Generalized symmetries and topological defects in 2d CFT

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These notes explore the interplay between two-dimensional conformal field theories (2D CFTs) and generalized symmetries. The motivation of this interplay is shown from the perspective of boundary and interface CFTs, and later on, we present an axiomatic approach to topological defect lines in CFTs. The Ising model is constructed from the standard 2D minimal model, while the defect lines it can accommodate are bootstrapped from the modular (defect) bootstrap. The discussion briefly mentions gauging discrete/non-invertible symmetries and their implications.

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I. CONFORMAL FIELD THEORY IN 2D

The study of extended operators has been a long-standing area of research within CFTs. Pioneering work in boundary CFTs by Cardy and rational CFTs by Moore and Seiberg laid the foundation for the explicit construction of extended operators on what today are known as generalized symmetries, as they, in some sense, enrich the structure of CFTs. In this section, we will explore various applications and establish connections between these concepts.

A. The torus partition function

Recall that one can define a 2D CFT on a Riemann surface, up to a universal conformal anomaly. We start by considering the genus g=1 case. Due to the state operator correspondence, the interpretation of correlation functions on the cylinder is straightforward. Starting from a state $|\psi_1\rangle$ at τ_1 , we want to compute the amplitude of $|\psi_2\rangle$ at τ_2 . This is

$$\langle \psi_2 | \psi_1 \rangle = \langle \psi_2 | e^{-HT} | \psi_1 \rangle$$

where H is the generator of time evolution, i.e. dilations, which in the cylinder is given by

$$H = L_0 - \frac{c}{24} + \bar{L}_0 - \frac{c}{24}$$

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and the c factors are interpreted as the Casimir energy. The partition function can thus be constructed from a cylinder evolved in imaginary time by ω_1 with H. To create a torus, we join both ends of the cylinder, allowing for a possible twist, which is realized by inserting a rotation $R = \exp\{2\pi i(L_0 - \bar{L}_0)\}$ of angle ω_2 . This twist comes from the fact that on the torus, one can either fix the periodicity of the torus or the differential structure but not both at the same time; the parameter that measures different torii is called the moduli. Finally, the torus is made from gluing both ends of the cylinder as shown in Figure 1. This is nothing but taking the trace in the above picture for which, setting $(\tau, \bar{\tau}) \equiv (-\omega_2 + i\omega_1, -\omega_2 - i\omega_1)$, the partition function thus can be written as

$$Z(\tau) \equiv \operatorname{tr}_{\mathcal{H}} q^{L_0 - \frac{c}{24}} \bar{q}^{\bar{L}_0 - \frac{c}{24}}, \quad q \equiv e^{2\pi i \tau}, \bar{q} \equiv e^{-2\pi i \bar{\tau}}.$$

Here, the parameter τ of the Riemann surface takes the role of the moduli.

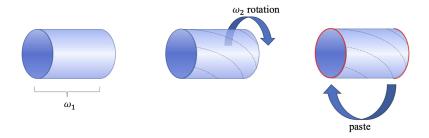


FIG. 1: Torus construction from gluing a cylinder. Image retrived from [2].

The fundamental domain of the group $PSL(2,\mathbb{Z})$ describes uniquely the orbits of equivalent torii and, in particular, this means that the partition function is invariant under these transformations. We consider two particular transformations, the translations T and the modular transformation S, given by:

$$T: \tau \to \tau + 1, \quad S: \tau \to -\frac{1}{\tau}.$$

where, for example, invariance under T requires

$$Z(\tau) = Z(\tau + 1) = \operatorname{tr}_{\mathcal{H}} q^{L_0 - \frac{c}{24}} \bar{q}^{\bar{L}_0 - \frac{c}{24}} e^{2\pi i (L_0 - \bar{L}_0)}.$$

which means that the spin must be an integer. The modular transformation imposes a rather stronger constraint,

$$Z(\tau) = Z\left(-\frac{1}{\tau}\right) \tag{1}$$

which in general puts constraints on the spectrum of the CFT –although it does not determine the underlying CFT as there are examples of CFTs with the same partition function–

By combining the S and T transformations, we can derive conformal bootstrap equations called modular bootstrap equations. Recall that on the sphere one can deduce consistency conditions from the 4-pt function by expanding in the different OPE channels leading to the conformal bootstrap. In the torus, consistency requires relations in the 0-pt function, i.e. the partition function.

Now, because we assume indecomposable representations of the conformal algebra factorize (holomorphic and antiholomorphic representations) one can write the partition function using the Virasoro characters

$$Z = \sum_{(h,\bar{h})} n_{h\bar{h}} \chi_h(q) \chi_{\bar{h}}(\bar{q}),$$

where

$$\chi_i(\tau) \equiv \mathrm{tr}_{\mathcal{V}_i} q^{L_0 - \frac{c}{24}} = \sum_n d(n) q^{h_i + n - \frac{c}{24}},$$

d(n) counts the number of descendant states at level n in the irreducible Verma module and, n_{ij} are the multiplicities of each (h, \bar{h}) representation. In genera, we assume $n_{00} = 1$, as the identity must be present and non-degenerate. In

particular, in terms of the Virasoro characters, we define the S modular matrix to be defined by the S modular transformation on the Virasoro characters,

$$S: \chi_h(\tau) \mapsto \sum_j \mathcal{S}_{hj} \chi_j(\tau).$$

A fascinating result of the modular S matrix is that the modular S matrix diagonalizes the fusion rules. A result known as the Verlinde formula,

$$N_{ij}^{k} = \sum_{i} \frac{S_{il}S_{jl}S_{kl}^{*}}{S_{l0}},$$
(2)

