Structure of the moduli space

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1 Introduction

A now-classical theorem due to Anderson [?] and Bando-Kasue-Nakajima [?] states that if (M, g_j) is a sequence of Einstein metrics on a four-manifold M with fixed diameter, and with a uniform local volume density, then some subsequence of these spaces converges to an Einstein orbifold (M_0, g_0) . At first, the convergence is only in the Gromov-Hausdorff topology, but is also true in a considerably more refined sense. Away from the orbifold points of M_0 , the convergence is \mathcal{C}^{∞} (again, up to a subsequence), and near the orbifold points, a suitable sequence of rescalings converges (again, locally in \mathcal{C}^{∞}) to a complete ALE space (Z, g_Z) . In fact, a more careful version of this rescaling argument produces a complete bubble true of ALE spaces.

It is natural to ask about a converse: namely, given an Einstein orbifold (M_0^4, g_0) with an orbifold point modelled on \mathbb{R}^4/Γ for some discrete group $\Gamma \subset SO(4)$, and a Ricci-flat ALE (asymptotically locally Euclidean) space (Z, g_Z) whose tangent cone at infinity is the same cone, is it possible to desingularize M_0 to obtain a family of smooth Einstein metrics (M, g_{ϵ}) by gluing a truncation of Z to a truncation of M_0 ? This is an obstructed problem and the answer is generally no. However, in some cases this has been done successfully. Biquard [?] carried out this gluing, but assuming that (M_0, g_0) is a Poincaré-Einstein space, i.e., an asymptotically hyperbolic space with Einstein metric, which moreover satisfies an extra compatibility condition at the orbifold point. That paper carries out the gluing when the discrete group is \mathbb{Z}_2 and the ALE space Z is the Eguchi-Hanson space. A sequence of later papers provided further refinements and a path to carrying out the gluing for more general groups Γ . The reason for passing from the compact to the asymptotically hyperbolic setting is that it is easier to control the cokernel of the linearized problem that must be analyzed to carry out the gluing.

More recently still, the second-named author here has analyzed this problem in much greater depth. In [?], [?] it is proved that any possible desingularization of M_0 is necessarily of the form assumed in this gluing procedure. In [?], it is proved that there is an infinite hierarchy of compatibility conditions at the orbifold points. These are obstructions to the possibility of gluing. Substantially more information is obtained in [?]. (SORRY – you'll want to rewrite this, no doubt).

In this paper we address a new aspect of this problem, by revealing an underlying variant of a semi-analytic structure near the frontier of the compactified Einstein moduli space. Roughly speaking, we prove that we can carry out a finite dimensional Liapunov-Schmidt reduction of the gluing problem modulo obstructions in the 'log-analytic' category, and from this deduce from a version of the Malgrange-Weierstrass preparation theorem that the Einstein moduli space itself has a log-semi-analytic structure. From this we can deduce answers to some classical questions about the set of Einstein metrics that can exist on a given 4-manifold M.

A function f(t) of one variable is said to be log-analytic if it can be expressed as a convergent sum

$$f(t) = \sum_{j=0}^{\infty} \sum_{k=0}^{N_j} a_{jk} t^j (\log t)^k$$
 (1)

in some interval $0 \le t < t_0$. This definition is inspired by the notion of a polyhomogeneous (phg) function, where the equality in (1) is replaced by a classical asymptotic expansion. A key step in our main result here is the assertion that the finite dimensional reduction of this gluing problem can be carried out in this log-analytic category, where t is the 'gluing parameter'.

At first glance, it might seem surprising that log terms arise in this problem. This can be explained by the observation that if one tries to study solutions of $\Delta u = 0$ in the complement of some compact set in the ALE space Z, then it is well-known that u has an asymptotic expansion as the radial variable ρ in Z tends to infinity. The expansion

involves terms of the form $\rho^{-\gamma_j}$ where γ_j is an indicial root of the problem, but a close examination of this asymptotic expansion shows that this asymptotic series may also contain terms like $\rho^{-\gamma_j} \log \rho$. We explain this phenomenon in more detail below. When Z is real analytic, e.g., if it is Ricci-flat, then one may prove that this series is convergent in this log-analytic sense (with $t = \rho^{-1}$.

The orbifold-ALE gluing here is not new, of course, and various versions appear in the aforementioned papers of Biquard and the second author. We pursue a slightly different strategy for the proof here in order to focus on this log-analytic structure, by using the Cauchy data matching technique. This goes back to [?] for a different geometric problem, and further back than that for certain analytic problems in gauge theory, but has been exploited in numerous settings since then. We develop a slight twist to this method here where two separate interface boundaries are introduced, separated by a large nappe of the cone $C(S^3/\Gamma)$.

2 Background

In this section we set up some basic notation that will be used in the rest of the paper. As explained in the introduction, let (M_0, g_0) be a four-dimensional Einstein orbifold. In other words, g_0 is an Einstein metric on the regular set of M_0 , while the singular set consists of N points, p_1, \ldots, p_N , around each of which the Einstein metric is asymptotic to the flat metric \mathbb{R}^4/Γ_j , $j=1,\ldots,N$. For simplicity, in this paper we always assume that N=1, but the extension of all our methods and results to the general case involves only more notation. Indeed, the fact that the analysis on an orbifold is the same as on a smooth space (up to finite quotients around singularities) allows us to iterate the construction to the whole tree of singularities dealing with one singularity and the corresponding Ricci-flat ALE orbifold at a time.

2.1 Gauged Einstein operator

For an Einstein metric g, define $B_g := \delta_g + \frac{1}{2}d\operatorname{tr}_g$ the Bianchi operator, where δ_g is the divergence with the convention that in coordinates, for a 1-form ω , $\delta_g \omega := -g^{ij} \nabla_j \omega_i$ and for a symmetric 2-tensor h, $(\delta_g h)_k := -g^{ij} \nabla_j h_{ik}$. Note that for a vector field X identified with the 1-form canonically associated by g, we find

$$2\delta_g^* X = \mathcal{L}_X g$$

where \mathcal{L} is the Lie derivative and δ_g^* , the formal adjoint of δ_g . Notice that a metric g in dimension 4 is Einstein if and only if it is a zero of

$$E(g) := \operatorname{Ric}(g) - \frac{\overline{R}(g)}{4}g,$$

and moreover that $B_g E(g) = 0$ by the Bianchi identity. We will be interested in the operator

 $\mathbf{\Phi}_{g_1}(g) := \operatorname{Ric}(g) - \frac{\overline{\mathrm{R}}(g)}{4}g + \delta_{g_1}^* B_{g_1} g$

on metrics close to g_1 . Denoting $\mathring{R}(h)(X,Y) = \sum_i h\Big(\operatorname{Rm}(e_i,X)Y,e_i\Big)$ for an orthonormal basis e_i , we have the following expression of the linearization: for h satisfying $\int_M \operatorname{tr}_{g_1} h dv(g) = 0$,

$$P_{g_1}(h) := d_{g_1} \Phi_{g_1}(h) = \frac{1}{2} \nabla_{g_1}^* \nabla_{g_1} h - \mathring{R}_{g_1}(h) + \frac{1}{2} \left(\operatorname{Ric}_{g_1} \circ h + h \circ \operatorname{Ric}_{g_1} - \frac{R(g_1)}{2} h \right) + \frac{1}{4 \operatorname{Vol}(g_1)} \int_M \left\langle \operatorname{Ric}(g_1) - \frac{R(g_1)}{2} g_1, h \right\rangle_{g_1} dv_{g_1}.$$
(2)

which would reduce to $P := \frac{1}{2}\nabla^*\nabla - \mathring{R}$ if the metric g_1 were Einstein.

2.2 Orbifold region

Call this sole orbifold point p. There is a neighborhood \mathcal{U} of p which is diffeomorphic to a truncated cone $C_{0,1}(S^3/\Gamma)$. There is an asymptotic normal form for the metric g_0 in this neighborhood, namely

$$g_0 = dr^2 + r^2 h_0 + \tilde{h}(r), \text{ where } \tilde{h}(r) \sim \sum_{j=1}^{\infty} r^{\gamma_j} h_j.$$
 (3)

Here h_0 is the standard round metric on the lens space $Y = S^3/\Gamma$, and h_j is a sequence of smooth tensors on Y. The exponents γ_j are a strictly positive monotone increasing sequence of real numbers. Thus $\tilde{h}(r)$ is a polyhomogeneous family of 2-tensors on Y, with the expansion as given. In some cases it is surely possible to prove that this is a convergent expansion, but we do not need this here.

2.2.1 Formal definitions and linear analysis

To adapt->

Definition 2.1 (Orbifold (with isolated singularities)). We will say that a metric space (M_o, g_o) is an orbifold if there exists $\epsilon_0 > 0$ and a finite number of points $(p_k)_k$ of M_o which we will call singular such that we have the following:

- 1. the space $(M_o \setminus \{p_k\}_k, g_o)$ is a Riemannian manifold,
- 2. for each singular point p_k of M_o , there exists a neighborhood of p_k , $U_k \subset M_o$, a finite subgroup acting freely on the sphere, $\Gamma_k \subset SO(4)$, and a diffeomorphism $\Phi_k : B_{\mathbf{e}}(0, \epsilon_0) \subset \mathbb{R}^4/\Gamma_k \to U_k \subset M_o$ for which, for any $l \in \mathbb{N}$, there exists $C_l > 0$ such that

$$r^l |\nabla^l (\Phi_k^* g_o - \mathbf{e})|_{C^2(\mathbf{e})} \leqslant C_l r^2.$$

Definition 2.2 (The function r_o on an orbifold). We define r_o , a smooth function on M_o satisfying $\Phi_k^* r_o := r$ on each U_k , and such that on $M_o \setminus U_k$, we have $\epsilon_0 < r_o < 1$ (the different choices will be equivalent for our applications).

We will denote, for $0 < \epsilon \leqslant \epsilon_0$,

$$M_o(\epsilon) := \{r_o > \epsilon\} = M_o \setminus \Big(\bigcup_k \Phi_k(B_{\mathbf{e}}(0, \epsilon))\Big).$$

Definition 2.3 (Infinitesimal deformations of an Einstein orbifold metric). Let (M_o, g_o) be an Einstein orbifold. We define $\mathbf{O}(g_o)$ as the finite dimensional kernel of the elliptic operator $P_{g_o} := \frac{1}{2} \nabla_{g_o}^* \nabla_{g_o} - \mathring{\mathbf{R}}_{g_o}$ on 2-tensors of $L^2(g_o)$, where $\mathring{\mathbf{R}}(h)(X,Y) = \sum_i h(\operatorname{Rm}(e_i, X)Y, e_i)$,.

2.2.2 Cut-off orbifold with boundary

In the following we shall fix some sufficiently small value a>0 and consider the truncated orbifold

$$M_0' = M_0 \setminus \{r < a\}. \tag{4}$$

This is a manifold with boundary, and the parameter a will be chosen eventually so that the remainder term $\tilde{h}(a)$ is sufficiently small.

