# Random Forests, Bagging, and Boosting

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#### Credits:

Jake VanderPlas, Python Data Science Handbook
P. Protopapas, K. Rader, W. Pan, Harvard
Hastie et al.,"The Elements of Statistical Learning: Data Mining,
Inference, and Prediction", Springer (2009)

#### Outline

**Bagging** 

**Random Forests** 

Boosting

#### Power of the crowds

Wisdom of the crowds



Crowdsourcing predictors?

#### Ensemble methods

- A single decision tree does not perform well
- But, it is super fast
- What if we learn multiple trees?
  - We need to make sure they do not all just learn the same.

# Bagging (Bootstrap Aggregating)

If we split the data in random different ways, decision trees give different results, **high variance**.

**Bagging:** Bootstrap **agg**regating is a method that results in **low** variance.

If we had multiple realizations of the data (or multiple samples) we could calculate the predictions multiple times and take the average of the fact that averaging multiple onerous estimations produce less uncertain results.

Averaging a set of observations reduces variance:  $\sigma^2/n$ 

#### Bagging

For each sample b, we calculate  $f^b(x)$ , then:

$$\hat{f}_{avg}(x) = \frac{1}{B} \sum_{b=1}^{B} \hat{f}^b(x)$$

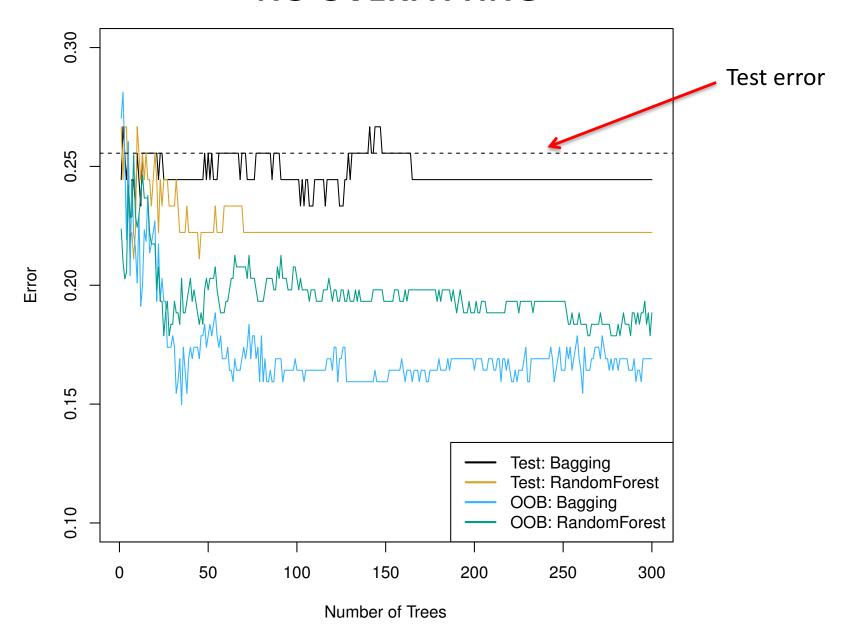
How? Bootstrap

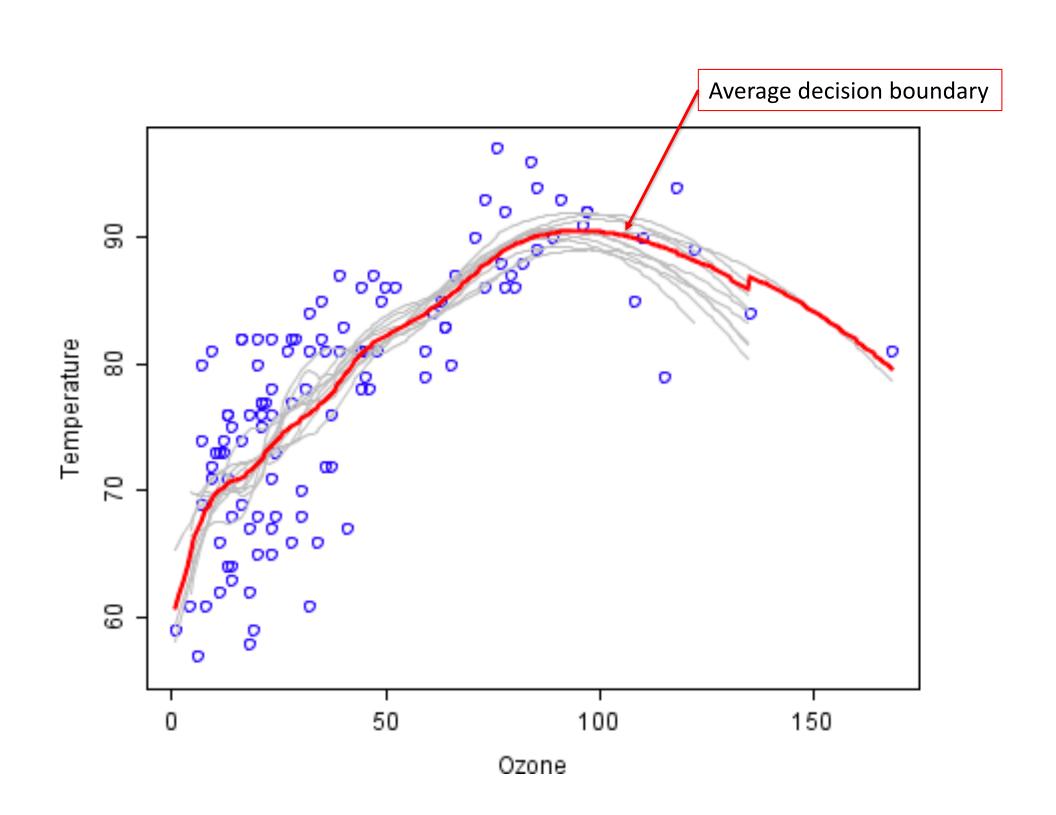
Construct B (hundreds) of trees (no pruning)

Learn a classifier for each bootstrap sample and average them:

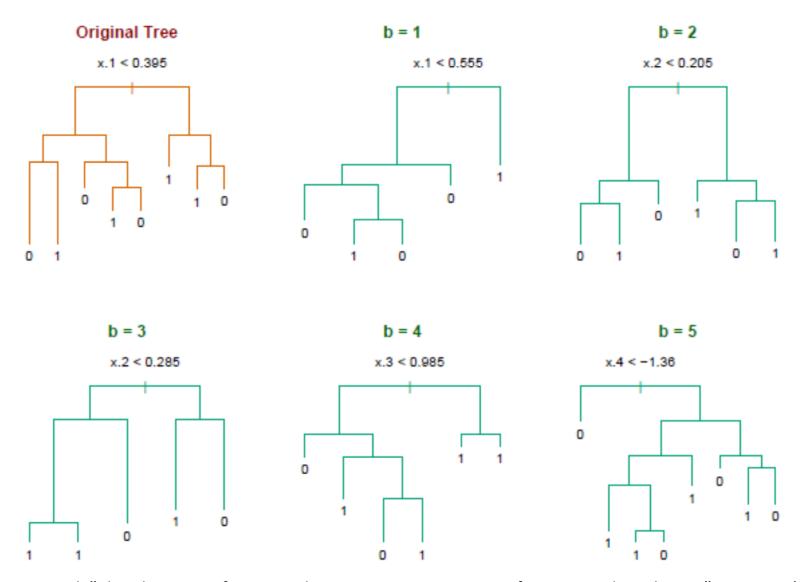
Very effective

# **Bagging for classification**: Majority vote **NO OVERFITTING**





# Bagging decision trees



Hastie et al.,"The Elements of Statistical Learning: Data Mining, Inference, and Prediction", Springer (2009)

# Out-of-Bag Error Estimation

- Given a standard training set D of size n, bagging generates m new training sets  $D_i$ , each of size n', by sampling from D uniformly with replacement.
- By sampling with replacement, some observations may be repeated in each  $D_{i}$ .
- If n'=n, then for large n the set  $D_i$  is expected to have the fraction (1 1/e) ( $\approx 63.2\%$ ) of the unique examples of D, the rest being duplicates.
- Observations not used in each bootstrap sample ( $^{\sim}1/3$ ) are called out-of-bag samples (OOB).
- We can predict the response for the *i-th* observation using each of the trees in which that observation was OOB and do this for *n* observations.
- Calculate overall OOB MSE or classification error.

