# Module LinearAlgebra

# **Functions**

# Classes

```
class Color (r, g, b, name)
```

Class that defines a color in RGB format

# class Colors

Class that defines a list of colors by name

Class variables

var colorsbyname

Static methods

def color(name)

Function that returns a color from his name

**Parameters** 

name: name of the color

def colors(names)

Return a list of colors fron their names

**Parameters** 

names: list of names

# class LinearAlgebra

Class used to define all the functions in this module to work with graphics in Blender Initializes the values for scene, objects, meshes, collection, etc.

# Methods

```
\label{eq:def_def} def \ add\_ligth(self, \ location=[0, \ 0, \ 100], \ energy=3, \ direction=[0, \ 0, \ -1])
```

Adds a ligth to the scene

**Parameters** 

```
location: location point of the light
  energy: energy of the ligth
  direction: direction of the light
def add_ligths(self, energy=1)
  Adds diferent lights to the scene
   Parameters
  energy: energy of the lights
def add_material(self, obj, material_name, r, g, b, opacity=1.0)
  Adds a material and color to an object
   Parameters
  obj: object
   material_name: material's name
   r, g, b: RGB color values
  opacity: the opacity
def animate_revolution_surface(self, fun=None, tmin=0.0, tmax=1.0, steps=256, curvethicknes=0.025,
                                thickness=0.025, frames=3, angle=3, radians=False, axis='Z',
                                symmetry=None, name='Revolution surface', color='AzureBlueDark',
                                point=None)
   Draws and animates a revolution surface from a curve
   Parameters
   fun: parametric equacion of the curve
  steps: number of steps to graw the curve
   curvethicknes: thickness of the curve
  frames: number of frames at each step of revolution
   angle: step angle of the revolution
   radians: if True, angle must be in radians
  axis: axis of revolution. It must be 'X', 'Y' or 'Z'
   symmetry: symmetry used to draw the curve
   name: name of the surface
  color: color of the surface
   point: if not None draw three points and a cercle. Must be a float between tmax and tmin
canònica')
   Draws the canonical base
   Parameters
   origin: point where to represent the base
   length: length of the axis
  scale: scale of the cylinder
```

zaxis: if False the z axis is not drawn

name: name of the object

```
def base_cilinder(self)
    Draws a base cilinder with radius 1 and depth 1
```

Draws a base cone with radius1=1.5, radius2=0, depth=2

```
def base_is_canonica(self)
```

def base cone(self)

Returns True if sel.base is the canonical basis

```
def base_no_canonica(self, origin=Vector((0.0, 0.0, 0.0)), u1=Vector((1.0, -1.0, 0.0)), u2=Vector((0.5, -0.5, -0.5)), u3=Vector((-1.0, 0.0, 1.0)), length=12, scale=0.04, name="Base B'")
```

Draws the base {u1,u2,u3} with origin in the point origin and sets the default origin and default base to them

#### **Parameters**

origin: origin of the vector and the base

u1, u2, u3: vectors of the base

length: length of the axis

scale: scale of the base

name: name of the base

Draw the components of a vectors in the canonical base and in the base {u1,u2,u3}. Sets the default origin and default base to them

# **Parameters**

vector: vector to draw

u1, u2, u3: vectors of the base

length: length of the axis

Draw the coordinates of a point in the canonical reference and in the reference {o;u1,u2,u3}. Sets the default origin and default base to them

# **Parameters**

```
punt: point to draw
```

origin: origin of the reference

u1, u2, u3: vectors of the base

length: length of the axis

Draws an elliptic cylinder

```
Parameters
       o: center of the elliptic cylinder
       u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
       a2, b2: squares of semi-axes of the elliptic cylinder. The equation is x'^2/a^2 + y'^2/b^2 = 1
       principal: if True, the principal axis are drawn
      canonica: if True, the canonical axis are drawn
       color: color of the surface
       name: name of the elliptic cylinder
       zmax: the elliptic cylinder is drawn between -zmax and zmax
      cmax: the canonical axis are drawn between -cmax and cmax
       pmax: the principal axis are drawn between -cmax and cmax
       thickness: thickness of the elliptic cylinder
      opacity: opacity of the elliptic cylinder
def cilindre_elliptic_simple(self, a=10, b=6, direccio='Z', pmax=26)
       Draws an elliptic cylinder with direction X, Y or Z
       Parameters
      a, b: semiaxis of the ellipse
      direction: direction of translation of the ellipse
      pmax = height of the cylindrer
 def \ cilindre\_hiperbolic(self, \ o=[\theta, \ \theta, \ \theta], \ u1=[1, \ \theta, \ \theta], \ u2=[\theta, \ 1, \ \theta], \ a2=1, \ b2=1, \ principal=True, \ a2=1, \ b2=1, \ principal=True, \ a3=1, \ b3=1, \ b3
                                                           canonica=True, color='AzureBlueDark', name='HyperbolicCylinder', xmax=None,
                                                           zmax=20, cmax=15, pmax=15, thickness=0.02, opacity=1.0)
      Draws an hyperbolic cylinder
       Parameters
       o: center of the hyperbolic cylinder
       u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
      a2, b2: squares of semi-axes of the hyperbolic cylinder. The equation is x'^2/a^2 - y'^2/b^2 = 1
       principal: if True, the principal axis are drawn
      canonica: if True, the canonical axis are drawn
       color: color of the surface
       name: name of the hyperbolic cylinder
      xmax: maximum value of the x coordinate
       zmax: the hyperbolic cylinder is drawn between -zmax and zmax
       cmax: the canonical axis are drawn between -cmax and cmax
       pmax: the principal axis are drawn between -cmax and cmax
      thickness: thickness of the hyperbolic cylinder
      opacity: opacity of the hyperbolic cylinder
```

def cilindre\_hiperbolic\_simple(self, a=4, b=3, direccio='Z', pmax=12, hmax=26)

Draws an hyperbolic cylinder with direction X, Y or Z

# **Parameters**

```
direction: direction of translation of the hyperbole
   pmax = maximum value of the independent variable
   hmax = height of the cylindrer
def cilindre_parabolic(self, o=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], a=1, principal=True, canonica=True,
                          color='AzureBlueDark', name='ParabolicCylinder', xmax=None, ymax=30, cmax=20,
                          pmax=20, thickness=0.02, opacity=1.0)
   Draws an hyperbolic paraboloid
   Parameters
   o: vertex of the hyperbolic paraboloid
   u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
   a: coefficient of the intial parabola
   principal: if True, the principal axis are drawn
   canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the elliptic paraboloid
   xmax: maximum value of the coordinate x
   ymax: maximum value of the coordinate y
   cmax: the canonical axis are drawn between -cmax and cmax
   pmax: the principal axis are drawn between -cmax and cmax
   thickness: thickness of the hyperbolic paraboloid
   opacity: opacity of the hyperbolic paraboloid
def cilindre_parabolic_simple(self, a=3, direccio='Z', pmax=10, hmax=26)
   Draws a parabolic cylinder with direction X, Y or Z
   Parameters
   a: the initial parabola has equation of type z=\pm x^2/a^2
   direction: direction of translation of the hyperbole
   pmax = maximum value of the independent variable
   hmax = height of the cylindrer
def clear(self)
   Clears and removes all the elements
def comp_times_vector(self, u, v)
   Computes the vectorial product u x v
   Parameters
   u, v: two Vectors
```

a, b: semiaxis of the hyperbole

def components\_in\_base(self, vector=None)

Returns the components of the vector 'vector' in the basis determined by self.rotation and the basis self.base

#### **Parameters**

vector: components of the vector in the canonical basis

Draws a cone

#### **Parameters**

o: center of the cone

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors

a2, b2, c2: squares of semi-axes of the cone. The equation is  $x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 0$ 

half: if True draws half cone

principal: if True, the principal axis are drawn

canonica: if True, the canonical axis are drawn

color: color of the surface

name: name of the cone

xmax: maximum value of the x coordinate

cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -pmax and pmax

thickness: thickness of the cone

opacity: opacity of the cone

# def con\_cilindre\_elliptic(self, a2=1, b2=1, c2=1, x0=5, a=8, b=5, zmax=15)

Draws a cone with vertex at (0,0,0) and equation  $x^2/a^2 + y^2/b^2 - z^2/c^2 = 0$ , an elliptic cylinder and their intersection

