

①

Review

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\* d-separation


For sets of nodes  $X, Y, E$

when is

$$\begin{cases} P(Y|X, E) = P(Y|E) \\ P(X|Y, E) = P(X|E) \\ P(X, Y|E) = P(X|E)P(Y|E) \end{cases}$$

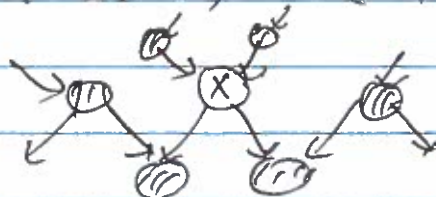
\* True if all paths from nodes in  $X$  to nodes in  $Y$  are "blocked".

A path is blocked if it has a node  $z$  that satisfies:

- 1)  $z \in E \longrightarrow \textcircled{z} \longrightarrow$  intervening cause
- 2)  $z \in E \longleftarrow \textcircled{z} \longrightarrow$  common cause
- 3)  $z \notin E$   $\longrightarrow \textcircled{z} \longleftarrow$  no observed common effect  
 $\text{desc}(z) \notin E$ 


\* Markov blanket  $B_X$  of node  $X$  consists of parents, children and spouses of  $X$ .  
 other parents of children

\* Thm:  $P(X|B_X, Y) = P(X|B_X)$  if  $Y \notin \{X, B_X\}$



## \* Inference in BNs

Query node  $Q$

Evidence nodes  $E$

How to compute  $P(Q|E)$ ?

## \* Polytrees

- singly connected networks
- polynomial time inference

## + Loopy BNs

- exact inference: node clustering, ...
- approximate inference: stochastic simulation, ...

## Learning

\* BN = DAG + CPTs not always available from experts

How to learn from examples?

## \* Issues:

- structure (DAG): known or unknown?
- evidence: "complete" data vs "incomplete" data
  - ↙ partial instantiation of nodes in BN

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- optimization :

combinatorial  
(eg. learning DAGs)

vs. continuous  
(eg. learning CPTs)

- algorithms

non-iterative

vs

iterative

(loop over data many times)

- solution : local vs global optima

\* Maximum likelihood estimation :

- simplest form of learning in DNs

- choose ("estimate") the model (DAG + CPTs)  
to maximize  $P(\underbrace{\text{observed data} | \text{model}}_{\text{"likelihood"}})$

Ex: biased coin

$P(X=\text{heads})$

(X)

$X \in \{\text{heads}, \text{tail}\}$

$P(X=\text{heads}) = p$

$P(X=\text{tails}) = 1-p$

\* How to estimate  $p$  from observed samples  
(eg. coin tosses) ?

## \* IID assumption

Samples are independently, identically distributed  
(according to  $P(x)$ )  
→  $\{x^{(1)}, x^{(2)}, \dots, x^{(T)}\}$   $T$  samples

## \* Probability of IID data

$$\begin{aligned} P(\text{data}) &= P(X=x^{(1)}) P(X=x^{(2)}) \dots P(X=x^{(T)}) \\ &= \prod_{t=1}^T P(X=x^{(t)}) \end{aligned}$$

## \* Log-probability

$$\begin{aligned} \mathcal{L} &= \log P(\text{data}) \\ \checkmark &= \log \prod_{t=1}^T P(X=x^{(t)}) \end{aligned}$$

log likelihood

$$\mathcal{L} = \sum_{t=1}^T \log P(X=x^{(t)})$$

Let  $N_H = \text{count}(X=\text{heads})$

$N_T = \text{count}(X=\text{tails})$

$$\Rightarrow N_H + N_T = T$$



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\* In terms of counts :

$$\ell(p) = \underbrace{N_H \log p}_{\text{heads}} + \underbrace{N_T \log(1-p)}_{\text{tails}}$$

