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CONTEXT TrafficLightColors

EXTENDS

SETS

Light

CONSTANTS

red

green

AXIOMS

axm1: false(theorem) $Light = \{red, green\}$

axm2: false(theorem) $red \neq green$

END

CONTEXT PersonIO

Description of the person if physically in or out of the room

Description of the person if physically in or out of the room

EXTENDS**SETS**

PersonIOState

CONSTANTS

in

out

AXIOMS

axm1: false(theorem) $PersonIOState = \{out, in\}$

axm2: false(theorem) $out \neq in$

END

CONTEXT SensorIO

Context describing the sensor states

Context describing the sensor states

EXTENDS**SETS**

SensorState Set of sensor statesSet of sensor states

CONSTANTS

on Sensor signal onSensor signal on

off Sensor signal offSensor signal off

AXIOMSaxm1: false(theorem) $SensorState = \{off, on\}$ axm2: false(theorem) $off \neq on$ **END**

CONTEXT Room

Context describing the room states

Context describing the room states

EXTENDS**SETS**

RoomState

CONSTANTS

empty

full

AXIOMS**axm1:** false(theorem) $RoomState = \{empty, full\}$ **axm2:** false(theorem) $empty \neq full$ **END**

MACHINE m0

First implementation of the model. The entry and exit of a person is considered without any external restriction to the room capacity.

First implementation of the model. The entry and exit of a person is considered without any external restriction to the room capacity.

REFINES

Room

SEES Room**VARIABLES**

room

INVARIANTS*inv1*: false<theorem> *room* ∈ *RoomState***EVENTS****Initialisation** true<extended>false**thenbegin***act1*: true*room* := *emptyroom* := *empty***end****Event** Person.Go.In <ordinary> $\hat{=}$ false**extendsrefines**false**wherewhen***grd1*: false<theorem> true*room* = *emptyroom* = *empty*true**thenbegin***act1*: true*room* := *fullroom* := *full***end****Event** Person.Go.Out <ordinary> $\hat{=}$ false**extendsrefines**false**wherewhen***grd1*: false<theorem> true*room* = *fullroom* = *full*true**thenbegin***act1*: true*room* := *emptyroom* := *empty***end****END**

MACHINE m1

Second implementation of the model. The entry and exit of a person is restringed by a traffic light that denote if the room is empty or full.

Second implementation of the model. The entry and exit of a person is restringed by a traffic light that denote if the room is empty or full.

m0

REFINES m0

Room, TrafficLightColors

SEES Room, TrafficLightColors**VARIABLES**

room

tfl Traffic Light Variable Traffic Light Variable

INVARIANTS

inv1: false(theorem) tfl ∈ Light

EVENTS**Initialisation** true(extended)

false then begin

act1: false room := empty room := empty

act2: true tfl := red tfl := red

end

Event Person_Go_In ⟨ordinary⟩ ≐

Person_Go_In

true extends refines Person_Go_In

false where when

grd1: false(theorem) false room = empty room = empty

grd2: false(theorem) true tfl = green tfl = green

true then begin

act1: false room := full room := full

act2: true tfl := red tfl := red

end

Event Person_Go_Out ⟨ordinary⟩ ≐

Person_Go_Out

true extends refines Person_Go_Out

false where when

grd1: false(theorem) false room = full room = full

true then begin

act1: false room := empty room := empty

end

Event Traffic_Switch_Green ⟨ordinary⟩ ≐

This is for the signal to know the state of the environment (due to the absence of the output sensor).)

This is for the signal to know the state of the environment (due to the absence of the output sensor).)

false extends refines

false where when

grd1: false(theorem) true room = empty room = empty

grd2: false(theorem) true tfl = red tfl = red

true then begin

act1: true tfl := green tfl := green

end

END

MACHINE m2

m1

REFINES m1

Room, TrafficLightColors, SensorIO, PersonIO

SEES Room, TrafficLightColors, SensorIO, PersonIO**VARIABLES**

room
 tfl Traffic Light variable *Traffic Light variable*
 ss Sensor variable *Sensor variable*
 wio Wire from sensor to controller *Wire from sensor to controller*
 p Person In/Out variable *Person In/Out variable*

