Intrusion-Detection-Model

1 Mounting Drive

```
[]: from google.colab import drive drive.mount('/content/drive')
```

2 Installations

```
[]: !pip install tensorflow --upgrade
[]: !pip install keras --upgrade
[]: !pip install yellowbrick==1.0.1
```

3 Imports

```
[]: import torch
     import torch.nn as nn
     from torch.utils.data import Dataset, DataLoader
     import os
     import numpy as np
     import pandas as pd
     import torch.optim as optim
     import torch.nn.functional as F
     import matplotlib.pyplot as plt
     from sklearn.decomposition import PCA
     import sklearn.cluster as cluster
     from mpl_toolkits.mplot3d import axes3d
     # from random import sample, shuffle
     import joblib
     from yellowbrick.cluster import KElbowVisualizer
     from scipy.stats import zscore, multivariate_normal
     import seaborn as sns
```

```
[]: import warnings warnings.filterwarnings('ignore')
```

4 Constants

```
[]: CSV_DIR = '/content/drive/My Drive/Colab Notebooks/Intrusion Detection/data/

→NSL-KDD/csv'

BATCH_SIZE = 128

FIG_TITLE_SIZE = 15

LEGEND_TEXT_SIZE = 11

MODELS_DIR = '/content/drive/My Drive/Colab Notebooks/Intrusion Detection/

→saved_models/grid_search'
```

5 Device Check for GPU

```
[]: device = torch.device('cuda: 0' if torch.cuda.is_available() else 'cpu')
print(device)
```

6 Dataset & DataLoader

6.1 NSLKDDDataset

6.2 NSLKDDFeatures

```
class NSLKDDFeatures(Dataset):
    def __init__(self, features):
        self.features = np.asarray(features)

def __len__(self):
        return self.features.shape[0]

def __getitem__(self, idx):
        return torch.from_numpy(self.features[idx])
```

6.3 NSLKDDSiameseNetDataSet

```
[]: class NSLKDDSiameseNetDataSet(Dataset):

    def __init__(self, partitioned_data, indices, labels, nsl_kdd_features):
        self.partitioned_data = partitioned_data
        self.indices = indices
        self.labels = labels
        self.nsl_kdd_features = nsl_kdd_features

def __len__(self):
    return len(self.indices)

def __getitem__(self, idx):
```

```
idx_tuple = self.indices[idx]
       if idx_tuple[0] == idx_tuple[1]:
           ret_list = self.partitioned_data[idx_tuple[0]][
               np.random.choice(
                   self.partitioned_data[idx_tuple[0]].shape[0], 2,__
\rightarrowreplace=False
       else:
           ret_list = list(map(
               lambda x: self.partitioned_data[x][
                   np.random.choice(self.partitioned_data[x].shape[0], 1)[0]
               ],
               idx_tuple)
           )
       return (
           torch.from_numpy(ret_list[0]),
           torch.from_numpy(ret_list[1]),
           torch.tensor(self.labels[idx], dtype=torch.int64)
       )
```

6.4 Training Data

```
[]: train_features_pd = pd.read_csv(os.path.join(CSV_DIR, 'training', __
     →'train_features_pca.csv'), header=None)
    train_labels_multiclass_pd = pd.read_csv(os.path.join(CSV_DIR, 'training', |
     train_labels_binary_pd = pd.read_csv(os.path.join(CSV_DIR, 'training', _
     →'train_labels_binary.csv'), header=None)
[]: train_features_pd.shape
[]: train_multiclass_ds = NSLKDDDataset(train_features, train_labels_multiclass)
    train_binary_ds = NSLKDDDataset(train_features, train_labels_binary)
[]: train_features_ds = NSLKDDFeatures(train_features)
[]: train_multiclass_dl = DataLoader(
        train_multiclass_ds,
        batch_size=BATCH_SIZE,
        shuffle=True
    )
    train_binary_dl = DataLoader(
```

```
train_binary_ds,
  batch_size=BATCH_SIZE,
  shuffle=True
)

train_features_dl = DataLoader(
  train_features_ds,
  batch_size=BATCH_SIZE,
  shuffle=True
)
```

6.5 Testing Data

```
[]: test_features_pd = pd.read_csv(os.path.join(CSV_DIR, 'testing',_
    test_labels_multiclass_pd = pd.read_csv(os.path.join(CSV_DIR, 'testing', __
     test_labels_binary_pd = pd.read_csv(os.path.join(CSV_DIR, 'testing',_
     []: test_features_pd.shape
[]: test_multiclass_ds = NSLKDDDataset(test_features, test_labels_multiclass)
    test_binary_ds = NSLKDDDataset(test_features, test_labels_binary)
[ ]: test_features_ds = NSLKDDFeatures(test_features)
[]: test_multiclass_dl = DataLoader(
       test_multiclass_ds,
       batch_size=BATCH_SIZE,
       shuffle=True
    )
    test_binary_dl = DataLoader(
       test_binary_ds,
       batch_size=BATCH_SIZE,
       shuffle=True
    test_features_dl = DataLoader(
       test_features_ds,
       batch_size=BATCH_SIZE,
       shuffle=True
    )
```