# **Parameters**

a2, b2, c2: coefficients of the equation of the cone

x0: (x0,0,0) is the center of the ellipse in the plain XY

a, b: semiaxis of this ellipse

zmax: maximum value of the z coordinate

# def con\_revolucio(self, a=1.5, pmax=8, direccio='Z', punt=None)

Draws an animation showing a cone of revolution a: slope of the initial straight line

pmax: maximum value of the independent variable

direccio: 'X', the initial line is in the plane YX and rotates around the X axis
'Y', the initial line is in the plane ZY and rotates around the Y axis
'Z', the initial line is in the plane XZ and rotates around the Z axis

punt: if it's a value between -pmax and pmax, the animation shows a rotating point

Draws a cone

# **Parameters**

o: center of the cone

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors

```
a2, b2, c2: squares of semi-axes of the cone. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 0
   half: if True draws half cone
   principal: if True, the principal axis are drawn
   canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the cone
   xmax: maximum value of the x coordinate
   cmax: the canonical axis are drawn between -cmax and cmax
   pmax: the principal axis are drawn between -pmax and pmax
   thickness: thickness of the cone
   opacity: opacity of the cone
def coordinates_en_referencia(self, point=None)
   Returns the coordinates of the point 'point' in the reference determined by self.origin, self.rotation and the basis self.base
   Parameters
   point: coordinates of the point in the canonical reference
def curve(self, fun=None, tmin=0.0, tmax=1.0, steps=25, thickness=0.01, name='Curve', color='White',
           axis=False, zaxis=True, o=Vector((0.0, 0.0, 0.0)), u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0,
           1.0, 0.0)), symmetry=None, change=False)
   Draws a curve in a reference R' determined by the origin o and basis {v1, v2, v3} constructed from u1 and u2 and the
   symmetric curve or curves from the parameter 'symmetry'
   Parameters
   fun: the parametric function
   tmin: minimum value of the parameter
   tmax: maximum value of the parameter
   steps: number of steps
   thickness: thickness of the curve
   name: name of the curve
   color: color of the curve
   axis: if True draws the axis of the reference R'
   zaxis: if True draws the z' axis
   o: origin of the reference R'
   u1, u2: vectors to construct the basis {v1, v2, v3}
   symmetry: list of values in ('XY','XZ','YZ','X','Y','Z','O'). For every value S, draw the symmetric curve respect to S
   change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}
def delete_base_cilinder(self)
   Removes the base cilinder
def delete base cone(self)
   Removes the base cone
```

def draw\_base\_axis(self, scale=0.05, head\_height=0.15, axis=0, name='Axis', positive=True, zaxis=True)

Draws a reference axis given by self.origin, self.rotation and the basis self.base

```
Parameters
   scale: scale of the cylinder
   head_height: height of the head of the vector from self.base
   axis: length of the coordinate axis. If the length is 0, only the basis vectors are drawn
   name: name of the result object
   positive: if True, draw the positive part of the axis
   zaxis: if True, draw the z axis
def draw circle(self, center=[0, 0, 0], u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0)),
                  axis=False, zaxis=False, radius=1, steps=25, thickness=0.01, name='Circle',
                  color='White', change=False)
   Draws a circle of center 'center' and radius 'radius' in the plane determined by vectors u1 and u2
   Parameters
   center: center of the circle
   u1, u2: vectors to construct the basis {v1, v2, v3}
   axis: if True draws the axis of the reference R'
   zaxis: if True draws the z' axis
   radius: radius of the circle
   steps: number of steps
   thickness: thickness of the curve
   name: name of the curve
   color: color of the curve
   change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}
def draw_components(self, vector=None, color='Cyan', name='Components', scale=0.0075)
   Draws the components of the the vector 'vector' in the reference given by self.origin, self.rotation and the basis self.base
   Parameters
   vector: the vector
   color: color of the lines of components
   name: name of the object
   scale: scale of the lines
def draw_cone(self, a=1.0, xmin=0.0, xmax=5.0, steps=50, scale=[1, 1, 1], half=False,
                color='AzureBlueDark', name='Cone', opacity=1.0, thickness=0.05)
   Draws a cone from the line z = a*x in the XZ plane
   Parameters
   a: slope of the line
   xmin: minimum value of x
   xmax: maximum value of x
   steps: numbers of steps to draw the parabola
```

scale: scaling factors in the X, Y and Z directions

half: if True, draws half cone color: color of the surface

name: name of the surface opacity: opacity of the surface thickness: thickness of the surface def draw\_cube(self, origin=None, scale=[1, 1, 1], scalelines=0.05, vectors=False, color='Blue', linecolor='Red', vectorcolor='Black', name='Parallelepiped', opacity=1.0, thickness=0.0) Draws a rectangular parallelepiped **Parameters** origin: center of the parallelepiped scale: scale of the sides of the parallelepiped scalelines: scale of the edges of the parallelepiped vectors: if True, draws vectors from the origin to the vertices color: color of the parallelepiped linecolor: color of the edges vectorcolor: color of the vectors name: name of the parallelepiped opacity: opacity of the parallelepiped thickness: thickness of the parallelepiped def draw\_curve(self, fun=None, tmin=0.0, tmax=1.0, steps=25, thickness=0.01, name='Curve', color='White', axis=False, zaxis=True, o=Vector((0.0, 0.0, 0.0)), u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0))) Draws a curve in a reference R' determined by the origin o and basis {v1, v2, v3} constructed from u1 and u2 **Parameters** fun: the parametric function tmin: minimum value of the parameter tmax: maximum value of the parameter steps: number of steps thickness: thickness of the curve name: name of the curve color: color of the curve axis: if True draws the axis of the reference R' zaxis: if True draws the z' axis o: origin of the reference R' u1, u2: vectors to construct the basis {v1, v2, v3} def draw\_ellipse(self, center=[0, 0, 0], u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0)), a=1, b=1, axis=False, zaxis=False, steps=25, thickness=0.01, name='Ellipse', color='White', change=False) Draws an ellipse of center 'center' and semi-axes a and b in the plane determined by vectors u1 and u2 **Parameters** center: center of the ellipse u1, u2: vectors to construct the basis {v1, v2, v3} a, b: semi-axes of the ellipse

```
axis: if True draws the axis of the reference R'
   zaxis: if True draws the z' axis
   steps: number of steps
   thickness: thickness of the curve
   name: name of the curve
   color: color of the curve
   change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}
def draw ellipsoid(self, radius=5.0, scale=[1.2, 1.8, 0.8], color='AzureBlueDark', name='Ellipsoid',
                      opacity=1.0, thickness=0.05)
   Draws en ellipsoid
   Parameters
   radius: radius of the sphere
   scale: scaling factors in the X, Y and Z directions
   color: color of the surface
   name: name of the surface
   opacity: opacity of the surface
   thickness: thickness of the surface
def draw_elliptic_cylinder(self, a=8.0, b=5.0, amin=0.0, amax=6.283185307179586, length=20, steps=200,
                               scale=[1, 1, 1], color='AzureBlueDark', name='EllipticCylinder', opacity=1.0,
                               thickness=0.05)
   Draws an eliptic cylinder from the ellipse x = a\cos(t)y = b\sin(t) in the XY plane
   Parameters
   a, b: coefficients of the ellipsw
   amin: minimum value of the angle t
   amax: maximum value of the angle t
   length: length in the Z direction
   steps: numbers of steps to draw the parabola
   scale: scaling factors in the X, Y and Z directions
   color: color of the surface
   name: name of the surface
   opacity: opacity of the surface
   thickness: thickness of the surface
def draw_elliptic_paraboloid(self, a=0.5, xmin=0.0, xmax=3.0, steps=50, scale=[1, 1, 1],
                                 color='AzureBlueDark', name='EllipticParaboloid', opacity=1.0,
                                 thickness=0.05)
   Draws an elliptic paraboloid from the parabola z=a*t^2
   Parameters
   a: coefficient of the parabola
   xmin: minimum value of x
   xmax: maximum value of x
```