Where N_{ij}^k are the coefficients of the fusion coefficients $\phi_i\phi_j = \sum N_{ij}^k\phi_k$ of the underlaying CFT. Indeed, if Equation (2) is satisfied, considering a vector v_a whose entries are given by $(v_a)_k = S_{ak}$, then

$$(N_i v_a)_j = \sum_k N_{ij}^k \mathcal{S}_{ka} = \frac{\mathcal{S}_{ia}}{\mathcal{S}_{0a}} \mathcal{S}_{ja} = \frac{\mathcal{S}_{ia}}{\mathcal{S}_{0a}} (v_a)_j.$$

We conclude v_a is an eigenvector with eigenvalue $n_{ia} = \frac{S_{ia}}{S_{0a}}$ and we define the **quantum dimension** of the TDL to be $d_a = n_{a0}$. In particular, note that

$$\chi_i(q) = \sum_j \left(\mathcal{S}^{-1} \right)_{ij} \chi_j(\tilde{q}) \xrightarrow{\tau \to i0^+} \left(\mathcal{S}^{-1} \right)_{i0} \chi_0(\tilde{q}) = d_i \chi_0(\tilde{q})$$

as the character is dominated by the vacuum.

B. Moore-Seiberg Construction

The modular bootstrap and the conformal bootstrap of four-point functions on the sphere are independent constraints on the spectrum of a CFT. The fact that one can obtain any closed orientable Riemann surfaces from different surgery procedures imposes consistency conditions on the fusion rules of 2d CFTs and, in fact, solving the conformal bootstrap for the four-point function on the sphere, as shown in Figure 2, and the one-point function on the torus,

$$\langle \mathcal{O} \rangle_{-1/\tau} = \tau^h \bar{\tau}^\hbar \langle \mathcal{O} \rangle_{\tau},$$

where the factor is a Weyl factor coming from the $w \to w'/\tau$ coordinate change, are sufficient to completely determine the CFT on arbitrary orientable Riemannian surfaces. We follow closely [2, 5] on this construction. Graphs are also retrieved from [2].

The construction goes as follows: A general genus g > 1 orientable Riemannian surface can be constructed by plumbing together 2g - 2 three-holed spheres. The plumbing construction glues together a pair of circular boundaries of three-holed spheres (or two-holed discs) by an PSL $(2, \mathbb{C})$ map. A typical plumbing map takes the form

$$z' = q/z, \quad q \in \mathbb{C}^{\times}$$

which identifies the boundary $|z| = r_1$ on one of the two-holed discs to the boundary $|z'| = r_2$ of the other two-holed disc, with $r_1r_2 = |q|$. There is one complex modulus q associated with each of the 3g-3 plumbing maps, giving rise to 3g-3 complex structure moduli of the Riemann surface.

The equivalence of different plumbing constructions of the same Riemann surface, and therefore of the consistency of the CFT on the surface, would be guaranteed provided that all sphere 4-point functions can be equivalently decomposed into two different channels, and that all torus 1-point functions constructed by plumbing together the inner and outer boundaries of a 1-punctured annulus are independent of the choice of how the torus is cut open into an annulus. The former is equivalent to the associativity of OPE, while the latter amounts to the modular covariance of the torus 1-point function of all primaries. Namely,

$$\langle \mathcal{O} \rangle_{-1/\tau} = \tau^h \bar{\tau}^\hbar \langle \mathcal{O} \rangle_\tau,$$

for every primary $\mathcal{O}_{h,\bar{h}}$.

Let us see how one can construct such correlation functions. From the fusion transformation of the four-point Virasoro block and the modular transformation of the torus one-point block, one can construct any fusion transformation

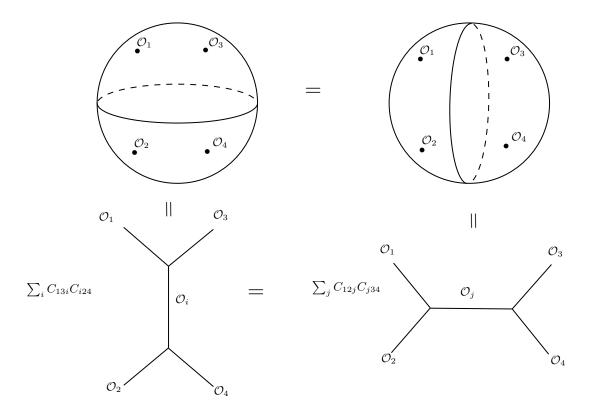


FIG. 2: Conformal bootstrap for the four-point function on the sphere

FIG. 3: Fusion of the torus.

$$\frac{j}{k} \times i = \int_{0}^{\infty} \frac{d\gamma_{q}}{2} \mathbf{F}_{\gamma_{p},\gamma_{q}} \begin{bmatrix} \gamma_{j} & \gamma_{i} \\ \gamma_{k} & \gamma_{l} \end{bmatrix} k \times q \times i$$

FIG. 4: Fusion on the sphere

(transformation between bases of functions for N-point functions on any Riemann surface). Indeed, from the fusion decompositions on the torus, as shown in Figure 3, and from the sphere fusion on the sphere, as shown in Figure 4 one can write the desired channel decomposition for any n-pt function.

For instance, consider the 2-pt function on the torus. Using the fusion transformations, one can write the channel decomposition, as shown in Figure 5. Similarly, the Virasoro block expansion can be performed for N-point functions on a Riemann surface of arbitrary genus using the plumbing construction.

$$i_{x} p = \int_{0}^{\infty} \frac{d\gamma_{q'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{q'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{q'}}{2} \int_{0}^{\infty} \frac{d\gamma_{p'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] \mathbf{F}_{\gamma_{p},\gamma_{p'}} \begin{bmatrix} \gamma_{j} & \gamma_{i} \\ \gamma_{q'} & \gamma_{q'} \end{bmatrix} j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{q'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] \mathbf{F}_{\gamma_{p},\gamma_{p'}} [\gamma_{p}] \mathbf{F}_{\gamma_{p},\gamma_{p'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{q'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] \mathbf{F}_{\gamma_{p},\gamma_{p'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{p'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] \mathbf{F}_{\gamma_{p},\gamma_{p'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{p'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] \mathbf{F}_{\gamma_{p},\gamma_{p'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{p'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] \mathbf{F}_{\gamma_{p},\gamma_{p'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{p'}}{2} S_{\gamma_{q},\gamma_{q'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac{d\gamma_{p'}}{2} S_{\gamma_{q'},\gamma_{q'}} [\gamma_{p}] j_{x} p = \int_{0}^{\infty} \frac$$

FIG. 5: 2-pt function channel transformation in the torus.