6.6 NumPy Arrays

```
[]: train_features_np = np.asarray(train_features_pd)
test_features_np = np.asarray(test_features_pd)

train_labels_binary_np = np.asarray(train_labels_binary_pd)
test_labels_binary_np = np.asarray(test_labels_binary_pd)

train_labels_multiclass_np = np.asarray(train_labels_multiclass_pd)
test_labels_multiclass_np = np.asarray(test_labels_multiclass_pd)
```

7 Data Plots

7.1 Plot Pie Chart

```
[]: def plot_pie_chart(labels_one_hot, title, figure_size=(8,8), have_title=True,__
      →log_scaling=False):
         labels = np.argmax(labels_one_hot, axis=1)
         names = ['Normal', 'DoS', 'Probe', 'R2L', 'U2R']
         _, sizes = np.unique(labels, return_counts=True)
         names_sizes_dict = dict(zip(names, sizes))
         sorted_names_sizes_dict = {k: v for k, v in sorted(
             names_sizes_dict.items(),
             key=lambda item: item[1],
             reverse=True
         )}
         names = list(sorted_names_sizes_dict.keys())
         sizes = list(sorted_names_sizes_dict.values())
         if log_scaling:
             sizes = np.log(sizes)
         fig = plt.figure(figsize=figure_size)
         ax = fig.add_subplot()
         theme = plt.get_cmap('gray')
         ax.set_prop_cycle('color', [theme(1. * i / len(sizes))
                                  for i in range(len(sizes))])
         patches, texts, autotexts = ax.pie(
             sizes,
             autopct='%1.1f%%',
```

```
startangle=90
         )
         autotexts[0].set_color('w')
         autotexts[1].set_color('w')
         # for text in autotexts:
         # text.set_fontsize(11)
         ax.axis('equal') # Equal aspect ratio ensures that pie is drawn as a circle.
         if have_title:
             plt.title(
                 title,
                 fontsize=LEGEND_TEXT_SIZE
             )
         plt.legend(
             names,
             fontsize=11
         )
         plt.savefig(title + '.png')
[]: plot_pie_chart(
         train_labels_multiclass_np,
         title='Class Distributions: Training Data (log scaled)',
         figure_size=(10,10),
         have_title=False,
         log_scaling=True
     )
[]: plot_pie_chart(
         test_labels_multiclass_np,
         title='Class Distributions: Testing Data (log scaled)',
         figure_size=(10,10),
         have_title=False,
         log_scaling=True
```

8 Model

8.1 Autoencoder

8.2 Anomaly Detector

```
class AnomalyDetector(nn.Module):
    def __init__(self):
        super(AnomalyDetector, self).__init__()

    self.activation = nn.LeakyReLU(inplace=True)

self.model = nn.Sequential(
    # nn.BatchNorm1d(num_features=67),
        nn.Linear(in_features=67, out_features=100),
        self.activation,

        nn.BatchNorm1d(num_features=100),
        nn.Linear(in_features=100, out_features=120),
        self.activation,

        nn.BatchNorm1d(num_features=120),
        nn.Linear(in_features=120, out_features=60),
```

```
self.activation,

nn.BatchNorm1d(num_features=60),
nn.Linear(in_features=60, out_features=30),
self.activation,

nn.BatchNorm1d(num_features=30),
nn.Linear(in_features=30, out_features=10),
self.activation,

nn.BatchNorm1d(num_features=10),
nn.Linear(in_features=10, out_features=2),
nn.Softmax(dim=1)
)

def forward(self, x):
    x = self.model(x)

    return x
```

8.3 SignatureGenerator

```
[]: class SignatureGenerator(nn.Module):
         def __init__(self):
             super(SignatureGenerator, self).__init__()
             self.activation = nn.LeakyReLU(inplace=True)
             self.model = nn.Sequential(
                 nn.Linear(in_features=67, out_features=100),
                 self.activation,
                 nn.BatchNorm1d(num_features=100),
                 nn.Linear(in_features=100, out_features=80),
                 self.activation,
                 nn.BatchNorm1d(num_features=80),
                 nn.Linear(in_features=80, out_features=60),
                 self.activation,
                 nn.BatchNorm1d(num_features=60),
                 nn.Linear(in_features=60, out_features=40),
                 self.activation,
                 nn.BatchNorm1d(num_features=40),
```

```
nn.Linear(in_features=40, out_features=20),
    self.activation,
    nn.BatchNorm1d(num_features=20),
    nn.Linear(in_features=20, out_features=10),
    nn.Sigmoid()
)

def forward(self, x):
    x = self.model(x)
    return x
```

8.4 L1Difference

```
[]: class L1Difference(nn.Module):
    def __init__(self):
        super(L1Difference, self).__init__()

    def forward(self, x1, x2):
        return abs(x1 - x2)
```

8.5 SiameseNet

```
class SiameseNet(nn.Module):
    def __init__(self):
        super(SiameseNet, self).__init__()
    self.signature_gen = SignatureGenerator()
    self.ll_diff = L1Difference()
    self.fc = nn.Linear(in_features=10, out_features=2)

def forward(self, x1, x2):
    x1_sig = self.signature_gen(x1)
    x2_sig = self.signature_gen(x2)

l1_diff = self.l1_diff(x1_sig, x2_sig)
    out = torch.softmax(self.fc(l1_diff), dim=1)
    return out
```