steps: numbers of steps to draw the parabola

scale: scaling factors in the X, Y and Z directions color: color of the surface name: name of the surface opacity: opacity of the surface thickness: thickness of the surface def draw frenet curve(self, fun=None, var=None, tmin=0.0, tmax=1.0, radius=0.1, steps=25, thickness=0.01, name='Curve', color='White', point=True, tangent=False, acceleration=False, normal=False, osculator=False, frenet=False, units=False, sizex=8, sizey=8, axis=10) Draws a curve and differents elements related to the curve **Parameters** fun: the parametric function var = parameter variable of the function fun tmin: minimum value of the parameter tmax: maximum value of the parameter radius: radius of the point steps: number of steps frames: increment of the frame set thickness: thickness of the curve name: name of the curve color: color of the curve point: if True draw a point along the curve tangent: if True draw the tangent vector along the curve acceleration: if True draw the acceleration vector along the curve normal: if True draw the normal vector along the curve osculator: if True draw the osculating plane along the curve frenet: if True draw the Frenet trihedron along the curve units: if True normalize the tangent and normal vectors sizex, sizey: sizes of the osculating plane axis: length of the coordinate axis def draw function(self, f=None, xmin=-3, xmax=3, xsteps=64, ymin=-3, ymax=3, ysteps=64, thickness=0.02, opacity=1.0, pmax=10, name='Function', color='AzureBlueDark', axis=False, o=Vector((0.0, 0.0, 0.0)), u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0))) Draws a function of two variables f(x,y) i the reference  $R' = \{0, v1, v2, v3\}$ **Parameters** f: the function of two variables f(x,y)xmin: minimum value of x xmax: maximum value of x

xsteps: steps in the x direction

ymin: minimum value of y

ymax: maximum value of y

ysteps: steps in the x direction

```
opacity: opacity of the surface
   pmax: the axis are drawn between -pmax and pmax
   name: name of the surface
   color: color of the surface
   axis: if True the axis of the reference R' are drawn
   o: origin of the reference R'
   u1, u2: vectors to construct the basis {v1, v2, v3}
def draw_hyperbole(self, center=[0, 0, 0], u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0)), a=1,
                     b=1, ymax=3.0, axis=False, zaxis=False, steps=25, thickness=0.01, name='Hyperbole',
                     color='White', change=False)
   Draws an hyperbole of center 'center' and semi-axes a and b in the plane determined by vectors u1 and u2
   Parameters
   center: center of the hyperbole
   u1, u2: vectors to construct the basis {v1, v2, v3}
   a, b: semi-axes of the hyperbole
   ymax: maximum value of the y'
   axis: if True draws the axis of the reference R'
   zaxis: if True draws the z' axis
   steps: number of steps
   thickness: thickness of the curve
   name: name of the curve
   color: color of the curve
   change: if True, set the reference self.origin, self.base to {o; v1, v2, v3}
def draw_hyperbolic_cylinder(self, a=1.0, b=4.0, xmin=2.0, xmax=6.0, length=20, steps=50, scale=[1, 1,
                                 1], color='AzureBlueDark', name='HyperbolicCylinder', opacity=1.0,
                                 thickness=0.05)
   Draws an hyperbolic cylinder from the hyperbole y = a * sqrt(x**2 - b) in the XY plane
   Parameters
   a, b: coefficients of the hyperbole
   xmin: minimum value of x
   xmax: maximum value of x
   length: length in the Z direction
   steps: numbers of steps to draw the parabola
   scale: scaling factors in the X, Y and Z directions
   color: color of the surface
   name: name of the surface
   opacity: opacity of the surface
   thickness: thickness of the surface
def draw_hyperbolic_paraboloid(self, a=0.2, b=0.4, xmax=10.0, ymax=10.0, steps=64, scale=[1, 1, 1],
                                   color='AzureBlueDark', name='HyperbolicParaboloid', opacity=1.0,
                                   thickness=0.05)
```

thickness: thickness of the surface

Draws an hyperbolic paraboloid with equation  $z = ax^2 - by^2$ 

#### **Parameters**

```
a, b: coefficients of the parabolic hyperboloid
```

xmax: maximum value of x

ymax: maxim value y

steps: numbers of steps to draw the parabola

scale: scaling factors in the X, Y and Z directions

color: color of the surface

name: name of the surface

opacity: opacity of the surface

thickness: thickness of the surface

# def draw\_line(self, start=[1, 1, 1], end=[10, 10, 10], scale=0.05, name='Line', color='Black')

Draws a line from the point start to the point end. The reference given by self.origin, self.rotation and the basis self.base is used

# **Parameters**

start: starting point of the line

end: ending point of the line

scale: scale of the cylinder

name: name of the object

color: color of the vector

# def draw\_mesh(self, mesh=None, name='Mesh', color='Blue', opacity=1)

Draws a mesh. This function is used by other functions

# **Parameters**

mesh: the mesh to be drawn

name: name of the mesh

color: color of the mesh

opacity: opacity of the mesh

Draws a one sheet hyperboloid from the hyperbole  $z = pm a*sqrt(x^2-b)$  in the XZ plane

# **Parameters**

a, b: coefficients of the hyperbole

xmin: minimum value of x

xmax: maximum value of x

steps: numbers of steps to draw the parabola

scale: scaling factors in the X, Y and Z directions

color: color of the surface

name: name of the surface

opacity: opacity of the surface

thickness: thickness of the surface

color: color of the parallelepiped

linecolor: color of the edges

```
def draw_parabola(self, vertex=[0, 0, 0], u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0)), a=1,
                    xmax=3.0, axis=False, zaxis=False, steps=25, thickness=0.01, name='Parabola',
                    color='White', change=False)
   Draws a parabola of vertex 'vertex' of equation y'=ax'^2 in the reference {vertex; v1, v2, v3} determined by vectors u1 and u2
   Parameters
  vertex: vertex of the parabola
   u1, u2: vectors to construct the basis {v1, v2, v3}
  a: coefficient of the parabola
  xmax: maximum value of x'
   axis: if True draws the axis of the reference R'
   zaxis: if True draws the z' axis
  steps: number of steps
   thickness: thickness of the curve
   name: name of the curve
   color: color of the curve
  change: if True, set the reference self.orifin, self.base to {o; v1, v2, v3}
def draw parabolic cylinder(self, p=0.25, xmin=0.0, xmax=6.0, length=20, steps=50, scale=[1, 1, 1],
                                color='AzureBlueDark', name='ParabolicCylinder', opacity=1.0, thickness=0.05)
   Draws a parabolic cylinder from the parabola z=p*x^2 in the XZ plane
   Parameters
   p: coefficients of the parabola
  xmin: minimum value of x
  xmax: maximum value of x
   length: length in the Y direction
  steps: numbers of steps to draw the parabola
  scale: scaling factors in the X, Y and Z directions
   color: color of the surface
   name: name of the surface
   opacity: opacity of the surface
   thickness: thickness of the surface
def draw_parallelepiped(self, origin=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], u3=[0, 0, 1],
                           scalelines=0.025, color='AzureBlueDark', linecolor='OrangeObscureDull',
                           name='Parallelepiped', opacity=1.0, thickness=0.0)
   Draws a parallelepiped
   Parameters
   origin: base vertex of the parallelepiped
   u1, u2, u3: vectors that gives the edges
  scalelines: scale of the edges of the parallelepiped
```

name: name of the parallelepiped opacity: opacity of the parallelepiped

thickness: thickness of the parallelepiped

Draws a parallelogram

#### **Parameters**

origin: base vertex of the parallelogram

u1, u2: vectors that gives the edges

scalelines: scale of the edges of the parallelogram

color: color of the parallelogram

linecolor: color of the edges

name: name of the parallelogram

opacity: opacity of the parallelogram

thickness: thickness of the parallelogram

Draws a plane with normal vector or base vectors. It passes through the point self.origin. Only normal or base can be not None

#### **Parameters**

normal: normal vector to the plane

base: list of two independent vectors

sizex: x-size of the plane

sizey: y-size of the plane

color: color of the plane

name: name of the plane

opacity: opacity of the plane

thickness: thickness of the plane

Draws a plane with normal vector or base vectors. It passes through the point origin. Only normal or base can be not None

