# Module LinearAlgebra

```
Functions
 def add_object_align_init(context, operator)
 def createFaces(vertIdx1, vertIdx2, closed=False, flipped=False)
 def create_mesh_object(context, verts, edges, faces, name)
 def draw_parametric_surface(eq,
                              range_u_min,
                              range_u_max,
                              range_u_step,
                              range_v_min,
                              range_v_max,
                              range_v_step,
                              name,
                              wrap_u=False,
                              wrap_v=False,
                              close_v=False)
 def object_data_add(context, obdata, operator=None, name=None)
Classes
 class Color (r, g, b, name)
     Class that defines a color in RGB format
 class Colors
     Class that defines a list of colors by name
     Class variables
      var colorsbyname
         The type of the None singleton.
     Static methods
      def color(name)
         Function that returns a color from his name
         Parameters
         name: name of the color
```

def colors(names)

Return a list of colors fron their names

names: list of names

```
class EuclideanReference (o=Vector((0.0, 0.0, 0.0)), u1=Vector((1.0, 0.0, 0.0)), \\ u2=Vector((0.0, 1.0, 0.0)))
```

Class used to work with Eucliean References

Initializes the elements of the reference from the origin and two independent vectors

#### **Parameters**

o: origin of u1, u2: vectors

#### Methods

```
def base(self)
```

Returns the columns of the matrix

```
def coordinates(self, u=Vector((0.0, 0.0, 0.0)))
```

Returns the coordinates of a point (expressed in the canonical reference) in the actual reference

#### **Parameters**

u: coordinates of a point in the canonical reference

#### class LinearAlgebra

Class used to define all the functions in this module to work with graphics in Blender Initializes the values for scene, objects, meshes, collection, etc.

#### Methods

```
def add_ligth(self, location=[0, 0, 100], energy=3, direction=[0, 0, -1])
```

Adds a ligth to the scene

#### **Parameters**

location: location point of the light

energy: energy of the ligth

direction: direction of the light

```
def add_ligths(self, energy=1)
```

Adds diferent lights to the scene

#### **Parameters**

energy: energy of the lights

```
def add_material(self, obj, material_name, r, g, b, opacity=1.0)
```

```
obj: object
  material_name: material's name
  r, g, b: RGB color values
  opacity: the opacity
def animate_revolution_surface(self,
                                 fun=None,
                                 tmin=0.0,
                                 tmax=1.0,
                                 steps=256,
                                 curvethicknes=0.025,
                                 thickness=0.025,
                                 frames=3,
                                 angle=3,
                                 radians=False,
                                 axis='Z',
                                 origin=Vector((0.0, 0.0, 0.0)),
                                 line=0,
                                 canonica=0,
                                 symmetry=None,
                                 name='Revolution surface',
                                 color='AzureBlueDark',
                                 point=None)
```

Draws and animates a revolution surface from a curve

#### **Parameters**

```
fun: parametric equacion of the curve
  steps: number of steps to graw the curve
  curvethicknes: thickness of the curve
  frames: number of frames at each step of revolution
  angle: step angle of the revolution
  radians: if True, angle must be in radians
  axis: axis of revolution. It must be 'X', 'Y' or 'Z'
  origin: point of the axis of revolution
  symmetry: symmetry used to draw the curve
  name: name of the surface
  color: color of the surface
  point: if not None draw three points and a cercle. Must be a float between tmax and tmin
def base_adaptada(self,
                    origin=Vector((0.0, 0.0, 0.0)),
                    axis=Vector((1.0, 1.0, 1.0)),
                    length=15,
                    scale=0.04,
                    name='Base adaptada')
```

Draws an ortonormal base from vector axis with origin in the point origin and sets the default origin and default base to them

```
Parameters
   origin: origin of the vector and the base
   axis: first vector of the base
   length: length of the axis
   scale: scale of the base
   name: name of the base
def base_canonica(self,
                    origin=Vector((0.0, 0.0, 0.0)),
                    length=15,
                    scale=0.04,
                    zaxis=True,
                    name='Base canònica')
   Draws the canonical base
   Parameters
   origin: point where to represent the base
   length: length of the axis
   scale: scale of the cylinder
   zaxis: if False the z axis is not drawn
   name: name of the object
def base_canonica_white(self,
                           origin=Vector((0.0, 0.0, 0.0)),
                           length=20,
                           scale=0.04,
                           zaxis=True,
                           name='Base canònica')
   Draws the canonical base in white
   Parameters
   origin: point where to represent the base
   length: length of the axis
   scale: scale of the cylinder
   zaxis: if False the z axis is not drawn
   name: name of the object
def base_cilinder(self)
   Draws a base cilinder with radius 1 and depth 1
def base_cone(self)
   Draws a base cone with radius1=1.5, radius2=0, depth=2
def base_disk(self)
   Draws a base cone with radius1=1.5, radius2=0, depth=2
def base_is_canonica(self)
   Returns True if self.base is the canonical basis
```

Draws the base {u1,u2,u3} with origin in the point origin and sets the default origin and default base to them

#### **Parameters**

Draw the components of a vectors in the canonical base and in the base {u1,u2,u3}. Sets the default origin and default base to them

#### **Parameters**

Draw the coordinates of a point in the canonical reference and in the reference {o;u1,u2,u3}. Sets the default origin and default base to them

```
punt: point to draw
origin: origin of the reference
u1, u2, u3: vectors of the base
```

```
length: length of the axis
def cilindre(self,
              centre=Vector((0.0, 0.0, 0.0)),
              radi=1,
              height=5,
              eix='Z',
              color='AzureBlueDark',
              circlecolor='Blue')
  Draws a bounded cylinder with direction eix Parameters:
  centre: center of the cylinder
  radi: radius
  height: height
  eix: X, Y, Z or a vector
  color: color of the cylinder
  circlecolor: color of the two circles of a bounded cylinder
def cilindre_elliptic(self,
                         o=[0, 0, 0],
                         u1=[1, 0, 0],
                         u2=[0, 1, 0],
                         a2=1,
                         b2=1,
                         principal=True,
                         canonica=True,
                         color='AzureBlueDark',
                         name='EllipticCylinder',
                         zmax=20,
                         cmax=20,
                         pmax=15,
                         thickness=0.02,
                         opacity=1.0,
                         preserve=True)
  Draws an elliptic cylinder
  Parameters
  o: center of the elliptic cylinder
  u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  a2, b2: squares of semi-axes of the elliptic cylinder. The equation is x'^2/a^2 + y'^2/b^2 = 1
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the elliptic cylinder
  zmax: the elliptic cylinder is drawn between -zmax and zmax
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
```

thickness: thickness of the elliptic cylinder

opacity: opacity of the elliptic cylinder

canonica: if True, the coordinates of punt are in the canonical reference

```
preserve: Keep self.origin and self.base as the principal reference
def cilindre_elliptic_simple(self, a=10, b=6, direccio='Z', pmax=20)
  Draws an elliptic cylinder with direction X, Y or Z
  Parameters
  a, b: semiaxis of the ellipse
  direction: direction of translation of the ellipse
```

## pmax = height of the cylindrer def cilindre\_hiperbolic(self, o=[0, 0, 0],u1=[1, 0, 0], u2=[0, 1, 0], a2=1,b2=1,principal=True, canonica=True, color='AzureBlueDark', name='Hyperbolic Cylinder', xmax=None, zmax=15, cmax=15,

pmax=15,

thickness=0.02, opacity=1.0, preserve=True)

Draws an hyperbolic cylinder

```
Parameters
  o: center of the hyperbolic cylinder
  u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  a2, b2: squares of semi-axes of the hyperbolic cylinder. The equation is x'^2/a^2 - y'^2/b^2 = 1
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the hyperbolic cylinder
  xmax: maximum value of the x coordinate
  zmax: the hyperbolic cylinder is drawn between -zmax and zmax
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
  thickness: thickness of the hyperbolic cylinder
  opacity: opacity of the hyperbolic cylinder
  preserve: Keep self.origin and self.base as the principal reference
def cilindre_hiperbolic_simple(self, a=4, b=3, direccio='Z', pmax=15, hmax=20)
  Draws an hyperbolic cylinder with direction X, Y or Z
```

```
a, b: semiaxis of the hyperbole
  direccio: direction of translation of the hyperbole
  pmax = maximum value of the independent variable
  hmax = height of the cylindrer
def cilindre_parabolic(self,
                         o=[0, 0, 0],
                         u1=[1, 0, 0],
                         u2=[0, 1, 0],
                         p=1,
                         principal=True,
                         canonica=True,
                         color='AzureBlueDark',
                         name='ParabolicCylinder',
                         xmax=12,
                         ymax=30,
                         cmax=20,
                         pmax=20,
                         thickness=0.02,
                         opacity=1.0,
                         preserve=True)
  Draws an hyperbolic paraboloid
```

### **Parameters**

```
o: vertex of the hyperbolic paraboloid
  u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  p: Parameter of the cylinder z' = x'^2/(2*p)
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the elliptic paraboloid
  xmax: maximum value of the coordinate x
  ymax: maximum value of the coordinate y
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
  thickness: thickness of the hyperbolic paraboloid
  opacity: opacity of the hyperbolic paraboloid
  preserve: Keep self.origin and self.base as the principal reference
def cilindre_parabolic_simple(self, a=3, direccio='Z', pmax=12, hmax=45)
  Draws a parabolic cylinder with direction X, Y or Z
```

```
a: the initial parabola has equation of type z=\pm x^2/a^2 directio: direction of translation of the parabola pmax = maximum value of the independent variable
```

```
hmax = height of the cylindrer
```

Draws a circle of center 'center' and radius 'radius' in the plane determined by vectors u1 and u2

#### **Parameters**

```
center: center of the circle
u1, u2: vectors to construct the basis {v1, v2, v3}
axis: if True draws the axis of the reference R'
zaxis: if True draws the z' axis
radius: radius of the circle
steps: number of steps
thickness: thickness of the curve
name: name of the curve
color: color of the curve
change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}

def clear(self)
Clears and removes all the elements
```

```
def components_en_canonica(self, vector=None)
```

Returns the components of the vector 'point' in the base determined by self.rotation and the basis self.base