8.6 MultiClassClassifier

```
[]: class MultiClassClassifier(nn.Module):
         def __init__(self):
             super(MultiClassClassifier, self).__init__()
             self.model = nn.Sequential(
                 nn.Linear(in_features=67, out_features=120),
                 nn.ReLU(inplace=True),
                 nn.BatchNorm1d(num_features=120),
                 nn.Linear(in_features=120, out_features=100),
                 nn.ReLU(inplace=True),
                 nn.BatchNorm1d(num_features=100),
                 nn.Linear(in_features=100, out_features=80),
                 nn.ReLU(inplace=True),
                 nn.BatchNorm1d(num_features=80),
                 nn.Linear(in_features=80, out_features=40),
                 nn.ReLU(inplace=True),
                 nn.BatchNorm1d(num_features=40),
                 nn.Linear(in_features=40, out_features=20),
                 nn.ReLU(inplace=True),
                 nn.BatchNorm1d(num_features=20),
                 nn.Linear(in_features=20, out_features=10),
                 nn.ReLU(inplace=True),
                 nn.BatchNorm1d(num_features=10),
                 nn.Linear(in_features=10, out_features=5),
                 nn.Softmax(dim=1)
             )
         def forward(self, x):
             return self.model(x)
```

9 Training Utilities

9.1 Network Loss

```
[]: def get_network_loss(net, dataloader):
    agg_loss = 0.0

    criterion = nn.CrossEntropyLoss()

    for i, data in enumerate(dataloader, 0):
        x, y = data
        y = torch.argmax(y, dim=1)

        x = x.to(device)
        y = y.to(device)

    outputs = net(x)
    loss = criterion(outputs, y)
        agg_loss += loss.item()

    return agg_loss / len(dataloader)
```

9.2 Train Network

```
[]: def train_network(net, trainloader, testloader, n_epochs, print_every=500):
         net.double()
         net.to(device)
         optimizer = optim.Adam(net.parameters())
         criterion = nn.CrossEntropyLoss()
         train_losses = []
         test_losses = []
         for epoch in range(n_epochs):
             running_loss = 0.0
             for i, data in enumerate(trainloader):
                 x, y = data
                 y = torch.argmax(y, dim=1)
                 x = x.to(device)
                 y = y.to(device)
                 optimizer.zero_grad()
                 outputs = net(x)
                 loss = criterion(outputs, y)
```

```
loss.backward()
        optimizer.step()
        running_loss += loss.item()
        if i % print_every == print_every-1:
            print('[%d, %5d] loss: %.6f' %
              (epoch + 1, i + 1, running_loss / print_every))
            running_loss = 0.0
    net.eval()
    train_loss = get_network_loss(net, trainloader)
    test_loss = get_network_loss(net, testloader)
    net.train()
    train_losses.append(train_loss)
    test_losses.append(test_loss)
    print('Training Loss: %.6f' % (train_loss))
    print('Testing Loss: %.6f' % (test_loss))
return train_losses, test_losses
```

9.3 Encoder Loss

9.4 Train Encoder

```
[]: def train_encoder(autoencoder, trainloader, testloader, n_epochs,_
      →print_every=500, autoencoder1=None, autoencoder2=None):
         autoencoder.double()
         autoencoder.to(device)
         optimizer = optim.Adam(autoencoder.parameters())
         criterion = nn.MSELoss()
         train losses = []
         test_losses = []
         for epoch in range(n_epochs):
             running_loss = 0.0
             for i, data in enumerate(trainloader, 0):
                 x = data
                 x = x.to(device)
                 with torch.no_grad():
                     if autoencoder1:
                         x = autoencoder1.encoder(x)
                     if autoencoder2:
                         x = autoencoder2.encoder(x)
                 optimizer.zero_grad()
                 outputs = autoencoder(x)
                 loss = criterion(outputs, x)
                 loss.backward()
                 optimizer.step()
                 running_loss += loss.item()
                 if i % print_every == print_every-1:
                     print('[%d, %5d] loss: %.6f' %
                       (epoch + 1, i + 1, running_loss / print_every))
                     running_loss = 0.0
             autoencoder.eval()
             train_loss = get_encoder_loss(autoencoder, trainloader, criterion, u
      →autoencoder1=autoencoder1, autoencoder2=autoencoder2)
             test_loss = get_encoder_loss(autoencoder, testloader, criterion, __
      →autoencoder1=autoencoder1, autoencoder2=autoencoder2)
             autoencoder.train()
             train_losses.append(train_loss)
             test_losses.append(test_loss)
             print('Training Loss: %.6f' % (train_loss))
```

```
print('Testing Loss: %.6f' % (test_loss))
return train_losses, test_losses
```

9.5 SiameseNet Loss

```
[]: def get_siamese_net_loss(siamese_net, dataloader, val_batches):
    agg_loss = 0.0
    criterion = nn.CrossEntropyLoss()

for i, data in enumerate(dataloader, 0):
    x1, x2, y = data

    x1 = x1.to(device)
    x2 = x2.to(device)
    y = y.to(device)

    outputs = siamese_net(x1.double(), x2.double())
    loss = criterion(outputs, y)
    agg_loss += loss.item()

if i == val_batches-1:
    break

return agg_loss / val_batches
```

