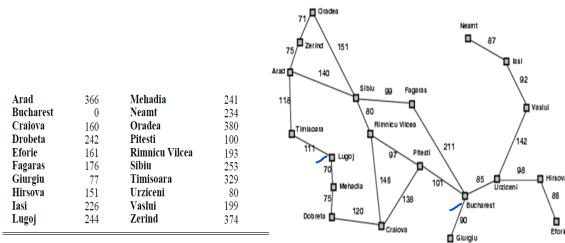
Algorithms and Problem Solving (15B11CI411) Tutorial 14-15

Week 14-15 (1-11th May, 2018)

- Q1. You are given two jugs, a 4-litre one and a 3-litre one. Neither have any measuring markers on it. There is a pump that can be used to fill the jugs with water. How can you get exactly 2 litres of water into 4-litre jug? Formulate the problem as a state-space problem
 - 1. Define a state space that contains all the possible configurations of the relevant objects.
 - 2. Specify the initial states.
 - 3. Specify the goal states.
 - 4. Specify a set of rules

Represent a state of the problem as a tuple (x, y) where x represents the amount of water in the 4-gallon jug and y represents the amount of water in the 3-gallon jug.

- **Q2.** Your goal is to navigate a robot out of a maze. The robot starts in the center of the *maze* facing north. You can turn the robot to face north, east, south, or west. You can direct the robot to move forward a certain distance, although it will stop before hitting a wall.
 - a. Formulate this problem. How large is the state space?
 - b. In navigating a maze, the only place we need to turn is at the intersection of two or more corridors. Reformulate this problem using this observation. How large is the state space now?
 - c. From each point in the maze, we can move in any of the four directions until we reach a turning point, and this is the only action we need to do. Reformulate the problem using these actions. Do we need to keep track of the robot's orientation now?
 - d. In our initial description of the problem we already abstracted from the real world, restricting actions and removing details. List three such simplifications we made.
- **Q3.** Consider a state space where the start state is number 1 and each state k has two successors: numbers 2k and 2k + 1.
 - a. Draw the portion of the state space for states 1 to 15.
 - b. Suppose the goal state is 11. List the order in which nodes will be visited for breadth-first search, depth-limited search with limit 3, and iterative deepening search.
- **Q4.** Trace the operation of A^* search applied to the problem of getting to Bucharest from Lugoj using the straight-line distance heuristic. Show the sequence of nodes that the algorithm will consider.



Values of h_{SLD} —straight-line distances to Bucharest.

Q5. Define different Types of Complexity Classes along with 2 suitable examples for each class. Also mention the relation between them.