#### **Parameters**

vector: components of the vector in the base self.rotation + self.base

```
def components_in_base(self, vector=None, base=None)
```

Returns the components of the vector 'vector' in the basis determined by self.rotation and the basis self.base

#### **Parameters**

```
vector: components of the vector in the canonical basis
```

base: A base of V3. If None, we use self.base

```
b2=1,

c2=1,

half=False,

principal=True,

canonica=True,

color='AzureBlueDark',

name='Cone',

xmax=None,

cmax=15,

pmax=15,

thickness=0.02,

opacity=1.0,

preserve=True)
```

Draws a cone

#### **Parameters**

```
o: center of the cone
u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
a2, b2, c2: squares of semi-axes of the cone. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 0
half: if True draws half cone
principal: if True, the principal axis are drawn
canonica: if True, the canonical axis are drawn
color: color of the surface
name: name of the cone
xmax: maximum value of the x coordinate
cmax: the canonical axis are drawn between -cmax and cmax
pmax: the principal axis are drawn between -pmax and pmax
thickness: thickness of the cone
opacity: opacity of the cone
preserve: Keep self.origin and self.base as the principal reference

def con_cilindre_elliptic(self, a2=1, b2=1, c2=1, x0=5, a=8, b=5, zmax=15)
```

Draws a cone with vertex at (0,0,0) and equation  $x^2/a^2 + y^2/b^2 - z^2/c^2 == 0$ , an elliptic cylinder and their intersection

#### **Parameters**

```
a2, b2, c2: coefficients of the equation of the cone
x0: (x0,0,0) is the center of the ellipse in the plain XY
a, b: semiaxis of this ellipse
zmax: maximum value of the z coordinate

def con_revolucio(self, a=1.5, pmax=8, direccio='Z', punt=None)
```

Draws an animation showing a cone of revolution a: slope of the initial straight line

```
pmax: maximum value of the independent variable

direccio: 'X', the initial line is in the plane YX and rotates around the X axis
    'Y', the initial line is in the plane ZY and rotates around the Y axis
    'Z', the initial line is in the plane XZ and rotates around the Z axis

punt: if it's a value between -pmax and pmax, the animation shows a rotating point
```

```
def con_simple(self, a=4, b=3, c=2, direccio='Z', pmax=12)
  Draws a con with direction X, Y or Z
  Parameters
  a, b, c: semiaxis of the cone
  direccio: direction of the negative coefficient
  pmax = maximum value of the independent variables
  hmax = height of the cone
def cone(self,
         o=[0, 0, 0],
         u1=[1, 0, 0],
         u2=[0, 1, 0],
         a2=1,
         b2=1,
         c2=1,
         half=False,
         principal=True,
         canonica=True,
          color='AzureBlueDark',
         name='Cone',
         xmax=None,
         cmax=15,
          pmax=15,
          thickness=0.02,
         opacity=1.0,
         preserve=True)
  Draws a cone
  Parameters
  o: center of the cone
  u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  a2, b2, c2: squares of semi-axes of the cone. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 0
  half: if True draws half cone
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the cone
  xmax: maximum value of the x coordinate
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -pmax and pmax
  thickness: thickness of the cone
  opacity: opacity of the cone
```

def coordinates\_en\_canonica(self, point=None)

preserve: Keep self.origin and self.base as the principal reference

Returns the coordinates of the point 'point' in the reference determined by self.origin, self.rotation and the basis self.base

point: coordinates of the point in the reference {self.origin;self.base}

```
def coordinates_en_referencia(self, point=None)
```

Returns the coordinates of the point 'point' in the reference determined by self.origin, self.rotation and the basis self.base

#### **Parameters**

point: coordinates of the point in the canonical reference

Draws a curve in a reference R' determined by the origin o and basis {v1, v2, v3} constructed from u1 and u2 and the symmetric curve or curves from the parameter 'symmetry'

```
Parameters
   fun: the parametric function
   tmin: minimum value of the parameter
   tmax: maximum value of the parameter
   steps: number of steps
   thickness: thickness of the curve
   name: name of the curve
   color: color of the curve
   axis: if True draws the axis of the reference R'
   zaxis: if True draws the z' axis
   o: origin of the reference R'
   u1, u2: vectors to construct the basis {v1, v2, v3}
   symmetry: list of values in ('XY','XZ','YZ','X','Y','Z','O'). For every value S, draw the symmetric curve respect to S
   change: if True, set the reference self.origin, self.base to {o; v1, v2, v3}
def delete_base_cilinder(self)
   Removes the base cilinder
def delete_base_cone(self)
   Removes the base cone
def delete_base_disk(self)
```

steps=128,
thickness=0.01,

```
def distancia_rectes_encreuen(self,
                                  p0=Vector((3.0, 4.0, -2.0)),
                                  v0=Vector((1.0, 2.0, 3.0)),
                                  c0='Black',
                                  n0='Primera recta',
                                  p1=Vector((-3.0, 4.0, 1.0)),
                                  v1=Vector((1.0, -2.0, -1.0)),
                                  c1='Blue',
                                  n1='Segona recta',
                                  canonica=True,
                                  length=12,
                                  size=15,
                                  scale=0.03)
  Draws the distance between two affine lines
  Parameters
  p0: point of the first line
  v0: generator of the first line
  c0: color of the first line
  n0: name of the first line
  p1: point of the second line
  v1: generator of the second line
  c1: color of the second line
  n1: name of the second line
  canonica: if True, draws the x, y and z axis
  length: length of the axis x, y and z
  size: lenght of the lines
def draw_base_axis(self, scale=0.05, head_height=0.15, axis=0, name='Axis', positive=True, zaxis=True)
  Draws a reference axis given by self.origin, self.rotation and the basis self.base
  Parameters
  scale: scale of the cylinder
  head_height: height of the head of the vector from self.base
  axis: length of the coordinate axis. If the length is 0, only the basis vectors are drawn
  name: name of the result object
  positive: if True, draw the positive part of the axis
  zaxis: if True, draw the z axis
def draw_circle(self,
                 center=[0, 0, 0],
                 u1=Vector((1.0, 0.0, 0.0)),
                 u2=Vector((0.0, 1.0, 0.0)),
                 axis=False,
                 zaxis=False,
                 radius=1,
```

```
name='Circle',
color='White',
fillcolor=None,
change=False)
```

Draws a circle of center 'center' and radius 'radius' in the plane determined by vectors u1 and u2

#### **Parameters**

```
center: center of the circle

u1, u2: vectors to construct the basis {v1, v2, v3}

axis: if True draws the axis of the reference R'

zaxis: if True draws the z' axis

radius: radius of the circle

steps: number of steps

thickness: thickness of the curve

name: name of the curve

color: color of the curve

change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}

def draw_components(self, vector=None, color='Cyan', name='Components', scale=0.0075)
```

Draws the components of the the vector 'vector' in the reference given by self.origin, self.rotation and the basis self.base

#### **Parameters**

Draws a cone from the line z = a\*x in the XZ plane

```
a: slope of the line

xmin: minimum value of x

xmax: maximum value of x

steps: numbers of steps to draw the parabola

scale: scaling factors in the X, Y and Z directions
half: if True, draws half cone
```

```
color: color of the surface
   name: name of the surface
   opacity: opacity of the surface
   thickness: thickness of the surface
def draw_cube(self,
               origin=None,
               scale=[1, 1, 1],
               scalelines=0.05,
                vectors=False,
               color='Blue',
               linecolor='Red',
               vectorcolor='Black',
                name='Parallelepiped',
                opacity=1.0,
                thickness=0.0)
   Draws a rectangular parallelepiped
   Parameters
   origin: center of the parallelepiped
   scale: scale of the sides of the parallelepiped
   scalelines: scale of the edges of the parallelepiped
   vectors: if True, draws vectors from the origin to the vertices
   color: color of the parallelepiped
   linecolor: color of the edges
   vectorcolor: color of the vectors
   name: name of the parallelepiped
   opacity: opacity of the parallelepiped
   thickness: thickness of the parallelepiped
def draw_curve(self,
                 fun=None,
                 tmin=0.0,
                 tmax=1.0,
                 steps=25,
                 thickness=0.01,
                 name='Curve',
                 color='White',
                 axis=False,
                 zaxis=True,
                 o=Vector((0.0, 0.0, 0.0)),
                 u1=Vector((1.0, 0.0, 0.0)),
                 u2=Vector((0.0, 1.0, 0.0)))
   Draws a curve in a reference R' determined by the origin o and basis {v1, v2, v3} constructed from u1 and u2
   Parameters
   fun: the parametric function
   tmin: minimum value of the parameter
   tmax: maximum value of the parameter
```

steps: number of steps

Draws a disc in a reference R' determined by self.origin and self.base

#### **Parameters**

```
radius: radius of the disc
  thickness: thickness of the surface
  name: name of the curve
  color: color of the curve
def draw_ellipse(self,
                  center=[0, 0, 0],
                  u1=Vector((1.0, 0.0, 0.0)),
                  u2=Vector((0.0, 1.0, 0.0)),
                  a=1,
                  b=1,
                  axis=False,
                  zaxis=False,
                  steps=25,
                  thickness=0.01,
                  name='Ellipse',
                  color='White',
                  change=False)
```

Draws an ellipse of center 'center' and semi-axes a and b in the plane determined by vectors u1 and u2

```
center: center of the ellipse
u1, u2: vectors to construct the basis {v1, v2, v3}
a, b: semi-axes of the ellipse
axis: if True draws the axis of the reference R'
zaxis: if True draws the z' axis
steps: number of steps
thickness: thickness of the curve
name: name of the curve
```

```
color: color of the curve
```

change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}

Draws en ellipsoid

#### **Parameters**

```
radius: radius of the sphere
scale: scaling factors in the X, Y and Z directions
color: color of the surface
name: name of the surface
opacity: opacity of the surface
thickness: thickness of the surface
```

