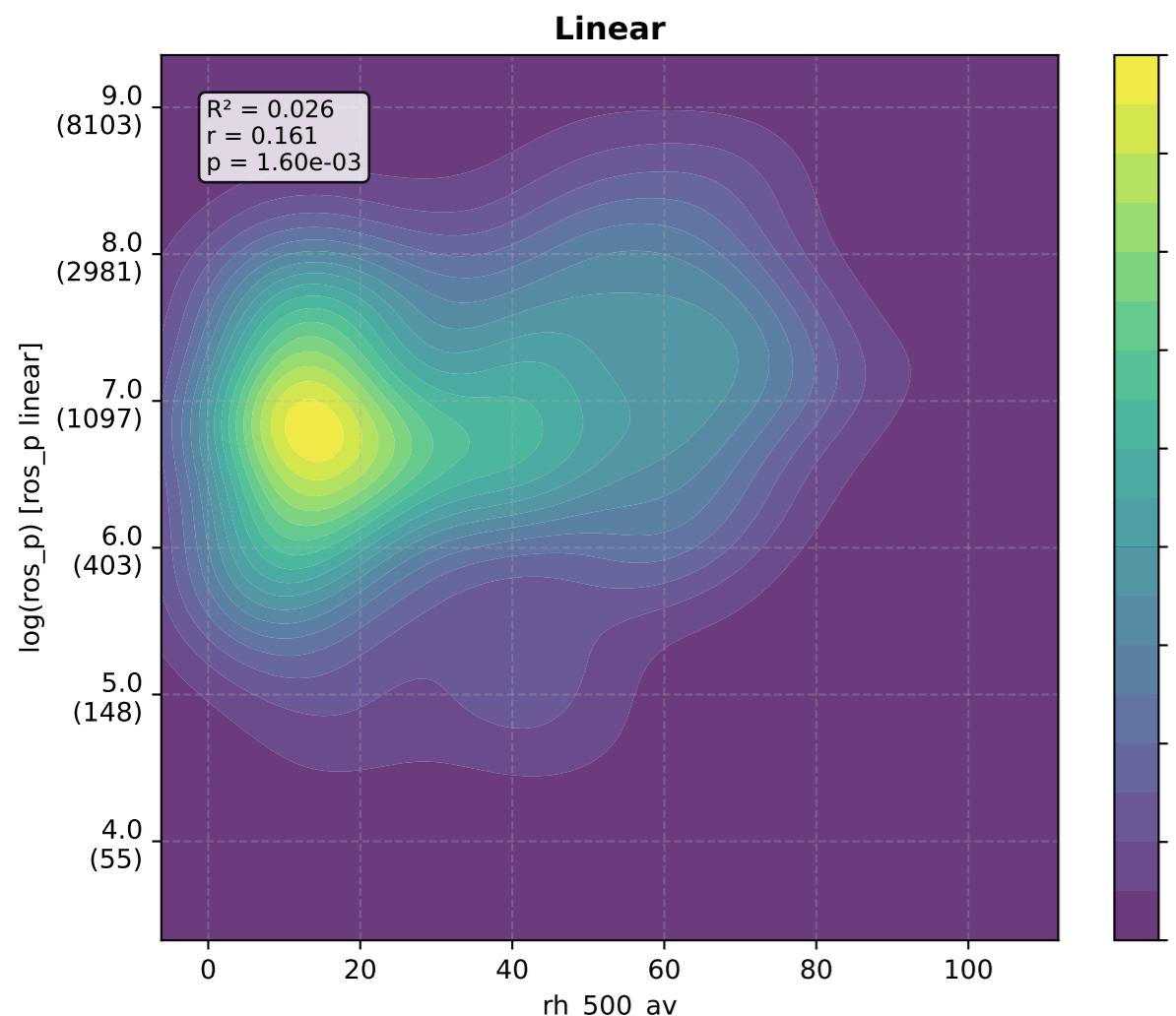
rh_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



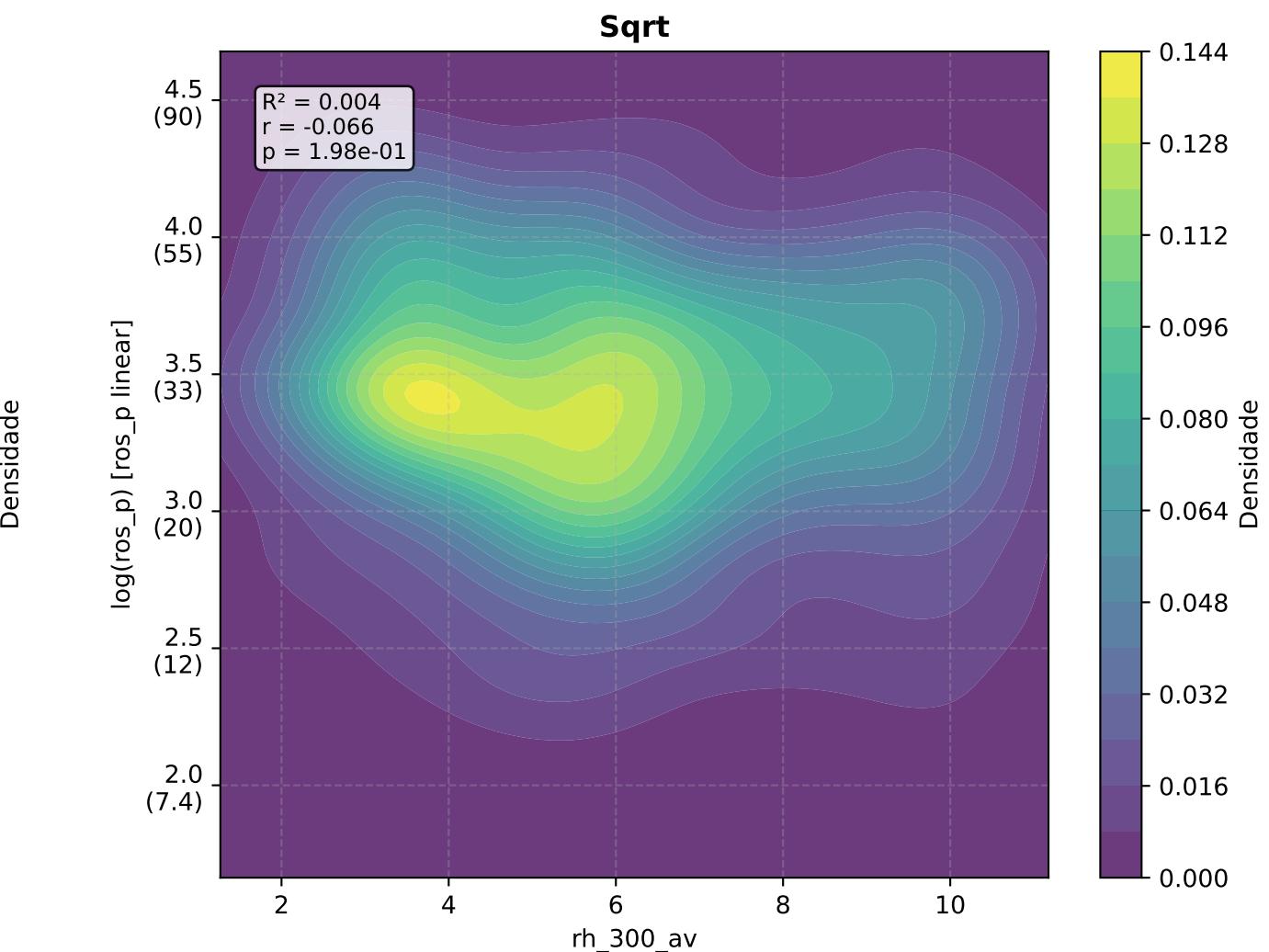
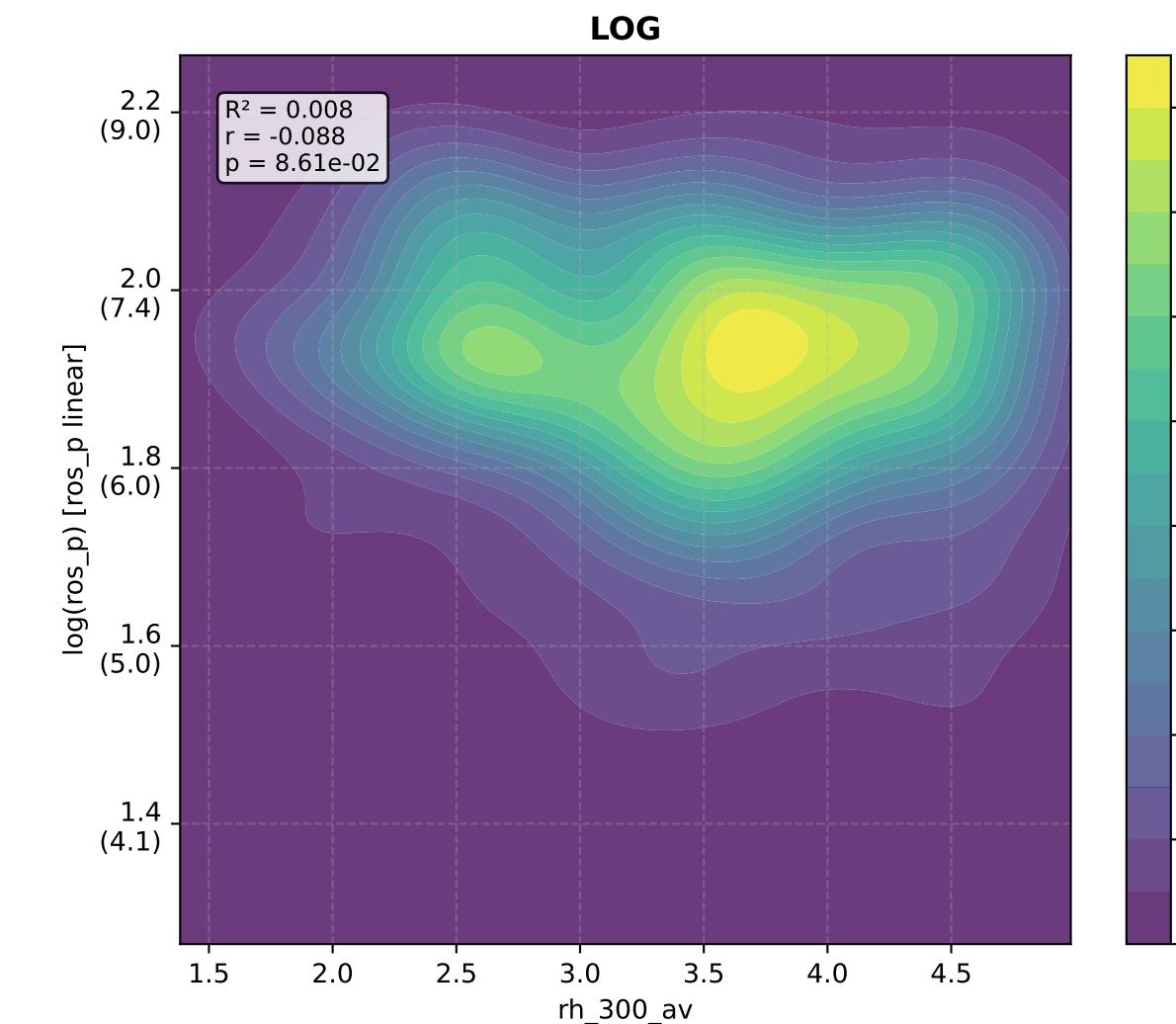
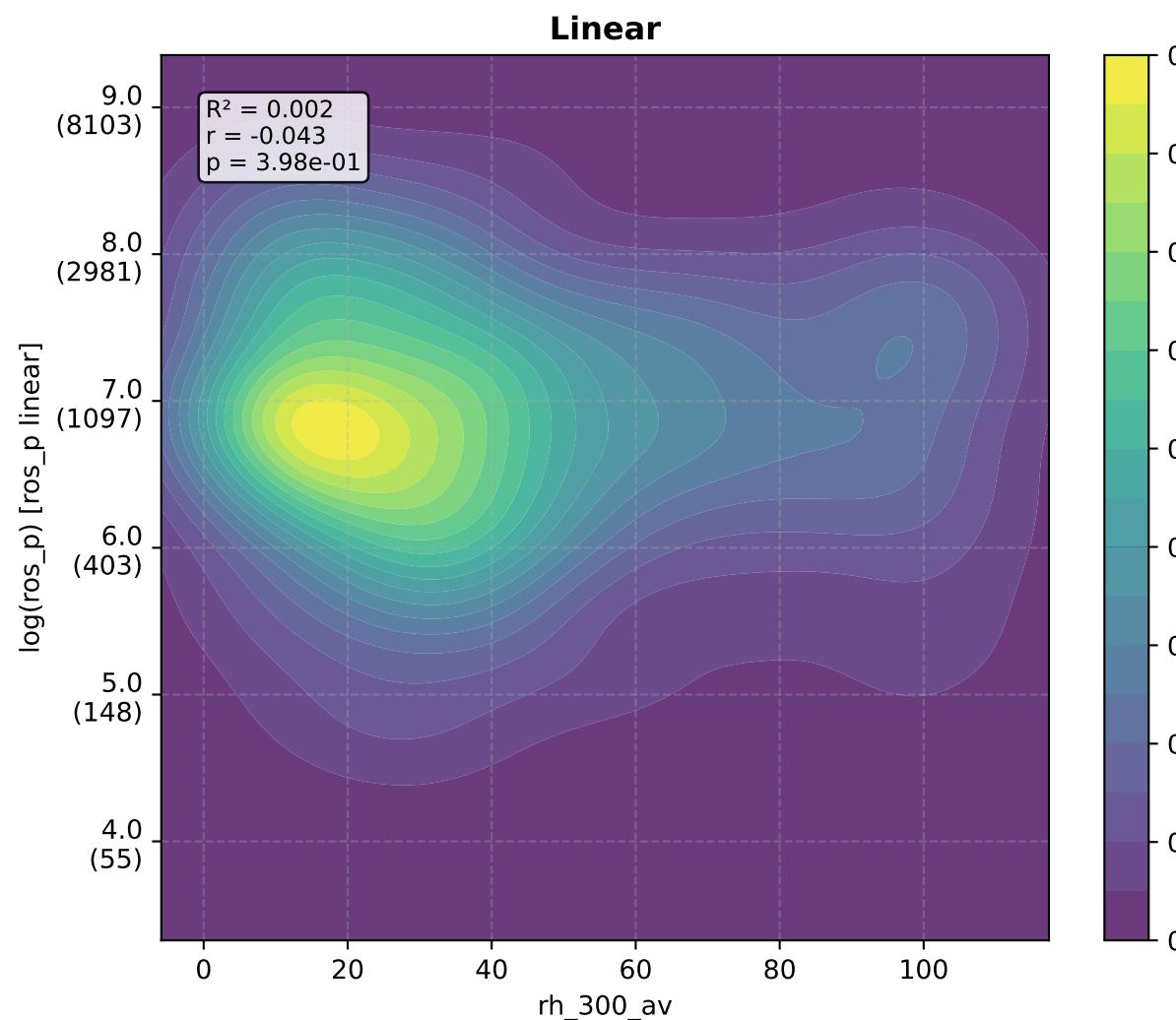
rh_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



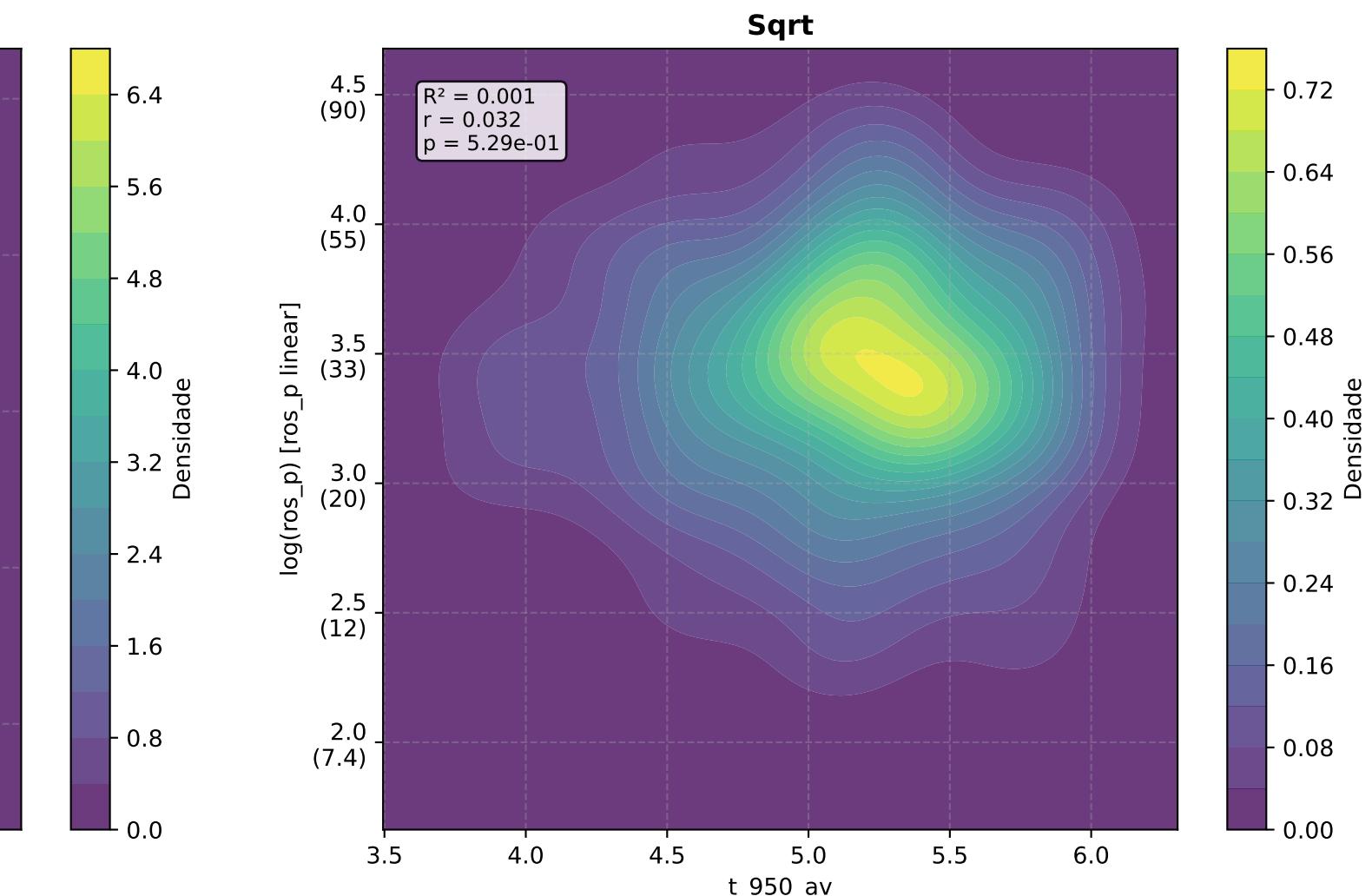
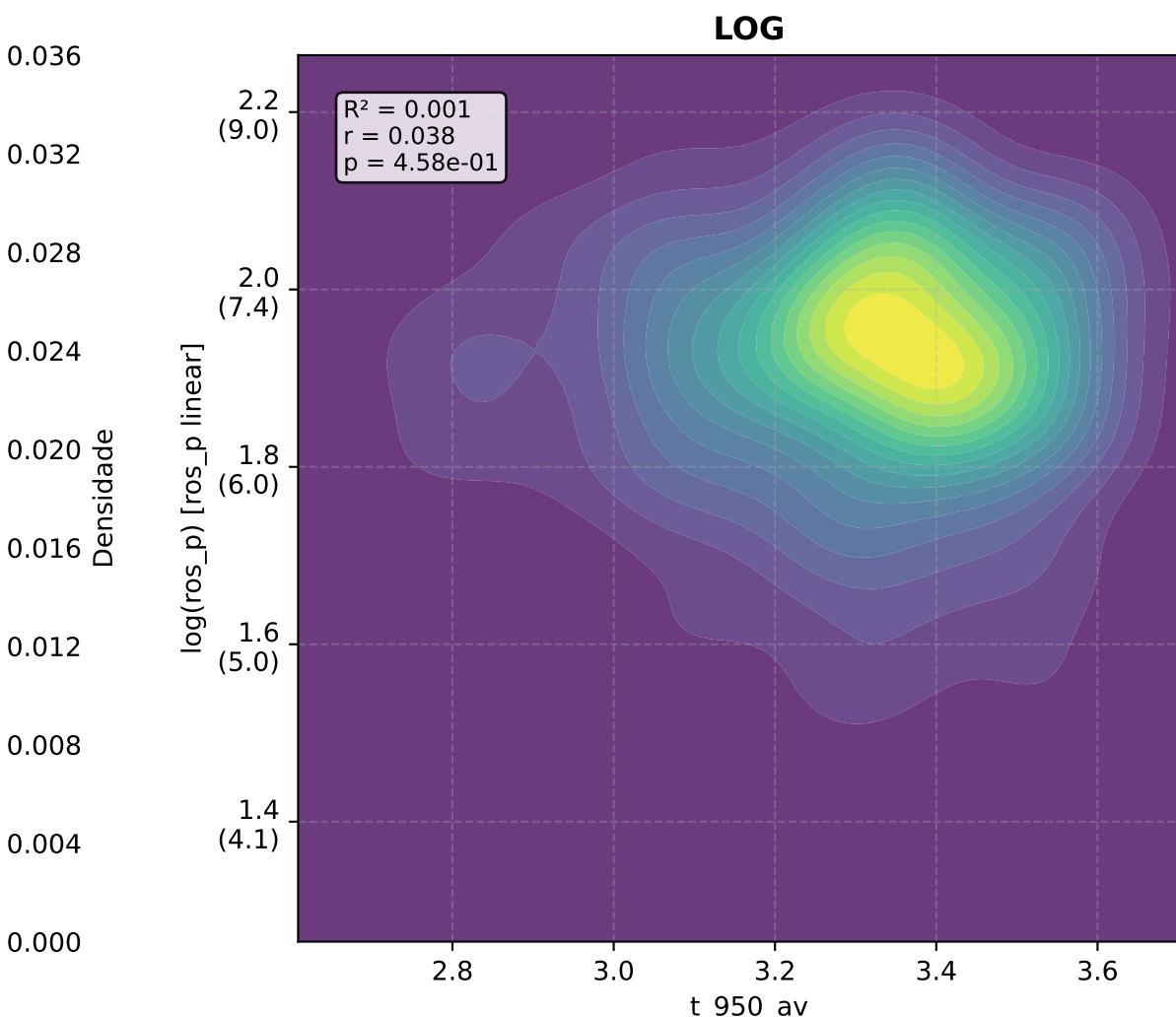
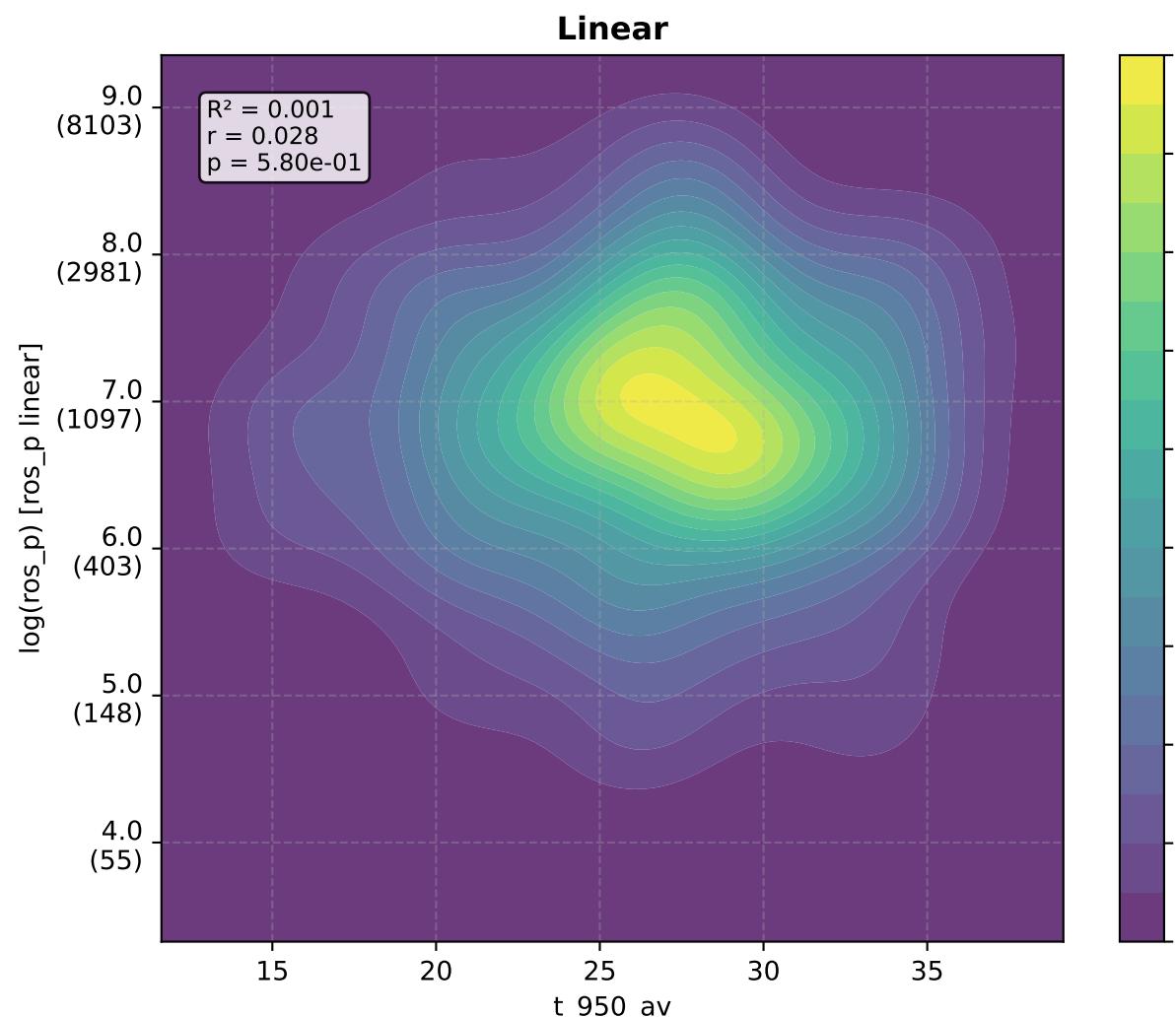
rh_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



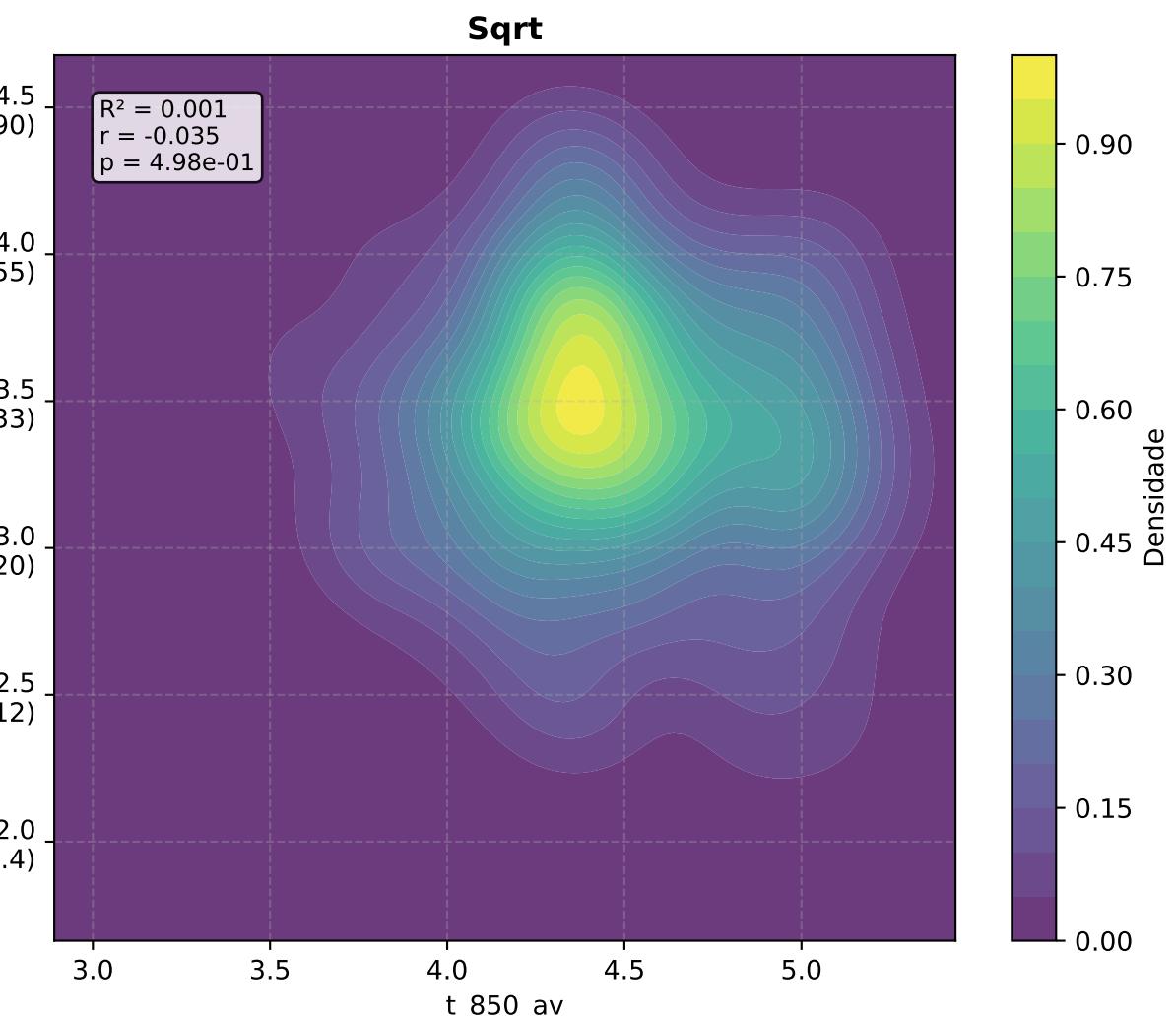
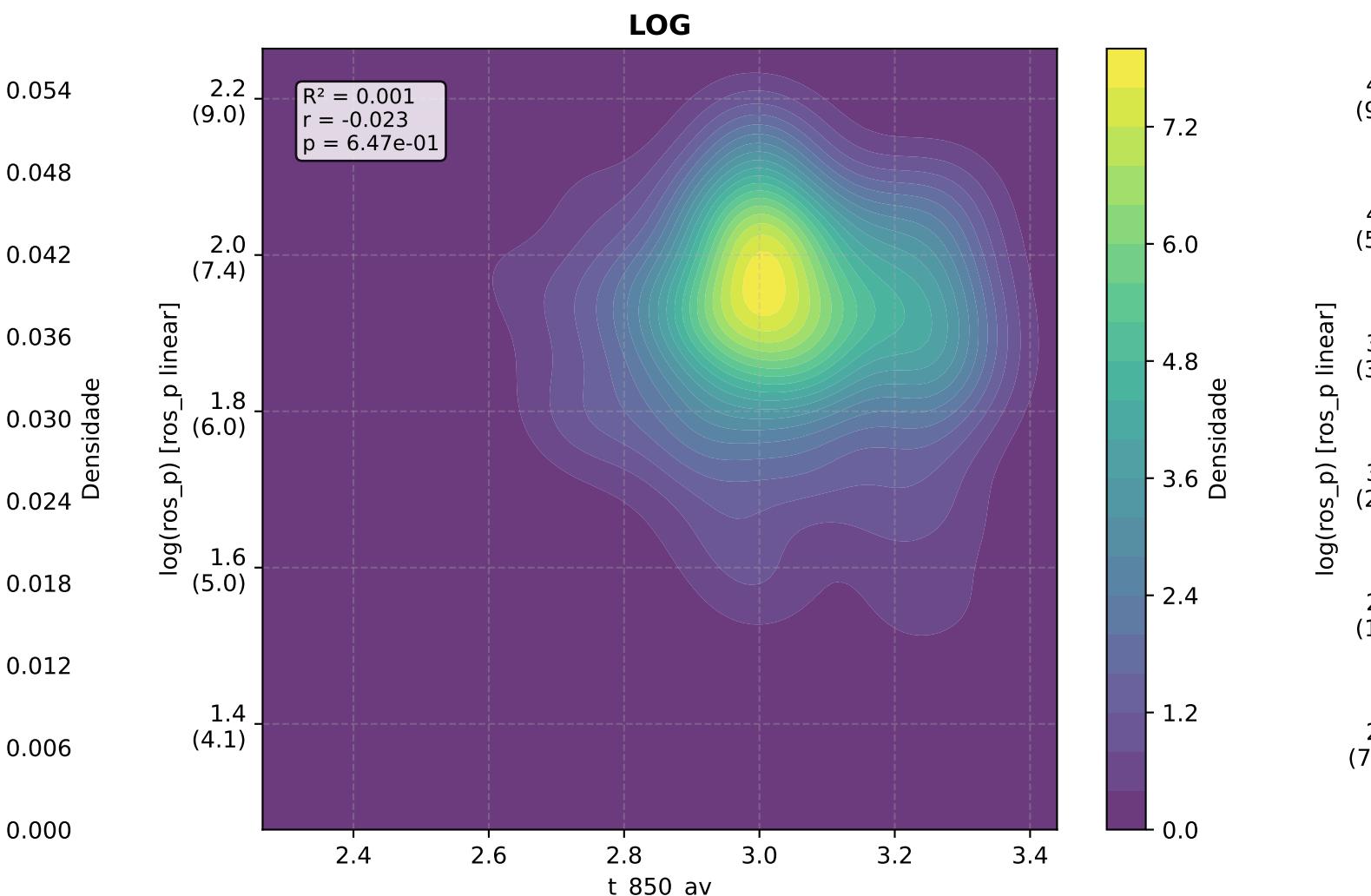
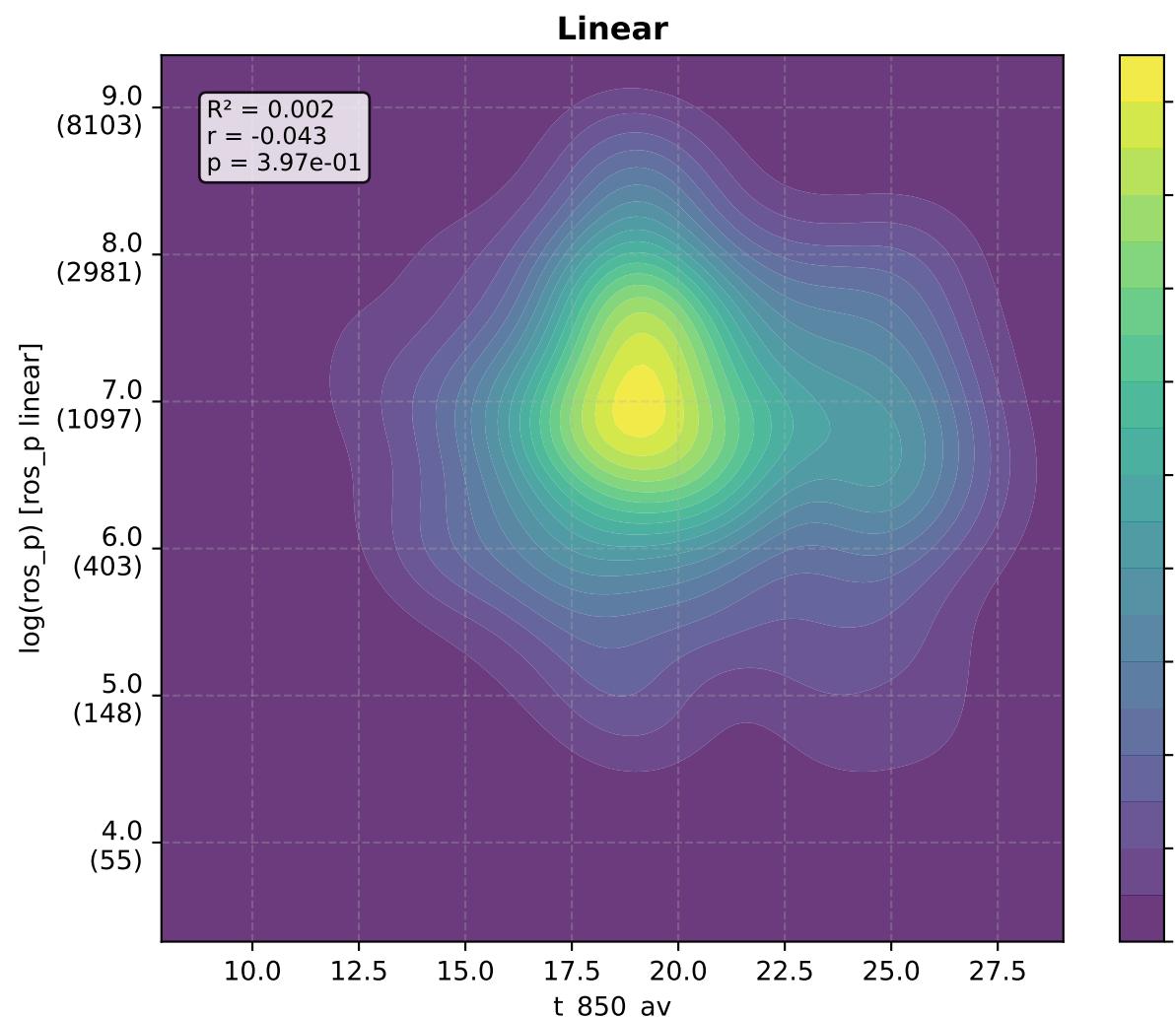
rh_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



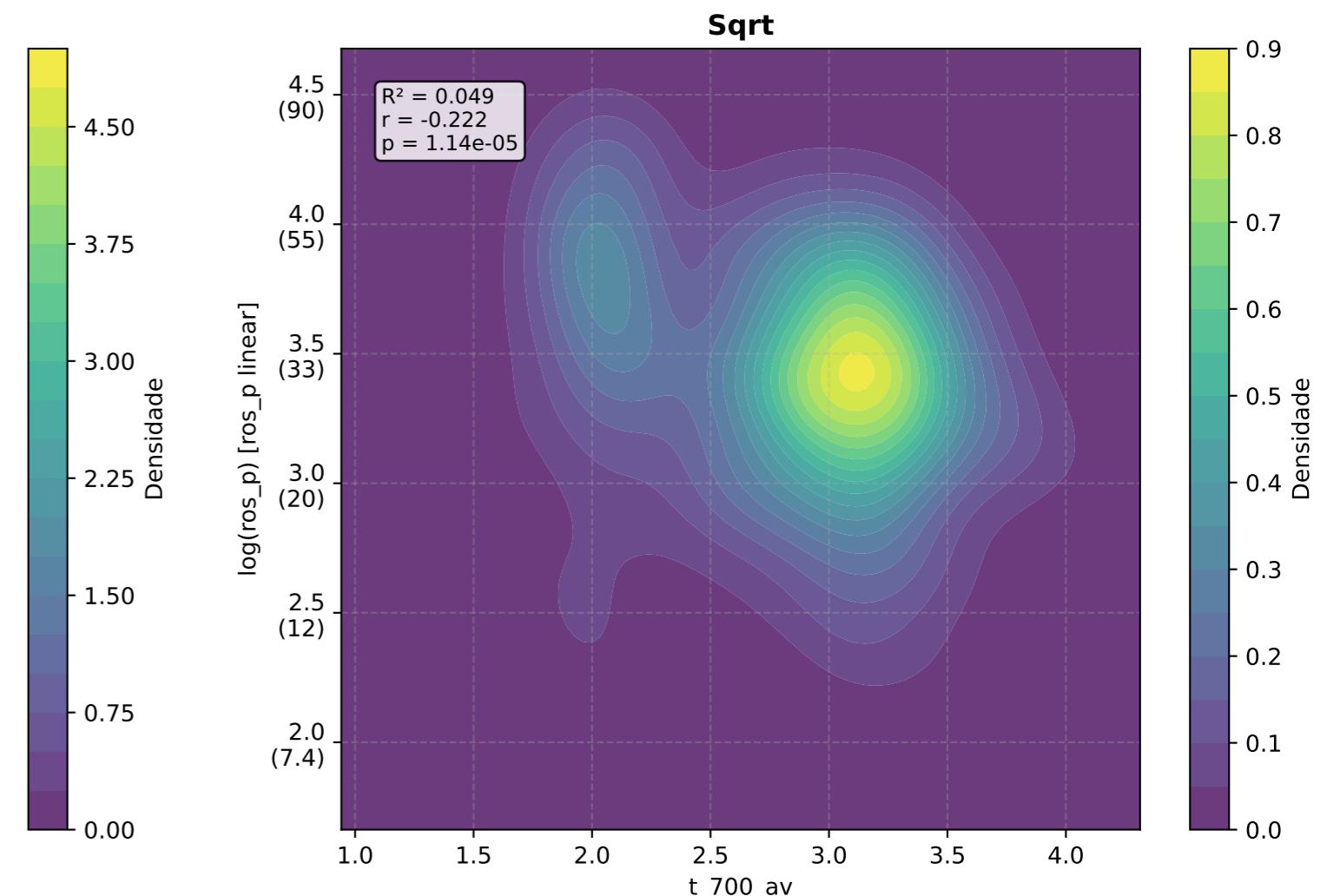
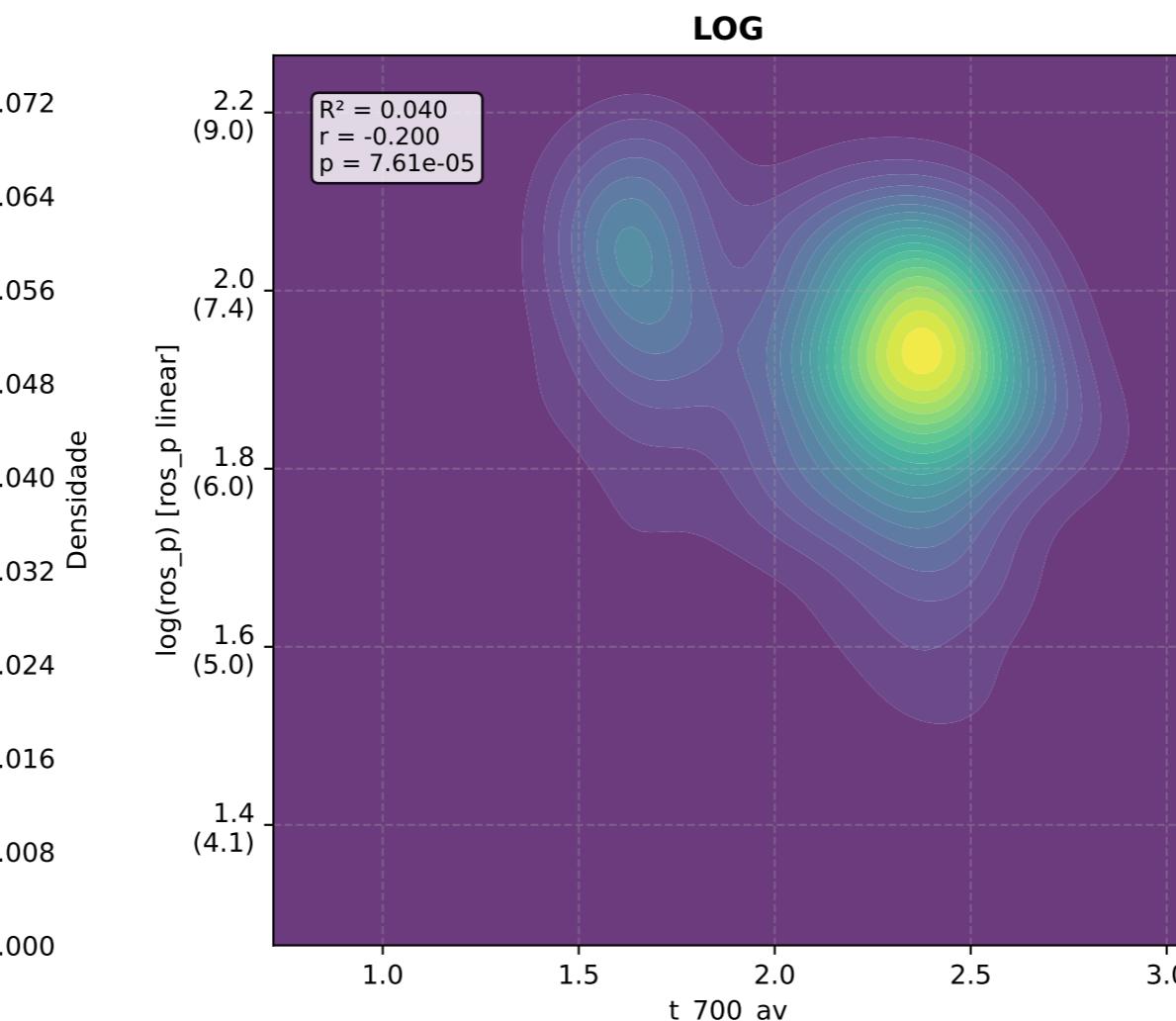
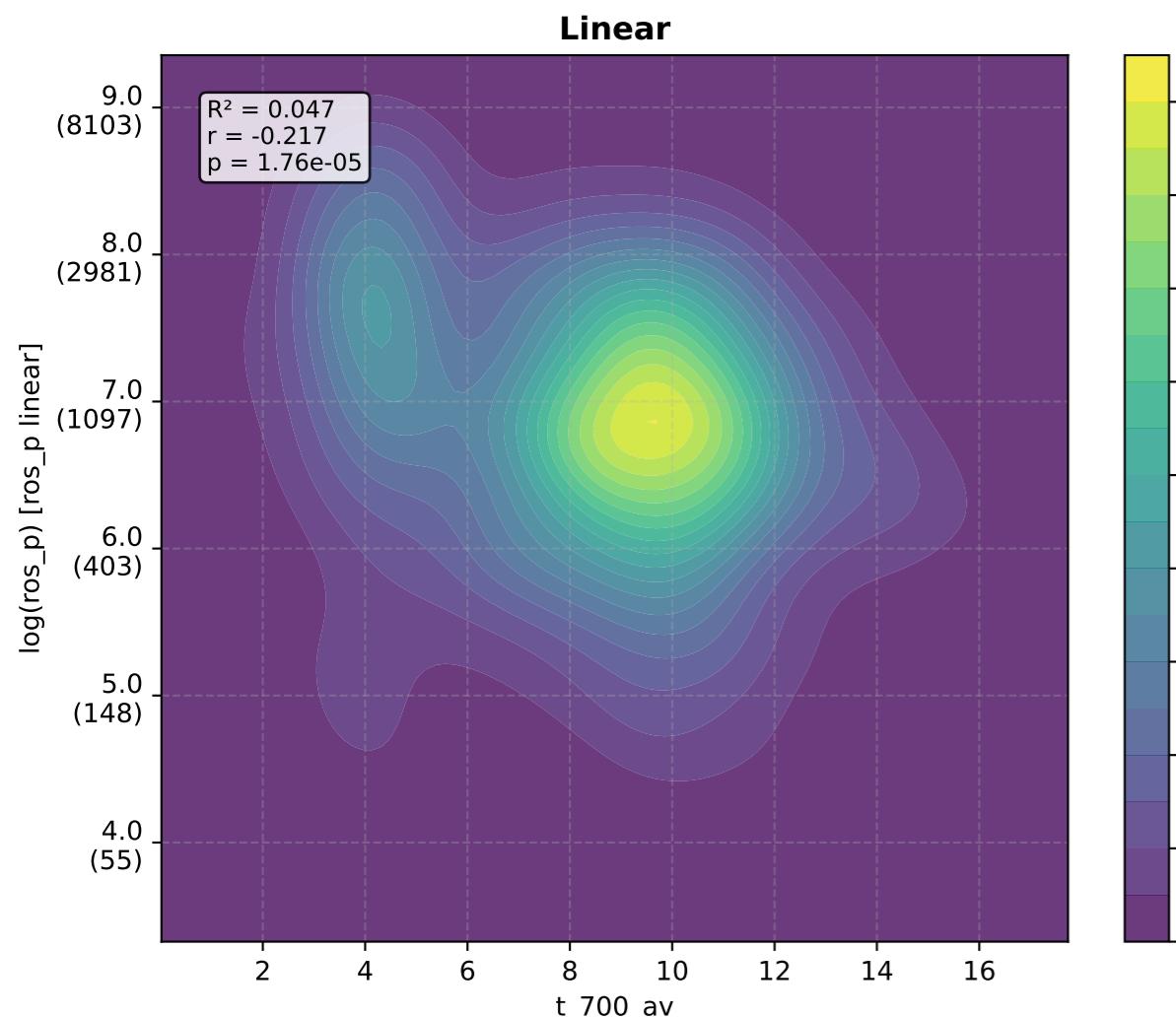
t_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



