

History entanglement entropy

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Abstract

A formalism is proposed to describe entangled quantum histories, and their entanglement entropy. We define a history vector, living in a tensor space with basis elements corresponding to the allowed histories, i.e. histories with nonvanishing amplitudes. The amplitudes are the components of the history vector, and contain the dynamical information. Probabilities of measurement sequences, and resulting collapse, are given by generalized Born rules: they are all expressed by means of projections and scalar products involving the history vector. Entangled history states are introduced, and a history density matrix is defined in terms of ensembles of history vectors. The corresponding history entropies (and history entanglement entropies for composite systems) are explicitly computed in two examples taken from quantum computation circuits.

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1 Introduction

Formulations of quantum mechanics based on histories, rather than on states at a given time, have their logical roots in the work of Feynman [1, 2] (see also the inspirational Chapter 32 of Dirac’s book [3]), and could be seen as generalizations of the path-integral approach. A list with the references more relevant for the present work is given in [4]-[20].

We have seen in [20] how to define a history operator on the Hilbert space \mathcal{H} of a physical system, in terms of which to compute probabilities of successive measurements at times t_1, \dots, t_n . In the present note we introduce a history vector, living in a tensor space $\mathcal{H} \odot \mathcal{H} \dots \odot \mathcal{H}$, where every \mathcal{H} corresponds to a particular t_i . This vector contains the same information as the history operator, but is more suited to define entanglement of histories, and compute their density matrices and corresponding von Neumann entropies.

This approach is similar in spirit to the one advocated in ref.s [15]-[19], but with substantial differences. In [15]-[19] the scalar product between history states depends on chain operators containing information on evolution and measurements. In our framework the algebraic structure does not depend on the dynamics, and *all* possible histories (not only “consistent” sets) correspond to orthonormal vectors in $\mathcal{H} \odot \mathcal{H} \dots \odot \mathcal{H}$. The dynamical information is instead encoded in the coefficients (amplitudes) multiplying the basis vectors.

The Born rules for probabilities and collapse are extended to history vectors in a straightforward way. Every history vector has a pictorial representation in terms of allowed histories, and its collapse after a measurement sequence entails the disappearance of some histories. In this sense measurement “alters the past”,

but never in a way to endanger causality. As an illustration, the formalism is applied to the entangler-disentangler and the teleportation quantum circuits.

The content of the paper is as follows. Chain operators and probabilities for multiple measurements at different times are recalled in Section 2. Section 3 introduces history amplitudes, an essential ingredient in the definition of the history vector, given in Section 4. The generalized Born rules for probabilities of outcome sequences and collapse are derived, using appropriate projectors on the history vector. In Section 5 we propose a definition for history entanglement, based on a tensor product between history states. Section 6 deals with density matrices, constructed using ensembles of history vectors. This allows the computation of history entropy, and history entanglement entropy for composite systems. Two examples based on quantum computation circuits are provided in Section 7, and we calculate their history entanglement entropy. Section 8 contains some conclusions.

2 Chain operators and probabilities

As recalled in [20], probabilities of obtaining sequences $\alpha = \alpha_1, \alpha_2, \dots, \alpha_n$ of measurement results, starting from an initial state $|\psi\rangle$, can all be expressed in terms of a chain operator $C_{\psi,\alpha}$. This operator encodes measurements at times t_1, \dots, t_n corresponding to projectors $P_{\alpha_1}, \dots, P_{\alpha_n}$, and unitary time evolution between measurements:

$$C_{\psi,\alpha} = P_{\alpha_n} U(t_n, t_{n-1}) P_{\alpha_{n-1}} U(t_{n-1}, t_{n-2}) \cdots P_{\alpha_1} U(t_1, t_0) P_\psi \quad (2.1)$$

with $t_0 < t_1 < \dots < t_{n-1} < t_n$ and $P_\psi = |\psi\rangle\langle\psi|$. The P_{α_i} are projectors on eigensubspaces of observables, satisfying orthogonality and completeness relations:

$$P_{\alpha_i} P_{\beta_i} = \delta_{\alpha_i, \beta_i} P_{\alpha_i}, \quad I = \sum_{\alpha_i} P_{\alpha_i} \quad (2.2)$$

and $U(t_{i+1}, t_i)$ is the evolution operator between times t_i and t_{i+1} .

The probability of obtaining the sequence α is given by

$$p(\psi, \alpha_1, \dots, \alpha_n) = \text{Tr}(C_{\psi,\alpha} C_{\psi,\alpha}^\dagger) \quad (2.3)$$

and could be considered the “probability of the history” $\psi, \alpha_1, \dots, \alpha_n$. We can easily prove that the sum of all these probabilities gives 1:

$$\sum_{\alpha} \text{Tr}(C_{\psi,\alpha} C_{\psi,\alpha}^\dagger) = 1 \quad (2.4)$$

by using the completeness relations in (2.2) and unitarity of the $U(t_{i+1}, t_i)$ operators. We also find

$$\sum_{\alpha_n} p(\psi, \alpha_1, \alpha_2, \dots, \alpha_n) = p(\psi, \alpha_1, \alpha_2, \dots, \alpha_{n-1}) \quad (2.5)$$

However other standard sum rules for probabilities are not satisfied in general. For example relations of the type

$$\sum_{\alpha_2} p(\psi, \alpha_1, \alpha_2, \alpha_3) = p(\psi, \alpha_1, \alpha_3) \quad (2.6)$$

hold only if the so-called *decoherence condition* is satisfied:

$$Tr(C_{\psi,\alpha} C_{\psi,\beta}^\dagger) + c.c. = 0 \quad \text{when } \alpha \neq \beta \quad (2.7)$$

as can be checked on the example (2.6) written in terms of chain operators, and easily generalized. Note that for chain operators the following is trivially true:

$$\sum_{\alpha_i} C_{\psi,\alpha_1, \dots, \alpha_n} = C_{\psi,\alpha_1, \dots, \alpha_n} \quad (2.8)$$

due to $\sum_{\alpha_i} P_{\alpha_i} = I$.

If all the histories we consider are such that the decoherence condition holds, they are said to form a *consistent set*, and can be assigned probabilities satisfying all the standard sum rules.

In general, histories do not form a consistent set: interference effects between them can be important, as in the case of the double slit experiment. For this reason we will not limit ourselves to consistent sets. Formula (2.3) for the probability of successive measurement outcomes holds true in any case.

3 Amplitudes

If $P_{\alpha_n} = |\alpha_n\rangle\langle\alpha_n|$, i.e. the eigenvalue α_n is nondegenerate, the chain operator can be written as

$$C_{\psi,\alpha} = |\alpha_n\rangle A(\psi, \alpha) \langle\psi| \quad (3.1)$$

where

$$A(\psi, \alpha) = \langle\alpha_n| U(t_n, t_{n-1}) P_{\alpha_{n-1}} U(t_{n-1}, t_{n-2}) \cdots P_{\alpha_1} U(t_1, t_0) |\psi\rangle \quad (3.2)$$

is the *amplitude* of the history ψ, α , and

$$|A(\psi, \alpha)|^2 = Tr(C_{\psi,\alpha} C_{\psi,\alpha}^\dagger) = p(\psi, \alpha) \quad (3.3)$$

This easily generalizes to the case of a g_n -degenerate eigenvalue α_n , with corresponding (orthonormal) eigenvectors $|\alpha_n, i\rangle$ ($i = 1, \dots, g_n$):

$$C_{\psi,\alpha} = \sum_i |\alpha_n, i\rangle A_i(\psi, \alpha) \langle\psi|, \quad \sum_i |A_i(\psi, \alpha)|^2 = Tr(C_{\psi,\alpha} C_{\psi,\alpha}^\dagger) = p(\psi, \alpha) \quad (3.4)$$

the amplitudes $A_i(\psi, \alpha)$ being given by formula (3.2) where $\langle\alpha_n|$ is substituted by $\langle\alpha_n, i|$.

