Introduction to Matlab

Lesson 02 — Importing, manipulating, and fitting Data

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- Download the data from the World Bank in CSV.
 - GDP per capita (constant 2010 US\$)
 - Urban population as a % of total population
- Rename to urban_pop.csv and real_gdp_percapita.csv
- Forget by now about the metadata files.
- Download in a subdirectory in the working directory as working_directory/data/

- Since the data files have headers or column names, we explicitly tell the command that.
- Let's import the data as a table using readtable()

```
close all
clear
clc

Material in the second of the se
```

- Tables in Matlab are a data type created to store data that is column oriented.
- They are not like arrays, we need to extract the numeric columns.
- Let's find out if country codes are the same for both variables.
- To make manipulation easier, transform to a cell array.

```
1 % Extract CountryCode for both files
2 ccode_gdp = table2cell(gdp(:,2));
3 ccode_pop = table2cell(pop(:,2));
```

To check if country codes coincide:

- 1. Compare one by one.
- 2. Check if all elements are true

```
1 % Compare strings one by one
2 compare_ccode = strcmp(ccode_gdp,ccode_pop);
3 all_true = all(compare_ccode);
4 disp(all_true)
```

Since they are, we can safely merge the two variables.

- Extract the numeric values of GDP and urban population.
- We use table2array() to convert into a matrix.
- We transpose so that each row is a year and each column a country.

```
1 % Extract GDP per capita and urban population as a matrices
2 gdp_pc = table2array(gdp(:,5:end));
3 pop_ub = table2array(pop(:,5:end));
```

- Explore the rough relationship between log(GDP) and urban population.
- To do a pooled scatter plot use the (:) operator. This converts a matrix into a vector.

```
1 % Explore the relationship between GDPpc and Urban population
2 figure
3 scatter(log(gdp_pc(:)),pop_ub(:),...
4     'filled','MarkerFaceAlpha',0.25)
5 hold on
6 lsline % add a least squares line
7
8 % Rough correlation
9 disp(corrcoef(log(gdp_pc(:)),pop_ub(:),'Rows','complete'))
```

• The correlation for all countries is 0.8290. Let's explore the correlation for each country individually.

```
1 % Correlation by country
2 [T, N] = size(gdp_pc); % Time periods (T) and number of
    countries (N)
4 corr_coefs = zeros(N,1);
5 \text{ for } n = 1:N
     tmp = corrcoef(log(gdp_pc(:,n)),pop_ub(:,n),'Rows','
         Complete'):
corr_coefs(n,1) = tmp(1,2);
8 end
no mean(corr_coefs, 'omitnan')
```

• The average is 0.54 and the standard deviation 0.60.

Exercise 1

Plot the evolution over time for a particular country. Plot the two series in the same graph with two different y—axes. Also, make sure you include the years in the x—axis.

How has it been for India?

```
1% Plot the evolution for
     India
_{2} vears = 1960:1960+T-1:
3 india = strcmp(ccode_gdp,'
     IND');
4 gdp_india = gdp_pc(:,india);
5 urb_india = pop_ub(:,india);
7 figure
8 plot(years,gdp_india,'-o')
9 hold on
10 yyaxis right
plot(years, urb_india, '-s')
```

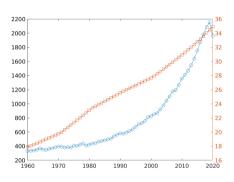


Figure 1: Real GDPpc and Urban Pop





 Let's estimate a linear regression for the relationship between GDP per capita and urban population with a time trend.

$$\log(GDPpc_{t,i}) = \beta_0 + \beta_1 urban_{t,i} + \beta_2 time_t + \varepsilon_{t,i}$$

 \circ The OLS estimator is $\hat{eta}=(X'X)^{-1}X'y$ where

$$X = \begin{pmatrix} 1 & urban_{1960,1} & 1960 \\ \vdots & \vdots & \vdots \\ 1 & urban_{2020,N} & 2020 \end{pmatrix} y = \begin{pmatrix} \log(GDPpc_{1960,1}) \\ \vdots \\ \log(GDPpc_{2020,N}) \end{pmatrix}$$