9.6 Train SiameseNet

```
x2 = x2.to(device)
        y = y.to(device)
        optimizer.zero_grad()
        outputs = siamese_net(x1.double(), x2.double())
        outputs = torch.squeeze(outputs)
        loss = criterion(outputs, y)
        loss.backward()
        optimizer.step()
        running_loss += loss.item()
        if i % print_every == print_every-1:
            print('[%d, %5d] loss: %.6f' %
              (epoch + 1, i + 1, running_loss / print_every))
            running_loss = 0.0
    siamese_net.eval()
    train_loss = get_siamese_net_loss(siamese_net, trainloader, val_batches)
    test_loss = get_siamese_net_loss(siamese_net, testloader, val_batches)
    siamese net.train()
    train_losses.append(train_loss)
    test_losses.append(test_loss)
    print('Training Loss: %.6f' % (train_loss))
    print('Testing Loss: %.6f' % (test_loss))
return train_losses, test_losses
```

9.7 Partition Dataset

```
[]: def partition_dataset(data, labels):
    unique_labels = np.unique(labels)
    final_data = [None] * len(unique_labels)
    n_samples = len(labels)
    for i in range(n_samples):
        curr_class = labels[i]
        if final_data[curr_class]:
            final_data[curr_class].append(data[i])
        else:
            final_data[curr_class] = [data[i]]

return list(map(lambda x: np.asarray(x), final_data))
```

9.8 Plotting Losses

```
[]: def plot_losses(train_losses, test_losses, title, xlabel, ylabel, start_idx=1,,,
      →interval_length=1, figure_size=(14,14)):
         train_losses_aggregated = []
         test_losses_aggregated = []
         n_epochs = len(train_losses)
         start idx -= 1
         i = start_idx
         while i < n_epochs:
             curr_train_sum = sum(train_losses[i : min(n_epochs, i +__
      →interval_length)])
             curr_test_sum = sum(test_losses[i : min(n_epochs, i + interval_length)])
             train_losses_aggregated.append(curr_train_sum / interval_length)
             test_losses_aggregated.append(curr_test_sum / interval_length)
             i += interval_length
         n = len(train_losses_aggregated)
         x = list(map(lambda x: (x * interval_length) + start_idx, np.arange(1, n+1)))
         plt.figure(figsize=figure_size)
         plt.plot(x, train_losses_aggregated, marker='o', linestyle='dashed')
         plt.plot(x, test_losses_aggregated, marker='o', linestyle='dashed')
         plt.legend(['Training Loss', 'Testing Loss'])
         plt.xlabel(xlabel)
         plt.ylabel(ylabel)
         plt.title(title)
         plt.grid()
         plt.xticks(x)
         plt.savefig(title + '.png')
         plt.show()
```

9.9 Saving and Loading Models

```
[]: def save_state_dict(model, filename):
    torch.save(model.state_dict(), filename)

[]: def load_state_dict(model, state_dict_path):
    state_dict = torch.load(state_dict_path)
    model.load_state_dict(state_dict)
```

```
model.double()
model.to(device)
```

10 Training

10.1 Autoencoders

10.1.1 Label Encoding

```
Autoencoder 1
[]: autoencoder_label_1 = Autoencoder(in_features=40, out_features=20)
     print(autoencoder_label_1)
[]: train_losses_encoder_label_1, test_losses_encoder_label_1 = train_encoder(
         autoencoder_label_1,
         trainloader=train_label_loader,
         testloader=test_label_loader,
         n_epochs=30
     )
[]: plot_losses(
         train_losses_encoder_label_1,
         test_losses_encoder_label_1,
         # start_i dx = 11,
         title='autoencoder_label_1',
         xlabel='Epochs',
         ylabel='Losses',
         interval_length=1,
         figure_size=(14,8)
     )
[]: save_state_dict(autoencoder_label_1, 'autoencoder_label_1.pth')
```

Autoencoder 2

```
[]: autoencoder_label_2 = Autoencoder(in_features=20, out_features=10) print(autoencoder_label_2)
```

```
[]: plot_losses(
    train_losses_encoder_label_2,
    test_losses_encoder_label_2,
    # start_idx=11,
    title='autoencoder_label_2',
    xlabel='Epochs',
    ylabel='Losses',
    interval_length=1,
    figure_size=(14,8)
)
```

```
[]: save_state_dict(autoencoder_label_2, 'autoencoder_label_2.pth')
```

10.2 Networks

```
[]: LOAD_DIR = '/content/drive/My Drive/Colab Notebooks/Intrusion Detection/

saved_models'
```

10.2.1 Loading Autoencoder 1

```
[]: autoencoder_label_1 = Autoencoder(in_features=40, out_features=20) load_state_dict(autoencoder_label_1, os.path.join(LOAD_DIR, 'autoencoder_label_1. 

→pth'))
```

10.2.2 Loading Autoencoder 2

```
[]: autoencoder_label_2 = Autoencoder(in_features=20, out_features=10)
load_state_dict(autoencoder_label_2, os.path.join(LOAD_DIR, 'autoencoder_label_2.

→pth'))
```

10.2.3 AnomalyDetector

```
[ ]: anomaly_detector = AnomalyDetector()
    print(anomaly_detector)
```

```
print_every=100
)

[]: plot_losses(
    train_losses_network_label,
    test_losses_network_label,
    # start_idx=37,
    title='network_label_double_encoder',
    xlabel='Epochs',
    ylabel='Losses',
    interval_length=1,
    figure_size=(14,8))
```