A scalar product between chain operators can be defined as

$$(C_{\psi,\alpha}, C_{\psi,\beta}) \equiv \text{Tr}(C_{\psi,\alpha} C_{\psi,\beta}^\dagger) \quad (3.5)$$

All the properties of a (complex) scalar product hold, in particular

$$(C_{\psi,\alpha}, C_{\psi,\alpha}) = p(\psi, \alpha) = 0 \iff C_{\psi,\alpha} = 0 \quad (3.6)$$

Note : if we divide the set $\alpha_1, \dots, \alpha_{n-1}$ into two complementary sets $\alpha_{i_1}, \dots, \alpha_{i_m}$ and $\alpha_{j_1}, \dots, \alpha_{j_p}$ with $m + p = n - 1$, then

$$\sum_{\alpha_{j_1} \dots \alpha_{j_p}} A(\psi, \alpha_1, \dots, \alpha_{n-1}, \alpha_n) = A(\psi, \alpha_{i_1}, \dots, \alpha_{i_m}, \alpha_n) \quad (3.7)$$

because of the completeness relations in (2.2). This just rephrases property (2.8) for chain operators, with the difference that α_n is never summed on since it enters the amplitude (3.2) as a bra rather than as a projector.

4 History vector, probabilities and collapse

Consider a physical system in the state $|\psi\rangle$ at time t_0 and devices that can be activated at times t_1, \dots, t_n to measure given observables, with projectors on eigen-subspaces as in (2.2). Before any measurement, the system can be described by a *history vector*, living in n -tensor space

$$|\Psi\rangle = \sum_{\alpha} A(\psi, \alpha) |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle \quad (4.1)$$

where the coefficients $A(\psi, \alpha)$ are given by the amplitudes of the histories $\alpha = \alpha_1, \dots, \alpha_n$, computed as in the previous Section, and $|\alpha_k\rangle$ are a basis of orthonormal vectors at each time t_k . If no degeneracy was present, these vectors would be just the eigenvectors of the observable(s) measured at time t_k . If the α_k ($k < n$) eigenvalues are degenerate, the information on degeneracy is lost in the symbol $|\alpha_k\rangle$, but is contained in the amplitude $A(\psi, \alpha)$, where the projectors P_{α_k} on the eigensubspaces are present. In case α_n is degenerate, the sum on α in (4.1) must include the degeneracy index i , and (4.1) will be short for

$$|\Psi\rangle = \sum_{\alpha,i} A_i(\psi, \alpha) |\alpha_1\rangle \odot \dots \odot |\alpha_{n-1}\rangle \odot |\alpha_n, i\rangle \quad (4.2)$$

Note : In the following we will assume for simplicity that α_n is nondegenerate: all the results generalize easily to the degenerate case, usually by summing on the index i .

The “time product” \odot has all the properties of a tensor product. The symbol \otimes (or just a blank) will be reserved for tensor products between states of subsystems at the same time t_k . The vector is normalized since

$$\langle \Psi | \Psi \rangle = \sum_{\alpha} |A(\psi, \alpha)|^2 = 1 \quad (4.3)$$

The *history content* of the system is defined to be the set of histories $\alpha = \alpha_1, \dots, \alpha_n$ contained in $|\Psi\rangle$, i.e. all histories having nonvanishing amplitudes.

Probabilities of measuring sequences $\alpha = \alpha_1, \dots, \alpha_n$ are given by the familiar formula

$$p(\psi, \alpha) = \langle \Psi | \mathbb{P}_\alpha | \Psi \rangle = |A(\psi, \alpha)|^2. \quad (4.4)$$

with

$$\mathbb{P}_\alpha = |\alpha_1\rangle\langle\alpha_1| \odot \dots \odot |\alpha_n\rangle\langle\alpha_n| \quad (4.5)$$

Formula (4.4) holds for sequences of measurements occurring at *all* times t_1, \dots, t_n .

What is the effect of a sequence of measurements with results $\alpha_1, \dots, \alpha_n$ on the system described by $|\Psi\rangle$? We can characterize this effect as a *collapse* of the history vector, implemented mathematically by \mathbb{P}_α . This projection collapses the state $|\Psi\rangle$ into the basis vector $|\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle$ up to a phase:

$$|\Psi\rangle \longrightarrow \frac{\mathbb{P}_\alpha |\Psi\rangle}{\sqrt{\langle \Psi | \mathbb{P}_\alpha | \Psi \rangle}} = |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle \quad (4.6)$$

The basis vector describes a system that has been “completely measured” with results $\alpha_1, \dots, \alpha_n$. Another sequence of measurements of the same observables at times t_i would yield the same results $\alpha_1, \dots, \alpha_n$ with probability one, according to the rule (4.4).

A *partial* measurement at times t_{i_1}, \dots, t_{i_m} ($m < n$) yielding the sequence $\alpha_{i_1}, \dots, \alpha_{i_m}$ likewise projects the state vector $|\Psi\rangle$ into

$$|\Psi_\alpha\rangle = \frac{\mathbb{P}_\alpha |\Psi\rangle}{\sqrt{\langle \Psi | \mathbb{P}_\alpha | \Psi \rangle}} \quad (4.7)$$

where now \mathbb{P}_α is the projector on the sequence $\alpha_{i_1}, \dots, \alpha_{i_m}$, i.e. a tensor product of identity operators and projectors at times t_{i_1}, \dots, t_{i_m} :

$$\mathbb{P}_\alpha = I \odot \dots \odot |\alpha_{i_1}\rangle\langle\alpha_{i_1}| \odot I \odot \dots \odot |\alpha_{i_m}\rangle\langle\alpha_{i_m}| \odot I \odot \dots \quad (4.8)$$

Then $|\Psi_\alpha\rangle$ is given, up to a normalization, by the expression (4.1) where the sum on α involves only the times t_j different from t_{i_1}, \dots, t_{i_m} , the rest of the α 's being fixed to the values $\alpha_{i_1}, \dots, \alpha_{i_m}$.

