

# Rafael Meireles Saback

Brazilian

Warsaw, Poland

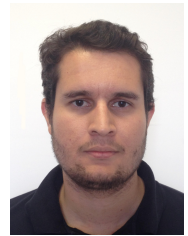
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Visa: Has work permit

[Github](#)

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## Summary

A focused and results-oriented professional who is an expert in analytical problem solving. Rafael is well-versed in front-end development skills, besides also having expertise in database concepts and Linux. Rafael is a fast learner and has a strong passion for learning new skills. He is fluent in Portuguese (native), English and Spanish, besides an intermediate knowledge of Polish (B1 national certificate).

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## Technical Skills & Tools

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|--------------|-----------|-----------------|
| • HTML5      | • C++     | • Apache JMeter |
| • CSS3       | • Linux   | • Jira          |
| • JavaScript | • Git     | • Vim           |
| • Sass       | • SQL     | • Atom          |
| • TypeScript | • Webpack | • Eclipse       |

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## Professional Experience

### Microstrategy GDC

August 2017 - Present

Senior Associate Consultant

Poland

The role consisted in the development of BI documents and dashboards on MicroStrategy's platform. Participated in two main projects, one on-site in Spain (Spanish skills were required) and one off-site with a client in Japan.

The technical skills developed were:

- Advanced customization of interactive documents using HTML, CSS and JavaScript/jQuery
- Stress and functional web testing using Apache JMeter
- DDL scripts for table creation and data loading into MS SQL database
- DML statements to retrieve data from database

### Brazilian Institute of Robotics / SENAI CIMATEC

August 2013 - December 2016

Underwater Robotics Researcher

Brazil

Major part of software development was done in C++, while a minor part, especially concerning the sys-

tem management layer, was done in Ruby. The whole programming was performed in Linux environment.

Member of the team responsible for hardware integration and maintenance, which comprised:

- Integration of sensors, thrusters and electronics inside FlatFish;
- Commissioning tests;

Member of the team responsible for software development and integration, which comprised:

- Development of algorithms used to control FlatFish's position (C++);
- Execution of unit tests for the components using Boost library;
- Development and integration of software components into the robotics framework ([Robot Construction Kit](#)) using Ruby;
- Development of GUIs using Qt with the purpose of monitoring FlatFish;
- FlatFish's system configuration in Linux environment.

**DFKI**

**Germany**

July 2014 - July 2015

Guest Researcher

Member of the team responsible for hardware integration, which comprised:

- Integration of sensors, thrusters and computers inside FlatFish;
- Commissioning tests.

Member of the team responsible for software development (C++, Ruby and Linux), which comprised:

- Development of communication driver for Seabotix LBV150;
- Development of control system for dealing with time-delayed underwater vehicles;

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## Education

- **Master in Electrical/Electronic Engineering (2017)** **Brazil**  
Federal University of Bahia (UFBA) - 2 years  
*"Robust Nonlinear Model Predictive Control with Fault-Tolerant Control Allocation Applied to an Autonomous Underwater Vehicle"*
- **Engineer's Degree in Electrical/Electronic Engineering (2013)** **Brazil**  
Federal University of Bahia (UFBA) - 5 years  
*"Evaluation of Advanced Control Strategy with Constraints for Stabilization of Severe Slug Flow"*

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## Language Skills

- Portuguese: native language
- English: fluent
- Spanish: fluent
- Polish: intermediate (B1 national certificate)