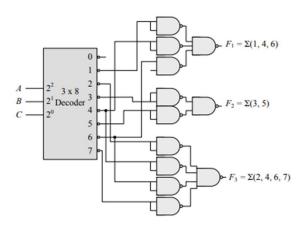


4.27

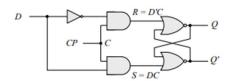


4.28 (a)

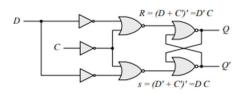
 $F_1 = \Sigma((2, 3, 4))$ 

 $-F_1 = \Sigma(0, 6, 7)$ 7 (b)

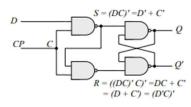


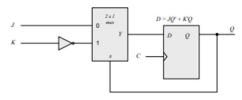




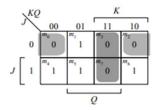


(c)





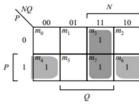
5.3 Q'(t+1) = (JQ' + K'Q)' = (J' + Q)(K + Q') = J'Q' + KQ



5.4

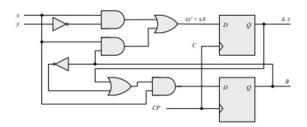
(a)	P $N$	Q(t+1)
	0 0	0
	0 1	Q(t)
	1 0	Q'(t)
	1 1	1

(b)	P	N	Q(t)	Q(t+1)
	0	0	0	0
	0	0	1	0
	0	1	0	0
	0	1	1	1
	1	0	0	1
	1	0	1	0
	1	1	0	1
	1	1	1	1



$$Q(t+1) = PQ' + NQ$$

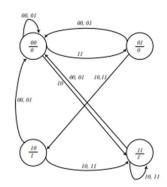
(d) Connect P and N together.



(b) A(t+1) = xy' + xB B(t+1) = xA + xB' z = A

| Martin | M

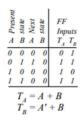
(c)



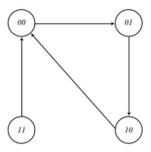
5.7



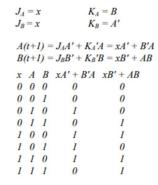
$$S = x \oplus y \oplus Q$$
$$Q(t+I) = xy + xQ + yQ$$

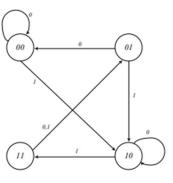


Repeated sequence:  $00 \longrightarrow 01 \longrightarrow 10 \longrightarrow$ 



5.9





**5.10** (a) 
$$J_A = Bx + B'y'$$
  $J_B = A'x$   $K_A = B'xy'$   $K_B = A + xy'$   $z = Axy + Bx'y'$ 

(b)											
	V Present B state		A Present  R state  K Inputs		> Next			In	FF Inputs J <sub>A</sub> K <sub>A</sub> J <sub>A</sub> J <sub>B</sub>		
	0	0	0	0	1	0	0	1	0	0	0
	0	0	0	1	0	0	0	0	0	0	0
	0	0	1	0	1	1	0	1	1	1	1
	0	0	1	1	0	1	0	0	0	1	0
	0	1	0	0	0	1	1	0	0	0	0
	0	1	0	1	0	1	0	0	0	0	0
	0	1	1	0	1	0	0	1	0	1	0
	0	1	1	1	1	1	0	1	0	1	0
	1	0	0	0	1	0	0	1	0	0	1
	1	0	0	I	1	0	0	0	0	0	1
	1	0	1	0	0	0	0	1	1	0	1
	1	0	1	1	1	0	0	0	0	0	1
	1	1	0	0	1	0	1	0	0	0	1
	1	1	0	1	1	0	0	0	0	0	1
	1	1	1	0	1	0	0	1	0	0	1
	1	1	1	1	1	0	1	1	0	0	1

(c)							
		xy					,
	AB	/	00	01	11	10	
		00	1	m <sub>j</sub>	m <sub>3</sub>	1	
		01	m <sub>4</sub>	m <sub>5</sub>	m, 1	m <sub>6</sub>	
		11	m <sub>12</sub>	1	m <sub>15</sub>	m <sub>14</sub>	B
	A	10	m <sub>s</sub>	1	1	m <sub>10</sub>	
		_			y	,	

$$A(t+1) = Ax' + Bx + Ay + A'B'y'$$

\xy					
AB	00	01	11	10	1
00	$m_0$	m <sub>1</sub>	m <sub>3</sub>	1	
A 01	m <sub>4</sub>	m <sub>5</sub>	m, 1	m <sub>6</sub>	
11	m <sub>12</sub>	m <sub>13</sub>	m <sub>15</sub>	m <sub>14</sub>	B
10	m <sub>s</sub>	m <sub>9</sub>	m <sub>11</sub>	m <sub>10</sub>	
_				7	-

$$B(t+1) = A'B'x + A'B'(x'+y)$$

5.16 (a) 
$$D_A = Ax' + Bx$$
 
$$D_B = A'x + Bx'$$

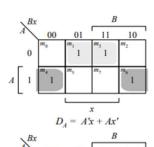
Present state		Input	Next state		
A	В	X	A B		
0	0	0	0 0		
0	0	1	0 1		
0	1	0	0 1		
0	1	1	1 1		
1	0	0	1 0		
1	0	1	0 0		
1	1	0	1 1		
1	1	1	1 0		

