

INDIAN INSTITUTE OF TECHNOLOGY, KANPUR

UGP REPORT

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## Auto Scaling of Key Value stores

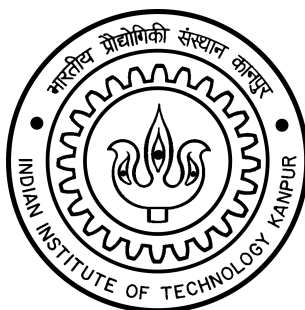
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## Abstract

In the modern day computing where application response is a critical metric, in memory databases are gaining popularity. In-memory databases primarily use main memory for data storage. These databases are becoming a crucial part of many applications due to the availability of less expensive RAM, and the demand for high response time. Some of the cases where in-memory databases perform exceptionally well are Queues, sticky sessions, caching, real-time data analysis, etc.

Generally, these in-memory databases are implemented as key-value stores; some well known key-value stores are Redis, Memcached, Hazelcast, etc. Large scale caching can be done by scaling the instances of these databases. Dynamic scaling of instances can provide cost-effective key-value storage services. This project aims at analyzing and providing an auto-scaling solution to this problem.

We try to collect statistics for different queries on different node configurations and try to find possible bottlenecks in the cluster based system. We analyze by scaling redis horizontally as well as vertically. For analyzing clusters we use an open source tool called Twemproxy (a fast, lightweight proxy for Memcached and redis). We limit resources and measure performance for these configurations. We also try to build a system which can be used to interact with the cluster and efficiently shard the requests among different instances.

## Introduction

### Key Value Stores

Key value stores are a special kind of database management system, where the data is organized in just 2 columns - a key, and a value. Here the key is mostly text, while the value can be anything and is simply an object. The actual data essentially becomes "value", which is indexed with "key", so whole data becomes schema-less and is just organized in just 2 columns. One important property is that since the data is indexed by just the keys, there is a lot of scope of distributing keys over different instances, making the system highly scalable.

These kind of databases fall into the category of nosql data stores, satisfying the BASE properties (Basically Available, Soft state, Eventually consistent). In the context of the CAP theorem (Consistency, Availability, Partition tolerance), these databases fall into the category of CP. Since these databases are generally implemented in cluster mode, we cannot guarantee availability on data.

These databases are generally in-memory which reside in main memory. In-memory databases are faster than disk-optimized databases because disk access is slower than memory access, the internal optimization algorithms are simpler and execute fewer CPU instructions.

### Scalability

**Scalability** is the property of a system to handle a growing amount of work by adding resources to the system [?]. In layman terms, when you realise your system is getting slow and is unable to handle the current number of requests, you need to scale the system. Scaling can be done in two ways:

- **Vertical Scaling:** Increasing the resources in the server which we are currently using, i.e increase the amount of CPU, GPU, CPU, etc. Vertical scaling generally costly, also it may require the system to go down for a moment when the scaling takes place (need for downtime).
- **Horizontal Scaling:** Increasing the number of servers (instances). This would lead to decrease in the overall load on the system, if requests are sharded properly. This kind of scaling solution is typically popular in tech industries, as it makes the system fault tolerant (single point of failure reduced). Important advantage of this method is that it can provide administrators with the ability to increase capacity on the fly.

### Redis

Redis project started by Salvatore Sanfilippo (*antirez*) is an open source, in-memory data structure store, used as a database, cache and message broker [?]. Apart from basic key-value structure it also supports other data structures like: strings, hashes, lists, sets, sorted sets with range queries, bitmaps, hyperloglogs, geospatial indexes with radius queries and streams. Redis has built in support for replication, on-disk persistence and automated partitioning with Redis cluster. Redis also supports trivial-to-setup master-slave asynchronous replication, with very fast non-blocking first synchronization, auto-reconnection with partial resynchronization on net split [?]. There is also support to run these operations in atomic fashion with the help of transactions.

