

Chapter 11: Introduction to Indexing and Hashing

Indexing: Basic Concepts

- Indexing mechanisms used to speed up access to desired data.
 - E.g., author catalog in library
- **Search Key** - attribute to set of attributes used to look up records in a file.
- An **index file** consists of records (called **index entries**) of the form

search-key	pointer
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- Index files are typically much smaller than the original file
- Two basic kinds of indices:
 - Ordered indices: search keys are stored in sorted order
 - Hash indices: search keys are distributed uniformly across “buckets” using a “hash function”.

Index Evaluation Metrics

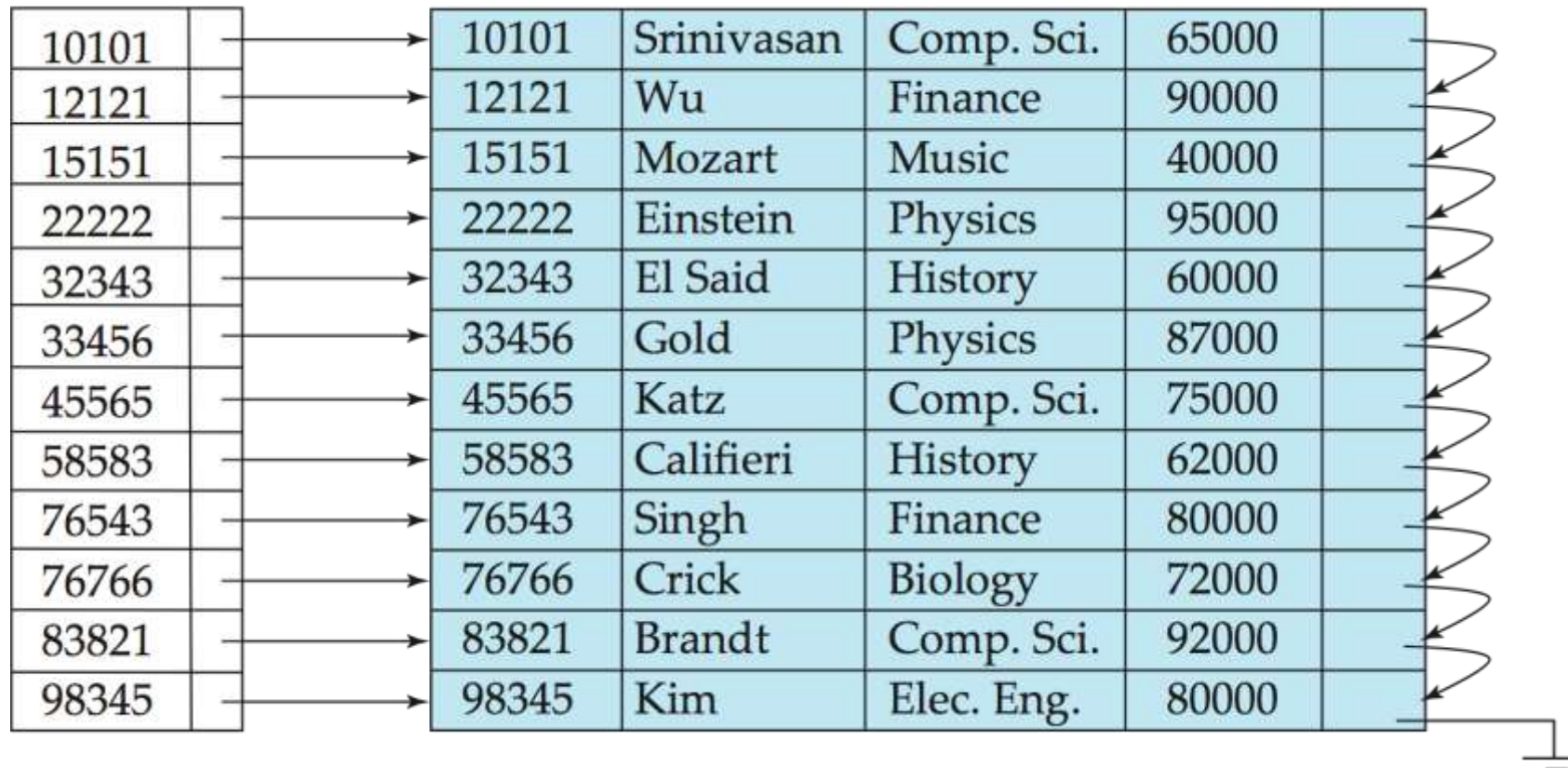
- Access types supported efficiently. E.g.,
 - records with a specified value in the attribute
 - or records with an attribute value falling in a specified range of values.
- Access time
- Insertion time
- Deletion time
- Space overhead