Draws an eliptic cylinder from the ellipse  $x = a\cos(t) y = b\sin(t)$  in the XY plane

xmax=3.0,

```
a, b: coefficients of the ellipsw
amin: minimum value of the angle t
amax: maximum value of the angle t
length: length in the Z direction
steps: numbers of steps to draw the parabola
scale: scaling factors in the X, Y and Z directions
color: color of the surface
name: name of the surface
opacity: opacity of the surface
thickness: thickness of the surface
def draw_elliptic_paraboloid(self,
a=0.5,
xmin=0.0,
```

```
steps=50,
scale=[1, 1, 1],
color='AzureBlueDark',
name='EllipticParaboloid',
opacity=1.0,
thickness=0.05)
```

Draws an elliptic paraboloid from the parabola z=a\*t^2

#### **Parameters**

```
a: coefficient of the parabola
  xmin: minimum value of x
  xmax: maximum value of x
  steps: numbers of steps to draw the parabola
  scale: scaling factors in the X, Y and Z directions
  color: color of the surface
  name: name of the surface
  opacity: opacity of the surface
  thickness: thickness of the surface
def draw_frenet_curve(self,
                        fun=None,
                        var=None,
                        tmin=0.0,
                        tmax=1.0,
                        radius=0.1,
                        steps=25,
                        thickness=0.01,
                        name='Curve',
                        color='White',
                        point=True,
                        tangent=False,
                        acceleration=False,
                        normal=False,
                        osculator=False,
                        frenet=False,
                        units=False,
                        sizex=8,
                        sizey=8,
                        axis=10)
```

Draws a curve and diferents elements related to the curve

### **Parameters**

fun: the parametric function

var = parameter variable of the function fun

tmin: minimum value of the parameter

tmax: maximum value of the parameter

radius: radius of the point

steps: number of steps

frames: increment of the frame set

```
name: name of the curve
  color: color of the curve
  point: if True draw a point along the curve
  tangent: if True draw the tangent vector along the curve
  acceleration: if True draw the acceleration vector along the curve
  normal: if True draw the normal vector along the curve
  osculator: if True draw the osculating plane along the curve
  frenet: if True draw the Frenet trihedron along the curve
  units: if True normalize the tangent and normal vectors
  sizex, sizey: sizes of the osculating plane
  axis: length of the coordinate axis
def draw_function(self,
                    f=None,
                    xmin=-3,
                    xmax=3,
                    xsteps=64,
                    ymin=-3,
                    ymax=3,
                    ysteps=64,
                    thickness=0.02,
                    opacity=1.0,
                    pmax=10,
                    name='Function',
                    color='AzureBlueDark',
                    axis=False,
                    o=Vector((0.0, 0.0, 0.0)),
                    u1=Vector((1.0, 0.0, 0.0)),
                    u2=Vector((0.0, 1.0, 0.0)))
  Draws a function of two variables f(x,y) i the reference R' = \{0, v1, v2, v3\}
  Parameters
  f: the function of two variables f(x,y)
  xmin: minimum value of x
  xmax: maximum value of x
  xsteps: steps in the x direction
  ymin: minimum value of y
  ymax: maximum value of y
  ysteps: steps in the x direction
  thickness: thickness of the surface
  opacity: opacity of the surface
  pmax: the axis are drawn between -pmax and pmax
  name: name of the surface
  color: color of the surface
  axis: if True the axis of the reference R' are drawn
  o: origin of the reference R'
```

thickness: thickness of the curve

```
u1, u2: vectors to construct the basis {v1, v2, v3}
```

Draws an hyperbole of center 'center' and semi-axes a and b in the plane determined by vectors u1 and u2

```
Parameters
  center: center of the hyperbole
  u1, u2: vectors to construct the basis {v1, v2, v3}
  a, b: semi-axes of the hyperbole
  ymax: maximum value of the y'
  axis: if True draws the axis of the reference R'
  zaxis: if True draws the z' axis
  steps: number of steps
  thickness: thickness of the curve
  name: name of the curve
  color: color of the curve
  change: if True, set the reference self.origin, self.base to {o; v1, v2, v3}
def draw_hyperbolic_cylinder(self,
                                 a=1.0,
                                 b=4.0,
                                 xmin=2.0,
                                 xmax=6.0,
                                 length=20,
                                 steps=50,
                                 scale=[1, 1, 1],
                                 color='AzureBlueDark',
                                 name='HyperbolicCylinder',
                                 opacity=1.0,
                                 thickness=0.05)
```

Draws an hyperbolic cylinder from the hyperbole y = a \* sqrt(x\*\*2 - b) in the XY plane

```
a, b: coefficients of the hyperbole xmin: minimum value of x xmax: maximum value of x length: length in the Z direction
```

```
steps: numbers of steps to draw the parabola
   scale: scaling factors in the X, Y and Z directions
   color: color of the surface
   name: name of the surface
   opacity: opacity of the surface
   thickness: thickness of the surface
def draw_hyperbolic_paraboloid(self,
                                   a=0.2,
                                   b=0.4,
                                   xmax=10.0,
                                   ymax=10.0,
                                   steps=64,
                                   scale=[1, 1, 1],
                                   color='AzureBlueDark',
                                   name='HyperbolicParaboloid',
                                   opacity=1.0,
                                   thickness=0.05)
   Draws an hyperbolic paraboloid with equation z = ax^2 - by^2
```

```
a, b: coefficients of the parabolic hyperboloid
  xmax: maximum value of x
  ymax: maxim value y
  steps: numbers of steps to draw the parabola
  scale: scaling factors in the X, Y and Z directions
  color: color of the surface
  name: name of the surface
  opacity: opacity of the surface
  thickness: thickness of the surface
def draw_line(self,
                start=[1, 1, 1],
                end=[10, 10, 10],
                scale=0.05,
                name='Line',
                color='Black',
                segment=False)
```

Draws a line from the point start to the point end. The reference given by self.origin, self.rotation and the basis self.base is used

#### **Parameters**

start: starting point of the line
end: ending point of the line
scale: scale of the cylinder
name: name of the object
color: color of the vector
segment: if True, draw points start and end

```
def draw_mesh(self, mesh=None, name='Mesh', color='Blue', opacity=1)
```

Draws a mesh. This function is used by other functions

```
Parameters
```

mesh: the mesh to be drawn

Draws a one sheet hyperboloid from the hyperbole  $z = pm a*sqrt(x^2-b)$  in the XZ plane

#### **Parameters**

a, b: coefficients of the hyperbole

```
xmin: minimum value of x
  xmax: maximum value of x
  steps: numbers of steps to draw the parabola
  scale: scaling factors in the X, Y and Z directions
  color: color of the surface
  name: name of the surface
  opacity: opacity of the surface
  thickness: thickness of the surface
def draw_parabola(self,
                   vertex=[0, 0, 0],
                   u1=Vector((1.0, 0.0, 0.0)),
                    u2=Vector((0.0, 1.0, 0.0)),
                    a=1,
                    xmax=3.0,
                    axis=False,
                    zaxis=False,
                    steps=25,
                    thickness=0.01,
                    name='Parabola',
                    color='White',
                    change=False)
```

Draws a parabola of vertex 'vertex' of equation y'=ax'^2 in the reference {vertex; v1, v2, v3} determined by vectors u1 and u2

```
vertex: vertex of the parabola
  u1, u2: vectors to construct the basis {v1, v2, v3}
  a: coefficient of the parabola
  xmax: maximum value of x'
  axis: if True draws the axis of the reference R'
  zaxis: if True draws the z' axis
  steps: number of steps
  thickness: thickness of the curve
  name: name of the curve
  color: color of the curve
  change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}
def draw_parabolic_cylinder(self,
                                p=0.25,
                                xmin=0.0,
                                xmax=6.0,
                                length=20,
                                steps=50,
                                scale=[1, 1, 1],
                                color='AzureBlueDark',
                                name='ParabolicCylinder',
                                opacity=1.0,
                                thickness=0.05)
  Draws a parabolic cylinder from the parabola z=p*x^2 in the XZ plane
  Parameters
  p: coefficient of the parabola
  xmin: minimum value of x
  xmax: maximum value of x
  length: length in the Y direction
  steps: numbers of steps to draw the parabola
  scale: scaling factors in the X, Y and Z directions
  color: color of the surface
  name: name of the surface
  opacity: opacity of the surface
  thickness: thickness of the surface
def draw_parallelepiped(self,
                           origin=[0, 0, 0],
                           u1=[1, 0, 0],
                           u2=[0, 1, 0],
                           u3=[0, 0, 1],
                           scalelines=0.025,
                           color='AzureBlueDark',
                           linecolor='OrangeObscureDull',
                           name='Parallelepiped',
                           opacity=1.0,
                           thickness=0.0)
```

## **Parameters** origin: base vertex of the parallelepiped u1, u2, u3: vectors that gives the edges scalelines: scale of the edges of the parallelepiped color: color of the parallelepiped linecolor: color of the edges name: name of the parallelepiped opacity: opacity of the parallelepiped thickness: thickness of the parallelepiped def draw\_parallelogram(self, origin=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], scalelines=0.025, color='AzureBlueDark', linecolor='OrangeObscureDull', name='Parallelogram', opacity=1.0, thickness=0.0)

Draws a parallelogram

```
Parameters
  origin: base vertex of the parallelogram
  u1, u2: vectors that gives the edges
  scalelines: scale of the edges of the parallelogram
  color: color of the parallelogram
  linecolor: color of the edges
  name: name of the parallelogram
  opacity: opacity of the parallelogram
  thickness: thickness of the parallelogram
def draw_plane(self,
                normal=None,
                base=None,
                 sizex=10,
                 sizey=10,
                 color='AzureBlueDark',
                 name='Plane',
                 opacity=1.0,
                 thickness=0.01)
```

Draws a plane with normal vector or base vectors. It passes through the point self.origin. Only normal or base can be not None

