

$\mathbb{R}^3 \rightarrow \mathcal{P}_2$:

$$T\left(\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}\right) = (9a_1 - 3a_2 + 5a_3)x^2 + (3a_1 + a_2 - 4a_3)x + 8a_1 - 4a_2$$

From the definition:

$$\begin{aligned} T(e_1) &= T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = (9 \cdot 1 - 3 \cdot 0 + 5 \cdot 0)x^2 + (3 \cdot 1 + 0 - 4 \cdot 0)x + (8 \cdot 1 - 4 \cdot 0) \\ &= 9x^2 + 3x + 8 \end{aligned}$$

Expressed in the basis $\{x^2, x, 1\}$, this is the coordinate vector:

$$[T(e_1)]_{B'} = \begin{pmatrix} 9 \\ 3 \\ 8 \end{pmatrix}$$

Similarly:

$$\begin{aligned} T(e_2) &= T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = (9 \cdot 0 - 3 \cdot 1 + 5 \cdot 0)x^2 + (3 \cdot 0 + 1 - 4 \cdot 0)x + (8 \cdot 0 - 4 \cdot 1) \\ &= -3x^2 + 1x - 4 \end{aligned}$$

So:

$$[T(e_2)]_{B'} = \begin{pmatrix} -3 \\ 1 \\ -4 \end{pmatrix}$$

Finally:

$$\begin{aligned} T(e_3) &= T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) = (9 \cdot 0 - 3 \cdot 0 + 5 \cdot 1)x^2 + (3 \cdot 0 + 0 - 4 \cdot 1)x + (8 \cdot 0 - 4 \cdot 0) \\ &= 5x^2 - 4x + 0 \end{aligned}$$

So:

$$[T(e_3)]_{B'} = \begin{pmatrix} 5 \\ -4 \\ 0 \end{pmatrix}$$

Answer:

$$T \text{ relative to } B, B' : A = \begin{pmatrix} 9 & -3 & 5 \\ 3 & 1 & -4 \\ 8 & -4 & 0 \end{pmatrix}$$