Ordered Indices

- In an **ordered index**, index entries are stored sorted on the search key value.
 - E.g., author catalog in library.
- **Clustering index**: in a sequentially ordered file, the index whose search key specifies the sequential order of the file.
 - Also called **Primary index**.
 - The search key of a primary index is usually but not necessarily the primary key.
- **Secondary index**: an index whose search key specifies an order different from the sequential order of the file. Also called **non-clustering index**.
- **Index-sequential file**: ordered sequential file with a primary index.

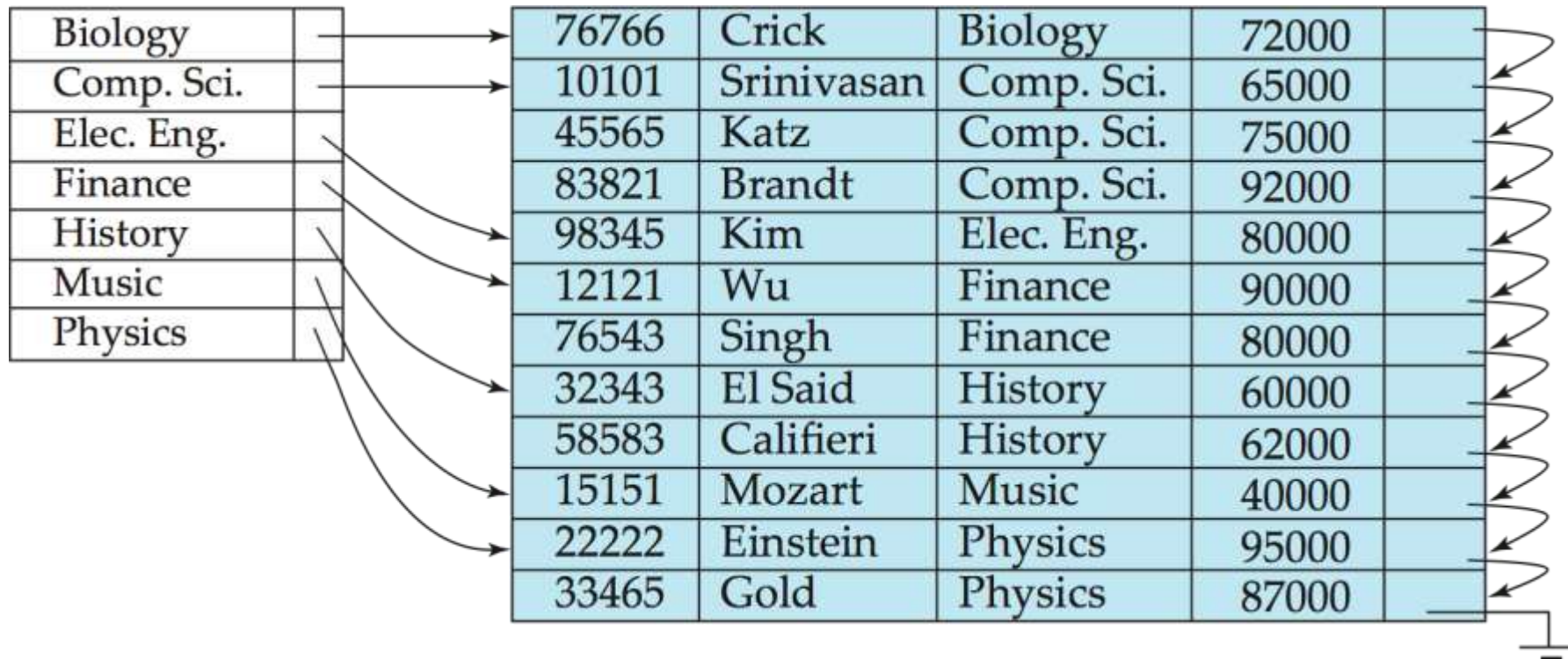
Dense Index Files

- **Dense index** — Index record appears for every search-key value in the file.
 - E.g. index on ID attribute of instructor relation