# **Parameters**

origin: a point in the plane

normal: normal vector to the plane

base: list of two independent vectors

sizex: x-size of the plane

sizey: y-size of the plane

vectors: if True, draw the generators of the plane

scalelines: scale of the lines limiting the plane

```
scalevector: scale of the generators
  color: color of the plane
   linecolor: color of the lines limiting the plane
  vectorcolor: color of the generators
   name: name of the plane
  opacity: opacity of the plane
   thickness: thickness of the plane
def draw_point(self, radius=0.1, location=(0, 0, 0), name='Point', color='Black', opacity=1.0)
   Draws a point (in the reference self.origin, self.base)
   Parameters
   radius: radius of the point
  location: location of the point
  name: name of the point
  color: color of the point
  opacity: opacity of the point
def draw points(self, points=[], name='Points', color='Blue', opacity=1)
   Draws a list of points
   Parameters
   points: list of points
   name: name of the list of points
  color: color of the points
  opacity: opacity of the points
def draw_polygon(self, origin=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], points=[[0, 0], [1, 0], [0, 1]],
                  scalelines=0.075, color='AzureBlueDark', linecolor='OrangeObscureDull', name='Polygon',
                  opacity=1.0, thickness=0.0, vectors=None, scalevectors=0.01)
  Draws a polygon
   Parameters
  origin: base vertex of the polygon
   u1, u2: base vectors for the polygon
   points: list of coordinates of points. The coordinates are taken in the reference {origin; u1, u2}
  scalelines: scale of the edges of the polygon
  color: color of the polygon
   linecolor: color of the edges
   name: name of the polygon
  opacity: opacity of the polygon
  thickness: thickness of the polygon
color='AzureBlueDark', linecolor='OrangeObscureDull', name='Pyramid', opacity=1.0,
                  thickness=0.0)
```

Draws a pyramid

```
origin: base vertex of the pyramid
   u1, u2, u3: vectors that gives the edges
   scalelines: scale of the edges of the pyramid
   color: color of the pyramid
   linecolor: color of the edges
   name: name of the pyramid
   opacity: opacity of the pyramid
   thickness: thickness of the pyramid
def\ draw\_regular\_polygon(self,\ origin=[0,\ 0,\ 0],\ u1=[1,\ 0,\ 0],\ u2=[0,\ 1,\ 0],\ vertexs=5,\ radius=1,
                            scalelines=0.075, color='AzureBlueDark', linecolor='OrangeObscureDull',
                            name='RegularPolygon', opacity=1.0, thickness=0.0, vectors=None)
   Draws a regular polygon
   Parameters
   origin: base vertex of the polygon
   u1, u2: base vectors for the polygon
   vertexs: number of vertices of the polygon
   radius: radius of the polygon
   scalelines: scale of the edges of the polygon
   color: color of the polygon
   linecolor: color of the edges
   name: name of the polygon
   opacity: opacity of the polygon
   thickness: thickness of the polygon
def draw_simple_curve(self, fun=None, tmin=0.0, tmax=1.0, steps=25, thickness=0.02, color='White',
                        name='Curve')
   Draws a parametric curve
   Parameters
   fun: the parametric function
   tmin: minimum value of the parameter
   tmax: maximum value of the parameter
   steps: number of steps
   thickness: thickness of the curve
   color: color of the curve
   name: name of the curve
def draw_surface(self, eq=None, umin=-1, umax=1, usteps=64, vmin=-1, vmax=1, vsteps=64, thickness=0.02,
                   opacity=1.0, pmax=10, name='Surface', color='AzureBlueDark', axis=False, o=Vector((0.0,
                   0.0, 0.0), u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0)), wrap_u=False,
                   wrap v=False, close v=False)
```

Parameters

Draws a parametric surface in the reference R'

**Parameters** 

```
eq: parametric equacion f(u,v)
   umin: minimum value of u
   umax: maximum value of u
   usteps: steps in the u direction
   vmin: minimum value of v
   vmax: maximum value of v
   vsteps: steps in the v direction
   thickness: thickness of the surface
   opacity: opacity of the surface
   color: color of the surface
   pmax: the principal axis are drawn between -cmax and cmax
   name: name of the surface
   color: color of the surface
   axis: if True draw the axis of the reference {o, v1, v2, v3}
   o: origin of the reference R'
   u1, u2: vectors to construct the basis {v1, v2, v3}
   scale: scale coefficients
   wrap_u: wrap the u coordinate
   wrap_v: wrap the u coordinate
   close_v: close the v coordinate
def draw_tetrahedron(self, origin=[0, 0, 0], u1=[2, 0, 0], u2=[1.0000000000000000, 1.7320508075688772,
                        0], u3=[1.0, 0.5773502691896257, 2], scalelines=0.025, color='AzureBlueDark',
                        linecolor='OrangeObscureDull', name='Tetrahedron', opacity=1.0, thickness=0.0)
   Draws a tetrahedron
   Parameters
   origin: base vertex of the tetrahedron
   u1, u2, u3: vectors that gives the edges
   scalelines: scale of the edges of the tetrahedron
   color: color of the tetrahedron
   linecolor: color of the edges
   name: name of the tetrahedron
   opacity: opacity of the tetrahedron
   thickness: thickness of the tetrahedron
def draw_triangle(self, origin=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], points=[[0, 0], [1, 0], [0, 1]],
                    scalelines=0.075, color='AzureBlueDark', linecolor='OrangeObscureDull',
                    name='Triangle', opacity=1.0, thickness=0.0)
   Draws a triangle. It's a polygon with three vertices
   Parameters
   origin: base vertex of the triangle
   u1, u2: base vectors for the triangle
   points: list of coordinates of points. The coordinates are taken in the reference {origin; u1, u2}
```

```
scalelines: scale of the edges of the triangle
   color: color of the triangle
   linecolor: color of the edges
   name: name of the triangle
   opacity: opacity of the triangle
   thickness: thickness of the triangle
def draw two sheets hyperboloid(self, a=2.0, b=1.0, xmin=0.0, xmax=5.0, steps=50, scale=[1, 1, 1],
                                    color='AzureBlueDark', name='HyperboloidTwoSheets', opacity=1.0,
                                     thickness=0.05)
   Draws a two sheet hyperboloid from the hyperbole z = pm a * math.sqrt(x**2+b) in the XZ plane
   Parameters
   a, b: coefficients of the hyperbole
   xmin: minimum value of x
   xmax: maximum value of x
   steps: numbers of steps to draw the parabola
   scale: scaling factors in the X, Y and Z directions
   color: color of the surface
   name: name of the surface
   opacity: opacity of the surface
   thickness: thickness of the surface
def draw_vector(self, vector=None, canonica=False, color='Black', scale=0.05, arrow=True,
                  head_height=0.15, axis=0, name='Vector', positive=True)
   Draw the vector with components 'vector'
   Parameters
   vector: components of the vector
   canonica: if True, the components are in the canonical basis, else they are in the basis self.base. Finally, self.rotation is
   applied
   color: color of the vector
   scale: scale of the cylinder
   arrow: if True draws the vector itself
   head_height: height of the head of the vector
   head_scale: scale of the head of the vector
   axis: if not zero, draw also the line generated by the vector
   positive: if axis is not zero and positive is True, draw only the positive part of the line generated by the vector
def draw vector field(self, f=None, xmin=-3, xmax=3, xsteps=8, ymin=-3, ymax=3, ysteps=8, zmin=-3,
                         zmax=3, zsteps=8, name='Vector Field', color='Red', scale=0.02, head_height=0.05)
   Draws a vector field
   Parameters
   f: the vector field
   xmin: minimum value of x
   xmax: maximum value of x
```

```
xsteps: steps in the x direction
   ymin: minimum value of y
   ymax: maximum value of y
   ysteps: steps in the y direction
   zmin: minimum value of z
   zmax: maximum value of z
   zsteps: steps in the z direction
   name: name of the vector field
   color: color of the vector field
   scale: scale of the vectors
   head_height: head height of the vectors
def draw_vectors(self, vectors=[], canonica=False, color='Black', scale=0.05, head_height=0.2,
                    name='Vectors', axis=0)
   Draws a list of vectors.
   Parameters
   vectors: list of vectors
   anonica: if True, the the vectors are expressed in the canonical basis.
   color: color of the vectors
   scale: scale of the cylinder
   head_height: height of the head of the vector
   axis: if not zero, draw also the line generated by every vector
def ellipse(self, center=Vector((0.0, 0.0, 0.0)), a=8, b=5, canonica=True)
   Draws the ellipse of equation (x-x0)^2/a^2 + (y-y0)^2/b^2 == 1
   Parameters
   centre: center of the ellipse
   a, b: semiaxis of the ellipse
   canonica: if True, draws the x and y axis
def ellipsoid(self, o=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], a2=1, b2=1, c2=1, principal=True,
                canonica=True, color='AzureBlueDark', name='Ellipsoid', cmax=15, pmax=15, thickness=0.02,
                opacity=1.0)
   Draws an ellipsoid
   Parameters
   o: center of the ellipsoid
   u1, u2: the principal basis \{v1, v2, v3\} is constructed from this vectors in the following way v1 = u1 v2 = u2 - u2. project(v1)
   v1.normalize() v2.normalize() v3 = v1.cross(v2)
   a2, b2, c2: squares of semi-axes of the ellipsoid. The equation is x'^2/a^2 + y'^2/b^2 + z'^2/c^2 = 1
   principal: if True, the principal axis are drawn
   canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the ellipsoid
   cmax: the canonical axis are drawn between -cmax and cmax
```

