

Applied  
Mathematics

Rafał  
Staroszczyk

Philosophy  
of Science

Mechanism of  
Universe

Differential  
models

Linear  
Regression

Dynamical  
Systems

# Applied Mathematics

Rafał Staroszczyk

# 1 Philosophy of Science Mechanism of Universe

## 2 Differential models

## 3 Linear Regression

## 4 Dynamical Systems

- Is universe deterministic or probabilistic?
- Can universe be described in mathematically "pretty" way?
- Can we find The Model?

## Simulation Hypothesis

We can't look into the code of the universe. We need models.

## Scientific method

Theory is the base of science. It requires falsifiable model described mathematically.

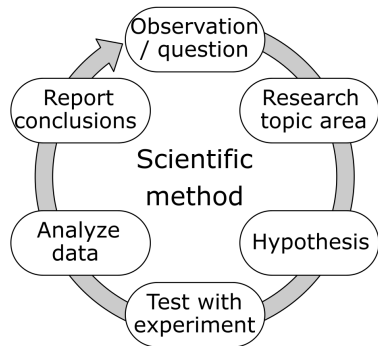


Figure: Source: [wikimedia.org](https://www.wikimedia.org/),  
Author: Efbrasil

# Important differential equations in physics

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Continuity  $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = \sigma$

Diffusion  $\frac{\partial \rho}{\partial t} = \nabla \cdot (D \nabla \rho)$

Harmonic oscillator  $\frac{d^2 \phi}{dt^2} + \omega_0^2 \phi = 0$

Euler-Lagrange  $\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} - \frac{\partial \mathcal{L}}{\partial q_i} = 0$

Laplace  $\nabla^2 V = 0$

Poisson  $\nabla^2 V = -\frac{\rho}{\epsilon_0}$

Helmholtz  $(\nabla^2 + k^2) V = 0$

Wave  $\left( \nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right) V = 0$

## Gauss's Law in Linear Medium

$$\nabla \cdot \mathbf{E} = \frac{\rho_f}{\epsilon_r \epsilon_0}$$

$$\oint_S \mathbf{E} \cdot d\mathbf{S} = \frac{Q_f}{\epsilon_r \epsilon_0}$$

## Capacitor equation

$$C = \frac{Q_f}{V} = \epsilon_r \epsilon_0 \frac{S}{d}$$

## Model

$$y_i = ax_i + b + e_i \quad y_i = C_i \quad a = \varepsilon_r \varepsilon_0 S \quad x_i = \frac{1}{d_i} \quad b = C_0$$

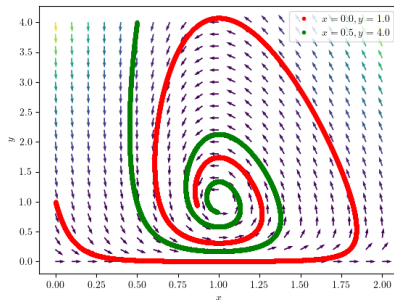
## Least Squares Method

$$G(a, b) = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - ax_i - b)^2$$

$$\frac{\partial G(a, b)}{\partial a} = 0 \quad \frac{\partial G(a, b)}{\partial b} = 0$$

## Equations

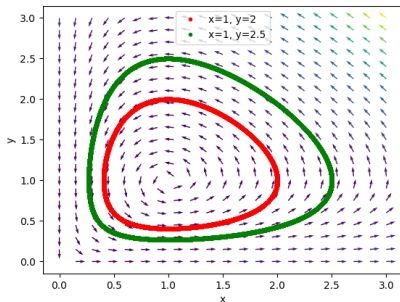
$$\begin{aligned}\frac{dx}{d\tau} &= a - axy \\ \frac{dy}{d\tau} &= xy - y\end{aligned}$$

Figure: Lotka model :  $a = 0.1$



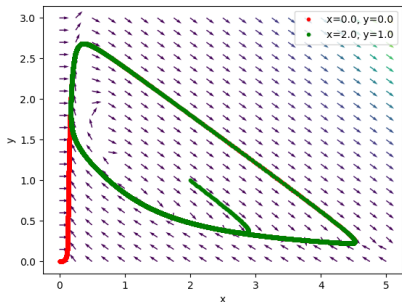
## Equations

$$\frac{dx}{d\tau} = ax - axy$$
$$\frac{dy}{d\tau} = xy - y$$

Figure: Lotka-Volterra model :  $a = 1$

## Equations

$$\begin{aligned}\frac{dx}{d\tau} &= 1 + ax^2y - ax - x \\ \frac{dy}{d\tau} &= -bx^2y + bx\end{aligned}$$

Figure: Brusselator model :  $a = 7$ ,  $b = 4$

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