II. DEFECT LINES IN 2d CFTS

Consider two, a priori different, CFTs, say CFT_1 and CFT_2 . Now, one can locally describe the theory of CFT_1 while inserting a non-local operator that acts as the boundary of the CFT. In particular, one can consider the case where the two CFTs coexist, separated by a domain wall or boundary. For this theory to be consistent, we require the interface to fulfill certain relations. In particular, we require a non-local operator, called the interface or the domain wall, to glue the two CFTs according to

$$T_1(x) - \bar{T}_1(\bar{x}) = T_2(x) - \bar{T}_2(\bar{x}), \quad x \in \mathbb{R}.$$

The interface D is the operator $D: \mathcal{H}_1 \to \mathcal{H}_2$ mapping the Hilbert space of one theory to the other, while \bar{D} is the reverse map. The existence of the gluing in particular may allow energy to flow through the defect depending on how the gluing is done. For instance, if

$$T_1(x) - \bar{T}_1(\bar{x}) = 0$$

then no energy can be carried by the interface and thus energy cannot flow between the CFTs. Similarly, one can also require the defect D to commute with the Virasoro generators in which case the defect is free to move subject to topological deformations. In particular, this means that the gluing must satisfy

$$T_1(x) = T_2(x), \quad \bar{T}_1(\bar{x}) = \bar{T}_2(\bar{x}), \quad x \in \mathbb{R}.$$
 (3)

The fact that T generates diffeomorphisms implies that D is thus topological and the two CFTs must coincide, up to an isomorphism of algebras. Consider now a map $D: \mathcal{H}_1 \to \mathcal{H}_2$, where

$$\mathcal{H}_1 = \bigoplus_{h,\bar{h}} N_{h,\bar{h}}^{(1)} \mathcal{H}_h \otimes \mathcal{H}_{\bar{h}} \quad \text{and } \mathcal{H}_2 = \bigoplus_{h,\bar{h}} N_{h,\bar{h}}^{(2)} \mathcal{H}_h \otimes \mathcal{H}_{\bar{h}}$$

are the Hilbert space of the CFT_1 , having $N_{h,\bar{h}}^{(1)}$ copies of $\mathcal{V}_h \otimes \mathcal{V}_{\bar{h}}$ and similarly for the CFT_2 . Since both representations are irreducible, Equation (3) means that D must send a Verma module of the CFT_1 to the same Verma module, up to different copies, of the CFT_2 (otherwise the representations would be reducible), and so D and \bar{D} are the interwiners of the different copies of the Verma modules in the two CFTs. Therefore, the set of Topological Defect Lines (TDLs) is:

$$\left\{ D_A \left| D_A = \sum_{i,r} D_A^{(h,\bar{h};sr)} P_{h,\bar{h}}^{rs} \right. \right\}, \tag{4}$$

where $P_{h,\bar{h}}^{rs}: (\mathcal{H}_h \times \mathcal{H}_{\bar{h}})^s \to (\mathcal{H}_h \times \mathcal{H}_{\bar{h}})^s$ are the interwiners of $\mathcal{V}_h \otimes \mathcal{V}_{\bar{h}}$ mapping r copies of the Hilbert space to the s copies of \mathcal{H}_2 satisfying

$$L_n^{(1)}P_{h,\bar{h}}^{rs}=P_{h,\bar{h}}^{rs}L_n^{(2)}, \quad \bar{L}_n^{(1)}P_{h,\bar{h}}^{rs}=P_{h,\bar{h}}^{rs}\bar{L}_n^{(2)},$$

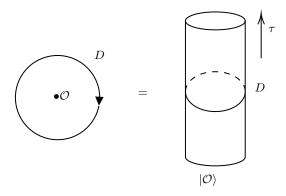


FIG. 6: Insertion of a space-like defect

and there are $\sum_{h,\bar{h}} N_{h,\bar{h}}^{(1)} N_{h,\bar{h}}^{(2)}$ choices of such A. Notice that in particular, the identity is a TDL. Few remarks are inorder.

1. Composition of two TDLs A and B, which we shall from now on call fusion, defines a new TDL $D_{A^{\dagger}B}: \mathcal{H}_1 \to \mathcal{H}_1$.

$$D_{A^{\dagger}D} = D_{A}^{\dagger}D_{B} = \sum_{h,\bar{h},r,r',s} \left(D_{A}^{(h,\bar{h};sr)}\right)^{*} \left(D_{B}^{(h,\bar{h};sr')}\right) P_{h,\bar{h}}^{rr'}$$

as † reverses the order.

2. Insertion of the defect on the partition function, as shown in Figure 6, gives

$$Z_A = \operatorname{tr}_{\mathcal{H}} D_A q^{L_0 - \frac{c}{24}} \bar{q}^{\bar{L}_0 - \frac{\bar{c}}{24}} = \sum_{h, \bar{h}, r, r', s} D_A^{(h, \bar{h}; sr)} \chi_h(q) \bar{\chi}_{\bar{h}}(\bar{q}).$$
 (5)

Thus, the action of the defect on fields is completely defined through it's action on the characters of the Verma modules. Due to modular invariance, it also implies the existence of topological defects along the "time" direction, see Figure 7, where we recognize as a twisted Hilbert space in the presence of a defect D. This Hilbert

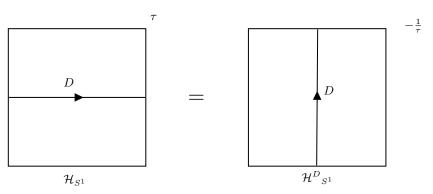


FIG. 7: Modularity of the defect insertion

space is denoted as $\mathcal{H}_{S^1}^D$ and is called the *D*-twisted sector.

