

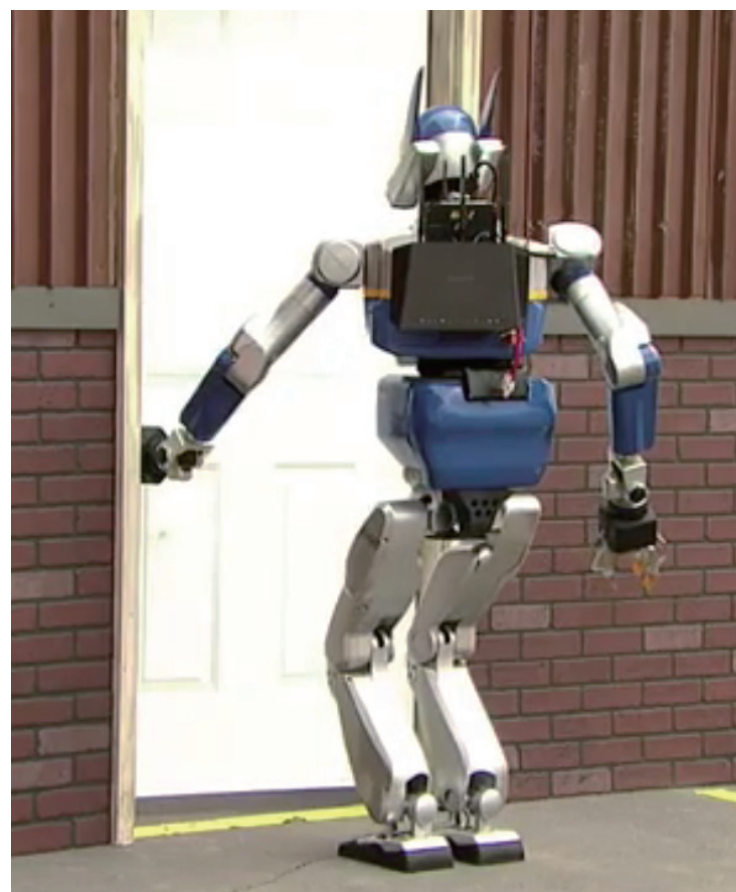
(a) LRF measurement
17:57:09 06/06/2015 UTC



(b) Walk to the opendoor point
17:57:50 06/06/2015 UTC



(c) Robot at the opendoor pose
17:57:09 06/06/2015 UTC



(d) The door open
17:59:57 06/06/2015 UTC