\*The probability that an observation is omitted is  $(1 - \frac{1}{n})^n$ .

$$\exp(-1) = \lim_{n \to \infty} (1 - \frac{1}{n})^n$$

$$\exp(-1) = 0.3678... \approx \frac{1}{3}$$

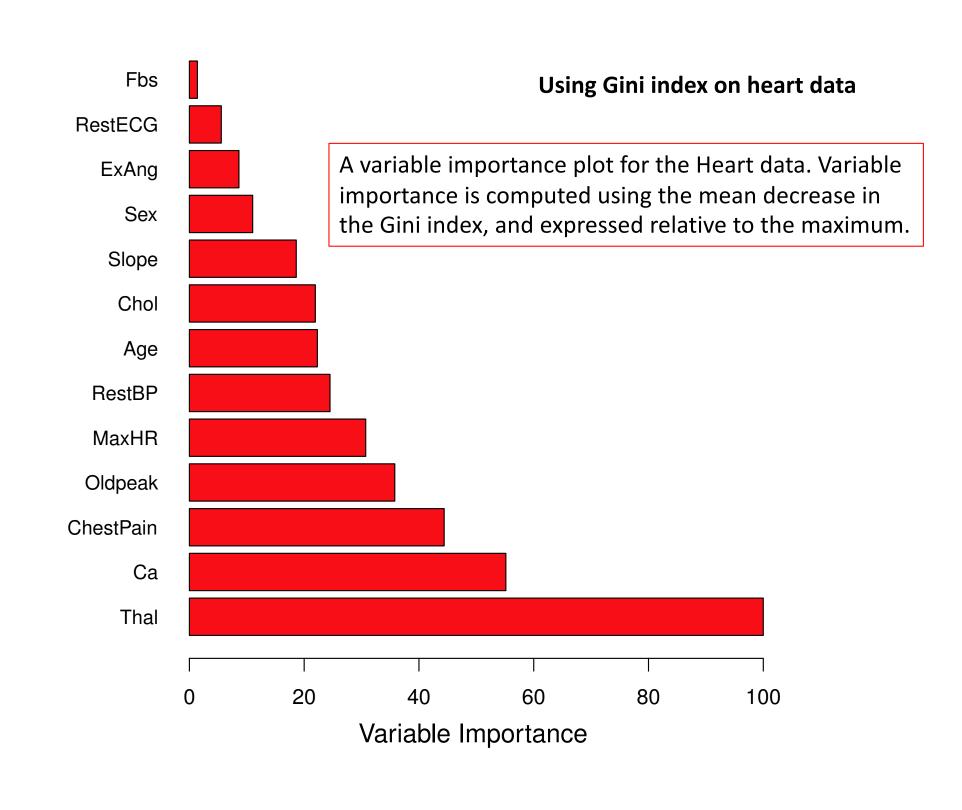
## Bagging

- Reduces overfitting (variance)
- Normally uses one type of classifier
- Decision trees are popular
- Easy to parallelize

#### Variable Importance Measures

- Bagging results in improved accuracy over prediction using a single tree.
- Unfortunately, difficult to interpret the resulting model.
- Bagging improves prediction accuracy at the expense of interpretability.

Calculate the total amount that the **RSS** or **Gini index** is decreased due to splits over a given predictor, averaged over all B trees.



## Variable Importance Measures

Record the prediction accuracy on the OOB samples for each tree.

Randomly permute the data for column *j* in the oob samples the record the accuracy again.

The decrease in accuracy as a result of this permuting is averaged over all trees, and is used as a measure of the importance of variable *j* in the random forest.

Each tree is identically distributed (i.d.), but not mutually independent.

- the expectation of the average of B such trees is the same as the expectation of any one of them.
- the bias of bagged trees is the same as that of the individual trees.
- i.d. and not i.i.d (independent and identically distributed).

A collection of random variables is independent and identically distributed (i.i.d. or IID) if each random variable has the same probability distribution as the others and all are mutually independent.

