

Weak Form for the Self-Adjoint S_N Formalism

1 Self-Adjoint S_N

$$\text{LHS : } = (-\vec{\Omega} \cdot \vec{\nabla} + \sigma_a)(\vec{\Omega} \cdot \vec{\nabla} + \sigma_a)\psi \quad (1)$$

$$= \underbrace{-\vec{\Omega} \cdot \vec{\nabla} \vec{\Omega} \cdot \vec{\nabla} \psi}_{\textcircled{1}} + \underbrace{\left[\sigma_a \vec{\Omega} \cdot \vec{\nabla} \psi - \vec{\Omega} \cdot \vec{\nabla} (\sigma_a \psi) \right]}_{\textcircled{2}} + \underbrace{\sigma_a^2 \psi}_{\textcircled{3}} \quad (2)$$

$$\text{RHS : } = (-\vec{\Omega} \cdot \vec{\nabla} + \sigma_a)Q \quad (3)$$

$$= \underbrace{-\vec{\Omega} \cdot \vec{\nabla} Q}_{\textcircled{4}} + \underbrace{\sigma_a Q}_{\textcircled{5}} \quad (4)$$

Note that for radiative transfer problem, σ_a is embedded in the source Q :

$$Q = \sigma_a B \quad (5)$$

where B is the Planckian source determined by the temperature.

2 Weak form

Multiply every term in LHS and RHS by basis function b_i and integrate over the problem volume:

LHS:

$$\begin{aligned} & \boxed{\int \textcircled{1} b_i dV} \\ &= \int -b_i \vec{\Omega} \cdot \vec{\nabla} \vec{\Omega} \cdot \vec{\nabla} \psi dV \end{aligned} \quad (6)$$

$$= - \underbrace{\oint (\vec{\Omega} \cdot \vec{\nabla} \psi) b_i \vec{\Omega} \cdot \vec{n} dA}_{*} + \int (\vec{\Omega} \cdot \vec{\nabla} \psi) (\vec{\Omega} \cdot \vec{\nabla} b_i) dV \quad (7)$$

$$\begin{aligned} & \boxed{\int \textcircled{2} b_i dV} \\ &= \int \left[\sigma_a \vec{\nabla} \cdot (\vec{\Omega} \psi) - \vec{\nabla} \cdot (\sigma_a \vec{\Omega} \psi) \right] b_i dV \end{aligned} \quad (8)$$

$$= \int (-\vec{\Omega} \psi \cdot \vec{\nabla} \sigma_a) b_i dV = \int (-\vec{\Omega} \psi b_i \cdot \vec{\nabla} \sigma_a) dV \quad (9)$$

$$= - \underbrace{\oint \sigma_a \psi b_i \vec{\Omega} \cdot \vec{n} dA}_{*} + \int \sigma_a \vec{\nabla} \cdot (\vec{\Omega} \psi b_i) dV \quad (10)$$

$$\begin{aligned}
& \boxed{\int \mathfrak{B} b_i dV} \\
& = \int \sigma_a^2 \psi b_i dV
\end{aligned} \tag{11}$$

RHS:

$$\begin{aligned}
& \boxed{\int \mathfrak{Q} b_i dV} \\
& = \int (-\vec{\Omega} \cdot \vec{\nabla} Q) b_i dV
\end{aligned} \tag{12}$$

$$= - \oint b_i Q \vec{\Omega} \cdot \vec{n} dA + \int Q \vec{\Omega} \cdot \vec{\nabla} b_i dV \tag{13}$$

$$\text{or} \tag{14}$$

$$= - \int \vec{\Omega} \cdot \vec{\nabla} (\sigma_a B) b_i dV \tag{15}$$

$$= - \int \vec{\Omega} (\vec{\nabla} \sigma_a B + \vec{\nabla} B \sigma_a) b_i dV \tag{16}$$

$$\begin{aligned}
& \boxed{\int \mathfrak{S} b_i dV} \\
& = \int \sigma_a Q b_i dV = \int \sigma_a^2 B b_i dV
\end{aligned} \tag{17}$$

Depending on the order of finite element chosen to represent the solution and material property (opacity (cross-section), source), two different sets of weak form are proposed:

If we choose to use piece-wise constant (0^{th} order) finite element, then it is suggested to use the terms underlined whenever possible (as seen in Eq. (10) and Eq. (13)).

If we choose to use piece-wise linear (1^{st} order) finite element, then it is suggested to use the terms double – lined whenever possible (as seen in Eq. (9) and Eq. (16)).