Necessary steps:

1. Reshape matrices into vectors of size $T \times N$ and create $time_t$.

```
1 % Reshape GDPpc matrix into a vector
_{2} v = reshape(gdp_pc, [T*N, 1]);
y = \log(y); % Recall our dependent variable is in logs!
5 % Reshape pop_ub in the same way
6 urb_vect = reshape(pop_ub,[T*N,1]);
8 % Create the time trend
9 years_mat = repmat(years, N, 1);
10 years_mat = years_mat ';
vears_vec = reshape(years_mat,[T*N,1]);
```

Necessary steps:

2. Remove missing values from all variables.

```
% Remove missing values from both variables
miss_y = isnan(y);
miss_u = isnan(urb_vect);
tot_miss = logical(miss_y + miss_u);

y_clean = y(~tot_miss);
u_clean = urb_vect(~tot_miss);
years_vec = years_vec(~tot_miss);
```

Necessary steps:

3. Construct X and compute $\hat{\beta}$

```
1 % Create matrix X
2 X = [ones(size(u_clean)), u_clean, years_vec];
3
4 % Estimate bhat
5 bhat = ((X')*X)\((X')*y_clean);
```

$$\hat{\beta} = \begin{pmatrix} 11.0201 \\ 0.0509 \\ -0.0027 \end{pmatrix}$$

So, $\Delta urban = 1$ percentage point is associated with $\Delta GDPpc = 5.09\%$. **NOT A CAUSAL RELATIONSHIP!!!**

Linear Regression — Other Ways

- What if we want standard errors, p-values ...?
- Fortunately, not by hand! (fitlm and LinearModel)
- These are found within the Statistics and Machine Learning Toolbox.
- Alternatives:
 - fit from the Curve Fitting Toolbox
 - regress from the Statistics and Machine Learning Toolbox
 - Spatial Econometrics Toolbox by James P. LeSage. Much more recommended for serious data work are R, Stata, Python

Linear Regression — fitlm and LinearModel

- fitlm creates a LinearModel object, estimates the model, and produces results for that particular model object.
- fitlm accepts data in table format or numeric array format. We will stick to numeric array.
- By default it includes a constant and deals with missing values.

```
1 % Control variables
2 Xfitlm = [urb_vect, years_vec];
3
4 % Model object
5 linmodel = fitlm(Xfitlm,y);
6 disp(linmodel)
```

Linear Regression — fitlm and LinearModel

The default output of the fitlm model includes

- \circ Coefficients, standard errors, t-statistics, p-values ...
- Reassuringly, we get the same coefficients as before.

```
1 >> disp(linmodel)
 Linear regression model:
      v \sim 1 + x1 + x2
  Estimated Coefficients:
                      Estimate
                                        SE
                                                   tStat
                                                               pValue
      (Intercept)
                          11.02
                                      0.92273
                                                 11.943
                                                             1.0777e-32
                      0.050911
                                    0.00032252
                                                 157.86
11
      x 1
      x 2
                     -0.0026586
                                                  -5.7161
                                                             1.1155e-08
12
                                   0.0004651
13
15 Number of observations: 12131, Error degrees of freedom: 12128
16 Root Mean Squared Error: 0.821
17 R-squared: 0.688, Adjusted R-Squared: 0.688
18 F-statistic vs. constant model: 1.34e+04, p-value = 0
```

Linear Regression — fitlm and LinearModel

We can perform some model diagnostics

- plotResiduals(linmodel) to show a histogram of residuals.
- o plotResiduals(linmodel, 'fitted') residuals vs fitted values.
- plotEffects(linmodel) to show size of coefficients.

We can access directly several derived objects

- o linmodel.LogLikelihood the log-likelihood.
- o linmodel. Residuals the residuals of the fitted model.
- linmodel.Coefficients the value of estimated coefficients.



Theorem 1 (Weierstrass' Approximation Theorem)

Let f(x) be a continuous real-valued function defined on [a,b]. Then, given ε we can find a polynomial p(x) such that

$$\sup |f(x) - p(x)| < \varepsilon$$

Informally: any continuous function on [a,b] can be approximated well by a polynomial function of a sufficient degree.