One intriguing property of redis which makes it different from other classical key value stores is: it gives support to mention expiration time for keys. This feature comes handy when we are using redis for cache purpose, old keys would be deleted automatically.


## Redis Cluster

Redis cluster can be defined as a collection of redis nodes which are able to communicate among themselves, and are able to respond to requests collectively. Redis Cluster provides a way to run a Redis installation where data is automatically sharded across multiple Redis nodes. Redis Cluster also provides some degree of availability during partitions that is in practical terms the ability to continue the operations when some nodes fail or are not able to communicate [?].

Every redis cluster node require two TCP ports, the lower one is used to server clients, while the higher one(lower port+10000) is used for Cluster bus (node-to-node communication). Redis cluster use CRC16 hashing system, using which every key is hashed to becomes part of one of 16384 hash slots (these are like buckets which contain keys, after hashing). So each cluster node is responsible for a subset of hash slots, that is keys which hash to a particluar hash slot, would be found in the node serving that hash slot. The user can force multiple keys to be part of the same hash slot by using a concept called hash tags.

### Creating a Redis Cluster

To create a redis cluster we need to run the required number of instances of redis (on different ports), and then inform all these nodes about cluster meet. A typical redis config file for cluster node is:



```
redis.conf
port 6379
cluster-enabled yes
cluster-config-file nodes.conf
cluster-node-timeout 5000
appendonly yes
```

After running all the required number of instances(with different ports, if running on same machine), we need to run:

```
\$ redis-cli --cluster create 127.0.0.1:7000 127.0.0.1:7001 \
127.0.0.1:7002 127.0.0.1:7003 127.0.0.1:7004 127.0.0.1:7005
```

Here the IPs mentioned are the host and ports of the redis instances. After running this command we are asked about the hash slot distribution, to be configured among the nodes. And that's it, all the node share infomation about cluster, and other nodes via messaging protocol. So after this process, each node will have a hash slot to node (IP:PORT) mapping, and all other cluster informations like node timeout etc.

### Redirection and Resharding

We assume that a client know nothing about the distribution of hash slots in the cluster, so it is equally probable to send a request to any of the node. On recieving a request, the redis node will find the hash slot to which this key belongs, if the hash slot is served by current node, it would simply return the value to the client. Is case hash slot is not served, it would check its internal hash slot to node map, and would respond to the client with an MOVED error, along this error message it would also send the IP of the node serving hash slot to which this key maps. This is pretty handy since client doesn't have to hit and try every node, it would get the correct address

after one try. Still there is an overhead, since we need to send a request twice (in worst case). We'll come to this issue in more detail in the partitioning section.

Redis Cluster supports the ability to add and remove nodes while the cluster is running. Adding or removing a node is abstracted into the same operation: moving a hash slot from one node to another. This means that the same basic mechanism can be used in order to rebalance the cluster, add or remove nodes, and so forth. Moving slots in running cluster is not an issue, since if the hash key is present in current node, it would simply return the value, in case that particular key is moved to another node, it would respond with an moved error. Hence resharding can be done in redis cluster without any down time.

## Partitioning

Partitioning refers to the way how we shard data among different nodes of redis cluster. Note that redis cluster provides a sharding scheme based on CRC16, but we can make some custom modification in the sharding scheme at different levels, these are:

1. **Client side partitioning:** In this scheme, redis clients select the node to which read/write request need to be made.
2. **Proxy assisted partitioning:** This scheme suggests that client sends request to a proxy, which analyzes the request and forwards it to the correct node. On receiving response it then returns it to the client. eg: Twemproxy
3. **Query Routing:** We can send request to any node, and the node will forward our request to the correct node. Redis cluster implements a similar kind of scheme, where instead of forwarding, it returns the address to which we should forward.

Among these partitioning schemes proxy assisted partitioning are most popular.

## **Design Details**

## References

- [1] Redis documentation, [redis.io](https://redis.io)
- [2] Bondi, Andre. *Characteristics of scalability and their impact on performance*. WOSP, 2000.