\* Maximum likelihood (ML) estimation :

$$0 = \frac{d\ell}{dp} = \frac{N_H}{p} + \frac{N_T(-1)}{1-p} \Rightarrow N_H(1-p) + N_T p = 0$$

$$\boxed{p = \frac{N_H}{N_H + N_T} = \frac{N_H}{T}} \quad \begin{array}{l} \text{ML estimate of } p = P(\text{heads}) \\ \text{is just empirical frequency...} \end{array}$$

Discrete BNs with "Complete" data

\* Given : fixed DAG over discrete nodes  $\{x_1, x_2, \dots, x_n\}$

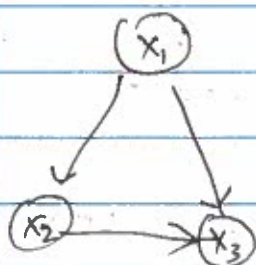
\* CPTs enumerate  $P(x_i = z \mid \underbrace{pa(x_i) = \pi}_{\substack{\text{parents} \\ \text{of } x_i}})$  as lookup tables  
↑  
some configuration of parents.

\* Data is T complete

instantiations of all nodes in BN

$$\{(x_1^{(t)}, x_2^{(t)}, \dots, x_n^{(t)})\}_{t=1}^T$$

Ex:



$n=3$

$t$	$X_1$	$X_2$	$X_3$
1	0	1	3
2	1	2	4
3	0	7	2
⋮	0	⋮	1
⋮	⋮	⋮	⋮
⋮	⋮	1	⋮
$T$	$D$	4	5

\* Each "n-tuple" of values is called an "example"

Goal: learn from examples

estimate CPTs  $\hat{P}(X_i = x_i | \text{pa}_i = \pi)$  that  
maximize probability of data set.  
likelihood

\* IID assumption

Samples are independently, identically distributed  
according to  $P(X_1, X_2, \dots, X_n)$

\* Probability of (IID) data set

$$P(\text{data}) = \prod_{t=1}^T P(X_1 = x_1^{(t)}, X_2 = x_2^{(t)}, \dots, X_n = x_n^{(t)})$$

↖ joint probability of  $t^{\text{th}}$  example.

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\* Work out  $t^{\text{th}}$  term in product:

$$\begin{aligned}
 & P(X_1 = x_1^{(t)}, \dots, X_n = x_n^{(t)}) \\
 & \quad \text{product rule} \\
 & = P(X_1 = x_1^{(t)}) P(X_2 = x_2^{(t)} | X_1 = x_1^{(t)}) \dots P(X_n = x_n^{(t)} | X_1 = x_1^{(t)}, \dots, X_{n-1} = x_{n-1}^{(t)}) \\
 & = \prod_{i=1}^n P(X_i = x_i^{(t)} | X_1 = x_1^{(t)}, \dots, X_{i-1} = x_{i-1}^{(t)}) \\
 & = \prod_{i=1}^n P(X_i = x_i^{(t)} | \text{pa}(X_i) = \text{pa}_i^{(t)}) \quad \text{cond. ind}
 \end{aligned}$$

\* log-likelihood

$$\begin{aligned}
 \mathcal{L} & = \log P(\text{data}) \\
 & = \log \prod_{t=1}^T P(x_1^{(t)}, x_2^{(t)}, \dots, x_n^{(t)}) \\
 & = \log \prod_{t=1}^T \prod_{i=1}^n P(x_i^{(t)} | \text{pa}(X_i) = \text{pa}_i^{(t)}) \\
 & = \sum_{t=1}^T \sum_{i=1}^n \log P(x_i^{(t)} | \text{pa}(X_i) = \text{pa}_i^{(t)}) \\
 & = \sum_{i=1}^n \sum_{t=1}^T \log P(x_i^{(t)} | \text{pa}(X_i) = \text{pa}_i^{(t)}) \quad (\text{swap order of sums})
 \end{aligned}$$

\* Let  $\text{count}(X_i = x, \text{pa}_i = \pi)$  denote # examples in table for which  $X_i = x$  and  $\text{pa}_i = \pi$ .