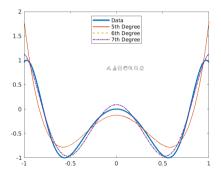
 \circ Suppose, we have the following relationship between y and x

$$y = \sin(5x^2 + \pi)$$

with $x \in \mathbb{R}$. Note that the function is continuous in \mathbb{R} .

- But we do not know the relationship (or it is very expensive to compute). Let us approximate by an n-degree polynomial.
- This is done with the commands polyfit and polyval to fit and evaluate polynomials respectively. (How exactly are we fitting...?)

- Let's fit the data using 5th, 6th, and 7th degree polynomials.
- Evaluate them and plot them.



Exercise 2

Generate a vector x in the interval [-4,4] with 1000 points (linspace). Now, create the variable $y=x^2+\varepsilon$ where ε is white noise (randn) with standard deviation 1.5. Fit a second degree polynomial and plot the simulated data and the fitted polynomial on the same plot.

Fitting data with noise.

```
1 X = linspace(-4,4,1000);
2 Y = X.^2 + 1.5.*randn(1,length(X));
3 p2 = polyfit(X,Y,2);
4
5 figure
6 scatter(X,Y)
7 hold on
8 plot(X,polyval(p2,X),'-','LineWidth',1.35)
9 title('Polynomial Fit')
```



Nonlinear Least Squares

- Consider a set of data points $(x_1, y_1), \ldots, (x_N, y_N)$ and a function $y = f(x, \beta)$ depending on unknown parameters $\beta = (\beta_1, \ldots, \beta_m)$ where N > m.
- \circ The Nonlinear Least Squares estimator is the set of coefficients eta such that

$$\min_{\beta} \sum_{i=1}^{N} (y_i - f(x_i, \beta))^2$$

- o polyfit is exactly doing that but when $f(x, \beta)$ is a polynomial of degree n.
- We can extend that to any nonlinear function easily.

Nonlinear Least Squares — Functions

- To perform NLLS Matlab provides several alternatives
- We will focus on lsqcurvefit. Other alternatives are
 - o lsqnonlin
 - o nlinfit
 - fitnlm (very similar to fitlm)
- **lsqcurvefit** and **lsqnonlin** are **equivalent** since they use the same algorithm.
- We will focus on **lsqcurvefit** provides a convenient way of writing the problem and advances syntax for the lecture on optimization.

Nonlinear Least Squares — lsqcurvefit

Suppose we want to fit a data generating process of the type

$$y = b_1 \exp(b_2 x) + \varepsilon$$
 where $\varepsilon \sim \mathcal{N}(0, 0.15)$ and $x \in [0, 5]$

- Suppose we have N pairs of observations (x_i, y_i) and we want to find parameters b_1 and b_2 that best fit the data.
- Let's simulate the data first

```
%Simulate data

2 N = 500;

3 b1 = 2;

4 b2 = -1.5;

5 x = linspace(0,5,N);

6 y = b1*exp(b2*x)+0.15*randn(1,N);
```

Nonlinear Least Squares — lsqcurvefit

o Once the data is simulated, we create an anonymous function of the form

$$y = b_1 \exp(b_2 x)$$

that takes as arguments both the coefficients b_1 and b_2 and the data, x.

```
1 % Declare anonymous function with our model
2 func_fit = @(b,xdata)(b(1)*exp(b(2)*xdata));
```

Now we can fit the function. However, we need to provide initial values!

```
1 % Fit
2 b00 = [1, -1]; % Initial condition
3 [bhat,resnorm,res,exitflag,output] = lsqcurvefit(func_fit,b00,x,y);
```

Nonlinear Least Squares — lsqcurvefit

Table 1: NLLS Fit with lsqcurvefit

	Estimate	Std Erro
b_1 b_2	1.9982 -1.5579	0.0362 0.0402

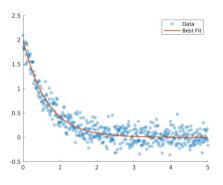


Figure 2: Performance of lsqcurvefit