10.3 Data Distributions

10.3.1 PCA

```
[ ]: pca = PCA(n_components=3)
   pca.fit(train_features_np)

[ ]: train_features_3dims = pca.transform(train_features_np)
   test_features_3dims = pca.transform(test_features_np)
```

10.3.2 Groups

10.3.3 Plot Points

```
[]: def plot_points(
             features,
             labels,
             title,
             groups,
             class_idx=None,
             one_hot_labels=True,
             figure_size=(8,8)
         ):
         fig = plt.figure(figsize=figure_size)
         ax = fig.add_subplot(111, projection='3d')
         if one_hot_labels:
             labels_indices = np.asarray(list(map(lambda x: np.argmax(x), labels)))
         else:
             labels_indices = labels
         data = []
         if class_idx:
             i = class_idx
             curr_data_indices = np.where(labels_indices == i)[0]
             curr_data = features[curr_data_indices]
             data.append(curr_data)
         else:
             for i in range(len(groups)):
                 curr_data_indices = np.where(labels_indices == i)[0]
                 curr_data = features[curr_data_indices]
                 data.append(curr_data)
         all_colors = (
             'grey',
             'orange',
             'cyan',
             'green',
             'maroon',
             'chocolate',
             'lightgreen',
             'dodgerblue',
             'darkslategray',
             'lightseagreen',
             'mediumspringgreen',
             'rebeccapurple',
             'hotpink',
             'indigo',
```

```
'midnightblue',
    'gold',
    'black',
    'crimson',
    'darkkhaki',
    'aqua'
)
colors = sample(all_colors, len(groups))
for features, color, group in zip(data, colors, groups):
    x = list(map(lambda x: x[0], features))
    y = list(map(lambda x: x[1], features))
    z = list(map(lambda x: x[2], features))
    ax.scatter(
        x, y, z,
        c=color,
        label=group,
    )
plt.legend()
plt.title(
    title,
    fontsize=15,
    loc='left'
)
plt.savefig(title + '.png')
```

10.3.4 Training Data Plots

Binary Class Distribution

```
[]: plot_points(
          train_features_3dims,
          train_labels_binary_np,
          groups=groups_binary,
          title='Binary Class Distribution',
          figure_size=(14,14)
)
```

Multi Class Distribution

```
groups=groups_multiclass,
  title='Multi Class Distribution',
  figure_size=(14,14)
)
```

Malicious Data Point Distributions

```
DoS

[]: plot_points(
          train_features_3dims,
          train_labels_multiclass_np,
          class_idx=1,
          groups=['DoS'],
          title='DoS',
          figure_size=(14,14)
)
```

Probe

```
[]: plot_points(
          train_features_3dims,
          train_labels_multiclass_np,
          class_idx=2,
          groups=['Probe'],
          title='Probe',
          figure_size=(14,14)
)
```

R₂L

```
[]: plot_points(
          train_features_3dims,
          train_labels_multiclass_np,
          class_idx=3,
          groups=['R2L'],
          title='R2L',
          figure_size=(14,14)
)
```

U2R

```
[]: plot_points(
          train_features_3dims,
          train_labels_multiclass_np,
          class_idx=4,
```

```
groups=['U2R'],
title='U2R',
figure_size=(14,14)
)
```

10.4 Anomaly Detection

10.4.1 Utilities

Plot Confusion Matrix

```
[]: def plot_confusion_matrix(
             cm, classes,
             normalize=False,
             title='Confusion Matrix',
             cmap=plt.cm.Blues,
             print_cm=False,
             save=False
         ):
         nnn
         This function prints and plots the confusion matrix.
         Normalization can be applied by setting `normalize=True`.
         import matplotlib.pyplot as plt
         import numpy as np
         import itertools
         if normalize:
             cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]
             print("Normalized confusion matrix")
         else:
             print('Confusion matrix, without normalization')
         if print_cm:
             print(cm)
         plt.imshow(cm, interpolation='nearest', cmap=cmap)
         # plt.title(title)
         plt.colorbar()
         tick_marks = np.arange(len(classes))
         plt.xticks(tick_marks, classes, rotation=45)
         plt.yticks(tick_marks, classes)
         fmt = '.2f' if normalize else 'd'
         thresh = cm.max() / 2.
         for i, j in itertools.product(range(cm.shape[0]), range(cm.shape[1])):
```

One Hot to Label Encoding

```
[]: def to_label(arr):
    return np.argmax(arr, axis=1)
```

Get Predictions

```
[]: def get_predictions(estimator, features, labels):
    return to_label(labels), estimator.predict(features), estimator.
    →predict_proba(features)
```

Get Scores

```
[]: def get_scores(y_true, y_pred):
    accuracy = accuracy_score(y_true, y_pred)
    precision = precision_score(y_true, y_pred)
    recall = recall_score(y_true, y_pred)
    f1 = f1_score(y_true, y_pred)

    return {
        'accuracy': accuracy,
        'precision': precision,
        'recall': recall,
        'f1': f1
}
```

Get Adjusted Classes

```
[]: def get_adjusted_classes(y_probs, thresh=0.5):
    return [int(y_prob >= thresh) for y_prob in y_probs]
```