Ex  $\text{count}(X_2 = 2, X_1 = 0) = 1$

$\text{count}(X_2 = 1, X_1 = 0) = 2$

$\vdots$

\* log-likelihood

$$\mathcal{L} = \sum_{i=1}^n \sum_x \sum_{\pi} \overbrace{\text{count}(X_i = x, \text{pa}_i = \pi)}^{\text{determined by data}} \log \underbrace{P(X_i = x | \text{pa}_i = \pi)}_{\substack{\text{values that } X_i \text{ can assume} \\ \text{configuration of parents of } X_i \\ \text{numbers we can choose}}}$$

\* ML estimation

How to choose  $P(X_i = x | \text{pa}_i = \pi)$  to maximize  $\mathcal{L}(\text{data})$ ?

\* ML solution (without proof):

$$P_{ML}(X_i = x | \text{pa}_i = \pi) = \frac{\text{count}(X_i = x, \text{pa}_i = \pi)}{\sum_{x'} \text{count}(X_i = x', \text{pa}_i = \pi)}$$

(empirical frequency of  $X_i = x$  and  $\text{pa}_i = \pi$  in your data.)



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$$= \begin{cases} \frac{\text{count}(X_i=x, pa_i=\pi)}{\text{count}(pa_i=\pi)} & \text{when } X_i \text{ has parents} \\ \frac{\text{count}(X_i=x)}{T} & \text{when } X_i \text{ is root node} \end{cases}$$

$T \rightarrow \# \text{ examples}$

### \* Properties of ML estimation

- Asymptotically correct:

$$P_{ML}(X_1, X_2, \dots, X_n) \rightarrow P(X_1, X_2, \dots, X_n) \text{ as } T \rightarrow \infty$$

- Problematic for sparse data ( $T$  small):

$$P_{ML}(X_i=x | pa_i=\pi) = 0 \text{ if } \text{count}(X_i=x, pa_i=\pi) = 0$$

$$P_{ML}(X_i=x | pa_i=\pi) \text{ undefined if } \text{count}(pa_i=\pi) = 0$$

### \* other useful notation

Indicator function:

$$I(x, x') = \begin{cases} 0 & \text{if } x \neq x' \\ 1 & \text{if } x = x' \end{cases}$$

$$\text{count}(pa_i=\pi) = \sum_{t=1}^T I(pa_i^{(t)}, \pi)$$

$$\text{count}(x_i = x, pa_i = \pi) = \sum_{t=1}^T \mathbb{I}(x_i^{(t)} = x) \mathbb{I}(pa_i^{(t)} = \pi)$$

Ex: Naive Bayes model for document classification.

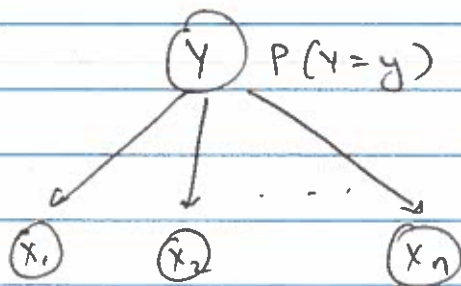
\* Variables

$$Y \in \{1, 2, \dots, n\}$$

eg. 1 = sports  
2 = politics

( $i=1..n$ )  $X_i \in \{0, 1\}$  does the  $i^{\text{th}}$  word in the dictionary appear in document?

\* BN = DAG + CPTs



$P(X_i=1 | Y=y)$  for  $i=1..n$

\* How to use model for document classification.

$$\begin{aligned} P(Y=y | \vec{X} = \vec{x}) &= \frac{P(\vec{X} = \vec{x} | Y=y) P(Y=y)}{P(\vec{X} = \vec{x})} && \text{Bayes rule} \\ &= \frac{\left\{ \prod_{i=1}^n P(X_i = x_i | Y=y) \right\} P(Y=y)}{\sum_{y'} \left\{ \prod_{i=1}^n P(X_i = x_i | Y=y') \right\} P(Y=y')} && \begin{array}{l} \text{prod rule} \\ + CI \\ \text{normalization} \end{array} \end{aligned}$$

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\* How to learn a model from a large corpus of documents?