- An average of B i.i.d. random variables, each with variance  $\sigma^2$ , has variance:  $\sigma^2/B$
- If i.d. (identical but not independent) and pair correlation  $\rho$  is present, then the variance is:

$$\rho \, \sigma^2 + \frac{1 - \rho}{B} \sigma^2$$

- As B increases the second term disappears but the first term remains.
- Why does bagging generate correlated trees?

- Suppose that there is one very strong predictor in the data set, along with a number of other moderately strong predictors.
- Then all bagged trees will select the strong predictor at the top of the tree and therefore all trees will look similar.
- How do we avoid this?

#### Ideas:

- Penalize the splitting (like in pruning) with a penalty term that depends on the number of times a predictor is selected at a given length.
- Restrict how many times a predictor can be used.
- Only allow a certain number of predictors.

 We want i.i.d such as the bias to be the same and variance to be less.

#### Other ideas:

What if we consider only a *subset of the predictors* at each split?

 We will still get correlated trees unless .... we randomly select the subset!

#### Outline

Bagging

**Random Forests** 

Boosting

#### Random Forests

- As in bagging, we build a number of decision trees on bootstrapped training samples.
- Each time a split in a tree is considered, a random sample of m predictors is chosen as split candidates from the full set of p predictors.

Note: that if m = p, then this is just bagging.

#### Random Forests

- Random forests are very popular.
- Leo Breiman's and Adele Cutler maintains a random forest website where the software is freely available, and it is included in every ML/STAT package.

http://www.stat.berkeley.edu/~breiman/RandomForests/

## Random Forests Algorithm

For b = 1 to B:

- (a) Draw a bootstrap sample Z\* of size N from the training data.
- (b) Grow a random-forest tree to the bootstrapped data, by recursively repeating the following steps for each node of the tree, until the minimum node size  $n_{min}$  is reached.
  - i. Select m variables at random from the p variables.
  - ii. Pick the best variable/split-point among the m.
  - iii. Split the node into two daughter nodes.

Output the ensemble of trees.

To make a prediction at a new point x we do:

For regression: average the results

For classification: majority vote

## Random Forests Tuning

The inventors make the following recommendations:

- For classification, the default value for m is sqrt(p) and the minimum node size is one.
- For regression, the default value for m is p/3 and the minimum node size is five.

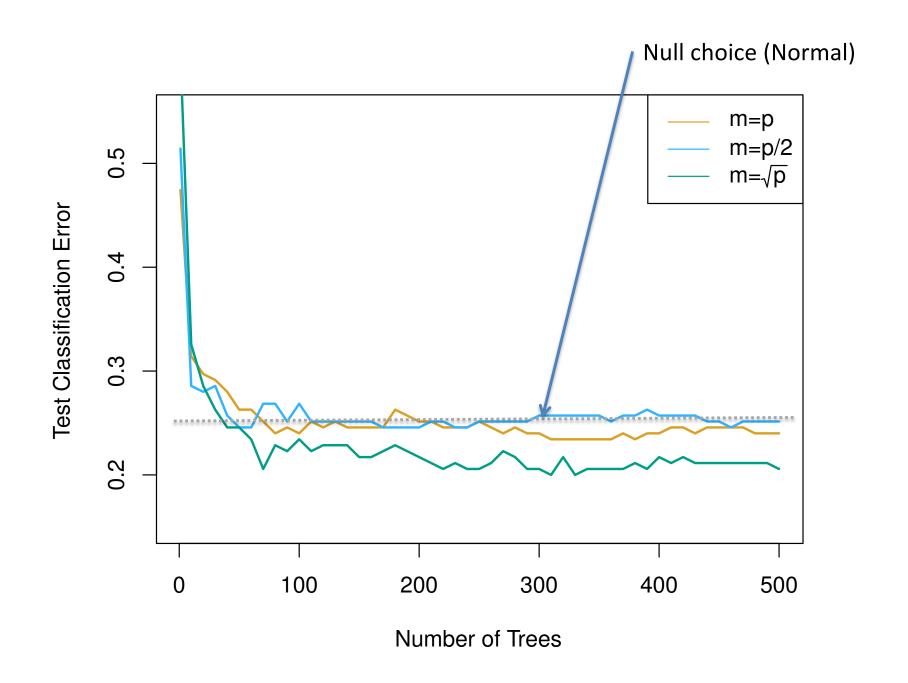
In practice the best values for these parameters will depend on the problem, and they should be treated as tuning parameters.