3. In particular, insertion of these types of TDL amounts to

$$Z_D = \operatorname{tr}_{\mathcal{H}^D} q^{L_0 - \frac{c}{24}} \bar{q}^{\bar{L}_0 - \frac{\bar{c}}{24}} = \sum_{h,\bar{h}} n_D^{h,\bar{h}} \chi_h(\tau) \bar{\chi}_{\bar{h}}(\bar{\tau})$$

for some positive integers $n_D^{h\bar{h}}$ defining the twisiting

$$\mathcal{H}^D = \bigoplus_{h,\bar{h}} n_D^{h,\bar{h}} \mathcal{H}_h \otimes \mathcal{H}_{\bar{h}}.$$

We conclude by remarking that the introduction of TDL may generate local fields, corresponding to states in the twisted Hilbert space. These are called **defect fields** and are of four kinds, depending on how the defects can be attached:

- 1. Junction fields: Inserting at least three defects, junction fields map one defect into at least two others.
- 2. **Defect-changing fields**: Fields mapping a TDL A into another B.
- 3. Twist fields: They terminate a defect A, i.e. they are defect-changing fields from A into the identity TDL 1.
- 4. Bulk fields: Fields that are uncharged under the TDL, i.e. TDLs are invisible for the fields.

Example II.1. Consider TDLs in a diagonal theory i.e. $CFT_1 = CFT_2$ and $N_{h,\bar{h}} = \delta_{h,\bar{h}}$. Since the interwinners are just projections on the Verma modules, we consider the type of TDL defined by

$$D_a = \sum_h \frac{\mathcal{S}_{ah}}{\mathcal{S}_{0h}} P_h,$$

where $P_h = P_{h,\bar{h}}^{11}$ in our previous notation, and S is the modular matrix. These types of TDLs are called Verlinde lines, and they are described by the underlying OPE fusion. Indeed, using S, we compute:

$$D_a D_b = \sum_{ij} \frac{\mathcal{S}_{ai}}{\mathcal{S}_{0i}} \frac{\mathcal{S}_{bj}}{\mathcal{S}_{0j}} \delta_{ij} P_j = \sum_{ijc} \frac{\mathcal{S}_{ai} \mathcal{S}_{bi}}{\mathcal{S}_{0i}} \frac{\mathcal{S}_{ic}^* \mathcal{S}_{cj}}{\mathcal{S}_{0j}} P_j \tag{6}$$

$$= \sum_{cj} N_{ab}^c \frac{\mathcal{S}_{cj}}{\mathcal{S}_{0j}} P_j = \sum_c N_{ab}^c D_c.$$
 (7)

Notice that acting on primary states we have

$$D_a |\phi_i\rangle = D_a^i |\phi_i\rangle = \frac{S_{ai}}{S_{0i}} |\phi_i\rangle, \quad D_a |0\rangle = \frac{S_{a0}}{S_{00}} |0\rangle = d_a |0\rangle,$$

where we used the quantum dimension of Section IA. We conclude that the expectation value of the TDL is precisely the quantum dimension of the TDL,

$$\langle D^a \rangle = d_a$$
.

III. GENERALIZED GLOBAL SYMMETRIES IN d = 2 CFT AND THEIR BOOTSTRAP

In 2d CFTs, since the action of TDL on charged operators preserves (h, \bar{h}) (since the operator commutes with the stress-tensor), from our point of view, we consider symmetries as topological defect lines (TDL) and every time we identify a symmetry we should ask what is the underlying TDL. Thus, we change the perspective to consider axiomatic CFTs in the presence of topological defect lines and ask the question: which kind of TDLs we can consistently accommodate? For this, we consider a set of axioms described by a so-called "symmetry enriched CFT" which will allow us to bootstrap different TDLs and their underlying symmetries.

Example III.1. For instance, consider the Ising model. The symmetry allows to write the Ward identities

$$\langle \sigma \sigma \sigma \rangle = \langle \sigma \epsilon \epsilon \rangle = 0,$$

and more generally, any odd number of insertions of σ vanish. The underlying reason is that we can define an associated TDL η acting on the fields by

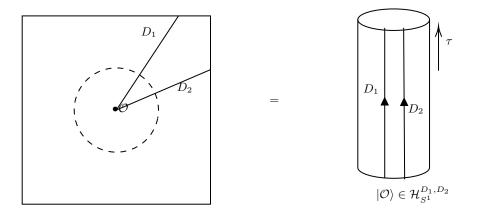


FIG. 8: Two defect insertions D_1 and D_2 . After a topological move we see it is irrelevant the order of D_1 and D_2 .

To define completely η we require, in addition, the action on the identity. This reduces simply to $1 \to \langle \eta \rangle 1$, so in order to generate the \mathbb{Z}_2 symmetry, η must have quantum dimension 1. On the other hand, the Ward identity

$$\langle \varepsilon \dots \varepsilon \rangle = 0$$

for odd number of insertions of ε , suggests there is an underlaying TDL guaranteeing that and, since $\langle \sigma \sigma \varepsilon \rangle \neq 0$, it cannot be a \mathbb{Z}_2 charge of ε . It turns out that this symmetry will be a non-invertible symmetry \mathcal{N} acting by

$$\varepsilon \to -\varepsilon \langle \mathcal{N} \rangle, \quad \sigma \to 0$$

allowing $\langle \sigma \sigma \varepsilon \rangle \neq 0$.