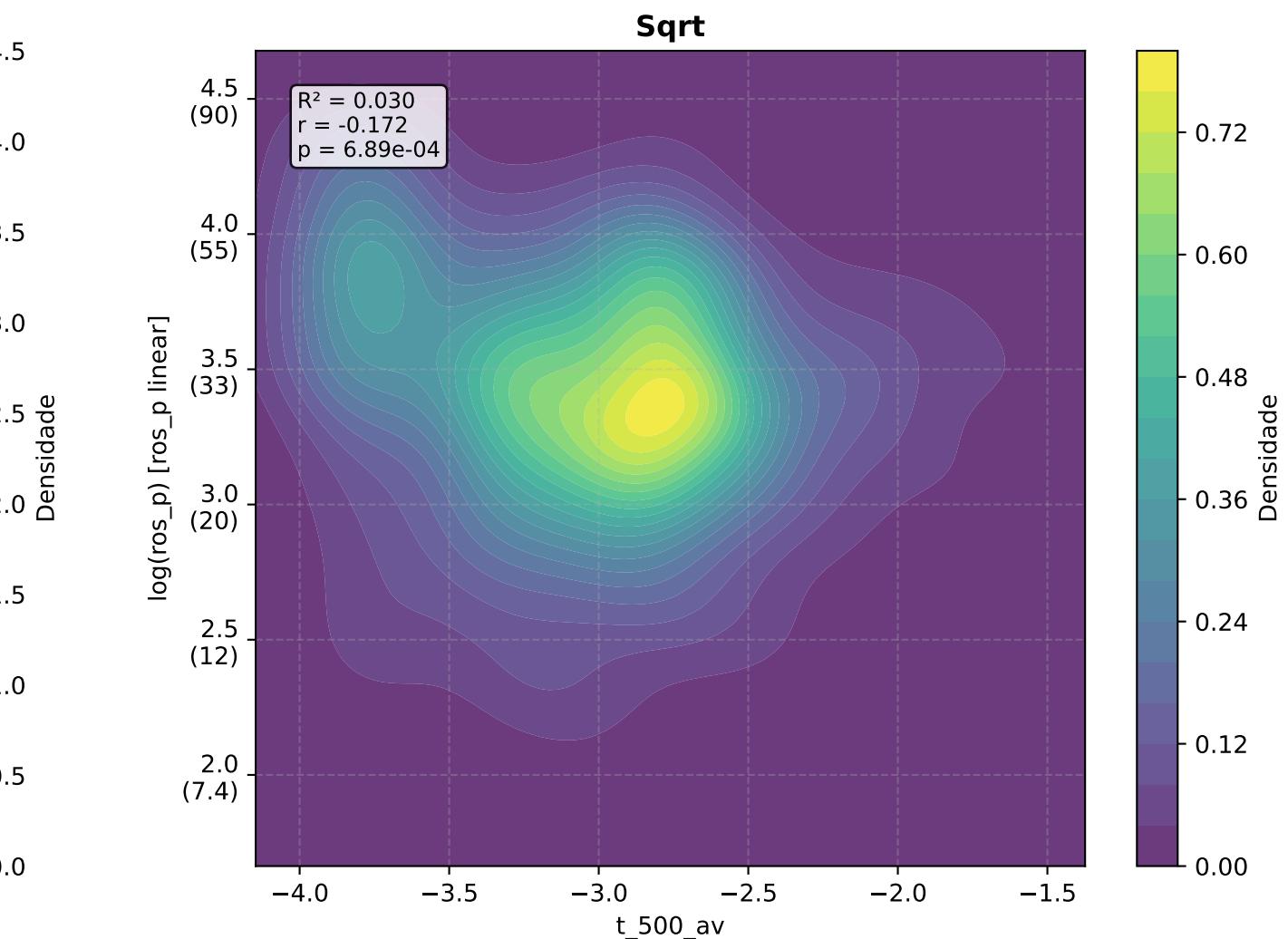
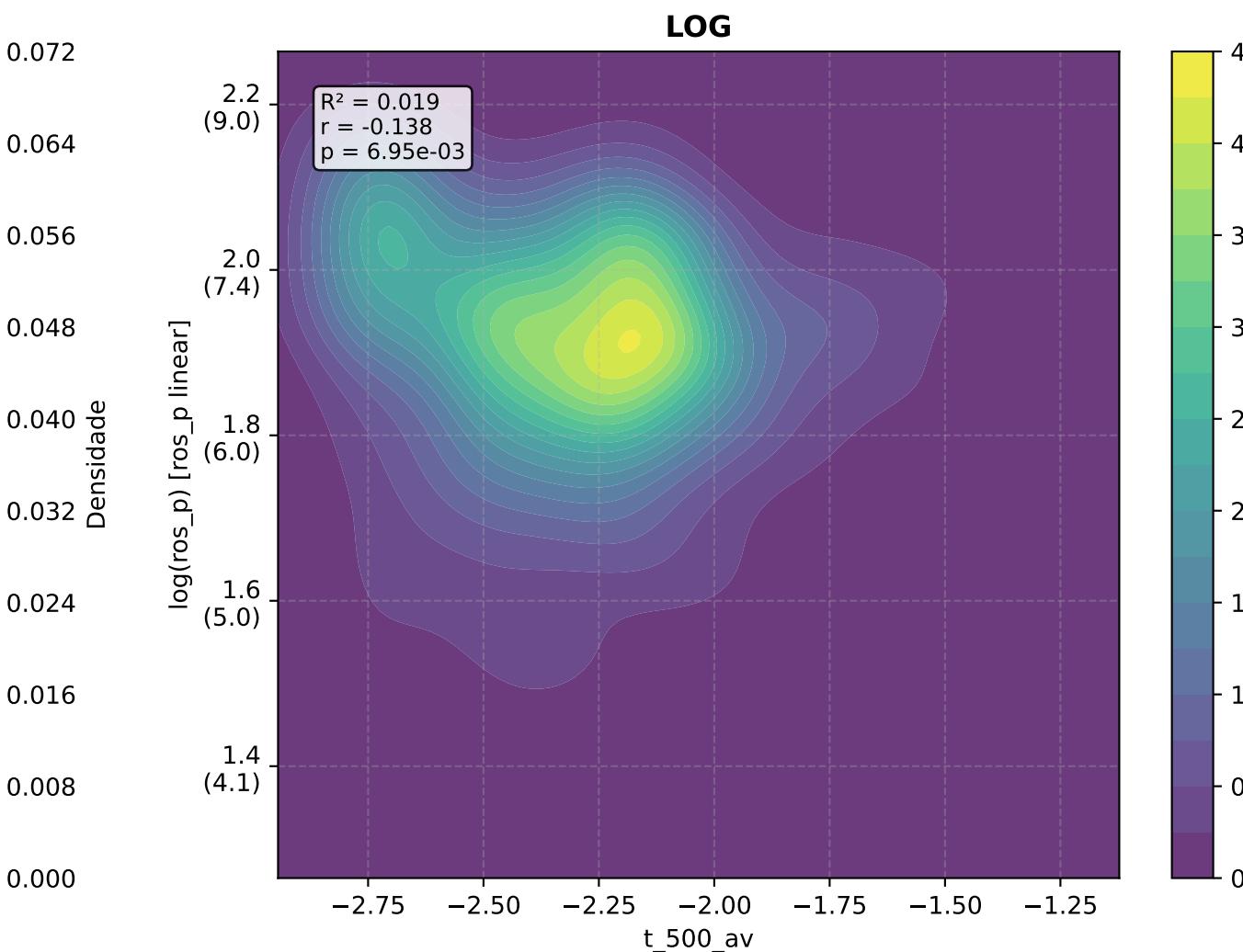
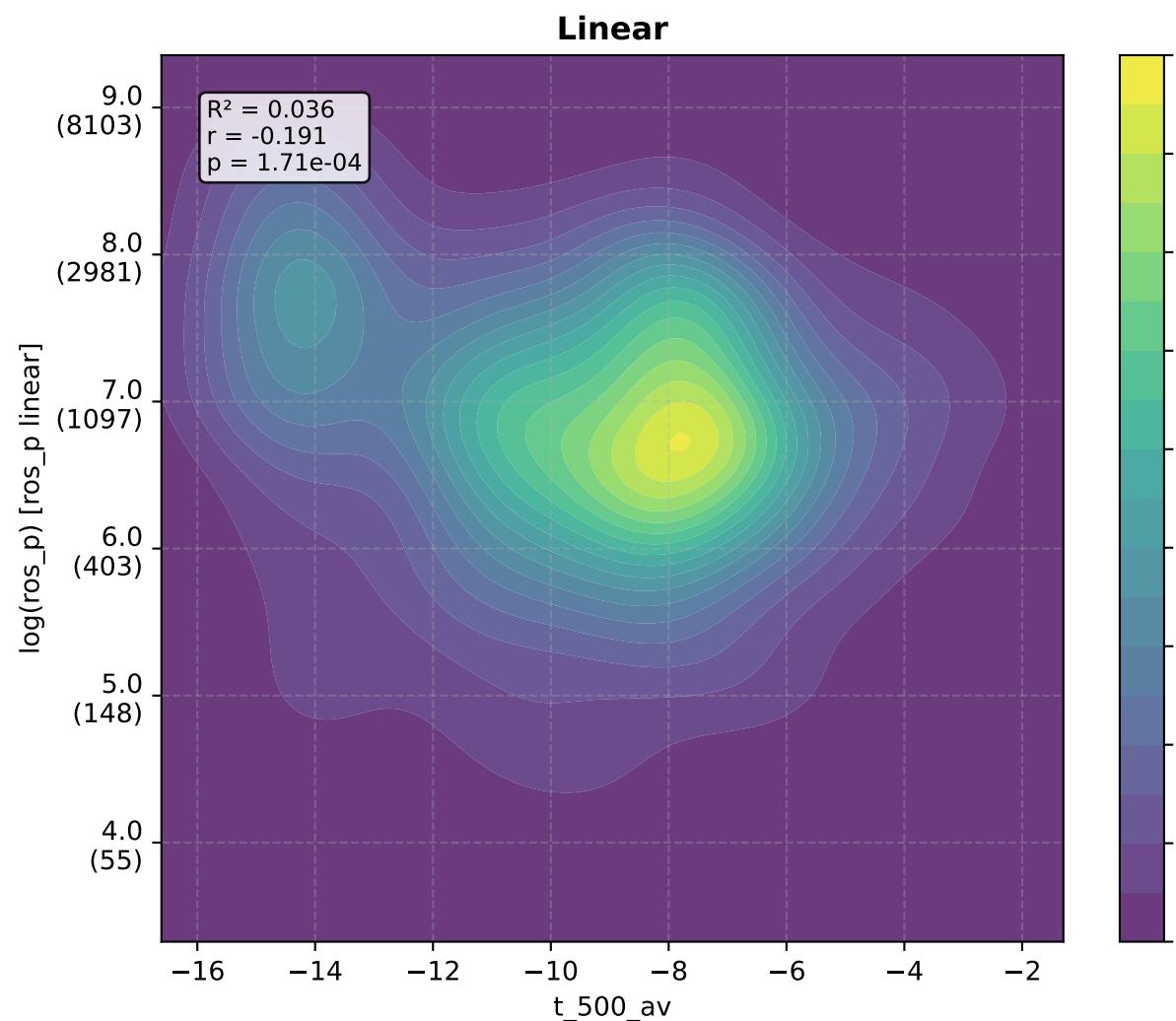
t_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



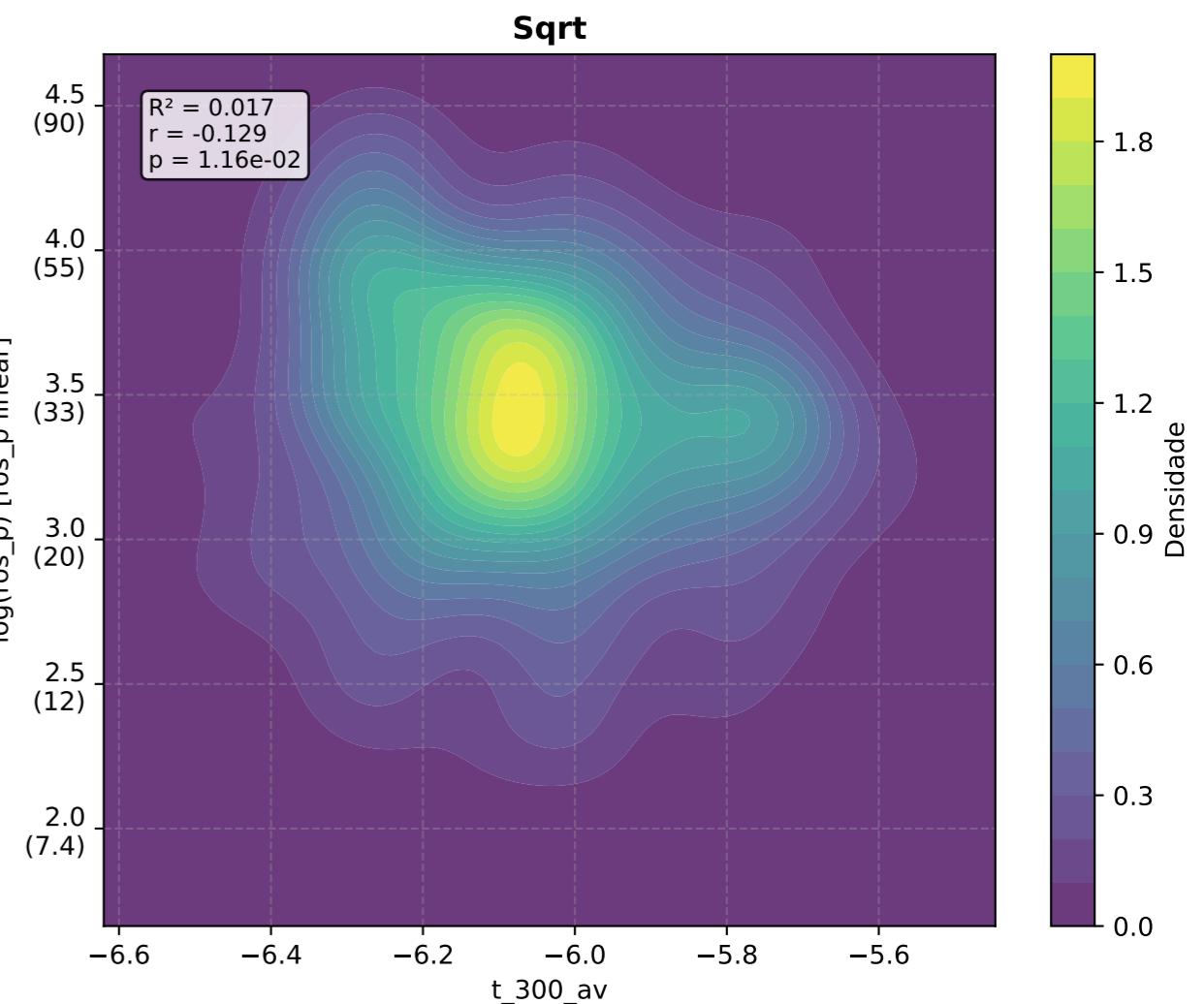
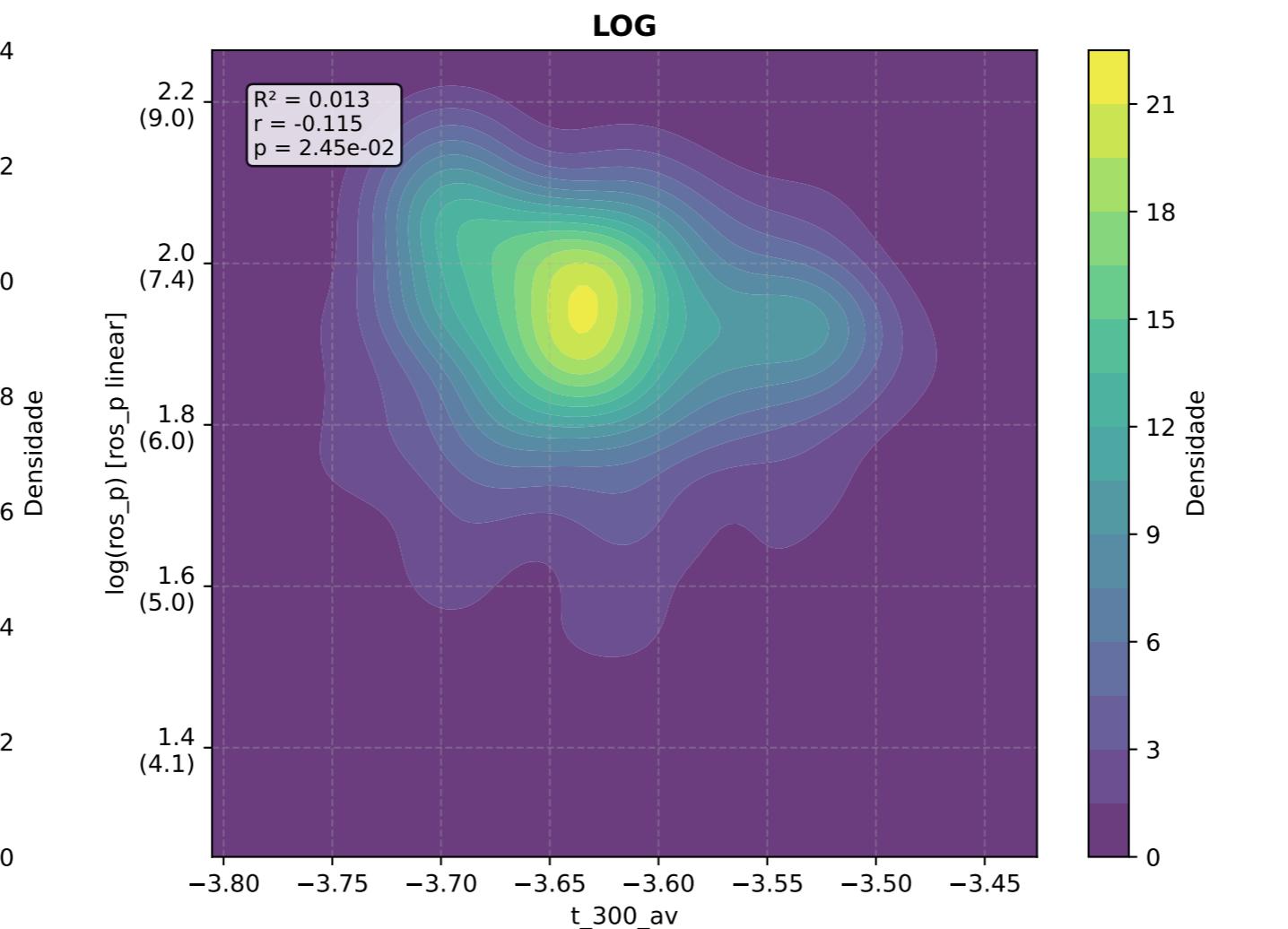
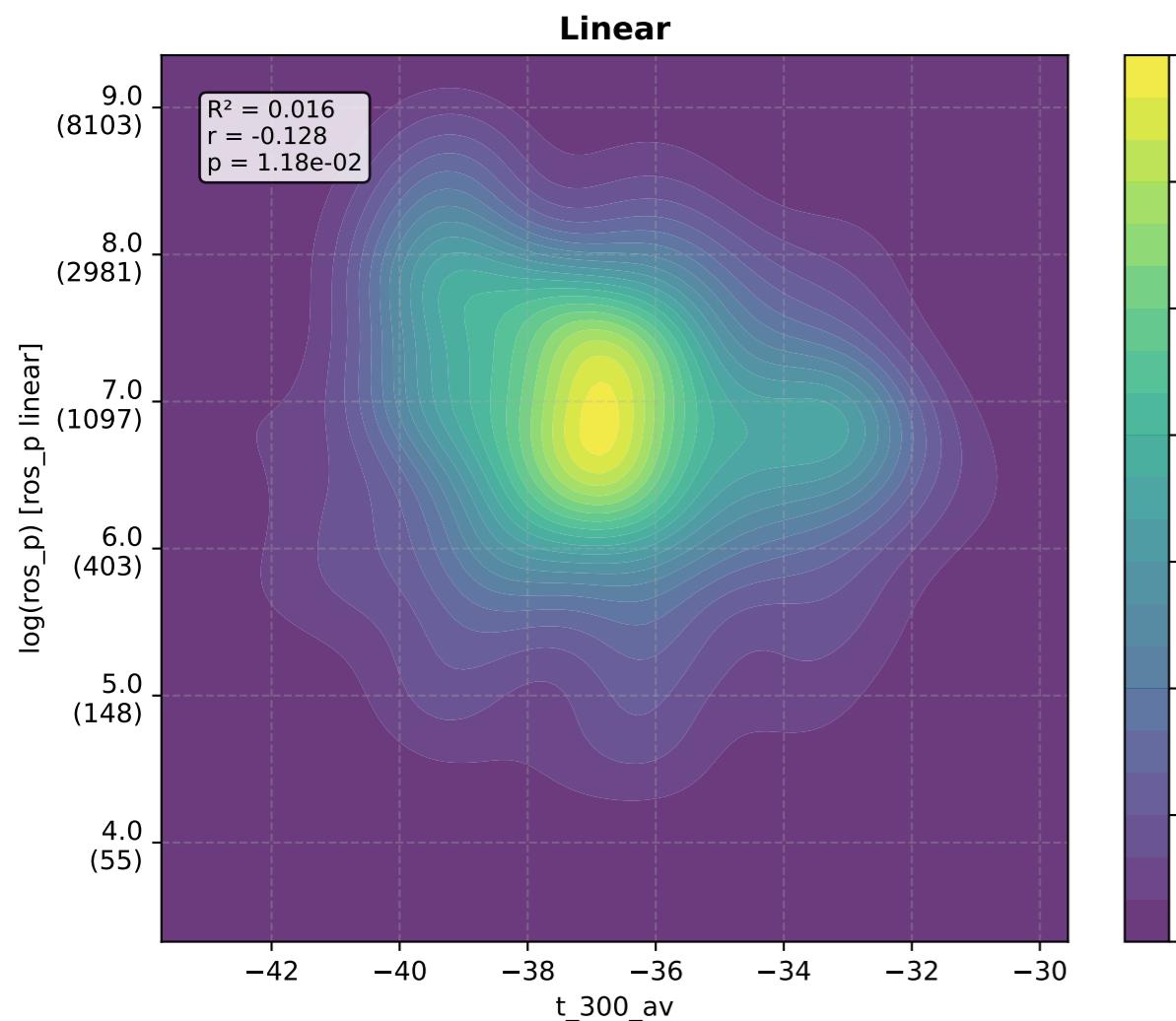
t_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



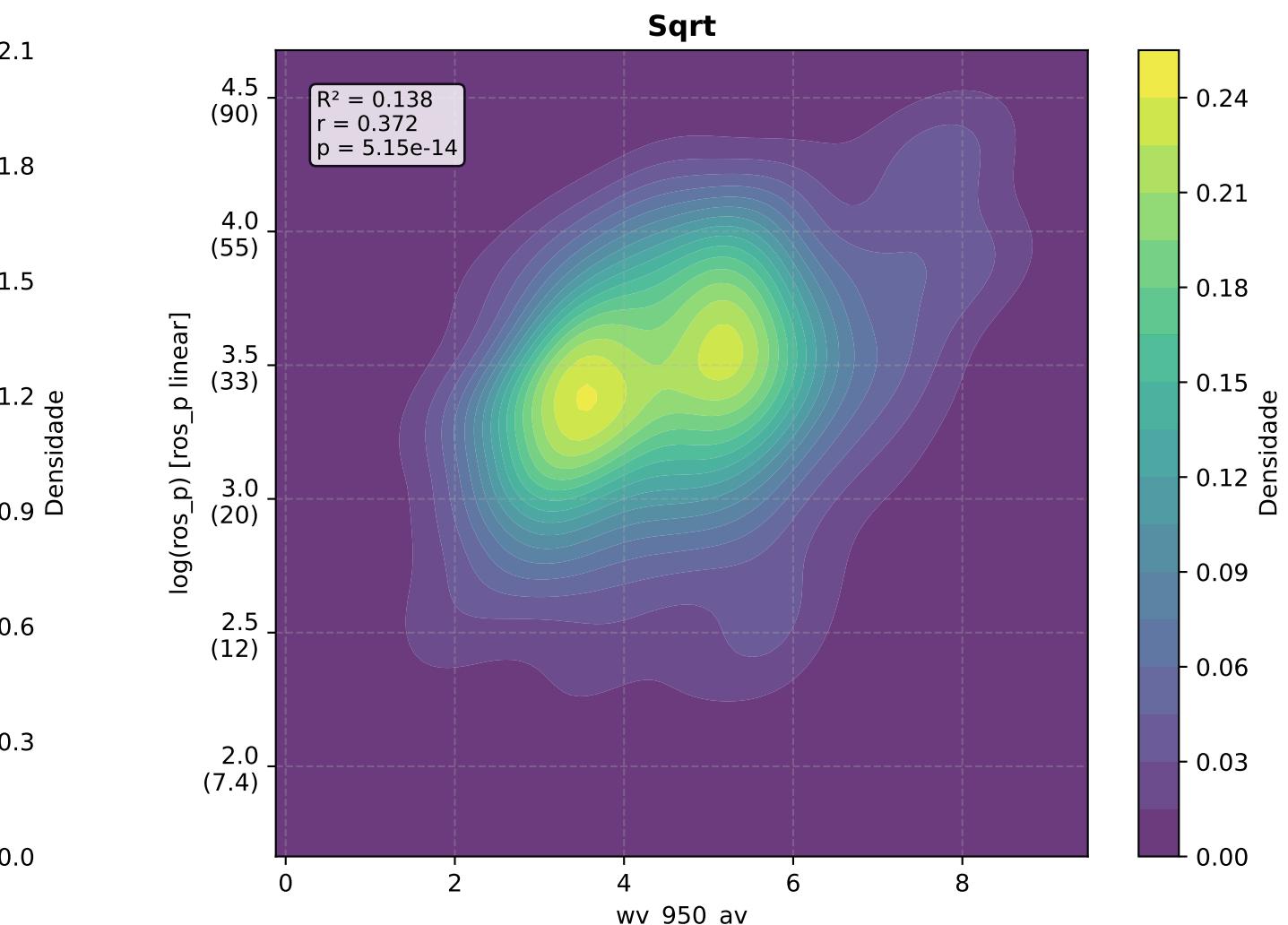
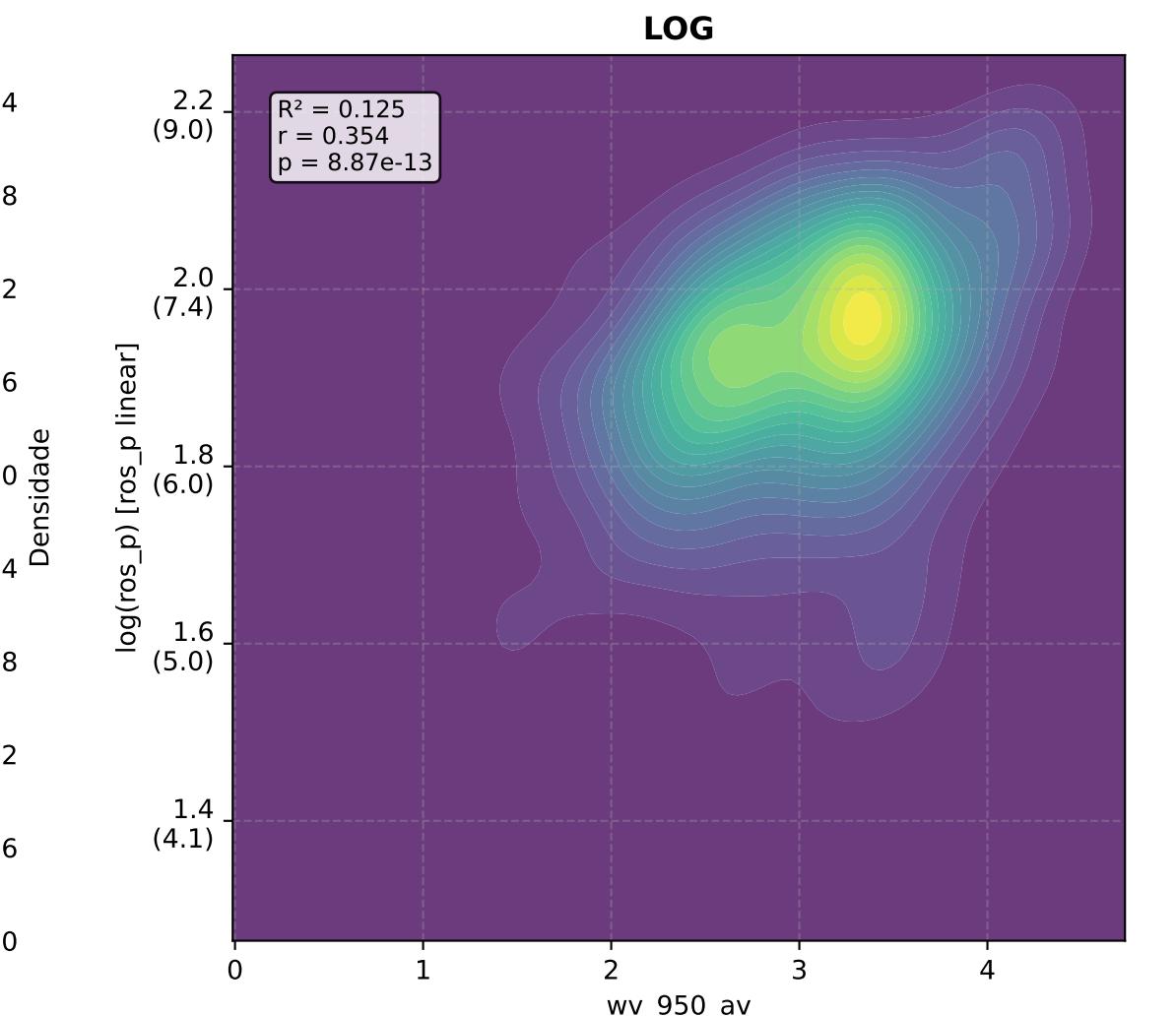
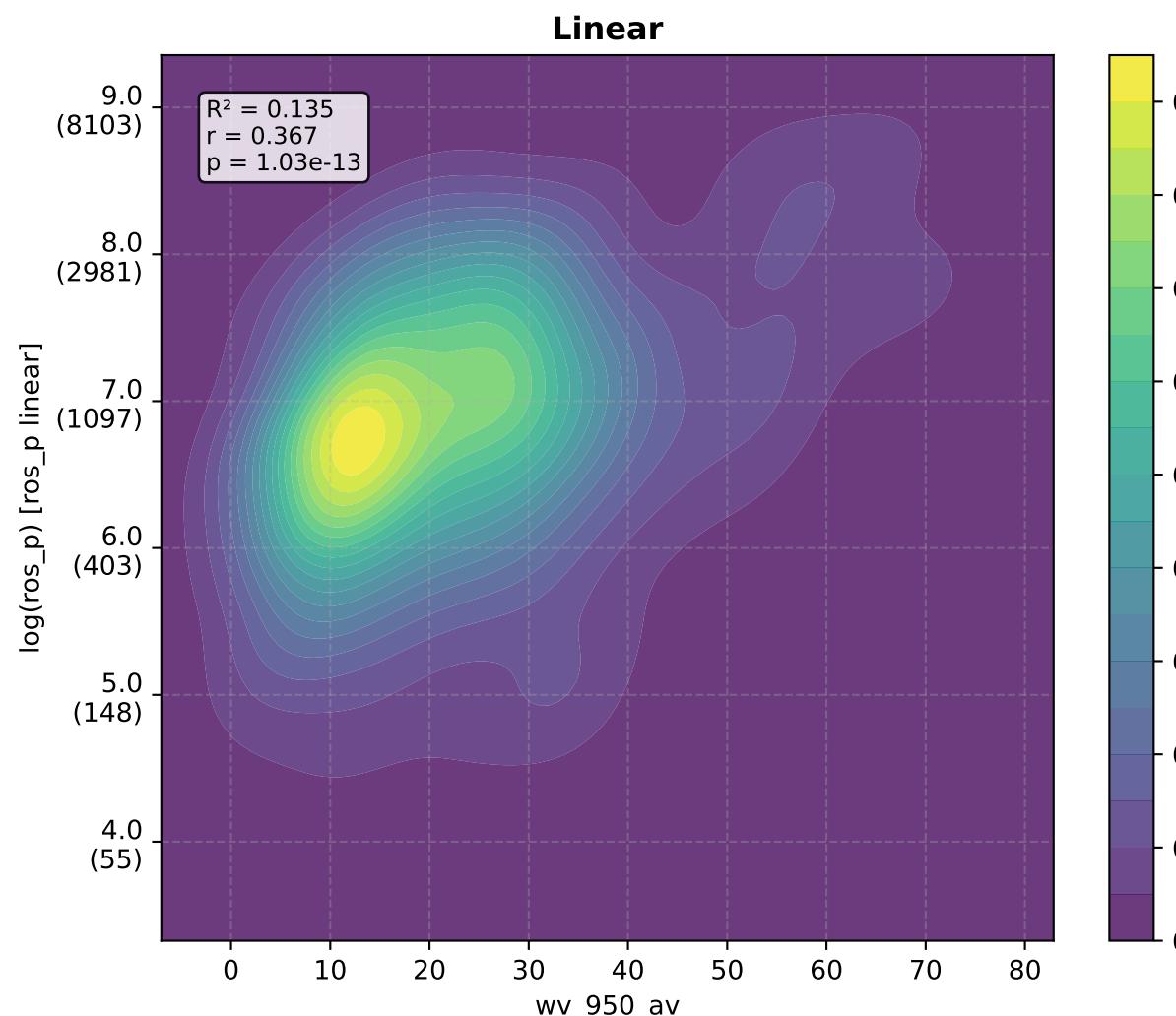
t_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



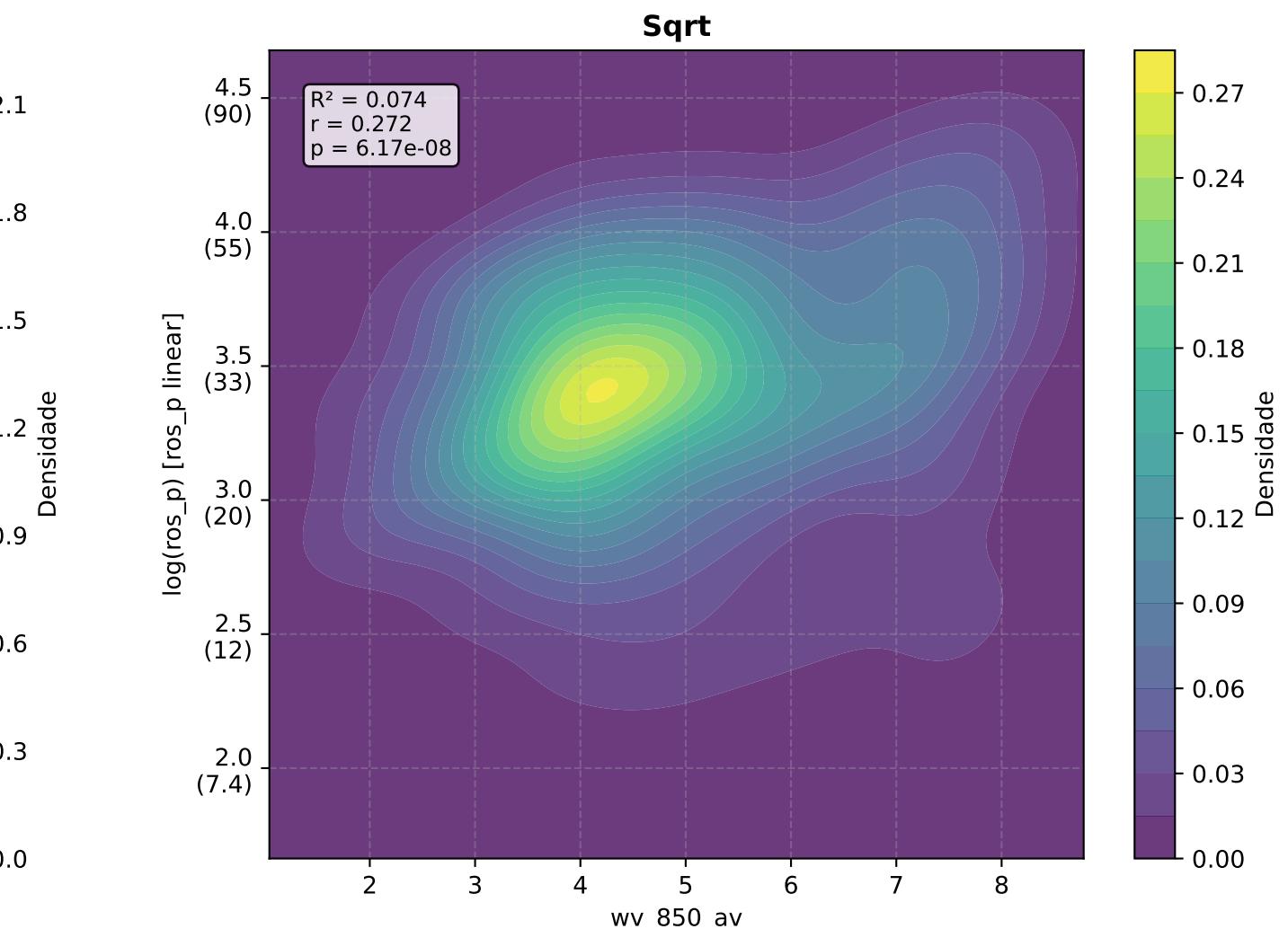
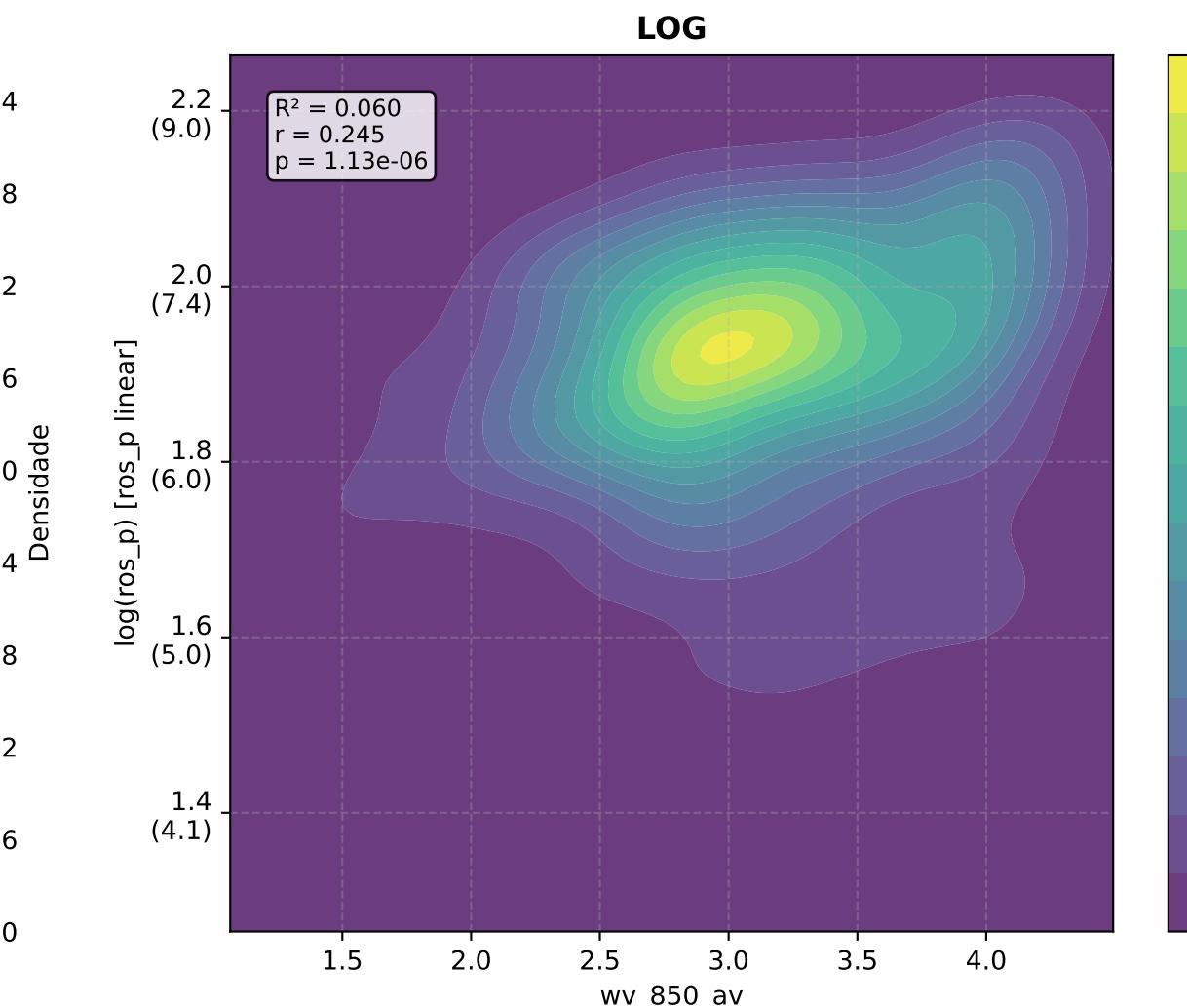
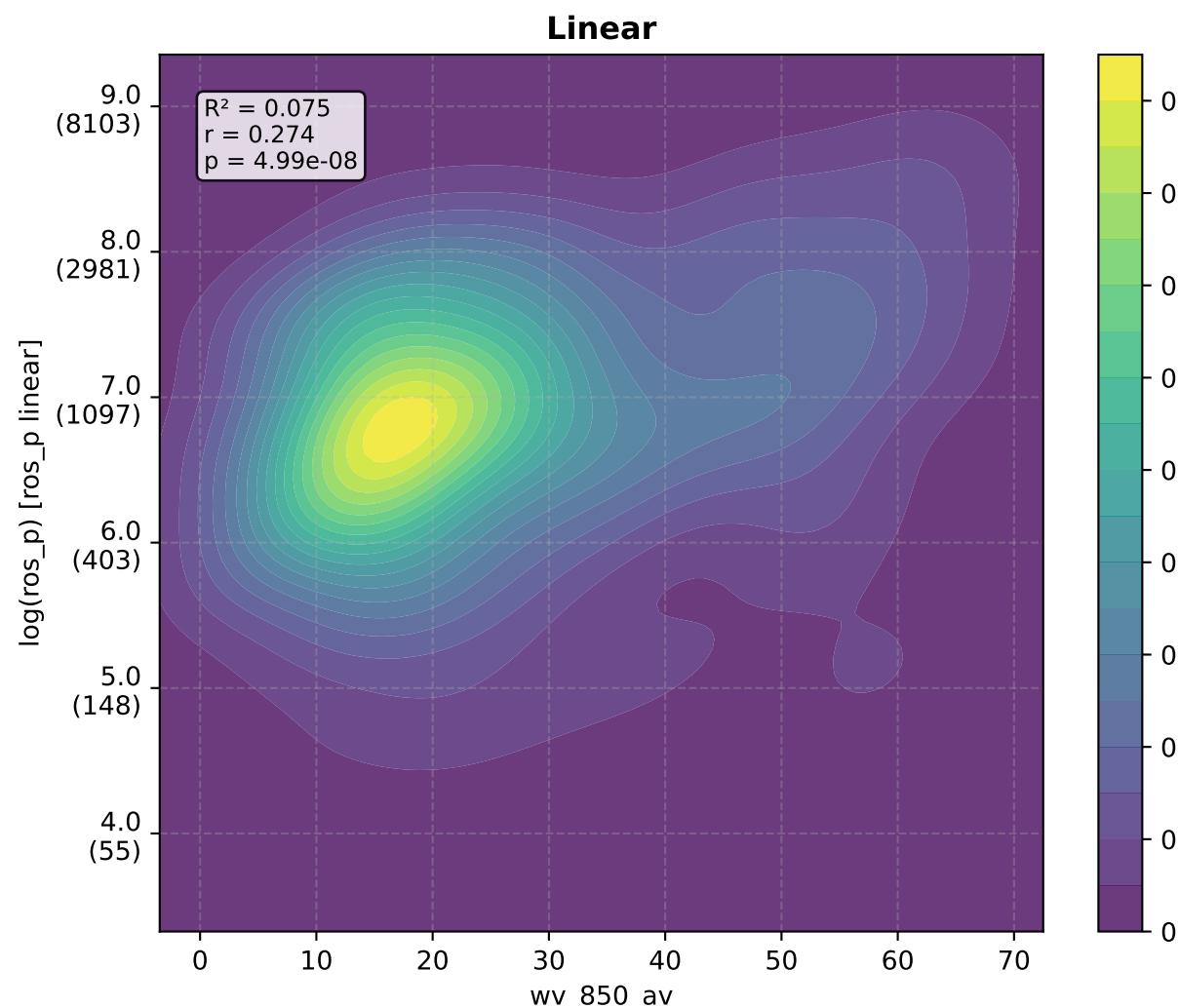
t_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



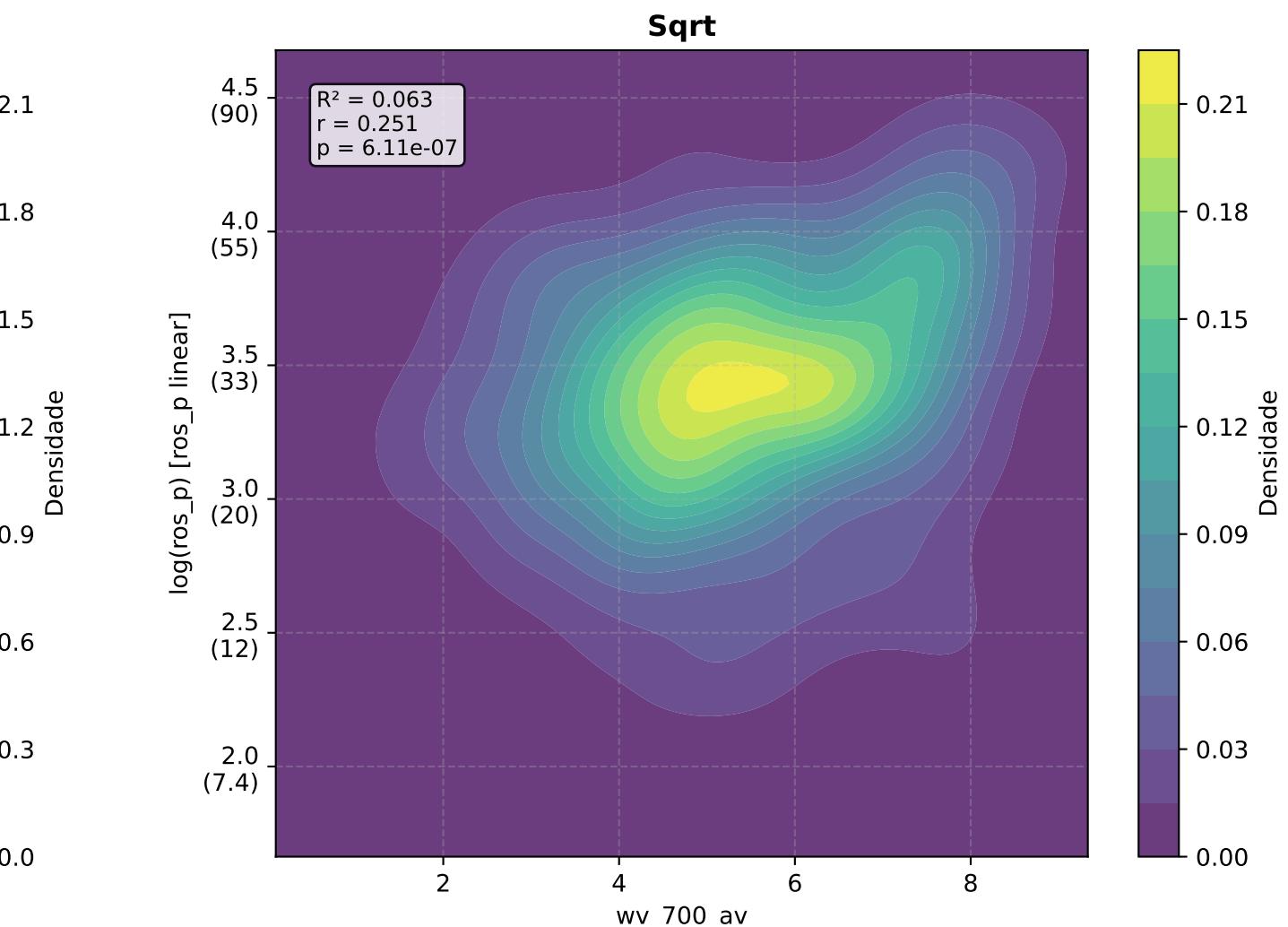
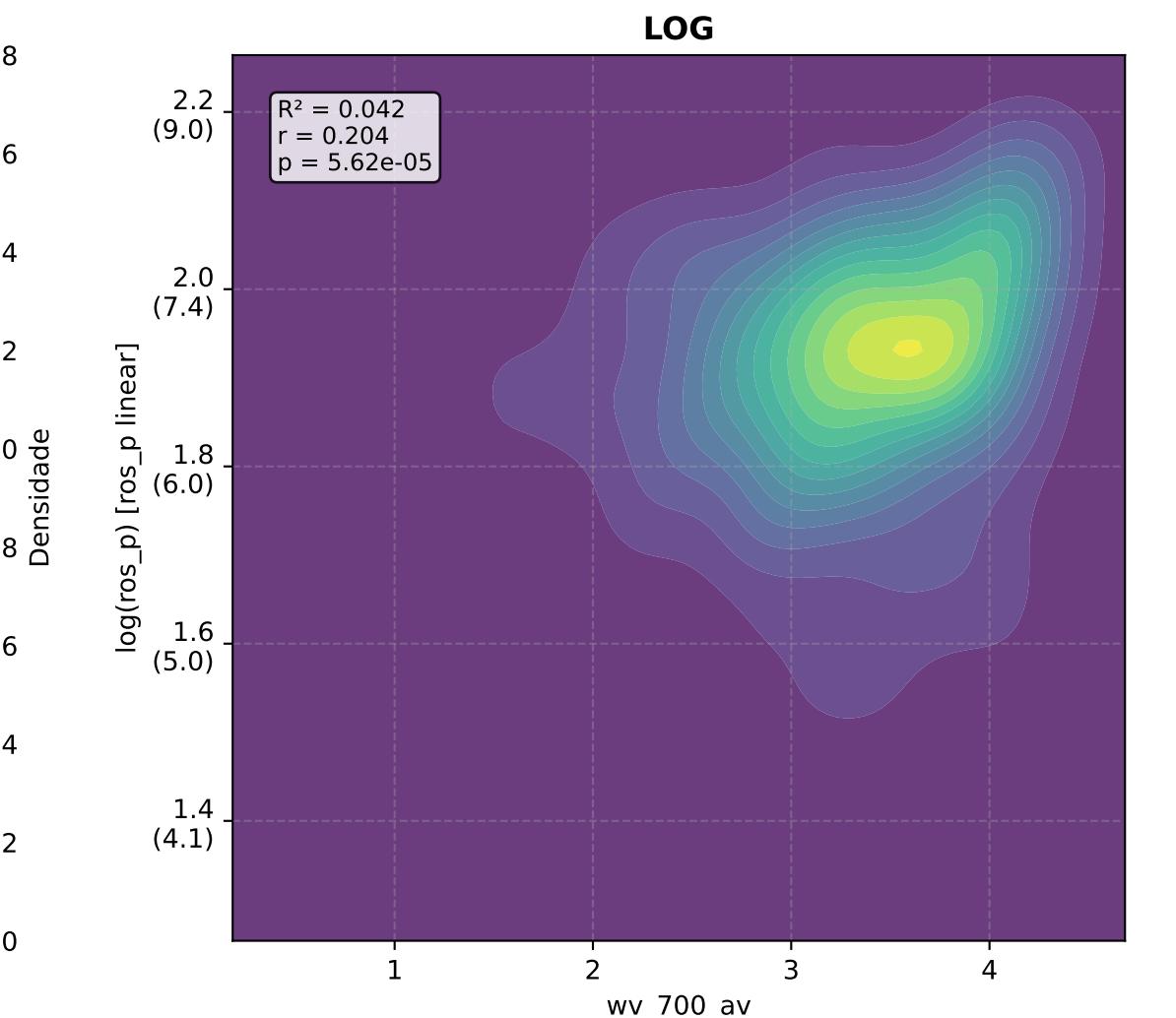
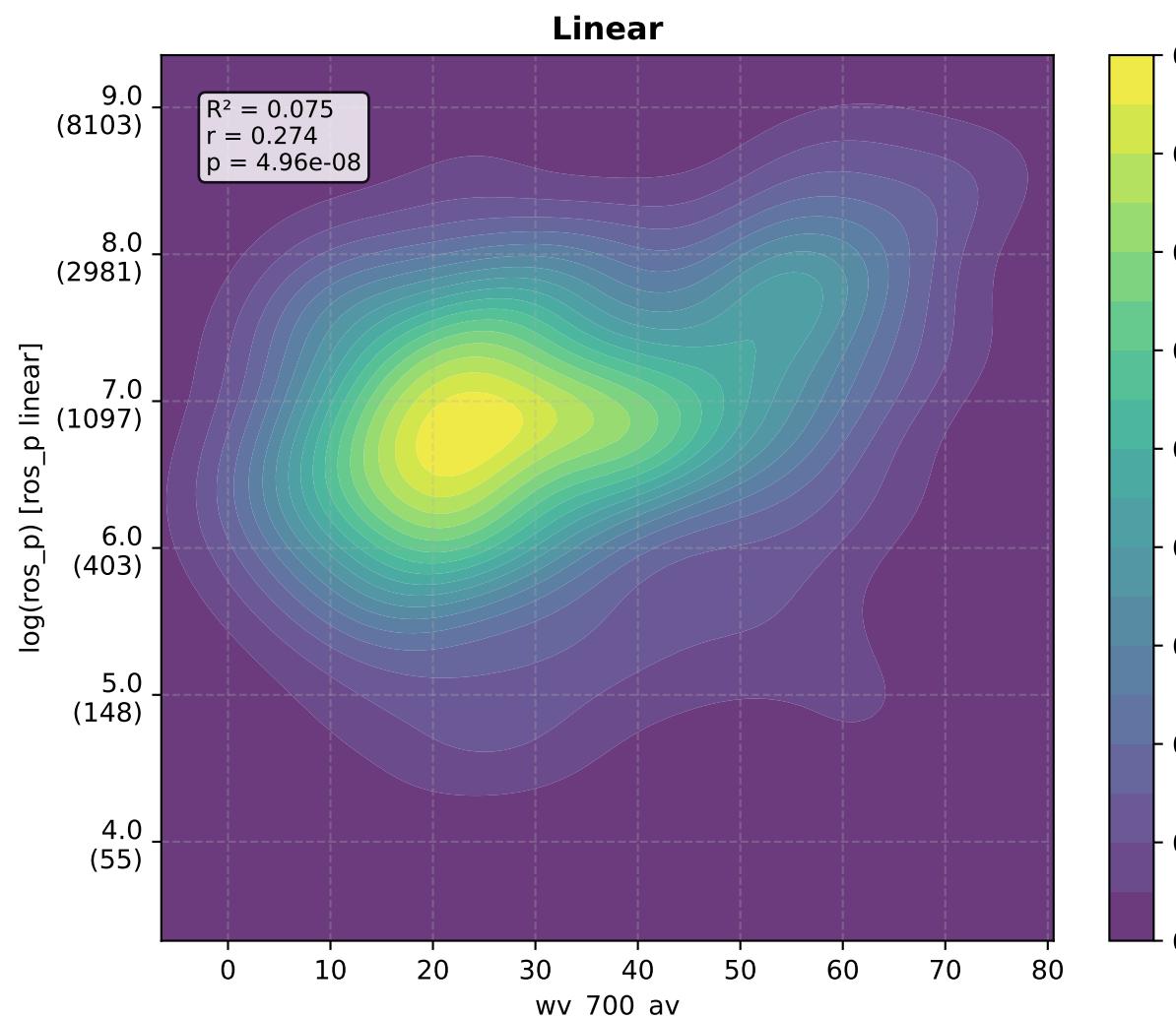
wv_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