Like with Bagging, we can use OOB and therefore RF can be fit in one sequence, with cross-validation being performed along the way. Once the OOB error stabilizes, the training can be terminated.

# Example

- 4,718 genes measured on tissue samples from 349 patients.
- Each gene has different expression.
- Each of the patient samples has a qualitative label with 15 different levels: either normal or 1 of 14 different types of cancer.

Use random forests to predict cancer type based on the 500 genes that have the largest variance in the training set.



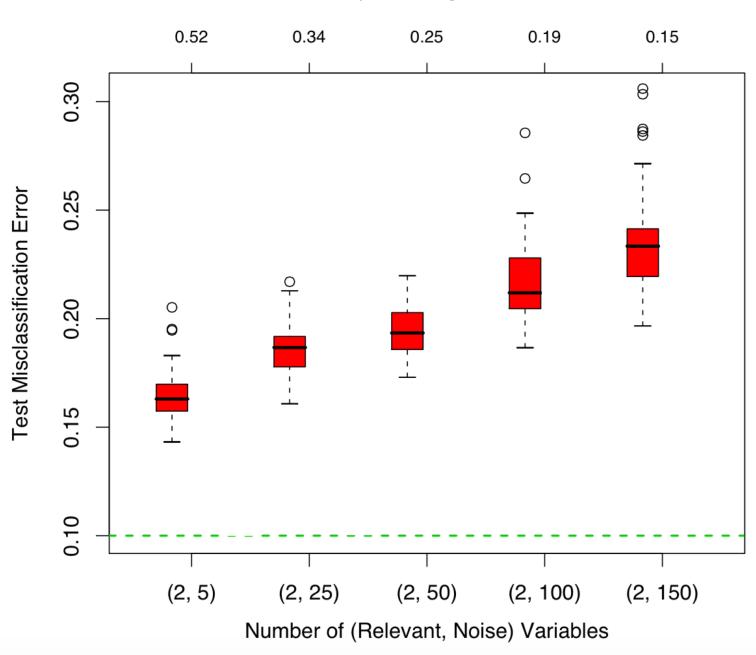
#### Random Forests Issues

When the number of variables is large, but the fraction of relevant variables is small, random forests are likely to perform poorly when *m* is small.

#### Why?

- At each split the chance can be small that the relevant variables will be selected.
- For example, with 3 relevant and 100 not so relevant variables the probability of any of the relevant variables being selected at any split is ~0.25.

#### Probability of being selected



#### Can RF overfit?

Random forests "cannot overfit" the data wrt to number of trees.

#### Why?

The number of trees, *B*, does not mean increased flexibility of the model.

#### Note on RF's

- There is a lot of discussion about gains in performance by controlling the depths of the individual trees grown in random forests.
- Full-grown trees seldom costs much (in the classification error) and results in one less tuning parameter.

#### Outline

Bagging

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## Boosting

Boosting is a general approach that can be applied to many statistical learning methods for regression or classification.

**Bagging**: Generate multiple trees from bootstrapped data and average the trees.

Recall bagging results in i.d. trees and not i.i.d.

**RF** produces i.i.d (or more independent) trees by randomly selecting a subset of predictors at each step.

# Boosting

Boosting works very differently.

- 1. Boosting does not involve bootstrap sampling
- 2. Trees are grown sequentially: each tree is grown using information from previously grown trees
- 3. Like bagging, boosting involves combining a large number of decision trees,  $f^1, \ldots, f^B$

# Sequential fitting

Given the current model,

- Fit a decision tree to the residuals (incorrectly classified samples) from the model.
- Add this new decision tree into the fitted function in order to update the residuals.
- The learning rate has to be controlled.