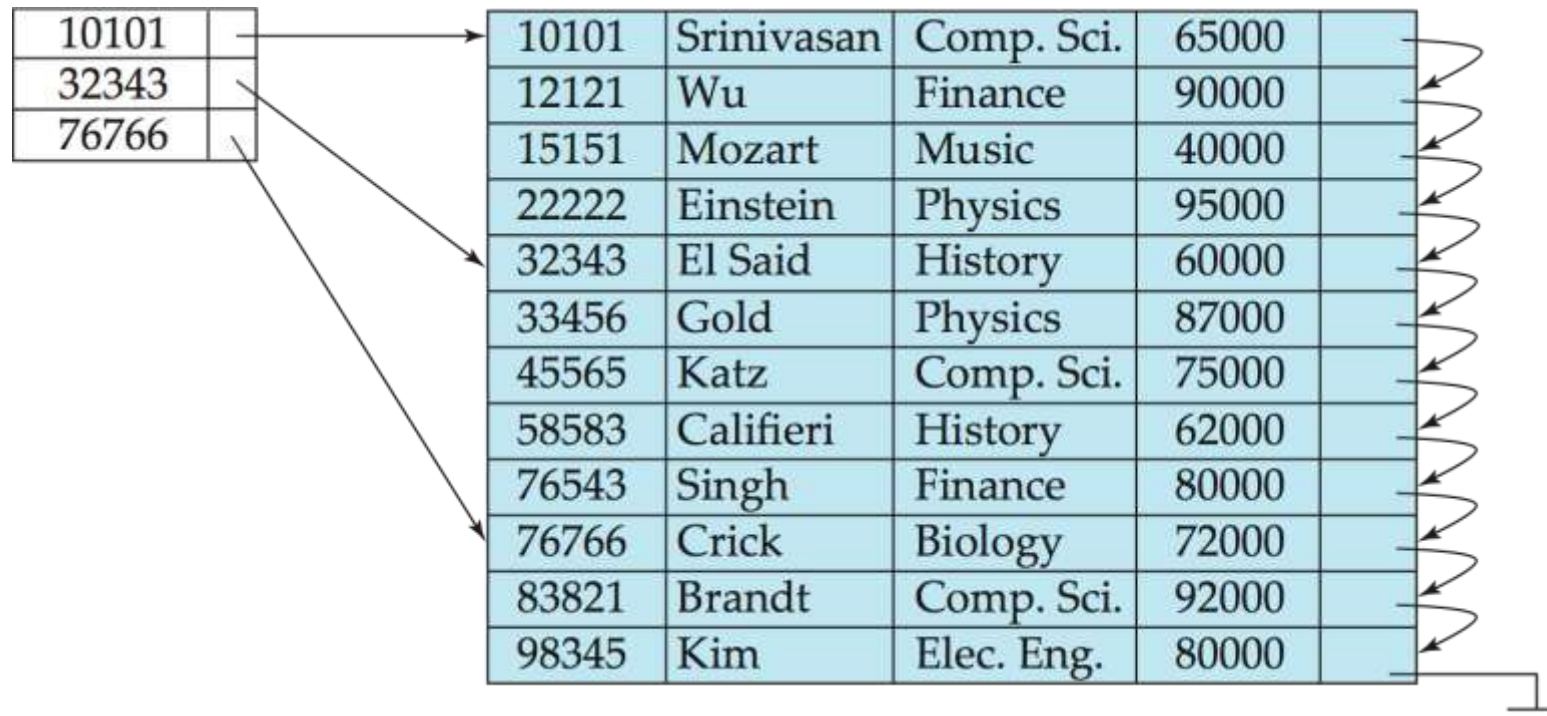
Dense Index Files (Cont.)