Plot ROC Curve

```
[]: def plot_roc_curve(fpr, tpr, title, label=None, figure_size=(8,8)):
    """
    The ROC curve, modified from
    Hands-On Machine learning with Scikit-Learn and TensorFlow; p.91
    """
    plt.figure(figsize=figure_size)
    plt.title('ROC Curve')
    plt.plot(fpr, tpr, linewidth=2, label=label)
    plt.plot([0, 1], [0, 1], 'k--')
    plt.axis([-0.005, 1, 0, 1.005])
    plt.xticks(np.arange(0,1, 0.05), rotation=90)
    plt.xlabel("False Positive Rate")
    plt.ylabel("True Positive Rate (Recall)")
    plt.legend(loc='best')

plt.savefig(title + '.png')
```

Plot Precision Vs Recall

```
[]: def plot_precision_recall_curve(p, r, y_scores, y_test, thresholds, title, t=0.
      \rightarrow5, figure_size=(8,8)):
         nnn
         Plots the precision recall curve and shows the current value for each
         by identifying the classifier's threshold (t).
         nnn
         # generate new class predictions based on the adjusted_classes
         # function above and view the resulting confusion matrix.
         v_pred_adj = get_adjusted_classes(v_scores, t)
         # plot the curve
         plt.figure(figsize=figure_size)
         plt.title(title)
         plt.step(r, p, color='b', alpha=0.2,
                  where='post')
         plt.fill_between(r, p, step='post', alpha=0.2,
                          color='b')
         plt.ylim([0.5, 1.01]);
         plt.xlim([0.5, 1.01]);
         plt.xlabel('Recall');
         plt.ylabel('Precision');
         # plot the current threshold on the line
         close_default_clf = np.argmin(np.abs(thresholds - t))
         plt.plot(r[close_default_clf] - 0.01, p[close_default_clf], '.', c='k',
                 markersize=15)
         plt.text(r[close_default_clf], p[close_default_clf], 'Current Threshold')
```

```
plt.savefig(title + '.png')
```

Plot Precision and Recall Vs Threshold

```
[]: def plot_precision_recall_vs_threshold(precisions, recalls, thresholds, title, u
      \rightarrowfigure_size=(8,8)):
         nnn
         Modified from:
         Hands-On Machine learning with Scikit-Learn
         and TensorFlow; p.89
         idx = np.argmin(abs(precisions - recalls))
         plt.figure(figsize=figure_size)
         plt.title(title)
         plt.plot(thresholds, precisions[:-1], "k--", label="Precision")
         plt.plot(thresholds, recalls[:-1], "k-", label="Recall")
         plt.plot(thresholds[idx], precisions[idx], 'ro')
         plt.text(thresholds[idx] + 0.01, precisions[idx], f'Threshold =
      →{thresholds[idx]}')
         plt.ylabel("Score")
         plt.xlabel("Decision Threshold")
         plt.legend(loc='best')
         plt.savefig(title + '.png')
         return thresholds[idx]
```

10.4.2 Clustering Normal Points

```
plot_points(
    train_features_3dims,
    train_labels_multiclass_np,
    class_idx=0,
    groups=['Normal'],
    title='Normal',
    figure_size=(14,14)
)
```

K-Means

Finding Optimal Clusters using K-Elbow Visualizer

```
[]: model = cluster.KMeans(random_state=42)
visualizer = KElbowVisualizer(
    model,
    k=(2,11),
    metric='calinski_harabasz'
)
visualizer.fit(train_features_normal)
```

```
Fitting
[]: N_CLUSTERS = 4

[]: kmeans_normal = cluster.KMeans(n_clusters=N_CLUSTERS, random_state=42)
    kmeans_normal.fit(train_features_normal)

[]: kmeans_normal.inertia_

[]: train_labels_normal = kmeans_normal.predict(train_features_normal)

[]: plot_points(
    features=pca.transform(train_features_normal),
    labels=train_labels_normal,
    groups=['Cluster' + str(i+1) for i in range(N_CLUSTERS)],
    one_hot_labels=False,
    title='K-Means Clustering on Normal Data Points - Training',
    figure_size=(14,14)
)

[]: test_labels_normal = kmeans_normal.predict(test_features_normal)
```

```
[]: plot_points(
         features=pca.transform(test_features_normal),
         labels=test_labels_normal,
         groups=['Cluster ' + str(i+1) for i in range(N_CLUSTERS)],
         one_hot_labels=False,
         title='K-Means Clustering on Normal Data Points - Testing',
         figure_size=(14,14)
     )
[]: joblib.dump(kmeans_normal, 'kmeans_normal.joblib')
    Partitioning Dataset
[]: partitioned_training_data_normal = partition_dataset(train_features_normal,_
      →train_labels_normal)
[]: for data in partitioned_training_data_normal:
         print(data.shape)
[]: partitioned_testing_data_normal = partition_dataset(test_features_normal,_
      →test_labels_normal)
[]: for data in partitioned_testing_data_normal:
         print(data.shape)
    SiameseNet Generating Data for NSLKDDSiameseNetDataset Instance
[ ]: TRAIN_MULT_FACTOR = 100000
     TEST MULT FACTOR = 20000
[]: indices = []
     for i in range(N_CLUSTERS):
         for j in range(i, N_CLUSTERS):
             indices.append((i,j))
     train_indices_final = indices * TRAIN_MULT_FACTOR
     shuffle(train_indices_final)
     test_indices_final = indices * TEST_MULT_FACTOR
     shuffle(test_indices_final)
[]: len(train_indices_final), len(test_indices_final)
[]: train_labels = list(map(lambda x: int(x[0] == x[1]), train_indices_final))
     test_labels = list(map(lambda x: int(x[0] == x[1]), test_indices_final))
```

```
[]: len(train_labels), len(test_labels)
    NSLKDDSiameseNetDataset Instance
[]: train_data_siamese_net = NSLKDDSiameseNetDataSet(
         partitioned_training_data_normal,
         train_indices_final,
         np.asarray(train_labels),
         train_features
     )
[]: trainloader_siamese_net = DataLoader(
         train_data_siamese_net,
         batch_size=256,
         shuffle=True
     )
[]: test_data_siamese_net = NSLKDDSiameseNetDataSet(
         partitioned_testing_data_normal,
         test_indices_final,
         np.asarray(test_labels),
         train_features
     )
[]: testloader_siamese_net = DataLoader(
         test_data_siamese_net,
         batch_size=256,
         shuffle=True
    Training Signatures for Each Cluster
[]: siamese_net = SiameseNet()
     print(siamese_net)
[]: train_losses_siamese_net, test_losses_siamese_net = train_siamese_net(
         siamese_net,
         trainloader=trainloader_siamese_net,
         testloader=testloader_siamese_net,
         n_epochs=50
     )
[]:
    Z-Score
[]: curr_cluster = partitioned_training_data_normal[0]
```

```
[ ]: curr_cluster.shape
[ ]: z_scores = zscore(curr_cluster)
[ ]: z_scores.shape
[ ]: sns.kdeplot(z_scores[:,5])
```