2.3 ALE region

Next, let (Z, g_Z) be a four-dimensional Ricci-flat ALE space which is modeled at infinity by the same cone $C(S^3/\Gamma)$. It follows from the classical theorem of Bando-Kasue-Nakajima [?] that there exists a compact set $K \subset Z$ and a 'radial' function ρ defined on $Z \setminus K$ such that g_Z deviates from the standard conic metric by a remainder term with a log-analytic expansion as $\rho \to \infty$, i.e.,

$$g_Z = d\rho^2 + \rho^2 h_0 + \hat{h}(\rho), \quad \hat{h}(\rho) \sim \sum_{j=1}^{\infty} \sum_{k=1}^{N_j} \hat{h}_{j,k} \rho^{-\gamma_j} (\log \rho)^k$$
 (5)

2.3.1 Formal definitions and linear analysis

Definition 2.4 (ALE orbifold (with isolated singularities and one end)). An ALE orbifold (N,b) is a orbifold for which there exists $\epsilon_0 > 0$ and a compact $K \subset N$ for which there exists a diffeomorphism $\Psi_{\infty} : (\mathbb{R}^4/\Gamma_{\infty}) \backslash B_{\mathbf{e}}(0,\epsilon_0^{-1}) \to N \backslash K$ such that we have

$$r^l |\nabla^l (\Psi_{\infty}^* b - \mathbf{e})|_{C^2(\mathbf{e})} \leqslant C_l r^{-4}.$$

Definition 2.5 (The function r_b on an ALE orbifold). We define r_b a smooth function on N satisfying $\Psi_k^* r_b := r$ on each neighborhood U_k of a singular point of definition A.1, and $\Psi_\infty^* r_b := r$ on U_∞ , and such that $\epsilon_0 < r_b < \epsilon_0^{-1}$ on the rest of N (the different choices are equivalent for our applications).

For $0 < \epsilon \leqslant \epsilon_0$, we will denote

$$N(\epsilon) := \{ \epsilon < r_b < \epsilon^{-1} \} = N \setminus \Big(\bigcup_k \Psi_k(B_{\mathbf{e}}(0, \epsilon)) \cup \Psi_{\infty} \Big((\mathbb{R}^4 / \Gamma_{\infty}) \setminus B_{\mathbf{e}}(0, \epsilon^{-1}) \Big) \Big).$$

Definition 2.6 (Infinitesimal deformations of Ricci-flat ALE orbifolds). Let (N, \mathbf{b}) be a Ricci-flat ALE orbifold. We define the space $\mathbf{O}(\mathbf{b})$ as the kernel of the operator $P_{\mathbf{b}} := \frac{1}{2} \nabla_{\mathbf{b}}^* \nabla_{\mathbf{b}} - \mathring{\mathbf{R}}_{\mathbf{b}}$ on $L^2(\mathbf{b})$.

For any $h \in \mathbf{O}(\mathbf{b})$, we have

- 1. $h = \mathcal{O}(r_b^{-4}),$
- 2. $\delta_{\mathbf{b}}h = 0$, and
- 3. $tr_{\bf b}h = 0$.

There is a particular infinitesimal Ricci-flat ALE deformation by rescaling and reparametrization which we denote \mathbf{o}_1 . It is of the form $\mathcal{L}_X \mathbf{b}$ for a harmonic vector field X asymptotic to $r_b \partial_{r_b}$ at infinity. It is linked to the notion of reduced volume of Ricci-flat ALE metric introduced in [?], see [?].

Definition 2.7 (Normalized Ricci-flat ALE metric). A normalized Ricci-flat ALE orbifold is a Ricci-flat ALE metric with reduced volume -1.

This prevents rescaling of the metric and Ricci-flat ALE deformation in the direction \mathbf{o}_1 . We will denote $\mathbf{O}_0(\mathbf{b})$ the $L^2(\mathbf{b})$ -orthogonal of \mathbf{o}_1 in $\mathbf{O}(\mathbf{b})$. These are the infinitesimal Ricci-flat ALE deformations preserving the reduced volume at first order.

2.3.2 Cut-off ALE space with boundary

2.4 Naïve gluings and Moduli space of Einstein metrics

2.4.1 Naïve gluing

Cut-off functions with small scale invariant derivatives. Let $u : \mathbb{R} \to \mathbb{R}^+$ be a C^{∞} cut-off function, identically equal 1 on $[-\infty, 0]$, and vanishing on $[1, +\infty]$. Let a > 0 and b > 1 and consider the following function:

$$\chi_{a,b}: x \in \mathbb{R}^4 \mapsto u\left(\frac{\log(|x|/a)}{\log b}\right).$$
(6)

Then, $\chi_{a,b}$ is a cut-off function supported in [0, ab] and equal to 1 on [0, a]. Moreover, for all $k \in \mathbb{N}$, there exists C_k such that for all $l \leq k$,

$$|x|^l |\nabla^l \chi_{a,b}|(x) \leqslant \frac{C_k}{\log b}.$$

In the rest of the article, we fix b > 1 large enough so that our derivatives are small enough for our applications, and we will denote $\chi := \chi_{1,b}$ a cut-off function decaying from 1 to 0 between 1 and b.

Naïve gluing of ALE spaces to orbifold singularities. Let $0 < \epsilon < \epsilon_0 b^{-2}$ be a fix constant, $0 < t < \epsilon^4$, (M_o, \mathbf{g}_o) an orbifold and $\Phi : B_{\mathbf{e}}(0, \epsilon_0) \subset \mathbb{R}^4/\Gamma \to U$ a local chart around a singular point $p \in M_o$ such that the metric $\Phi^*\mathbf{g}_o$ is analytic. Let also (N, \mathbf{b}) be an ALE orbifold asymptotic to \mathbb{R}^4/Γ , and $\Psi_\infty : (\mathbb{R}^4/\Gamma_\infty) \setminus B_{\mathbf{e}}(0, \epsilon_0^{-1}) \to N \setminus K$ a chart at infinity in which $\Psi_\infty^*\mathbf{b}$ equals a power series in r^{-1} .

Definition 2.8 (Naïve desingularization of an orbifold by an ALE space). We define a naïve desingularization of an orbifold (M_o, g_o) at p by (N, b) at scale t, which we will denote $(M_o \# N, g_o \#_{p,t} b)$ by putting $g_o \#_{p,t} b = g_o$ on $M \setminus U$, $g_o \#_{p,t} b = tb$ on K, and

$$g_o \#_{p,t} b = \chi \Big((b\epsilon)^{-1} r \Big) \Phi^* g_o + \chi \Big((b\epsilon)^{-1} r \Big) \chi \Big(b(\epsilon^{-1} \sqrt{t})^{-1} r \Big) \mathbf{e} + \Big(1 - \chi (b(\epsilon^{-1} \sqrt{t})^{-1} r) \Big) \Psi_{\infty}^* b$$
on $A_{\mathbf{e}}((b\epsilon)^{-1} \sqrt{t}, b^2 \epsilon)$.

Remark 2.9. In these naïve gluings, we essentially identify r_o and $\sqrt{t} \cdot r_b$.

More generally, it is possible to desingularize iteratively by trees of ALE orbifolds. For $t=(t_j)_j$, if N_j is glued to $p_j \in N_{j_1}$, and N_{j_1} is glued to $p_{j_1} \in N_{j_2}$, ..., $N_{j_{k-1}}$ is glued to N_{j_k} , which is glued to M_o , we define $T_j := t_{j_1}t_{j_2}...t_{j_k}$. This way, on each $N_j(b\epsilon)$, the metric is T_jb_j . We then obtain a covering of the manifold $M=M_o\#_jN_j$ adapted to a degeneration at relative scales $(t_j)_j$:

$$M = \bigcup_{j} \left(N_{j}(\epsilon) \cup A_{j}(t, \epsilon) \right) \cup M_{o}(\epsilon), \tag{7}$$

where for each j, $A_j(t,\epsilon) := A_{\mathbf{e}}(\epsilon^{-1}\sqrt{T_j}\sqrt{t_j},\epsilon\sqrt{T_j})$ is an intermediate annulus where the metric is flat. A configuration as above is called a *desingularization pattern* and denoted by D as in g_t^D .

We define cut-off functions on M_o and on N, and the associated gluing annuli $A_j(t,\epsilon)$. These cutoff functions are actually a partition of the unity on M, associated to the covering (7) that is,

$$1 \equiv \chi_{M_o(\epsilon)} + \sum_j \left(\chi_{N_j(\epsilon)} + \chi_{A_j(t,\epsilon)} \right). \tag{8}$$

Finally, on a naïve desingularization (M, g^D) , we define a function r_D in the following way: $r_D = r_o$ on $M_o(\epsilon)$, $r_D = \sqrt{T_j} r_{b_j}$ on each $N_j(\epsilon)$, and $r_D = r$ on each $A_j(t, \epsilon)$. The function r_D is smooth on M.

Remark 2.10. On the compact sets $M_o(\epsilon^{-1}\sqrt{t})$ and $N_j(\epsilon^{-1}\sqrt{t})$, the metric g^D respectively equals

$$\tilde{g}_o := \chi_{M_o(\epsilon)} g_o + (1 - \chi_{M_o(\epsilon)}) \mathbf{e},$$
(9)

and

$$\tilde{g}_{b_i} := \chi_{N_i(\epsilon)} b_j + (1 - \chi_{N_i(\epsilon)}) \mathbf{e}, \tag{10}$$

where \mathbf{e} is a flat metric to which g_o and the b_j are asymptotic at their singular points and infinities.

2.4.2 Gauged Einstein equation close to a naïve gluing

Let K_o be the L^2 -kernel of $B_{g_o}\delta_{g_o}^* = \nabla_{g_o}^*\nabla_{g_o} - \text{Ric}(g_o)$ on 1-forms of (M_o, g_o) , define $\tilde{\mathbf{K}}_o := \chi_{M_o(b\epsilon)}\mathbf{K}_o$,

$$\tilde{B}_{g^D} := \pi_{\tilde{\mathbf{K}}_o^{\perp}} B_{g^D} \text{ and } \tilde{B}_{\tilde{g}_o} := \pi_{\tilde{\mathbf{K}}_o^{\perp}} B_{\tilde{g}_o}.$$

Ads in the first section, we will be interested in the operator

$$\Phi_{g^D}(g) := \operatorname{Ric}(g) - \frac{\overline{\mathrm{R}}(g)}{4}g + \delta_{g^D}^* \tilde{B}_{g^D} g$$

on metrics close to g^D . Denoting $\mathring{R}(h)(X,Y) = \sum_i h\Big(\operatorname{Rm}(e_i,X)Y,e_i\Big)$ for an orthonormal basis e_i , we have the following expression of the linearization: for h satisfying $\int_M \operatorname{tr}_{g^D} h dv(g) = 0$,

$$P_{g^{D}}(h) := d_{g^{D}} \mathbf{\Phi}_{g^{D}}(h) = \frac{1}{2} \nabla_{g^{D}}^{*} \nabla_{g^{D}} h - \mathring{\mathbf{R}}_{g^{D}}(h) + \frac{1}{2} \left(\operatorname{Ric}_{g^{D}} \circ h + h \circ \operatorname{Ric}_{g^{D}} - \frac{\overline{\mathbf{R}}(g^{D})}{2} h \right) + \frac{1}{4 \operatorname{Vol}(g^{D})} \int_{M} \left\langle \operatorname{Ric}(g^{D}) - \frac{\mathbf{R}(g^{D})}{2}, h \right\rangle_{g^{D}} dv_{g^{D}} g^{D} - \delta_{g^{D}}^{*} B_{g^{D}} h + \delta_{g^{D}}^{*} \tilde{B}_{g^{D}} h.$$

$$\tag{11}$$

which would reduce to $P := \frac{1}{2} \nabla^* \nabla - \mathring{\mathbf{R}}$ if the metric g^D were Einstein and $\tilde{B} = B$.

