

## Homework 4

Submit answers for problems 1–6. Problems 7 and 8 are included as practice problems.

1. Exercise T3.55.
2. Exercise T4.13.
3. Exercise A4.39.
4. Exercise T4.25.
5. Exercise A4.21(a,b)
6. Exercise A15.6.
7. Exercise T4.26(a).

**Solution.** The problem is equivalent to

$$\begin{aligned} & \text{minimize} && \mathbf{1}^T t \\ & \text{subject to} && t_i(a_i^T x - b_i) \geq 1, \quad i = 1, \dots, m \\ & && t \succeq 0. \end{aligned}$$

Writing the hyperbolic constraints as second order cone constraints yields an SOCP

$$\begin{aligned} & \text{minimize} && \mathbf{1}^T t \\ & \text{subject to} && \left\| \begin{bmatrix} 2 \\ a_i^T x - b_i - t_i \end{bmatrix} \right\|_2 \leq a_i^T x - b_i + t_i, \quad i = 1, \dots, m \\ & && t \succeq 0. \end{aligned}$$

8. Exercise T4.27.

**Solution.** To show the equivalence with the problem in the hint, we assume  $x \succeq 0$  is fixed, and optimize over  $v$  and  $w$ . This is a quadratic problem with equality constraints:

$$\begin{aligned} & \text{minimize} && \begin{bmatrix} v \\ w \end{bmatrix}^T \begin{bmatrix} I & 0 \\ 0 & \mathbf{diag}(x)^{-1} \end{bmatrix} \begin{bmatrix} v \\ w \end{bmatrix} \\ & \text{subject to} && \begin{bmatrix} I & B \end{bmatrix} \begin{bmatrix} v \\ w \end{bmatrix} = Ax + b. \end{aligned}$$

The optimality conditions (from lecture 4, page 13) are

$$\begin{bmatrix} v \\ \mathbf{diag}(x)^{-1}w \end{bmatrix} = \begin{bmatrix} I \\ B^T \end{bmatrix} \nu, \quad \begin{bmatrix} I & B \end{bmatrix} \begin{bmatrix} v \\ w \end{bmatrix} = Ax + b.$$

In other words,  $v$  and  $w$  are optimal if and only if there exists a  $\nu$  such that

$$v = \nu, \quad w = \mathbf{diag}(x)B^T\nu, \quad v + Bw = Ax + b.$$

Substituting the expressions for  $v$  and  $w$  from the first two equations in the third equation, we find that  $\nu$  must satisfy

$$(I + B \mathbf{diag}(x)B^T)\nu = Ax + b.$$

Since the matrix on the left is invertible for  $x \succeq 0$ , we can solve for  $\nu$ . Therefore the optimal  $v, w$  for the optimization problem in the hint are

$$v = \nu = (I + B \mathbf{diag}(x)B^T)^{-1}(Ax + b)$$

and

$$w = \mathbf{diag}(x)B^T\nu = \mathbf{diag}(x)B^T(I + B \mathbf{diag}(x)B^T)^{-1}(Ax + b).$$

Substituting these expressions for  $v$  and  $w$  in the objective of the problem in the hint, we obtain

$$v^T v + w^T \mathbf{diag}(x)^{-1}w = (Ax + b)^T(I + B \mathbf{diag}(x)B^T)^{-1}(Ax + b).$$

This shows that the problem is equivalent to the problem in the hint.

As in exercise 4.26 we now introduce hyperbolic constraints and formulate the problem in the hint as

$$\begin{aligned} & \text{minimize} && t + \mathbf{1}^T s \\ & \text{subject to} && v^T v \leq t \\ & && w_i^2 \leq s_i x_i, \quad i = 1, \dots, n \\ & && x \succeq 0 \end{aligned}$$

with variables  $t \in \mathbf{R}$ ,  $s, x, w \in \mathbf{R}^n$ ,  $v \in \mathbf{R}^m$ . Converting the hyperbolic constraints into second order cone constraints results in the SOCP

$$\begin{aligned} & \text{minimize} && t + \mathbf{1}^T s \\ & \text{subject to} && \left\| \begin{bmatrix} 2v \\ 1 - t \end{bmatrix} \right\|_2 \leq 1 + t \\ & && \left\| \begin{bmatrix} 2w_i \\ s_i - x_i \end{bmatrix} \right\|_2 \leq s_i + x_i, \quad i = 1, \dots, n \\ & && x \succeq 0. \end{aligned}$$