Graph Learning 6. Spectral Embedding

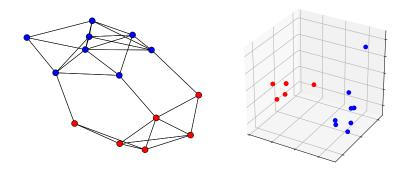
Thomas Bonald

2024 - 2025



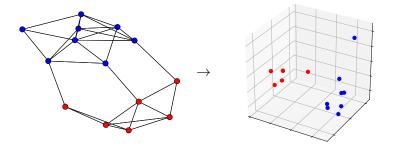
Motivation

Representation of a graph in a vector space of low dimension



Outline

- ► Laplacian matrix
- ► Transition matrix
- Spectral embedding
- ► Algorithms
- Extensions



Laplacian matrix

Definition

$$L = D - A$$

Properties

- Symmetric
- ► Positive semi-definite
- Discrete differential operator

$$L = \nabla^T \nabla$$

with ∇ the $m \times n$ incidence matrix of the graph

Spectral analysis

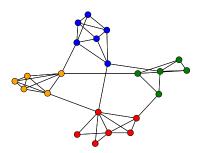
Theorem

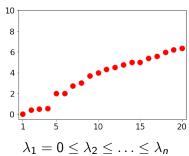
$$L = U \Lambda U^T$$

where

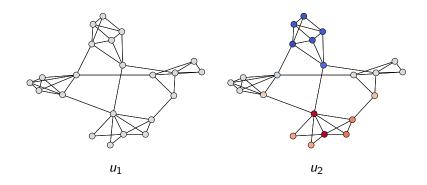
- $V = (u_1, \ldots, u_n)$ with $U^T U = I$
- $ightharpoonup \Lambda = \operatorname{diag}(\lambda_1, \ldots, \lambda_n) \text{ with } \lambda_1 = 0 \le \lambda_2 \le \ldots \le \lambda_n$

Note: $u_1 \propto 1$

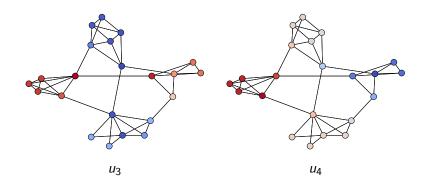




Eigenvectors



Eigenvectors

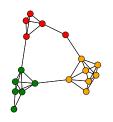


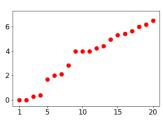
Connected components

Proposition

The **multiplicity** of the eigenvalue $\lambda=0$ of the Laplacian matrix L is equal to the number of connected components of the graph.

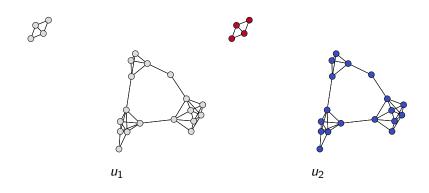






$$\lambda_1=\lambda_2=0<\lambda_3\ldots\leq\lambda_n$$

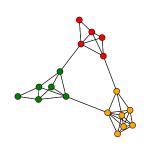
Eigenvectors



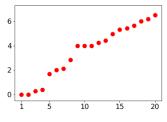
Heat diffusion

Dynamics

$$\forall t \geq 0$$
, $T(t) = e^{-Lt}T(0)$ with $e^{-Lt} = Ue^{-\Lambda t}U^T$







$$\lambda_1=\lambda_2=0<\lambda_3\ldots\leq\lambda_n$$

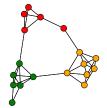
Regularization

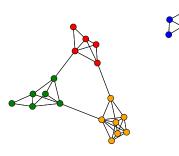
Principle

When the graph is disconnected, use

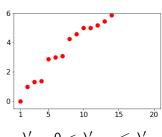
$$A' = A + \frac{11^T}{n} \quad D' = D + I$$







Regularization



$$\lambda_1'=0<\lambda_2'\ldots\leq\lambda_n'$$

Outline

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- 2. Transition matrix
- 3. Spectral embedding
- 4. Algorithms
- 5. Extensions