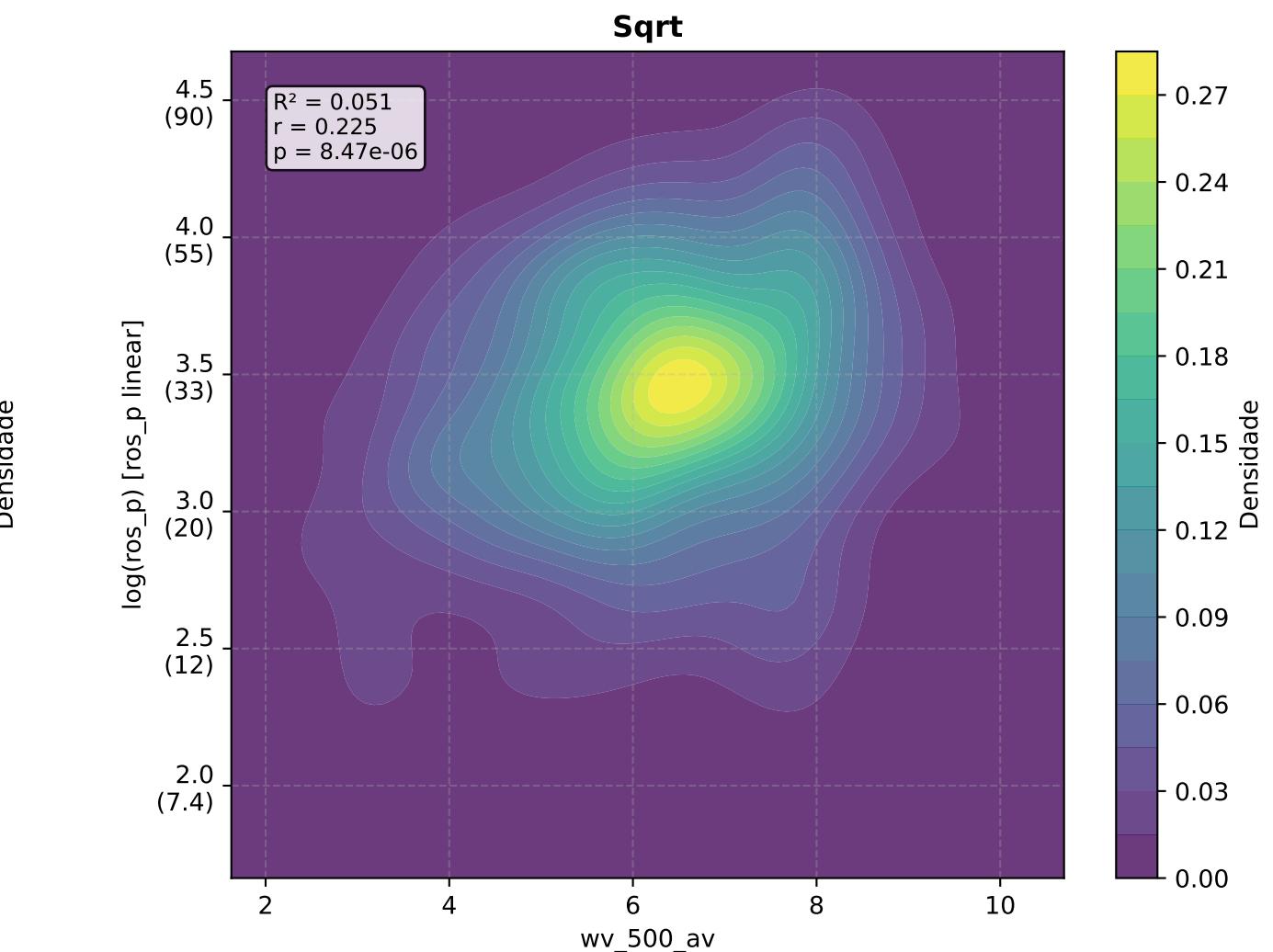
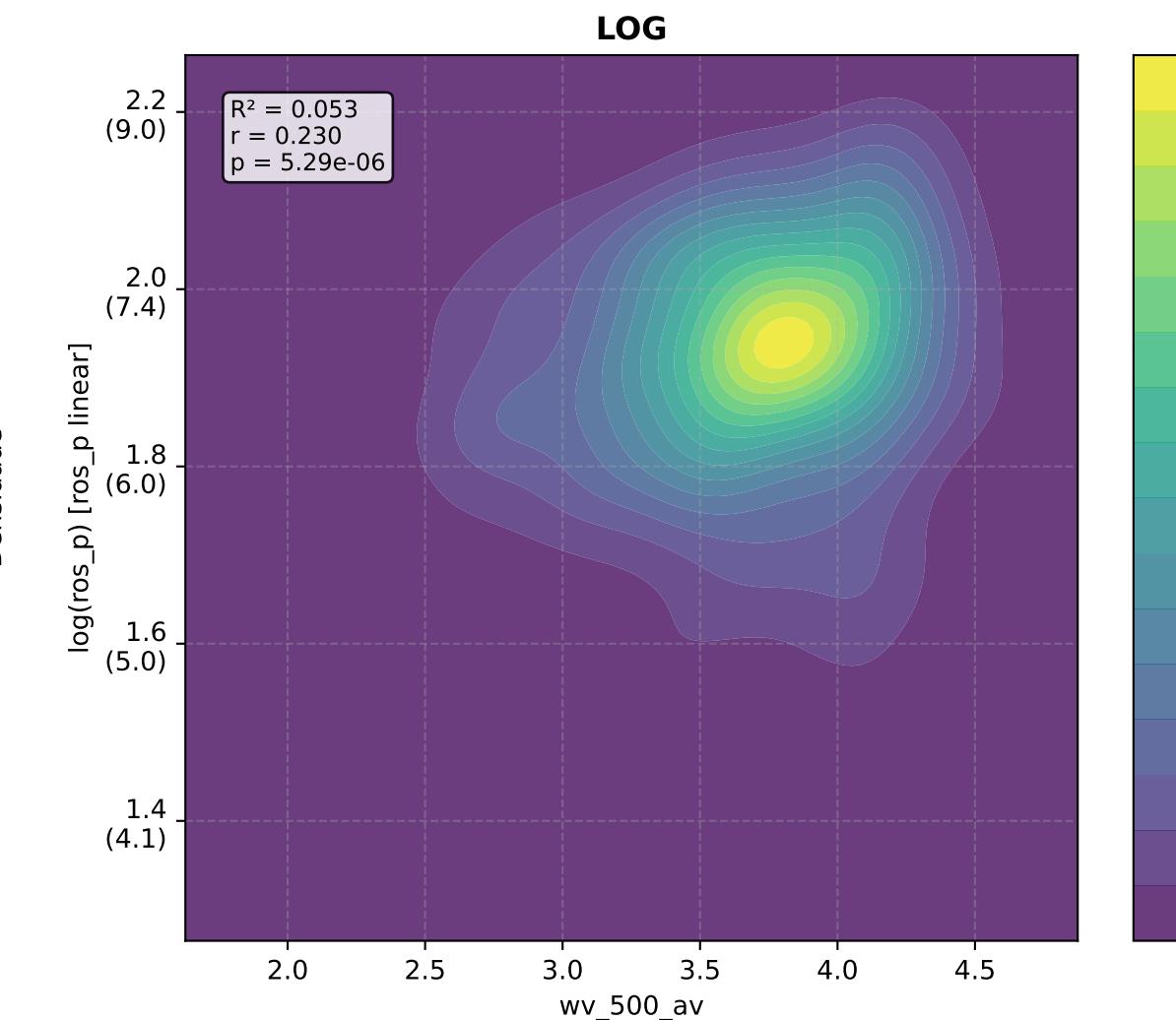
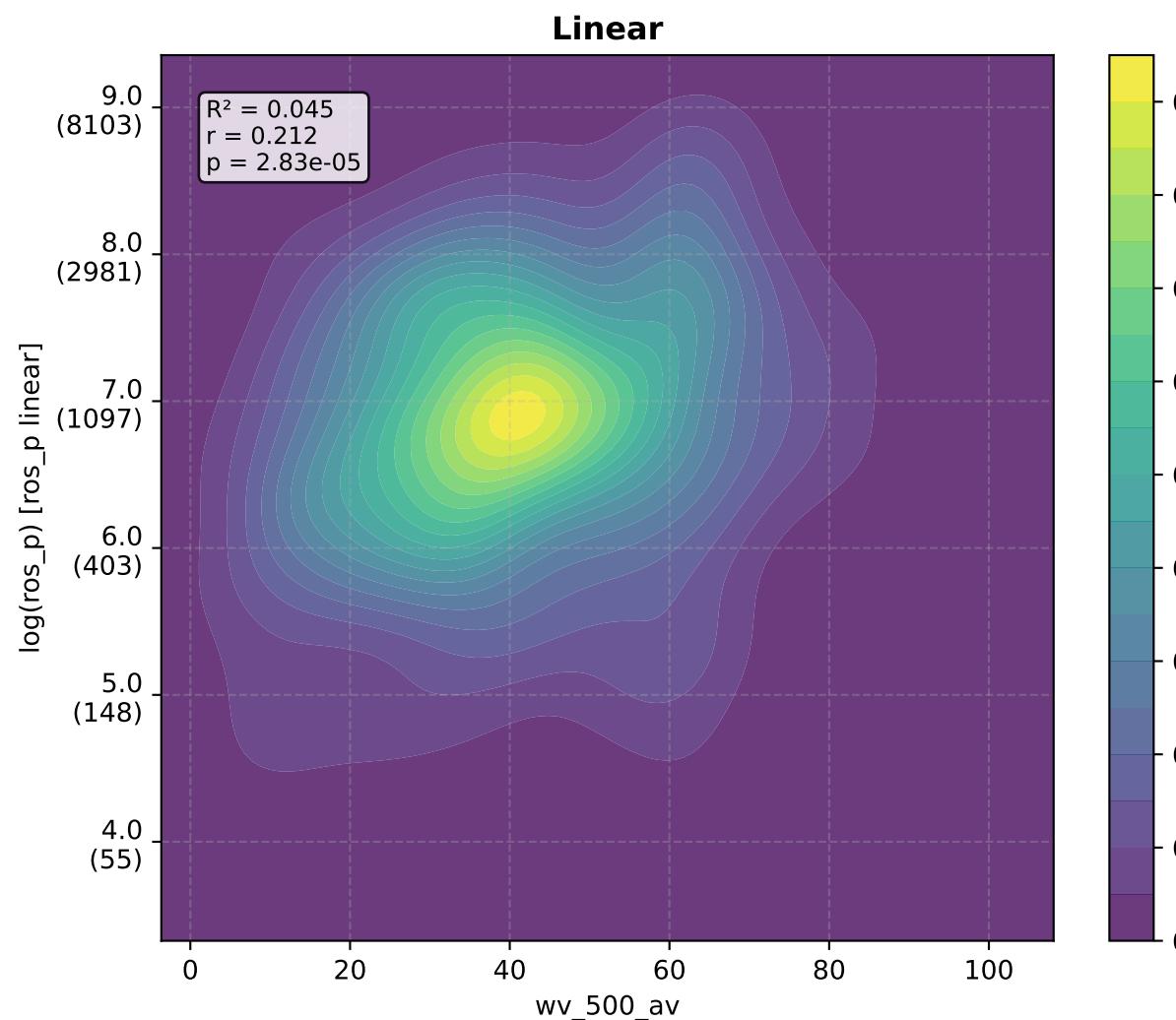
wv_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



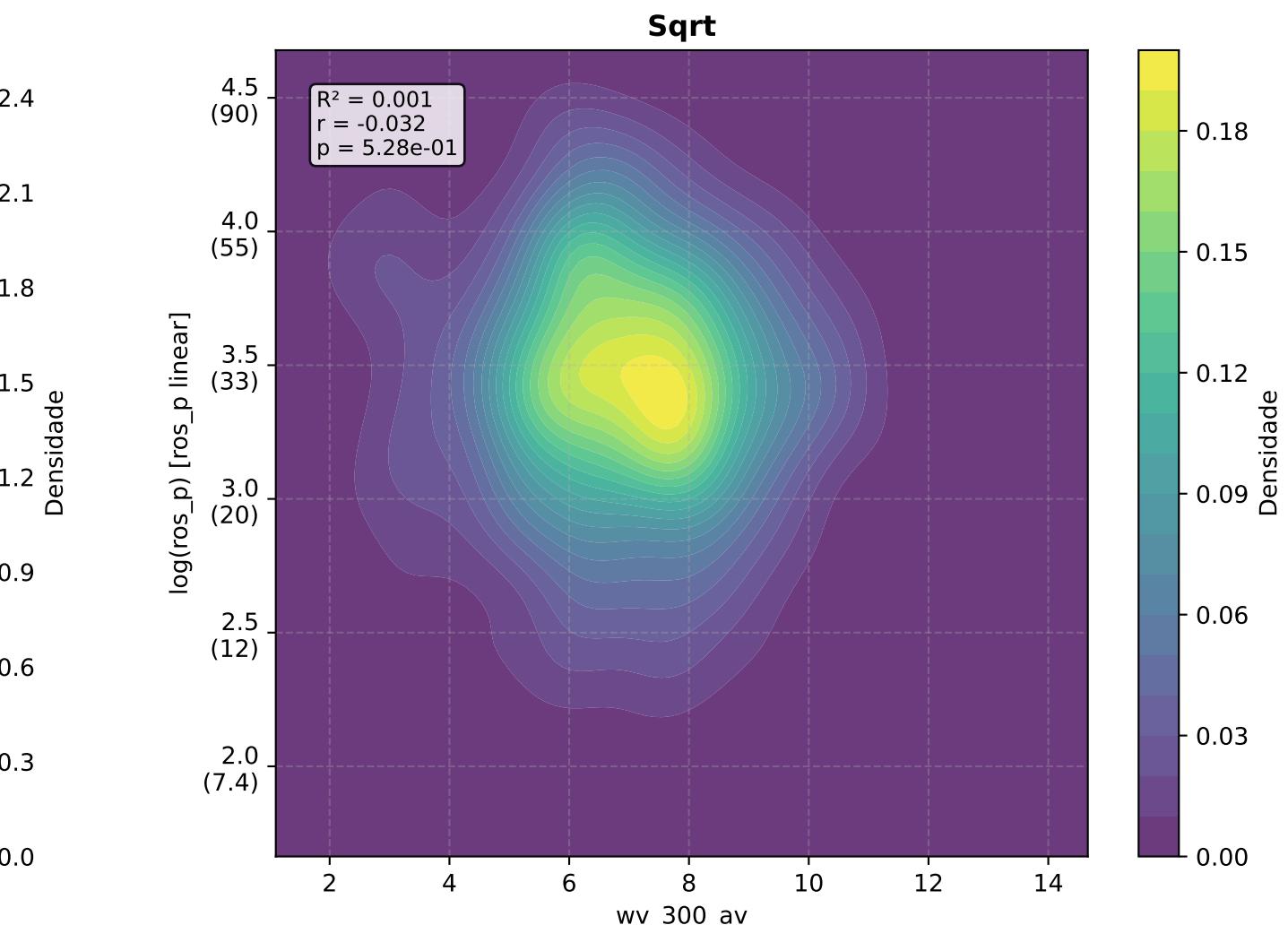
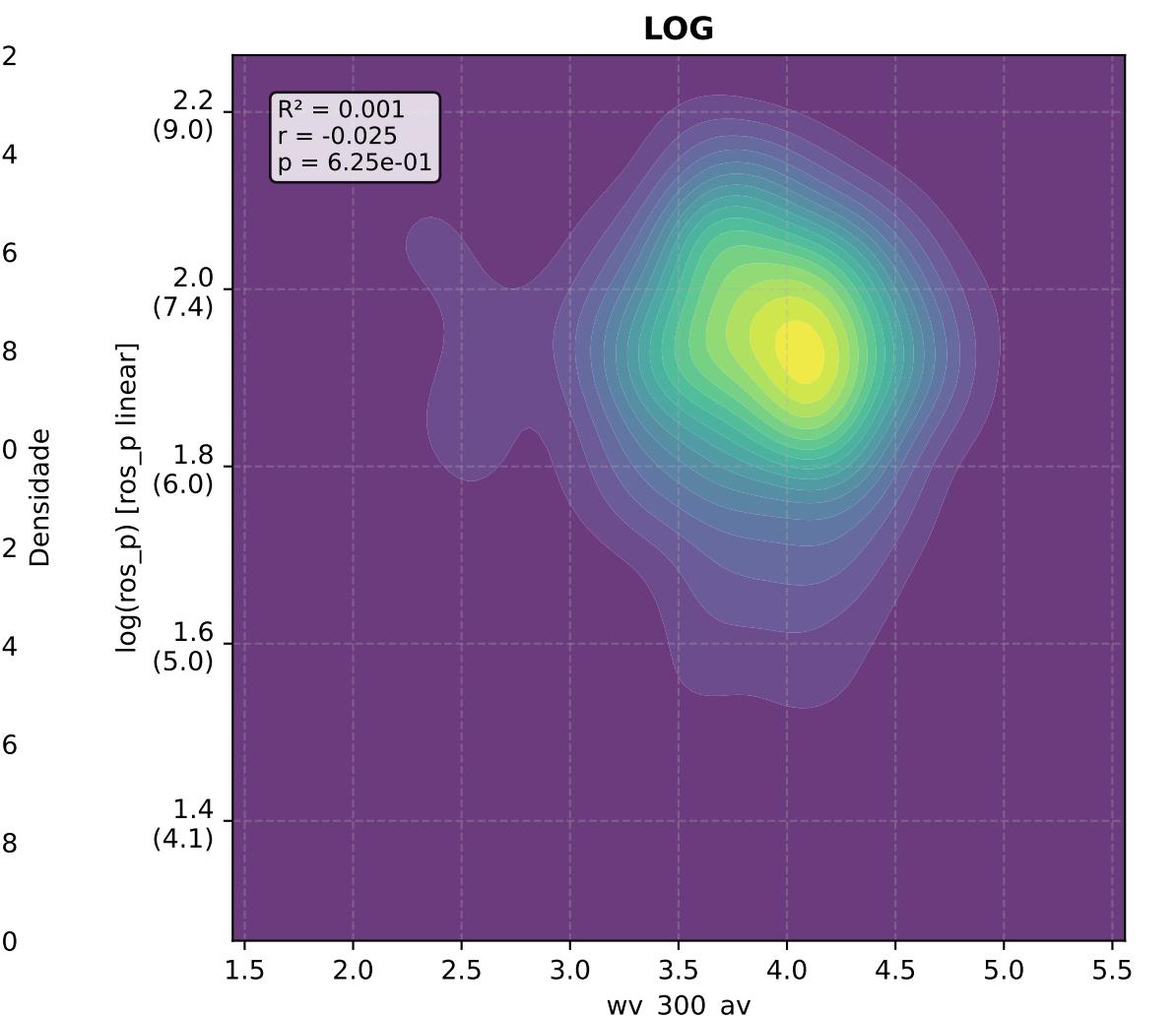
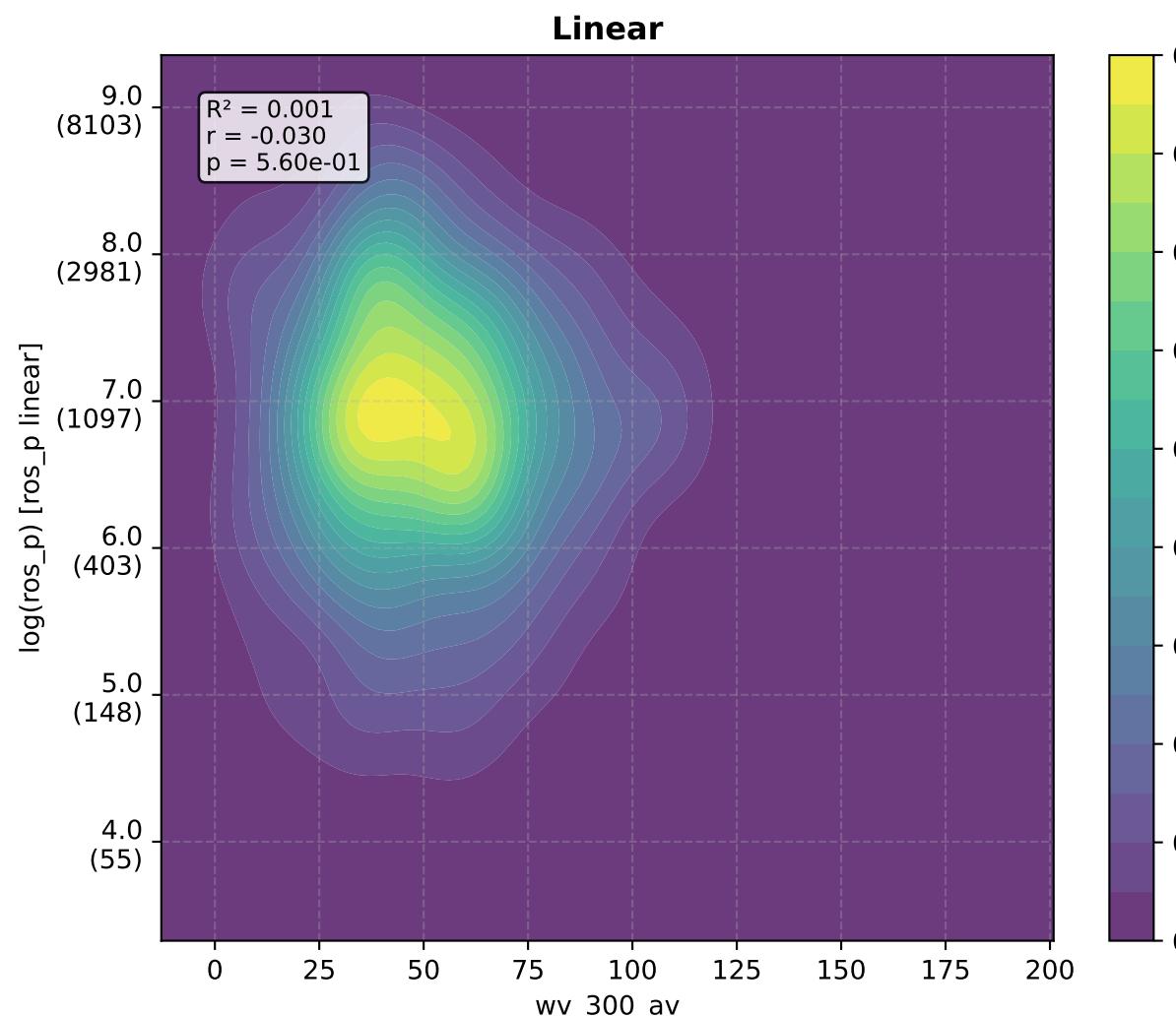
wv_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



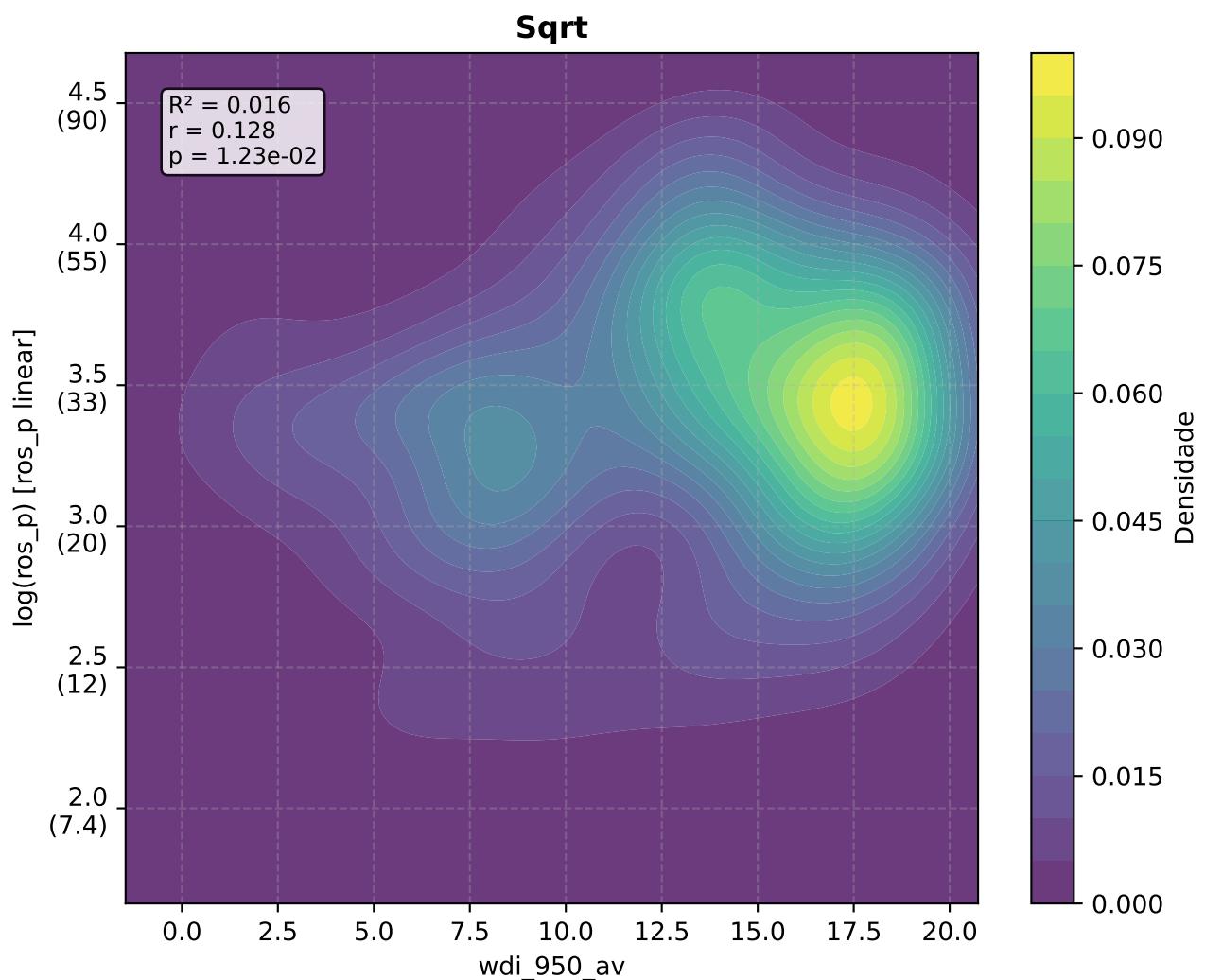
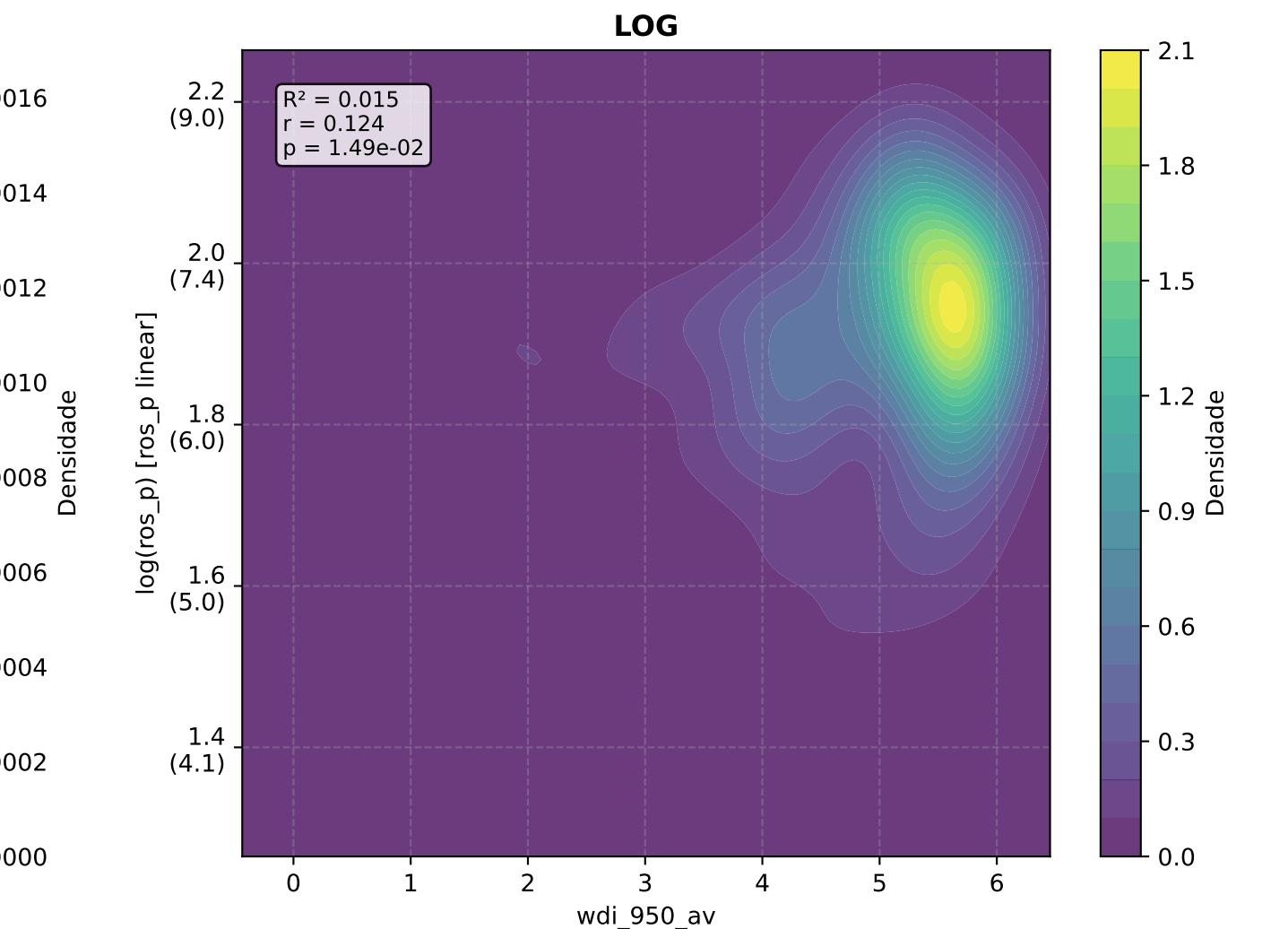
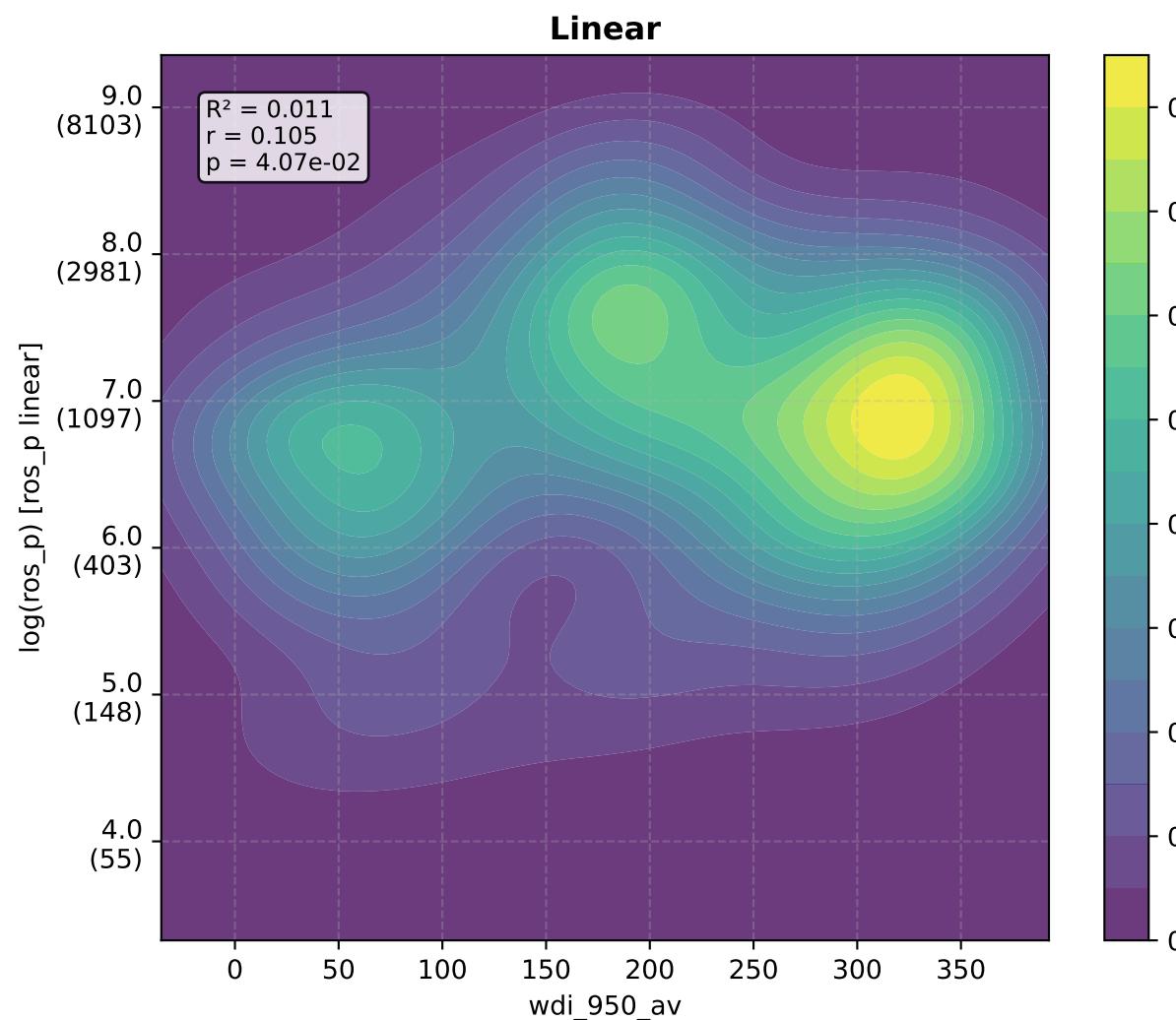
wv_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



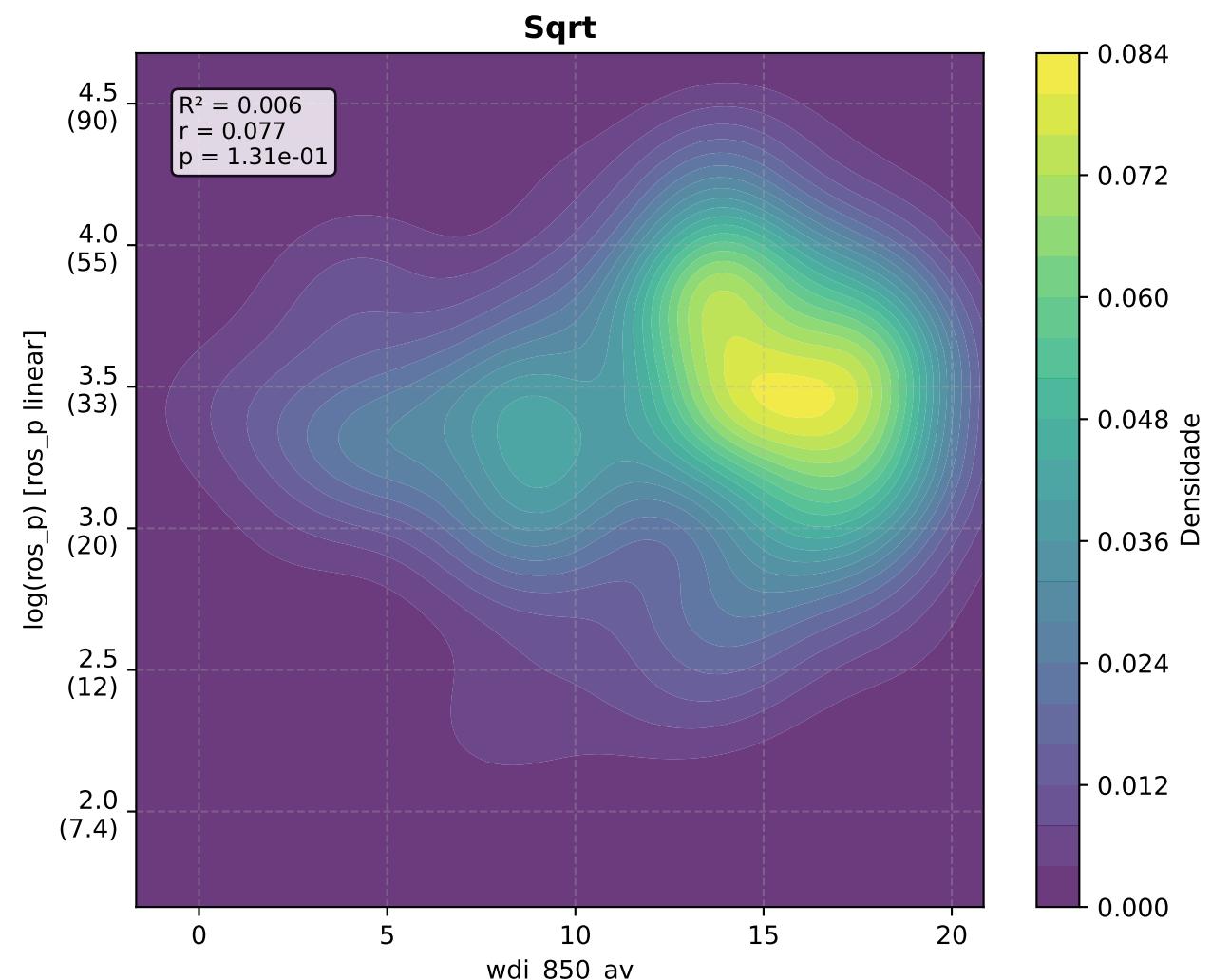
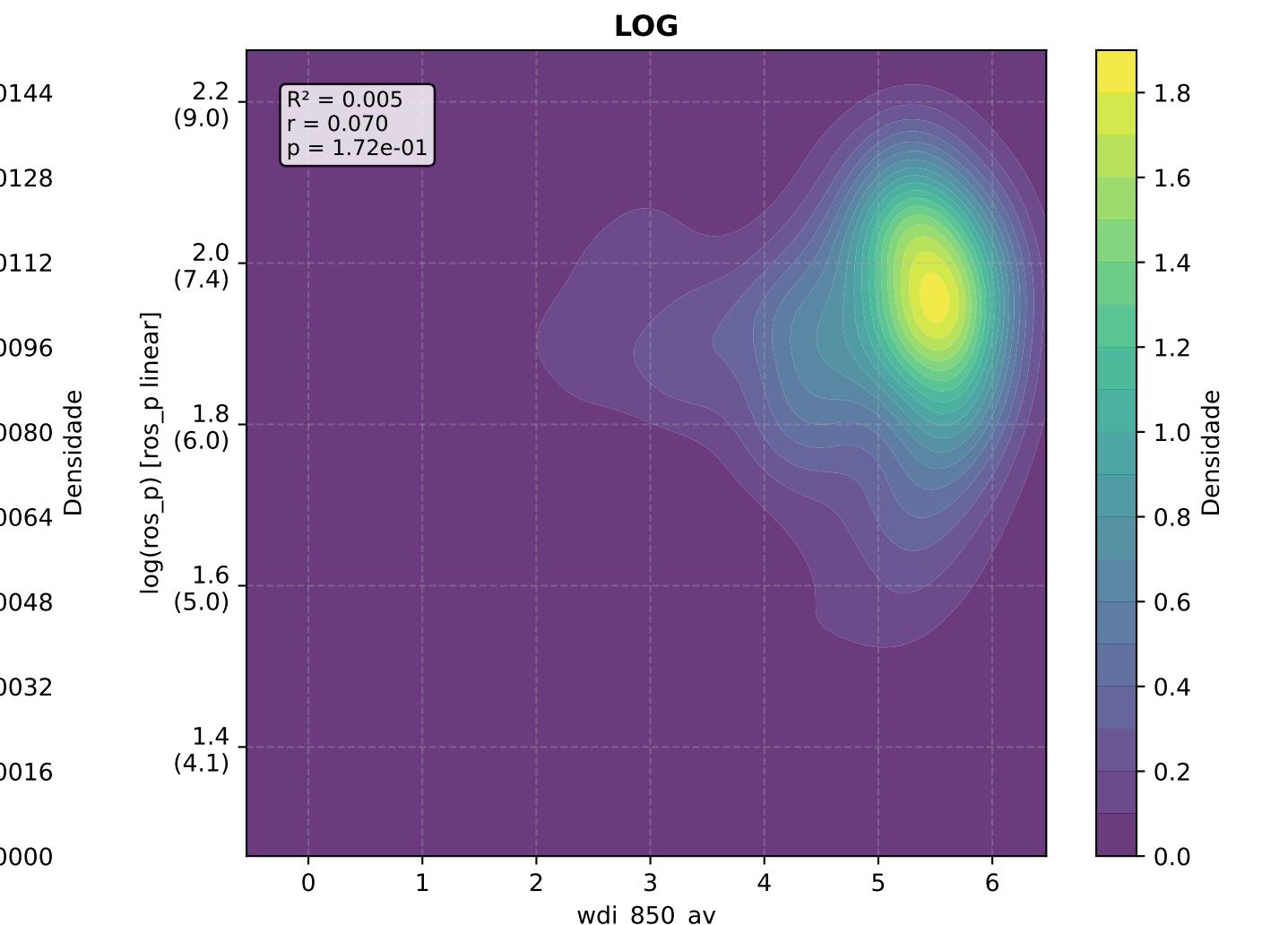
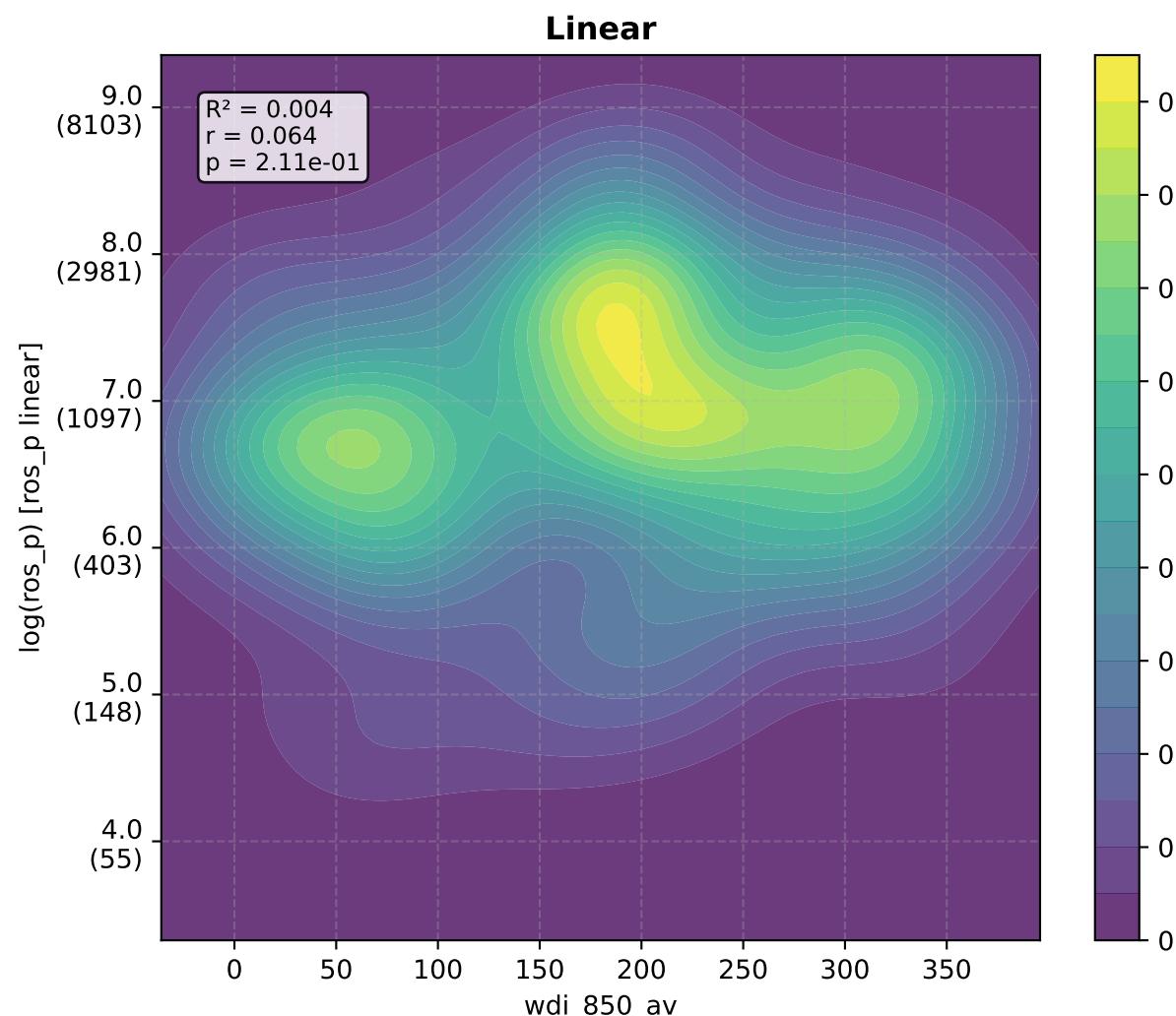
wv_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