Naturally, not every TDL (symmetry) is allowed. We are going to see how the space of allowed TDLs is greatly constrained by the (defect) modular bootstrap. Before we present the relevant axioms for CFTs interplaying with TDLs, let us introduce the relevant terminology and rules of the game.

First, for every TDL D, which we assume to act faithfully on all local operators (i.e. only defect that acts trivially is the identity defect), we define the dual defect \bar{D} as the orientation-reversed defect.

$$\overline{D}$$
 D

and we say a defect is **simple** if dim $V_{D\bar{D}}=1$, where $V_{D\bar{D}}\subset\mathcal{H}$ is the Hilbert space of junctions between D and \bar{D} . This means there is only one junction v, which is the identity field, as shown in the Figure:

$$\begin{array}{c} D \\ \hline \end{array} = \begin{array}{c} \overline{D} \\ \hline \end{array} \begin{array}{c} D \\ \hline \end{array}$$

We define the multi-defect Hilbert space $\mathcal{H}_{S^1}^{D_1,D_2,...,D_j}$ as the Hilbert space describing the action of multi-defect insertions of simple topological defect lines, see Figure 8. For non-simple defect lines, we define the Hilbert space of the insertion as the direct sum of their underlying simple TDL Hilbert spaces. For instance, for $D=D_1+D_2$ we define

$$\mathcal{H}_{S^1}^{D_1+D_2} := \mathcal{H}_{S^1}^{D_1} \oplus \mathcal{H}_{S^1}^{D_2}.$$

It follows that if D is not simple, then $D = \sum_{i=1}^{n} D_i$ for D_i simple lines, and we have:

This is translated in terms of junctions as $dim(D\bar{D}) \geq 1$ as the first term admits a unique v = 1. Similarly, we define the topological junctions $v \in V_{D_1D_2D_3}$ as morphisms between D_1D_2 and \bar{D}_3 and, for higher junctions we write $V_{D_1...D_n} \subset \mathcal{H}$ as the space of n junctions. Finally, fusion of defects is defined as the fusion of simple defects. For the latter, we require the fusion rules:

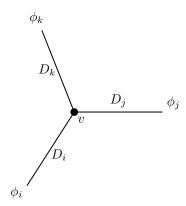
$$D_i D_j = \sum_k N_{ij}^k D_k,$$

where N are the fusion coefficients and fusion satisfies commutativity, associativity, and bilinearity. Associativity is motivated by the fact that insertion of two TDLs, under topological moves, relates $D_1D_2 = D_2D_1$ as shown in Figure 8.

Finally, it is easy to see that $N_{ij}^k = \dim V_{D_iD_j\bar{D}_k}$ and, in particular, note that the symmetries associated to TDLs will not be invertible as fusion, in general, gives a non-simple TDL. If the symmetry is invertible, then one can label defects by group elements g_i whose junctions are $\dim V_{g_1...g_n} = 1$ if $g_1g_2...g_n = 1$ and is otherwise zero.

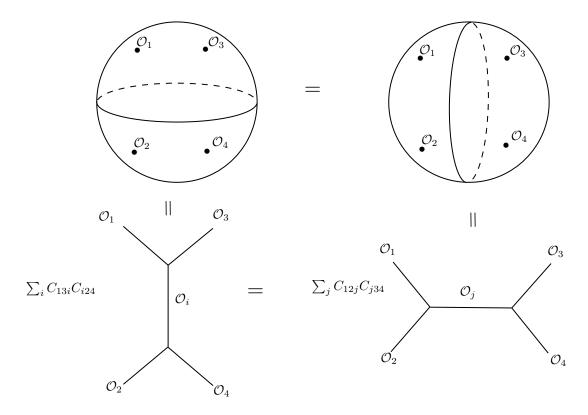
Having unpacked the definitions of lines and junctions, we define a **symmetry enriched CFT** as a CFT enriched by a collection of topological defect lines $\{D_i\}$ such that:

- 1. Data: The data are those of a CFT, i.e. a spectrum S of local fields enriched with the structure of TDLs. This constitutes:
 - (a) A collection of twisted Hilbert spaces $\mathcal{H}_{S^1}^{D_i...D_j}$ describing the action of multi-defect insertions on the fields of the CFT.
 - (b) The collection of three-point functions of operators attached to defects,



for v a topological junction i.e. an operator of dimension $h = \hbar = 0$ inside $\mathcal{H}_{S^1}^{D_1...D_n}$, $\{\phi_i\}$ local fields of the underlaying CFT and, $\{D_i\}$ TDLs.

- 2. Bootstrap conditions (locality): The axioms of locality and coherence are those of Moore and Seiberg compatible with the presence of TDLs,
 - (a) Sphere four-point crossing in the presence of topological defects,



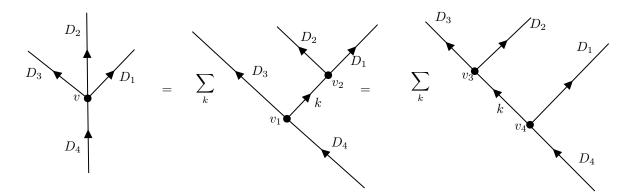
(b) Modular covariance of the torus one-point function with defects,

$$\langle \mathcal{O} \rangle_{\mathcal{H}^D, -1/\tau} = \tau^h \bar{\tau}^\hbar \langle \hat{D} \mathcal{O} \rangle_{\mathcal{H}, \tau},$$

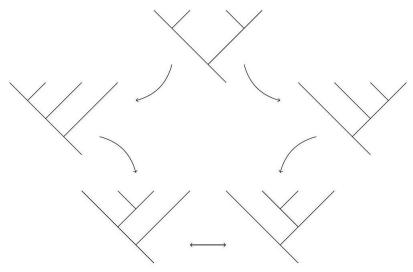
for every primary $\mathcal{O}_{h,\bar{h}}$ and D TDL.