pmax: the principal axis are drawn between -pmax and pmax thickness: thickness of the ellipsoid opacity: opaccity of the ellipsoid def ellipsoide(self, o=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], a2=1, b2=1, c2=1, principal=True, canonica=True, color='AzureBlueDark', name='Ellipsoid', cmax=15, pmax=15, thickness=0.02, opacity=1.0) Draws an ellipsoid **Parameters** o: center of the ellipsoid u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors in the following way v1 = u1 v2 = u2 - u2.project(v1) v1.normalize() v2.normalize() v3 = v1.cross(v2) a2, b2, c2: squares of semi-axes of the ellipsoid. The equation is  $x'^2/a^2 + y'^2/b^2 + z'^2/c^2 = 1$ principal: if True, the principal axis are drawn canonica: if True, the canonical axis are drawn color: color of the surface name: name of the ellipsoid cmax: the canonical axis are drawn between -cmax and cmax pmax: the principal axis are drawn between -pmax and pmax thickness: thickness of the ellipsoid opacity: opaccity of the ellipsoid def ellipsoide revolucio(self, a=12, b=8, direccio='Z', punt=None) Draws an animation showing an ellipsoid of revolution a, b: semiaxis of the initial ellipse direccio: 'X', the initial ellipse is in the plane XZ and rotates around the X axis 'Y', the initial ellipse is in the plane YZ and rotates around the Y axis 'Z', the initial ellipse is in the plane ZX and rotates around the Z axis punt: if it's a value between  $\theta$  and pi, the animation shows a rotating point canonica=True, color='AzureBlueDark', name='EllipticCylinder', zmax=20, cmax=15, pmax=15, thickness=0.02, opacity=1.0, change=False) Draws an elliptic cylinder **Parameters** o: center of the elliptic cylinder u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors a2, b2: squares of semi-axes of the elliptic cylinder. The equation is  $x'^2/a^2 + y'^2/b^2 = 1$ principal: if True, the principal axis are drawn canonica: if True, the canonical axis are drawn color: color of the surface name: name of the elliptic cylinder zmax: the elliptic cylinder is drawn between -zmax and zmax cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -cmax and cmax

thickness: thickness of the elliptic cylinder opacity: opacity of the elliptic cylinder def elliptic\_paraboloid(self, o=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], a2=1, b2=1, principal=True, canonica=True, color='AzureBlueDark', name='EllipticParaboloid', xmax=None, cmax=15, pmax=15, thickness=0.02, opacity=1.0) Draws an elliptic paraboloid **Parameters** o: vertex of the elliptic paraboloid u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors a2, b2: squares of semi-axes of the elliptic paraboloid. The equation is  $z = x'^2/a^2 + y'^2/b^2$ principal: if True, the principal axis are drawn canonica: if True, the canonical axis are drawn color: color of the surface name: name of the elliptic paraboloid xmax: maximum value of the coordinate x cmax: the canonical axis are drawn between -cmax and cmax pmax: the principal axis are drawn between -cmax and cmax thickness: thickness of the elliptic paraboloid opacity: opacity of the elliptic paraboloid def esfera(self, centre=Vector((0.0, 0.0, 0.0)), radi=10, cmax=20) Draws a sphere **Parametre** centre: center of the sphere radi: radius of the sphere cmax: maximum values of the x, y and z coordinates def esfera\_cilindre\_elliptic(self, radi=10, x0=5, a=5, b=5) Draws an sphere centered at (0,0,0), an elliptic cylinder and their intersection **Parameters** radi: radius of the sphere x0: (x0,0,0) is the center of the ellipse in the plain XY a, b: semiaxis of this ellipse def gir\_poligon(self, centre=Vector((0.0, 0.0, 0.0)), costats=6, origen=Vector((0.0, 0.0, 0.0)), radi=8) Draws an animation of the rotation around a point of a polygon in the plane XY **Parameters** centre: center of the polygon costats: sides of the polygon

 $\label{eq:continuous} \mbox{def hiperbola(self, center=Vector((0.0, 0.0, 0.0)), a=8, b=5, negatiu=False, canonica=True)} \\$ 

origen: center of the rotation

radi: radius of the polygon

Draws the hyperbole of equation  $(x-x0)^2/a^2 - (y-y0)^2/b^2 == 1$  (or -1)

#### **Parameters**

centre: center of the hyperbole

a, b: semiaxis of the hyperbole

canonica: if True, draws the x and y axis

negatiu: if True, draws the hyperbole  $(x-x0)^2/a^2 - (y-y0)^2/b^2 == -1$ 

Draws a two sheets hyperboloid

# **Parameters**

o: center of the hyperboloid

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors

a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is  $x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = -1$ 

principal: if True, the principal axis are drawn

canonica: if True, the canonical axis are drawn

color: color of the surface

name: name of the hyperboloid

xmax: maximum value of the x coordinate

cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -cmax and cmax

thickness: thickness of the hyperboloid

opacity: opacity of the hyperboloid

def hiperboloide\_dues\_fulles\_revolucio(self, a=3, b=2, pmax=8, direccio='Z', punt=None)

Draws an animation showing a two sheet hyperboloid of revolution a, b: semiaxis of the initial hyperbole

```
\ensuremath{\mathsf{pmax}}\xspace : \ensuremath{\mathsf{maximum}}\xspace value of the independent variable
```

direccio: 'X', the initial hyperbole is in the plane YX and rotates around the X axis
'Y', the initial hyperbole is in the plane ZY and rotates around the Y axis
'Z', the initial hyperbole is in the plane XZ and rotates around the Z axis

punt: if it's a value between  $\theta$  and pi, the animation shows a rotating point

Draws an one sheet hyperboloid

# **Parameters**

o: center of the hyperboloid

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors

a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is  $x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 1$ 

```
principal: if True, the principal axis are drawn
```

canonica: if True, the canonical axis are drawn

color: color of the surface

name: name of the hyperboloid

xmax: maximum value of the x coordinate

cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -cmax and cmax

thickness: thickness of the hyperboloid

opacity: opacity of the hyperboloid

#### def hiperboloide\_una\_fulla\_revolucio(self, a=3, b=2, pmax=8, direccio='Z', punt=None)

Draws an animation showing an one sheet hyperboloid of revolution a, b: semiaxis of the initial hyperbole

pmax: maximum value of the independent variable

direccio: 'X', the initial hyperbole is in the plane XZ and rotates around the X axis
'Y', the initial hyperbole is in the plane YX and rotates around the Y axis
'Z', the initial hyperbole is in the plane ZX and rotates around the Z axis

punt: if it's a value between 0 and pi, the animation shows a rotating point

Draws an hyperbolic cylinder

#### **Parameters**

o: center of the hyperbolic cylinder

u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors

a2, b2: squares of semi-axes of the hyperbolic cylinder. The equation is  $x'^2/a^2 - y'^2/b^2 = 1$ 