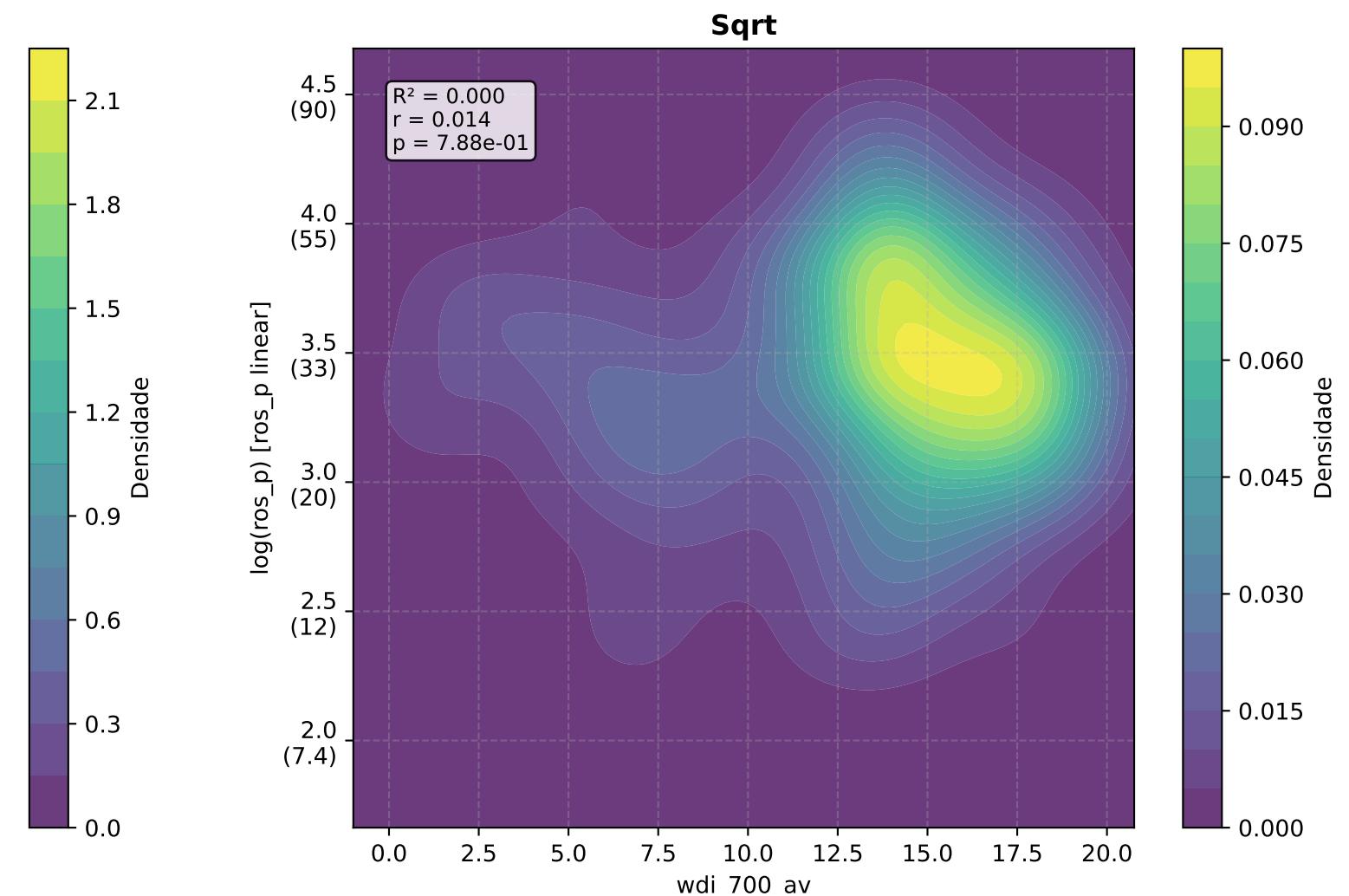
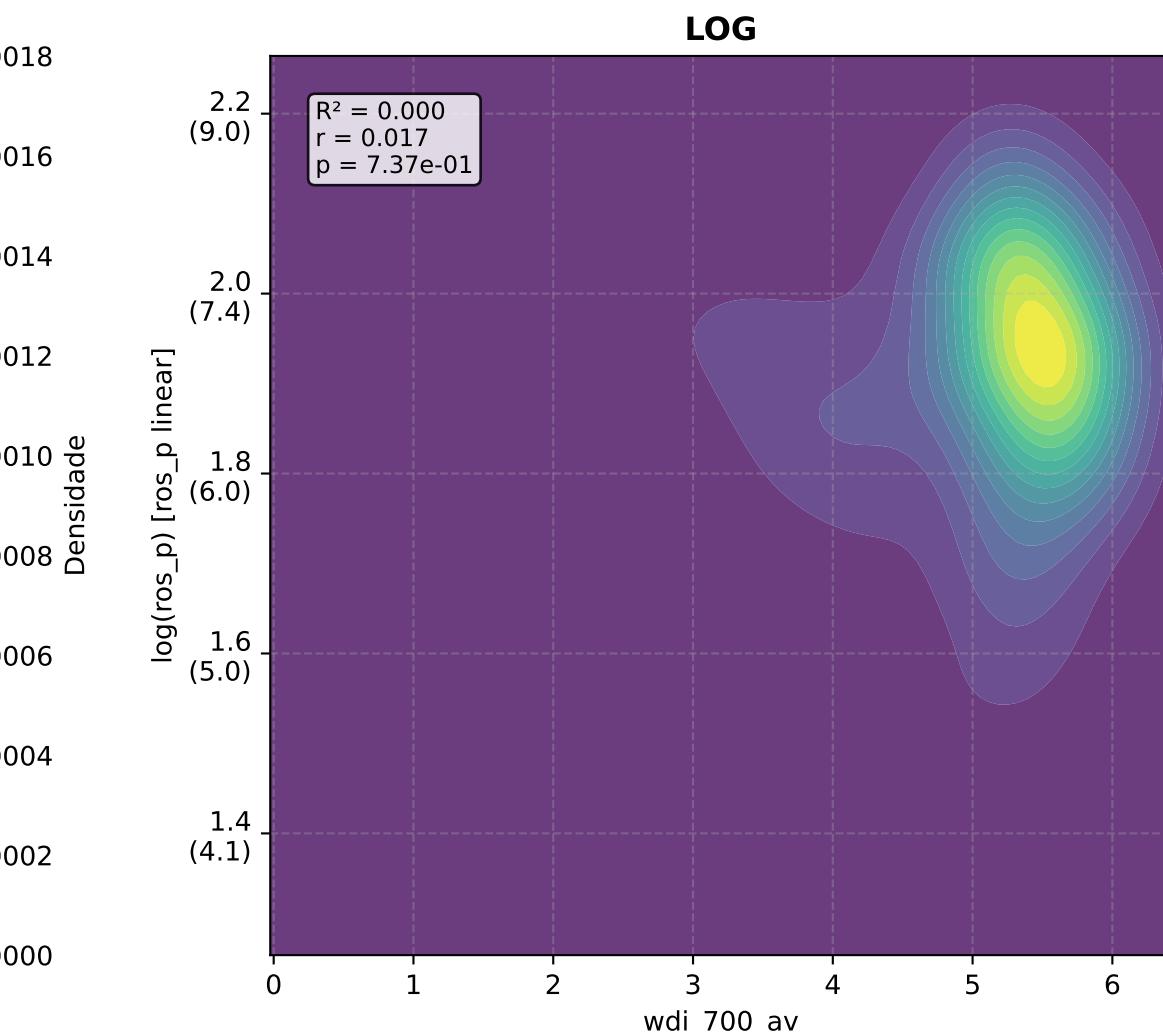
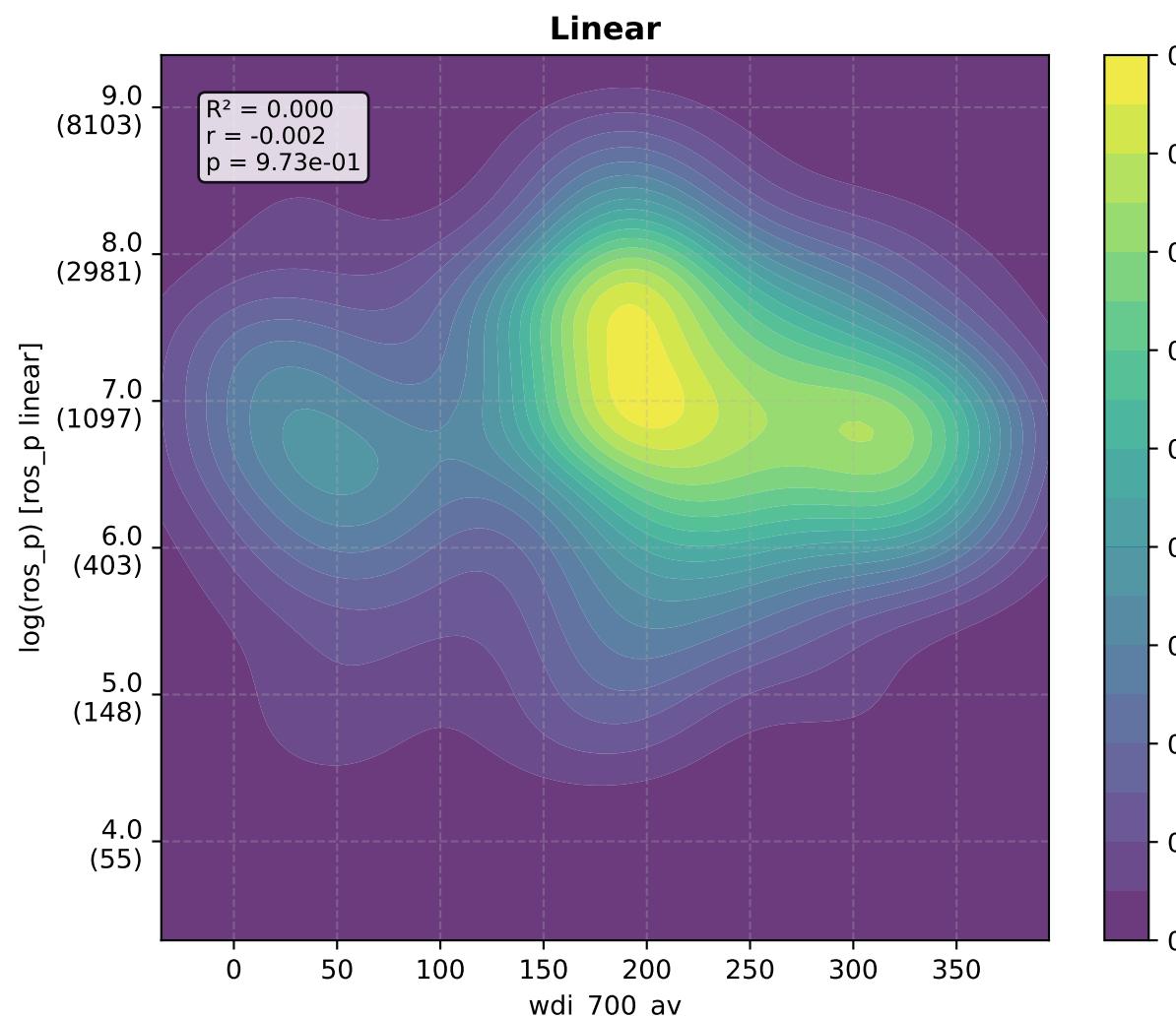
wdi_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



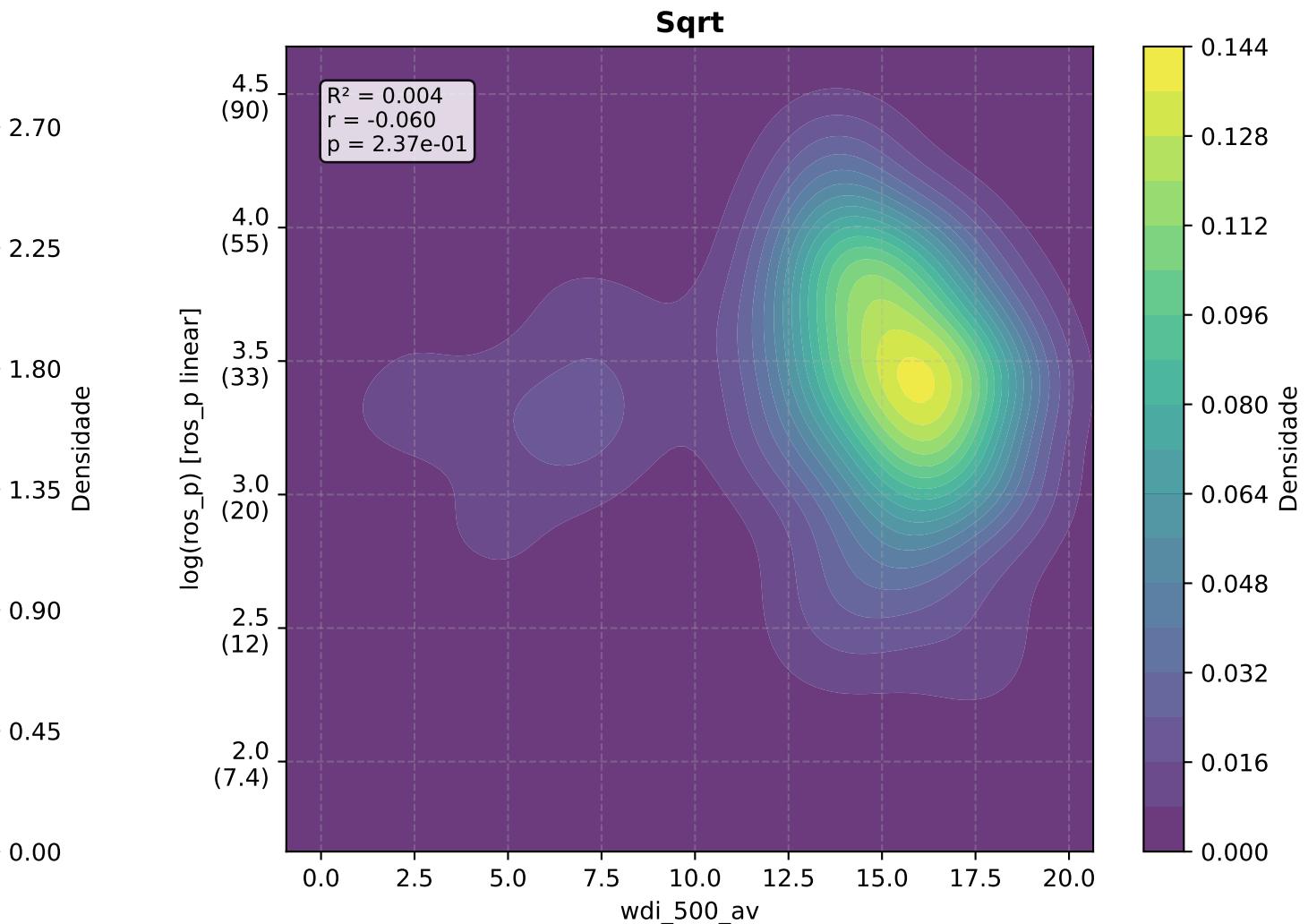
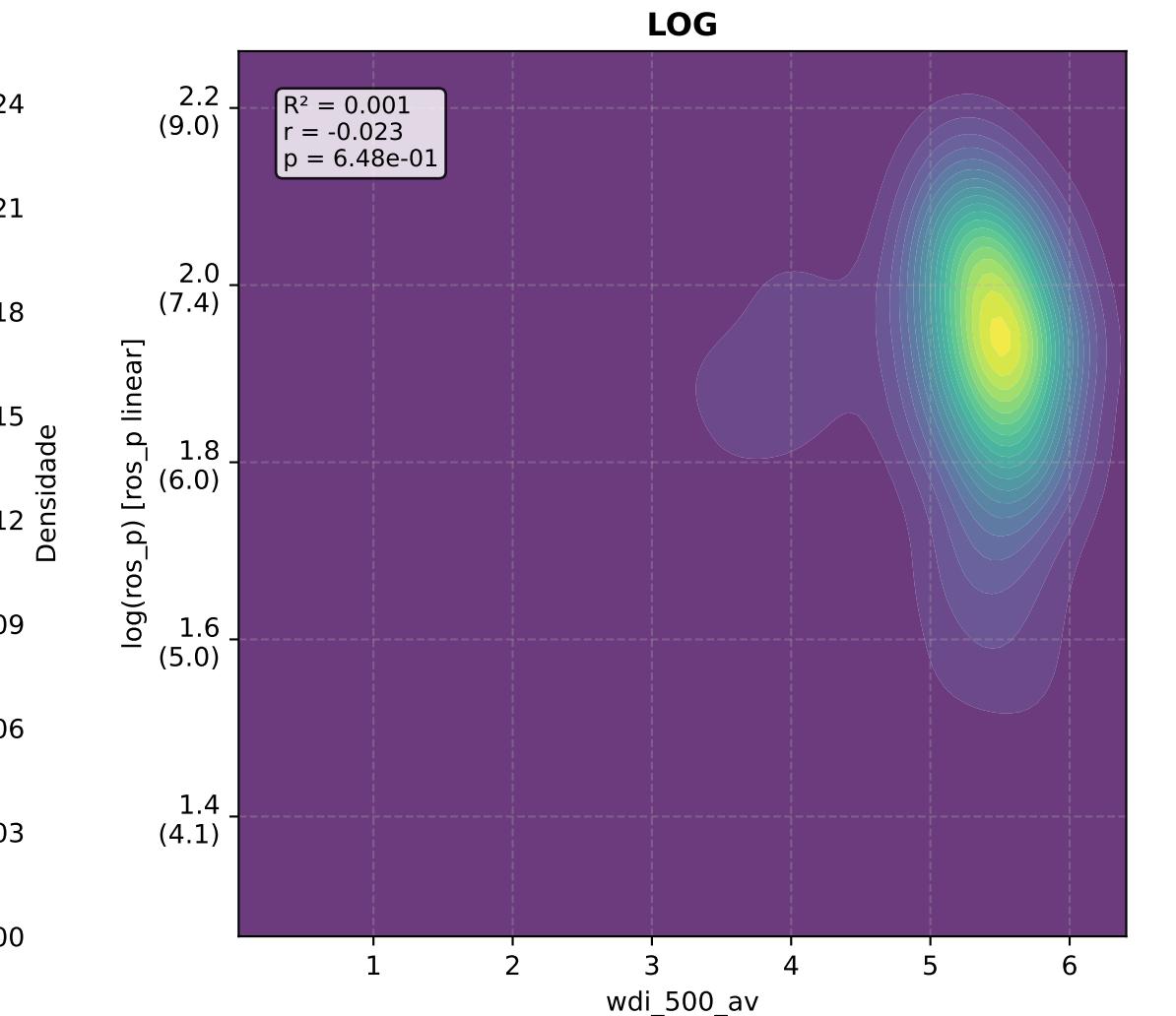
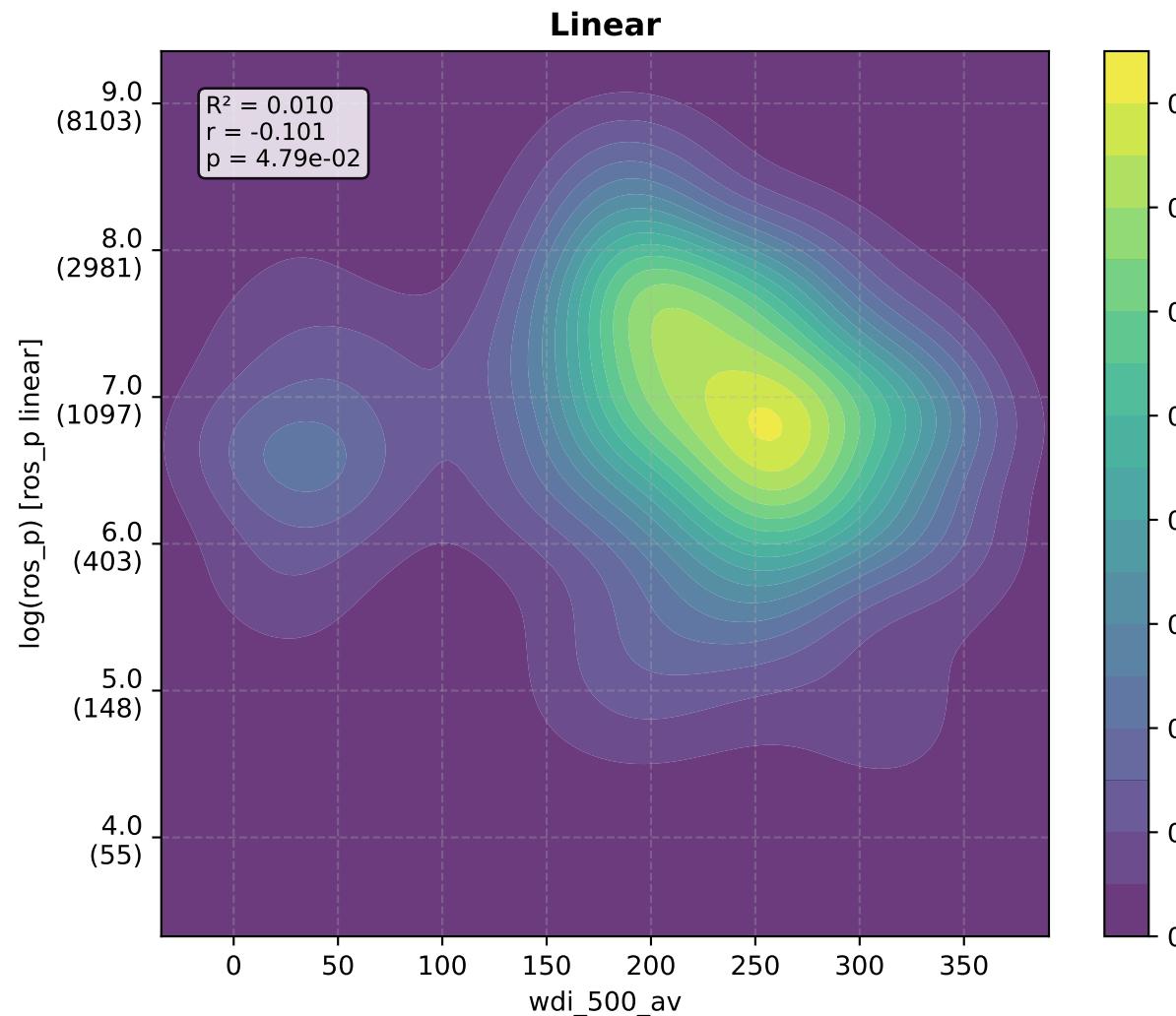
wdi_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



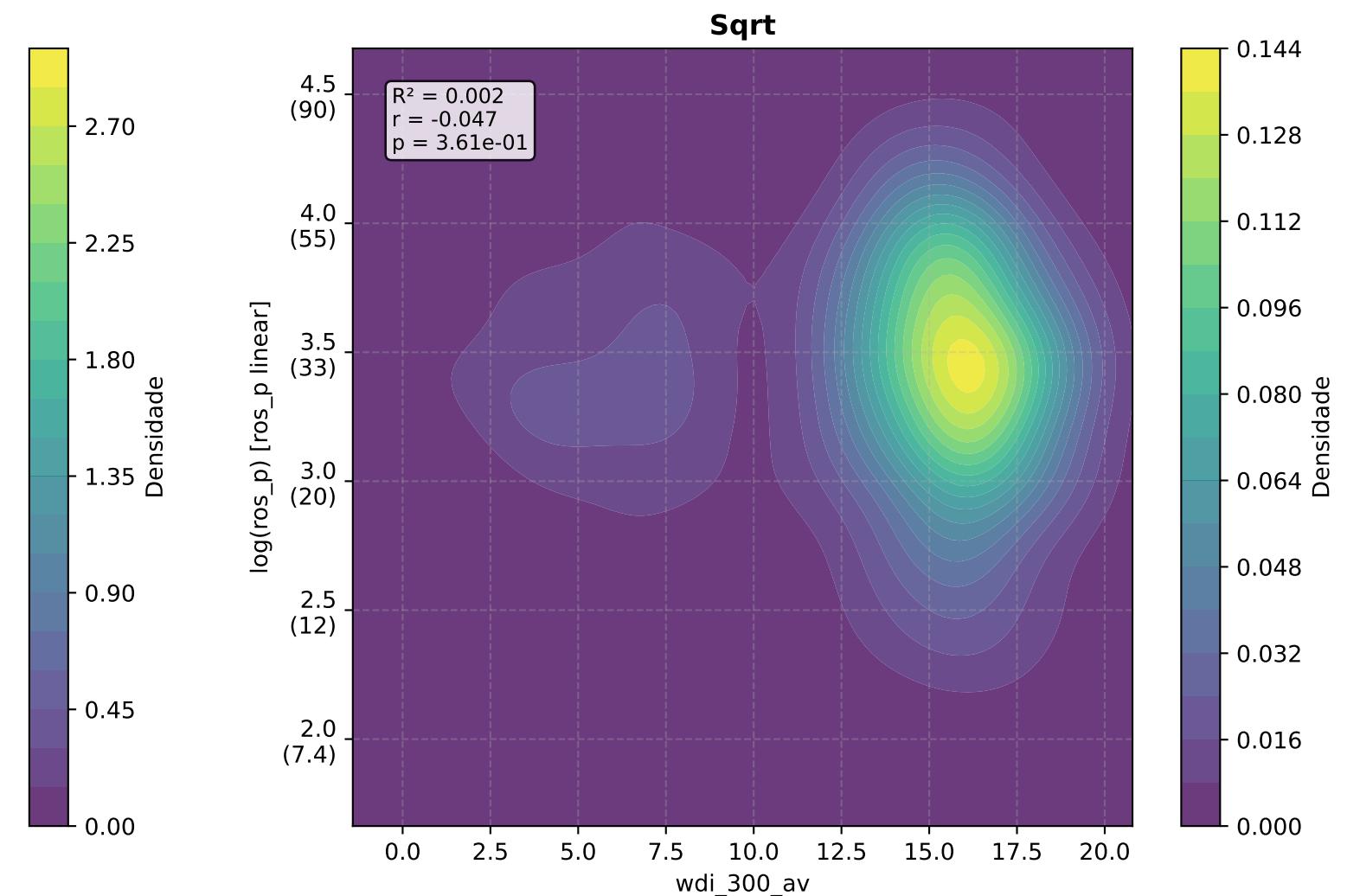
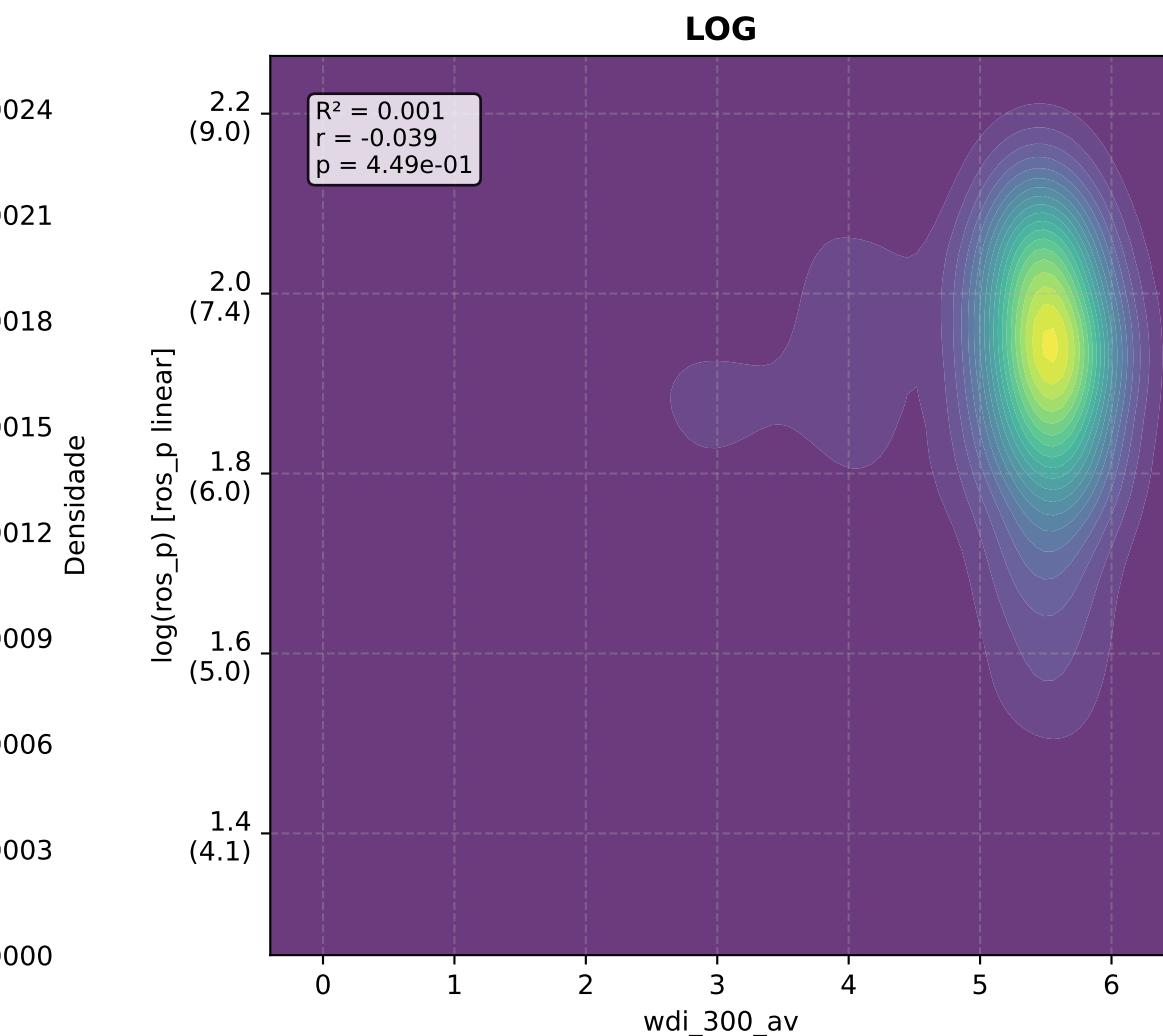
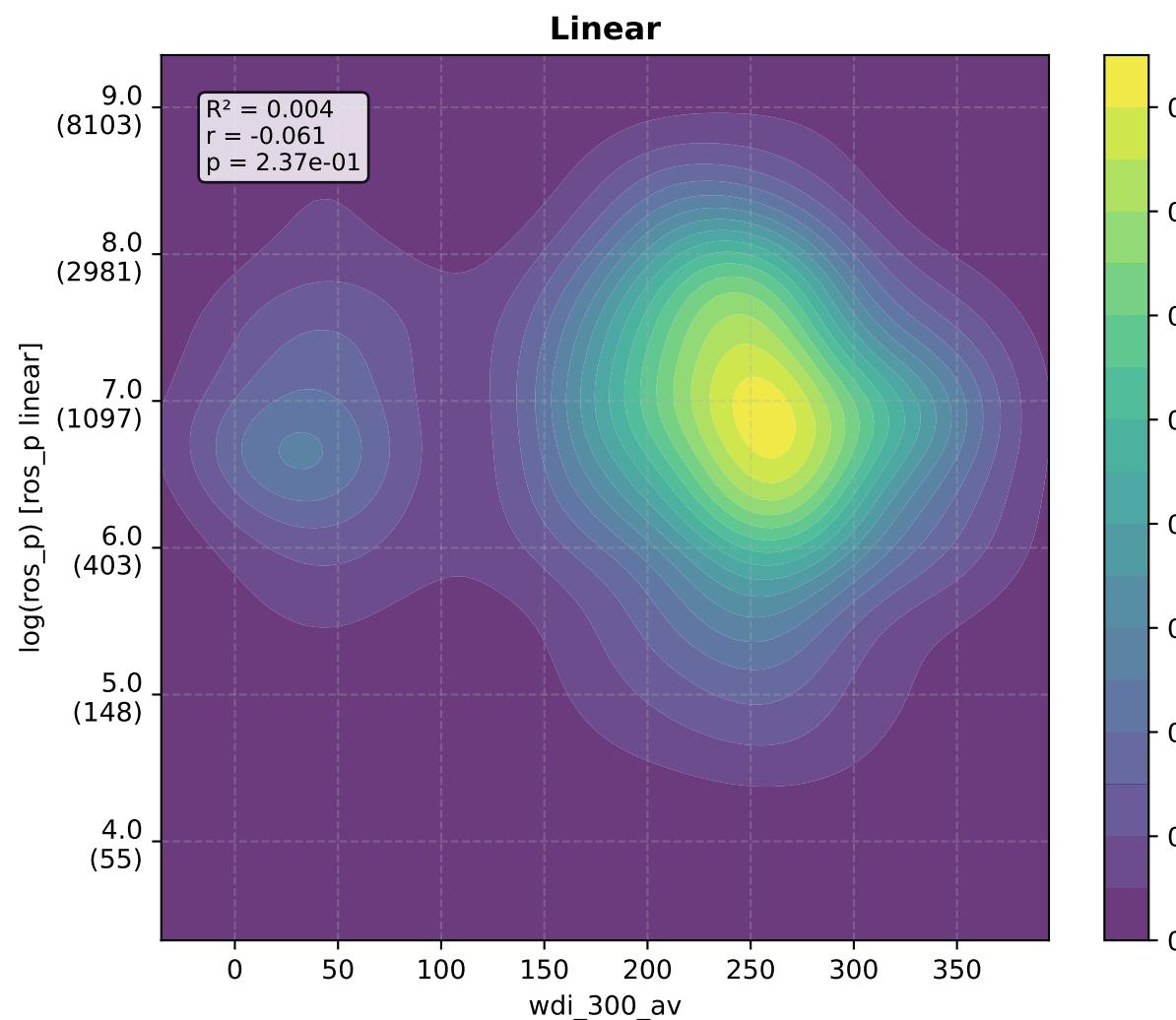
wdi_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



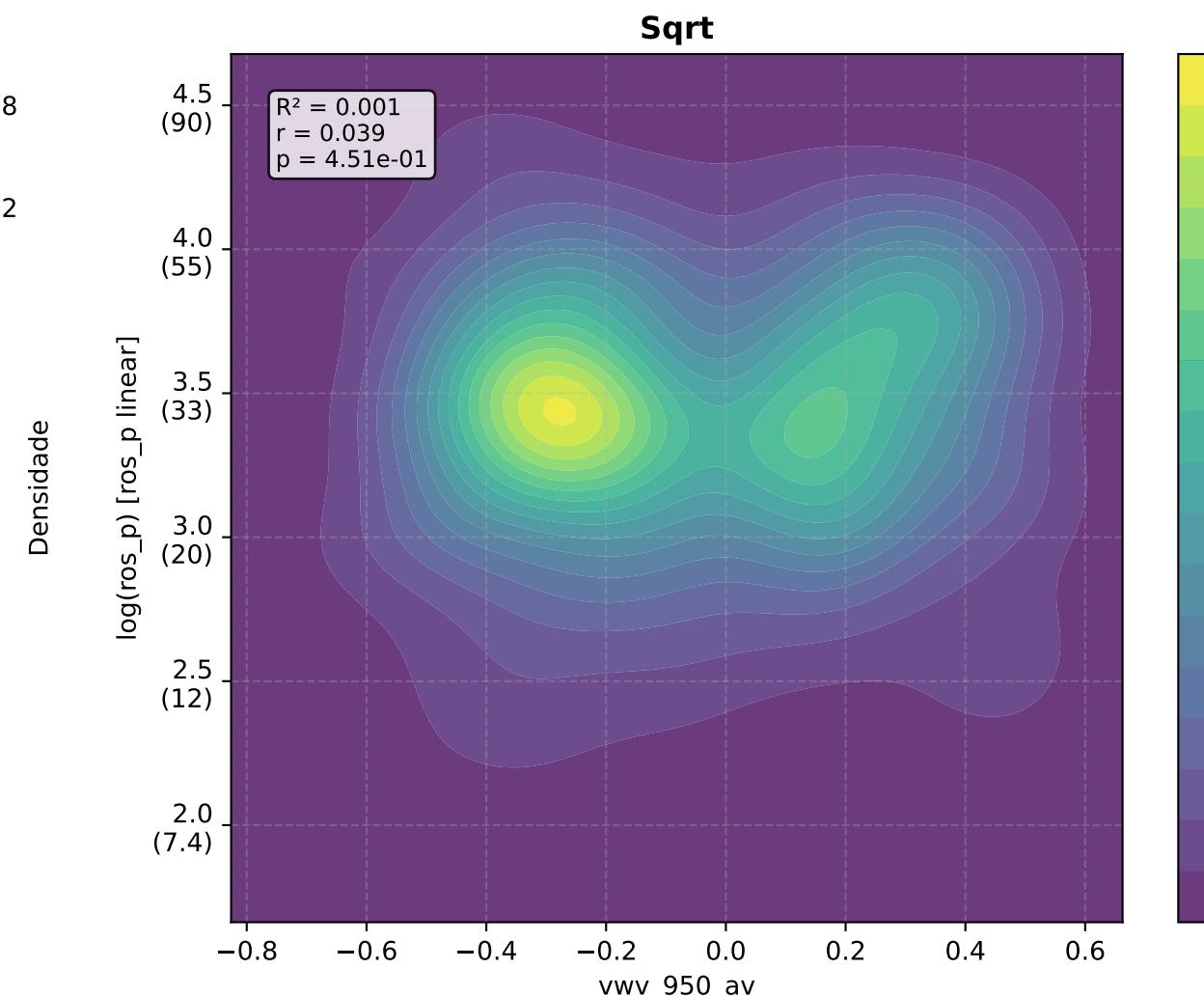
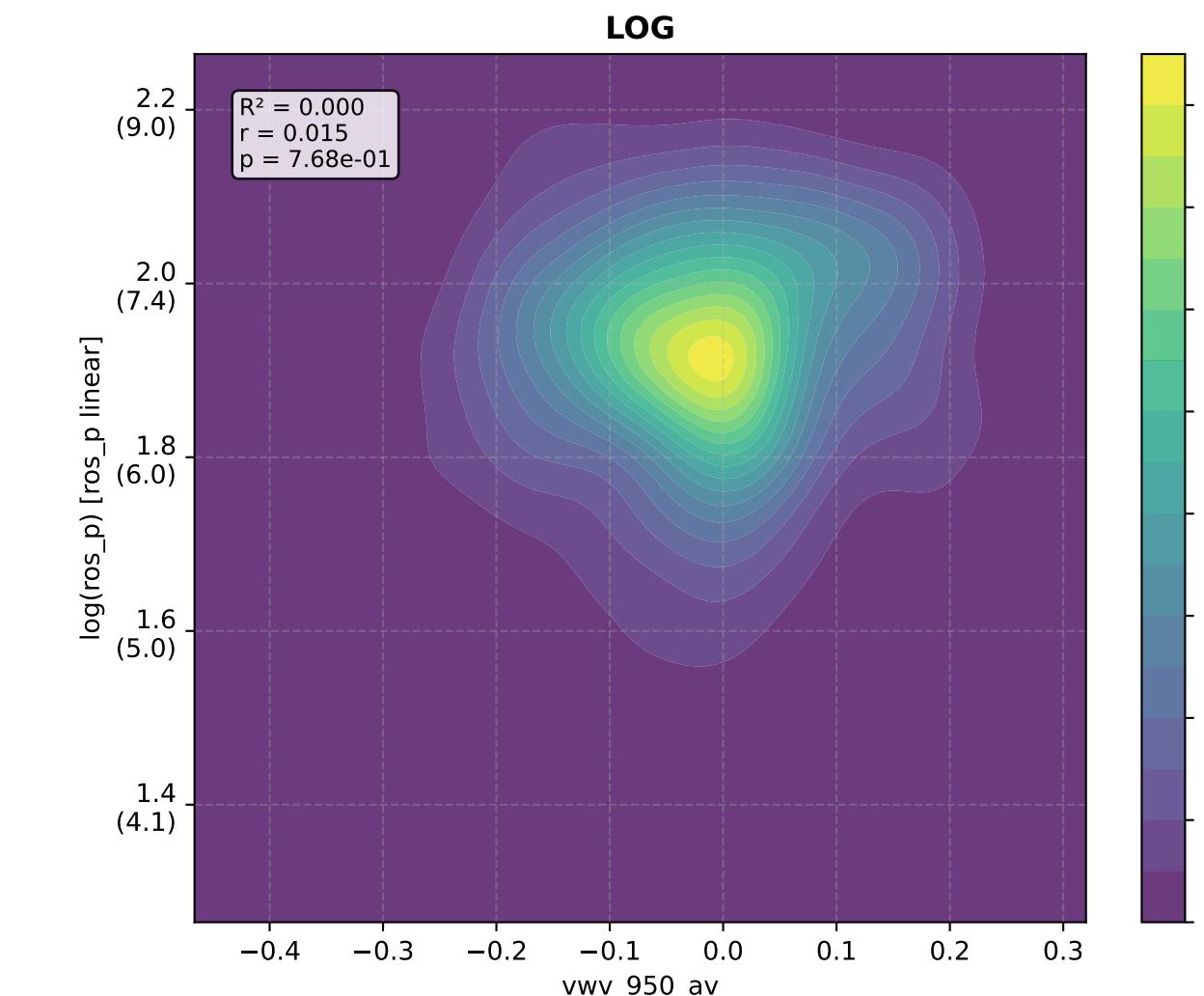
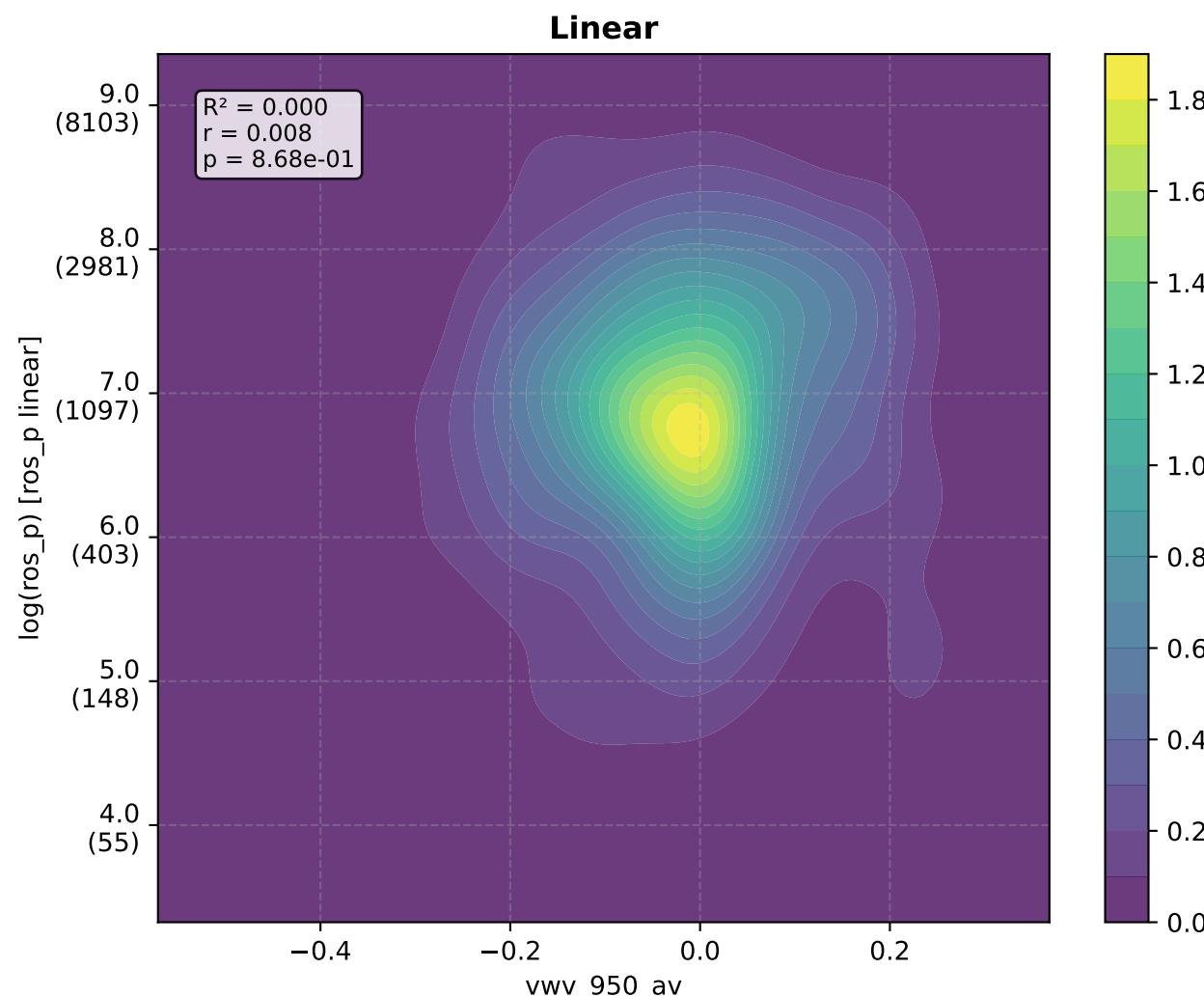
wdi_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



wdi_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



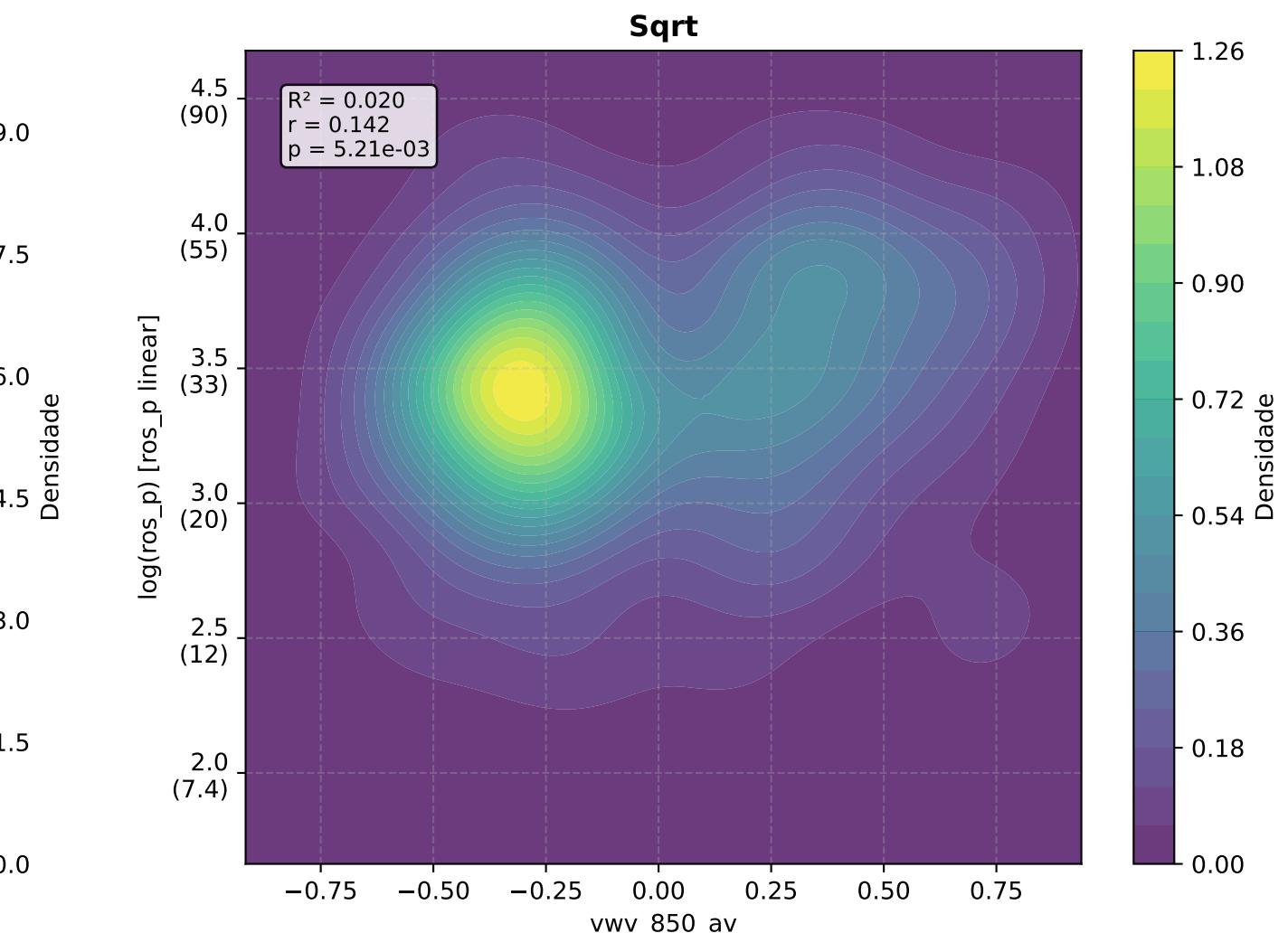
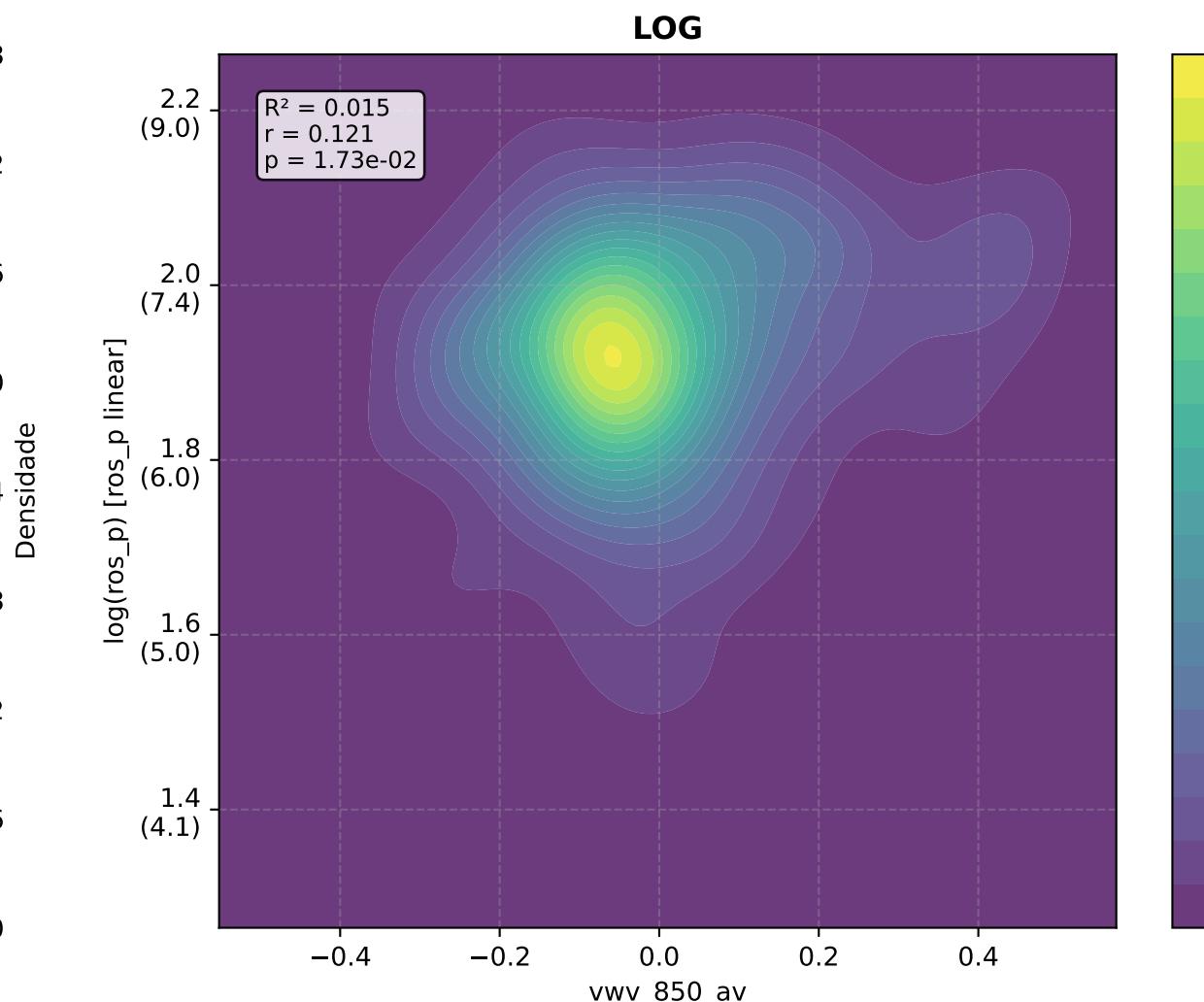
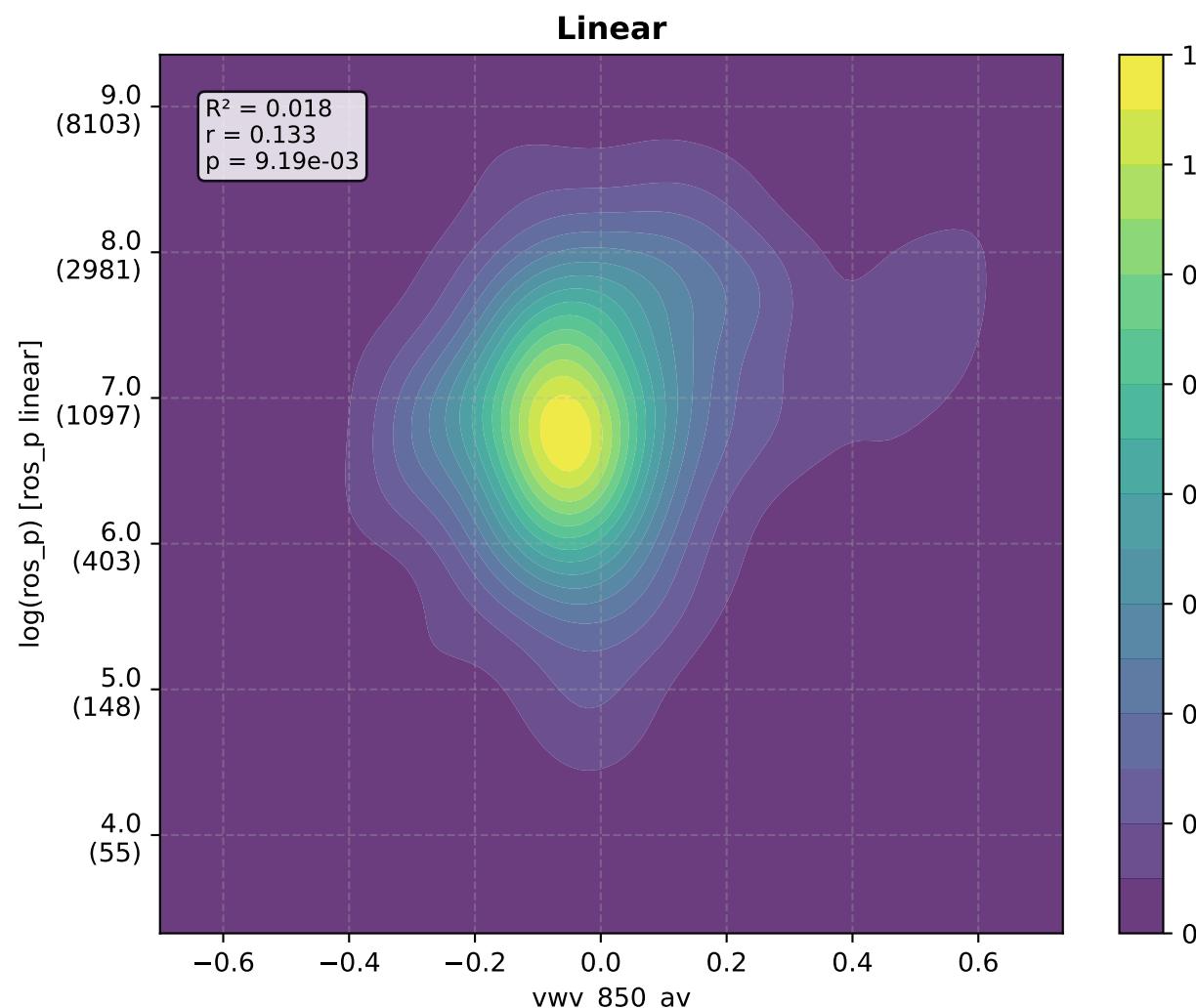
vwv_950_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