2.5 Moduli space of Einstein metrics near an Einstein orbifold

The moduli space consists in perturbations of naïve gluings

3 Spaces of log-analytic functions

We recall from the introduction that a log-analytic function of a single variable t is one which can be represented as a convergent sum

$$u(t) = \sum_{j=0}^{\infty} \sum_{k=0}^{N_j} a_{jk} t^j (\log t)^k.$$

Note that there are only finitely many powers of $\log t$ associated to any monomial t^j . If u depends on other variables, say y, we may consider similar expansions where the coefficients a_{jk} depend on this variable y. We require that each a_{jk} lie in some Banach space of functions, and that this series converge in that Banach norm.

In this section we study a scale of topologies on log-analytic functions defined on the nappe of a cone

$$A_{r_1,r_2} = \{(r,y) \in C(S^3/\Gamma) : r_1 \le r \le r_2\}.$$

We consider functions u(t, y) as above which, for each t, lie in the Sobolev space $H^s(S^3/\Gamma)$ (and are primarily interested in the case where s > 3/2), but shall place additional spectral hypotheses on each coefficient $a_{ik}(y)$.

Definition 3.1. Consider the space \mathcal{T} of functions on A_{r_1,r_2} of the form

$$u(r,y) = \sum a_{jk\ell m}(y) \left(\frac{r}{r_2}\right)^j \left(\log\left(\frac{r}{r_2}\right)\right)^k \left(\frac{r_1}{r}\right)^\ell \left(\log\left(\frac{r_1}{r}\right)\right)^m$$

where $k \leq j$, $m \leq \ell - 2$, and each $a_{jk\ell m}$ lies in the sum of the first $n = n(j,\ell)$ spherical harmonics on S^3/Γ , where $n(j,\ell) = \min\{j,\ell-2\}$. It is straightforward to consider the situation where each $a_{jk\ell m}$ takes values in some fixed vector space. (If we allow these coefficients to take values in some vector bundle over S^3/Γ , it would be necessary to replace this last spectral condition with some obvious generalization.)

Next, we introduce a doubly-indexed scale of norms on elements of \mathcal{T} :

Definition 3.2. Fix s > 3/2 and $\alpha > 0$. Define, for any $u \in \mathcal{T}$ with sufficiently fast decaying coefficients, the norm

$$||u||_{s,\alpha}^2 := \sum_{m,a,n,b} (1+m)^{2\alpha} (1+n)^{2\alpha} ||u_{manb}||_{H^s(S^3/\Gamma)}^2.$$

This defines a Banach space, which we denote $\mathcal{A}_{s,\alpha}^0$.

Next, if ∇ denotes the standard covariant derivative on A_{r_1,r_2} with respect to the exact conic metric, we set for any $p \in \mathbb{N}$,

$$\mathcal{A}_{s,\alpha}^p = \{ u \in \mathcal{A}_{s,\alpha}^0 : \nabla^i u \in \mathcal{A}_{s,\alpha}^0 \ 0 \le i \le p \}.$$

Observe that if $u \in \mathcal{A}^p_{s,\alpha}$ for some p, s, α , then

$$u(r_1, y) = \sum_{jk\ell} u_{jk\ell 0}(y) \left(\frac{r_1}{r_2}\right)^j \left(\log\left(\frac{r_1}{r_2}\right)\right)^k$$

is a log-analytic function in the variable $t = r_1/r_2$ with values in $H^s(S^3/\Gamma)$. The analogous statement is true for $u(r_2, y)$.

Remark 3.3. The normal derivative of a function with bounded $\|.\|_{s,\alpha}$ -norm is a $H^{s-1}(\mathbb{S}^3)$ -function. More precisely, if we consider the derivative in the direction $r\partial_r$, then we obtain a log-analytic development in $\frac{r_1}{r_2}$.

Remark 3.4. The projection on the harmonic function with the same Dirichlet data and products are continuous for s > 3/2 and $\alpha \ge 0$ since $H^s(\mathbb{S}^3)$ is a Banach algebra and since $(1 + m + m') \le (1 + m)(1 + m')$ for nonnegative m, m'.

We can extend this norm to functions u which take values in some vector bundle E over A_{r_1,r_2} where $E = \pi^* E_0$; here $\pi : A_{r_1,r_2} \to S^3/\Gamma$ is the natural projection and E_0 is a vector bundle over S^3/Γ . It is particularly simple to do this when E is the subbundle of symmetric 2-tensors.

3.1 Properties of the Banach spaces $A_{s,\alpha}^k$

Let us start with the behavior of the family \mathcal{T} with respect to usual operations.

Lemma 3.5. The family \mathcal{T} is closed under differentiation (term by term), multiplication and inverse of the Laplacian (up to harmonic functions).

Proof. The proof follows from Y. Chen's Section 3, see also Meyers where the main ideas are from. For the inverse, it comes from the explicit formula:

$$\Delta(r^{k+2}\log^{l}r\phi_{m}) = (\lambda_{k+2} - \lambda_{m})r^{k}\log^{l}r\phi_{m} + l(n+2k+2)r^{k}\log^{l-1}r\phi_{m} + l(l-1)r^{k}\log^{l-2}r\phi_{m}$$
(12)

where $\lambda_m = m(m+n-2)$ for all $m \in \mathbb{N}$ and where ϕ_m is an eigenfunction of $-\Delta_{\mathbb{S}^{n-1}}$ associated to λ_m .

We now turn to the behavior of the Banach space restricted to symmetric 2-tensors and their derivatives.

Proposition 3.6. Let h be a symmetric 2-tensor and $u_1, ..., u_l$ be tensors on a neighborhood of the infinity of \mathbb{R}^4 .

1. By construction,

$$||h||_{\mathcal{A}^k_{s,\alpha}} \leqslant ||h||_{\mathcal{A}^l_{s,\alpha}}$$

if $k \leq l$.

2. Moreover, the linear maps

$$h \in \mathcal{A}_{s,\alpha}^{k+2} \to \nabla^l h \in \mathcal{A}_{s,\alpha}^{k+2-l}$$

are continuous with operator norm less than 1 when $l \in \{1, 2\}$ and so is the map $h \in \mathcal{A}_{s,\alpha}^{k+2} \mapsto \Delta h \in \mathcal{A}_{s,\alpha}^{k}$.

3. For a multilinear form Q composed of various contractions with the metric e,

$$||Q(u_1,...,u_l)||_{\mathcal{A}_{s,\alpha}^k} \leqslant C||u_1||_{s,\alpha}...||u_l||_{s,\alpha},$$

where C > 0 depends on Q.

4. The map $h \in_{s,\alpha} \mapsto (\mathbf{e} + h)^{-1} \in \mathcal{A}_{s,\alpha}^k$ is also log-analytic.

Proof. The first two points are direct consequences of the definition.

For the third point, Cauchy product formula applied to the product of

$$\sum_{m,a,n,b} \left(\frac{r}{r_2}\right)^m \left(\frac{r}{r_1}\right)^{-n} \log^a \left(\frac{r}{r_2}\right) \log^b \left(\frac{r}{r_1}\right) u_{manb}$$

and

$$\sum_{p,q,c,d} \left(\frac{r}{r_2}\right)^p \left(\frac{r}{r_1}\right)^{-q} \log^c \left(\frac{r}{r_2}\right) \log^d \left(\frac{r}{r_1}\right) v_{pqcd}$$

gives:

$$\sum_{M,N,A,B} \left(\frac{r}{r_2}\right)^M \log^A \left(\frac{r}{r_2}\right) \left(\frac{r}{r_1}\right)^{-N} \log^B \left(\frac{r}{r_1}\right) \sum u_{manb} v_{pqcd}$$

where the second sum is taken among m+p=M, n+q=N, a+c=A and b+d=B. Since $H^s(\mathbb{S}^{n-1})$ is a Banach algebra for s>3/2, we have

$$\left\| \sum u_{manb} v_{pqcd} \right\|_{H^{s}(\mathbb{S}^{n-1})} \leqslant C \sum \|u_{manb}\|_{H^{s}(\mathbb{S}^{n-1})} \|v_{pqcd}\|_{H^{s}(\mathbb{S}^{n-1})}.$$

We therefore find

$$\sum_{M,N,A,B} (1+M)^{2\alpha} (1+N)^{2\alpha} \left\| \sum u_{manb} v_{pqcd} \right\|_{H^{s}(\mathbb{S}^{n-1})}^{2} \\
\leqslant C \sum_{M,N,A,B} (1+M)^{2\alpha} (1+N)^{2\alpha} \sum \|u_{manb}\|_{H^{s}(\mathbb{S}^{n-1})}^{2} \|v_{pqcd}\|_{H^{s}(\mathbb{S}^{n-1})}^{2} \\
\leqslant C \left(\sum_{m,n,a,b} (1+m)^{2\alpha} (1+n)^{2\alpha} \|u_{manb}\|_{H^{s}(\mathbb{S}^{n-1})}^{2} \right) \left(\sum_{p,q,c,d} (1+p)^{2\alpha} (1+q)^{2\alpha} \|v_{pqcd}\|_{H^{s}(\mathbb{S}^{n-1})}^{2} \right) \\
= \|u\|_{A_{s,\alpha}}^{2} \|v\|_{A_{s,\alpha}}^{2}$$

where we again used Cauchy product formula.

For higher derivatives, we use the (formal) equality $\nabla^l(uv) = \sum_{k=0}^l \binom{l}{k} \nabla^k u \nabla^{l-k} v$ and just apply the previous argument to each term of the sum. The generalization to tensors and multilinear operations is straightforward by looking at the tensors in coordinates.

Let us finally turn to the last point. Equipping the pointwise norm of symmetric 2-tensors seen as matrices on the tangent spaces with a Banach algebra norm yields the same result and the control:

$$||u \circ v||_{\mathcal{A}_{s,\alpha}} \leqslant C||u||_{\mathcal{A}_{s,\alpha}}||v||_{0,\epsilon}$$

where \circ is pointwise the matrix composition on each tangent space. From the expression

$$(\mathbf{e} + h)^{-1} = \sum_{k=0}^{+\infty} (-h)^k,$$

where $(-h)^k = (-h) \circ \ldots \circ (-h)$, we find the result.

3.2 Boundary conditions.

Definition 3.7. Let $h \in \mathcal{A}_{s,\alpha}^{k+2}$ be a 2-tensor. We define $\pi_H h$ as the unique harmonic symmetric 2-tensor whose restriction to $r = r_1$ and $r = r_2$ is equal to the restriction of h on the same spheres.

Without loss of generality, for simpler formulas, we will restrict ourselves to the situation where $r_1 = \epsilon$ and $r_2 = \epsilon^{-1}$. The general situation of an annulus $\mathcal{A}_e(r_1', r_2')$ is reduced to this by a change of variable $r' = \sqrt{r_1' r_2'}$ which gives $\epsilon = \sqrt{\frac{r_1'}{r_2'}}$.

We can explicit the projection π_H in the following form

$$\pi_H h = \sum_{k \ge 0} (\epsilon r_e)^k \tilde{H}_k^+ + (\epsilon^{-1} r_e)^{-2-k} \tilde{H}_k^-$$
 (13)

where the \tilde{H}_k^{\pm} are homogeneous with $|\tilde{H}_k^+|_{g_e} \sim r_e^0$ and whose coefficients (in the canonical basis of \mathbb{R}^4), once restricted to the sphere are eigenvectors associated to -k(k+2). Indeed, if we decompose in spherical harmonics $h_{|S_e(\epsilon)} =: \sum_k H_k(\epsilon)$ and $h_{|S_e(\epsilon^{-1})} =: \sum_k H_k(\epsilon^{-1})$, we have the system

$$\begin{cases}
H_k(\epsilon^{-1}) = \tilde{H}_k^+ + \epsilon^{4+2k} \tilde{H}_k^-, \\
H_k(\epsilon) = \epsilon^{2k} \tilde{H}_k^+ + \tilde{H}_k^-,
\end{cases}$$
(14)

and therefore,

$$\begin{cases}
\tilde{H}_k^+ = \frac{1}{1 - \epsilon^{4+4k}} \left(H_k(\epsilon^{-1}) - \epsilon^{4+2k} H_k(\epsilon) \right), \\
\tilde{H}_k^- = \frac{1}{1 - \epsilon^{4+4k}} \left(H_k(\epsilon) - \epsilon^{2k} H_k(\epsilon^{-1}) \right),
\end{cases}$$
(15)

Proposition 3.8. The projection $\pi_H: \mathcal{A}^{k+2}_{s,\alpha} \to \mathcal{A}^{k+2}_{s,\alpha}$ is continuous.