The projected history vector $|\Psi_\alpha\rangle$ can be used to compute conditional probabilities. The probability of obtaining the results $\beta_{j_1}, \dots, \beta_{j_p}$ at times t_{j_1}, \dots, t_{j_p} , given that $\alpha_{i_1}, \dots, \alpha_{i_m}$ are obtained at times t_{i_1}, \dots, t_{i_m} (with j_1, \dots, j_p and i_1, \dots, i_m having no intersection, and union coinciding with $1, \dots, n$), is given by

$$p(\beta|\alpha) = \langle \Psi_\alpha | \mathbb{P}_\beta | \Psi_\alpha \rangle \quad (4.9)$$

Finally, to compute probabilities for sequences $\alpha_{i_1}, \dots, \alpha_{i_m}$ in partial measurements at times t_{i_1}, \dots, t_{i_m} , we need a “shorter” history vector with a reduced number

of factors in the \odot product corresponding to the subset $t_{i_1}, \dots t_{i_m}$. This vector can be obtained from $\mathbb{P}_\alpha |\Psi\rangle$ (with \mathbb{P}_α as in (4.8)) by using a further projection \mathcal{P} , defined on the basis vectors as:

$$\mathcal{P}_{i_1, \dots, i_m} |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle \equiv |\alpha_{i_1}\rangle \odot \dots \odot |\alpha_{i_m}\rangle \quad (4.10)$$

if $t_{i_1}, \dots t_{i_m}$ contains t_n , and as

$$\mathcal{P}_{i_1, \dots, i_m} |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle \equiv |\alpha_{i_1}\rangle \odot \dots \odot |\alpha_{i_m}\rangle \odot |\alpha_n\rangle \quad (4.11)$$

if $t_{i_1}, \dots t_{i_m}$ does not contain t_n . For example

$$\mathcal{P}_{1,3,5} |\alpha_1\rangle \odot |\alpha_2\rangle \odot |\alpha_3\rangle \odot |\alpha_4\rangle \odot |\alpha_5\rangle = |\alpha_1\rangle \odot |\alpha_3\rangle \odot |\alpha_5\rangle \quad (4.12)$$

$$\mathcal{P}_{1,2} |\alpha_1\rangle \odot |\alpha_2\rangle \odot |\alpha_3\rangle \odot |\alpha_4\rangle \odot |\alpha_5\rangle = |\alpha_1\rangle \odot |\alpha_2\rangle \odot |\alpha_5\rangle \quad (4.13)$$

The action of \mathcal{P} is then extended by linearity on any $|\Psi\rangle$. Applying it to the vector $\mathbb{P}_\alpha |\Psi\rangle$ yields, when $t_{i_1}, \dots t_{i_m}$ contains t_n :

$$\begin{aligned} \mathcal{P}_{i_1, \dots, i_m} \mathbb{P}_\alpha |\Psi\rangle &= \mathcal{P}_{i_1, \dots, i_m} \sum_{\alpha_{j_1}, \dots, \alpha_{j_p}} A(\psi, \alpha) |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle = \\ &= \left(\sum_{\alpha_{j_1}, \dots, \alpha_{j_p}} A(\psi, \alpha) \right) |\alpha_{i_1}\rangle \odot \dots \odot |\alpha_{i_m}\rangle = A(\psi, \alpha_{i_1}, \dots, \alpha_{i_m}) |\alpha_{i_1}\rangle \odot \dots \odot |\alpha_{i_m}\rangle \end{aligned} \quad (4.14)$$

where we have used eq. (3.7) in the second line. Then the probability $|A(\psi, \alpha_{i_1}, \dots, \alpha_{i_m})|^2$ of obtaining the partial sequence $\alpha_{i_1}, \dots, \alpha_{i_m}$ can be expressed as a scalar product

$$p(\psi, \alpha_{i_1}, \dots, \alpha_{i_m}) = |A(\psi, \alpha_{i_1}, \dots, \alpha_{i_m})|^2 = \langle \Psi | \mathbb{P}_\alpha \mathcal{P}_{i_1, \dots, i_m}^\dagger \mathcal{P}_{i_1, \dots, i_m} \mathbb{P}_\alpha | \Psi \rangle \quad (4.15)$$

where $\langle \alpha_1 | \odot \dots \odot \langle \alpha_n | \mathcal{P}_{i_1, \dots, i_m}^\dagger$ is the conjugate of (4.10) or (4.11). Note that

$$\mathbb{Q}_{i_1, \dots, i_m} \equiv \mathcal{P}_{i_1, \dots, i_m}^\dagger \mathcal{P}_{i_1, \dots, i_m} \quad (4.16)$$

is a hermitian operator in n -tensor space, with matrix elements

$$\langle \alpha_1 | \odot \dots \odot \langle \alpha_n | \mathbb{Q}_{i_1, \dots, i_m} | \beta_1 \rangle \odot \dots \odot | \beta_n \rangle = \delta_{\alpha_{i_1} \beta_{i_1}} \cdots \delta_{\alpha_{i_m} \beta_{i_m}} \quad (4.17)$$

When $t_{i_1}, \dots t_{i_m}$ does not contain t_n , α_n must be contained in $\alpha_{j_1}, \dots, \alpha_{j_p}$, and we have

$$\begin{aligned} \mathcal{P}_{i_1, \dots, i_m} \mathbb{P}_\alpha |\Psi\rangle &= \mathcal{P}_{i_1, \dots, i_m} \sum_{\alpha_{j_1}, \dots, \alpha_{j_{p-1}}, \alpha_n} A(\psi, \alpha) |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle = \\ &= \sum_{\alpha_n} \left(\sum_{\alpha_{j_1}, \dots, \alpha_{j_{p-1}}} A(\psi, \alpha) \right) |\alpha_{i_1}\rangle \odot \dots \odot |\alpha_{i_m}\rangle \odot |\alpha_n\rangle = \\ &= \sum_{\alpha_n} A(\psi, \alpha_{i_1}, \dots, \alpha_{i_m}, \alpha_n) |\alpha_{i_1}\rangle \odot \dots \odot |\alpha_{i_m}\rangle \odot |\alpha_n\rangle \end{aligned} \quad (4.18)$$

The sequence probability $|A(\psi, \alpha_{i_1}, \dots \alpha_{i_m})|^2$ is given by the same scalar product:

$$\langle \Psi | \mathbb{P}_\alpha \mathbb{Q}_{i_1, \dots, i_m} \mathbb{P}_\alpha | \Psi \rangle = \sum_{\alpha_n} |A(\psi, \alpha_{i_1}, \dots \alpha_{i_m}, \alpha_n)|^2 = |A(\psi, \alpha_{i_1}, \dots \alpha_{i_m})|^2 \quad (4.19)$$

in virtue of relation (2.5). Therefore we have established the formula

$$p(\psi, \alpha_{i_1}, \dots \alpha_{i_m}) = \langle \Psi | \mathbb{P}_\alpha \mathbb{Q}_{i_1, \dots, i_m} \mathbb{P}_\alpha | \Psi \rangle \quad (4.20)$$

for any partial sequence $\alpha_{i_1}, \dots \alpha_{i_m}$.

Note: when $m = 0$ (and therefore α_n is contained in $\alpha_{j_1}, \dots \alpha_{j_p}$), \mathbb{P}_α = identity in tensor space and \mathcal{P} projects on t_n . The projected vector in (4.18) becomes $\sum_{\alpha_n} A(\psi, \alpha_n) |\alpha_n\rangle$ and is just the (usual) state vector $|\psi(t_n)\rangle$ of the system at time t_n , since

$$|\psi(t_n)\rangle = U(t_n, t_0) |\psi\rangle = \sum_{\alpha_n} |\alpha_n\rangle \langle \alpha_n| U(t_{i_1}, t_0) |\psi\rangle = \sum_{\alpha_n} A(\psi, \alpha_n) |\alpha_n\rangle \quad (4.21)$$

In conclusion, *probabilities for (sequences of) measurements at any times can be computed via scalar products involving appropriate projections of the history vector $|\Psi\rangle$* .