Note that one can choose to use either the underlined or the double – lined, not both. Because they are mathematically equivalent.

3 Boundary condition

For the in-coming directions, we use Dirichlet boundary condition to explicitly specify the value of ψ on the boundary.

For the out-going directions, we use the first order equation:

$$\vec{\Omega} \cdot \vec{\nabla} \psi + \sigma_a \psi = Q \Rightarrow \boxed{\vec{\Omega} \cdot \vec{\nabla} \psi = Q - \sigma_a \psi} \quad (18)$$

The out-going boundary condition Eq. (18) is applied to the $*$ term only, where $\vec{\Omega} \cdot \vec{\nabla} \psi$ is replaced by $Q - \sigma_a \psi$, yielding:

$$* = \oint (\vec{\Omega} \cdot \vec{\nabla} \psi) b_i \vec{\Omega} \cdot \vec{n} dA = - \underbrace{\oint Q b_i \vec{\Omega} \cdot \vec{n} dA}_{\text{move to RHS}} + \underbrace{\oint \sigma_a \psi b_i \vec{\Omega} \cdot \vec{n} dA}_{\text{keep on LHS}}, \quad \text{for } \vec{\Omega} \cdot \vec{n} > 0 \quad (19)$$

The $\vec{\Omega} \cdot \vec{n} > 0$ portion of this $*$ term is neglected, it is equivalent to force:

$$* = \oint (\vec{\Omega} \cdot \vec{\nabla} \psi) b_i \vec{\Omega} \cdot \vec{n} dA = 0, \quad \text{for } \vec{\Omega} \cdot \vec{n} < 0 \quad (20)$$

4 Final form after cancellation of the surface terms

Take the five kernels listed in the above section, using the underlined as seen in Eq. (10) and Eq. (13), and also applying the first order boundary condition Eq. (18) for both out-going and in-coming directions for the boundary term ($*$), we get:

$$\begin{aligned} \text{LHS} := & - \cancel{\oint Q b_i \vec{\Omega} \cdot \vec{n} dA}^{\text{II}} + \cancel{\oint \sigma_a \psi b_i \vec{\Omega} \cdot \vec{n} dA}^{\text{I}} + \int (\vec{\Omega} \cdot \vec{\nabla} \psi) (\vec{\Omega} \cdot \vec{\nabla} b_i) dV \\ & - \cancel{\oint \sigma_a \psi b_i \vec{\Omega} \cdot \vec{n} dA}^{\text{I}} + \boxed{\int \sigma_a \vec{\nabla} \cdot (\vec{\Omega} \psi b_i) dV} \\ & + \int \sigma_a^2 \psi b_i dV \end{aligned} \quad (21)$$

$$\begin{aligned} \text{RHS} := & - \cancel{\oint b_i Q \vec{\Omega} \cdot \vec{n} dA}^{\text{II}} + \int Q \vec{\Omega} \cdot \vec{\nabla} b_i dV \\ & + \int \sigma_a Q b_i dV \end{aligned} \quad (22)$$

We can see that the “I” terms cancels out each other, and the same for the “II” terms. Finally, expand out the boxed term in LHS:

$$\boxed{\int \sigma_a \vec{\nabla} \cdot (\vec{\Omega} \psi b_i) dV} = \int \sigma_a b_i \vec{\Omega} \cdot \vec{\nabla} \psi dV + \int \sigma_a \psi \vec{\Omega} \cdot \vec{\nabla} b_i \quad (23)$$

Our final form becomes:

$$\begin{aligned}
\text{LHS} := & \int (\vec{\Omega} \cdot \vec{\nabla} \psi) (\vec{\Omega} \cdot \vec{\nabla} b_i) dV \\
& \int \sigma_a b_i \vec{\Omega} \cdot \vec{\nabla} \psi dV + \int \sigma_a \psi \vec{\Omega} \cdot \vec{\nabla} b_i \\
& + \int \sigma_a^2 \psi b_i dV
\end{aligned} \tag{24}$$

$$\begin{aligned}
\text{RHS} := & \int Q \vec{\Omega} \cdot \vec{\nabla} b_i dV \\
& + \int \sigma_a Q b_i dV
\end{aligned} \tag{25}$$

The same as Dr. Ragusa's derivation. However, in my implementation I only used the first order boundary condition for the out-going directions, as explained in the Boundary condition section. Therefore, the "I" and "II" terms doesn't cancel themselves out completely. The in-coming portion of those terms remains.