#### **Parameters**

normal: normal vector to the plane base: list of two independent vectors

sizex: x-size of the plane

```
sizey: y-size of the plane
  color: color of the plane
  name: name of the plane
  opacity: opacity of the plane
  thickness: thickness of the plane
def draw_plane_surface(self,
                         origin=None,
                         normal=None,
                         base=None,
                         sizex=10,
                         sizey=10,
                         vectors=False,
                         scalelines=0.05,
                         scalevector=0.03,
                         color='AzureBlueDark',
                         linecolor='BlueDarkDull',
                         vectorcolor='Black',
                         name='Plane',
                         opacity=1.0,
                         thickness=0.01)
  Draws a plane with normal vector or base vectors. It passes through the point origin. Only normal or base can be not None
```

```
origin: a point in the plane
  normal: normal vector to the plane
  base: list of two independent vectors
  sizex: x-size of the plane
  sizey: y-size of the plane
  vectors: if True, draw the generators of the plane
  scalelines: scale of the lines limiting the plane
  scalevector: scale of the generators
  color: color of the plane
  linecolor: color of the lines limiting the plane
  vectorcolor: color of the generators
  name: name of the plane
  opacity: opacity of the plane
  thickness: thickness of the plane
def draw_point(self, radius=0.1, location=(0, 0, 0), name='Point', color='Black', opacity=1.0)
  Draws a point (in the reference self.origin, self.base)
```

#### **Parameters**

radius: radius of the point location: location of the point name: name of the point color: color of the point

```
opacity: opacity of the point
def draw_points(self, points=[], name='Points', color='Blue', opacity=1)
  Draws a list of points
  Parameters
  points: list of points
  name: name of the list of points
  color: color of the points
  opacity: opacity of the points
def draw_polygon(self,
                  origin=[0, 0, 0],
                  u1=[1, 0, 0],
                  u2=[0, 1, 0],
                  points=[[0, 0], [1, 0], [0, 1]],
                   scalelines=0.075,
                   color='AzureBlueMedium',
                   linecolor='AzureBlueDark',
                  name='Polygon',
                  opacity=1.0,
                   thickness=0.0,
                   vectors=None,
                   scalevectors=0.01)
  Draws a polygon
  Parameters
  origin: base vertex of the polygon
  u1, u2: base vectors for the polygon
  points: list of coordinates of points. The coordinates are taken in the reference {origin; u1, u2}
  scalelines: scale of the edges of the polygon
  color: color of the polygon
  linecolor: color of the edges
  name: name of the polygon
  opacity: opacity of the polygon
  thickness: thickness of the polygon
def draw_pyramid(self,
                  origin=[0, 0, 0],
                  u1=[1, 0, 0],
                  u2=[0, 1, 0],
                  u3=[0.5, 0.5, 1],
                   scalelines=0.025,
                  color='AzureBlueDark',
                   linecolor='OrangeObscureDull',
                  name='Pyramid',
                   opacity=1.0,
                   thickness=0.0)
```

Draws a pyramid

```
origin: base vertex of the pyramid
  u1, u2, u3: vectors that gives the edges
  scalelines: scale of the edges of the pyramid
  color: color of the pyramid
  linecolor: color of the edges
  name: name of the pyramid
  opacity: opacity of the pyramid
  thickness: thickness of the pyramid
def draw_regular_polygon(self,
                           origin=[0, 0, 0],
                           u1=[1, 0, 0],
                            u2=[0, 1, 0],
                            vertexs=5,
                            radius=1,
                            scalelines=0.075,
                            color='AzureBlueDark',
                            linecolor='OrangeObscureDull',
                            name='RegularPolygon',
                            opacity=1.0,
                            thickness=0.0,
                            vectors=None)
  Draws a regular polygon
  Parameters
  origin: base vertex of the polygon
  u1, u2: base vectors for the polygon
  vertexs: number of vertices of the polygon
  radius: radius of the polygon
  scalelines: scale of the edges of the polygon
  color: color of the polygon
  linecolor: color of the edges
  name: name of the polygon
  opacity: opacity of the polygon
  thickness: thickness of the polygon
def draw_simple_curve(self, fun=None, tmin=0.0, tmax=1.0, steps=25, thickness=0.02, color='White',
                        name='Curve')
  Draws a parametric curve
  Parameters
  fun: the parametric function
  tmin: minimum value of the parameter
  tmax: maximum value of the parameter
```

steps: number of steps

thickness: thickness of the curve

```
name: name of the curve
def draw_surface(self,
                 eq=None,
                 umin=-1,
                 umax=1,
                 usteps=64,
                 vmin=-1,
                 vmax=1,
                 vsteps=64,
                 thickness=0.02,
                 opacity=1.0,
                 pmax=10,
                 name='Surface',
                 color='AzureBlueDark',
                 axis=False,
                 o=Vector((0.0, 0.0, 0.0)),
                 u1=Vector((1.0, 0.0, 0.0)),
                 u2=Vector((0.0, 1.0, 0.0)),
                 wrap_u=False,
                 wrap_v=False,
                 close_v=False)
```

color: color of the curve

Draws a parametric surface in the reference R'

```
Parameters
  eq: parametric equacion f(u,v)
  umin: minimum value of u
  umax: maximum value of u
  usteps: steps in the u direction
  vmin: minimum value of v
  vmax: maximum value of v
  vsteps: steps in the v direction
  thickness: thickness of the surface
  opacity: opacity of the surface
  color: color of the surface
  pmax: the principal axis are drawn between -cmax and cmax
  name: name of the surface
  color: color of the surface
  axis: if True draw the axis of the reference {o, v1, v2, v3}
  o: origin of the reference R'
  u1, u2: vectors to construct the basis {v1, v2, v3}
  scale: scale coefficients
  wrap_u: wrap the u coordinate
  wrap_v: wrap the u coordinate
  close_v: close the v coordinate
def draw_tetrahedron(self,
                        origin=[0, 0, 0],
```

```
u1=[2, 0, 0],
u2=[1.000000000000000002, 1.7320508075688772, 0],
u3=[1.0, 0.5773502691896257, 2],
scalelines=0.025,
color='AzureBlueDark',
linecolor='OrangeObscureDull',
name='Tetrahedron',
opacity=1.0,
thickness=0.0)
```

Draws a tetrahedron

#### **Parameters**

```
origin: base vertex of the tetrahedron
  u1, u2, u3: vectors that gives the edges
  scalelines: scale of the edges of the tetrahedron
  color: color of the tetrahedron
  linecolor: color of the edges
  name: name of the tetrahedron
  opacity: opacity of the tetrahedron
  thickness: thickness of the tetrahedron
def draw_triangle(self,
                    origin=[0, 0, 0],
                    u1=[1, 0, 0],
                    u2=[0, 1, 0],
                    points=[[0, 0], [1, 0], [0, 1]],
                    scalelines=0.075,
                    color='AzureBlueMedium',
                    linecolor='OrangeObscureDull',
```

Draws a triangle. It's a polygon with three vertices

name='Triangle',
opacity=1.0,
thickness=0.01)

```
Parameters

origin: base vertex of the triangle

u1, u2: base vectors for the triangle

points: list of coordinates of points. The coordinates are taken in the reference {origin; u1, u2} scalelines: scale of the edges of the triangle

color: color of the triangle

linecolor: color of the edges

name: name of the triangle

opacity: opacity of the triangle

thickness: thickness of the triangle

def draw_two_sheets_hyperboloid(self,

a=2.0,

b=1.0,

xmin=0.0,
```

xmax=5.0,

```
steps=50,
scale=[1, 1, 1],
color='AzureBlueDark',
name='HyperboloidTwoSheets',
opacity=1.0,
thickness=0.05)
```

Draws a two sheet hyperboloid from the hyperbole z = pm a \* math.sqrt(x\*\*2+b) in the XZ plane

#### **Parameters**

a, b: coefficients of the hyperbole

xmin=-3, xmax=3,

```
xmin: minimum value of x
  xmax: maximum value of x
  steps: numbers of steps to draw the parabola
  scale: scaling factors in the X, Y and Z directions
  color: color of the surface
  name: name of the surface
  opacity: opacity of the surface
  thickness: thickness of the surface
def draw_vector(self,
                  origin=Vector((0.0, 0.0, 0.0)),
                  vector=None,
                  canonica=False,
                  color='Black',
                  scale=0.05,
                  arrow=True,
                  head_height=None,
                  axis=0,
                  name='Vector',
                  positive=True)
  Draw the vector with components 'vector' trough 'origin'
  Parameters
  origin: point of the line
  vector: components of the vector
  canonica: if True, the components are in the canonical basis, else they are in the basis self.base. Finally, self.rotation is
  applied
  color: color of the vector
  scale: scale of the cylinder
  arrow: if True draws the vector itself
  head_height: height of the head of the vector
  head_scale: scale of the head of the vector
  axis: if not zero, draw also the line generated by the vector
  positive: if axis is not zero and positive is True, draw only the positive part of the line generated by the vector
def draw_vector_field(self,
                         f=None,
```

```
xsteps=8,
ymin=-3,
ymax=3,
ysteps=8,
zmin=-3,
zmax=3,
zsteps=8,
name='Vector Field',
color='Red',
scale=0.02,
head_height=0.05)
```

Draws a vector field

#### **Parameters**

```
f: the vector field
  xmin: minimum value of x
  xmax: maximum value of x
  xsteps: steps in the x direction
  ymin: minimum value of y
  ymax: maximum value of y
  ysteps: steps in the y direction
  zmin: minimum value of z
  zmax: maximum value of z
  zsteps: steps in the z direction
  name: name of the vector field
  color: color of the vector field
  scale: scale of the vectors
  head_height: head height of the vectors
def draw_vectors(self,
                   vectors=[],
                   canonica=False,
                   color='Black',
                   scale=0.05,
                   head_height=0.2,
                   name='Vectors',
                   axis=0)
```