Proof. Let us start by writing the explicit developments of the boundary conditions $h_{S(\epsilon)\cup S(\epsilon^{-1})}$ for $h\in\mathcal{T}$ with

$$h(r,x) := \sum_{m,a,n,b} \left(\frac{r}{\epsilon^{-1}}\right)^m \left(\frac{r}{\epsilon}\right)^{-n} \log^a \left(\frac{r}{\epsilon^{-1}}\right) \log^b \left(\frac{r}{\epsilon}\right) h_{manb}(x)$$

At $S(\epsilon)$, with the above notations of we have:

$$H_l(\epsilon) = \sum_{m,n,b} \epsilon^{2n} \log^b(\epsilon^{-2}) h_{m,n;l}^{0,b}$$
(16)

and similarly

$$H_l(\epsilon^{-1}) = \sum_{m,n,a} \epsilon^{2m} \log^a(\epsilon^2) h_{m,n;l}^{a,0}.$$
 (17)

Using (15), we find that the $\|\tilde{H}_k^{\pm}\|_{H^s(\mathbb{S}^3)}$ are controlled linearly by the norm of the $||H_k(\epsilon^{\pm 1})||_{H^s(\mathbb{S}^3)}$ for $\epsilon < \epsilon_0 1$ uniformly in ϵ_0 . Now we have the expressions:

$$H_k(\epsilon^{-1}) = \sum_{m,n,a,0} \epsilon^{2m} \log^a(\epsilon^2) h_{m,n,a,0}^{[k]},$$

where $h_{m,n,a,0}^{[k]}$ denotes the L^2 -projection on the k-th harmonic of $h_{m,n,a,0}$. We therefore have $\sum_k (1+k)^{2\alpha} \|H_k(\epsilon^{-1})\|_{H^s}^2 \leq \|h\|_{s,\alpha}^2$. There is a similar formula for $H_k(\epsilon)$ and we also find $\sum_k (1+k)^{2\alpha} \|H_k(\epsilon)\|_{H^s}^2 \leq \|h\|_{s,\alpha}^2$.

Now, we have:

$$\|\pi_{H}h\|_{s,\alpha}^{2} = \sum_{k} (1+k)^{2\alpha} \left(\|\tilde{H}_{k}^{+}\|_{H^{s}}^{2} + \|\tilde{H}_{k}^{+}\|_{H^{s}}^{2} \right)$$

$$\leq C \sum_{k} (1+k)^{2\alpha} \left(\|H_{k}(\epsilon^{-1})\|_{H^{s}}^{2} + \|H_{k}(\epsilon)\|_{H^{s}}^{2} \right)$$

$$\leq 2C \|h\|_{s,\alpha}^{2}.$$

In particular, the linear subspace $\mathring{A}_{s,\alpha}^{k+2} = \ker_{\mathcal{A}_{s,\alpha}^{k+2}} \pi_H$ is closed and therefore a (sub)Banach space.

log-analytic maps between Banach spaces 4

Inverse function theorem, strategy of Buffoni-Toland from the techniques used to prove Weierstrass division theorem for converging power series, cite Lojasiewicz-Maszczyk-Rusek

** Applications: log-analytic implicit function theorem, composition of log-analytic functions is log-analytic.

Let us extend the classical inverse and implicit function theorems for real-analytic maps to maps with *converging* polyhomogeneous developments. We mostly follow the strategy of [?] and extend it to the presence of powers of logarithms.

Let X and Y be Banach spaces (over \mathbb{R}) and $U \subset X$ open. We say that $f : \mathbb{R} \times U \to Y$ is real-analytic at x_0 if for $||x - x_0||$ small enough, one has:

$$f(x) = f(x_0) + \sum_{k=1}^{\infty} m_k (x - x_0)^k$$

where the different $m_k: X^k \to Y$ are symmetric k-linear and satisfy: there exists r > 0 such that for all k,

$$\sup_{k\geqslant 1}r^k\|m_k\|<+\infty,$$

where $||m_k|| := \sup_{\forall l, ||x_l|| \leq 1} ||m_k(x_1, ..., x_k)||$. The supremum of the r as above is the radius of convergence of f at x_0 .

We say that $F: (-\epsilon, \epsilon) \times U \to Y$ for $\epsilon > 0$ is log-analytic at x_0 if there exists $f: (-\epsilon, \epsilon) \times (-\epsilon \log \epsilon, \epsilon \log \epsilon) \times U \to Y$ real-analytic at $(0, 0, x_0)$ such that

$$F(t,x) = f(s, s \log|s|, x)$$

for all $s \in (-\epsilon, \epsilon)$ and $x \in U$.

It might be some $s \log^{\alpha} s$ instead

Definition 4.1. More generally, we say that $F: \mathcal{U} \subset X \to Y$ is log-analytic if around each $x_0 \in X$, there exists a finite linearly independent family of vectors $e_1, ..., e_n \in X$ and a complement X' such that

$$\mathbb{R}e_1 \oplus \ldots \oplus \mathbb{R}e_n \oplus X' = X$$

such that

$$F(s_1e_1 + ... + s_ne_n + x') = f(s_1, s_1 \log |s_1|, ..., s_n, s_n \log |s_n|, x')$$

for $f: \mathbb{R}^{2n} \times X'$ real-analytic on the associated neighborhood of x_0 .

Is that a good definition?

4.1 log-analytic inverse and implicit function theorems

Let $(E_r, \|\cdot\|_r)$ be the Banach space of functions $u: B_{\mathbb{R}\times X}(0, r^2) \times B_{\mathbb{R}\times X}(0, r) \to Y$ with

$$u((s,x),(t,y)) = \sum_{m,n,a,b \ge 0} u_{m,n}^{a,b}(x,y)s^m \log^a |s| \cdot t^n \log^b |t|,$$

the number of vectors clearly depends on the point

We should add a bound on a, b, probably $a \leq m$ and $b \leq n$

where $u_{m,n}^{a,b}(x,y) = \sum_{p,q} u_{m,n;p,q}^{a,b} x^p y^q$ is real-analytic from $X \times X$ to Y

$$||u||_r = \sum_{m,n,a,b,p,q \ge 0} ||u_{m,n;p,q}^{a,b}||_r^{2(m+p)+(n+q)}$$

which can also be seen as:

$$||u||_r = \sum_{m,n,a,b \ge 0} ||u_{m,n}^{a,b}||_r r^{2m+n},$$

where

$$||u_{m,n}^{a,b}||_r := \sum_{p,q \ge 0} ||u_{m,n;p,q}^{a,b}||_r^{2p+q}$$

as in [?].

Denote

$$F_r := \{ u \in E_r, u((s, x); (0, 0)) = 0, \ \forall (s, x) \} = \{ u \in E_r, u_{m,0;p,0}^{a,b} = 0, \ \forall m, p, a, b \}.$$

Following [?], we define for any $w \in E_r$ and $u \in F_r$

$$L_w u((s,x),(t,y)) = \partial_{(t,y)} u[(s,x),(t,y)] w((s,x),(t,y)) - \partial_{(t,y)} u[(s,x),(0,0)] w((s,x),(0,0)).$$

We will also denote $w_0((s, x), (t, y)) = (t, y)$.

Let us then define a *linear* operator: $L(u): F_r \to F_r$ which is chosen to satisfy: $L_{w_0} \circ L = I_{F_r}$, the identity of F_r , that is:

$$\partial_{(t,y)} \left(L(u) \right) \left[(s,x), (t,y) \right] (t,y) = \sum_{m,n,a,b,p,q \geqslant 0, n+q \geqslant 1} u_{m,n;p,q}^{a,b} x^p y^q s^m \log^a |s| \cdot t^n \log^b |t|$$
 (18)

thanks to the formula:

$$\partial_t t^n \log^b |t| = nt^{n-1} \log^b |t| + bt^{n-1} \log^{b-1} |t|$$

for t > 0, as well as $y\partial_y y^n = ny^n$. Finding the right linear transformation L on the coefficients $u_{m,n}^{a,b}$ amounts to inverting the $(b_n + 2) \times (b_n + 2)$ matrix with diagonal (n,...,n) and subdiagonal $(0,1,...,b_n-1,b_n)$, where b_n is the maximum of b such that there is a (non zero) $t^n \log^b |t|$ term in the sum. The coefficients seem to be bounded by $\max(1/n,b_n/n)$.

We then have the following property.

needed

if

Lemma 4.2. The linear operator $L_w \circ L : F_r \to F_r$ satisfies:

$$||L_w \circ L|| \leqslant \frac{||w||_r}{r}.$$

Proof. As in [?], using (18), for $u \in F_r$, with

$$u((s,x),(t,y)) = \sum_{m,n,a,b \ge 0} u_{m,n}^{a,b}(x,y)s^m \log^a |s| \cdot t^n \log^b |t|,$$

and for $p', q', a', b' \ge 0$, define

$$w = x^{p'}y^{q'}s^{m'}\log^{a'}|s| \cdot t^{n'}\log^{b'}|t|,$$

we find:

$$L_{w} \circ Lu((s,x),(t,y)) = \sum_{\substack{m,n,a,b,p,q \geqslant 0, \ n+q \geqslant 1}} u_{m,n;p,q}^{a,b} x^{p} y^{q} s^{m} \log^{a} |s| \cdot t^{n} \log^{b} |t|$$

$$\times x^{p'} y^{q'} s^{m'} \log^{a'} |s| \cdot t^{n'} \log^{b'} |t|$$

$$- \sum_{\substack{m \geqslant 0,a \geqslant 0}} (u_{m,1;p,0}^{a,b} + u_{m,0;p,1}^{a,b}) x^{p} s^{m} \log^{a} |s|$$

$$\times x^{p'} s^{m'} \log^{a'} |s| \epsilon(q',b'),$$

where $\epsilon(q',b')=1$ if (q',b')=(0,0) and $\epsilon(q',b')=0$ otherwise.

And we therefore find:

$$||L_{w} \circ Lu||_{r} \leqslant \sum_{M \geqslant 0, N \geqslant 1} r^{2M+N} \sum_{m+p+p'=M, n+q+q'=N+1} ||u_{m,n;p,q}^{a,b}||$$

$$= \frac{1}{r} \Big(\sum_{m,p,n,q \geqslant 0, n+q \geqslant 1} r^{2(m+p)+(n+q)} ||u_{m,n;p,q}^{a,b}|| \Big) r^{p'+q'}$$

$$= \frac{||w||_{r} ||u||_{r}}{r}$$

By bilinearity of $(u, w) \mapsto L_w \circ Lu$, and triangle inequality we conclude that for arbitrary $(w, u) \in E_r \times F_r$

$$||L_w \circ Lu||_r \leqslant \frac{||w||_r ||u||_r}{r}.$$

This lets us prove the main step of the proof of our inverse and implicit function theorems in next subsection.

