

## Lecture Notes for 3/11/2025

### 4.4 Basis and dimension

First, let us do a brief review.

Definition of a span and a spanning set: Let  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$  be  $k$  given vectors in  $\mathbb{R}^n$ . The span of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ ,  $\text{Span}(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ , is the set that contains all possible linear combination of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ .  $\text{Span}(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$  is a subspace of  $\mathbb{R}^n$  and  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$  is called a spanning set of this subspace.

$$a_1 \mathbf{v}_1 + a_2 \mathbf{v}_2 + \dots + a_k \mathbf{v}_k$$

Example 1. The span of  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  is what? What about the span of  $\mathbf{v}_1 = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ -4 \end{bmatrix}$ ?

$\text{span}\left\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right\}$  any vector in  $\mathbb{R}^2$  looks like

↑  
spanning set

$$\begin{bmatrix} x \\ y \end{bmatrix} = \underline{x} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \underline{y} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \in \text{span}\left\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right\}$$

$$\begin{bmatrix} x \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ y \end{bmatrix}$$

$$\text{span}\left\{\begin{bmatrix} 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -4 \end{bmatrix}\right\} = ? \mathbb{R}^2$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \frac{x}{3} \begin{bmatrix} 3 \\ 0 \end{bmatrix} + \frac{y}{-4} \begin{bmatrix} 0 \\ -4 \end{bmatrix}$$

Example 2. The span of  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} 2 \\ -2 \end{bmatrix}$  is the same as the span of  $\mathbf{v}_1$  since  $\mathbf{v}_2$  is a scalar multiple of  $\mathbf{v}_1$ . So  $\text{Span}(\mathbf{v}_1, \mathbf{v}_2) \neq \mathbb{R}^2$ . Why?

$$\text{span}\left\{\begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \end{bmatrix}\right\} \stackrel{?}{=} \mathbb{R}^2$$

$$\begin{bmatrix} 2 \\ -2 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$x \begin{bmatrix} 1 \\ -1 \end{bmatrix} + y \begin{bmatrix} 2 \\ -2 \end{bmatrix} = x \begin{bmatrix} 1 \\ -1 \end{bmatrix} + 2y \begin{bmatrix} 1 \\ -1 \end{bmatrix} = (x+2y) \begin{bmatrix} 1 \\ -1 \end{bmatrix} \in \text{span}\left\{\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right\}$$

Quiz Question 1. Which of the following statement is correct?

A. The span of  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  is  $\mathbb{R}^2$ ;  $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$

B. The span of  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  is  $\mathbb{R}^3$ ;

C. The span of  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  is  $\mathbb{R}^3$ ;

D. The span of  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  is not  $\mathbb{R}^3$ .

Definition of linear independence and dependence: The vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$  are (called) linearly independent if the equation

$$a_1 \mathbf{v}_1 + a_2 \mathbf{v}_2 + \dots + a_k \mathbf{v}_k = \mathbf{0}$$

has only the trivial solution  $a_1 = a_2 = \dots = a_k = 0$ . If on the other hand, this equation has non-trivial solutions, then  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$  are (said to be) linearly dependent.

Example 1. Determine whether

$$\mathbf{v}_1 = \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 5 \\ -2 \\ -1 \end{bmatrix}$$

are linearly ~~independent~~ *dependent*.  $\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$

$$a_1 \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + a_2 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + a_3 \begin{bmatrix} 5 \\ -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & 5 & 0 \\ -1 & -1 & -2 & 0 \\ 0 & 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \det = 2 + 0 - 5 - 0 - (-4) - 1 = -3 + 3 = 0$$

Example 2. Determine the values of  $c$  so that the vectors

$$\mathbf{v}_1 = \begin{bmatrix} c \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0 \\ 3 \\ 2 \end{bmatrix}$$

are linearly independent.

$$\Rightarrow \det \begin{bmatrix} c & 1 & 0 \\ 1 & -1 & 3 \\ 0 & 1 & 2 \end{bmatrix} \neq 0$$

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$$c \neq -\frac{2}{5}$$

$$-5c \neq 2$$

$$-2c + 0 + 0 - 0 - 3c - 2 = -5c - 2 \neq 0$$

Quiz Question 2. Determine the value of  $c$  so that the vectors

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}, \quad \begin{bmatrix} c \\ 5 \\ -2 \end{bmatrix}$$

are linearly DEPENDENT.

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$$\begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 4 \\ 7 \end{bmatrix}, \begin{bmatrix} -9 \\ 0 \\ 8 \end{bmatrix} \quad ?$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ for } \mathbb{R}^2 \rightarrow \begin{bmatrix} 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -4 \end{bmatrix}$$

$$\underline{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}} \text{ for } \mathbb{R}^3 \quad \underline{\begin{bmatrix} x \\ y \\ z \end{bmatrix} = x \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}$$

**Definition of a basis.** A spanning set of a vector space is called a basis of the vector space if it is linearly independent. Note a vector space can be a subspace in  $\mathbb{R}^n$ , not necessary the entire  $\mathbb{R}^n$ .