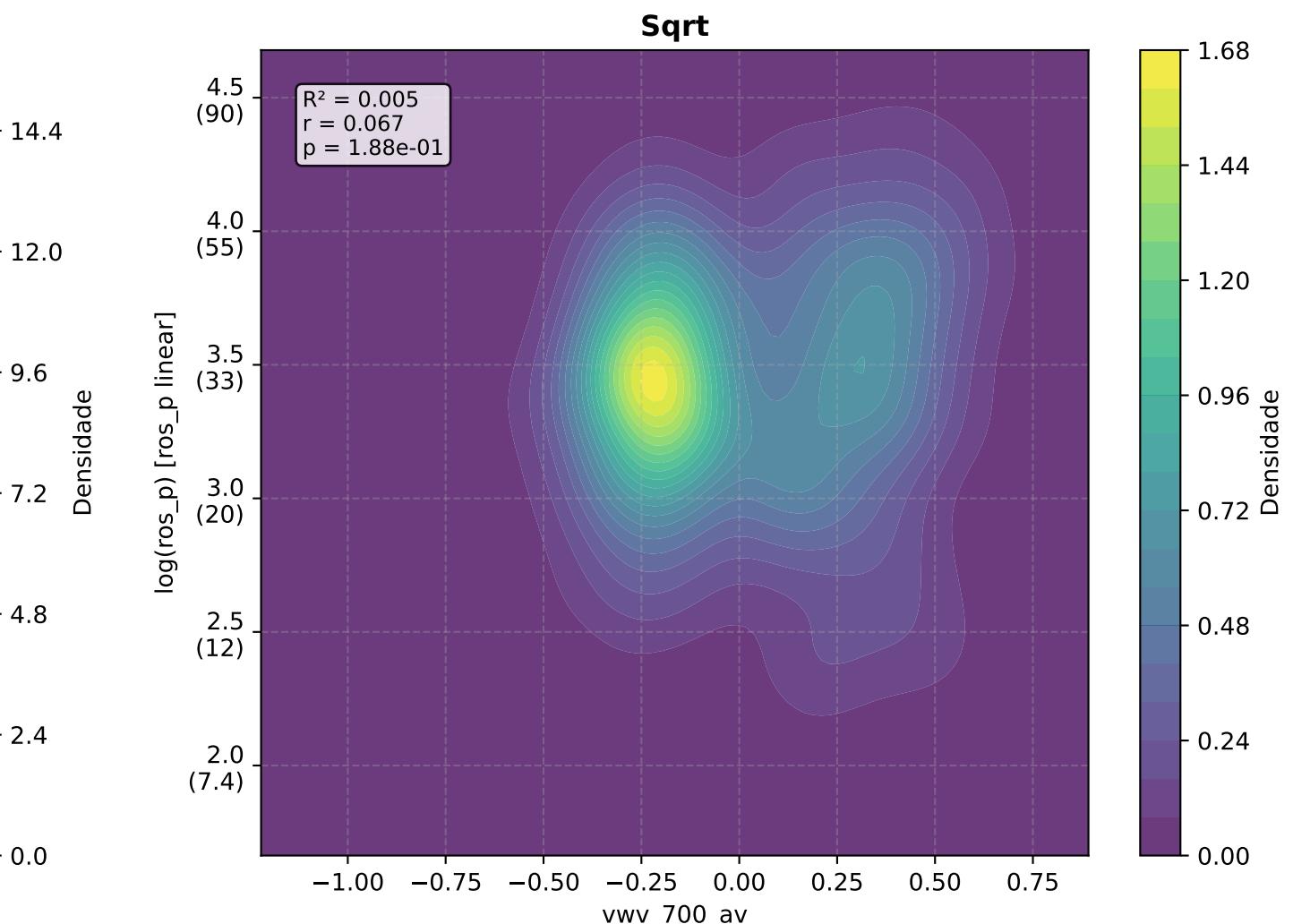
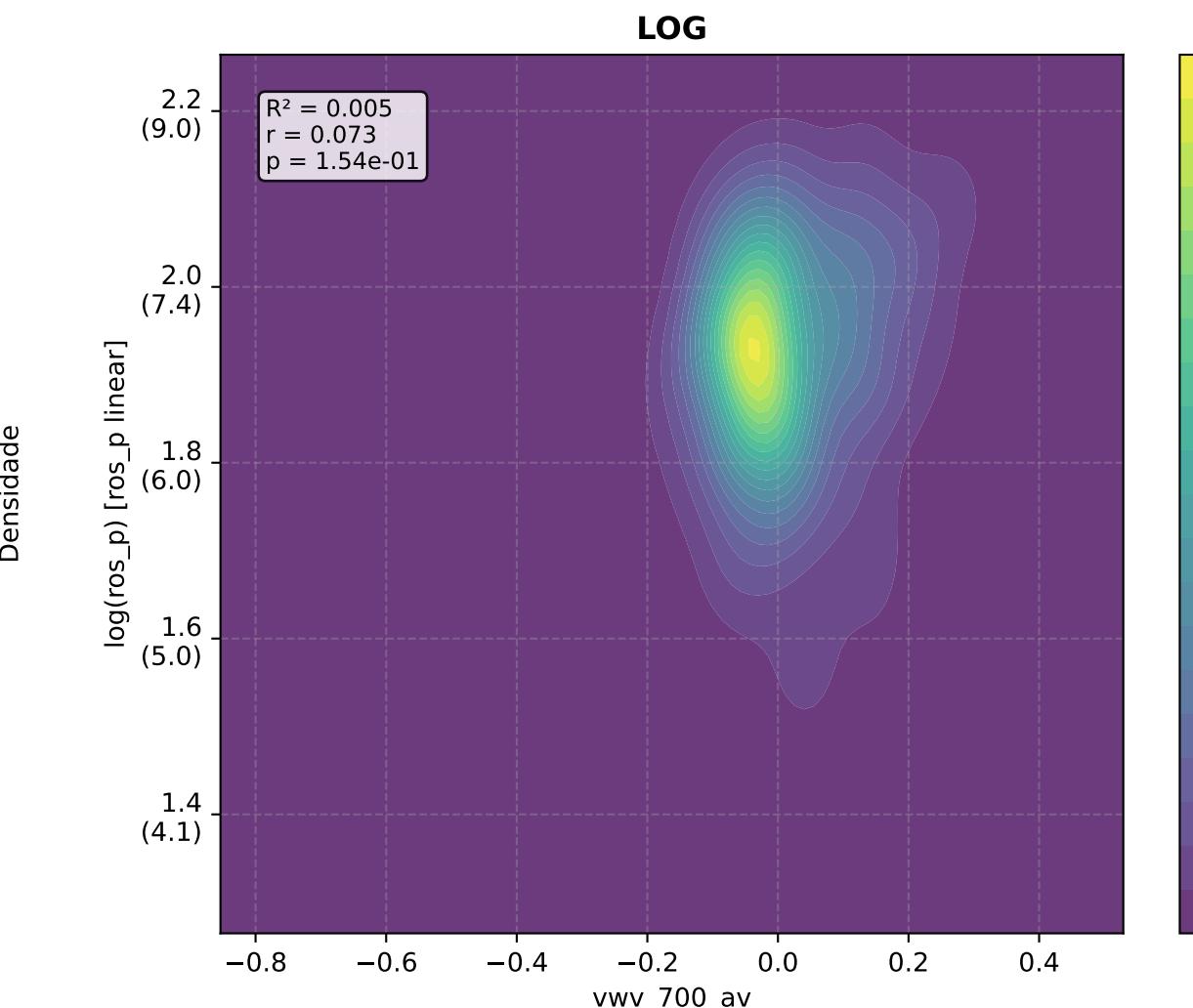
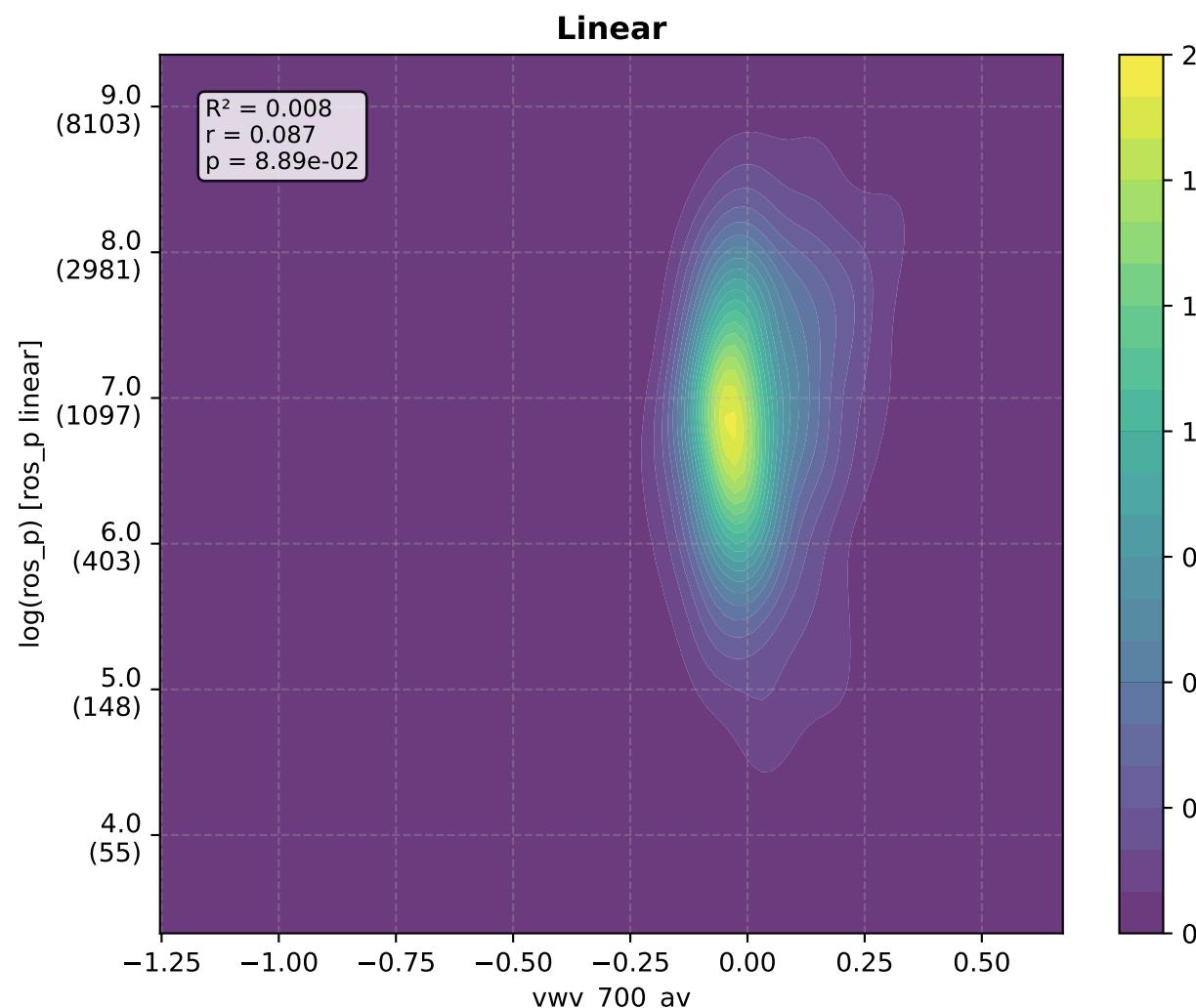
Densidade

Densidade

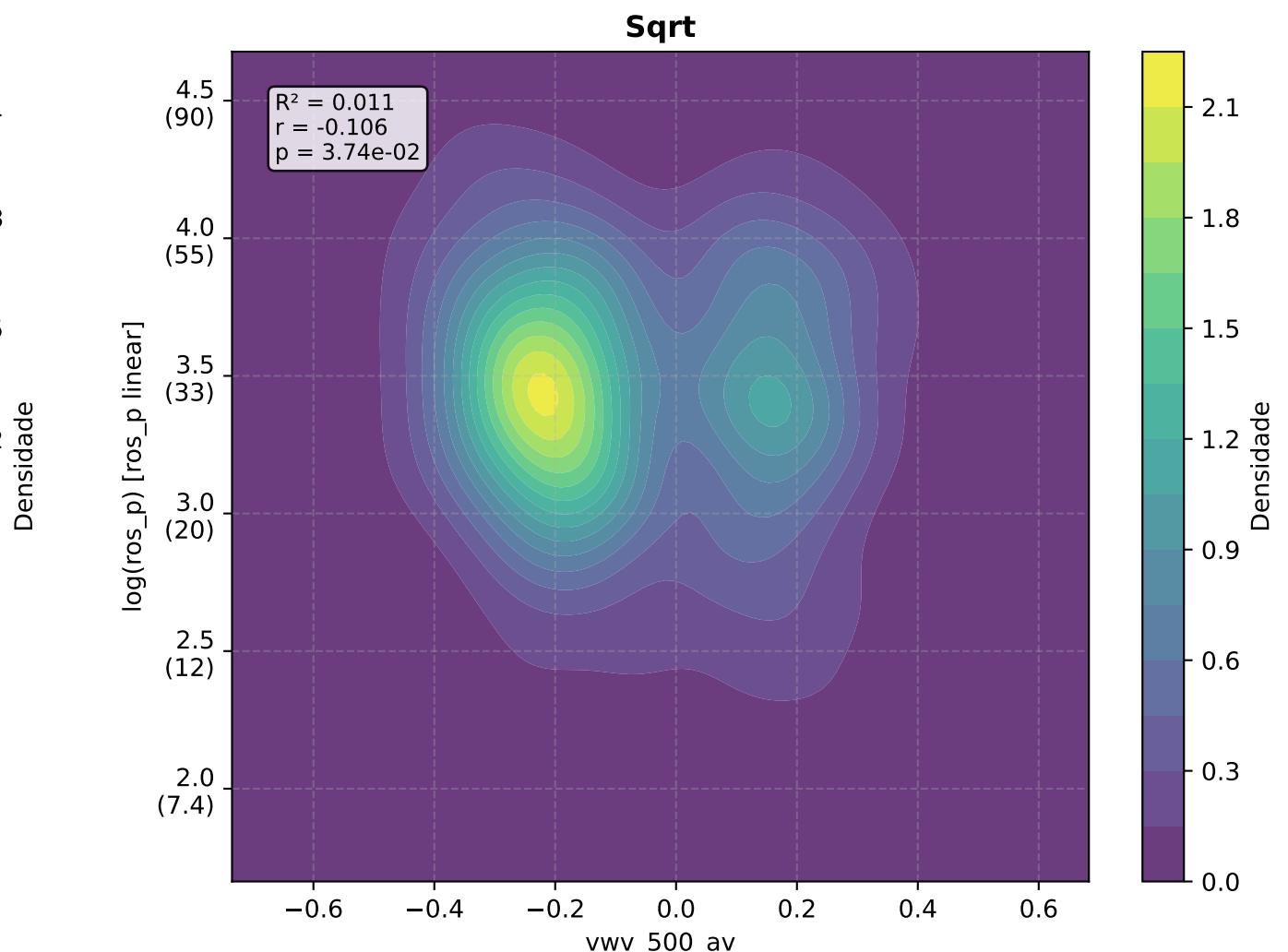
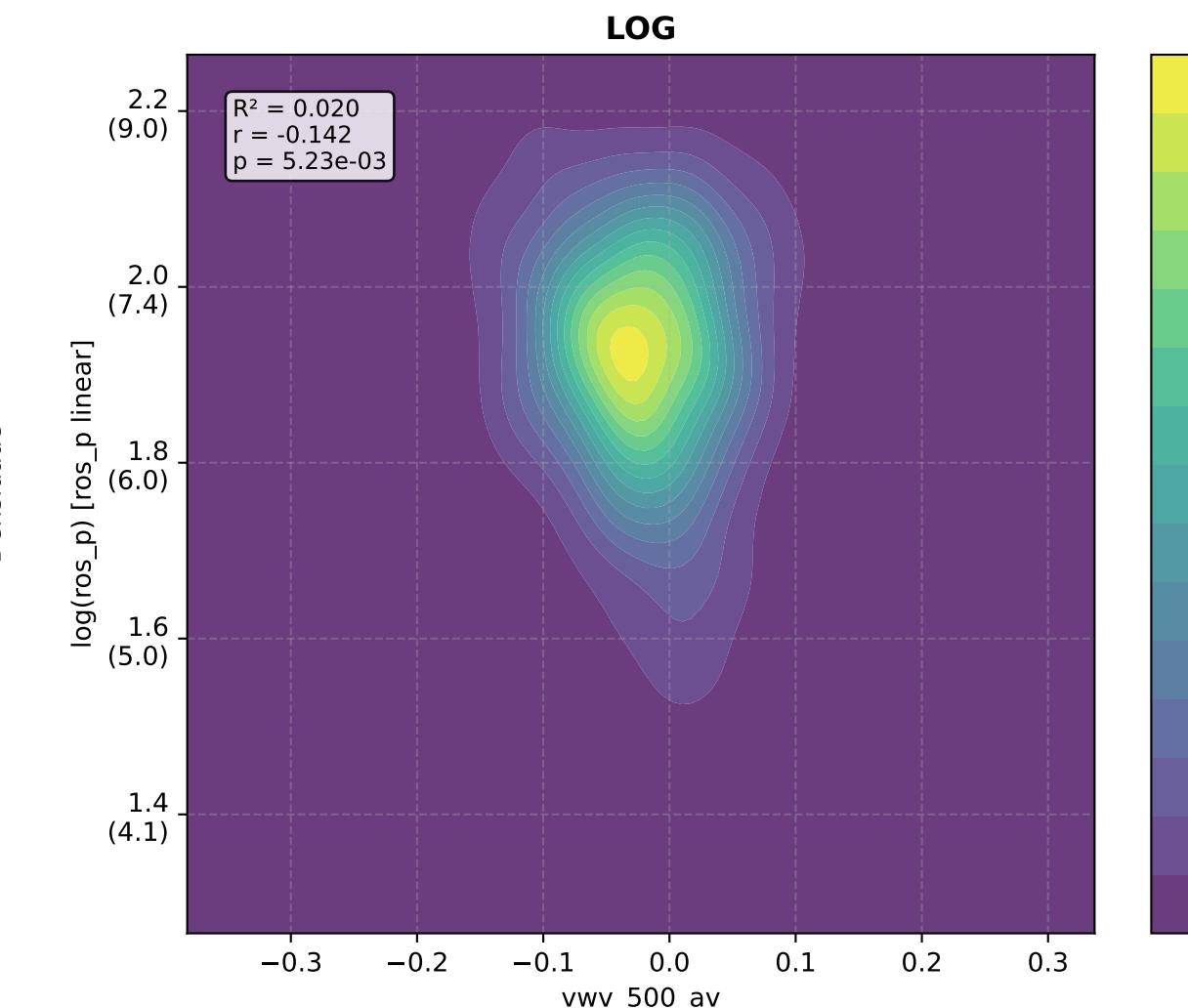
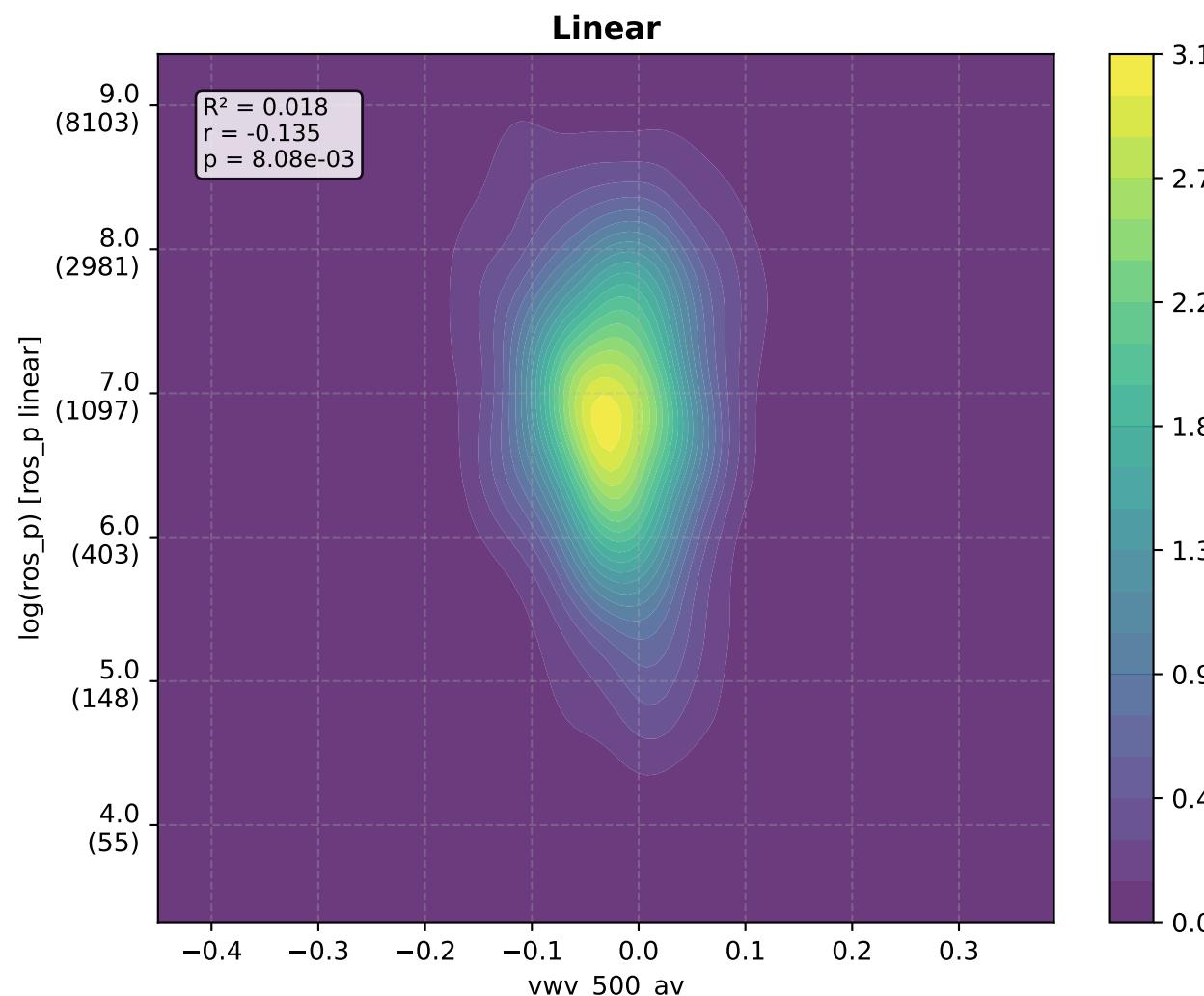
vwv_850_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



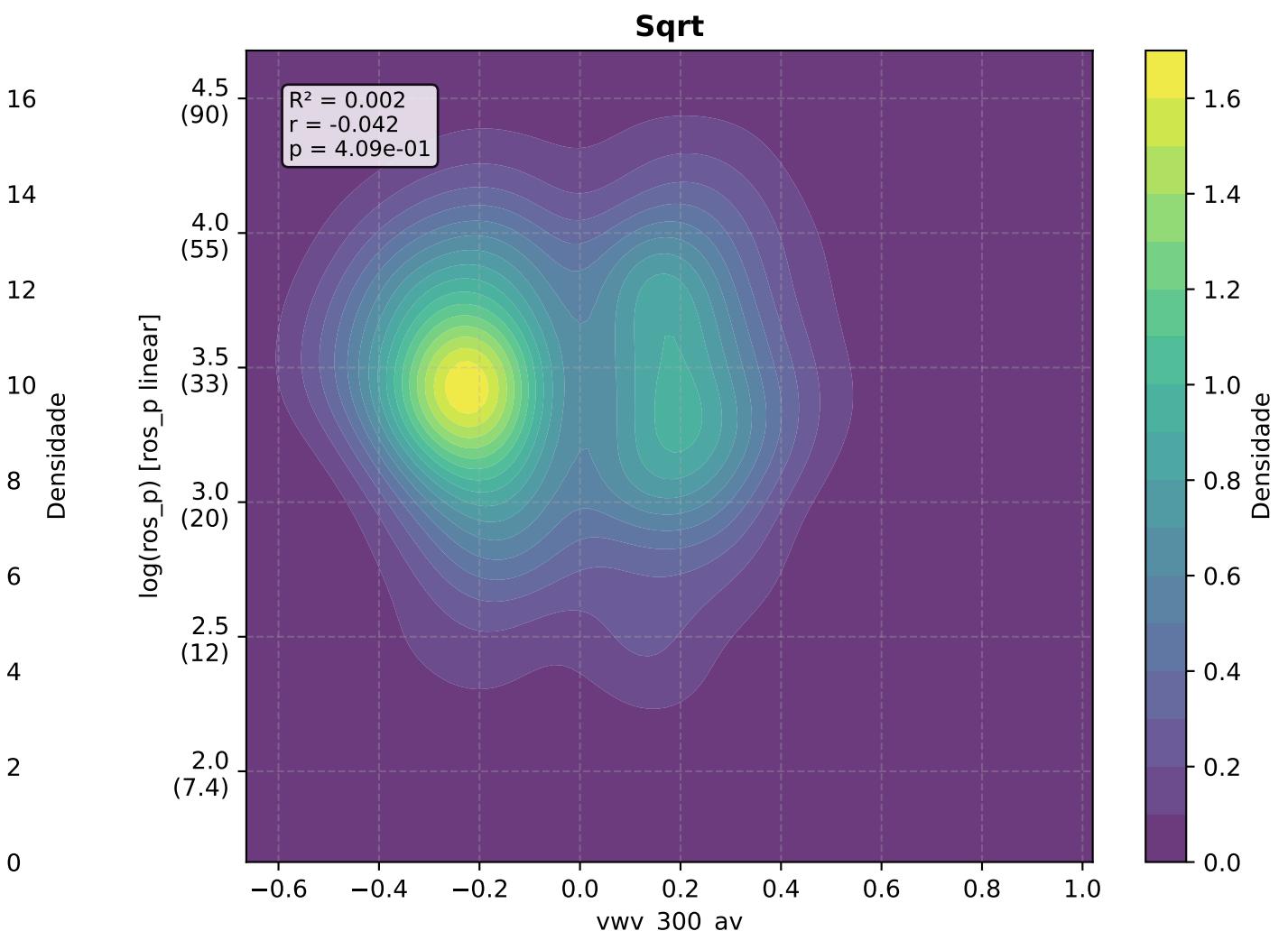
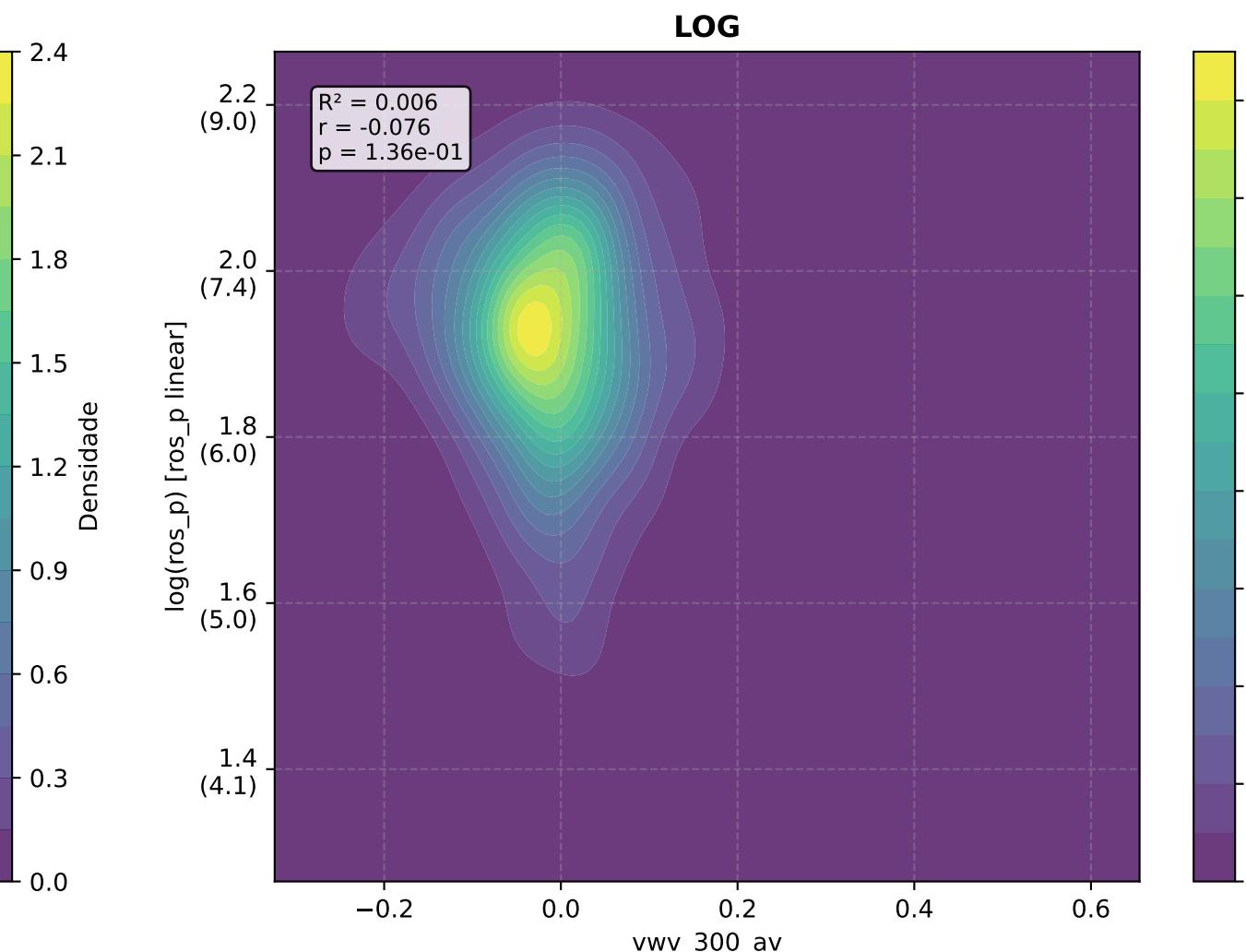
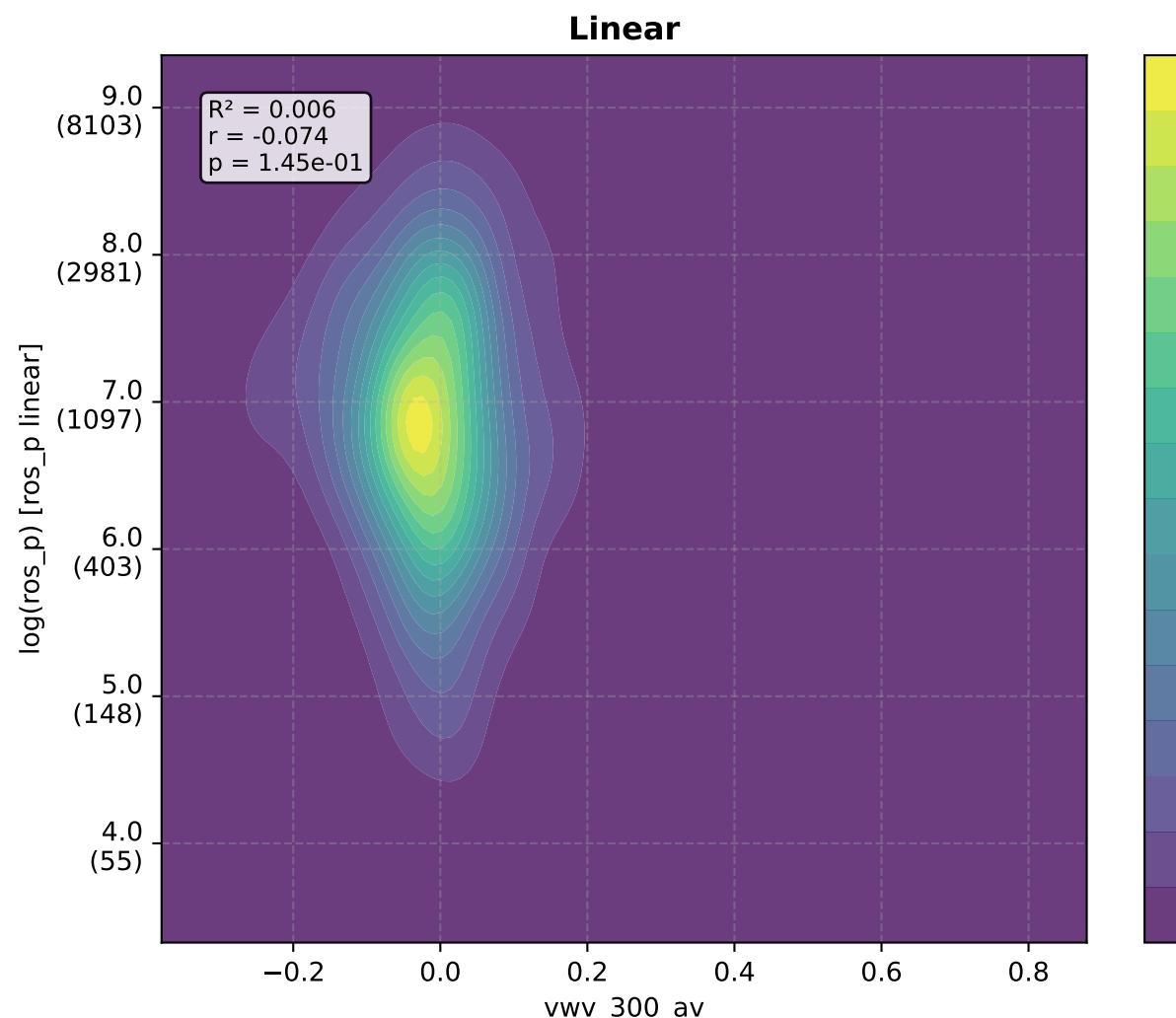
vwv_700_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



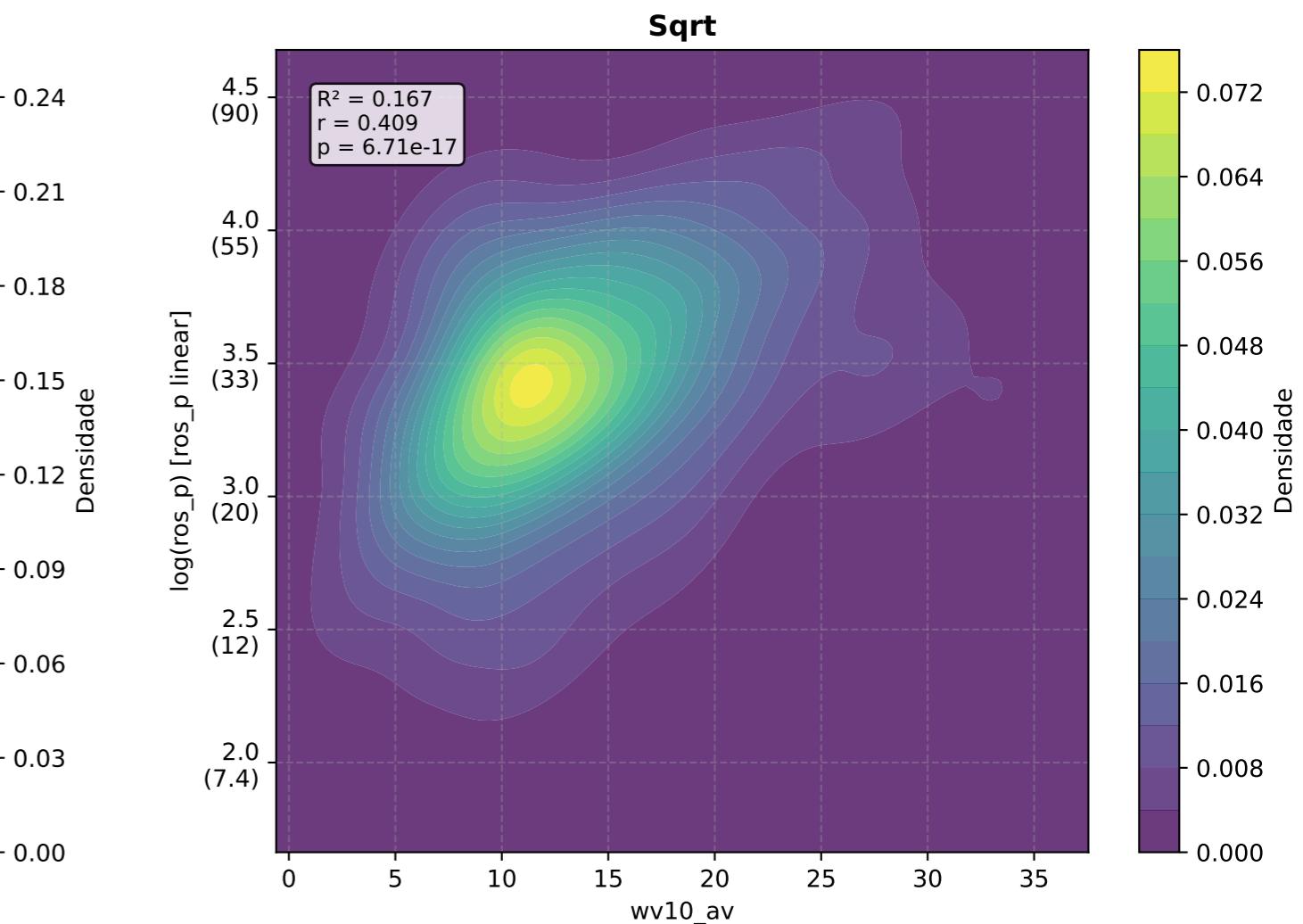
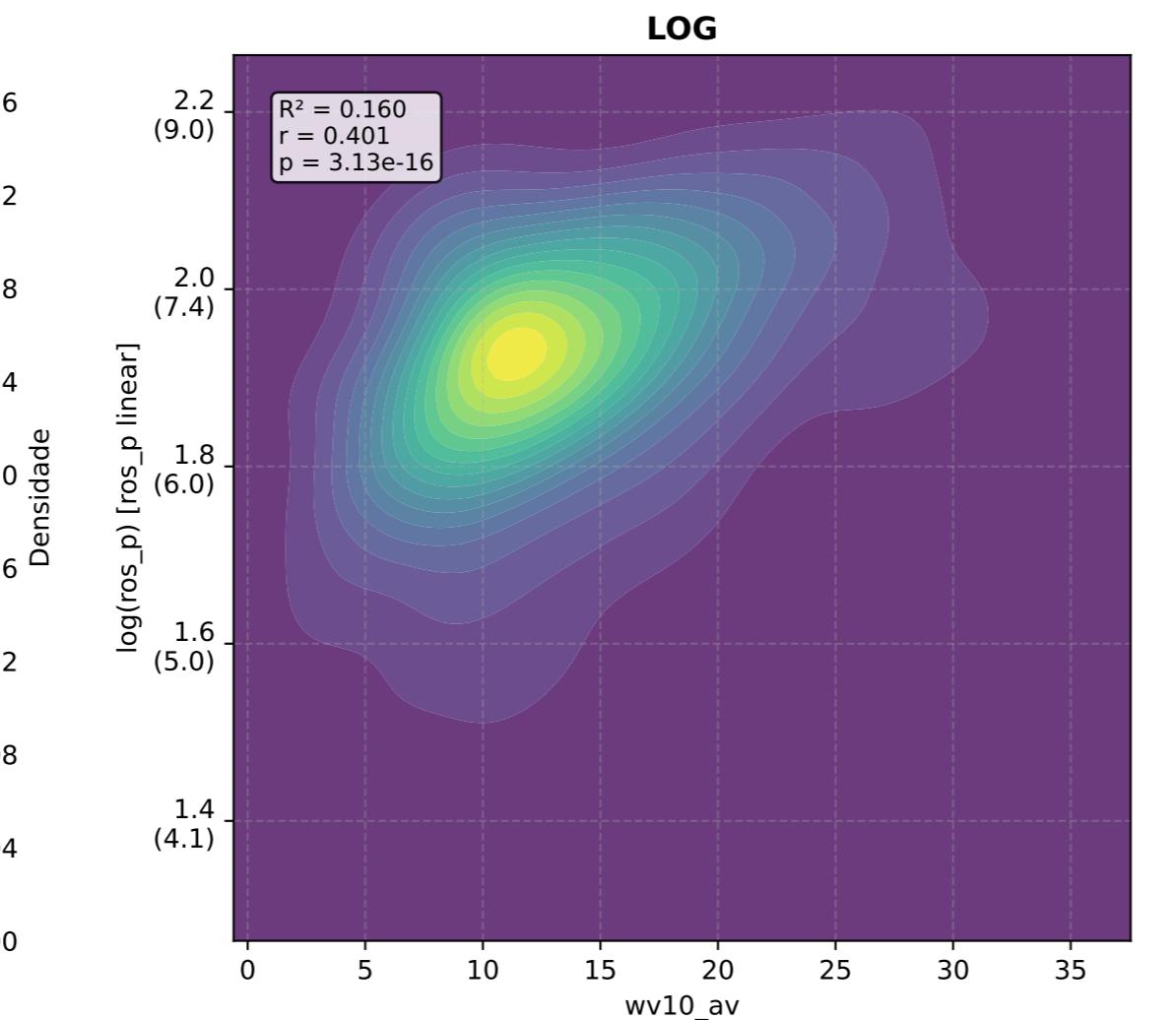
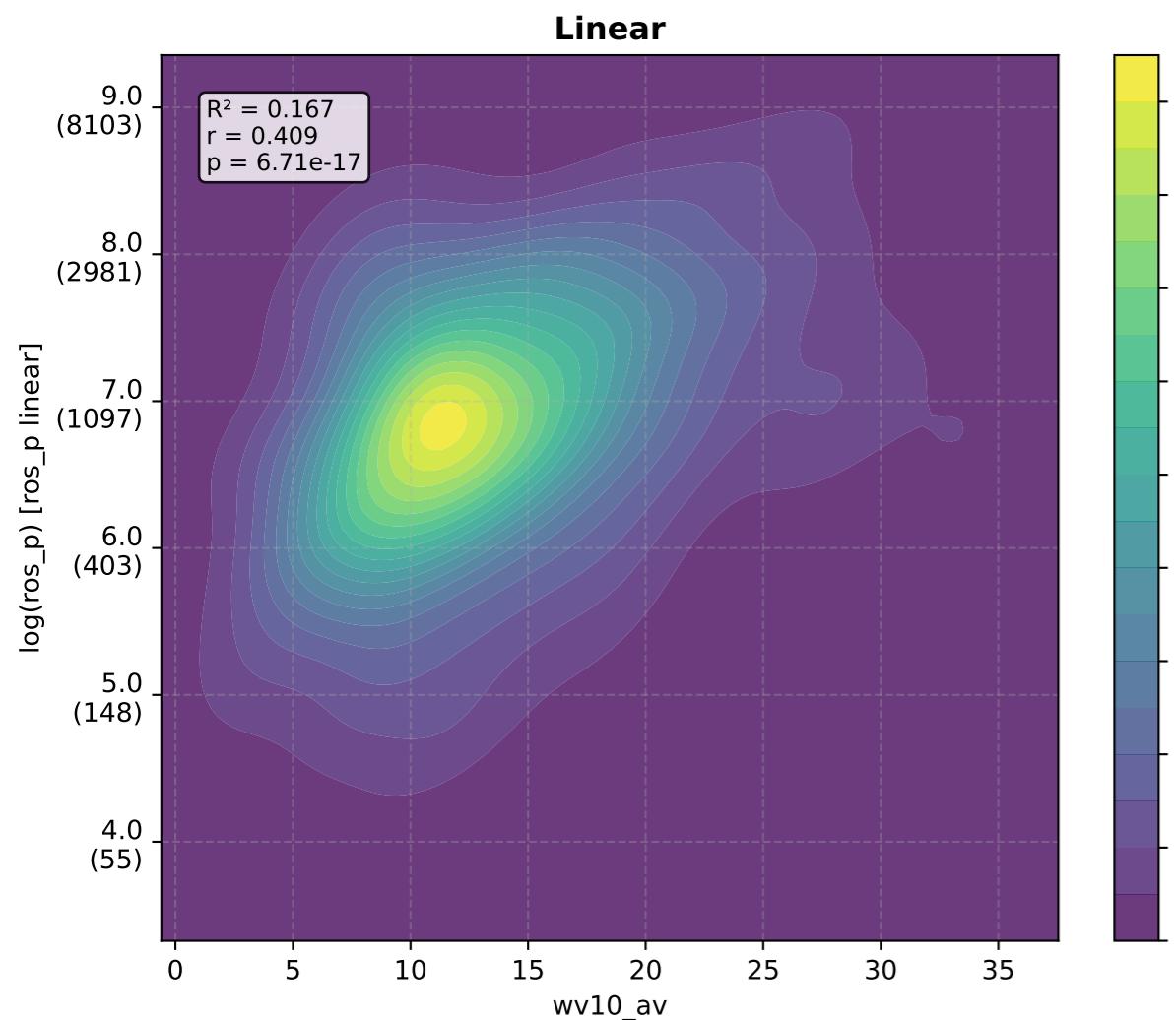
vwv_500_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