principal: if True, the principal axis are drawn

canonica: if True, the canonical axis are drawn

color: color of the surface

name: name of the hyperbolic cylinder

xmax: maximum value of the x coordinate

zmax: the hyperbolic cylinder is drawn between -zmax and zmax

cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -cmax and cmax

thickness: thickness of the hyperbolic cylinder

opacity: opacity of the hyperbolic cylinder

Draws an hyperbolic paraboloid

#### **Parameters**

o: vertex of the hyperbolic paraboloid

```
u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
   a2, b2: squares of semi-axes of the hyperbolic paraboloid. The equation is z = x'^2/a^2 - y'^2/b^2
   principal: if True, the principal axis are drawn
   canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the elliptic paraboloid
   xmax: maximum value of the coordinate x
   ymax: maximum value of the coordinate y
   cmax: the canonical axis are drawn between -cmax and cmax
   pmax: the principal axis are drawn between -cmax and cmax
   thickness: thickness of the hyperbolic paraboloid
   opacity: opacity of the hyperbolic paraboloid
def join(self, list)
   Joins a list of objects
   Parameters
   list: list of objects
def moviment_helicoidal_ortoedre(self, centre=Vector((0.0, 0.0, 0.0)), costats=Vector((3.0, 4.0, 2.0)),
                                      opacity=1, origen=Vector((4.0, 3.0, 0.0)), eix='Z', translacio=0.0)
   Draws an animation of the helical motion of an orthohedron around an affine line
   Parameters
   centre: center of the orthohedron
   costats: half sides of the orthohedron
   origen: point of the affine line
   eix: axis of rotation
   opacity: opacity of the orthohedron
   translation: translation of the helical motion (distance by frame) if translation = 0.0, it's a rotation motion
def one_sheet_hyperboloid(self, o=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], a2=1, b2=1, c2=1,
                              principal=True, canonica=True, color='AzureBlueDark',
                              name='OneSheetHyperboloid', xmax=None, cmax=15, pmax=15, thickness=0.02,
                              opacity=1.0)
   Draws an one sheet hyperboloid
   Parameters
   o: center of the hyperboloid
   u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
   a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = 1
   principal: if True, the principal axis are drawn
   canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the hyperboloid
   xmax: maximum value of the x coordinate
   cmax: the canonical axis are drawn between -cmax and cmax
```

```
pmax: the principal axis are drawn between -cmax and cmax
   thickness: thickness of the hyperboloid
  opacity: opacity of the hyperboloid
def parabola(self, vertex=Vector((0.0, 0.0, 0.0)), p=5, xmax=15, eixos='XY', canonica=True)
   Draws the parabola of equation y - y0 = (x-x0)^2/(2p) or x - x0 = (y-y0)^2/(2p)
   Parameters
  vertex: vertex of the parabola
   p: parameter of the parabola
   pmax: maximum value of the independent variable
  eixos: 'XY', draws y - y0 = (x-x0)^2/(2p) 'YX', draws x - x0 = (y-y0)^2/(2p)
  canonica: if True, draws the x and y axis
color='AzureBlueDark', name='ParabolicCylinder', xmax=None, ymax=30, cmax=20,
                         pmax=20, thickness=0.02, opacity=1.0)
   Draws an hyperbolic paraboloid
   Parameters
  o: vertex of the hyperbolic paraboloid
   u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  a: coefficient of the intial parabola
   principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the elliptic paraboloid
  xmax: maximum value of the coordinate x
   ymax: maximum value of the coordinate y
   cmax: the canonical axis are drawn between -cmax and cmax
   pmax: the principal axis are drawn between -cmax and cmax
   thickness: thickness of the hyperbolic paraboloid
  opacity: opacity of the hyperbolic paraboloid
def paraboloide_elliptic(self, o=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], a2=1, b2=1, principal=True,
                           canonica=True, color='AzureBlueDark', name='EllipticParaboloid', xmax=None,
                           cmax=15, pmax=15, thickness=0.02, opacity=1.0)
   Draws an elliptic paraboloid
   Parameters
   o: vertex of the elliptic paraboloid
   u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
  a2, b2: squares of semi-axes of the elliptic paraboloid. The equation is z = x'^2/a^2 + y'^2/b^2
   principal: if True, the principal axis are drawn
  canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the elliptic paraboloid
```

xmax: maximum value of the coordinate x cmax: the canonical axis are drawn between -cmax and cmax pmax: the principal axis are drawn between -cmax and cmax thickness: thickness of the elliptic paraboloid opacity: opacity of the elliptic paraboloid def paraboloide elliptic revolucio(self, a=0.5, pmax=5, direccio='Z', punt=None) Draws an animation showing an elliptic paraboloid of revolution a: The constant of the initial parabola pmax: maximum value of the independent variable direccio: 'X', the initial parabola is in the plane YX and rotates around the X axis 'Y', the initial parabola is in the plane ZY and rotates around the Y axis 'Z', the initial parabola is in the plane XZ and rotates around the Z axis punt: if it's a value between -pmax and pmax, the animation shows a rotating point def paraboloide\_hiperbolic(self, o=[0, 0, 0], u1=[1, 0, 0], u2=[0, 1, 0], a2=1, b2=1, principal=True, canonica=True, color='AzureBlueDark', name='HyperbolicParaboloid', xmax=None, ymax=None, cmax=15, pmax=15, thickness=0.02, opacity=1.0) Draws an hyperbolic paraboloid **Parameters** o: vertex of the hyperbolic paraboloid u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors a2, b2: squares of semi-axes of the hyperbolic paraboloid. The equation is  $z = x'^2/a^2 - y'^2/b^2$ principal: if True, the principal axis are drawn canonica: if True, the canonical axis are drawn color: color of the surface name: name of the elliptic paraboloid xmax: maximum value of the coordinate x ymax: maximum value of the coordinate y cmax: the canonical axis are drawn between -cmax and cmax pmax: the principal axis are drawn between -cmax and cmax thickness: thickness of the hyperbolic paraboloid opacity: opacity of the hyperbolic paraboloid def paraboloide\_hiperbolic\_simple(self, a=3, b=4, xmax=12, ymax=12) Draws the hyperbolic paraboloid of equation  $z = x^2/a^2 - y^2/b^2$ **Parameters** a, b: constants the defines he hyperbolic paraboloid xmax, ymax: maximun values of the x and y coordinates

def pla\_afi(self, punt=Vector((0.0, 0.0, 0.0)), v1=Vector((3.0, 2.0, 1.0)), v2=Vector((1.0, -2.0, 0.5)),

canonica=False, name='Pla afí', length=15, color='Cyan', sizex=25, sizey=20, opacity=0.8,

Draws the affine plane generated by two vectors passing through a point

elements=True)

```
punt: point of the plane
  v1, v2: generators of the plane
  canonica: if True, draws the x, y and z axis
   name: name of the affine plane
  length: length of the axis x, y and z
  color: color of the plane
  sizex, sizey: size of the plane
  opacicity: opacity of the plane
def pla_vectorial(self, v1=Vector((3.0, 2.0, 1.0)), v2=Vector((1.0, -2.0, 0.5)), canonica=False,
                   length=15, color='Cyan', sizex=25, sizey=20, opacity=0.8)
   Draws the plane generated by two vectors
   Parameters
  v1, v2: generators of the plane
  canonica: if True, draws the x, y and z axis
  length: length of the axis x, y and z
  color: color of the plane
  sizex, sizey: size of the plane
  opacicity: opacity of the plane
-3.0)), v1=Vector((3.0, -1.0, 1.0)), v2=Vector((1.0, 0.5, 0.5)),
                                            radi=0.15, sizex=35, sizey=30, canonica=True)
   Draws the orthogonal projection and the symmetric of a point with respect an affine plane
   Parameters
   punt: the initial point
  p0: point of the affine plane
  v1, v2: generators of the plane
  radi: radius of the points
  sizex, sizey: sizes of the affine plane
  canonica: if True, draws the x, y and z axis
def projeccio_ortogonal_simetric_pla_vectorial(self, vector=Vector((7.0, -1.0, 12.0)), v1=Vector((3.0,
                                                  -1.0, 1.0)), v2=Vector((1.0, 0.5, 0.5)), canonica=True)
   Draws the otoghonal projection and the symmetric of a vector with respecte a plane
   Parameters
  vector: the initial vector
  v1, v2: generators of the plane
  canonica: if True, draws the x, y and z axis
def projeccio_ortogonal_simetric_recta_afi(self, punt=Vector((6.0, -5.0, 8.0)), p0=Vector((3.0, -2.0,
                                              -3.0)), v1=Vector((3.0, -1.0, 1.0)), scale=0.1, radi=0.15,
                                              canonica=True)
```

Draws the orthogonal projection and the symmetric of a point with respect an affine line