INVARIANTS

inv_room1: false⟨theorem⟩ $room = full \Rightarrow tfl = red$
inv_room2: false⟨theorem⟩ $room = full \Rightarrow p = in$
inv_ss1: false⟨theorem⟩ $ss \in SensorState$
inv_ss2: false⟨theorem⟩ $ss = on \Rightarrow wio = 0$
inv_ss3: false⟨theorem⟩ $ss = off \wedge wio = 0 \Rightarrow tfl = red$
inv_wio1: false⟨theorem⟩ $wio \in \{0, 1\}$
inv_wio2: false⟨theorem⟩ $wio = 1 \Rightarrow tfl = green$
inv_wio3: false⟨theorem⟩ $wio = 0 \Leftrightarrow (p = in \wedge room = full) \vee (p = out \wedge room = empty)$
inv_wio4: false⟨theorem⟩ $wio = 1 \Rightarrow p = in \wedge room = empty$
inv_p1: false⟨theorem⟩ $p \in PersonIOState$
inv_p2: false⟨theorem⟩ $p = out \Rightarrow room = empty$

EVENTS**Initialisation** true⟨extended⟩**false** **then** **begin**

act1: false $room := empty$ $room := empty$
act2: false $tfl := red$ $tfl := red$
act4: true $wio := 0$ $wio := 0$
act3: true $ss := off$ $ss := off$
act5: true $p := out$ $p := out$

end**Event** Person_Go_In ⟨ordinary⟩ $\hat{=}$

Event where the controller knows the signal from the cable (which assumes a person has entered) and then changes the state.

Event where the controller knows the signal from the cable (which assumes a person has entered) and then changes the state. Person_Go_In

false **extends** **refines** Person_Go_In**false** **where** **when**

grd1: false⟨theorem⟩ true $room = empty$ $room = empty$
grd2: false⟨theorem⟩ true $wio = 1$ $wio = 1$

true **then** **begin**

act1: true $room := full$ $room := full$
act2: true $wio := 0$ $wio := 0$
act3: true $tfl := red$ $tfl := red$

end**Event** Person_Go_Out ⟨ordinary⟩ $\hat{=}$

Exit event. As there is no exit sensor, we can assume that both states (To be inside and room is full) change simultaneously.

Exit event. As there is no exit sensor, we can assume that both states (To be inside and room is full) change simultaneously. Person_Go_Out

true **extends** **refines** Person_Go_Out**false** **where** **when**

grd1: false⟨theorem⟩ false $room = full$ $room = full$
grd2: false⟨theorem⟩ true $p = in$ $p = in$

true **then** **begin**

act1: false $room := empty$ $room := empty$


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    act2: truep := outp := out
end
Event Traffic_Switch_Green ⟨ordinary⟩ ≐
  Event where sensor is on and it is satisfied that entry can be allowed.
  Event where sensor is on and it is satisfied that entry can be allowed.
trueextendsrefines Traffic_Switch_Green
  falsewherewhen
    grd1: false⟨theorem⟩ falseroom = emptyroom = empty
    grd2: false⟨theorem⟩ falsefl = redfl = red
    grd3: false⟨theorem⟩ truess = onss = on
  truethenbegin
    act1: falsefl := greenfl := green
  end
Event Sensor_Turn_On ⟨ordinary⟩ ≐
  Event where sensor is on with no one is staging
  Event where sensor is on with no one is staging
falseextendsrefines
  falsewherewhen
    grd1: false⟨theorem⟩ truess = offss = off
    grd2: false⟨theorem⟩ truewio = 0wio = 0
  truethenbegin
    act1: truess := onss := on
  end
Event Person_Go_Out_Sensor ⟨ordinary⟩ ≐
  Event where situation satisfied that person who is waiting, can go inside.
  Event where situation satisfied that person who is waiting, can go inside.
falseextendsrefines
  falsewherewhen
    grd1: false⟨theorem⟩ truefl = greenfl = green
    grd2: false⟨theorem⟩ truess = onss = on
  truethenbegin
    act1: truep := inp := in
      Person physically go inside
      Person physically go inside
    act2: truess := offss := off
      sensor is turned off
      sensor is turned off
    act3: truewio := 1wio := 1
  end
end
END

```