Proposition 4.3. Suppose that F is a log-analytic map from a neighborhood of $\mathbb{R} \times X$ to itself and that F(0) = 0 as well as $dF[0] = I_{\mathbb{R} \times X}$, the identity of $\mathbb{R} \times X$. Then, there exist open neighborhoods \mathcal{U} and \mathcal{V} of $0 \in \mathbb{R} \times X$ and a log-analytic function $G: V \to \mathbb{R} \times X$ such that we have:

$$F(t,y) = (s,x), (t,y) \in \mathcal{U} \iff G(s,x) = (t,y), x \in \mathcal{V}.$$

Proof. For r > 0 sufficiently small, let $v, w \in E_r$ defined for $((s, x), (t, y)) \in B_{\mathbb{R} \times X}(0, r^2) \times B_{\mathbb{R} \times X}(0, r)$ by:

$$v((s,x),(t,y)) := F(t,y) - (s,x)$$
 and $w((s,x),(t,y)) = v((s,x),(t,y)) - (t,y)$.

And denote the coefficients of the expansion of F:

$$F(t,y) = \sum_{n,b,p \geqslant 0} F_{n;p}^b t^n \log^b |t| y^p.$$

Then,

$$w((s,x),(t,y)) = -(s,x) + \sum_{b\geqslant 0, n+p\geqslant 2} F_{n;p}^b t^n \log^b |t| y^p$$

because $dF[0] = F = I_{\mathbb{R} \times X}$. This yields:

$$||w||_r \leqslant r^2 + \sum_{b \ge 0, n+n \ge 2} ||F_{n;p}^b|| r^{n+p} \leqslant r^2 C(F)$$

for some constant C(F) > 0.

Now, by definition of v, w and w_0 , and (18) we have: $L_v \circ L - I_{\mathbb{R} \times X} = L_w \circ L$. In particular, by Lemma 4.2, we find:

$$||L_v \circ L - I_{\mathbb{R} \times X}|| \leqslant rC(F)$$

for r > 0 sufficiently small. Therefore, choosing r small enough, $L_v \circ L$ is an isomorphism of F_r and we can define u_0 uniquely by:

$$L_v \circ Lu_0((s, x), (t, y)) = (t, y)$$
 (19)

As in [?], by defining

$$G(s,x) := \partial_{(t,y)}(Lu_0)[(s,x),(0,0)](s,x)$$
(20)

we find:

$$(t,y) - G(s,x) = L_v \circ Lu_0((s,x),(t,y)) - \partial_{(t,y)}(Lu_0)[(s,x),(0,0)](s,x)$$

$$= L_v \circ Lu_0((s,x),(t,y)) + \partial_{(t,y)}(Lu_0)[(s,x),(0,0)]v((s,x),(0,0))$$

$$= \partial_{(t,y)}(Lu_0)[(s,x),(t,y)](v((s,x),(t,y)))$$

$$= \partial_{(t,y)}(Lu_0)[(s,x),(t,y)](F(t,y) - (s,x))$$

where we successively used (19) and (20), the fact that v((s, x), (0, 0)) = -(s, x), the definition of L_v , and the definition of v.

In particular, as in the statement of the Proposition, in well-chosen neighborhoods of 0, F(t,y) = (s,x) if and only if G(s,x) = (t,y) because $\partial_{(t,y)}(Lu_0)[(s,x),(t,y)]$ is a bijection. It is clear that G is log-analytic and this proves the proposition.

4.2 Inverse and implicit function theorems

Up to a translation from $x_0 \in X$ and a linear transformation by $(dF[x_0])^{-1}$, we have the following general inverse function theorem.

Theorem 4.4. Let $F : \mathbb{R} \times X \to Y$ be a log-analytic map and assume that the linearization of F at $(s_0, x_0) \in \mathbb{R} \times X$ is invertible. Then there exists a local inverse $G : \mathcal{V} \subset Y \mapsto \mathcal{U} \subset \mathbb{R} \times X$ which is log-analytic in the following sense:

$$G = \tilde{G} \circ (d_{x_0} F)^{-1}$$

where $\tilde{G}: \mathbb{R} \times X \to \mathbb{R} \times X$ is log-analytic.

We need no logarithm at the linear level linearization – The " \mathbb{R} " factor on the image Y, where logarithmic terms may appear is the image of the \mathbb{R} factor of $\mathbb{R} \times X$ by the linearization of F.

This classically also implies the following implicit function theorem.

Theorem 4.5. Let X, Y and Z be Banach spaces, and let $\mathcal{U} \subset X \times Y$ be open, $(x_0, y_0) \subset X \times Y$ and $F : \mathcal{U} \to Z$ be log-analytic. Assume that the partial derivative $\partial_x F[x_0, y_0]$ is a homeomorphism.

Then, there exists an open neighborhood $\mathcal{V} \subset Y$ of y_0 , $\mathcal{W} \subset \mathcal{U}$ neighborhood of (x_0, y_0) and $\phi : \mathcal{V} \to X$ log-analytic such that:

$$F^{-1}(\{F(x_0, y_0)\}) \cap W = \{(\phi(y), y), y \in \mathcal{V}\}.$$

Proof. The idea is to invert H(x,y) := (y, F(x,y))...

Another consequence which might very well be important for us is the fact that the composition of log-analytic maps is also log-analytic.

Theorem 4.6. A composition of log-analytic maps is log-analytic.

5 Cauchy-data matching for the projected problem

5.1 Linear problem on each region

5.1.1 Linear problem on the ALE and orbifold spaces

Linearization of Einstein operator on a compact orbifold. On an orbifold, the linear operator $L_o: \tilde{\mathbf{O}}(g_o) \oplus H^{s+1/2}(M_o) \cap \tilde{\mathbf{O}}(g_o)^{\perp} \to H^{s-3/2}(M_o)$,

$$L_o(\mathbf{o}_o, h) \mapsto$$

is an isomorphism.

The leading terms of the elements of the kernel on the orbifold: if there is some ϕ_m associated to the m-th eigenvalue of the spherical Laplacian, then the associated element of the kernel of L_{g_o} has a development:

$$r^{-2-m}\phi_m + \mathcal{O}(r^{-2-m+1})$$

hence, restricted to some small r, one mostly sees that first term (it's the only one remaining as $r \to 0$)...

- ** Kernel/cokernel of the linearization on the orbifold/ALE
- ** Kernel/cokernel of the linearization on the orbifold/ALE with boundary
- ** Linear Dirichlet to Neumann problem on the orbifold/ALE with boundary
- ** invertibility for the Linear Dirichlet to Neumann problem projected on the high frequencies

Linearization on an ALE space. On an ALE space, the linear operator L_Z : $\tilde{\mathbf{O}}(g_Z) \oplus H^{s+1/2}(Z) \cap \tilde{\mathbf{O}}(g_Z)^{\perp} \to H^{s-3/2}(Z)$,

$$L_Z(\mathbf{o}_Z,h) \mapsto$$

is an isomorphism.

Here, the leading term for the Dirichlet problem from some ϕ_m is this time in $r^m\phi_m + \mathcal{O}(r^{m-1})$.

5.1.2 Linear problem on a flat annulus

- ** Explicit solution
 - ** Kernel/cokernel
- ** invertibility for the Linear Dirichlet to Neumann problem projected on the high frequencies

See notations:

Let us now consider the Dirichlet-to-Neumann map obtained on the annulus.

Let $A_e(r_1, r_2)$ be a flat annulus and consider $H(r_1)$ and $H(r_2)$ be functions in $H^s(\mathbb{S}^3)$. We define H the unique harmonic function with Dirichlet conditions $H(r_1)$ and $H(r_2)$ at $r = r_1$ and $r = r_2$. We then denote $H'(r_1)$ and $H'(r_2)$ as the restrictions of $\nabla_{r\partial_r}H$ respectively at $r = r_1$ and $r = r_2$.

Definition 5.1 (Linear Dirichlet-to-Neumann map on a flat annulus). We define DtN: $H^s(\mathbb{S}^3)^2 \to H^{s-1}(\mathbb{S}^3)^2$, by

$$DtN: (H(r_1), H(r_2)) \mapsto (H'(r_1), H'(r_2)).$$

Definition 5.2 (Boundary conditions H_0^s and H_{Im}^{s-1}). We define H_0^s as the subspace of $H^s(\mathbb{S}^3)^2$ consisting of functions $(H(r_1), H(r_2))$ such that the average of $H(r_1)$ is equal to the opposite of the average of $H(r_2)$.

We also define H_{Im}^{s-1} as the subspace of $H^{s-1}(\mathbb{S}^3)^2$ consisting of functions $(H(r_1), H(r_2))$ such that the average of $H(r_1)$ is equal to the average of $-\epsilon^4 H(r_2)$.

Remark 5.3. This represents a complement of constant functions which will be both the kernel and cokernel of our Dirichlet-to-Neumann operator DtN.

Proposition 5.4. The map $DtN: H_0^s \to H_{Im}^{s-1}$ is a continuous linear isomorphism.

Proof. As in the previous section, let us limit ourselves to the situation when $r_1 = \epsilon$ and $r_2 = \epsilon^{-1}$ for some $0 < \epsilon < 1$.

We have an explicit expression of H by (15). This directly gives us the following values:

$$H'(\epsilon) = \sum_{k} \frac{k\epsilon^{2k}}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon^{-1}) - \epsilon^{4+2k} H_k(\epsilon) \Big)$$

$$+ \frac{-2 - k}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon) - \epsilon^{2k} H_k(\epsilon^{-1}) \Big)$$

$$= \sum_{k} \frac{(2 + 2k)\epsilon^{2k}}{1 - \epsilon^{4+4k}} H_k(\epsilon^{-1})$$

$$+ \frac{-2 - k - k\epsilon^{4+4k}}{1 - \epsilon^{4+4k}} H_k(\epsilon).$$

and

$$H'(\epsilon^{-1}) = \sum_{k} \frac{k}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon^{-1}) - \epsilon^{4+2k} H_k(\epsilon) \Big)$$

$$+ \frac{(-2 - k)\epsilon^{4+2k}}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon) - \epsilon^{2k} H_k(\epsilon^{-1}) \Big)$$

$$= \sum_{k} \frac{k + (2 + k)\epsilon^{4+4k}}{1 - \epsilon^{4+4k}} H_k(\epsilon^{-1})$$

$$+ \frac{(-2 - 2k)\epsilon^{4+2k}}{1 - \epsilon^{4+4k}} H_k(\epsilon).$$

We therefore see that for $\epsilon > 0$ small enough and $k \ge 1$, the map $(H_k(\epsilon), H_k(\epsilon^{-1})) \to (H'_k(\epsilon), H'_k(\epsilon^{-1}))$ is invertible, where $(H'_k(\epsilon), H'_k(\epsilon^{-1}))$ is the projection on the k-th eigenvalue of the spherical Laplacian.

There remains to study the case of k=0 separately to determine the kernel and cokernel of our Dirichlet-to-Neumann operator. Let us first rewrite the associated components:

$$H_0'(\epsilon) = \frac{-2}{1 - \epsilon^4} \Big(H_0(\epsilon) - H_0(\epsilon^{-1}) \Big),$$

and

$$H'_0(\epsilon^{-1}) = \frac{-2\epsilon^4}{1 - \epsilon^4} (H_0(\epsilon) - H_0(\epsilon^{-1})).$$

We see that the kernel of the operator corresponds to restrictions of constant 2-tensors, i.e. $H_0(\epsilon) = H_0(\epsilon^{-1})$. We also see that the cokernel is composed of elements satisfying $H'_0(\epsilon) = -\epsilon^4 H'_0(\epsilon^{-1})$.