- Dense index on dept_name, with instructor file sorted on dept_name



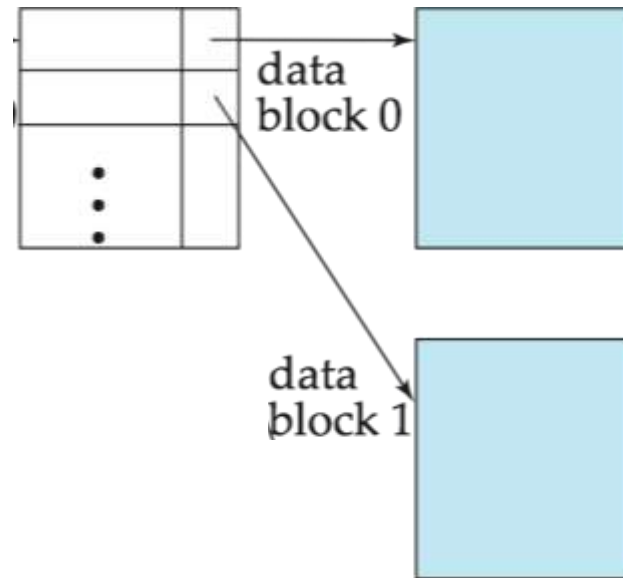
Sparse Index Files

- **Sparse Index:** contains index records for only some search-key values.
 - Applicable when records are sequentially ordered on search-key
- To locate a record with search-key value K we:
 - Find index record with largest search-key value $< K$
 - Search file sequentially starting at the record to which the index record points



Sparse Index Files (Cont.)

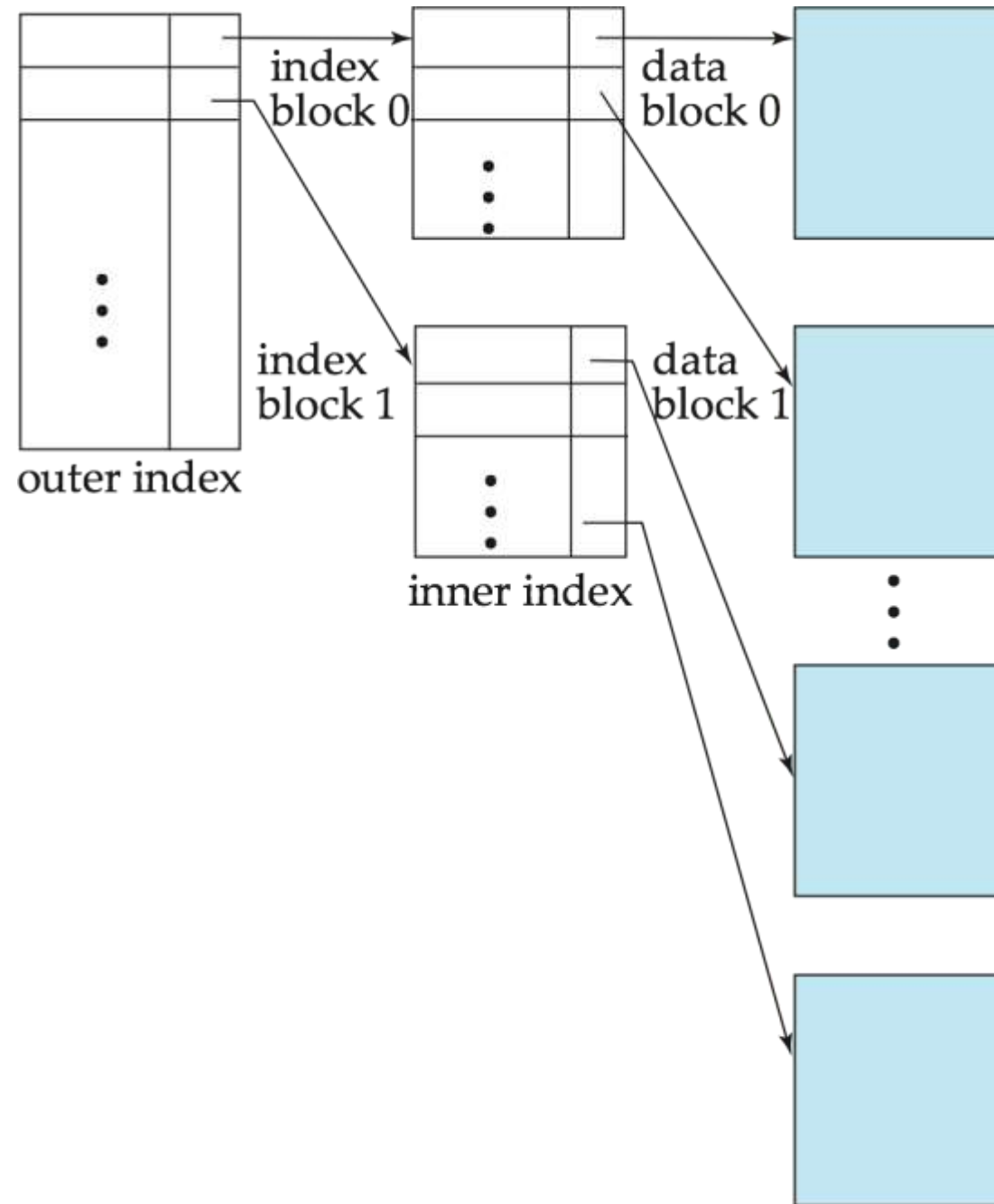
- Compared to dense indices:
 - Less space and less maintenance overhead for insertions and deletions.
 - Generally slower than dense index for locating records.
- **Good tradeoff:** sparse index with an index entry for every block in file, corresponding to least search-key value in the block.