Draws a list of vectors.

```
vectors: list of vectors
canonica: if True, the the vectors are expressed in the canonical basis.
color: color of the vectors
scale: scale of the cylinder
head_height: height of the head of the vector
axis: if not zero, draw also the line generated by every vector

def ellipse(self, center=Vector((0.0, 0.0, 0.0)), a=8, b=5, canonica=True)
```

c2=1,

principal=True,
canonica=True,

color='AzureBlueDark',
name='Ellipsoid',

```
Parameters
  centre: center of the ellipse
  a, b: semiaxis of the ellipse
  canonica: if True, draws the x and y axis
def ellipsoid(self,
                o=[0, 0, 0],
                u1=[1, 0, 0],
                u2=[0, 1, 0],
                a2=1,
                b2=1,
                c2=1,
                principal=True,
                canonica=True,
                color='AzureBlueDark',
                name='Ellipsoid',
                cmax=15,
                pmax=15,
                thickness=0.02,
                opacity=1.0,
                preserve=True)
  Draws an ellipsoid
  Parameters
  o: center of the ellipsoid
  u1, u2: the principal basis \{v1, v2, v3\} is constructed from this vectors in the following way v1 = u1 v2 = u2 - u2. project\{v1\}
  v1.normalize() v2.normalize() v3 = v1.cross(v2)
  a2, b2, c2: squares of semi-axes of the ellipsoid. The equation is x'^2/a^2 + y'^2/b^2 + z'^2/c^2 = 1
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the ellipsoid
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -pmax and pmax
  thickness: thickness of the ellipsoid
  opacity: opaccity of the ellipsoid
  preserve: Keep self.origin and self.base as the principal reference
def ellipsoide(self,
                 o=[0, 0, 0],
                 u1=[1, 0, 0],
                 u2=[0, 1, 0],
                 a2=1,
                 b2=1,
```

```
cmax=15,
pmax=15,
thickness=0.02,
opacity=1.0,
preserve=True)
```

Draws an ellipsoid

#### **Parameters**

```
o: center of the ellipsoid

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors in the following way v1 = u1 v2 = u2 - u2.project(v1)
v1.normalize() v2.normalize() v3 = v1.cross(v2)

a2, b2, c2: squares of semi-axes of the ellipsoid. The equation is x'^2/a^2 + y'^2/b^2 + z'^2/c^2 = 1

principal: if True, the principal axis are drawn

canonica: if True, the canonical axis are drawn

color: color of the surface

name: name of the ellipsoid

cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -pmax and pmax

thickness: thickness of the ellipsoid

opacity: opaccity of the ellipsoid

preserve: Keep self.origin and self.base as the principal reference
```

Draws an animation showing an ellipsoid of revolution a, b: semiaxis of the initial ellipse

def ellipsoide\_revolucio(self, a=12, b=8, direccio='Z', punt=None)

```
direccio: 'X', the initial ellipse is in the plane XZ and rotates around the X axis
'Y', the initial ellipse is in the plane YZ and rotates around the Y axis
'Z', the initial ellipse is in the plane ZX and rotates around the Z axis

punt: if it's a value between 0 and pi, the animation shows a rotating point
```

```
def elliptic_cylinder(self,
                      o=[0, 0, 0],
                       u1=[1, 0, 0],
                       u2=[0, 1, 0],
                       a2=1,
                       b2=1,
                       principal=True,
                       canonica=True,
                       color='AzureBlueDark',
                       name='EllipticCylinder',
                       zmax=20,
                       cmax=20,
                       pmax=15,
                      thickness=0.02,
                       opacity=1.0,
                       preserve=True)
```

Draws an elliptic cylinder

#### **Parameters**

o: center of the elliptic cylinder

```
a2, b2: squares of semi-axes of the elliptic cylinder. The equation is x'^2/a^2 + y'^2/b^2 = 1
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the elliptic cylinder
  zmax: the elliptic cylinder is drawn between -zmax and zmax
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
  thickness: thickness of the elliptic cylinder
  opacity: opacity of the elliptic cylinder
  preserve: Keep self.origin and self.base as the principal reference
def elliptic_paraboloid(self,
                            o=[0, 0, 0],
                            u1=[1, 0, 0],
                            u2=[0, 1, 0],
                            a2=1,
                            b2=1,
                            principal=True,
                            canonica=True,
                            color='AzureBlueDark',
                            name='EllipticParaboloid',
                            xmax=None,
                            cmax=15,
                            pmax=15,
                            thickness=0.02,
                            opacity=1.0,
                            preserve=True)
  Draws an elliptic paraboloid
  Parameters
  o: vertex of the elliptic paraboloid
  u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  a2, b2: squares of semi-axes of the elliptic paraboloid. The equation is z = x'^2/a^2 + y'^2/b^2
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the elliptic paraboloid
  xmax: maximum value of the coordinate x
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
  thickness: thickness of the elliptic paraboloid
  opacity: opacity of the elliptic paraboloid
  preserve: Keep self.origin and self.base as the principal reference
def esfera(self, centre=Vector((0.0, 0.0, 0.0)), radi=10, cmax=20, name='Esfera')
```

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors

```
Parametre
  centre: center of the sphere
  radi: radius of the sphere
  cmax: maximum values of the x, y and z coordinates
def esfera_cilindre_elliptic(self, radi=10, x0=5, a=5, b=5)
  Draws an sphere centered at (0,0,0), an elliptic cylinder and their intersection
  Parameters
  radi: radius of the sphere
  x0: (x0,0,0) is the center of the ellipse in the plain XY
  a, b: semiaxis of this ellipse
def gir_poligon(self,
                 centre=Vector((0.0, 0.0, 0.0)),
                 costats=6,
                 origen=Vector((0.0, 0.0, 0.0)),
                 radi=8)
  Draws an animation of the rotation around a point of a polygon in the plane XY
  Parameters
  centre: center of the polygon
  costats: sides of the polygon
  origen: center of the rotation
  radi: radius of the polygon
def hiperbola(self, center=Vector((0.0, 0.0, 0.0)), a=8, b=5, negatiu=False, canonica=True)
  Draws the hyperbole of equation (x-x0)^2/a^2 - (y-y0)^2/b^2 == 1 (or -1)
  Parameters
  centre: center of the hyperbole
  a, b: semiaxis of the hyperbole
  canonica: if True, draws the x and y axis
  negatiu: if True, draws the hyperbole (x-x0)^2/a^2 - (y-y0)^2/b^2 == -1
def hiperboloide_dues_fulles(self,
                                o=[0, 0, 0],
                                u1=[1, 0, 0],
                                u2=[0, 1, 0],
                                a2=1,
                                b2=1,
                                c2=1,
                                principal=True,
                                canonica=True,
```

color='AzureBlueDark',
name='TwoSheetParaboloid',

xmax=None,

```
cmax=15,
pmax=15,
thickness=0.02,
opacity=1.0,
preserve=True)
```

Draws a two sheets hyperboloid

```
o: center of the hyperboloid
u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = -1
principal: if True, the principal axis are drawn
canonica: if True, the canonical axis are drawn
color: color of the surface
name: name of the hyperboloid
xmax: maximum value of the x coordinate
cmax: the canonical axis are drawn between -cmax and cmax
pmax: the principal axis are drawn between -cmax and cmax
thickness: thickness of the hyperboloid
opacity: opacity of the hyperboloid
preserve: Keep self.origin and self.base as the principal reference

def hiperboloide_dues_fulles_revolucio(self, a=3, b=2, pmax=8, direccio='Z', plane='XZ', punt=None)
Draws an animation showing a two sheet hyperboloid of revolution a, b: semiaxis of the initial hyperbole
```

```
def hiperboloide_una_fulla(self,
```

```
o=[0, 0, 0],
u1=[1, 0, 0],
u2=[0, 1, 0],
a2=1,
b2=1,
c2=1,
principal=True,
canonica=True,
color='AzureBlueDark',
name='OneSheetHyperboloid',
xmax=None,
cmax=15,
pmax=15,
thickness=0.02,
opacity=1.0,
preserve=True)
```

```
Parameters

o: center of the hyperboloid

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors

a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 1

principal: if True, the principal axis are drawn

canonica: if True, the canonical axis are drawn

color: color of the surface

name: name of the hyperboloid

xmax: maximum value of the x coordinate

cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -cmax and cmax

thickness: thickness of the hyperboloid

opacity: opacity of the hyperboloid

preserve: Keep self.origin and self.base as the principal reference
```

def hiperboloide\_una\_fulla\_revolucio(self, a=3, b=2, pmax=8, direccio='Z', plane='XZ', punt=None)

Draws an animation showing an one sheet hyperboloid of revolution a, b: semiaxis of the initial hyperbole

```
def hyperbolic_cylinder(self,
                         o=[0, 0, 0],
                         u1=[1, 0, 0],
                         u2=[0, 1, 0],
                         a2=1,
                         b2=1,
                         principal=True,
                         canonica=True,
                         color='AzureBlueDark',
                         name='Hyperbolic Cylinder',
                         xmax=None,
                         zmax=15,
                         cmax=15,
                         pmax=15,
                         thickness=0.02,
                         opacity=1.0,
                         preserve=True)
```

Draws an hyperbolic cylinder

#### **Parameters**

```
o: center of the hyperbolic cylinder
```

u1, u2: the principal basis  $\{v1, v2, v3\}$  is constructed from this vectors

a2, b2: squares of semi-axes of the hyperbolic cylinder. The equation is  $x'^2/a^2 - y'^2/b^2 = 1$ 

principal: if True, the principal axis are drawn

```
canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the hyperbolic cylinder
  xmax: maximum value of the x coordinate
  zmax: the hyperbolic cylinder is drawn between -zmax and zmax
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
  thickness: thickness of the hyperbolic cylinder
  opacity: opacity of the hyperbolic cylinder
  preserve: Keep self.origin and self.base as the principal reference
def hyperbolic_paraboloid(self,
                             o=[0, 0, 0],
                             u1=[1, 0, 0],
                             u2=[0, 1, 0],
                             a2=1,
                             b2=1,
                             principal=True,
                             canonica=True,
                             color='AzureBlueDark',
                             name='HyperbolicParaboloid',
                             xmax=None,
                             ymax=None,
                              cmax=15,
                              pmax=15,
                              thickness=0.02,
                              opacity=1.0,
                              preserve=True)
  Draws an hyperbolic paraboloid
  Parameters
  o: vertex of the hyperbolic paraboloid
  u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  a2, b2: squares of semi-axes of the hyperbolic paraboloid. The equation is z = x'^2/a^2 - y'^2/b^2
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the elliptic paraboloid
  xmax: maximum value of the coordinate x
  ymax: maximum value of the coordinate y
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
  thickness: thickness of the hyperbolic paraboloid
  opacity: opacity of the hyperbolic paraboloid
```

def **join**(self, llista)