Few remarks are in order:

- 1. Note that the data of a symmetry enriched CFT includes the usual \mathcal{H}_{S^1} and three point functions as we could set D=1.
- 2. In a general junction Hilbert space there is no canonical basis. Due to the fact that many bases of $V_{D_1D_2D_3\bar{D}_4}$ can be constructed from bases of three-fold junctions,

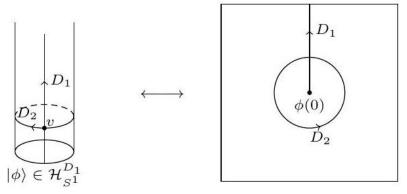


there exists a unitary change of basis $(F_4^{321})_{ab}$ mapping the basis $v_1 \otimes v_2$ to $v_3 \otimes v_4$. It can be shown that the fusion coefficients F have to obey an equation of the form $FF = \sum FFF$, obtained by performing the following fusion steps:

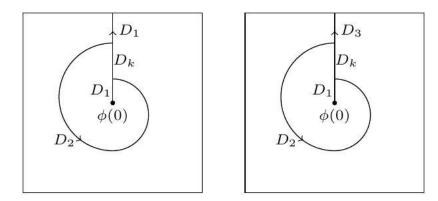


This is the "cocycle" condition which classifies anomalies from preventing the gauging of the underlaying symmetry [4].

3. In terms of our axioms, an action of a defect D_2 acting on the twisted Hilbert space $\mathcal{H}_{S^1}^{D_1}$,



is described by some topological junction $v \in V_{D_1D_2\bar{D}_1\bar{D}_2}$ which in turn can be described in terms of an intermediate insertion of a defect $D_k \in D_1D_2$. This is called the **Lasso action** and is pictured as



There are dim $V_{D_1D_2D_k}$ choices of v (or equivalently there are as many choices of D_k as resolutions of a junction with four vertex), hence $V_{D_1D_2\bar{D}_1\bar{D}_2}$ is typically of dimension larger than 1 (in contrast to invertible symmetries). This means that there are multiple possible actions of D_2 on $\mathcal{H}_{S^1}^{D_1}$ as shown in the left and right pictures above.

A. Defect Bootstrap

Similarly to the CFT in the torus, consistency of modularity in the presence of a defect insertion leads to the modular bootstrap on symmetry-enriched CFTs.

$$\operatorname{Tr}_{\mathcal{H}_{S^1}} \left(\widehat{D} q^{L_0 - c/24} \bar{q}^{\bar{L}_0 - c/24} \right) = \operatorname{Tr}_{\mathcal{H}_{S^1}^D} \left(\widetilde{q}^{L_0 - c/24} \bar{\tilde{q}}^{\bar{L}_0 - c/24} \right),$$
 (8)

where $\tilde{q} = e^{2\pi i(-1/\tau)}$. Moreover, because the TDLs commute with the Virasoro generators, they do not change the dimensions of states. Since we assumed a CFT with a unique vacuum, the action of the defect must simply rescale the vacuum by some number $\langle D \rangle = \langle 0|D|0 \rangle$ which we identify as the quantum dimension,

$$D|0\rangle = \langle D\rangle |0\rangle.$$

In particular, the quantum dimension is useful to determine the invertibility of the symmetry. If $\langle D \rangle = 1$ then D is invertible (as in that case $N = \delta_{DD'}$ for some D') as we saw in the Ising model of Example III.1 and, if $\langle D \rangle > 1$ then D is not invertible. Let us concretely show how the defect modular bootstrap allows us to bootstrap TDLs in the familiar Ising model.

1. Symmetry-enriched CFT: The Ising model revisited

Consider the Ising model i.e. a CFT with charge c=1/2 and spectrum $\{1, \varepsilon, \sigma\}$ of weights h=0,1/2,1/16 respectively. The Virasoro characters are computed to be

$$\chi_{1}(\tau) \ = \ \frac{1}{2\sqrt{\eta(\tau)}} [\sqrt{\theta_{3}(0|\tau)} + \sqrt{\theta_{4}(0|\tau)}], \quad \chi_{\varepsilon}(\tau) \ = \ \frac{1}{2\sqrt{\eta(\tau)}} [\sqrt{\theta_{3}(0|\tau)} - \sqrt{\theta_{4}(0|\tau)}], \quad \chi_{\sigma}(\tau) \ = \ \frac{1}{\sqrt{2\eta(\tau)}} \sqrt{\theta_{2}(0|\tau)}$$

for θ_n the modular theta functions and η the Dedekind eta function. These characters count the number of the descendants at each level. For instance, for the first 10 leveles, expanding the characters in powers of q they give

$$q^{\frac{1}{48}}\chi_1(\tau) = 1 + q^2 + q^3 + 2q^4 + 2q^5 + 3q^6 + 3q^7 + 5q^8 + 5q^9 + 7q^{10} + O\left(q^{481/48}\right)$$

$$q^{-\frac{23}{48}}\chi_{\epsilon}(\tau) = 1 + q + q^2 + q^3 + 2q^4 + 2q^5 + 3q^6 + 4q^7 + 5q^8 + 6q^9 + 8q^{10} + O\left(q^{481/48}\right)$$

$$q^{-\frac{1}{24}}\chi_{\sigma}(\tau) = 1 + q + q^2 + 2q^3 + 2q^4 + 3q^5 + 4q^6 + 5q^7 + 6q^8 + 8q^9 + 10q^{10} + O\left(q^{481/48}\right).$$