5 History entanglement

It is useful to define a tensor product between history vectors of subsystems. On the basis history vectors the product acts as

$$(|\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle)(|\beta_1\rangle \odot \dots \odot |\beta_n\rangle) \equiv |\alpha_1\rangle |\beta_1\rangle \odot \dots \odot |\alpha_n\rangle |\beta_n\rangle \quad (5.1)$$

and is extended by bilinearity on all linear combinations of these vectors. No symbol is used for this tensor product, to distinguish it from the tensor product \odot involving different times t_k .

This allows a definition of product history states, which are defined to be expressible in the form:

$$(\sum_{\alpha} A(\psi, \alpha) |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle)(\sum_{\beta} A(\psi, \beta) |\beta_1\rangle \odot \dots \odot |\beta_n\rangle) \quad (5.2)$$

or, using bilinearity:

$$\sum_{\alpha, \beta} A(\psi, \alpha) A(\psi, \beta) |\alpha_1 \beta_1\rangle \odot \dots \odot |\alpha_n \beta_n\rangle \quad (5.3)$$

with $|\alpha_i \beta_i\rangle \equiv |\alpha_i\rangle |\beta_i\rangle$ for short. A product history state is thus characterized by factorized amplitudes $A(\psi, \alpha, \beta) = A(\psi, \alpha) A(\psi, \beta)$.

If the history state cannot be expressed as a product, we define it to be *history entangled*¹. In this case, results of measurements on system A are correlated with those on system B and viceversa. Indeed if the amplitudes $A(\psi, \alpha, \beta)$ in the history state

$$|\Psi^{AB}\rangle = \sum_{\alpha, \beta} A(\psi, \alpha, \beta) |\alpha_1 \beta_1\rangle \odot \dots \odot |\alpha_n \beta_n\rangle \quad (5.4)$$

are not factorized, the probability for Alice to obtain the sequence α if Bob obtains the sequence β depends on β , and viceversa, this probability being proportional to $|A(\psi, \alpha, \beta)|^2$. On the other hand, if the history state is a product (5.2), the probability for Alice is $|A(\psi, \alpha)|^2$ and does not depend on β (and likewise for Bob).

We have the following criterion for history entanglement: starting from an initial state $|\psi\rangle$ at t_0 , we examine all intermediate states of the system at times t_i , given by repeated application of the evolution operators $U(t_i, t_{i-1})$. If at least one of these intermediate states is an entangled state, then the history state of the system is entangled. This is because an entangled state at time t_i implies a correlation between measurements at time t_i , which would be impossible if the history amplitudes for Alice and Bob measurements were factorized. Note that an entangled initial state $|\psi\rangle$ does not necessarily imply history entanglement, since $U(t_1, t_0)$ could disentangle it.

The history vector (5.4) describes a bipartite system where the observables being measured at times t_i are local observables of the form $A_i \otimes I, I \otimes B_i$, with eigenvalues α_i and β_i respectively. This is not the most general history state of a bipartite system: the observables can be chosen to be global operators C_i acting on the whole AB, with eigenvalues γ_i . Then the history state reads:

$$\Psi^{AB} = \sum_{\gamma} A(\psi, \gamma) |\gamma_1\rangle \odot \dots \odot |\gamma_n\rangle \quad (5.5)$$

In this case we cannot extract from $|\Psi^{AB}\rangle$ individual histories for the subsystems A and B.

Finally, the correlations in an entangled history system can be distinguished from the “classical” correlations due to a statistical ensemble of history states, as discussed in next Section.

6 Density matrix and history entropy

A system in the pure history state $|\Psi\rangle$ has the density matrix:

$$\rho = |\Psi\rangle\langle\Psi| \quad (6.1)$$

¹This entanglement is quite different from the one considered in ref.s [15]-[18], where it involves superpositions of history states (without need of a composite system), and should be considered as a *temporal* entanglement.

a positive operator satisfying $Tr(\rho) = 1$ (due to $\langle \Psi | \Psi \rangle = 1$). A mixed history state has density matrix

$$\rho = \sum_i p_i |\Psi_i\rangle\langle\Psi_i| \quad (6.2)$$

with $\sum_i p_i = 1$, and $\{|\Psi_i\rangle\}$ an ensemble of history states.

Probabilities of measuring sequences $\alpha = \alpha_1, \dots, \alpha_n$ in history state ρ are given by the standard formula:

$$p(\alpha_1, \dots, \alpha_n) = Tr(\rho \mathbb{P}_\alpha) \quad (6.3)$$

(cf. equation (4.4) for pure states).

A (partial) measurement as the one considered in eq. (4.7) projects the density matrix in the usual way:

$$\rho \longrightarrow \rho_\alpha = |\Psi_\alpha\rangle\langle\Psi_\alpha| = \frac{\mathbb{P}_\alpha \rho \mathbb{P}_\alpha}{Tr(\rho \mathbb{P}_\alpha)} \quad (6.4)$$

and the probability of obtaining the partial sequence $\alpha_{i_1}, \dots, \alpha_{i_m}$ is given by

$$p(\alpha_{i_1}, \dots, \alpha_{i_m}) = Tr(\rho \mathbb{P}_\alpha \mathbb{Q}_{i_1, \dots, i_m} \mathbb{P}_\alpha) \quad (6.5)$$

cf. formula (4.20).

If a measurement is performed on $|\Psi\rangle = \sum_\alpha A(\psi, \alpha)|\alpha\rangle$, but the result remains unknown, the density matrix becomes

$$\rho \longrightarrow \rho' = \sum_\alpha |A(\psi, \alpha)|^2 |\Psi_\alpha\rangle\langle\Psi_\alpha| \quad (6.6)$$

and describes a *mixed* history state.

Consider now the following two history states:

1) the pure history state:

$$|\Psi\rangle = \sum_\alpha A(\psi, \alpha)|\alpha\rangle \quad (6.7)$$

where $|\alpha\rangle \equiv |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle$. Its density matrix is

$$\rho_{pure} = |\Psi\rangle\langle\Psi| = \sum_{\alpha, \alpha'} A(\psi, \alpha)A(\psi, \alpha')^* |\alpha\rangle\langle\alpha'| \quad (6.8)$$

2) the mixed history state

$$\rho_{mixed} = \sum_\alpha |A(\psi, \alpha)|^2 |\alpha\rangle\langle\alpha| \quad (6.9)$$

The probabilities of obtaining a sequence α are the same for the two states, so they cannot be distinguished by a sequence of measurements at times t_1, \dots, t_n . Recall the similar situation for ordinary state vectors, where for example the mixed state

$\rho_{mixed} = \frac{1}{2}|0\rangle\langle 0| + \frac{1}{2}|1\rangle\langle 1|$ can be distinguished from the pure state $\rho_{pure} = \frac{1}{2}(|0\rangle + |1\rangle)(\langle 0| + \langle 1|)$ by measurements in a basis different from the computational one. For history states however we must stick to the given set of observables at each time t_i , which defines the history vector. Indeed the measuring devices are part of the history description of the quantum system. One can change description by changing the measuring apparati, but then one must compute the new amplitudes for the new histories. There is no straightforward operation on the old history state that relates it to the new one².

