



CentraleSupélec

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# RAPPORT TL SIR COMMANDE DE ROBOT PAR INTERFACE CÉRÉBRALE

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# 1 Introduction

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## 2 Analyse des resultats

egbfoaubgoabgoabogbaojbfaobfaob

### 3 Methodology and performed work

#### 3.1 Bibliographical Research

A footnote <sup>1</sup>

You can see a duck in figure 1.



Figure 1: A duck

##### 3.1.1 Deep Learning

##### 3.1.2 Transfer Learning

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<sup>1</sup><https://hal.archives-ouvertes.fr/>

## **4 Analysis of the results**

### **4.1 Training new models**

### **4.2 Deploying the models and API**

## 5 Contributions

## 6 Conclusions et recommandations



## **Appendix A: Recommendations from the directors**