The partition function is thus given by

$$Z_{\text{Ising}} = |\chi_1(\tau)|^2 + |\chi_{\sigma}(\tau)|^2 + |\chi_{\varepsilon}(\tau)|^2.$$

For defect insertions we consider the action under TDL insertions,

$$Z^{Ising}[g_1, g_2](\tau, \bar{\tau}) = \operatorname{tr}_{\mathcal{H}_{S^1}^{g_1}} \left(g_2 q^{L_0 - \frac{1}{48}} \bar{q}^{\bar{L}_0 - \frac{1}{48}} \right)$$

for g_1 a TDL defect twisting the Hilbert space and g_2 for the TDL in the transverse direction. As we saw earlier on Equation (5), the action of a TDL is completely characterized by the action on the characters so it is enough to define it on each character. From now on, we consider the usual \mathbb{Z}_2 symmetry $\sigma \to -\sigma$ represented by the TLD η as seen by inserting the line along the time direction ($g_1 = 0, g_2 = 1$ where 1 represents an insertion and 0 otherwise). The fields 1 and ε are invariant (uncharged) so this leads to

$$Z^{\text{Ising}}[0,1](\tau,\bar{\tau}) = |\chi_1(\tau)|^2 + |\chi_{\sigma}(\tau)|^2 - |\chi_{\varepsilon}(\tau)|^2.$$

Similarly, with the help of the modularity

$$Z_{T^2}^{\text{Ising}}[D,0](\tau,\bar{\tau}) = Z_{T^2}^{\text{Ising}}[0,D](-1/\tau,-1/\bar{\tau}). \tag{9}$$

and, since the characters satisfy

$$\chi_1\left(-\frac{1}{\tau}\right) = \frac{1}{2\sqrt{\eta(\tau)}} \left[\sqrt{\theta_3(0|\tau)} + \sqrt{\theta_2(0|\tau)}\right]$$

$$\chi_{\varepsilon}\left(-\frac{1}{\tau}\right) = \frac{1}{2\sqrt{\eta(\tau)}} \left[\sqrt{\theta_3(0|\tau)} - \sqrt{\theta_2(0|\tau)}\right]$$

$$\chi_{\sigma}\left(-\frac{1}{\tau}\right) = \frac{1}{\sqrt{2\eta(\tau)}} \sqrt{\theta_4(0|\tau)}$$

we find

$$Z^{\text{Ising}}[1,0](\tau,\bar{\tau}) = |\chi_{\sigma}(\tau)|^2 + \chi_1(\tau)\chi_{\varepsilon}(\bar{\tau}) + \chi_1(\bar{\tau})\chi_{\varepsilon}(\tau)$$

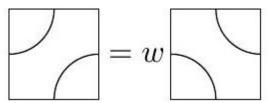
which gives the relation how the defect twisting acts on the characters. Moreover, the insertion of both types of defects can be found from the modular constraint

$$Z^{\text{Ising}}[1,1](\tau,\bar{\tau}) = \sum_{i,j \in \{0,\frac{1}{2},\frac{1}{16}\}} n_{ij}\chi_i(\tau)\chi_j(\bar{\tau}) = \sum_{i,j \in \{0,\frac{1}{2},\frac{1}{16}\}} n_{ij}\chi_i\left(-\frac{1}{\tau}\right)\chi_j\left(-\frac{1}{\bar{\tau}}\right)$$

for $n \in M_{3,3}(\mathbb{Z}_{\geq 0})$ which leads to the matrix

$$n = \begin{pmatrix} t+s & t & 0 \\ t & t+s & 0 \\ 0 & 0 & s \end{pmatrix} \implies n \in \operatorname{Span}_{\mathbb{Z}_{\geq 0}} \left\{ \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}.$$

Both solutions determine action of lines in the twisted sector. In particular, since there are no topological junctions (no defect transforming junctions), there are two resolutions of the lasso action of 4-junctions, simply related by a phase w,



Here, both solutions show $\omega=1$ as the matrices are symmetric. We recognize the second solution as $Z_{T^2}^{\text{Ising}}[0,0]$ giving the first solution to be

$$Z_{T^2}^{\text{Ising}}[1,1] = |\chi_1(\tau)|^2 + |\chi_{\epsilon}(\tau)|^2 + \chi_1(\tau)\chi_{\epsilon}(\bar{\tau}) + \chi_1(\bar{\tau})\chi_{\epsilon}(\tau).$$

Notice that we can also compute the matrix S. From

$$\begin{split} \chi_0\left(-\frac{1}{\tau}\right) &= \frac{1}{2}\left(\sqrt{\frac{\Theta_3(\tau)}{\eta(\tau)}} + \sqrt{\frac{\Theta_2(\tau)}{\eta(\tau)}}\right) \\ &= \frac{1}{2}\left(\sqrt{\frac{\Theta_2(\tau)}{\eta(\tau)}} + \frac{1}{2}\left(\sqrt{\frac{\Theta_3(\tau)}{\eta(\tau)}} + \sqrt{\frac{\Theta_4(\tau)}{\eta(\tau)}}\right) + \frac{1}{2}\left(\sqrt{\frac{\Theta_3(\tau)}{\eta(\tau)}} - \sqrt{\frac{\Theta_4(\tau)}{\eta(\tau)}}\right)\right) \\ &= \frac{1}{2}\left(\chi_0(\tau) + \chi_{\frac{1}{2}}(\tau) + \sqrt{2}\chi_{\frac{1}{16}}(\tau)\right) \\ \chi_{\frac{1}{2}}\left(-\frac{1}{\tau}\right) &= \frac{1}{2}\left(\chi_0(\tau) + \chi_{\frac{1}{2}}(\tau) - \sqrt{2}\chi_{\frac{1}{16}}(\tau)\right) \\ \chi_{\frac{1}{16}}\left(-\frac{1}{\tau}\right) &= \frac{1}{\sqrt{2}}\left(\chi_0(\tau) - \chi_{\frac{1}{2}}(\tau)\right) \end{split}$$

we deduce

$$S = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{\sqrt{2}} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \end{pmatrix}$$

from which we have

$$N_{ij}^{k} = \sum_{l=0}^{2} \frac{S_{jl}S_{il}(S^{-1})_{lk}}{S_{0l}}$$

giving

$$N_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad N_{\varepsilon} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad N_{\sigma} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$

which, using the fusion algebra $[\Phi_i] \times [\Phi_j] = \sum_k \mathcal{N}_{ij}^k [\Phi_k]$, leads to the fusion rules

$$\varepsilon \times \sigma = \sigma$$
, $\sigma \times \sigma = 1 + \varepsilon$, $\varepsilon \times \varepsilon = 1$

as expected.