**Parameters** 

```
punt: the initial point
   p0: point of the affine line
   v1: generator of the line
   radi: radius of the points
   canonica: if True, draws the x, y and z axis
def projeccio_ortogonal_simetric_recta_vectorial(self, vector=Vector((7.0, -1.0, 12.0)), v1=Vector((3.0,
                                                      -1.0, 1.0)), canonica=True)
   Draws the otoghonal projection and the symmetric of a vector with respecte a line
   Parameters
   vector: the initial vector
   v1: generator of the line
   canonica: if True, draws the x, y and z axis
def punt_referencia_canonica(self, punt=Vector((-4.0, 7.0, 6.0)), radius=0.1, length=12, name='Punt p',
                                coordenades=True)
   Draws a point expressed in the canonical reference
   Parameters
   punt: the point to draw
   length: length of the axis
   name: name of the point
   components: if True draws lines representing the coordinates
def punt_referencia_no_canonica(self, punt=Vector((5.0, 6.0, -5.0)), origin=Vector((-2.0, 3.0, 3.0)),
                                   u1=Vector((-0.333333333432674408, -0.6666666865348816,
                                   0.6666666865348816)), u2=Vector((0.6666666865348816, 0.33333333432674408,
                                   0.666666865348816)), u3=Vector((-0.666666865348816, 0.6666666865348816,
                                   0.333333432674408)), length=12, scale=0.04, radius=0.1, name='Punt p')
   Draws a point expressed in the reference {0,u1,u2,u3} with origin in the point origin and sets the default origin and default
   base to them
   Parameters
   punt: point to draw
   origin: origin of the reference
   u1, u2, u3: vectors of the base
   length: length of the axis
   scale: scale of the axis
   name: name of the reference
def referencia_canonica(self, origin=Vector((0.0, 0.0, 0.0)), length=15, scale=0.04, zaxis=True,
                          name='Referència canònica')
   Draws the canonical reference
   Parameters
   origin: point where to represent the base
```

**Parameters** 

length: length of the axis

```
scale: scale of the cylinder
       zaxis: if False the z axis is not drawn
       name: name of the object
 \label{eq:def-def-def-def-def-def} {\tt def-referencia\_no\_canonica(self, origin=Vector((0.0, 0.0, 0.0)), u1=Vector((1.0, -1.0, 0.0)
                                                                        u2=Vector((-0.5, 1.0, 0.5)), u3=Vector((-1.0, 0.0, 1.0)), length=12,
                                                                        scale=0.04, name="Referència R'")
       Draws the reference {o;u1,u2,u3} with origin in the point origin and sets the default origin and default base to them
       Parameters
       origin: origin of the reference
       u1, u2, u3: vectors of the base
       length: length of the axis
       scale: scale of the axis
       name: name of the reference
def reset(self)
       Resets origin, base, rotation, frames and colors
def reset_base(self)
       Sets self.base to the canonical basis
def reset_colors(self)
       Set self.colors to default colors
def reset_frames(self)
       Set self.frame to 0
       Parameters
       name: name of a color
def reset_origin(self)
       Sets the origin to the point (0,0,0)
def reset_rotation(self)
       Sets the rotation to identity, i.e., rotation of 0 degrees around the vector (1,0,0)
def revolution_surface(self, fun=None, tmin=0.0, tmax=1.0, o=Vector((0.0, 0.0, 0.0)), u1=Vector((1.0,
                                                             0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0)), pmax=0, steps=256, thickness=0.025,
                                                             axis='Z', name='Revolution surface', color='AzureBlueDark')
       Draws a revolution surface from a curve in the reference R'
       Parameters
       fun: parametric equacion of the curve
       steps: number of steps
       axis: axis of revolution. It must be 'X', 'Y' or 'Z'
       o: origin of the reference R'
```

u1, u2: vectors to construct the basis {v1, v2, v3}

pmax: the principal axis are drawn between -pmax and pmax

```
color: color of the surface
def rotacio_ortoedre(self, centre=Vector((0.0, 0.0, 0.0)), costats=Vector((8.0, 5.0, 4.0)), eix='Z',
       Draws an animation of an orthohedron rotating around a vectorial line
       Parameters
       centre: center of the orthohedron
       costats: half sides of the orthohedron
       eix: axis of rotation
      opacity: opacity of the orthohedron
\tt def\ rotacio\_ortoedre\_angles\_euler(self,\ centre=Vector((0.0,\ 0.0,\ 0.0)),\ costats=Vector((8.0,\ 5.0,\ 4.0)),\ costats=Vector((8.0,\
                                                                                      psi=90, theta=60, phi=45, radians=False, opacity=1, eixos='zxz')
       Draws an animation of an orthohedron rotating given the Euler's angles
       Parameters
       centre: center of the orthohedron
       costats: half sides of the orthohedron
       psi, theta, phi: Euler's angles
       radians: if True the Euler's angles must in radians. If False in degrees
       opacity: opacity of the orthohedron
       eixos: axis of the three rotations
def rotacio_ortoedre_voltant_vector(self, centre=Vector((0.0, 0.0, 0.0)), costats=Vector((8.0, 5.0,
                                                                                           4.0)), angle=80, radians=False, vector=Vector((1.0, -2.0, 1.0)),
                                                                                           opacity=0.7, euler=None, reverse=False)
       Draws an animation of a vector rotating around a vectorial line
       Parameters
       centre: center of the orthohedron
       costats: half sides of the orthohedron
       angle: angle of rotation
       radians: if True the Euler's angles must in radians. If False in degrees
       vector: generator of the vectorial line
       opacity: opacity of the orthohedron
       euler: None or the value of the three Euler's axis
       reverse: if True, shows the rotation with Euler's angles in reverse order
def rotacio_vector(self, vector=Vector((6.0, 8.0, 5.0)), eix=Vector((1.0, 1.0, 1.0)))
```

Draws an animation of a vector rotating around a vectorial line

#### **Parameters**

```
vector: vector to rotate
```

eix: axis of rotation, given by a vector or by X, Y or Z

Rotates an object by the Euler angles psi, theta and phi

```
Parameters
```

object: the object

psi, theta, phi: the Euler angles expressed in degrees

axis: it must be 'XYZ', 'XZY', 'YXZ', 'YZX', 'ZXY', 'ZYX', 'XYX', 'XZX', 'YXY', 'YZY', 'ZXZ' or 'ZYZ'

amax: axis valur for draw\_base\_axis

scaleaxis: scale value for draw\_base\_axis

local: if True the center of rotation is the location of the object

radians: if True, psi, theta and phi must be in radians

positive: if False and psi, theta or phi are greather than 180 degrees, they rae converted to negative angles

Rotates an object around the axis

# **Parameters**

obj: the object

axis: it must be 'X', 'Y', 'Z' or a Vector

local: if True the center of rotation is the location of the object

Rotates an object around an angle 'angle' around the axis

# **Parameters**

obj: the object

axis: any non nul Vectors

angle: the angle of rotation in degrees

frames: increment of the frame set

scaleaxis: scale value for draw\_base\_axis

local: if True the center of rotation is the location of the object

def rotate\_vector(self, vector=None, axis='Z')

Rotates a vector around the axis

# **Parameters**

vector: the vector

axis: it must be 'X', 'Y', 'Z' or a vector

 $\tt def \ set\_base(self, \ base=[[1, \ 0, \ 0], \ [0, \ 1, \ 0], \ [0, \ 0, \ 1]], \ orthonormal=False)$ 

Sets the self.base, i.e., the basis of the reference coordinates used to display objects

# **Parameters**

base: list of three vectors

orthonormal: if True, the Gram-Schmidt method is applied and the vectors are normalized.

def set\_colors(self, names)

Set self.colors to the list of colors with names 'names'

```
Parameters
```

names: list of name colors

```
def set_cursor(self, origin=[0, 0, 0], direction=[1, 0, 0], axis='x')
```

Sets the cursor position and direction

#### **Parameters**

origin: position of the cursor

direction: vector that indicates the direction of the axis 'axis'

axis: 'x', 'y' or 'z'

Sets the rotation of the cursor

# **Parameters**

origin: position of the cursor

rotation: matrix of a rotation

# def set\_default\_color(self, name)

Set self.defaultcolor to the color with name 'name'

# **Parameters**

name: name of a color

# def set\_origin(self, vector=[0, 0, 0])

Sets the origin of the reference coordinates used to display objects.

#### **Parameters**

vector: origin's position

# def set\_rotation(self, angle=None, vector=None, quaternion=None)

Sets self.rotation to the rotation defined by an angle and an axis or by a quaternion.