5.2 The non linear situation

** Application of log-analytic implicit function theorem

6 Reduction to finite dimensions, and Einstein metrics modulo obstructions

** Linear Einstein modulo obstruction problem on each space

- ** Resulting DtN problem
- ** Invertibility of linear DtN problem
- ** Application of log-analytic implicit function theorem

6.0.1 Cut-off of the kernel

To arrange ->

Let us define the projection of $\mathbf{O}(g_o)$ and the $\mathbf{O}(\mathbf{b}_j)$ on (M, g^D) by cut-off:

$$\tilde{\mathbf{O}}(g_o) := \chi_{M_o(b\epsilon)} \mathbf{O}(g_o), \tag{21}$$

$$\tilde{\mathbf{O}}(\mathbf{b}_j) := \chi_{N_j(b\epsilon)} \mathbf{O}(\mathbf{b}_j), \text{ and } \tilde{\mathbf{O}}_0(\mathbf{b}_j) := \chi_{N_j(b\epsilon)} \mathbf{O}_0(\mathbf{b}_j)$$
 (22)

and finally the approximate kernel on (M, g_t^D) ,

$$\tilde{\mathbf{O}}(g^D) := \bigoplus_j \tilde{\mathbf{O}}(\mathbf{b}_j) \oplus \tilde{\mathbf{O}}(g_o) \text{ and } \tilde{\mathbf{O}}_0(g^D) := \bigoplus_j \tilde{\mathbf{O}}_0(\mathbf{b}_j) \oplus \tilde{\mathbf{O}}(g_o).$$
 (23)

We are interested in the operator $\Psi_{g^D}: \left(g^D + C^{2,\alpha}_{\beta,*}(g^D) \cap \tilde{\mathbf{O}}(g^D)^{\perp}\right) \times \tilde{\mathbf{O}}(g^D) \to r_D^{-2} C^{\alpha}_{\beta}(g^D),$

$$\Psi_{q^D}(g,\tilde{\mathbf{o}}) := \Phi_{q^D}(g) + \tilde{\mathbf{o}}. \tag{24}$$

6.0.2 Einstein modulo obstructions metrics

Definition 6.1 (Einstein modulo obstructions metric). For any $(t, v) \in \mathbb{R}^+_* \times \tilde{\mathbf{O}}_0(g^D)$ close enough to (0, 0) there exists a unique solution $\hat{g}_{t,v}$ to the equation

$$\Phi(\hat{g}_{t,v}) \in \tilde{\mathbf{O}}(g_t^D),$$

satisfying the following conditions:

1.
$$\|\hat{g}_{t,v} - g_t^D\|_{C^{2,\alpha}_{\beta,*}} \leq C(t^2 + \|v\|_{L^2}^2)$$
, for some $C > 0$,

2.
$$\hat{g}_{t,v} - (g_t^D + v)$$
 is $L^2(g_t^D)$ -orthogonal to $\tilde{\mathbf{O}}_0(g_t^D)$, and

3.
$$\tilde{B}_{q_{t}^{D}}\hat{g}_{t,v}=0$$
.

It is called an Einstein modulo obstructions desingularization of (M_o, \mathbf{g}_o) . We will denote $-\hat{\mathbf{o}}_{t,v} = \mathbf{\Phi}(\hat{g}_{t,v}) \in \tilde{\mathbf{O}}(g_t^D)$, for which $\mathbf{\Psi}_{g_t^D}(\hat{g}_{t,v}, \hat{\mathbf{o}}_{t,v}) = 0$.

Remark 6.2. Note that if the obstructions vanish for a metric $\hat{g}_{t,v}$, then it is Einstein. Indeed, we know that $\tilde{B}_{\hat{g}_{t,v}}E(\hat{g}_{t,v})=0$ and by the first condition, $\hat{g}_{t,v}$ and g^D are very close to each other hence $\tilde{B}_{\hat{g}_{t,v}}\delta_{g_t^D}^*$ restricted to the orthogonal of $\tilde{\mathbf{K}}_o$ (the image of $\tilde{B}_{\hat{g}_{t,v}}$) is injective.

A Einstein modulo obstructions desingularizations

A.1 Orbifolds, ALE spaces and naïve desingularizations

A.1.1 Orbifolds and ALE spaces

We start by defining our model spaces asymptotic to some quotient of the Euclidean space $(\mathbb{R}^4/\Gamma, \mathbf{e})$ for $\Gamma \subset SO(4)$ acting freely on \mathbb{S}^3 . We also denote $r = d_{\mathbf{e}}(0, .)$.

Einstein metrics and their deformations on an orbifold.

Definition A.1 (Orbifold (with isolated singularities)). We will say that a metric space (M_o, g_o) is an orbifold if there exists $\epsilon_0 > 0$ and a finite number of points $(p_k)_k$ of M_o which we will call singular such that we have the following:

- 1. the space $(M_o \setminus \{p_k\}_k, g_o)$ is a Riemannian manifold,
- 2. for each singular point p_k of M_o , there exists a neighborhood of p_k , $U_k \subset M_o$, a finite subgroup acting freely on the sphere, $\Gamma_k \subset SO(4)$, and a diffeomorphism $\Phi_k : B_{\mathbf{e}}(0, \epsilon_0) \subset \mathbb{R}^4/\Gamma_k \to U_k \subset M_o$ for which, for any $l \in \mathbb{N}$, there exists $C_l > 0$ such that

$$r^l |\nabla^l (\Phi_k^* g_o - \mathbf{e})|_{C^2(\mathbf{e})} \leqslant C_l r^2.$$

Definition A.2 (The function r_o on an orbifold). We define r_o , a smooth function on M_o satisfying $\Phi_k^* r_o := r$ on each U_k , and such that on $M_o \setminus U_k$, we have $\epsilon_0 < r_o < 1$ (the different choices will be equivalent for our applications).

We will denote, for $0 < \epsilon \leq \epsilon_0$,

$$M_o(\epsilon) := \{r_o > \epsilon\} = M_o \setminus \Big(\bigcup_k \Phi_k(B_{\mathbf{e}}(0, \epsilon))\Big).$$

Definition A.3 (Infinitesimal deformations of an Einstein orbifold metric). Let (M_o, g_o) be an Einstein orbifold. We define $\mathbf{O}(g_o)$ as the finite dimensional kernel of the elliptic operator $P_{g_o} := \frac{1}{2} \nabla_{g_o}^* \nabla_{g_o} - \mathring{\mathbf{R}}_{g_o}$ on 2-tensors of $L^2(g_o)$, where $\mathring{\mathbf{R}}(h)(X,Y) = \sum_i h(\operatorname{Rm}(e_i, X)Y, e_i)$,.

ALE Ricci-flat metrics and their deformations. Let us now turn to ALE Ricci-flat metrics.

Definition A.4 (ALE orbifold (with isolated singularities and one end)). An ALE orbifold (N,b) is a orbifold for which there exists $\epsilon_0 > 0$ and a compact $K \subset N$ for which there exists a diffeomorphism $\Psi_{\infty} : (\mathbb{R}^4/\Gamma_{\infty}) \backslash B_{\mathbf{e}}(0,\epsilon_0^{-1}) \to N \backslash K$ such that we have

$$r^l |\nabla^l (\Psi_{\infty}^* b - \mathbf{e})|_{C^2(\mathbf{e})} \leqslant C_l r^{-4}$$

Definition A.5 (The function r_b on an ALE orbifold). We define r_b a smooth function on N satisfying $\Psi_k^* r_b := r$ on each neighborhood U_k of a singular point of definition A.1, and $\Psi_\infty^* r_b := r$ on U_∞ , and such that $\epsilon_0 < r_b < \epsilon_0^{-1}$ on the rest of N (the different choices are equivalent for our applications).

For $0 < \epsilon \leq \epsilon_0$, we will denote

$$N(\epsilon) := \{ \epsilon < r_b < \epsilon^{-1} \} = N \setminus \Big(\bigcup_k \Psi_k(B_{\mathbf{e}}(0, \epsilon)) \cup \Psi_{\infty} \Big((\mathbb{R}^4 / \Gamma_{\infty}) \setminus B_{\mathbf{e}}(0, \epsilon^{-1}) \Big) \Big).$$

Definition A.6 (Infinitesimal deformations of Ricci-flat ALE orbifolds). Let (N, \mathbf{b}) be a Ricci-flat ALE orbifold. We define the space $\mathbf{O}(\mathbf{b})$ as the kernel of the operator $P_{\mathbf{b}} := \frac{1}{2} \nabla_{\mathbf{b}}^* \nabla_{\mathbf{b}} - \mathring{\mathbf{R}}_{\mathbf{b}}$ on $L^2(\mathbf{b})$.

For any $h \in \mathbf{O}(\mathbf{b})$, we have

- 1. $h = \mathcal{O}(r_b^{-4}),$
- 2. $\delta_{\mathbf{b}}h = 0$, and
- 3. $tr_{\bf h}h = 0$.

There is a particular infinitesimal Ricci-flat ALE deformation by rescaling and reparametrization which we denote \mathbf{o}_1 . It is of the form $\mathcal{L}_X \mathbf{b}$ for a harmonic vector field X asymptotic to $r_b \partial_{r_b}$ at infinity. It is linked to the notion of reduced volume of Ricci-flat ALE metric introduced in [?], see [?].

Definition A.7 (Normalized Ricci-flat ALE metric). A normalized Ricci-flat ALE orbifold is a Ricci-flat ALE metric with reduced volume -1.

This prevents rescaling of the metric and Ricci-flat ALE deformation in the direction \mathbf{o}_1 . We will denote $\mathbf{O}_0(\mathbf{b})$ the $L^2(\mathbf{b})$ -orthogonal of \mathbf{o}_1 in $\mathbf{O}(\mathbf{b})$. These are the infinitesimal Ricci-flat ALE deformations preserving the reduced volume at first order.

A.2 Einstein modulo obstructions metrics

B Definition of the norm on an annulus

B.1 Solving the Dirichlet problem

Lemma B.1. The map $\Phi: \mathcal{A}^{k+2}_{s,\alpha} \to \mathcal{A}^k_{s,\alpha}$ defined by

$$\Phi: h \mapsto \operatorname{Ric}(\mathbf{e} + h) + \delta_{\mathbf{e}}^* B_{\mathbf{e}}(h)$$

is log-analytic. Its linearization at 0 restricted to $\mathring{A}_{s,\alpha}^{k+2}$ is moreover a homeomorphism.

Proof. Looking at the expressions of Ric and $\delta_{\mathbf{e}}^* B_{\mathbf{e}}$ in coordinates, we find:

$$\operatorname{Ric}(\mathbf{e}+h) + \delta_{\mathbf{e}}^* B_{\mathbf{e}}(h) = Q_1 \Big((\mathbf{e}+h)^{-1}, \nabla^2 h \Big) + Q_2 \Big((\mathbf{e}+h)^{-1}, (\mathbf{e}+h)^{-1}, \nabla h, \nabla h \Big).$$

The composition of log-analytic functions is log-analytic by Theorem ??. Therefore, \blacksquare by the above Proposition 3.6, the map Φ is indeed a log-analytic map between Banach spaces.