2. Bootstrapping defect lines

Now, let us consider a general TDL D and let us define D by the action of the operators of the theory. For the Ising on the torus, we have

$$Z_{T^2}^{\text{Ising}}[0, D](\tau, \bar{\tau}) \equiv \operatorname{tr}_{\mathcal{H}_{S^1}}(Dq^{L_0 - \frac{1}{48}}q^{\bar{L}_0 - \frac{1}{48}}) = d_1|\chi_0(\tau)|^2 + d_{\epsilon}|\chi_{\frac{1}{5}}(\tau)|^2 + d_{\sigma}|\chi_{\frac{1}{16}}(\tau)|^2, \tag{10}$$

for d, the charges of the operators under the action of D. Thus, characterizing completely the line defect is done by specifying the coefficients $(d_1, d_{\varepsilon}, d_{\sigma})$. In general, modularity (c.f. Figure 7) constrains greatly the values of d as for the insertion of the defect, we must have

$$Z_{T^2}^{\text{Ising}}[D,0](\tau,\bar{\tau}) = Z_{T^2}^{\text{Ising}}[0,D](-1/\tau,-1/\bar{\tau}). \tag{11}$$

where the LHS is now a the insertion of the defect twisting the Hilbert space which can be written as

$$Z_{T^2}^{\text{Ising}}[D,0](\tau,\bar{\tau}) \equiv \operatorname{tr}_{\mathcal{H}_{S^1}^D}(q^{L_0 - \frac{1}{48}}q^{\bar{L}_0 - \frac{1}{48}}) = \sum_{i,j \in \{0,\frac{1}{2},\frac{1}{16}\}} n_{ij}\chi_i(\tau)\chi_j(\bar{\tau}).$$

Plugging Equation (10) in the modular Equation (11) yields the system of equations:

$$\begin{cases}
d_{\sigma} = s \\
d_{\varepsilon} = t - \sqrt{2}u, \quad s, t, u \in \mathbb{Z} \implies (d_{1}, d_{\sigma}, d_{\varepsilon}) \in \operatorname{Span}_{\mathbb{Z}}\{(1, 1, 1), (\sqrt{2}, -\sqrt{2}, 0), (1, 1, -1)\}.
\end{cases}$$

$$(12)$$

Note that here we have written in the basis where we recognize the first defect as the identity defect and the third as the η defect (whose quantum dimensions are 1). The remaining solution is the anticipated \mathcal{N} non-invertible symmetries, whose quantum dimension is $\sqrt{2}$ as we expected it to be greater to 1.

To see that this new bootstrapped defect \mathcal{N} is a non-invertible symmetry we compute the fusion rule for \mathcal{N}^2 . This can be found by squaring the eigenvalues d_i and reexpressing them in the basis of other solutions $\{d_i\}$, as shown by the Verlinde formula. The same can be done for all types of fusion and we find:

$$\mathcal{N}^2 = 1 + \eta, \quad \eta^2 = 1, \quad \mathcal{N}\eta = \eta \mathcal{N} = \mathcal{N}.$$

Notice, in particular, that these fusion composes a dimension 2 space, which means, as we saw earlier, they cannot be invertible. We can compute the Ising F-symbols by looking at the resolutions of 4-junctions with 3-junctions. Writing η as a dashed line and \mathcal{N} as a solid line, we find

Finally, the action on local operators are found to be

$$\begin{array}{cccc}
\bullet \epsilon & \mathcal{N} & = -\sqrt{2}\epsilon, & \bullet \epsilon & \eta & = 0, \\
\bullet \sigma & \mathcal{N} & = 0, & \bullet \sigma & \eta & = \sqrt{2}\mu \bullet - -, \\
\bullet \sigma & \bullet \sigma & \bullet \sigma & \bullet \sigma & = 0,
\end{array}$$

where $\sqrt{2}$ is the quantum dimension $\langle \mathcal{N} \rangle = \sqrt{2}$, and μ is a primary operator in the twisted sector:

$$\mathcal{H}_{S^1}^{\eta} = \left\{ \psi_{1/2,0}, \widetilde{\psi}_{0,1/2}, \mu_{1/16,1/16} \right\}.$$

Moreover, passing the non-invertible TDL through local operators gives

and $1 \to d_{\mathcal{N}} 1$, where $d_{\mathcal{N}}$ is the quantum dimension of the TDL \mathcal{N} .

IV. FINAL REMARKS

We have embarked on a study of the extension of two-dimensional conformal field theories (2D CFTs) in the presence of extended operators known as topological defect lines. In this context, the bootstrap has proven to be an extremely important tool, enabling us to constrain the possible symmetries of our theory. The introduction of extended operators, as viewed from the boundary perspective, can be interpreted as long-range interactions where projections, commonly referred to as topological defect lines (TDLs), can become dynamical. When we dynamically introduce these operators, i.e., we simply sum over all such symmetry generators, we gauge the symmetry. This process leads to intriguing concepts of discrete gauging and anomalies, which undoubtedly play a significant role in this picture.

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