But then, how can we distinguish between the two history states (6.8) and (6.9) ? There is a way, by using *partial* measurements. Indeed the probability of obtaining a given partial sequence $\alpha_{i_1}, \dots, \alpha_{i_m}$, given by formula (4.20), takes different values for the states (6.8) and (6.9). In the pure state this probability reads:

$$p(\alpha_{i_1}, \dots, \alpha_{i_m}) = Tr(\rho_{pure} \mathbb{P}_\alpha \mathbb{Q}_{i_1, \dots, i_m} \mathbb{P}_\alpha) = |A(\psi, \alpha_{i_1}, \dots, \alpha_{i_m})|^2 = \left| \sum_{\alpha_{j_1}, \dots, \alpha_{j_p}} A(\psi, \alpha) \right|^2 \quad (6.10)$$

whereas for the mixed state:

$$p(\alpha_{i_1}, \dots, \alpha_{i_m}) = Tr(\rho_{mixed} \mathbb{P}_\alpha \mathbb{Q}_{i_1, \dots, i_m} \mathbb{P}_\alpha) = \sum_{\alpha_{j_1}, \dots, \alpha_{j_p}} |A(\psi, \alpha)|^2 \quad (6.11)$$

with $\alpha_{j_1}, \dots, \alpha_{j_p}$ complementary to $\alpha_{i_1}, \dots, \alpha_{i_m}$. Thus the difference is due to sum of square moduli being different from square modulus of sum, and we can experimentally distinguish between ρ_{pure} and ρ_{mixed} .

Consider now a system AB composed by two subsystems A and B, and devices measuring observables $\mathbb{A}_i = A_i \otimes I$ and $\mathbb{B}_i = I \otimes B_i$ at each t_i . Its history state is

$$|\Psi^{AB}\rangle = \sum_{\alpha, \beta} A(\psi, \alpha, \beta) |\alpha_1 \beta_1\rangle \odot \dots \odot |\alpha_n \beta_n\rangle \quad (6.12)$$

where α_i, β_i are the possible outcomes of a joint measurement at time t_i of A and B. The amplitudes $A(\psi, \alpha, \beta)$ are computed using the general formula (3.2), with projectors

$$\mathbb{P}_{\alpha_i, \beta_i} = |\alpha_i, \beta_i\rangle \langle \alpha_i, \beta_i| = |\alpha_i\rangle \langle \alpha_i| \otimes |\beta_i\rangle \langle \beta_i| \quad (6.13)$$

corresponding to the eigenvalues α_i, β_i . The density matrix of AB is

$$\begin{aligned} \rho^{AB} &= |\Psi^{AB}\rangle \langle \Psi^{AB}| = \\ &= \sum_{\alpha, \beta, \alpha', \beta'} A(\psi, \alpha, \beta) A(\psi, \alpha', \beta')^* |\alpha_1 \beta_1\rangle \odot \dots \odot |\alpha_n \beta_n\rangle \langle \alpha_1 \beta_1| \odot \dots \odot \langle \alpha_n \beta_n| \end{aligned} \quad (6.14)$$

²Trying to express $|\alpha_i\rangle$ in terms of eigenvectors of other observables in (4.1) leads to wrong history amplitudes, as one can easily verify in the case of a qubit with evolution $t_0 \rightarrow t_1 \rightarrow t_2$.

Applying here the discussion of the preceding paragraph, we see that if (6.12) describes an entangled state, the correlations between Alice α and Bob β sequences can be distinguished from correlations due to a statistical ensemble.

We can define *reduced density matrices* by partially tracing on the subsystems:

$$\rho^A \equiv Tr_B(\rho^{AB}), \quad \rho^B \equiv Tr_A(\rho^{AB}) \quad (6.15)$$

In general ρ^A and ρ^B will not describe pure history states anymore.

This definition makes sense only if the reduced density matrices can be used to compute statistics for measurements on the subsystems. Note that the history vector describes joint measurements on A and B, and therefore the probability for Alice to obtain a particular sequence $\alpha_1, \dots, \alpha_n$ in measuring A on her subsystem must be computed taking into account that also B gets measured (the result being unknown to Alice). This probability is therefore given by the sum

$$p(\alpha) = \sum_{\beta} p(\alpha, \beta) = \sum_{\beta} |A(\psi, \alpha, \beta)|^2 \quad (6.16)$$

Let us check that we obtain the same answer using the reduced density operator for Alice. Taking the partial trace on B of (6.14) yields:

$$\rho^A = \sum_{\alpha, \alpha', \beta} A(\psi, \alpha, \beta) A^*(\psi, \alpha', \beta) |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle \langle \alpha'_1| \odot \dots \odot \langle \alpha'_n|, \quad (6.17)$$

a positive operator with unit trace. The standard expression in terms of ρ^A for Alice's probability to obtain the sequence α is

$$p(\alpha) = Tr(\rho^A \mathbb{P}_{\alpha}) \quad (6.18)$$

with

$$\mathbb{P}_{\alpha} = (P_{\alpha_1} \otimes I) \odot \dots \odot (P_{\alpha_n} \otimes I), \quad P_{\alpha_i} = |\alpha_i\rangle \langle \alpha_i| \quad (6.19)$$

It is immediate to verify that indeed the probability as computed in (6.18) coincides with (6.16), and therefore the definition (6.15) gives the correct density matrices for the subsystems.

On the other hand, the probability for Alice to obtain the sequence $\alpha_1, \dots, \alpha_n$ with no measurements on Bob's part is different from (6.16). Indeed, the history vector of the composite system is different, since only Alice's measuring device is activated, and reads

$$|\Psi^{AB}\rangle = \sum_{\alpha} A(\psi, \alpha) |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle \quad (6.20)$$

where the amplitudes $A(\psi, \alpha)$ are obtained from the general formula (3.2) using the projectors P_{α_i} of (6.19). Here the reduced density operator ρ^A is simply

$$\rho^A = \sum_{\alpha, \alpha'} A(\psi, \alpha) A(\psi, \alpha')^* |\alpha_1\rangle \odot \dots \odot |\alpha_n\rangle \langle \alpha_1| \odot \dots \odot \langle \alpha_n| \quad (6.21)$$

(the trace on B has no effect, since history vectors contain only results of Alice), and the probability of Alice finding the sequence α is

$$p(\alpha) = \text{Tr}(\rho^A \mathbb{P}_\alpha) = |A(\psi, \alpha)|^2 \quad (6.22)$$

differing in general from (6.16).

Note: the amplitudes in (6.20) can also be computed as $A(\psi, \alpha) = \sum_\beta A(\psi, \alpha, \beta)$ due to $\sum_{\beta_i} |\beta_i\rangle\langle\beta_i| = I \rightarrow \sum_{\beta_i} \mathbb{P}_{\alpha_i, \beta_i} = P_{\alpha_i} \otimes I$. Thus the difference of the two situations described above is due to

$$\sum_\beta |A(\psi, \alpha, \beta)|^2 \neq |A(\psi, \alpha)|^2 \quad (6.23)$$

in general. In particular cases the equality sign holds, for example when the evolution operator is factorized $U = U^A \otimes U^B$, i.e. when A and B do not interact.