Transition matrix

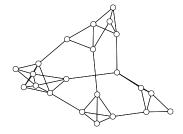
Definition

$$P = D^{-1}A$$

Property

P is a stochastic matrix:

$$P \geq 0$$
 and $P1 = 1$



Spectral analysis

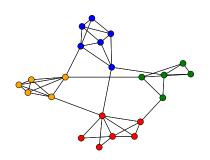
Theorem

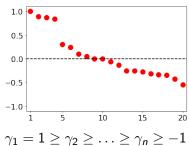
$$P = V\Gamma V^T D$$

where

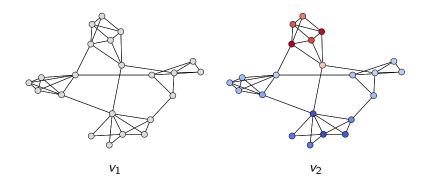
- $V = (v_1, \ldots, v_n)$ with $V^T DV = I$
- $ightharpoonup \Gamma = \operatorname{diag}(\gamma_1, \dots, \gamma_n) \text{ with } \gamma_1 = 1 \geq \gamma_2 \geq \dots \geq \gamma_n \geq -1$

Note: $v_1 \propto 1$

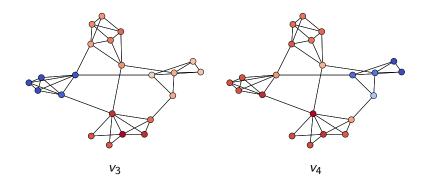




Eigenvectors



Eigenvectors

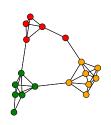


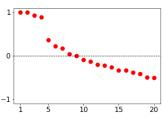
Connected components

Proposition

The **multiplicity** of the eigenvalue $\gamma=1$ of the transition matrix P is equal to the number of connected components of the graph.







$$\gamma_1 = \gamma_2 = 1 > \ldots \geq \gamma_n \geq -1$$

Heat diffusion

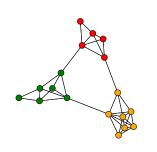
Dynamics

$$\forall t \geq 0, \quad T(t) = P^t T(0) \quad \text{with} \quad P^t = V \Gamma^t V^T D$$

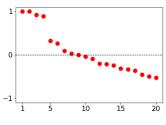
Heat diffusion

Dynamics

$$\forall t \geq 0$$
, $T(t) = P^t T(0)$ with $P^t = V \Gamma^t V^T D$







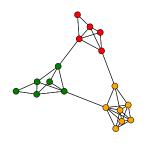
$$\gamma_1 = 1 \ge \gamma_2 \ge \ldots \ge \gamma_n \ge -1$$

Regularization

Principle

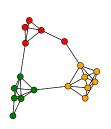
When the graph is disconnected, use

$$A' = A + \frac{11^T}{n} \quad D' = D + I$$

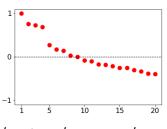








Regularization



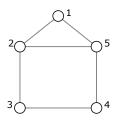
$$\gamma_1'=1>\gamma_2'\geq\ldots\geq\gamma_n'\geq-1$$

Exercise

The top eigenvalues of the transition matrix are:

$$\gamma_1=1, \gamma_2=\frac{1}{3}, \gamma_3=0$$

Give the corresponding **right eigenvectors**.

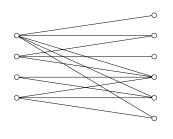


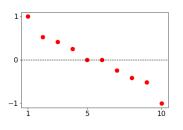
Case of bipartite graphs

Proposition

The transition matrix of a bipartite graph has a **symmetric** spectrum:

 γ eigenvalue \iff $-\gamma$ eigenvalue

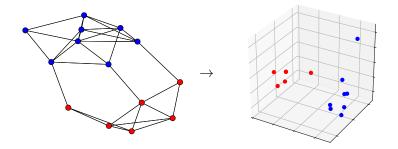




$$\gamma_1 = 1 > \gamma_2 \ge \ldots \ge \gamma_{n-1} > \gamma_n = -1$$

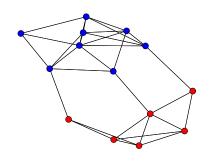
Outline

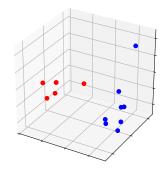
- 1. Laplacian matrix
- 2. Transition matrix
- 3. Spectral embedding
- 4. Algorithms
- 5. Extensions



An optimization problem

$$\min_{X} \sum_{i < j} A_{ij} ||X_i - X_j||^2$$





Laplacian matrix

Lemma

$$\operatorname{tr}(X^T L X) = \sum_{i < j} A_{ij} ||X_i - X_j||^2$$

Spectral embedding

Definition

Embedding $X = (u_2, \dots, u_{K+1})$ given by the first K eigenvectors (except the first) of the **Laplacian matrix** L