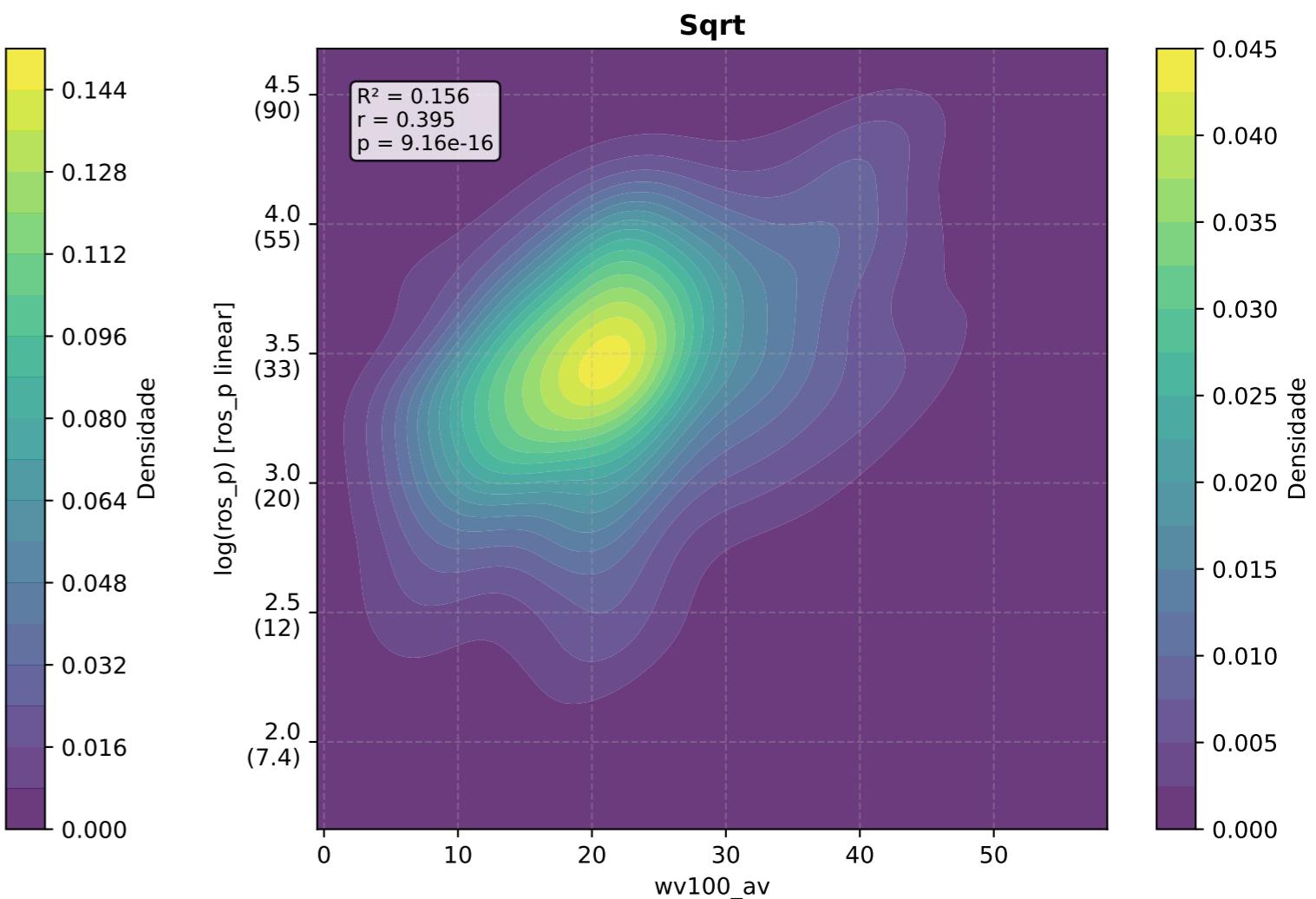
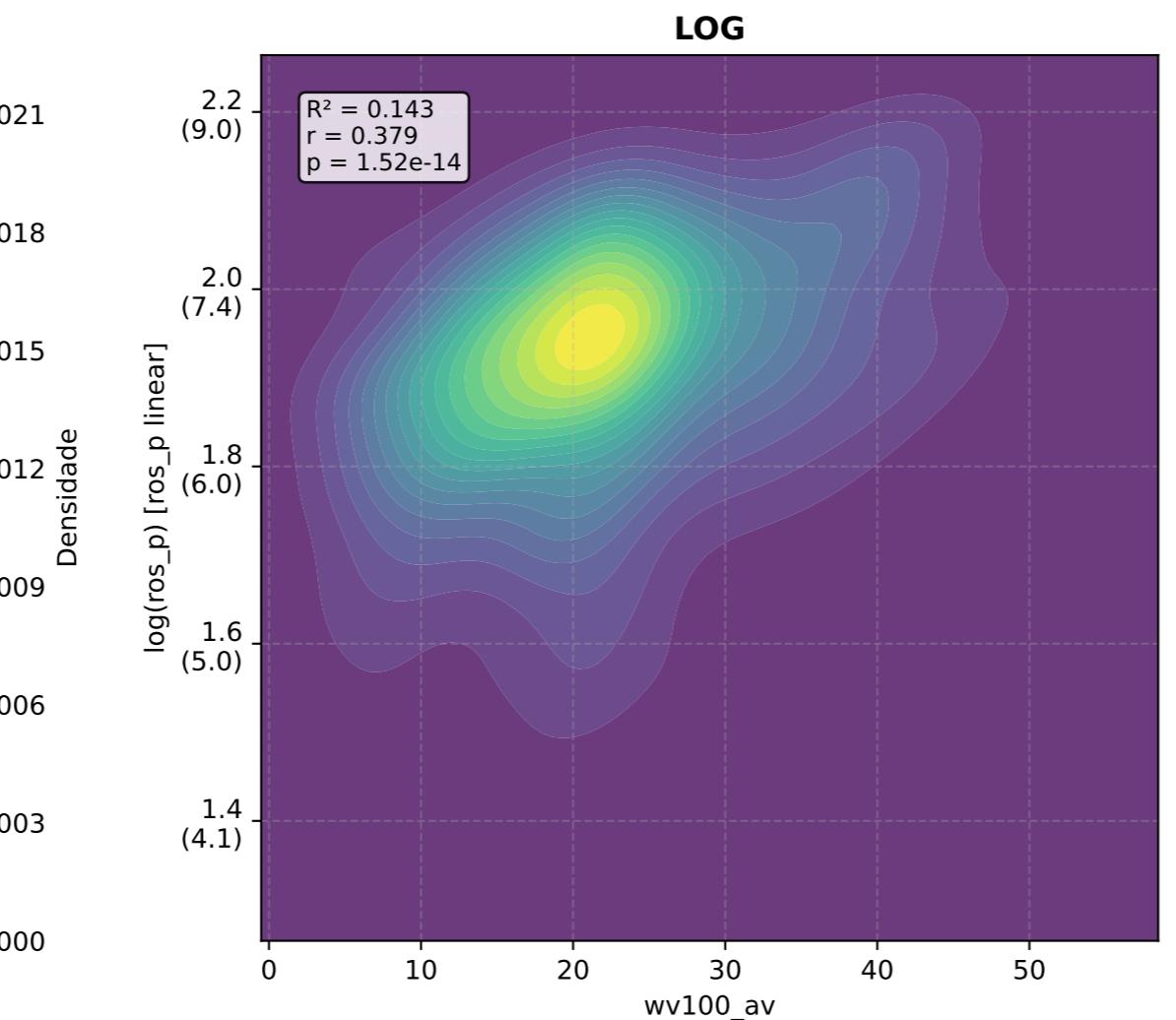
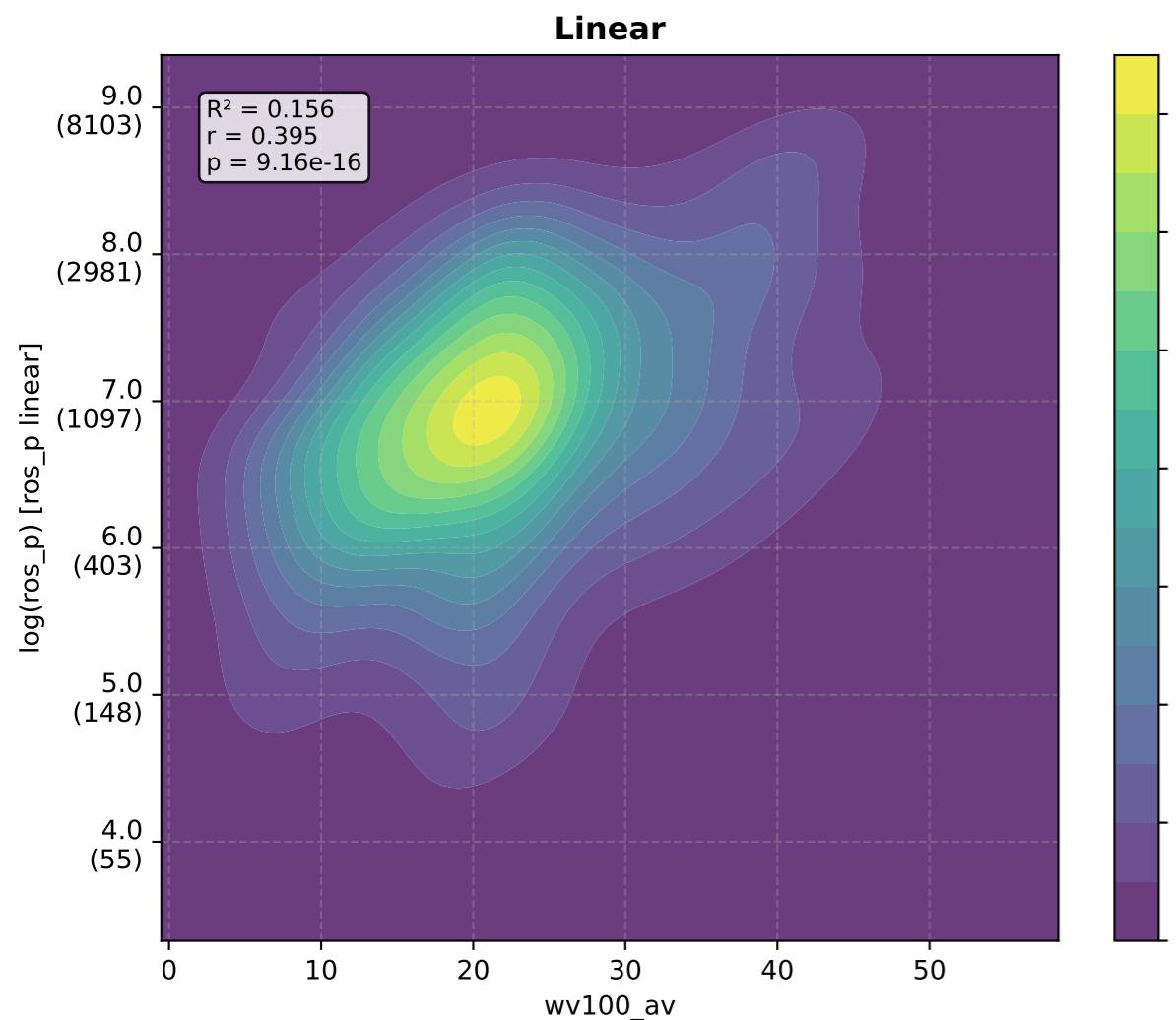
vwv_300_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



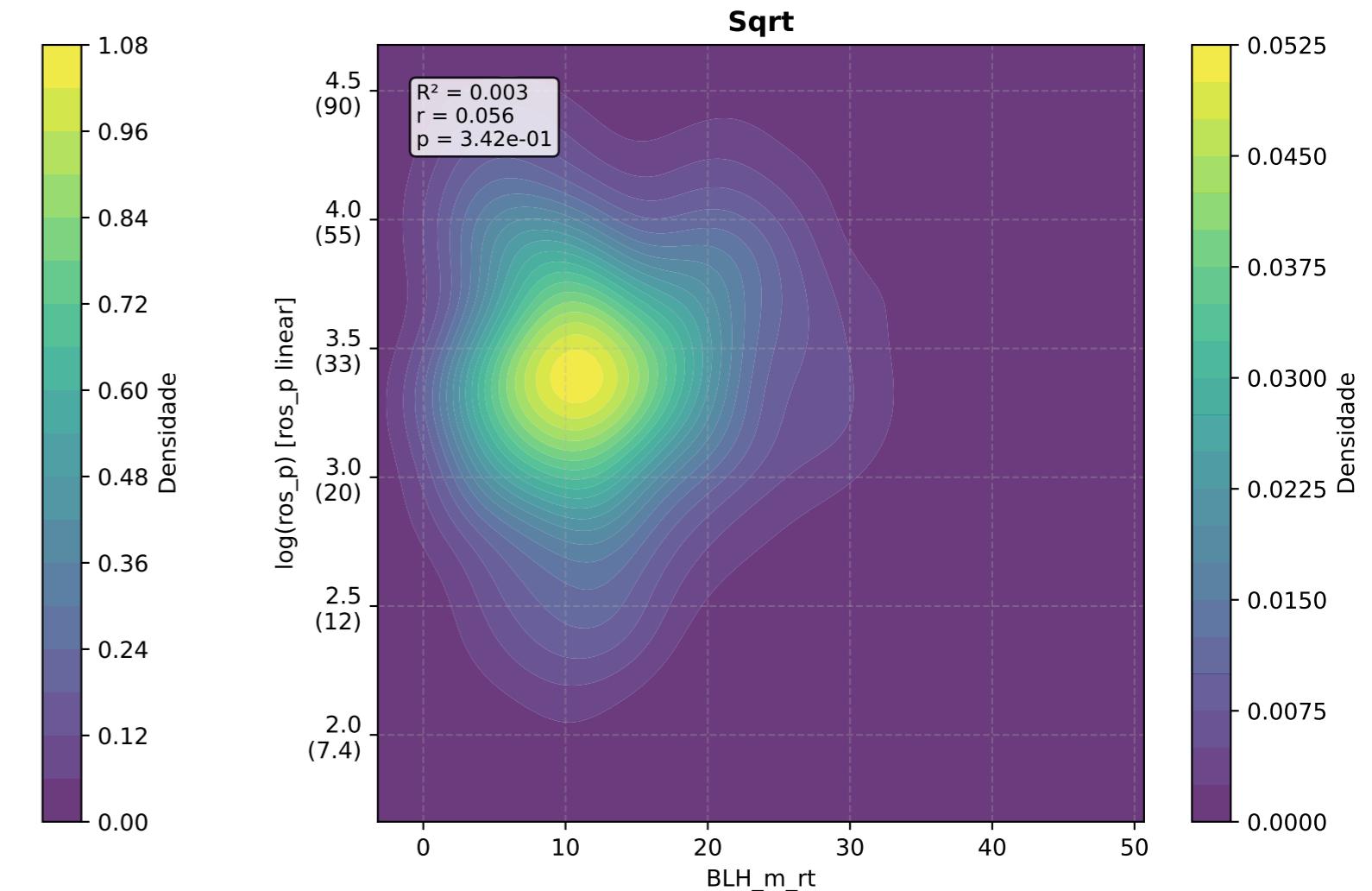
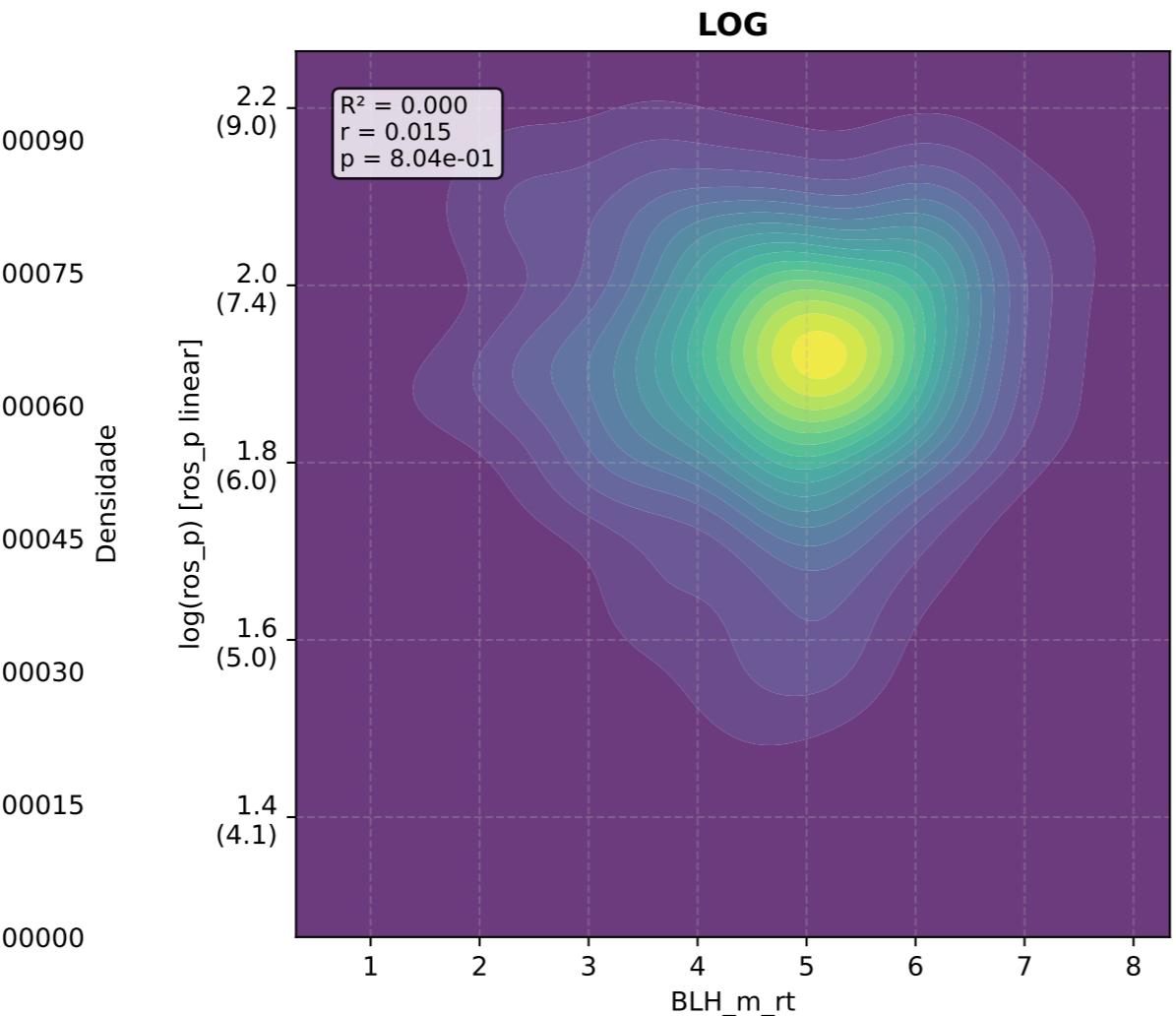
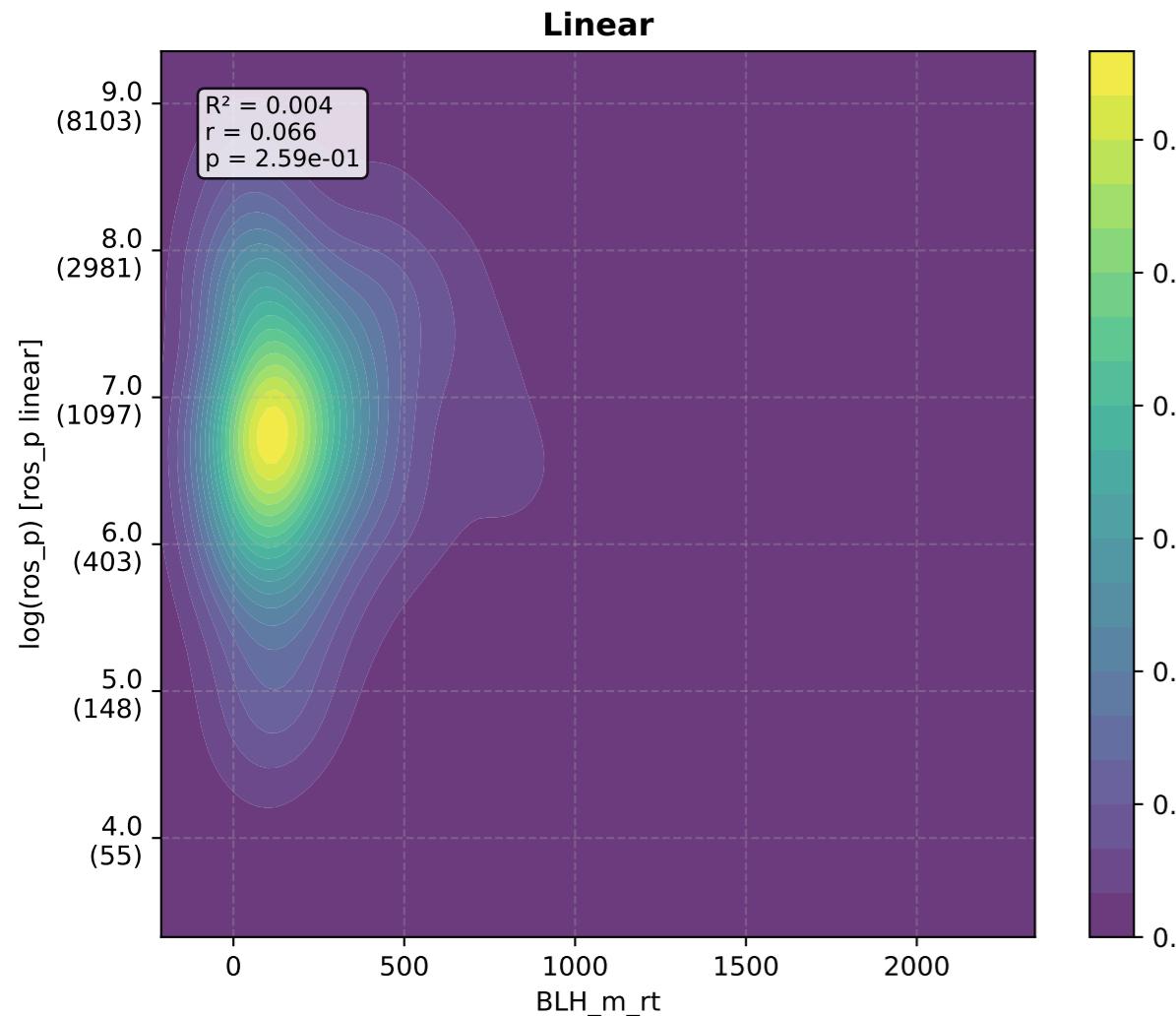
wv10_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



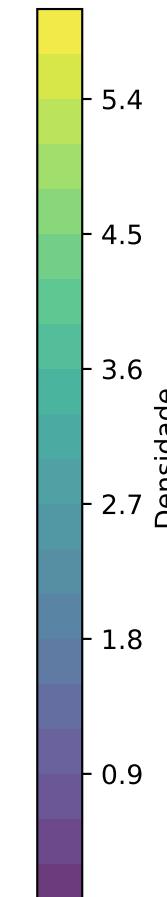
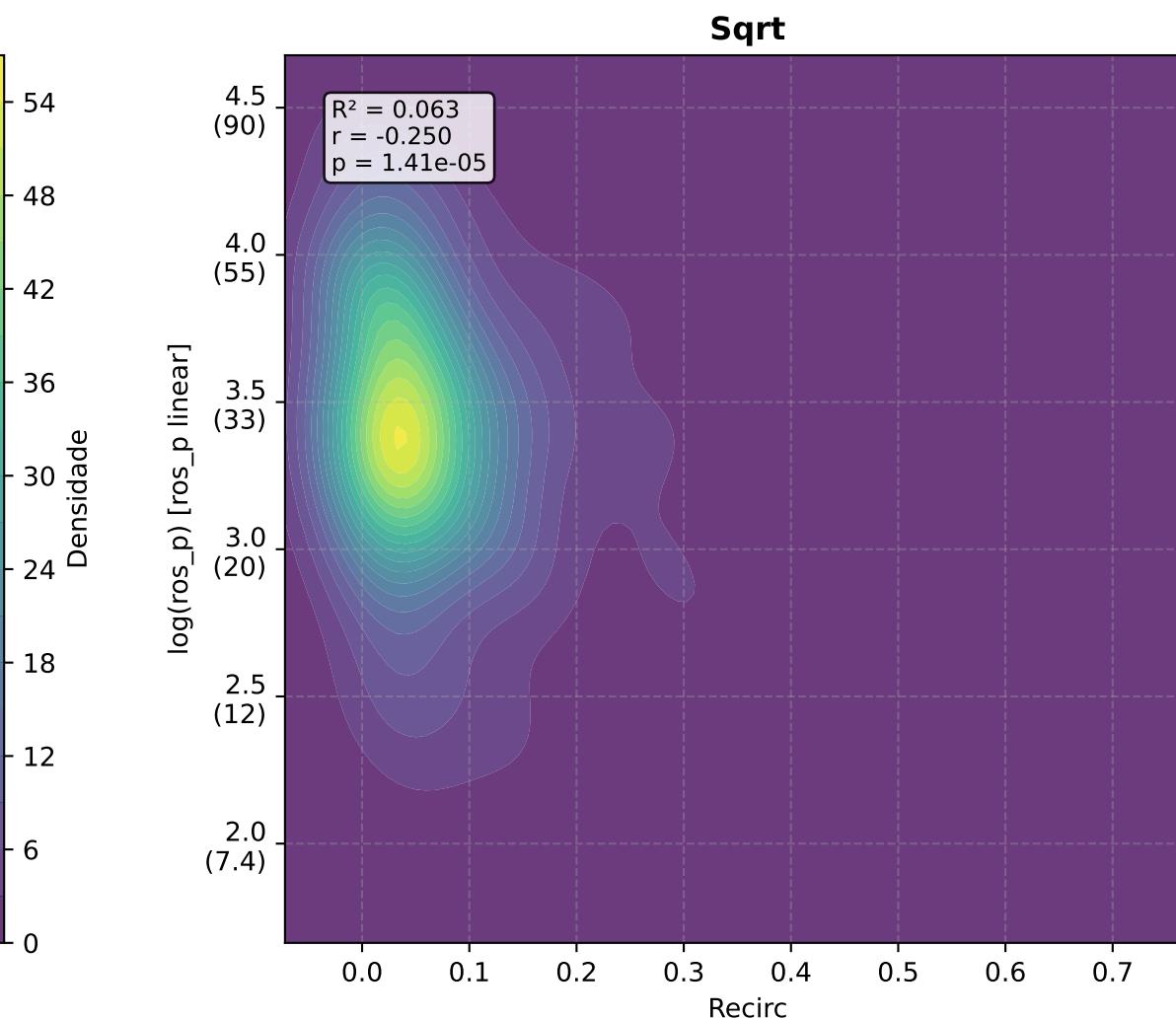
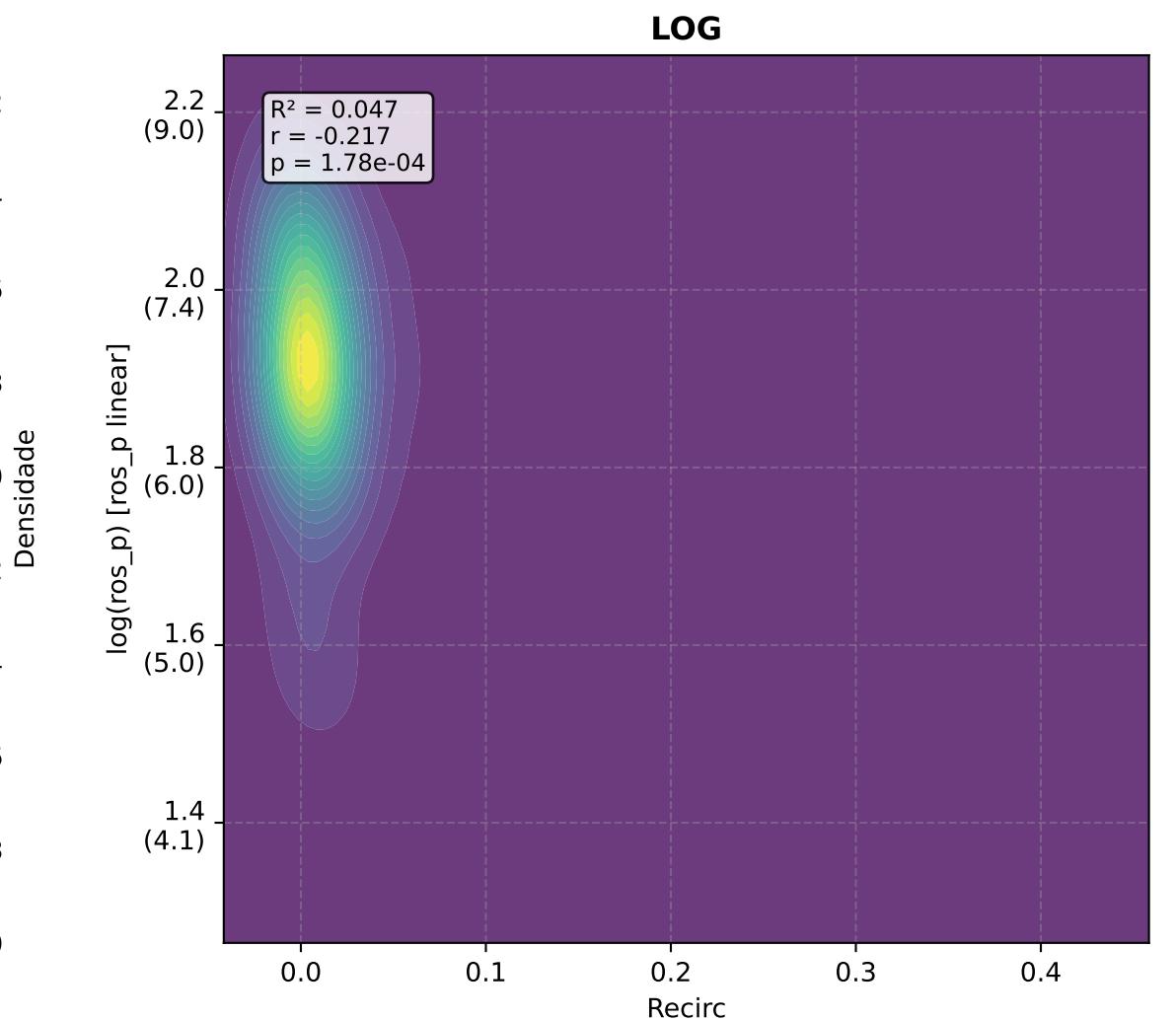
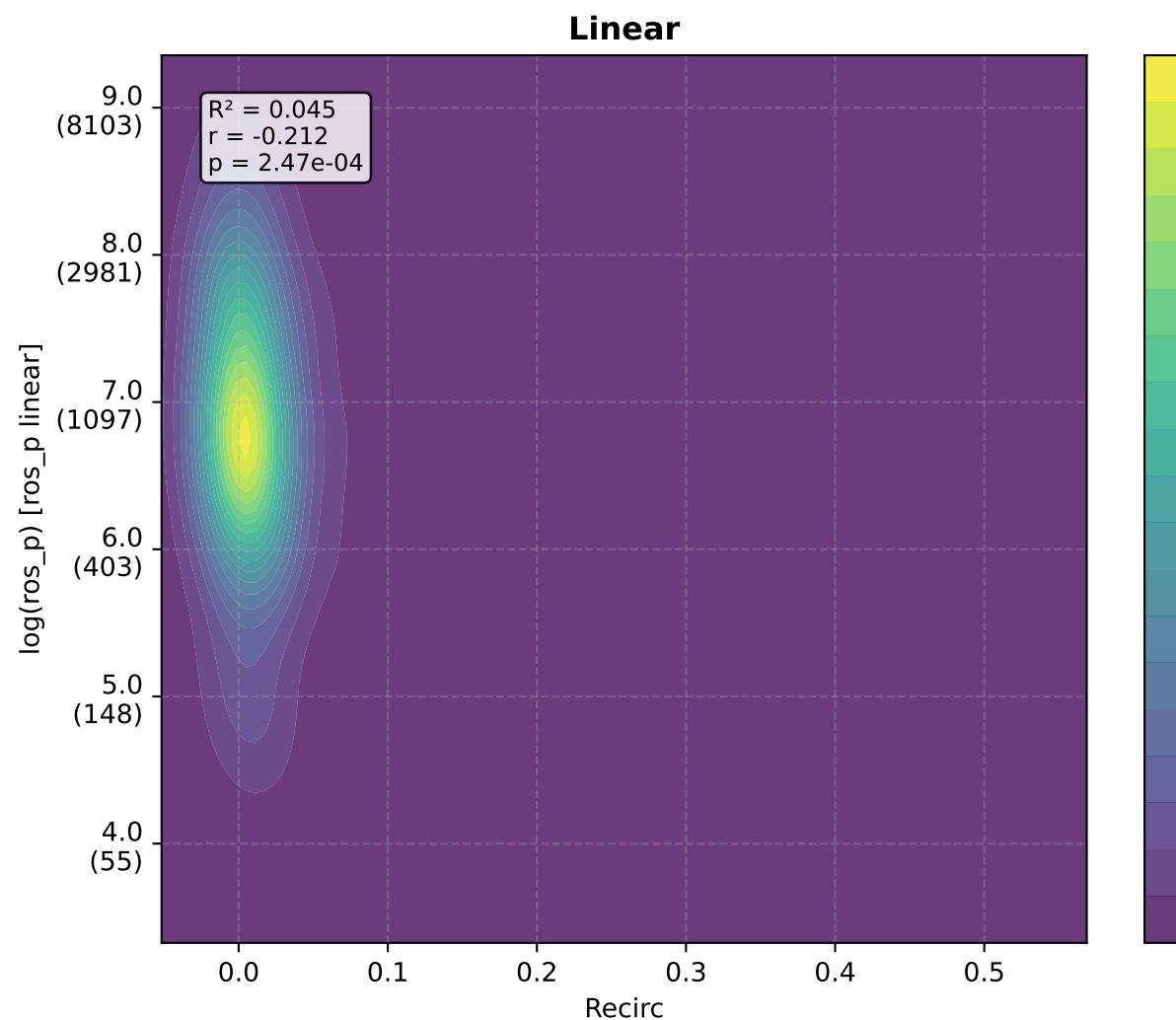
wv100_av vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



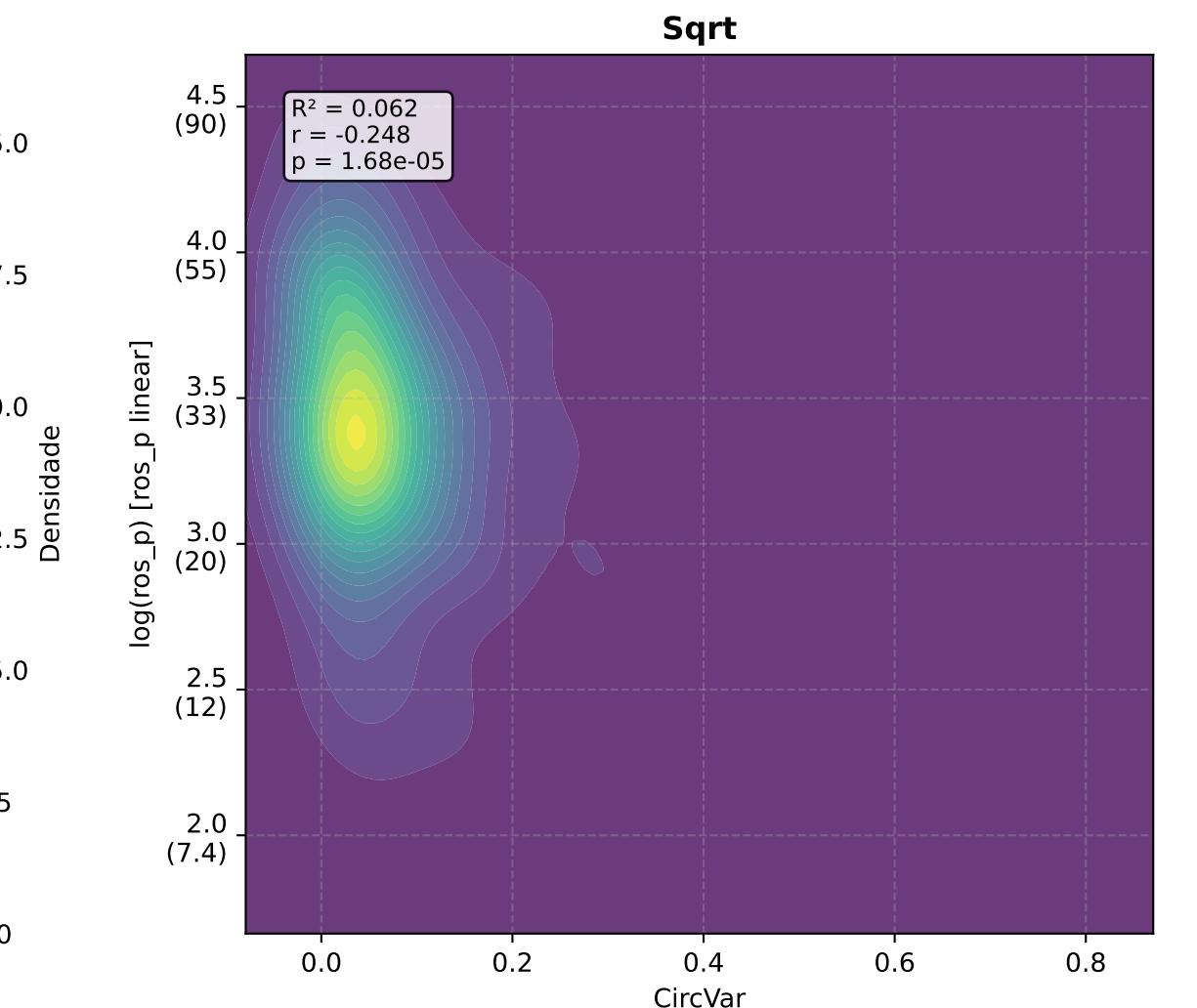
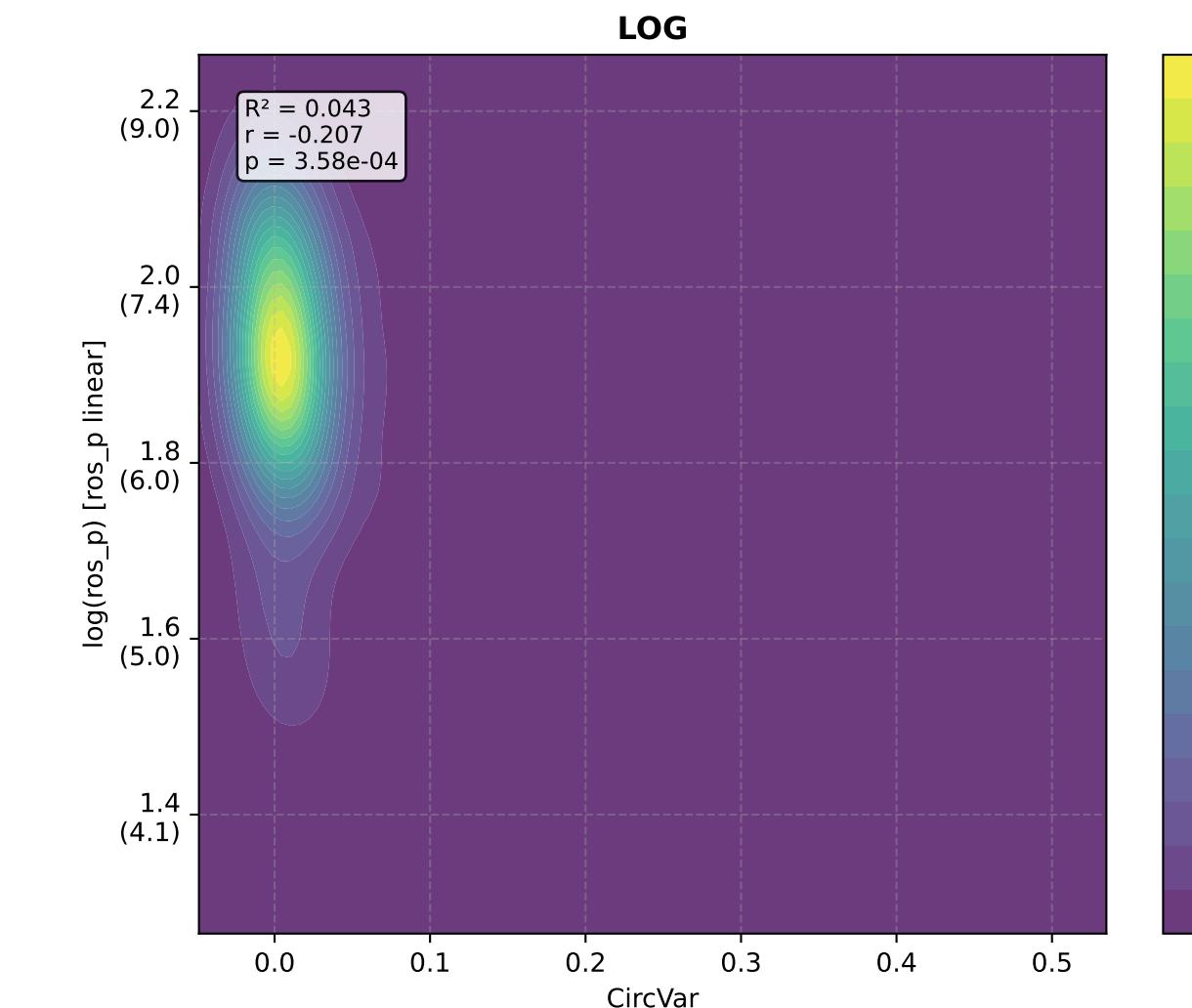
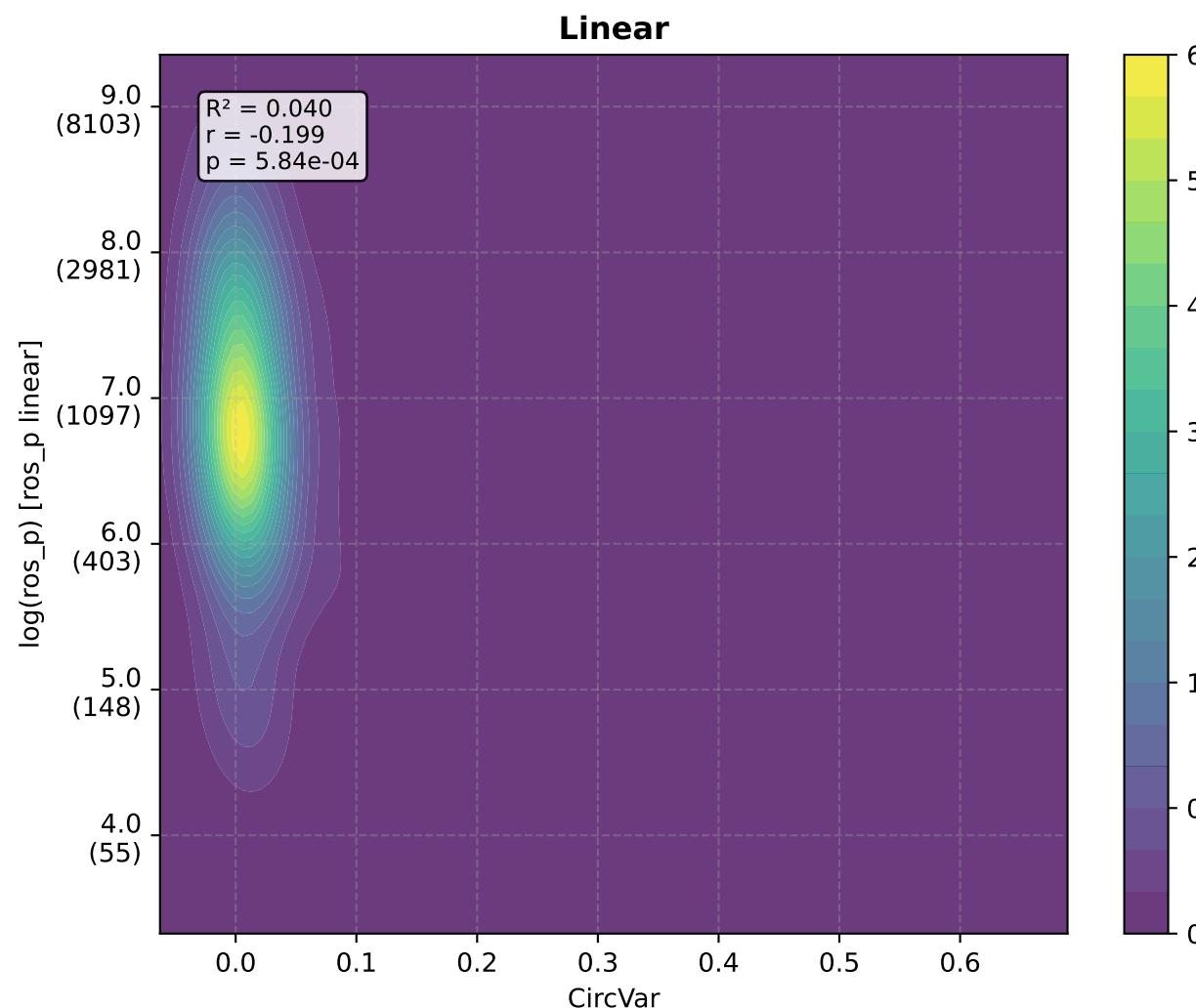
BLH_m_rt vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



Recirc vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



CircVar vs ros_p - KDE Cloud (Linear, LOG & Sqrt)

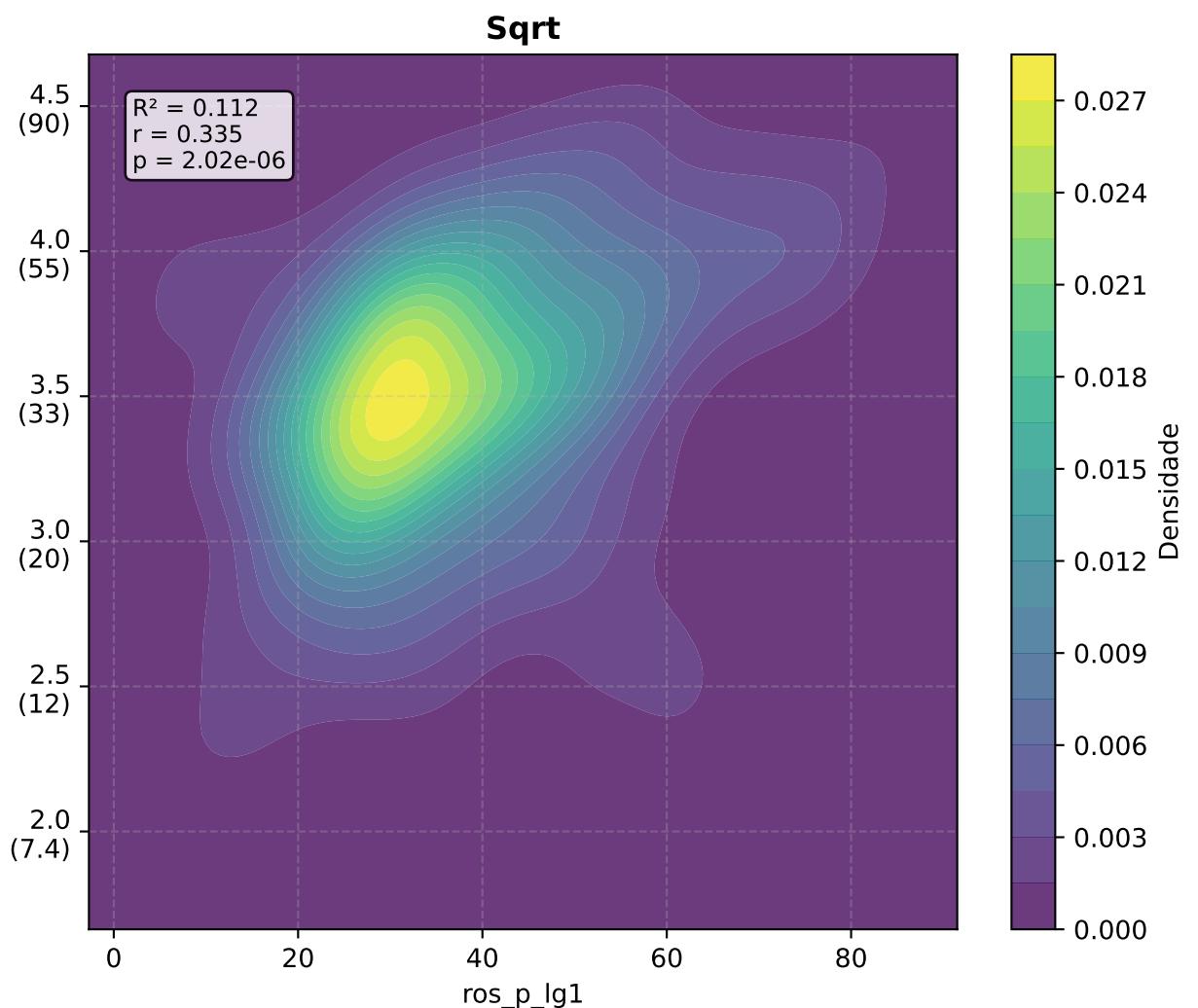
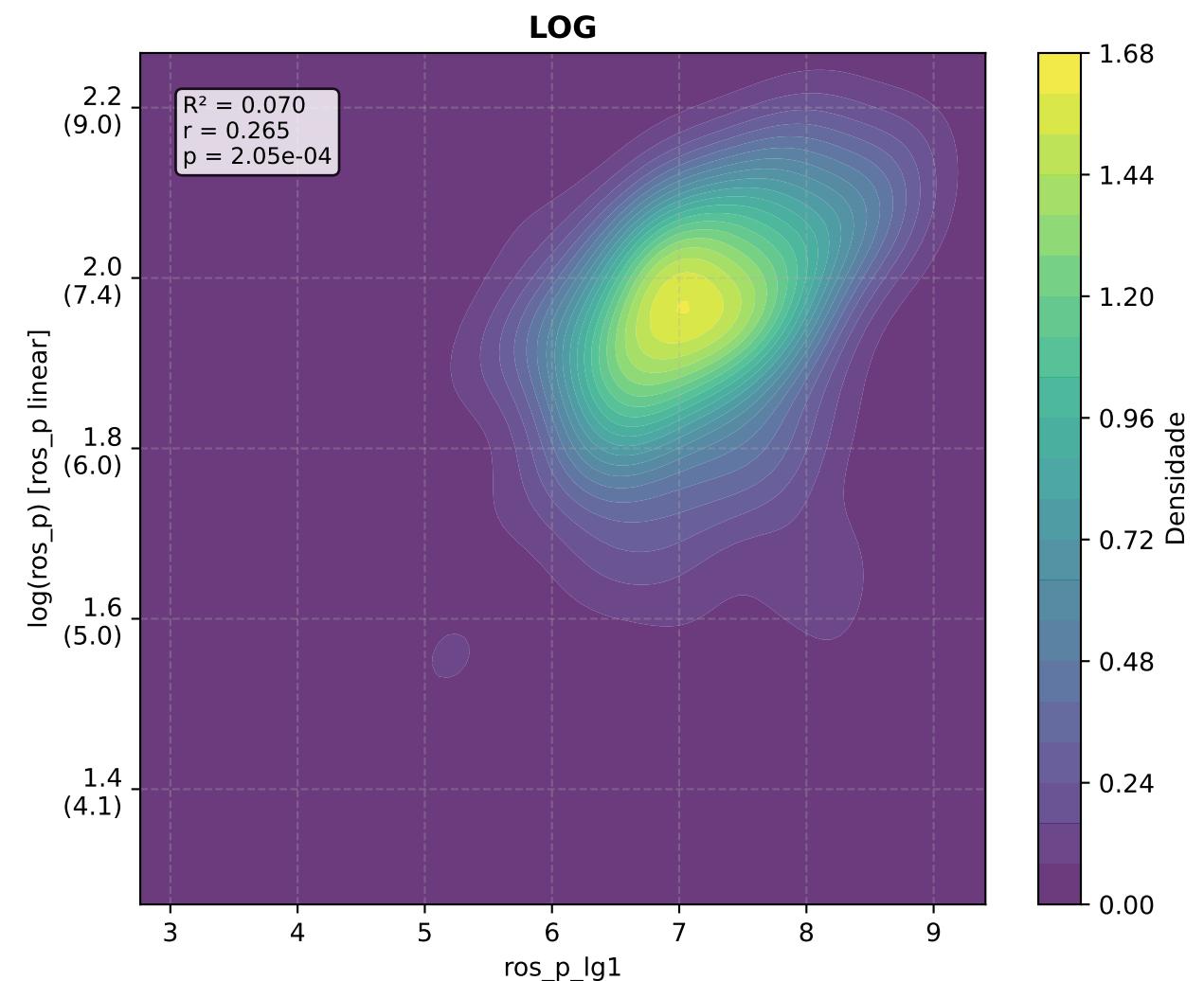
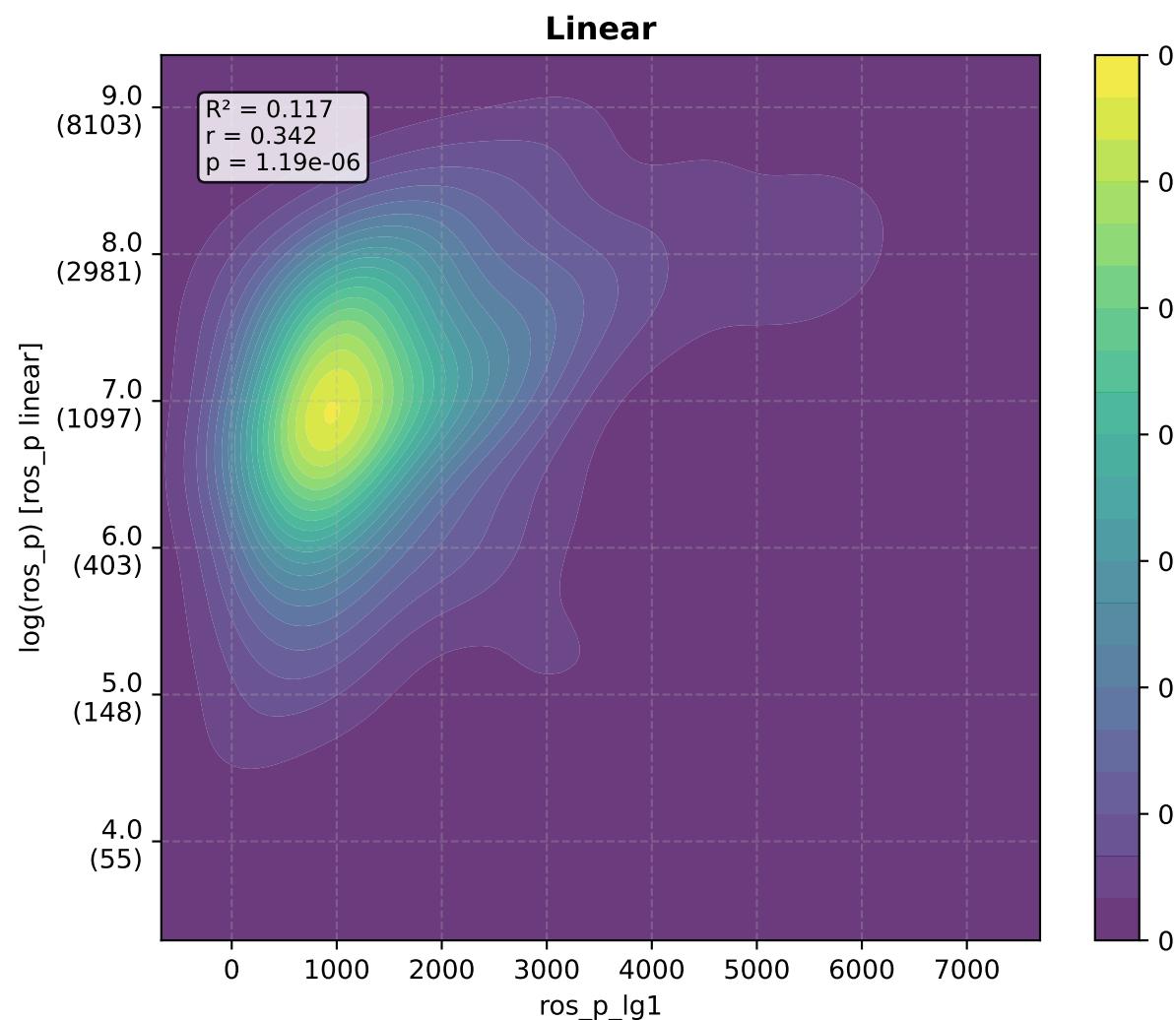


