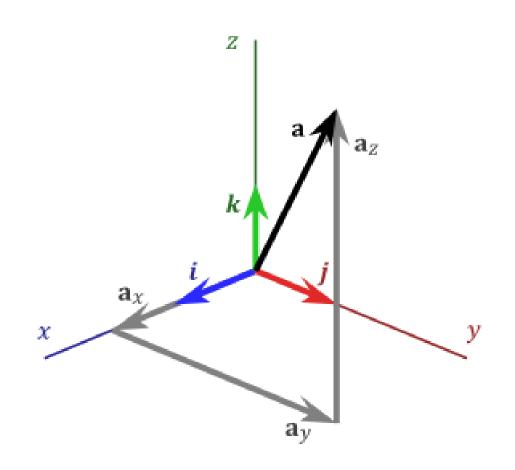
# 4. Linear algebra I



# Linear algebra

(see Appendix of Griffiths "Introduction to quantum mechanics" (2<sup>nd</sup> edition))

Linear algebra is a generalization of vector spaces to

- (1) Complex numbers
- (2) Arbitrary dimensions

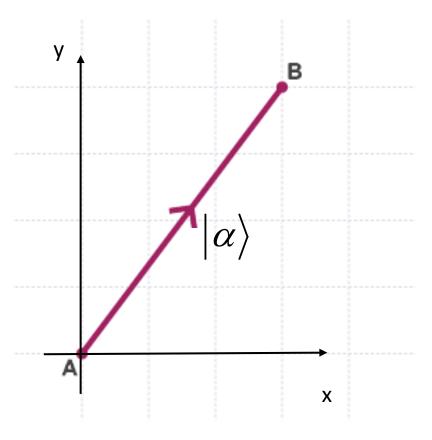
## Vectors and scalars

**Vectors** are quantities that have a magnitude and direction.

**Scalars** are quantities that only have magnitude.

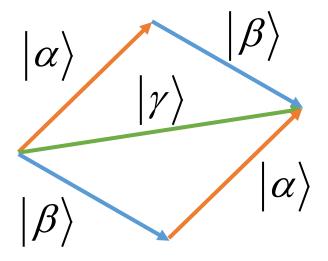
Denote a vector as |lpha
angle

(Just a different notation to  $\overset{
ightharpoonup}{lpha}$  )



#### Vector addition

Define as  $|\alpha\rangle + |\beta\rangle = |\gamma\rangle$ 



Vector addition is commutative

$$|\alpha\rangle + |\beta\rangle = |\beta\rangle + |\alpha\rangle$$

Vector addition is associative

$$|\alpha\rangle + (|\beta\rangle + |\gamma\rangle) = (|\alpha\rangle + |\beta\rangle) + |\gamma\rangle$$

There is a zero vector

$$|\alpha\rangle + |0\rangle = |\alpha\rangle$$

There is an inverse vector

$$|\alpha\rangle + |-\alpha\rangle = |0\rangle$$

# Scalar multiplication

Multiplying a vector by a scalar is another vector

Scalar multiplication is distributive

Scalar multiplication is associative

Multiplication by zero

Multiplication by one

Inverse of a vector

$$a|\alpha\rangle = |\gamma\rangle$$

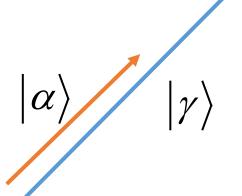
$$a(|\alpha\rangle + |\beta\rangle) = a|\alpha\rangle + a|\beta\rangle$$
$$(a+b)|\alpha\rangle = a|\alpha\rangle + b|\alpha\rangle$$

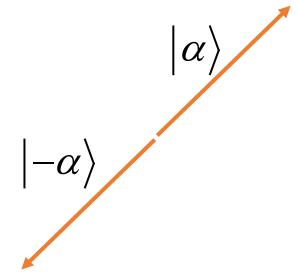
$$a(b|\alpha\rangle) = (ab)|\alpha\rangle$$

$$0|\alpha\rangle = |0\rangle$$

$$1|\alpha\rangle = |\alpha\rangle$$

$$|-\alpha\rangle = (-1)|\alpha\rangle = -|\alpha\rangle$$





## Components

Components: Given a particular basis  $|e_1\rangle, |e_2\rangle, \dots, |e_n\rangle$ , the n-tuple  $|\alpha\rangle \leftrightarrow (a_1, a_2, \dots, a_n)$  by writing the vector as  $|\alpha\rangle = a_1|e_1\rangle + a_2|e_2\rangle + \dots + a_n|e_n\rangle$ 