Multilevel Index

- If primary index does not fit in memory, access becomes expensive.
- Solution: treat primary index kept on disk as a sequential file and construct a sparse index on it.
 - outer index – a sparse index of primary index
 - inner index – the primary index file
- If even outer index is too large to fit in main memory, yet another level of index can be created, and so on.
- Indices at all levels must be updated on insertion or deletion from the file.

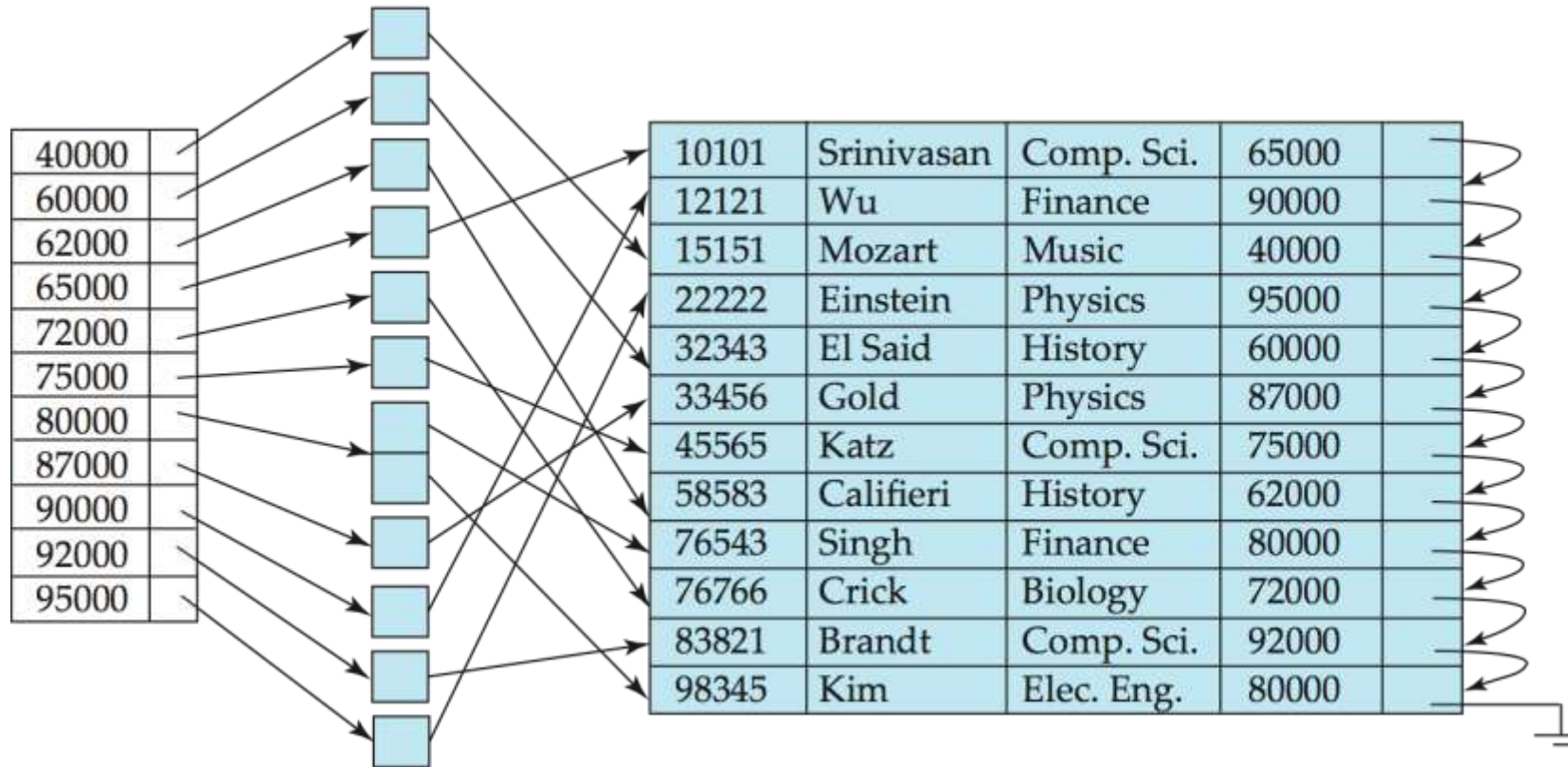
Multilevel Index



Secondary Indices

- Frequently, one wants to find all the records whose values in a certain field (which is not the search-key of the primary index) satisfy some condition.
 - Example 1: In the instructor relation stored sequentially by ID, we may want to find all instructors in a particular department
 - Example 2: as above, but where we want to find all instructors with a specified salary or with salary in a specified range of values