Joins a list of objects

preserve: Keep self.origin and self.base as the principal reference

#### **Parameters**

llista: list of objects

Draws an animation of the helical motion of an orthohedron around an affine line

## **Parameters**

centre: center of the cylinder radi: radius of the cylinder altura: height of the cylinder origen: point of the affine line eix: axis of rotation

opacity: opacity of the orthohedron

translation: translation of the helical motion (distance by round) if translation = 0.0, it's a rotation motion aligned: if True, aligns the orthohedron with the axis of rotation

```
def moviment_helicoidal_ortoedre(self,
```

```
centre=Vector((0.0, 0.0, 0.0)),
costats=Vector((3.0, 5.0, 2.0)),
opacity=1,
origen=Vector((4.0, 3.0, 0.0)),
eix='Z',
rounds=1,
translacio=0.0,
aligned=False)
```

Draws an animation of the helical motion of an orthohedron around an affine line

## **Parameters**

centre: center of the orthohedron
costats: half sides of the orthohedron
origen: point of the affine line
eix: axis of rotation
opacity: opacity of the orthohedron

translation: translation of the helical motion (distance by round) if translation = 0.0, it's a rotation motion

aligned: if True, aligns the orthohedron with the axis of rotation  $% \left( 1\right) =\left( 1\right) \left( 1\right)$ 

```
def moviment_helicoidal_punt(self,
```

```
punt=Vector((0.0, 0.0, 0.0)),
origen=Vector((-3.0, -3.0, -4.0)),
eix='Z',
```

```
rounds=5,
angle=360,
stop=0,
translacio=2,
vectors=True,
length=15,
reverse=False)
```

Draws an animation of the helical motion of an orthohedron around an affine line

#### **Parameters**

```
punt: posició inicial del punt
origen: point of the affine line
eix: axis of rotation
rounds: rounds of the point aroud the axis
```

translation: translation of the helical motion (distance by frame) if translation = 0.0, it's a rotation motion

```
def one_sheet_hyperboloid(self,
                          o=[0, 0, 0],
                          u1=[1, 0, 0],
                          u2=[0, 1, 0],
                          a2=1,
                          b2=1,
                          c2=1,
                          principal=True,
                          canonica=True,
                          color='AzureBlueDark',
                          name='OneSheetHyperboloid',
                          xmax=None,
                           cmax=15,
                           pmax=15,
                           thickness=0.02,
                           opacity=1.0,
                           preserve=True)
```

Draws an one sheet hyperboloid

## **Parameters**

```
o: center of the hyperboloid
u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 1
principal: if True, the principal axis are drawn
canonica: if True, the canonical axis are drawn
color: color of the surface
name: name of the hyperboloid
xmax: maximum value of the x coordinate
cmax: the canonical axis are drawn between -cmax and cmax
pmax: the principal axis are drawn between -cmax and cmax
thickness: thickness of the hyperboloid
opacity: opacity of the hyperboloid
```

preserve: Keep self.origin and self.base as the principal reference

```
def ortoedre(self,
              centre=Vector((0.0, 0.0, 0.0)),
              costats=[6, 10, 8],
              scalelines=0.05,
              vectors=False,
              color='Blue',
              linecolor='Red',
              vectorcolor='Black',
              name='Ortoedre',
              opacity=1.0,
              thickness=0.0)
\texttt{def parabola}(\texttt{self, vertex=Vector}((0.0, 0.0, 0.0)), p=5, xmax=15, eixos='XY', canonica=True)
  Draws the parabola of equation y - y0 = (x-x0)^2/(2p) or x - x0 = (y-y0)^2/(2p)
  Parameters
  vertex: vertex of the parabola
  p: parameter of the parabola
  pmax: maximum value of the independent variable
  eixos: 'XY', draws y - y0 = (x-x0)^2/(2p) 'YX', draws x - x0 = (y-y0)^2/(2p)
  canonica: if True, draws the x and y axis
def parabolic_cylinder(self,
                         o=[0, 0, 0],
                         u1=[1, 0, 0],
                         u2=[0, 1, 0],
                         p=1,
                         principal=True,
                         canonica=True,
                         color='AzureBlueDark',
                         name='ParabolicCylinder',
                         xmax=12,
                         ymax=30,
                         cmax=20,
                         pmax=20,
                         thickness=0.02,
                         opacity=1.0,
                         preserve=True)
  Draws an hyperbolic paraboloid
  Parameters
  o: vertex of the hyperbolic paraboloid
```

```
o: vertex of the hyperbolic paraboloid u1, u2: the principal basis \{v1, v2, v3\} is constructed from this vectors p: Parameter of the cylinder z' = x'^2/(2*p) principal: if True, the principal axis are drawn canonica: if True, the canonical axis are drawn color: color of the surface name: name of the elliptic paraboloid xmax: maximum value of the coordinate x ymax: maximum value of the coordinate y
```

pmax: the principal axis are drawn between -cmax and cmax thickness: thickness of the hyperbolic paraboloid opacity: opacity of the hyperbolic paraboloid preserve: Keep self.origin and self.base as the principal reference def paraboloide\_elliptic(self, o=[0, 0, 0],u1=[1, 0, 0], u2=[0, 1, 0], a2=1,b2=1,principal=True, canonica=True, color='AzureBlueDark', name='EllipticParaboloid', xmax=None, cmax=15, pmax=15, thickness=0.02, opacity=1.0, preserve=True) Draws an elliptic paraboloid

cmax: the canonical axis are drawn between -cmax and cmax

#### **Parameters**

o: vertex of the elliptic paraboloid
u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
a2, b2: squares of semi-axes of the elliptic paraboloid. The equation is z = x'^2/a^2 + y'^2/b^2
principal: if True, the principal axis are drawn
canonica: if True, the canonical axis are drawn
color: color of the surface
name: name of the elliptic paraboloid
xmax: maximum value of the coordinate x
cmax: the canonical axis are drawn between -cmax and cmax
pmax: the principal axis are drawn between -cmax and cmax
thickness: thickness of the elliptic paraboloid
opacity: opacity of the elliptic paraboloid
preserve: Keep self.origin and self.base as the principal reference

Draws an animation showing an elliptic paraboloid of revolution a: The constant of the initial parabola

#### **Parameters**

a, b: constants the defines he hyperbolic paraboloid xmax, ymax: maximun values of the x and y coordinates

```
def paraboloide_hiperbolic(self,
```

```
o=[0, 0, 0],
u1=[1, 0, 0],
u2=[0, 1, 0],
a2=1,
b2=1,
principal=True,
canonica=True,
color='AzureBlueDark',
name='HyperbolicParaboloid',
xmax=None,
ymax=None,
cmax=15,
pmax=15,
thickness=0.02,
opacity=1.0,
preserve=True)
```

Draws an hyperbolic paraboloid

## **Parameters**

```
o: vertex of the hyperbolic paraboloid
u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
a2, b2: squares of semi-axes of the hyperbolic paraboloid. The equation is z = x'^2/a^2 - y'^2/b^2
principal: if True, the principal axis are drawn
canonica: if True, the canonical axis are drawn
color: color of the surface
name: name of the elliptic paraboloid
xmax: maximum value of the coordinate x
ymax: maximum value of the coordinate y
cmax: the canonical axis are drawn between -cmax and cmax
pmax: the principal axis are drawn between -cmax and cmax
thickness: thickness of the hyperbolic paraboloid
opacity: opacity of the hyperbolic paraboloid
preserve: Keep self.origin and self.base as the principal reference

def paraboloide_hiperbolic_simple(self, a=3, b=4, xmax=12, ymax=12)
```

## **Parameters**

```
a, b: constants the defines he hyperbolic paraboloid xmax, ymax: maximun values of the x and y coordinates
```

Draws the hyperbolic paraboloid of equation  $z = x^2/a^2 - y^2/b^2$ 

```
p0=Vector((1.0, 1.0, 1.0)),
u=Vector((1.0, 0.0, 0.0)),
q0=Vector((-1.0, 2.0, -2.0)),
v=Vector((0.0, 0.0, 1.0)),
sizex=60,
sizey=80,
length=5,
t1=0,
t2=0,
head_height=0.1)
```

Draws the straigth line perpendicular to a given two non parallel lines

## **Parameters**

```
p0: point of the first line
  u: director vector of the first line
  q0: point of the second line
  v: director vector of the second line
  sizex, sizey: sizes of the rectangle
  length: length og the vectors
  t1, t2: displacement of the points p0 and q0
def pla_afi(self,
             punt=Vector((0.0, 0.0, 0.0)),
             normal=None,
             v1=Vector((3.0, 2.0, 1.0)),
             v2=Vector((1.0, -2.0, 0.5)),
             canonica=False,
             name='Pla afí',
             length=15,
             color='Cyan',
             sizex=25,
             sizey=20,
             opacity=0.9,
             elements=True)
```

Draws the affine plane generated by two vectors passing through a point

```
punt: point of the plane

normal: normal vector of the plane

v1, v2: generators of the plane

canonica: if True, draws the x, y and z axis

name: name of the affine plane

length: length of the axis x, y and z

color: color of the plane

sizex, sizey: size of the plane

opacicity: opacity of the plane

def pla_vectorial(self,

v1=Vector((3.0, 2.0, 1.0)),

v2=Vector((1.0, -2.0, 0.5)),
```

```
canonica=False,
length=15,
color='Cyan',
sizex=25,
sizey=20,
opacity=0.8,
thickness=0.01)
```

Draws the plane generated by two vectors

## **Parameters**

normals=None, colors=None, canonica=True, length=25, sizex=45, sizey=40, opacity=1.0, elements=False)

Draws threee planes

## **Parametres**

```
punts: three points, one for each plane
normals: three normal vectors, one for each plane
colors: three colors, one for each plane
canonica: if True, draws the x, y and z axis
length: length of the axis x, y and z
sizex, sizey: size of the planes
opacicity: opacity of the planes
elements: if True, draws the point and the normal vector for each plane

def product_components(self, u, v)
```

# Parameters

Computes the vectorial product u x v

u, v: two Vectors

```
v1=Vector((3.0, -1.0, 1.0)),
v2=Vector((1.0, 0.5, 0.5)),
radi=0.15,
sizex=35,
sizey=30,
line=1.8,
canonica=True)
```

Draws the orthogonal projection and the symmetric of a point with respect an affine plane

