

Applied
Mathematics

Rafał
Staroszczyk

Philosophy
of Science

Mechanism of
Universe

Differential
models

Linear
Regression

Dynamical
Systems

Bibliography

Applied Mathematics

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① Philosophy of Science Mechanism of Universe

② Differential models

③ Linear Regression

④ Dynamical Systems

⑤ Bibliography

- Is universe deterministic or probabilistic?
- Can universe be described in mathematically "pretty" way?
- Can we find The Model?

Simulation Hypothesis

We can't look into the code of the universe. We need models.

Scientific method

Theory is the base of science. It requires falsifiable model described mathematically.

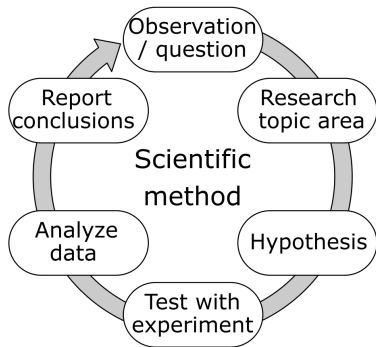


Figure: Source: [wikimedia.org](https://www.wikimedia.org/),
Author: Efbrasil

Important differential equations in physics

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Continuity $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = \sigma$

Diffusion $\frac{\partial \rho}{\partial t} = \nabla \cdot (D \nabla \rho)$

Harmonic oscillator $\frac{d^2 \phi}{dt^2} + \omega_0^2 \phi = 0$

Euler-Lagrange $\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} - \frac{\partial \mathcal{L}}{\partial q_i} = 0$

Laplace $\nabla^2 V = 0$

Poisson $\nabla^2 V = -\frac{\rho}{\epsilon_0}$

Helmholtz $(\nabla^2 + k^2) V = 0$

Wave $\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right) V = 0$

Gauss's Law in Linear Medium

$$\nabla \cdot \mathbf{E} = \frac{\rho_f}{\varepsilon_r \varepsilon_0}$$

$$\oint_S \mathbf{E} \cdot d\mathbf{S} = \frac{Q_f}{\varepsilon_r \varepsilon_0}$$

Capacitor equation

$$C = \frac{Q_f}{V} = \varepsilon_r \varepsilon_0 \frac{S}{d}$$

Model

$$y_i = ax_i + b + e_i \quad y_i = C_i \quad a = \varepsilon_r \varepsilon_0 S \quad x_i = \frac{1}{d_i} \quad b = C_0$$

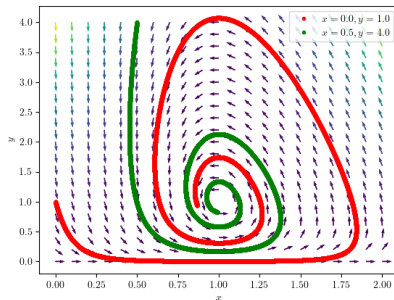
Least Squares Method

$$G(a, b) = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - ax_i - b)^2$$

$$\frac{\partial G(a, b)}{\partial a} = 0 \quad \frac{\partial G(a, b)}{\partial b} = 0$$

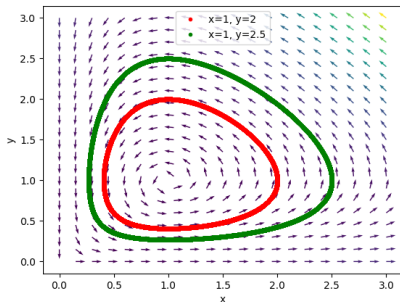
Equations

$$\frac{dx}{d\tau} = a - axy$$
$$\frac{dy}{d\tau} = xy - y$$

Figure: Lotka model : $a = 0.1$

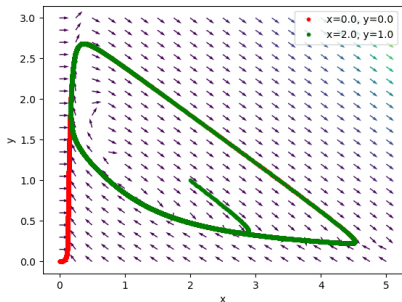
Equations

$$\frac{dx}{d\tau} = ax - axy$$
$$\frac{dy}{d\tau} = xy - y$$

Figure: Lotka-Volterra model : $a = 1$

Equations

$$\begin{aligned}\frac{dx}{d\tau} &= 1 + ax^2y - ax - x \\ \frac{dy}{d\tau} &= -bx^2y + bx\end{aligned}$$

Figure: Brusselator model : $a = 7$, $b = 4$

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