- We can have a secondary index with an index record for each search-key value

Secondary Indices Example



Secondary index on *salary* field of *instructor*

- Index record points to a bucket that contains pointers to all the actual records with that particular search-key value.
- Secondary indices have to be dense

Primary and Secondary Indices

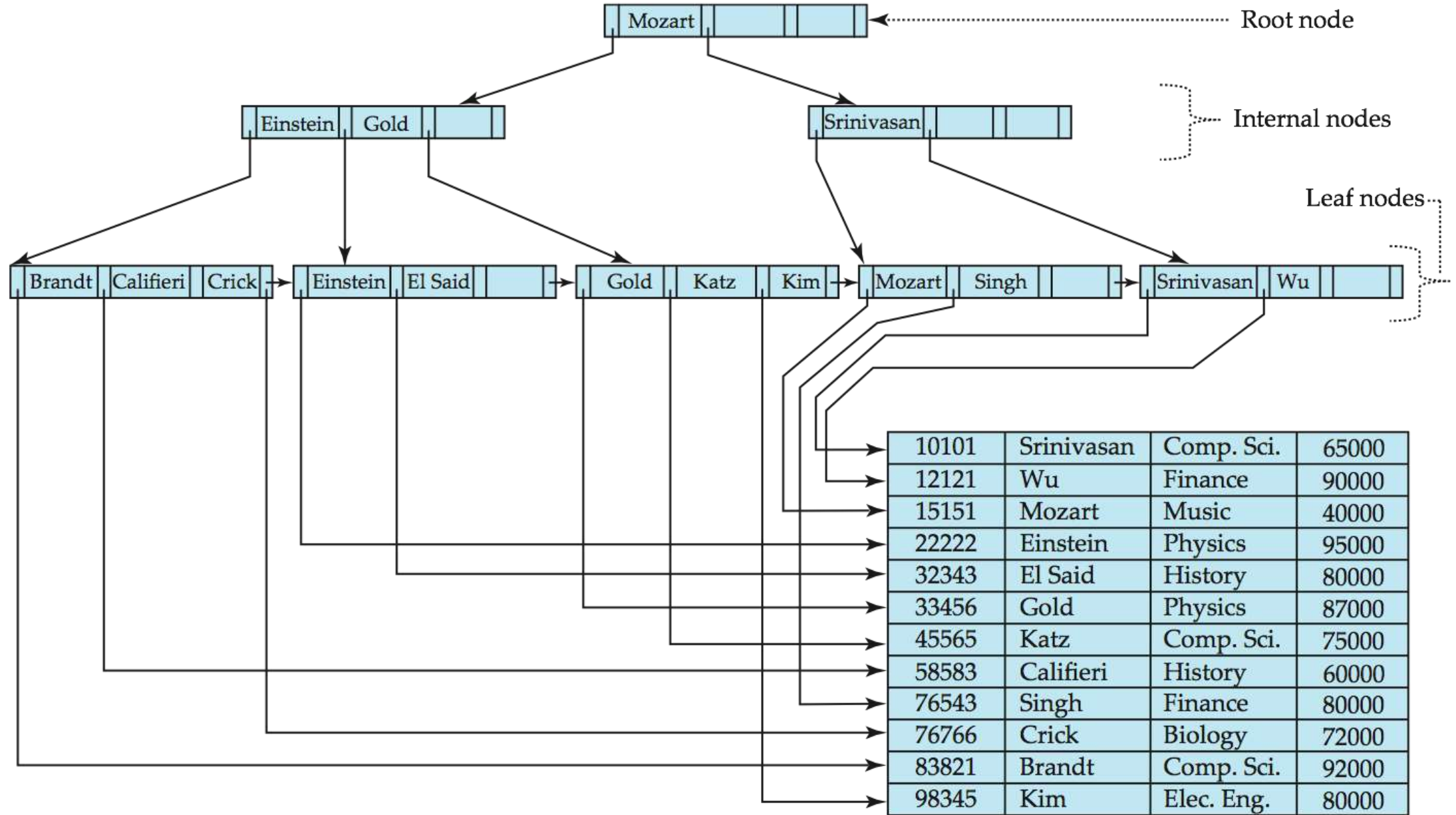
- Indices offer substantial benefits when searching for records.
- BUT: Updating indices imposes overhead on database modification --when a file is modified, every index on the file must be updated,
- Sequential scan using primary index is efficient, but a sequential scan using a secondary index is expensive
 - Each record access may fetch a new block from disk
 - Block fetch requires about 5 to 10 milliseconds, versus about 100 nanoseconds for memory access

