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 \mathbf{END}

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CONTEXT PersonIO

Descripcion de la persona si está fisicamente dentro o fuera de la habitacion

SETS

PersonIOState

CONSTANTS

in

out

AXIOMS

```
axm1: PersonIOState = \{out, in\}
axm2: out \neq in
```

 \mathbf{END}

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CONTEXT SensorIO

Contexto donde se describe los estados del sensor

SETS

SensorState Conjunto de estados del sensor

CONSTANTS

on Señal del sensor on off Señal del sensor off

AXIOMS

 \mathbf{END}

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```
CONTEXT Room
SETS

RoomState

CONSTANTS

empty
full

AXIOMS

axm1: RoomState = {empty, full}

axm2: empty ≠ full

END
```

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MACHINE m0

Primera implementacion del modelo. Se considera la entrada y la salida de una persona sin ningún tipo de restricción externa al aforo de la habitación.

SEES Room

```
VARIABLES
```

room

INVARIANTS

```
inv1: room \in RoomState
```

EVENTS

```
Initialisation (extended)
     begin
           act1: roomempty
     end
Event Person_Go_In ⟨ordinary⟩
     when
           grd1: room = empty
     then
           act1: roomfull
     end
```

${\bf Event} \ {\bf Person_Go_Out} \ \langle {\bf ordinary} \rangle$

when grd1: room = fullthen ${\tt act1:}\ roomempty$ $\quad \textbf{end} \quad$

END

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```
MACHINE m1
\mathbf{REFINES} \ \mathrm{m0}
SEES Room, Traffic Light Colors
VARIABLES
       room
       tfl Traffic Light Variable
INVARIANTS
       \verb"inv1": tfl \in Light"
EVENTS
Initialisation (extended)
      begin
            act1: roomempty
            act2: tflred
      end
Event Person_Go_In ⟨ordinary⟩
extends Person_Go_In
      when
            grd1: room = empty
            {\tt grd2:} \quad tfl = green
      then
            act1: roomfull
            act2: \ tflred
      end
Event Person_Go_Out ⟨ordinary⟩
extends Person_Go_Out
      when
            grd1: room = full
      then
            act1: roomempty
      end
 {\bf Event} \  \, {\rm Traffic\_Switch\_Green} \  \, \langle {\rm ordinary} \rangle 
      Esto es para que la señal conozca el estado del environment (debido a la ausencia del sensor de salida)
      when
            grd1: room = empty
            grd2: tfl = red
      then
            act1: tflgreen
      end
END
```

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```
MACHINE m2
REFINES m1
SEES Room, Traffic Light Colors, Sensor IO, Person IO
VARIABLES
       room
       tfl Traffic Light variable
       ss Sensor variable
       wio Wire from sensor to controller
       p Person In/Out variable
INVARIANTS
       inv_room1: room = fulltfl = red
       inv\_room2: room = full p = in
       inv_ss1: ss \in SensorState
       inv_ss2: ss = onwio = 0
       inv_ss3: ss = off \land wio = 0tfl = red
       inv_wio1: wio \in \{0,1\}
       inv_wio2: wio = 1tfl = green
       inv_wio3: wio = 0 (p = in \land room = full) \lor (p = out \land room = empty)
       inv_wio4: wio = 1p = in \land room = empty
       inv_p1: p \in PersonIOState
       inv_p2: p = outroom = empty
EVENTS
Initialisation (extended)
     begin
           act1: roomempty
           act2: tflred
           act4: wio0
           act3: ssoff
            act5: pout
     end
Event Person_Go_In ⟨ordinary⟩
     Event where the controller knows the signal from the cable (which assumes a person has entered) and then
     changes the state.
refines Person_Go_In
     when
           grd1: room = empty
           grd2: wio = 1
     then
           act1: roomfull
           act2: wio0
            act3: tflred
     end
Event Person_Go_Out ⟨ordinary⟩
     Exit event. As there is no exit sensor, we can assume that both states (To be inside and room is full)
     change simultaneously.
extends Person_Go_Out
     when
            grd1: room = full
            grd2: p = in
     then
           act1: roomempty
            act2: pout
     end
Event Traffic_Switch_Green (ordinary)
```

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Event where sensor is on and it is satisfied that entry can be allowed.

```
extends Traffic_Switch_Green
      when
            grd1: room = empty
            grd2: tfl = red
            grd3: ss = on
      then
            act1: tflgreen
      end
Event Sensor_Turn_On \( \text{ordinary} \)
      Event where sensor is on with no one is staging
      when
            grd1: ss = off
            grd2: wio = 0
      then
            act1: sson
      end
Event Person_Go_Out_Sensor \( \text{ordinary} \)
      Event where situation satisfied that person who is waiting, can go inside.
      when
            grd1: tfl = green
            grd2: ss = on
      then
            act1: pin
               Person physically go inside
            act2: ssoff
               sensor is turned off
            act3: wio1
      \mathbf{end}
END
```

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