#### **Parameters**

```
punt: the initial point
  p0: point of the affine plane
  v1, v2: generators of the plane
  radi: radius of the points
  sizex, sizey: sizes of the affine plane
  factor: how to draw the perpendicular line
  canonica: if True, draws the x, y and z axis
def projeccio_ortogonal_simetric_pla_vectorial(self,
                                                     vector=Vector((7.0, -1.0, 12.0)),
                                                     v1=Vector((3.0, -1.0, 1.0)),
                                                     v2=Vector((1.0, 0.5, 0.5)),
                                                     sizex=None,
                                                     sizey=None,
                                                     color='AzureBlueDark',
                                                     canonica=True,
                                                     orthogonal=False,
                                                     orthonormal=False,
                                                     thickness=0.01)
```

Draws the otoghonal projection and the symmetric of a vector with respecte a plane

## **Parameters**

Draws the orthogonal projection and the symmetric of a point with respect an affine line

```
punt: the initial point
  p0: point of the affine line
  v1: generator of the line
  radi: radius of the points
  sizex, sizey: sizes of the affine plane
  canonica: if True, draws the x, y and z axis
def projeccio_ortogonal_simetric_recta_vectorial(self,
                                                       vector=Vector((7.0, -1.0, 12.0)),
                                                       v1=Vector((3.0, -1.0, 1.0)),
                                                       canonica=True,
                                                       length=15)
  Draws the otoghonal projection and the symmetric of a vector with respecte a line
  Parameters
  vector: the initial vector
  v1: generator of the line
  canonica: if True, draws the x, y and z axis
  length: length for x, y and z axis and v1 axis
def punt_referencia_canonica(self,
                                punt=Vector((-4.0, 7.0, 6.0)),
                                radius=0.1,
                                length=12,
                                scale=0.06,
                                name='Punt p',
                                color='Black',
                                coordenades=True,
                                vector=True)
  Draws a point expressed in the canonical reference
  Parameters
  punt: the point to draw
  length: length of the axis
  name: name of the point
  coordenades: if True draws lines representing the coordinates
  vector: if True, it draws the position vector
def punt_referencia_no_canonica(self,
                                   punt=Vector((5.0, 6.0, -5.0)),
                                   origin=Vector((-2.0, 3.0, 3.0)),
                                   u1=Vector((-0.33333333432674408, -0.66666666865348816,
                                   0.66666666865348816)),
                                   \verb"u2=Vector"((0.6666666865348816, 0.3333333432674408, 0.66666666865348816))",
                                   u3=Vector((-0.6666666865348816, 0.6666666865348816,
                                   0.3333333432674408)),
                                   color='Black',
```

length=12,
scale=0.04,

```
radius=0.1,
name='Punt p',
vector=True)
```

Draws a point expressed in the reference {0,u1,u2,u3} with origin in the point origin and sets the default origin and default base to them

#### **Parameters**

```
punt: point to draw
  origin: origin of the reference
  u1, u2, u3: vectors of the base
  length: length of the axis
  scale: scale of the axis
  name: name of the reference
  vector: if True, it draws the position vector
def recta_afi(self,
               punt=Vector((3.0, 4.0, -2.0)),
               v=Vector((1.0, 2.0, 1.0)),
               color='Black',
               size=15,
               name='Recta afi',
               canonica=True,
               length=12,
               scale=0.03,
               elements=True)
```

Draws the affine line generated by a vector passing through a point

# **Parameters**

```
punt: point of the plane
  v: generators of the line
  canonica: if True, draws the x, y and z axis
  name: name of the affine plane
  length: length of the axis x, y and z
  color: color of the plane
  size: lenght of the line
  scale: scale of the line
def rectangle(self,
               origin=[0, 0, 0],
               u1=[1, 0, 0],
               u2=[0, 1, 0],
                scalelines=0.1,
               color='AzureBlueMedium',
               linecolor='AzureBlueDark',
               name='Rectangle',
                sizex=10,
                sizey=10,
                opacity=1.0,
                thickness=0.0)
```

Draws a rectangle

```
Parameters
   origin: base vertex of the rectangle
   u1, u2: base vectors for the rectangle
   scalelines: scale of the edges of the rectangle
   color: color of the rectangle
   linecolor: color of the edges
   name: name of the rectangle
   sizex, sizey: sizes of the rectangle
   opacity: opacity of the rectangle
   thickness: thickness of the rectangle
def referencia_canonica(self,
                           origin=Vector((0.0,\ 0.0,\ 0.0)),
                           length=15,
                           scale=0.04,
                           zaxis=True,
                           name='Referència canònica')
   Draws the canonical reference
   Parameters
   origin: point where to represent the base
   length: length of the axis
   scale: scale of the cylinder
   zaxis: if False the z axis is not drawn
   name: name of the object
def referencia_no_canonica(self,
                              origin=Vector((0.0, 0.0, 0.0)),
                              u1=Vector((1.0, -1.0, 0.0)),
                              u2=Vector((-0.5, 1.0, 0.5)),
                               u3=Vector((-1.0, 0.0, 1.0)),
                               length=12,
                               scale=0.04,
                               preserve=True,
                              name="Referència R'")
   Draws the reference {o;u1,u2,u3} with origin in the point origin and sets the default origin and default base to them
   Parameters
   origin: origin of the reference
   u1, u2, u3: vectors of the base
   length: length of the axis
   scale: scale of the axis
   name: name of the reference
def reset(self)
```

Resets origin, base, rotation, frames and colors

def reset\_base(self)

```
Sets self.base to the canonical basis
def reset_colors(self)
   Set self.colors to default colors
def reset_frames(self)
   Set self.frame to 0
   Parameters
   name: name of a color
def reset_origin(self)
   Sets the origin to the point (0,0,0)
def reset_rotation(self)
   Sets the rotation to identity, i.e., rotation of 0 degrees around the vector (1,0,0)
```

```
def revolution_surface(self,
                       fun=None,
                        tmin=0.0,
                       tmax=1.0,
                       o=Vector((0.0, 0.0, 0.0)),
                       u1=Vector((1.0, 0.0, 0.0)),
                       u2=Vector((0.0, 1.0, 0.0)),
                       pmax=0,
                       steps=256,
                       thickness=0.025,
                       axis='Z',
                       name='Revolution surface',
                        color='AzureBlueDark')
```

Draws a revolution surface from a curve in the reference R'

# **Parameters**

```
fun: parametric equacion of the curve
   steps: number of steps
   axis: axis of revolution. It must be 'X', 'Y' or 'Z'
   o: origin of the reference R'
   u1, u2: vectors to construct the basis {v1, v2, v3}
   pmax: the principal axis are drawn between -pmax and pmax
   color: color of the surface
def rotacio_ortoedre(self,
                        centre=Vector((0.0, 0.0, 0.0)),
                        costats=Vector((8.0, 5.0, 4.0)),
                        eix='Z',
                        angle=360,
                        stop=0,
                        opacity=1)
```

Draws an animation of an orthohedron rotating around a vectorial line

Draws an animation of an orthohedron rotating given the Euler's angles

#### **Parameters**

reverse=False)

Draws an animation of a vector rotating around a vectorial line

```
length=None,
stop=0,
vectors=True)
```

Draws an animation of a point rotating around an afine line

#### **Parameters**

Draws an animation of a vector rotating around a vectorial line

#### **Parameters**

```
vector: vector to rotate
  eix: axis of rotation, given by a vector or by X, Y or Z
  adaptada: if True, draws a base adapted to the rotation
def rotate_euler(self,
                  obj=None,
                  psi=0.0,
                  theta=0.0,
                  phi=0.0,
                   frames=3,
                  axis='ZXZ',
                  amax=15,
                   scaleaxis=0.075,
                   reverse=False,
                  local=False,
                   stop=0,
                   radians=False,
                   canonica=True,
                   positive=False)
```

Rotates an object by the Euler angles psi, theta and phi

```
object: the object
psi, theta, phi: the Euler angles expressed in degrees
axis: it must be 'XYZ', 'XZY', 'YXZ', 'YZX', 'ZXY', 'ZYX', 'XYX', 'XZX', 'YXY', 'YZY', 'ZXZ' or 'ZYZ'
amax: axis value for draw_base_axis
scaleaxis: scale value for draw_base_axis
local: if True the center of rotation is the location of the object
radians: if True, psi, theta and phi must be in radians
positive: if False and psi, theta or phi are greather than 180 degrees, they are converted to negative angles
```

```
def rotate_object(self,
                    obj=None,
                    axis='Z',
                    frames=1,
                    origin=Vector((0.0, 0.0, 0.0)),
                    angle=360,
                    localaxis=None,
                    localangle=None,
                    translation=0.0,
                    rounds=1,
                    stop=0,
                    length=25,
                    draw=True)
  Rotates an object around the axis
  Parameters
  obj: the object
  axis: it must be 'X', 'Y', 'Z' or a Vector
  frames: increment of the frame set
  traslation: tranlation by round
  local: if True the center of rotation is the location of the object
def rotate_object_by_axis_angle(self,
                                    obj=None,
                                    axis=Vector((1.0, 0.0, 0.0)),
                                    angle=90,
                                    amax=15,
                                    frames=1,
                                    scaleaxis=0.075,
                                    local=False)
  Rotates an object around an angle 'angle' around the axis
  Parameters
  obj: the object
  axis: any non nul Vector
  angle: the angle of rotation in degrees
  frames: increment of the frame set
  scaleaxis: scale value for draw_base_axis
  local: if True the center of rotation is the location of the object
def rotate_objects(self,
                     objs=[],
                     axis='Z',
                     angle=None,
                     frames=1,
                     origin=Vector((0.0, 0.0, 0.0)),
                     translation=0,
                     rounds=1,
                     length=25,
                     stop=0,
                     draw=False)
```

```
Parameters
```

objs: the list of objects

Rotates a point around an affine line

## **Parameters**

```
point: the point
  origen: a point of the affine line
  axis: it must be 'X', 'Y', 'Z' or a vector
  length: length of the

def rotate_vector(self, vector=None, axis='Z', length=25, angle=360, stop=0)
  Rotates a vector around the axis
```

Parameters

Draws an spheric segment in a sphere centered at origin with radius r from the point whith spherical coordinates (radi,p1,s1) to the point (radi,p2,s2).