10.4.3 Random Forest Classifier

Grid Search

```
Recall
```

```
[]: rfc = RandomForestClassifier(
    class_weight='balanced',
    max_depth=58,
    min_samples_leaf=2
)

param_grid = {
    'n_estimators': np.arange(100, 120),
}

rfc_grid_search_recall = GridSearchCV(
    estimator=rfc,
    param_grid=param_grid,
    scoring=make_scorer(recall_score),
    verbose=2,
    cv=5,
    n_jobs=5
)
```

```
[]: rfc_grid_search_recall.fit(train_features_np, to_label(train_labels_binary_np))
```

```
[ ]: rfc_grid_search_recall.best_score_
```

```
[]: rfc_grid_search_recall.best_params_
```

```
[]: joblib.dump(rfc_grid_search_recall, 'rfc_grid_search_recall.joblib')
```

Model

```
[]: rfc_grid_search_recall = joblib.load(os.path.join(MODELS_DIR, 

→'rfc_grid_search_recall.joblib'))
```

```
[]: rfc = rfc_grid_search_recall.best_estimator_
     y_true, y_pred, y_probs = get_predictions(
         test_features_np,
         test_labels_binary_np
     )
[]: cm = confusion_matrix(
        y_pred=y_pred,
         y_true=y_true
     )
[]: plot_confusion_matrix(
         cm,
         classes=[0,1],
         title='Random Forest Classifier with Optimized Recall',
         save=True,
         normalize=True,
         cmap=plt.cm.Greys
     )
[]: p, r, thresholds = precision_recall_curve(y_true, y_probs[:,1])
[]: best_threshold_rfc = plot_precision_recall_vs_threshold(
         p, r, thresholds,
         title='Precision and Recall Scores as a Function of the Decision Threshold',
     )
[]: plot_precision_recall_curve(
         p, r, y_probs[:,1], y_true, thresholds,
         title='Precision Recall Curve',
         t=best_threshold_rfc,
     )
[]:|fpr, tpr, auc_thresholds = roc_curve(y_true, y_probs[:,1])
[]: auc(fpr, tpr)
[]: plot_roc_curve(
         fpr, tpr,
         title='ROC Curve',
         label='Recall Optimized'
[]: y_pred_adjusted = get_adjusted_classes(y_probs[:,1], thresh=best_threshold_rfc)
```