Now, the linearization of Φ at 0 is simply $-\frac{1}{2}\Delta_{\mathbb{R}^4}: \mathring{A}^{k+2}_{s,\alpha} \to \mathcal{A}^k_{s,\alpha}$ which is continuous by definition of the norms. It is moreover injective on symmetric 2-tensors satisfying $h_{|\mathbb{S}^n} \equiv 0$ by the classification of harmonic tensors (or functions) on $\mathbb{R}\backslash B(0,\epsilon)$.

It is also surjective because we allowed logarithmic terms, see for instance the proof of Lemma 3.5, where the inverse is explicited – up to adding harmonic terms to ensure that the condition $h_{|\mathbb{S}^n} \equiv 0$ is satisfied. This inverse is moreover continuous by Banach's inverse theorem.

Let us define our operator $\underline{\Psi}: \mathcal{A}_{\epsilon,H}^{k+2} \times \mathcal{A}_{\epsilon,0}^{k+2} \to \mathcal{A}_{\epsilon}^{k}$ by:

$$\mathbf{\Psi}(H,h_0) := \mathbf{\Phi}(H,h_0).$$

Theorem B.2. For any H harmonic on the annulus $A_e(r_1, r_2)$, there exists a unique 2-tensor $h_0(H) \in \mathring{A}^{k+2}_{s,\alpha}$ such that

$$\Psi(H, h_0(H)) = 0.$$

Moreover, $H \mapsto h_0(H)$ is log-harmonic.

Revoir les notations et définir H *Proof.* The map Ψ is log-analytic and its linearization in the $\mathring{A}_{s,\alpha}^{k+2}$ direction is invertible by Lemma B.1. By our implicit function theorem Theorem ?? in the Appendix, there exists a log-analytic map $H \mapsto h_0(H)$ from $\mathcal{A}_{s,\alpha,H}^{k+2}$ to $\mathring{A}_{s,\alpha}^{k+2}$ in a neighborhood of 0 so that the set of zeroes of Ψ about (0,0) is parametrized by $\mathcal{A}_{s,\alpha,H}^{k+2}$ and given by:

$$\Psi(H, h_0(H))$$

for H in a neighborhood of $0 \in \mathcal{A}^{k+2}_{s,\alpha,H}$.

B.2 Dirichlet-to-Neumann map on the annulus

Let us now consider the Dirichlet-to-Neumann map obtained on the annulus.

B.2.1 The linear problem

Let us first consider the linear problem which is explicit and will be important to apply some inverse function theorem later on.

Let $A_e(r_1, r_2)$ be a flat annulus and consider $H(r_1)$ and $H(r_2)$ be functions in $H^s(\mathbb{S}^3)$. We define H the unique harmonic function with Dirichlet conditions $H(r_1)$ and $H(r_2)$ at $r = r_1$ and $r = r_2$. We then denote $H'(r_1)$ and $H'(r_2)$ as the restrictions of $\nabla_{r\partial_r}H$ respectively at $r = r_1$ and $r = r_2$.

Definition B.3 (Linear Dirichlet-to-Neumann map on a flat annulus). We define DtN: $H^s(\mathbb{S}^3)^2 \to H^{s-1}(\mathbb{S}^3)^2$, by

$$DtN: (H(r_1), H(r_2)) \mapsto (H'(r_1), H'(r_2)).$$

Definition B.4 (Boundary conditions H_0^s and H_{Im}^{s-1}). We define H_0^s as the subspace of $H^s(\mathbb{S}^3)^2$ consisting of functions $(H(r_1), H(r_2))$ such that the average of $H(r_1)$ is equal to the opposite of the average of $H(r_2)$.

We also define H_{Im}^{s-1} as the subspace of $H^{s-1}(\mathbb{S}^3)^2$ consisting of functions $(H(r_1), H(r_2))$ such that the average of $H(r_1)$ is equal to the average of $-\epsilon^4 H(r_2)$.

Remark B.5. This represents a complement of constant functions which will be both the kernel and cokernel of our Dirichlet-to-Neumann operator DtN.

Proposition B.6. The map $DtN: H_0^s \to H_{Im}^{s-1}$ is a continuous linear isomorphism.

Proof. As in the previous section, let us limit ourselves to the situation when $r_1 = \epsilon$ and $r_2 = \epsilon^{-1}$ for some $0 < \epsilon < 1$.

We have an explicit expression of H by (15). This directly gives us the following values:

$$H'(\epsilon) = \sum_{k} \frac{k\epsilon^{2k}}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon^{-1}) - \epsilon^{4+2k} H_k(\epsilon) \Big)$$

$$+ \frac{-2 - k}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon) - \epsilon^{2k} H_k(\epsilon^{-1}) \Big)$$

$$= \sum_{k} \frac{(2 + 2k)\epsilon^{2k}}{1 - \epsilon^{4+4k}} H_k(\epsilon^{-1})$$

$$+ \frac{-2 - k - k\epsilon^{4+4k}}{1 - \epsilon^{4+4k}} H_k(\epsilon).$$

and

$$H'(\epsilon^{-1}) = \sum_{k} \frac{k}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon^{-1}) - \epsilon^{4+2k} H_k(\epsilon) \Big)$$

$$+ \frac{(-2 - k)\epsilon^{4+2k}}{1 - \epsilon^{4+4k}} \Big(H_k(\epsilon) - \epsilon^{2k} H_k(\epsilon^{-1}) \Big)$$

$$= \sum_{k} \frac{k + (2 + k)\epsilon^{4+4k}}{1 - \epsilon^{4+4k}} H_k(\epsilon^{-1})$$

$$+ \frac{(-2 - 2k)\epsilon^{4+2k}}{1 - \epsilon^{4+4k}} H_k(\epsilon).$$

We therefore see that for $\epsilon > 0$ small enough and $k \ge 1$, the map $(H_k(\epsilon), H_k(\epsilon^{-1})) \to (H'_k(\epsilon), H'_k(\epsilon^{-1}))$ is invertible, where $(H'_k(\epsilon), H'_k(\epsilon^{-1}))$ is the projection on the k-th eigenvalue of the spherical Laplacian.

There remains to study the case of k=0 separately to determine the kernel and cokernel of our Dirichlet-to-Neumann operator. Let us first rewrite the associated components:

$$H_0'(\epsilon) = \frac{-2}{1 - \epsilon^4} \Big(H_0(\epsilon) - H_0(\epsilon^{-1}) \Big),$$

and

$$H_0'(\epsilon^{-1}) = \frac{-2\epsilon^4}{1 - \epsilon^4} (H_0(\epsilon) - H_0(\epsilon^{-1})).$$

We see that the kernel of the operator corresponds to restrictions of constant 2-tensors, i.e. $H_0(\epsilon) = H_0(\epsilon^{-1})$. We also see that the cokernel is composed of elements satisfying $H'_0(\epsilon) = -\epsilon^4 H'_0(\epsilon^{-1})$.

B.2.2 The nonlinear problem

Let $A_e(r_1, r_2)$ be a flat annulus and consider $H(r_1)$ and $H(r_2)$ be functions in $H^s(\mathbb{S}^3)$. We define \mathcal{H} the unique zero of Φ with Dirichlet conditions $H(r_1)$ and $H(r_2)$ at $r = r_1$ and $r = r_2$ obtained by Theorem B.2. We then denote $\mathcal{H}'(r_1)$ and $\mathcal{H}'(r_2)$ as the restrictions of $\nabla_{r\partial_r}\mathcal{H}$ respectively at $r = r_1$ and $r = r_2$.

Definition B.7 (Nonlinear Dirichlet-to-Neumann map on a flat annulus). We define for s > 5/2, $\mathcal{D}t\mathcal{N}: H^s(\mathbb{S}^3) \to H^{s-1}(\mathbb{S}^3)$, by

$$\mathcal{D}t\mathcal{N}: (H(r_1), H(r_2)) \mapsto (\mathcal{H}'(r_1), \mathcal{H}'(r_2)).$$

Theorem B.8. The map $\pi_{H^{s-1}_{Im}}\mathcal{D}t\mathcal{N}: H^s_0 \to H^{s-1}_{Im}$ has a log-analytic inverse in a neighborhood of $0 \in H^s(\mathbb{S}^3)^2$.

Proof. We have just seen from Theorem B.2 that the solution \mathcal{H} to the Dirichlet problem depends log-analytically on the Dirichlet data. The Neumann restriction also depends log-analytically and, the (linear) orthogonal projection $\pi_{H_{Im}^{s-1}}$ on H_{Im}^{s-1} preserves log-analyticity.

The linearization $\pi_{H_{Im}^{s-1}}\mathcal{D}t\mathcal{N}$ is exactly the linear operator $\operatorname{DtN}: H_0^s \to H_{Im}^{s-1}$ which is a linear isomorphism by Proposition B.6. We can then use the inverse function theorem for log-analytic functions to conclude.

We probably need to emphasize that the resulting map depends log-analytically on $\frac{r_1}{r_1}$?

C Dirichlet-to-Neumann map on a manifold with sphere-like boundaries

Let us consider an Einstein orbifold (M_o, g_o) which is either ALE or compact, and consider the modified metric (M_o, \tilde{g}_o) obtained by smoothly gluing exactly flat cones thanks to a cut-off function between $r_0 > 0$ and $2r_0$ chosen small enough in orbifold and between $R_0 > 0$ and $2R_0$ large enough in the ALE region if there is one. We finally consider the manifold with boundary obtained by considering the region with $r_2 < r < R_1$ for $r_2 < r_0 \ll 1 \ll R_0 < R_1$.

We want to understand the Dirichlet-to-Neumann map for this kind of space.

C.1 Linear Dirichlet-to-Neumann problem

Here we really need to careful about the regularity on the boundaries: we want to go from H^s to H^{s-1} and we want the result to be a linear isomorphism

ref

We need to be precise about the kernel/cokernel, there must be one...

On the ALE, we will not see any $\frac{cst}{r^2}$ in the kernel but we will see all of the cst.

On the orbifold however, we will have $\frac{cst}{r^2}$ when the constants are not in the L^2 kernel

C.1.1 On an orbifold

On an orbifold, the linear operator $L_o: \tilde{\mathbf{O}}(g_o) \oplus H^{s+1/2}(M_o) \cap \tilde{\mathbf{O}}(g_o)^{\perp} \to H^{s-3/2}(M_o)$,

$$L_o(\mathbf{o}_o, h) \mapsto$$

is an isomorphism.

What can we say about the DtN map?

The leading terms of the elements of the kernel on the orbifold: if there is some ϕ_m associated to the m-th eigenvalue of the spherical Laplacian, then the associated element of the kernel of L_{g_o} has a development:

$$r^{-2-m}\phi_m + \mathcal{O}(r^{-2-m+1})$$

hence, restricted to some small r, one mostly sees that first term (it's the only one remaining as $r \to 0$)...

C.1.2 On an ALE space

On an ALE space, the linear operator $L_Z: \tilde{\mathbf{O}}(g_Z) \oplus H^{s+1/2}(Z) \cap \tilde{\mathbf{O}}(g_Z)^{\perp} \to H^{s-3/2}(Z)$,

$$L_Z(\mathbf{o}_Z,h) \mapsto$$

is an isomorphism.

What can we say about the DtN map?

Here, the leading term for the Dirichlet problem from some ϕ_m is this time in $r^m \phi_m + \mathcal{O}(r^{m-1})$.

C.2 Nonlinear Dirichlet-to-Neumann problem

Modulo cut-off obstructions!

We want to have a log-analytic map – from H^s to H^{s-1} .