### **Parameters**

r: radius of the sphere p1: polar angle of the first point s1: azimuthal angle of the first point p2: polar angle of the second point s2: azimuthal angle of the second point

```
\texttt{def} \ \textbf{set\_base}(\texttt{self}, \ \texttt{base=[[1, 0, 0], [0, 1, 0], [0, 0, 1]], orthonormal=False)}
```

Sets the self.base, i.e., the basis of the reference coordinates used to display objects

```
Parameters
```

base: list of three vectors

orthonormal: if True, the Gram-Schmidt method is applied and the vectors are normalized.

```
def set_colors(self, names=None)
```

Set self.colors to the list of colors with names 'names'

## **Parameters**

names: list of name colors

```
def set_cursor(self, origin=[0, 0, 0], direction=[1, 0, 0], axis='x')
```

Sets the cursor position and direction

## **Parameters**

origin: position of the cursor

direction: vector that indicates the direction of the axis 'axis'

```
axis: 'x', 'y' or 'z'
```

```
def set_cursor_rotation(self,
```

```
origin=[0, 0, 0],
rotation=Matrix(((1.0, 0.0, 0.0), (0.0, 1.0, 0.0), (0.0, 0.0, 1.0))))
```

Sets the rotation of the cursor

## **Parameters**

origin: position of the cursor

rotation: matrix of a rotation

```
def set_default_color(self, name)
```

Set self.defaultcolor to the color with name 'name'

## **Parameters**

name: name of a color

```
def set_origin(self, vector=[0, 0, 0])
```

Sets the origin of the reference coordinates used to display objects.

#### **Parameters**

vector: origin's position

```
def set_rotation(self, angle=None, vector=None, quaternion=None)
```

Sets self.rotation to the rotation defined by an angle and an axis or by a quaternion.

# **Parameters**

angle: angle of rotation in degrees

vector: axis of rotation

quaternion: quaternion that defines a rotation

The angle and vector takes precedence over the quaternion

def simple\_curve(self,

```
tmin=0.0,
                   tmax=1.0,
                   steps=25,
                   name='Simple curve',
                   symmetry=None,
                   draw=False)
  Return a curve defined by the parametrization f
  Parameters
  f: Parametrization of the curve
  tmin: minimum value of the parameter
  tmax: maximum value of the parameter
  steps: number of steps
  name: name of the curve
  symmetry: None or a value in the list ('XY','XZ','YZ','X','Y','Z','O'). Symmetry of the curve
  draw: if True, the curve is drawn
def sphere(self,
            o=[0, 0, 0],
            r2=1,
            principal=True,
            canonica=True,
            color='AzureBlueDark',
            name='Sphere',
            cmax=15,
            pmax=15,
            thickness=0.02,
            opacity=1.0,
            preserve=True)
  Draws a sphere of center 'o' and radius squared equal to 'r2'
  Parameters
  o: center of the sphere
  r2: radius of the sphere squared
  principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
  color: color of the surface
  name: name of the sphere
  cmax: the canonical axis are drawn between -cmax and cmax
  pmax: the principal axis are drawn between -cmax and cmax
  thickness: thickness of the sphere
  opacity: opacity of the sphere
  preserve: Keep self.origin and self.base as the principal reference
```

def superficie\_revolucio\_parabola(self, a=0.2, vertex=Vector((0.0, 0.0, 0.0)), pmax=8, pla='XZ',

Draws an animation of a revolution surface from a parabola

#### **Parameters**

```
a: the parabola is of the form y = a*x^2
vertex: vertex of the parabola
pmax: maximum value of the independent variable
```

pla: a value from the list ('XY','YX','XZ','ZX','YZ','ZY') representing the variables for the equation 'XY'  $y = ax^2$  and rotaqtion around the X axis 'YX'  $x = ay^2$  and rotaqtion around the Y axis 'XZ'  $z = ax^2$  and rotaqtion around the Z axis 'YZ'  $z = ay^2$  and rotaqtion around the Z axis 'YZ'  $z = ay^2$  and rotaqtion around the Z axis 'YZ'  $z = ay^2$  and rotaqtion around the Z axis

punt: punt: if it's a float value, draws a moving poing

```
def tor(self, centre=Vector((8.0, 0.0, 3.0)), radi=3, cmax=15, punt=None)
```

Draws a torus of revolution from a circumference

#### **Parameters**

```
centre: center of the circumference
  radi: radius of the circumference
  cmax: maximum values of the x, y and z coordinates
  punt: if it's a float value, draws a moving poing
def triangle(self,
             vertices=[[0, 0, 0], [1, 0, 0], [0, 1, 0]],
             scalelines=0.075,
             color='AzureBlueMedium',
             linecolor='Blue',
             name='Triangle',
             baricentre=False,
              factors=(2, 2, -2),
             ortocentre=False,
              circumcentre=False,
             opacity=1.0,
             radius=0.03)
```

Draws a triangle from the vertices

```
s2=1.5707963267948966,
p3=0,
s3=0)
```

Draws an spheric triangle in a sphere centered at origin with radius r with vetices whith spherical coordinates (radi,p1,s1), (radi,p2,s2) and (radi,p2,s2).

#### **Parameters**

r: radius of the sphere p1: polar angle of the first point s1: azimuthal angle of the first point p2: polar angle of the second point s2: azimuthal angle of the second point p3: polar angle of the third point s3: azimuthal angle of the third point

```
def triangle_esferic_aleatori(self, r=10)
```

Draws a random spheric triangle in a sphere centered at origin with radius r

#### **Parameters**

r: radius of the sphere

```
def two_sheets_hyperboloid(self,
                           o=[0, 0, 0],
                           u1=[1, 0, 0],
                           u2=[0, 1, 0],
                           a2=1,
                           b2=1,
                           c2=1,
                           principal=True,
                           canonica=True,
                           color='AzureBlueDark',
                           name='TwoSheetParaboloid',
                           xmax=None,
                           cmax=15,
                           pmax=15,
                           thickness=0.02,
                           opacity=1.0,
                           preserve=True)
```

Draws a two sheets hyperboloid

## **Parameters**

```
o: center of the hyperboloid
u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = -1
principal: if True, the principal axis are drawn
canonica: if True, the canonical axis are drawn
color: color of the surface
name: name of the hyperboloid
xmax: maximum value of the x coordinate
cmax: the canonical axis are drawn between -cmax and cmax
pmax: the principal axis are drawn between -cmax and cmax
thickness: thickness of the hyperboloid
opacity: opacity of the hyperboloid
```

preserve: Keep self.origin and self.base as the principal reference

Draws a vector expressed in the canonical base

#### **Parameters**

vector: the vector to draw length: length of the axis name: name of the vector

components: if True draws lines representing the components

```
def vector_base_no_canonica(self,
```

```
vector=Vector((5.0, 6.0, -5.0)),
origin=Vector((0.0, 0.0, 0.0)),
u1=Vector((-0.3333333432674408, -0.6666666865348816, 0.6666666865348816)),
u2=Vector((0.66666666865348816, 0.33333333432674408, 0.6666666865348816)),
u3=Vector((-0.6666666865348816, 0.6666666865348816, 0.33333333432674408)),
length=12,
scale=0.04,
name="Base B'",
canonica=True,
preserve=False)
```

Draws a vector expressed in the base {u1,u2,u3} with origin in the point origin and sets the default origin and default base to them

#### **Parameters**

vector: vector to draw

origin: origin of the vector and the base

u1, u2, u3: vectors of the base

length: length of the axis

scale: scale of the base

name: name of the base

```
\texttt{def vectors\_to\_quaternion}(\texttt{self}, \ \texttt{u1=Vector}((1.0, \ 0.0, \ 0.0)), \ \texttt{u2=Vector}((0.0, \ 1.0, \ 0.0)))
```

Returns the quaternion correspondint to the base  $\{v1, v2, v3\}$  u1, u2: the principal basis  $\{v1, v2, v3\}$  is constructed from this vectors in the following way v1 = u1 v2 = u2 - u2.project(v1) v1.normalize() v2.normalize() v3 = v1.cross(v2)

class Rotation (angle=None, vector=None, axis=None, quaternion=None, radians=False)

Class used for work with rotations. The stored value in the class is a quaternion

Initializes the value for a rotation

# Parameters

angle: angle of rotation

vector: axis of rotation

quaternion: The quaternion itself

radians: must be True if the angle is entered in radians and False if the is entered in degrees.

# Static methods

```
def from_euler_angles(psi, theta, phi, axis='ZXZ', radians=False)
```

Initializes a rotation from its Euler angles in the order ZXZ

## **Parameters**

```
phi, theta, psi: Euler angles axis: it must be 'XYZ', 'XZY', 'YXZ', 'YZX', 'ZXY', 'ZYX', 'XYX', 'XZX', 'YXY', 'YZY', 'ZXZ' or 'ZYZ'
```

radians: if radians, psi, theta and must be in radians

## Methods

```
def apply(self, v)
```

Applies the rotation to an object v Parameters: v: any object that can be transformed by a rotation

```
def to_axis_angle(self, radians=False)
```

Returns the axis and angle of the rotation

## **Parameters**

radians: if True, the angle returned is in radians, if not, is returned in degrees

```
def to_euler_angles(self, axis='ZXZ', randomize=False, radians=False)
```

Returns the Euler angles according to axis 'axis'

#### **Parameters**

```
axis: it must be 'XYZ', 'XZY', 'YXZ', 'YZX', 'ZXY', 'ZYX', 'XYX', 'XZX', 'YXY', 'YZY', 'ZXZ' or 'ZYZ' radians: if True, the angle returned is in radians, if not, is returned in degrees
```

# **Functions**

- add\_object\_align\_init
- ∘ createFaces
- create\_mesh\_object
- draw\_parametric\_surface
- object\_data\_add

#### Classes

- Color
- Colors
- color
- colors
- colorsbyname
- EuclideanReference
- base
- coordinates

## LinearAlgebra

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- add\_ligths
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## Rotation

- apply
- from\_euler\_angles
- to\_axis\_angle
- to\_euler\_angles