

Department of Mathematics
Odd Semester 2017

Probability and Random Processes
Probability and Random Processes
Tutorial Sheet 7

15B11MA301
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B.Tech. Core

Random Process

1. Define a random process and classify them with suitable examples.
2. In an experiment of two fair dice, the process $\{X(t)\}$ is defined as $X(t) = \sin \pi t$, if the experiment shows a prime sum and $X(t) = 2t + 1$, otherwise. Find the mean of the process. Is the process stationary? [Ans: not stationary]
3. Let $X(t) = A \cos \lambda t + B \sin \lambda t$, with random variable A taking values 1 and 3 with equal probabilities and random variable B taking values -1 and 1 with probabilities $\frac{1}{4}$ and $\frac{3}{4}$ respectively. Test the process $\{X(t)\}$ for stationarity. [Ans: not stationary]
4. Test the random processes $\{X(t)\}$ and $\{Y(t)\}$ for WSS when:
 - (i) $X(t) = \cos(\lambda t + Y)$, where λ is a constant and Y is uniform in $(0, 2\pi)$
[Ans: WSS]
 - (ii) $Y(t) = X \sin(\lambda t)$, where λ is a constant and X is uniform in $(-1, 1)$.
[Ans: not WSS]
5. Find auto correlation functions of the processes $\{X(t)\}$ and $\{Y(t)\}$ such that $X(t) = A \cos \lambda t + B \sin \lambda t$ and $Y(t) = B \cos \lambda t - A \sin \lambda t$, where A and B are uncorrelated random variables taking value -4 and 4 with equal probabilities. Prove that $\{X(t)\}$ and $\{Y(t)\}$ are jointly WSS.
6. Given a random variable Y with characteristic function $\phi(w) = E(e^{iwY})$ and a random process defined by $X(t) = \cos(3t + 2Y)$. Find the condition under which the process $\{X(t)\}$ is WSS. [Ans: $\phi(4) = \phi(8) = 0$]
7. If $\{X(t)\}$ is a WSS process with $E\{X(t)\} = 2$ and $R_{XX}(\tau) = 4 + e^{-|\tau|/10}$, find the variance of $X(1)$, $X(2)$ and $X(3)$. Also compute the second order moment about origin of $X(1) + X(2) + X(3)$.
8. Define a Random walk and prove that the limiting form of a random walk is Wiener process.

When we do any random experiment then we find lot of outcome. A variable which represent this outcome is called Random Variable, whereas a function or rule which assigns a time function to every outcome of a random experiment is called a random process.

Mean of random process $\{X(t)\}$

$$\mu(t) = E\{X(t)\}$$

Autocorrelation

$$R_{xx}(t_1, t_2) = R(t_1, t_2) = E\{X(t_1) X(t_2)\}$$

Autocovariance

$$\begin{aligned} C_{xx}(t_1, t_2) &= C(t_1, t_2) \\ &= E\{[X(t_1) - \mu(t_1)] [X(t_2) - \mu(t_2)]\} \\ &= R(t_1, t_2) - \mu(t_1) \mu(t_2) \end{aligned}$$

Correlation coefficient $\rho_{xx}(t_1, t_2) = \rho(t_1, t_2)$

$$= \frac{C(t_1, t_2)}{\sqrt{C(t_1, t_1) \times C(t_2, t_2)}}$$

Cross-correlation of 2 processes $\{X(t)\}$ & $\{Y(t)\}$ (jointly)

$$R_{xy}(t_1, t_2) = E\{X(t_1) Y(t_2)\}$$

Cross-covariance $= C_{xy}(t_1, t_2) = R_{xy}(t_1, t_2) - \mu_x(t_1) \mu_y(t_2)$

Cross-correlation coefficient $\rho_{xy}(t_1, t_2)$

$$= \frac{C_{xy}(t_1, t_2)}{\sqrt{C_{xx}(t_1, t_1) \times C_{yy}(t_2, t_2)}}$$

Strongly stationary Process:- (SSS Process)
(strict sense stationary process)

If SSS then densities of $X(t)$ & $X(t+h)$ are the same i.e. $f(x, t) = f(x, t+h)$

$\Rightarrow f(x, t)$ is independent of t .

$\Rightarrow E\{X(t)\}$ is independent of time

$$E\{X(t)\} = \text{Const.}$$

Wide sense stationary process (WSS) :-

$$E[X(t)] = \text{const}$$

$$R(t_1, t_2) = \text{function of } (t_1 - t_2)$$

$\{X(t)\}$ need not be SSS.