# **Parameters**

angle: angle of rotation in degrees

vector: axis of rotation

quaternion: quaternion that defines a rotation

The angle and vector takes precedence over the quaternion

# 

Return a curve defined by the parametrization  $\boldsymbol{f}$ 

# **Parameters**

f: Parametrization of the curve

tmin: minimum value of the parameter

tmax: maximum value of the parameter

steps: number of steps

name: name of the curve

symmetry: None or a value in the list ('XY','XZ','YZ','X','Y','Z','O'). Symmetry of the curve

draw: if True, the curve is drawn

Draws a sphere of center 'o' and radius squared equal to 'r2'

#### **Parameters**

o: center of the spherecmax=15

r2: radius of the sphere squared

principal: if True, the principal axis are drawn

canonica: if True, the canonical axis are drawn

color: color of the surface

name: name of the sphere

cmax: the canonical axis are drawn between -cmax and cmax

pmax: the principal axis are drawn between -cmax and cmax

thickness: thickness of the sphere

opacity: opacity of the sphere

Draws an animation of a revolution surface from a parabola

# **Parameters**

a: the paràbola is of the form  $y = a*x^2$ 

vertex: vertex of the parabola

pmax: maximum value of the independent variable

pla: a value from the list ('XY','YX','XZ','ZX','YZ','ZY') representing the variables for the equation 'XY'  $y = ax^2$  and rotaqtion around the X axis 'YX'  $x = ay^2$  and rotaqtion around the Y axis 'XZ'  $z = ax^2$  and rotaqtion around the Z axis 'YZ'  $z = ay^2$  and rotaqtion around the Y axis 'ZY'  $y = az^2$  and rotaqtion around the Z axis

punt: punt: if it's a float value, draws a moving poing

def tor(self, centre=Vector((8.0, 0.0, 3.0)), radi=3, punt=None)

Draws a torus of revolution from a circumference

# **Parameters**

centre: center of the circumference

radi: radius of the circumference

cmax: maximum values of the x, y and z coordinates

punt: if it's a float value, draws a moving poing

Draws a two sheets hyperboloid

**Parameters** 

```
o: center of the hyperboloid
   u1, u2: the principal basis {v1, v2, v3} is constructed from this vectors
   a2, b2, c2: squares of semi-axes of the hyperboloid. The equation is x'^2/a^2 + y'^2/b^2 - z'^2/c^2 = -1
   principal: if True, the principal axis are drawn
   canonica: if True, the canonical axis are drawn
   color: color of the surface
   name: name of the hyperboloid
  xmax: maximum value of the x coordinate
   cmax: the canonical axis are drawn between -cmax and cmax
   pmax: the principal axis are drawn between -cmax and cmax
   thickness: thickness of the hyperboloid
  opacity: opacity of the hyperboloid
def vector_base_canonica(self, vector=Vector((-4.0, 7.0, 6.0)), length=12, name='Vector',
                            components=True)
   Draws a vector expressed in the canonical base
   Parameters
   vector: the vector to draw
   length: length of the axis
   name: name of the vector
  components: if True draws lines representing the components
def vector base no canonica(self, vector=Vector((5.0, 6.0, -5.0)), origin=Vector((0.0, 0.0, 0.0)),
                                ul=Vector((-0.3333333432674408, -0.6666666865348816, 0.6666666865348816)),
                                u2=Vector((0.666666865348816, 0.3333333432674408, 0.6666666865348816)),
                                u3=Vector((-0.6666666865348816, 0.6666666865348816, 0.3333333432674408)),
                                length=12, scale=0.04, name="Base B'")
   Draws a vector expressed in the base {u1,u2,u3} with origin in the point origin and sets the default origin and default base to
   them
   Parameters
   vector: vector to draw
   origin: origin of the vector and the base
   u1, u2, u3: vectors of the base
  length: length of the axis
```

scale: scale of the base

name: name of the base

```
def vectors_to_quaternion(self, u1=Vector((1.0, 0.0, 0.0)), u2=Vector((0.0, 1.0, 0.0)))
```

Returns the quaternion correspondint to the base  $\{v1, v2, v3\}$  u1, u2: the principal basis  $\{v1, v2, v3\}$  is constructed from this vectors in the following way v1 = u1 v2 = u2 - u2.project(v1) v1.normalize() v2.normalize() v3 = v1.cross(v2)

class Rotation (angle=None, vector=None, axis=None, quaternion=None, radians=False)

Class used for work with rotations. The stored value in the class is a quaternion

Initializes the value for a rotation

# **Parameters**

angle: angle of rotation

vector: axis of rotation

quaternion: The quaternion itself

radians: must be True if the angle is entered in radians and False if the is entered in degrees.

# Static methods

```
def from_euler_angles(psi, theta, phi, axis='ZXZ', radians=False)
```

Initializes a rotation from its Euler angles in the order ZXZ

# **Parameters**

phi, theta, psi: Euler angles

axis: it must be 'XYZ', 'XZY', 'YXZ', 'YZX', 'ZXY', 'ZYX', 'XYX', 'XZX', 'YXY', 'YZY', 'ZXZ' or 'ZYZ' radians: if radians, psi, theta and must be in radians

# Methods

# def apply(self, v)

Applies the rotation to an object v Parameters: v: any object that can be transformed by a rotation

# def to\_axis\_angle(self, radians=False)

Returns the axis and angle of the rotation

# **Parameters**

radians: if True, the angle returned is in radians, if not, is returned in degrees

```
def to_euler_angles(self, axis='ZXZ', randomize=False, radians=False)
```

Returns the Euler angles according to axis 'axis'

#### **Parameters**

axis: it must be 'XYZ', 'XZY', 'YXZ', 'YZX', 'ZXY', 'ZYX', 'XYX', 'XZX', 'YXY', 'YZY', 'ZXZ' or 'ZYZ' radians: if True, the angle returned is in radians, if not, is returned in degrees

# Index

# **Functions**

createFaces
create\_mesh\_object
draw parametric surface

# Classes

# Color

# **Colors**

color colors

colorsbyname

# LinearAlgebra

add\_ligth

 $add\_ligths$ 

add material

animate\_revolution\_surface

base canonica

base\_cilinder

base\_cone

base\_is\_canonica

base\_no\_canonica

canvi\_base

canvi coordenades

cilindre elliptic

cilindre\_elliptic\_simple

cilindre\_hiperbolic

cilindre\_hiperbolic\_simple

cilindre\_parabolic

cilindre parabolic simple

clear

comp\_times\_vector

components\_in\_base

con

con\_cilindre\_elliptic

con\_revolucio

cone

 ${\tt coordinates\_en\_referencia}$ 

curve

delete base cilinder

delete\_base\_cone

draw\_base\_axis

draw\_circle

 ${\tt draw\_components}$ 

draw\_cone

draw\_cube

draw\_curve

draw\_ellipse

draw\_ellipsoid

draw\_elliptic\_cylinder

draw\_elliptic\_paraboloid

draw frenet curve

draw\_function

```
draw hyperbole
draw hyperbolic cylinder
draw_hyperbolic_paraboloid
draw_line
draw mesh
draw one sheet hyperboloid
draw parabola
draw parabolic cylinder
draw_parallelepiped
draw parallelogram
draw plane
draw plane surface
draw_point
draw points
draw_polygon
draw_pyramid
draw regular polygon
draw_simple_curve
draw_surface
draw tetrahedron
draw triangle
draw_two_sheets_hyperboloid
draw_vector
draw vector field
draw_vectors
ellipse
ellipsoid
ellipsoide
ellipsoide revolucio
elliptic cylinder
elliptic_paraboloid
esfera
esfera_cilindre_elliptic
gir_poligon
hiperbola
hiperboloide dues fulles
hiperboloide dues fulles revolucio
hiperboloide una fulla
hiperboloide una fulla revolucio
hyperbolic cylinder
hyperbolic_paraboloid
join
moviment helicoidal ortoedre
one sheet hyperboloid
parabola
parabolic cylinder
paraboloide_elliptic
paraboloide_elliptic_revolucio
paraboloide hiperbolic
paraboloide_hiperbolic_simple
pla_afi
pla vectorial
projeccio ortogonal simetric pla afi
projeccio_ortogonal_simetric_pla_vectorial
projeccio ortogonal simetric recta afi
projeccio_ortogonal_simetric_recta_vectorial
punt_referencia_canonica
```

```
punt referencia no canonica
referencia canonica
referencia_no_canonica
reset
reset_base
reset colors
reset\_frames
reset_origin
reset_rotation
revolution_surface
rotacio ortoedre
rotacio ortoedre angles euler
rotacio_ortoedre_voltant_vector
rotacio vector
rotate euler
rotate_object
rotate object by axis angle
rotate_vector
set_base
set colors
set cursor
set_cursor_rotation
set_default_color
set origin
set\_rotation
simple_curve
sphere
superficie_revolucio_parabola
tor
two sheets hyperboloid
vector_base_canonica
vector_base_no_canonica
vectors_to_quaternion
Rotation
```

apply
from\_euler\_angles
to\_axis\_angle
to\_euler\_angles

Generated by pdoc 0.10.0.