Theorem

The spectral embedding is optimal:

$$X = \arg\min_{X:X^T = 0, X^T X = I_K} \operatorname{tr}(X^T L X)$$

Spectral embedding

Definition

Embedding $X = (u_2, \dots, u_{K+1})$ given by the first K eigenvectors (except the first) of the **Laplacian matrix** L

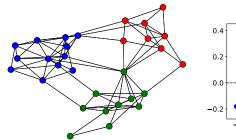
Theorem

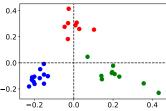
The spectral embedding is optimal:

$$X = \arg\min_{X:X^T = 0, X^T X = I_K} \operatorname{tr}(X^T L X)$$

Note: The embedding is centered:

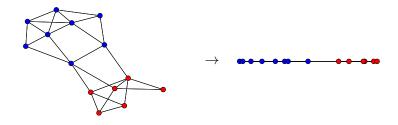
$$\sum_{i=1}^n X_i = 0$$





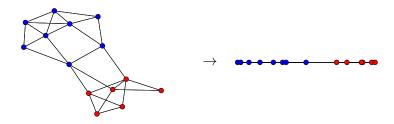
A mechanical system

Nodes = particles, edges = (attractive) springs Put nodes on a line at positions $x_1, \ldots, x_n \in \mathbb{R}$



A mechanical system

Nodes = particles, edges = (attractive) springs Put nodes on a line at positions $x_1, ..., x_n \in \mathbb{R}$

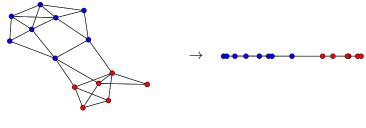


Potential energy

$$E = \frac{1}{2} \sum_{i < i} A_{ij} (x_i - x_j)^2 = \frac{1}{2} x^T L x$$

A harmonic oscillator

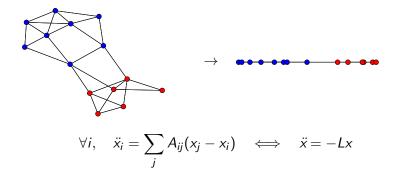
Let the system **evolve**, assuming **unit** masses, starting from positions $x_1, \ldots, x_n \in \mathbb{R}$



$$\forall i, \quad \ddot{x}_i = \sum_i A_{ij}(x_j - x_i) \quad \Longleftrightarrow \quad \ddot{x} = -Lx$$

A harmonic oscillator

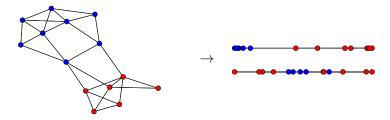
Let the system **evolve**, assuming **unit** masses, starting from positions $x_1, \ldots, x_n \in \mathbb{R}$



Eigenvectors of $L \rightarrow$ **eigenmodes** Eigenvalues of $L \rightarrow$ **levels of energy**

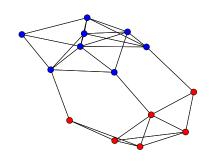
Eigenmodes

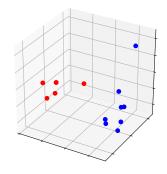
The most interesting **eigenmodes** are those of **lowest energy** (equivalently, of lowest eigenfrequency)



Back to the optimization problem

$$\min_{X:X^T = 0, X^T X = I} \sum_{i < j} A_{ij} ||X_i - X_j||^2$$





Spectral embedding

Definition

Embedding $X = (v_2, ..., v_{K+1})$ given by the K leading eigenvectors (except the first) of the **transition matrix** P

Theorem

The spectral embedding is optimal:

$$X = \arg\min_{X: X^T d = 0, X^T D X = I_K} \operatorname{tr}(X^T L X)$$

Spectral embedding

Definition

Embedding $X = (v_2, ..., v_{K+1})$ given by the K leading eigenvectors (except the first) of the **transition matrix** P

Theorem 1

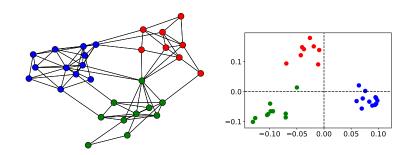
The spectral embedding is optimal:

$$X = \arg\min_{X: X^T d = 0, X^T D X = I_K} \operatorname{tr}(X^T L X)$$

Note: The **weighted** embedding is centered:

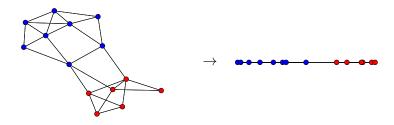
$$\sum_{i=1}^n d_i X_i = 0$$

Example



Back to the mechanical system

Nodes = particles, edges = (attractive) springs Put nodes on a line at positions $x_1, ..., x_n \in \mathbb{R}$

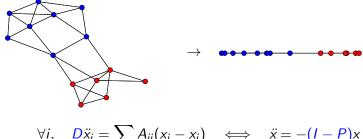


Potential energy

$$E = \frac{1}{2} \sum_{i < j} A_{ij} (x_i - x_j)^2 = \frac{1}{2} x^T L x$$

Harmonic oscillator

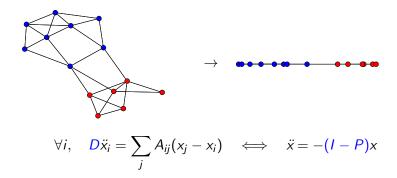
Let the system **evolve**, with **masses** equal to the **degrees**, starting from positions $x_1, \ldots, x_n \in \mathbb{R}$



$$\forall i, \quad D\ddot{x}_i = \sum_i A_{ij}(x_j - x_i) \quad \Longleftrightarrow \quad \ddot{x} = -(I - P)x$$

Harmonic oscillator

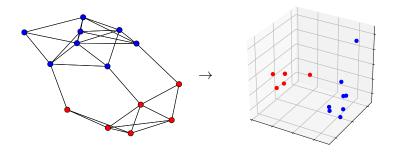
Let the system **evolve**, with **masses** equal to the **degrees**, starting from positions $x_1, \ldots, x_n \in \mathbb{R}$



Eigenvectors of $P \rightarrow$ eigenmodes 1 - eigenvalues of $P \rightarrow$ levels of energy

Outline

- 1. Laplacian matrix
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Algorithms

Need to compute the first **eigenvectors** of some matrix M (either the Laplacian L or the normalized Laplacian $D^{-\frac{1}{2}}LD^{-\frac{1}{2}}$)

Lanczos' algorithm Power iteration

Lanczos 1950

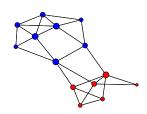
$$x \leftarrow \frac{Mx}{||Mx||}$$

Halko's algorithm

Random projection Power iteration QR decomposition Halko 2009

Back to regularization

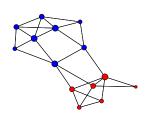
$$A' = A + \frac{11^T}{n}$$



The adjacency matrix becomes dense...

Back to regularization

$$A' = A + \frac{11^T}{n}$$

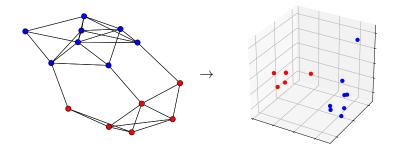


The adjacency matrix becomes **dense**... but with a nice **sparse** + **low** rank structure:

$$A'x = Ax + \frac{1^Tx}{n}1$$

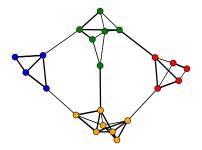
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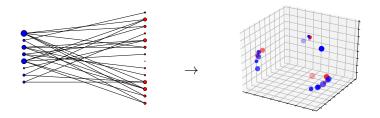
Weighted graphs

$$\min_{X} \sum_{i < j} A_{ij} ||X_i - X_j||^2$$



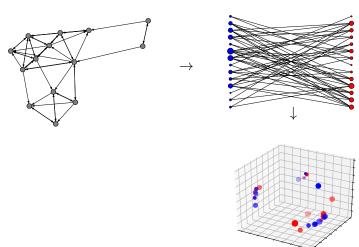
Case of bipartite graphs

Co-embedding of nodes in the same space



Case of directed graphs

Idea: See the directed graph as a bipartite graph, with biadjacency matrix \boldsymbol{A}



Summary

Spectral embedding

- Based on the spectral decomposition of the **Laplacian matrix** L = D A or the **transition matrix** $P = D^{-1}A$
- ► Eigenmodes of a mechanical system
- ► Fast and scalable algorithms
- ► Applicable to **weighted**, **bipartite** and **directed** graphs