Finally, we can define the system *history* (von Neumann) entropy as

$$S(\rho^{AB}) = -\rho^{AB} \log \rho^{AB} \quad (6.24)$$

and, when ρ^{AB} is a pure history state, the *history entanglement entropies* for subsystems A and B:

$$S(\rho^A) = -\rho^A \log \rho^A, \quad S(\rho^B) = -\rho^B \log \rho^B \quad (6.25)$$

All known properties of von Neumann entropy hold, since they depend on ρ^{AB} being a positive operator with unit trace, and ρ^A, ρ^B reduced density operators obtained by partial tracing. Some of these properties will be verified in the examples of next Section.

7 Examples

In this Section we examine two examples of quantum systems evolving from a given initial state, and subjected to successive measurements. They are taken from simple quantum computation circuits³ where unitary gates determine the evolution between measurements. Only two gates are used: the Hadamard one-qubit gate H defined by:

$$H|0\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle), \quad H|1\rangle = \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle) \quad (7.1)$$

and the two-qubit *CNOT* gate:

$$\text{CNOT}|00\rangle = |00\rangle, \quad \text{CNOT}|01\rangle = |01\rangle, \quad \text{CNOT}|10\rangle = |11\rangle, \quad \text{CNOT}|11\rangle = |10\rangle \quad (7.2)$$

Quantum computing circuits in the consistent history formalism have been discussed for example in ref.s [5, 22].

³A review on quantum computation can be found for ex. in [21].

7.1 Entangler-disentangler

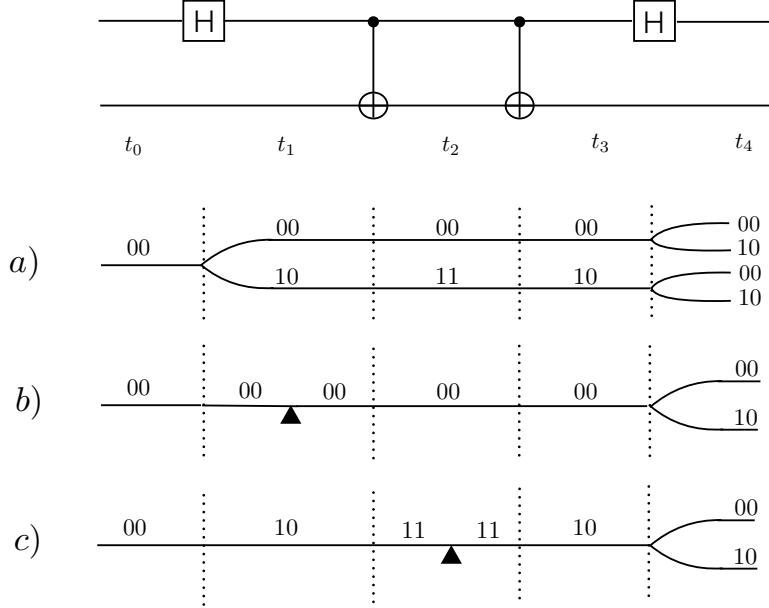


Fig. 1 The entangler - disentangler circuit, and some history diagrams for initial state $|00\rangle$: a) no measurements, or Bob measures 0 at t_1 ; b) Alice measures 0 at t_1 ; c) Alice measures 1 at t_2 . Black triangles indicate measurements.

If the initial state (at t_0) is $|00\rangle$, the history state of the system before any measurements (at times t_1, \dots, t_4) is given by

$$|\Psi\rangle = \frac{1}{2}(|00\rangle \odot |00\rangle \odot |00\rangle \odot |00\rangle + |00\rangle \odot |00\rangle \odot |00\rangle \odot |10\rangle + |10\rangle \odot |11\rangle \odot |10\rangle \odot |00\rangle - |10\rangle \odot |11\rangle \odot |10\rangle \odot |10\rangle) \quad (7.3)$$

the amplitudes being given by formula (3.2), i.e.

$$\begin{aligned} A(00, 00, 00, 00, 00) &= \langle 00|(H \otimes I)|00\rangle\langle 00|CNOT|00\rangle\langle 00|CNOT|00\rangle\langle 00|(H \otimes I)|00\rangle = +\frac{1}{2} \\ A(00, 00, 00, 00, 10) &= \langle 10|(H \otimes I)|00\rangle\langle 00|CNOT|00\rangle\langle 00|CNOT|00\rangle\langle 00|(H \otimes I)|00\rangle = +\frac{1}{2} \\ A(00, 10, 11, 10, 00) &= \langle 00|(H \otimes I)|10\rangle\langle 10|CNOT|11\rangle\langle 11|CNOT|10\rangle\langle 10|(H \otimes I)|00\rangle = +\frac{1}{2} \\ A(00, 10, 11, 10, 10) &= \langle 10|(H \otimes I)|10\rangle\langle 10|CNOT|11\rangle\langle 11|CNOT|10\rangle\langle 10|(H \otimes I)|00\rangle = -\frac{1}{2} \end{aligned} \quad (7.4)$$

These amplitudes (or equivalently the history vector $|\Psi\rangle$) encode all the necessary information to compute probabilities, according to the rules of Section 4. For example the probability of measuring any of those four sequences is $1/4$, whereas the

probability of measuring 10 at t_4 without measurements at t_1, t_2, t_3 is zero (the two histories with 10 at t_4 have opposite amplitudes and therefore interfere).

The history content of the system before measurements is displayed in diagram a) of Fig. 1. Measurements by Alice project the state $|\Psi\rangle$ and reduce its history content as shown in diagrams b) and c).

The unmeasured state $|\Psi\rangle$ is history entangled, whereas the projected $|\Psi_\alpha\rangle$ after Alice measurements in diagrams b) and c) is a product history state.

The reduced density operator for Alice before measurements is

$$\begin{aligned} \rho^A \equiv Tr_B(\rho^{AB}) = Tr_B|\Psi\rangle\langle\Psi| = \\ \frac{1}{4}|0\rangle\odot|0\rangle\odot|0\rangle\odot|0\rangle\langle 0|\odot\langle 0|\odot\langle 0|\odot\langle 0| + \frac{1}{4}|0\rangle\odot|0\rangle\odot|0\rangle\odot|1\rangle\langle 0|\odot\langle 0|\odot\langle 0|\odot\langle 1| \\ + \frac{1}{4}|1\rangle\odot|1\rangle\odot|1\rangle\odot|0\rangle\langle 1|\odot\langle 1|\odot\langle 1|\odot\langle 0| + \frac{1}{4}|1\rangle\odot|1\rangle\odot|1\rangle\odot|1\rangle\langle 1|\odot\langle 1|\odot\langle 1|\odot\langle 1| \\ + \frac{1}{4}|0\rangle\odot|0\rangle\odot|0\rangle\odot|0\rangle\langle 0|\odot\langle 0|\odot\langle 0|\odot\langle 1| + \frac{1}{4}|0\rangle\odot|0\rangle\odot|0\rangle\odot|1\rangle\langle 0|\odot\langle 0|\odot\langle 0|\odot\langle 0| \\ - \frac{1}{4}|1\rangle\odot|1\rangle\odot|1\rangle\odot|0\rangle\langle 1|\odot\langle 1|\odot\langle 1|\odot\langle 1| - \frac{1}{4}|1\rangle\odot|1\rangle\odot|1\rangle\odot|1\rangle\langle 1|\odot\langle 1|\odot\langle 1|\odot\langle 0| \end{aligned} \quad (7.5)$$