Addition: 
$$|\alpha\rangle + |\beta\rangle \leftrightarrow (a_1 + b_1, a_2 + b_2, \dots, a_n + b_n)$$

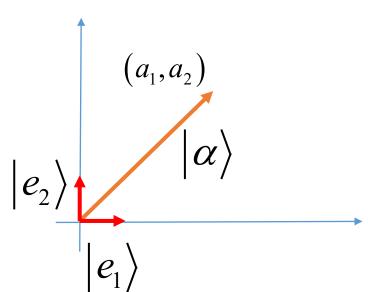
Scalar multiplication:  $c|\alpha\rangle \leftrightarrow (ca_1, ca_2, \dots, ca_n)$ 

Null vector:  $|0\rangle \leftrightarrow (0, 0, \dots, 0)$ 

Inverse vector:  $|-\alpha\rangle \leftrightarrow (-a_1, -a_2, \dots, -a_n)$ 

Basis: A set of vectors that you can construct any vector out of. E.g.

$$|e_1\rangle, |e_2\rangle, \ldots, |e_n\rangle$$



## Question

1) Find 
$$|\alpha\rangle + 2|\beta\rangle$$

2) Find 
$$|\beta\rangle - |\alpha\rangle$$

$$|\alpha\rangle = 2|e_1\rangle + i|e_2\rangle$$
$$|\beta\rangle = (1-i)|e_1\rangle + |e_2\rangle$$

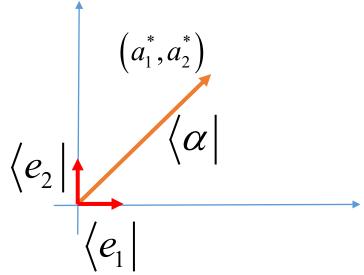
## Conjugate vector

Define the conjugate vector as

$$\langle \alpha | = a_1^* \langle e_1 | + a_2^* \langle e_2 | + \dots + a_n^* \langle e_n |$$

These can be represented by row vectors, with elements that are complex conjugates of the original vector

$$\langle \alpha | = (a_1^* \cdots a_n^*)$$



# Inner products

Generalization of the dot product, which takes two vectors and gives a scalar

Component form definition

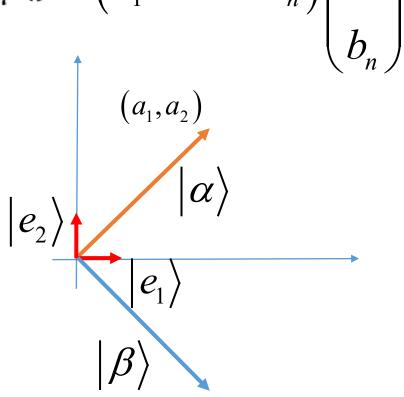
$$\langle \alpha | \beta \rangle = a_1^* b_1 + a_2^* b_2 + \dots + a_n^* b_n = \begin{pmatrix} a_1^* & \dots & a_n^* \end{pmatrix}$$
  $\vdots$ 

If the vectors are orthogonal, then the inner product is zero

$$\langle \alpha | \beta \rangle = 0$$

Magnitude of inner product tells you how similar the vectors are. "Fidelity"

$$F = \left| \left\langle \alpha \left| \beta \right\rangle \right|^2$$



#### Norm of a vector

$$\|\alpha\| \equiv \sqrt{\langle \alpha | \alpha \rangle}$$

("length of a vector")

$$\langle \alpha | \alpha \rangle = |a_1|^2 + |a_2|^2 + \dots + |a_n|^2$$

Unit vector: A vector with norm = 1

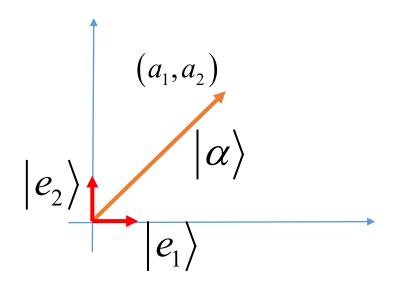
$$\langle e_i | e_j \rangle = \delta_{ij}$$