# Boosting for regression

- 1. Set f(x)=0 and  $r_i=y_i$  for all i in the training set.
- 2. For b=1,2,...,B, repeat:
  - a. Fit a tree with d splits (+1 terminal nodes) to the training data (X, r).
  - b. Update the tree by adding in a shrunken version of the new tree:

$$\hat{f}(x) \leftarrow \hat{f}(x) + \lambda \, \hat{f}^b(x)$$

c. Update the residuals,

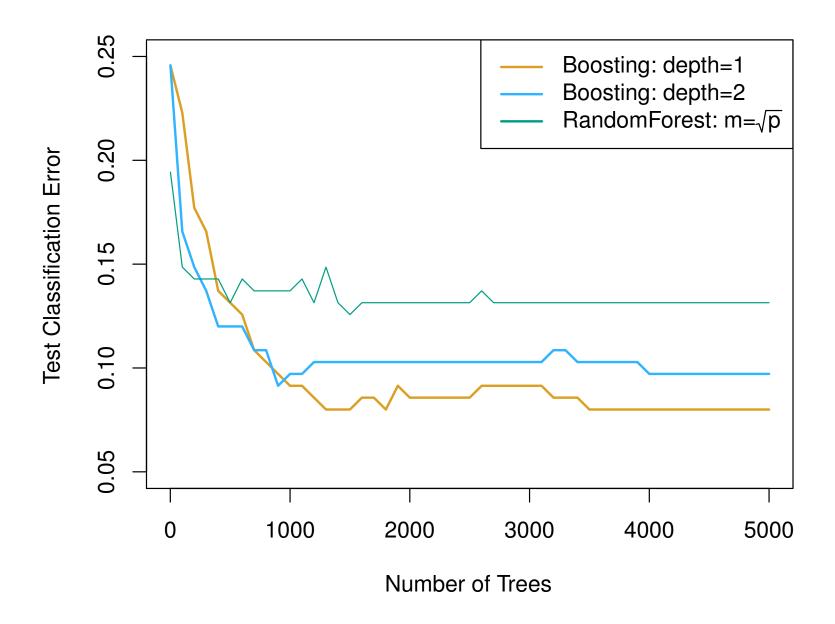
$$r_i \leftarrow r_i - \lambda \hat{f}^b(x_i)$$

3. Output the boosted model,

$$\hat{f}(x) = \sum_{b=1}^{B} \lambda \hat{f}^b(x)$$

#### Boosting tuning parameters

- The number of trees B. RF and Bagging do not overfit as B increases. Boosting can overfit! Cross Validation.
- The shrinkage parameter  $\lambda$ , a small positive number. Typical values are 0.01 or 0.001 but it depends on the problem.  $\lambda$  only controls the learning rate.
- The number d of splits in each tree, which controls the complexity of the boosted ensemble. Stumpy trees, d = 1 works well.



#### **Decision Tree Flavors**

- ID3 (alternative Dichotomizer), was the first of three Decision Tree implementations developed by Ross Quinlan (Quinlan, J. R. 1986. Induction of Decision Trees. Mach. Learn. 1, 1 (Mar. 1986), 81-106.)
   Only categorical predictors and no pruning.
- C4.5, Quinlan's next iteration. The new features (versus ID3) are: (i) accepts both continuous and discrete features; (ii) handles incomplete data points; (iii) solves over-fitting problem by (a very clever) bottom-up technique usually known as "pruning"; and (iv) different weights can be applied to the features that comprise the training data.

Used in orange <a href="http://orange.biolab.si/">http://orange.biolab.si/</a>

#### **Decision Tree Flavors**

- C5.0, The most significant feature unique to C5.0 is a scheme for deriving rule sets. After a tree is grown, the splitting rules that define the terminal nodes can sometimes be simplified: that is, one or more condition can be dropped without changing the subset of observations that fall in the node.
- CART or Classification And Regression Trees is often used as a generic acronym for the term Decision Tree, though it apparently has a more specific meaning. In sum, the CART implementation is very similar to C4.5. Used in sklearn.

#### Missing data

- What if we miss predictor values?
  - Remove those examples => depletion of the training set
  - Impute the values either with mean, knn, from the marginal or joint distributions.
- Trees have a nicer way of doing this
  - Categorical.

#### Further reading

- Pattern Recognition and Machine Learning, Christopher M.
   Bishop
- The Elements of Statistical Learning
   Trevor Hastie, Robert Tibshirani, Jerome Friedman
   <a href="http://statweb.stanford.edu/~tibs/ElemStatLearn/printings/ESLII\_print10.pdf">http://statweb.stanford.edu/~tibs/ElemStatLearn/printings/ESLII\_print10.pdf</a>