Bx			В	
A	00	01	11	10
0	m <sub>o</sub>	<i>m</i> <sub>1</sub>	1	m <sub>2</sub>
$A \begin{bmatrix} 1 \end{bmatrix}$	1	m <sub>5</sub>	m, 1	1
_				_
	D	Ax = Ax		
Bx			В	
ABX	00	01	11	10
A $Bx$ $0$		01 m <sub>1</sub>		
A	00	$m_1$	11	10
0	00 m <sub>o</sub>	1	11 m <sub>3</sub> 1	10

$$D_A = A'x + Ax'$$

$$D_B = AB + Bx'$$

Present state		Input	Next state		
A	В	X	A B		
0	0	0	0 0		
0	0	1	1 1		
0	1	0	0 1		
0	1	1	1 0		
1	0	0	1 0		
1	0	1	0 0		
1	1	0	1 1		
1	1	1	0 1		



$$D_{A} = AX + AX$$

$$0 0 01 11 10$$

$$0 0 01 1 1 0$$

$$0 0 01 1 1 0$$

$$0 0 01 1 1 0$$

$$0 0 01 1 1 10$$

$$0 0 01 1 1 10$$

$$0 0 01 1 1 10$$

$$0 0 01 1 1 10$$

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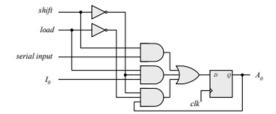
$$0 01$$

$$0 0$$

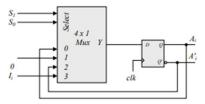
5.18 Binary up-down counter with enable E.

Present state A B	Input x	Next state A B	Flip-flo	
00	0 1	00	0 x	0 x
00	01	00	0 x	0 x
00	10	1 1	1 x	1 x
00	11	0 1	0 x	1 x
0 1	00	0 1	0 x	x 0
01	01	0 1	0 x	x 0
0 1	10	0 1	0 x	x 1
0 1	11	10	1 x	x 1
10	00	10	x 0	1 0
10	01	10	x 0	1 0
10	10	0 1	x l	x 1
10	11	1 1	x 0	x 1
11	00	1 1	x 0	x 0
11	01	1 1	x 0	x 0
11	10	1 1	1 0	x 1
11	11	11	x l	x 1

- **6.4** 0110 => 0011, 0001, 1000, 1100, 1110, 0111, 1011
  - 6.6 First stage of register:



6.7 First stage of register:



- 6.11 (a) A count down counter.
  - (b) A count up counter.
- 6.12 Similar to diagram of Fig. 6.8.
  - (a) With the bubbles in C removed (positive-edge).
  - (b) With complemented flip-flops connected to C.

## 6.19 (b) From the state table in Table 6.5:

$$\begin{array}{l} D_{Q1} = Q_1' \\ D_{Q2} = \sum \left(1, 2, 5, 6\right) \\ D_{Q4} = \sum \left(3, 4, 5, 6\right) \\ D_{Q8} = \sum \left(7, 8\right) \\ \text{Don't care: d} = \sum \left(10, 11, 12, 13, 14, 15\right) \end{array}$$

$$D_{Q2} = Q_2 Q'_1 + Q'_8 Q'_2 Q_1$$

Simplifying with maps: 
$$D_{Q2} = Q_2Q'_1 + Q'_8Q'_2Q_1$$

$$D_{Q4} = Q_4Q'_1 + Q4Q'2 + Q'_4Q_2Q_1$$

$$D_{Q8} = Q_8Q'_1 + Q_4Q_2Q_1$$

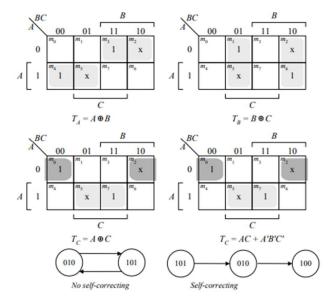
$$D_{08} = Q_8 Q_1' + Q_4 Q_2 Q_1$$

$$J_{A0} = LI_0 + L'C$$
  $KA_0 = LI'_0 + L'C$ 

(b) 
$$J = [L(LI)']'(L+C) = (L'+LI)(L+C)$$
 
$$LI + L'C + LIC = LI + L'C \text{ (use a map)}$$
 
$$K = (LI)'(L+C) = (L'+I')(L+C) = LI' + L'C$$

6.24

Present state	Next state	Flip	-flop i	nputs
ABC	ABC	$T_{\mathcal{A}}$	$T_B$	$T_C$
000	001	0	0	1
001	011	0	1	0
010	xxx	X	X	X
011	111	1	1	0
100	000	1	1	0
101	xxx	X	X	X
110	100	0	1	0
111	110	0	0	1



Present state	Next state	Flip-flop inputs					
ABC	ABC	$J_{_A}$	$K_{\Lambda}$	$J_B$	$K_B$	$J_c$	$K_{C}$
000	001	0	x	0	X	1	x
001	010	0	X	1	X	X	1
010	011	0	X	X	0	1	X
011	100	1	X	X	1	X	1
100	100	X	X	0	0	1	X
101	110	X	X	1	x	X	1
110	000	X	X	X	1	0	X
111	xxx	x	x	x	x	x	x