Components of the vector

$$a_i = \langle e_i | \alpha \rangle$$

$$|\alpha'\rangle = \frac{|\alpha\rangle}{\sqrt{\langle\alpha|\alpha\rangle}}$$

$$\langle \alpha' | \alpha' \rangle = 1$$



## Question

- 1) Find  $\langle \alpha | \beta \rangle$
- 2) Normalize  $|\alpha\rangle$

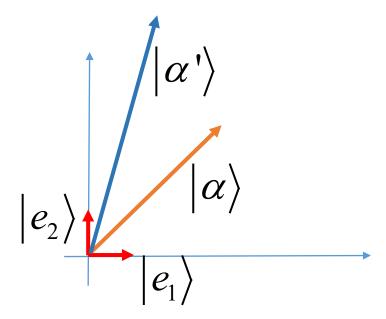
$$|\alpha\rangle = 2|e_1\rangle + i|e_2\rangle$$
  
 $|\beta\rangle = (1-i)|e_1\rangle + |e_2\rangle$ 

## Operators

Linear transformation: Takes a vector and transforms it to another vector  $|\alpha\rangle \to |\alpha'\rangle = \hat{T}|\alpha\rangle$ 

"Linear" means

$$\hat{T}(a|\alpha\rangle + b|\beta\rangle) = a(\hat{T}|\alpha\rangle) + b(\hat{T}|\beta\rangle)$$



Operators are some kind of "machines" that turn one vector into another

$$|\alpha\rangle$$
  $\Rightarrow$   $|\alpha'\rangle$ 

# Operators and matrices

 $|\alpha'\rangle = \hat{T}|\alpha\rangle$ Linear operators can always be represented by matrices

$$\mathbf{T} = \begin{pmatrix} T_{11} & T_{12} & \dots & T_{1n} \\ T_{21} & T_{22} & \dots & T_{2n} \\ \vdots & \vdots & & \vdots \\ T_{n1} & T_{n2} & \dots & T_{nn} \end{pmatrix}$$

$$\mathbf{T} = \begin{pmatrix} T_{11} & T_{12} & \dots & T_{1n} \\ T_{21} & T_{22} & \dots & T_{2n} \\ \vdots & \vdots & & \vdots \\ T_{n1} & T_{n2} & \dots & T_{nn} \end{pmatrix} \qquad \mathbf{a} \equiv \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} \qquad \mathbf{a}' = \mathbf{Ta} \qquad a'_i = \sum_{j=1}^n T_{ij} a_j.$$

The elements of the matrices are

$$T_{ij} = \langle e_i | \hat{T} | e_j \rangle$$

The operator itself can be written

$$\hat{T} = \sum_{ij} T_{ij} \left| e_i \right\rangle \left\langle e_j \right|$$

## Outer product

We can also take a vector and conjugate vector and make an operator:

$$S = |\alpha\rangle\langle\beta| = \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \begin{pmatrix} b_1^* & \cdots & b_n^* \end{pmatrix} = \begin{pmatrix} a_1b_1^* & a_1b_n^* \\ a_nb_1^* & a_nb_n^* \end{pmatrix}$$

A simple example is the outer product of two unit vectors

$$|e_1\rangle\langle e_3| = \begin{pmatrix} 1\\0\\0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1\\0 & 0 & 0\\0 & 0 & 0 \end{pmatrix}$$
 This explains why we can write the operator T as 
$$\hat{T} = \sum_{ij} T_{ij} |e_i\rangle\langle e_j|$$
 
$$\mathbf{T} = \begin{pmatrix} T_{11} & T_{12} & \dots & T_{1n}\\T_{21} & T_{22} & \dots & T_{2n}\\\vdots & \vdots & & \vdots\\T_{n1} & T_{n2} & \dots & T_{nn} \end{pmatrix}$$

This explains why we can write the operator T as

$$= \sum_{ij} T_{ij} \left| e_i \right\rangle \left\langle e_j \right|$$

$$\mathbf{T} = \begin{pmatrix} T_{11} & T_{12} & \dots & T_{1n} \\ T_{21} & T_{22} & \dots & T_{2n} \\ \vdots & \vdots & & \vdots \\ T_{n1} & T_{n2} & \dots & T_{nn} \end{pmatrix}$$

#### Question

1) Find 
$$Z|lpha
angle$$

2) Use the above result to find  $\langle \beta | Z | \alpha \rangle$ 

$$\begin{vmatrix} \alpha \rangle = \frac{|e_1\rangle + |e_2\rangle}{\sqrt{2}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\1 \end{pmatrix}$$

$$Z = \begin{pmatrix} 1 & 0\\0 & -1 \end{pmatrix}$$

$$|\beta\rangle = \frac{|e_1\rangle - |e_2\rangle}{\sqrt{2}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\-1 \end{pmatrix}$$