Densidade

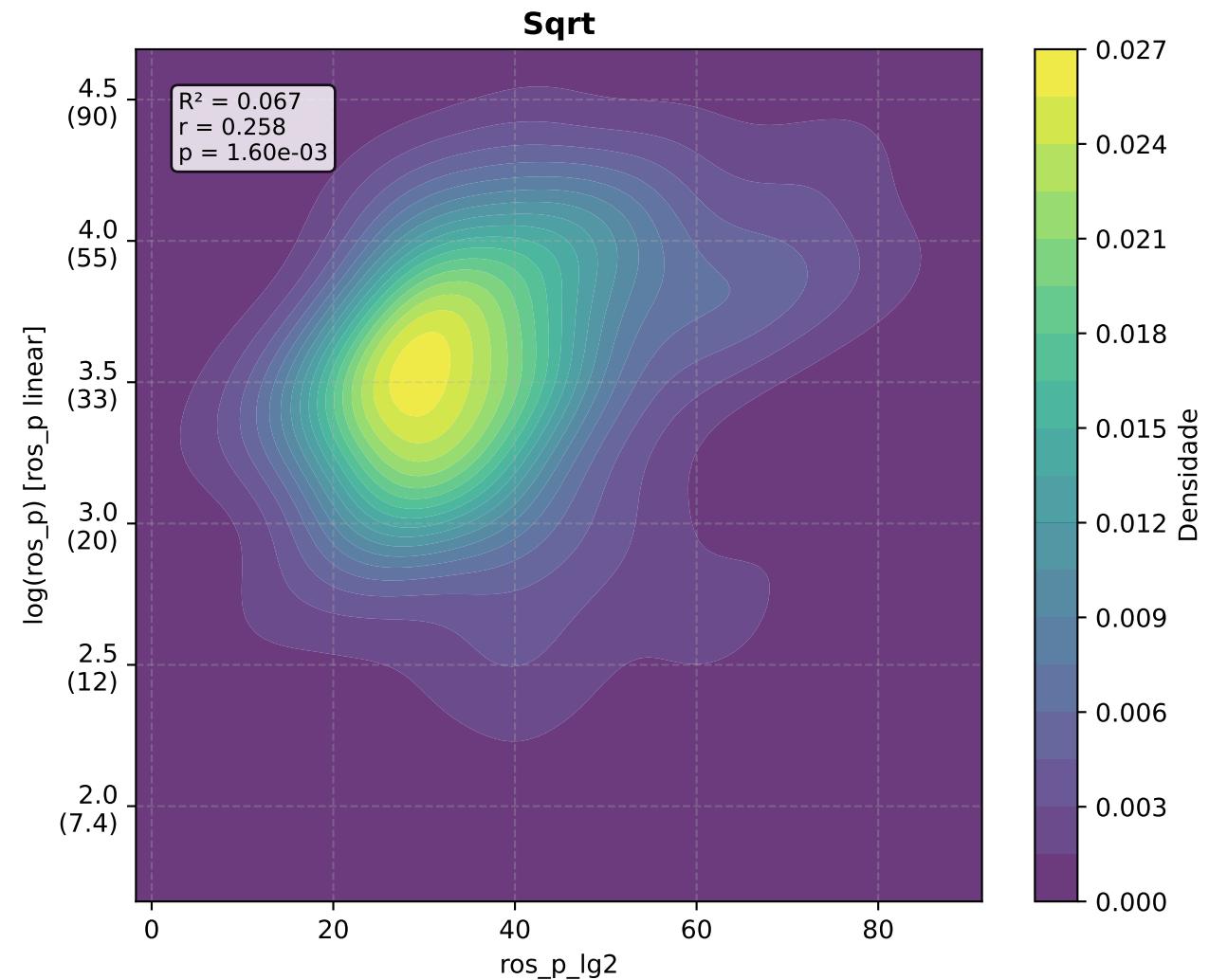
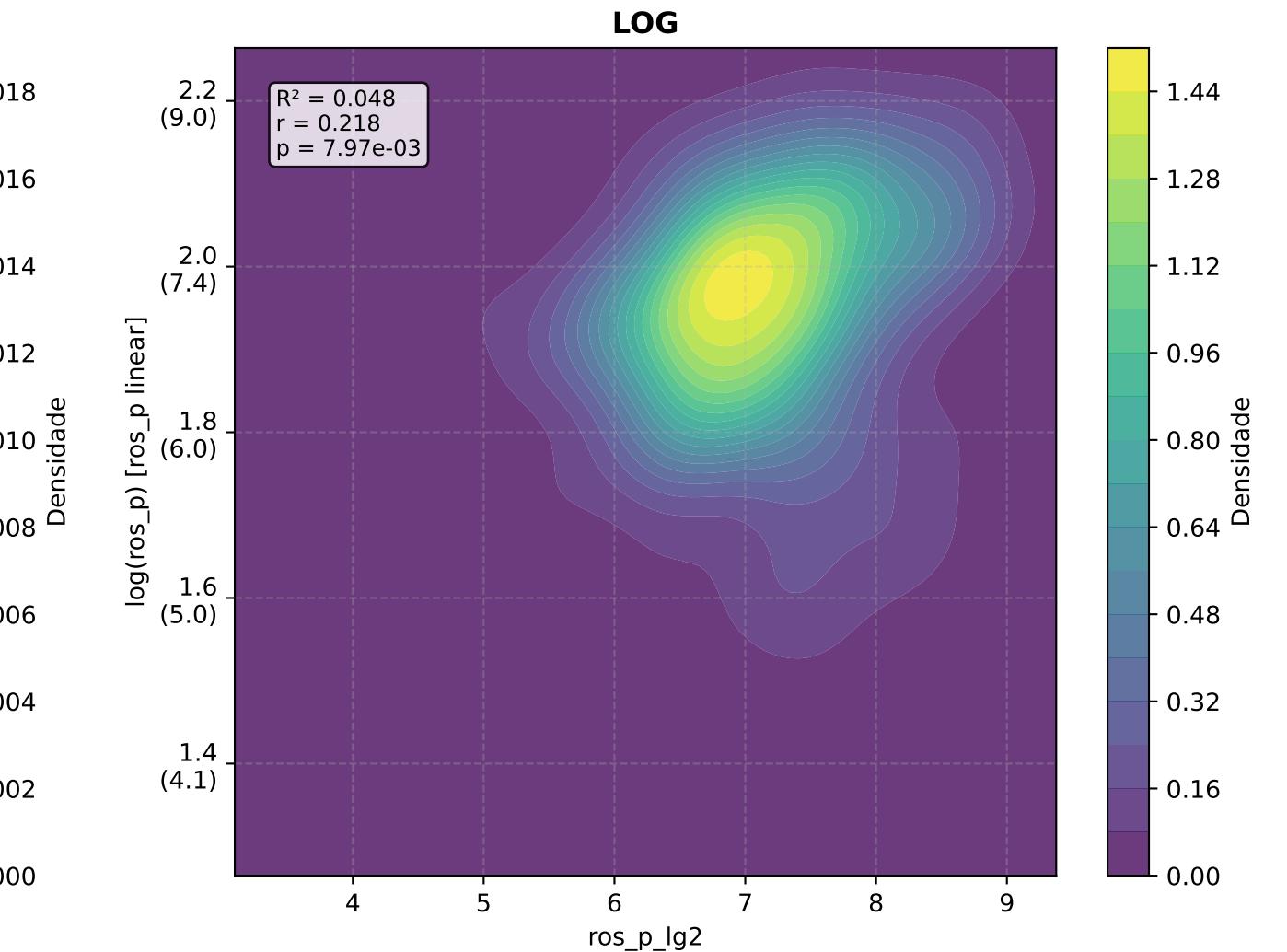
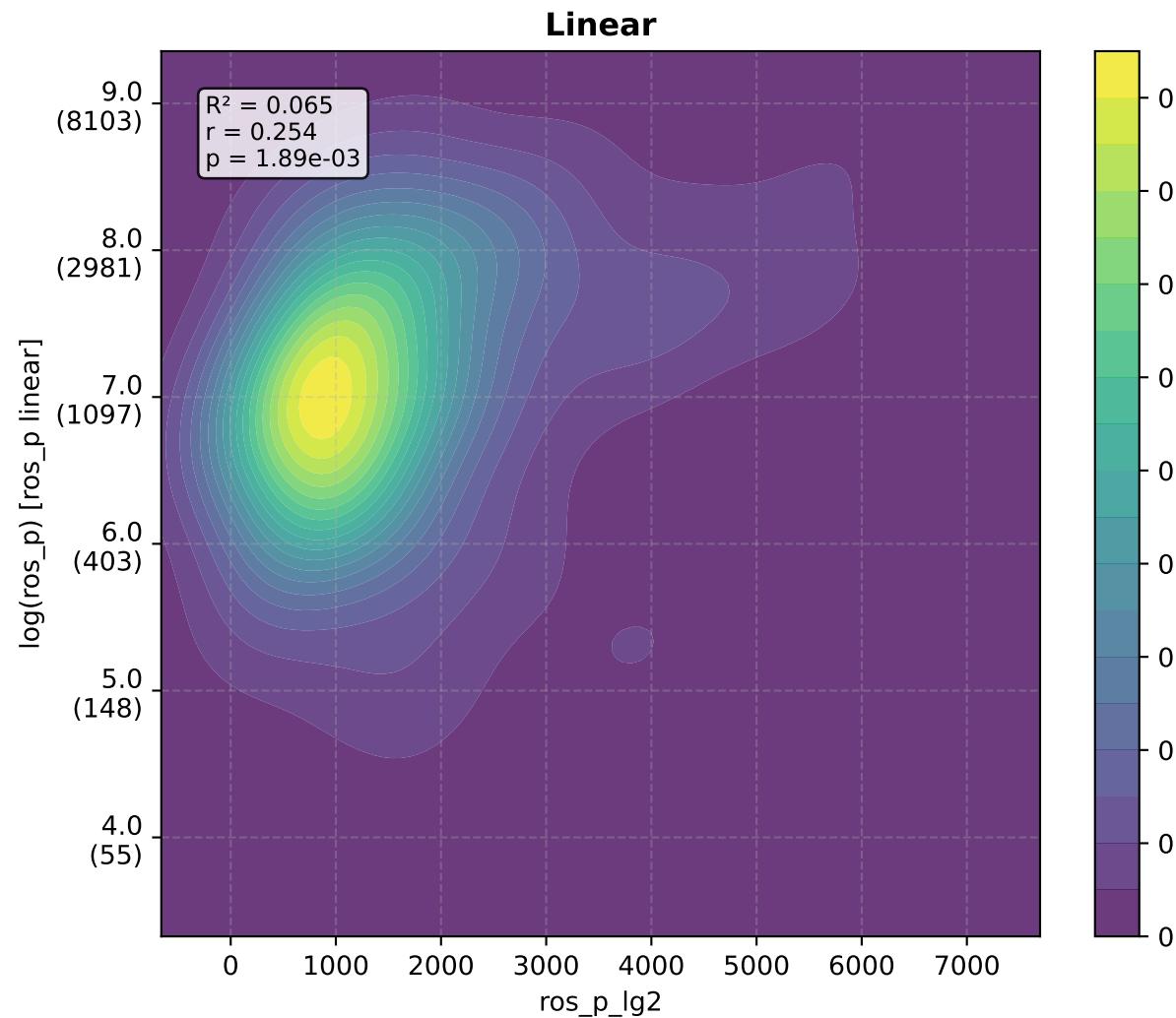
Densidade

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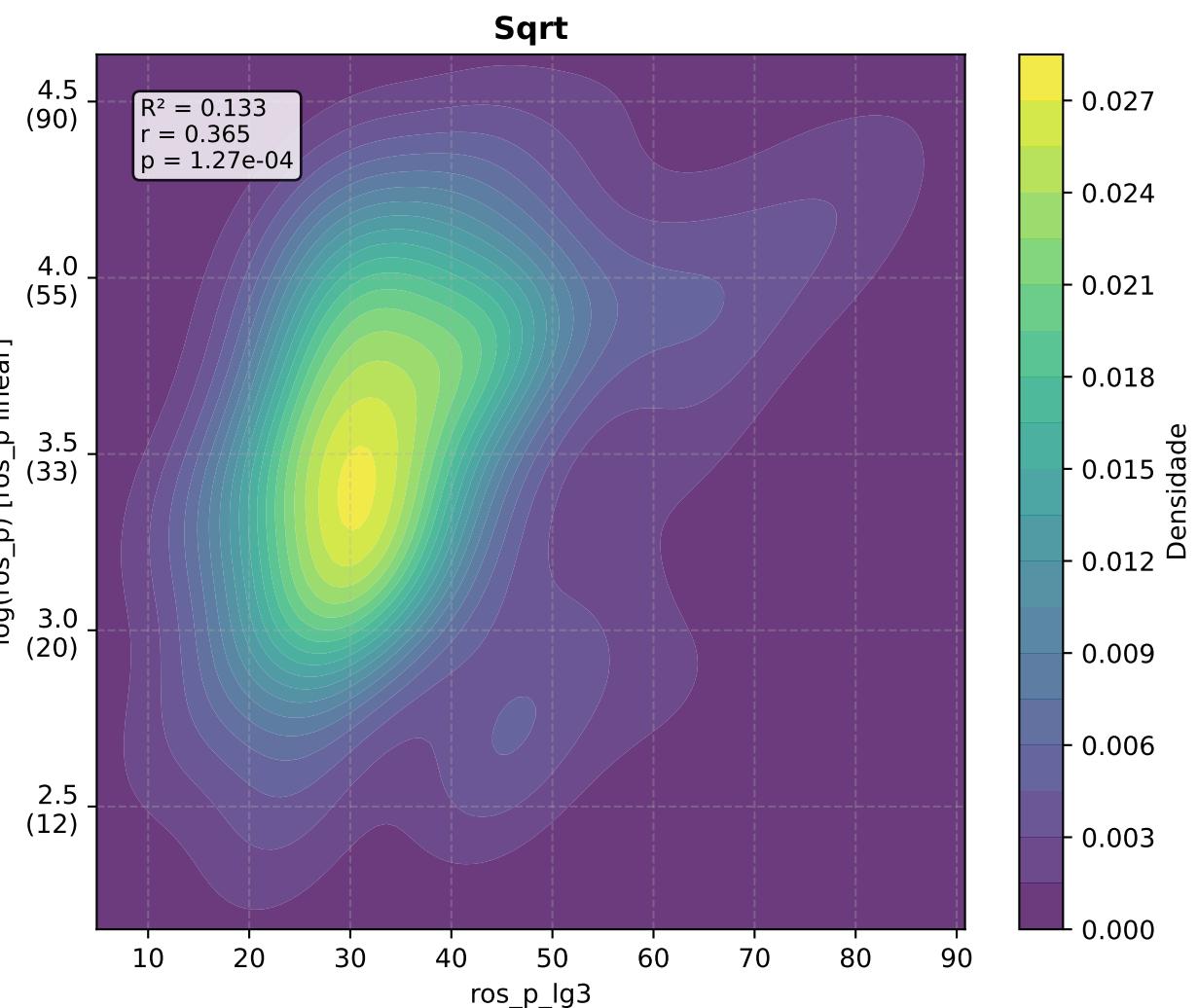
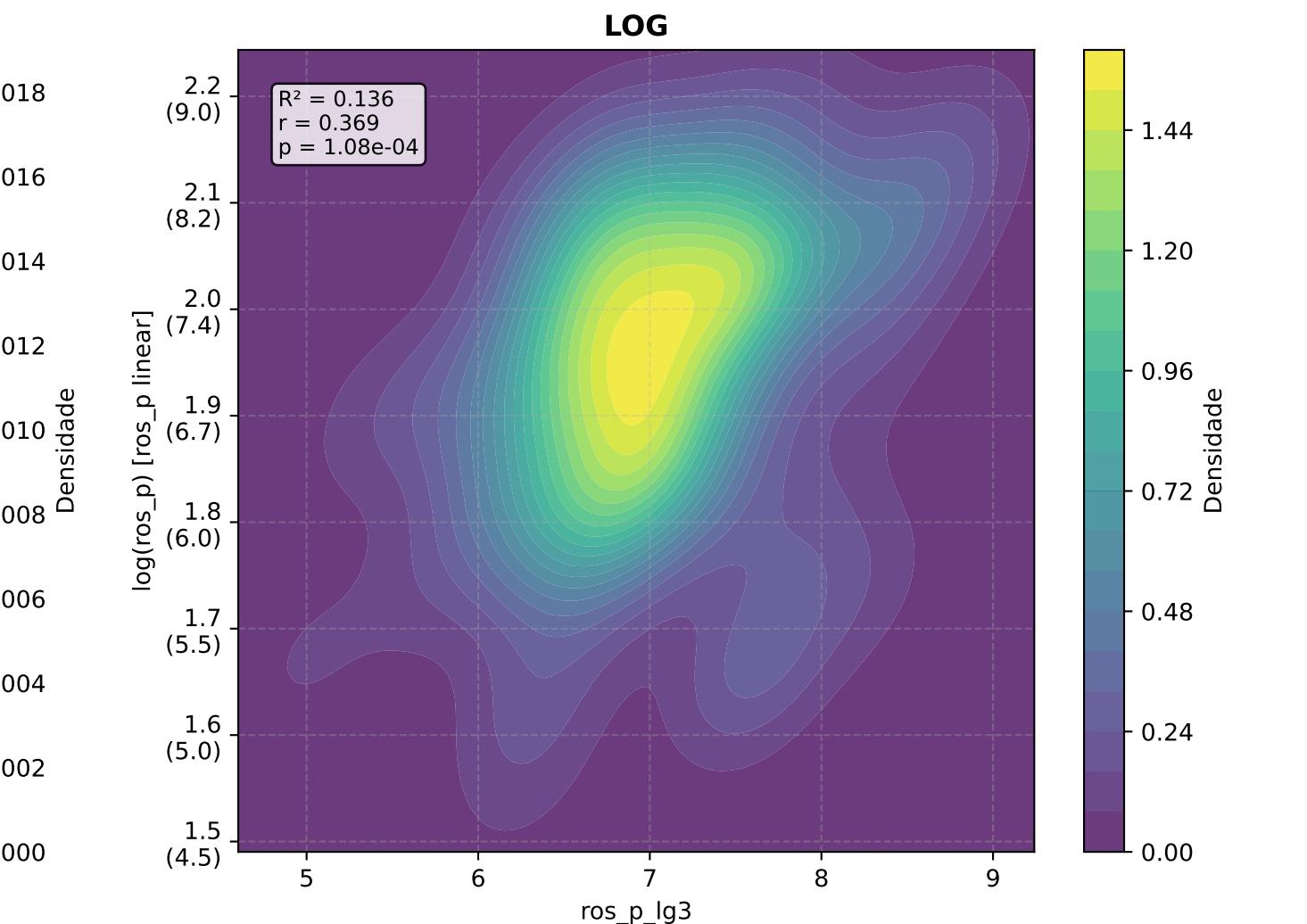
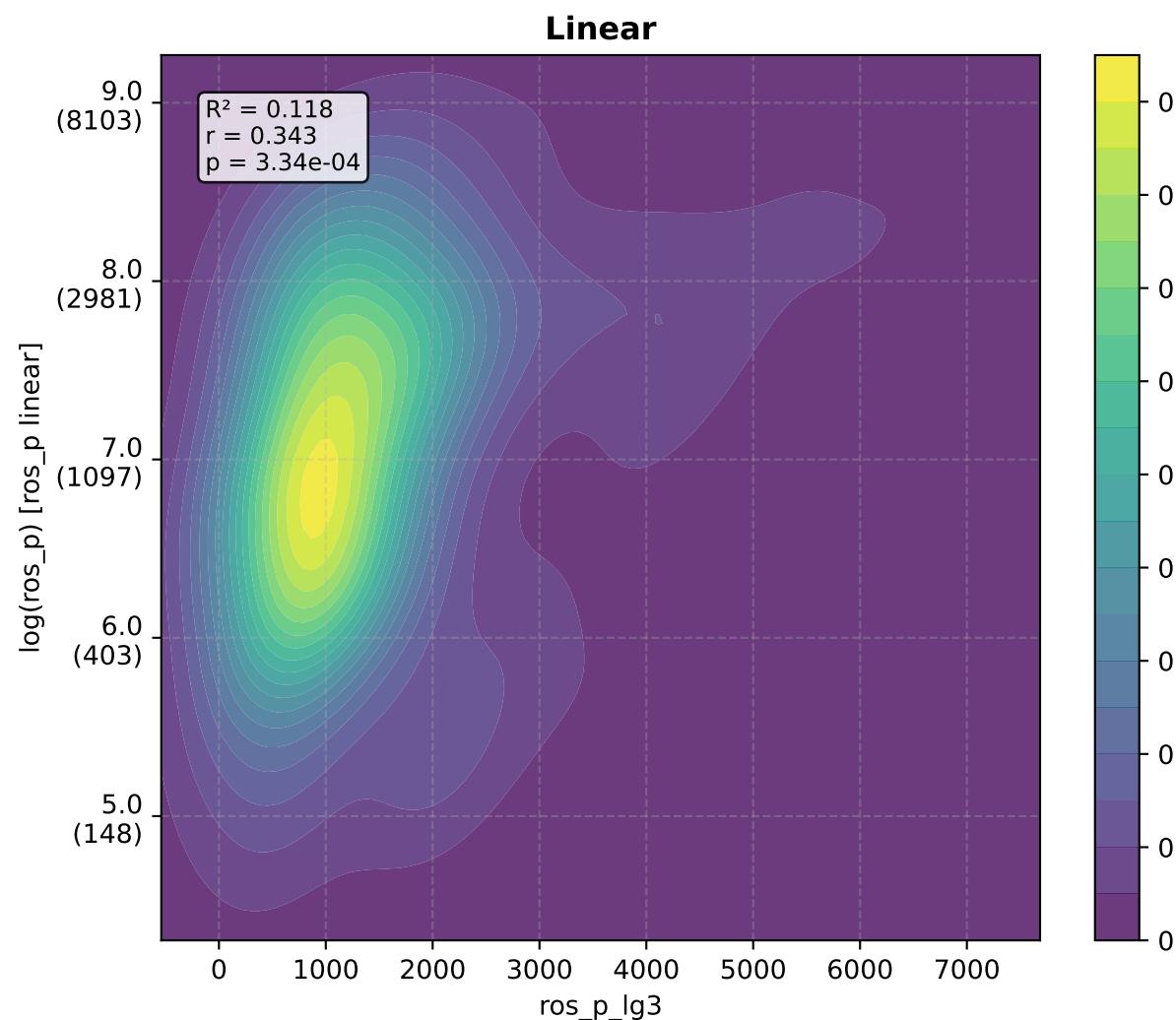
ros_p_lg1 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



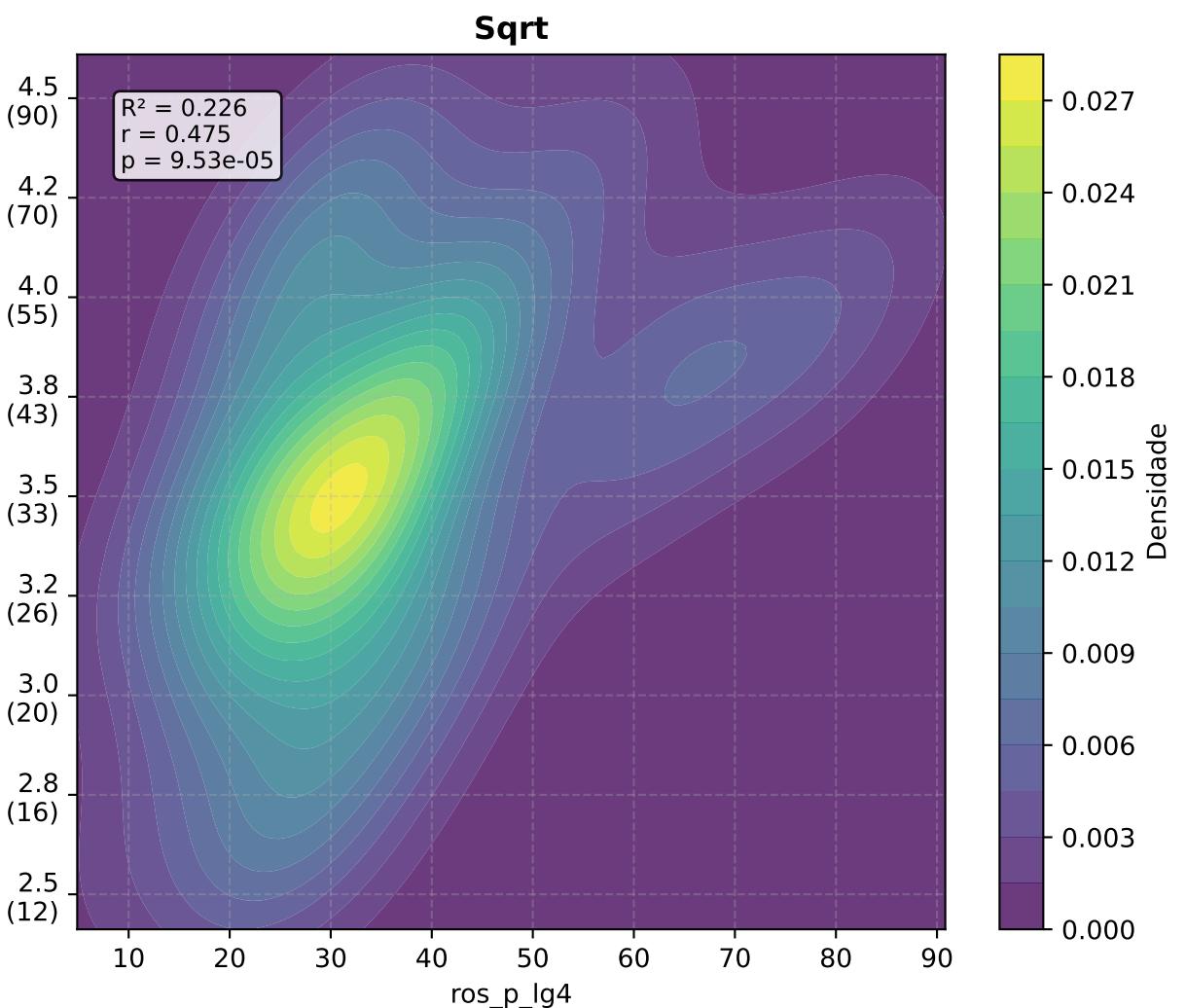
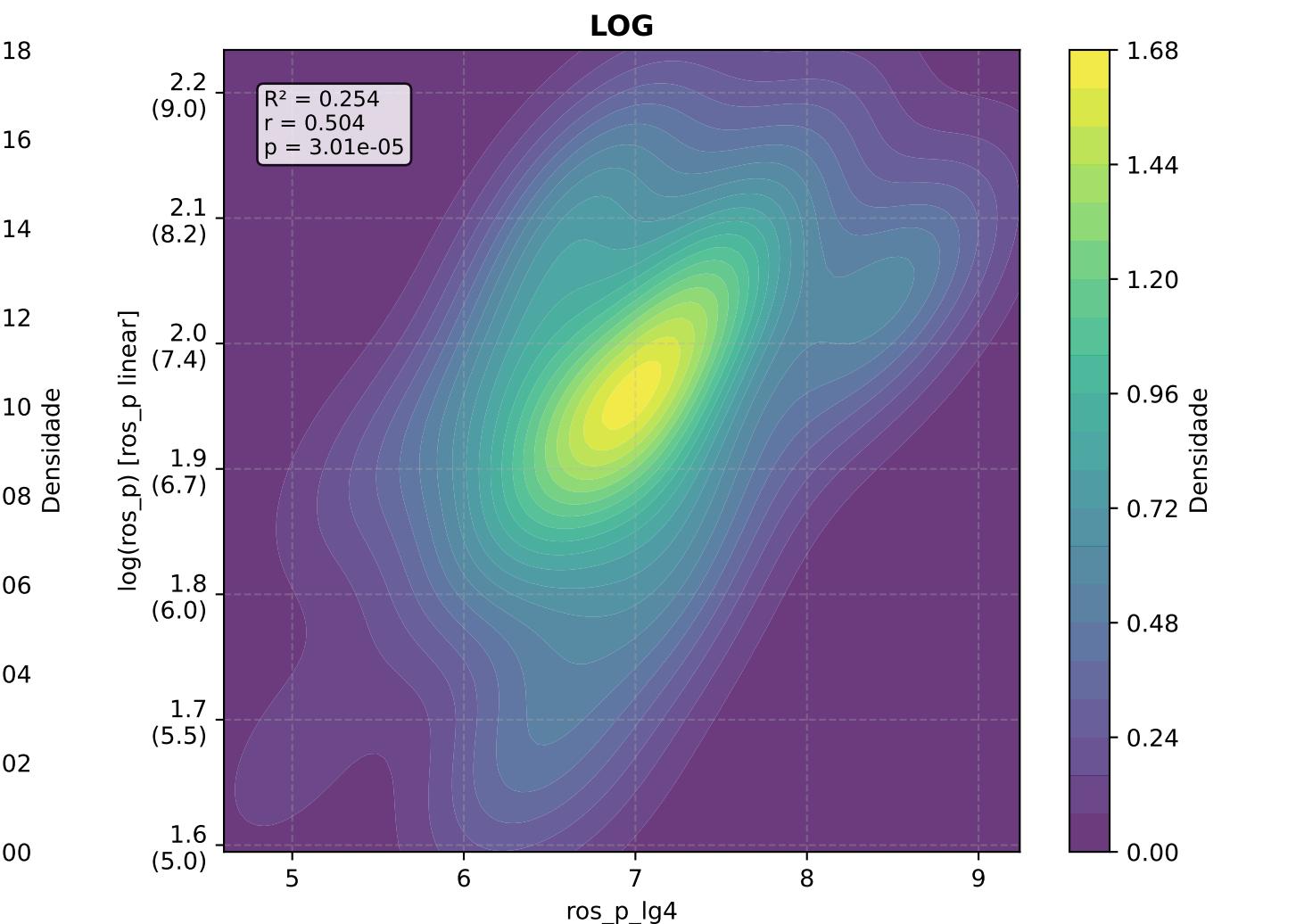
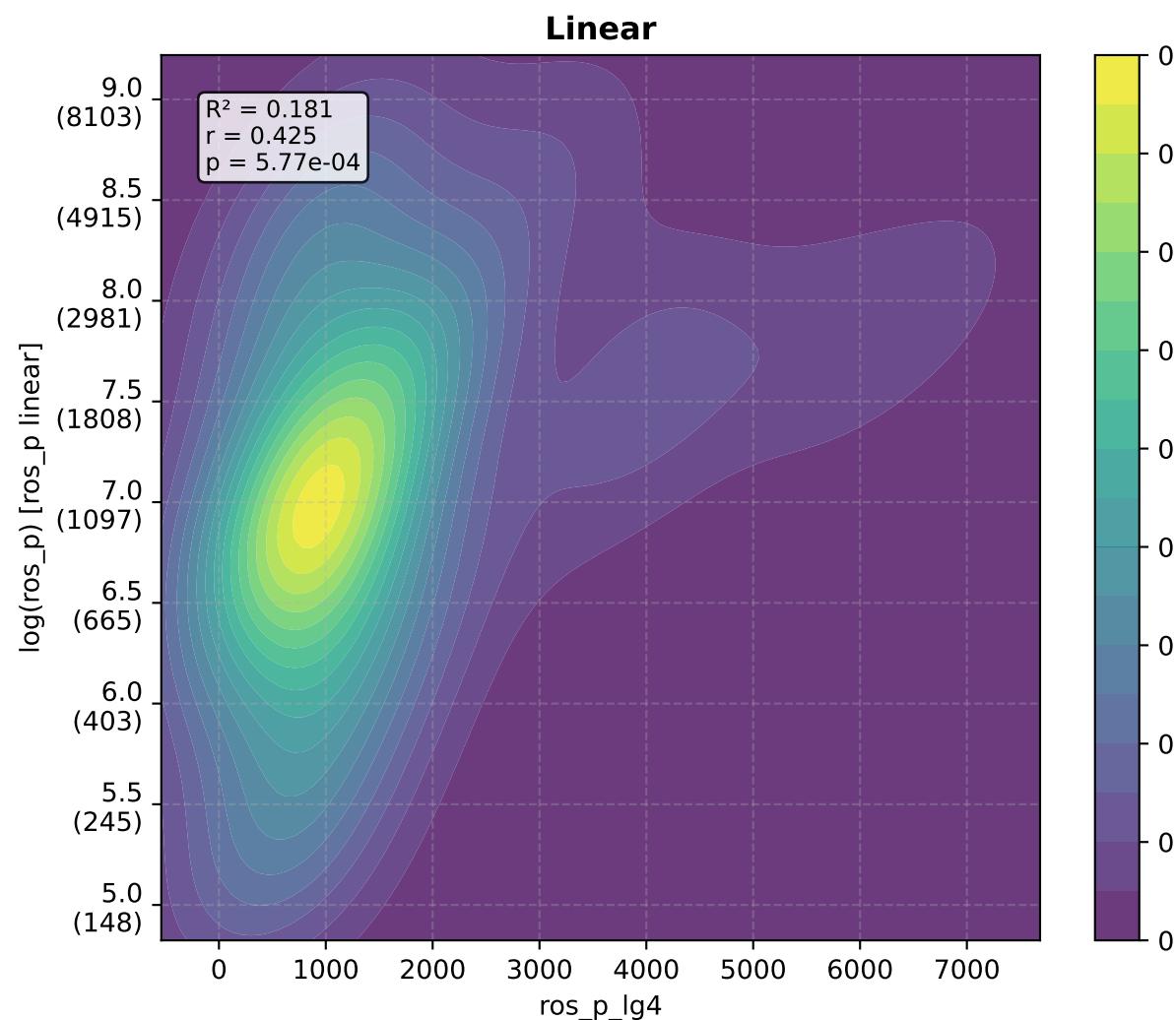
ros_p_lg2 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



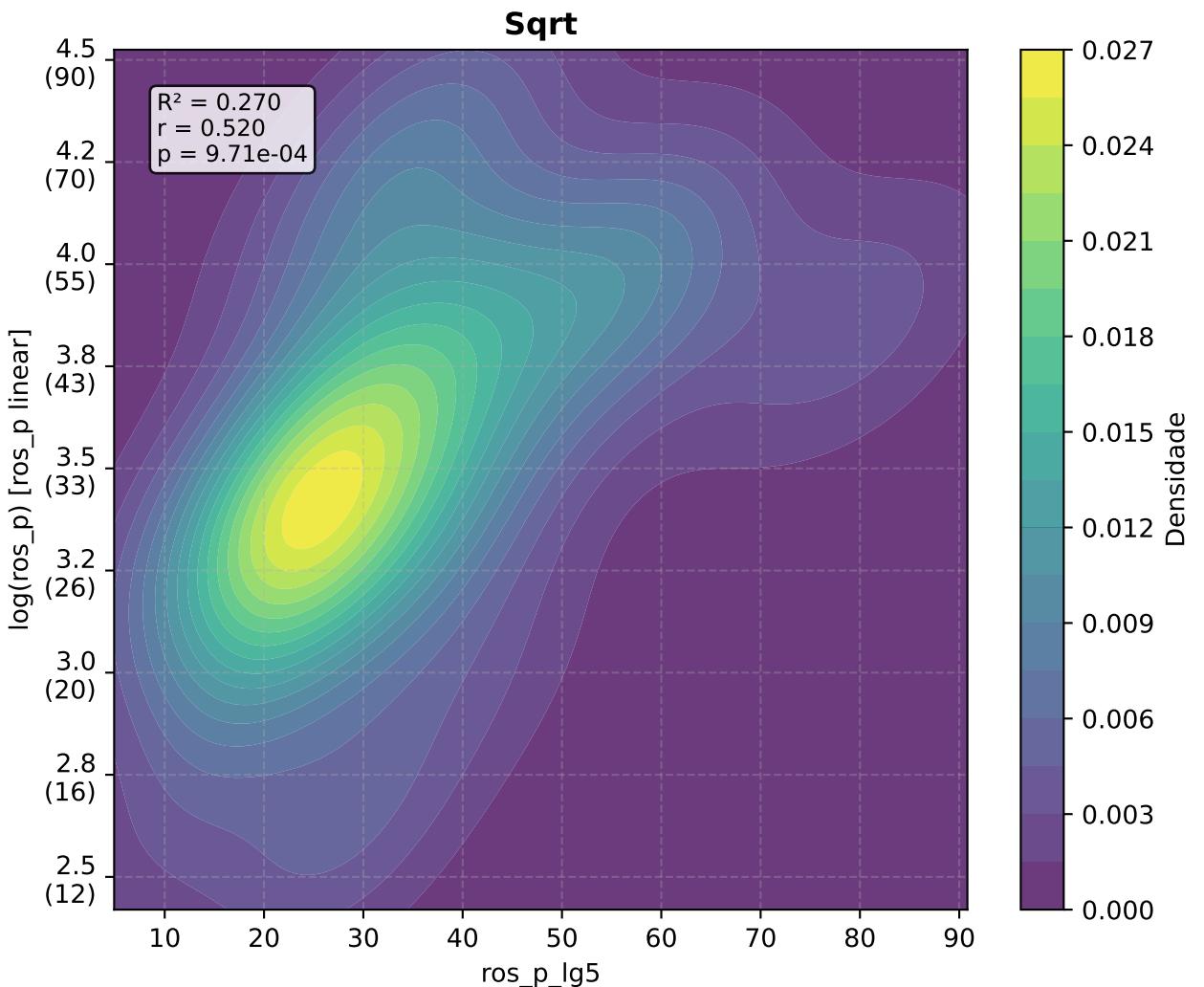
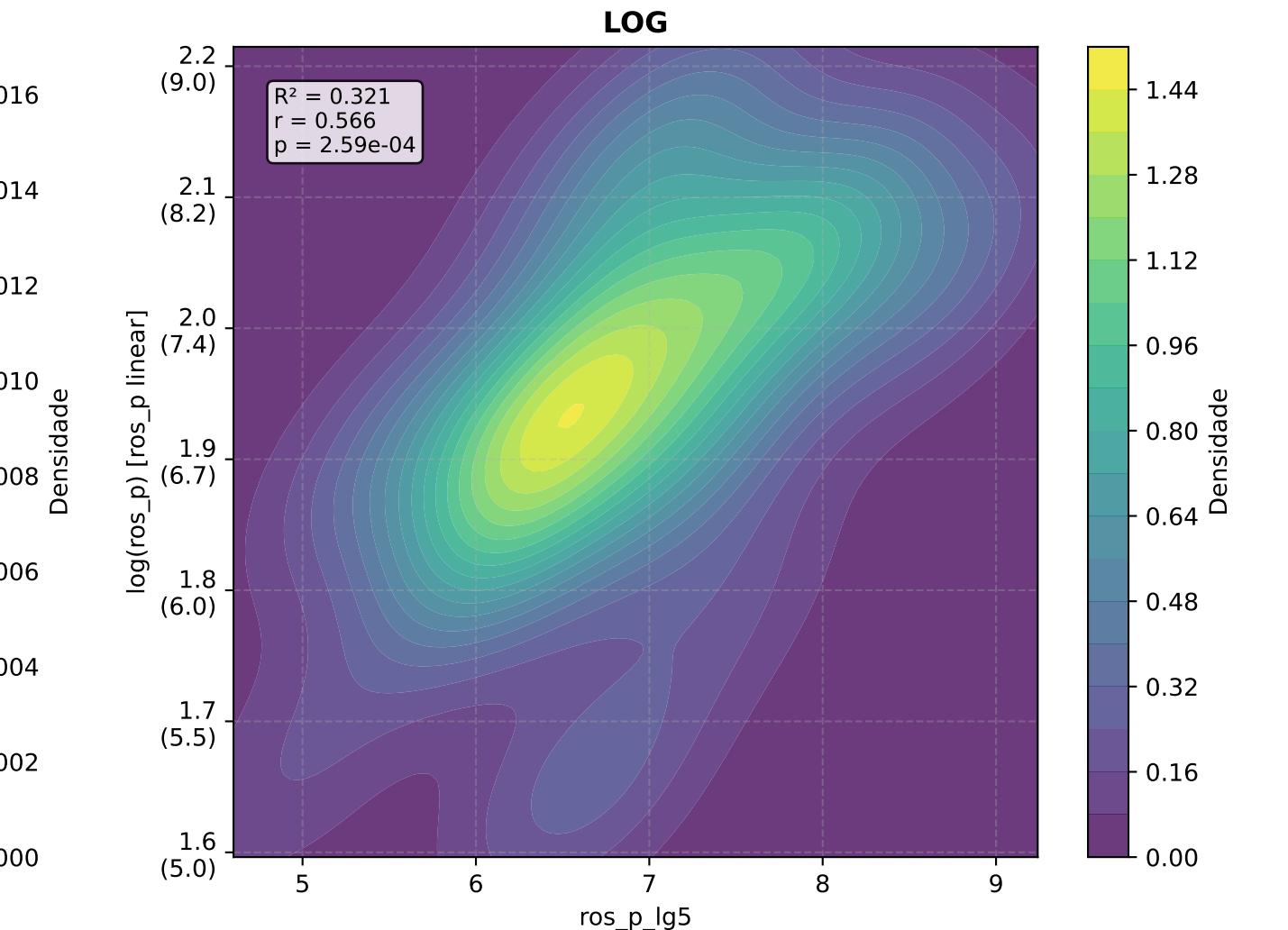
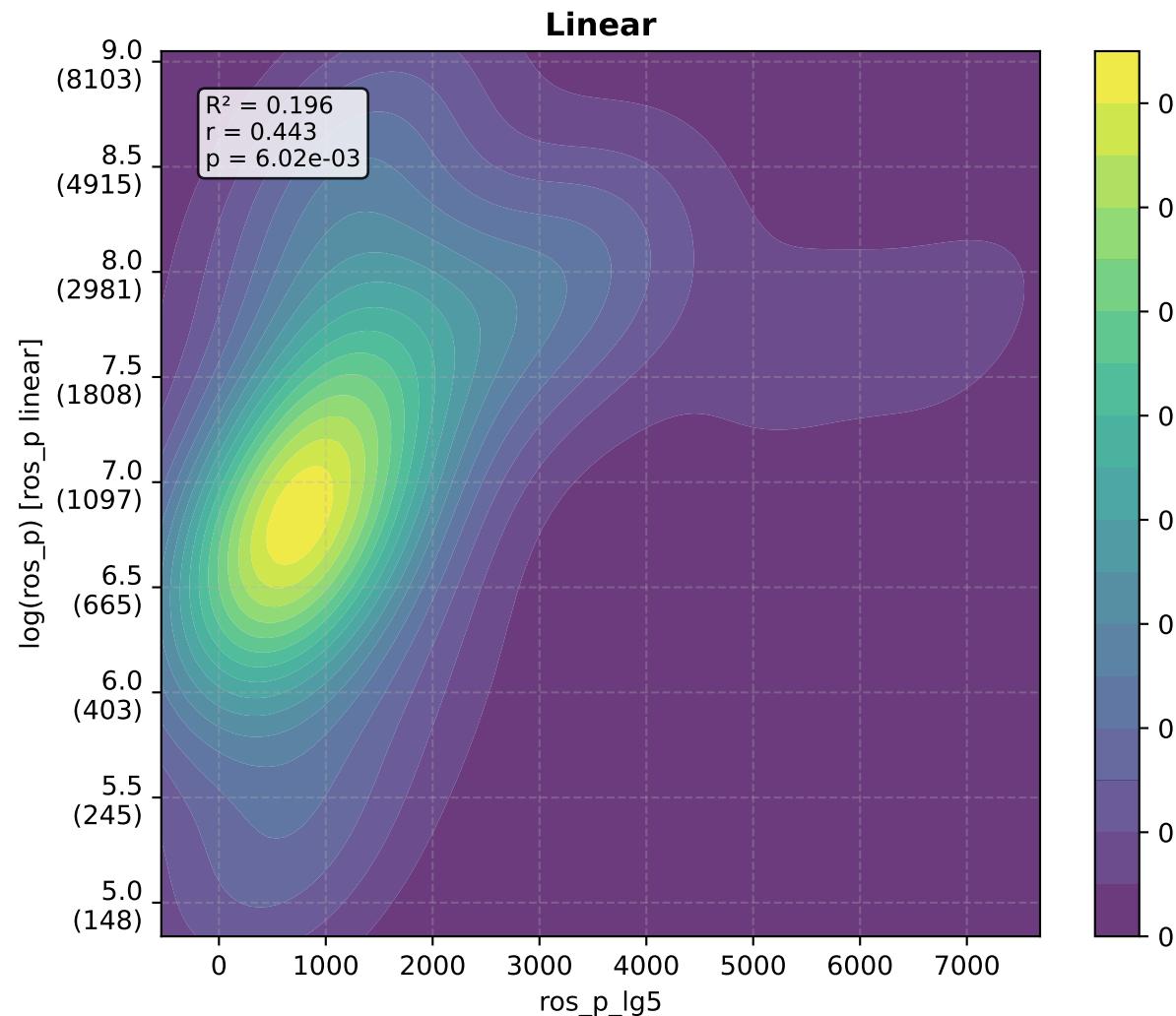
ros_p_lg3 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



ros_p_lg4 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



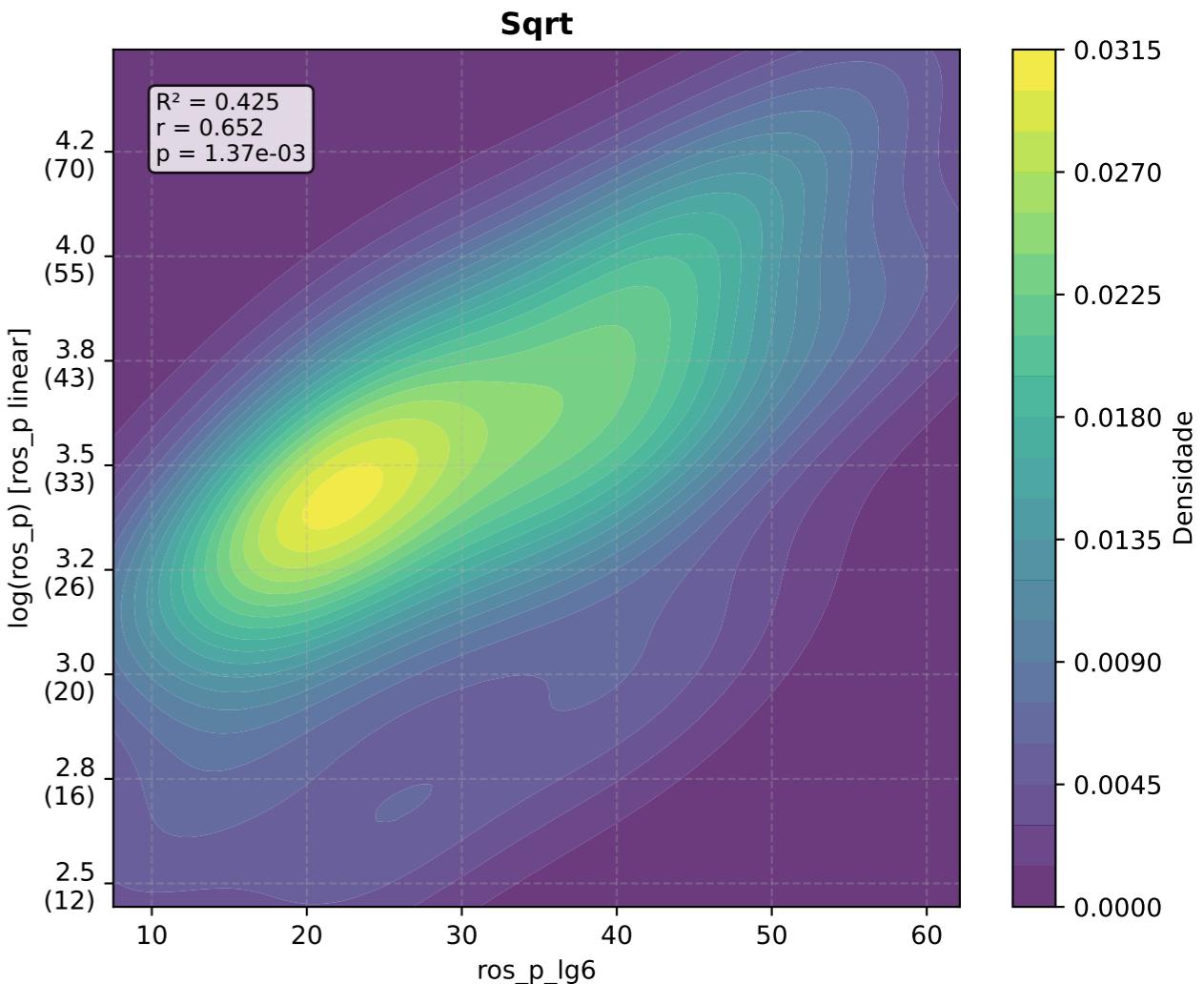
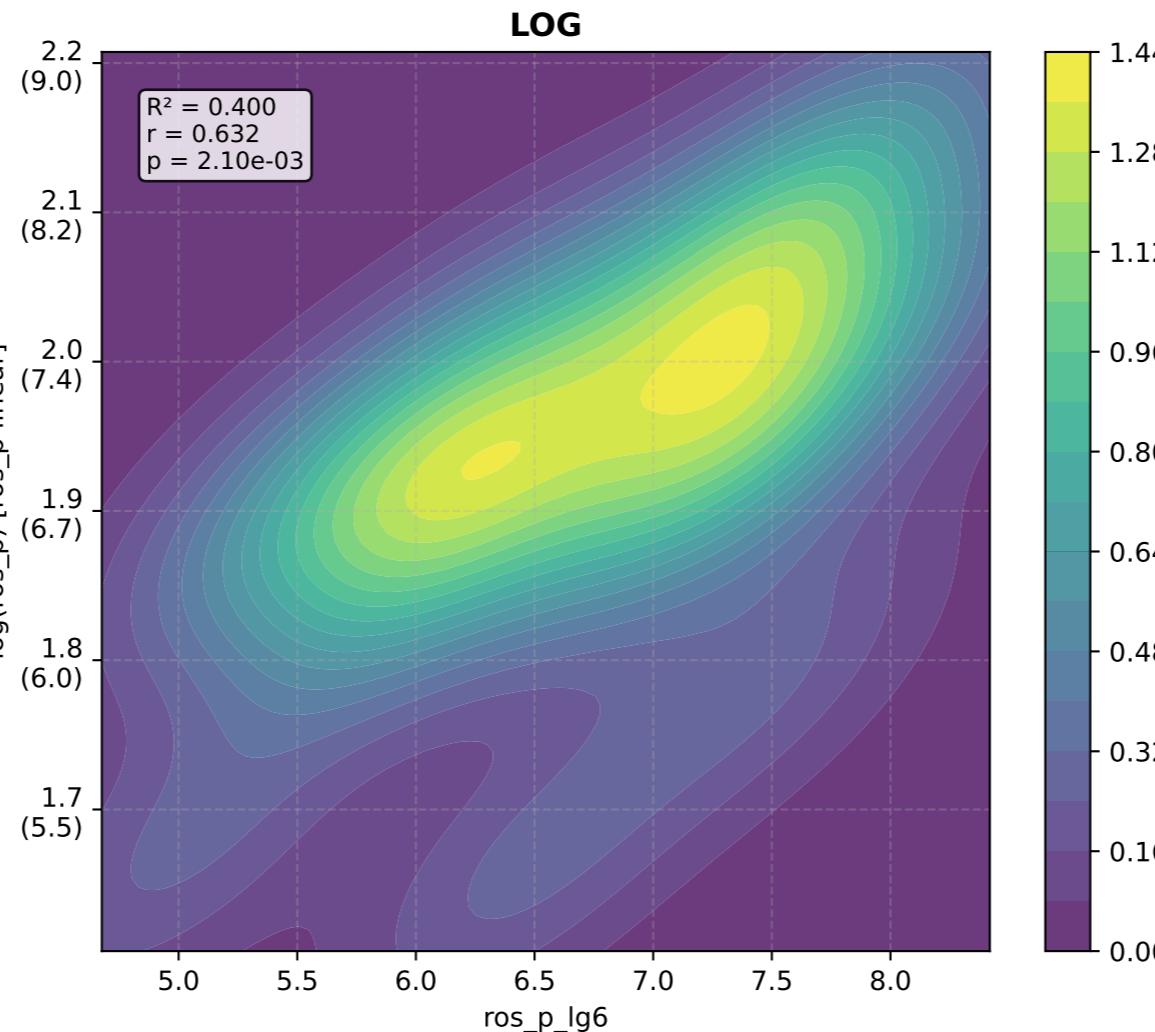
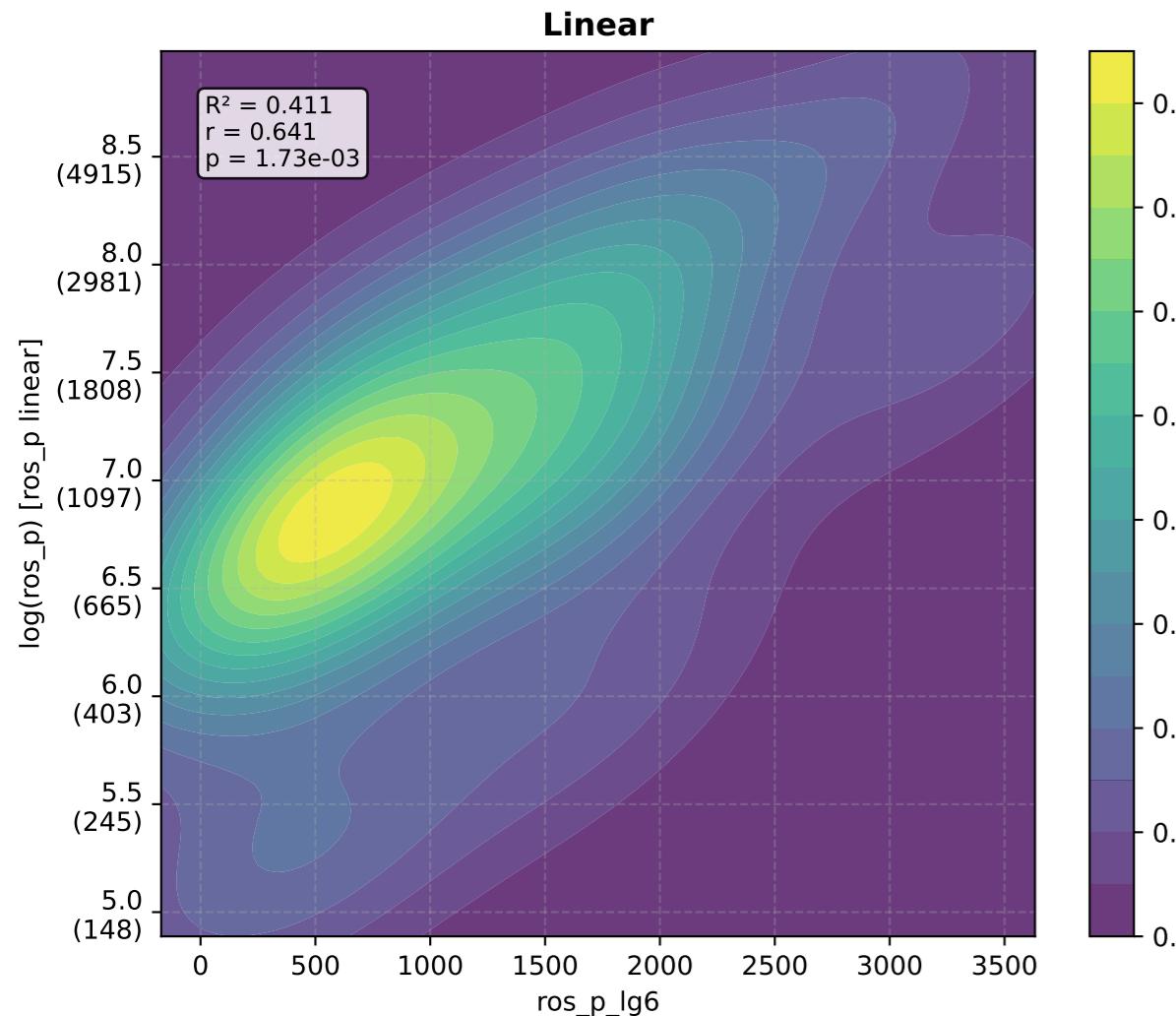
ros_p_lg5 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