D [From previous notes] Boundary problems for Ricciflat ALE metrics and orbifold

Let us look at the problem at a linear level, i.e. search for solutions of

$$\begin{cases}
P_{\mathbf{b}}h = 0, \\
h = \phi \text{ on } \epsilon^{-1}\mathbb{S}^3/\Gamma.
\end{cases}$$
(25)

for some boundary condition $\phi: \epsilon^{-1}\mathbb{S}^3/\Gamma \to \operatorname{Sym}^2(T\mathbb{R}^4/\Gamma)$. Similarly, on the orbifold, the problem becomes:

$$\begin{cases}
P_{go}h = 0, \\
h = \phi \text{ on } \epsilon \mathbb{S}^3/\Gamma.
\end{cases}$$
(26)

for some small $\epsilon > 0$.

D.1 Asymptotics of the (co)kernel and obstructions

Let us classify the L^2 -infinitesimal deformations of **b** by their order of decay at infinity:

$$\mathbf{O}(\mathbf{b}) = igoplus_{j=4}^{j_{ ext{max}}} \mathbf{O}^{(j)}(\mathbf{b})$$

in the following way. Let j_{max} be the maximum of $j \geq 4$ such that there exists $\mathbf{o} \in \mathbf{O}(\mathbf{b})$ with $\mathbf{o} = \mathcal{O}(r^{-j})$. Define $\mathbf{O}^{(j_{\text{max}})}(\mathbf{b})$ as the subspace of $\mathbf{O}(\mathbf{b})$ spanned by the tensors in $r^{-j_{\text{max}}}$ at infinity. We then define $\mathbf{O}^{(j_{\text{max}}-1)}(\mathbf{b})$ as the subspace of $\mathbf{O}(\mathbf{b})$ spanned by the tensors in $r^{-(j_{\text{max}}-1)}$ at infinity and $L^2(\mathbf{b})$ -orthogonal to $\mathbf{O}^{(j_{\text{max}})}(\mathbf{b})$. We then iteratively define the subspaces $\mathbf{O}^{(j)}(\mathbf{b})$ which are $L^2(\mathbf{b})$ -orthogonal to each other by construction.

The most important aspect of these infinitesimal deformations for the obstructions to the desingularization of Einstein metrics is their asymptotic terms. More precisely, if $\mathbf{o} \in \mathbf{O}^{(j+2)}(\mathbf{b})$, then at infinity $\mathbf{o} = r^{-2-j}\phi_j + \mathcal{O}(r^{-3-j})$, where ϕ_j is a 2-tensor whose coefficients are spherical harmonics associated to the *j*-th eigenvalue. Denote $\mathbb{O}^{[j]}(\mathbf{b})$ the space of spherical harmonics ϕ_j appearing as the asymptotic term of an element of $\mathbf{O}^{(j+2)}(\mathbf{b})$. The link with obstructions is the following result.

Proposition D.1. Let H_2 be a quadratic harmonic 2-tensor in Bianchi gauge (say the quadratic terms of a Ricci flat orbifold). There exists a symmetric 2-tensor h_2 and $\mathbf{o} \in \mathbf{O}^{(4)}(\mathbf{b})$ solutions to

$$P_{\mathbf{b}}(h_2) = \mathbf{o},$$

with $h_2 = H_2 + \mathcal{O}(r^{-2+\epsilon})$. Moreover, $\mathbf{o} = 0$ if and only if $r^{-2}H_2 \perp_{L^2(\mathbb{S}^3)} \mathbb{O}^{[2]}(\mathbf{b})$. Note that $\mathbb{O}^{[2]}(\mathbf{b}) \neq$ and there are always obstructions to solve this kind of equation.

Idea of proof. Consider a cut-off function χ supported at infinity of (N, \mathbf{b}) . The goal is to find h' decaying at infinity (in $\mathcal{O}(r^{-2+\epsilon})$) such that

$$P_{\mathbf{b}}(\chi H_2 + h') = \mathbf{o},$$

where we remark that

$$P_{\mathbf{b}}h' \perp \mathbf{O}(\mathbf{b}).$$

We must therefore have

$$\mathbf{o} = \pi_{\mathbf{O}(\mathbf{b})} P_{\mathbf{b}}(\chi H_2).$$

Conversely, if $P_{\mathbf{b}}(\chi H_2) - \mathbf{o}$ decays and is orthogonal to the cokernel $\mathbf{O}(\mathbf{b})$, then there exists a decaying h' such that $-P_{\mathbf{b}}(h') = P_{\mathbf{b}}(\chi H_2) - \mathbf{o}$.

By integration by parts of $P_{\mathbf{b}}(\chi H_2)$ against $v \in \mathbf{O}(\mathbf{b})$ with $v = V^4 + \mathcal{O}(r^{-5})$, we find that $(P_{\mathbf{b}}(\chi H_2), v)_{L^2(\mathbf{b})}$ is proportional to $\int_{\mathbb{S}^3/\Gamma} \langle H_2, V^4 \rangle_{\mathbf{e}} dv_{\mathbb{S}^3/\Gamma}$.

Remark D.2. A similar result is true for H_i with homogeneous harmonic polynomials of order i as coefficients, but it would also involve other asymptotics of the other $\mathbf{O}^{(j+2)}(\mathbf{b})$ for $j \leq i$. For instance, if $\mathbf{o}_4 \in \mathbf{O}^{(4)}(\mathbf{b})$ has some $r^{-2-i}\phi_i$ in its development, then there will also be \mathbf{o}_4 in the obstructions.

D.2 Solving the linearized boundary problem on a Ricci-flat ALE space

On a given Ricci-flat ALE space, solving (25) is always possible, but something happens if ϕ has some spherical harmonics coinciding with the element of some $\mathbb{O}^{[2]}(\mathbf{b})$ for instance.

Essentially, if for simplicity that $\mathbf{O}(\mathbf{b}) = \mathbf{O}^{(4)}(\mathbf{b})$, the idea is that the kernel of $P_{\mathbf{b}}$ is composed of symmetric 2-tensors asymptotic to all harmonic polynomials **except** the ones of the form $r^2\phi_2$ for $\phi_2 \in \mathbb{O}^{[2]}(\mathbf{b})$ which are **replaced** by the associated elements of $\mathbf{O}(\mathbf{b})$ which are asymptotic to $\frac{\phi_2}{r^4}$.

Proposition D.3. Assume for simplicity that $\mathbf{O}(\mathbf{b}) = \mathbf{O}^{(4)}(\mathbf{b})$ (as for Eguchi-Hanson for instance). Let $\phi : \epsilon^{-1} \mathbb{S}^3 / \Gamma \to \operatorname{Sym}^2(T\mathbb{R}^4 / \Gamma)$.

1. If $\phi \perp \mathbb{O}^{[2]}(\mathbf{b})$, then, the solution of (25) is uniformly bounded by a function $\|\phi\|_{L^2}$ (but independently of ϵ) on the interior of $\epsilon^{-1}\mathbb{S}^3/\Gamma$.

More precisely, if $\phi = \phi_j$ where ϕ_j has eigenfunctions of the spherical Laplacian associated to the j-th eigenvalue as coefficient, then, as $\epsilon \to 0$, we have:

$$h = (\epsilon r)^j \phi_j + \mathcal{O}(\epsilon^j r^{j-1})$$

at infinity for the solution h of (25).

2. If ϕ is not orthogonal to $\mathbb{O}^{[2]}(\mathbf{b})$, then, it is **not** uniformly bounded in independently of ϵ in the interior of $\epsilon^{-1}\mathbb{S}^3/\Gamma$.

More precisely, if $\phi = \phi_2 \in \mathbb{O}^{[2]}(\mathbf{b})$, and if $\mathbf{o} \in \mathbf{O}(\mathbf{b})$ is the associated element, then:

$$h \approx \epsilon^{-4} \mathbf{o}$$

in the interior of $\epsilon^{-1}\mathbb{S}^3/\Gamma$.

There are similar results for orbifolds where the kernel of P_o includes every $\frac{\phi_j}{r^{2+j}}$ except those which appear in the developments of the elements of $\mathbf{O}(g_o)$, the L^2 -kernel.

D.3 Solving the boundary value problem modulo obstructions

It is not satisfying to solve the boundary value $\phi_2 \in \mathbb{O}^{[2]}(\mathbf{b})$ by some approximation of $\mathbf{o} = \frac{\phi_2}{r^4} + \dots$ for several reasons:

- 1. The Dirichlet to Neumann map will not match that of the orbifold where the solution is asymptotic to $H_2 = r^2 \phi_2$,
- 2. the solution is not bounded independently of ϵ it is in contradiction (at the linear level for now...) with the convergence to **b** of the rescalings of the degeneration of Einstein metrics.

We can however solve it modulo obstruction using Proposition D.1 in order to "replace" $\frac{\phi_2}{r^4}$ by $r^2\phi_2$. That is solve:

$$\begin{cases}
P_{g_o}h \in \mathbf{O}(\mathbf{b}) \text{ or } \chi \mathbf{O}(\mathbf{b}) \text{ for some cut-off } \chi \text{ supported in a large region,} \\
h = \phi \text{ on } \epsilon \mathbb{S}^3 / \Gamma,
\end{cases}$$
(27)

and chose the solutions growing polynomially at infinity.

Remark D.4. Here the solution is probably not unique as we can compensate portions of ϕ_2 by either the element asymptotic to $\frac{\phi_2}{r^4}$ or $r^2\phi_2$? This kind of non uniqueness is expected as in the end, there is $\mathbf{O}(\mathbf{b}) \oplus \mathbf{O}(g_o)$ degrees of freedom.

The boundary value for all of the 2-tensors h_j satisfying

$$P_{\mathbf{b}}h_j \in \mathbf{O}(\mathbf{b}),$$

and $h_j = r^j \phi_j + ...$ can be chosen so that it is $\epsilon^{-j} \phi_j + \mathcal{O}(\epsilon^{4-j})$. The h_j are unique up to the harmonic 2-tensors growing slower at infinity.

D.4 Limiting behavior of the Dirichlet to Neumann maps on the ALE and the orbifold

Let us look at the linearized Dirichlet problem when $\epsilon \to 0$.

Conjecture D.5. There is no cokernel for the operator "modulo obstructions". The kernel should be composed of approximations of $\epsilon^2 h_2 - \epsilon^{-4} \mathbf{o}$ for $h_2 \sim r^2 \phi_2$ and $\mathbf{o} \sim r^{-4} \phi_2$.

The Dirichlet to Neumann map "sees" this kernel.

D.5 Matching boundary values

The orbifold is solution of $\mathrm{Ric}(g_o) = \Lambda g_o$ with boundary

$$\mathbf{e} + \sum_{i=2}^{+\infty} \epsilon^i \phi_i$$

on $\epsilon \mathbb{S}^3/\Gamma$, and the Ricci-flat ALE metric is solution of $\text{Ric}(\mathbf{b}) = 0$ with boundary condition

$$\mathbf{e} + \sum_{j=2}^{+\infty} \epsilon^{j+2} \psi_j$$

on $\epsilon^{-1}\mathbb{S}^3/\Gamma$.

Conjecture D.6. Matching the two Dirichlet and Neumann conditions when considering the cut-off of obstructions should (formally) correspond to the development in Section ??.

Remark D.7. If we do not consider cut-offs of the obstructions (far away from the gluing region), we need to match the obstructions on the ALE on the orbifold and vice versa. It is unclear to me how to do that in a systematic way past the first asymptotics...

The advantage of matching the metrics and their derivatives on a hypersurface is that it must be much easier to preserve analyticity (what if there are log-terms however?) if we do it "directly" by fixed point. The hope is that we could maybe "read" the obstructions in the development of the boundary function in spherical harmonics obtained by fixed point, no? Can we have any control on its value?