Q.2:-

$$S = \{ \begin{matrix} (1,1) & (1,2) & (1,3) & (1,4) & (1,5) & (1,6) \\ (2,1) & (2,2) & (2,3) & (2,4) & (2,5) & (2,6) \\ (3,1) & (3,2) & (3,3) & (3,4) & (3,5) & (3,6) \\ (4,1) & (4,2) & (4,3) & (4,4) & (4,5) & (4,6) \\ (5,1) & (5,2) & (5,3) & (5,4) & (5,5) & (5,6) \\ (6,1) & (6,2) & (6,3) & (6,4) & (6,5) & (6,6) \end{matrix} \}$$

prime sum

$$2 - (1,1)$$

$$3 - (1,2) (2,1)$$

$$5 - (1,4) (2,3) (3,2) (4,1)$$

$$7 - (1,6) (2,5) (3,4) (4,3) (5,2) (6,1)$$

$$11 - (5,6) (6,5)$$

$$P(\text{prime sum}) = \frac{15}{36} = \frac{5}{12}$$

$$E(X(t)) = \sum x_i p_i$$

$$P(\text{not prime sum}) = \frac{21}{36} = \frac{7}{12}$$

$$\begin{aligned} E\{X(t)\} &= P\{X(t) = \sin \pi t\} \sin \pi t + P\{X(t) = 2t+1\} (2t+1) \\ &= \frac{5}{12} \sin \pi t + \frac{7}{12} (2t+1) \end{aligned}$$

It depends upon t so it is not stationary.

Q.3:-

$$\{X(t)\} = A \cos \lambda t + B \sin \lambda t$$

with R.V. A taking values 1 & 3 equal probability

& R.V. B taking values -1 & 1 with prob. $\frac{1}{4}$ & $\frac{3}{4}$

$$\begin{aligned} E\{X(t)\} &= E\{A \cos \lambda t + B \sin \lambda t\} \\ &= \cos \lambda t E(A) + \sin \lambda t E(B) \end{aligned}$$

$$E(A) = 1 \times \frac{1}{2} + \frac{1}{2} \times 3 = 2$$

$$= -1 \times \frac{1}{4} + 1 \times \frac{3}{4} = \frac{3-1}{4} = \frac{1}{2}$$

$$E\{X(t)\} = 2 \cos \lambda t + \frac{1}{2} \sin \lambda t$$

$E\{X(t)\}$ depends on t , so not stationary.

Q.4:- i) $X(t) = \cos(\lambda t + Y)$, $Y \sim (0, 2\pi)$

P.d.f of this $Y \sim f_Y(y) = \frac{1}{2\pi}$, $0 \leq y \leq 2\pi$

$$\begin{aligned} E(X(t)) &= E[\cos(\lambda t + Y)] \\ &= E[\cos \lambda t \cos Y - \sin \lambda t \sin Y] \\ &= \cos \lambda t E(\cos Y) - \sin \lambda t E(\sin Y) \end{aligned}$$

$$\begin{aligned} E(\cos Y) &= \int_0^{2\pi} \frac{1}{2\pi} \cos Y \, dY \\ &= \frac{1}{2\pi} [-\sin Y]_0^{2\pi} = 0 \end{aligned}$$

$$\begin{aligned} E(\sin Y) &= \int_0^{2\pi} \frac{1}{2\pi} \sin Y \, dY \\ &= \frac{1}{2\pi} [\cos Y]_0^{2\pi} = \frac{1}{2\pi} [1 - 1] = 0 \end{aligned}$$

$$\begin{aligned} E(X(t)) &= \cos \lambda t E(\cos Y) - \sin \lambda t E(\sin Y) \\ &= 0 \end{aligned}$$

or

$$\begin{aligned} E\{X(t)\} &= \int_0^{2\pi} \frac{1}{2\pi} \cos(\lambda t + Y) \, dY \\ &= \frac{1}{2\pi} [\sin(\lambda t + Y)]_0^{2\pi} \\ &= \frac{1}{2\pi} [\sin(2\pi + \lambda t) - \sin(\lambda t)] \\ &= \frac{1}{2\pi} [\sin \lambda t - \sin \lambda t] \end{aligned}$$

$$= 0 = \text{const}$$

$$E\{X(t_1) X(t_2)\} = E\{\cos(\lambda t_1 + Y) \cos(\lambda t_2 + Y)\} \quad 3$$

$$= \frac{E}{2} \{ \cos(\lambda t_1 + Y + \lambda t_2 + Y) + \cos(\lambda t_1 + Y - \lambda t_2 - Y) \}$$