B+-Tree Index Files

B⁺-tree indices are an alternative to indexed-sequential files.

- Disadvantage of indexed-sequential files
 - performance degrades as file grows, since many overflow blocks get created.
 - Periodic reorganization of entire file is required.
- Advantage of B⁺-tree index files:
 - automatically reorganizes itself with small, local, changes, in the face of insertions and deletions.
 - Reorganization of entire file is not required to maintain performance.
- (Minor) disadvantage of B⁺-trees:
 - extra insertion and deletion overhead, space overhead.
- Advantages of B⁺-trees outweigh disadvantages
 - B⁺-trees are used extensively

Example of B⁺-Tree



Static Hashing

- A **bucket** is a unit of storage containing one or more records (a bucket is typically a disk block).
- In a **hash file organization** we obtain the bucket of a record directly from its search-key value using a **hash function**.
- Hash function h is a function from the set of all search-key values K to the set of all bucket addresses B .
- Hash function is used to locate records for access, insertion as well as deletion.
- Records with different search-key values may be mapped to the same bucket; thus entire bucket has to be searched sequentially to locate a record.

Example of Hash File Organization

Hash file organization of *instructor* file, using *dept_name* as key (See figure in next slide.)

- There are 10 buckets,
- The binary representation of the *i*th character is assumed to be the integer *i*.
- The hash function returns the sum of the binary representations of the characters modulo 10
 - E.g. $h(\text{Music}) = 1$ $h(\text{History}) = 2$
 $h(\text{Physics}) = 3$ $h(\text{Elec. Eng.}) = 3$

Example of Hash File Organization

bucket 0

bucket 1

15151	Mozart	Music	40000

bucket 2

32343	El Said	History	80000
58583	Califieri	History	60000

bucket 3

22222	Einstein	Physics	95000
33456	Gold	Physics	87000
98345	Kim	Elec. Eng.	80000

bucket 4

12121	Wu	Finance	90000
76543	Singh	Finance	80000

bucket 5

76766	Crick	Biology	72000

bucket 6

10101	Srinivasan	Comp. Sci.	65000
45565	Katz	Comp. Sci.	75000
83821	Brandt	Comp. Sci.	92000

bucket 7

Hash file organization of *instructor* file, using *dept_name* as key (see previous slide for details).