or, in simplified notations:

$$\rho^A = \frac{1}{2} \frac{|0000\rangle + |0001\rangle}{\sqrt{2}} \frac{\langle 0000| + \langle 0001|}{\sqrt{2}} + \frac{1}{2} \frac{|1111\rangle - |1110\rangle}{\sqrt{2}} \frac{\langle 1111| - \langle 1110|}{\sqrt{2}} \quad (7.6)$$

where $|0000\rangle \equiv |0\rangle\odot|0\rangle\odot|0\rangle\odot|0\rangle$ etc. This density operator describes a mixed history state, with an ensemble of two history vectors

$$|000+\rangle = \frac{|0000\rangle + |0001\rangle}{\sqrt{2}}, \quad |111-\rangle \equiv \frac{|1111\rangle - |1110\rangle}{\sqrt{2}} \quad (7.7)$$

with equal probabilities = 1/2. The reduced density matrix can be used to compute statistics for Alice measurements. The AB system entropy is zero, since it is in a pure state, but the entropy corresponding to ρ^A (the entropy “seen” by Alice) is

$$S(\rho^A) = -Tr(\rho^A \log \rho^A) = -2\left(\frac{1}{2} \log \frac{1}{2}\right) = 1 \quad (7.8)$$

since ρ^A has two nonzero eigenvalues equal to $\frac{1}{2}$. This is consistent with ρ^A describing a mixed history state.

The reduced density operator for Bob is easily computed:

$$\rho^B = Tr_A(\rho^{AB}) = \frac{1}{2}|0000\rangle\langle 0000| + \frac{1}{2}|0100\rangle\langle 0100| \quad (7.9)$$

describing a statistical ensemble of the two histories $|0000\rangle$ and $|0100\rangle$ with equal probabilities = 1/2, and history entropy $S(\rho^B) = S(\rho^A) = 1$.

Note that without measurements the circuit is simply the identity circuit for two qubits, so the initial state 00 can only propagate to 00 at time t_4 . The situation is different when intermediate measurements are performed, as depicted in diagrams b) and c). In these cases also the state 10 at time t_4 becomes available.

7.2 Teleportation

The teleportation circuit [23] is the three-qubit circuit given in Fig. 3, where the upper two qubits belong to Alice, and the lower one to Bob.

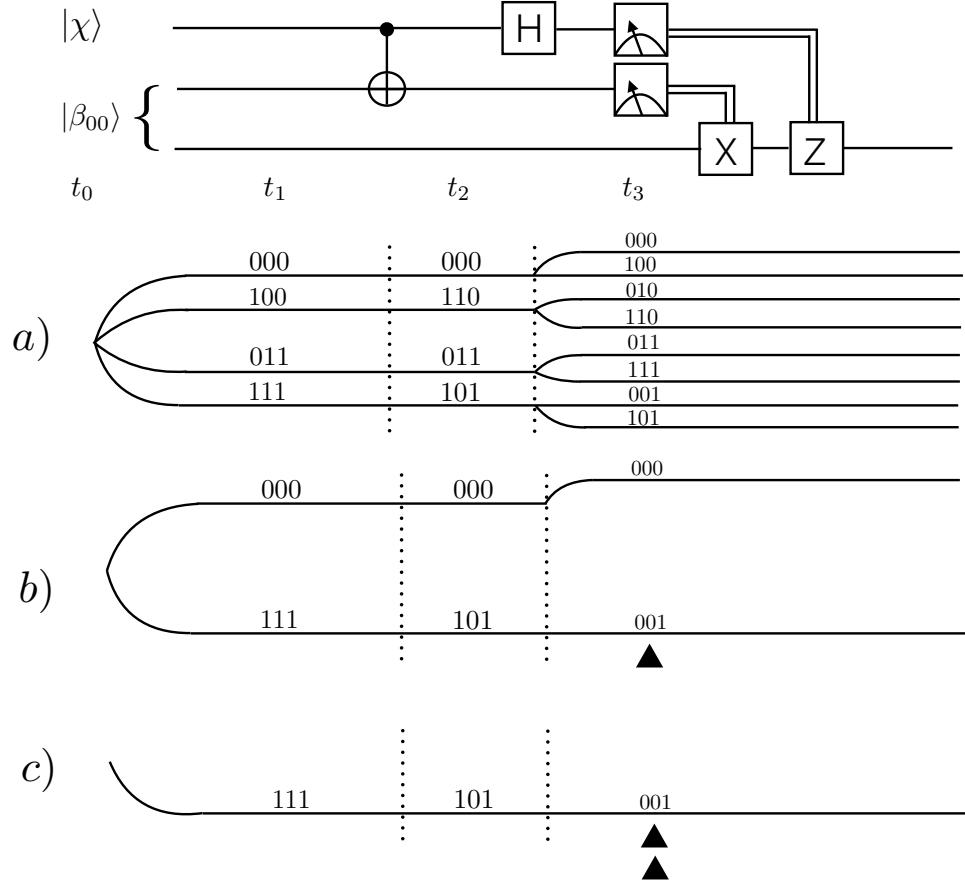


Fig. 2 Teleportation circuit: a) no measurements; b) Alice measures 00 at time t_3 ; c) at time t_3 Alice measures 00 and Bob measures 1.

The initial state is a three-qubit state, tensor product of the single qubit $|\chi\rangle = \alpha|0\rangle + \beta|1\rangle$ to be teleported and the 2-qubit entangled Bell state $|\beta_{00}\rangle = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)$. Before any measurement, the history vector contains 8 histories:

$$\begin{aligned}
 |\Psi\rangle = & \frac{1}{2}(\alpha|000\rangle \odot |000\rangle \odot |000\rangle - \alpha|000\rangle \odot |000\rangle \odot |100\rangle + \\
 & + \beta|100\rangle \odot |110\rangle \odot |010\rangle - \beta|100\rangle \odot |110\rangle \odot |110\rangle \\
 & + \alpha|011\rangle \odot |011\rangle \odot |011\rangle - \alpha|011\rangle \odot |011\rangle \odot |111\rangle \\
 & + \beta|111\rangle \odot |101\rangle \odot |001\rangle - \beta|111\rangle \odot |101\rangle \odot |101\rangle
 \end{aligned} \tag{7.10}$$

the amplitudes being given by

$$A(\chi \otimes \beta_{00}, \alpha_1, \alpha_2, \alpha_3) = \langle \alpha_3 | H_1 P_{\alpha_2} \text{CNOT}_{1,2} P_{\alpha_1} | \chi \otimes \beta_{00} \rangle \tag{7.11}$$

For example

$$A(\chi \otimes \beta_{00}, 000, 000, 000) = \langle 000 | H_1 | 000 \rangle \langle 000 | \text{CNOT}_{1,2} | 000 \rangle \langle 000 | \chi \otimes \beta_{00} \rangle = \alpha/2 \quad (7.12)$$

where $H_1 \equiv H \otimes I \otimes I$ and $\text{CNOT}_{1,2} \equiv \text{CNOT} \otimes I$. For the moment we do not take into account the X and Z gates, activated by the results of Alice measurements at t_3 . The history vector has the representation given in Fig. 2a.