$$= \frac{E}{2} \{ \cos(\lambda(t_1 + t_2) + 2Y) + \cos \lambda(t_1 - t_2) \}$$

$$= \frac{1}{2} \times \frac{1}{2\pi} \int_0^{2\pi} \cos[\lambda(t_1 + t_2) + 2Y] + \cos \lambda(t_1 - t_2) dy$$

$$= \frac{1}{4\pi} \left[\frac{\sin(\lambda(t_1 + t_2) + 2Y)}{2} + \cos \lambda(t_1 - t_2) \cdot Y \right]_0^{2\pi}$$

$$= \frac{1}{4\pi} \left[\frac{\sin \lambda(t_1 + t_2) + 4\pi}{2} + 2\pi \cos \lambda(t_1 - t_2) - \frac{\sin \lambda(t_1 + t_2)}{2} \right]$$

$$= \frac{1}{2} \cos \lambda(t_1 - t_2) \quad \text{which is a function of } t_1 - t_2$$

$\therefore \{X(t)\}$ is WSS process.

ii) $Y(t) = X \sin(\lambda t), \quad X \sim (-1, 1)$

$$X \sim f_X(x) = \frac{1}{2}, \quad -1 \leq x \leq 1$$

$$E\{Y(t)\} = \int_{-1}^1 x \sin(\lambda t) \times \frac{1}{2} dx$$

$$= \frac{1}{2} \sin(\lambda t) \cdot \left[\frac{x^2}{2} \right]_{-1}^1$$

$$= 0 \quad \text{const.}$$

$$R(t_1, t_2) = E\{Y(t_1) Y(t_2)\}$$

$$= E\{X^2 \sin(\lambda t_1) \sin(\lambda t_2)\}$$

$$= E\left\{ \frac{X^2 \cos(\lambda(t_1 - t_2)) - \cos(\lambda(t_1 + t_2))}{2} \right\}$$

$$= \int_{-1}^1 \frac{\cos(\lambda(t_1 - t_2)) - \cos(\lambda(t_1 + t_2))}{2} \cdot \frac{x^2}{2} dx$$

$$= \frac{\cos(\lambda(t_1 - t_2)) - \cos(\lambda(t_1 + t_2))}{4 \times 3} \cdot x^3 \Big|_{-1}^1$$

$$= \frac{\cos(\lambda(t_1 - t_2)) - \cos(\lambda(t_1 + t_2))}{6}$$

Not a function of $t_1 - t_2$

So not WSS process.

⑤ Auto Correlation Function $R_{xy}(t_1, t_2)$

$$X(t) = A \cos \lambda t + B \sin \lambda t$$

$$Y(t) = B \cos \lambda t - A \sin \lambda t$$

A & B are uncorrelated r.v

$$\text{i.e. } E(AB) = E(A)E(B)$$

$$E(A) = -4 \times \frac{1}{2} + 4 \times \frac{1}{2} = 0$$

$$E(B) = 0$$

$$\text{i.e. } E(AB) = 0$$

$$E(A^2) = 16 \times \frac{1}{2} + 16 \times \frac{1}{2} = 16 \quad \text{Var}(A)$$

$$E(B^2) = 16 = \text{Var}(B)$$

$$R_{xx}(t_1, t_2) = E\{X(t_1)X(t_2)\} = E\{(A \cos \lambda t_1 + B \sin \lambda t_1)(A \cos \lambda t_2 + B \sin \lambda t_2)\}$$

$$= E(A^2) \cos \lambda t_1 \cos \lambda t_2 + E(BA) \sin \lambda t_1 \cos \lambda t_2 + E(AB) \cos \lambda t_1 \sin \lambda t_2 + E(B^2) \sin \lambda t_1 \sin \lambda t_2$$

$$= 16 (\cos \lambda t_1 \cos \lambda t_2 + \sin \lambda t_1 \sin \lambda t_2)$$

$$= 16 \cos(\lambda(t_1 - t_2))$$

$$R_{yy}(t_1, t_2) = E(Y(t_1)Y(t_2))$$

$$= E[(B \cos \lambda t_1 - A \sin \lambda t_1)(B \cos \lambda t_2 - A \sin \lambda t_2)]$$

$$= 16 [\cos \lambda t_1 \cos \lambda t_2 + \sin \lambda t_1 \sin \lambda t_2]$$

$$= 16 \cos(\lambda(t_1 - t_2))$$

$$R_{yy}(t_1, t_2) = E\{y(t_1)y(t_2)\}$$

$$= E\{(A \cos \lambda t_1 + B \sin \lambda t_1)(B \cos \lambda t_2 - A \sin \lambda t_2)\}$$

$$= E\{AB \cos \lambda t_1 \cos \lambda t_2 - A^2 \cos \lambda t_1 \sin \lambda t_2 + B^2 \sin \lambda t_1 \cos \lambda t_2 - AB \sin \lambda t_1 \sin \lambda t_2\}$$

$$= E(B^2) \sin \lambda t_1 \cos \lambda t_2 - E(A^2) \cos \lambda t_1 \sin \lambda t_2$$

$$= 16 [\cos \lambda t_2 \sin \lambda t_1 - \cos \lambda t_1 \sin \lambda t_2]$$

$$= 16 \sin [\lambda(t_1 - t_2)]$$

is a function of $t_1 - t_2$

\therefore jointly WSS.