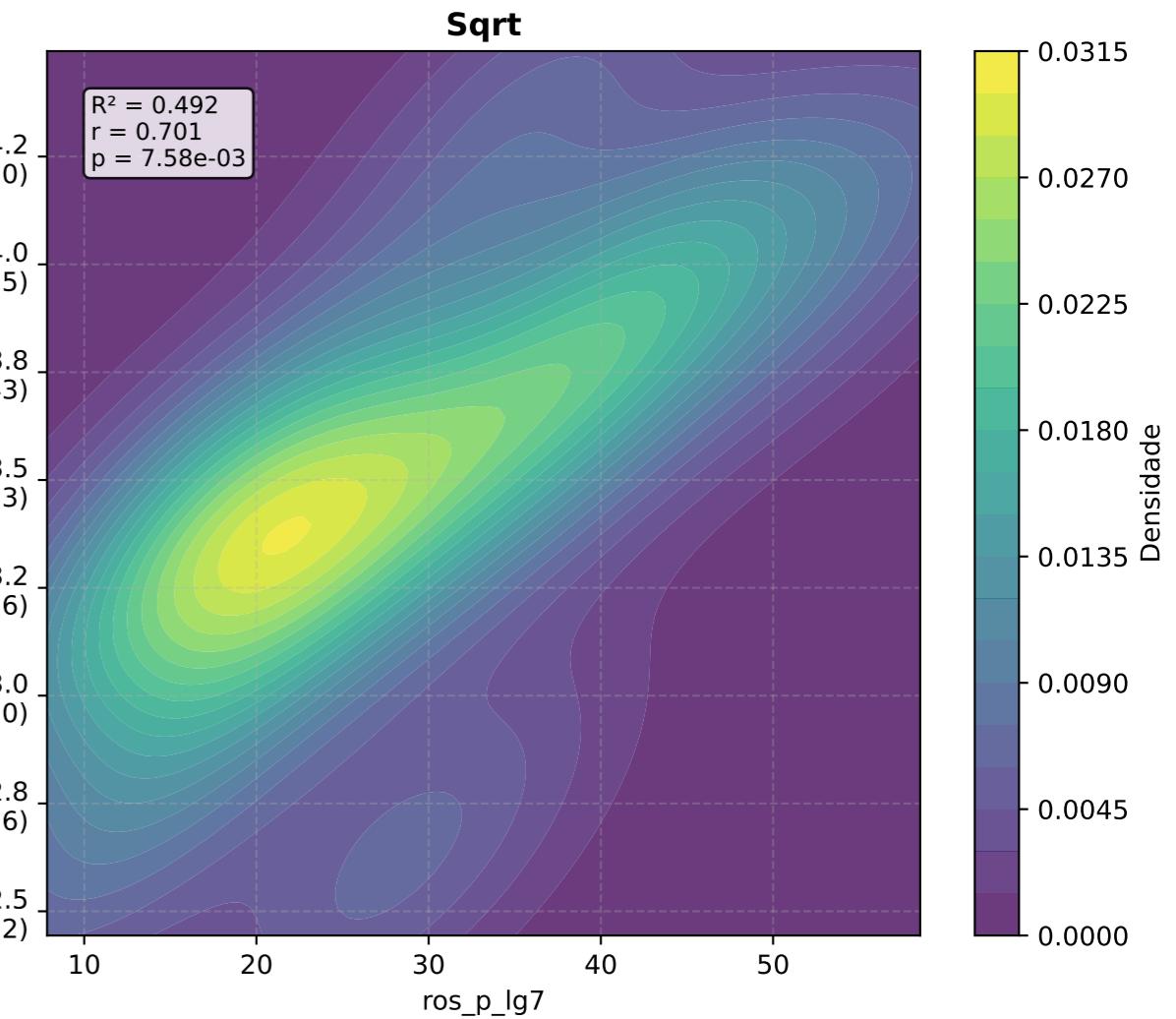
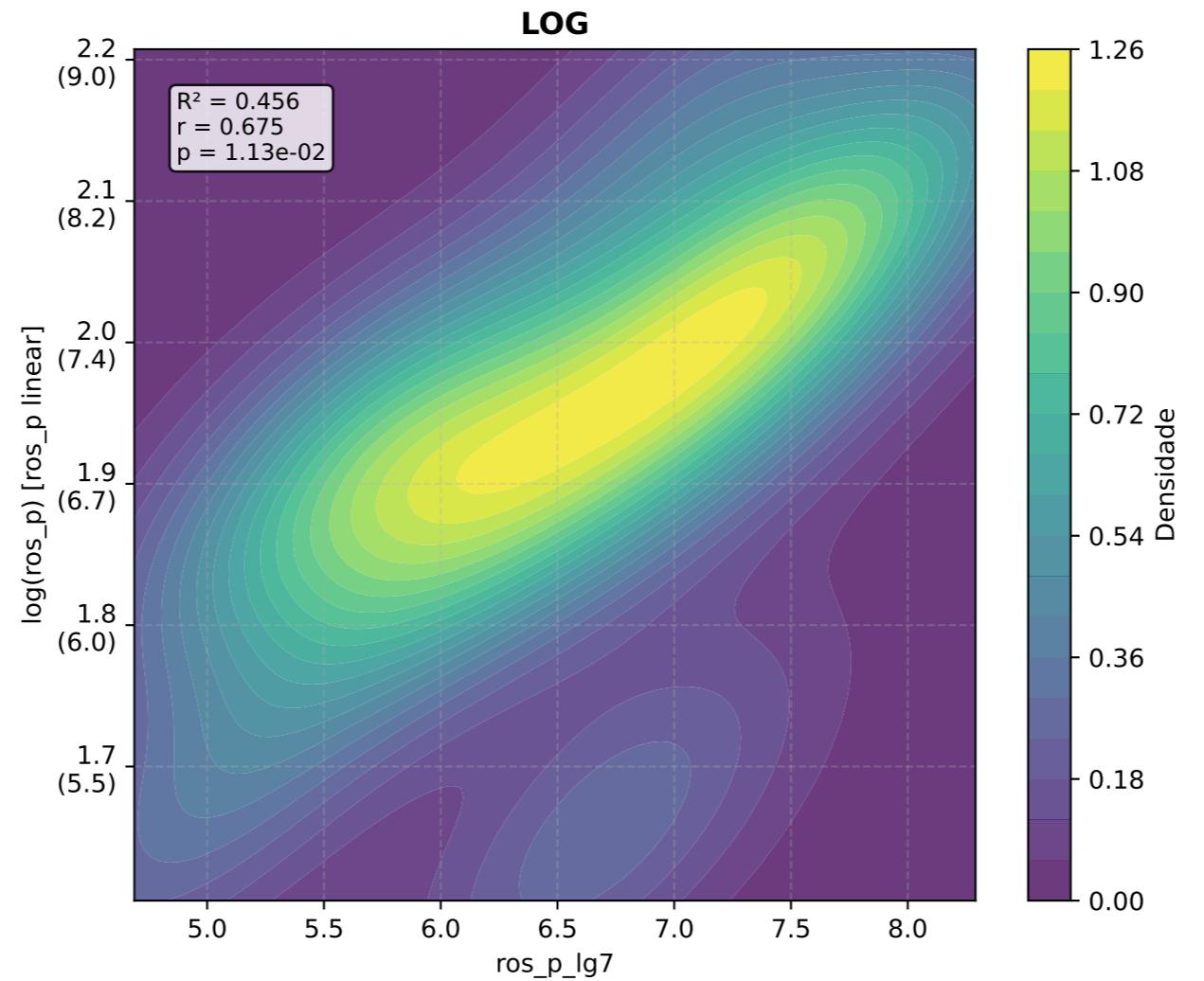
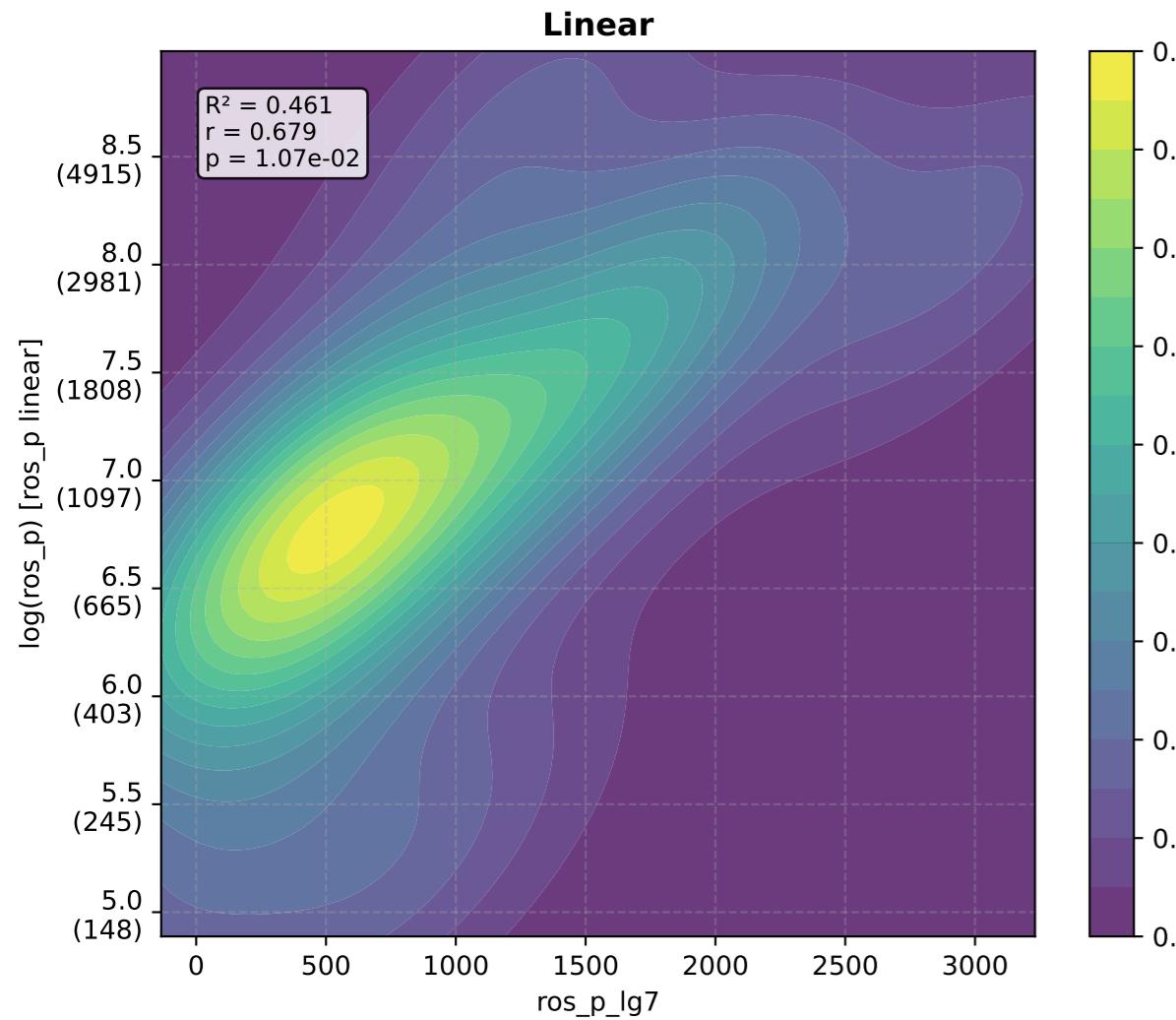
Densidade

Densidade

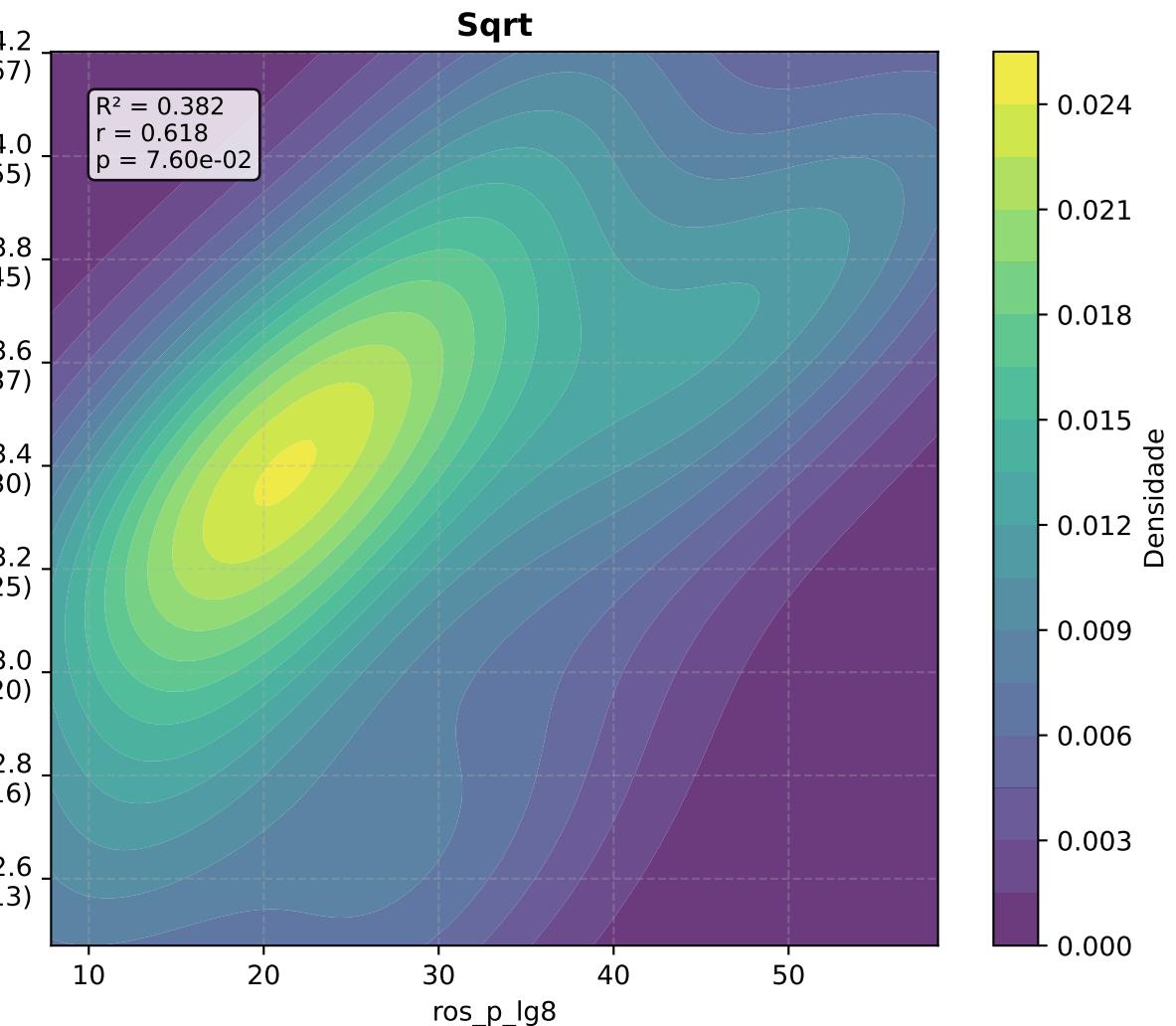
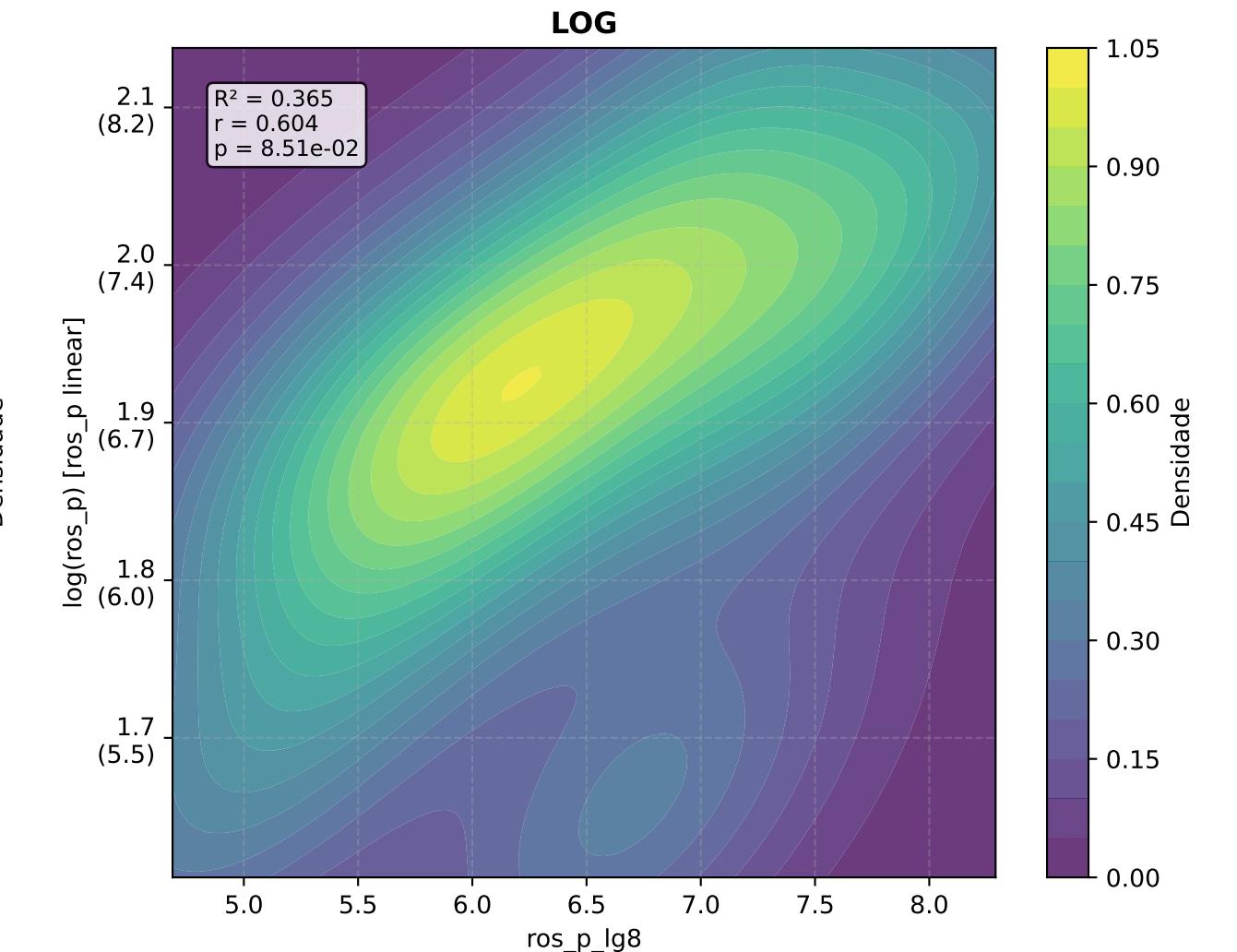
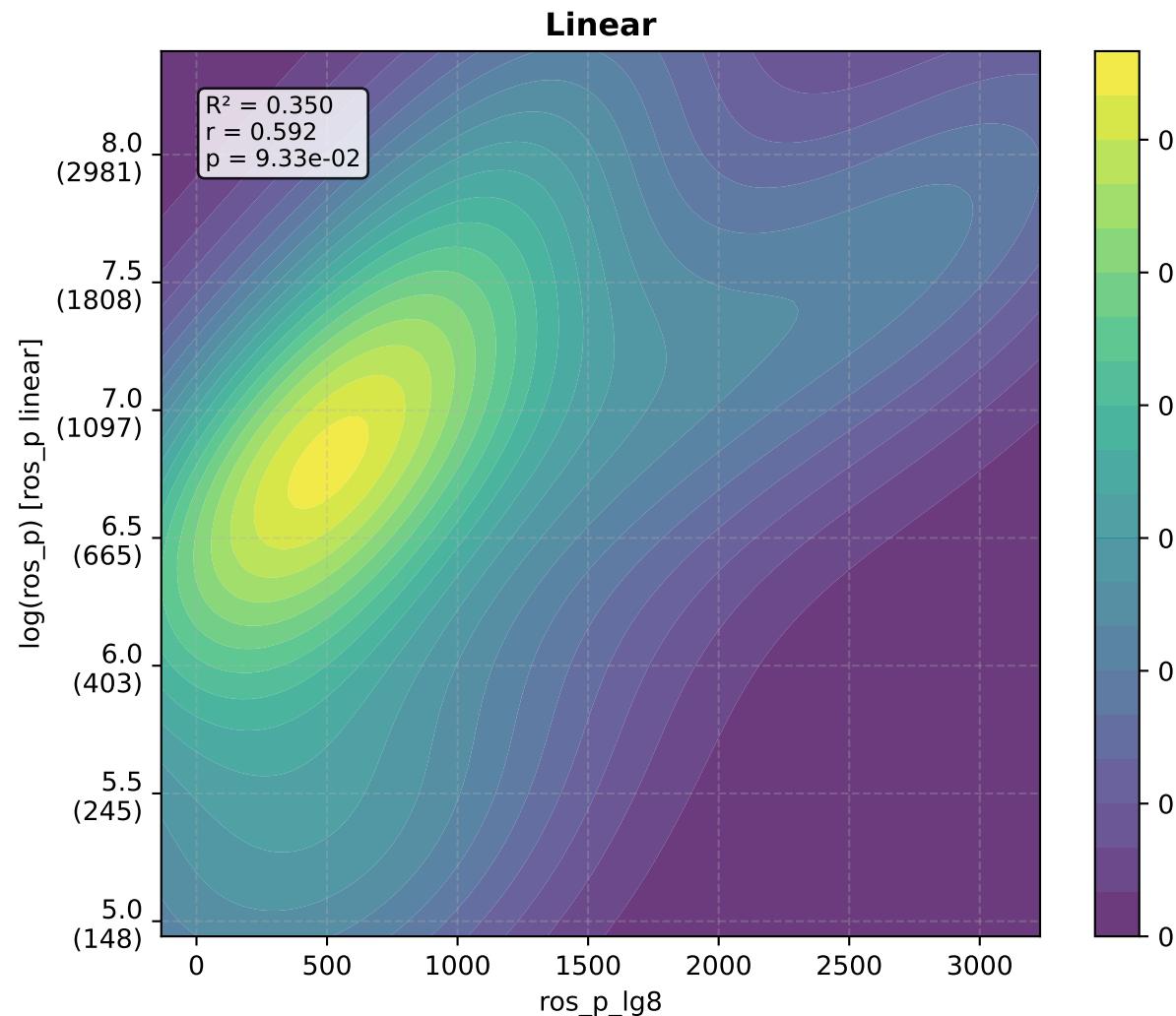
ros_p_lg6 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



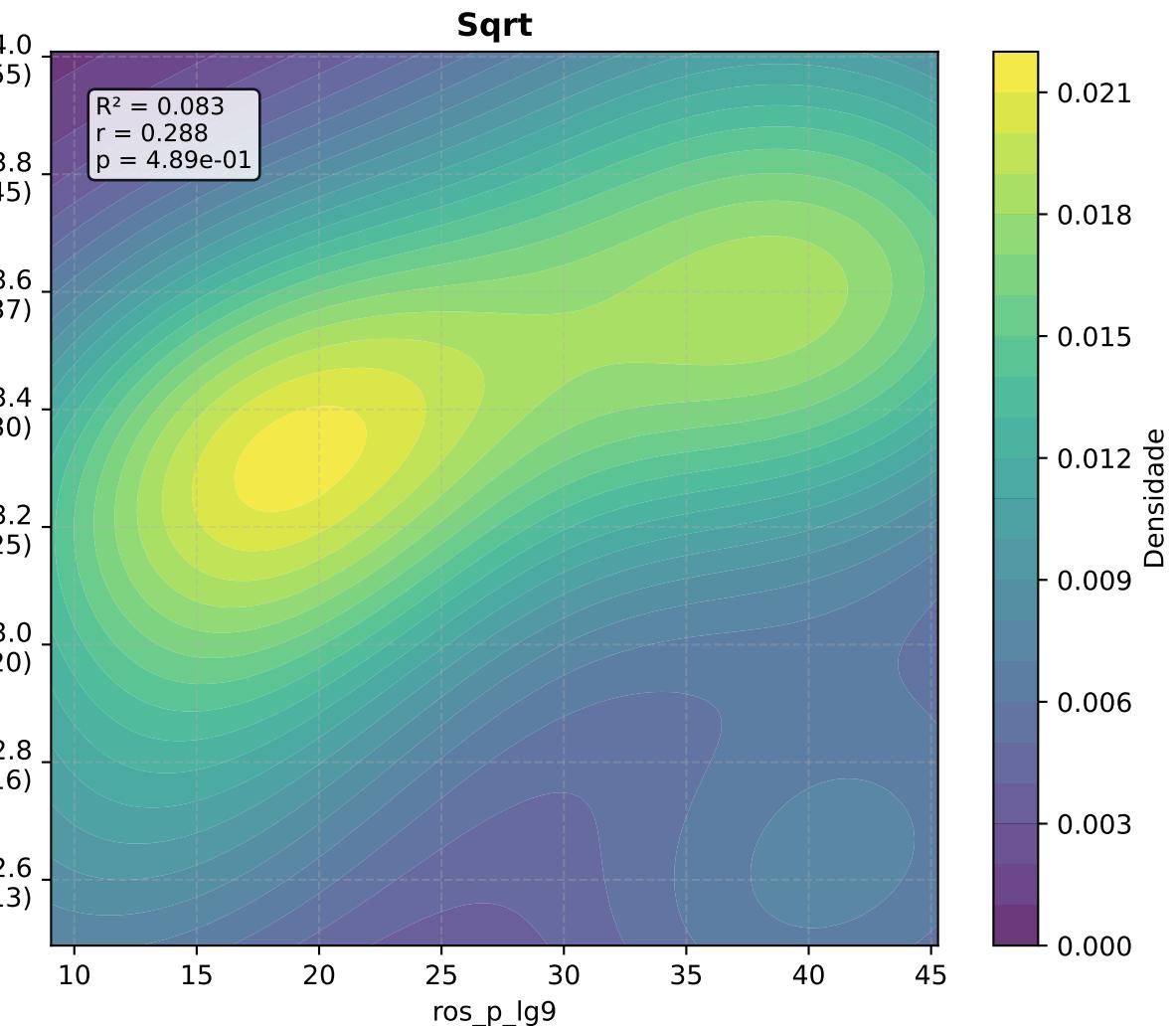
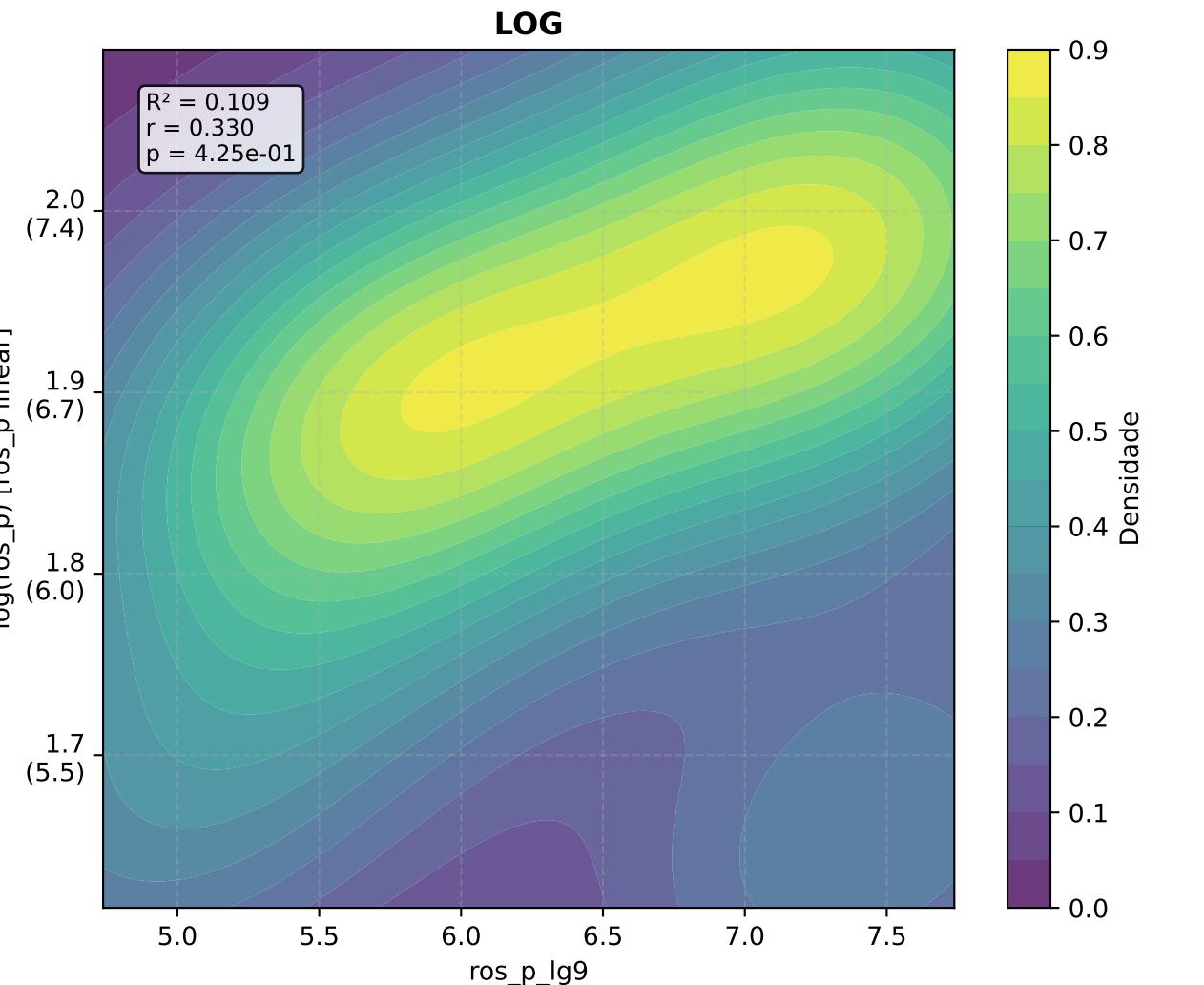
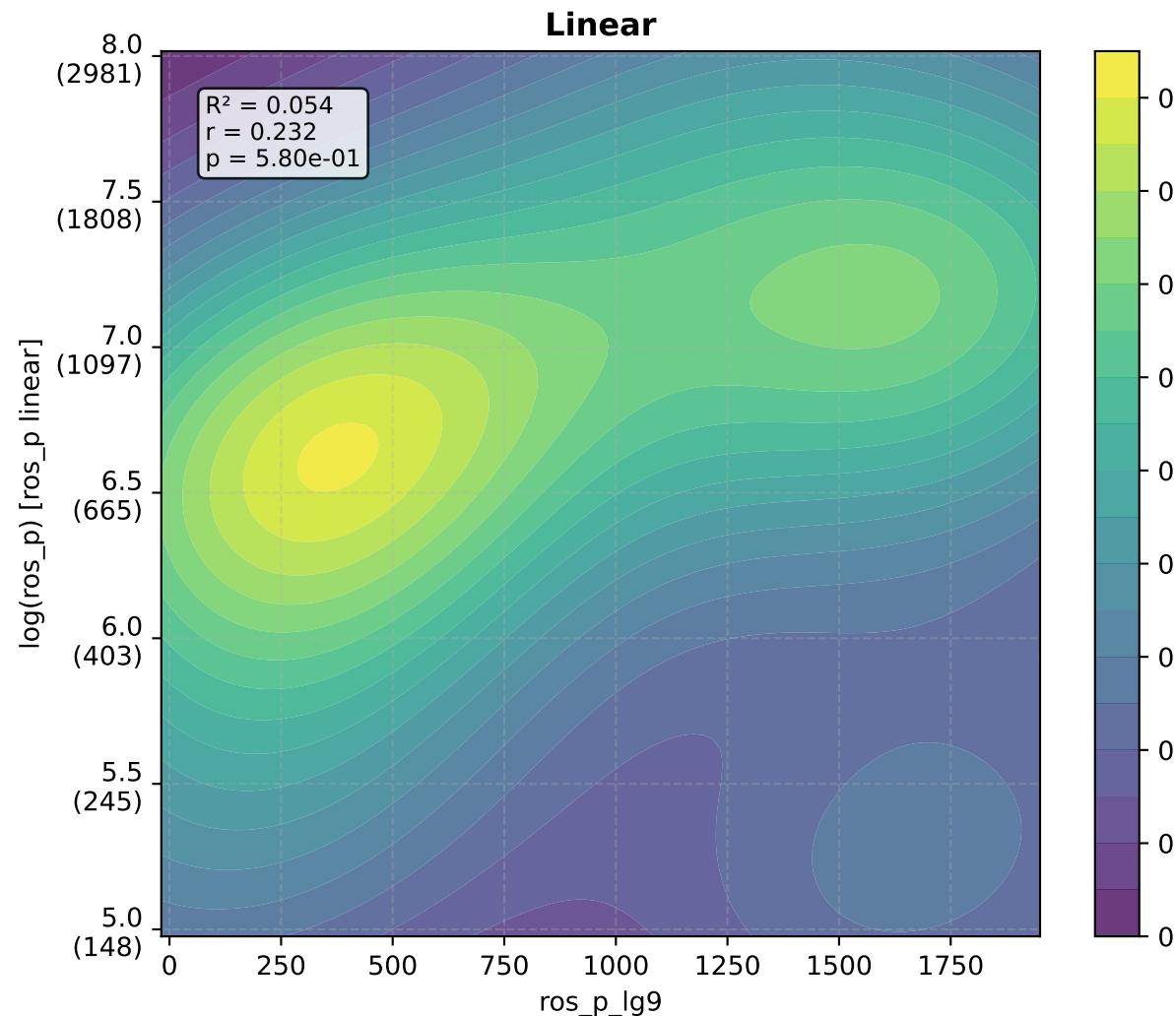
ros_p_lg7 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



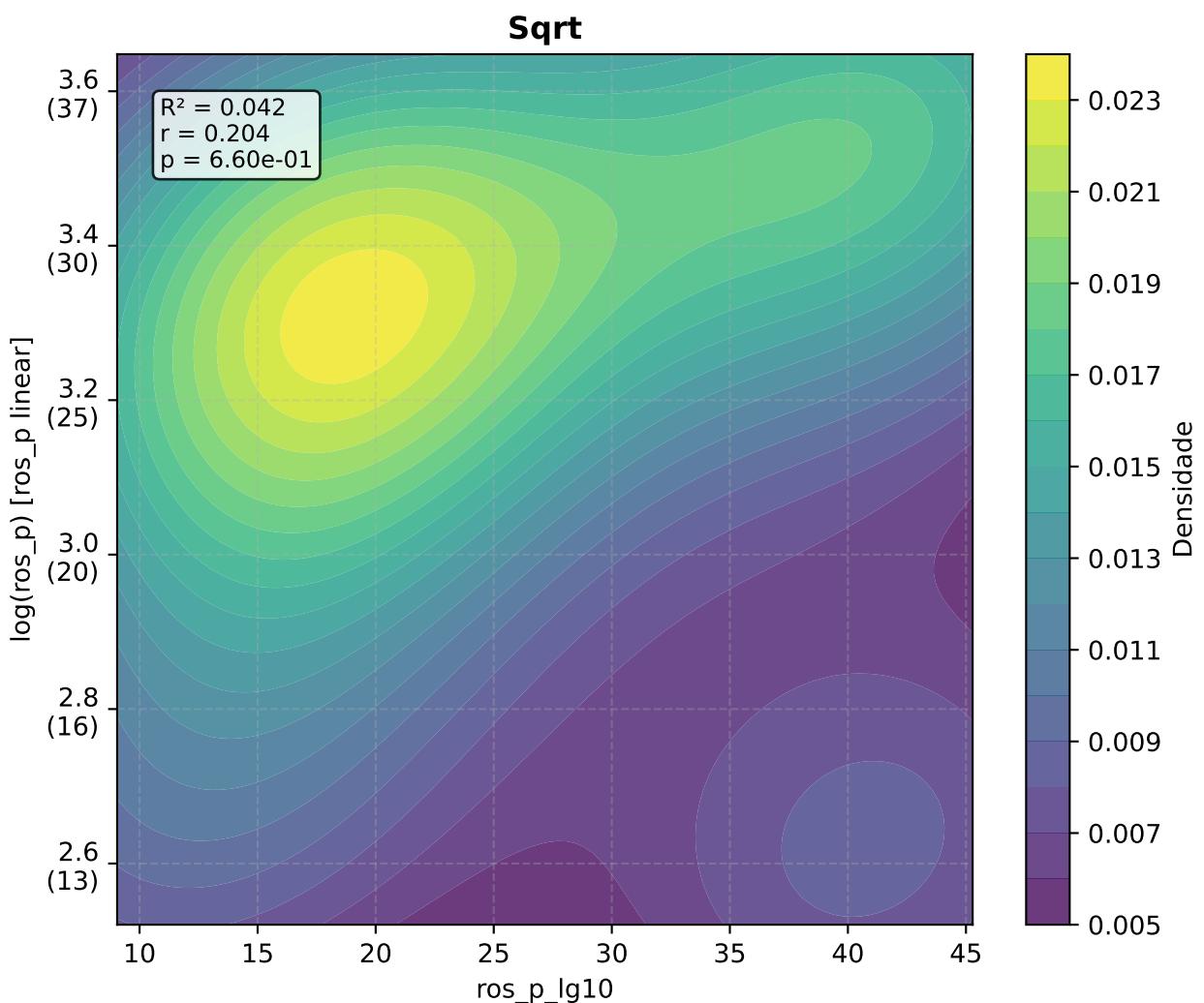
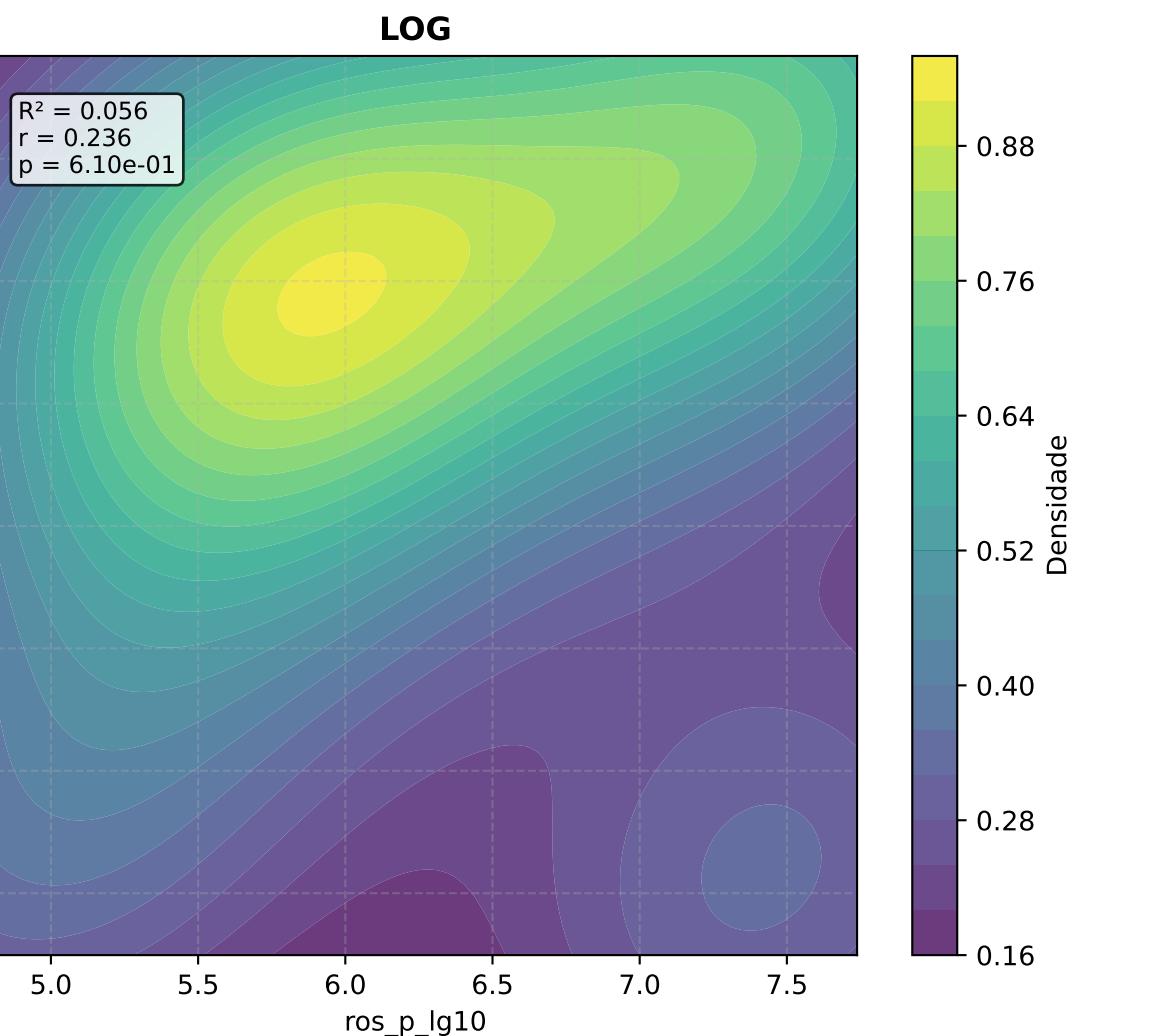
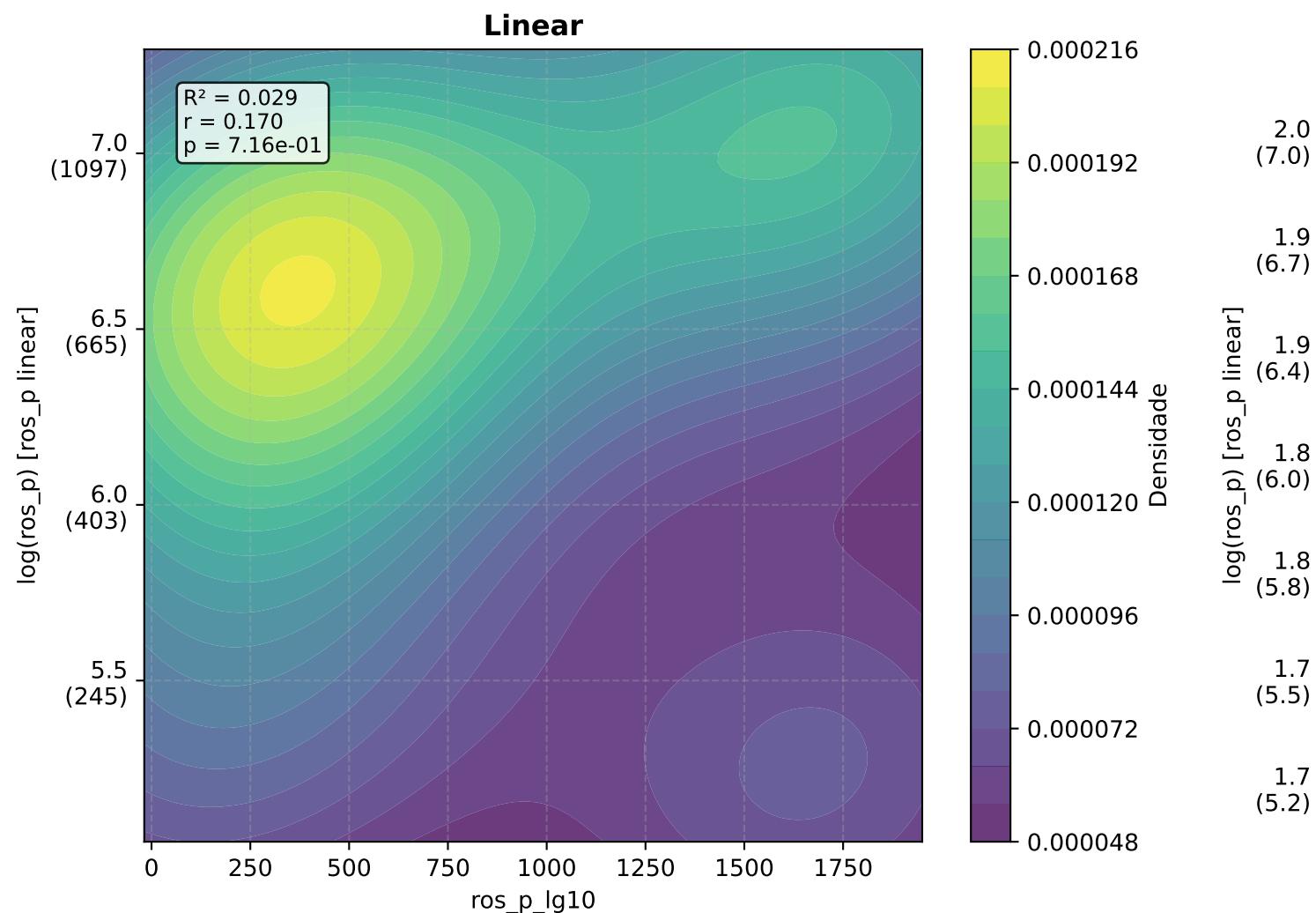
ros_p_lg8 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



ros_p_lg9 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



ros_p_lg10 vs ros_p - KDE Cloud (Linear, LOG & Sqrt)



f_start vs ros_p - KDE Cloud (Linear, LOG & Sqrt)

