CS471: Operating System Concepts Fall 2006

(Lecture: TR 11:25-12:40 PM)

Homework #3 Points: 20

Due: September 19, 2006

Question 1 [Points 10] Exercise 6.1: Provide an argument to show that the algorithm satisfies all three requirements for the critical section problem.

Answer: To prove property (a) we note that each pi enters the critical section only if the flag[j] = false. Since only pi can update flag[j], and since pi, inspects flag[j] only while flag[j] = true, the results follows

- a. To prove property (b), we first note that the value of variable turn is changed only at the end of the critical section. Suppose that only process pi wants to enter the critical section. In this case, it will find flag[j] = false and immediately enter the critical section, independent of the value of the turn. Suppose that both processes want to enter the critical section and the value of turn = 0. Two cases are now possible. If pi finds flag[0] = false then it will enter the critical section. If pi finds the flag[0] = true then it will enter the critical section. If pi finds flag[0] = true then we claim that p0 will enter critical section before p1. Moreover, it will do so within a finite amount of time.
- b. To demonstrate this fact, first consider process p0. Since *turn* = 0, it will only be waiting for *flag*[1] to be set to false; more precisely, it will not be executing in the *begin* block associated with the *if* statement. Furthermore, it will not change the value of *flag*[0]. Meanwhile, process p1 will find *flag*[0] = *true* and turn = 0. It will set *flag*[1] = *false* and wait until *turn* = 1. At this point, p0 will enter the critical section. A symmetric argument can be made if *turn* = 1.

Question 2 [Points 5] Exercise 6.9: Show that, if the wait and signal operations are not executed atomically, then mutual exclusion may be violated.

Answer: Consider the wait(S) semaphore operation defined in page 202 of the textbook. Suppose wait(S) is not executed atomically. Then there will be several problems. As an example consider the statement S→value--. This statement actually consists of 3 CPU instructions.

LOAD S → value SUB 1 STO S→ value

If two processes Pi and Pj execute the wait statement and if the S→value is 1 before Pi and Pj execute the wait statement. We know how the final value of

S→value may be either -1 or 0 depending on how the CPU instructions of Pi and Pj are interleaved. Only -1 value is correct. If the value was 0, then there would be 1 process in the list but the value would show that there are now. This creates a problem.

Similarly, if signal(S) is not implemented atomically, due to similar problems (e.g., $S \rightarrow value++$), mutual exclusion condition could be violated due to incorrect value.

Question 3 [Points 5] Exercise 6.13: Write a bounded-buffer monitor in which the buffers (portions) are embedded within the monitor itself.

Answer:

```
Monitor boundedbuffer
          Const bufsize = 100;
          item buf[100];
          int in, out, count;
          condition Producer, Consumer;
           void produce (item x) {
             if (count == bufsize) Producer.wait();
             buf[in] = x;
            count++;
            in = (in + 1) \% n;
            Consumer.signal();
           void consume (item& x) {
              if (count == 0) Consumer.wait();
              x = buf[out];
              count --;
              out = (out + 1) \% n;
              Producer.signal();
          }
          initialization_code() {
              in:=0;
              out:=0:
              count:=0;
           }
}
```