(7)

$\{X(t)\}$ is a WSS process i.e. $\tau = t_1 - t_2$

with $E\{X(t)\} = 2$

$$R_{XX}(t_1, t_2) = 4 + e^{-|t_1 - t_2|/10} \quad R_X(t_1, t_2) = E\{X(t_1)X(t_2)\}$$

$$E\{X^2(t)\} = R_{XX}(t, t) = 4 + e^0 = 5$$

$$E\{X(t)X(t)\}$$

$$\text{variance} = E\{X^2(t)\} - (E\{X(t)\})^2$$

$$= 5 - 4 = 1$$

2nd order moment of $X(1) + X(2) + X(3)$

$$\text{i.e. } E\{X(1) + X(2) + X(3)\}^2$$

$$= E\{X^2(1)\} + E\{X^2(2)\} + E\{X^2(3)\} + 2E\{X(1)X(2)\} + 2E\{X(2)X(3)\} + 2E\{X(3)X(1)\}$$

$$= 5 + 5 + 5 + 2[4 + e^{-1/10} + 4 + e^{-1/5} + 4 + e^{-1/10}]$$

$$= 39 + 4e^{-1/10} + 2e^{-1/5} \quad \text{Ans}$$

$$\therefore E\{X(1)X(2)\} = R(1, 2) = 4 + e^{-1/10}$$

$$E\{X^2(t)\}$$

⑥ Given $X(t) = \cos(3t + 2\pi)$

$$\phi(2\omega) = E(e^{i\omega Y})$$

$$E[X(t)] = E[\cos(3t + 2\pi)]$$

$$= E[\cos 3t \cos 2\pi - \sin 3t \sin 2\pi]$$

$$= \cos 3t E(\cos 2\pi) - \sin 3t E(\sin 2\pi)$$

Now find $E(\cos 2\pi) = ?$

$$E(\sin 2\pi) = ?$$

$$\phi(2\omega) = E[e^{i\omega Y}] = E[\cos \omega Y + i \sin \omega Y]$$

$$E(\cos \omega Y) + i E(\sin \omega Y) = \phi(2\omega)$$

Put $\omega = 2$

$$\phi(4) = E(\cos 2\pi) + i E(\sin 2\pi)$$

Put $\phi(4) = 0$

$$0 = E(\cos 2\pi) + i E(\sin 2\pi)$$

$$\Rightarrow E(\cos 2\pi) = 0, E(\sin 2\pi) = 0$$

$$E(X(t)) = 0$$

$$R(t_1, t_2) = E[X(t_1) X(t_2)]$$

$$= E[\cos(3t_1 + 2\pi) \cos(3t_2 + 2\pi)]$$

$$= \frac{E}{2} [\cos(3t_1 + 2\pi + 3t_2 + 2\pi) + \cos(3t_1 + 2\pi - 3t_2 - 2\pi)]$$

$$= \frac{E}{2} [\cos(3(t_1 + t_2) + 4\pi) + \cos(3(t_1 - t_2))]]$$

$$= \frac{1}{2} \cos 3(t_1 - t_2) + \frac{1}{2} E[\cos 3(t_1 + t_2) \cos 4\pi - \sin 3(t_1 + t_2) \sin 4\pi]$$

$$= \frac{1}{2} \cos 3(t_1 - t_2) + \frac{1}{2} E(\cos 4\pi) \cos 3(t_1 + t_2) + \frac{1}{2} E(\sin 4\pi) \sin 3(t_1 + t_2)$$

$$= \frac{1}{2} \cos 3(t_1 - t_2) + \frac{1}{2} \times 0 + \frac{1}{2} \times 0$$

$$= \frac{1}{2} \cos 3(t_1 - t_2) \text{ is WSS process.}$$

\therefore

Put $\omega = 4$

$\therefore \phi(8) = 0$

$$\phi(2\omega) = E(\cos 2\omega Y) + i E(\sin 2\omega Y)$$

$$\phi(8) = E(\cos 4\pi) + i E(\sin 4\pi)$$

$$E(\cos 4\pi) = 0 \quad E(\sin 4\pi) = 0$$