10.4.4 AdaBoost Classifier

Grid Search

```
Recall
```

Model

→joblib')

```
[]: adaboost_clf_grid_search_recall = joblib.load(os.path.join(MODELS_DIR, ⊔
→'adaboost_clf_grid_search_recall.joblib'))
```

```
[]: adaboost_clf = adaboost_clf_grid_search_recall.best_estimator_
     y_true, y_pred, y_probs = get_predictions(
         adaboost_clf,
         test_features_np,
         test_labels_binary_np
     )
[]: cm = confusion_matrix(
        y_pred=y_pred,
         y_true=y_true
     )
[]: plot_confusion_matrix(
         cm,
         classes=[0,1],
         title='AdaBoost Classifier with Optimized Recall',
         save=True,
         normalize=True,
         cmap=plt.cm.Greys
     )
[]: p, r, thresholds = precision_recall_curve(y_true, y_probs[:,1])
[]: best_threshold = plot_precision_recall_vs_threshold(
         p, r, thresholds,
         title='Precision and Recall Scores as a Function of the Decision Threshold',
     )
[]: plot_precision_recall_curve(
         p, r, y_probs[:,1], y_true, thresholds,
         title='Precision Recall Curve',
         t=best_threshold,
     )
[]:|fpr, tpr, auc_thresholds = roc_curve(y_true, y_probs[:,1])
[]: auc(fpr, tpr)
[]: plot_roc_curve(
         fpr, tpr,
         title='ROC Curve',
         label='Recall Optimized'
[]: y_pred_adjusted = get_adjusted_classes(y_probs[:,1], thresh=best_threshold)
```

```
[]: cm = confusion_matrix(
         y_pred=y_pred_adjusted,
         y_true=y_true
[]: plot_confusion_matrix(
         cm.
         classes=[0,1],
         title='AdaBoost Classifier with Optimized Recall',
         save=True,
         normalize=True,
         cmap=plt.cm.Greys
[]:
    10.5 MultiClassClassifier
    Utilities
[]: def print_counts(labels):
         labels = np.argmax(labels, axis=1)
         for i in range(5):
             print(len(np.where(labels == i)[0]))
[]: print_counts(test_labels_multiclass_np)
    Model
[]: over_sampler = SVMSMOTE()
[]: x_train, y_train = over_sampler.fit_resample(
         train_features_np, np.argmax(
             train_labels_multiclass_np,
             axis=1
         )
     )
[]: x_train, y_train = shuffle(x_train, y_train)
[]: Counter(y_train)
[]: x_test, y_test = test_features_np, test_labels_multiclass_np
[]: x_train.shape, x_test.shape, y_train.shape, y_test.shape
```

```
[]: lstm_output_size = 70
[]: cnn = Sequential()
     cnn.add(Convolution1D(64, 3, __
     →border_mode="same", activation="relu", input_shape=(67, 1)))
     cnn.add(Convolution1D(64, 3, border_mode="same", activation="relu"))
     cnn.add(MaxPooling1D(pool_length=(2)))
     cnn.add(Convolution1D(128, 3, border_mode="same", activation="relu"))
     cnn.add(Convolution1D(128, 3, border_mode="same", activation="relu"))
     cnn.add(MaxPooling1D(pool_length=(2)))
     cnn.add(LSTM(lstm_output_size))
     cnn.add(Dropout(0.1))
     cnn.add(Dense(5, activation="softmax"))
[]: cnn.summary()
[]: cnn.compile(loss='categorical_crossentropy', optimizer='adam',__
      →metrics=['accuracy'])
[]: history_1 = cnn.fit(
         np.expand_dims(x_train, axis=2), to_categorical(
             y_train,
             num classes=5
         ),
         batch_size=128,
         epochs=5,
         validation_data=(
             np.expand_dims(x_test, axis=2), y_test
         )
[]: all_losses = []
[]: for loss in history_1.history['loss']:
         all_losses.append(loss)
[]: all_acc = []
[]: for acc in history_1.history['accuracy']:
         all_acc.append(acc)
[]: len(all_losses), len(all_acc)
[]: plt.figure(figsize=(8,8))
     plt.plot(
         np.linspace(1, 10, 10) * 10,
```

```
all_losses,
         'k--',
         marker='D'
     plt.xlabel('Epochs')
     plt.ylabel('Loss')
     plt.savefig('Loss.png')
[]: plt.figure(figsize=(8,8))
     plt.plot(
         np.linspace(1, 10, 10) * 10,
         all_acc,
         'k--',
         marker='D'
     plt.xlabel('Epochs')
     plt.ylabel('Accuracy')
     plt.savefig('Accuracy.png')
[]: cnn.save('conv_model.h5')
[]: import pickle as pk
     with open('history.pkl', 'wb') as f:
         pk.dump(history, f)
[]: import pickle as pk
     with open('history_1.pkl', 'wb') as f:
         pk.dump(history_1, f)
[]: plot_model(cnn, show_layer_names=False, show_shapes=True, t)
[ ]: y_pred_rfc = rfc.predict(test_features_np)
[]: normal_samples_indices = np.where(y_pred_rfc == 0)[0]
     x_train_normal = test_features_np[normal_samples_indices]
     y_train_multiclass_normal = test_labels_multiclass_np[normal_samples_indices]
[]: y_train_multiclass_normal
[]: x_train_normal.shape, y_train_multiclass_normal.shape
```

```
[]: malicious_samples_indices = np.where(y_pred_rfc == 1)[0]
     x_train_malicious = test_features_np[malicious_samples_indices]
     y_train_multiclass_malicious = ___
      →test_labels_multiclass_np[malicious_samples_indices]
[]: x_train_malicious.shape, y_train_multiclass_malicious.shape
[]: y_true, y_pred, _ = get_predictions(
         np.expand_dims(x_train_malicious, axis=2),
         y_train_multiclass_malicious
[]: y_true_with_zeros = np.concatenate((y_true, np.argmax(y_train_multiclass_normal,_
      \rightarrowaxis=1)))
[]: y_true_with_zeros.shape
[]: pred = np.argmax(y_pred, axis=1)
[]: pred_with_zeros = np.concatenate((pred, np.asarray([0] * 13920)))
[]: pred_with_zeros.shape
[]: pred_with_zeros
[]: cm = confusion_matrix(
         y_pred=pred_with_zeros,
         y_true=y_true_with_zeros
[]: plot_confusion_matrix(
         classes=['Normal', 'DoS', 'Probe', 'U2R', 'R2L'],
         title='Final Confusion',
         save=True,
         normalize=True,
         cmap=plt.cm.Greys
[]:
```