$P_{ML}(Y=y)$  fraction of documents with topic  $y$   
 $P_{ML}(X_i=1 | Y=y)$  fraction of documents with topic  $y$  that contain  $i^{th}$  word in dict

\* Weaknesses of model

- "naive Bayes" assumption that words appear independently given topic
- "bag-of-words" representation ignores word ordering

Ex: Markov models of language

\* Let  $w_l$  denote the ~~the~~ word at  $l^{th}$  position in sentence.  
How to model  $P(w_1, w_2, \dots, w_L)$ ? probability of sentence with  $L$  words.

\* Simplifying assumptions:

(1) finite context/memory. "k-gram" model

$$P(w_l | w_1, w_2, \dots, w_{l-1}) = P(w_l | w_{l-1}, w_{l-2}, \dots, w_{l-(k-1)})$$

k-1 previous words

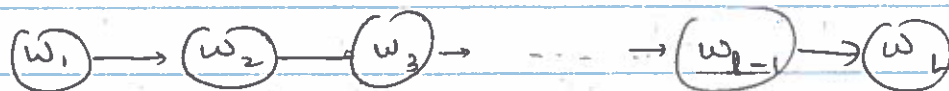
eg.  $P(w_l | w_1, \dots, w_{l-1}) = P(w_l | w_{l-1})$  "bi-gram" model.

(2) position invariance (for bigram model)

$$P(w_{l+b+1}=w' \mid w_l=w) = P(w_{l+b+1}=w' \mid w_{l+b}=w)$$

↑  
b is any positive or  
negative shift

\* BN for bigram-model of language



Also: same CPT is used at all non-root nodes in BN.

\* learning bigram model.

- collect large corpus of text  $\sim 10^8$  words (at least)
- vocabulary size  $V \sim 10^5$  dictionary entries

\* Count  $C_{ij}$  = # times that word  $j$  follows word  $i$   
count  $C_i$  = # times that word  $i$  appears in corpus

$$\text{estimate } P_{ML}(w_{l+1}=j \mid w_l=i) = \frac{C_{ij}}{C_i}$$

\* Note: no generalization to unseen word combinations



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\*  $n$ -gram model: condition on previous  $n-1$  words

$$P(w_L | w_1 \dots w_{L-1}) = P(w_L | w_{L-1}, \dots, w_{L-(n-1)})$$

$n=1$  unigram

$n=2$  bigram

$n=3$  trigram

$\vdots$

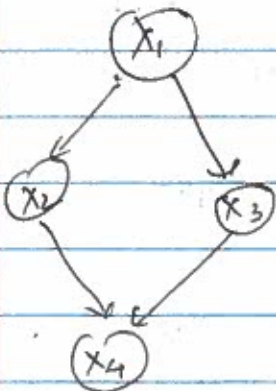
$n$ -gram counts get increasingly sparse for larger  $n$ .

Learning (ML estimation) from incomplete data

\* Given: fixed DAG over discrete nodes  $\{X_1, X_2, X_3\}$

Also: data set of  $T$  examples, but each example is a partial instantiation of nodes in BN.

Ex:



$t$	$X_1$	$X_2$	$X_3$	$X_4$
1	1	?	4	?
2	0	?	?	1
3	1		5	3
$\vdots$				
$T-1$	0		3	?
$T$	1	?	?	

\* Goal: estimate CPTs  $P(X_i = x \mid \text{pa}_i = \pi)$  that maximize (marginal) probability of partially observed data.

\* Variables in BN

$X$  = all nodes in BN

$H$  = subset of nodes that are unobserved ("hidden")

$V$  = subset of nodes observed ("visible")

\* log-likelihood

Assume that  $T$  examples are i.i.d from joint distribution  $P(X_1, X_2, \dots, X_n)$

$$\mathcal{L} = \log P(\text{data})$$

$$= \log \prod_{t=1}^T P(V = v^{(t)})$$

↖ visible nodes on  $t^{\text{th}}$  example

$$= \sum_{t=1}^T \log P(V = v^{(t)})$$

↖ marginal probability.  
(not joint)