Suppose now that Alice measures her two qubits at time t_3 , without any prior measurement. To compute probabilities we need first to compute $\mathbb{P}_{\alpha_3}|\Psi\rangle$ where α_3 can take the four values 00, 01, 10, 11. For example, if $\alpha_3 = 00$, then $\mathbb{P}_{\alpha_3} = I \odot I \odot (P_{00} \otimes I)$, and

$$\mathbb{P}_{\alpha_3=00}|\Psi\rangle = \frac{\alpha}{2}|000\rangle \odot |000\rangle \odot |000\rangle + \frac{\beta}{2}|111\rangle \odot |101\rangle \odot |001\rangle \quad (7.13)$$

Projecting on t_3 yields

$$\mathcal{P}_3 \mathbb{P}_{\alpha_3=00}|\Psi\rangle = \frac{\alpha}{2}|000\rangle + \frac{\beta}{2}|001\rangle \quad (7.14)$$

so that

$$p(\psi, \alpha_3 = 00) = \langle \Psi | \mathbb{P}_{\alpha_3=00} \mathcal{P}_3^\dagger \mathcal{P}_3 \mathbb{P}_{\alpha_3=00} |\Psi\rangle = \frac{1}{4}(|\alpha|^2 + |\beta|^2) = \frac{1}{4} \quad (7.15)$$

The other three outcomes for α_3 have the same probability = 1/4.

Once Alice has obtained 00 at t_3 , corresponding to the projector $P_{\alpha_3} = P_{00} \otimes I$, the history vector collapses into

$$|\Psi_\alpha\rangle = \frac{I \odot I \odot (P_{00} \otimes I)|\Psi\rangle}{\sqrt{\langle \Psi | I \odot I \odot (P_{00} \otimes I) |\Psi\rangle}} = \alpha|000\rangle \odot |000\rangle \odot |000\rangle + \beta|111\rangle \odot |101\rangle \odot |001\rangle \quad (7.16)$$

and corresponds to the diagram b) in Fig. 2. With this vector we can compute the conditional probabilities that Bob measures 0 or 1 at t_3 , given that Alice has measured 00:

$$\begin{aligned} p(0_B|00_A) &= \langle \Psi_\alpha | I \odot I \odot I \otimes P_0 | \Psi_\alpha \rangle = |\alpha|^2 \\ p(1_B|00_A) &= \langle \Psi_\alpha | I \odot I \odot I \otimes P_1 | \Psi_\alpha \rangle = |\beta|^2 \end{aligned} \quad (7.17)$$

To find the (usual) state vector of the system at time t_3 we project $|\Psi_\alpha\rangle$ on t_3 with the use of the \mathcal{P}_3 projector:

$$|\Psi'\rangle = \mathcal{P}_3 |\Psi_\alpha\rangle = \alpha|000\rangle + \beta|001\rangle = |00\rangle(\alpha|0\rangle + \beta|1\rangle) \quad (7.18)$$

and we see that Bob's qubit is in the correctly teleported state $|\chi\rangle = \alpha|0\rangle + \beta|1\rangle$.

Similar arguments hold if Alice obtains 01 or 10 or 11. In these cases Bob's qubit at time t_3 is found to be in states that can be transformed into $|\chi\rangle$ using X and Z gates, represented by the Pauli matrices σ_x and σ_z on the $(|0\rangle, |1\rangle)$ basis.

Finally, if at time t_3 Alice measures 00 and Bob measures 1, the history vector $|\Psi\rangle$ collapses into

$$|\Psi_\alpha\rangle = \frac{I \odot I \odot (P_{00} \otimes P_1)|\Psi\rangle}{\sqrt{\langle\Psi|I \odot I \odot (P_{00} \otimes P_1)|\Psi\rangle}} = |111\rangle \odot |101\rangle \odot |001\rangle. \quad (7.19)$$

and corresponds to the diagram c) in Fig. 2.

The unmeasured history vector $|\Psi\rangle$ in (7.10) is entangled. The history vector $|\Psi_\alpha\rangle$ in (7.16) after Alice measures 00 is likewise entangled, even if the (usual) state of the system at t_3 is a product state. Only the history state (7.19) is a product history state ($|11\rangle \odot |10\rangle \odot |00\rangle$) \otimes ($|1\rangle \odot |1\rangle \odot |1\rangle$).

Density matrix and entropy

The von Neumann entropy for the system before measurements is zero, since the system is in a pure history state. The reduced history density matrix for Bob, before any measurement, is given in terms of the history vector $|\Psi\rangle$ in (7.10):

$$\rho^B = Tr_A(|\Psi\rangle\langle\Psi|) = \frac{1}{2}(|0\rangle \odot |0\rangle \odot |0\rangle\langle 0| \odot \langle 0| \odot \langle 0| + |1\rangle \odot |1\rangle \odot |1\rangle\langle 1| \odot \langle 1| \odot \langle 1|) \quad (7.20)$$

and does not depend on α and β . It describes a mixed history state, with corresponding von Neumann entropy $S(\rho^B) = \log 2 = 1$.

If Alice measures her two qubits, without communicating her result, the density matrix of the system becomes

$$\rho^{AB} = \sum_{\gamma} |A(\psi, \gamma)|^2 |\gamma\rangle\langle\gamma| \quad (7.21)$$

(the sum on γ is over the 8 histories contained in the history vector $|\Psi\rangle$) yielding a matrix with 4 eigenvalues equal to $|\alpha|^2/4$ and 4 eigenvalues equal to $|\beta|^2/4$. Then the von Neumann entropy is

$$S(\rho^{AB}) = -|\alpha|^2 \log \frac{|\alpha|^2}{4} - |\beta|^2 \log \frac{|\beta|^2}{4} = -|\alpha|^2 \log |\alpha|^2 - |\beta|^2 \log |\beta|^2 + 2 \quad (7.22)$$

Setting $p = |\alpha|^2$, the entropy $S(p) = 2 - p \log p - (1-p) \log(1-p)$ is maximum and equal to $\log 2 + 2 = 3$ when $p = 1/2$, and is minimum and equal to 2 when $p = 0, 1$.

The reduced density matrix for Bob computed from (7.21) coincides with the one before measurements by Alice given in (7.20), as expected, since Alice's act of measuring cannot be detected by Bob (only the two qubits of Alice are interacting). The corresponding von Neumann entropy is therefore the same: $S(\rho^B) = -\log(1/2) = 1$.

8 Conclusions

History amplitudes, or equivalently chain operators, contain all the information necessary to compute probabilities of outcome sequences when measuring a given physical system. In the paper [20] we proposed a pictorial way to represent the history content (i.e. the set of all histories with nonvanishing amplitudes) encoded in a history operator, acting on the Hilbert space \mathcal{H} of physical states. In the present paper amplitudes are used to construct a history vector, living in a tensor product of multiple \mathcal{H} copies, in terms of which all probabilities can be expressed via projections and scalar products.

The formalism proposed here has two advantages with respect to the usual state vector description of a physical system:

- 1) it provides a convenient way to keep track of all possible histories of the system, and of their reduction due to measurements. This can be translated into graphs that facilitate intuition on how the system behaves under unitary time evolution and measurements at different times.
- 2) it allows the definition of history entanglement, history entropy, and history entanglement entropy for composite systems.

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