Hash Functions

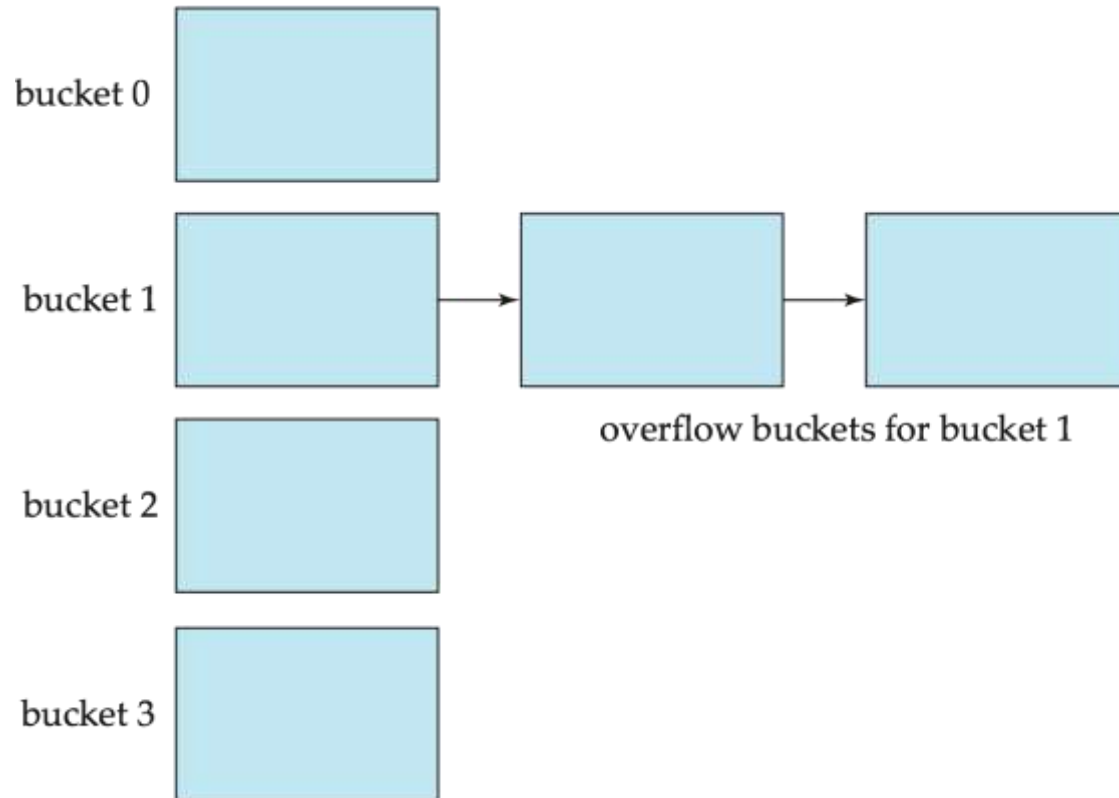
- Worst hash function maps all search-key values to the same bucket; this makes access time proportional to the number of search-key values in the file.
- An ideal hash function is **uniform**, i.e., each bucket is assigned the same number of search-key values from the set of all possible values.
- Ideal hash function is **random**, so each bucket will have the same number of records assigned to it irrespective of the actual distribution of search-key values in the file.
- Typical hash functions perform computation on the internal binary representation of the search-key.
 - For example, for a string search-key, the binary representations of all the characters in the string could be added and the sum modulo the number of buckets could be returned. .

Handling of Bucket Overflows

- Bucket overflow can occur because of
 - Insufficient buckets
 - Skew in distribution of records. This can occur due to two reasons:
 - ▶ multiple records have same search-key value
 - ▶ chosen hash function produces non-uniform distribution of key values
- Although the probability of bucket overflow can be reduced, it cannot be eliminated; it is handled by using **overflow buckets**.

Handling of Bucket Overflows (Cont.)

- **Overflow chaining** – the overflow buckets of a given bucket are chained together in a linked list.
- Above scheme is called **closed hashing**.
 - An alternative, called **open hashing**, which does not use overflow buckets, is not suitable for database applications.



Bitmap Indices

- Bitmap indices are a special type of index designed for efficient querying on multiple keys
- Records in a relation are assumed to be numbered sequentially from, say, 0
 - Given a number n it must be easy to retrieve record n
 - ▶ Particularly easy if records are of fixed size
- Applicable on attributes that take on a relatively small number of distinct values
 - E.g. gender, country, state, ...
 - E.g. income-level (income broken up into a small number of levels such as 0-9999, 10000-19999, 20000-50000, 50000- infinity)
- A bitmap is simply an array of bits

Bitmap Indices (Cont.)

- In its simplest form a bitmap index on an attribute has a bitmap for each value of the attribute
 - Bitmap has as many bits as records
 - In a bitmap for value v , the bit for a record is 1 if the record has the value v for the attribute, and is 0 otherwise

record number	<i>ID</i>	<i>gender</i>	<i>income_level</i>
0	76766	m	L1
1	22222	f	L2
2	12121	f	L1
3	15151	m	L4
4	58583	f	L3

Bitmaps for *gender*

m	10010
f	01101

Bitmaps for *income_level*

L1	10100
L2	01000
L3	00001
L4	00010
L5	00000