Example:  $\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n$  is a basis of  $\mathbb{R}^n$  (called the standard basis).

$$\text{span} \{ \mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k \}$$

The following theorem is quite important in the context of this section.

**Theorem.** If  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  and  $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_m$  are both bases of the same vector space  $V$ , then  $m = n$ .

Because of this theorem, we can define the dimension of a vector space  $V$  as the number of vectors in any of its bases.

It is also important to note the following theorem.

**Theorem.** If  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  is a basis of the vector space  $V$ , then any vector  $\mathbf{v} \in V$  can be written a linear combination of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  and this linear combination is unique. Say

$$\mathbf{v} = c_1 \underline{\mathbf{v}_1} + c_2 \underline{\mathbf{v}_2} + \dots + c_n \underline{\mathbf{v}_n}$$

We say that  $c_1, c_2, \dots, c_n$  are the coordinates of  $\mathbf{v}$  with respect to the basis  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ .

If our vector space is  $\mathbb{R}^n$  then obviously its dimension is  $n$  since we know its standard basis contains  $n$  vectors. But what if our vector space is a subspace of  $\mathbb{R}^n$  which is spanned by some vectors?

Answer: using Gaussian elimination method to find a basis within a known spanning set of the subspace.

Example. Find the dimension of the subspace  $W$  of  $\mathbb{R}^3$  that is the span of

$$\text{span}\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ -11 \end{bmatrix} \right\} = \text{span}\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 1 & 0 & 1 & 3 \\ 0 & 1 & 2 & -1 \\ -3 & 2 & 1 & -11 \end{bmatrix} \xrightarrow{3R_1 + R_3 \rightarrow R_3} \begin{bmatrix} 1 & 0 & 1 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 2 & 4 & -2 \end{bmatrix}$$

$$\xrightarrow{-2R_2 + R_3 \rightarrow R_3} \begin{bmatrix} 1 & 0 & 1 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

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Quiz Question 3. Find the dimension of the subspace in  $\mathbb{R}^4$  whose spanning set contains the following vectors:

$$\begin{bmatrix} 2 \\ 0 \\ 4 \\ 0 \end{bmatrix}, \quad \begin{bmatrix} -1 \\ 0 \\ -2 \\ 0 \end{bmatrix}, \quad \begin{bmatrix} -1 \\ 3 \\ 4 \\ -3 \end{bmatrix}, \quad \begin{bmatrix} 0 \\ 1 \\ 2 \\ -1 \end{bmatrix}.$$

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$$V = \text{span} \{ \underline{v_1, v_2, \dots, v_k} \}$$

$$A\vec{x} = \vec{b} \neq \vec{0}$$

**Theorem.** Let  $A$  be a matrix of size  $m \times n$ . The set of all solutions to a homogeneous linear equation system (written in matrix form)  $A\mathbf{x} = \mathbf{0}$  is a subspace of  $\mathbb{R}^n$ .

$$\begin{aligned} A\vec{x}_1 &= \vec{0} \\ A\vec{x}_2 &= \vec{0} \end{aligned}$$

$\vec{x}_1, \vec{x}_2$  solutions, is  $\vec{x}_1 + \vec{x}_2$  a solution?

$$A(\vec{x}_1 + \vec{x}_2) = \vec{0}?$$

$$A\vec{x}_1 + A\vec{x}_2 = \vec{0} + \vec{0} = \vec{0}$$

$$A(c\vec{x}_1) = c A\vec{x}_1 = c \cdot \vec{0} = \vec{0}$$

Why?

$$\begin{bmatrix} 1 & 2 & 0 & 1 \\ -1 & 0 & 4 & 1 \\ 1 & 3 & -5 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$3 \times 4$   
=

$$A\vec{x} = \vec{0}$$

Let  $W$  be the subspace given by the above theorem. How do we determine its dimension (or find a basis of it)?

Example.

$$\begin{bmatrix} | & | & | & | \end{bmatrix} \begin{matrix} \uparrow \\ \uparrow \end{matrix} \quad A \rightsquigarrow A = \begin{bmatrix} 1 & 2 & 0 & -3 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = -2x_2 + 3x_4$$

$$x_2 = 1 \cdot x_2 + 0 \cdot x_4$$

$$x_3 = 0 \cdot x_2 + 1 \cdot x_4$$

$$x_4 = 0 \cdot x_2 + 1 \cdot x_4$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 3 \\ 0 \\ 1 \\ 1 \end{bmatrix} = \text{span} \{ \vec{v}_1, \vec{v}_2 \}$$

$\vec{v}_1 \quad \vec{v}_2$



Quiz Question 4. Let  $W$  be the subspace of  $\mathbb{R}^7$  that consists of the solutions to the equation system  $A\mathbf{x} = \mathbf{0}$  where

$$A = \begin{bmatrix} 1 & 2 & 0 & -3 & 0 & 1 & 3 \\ 0 & 0 & 1 & -1 & 4 & 3 & 2 \\ 0 & 0 & 0 & 0 & 0 & 2 & 1 \end{bmatrix}$$

*span {*

Find the dimension of  $W$ .

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